## MICRO-CONTROLLER X Type : PXF-2 Operation Manual

## PLEASE READ FIRST

Please read the section "Safety Warnings" thoroughly before using. Safety precautions must be taken by every user to prevent accidents. Failure to comply with the instructions contained in this manual may reduce the safety of the instrument.
The safety requirements are classified into "Warning" and "Caution" according to the following interpretations:

| $\lfloor$ WWARNING | Mishandling may lead to serious injury or death. |
| :--- | :--- |
| $\Delta$ CAUTION | Mishandling may result in personal injury or damage to the <br> property. |

## $\triangle$ WARNING

## Installation and wiring

- This equipment is intended to be used under the following conditions.

| Ambient temperature | -10 to $50^{\circ} \mathrm{C}$ |
| :--- | :--- |
| Operating humidity | $90 \% \mathrm{RH}$ or less (Non condensation) |
| Installation category: | II |
| Pollution degree: | 2 |
| Recommended fuse | $250 \mathrm{~V} \mathrm{AC}, 0.1 \mathrm{~A} \mathrm{T(Time-Lag)} \mathrm{(AC100~240V)}$ |
|  | $400 \mathrm{~V} \mathrm{DC} / 400 \mathrm{~V} \mathrm{AC}, 1 \mathrm{~A} \mathrm{T(Time-Lag)} \mathrm{(DC/AC24V)}$ |
| Usage environment | Indoor use |

- If accessible Safety Extra Low Voltage (SELV) circuits are to be connected to Signal input terminal, SSR drive output terminal, Current output terminal or Communication (RS485) terminal, ensure to provide a basic insulation between the SELV circuits and these terminals. For example, use transformer which has a basic insulation or higher degree of insulation.
If accessible Safety Extra Low Voltage (SELV) circuits are to be connected to Communication (RS-485) terminal, be sure to provide a basic insulation between these terminals. For example, use a RS-485/232 converter which has a basic insulation. The basic insulation requires a clearance at least 1.5 mm and a creepage of at least 3.0 mm . Failure to maintain these minimum distances would invalidate the UL61010/EN61010 safety approval.
- For 24 V DC/AC power supply model, if the equipment is connected to the Safety Extra Low Voltage (SELV) circuit, a basic insulation must be provided between the SELV circuit and the power input terminals.
Otherwise, the power input terminals must be connect to Extra Low Voltage (ELV) circuit so as to prevent the electric shock.
- For CT input, use Current Transfer which has specification as shown below in order to prevent the electric shock and spread of fire.

| 1) Over Voltage Category | II |
| :--- | :--- |
| 2) Pollution Degree | 2 |
| 3) Required level of Insulating | BASIC INSULATION, SUPPLYMENTARY INSULATION, or |
| 4) Maximum Voltage line to neutral | REINFORCED INSULATION |

## About safety standard

Please observe the following instructions to meet the requirements of safety standard. Failure to observe these instructions violates safety standards.
(This product is not safety equipment.)

- Install a recommended fuse, which is specified in the instruction manual, between the external main power (Mains Circuit) and this equipment.
- Do not connect SELV directly to Signal input terminal, SSR Drive output terminal, Current output terminal, or Communication (RS-485) terminal. Otherwise, it may result in electrical shock.
If accessible Safety Extra Low Voltage (SELV) circuits are to be connected to Signal input terminal, SSR Drive output terminal, Current output terminal or Communication (RS-485) terminal, ensure to provide a basic insulation between the SELV circuits and these terminals. For example, use transformer which has a basic insulation or higher degree of insulation.
If accessible Safety Extra Low Voltage (SELV) circuits are to be connected to Communication (RS-485) terminal, be sure to provide a basic insulation between these terminals
For example, use a RS-485/232 converter which has a basic insulation.
The basic insulation requires a clearance at least 1.5 mm and a creepage of at least 3.0 mm .
- Be sure to install an appropriate external protective circuit to prevent excessive temperature rise etc.
- When performing wiring work, be sure to turn the power off and to wear protection gloves or safety glasses, to prevent an electric shock.
- Set proper parameter input signals which correspond to each input to be connected.

Be careful not to confuse voltage input with current input, or vice versa.

- Do not use this equipment for the measurement of circuits which falls under measurement categories II, III, or IV.
- Do not use this equipment for measurement of signals to which a voltage over $30 \mathrm{Vr} . \mathrm{m} . \mathrm{s}$. or over 60 V DC is applied.
- Be sure to use terminal covers. Before removing a terminal cover, turn off all the power.
$\rightarrow$ For the above, if voltage exceeds 50 Vdc (called danger voltage), grounding and basic insulation for all terminals of the equipment and auxiliary insulation for DO outputs are required.
Note that the insulation class for this equipment is as follows. Before installing, please confirm that the insulation class for equipment meets usage requirements.

Type PXF4


Type PXF5/9


- In cases where damage or problems with this equipment may lead to serious accidents, install appropriate external protective circuits.
- As this equipment does not have a power switch or fuses, install them separately as necessary. If you install a fuse, be sure to place it between the main power switch and this equipment.
(Main power switch: 2-point Breaker, fuse rating: 250V 1A)
- A power switch or a circuit breaker should be installed within the power supply facility.
- A power switch or a circuit breaker should be properly installed within easy reach of an operator.
- A power switch or a circuit breaker should be identified as the one for this product.
- Electrical wiring must be made by the qualified personnel only and in accordance with your local and national standards.
- For power supply wiring, use wire equal to 600 V vinyl insulation or above.
- To prevent damage and failure of the equipment, provide the rated power voltage.
- To prevent shock and equipment failure, do not turn the power ON until all wiring is complete.
- Before feeding power, confirm that clearance space has been secured to prevent shock and fire with the equipment.
- Do not touch the terminal while the machine is on. Doing so risks shock or equipment errors.
- Never disassemble, convert, modify or repair this equipment. Doing so carries the risk of abnormal operation, shock and fire.
- Output relays has limited-life. The contact of output relay may stay ON or OFF when it reaches the end of its service life. Be sure to provide an external protective circuit for safety.
- The factory default setting of this equipment is as follows. Change the setting as necessary so as the equipment to meet your application.
Please note that the improper settings may result in overheat or unexpected damage. For the details of operation, read this manual.

Control output 1: heating control
Control output 2 (optional): cooling control
Digital input 1 to 5 (optional): no function

- Symbols on the equipment

Please read this instruction manual thoroughly, and use the product accordingly.

## Maintenance

- When installing and removing the equipment, turn the power OFF. Failing to do so may cause shock operational errors or failures.
- Periodic maintenance is recommended for continuous and safe use of this equipment.
- Some components used on this equipment have a limited life and/or may deteriorate over time.
- The warranty period for this unit (including accessories) is three year after the date of manufacture, if the product is used properly.


## Cautions on installation

Avoid the following places for installation:

- A place where the ambient temperature may reach beyond the range of from 0 to $50^{\circ} \mathrm{C}$ while in operation.
- A place with rapid temperature changes, leading to dew condensation
- A place where corrosive gases (sulfide gas and ammonia gas, in particular) or combustible gases are emitted.
- A place with vibration or shock directly. (Vibration and shock may cause output relay malfunction.)
- A place exposed to water, oil, chemicals, steam and/or vapor.
(If the equipment gets wet, there is a risk of electric shock or fire, so have it inspected by the distributor.)
- A place where the unit is exposed to dust, salt air, or air containing iron particles.
- A place where the unit is subject to interference with static electricity, magnetism, and noise.
- A place where the unit is exposed to direct sunlight.
- A place where the heat may be accumulated due to the radiation of heat.

Recommended site condition:

- A place where the ambient humidity during operation is between 45 to $85 \% \mathrm{RH}$.

> About EMC standard
> - This equipment is designed as Class A (for industrial environment). Do not use this equipment in home environment, or it may cause electric jamming. If you use this equipment in home environment, install appropriate measures on the outside of the equipment.
> - Under the requirement of EMC standard, the maximum length of a sensor to be connected to this equipment is 30 m . Do not connect the sensor longer than 30 m .

## Caution on installation on panel

- Attach the included Fixtures (2 pieces) onto the top and bottom of PXF5/9, and tighten them with a screwdriver. The clamp torque is approx. $0.15 \mathrm{~N} \cdot \mathrm{~m}(1.5 \mathrm{~kg} \cdot \mathrm{~cm})$ The plastic fixture is designed such that over tightening will cause left/right cracking to the central area of the Fixtures and hence reduce the torque. Cracking to the central area will not cause any problems in terms of usability of the equipment as is.
(However, do exercise caution in not applying too much torque because the casing is made of plastic.)
- The front of this equipment is waterproof in compliance with NEMA-4X standards (IP66-equivalent). However, regarding waterproofing between the equipment and the panel, use the included packing to ensure waterproofing and attach it according to the guidelines below. (Incorrect attachment may cause the equipment to lose its waterproof capabilities.)
(1)As shown in Fig. 1, insert the panel after attaching the packing to the equipment case.
(2)As shown in Fig. 2, tighten the fixture screws so that no gaps can remain between the equipment face, the packing and the panels. Once finished, confirm that there are no changes in shape such as displaced or improperly-fitted packing, etc. as shown in Fig. 3.
- Please exercise caution if the panel strength is weak and gaps develop between the packing and the panel, as this will result in the loss of its waterproofing capabilities.

Fig. 1


Fig. 2


Fig. 3



Mounting on vertical plane (in horizontal position)

## PXF5/9

Fig. 1


Fig. 2


Fig. 3


Mounting on vertical plane (in horizontal position)

## Caution

- In order not to hamper heat radiation, do not block the sides of the equipment.
- Do not block the air vents on the upper part of the terminal.
- For PXF9, please attach the Fixtures to the attachment holes in the center of the main unit.


## Cautions on wiring

- For thermocouple input, use the designated compensation lead; for resistance temperature sensors, use wires with small lead wire resistance and without any resistance difference among the three wires.
- To avoid noise conductor effects, do not use input signal wires in close proximity with electric power lines or load lines.
- Use the input signal lines and output signal lines that are separated from each other and are shielded.
- If there is a lot of noise from the power source, adding an insulation transducer and using a noise filter is recommended. Always attach a noise filter to a panel that is grounded securely, and keep the wiring between the noise filter output side and the measuring equipment power terminal wiring to a minimum length. Please do not attach fuses and switches, etc. to the noise filter output wiring since doing so will decrease the filter's effectiveness.
- Twisting the measuring instrument wiring is effective when connecting the wires. (The shorter the pitch of the twist, the more effective the connection is against noise.)
- When the power is turned on, it takes some time before a contact output starts operation. If using it as a signal to an external interlock circuit, please couple it with a delayed relay.
Concerning the output relay, connecting the maximum rated load will shorten the relay's life; so please attach an auxiliary relay. If the output operation frequency is high, selecting a SSR drive output type is recommended.
[Proportional cycles] Relay output: 30 seconds or more, SSR drive output: 1 second or more


PXF5/9
(Example)


PXF4

- When inductive loads such as magnetic opening/closing equipment, etc. as relay output equipment are connected, use of a serge absorber is recommended in order to protect the connection points against opening/closing surges and to ensure long-term use.

Recommended specification for surge absorber

| Voltage | Nominal varistor voltage |
| :--- | :--- |
| 100 V | 240 V |
| 200 V | 470 V |

## Key Operation Cautions/Error Operations

- The alarm function does not work properly when an error takes place unless the settings are made correctly. Always verify its setting before operation.
- If the input wiring breaks, the display will read "UUUU" or "LLLL". When replacing the sensor, always turn the power OFF.


## Others

- Do not wipe the equipment with organic solvents such as alcohol or benzene, etc. If wiping is necessary, use a neutral cleaning agent.
- Do not use mobile phones near the instrument (within 50 cm ). Otherwise malfunction may occur.
- Trouble may occur if the equipment is used near a radio, TV, or wireless device.
- Do not turn off the power right after you change the setting. If you turn off the power after setting change, be sure to wait for a few seconds before turning it off, so that the changed values can be stored on the nonvolatile memory.


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## For Proper Use

| Confirmation of model code | Please confirm that the model delivered matches your order. "Model Specifications" (page 10) |
| :---: | :---: |
| 1 |  |
| Installation and Mounting | External dimensions <br> -Panel cutout <br> - Panel mounting dimensions <br> "3 Installation and Mounting" (instruction manual) |
| 1 |  |
| Wiring | Terminal connection diagram "4 Wiring" (instruction manual) |
| $\pm 1$ |  |
| Power ON |  |
| $\square$ |  |
| Display and Operations | Changing set value |
| Parameters List | Basic operations |
| Functions of the | Parameters List |
| Temperature Controller | Parameter setting |
|  | "2-1 Basic operation" (page 19) |
|  | "2-2 Changing SV (set value)" (page 20) |
|  | "3-2 CH1 PID (Control parameters) " (page 41) |
| 1 |  |
| Advanced Usage | Setting of input sensor and input range |
|  | Selecting control method |
|  | Controlling through auto-tuning |
|  | Parameter setting |
|  | "3-7 CH6 SET (Setup parameters)" (page 114) |
|  | "3-2 CH1 PID (Control parameters)" (page 41) |
|  | "AT Auto tuning (005)" (page 33) |
|  | "(4) Self tuning control (SELF) (3) Fuzzy control (FUZY)" (page 151) |
|  |  |
| Operation |  |
| $\underline{L}$ |  |
| Error Indications | Display during equipment error "4 TROUBLESHOOTING" (page 197) |

Wait 30 minutes for the controller to be stabilized thermally. Operations such as measurements should be started after the equipment has been energized at least for 30 minutes.

## Model Specifications

<PXF4>
<48×48mm size>
PXF4 Standard Model List


Note 1: Not available for the 7th code "C", "E", "P", "R", "S".
However, if you want to order the 6th code "A" (SPST relay contact for the control output 1) and the 7th code "R" or "S" (current/voltage re-transmission output for the control output 2), specify the model as follows:
PXF4AA $\frac{R}{S}$ 2-पロप02
Note 2: When using the CT input as a heater burnout alarm, add one alarm output for it in the 9th code.
Note 3: When using the current input for the remote SV input, add a 250 -ohm resistor to the input terminal.
<48 $\times 48 \mathrm{~mm}$ size>
Motorized Valve Control Model List



Note 1: When using the CT input as a heater burnout alarm, add one alarm output for it. (Add one point in the 9th code.) Note 2: When a current input is used, a resistance of $250 \Omega$ is required at the input terminal.

Motorized Valve Control Model List



## 1

## Part names and functions

This section describes the names and functions of each part of the front panel. The front panel has the PV and SV displays, the status indicator lamps, and the setting keys, etc. Their functions are explained below. Please read and understand them before using the PXF.
For details about the setting of parameters, see Chapter 2.
<PXF4>


USER key

- Press this key once in PV/SV display to switch between SV display and MV display.
- Press and hold this key in PV/SV display to start the assigned function. (No function is allocated at the factory.)
- Press this key once in operation control mode, channelselection mode, or setup mode to return to PV/SV display.
SEL key
- Press this key once in PV/SV display to move to operation control mode.
- Press and hold this key in setup mode to move to channel selection mode.
- Press this key once in channel selection mode to move to setup mode.
- Press and hold this key in setup mode to move to channel selection mode.
- Press this key once in parameter selection submode of setup mode to enter parameter editing submode.
- Press this key once in parameter editing submode to save the change and return to parameter selection submode.
< key
- Use the this key to select the digit when changing values.
v^ key
- Use the this key to change SV value when in PV/SV screen.
- During in operation control mode, channel selection mode, or setup mode, this key allows you to change parameters to be displayed.
- During in parameter setting mode, this key allows you to change parameter settings.

Indicators

(1) Indicates process value (PV)

Shows parameter name when in parameter setting.
(2) Set point (SV)

Shows set value. Shows parameter set point when in parameter setting.
(3) Screen No.

Shows screen No. when in parameter setting.
(4) OUT1 indicator

Lights during control output 1 is ON.
(5) OUT2 indicator

Lights during control output 2 is ON .
(6) EV 1, EV 2, EV 3 indicators

Lights during digital output 1 to 3 are ON.
(7) STBY indicator

Lights during standby.
(8) MANU indicator

Lights during manual mode.
(9) Lock indicator

Lights during key lock.
(10) No. indicator

Lights during a screen No. is displayed.
(11) RUN/HOLD/END indicators

Lights during ramp/soak operation.
(12) AT indicator

Lights during auto tuning.
(13) MV indicator

Lights during MV is displayed on SV display.
$(14)^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{F}$ indicator
Shows the temperature unit under use.

USER + ^ key

- Press and hold this key in PV/SV display to start the assigned function.
(The factory set function for this key is switching between RUN and standby.)
USER + v key
- Press and hold this key in PV/SV display to start the assigned function.
(The factory set function for this key is switching between start/stop of auto-tuning.)
(15) A, \%, kW/h indicator

Shows the unit being applied to values on SV display during the operation mode.

## <PXF5/9>



## USER key

- Press this key once in PV/SV display to switch between SV display and MV display.
- Press and hold this key in PV/SV display to start the assigned function. (No function is allocated at the factory.)
- Press this key once in operation control mode, channelselection mode, or setup mode to return to PV/SV display.
SEL key
- Press this key once in PV/SV display to move to operation control mode.
- Press and hold this key in setup mode to move to channel selection mode.
- Press this key once in channel selection mode to move to setup mode.
- Press and hold this key in setup mode to move to channel selection mode.
- Press this key once in parameter selection submode of setup mode to enter parameter editing submode.
- Press this key once in parameter editing submode to save the change and return to parameter selection submode.
< key
- Use the this key to select the digit when changing values.
v^ key
- Use the this key to change SV value when in PV/SV screen.
- During in operation control mode, channel selection mode, or setup mode, this key allows you to change parameters to be displayed.
- During in parameter setting mode, this key allows you to change parameter settings.


## Indicators

PXF5


PXF9

(1) Indicates process value (PV)

Shows parameter name when in parameter setting.
(2) Set point (SV)

Shows set value. Shows parameter set point when in parameter setting.
(3) Screen No.

Shows screen No. when in parameter setting.
(4) OUT1 indicator

Lights during control output 1 is ON .
(5) OUT2 indicator

Lights during control output 2 is ON .
(6) EV 1, EV 2, EV 3 indicators

Lights during digital output 1 to 3 are ON.
(7) STBY indicator

Lights during standby.
(8) MANU indicator

Lights during manual mode.
(9) Lock indicator

Lights during key lock.
(10) No. indicator

Lights during a screen No. is displayed.
(11) RUN/HOLD/END indicators

Lights during ramp/soak operation.
(12) AT indicator

Lights during auto tuning.
(13) MV indicator

Lights during MV is displayed on SV display.
(14) ${ }^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{F}$ indicator

Shows the temperature unit under use.

## USER + ^ key

- Press and hold this key in PV/SV display to start the assigned function.
(The factory set function for this key is switching between RUN and standby.)
USER + v key
- Press and hold this key in PV/SV display to start the assigned function.
(The factory set function for this key is switching between start/stop of auto-tuning.)
(15) A, \%, kW/h indicator

Shows the unit being applied to values on SV display during the operation mode.
(16) Bar graph Shows MV.

## 1-1 Digital characters

The following tables provide correspondence between digital characters used for the display of the controller and alphanumerical characters. (See the following table for details.)

| Alphabet | Digital characte | Alphabet | Digital characte | Alphabet | Digital characte |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A | П | K | 17 | U | 4 |
| B | 6 | L | $L$ | V | $\\|^{\prime \prime}$ |
| C | $L$ | M | M | W | in |
| D | $d$ | N | Niv | X | $\checkmark$ |
| E | $E$ | O | 0 | Y | 3 |
| F | $F$ | P | $\square$ | Z | - |
| G | 5 | Q | - |  |  |
| H | $H$ | R | $\square$ |  |  |
| I | $\bar{L}$ | S | 5 |  |  |
| J | - | T | $L$ |  |  |


| Number characte | Digital characte | Number characte | Digital characte |
| :---: | :---: | :---: | :---: |
| 1 | 1 | 6 | $\square$ |
| 2 | 7 | 7 | 7 |
| 3 | 7 | 8 | $\square$ |
| 4 | 4 | 9 | $\square$ |
| 5 | 5 | 0 | $\square$ |

## 2 Basic Operation

## 2-1 Basic operation

The below figure illustrates the mode transition and the key operations.


## Operation mode

In this mode the normal operation is performed. The process value (PV) and the set value (SV) are displayed. The device starts in this mode when you turn on the power. You can change the set value (SV) in this mode. You can check the output value (MV) and the amount of electric power by switching the screen.

## Operation control mode

In this mode you can put the device to standby or change the alarm set value.

## Channel selection mode

In this mode you can select the parameter channel to be displayed.

## Setup mode

In this mode you can setup each parameter. This mode includes the parameter selection submode and the parameter editing submode, which can be switched by SEL key. In the parameter selection submode, you can switch between parameters by using $\wedge \vee$ keys. In the parameter editing submode, you can change parameter values by using $\wedge \vee$ keys.

## 2-2 Changing SV (set value)

## [Description]

- The SV is a target value for control.
- SV must be within the range between SVL (lower limit) and SVH (upper limit) which belong to Pid parameter.
Related parameters: SVL (page 50), SVH (page 50)
[Setting example] Changing the SV from $250^{\circ} \mathrm{C}$ to $1195^{\circ} \mathrm{C}$



## 2-3 Parameters List

The following explains each channel parameter.

- The range of the parameters in the shaded area indicates the industrial values. When you change the PV input lower limit (Pvb), PV input upper limit (PvF), or decimal place position (Pvd), reconfigure all the industrial values.
- When the parameter that has [RESET] on its Remarks column is changed, turn off the power once, and then re-start the controller.

| Operation control parameter |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Parameter |  |  | Function | Setting range | Initial value | Remarks |
| No | Display | Name |  |  |  |  |
| 001 | MRA | Switchover between auto and manual mode | Switchover between auto and manual modes | OFF (auto) / on(manual) | ofF | This parameter is not displayed in default setting. If you need to change this parameter, change the setting of "Ch11 dSP' so that it appears. |
| 002 | Stb ${ }^{\text {ch }}$ | Switchover between RUN and standby | Switchover the operation mode betwsen RUN and standby | ofF(RUN) / on(standty) | OFF |  |
| 003 | REM | Localiremote switchover | Swiches SV between localremote. | LOCL (local) / REM (remote) | LoCL |  |
| 004 | Proú | Ramp soak control command | Changes ramp soak run states | OFF (stop)rUn (run) hid (hold) | OFF | Displays End (when ending) or GS (during guaranty soak). |
| 005 | At | Auto-tuning run command | Runs auto-tuning. | ofF (stop/finish)on (normal type)Lo (low PV type) | dFF |  |
| 006 | LACH | Alarm output latch release command | Cancels the alarm output latch state | oFF / rST (latch resels) | ofF |  |
| 007 | 5\%'H | SV selection | Chooses the SV No. used for control |  | LoCL | When changing the SV with the front key, do not change the "Svi" parameter via communication. Otherwise, the changed SV may not be stored correcty: |
| 008 | PL M | PID selection | Chooses the PID No. used for contral | LoCL (PID ch) <br> Pid 1 (PID group No. 1) <br> Pid 2 (PID group No. 2) <br> Pid 3 (PID group No. 3) <br> Pld 4 (PID group No. 4 ) Pid 5 (PID group No. 5 ) <br> Pid 5 (PID group No. 5 ) <br> Pid 7 (PID group No. 7 ) <br> बi (chooses PID group according to DI) | LoCL |  |
| 009 | Al I |  | Sets the alarm value for ALM1. | Absolute value alarm: 0 to $100 \%$ FS Devition alam: - 100 to 10 CO FS | 2.50\%FS |  |
| 010 | AI-L | ALM1 set value |  |  |  |  |
| 011 | Al-H |  |  |  |  |  |
| 012 | ALC |  | Sets the alarm value for ALM2. | Absolute value alarm: 0 to $100 \%$ FS | 2.50\%FS |  |
| 013 | $\mathrm{AL}^{2}-1$ | ALM2 set value |  |  |  |  |
| 014 | $\mathrm{AL}^{2}-\mathrm{H}$ |  |  |  |  |  |
| 015 | AL 3 |  | Sets the alarm value for ALM3. | Absolute value alarm: 0 to $100 \% \mathrm{FS}$ Deviation alarmi -100 to 10CH FS | 2.50\%FS |  |
| 016 | A3-L | ALM3 set value |  |  |  |  |
| 017 | A3-H |  |  |  |  |  |
| 018 | AL4 |  | Sets the alarm value for ALM4. | Absolute value alarm: 0 to $100 \% \mathrm{FS}$ | 2.50\% FS |  |
| 019 | A4-L | ALM4 set value |  |  |  |  |
| 020 | R4-H |  |  |  |  |  |
| 021 | ALS |  | Sets the alarm value for ALM5. | Absolute value alarm: 0 to $100 \%$ FS | 2.50\%FS |  |
| 022 | A5-L | ALM5 set value |  |  |  |  |
| 023 | A5-H |  |  |  |  |  |
| 027 | LLMd | Electric power calculation command | Switches among onioftihold of electre power calculation. | ofF (stop calculation) run (run calculation) hld (suspend calculation) | ofF |  |
| 028 | Lol | Key lock | Sets the key lock to prevent wrong ojeration | ofF (no lock) <br> ALL (all lock) <br> PArA (All but SV locked) | ofF |  |



Note 1: "SVL" and "SVH" must be set so that SvL < Svh. When you change the values for "SVL" and "SVH", check SV1 ("Sv1 Ch2") through SV 7 ("Sv7 Ch2").

