

PRACTICAL

Australia \$1.50 Malaysia \$4.95 IR £1.23 (inc. VAT)

# ELECTRONICS

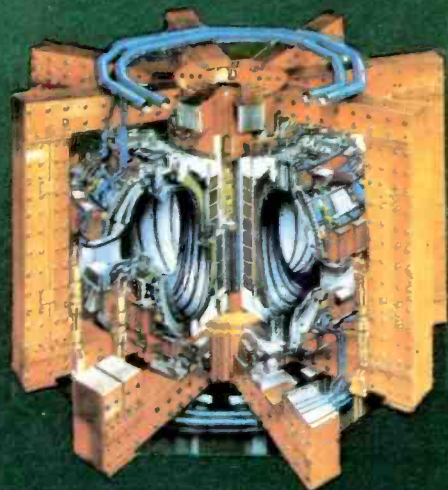
JUNE 1983

85p



## PERCUSSION MICROSYNTH

## Computing: PROGRAM CONDITIONER



## FUSION: Towards Reality

Spacewatch • Equipment Bargains

# EXTRA EDITORIAL PAGES!



# SAVE ON THE PRICE OF YOUR COLOUR PRINTS!

NOW ONLY 12p EACH

## with the Practical Electronics Colour Print Service

While prices go up elsewhere, Practical Electronics makes a bargain offer in its Colour Print Service. Now you can have as many films printed as you like, including Giant Superprints, at only 12p a print. There is no developing charge and just 25p towards postage and packing.

At this new price, the magazine Colour Print Service, already used by hundreds of thousands of readers, is as fast and efficient as ever. Here's all you have to do to enjoy its advantages.

Send any make of colour print film, including disc film, inside the envelope enclosed with this issue. Or fill in the coupon below and send with your colour print film in a strong envelope to:

**Practical Electronics Colour Print Service, FREEPOST, READING RG1 1BR. No stamp is required.**

### SEND NO MONEY

We are so confident in the reliability of our service and the quality of our prints (each one date-stamped with the month and year of developing) that you don't pay until you've seen them.

### LUXURY COLOUR PRINTS

You will be amazed at the beautiful colours and sheen finish of these prints. They have elegant rounded corners and are borderless to give you maximum picture area. And with the Giant Superprints, you get 30 per cent more picture area than the standard enprints *at no extra cost!*

*Offer excludes Black & White, transparency, sub-miniature, C22 & Argva CNS film. Superprints can only be produced from Kodacolor II, C41 cassette, cartridge and disc film not half frame. Prices correct at time of going to press.*

### UNBEATABLE VALUE

All you pay for the Colour Print Service is 12p for each good print received plus 25p towards postage and packing. The most you would pay us for processing and printing a 24-exposure film for example is £3.13. Compare that with the price you would pay in the shops.

### FREE ALBUM PAGES

With each film we process, you receive an album page voucher. Collect and return three vouchers, and you receive a set of FREE album pages to fit into our specially designed album for any size of print up to 4in. by 6in.

### HOW YOU BENEFIT

You benefit in three ways. Firstly, you pay nothing for the actual processing—only for prints and postage and packing. Secondly, you enjoy a personal service with every care taken over each individual order. And thirdly, you pay only for what you get—with no credit vouchers as with many other companies. An invoice comes with your prints, so it is a straight business transaction.

### 48 HOURS IN-LAB SERVICE

Your films will be processed within 48 hours\* of receipt, but please allow for postal delays.

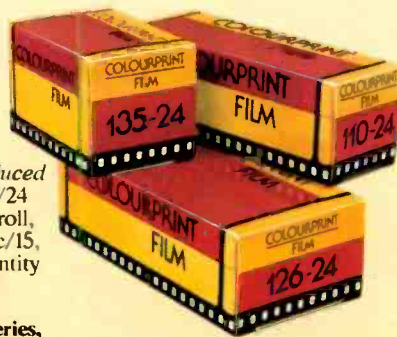
The price of this offer is limited to the U.K.

\*C41 Process cassette and cartridge film only.



### FILMS AT REDUCED PRICES

Always keep your camera action-ready. Order replacement films at our specially reduced prices: 110/24, 126/24 or 35/24 at £1.20 a roll, or three for £3; disc/15, £1.30 each (no quantity discount).



If you have any queries, contact our Customer Service on Reading (0734) 597332.

Use this label if you have no envelope, or pass it to a friend. It is used to pack your prints.

To: Practical Electronics Colour Print Service  
FREEPOST, READING RG1 1BR

- Please print my film Superprint size
- Standard Enprint size

If film is being ordered ● Please send me \_\_\_\_\_  
of 110/24  of 126/24  of 35/24  of disc/15

- Tick box(es) as required.

From: Practical Electronics Colour Print Service  
FREEPOST, READING RG1 1BR

Mr/Ms \_\_\_\_\_

Address \_\_\_\_\_

\_\_\_\_\_

Postcode \_\_\_\_\_

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VOLUME 19

No. 6

JUNE 1983

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<b>MICRO-FILE</b> by R. W. Coles	between pages 42 and 43
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OUR JULY ISSUE WILL BE ON SALE FRIDAY, JUNE 3rd, 1983  
(for details of contents see page 41)

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# WATFORD ELECTRONICS

33, CARDIFF ROAD, WATFORD, HERTS WD1 8ED, ENGLAND  
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**POLYESTER CAPACITORS: (Axial Lead)** 400V: 1nF, 1.5n, 2n2, 3n3, 4n7, 6n8 11p; 100V: 15n, 18n, 22n 12p; 33n, 47n, 68n 16p; 100n, 150n 20p; 220n 30p; 330n 42p; 470n 52p; 680n 60p; 1µF: 68µ, 2µ, 4µ, 7.5µ. 1000V: 1nF 17p; 10nF 30p; 15n 40p; 22n 36p; 33n 42p; 47n, 100n 50p.

**POLYESTER RADIAL LEAD CAPACITORS:** 250V: 10n, 20n, 15n, 22n, 27n 6p; 33n, 47n, 68n, 100n 7p; 150n, 220n 10p; 330n, 470n 13p; 680n 19p; 1µ: 23µ, 15µ, 40µ; 2µ, 4µ, 7.5µ.

**ELECTROLYTIC CAPACITORS (Values in µF):** 500V: 10µF 52p; 47 78p; 63V: 0.47, 1.0, 1.5, 2.2, 3.3, 8p; 4.7 9p; 10 10p; 15 12p; 22 13p; 47 12p; 68 16p; 100 19p; 220 20p; 1000 70p; 2200 90p; 50V: 50µ 20p; 100 20p; 240V: 40V: 6.8, 10µ, 22µ, 33µ, 47µ, 68µ, 100µ 46p; 220V: 30µ, 33µ, 47µ, 68µ, 100µ 46p; 25V: 50µ, 30µ, 33µ, 47µ, 68µ, 100µ 46p; 10V: 2.2, 4.0, 8p; 100 9p; 15 10p; 22 11p; 33 12p; 47 12p; 68 13p; 100 13p; 220 13p; 330 16p; 470 16p; 1500 17p; 2200 19p.

**TANTALUM BEAD CAPACITORS:** 35V: 0.1µ, 0.22, 0.33 15p; 0.47, 0.68, 1.0, 1.5 16p; 2.2, 3.3 18p; 4.7 20p; 6.8 22p; 10 22p; 15 22p; 22 22p; 33 22p; 47 22p; 68 22p; 100 22p; 150 22p; 220 22p; 330 22p; 470 22p; 680 22p; 1000 22p; 1500 22p; 2200 22p; 3300 22p; 4700 22p; 6800 22p; 10000 22p.

**SILVER MICA (pf)** 2, 3, 3.3, 4.7, 6.8, 8.2, 10, 12, 18, 22, 27, 33, 39, 47, 50, 56, 68, 75, 82, 85, 100, 120, 150, 180 18p each. 120, 250, 270, 330, 360, 390, 470, 600, 800 & 820pf 21p each. 1000, 1200, 1800 30p each. 3300, 4700 60p each.

**SIEMENS** multilayer miniature capacitors. 250V: 1nF, 1.5n, 2n2, 3n3, 4n7, 6n8, 8n2, 10n, 15n, 22n 7p; 18n, 27n, 33n, 39n, 47n 8p; 39n, 56n, 68n 9p. 100V: 100n, 120n, 150n; 150n 11p; 220n 13p; 330n 18p; 470n 23p; 680n 30p; 1µF: 3µ, 4µ, 7.5µ.

**CERAMIC CAPACITORS: 50V** Range 1pF to 6800pF 4p; 10nF, 15n, 33n, 47n 6p; 100n/30p; 1500n/10p.

**POLYSTYRENE Caps:** 10pF to 1nF 8p; 1n5 to 12nF 10p.

**RESISTORS S.I.L. Package:** 7 Commoned, 100k, 680k, 1k, 2k, 4k, 7k, 10k, 47k, 100k 24p. 8 Commoned: (9 pins) 150k, 180k, 270k, 330k, 1k, 2k, 4k, 7k, 10k, 22k, 47k, 100k 26p.

**LINEAR IC's**  
555 CMOS 80 LM311 55  
702 78 LM319 195  
709C 8 pin 45 LM324 90  
710 48 LM335 128  
714 14 LM339 47  
747C 14 pin 68 LM348 64  
748C 8 pin 36 LM349 118  
753 8 pin 185 LM358 60  
810 15 SN7677 17  
850 75 LM392 48  
9400CJ 350 LM390 80  
AY-1-1320 225 LM381N 145  
AY-1-5050 99 LM384 118  
AY-1-5691 160 LM384 160  
AY-1-8720 20 LM386 90  
AY-3-1270 675 LM387 120  
AY-3-8910 420 LM389 95  
AY-3-8912 450 LM392 45  
AY-5-1230 450 LM393 45  
AY-5-1317A 630 LM394CH 290  
CA3011 120 LM257CN 325  
CA3012 175 MT33 70  
CA3014 275 LM2917 195  
CA3018 86 LM3302 75  
CA3019 80 LM3900 50  
CA3020 210 LM3929 88  
CA3023 210 LM3911 125  
CA3028A 205 LM3914 125  
CA3035 285 LM3915 200  
CA3036 270 LM3916 110  
CA3043 275 LM13600 280  
CA3045 365 LS7220 280  
CA3046 70 M15153L 230  
CA3048 295 M1515L 190  
CA3059 285 M70681 125  
CA3075 213 MB3712 220  
CA3080E 70 MB3756 440  
CA3081 190 MC1303 98  
CA3086 48 MC1304P 260  
CA3089E 280 MC1319 195  
CA3090A 375 MC1445 250  
CA3123 168 MC1455 50  
CA3130 90 MC1458 35  
CA3140 40 MC1469 300  
CA3160 95 MC1494 694  
CA3161E 180 MC1495 350  
CA3162E 180 MC1496 350  
CA3189 200 MC1596 225  
CA3240 110 MC1648 290  
HA1366 175 MC1709G 90  
HA1388 255 MC3302 90  
ICL7106 890 MC3340P 120  
ICL7107 978 MC3360P 120  
ICL7204 650 MC3401 65  
ICL7611 99 MC3403 75  
ICL7660 248 MC3405 150  
ICL803BCC 300 MC3423P 80  
ICL8211 350 MF10 380  
ICM7204 1150 MFC60390 630  
ICM7205 1150 MFC6240 630  
ICM7207 475 ML924 275  
ICM7215 1050 MSM5626 280  
ICM7216A 222 NE515 170  
ICM7217A 750 NE529 225  
ICM7224 785 NE531 140  
ICM7240 390 NE543 210  
ICM7555 80 NE544 210  
ICM7556 150 NE555 160  
LA3350 220 NE560 140  
LA4031P 240 NE568 140  
LA4032 295 NE560 325  
LA4400 295 NE571 395  
LA4422 275 NE562B 410  
LC7130 340 NE564 420  
LC7137 395 NE566 155  
LF347 150 NE567 140  
LF351 48 NE570 410  
LF352 48 NE571 410  
LF355 85 NE5532 145  
LF356 95 NE5534 105  
LF357 110 OM335 760  
LF398 475 RC1436D 60  
LM10 328 RC1458 60  
LM100A 24 S5668 225  
LM1001 48 SAB3209 425  
LM308 45 SAB3210 328

**COMPUTER IC's**  
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**RESISTORS** Range 1pF to 100k. 5% Carbon. Hi-stab, Miniature, 5% Carbon. 0.25W 202-4 M7 E24 3p 1p; 0.5W 202-4 M7 E12 3p 1p; 1W 202-10M E12 6p 4p; 1% Metal Film 511-1M 8p 8p.

## TRANSISTORS

AC125/6	35	BC307B	14	BFY64	35	TIP34C	88	2N1613	30	2SC1061	250
AC127/8	35	BC308B	16	BFY81	120	TIP35A	110	2N1617B	160	2SC1096	85
AC141/2	30	BC327/8	15	BFY90	80	TIP35C	128	2N1621B	295	2SC1162	30
AC176	28	BC337/8	15	BR939	40	TIP36A	130	2N2219A/20A	140	2SC1172	125
AC187/8	32	BC441	34	BSX20	25	TIP41A	50	2N2369A	18	2SC1306	100
AD145	41	BC442	34	BU105	170	TIP41B	52	2N2646	45	2SC1307	150
AD149	79	BC477/8	40	BU205	190	TIP42A	55	2N2846	80	2SC1449	85
AD161/2	42	BC516/7	40	BU206	200	TIP42B	58	2N3004A/05A	25	2SC1679	140
AF118	95	BC547/8	12	BU208	200	TIP210	70	06A/07A	28	2SC1678	190
AF139	40	BC549C	14	BU300	250	TIP212	70	2N2928G	10	2SC1923	50
AF239	55	BC556/7	15	BU308	250	TIP214	100	TIP141	100	2N2945	225
BC107/8	10	BC558/9	15	BU309	250	TIP217	105	2N3054	58	2SC1953	90
BC107B	12	BC569	15	BU310	250	TIP219	120	2N3055	48	2SC1957	90
BC108	12	BC570	10	BU311	250	TIP225	60	2N3442	140	2SC1969	140
BC108C	12	BCV71/2	20	BU312	250	TIP3055	60	2N3614	199	2SC2028	200
BC109	12	BD124	115	BU313	250	TIP3056	32	2N3615	199	2SC2029	200
BC109B	12	BD131/2	48	BU314	250	TIP3057	32	2N3616	199	2SC2030	200
BC109C	12	BD135	45	BU315	250	TIP3058	32	2N3617	199	2SC2031	200
BC117/8	20	BD136/7	45	BU316	250	TIP3059	32	2N3618	199	2SC2032	200
BC147/8	30	BD138/9	45	BU317	250	TIP3060	32	2N3619	199	2SC2033	200
BC147B	10	BD140	40	BU318	250	TIP3061	32	2N3620	199	2SC2034	200
BC148C	10	BD142	40	BU319	250	TIP3062	32	2N3621	199	2SC2035	200
BC149	10	BD144	40	BU320	250	TIP3063	32	2N3622	199	2SC2036	200
BC149C	12	BD146	40	BU321	250	TIP3064	32	2N3623	199	2SC2037	200
BC153/4	12	BD148	40	BU322	250	TIP3065	32	2N3624	199	2SC2038	200
BC157/8	10	BD150	40	BU323	250	TIP3066	32	2N3625	199	2SC2039	200
BC159	11	BD152	40	BU324	250	TIP3067	32	2N3626	199	2SC2040	200
BC167A	10	BD154	40	BU325	250	TIP3068	32	2N3627	199	2SC2041	200
BC168C	10	BD156	40	BU326	250	TIP3069	32	2N3628	199	2SC2042	200
BC169C	10	BD158	40	BU327	250	TIP3070	32	2N3629	199	2SC2043	200
BC170	15	BD160	40	BU328	250	TIP3071	32	2N3630	199	2SC2044	200
BC171/2	11	BD162	40	BU329	250	TIP3072	32	2N3631	199	2SC2045	200
BC173	11	BD164	40	BU330	250	TIP3073	32	2N3632	199	2SC2046	200
BC177/8	16	BD166	40	BU331	250	TIP3074	32	2N3633	199	2SC2047	200
BC179/81	20	BD168	40	BU332	250	TIP3075	32	2N3634	199	2SC2048	200
BC182/3	10	BD170	40	BU333	250	TIP3076	32	2N3635	199	2SC2049	200
BC184	10	BD172	40	BU334	250	TIP3077	32	2N3636	199	2SC2050	200
BC184L	10	BD174	40	BU335	250	TIP3078	32	2N3637	199	2SC2051	200
BC186/7	26	BD176	40	BU336	250	TIP3079	32	2N3638	199	2SC2052	200
BC212/3L	10	BD178	40	BU337	250	TIP3080	32	2N3639	199	2SC2053	200
BC214L	10	BD180	40	BU338	250	TIP3081	32	2N3640	199	2SC2054	200
BC214L	10	BD182	40	BU339	250	TIP3082	32	2N3641	199	2SC2055	200
BC237/8	14	BD184	40	BU340	250	TIP3083	32	2N3642	199	2SC2056	200

**74S Series**  
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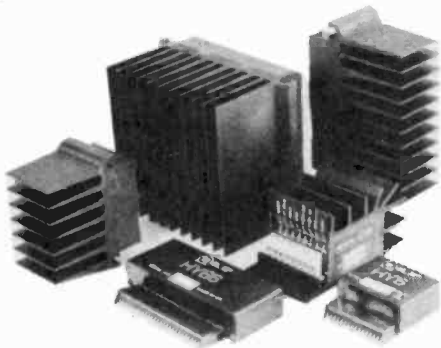
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**74ALS Series**  
74ALS00 24  
74ALS01 24  
74ALS02 24  
74ALS03 24  
74



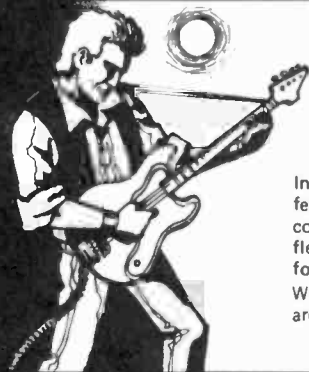


# GET BIG POWER



## Modular Amplifiers the third generation

Due to continuous improvements in components and design ILP now launch the largest and most advanced generation of modules ever.



## WE'RE INSTRUMENTAL IN MAKING A LOT OF POWER

In keeping with ILP's tradition of entirely self-contained modules featuring, integral heatsinks, no external components and only 5 connections required, the range has been optimized for efficiency, flexibility, reliability, easy usage, outstanding performance, value for money.

With over 10 years experience in audio amplifier technology ILP are recognised as world leaders.



### BIPOLAR MODULES

Module Number	Output Power W rms	Load Impedance $\Omega$	DISTORTION T.H.D. Typ at 1KHz	I.M.D. 90Hz/7KHz 4:1	Supply Voltage Typ	Size mm	WT gms	Price inc. VAT
HY30	15	4.8	0.015%	<0.006%	$\pm 18$	76 x 68 x 40	240	£8.40
HY61	30	4.8	0.015%	<0.006%	$\pm 25$	76 x 68 x 40	240	£9.55
HY68/69	30 x 30	4.8	0.015%	<0.006%	$\pm 25$	120 x 78 x 40	420	£18.69
HY124	60	4	0.01%	<0.006%	$\pm 26$	120 x 78 x 40	410	£20.75
HY128	60	4	0.01%	<0.006%	$\pm 35$	120 x 78 x 40	410	£20.75
HY244	120	4	0.01%	<0.006%	$\pm 35$	120 x 78 x 50	520	£25.47
HY248	120	4	0.01%	<0.006%	$\pm 50$	120 x 78 x 50	520	£25.47
HY364	180	4	0.01%	<0.006%	$\pm 45$	120 x 78 x 100	1030	£38.41
HY368	180	4	0.01%	<0.006%	$\pm 45$	120 x 78 x 100	1030	£38.41

Protection: Full load line, Slew Rate: 15v/ $\mu$ s. Rise time: 5 $\mu$ s. S/N ratio: 100db. Frequency response (-3dB) 15Hz - 50KHz. Input sensitivity: 500mV rms. Input Impedance: 100K  $\Omega$ . Damping factor: 100Hz >400.

### MOSFET MODULES

Module Number	Output Power W rms	Load Impedance $\Omega$	DISTORTION T.H.D. Typ at 1KHz	I.M.D. 90Hz/7KHz 4:1	Supply Voltage Typ	Size mm	WT gms	Price inc. VAT
MOS128	60	4.8	<0.005%	<0.006%	$\pm 45$	120 x 78 x 40	420	£30.44
MOS248	120	4.8	<0.005%	<0.006%	$\pm 55$	120 x 78 x 80	850	£38.88
MOS364	180	4	<0.005%	<0.006%	$\pm 55$	120 x 78 x 100	1025	£45.54

Protection: Able to cope with complex loads without the need for very special protection circuitry (fuses will suffice). Slew rate: 20v/ $\mu$ s. Rise time: 3 $\mu$ s. S/N ratio: 100db. Frequency response (-3dB) 15Hz - 100KHz. Input sensitivity: 500mV rms. Input Impedance: 100K  $\Omega$ . Damping factor: 100Hz >400.

### PRE-AMP SYSTEMS

Module Number	Module	Functions	Current Required	Price inc. VAT
HY6	Mono pre-amp	Mic/Mag. Cartridge/Tuner/Tape/Aux + Voi/Bass/Treble	10mA	£7.60
HY66	Stereo pre-amp	Mic/Mag. Cartridge/Tuner/Tape/Aux + Voi/Bass/Treble/Balance	20mA	£14.32
HY73	Guitar pre-amp	Two Guitar (Bass Lead) and Mic + separate Volume/Bass/Treble + Mix	20mA	£15.36
HY78	Stereo pre-amp	As HY66 plus tone controls	20mA	£14.20

Most pre-amp modules can be driven by the PSU driving the main power amp. A separate PSU 30 is available purely for pre-amp modules if required for £5.47 (inc. VAT). Pre-amp and mixing modules in 18 different variations. Please send for details.

### Mounting Boards

For ease of construction we recommend the B6 for modules HY6-HY13 £1.05 (inc. VAT) and the B66 for modules HY66-HY78 £1.29 (inc. VAT).

### POWER SUPPLY UNITS (Incorporating our own toroidal transformers)

Model Number	For Use With	Price inc. VAT
PSU 21X	1 or 2 HY30	£11.93
PSU 41X	1 or 2 HY60, 1 x HY6060, 1 x HY124	£13.83
PSU 42X	1 x HY128	£15.90
PSU 43X	1 x MOS128	£16.70
PSU 51X	2 x HY128, 1 x HY244	£17.07

Model Number	For Use With	Price inc. VAT
PSU 52X	2 x HY124	£17.07
PSU 53X	2 x MOS128	£17.86
PSU 54X	1 x HY248	£17.86
PSU 55X	1 x MOS248	£19.52
PSU 71X	2 x HY244	£21.75

Model Number	For Use With	Price inc. VAT
PSU 72X	2 x HY248	£22.54
PSU 73X	1 x HY364	£22.54
PSU 74X	1 x HY368	£24.20
PSU 75X	2 x MOS248, 1 x MOS368	£24.20

Please note: X in part no. indicates primary voltage. Please insert "0" in place of X for 110V, "1" in place of X for 220V, and "2" in place of X for 240V.

# WITH A LOT OF HELP FROM



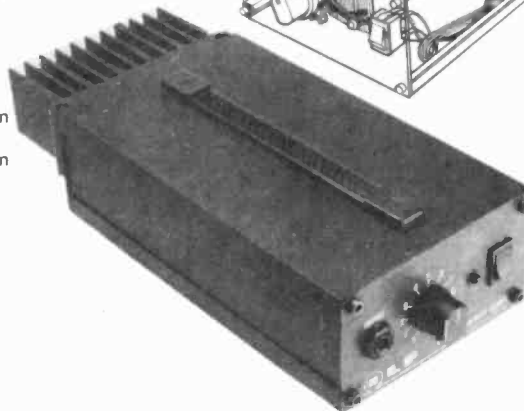
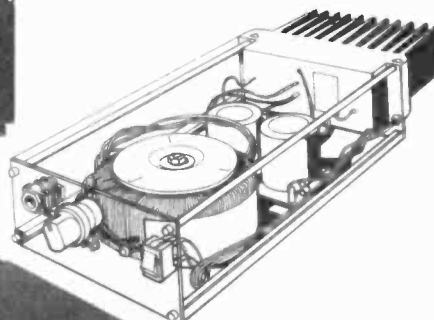
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Each Unicase kit contains all the hardware required down to the last nut and bolt to build a complete unit without the need for any special tools.

Because of ILP's modular approach, "open plan" construction is used and final assembly of the unit parts forms a compact aesthetic unit. By this method construction can be achieved in under two hours with little experience of electronic wiring and mechanical assembly.



### Hi Fi Separates

**UC1 PRE AMP UNIT:** Incorporates the HY78 to provide a "no frills", low distortion, (< 0.01%), stereo control unit, providing inputs for magnetic cartridge, tuner, and tape/monitor facilities. This unit provides the heart of the hi fi system and can be used in conjunction with any of the UP Unicase series of power amps. For ultimate hum rejection the UC1 draws its power from the power amp unit.

**POWER AMPS:** The UP series feature a clean line front panel incorporating on/off switch and concealed indicator. They are designed to compliment the style of the UC1 pre-amp. Performance for each unit which includes the appropriate power supply, is as specified on the facing page.



### Power Slaves

Our power slaves, which have numerous uses i.e. instrument, discotheque, sound reinforcement, feature in addition to the hi fi series, front panel input jack, level control, and a carrying handle. Providing the smallest, lowest cost, slave on the market in this format.

#### UNICASES

HiFi Separates						Price Inc. VAT
UC1	Preamp					£29.95
UP1X	30 + 30W/4-8Ω	Bipolar	Stereo	HiFi		£54.95
UP2X	60W/4Ω	Bipolar	Mono	HiFi		£54.95
UP3X	60W/8Ω	Bipolar	Mono	HiFi		£54.95
UP4X	120W/4Ω	Bipolar	Mono	HiFi		£74.95
UP5X	120W/8Ω	Bipolar	Mono	HiFi		£74.95
UP6X	60W/4-8Ω	MOS	Mono	HiFi		£64.95
UP7X	120W/4-8Ω	MOS	Mono	HiFi		£84.95
Power Slaves						
US1X	60W/4 Ω	Bipolar	Power	Slave		£59.95
US2X	120W/4 Ω	Bipolar	Power	Slave		£79.95
US3X	60W/4-8Ω	MOS	Power	Slave		£69.95
US4X	120W/4-8Ω	MOS	Power	Slave		£89.95

Please note X in part number denotes mains voltage. Please insert '0' in place of X for 110V, '1' in place of X for 220V (Europe), and '2' in place of X for 240V (U.K.). All units except UC1 incorporate our own toroidal transformers.

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SX12	200	1/4 watt Carbon Resistors	£1
SX13	200	1/4 watt Carbon Resistors	£1
SX14	150	1/4 watt Resistors 22 ohm-2m2 Mixed	£1
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Paks SX12-15 contain a range of Carbon Film Resistors of assorted values from 22 ohms to 2.2 meg. Save pounds on these resistor paks and have a full range to cover your projects.

\*Quantities approximate, count by weight.

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SX20	100	Assorted Polyester/Polystyrene Capacitors	£1
SX21	60	Mixed C280 type capacitors metal foil	£1
SX22	100	Electrolytics, all sorts	£1
SX23	50	Quality Electrolytics 50-1000mF	£1
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**SX53** 1 Power finned Heatsink. This heatsink gives the greatest possible heat dissipation in the smallest space owing to its unique staggered fin design, pre drilled.

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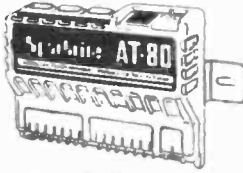
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Step-by-step fully illustrated assembly and fitting instructions are included together with circuit descriptions. Highest quality components are used throughout.

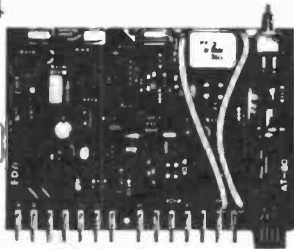
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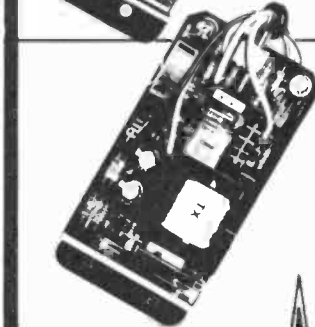


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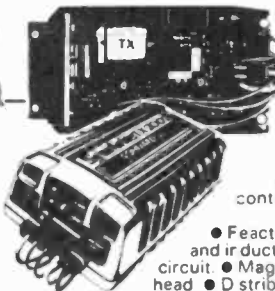
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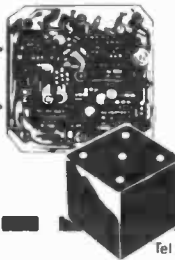


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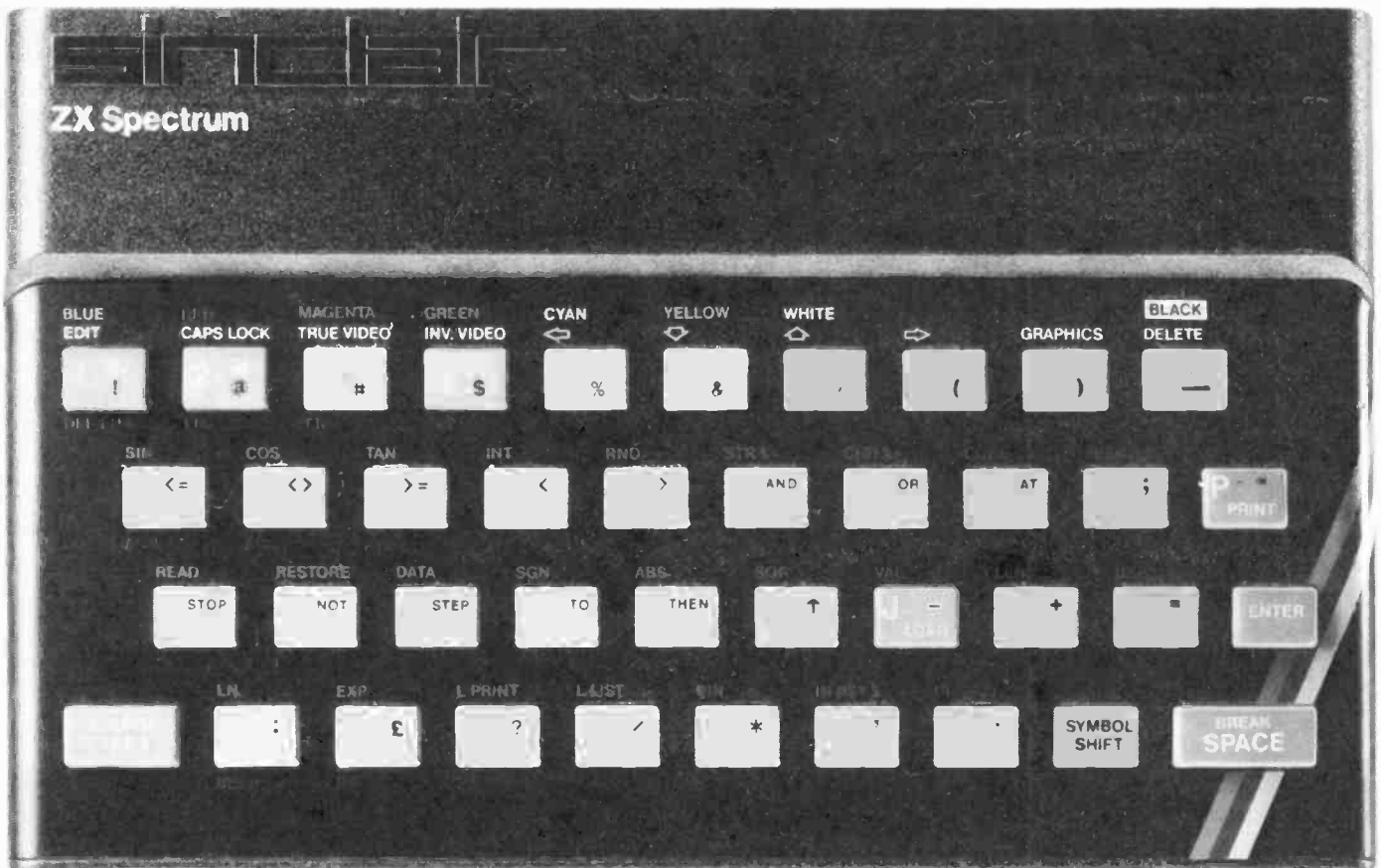
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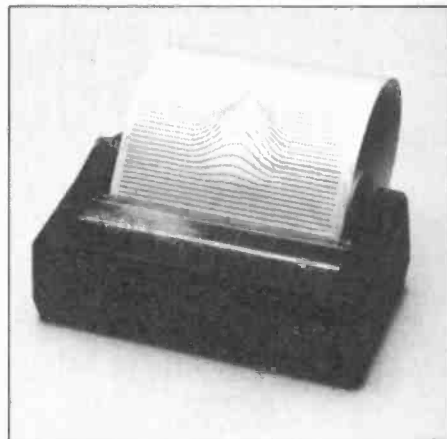
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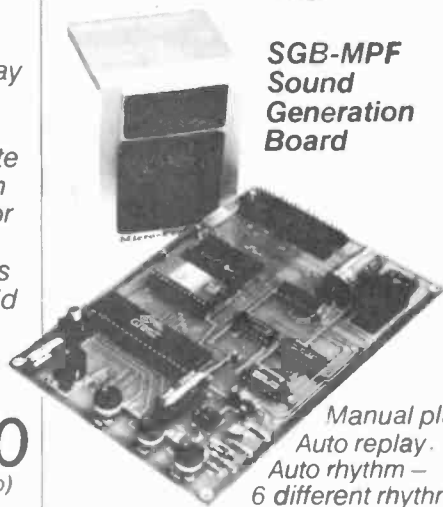
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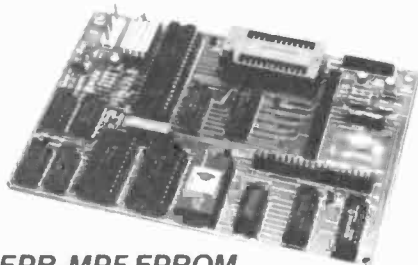
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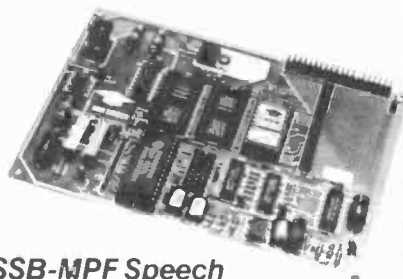
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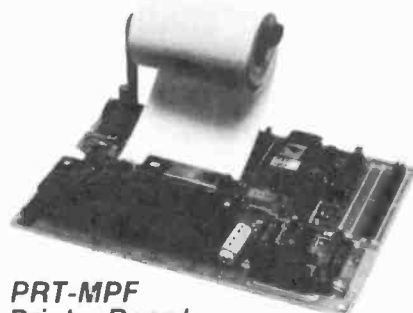
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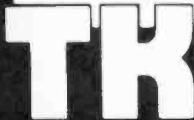
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75175	1.44
75182	0.50
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75189	0.37

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75451	0.22
75452	0.22
75453	0.22
75454	0.22
75468	0.88
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TL068	0.32
TL071	0.29
TL072	0.47
TL074	1.00
TL081	0.28
TL082	0.46
TL084	1.58
TL091	0.40
TL092	0.58
TL094	1.34
TL487	0.82
TL489	0.82
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22 17 38 65	7415
24 21 48 70	01
28 24 55 80	02
40 30 76 99	03

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4001	0.10
4002	0.12
4006	0.42
4007	0.14
4008	0.32
4009	0.24
4010	0.24
4011	0.10
4012	0.18
4013	0.20
4014	0.40
4015	0.36
4016	0.20
4017	0.32
4018	0.36
4019	0.36
4020	0.36
4021	0.40
4022	0.40
4023	0.13
4024	0.32
4025	0.13
4026	0.74
4027	0.20
4028	0.32
4031	0.94
4033	1.80
4034	0.94
4035	0.90
4040	0.39
4041	0.39
4042	0.40
4043	0.36
4044	0.38
4045	1.35
4046	0.42
4047	0.70
4048	0.38
4049	0.23
4051	0.39
4052	0.14
4053	0.44
4054	0.85
4055	0.85
4060	0.39
4063	0.85
4066	0.24
4068	0.14
4069	0.14
4070	0.13
4071	0.13
4072	0.13
4073	0.14
4075	0.13
4076	0.43
4077	0.13
4078	0.15
4081	0.13
4082	0.13
4085	0.50
4086	0.44
4093	0.20
4502	0.46
4507	0.32
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4510	0.40
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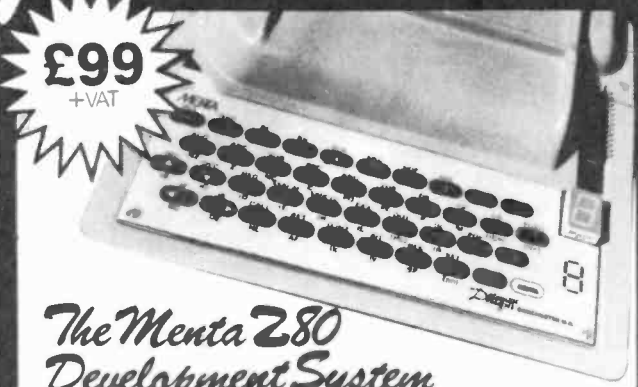


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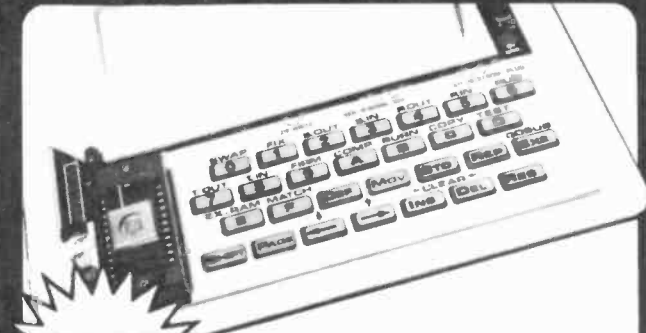
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## FEATURE

THIS issue of PE carries the first of a regular line of feature articles on various aspects of electronics and its applications. The first article could not get further from the hobbyist concept of PE. It describes a piece of equipment costing some £500 million to build, requiring 700 megawatts of power just to start it up and being quite simply gigantic in size.

No doubt some readers will be aware of the JET Tokamak, of the fact that its trials will be starting within the next month and that it has been built in the heart of Oxfordshire. But how many will know what it is designed to find out, the problems involved in generating and containing a plasma at 100 million degrees Centigrade and what impact it could have on our future energy supply? We must say that until recently we were not conscious of its existence and this article would not have appeared if our Technical Editor had not read a small piece in a newspaper he was standing on whilst decorating!

It is our intention on PE to bring you a wide range of feature articles, some

relating directly to our hobby and some, like *Fusion*, giving a glimpse into the future and showing how the application of complex electronics can change our world. Next month our feature will investigate the *Fairlight Music Computer*, an instrument that has changed the world of music. Ray Hammond, author of the recently released book *The Musician And The Micro*, takes an in-depth look at what the Fairlight is, what it can do and just how it does it. The feature will make fascinating reading to anyone with any interest in electronics, computing or music.

After that we are planning to look at such things as robot vision, satellite TV, fibre optics, radio astronomy and one or two other exciting and possibly "unknown" areas. We will reveal more at a later date.

Most of the articles will be written by experts at the sharp end of the developments or researched and written by experienced technical authors. They will be revealing, factual and authoritative. In fact just what you have come to expect from PE.

## CARTE BLANCHE

This issue also sees a new page from our very own "V.T.", Vernon Trent. We have given Vernon *carte blanche* to write what he likes about anything he likes, when he likes — provided it's linked to electronics and he does it every month (writes that is). Only his name has been changed to protect him from the wrath of anyone he takes to task!

*Vernon Trent at Large* should make entertaining reading, it will sometimes have a message or moral behind it. It might be instructive or informative, it could even be funny and it may well add to our post bag when all you "worthy sextons" start writing in. As we have said V.T. speaks for himself and not necessarily PE (or anyone else). Perhaps this is something you didn't expect from PE!

We hope these new features add to your enjoyment of the magazine.



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## Letters and Queries

We are unable to offer any advice on the use or purchase of commercial equipment or the incorporation or modification of designs published in PE. All letters requiring a reply should be accompanied by a stamped, self addressed envelope, or addressed envelope and international reply coupons, and each letter should relate to one published project only.

Components and p.c.b.s are usually available from advertisers; where we anticipate difficulties a source will be suggested.

## Back Numbers

Copies of most of our recent issues are available from: Post Sales Department (Practical Electronics), IPC Magazines Ltd., Lavington House, 25 Lavington Street, London SE1 0PF, at £1 each including Inland/Overseas p&p. Please state month and year of issue required.

## Binders

Binders for PE are available from the same address as back numbers at £5.50 each

to UK or overseas addresses, including postage and packing, and VAT where appropriate. Orders should state the year and volume required.

