# 4/3-way servo solenoid directional control valves, pilot operated, with electrical position feedback and on-board electronics (OBE)

**RE 29088/10.10** 1/18 Replaces: 01.09

Type 4WRLE 10...35, symbols V/V1

Sizes (NG) 10, 16, 25, 27, 35 Unit series 3X Maximum working pressure P, A, B 350 bar (NG27: 280 bar) Nominal flow 40...1000 l/min ( $\Delta p = 10$  bar)



Type 4WRLE 10...35

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#### **Features**

- Pilot operated 4/3-way servo solenoid directional control valves NG10 to NG35
- Pilot valve NG6, with control piston and sleeve in servo quality, actuated on one side, 4/4 fail-safe position when switched off
- Control solenoid with electric position feedback and on-board electronics (OBE), calibrated at the factory
- Main stage in servo quality with position feedback
- Flow characteristic
  - M = Progressive with fine metering notch
  - P = Non-linear curve
  - L = Linear
- Electrical connection 6P+PE
   Signal input of differential amplifier with interface
   A1 ±10 V, or interface F1 4...20 mA (*R*sh = 200 Ω)

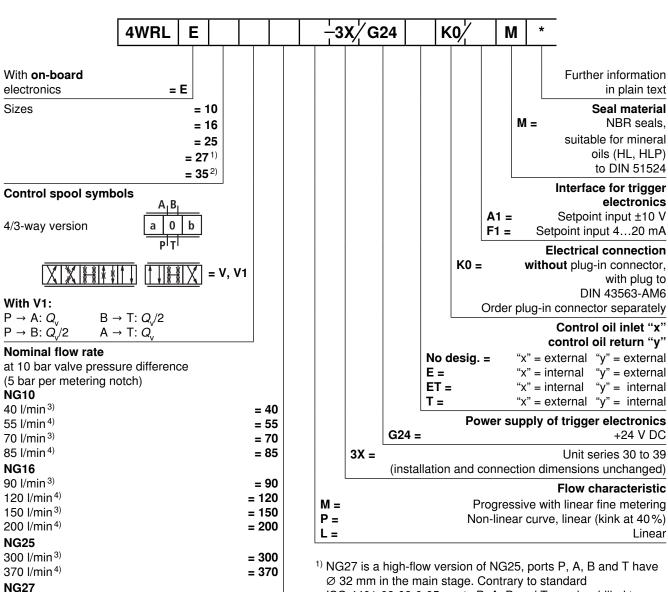
For information regarding the available spare parts see: www.boschrexroth.com/spc

#### **Ordering data**

430 l/min 1)4)

1000 l/min<sup>2)4)</sup>

NG35

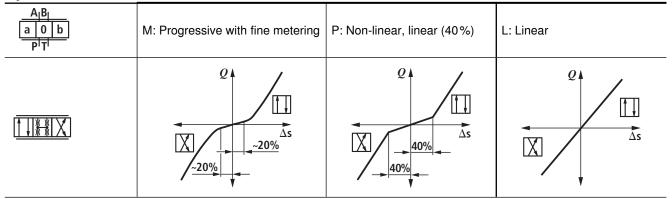


= 430

= 1000

- $^{1)}$  NG27 is a high-flow version of NG25, ports P, A, B and T have  $\varnothing$  32 mm in the main stage. Contrary to standard ISO 4401-08-08-0-05, ports P, A, B and T may be drilled to max.  $\varnothing$  30 mm in the control block. These valves therefore offer higher flow rates  $Q_{\rm A}$ :  $Q_{\rm R}$
- $^{2)}$  NG35 is a high-flow version of NG32, ports P, A, B and T have  $\varnothing$  50 mm in the main stage. Contrary to standard ISO 4401-10-09-0-05, ports P, A, B and T may be drilled to max.  $\varnothing$  48 mm in the control block. These valves therefore offer higher flow rates  $Q_{\rm A}$ :  $Q_{\rm B}$
- <sup>3)</sup>  $Q_N$ : Flow characteristic "P"
- <sup>4)</sup>  $Q_N$ : Flow characteristic "M" or "L"