Ch2 PLT (PID palette parameters)

| Parameter |  |  | Function | Setting range | Initial value | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Ne | Display | Name |  |  |  |  |
| 100 | 5\% 1 | sv1 | Sets the SV (set value) | SV limit (lower)(SVL) to SV limit (upper)(SVH) \%FS | 0\%FS | Note 1) |
| 101 | PI | Proportional band 1 (\%) | Sets the proportional band. | 0.1 to $999.9 \%$ | 5.0\% |  |
| 102 | il | Integration time 1 | Sets the integration time. | 0 to 3200 sec | 240 sec |  |
| 103 | d! | Differential time 1 | Sets the differential time. | 0.0 to 999.9 sec | 60.0 sec |  |
| 104 | HYS I | ONVOFF control hysteresis 1 | Sets the hysteresis when using the ONOOFF control. | 0 to 50\%ms | 0.25\%FS |  |
| 105 | [ol 1 | Cooling proportional band 1 (\%) | Selts the cooling proportional band. | 0.0 to 100.0 | 1.0 |  |
| 106 | dbl | Dead band 1 (\%) | Sets the dead band | -50.0 to 50.0\% | 0.0\% |  |
| 107 | bril I | Output convergence value 1 (\%) | Offset value which is added to the control output | -100.0 to 100.0\% | O/50 (single/dual) |  |
| 108 | RR I | Ant-reset windup 1 | Sets the ant-reset windup | 0 to 100\%FS | 100\%\%FS |  |
| 109 | REI I | Normalireverse 1 | Selects single control or dual control. Sels the control action (normal or reverse) | rv- (heat (reverse)/cool (none)) no- (heat (normaly cool (none)) <br>  rvve (heat (reverse) icool (reverse)) nono (heat (normal) cool (normai)) | $\underset{\text { (single/dual) }}{\text { rv-ivno }}$ | Note 2) [RESET] |
| - | : | : | : | : |  |  |
| 160 | 5\%7 | SV7 | Sets the SV (set value) | SV limit (lower)(SVL) to SV limia (upper)(SVH) \%FS | 0\%FS | Note 1) |
| 161 | P7 | Proportional band 7 (\%) | Sets the proportional band. | 0.1 to 999.9\% | 5.0\% |  |
| 162 | -7 | Integration time 7 | Sets the integration time. | 0 to 3200 sec | 240 sec |  |
| 163 | $d^{17}$ | Differential time 7 | Sets the differential time. | 0.0 to 999.9 sec | 60.0 sec |  |
| 164 | HYS7 | ONOFF control hysteresis 7 | Sets the hysteresis when using the ON/OFF control. | 0 to 50\%.FS | 0.25\%FS |  |
| 165 | [ol7 | Cooling proportional band 7 (\%) | Sets the cooling proportional band. | 0.0 to 100.0 | 1.0 |  |
| 168 | db7 | Dead band 7 (\%) | Sets the dead band | -50.0 to 50.0\% | 0.0\% |  |
| 167 | bRL? | Output corvergence value 7 (\%) | Offset value which is added to the control output | -100.0 to 100.0\% | Q/50 (single/dual) |  |
| 168 | RPI | Ant-reset windup 7 | Sets the ant-reset windup | $010100 \%$ FS | 100\%.FS |  |
| 169 | REVI | Norma/reverse 7 | Selects single control or dual control. Sets the control action (normal or reverse). | rv- (heat (reverse)/cool (none)) no-(heat (normal) cool (none)) runo (heat (reverse) cool (nommal)) norv (heat (normal) Ycool (reverse) rviv (heat (reverse)/cool (reverse)) nono (heat (normal)cool (normal)) | $\begin{gathered} \text { rv-i/ivno } \\ \text { (singleidual) } \end{gathered}$ | Note 2) [RESET] |
| 170 | REF I | PID switching point 1 | Sets the PID switching point for palette 1. | $010100 \%$ FS | 0\%FS |  |
| : | . | . | $:$ |  |  |  |
| 176 | REFT | PID switching point 7 | Sets the PID switching point for palette 7. | 0t0 100\%Fs | 0\%FS |  |
| 177 | 5VM' | Max SV selection number | Choosing SV with the user key sets it to the maximum possible number. |  | Sv7 |  |
| 178 | PL Mim | Max PID selection number | Choosing PID with the user key sets it to the maximum possible number. |  | Pid7 |  |

Note 1: "SvL" and "Svh" must be set so that SvL < Svh. When you change the values for "SvL" and "Svh", check SV1 ("Sv1 Ch2") through SV 7 ("Sv7 Ch2"). Note 2: Set the same value as the one for the Norma//Reverse setting ('rEv Ch1").

## Ch 3 PRG（ramp soak parameters）

| Parameter |  |  | Function | Setting range | Initial value | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Ne | Display | Name |  |  |  |  |
| 200 | PtN | Ramp soak operation pattem（Step No．） | Sets which steps to use in the ramp soak operation pattern |  | 14 | Note 1） |
| 201 | どNUU | Ramp soak time units | Sets the units of the ramp soak time | hh．MM（hour．min） MM．SS（min：sec） | hh．MM |  |
| 202 | $5 t^{\prime \prime}-1$ | Ramp soak 1 seg／sV 1 | Sets the SV | 0 to 100\％${ }^{\text {a }}$ S | 0\％FS |  |
| 203 | EHIR | Ramp soak 1 seg ramp time | Sets the ramp time． | 00：00 to 99：59 （hourminimincsec） | 00：00 |  |
| 204 | LH 15 | Ramp soak 1 seg soak time | Sels the soak time． | 00：00 to 99：59 （hour－min／min：sec） | 00：00 |  |
| 205 | $5 y^{\prime \prime}-2$ | Ramp soak 2 seg／SV 2 | Sets the SV | 0 to 100\％FS | 0\％FS |  |
| 206 | EMER | Ramp soak 2 seg ramp time | Sets the ramp time． | $\begin{aligned} & \text { 00:00 to 99:59 } \\ & \text { (hour:min/min:sec) } \end{aligned}$ | 00：00 |  |
|  | ： |  | ： |  | : | : |
| 389 | E63P | Ramp soak 63 seg ramp time | Sets the ramp time． | 00：00 to 99：59 （hour．min／min＇sec） | 00：00 |  |
| 390 | t635 | Ramp soak 63 seg soak time | Sets the soak time． | 00：00 to 99：59 （hour．min／min：sec） | 00：00 |  |
| 391 | 51654 | Ramp soak 64 seg／SV 64 | Sets the SV | 0 to 100\％Fs | 0\％FS |  |
| 392 | E54P | Ramp soak 64 seg ramp time | Sets the ramp time． | 00：00 to 99：59 （hour：min／min sec） | 00：00 |  |
| 393 | $t 645$ | Ramp soak 64 seg soak time | Sets the soakk time． | $\begin{array}{\|l\|} \hline \text { OD:00 to } 99: 59 \\ \text { (hour:min/min:sec) } \end{array}$ | 00：00 |  |
| 394 | Mod | Ramp soak mode | Sets the program operation method | 0 to 15 | 0 |  |
| 395 | E50H | Guaranty soak ONOFF | Sets the guaranty soak ON or OFF | ofF（guaranty soak off） on（guaranty soak on） | OFF |  |
| 396 | L5－L | Guaranty soak band（Lower） | Sets the lower limit of guaranty soak | 0 to 50\％FS | 1．25\％FS |  |
| 397 | U5－H | Guaranty soak band（Upper） | Sets the upper limit of guaranty soak | 0 to 50\％．FS | 1．25\％FS |  |
| 398 | PVSt | PV start | Sets whether or not to starr ramp soak with PV． | ofF（PV start off） on（PV start on） | OFF |  |
| 399 | ［o咾 | Restore mode | Sets how to restart when the controler is restored atter a power loss． | rES（Reset） Con（Continue） ini（Restart） | rES |  |
| 400 | Pt開 | Max pattern selection | Sets the maximum pattern number selectable by using the user key． | 0 to 14 | 14 |  |
| 401 | PM ${ }^{-1 / N}$ | Min pattern selection | Sets the minimum pattern number selectable by using the user key． | 0 10 14 | 0 |  |

Note 1：Do not change this parameter during the ramp soak operation．Be sure to set＂PRG＂$=$＂oFF＂before changing the parameter

Ch 4 MON (monitor parameters)

| Parametor |  |  | Function | Setting range | Initial value | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Ne | Display | Name |  |  |  |  |
| 420 | Stht | Ramp soak progess | Displays the progess of the ramp soak |  | - |  |
|  |  |  |  |  End (ramp soak finished) |  |  |
| 421 | M $\mathrm{Ma}^{\prime \prime}$ | MVI(\%) | Displays the output value of the control output (OUT1) | -5.0 to 105.0\% | - |  |
| 422 | Miv | NV2(\%) | Displays the output value of the control output (OUT2) | -5.0 to 105.0\% | - |  |
| 423 | PFb | PfB input value (\%) | Displays the postion feedback input value. | -10.0 10 110.0\% | - |  |
| 424 | R5\% | Remote SV | Shows a remote SV. | 500 105\%Fs | - |  |
| 425 | [t] | Heater current ( $\mathcal{A}$ ) | Shows a heater current value. (A current value when OUT1 is ON .) | 010110.0 A | - |  |
| 427 | [[] | SSR leak curront (A) | Shows a leak current value. (A current value when OUT1 is OFF.) | 010110.0 A | - |  |
| 429 | LMI | Remaining time on timer 1 | Displays the remaining time on timer 1 | 0 to 9999 seed 0 to 9999 min | - |  |
| 430 | tMc | Remaning time on timer 2 | Displays the remaining time on timer 2 | 0 10 $9999 \mathrm{sec} / 0$ to 9999 min | - |  |
| 431 | LM ${ }^{\text {S }}$ | Remaning time on timer 3 | Displays the remaining time on timer 3 | 0109999 sec 0 0 009999 min | - |  |
| 432 | LTM | Remaining time on timer 4 | Displays ter remarining bime on tmer 4 | 0109999 sec 010 t 9999 min | - |  |
| 433 | LMS | Remairing time on timer 5 | Displays the remaining time on timer 5 | 0 10 9999 sec 00 to 9999 min | - |  |
| 435 | [ой | Communication status | Displays the commurication status. | 0 to 9999 times (number of communication times) | - |  |
| 436 | CURI | Current (A) | Shows a value measured by CT. | 010110.0 A | - |  |
| 438 | Poll | Electric power | Shows a calulated amount of electric power. | 0.0 to 9999 KW | - |  |
| 439 | HWH | Power | Displays the calculated amount of electric power. | 0.0 to 999.9 Wh | - |  |
| 440 | RCNI | Number of opetating times (control relay <br> 1) | Displayes the number of times that control relay 1 has operated. | 0 to 9990k times | - |  |
| 441 | RLMz | Number of opetating times (control relay 2) | Displayes the number of times that control relay 2 has operated. | 0 to 9999k times | - |  |
| 442 | Runt | Operating days | Displays the number of days oparated, converted from total operating time. | 0105000 days | - |  |
| 443 | FRilt | Error source | Displays the source of an error | 0 bit: PV input underflow (LLLL) <br> 2 bit: PV underrange <br> 3 bit: PV overrange <br> 4 bit: RSV underrange <br> 5 bit: RSV overrange <br> 6 bit: Range setting error <br> 8 bit: PV input circuit error <br> 9 bit: R-SV input circuit error 10 bit CT/PFB input circuit error 11 bit PFB input underrange <br> 12 bit: PFB input overrange | - |  |
| 444 | di | Di inpuit stue | Displays he state of D. | $\begin{aligned} & \text { Oba Dit } \\ & 1 \text { ba } \mathrm{Dl\mid} \\ & 2 \mathrm{bat} \\ & \hline \end{aligned}$ | - |  |
| 445 | ERSt | Commurication error station number | Shows the station number under a cooperative communicaton error or a programless communication error | 11031 | - |  |
| 446 | Pl/Ho | Carrent PIO No. | Displays the currently used PID number. | 0107 | - |  |
| 447 | Ptilo | Current patiern No . | Displays the ramp soak pateern number being used. | 01015 | - |  |

Ch 5 ALM (alarm parameters)

| Parameter |  |  | Function | Setting range |  | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| No | Display | Name |  |  | Initial value |  |
| 470 | A it $P$ | ALM1 alarm type | Set the alarm type for ALM1. | 0 to 47 | 0 | Refer to section 11 for the detail. |
| 471 | A IHY | ALM1 hysteresis | Sets the hysteresis for alarm output 1 ON/OFF | 0 10 50\%.FS | 0.25\%Fs |  |
| 472 | dLyl | ALM1 delay | Sets the delay before detecting alarm output 1 | 0 to 9999 [secimin] | 0 |  |
| 473 | dl IU | ALM1 delay time units | Sets the delay time units for alarm output 1 | sec (second)/Min (minute) | sec |  |
| 474 | Ropl | ALM1 option function | Assigns the optional functions to ALM1 <br> Ones digit alarm output latch <br> Tens digt: error alarm <br> Hundreds digit inverted output Thousands digit: hold tesel <br> hold resel | 0000 to 1111 | 0000 |  |
| : | : |  |  |  |  |  |
| 490 | RSt $P$ | ALM5 alarm type | Set the alarm type for ALM5. | 0 10 58 | 0 | Refer to section 11 for the detail. |
| 491 | RSHY | ALM5 hysteresis | Sets the hysteresis for alarm output 5 ON/OFF | 0 10 50\%6FS | 0.25\%FS |  |
| 492 | dl 45 | ALM 5 delay | Sets the delay before detecting alarm output 5 | 0 to 9999[sedmin] | 0 |  |
| 493 | dLSU | ALM5 delay time units | Sets the delay time unit for alarm output 5 | sec (second) Min (minute) | sec |  |
| 494 | RopS | ALM5 option | Assigns the optional functions to ALM5 Ones digit alarm output latch Tens digit: efror alarm Hundreds digit inverted output Thousands digit: hold reset | 0000 to 1111 | 0000 |  |
| 500 | Hbl | HB alarm set value | Sets the value to activate the heater burnout alarm. | 0.0 to 100.0 (A) | 0.0A |  |
| 501 | Hb IH | HB alarm hysteresis | Sets an ON/OFF hysteresis for the heater burnout alarm. | 0.0 to 100.0 (A) | 0.5 A |  |
| 502 | H51 | Shorted-load alarm set value | Sets the value to activate the shorted load alarm. | 0.0 to 100.0 ( A$)$ | 0.0 A |  |
| 503 | HS IH | Shorted-load alarm hysteresis | Sets an ON/OFF hysteresis for the shorted heater-load alarm. | 0.0 to 100.0 (A) | 0.5 A |  |
| 508 | LbEM | Loop break detection time | Sets the time before detecting a broken loop | 0 to 9999 sec | 0 (OII) |  |
| 509 | LbAb | Loop break detector detection range ( ${ }^{\circ} \mathrm{C}$ ) | Sets the temperature range before detecting a broken loop | 0.0 to 100.0\%\%FS | 2.50\% FS |  |
| 511 | WHRL | Electricity alarm setpoint | Sets the value for electricity alarm. | 0-9999kWh | 0 |  |


| CH 6 SET (setup parameters) |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Parametor |  |  | Function | Setting range | Initial value | Remarks |
| № | Display | Name |  |  |  |  |
| 530 | PV't | PV input type | Sets the type of input sensor | JPT1: 0.0 to $150.0^{\circ} \mathrm{C}$ <br> $\mathrm{JPT} 2: 0.0$ to $300.0^{\circ} \mathrm{C}$ $\mathrm{JPT} 3: 0.0$ to $500.0^{\circ} \mathrm{C}$ <br> JPT4: 00 to $6000^{\circ} \mathrm{C}$ <br> JPT5: -50.0 to $100.0^{\circ} \mathrm{C}$ <br> JPT6 <br> 100.0 to <br> JPTV:-199.9 $9080000^{\circ} \mathrm{C}$ <br> PT1: $0.010150 .0^{\circ} \mathrm{C}$ <br> PT2:0.0 $10300.0^{\circ} \mathrm{C}$ <br> PT4: 0.010 10 $600.00^{\circ} \mathrm{C}$ <br> PT5: - 50.0 to $100.0^{\circ} \mathrm{C}$ <br> PT6: 100.0 to $200.0^{\circ} \mathrm{C}$ <br> PT7: -100.9 to $600.0^{\circ} \mathrm{C}$ <br> PT8. -200 to $850^{\circ} \mathrm{C}$ <br> $\mathrm{H}=0.0$ to $400.0^{\circ} \mathrm{C}$ $\mathrm{J}=-20.0$ to $40.0 \mathrm{O}^{\circ} \mathrm{C}$ <br> J3: 0.0 to $8000^{\circ} \mathrm{C}$ <br> J4: -100 to $1000^{\circ \prime} \mathrm{C}$ <br> K1:0 to $400^{\circ} \mathrm{C}$ <br> K2. 20.0 to $500.0^{\circ} \mathrm{C}$ <br> $\mathrm{K3}: 0.0$ to $80000^{\circ} \mathrm{C}$ $\mathrm{K} 4-200$ t 1300 C <br> R. $0.201700^{\circ} \mathrm{C}$ <br> B: 0 to $1800^{\circ} \mathrm{C}$ <br> STI:-199.9 to $200.00^{\circ} \mathrm{C}$ <br> PT2:-199.9 to $400.0^{\circ} \mathrm{C}$ <br> E1:00 to $740.0^{\circ} \mathrm{C}$ <br> E2: -150.0 to $740.0^{\circ} \mathrm{C}$ <br> -100 to $850^{\circ} \mathrm{C}$ <br> Ui: -199.9 to $400.0^{\circ} \mathrm{C}$ <br> U 2 <br> $\mathrm{~N},-200$ to $20.400^{\circ} \mathrm{C}$ <br> C <br> $\mathrm{N}-200$ to $1300^{\circ}$ $\mathrm{W} \cdot \mathrm{O}$ to $2300^{\circ} \mathrm{C}$ <br> $\mathrm{PL}-2: 0$ to $1300^{\circ} \mathrm{C}$ <br> $0-5 \mathrm{~V} .0$ to 5 V <br> 1.5. 1 to 5 V $0-10: 0$ to 10 V <br> 2-10:210 10 V <br> MV: 0 to 100 mV <br> 0-20:0 to 20 mA $4-20: 4$ to 20 mA | K1 | [RESET] <br> Refer to section 10 for the detail. |
| 531 | PVb | PV input lower limit | Sets the lower limit of PV input | -1999 to 9999 | 0 | [RESET] |
| 532 | PVF | PV input upper Imit | Sets the upper limit of PV input | -1999 to 9999 | 400 | [RESET] |
| 533 | Pid | Decimal point position | Sets the decimal point position for the PV/sV | 0 : No digit atter decimal point <br> 1: 1 digit affer decimal point <br> 2. 2 digit after decimal point 3: 3 digit after decimal point | 0 | [RESET] |
| 534 | PV' | Unit | Unit | ${ }^{\circ} \mathrm{C}$ and ${ }^{\circ} \mathrm{F}$ |  |  |
| 535 | [ LUE | Square-root extractor cut point | Selt the cut point for square roct calculation. | -0.1 to 105.0(\%) | -0.1\% |  |
| 536 | PVof | PV input shif | Sets the amount of shiff for PV Input | -10 to 10\%Fs | $0.00 \%$ \% 5 |  |
| 537 | 5\% ${ }^{\circ}$ | SV shift | Sets fre amourt of shiff for PV irput. | . 50 to 50\% FS | 0.00\% |  |
| 538 | tF | PV input filter | Sets the time constant for the PV input fiter | 0.0 to 120.0 sec | 5.0 sec |  |
| 539 | Adul | PV display zero adiusiment | Adjusts zero side of PV display. | -50 to 50\%FS | 0.00\%FS |  |
| 540 | Adu5 | PV display span adjustment | Adjusts span side of PV display. | . 50 to 50\% Fs | 0.00\%FS |  |
| 541 | R[J | Cold junction compensation | Sets on/off of cold junction compensation. | $\begin{array}{\|l\|} \hline \text { ofF } \\ \text { on } \\ \hline \end{array}$ | $\mathrm{o}^{\mathrm{N}}$ |  |
| 543 | REMO | Remote SV zero adjusment | Adjusts the zero side of the remote SV input. | -50 to 50\% Fs | 0.00\%FS |  |
| 544 | REMS | Remote SV span adjustment | Adjusts the span side of the remole SVirput. | -50 to 50\%Fs | 0.00\%FS |  |
| 545 | REMP | Remote SV input range | Sets the range for remote SV irput. | $0.5 \mathrm{v}: 0$ to 5 V 1-5V: 1 to 5 V $0-10: 0$ to 10 V <br> 2-10:2 to 10 V | 1.5 V |  |
| 545 | R[U | Remote SV input filier | Sets fre fime constart for the RSV input filer | 0.0 to 120.0 sec | 0.0 s |  |
| 547 | $[18$ | OUT1 range | Sets the range of the control output 1(OUT1) | $0-5 \mathrm{v}: 0$ to 5 V <br> 1-5v: 1 to 5 V <br> $0-10.0$ to 10 V <br> $2-10: 2$ to 10 V <br> $0-20: 0$ to 20 mA <br> 4-20:4 to 20 mA | $\begin{aligned} & 0-10 \text { (voltage) } \\ & 4-20 \text { (current) } \end{aligned}$ | Displayed when the control output 1 is current or voitage output. |
| 54 B | [2P | OUT2 range | Sets the range of the control oupput 2(OUT2) | $0-5 \mathrm{v}$ : 0 to 5 V <br> 1-5V: 1 to 5 V <br> $0-10: 0$ to 10 V <br> 2-10: 2 to 10 V <br> D-20: 0 to 20 mA <br> $4-20: 4$ to 20 mA | $\begin{aligned} & 0-10 \text { (voltage) } \\ & 4-20 \text { (current) } \end{aligned}$ | Displayed when the control output 2 is current or voltage output. |
| 549 | Flal | MV1 during FALT | Sets the output value for the control output (MV1) during FALT | -5.0 to 105.0\% | -5.0\% |  |
| 550 | Fla? | MV2 during FALT | Sets the output value for the control output (MV2) during FALT | -5.0 to 105.0\% | -5.0\% |  |
| 551 | SFal | Mvi during Sott Star | Sets the value for the control output (MV1) during sot start | -5.0 t0 105.0\% | 105.0\% |  |
| 553 | 5FEM | Soff Start set time | Sets the time from startup to the finish of soff start | 00:00 to 98:59 (hour.min) | 00:00 | Be sure to set 0.00 during dual control. |
| 554 | 5601 | MV1 during standby | Sets the value tor the control output (MV1) during standby | -5.0 to 105.0\% | -5.0\% |  |
| 555 | 5602 | MV2 during standby | Sets the value for the control output (MV2) during standby | -5.0 to 105.0\% | -5.0\% |  |
| 556 | 5bidd | Standby mode | Sets onvoff of the alarm output during standey | 0: $A L M=O F F, A O=O N$ <br> 1. $A L M=O N, A O=O N$ 2. $A L M=O F F, A O=O F F$ <br> 3. $\mathrm{ALM}=\mathrm{ON}, \mathrm{AO}=\mathrm{OFF}$ | 0 | [RESET] |
| 557 | Rok | AO output tpe | Selects what to transfer to the analog output. | $\begin{aligned} & \text { PV } \\ & \text { SV } \\ & \text { MV } \\ & \text { DV } \\ & \text { PFb } \end{aligned}$ | PV |  |
| 558 | Rol | AO lower scaling | Sets the AO lower scaling | -100.0 to 100.0\% | 0.0\% |  |
| 559 | RoH | AO upper scaling | Sets the $A O$ upper scaling | -100.0 to 100.0\% | 100.0\% |  |
| 561 | Volt | Fixed voltage value | Sets the vollage for calculating electric power | 160500 V | 100 (100 V) |  |
| 562 | [UR | Current value for simple power calculation | Sets the current value for simple power calculation | 0.0 to 100.0A | 0 (0.0A) |  |
| 563 | -M゙N | Eleetric eurrent nulificaton point | Sets the value that the values below which are nullifed before power calculation. <br> The set value or below are treated as null in calculation. | 0.010100 .0 A | 0 (0.0A) |  |
| 564 | WdP | Decial point posstion for electric power | Sets the position of decimal point for calculationed power consumption. | $\begin{aligned} & 0: 0 \\ & 1: 0.1 \\ & 2: 0.01 \\ & 3: 0.001 \end{aligned}$ | 1:0.1 | Do not change it during calculation. |
| 565 | PHY | Power factor for simple calculation | Sets the power factor for simple calculation | 0.00101 .00 | 1.00 |  |
| 566 | RYCN | Upper limit of relay contact operation | Sets the upper limit on the number of times a relay contact can operate. If you set it to 0 , no alarm will be generated. | 0109999 | 10 (10K times) |  |
| 587 | OPEH | Upper limit of operating days | Sets the upper limit on the number of days the device operates. If you set it to 0 , no alarm will be generated. | 0 to 5000 | 3650 (3850 days) |  |

Ch 7 SYS（system parameters）

| Parametor |  |  | Function | Setting range | Initial value | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Ne | Display | USER key Name | Assions the tunction to the［USER］key | 0 to 27 |  |  |
|  |  |  |  |  |  | Reter |
| 591 | UKY？ | USER＋UP key | Assigns the function to the［USER］$+\wedge$ key | 06027 | 5 |  |
| 592 | UKY | USER－DOWN key | Assigns the function to the［USER］+V key | 01027 | 1 |  |
| 593 | díl | D－1 Anction | Allocates a Anction to D－1． | $0-48$ | 0 | Refer to section 14 for the detal． |
| 594 | dic | D＋2 2 tuction | Alocates a finction to D－ 2 ． | 0－48 | 0 |  |
| 595 | di ${ }^{3}$ | Di．3 finction | Allocates a finction to D1．3． | 048 | 0 |  |
| 596 | di＇4 | D14 function | Allocates a function to DIP4． | 0.48 | 0 |  |
| 597 | dis | D－5 function | Alocates a function to D－5． | 048 | 0 |  |
| 599 | ollt | OUT1 output type | Selects the content to be output trom OUT1 | 010427 | 1 | Refer to section 13 for the detall． |
| 600 | oluet | OUT2 output type | Selects the content to be output from OUT2 | 010427 | 2 |  |
| 601 | dolt | D01 output type | Selects the content to be output from DO1． | 0 06427 | 3 |  |
| 602 | doct | DO2 output type | Selects the content to be output from DO2 | 010427 | 4 |  |
| 603 | do3t | DO3 outpur type | Selects the content to be outpu from DO3． | 010427 | 5 |  |
| 604 | do4t | D04 outpur type | Selects the content to be oupua from DO4． | 010427 | 6 |  |
| 605 | do5t | DO5 output typ | Selects tre content to be output from DO5． | 010427 | 7 |  |
| 607 | Loll 1 | LED indicator assignment（OUT1） | Selects the content for OUT1 to indicate． | 010427 | 1 |  |
| 608 | Loll | LED indicator assignment（OUT2） | Selects the content tor OUT2 to indicate． | 010427 | 2 |  |
| 609 | LEF＇ | LED indicator assionment（Ev1） | Selects the content for EV1 lamp to indicate． | 010427 | 3 |  |
| 610 | LEV？ | LED indicator assionment（EV2） | Selects the content for EV2 lamp to indicate． | 06427 | 4 |  |
| 611 | LEF3 | LED indicator assionment（Ev3） | Selects the content for EV3 lamp to indicate． | 0 to 427 | 5 |  |
| 612 | LE＇4 | LED indicator assigment（Ev4） | Selects the content for EV4 lamp to indicate． | 010427 | 6 |  |
| 613 | LEW | LED indicator assigment（EV6） | Selects the content for EVS lamp to indicate． | 010427 | 7 |  |
| 614 | LEN6 | LED indicator assigrment（Ev6） | Selects the content for EVE lamp to indicate． | 010427 | 0 |  |
| 615 | L5tb | LED indicator assionment（STBY） | Selecels the content for STBY lamp to indicate． | 06427 | 12 |  |
| 616 | LMATV | LED indicator assignment（MANU） | Selects the content for MAN Iamp to indicate． | 010427 | 13 |  |
| 617 | RTPP | Ramp SV ONOFF | Sels the ramp SV ONOFF | $\begin{array}{\|l\|l\|} \hline \text { off } \\ { }_{\mathrm{NN}} \end{array}$ | ${ }^{1}(\mathrm{ON})$ |  |
| 618 | RMPL | Ramp SV－Deciline | Sels the slope for a falling SV during ramp SV operations | $010100 \%$ Fs | 0．00\％6F |  |
| 619 | RMPH | Ramp SVVIncine | Selts the siope for a rising SV during ramp SV operations | 0 to 100\％．FS | 0．00\％\％ 6 |  |
| 620 | RMPU | Ramp SV－slope time unit | Sets the unit of time for the slope during ramp SV operations | our：slope temperature／hour Min：slope temperature／min | nour |  |
| 821 | $5{ }^{\prime \prime} \mathrm{t}$ | Ramp SV－display mode | Displays the SV during ramp operations or the SV goal value on the SV display | $\begin{aligned} & \text { IMP: ramping SV } \\ & \hline \text { Tro target SV } \end{aligned}$ | mP |  |
| 622 | ［tRL | Controd metiod | Selects the control method． | ONOF：ONOFF control Pidd PID control SELF：Selly conitiol 2FRE： 2 －degrees－of－freedom PID | Pid |  |
| 623 | PRTS | Contol arget | Selects the control target | SRV1：servo control 1 SRV2：servo control 2 PFb ：Position feedback control | SRV1（SrV1 without position eedback control PFB（PFb：with control） |  |
| 624 | ollof | ONOFF hysteresis | Selects the hysteresis operation during 2－position contol． | $\begin{aligned} & \text { ofF } \\ & { }_{\mathrm{oN}} \end{aligned}$ | ON |  |
| 626 | $5 \mathrm{EHM}^{\text {d }}$ | Start mode | Sets the operation mode during statup | AUTo：starts in AUTO mode MAN starts in Manual mode REM．starts in remote mode STbY：starts in Standby mode | AUTO |  |
| 627 | dt | Control operation cycle | Sels the control operation cycle． | 0.1 to 0．95， 1 to 989 S | 0.15 |  |
| 628 | Ples | PID pallette swithing melhod | Sels the method for switching among PID palete． | $\begin{aligned} & \text { 0: selected PID Na } \\ & \text { i:solected SV Na } \\ & \text { 2:PV } \end{aligned}$ | 0 |  |

