

TRIO MOTION TECHNOLOGY **DX3 SERVO PACKAGES**

MOTION TECHNOLOGY

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Cost Optimised Servo Drive

DX3, the single-axis ac servo drive, is designed to create the most cost-effective optimised entry level solution with excellent performance and practical control functions. The Trio DX3 drive is compatible with Trio MX servo motors and Trio Motion Coordinators to provide high-speed, highprecision, high performance machine solutions.

With a power range from 50W to 7.5kW and options for EtherCAT or Conventional (Pulse & Direction, Analogue and CANopen) control, DX3 will suit a wide variety of machine types.

DX3 is fully integrated into Trio's application development tool, *Motion* Perfect, our software environment for system planning, configuration, virtualisation and machine programming.

AT A GLANCE

- ★ Fully integrated into *Motion* Perfect ★ Keypad interface
- Matched with MX motor range
- ★ Internal drive protection functions
- ★ Comprehensive tuning technology
- ★ Field upgradable firmware
- ★ Electronic nameplate
- ★ Compact size
- ★ Zero stacking
- ★ USB commissioning

- ★ 200V ac from 50W to 2kW
- ★ 400V ac from 1kW to 7.5kW
- ★ 350% overload
- ★ 2 Touch Probe inputs
- ★ Preset positions, up to 32 stored positions - Conventional drives only (no Motion Coordinator required)
- ★ EtherCAT or Conventional (Pulse & Direction, Analogue, CANopen) control

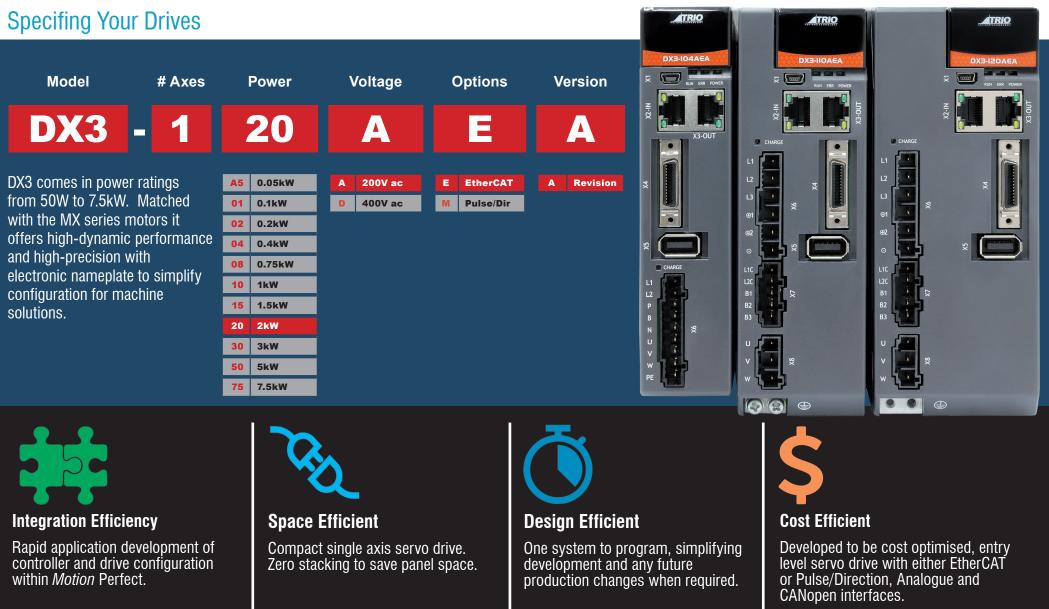


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Preliminary specifications may change without notice

DX3 200V Servo Solutions

Specification

Product	Part #	Output Power	Ĥ	w	D	
200V ac						
DX3-1A5AEA	D3000	5014	172	10	180	
DX3-1A5AMA	D3020	50W		40		
DX3-101AEA	D3001	100W	172	40	180	
DX3-101AMA	D3021	10070	172	40		
DX3-102AEA	D3002	200W	172	40	180	
DX3-102AMA	D3022	20000				
DX3-104AEA	D3003	400W	172	40	180	
DX3-104AMA	D3023	40011	172			
DX3-108AEA	D3004	750W	172	55	180	
DX3-108AMA	D3024	10011		00		
DX3-110AEA	D3005	1kW	172	55	180	
DX3-110AMA	D3025			00		
DX3-115AEA	D3006	1.5kW	172	70	180	
DX3-115AMA	D3026	1.0KW	112		100	
DX3-120AEA	D3007	2kW	172	70	180	
DX3-120AMA	D3027	2.000	112	10		