#### **Symbols**



### Testing and service equipment

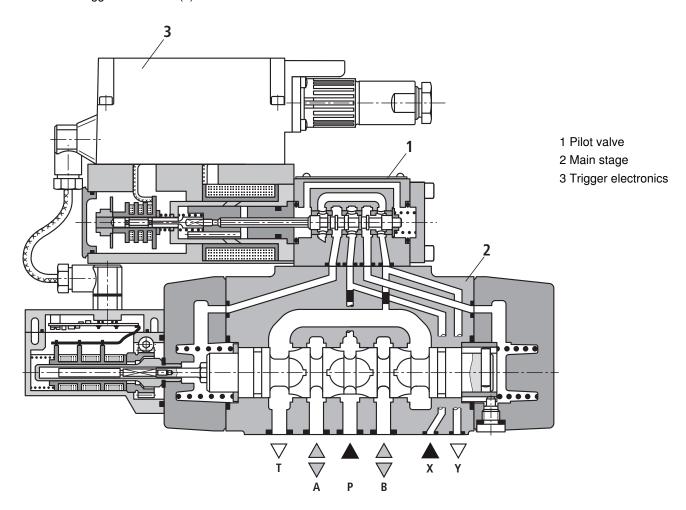
- Service case type VT-VETSY-1 with test device, see data sheet 29685
- Measuring adapter 6P+PE type VT-PA-2, see data sheet 30068

#### Function, sectional diagram

#### Construction

The valve consists of three main assemblies:

- Pilot valve (1) with control spool and sleeve, return springs, control solenoid and inductive position transducer
- Main stage (2) with centering springs and position feedback
- On-board trigger electronics (3)



#### **Functional description**

spool to mid position.

spool is held by springs in the fail-safe position, and the main stage spool remains in spring-centered offset position at 1...6% of the stroke in the direction P-B/A-T. In the on-board electronics, the pre-defined setpoint is compared with the actual value for the position of the main stage control spool. In the event of an error signal, the control solenoid is actuated, and the pilot spool is moved as the magnetic force changes. The flow released through the control cross-sections causes the main control spool to move. The stroke/control cross-section of the main control spool is controlled proportionately to the setpoint. If the input

When the control solenoid is not actuated, the control

The control oil is conveyed to the pilot valve either internally via port P or externally via port X. The oil returns to the tank internally via port T or externally via port Y.

setpoint is 0 V, the electronics move the main stage control

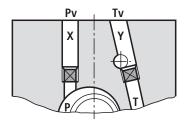
#### Power failure

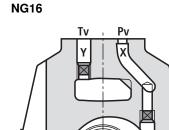
In the event of a power failure or an open circuit, the on-board electronics cut off the electricity to the control solenoid and the pilot spool moves to the fail-safe position, relieving the control oil chambers of the main stage. The main stage control spool is held by springs in the offset position.

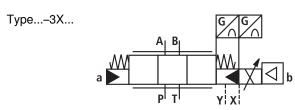
#### **Control oil supply**

The pilot valve can be supplied both via ports X and Y (externally) and via the main flow channels P and T.

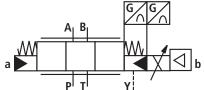
NG10, 25, 27, 35



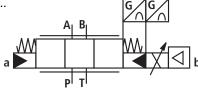




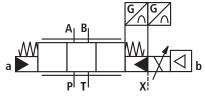
Type...-3X...E...



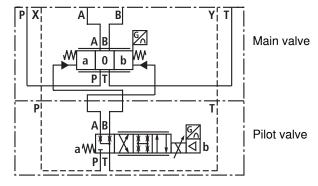
Type...-3X...ET...



Type...-3X...T...



Symbol in detail (external control oil inlet and outlet)



No designation =

x = external x = internal

"y" = external

E = ET = T =

x = internal "x" = external "y" = external = internal = internal

#### **Important**

Hydraulic symbols are largely derived from the symbols of the switching valves. 4/3-way servo solenoid directional control valves (pilot operated) do not have a closed mid position when switched off! They only perform their function in an active, closed control loop, even if the pilot valve features a fail-safe 4th position. See technical data for details on "switch-off behavior".

