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**DONBOL: A Computer Program for
Predicting Axisymmetric Nozzle
Afterbody Pressure Distributions
and Drag at Subsonic Speeds**

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SUMMARY

A Neumann solution for inviscid external flow has been coupled to a modified Reshotko-Tucker integral boundary-layer technique, the control volume method of Presz for calculating flow in the separated region, and an inviscid one-dimensional solution for the jet exhaust flow in order to predict axisymmetric nozzle afterbody pressure distributions and drag. The viscous and inviscid flows are solved iteratively until convergence is obtained. A computer algorithm of this procedure has been written and is called DONBOL. This paper provides a description of the computer program and a guide to its use. Comparisons of the predictions of this method with experiment show that the method accurately predicts the pressure distributions of boattail afterbodies which have the jet exhaust flow simulated by solid bodies. For nozzle configurations which have the jet exhaust simulated by high-pressure air, the present method significantly underpredicts the magnitude of nozzle pressure drag. This deficiency results because the method neglects the effects of jet plume entrainment. This method is limited to subsonic free-stream Mach numbers below that for which the flow over the body of revolution becomes sonic.

INTRODUCTION

The drag-producing components of the airplane propulsion system are usually installed in areas where the flow field is extremely complex. High body slopes and long boundary-layer runs, especially in the afterbody nozzle region, result in strong viscous effects on boattail drag. Furthermore, the viscous nature of the jet exhaust plume complicates the flow in this region. Because of these strong viscous interactions, current methods used for predicting the installed propulsion system drag are usually limited to empirical techniques. Recently, however, investigators have achieved some success in predicting uninstalled drag of axisymmetric nozzles with what is usually called the patched viscous-inviscid technique. (See refs. 1 to 7, for example.) In reference 1, Reubush and Putnam combine iteratively a conventional boundary-layer technique with a linearized potential-flow computation to account for the viscous-inviscid interaction. For boattail nozzles on which boundary-layer separation occurs, Reubush and Putnam employ the discriminating streamline concept of Presz (refs. 8 and 9) to separate the reverse flow region from the outer flow. The patched viscous-inviscid interaction methods have been successful in predicting the qualitative trends in boattail pressure drag with Mach number, Reynolds number, and nozzle geometry in spite of the complexity of the flow even for isolated boattails. (See ref. 1, for example.) In general, however, these techniques substantially underpredict the absolute levels of pressure drag on boattail nozzles at subsonic speeds.

Recently, an improved analytical model of the flow in the separated region has been developed by Presz (refs. 10 and 11). With this analytical model, the effects of axial-pressure gradients, surface skin friction, and jet plume entrainment on the shape of the discriminating streamline are computed. Predictions made using this new technique (refs. 10 and 11) are in substantially

better agreement with experiment than the predictions of the previous methods (refs. 1 to 7). This improved model of the separated flow region, therefore, has been combined iteratively with the inviscid linearized potential-flow solution described in reference 1.

The present paper describes the various components of the resulting computer algorithm called DONBOL. Also, this paper illustrates the prediction capabilities of the method by comparison with experimental data. A user's guide to the computer program is presented. The computer program may be obtained from COSMIC, Suite 112, Barrow Hall, University of Georgia, Athens, GA 30602.

SYMBOLS

The symbols used in the computer printouts are given in a separate column.

A	SREF	maximum cross-sectional area of body of revolution
B		compressibility correction factor (see eq. (6))
C_D		boattail pressure drag coefficient, $Drag/q_\infty A$
	CDF	skin-friction drag coefficient
	CDP	pressure drag coefficient
	CDT	total drag coefficient
C_p	CP	static pressure coefficient
c_f	CF	local skin-friction coefficient
D	D	maximum diameter of body of revolution
d_b	DB	base diameter
H	H	boundary-layer shape factor, δ^*/θ
L		length of body of revolution
	L	reference length
l		length of nozzle or boattail
M	MO	Mach number
NPR		ratio of jet total pressure to free-stream static pressure, $P_{t,jet}/P_\infty$
N_{Re}		Reynolds number based on distance from nose of model to start of boattail

p		static pressure
p _t	PT	total pressure
q _∞		free-stream dynamic pressure
R		gas constant
	RC	body radius corrected for δ* and discriminating streamline
r	R	radial coordinate of cylindrical coordinate system with origin at nose of body of revolution
	RDS	radius of the discriminating streamline
r*		radius of stream tube for Mach number of 1
T _t	TT	total temperature
V _r	VR	ratio of radial velocity to free-stream velocity
	VT	ratio of local velocity to free-stream velocity
V _x	VX	ratio of axial velocity to free-stream velocity
x	X	axial coordinate of cylindrical coordinate system with origin at nose of body of revolution
Δx		axial distance downstream of start of boattail
β		$= \sqrt{1 - M_{\infty}^2}$
γ		ratio of specific heats
	DEL	boundary-layer thickness
δ*	DEL*	boundary-layer displacement thickness
	ETA	local flow angle
θ	THETA	boundary-layer momentum thickness
Subscripts:		
a		analogous configuration (see eqs. (1) to (6))
des		design conditions of nozzle
e		exit
exp		experiment

jet	jet
p	predicted
s	separation
∞	free stream

DESCRIPTION OF METHOD

The present analytical method has been developed to calculate the flow over axisymmetric boattail bodies at subsonic speeds. It is assumed that the flow is composed of a viscous layer near the body, an inviscid external flow, and, if present, an inviscid jet exhaust flow. (See fig. 1.) The effect of the viscous layer is accounted for by modifying the body shape with an appropriate displacement thickness. In the framework of this representation, any boundary-layer separation on the boattail or nozzle surface is accounted for by modifying the afterbody geometry and plume boundary.

Inviscid External Flow Solution

The Neumann solution of reference 12 for incompressible flow over bodies of revolution was used to calculate the inviscid external flow. Since this is a solution for incompressible flow, the compressibility correction of reference 13 was used to correct for Mach number effects. The incompressible flow field considered is that for an "analogous" configuration obtained by means of the affine coordinate transformation given by the following equations:

$$x_a = \frac{x}{\beta} \quad (1)$$

$$r_a = r \quad (2)$$

where

$$\beta = \sqrt{1 - M_\infty^2} \quad (3)$$

The calculated flow velocities of the analogous configuration are then corrected using the following equations:

$$v_x = \frac{v_{x,a}}{\beta^2} \quad (4)$$

$$v_r = \frac{\beta v_{r,a}}{\beta^2} \quad (5)$$

where

$$B = \sqrt{1 - M_{\infty}^2 (1 + V_{x,a})} \quad (6)$$

The pressure coefficients are obtained from the corrected velocities by using the compressible Bernoulli equation and the isentropic flow relations. Experience to date indicates that this compressibility correction provides better agreement with experimental results for flow over boattails than the classic Goethert compressibility correction.

Because the inviscid outer flow solution is based on incompressible flow theory with a compressibility correction, the present method is limited to free-stream Mach numbers for which the flow is subsonic everywhere.

Inviscid Jet Exhaust Flow

To calculate the inviscid boundary of the jet exhaust flow, a procedure based on one-dimensional isentropic flow theory has been developed and is used in the present computer program, DONBOL. The procedure for calculating the radius of the inviscid jet plume at any axial location downstream of the nozzle exit is as follows. Initially, a shape for the jet plume boundary is assumed. Next, the pressure distribution along this boundary is calculated. Then, a new value of the radius at each axial location is ascertained by calculating the cross-sectional area required to expand isentropically from the flow conditions at the nozzle exit to the pressure on the boundary at that location. This new boundary is used in the next iteration as the guess. The equations used to compute the inviscid jet plume boundary from the flow conditions at the nozzle exit and the pressure distribution along the boundary are as follows:

$$\left(\frac{P_t}{P}\right)_{des} = \left(1 + \frac{\gamma - 1}{2} M_{des}^2\right)^{\gamma/(\gamma-1)} \quad (7)$$

$$P_e = q_{\infty} C_{p,e} + p_{\infty} \quad (8)$$

If

$$\frac{P_{t,jet}}{P_e} > \left(\frac{P_t}{P}\right)_{des}$$

then

$$M_{jet} = M_{des} \quad (9)$$

If

$$\frac{P_{t,jet}}{P_e} \leq \left(\frac{P_t}{P} \right)_{des}$$

then the static pressure across the exit is assumed equal to the external static pressure at the exit and

$$M_{jet} = \sqrt{\frac{2}{\gamma - 1} \left[\left(\frac{P_{t,jet}}{P_e} \right)^{(\gamma-1)/\gamma} - 1 \right]} \quad (10)$$

Then

$$\frac{r^*}{r_e} = \sqrt{M_{jet} \left(\frac{\gamma + 1}{2} \right)^{(\gamma+1)/2(\gamma-1)} \left(1 + \frac{\gamma - 1}{2} M_{jet}^2 \right)^{-(\gamma+1)/2(\gamma-1)}} \quad (11)$$

Now at any given x-location downstream of nozzle exit since C_p is a function of x ,

$$p = \alpha_\infty C_p + p_\infty \quad (12)$$

$$M = \sqrt{\frac{2}{\gamma - 1} \left[\left(\frac{P_{t,jet}}{p} \right)^{(\gamma-1)/\gamma} - 1 \right]} \quad (13)$$

and

$$\frac{r^*}{r} = \sqrt{M \left(\frac{\gamma + 1}{2} \right)^{(\gamma+1)/2(\gamma-1)} \left(1 + \frac{\gamma - 1}{2} M^2 \right)^{-(\gamma+1)/2(\gamma-1)}} \quad (14)$$

Then

$$\frac{r}{r_e} = \frac{r^*/r_e}{r^*/r} \quad (15)$$

Also

$$V_{x,jet} = M \sqrt{\frac{\gamma R T_{t,jet}}{1 + \frac{\gamma - 1}{2} M^2}} \quad (16)$$

This procedure has been used to calculate the shape of the inviscid jet plume for the exhaust flow from a convergent nozzle at two nozzle pressure ratios. The procedure is compared in figure 2 with the predictions of the method of Salas (ref. 14) modified to account for pressure variation along the jet boundary. The identical longitudinal pressure distribution along the boundary of the jet was assumed with each method. However, slightly different pressure distributions were assumed for each nozzle pressure ratio. At NPR = 2.90, the shapes of the jet exhaust plume boundary predicted by the two methods are in very good agreement. At NPR = 5.03, the one-dimensional method does not agree as well with the method of Salas. As will be shown later, however, the one-dimensional method does provide a reasonable estimate of the effects of NPR on nozzle drag.

Viscous Flow

The properties of the viscous boundary layer (both attached and separated) and the location of any separation on the nozzle boattail are calculated using the methods and computer algorithm developed by Presz, King, and Buteau and described in reference 10. Presz, King, and Buteau computed the turbulent boundary-layer displacement-thickness distribution along the body with the method described in reference 15. This method is a modified version of the Reshotko-Tucker integral boundary-layer solution (ref. 16). A comparison of the predictions of this technique with the experimental measurements of Winter, Rotta, and Smith (ref. 17) at $M_{\infty} = 0.6$ and a Reynolds number, based on body length, of 9.85×10^6 is presented in figure 3.

If boundary-layer separation occurs on the boattail, the boundary-layer equations become singular at the separation point. To overcome this difficulty, Presz uses the concept of a discriminating streamline to separate the reverse flow region from the outer boundary-layer flow. This method, described in reference 10, accounts for the effects of axial-pressure gradients, surface skin friction, and viscous mixing in the jet exhaust flow on the shape of this discriminating streamline. Note that the present method does not account for the effects of viscous mixing downstream of the reattachment point.

The use of Presz's model of the separated region requires that some method be available for predicting the location of separation. Several methods are available. They include Presz's control volume technique (ref. 8), Goldschmied's criterion (ref. 18), a modified Page criterion (ref. 19), and Stratford's criterion (ref. 20). A discussion of the accuracy of the various separation location criteria is given in reference 21 by Abeyounis. Any of these methods can be used in the current computer program.

Viscous-Inviscid Interaction

Since the boundary-layer displacement thickness, the discriminating streamline shape, and the inviscid jet boundary are functions of the pressure distribution along the body and the jet boundary, the final converged solution must be obtained by iteration between the inviscid outer flow solution, the inviscid jet plume solution, and the viscous boundary-layer solution. The iteration algorithm used in the present method is shown in figure 4 and is as follows:

- (1) Calculate the inviscid pressure distribution on the body of revolution.
- (2) Calculate the inviscid jet plume boundary.
- (3) Calculate the boundary-layer displacement thickness.

(4) Calculate the location of boundary-layer separation on the boattail. The separation location is calculated using the criteria selected by the user and is based on the pressure distribution and, in some cases, boundary-layer characteristics of the flow over the body. For the first iteration, a separation location will always be predicted. Ideally, the separation location should move aft with increasing number of iterations, and the separation region should essentially disappear as the solution approaches convergence for nozzles and flow conditions where no boundary-layer separation would occur. Unfortunately, with the available separation criteria, this separation region does not always disappear. It is suggested that a solution first be attempted assuming attached flow for nozzles when there is a question about whether or not separation occurs. If the solution diverges, the user can then assume that the flow is not attached, and the calculation must be repeated assuming that the flow is separated.

(5) If a separated flow calculation is required, calculate the shape of the discriminating streamline. To speed convergence and to eliminate some initial numerical stability problems, the present method assumes that for the first four iterations, axial-pressure gradients do not affect the shape of the discriminating streamline. After nine iterations, the shape of the discriminating streamline is frozen.

will it converge
if not frozen

(6) Correct the body geometry for boundary-layer displacement effects by adding an effective displacement thickness to the original body. The effective displacement thickness includes the discriminating streamline in the separation region. A relaxation procedure described in reference 8 is used to expedite convergence and to eliminate instabilities in the iteration procedure.

(7) Repeat steps (1) to (6) for the desired number of iterations. In the present algorithm, no convergence criteria are specified. Convergence is assumed to occur when two successive iterations plotted to a reasonable scale give essentially the same results. To obtain this result, most configurations require about 15 iterations.

COMPARISONS OF PREDICTIONS AND EXPERIMENT

The predictions of program DONBOL for an $l/D = 1.768$, $d_b/D = 0.51$ circular-arc afterbody with a solid cylindrical jet plume simulator and with attached boundary-layer flow are compared with the experimental data of reference 22 in figure 5. At both free-stream Mach numbers shown, the agreement between the predicted and experimental pressure distributions is excellent. The boattail pressure drag of the configuration is underpredicted. However, the differences between theory and experimental drag are within the accuracy of the experimental measurements. These results are typical of all attached-flow cases computed to date with DONBOL. } factor of two different

For boattail nozzles and afterbodies on which the boundary layer separates, the agreement between the predictions of the present method and experiment depends on the chosen separation criterion. In reference 21 Abeyounis showed that a criterion predicts significantly different locations for separation depending on whether the theoretical inviscid pressure distribution or the experimental pressure distribution is used. This result suggests that the predicted separation location may also be a function of the iteration algorithm used in a patched viscous-inviscid interaction procedure such as DONBOL. Therefore, the accuracy of a given separation criterion should be assessed using the total prediction algorithm for which it is to be incorporated. Predictions of the separation location criteria incorporated in DONBOL are compared with the experimental data of Abeyounis (ref. 21) in figure 6(a). The large differences shown in predicted separation location can affect predicted afterbody pressure distributions and drag significantly, as illustrated in figure 6(b). Based on these limited results and because it more accurately predicts the location of separation on the steep, highly separated $l/D = 0.8$ boattail configuration, the method of Presz is recommended and is used for all further calculations presented in this paper.