## Subscriptions

Copies of PE are available by post, inland or overseas, for £13.00 per 12 issues, from: Practical Electronics, Subscription Department, Oakfield House, Perrymount Road, Haywards Heath, West Sussex RH16 3DH. Cheques and postal orders should be made payable to IPC Magazines Limited.



Items mentioned are available through normal retail outlets, unless otherwise specified. Prices correct at time of going to press.

## Y's and Wherefores

**Why QWERTY? Do we stop at Y because it sounds friendly? Full name, then: QWERTYUIOP! But this is the lesser mystery surrounding the conventional typewriter keyboard. Why are the letters so arranged to start with. Conflicting reports have been published as to the historical explanation of this configuration, but in PE we now present the truth (of course).**

Over a century ago Frederick Sholes, E. P. Curry and G. W. Carr described the forerunner of today's typewriter in British patent 2418 of 1879. This is a fact stated in the UK PIN (Patents Information Network) Bulletin, and it is also a fact that the early keyboard was designed so that frequently adjacent characters in use are not adjacent mechanically. The letters E and F are an example of this, and by keeping them apart they will not jam together when the word "efficient" is typed rapidly. Sholes's typewriter comprised a circle of hammers, with T and H on opposite sides of the basket. It is a myth that the designer's intention was to avoid key jamming by deliberately slowing down the typist through the use of a *quirky* keyboard.

Why do we couple the high technology keyboard of today's word processor, for example, to a key layout philosophy governed by archaic mechanics? Answer: Commerce thrives on providing for people's needs, and people need what their fingers are familiar with . . . when it comes to typing.



Attempts to shatter the mould do exist. The first photograph shows PCD Maltron's ergonomically designed keyboard. Although this looks like a fire damaged item, it is shaped to accommodate the contours, and finger positions and lengths, of the human hand. The character positions are scientifically placed so that the most frequently used keys are the most convenient to press. Typing speed improvements of up to 40% have been achieved, and tests have shown that re-training the QWERTYite is surprisingly quick, leaving her confidently bidextrous. Humans, after all, are curvey, so this keyboard might be a guide to future architecture. Why should machines which we human beings have to work with be rigid, and squared off with sharp corners? Machines should *bend* to suit people, not vice versa.

Another key approach is the Microwriter, which completely abandons the concept of having a button to represent each alphanumeric character. Combinational use of only six keys enables one-handed operation. Imaginary linking of the shape of the required character, to the shape formed by the buttons to be pressed, allows the Microwriter to be mastered in as little as 20 minutes. A single-line display shows what has been keyed into this portable unit, and an integral word processor allows subsequent editing. Later the writer can be linked

to a host computer to download the day's work. The reclined executive, typing on the Microwriter, takes on the appearance of



someone impatiently tapping his fingers on the desk. Pen and paper are endangered species!

## ROBOTIC SHEEP SHEARING

*Robotic sheep shearing is here (in Australia, at least Bruce), according to a report in Electronics Times. In it, John Mathews, of the National Institute of Agricultural Engineering is said to believe that robotic sheep shearing, and even robotic artificial insemination is a workable idea. The Australian Wool Board has issued contracts to researchers to look into these possibilities. Melbourne and Perth, it is claimed, already have robotic shearers.*

*Not for animal lovers, the Perth system*

*takes a computerised picture of the sheep's contours as it moves along a conveyor belt. The computer then controls the shearing arm in accordance with this information, stored in its memory. In a demonstration, the sheep was held still whilst being shorn, using an electric current passed via an electrode in its mouth. This apparently freezes the animal's muscles, keeping nicks to a similar level to that of manual shearing. Mathews predicts that farmers will be using robotic sheep shearers by 1990.*



"THATS A PRETTY VOLATILE RAM BRUCE . . . YER'LL NEED A BYTE CHECK ON YER BUFFER WHEN HE'S DONE WITH YER!!"

# MARKET PLACE

## Pollution Monitor

A personal pollution monitor in use by the Environmental Protection Agency in the USA has been designed to be worn by people as they go about their daily business in urban areas, the unit weighs only 2 lb and continuously sucks in air to measure the level of carbon monoxide. It stores and displays hourly averages of the pollution that its wearer has inhaled, and can later chart a graph. The system is far more indicative of pollution dangers than the conventional fixed point sampling method, and Federal officials say that the study could lead to changes in carbon monoxide regulations in 90 US cities.

## DBS News

On March 7th, 1983, Bryce McCrerrick, BBC Director of Engineering, and Alan Jefferis, Managing Director of United Satellites Limited (Unisat), signed Heads of Agreement for provision by Unisat of two direct broadcasting by satellite television channels for the BBC DBS services due to start in 1986.

Unisat, jointly owned by British Telecom, British Aerospace and the General Electric Company, will be responsible for building and launching two satellites in 1986, the first to be operational and the second as a flying spare. A third spacecraft will be available on the ground as an additional safeguard. Launch will be by the European Ariane rocket or by the American Space Shuttle, the final choice to be made nearer the time. The satellites will be in geostationary orbit 36,000km above the equator and will provide signals of sufficient power for high-quality reception by individual households, with suitable receivers and small dish antennas less than 1 metre in diameter, within a 'footprint' covering the United Kingdom and parts of Western Europe. The agreement covers a period of operation of the satellite service of at least seven years.

The satellite will carry transponders for two BBC DBS services; DBS 1 will be a Subscription Channel carrying feature films and other attractions; and DBS 2 will have an international flavour. There will also be a number of digital sound channels affording stereo sound with television and some high-quality radio channels.

The signing of the Heads of Agreement represents a notable landmark in the development of British broadcasting. It will be followed later by completion of a full Agreement covering the finer details.

*PE will be publishing an article on the proposed new system in a few months' time*

## SOLID STATE MICRO

Lamentably, Solid State Micro Technology (for Music Inc.) has no current UK outlet. Although the SSM2040 Voltage Controlled Filter (used in the Audio Sweep Oscillator of PE Oct. '82) is available from Digisound (14 Queen St., Blackpool), this is a residual stock, since that company is no longer an outlet for Solid State Micro.

However, we are informed by Solid State Micro that they will take overseas orders from hobbyists, for their popular range of i.c.s. They require prepayment in the form of a money order in US dollars, allowing \$2 for p&p for small packets. Prices (1-24) are indicated:

SSM-2000, 2010, 2020, 2030, 2040, 2024, 2050 ...	\$7.50
SSM-2011, 2022, 2031, 2044, 2056 .....	\$5.75
SSM-2015, 2033, 2038 .....	\$10
SSM-2012/2012A .....	\$9.50
SSM-2100 .....	\$10

Solid State Micro are on the lookout for a non-OEM outlet in the UK, but

for the meantime, here is their US address: Solid State Micro Technology for Music Inc., 2076B Walsh Ave., Santa Clara, CA95050, USA.

## Static Bike

One day, when the final tree has fallen, the last lawn has gone nylon, and the world is artificially oxygenated, people may wonder what it must have been like to go for a leisurely bicycle ride down a country lane. The technology to simulate this experience will be old hat by then, but today it's the very latest thing, if only for Americans with sufficient disposable income to accommodate the dismissal of \$20,000.

The static exercise bike is connected to a laser video disc system which projects the way ahead onto a 45 inch screen. As the rider imbibes the fresh office air, the bike is electromechanically punched up and down to simulate bumps in the road. That's not all; a choice of directions accompanies each fork in the lane, selectable by push button. The video disc has the capacity to store many parallel route options from which the laser head can be instructed to select by computer.

## Silicon News Corner

Bulletins announcing new semiconductor devices arrive at PE daily, so it is possible only to describe them briefly. Details of how to obtain further information are included, however.

**National Semiconductor** ♦ CMOS UART with near-NMOS speed. The NSC858 interfaces to NSC800, 8085 and 1802  $\mu$ Ps. Has internal diagnostics and Baud generator, and consumes 50mW.

♦ The NMC9306/COP494 is a low cost 256-bit serial Electrically Erasable Programmable Memory. Needing only 5V to operate, this TTL compatible, non-volatile 16 x 16 serial read/write memory has Microwire™ I/O. It employs floating gate technology and is compatible with COP400 processors

♦ Combined 4-digit alphanumeric display and CMOS driver i.c. is called the NSM 1416. It features a 4mm, 16 segment font, and an on-board memory to store four 7-bit ASCII words (the four display chars), and an ASCII-to 16 seg. alphanumeric ROM decoder plus multiplexing. Other features: Cascade ability,  $\mu$ P bus compatibility with 300ns access time.

♦ New 4MHz version of NSC800  $\mu$ P speed compatible with all Z80 4MHz 8-bit micros. The NSC800D-4 has 60% speed improvement over NSC800. Set of 158 instructions; consumes 16mA typical. Also houses internal DRAM refresh circuitry. National Semiconductor, 301 Harpur Centre, Horne Lane, Bedford.

**Synertek (Honeywell)** ♦ Low cost SY68045 CRT Controller. 5V device pin compatible with industry standard 6845. Although flexible, primarily for interface with 6500/6800/68000  $\mu$ Ps. Adds to Synertek's CRT device family, of which the SY6545R is addressable up to 16K of video RAM, incorporating light pen interface. Synertek, 3001 Stender Way MS-34, Santa Clara, CA 95054.

**Mitel** ♦ Complete monolithic DTMF receiver (18 pin) incorporating bandsplit filter and digital decoder functions. Called the MT8870, this ISO-CMOS device also includes differential amp, clock osc., and latched tristate bus interface. Power is 15mW at 5V. Pronto Electronic Systems Ltd., 466-478 Cranbrook Road, Gants Hill, Ilford, Essex.

**Precision Monolithics** ♦ 1983 Product Selection Guide. Bourns Electronics Ltd., Hodford House, 17/27 High Street, Hounslow, Middx.

**Intersil** ♦ Two-stage, differential output, wide-band video amp, the NE/SE592 offers fixed gains of 100 and 400 using no external components, or variable gain. Bandpass capability makes this ideal for pulse amplification in floppy disc units. Pin-for-pin replacement for  $\mu$ A733.

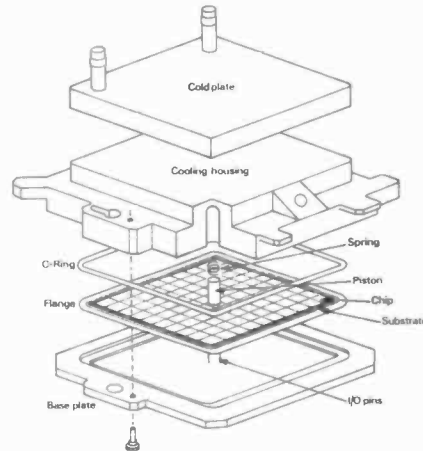
♦ ICL7415 is a 16-bit,  $\mu$ P compatible multiplying D/A converter. Has 16-bit resolution, linearity of 0.003% FSR, output current settling time of 3 $\mu$ s, and four quadrant multiplication. Intersil Datel (UK) Ltd, Snamprogetti House, Basing View, Basingstoke.

## IBM's COOL CHIPS

Researchers at IBM's East Fishkill laboratories have found an ingenious way to remove heat from the silicon devices used in today's generation of fast computers. Their solution comes in the shape of a Thermal Conduction Module (TCM) which comprises up to 118 LSI chips mounted on a 30 layer ceramic substrate. The considerable heat generated in a densely packed TCM, typically containing over 25,000 logic circuits and 65,000 array bits of storage, is removed through a matrix of aluminium pistons, each spring-loaded against a chip. Backed up by water circulation, a TCM has a cooling capacity of up to 300 W.

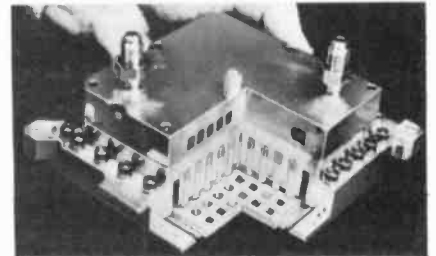
The ceramic layers carry interwiring between the chips, with power distribution dominating the lower levels, and signal routes occupying the upper levels. A key feature is the routing of all signal connections from each chip via an array of surface pads, which in turn are connected to internal wiring layers. In the event of modifications, connections to buried layers may be removed and substitute wires ultrasonically bonded to the gold-plated pads.

The same function of one typical TCM would, using the technology of the IBM 3033 processor, require 1,880 single-chip logic modules, 80 array modules with associated terminating devices, 52 multi-layer printed circuit cards and four large



Exploded view of a TCM. Measures 15 x 15 x 6cm.

multilayer p.c.b.s with associated interconnecting cables. The reduction in hardware using TCM's results in greater reliability and cost saving. A reduction factor of 7:1 in interwiring length increases execution



Cut-away view of a TCM, revealing the pistons that bear down on each LSI chip. The TCM is used in IBM's new 3081 series processor.

speed by reducing what is called "time-of-flight" circuit delay. This also limits the drive circuit power requirements.

The Japanese are said to be working on water-cooled computers, but it is believed that IBM has a clear lead at this stage.

## Robot Trainer

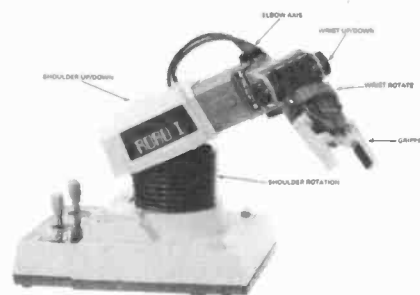
The robot arm shown in the photograph is called Armatron. It is manufactured by Tomy Corp, and has surprising flexibility due to the number of controllable axes. Armatron stands about 250mm high, being made out of blue/grey plastic, and comes with a set of important looking components for manipulation practice. This robot arm is intended to teach the geometrics of robot manipulation to youngsters, for it cannot be programmed and will not interface to a computer, but is operated entirely by way of two joysticks. It nevertheless is a fascinating and instructive gadget with which to experiment; any combination of axes can be simultaneously activated.

The robot's console has an integral timer switch that shuts off power from the battery (two D-cells) after a preset time period. One's progress can be monitored, or competitions held using this timer, during tasks using the "industrial components" supplied. The timer's lapsing "energy level" as it is called, can be seen through a row of windows on the robot's console, where orange squares disappear one by one.

Armatron is entirely mechanical, being powered from a single d.c. motor. Revolving drive shafts carry power through the arm to each axis, a system involving numerous differential gears. The joysticks

operate into a drum of centrifugal gears which distributes power from a single drive shaft. The mechanics alone of Armatron are intriguing enough, but by the same token a disappointment to the micro/robotics buff. There's no rational way to interface Armatron to a micro (our original reason for examining the robot). In any case, the machine lacks the necessary precision for simple operation from a program of instructions, and would therefore require positional feedback, making the modifications still more disproportionate.

By the time this item is in print, Armatron (called Robo I outside the UK) should be available through high street shops at around £35.



## GSC Launch

Global Specialties have just launched three new test instruments: an autoranging capacitance meter, a frequency counter and a handheld frequency counter-timer.

The autoranging capacitance meter, model 3002, incorporates a 3½ digit l.c.d. and measures 193 x 95 x 44mm. The unit provides direct readings of capacitance from 1pF to 19990µF over eight automatically selected ranges with an accuracy within 0.2% (± one count) from 1pF to 199µF and 1.0% (± one count) between





# MARKET PLACE

200µF and 19990µF. The 3002 is priced at £165.50 including VAT.

The frequency counter, model 6000, can measure from 50Hz to 650MHz and has an 8-digit l.e.d. display, simple push-button controls with l.e.d. indicators for selecting the input, gate time and low pass filter.

Two BNC inputs are provided: one covering the range 5Hz to 100MHz with a 1MΩ input impedance and the other for signals between 40MHz and 650MHz with a 50Ω impedance. Gate times of 0.1, 1.0 and 10 seconds are available. The instrument which measures 76 x 254 x 178mm is priced at £315.39 including VAT.

The last unit in the range is the model 5000 handheld counter-timer which is battery operated and includes pulse-width measurement facilities in addition to frequency and period.

The unit has an 8-digit l.c.d. and covers the frequency range from 0.1Hz to 50MHz incorporating a wide range of signal-conditioning facilities including attenuation, slope selection, a.c. or d.c. coupling and a variable trigger level.

The model 5000 is priced at £274.85 including VAT.

For complete details of these and the rest of the GSC range of instruments send a self-addressed envelope to GSC, Shire Hill Industrial Estate, Saffron Walden, Essex CB11 3AQ.

## Fair News

Those readers who came to the first Electronics Hobbies Fair last November will not want to miss the second one, so make a note of the dates now: October 27th to the 30th 1983. The event will take place in the same excellent venue (Alexandra Pavilion) and it will have all the best attractions of "number one" with plenty of new ones. Something for everyone with any interest in electronics.

The foremost consumer electronics exhibition goes forward so make sure you are there.

## Briefly...

A team of scientists from Lockheed's Palo Alto Research Laboratory and Stanford University have achieved a breakthrough in understanding how radio waves interact with the Earth's magnetosphere and ionosphere. The SEEP (Stimulated Emission of Energetic Particles)

study, sponsored by the Office of Naval Research, is said to have confirmed a long believed theory that man-made Very Low Frequency (v.l.f.) radio waves traverse earth's magnetic field lines to great altitudes and dislodge electrons. In a process identical to that caused by sunspot activity these electrons are dumped into the ionosphere, causing a miniature aurora borealis, and the release of X-rays. Remarkable improvements in radio communications could result from this discovery. It may be possible to use magnetic field lines to capture and amplify v.l.f. radio waves.



*A new component, developed by Ferranti at Dalkeith, is believed to be the most accurate and first of its kind in the world. It is an encoder, Type 35HA, and is used to measure the rotation of a shaft down to 1/3000th of a degree. According to Ferranti News, if you were to plot a triangle between the outer edges of a house brick and an observation point 24 miles away, this would be the angle formed at the observer's point!*

*Encoders are used for radio telescope tracking, laser pointing systems and robotics. The computerised 35HA can work accurately up to 1000 r.p.m.*

## Countdown ...

Please check dates before setting out, as we cannot *guarantee* the accuracy of the information presented below. Note: some exhibitions may be trade only. If you are organising any electrical/electronics, radio or scientific event, big or small, we shall be glad to include it here. Address details to Mike Abbott.

**Compec Scotland** May 17-19. Kelvin Hall, Glasgow. **Z1**  
**Welsh Amateur Radio, TV & Electronics Rally** May 22. Barry Memorial Hall, S. Glam. **C**  
**Computers In The City** (conf. & ex.) May 24-26. Barbican. **O**  
**Business Telecom** May 24-26. Barbican. **O**  
**International Word Processing** May 24-27. Wembley Conf. Cntr. **Z**  
**Motradex** May 25-27. Sandown Exhibition Centre, Surrey. **Z1**  
**East Suffolk Wireless Revival** May 29. Ipswich Civil Service Sportsground. **V1**  
**Russian Holography** June-Sept. Inc. Light Fantastic Gallery. **A8**  
**Apple Exhibition** June 3-5. Fulcrum Cntr., Slough. **J1**  
**Semlab** June. Olympia. **I**  
**IBM Productivity** (conf. & small ex.) June 14-16. Tara Hotel, London. **O**  
**The Computer Fair** June 16-19. Earls Court. **Z1**  
**Compec North** June 21-23. Belle Vue, Manchester. **Z1**  
**Transducer/Tempcon** June 28-30. Wembley Conf. Cntr. **T**  
**Leeds Electronics Show** July 5-7. University. **E**  
**Satellite TV & Cable TV** July 5-7. Alex. Palace, London. **G4**  
**IBM User Show** July 12-14. Wembley. **O**  
**BAEC Amateur Electronics** July 16-24. Shelter, Esplanade, Penarth, S. Glamorgan. **B9**

**Laboratory Edinburgh** July 18-20. University. **E**  
**Acorn Exhibition** Aug. 25-28. Cunard Int. Hotel, Hammersmith, London. **J3**  
**BARTAG Rally** (radio teleprinter) Aug. 29. Sandown Park, Esher, Surrey. **E2**  
**Weldex** Sept. 12-16. NEC B/ham. **I**  
**Testmex** Sept. 13-15. Grosvenor House, Park Lane, London. **E**  
**Personal Computer World Show** Sept. 28-Oct. 2. Barbican, London. **M**  
**Laboratory London** Oct. 12-14. Barbican Centre. **E**  
**Drives/Motors/Controls** Oct. 12-14. Leeds University. **E**  
**Computer Graphics** Oct. 18-20. Wembley. **O**  
**PARC** (computers in architecture, conf.) Oct. 18-20. Wembley. **O**  
**International Business Show** Oct. 18-26. NEC. **T**  
**Business Efficiency Exhibition** Oct. 22-26. Earls Court, London. **Z**  
**Electronics Hobbies Fair** Oct. 27-30. Alex Pavilion, London. **Z1**  
**Compec** Nov. 15-18. Olympia, London.  
**Northern Computer Fair** Nov. 24-26. Belle Vue, Manchester. **Z1**  
**A8** Holographic Exhibitions ☎ 01-826 6423  
**B9** Cyril Bogod, British Am. Elect. Club ☎ 0222 707813  
**C** Reg. Rowles ☎ Cardiff 565656  
**E** Evan Steadman ☎ 0799 22612  
**E2** BARTG 89 Linden Gdns., Enfield, Middx.  
**G4** Intech Exhibitions, 55 London Rd., St. Albans  
**I** Industrial Trade Fairs ☎ 021 705 6707  
**J1** Database Publications, Stockport, Cheshire  
**J3** Computer Marketplace. ☎ 01-930 1612  
**M** Montbuild ☎ 01-486 1951  
**O** Online ☎ 09274 28211  
**T** Trident ☎ 0822 4671  
**V1** Jack Tootill, 76 Fircroft Rd., Ipswich IP1 6PX  
**Z** BETA Exhibitions ☎ 01-405 6233  
**Z1** IPC Exhibitions ☎ 01-643 8040

# PROGRAM CONDITIONER

IAN HICKMAN

THE usual way to copy a personal computer program stored on cassette is to load the program into the computer and record it onto another cassette. This method has both advantages and disadvantages. On the plus side, only one cassette recorder is required, and the program listing can be checked for errors on the visual display unit screen—usually a TV set—as it loads. Further, when it is recorded, the new recording is retimed by the computer so that any timing imperfections on the original due to flutter or other cassette deck limitations are not compounded.

On the debit side, the computer is tied up whilst loading and recording are in progress. Also, it is sometimes found that the program won't load correctly in the first place, due to inadequacies in the original recording or in the cassette machine used for playback, or due to the combination of the two—there are fairly startling differences in performance between different models.

The circuit forming the subject of this article can often circumvent this problem and is thus useful as a signal conditioner to rescue poor recordings and enable them to be successfully loaded into a computer. Also, if two recorders are available, it permits programs to be copied directly without tying up a computer. The latter method is particularly useful for the enthusiast who is still saving up for a computer system but who wants to be able to collect programs from friends in the meantime.

The circuit consists of four sections—a selectable high-pass filter, an adjustable all-pass filter, an output stage providing clipping and shaping, and an audio stage driving a monitor loudspeaker. To understand the purpose of the various stages—particularly the all-pass filter (also known as a phase equaliser)—one needs to know a little of how tape recording works.

## RECORDING ON TAPE

Magnetic recording tape consists of thin plastic, coated with finely divided iron oxide or other suitable magnetic powder. You may have noticed that once pins have been picked up with a magnet, they will tend to stick together even in the absence of a magnet. This effect is called remanence and is the basis of tape recording. Fig. 1 shows how a recording head records the signal onto the tape.

The relation between the record current and the remanent magnetism is nonlinear, so a high frequency (50 to 100kHz) bias current is added to spread the recording to the linear parts of the characteristic. On cassette recorders the same head is usually used for playback, so that monitoring from

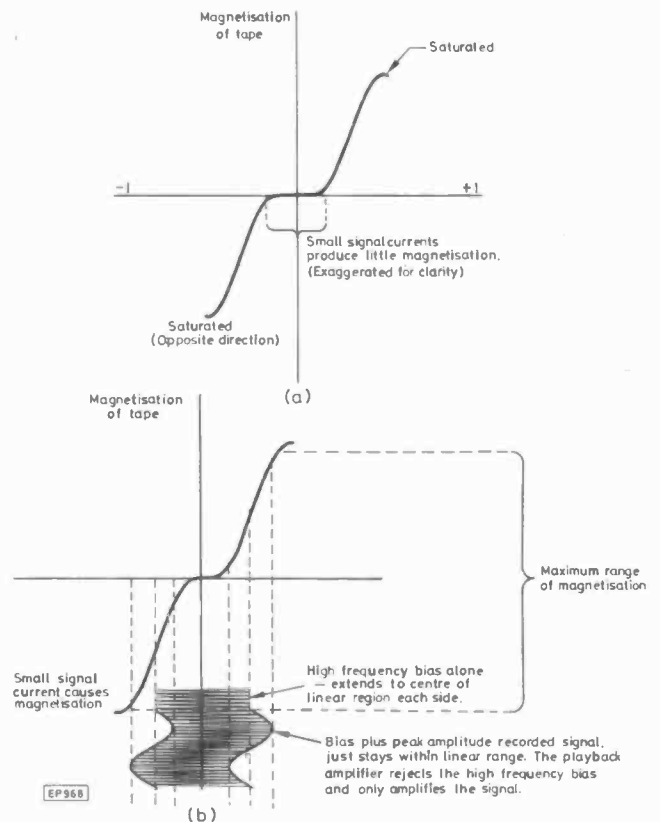


Fig. 1. Magnetic tape recording with (a) no bias and (b) the effect of bias

the tape is not possible. Another head uses the a.c. bias current at a much higher power to erase previous recordings. Quarter track heads are used in stereo cassette recorders, providing two tracks in either direction. Mono recorders use half track heads in the same way as older half track reel to reel recorders. With stereo cassette machines, the two tracks of the stereo signal are on the same side of the tape, and both are erased at the same time by the erase head. As with reel to reel recorders, the erase head is energised during recording and the tape passes over it first, before reaching the record head. Thus four track mono use is not available, but mono cassette recordings can be played on

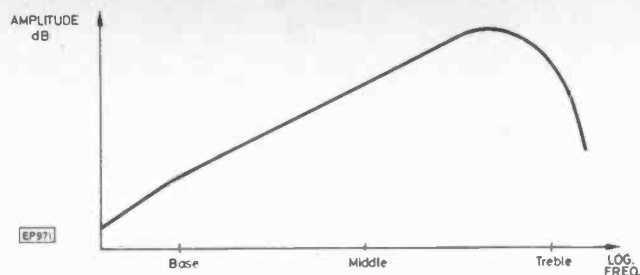


Fig. 2. Typical tape playback curve for constant peak recorded flux density

stereo cassette decks and vice versa. Of course the result is always mono except in the case of a cassette recorded on a stereo machine being replayed on a stereo machine.

There is nothing to prevent one using an older reel to reel recorder for storing personal computer programs on tape, though cassette machines are almost invariably used because of their greater convenience.

Also, the greater demands made on the tape by the very low tape speed ( $1\frac{1}{8}$  in per second) and narrow track of the heads used in cassette machines has resulted in the development of much better tape, suffering less from drop outs (random areas of low sensitivity along the tape) than older reel to reel tapes. However, whatever type of tape is used, one still has to cope with the basic frequency response of magnetic recording tape, as shown in Fig. 2. The 6dB per octave roll-off in the middle and lower frequency region is a result of the law of induction, the induced voltage on playback (for constant peak recorded flux level) is directly proportional to the rate of change of flux density, and hence to the frequency.

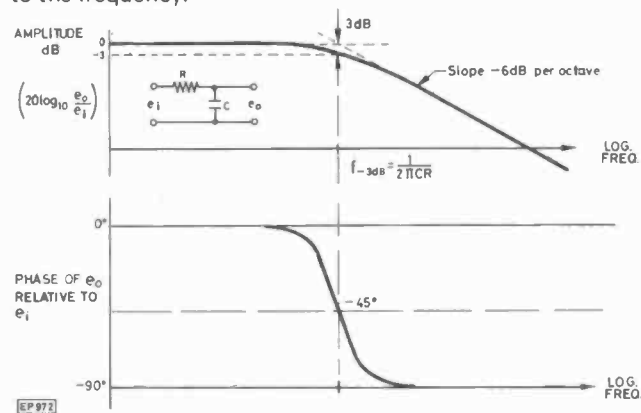


Fig. 3. Bode plot of phase and amplitude against frequency for a top-cut circuit

At higher frequencies, another effect takes over. The shorter and fatter a magnet, the greater the tendency to self-demagnetisation—which explains why, before the invention of modern improved magnetic materials, magnets were always long and thin. The same effect is observed in tape recording where the shorter recorded wavelength along the tape results in a falling high frequency response. The effect is compounded by the bias waveform, which unfortunately acts increasingly as an erase signal as the recorded frequency rises. The signal applied to the erase head is simply the bias waveform, but at a very much higher level.

To obtain a level overall response independent of frequency, on playback the middle and bass are boosted by 6dB per octave and the high frequencies, above the frequency of maximum response are also boosted. The rate of fall-off of the high frequency response is in fact faster than 6dB per octave, so boost is also applied during recording.

## EFFECT OF PHASE

It is usually claimed that the phase response of audio equipment is unimportant as the ear is not sensitive to phase, and this is certainly largely true as otherwise tape recordings would all sound awful. The fact is that audio tape recorders of all types do dreadful things to the relative phase of the harmonics of, for example, a squarewave. To see why we must now digress a moment and look at phase and amplitude responses versus frequency for various circuits and processes, usually called bode plots.

Fig. 3 shows a top cut or high frequency roll-off circuit, together with its Bode plots. It can be seen that at low frequencies, where the response is level, there is little if any phase shift; whilst at high frequencies, where the response is falling off at 6dB per octave, the phase shift approaches 90° lagging. At the point where the 6dB/octave asymptote crosses the level asymptote, the amplitude response is -3dB, and the phase shift is -45° (45° lagging). Bode's relations show that generally a lagging or negative phase shift is associated with an amplitude response which is falling with increase of frequency, and a leading or positive phase shift with a rising amplitude response. The change in amplitude of response in dBs (decibels) between two frequencies  $f_1$  and  $f_2$  is proportional to the integral of the phase shift between limits  $f_1$  and  $f_2$ , and the phase shift at any frequency is proportional to the rate of change of amplitude response. The going rate of exchange is 90° (lead or lag) for a 6dB/octave rate of change of amplitude (rising or falling with frequency respectively).

Does this apply universally? Well, almost; that is it applies to all "minimum phase" circuits and processes and this includes most tone control networks and filters. There are, however, "non minimum phase" networks. This can occur for example where there are two parallel paths through a network. In such cases Bode's relationships do not apply—a well known example is the twin tee network. There are a number of non minimum phase processes and two other examples are all-pass filters and tape recorders.

In tape recording, it has been explained that the high frequency roll off is due to self- and bias-demagnetisation, and in fact there is no associated phase shift involved—a non minimum phase process. The treble boost applied on both record and playback to maintain a level response is a minimum phase process and thus, overall, the amplitude response is level, but the phase advanced.

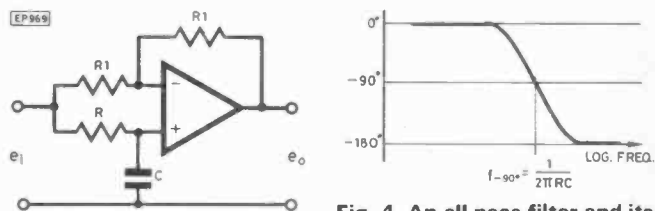


Fig. 4. An all pass filter and its phase response. Here gain is unity at all frequencies

The all pass filter in Fig. 4 has an amplitude response independent of frequency, but provides a phase response which varies with frequency. At very low frequencies, it is a non inverting amplifier with unity gain, i.e. 0° phase shift. At a frequency  $f_{90} = 1/(2\pi CR)$  it has a 90° phase lag and at high frequencies the phase shift becomes 180° lagging, all the while with a flat amplitude response. Fig. 5 shows the effect on a square wave of changing the product CR. When  $1/(2\pi CR)$  is very much lower than the fundamental frequency of the square wave,  $f_t$ , all the frequency components of the square wave are shifted by -180°, so the waveform is unaffected. If  $f_{90}$  rises—say by reducing the value of R—the

effect on the squarewave at first is not unlike the slope or tilt produced by an inadequate coupling capacitor—Fig. 5(a). As  $f_{90}$  approaches  $f_f$ , the effect is more marked, but as the fundamental is now shifted in phase relative to the harmonics without its amplitude being reduced, we see the waveform of Fig. 5(b), and as  $f_{90}$  becomes higher and then much higher than  $f_f$  we see waveforms like Figs. 5(c) and (d).

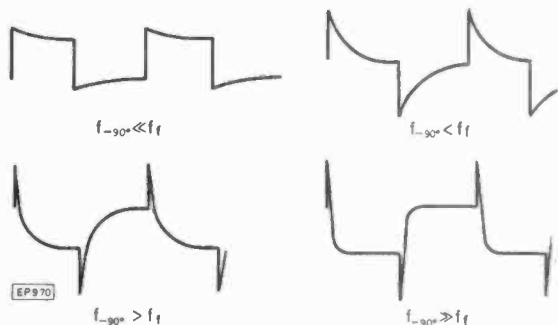


Fig. 5. Effect of the all pass filter on an ideal square wave of frequency  $f_f$

### RECORDING PROGRAMS

Returning now to the topic of recording programs on cassettes, the usual format is CUTS (computer users' tape system), also known as the Kansas City interface. This is an FSK (frequency shift keying) system where a frequency of 1200Hz represents a zero and 2400Hz a 1. As the signalling rate is 300 bauds (300 signal elements per second) one signal element consists of either 4 cycles of 1200Hz tone (a zero) or 8 cycles of 2400Hz tone (a 1). The format is a 1 as a start bit, eight data bits (1s or 0s according to the byte to be transmitted) and two stop bits. On replay, the computer looks for a 0 (start bit) following a long string of 1s, and thereafter for succeeding start bits following the two stop bits. Signal conditioning circuitry in the computer's CUTS input turns the two tones into 0 or 1 levels as appropriate.

Thus the system is asynchronous, and provided the difference in speed between the recorder used to make the recording and that used to reproduce it (allowing also for the effects of flutter and noise) is not more than a few percent then no problems should arise. Nevertheless, the phase distortion already noted is bound to occur in the cassette recording/playback process, so compensation for the phase advance of the harmonics is applied by a phase retard (top cut) circuit in the computer's CUTS output—Fig. 6(b). Allowing for the limited frequency response of most cassette recorders, this would ideally appear on playback as in Fig. 6(c).

Several deviations from the ideal playback waveform are commonly observed. The waveform often has superimposed hum at 50Hz (poor layout, induced hum from the recorder's mains transformer), at 100Hz (inadequate smoothing of full wave rectifier output), and at 150Hz (a third harmonic component of the mains transformer's magnetising current due to using the core laminations at a peak flux density approaching saturation). The smallish internal speaker used in many machines is relatively insensitive at 150Hz and completely dead at 50Hz, so the manufacturer has little incentive to worry over much about these hum components in the playback signal. To cope with this problem, the circuit described later has an active 2 pole high pass filter which can be switched into circuit if required.

Another problem one encounters is excessive phase distortion, due to a variety of causes. One commercially produced program appeared to have been recorded without sufficient phase retard, or maybe excessive peaking in the record circuitry. The result was that playback on the author's

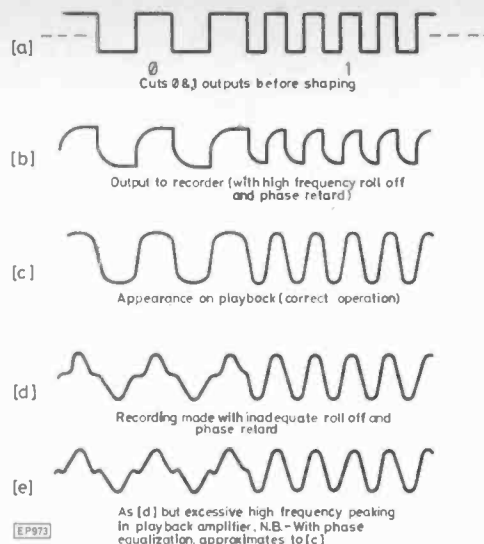


Fig. 6. Waveforms associated with cassette program recording

Trophy CR100 cassette recorder resulted in the 1200Hz tone appearing as in Fig. 6(d). The program loaded o.k., but on a colleague's cassette deck (which was evidently equipped with extra enthusiastic treble peaking in the playback equalisation section) the waveform appeared as in Fig. 6(e). The additional zero crossings got sliced in the computer's CUTS input circuit, turning occasional 0s into 1s and corrupting the program. The extraneous wiggles could be reduced with the aid of the tone control (which, like the volume control, controlled the output at the recorder's 5 pin DIN auxiliary socket) but that also had the undesirable effect of attenuating the 2400Hz 1 tone. The all pass filter in the signal conditioner described in this article permits the harmonics to be properly relocated in phase relative to the fundamental, resulting in the 1200Hz tone again resembling a squarewave, without attenuating the 2400Hz tone at all. So, having prepared the ground, let's look at the full circuit of the Program Conditioner, Fig. 7.

### THE SIGNAL CONDITIONER

This uses a TLO84 quad op-amp and the whole instrument fits in a small sloping panel plastic case, powered from an internal PP7 battery. Two input sockets are provided, the first (JK1) being a 3.5mm jack socket. This accepts a jack to jack lead from a cassette recorder's earphone socket, a suitable level being set with the recorder's volume control. The second input socket (SK2) accepts an input from the recorder's auxiliary socket. The latter is usually a 5 pin 180° DIN socket and to prevent the DIN plug to DIN plug lead from being connected the wrong way round, a 5 pin 270° DIN socket is used on the Program Conditioner. On the 180° DIN plug, the two signal output pins (usually pins 3 and 5) are connected in parallel so that a stereo cassette deck is used in the mono mode. Most recorders provide the AUX output signal at a fixed standard level, unaffected by the volume control or tone control (if any), but on some machines the AUX level is affected by these controls—in which case a medium volume setting (and no top cut) should be selected.

The input signal is applied to IC1b which acts as a non inverting buffer amplifier when S1 is closed, and as a high pass filter when S1 is open. In this mode, it provides, nominally, a 300Hz corner frequency with 12dB attenuation at 150Hz and 30dB at 50Hz, with little effect at 1200Hz—the lower of the two tones used in recording programs.