#### **Technical data**

General							
Construction		Spool type valve, pilot operated					
Actuation		Servo solenoid directional control valve NG6 OBE, with position controller for pilot valve and main stage					
Type of mounting		Subplate, mounting hole configuration NG1035 to ISO 4401					
Installation position		Optional					
Ambient temperature range °C		-20+50					
Weight	kg	NG10	8.7	<b>NG16</b> 10.6	<b>NG25</b> 18.4	<b>NG27</b> 18.4	NG35 81
Vibration resistance, test co	ndition	Max. 2	5 <i>g</i> , shal	ken in 3 dimensio	ons (24 h)		
Hydraulic (measured v	with HLP 46	6, ϑ <sub>oil</sub> =	= 40 °C	±5 °C)			
Pressure fluid	Hydraulic oil to DIN 51524535, other fluids after prior consultation						
Viscosity range recommend	20100						
max. permi	10800						
Pressure fluid temperature r	-20+70						
Maximum permissible degree of contamination of pressure fluid Purity class to ISO 4406 (c)		Class 18/16/13 <sup>1)</sup>					
Flow direction	See symbol						
Nominal flow at		NO	G10	NG16	NG25	NG27	NG35
$\Delta p = 5$ bar per notch <sup>2)</sup>	l/min	40 55	70 85	90 120 150 200	300 370	430	1000
Max. Ports P, A, B working External control oil inlet bar pressure Ports P, A, B Internal control oil inlet bar		3	50	350	350	280	350
		250					
Ports T, X, Y	250						
Min. control oil pressure in "pilot stage" bar		10					
$Q_{max}$	l/min		70	450	900	1000	3500
Q <sub>N</sub> pilot valve	$Q_{\rm N}$ pilot valve I/min		4	12	24	24	40
Nominal flow of pilot valve at 100 bar	cm <sup>3</sup> /min	<1	180	<300	< 500	< 500	<900
Nominal flow of main stage at 100 bar	cm <sup>3</sup> /min	<400	<600	<1000	<1000	<1000	< 6000
Static/Dynamic							
Hysteresis %		<0.1, scarcely measurable					
Manufacturing tolerance for	Q <sub>max</sub> %	≦10					
Response time for signal	0100%	25		26	32	32	90
change (at X = 100 bar)	010%	1	14	15	18	18	40
Response time for signal	0100%	85		80	120	120	350
change (at X = 10 bar)	010%	5	50 30 50 50			150	
Switch-off behavior		After electrical switch-off: Pilot valve in fail-safe Main stage moves to spring-centered "offset position": 16% P-B/A-T					
Thermal drift		Zero point displacement <1% at ΔT = 40 °C					
Zero adjustment		Factor	y-set ±1	%			

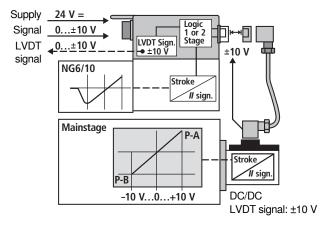
<sup>1)</sup> The purity classes stated for the components must be complied with in hydraulic systems. Effective filtration prevents problems and also extends the service life of components. For a selection of filters, see www.boschrexroth.com/filter.

<sup>&</sup>lt;sup>2)</sup> Flow rate at a different  $\Delta p$   $Q_x = Q_{nom} \cdot \sqrt{\frac{\Delta p_x}{35}}$ 