An illustration of the capabilities of the present method for predicting the effects of free-stream Mach number on the pressure distribution and drag of an afterbody with separated boundary layer is shown in figure 7. The experimental data from references 22 and 23 shown in this figure are for the same $l/D = 0.8$, $d_b/D = 0.51$ circular-arc afterbody with solid cylindrical plume simulator for which separation location data are presented in figure 6(a). At a Mach number of 0.4 where the separation location is accurately predicted using the Presz criterion, the agreement between experimental and predicted pressure distributions is very good. As the difference in predicted and actual separation location increases with increasing free-stream Mach number, the agreement in pressure distributions between theory and experiment deviates somewhat. However, as shown in figure 7(b) the agreement between predicted and actual boattail pressure drag improves with increasing Mach number. This agreement is essentially within experimental accuracy throughout the range of Mach numbers for which the theory is applicable. } as assumption gets worse, results get better? } says it doesn't matter anyhow

At a given free-stream Mach number, the agreement between theory and experiment is a function of boattail geometry. The comparisons between the theory and experiment of reference 23 shown in figure 8 indicate that for boattails with less closure than the configuration of figure 7, substantially better agreement between theory and experiment can result.

The capabilities of the present method for predicting the effects of Reynolds number on boattail pressure distributions and drag are illustrated in figure 9. The agreement between theory and experiment is a function of Reynolds number and boattail geometry. However, the predicted variation of the boattail-pressure drag coefficient with Reynolds number is in relatively good agreement with the experimental results (fig. 9(c)).

A comparison of the experimental (refs. 22 to 24) and predicted effects of the ratio of nozzle total pressure to free-stream static pressure NPR on the pressure distribution and drag of a $l/D = 0.8$, $d_b/D = 0.51$ circular-arc nozzle is shown in figure 10. In general, the present method reasonably predicts the variation of the pressure distributions with NPR. However, at both $M_{\infty} = 0.6$ and 0.8 (figs. 10(a) and 10(b)) DONBOL generally predicts more positive pressures than actually exist on the nozzle. As a result, the magnitude of the boattail drag is substantially underpredicted (fig. 10(c)). These deficiencies probably result because the present method does not account for the effects of jet entrainment. Note that the present method does account for the effects of jet entrainment on the shape of the separation discriminating streamline, but does not account for jet plume entrainment in any manner downstream of the reattachment of the separated boundary layer. Jet entrainment downstream of reattachment should reduce the pressures on the nozzle and thereby increase the nozzle drag. As shown in figure 10(c), the present method accurately predicts the nozzle drag when the jet exhaust flow is simulated experimentally by a solid cylindrical sting. This solid sting, of course, does not simulate the effects of jet plume entrainment, but does simulate the effects of jet plume blockage on the flow over the nozzle. Even though the present method does not accurately predict the magnitude of nozzle drag, it does predict the decrease in drag at the higher nozzle total-pressure ratios. The present method does not, however, predict the increase in drag at the lower pressure ratios. Further illustrations of the capabilities of the present method for predicting pressure distributions and drag for nozzles with jet exhaust flow are shown in figure 11. Here the program DONBOL was used to calculate the flow over the equivalent bodies of reference 25 with the nozzles operating at an NPR of approximately 2.5. For these configurations, the predictions generally agree better with experiment than for the configuration shown in figure 10.

DESCRIPTION OF COMPUTER PROGRAM

A flow chart of program DONBOL is presented in figure 12 and a listing of the program is provided in the appendix. This program is written in overlay form and consists of the main overlay and four primary overlays. Primary overlays 1 to 3 are used to calculate the inviscid external flow, and overlay (5,0) is used to calculate the inviscid jet exhaust flow, the boundary-layer flow, and the "effective" body geometry for further iterations. The program uses nine disk files during computation. Input data are obtained from TAPE5 and the results are written on TAPE6 which is set equal to OUTPUT. A restart output file is written on TAPE7. The remaining disk files are used internally by the program. DONBOL requires about 125 000 octal storage locations on the Control Data CYBER 175 computer system and executes 15 iterations in approximately 3 minutes.

A brief description of the various routines in the program is given in the following list:

- DONBOL** This routine reads the input data, stores the x- and r-coordinates on TAPE13, and controls the iteration procedure. All primary overlays are called from this routine.
- ONE** This routine prints certain control parameter information and calls subroutines BASIC1 and MATRIX.
- BASIC1** This subroutine makes the compressibility correction transformations to the x- and r-coordinates, calculates coordinates of the midpoint of each body panel, and calculates the slope of each body panel.
- MATRIX** The influence coefficient matrix and the boundary condition matrix are set up in this subroutine. MATRIX calls subroutine XYZ.
- XYZ** The influence coefficients are calculated by this subroutine. A constant source of unit strength is assumed to act on each panel. The influence coefficient is the integral of the effect of the constant strength source. The subroutine calls XYZ1 and XYZ2.
- XYZ1** This subroutine performs the integration of the effects of the constant strength source for points within a specified radius of the singularity.
- XYZ2** This subroutine performs the integration using Simpson's rule to determine the influence of the unit source panel at all distances greater than the specified radius from the singularity. The routine calls subroutine ELIP.
- ELIP** This subroutine is used to calculate the value of various elliptical integrals.
- TWO** This routine initializes parameters for call to MISNA2.
- MISNA2** This subroutine calculates the strengths of the source panels by solving the matrix equation using a Seidel iteration procedure.
- THREE** This routine initializes various parameters and then calls subroutine AXIS. The pressure coefficients computed by AXIS are then written on TAPE13.
- AXIS** This subroutine calculates velocity components of the flow and surface-pressure coefficients. The velocity components are corrected for compressibility effects using either the Goethert or Labrujere method, before computing the pressure coefficient.
- FIVE** This routine is the interface between the inviscid external flow calculation and the viscous flow calculations. The body geometry and pressure coefficients are read from TAPE13. The inviscid jet plume

exhaust flow boundary and velocity are calculated. The viscous subroutine package is called to obtain boundary-layer parameters and the corrected effective body contour. See reference 8 for details of the subroutines in the viscous package. Routine FIVE also computes the drag coefficient. The results are printed and the final solution put on TAPE7 for further iteration if necessary.

IUNI This is a Langley Research Center computer system library subroutine. The subroutine uses first- or second-order Lagrangian interpolation to estimate the value of a set of functions at a specified value of the independent value.

Description of Input Data Cards

Sample input data required for program DONBOL are presented in figure 13. This figure presents the input data required to compute the flow over a boat-tail nozzle configuration with jet exhaust flow. This test case also illustrates the input data required to compute flow conditions at points off the body. Specifically, the input data required are as follows:

Card 1: identification.- Card 1 contains any desired identifying information in columns 1 to 80.

Card 2: control integers.- Card 2 contains 13 integers, each punched right justified in a five-column field. An identification of the card columns, the name used by the source program, and a description of each integer is given in the following table:

<u>Columns</u>	<u>FORTTRAN name</u>	<u>Description</u>
1 to 5	ISWITCH	Calculation Option Code: If ISWITCH = 1, potential-flow solution only. If ISWITCH = 2, boundary-layer effects on pressure distribution are included in solution using an iteration scheme. If ISWITCH = 3, boundary-layer solution only.
6 to 10	IPRINT	Iteration number to start printing results.
11 to 15	IPUNCH	Punch option code: If IPUNCH greater than 0, last iteration is written on TAPE7 in format necessary for a restart of solution. CP for last iteration also written on TAPE7.
16 to 20	ITERA	Iteration number for first calculation of this submittal. For initial submittal of any calculation, ITERA must be 0.

<u>Columns</u>	<u>FORTTRAN name</u>	<u>Description</u>
21 to 25	ITERMAX	Maximum number of iterations (less than or equal to 20).
26 to 30	IMACH	Compressibility correction code: If IMACH = 1, Goethert compressibility correction used. If IMACH = 2, Labrujere compressibility correction used.
31 to 35	ISEP	Separation location criteria code: If ISEP = 0, no separation model used. If ISEP = 1, separation location specified by user. }! If ISEP = 2, Presz control volume criterion used. If ISEP = 3, Goldschmied criterion used. If ISEP = 4, modified Page criterion used. If ISEP = 5, Stratford criterion used.
41 to 45	INT(3)	X-array location to start search for separation.
46 to 50	INT(4)	X-array location to end search for separation.
51 to 55	INT(5)	Jet plume and entrainment option: If INT(5) = 0, omit jet plume and entrainment calculations. If INT(5) = 1, include jet plume and entrainment calculations.
56 to 60	INT(6)	X-array location of nozzle exit.
61 to 65	INT(7)	Smoothing parameter: If INT(7) = 0, no smoothing. If INT(7) = 1, aerodynamic body contour and pressure distribution are smoothed. INT(7) = 1 should be used. }!
66 to 70	IFLAG5	An integer which if greater than 0 specifies that off-body points are to be calculated.

Card 3: free-stream conditions and reference dimensions.- Card 3 contains quantities used to define the free-stream flow and dimensional information required to convert body coordinate inputs to meters. If the separation location is to be input by the user, it is given on this card. Identification of the card columns, names used in the source program, and a description of each variable is given in the following table:

<u>Columns</u>	<u>FORTRAN name</u>	<u>Description</u>
1 to 10	MO	Free-stream Mach number.
11 to 20	PT	Free-stream total pressure, Pa.
21 to 30	TT	Free-stream total temperature, K.
31 to 40	REFL	Reference length - factor required to convert input values of x and r to meters.
41 to 50	SREF	Reference area, meters ² .
51 to 60	XSEPND	The x-coordinate of the separation location. Required if ISEP = 1.

Card 4: jet exhaust conditions.- This card contains quantities used to define the jet exhaust flow. If there is no jet exhaust flow (INT(5) = 0) this card may be blank, but it must be input. The card contains the following information:

<u>Columns</u>	<u>FORTRAN name</u>	<u>Description</u>
1 to 10	XMJET	Mach number of jet at nozzle exit.
11 to 20	PTJET	Jet total pressure, Pa.
21 to 30	TTJET	Jet total temperature, K.
31 to 40	RJET	Radius of nozzle exit.

Cards 5, 6, . . .: remaining data input cards.- The remaining data cards provide a description of the body geometry, the location of any off-body points at which the flow is to be calculated, and the surface pressure coefficients if the boundary-layer solution only is to be computed. Unless otherwise noted, each card contains up to six values with each value punched in a ten-column field with a decimal.

Body geometry cards: The first body geometry data card gives the number of coordinates, NN. The integer, NN is punched in columns 1 to 5 right justified. The number of body coordinates may not be greater than 200. The next group of body geometry data cards contains the axial location at which the body radius is to be specified. There are exactly NN locations with up to six values per card. The next group of body geometry data cards contains the radius of the body at the specified axial locations. Again there are NN values of the body radius specified. Note that if the jet exhaust flow option is selected, an initial guess of the shape of the jet plume boundary must be included in the description of the body geometry.

Off-body points: If the flow is to be calculated at any off-body points and $IFLAG5 > 0$, then the following cards must be input. First the number of off-body points must be specified on a data card. The number of off-body points is punched in columns 1 to 5 right justified. (Note that the sum of the points on the body of revolution and the off-body points may not be greater than 200.) Then a group of data cards giving the location of the x-coordinates at which the flow is to be calculated is input. This group of cards is followed by a group of cards on which the r-coordinates of the off-body points are specified.

Pressure coefficients cards: This group of cards is input only if the program is to be restarted or if $ISWITCH = 3$, that is, when the boundary-layer solution only is to be calculated. The pressure coefficient at each body x-coordinate location is input with six values per card.

Description of Output

Program output consists of printed output and a disk file TAPE7 written in the form necessary for a restart of the program. An example of the printed output is presented in figure 14 for the test case presented in figure 13.

The first page of output includes the program title, case identification, list of control options selected, free-stream conditions, and, if requested, jet exhaust flow conditions. On the second page, several diagnostic messages from various routines in the program are written.

Following these pages, the results of the calculation are output. Case identification and free-stream conditions are again specified. The iteration number, the reference length L , the reference area $SREF$, and the axial location of boundary-layer separation and reattachment are given. Following this information, tabulated listings of the body axial coordinate X/L , the body radial coordinate R/L , the body radius corrected for the discriminating streamline RDS/L , and the body radius corrected for boundary-layer displacement thickness and the discriminating streamline RC/L are printed. Also listed are values of pressure coefficient CP , local skin-friction coefficient CF , boundary-layer thickness DEL/L , boundary-layer displacement thickness $DEL*X/L$, boundary-layer momentum thickness $THETA/L$, and boundary-layer shape factor H . In addition, listings of the pressure drag coefficient CDP , skin-friction drag coefficient CDF , and total drag coefficient CDT are given. The drag values listed are based on the reference area $SREF$ and are the integrals of the pressure forces and/or skin-friction forces from the nose of the body to the specified X/L location. To obtain the nozzle boattail pressure drag coefficient, for example, it is necessary to subtract the value of the pressure drag coefficient at the start of the boattail from the value of the pressure drag coefficient at the nozzle exit or end of the boattail. This information is repeated for each iteration as specified in the input data.

If flow conditions at off-body points are calculated, the axial location X/L and radial location R/L of the off-body points are tabulated on the next page together with the ratio of axial velocity to free-stream velocity VX ,

the ratio of radial velocity to free-stream velocity V_R , and the ratio of local velocity to free-stream velocity V_T . Also tabulated are the local flow angle η in radians, the local Mach number M_L , and the local pressure coefficient C_P .

CONCLUDING REMARKS

A computer program has been written to compute the flow over axisymmetric nozzle configurations at subsonic speeds with and without separated flow. The computer algorithm is based on a patched viscous-inviscid interaction procedure. That is, solutions for the various regions of the flow are coupled together and solved iteratively to obtain a converged solution. The results of the present algorithm called DONBOL are in good agreement with experimental pressure distribution results for flow over nozzles with the jet exhaust simulated with solid bodies. The method substantially underpredicts the magnitude of the boattail drag when the jet exhaust flow is simulated with high-pressure air. This deficiency results because the present technique does not account for the effects of jet plume entrainment downstream of reattachment of the separated boundary layer on the flow over the nozzle. The method is limited to free-stream Mach numbers below that for which flow on the body of revolution reaches sonic speeds.