Ch 8 MATH（calculation parameters）

| Parameter |  |  | Function | Setting range | Initial value | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Ne | Display | Name |  |  |  |  |
| 650 | MREH | Simple calculation ON／OFF | Sets ON／OFF of simple calculation | OFF／ON | OFF |  |
| 651 | W M ${ }^{\text {M }}$ | Wafer 1 calculation | Sets the wafer 1 calculaton． | 0.8 | 0 |  |
| 652 | WK1 | Wafer 1 input 1 | Sets the wafer 1 irput 1. | 0 ¢0 9999 | 0 |  |
| 653 | WK゙て | Wafer 1 input 2 | Sels the water 1 irput 2. | 0109999 | 0 |  |
| 654 | Wに゙3 | Water 1 input 3 | Sets the water 1 input 3 ． | 0 to 9999 | 0 |  |
| 655 | H101 | Simple calculation result water 1 output 1 | Displays the water 1 output 1. | －1999 to 9999 | － |  |
| 656 | W 102 | Simple calculation result water 1 output 2 | Displays the wafer 1 output 2. | －1899 to 9999 | － |  |
| 657 | W 103 | Simple calculation result wafer 1 output 3 | Displays the wafer 1 output 3. | －1999 to 9999 | － |  |
| 658 | W104 | Simple calculation result water 1 output 4 | Displays the water 1 output 4 ． | －1999 to 9999 | － |  |
| 659 | WZMA | Water 2 calculation | Sets fre water 2 calcuiation． | 0109999 | 0 |  |
| 660 | WCE1 | Water 2 input 1 | Sets the water 2 input 1. | 0 to 9999 | 0 |  |
| ： | ： | ： | ： | ， |  | ： |
| 729 | WRO3 | Simple calculation result water 10 output 3 | Displays tre water 10 output 3. | －1999 to 9999 | － |  |
| 730 | WROY | Simple calculation result water 10 output 4 | Displays the water 10 output 4 ． | －1999 to 9999 | － |  |
| 731 | ［oin！ | Constant 1 | Sets the constant 1. | －1999 to 9999 | ． |  |
| ： | ： | ． | : | $:$ |  | ： |
| 740 | ［omh | Constant 10 | Sets the constant 10. | -1999 to 9999 | 0 |  |

## Ch 9 COM (communication parameters)

| Parametor |  |  | Function | Setting range | Initial value | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| No | Display | Name |  |  |  |  |
| 760 | [tyP | Communication type | Selects the type of communication. | 0: MODBUS RTU <br> 1: Cooperative operation <br> 2: Programless communication | 0 | [RESET] Note 1 |
| 761 | StNo | Staton No. | Sets the station number. | 0 to 255 (0. unresponsive communication) | 1 | [RESET] |
| 762 | 5PEd | RS-485 baud rate | Sets the baud rate | 98: 9600 bps 192: 19200 bps $384: 38400 \mathrm{bps}$ $115 \mathrm{~K}: 115 \mathrm{Kbps}$ 115K. 115 kbps | 0 (96) | [RESET] |
| 763 | PREY | RS-485 parity | Sets the parity check | none odd even | 1(odd) | [RESET] |
| 764 | ¿胜 ${ }^{\prime}$ | RS-485 response interval | Widen the time interval of receiving response. (Set value $\times 20$ ms) | 0 to 100 | 1 (20 ms) | [RESET] |
| 767 | SC[ | Communication permissions | Sets whether or not overwiting is possible from the master side (PC, etc.) | r. Read only rW. Read/overwite permitted | 1 (RNW) | [RESET] |
| 769 | UROI | MODBUS user address setting 1 | Sets the MODBUS user address |  | 30001 | [RESET] |
| : |  |  |  |  |  |  |
| 800 | UR33 | MODBUS user address setting 32 |  |  | 30001 | [RESET] |
| 801 | [515 | Communication SV gain | Configures the gain to be added to the SV changed through cooperative operation. | 0.001 to 9.999\% | 1.000\% |  |
| 802 | [51.5 | Communication SV shift | Sets the shift value for the SV changed through cooperative operation. | -100 to 100\% FS | 1.000\% |  |
| 803 | HIH. | Cooperative operation iterns | Selects the items to be changed through cooperative operation. | 0: SV and RUN/standby <br> 1: all parameters | 0\%FS | [RESET] |
| 804 | RP[y | All parameters copy | Copies all parameter values of a master to slave devices. | $\begin{aligned} & \text { 0: not copy } \\ & \text { 1: copy } \end{aligned}$ | - |  |
| 805 | Pl St | Target PLC stafon No | Sets the target staton number for programiess communication. | 0 10 255 (0. undefined) | 0 | [RESET] |
| 806 | PRdH | PLC registration number allocaton ruie | Define the method for allocating registration numbers to the PLC programless communication areas. | o: contiguous allocation] <br> 1: individual allocation | 0 | [RESET] |
| 807 | MSWL | Communication interval between temperature controllers | Sets the time interval of programiess communicatons between temperature controlers. | 010100 ms | 0 | [RESET] |
| 808 | PLWE | Communication interval between a PLC and temperature controllers | Sets the time interval of programiess communications between a PLC and temperature controlers (setpoint $\times 2 \mathrm{~ms}$ ) | 010100 | 20 ms | [RESET] |
| 809 | PLAd | Head of PLC registration numbers | Sets the PLC register number to which PXF accesses in programiess communication. | 0000 to FFFF | 10 (20 ms) | [RESET] |
| 810 | SROI | Modbus address of data No. 1 in setting area | Sets a MODBUS address for data to be registered in setting area data field in programless communication | 40001 to 49999. MODEUS address. 0. undefined | 0 | [RESET] |
| : | : | : |  |  |  | $:$ |
| 825 | 5816 | Modbus address of data No. 16 in setting area | Sets a MODBUS address for data to be registered in setting area data field in programless communication | 40001 to 49999 . MODBUS address. 0. undefined | 0 | [RESET] |
| 826 | MRO 1 | Modbus address of data No. 1 in monitor area | Sets a MODBUS address for data to be registered in monitor area data field in programiess communication | 30001 to 39999,40001 to 49999 . MODBUS address, 0. undefined | 0 | [RESET] |
| : | : | : |  |  |  |  |
| 841 | MR 16 | Modbus address of data No. 16 in monitor area | Sets a MODBUS address for data to be registered in monitor area data field in programiess communication | 30001 to 39999,40001 to 49999 : MODBUS address, 0 : undefined | 0 | [RESET] |
| 842 | $A F_{L}^{-}:$ | Auto Fix | Sets the auto write function for communication. | oNiofF | on | Note 2 |

Note 1) Refer to the communication instruction manual (MODBUS) for the detail of communication functions
Note 2) You cannot set or change this parameter by using the loader software.

## Ch 10 PFB (PFB parameters)

| Parameter |  |  | Function | Setting range | Initial value | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| No | Display | Name |  |  |  |  |
| 870 | PGAP | PFB dead band | Sets fre dead band for PFB. | 0.0 to 100.0\% | 50\% |  |
| 871 | tricl | Valve stroke time | Sets the full-stroke fime for the valve. | 5 to 1805 | 30 s |  |
| 873 | [RL | PFB input adjustment | Carry out zero/span adjustment of PFB input. | O: no adustmentforced termination <br> 1: zero adjustment. <br> 2: span adjustment <br> 3: auto adjustment | - |  |

## Ch 11 DSP (parameter mask)

| Parameter |  |  | Function | Setting range | Initial value | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Ne | Display | Name |  |  |  |  |
| - | - | Parameter mask | Sets the parameters to be displayed/not displayed. | OFF/disp | Values differ depending on the model. |  |

Ch 12 CFG (configuration parameters)

| Parametor |  |  | Function | Setting range | Initial value | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Ne | Display | Name |  |  |  |  |
| 940 | tolt | Operation timeout | Sets the time until the display returns to PVISV screen from setting screen. |  | 60 S |  |
| 942 | 50F\% | Blinking SV during Soft Start | Sels whether or not to blink SV during Sof Start. | $\begin{aligned} & \text { OFF OFF OFF } \\ & \text { ON ON } \end{aligned}$ | ON |  |
| 943 | RLMF | Blinking PVISV at ALM | Selt whether or not to bink PVVISV when DO becomes ON. |  | 0 |  |
| 944 | LofF | Display timeout | Sets the time untt the display automatically tums off |  | ofF |  |
| 945 | d5Pt | PVisV Display oft | Sels ONOFF of PV and SV display |  <br> 2.PVOFF <br> if PV and SV OfF <br> 4. PV. SV and indicators OFF (all OFF) 5: SV OFF (relights tor 5 sec by pressing <br> key. 6 :PV OFF (reilights tor 5 sec. by pressing any <br> key. FV and sv off (reights for 5 sec. by <br>  sec by pressing any key) | ${ }^{0}$ |  |
| 946 | FLLF | Blinking PV at input error | Sels whether or not to blink PV at a n input error | 0. PV binks at an input erros 1: No blink . | 0 |  |
| 947 | blit | Brighness | Selts the brightess of LED Dackight | 0 to 3 (3 is the brightest) | 3 |  |
| 948 | blan | Controd at bumout | Sets whether to continue or to stop control when the device detects a burnout of PV input | OFF. stops control ow. continues control | off |  |
| 950 | PLDI | Model code | Shows modol code | - | P |  |
| 951 | PLOC |  |  |  | $\times$ |  |
| 952 | Pl03 |  |  |  | F |  |
| : | : | : | : | : | : | : |
| 962 | PLB |  |  |  | $\cdot$ |  |
| 963 | RSt | Reset | Resets the controler | ofF: No reset IST Performs reset | off |  |
| 964 | VER I | Sotware version | Shows the sotware version | - | - |  |
| 965 | VERPR |  |  |  |  |  |
| 966 <br> 967 | $\begin{aligned} & \text { VERE } \\ & \text { VERP } \end{aligned}$ |  |  |  |  |  |

Ch 13 PASS (password parameters)

| Parameter |  |  | Function | Setting range | Initial value | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Ne | Display | Name |  |  |  |  |
| 990 | PAS 1 | Password1 setup | Sets password 1. | 0000 to FFFF | 0000 |  |
| 991 | PRS2 | Password2 setup | Sets password 2. | 0000 to FFFF | 0000 |  |
| 992 | PR53 | Password3 setup | Sets password 3. | 0000 to FFFF | 0000 |  |

## 3 Parameter functions and setting procedure

## 3-1 Operation mode

## MAN Auto/manual switchover (001)

## [Description]

$\qquad$
Manual control allows you to set the control output to any value.

- Range: oFF (auto) / on(manual)
- MANU indicator lights during manual operation.
- In this screen, only the switchover between auto/manual is available. Manual operation of control output is available on PV/MV screen.


## Note:

This parameter is not displayed in default setting. To use this parameter, change the setting of "CH11 dSP".
[Setting example] Changing the mode from Auto to Manual


## StbY RUN/Standby switchover (002)

## [Description]

Allows you to switch between operation mode and standby mode.
The following items used during standby can be set beforehand.

- Control output (-5.0 to $105.0 \%$ )
- Alarm output (ON/OFF)
- Transfer output (ON/OFF)

You can set the detail of standby mode in "Standby mode".
Related parameters: $\quad$ SbMd (page 133), Sbo1 (page 132), Sbo2 (page 132)
Point: - When "hold alarms" is on, the hold function activates when you switch the standby setting from on to off.

- If the instrument is put into standby during auto tuning, the auto tuning is canceled. To complete auto-tuning, turn standby mode off and restart auto tuning.
- When the controller switches to standby mode, the ON delay timer will be reset. It will begin again when standby mode is turned off.
[Setting example] Switching to Standby mode

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r\|} \hline 245 & \mathrm{Pv} \\ 250 & \mathrm{sv} \end{array}$ | 1. Check that the PV/SV display is shown. |
| M A N  <br> oFF  <br> sv  | 3. Use the (1) keys to change MAN to StbY. |
| St b Y pv <br> oFF sv | 4. Press the SEL key to enter StbY mode. <br> (The lower part of the screen begins to blink.) |
| $\begin{array}{cc} \hline \mathrm{StBY} \\ \mathrm{St} & { }_{\mathrm{oN}} \\ & { }_{\mathrm{SV}} \end{array}$ | 5. Use the (1) () keys to change oFF to oN. <br> 6. Press the SEL key to save the change. Now the controller is in the Standby Mode. (STBY indicator turns on.) |
|  | 7. Press the () key to return to the PV/SV display. |

## REM Remote/local switchover (003)

## [Description]

$\qquad$
The following will switch you between local SV and remote SV operation. In remote SV operation, SV is controlled by an external SV input (RSV).


## Note:

During remote operation, you cannot change the SV by using UP/DOWN keys on the front panel.
[Setting example] Switching to the remote SV mode


## PRoG Ramp Soak control command (004)

[Description]
Allows you to switch between Ramp/soak states.
You can select among the following three state.

- oFF (stop): Ramp/soak is stopped.
- RUN (start): Ramp/soak starts.
- HLd (hold): Ramp/soak hold. To release the hold, select "RUN" again.

The parameter information changes automatically depending on the ramp/soak state.

- GS (Guaranty soak ON): Guaranty soak is activated and PV is out of guaranty soak setting range.
- ENd (end): Ramp/soak has finished.

During ramp soak operation, one of RUN, HOLD, or END indicators light according to the state of ramp soak.
During ramp soak operation, on-going step No. and "r" (ramp) or "-" (soak) are displayed on the screen No. area of operation screen (PV/SV screen).
For example, " 2 r " appears during step 2 ramp , and "2-" during step 2 soak.
Related parameters: PRG (CH3) (page 70)
[Setting example] Ramp Soak command is carried out


## AT Auto tuning (005)

## [Description]

$\qquad$
Running auto-tuning automatically sets the optimal PID.

- Setting range

| oFF: | Stop/Finish |
| :--- | :--- |
| oN: | starts auto tuning (normal type) |
| L-oN: | starts auto tuning (low-PV type) |

There are the following two types in auto-tuning.

| Normal type | Performs ON/OFF operation with SV as the baseline to calculate PID. |  |
| :---: | :---: | :---: |
| Low-PV type | Perfoms ON/OFF operation with SV-10\% to calculate PID. Use the this setting if you want to prevent overshoot. |  |

- When auto tuning is normally completed, the automatically set PID parameter value is maintained even if the power is turned off. If the power is turned off during auto tuning, the auto-tuning function is invalidated with PID parameters unchanged. In such a case, start again from the beginning.
- Since ON-OFF operation (2-position operation) is performed during auto tuning, PV may fluctuate greatly depending on the process. Do not perform auto tuning for the processes where large fluctuation of PV is not allowed. Do not perform auto tuning, either, for the processes where the response is quick, such as pressure control or flow rate control.
- If auto tuning does not end after 4 hours, it means that tuning may not be completed successfully. Check input/output wiring and parameters such as control output (forward, reverse) and input sensor type.
- When you change SV or PV input type, or when operation does not work properly due to the change in operating conditions, perform auto tuning again.
- You can run auto-tuning when the control type is set to "fuzzy" or "PID2".
- You cannot run auto-tuning during manual mode.
- When you are using the PID selection function, the auto-tuning result for the selected PID group is stored.
- Auto tuning is forcibly terminated when SV is changed by the ramp soak function, remote SV function, or ramp SV.


## Note:

Since ON/OFF control is performed during auto-tuning, overshoot against the SV may occur. To reduce the overshoot, execute the auto-tuning with [L-on] (Low PV).
Related parameters: CtRL (CH7) (page 153)

| Display | Operating procedure |
| :---: | :---: |
| 245 250 sv Sv | 1. Check that the PV/SV display is shown. |
| M A N  <br> oFF sv | 3. Use the (1)(1) keys to change MAN to At. |
| A t pv <br> oFF sv | 4. Press the SEL key to enter At mode. (The lower part of the screen begins to blink.) |
| AT oN sv | 5. Use the (1) keys to change ofF to oN. |
|  | 6. Press the SEL key to save the change. <br> Auto tuning starts. <br> AT indicator lamp blinks. <br> 7. Press the () key to return to the PV/SV display. |

## LACH Alarm output latch release (006)

## [Description]

$\qquad$
Allows you to cancel the alarm Latch.

- Setting range
oFF: keeps the latch on
RSt: releases latch
[Setting example] Releasing alarm output latch



## SVN SV selection (007)

## [Description]

$\qquad$
Allows you to easily switch SV among the following.

- Setting range: LoCL, SV1, SV2, SV3, SV4, SV5, SV6, SV7, di

To use this function, you need to configure SVs (SV1 to SV7) in the PID palette parameters. It is recommended to activate the ramp SV before changing SV number so that control disorders can be reduced.
Related parameters: RMP (CH7) (page 148)
Note:
Changing the SV number will not change the control parameters (PID, etc).
When changing the SV value with the front panel key, do not change the "Svn" parameter via communication. Otherwise, the changed SV may not be stored correctly.
[Setting example] Changing SV Number

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r} 245 \\ 250 \end{array} \mathrm{SV}_{\mathrm{sV}}$ | 1. Check that the PV/SV display is shown. |
| MA N <br> oFF | 3. Use the ©(1) keys to change MAN to SVN. |
| SVN <br> LoCL | 4. Press the SEL key to enter SVN mode. <br> (The lower part of the screen begins to blink.) |
| SV3 ${ }^{\text {sv }}$ | 5. Use the ©() keys to change LoCL to SV3. |
|  | 6. Press the SEL key to save the change. <br> The SV used for control is now set to "SV3". <br> 7. Press the key to return to the PV/SV display. |

## PLN1 PID selection (008)

## [Description]

$\qquad$
Allows you to easily switch PID No. among those you configured in the PID palette parameters.
This allows you to change the PID according to the change of SV or control target.

- Range: LoCL, Pid1, Pid2, Pid3, Pid4, Pid5, Pid6, Pid7, di
[Setting example] Changing PID Number

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{pv} \\ 250 & \mathrm{sv} \end{array}$ | 1. Check that the PV/SV display is shown. |
| M A N  <br> oFF  <br> vv  | 3. Use the © () keys to change MAN to PLN1. |
|  | 4. Press the SEL key to enter PLN1 mode. (The lower part of the screen begins to blink.) |
| Pid1 sv | 5. Use the ©() keys to change LoCL to Pid1. <br> 6. Press the SEL key to save the change. <br> The PID calculation parameter used for control is now set to Pid1. <br> 7. Press the key to return to the $\mathrm{PV} / \mathrm{SV}$ display. |

AL1 A1-L A1-H Alarm settings (009 to 011)

| AL2 | A2-L | A2-H | (012 to 014) |
| :--- | :--- | :--- | :--- |
| AL3 | A3-L | A3-H | (015 to 017) |
| AL4 | A4-L | A4-H | (018 to 020) |
| AL5 | A5-L | A5-H |  |

[Description]
Allows you to set the values for alarm 1 to alarm 5.

- Setting range: absolute value alarm: $0 \%$ to $100 \% \mathrm{FS}$ deviation alarm: $-100 \%$ to $100 \%$ FS
Related parameters: CH5 Alarm parameters (page 100)
[Setting example] Setting alarms

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{PV} \\ 250 & \mathrm{sv} \end{array}$ | 1. Check that the PV/SV display is shown. |
| MA N <br> oFF | 3. Use the (1) keys to change MAN to AL1. |
| $\begin{array}{r\|l} \text { A L } 1 & \mathrm{pv} \\ 0010 & \mathrm{sv} \end{array}$ | 4. Press the SEL key to enter AL1 mode. <br> (The first digit of the lower part of the screen begins to blink.) |
| 0020 sv | 5. Use the ()(1)() keys to change 10 to 20 . <br> 6. Press the SEL key to save the change. The alarm value is now set to $20^{\circ} \mathrm{C}$. |
|  | 7. Press the () key to return to the PV/SV display. |

## WCMd Electric power calculation command (027)

## [Description]

$\qquad$
Allows you to switch the electric power calculation status among the following three modes.
oFF: Stops calculation. (Calculated amount of electric power will be cleared.)
RUN: Calculates the amount of electric energy.
HLd: Suspend the calculation. (Calculated value of electric power will be retained.)
Related parameters: CH6 Setup parameters (page 114)
[Setting example] Switching electricity power calculation status


## LoC Key lock (028)

## [Description]

$\qquad$
Prevents SV parameters from being changed.
The following three settings are available:
oFF: No lock
ALL: All locked
PARA: All but SV locked
The channel menu can be displayed even when key lock is active.
Related parameters: Accidental operation can also be prevented with a password. See CH13 Password parameters (page 195).
[Setting example] Setting Key Lock

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. |
| M A N  <br> oFF  <br> SV  | 3. Use the ©() keys to change MAN to LoC. |
| Lo C Pv <br> oFF sv | 4. Press the SEL key to enter LoC mode. <br> (The first digit of the lower part of the screen begins to blink.) |
| ALL ${ }^{\text {sv }}$ | 5. Use the ©() keys to change oFF to ALL. <br> 6. Press the SEL key to save the change. Key Lock is now activated. |
|  | 7. Press the () key to return to the PV/SV display. |

## 3-2 CH1 PID (Control parameters)

## P Proportional band (050) <br> Integration time (051) <br> d Differential time (052)

## [Description]

Allows you to set PID (Proportional Band, Integration Time, Differential Time).
Setting range
P: $\quad 0.1$ to $999.9 \%$
I: $\quad 0$ to 3200 seconds
D: $\quad 0.0$ to 999.9 seconds

The following control methods are available with PID settings.

| ON/OFF control <br> (2-position control) | When the control method CtRL is set to oNoF, ON/OFF control is used. Use the <br> this function when you want to run simple control without worrying about the <br> controllability. |
| :--- | :--- |
| PID control | Use this function when you want to control with high controllability. <br> $\mathrm{P}, \mathrm{I}$, and D should be adjusted to optimal values for the control target, although Pid <br> can be activated with $\mathrm{P} \neq 0, \mathrm{I} \neq 0$, and $\mathrm{D} \neq 0$. In normal situations, run auto-tuning <br> to optimally adjust $\mathrm{P}, \mathrm{I}$, and D before using this function. |
| PI control | When $\mathrm{P} \neq 0, \mathrm{I} \neq 0$, and $\mathrm{D}=0, \mathrm{D}$ control is turned off and PI control is used. |
| P control | When $\mathrm{P} \neq 0$ and $\mathrm{I}=0, \mathrm{D}=0, \mathrm{I}$ and D controls are turned off and P control is used. <br> In principle, P control generates offset and PV does not agree with SV. In this case, <br> adjust the output convergence value "bAL". |

Running auto-tuning automatically sets the optimal PID. See "AT Auto tuning (005) " (page 33)
The PID settings configured by auto-tuning are generally considered to be optimal settings. If you want to change the responsiveness, adjust PID manually.
Generally, control becomes unstable when " P " is set too small. On the other hand, setting it too big makes the response slow.
Set the hysteresis for the ON/OFF (2-position) control with the parameter "hyS".

## Note

Do not perform auto tuning during ON/OFF control.
[Setting example] Setting $P=10.0 \%, I=100 \mathrm{sec} ., D=20 \mathrm{sec}$.


## HYS ON/OFF control hysteresis (053)

## [Description]

$\qquad$
Allows you to set the hysteresis for ON/OFF (2 position) control

- Setting range: 0.0 to $50.0 \%$ FS

The controllability varies with the size of the hysteresis.

| Small hysteresis | • |
| :--- | :--- |
| Largh-precision control |  |
|  | Frequency of output relays is high, so lifespan becomes short. |

The relationship between SV and hysteresis in normal and reverse operation is shown below.


- During ON/OFF control, the i and d settings do not affect control.
- If the hysteresis width is narrow, and PV and SV are nearly equal, the output may frequently switch on and off. Note that it may affect the life of the contact.
[Setting example] Changing the hysteresis range from 25\%FS to 30\%FS

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{PV} \\ 250 & \mathrm{sv} \\ \hline \end{array}$ | 1. Check that the PV/SV display is shown. |
| CH1 pv  <br>  Pid Sv | 3. Press the SEL key to enter CH1 (PID parameters). $P$ is displayed. |
| $\mathbf{P}$ PV <br> 5.0 sv | 4. Use the ©() keys to change $P$ to HYS. <br> 5. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| HY S pv <br> 25 sv | 6. Use the (1) (1) keys to change 25 to 30 . <br> 7. Press the SEL key to save the change. |
| 30 sv | 8. Press the (b) key to return to the PV/SV display. |

## CooL Cooling proportional band coefficient (054)

## [Description]

Allows you to set the proportional band coefficient for cooling.

- Setting range: 0.0 to 100.0

The relationship between heating control output and cooling control output is outlined below.


Cooling proportional band is set after the optimal value for heating proportional band is set.
Cooling proportional band $=($ Proportional band $\mathrm{P} / 2) \times$ Coefficient
The following example shows how the cooling proportional band is calculated.
Example: Calculating the coefficient that will give a cooling proportional band of $10 \%$ when proportional band $(P)=50 \%$ with full scale cooling
$10 \%=(50 \% / 2) \times$ Coefficient
Coefficient $=0.4$
To set cooling as a secondary operation, set "Cool" to 0.0 .
With two outputs set as $\mathrm{P}=0.0$ and $\mathrm{Cool}=0.0$, heating and cooling outputs become ON/OFF actions (3-position control). In this situation, the ON/OFF hysteresis is $0.5 \% \mathrm{FS}$ (fixed) for heating and cooling outputs. The point of operation for the heating output can be shifted with the "HYS" parameter. The point of operation for the cooling output can be shifted with the "db" parameter.
The relationship between SV and hysteresis in normal and reverse operation is shown below.