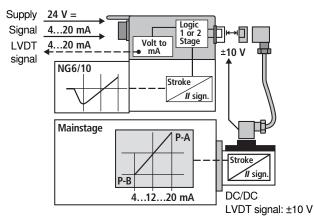
#### **Technical data**

Electric pilot valve NG6, trigger electronics integrated in the valve				
Cyclic duration factor %	100 ED			
Degree of protection	IP 65 to EN 60529 and IEC 14434/5			
Connection	Plug-in connector 6P+PE, DIN 43563			
Power supply Terminal A: Terminal B: 0 V	24 V DC <sub>nom</sub> min. 21 V DC/max. 40 V DC Ripple max. 2 V DC			
Max. power consumption	40 VA			
External fuse	2,5 A <sub>F</sub>			
Input, "Standard" version Terminal D: $U_{\rm E}$ Terminal E:	Differential amplifier, $R_{\rm i}$ = 100 k $\Omega$ 0 ±10 V 0 V			
Input, "mA signal" version Terminal D: I <sub>D-E</sub> Terminal E: I <sub>D-E</sub>	Burden, $R$ sh = 200 $\Omega$ 4(12)20 mA Current loop $I_{D-E}$ feedback			
Max. differential input voltage at 0 V	$ \begin{bmatrix} D \to B \\ E \to B \end{bmatrix} $ max. 18 V DC			
Test signal, "Standard" version Terminal F: <i>U</i> <sub>Test</sub> Terminal C:	LVDT 0±10 V Reference 0 V			
Test signal, "mA signal" version Terminal F: $I_{\rm F-C}$ Terminal C: $I_{\rm F-C}$	LVDT signal 420 mA at external load 200500 $\Omega$ max. 420 mA output Current loop $I_{\rm F-C}$ feedback			
Protective conductor and screen	See pin assignment (CE-compliant installation)			
Calibration	Calibrated at the factory, see valve characteristic curve			
Electromagnetic compatibility tested according to	EN 61000-6-2: 2005-08 EN 61000-6-3: 2007-01			

#### **Version A1: Standard**



#### Version F1: mA signal

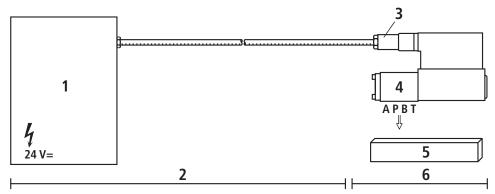


#### Important

Pilot operated 4/3-way servo solenoid directional control valves only perform their function in an active closed control loop and do not have a fail-safe position when switched off. For this reason, many applications require the use of "external check valves", which must be taken into account during the On/Off switching sequence.

#### **Electric connection**

For electrical data, see page 7



- 1 Control
- 2 Provided by customer
- 3 Plug-in connector
- 4 Valve
- 5 Connecting surface
- 6 Provided by Rexroth

#### Technical notes on the cable

Version: - Multi-wire cable

> - Extra-finely stranded wire to VDE 0295, Class 6

- Protective conductor, green/yellow

- Cu braided screen

Types: - e.g. Ölflex-FD 855 CP

(from Lappkabel company)

No. of wires: - Determined by type of valve,

plug types and signal assignment

- 0.75 mm<sup>2</sup> to 20 m length Cable Ø:

1.0 mm<sup>2</sup> to 40 m length

Outside Ø: - 9.4...11.8 mm - Pg11

12.7...13.5 mm - Pg16

Voltage supply 24 V  $\rm DC_{\rm nom.}$ , if voltage drops below 18 V DC, rapid shutdown resembling

"Enable OFF" takes place internally.

In addition, with the "mA signal" version:

 $I_{D-E} \ge 3 \,\text{mA} - \text{valve is active}$ 

 $I_{D-E} \le 2 \text{ mA} - \text{valve is deactivated.}$ 

Electrical signals emitted via the trigger electronics

(e.g. actual values) must not be used to shut down safety-

relevant machine functions!

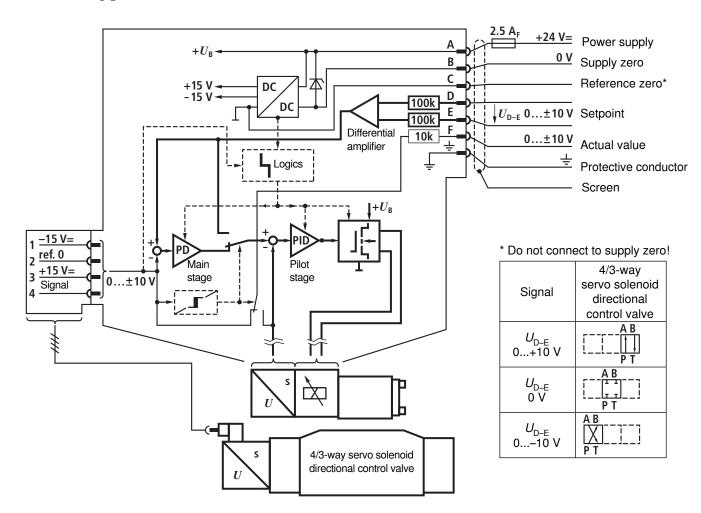
(See European Standard, "Technical Safety Requirements for Fluid-Powered Systems and Components - Hydraulics",

EN 982.)