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APPENDIX

TABULATED LISTING OF COMPUTER PROGRAM

APPENDIX

C			SEPARATION.	*DON	66	
C				*DON	67	
C	2	51=55	INT(5) JET PLUME AND ENTRAINMENT OPTION =	*DON	68	
C			IF INT(5)=0 OMIT JET PLUME AND	*DON	69	
C			ENTRAINMENT CALCULATIONS.	*DON	70	
C			IF INT(5)=1 INCLUDE JET PLUME AND	*DON	71	
C			ENTRAINMENT CALCULATIONS.	*DON	72	
C	2	56=60	INT(6) X-ARRAY LOCATION OF NOZZLE EXIT.	*DON	73	
C				*DON	74	
C	2	61=65	INT(7) SMOOTHING PARAMETER =	*DON	75	
C			IF INT(7)=0 NO SMOOTHING.	*DON	76	
C			IF INT(7)=1 AERODYNAMIC BODY CONTOUR	*DON	77	
C			AND PRESSURE DISTRIBUTION ARE SMOOTHED	*DON	78	
C				*DON	79	
C	2	66=70	IPLAGS AN INTEGER WHICH IF GREATER THAN 0	*DON	80	
C			SPECIFIES THAT OFF BODY POINTS ARE TO	*DON	81	
C			BE CALCULATED.	*DON	82	
C				*DON	83	
C				*DON	84	
C	CARD	COL	NAME DESCRIPTION	*DON	85	
C				*DON	86	
C	3	1=10	MN FREE STREAM MACH NUMBER.	*DON	87	
C				*DON	88	
C	3	11=20	PT FREE STREAM TOTAL PRESSURE, PASCALS	*DON	89	
C				*DON	90	
C				*DON	92	
C	3	21=30	TY FREE STREAM TOTAL TEMPERATURE, KELVIN	*DON	91	
C	3	31=40	REFL REFERENCE LENGTH = FACTOR REQUIRED TO	*DON	93	
C			CONVERT INPUT VALUES OF X AND R TO	*DON	94	
C			METERS.	*DON	94A	
C				*DON	95	
C	3	41=50	BRFF REFERENCE AREA, SQ METERS	*DON	96	
C				*DON	97	
C	3	51=60	XSEPND THE X-COORDINATE OF THE SEPARATION	*DON	98	
C			LOCATION. REQUIRED IF ISEP=1.	*DON	99	
C				*DON	100	
C	4	1=10	XMJET MACH NUMBER OF JET AT NOZZLE EXIT.	*DON	101	
C				*DON	102	
C	4	11=20	PTJET JET TOTAL PRESSURE, PASCALS	*DON	103	
C				*DON	104	
C	4	21=30	TTJET JET TOTAL TEMPERATURE, KELVIN	*DON	105	
C				*DON	106	
C	4	31=40	RJET RADIUS OF NOZZLE EXIT	*DON	107	
C				*DON	108	
C	5	1=5	NN NUMBER OF COORDINATES FOR BODY	*DON	109	
C				*DON	110	
C	6	1=60	X(I),I=1,NN THE X-COORDINATES OF THE POINTS DEFIN-	*DON	111	
C			ING THE BODY. DATA IS INPUT WITH A	*DON	112	
C			FORMAT OF 6F10.6. MAY BE MORE THAN	*DON	113	
C			ONE CARD	*DON	114	
C				*DON	115	
C	7	1=60	R(I),I=1,NN THE R-COORDINATES OF THE POINTS DEFIN-	*DON	116	
C			ING THE BODY. DATA IS INPUT WITH A	*DON	117	
C			FORMAT OF 6F10.6. MAY BE MORE THAN	*DON	118	
C			ONE CARD	*DON	119	
C				*DON	120	
C				*DON	121	
C				*DON	122	
C				*DON	123	
C	IF IPLAGS GREATER THAN 0 THE FOLLOWING CARDS MUST BE INPUT				*DON	124
C				*DON	125	
C	CARD	COL	NAME DESCRIPTION	*DON	126	
C				*DON	127	
C	8	1=5	NN NUMBER OF OFF BODY POINTS	*DON	128	
C				*DON	129	
C	9	1=60	X(I),I=1,NN THE X-COORDINATES OF THE OFF BODY	*DON	130	

APPENDIX

C			POINTS, DATA IS INPUT WITH A FORMAT	*DON	131
C			OF 6F10.6. MAY BE MORE THAN ONE CARD.	*DON	132
C	10	1=60	R(I),I=1,NN THE R=COORDINATES OF THE OFF BODY	*DON	133
C			POINTS, DATA IS INPUT WITH A FORMAT	*DON	134
C			OF 6F10.6. MAY BE MORE THAN ONE CARD.	*DON	135
C				*DON	136
C			IF ISWITCH IS EQUAL TO 3 THE FOLLOWING CARD MUST BE INPUT	*DON	137
C				*DON	138
C				*DON	139
C			CARD COL NAME DESCRIPTION	*DON	140
C				*DON	141
C	11	1=60	CP(I),I=1,NN PRESSURE COEFFICIENT AT EACH X=	*DON	142
C			COORDINATE ON BODY, DATA IS INPUT	*DON	143
C			WITH A FORMAT OF 6F10.6. MAY BE MORE	*DON	144
C			THAN ONE CARD.	*DON	145
C				*DON	146
C			*****	*DON	147
C				DON	148
C			COMMON HEDR(8),ISWITCH,IPUNCH,ITERA,ITERMAX,IMACH,ISEP,INT(8),IFLADON	DON	149
C			1G5,FLG05,MN,APT,ATT,REFL,SREF,XSEPND,NN,BDN,ND(2),NT,NSIGA,IPRINT,	DON	150
C			2AMJET,PTJET,TTJET,RJET,RSTAR	DON	151
C			COMMON /SAVE/ VDUM(951)	DON	152
C			DIMENSION X(200), R(200), CP(200)	DON	153
C			INTEGER FLG05,BDN	DON	154
C			REAL MN	DON	155
C				DON	156
C			LINK=4LLINK	DON	157
C			BDN=1	DON	158
C			DO 10 I=1,200	DON	159
10			CP(I)=0.0	DON	160
20			READ (5,70) HEDR	DON	161
			IF (EOF(5)) 60,30	DON	162
30			READ (5,80) ISWITCH,IPRINT,IPUNCH,ITERA,ITERMAX,IMACH,ISEP,(INT(I)	DON	163
			1,I=2,7),IFLAG5	DON	164
			READ (5,90) MN,APT,ATT,REFL,SREF,XSEPND,AMJET,PTJET,TTJET,RJET	DON	165
			READ (5,80) NN	DON	166
			READ (5,90) (X(I),I=1,NN)	DON	167
			DO 40 IZ=1,2	DON	168
			IF (IZ.EQ.1.OR.ITERA.GT.0) READ (5,90) (R(I),I=1,NN)	DON	169
			WRITE (13) NN,(X(I),I=1,200)	DON	170
			WRITE (13) NN,(R(I),I=1,200)	DON	171
40			CONTINUE	DON	172
			IF ((ISWITCH.EQ.3).OR.(ITERA.GT.0)) READ (5,90) (CP(I),I=1,NN)	DON	173
			WRITE (13) (CP(I),I=1,200)	DON	174
			IF (ISWITCH.EQ.3) CALL OVERLAY (LINK,5,0)	DON	175
			IF ((ISWITCH.EQ.1).OR.(ISWITCH.EQ.2)) GO TO 50	DON	176
			GO TO 20	DON	177
50			IF (ITERA.GT.ITERMAX.AND.IFLAG5.EQ.0) GO TO 20	DON	178
			REWIND 3	DON	179
			REWIND 4	DON	180
			REWIND 9	DON	181
			REWIND 11	DON	182
			REWIND 12	DON	183
			REWIND 13	DON	184
			CALL OVERLAY (LINK,1,0)	DON	185
			CALL OVERLAY (LINK,2,0)	DON	186
			CALL OVERLAY (LINK,3,0)	DON	187
			IF (IFLAG5.GT.0.AND.ITERA.GE.(ITERMAX+1)) GO TO 20	DON	188
			CALL OVERLAY (LINK,5,0)	DON	189
			ITERA=ITERA+1	DON	190
			GO TO 50	DON	191
60			CONTINUE	DON	192
			STOP	DON	193
C				DON	194
C				DON	195
C				DON	196

APPENDIX

70	FORMAT (8A10)	DON 197
80	FORMAT (16I5)	DON 198
90	FORMAT (6F10,6)	DON 199
	END	DON 200
	OVERLAY(LINK,1,0)	
	PROGRAM ONE	ONE 1
C		ONE 2
C	*CONTROL FOR BASIC DATA AND FORM MATRIX	ONE 3
C		ONE 4
	COMMON HEDR(8),ISWITCH,IPUNCH,ITERA,ITERMAX,IMACH,ISEP,INT(8),IFLAONE	5
	1G5,FLG05,MN,APT,ATT,REFL,SREF,XSEPND,NN,BDN,ND(2),NT,NSIGA,IPRINT,ONE	6
	2AMJET,PTJET,TTJET,RJET,RSTAR	ONE 7
	COMMON /CL/ X1(200),Y1(200),X2(200),Y2(200),DELS(200),SINA(200),COONE	8
	ISA(200),XP(200),YP(200)	ONE 9
	COMMON /TL/ TX1(200),TY1(200),NG(200),TG(200),ALFA(200),RSDS(200),ONE	10
	1DALF(200),TEMP(1017)	ONE 11
	INTEGER FLG05,BDN	ONE 12
	REAL MN,NG	ONE 13
C		ONE 14
C	OUTPUT CASE CONTROL DATA	ONE 15
C		ONE 16
	FLG05=0	ONE 17
	IF (ITERA.GT.0) GO TO 10	ONE 18
	WRITE (6,250)	ONE 19
	WRITE (6,20) HEDR	ONE 20
	IF (IFLAG5.GT.0) WRITE (6,30)	ONE 21
	IF (IMACH.EQ.1) WRITE (6,40)	ONE 22
	IF (IMACH.EQ.2) WRITE (6,50)	ONE 23
	WRITE (6,60)	ONE 24
	IF (ISEP.EQ.0) WRITE (6,70)	ONE 25
	IF (ISEP.GT.0) WRITE (6,80)	ONE 26
	IF (ISEP.EQ.1) WRITE (6,90) XSEPND	ONE 27
	IF (ISEP.EQ.2) WRITE (6,100)	ONE 28
	IF (ISEP.EQ.3) WRITE (6,110)	ONE 29
	IF (ISEP.EQ.4) WRITE (6,120)	ONE 30
	IF (ISEP.EQ.5) WRITE (6,130)	ONE 31
	IF (ISEP.GE.2) WRITE (6,140) INT(3)	ONE 32
	IF (ISEP.GE.2) WRITE (6,150) INT(4)	ONE 33
	IF (INT(5).GT.0) WRITE (6,160)	ONE 34
	WRITE (6,170) INT(6)	ONE 35
	IF (INT(7).GT.0) WRITE (6,180)	ONE 36
	WRITE (6,190)	ONE 37
	G=1.4	ONE 38
	G1=(G-1.)/2.	ONE 39
	G2=G/(G-1)	ONE 40
	RG=286.96	ONE 41
	PO=APT/(1.+G1*MN**2)**G2	ONE 42
	TO=ATT/(1.+G1*MN**2)	ONE 43
	RHO=PO/(TO*RG)	ONE 44
	XMU=1.458/10**6*TO**1.5/(TO+110.33)	ONE 45
	RN=RHO*MN**8QRT(G*RG*TO)/XMU	ONE 46
	RN=RN/10.**6	ONE 47
	WRITE (6,200)	ONE 48
	WRITE (6,210) MN,APT,ATT	ONE 49
	WRITE (6,220) RN	ONE 50
	IF (INT(5).GT.0) WRITE (6,240)	ONE 51
	IF (INT(5).GT.0) WRITE (6,210) AMJET,PTJET,TTJET	ONE 52
	XNPR=PTJET/PO	ONE 53
	IF (INT(5).GT.0) WRITE (6,230) XNPR	ONE 54
	IF (IPRINT.GT.0) WRITE (6,250)	ONE 55
C		ONE 56
C	SETUP FOR UNIFORM FLOW	ONE 57
C		ONE 58
10	CALL BASIC1	ONE 59
	NSIGA=1	ONE 60
	REWIND 4	ONE 61

APPENDIX

	CALL MATRIX	ONE	62
C		ONE	63
C		ONE	64
C		ONE	65
20	FORMAT (10X,64HDOONBOL == AN AXISYMMETRIC INVISCID/VISCID INTERACONE	ONE	66
	CTION PROGRAM//16X,52HBY LAWRENCE E. PUTNAM, NASA, LANGLEY RESEARONE	ONE	67
	2H CENTER//2X,13HCASE TITLE = ,8410//13X,29H***** CASE CONTROL DATAONE	ONE	68
	3 *****//)	ONE	69
30	FORMAT (13X,15H0FF=BODY POINTS)	ONE	70
40	FORMAT (13X,35HGOETHERT COMPRESSIBILITY CORRECTION)	ONE	71
50	FORMAT (13X,36HLABRUJERE COMPRESSIBILITY CORRECTION)	ONE	72
60	FORMAT (13X,48HMODIFIED RESHOTKO TUCKER BOUNDARY LAYER SOLUTION)	ONE	73
70	FORMAT (13X,29HSEPARATED FLOW MODEL NOT USED)	ONE	74
80	FORMAT (13X,64HPRESZ MODIFIED CONTROL VOLUME DISCRIMINATING STREAMONE	ONE	75
	LINE SOLUTION)	ONE	76
90	FORMAT (13X,46HSEPARATION LOCATION SPECIFIED BY USER AT X/L =,F10,ONE	ONE	77
	16)	ONE	78
100	FORMAT (13X,49HPRESZ CONTROL VOLUME SEPARATION LOCATION CRITERIA)	ONE	79
110	FORMAT (13X,40HGOLDSCHMIED SEPARATION LOCATION CRITERIA)	ONE	80
120	FORMAT (13X,42HMODIFIED PAGE SEPARATION LOCATION CRITERIA)	ONE	81
130	FORMAT (13X,38HSTRATFORD SEPARATION LOCATION CRITERIA)	ONE	82
140	FORMAT (13X,34HSTART SEARCH FOR SEPARATION AT I =,I4)	ONE	83
150	FORMAT (13X,32HEND SEARCH FOR SEPARATION AT I =,I4)	ONE	84
160	FORMAT (13X,29HJET EXHAUST PLUME CALCULATION)	ONE	85
170	FORMAT (13X,18HNOZZLE EXIT AT I =,I4)	ONE	86
180	FORMAT (13X,26HSMOOTH AERODYNAMIC CONTOUR)	ONE	87
190	FORMAT (13X,28HSMOOTH PRESSURE DISTRIBUTION)	ONE	88
200	FORMAT (1H0,12X,22HFREE STREAM CONDITIONS)	ONE	89
210	FORMAT (20X,20HMACH NUMBER =,F12,3/20X,20HTOTAL PRESSURE	ONE	90
	1 =,F12,3,8H PASCALS/20X,20HTOTAL TEMPERATURE =,F12,3,7H KELVIN)	ONE	91
220	FORMAT (20X,20HREYNOLDS NUMBER =,F12,3,18H MILLION PER METER)	ONE	92
230	FORMAT (20X,20HNPR =,F12,3)	ONE	93
240	FORMAT (1H0,12X,37HJET EXHAUST CONDITIONS AT NOZZLE EXIT)	ONE	94
250	FORMAT (1H1)	ONE	95
	END	ONE	96-
	SUBROUTINE BASIC1	BAS	1
C		BAS	2
C	* READ DATA AND SETUP FOR UNIFORM FLOW	BAS	3
C		BAS	4
	COMMON HEDR(8),ISWITCH,IPUNCH,ITERA,ITERMAX,IMACH,ISEP,INT(8),IFLABAS	BAS	5
	1G5,FLG05,MN,APT,ATT,REFL,SREF,XSEPND,NN,BDN,ND(2),NT,NSIGA,IPRINT,BAS	BAS	6
	2AMJET,PTJET,TTJET,RJET,RSTAR	BAS	7
	COMMON /CL/ X1(200),Y1(200),X2(200),Y2(200),DELS(200),SINA(200),COBAS	BAS	8
	18A(200),XP(200),YP(200)	BAS	9
	COMMON /TL/ TX1(200),TY1(200),NG(200),TG(200),ALFA(200),RBD8(200),BAS	BAS	10
	1DALF(200),TEMP(1017)	BAS	11
	INTEGER FLG05,BDN	BAS	12
	REAL MN,NG	BAS	13
C		BAS	14
	REWIND 13	BAS	15
	NT=0	BAS	16
	K=0	BAS	17
	K2=1	BAS	18
	IF (ITERA,GT,ITERMAX) FLG05=IFLAG5	BAS	19
	IF (FLG05,NE,0) K2=2	BAS	20
C		BAS	21
C	* MAJOR LOOP * NO. OF BODIES + OFF BODY POINTS	BAS	22
C		BAS	23
	DO 130 L=1,K2	BAS	24
	IF (FLG05,GT,0,AND,L,GT,1) GO TO 10	BAS	25
	ND(L)=NN	BAS	26
	M=NN=1	BAS	27
	READ (13) BLANK	BAS	28
	READ (13) BLANK	BAS	29
	READ (13) NN,(TX1(I),I=1,NN)	BAS	30
	READ (13) NN,(TY1(I),I=1,NN)	BAS	31