[Setting example] Changing cooling proportional band coefficient from 1.0 to 2.5

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r\|} \hline 245 & \mathrm{pv} \\ 250 & \mathrm{sv} \end{array}$ | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). |
| $\boldsymbol{P}$ PV <br> 5.0 SV | 3. Press the SEL key to enter CH1 (PID parameters). $P$ is displayed. |
| $\begin{array}{r} \text { Coo L } \\ 1.0 \\ \mathrm{sv} \\ \mathrm{sv} \end{array}$ | 4. Use the ©() keys to change P to Cool. <br> 5. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 2.5 sv | 6. Use the (a) keys to change 1.0 to 2.5 . <br> 7. Press the SEL key to save the change. |
|  | 8. Press the (L) key to return to the PV/SV display. |

[Description]
Shifts the cooling proportional band against the set value as follows.

" db " is called dead band when the value is positive, and overlap band when the value is negative.

- Range: -50\% to 50\%
" db " is measured as a percentage of MV and can be converted to a percentage deviation by the following formula.
DB [\%] = deviation x 100/P [\%]
Example: Proportional Band $(\mathrm{P})=5.0 \%$, with a desired dead band of $1 \%$ deviation from SV:
$\mathrm{DB}[\%]=1.0 \times 100 / 5.0=20[\%]$
Dead band $=20$ (\%)
[Setting example] Setting Dead band to 1.5\%

| Display | Operating procedure |
| :---: | :---: |
| 245 250 pv | 1. Check that the PV/SV display is shown. |
| CH1 PV  <br>  Pid SV <br>    | 2. Press and hold the SEL key to display CH1 (PID parameters). |
| $\mathbf{P}$ Pv <br> 5.0 sv | 3. Press the SEL key to enter CH1 (PID parameters). $P$ is displayed. |
| d b PV <br> 0.0 SV | 4. Use the ©() keys to change P to db . <br> 5. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 1.5 sv | 6. Use the ©(1) keys to change 0.0 to 1.5 . <br> 7. Press the SEL key to save the change. <br> 8. Press the () key to return to the PV/SV display. |

## bAL <br> Output convergence value (056)

## [Description]

$\qquad$
Output convergence value is a function that adds an offset to MV value.

- Setting range bAL: - 100 to $100 \%$

By this function, the bAL offset is added to original MV which is the result of PID calculation determined by PV and SV, and the total value is outputted as MV.
(The factory setting of bAL is $0 \%$ for single output, $50 \%$ for dual output.)

[Setting example] Changing Output convergence value from 0.0\% to 3.0\%

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the SEL key to enter CH1 (PID parameters). $P$ is displayed. <br> 4. Use the (1) (v) keys to change $P$ to bAL. <br> 5. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) <br> 6. Use the ©(1) keys to change 0.0 to 3.0. <br> 7. Press the SEL key to save the change. <br> 8. Press the (L) key to return to the PV/SV display. |
| CH1 pv  <br>  Pid sv |  |
| $\mathbf{P}$ PV <br> 5.0 sv |  |
| b A L 0.0 |  |
| 3.0 sv |  |
|  |  |

## AR Anti-reset windup (057)

[Description]
Anti-reset windup is a function that limits the range of valid integration to control overshooting.
Setting range Ar: 0 to $100 \%$ FS

- The anti-reset windup function ("AR") cuts integration that falls outside of the Ar set range that is centered around SV. It is automatically set to the optimum value when auto-tuning is activated

[Setting example] Changing the anti-reset windup to $500^{\circ} \mathrm{C}$

| Display | Operating procedure |
| :---: | :---: |
| 245 250 pv | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). |
| P Pv <br> 5.0 sv | 3. Press the SEL key to enter CH1 (PID parameters). $P$ is displayed. |
| A R PV <br> 100 SV | 4. Use the (1) keys to change $P$ to $A R$. <br> 5. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 500 sv | 6. Use the ©(1) keys to change 100 to 500 . <br> 7. Press the SEL key to save the change. |
|  | 8. Press the (5) key to return to the PV/SV display. |

## REV Normal/reverse operation (058)

## [Description]

$\qquad$
Specifies whether the control operations are normal or reverse.

- Setting range

| RV_: | heat (reverse) / cool (none) |
| :--- | :--- |
| No_- : | heat (normal) / cool (none) |
| RVNo: | heat (reverse) / cool (normal) |
| NoRV: | heat (normal) / cool (reverse) |
| RVRV: | heat (reverse) / cool (reverse) |
| NoNo: | heat (normal) / cool (normal) |

Most temperature control is done with heating in reverse and cooling in normal.

[Setting example] Setting the heating control to reverse, cooling control to normal action


SVL SV lower limit (059)
SVH SV upper limit (060)
[Description] $\qquad$
These parameters specify the setting range of the SV (Setting value). You can set any value within the measurement range.

- Setting range: 0 to $100 \%$ FS (Upper/Lower)

The relationship between SV limits and the measurement range is as follows:


Note:

- Before setting SVH/SVL, be sure to set the following parameters in CH6 Setup parameters.

PV lower limit ( PVb )/PV upper limit (PVF)

- SVs set before setting the SV limits (Local SV, Palette SV, etc.) are affected by new SV limits.
- Make sure to set the value of SVh greater than SVL.
[Setting example] Setting the lower SV limit to $50^{\circ} \mathrm{C}$

| Display | Operating procedure |
| :---: | :---: |
| 2450 pv | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). |
| P Pv <br> 5.0 sv | 3. Press the SEL key to enter CH1 (PID parameters). $P$ is displayed. |
| S V L ${ }_{\text {c\|iv }}^{\text {pv }}$ | 4. Use the ©() keys to change $P$ to SVL. <br> 5. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 50 sv | 6. Use the (1) keys to change 0 to 50 . <br> 7. Press the SEL key to save the change. <br> 8. Press the key to return to the PV/SV display. |

## tC1 OUT1 proportional cycle (061)

tC2 OUT2 proportional cycle (062)

## [Description]

$\qquad$
When using contact output and SSR drive output with PV input inside the proportional band, output will switch between ON and OFF at regular intervals.

- These intervals are called proportional cycles. OUT1 and OUT2 can be set separately.

Setting range: 1 to 150


The following are the recommended settings for each control output.

| Contact <br> output | The shorter the proportional cycle, the finer the control, however shorter proportional cycles <br> also shorten the lifespan of the contact points and operating device. Keep a balance between <br> controllability and controller lifespan when adjusting the proportional cycles. <br> Approx.: 30 sec |
| :--- | :--- |
| SSR drive <br> output | Because there are no mechanical parts, use a short proportional cycle if the operating device <br> is working properly. <br> Approx.: 1 or 2 seconds |

## Note:

- TC2 is only valid when there are dual outputs.
- The proportional cycle for the current output is same as the blinking cycle of OUT indicator (approximately 1 second).
[Setting example] Setting OUT1 proportional cycle to 60 sec

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. |
| $\begin{array}{lr\|l} \mathrm{CH} & 1 & \mathrm{PV} \\ & \text { Pid } & \mathrm{sv} \end{array}$ | 2. Press and hold the SEL key to display CH1 (PID parameters). |
| $\mathbf{P}$ PV <br> 5.0 sV | 3. Press the SEL key to enter CH1 (PID parameters). $P$ is displayed. |
| t C1  <br>  pV <br> 30 sV | 4. Use the ©() keys to change P to tC 1 . <br> 5. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 60 sv | 6. Use the (1) keys to change 30 to 60 . <br> 7. Press the SEL key to save the change. <br> 8. Press the key to return to the PV/SV display. |

## PLC1 PHC1 OUT1 Upper/Lower Limits $(063,064)$ <br> PLC2 PHC2 OUT2 Upper/Lower Limits $(065,066)$

## [Description]

$\qquad$
This parameter specifies the upper and lower limits for output control.

- Setting range

| Output | Lower limit | Upper limit | Setting range |
| :--- | :--- | :--- | :--- |
| OUT1 | PLC1 | PHC1 | -5.0 to $105.0 \%$ |
| OUT2 | PLC 2 | PHC 2 | -5.0 to $105.0 \%$ |

PHC
[Setting example] Setting OUT1 lower limit to 5\%


## PCUt Type of output limiter (067)

## [Description]

$\qquad$
You can choose whether to apply the limit on the output value or let it exceed the limit.
The output changes according to the limit, as follows.

| output value |  | Setting ra | nge |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 105\% | ------ | Setting | Output | (OUT1) | Output | (OUT2) |
|  |  |  | Lower limit | Upper limit | Lower limit | Upper limit |
| PHC | $\checkmark$ | 0 | -5\% | 105\% | -5\% | 105\% |
|  |  | 1 | limit | 105\% | -5\% | 105\% |
|  |  | 2 | -5\% | limit | -5\% | 105\% |
| PLC |  | 3 | limit | limit | -5\% | 105\% |
|  | ${ }^{\text {no limit }}$ | 4 | -5\% | 105\% | limit | 105\% |
| $5 \%$ | $\triangle$ PLC PHC $\begin{gathered}\text { output value } \\ \text { (before limiting) }\end{gathered}$ | 5 | limit | 105\% | limit | 105\% |
|  |  | 6 | -5\% | limit | limit | 105\% |
|  |  | 7 | limit | limit | limit | 105\% |
|  |  | 8 | -5\% | 105\% | -5\% | limit |
|  |  | 9 | limit | 105\% | -5\% | limit |
|  |  | 10 | -5\% | limit | -5\% | limit |
|  |  | 11 | limit | limit | -5\% | limit |
|  |  | 12 | -5\% | 105\% | limit | limit |
|  |  | 13 | limit | 105\% | limit | limit |
|  |  | 14 | -5\% | limit | limit | limit |
|  |  | 15 | limit | limit | limit | limit |

## [Setting example] Setting to keep all the outputs within limits

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{pv} \\ 250 & \mathrm{sv} \\ \hline \end{array}$ | 1. Check that the PV/SV display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters). |
| $\begin{array}{lrrr}\text { CHI } & 1 & \text { PV } \\ & \text { Pid } & \text { SV }\end{array}$ | 3. Press the SEL key to enter CH1 (PID parameters). $P$ is displayed. |
| $\mathbf{P}$ PV <br> 5.0 sv | 4. Use the ©() keys to change $P$ to PCUt. <br> 5. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
|  | 6. Use the <br> keys to change 0 to 15 (limit all). <br> 7. Press the SEL key to save the change. |
| 15 sv | 8. Press the (-) key to return to the PV/SV display. |

ALPA 2-degrees-of-freedom coefficient a (073)
bEtA 2-degrees-of-freedom coefficient $\beta$ (074)

## [Description]

$\qquad$
These coefficients are used to suppress overshoot generated in PID control.
The 2-degrees-of-freedom PID system of this instrument adopts set value (SV) filter method, which is effective in suppressing overshoot at the time of setting change or start-up.
If ALPA $(\alpha)$ is set to $100.0 \%$, and bEtA ( $\beta$ ) to $0.0 \%$, ordinary PID control ( 1 degree of freedom PID) is performed.
Adjust ALPA ( $\alpha$ ) and bEtA ( $\beta$ ) as follows.
(1)Set ALPA ( $\alpha$ ) to $40.0 \%$, and bEtA ( $\beta$ ) to $100.0 \%$. (Factory default setting)
(2)Perform control and check responsiveness (overshoot volume).

If overshoot cannot be improved in this stage, adjust ALPA ( $\alpha$ ) and bEtA ( $\beta$ ), following the definition listed in the following table.
Generally, ALPA ( $\alpha$ ) does not require adjustment. Therefore, it is recommended to use the instrument with ALPA ( $\alpha$ ) set to $40.0 \%$.

| Result of control | bEtA | ALPA |
| :---: | :---: | :---: |
| Large overshoot | Increase BETA $(\beta)$ by $20 \%$ | Decrease ALPA $(\alpha)$ by $10 \%$ |
| Small overshoot | Decrease BETA $(\beta)$ by $20 \%$ | Increase ALPA $(\alpha)$ by $10 \%$ |

Setting range

| ALPA | -300.0 to 300.0 |
| :--- | :--- |
| bEtA | 0.0 to 900.0 |

[2 degrees of freedom PID block diagram]


## Note:

Changing ALPA ( $\alpha$ ) should be performed during manual mode.
Before changing ALPA ( $\alpha$ ) setting, set bEtA ( $\beta$ ) to $0.0 \%$. First, change ALPA ( $\alpha$ ) setting, and then set bEtA ( $\beta$ ) to desired value. Improper procedure may cause output (target value) to increase temporarily, thus posing danger.
The purpose of this function is to suppress overshoot generated in ordinary PID control. Overshoot may not always be eliminated.
[Setting example] Setting the 2-degrees-of-freedom coefficient a to 50.0\%

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{PV} \\ 250 & \mathrm{SV} \end{array}$ | 1. Check that the PV/SV display is shown. |
| CHI 1 PV <br>  Pid  | 2. Press and hold the SEL key to display CH1 (PID parameters). |
| P pv <br> 5. 0 sv | 3. Press the SEL key to enter CH1 (PID parameters). $P$ is displayed. |
| A L P A 40.0 $\mathrm{sV}_{\mathrm{sv}}$ | 4. Use the ©() keys to change $P$ to ALPA. <br> 5. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 50. 0 sv | 6. Use the © () keys to change 40.0 to 50.0. <br> 7. Press the SEL key to save the change. <br> 8. Press the key to return to the PV/SV display. |

## 3-3 CH2 PLT (PID palette parameters)

PID palette parameters are used to register SVs, PIDs, and other control parameters. Up to seven sets of SVs and PIDs can be stored, and you can toggle among them by simply selecting their numbers.
This is very useful when operating conditions change frequently.
The palette menu ( CH 2 ) consists of the following function blocks:


To change the SV No. or PID No., refer to "SV selection" (page 36), "PID selection" (page 37).

## SV1 to SV7 Set Value (100 to 160)

## [Description]

$\qquad$
Up to seven SVs (SV1-SV7) can be recorded. Recorded SVs can be invoked by the SV selection ("Svn") parameter in the operation menu.
Setting range: SV lower limit (SVL) to SV upper limit (SVH) \%FS
It is recommended to activate the ramp SV before changing SV number, so that control disorders can be reduced.
Related parameters: "SV selection" (page 36)
[Setting example] Setting SV1 to $300^{\circ} \mathrm{C}$


P1 to P7 Proportional band (101 to 161)
i1 to 17 Integration time (102 to 162)
d1 to d7 Differential time (103 to 163)

## [Description]

These parameters allows you to configure PID. Up to seven types of PID (palettes 1 to 7) can be recorded.
Recorded PIDs can be called from selected PID number ("PLN1") in the operation menu CH1.

- Setting range

Proportional band (P): 0.0 to $999.9 \%$
Integration time (I): 0 to 3200 seconds
Differential time (D): $\quad 0.0$ to 999.9 seconds
Related parameters: "Proportional Band, Integration Time, Differential Time (CH1)" (page 41)
When a PID No. is changed, the following parameters change to match it.

- ON/OFF control hysteresis
- Cooling proportional band
- Dead band
- Output convergence value
- Anti-reset windup
- Normal/reverse operation

Running auto-tuning will automatically set to the PID No. selected in the PID selection parameter.

## Note:

- For safety, make sure to turn off the power before switching the normal/reverse operations by using the PID selection function. (Do not switch between normal and reverse while operation.)
- If "(PID No. +1, SV No. +1 (increment))" function is executed under the "PID No. = SV No.", PID No. and SV No. is automatically set to the same value.
- PID is switched per palette. You cannot combine the values of PID among palettes.
[Setting example] Setting $P=10.0 \%, I=100$ sec., $D=20 \mathrm{sec}$.

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r\|} \hline 245 & \mathrm{pv} \\ 250 & \mathrm{sv} \end{array}$ | 1. Check that the PV/SV display is shown. |
| H 2 PV <br>  PLt Sv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the key to access CH2 (PID palette parameters). |
| S V 1PV  <br> 0  | 4. Press the SEL key to enter CH2 (PID palette parameters). SV1 (set value) is displayed. |
| P1 pv <br> 10.0 sv | 5. Use the (1) (1) keys to change SV1 to P1. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 11 PV <br> 100 SV | 7. Use the (1)() keys to change 5.0 to 10.0 . <br> 8. Press the SEL key to save the change. <br> 9. Use the () key to change 100 to 20 . |
| $\begin{array}{cc}\text { d } 1 & \mathrm{pv} \\ 20 & \mathrm{sv}\end{array}$ | 10. Repeat the same steps to set Pid2 to Pid7. <br> 11. Press the key to return to the $\mathrm{PV} / \mathrm{SV}$ display. |

## HYS1 to HYS7 ON/OFF control hysteresis (104 to 164)

## [Description]

$\qquad$
This parameter allows you to set the hysteresis width for the ON/OFF control. Up to seven types of hysteresis (for palettes 1 to 7) can be recorded. Recorded hysteresis can be called by PID selection ("PLN1") in the operation mode.

- Setting range: 0 to $50 \%$ FS

Related parameters: "ON/OFF control hysteresis" (page 43)
[Setting example] Setting the ON/OFF control hysteresis 1 to $3^{\circ} \mathrm{C}$

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the $\mathrm{PV} / \mathrm{SV}$ display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the (\%) key to access CH2 (PID palette parameters). |
| SV17 ${ }^{\text {PV }}$ | 4. Press the SEL key to enter CH2 (PID palette parameters). SV1 (set value) is displayed. |
| HYS 1pv  <br> 1 sv | 5. Use the ©() keys to change SV1 to HYS1. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 3 sv | 7. Use the © () keys to change 1 to 3 . <br> 8. Press the SEL key to save the change. <br> 9. Repeat the same steps to set HYS2 to HYS7. <br> 10. Press the ()) key to return to the $\mathrm{PV} / \mathrm{SV}$ display. |

## CoL1 to CoL7 Cooling Proportional Band (105 to 165)

[Description] $\qquad$
Allows you to set the cooling proportional band when dual outputs are selected. Up to seven types of cooling proportional band (for palettes 1 to 7) can be recorded.
Recorded cooling proportional band can be called from PID selection ("PLN1") in the operation mode.

- Setting range: $0.0 \%$ to $100.0 \%$

Related parameters: "Cooling Proportional Band Coefficient" (p. 45)
[Setting example] Setting the Cooling proportional band 1 to 5.0\%

| Display | Operating procedure |
| :---: | :---: |
| 245 250 SV | 1. Check that the PV/SV display is shown. |
| H 2 Pv <br>  PLt sv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the key to access CH2 (PID palette parameters). |
| S V 1$P V$  <br> 0 $S V$ | 4. Press the SEL key to enter CH2 (PID palette parameters). SV1 (set value) is displayed. |
|  | 5. Use the ©() keys to change SV1 to CoL1. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 5. 0 sv | 7. Use the ©(1) keys to change 1.0 to 5.0. <br> 8. Press the SEL key to save the change. <br> 9. Repeat the same steps to set CoL2 to CoL7. <br> 10. Press the (b) key to return to the PV/SV display. |

## db1 to db7 Dead band (106 to 166)

## [Description]

$\qquad$
Allows you to set the dead band when dual outputs are selected. Up to seven types of dead band (for palettes 1 to 7) can be recorded.
Recorded dead band can be called from PID selection ("PLN1") in the operation mode.

- Setting range: $-50.0 \%$ to $50.0 \%$

Related parameters: "Dead Band" (page 46)
[Setting example] Setting Dead band 1 to 7.0\%

| Display | Operating procedure |
| :---: | :---: |
| 245 250 sv | 1. Check that the PV/SV display is shown. |
| $\begin{array}{ll\|l} \mathrm{CH} & \mathbf{2} & \mathrm{pv} \\ & \text { PLt } & \mathrm{sv} \end{array}$ | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the © key to access CH 2 (PID palette parameters). |
| S V 1 pv <br> 0 sv | 4. Press the SEL key to enter CH2 (PID palette parameters). SV1 (set value) is displayed. |
| d b 1 Pv <br> 0.0 sv | 5. Use the ©() keys to change SV 1 to dbl. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 7.0 sv | 7. Use the ©() keys to change 0.0 to 7.0 . <br> 8. Press the SEL key to save the change. <br> 9. Repeat the same steps to set db2 to db7. <br> 10. Press the © key to return to the PV/SV display. |

## bAL1 to bAL7 Output convergence value (107 to 167)

[Description] $\qquad$
Allows you to set the output convergence value. Up to seven types of output convergence value (for palettes 1 to 7) can be recorded. Recorded output convergence value can be called from PID selection ("PLN1") in the operation mode.

- Setting range: $-100.0 \%$ to $100.0 \%$

Related parameters: "Output Convergence Value" (page 47)
[Setting example] Setting Output convergence value 1 to -5.5\%

| Display | Operating procedure |
| :---: | :---: |
| 245 250 sv | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the key to access CH2 (PID palette parameters). |
|  | 4. Press the SEL key to enter CH2 (PID palette parameters). SV1 (set value) is displayed. |
| b A L 1 0.0 pv sv | 5. Use the © () keys to change SV1 to bAL1. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| -5.5 sv | 7. Use the ©() keys to change 0.0 to -5.5 . <br> 8. Press the SEL key to save the change. <br> 9. Repeat the same steps to set bAL2 to bAL7. <br> 10. Press the () key to return to the $P V / S V$ display. |

## [Description]

$\qquad$
Allows you to set the anti-reset windup. Up to seven types of anti-reset windup (for palettes 1 to 7) can be recorded.
Recorded anti-reset windup can be called from PID selection ("PLN1") in the operation mode.

- Setting range: $0.0 \%$ to $100.0 \%$

Related parameters: "Anti-reset windup" (page 48)
[Setting example] Setting the anti-reset windup 1 to 50 FS

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the $\mathrm{PV} / \mathrm{SV}$ display is shown. |
| CHEV $\mathbf{2}$ PV <br>  PLt SV | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the () key to access CH2 (PID palette parameters). |
| S V 1 PV <br> 0 SV | 4. Press the SEL key to enter CH2 (PID palette parameters). SV1 (set value) is displayed. |
| A R 1 pv <br> 100 sV | 5. Use the ©() keys to change SV1 to AR1. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 50 sv | 7. Use the ©(1) keys to change 100 to 50 . <br> 8. Press the SEL key to save the change. <br> 9. Repeat the same steps to set bAL2 to bAL7. <br> 10. Press the (1) key to return to the $\mathrm{PV} / \mathrm{SV}$ display. |

## REV1 to REV7 Normal/reverse (109 to 169)

## [Description]

$\qquad$
Allows you to set the normal/reverse setting. Up to seven types of normal/reverse settings (for palettes 1 to 7 ) can be recorded.
Recorded normal/reverse settings can be called from PID selection ("PLN1") in the operation mode.

| Range | Control operation |
| :--- | :--- |
| RV__ | heat (reverse) / cool (none) |
| No__ | heat (normal) / cool (none) |
| RVNo | heat (reverse) / cool (normal) |
| NoRV | heat (normal) / cool (reverse) |
| RVRV | heat (reverse) / cool (reverse) |
| NoNo | heat (normal) / cool (normal) |

Related parameters: "Normal/Reverse" (CH1) (page 49)
[Setting example] Setting the normal/reverse 1 to heat (reverse)/ cool (normal) $\qquad$


## REF1 to REF7 PID palette switching point (170 to 176)

## [Description]

$\qquad$
This parameter allows you to set threshold value at which the controller automatically switches among PID palettes.

- Setting range: 0 to $100 \%$ FS

Related parameters: PID palette switching method (CH 7) (page 161)
[Setting example] Setting the PID palette switching point 1 to 30\% FS


SVMX Max SV selection number (177)
[Description] $\qquad$
Allows you to set the maximum SV number that can be selected via the USER key.

- Setting range: SV1 to SV7, LoCL, di

Related parameters: "User key assignment" (CH 7) (page 141)
[Setting example] Setting the max. SV selection number to SV4

| Display | Operating procedure |
| :---: | :---: |
| 245 250 sv | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the () key to access CH2 (PID palette parameters). |
| S V 1 ${ }^{\text {Pv }}$ | 4. Press the SEL key to enter CH2 (PID palette parameters). SV1 (set value) is displayed. |
| S VMX pv <br> SV7 sv | 5. Use the ©() keys to change SV1 to SVMX. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| SV4 ${ }^{\text {sv }}$ | 7. Use the $(\mathbb{C}$ ( keys to change SV7 to SV4. <br> 8. Press the SEL key to save the change. |
|  | 9. Press the () key to return to the PV/SV display. |

## PL1M Max PID selection number (178)

## [Description]

$\qquad$
Allows you to set the maximum PID number that can be selected via the USER key.

- Setting range: Pid1 to Pid7, LoCL, di

Related parameters: "User key assignment" (CH 7) (page 141)
[Setting example] Setting the max. PID selection number to PID6 $\qquad$

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{pv} \\ 250 \end{array}$ | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the key to access CH 2 (PID palette parameters). |
|  | 4. Press the SEL key to enter CH2 (PID palette parameters). SV1 (set value) is displayed. |
|  | 5. Use the ©() keys to change SV1 to PL1M. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| Pid6 ${ }^{\text {sv }}$ | 7. Use the © keys to change "Pid7" to "Pid6". <br> 8. Press the SEL key to save the change. |
|  |  |

## 3-4 CH3 PRG (Ramp soak parameters)

This function automatically runs according to SVs and the times for the SV changes configured previously. You can choose up to 64 steps for SV setting and 14 types of operation patterns.

- Ramp: Changing SV towards a target SV
- Soak: Maintains a SV

The ramp/soak parameters ( CH 3 ) consists of the following function blocks.

[Description]


The 64 -step ramp/soak patterns are divided into 15 segments. You can choose any one to use.

- Setting range

| 0 | steps 1 to 8 | 8 | steps 1 to 16 |
| :--- | :--- | :--- | :--- |
| 1 | steps 9 to 16 | 9 | steps 17 to 32 |
| 2 | steps 17 to 24 | 10 | steps 33 to 48 |
| 3 | steps 25 to 32 | 11 | steps 49 to 64 |
| 4 | steps 33 to 40 | 12 | steps 1 to 32 |
| 5 | steps 41 to 48 | 13 | steps 33 to 64 |
| 6 | steps 49 to 56 | 14 | steps 1 to 64 |
| 7 | steps 57 to 64 | di | depending on di |

Note:
Do not change this parameter during the ramp soak operation. Be sure to set "PRG" = "OFF" before changing the parameter.
[Setting example] Setting the Ramp/Soak Activation Pattern to steps 1 to 8

| Display | Operating procedure |
| :---: | :---: |
| 245 PV | 1. Check that the $\mathrm{PV} / \mathrm{SV}$ display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the (\%) key to access CH3 (Ramp soak parameters). <br> 4. Press the SEL key to enter CH3 (Ramp soak parameters). PtN (Ramp soak operation pattern) is displayed. <br> 5. Press the SEL key. (The first digit of the lower part of the screen begins to blink.) <br> 6. Use the © (v) keys to change 14 to 0 . <br> 7. Press the SEL key to save the change. <br> 8. Press the (). key to return to the PV/SV display. |
| CH 3 Pv <br>  PRG sv |  |
| Pt PV <br> 14 SV |  |
| 0 sv |  |

[Description] $\qquad$
Allows you to set the time units for Ramp/soak operation.

