AUTOMATION APPLICATIONS
IN AN ADVANCED AIR TRAFFIC
MANAGEMENT SYSTEM
Volume VB: DELTA Simulation Model - Programmer's Guide
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### 1.0 INTRODUCTION

This is Volume V-Book II of a five volume report produced for the Automation Applications Study of the Advanced Air Traffic Management System. This volume describes the DELTA (Determine Effectiveness Levels for Task Allocation) digital computer simulation model. The volume is divided into two Books: Book I - User's Guide and Book II - Programer's Guide.

The User's Guide is designed to permit an analyst to understand what the model simulates and how to exercise the model. It discusses the concepts from which the model was constructed. A complete input data specification and deck setup is described to show how cases are set up. A test case is provided to show how a case would look. Several auxilliary programs which are used to produce input files are described along with the Post Processor Program which is used to produce an additional output report for the DELTA model.

The Programmer's Guide is designed to give a programmer insight as to how the DELTA model was built and to enable him to make extensions or modifications to the model's code. There is a general discussion of the program structure and a description of the link structure and the system considerations.

There are detailed descriptions of the subroutines and the dynamic memory file structures. Samples of overlay structures are given and a list of subroutines which reference the files is shown.

### 2.0 PROGRAM STRUCTURE

### 12.1 General Discussion

In this documentation a "run" refers to an exercise of the model for which the input data remains fixed. Each approach to the computer is called a "job" and will usually be synonomous with run for this model. The complete input data set for a run specifies a "case".

The computer software for the DELTA model is composed of a program with three major components: input processor, simulation, and report generator, plus three separately executable proarams: Terminal Generation Program, Interarrival Times Generation Program, and Post Processor. The input processor component sets up SALSIM files, allocates dynamic memory, reads scenario data and performs limited validity checkina on the data. The simulation component simulates the interaction between resources and service requestors in an Air Traffic Management environment and writes a history tape. The report generator component summarizes information available during the execution of the run. The Post Processor proaram sorts information on the history tape and produces an additional report. The Terminal General Program is used to produce a random access data file used by the simulation. The Interarrival Times Generation Program is used as an aid in defining flight plans to stimulate the model. The separately executable programs are described in specific sections of both books of this volume.

### 2.1.1 Input Processor

That data which describes the SALSIM parameters and the scenario are read by the input processor. The SALSIM routine XXSTRT allocates the dynamic memory and sets up the bookkeeping for the loaic control chains which will be executed. The routine INITIA sets up the bookkeeping. for the user's dynamic memory files and reads the scenario data: namelist, task allocations and times, aircraft types, jurisdiction and resource descriptions, and initiates the tasks which are performed cyclically.

### 2.1.2 Simulation

The execution of the simulation component is controlled by SIMRUN which alternately transfers control between EXOG and ELIST. EXOG reads the input file for exogenous events which are used to stimulate various tasks in the model, while ELIST calls the Logic Control Chain (LCC, subroutine) which is next in the time queue to be performed. SIMRUN determines when it is appropriate to read the next exogenous event and updates the simulation clock after all tasks for a particular time have been executed.

The LCC's are called, in general, directly by ELIST. If one LCC is supposed to cause another LCC to begin execution, then it will create an "event notice" for that LCC and file it in the simulation time queue. When the appropriate time occurs for the LCC to be executed, then ELIST calls the LCC. The LCC immediately calls ALLOC to get a resource allocated to perform the task. If none is available, the task is put into a queue to be performed when a resource can be assigned; otherwise, the resource is set busy and the task is performed.

There are two types of tasks: cyclical (time stimulated) and event stimulated. The cyclical tasks are executed at some regular frequency during the run and stimulate themselves. Event stimulated tasks occur either exogenously - externally stimulated, or endogenously - internally stimulated. An exogenous event, read from the input tape by EXOG, can cause an entire chain of events to occur. For example, "filing a flight plan" is an exogenous event which can generate events throughout the air traffic management system until the aircraft either lands or flies out of the geography being modelled. A typical run combines the cyclical tasks, which appear as "background" consumers of resources; and the user generated tasks, which are initiated by input.

A run is terminated by input of an exogenous event. to call the run summary at some specified game time. The simplest type of run would be one where there were no external events other than the termination. This would give a measure of how many resources were being consumed by background tasks.

### 2.1.3 Report Generator

The DELTA model has a run summary which presents information on resource utilization for the run which was calculated during execution. The data is broken down by jurisdiction, resource pool and element. The summary also lists statistics on the utilization of the dynamic memory.
2.2 Subroutine and Link Structure
Figure 2.2-1 shows the basic subroutine linkage of the DELTA model.In general the figure is read from left to right, then top to bottom.Since all 165 functional analysis task subroutines are called directly orindirectly by ELIST, the figure merely references the function number.Also the algorithms are shown only by their primary subroutine name; theirstructures are shown in the following figures. Figure 2.2-2 shows thestructure of the algorithm which moves aircraft, simulates error and per-forms boundary crossings. The metering and sequencing algorithm is shownin Figure 2.2-3. Figure 2.2-4 illustrates the calling structure of thehazard evaluation and conflict resolution algorithm.


Figure 2.2-1 Basic Linkage of DELTA Model


Figure 2.2-2 Linkage Of Kinematics Algorithm


Figure 2.2-2 continued


Fioure 2.2-3 Linkage of Meterina and Sequencing Algorithm


Figure 2.2-4 Linkage Of Hazard Evaluation and Conflict Resolution Algorithms


Figure 2.2-4 continued


Figure 2.2-4 continued

### 2.3 System and Hardware Considerations

The DELTA Model software was designed to be compiled and executed on a CDC 6600 compatible system using a MACE operating system. Elsewhere in this volume is a detailed account of the job control cards required to execute the model on the TRW in-house configuration. As described in Section 3.1, the model uses some CDC and TRW-unique software. The model routines all compile using the RUNX compller.

The software making up the DELTA Model requires a large amount of core if no overlays are used. During the debug phase of development, an overlay structure was configured permitting the model to fit within 60,000 octal words of memory. (Note that the core sizes are indicated in octal numbers, following the CDC conventions.) This was done at the expense of the dynamic memory and the input/output buffers. During model exercise, a more optimal overlay was used, requiring 117,000 octal words. This overlay is described in Section 5. The overlays are designed to utilize the Automatic Overlay Loading feature of the CDC Loader.

In order to run DELTA on other systems, several software modifications must be made. Of primary importance is the sixty bit word length found on the CDC systems discussed above. This word length permits fifteen significant digits on real numbers. This is especially important with respect to the model's internal clock, which must maintain flight durations of multiple hours, manual task times in tenths of seconds and automated task times in nanoseconds. Here the sixty bits is of greatest value.

Several instances can be found within the MQVAC loaic of the use of the sixty bits as holders of three twenty bit words, such as normalize error terms or pointers within dynamic memory. However, these conditions are in the minority, since the model was written to be as hardware independent as possible. The MAIN routine is also specific to the CDC system, and would require modification should the system be changed. See Section 3.3.

The format statements are another area which would require modification. The CDC FORTRAN permits the use of the asterisk (*) for delimiting literals within Format statements and the use of $\emptyset$-formats to read and write octal variables. These must be changed. However, these areas appear to be only system dependencies in the model software.

### 3.0 SUBROUTINE DESCRIPTINNS

### 3.1 Introduction

The DELTA Model is composed of five types of routines. These are the following:
A. FORTRAN or system library routines, such as SIN and ARS.
B. SALSIM utilities, such as CAUSE and DELAY.
C. Model utility routines, such as ALLDC and TSELEC.
D. Algorithms, such as METSEQ and MOVAC.
E. Functional analysis routines, T01101 through T17300.

These routines combine to form the simulation program. Most of the routines are written in FORTRAN IV. The software developed for this model (types C, D and E) is heavily commented to eliminate the need for detailed flow charts or narrative descriptions. This section is intended to provide the programmer with a basic backaround for understanding the program. The descriptions are intended to amplify those in the User's Guide, Book I of this volume.

### 3.1.1 System Library Routines

It is necessary to discuss several of the routines of the first type, those supplied in the FORTRAN Library of Subroutines or in the TRW Subroutine Library. Most of the routines that belong to type A are common to all FORTRAN Packages. There are five exceptions, however. These are routines that are peculiar to CDC FORTRAN or the TRW Subroutine Library. These routines are described below.

LBYT - This routine is used to extract the values of bits within a word. It will extract from one to sixty bits from a word. The routine is part of the TRW Subroutine Library.

SBYT - This routine is used to set the values of bits within a word. It will set from one to sixty bits of a word. The routine is part of the TRW Subroutine Library.

UPR1 - This routine is a uniform pseudo random number generator. It is called by function subprogram RANF. UPRT is part of, the TRW Subroutine Library. It is similar to IBM's RANDU subprogram in many respects.

FNRN - This routine is a normal random number generator. It is part of the TRW Subroutine Library.

Finally, the direct access input/output routines used in the model are specific to the CDC FORTRAN Library of Subroutines. These are $9 P E N M S$, CLDSEMS, READMS and WRITMS. Since there is no standard direct access I/0 package defined for FORTRAN, it is common for each manufacturer to use his own I/O routines.

### 3.1.2 SALSIM Utilities

The remaining types of routines will be discussed below. The SALSIM utilities are FORTRAN subroutines which facilitate the construction of the event stepped features of the simulations. For example, they permit the use of dynamic memory, providing efficient core allocation. They provide for an internal model clock, interaction between exogenously and endoqenously stimulated events and event scheduling. These routines are general purpose in nature.

### 3.1.3 Model Utilities

The model utilities are specifically designed for the DELTA Model. They are intended to facilitate the special-purpose processing common to many of the routines in the model. Five of these routines deserve special mention. These are the routines most directly concerned with resource utilization: ALLøC, GETASK, GETIME, DELAY and TSELEC.

ALLDC is used to assign a resource element to a task. If no resource element is available, this routine attempts to increase the capability of the resource pool (either by incrementina the number of controllers for a manual pool or by increasing the computer's speed for an automated pool), if the pool is not at maximum capability. Failina this, ALLøC will place the task in the Task Queue.

GETASK is a routine used to obtain all pertinent information on the allocation and task time for a particular task. It is used by ALLøC, GETIME, TSELEC and other utilities. Given the LCC Number (see Table 3.2-3), GETASK searches the task data files and returns the desired data.

GETIME is used to determine the amount of time required for the performance of a task. It uses GETASK to select the distribution or number of instructions, and then picks a time from the distribution or determines the length of time from the number of instructions and the computer's processina rate. This time is used by DELAY as the lenath of time to interrupt processing and the time is credited to the resource element performing the task.

TSELEC is used to relieve the resource element from its current assignment at completion, and attempt to reassian it to either the next task in a task chain or to the hiahest priority task in the Task queue. If there are no further demands on the resource element, it is placed in a not busy status and returned to the resource pool.

This set of model utilities is the basic requirement for the treat ing of resource utilization within the DELTA Model. It will be discussed below.

### 3.1.4 Algorithms

There are three principle algorithms used in this model. They are responsible for the motion of the aircraft throuah the system. The first of these is MØVAC, which contains the aircraft kinematics, the naviaation error model, and the boundry crossing logic. The schedulina and interleaving of arrivals and departures, metering and sequencina, is performed by the METSEQ algorithm. Separation assurance, conflict detection, hazard evaluation, and conflict resolution are performed by CONDET algorithm. The analysis on which these alaorithms is founded is described in the User's Guide, Book I of this volume. The resulting routines are described briefly below.

### 3.1.5 Functional Analysis Routines

The functional analysis resulted in the generation of about two hundred routines. The functional analysis is described in great detail in Volume II. The resulting software is described briefly below.

Of the seventeen functions defined by the functional analysis, Functions 10. and 14. were not modelled. In order to simplify some of the programming, some functional analysis tasks were grouped into single routines. Except for these routines, there is a direct relationship between functional analysis tasks and functional analysis routines.

### 3.2 Conventions

The DELTA Model employs several programming conventions or standard practices which, during model development and testing, permitted a high degree of commonality among the routines. This is especially true of the functional analysis routines. These conventions will be described in this section to provide the programmer with greater insight into the model.construction.

### 3.2.1 Subroutine Naming Convention

As discussed in the previous section, there is a close relationship between the functional analysis described in Volume II and the functional analysis routines. To foster this relationship, a naming convention was adopted in which the task name is embedded in the subroutine name. Thus, task one, of subfunction one, of function one (Task 1.1.1) is simulated by a routine named T01101. In general, the routine name is of the form, Tffstt, where ff is the function number, $s$ is the subfunction number and tt is the task number. Table 3.2-1 contains a complete list of the routines of this sort.

This table also contains the Logical Control Chain (LCC) number for each routine which is an LCC. The LCC is a SALSIM-based convention. It represents a triggerable routine, as opposed to those which are simply FORTRAN subprograms. This difference will be described in a discussion of the SALSIM utility routines, Section 3.4. The use of dynamic memory and the dynamic memory file structures will be discussed in Section 4. Dynamic memory is another SALSIM-based programming convention.