APPENDIX

	GO TO 20	BAS 32
10	CONTINUE	BAS 33
C		BAS 34
C	* BASIC DATA CALC. AND PRINT (UNTRANSFORMED COORDINATES)	BAS 35
C		BAS 36
	BDN=0	BAS 37
	READ (5,150) ND(2)	BAS 38
	NN=ND(2)	BAS 39
	READ (5,160) (TX1(I),I=1,NN)	BAS 40
	READ (5,160) (TY1(I),I=1,NN)	BAS 41
	GO TO 50	BAS 42
20	SUMS=0.0	BAS 43
	DO 30 I=1,M	BAS 44
	T1=TX1(I+1)-TX1(I)	BAS 45
	T2=TY1(I+1)-TY1(I)	BAS 46
	X2(I)=(TX1(I+1)+TX1(I))/2.	BAS 47
	Y2(I)=(TY1(I+1)+TY1(I))/2.	BAS 48
	DELS(I)=SQRT(T1*T1+T2*T2)	BAS 49
	SUMS=SUMS+DELS(I)	BAS 50
	RSDS(I)=SUMS	BAS 51
30	ALFA(I)=ATAN2(T2,T1)	BAS 52
	MA=M-1	BAS 53
	DO 40 I=1,MA	BAS 54
40	DALF(I)=(ALFA(I+1)-ALFA(I))*57.2957795	BAS 55
50	CONTINUE	BAS 56
	IF (MN) 60,80,60	BAS 57
60	SRM=SQRT(1.-MN*MN)	BAS 58
	DO 70 I=1,NN	BAS 59
70	TX1(I)=TX1(I)/SRM	BAS 60
C		BAS 61
C	* SHIFT X1 AND Y1 TO COMMON /CL/	BAS 62
C		BAS 63
80	IF (BDN) 110,90,110	BAS 64
90	DO 100 I=1,NN	BAS 65
	XP(I)=TX1(I)	BAS 66
100	YP(I)=TY1(I)	BAS 67
	WRITE (12) (XP(I),I=1,NN),(YP(I),I=1,NN)	BAS 68
	GO TO 130	BAS 69
110	DO 120 I=1,NN	BAS 70
	K=K+1	BAS 71
	X1(K)=TX1(I)	BAS 72
120	Y1(K)=TY1(I)	BAS 73
	NT=NT+M	BAS 74
130	CONTINUE	BAS 75
	REWIND 13	BAS 76
C		BAS 77
C	* CALC. PARAMETERS WITH TRANSFORMED COORDINATES AND	BAS 78
C	MACH NO. ADJUSTMENT	BAS 79
C		BAS 80
	J1=0	BAS 81
	N1=ND(1)=1	BAS 82
	DO 140 J=1,N1	BAS 83
	J1=J1+1	BAS 84
	T1=X1(J1+1)-X1(J1)	BAS 85
	T2=Y1(J1+1)-Y1(J1)	BAS 86
	X2(J)=(X1(J1+1)+X1(J1))/2.	BAS 87
	Y2(J)=(Y1(J1+1)+Y1(J1))/2.	BAS 88
	DELS(J)=SQRT(T1*T1+T2*T2)	BAS 89
	COSA(J)=T1/DELS(J)	BAS 90
140	SINA(J)=T2/DELS(J)	BAS 91
	J1=J1+1	BAS 92
C		BAS 93
C	* SAVE PARAMETERS	BAS 94
C		BAS 95
	WRITE (12) (X1(I),I=1,J1),(Y1(I),I=1,J1),(X2(I),I=1,NT),(Y2(I),I=1,NT),	BAS 96
	(DELS(I),I=1,NT)	BAS 97

APPENDIX

	REWIND 12	BAS 98
C		BAS 99
C	* SAVE SINA AND COSA ON TAPE 4 FOR CALC. OF MATRIX	BAS 100
C	SOLUTION (RIGHT HAND MATRIX)	BAS 101
	WRITE (4) (SINA(I),I=1,NT),(COSA(I),I=1,NT)	BAS 102
	RETURN	BAS 103
C		BAS 104
C		BAS 105
150	FORMAT (2I5)	BAS 106
160	FORMAT (6F10,0)	BAS 107
	END	BAS 108
	SUBROUTINE MATRIX	MAT 1
C		MAT 2
C	* COMPUTE MATRIX A,B,Z OR X,Y,Z	MAT 3
C		MAT 4
	COMMON HEDR(8),ISWITCH,IPUNCH,ITERA,ITERMAX,IMACH,ISEP,INT(8),IPLAMAT	MAT 5
	1G5,FLG05,MN,APT,ATT,REFL,SREF,XSEPND,NN,BDN,ND(2),NT,NSIGA,IPRINT,MAT	MAT 6
	2AMJET,PTJET,TTJET,RJET,RSTAR	MAT 7
	COMMON /CL/ X1(200),Y1(200),X2(200),Y2(200),DELS(200),SINA(200),COMAT	MAT 8
	1SA(200),XP(200),YP(200)	MAT 9
	COMMON /TL/ A(200),B(200),AX(200),AY(200),AZ(200),CX(200),CY(200),MAT	MAT 10
	1CZ(200),AXV(200),AYV(200),VN(200,1),VT(200,1),BON,YZERO,IAC,II,JJ,MAT	MAT 11
	2J1,SJ,DS,DX,DY,NI,XJ,YJ,XK,EK,EKK,KK	MAT 12
	INTEGER FLG05,BDN	MAT 13
	REAL MN	MAT 14
C		MAT 15
C	* INITIALIZE	MAT 16
	L1=NT	MAT 17
	BDN=0,0	MAT 18
	YZERO=0,0	MAT 19
	IAC=1	MAT 20
10	DO 20 I=1,NT	MAT 21
	J=1	MAT 22
	VN(I,J)=0,	MAT 23
20	VT(I,J)=0,	MAT 24
C		MAT 25
C	* I MIDPOINT LOOP	MAT 26
C		MAT 27
	DO 70 I=1,L1	MAT 28
	II=I	MAT 29
C		MAT 30
C	J1 IS THE COORDINATE COUNTER	MAT 31
C		MAT 32
	J1=0	MAT 33
	N1=ND(1)=1	MAT 34
	KK=1	MAT 35
	DO 30 J=1,N1	MAT 36
	JJ=J	MAT 37
	J1=J1+1	MAT 38
C		MAT 39
C	* COMPUTE X,Y,Z MATRICES	MAT 40
C		MAT 41
	CALL XYZ	MAT 42
30	CONTINUE	MAT 43
	J1=J1+1	MAT 44
	IF (BON) 40,50,40	MAT 45
C		MAT 46
C	* SAVE X,Y,Z ON TAPE *OFF BODY POINTS	MAT 47
C		MAT 48
40	WRITE (9) (AX(J),J=1,NT),(AY(J),J=1,NT),(AZ(J),J=1,NT)	MAT 49
	GO TO 70	MAT 50
C		MAT 51
C	* SAVE A,B,Z ON TAPE *ON BODY	MAT 52
C		MAT 53
50	DO 60 J=1,NT	MAT 54
	A(J)=AX(J)*SINA(I)+AY(J)*COSA(I)	MAT 55

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60	B(J)=AX(J)*COSA(I)+AY(J)*SINA(I)	MAT	56
	WRITE (9) (A(J),J=1,NT),(B(J),J=1,NT),(AZ(J),J=1,NT)	MAT	57
70	CONTINUE	MAT	58
C		MAT	59
C	* TEST IF OFF BODY COMPLETED	MAT	60
C	* TEST IF OFF BODY	MAT	61
C		MAT	62
	IF (FLG05,EQ,0,OR,B0N,NE,0.) GO TO 90	MAT	63
C		MAT	64
C	* INITIAL FOR OFF BODY * THEN RE=ENTER I,J LOOPS	MAT	65
	B0N=1,	MAT	66
	L1=ND(2)	MAT	67
	DO 80 I=1,L1	MAT	68
	X2(I)=XP(I)	MAT	69
80	Y2(I)=YP(I)	MAT	70
	GO TO 10	MAT	71
90	REWIND 9	MAT	72
	REWIND 4	MAT	73
	RETURN	MAT	74
	END	MAT	75
	SUBROUTINE XYZ	MAT	76
C		XYZ	1
C	* CONTROL FOR X,Y,Z MATRICES COMPUTATION	XYZ	2
C		XYZ	3
	COMMON HEDR(8),ISWITCH,IPUNCH,ITERA,ITERMAX,IMACH,ISEP,INT(8),IFLAXYZ	XYZ	4
	1G5,FLG05,MN,APT,ATT,REFL,SREF,XSEPND,NN,B0N,ND(2),NT,NSIGA,IPRINT,XYZ	XYZ	5
	2AMJET,PTJET,TTJET,RJET,RSTAR	XYZ	6
	COMMON /CL/ X1(200),Y1(200),X2(200),Y2(200),DELS(200),SINA(200),COXYZ	XYZ	7
	1BA(200),XP(200),YP(200)	XYZ	8
	COMMON /TL/ A(200),B(200),AX(200),AY(200),AZ(200),CX(200),CY(200),XYZ	XYZ	9
	1CZ(200),AXV(200),AYV(200),VN(200,1),VT(200,1),B0N,YZERO,IAC,I,J,J1XYZ	XYZ	10
	2,SJ,DS,DX,DY,NI,XJ,YJ,XK,EK,EKK,K	XYZ	11
	INTEGER FLG05,B0N	XYZ	12
	REAL MN	XYZ	13
C		XYZ	14
	IF (B0N) 50,10,50	XYZ	15
10	IF (J=I) 60,20,60	XYZ	16
C		XYZ	17
C	* J EQUAL I PATH	XYZ	18
C		XYZ	19
20	T1=.5*DELS(J)	XYZ	20
	SJ=T1/Y2(J)	XYZ	21
	IF (SJ=.08) 30,30,40	XYZ	22
30	CALL XYZ1	XYZ	23
	GO TO 190	XYZ	24
40	SJ=.08	XYZ	25
	CALL XYZ1	XYZ	26
	NI=33	XYZ	27
	T2=.08*Y2(J)	XYZ	28
	DS=(T1-T2)/32,	XYZ	29
	DX=DS*COSA(J)	XYZ	30
	DY=DS*SINA(J)	XYZ	31
	XJ=X2(J)+T2*COSA(J)-DX	XYZ	32
	YJ=Y2(J)+T2*SINA(J)-DY	XYZ	33
	CALL XYZ2	XYZ	34
	GO TO 180	XYZ	35
C		XYZ	36
C	* INITIAL Y COORDINATE MID=POINT FOR ZERO TEST	XYZ	37
C		XYZ	38
50	YZERO=Y2(I)=.000001	XYZ	39
C		XYZ	40
C	* J NOT EQUAL I PATH	XYZ	41
C	* COMPUTE MINIMUM DISTANCE TO I MIDPOINT	XYZ	42
C		XYZ	43
60	D1=(X2(I)-X1(J1))**2+(Y2(I)-Y1(J1))**2	XYZ	44
		XYZ	45

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D2=(X2(I)-X2(J))**2+(Y2(I)-Y2(J))**2
D3=(X2(I)-X1(J1+1))**2+(Y2(I)-Y1(J1+1))**2
IF (D1=D2) 80,80,70
70 IF (D2=D3) 100,100,90
80 IF (D1=D3) 110,110,90
90 DM=SQRT(D3)
GO TO 120
100 DM=SQRT(D2)
GO TO 120
110 DM=SQRT(D1)
C
C      * COMPUTE NO. OF INTERVALS(NI) AND DELTA S (DS)
C      FOR SIMPSON RULE INTEGRATION
C
120 IF (DM.EQ.0,0) GO TO 150
NI=8.*DELS(J)/DM+.9
IF (NI) 130,130,140
130 NI=3
DS=DELS(J)/2.
GO TO 170
140 NI=NI+NI
IF (NI=128) 160,150,150
150 NI=129
DS=DELS(J)/128.
GO TO 170
160 XNI=NI
NS=DELS(J)/XNI
NI=NI+1
170 DX=DS*COSA(J)
DY=DS*SINA(J)
180 XJ=X1(J1)-DX
YJ=Y1(J1)-DY
CALL XYZ2
190 RETURN
END
SUBROUTINE XYZ1
C
C      * COMPUTE X,Y,Z MATRICES FOR SJ LESS THAN OR EQUAL .08
C
COMMON HEDR(8),ISWITCH,IPUNCH,ITERA,ITERMAX,IMACH,ISEP,INT(8),IFLAXY1
105,FLG05,MN,APT,ATT,REFL,8REF,XSEPND,NN,BDN,ND(2),NT,NSIGA,IPRINT,XY1
ZAMJET,PTJET,TTJET,RJET,RSTAR
COMMON /CL/ X1(200),Y1(200),X2(200),Y2(200),DELS(200),SINA(200),COXY1
18A(200),XP(200),YP(200)
COMMON /TL/ A(200),B(200),AX(200),AY(200),AZ(200),CX(200),CY(200),XY1
1CZ(200),AXV(200),AYV(200),VN(200,1),VT(200,1),BON,YZERO,IAC,I,J,J1XY1
Z,8J,DS,DX,DY,NI,XJ,YJ,XK,EK,EKK,K
INTEGER FLG05,BDN
REAL MN
C
C      * INITIALIZE
C
T1=8J*8J
T2=ALOG(8J/8.)
T3=SINA(J)*SINA(J)
T4=T2+T3
T5=.6666666667*T3
T6=T5*T3
T7=8J*8J
T8=T7+T7
T9=.6.2831853*COSA(J)
T10=.6.2831853*SINA(J)
T11=T1*8J
C
C      * AXIS FLOW
C