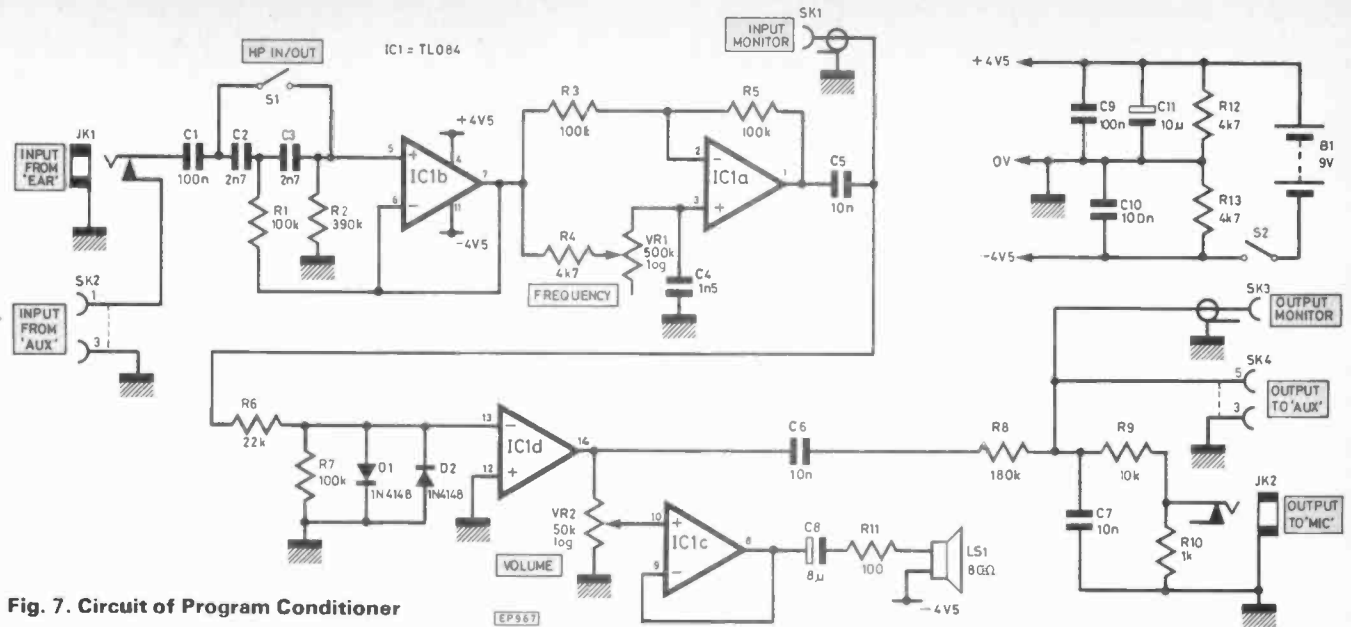


Fig. 7. Circuit of Program Conditioner

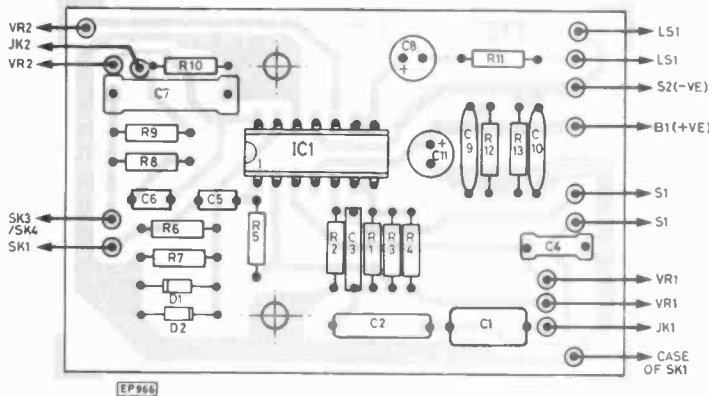
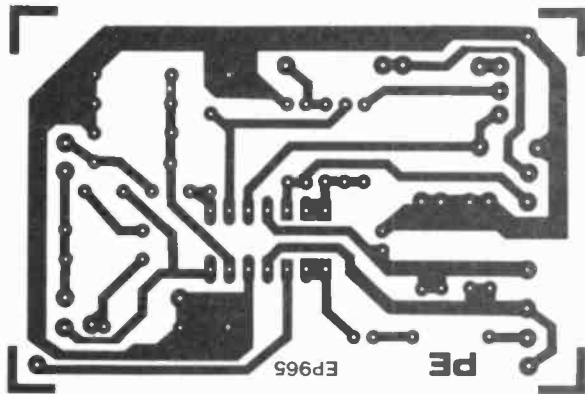


Fig. 8. Printed circuit detail and component overlay

The output of the high pass filter stage is applied to the all pass filter, IC1a. The turnover frequency of this stage (at which the phase shift is 90°) is adjustable by VR1 from about 200Hz to 20kHz. At the latter setting (VR1 fully anticlockwise) the all pass filter is effectively out of circuit since the vast majority of cassette recorders cannot reproduce frequencies this high. Thus, with VR1 set anticlockwise and S1 closed (high pass filter bypassed) the playback signal from the recorder can be observed by connecting an oscilloscope to SK1, the "Input Monitor" socket. Any hum or phase distortion can thus be observed, as can the corrective effect of the two filters. The filtered, phase corrected signal is fed to

Resistors		Integrated Circuit	
R1	100k	IC1	TL084
R2	390k	<b>Potentiometer</b>	
R3	100k	VR1	500k log
R4	4.7k	VR2	50k log
R5	100k	<b>Switches</b>	
R6	22k	S1	S.p.s.t.
R7	100k		miniature toggle
R8	180k	S2	S.p.s.t.
R9	10k		miniature toggle
R10	1k	<b>Battery</b>	
R11	100	B1	PP7
R12-R13	4.7k (2 off)	<b>Loudspeaker</b>	
All resistors ¼W 5%		LS1	80 ohm 2in
Capacitors		Sockets	
C1	0.1µ	JK1, JK2	miniature sockets
C2-C3	2.7n (2 off)	SK1, SK3	BNC connectors
C4	1.5n	SK2, SK4	5 way 240° chassis mounting sockets
C5-C7	10n (3 off)		
C8	8µ 16V		
C9-C10	0.1µ (2 off)		
C11	10µ 16V		

IC1d where it is sliced to produce a near ideal squarewave, as this op-amp is run open loop a.c. coupled as a comparator. IC1c, controlled by volume control VR2, provides a drive to the miniature loudspeaker, permitting audible monitoring. This is useful when using the EAR output of the cassette deck, as this cuts out the recorder's internal loudspeaker. R8, 9, 10 and C7 provide shaping, phase retard and level adjustment for the two outputs and the monitor output. The latter (SK3) is provided to permit viewing of the output waveform on a 'scope, whilst the output to a computer's cuts input (or to a second cassette machine for direct copying) is taken from SK4, or from JK2 if the cassette's microphone input is used instead of AUX.

**CONSTRUCTION**

With a quad op-amp and modern miniature components the circuit board takes up very little space and weighs very little. The p.c.b. assembly is stood off from the front panel as shown in Fig. 9 and the latter includes all circuit components

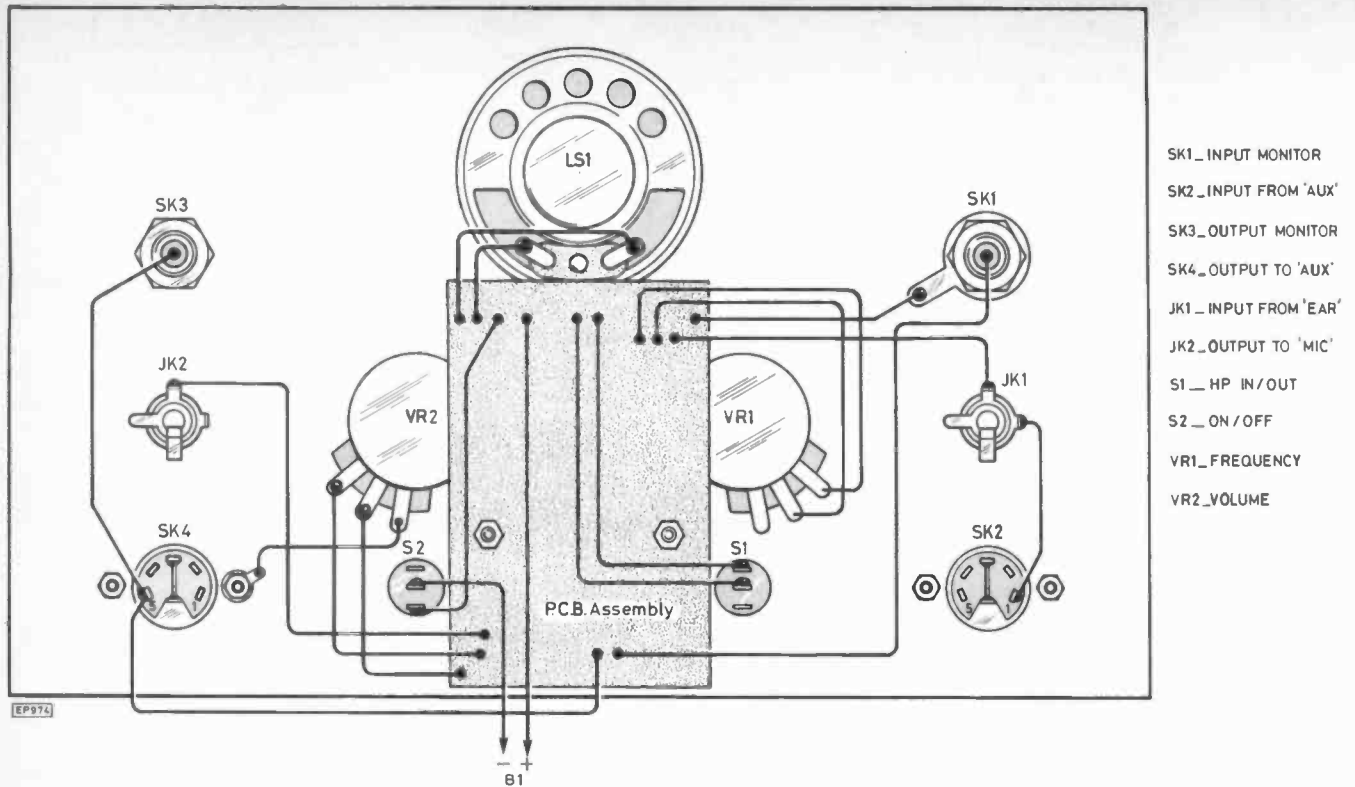


Fig. 9. Placement of case mounted components with board interwiring

except the battery. This combines for neatness and easy access if servicing is required.

Etching details for the printed circuit and the component overlay are shown in Fig. 8. Other layouts, such as on Veroboard, can be used but watch out for op-amp outputs running close to inputs—this could cause instability. The component assembly is built into a plastic box with a sloping front panel 12.5 by 21cm. This provides space for an uncluttered panel layout and just sufficient depth to accommodate a PP7 layer type battery. As the whole instrument draws only about 8 milliamps with intermittent use battery life should be almost indefinite. A photograph of the front panel is shown with appropriate legends.

## USE

To obtain the best from the Program Conditioner one really needs to observe the signal at the input monitor socket on a 'scope. The simplest of these suffices, e.g. a single trace instrument with a bandwidth covering the audio band is quite adequate, though good triggering is, as always, important. One can soon tell from the appearance of the trace and the sound from the monitor speaker whether the playback signal is of good quality. If the trace is fuzzy in the vertical direction, this usually indicates hum, as can be verified by switching to a slow timebase setting—switching in the high pass filter should cure this. Fuzziness of the trace in the horizontal direction usually indicates speed variations (wow and flutter), either due to the machine which recorded the program in the first place, or due to the cassette deck being used for playback. The ear becomes quite good at detecting this with practice. There is little that can be done about this (other than using a better cassette deck if the flutter is due to playback) but it does make correct equalisation more important. If the 1200Hz tone looks a bit peaky and triangular, advance the phase equaliser control VR1 from the fully

anticlockwise position. You should see the 1200Hz tone become squarer, with faster rise and fall times as it passes through the mean value, when the fundamental is correctly phased with respect to the harmonics.

This is the correct condition, over compensation will result in a return to the peaky, triangular waveform. There will be comparatively little effect on the 2400Hz tone on most small cassette machines as they will already be falling off considerably in frequency response at the odd harmonics of this frequency.

Use of this Program Conditioner can enable a program to be successfully loaded which otherwise might be difficult or impossible; it should then of course be recorded from the computer to avoid further problems. Alternatively, the Program Conditioner can be used to clean up and optimise a program on cassette for rerecording on another machine without tying up a computer at all. Providing the original recording loads, the rerecorded copies should likewise do so.

★



# Patents Review

Copies of Patents can be obtained from:  
 the Patents Office Sales, St. Mary Cray, Orpington, Kent. Price £1.60 each.

## THEFT DETECTOR

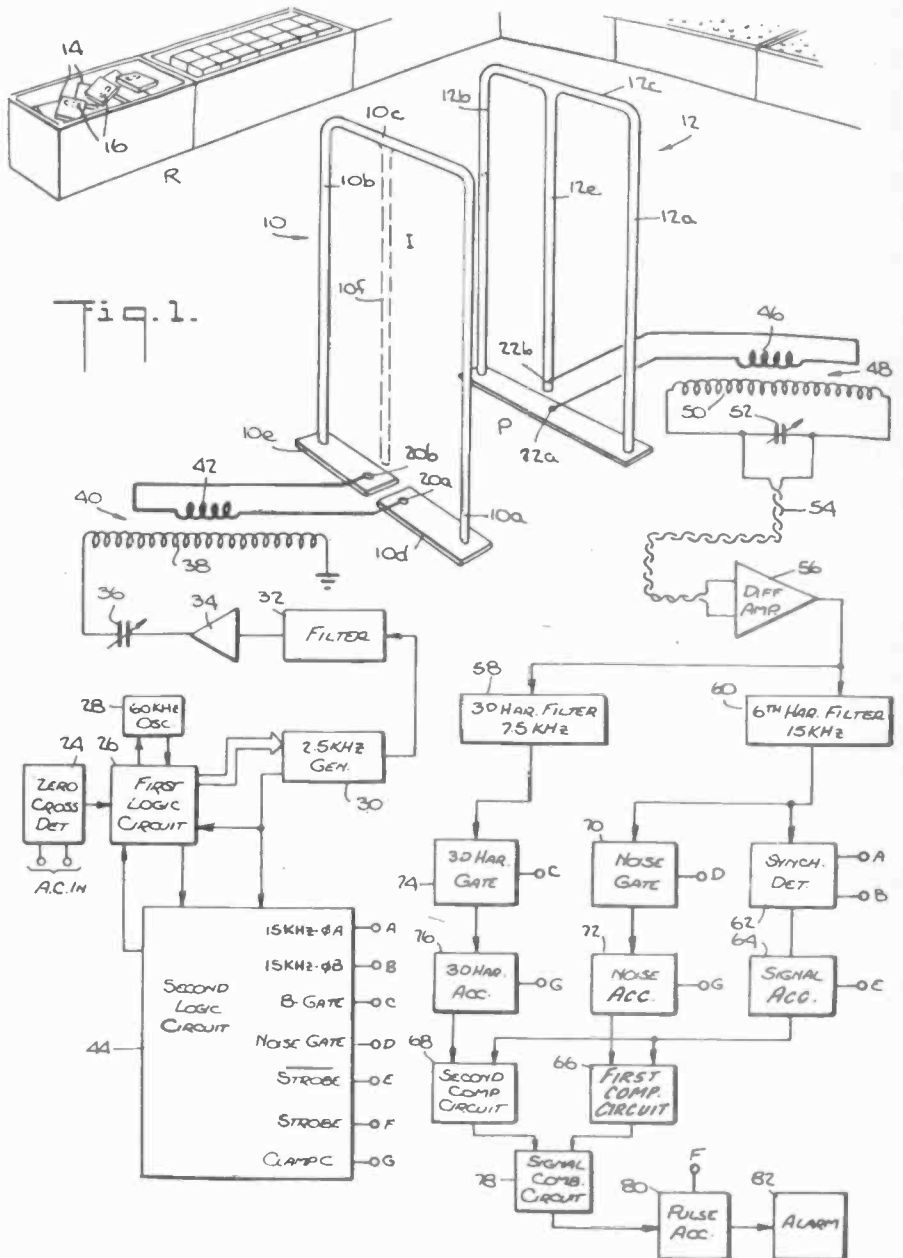
The Knogo Corporation of Hicksville USA (yes, there really is a Hicksville, USA!) has filed a British application, 2 101 454, on an elaborate approach to theft detection in shops. In Fig. 1 transmitter aerial 10 and receiver aerial 12 are arranged on opposite sides of a shop check-out point. All the goods in the shop carry targets 16 which are thin strips of magnetic material which is easily saturated in a strong field. The transmitter aerial 10 produces an alternating magnetic field of fixed frequency, around 2.5kHz, which is strong enough to cause a target strip in the check-out zone to become magnetically saturated and unsaturated in cycles synchronised to the alternating magnetic field. This makes the target emit its own alternating fields, which are at harmonics of the basic field frequency. A receiver, connected to aerial 12, responds to a selected harmonic e.g. the sixth at 15kHz, to set off an alarm when it senses a cyclically varying signal.

In practice the transmitter aerial 10 is a single one turn loop and the receiver aerial 12 is a pair of single turn loops. Mains power is fed through a zero crossing detector 24, which produces a pulse each time the voltage passes through zero. These pulses are applied through logic circuit 26 to an oscillator 28 which produces high frequency signal bursts. The oscillator output is divided down and converted into four separate 15kHz signals, each of different phase. The signals are fed to 2.5kHz generator 30 which divides them down again to produce square waves at 2.5kHz during the time periods when the oscillator 28 is on. The square wave outputs from the 2.5kHz generator 30 are filtered at 32 to produce a sine wave, which is applied to a series resonance circuit, made up from capacitor 36 and transformer primary 38.

Large currents, of over 100 amps r.m.s., are fed to the aerial 10. The receiver aerial 12 is in the form of two parallel loops, so a changing magnetic field applied uniformly to both loops induces bucking currents which cancel each other out. In this way the effect of direct transmission between the aerial 10 and 12 is eliminated. When a target strip 16 passes by the aerials it will always be closer to one of the two receiver aerial loops than the other. So its harmonic magnetic field gives a detectable current in receiver transformer coil 46. The signal is filtered to separate any sixth harmonic content. This is then pulsed and stored. When a

pre-determined number of pulses, for instance two, have accumulated during successive transmitter signal intervals alarm 82 is tripped. The storage feature prevents

false alarms through spurious harmonics getting into the system. The patent gives full details of the circuit, including component types and values.





# ROCKTONE

THE ROCKTONE is intended as a versatile aid for technicians working within the music industry, such as soundcrew, DJs and engineers, and provides a compact and robust unit which allows accurate adjustment of tone controls, graphic equalisers and crossover units of a PA system or disco amplifier. It allows correct tonal balance to be obtained by pinpointing irregularities in frequency response thus achieving a true-to-life sound system.

A sinewave is injected into the input of the amplifier/mixer of the sound system to be tested or adjusted. This signal automatically sweeps through the audio band (20Hz–20kHz), and by adjusting parameters such as the graphics, speaker combinations, position and direction, tape or phono de-emphasis etc, a superior sound may be obtained. This method, unlike expensive real-time bandwidth analysers, which need a display and precision microphone and pre-amp set-up, requires only a trained ear to set up a complete PA system in minutes, free of any spurious resonances and dropouts that may occur.

## GENERAL

The Rocktone is based on two i.c.s—the XR2206 and the LM324 quad op-amp. The XR2206 is a high-quality waveform generator which can produce sinewave frequencies ranging from a fraction of a Hz to several hundred kHz, and which may be swept over a large range using an external current source or variable resistance.

The swept frequency output is buffered/amplified and inverted by two of the op-amps to produce a balanced line output of 0dB. The other two op-amps form a comparator and monostable which produce a reset mechanism enabling the circuitry to automatically sweep and resweep through the audio band at an adjustable rate.

## OPERATION

The output frequency of the generator is proportional to the current drawn from pin 7 of IC1, given a fixed value of C3. This variable current is generated by TR1, the base current of this device being supplied by the charge stored on C4 via a limiting resistor, R2. The discharge time of C4 is determined by the setting of VR1. D2, D3 and R5, D4 in this path produce a rate of discharge that allows even time spacing between octaves, as the frequency sweeps across the audio band. The voltage on C4 is monitored by IC2a which compares this to a preset value, determined by D6 and the variable potential divider, R7 and VR4. When the voltage on C4 falls to about 0.7 volts, i.e. the base-emitter threshold of TR1, the output of IC2a goes high which triggers IC2b, the monostable. The current through TR1 is now at a minimum and thus the output frequency also falls to a minimum value.

The monostable time period (approx 10ms) is determined by R15, C6 and the hysteresis produced by R13 and R14. D8 clamps the inverting input of IC2b pin 6, to a diode drop below

0 volts. When the monostable is triggered IC2b is switched on, charging up C4 via R3, and D1 to D5 producing a constant charging voltage. D1 is introduced to prevent C4 from discharging via the charging path. TR1 consequently conducts and the output frequency rapidly increases to its upper limit, determined by R1. The frequency then sweeps down as described earlier.

The automatic sweep may be disabled, and the frequency set manually by VR2. S2a disables the comparator, while S2b discharges C4 and switches in VR2. Note that VR2 is connected in the 'anti-log' configuration.

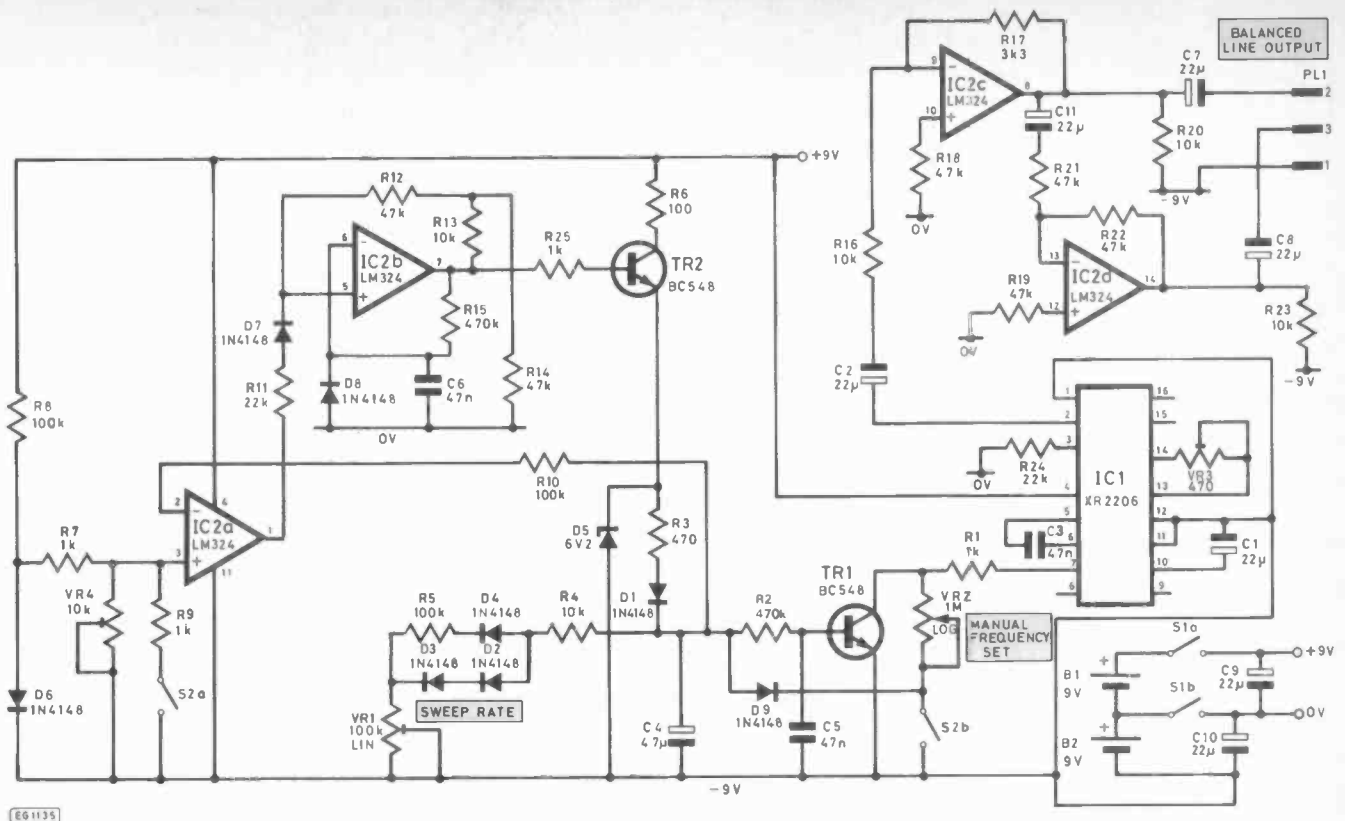
IC2c acts as a buffer/amplifier, the gain set at  $-1/3$  by R16, 17. IC2d acts as an inverter and together with the complementary output of IC2c produces a balanced output at 'line' level, about 2.2V pk-pk.

## CONSTRUCTION

Assemble the p.c.b. in the usual order, i.e. resistors first, then capacitors and diodes followed by semiconductors and i.c.s using the component layout in Fig. 3 as a guide. Check the polarity and orientation of the i.c.s, diodes and capacitors before soldering. On the prototype unit C5 was mounted on the track side of the p.c.b., care must be taken to ensure that the compo-



**D. HEAD B.Sc.(Hons) P.D'LEMOS B.Sc.**  
(OF MAZTEK ELECTRONIC SYSTEMS AND INSTRUMENTS)



EG1135

Fig. 1. Circuit diagram

ment body remains clear of the tracks. Once the p.c.b. has been assembled, solder in the connecting wires, battery clips and potentiometers, taking care to wire up VR2 in the 'anti-log' configuration, i.e. maximum resistance between the potentiometer connections in the 'off' position.

### TESTING AND ALIGNMENT

Connect up the batteries and switch the unit on with the manual override control (VR2) set to 3/4 maximum. Monitor the output of IC1 (pin 2) with the aid of an oscilloscope and

check that a 3V pk-pk 1kHz signal is present. If no signal is present, check IC1 and associated components.

Adjust VR3 for best sinewave purity, i.e. with least 'triangle ramping' distortion. Monitor the outputs of IC2c-d (pins 8 & 14), and check that there is just over 1V pk-pk of signal with respect to 0V and approximately 2.2V between outputs. If there is any variation check R16 and R17, and IC2d associated components. Adjusting VR2 should give a range of frequencies between 20Hz and 20kHz. Switch over to automatic sweep and monitor the falling frequency waveform with VR1 set maximum

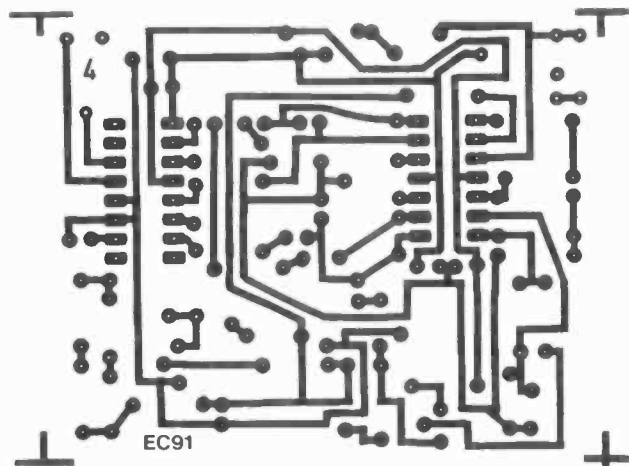
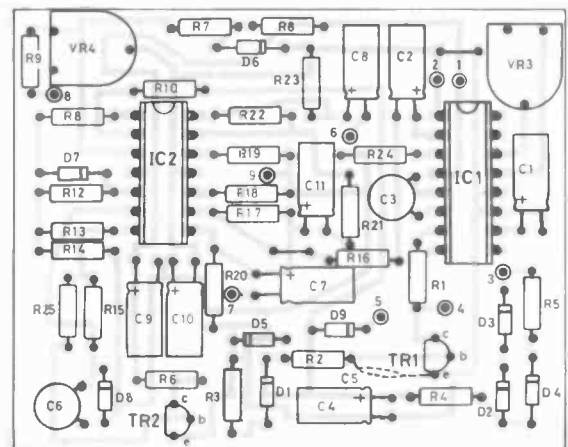


Fig. 2. P.c.b. design



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Fig. 3. Component layout

anticlockwise, i.e. slowest sweep rate. Adjust VR4 anticlockwise to decrease the lowest frequency output, which should be set at 20Hz. The sweep rate should be adjustable between about 5 and 20 seconds via VR1 and produce an even time span between octaves. If this is incorrect then check C4, TR1, VR1 and associated components.

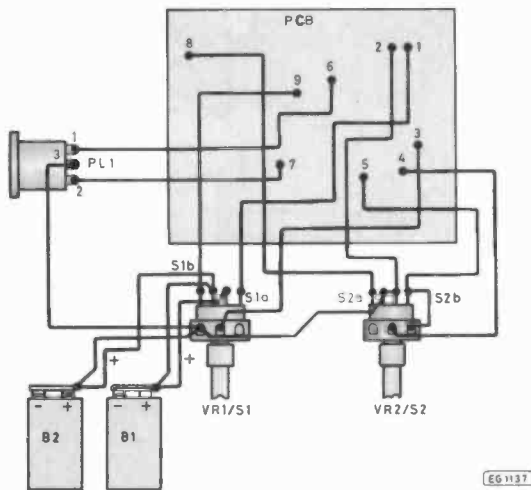
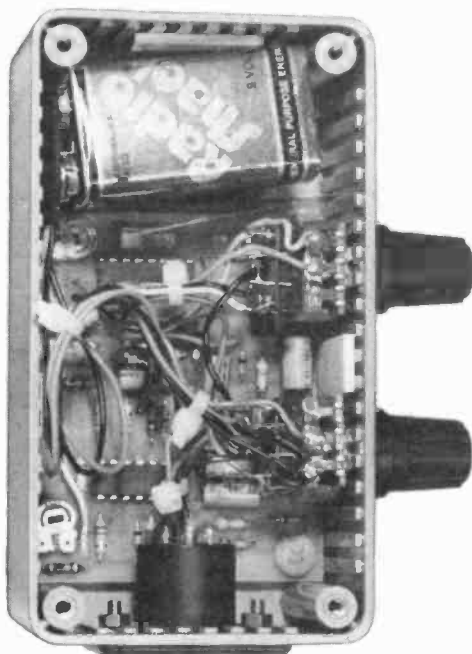


Fig. 4. Wiring details

**USAGE**

The PA should first be set up approximately using a vocal microphone or tape, the input equalisation being bypassed or set flat. Consideration should be given to the type of sound that is to be reproduced, thus providing a reasonable starting point for frequency analysis. The Rocktone can then replace the input to provide an accurate signal reference.

Using the Rocktone in its sweep mode and set to a long sweep time, the output of the speakers as affected by the acoustics of their environment can be heard. Careful attention to the volume



Final assembly showing p.c.b. in position

**COMPONENTS ...**

**Resistors**

- R1, R7, R9, R25 1k (4 off)
- R2, R15 470k (2 off)
- R3 470
- R4, R13, R16, R20, R23 10k (5 off)
- R5, R8, R10 100k (3 off)
- R6 100
- R11, R24 22k (2 off)
- R12, R14, R18, R19, R21, R22 47k (6 off)
- R17 3k3
- All resistors 1/4W 10%

**Capacitors**

- C1, C2, C6 to C10 22µ 16V electrolytic (7 off)
- C3, C5 47n ceramic (2 off)
- C4 47µ 16V electrolytic

**Semiconductors**

- D1 to D4, D6 to D9 1N4148 (8 off)
- D5 6V2 Zener, 400mW
- TR1, TR2 BC548 (2 off)
- IC1 XR2206
- IC2 LM324

**Potentiometers**

- VR1 100k Lin (miniature) plus dpst switch
- VR2 1M Log (miniature) plus dpst switch
- VR3 470 preset
- VR4 10k preset

**Miscellaneous**

- P.c.b. (see Constructor's note)
- Case, about 40 x 65 x 180mm
- PL11, XLR Series Connector, 3-pin plug
- 9V PP3 battery (2 off)
- Battery clips (2 off)
- Knobs (2 off)

**Constructor's note**

A complete kit of parts for this project is available from **Watford Electronics, 33 Cardiff Road, Watford, Herts (0923 40588)**. The kit is priced at £19.95 including VAT and p&p.

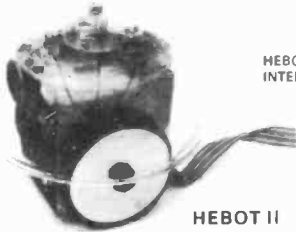
present in the room as each frequency sweeps through will reveal resonances of loud peaks and weaknesses where response is poor or absorption is high. Output equalisation should now be readjusted to provide a smoother response. As the response becomes increasingly flat with adjustment, smaller variations will become audibly apparent. It is common with most sound systems to have frequency bands of particularly high irregularity, often at 100-300Hz, 1-2.5kHz, and at 5-6kHz as cross-over points, cabinets, drivers, filters and amplifiers peak. These points will produce a warbling sound during incorrect adjustment when swept.

Use should also be made of the manual frequency control facility to pinpoint the frequencies concerned, rolling the frequency back and forth over the band required. With some practice and attention to detail a smooth response will be obtained. As a final check, the whole band should be covered at a fast sweep rate. Professional use of this unit at major European and UK concerts has revealed several additional uses for the Rocktone. It has proved invaluable for testing speakers, filters, signal cables, channel and effects patching and in the workshop as a general purpose frequency generator. ★

# Get moving with these new developments in UK Robotics

— advanced electrohydraulic designs for education, industry and now available to the home constructor.

Hebot II is a turtle-type robot which takes programming out of the two dimensional world of the VDU into the real three dimensional world. Given a DC supply of 9-15V it can perform a bewildering number of moves under computer control — forwards backwards, left and right — with each wheel independently controlled. It has blinking eyes, bleeps with a choice of two tones and has a solenoid operated pen to chart its progress. Touch sensors coupled to its shell return data about its environment to the computer for it to calculate evasive or exploratory action. Hebot II connects directly to an I/O port or alternatively with the universal interface board to the expansion bus of a ZX81 or other computer.



HEBOT II

Up to the nano-second hard, firm and software developments embodied in a complete system. 12 Mega Hertz 16 bit CPU; 64K upwardly compatible DRAM; separate 16K video DRAM and 24K TI Power Basic with overwrite. Supports up to four Disc drives of mixed type with 16 serial I/O ports. Programmable Baud rate and comprehensive E Bus interface designed to support real world applications.

Very high resolution graphics gives 3D simulation in 16 colours on 36 prioritised planes of user definable characters. Software FORTH coming includes this trendy language along with NOS C/PM.

Hardware components available separately with details in Nov. Dec. and Jan issues of ETI. Software features include: Real time clock, full renumber command, buffered I/O to free machine whilst

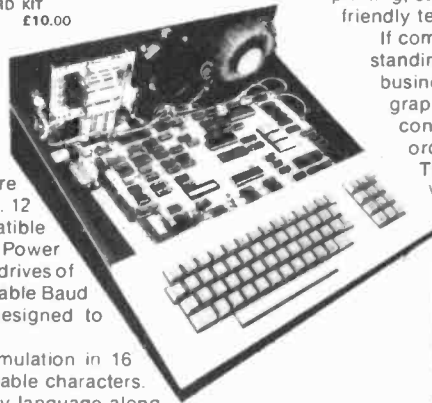
Robotic experience is becoming as essential a subject as computing. MICROGRASP provides the lowest cost means of acquiring that experience but despite its ultra low price the robot has considerable versatility. There are 5 axes each using a servo motor and there is feedback from each of the arm movements. Control is by any computer with an expansion bus — the ZX81 being particularly suitable. Servoing is achieved with hardware on the interface board to keep programming simple and the robot is operated under BASIC commands with no computer specific software required. The interface board is memory mapped using only 64 bytes at any of 1024 switch selectable locations.

MICROGRASP robot kit with power supply £145.00  
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MICROGRASP, INTERFACE BOARD AND ZX81

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printing, call to machine code routines, hexadecimal support and user-friendly textual error trapping messages.

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Top of the range is the Genesis P102 which has dual speed control, continuous servo operation and double acting cylinders for increased torque on the wrist and arm rotation joints. The microprocessor based control system has additional memory, position interrogation via the RS232C interface increasing the versatility of computer control and inputs are provided for machine tool interfacing.

6 axis system READY BUILT

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 Lifting capacity: 1500gm  
 Arm lift: 6.6"  
 Weight: 29Kg  
 4 axis model in kit form £425  
 5 axis model in kit form £475

**Genesis P101**  
 Base: 19.5" x 11" x 7.5"  
 Lifting capacity: 2000gm  
 Arm lengths between axes: 14.0"  
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 6 axis model in kit form £675

Complete Systems as shown in Photograph on right

**Genesis S101**  
 4 axis system in kit form £681.50  
 5 axis system in kit form £737.50  
 5 axis system Ready Built £1450

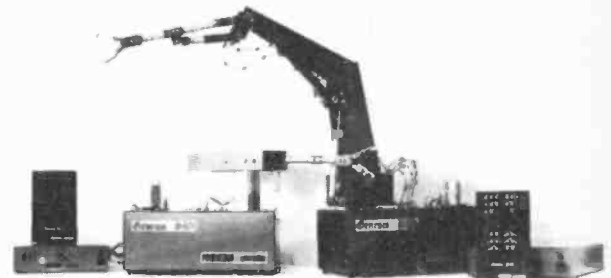
**Genesis P101**  
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All prices exclusive of VAT

With prices starting below £1,000 the Genesis range of general purpose robots provide a first rate introduction to robotics for both education and industry. Each has a self-contained hydraulic power source which enables loads of several pounds to be smoothly handled. The system operated from a single phase 240 or 120V AC supply or a 12V DC supply. The machine can be supplied with up to 6 axes each of which is fully independent but capable of simultaneous operation. Position control is achieved by means of a closed-loop feedback system based around a dedicated microprocessor. Movement sequences can be entered, stored and replayed by use of a hand held controller. Alternatively the systems can also be interfaced to an external computer via a standard RS 232C link.



GENESIS P102 PROCESSOR BOX AND HAND HELD CONTROLLER



GENESIS S101 AND GENESIS P101 WITH PROCESSOR BOXES AND HAND-HELD CONTROLLERS

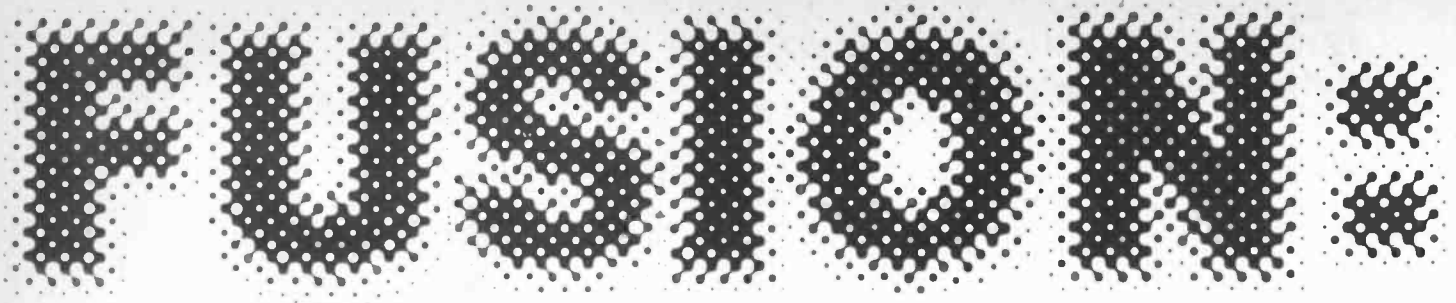


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**T**HE DREAM a few decades ago, of abundant cheap energy, began as a nightmare. The power of the atom first flashed its awesome might across two Japanese cities. Yet as the horror subsided into that dream of peacetime nuclear power, mankind's fleeting phantasm of a clean, cheap energy culture threatened to revert to a nightmare again. Many feel that the unstable dream, in its original form at least, now lies at the bottom of the sea in a cannister marked "Radio Active Waste". Some argue that it has been stamped "Unmanageable", and laid to rest on Three Mile Island. Whatever the case, in the 1980s energy is neither cheap, nor abundant. The great illusionist is *fission*—the process of splitting atoms to generate heat, to generate steam, to generate electricity. Fission produces high energy radiation, and creates spent fuel that is a menace for generations.

#### INCREDIBLE OBJECTIVE

Matter to energy! Is the alchemy not safely possible? Collectively, Europe intends to find out. Whilst the Sizewell debate radiates through the media, a far more portentous project which *really could* change our lives, is quietly forcing back the frontier of nuclear engineering. The project, based at Culham in Oxfordshire, is known as the Joint European Torus (JET). The complex houses the most ambitious *fusion* venture of the European Atomic Energy Community (Eurotom). As far as the fusion alternative is concerned, only one mechanism has the potential to produce enough heat to generate commercially viable electric power. This toroidal machine is called a Tokamak, and at Culham they have constructed a leviathan.

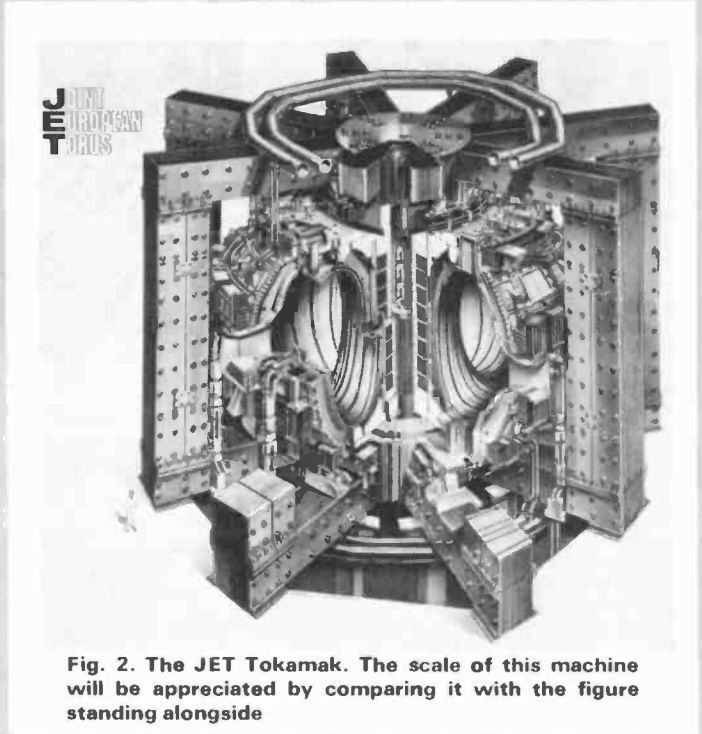


Fig. 2. The JET Tokamak. The scale of this machine will be appreciated by comparing it with the figure standing alongside



Fig. 1. Aerial view of the JET laboratories at Culham, in Oxfordshire

Fission's only attribute is the bare fact that it can generate electricity, but because of its deadly pollution it lacks widespread approbation. Fusion, on the other hand, could fulfil the promise of a renewable energy source *without* the need to handle and dump toxic wastes. An elegant, but demanding alternative, as you will see.

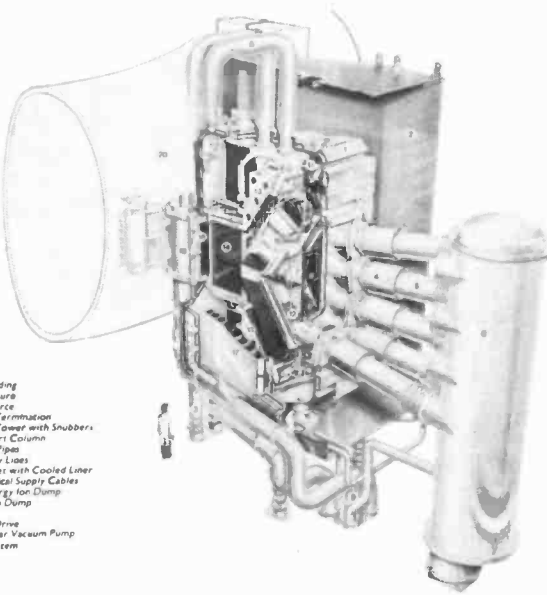
The objective of the JET project is to create a plasma with a size, density and temperature comparable to that required by a power producing reactor. This plasma will need to reach a temperature of 100 million degrees centigrade. The plasma column will be about two metres in diameter, and have a density 100 million million atoms per cubic centimetre. Although many other difficulties lie in the path towards an economic fusion power station, achieving these parameters on the JET will be a quantum leap forward.