- Setting range: $\mathrm{HH}: \mathrm{MM}$ (hour:min) MM : SS(min:sec)

Note:
Time units can not be set separately for each step.
All steps use the same unit of time.
[Setting example] Setting the time unit to MM:SS


## SV-1 to SV64 Ramp soak seg1 SV1 to seg64 SV64 (202 to 391)

tM1R to t64R Ramp soak seg1 ramp time to seg64 ramp time (203 to 392)
tM1S to t64S Ramp soak seg1 soak time to seg64 ramp time (204 to 393)

## [Description]

$\qquad$
Sets the ramp soak SV, ramp time and soak time.
Setting range:

| SV | SV lower limit (SVL) to SV upper limit (SVH) \%FS |
| :--- | :--- |
| Ramp time | $00: 00$ to $99: 59$ (hour: $\mathrm{min} / \mathrm{min}: \mathrm{sec}$ ) |
| Soak time | $00: 00$ to $99: 59$ (hour: $\mathrm{min} / \mathrm{min}: \mathrm{sec}$ ) |



- The segment that both ramp time and soak time are set to 0.00 will be skipped.
(Example)

| SV-1 $: 50$ | SV-2 $: 200$ | SV-3: 100 |
| :--- | :--- | :--- |
| TM1r $: 0.10$ | TM2r $: 0.00$ | TM3r $: 1.00$ |
| TM1S $: 0.05$ | TM2S $: 0.00$ | TM3S $: 0.75$ |



- The SV limit function (SV-h, SV-L) is in effect while ramp/soak is running.

The set value (SV-n) does not change, but the value is limited during ramp/soak. For the above reason, the value may not change at the set times and the ramp soak runs with the following pattern.

[Setting example] Setting SV1, ramp time, and soak time for step1


## Mod Ramp soak mode (394)

## [Description]

Allows you to set the method of ramp/soak operation.
The following items can be set.

| Power-on start | Starts ramp/soak with the current PV when the main unit is turned on. |
| :--- | :--- |
| END time output | Maintains the same state as at the end of ramp/soak when ramp/soak is <br> complete. |
| oFF time output | Switches to the OFF state when ramp/soak is complete. |
| Repeat operation | Repeats ramp/soak from step 1 when the last step finishes. |



- You can choose from the following 16 modes.

| MOD | Power-on start | Ending output | OFF output | Repeat behavior |
| :--- | :--- | :--- | :--- | :--- |
| 0 | none | Maintain control | Maintain control | none |
| 1 | none | Maintain control | Maintain control | on |
| 2 | none | Maintain control | Standby Mode | none |
| 3 | none | Maintain control | Standby Mode | on |
| 4 | none | Standby Mode | Maintain control | none |
| 5 | none | Standby Mode | Maintain control | on |
| 6 | none | Standby Mode | Standby Mode | none |
| 7 | none | Standby Mode | Standby Mode | on |
| 8 | on | Maintain control | Maintain control | none |
| 9 | on | Maintain control | Maintain control | on |
| 10 | on | Maintain control | Standby Mode | none |
| 11 | on | Maintain control | Standby Mode | on |
| 12 | on | Standby Mode | Maintain control | none |
| 13 | on | Standby Mode | Maintain control | on |
| 14 | on | Standby Mode | Standby Mode | none |
| 15 | on | Standby Mode | Standby Mode | on |

- When not in repeat operation, the last SV value is held when ramp/soak finishes.
[Setting example] Setting the ramp soak mode to 1

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. |
| C H 3 pv <br>  PRG sv <br>    | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the (-) key to access CH 3 (Ramp soak parameters). |
| Pt PV <br> 14 SV | 4. Press the SEL key to enter CH3 (Ramp soak parameters). PtN (Ramp soak operation pattern) is displayed. |
| M O d ${ }^{\text {PV }}$ | 5. Use the (1) () keys to change PtN to Mod. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) <br> 7. Use the (a) (v) keys to change 0 to 1 . <br> 8. Press the SEL key to save the change. |
|  |  |
|  |  |
|  |  |
|  | 9. Press the (L) key to return to the PV/SV display. |

## GSoK Guarantee soak (395)

GS-L Guarantee soak band (lower) (396)
GS-H Guarantee soak band (upper) (397)

## [Description]

This function guarantees the soak time. Soak time is counted down only when PV is in the certain temperature range.
As seen in the figure below, only the sum of the shaded areas is counted as soak time. The operation moves onto the next step when the total soak time has reached the specified soak time.


Setting range:

| Guarantee soak | on/off |
| :--- | :--- |
| Guarantee soak upper limit | 0 to $50 \%$ FS |
| Guarantee soak lower limit | 0 to $50 \%$ FS |

[Setting example] Setting guaranty soak to ON and upper/lower limits to $5^{\circ} \mathrm{C}$


| Pt N | Pv |
| ---: | ---: |
| 14 | sv |

4. Press the SEL key to enter CH3 (Ramp soak parameters). PtN (Ramp soak operation pattern) is displayed.

| G S o K <br> oFF | pv |
| ---: | ---: |
| sv |  |$|$

5. Use the ©() keys to change PtN to GSoK.
6. Press the SEL key.
(The first digit of the lower part of the screen begins to blink.)
7. Use © (v) keys to change "oFF" to " oN ".
8. Press the SEL key to save the change.


5 sv
9. Use (A) keys to change GSoK to GS-L.
10. Press the SEL key.
(The first digit of the lower part of the screen begins to blink.)
11. Use the (^) (v) keys to change 0 to 5 .
12. Press the SEL key to save the change.
13. Use (A) keys to change GS-L to GS-H.
14. Press the SEL key.
(The first digit of the lower part of the screen begins to blink.)
15. Use the (^) (v) keys to change 0 to 5 .
16. Press the SEL key to save the change.
17. Press the (5) key to return to the $\mathrm{PV} / \mathrm{SV}$ display.

## PVSt PV start (398)

## [Description]

$\qquad$
When the ramp soak starts (RUN), this function searches the first point where the measurement value (PV) and the program pattern match, and starts operation at that point.
If the measurement value does not match the pattern as with (3), the normal operation starts.


Setting range: oN (PV start on), oFF (PV start off)
[Setting example] Setting PV start to ON

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the key to access CH3 (Ramp soak parameters). |
| Pt PV <br> 14 sv | 4. Press the SEL key to enter CH3 (Ramp soak parameters). PtN (Ramp soak operation pattern) is displayed. |
|  | 5. Use the ©(1) keys to change PtN to PVSt. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| ON $\mathrm{sv}^{\text {d }}$ | 7. Use © (V) keys to change " oFF " to " oN ". <br> 8. Press the SEL key to save the change. |
|  | 9. Press the () key to return to the PV/SV display. |

[Description] $\qquad$
This parameter specifies the ramp soak operation when the power is restored after being interrupted due to power outage or other reasons.
Setting range
RES: Does not operate ramp soak.
CoN : Resumes the operation from the status of the time at which power is turned off. (It can restore the state to five minutes before maximum.)
iNi: Starts the Ramp/Soak from the first step again.
Note:
Do not change this parameter during the ramp soak operation. Be sure to set "PRG" = "oFF" before changing the parameter.
[Setting example] Setting the restore mode so that the device resumes the operation

| Display | Operating procedure |
| :---: | :---: |
| 245 pv | 1. Check that the PV/SV display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the (1) key to access CH 3 (Ramp soak parameters). <br> 4. Press the SEL key to enter CH3 (Ramp soak parameters). PtN (Ramp soak operation pattern) is displayed. <br> 5. Use the (1) keys to change PtN to CoNt. <br> 6. Press the SEL key. (The first digit of the lower part of the screen begins to blink.) <br> 7. Use © © keys to change "RES" to "CoNt". <br> 8. Press the SEL key to save the change. <br> 9. Press the (ㄴ) key to return to the PV/SV display. |
| H 3 PV <br>  PRG SV |  |
| P PV <br> 14 SV |  |
| Cov  <br> RES  <br> $N V$  |  |
| CoNt sv |  |
|  |  |

## PtNM Max pattern selection (400) <br> PMiN Min pattern selection (401)

## [Description]

$\qquad$
Sets the max./min. pattern number that can be selected when proceeding the Ramp/soak activation pattern with USER keys.

- Setting range: 0 to 14
- Related parameters: Ramp soak operation pattern (CH 3) (page 71)

User key assignment (CH 7) (page 141)

## Note:

Do not set a value for Min pattern selection that is larger than the value for Max pattern selection.
[Setting example] Setting the min. number to 2 and max. number to 4

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the (\%) key to access CH 3 (Ramp soak parameters). <br> 4. Press the SEL key to enter CH3 (Ramp soak parameters). PtN (Ramp soak operation pattern) is displayed. <br> 5. Use the © (®) keys to change PtN to PtNM. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) <br> 7. Use the (A) keys to change 14 to 4 . <br> 8. Press the SEL key to save the change. <br> 9. Use the ©() keys to change PtNM to PMiN. <br> 10. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) <br> 11. Use the (^) keys to change 0 to 2 . <br> 12. Press the SEL key to save the change. <br> 13. Press the key to return to the PV/SV display. |
| H 3 pv <br>  PRG sv |  |
| P PV <br> 14 SV |  |
| P $\mathbf{N M}$ pv <br> 14 sv |  |
| 4 sv |  |
| PM i N PV <br>  0 SV |  |
| 2 sv |  |
|  |  |

## 3-5 CH4 MON (Monitor parameters)

## StAt Ramp soak progress (420)

[Description] $\qquad$
Displays the progress of the ramp soak.
The ramp soak status are indicated as follows.

| Display | Status |
| :--- | :--- |
| oFF | Ramp soak is stopped |
| 1-RP | Step 1 ramp |
| 1-St | Step 1 soak |
| 2-RP | Step 2 ramp |
| 2-St <br> $\vdots$ <br> 64RP | Step 2 soak <br> $\vdots$ <br> Step 64 ramp |
| 64St | Step 64 soak |
| ENd | Ramp soak is finished |

Related parameters: Ramp soak parameters (CH 3) (page 70)
[Setting example] Checking ramp soak progress

| Display |  | Operating procedure |
| :---: | :---: | :---: |
| 245 | PV | 1. Check that the PV/SV display is shown. |
| CH4 <br>  <br>  <br>  <br> $M o N$ | PV SV | 2. Press and hold the SEL key to display CH1 (PID parameters). |
| $\begin{array}{r} \mathrm{Stt} \\ \mathrm{oFF} \end{array}$ | PV | 4. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. |
| 5. Press the ( ) key to return to the PV/SV display. |  |  |

MV1, MV2 Control output (MV1, MV2) $(421,422)$

## [Description]

$\qquad$
Displays the output values (OUT1/OUT2).
[Setting example] Checking the output value (OUT1)

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{PV} \\ 250 & \mathrm{SV} \end{array}$ | 1. Check that the PV/SV display is shown. |
| CH $\mathbf{4}$ pv <br>  MoN sv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH4 (Monitor parameters). |
| Stat oFF t | 4. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. |
| MV 1 pv <br> 58.4 sv | 5. Use the ©() keys to change StAt to MV1. <br> The output value of OUT1 is displayed. <br> 6. Repeat the same steps to check the output value of OUT2. |
|  | 7. Press the ( ) key to return to the PV/SV display. |

## PFb PFB input value (423)

## [Description]

Motorized valve opening will be displayed when using position feedback (PFB) as the control.
[Setting example] Checking the PFB input value

| Display | Operating procedure |
| :---: | :---: |
| 245 Pv | 1. Check that the PV/SV display is shown. |
| CH $\mathbf{4}$ PV <br>  MoN sV | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH4 (Monitor parameters). |
|  | 4. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. |
| P F b ${ }^{\text {Pv }}$ | 5. Use the ©(1) keys to change "StAt" to "PFb". The input value for PFB is displayed. |
|  | 6. Press the () key to return to the PV/SV display. |

## [Description]

Displays the remote SV input value.
[Setting example] Checking the remote SV input value

| Display | Operating procedure |
| :---: | :---: |
| 245 Pv | 1. Check that the PV/SV display is show $n$. <br> 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the (1) key to access CH 4 (Monitor parameters). <br> 4. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. <br> 5. Use the © (1) keys to change "StAt" to "RSV". The input value for remote SV is displayed. <br> 6. Press the (b) key to return to the PV/SV display. |
|  |  |
|  |  |
| $\begin{array}{rr}\text { R S V } & \text { pv } \\ 17.5 & \\ \text { sv }\end{array}$ |  |
|  |  |

## Ct1 <br> Heater current (425)

## [Description]

Display the Heater current value.
(The current value measured during the control output 1 is ON is indicated.)
[Setting example] Checking the heater current value


## LC1 Leak current (427)

## [Description]

$\qquad$
Display the Leak current value.
(The current value measured during the control output 1 is OFF is indicated.)
[Setting example] Checking the leak current value

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{Pv} \\ 250 \end{array}$ | 1. Check that the PV/SV display is shown. |
| C H <br>  <br>  <br>  <br>  <br> MoN sv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH4 (Monitor parameters). |
| Stat $\mathrm{At}^{\text {t }}$ oFF | 4. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. |
| L C 1 pv | 5. Use the (a) keys to change "StAt" to "LC1". The leak current value is displayed. |
|  | 6. Press the () key to return to the PV/SV display. |

tM 1 to tM5 Remaining time on timer (429 to 433)
[Description]
Displays the remaining time on timer.
Related parameters: ALM hysteresis, ALM delay, ALM delay time units (CH 5) (page 100)
[Setting example] Checking the remaining time on the timer 1

| Display | Operating procedure |
| :---: | :---: |
| 245 PV | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH4 (Monitor parameters). |
|  | 4. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. |
| t M 1PV  <br> 8 SV | 5. Use the ©() keys to change StAt to tM 1 . <br> The remaining time on the timer 1 is displayed. |
|  | 6. Repeat the same steps to check the remaining times of the timer2 and the timer 3. <br> 7. Press the key to return to the PV/SV display. |

## CoMM Communication status (435)

## [Description]

$\qquad$
Counts the number of communication times.
If the counter has reached 9999, it restarts counting from zero.
[Setting example] Checking the count $\qquad$

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{PV} \\ 250 & \mathrm{sV} \end{array}$ | 1. Check that the PV/SV display is shown. |
| C 4 pv <br>  MoN sv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH4 (Monitor parameters). |
| $\begin{array}{r\|r\|} \hline \text { Stat Av } & \text { pv } \\ \text { oFF } & \text { sv } \end{array}$ | 4. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. |
| C o MMPV  <br> 0 SV | 5. Use the ©() keys to change StAt to CoMM. Communication count is displayed. |
|  | 6. Press the (b) key to return to the PV/SV display. |

## CUR1 Current (436)

[Description]
Displays the electric current value measured with CT.
(The value is independent of the control output 1.)
[Setting example] Checking the leak current value


## PoW Electric power (438)

## [Description]

Displays the calculated amount of electric power (kW).
[Setting example] Checking the electric power

| Display | Operating procedure |
| :---: | :---: |
| 245 pv | 1. Check that the PV/SV display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters) <br> 3. Use the (1) key to access CH 4 (Monitor parameters). <br> 4. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. <br> 5. Use the ©() keys to change "StAt" to "PoW". <br> The electric power is displayed. <br> 6. Press the () key to return to the PV/SV display. |
| C H <br>  <br>  <br>  <br>  <br> MoN sv |  |
| St A t oFF |  |
| PoW ${ }^{\text {pv }}$ |  |
|  |  |

[Description]
Displays the calculated amount of electric power.
[Setting example] Checking the amount of electric power

| Display | Operating procedure |
| :---: | :---: |
| 245 PV <br> 250 SV | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH4 (Monitor parameters). |
| $\begin{array}{r\|r\|} \mathrm{oFF} & \mathrm{sv} \\ \mathrm{st} \end{array}$ | 4. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. |
| KWH pv <br> 1.2 sv | 5. Use the (1) keys to change StAt to KWH. The amount of electric power is displayed. |
|  | 6. Press the (b) key to return to the PV/SV display. |

## RCN1, RCN2 Number of operating times $(440,441)$

## [Description]

$\qquad$
Displays the number of times that control output relay 1 or 2 has operated.
The number is displayed in increments of 1000 .
(For example, when 1 is displayed, it means the relay has operated 1000 times.)
[Setting example] Checking the number of operating times (control relay 1)

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the (1) key to access CH4 (Monitor parameters). <br> 4. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. <br> 5. Use the (1) keys to change StAt to RCN1. <br> The number of times that control output relay 1 has operated is displayed. <br> 6. Repeat the same steps to check the number of operating times of control output relay 2. <br> 7. Press the (b) key to return to the PV/SV display. |
| $\begin{array}{lr\|r} \mathrm{CH} & 4 & \mathrm{Pv} \\ & \mathrm{MoN} & \mathrm{sv} \end{array}$ |  |
| Stat oFF |  |
| RCN1 ${ }^{\text {PV }}$ |  |
|  |  |

[Description]
Displays the number of days that the temperature controller has been operated.
[Setting example] Checking the number of days the controller has operated


## FALt Error source (443)

## [Description]

$\qquad$
Displays the source of an error. (with hexadecimal number)

| 0 bit | PV input underflow (LLLL) |
| :--- | :--- |
| 1 bit | PV input overflow (UUUU) |
| 2 bit | PV under range |
| 3 bit | PV over range |
| 4 bit | RSV under range |
| 5 bit | RSV over range |
| 6 bit | Range setting error |
| 8 bit | PV input circuit error |
| 9 bit | RSV input circuit error |
| 10 bit | CT \& PFB input circuit error |
| 11 bit | PFB input underrange |
| 12 bit | PFB input overrange |

[Setting example] Checking the error source

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{PV} \\ 250 & \mathrm{sV} \end{array}$ | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH4 (Monitor parameters). |
| $\begin{array}{cc} \mathrm{St} & \mathrm{At} \\ \mathrm{oFF} & \mathrm{sv} \end{array}$ | 4. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. |
| $\begin{array}{r} \text { FALt } \\ 0000 \end{array}$ | 5. Use the © (1) keys to change StAt to FALt. <br> The error source is displayed. (with hexadecimal number) |
|  | 6. Press the (4) key to return to the PV/SV display. |

## Di DI input state (444)

## [Description]

Displays the state of DI (with hexadecimal number).

| 0 bit | DI 1 |
| :--- | :--- |
| 1 bit | DI 2 |
| 2 bit | DI 3 |
| 3 bit | DI 4 |
| 4 bit | DI 5 |

[Setting example] Checking the DI input state

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{PV} \\ 250 & \mathrm{sV} \end{array}$ | 1. Check that the PV/SV display is shown. |
| CH $\mathbf{4}$ pv <br>  MoN sv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH4 (Monitor parameters). |
| St At <br> oFF | 4. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. |
| d i pv <br> 0000 sv | 5. Use the ©() keys to change "StAt" to "di". The DI input state is displayed in hexadecimal. |
|  | 6. Press the () key to return to the PV/SV display. |

## ERSt Communication error station number (445)

## [Description]

$\qquad$
Shows the station number under error and the detail of error during cooperative communication or programless communication.
[Setting example] Checking the station number under communication error

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. |
| CH $\mathbf{4}$ pv <br>  MoN sv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH4 (Monitor parameters). |
| $\mathbf{S t a t}$  <br> oFF  <br>  sv | 4. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. |
| ERS t ${ }^{\text {P }}$ Pv | 5. Use the ©() keys to change "StAt" to "ERSt". <br> The station number under communication error is displayed. |
|  | 6. Press the (b) key to return to the PV/SV display. |

[Description]
Displays the PID palette No. currently selected.
[Setting example] Checking the PID number currently selected

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters) <br> 3. Use the () key to access CH 4 (Monitor parameters). <br> 4. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. <br> 5. Use the © (N keys to change "StAt" to "PLNo". The PID number currently selected is displayed. <br> 6. Press the (ㄴ) key to return to the PV/SV display. |
|  |  |
| Stat oFF A |  |
| P L O <br> LoCL |  |
|  |  |

## [Description]

$\qquad$
Displays the ramp soak pattern No. currently selected.
[Setting example] Checking the pattern number currently selected

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r\|} \hline 245 & \mathrm{pv} \\ 250 & \mathrm{sv} \end{array}$ | 1. Check that the PV/SV display is shown. |
| CH $\mathbf{4}$ pv <br>  MoN sv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH4 (Monitor parameters). |
| Stav  <br> oFF  <br> Pv  | 4. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. |
| PtNo LoCL | 5. Use the ©() keys to change "StAt" to "PtNo". The currently selected pattern number is displayed |
|  | 6. Press the ( () $^{\text {key to return to the PV/SV display. }}$ |

## 3-6 CH5 ALM (Alarm parameters)

The alarm parameters (CH5) consists of the following function blocks.


PXF4 can use ALM1 to ALM3.
PXF5/9 can use ALM1 to ALM5.
Alarm threshold values are set under ALM1 to ALM5 in the Operation control parameters.

A1tP to A5tP Alarm type (470, 475, 480, 485, 490)
[Description]
Set the alarm type for ALM1 to ALM5.
You can select the alarm type from the below tables.

## 1-point alarm



2-point alarm


What is alarm with hold?
The alarm will not turn ON immediately when the process value gets into the alarm band and enters again.


Note:

- When alarm action code is changed, alarm set value may also become different from previous settings.
- When alarm action type code is changed, turn off the power once, and then re-start the controller, before starting control.
- ALn: indicates the alarm set values (AL1 to AL5).
- ALnh: indicates the alarm set values (A1-H to A5-H).
- ALnL: indicates the alarm set values (A1-L to A5-L).
- dLYn: indicates the alarm delay set values (dLY1 to dLY5).

You can assign different event output functions for DO1 to DO5, other than alarm functions.
Refer to "CH. 7 OUT, DO, and LED indicator assignment" for event output functions.
[Setting example] Setting the type of the alarm 1 to "upper limit deviation alarm with hold"

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the (-) key to access CH5 (Alarm parameters). <br> 4. Press the SEL key to enter CH5 (Alarm parameters). A1tP (alarm type) is displayed. <br> 5. Press the SEL key. (The first digit of the lower part of the screen begins to blink.) <br> 6. Use the (a) (veys to change 0 to 8 . <br> 7. Press the SEL key to save the change. <br> 8. Repeat the same steps to set the type for the alarm 2 to the alarm 3. <br> 9. Press the (L) key to return to the PV/SV display. |
|  |  |
| A 1 t P ${ }^{\text {P }}$ PV |  |
| 8 sv |  |
|  |  |

A1HY to A5HY Alarm hysteresis (471, 476, 481, 486, 491)
dLY1 to dLY5 Alarm delay $(472,477,482,487,492)$
dL1U to dL5U Alarm delay time units (473, 478, 483, 488,493)

## [Description]

Alarm parameter settings are as follows:

| Alarm hysteresis | Specifies alarm detection width and recovery width. <br> Setting range: 0 to $50 \%$ FS |
| :--- | :--- |
| Alarm delay time | Specifies the amount of time from the occurrence of the alarm to the <br> sounding of the alarm. <br> Setting range: 0 to $9999(\mathrm{sec} / \mathrm{min})$ |
| Alarm delay time units | Specifies the unit of time ( $\mathrm{sec} / \mathrm{min})$ used for the alarm delay <br> Setting range: $\mathrm{sec} / \mathrm{min}$ |

The alarm and hysteresis are related as follows.

[Setting example ] Setting the Alarm 1 hysteresis to $5^{\circ} \mathrm{C}$, delay time to 30, and delay time unit to seconds

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. |
| H 5 PV <br>  ALM sv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH5 (Alarm parameters). |
|  | 4. Press the SEL key to enter CH5 (Alarm parameters). A1tP (alarm type) is displayed. |
| A 1 HY pv  <br>  1 sV | 5. Use the ©() keys to change A1tP to A1HY. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 5 sv | 7. Use the (1) keys to change 1 to 5 . <br> 8. Press the SEL key to save the change. |
| d L Y 1 pv  <br>  0 sv | 9. Use the ©() keys to change A1HY to dLY1. <br> 10. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 30 sv | 11. Use the © © (จ) keys to change 0 to 30 . 12. Press the SEL key to save the change. |
| d L 1 U ${ }_{\text {d }}$ PV | 13. Use the ©() keys to change dLY1 to dL1U. <br> 14. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| SEC $\mathrm{sv}^{\text {a }}$ | 15. Use the © (© keys to change MiN to SEC. <br> 16. Press the SEL key to save the change. <br> 17. Repeat the same steps to set the hysteresis, delay time, and delay time unit for the alarm 2 to the alarm 3 . |
|  | 18. Press the ( ) key to return to the PV/SV display. |

## [Description]

$\qquad$
You can set the optional functions to the alarm 1 to the alarm 5, if you need. The four types of optional functions are assigned for each bit.

- Setting range: 0000 to 1111

The inverted output alarm can be imitated in software by changing from SPST contact to SPDT contact. It becomes SPST contact when power is cut.
Alarms are set per bit.


| bit | Function | Description |
| :--- | :--- | :--- |
| bit 0 | Alarm latch | Latches (maintains) the state when an event occurs. |
| bit 1 | Input error alarm | Outputs when an input error ("UUUU" or "LLLL" is displayed) occurs. <br> Set the alarm type to "0" to use this function. |
| bit 2 | Inverted output function | Inverts the output and outputs from the DO terminal when an event <br> occurs. |
| bit 3 | Hold reset function | When an alarm with hold is applied, the hold function is reset when <br> any of the following actions occur: <br> SV change/alarm type change/alarm set value change/standby cancel// <br> power off and on |

[Setting example] Adding the alarm latch and the converted output function to the alarm 1

\begin{tabular}{|c|c|}
\hline Display \& Operating procedure \\
\hline \[
\begin{array}{r|r}
245 \& \mathrm{PV} \\
250 \& \mathrm{sV}
\end{array}
\] \& 1. Check that the PV/SV display is shown. \\
\hline \begin{tabular}{lr|l|}
\hline \& CH \& 5 \\
\& ALM \& sv \\
\& \&
\end{tabular} \& \begin{tabular}{l}
2. Press and hold the SEL key to display CH1 (PID parameters). \\
3. Use the () key to access CH 5 (Alarm parameters).
\end{tabular} \\
\hline A 1 t P \({ }^{\text {P }}\) PV \& 4. Press the SEL key to enter CH5 (Alarm parameters). AltP (alarm type) is displayed. \\
\hline A OP 1
P
0000

pv \& | 5. Use the ©() keys to change A1tP to AoP1. |
| :--- |
| 6. Press the SEL key. |
| (The first digit of the lower part of the screen begins to blink.) | <br>

\hline 0101 sv \& | 7. Use the (1) keys to change 0000 to 0101 . |
| :--- |
| 8. Press the SEL key to save the change. | <br>


\hline \& | 9. Repeat the same steps to set the optional functions for the alarm 2 to the alarm 3. |
| :--- |
| 10. Press the () key to return to the $\mathrm{PV} / \mathrm{SV}$ display. | <br>

\hline
\end{tabular}

## Hb1 Heater break alarm set value (500)

Hb1H Heater break alarm hysteresis (501)

## [Description]

$\qquad$
This function controls whether the heater break alarm is active.
The heater break alarm includes the following settings:

| Heater break alarm Settings | The electric current set value at which the alarmtrips. <br> - Range: 0.0 A to 100.0 A |
| :--- | :--- |
| Heater break alarm hysteresis | The detection and recovery width of the heater break alarm hysteresis. <br> - Range: 0.0 A to 100.0 A |

- The following connection diagram includes CT connections.



## Note:

- This is not used when the heater is controlled by thyristor phase angle control.
- When the margin of error is large due to low heater capacity, the problem is resolved by doubling the current to increase the sensitivity. (Be sure to double the setting value in such cases.)
- If there are multiple CTs, make sure to use the same procedure for each of them.