#### **On-board electronics**

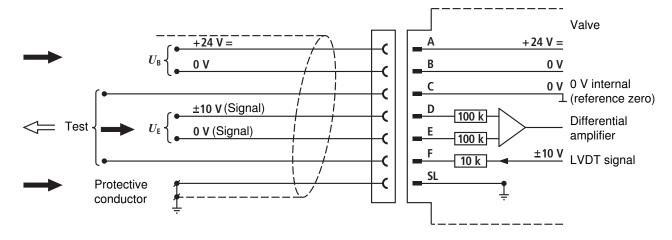
#### Block diagram/pin assignment

Version A1:  $U_{\rm D-E}$  ±10 V



#### Pin assignment 6P+PE

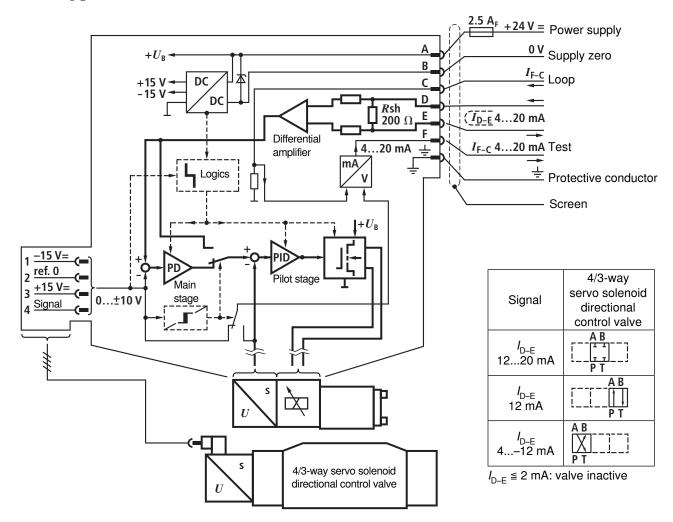
Version A1:  $U_{\rm D-E}$  ±10 V ( $R_{\rm i}$  = 100 k $\Omega$ )



#### **On-board electronics**

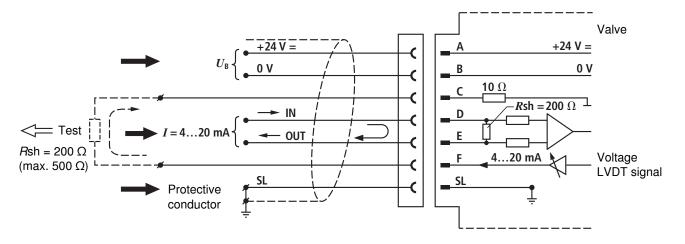
#### Block diagram/pin assignment

Version F1:  $I_{D-E}$  4...12...20 mA



#### Pin assignment 6P+PE

Version F1:  $I_{\rm D-E}$  4...12...20 mA (Rsh = 200  $\Omega$ )