200Vac								
Drive Model: DX3-	1A5A	101A	102A	104A	108A	110A	115A	120A
Continuous output current [Arms]	0.9	1.1	1.5	2.9	5.1	6.9	9.5	12.6
Maximum output current [Arms]	3.3	4	5.8	11.5	19.5	21	31.6	42
Main power supply unit capacity [kVA] (single phase)	0.2	0.3	0.6	1.2	1.9	2.6	4.0*	-
Main power supply capacity [kVA] (three-phase)	-	-	-	-	1.6	2	3	3.5

*: When operating from a single-phase power supply for the DX3-15AEA (rated power 1.5 kW), please deratify to 1.2 kW.

Products ending with AEA / DEA = EtherCAT Products ending with AMA / DMA = Conventional

<u>____</u> \geq RUN ERR POWER X3-OUT _0_ 0 CHARGE L1 L2 P В Ν 2 П U П W PE ٢ DX3-1A5AEA/AMA DX3-101AEA/AMA

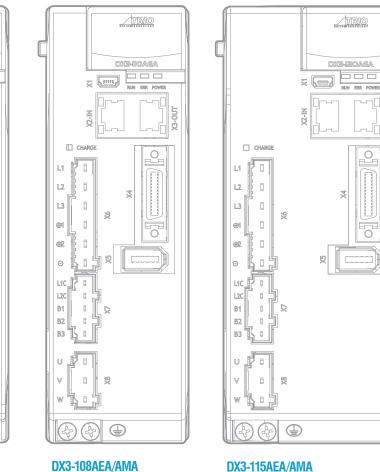
<u>/ TIRIO</u>

DX3-104AEA

DX3-102AEA/AMA

DX3-104AEA/AMA





DX3-110AEA/AMA



Products ending with AEA / DEA = EtherCAT Products ending with AMA / DMA = Conventional

DX3-150DEA/DMA DX3-175DEA/DMA

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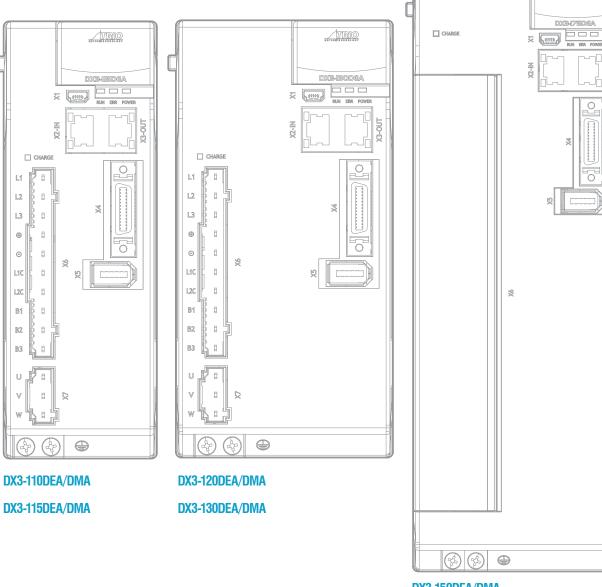
400V Servo Solutions

400Vac

DX3

Specification

Drive model: DX3-	110D	115D	120D	130D	150D	175D
Continuous output current [Arms]	3.6	5	7.1	12	17	27.3
Maximum output current [Arms]	10.9	16.3	24.7	37.8	53	70.7
Main power supply capacity [kVA] (three-phase)	1.8	2.8	3.5	5	8.2	12