- The heater break detector CT is connected as shown below:
- The heater break alarm is effective only for a singlephase power supply. It cannot be used for a threephase power supply.
- The heater current detection is available only after the control output 1 has been working for at least 0.3 seconds.
- The heater break alarm is not available when the control output 1 is current or voltage output.
[Setting example ] Setting the HB alarm to 5A and the HB alarm hysteresis to 2A

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r} 245 \\ 250 \end{array}$ | 1. Check that the PV/SV display is shown. |
|  | 2. Switch to manual mode. <br> (Refer to "Auto/manual switchover" on page 29.) |
| $24 \frac{\mathrm{MNU}}{2}$ | 3. In MV display, use the © key to set the control output (MV) to $100 \%$. |
| CH $\mathbf{4}$ PV <br>  MoN sv | 4. Press and hold the SEL key to display CH1 (PID parameters). <br> 5. Use the © key to access CH 4 (Monitor parameters). |
| StAt oFF | 6. Press the SEL key to enter CH4 (Monitor parameters). StAt (Ramp soak progress) is displayed. |
| C 1 Pv <br> 7.1 sv | 7. Use the ©() keys to change "StAt" to "Ct1" (heater current). <br> Check the value of CT1. <br> (The appropriate trigger value for HB alarm is 70 to $80 \%$ of the current value.) |


[Description] $\qquad$
These are the functions to detect short-circuiting of the SSR or Conductor.
The setting items of the load short-circuit alarm are as follows:

| Load shortcircuit alarm <br> setting | Sets the electrical current value at which to detect a load short-circuit alarm. <br> $\bullet$ Range: 0.0 to 100.0 A |
| :--- | :--- |
| Load shortcircuit alarm <br> hysteresis | Sets the space between the detection and restoration of the load short-circuit <br> alarm. <br> • Range: 0.0 A to 100.0 A |

- The current detection is available only after the control output 1 has been inactive for at least 0.3 seconds.
- The shorted-load alarm is not available when the control output 1 is current or voltage output.
[Setting example ] Setting the shorted-load alarm set value to 5A and the shorted load alarm hysteresis to 2A



## LbtM Loop break detection time (508) <br> LbAb Loop break detection range (509)

## [Description]

$\qquad$
This function detects if the control loop is broken.
This function does not use a CT like the heater break alarm, while instead it checks the change of control output and PV to determine if the loop is broken.
The loop break detector has the following functions.

| Loop break detection time | Specifies how much time must pass before the loop is determined to be <br> broken. <br> Setting range: 0 to 9999 sec. |
| :--- | :--- |
| Loop break detection <br> range | Sets the temperature range before detecting a broken loop <br> Setting range: 0.0 to $100.0 \%$ FS |

Loop break detection time and width are related as follows:
Example of Loop Break Detection in Reverse Operation


Note:
If there is an abnormal input (UUUU, LLLL) or an input setting error (Err), the alarm sounds even before the loop break detection time period.
[Setting example] Setting the loop break detection time to 600 sec . and detection range to $20^{\circ} \mathrm{C}$


## WHAL Electricity alarm (511)

## [Description]

$\qquad$
Allows you to set the value for electricity alarm.
The electricity alarm will be activated when the amount of electric power has reached the setpoint.

- Setting range

| Decimal point position for <br> electric power $(\mathrm{WdP})$ | Setting range |
| :--- | :--- |
| 0 | 0 to 9999 kWh |
| 0.1 | 0.0 to 999.9 kWh |
| 0.01 | 0.00 to 99.99 kWh |
| 0.001 | 0.000 to 9.999 kWh |

[Setting example] Setting the electricity alarm to 20.0 kWh


## 3-7 CH6 SET (Setup parameters)

PVt PV input type (530)
[Description] $\qquad$
Allows you to select PV input source from thermocouples, RTD, and others.
Note:

- The connection to the terminal block differs with types of input (thermocouple/RTD/voltage or current input). Check the Instruction Manual.
[Setting example] Changing the input from thermocouple K to thermocouple R

[Description] $\qquad$
Allows you to set the upper/lower limit of PV input within the measurement range.
Setting range: -1999 to 9999


Note:

- Be sure to set the values so that PVF is greater than PVb.
- Be sure to set the values so that the subtraction of PVb from PVF is less than 10000 with no decimal point.
[Setting example] Setting the PV input upper limit to $1000^{\circ} \mathrm{C}$ and lower limit to $200^{\circ} \mathrm{C}$



## PVd Decimal point position (533)

## [Description]

Sets the decimal point position for the PV.

- Setting range 0: No digit after decimal point

1: 1 digit after decimal point
2: 2 digit after decimal point
3: 3 digit after decimal point
8, 8, 8

- Two, three decimal places are available only when the input is voltage/current.
- If you change the setting from numerals without decimal point to numerals with decimal point, the measurement range is limited to the range from $-199.9^{\circ} \mathrm{C}$ through $999.9^{\circ} \mathrm{C}$. For example, if you make the above change when the range is from 0 through $1300^{\circ} \mathrm{C}$, the range will become the one from 0.0 through $999.9^{\circ} \mathrm{C}$.
[Setting example] Setting the PV display with one decimal place



## CUt Square-root extractor cut point (535)

## [Description]

$\qquad$

## Square root extractions

- To convert differential pressure to flow rate, square root extraction is used.

Where the differential pressure is small, the differential pressure to the router cut point is handled as zero, because under such a condition flow fluctuation or noise affects largely on readings.


Setting range: -0.1 to $105.0 \%$ (Setting $-0.1 \%$ cancels square root extraction)
[Setting example] Setting the cut point to 1.0


## PVoF PV input shift (536)

[Description] $\qquad$
This function shifts PV input before display.
This function can be used to make the SV value correspond with other instruments.

- Setting range: -10 to $10 \%$ FS

[Setting example] Setting the PV input shift to $-5.0^{\circ} \mathrm{C}$



## SVoF SV shift (537)

## [Description]

$\qquad$
This function specifies the SV shift.
This is used to eliminate remaining offset when using $P$ control.

- Controls act on the calculated SV with SV offset.
- Alarm determination acts on the displayed SV without SV offset.
- Range: -50\% to 50\%
[Setting example] Setting the SV shift to $7^{\circ} \mathrm{C}$

| Display | Operating procedure |
| :---: | :---: |
| 245.0 pv <br> 250.0 sv | 1. Check that the PV/SV display is shown. |
| CH 6 <br>   <br>  SEt <br>  sv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the () key to access CH6 (Setup parameters). |
| P V t ${ }^{\text {pv }}$ pr | 4. Press the SEL key to enter CH 6 (Setup parameters). PVt ( PV input type) is displayed. |
| $\begin{array}{r}\text { S V o F } \\ 0.0 \\ 0.0 \\ \hline\end{array}$ | 5. Use the © () keys to change "PVt" to "SVoF". <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| $7.0{ }^{\text {sv }}$ | 7. Use the $\mathbb{( 1 )}$ keys to change " 0.0 " to " 7.0 ". <br> 8. Press the SEL key to save the change. |
|  | 9. Press the () key to return to the PV/SV display. |

## tF PV input filter (538)

## [Description]

This low-pass filter function reduces noise and signal fluctuation.

- Setting range: 0.0 to 120.0 sec . (input filter time constant)


If the input filter time constant is set to 5 and input is changed from 0 to $100 \%$, the PV display gradually changes, and it takes about 5 seconds for the value to change from 0 to $63.2 \%$, as shown in the figure below.


Note:
The factory setting for input filter time constant is $5 \%$. Do not change this value unless absolutely necessary.
[Setting example] Setting the PV input filter time constant to 10 seconds

| Display | Operating procedure |
| :---: | :---: |
| $2 \begin{array}{r}45 \\ 250\end{array}$ | 1. Check that the PV/SV display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the () key to access CH 6 (Setup parameters). <br> 4. Press the SEL key to enter CH 6 (Setup parameters). PVt ( PV input type) is displayed. <br> 5. Use the (^) keys to change PVt to tF. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) <br> 7. Use the ©(ㄷ) keys to change 5 to 10 . <br> 8. Press the SEL key to save the change. <br> 9. Press the (b) key to return to the PV/SV display. |
|  |  |
| P V t <br> K1 |  |
| t F PV  <br>  5 sV |  |
| 10 sv |  |
|  |  |

AdJO PV display zero adjustment (539)
AdJS PV display span adjustment (540)
[Description]
This is the procedure for adjusting the PV display zero/span.
Set the following equipment before using these parameters or starting revisions.

- mv Generator

1 V to 5 V (for voltage/current input)
0 mV to 100 mV (for thermocouple input)

- Dial resistance unit
100.0 to 400.0 (for resistance thermometer bulb input)
- Range: $-50.0 \%$ to $50.0 \%$ FS (zero/span)


Note:

- Set the zero/span adjustment value to "0" to restore the factory setting.
- The user correction function operates independently from the controller adjustment value. Setting this value to 0 returns the settings to the factory settings.



## Caution:

Be sure to set the cold junction compensation back to "ON" when using thermocouple input.

## RCJ Cold junction compensation (541)

## [Description]

$\qquad$
This is the procedure for turning cold junction compensation on or off when using input from a thermocouple sensor.
This setting should be left "ON" during normal operation. It should oly be turned off when cold junction compensation is being performed externally or you wish to record temperature differences.

- Range oN: Cold junction compensation on oFF: Cold junction compensation off
[Setting example] Setting the cold junction compensation to OFF

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the () key to access CH 6 (Setup parameters). <br> 4. Press the SEL key to enter CH6 (Setup parameters). PVt ( PV input type) is displayed. <br> 5. Use the © keys to change "PVt" to "RCJ". <br> 6. Press the SEL key. <br> 7. Use the ©() keys to change "oN" to "oFF". <br> 8. Press the SEL key to save the change. <br> 9. Press the (L) key to return to the PV/SV display. |
|  |  |
| PVt  <br> $\mathrm{K1}$ PV |  |
|  |  |
| oFF sv |  |
|  |  |

## REMO Remote SV zero adjustment (543) <br> REMS Remote SV span adjustment (544)

## [Description]

This function adjusts remote SV zero/span.
Use this function to match zero/span to an output gauge.

- Range: $-50 \%$ to $50 \%$ FS (zero/span)

If the input range is 1 V to 5 V , zero and span adjustment shall be as follows.

[Setting example] Adjusting zero and span in PV display

| Display | Operating procedure |
| :---: | :---: |
| 245 250 PV | 1. Confirm the accuracy of PV display by checking PV display when an output gauge or a dial resistor is set to $0 \%$ and $100 \%$. This example assumes a zero deviation of $-5 \%$ and a span deviation of $7 \%$. <br> See "Remote SV" on page 85. <br> 2. Check that the PV/SV display is shown. <br> 3. Press and hold the SEL key to display CH1 (PID parameters). <br> 4. Use the (\%) key to access CH 6 (Setup parameters). |
|  | 5. Press the SEL key to enter CH6 (Setup parameters). PVt ( PV input type) is displayed. |
|  | 6. Use the ©(1) keys to change "PVt" to "REM0". <br> 7. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) <br> 8. Use the © () keys to change " 0 " to " 5 ". <br> 9. Press the SEL key to save the change. |
| REMS PV <br> 0 sv <br> -7 sv | 10. Use the © (1) keys to change "PVt" to "REMS". <br> 11. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) <br> 12. Use the © keys to change " 0 " to " -7 ". <br> 13. Press the SEL key to save the change. <br> 14. Press the (ㄴ) key to return to the PV/SV display. <br> 15. By using a device on output side, input the values corresponds to $0 \%$ and $100 \%$ to check errors of remote SV display. Fix the errors, if any. |

## REMR Remote SV input range (545)

[Description]
This is the procedure for specifying the remote SV input range.

- Range $0-5 \mathrm{~V}: 0 \mathrm{~V}$ to 5 V
$1-5 \mathrm{~V}: 1 \mathrm{~V}$ to 5 V
$0-10$ : 0 V to 10 V
$2-10: 2 \mathrm{~V}$ to 10 V
[Setting example] Setting the remote SV input range to $0-5 \mathrm{~V}$



## RtF Remote SV input filter (546)

## [Description]

$\qquad$
This low-pass filter function reduces noise and signal wavering.

- Range: 0.0 sec to 120.0 sec (input filter damping)


When the input suddenly steps from $0 \%$ to $100 \%$ with the input filter constant set to 5 seconds, the remote SV display will change slowly and take 5 seconds to change from $0 \%$ to $63.2 \%$.


Note:
The factory setting for input filter damping is $5 \%$. Do not change this unless absolutely necessary.
[Setting example] Setting the remote SV input filter to 10.0 s

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. |
| CH 6 pv <br>  SEt sv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the () key to access CH 6 (Setup parameters). |
| P V t Pv <br> K 1 sv | 4. Press the SEL key to enter CH 6 (Setup parameters). $\mathrm{PVt}(\mathrm{PV}$ input type) is displayed. |
| R t F pv <br> 0.0 sv | 5. Use the $\mathrm{C}^{()}$keys to change "PVt" to "RtF". <br> 6. Press the SEL key. |
| 10.0 sv | 7. Use the $)^{() \text {( keys to change " } 0.0 \text { " to " } 10.0 \text { ". }}$ <br> 8. Press the SEL key to save the change. |
|  | 9. Press the () key to return to the PV/SV display. |

[Description] $\qquad$
Allows you to set the range of the control output 1(OUT1, OUT2).

- Setting range
$0-5 \mathrm{~V}: 0$ to 5 V
$1-5 \mathrm{~V}: 1$ to 5 V
0-10: 0 to 10 V
2-10: 2 to 10 V
0-20: 0 to 20 mA
4-20: 4 to 20 mA


## Note

If you have selected current output for the output 1 and the output 2 in model selection, do not set this parameter to $0-5 \mathrm{~V}, 1-5 \mathrm{~V}, 0-10$, or $2-10$.
If you have selected voltage output for the output 1 and the output 2 in model selection, do not set this parameter to $0-20$ or 4-20. Wrong settings may cause malfunction.
[Setting example] Setting OUT1 range to 0-20 mA

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{PV} \\ 250 & \mathrm{SV} \end{array}$ | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH6 (Setup parameters). |
| PV t  <br> K 1 Pv | 4. Press the SEL key to enter CH6 (Setup parameters). PVt (PV input type) is displayed. |
| C1 R Pv <br> $4-20$  <br> Sv  | 5. Use the ©() keys to change PVt to C1R. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 0-20 sv | 7. Use the ©() keys to change " $4-20$ " to " $0-20$ ". <br> 8. Press the SEL key to save the change. |
|  | 9. Press the () key to return to the PV/SV display. |

[Description] $\qquad$
Allows you to specify the control output values when the controller falls into FALT (input error).

- Setting range: $-5.0 \%$ to $105.0 \%$ (OUT1/OUT2)
[Setting example] Setting the OUT1/OUT2 during FALT to 5\%



## SFtM Soft start set time (553)

## [Description]

This function controls the maximum output produced when turning on the equipment (including the temperature controller). The controls place an upper limit on the output for a set time period after the power is turned on. This function is useful for effects such as suppressing the heater output during equipment startup, or lightening the load. After the specified time has passed after switching on the equipment (or if SFTM = 0), the soft start function ends and normal controls begin.

| Parameter | Function |
| :--- | :--- |
| SFo1 | OUT1 is limited for the time period specified in SFTM after the power is <br> turned on. |
| SFTM (in hh:mm) | Sets the time for soft start to function after turning power on. <br> Setting "0" will turn off soft start. |



During manual mode, the manual output value has priority, but soft start will continue to keep track of the set time period.

Note:
The soft start function cannot be used when there are dual outputs.
Do not use self-tuning during soft start. The soft start may not be controlled correctly.
[Setting example] Setting OUT1 during soft start to $5 \%$, and time to 30 minutes $\qquad$


Sbo1 MV1 during standby (554)
Sbo2 MV2 during standby (555)
[Description] $\qquad$
Allows you to set the control output values used during standby mode.

- Setting range: $-5.0 \%$ to $105.0 \%$ (OUT1/OUT2)
[Setting example] Setting OUT1 during standby to 5\%

| Display | Operating procedure |
| :---: | :---: |
| 245 PV | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH6 (Setup parameters). |
| P V  <br> K 1 sv | 4. Press the SEL key to enter CH6 (Setup parameters). PVt (PV input type) is displayed. |
| S b o 1 -5.0 $\mathrm{PV}^{\text {SV }}$ | 5. Use the (1) () keys to change PVt to Sbo1. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 5. 0 lv | 7. Use the ©() keys to change -5.0 to 5.0 . <br> 8. Press the SEL key to save the change. <br> 9. Repeat the same steps to set OUT2 during standby. |
|  | 10. Press the (b) key to return to the PV/SV display. |

## SbMd Standby mode (556)

## [Description]

$\qquad$
Allows you to specify the alarm action during standby.
Select the alarm action and transfer output during standby among the following four combinations.

Setting range

| SbMd | Alarm action | Transfer output |
| :--- | :--- | :--- |
| 0 | Suspends the alarm action. (alarm output OFF) | Continues to output. |
| 1 | Keeps the alarm action ON | Continues to output. |
| 2 | Suspends the alarm action. (alarm output OFF) | Outputs $-5 \%$ value. |
| 3 | Keeps the alarm action ON | Outputs $-5 \%$ value. |

[Setting example] Setting the alarm action to be continued during standby

| Display | Operating procedure |
| :---: | :---: |
| 245 Pv | 1. Check that the PV/SV display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the () key to access CH 6 (Setup parameters). <br> 4. Press the SEL key to enter CH6 (Setup parameters). $\mathrm{PVt}(\mathrm{PV}$ input type) is displayed. <br> 5. Use the (1) keys to change PVt to SbMd . <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) <br> 7. Use the (®) keys to change 0 to 1 . <br> 8. Press the SEL key to save the change. <br> 9. Press the (ㄴ) key to return to the PV/SV display. |
|  |  |
| P V t <br> K1 <br> Pv |  |
| S b M d  <br> Pv  <br> 0 Sv |  |
| 1 sv |  |
|  |  |

## Aot AO output type (557)

[Description]
This is the procedure to specify what output is retransmitted.
The following five settings are available:

- Range

Pv: Measurement
Sv: Set value
Mv: Control output
Dv: Variable (PV-SV)
PFb: Position Feedback (Do not select this if you ordered the version without PFB input.)
[Setting example] Setting the AO output type to SV

| Display | Operating procedure |
| :---: | :---: |
| 245 Pv | 1. Check that the PV/SV display is shown. |
| CH6 pv  <br>  SEt sv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH6 (Setup parameters). |
| PV  <br> K 1 sv | 4. Press the SEL key to enter CH6 (Setup parameters). PVt ( PV input type) is displayed. |
| A O t <br> PV <br> PV | 5. Use the (c) keys to change "PVt" to "Aot". <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| SV ${ }^{\text {sv }}$ | 7. Use the ©() keys to change "PV" to "SV", <br> 8. Press the SEL key to save the change. |
|  | 9. Press the (b) key to return to the PV/SV display. |

## [Description]

This is the procedure for specifying the upper and lower limits of re-transmission input.

- Range: $-100 \%$ to $100 \%$ FS (Upper/lower limit)


Calculate the set value with the following equation. (Use the example set value below as a reference.)
Set value $(\%)=(A \div B) \times 100[\%]$
$\mathrm{A}=($ Desired temperature $)-($ Set value of parameter "PVb")
B = (Set value of parameter "PVF") - (Set value of "PVb")

- When the value of the re-transmission output type (ex: SV) is equal to the AoL set value, the re-transmission output will be $0 \%$ (output).
- When the value of the re-transmission output type (ex: SV) is equal to the AoH set value, the re-transmission output will be $100 \%$ (output).


## Note:

Make sure to set the value of AoH greater than AoL.
[Setting example] Setting the AO lower scaling to -80\%, upper scaling to 80\% $\qquad$


## VoLt Fixed voltage value (561) <br> CRU Current value for simple power calculation (562) <br> iMiN Electric current nullification point (563) <br> WdP Decimal point position for electric power (564) <br> PHY Power factor for simple calculation (565)

## [Description]

These parameters are used for calculating the amount of electric power, based on the time duration that the control output relay 1 has operated.

- The amount of electric power is calculated by the following expression, with Fixed voltage value (VoLt), Current value for simple calculation (CUR), and Power factor for simple calculation (Phy).
Amount of electric energy $(\mathrm{kWh})=\Sigma$ (OUT1ON $\times$ VoLt $\times$ CUR $\times$ Phy $)$
OUT1ON: percentage of time that the control output relay 1 has operated
- The amount of electric power is displayed with the decimal point position set in Decimal point position for electric power (WdP).
- If the amount of electric power has reached the maximum value (9999) during calculation, the device restarts calculation from zero
- The calculated amount of electric power is saved on the nonvolatile memory every 5 minutes.
[Fixed voltage value (VoLt)]
Allows you to set the voltage value to be applied on the controlled device when the control output relay 1 is activated.

Setting range: 1 to 500 V
[Current value for simple power calculation (CUR)]
Allows you to set the current which flows through the controlled device when the control output relay 1 is activated. If you set to 0.0 , power calculation is carried out based on the current value measured by CT.
Setting range: 0.0 to 100.0 A
[Electric current nullification point (iMiN)]
Allows you to set the value below which the current value measured by CT to be used for power calculation is nullified.
The current value below the setpoint is treated as 0 A in power calculation.
Setting range: 0.0 A to 100.0 A
[Decimal point position for electric power (WdP)]
Allows you to set the decimal point position for electric energy. The maximum value of electric energy changes with the decimal point position.

Setting range: 0 to 3

| Decimal point position | Max. electric energy |
| :--- | :--- |
| 0 | $9999(\mathrm{kWh})$ |
| 1 | $999.9(\mathrm{kWh})$ |
| 2 | $99.99(\mathrm{kWh})$ |
| 3 | $9.999(\mathrm{kWh})$ |

[Power factor for simple calculation (PHY)]
Allows you to set the power factor for calculating electric power.
Setting range: 0.00 to 1.00
[Setting example] Setting the voltage to 150 V , current to 1.2 A , decimal place to 0.01 $\qquad$


## RYCN Upper limit of relay contact operation (566)

## [Description]

$\qquad$
Allows you to set the upper limit on the number of times that the control output relay 1 and 2 can operate. The alarm will be activated when the control output relay 1 or 2 has operated the number of times you set.

- You can set the upper limit of operating times in increments of 1000. (For example, if you set this parameter to 1 , the alarm will be activated when the relay worked 1000 times.)
- If you set it to 0 , no alarm will be generated.
- The numbers of times that the control output relays have operated are saved on the nonvolatile memory every 10 minutes.
[Setting example] Setting the upper limit of contact operation to 20 thousand times

| Display | Operating procedure |
| :---: | :---: |
| 245 250 $\mathrm{pv}_{\mathrm{sv}}$ | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the () key to access CH 6 (Setup parameters). |
| P V t Pv <br> K 1 sv | 4. Press the SEL key to enter CH6 (Setup parameters). $\mathrm{PVt}(\mathrm{PV}$ input type) is displayed. <br> 5. Use the ©() keys to change PVt to RYCN. |
| R Y C N pv <br> 10 sv | 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) <br> 7. Use the (1) © keys to change 10 to 20 . |
| 20 sv | 8. Press the SEL key to save the change. |
|  | 9. Press the () key to return to the PV/SV display. |

## oPtM Upper limit of operating days (567)

[Description] $\qquad$
Allows you to set the upper limit on the number of days that the device can operate.
The alarm will be activated when the number of operating days has reached the setpoint.