Plasmas, and their physics are complicated, and not yet fully understood by scientists. There is no guarantee that the JET apparatus, designed in 1974, will be able to achieve the specified parameters. The *Joint European Torus* is nevertheless thought to be the most advanced Tokamak of its type in the world. In it incredible electric power is required to heat up the plasma. Even the 4.8 million amperes heating current is totally inadequate to generate the plasma temperatures necessary for nuclear fusion.

# Towards

# REALITY

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- 13 Full Energy Ion Dump
- 14 Calorimeter
- 15 Calorimeter Drive
- 16 Turbomolecular Vacuum Pump
- 17 Cropping System
- 18 Fast Shutter
- 19 Rotary Valve
- 20 JET Torus

**Fig. 3. The neutral injection system. This beams energetic neutral hydrogen atoms into the plasma. The power supply for this system is regulated and switched by large tetrode valves**

Further heating must be introduced by squirting in highly energetic neutral atoms, a process called Neutral Injection heating (Fig. 3). Still more energy has to be found by way of high energy Radio Frequency heating (Fig. 4).

Over a period of some four years, starting in 1983, the plasma power capability of the Tokamak will be increased in stages until it reaches 25 megawatts. At full power, temperatures averaging 50 million degrees are anticipated; at which stage the thermonuclear reactions brought about by the introduction of deuterium-tritium plasmas, will push the temperature up to the required 100 million degrees centigrade. If ignition is achieved, the powerful external heating systems can be turned off, leaving the plasma temperature to rise by itself until the end of the pulse. The less fortunate outcome would be that the plasma simply does not reach a high enough temperature to justify the use of tritium.

## WHAT IS FUSION?

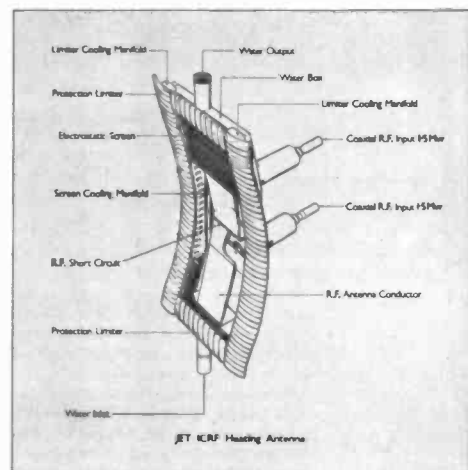
At the centre of every atom is a nucleus comprising positively charged protons, and uncharged neutrons. Orbiting this cluster, as if in a microscopic solar system, are negatively charged electrons. The strength of the invisible force which holds together

the cluster of protons and neutrons varies from element to element, but it is possible to create a nuclear reshuffle in which a surplus quantity of that binding energy is released. Fusion is such a reshuffle, for it is the *fusing* together of two or more elements into one or more heavier elements, during which there is a yield of surplus binding energy. In the case of deuterium (D) and tritium (T), helium, and a neutron are also released upon fusing.

Deuterium and tritium (the two heavy isotopes of hydrogen) are favoured because they have a high reaction rate whilst imposing the least stringent conditions. Deuterium could not be more plentiful on this planet, as it is obtained from ordinary water. Tritium, however, is rare, but can be manufactured from the fusion process itself. By bombarding a blanket containing lithium (which is plentiful) with those expelled neutrons, both tritium and helium are produced.

## THE NEED FOR HEATING

Because the deuterium and tritium nuclei each have a positive electric charge they strongly repel each other. They simply will not come close enough together for a fusion reaction to occur. The way to overcome this obstacle is to impart sufficient energy to their nuclei to overcome the mutual electrostatic repulsion. Heating the gaseous fuels to a very high temperature will do just that, by ionising them—stripping the electrons away from their parent nuclei. The result is a mixture of positively and negatively charged particles. A gas in this disrupted condition is called a



**Fig. 4. Radio frequency heating antenna. Operates at the ion cyclotron frequency (25–55MHz on the JET)**

plasma. See Fig. 5. At 100 million degrees centigrade, abundant fusion reactions occur in a deuterium-tritium plasma, releasing large amounts of energy.

### WHAT IS A TOKAMAK?

There is no known material out of which a vessel could be made, to contain a one hundred million degree inferno without itself vapourising. Yet containment is essential if the amount of energy produced by fusion is to exceed the amount of power required to run the system. The latter requirement is an obvious precondition, and is expressed as the product of fuel density and confinement time (known as Lawson's Criterion).

Since a plasma is a mixture of charged particles it can be influenced by a magnetic field, and for over thirty years investigations into how to achieve the magnetic suspension of a fusion reaction have led to a machine called the Tokamak. In this configuration, even though high temperature plasmas have a natural tendency to expand, they remain in a compressed column, held there by a magnetic force for periods in excess of one second. The plasma's charges whirl around randomly, unable to escape. See Fig. 6. Because of this, heat is not lost, nor are impurities released through contact with any physical object—in theory at least. But even the Tokamak is only partially efficient in these aims.

### THE JET TOKAMAK

A complex array of magnetic circuits are required to activate the JET Tokamak. The main component of the system is the set of toroidal field windings which are used to suspend the plasma. In shaping the plasma column, these toroidal coils, shown in Fig. 7, are assisted by poloidal coils. However, the most interesting field action is that of the transformer which induces the plasma heating current. Whilst the primary of this is also a poloidal winding, its secondary is the plasma itself. The toroidal circuit of plasma acts as a single-turn secondary winding.

The JET will use hydrogen plasmas during its early life, before moving on, if successful, to deuterium-tritium plasmas to obtain a fusion ignition.

### ENGINEERING STATISTICS

The accompanying photographs show the standard of engineering required to build the 100 tonne vacuum vessel and its peripherals. The 32 toroidal field coils alone add up to 384 tonnes (12 tonnes a piece), and these are each 24 turns of heavy

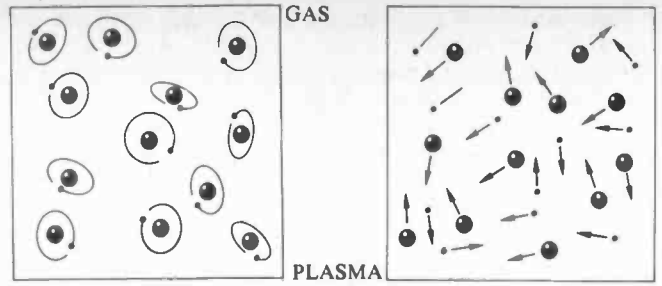


Fig. 5. Heat turns gas into plasma by dislodging the electrons from their orbits

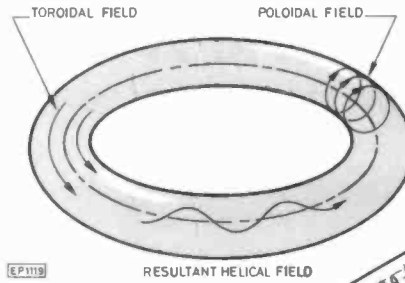
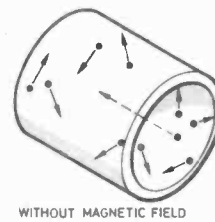
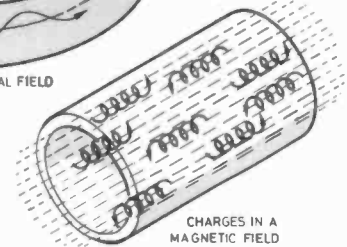


Fig. 6. The Tokamak is a toroidal vacuum container in which plasma is suspended away from the inside surface by a magnetic field set up by external coils



WITHOUT MAGNETIC FIELD



CHARGES IN A MAGNETIC FIELD

Fig. 7. The JET inductive system simplified. The plasma itself acts as a winding, to heat and shape the plasma

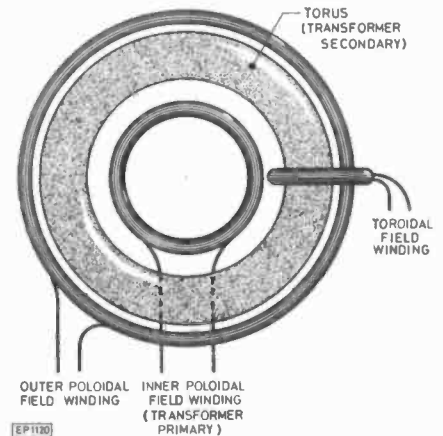
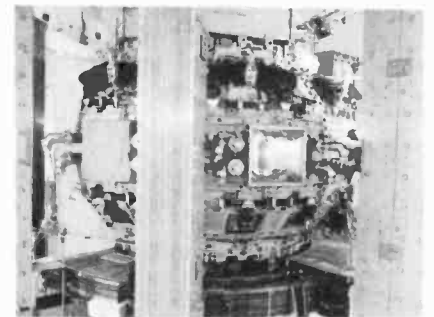
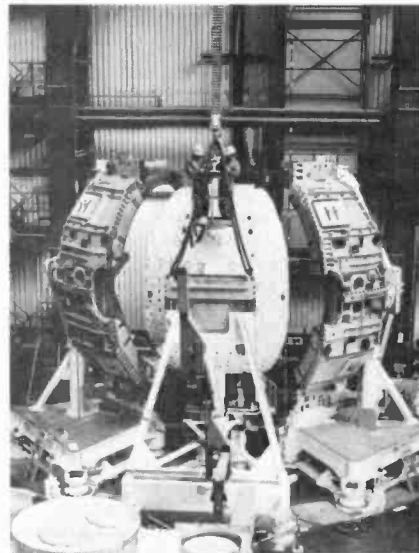
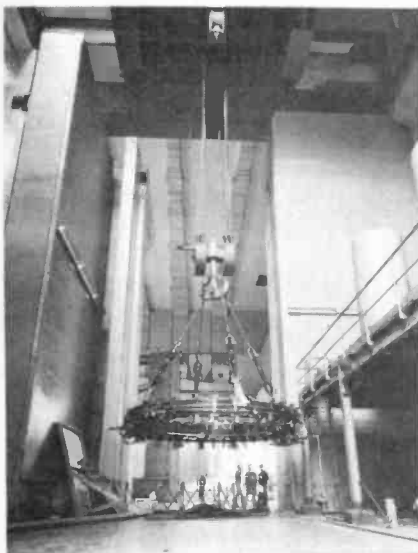


Fig. 8 (leftmost). A poloidal field coil suspended during construction

Fig. 9. An octant is seen being lowered into position

Fig. 10. Complexity of the JET hardware is apparent during construction



copper bar capable of conducting 66,000 amperes. It takes 700 litres of water per second to cool these coils. In the fully completed design, the total magnetic field at the plasma centre will be 3.4 Teslas. The coils are "D" shaped because this is the shape they would deform to, if flexible, under the 2000 tonnes of mechanical force developed by their own magnetic field. This geometry, therefore, gives rise to minimum stress. Magnetic effects produce an enormous twisting moment throughout the entire structure, which is designed to withstand up to 20,000 tonnes metre.

The torus hall is built around a pit housing the ring manifolds which supply water, the vacuum and hot carbon dioxide to the machine. The massive limbs of the magnetic circuit (Fig. 12), the bulkiest components of all, support the toroidal structure. This toroidal vacuum vessel is fabricated from eight welded sections, called octants. The vessel has to support a very high vacuum, and so before each run is baked at 500°C for several hours to "descale" its surfaces of potential gas forming particles, otherwise outgassing would offset the pressure. This is the purpose of the hot carbon dioxide supply. Welding between octants is so superb that it would take 3000 years for one litre of air to penetrate the system.

In use, conventional heating elements attached to the vessel help to achieve the base pressure of  $10^{-10}$  torr. required to minimise the level of impurities in the plasma.

Materials and engineering parts for the JET have been manufactured by industry throughout Europe, and the project has cost around £500 million.

#### FLYWHEEL GENERATOR

It would be unfair to dim the lights of Oxfordshire every time the JET is pulsed. With its 700 megawatt thirst for power, a substantial part of the supply has to come from two flywheel generators, each accelerated by a 8.8 megawatt pony motor. Flywheels weighing 775 tonnes rotate at 225 rev/min to make 2600 megajoules available to the Tokamak (Fig. 14). Four rectifier stacks convert the first rotor's output to d.c. for the toroidal coils. In the case of the poloidal field, specially designed fast air-blast circuit breakers initially interrupt 80 kiloamperes to generate a back e.m.f. capable of ionising the gas. This system also allows reversal of the poloidal coil connections to obtain maximum flux change in the heating current transformer.

Fig. 11. Octants awaiting assembly. A toroidal field winding assembly is in the foreground

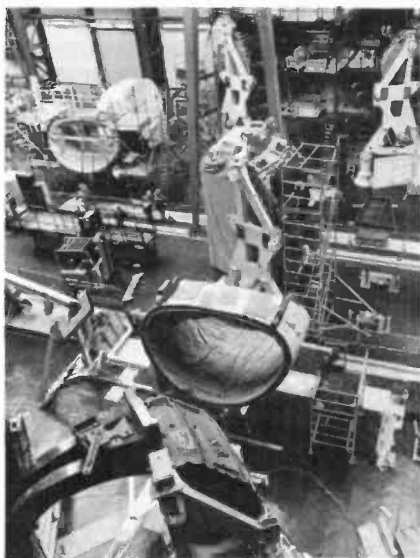
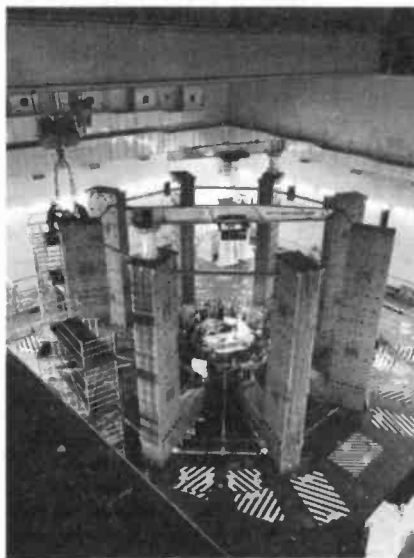
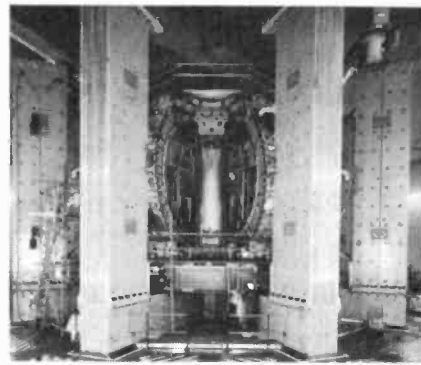


Fig. 12. Apparatus under construction, showing the massive transformer limbs



All photographs courtesy of the JET Joint Undertaking

Fig. 13. Octants in position between the transformer limbs



#### COMPUTER CONTROL

The JET is a learning tool, and because of this its computers have a dual task; the first being to control the operating parameters, the second being data acquisition and storage. A network of 25 Norsk Data ND-100 and ND-500 minicomputers is used in a hierarchical structure, in which each processor monitors its own part of the machine. Information is transmitted along fibre-optic loops at a rate of 5 million bits per second, and each pulse of the JET results in the collection of over one million datum entries.

The Control Room's ND-560 computer files the data for use by the experimentalists, before transferring it to Culham Laboratory's large computers for further analysis, and archiving.

#### DIAGNOSTICS

Gathering information about the behaviour of high temperature plasmas obviously cannot employ sensors requiring physical contact with it. Passive, and active particle beams, light, and electromagnetic radiations are used. Fig. 15 shows the complexity of the diagnostic equipment.

*Plasma position* within the vessel is detected using inductive coils integrated into the vacuum vessel wall.

Interferometers detect the delay, measured against a microwave or infra-red reference beam, caused by electrons in the plasma. This allows measurement of *electron density*.

The *type, density and temperature* of energetic atoms within the plasma determines the wavelength and intensity of emitted light. Spectrometers are used to detect this light emission.

*Local values of electron density and temperature* are discovered by a technique called Thomson Scattering. In this, the degree of scattering of high intensity, pulsed laser light is observed.

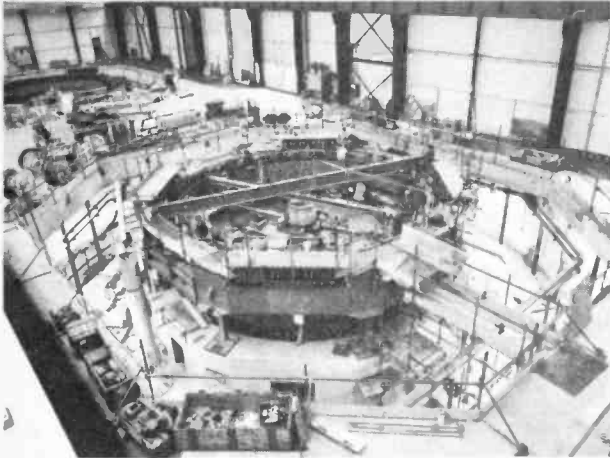
*Plasma ion temperature* is ascertained by observing the neutral particles escaping from the plasma. These particles have thermal equilibrium, and escape through the magnetic barrier because of their neutrality.

A bolometer measures the broad spectrum of *radiated energy loss*. A temperature-sensitive resistor mounted on a foil absorber acts as the detector.

Measurement of the plasma's X-ray emission yields information on *density, temperature and impurity content*.



**Fig. 14. One of the 400MW flywheel generators under construction. Two of these generators supply power to the Tokamak, which, when surge loaded, drop to half speed. The rotors weigh 775 tonnes each!**



In the latter phase of the JET's life, measurement of the neutron emission during fusion will reveal the *reaction rate*.

Once deuterium-tritium fusion has occurred, this high energy neutron radiation will have activated the machinery, seriously restricting access by personnel. For this reason, all sensory transmitting and receiving equipment has been mounted outside the biological shield, despite the alignment exactitudes this imposed.

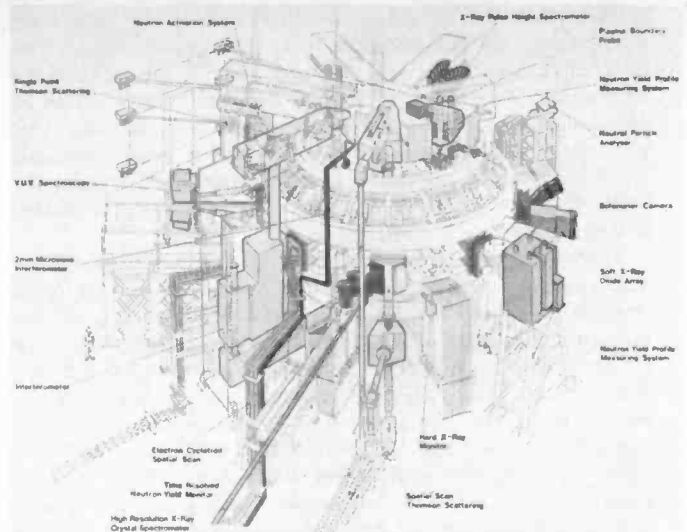
#### SERVOMANIPULATORS

Once irradiated, it will be unsafe for human beings to inspect the torus walls, or service the machine's auxiliary equipment. However, the unpredictable nature of the handling places this work outside the realm of programmable robots. It was decided to employ remote handling manipulators which operators control by viewing through closed circuit television links. The slave unit, at work in the radio active area, is designed to reflect back to the operator the forces exerted by its manipulator. This gives a "feel" to the operator as he remotely uses power tools, spanners and welding torches, etc.

#### LEAGUE OF FOUR

Only four large Tokamaks exist, either completed or under construction. Apart from the European torus, there is the

**Fig. 15. JET diagnostic system**



USSR's T15, the USA's TFTR, and Japan's JT-60.

The release of energetic neutrons from this type of machine could be used to heat up a surrounding blanket, in order to raise steam for a conventional steam-turbine generator. No such provision to generate electricity has been made on the JET, as this will be the subject of study for the next generation of fusion experiments.

At the time of going to press, it was thought that the JET would be powered up for the first time in June 1983.

The Sun is a typical star, producing  $3.3 \times 10^{26}$  joules per second by fusion, and is consequently reducing in mass at a rate of  $4.2 \times 10^9$  kg/s (one millionth of its total mass every ten million years).

The thermonuclear reactions which make our sun shine will not be casually mastered; notwithstanding Culham's wrestling ground, the commonplace fusion power station is reckoned to be sixty years away. In the meantime, therefore, fission, with all its imperfections, will continue to serve in an era of its own. ★

#### ACKNOWLEDGEMENTS

The technical data in this article is based entirely on material supplied by the JET Joint Undertaking. All photographs and diagrams shown are courtesy of same.

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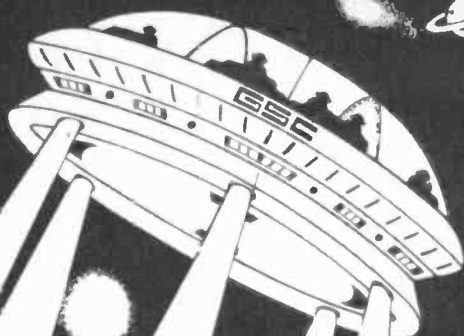
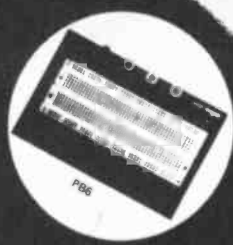
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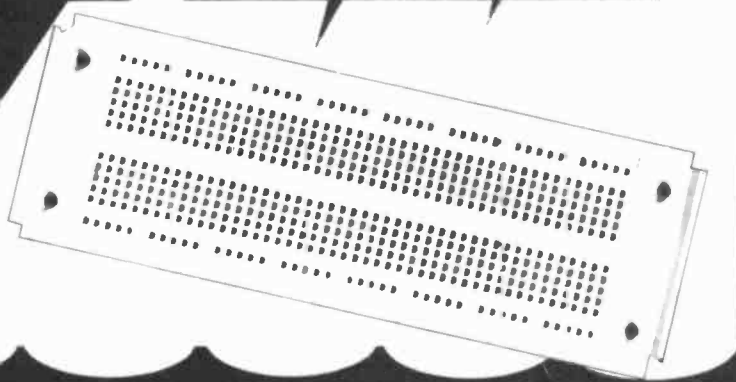
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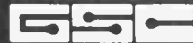
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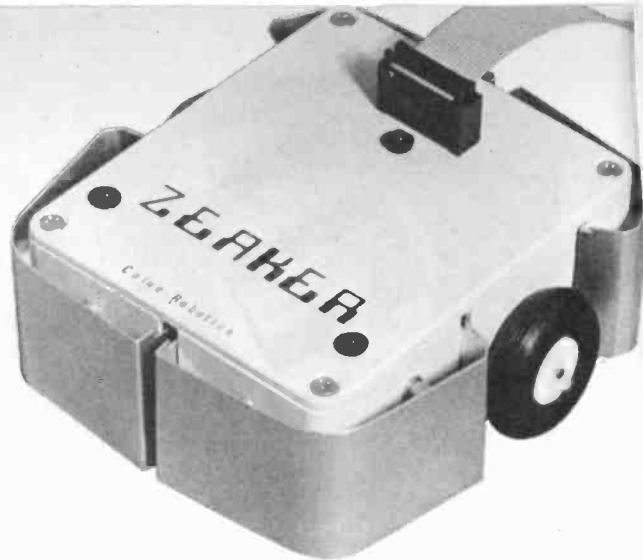
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# ZEAKER

## MICRO-ROBOT

PART 2

DAVID BUCKLEY



In the Control Station the holder for the four C-cell Nicads is bolted to the bottom of the box (actually the lid, but the box is used upside down), offset towards one side to allow room for the power/charge lamp. The Nicad supply on/off switch and indicator l.e.d. are fitted to the front of the box. The 3.5mm jack socket for the ZX81 power supply and 2½ foot link to the ZX81 are fitted to the rear.

The three 16 way ribbon cables (two to the computer interface board and the umbilical to Zeaker) leave the box through cut outs in what is now the lid, these should be of a size such that the ribbon cable is just clamped when the box is closed.

### CONTROL STATION CIRCUIT DESCRIPTION

The circuit (Fig. 1) can be divided into two distinct parts: the computer READ port and the computer WRITE port. In the prototype both these ports are memory mapped at address 35000 decimal.

Dealing first with the READ port. Data lines D0 to D7 are normally held high by resistor pack IC3. Lines D6 and D7 terminate on pads inside Zeaker and are not used hence D6 and D7 are always high. The remaining lines D0 to D5 terminate at the insulated pillars set into the sides of Zeaker and indicate the state of the tactile sensor switches, a low data line implying that Zeaker is touching something (see table of sensor codes). All the fenders are connected to 0V and on impact with an obstacle a fender will move in and make contact with one or more pillars, hence shorting the respective data lines to 0V.

Turning now to the WRITE port. D0, D1 control the port drive motor; D1, D2 control the starboard drive motor; D4 the pen; D5 the lights; and D6 and D7 the horn.

One end of the port drive motor goes to the centre tag of the battery and the other to the junction of TR3 and TR4. Turning on TR3 will cause the motor to run forwards and turning on TR4 will cause it to run in reverse.

D0 high is port motor forwards and D1 high is port motor reverse. IC1a and IC1b are wired as a set reset latch which ignores the condition D0 high and D1 high, so preventing destruction of TR3 and TR4.

When D0 goes high the output of IC1a goes low, so turning on TR2 which turns on TR3, when D0 is low TR2 is held off by R2 and R3. TR1 is normally held on by R1 and R4 and so shorts TR4 base to earth but when D1 goes high the output of IC1b goes low and turns off TR1, TR4 is now able to turn on by base current through R5.

The operation of the starboard motor is similar except that forward and reverse are switched around so TR8 on gives starboard motor forwards. This evens out battery drain when going forwards or backwards.

Data line D4 high turns on TR9 which turns on TR10, switching on the solenoid which lowers the pen. The l.e.d. D3 provides indication that the solenoid is activated. Diode D4 is to short out the inductive high reverse voltage when current through the solenoid is halted by TR10 turning off.

Data line D5 high turns on TR11 which turns on TR12, lighting D1 and D2, the red and green l.e.d.s.

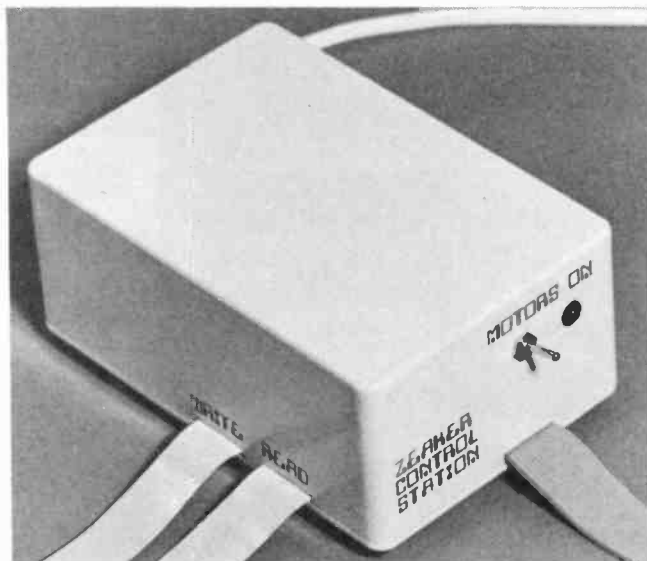
Data lines D6 and D7 control the horn, via the reset lines of IC2 which is wired as two astables. The frequency components R20, R21, C2 and R22, R23, C5 were chosen by experiment so that the tones sounded right when both are on together. C3 and C4 are the usual blocking capacitors.

### CONTROL STATION PCB

The p.c.b. for the control station is shown in Fig. 2 with the component layout shown in Fig. 3. The resistors by the 556 are mounted on end but the others are mounted flat. There are a number of wire links to be soldered in place and these are best done with insulated wire. None of the transistors need heatsinks and are all mounted vertically. The three 16 way flying leads can be soldered directly into the p.c.b. but it is easier to use headers on the leads and plug them into the p.c.b.

### CONTROL STATION CHECKOUT

The easiest way is to plug the read and write cables into the interface board, plug the ZX81 power supply into the back of the control station and plug the flying power lead







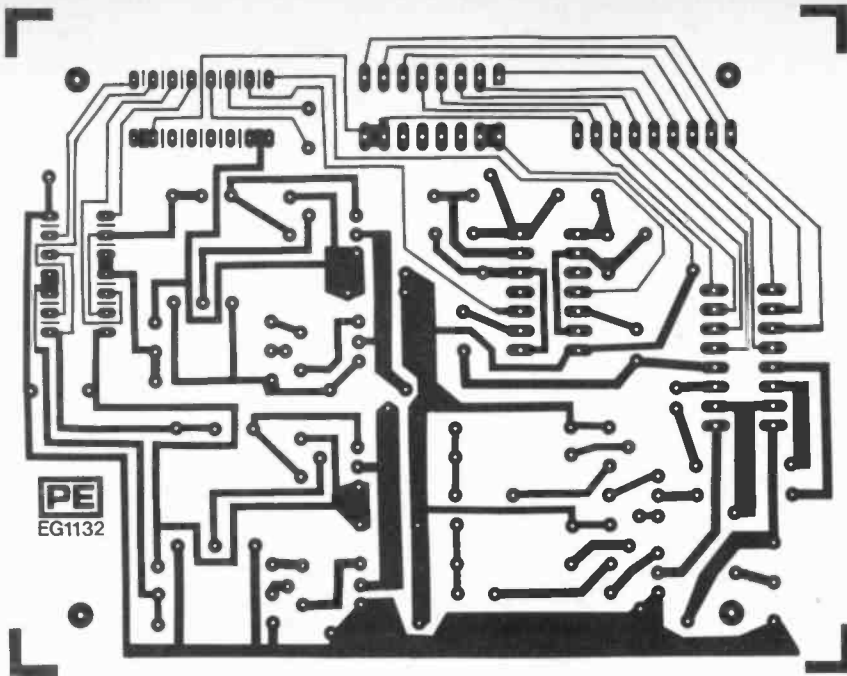


Fig. 2. P.c.b. design

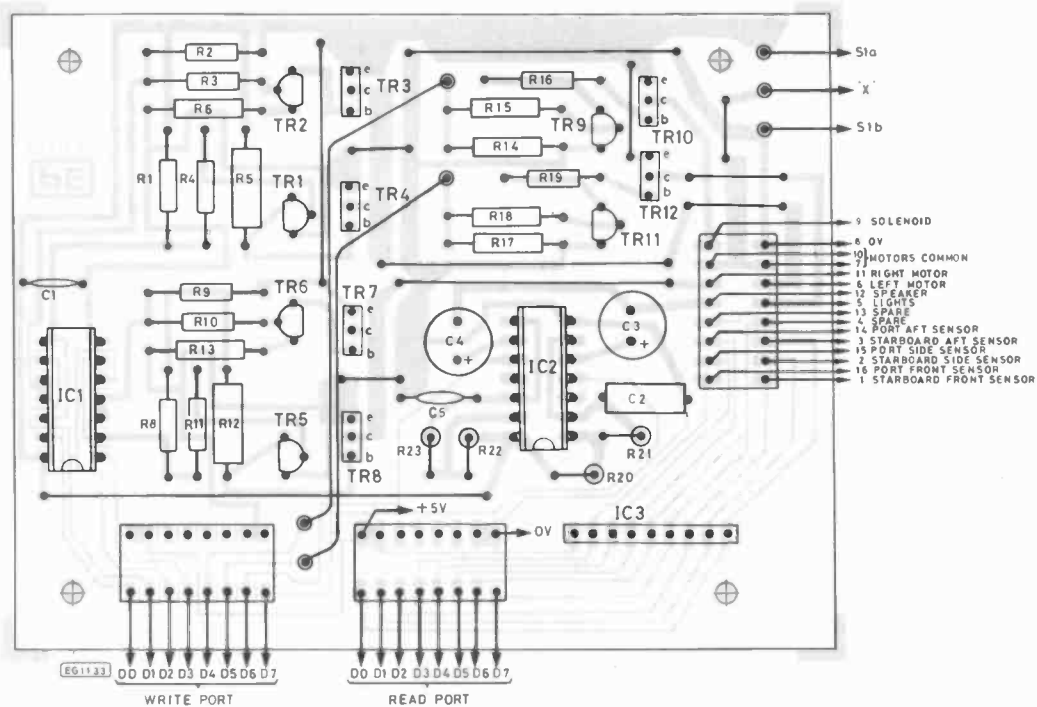


Fig. 3. Component layout

bits (6 for the unexpanded Zeaker). The particular way that these are available will depend upon the microcomputer and interface used. The signal allocation for the output and input connector leads are shown in Fig. 5.

Writing (POKEing for a memory mapped port) a word to the port sets the respective bits of the output latch. Reading (PEEKing) the port will return the status of the bump sensors.

A list of the control codes and their effect is given in Table 1. Any combination of control codes can be written to the port and Zeaker will be controlled by their combined effect e.g. writing a 1 will set the port motor to forwards and writing a 4 will set the starboard motor to forwards, hence writing 5 (=4+1) will set both motors on forwards. Writing 37 (=5+32) will set both motors on forwards and also switch on the lights.

# COMPONENTS . . .

## CONTROL STATION

### Resistors

R1,R2,R3,R4,R8,R9,R11, R19,R20,R22	10k (10 off)
R5,R12 $\frac{1}{2}$ W 10% carbon	820 (2 off)
R6,R13 $\frac{1}{2}$ W 5%	470 (2 off)
R7	100
R14,R17 $\frac{1}{2}$ W 2%	1M (2 off)
R15,R18 $\frac{1}{2}$ W 5%	4k7 (2 off)
R16,R19 $\frac{1}{2}$ W 2%	220 (2 off)
R21 $\frac{1}{2}$ W 5%	220k
R23 $\frac{1}{2}$ W 5%	56k
All resistors $\frac{1}{4}$ W 5% carbon except where otherwise stated	

### Capacitors

C1	100n ceramic disc
C2	10n ceramic disc
C3,C4	47 $\mu$ 16V elect (2 off)
C5	22n ceramic disc

### Semiconductors

D1	red l.e.d.
TR1,TR5,TR9,TR11	BC238 (4 off)
TR2,TR6	BC308 (2 off)
TR3,TR7,TR10,TR12	BD132 (4 off)
TR4,TR8	BD131 (2 off)
IC1	74LS00
IC2	556
IC3	pack of 8 commoned resistors RS type 140 271

### Miscellaneous

- ABS plastic box 150 x 100 x 60mm
- Battery holder for 4 C-cells
- Nicad C-cells (4 off)
- MES lampholder
- MES 12V 280mA bulb
- Double pole on/off switch
- 3.5mm jack plug and socket
- 16 pin d.i.l. IDC header (5 off)
- 16 pin d.i.l. sockets (3 off)
- 14 pin d.i.l. sockets (2 off)
- 3 metres of 16 way grey ribbon cable
- Molex 16 pin JD connector to mate with the 5332 series connector on Zeaker

### Constructor's Note

The toe cover cap is available from most hardware stores and the wheels and motor gearboxes assemblies are obtainable from hobby shops.

A complete kit of parts for the vehicle (including machined, cut and ready-bent items) and control station with a manual and software is available from Colne Robotics Ltd., Beaufort Road, off Richmond Road, Twickenham TW1 2PH (01-892 8197/8241). Price £59.95 inc. VAT.

Colne Robotics are also able to supply the separate parts, please write or phone for details.

The two longer programs mentioned in the text are available from Colne either on cassette or as a print-out. Please state the type of computer being used with Zeaker when ordering programs.

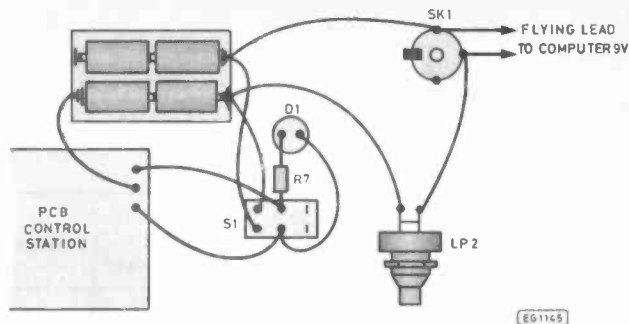
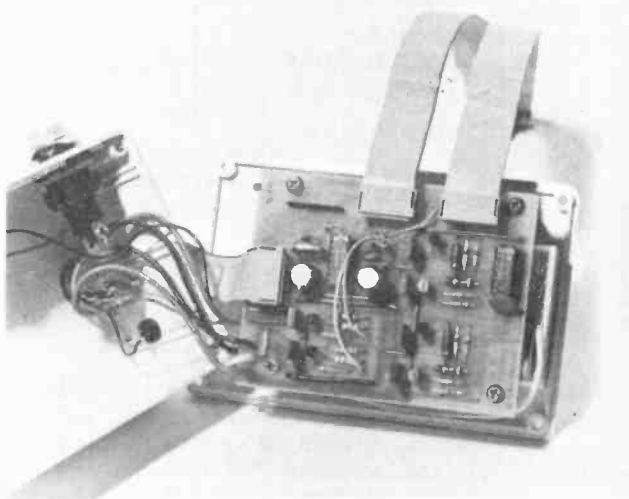
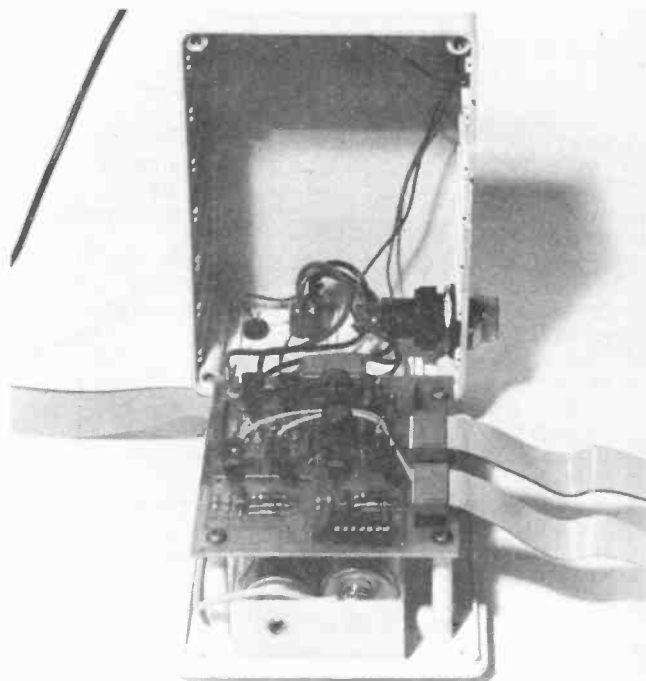


Fig. 4. Wiring diagram



Interior views of the Control Station showing the battery housing and the p.c.b. mounting details

FROM COMPUTER WRITE PORT

								Pin 1
D7	D6	D5	D4	D3	D2	D1	D0	
0V	0V					5V	5V	

TO COMPUTER READ PORT

								Pin 1
D7	D6	D5	D4	D3	D2	D1	D0	
0V	0V					5V	5V	

UMBILICAL CORD

0V	Motor Common 2.5V	Motor Starboard	Lights	Spare	Sensor Starboard Rear	Sensor Starboard Side	Sensor Starboard Front
Solenoid	Motor Common 2.5V	Motor	Speakers	Spare	Sensor Port Rear	Sensor Port Side	Sensor Port Front

Fig. 5. PSU DIL headers Signal Allocations

KEYBOARD TEACH PROGRAM  
1K ZX81

```

(1 REM TEACH/DOIT)
5 FAST
10 LET A=35000 _____ 35000 IS A PORT ADDRESS
20 POKE A,0 _____ SWITCH OFF VEHICLE
30 DIM M$(10,2)
40 LET K1=.6 _____ STRAIGHT RUN CONSTANT
50 LET K2=.61 _____ TURN CONSTANT
60 FOR S=1 TO 10
65 CLS
70 PRINT "TEACH", "STEP";S, "MOVE AND DIST/ANGLE/TIME"
80 INPUT C$
90 INPUT D
100 IF C$="F" THEN LET M$(S,1)=CHR$(5)
110 IF C$="B" THEN LET M$(S,1)=CHR$(10)
120 IF C$="L" THEN LET M$(S,1)=CHR$(6)
130 IF C$="R" THEN LET M$(S,1)=CHR$(9)
140 IF C$="S" THEN LET M$(S,1)=CHR$(0)
150 LET M$(S,2)=CHR$(D)
160 IF C$="F" OR C$="B" THEN LET M$(S,2)=CHR$(D*K1)
170 IF C$="R" OR C$="L" THEN LET M$(S,2)=CHR$(D*K2)
210 NEXT S
220 PRINT "TO DOIT PRESS D"
230 PAUSE 50000 _____ WAIT UNTIL ANY KEY PRESSED
240 FOR S=1 TO 10
250 POKE A,CODE M$(S,1)
260 PAUSE CODE M$(S,2)
270 NEXT S
280 POKE A,0
290 GOTO 230
    
```

RANDOM MOVE PROGRAM  
1K ZX81

```

1 REM RANDOM MOVE
10 LET A=35000 _____ 35000 IS PORT ADDRESS
20 POKE A,0 _____ SWITCH OFF VEHICLE
30 PRINT "PRESS S TO STOP"
40 IF INKEY$="S" THEN GOTO 200
50 PAUSE 5
60 POKE A,32+5 _____ SWITCH ON LIGHTS AND FORWARD
70 PAUSE 5
80 POKE A,5
90 LET B=PEEK A
100 IF B=255 THEN GOTO 40
110 POKE A,64+10 _____ LOW HORN AND BACKWARDS
120 PAUSE 30
130 IF B>250 THEN GOTO 170
140 POKE A,128+6 _____ HIGH HORN AND LEFT
150 PAUSE 50*RND _____ RANDOM TURN TIME
160 GOTO 40
170 POKE A,128+9 _____ HIGH HORN AND RIGHT
180 PAUSE 50*RND _____ RANDOM TURN TIME
190 GOTO 40
200 POKE A,0 _____ SWITCH OFF VEHICLE
    
```

CONTROL CODES

- 1 Port forward
- 2 Port back
- 4 Starboard forward
- 8 Starboard back
- 16 Solenoid on
- 32 Lights on
- 64 Horn 1
- 128 Horn 2
- 192 Horn 1 plus Horn 2

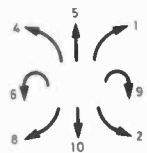


Table 1

SENSOR CODES

- D0 Starboard sensor Aft closed
- D1 Starboard sensor Side closed
- D2 Starboard sensor Front closed
- D3 Port sensor Front closed
- D4 Port sensor Side closed
- D5 Port sensor Aft closed
- D6 Spare
- D7 Spare

Table 2

When a port is read the resulting number will depend on which if any of the six sensor switches are closed. If none are closed i.e. if Zeaker is not touching anything then all 8 bits will be high and a read will return 255. If say the starboard front sensor is pressed then from Table 3, D3 will be low and hence a read will return 247. If both front sensors are pressed in then both D2 and D3 will be low and hence a read will return 243.