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10  AX(J)=T10+SINA(J)*COSA(J)*(T7+(T4+2.16666667)*T11/12.)          XY1  32
    AX(J)=T10+SINA(J)*COSA(J)*(T7+(T4+2.16666667)*T11/12.)          XY1  33
    AY(J)=T7*T4-T9=(1.+T2-T3-T6)*T11/8.                               XY1  34
    T12=T1+T1                                                           XY1  35
    AZ(J)=Y2(J)*T8*(1.-T2+T1*(2.-T12+3.*T2*(1.+T12))/144.)          XY1  36
    RETURN                                                                XY1  37
    END                                                                    XY1  3A=
    SUBROUTINE XYZ2                                                       XY2  1
C                                                                    XY2  2
C          * COMPUTE X,Y,Z MATRICES USING SIMPSON RULE INTEGRATION    XY2  3
C                                                                    XY2  4
    COMMON HEDR(8),ISWITCH,IPUNCH,ITERA,ITERMAX,IMACH,ISEP,INT(8),IFLAXY2  5
    1G5,FLG05,MN,APT,ATT,REFL,SREF,XSEPND,NN,BDN,ND(2),NT,NSIGA,IPRINT,XY2  6
    2AMJET,PTJET,TTJET,RJET,RSTAR                                       XY2  7
    COMMON /CL/ X1(200),Y1(200),X2(200),Y2(200),DELS(200),SINA(200),COXY2  8
    1SA(200),XP(200),YP(200)                                             XY2  9
    COMMON /TL/ A(200),B(200),AX(200),AY(200),AZ(200),CX(200),CY(200),XY2  10
    1CZ(200),AXV(200),AYV(200),VN(200,1),VT(200,1),BON,YZERO,IAC,I,J,J1XY2  11
    2,SJ,DS,DX,DY,NI,XJ,YJ,XK,EK,EKK,K                                  XY2  12
    INTEGER FLG05,BDN                                                    XY2  13
    REAL MN                                                                XY2  14
C                                                                    XY2  15
C          * INITIALIZE                                                XY2  16
C                                                                    XY2  17
10  S2=.66666667*DS                                                       XY2  1A
    S4=S2+S2                                                               XY2  19
    T1=Y2(I)*Y2(I)                                                         XY2  20
C                                                                    XY2  21
C          * NO. OF INTERVAL LOOP                                       XY2  22
C                                                                    XY2  23
    DO 130 I8=1,NI                                                         XY2  24
    XJ=XJ+DX                                                                XY2  25
    YJ=YJ+DY                                                                XY2  26
    T2=YJ*YJ                                                                XY2  27
    T3=X2(I)-XJ                                                            XY2  2A
    T4=T3*T3                                                                XY2  29
    T5=(Y2(I)+YJ)**2                                                       XY2  30
    T6=T4+T5                                                                XY2  31
    T7=SQRT(T6)                                                            XY2  32
    T8=T2+T4                                                                XY2  33
    T9=(Y2(I)-YJ)**2                                                       XY2  34
    T10=T9+T4                                                               XY2  35
C                                                                    XY2  36
C          * COMPUTE ELLIPIC INTEGRAL                                       XY2  37
C                                                                    XY2  38
    XK=4.*YJ*Y2(I)/T6                                                       XY2  39
    CALL ELIP                                                                XY2  40
C                                                                    XY2  41
C          * AXIS FLOW                                                    XY2  42
C                                                                    XY2  43
    T11=YJ/T7                                                                XY2  44
    IF (Y2(I),EQ,0.) GO TO 20                                               XY2  45
    T12=YJ/Y2(I)                                                            XY2  46
    FV2=(EKK+EKK*(T1-T8)/T10)/T7                                           XY2  47
    FV3=Y2(I)/T10*T3/T7+EKK                                               XY2  4A
    F1=FV3*T12                                                            XY2  49
    F2=FV2*T12                                                            XY2  50
    FV4=FV2*T3/Y2(I)                                                       XY2  51
    GO TO 30                                                                XY2  52
20  FV2=0.                                                                XY2  53
    FV3=0.                                                                XY2  54
    FV4=0.                                                                XY2  55
    F2=0.                                                                XY2  56
    F1=T11/T10*T3+EKK                                                       XY2  57
30  F3=T11+EKK                                                            XY2  58
C                                                                    XY2  59

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APPENDIX

C	* SIMPSON RULE INTEGRATION	XY2	60
C		XY2	61
	IF (IS=1) 40,40,50	XY2	62
C		XY2	63
C	* FIRST PASS	XY2	64
C		XY2	65
40	AXS=F1	XY2	66
	AYS=F2	XY2	67
	AZS=F3	XY2	68
	IA=0	XY2	69
	GO TO 120	XY2	70
50	IF (IS=NI) 60,90,60	XY2	71
60	IF (IA) 80,70,80	XY2	72
C		XY2	73
C	* EVEN PASS	XY2	74
C		XY2	75
70	AXS=AXS+4,*F1	XY2	76
	AYS=AYS+4,*F2	XY2	77
	AZS=AZS+4,*F3	XY2	78
	IA=1	XY2	79
	GO TO 120	XY2	80
C		XY2	81
C	* ODD PASS	XY2	82
C		XY2	83
80	AXS=AXS+F1+F1	XY2	84
	AYS=AYS+F2+F2	XY2	85
	AZS=AZS+F3+F3	XY2	86
	IA=0	XY2	87
	GO TO 120	XY2	88
C		XY2	89
C	* LAST PASS	XY2	90
C		XY2	91
90	IF (J=I) 110,100,110	XY2	92
100	IF (BON,NE,0,0) GO TO 110	XY2	93
	AX(J)=AX(J)+84*(AXS+F1)	XY2	94
	AY(J)=AY(J)+82*(AYS+F2)	XY2	95
	AZ(J)=AZ(J)+84*(AZS+F3)	XY2	96
	GO TO 120	XY2	97
110	AX(J)=-84*(AXS+F1)	XY2	98
	AY(J)=-82*(AYS+F2)	XY2	99
	AZ(J)=84*(AZS+F3)	XY2	100
120	CONTINUE	XY2	101
130	CONTINUE	XY2	102
	RETURN	XY2	103
	END	XY2	104
	SUBROUTINE ELIP	ELI	1
C		ELI	2
C	* HASTINGS APPROXIMATION FOR ELLIPTIC INTEGRALS	ELI	3
C		ELI	4
	COMMON /TL/ A(200),B(200),AX(200),AY(200),AZ(200),CX(200),CY(200),	ELI	5
	1CZ(200),AXV(200),AYV(200),VN(200,1),VT(200,1),BON,YZERO,IAC,I,J,J1	ELI	6
	2,BJ,DS,DX,DY,NI,XJ,YJ,XK,EKK,EKK,K	ELI	7
C		ELI	8
10	ETA=1,-XK	ELI	9
	IF (ETA) 20,20,30	ELI	10
20	WRITE (6,40) ETA	ELI	11
	CALL EXIT	ELI	12
30	ELN=ALOG(ETA)	ELI	13
	EKK=1,38629436112+ETA*(0.09666344259+ETA*(0.03590092383+ETA*(0.037	ELI	14
	142563713+ETA*0.01451196212)))=ELN*(0.5+ETA*(0.12498593597+ETA*(0.0	ELI	15
	26880248576+ETA*(0.03328355346+ETA*0.00441787012)))	ELI	16
	EKK=1,+ETA*(0.44325141463+ETA*(0.06260601220+ETA*(0.04757383546+ET	ELI	17
	1A*0.01736506451)))=ELN*(ETA*(0.24998368310+ETA*(0.09200180037+ETA*	ELI	18
	2(0.04069697526+ETA*0.00526449639)))	ELI	19
	RETURN	ELI	20
C		ELI	21

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40	FORMAT (1M136H,27H* ERROR IN SUBROUTINE ELIP ,ETA=F15.8)	ELI	22
	END	ELI	23=
	OVERLAY(LINK,2,0)		
	PROGRAM TWO	TWO	1
C		TWO	2
C	* COMPUTE SOURCE DENSITY SIGMA BY SIEDEL ITERATION	TWO	3
C		TWO	4
	COMMON HEDR(8),ISWITCH,IPUNCH,ITERA,ITERMAX,IMACH,ISEP,INT(8),IFLATWO	TWO	5
	1G5,FLG05,MN,APT,ATT,REFL,SREF,XSEPND,NN,BDN,ND(2),NT,NSIGA,IPRINT,	TWO	6
	2AMJET,PTJET,TTJET,RJET,RSTAR	TWO	7
	COMMON /C2/ A(200),R(200),NSIG,IT	TWO	8
	DIMENSION ASIG(200,1)	TWO	9
	INTEGER FLG05,BDN	TWO	10
	REAL MN	TWO	11
C		TWO	12
C	* AXIS FLOW	TWO	13
C		TWO	14
	READ (4) (R(I),I=1,NT)	TWO	15
10	REWIND 4	TWO	16
	IT=9	TWO	17
	NSIG=NSIGA	TWO	18
C		TWO	19
C	* SOLVE SIMULTANEOUS EQUATIONS FOR SIGMAS	TWO	20
C		TWO	21
	CALL MISNA2 (ASIG)	TWO	22
	REWIND 9	TWO	23
C		TWO	24
C	* WRITE SIGMAS ON TAPE 3	TWO	25
C		TWO	26
	WRITE (3) (ASIG(I,1),I=1,NT)	TWO	27
	END	TWO	28=
	SUBROUTINE MISNA2 (SIG)	MIS	1
C		MIS	2
C	* SOLVE LINEAR SIMULTANEOUS EQUATIONS BY SEIDEL ITERATION	MIS	3
C		MIS	4
	COMMON HEDR(8),ISWITCH,IPUNCH,ITERA,ITERMAX,IMACH,ISEP,INT(8),IFLAMIS	MIS	5
	1G5,FLG05,MN,APT,ATT,REFL,SREF,XSEPND,NN,BDN,ND(2),NT,NSIGA,IPRINT,	MIS	6
	2AMJET,PTJET,TTJET,RJET,RSTAR	MIS	7
	COMMON /C2/ A(200),R(200),NSIG,IT	MIS	8
	DIMENSION SIG(200,1), KFLAG(1), DSIG1(1), DSIG(200,1)	MIS	9
	INTEGER FLG05,BDN	MIS	10
	REAL MN	MIS	11
C		MIS	12
C	* INITIALIZE	MIS	13
C		MIS	14
10	NTU=0	MIS	15
	ITER=0	MIS	16
	NCONV=0	MIS	17
	DO 20 J=1,NSIG	MIS	18
	KFLAG(J)=0	MIS	19
	DO 20 I=1,NT	MIS	20
20	SIG(I,J)=0.0	MIS	21
30	DO 40 I=1,NSIG	MIS	22
40	DSIG1(I)=0.0	MIS	23
C		MIS	24
C	* COMPUTE SIGMA AND DELTA SIGMA	MIS	25
C		MIS	26
	DO 100 I=1,NT	MIS	27
	IF (NTU=3) 50,60,70	MIS	28
C		MIS	29
C	* PLACE A IN LEFT SIDE MATRIX	MIS	30
C		MIS	31
30	READ (9) (A(L),L=1,NT)	MIS	32
C		MIS	33
C	* SAVE LEFT SIDE MATRIX	MIS	34
C		MIS	35

APPENDIX

	WRITE (3) (A(L),L=1,NT)	MIS 36
	WRITE (11) (A(L),L=1,NT)	MIS 37
	GO TO 80	MIS 38
C		MIS 39
C	* READ LEFT SIDE MATRIX	MIS 40
C		MIS 41
60	READ (3) (A(L),L=1,NT)	MIS 42
	GO TO 80	MIS 43
70	READ (11) (A(L),L=1,NT)	MIS 44
80	DO 100 J=1,NSIG	MIS 45
	IF (KFLAG(J).NE.0) GO TO 100	MIS 46
	SUM=0.0	MIS 47
	DO 90 L=1,NT	MIS 48
90	SUM=SUM+A(L)*SIG(L,J)	MIS 49
	DSIG(I,J)=(R(I)-SUM)/A(I)	MIS 50
	SIG(I,J)=SIG(I,J)+DSIG(I,J)	MIS 51
	IF (ABS(DSIG(I,J)).GT.DSIG1(J)) DSIG1(J)=ABS(DSIG(I,J))	MIS 52
100	CONTINUE	MIS 53
C		MIS 54
C	* TEST FOR SOLUTION	MIS 55
C		MIS 56
	REWIND 3	MIS 57
	REWIND 11	MIS 58
	ITER=ITER+1	MIS 59
	DO 110 J=1,NSIG	MIS 60
	IF (KFLAG(J).NE.0) GO TO 110	MIS 61
	IF (DSIG1(J).GE.1.E=6) GO TO 110	MIS 62
	KFLAG(J)=ITER	MIS 63
	NCONV=NCONV+1	MIS 64
	IF (NCONV.EQ.NSIG) GO TO 130	MIS 65
110	CONTINUE	MIS 66
	IF (ITER.EQ.100) GO TO 130	MIS 67
	IF (NTU.EQ.3) GO TO 120	MIS 68
	NTU=3	MIS 69
	GO TO 30	MIS 70
120	NTU=11	MIS 71
	GO TO 30	MIS 72
C		MIS 73
C	* PRINT NO. OF ITERATIONS	MIS 74
C		MIS 75
130	DO 150 J=1,NSIG	MIS 76
	IF (KFLAG(J).NE.0) GO TO 140	MIS 77
	WRITE (6,160) ITERA	MIS 78
	GO TO 150	MIS 79
140	WRITE (6,170) ITERA,KFLAG(J)	MIS 80
150	CONTINUE	MIS 81
	RETURN	MIS 82
C		MIS 83
C		MIS 84
160	FORMAT (1H0,10HFOR ITERA=,I3,46H NO CONVERGENCE IN MISNA2 AFTER 10MIS 85	
	10 ITERATIONS)	MIS 86
170	FORMAT (1H0,10HFOR ITERA=,I3,I5,46H ITERATIONS REQUIRED FOR CONVERMIS 87	
	IGENCE IN MISNA2)	MIS 88
	END	MIS 89
	OVERLAY(LINK,3,0)	
	PROGRAM THREE	THR 1
C		THR 2
C	* COMPUTE VELOCITY COMPONENTS AND PRINT	THR 3
C		THR 4
	COMMON HEDR(8),ISWITCH,IPUNCH,ITERA,ITERMAX,IMACH,ISEP,INT(6),IPLATHR 5	
	1G5,FLG05,MN,APT,ATT,REPL,8REF,XSEPND,NN,BDN,ND(2),NT,NSIGA,IPRINT,THR 6	
	2AMJET,PTJET,TTJET,RJET,RSTAR	THR 7
	COMMON /C4/ X1(200),Y1(200),X2(200),Y2(200),DELS(200),SINA(200),COTHR 8	
	ISA(200),XP(200),YP(200)	THR 9
	COMMON /TC/ RB(200,2),SIG(200,1),A(200),B(200),Z(200),PHI(200,1),XTHR 10	
	IN(200,1),T(200,1),TS(200,1),NSIG,NP,NI,SUMV,SUMM(4)	THR 11