### 3.2.2 SALSIM Conventions

The use of the model and SALSIM utility routines is another convention of the DELTA Model. It imposes a great deal of similarity among the task-simulating routines. Figure 3.2-1 represents the typical structure of one of these routines. The Standard Event Notice, Page 4.0-23 , carries all the information necessary for the operation of each of these LCCs. This is done by means of standard locations for pointers and indicators within dynamic memory.

```
TSELEC - 1
M\emptysetVAC - 2
T01101 - 3
T01102 - 4
T01103 - 5
T01201 - 6
T01202 - 7
T01301 - 8
T01302 - 9
T01303 - 10
T02000-11
T02MAN - 12
T02AUT - 13
T02ALG - 14
T02202 - 15
T03000 - 16
T04100 - 17
T04101 - 18
T04102 - 19
T04201 - 20
T04202 - 21
T04203 - 22
T04204 - 23
T04205 - 24
T04206 - 25
T04207 - 26
T04208 - 27
T04209 - 28
T04210-29
T04211 - 30
T04212 - 31
T04213-32
T04301 - 33
T04302 - 34
T04303 - 35
T04304 - 36
T04401 - 37
T04402 - 38
T04403-- 39
T04404 - 40
T04405 - 41 (DELETED)
T05101 - 42
T05102 - 43
T05103 - 44
T05201 - 45
T05202 - 46
T05203 - 47
T05204 - 48
T05301 - 49
T05302 - 50
T05303 - 51
T0522A - 52
```

| T05100-53 |  | T11101-142 |
| :---: | :---: | :---: |
| T061AU - 54 |  | T11102-143 |
| T061MN - 55 |  | T11201-144 |
| T06201-56 |  | T11202-145 |
| T06303-57 |  | T11203-146 |
| T06400-58 |  | T11204-147 |
| T06401-59 |  | T11301-148 |
| T06402-60 |  | T11302-149 |
| T06402-61 |  | T11303-150 |
| T06403-62 |  | T11401-151 |
| T06405-63 |  | T11402-152 |
| T06406-64 |  | T11403-153 |
| T06407-65 |  | T11501-154 |
|  |  | T11502-155 |
| T07101-66 |  | T11503-156 |
| T07102-67 |  |  |
| T07103-68 |  | T12101-102 |
| T07104 - 69 |  | T12102-103\& 104 |
| T07105 - 70 |  | T12103-105 |
| T07201-71 |  | T12104-106 |
| T07202-72 |  | T12105-107 |
| T07301-73 |  | T12106-108 |
| T07302-74 |  | T12107-109 |
| T07,303-75 |  | T12201-110 |
| T07401-76 |  | T12202-111 |
| T07402-77 |  | T12204-112 |
| T07403-78 |  | T12205-113 |
| T07404-79 |  | T12206-114 |
|  |  | T12207-115 |
| T08101-80 |  | T12301-116 |
| T08102-81 |  | T12302-117 |
| T08103-82 |  | T12303-118 |
| T08104 - 83 |  | T12304-119 |
| T08105-84 |  |  |
| T08107-85 | ' | T13100-120 |
| T08108-86 |  | T13102-121 |
| T08109-87 |  | T13104-122 |
| T08200-88 |  | T13105-123 |
| T08201-89 |  | T13201-124 |
| T08202 - 90 |  | T13202-125 |
| T08203-91 |  | T13203-126 |
| T08204 - 92 |  | T13301-127 |
| T08205-93 |  | T13302-128 |
| T09100-94 |  | (F14.0 Not Modeled) |
| T09201-95 |  |  |
| T09202-96 |  |  |
| T09300-97 |  |  |
| T09400-98 |  |  |
| T09501-99 |  |  |
| T09505 - 100 |  |  |
| T09506-101 |  |  |
| (F10.0 Not Modeled) |  |  |

Table 3.2-1 Table of LCC Numbers for Routine Names

```
T15101 - 160
T15102 - 161
T15201 - 162
T15202 - 163
T15203-164
T15204-165
T15205 - 166
T15206 - 167
```

```
T16101 - 129
T16102 - 130
T16103-131
T16201-132
T16202 - }13
T16203 - 134
T16204 - 135
T16205 - 136
T16206-137
T16207 - 138
T16208-139
T16209 - 140
T16210 - 141
T17100-157
T17200-158
T17300 - 159
Utilities and Algorithms
UDP\emptysetF - 168
UDMSW - }169\mathrm{ (not used)
DRPAC - 170
METSEQ - 171
HAZARD - }17
TCANAC - 173
RSCRSE - }17
```

Table 3.2-1 (contd.) Table of LCC numbers for Routine Names

Grouped Names
Functional
Analysis Names

Analysis Names

Grouped Names
$\qquad$

Functional
Analysis Names



Figure 3.2-1 Flow Chart of a Typical Functional Analysis Routine.

Page 3.2-6

### 3.2.3 Typical LCC

A positive value for NXTSK is used to indicate that the processing has resumed after a delay. ALLOC sets the value of IRESRC, which is then tested to determine if the task was placed in the Task Queue due to the unavailability of a resource element for the current task indicated by a negative IRESRC. If not, GETIME is used to generate a task time which is then passed to DELAY. Following the delay, any processing required by the task is performed and the next task to be performed, if any, is determined. Triggering TSELEC then results in the triggering of the selected task or next activity for the resource element allocated for this task. This structure is basic to the resource-using routines.

### 3.2.4 Variable Naming Convention

Where possible, variable names for the task routines are related to both their usage and their task number. Figure 3.2-2 contains an outline of this naming convention. Further discussion of input variables will be found in Book I of this Volume.

### 3.2.5 Task Grouping Convention

As will be noticed in Table 3.2-1, there is not a one-to-one relationship between functional analysis tasks and LCCs. This is due to a simplification made to the programming logic. It was decided that in several instances, there are tasks which could be grouped together in all reasonable system designs. These groupings are indicated in Table 3.2-2. The groupings reduce the number of LCCS required to model all the tasks. Another form of grouping of task performance used in the model is the blocking of tasks. This is done typically for time-cyclic tasks performed for all aircraft in a jurisdiction. Blocking involves performing the task for several aircraft together by multiplying the task performance times by the appropriate number of aircraft. This is determined by input, to give the user as much control as possible. A third grouping technique is along allocation lines. Thus, all manual tasks in such a grouping are simulated by one routine and the automated tasks, by another.
As many variables as possible will have names made up in the following way:
affstt
where $f f$ is the Function number
5 is the Subfunction number
tt is the Task number
and $a$ is an alphabetic with the following characteristics:
$C=$ Duration of one cycle of a periodic task (hrs.).
$F=$ Rate (inverse of frequency) of a periodic task.
$I=$ ELIST block pointer (defined in Block Data).
$M=$ Mask for a test under mask.
$P=$ Probability of condition occurring.
$R=$ Requirement (Comparison word for test under mask).
$T=$ Subroutine name containing referenced task.

FIGURE 3.2-2 NAMING SCHEME FOR STANDARD VARIABLES

### 3.2.6 Parallel Tasks

Some tasks may not be triggered until a set of parallel tasks have been completed, as in the case of Function 4, for example. Towards this end, the ACCUM routine was designed to accumulate task completions until all required tasks had been performed, before the indicated next task could be triggered.

### 3.2.7 Bit Logic Conventions

In order to carry as much information as possible per word of data, the model often uses the sign of a variable as a logical indicator. For example, in the Standard Event Notice, a positive value for IACFT implies that the value is the pointer to an aircraft, while a negative value indicates that the absolute value is a pointer to a jurisdiction. Similarly, a positive IRESRC is a pointer to a resource element, while a negative value indicates a pointer to a resource pool.

ACBITS of the Aircraft File is a collection of indicators describing the status and other information on the aircraft to which it belongs. This is done by considering the word to be a collection of binary switches, which are for the most part independent. LBYT and SBYT, described above, are used to test and set these bits: Table 3.2-3 contains a description of their uses. Table 3.2-4 indicates which routines use particular bits. As can be seen, only thirty two of the sixty bits have been used, in order to permit the conversion of the program to other computer systems.

### 3.2.8 Internal Units

Within the algorithms, a units convention was adopted, covering the units used within the model to reduce repeated conversion. The DELTA Model uses nautical miles, hours and radians as standard units, converting inputs when read. Hence, speeds are in knots (nautical miles per hour) and turn rates are in radians per hour. All distances, including altitudes, are in nautical miles.

TABLE 3.2-3 ACBITS USAGE
DESCRIPTION
Discrepancy between flight plan and capability and status
of Aircraft
Discrepancy between flight plan and operational and
environmental condition
Discrepancy between flight plan and other approved flight
plans
Discrepancy between flight plan and flow control directives
Discrepancy between flight plan and rules and procedures
Discrepancy between flight plan and flight progress
Discrepancy between flight plan and user class/pilot
qualifications
Flight plan being reviewed (subsequent reviews)
Current deviation out-of-tolerances
Enlarged tolerances being used
End of flight Indicator
Flight plan revision from Task 7.1 .5
Flight plan under revision
Short range deviation out of tolerances
Long range deviation out of tolerances
Controlled aircraft
Intensions known aircraft
IFR aircraft
VFR aircraft
Flight plan being resubmitted (subsequent submission)
Metering and Sequencing status switch
l = M\&S Queue entry created,
2 = Missed approach selected
3 = M\&S hold complete
4 = M\&S no hold solution
5 = M\&s hold solution
6 = Missed approach solution
Not used
Iot used
Special call 2 for movaC triggered
Hold type indicator for aircraft in holds (T-en route,
F $\rightarrow$ M\&S)

## TABLE 3.2-3 ACBITS USAGE (Cont'd)

## BIT NUMBER <br> DESCRIPTION

| 28 | Hold status indicator ( $F \rightarrow$ never in hold), see Bit 31 |
| :--- | :--- |
| 29 | Not used |
| 30 | Aircraft handover initiated |
| 31 | Hold status indicator ( $F \rightarrow$ had been held, not currently, <br>  <br> 32$\quad$Emergently in hold) |
| 32 | Emergicator |

Page 3.2-12


## Page 3.2-13

```
            LEGEND: T = Set On; F = Set Off; U = Use
SUB-
\begin{tabular}{lllllllllllllllll} 
ROUTINE & 16 & 15 & 14 & 13 & 12 & 11 & 10 & 9 & 8 & 7 & 6 & 5 & 4 & 3 & 2 & 1 \\
\hline
\end{tabular}
ACJBC2
CONDET U
FILHAZ U
MQVAC
RECHECK U
T\emptysetLFX5 U U
T03000 TF
T04101 F
T04201 U
T04202 U
T04203 U
T04204
T04205
T04206
T04207
T04210
T04302
T04401
T04402
T05202
T0522A
T06403
T07102 U
T07104 TU T
T07201 U U U TF
T07301
T07302
T07303
T07401 U U
T07403
T
T07404
T16103
UDP\emptysetF
M16
TABLE 3.2-4 ACBITS CROSS REFERENCE (Cont'd)
```


### 3.3 MAIN Routine

Program MAIN is the entry point for the model. Within CDC program structure, the main routine includes the input/output device list for the remainder of the routines. It is also the first routine loader, and, CDC convention indicated that the lenaths of the common blocks are determined at the first encounter of a common block. Hence, it is in MAIN that the length of the IV array for dynamic memory is set. For batch processina, a lenath of 15,000 words has been used. This value is compiled into MAIN. The minimum lenath permitted is 2000 words, since this lenath is compiled into most of the LCCs.

The DELTA Model uses the following set of FORTRAN loaical units:

TAPE5 is the main input file, containing the SALSIM card, Name list, task input data, pilot response times, aircraft type data, jurisdiction data, scenario data and exoaenous inputs.

TAPE6 is the primary scenario output file, containing diagnostic and warning messages and the DATAFIL end of run summary.

TAPE10 is used for the ACPTS file, maintained as a temporary file by GETAC and MQDAC.

TAPEL2 is the Conflict Detection Grid file, maintained as a temporary file by CANDET.

TAPE14 is the simulation history file which is used by the Post Processor in various forms.

TAPE21 is the prime file for aircraft pair data, used as a temporary file by the Conflict Detection routines.

TAPE22 is the Conflict Resolution Maneuver file.
TAPE23 is the file used by the Conflict Detection routines to check for new conflicts.

TAPE30 is the Terminal Data input file used by METSEO.
The only other activity performed by MAIN is the calling of XXSTRT, the SALSIM initialization routine.

### 3.4 Utility Routines

### 3.4.1 SALSIM Subroutines

All of the list processing requirements described in section 5.0, Dynamic Memory File Structure, utilize a TRW simulation lanquage called SALSIM.

SALSIM is comprised of FORTRAN subroutines and functions which allow the user to create lists having an arbitrary number of entries. The system uses a large one dimensional array, IV, which contains all the lists.

For example, a typical list of information might have 8 records, each 10 words long. Ten consecutive words (subscripts) of the IV array then holds 1 record. Each record is located somewhere in the IV array. Note that although words of a record are consecutive, the records themselves usually are not consecutive. One of the ten bytes of each record contains the IV array subscript of the first word for the next record in the list.

Each record of a few lists also contains a similar subscript for the preceding record in a list. When there is no preceding or following record in the list, the byte containing the IV subscript is zero. Each item in a record for a single list has a name equivalenced relative to the IV array for easier accessinc.

The SALSIM subroutines are used for bookkeepina of the lists. They allow the user to easily insert a record into a list withnut consciously changing pointers to or from that record.

The primary advantage of using this list processing technique is that data storage can be allocated dynamically. Once a fixed amount of core has been allocated to the IV array, the amount of core used by each list can be allocated or freed repeatedly durina execution according to the requirements of the current model run.

Each list has an ordering which is specified when the list is created. Each list has exactly one of the following orderings for filing and accessing records: last in first out, first in first out, increasing order of attribute (ranked low is first), decreasing order of attribute (ranked high is first).

The ordering as well as other characteristics for a list are defined exactly once when the list is created by use of the SALSIM DEFSET function, which is described in detail later in this section.

SALSIM is used extensively by the utilities, aloorithms, and functional analysis tasks described in sections 3.4, 3.5, and 3.6. Besides using SALSIM to handle lists of data, these routines can triager (schedule) events to occur at a future simulation time. Events are placed in a queue (another list) until the simulation time has caught up with the event. The event is then removed from the queue and processed by the indicated subroutine, called an LCC.

Each LCC has associated with it a number which the user indicates when triggering an LCC for execution by use of the CAUSE subroutine described in this section. A complete list of the LCC numbers is aiven in section 3.2, CONVENTIONS.