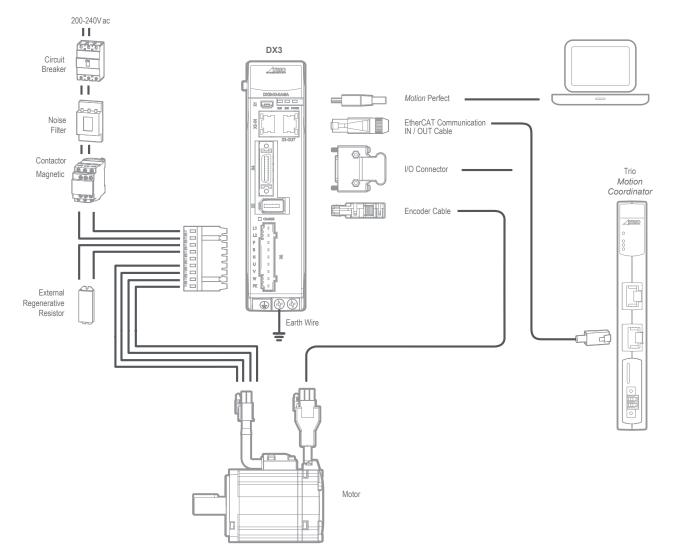


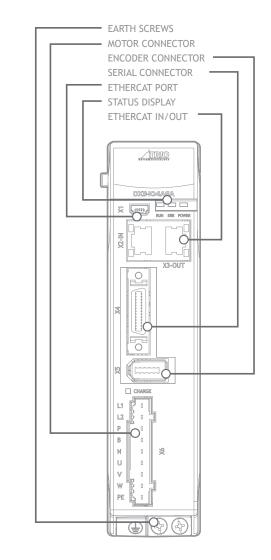
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DX3 Wiring Solution Example



EtherCAT Model Configuration (50W - 400W)



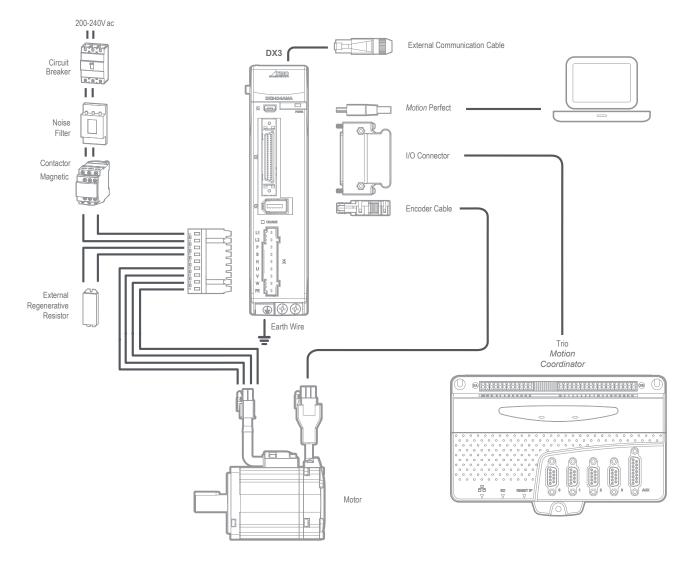


Example illustration showing **AEA** / **DEA** = **EtherCAT**

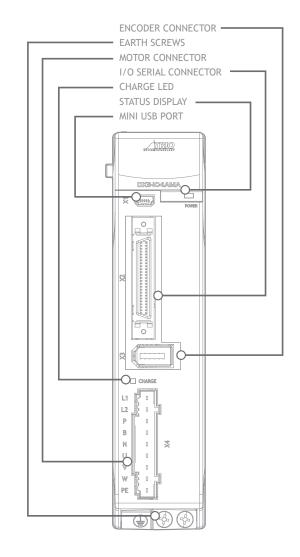
DX3 Wiring Solution Example



Pulse / Dir Model Configuration (50W - 400W)