APPENDIX

	INTEGER FLG05,BDN	THR 12
	REAL MN	THR 13
C	REWIND 3	THR 14
	IF (FLG05,EQ,0) GO TO 10	THR 15
C		THR 16
C	* READ OFF=BODY XP,YP	THR 17
C		THR 18
	NP=ND(2)	THR 19
	READ (12) (XP(I),I=1,NP),(YP(I),I=1,NP)	THR 20
C		THR 21
C	* READ X1,Y1,X2,Y2,DELS WITH MACH NO. ADJUSTMENT IF ANY	THR 22
C		THR 23
C		THR 24
10	NI=NT+1	THR 25
	READ (12) (X1(I),I=1,NI),(Y1(I),I=1,NI),(X2(I),I=1,NT),(Y2(I),I=1,	THR 26
	INT),(DELS(I),I=1,NT)	THR 27
C		THR 28
C	* READ SINA,COSA,NO,TO,.	THR 29
C		THR 30
	READ (4) (A(I),I=1,NT),(B(I),I=1,NT)	THR 31
	SUMV=0.0	THR 32
	DO 20 I=1,NT	THR 33
	SINA(I)=A(I)	THR 34
	COSA(I)=B(I)	THR 35
20	SUMV=SUMV+B(I)*DELS(I)*Y2(I)**2	THR 36
	SUMV=SUMV*3.14159265	THR 37
	L=1	THR 38
	DO 30 I=1,NT	THR 39
	RB(I,L)=A(I)	THR 40
30	RB(I,L+1)=B(I)	THR 41
	REWIND 4	THR 42
	NSIG=NSIGA	THR 43
	CALL AXIS	THR 44
	REWIND 13	THR 45
	BLANK=0.0	THR 46
	READ (13) DUMMY	THR 47
	READ (13) DUMMY	THR 48
	WRITE (13) NN,BLANK,(X2(I),I=1,199)	THR 49
	WRITE (13) NN,BLANK,(Y2(I),I=1,199)	THR 50
	WRITE (13) BLANK,(T3(I,1),I=1,199)	THR 51
	END	THR 52
	SUBROUTINE AXIS	AXI 1
C		AXI 2
C	* COMPUTE AXISYMMETRIC VELOCITY COMPONENTS AND PRINT	AXI 3
C		AXI 4
	COMMON HEDR(8),ISWITCH,IPUNCH,ITERA,ITERMAX,IMACH,ISEP,INT(8),IFLAAXI	AXI 5
	IG5,FLG05,MN,APT,ATT,REFL,SREF,XSEPND,NN,BDN,ND(2),NT,NSIGA,IPRINT,AXI	AXI 6
	ZAMJET,PTJET,TTJET,RJET,RSTAR	AXI 7
	COMMON /C4/ X1(200),Y1(200),X2(200),Y2(200),DELS(200),SINA(200),COAXI	AXI 8
	ISA(200),XP(200),YP(200)	AXI 9
	COMMON /TC/ RB(200,2),SIG(200,1),A(200),B(200),Z(200),PHI(200,1),XAXI	AXI 10
	IN(200,1),T(200,1),T3(200,1),INBIG,INP,NI,SUMV,SUMM(4)	AXI 11
	DIMENSION VX(200,1),VY(200,1),VT(200,1),TH(200,1),CP(200,1),SAXI	AXI 12
	IUMTDS(4)	AXI 13
	EQUIVALENCE (VX,XN), (VY,T), (VT,T3), (TH,SIG), (CP,T3)	AXI 14
	REAL MN	AXI 15
	INTEGER FLG05,BDN	AXI 16
C		AXI 17
	NC=NT	AXI 18
	N=1	AXI 19
	NP=INP	AXI 20
C		AXI 21
C	* READ AXIS SIGMAS	AXI 22
C		AXI 23
	SUMM(N)=0.0	AXI 24
	SUMTDS(N)=0.0	AXI 25

APPENDIX

	READ (3) (SIG(I,N),I=1,NC)	AXI 26
C		AXI 27
C	* NO. OF MIDPOINTS LOOP	AXI 28
C		AXI 29
	DO 20 I=1,NT	AXI 30
C		AXI 31
C	* READ MATRICES A,B,Z	AXI 32
C		AXI 33
	READ (9) (A(J),J=1,NT),(B(J),J=1,NT),(Z(J),J=1,NT)	AXI 34
C		AXI 35
C	* NO. OF FLOWS LOOP	AXI 36
C		AXI 37
	N1=0	AXI 38
	N1=N1+2	AXI 39
	SN=0,0	AXI 40
	ST=0,0	AXI 41
	SP=0,0	AXI 42
C		AXI 43
C	* NO. OF ELEMENTS LOOP	AXI 44
C		AXI 45
	DO 10 J=1,NT	AXI 46
	SN=SN+A(J)*SIG(J,N)	AXI 47
	ST=ST+B(J)*SIG(J,N)	AXI 48
10	SP=SP+Z(J)*SIG(J,N)	AXI 49
	XN(I,N)=SN-RB(I,N1=1)	AXI 50
	PHI(I,N)=SP	AXI 51
	T(I,N)=ST+RB(I,N1)	AXI 52
	SUMM(N)=SUMM(N)+PHI(I,N)*Y2(I)*RB(I,N1=1)*DELS(I)	AXI 53
	CP(I,N)=1.=T(I,N)**2	AXI 54
20	CONTINUE	AXI 55
	IF (MN.EQ.0,0) GO TO 60	AXI 56
C		AXI 57
C	* MACH NO. ADJUSTMENT	AXI 58
C		AXI 59
	D1=MN*MN	AXI 60
	D2=1.=D1	AXI 61
	D3=SQRT(D2)	AXI 62
	D4=.7*D1	AXI 63
	D5=.2*D1	AXI 64
	DO 30 I=1,NT	AXI 65
	IF (IMACH.LT.2) BB=D2	AXI 66
	IF (IMACH.GE.2) BB=1.=MN**2*T(I,N)*COBA(I)	AXI 67
	IF (BB.LE.0,0) GO TO 160	AXI 68
	TX=(T(I,N)*COBA(I)=1.)/BB+1.	AXI 69
	TY=T(I,N)*SINA(I)*D3/BB	AXI 70
	T(I,N)=SQRT(TX*TX+TY*TY)	AXI 71
	CP(I,N)=((1.+D5*(1.=T(I,N)**2))**3.5=1.)/D4	AXI 72
30	CONTINUE	AXI 73
	D2=1.=D1	AXI 74
	D3=SQRT(D2)	AXI 75
C		AXI 76
C	* ELIMINATE MACH NO EFFECT FOR PRINTOUT	AXI 77
C		AXI 78
	DO 40 I=1,NI	AXI 79
40	X1(I)=X1(I)*D3	AXI 80
	J1=0	AXI 81
	M=ND(1)=1	AXI 82
	DO 50 J=1,M	AXI 83
	J1=J1+1	AXI 84
	T1=X1(J1+1)=X1(J1)	AXI 85
	T2=Y1(J1+1)=Y1(J1)	AXI 86
	X2(J)=(X1(J1+1)+X1(J1))/2.	AXI 87
	DELS(J)=SQRT(T1*T1+T2*T2)	AXI 88
	COBA(J)=T1/DELS(J)	AXI 89
50	SINA(J)=T2/DELS(J)	AXI 90
	J1=J1+1	AXI 91

APPENDIX

60	CONTINUE	AXI 92
	IF (PLG05,EQ,0) RETURN	AXI 93
C		AXI 94
C	* OFF=BODY POINT	AXI 95
C		AXI 96
	DO 80 I=1,NP	AXI 97
C		AXI 98
C	* READ MATRICES X,Y,Z	AXI 99
C		AXI 100
	READ (9) (A(J),J=1,NT),(B(J),J=1,NT),(Z(J),J=1,NT)	AXI 101
C		AXI 102
C	* NO. OF FLOW	AXI 103
C		AXI 104
	SX=0,0	AXI 105
	SY=0,0	AXI 106
	SP=0,0	AXI 107
C		AXI 108
C	* NO. OF ELEMENTS LOOP	AXI 109
C		AXI 110
	DO 70 J=1,NT	AXI 111
	SX=SX+A(J)*SIG(J,N)	AXI 112
	SY=SY+B(J)*SIG(J,N)	AXI 113
70	SP=SP+Z(J)*SIG(J,N)	AXI 114
	PHI(I,N)=SP	AXI 115
	VX(I,N)=SX+1,	AXI 116
	VY(I,N)=SY	AXI 117
80	CONTINUE	AXI 118
	IF (MN,EQ,0,0) GO TO 110	AXI 119
C	* MACH NO. ADJUSTMENT	AXI 120
	DO 90 I=1,NP	AXI 121
	BB=D2	AXI 122
C		AXI 123
C	LABRUJERE COMPRESSIBILITY CORRECTION	AXI 124
C		AXI 125
	IF (IMACH,GE,2) BB=1.-MN**2*VX(I,N)	AXI 126
	VY(I,N)=VY(I,N)*D3/BB	AXI 127
	VX(I,N)=(VX(I,N)-1.)/BB+1.	AXI 128
90	CONTINUE	AXI 129
	DO 100 I=1,NP	AXI 130
100	XP(I)=XP(I)*D3	AXI 131
C		AXI 132
C	* COMPUTE VT AND THETA	AXI 133
C		AXI 134
110	CONTINUE	AXI 135
	DO 120 I=1,NP	AXI 136
	VT(I,N)=SQRT(VX(I,N)**2+VY(I,N)**2)	AXI 137
120	TH(I,N)=ATAN2(VY(I,N),VX(I,N))*57.2957795	AXI 138
C		AXI 139
C	* PRINT AXIS FLOW (OFF=BODY) OUTPUT	AXI 140
C		AXI 141
	L=1	AXI 142
	I=1	AXI 143
	LCTR=45	AXI 144
130	WRITE (6,170) HEDR	AXI 145
	WRITE (6,180)	AXI 146
	WRITE (6,190)	AXI 147
140	CONTINUE	AXI 148
	CP2=((1.+D5*(1.=VT(I,L)**2))**3,5=1.)/D4	AXI 149
	XM2=VT(I,L)*MN/SQRT(1.=D5*(VT(I,L)**2=1.))	AXI 150
	WRITE (6,210) I,XP(I),YP(I),VX(I,L),VY(I,L),VT(I,L),TH(I,L),XM2,CP	AXI 151
12		AXI 152
	I=I+1	AXI 153
	IF (I,GT,NP) GO TO 150	AXI 154
	IF (I,LE,LCTR) GO TO 140	AXI 155
	LCTR=LCTR+45	AXI 156
	GO TO 130	AXI 157

APPENDIX

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150 CONTINUE AXI 158
RETURN AXI 159
160 WRITE (6,200) AXI 160
STOP AXI 161
C AXI 162
C AXI 163
C AXI 164
170 FORMAT (1H1,25X,23HPOTENTIAL FLOW SOLUTION//6X,8A10//) AXI 165
180 FORMAT (1X,35H OFF-BODY UNIFORM AXISYMMETRIC FLOW) AXI 166
190 FORMAT (1X//10X,3HX/L,9X,3HR/L,10X,2HVV,10X,2HVR,10X,2HVT,9X,3HETA AXI 167
1,10X,2HML,10X,2HCP//) AXI 168
200 FORMAT (1X////1X,73HFREESTREAM MACH NUMBER TOO LARGE FOR LABRUJERE AXI 169
1 COMPRESSIBILITY CORRECTION/1X,62HRESUBMIT USING IMACH=1 FOR GOETH AXI 170
2ERT COMPRESSIBILITY CORRECTION) AXI 171
210 FORMAT (1X,I3,8F12.6) AXI 172
END AXI 173
OVERLAY(LINK,5,0)
PROGRAM FIVE FIV 1
C FIV 2
C VISCOUS FLOW/POTENTIAL FLOW INTERFACE PROGRAM FIV 3
C FIV 4
COMMON HEDR(8),ISWITCH,IPUNCH,ITERA,ITERMAX,IMACH,ISEP,INT(8),IFLAFIV 5
1G5,FLG05,MO,APT,ATT,REFL,SREF,XSEPND,NN,BDN,ND(2),NT,NBGA,IPRINT,FIV 6
2AMJET,PTJET,TTJET,RJET,RSTAR FIV 7
COMMON /SAVE/ VDUM(402),RDS(201),XIN,VDUM2(347) FIV 8
DIMENSION X(200), R(200), CP(200), ME(200), THETA(200), CAPH(200),FIV 9
1 CF(200), CAPHI(200), CDF(200), CDP(200), CDT(200), RCPUNCH(200), FIV 10
2XO(200), RO(200), CS(200), RI(200), UI(200), DELI(200), RET(200), FIV 11
3TAW51(200), TPPT(200), FNN(200), DELTA(200), FLOT(15), FLOT0(7) FIV 12
INTEGER FLG05,BDN FIV 13
REAL MO,ME FIV 14
C FIV 15
C INITIALIZE FIV 16
C FIV 17
G=1.4 FIV 18
G1=(G-1.)/2. FIV 19
G2=G/(G-1.) FIV 20
G3=1./(G-1.) FIV 21
G4=(G+1.)/2. FIV 22
G5=G4*G3 FIV 23
G6=G4/G1 FIV 24
TT=ATT FIV 25
PT=APT FIV 26
ME(1)=0.0 FIV 27
THETA(1)=0.0 FIV 28
CAPH(1)=1.3 FIV 29
CAPHI(1)=1.3 FIV 30
CF(1)=0.0 FIV 31
C FIV 32
C READ XO,RO,X,R,AND CP FROM TAPE13 FIV 33
C FIV 34
REWIND 13 FIV 35
READ (13) NXO,(XO(I),I=1,NXO) FIV 36
READ (13) NXO,(RO(I),I=1,NXO) FIV 37
READ (13) NUM,(X(I),I=1,NUM) FIV 38
READ (13) NUM,(R(I),I=1,NUM) FIV 39
READ (13) CP FIV 40
C FIV 41
C OBTAIN CP AND R AT ORIGINAL X FIV 42
C FIV 43
NTAB=1 FIV 44
IORDER=2 FIV 45
IPT=1 FIV 46
DO 10 I=2,NUM FIV 47
CALL IUNI (200,NUM,X,NTAB,CP,IORDER,XO(I),CS(I),IPT,IERR) FIV 48
10 CONTINUE FIV 49

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APPENDIX

	DO 20 I=2,NUM	FIV 50
	CP(I)=CS(I)	FIV 51
	R(I)=RO(I)	FIV 52
20	X(I)=XO(I)	FIV 53
	CONTINUE	FIV 54
	REWIND 13	FIV 55
	DO 30 J=1,NUM	FIV 56
	IF (ITERA, EQ, 0) RDS(J)=R(J)	FIV 57
	X(J)=X(J)*REFL	FIV 58
	R(J)=R(J)*REFL	FIV 59
	RDS(J)=RDS(J)*REFL	FIV 60
30	CONTINUE	FIV 61
	DO 40 I=1, NXD	FIV 62
	XO(I)=XO(I)*REFL	FIV 63
	RO(I)=RO(I)*REFL	FIV 64
40	CONTINUE	FIV 65
C		FIV 66
C	CALCULATE FREE STREAM CONDITIONS	FIV 67
C		FIV 68
	PO=PT*(1,+G1*MO**2)**(=G2)	FIV 69
	GINF=G/2,*PO*MO**2	FIV 70
	RG=286,96	FIV 71
	PI=3,1415926	FIV 72
	CP(1)=(PT=PO)/(0,5*PO*G*MO**2)	FIV 73
C		FIV 74
C	CALCULATE PLUME BOUNDARY AND VELOCITY	FIV 75
C	USING ONE DIMENSIONAL METHOD	FIV 76
C		FIV 77
	DO 50 I=1,200	FIV 78
	UI(I)=0,0	FIV 79
	RI(I)=0,0	FIV 80
50	CONTINUE	FIV 81
	IT=INT(6)	FIV 82
	NJ=NUM=IT+1	FIV 83
	IF (INT(5), EQ, 0) GO TO 90	FIV 84
	RJET=RJET*REFL	FIV 85
	K=0	FIV 86
	DO 80 I=IT, NUM	FIV 87
	K=K+1	FIV 88
	PE=GINF*CP(I)+PO	FIV 89
	PRAT=PTJET/PE	FIV 90
	IF (I, GT, IT) GO TO 70	FIV 91
	PCRIT=(1,0+G1*AMJET**2)**G2	FIV 92
	IF (PRAT, GT, PCRIT) GO TO 60	FIV 93
	RSTAR=PRAT**=(1,/G)+SQRT(G4**G6/G1*(1,=PRAT**=(1,/G2)))	FIV 94
	RSTAR=SQRT(RSTAR)*RJET	FIV 95
	GO TO 70	FIV 96
60	ASTAR=G4**G5*AMJET/(1,+G1*AMJFT**2)**G5	FIV 97
	RSTAR=SQRT(ASTAR)*RJET	FIV 98
70	XME=SQRT((PRAT**=(1,/G2)=1,)/G1)	FIV 99
	ASOA=G4**G5*XME/(1,+G1*XME**2)**G5	FIV 100
	IF (I, GT, IT) R(I)=RSTAR/SQRT(ASOA)	FIV 101
	UI(K)=XME*SQRT(G*RG*TTJET/(1,+G1*XME**2))	FIV 102
	RI(K)=R(I)	FIV 103
80	CONTINUE	FIV 104
	RJET=RJET/REFL	FIV 105
90	CONTINUE	FIV 106
C		FIV 107
C	PREPARE INPUT TO SUBROUTINE VISCOUS	FIV 108
C		FIV 109
	INT(1)=NUM	FIV 110
	INT(2)=1	FIV 111
	INT(8)=ISEP=2	FIV 112
	FLOT(1)=12,	FIV 113
	FLOT(2)=0	FIV 114
	FLOT(3)=PT/FLOT(1)**2/47,880258	FIV 115