## SALSIM Subroutine: CANCEL (LCCNO, IPT)

A. PURPOSE

This routine cancels an event notice in the event queue.
B. INPUT

LCCNO: LCC number of the event. (Integer)
IPT: Pointer to the event in the IV array. (Integer)
c. OUTPUT

None
D. USAGE

CALL CANCEL (LCCNO, IPT)

SALSIM Subroutine: CAUSE (LCCNO, IPT, TIME)
A. PURPOSE

This routine schedules an event to be processed by a specified subroutine at a aiven simulation time.
B. INPUTS

LCCNO: LCC number of subroutine to be triggered. (Integer) IPT: Current event number, a number assianed by the system and always acessed from the integer variable EVENT. (Integer)
TIME: Simulation time that subroutine is to be called. (Integer)
c. OUTPUT

None
D. USAGE

CALL CAUSE (LCCNO, IPT, TIME)

SALSIM Function $\mathrm{I}=$ CREATE (L)
A. PURPOSE

This routine allocates a specified amount of consecutive words in the IV array to store a record in a list.
B. INPUTS

L: Length of record to be created. (Integer)
C. OUTPUT

I: The pointer to record, i.e., the IV subscript number preceding the location of the record to be stored. (Integer)
D. USAGE

I=CREATE (L)
E. REMARK

This routine does not store the record. The record is stored in a list by the FILE command, which uses the I parameter as input.

```
SALSIM Function ISET=DEFSET (T,F,L,S,P,R)
```

A. PURPOSE

DEFSET defines the attributes of a list to be created. These attributes remain unchanged for the duration of the model run or until the list is deleted (not just emptied).
B. INPUTS

T: An integer that indicates the ordering rule for the list. The permissible values of $T$ are:

1, last in first out;
2, first in first out;
3, increasing order of attribute (ranked low is first);
4, decreasing order of attribute (ranked high is first).

F: First pointer (Integer)
L: Last pointer (Integer)
S: The word position in a record for holding the pointer (subscript) to the record's predecessor. (Integer)

P: The word position in a record for holding the pointer to the record's successor. (Integer)

R: Used only for ranked files ( $T=3$ or 4). This is the word position in a record upon which the list is ordered. R is zero for ( $\mathrm{T}=1$ or 2). (Integer)
C. OUTPUT

ISET: The pointer (subscript) in the IV array that holds the DEFSET information. (Integer)
D. USAGE

ISET= DEFSET (T,F,L,S,P,R)
E. REMARK

The DEFSET is called exactly once to create a list. The ISET parameter is used as input to many SALSIM subroutines.
SALSIM Subroutine DELAY (EVENT, D)
A. PURPOSE
This routine delays the current event, whose number isEVENT, for a specified amount of time. When this time occurs,processing of the event resumes.In addition, this subroutine talleys the resource utiliza-tion time and stores the result in the Resource Element File.
B. INPUTS
EVENT: The current event number, which is always accessedfrom the variable EVENT. (Integer)
D: The time delay from current time. (Integer)
c. OUTPUT
None
D. USAGE
CALL DELAY (EVENT, D)

SALSIM Subroutine DSTROY (IPTR, L)
A. PURPOSE

DSTROY releases the locations in the IV array for a record no longer needed. The space is then available to store a record for any list.
B. INPUTS

IPTR: The pointer to the record to be destroyed. (Integer)
L : The length of the record to be destroyed. (Integer)
c. OUTPUT

None
D. USAGE

CALL DSTROY (IPTR, L)

## SALSIM Subroutine FILE (IPTR, ISET, IPT1)

A. PURPOSE

FILE inserts a record into a list according to the ordering defined by the DEFSET function.
B. INPUTS

IPTR: The pointer to the first word of the record in the IV array. IPTR is obtained from the CREATE function, which is usually performed prior to executing the FILE subroutine.
(Integer)
ISET: The pointer to the list's DEFSET characteristics. (Integer)

IPT1: Index (owner) of the list. (Integer)
C. OUTPUT

None
D. USAGE

CALL FILE (IPTR, ISET, IPT1)

## SALSIM Function $\mathrm{IT}=$ FIRST (ISET, J)

A. PURPOSE

FIRST stores in the variable Il, the address of the first record in the list associated. with list ISET, J.
B. INPUT

ISET: The pointer to the list's DEFSET characteristics (Integer)

J: Index (owner) of list. (Integer)
C. OUTPUT

I]: The pointer to the first record of the list, i.e., the subscript in the IV array. Il is zero if the list is empty. (Integer)
D. USAGE

$$
I I=F I R S T(I S E T, J)
$$

SALSIM Function I2=NEXT (ISET, IPTR)
A. PURPOSE

The NEXT function retrieves the address (subscript) of the record following a specified record address.
B. INPUT

ISET: The pointer to the list's DEFSET characteristics (Integer)

IPTR: The address of the record for which the next record is desired. (Integer)
c. OUTPUT

I2: The pointer to the next record. (Integer)
D. USAGE

I2 $=$ NEXT (ISET, IPTR)

## SALSIM Function $\mathrm{II}=$ RFIRST (ISET,U)

## A. PURPOSE

This function removes the first member from a specified list.
B. INPUT

ISET: The pointer to the list's DEFSET characteristics. (Integer)

IPTR: The index (owner) of list. (Integer)
C. OUTPUT

I1: The address of the record removed from the list. (Integer)
D. USAGE
$\mathrm{II}=\operatorname{RFIRST}(\mathrm{ISET}, \mathrm{J})$

## E. REMARKS

This function does not release the space occupied by the record removed from the IV array. To do so, the DSTROY subroutine should follow the RFIRST function.

```
SALSIM Subroutines RSPEC (IPTR, ISET, J)
    or RSPECl (IPTR, ISET, J)
```

A. PURPOSE

Subroutine RSPEC removes a record from a specified ranked file. Subroutine RSPEC1 removes a record from a specified last-in-first-out file.
B. INPUT

IPTR: The pointer to the record to be removed. (Integer)
ISET: The pointer to the list's DEFSET characteristics.
$\checkmark$ : The index of the list.
C. OUTPUT

None
D. USAGE

CALL RSPEC (IPTR, ISET, J)
CALL RSPECI (IPTR, ISET, J)
E. REMARKS

These subroutines do not release the space occupied by the record removed from the IV array. To do this, the DSTROY subroutine should follow the RSPEC or RSPECl subroutine.
3.4.2 Model Utility Descriptions
The DELTA Model utilities are described in this section. Briefly,
these are the following:
ABDRTT - Abnormal end of run routine.
ACCUM - Accumulate completions of parallel tasks.
ALLDC - Allocate resources to perform tasks.
CANAC - Cancel the aircraft.
DATAFIL - Write out end of run summary.
DRPAC - Drop the aircraft from memory.
ELIST - LCC driver routine.
GETAC - Search for aircraft.
GETASK - Get task information.
GETIME - Get task performance times.
GETQLR - Get tolerance data.
IDECSN - Search files using test under mask.
IDPTR - Search LIFO files for matching mnemonics.
M@DAC - Maintain the aircraft file.
PILØTR - Determine pilot's response time.
TCANAC - LCC call to CANAC.
TSELEC - Select next task to be performed.
UDPQF - Update phase of flight.

## SUBROUTINE NAME: ABØRTT

A. PURPOSE

This routine is responsible for terminating a model run due to any abnormal condition detected by either SALSIM routines or model routines. It will print an error message, and, if possible, call DATAFIL routine.
B. DISCUSSION

ABØRTT is required by the SALSIM utilities. All abort conditions in the model will result in the calling of this routine. After printing its message, AB $\emptyset R T T$ determines if it has been called from DATAFIL routine. If this is not the case, DATAFIL is called and the run terminates in a STøP 7777. Otherwise, the run is terminated without calling DATAFIL again, and so avoids a closed loop situation.
c. INPUTS

Common variables input are the following:
TIME, model clock time at end of run;
IT, LCC number in which error was found;
EVENT, pointer to the event notice being processed;
IERRQR, error number set by SALSIM utilities.
D. OUTPUTS

AB@RTT prints out an error message and, after calling DATAFIL, it uses a numbered stop, STøP 7777.
E. STIMULI

This routine is called by any routine which has diagnostic error tests as opposed to warning-level error messages.
F. SUBROUTINES CALLED

DATAFIL is called to list the dynamic memory files, giving resource utilization data and end of run statistics useful in tracking down the cause of the error.

## A. PURPOSE

This routine increments and compares IACCUM to ILIMIT.

## B. DISCUSSION

ACCUM is used to stimulate the next LCC after the completion of the last LCC of a set of LCCs stimulated in parallel. It makes use of an accumulator block defined by the appropriate driver routine. Each of the LCCs contains a pointer to the accumulator block (IACBLK), which is passed in the calling sequence. The driver sets the limit (ILIMIT) which is the number of parallel LCCs, and the next LCC pointer (NXTSK) into the accumulator block.

When called, ACCUM increments IACCUM by one. It compares IACCUM to ILIMIT and triggers NXTSK when IACCUM is not less than ILIMIT. ACCUM then returns to the calling LCC.
C. INPUTS

1. Catling Sequence: ACCUM(IPTR) where IPTR is the pointer to the appropriate accumulator block
2. COMMON Variables used: IACCUM(IPTR) is the counter, ILIMIT (IPTR) is the limit on the count, NXTSK(IPTR) is the LCC to be triggered.
D. OUTPUT

None
E. STIMULI

1. The subroutine is called by every LCC triggered in parallel where it is necessary to know when the last LCC is completed.
2. ACCUM may trigger NXTSK LCC if the limit is reached.
F. SUBROUTINES CALLED

ACCUM calls CAUSE to trigger NXTSK.

SUBROUTINE NAME: ALLDC

## A. PURPOSE

This utility routine allocates the given task to either the appropriate queue or the appropriate resource. This routine is also responsible for monitoring the back log for the given resource pool and adding additional resource elements when necessary.

## B. DISCUSSION

ALLDC allocates the task pointed to by the event notice and IT. It determines the jurisdiction and resource pool responsible for the task and attempts to acquire a resource element. If none is available, it stores the task in the queue for that resource pool. If the queues are too long or too much delay is expected, additional elements may be added.

Specifically, IRESRC .GT. 0 is the Allocated Task Indicator. IRESRC contains the resource element pointer. IRESRC .EQ. O indicates not from queue, and IRESRC .LT. 0 indicates placed in queue. IACFT .GT. 0 is the pointer to the Aircraft File which includes the jurisdiction pointer. IJURIS. IACFT .LE. 0 indicates the jurisdiction directly; the jurisdiction pointer IJURIS. IACFT .LE. 0 indicates the jurisdiction directly; the jurisdiction pointer is absolute value of IACFT, in this rase. From the jurisdiction, it is possible to determine the appropriate resource pool. JPD日L, returned from GETASK, defines which resource pool of the jurisdiction is to be used, and is pointed to by JRSCPL.

The elements of the pool which are not busy are stored in the IREFIL. If the file is empty, no elements are available, so the task is placed in the ITASKQ, task queue. Otherwise, the element is removed from the IREFIL and the task is allocated to the element.
C. INPUT

1. Common Variables Used: IT, the current task pointer; EVENT, the current event notice pointer; IACFT (EVENT), the current aircraft or jurisdiction pointer;

# IRESRC (EVENT), the current resource pointer; <br> IJURIS, the current aircraft's jurisdiction pointer; <br> JRSCPL, the pointer to the jurisdiction's resource pool. 

2. Subroutine returns: GETASK returns the following:

JPRID, task priority;
JP@DL, characteristic rasource pool;
RFIRST returns pointer to first available resource element, if any.
D. OUTPUTS

Common Variables: IPRI® (EVENT), the task queue priority, is set to JPRID;
IRESRC (EVENT); is set as FROM MUEUE flag;
IRSTAT, resource element status set to 1 to indi-
cate element is busy.
E. STIMULI

ALLØC is called in each routine which utilizes a resource. ALLDC does not trigger any LCCs.
F. SUBROUTINES CALLED

GETASK, called to determine priority and resource pool required for task;

RFIRST removes resource element from file for pool;
FILE places current task into ITASKQ file for pool.

## SUBROUTINE NAME: CANAC

A. PURPOSE

CANAC is intended to remove the aircraft from the system.
B. DISCUSSION

This routine is designed to remove all indication of the aircraft from the system. It will destroy all traces of the aircraft from the system, including the aircraft's Time/Position Queue, Conflict File, Runway Queue, and cancel as many scheduled events as possible. The aircraft file is allowed to remain in dynamic memory for a tenth of an hour after the aircraft leaves the system, to clear up any in-progress tasks. IJURIS is set negative as an indicator that CANAC HAS PROCESSED THE AIRCRAFT.
C. INPUTS

CANAC calling sequence passes the aircraft pointer and an indicator used to determine the reason for the call.

Common variables used are those in the aircraft file, the conflict history file, the time/position queue and the runway and terminal files.
D. OUTPUTS

None.
E. STIMULI

This routine is called as an LCC using routine TCANAC and as subroutine by UDPめF, and $T 04402$.
F. SUBROUTINES CALLED

CANEVT1 is called to cancel special call to MOVAC; RSPEC and RFIRST are used to remove files from queues; DSTRØY is called to remove files from dynamic memory; CAUSE is called to trigger DRPAC.

## SUBROUTINE NAME: DATAFIL

## A. PURPOSE

DATAFIL is intended to write out the dynamic memory files dealing with resource utilization.
B. DISCUSSION

This routine will write out the end of run information generated by the model. This includes information from the Resource Element File, the Resource Pool File, the Aircraft File, the Task Queue, the Jurisdiction File, the Terminal File, the Runway Queue, and the Metering and Sequencing File. The principle concern is with resource utilization. The print out is described elsewhere.
C. INPUTS

DATAFIL uses information from the files indicated above. Additionally, if, the run has teminated normally, it will read in a run title from the exogenous event file.
D. OUTPUTS

DATAFIL writes out the end of run summary.

## E. STIMULI

This routine is called from either ELIST when exogenous event 180 is encountered or $A B \emptyset R T T$.
F. SUBROUTINES CALLED

None.