- You can set the upper limit of operating days in days.
(For example, if you set this parameter to 1 , the alarm will be activated when the device worked 1 day.)
- If you set it to 0 , no alarm will be generated.
- The number of operating days is saved on the nonvolatile memory every 10 minutes.
[Setting example] Setting the upper limit of operating days to 100 days

| Display | Operating procedure |
| :---: | :---: |
| $245{ }^{245}$ | 1. Check that the PV/SV display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the () key to access CH 6 (Setup parameters). <br> 4. Press the SEL key to enter CH6 (Setup parameters). PVt ( PV input type) is displayed. <br> 5. Use the ©(1) keys to change PVt to oPtM. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) <br> 7. Use the ©() keys to change 3650 to 100 . <br> 8. Press the SEL key to save the change. <br> 9. Press the () key to return to the PV/SV display. |
| CH6 PV  <br>  SEt SV |  |
| P V t <br> K1 <br> PV |  |
| OP t M ${ }^{\text {P }}$ Pv |  |
| 100 sv |  |
|  |  |

## 3-8 CH7 SYS (System parameters)

UKY1 USER key assignment (590)
UKY2 USER key assignment (591)
UKY3 USER key assignment (592)

## [Description]

$\qquad$

- Allows you to assign functions to each USER key.

| UKY1 | USER key |
| :--- | :--- |
| UKY2 | USER key +v key |
| UKY3 | USER key $+\wedge$ key |

Select a function from the table below.

| Setpoint *1 | Function |
| :---: | :---: |
| 0 | No function |
| 1 | Switchover between STBY ON/OFF |
| 2 | Switchover between Auto/Manual |
| 3 | Switchover between Local/Remote. |
| 5 | Starts AT (standard) |
| 6 | Starts AT (low PV) |
| 8 | Ramp SV RUN/HOLD switchover |
| 9 | Ramp soak RUN/OFF switchover |
| 10 | Ramp soak RUN/HOLD switchover |
| 12 | Latch release (all) |
| 13 | Latch release (ALM1) |
| 14 | Latch release (ALM2) |
| 15 | Latch release (ALM3) |
| 16 | Latch release (ALM4) |
| 17 | Latch release (ALM5) |
| 19 | Start timer (ALM1) |
| 20 | Start timer (ALM2) |
| 21 | Start timer (ALM3) |
| 22 | Start timer (ALM4) |
| 23 | Start timer (ALM5) |
| 25 | SVNo. + 1 (send) *2 |
| 26 | PIDNo. + 1 (send) *2 |
| 28 | Ramp soak pattern No. +1 (send) *3 |
| 29 | (SV No.,PID No.) + 1 (send) *2 |

Note *1: Enter the numbers only listed in this table.
*2: When the number has reached the maximum, it returns to zero.
*3: When the number has reached the maximum, it returns to the minimum number.
[Setting example] Assigning the switchover between STBY ON/OFF to the USER key

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{PV} \\ 250 & \mathrm{sV} \end{array}$ | 1. Check that the PV/SV display is shown. |
| $\begin{array}{ll\|l} \hline \text { CH } & 7 & \mathrm{Pv} \\ & \mathrm{SYS} & \mathrm{SV} \end{array}$ | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH7 (System parameters). |
| UKY 1PV  <br>  0 | 4. Press the SEL key to enter CH7 (System parameters). <br> UKY1 (USER key assignment) is displayed. <br> 5. Press the SEL key. |
| 1 sv | 6. Use the © (ㄴ) keys to change 0 to 1 . <br> 7. Press the SEL key to save the change. |
|  | 8. Press the (b) key to return to the PV/SV display. |

## di1 to di5 DI function select (593 to 597)

## [Description]

You can allocate one of the following functions to each of DI1 to DI5. These functions are activated by external DI signals.

| No. | Function | Action | ON | OFF | Criteria |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | No function | No action | - | - | - |
| 1 | Standby ON/OFF switchover | Switches between Standby ON/OFF. | Standby | Cancels Standby | Edge |
| 2 | Auto/manual switchover | Switches the control output action between auto/manual. | Manual | Auto | Edge |
| 3 | Local/remote switchover | Switches SV between local/remote. | Remote | Local | Edge |
| 4 | Setting prohibited | - | - | - | - |
| 5 | Auto tuning (standard) start | Runs standard auto-tuning. | Start | Stop | Edge |
| 6 | Auto tuning (low-PV) start | Runs low-PV type auto-tuning. | Start | Stop | Edge |
| 7 | Ramp SV ON/OFF | Enables or disables ramp SV. | Disable | Enable | Edge |
| 8 | Ramp SV hold | Switches between ramp SV hold and hold cancel. | Hold | Hold cancel | Edge |
| 9 | Ramp soak RUN/OFF | Switches between ramp soak RUN/OFF. | RUN | OFF | Edge |
| 10 | Ramp soak RUN/HOLD | Switches between ramp soak RUN/HOLD. | RUN | HOLD | Edge |
| 11 | Setting prohibited | - | - | - | - |
| 12 | Unlatch (all) | Cancels all the alarm latches. | Unlatch | - | Edge |
| 13 | Unlatch (alarm 1) | Unlatches the alarm 1. |  |  |  |
| 14 | Unlatch (alarm 2) | Unlatches the alarm 2. |  |  |  |
| 15 | Unlatch (alarm 3) | Unlatches the alarm 3. |  |  |  |
| 16 | Unlatch (alarm 4) | Unlatches the alarm 4. |  |  |  |
| 17 | Unlatch (alarm 5) | Unlatches the alarm 5. |  |  |  |
| 18 | Setting prohibited | - | - | - | - |
| 19 | Timer (alarm 1) | Runs the timer for the alarm 1. | Timer ON | Timer OFF | Level |
| 20 | Timer (alarm 2) | Runs the timer for the alarm 2. |  |  |  |
| 21 | Timer (alarm 3) | Runs the timer for the alarm 3. |  |  |  |
| 22 | Timer (alarm 4) | Runs the timer for the alarm 4. |  |  |  |
| 23 | Timer (alarm 5) | Runs the timer for the alarm 5. |  |  |  |
| 24 | Setting prohibited | - | - | - | - |
| 25 | SV No. + 1 | Increases the SV number by 1. | + 1 | - | Level |
| 26 | SV No. +2 | Increases the SV number by 2 . | + 2 | - | Level |
| 27 | SV No. + 4 | Increases the SV number by 4. | + 4 | - | Level |
| 28 | PID No. + 1 | Increases the PID number by 1. | + 1 | - | Level |
| 29 | PID No. + 2 | Increases the PID number by 2 . | + 2 | - | Level |
| 30 | PID No. +4 | Increases the PID number by 4. | + 4 | - | Level |
| 31 | $\begin{aligned} & \hline \text { SV No. }+1, \\ & \text { PID No. }+1 \end{aligned}$ | Increases both the SV number and PID number by 1. | + 1 | - | Level |
| 32 | $\begin{aligned} & \hline \text { SV No. + 2, } \\ & \text { PID No. }+2 \end{aligned}$ | Increases both the SV number and PID number by 2 . | + 2 | - | Level |
| 33 | $\begin{array}{\|l} \hline \text { SV No. }+4, \\ \text { PID No. }+4 \\ \hline \end{array}$ | Increases both the SV number and PID number by 4. | + 4 | - | Level |
| 34 | Ramp soak OFF | Stops ramp soak operation. | OFF | - | Edge |
| 35 | Ramp soak RUN | Runs ramp soak. | RUN | - | Edge |
| 36 | Ramp soak HOLD | Holds ramp soak. | HOLD | - | Edge |
| 37 | Pattern No. + 1 | Increases the pattern number by 1. | + 1 | - | Level |
| 38 | Pattern No. +2 | Increases the pattern number by 2 . | +2 | - | Level |


| No. | Function | Action | ON | OFF | Criteria |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 39 | Pattern No. +4 | Increases the pattern number by 4. | + 4 | - | Level |
| 40 | Pattern No. +8 | Increases the pattern number by 8. | $+8$ | - | Level |
| 41 | DI soft start | Starts DI soft start. | Start | - | Edge |
| 42 | Setting prohibited | - | - | - | - |
| 43 | Delay start (alarm 1) | Enables delay start with the delay time = dLY 1. | Delay start enabled |  | - |
| 44 | Delay start (alarm 2) | Enables delay start with the delay time = dLY2. | Delay start enabled |  | - |
| 45 | Delay start (alarm 3) | Enables delay start with the delay time $=$ dLY3 . | Delay start enabled |  | - |
| 46 | Delay start (alarm 4) | Enables delay start with the delay time = dLY4. | Delay start enabled |  | - |
| 47 | Delay start (alarm 5) | Enables delay start with the delay time $=$ dLY5 . | Delay start enabled |  | - |
| 48 | Setting prohibited | - | - | - | - |

## Note:

When the DI function for edge operation is selected please note the following:

- When the power to the unit is turned on with DI turned on, the ON edge is accepted and the selected function is performed.
- When the power to the unit is turned on with DI turned off, the OFF edge is rejected and the selected function is not performed.
[Setting example] Setting the DI1 function to "standby ON/OFF switchover"

| Display | Operating procedure |
| :---: | :---: |
| 245 250 sv | 1. Check that the PV/SV display is shown. |
| CH   <br>  7 pv <br>  SYS sv | 2. Press and hold the SEL key to display CH1 (PID parameters). |
| UKY 1 pv  <br>  0 sv | 4. Press the SEL key to enter CH7 (System parameters). UKY1 (User key) is displayed. |
| d iPv   <br>    <br>  0 sv <br>    | 5. Use the © © keys to change "UKY 1 " to "dil". <br> 6. Press the SEL key. (The first digit of the lower part of the screen begins to blink.) |
| 1 sv | 7. Use the ©() keys to change " 0 " to " 1 ". <br> 8. Press the SEL key to save the change. |
|  | 9. Press the () key to return to the PV/SV display. |

OU1t OUT1 output type (599)
oU2t OUT2 output type (600)
do1t to do3t Output type (DO1 to DO3) (601 to 603)
LoU1 LED indicator assignment (OUT1) (607)
LoU2 LED indicator assignment (OUT2) (608)
LEV1 to LEV6 LED indicator assignment (EV1 to EV6) (609 to 614)
LStb LED indicator assignment (STBY) (615)
LMAN LED indicator assignment (MAN) (616)

## [Description]

You can select what to be output from each output terminal, and what each indicator lamp means.
Select numbers from the table below.

| $\begin{aligned} & \text { OUT } \\ & \text { (relay/SSR) } \end{aligned}$ | OUT <br> (current voltage) | DO | Indicator lamps Set value | Category | Function |
| :---: | :---: | :---: | :---: | :---: | :---: |
| oU1T, <br> oU2T | oU1T, <br> oU2T | $\begin{aligned} & \text { do1T, do2T, } \\ & \text { do3T, do4T, do5T } \end{aligned}$ | LoU1, LoU2, LEV 1 to 6, LSTb, LMAN |  |  |
| 0 | 0 | 0 | 0 |  | None |
| 1 | 1 | 1 | 1 | Control output | MV1 (heating) |
| 2 | 2 | 2 | 2 |  | MV2 (cooling) |
| 3 | - | 3 | 3 | Alarm output | Alarm 1 |
| 4 | - | 4 | 4 |  | Alarm 2 |
| 5 | - | 5 | 5 |  | Alarm 3 |
| 6 | - | 6 | 6 |  | Alarm 4 |
| 7 | - | 7 | 7 |  | Alarm 5 |
| 10 | - | 10 | 10 | Status output | During auto-tuning startup |
| 11 | - | 11 | 11 |  | Normal |
| 12 | - | 12 | 12 |  | Standby |
| 13 | - | 13 | 13 |  | During manual mode |
| 15 | - | 15 | 15 |  | During ramp SV |
| 16 | - | 16 | 16 |  | System error |
| 20 | - | 20 | 20 | Ramp soak Event output | OFF |
| 21 | - | 21 | 21 |  | RUN |
| 22 | - | 22 | 22 |  | HOLD |
| 23 | - | 23 | 23 |  | GS (Guaranty soak) |
| 24 | - | 24 | 24 |  | END |
| 30 | - | 30 | 30 | simple calculation result | Simple calculation result wafer 1 output 1 |
| 31 | - | 31 | 31 |  | Simple calculation result wafer 1 output 2 |
| 32 | - | 32 | 32 |  | Simple calculation result wafer 1 output 3 |
| 33 | - | 33 | 33 |  | Simple calculation result wafer 1 output 4 |
|  |  |  |  |  |  |
| 66 | - | 66 | 66 |  | Simple calculation result wafer 10 output 1 |
| 67 | - | 67 | 67 |  | Simple calculation result wafer 10 output 2 |
| 68 | - | 68 | 68 |  | Simple calculation result wafer 10 output 3 |
| 69 | - | 69 | 69 |  | Simple calculation result wafer 10 output 4 |
| 170 | - | 170 | 170 | Ramp soak Time signal | Time signal (step 1 ramp) |
| 171 | - | 171 | 171 |  | Time signal (step 1 soak) |
| 172 | - | 172 | 172 |  | Time signal (step 2 ramp) |
| 173 | - | 173 | 173 |  | Time signal (step 2 soak) |
|  |  |  |  |  |  |
| 294 | - | 294 | 294 |  | Time signal (step 63 ramp ) |
| 295 | - | 295 | 295 |  | Time signal (step 63 soak) |
| 296 | - | 296 | 296 |  | Time signal (step 64 ramp ) |
| 297 | - | 297 | 297 |  | Time signal (step 64 soak) |
| 300 | - | 300 | 300 | Ramp soak Relative time signal | Time signal (1st step ramp) |
| 301 | - | 301 | 301 |  | Time signal (1st step soak) |
| 302 | - | 302 | 302 |  | Time signal (2nd step ramp) |
| 303 | - | 303 | 303 |  | Time signal (2nd step soak) |
|  |  |  |  |  |  |
| 424 | - | 424 | 424 |  | Time signal (63rd step ramp) |
| 425 | - | 425 | 425 |  | Time signal (63rd step soak) |
| 426 | - | 426 | 426 |  | Time signal (64th step ramp) |
| 427 | - | 427 | 427 |  | Time signal (64th step soak) |

Notes: - Enter the numbers only listed in this table.

- Use only 0 , 1 , or 2 for current and voltage output.
- When you select control output for an indicator, the indicator blinks at the intervals of "tC1" and "tC2".
[Setting example] Setting MV1 to be output from OUT1, alarm output 1 from DO1, alarm output 1 from OUT1 indicator


RMP Ramp SV ON/OFF (617)
RMPL Ramp SV-decline (618)
RMPH Ramp SV-incline (619)
RMPU Ramp SV-slope time unit (620)

## [Description]

This function changes a SV to the new value at the preset ramp rate.
SV changes smoothly, not stepwise. Incline and decline rates can be set independently.

- Setting range

Ramp SV-incline/decline: $0 \%$ to $100 \% \mathrm{FS} /{ }^{\circ} \mathrm{C}$
Ramp SV-slope time unit: hoUr (slope temperature/hour), Min (slope temperature/min)
Operation is as follows for changing SV.

[Setting example] Setting the ramp SV incline to $10^{\circ} \mathrm{C} / \mathrm{min}$, and decline to $5^{\circ} \mathrm{C} / \mathrm{min}$ $\qquad$


## SVt Ramp SV display mode (621)

## [Description]

$\qquad$
Selects which to display between the SV during ramp operations or the SV goal value.

[Setting example] Setting the target SV to be displayed

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r\|} \hline 245 & \mathrm{pv} \\ 250 & \mathrm{sv} \end{array}$ | 1. Check that the PV/SV display is shown. |
| CH 7 pv <br>  SYS sv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH7 (System parameters). |
| UKY 1 $\begin{aligned} & \text { Pv } \\ & 0\end{aligned}$ | 4. Press the SEL key to enter CH7 (System parameters). UKY1 (USER key assignment) is displayed. |
| $\begin{array}{c\|c\|} \hline \mathrm{SV} \mathrm{t} & \mathrm{Pv} \\ \mathrm{RMP} & \mathrm{sv} \end{array}$ | 5. Use the ©() keys to change UKY1 to SVt. <br> 6. Press the SEL key. (The first digit of the lower part of the screen begins to blink.) |
| tRG sv | 7. Use the © (1) keys to change RMP to tRG. <br> 8. Press the SEL key to save the change. |
|  | 9. Press the (b) key to return to the PV/SV display. |

## [Description]

This controller has six temperature control functions. Select the best control method for your application.

- Temperature control functions

| ON/OFF (2-position) <br> control | Switches output control ON/OFF according to the SV/PV magnitude <br> relationship. Control systems can be built from simple elements such as <br> SSR. This is appropriate for situations which require a low degree of <br> accuracy. |
| :--- | :--- |
| PID control | PID calculation and controls proceed according to the previously set PID <br> parameters. PID parameters can be set manually or through auto-tuning <br> (AT). <br> It is the most basic control in this equipment. |
| Fuzzy control | Reduces the amount of overshoot during control. It is effective when you <br> want to suppress overshoot while changing SV, even during processes <br> where it may take a long time to reach the target value. |
| Self tuning control | Adds controls while automatically calculating PID to meet the control target <br> or changing SV. It is effective when the control conditions change <br> frequently. |
| PID2 control | Suppresses the amount of overshoot during control for processes that turn <br> the control target off and then on again. It is effective when the control <br> target turns on and off while power flows continuously to the temperature <br> controller. |
| 2-degree-of freedom PID <br> control | The function is used to suppress overshoot generated in PID control. The 2 degrees <br> of freedom PID system of this instrument adopts set value SV) filter method, <br> which is effective at suppressing overshoot at the time of setting change or power <br> ON. |

## (1) ON/OFF (2-position) control (oNoF)

When you set the control method (CtRL) to oNoF, the device uses ON/OFF control.
In ON/OFF control, the controller switches the control output between ON (100\%) and OFF ( $0 \%$ ) according to the SV/PV magnitude relationship. You can set the output hysteresis in the control parameters (CH2 PLT)

## Reverse Operation (Heating)

Method used to control the electrical heating furnace. Set the HYS to an appropriate value according to the control target.

| Parameter | Set value |
| :--- | :--- |
| CtRL | oNoF |
| REV | RV $_{--}$ |
| HYS | optional (default: $1^{\circ} \mathrm{C}$ ) |



Normal operation (Cooling)
Method used to control the cooling machine.

| Parameter | Set value |
| :--- | :--- |
| CtRL | oNoF |
| REV | No_-_ |
| HYS | optional (default: $1^{\circ} \mathrm{C}$ ) |

- During ON/OFF control, the P, I and D settings do not affect control.
- In the manual operation during ON/OFF control, MV displayed by pressing UP key is $100 \%$, and MV displayed by pressing DOWN key is $0 \%$.
- If the hysteresis width is narrow, and PV and SV are nearly equal, the output may frequently switch on and off. Note that it may affect the of the contact life.


## (2) PID control (Pid)

Pid control starts when the parameter "CtRL" is "Pid". Pid control calculate Pid and output the result according to the set values of the parameters "P", "i", "d", and "AR". (-5 to 105\%)
Each parameter can be set either by manually tuning the values or by running auto-tuning (AT) to automatically set the values.
Related parameters: Auto-tuning (page 33)
(3) Fuzzy control (FUZY)

This control minimizes the overshoot compared to normal PID. Fuzzy control can only be used after autotuning has been activated and a PID set.
Related parameters: Auto-tuning (page 33)
(4) Self tuning control (SELF)

Adds controls while automatically calculating PID to meet the control target or changing SV. Self-tuning is especially effective for situations when a high level of control is not needed, but auto-tuning cannot be run due to frequent changes in the control target conditions. If a high degree of control is required, select PID control, fuzzy control or PID2 control.

## Conditions where self-tuning can be used

- When temperature rises right after the power is turned on
- When temperature rises after SV change (or when the controller judges it necessary)
- When the controller judges it necessary because the control has become unstable

Conditions where self-tuning cannot be used

- During standby
- During ON/OFF (2 setting) control
- During auto-tuning
- During ramp/soak operation
- When input error occurs
- When dual output is used
- When any of the P, I, D, or Ar parameters have been manually configured
- During manual mode
- During soft start


## Conditions where self-tuning is halted

- When SV is changed (including when SV is changed by the ramp/soak function, remote SV function, or ramp SV .)
- When self-tuning has not finished after running for nine or more hours
- The equipment will not be tuned properly if power is turned on first.
- When redoing the self-tuning settings, first set the control method to PID ("Pid"), and then set back to self-tuning.



## (5) PID2 control (Pid2)

This type of control reduces overshoot during control for processes that turn the control target off and then on again. The algorithm used prevents over integration of the PID calculations even while the control loop is still open. PID2 control can only be used after auto-tuning has been activated and a PID set.

(6) 2-degrees-of-freedom PID (2 FRE)

The 2 degrees of freedom PID system of this instrument adopts set value (SV) filter method, which is effective in suppressing overshoot at the time of setting change or power ON.
The controllability of 2-degrees-of-freedom PID control changes according to the settings of coefficient $\alpha$ and $\beta$.
If you set coefficient $\alpha$ to $100.0 \%$ and $\beta$ to $0.0 \%$, normal PID control is operated.
Adjust $\alpha$ and $\beta$ as follows.

1) set $\alpha=40.0 \%, \quad \beta=100.0 \%$ (Factory default setting)
2) Perform control and check responsibility (overshoot volume).

If overshoot is not reduced, adjust $\alpha$ and $\beta$ as follows.
Generally, ALPA ( $\alpha$ ) does not require adjusting. Therefore, it is recommended to use the instrument with
ALPA ( $\alpha$ ) set to $40.0 \%$.

| Result of control | Coefficient $\beta$ | Coefficient $\alpha$ |
| :--- | :--- | :--- |
| Large overshoot | Increase $\beta$ by $20 \%$ | Decrease $\alpha$ by $10 \%$ |
| Small overshoot | Decrease $\beta$ by $20 \%$ | Increase $\alpha$ by $10 \%$ |

[Setting example] Setting the control method to ON/OFF control

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{Pv} \\ 250 & \mathrm{sv} \end{array}$ | 1. Check that the PV/SV display is shown. |
| H 7 PV <br>  SYS SV | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH7 (System parameters). |
| UKY 1 ${ }^{\text {U }}$ PV | 4. Press the SEL key to enter CH7 (System parameters). UKY1 (USER key assignment) is displayed. |
| CtPL $\mathrm{RL}^{\text {PV }}$ | 5. Use the ©(1) keys to change UKY1 to CtRL. <br> 6. Press the SEL key. (The first digit of the lower part of the screen begins to blink.) |
| oNoF sv | 8. Press the SEL key to save the change. <br> 9. Press the key to return to the $\mathrm{PV} / \mathrm{SV}$ display. |

## [Description]

$\qquad$
This controller has three valve control functions.
Select the best function for the current application.
$\bullet$ Valve Control Functions

| Servo control 1 | Controls the motorized valve opening through [OPEN], [CLOSE] <br> connection points. |
| :--- | :--- |
| Servo control 2 | Controls the motorized valve opening through [OPEN], [CLOSE] <br> connection points. The opening of the valve can be displayed by reading the <br> open position signal from the motorized valve, but it cannot be used in <br> control output calculations. |
| Position feedback | Inserts controls by adding the opening signal from the motorized valve to <br> the control calculation results. Controls the motorized valve opening <br> through [OPEN], [CLOSE] connection points. <br> This control can be used when there are opening signals coming from the <br> motorized valve. |

## (1) Servo Control 1/Servo Control 2

Adjusts and controls the motorized valve opening through [OPEN], [CLOSE] connection points.
In manual mode, press the key to switch between [OPEN] and [CLOSE].
Servo control 1 and servo control 2 have the following differences.

- Servo Control 1: No valve opening display
- Servo Control 2: Has valve opening display

Neither control can be used to control the valve opening itself.


## Note:

- Servo control 1 can control the motorized valve even without a valve opening signal from the motorized valve. (The motorized valve opening is estimated from a calculation of the valve stroke time.)
- Servo control 2 adds the valve opening signal display function to servo control 1. Valve position display can be used to automatically or manually adjust zero/span.
- Zero/span adjustment is necessary for using valve position indication.
[Setting example] Changing the control target from servo1 to servo2

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{Pv} \\ 250 & \mathrm{sV} \end{array}$ | 1. Check that the PV/SV display is shown. |
| CH 7 PV <br>  SYS SV | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH7 (System parameters). |
| UKY 1PV   <br>  0 sv | 4. Press the SEL key to enter CH7 (System parameters). UKY1 (USER key assignment) is displayed. |
| $\begin{array}{r\|r} \text { PRPS S } & \text { pv } \\ \text { SRV1 } & s v \end{array}$ | 5. Use the ©() keys to change "UKY1" to "PRCS". <br> 6. Press the SEL key. (The first digit of the lower part of the screen begins to blink.) |
| SRV2 sv | 8. Press the SEL key to save the change. <br> 9. Press the key to return to the PV/SV display. |

(2) Position Feedback Control (PFB control)

Position feedback control (PFB) is used to control the position of the motorized valve based on the position signal transmitted from the motorized valve. During manual mode, the controller displays the valve position signal as MV.
Because it is based on the actual valve position, PFB control is more precise than the servo 1 /servo 2 control.
[Setting example] Changing to PFB control

| Display | Operating procedure |
| :---: | :---: |
| 245 250 sv | 1. Check that the PV/SV display is shown. |
| CH   <br>  7 pv <br>  SYS sv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the () key to access CH 7 (System parameters). |
| UK Y 1  <br>   <br> 0 pv <br> sv  | 4. Press the SEL key to enter CH7 (System parameters) UKY1 (USER key assignment) is displayed. |
| $\begin{array}{r\|r} \text { PRCS } & \mathrm{pv} \\ \text { SRV1 } & \mathrm{sv} \end{array}$ | 5. Use the © () keys to change "UKY1" to "PRCS". <br> 6. Press the SEL key. (The first digit of the lower part of the screen begins to blink.) |
| PFb ${ }^{\text {sv }}$ | 8. Press the SEL key to save the change. <br> 9. Press the © ( key to return to the $\mathrm{PV} / \mathrm{SV}$ display. |

## oNoF ONOFF Hysteresis (624)

## [Description]

$\qquad$
Selects the hysteresis operation during two state action.
OFF: Performs two state action at SV+HYS/2 and SV-HYS/2.
ON: Performs two state action at SV, SV+HYS and SV, SVHYS.

|  | oNoF: OFF | oNoF: ON |
| :---: | :---: | :---: |
| Reverse |  |  |
| Normal Operation |  |  |

[Setting example] Setting the start mode to control output manual mode

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 \\ 250 & \mathrm{SV} \end{array}$ | 1. Check that the PV/SV display is shown. |
| CH 7 PV <br>  SYS SV | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH7 (System parameters). |
| UKY 1Pv  <br>  0 | 4. Press the SEL key to enter CH7 (System parameters). UKY1 (USER key assignment) is displayed. |
| $\begin{array}{c\|c} \text { O N O F } & \text { pv } \\ \text { oFF } & \text { sv } \end{array}$ | 5. Use the ©() keys to change "UKY1" to " oNoF ". <br> 6. Press the SEL key. (The first digit of the lower part of the screen begins to blink.) |
| ON sv | 8. Press the SEL key to save the change. <br> 9. Press the key to return to the PV/SV display. |

[Description]
Allows you to specify the mode that the device starts up.
Select from the following four options.

- Setting range

| AUto | Control output auto mode |
| :--- | :--- |
| MAN | Control output manual mode |
| REM | Remote SV mode |
| StbY | Standby Mode |

[Setting example] Setting the start mode to control output manual mode

dt Control operation cycle (627)
[Description] $\qquad$
Allows you to set the control operation cycle.
Note:
Be sure to restart the controller after changing the setpoint.
Setting range: 0.1 to $0.9 \mathrm{~s}, 1$ to 99 s
[Setting example] Setting the control operation cycle to 0.2 seconds.


## PLtS PID palette switching method (628)

## [Description]

This instrument is provided with 7 groups of control palettes (group of control parameters) in CH2 (PLT), in addition to control parameters in CH1 (PID). Control can be made while switching these control palettes. Select control palette switching method with PLTS parameter.

Setting range

| $\begin{array}{\|l\|} \hline 0 \\ \text { (PID selection) } \\ \hline \end{array}$ | Operation is performed with the control palette set at PLN1 (PID selection). |
| :---: | :---: |
| 1 <br> (SV selection) | Operation is performed with the control palette of the SV No. selected by SVn. |
| $2$ <br> (Switch according to PV) | Operation is performed while control palettes are automatically switched depending on the measurement value (PV), with the value set for REF1 to REF7 as threshold. <br> The following figure shows the relation between the PV reference point and the control palettes. |

[Setting example] Switching palettes by SV selection No.


## 3-9 CH8 MATH (Calculation parameters)

MAtH Simple calculation ON/OFF (650)
W1MA to MAo4 Simple calculation setting and result (651 to 730)
CoN1 to CoNA Constant setting (731 to 740)
[Description] $\qquad$
The controller can make calculations with alarm outputs or control status, and send calculation results to DO or LED.
A calculation is done by combination of function blocks called "wafer".