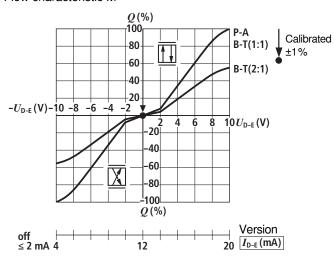


# **Characteristic curves** (measured with HLP 46, $\vartheta_{oil}$ = 40 °C±5 °C)

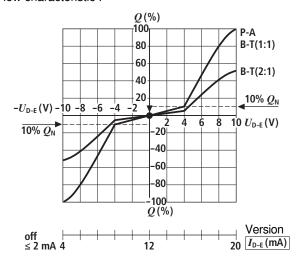
Flow rate - signal function

$$Q = f(U_{D-E})$$
  
 $Q = f(I_{D-E})$ 

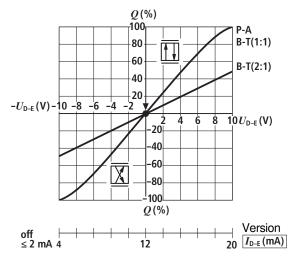
Flow characteristic M



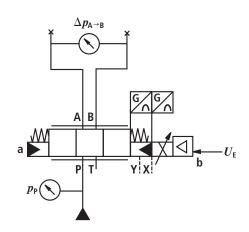
Flow characteristic P

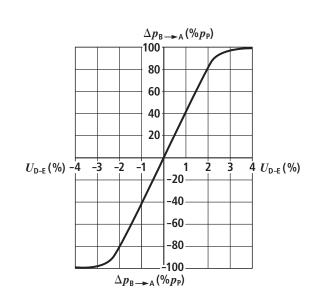


Flow characteristic L



#### Pressure gain

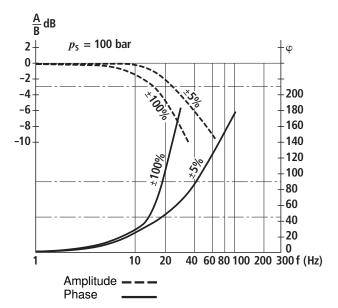




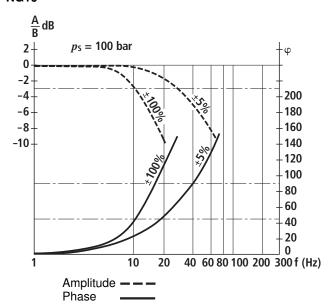
# Characteristic curves (measured with HLP 46, $\vartheta_{oil}$ = 40 °C ±5 °C)

#### **Bode diagram**

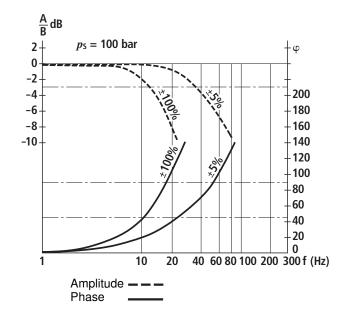
#### **NG10**



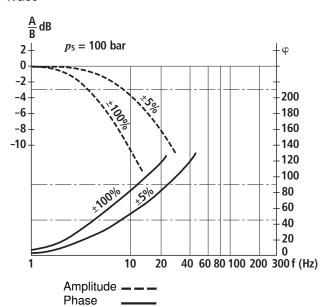
#### **NG16**



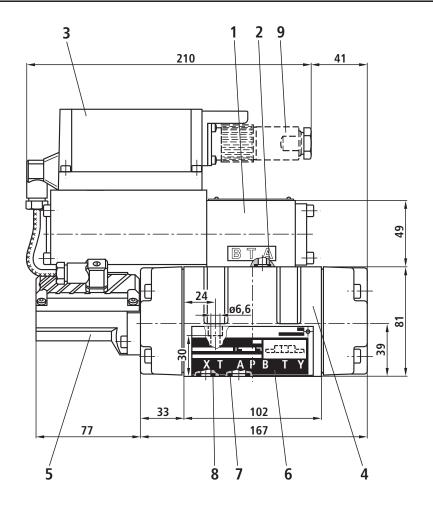
#### NG25/27

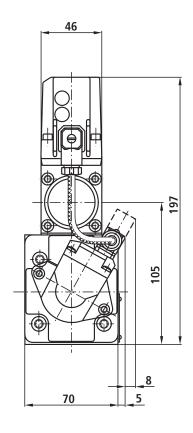


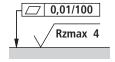
#### NG35



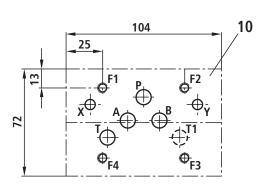
#### Unit dimensions NG10 (dimensions in mm)







Required surface quality of valve mounting face



- 1 Pilot valve
- 2 O-ring 9.25 x 1.78 (ports P, A, B, T)
- 3 On-board electronics
- 4 Main valve
- 5 Inductive position transducer (main valve)
- 6 Nameplate
- 7 O-ring 12 x 2 (ports P, A, B, T, T1)
- 8 O-ring 10 x 2 (ports X, Y)

- **9** Plug-in connector not included in delivery, see data sheet 08008 (order separately)
- 10 Machined valve contact surface, mounting hole configuration according to ISO 4401-05-05-0-05

Deviates from standard:

Ports P, A, B, T, T1 Ø 10.5 mm

Minimum thread depth: Ferrous metal 1.5 x  $\varnothing$ 

Non-ferrous 2 x Ø

Subplates, see data sheet 45055 (order separately)

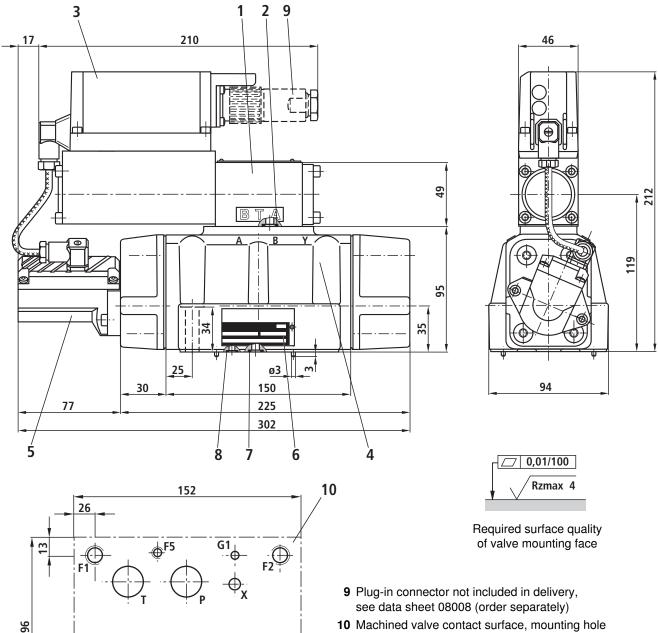
Valve fastening bolts (order separately)

The following valve fastening bolts are recommended:

**4 cheese-head bolts ISO 4762-M6x40-10.9-N67F82170** (galvanized in accordance with Bosch standard N67F82170)

Tightening torque  $M_A = 11+3 \text{ Nm}$ 

#### Unit dimensions NG16 (dimensions in mm)



- 1 Pilot valve
- 2 O-ring 9.25 x 1.78 (ports P, A, B, T)
- 3 On-board electronics
- 4 Main valve
- 5 Inductive position transducer (main valve)
- 6 Nameplate
- 7 O-ring 23 x 2.5 (ports P, A, B, T)
- 8 O-ring 9 x 2 (ports X, Y)

10 Machined valve contact surface, mounting hole configuration according to ISO 4401-07-07-0-05 Deviates from standard: Ports P, A, B, T Ø 20 mm
Minimum through doubth: Foregue motal 1.5 x Ø

Minimum thread depth: Ferrous metal 1.5 x  $\varnothing$ Non-ferrous 2 x  $\varnothing$ 

**Subplates**, see data sheet 45057 (order separately)

Valve fastening bolts (order separately)

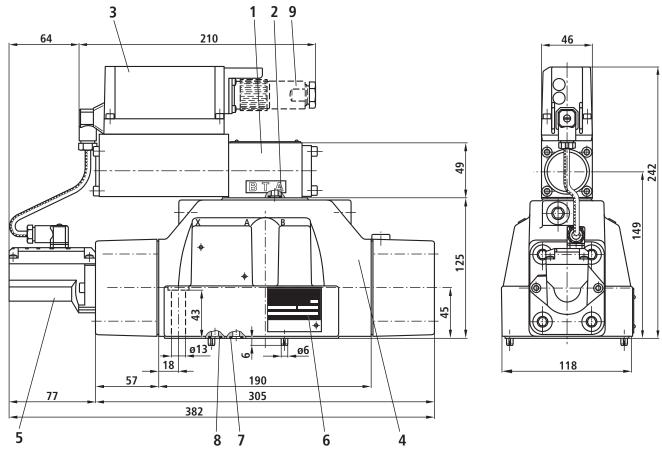
The following valve fastening bolts are recommended:

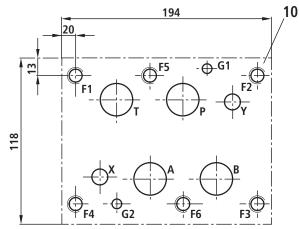
2 cheese-head bolts ISO 4762-M6x45-10.9-N67F82170 (galvanized in accordance with Bosch standard N67F82170) Tightening torque  $M_{\rm A}$  = 11+3 Nm