SUBROUTINE NAME: DRPAC
A. PURPOSE

This routine is responsible for the final removal of an aircraft from the dynamic memory.
B. DISCUSSION

DRPAC performs two duties, it destroys the indicated aircraft file and its own event notice. This routine is an LCC. The aircraft file is permitted to remain available after aircraft cancellation so that tasks in progress may have valid pointers to the aircraft with indications that the aircraft is cancelled to avoid additional processing. A negative IJURIS is this indicator.
c. INPUTS

The pointer to the aircraft file is the only input to this routine.
It is passed via the. IACFT variable of the standard event notice.
D. OUTPUTS

None.
E. STIMULI

DRPAC is triggered by CANAC.
F. SUBROUTINES CALLED

DSTRDY is called to relinquish the aircraft file back to dynamic memory.

## SUBROUTINE NAA:AE: ELIST

A. PURPOSE

ELIST is the central driver for all model logical control chain(LCC) routines. It is responsible for calling all LCCs.
B. DISCUSSION

ELIST and its EL-subroutines are the main driving utilities required by the SALSIM model structure. ELIST decodes the LCC number, identifying which subroutine should be called for a given LCC number. Due to the overlay constraints, several small routines which behave like ELIST but that are only concerned with LCCs for a particular function were used. These are ELO1, ELO4, EL05, ELO5, ELO7, ELO8, ELO9, EL12, ELI5, EL16 and EL17. They are associated with Functions 1., 4., and so on.
c. INPUTS

ELIST receives the LCC number and event notice pointer from SIMRUN, the SALSIM driver, through a calling sequence.
D. OUTPUTS

None.
E. STIMULI

Every LCC uses the ELIST routine as a driver.
F. SUBROUTINES CALLED

ELIST calls all LCCs and the functional drivers listed in B.

SUBROUTINE NAME: GETAC

## A. PURPOSE

This routine determines the pointer to the Aircraft Data File for the aircraft named or identified in ACNAME and returns the pointer to IPTRAC. If the aircraft identification is not found, the pointer is set to zero.

The file of id versus pointer is kept on a high speed storage device, IACPTS, and read if a test reveals that the data has been overlaid.
B. DISCUSSION

The variable ITEST is set in a DATA statement. When GETAC is overlaid and returned to core, the initial value from the DATA statement is present, indicating that IACPTS must be accessed to read the file. ITEST is set different from its initial value after the read and rewind. The file is rewound after each accessing to assure its readiness to be read.

ACNAME is compared to each ACIDS aircraft identification. (The file may seem redundant, and it is. The alternative to this file search is to search each jurisdiction for its associated Aircraft Data Files, which also include the aircraft identifiers. This process is more time consuming than the maintenance of a table of ids versus pointers.) When a match between ACNAME and ACIDS is found, the pointer value IPTRAC is set to the appropriate value of IPTTRS. If no match is found, zero is returned. The DO-LOOP index IAC is retained in COMMON ACPTS. It will contain the index of the match or one more than the number of aircraft, NAC, if no match is found.
c. INPUTS

1. Calling Sequence: GETAC(ACNAME, IPTRAC) where ACNAME contains and aircraft identifier.
2. Common Variables: From COMMON ACPTS,

NAC, number of aircraft active in the system, ACIDS, array containing the aircraft identifiers, IPTRS, array containing the pointers to the Aircraft Data File.

# 3. Internal Variables: ITEST, used to determine whether it is necessary to read IACPTS, set to zero in DATA statement, reset to 1 if IACPTS is read. 

D. OUTPUTS

1. Calling Sequence: GETAC(ACNAME, IPTRAC) where IPTRAC contains the pointer to the Aircraft Data File or zero if none found.
2. Common Variables: IAC, the index of arrays ACIDS and IPTRS.

## E. STIMULI

This routine is called from MODAC and anywhere it is necessary to convert aircraft id to pointer, such as aircraft exogenous events, where only the id of the aircraft is available.

## F. SUBROUTINES CALLED

None

SUBROUTINE NAME: GETASK
A. PURPOSE

GETASK is used to retrieve task information by the model utilities.
B. DISCUSSION

This routine provides a table look up capability within the task data files. It is intended to first check the value of the input task pointer, ITSKPT to determine if there is a valid pointer. If not, IDECSN is called to generate the needed subscript. The task file is searched using a test value composed of the LCC number, the aircraft user class and phase of flight. IDECSN returns with the needed value for ITSKPT. With this, the resource pool indicator, priority value, and task time indicator are retrieved.
C. INPUTS

GETASK inputs the aircraft pointer and phase of flight and user class from common. The task pointers ITASK and ITSKPT are passed through the calling sequence.
D. OUTPUTS

GETASK puts out the following parameters via its calling sequence:
ITIME, the number of instructions, if negative, or the subscript to the appropriate task time distribution. IT.SKPT, the task subscript (may also be an input). JPRI $\emptyset$, the task priority. JPQDL, the resource pool indicator.

## E. STIMULI

GETASK is called by ALLØC, TSELEC, and GETIME.
F. SUBROUTINES CALLED

IDECSN is used to search the task data files for the task pointer.

## SUBROUTINE NAME: GETIME

## A. PURPOSE

This routine is responsible for calculating the time required to perform the indicated task, including input time, set-up time, performance time, and output time. Performance time is taken from a specific distribution.

## B. DISCUSSION

The GETIME function selects a manual task time from the input distribution by determining the half of the distribution randomly and then adding the interquartile distance times a uniformly distributed random number between 0 and 1. An automated task time is generated by dividing number of instructions by computer speed.
C. INPUTS

Calling Sequence: GETIME (ITSKPT) where ITSKPT is a dummy variable.
D. OUTPUTS

Calling Sequence: GETIME (ITSKPT) where GETIME returns the resultant time for one repetition.
E. STIMULI

Every LCC using a resource employs this function to determine the delay time.
F. SUBROUTINES CALLED

GETASK is called to determine instruction count or time distribution.
A. PURPOSE

This routine is responsible for determining the tolerances which are applicable to the given aircraft.
B. DISCUSSION

Tolerances are set to the predetermined values shown below.
C. INPUTS

Calling Sequences: GETØLR (ITSKPT, TØLHØR, TØLVRT) where ITSKPT is a dummy variable.
D. OUTPUTS

Calling Sequence: GETØLR (ITSKPT, TOLH $\emptyset R$, T $\emptyset L V R T$ ) where GETQLR is the time tolerance, set to 5 minutes, $T \emptyset L H \emptyset R$ is the lateral (horizontal) tolerance, set to 10 nautical miles, and TØLVRT is the vertical tolerance set to 1 nautical mile.
E. STIMULI

The function is used in Tasks 7.2.1 and 7.3.3 and 9.5.1. No LCCs are stimulated by this routine.
F. SUBROUTINES CALLED

None.

## SUBROUTINE NAME: IDECSN

A. PURPOSE

IDECSN is used to search the task files to determine task pointer.
B. DISCUSSION

This routine performs a search on the comparison data and the mask word passed from GETASK or PILØTR. The input state word is anded with the mask word and then compared with each word in the comparison array until a match is found. The first match ends this search. The subscript of the matching element is returned. If no match is found, a zero subscript is returned.
C. INPUTS

ISTATE, NSTATE, MASKS and CDMPS are passed by means of the calling sequence.

ISTATE is the word being tested;
NSTATE is the length of the CPMPS array being searched;
MASKS is the mask word, with which ISTATE is anded, to produce a test under mask;

CDMPS is the array peing searched.
D. OUTPUTS

IDECSN, the value returned by the function subprogram IDECSN, is the subscript of the matching element of CøMPS found.

## E. STIMULI

GETASK and PILØTR are the only routines calling IDECSN, though the routine was designed to be general purpose in structure.
F. SUBROUTINES CALLED

Only the AND routine is called, it is designed to return the result of a logical AND operation between the elements of its calling sequence.

## SUBROUTINE NAME: IDPTR

## A. PURPOSE

This routine compares the ID to the file ISET member-id and returns with the pointer to the matching member.
B. DISCUSSION

IDPTR is a function. It is used to scan all members of file ISET, from FIRST, through NEXT, until it has exhausted the file or found a member with id MEMID that matches ID. If a match is found, the function is set to that pointer, otherwise a zero is returned. It is assumed that all files are one index LIFO files and MEMID is the second word of the member. c. INPUTS

1. Calling Sequence: IDPTR(ISET, ID) where ISET is the pointer to the set definition block defined by DEFSET, and ID is the identifier to be searched for.
2. Common Variables: MEMID (MPTR) is the member identifier of the MPTR member.
D. OUTPUTS

The function value returned is either the pointer to the matching member or zero if no match is found.
E. STIMULI

The routine is used in T03000.
F. SUBROUTINES CALLED

FIRST, used to find first member of file, and NEXT, used to find ensuing members.

SUBROUTINE NAME: M@DAC
A. PURPOSE

This utility routine modifies the Aircraft Identification File by adding or deleting entries.
B. DISCUSSION

MGDAC modifies the data manipulated by GETAC. Entry addition is denoted by IMめD greater than zero, IM $\varnothing D$ is equal to the pointer to the Aircraft Data File. Deletion is denoted by IMOD less than or equal to zero.

GETAC is called to determine the existence of a matching aircraft identifier and to insure the presence of the data files in core. (GETAC, COMMON ACPTS and MODAC must be in the same overlay.) If match is found, and the modification was to be a deletion, the indicated entry is deleted from both ACIDS and IPTRS, indexed by IAC, and the arrays are condensed. If no match was found and the modification was to be an addition, the entry is appended onto the end of the arrays. In both of the latter cases, the arrays are written out to IACPTS for maintenance.

In any other case, an error is indicated by setting IERR non-zero. The file is not changed and not written out to IACPTS. Also, if more than 2000 aircraft are loaded, no action is taken.
c. INPUTS
 the aircraft identifier, and IMळD is a switch equal to either the Aircraft Data File pointer to indicate an ADD or is less than or equal to zero to indicate a DELETE.
2. Common Variables: IAC, index of ACIDS and IPTRS, as returned from GETAC,
ACIDS, aircraft id array,
IPTRS, pointers to Aircraft Data File, NAC, number of aircraft.
D. OUTPUTS

1. Calling Sequence: MøDAC(ACNAME, IM $\nsupseteq D$, IERR) where

IERR $=1$ for redundant aircraft id found during an ADD
IERR $=2$ for no match found during a DELETE
IERR $=3$ for overflow (number of aircraft 2000, maximum)
IERR $=0$ for no error.

## E. STIMULI

This routine is called in Function 3, to add an aircraft and in 4.4.2 to cancel an aircraft. INITIA uses M 9 DAC to add the initial load of aircraft.
F. SUBROUTINES CALLED

GETAC is called to seek a matching aircraft id.

## SUBROUTINE NAME: PILøTR

A. PURPOSE

This routine is responsible for generating the time delay required for the pilot to respond to a request for data coming from the indicated task.
B. DISCUSSION

This routine uses a set of response time distributions input to the model. These times should represent nominal response times. The times are generated from the distributions in the same manner used by GETIME for task times.
C. INPUTS

The distributions are passed through common. The task numbers are passed via ITSKPT of the calling sequence.
D. OUTPUTS

PILØTR returns the time for the pilot's response as a delta time.
E. STIMULI

PILØTR is called by those routines which have requests made of the pilot for which a response is needed before further processing can occur.
F. SUBROUTINES CALLED

IDECSN is called to determine the task pointer.

```
Page 3.4-34
```


## SUBROUTINE NAME: TCANAC

A. PURPOSE

This routine cancels an airciraft from the system after it lands or flies out of the system.
B. DISCUSSION

TCANAC is an LCC and thus is executed at the precise moment an aircraft lands or leaves the system. It is triggered by a call to the SALSIM subroutine CAUSE.
C. INPUTS

1. Pointer to aircraft file ACFIL.
2. Simulation time that aircraft leaves system.
D. OUTPUT

None.
E. STIMULI

The routine is triggered by numerous subroutines within the algorithms MOVAC, METSEØ, and CONDET.
F. SUBROUTINES CALLED

DRPAC (drop aircraft).
CANAC which performs the actual cancellation.

## SUBROUTINE NAME: TSELEC

## A. PUIRPOSE

This utility LCC is responsible for concluding the utilization of a resource element by one task and settina the element busy on either the next task in a chain or the highest priority task in the queue for that resource pool or setting the element not busy.

## B. DISCUSSION

TSELEC is the only routine able to destroy an event notice of resource-using LCCs. This is done when NXTSK (EVENT) is zero, indicating no next task in a chain. If there is a next task which is not performed by the indicated resource type, the task is triggered with no preallocation of resource. If the current resource may perform the next task, the priorities of the next task and the highest priority task in the resources task queue are compared. If the next task is of comparable. or higher task, the next task is triggered with a preallocated resource. If the highest priority task has the higher priority, it is removed from the task queve and triggered with a pre-allocated resource, also triggering the next task with no pre-allocated resource.

TSELEC checks for short term overloading of manual resources, and assigns alternate resource elements if available. TSELEC returns nonbusy elements to the resource pools. As can be seen from the above, TSELEC and ALLDC are complementary routines.
C. INPUT

1. Common Variables Used: IRESRC (EVENT), resource element; NXTSK (EVENT), pointer to next task, if any;
ITASKQ data, including IPRID, the highest priority task in
the task queue.
IREFIL data, including IPØOL and ISTCBT data;
2. Subroutine returns: GETASK returns the following parametersJPRID, the task priority for the NXTSK
JPQOL, the characteristic resource poolfor NXTSK
ITSKPT, the subscript of the Task File for NXTSK
D. OUTPUTS
Common Variables: IRESRC (EVENT) and
IRESRC (KPTR) the allocation flags
E. STIMULI
TSELEC is triggered in each routine which utilizes a resource.
This routine, in turn, may trigger either or both the NXTSK and/or thehighest priority task in the Task Queue.
F. SUBRØUTINES CALLED
FIRST, called to determine the ihighest priority task;
DSTRDY, called to destroy the event notice;
GETASK, called to determine data on NXTSK;
CAUSE, used to trigger LCCs;
RFIRST, used to remove resource element from IREFIL or highestpriority task from ITASKQ;
FILE, used to return resource element to IREFIL.