Products ending with AMA / DMA = Conventional





All Models Specification

Universal specificati	ons		Description				
Input power 200VAC		200VAC	Single-phase AC 200V ~ 240V, -15% ~ +10%, 50Hz/60Hz				
			Three-phase AC 200V ~ 240V, -15% ~ +10%, 50Hz/60Hz (rated power ≥0.75kW)				
		400VAC	Three Phase AC 380V ~ 440V, -15% ~ +10%, 50Hz/60Hz				
Control the power supply		200VAC	Single phase AC 200V ~ 240V, -15% ~ +10%, 50Hz/60Hz				
		400VAC	Three phase AC 200V ~ 440V, -15% ~ +10%, 50Hz/60Hz				
Control mode			SVPWM control				
Feedback			Serial communication encoder with MX motors				
	Working environment	Temperature	When using a single device: -5° C ~ 55° C When multi-device is installed closely: -5° C ~ 40° C				
		Humidity	5% to 95% RH (no condensation)				
	Storage environment	Temperature	-20°C ~ 85°C				
Terms of use	otorage environment	Humidity	5% to 95% RH (no condensation)				
rerms of use	Protection class		IP20				
	Altitude		1000m or less				
	Vibration resistant		4.9m/s2				
	Impact resistant		19.6m/s2				
	Power system		TN system				
Installation structure			Base mounting				
	Speed control range		1:5000				
	Speed volatility		The rated speed \pm less than 0.01% (when the load fluctuates: 0% to 100%) 0% of the rated speed (voltage fluctuations: at \pm 10%) The rated speed is \pm below 0.1% (temperature fluctuations: 25°C \pm 25°C)				
Performance	Soft-start settings		0 ~10s (acceleration and deceleration can be set separately)				
	Input signal		Operating voltage range: 24 VDC±20% Number of input channels: 5 on AEG/DEG, 10 on AMG/DMG				
	Output signal		Operating voltage range: 5 VDC to 30 VDC Number of output channels: 3 on AEG/DEG, 5 on AMG/DMG				
USB port	Communication standards		Conforms to USB 2.0 standard (12 Mbps), OTG				
Commissioning Darts			USB				
Commissioning Ports			EtherCAT (CoE) (only available on AEG/DMG)				
Commisioning Software			Motion Perfect				
Display			5-digit				
Operator Panel			4 buttons				
Indicator Lamps			CHARGE, POWER				
Regenerative braking			Products with rated power of 50W to 400W do not have built-in braking resistors Products with a power rating of 750W to 7.5kW have built-in braking resistors				
Protection features			Overcurrent, overvoltage, undervoltage, overload, regeneration anomaly, overspeed, etc				
Accessibility			Alarm recording, Jog operation, load inertia identification, mechanical analyzer, automatic tuning tools, etc				



EtherCAT Model (AEA, DEA) Specification

EtherCAT Specifications Description IEC 61158 Type12, IEC 61800-7 CiA402 Drive Profile Applicable communication standards Physical layer 100BASE-TX (IEEE802.3) X2-IN (RJ45): EtherCAT Signal IN Bus connection X3-OUT (RJ45): EtherCAT Signal OUT Cable Category 5 twisted pair (4 pairs of shielded twisted pairs). SM0: Output mailbox, SM1: Enter mailbox Sync Manager SM2: Output process data, SM3: Input process data FMMU0: Maps to the Process Data (RxPDO) output area FMMU FMMU1: Maps to the Process Data (TxPDO) send zone FMMU2: Maps to mailbox status EtherCAT Commands (Data Link Layer) APRD, FPRD, BRD, LRD, APWR, FPWR, BWR, LWR, ARMW, FRMW PDO data Dynamic PDO mapping Emergencies, SDO requests, responses, SDO information (TxPDO/RxPDO and remote TxPDO/ MailBox(CoE) RxPDO are not supported) MailBox(FoE) Support FOE firmware upgrade Distributed Clock (DC) Free-run mode and DC mode (switchable) DC synchronization period: 125 µ s to 8ms Slave Information Interface 2048 bytes (read-only) Homing mode, Profile position mode, Profile velocity mode, Profile torque mode, Interpolated position CiA402 Drive Profile mode, Cyclic synchronous position mode, Cyclic synchronous velocity mode, Cyclic synchronous torque mode. Touch probe function. Torque limit function FoE (File Over EtherCAT) Download new firmware via FoF

Conventional (AMA, DMA) Specification

Step/Pulse Model Specifications			Description				
Torque Control	Analogue	Reference Voltage	±10VDC at rated torque Max. input voltage: ±12V				
	reference	Input Impedance	10MΩ or above				
		Circuit Time Constant	10µs				
	Torque Selection	Presets	4 torque selections				
	Analogue	Reference Voltage	±10VDC at rated speed Max. input voltage: ±12V				
Speed Captrol	reference	Input Impedance	10MΩ or above				
Speed Control		Circuit Time Constant	10µs				
	Speed selection	Presets	32 speed selections				
		Туре	Pulse + Direction CCW + CW Pulse A/B Quardature				
Position Control	Pulse reference	Voltage	5V				
		Max Frequency	500kHz (differential) 200kHz (single ended)				
CANopen	CiA402 Drive Pro	ofile	Homing mode, Profile position mode, Profile velocity mode, Profile torque mode, Interpolated position mode				
	Туре		A/B/Z Quadrature				
Encoder output	Voltage		5V				
	Max Frequency		500kHz (differential)				