APPENDIX

	FLOT(4)=TT+1,8	FIV 116
	FLOT(5)=MO	FIV 117
	FLOT(6)=ITERA+1	FIV 118
	FLOT(7)=G	FIV 119
	FLOT(8)=CAPHI(INT(2))	FIV 120
	FLOT(9)=THETA(INT(2))+FLOT(1)/.3048	FIV 121
	FLOT(10)=IPRINT	FIV 122
	FLOT(11)=UI(1)*FLOT(1)/.3048	FIV 123
	FLOT(12)=0,25	FIV 124
	FLOT(13)=0,0	FIV 125
	FLOT(14)=0,0	FIV 126
	FLOT(15)=XSEPND*REFL*FLOT(1)/.3048	FIV 127
	IF (ITERA.EQ.0) XIN=X(NUM)	FIV 128
	IF (INT(7).GT.0) CALL SMINT (X,CP,NUM,INT(3),NUM)	FIV 129
	XIN=XIN+FLOT(1)/.3048	FIV 130
	DO 100 I=1,NUM	FIV 131
	X(I)=X(I)*FLOT(1)/.3048	FIV 132
	R(I)=R(I)*FLOT(1)/.3048	FIV 133
	RDS(I)=RDS(I)*FLOT(1)/.3048	FIV 134
100	CONTINUE	FIV 135
	DO 110 K=1,NJ	FIV 136
	RI(K)=RI(K)*FLOT(1)/.3048	FIV 137
	UI(K)=UI(K)*FLOT(1)/.3048	FIV 138
110	CONTINUE	FIV 139
	CALL VISCUS (INT,FLOT,X,R,CP,RI,UI,FLOTO,RCPUNCH,ME,THETA,DELTA,CAPHI,CF,DELI,CAPHI,RET,TAWS1,PTPT,FNN)	FIV 140
C		FIV 141
C	CHANGE OUTPUT FROM VISCOUS TMETERS	FIV 142
C		FIV 143
	FLOTO(7)=FLOTO(7)/FLOT(1)*.3048	FIV 144
	XIN=XIN/FLOT(1)*.3048	FIV 145
	DO 120 I=1,NUM	FIV 146
	X(I)=X(I)/FLOT(1)*.3048	FIV 147
	R(I)=R(I)/FLOT(1)*.3048	FIV 148
	RDS(I)=RDS(I)/FLOT(1)*.3048	FIV 149
	RCPUNCH(I)=RCPUNCH(I)/FLOT(1)*.3048	FIV 150
	THETA(I)=THETA(I)/FLOT(1)*.3048	FIV 151
	DELTA(I)=DELTA(I)/FLOT(1)*.3048	FIV 152
	DELI(I)=DELI(I)/FLOT(1)*.3048	FIV 153
120	CONTINUE	FIV 154
	DO 130 K=1,NJ	FIV 155
	UI(K)=UI(K)/FLOT(1)*.3048	FIV 156
130	CONTINUE	FIV 157
	QS=QINF*SBREF	FIV 158
C		FIV 159
C	CALCULATION OF DRAG COEFFICIENTS	FIV 160
C		FIV 161
	CDP(1)=0,0	FIV 162
	CDP(1)=0,0	FIV 163
	CDT(1)=0,0	FIV 164
	ROLD=0,0	FIV 165
	GOLD=0,0	FIV 166
	DO 140 J=2,NUM	FIV 167
	PE=PO*(1.+G/2,MO**2*CP(J))	FIV 168
	QNEW=G/2,PE*ME(J)**2	FIV 169
	RNEW=RO(J)	FIV 170
	ANGLE=ATAN((RNEW-ROLD)/(X(J)-X(J-1)))	FIV 171
	SL=PI*(RNEW+ROLD)*SQRT((RNEW-ROLD)**2+(X(J)-X(J-1))**2)	FIV 172
	CDP(J)=(CP(J)+CP(J-1))*(QNEW+GOLD)*SL*COS(ANGLE)/QS/4,+CDP(J-1)	FIV 173
	CDP(J)=PI/SBREF*(RNEW*CP(J)+ROLD*CP(J-1))*(RNEW+ROLD)+CDP(J-1)	FIV 174
	CDT(J)=CDP(J)+CDF(J)	FIV 175
	ROLD=RNEW	FIV 176
	GOLD=QNEW	FIV 177
140	CONTINUE	FIV 178
C		FIV 179
C	OUTPUT DATA	FIV 180
		FIV 181

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C	DO 150 N=1,NUM	FIV 182
	X(N)=X(N)/REFL	FIV 183
	R(N)=R(N)/REFL	FIV 184
	THETA(N)=THETA(N)/REFL	FIV 185
	DELTA(N)=DELTA(N)/REFL	FIV 186
	RCPUNCH(N)=RCPUNCH(N)/REFL	FIV 187
	RDS(N)=RDS(N)/REFL	FIV 188
	DELI(N)=DELI(N)/REFL	FIV 189
150	CONTINUE	FIV 190
	IF (ITERA,LT,IPRINT) GO TO 170	FIV 191
	FLOTO(7)=FLOTO(7)/REFL	FIV 192
	XINND=XIN/REFL	FIV 193
	N1=1	FIV 194
160	N2=N1+34	FIV 195
	IF (N2,GE,NUM) N2=NUM	FIV 196
	WRITE (6,200) HEDR,ITERA,MO,TT,PT,REFL,SREF	FIV 197
	PRINT 210, FLOTO(7),XINND	FIV 198
	WRITE (6,220)	FIV 199
	WRITE (6,230) (X(N),R(N),CP(N),CF(N),CDP(N),CDF(N),CDT(N),RDS(N),R	FIV 200
	CPUNCH(N),DELTA(N),DELI(N),THETA(N),CAPH(N),N=N1,N2)	FIV 201
	IF (N2,GE,NUM) GO TO 170	FIV 202
	N1=N2+1	FIV 203
	GO TO 160	FIV 204
170	CONTINUE	FIV 205
	REWIND 13	FIV 206
	READ (13) BLANK	FIV 207
	READ (13) BLANK	FIV 208
	NN=NUM	FIV 209
	WRITE (13) NN,(X(I),I=1,NN)	FIV 210
	WRITE (13) NN,(RCPUNCH(I),I=1,NN)	FIV 211
	WRITE (13) CP	FIV 212
C		FIV 213
C	WRITE DATA ON TAPE 7 FOR RESTART	FIV 214
C		FIV 215
	IF (IPUNCH,LT,1) GO TO 190	FIV 216
	IF (ITERA,NE,ITERMAX) GO TO 190	FIV 217
	DO 180 I=1,NX0	FIV 218
	XO(I)=XO(I)/REFL	FIV 219
	RO(I)=RO(I)/REFL	FIV 220
180	CONTINUE	FIV 221
	IDM=ITERMAX+1	FIV 222
	REWIND 7	FIV 223
	WRITE (7,270) HEDR	FIV 224
	WRITE (7,240) ISWITCH,IPRINT,IPUNCH,IDM,IMACH,ISEP,(INT(I),I=2	FIV 225
	1,7),IFLAGS	FIV 226
	WRITE (7,280) MO,APT,ATT,REFL,SREF,XSEPND	FIV 227
	WRITE (7,280) AMJET,PTJET,TTJET,RJET	FIV 228
	WRITE (7,240) NN	FIV 229
	WRITE (7,290) (XO(I),I=1,NN)	FIV 230
	WRITE (7,300) (RO(I),I=1,NN)	FIV 231
	WRITE (7,250) (RCPUNCH(I),I=1,NN)	FIV 232
	WRITE (7,260) (CP(I),I=1,NN)	FIV 233
190	CONTINUE	FIV 234
C		FIV 235
C		FIV 236
200	FORMAT (1H1,8A10,5X,14HITERATION NO ,I2//2X,4HMO =,F7.4,4X,4HPT =FIV 237	
	1,F7.2,7H KELVIN,4X,4HPT =,F10.1,8H PASCALS,4X,3HL =,F10.6,7H METERFIV 238	
	28,4X,6HSREF =,F10.6,10H 80 METERS//) FIV 239	
210	FORMAT (4X,34HBOUNDARY LAYER SEPARATION AT X/L =,F10.6,12X,36HBOUNFIV 240	
	1DARY LAYER REATTACHMENT AT X/L =,F10.6,//) FIV 241	
220	FORMAT (5X,3HX/L,5X,3HR/L,5X,2HCP,6X,2HCF,6X,3HCDP,5X,3HCFIV 242	
	1DT,4X,5HRDS/L,4X,4HRC/L,2X,6HDEL*/L,3X,5HDEL/L,2X,7HTHETA/L,3X,1HMFIV 243	
	2//) FIV 244	
230	FORMAT (1X,13F8.4)	FIV 245
240	FORMAT (16I5)	FIV 246
		FIV 247

APPENDIX

250	FORMAT (6F10,6,4X,2HRC)	FIV 24A
260	FORMAT (6F10,6,4X,2HCP)	FIV 24B
270	FORMAT (8A10)	FIV 250
280	FORMAT (F10,6,F10,1,F10,2,3F10.6)	FIV 251
290	FORMAT (6F10,6,4X,2HXD)	FIV 252
300	FORMAT (6F10,6,4X,2HRO)	FIV 253
	END	FIV 254
	SUBROUTINE VISCUS (INT,FLOT,XA,RAD,CP,RI,UJ,FLOTO,RADO,A,THR,DELS1	VIS 1
	1,H51,CFA,DELI,H1,RET,TAWS1,PTB51,FNN51)	VIS 2
C		VIS 3
C	VISCOUS FLOW SUBROUTINE PACKAGE	VIS 4
C		VIS 5
	COMMON /SAVE/ SB(201),SC(201),Y(201),XIN,XSEPSV(20),DELSV(20),YOUT	VIS 6
	1(201)	VIS 7
	DIMENSION INT(8), FLOT(15), FLOTO(7), XA(201), RAD(201), U(201), RVIS	VIS 8
	1ADO(201), A(201), THR(201), DELS1(201), H51(201), CFA(201), DEL1(2	VIS 9
	201), H1(201), RET(201), TAWS1(201), PTB51(201), FNN51(201), CP(201	VIS 10
	3), RI(201), UJ(201), VBLC(201), SB(201), S1(201), DSTAR(201), CBV(VIS	VIS 11
	4201), CPCV(4)	VIS 12
C		VIS 13
	ANA=FLOT(6)	VIS 14
	IAN=ANA	VIS 15
	THR(1)=0.	VIS 16
	DELS1(1)=0.	VIS 17
	DELI(1)=0.	VIS 18
	H51(1)=0.	VIS 19
	RET(1)=0.	VIS 20
	TAWS1(1)=0.	VIS 21
	PTB51(1)=0.	VIS 22
	FNN51(1)=0.	VIS 23
	NN=INT(1)	VIS 24
	NAZ=INT(2)	VIS 25
	NMIN=INT(3)	VIS 26
	NMAX=INT(4)	VIS 27
	IJET=INT(5)	VIS 28
	NEXT=INT(6)	VIS 29
	ISMOO=INT(7)	VIS 30
	I PRESS=INT(8)	VIS 31
	Z=FLOT(1)	VIS 32
	TWW=FLOT(2)	VIS 33
	PT=FLOT(3)	VIS 34
	YT=FLOT(4)	VIS 35
	AMIN=FLOT(5)	VIS 36
	GA=FLOT(7)	VIS 37
	HIX=FLOT(8)	VIS 38
	THRR=FLOT(9)	VIS 39
	C=FLOT(12)	VIS 40
	X8IN=FLOT(15)	VIS 41
	IF (IAN,EQ,1) XIN=XA(NN)	VIS 42
	R=53.35	VIS 43
	GC=32.174	VIS 44
	PFREE=PT*(1.+(GA=1.)*.5*AMIN**2)**(GA/(1.-GA))	VIS 45
	IF (ANA,GT,1) GO TO 20	VIS 46
	DO 10 I=1,NN	VIS 47
10	Y(I)=RAD(I)	VIS 48
	XSEP=0.	VIS 49
20	CONTINUE	VIS 50
	DO 30 I=1,NN	VIS 51
30	SB(I)=3.1416*Y(I)**2	VIS 52
C		VIS 53
C	CALCULATE VELOCITY FROM CP	VIS 54
C		VIS 55
	DO 40 I=1,NN	VIS 56
	PL=.5*GA*PFREE*AMIN**2*CP(I)+PFREE	VIS 57
	AML2=2./((GA=1.)*((PL/PT)**((1.-GA)/GA)=1.)	VIS 58
	IF(AML2,LE,0.0) AML2=0.00000001	VIS 58A