SUBROUTINE NAME: UDPOF
A. PURPOSE

Subroutine UDPOF updates the phase of flight for a single aircraft and performs tasks associated with change in status for the aircraft.
B. DISCUSSION

All input to UDPØF is entered into the Event Notice for UDPØF.
C. INPUTS
(Subroutine MØVAC supplies only the parameter IACPDF. The other triggering routines supply IACPDF as well as most of the other parameters.)

IACPDF: Pointer to aircraft file whose aircraft's phase of flight is to be updated.

TESCAP: Time between approach and missed approach, if any.
IRWPTR: Pointer to IRWQUE member.
ITAKEØF: Time between take-off and departure.
TARRTR: Time between arrival and approach, if any.
TMSDAP: Time between missed approach and approach, if any.
IDEPTR: Time between departure and enroute time.
TAPRCH: Time between approach and landing.
TLNDING: Time between landing and the cancelling of the aircraft from the system.
D. OUTPUTS

None.
E. STIMULI

UDPDF is stimulated by subroutine MQVAC, METSEQ, or $T 03000$.
F. SUBROUTINES CALLED

I06401, RSPEC, DSTRØY, SBYT, M@VAC, METSEQ, CANCEL, 107201, I05103, I05102, UDPDF, I06401, I06201, I07102 and I07301.

### 3.5 Algorithms

The algorithms are concerned with guiding an aircraft from preflight or from the time the aircraft enters the system until it either lands or leaves the system. This section gives a synopsis of the tasks performed by each of these algorithms and the highest subroutine that performs the tasks, as indicated in the flowcharts in section 2.2, Subroutines and Link Structure. A detailed explanation of the operation and logic of these alqorithms is presented in section 2 of the User's Guide.

Subroutine METSEQ (metering and sequencing) maintains aircraft which are taking off and landing. It primarily flies aircraft in the terminal area and schedules their maneuvers on the runways.

Subroutine MOVAC maintains the aircraft outside terminal areas. It is responsible for moving aircraft along their fliaht paths (time-position queues) and determining when an aircraft must maintain a holding pattern. The aircraft usually do not fly along their exact flight paths because random errors due to motion and chanaes in speed are generated for each aircraft.

A subroutine of MOVAC, BNDRY, is responsible for maintaining the current jurisdiction for each aircraft. It also records information about any aircraft that leaves the system.

Subroutine CRASH, which is called by MOVAC, performs the actual movement of aircraft outside the terminal area. In addition, it projects for conflict detection (CONDET), the region in which an aircraft probably can be found for a given time interval:

The detection of a conflict in actual flight paths for any pair of aircraft is performed in the two subroutines, CONDET and HAZARD. Subroutine CONDET performs preliminary analysis in order to eliminate easily pairs of aircraft which definitely have no conflict. Subroutine HAZARD performs analysis in depth for pairs of aircraft not already eliminated by CONDET.

If HAZARD finds a conflict between a pair of aircraft, subroutine RESOLV determines what maneuvers are necessary to resolve the conflict safely. Subroutine RSCRSE then maneuvers the two aircraft to resume their intended courses.

### 3.6 Functional Analysis Tasks

On the following pages are flowcharts which show the calling sequences of the LCC's for each function.

Each LCC is a subroutine which is initially triggered (executed) at a simulation time determined by user input data or, more frequently, by a simulated event. Each LCC can in turn trigger one or more LCC's including itself, or can be the last in a sequence of LCC's. The flowcharts for each function display the LCC's that triggered that function, the logical flow within the function, and the action taken when the function completes its chain of LCC's.

Each LCC is tested by a numerical code. LCC number ff.s.tt means function number ff, subfunction number $s$, and task number $t t$. The subroutine performing the LCC has name Tffstt.

A complete description of the tasks performed by each of these routines is given in "Function Analysis of Air Traffic Management, Final Report, Volume II." It should be noted that many of the tasks described in this reference have been grouped and written as a single FORTRAN subroutine. The flowcharts indicate only the group name.

Below are listed the group names with the tasks they encompass:

Subroutine Name of
Grouped Tasks

Group Name
In Flowcharts
2.1 .1
2.1.2
2.1 .3
2.1 .4
2.1 .5
2.1 .6
2.2 .1
2.2.3
2.2 .4
2.3 .1
2.3.2

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|  |  | 2.3.3 |
| :---: | :---: | :---: |
|  |  | 2.3.4 |
|  |  | 2.3 .5 |
| T03000 | 3.0 .0 | 3.1 .1 |
|  |  | 3.1 .2 |
|  |  | 3.1 .3 |
|  |  | 3.2 .1 |
|  | , : . | 3.2 .2 |
|  |  | 3.2 .3 |
|  |  | 3.3 .1 |
|  |  | 3.3 .2 |
|  |  | 3.3 .3 |
| T06TAU (automatic) | 6.1.AU and | 6.1 .1 |
| T061MN (manual operations) | 6.1.MN | 6.1 .2 |
|  |  | 6.1 .3 |
|  |  | 6.1 .4 |
|  |  | 6.1 .5 |
|  |  | 6.3 .1 |
|  |  | 6.3 .2 |
| T08105 | 8.1 .5 | 8.1 .5 |
|  |  | 8.1 .6 |
| T09100 | 9.1 .0 | 9.1 .1 |
|  |  | 9.1 .2 |
|  |  | 9.1 .3 |
| T09300 | 9.3 .0 | 9.3 .1 |
|  |  | 9.3 .2 |
| T09400 | 9.4 .0 | 9.4 .1 |
|  |  | 9.4 .2 |


| T09501 | 9.5.1 | 9.5 .1 |
| :---: | :---: | :---: |
|  |  | 9.5.2 |
|  |  | 9.5.3 |
|  |  | 9.5.4 |
| T09506 | 9.5 .6 | 9.5 .6 |
|  |  | 9.5.7 |
| T12202 | 12.2 .2 | 12.2.2 |
|  |  | 12.2 .3 |
| T13100 | 13.1 .00 | 13.1.1 |
|  |  | 13.1 .3 |
| 717100 | 17.1 .0 | 17.1.1 |
|  |  | 17.1 .2 |
|  |  | 17.1 .3 |
|  |  | 17.1 .4 |
|  |  | 17.1 .5 |
|  |  | 17.1 .6 |
|  |  | 17.1 .7 |
|  |  | 17.1 .8 |
| T17200 | 17.2.0 | 17.11 .1 |
|  |  | 17.11.2 |
| T17300 | 17.3.0 | 17.2.1 |
|  |  | 17.2 .2 |
|  |  | 17.2 .3 |
|  |  | 17.2 .4 |
|  |  | 17.2 .5 |
|  |  | 17.2 .6 |
|  |  | 17.7 .1 |
|  |  | 17.7 .2 |
|  |  | 17.7 .3 |
|  |  | 17.7 .4 |

17.7.5
17.8 .1
17.8.2
17.8 .3
17.8 .4
17.8 .5
17.9 .1
17.9 .2
17.9 .3
17.9 .4
17.9 .5
17.9 .6
17.10 .1
17.10 .2
17.10 .3
17.11 .1
17.11 .2

User input data that triggers an LCC is called an exogenous event. One example is the Preparation of Flight Plan. For each aircraft in the system, the user specifies data such as aircraft characteristics, flight options, time information and aircraft location. During model execution, subroutine $T 03000$ is executed when the aircraft enters the system. This routine sets up all queues, switches, and other information that signifies this aircraft has entered a phase of flight.

The list below gives each exogenous event and the LCC it triggers. The input formats for these events can be found elsewhere.

EXOGENOUS EVENT
Prepare flight plan $T 03000$
Accept data link request $T 01101$
Accept telephone request T01102
Capability change; Status 106400
change; emergency
Acquire and analyze data
T15102

## Page 3.6-5

LCC's are triggered most often in the model by algorithms and utilities, which do so in response to events simulated. For example, UDPDF, which updates phase of flight for a single aircraft, triggers subroutines T05102, T05103, T06201, T06401, T07102, T07201, and T07301. A complete description of the utility routines is given in section 3.4 UTILITY ROUTINES, and the algorithms in section 3.5 ALGORITHMS.


FIGURE 3.6-1 LOGICAL FLOW OF FUNCTION 1.0

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\text { Pane } 3.5-7
$$



FIGURE 3.6-2 LOGICAL FLOW OF FUNCTION 2.0

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Figure 3.6-3 Logical Flow of Function 3.0

Page 3.6-9


Page 3.6-10
(200)


FIGURE 3.6-6 LOGICAL FLOW - FUNCTION 6.0


Figure 3.6-7 Logical Flow of Function 7.0


FIGURE 3.6-8 LOGICAL FLOW - FUNCTION 8.0

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ALL AIRCRAFT


FIGURE 3.6-9 LOGICAL FLOW OF FUNCTION 9.0

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Figure 3.6-10 Logical Flow of Function, 11


Figure 3.6-11 Logical Flow of Function 12

Page 3.6-17


FIGURE 3.6-12 LOGICAL FLOW OF FUNCTION 13.0


Figure 3.6-13LOGICAL FLOW OF FUNCTION 15.0


Fiqure 3.6-14 Loaical Flow of Function 16.0


Figure 3.6-15 Logical Flow of Function 17

### 4.0 DYNAMIC MEMORY FILES

The dynamic memory files are sets of data, each havina a variable number of fixed length records. A detailed explanation of the structure and manipulation of these files is given in Section 3.4.2, SALSIM.

Some of the files contain lists of items with their properties. For example, file IACFIL has one record for each aircraft in the sustem. Each record includes the aircraft type and location. The remainino files consist of queues of events which are processed in a specified order and then deleted from the list. For example, events are both stored in and deleted from the Standard Event Notice file in the order they are to be processed.

Many of the lists are linked to form essentially a list of lists. The relation of these data files is shown in figure $4.0-1$, MODEL DATA STRUCTURES. Following this fiqure are tables showina the contents of each file.

Below is a list of all the dynamic memory files and a synopsis of their contents.

Name
$\qquad$

IADJC

IADJS

IACFIL

IACTYP

ICONFL

## Contents

Accumulator block, which contains a list of events to be processed by subroutine ACCUM, as well as a count of parallel tasks.
List of jurisdictions adjacent to the floor of the owner jurisdiction.

List of jurisdictions contiquous to the side of the owning jurisdiction vertex.

Aircraft file which contains one record for each aircraft in the system.

File of aircraft characteristics. There is one record for each aircraft type.
List of aircraft which required resolution of a conflict in their fliaht paths. Conflict was recoanized by subroutine CONDET.

|  | Event notice for subroutine METSEO, which contains the standard event notice for the periodic stimulation of METSEO, as well as a list of aircraft incurring a missed approach. |
| :---: | :---: |
|  | Event notice for UDPOF which contains lists of time intervals for aircraft being in a given phase of flight. |
| HEFIL | List of aircraft which required resolution of a conflict in flight paths. Conflict was confirmed by subroutine HAZARD. |
| IJURFL | List of jurisdictions. |
| IVERTX | List of floor vertices for the owner jurisdiction. |
| IMSQUÉ | List of aircraft to be processed by subroutine METSEQ. These events are created by subroutines MOVAC and T03000. |
| - | MOVAC Special Call 4 Event Notice which is a list of aircraft scheduled to make turn. |
| IREFIL | Resource element file, which holds the tallies for resource utilization. |
| IRPFIL | Resource pool file which defines the groups of resource elements. |
| TRWQUE | Runway queue which contains, for each runway, a list of aircraft scheduled to land on the runway. |
| - | Standard event notice, which is a list of LCC's to be triggered at a specified time. |
| ITASKQ | List of events (from the standard event notice above) which could not be processed when triggered. |
| ITPQUE | Time-position queue, which contains for each aircraft the set of fixed: points an aircraft must follow from take-off to landing. |