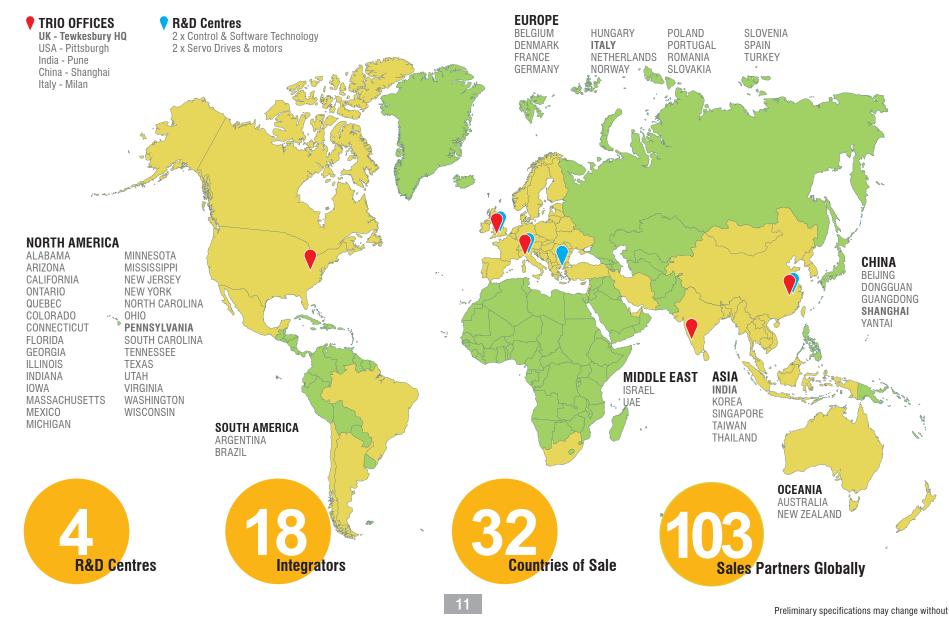
Everything you need... Nothing more





TRIO Worldwide Network









Trio Machine Automation Dechnology Trio has developed powerful rich set of software tools for use with Trio systems. These tools provide all the features necessary for setup and programming to ensure minimum development time.	Development Tools		Motion-iX - Advanced Motion Core			Network / Technologies	
	Project Management	3D Visualisation	Motion-iX Programming	64bit Precision	Up to 128 axis Coordination Control	EtherCAT	RTEX
	Security Project Encryption	6D Motion Scope	IEC61131	Scalable Motion Technologies	Complex Motion	ETHERNET-IP	PROFINET
	Simulation	CAMGen	PLCopen	Kinematic SCARA Delta Cartesian	G-Code and HPGL	MODBUS	DEVICENET
	Drive Configuration	CAD2Motion	API - PC Application Development	Path Planning Look Ahead	Advanced Interpolation	CANOPEN	FUNCTIONAL SAFETY (STO)
	HMI Design	Program Libraries	MOTION-rX ROBOTICS Programming	GEARING/CAM MOVELINK FLEXLINK	Registration Control	OPC UA	

Combining an advanced motion core with Trio's ease-of-use, Motion-iX offers performance and dependability of packaged solutions, from "The Motion Specialist", where motion is the core and not just a bolt-on capability. Motion-iX – a unified software engineering framework for machine development, that places the focus on optimising motion and complex kinematics, including robotics such as SCARA, to deliver truly optimal machine control performance.

Motion-iX includes development in IEC61131 and PLCopen, and boasts inverse kinematics capabilities to truly coordinate all machine axes as one, including

robots to maintain tight synchronisation or robots and machine as one. Virtualization allows simulation of the mechanics and motion to significantly reduce development and testing, delivering optimal control every time, by minimising machine cycle times.

Motion Perfect

Design, Develop, Test, Deploy and Secure



Built on Trio's **Motion-iX** core technology, *Motion* Perfect provides the user with a re-designed easy to understand interface for rapid application development, controller and drive configuration and monitoring of functions.

The commissioning of DX Servo Drives is made simple with a series of Device Configuration Screens allowing access to status information and diagnostics at a glance. All motor axes can be detected, setup, monitored and controlled in real-time from the easy to use dialogue windows.

Motion Perfect includes access to IEC 61131 and PLCopen and the robotics solution; TrioRPS. Advanced visualisation including a 3D oscilloscope and IP protection of your projects are also included within *Motion* Prefect.



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Trio Motion Technology specialises in advanced motion control as a core, providing a range of *Motion Coordinators*, drives and motors, expansion interfaces, I/O modules and HMI's built on *Motion*-ix technologies and designed to enable the control of industrial machines with the minimum of external components.

In support of the Trio concept, we aim to offer the best technical support by telephone, email, our comprehensive website and training courses held throughout the year. Please look at our web site for details.

www.triomotion.com

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