It is reasonably easy to determine which sensors are closed by subtracting the return value from 255 and transforming the result into binary. For the previous example of both front sensors closed this returns 243. Now  $255 - 243 = 12 = 8 + 4 = 2^3 + 2^2$  hence data lines 3 and 2 are at 0V which from Table 2 means that both front sensors are closed.

Although this may seem a complicated procedure to go through each time, remember a computer controls Zeaker and it will do all the tiresome calculations.

The initial software consists of two short programs, one which allows you to build a simple pattern and repeat it and the other lets Zeaker find its own way around obstacles, and two longer programs, which are available from Colne, one of which allows several patterns to be built up and joined together and the other allowing Zeaker to memorise its environment and to avoid obstacles sensibly.

For the initial ZX81 version of Zeaker the two short programs will each fit into 1K of memory and so can be run on an unexpanded ZX81. Writing a 1K program to control Zeaker from BASIC does not allow the full range of Zeaker's capabilities to be used. However, the two ZX81 1K programs here should give an idea of the ease with which Zeaker may be controlled from BASIC.

#### PROGRAM NOTES

Encoding the move code and time of move into the character array M\$ saves 80 bytes over using the numerical array. Against this must be set the 18 bytes for the CODE, CHR \$ and \$ used in the listing, resulting in 62 bytes saved. The program just fits in 1K and can be edited and run. Report code 4 (out of memory) comes up most of the time but should be ignored. The program can store up to 10 moves and prompts for the move.

F=Forward	and	Distance millimetres
B=Backward		Distance millimetres
R=Rotate Right		Angle degrees
L=Rotate Left		Angle degrees
S=Stop		Time in 50th second

To escape from the program press break.

The constants K1 and K2 should be fine tuned to the particular vehicle. The maximum value of any entry in M\$ is 255 and hence entering numbers greater than this in response to the prompt will cause the program to halt with an error code.

#### FURTHER DEVELOPMENTS

Although all 8 data read lines are connected to Zeaker only 6 of them are actually used, the remaining two terminate at pads by the Molex connector on the p.c.b. in the lid of Zeaker.

It is intended that these spare lines should be used to interface to add-on circuitry which will enable Zeaker to follow a white line, induction loop cable or simply seek or avoid light or heat.

Also instead of sending just the horn tones down the umbilical cord to the speaker it is possible to connect the output of a complex sound generator or a computer speech board to a pad by the umbilical cord connection on the p.s.u. board and Zeaker will be able to chuff along like a steam train or emit some more appropriate sound. It could also give a running commentary on its progress e.g. "Forward", "Right", "Left", "Ouch"! "Hit something at Left Front" etc.

Whilst Zeaker is relatively simple it is capable of quite complex interactions with its environment and in many respects it is only limited by the ingenuity of the controlling software. ★

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# JULY

issue!



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## Space Watch...

### THE IRAS SATELLITE SUCCESS

If the International Infrared Astronomical Satellite continues as it has begun it will have added much to offset some of the other disappointing news in other directions. First then the good news.

Another pass of the satellite was witnessed by the Parliamentary Under Secretary of State for the Department of Education and Science, Mr. William Shelton MP. Certain initiating commands made from Chilton, Oxon, the control station for the satellite, were performed by Mr. Shelton. This second event to which the press were invited was also a great success. Already a large amount of data had been collected. It is clear that there may be quite a long gap between the cessation of operations and publication of all the data.

It was expected that the useful life of the satellite would be in the order of 200 days, but as the boiling off of the coolant (superfluid Helium) is slower than was expected it may be possible to extend the time to 300 days. Altogether this has been a most satisfactory scientific satellite. The actual planned survey was scheduled to be complete in 200 days and the principal scan may well be so completed. This will enable the bonus time to be used for extra scans by the Dutch special additional experiment (DAX). This was a special 'close-up' facility which means that if something unusual is seen it will be possible to look at it in greater detail. Already such a situation has arisen in that during the scan of the Greater Magellanic Cloud it was noticed that there was intense emission round the Tarantula Nebula. Also just one minute of time spent on surveying the Galaxy away from the Earth's atmosphere has yielded more than all previous surveys.

The wide range of the telescope enables it to assess the cool clouds and the hot new clouds. It has thus been possible to say that the cool clouds are large and extensive and that as they get hotter clouds or cloudlets formed are consistent with the present theories of the evolution of new stars. That is that the large and diffuse clouds at wavelengths of 100 micrometres are beginning to condense under gravitational pressure. As the clouds become smaller and are under the influence of the increased internal pressure giving rise to nuclear reactions they shine as stars in their own right. The telescope therefore can give extremely adequate proof of the theories of stellar evolution. It is no exaggeration to say that this 'eye' is another of those vital milestones that

precede not only acceptance of recent thinking but provide the impetus for the thinking of the immediate future.

A footnote here might be appropriate. During a private conversation with Mr. Shelton and in answer to some of his questions about the publication of scientific progress the author took the opportunity to emphasise that the change of name from SRC to SERC (Science and Engineering Research Council) had already been reflected in a more useful spread of information which enabled the very efficient publicity section to spread its wings.

### PROJECT UNIVERSE

This venture which involves the Orbital Test Satellite (OTS) was again a task for Mr. William Shelton to play the role of initiator of this new joint effort. In the early development of microelectronics there seemed to be much misapplication as well as a great deal of incompatibility and no doubt this was the partial cause of high prices. The new techniques and especially proper attention to the importance of compatibility has brought some order out of chaos, with the fall of prices and the increasing sophistication of both hardware and software, giving impetus to the number of users in business and at home, which now opens the way for real improvement and standardisation. In this regard the most exciting development has been the setting up of Local Area Networks. These set up communication links between computers and their peripherals whose performance in terms of speed and reliability is comparable to that of the computers themselves. Local Area Networks (LANs) can provide electronic mail, the sharing within an office of costly printers etc., and scope for integrating computer aided design and manufacture.

A single LAN can link scores of computers, work stations and peripherals. Like *LEGO* it can go on and on. All this means that computer technology is pushed to its limits. This is as it should be. There is in operation a ring LAN known as the Cambridge Ring. This was developed by the Cambridge University Computer Laboratory and can offer a capacity of 4.2 Megabits. In the literature this is the equivalent of 50 pages of the Concise Oxford Dictionary every second. Even so the Ring with all its facilities can only cope over short distances. To extend such a facility nationally or internationally requires another facility. This really is what Project Universe is all about. The name of that facility is provided by the consortium involved: The Universities Expanded Ring Experiment. The consortium comprises the Department of Industry, The Rutherford and Appleton Laboratory of the Science and Engineering Research Council, British Telecom, Cambridge University, GEC, Logica, Loughborough University of Technology and University College, London.

The operational set-up is as follows—the LANs at Rutherford, Loughborough, Cambridge, Martlesham (Telecom Research Laboratory), Chelmsford (GEC/Marconi Research Centre), and London (University College and Logica) with (a terrestrial link between them) are all linked via the Orbital Test Satellite, which provides the high bandwidth capacity required for fast transmission of data. To take data from a network and transmit it to a satellite requires a Satellite Bridge.

### THE LINK DRIVING COMPUTER

This is a major element of the Satellite Bridge. In the Project Universe sites this is provided by the GEC 4065 mini-computer with 64K bytes of semiconductor memory, a four-channel synchronous communications controller and cartridge discs. The LDC applies the necessary procedures, holds enormous amounts of data in buffer stores to await transmission and keeps account of the amount of traffic the Ring wants to send. It of course provides complementary functions for incoming data.

For the outward path the next step involves the Computer Interface Module which is responsible for controlling access to the satellite. There is a master Earth station which establishes a time frame by broadcasting every 130 milliseconds a reference burst which lasts for 100 to 200 microseconds, available to lock all the stations. Full assurance of confidentiality is achieved. The data is transmitted via a 3 metre dish at a frequency of 14GHz transmitting and 11GHz receiving. The real time for the out and return time is approaching 0.25 seconds.

### THE ORBITING SATELLITE

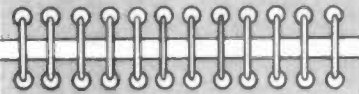
The European Space Agency satellite (Orbital Test Satellite), is a three axis stabilised geosynchronous satellite launched in 1978. It is in orbit 36,000km above equatorial Gabon. One of the purposes of the satellite was to prepare for the European Communications Satellite system with services such as British Telecom SatStream. It has a polar power transponder to re-broadcast up to 7,200 simultaneous telephone conversations. This project heralds the future in which the electronic office becomes truly international.

### SPACE POWER EFFORT

Three Energy Agencies, the Defence Department, the Energy Department and the Aeronautics and Space Research Projects Agency have agreed to proceed with the high power project which will be known as SP-100 (solar power 100kW) for future deployment in space. The organisation controlling the project will be the Defence Advanced Research Projects Agency. This decision marks the end of a ten year delay in coming to agreement among the parties. The escalation, promoted by defence authorities for military considerations and fear that America has of a space war, has overcome the profitability point of view.

Because the new agency, DARPA, is responsible for the space-borne laser technology, particle beam technology and space-borne radar techniques, it is in a position to assess the needs of such activities; and more closely when they will be needed DARPA will have disposition control. The scheme has far reaching consequences because some of the thinking is in terms of nuclear units of hundreds of kilowatts, and further to tens of megawatts into the 21st century. It is envisaged that this work could result in 100 kilowatt units using a combination of systems; reactors could be available in the second half of this decade.

## Frank W. Hyde



# INDUSTRY NOTEBOOK

By Nexus



## China Trade

Since writing a couple of months ago of prospects in China, more heartening news has emerged. At least two Racal Group companies are active in the market. Racal-Dana Instruments has concluded a deal with the Government of the People's Republic which involves assembly of the '99 series' frequency counters in Shanghai.

Kits will be shipped to Shanghai from the company's Windsor base, and although all details have not been revealed it is more than probable that the agreement includes provision of production aids including jigs, automated assembly and automatic test equipment. In fact a literal Chinese 'copy' of the UK production facility.

A couple of weeks after the instrument assembly deal Racal Recorders was able to announce that the Chinese Civil Aviation Authority had chosen the Racal International Communications Recorder as 'standard fit' at major airports. The ICR is a multi-channel (typically 20) long-play tape recorder which records all ground-air communications. Together with the aircraft-fitted 'black box' it provides major evidence in disaster enquiries. Thus, quality and reliability are all-important and it seems the Racal product was chosen after competitive trials with other makes.

At present such orders are marginal, a trickle rather than a flood of trade, and they need a lot of hard work and considerable investment in time and travel to obtain. Racal-Dana, for example, has been building bridges with 40 Import/Export Corporation branches in Shanghai, Beijing, Guanzhou and Harbin. Patience and dedication now could be richly rewarded by future business.

Cable & Wireless runs the hub of international telecommunications traffic in the Far East from its Hong Kong base. C & W's chairman and chief executive, Eric Sharp, asserts that the Far East is the region with fastest economic growth and that 'our involvement with the Chinese Telecommunications Authority is a major development of our established business there'. The extent of the involvement is not

revealed but is probably already considerable and increasing if only because C & W have a highly trained and Chinese speaking staff on the spot. Again, growth potential is clearly enormous, the number of telephones in the world 30 years ago was 70 million—today it is over 500 million; and China must be near the bottom of the world league in telephone sales penetration.

## Lesson

The recent water strike provided some much needed education. Few people outside the industry itself had the faintest idea of what is involved in gathering, purifying and distributing the precious liquid to our houses, offices and factories. Almost daily exposure on TV gave us a glimpse of the technology involved.

But the most potent lesson was in what didn't happen. City streets were not awash with sewage after a few days. Nor after a few weeks. Public health did not break down. Stand-by troops were never used.

Much of the credit for the maintenance of supply must go to automation, water supply may be the oldest of the distributive industries, preceding gas and electricity. Some of our town sewers are still 19th century but elsewhere the industry is far from old-fashioned, and new equipment and systems are going in all the while.

An example is a Marconi contract for radio monitoring and alarm for a network of 35 unattended sewage pumping stations in South Northamptonshire. The system is microprocessor-based and each pumping station is fitted with an 'intelligent' alarm to alert the control centre of any malfunction. A visual display and hard-copy printout of system status is at the control centre. Standard practice so far, except that the base control centre itself is open only in normal office hours.

To cover all contingencies Marconi is supplying two transportable control stations so that a duty controller can be in touch with system status from anywhere in the area and at any time.

We shall never know how long it would have been before public health became endangered. And we were lucky with the weather (fewer burst mains than expected) and with some essential maintenance carried out by management personnel. There was inconvenience to the public but no disaster. Which leaves us wondering whether the water industry might, perhaps, be a little overmanned.

## Recession?

What recession? Where? The electronics industry is clearly a special case but here, for the record, are a few success stories.

Marconi Avionics has signed a contract worth £30 million for the supply of 'head-up' displays for use in General Dynamics F-16 combat aircraft. This however, is for initial development and production, signifying follow-on orders.

Applied Computer Techniques (ACT) is investing £10 million in a new plant at Glenrothes, Fife, said to be one of the

world's biggest start-ups in microcomputers. Two hundred jobs this year, 400 by 1984.

Hewlett-Packard Ltd in the UK has enjoyed a 42 per cent increase in turnover. Exports were up 34 per cent and sales per employee have rocketed from £63,000 to £83,000 per year. Amazing!

IBM United Kingdom—Turnover up by 24 per cent to £1.24 billion. Pre-tax profits up 40 per cent to £225 million.

Standard Telephones and Cables—Turnover up 11 per cent, pre-tax profits up by 27 per cent. Exports at £143 million, 14 per cent up.

Plessey—Pre-tax profits up 29 per cent in the first nine months of the financial year.

Digital Equipment is spending £7 million setting up an office systems software development facility at Reading. Jobs for 250-300 in addition to the existing 120 in the present DEC software group.

Of course it's not all sweetness and light for every company but if these are hard times what's it going to be like in a boom?

## Jobs and Pay

The Institution of Electrical Engineers 1983 Salary Survey is full of interest. The sample totalled 7616 Fellows, Members and Associates in the UK and Republic of Ireland. The dominant field of occupation remains 'Electronic or telecommunications equipment development or manufacture'.

Compared with the 1982 Survey, unemployment is down from 1.2 per cent to 0.7 per cent, reflecting continued and indeed increasing demand for qualified engineers. But there is a small shift in employment from the public sector to the private sector of industry, up 2.1 per cent at 56.1 per cent. In 1976 only 45.8 per cent were in the private sector.

Salaries, however, are still higher in the public than in the private sector although the gap is narrowing. Taking all members in all grades and types of job, the salary range is from £6,000 for a young Associate up to £25,000 p.a. for a Member or Fellow in a senior position.

It's good to see salaries rising. But better still the low unemployment in the profession. Less than 1 per cent leads us to ask again, what recession?

## Shifting Pattern

The personal micro boom is shifting the pattern of trade. Many electronic hobbyists are spending on factory produced micros money they would otherwise be spending on components or kits. But perhaps only a temporary diversion of funds. The hard core of home constructors get as much if not more satisfaction from the making of a project and the understanding of how it works as from its end-use.

My own view is, that out of the thousands of purchasers of personal micros, quite a proportion will feel encouraged to take an interest in home construction where no interest had hitherto been shown. In fact a wider general enthusiasm for electronics could add to the ranks of the d.i.y. hobbyist.

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## HIGH QUALITY AUDIO PREAMPLIFIER (HA 12017)

HI-FI preamplifier designs of recent years have tended to use one of two basic circuits for the 'disc' input amplifier; either a conventional high performance opamp, or a discrete transistor based design. Opamps are simple, cheap, and easy to use, but in the highest quality systems they can sometimes create problems of noise or distortion. Furthermore, their maximum supply voltage is normally limited to around  $\pm 15$  volts, thus limiting their dynamic range and overload handling capability. Discrete transistor preamps, on the other hand, can be very complex to design and build. They are usually rather bulky, requiring large areas of Veroboard or p.c.b., and are often difficult to modify and experiment with. The performance, however, can be made very good indeed. The Hitachi HA 12017 is an i.c. which is specifically designed as a low noise, very low distortion audio preamplifier, and is able to offer the high performance of complex discrete designs with all the advantages and simplicity of integrated circuit technology. The i.c. has been developed from a similar device produced by Hitachi a few years ago, which has become somewhat of a standard in Japanese hi-fi equipment.

Although the i.c. can be used in a flat configuration (i.e. with no audible frequency dependent response characteristics), it is primarily designed and optimised for use as an R.I.A.A. equalised magnetic pick up preamplifier, for use with audio discs. (R.I.A.A. is the response characteristic standardised for use in record reproduction; it is the exact converse of the filtration which is applied to the cutting head when the master disc of the record in question is first made. By using such an arrangement of filtration, the modulation level recorded onto the disc can be made relatively high, improving the signal-to-noise ratio substantially.)

The pin configuration is shown in Fig. 1, and probably the most notable point to make about this is that the device comes in a single-in-line package; there is only one row of pins which stick straight out of the side so that

when mounted on its circuit board, the package stands vertically off the board. For experimental purposes, you could plug the two i.c.s (for stereo) into one ordinary 16 pin i.c. socket, but for a permanent installation this is not recommended, since at very low signal levels the quality of the connection could be a little suspect.

The specifications for the HA 12017 are

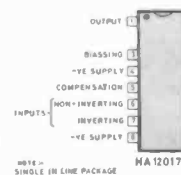
Characteristic	Notes	Min. value	Typically	Max. value	Unit
Supply Voltage	All specs below are measured at $\pm 24V$	$\pm 6$	$\pm 24$	$\pm 26.5$	V
Quiescent current	No input signal		4.0	6.0	mA
Temp. range		-30		+75	$^{\circ}C$
Dissipation				500	mW
Total harmonic distortion	20Hz-20kHz output 10V r.m.s.		0.002	0.01	%
Output voltage	Freq. 1kHz, THD-0.1%	13.5	14.7		Vrms
Open loop gain	Freq. 1kHz	95	105		dB
Max. input level	Freq. 1kHz, THD -0.1%		235		mVrms
Output noise A	Source resistance -43 $\Omega$ Weighting curve used		11.5	15.6	$\mu V$
Output noise B	Source resistance -3k3 Wide band (20Hz-20kHz)		53	90	$\mu V$
Supply rejection ratios	+ve supply } @ 100Hz -ve supply } ripple		56 45		dB dB

shown in Fig. 1, and they make interesting reading for all those interested in high quality performance! All the figures are based on the use of the i.c. in a complete R.I.A.A. equalised circuit, as shown in Fig. 2, so they are realistic indicators of the performance of the whole disc preamplifier stage.

### SUPPLY AND OUTPUT VOLTAGES

Although the supply voltage can be as low as  $\pm 6V$ , the recommended rails are  $\pm 24V$ . This is intended to allow a very high output level to be obtained from the device before clipping occurs; typically 14.7V r.m.s., or 41.6V pk/pk. The R.I.A.A. equalised circuit of Fig. 2 has a gain of 35.9dB at 1kHz (a voltage gain of 62 times), so the maximum input level is defined as 1/62 of the maximum

**Fig. 1 (right) HA12017 pin-out and (below) its specification. Note that this refers to the R.I.A.A. equalised circuit of Fig. 2**



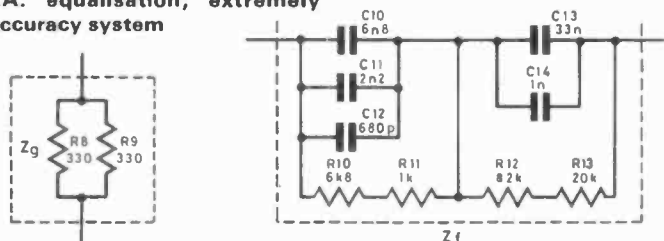
output voltage; this works out as an input of 235mV r.m.s. Most magnetic pick up cartridges only produce a typical signal level of a few millivolts, so this may seem to be an unnecessarily large input signal handling capability. However, some audio sounds and effects, especially those of a percussive or synthesised nature, can include much higher voltage short duration spikes or transients, which generate cartridge outputs much higher in level than the nominal few millivolts. By allowing up to 235mV (664mV pk/pk) before clipping occurs, the i.c. allows plenty of headroom before these transients are distorted in any way. (Typically in the order of 30 to 40dB, depending on the cartridge used.) As a result, the audible quality is excellent, and the sound is very clean. Many low supply rail designs are somewhat lacking in this

respect, so don't reduce the supply rails below  $\pm 24V$  unless it's absolutely necessary!

### DISTORTION

A large signal overload handling capability is of very little use to us if the device produces unacceptable amounts of distortion. In fact, the distortion specification is one of the HA 12017's most impressive features; typically 0.002% (1kHz at 10V r.m.s. out). The actual graph of third harmonic distortion versus output signal level is shown in Fig. 5, and it can be seen that clipping (i.e. the sudden onset of large amounts of distortion) occurs at around 15V r.m.s. (as we have already established), and distortion slowly starts to rise at below 1 to 2V r.m.s., which is not unreasonable. The distortion of this i.c. is so low that it could well be used in audio test equipment; as a front end amplifier in a distortion measuring set, or even

**Fig. 3. Feedback components for R.I.A.A. equalisation; extremely high accuracy system**



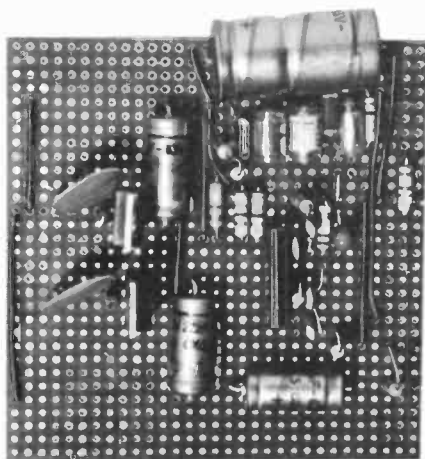
EG112C

as the central building block of a low distortion oscillator, for example. In this type of application, its own distortion is so low that it will have virtually no effect on the measurements of most audio system performance.

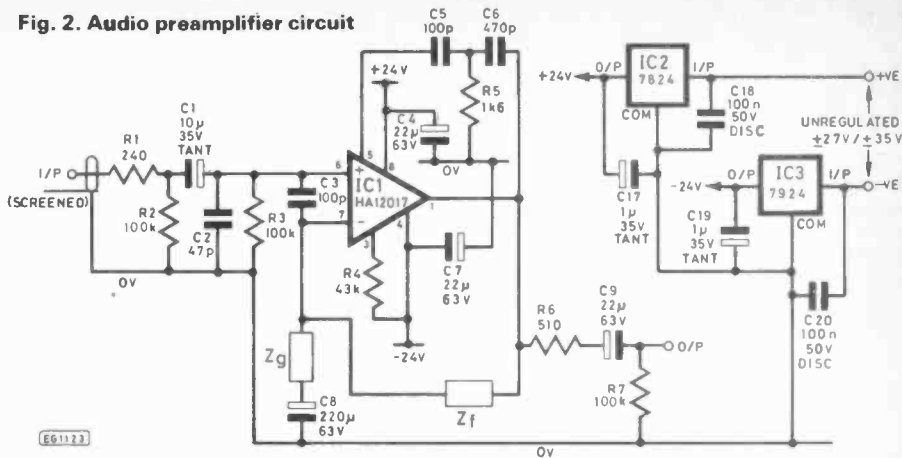
### NOISE

Noise is one of the most important and fundamental specifications in any audio system. Arguments may rage over the audibility of phase changes or certain types of distortion, but the undesirable and intrusive nature of noise in audio reproduction is not under dispute.

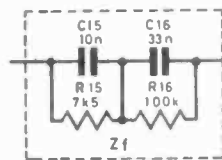
As the front end amplifier in the audio signal path, the disc preamplifier is required to add the most gain to the signal, and hence also adds the most noise, defining the overall noise level generated by the complete system. As with the other operational parameters of this device, the noise specifications are very good;



**Fig. 2. Audio preamplifier circuit**

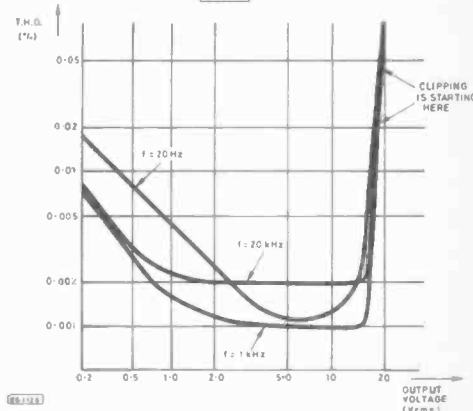


EG1123



**Fig. 4. Feedback components for R.I.A.A. equalisation; non-critical accuracy**

EG1125

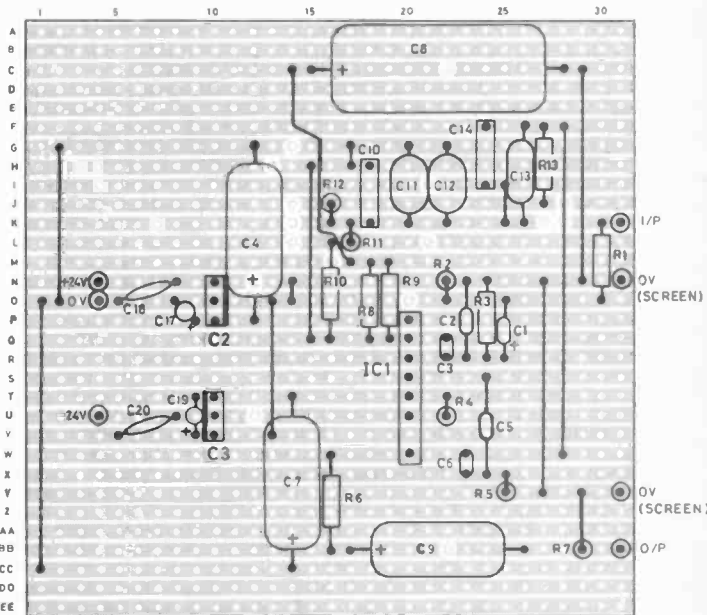


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**Fig. 5. Graph of distortion against output voltage for main circuit**

with a source resistance of 3k3, and a 20Hz to 20kHz bandwidth, the output noise voltage is typically 53 $\mu$ V, or -83dBu. This gives a dynamic range of 109dB (i.e. the difference between the maximum output signal level and the output noise), and a signal-to-noise ratio for a typical magnetic cartridge, producing 5mV r.m.s. signal, of 75dB (assuming a cartridge impedance of 3k3). In practice, the prototype circuit gave an output noise, including residual hum, of -84dBu (49 $\mu$ V) with a 3k3 resistor across its input, and -90dBu (25 $\mu$ V) with the input short circuited; both these figures were measured for the range 20Hz to 20kHz. The equivalent input noise, as derived from the specifications, is 0.85 $\mu$ V, or -119dBu.

**Fig. 6. Board assembly**



EG1127A



## CONSTRUCTION

Fig. 6 shows the Veroboard layout for a complete mono disc preamplifier. 24V power supply regulators have been added to allow any d.c. unregulated supply of +/- 27V to +/- 35V to be used. The regulated supplies can be used to feed a second preamplifier, of course, as in the case of a stereo system. The layout has been arranged to use the circuitry of Fig. 3, i.e. the high accuracy equalisation components, but the non-critical components of Fig. 4 could easily be fitted if preferred. For optimum performance, all resistors should be metal film types, and the capacitors should be as follows:

C2, C3, C5, C6 ceramic plate  
C1, C17, C19 tantalum bead, 35V rating or more

C10, C13 (or C15, C16) polycarbonate  
C11, C12, C14 polystyrene  
C4, C7, C8, C9 electrolytic, 63V rating (50V will also do)  
C18, C20 disc ceramic, 50V rating or more

All the normal rules and conventions of audio practice should be adhered to; plenty of supply decoupling, mains transformer far away from the preamplifier inputs, short signal leads, very thick earth wires, taken down to just one central common earth point, good quality connectors, etc. Some of the interconnections and layout of components in Fig. 6 may seem a little strange at first sight. Do beware of changing the layout arbitrarily, however, because some of the layout and linking is critical for achieving low hum and good stability from the system. Designing your own

p.c.b. for the circuit, in that respect, offers the chance of achieving even better performance than the Veroboard layout, but be prepared for some experimentation! The input impedance of the circuit is approximately 47k, to match the most popular magnetic pick-up cartridges (change C2 to suit the loading requirements of the cartridge in question). No volume or tone controlling is shown, of course, since our primary concern is the preamplifier i.e. We'll look at devices to do these other audio functions at a later date! However, we do now have a very high quality, very low distortion, low cost disc preamplifier design based on the HA 12017. The only problem now is the designing of the power amplifier to fully do the preamp justice!

The HA 12017 is readily available from **Ambit International**.

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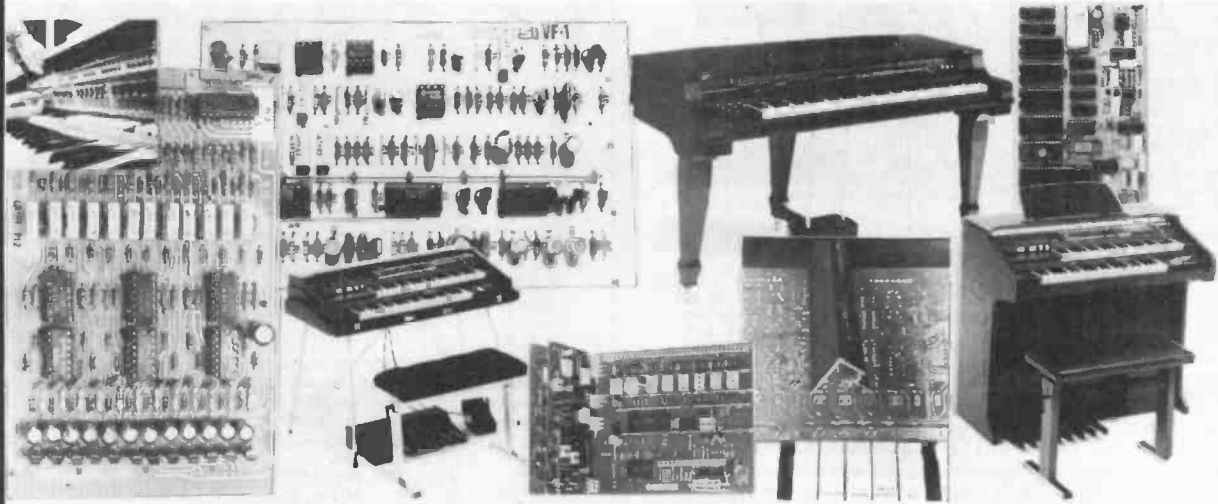
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CA3161E	100	NE566	140	8797	90	4584	80	LS33	14	LS190	35							79L15	60						
CA3189	200	NE567	100	81LS95	80	4584	40	LS37	14	LS191	35							79L15	60						
CA3240E	110	NE570	370	81LS96	80	4585	50	LS37	14	LS192	35							79L15	60						
ICL7106	680	NE571	370	81LS97	80	4027	20	LS38	14	LS193	36							79L15	60						
ICL7511	95	RC4136	55	81LS98	85	4028	37	LS40	12	LS194	32							79L15	60						
ICL7621	180	RC4568	45	6522	310	4029	43	LS42	28	LS195	40							79L15	60						
ICL7622	180	SL490	250	6532	675	4035	45	LS47	35	LS196	43							79L15	60						
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LM10	325	TBA950	220	8155	350	4051	42	LS74	16	LS203	50							79L15	60						
LM301A	74	TOA1008	310	8212	110	4052	48	LS75	16	LS204	55							79L15	60						
LM311	70	TOA1022	480	8216	100	4053	48	LS76	16	LS205	55							79L15	60						
LM318	120	TOA1024	115	8224	110	4066	22	LS77	17	LS206	55							79L15	60						
LM324	30	TL061	40	8225	250	4068	14	LS78	17	LS207	55							79L15	60						
LM334Z	90	TL062	60	8228	220	4069	13	LS83	33	LS208	29							79L15	60						
LM335Z	120	TL064	95	8243	270	4071	13	LS85	39	LS258	32							79L15	60						
LM339	45	TL071	25	8250	865	4072	13	LS86	15	LS259	53							79L15	60						
LM348	60	TL072	45	8251	250	4073	13	LS90	22	LS266	18							79L15	60						
LM358	55	TL074	95	8253	400	4075	13	LS93	26	LS267	18							79L15	60						
LM377	165	TL081	24	8255	225	4076	44	LS95	32	LS273	53							79L15	60						
LM380	65	TL082	45	8257	400	4078	13	LS99	36	LS279	53							79L15	60						
LM381	120	TL084	90	8259	395	4081	12	LS109	21	LS280	40							79L15	60						
LM382	110	TL170	49	8279	385	4082	12	LS112	20	LS283	38							79L15	60						
LM384	130	UA2240	115	8832	250	4093	23	LS113	20	LS289	40							79L15	60						
LM386	65	ULN2003	75	9602	220	4099	70	LS114	21	LS290	40							79L15	60						
LM387	120	ULN2004	75	Z80ACTC	260	4502	50	LS114	21	LS293	40							79L15	60						
LM393	95	XR2206	285	Z80ADART	775	4508	110	LS125	34	LS365	27							79L15	60						
LM711	60	ZN414	78	Z80ADMA	975	4510	45	LS126	25	LS366	27							79L15	60						
LM725	325	ZN423	130	Z80API0	270	4511	45	LS132	29	LS367	27							79L15	60						
LM733	60	ZN424	130	ZN425EB	320	4512	42	LS136	23	LS368	27							79L15	60						
LM747	60	ZN425E	340	ZN426EB	320	4514	110	LS138	27									79L15	60						
LM1458	40	ZN426E	290	ZN427EB	575	4515	110	LS139	27									79L15	60						
LM2917	185	ZN427E	575	ZN428EB	395	4516	50	LS01	11									79L15	60						

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a.c. V 10V, 30V, 100V, 300V, 1000V.  
a.c. I 3mA, 10mA, 30mA, 100mA, 1.0A, 10A.  
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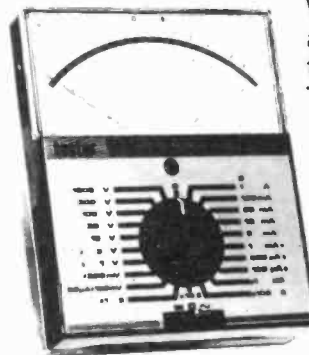
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a.c. V 10V, 30V, 100V, 300V, 1000V;  
a.c. I 3mA, 10mA, 30mA, 100mA, 1A, 3A.  
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# VERNON TRENT *at Large!*

THE other night I had to go to one of those ghastly industry dinners. But for once it didn't turn out too badly. My table-mate chanced to be something of a high-flyer in the Patent Office and his witty conversation helped the steamed cod and mash down a treat. Over the brandy, which was extra (I could only afford one—he had three), he told me that his office cellars are full and running over with clever inventions which for some strange reasons never made it to the retail counters.

There was this harness for long-distance rail travellers. The idea was for the user to clamber into it and fix the free end to the luggage rack. Then whenever the train lurched he could go on snoozing without being shot into the lap of his unfortunate neighbour. I wonder why this excellent aid to passenger-comfort never rocked the marketplace? Maybe it was blacked by ASLEF.

Another innovation was a pair of plastic sleeves for melon-eaters. It was to stop the succulent juice oozing down to their armpits. It's believed that this one failed because the inventor didn't bother to find out that your genuine melon-lover looks upon the juice-flow as part of the ecstasy.

Happily such piffling restraints have not, in the main, held up the acceptance of that particle which all of us in the business prefer, the electron. Yet though it has wormed its way into most walks of life, there are still one or two areas where it has tended to be given the big elbow.

An outstanding example is the Church. Now, let's face it. Apart from fringe elements who scorn the dog-collar in favour of the T-shirt with the rude inscription ("Good grief man. I'm one of the lads, just like you") and who back the twang of the guitar against the swell of the organ, there is no body more resistant to change.

That could be good for the soul. After all, there's much to be said for stability in a world where standards and values change with the speed of a mannequin.

For all that, it's time the Church stopped standing still and for those at the pinnacle to have another think. So let's have a quick word with the Archbishop of Canterbury, Cardinal Hume, the chaps on the Nonconformist front and, naturally, the chief Rabbi. We have a duty to make them aware of the ways in which modern technology can do nothing but good for their missions.

Every day you can read about the sad financial plight of churches all over the country. There's hardly a parish which hasn't its crumbling tower (almost always Norman), on-the-blink heating, a cracked font or a bronchitic organ.

What about a set of microprocessor-

controlled doors which will not open until after the collection has been taken up? We all know the mean skivers who slip through the offertory net by pretending they've a bus to catch or feign an urgent need for the loo. This would stop them creeping out the minute the churchwarden picked up the plate.

A more sophisticated system would be one that linked the door-control to a collection-calculator, with a read-out in the vestry. Then all present would remain virtual prisoners until a previously-determined cash target had been reached.

One of the deadliest things that can happen to a clergyman—apart from dropping the first-born of the patron of the living in the font—is to watch horrified as members of his congregation nod off during what he thought was a pretty rivetting sermon. It's the sort of thing that's likely to happen at Sunday evening. Dieticians reckon it's the lunchtime meat and two veg followed by spotted dick and custard that does it.

A low-voltage electric shock, controlled from the pulpit and applied via the pew seat, would jolly soon remind these laggards that if they want to get to the pearly gates they'd better pay more attention to the directions. This shock therapy could also be made to work the other way. A high-intensity infrared beam—governed by a simple timer—would gently heat up the seat of the preacher's trousers if he droned on for longer than was decently acceptable.

Of course, you'd have to reckon with the wily old prelate—probably a reader of PE—who knew the drill and had equipped himself with a pair of pants insensitive to infra-red. One way to put him in his place would be to install an ejector apparatus under the pulpit floor instead. However, for reasons of sheer Christian charity it shouldn't be used on any incumbent over the age of 80.

You may think, if you have a business background, that a squad of robot choirboys is something of an extravagant capital investment yielding a small return. This is not so. Those clergymen who have been bold enough to take such a step are over the moon—which for them is a step in the right direction anyway.

One of them, a diocesan bishop no less, told me: "Ah, the blessed relief of witnessing the end of the placing of rude-sounding cushions on minor canons' stalls and the demise of bubble gum popping during the Venite." But, he admitted to me privately with a sigh, he did sometimes miss the pleasure of cuffing the little perishers round the lughole.

Baptisms have a special hazard for men of the cloth. They never know what to expect. All too often they are called upon to handle

infants who are either equipped with Tannoy-type voiceboxes or who have forgotten to go before they came out. Frequently both.

Apart from stuffing his stole down the baby's throat, there's not much a parson can do about the former. But if he's technically-minded enough to insert moisture-detectors in his cassock sleeves, he has a sporting chance of whipping junior back into mum's arms before any damage arises out of the latter. Electronics saves pounds on cleaning bills.

Most clerics are like actors. They must have the smell of the crowd and simply cannot do their stuff well in the hollowness of half-empty churches. They become about as helpful to the propagation of the Word as a pork butcher is to a vegetarian. Their confidence can be speedily restored by the use of holographic laser techniques to project images of large congregations.