FIGURE 4.0-1 MODEL DATA STRUCTURES

FILE STRUCTURE

DESCRIPTION:
FILE NAME:
FILE
OWNER:
 ORDERING SCHEME: H/A LENGTH NAME: LEVNTL This Block is Used by ACCUM. ATTRIBUTES

| NAME | $\begin{array}{\|c\|} \hline \text { NORD } \\ \text { NO. } \end{array}$ | $\begin{array}{\|c\|} \hline \text { DATA } \\ \text { TYPE } \end{array}$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
| IACCUM | 1 | I | Accumulator |  |
| ILIMIT | 2 | I | Limit |  |
|  | 3 | - | Not Used |  |
| NXTSK | 4 | I | Task to be Triggered When IACCUM.GE. ILIMIT |  |
| IHøLD | 5 | - | Utility Word |  |
| IACFT | 6 | I | Alrcraft or Jurisdiction Pointer |  |
| IRESRC | 7 | - | Not Used |  |
| IACBLK | 8 | - | Utility Word |  |
|  |  |  |  |  |
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PAGE: $ـ^{0 F} \quad 1$ DESCRIPTION: Adjacent Ceiling Jurisdiction File FILE NAME: IADJC ORDERING SCHEME: LIFO OWNER: _._Jurisdiction File ATTRIBUTES

| NAME | $\begin{array}{\|c\|c\|} \hline \text { WORD } \\ \text { NO. } \end{array}$ | $\begin{array}{l\|l\|} \text { DATA } \\ \text { TYPA } \end{array}$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
| IAC | 1 | I | Successor |  |
| JACJC | 2 | I | Pointer to Neighboring Jurisdiction (If Negative, |  |
|  |  |  | No Handoff is Required) |  |
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Page 4.0-6
FILE STRUCTURE


| NAME | $\begin{array}{\|c\|} \text { NORD } \\ \text { NO. } \end{array}$ | $\left\|\begin{array}{l} \text { DATA } \\ \text { TYPE } \end{array}\right\|$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
| IAF | 1 | I | Successor |  |
| JADJF | 2 | I | Pointer to Neighboring Jurisdiction (If Negative, |  |
|  |  |  | No Handoff is Required) |  |
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FILE STRUCTURE
 1 ATTRIBUTES

| NAME | WORD NO. | DATA | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
| IAS | 1 | I | Successor |  |
| JADJS | 2 | I | Pointer to Neighboring Jurisdiction (If Negative, |  |
|  |  |  | No Handoff is Required) |  |
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FILE STRUCTURE
PAGE: $\qquad$ $0 F$ 2
DESCRIPTION: Aircraft File
 ATTRIBUTES

| NAME | $\begin{gathered} \text { NORD } \\ \text { NO. } \end{gathered}$ | $\left\|\begin{array}{l} \text { DATA } \\ \text { TYPE } \end{array}\right\|$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
|  | 1 | I | Successor |  |
|  | 2 | I | Predecessor |  |
| ACID | 3 | A | Identification |  |
| ICLASS | 4 | I | Avionics User Class |  |
| ITYPE | 5 | I | Aircraft Type (Pointer to Aircraft Characteristics File |  |
| IPRTY | 6 | I | Priority of Flight Plan |  |
| IPHASE | 7 | I | Current Phase of Flight |  |
| ACBITS | 8 | L | State Vector (CDL) |  |
| ENDUR | 9 | R | Endurance | Hrs. |
| $\begin{aligned} & \text { IORGAP } \\ & \text { IJURIS } \\ & \hline \end{aligned}$ | 10 | $\begin{aligned} & \mathrm{I} \\ & \mathrm{I} \\ & \hline \end{aligned}$ | Pointer to Origin Pointer to Current Jurisdiction |  |
| $\begin{aligned} & \text { ACETD } \\ & \text { ETL. } \\ & \hline \end{aligned}$ | 11 | $\begin{aligned} & \mathrm{R} \\ & \mathrm{R} \\ & \hline \end{aligned}$ | Estimate Time of Departure Estimated Time Left in Jurisdiction | Hrs. Hrs. |
| NJURIS | 12 | I | Pointer to Next Jurisdiction |  |
| ACETA | 13 | R | Estimated Time of Arrival at Destination | Time of Day |
| IDENT | 14 | I | Pointer to Destination |  |
| IALTD | 15 | $\begin{array}{\|l\|l} \mathrm{I} \\ \mathrm{I} \end{array}$ | Pointer to Alternate Destination Pointer to Owner of Runway Que during Aprch or Dep |  |
| IFSTPQ | 16 | I | Pointer to First Member of Time/Position Queue |  |
| IFFIX | 17 | I | Pointer to Last Member of Time/Position Queue |  |

## FILE STRUCTURE



ATTRIBUTES

| NAME | $\begin{gathered} \text { WORD } \\ \text { NO. } \end{gathered}$ | $\left\|\begin{array}{l} \text { DATA } \\ \text { TYPE } \end{array}\right\|$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
| TUPDAT | 18 | R | Time of Last Update | $\begin{array}{\|c} \text { Time of } \\ \text { Day } \end{array}$ |
| IDPRW | 19 | I | Pointer to First Member of Conflict History File Pointer to Departure Runway for Departing Aircraft |  |
| HQLDTM | 20 | R | Hold Time for Metering and Sequencing Holds | Hrs. |
| X | 21 | $R$ | X-coordinate of Aircraft Position | N.Mi. |
| $Y$ | 22 | R | Y-coordinate of Aircraft Position | N.Mi |
| Z | 23 | R | Z-coordinate of Aircraft Position | N.Mi |
| XVEL | 24 | R | X-component of Aircraft Velocity | Kts. |
| YVEL | 25 | R | Y-component of Aircraft Velocity | Kts. |
| RVEL | 26 | R | Z-component of Aircraft Velocity. | Kts. |
| N07201 | 27 | I | Pointer to Event Notice for 7.2.1 LCC |  |
| N07301 | 28 | I | Pointer to Event Notice for 7.3.1 LCC |  |
| $\begin{array}{\|l\|} \hline \text { IPTEVT } \\ \text { XPTEVT } \\ \hline \end{array}$ | 29 | $\begin{aligned} & \mathrm{I} \\ & \mathrm{R} \\ & \hline \end{aligned}$ | 3 Pointers to MøVAC Special Calls Packed Into One Word |  |
| ERR@R | 30 | R | 3 Coded Navigation Error Terms Packed Into One Word |  |
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Page 4.0-10
FILE STRUCTURE
PAGE: $\qquad$ OF 1


| NAME | $\begin{array}{\|c\|} \hline \text { WORD } \\ \text { NO. } \end{array}$ | $\left\|\begin{array}{l} \text { DATA } \\ \text { TYPE } \end{array}\right\|$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
|  | 1 | I | Successor |  |
| MEMID | 2 | A | Aircraft Type Identifier |  |
| JSPD | 3 | I | Speed Class (Velocity/100) |  |
| Thett | 4 | R | Turn Rate | Rad/Hr. |
| RMSQA | 5 | R | Desired Aircraft Horizontal Miss Distance Squared | $(N M)^{2}$ |
| RALTA | 6 | R | Desired Aircraft Vertical Miss Distance | NM |
| IALT | 7 | I | 0-No Altitude Information Available <br> 1 - Altitude Information Available |  |
| ALTL | 8 | R | Minimum Altitude | NM |
| ALTH | 9 | R | Maximum Altitude | NM |
| CRATE | 10 | R | Climb or Dive Rate | NM/Hr. |
| TLEAD | 11 | R | Minimum Lead Time for Metering and Sequencing | Hrs. |
| FSF | 12 | R | Flight Endurance Margin | Hrs. |
| ACRDT | 13 | R | Runway Occupancy Time | Hrs. |
| THETH | 14 | R | Turn Rate in Hold Pattern | Rad/Hr |
| DTRTM | 15 | R | Departure Transition Time Interval | Hrs. |
| ITYPAC | 16 | I | Aircraft Type Number |  |
|  |  |  |  |  |

Page 4.0-11
FILE STRUCTURE


| NAME | $\begin{array}{\|l} \text { WORD } \\ \text { NO. } \end{array}$ | DATA TYPE | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
|  | 1 | I | Successor |  |
| ID2 | 2 | I | Pointer to Second Aircraft in Conflict Pair |  |
| CNTR | 3 | I | Indicator for Action History |  |
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PAGE: 1 0F 1
DESCRIPTION: $\begin{aligned} & \text { Event Notice For METSEQ } \\ & \text { FILE NAME: } \frac{N / A}{N / A} \\ & \text { OWNER: }\end{aligned}$ ( ORDERING SCHEME: RL on Time

ATTRIBUTES

| NAME | $\begin{array}{\|c\|} \hline \text { WORD } \\ \text { NO. } \end{array}$ | $\begin{array}{\|l\|} \hline \text { DATA } \\ \text { TYPE } \end{array}$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
|  | 1 | I | Successor |  |
|  | 2 | I | Predecessor |  |
|  | 3 | R | Time | Hrs. |
| TESCAP | 3 | R | Time Between IAPRCH and MSDAPR if Any | $\triangle$ Hrs. |
|  | 4 | I | Standard Call Indicator (.EQ. 1) |  |
| IACPØF | 4 | I | Pointer to Aircraft if Special Call (.NE. 1) |  |
|  | 5 | I | Not Used |  |
| TMSKAP | 6 | R | Time Between MSDAPR and IAPRCH | $\triangle$ Hrs. |
| TAPRCH | 7 | R. | Time Between IAPRCH and LANDING | $\triangle$ Hrs. |
| TLNDNG | 8 | R | Time Between LANDING and CANAC | $\triangle$ Hrs. |
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* For Special Calls Due to MSDAPR

Page 4.0-13
FILE STRUCTURE
PAGE: 1 OF 1
DESCRIPTION: Event Notice for UDPQF


ATTRIBUTES

| NAME | WORD No. | $\begin{aligned} & \text { DATA } \\ & \text { TYPA } \end{aligned}$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
|  | 1 | I | Successor. |  |
|  | 2 | I | Predecessor |  |
|  | 3 | R | Time | Hrs. |
| TESCAP | 3 | R | Time Between IAPRCH And MSDAPR if Any | $\Delta \mathrm{Hrs}$. |
| IACPDF | 4 | I | Pointer to Aircraft (.NE.1) |  |
| IRWPTR | 5 | I | Pointer to IRWQUE Member |  |
| ITAKøF | 6 | R | Time Between ITAKøF And IDEPTR | $\Delta \mathrm{Hrs}$. |
| TARRTR | 6 | R | Time Between IARRTR And IAPRCH If Any | $\Delta \mathrm{Ars}$. |
| TMSDAP | 6 | R | Time Between MSDAPR And IAPRCH If Any | $\Delta \mathrm{Hrs}$. |
| IDEPTR | 7. | R | Time Between IDEPTR And InRDUT | $\Delta \mathrm{H}$ rs. |
| TAPRCH | 7 | R | Time Between IAPRCH And LANDING | $\Delta \mathrm{Hrs}$. |
| TENRTE | 8 | R | Time Between INRQUT And Anything Else (Not Used) | $\Delta \mathrm{Hrs}$. |
| TLNDNG | 8 | R | Time Between LANDINg And CANAC | $\Delta H r s$. |
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Page 4.0-14
FILE STRUCTURE

DESCRIPTION: Hazard Evaluation Data
FILE NAME: $\overline{\text { HEFIL }}$ ORDERING SCHEME: $\frac{N / A}{\text { LEVNTL }}$
OWNER:
ATTRIBUTES

| NAME | $\left.\begin{array}{\|c\|} \hline \text { WORD } \\ \text { NO. } \end{array} \right\rvert\,$ | $\begin{array}{\|c\|} \left\|\begin{array}{l} \text { DATAA } \\ \text { TYPE } \end{array}\right\| \end{array}$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
| IDCDL1 | 1 | I | Pointer to First Aircraft of Conflict Pair |  |
| IDCON2 | 2 | I | Pointer to Second Aircraft of Conflict Pair |  |
| HEDELT | 3 | R | Utility Word* |  |
| HEIMM | 4 | R | Utility Word* |  |
| HERISK | 5 | R | Utility Word* |  |
| INDXHE | 6 | I | Utility Word* |  |
| HEPACK | 7 | I | Utility Word* |  |
|  | 8 |  | Not Used |  |
|  |  |  |  |  |
|  |  |  | * See Table 4.0-1 Cross Reference of the |  |
|  |  |  | Conflict Pair Information Block |  |
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Page 4.0-15

|  | $\begin{aligned} & \text { IDCON } \\ & \text { (IPTR) } \end{aligned}$ | $\begin{aligned} & \text { IDCON2 } \\ & \text { (IPTR) } \end{aligned}$ | $\begin{aligned} & \text { HEDELT } \\ & \text { (IPTR) } \end{aligned}$ | $\begin{aligned} & \text { HEIMM } \\ & \text { (IPTR) } \end{aligned}$ | $\begin{aligned} & \text { HERISK } \\ & \text { (IPTR) } \end{aligned}$ | $\begin{aligned} & \text { IWDXHE } \\ & \text { (IPTR) } \end{aligned}$ | $\begin{aligned} & \text { HEPACK } \\ & \text { (IPTR) } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { METERING } \\ & \text { AND } \\ & \text { SEQUENCING } \end{aligned}$ | Pointer to Aircraft (lower number pointer) | Pointer to Aircraft (higher number pointer) | Length of time which this pair is to be checked by 8.1.5 | Imminence | Risk | . |  |
| KINEMATICS | Pointer to Aircraft (lower number pointer) | Pointer to Aircraft (higher number pointer) | Length of time which this pair is to be checked by 8.1 .5 | Imminence | Risk |  |  |
| $\begin{aligned} & \text { HAZARD } \\ & \text { EVALUATION } \\ & \text { (HAZEV) } \end{aligned}$ | Pointer to Aircraft (lower number pointer) | Pointer to Aircraft (higher number pointer) | Time until HAVEV next checks this aircraft pair | Imminence | Risk | Index for this aircraft pair for RESDLV | Packed <br> informa- <br> tion <br> variable <br> for RESØLV |
| T08105 |  |  |  |  |  |  |  |
| T08107 |  |  |  | X | $x$ |  |  |
| T08108 |  |  |  |  |  |  | - |
| T08109 |  |  |  |  |  |  |  |
| $\begin{aligned} & \text { T08200 } \\ & \text { (before } \\ & \text { RESOLV } \\ & \text { call) } \end{aligned}$ | $\checkmark$ |  | A coefficient for lag time determination | B coefficient for lag time determination |  |  |  |
| RESDLV | $x$ | $x$ | X | X | $x$ | $x$ | X <br> Hypothesize <br> /Analyze <br> \# of loops |
| $\begin{aligned} & \text { T08200 } \\ & \text { (after } \\ & \text { RESDLV } \\ & \text { call }) \end{aligned}$ |  |  | $x$ <br> Number of loops through this subfunction | $X$ <br> Additional <br> pilot noti- <br> fication <br> loop (0 or <br> 1) (ADDPRL) | Total pilot delay between <br> 8.2.4 and 8.2 .5 |  |  |
| T08201 |  |  |  |  |  |  | X |
| T08202 |  |  |  |  |  |  | X |
| T08203 |  |  | $x$ |  |  |  |  |
| T08204 |  |  | $x$ | X | $x$ |  |  |
| T08205 |  |  |  |  |  |  |  |

NOTE: $X$ - Last previsouly defined variable used in the indicated subroutine. Writing indicates the value that variable is set to in the subroutine.