Material no. 2910151211

**4 cheese-head bolts ISO 4762-M10x50-10.9-N67F82170** (galvanized in accordance with Bosch standard N67F82170) Tightening torque  $M_{\rm A}=50+10~{\rm Nm}$ 

#### Unit dimensions NG25/27 (dimensions in mm)





**\_\_\_\_\_ 0,01/100** Rzmax 4

Required surface quality of valve mounting face

- 1 Pilot valve
- 2 O-ring 9.25 x 1.78 (ports P, A, B, T)
- 3 On-board electronics
- 4 Main valve
- 5 Inductive position transducer (main valve)
- 6 Nameplate
- 7 O-ring (ports P, A, B, T)

NG25: 28 x 3 NG27: 34.6 x 2.62

8 O-ring 15 x 2.5 (ports X, Y)

- 9 Plug-in connector not included in delivery, see data sheet 08008 (order separately)
- 10 Machined valve contact surface, mounting hole configuration according to ISO 4401-08-08-0-05

Deviates from standard:

NG25: Ports P, A, B, T  $\varnothing$  25 mm

NG27: Ports P, A, B, T Ø 32 mm

Minimum thread depth: Ferrous metal 1.5 x Ø

Non-ferrous 2 x Ø

**Subplates**, see data sheet 45059 (order separately)

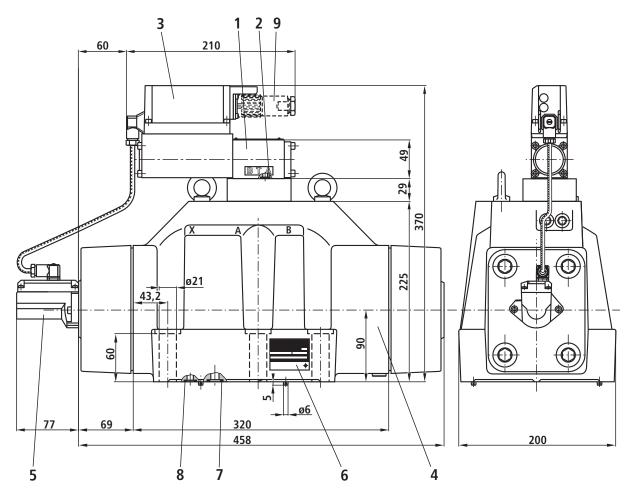
Valve fastening bolts (order separately)

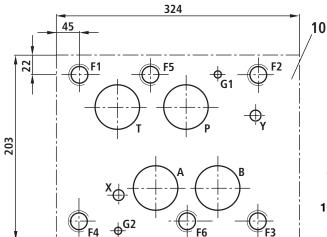
The following valve fastening bolts are recommended:

6 cheese-head bolts ISO 4762-M12x60-10.9-N67F82170 (galvanized in accordance with Bosch standard N67F82170)

Tightening torque NG25  $M_A$  = 90+30 Nm, NG27  $M_A$  = 90±15 Nm

#### Unit dimensions NG35 (dimensions in mm)





0,01/100 Rzmax 4

Required surface quality of valve mounting face

- 1 Pilot valve
- 2 O-ring 9.25 x 1.78 (ports P, A, B, T)
- 3 On-board electronics
- 4 Main valve
- 5 Inductive position transducer (main valve)
- 6 Nameplate
- **7** O-ring 53.57 x 3.53 (ports P, A, B, T)
- 8 O-ring 15 x 2.5 (ports X, Y)

- 9 Plug-in connector not included in delivery, see data sheet 08008 (order separately)
- 10 Machined valve contact surface, mounting hole configuration according to ISO 4401-10-09-0-05 Deviates from standard:

Ports P, A, B, T Ø 48 mm

Minimum thread depth: Ferrous metal 1.5 x Ø Non-ferrous 2 x Ø

Subplates, see data sheet 45060 (order separately)

Valve fastening bolts (order separately)

The following valve fastening bolts are recommended:

6 cheese-head bolts ISO 4762-M20x90-10.9-N67F82170 (galvanized in accordance with Bosch standard N67F821 70)

Tightening torque  $M_A = 450+110 \text{ Nm}$ 

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