There are three standard features of church weddings: The nudge-nudge innuendo of the groom's mates; snivelling matrons; and an appeal by the old knot-tier about scattering confetti in the churchyard. ("Not only does it spoil the beauty of the church's environment, but we have to pay our worthy sexton overtime to clear it up. And that grasping swine doesn't come cheap.")

The solution is as simple to me as the theory of relativity was to our Albert. You get yourself an electrostatically-charged cat and chase it round until not a scrap of confetti remains.

Satellite TV is something else that could also come in handy on the Church's march. Who knows? The way things move nowadays, it may eventually become possible to establish two-way communication (using triphonic techniques, of course, during Trinity) with Paradise. Such a facility would have to be used with dignity and care, being restricted in the first instance to ordained ministers only. We couldn't have laymen trying to get in by the back door.

I'm not daft enough to expect an early and positive response to my case, well-founded as it is. Down the centuries the Church has always moved in a pedestrian way its wonders to perform. There are, for example, still places with hand-pumped organs, reserved pews for the squire and his brood and venerable vergers who double-up as gravediggers and pull at their forelocks whenever the vicar comes within 50 yards. It takes a powerful electronic device to get through barriers like that.

But a seed has been sown. Let us trust that it has not fallen upon stony ground but will become fruitful and multiply.

*V.T.'s views and opinions are entirely his own and not necessarily those of PE or anyone else.*



# PERCUSSION MICROSYNTH

Effectively two complete synthesisers in one package, together with a variable angle LFO to modulate the VCOs or filters, and a voltage controlled phaser to phase either or both synthesiser outputs

## A.R. BRADFORD M.Sc.

THE Percussion Microsynth is provided with internal trigger pads of variable sensitivity so that it may be played with hands or drum sticks. Thus it may be used either to augment an existing drum kit (whether mechanical or electronic) or as a self contained free standing unit in the manner of a pair of electronic "bongos". While the unit is quite capable of imitating conventional drums, cymbals, etc, this is hardly the purpose for which it was conceived — it would for example be simpler and cheaper to use a real pair of bongos if this was all that was required. The strength of an instrument like this is that it is capable of creating a vast range of different sounds from bells to explosions, triangles to "Big Ben", gongs and metallic "dustbin lid" sounds, to rockets, marching feet, steam trains, wind and surf effects, as well as a vast array of abstract sounds. In this respect it should not be confused with the range of low cost "percussion synthesisers" currently on the market, which tend to be of extremely limited capability.

The Percussion Microsynth may also be triggered from an external microphone so as to respond to a particular part of a drum kit, as well as to voices, etc. It may also be triggered electronically from one output of a drum machine such as the *PE Master Rhythm*, as well as from the gate outputs of a sequencer. In relation to this, the 1V per octave control inputs to the VCOs enable the Percussion Microsynth to be used as a dual "slave" synthesiser in conjunction with a sequencer or a polyphonic keyboard controller.

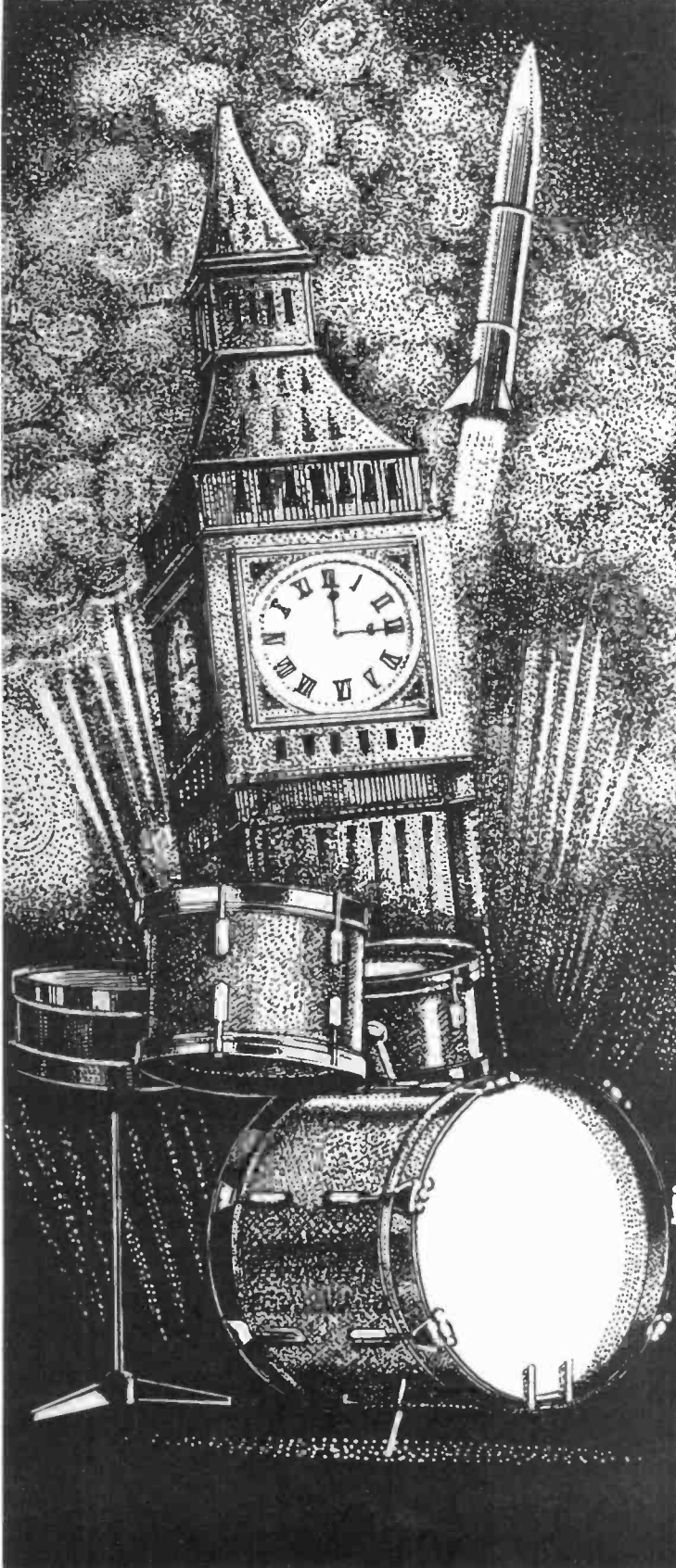
In addition a dynamic sensitivity function is provided. That is, the harder you hit the drum pads, the greater the effect produced, be it loudness or sweep of pitch, etc.

In spite of the tremendous range of sounds available — greater than most commercial units — simple low cost circuitry has been employed throughout. The entire unit is built on one 16in x 5½in printed circuit board.

### PRINCIPLES OF OPERATION

The general scheme of the unit is shown in Fig. 1. The signal from the transducer is used both to trigger the envelope shaper and to provide the control voltage which is the basis of the touch sensitivity. The latter part of the circuitry comprises an envelope follower and a sample and hold which samples the rectified voltage from the transducer instantaneously, each time a new signal is received from the transducer. The output voltage from the envelope shaper is then multiplied by the output voltage from the sample and hold, so as to achieve envelopes of amplitude proportional to the size of the signal received from the transducer. With the "Touch" switch off, the envelope is multiplied by a constant factor of 1. Although no provision has been made for it as such, the astute synthesist will spot here a facility for external voltage control of the envelope size, and a possible modification for implementing this will be mentioned later.

The envelope is hard-wired to the VCA to effect volume contours, and may also be switched in to the VCO or VCF to produce sweeps in pitch or harmonic content. The envelope shaper itself is of the Attack/Release type, the provision of



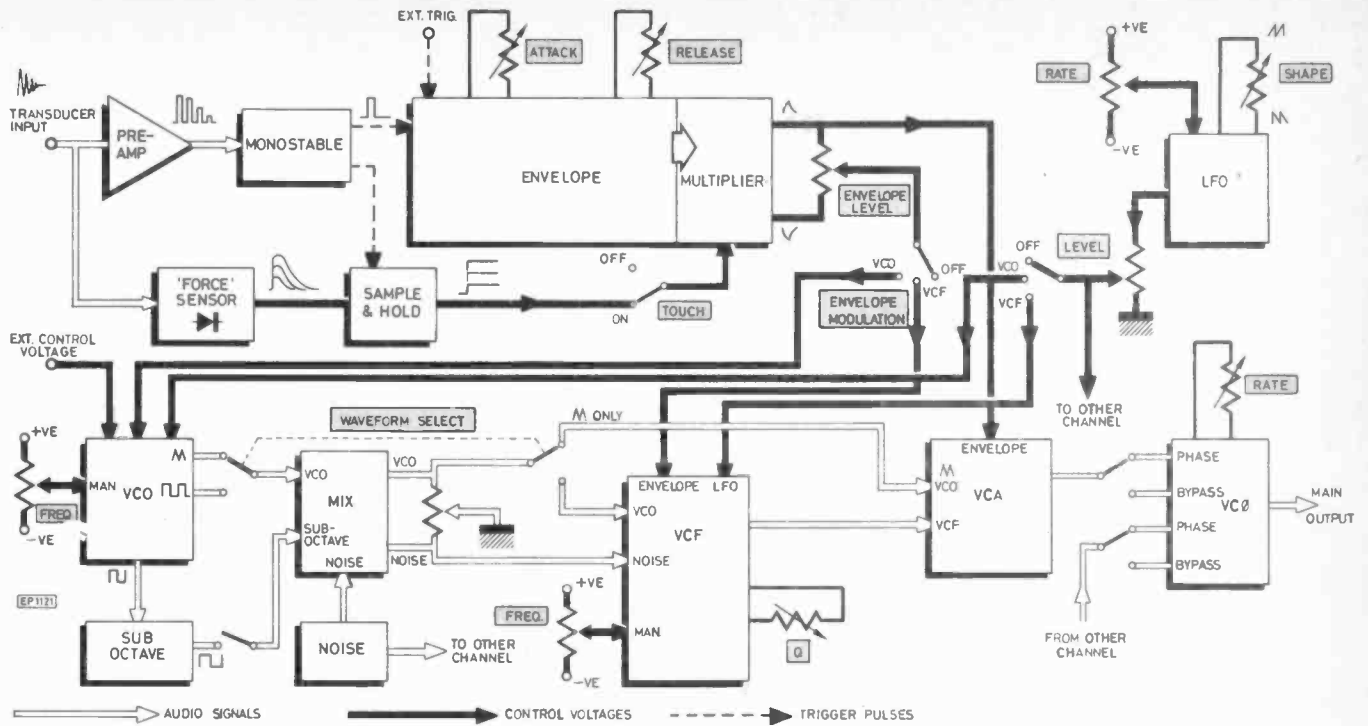


Fig. 1. Block diagram of one channel of the drum synth, plus phaser and LFO

an attack control greatly extending the range of sounds available (that is, they need not be percussive at all! They could for example be reversed starting slowly and finishing abruptly, or be of a gentle, singing quality).

The VCO produces either smooth sounding triangular, or harsh square waveforms, with provision for external voltage control of the pitch. A simple circuit provides a sub-octave. The triangle waveform goes straight to the VCA, while the square wave and/or sub-octave go to the VCF. In this way the instrument can produce warm sounds in which the VCF filters out the higher harmonics in the sub-octave waveform without affecting the triangular waveform an octave higher. The mix control cross-fades continuously from white noise (which is fed into the VCF) to oscillator output, including the sub-octave when it is switched in.

The VCF is a low-pass type with variable resonance, which has been modified so that it will also oscillate when the resonance control is turned fully clockwise. Thus the VCF can be used as an auxiliary sound source in conjunction with the triangle from the VCO, in order to produce bell-like sounds.

Each channel of the instrument may be switched through the phaser (VCØ), in which the phasing rate is manually controlled.

The LFO (low frequency oscillator) can be used to modulate either the VCO or VCFs, from 0.2Hz to 30Hz to any degree set by the "Depth" control. The LFO is of a novel design in which the "Shape" control varies the shape of the LFO waveform continuously from rising ramp, through triangular, to falling ramp, and many interesting effects can be obtained in the manipulation of this one control.

### CIRCUIT DESCRIPTION

The complete circuit of one channel of the synthesiser is shown in Fig. 2. IC1 pins 5, 6, and 7 (IC101 pins 1, 2 and 3) is a microphone preamplifier with a sensitivity of about -50dB, catering for the low impedance microphones found in stage or studio environments, although high impedance microphones will work just as well. C1 to C3 (C101 to

C103) form a band-pass network so that the unit responds neither to low frequency noises transmitted through the floor (vital on stage), nor to radio signals. The resultant signal is mixed with the output from the internal transducer which is of a high impedance crystal type. From here the signal takes two separate paths. IC1 pins 12, 13 and 14 (IC101 pins 8, 9 and 10) is a hard limiting amplifier and triggers the CMOS monostable (half of IC3, IC103), producing a 10 msec pulse, which in turn triggers the envelope shaper. VR1 (VR101) is the sensitivity control, while C4 (C104) removes radio pickup and local decoupling of the trigger circuitry also helps to eliminate spurious triggering.

The pulse from the monostable sets the set-reset flip-flop (the other half of IC3, IC103) which turns on the CMOS switch connecting the "Attack" pot to C11 (C111). This capacitor therefore charges down from +8.5V towards -8.5V. The voltage on C11 (C111) is inverted by IC7 (IC107) to give a positive going envelope, and this is fed back via divider R20, R21 (R120, R121) to the reset input of the flip-flop. Thus the flip-flop is reset when the output of IC7 (IC107) reaches about +6V. The "Attack" pot is then disconnected from C11 (C111) and connected instead by the other CMOS switch to the "Release" pot. Thus C11 (C111) discharges back up to +8.5V at a rate set by VR4 (VR104). The positive going envelope from IC7 (IC107) pins 1, 2 and 3 is reinverted by the other half of IC7 (IC107), pins 5, 6 and 7, and the "Level" control VR5 (VR105) cross fades between positive and negative going envelopes, with the back-to-back diodes creating a dead band around the centre (zero) position. The output is used via S4 (S104) to modulate the VCO or VCF.

The voltage from the microphone input or transducer is also amplified to a lesser extent by IC1 pins 1, 2 and 3 (IC101 pins 5, 6 and 7). D1, R12 and C8 (D101, R112 and C108) produce a d.c. envelope of the shape indicated and of amplitude proportional to the size of the signal coming from the microphone or transducer. This envelope, added to a d.c. offset from VR2 (VR102), is amplified and inverted by IC4 (IC104).

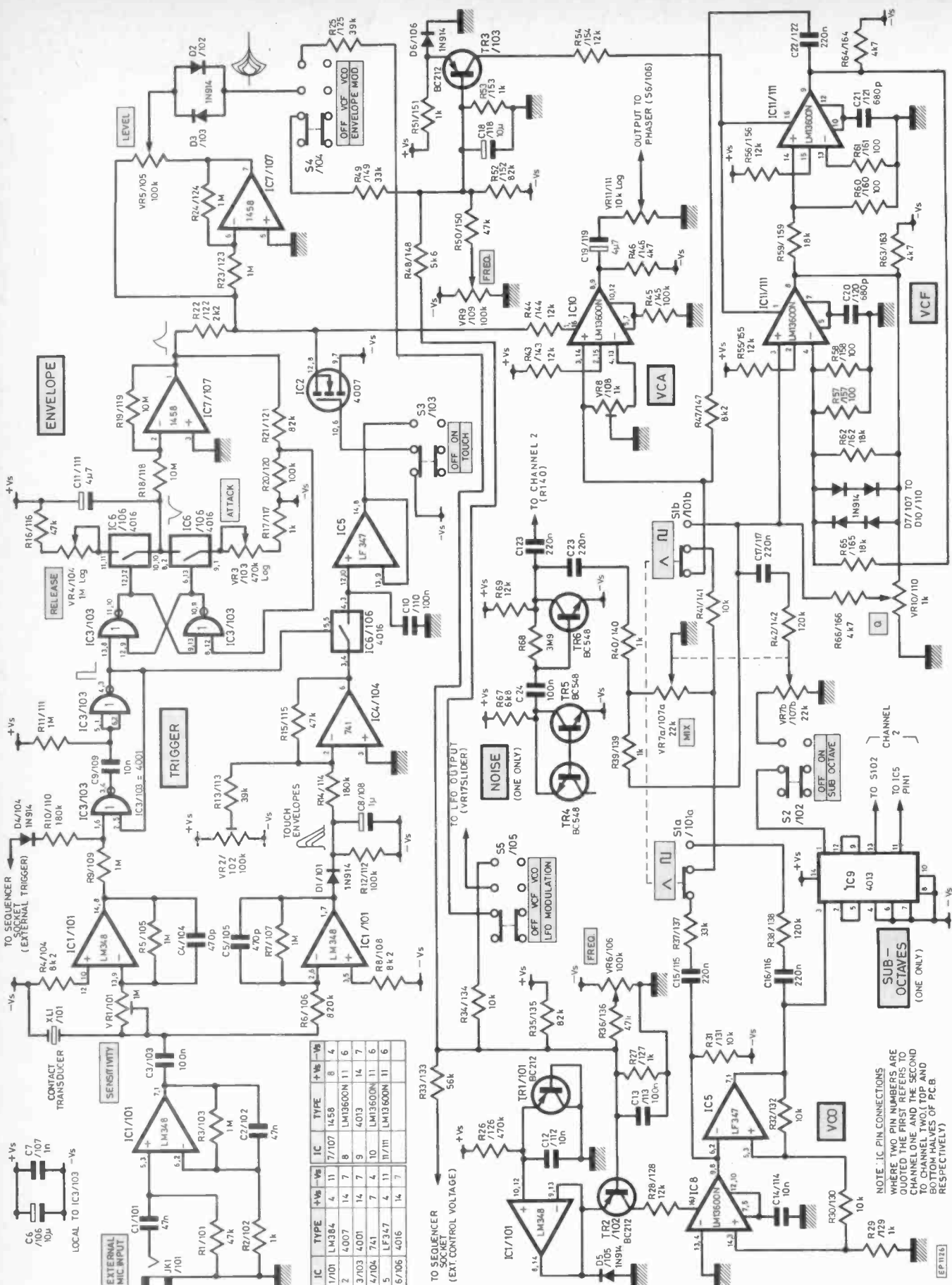


Fig. 2. Circuit of one channel of the synthesiser

CMOS switch IC6 pins 3, 4 and 5 (IC106 pins 3, 4 and 5) together with C10 (C110) and IC5 pins 12, 13 and 14 (IC105 pins 8, 9 and 10) form a sample and hold circuit, sampling the "touch" envelope each time the CMOS switch IC6 pins 3, 4, and 5 receives a pulse from the monostable. The output of IC7 (IC107) pin 1 passes through a divider formed by R22 (R122) and a CMOS FET IC2 pins 9, 10 and 12 (pins 6, 7 and 8). With the "Touch" switch S3 (S103) in the off position the gate of this FET is connected to the negative rail so that the FET is biased off and the envelope shaper output is unattenuated. With S3 (S103) on, the resistance of the FET, and therefore the size of the envelope, is determined by the touch circuitry.

It has been mentioned that there is potential for externally controlling the size of the envelopes. This could be achieved by feeding a control voltage into pin 2 of IC4 (IC104) — say 0 to 10V positive via a 180k resistor. Alternatively the connection between S3 (S103) and the negative rail could be broken, and a control voltage fed in directly to the gate of the FET. In doing this the gate of the FET should be connected to the negative rail via a 1M resistor.

## SOUND SOURCES

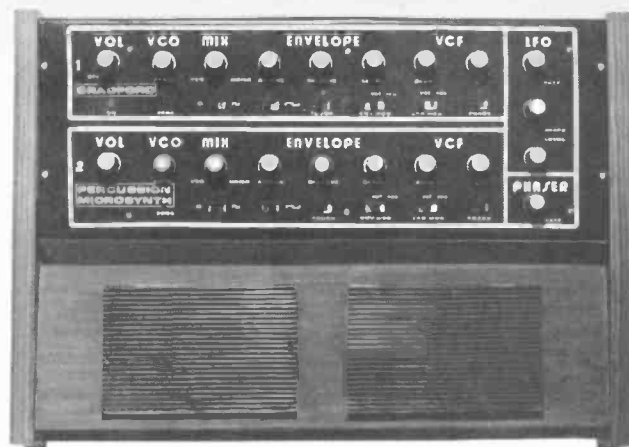
The VCO is a simple triangle/square oscillator. IC8 is a dual operational transconductance amplifier (OTA) configured as an integrator which ramps positive at a rate proportional to the current flowing into its control input, until the threshold of the Schmitt trigger IC5 pins 5, 6 and 7 (pins 1, 2 and 3) is exceeded. IC5 then changes state and the OTA output ramps downwards, and so on. The control current for the OTA is sourced by TR2 (TR102), temperature compensated by TR1 (TR101). The exponential law provided by the use of a transistor is not entirely necessary, but is preferred in this application as it renders the pitch of the VCO more controllable at low frequencies. Also it allows the control voltage inputs to be referenced to 0V instead of 1V above the negative rail, as is the case of OTA control input pins. In addition this arrangement allows the Percussion Microsynth to play musical scales when slaved to a standard 1V per octave sequencer or polyphonic keyboard controller. The external control voltage is applied via R33 (R133). (In connection with this usage, the sequencer or controller could also be made to determine the note length were it to provide the reset pulse, to the envelope flip-flop, instead of the resistive divider.) Such applications are however left entirely to constructors' ingenuity.

TR4, TR5 and TR6 form a white noise generator feeding both channels of the instrument, and VR7 (VR107) cross fades between noise and oscillator outputs.

IC9 contains two divide-by-two gates, each driven by the Schmitt output of its respective VCO in order to provide a square wave one octave below the VCO pitch. Each sub-octave may be switched into its respective filter, regardless of whether a triangular or square wave output is selected from the VCO.

## FILTERS

Each VCF is a standard state-variable design built round a dual OTA chip IC11 (IC111). This provides a low pass output into the VCA, with the degree of resonance controlled by VR10 (VR110). Although basically the same as used in the Microsynth, here the VCF has been modified so that with VR10 (VR110) at maximum, the circuit will oscillate in the range of a few hundred hertz to 10kHz, depending on the setting of VR9 (VR109) as well as any other modulating voltages selected from the envelope and/or the LFO. This is achieved by increasing the feedback, that is decreasing the value of R66 (R166); at the same time the diode network



Showing control panel and trigger pads

around R62 (R162) limits the output excursions of IC11 (IC111) pin 8. The overall gain of the filter is fixed so that the output waveform is a reasonable facsimile of a sine wave.

The control current for the VCF is sourced by TR3 (TR103), temperature stabilised by D6 (D106). This arrangement is not accurate enough to drive a VCO for musical purposes, but is quite adequate for the filter in this application.

## VCA

IC10 pins 1 to 8 (pins 9 to 16) is another OTA without the time constants in the form of R-C networks that would otherwise make it a filter. Thus it behaves as a current controlled amplifier, with the gain determined by the current supplied by the envelope shaper.

## PHASER AND OUTPUT

The output from each VCA may be switched via S6 (S106) so that part of the output signal passes through the four stages of phase shift (IC12). The overall degree of phase shift is controlled by four CMOS FETs (IC15, IC2). Dual op-amp IC13 forms an oscillator providing a slow triangle waveform to sweep the phase shift at a rate set by VR15, while VR13 biases the FETs to the centre of their useful ranges. In order to actually create the phasing effect, the phase shifted signals are mixed back together with the original signals in TR7 (Fig. 3).

Three outputs are provided from the Percussion Microsynth: a line level output for feeding to a mixing desk or external amplifier, and two low impedance outputs, one for a speaker and the other for headphones. The line level is trimmed by VR12, and the amplified outputs by VR14, each of which is accessible by a screwdriver through holes in the front panel. IC14 is a monolithic power amplifier which can deliver 2 watts into 8 ohms. R101 and R102 attenuate this output to suit standard headphones.

## LOW FREQUENCY OSCILLATOR

The standard integrator/Schmitt oscillator of Fig. 4 is fed alternately with positive and negative going control voltages, selected by the CMOS switches which are driven in antiphase by the Schmitt output. The "Shape" control VR18 varies the relative rates at which the integrator ramps up and down but the overall time period remains constant, being determined only by the input control voltage from the "Rate" control VR16.

The LFO oscillates over the range 0.2Hz to 30Hz, and is used to modulate the VCOs or VCFs as selected by S5 (S105), to a degree set by the "Level" control VR17.



# COMPONENTS

## Resistors

R1,101	47k	R70	2k2
R2,102	1k	R71	2k2
R3,103	1M	R72	68k
R4,104	8k2	R73	68k
R5,105	1M	R74	1k
R6,106	820k	R75 to R87	100k (13 off)
R7,107	1M	R88	2M2
R8,108	8k2	R89	1k
R9,109	1M	R90	4k7
R10,110	180k	R91	10k
R11,111	1M	R92	2M2
R12,112	100k	R93	1M
R13,113	39k	R94	15k
R14,114	180k	R95	47k
R15,115	47k	R96	100k
R16,116	47k	R97	1M
R17,117	1k	R98	½ watt 10R
R18,118	10M	R99	2R7
R19,119	10M	R100	100R
R20,120	100k	R167	220R
R21,121	82k	R168	220R
R22,122	2k2	R169	10k
R23,123	1M	R170 to R174	1M (5 off)
R24,124	1M	R175	10k
R25,125	39k	R176	1k
R26,126	470k	R177	820R
R27,127	1k	R178	270R
R28,128	12k	R179	820R
R29,129	1k	R180	270R
R30,130	10k	R181	820R
R31,131	10k	R182	4k7

## Semiconductors

IC1,101	LM348
IC2	4007
IC3,103	4001
IC4,104	741
IC5	LF347
IC6,106	4016
IC7,107	1458
IC8	LM13600N
IC9	4013
IC10	LM13600N
IC11,111	LM13600N
IC12	LM348
IC13	1458
IC14	LM380N
IC15	4007
IC16	LM348
IC17	4016
IC18, IC19	LM317U
D1,101 to D10,110	1N914 (20 off)
D11 to D18	1N4001 (8 off)
TR1,101 to TR3,103	BC212L (3 off)
TR4 to TR7	BC548C (4 off)
D19	red l.e.d.

## Potentiometers

VR1,101	preset 1M
VR2,102	preset 100k
VR3,103	pot log 470k
VR4,104	pot log 1M
VR5,105	pot lin 100k
VR6,106	pot lin 100k
VR7,107	dual pot lin 22k /
VR8,108	preset 1k
VR9,109	pot lin 100k
VR10,110	pot lin 1k

VR11	SW pot log 10k	VR16	pot log 100k
VR111	pot log 10k	VR17	pot log 10k
VR12	preset 22k	VR18	pot lin 100k
VR13	preset 100k	VR19	preset 1k
VR14	preset 22k	VR20	preset 1k
VR15	pot log 1M		

## Capacitors

C1,101	polyester 47n
C2,102	polyester 47n
C3,103	polyester 100n
C4,104	polystyrene 470p
C5,105	polystyrene 470p
C6,106	p.c. elec 25V 10µ
C7,107	polystyrene 1n
C8,108	p.c. elec 25V 1µ
C9,109	polyester 10n
C10,110	polyester 100n
C11,111	p.c. elec 16V 4µ7
C12,112	polyester 10n
C13,113	polyester 100n
C14,114	polyester 10n
C15,115	polycarbonate 220n
C16,116	polycarbonate 220n
C17,117	polycarbonate 220n
C18,118	p.c. elec 10V 10µ
C19,119	p.c. elec 16V 4µ7
C20,120	polystyrene 680p
C21,121	polystyrene 680p
C22,122	polycarbonate 220n
C23,123	polycarbonate 220n
C24	polyester 100n
C25	polyester 10n
C26	polyester 100n
C27	polystyrene 1n
C28 to C30	polyester 10n (3 off)
C31 to C35	p.c. elec 10V 4µ7 (5 off)
C36	polystyrene 100p
C37	tantalum 4µ7
C38	p.c. elec 25V 4µ7
C39	polyester 100n
C40	p.c. elec 25V 470µ
C41	polycarbonate 470n
C42, C43	polyester 100n
C44, C45	p.c. elec 25V 2,200µ
C46, C47	p.c. elec 16V 10µ
C48, C49	p.c. elec 16V 1,000µ
C50, C51	polyester 47n

## Switches

S1,101 to S3,103, and S6,106 are 2-pole, 2-position p.c.b. mounting slide switches (8 off). S4,104 and S5,105 are 2-pole, 3-position p.c.b. mounting slide switches (4 off).

## Miscellaneous

T1—Transformer 0-12V, 0-12V 500mA, solder tag, panel fuseholder 20mm, FS1—20mm fuse 500mA, mono jack sockets (4 off), stereo jack socket (1 off), Dinlatch 5-pin A socket (1 off), miniature mains cable and grommet (¾ in. dia) to suit, 0.5m 4-way ribbon cable, 1m miniature screened cable, p.c.b., front panel, Microsynth cabinet, Percussion Microsynth dual trigger pad assembly, push-on knobs plus colour coded caps to taste, R.S. type (20 off), 6BA ½ in spacers (6 off), 6BA ¾ in bolts (10 off), 6BA nuts (20 off), domed-head ½ in self-tap screws (6 off), stick-on feet (4 off), crystal microphone inserts (2 off), M5 bolts ½ in. (4 off).

Parts and complete kits available from:—**Clef Products Ltd., 44A, Bramhall Lane South, Bramhall, Stockport, Cheshire SK7 1AH.**

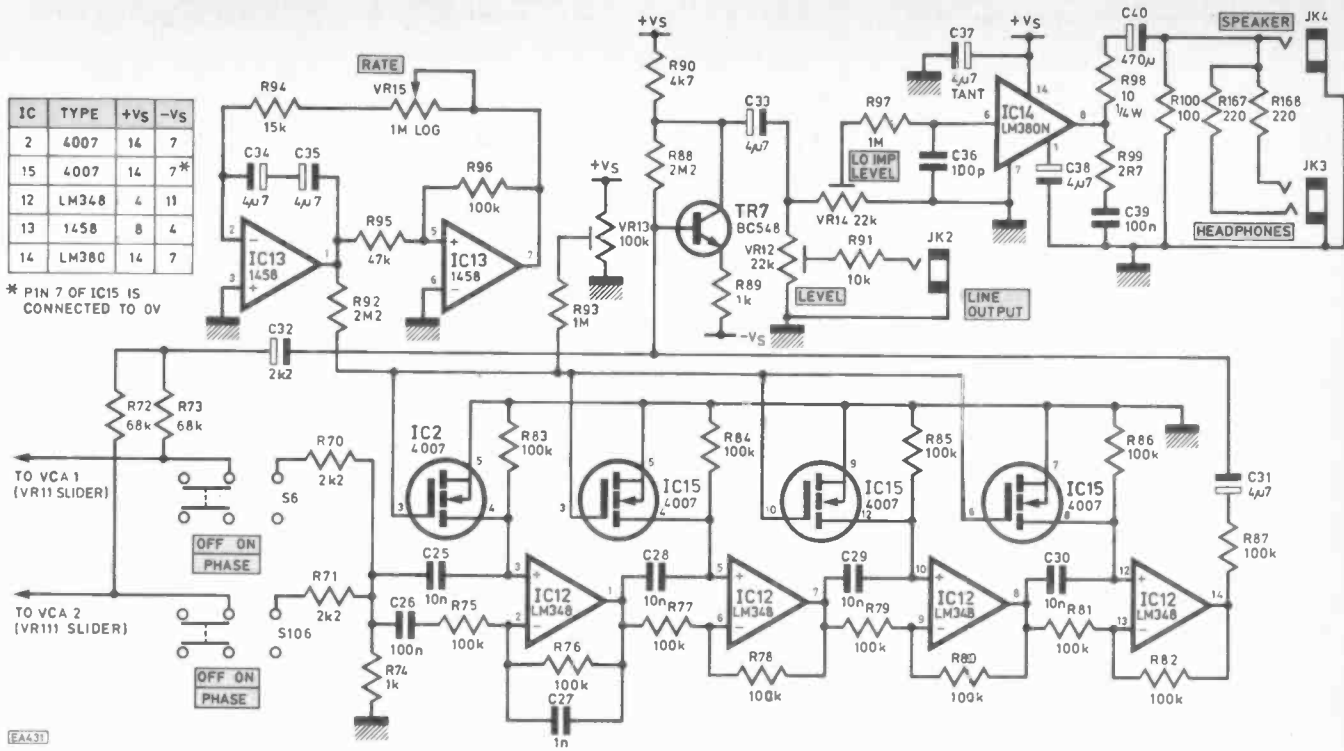


Fig. 3. Phaser and output

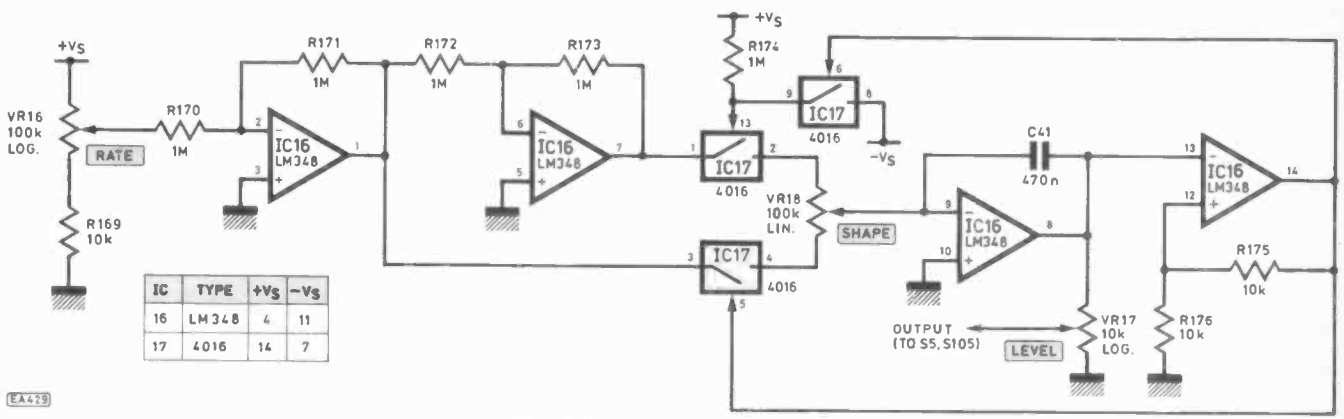


Fig. 4. Low frequency oscillator

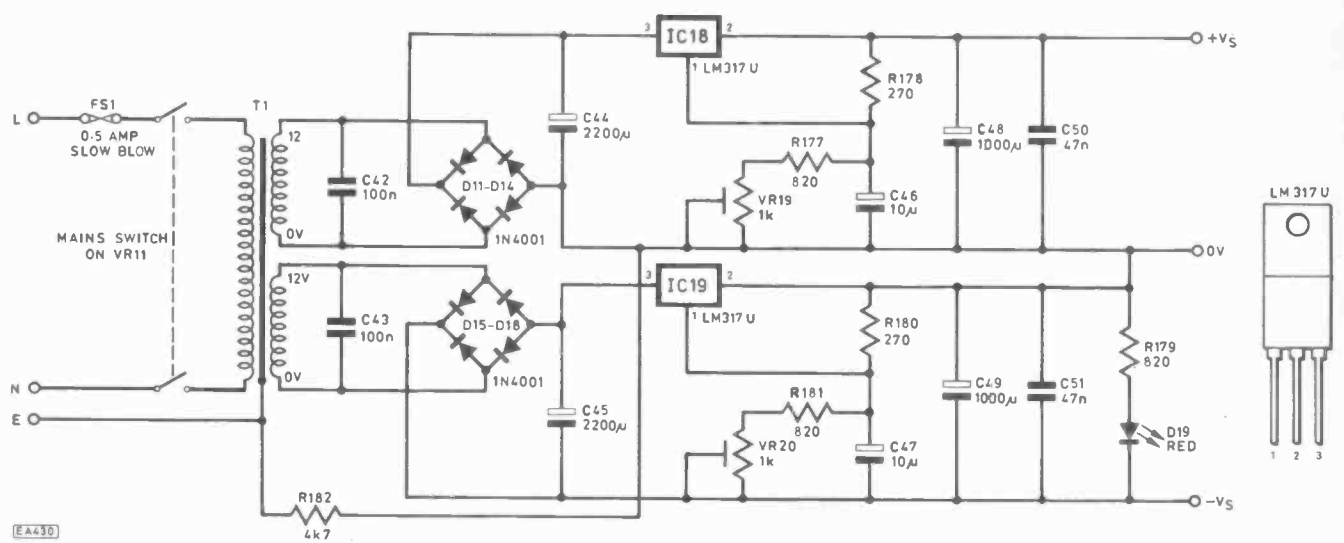
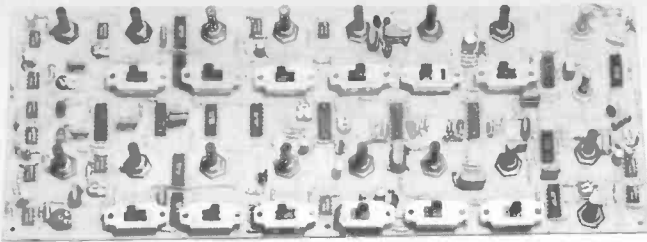


Fig. 5. Power supply unit



Board assembly

## POWER SUPPLY

This is a highly stable, monolithic regulator type providing  $\pm 8.5V$ , trimmed by VR18 and VR19. *Since the CMOS i.c.s are run directly across the positive and negative supply rails for economy of design, on no account must these voltages be exceeded, and the power supply voltages must be set before connecting power to the main part of the circuit board.* Wire links are provided on the p.c.b. for this reason and these should not be inserted until the supply rails are set.

**Next Month: Construction, setting-up and test programs.**

# Readout...

## Help Sought

I wonder if any of your readers can come up with a design to overcome a problem in AV (Audio-Visual) presentation. In this, a minimum of two slide projectors are used with a fade unit to dissolve from one picture to another throughout a continuous sequence of colour transparencies, usually shown on a large screen to an audience. Rather than cine's frames-per-second, the AV viewer has so many seconds-per-frame to take in the picture, this being controlled by a programme stored on tape via an electronic fade unit.

The problem is that the lamp fade system has eclipsed the old iris diaphragm mechanism used to regulate the projector's light source. Basic though the iris mechanism is, it can be exploited to obtain a wide range of effects that the lamp fade system cannot. Unfortunately, as things stand at present, use of the iris method necessitates manual operation of the AV performance, for there is no way by which this mechanism can be automatically controlled from tape.

Although PE has never published an automatic iris controller, I wondered if any of its readers have cracked this problem, or would be interested in having a go at it. I have been told that radio control type feedback servos might do the trick, but to maximise the special effects capability of the iris, timing and positional instructions would need to be able to go into the taped programme.

Tony Hadfield  
Wimborne, Dorset.

*If anyone would like to contact Mr. Hadfield, would they please write to him c/o PE.*

## Greed

I noticed in your Nexus column (issue April 1983), the glee or should I say greed, at the sale of Cable & Wireless, and the proposed sale of British Telecom.

Do you not feel there are greater issues at stake than the prospect of lining ones own pockets?

To de-nationalise British Telecom means that the profit will instead be shared by the few lucky enough to be able to buy sufficient shares. Therefore, the British public will be robbed of the money.

Services such as call boxes, emergency services and telephones for the disabled will be threatened.

Despite these services which are loss makers, British Telecom is a profitable and efficient service. In the past ten years telephones have doubled while staff has increased by only six per cent. What private firm can boast this productivity?

British Telecom belongs to the people. Help to keep it that way.

R.G.A. Dewhurst,  
Hoddesdon.

*Nexus comments:—*

*The Littlechild Report on BT privatisation makes provision for safeguarding emergency and rural call box services. The objective is to inject private capital to provide a more efficient service with lower costs. Far from robbing the public, lower costs will benefit private as well as business subscribers. Cable & Wireless was not sold outright. The Government, representing the people, retained a majority shareholding. C & W's 57 percent profit rise in its first year of privatisation yielded extra tax revenue. Profit and social responsibility are not incompatible. Without generating profit from trade and industry there would be no funds for education, health and other social services.*

## Sexist

I have just ordered a back issue of PE: and noticed your preview of the Electronics Hobby Fair at Alexandra Pavilion.

In your description of the event, you mention that "For wives/girl friends there is the added attraction of the nearby Wood Green Shopping City . . . although we are sure they will find plenty to interest them in the special exhibits at the Fair".

Reaction such as "sexist!" and "promu patriarchy!" are probably a bit strong, but I feel that your comment might have caused offence to the many competent women electrical engineers who read PE.

At a time when the number of women entering the field is disappointingly low (and a quote from the IEE is appropriate: Extract from IEE booklet "Training Requirements",

published 1979. "The Council of Engineering is concerned that few women take up electrical engineering as a profession, and is most anxious to see an increase in the number of women Members of the Institution") I feel that what you said was not encouraging.

I realise that at the moment, the majority of electronic enthusiasts are male, and that PE is targeted at this population, but I believe that such discrimination is to the disadvantage of expanding interest in the field.

Brian Carse,  
Coventry.

*No offence intended—Ed.*

## Slow Industry

With reference to the January edition of Practical Electronics concerning the slow approach to electronics of the motor industry. Isn't it the wrong way round? Isn't the electronic industry slow in taking in millions of pounds by designing and producing an all electric car (with one or two electric motors) with both speed and range (200 miles approx. before recharging). Are not the hybrid cars a sort of half way house?