Page 4.0-16

## FILE STRUCTURE



| NAME | $\begin{array}{\|c} \text { NORD } \\ \text { NO. } \end{array}$ | $\left\|\begin{array}{l} \text { DATA } \\ \text { TYPE } \end{array}\right\|$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
|  | 1 | I | Successor |  |
| MEMID | 2 | A | Jurisdiction Identifier |  |
|  | 3 |  | Not Used |  |
|  | 4 | I | Pointer to First Aircraft Owned by Jurisdiction |  |
|  | 5 | I | Pointer to Last Aircraft Owned by Jurisdiction |  |
| NACFT | 6 | I | Number of Aircraft Owned by Jurisdiction |  |
| ICAP | 7 | I | Capacity of Jurisdiction if .GT.O <br> Pointer to Terminal File if .LT. 0 |  |
| IPTVRT | 8 | I | Pointer to Jurisdiction Vertices File |  |
| IPTJAC | 9 | I | Pointer to Adjacent Floor Jurisdictions File |  |
| IPTJAF | 10 | I | Pointer to Adjacent Ceiling Jurisdictions File |  |
| CEIL | 11 | R | Jurisdiction Ceiling Altitude | N.MI |
| FLøDR | 12 | R | Jurisdiction Floor Altitude | N.MI |
| $\begin{array}{\|c} \hline \text { JRSCPL } \\ +1 \end{array}$ | 13 | I | Pointer to Resource Pool File for Pool 1 |  |
|  | 14 | I | Pointer to Resource Pool File for Pool 2 |  |
|  | : |  |  |  |
|  | $12+n$ | I | Pointer to Resource Pool File for Pool n |  |
|  |  |  |  |  |

Page 4.0-17
FILE STRUCTURE
PAGE: 1 OF 1
DESCRIPTION: Jurisdiction Vertices File FILE NAME: OWNER:

IVERTX
$\qquad$ ORDERING SCHEME: LIFO (Clockwise) lengTh name: $\qquad$
$\qquad$ ATTRIBUTES

| NAME | WORD | DATA |  | DESCRIPTION | UNITS |
| :--- | :---: | :---: | :--- | :--- | :--- |
| IVX | 1 | I | Successor |  |  |
| IDS | 2 | I | Pointer to IADJS File |  |  |
| XVERT | 3 | R | X-coordinate of Vertex | N.MI |  |
| YVERT | 4 | $R$ | Y-coordinate of Vertex | N.MI |  |
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Page 4.0-18
FILE STRUCTURE

DESCRIPTION:
Metering and Sequencing Queue
FILE NAME: IMSQUE
OWNER:
Terminal File
ORDERING SCHEME: RL on RANKS LENGTH NAME: $\qquad$
ATTRIBUTES

| NAME | ORD | DATA |  | DESCRIPTION | UNITS |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | TYPE |  | I | Successor |  |
|  | 2 | I | Predecessor |  |  |
| RANKS | 3 | R | Ranking Variable (Speed Class and ETA or ETD) |  |  |
| IMSAC | R | I | Pointer to Aircraft File |  |  |
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FILE STRUCTURE
PAGE: 1 OF 1 DESCRIPTION: MQVAC Special Call 4 Eyent Notice FILE NAME: N/A

ORDERING SCHEME: N/A OWNER: $\qquad$ LENGTH NAME: $\qquad$ ATTRIBUTES

| NAME | $\begin{array}{\|c\|} \hline \text { WORD } \\ \text { NO. } \\ \hline \end{array}$ | $\begin{array}{\|l\|} \hline \text { DATA } \\ \text { TYPE } \\ \hline \end{array}$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
|  | 1 | I | Successor |  |
|  | 2 | I | Predecessor |  |
|  | 3 | I | Time |  |
| XT0 | 4 | R | Proposed X-coordinant | N.MI |
| IH@LD | 5 | I | Special Call Indicator (.EQ. 4) |  |
| IACID | 6 | I | Pointer to Aircraft File |  |
| $Y T D$ | 7 | R | Proposed Y-coordinant | N.MI |
| ZTD | 8 | R | Proposed Z-coordinant | N.MI |
|  |  |  |  |  |
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## FILE STRUCTURE

PAGE : $\qquad$ OF
DESCRIPTION:
FILE NAME:
Resource Element File OWNER: $\qquad$
Resource Pool File $\qquad$ ORDERING SCHEME: RL on TNA LENGTH NAME: $\qquad$
ATTRIBUTES

| NAME | WORD | $\begin{array}{\|l\|} \hline \text { DATA } \\ \text { TYPB } \end{array}$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
| STCBT | 1 | I | Successor If Not Busy <br> Short Term Cumulative Busy Time If Busy | Hrs. |
| IRSTAT | 2 | I | Predecessor If Not Busy Resource Status or ITSKPT If .LT. 0 |  |
| TNA | 3 | R | Time Next Available ( $T N A=T F A+\frac{C B T}{\underline{\square L T}}$ ) | Hrs. |
| TFA | 4 | R | Time First Available | Hrs. |
| CBT | 5 | R | Cumulative Busy Time | Hrs. |
| IPQOL | 6 | I | Pointer to Resource Pool |  |
|  | 7 | I | Successor of Resource Element |  |
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FILE STRUCTURE

DESCRIPTION: Resource Pool File

$$
\text { PAGE: } 1 \text { or } 1
$$ FILE NAME: IRPFIL OWNER: Pointed to by Jurisdiction File ORDERING SCHEME: N/A LENGTH NAME: $\qquad$ ATTRIBUTES

| NAME | $\left\lvert\, \begin{gathered} \text { WORD } \\ \text { NO. } \end{gathered}\right.$ | $\left\lvert\, \begin{array}{\|l\|} \text { DATA } \\ \text { TYPE } \end{array}\right.$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
| IJORPL | 1 | I | Pointer to Jurisdiction File. |  |
| N®ELMT | 2 | I | $\text { Current }\left\{\begin{array}{l} \text { Computer Rate for Automated Resource } \\ \text { Number of Elements for Manual } 1 \text { Resource } \end{array}\right.$ | $\begin{array}{\|l\|} 10^{2} \text { Inst } \\ \text { El ement } \end{array}$ |
| MEXLMT | 3 | I | $\text { Maximum }\left\{\begin{array}{l} \text { Computer Rate } \\ \text { Number of Elements } \end{array}\right.$ | $\begin{aligned} & 10^{2} \text { Inst } \\ & \text { Element } \end{aligned}$ |
|  | 4 | I | Pointer to First Task in Queue |  |
|  | 5 | I | Pointer to Last Task in Queue |  |
| IFSTRE | 6 | I | Pointer to First Available Resource Element in Pool |  |
| IPLTYP | 7 | I | Pointer to Last Available Resource Element. <br> (If .LT.0, this word indicates an Automated Pool) |  |
| IPLCHR | 8 | I | Pool Characteristic Displacement in Jurisdiction File |  |
|  | 9 | I | Pointer to First Resource Element Owned by Pool |  |
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Page 4.0-22
FILE STRUCTURE

DESCRIPTION:


PAGE: $\qquad$ ut $\qquad$
file name: $\qquad$ 1 OWNER: $\qquad$
$\qquad$ ORDERING SCHEME: RL on ARTIME LENGTH NAME: $\qquad$
ATTRIBUTES

| NAME | $\begin{gathered} \text { WORD } \\ \text { NO. } \end{gathered}$ | $\begin{aligned} & \text { DATA } \\ & \text { TYPE } \end{aligned}$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
| ISUCR | 1 | I | Successor |  |
| IPRDR | 2 | I | Predecessor |  |
| IACPTR | 3 | I | Pointer to Aircraft File |  |
| ARTIME | 4 | R | Runway Arrival Time | Hrs. |
| RWCTM | 5 | R | Runway Clearance Time | Hrs. |
| VELAC | 6 | R | Average Sequencing Route Velocity | Kt. |
| $\begin{aligned} & \text { JALTD } \\ & \text { ACTA } \\ & \hline \end{aligned}$ | 7 | $\begin{aligned} & \mathrm{I} \\ & \mathrm{R} \\ & \hline \end{aligned}$ | Holder for IALTD for Departures Current Advance Time Available for Arrivals | $\triangle \mathrm{Hrs}$. |
| ACTR | 8 | R | Current Retard Time Available for Arrivals | $\triangle$ Hrs. |
| $\begin{aligned} & \text { TIMDEP } \\ & \text { IFETA } \\ & \hline \end{aligned}$ | 9 | $\begin{aligned} & \hline \mathrm{R} \\ & \mathrm{I} \\ & \hline \end{aligned}$ | Departure Time Interval Pointer to Feeder Fix for Arrivals | $\triangle$ Hrs. |
| IP $\emptyset \mathrm{F}$ | 10 | I | Pointer to UDP@F Event Notice |  |
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Page 4.0-23
FILE STRUCTURE

|  | PAGE: _ ${ }^{\text {OF }}$ |
| :---: | :---: |
| DESCRIPTION: Standard Event Notice |  |
| FILE NAME: N/A | ORDERING SCHEME: RL on TIME |
| OWNER: N/A | LENGTH NAME: LEVNTL |
| ATTRIBUTES |  |


| NAME | $\left\|\begin{array}{c} \text { WORD } \\ \text { NO. } \end{array}\right\|$ | $\begin{aligned} & \text { DATA } \\ & \text { TYPA } \end{aligned}$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
|  | 1 | I | Successor |  |
|  | 2 | I | Predecessor |  |
|  | 3 | R | Time | Hrs. |
| $\begin{aligned} & \text { IBLDCK } \\ & \text { NXTSK } \end{aligned}$ | 4 | I | Next Task for Select or Delay Return Flag |  |
| IHØLD | 5 | I | Utility Word |  |
| IACFT | 6 | I | Pointer to Aircraft File If .GT. 0 Pointer to Jurisdiction File If .LT. 0 |  |
| IRESRC | 7 | I | Pointer to Resource Element File If .GT. 0 Pointer to Resource Pool If .LT. 0 |  |
|  |  |  | Indicator that the fask is Unassigned if . EQ. 0 |  |
| $\begin{array}{\|l\|} \hline \text { WIRKTM } \\ \text { IACBLK } \end{array}$ | 8 | $\begin{aligned} & \hline R \\ & \mathrm{R} \end{aligned}$ | Accumulator or Utility Word |  |
|  |  |  |  |  |
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Page 4.0-24
FILE STRUCTURE

DESCRIPTION: Task Queue
PAGE: 1 UF
FILE NAME: ITASKO OWNER: Resource Pool File ORDERING SCHEME: $\frac{\text { RH on IPRID }}{\text { LEVGTH NAME: }}$ ATTRIBUTES

| NAME | NORD | DATA |  | DESCRIPTION | UNITS |
| :--- | :---: | :---: | :--- | :--- | :--- |
|  | 1 | I | Successor |  |  |
|  | 2 | I | Prececessor |  |  |
| IPRID | 3 | I | Priority |  |  |
| NXTSK | 4 | I | Task Number |  |  |
| IHØLD | 5 | I | Utility Word |  |  |
| IACFT | 6 | I | Aircraft or Jurisdiction Pointer |  |  |
| IRESRC | 7 | I | Pointer to Resource Pool (Negative) |  |  |
| WQRKTM | 8 | R <br> I | Utility Word |  |  |
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PAGE: $\qquad$ F 1
DESCRIPTION: Terminal File
FILE NAME: ITRMFL ORDERING SCHEME: LIFO
OWNER: Indexed Pointed to by Jurisdic- LENGTH NAME:
 ATTRIBUTES

| NAME | $\begin{gathered} \text { NORD } \\ \text { NO. } \end{gathered}$ | $\left\lvert\, \begin{aligned} & \text { DATA } \\ & \text { TYPE } \end{aligned}\right.$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
|  | 1 | I | Successor |  |
|  | 2 | I | Pointer to Jurisdiction File |  |
| ITERM | 3 | I | Pointer to Mass-Storage Terminal File |  |
|  | 4 | I | Pointer to First Metering and Sequencing Queue Entry |  |
|  | 5 | I | Pointer to Last Metering and Sequencing Queue Entry |  |
| PMSDAP | 6 | R | Probability of Missed Approach |  |
| IQAQD | 7 | I | Total Number of Runway Queue Entries $\begin{gathered}\text { (Carried } \\ \text { Negative) }\end{gathered}$ |  |
| NRW | 8 | I | Number of Runways |  |
|  | 9 | I | Pointer to First Runway Queue Entry for Runway 1 |  |
|  | 10 | I | Pointer to Last Runway Queue Entry for Runway 1 |  |
|  | 11 | I | Pointer to First Runway Queue Entry for Runway 2 |  |
|  | 12 | I | Pointer to Last Runway Queue Entry for Runway 2 |  |
|  | ! |  |  |  |
|  | $\begin{aligned} & 9+2 \pi \\ & (\mathrm{NRW} \\ & -7) \end{aligned}$ | I | Pointer to First Runway Queue Entry for Runway NRW |  |
|  | $\left(\begin{array}{l} 0+2 \\ (\mathrm{NRW} \\ -1 \end{array}\right.$ | I | Pointer to Last Runway Queue Entry for Runway NRW |  |
|  |  |  |  |  |
|  |  |  | $\cdots \cdot \cdots$ |  |

Page 4.0-26

## FILE STRUCTURE



| NAME | $\begin{aligned} & \text { NORD } \\ & \text { NO. } \end{aligned}$ | $\begin{array}{\|c\|} \hline \text { DATA } \\ \text { TYPE } \end{array}$ | DESCRIPTION | UNITS |
| :---: | :---: | :---: | :---: | :---: |
| ISUCC | 1 | I | Successor |  |
| IPRED | 2 | I | Predecessor |  |
| ETA | 3 | R | Estimated or Intended Time of Arrival | Hrs. |
| XINTND | 4 | R | Intended X-coordinant | N.MI |
| YINTND | 5 | R | Intended Y-coordinant | N.MI |
| ZINTND | 6 | R | Intended Z-coordinant | N.MI |
| SPDLEG | 7 | R | 3-Dimensional Speed for Next Route Leg if .GT.O. Pointer to Arrival Runway if .LT. 0 . | Kts. |
| TLEG | 8 | R | Time to the Next Fix Point if .GT.O. Pointer to Feeder Fix if .LT. 0 . | $\Delta \mathrm{Hr} .$ |
|  |  |  | End of Flight Plan Indicator if . EQ. 0. |  |
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### 5.0 PROGRAM OVERLAYS

The DELTA simulations consists of over 200 subroutines and has variable core requirements depending on the dynamic memory specified. The model has an input and utilization phase and a simulation phase. There is an obvious split between these two phases which lends itself to overlaying. However, the bulk of the executable code is within the simulation phase and it is desirable to overlay within this phase so as to not use an inordinate amount of central memory. Because the 165 functional task subroutines are executed in what amounts to an unpredictable sequence, it is extremely difficult to define a "logical" overlay structure which will avoid excessive loading of overlays during execution. Consequentially, the subroutines were grouped together by functions and algorithms.