- You can register 10 wafers maximum.
- There are the following six kinds of calculation in the simple calculation function.


| 5 | RFLGC5 |  |
| :---: | :---: | :---: |
| A | A $\cdot \mathrm{B}+\mathrm{C}$ | OUT1 |
|  | $\overline{A \cdot B+C}$ | OUT2 |
|  | $A \cdot B+\bar{C}$ | оитз |
| c | $\overline{A \cdot B+\bar{C}}$ | UT4 |



You can use the following values as inputs for calculation.

| No | Category | Function |
| :---: | :---: | :---: |
| 0 |  | No input |
| 3 | Alarm output | Alarm 1 |
| 4 |  | Alarm 2 |
| 5 |  | Alarm 3 |
| 6 |  | Alarm 4 |
| 7 |  | Alarm 5 |
| 20 | Ramp soak event output | Ramp soak (OFF) |
| 21 |  | Ramp soak (RUN) |
| 22 |  | Ramp soak (HOLD) |
| 23 |  | Guarantee soak (GS) |
| 24 |  | Ramp soak (END) |
| 30 | simple calculation result | Simple calculation result wafer 1 output 1 |
| 31 |  | Simple calculation result wafer 1 output 2 |
| 32 |  | Simple calculation result wafer 1 output 3 |
| 33 |  | Simple calculation result wafer 1 output 4 |
| ! |  | $\vdots$ |
| 66 |  | Simple calculation result wafer 10 output 1 |
| 67 |  | Simple calculation result wafer 10 output 2 |
| 68 |  | Simple calculation result wafer 10 output 3 |
| 69 |  | Simple calculation result wafer 10 output 4 |
| 70 | Constant | Constant 1 |
| ! |  | ! |
| 79 |  | Constant 10 |
| 94 | Input error | Underrange |
| 95 |  | Overrange |
| 98 |  | Range setting error |
| 103 |  | Input error |
| 104 | Operation information | Auto/manual mode status |
| 105 |  | RUN/standby status |
| 107 |  | Auto-tuning RUN/STOP |
| 108 |  | Auto-tuning normal type start-up |
| 109 |  | Auto-tuning low-PV type start-up |
| 170 | Ramp soak time signal | Time signal (step 1 ramp ) |
| 171 |  | Time signal (step 1 soak) |
| 172 |  | Time signal (step 2 ramp) |
| 173 |  | Time signal (step 2 soak) |
| ! |  | ! |
| 294 |  | Time signal (step 63 ramp ) |
| 295 |  | Time signal (step 63 soak) |
| 296 |  | Time signal (step 64 ramp ) |
| 297 |  | Time signal (step 64 soak) |
| 300 | Ramp soak relative time signal | Time signal (1st step ramp) |
| 301 |  | Time signal (1st step soak) |
| 302 |  | Time signal (2nd step ramp) |
| 303 |  | Time signal (2nd step soak) |
| ! |  | ! |
| 424 |  | Time signal (63th step ramp) |
| 425 |  | Time signal (63th step soak) |
| 426 |  | Time signal (64th step ramp) |
| 427 |  | Time signal (64th step soak) |

(1) Simple calculation ON/OFF (MAtH) (650)

Allows you to switch between ON/OFF of simple calculation.
Setting range: ON, OFF
(2) Calculation setting (wafer 1 to wafer 10) (W1MA to WAMA) (651 to 723)

Allows you to set the contents of wafer calculation.
Setting range: 1 to 6
(3) Input 1 setting (wafer 1 to wafer 10) (W1i1 to WAi1) (652 to 724)

Input 2 setting (wafer 1 to wafer 10) (W1i2 to WAi2) (653 to 725)
Input 3 setting (wafer 1 to wafer 10) (W1i3 to WAi3) (654 to 726)
Sets the input used in wafer calculation.
Setting range: 0 to 347
(4) Output 1 setting (wafer 1 to wafer 10) (W1o1 to WAo1) (655 to 727)

Output 2 setting (wafer 1 to wafer 10) (W1o2 to WAo2) (656 to 728)
Output 3 setting (wafer 1 to wafer 10) (W1o3 to WAo3) (657 to 729)
Output 4 setting (wafer 1 to wafer 10) (W1o4 to WAo4) (658 to 730)
Shows the result of wafer calculation.
(5) Constant 1 to constant 10

Allows you to set the constant used in wafer calculation.
Setting range: -32767 to 32767
[Setting example] Setting DO1 to output a logical sum of ON/OFF information of Alarm 1, 2, and 3 $\qquad$


| Screen <br> № | Display | Set value | Description |
| :---: | :---: | :---: | :--- |
| 650 | MAtH | ON | Makes the simple calculation. |
| 651 | W1MA | 2 | Carries out the "logical operation wafer 2" on wafer 1. |
| 652 | W1i1 | 1 | Enter the Alarm 1 ON/OFF information to the input 1 of wafer 1. |
| 653 | W1i2 | 2 | Enter the Alarm 2 ON/OFF information to the input 2 of wafer 1. |
| 653 | W1i3 | 3 | Enter the Alarm 3 ON/OFF information to the input 3 of wafer 3. |
| 601 | do1t | 30 | Outputs the output 1 of wafer 1 from DO1. |



## 3-10 CH9 COM (Communication parameters)

This device uses an RS-485 interface and can therefore communicate with personal computers, programmable operation indicators, and other devices. These parameters set the communication conditions for sending and receiving data.


Note:
When using an RS-232C to RS-485 converter, make sure to correctly connect the cable between the converter and master. Communication will not occur properly if the connection is incorrect. Also make sure to correctly set any communication settings (such as communication speed and parity) on the RS-232C and RS-485 converter. Communication will not occur properly if the settings are incorrect.

The following describes the typical communication behavior available when using MODBUS RTU. The center of communications (personal computer, etc) on a network is called the "master". There can only be one master per network. The other devices on the network (including this device) are calledl "slaves" (1: N connection communication). Set a station number for each slave so that they do not overlap with each other. Communication consists of the master sending out a message with a station number attached and each slave determining if the message is meant for it. The slave to which the message was sent then responds to the master. Slaves do not initiate communication. A network consists of 1 master and up to 31 slaves (including this device). A network cable can be up to 500 m long.

Refer to the "Micro Controller (Model: PXF) Communication Function Manual (MODBUS)" for information on communication procedures, protocols and settings.

## CtyP Communication type (760)

## [Description]

$\qquad$
Selects the type of communication.

- Setting range

| 0 | MODBUS RTU |
| :--- | :--- |
| 1 | Cooperative operation |
| 2 | Programless communication |

Their functions are as follows: Refer to the "Micro Controller (Model: PXF) Communication Function Manual
(MODBUS)" for the detail.

| 0: MODBUS RTU | Typical master/stave communication is available. A PC or PLC acts as <br> a master, while multiple temperature controllers act as as slaves. <br> Communication is made in such a way that the master sends messages <br> to the slaves, and the slaves respond to it. |
| :--- | :--- |
| 1: Cooperative operation | When you control one temperature controller, the other controllers <br> follow it. The controller acts as a master, while other controllers act as <br> slaves. When you change the settings of the master controller, a <br> message will be sent to all slave controllers so that they follow the <br> change of the master. |
| 2: Programless communication | PLC can read the data of temperature controllers or write data on <br> temperature controllers without preparing a rudder program. One PLC <br> act as a master, and multiple temperature controllers act as slaves. Each <br> temperature controller in turn carries out master-slave communication <br> with PLC. The communication protocol is MODBUS RTU. |

Note:
Be sure to restart the controller after changing set points.
[Setting example] Setting the station No. to 3

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. |
| H 9 pv <br>  CoM sv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH9 (Communication parameters). |
| ¢ y P pv  <br>  0 $s v$ <br>    | 4. Press the SEL key to enter CH9 (Communication parameters). CtyP (communication type) is displayed. <br> 5. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 2 sv | 6. Use the © (v) keys to change 0 to 2 . <br> 7. Press the SEL key to save the change. <br> 8. Press the (L) key to return to the PV/SV display. |

StNo Station No. (761)

## [Description]

Allows you to set the station number.

- Setting range: 0 to 255
(Note that setting the station number to 0 will suspend communication.)
If there are two or more slave devices, make sure that they do not have the same station numbers. If two devices on the same network share a station number, communication becomes unavailable.
[Setting example] Setting the station No. to 3



## SPEd RS485 baud rate (762)

## [Description]

$\qquad$
Allows you to set the baud rate of RS-485 communication.

- Setting range: $96(9600 \mathrm{bps}), 192(19200 \mathrm{bps}), 384$ ( 38400 bps ), 115 k ( 115 kbps )

Note:
Be sure to restart the controller after changing the setpoint.
[Setting example] Setting the baud rate to 19200 bps

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{Pv} \\ 250 & \mathrm{sv} \end{array}$ | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH9 (Communication parameters). |
| St $\mathrm{So}^{\text {PV }}$ | 4. Press the SEL key to enter CH9 (Communication parameters). StNo (station No.) is displayed. |
| SPE d ${ }_{\text {Pv }}$ | 5. Use the ©() keys to change StNo to SPEd. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 192 sv | 7. Use the (ㄷ) keys to change 96 to 192. <br> 8. Press the SEL key to save the change. |
|  | 9. Press the (b) key to return to the PV/SV display. |

[Description] $\qquad$
Allows you to set the parity check of RS-485 communication.

- Setting range: NoNE (no parity), odd, EVEN

Note:
Be sure to restart the controller after changing the setpoint.
[Setting example] Setting the RS-485 parity to NoNE (no parity)

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r} 245 & \mathrm{PV} \\ 250 & \mathrm{sV} \end{array}$ | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH9 (Communication parameters). |
| S  <br> 1 PV | 4. Press the SEL key to enter CH9 (Communication parameters). StNo (station No.) is displayed. |
|  | 5. Use the (1) keys to change StNo to PRtY. <br> 6. Press the SEL key. <br> (The lower part of the screen begins to blink.) |
| NoNE $\mathrm{sv}^{\text {sv }}$ | 7. Use the © (1) keys to change odd to NoNE. <br> 8. Press the SEL key to save the change. |
|  | 9. Press the () key to return to the PV/SV display. |

## [Description]

$\qquad$
Allows you to set the time interval before sending response.
Setpoint x 20 ms makes the response interval time.

- Setting range: 0 to 100
[Setting example] Setting the responce interval to 40 ms



## SCC Communication permission (767)

[Description] $\qquad$
Allows you to specify whether the master is permitted or forbidden to write to the slave.

- Setting range R: read only

RW: read/write
[Setting example] Enabling the write protection

| Display | Operating procedure |
| :---: | :---: |
| 245 PV | 1. Check that the PV/SV display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the () key to access CH9 (Communication parameters) <br> 4. Press the SEL key to enter CH9 (Communication parameters). StNo (station No.) is displayed. <br> 5. Use the (1) keys to change StNo to SCC. <br> 6. Press the SEL key. <br> (The lower part of the screen begins to blink.) <br> 7. Use (^) keys to change RW to R. <br> 8. Press the SEL key to save the change. <br> 9. Press the (L) key to return to the PV/SV display. |
|  |  |
| St  <br>  PV <br>  SV |  |
| SCP pv <br> RW Sv |  |
| R $\mathrm{sv}^{\text {sv }}$ |  |
|  |  |

## UA01 to UA32 MODBUS user address setting 1 to 32 (769 to 800)

## [Description]

$\qquad$
By registering a MODBUS communication address with the user address area, you can read/write the data of addresses through one communication even if those address are not sequential.
You can register 32 addresses maximum.
The registered addresses are allocated to MODBUS address 45001 to 45032 . By reading/writing on MODBUS address 45001 to 45032 , you can read/write the data of registered addresses.

- Setting range: 30001 to 49999

Note:
Be sure to restart the controller after changing the setpoint.
[Setting example] Setting the user address 1 to 30100


- Cooperative operation parameters

CSVG Communication SV gain (801)
CSVS Communication SV shift (802)
kykd Cooperative operation items (803)
APCy All parameters copy (804)

- Programless communication parameters

PLSt Target PLC station No. (805)
PAdk PLC registration number allocation rule (806)
MSWt Communication interval between temperature controllers (807)
PLWt Communication interval between PLC and temperature controllers (808)
PLAd Head of PLC registration numbers (809)
SA01 to SA16 Modbus address of data No. 1 to No. 16 in setting area (810) to (825)
MA01 to MA16 Modbus address of data No. 1 to No. 16 in monitor area (826) to (841)
Refer to the "Micro Controller (Model: PXF) Communication Function Manual (MODBUS)" for configuration of cooperative operation parameters and programless communicaiton parameters.

## AFix Auto Fix (842)

## [Description]

$\qquad$
Sets whether or not to automatically save parameter values that are written via communication onto EEPROM.

- Setting range oN: Automatic data save
oFF: No data save
[Setting example] No data save $\qquad$

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the (\%) key to access CH9 (Communication parameters). <br> 4. Press the SEL key to enter CH9 (Communication parameters). StNo (station No.) is displayed. <br> 5. Use the ©() keys to change StNo to AFix. <br> 6. Press the SEL key. <br> (The lower part of the screen begins to blink.) <br> 7. Use © (v) keys to change oN to oFF. <br> 8. Press the SEL key to save the change. <br> 9. Press the (L) key to return to the PV/SV display. |
| CH 9 pv <br>  CoM sv |  |
| St  <br>   <br> 1 PV |  |
|  |  |
| oFF sv |  |
|  |  |

## Note:

You cannot set or change this parameter by using the loader software.

## 3-11 CH10 PFB (PFB parameter)

PGAP PFB dead band (870)
[Description]
The dead band can be set to not output the valve open or close signal.
Using the valve dead band suppresses the motorized valve hatching and allows greater stabilization of the output.


- Range: $0.0 \%$ to $100.0 \%$

Note:
Narrow dead band may cause output chattering.
[Setting example] Setting parameter mask $\qquad$


## tRVL Valve stroke time (871)

## [Description]

$\qquad$
This function controls the time it takes for the motorized valve to go from fully open to fully closed.
Refer to the motorized valve makerís catalog for the correct stroke time.

- Range: 5 sec to 180 sec
[Setting example] Setting the valve stroke time to 50 seconds

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r\|r\|} \hline 245 & \mathrm{Pv} \\ 250 & \mathrm{sV} \end{array}$ | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH10 (PFB parameters). |
| $\begin{array}{r\|r\|} \hline \text { PGAP } & p v \\ 0.0 & s v \end{array}$ | 4. Press the SEL key to enter CH10 (PFB parameters). PGAP (PFB dead band) is displayed. |
| $\begin{array}{r\|r} \hline \text { t R V L } & \mathrm{pv} \\ 30 \end{array}$ | 5. Use the ©() keys to change "PGAP" to "tRVL". <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| 50 sv | 7. Use the ©(․) keys to change " 30 " to " 50 ". <br> 8. Press the SEL key to save the change. <br> 9. Press the (L) key to return to the PV/SV display. |

## CAL PFB input adjustment (873)

[Description]
This function adjusts whether PFB input is zero (fully closed) or span (fully opened).
There are automatic and manual methods for adjusting.

| Setting | Function | Explanation |
| :--- | :--- | :--- |
| 0 | None/forcible termination | Ends adjustment immediately |
| 1 | Zero adjustment | Manually adjust zero |
| 2 | Span adjustment | Manually adjust span |
| 3 | Automatic adjustment | Automatically adjusts zero/span |

## Making Adjustments Manually

This section explains how to make motorized valve adjustments manually.
Note:
Manual adjustment must be set in the order zero (fully closed), then span (fully open). Adjustments cannot be made on just zero or just span.
[Setting example] Making the adjustment manually



## Making the adjustment automatically

The following steps explain how to make adjustments to zero and span automatically.

- In automatic adjustment, the controller fully opens or fully closes the motorized valve to make zero and span adjustment for PFB input. The controller also change the valve stroke time "TrvL" to the optimal value.
- When running automatic adjustment with "CAL" at " 3 ", an adjustment error has occurred if the display changes to " 10 " or " 20 ". Remove the source of the error and perform adjustment again.

| CAL display | Error name | Error source | Measures against error |
| :--- | :--- | :--- | :--- |
| 10 | Over travel time | Automatic adjustment does <br> not finish within 180 <br> seconds. | The full stroke time greater than 180 seconds <br> cannot be used for the motorized valve. <br> Use a full stroke time within 180 seconds for <br> the motorized valve. |
| 20 | PFB span error | There is an error in the span <br> value for PFB input. | Recheck the valve control output and PFB <br> input wire connection. |

[Setting example] Making the adjustment automatically


## Note:

Automatic adjustment of PFB input is available only in the manual mode.

## 3-12 CH11 DSP (Parameter mask)

## dp01 Parameter mask

[Description] $\qquad$

- The parameter mask allows you to hide unused parameters or to skip over the parameters you want to keep their setpoints. To hide a parameter, change its parameter mask setting from "diSP" to "oFF". You can also select a whole channel to hide.
Note:
Do not let the parameters which are not described in this operation manual appear on the screen.
[Setting example] Setting parameter mask

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. |
|  | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH11 (Parameter mask). |
| d S P pv <br> CH sv | 4. Press the SEL key to enter CH11 (Parameter mask). dSP (parameter mask) is displayed. |
| $P \quad i d$ dv  <br>  diSP  <br> SV   | To set parameter mask for a whole channel <br> 5. Press the SEL key. <br> Use the © (․) keys to select the CH to hide, and the press the SEL key. |
|  |  |
| $\begin{array}{l\|l} \text { d S P } & \text { pv } \\ \text { CH1 Pid } & \text { sv } \end{array}$ | 6. Use the (1) keys to select CH to which the parameter you want to hide belongs. <br> 7. Press the SEL key. |
| $\mathbf{P}$ $p v$ <br> diSP sv | 8. Use the (1) keys to select the parameter to hide, and the press the SEL key. |
| oFF ${ }^{\text {sv }}$ | 9. Press the (b) key to return to the PV/SV display. |

## 3-13 CH12 CFG (Configuration parameters)

## toUt Operation timeout (940)

## [Description]

- Sets the time until the display returns to the PV/SV screen when no operation is made during setting mode (channel display or parameter display).
- Setting range: $15 \mathrm{~S}: 15$ sec., $30 \mathrm{~S}: 30$ sec., $60 \mathrm{~S}: 60$ sec., 5 M : $5 \mathrm{~min} ., 10 \mathrm{M}$ : 10 min ., non: no return
[Setting example] Setting the operation timeout to 5 minutes

\begin{tabular}{|c|c|}
\hline Display \& Operating procedure \\
\hline 245
250 PV \& \multirow[t]{5}{*}{\begin{tabular}{l}
1. Check that the PV/SV display is shown. \\
2. Press and hold the SEL key to display CH1 (PID parameters). \\
3. Press the key to display CH 12 (Configuration parameters). \\
4. Press the SEL key to enter CH12 (Configuration parameters). toUt (operation timeout) is displayed. \\
5. Press the SEL key. \\
(The first digit of the lower part of the screen begins to blink.) \\
6. Use the (^) (veys to change 60 S to 5 M . \\
7. Press the SEL key to save the change. \\
8. Press the (5) key to return to the PV/SV display.
\end{tabular}} \\
\hline  \& \\
\hline \(\mathbf{t}\) O U t

60 S \& <br>
\hline 5 M sv \& <br>
\hline \& <br>
\hline
\end{tabular}

## SoFK Blinking SV during soft start (942)

[Description] $\qquad$

- Specifies whether or not to blink "SoFT" on SV display during soft start.
- Setting range: oFF: does not display "SoFT" and SV alternately.
oN: displays "SoFT" and SV alternately.
[Setting example] Setting not to blink SoFt



## [Description]

$\qquad$

- Specifies the contents displayed when an alarm occurs.

| Setting | Function |
| :--- | :--- |
| 0 | Displays PV (no change) |
| 1 | Displays PV and the alarm status alternately |
| 2 | Displays flashing PV |
| 3 | Displays the alarm status only (PV is not displayed) |

- The following shows the detail of the contents displayed for each setting.

Setting 0: Displays PV (no change)


Setting 1: PV and the alarm status are alternately displayed when an alarm or alarms occur.

- PV and the alarm number that is activated ("AL1" for the alarm 1 and "AL2" for the alarm 2) are alternately displayed.
oThe alarm number that is activated ("AL1" for the alarm 1, "AL2" for the alarm 2).


PV for 3 sec .

"AL1" for 1 sec .


PV for 3 sec .


Setting 2: Blinking PV is displayed when an alarm or alarms occur.


Setting 3: The alarm status is only displayed when an alarm or alarms occur. PV is not displayed.

- Will be displayed on PV display area.
- The alarm number that is activated ("AL1" for the alarm 1, "AL2" for the alarm 2).
- When both of the alarm 1 and 2 are activated, "AL1" and "AL2" are displayed alternately.

[Setting example] Setting to display only the alarm status during an alarm

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. |
| CH1  <br> CFG pv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the key to display CH12 (Configuration parameters). |
| $\begin{array}{r}\text { tout } \\ 60 \mathrm{~S} \\ \hline \text { PV } \\ \\ \hline\end{array}$ | 4. Press the SEL key to enter CH12 (Configuration parameters). toUt (operation timeout) is displayed. |
| A LM Fpv  <br> 0 sV | 5. Use the (1) keys to change toUt to ALMF. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) <br> 7. Use the © (v) keys to change 0 to 3 . |
| 3 sv | 8. Press the SEL key to save the change. |
|  | 9. Press the (b) key to return to the PV/SV display. |

[Description] $\qquad$
With this function, the displays and indicator lamps are automatically turned off if the specified time passed without any key operation.

| Setting | Function |
| :--- | :--- |
| oFF | Displays stay ON |
| 15 S | Displays are turned off 15 seconds after the last key <br> operation. |
| 30 S | Displays are turned off 30 seconds after the last key <br> operation. |
| 1 M | Displays are turned off 1 minute after the last key <br> operation. |
| 5 M | Displays are turned off 5 minutes after the last key <br> operation. |

- When the displays are turned off, all the displays and lamps except SV lamp will be turned off and PV lamp blinks.
- The displays stay ON during an input error or an alarm status.
- PV and SV will be turned on when an input error or an alarm occurs during the displays are turned off.
[Setting example] Setting the time for auto display off to 15 seconds after the last key operation

[Description] $\qquad$
This parameter is used to manually turn off the PV, SV, and LED lamps on PV/SV screen.

| Setting | Function |
| :--- | :--- |
| 0 | PV, SV, and LED lamps stay ON |
| 1 | SV display OFF |
| 2 | PV display OFF |
| 3 | PV and SV displays OFF |
| 4 | PV, SV, and LED lamps OFF |
| 5 | SV display OFF (relights for 5 sec. by pressing any key) |
| 6 | PV display OFF (relights for 5 sec. by pressing any key) |
| 7 | PV and SV displays OFF (relights for 5 5ec. by pressing any key) |
| 8 | PV, SV, and LED lamps OFF (relights for 5 sec. by pressing any key) |

- In settings 5 to 8 , the displays and lamps stay ON even after 5 seconds, if an input error or an alarm has occurred.
- PV and SV will be turned on when an input error or an alarm occurs during the displays are turned off.
[Setting example] Turning off the PV display



## FLtF Blinking PV at input error (946)

## [Description]

$\qquad$
Allows you to set whether or not to blink PV during an input error (UUUU, LLLL, ERR).

| Setting | Function |
| :--- | :--- |
| 0 | PV blinks during an input error |
| 1 | PV does not blink during an input error |

[Setting example] Setting PV display not to blink during an input error

bLit Brightness (947)
[Description]
Allows you to set the brightness of LED backlight.

- Setting range: 0 to 3 ( 3 is the brightest)
[Setting example] Setting the brightness to 0 (the darkest)

| Display | Operating procedure |
| :---: | :---: |
| 245 250 | 1. Check that the PV/SV display is shown. <br> 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the (-) key to display CH12 (Configuration parameters). <br> 4. Press the SEL key to enter CH12 (Configuration parameters). toUt (operation timeout) is displayed. <br> 5. Use the ©() keys to change toUt to bLit. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) <br> 7. Use the © (v) keys to change 3 to 0 . <br> 8. Press the SEL key to save the change. <br> 9. Press the (5) key to return to the PV/SV display. |
| CH12 ${ }_{\text {CFV }}^{\text {CFG }}$ |  |
|  |  |
| b L i $\mathbf{i}$ Pv <br>  3 SV |  |
| 0 sv |  |
|  |  |

## bCoN Control at burnout (948)

## [Description]

$\qquad$
Allows you to set whether to continue or to stop control when the device detects a burnout of PV input.

- Setting range: oN: continues control
oFF: Stop control (control output depends on the set values of FL01 and FL02.)
[Setting example] Setting to continue the control at burnout $\qquad$

| Display | Operating procedure |
| :---: | :---: |
| $\begin{array}{r} 245 \\ 250 \mathrm{sv} \\ \mathrm{sv} \end{array}$ | 1. Check that the PV/SV display is shown. |
| CH12 1 pv | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Press the key to display CH12 (Configuration parameters). |
|  | 4. Press the SEL key to enter CH12 (Configuration parameters). toUt (operation timeout) is displayed. |
| b Com ${ }^{\text {b }}$ pv | 5. Use the (1) keys to change toUt to bCoN. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| ON sv | 7. Use © ( ) keys to change " oFF " to " oN ". <br> 8. Press the SEL key to save the change. |
|  | 9. Press the (b) key to return to the PV/SV display. |

## PL01 to PL13 Model code (950 to 962)

[Description]
Displays the model code of the controller.
[Setting example] Checking the model code


## [Description]

$\qquad$
Allows you to reset the controller without recycling the power.

- Setting range: oFF: do nothing

RSt: reset the controller
Resetting the controller is equivalent to turning the power off and on.
[Setting example] Resetting the controller


VER1 to VER4 Software version (965 to 968)
[Description]
You can check the software version.
[Setting example] Checking the software version

\begin{tabular}{|c|c|}
\hline Display \& Operating procedure \\
\hline \[
\begin{array}{r|r}
245 \& \mathrm{PV} \\
250 \& \mathrm{SV}
\end{array}
\] \& 1. Check that the PV/SV display is shown. \\
\hline \[
\begin{array}{r|r|}
\text { CH } 12 \& \mathrm{Pv} \\
\text { CFG } \& \mathrm{sv}
\end{array}
\] \& \begin{tabular}{l}
2. Press and hold the SEL key to display CH1 (PID parameters). \\
3. Press the key to access CH12 (Configuration parameters).
\end{tabular} \\
\hline t O U t

60 S \& 4. Press the SEL key to enter CH12 (Configuration parameters). toUt (operation timeout) is displayed. <br>

\hline VER 1 | PV |  |
| ---: | ---: |
| F | SV | \& | 5. Use the ©() keys to change "toUt" to "VER1". |
| :--- |
| 6. Press the (1) key by looking from VER1 through VER4, you can check the software version. | <br>

\hline VER 4 ${ }_{\text {R }} \mathrm{pv}$ \& 7. Press the ( ) key to return to the PV/SV display. <br>
\hline
\end{tabular}

## 3-14 CH13 PASS (Password parameters)

## PAS1 to PAS3 Password setup (990 to 992)

## [Description]

$\qquad$
Allows you to hide a bundle of channels. Once you set a password, an operator will need to enter the password to see the channels.
You can set three passwords maximum: PAS1, PAS2, and PAS3.
Passwords are required at the points shown below. By entering the correct password, you can proceed to the next screen.
Note:
If you forget the password, you can use the master password (FEFE).

[Setting example] Setting the password for parameter change

| Display | Operation procedure |
| :---: | :---: |
| $\begin{array}{r\|r\|} \hline 245 & \mathrm{pv} \\ 250 & \mathrm{sv} \\ \hline \end{array}$ | 1. Check that the PV/SV display is shown. |
| CH13 <br> PASS | 2. Press and hold the SEL key to display CH1 (PID parameters). <br> 3. Use the key to access CH13 (Password parameters). |
| $\begin{array}{r\|r\|} \hline \text { P A S 1 } & \text { pv } \\ 0000 & \mathrm{sv} \end{array}$ | 4. Press the SEL key to enter CH13 (Password parameters). PAS1 (password) is displayed. |
| P A S 2 pv <br> 0000 sv | 5. Use the () keys to change PAS1 to PAS2. <br> 6. Press the SEL key. <br> (The first digit of the lower part of the screen begins to blink.) |
| **** sv | 7. Use the $\qquad$ keys to set the password "****" <br> 8. Press the SEL key to save the change. |
|  | 9. Press the () key to return to the PV/SV display. |

## 4 <br> TROUBLESHOOTING

When a trouble occurs, first check the model, wiring, and parameter settings. The following table shows some typical cases and their solutions.

| Trouble | Cause | Solution | Reference Ch. <br> Screen No. |
| :--- | :--- | :--- | :--- |
| Cannot communicate <br> with the host | Parity does not agree. | Make the parity on the host and the unit <br> the same. | No. 763 |
|  | Communication speed does not <br> agree. | Make the communication speed on the host <br> and the unit the same. | No. 762 |
| Parameters you want <br> to view do not appear | Display mask is set. | A password is set. | Check the DSP settings. |

$\triangle$ Caution on Safety
*Before using this product, be sure to read its instruction manual.

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