I am quite confident that sooner or later an efficient electric car will arrive and the internal combustion engine will be an interested relic of the past.

Edwin R. Caruth,  
Leeds.

*This may well start to happen when Clive Sinclair launches his long awaited electric vehicle—Ed.*

## Excellent!

The recent issues of PE prompt me to send my congratulations to you and your staff on the excellent articles on microprocessors which have appeared.

Following the early articles on the UK101 to the *Ultimum* and *Microfile*, all have proved very useful. The *Ultimum* motherboard will give my UK101 some more years of interesting work.

The *Microfile* series, giving the characteristics and applications of i.c.s, is most welcome—an essential addition to tense manufacturers' data sheets.

As well as a "hobby interest" in the subject I lecture at a college of technology, and PE is an essential ingredient in keeping up with the subject.

With best wishes for the future.

George Small,  
Chesham, Bucks.

*Thank you.*

# MICRO PROMPT

The hardware and software exchange point for PE computer projects

## ULTIMUM UPDATE

We have now moved to Issue 2 of the Motherboard, to correct as many original errors as possible. As always, some anomalies have crept in.

The known errata for Issue 1 are as follows:

Link 11—Z80 position should be GND, not open (available near IC8, connects to IC8 pin 7).

Link 12—does not exist.

Link 13—located next to IC4 pin 11, should be open for Z80 systems and made for 65/68 systems.

There is insufficient provision for I/O mapping and external buffering close to the host.

The relevant part of the circuit in Issue 2 is as shown in Fig. 1, below.

Note that LK13 has been renamed LK14. LK12 now allows more reliable production of BRD, BWR in exclusively memory-mapped Z80 systems: 'B' should be connected to 'A' for Z80 and to 'C' for 65/68 systems. If I/O mapping is required then the LK13 default 'M' connections should be cut and the 'I/O' connections made. Pins 10 and 11 of the 40-way host connector (SK1, 2, 3) have been assigned and connected to, respectively, data buffer gate and +5V to simplify buffering at the host end of a cable. R/W or WR should be used for the data buffer direction on such buffering.

Yes, we will produce a complete manual but it will be available only after the series is completed. We are very keen to see an Ultimum user group. At present due to lack of space at 33, Cardiff Road, Watford we can't start the ball rolling, but in the latter part of 1983 we shall certainly make sure

## ROMDOS TO VORTEX

Sir—This short machine code routine should be of interest to any UK101 super-board owners who have upgraded their systems to 5¼" floppy disks.

The routine allows users of the new Vortex Disk system to read program files from the ROMDOS Disk system.

The need for the program arises because:

- 1) the directory is on a different track on both systems, and
- 2) the BASIC work space is different on both systems.

The routine is instant compared to the alternatives i.e. saving the program to tape, then booting up vortex and reloading the tape or indirect files, which limits the size of program to be moved to less than half the size of the free BASIC workspace (about 10K in A32K system). This routine only requires 70–80 Bytes of memory anywhere in RAM and is totally relocatable.

The routine works by loading a ROMDOS program into Vortex workspace then updating all the pointers and line links, allowing you to run or reSAVE the program on a Vortex Disk.

### To use the program

- 1) Make a note of the starting tracks of BASIC programs to be transferred.
- 2) Boot up Vortex Disk.

one is organised (we have already spoken to West London and North London computer users' groups and they are both keen to help us).

William Edwards,  
Watford Electronics.

- 3) Type in the routine and save on disk (the code is totally relocatable) i.e. it will run from anywhere in memory without modification.
- 4) Load the program required by using the !LO (Track No.) Command.
- 5) Execute code Reset M \$7000G or BASIC 5 and GO\$7000.
- 6) You should now be in immediate mode and can SAVE/LIST/RUN the program.

B. Brownhill,  
Midlothian.

```

7000 A97F LDA #87F
7002 B5FE STA $FE
7004 A927 LDA #827
7006 B5FF STA $FF
7008 A000 LDY #800
700A B1FE LDA ($FE), Y
700C AA TAX
700D 20F9FE JSR $FEF9
7010 B1FE LDA ($FE), Y
7012 F00E BEQ $7022
7014 18 CLC
7015 6915 ADC #815
7017 91FE STA ($FE), Y
7019 85FF STA $FF
    
```

```

701B 8A TXA
701C 85FE STA $FE
701E A900 LDA #800
7020 F0E8 BEQ $700A
7022 20F9FE JSR $FEF9
7025 A5FE LDA $FE
7027 857B STA $7B
7029 857D STA $7D
702B A5FF LDA $FF
702D 857C STA $7C
702F 857E STA $7E
7031 A927 LDA #827
7033 857A STA $7A
7035 A97F LDA #87F
    
```

```

7037 8579 STA $79
7039 60 RTS
    
```

## ULTIMUM CRUNCHER

Sir—I have been reading your Ultimum series and I am very impressed with the system.

However, for the benefit of myself and many others, could you please publish details of how to generate a signal similar to RFSH from an 8080/8085 system to allow the WE of the Dynamic RAM board.

I would also like to see a "number cruncher" board. Although chips such as the AM9511 and AM9512 are quite expensive, I feel that such a board would be worthwhile.

S. C. Winsor,  
Kenilworth.

On the point of the Number Cruncher, Watford Electronics replies: At present the cost of available number cruncher i.c.s is prohibitive, in that a number cruncher board for the Ultimum based on one of these chips would be of a disproportionately high price. However, it is the view of W.E. that at some time in the near future these chips will come down in price to a more suitable level, at which point a number cruncher for Ultimum will certainly become a reality.

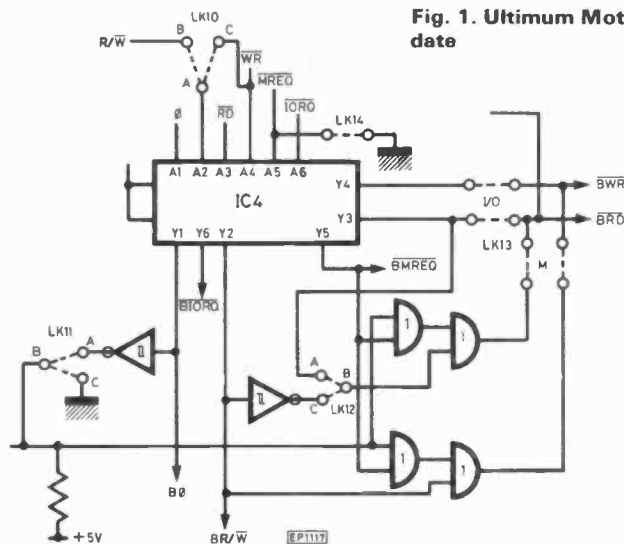


Fig. 1. Ultimum Motherboard update



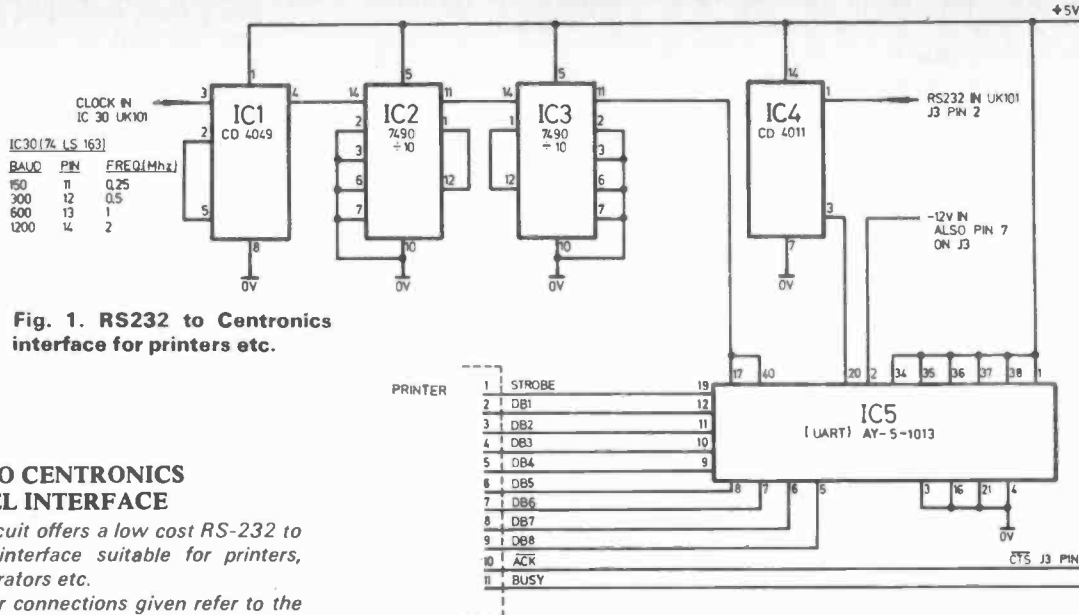


Fig. 1. RS232 to Centronics interface for printers etc.

### SERIAL TO CENTRONICS PARALLEL INTERFACE

Sir—This circuit offers a low cost RS-232 to centronics interface suitable for printers, sound generators etc.

Computer connections given refer to the UK-101 and Ohio CIP series, as subtle clock chain differences may be noted the approximate baud/frequency relationship is shown on the circuit diagram.

The circuit is based on a low cost AY-5-1013 UART configured for even parity, two stop and eight data bits. A clock signal equal to sixteen times the baud rate is required at pins 17 and 40 (i.e. 300 baud  $\times$  16 = 4 800hz). It is recommended that a data sheet be obtained with the chip. This will allow the constructor to configure the circuit for any computer.

IC1 provides a C-MOS buffer to the heavily loaded clock chain, whilst ICs 2 and 3 are divide-by-10 counters to feed the UART clock. The UART is frequency tolerant and a TTL clock could be constructed separately.

The RS-232 input is fed to the UART via an inverting gate IC4, this helps re-establish signal levels after the ribbon cable. The circuit is not critical and may be constructed on perforated board.

A -12 volt level is essential to proper UART operation. This can be provided with a small 12 volt transformer, bridge rectifier and 470 $\mu$ F/25 volt capacitor. A simple 12 volt Zener diode will ensure the recommended stability.

Ohio users must locate and cut the track connecting pin 7 of J3 to 0 volts. For those opposed to track cutting, the -12 volts may alternatively be fed to the collector of transistor (PNP) Q1 through a 1k 5% resistor.

The link between pin 9 of J3 (CTS) and 0 volts must also be removed, connecting a 1k 5% resistor between pin 9 and 0 volts will ensure computer operation with the peripheral disconnected.

Connections are best made with ribbon cable using the centronic recommendation, i.e. (1) 0 volts, (2) strobe, (3) 0 volts, (4) BDI, (5) 0 volts etc., this will minimise cross talk.

For cable lengths exceeding a metre, ICs 1-3 should be at the computer and ICs 4 and 5 at the peripheral.

Ohio/UK-101 users can turn on the inter-

face with POKE 517,1 (or SAVE) and turn off with POKE 517,0. OS-65D users should use POKE 8994,1 to turn on and POKE 8994,2 to disable.

Owners of Series Two dual display format boards and OS-65D version 3.3 will note that the Baud rate doubles from 300 to 600 when the 48 character mode is selected.

A word of caution; semiconductor junctions take exception to negative voltage inputs so be careful where you connect the -12 volts. If in doubt consult your local users' group which will have a number of members willing and competent to help you.

Experimentation with Busy and ACK will show which is best for connection to CTS.

It has been found in some instances both may be connected to CTS each via a 120 ohms series resistor. POKE 13,40 for ROM BASIC or 21,40 with disc will allow running without the CTS handshake,

P. Whittaker,  
Transvaal,  
S. Africa

### UK101 as clock

Sir—I have written a short program which displays a digital clock on the screen. Time is kept by the delay in line 190, which might have to be changed to suit other UK101's. The delay lasts approximately 1 second. At the beginning of the program you enter the current time, using the 24 hour clock, and then press return.

David C. Howarth,  
Bathgate.

```

10 PRINTCHR$(12);:K=48
20 PRINT:PRINT:PRINTTAB(12)"DIGITAL CLOCK"
30 PRINT:INPUT"TENS OF HOURS . . . .";H2:H2=H2+K
40 INPUT"UNITS OF HOURS . . .";H1:H1=H1+K
50 INPUT"TENS OF MINUTES . . .";M2:M2=M2+K
60 INPUT"UNITS OF MINUTES . . .";M1:M1=M1+K
70 INPUT"TENS OF SECONDS . . .";S2:S2=S2+K
80 INPUT"UNITS OF SECONDS . . .";S1:S1=S1+K
90 PRINTCHR$(12):POKE53325,32:PRINTTAB(12)"DIGITAL CLOCK"
100 POKE53732,58:POKE53727,58
110 POKE53735,S1:POKE53734,S2:POKE53730,M1:POKE53729,M2
120 POKE53725,H1:POKE53724,H2
130 S1=S1+1:IF S1=58 THEN S2=S2+1:S1=K
140 IF S2=54 AND S1=K THEN M1=M1+1:S2=K
150 IF M1=58 THEN M2=M2+1:M1=K
160 IF M2=54 AND M1=K THEN H1=H1+1:M2=K
170 IF H1=58 THEN H2=H2+1:H1=K
180 IF H2=50 AND H1=52 AND M2=K AND M1=K AND S2=K AND S1=K THEN GOTO SUB200
190 FOR I=1 TO 1042:NEXT:GOTO 110
200 M1=K:M2=K:S2=K:S1=K:H1=K:H2=K:RETURN
OK

```

## MICROCONTROLLER KEYBOARD

Sir—I have found the keyboard of the Microcontroller awkward to use owing to the unusual layout of the hex keys. The method used to decode which key is pressed makes it a relatively simple process to alter the keyboard layout with software modifications, without affecting the rest of the controller, its routines, or any programs already being used.

The keycode converter starting at F877 uses a table of key addresses at F89C—F8BB to determine which key is pressed, the value from this table is then converted to the key code with the aid of a subroutine at F86D.

All that is necessary to modify the keyboard layout to suit your personal taste is to re-arrange the order of the key address table. Table 1 shows the present order of the key address table in the monitor. Table 2 shows the order necessary to give a keyboard layout as shown adjacent.

W.T. Baillie  
Milton Keynes

**TABLE 1. DISBUG KEY ADDRESS TABLE**

ADDRESS	CONTENTS
F89C	00 01 11 12 20 21 22 30
F8A4	31 32 42 43 44 64 63 41
F8AC	33 23 13 03 35 17 27 37
F8B4	25 01 06 07 05 16 40 54

**TABLE 2. MODIFIED TABLE FOR LAYOUT AS SHOWN BELOW**

ADDRESS	CONTENTS
F89C	42 00 02 01 43 10 11 12
F8A4	44 20 21 22 64 30 31 32
F8AC	25 33 23 13 63 17 27 37
F8B4	41 03 06 07 05 16 40 54

PF1	C	D	E	F	BREAKPOINT	REGISTER	.	GO
PF2	8	9	A	B	PRESET			1/2
SHIFT	4	5	6	7	MEMORY	CANCEL	*	RESTART
#	∅	1	2	3	ENTER			NEXT

## M/C PROGRAM SEARCH

Sir—As this is my first attempt to write a program in machine code, it may be a little crude. But it works well and achieves the intended results.

The program is for UK101 owners, who like myself save several programs on one tape. It enables you to leave the searching for the start of the program to the computer. The first line of each program should be the name or code for that program, e.g. 1REM \* A123. In this case the code word is 4 digits long. But by changing the contents of 02AB it can be made to the length you require.

To operate the program you just type LOAD as usual. Then you give the code number. The computer then searches for, and loads, the required program. At the end it displays the message "Program Loaded" and disables the load flag so the next program is not loaded.

The program works by altering the load vectors at 021E 021F to cause a jump to the search routine. This is done by poking 542, 75 and 543, 2. When the code is found, the program jumps back to the load routine (FF8B). Within the program, the addresses 0004 and 0005 are altered to contain the address 0222. This causes a jump at the end of loading to this address, instead of the usual syntax error signal, followed by OK. The message "Program Loaded" is displayed, and the load flag is set to 0.

Although this routine takes up pretty well all the unused RAM, I think it is very useful. And no doubt the more skilful programmers will be able to shorten it.

```

0222 A9 C3 LD#SC3
0224 85 04 STAS0004
0226 A9 A8 LDA#$A8
0228 85 05 STAS0005
022A A9 00 LDA#$00
022C 8D 03 02 STAS0203
02F 20 5F 02 JSR$Z025F
    
```

```

0232 A2 00 LDX#$00
0234 20 B8 02 JSR$02B8
0237 A2 0A LDX#$0A
0239 20 B8 02 JSR$0238
023C A2 1F LDX#$1F
023E 20 B8 02 JSR$02B8
0241 60 RTS
0242 A9 22 LDA#$22
0244 85 04 STAS0004
0246 A9 02 LDA#$02
0248 85 05 STAS0005
024A 60 RTS
024B 48 PHA
024C 8A TXA
024D 48 PHA
024E A9 42 LDA#$42
0250 85 04 STAS0004
0252 A9 02 LDA#$02
0254 85 05 STAS0005
0256 20 73 02 JSR$0273
0259 68 PLA
025A AA TAX
025B 68 PLA
025C 4C 8B FF JMP$FF8B
025F A0 00 LDY#$00
0261 A9 20 LDA#$20
0263 99 00 D3 STASD300, Y
0266 99 00 D2 STASD200, Y
0269 99 00 D1 STASD100, Y
026C 99 00 D0 STASD000, Y
026F C8 1NY
0270 D0 F1 BNE$0261
0272 60 RTS
0273 20 5F 02 JSR$025F
0276 A2 00 LDX#$00
0278 20 B8 02 JSR$02B4
027B A2 11 LDX#$11
0270 20 B8 02 JSR$0238
0280 A2 00 LDX#$00
0282 20 00 FD JSR$FD00
0285 C9 1C CMP#$1C
0287 F0 EA BEQ$0273
0289 20 2D BF JSR$BF2D
028C C9 0D CMP#$0D
028E F0 07 BEQ$0297
0290 9D F0 00 STAS00F0, X
0293 E8 INX
0294 4C 82 02 JMP$0282
    
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0297 20 SF 02 JSR$025F
029A A2 29 LDX#$29
029C 20 B8 02 JSR$02B8
029F A2 00 LDX#$00
02A1 20 80 FE JSR$FE80
02A4 DD F0 00 CMP$00F0, X
02A7 D0 06 BNE$02AF
02A9 E8 INX
02AA E0 04 CPX#$04
02AC D0 F3 BNE$02A1
02AE 60 RTS
02AF E0 00 CPX#$00
02B1 F0 EE BEQ$029F
02B3 A2 00 LDX#$00
02B5 4C A4 02 JMP$02A4
02B8 BD CA 02 LDA$02CA, X
02BB C9 00 CMP#$00
02BD F0 07 BEQ$02C6
02BF 20 2D BF JSR$BF2D
02C2 E8 INX
02C3 4C B8 02 JMP$02B8
02C6 60 RTS
02CA 0D 50 52 4F 47 52 41 4D
02D2 20 00
02D4 4C 4F 41 44 45 44 00
02DB 4E 55 4D 42 45 52 00
02E2 00 41 47 49 4E 00
02E9 0A 0A 0A 0A 0A 0A 00
02F0 53 45 41 52 43 48 49
02F7 4E 47 00
    
```

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Software and hardware designs submitted should be accompanied by a declaration to the effect that it is the original work of the undersigned, and that it has not been accepted for publication elsewhere.

W. H. Ashworth,  
Preston.

# AUTOMOBILE TEST SET

MICHAEL TOOLEY B.A.

DAVID WHITFIELD M.A. M.Sc.

## PART TWO

In the first part of this article the principles of operation of the various functions of the Auto Test Set were described in detail, together with their usefulness to the troubleshooting and performance-conscious motorist. This article carries on from the detailed circuit description by covering the construction of the complete instrument, and concludes with a detailed series of tests and calibration steps, together with some fault-finding hints and suggestions.

### CONSTRUCTION

A diecast box is used in the construction of the Auto Test Set to ensure that the final unit is rugged enough to withstand hard use. The majority of the small components are mounted inside the box on a single-sided printed circuit board. The copper foil pattern for the board is shown in Fig. 7, with the corresponding component layout in Fig. 8. The interconnection wiring points have been labelled for later identification. No special handling procedures need to be observed in mounting the components on the p.c.b., but constructors may wish to use 14-pin d.i.l. sockets for mounting IC1 and IC2. Care should be taken to ensure the correct orientation of all of the polarised components (semiconductors and electrolytic capacitors) before soldering them in place. The use of terminal pins is recommended for ease of installation of the interconnection wiring.

When all of the components have been mounted on the p.c.b., a careful visual inspection of the track side of the board should be made before proceeding. Particular attention should be paid to soldered joints, and all dry joints and solder bridges should be rectified at this stage. After a final check on the orientation of polarised components, the p.c.b. may be mounted in the base of the diecast box using four short pillars. When positioning the board, adequate clearance should be left for the d.c. supply sockets, SK3 and SK4, which should be mounted on the side of the box and adjacent to pins A and B. Short lengths of insulated wire should then be used to connect SK3 (red) to pin B, and SK4 (black) to pin A; the wire links used should be long enough to allow the p.c.b. to be easily removed from the box for troubleshooting.

The remaining components are mounted on the lid of the diecast box, as shown in Fig. 9. The assembly sequence is simplified if all of the necessary holes are cut before any of the components are mounted. Marking out of the holes is simplified if the lid is first covered with masking tape, and the hole positions marked on the tape before being centrepunched. The cutout for the meter is most easily made by

drilling a series of holes around the circumference to remove the majority of the metal, and then cleaning up the hole with a file until the meter is an easy fit. When the meter, switches, terminals and l.e.d.s have been mounted, the next step is to fit the remaining components to the switch and meter terminals as shown in Fig. 9. It should be noted that, when making up the necessary values for R28 to R31, it may be easier to use a number of standard values in series/parallel, e.g. R28 may be made up from two 100 kilohm resistors in parallel.

The final assembly step is to install the interconnection wiring between the p.c.b. and the components mounted on the lid of the box. Ribbon cable provides one of the most convenient methods of installing the wiring, and it is suggested that one piece be used for each of the four groups of terminal pins. The cable lengths should be adequate to allow the lid to be laid flat alongside the box during calibration. The wire from S2 to one end of R33 should be connected as shown by the solid line, and R33 should temporarily be fitted as a short length of wire. A final check of the wiring should show that pins J and K on the p.c.b. are the only ones left unconnected; these may be used if an alternative buzzer is to be used off the board, but otherwise they may remain unconnected.

### TESTS AND ADJUSTMENTS

The initial tests and adjustments require the use of a power supply or battery capable of delivering 12 volts at up to approximately 120mA. Ideally, the supply should have an electronic over-current trip, but if this is not available, an appropriately rated line fuse will suffice to protect against catastrophic failures or errors. Before connecting the supply, the controls on the Auto Test Set should be set to the following: S1 to the 'Carry' position; S2 to the '4 cyl' position; S3 to 'Off'. The power supply should be connected to SK3/SK4 via a multimeter set to the d.c. current range rated at a minimum of 100mA.

Switching on the supply to the Auto Test Set should cause the 'NOGO' and the 'Power' l.e.d.s to be illuminated; no other l.e.d.s should be illuminated. The supply current indicated should be approximately 40mA, but only significant variations from this value should be considered as significant. Should neither of the l.e.d.s be illuminated and no supply current be drawn, the polarity of D12 and the power supply wiring should be carefully checked. Moving the instrument sharply should show that the meter movement is significantly damped; if not, the wiring to S1 and ME1

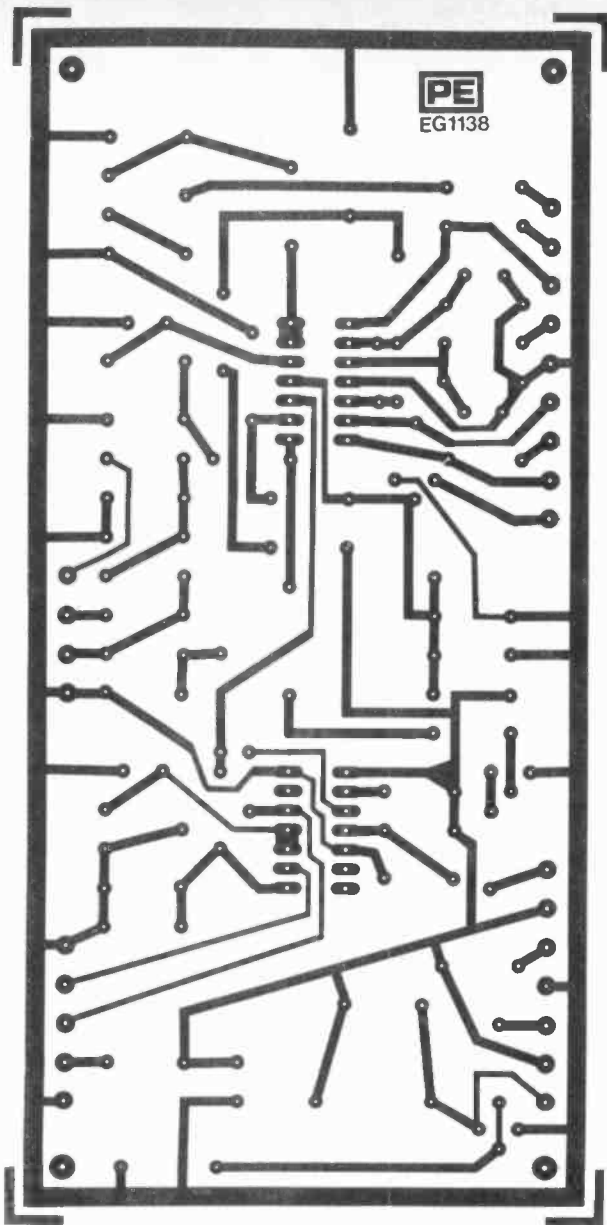


Fig. 7. Foil pattern for board underside

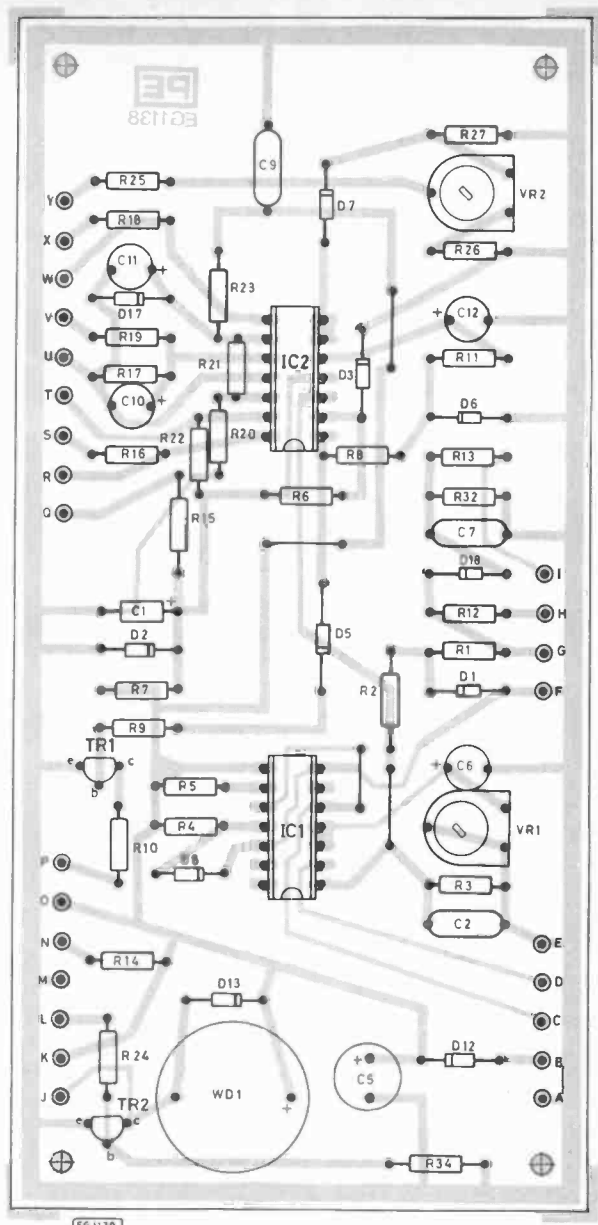


Fig. 8. Component layout. Note that in Fig. 2 pins 3/2 of IC2a should be reversed

should be re-examined. If the supply current is significantly lower than expected, and everything appears as normal except that no i.e.d.s are illuminated, then it is possible that the polarity of the i.e.d.s is incorrect. When these initial tests are satisfactory, the functions may be tested.

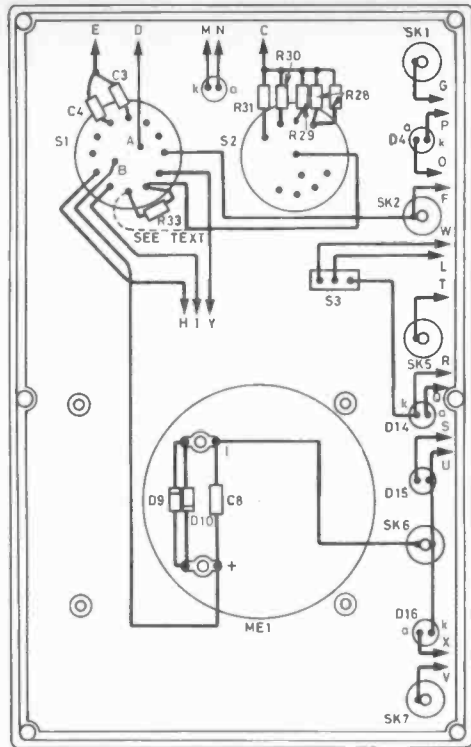
The function switch should now be moved to the '0 to 15V' position, and the circuit shown in Fig. 10 set up to allow testing of the two voltmeter ranges. As the potentiometer is varied from minimum to maximum setting, the meter indication should move over the full scale. Significant scale errors should lead to investigation of the wiring to ME1, S1, and the value of R12. As the setting of the potentiometer is increased from minimum, D4 should become illuminated at a potential of approximately 1V. Should the i.e.d. fail to illuminate, the polarity of D3, D4, D5 and TR1, and the power supply to IC2 should be checked to determine the source of the problem.

The offset zero voltage range is checked using the same arrangement as shown in Fig. 10, but with the function switch now set to '10 to 15V'. Varying the voltage applied to

SK1/SK2 over the range 10 to 15V by means of the potentiometer, and comparing the measured voltage with that indicated by the test set should produce a response of the type shown in Fig. 11. Any significant movement of the curve up or down the axis, representing consistently high or low indications, should initially lead to a check on the value of R13. The most likely cause, however, is that the nominal Zener voltage of D18 is at one end (high or low) of the tolerance band, and this may be cured by either replacing the diode with an alternative, or by padding the diode.

Calibration of the dwell range involves selecting the 'Dwell' position on the function switch, and disconnecting all inputs from SK1/SK2. In this condition the meter should indicate very close to zero, and D4 should be extinguished. Possible problems in the i.e.d. circuitry should already have been eliminated, so any significant meter indication would suggest a fault around IC2b. Calibration of the range involves the correct adjustment of VR2, and this is done most easily by connecting a lead between SK1 and SK3. VR2 is then adjusted to produce a full-scale meter indication,





EG1140 Fig. 9. Interconnection wiring

equivalent to 100% duty cycle. With the component values and types specified, it is possible that the maximum indication which may be achieved by adjusting VR2 will be just below full-scale on the meter. In such cases D6 may be replaced by a diode rated at 6.2 volts, or a silicon diode (e.g. 1N4148) may be wired forward-biased in series with the existing diode. The calibration of the dwell meter scale is independent of the setting of S2, and depends only on the number of engine cylinders; Table 1 shows the way in which the meter markings correspond to the dwell angle. As a final stage in the calibration the scale may optionally be checked at mid-scale by applying a square wave signal, amplitude between 5 and 12V pk-pk and frequency between 10 and 300Hz, and verifying that a half-scale indication is obtained.

The tachometer ranges are calibrated by adjusting the setting of VR1, and determining the value and position of R33. The setting up procedure starts by selecting the '1500 RPM' position on S1, and ensuring that S2 is still set to '4 cyl'. A signal generator producing a signal at 50Hz (corresponding to a 4 cylinder engine at 1500 RPM) and an amplitude of 5 to 12V pk-pk should be applied to SK1/SK2. The circuit shown in Fig. 12 may be used in place of a signal generator if none is available. The setting of VR1 should now be increased from minimum until a full-scale indication is achieved. If such an adjustment is not possible, then the values of C3, VR1 and R28 should be checked, followed by a check to the wiring of IC1 and S1/S2 if this does not reveal

Table 1. Showing meter indication of dwell angle

Meter Indication ( $\mu\text{A}$ )	Equivalent Dwell Angle ( $^\circ$ )			
	4 cyl	5 cyl	6 cyl	8 cyl
0	90	72	60	45
10	72	57.6	48	36
20	54	43.2	36	27
30	36	28.8	24	18
40	18	14.4	12	9
50	0	0	0	0

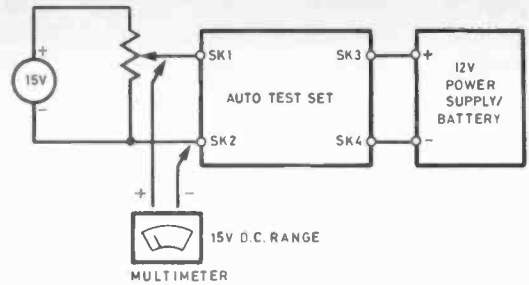
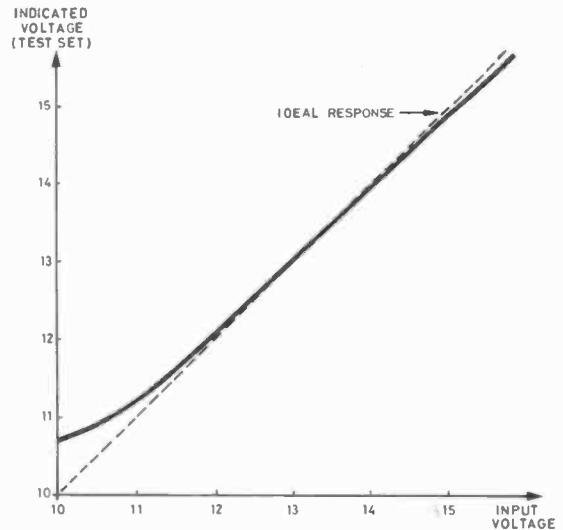


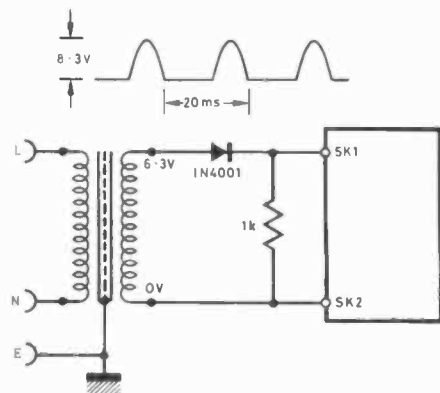
Fig. 10. Test configuration for the voltmeter ranges

the fault. When a full-scale indication has been obtained, S2 should be moved from the 4 cylinder position through the other positions. The meter indications should change from 1500 RPM (4 cylinders) through 1200 RPM, 1000 RPM to 750 RPM (8 cylinders) as the switch is rotated. Any errors would indicate that the values of R28 to R31 should be re-checked. The calibration of the basic range is now complete, but now the two ranges must be made to track correctly, and this involves R33. S2 should be set to the '4 cyl' position again.



EG1142

Fig. 11. Typical response for the offset zero voltmeter range



EG1143

Fig. 12. A tachometer calibration signal source

If moving S1 from '1500 RPM' to '5000 RPM' still produces an indication of 1500 RPM, then R33 is unnecessary, and the wire link should be retained in its place. The more likely result, however, is that the value indicated will be either too high or too low, by up to approximately 10%. If the new indication is too high, the temporary wire

link should be replaced by a suitable fixed resistor (typically in the range 1 to 4.7 kilohms) to restore the correct reading. If the new reading is too low, the wire from S1 to S2 should be reconnected in the position shown by the dotted line, i.e. at the other end of where R33 will be. VR1 should now be re-adjusted to produce an indication of 1500 RPM. S1 should then be moved back to the '1500 RPM', where the reading will now be too high. R33 is now selected to return the reading to 1500 RPM, and a value in the same 1 to 4.7 kilohms range is to be expected. It should be noted that the use of a single tracking correction resistor is a compromise to simplify the interconnection wiring; ideally a different value should be used for each of the ranges selected by S2. However, the error introduced will be small enough to be ignored in most cases, but the unused half of S2 may be used if necessary to allow individual calibration of the four ranges.

Verifying the correct operation of the lamp/fuse testing facility requires two fixed resistors, having values of 100 and 270ohms, respectively. S2 should be set to the 'Z' position, and with nothing connected to SK5, D14 should be illuminated, D15 should be extinguished and the buzzer should be silent. With the 270ohm resistor connected be-

tween SK5 and SK6 there should be no change in this situation. Replacing the 270ohm resistor by the 100ohm resistor, however, should cause the buzzer to sound and D15 to become illuminated. It is quite normal for D14 not to be totally extinguished. Any deviation from this behaviour should lead to investigation of IC2d and its associated components. Moving S3 to the 'Off' or 'V' position while the 100ohm resistor is connected should silence the buzzer but have no other effect. If the buzzer remains on, a check of the wiring of S3, the value of R34 and the polarity of TR2 should be made.

The circuit tracer facility is the only remaining part of the Auto Test Set to be tested. The configuration of Fig. 10 may be re-used for this purpose, but with SK7 and SK6 substituted for SK1 and SK2, respectively. S3 should be switched to the 'V' position. As the input voltage is increased from zero, D16 should become illuminated and the buzzer should sound at a level of approximately 9 to 10 volts. Moving S3 to 'Off' should silence the buzzer. Any error in the operation of the circuit tracer should lead to an investigation of the circuitry associated with IC2c.

This completes the testing and calibration of the Auto Test Set, which is now ready for use.