During development it was desirable to execute the DELTA model in timeshare mode to be able to use the Debug facility available with TRW/TSS. In order to do this, the model was forced to fit in $60_{8} \mathrm{~K}$ words of core. This was accomplished by heavily overlaying the alcorithms and keeping the dynamic memory to the minimum value of $2_{10} \mathrm{~K}$ words. Ficure $5.0-1$ shows the LINK directives needed to fit the DELTA simulation into 60 K core.

However, the 60 K overlay is extremely inefficient because of excessive loading of overlay seaments. For production runs, it is desirable to execute them in batch mode. This can be accomplished by using the SUBMIT command to make remote job submission and makes available up to 3808 K words of central memory for use. Figure 5.0-2 shows the LINK directives used for production runs.

This overlay requires approximately $117_{8} \mathrm{~K}$ words of core for a ${ }^{15} 10$ K word dynamic memory allocation. Output from the Post Processor showed certain tasks were being performed with high frequency compared to most other tasks. To improve the overlay efficiency, these tasks were moved into Segment $B$ which is resident continuously durina the simulation phase. Further experience with the DELTA model may suagest changes in this overlay structure to improve the overall execution efficiency and cost.

Figure 5.0-1 Link Directives for DELTA Simulation to fit into $60_{8}$ K Core.


## (Continued)

Figure 5.0-1 Link Directives for DELTA Simulation to fit into $60{ }_{8} \mathrm{~K}$ Core.

(Continued)
Figure 5.0-1 Link Directives for DELTA Simulation to fit into $60_{8} \mathrm{~K}$ Core.


Figure 5.0-2 Link Directives for Production Runs.


## (Continued)

Figure 5.0-2 Link Directives for Production Runs.


## (Continued)

Figure 5.0-2 Link Directives for Production Runs.


### 6.0 TERMINAL GENERATION PROGRAM

This section presents a FORTRAN source listina of the Terminal Generation Program. A description of the use of this program can be found in Book I of this volume.

Figure 6.0-1 Terminal Generation Prooram.

0
G READ IN NUMEER OF TERMINALS AND SET JO JUTSIDE TO-LOOP.
60 WRITE (6,912) NREC


## (Continued)

Figure 6.0-1 Terminal Generation Program.
READ(2.90?)ATERM

(Continued)
Figure 6.0-1 Terminal Generation Program.

## (Continued)

Figure 6.0-1 Terminal Generation Program.

901 FORMAT(I2)
901 FOPMAT15105,24(ノ「10151) FORMAT13F12.51
FORMAT(2I2)
FO2MAT(I2,2F10.5) INFORMAIION. 웅

-
$\cos \omega \infty$
READ NUMBER OF ESCAPE ROUTES AUD SET UP OUTER DO-LOOP.

$$
\begin{aligned}
& \text { READ } 3,901) \text { NOER } \\
& \text { IF EOF,31 } 700,20 \mathrm{D}
\end{aligned}
$$

300

$$
\begin{aligned}
& \text { IF EOF, } 31700,200 \\
& 30 \cap K K=1
\end{aligned}
$$

$$
\begin{aligned}
& \text { DO } 300 K K=1, \text { NOER } \\
& \text { READ }(3,906) \text { NOERPT, }
\end{aligned}
$$

$$
\text { READ }(3,906) \text { NOERPT, IEFFX }
$$

$$
\begin{aligned}
& \text { IF(EOF,3) } 700,21 \text { O } \\
& \text { IF (NOERPT.LT.11) GOT? }
\end{aligned}
$$

$$
\begin{aligned}
& \text { IF INOERPT.LT.I1) EO TS } 220 \\
& \text { WRITE(5, } 0 \text { NI NOERPT }
\end{aligned}
$$

CONTINUE

$$
\text { GO TO } 700
$$

$$
\begin{aligned}
& \text { S } 1030 N=7 \\
& \cdot 0=H 1 N 73
\end{aligned}
$$

$$
\begin{aligned}
& =108200 \\
& 51030 N=7
\end{aligned}
$$

$$
O E \cdot \varepsilon I G O=
$$

$$
\begin{aligned}
& 00280 \\
& J=K-1
\end{aligned}
$$

$$
\begin{aligned}
& J=K-1 \\
& E L N T H=E L I
\end{aligned}
$$

$$
+\quad \text { CONTINUE }
$$

$$
\begin{aligned}
& \text { IPER(KK) }=\text { NREC } \\
& \text { NREC }=N R E G+1
\end{aligned}
$$

CONTINUE 200
210
220
230
240
250
260
270

$$
1
$$

$$
21
$$

$$
+(E R X Y Z(2, K)-E P X Y Z(Z, J)) *+2+(E R X Y Z(3, K)-E R X Y Z(3, J)) * * 2)
$$

$$
\begin{aligned}
& \text { CALL WRITMS(3J,NOLRPT, ЭO, NREC) } \\
& \text { TPER(KK) MPFC }
\end{aligned}
$$

$$
\begin{aligned}
& \text { NREC = NREG }+1 \\
& \text { CONTINUE }
\end{aligned}
$$

$\stackrel{O}{\sim}$
(Continued)
Figure 6.0-1 Terminal Generation Program.

7.0 INTERARRIVAL TIMES GENERATION PROGRAM

This section presents a FORTRAN source listing of the Interarrival Times Generation Proaram. A description of the use of this program can be found in Book I of this volume.

```
LIST, SDATA
    DROGRAM SDATA(UALUES,OITDIJT,TADF5=UALIJES,TADEG=OUTDITT)
        NAMELIST/UALUES/NUMX, XMU, RNDPRM, XMAX
    1. READ (5,VALUES)
        IF (N!NM - EO. T) GO TO lTO
        2Z=RANF (R.NDPRM)
        RNDPRM=?.
        WRITE (6,90) XMU
        SUM=0.
        DO 10 I=1,NUMX
        R=RANF(O.)
        IF (R.EQ.0.) GO TO 17
        X=-1.*MM*ALOG(R)
            IF(X.GT. XMAY) X=YMU
        SUM=SIJM+Y
        WRITE (6,95) X,SUM
    10 CONTINUE
    GO TO 1
    90. FORMAT (6HMEAN =:,2X,F7.6)
    95 FOFMAT (F9.6, 2X,FR.6)
17% STOP
    END
```

Figure 7.0-1 Interarrival Times Generation Program.

### 8.0 POST PROCESSOR PROGRAM

8.1 Description Of Loo Tape

In ELIST, each time a "resource-usina." task is completed, the following record is written on the Post Processor, loa tape:

Time, Task Number, Aircraft Id (or spaces), Jurisdiction Id, Phase of Flight (or spaces), Resource Element Number, Resource Pool Type.

In 703000 , each time an aircraft is added, the following record is written:

Time, 2999, Aircraft Id, Jurisdiction Id, Phase of Flight, A/C INP.

In MOVAC, when an aircraft is removed from an enroute hold, the following record is written:

Time, 4999, Aircraft Id, Jurisdiction Id, Phase of Flight, Length of Hold.

In M, ${ }^{2} A C$, when an aircraft is removed from a Meterina and Sequencing Hold, the following record is written:

Time, 5999, Aircraft Id, Jurisdiction Id, Phase of Flight, Length of Hold.

In ACJBC2, each time an aircraft crosses a jurisdiction boundary causing a handoff, the following record is written:

Time, 6999, Aircraft Id, New.Jurisdiction Id, Phase of Flight, 01d Jurisdiction Id.

In UDPØF, each time an aircraft changes its phase of flioht, the following record is written:

Time, 7999, Aircraft Id, Jurisdiction Id, New Phase of
Flight, and on landings, the difference, ENDURANCE - TIME.
In CANAC, each time an aircraft is dropped, the following record is written:

Time, 8999, Aircraft Id, Jurisdiction Id, Phase of Flight, DLD, Source of Call Indicator, set as follows:

2 - BNDRY (Flew out of system)
4 - ACT4 (Reached last point in flioht plan)
38 - T04402 (Cancelled Flight Plan)
168 - UDPOF (Aircraft Landed, usually superceded by ACT4)
If the program ends with aircraft still in the system, the following information is printed for each aircraft remaining:

Time, 9999, Aircraft Id, Jurisdiction Id, Phase of Flight, DATAFIL.

### 8.2 Source Listing

This section presents a FORTRAN source listing of the DELTA Post Processor Program. A description of the use of this program can be found in Book I of this volume.


$$
\begin{aligned}
& 000037 \\
& 000042 \\
& 000043
\end{aligned}
$$

000145
000055
000067
000071
115 NJUR $\begin{aligned} & \text { INこREMFNT JURISJICTION COUNTER } \\ & =\text { NJUR }+1\end{aligned}$
$-C R=J B L A N K$
C SAME JURTSOTCTIONZ

$$
12 / 13 / 73.10 .47 .03
$$

POラTOPC
36
POTTOPO

$$
\text { GO TO } 115
$$

Page 8.2-4
posiope
12/13/73. 10.47.03.
RUNX COMDILER (VE?.26)
osto
run COMPILER (VER.26)
POJTOPG

Page 8.2-6
RUNX COMSILER (VE?.25)
000363
009375
000376
000376
000420
000422 000426 000432
000434 000435 000447 000450 000460
005460 000461 000475 000476 000504 000515
000520 003522

$$
\begin{aligned}
& \text { KEY, } \mathrm{C} \text { EQ. } 5, ~ A I R G R A F T \text { GHANGING JURISOICIIONS (ACJBCZI } \\
& \mathrm{C} \text { WRITE }(6,9855) \text { AC, TIME, JUR }
\end{aligned}
$$

$$
\begin{aligned}
& \text { WRIT: } 66 ? \\
& \text { GO TO } 70 ?
\end{aligned}
$$

$$
\begin{aligned}
& 30
\end{aligned}
$$

 ENJ
002362
000345

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|  |  | $\varepsilon \angle T 000$ |  | 051 | カレて007 | 19ヶ000 |  |
| HEM000 | こてカロ00 | SLEGOG |  |  |  |  |  |
| L2E000 | ナTEOOO | なりて000 |  | 001 | st2007 | C9\％000 |  |
|  |  | $0 ヶ 2000$ |  | 069 | 012007 | OSTOCO |  |
|  |  | LEZ000 |  | 089 | ＋02007 | SEMOOO |  |
|  |  | 9と2000 |  | ［1＜$<9$ | S91607 | $9 \angle 2000$ |  |
|  |  | SECOOO |  | 099 | 191007 | ¢98000 |  |
|  |  | ゅをZ000 |  | US9 | SSTCO7 | 9力E000 |  |
|  |  | EE2000 |  | 0ヶ9 | IST007 | IEEOOO |  |
|  |  | 2¢2000 |  | $0 ¢ 9$ | CSTDET | CEEOCO |  |
|  |  | I¢ 2000 |  | 029 |  | STEOOO |  |
|  |  | $0 ¢ 2000$ |  | CL9 | ¢ヶTCOT | HIEOCO |  |
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|  |  | £ +2000 |  | SLS | 121007 | $\angle$ ここOC0 |  |
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|  |  | E $\angle T 000$ |  | GTS | 4 20007 | ＋$\angle T 000$ |  |
| 215000 | ＋92000 | 9ヶ2000 |  | 0 OS | $\angle 90007$ | TSTOOC |  |
|  |  | Shtcoo |  | 405 | ＋90007 | 9わ1000 |  |
|  |  | $\angle 41000$ |  | 205 | 150007 | £2I000 |  |
|  | 920000 | S20000 |  | 005 | 250007 | SITOOD |  |
|  |  | G 20000 |  | 521 | 470007 | TOTOOO |  |
|  |  | HSOOOO |  | 515 | 280007 | 220000 |  |
|  |  | TッOCOO |  | 0 IT | 520007 | $5+0000$ |  |
|  |  | I＋0000 |  | 501 | 220007 | 270000 |  |
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|  | 000601 | C00053 |
|  | 000614 | C00066 |
|  | 000617 | 200071 |
|  | 000633 | $\bigcirc 00105$ |
|  | 003645 | C00117 |
|  | 000661 | cool3 |
|  | 000675 | COJ147 |
|  | 000707 | 000161 |
|  | 000721 | C00173 |
|  | 000733 | CJJ 205 |


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| 000303 | 000472 |
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|  | 901002 | VOCOCL | NJUR |
|  | 001005 | V00017 | NLAVO |
|  | 001001 | V00003 | NLCC |
|  | 000751 | A00001 | Phase |
|  | 001013 | $\checkmark 00015$ | TIME |
|  | 001005 | V00007 | TLAVDL |
|  | 001004 | v00006 | rlandi |
| START OF 000526 | LONSTAN |  |  |
| START OF | TEMPORA |  |  |
| 000742 |  |  |  |
| START OF | INDIREC |  |  |
| 000750 |  |  |  |
| COMPILER | SPACE |  |  |
| UNUSED－ | 010000 | USED | 040000 |

## APPENDIX REPORT OF INVENTIONS

A diligent review of the work performed under this contract, has revealed no new innovation, discovery, improvement, or invention.