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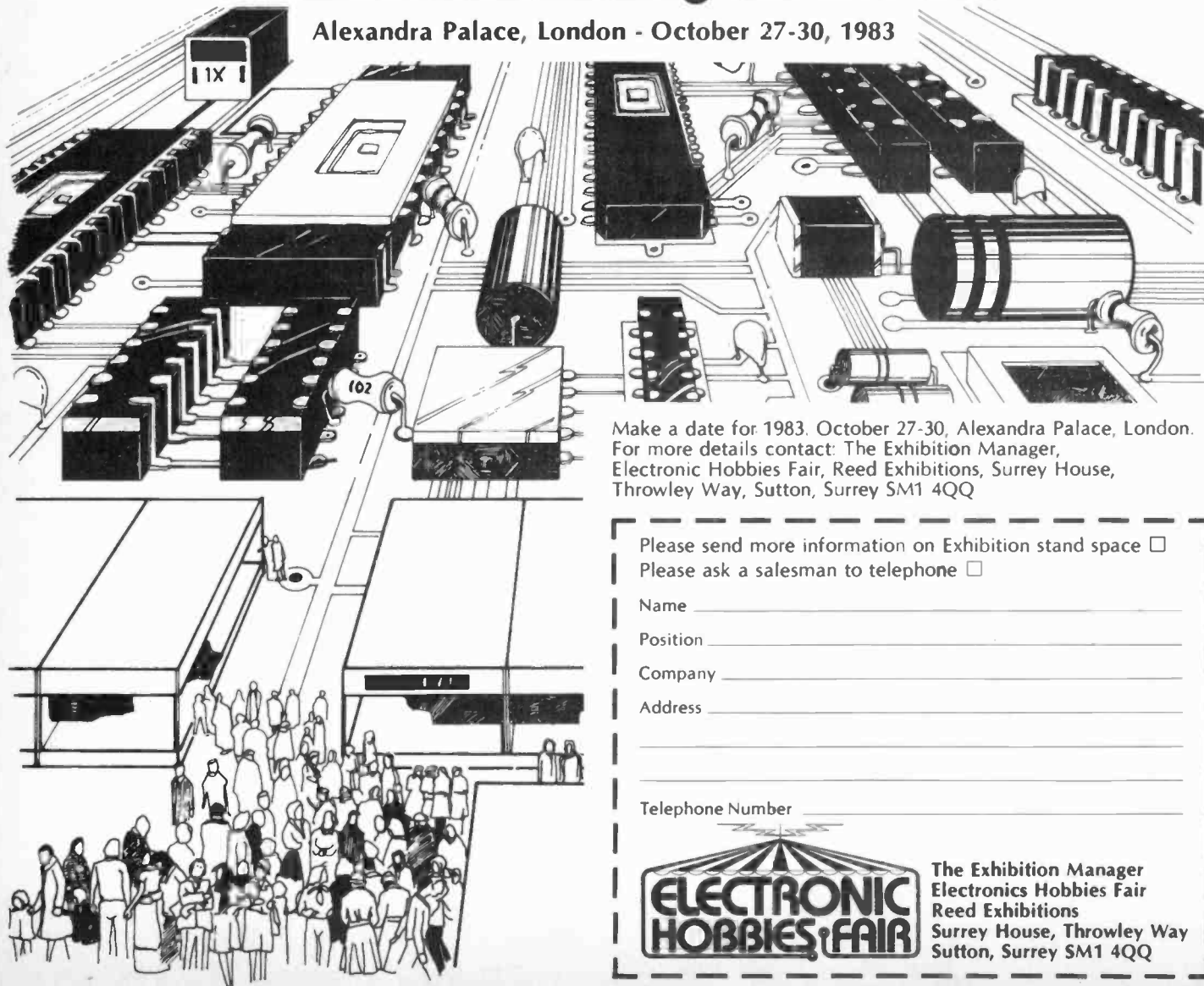
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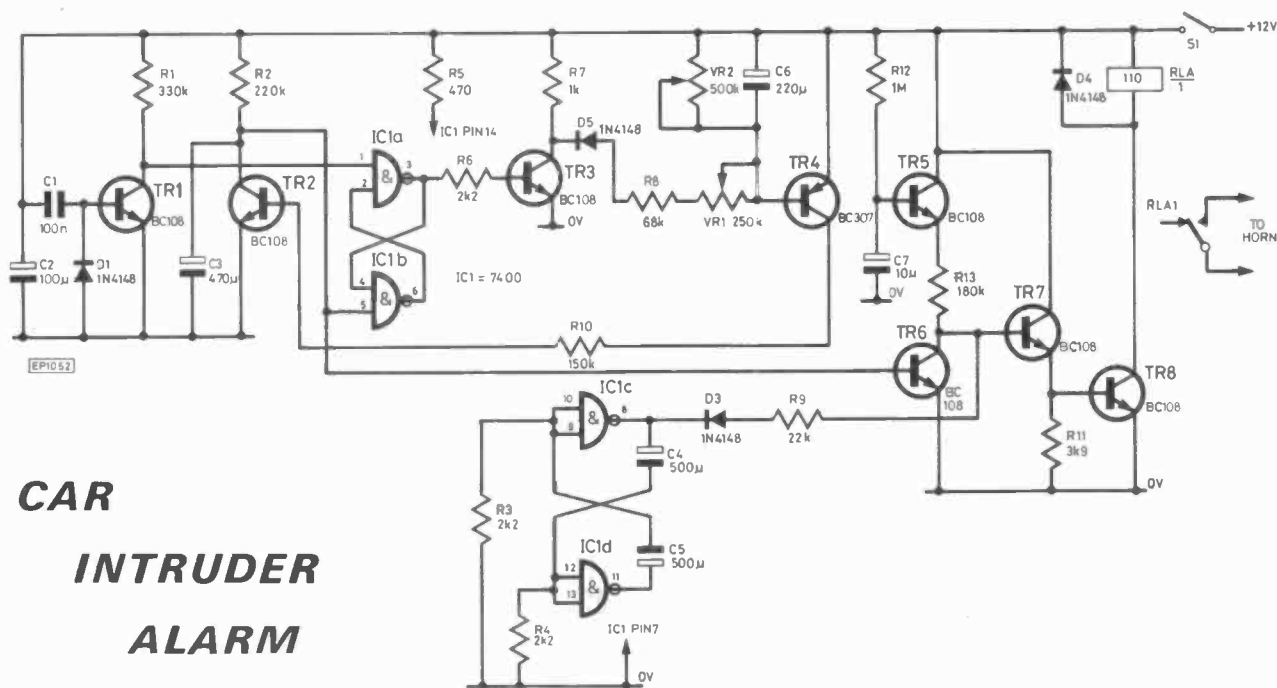
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## CAR INTRUDER ALARM

THE design requirements for this were as follows.

Able to be triggered by any electrical equipment in the car being operated, i.e. courtesy light, ignition, lights etc., but not the horn when being used to provide the alarm. To provide a delay of about 15 seconds to allow the car owner time to leave the vehicle after switching on the internal arming switch and a delay of about 8–10 seconds before the alarm operates to allow time for the owner to disarm on re-entry to the vehicle.

It must have a pulsating alarm which ceases after 30 seconds, but re-arms the circuit after 10–15 seconds.

On closure of S1 it takes approximately 10 to 15 seconds for C3 to become positively charged via R2. This puts a positive potential on pin 5 of IC1a and the

base of TR6 which in turn makes the base of TR7 negative, which means that RLA1 is de-energised. R12 and C7 are included to stop TR6 collector going positive before its base goes positive.

On opening the car door the courtesy light operates, which causes a negative pulse at TR1 collector and pin 1 of IC1a. This causes the bistable to operate which turns on TR3 allowing C6 to charge, putting a negative potential on the base of TR4. The time for C6 to charge is determined by R8 and VR1. Discharge time is determined by VR2. The base of TR2 is now positive, causing the collector to go negative. This causes two functions.

The base of TR6 is made negative turning it off, which puts the base of TR7 positive, this is modulated by IC1b which is oscillating at about 1 hertz, thereby

switching TR8 on and off allowing alternate operation of the relay.

The second function causes pin 5 of IC1a to be held negative thus preventing operation of the bistable whilst the relay is operating.

When C6 has discharged the relay ceases to operate and the bistable returns to an operational state.

The relay in the prototype was used to pulsate the horn but it could also be used to pulsate the headlights or operate a siren. The relay contacts must be capable of carrying the current demanded by the warning devices being used. VR1 is used to adjust the re-entry time delay and VR2 to adjust the relay operation time.

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Chorley,  
Lancs.

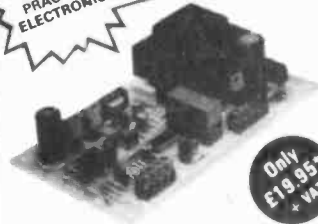




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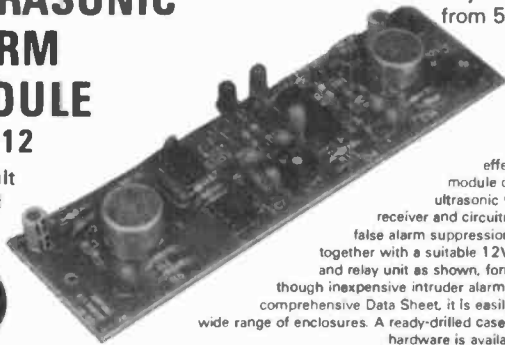
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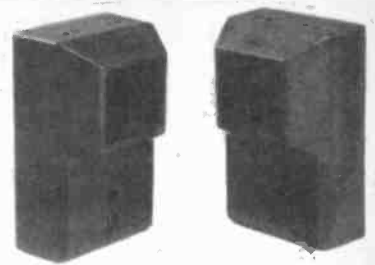
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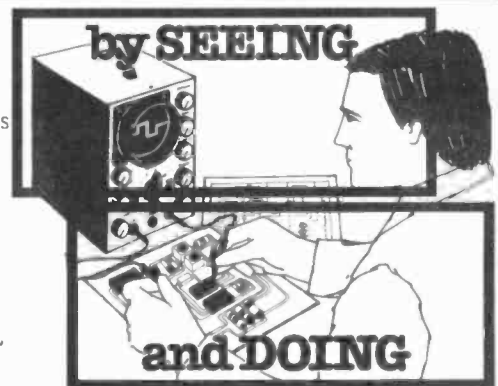
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# Ultimum Computer Interface

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THE PORT card for the Ultimum system provides all the facilities one is ever likely to need for running printers, terminals and so on, plus a few extra goodies. A real-time clock with battery backup is included, allowing your system to always know the correct date and time. Both this, and all of the ports provided by the card have interrupt facilities, to allow any or all of them to be run in an interrupt-driven mode with all its attendant advantages of software efficiency. All handshakes on the two parallel ports are performed by hardware, again reducing the software load. The serial port provides and accepts both full V24 level and TTL level RS232 signals in full-duplex mode with complete modem handshaking provision.

### HARDWARE

The circuit divides very neatly into four parts, as may be seen from the diagram (Fig. 8.1). The decoding section is fairly standard; ICs 7 & 8 compare the top eight address bits with those set up on link 1. IC6 decodes further using four more address bits to give sixteen outputs covering sixteen locations each, any of which is available (on link 2) for the master selects MS1 and MS2.

The 58174 real-time clock (IC2) consumes only ten microamps in standby mode and operates down to 2.2 volts. Since the trickle charge current for the battery is 1mA, rather odd but simple circuitry may be used in the backup supply. R9 charges the battery in normal operation and, when power is removed from the card, has very little effect on the 3.6 volts from the battery. The open collector output of IC5 combined with R10 ensures that the clock remains deselected under power-down conditions. Link 4 allows connection of the internal timer to the system interrupt line.

The serial port is handled by IC1, a 6551 asynchronous communications interface adaptor. This handles conversion between serial and parallel formats including some error checking features. Buffering and level conversion on the output side is provided by IC11. The CCITT recommendation V24 specifies a minimum  $\pm 3V$  signal and a typical  $\pm 12V$ . The EIA standard RS-232C is similar, and specifies in addition a maximum output slew rate of  $30V/\mu s$ , data rate of 20kb/s and cable length of 50 feet. The purpose of the slew rate specification is to control emission (which causes crosstalk) and reflection problems. The capacitors C1-3 perform this function, the outputs of the line drivers being current limited. Input buffering and level conversion is provided by IC10. Resistors R14-17, which are not normally fitted, allow correct termination of electrically long transmis-

sion lines. The transition points of the line receivers are about 1.3 volts. This has two useful effects. First, an open or shorted input will be seen as continuous "mark" (as if no characters were being output by the remote transmitter) rather than noise, and secondly, a TTL specification input ( $<0.8V = "0"$ ,  $>2.4V = "1"$ ) can be correctly read. IC10 also provides for filtering (C4-7) and about 500mV of hysteresis to eliminate noise on the input. The value of capacitor given causes the receiver to reject a 3V noise pulse less than 400ns wide. If noise problems are experienced they may be increased, paying careful attention to the Baud rate in use.

The values of C1-3 may be similarly modified if necessary. The supply-line diodes around IC10 protect it from damage when a signal is received with the power supply off.

Both the parallel ports are handled by (surprise, surprise!) an 8255, IC3. The circuitry is designed to take best advantage of the 8255 using port B in mode 1, output, for the Centronics parallel port and port A in mode 2, bidirectional, for the auxiliary port. ICs 4 and 5 provide increased current driving capability for the Centronics output. Link 3 may be used to select BUSY for the handshaking if  $\overline{ACK}$  is not available. In mode 1 the 8255 handles the required handshaking for the Centronics protocol on port B using lines 1 and 2 of port C. An interrupt request is available out of port C line zero; if interrupts will never be required for the Centronics port R5 may be omitted. Port A requires four handshake lines to run in full bidirectional mode; these are provided by port C lines 4-7 and consist of:

- a) Output Buffer Full and Acknowledge (output operations)
- b) Strobe and Input Buffer Full (input operations)

An interrupt request is available for the port on C3; R4 may be omitted if it will never be used. If no interrupts from the 8255 will ever be required then TR1 and R6 may also be omitted. It should be noted that the drive capability of port A is limited to 200 $\mu A$  (source), 1.7mA (sink) and buffering may be required for any particular application. The port may of course be used as a purely unidirectional one without modifying the 8255 mode (two parallel printers?).

### CONSTRUCTION

The usual order of construction applies: Sockets first followed by discrete components. Then fit the i.c.s and finally solder the battery in, being careful at all times not to short it out. Try not to subject the crystals to excessive brutality; they don't appreciate it. Finally choose and fit your

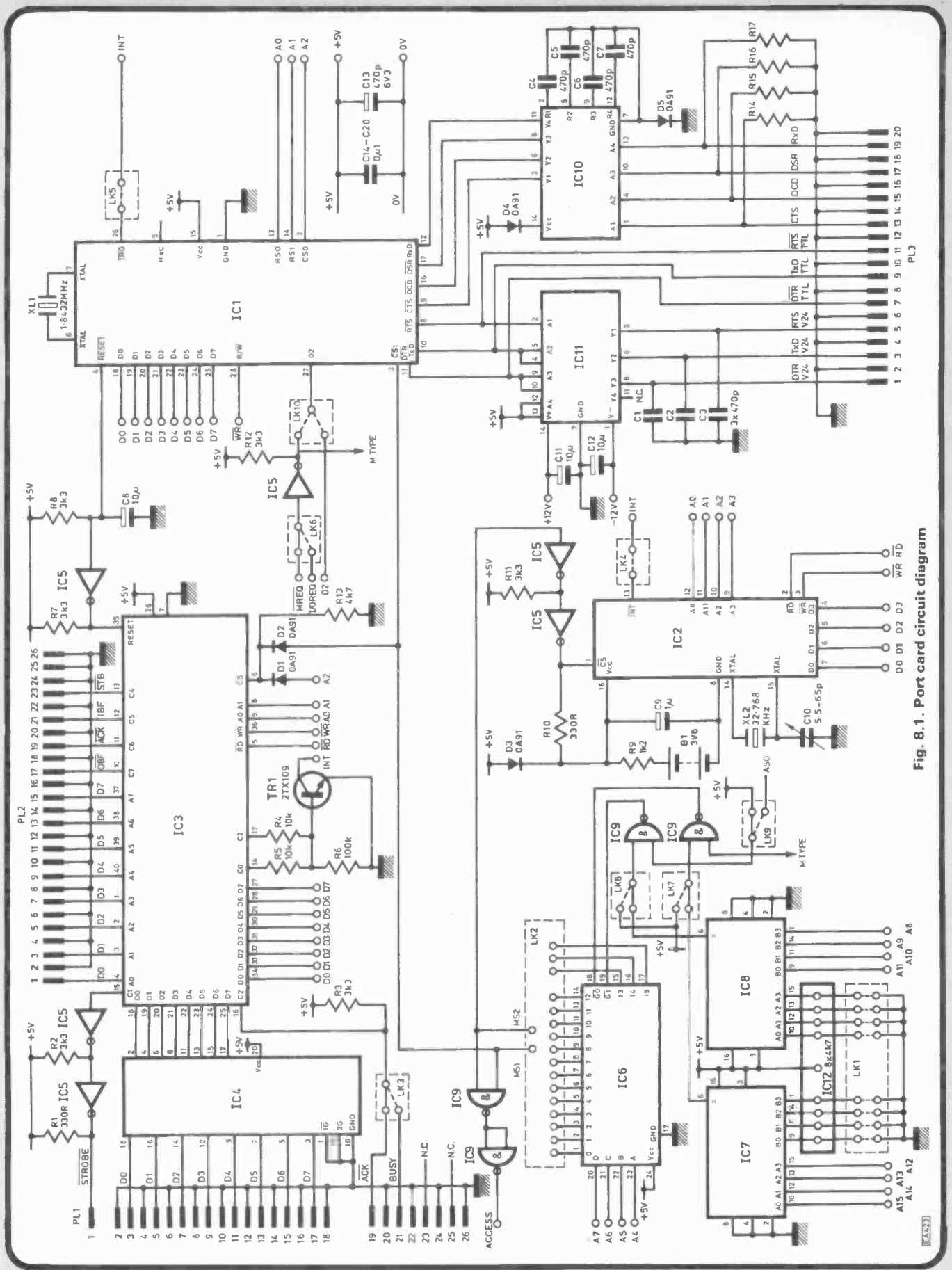


Fig. 8.1. Port card circuit diagram



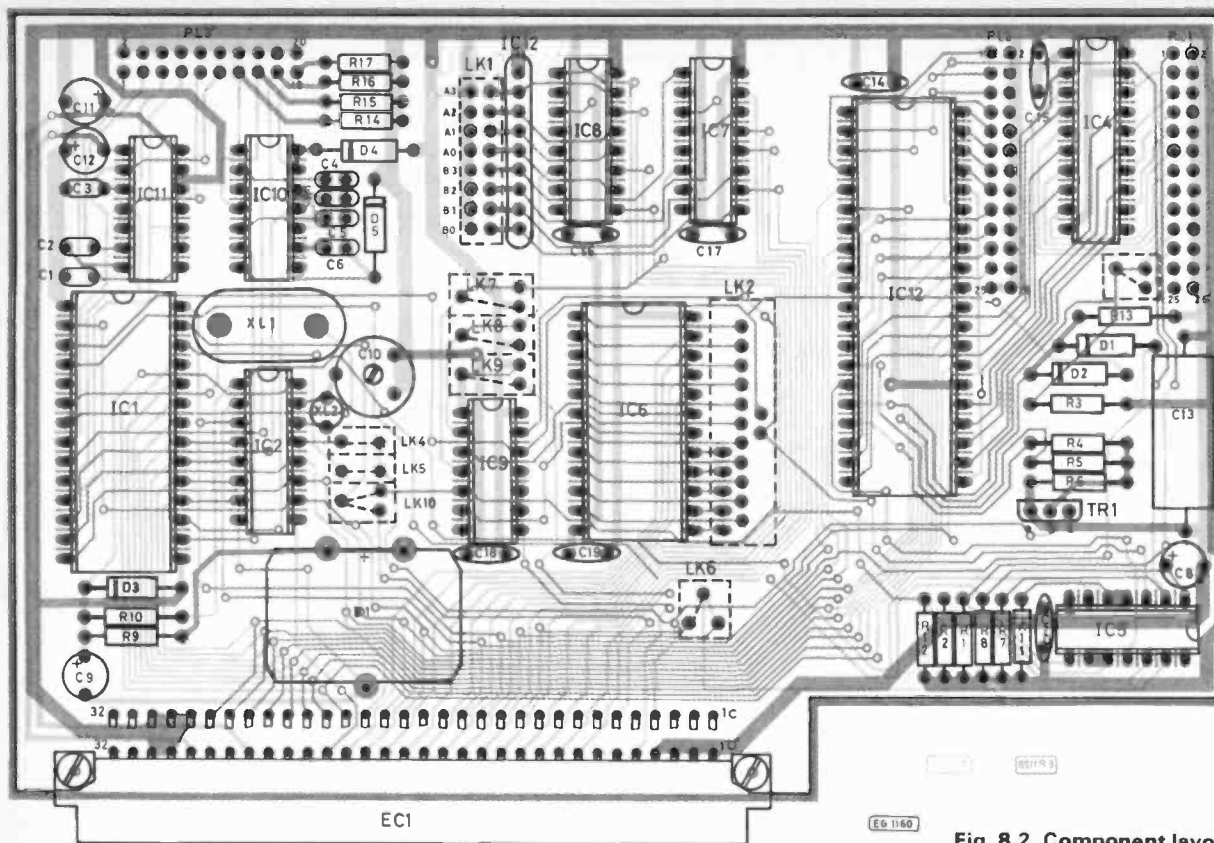


Fig. 8.2. Component layout (actual size)

## COMPONENTS ...

### Resistors

R1,R10	330 (2 off)
R2,R3,R7,R8,R11,R12	3k3 (6 off)
R4,R5	10k (2 off)
R6	100k
R9	1k2
R13	4k7
R14-17	not supplied in kit

### Capacitors

C1-7	470p ceramic (7 off)
C8,C11, C12	10 $\mu$ /16V tant. (3 off)
C9	1 $\mu$ /16V tant.
C10	5-65p trimmer
C13	470 $\mu$ /6V3
C14-20	100n ceramic (7 off)

### Semiconductors

D1-5	0A90 (5 off)
TR1	ZTX109
IC1	6551 ACIA
IC2	58174 RTC
IC3	8255 PPI
IC4	74LS244
IC5	74LS05

IC6	74LS154
IC7,IC8	74LS85 (2 off)
IC9	74LS00
IC10	1489 Quad line receiver
IC11	1488 Quad line driver
IC12	8 x 4k7 resistor s.i.l.

### Miscellaneous

X1	1.8432MHz crystal
X2	32.768kHz crystal
B1	3V6 p.c.b. mounting Ni-Cad
EC1	2 x 32 A+C right-angled male DIN
PL1, PL2	2 x 13 male IDC pins
PL3	2 x 10 male IDC pins
sockets ...	
14 pin	4 off
16 pin	3 off
20 pin	1 off
24 pin	1 off
28 pin	1 off
40 pin	1 off
Printed circuit board WE05PRT	

### Constructors' Note

Kits for all parts of the Ultimium will be available from **Watford Electronics**, 33 Cardiff Rd., Watford, Herts, WD1 8ED. Send SAE for price list of boards now available.

**Table 8.1. Link options**

1. Addressing: Top eight bits. Mode='0'. Marked end is least significant.
2. Addressing: Page subdivisions. Marked end is lowest address.
3. Centronics handshake: Default is  $\overline{ACK}$ . Alternative is BUSY.
4. Timer interrupt.
5. ACIA interrupt.
6. Address space: Default is memory-mapped. Alternative is I/O mapped.
7. Address space size: Make for 8-bit space and remove ICs 7 & 8.
8. Mapping: Default is 'permanent'. Alternative is 'mappable'.
9. Z80/65 or 68: No default.

**Table 8.3. Year status codes for register 13 of 58174**

Address 13 Write Mode

	DB3	DB2	DB1	DB0
Leap year	1	0	0	0
Leap year +1	0	1	0	0
Leap year +2	0	0	1	0
Leap year +3	0	0	0	1

Selected counter	Address bits				Mode
	AD3	AD2	AD1	AD0	
0 Test only	0	0	0	0	Write only
1 Tenths of sec.	0	0	0	1	Read only
2 Units of secs.	0	0	1	0	Read only
3 Tens of secs.	0	0	1	1	Read only
4 Units of mins.	0	1	0	0	Read or Write
5 Tens of mins.	0	1	0	1	Read or Write
6 Units of hours	0	1	1	0	Read or Write
7 Tens of hours	0	1	1	1	Read or Write
8 Units of days	1	0	0	0	Read or Write
9 Tens of days	1	0	0	1	Read or Write
10 Day of week	1	0	1	0	Read or Write
11 Units of months	1	0	1	1	Read or Write
12 Tens of months	1	1	0	0	Read or Write
13 Years	1	1	0	1	Write only
14 Stop/Start	1	1	1	0	Write only
15 Interrupt and status	1	1	1	1	Read or Write

**Table 8.2. Address decoding for clock registers of 58174**

**Table 8.4. Register 15 of 58174. Interrupt selection data**

Address 15 Write Mode

Function	DB3	DB2	DB1	DB0
No Interrupt	X	0	0	0
Interrupt at 60 sec. intervals*	0/1	1	0	0
Interrupt at 5.0 sec. intervals*	0/1	0	1	0
Interrupt at 0.5 sec. intervals*	0/1	0	0	1

\*±16.6 mS

DB3 = 0, single interrupt    DB3 = 1, repeated interrupt

**Fig. 8.3. Example clock program**

```

10 MS2=address of clock
20 R=9:GOSUB 1000
30 R=8:GOSUB 1000
40 PRINT " ";
50 R=12:GOSUB 1000
60 R=11:GOSUB 1000
70 PRINT " ";
80 R=7:GOSUB 1000
90 R=6:GOSUB 1000
100 PRINT ":";
110 R=5:GOSUB 1000
120 R=4:GOSUB 1000
130 PRINT ":";
140 R=3:GOSUB 1000
150 R=2:GOSUB 1000
160 PRINT
170 GOTO 20
1000 A=PEEK (MS2+R)
1010 IF A=15 THEN 1000
1020 PRINT A;
1030 RETURN
    
```

**Table 8.5. Internal registers of 6551**

RS <sub>1</sub>	RS <sub>0</sub>	Write	Read
0	0	Transmit Data Register	Receiver Data Register
0	1	Programmed Reset (Data is "Don't Care")	Status Register
1	0		Command Register
1	1		Control Register

required link options. The card occupies two sixteen-location chunks of address space which must be in the same 256-location page. Link 1 sets (in binary, made="0") the page number and link 2 selects two of sixteen subdivisions of the page. In hexadecimal terms, link 1 defines the first two digits and link 2 the third of the four required to describe a 64K address space. If the I/O option is being used in a machine with only one page of I/O space, ICs 7 & 8 should be omitted.

**SOFTWARE**

The 58174 maintains sixteen internal registers (Table 8.2) and as such uses the entire address space selected by MS2. The counter registers (1 to 12) hold the date-time in BCD format. If a counter is being updated at the time it is read, the value 15 will be returned which is an illegal BCD code and thus may be detected. The most significant four data bits will be ignored on a write and are undefined on a read and should be masked out by software. Register zero is used during manufacture and should not be accessed apart from writing a zero to it at system initialisation time. The value zero when written into register 14 will stop the clock; the

value one will re-start it. This allows time data to be loaded and the clock then to be started precisely. Register 13 may be used to set the year status according to Table 8.3. Register 15 is the interrupt status register. It may be set in accordance with Table 8.4 to request single or repeated interrupts in one of three time periods. Once set, the interrupt request will be cleared by a read of the status register. Fig. 8.3 is an example program which reads the date and time.

The 6551 has six internal locations mapped onto four addresses (Table 8.5). On the card these appear at MS1 + 4 to MS1 + 7. Figs. 4 to 7 give information on their function. The conditions reflected by bits 3 to 6 of the status register can cause an interrupt if enabled by bits 0 to 3 of the command register. The interrupt from status register bits 5 and 6 occurs on a change of state.

Note that CTS must be input to the 6551 for the transmit side to operate. If no suitable signal is available from the remote terminal then connect it to DTR/V24 at PL3. Fig. 8.8 gives an example program which uses the 6551 for output without using interrupts, and a suggested sequence of checks when interrupts are being used.

### CONTROL REGISTER

The Control Register is used to select the desired mode for the SY6551. The word length, number of stop bits, and clock controls are all determined by the Control Register, which is depicted in Figure 6.

#### STOP BITS

- 0 = 1 Stop Bit
- 1 = 2 Stop Bits
- 1 Stop Bit if Word Length = 8 Bits and Parity\*
- 1½ Stop Bits if Word Length = 5 Bits and No Parity

#### WORD LENGTH

BIT 6	BIT 5	DATA WORD LENGTH
0	0	8
0	1	7
1	0	6
1	1	5

#### RECEIVER CLOCK SOURCE

- 0 = External Receiver Clock
- 1 = Baud Rate Generator

\*This allows for 9-bit transmission (8 data bits plus parity).



				BAUD RATE GENERATOR
0	0	0	0	16x EXTERNAL CLOCK
0	0	0	1	50 BAUD
0	0	1	0	75
0	0	1	1	109.92
0	1	0	0	134.58
0	1	0	1	150
0	1	1	0	300
0	1	1	1	600
1	0	0	0	1200
1	0	0	1	1800
1	0	1	0	2400
1	0	1	1	3600
1	1	0	0	4800
1	1	0	1	7200
1	1	1	0	9600
1	1	1	1	19,200

HARDWARE RESET  
PROGRAM RESET

7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	0
-	-	-	-	-	-	-	-

Fig. 8.4. Control register format

### COMMAND REGISTER

The Command Register is used to control Specific Transmit/Receive functions and is shown in Figure 7.

#### PARITY CHECK CONTROLS

BIT 7	BIT 6	BIT 5	OPERATION
-	-	0	Parity Disabled - No Parity Bit Generated - No Parity Bit Received
0	0	1	Odd Parity Receiver and Transmitter
0	1	1	Even Parity Receiver and Transmitter
1	0	1	Mark Parity Bit Transmitted, Parity Check Disabled
1	1	1	Space Parity Bit Transmitted, Parity Check Disabled

#### NORMAL/ECHO MODE FOR RECEIVER

- 0 = Normal
- 1 = Echo (Bits 2 and 3 must be "0")



#### DATA TERMINAL READY

- 0 = Disable Receiver and All Interrupts (DTR high)
- 1 = Enable Receiver and All Interrupts (DTR low)

#### RECEIVER INTERRUPT ENABLE

- 0 = IRQ Interrupt Enabled from Bit 3 of Status Register
- 1 = IRQ Interrupt Disabled

#### TRANSMITTER CONTROLS

BIT 3	BIT 2	TRANSMIT INTERRUPT	RTS LEVEL	TRANSMITTER
0	0	Disabled	High	Off
0	1	Enabled	Low	On
1	0	Disabled	Low	On
1	1	Disabled	Low	Transmit BRK

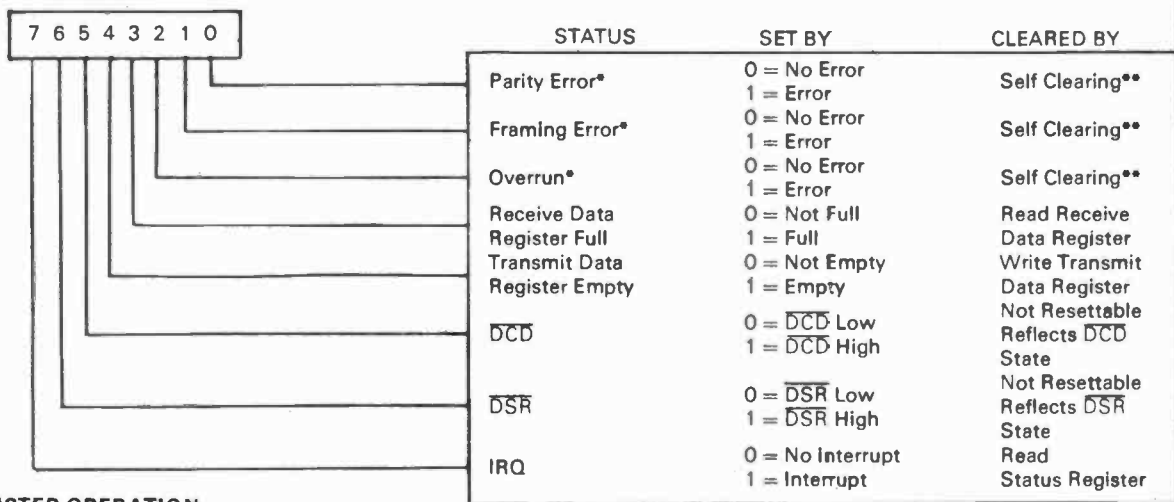
HARDWARE RESET  
PROGRAM RESET

7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	0
-	-	-	0	0	0	0	0

Fig. 8.5. Command register format

## STATUS REGISTER

The Status Register is used to indicate to the processor the status of various SY6551 functions and is outlined in Figure 8.



## STATUS REGISTER OPERATION

Because of the special functions of the various status bits, there is a suggested sequence for checking them. When an interrupt occurs, the R6551 should be interrogated, as follows:

1. Read Status Register  
This operation automatically clears Bit 7 (IRQ). Subsequent transitions on DSR and DCD will cause another interrupt.
2. Check IRQ Bit.  
If not set, Interrupt source is not the R6551.
3. Check DCD and DSR.  
These must be compared to their previous levels, which must have been saved by the processor. If they are both "0" (modem "on-line") and they are unchanged then the remaining bits must be checked.
4. Check RDRF (Bit 3).  
Check for Receiver Data Register Full.
5. Check Parity, Overrun, and Framing Error (Bits 0-2).  
Only if Receiver Data Register is full.
6. Check TDRE (Bit 4).  
Check for Transmitter Data Register Empty.
7. If none of the above, then CTS must have gone to the FALSE (high) state.

\*NO INTERRUPT GENERATED FOR THESE CONDITIONS.  
\*\*CLEARED AUTOMATICALLY AFTER A READ OF RDR AND THE NEXT ERROR FREE RECEIPT OF DATA.

	7	6	5	4	3	2	1	0
HARDWARE RESET	0	-	-	1	0	0	0	0
PROGRAM RESET	-	-	-	-	-	0	-	-

Fig. 8.6. Status register format

```

10 MS1=address
20 TDR=MS1 + 4:STR=MS1+5
30 CMR=MS1+6:CTR=MS1+7
40 POKE STR, 0 ; Reset
50 POKE CTR, 184 ; 2 stop bits, 7 data bits, 1200 baud
60 POKE CMR, 42 ; odd parity, transmit on, no
; interrupts
70 A$=characters to be output
80 L=LEN(A$)
90 FOR X=1 TO L
100 IF (PEEK(STR) AND 16) = 0 THEN 100;
; Wait for TDR empty
110 POKE TDR, ASC(MID$(A$,X,1))
120 NEXT X
    
```

Fig. 8.8. Example serial output program

These registers are used as temporary data storage for the 6551 Transmit and Receive circuits. The Transmit Data Register is characterized as follows:

- Bit 0 is the leading bit to be transmitted.
- Unused data bits are high-order bits and are "don't care" for transmission.

The Receive Data Register is characterized in a similar fashion:

- Bit 0 is the leading bit received.
- Unused data bits are the high-order bits and are "0" for the receiver.
- Parity bits are not contained in the Receive Data Register, but are stripped-off after being used for external parity checking. Parity and all unused high-order bits are "0".

Figure 9 illustrates a single transmitted or received data word, for the example of 8 data bits, parity, and 1 stop bit.

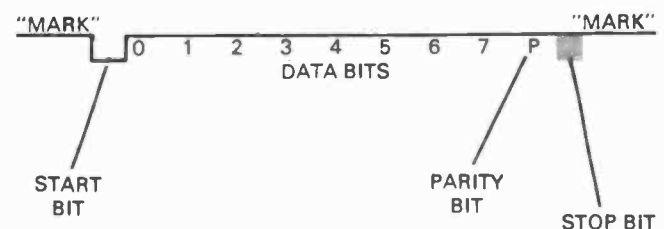


Fig. 8.7. Transmit and Receive data registers

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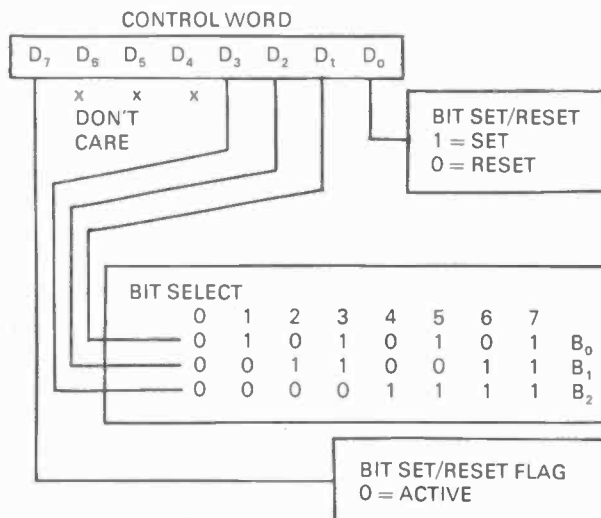
SAT ELECTRONICS, THE DESIGN CONSULTANTS, 235 CROSS ST SALE, CHESHIRE, M33 1JR Technical enquiry line 061 973 7882

D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>
OBF	INTE	IBF	INTE	INTR	INTE	OBF	INTR
A	AO	A	AI	A	B	B	B

INTE=Interrupt Enable  
INTR=Interrupt Request

Fig. 8.9. 8255 status word, mode 2 + 1

Fig. 8.10. Bit Set/Reset format



The 8255 has the usual four registers, located in the address space at MS1 to MS1 + 3. Having defined ports A and B to be working in modes requiring handshaking, port C is dedicated to these control functions and attempting to use it normally does not make much sense. Bits in it however do have specific uses as is shown in Fig. 8.9. It will often be most appropriate to manipulate them using the individual bit set/reset capability which the 8255 provides for port C. The required format is given in Fig. 8.10.

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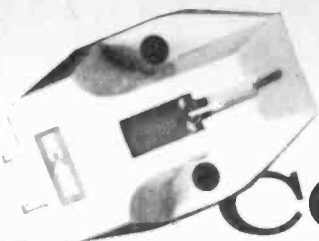
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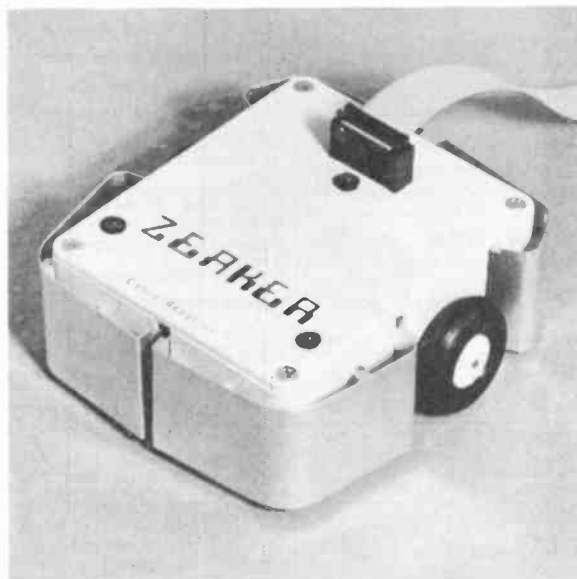
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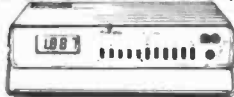
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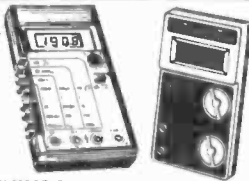
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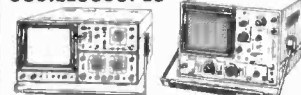
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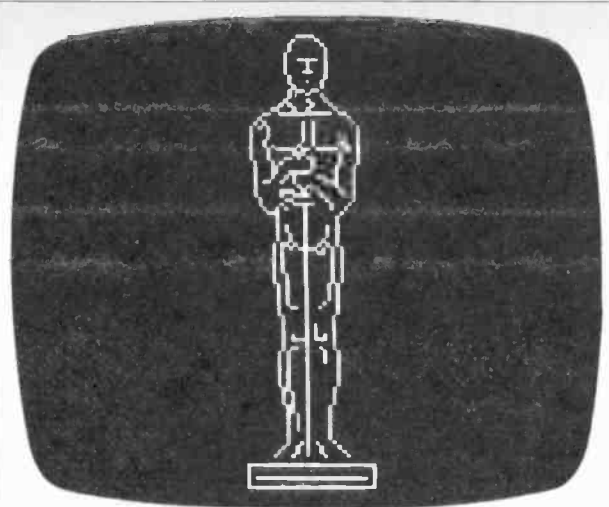


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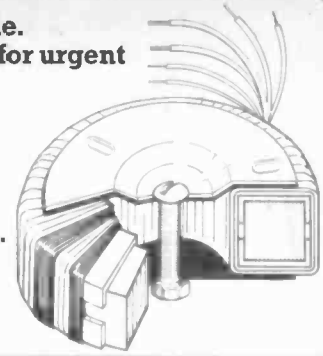
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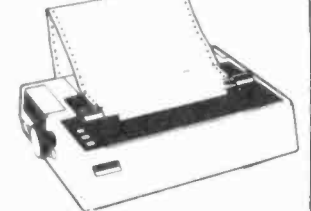
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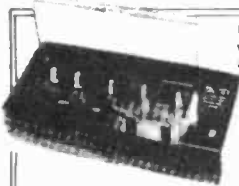
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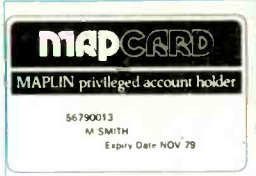
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7436	22p	74LS26	14p	74LS374	140p	74C55	45p	4089	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7437	22p	74LS26	14p	74LS374	140p	74C56	45p	4090	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7438	22p	74LS26	14p	74LS374	140p	74C57	45p	4091	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7440	15p	74LS28	14p	74LS374	140p	74C58	45p	4092	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7441	55p	74LS30	13p	74LS374	140p	74C59	45p	4093	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7442A	30p	74LS32	13p	74LS374	140p	74C60	45p	4094	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7443	30p	74LS32	13p	74LS374	140p	74C61	45p	4095	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7444A	50p	74LS33	14p	74LS374	140p	74C62	45p	4096	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7445A	50p	74LS33	14p	74LS374	140p	74C63	45p	4097	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7446A	35p	74LS38	14p	74LS374	140p	74C64	45p	4098	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7447A	35p	74LS38	14p	74LS374	140p	74C65	45p	4099	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7448	45p	74LS42	14p	74LS374	140p	74C66	45p	4100	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7449	45p	74LS42	14p	74LS374	140p	74C67	45p	4101	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7450	15p	74LS47	36p	74LS374	140p	74C68	45p	4102	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7451	15p	74LS47	36p	74LS374	140p	74C69	45p	4103	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7452	15p	74LS47	36p	74LS374	140p	74C70	45p	4104	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7453	15p	74LS47	36p	74LS374	140p	74C71	45p	4105	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7454	15p	74LS55	14p	74LS374	140p	74C72	45p	4106	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7455	15p	74LS55	14p	74LS374	140p	74C73	45p	4107	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7456	15p	74LS55	14p	74LS374	140p	74C74	45p	4108	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7457	15p	74LS55	14p	74LS374	140p	74C75	45p	4109	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7458	15p	74LS55	14p	74LS374	140p	74C76	45p	4110	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7459	15p	74LS55	14p	74LS374	140p	74C77	45p	4111	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7460	15p	74LS55	14p	74LS374	140p	74C78	45p	4112	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7461	15p	74LS55	14p	74LS374	140p	74C79	45p	4113	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7462	15p	74LS55	14p	74LS374	140p	74C80	45p	4114	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7463	15p	74LS55	14p	74LS374	140p	74C81	45p	4115	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7464	15p	74LS55	14p	74LS374	140p	74C82	45p	4116	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7465	15p	74LS55	14p	74LS374	140p	74C83	45p	4117	14p	CA3161E	150p	NE555	45p	8748	£16	NE555	45p	MC3487	500p
7466	15p	74LS55	14p	74LS374	140p	74C84	45p	4118	14p	CA3161E	150p	NE555	45p	8748	£16	NE555			

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