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AML=SQRT(AML2) VIS 59
TL=TT/(1,+(GA=1,)*.5*AML**2) VIS 60
40 U(1)=SQRT(2,/(GA=1,)*GA*R*GC*(TT=TL)) VIS 61
C SHAPEJ CALCULATES 1ST DERIVATIVE OF CONTOUR VIS 62
C VIS 63
C CALL SHAPEJ (88,81,XA,NN) VIS 64
C VIS 65
C NEWBL CONTROL CALCULATION OF BOUNDARY LAYER VIS 66
C VIS 67
C CALL NEWBL (VBLC,XA,Y,88,NAZ,NN,TWW,Z,PT,TT,ANA,GA,U,81,CFA,HIX,TH VIS 68
1RR,A,DEL1,RET,THR,DSTAR,DEL51,H51,TAWS1,PTB51,FNNS1,H1,DRAG) VIS 69
FLOTO(1)=DRAG VIS 70
IF (IPRESS,GE,0) GO TO 50 VIS 71
IF (IPRESS,EQ,-1,AND,XSIN,NE,0,0) GO TO 90 VIS 72
XSIN=XA(NEXT=1) VIS 73
GO TO 85 VIS 74
50 CONTINUE VIS 75
C VIS 76
C FIX DETERMINES MIN. CP. THE MIN CP IS USED AS START VIS 77
C LOCATION IN SEARCH FOR SEPARATION VIS 78
C VIS 79
C CALL FIX (NMIN,NMAX,CP,MI) VIS 80
CPS=0 VIS 81
CPCV(4)=1,00 VIS 82
C VIS 83
C SEPA DETERMINES SEPARATION PROPERTIES VIS 84
C VIS 85
C IF (MI=NN) 60,170,170 VIS 86
60 CONTINUE VIS 87
MM=MI=NAZ VIS 88
CALL SEPA (XA,RAD,CP,AMIN,CFA(MI),DEL1(MM),THR(MM),RET(MM),CP(MI), VIS 89
1MI,NMAX,CPCV) VIS 90
CPS=CPCV(IPRESS+1) VIS 91
FLOTO(2)=CPCV(1) VIS 92
FLOTO(3)=CPCV(2) VIS 93
FLOTO(4)=CPCV(3) VIS 94
FLOTO(5)=CPCV(4) VIS 95
DO 80 I=MI,NMAX VIS 96
IF (CP(I)=CPS) 80,70,70 VIS 97
70 XSEP=((CPS=CP(I=1))/(CP(I)=CP(I=1)))+(XA(I)=XA(I=1))+XA(I=1) VIS 98
AML=A(I) VIS 99
GO TO 90 VIS 100
80 CONTINUE VIS 101
IF (IAN,EQ,1) GO TO 90 VIS 102
IF (XSIN,NE,0,) GO TO 90 VIS 103
IF (XSEPSV(IAN=1),EQ,0,) GO TO 90 VIS 104
85 XSEP=XA(NEXT=1) VIS 105
WRITE (6,220) XSEP VIS 106
90 CONTINUE VIS 107
C VIS 108
C CALCULATE SEPARATION POINT VIS 109
C VIS 110
C IF (ANA,EQ,1,) GO TO 160 VIS 111
IF (ANA,GT,2,) GO TO 100 VIS 112
DELSV(2)=ABS(XSEP-XSEPSV(1)) VIS 113
XSEP=XSEPSV(1) VIS 114
GO TO 160 VIS 115
100 CONTINUE VIS 116
IF (ANA,EQ,3,) GO TO 140 VIS 117
IF (ANA,GE,8,) GO TO 150 VIS 118
AVEDEL=0. VIS 119
IAN1=IAN=1 VIS 120
DO 110 IBJ=2,IAN1 VIS 121
110 AVEDEL=AVEDEL+DELSV(IRJ) VIS 122
AVEDEL=AVEDEL/IAN1 VIS 123
VIS 124

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APPENDIX

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IF (ABS(XSEP-XSEPSV(IAN=1)),LT,2,AVEDEL) GO TO 140          VIS 125
IF (XSEP-XSEPSV(IAN=1)) 120,120,130                        VIS 126
120 XSEP=XSEPSV(IAN=1)+2,AVEDEL                               VIS 127
GO TO 140                                                    VIS 128
130 XSEP=XSEPSV(IAN=1)+2,AVEDEL                               VIS 129
140 DELSV(IAN)=ABS(XSEP-XSEPSV(IAN=1))                      VIS 130
XSEP=(XSEP+XSEPSV(IAN=1))*5                                 VIS 131
GO TO 160                                                    VIS 132
150 CONTINUE                                                  VIS 133
XSEP=AMIN1(XSEPSV(7),XSEPSV(6),XSEPSV(5))                 VIS 134
160 XSEPSV(IAN)=XSEP                                         VIS 135
170 CONTINUE                                                  VIS 136
DO 180 I=1,NN                                               VIS 137
180 CSV(I)=CP(I)                                             VIS 138
IF (XBIN,NE,0.) XSEP=XBIN                                    VIS 139
IF (ANA,GT,4) GO TO 200                                     VIS 140
C                                                            VIS 141
C      ZERO CP FOR THE FIRST 4 ITERATIONS                    VIS 142
C                                                            VIS 143
DO 190 I=1,NN                                               VIS 144
RATIO=0.                                                    VIS 145
190 CSV(I)=CP(I)*RATIO                                       VIS 146
C                                                            VIS 147
C      SEP CALCULATES THE AERODYNAMIC CONTOUR              VIS 148
C                                                            VIS 149
200 CALL SEP (NN,XA,RAD,CSV,XSEP,AMIN,GA,TT,PT,RADO,DBSTAR,Y,ANA,IJET,NVIS) VIS 150
1EXT,RI,UJ,C)                                             VIS 151
FLOTO(7)=XSEP                                             VIS 152
IF (ISM00,EQ,0) GO TO 210                                  VIS 153
CALL SMINT (XA,RADO,NN,NMIN,NMAX)                          VIS 154
WRITE (6,220) (I,XA(I),RADO(I),I=1,NN)                    VIS 155
C                                                            VIS 156
210 RETURN                                                  VIS 157
C                                                            VIS 158
C                                                            VIS 159
220 FORMAT (54H DID NOT SEPARATE, USE NOZZLE EXIT AS SEPARATION POINT, VIS 160
1E12,4)                                                    VIS 161
END                                                         VIS 162
SUBROUTINE SHAPEJ (SS,S1,X,NN)                               SHA 1
C                                                            SHA 2
C      THIS SUBROUTINE SETS THE BOUNDARY CONDITIONS. THESE BOUNDARY SHA 3
C      CONDITIONS ARE SET BY THE INITIAL AND FINAL SLOPES OF THE SHA 4
C      CROSSSECTIONAL AREA CURVES.                          SHA 5
C                                                            SHA 6
C      DIMENSION C1SS(201), C2SS(201), C3SS(201), S8(1), S1(1), X(1) SHA 7
C                                                            SHA 8
CALL POWER (X,NN)                                           SHA 9
CALL SUMA (2,NN=1,3,X,SS,C1SS,C2SS,C3SS,S1,1)              SHA 10
S1(1)=0.0                                                   SHA 11
S1(NN)=0.0                                                  SHA 12
RETURN                                                      SHA 13
END                                                         SHA 14
SUBROUTINE POWER (X,NN)                                      POW 1
C                                                            POW 2
DIMENSION X(1)                                             POW 3
COMMON /COEFF/ X2(201),X3(201),X4(201)                     POW 4
C                                                            POW 5
DO 10 I=1,NN                                               POW 6
X2(I)=X(I)*X(I)                                           POW 7
X3(I)=X2(I)*X(I)                                          POW 8
X4(I)=X3(I)*X(I)                                          POW 9
10 CONTINUE                                                 POW 10
RETURN                                                      POW 11
END                                                         POW 12
SUBROUTINE SUMA (NX,NY,LZ,X,S,C1,C2,C3,S1,L)               SUM 1
C                                                            SUM 2

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APPENDIX

C	THIS SUBROUTINE CURVE FITS A PARABOLIC ARC THRU LEAST SQUARES	SUM	3
C		SUM	4
	COMMON /COEFF/ X2(201),X3(201),X4(201)	SUM	5
	DIMENSION X(1), S(1), S1(1), C1(1), C2(1), C3(1)	SUM	6
	DOUBLE PRECISION SUM1,SUM2,SUM3,SUM4,SUM5,SUM6,SUM7	SUM	7
C		SUM	8
	LN=LZ/2	SUM	9
	C1(NX=1)=0,0	SUM	10
	C2(NX=1)=0,0	SUM	11
	C3(NX=1)=0,0	SUM	12
	DO 30 J=NX,NY	SUM	13
	SUM1=0,0	SUM	14
	SUM2=0,0	SUM	15
	SUM3=0,0	SUM	16
	SUM4=0,0	SUM	17
	SUM5=0,0	SUM	18
	SUM6=0,0	SUM	19
	SUM7=0,0	SUM	20
	M=J-LN	SUM	21
	MM=J+LN	SUM	22
	DO 10 I=M,MM	SUM	23
	SUM1=SUM1+X(I)	SUM	24
	SUM2=SUM2+X2(I)	SUM	25
	SUM3=SUM3+X3(I)	SUM	26
	SUM4=SUM4+X4(I)	SUM	27
	SUM5=SUM5+(X(I)*S(I))	SUM	28
	SUM6=SUM6+(X2(I)*S(I))	SUM	29
	SUM7=SUM7+S(I)	SUM	30
10	CONTINUE	SUM	31
	AA=SUM7	SUM	32
	AB=SUM1	SUM	33
	AC=SUM2	SUM	34
	AD=SUM5/SUM1	SUM	35
	AE=SUM2/SUM1	SUM	36
	AF=SUM6/SUM2	SUM	37
	AG=SUM3/SUM1	SUM	38
	AH=SUM4/SUM2	SUM	39
	AI=SUM3/SUM2	SUM	40
	AAAR=AA/LZ	SUM	41
	A=AAAR-AD	SUM	42
	C=AAAR-AF	SUM	43
	ABAR=AB/LZ	SUM	44
	R=ABAR-AE	SUM	45
	D=ABAR-AI	SUM	46
	ACAR=AC/LZ	SUM	47
	E=ACAR-AG	SUM	48
	G=ACAR-AH	SUM	49
	R=R+,ID=10	SUM	50
	D=D+,ID=10	SUM	51
	EB=E/B	SUM	52
	AM=EB-G/D	SUM	53
	IF (ABS(AM),LE,0,1D=10) GO TO 20	SUM	54
	AOR=A/B	SUM	55
	C3(J)=(AOR=C/D)/AM	SUM	56
	C2(J)=AOR-EB*C3(J)	SUM	57
	C1(J)=AAAR=C2(J)*ABAR=C3(J)*ACAR	SUM	58
	GO TO 30	SUM	59
20	CONTINUE	SUM	60
	C3(J)=C3(J=1)	SUM	61
	C2(J)=C2(J=1)	SUM	62
	C1(J)=C1(J=1)	SUM	63
30	CONTINUE	SUM	64
	IF (L,EQ,0) RETURN	SUM	65
C		SUM	66
C	COMPUTE 1ST DERIV. OF X VS S CURVE.	SUM	67
C		SUM	68

APPENDIX

	DO 40 J=NX,NY	SUM	69
	S1(J)=C2(J)+2*C3(J)*X(J)	SUM	70
40	CONTINUE	SUM	71
	DO 50 J=1,LN	SUM	72
	K=NX+LN+J-1	SUM	73
	S1(K)=C2(NX)+2*C3(NX)*X(K)	SUM	74
	I=J+NY	SUM	75
	S1(I)=C2(NY)+2*C3(NY)*X(I)	SUM	76
50	CONTINUE	SUM	77
	RETURN	SUM	78
	END	SUM	79=
	SUBROUTINE NEWBL (VBLC,X,YO,S,NAZ,NN,TWW,Z,PT,TT,ANA,GA,U,S1,CFA,HNBL		1
	1IX,THRR,AM,DEL1,RET,THR,DBSTAR,DELS1,H51,TAW51,PTB51,FNN51,H1,DRAG)NBL		2
C		NBL	3
	DIMENSION H1(1), DBSTAR(201), U(1), VBLC(1), X(1), YO(1), S(1), S1(NBL		4
	11), CFA(201), AM(1), THR(1), DEL1(1), RET(1), DELS1(1), H51(1), TANBL		5
	2W51(1), PTB51(1), FNN51(1), BC(201), CPB(201), YBAR(201)		6
	COMMON /SAVE/ SB(201),SC(201),Y(201),XIN		7
C		NBL	8
	NBJ=NN=NAZ+1	NBL	9
	DO 10 I=1,NN	NBL	10
10	VBLC(I)=U(I)	NBL	11
	DO 20 KJ=1,NBJ	NBL	12
	NJA=NAZ+KJ-1	NBL	13
	CPB(KJ)=VBLC(NJA)	NBL	14
	YBAR(KJ)=X(NJA)	NBL	15
	BC(KJ)=YO(NJA)	NBL	16
20	CONTINUE	NBL	17
	ABC=PT	NBL	18
	CALL BLC (PT,TT,YBAR,BC,CPB,TWW,Z,NBJ,DBSTAR,THRR,HIX,H1,CFA,AM,GA,	NBL	19
	1DEL1,RET,THR,DELS1,H51,TAW51,PTB51,FNN51,DRAG)	NBL	20
	PT=ABC	NBL	21
	IF (NAZ) 60,60,30	NBL	22
30	DO 40 NJ=1,NBJ	NBL	23
	NAJ=NAZ+NJ-1	NBL	24
	CPB(NAJ)=CFA(NJ)	NBL	25
	BC(NAJ)=AM(NJ)	NBL	26
	YBAR(NAJ)=DBSTAR(NJ)	NBL	27
40	CONTINUE	NBL	28
	DO 50 NJ=1,NAZ	NBL	29
	YBAR(NJ)=DBSTAR(2)	NBL	30
	CPB(NJ)=CFA(2)	NBL	31
	BC(NJ)=AM(1)	NBL	32
50	CONTINUE	NBL	33
60	CONTINUE	NBL	34
	DO 100 I=1,NN	NBL	35
	CFA(I)=CPB(I)	NBL	36
	AM(I)=BC(I)	NBL	37
	DBSTAR(I)=YBAR(I)	NBL	38
	IF (S(I)=.1E=8) 70,70,80	NBL	39
70	RCO=0.0	NBL	40
	GO TO 90	NBL	41
80	CONTINUE	NBL	42
	RCO=S1(I)/(2.0*SQRT(3.1416*S(I)))	NBL	43
	RCO=ABS(RCO)	NBL	44
90	CONTINUE	NBL	45
	DEV=RCO**2+1.0	NBL	46
	SUQ=1.0/DEV	NBL	47
	AMB=SQRT(SUQ)	NBL	48
	DBSTAR(I)=DBSTAR(I)/AMB	NBL	49
100	CONTINUE	NBL	50
	IF (ANA,GT.1.) GO TO 120	NBL	51
	DO 110 I=1,NN	NBL	52
	SC(I)=0.	NBL	53
110	SR(I)=0.	NBL	54
120	ABC=0.	NBL	55

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	DO 140 I=1,NN	NBL 56
	IF (ANA,LE,3.) GO TO 130	NBL 57
	DSTAR(I)=.25*DSTAR(I)+.5*8B(I)+.25*8C(I)	NBL 58
130	8C(I)=8B(I)	NBL 59
	8B(I)=DSTAR(I)	NBL 60
140	CONTINUE	NBL 61
	RETURN	NBL 62
	END	NBL 63
	SUBROUTINE BLC (PT,TT,XV,YV,V,TWW,Z,NN,DSTAR,THRR,HIX,HICH,CFA,AM,BLC	1
	IGAM,DEL1,RET,THB,DELS1,H51,TAW51,PTB51,FNN51,DRAG)	BLC 2
C		BLC 3
	DIMENSION AM(1),XV(1),YV(1),V(1),DSTAR(1),HICH(1),DEL1(1),CBLC	4
	1FA(201),DELS1(1),H51(1),TAW51(1),PTB51(1),FNN51(1),RET(1),TBLC	5
	2HB(1),X(201),Y(201)	BLC 6
C		BLC 7
	TF(X)=1+.2*X**2	BLC 8
	PF(X)=TF(X)**3.5	BLC 9
	TAW(X)=1+.178*X**2	BLC 10
	H2(X)=(X*(X+1.))**2)/2.	BLC 11
	H3(HI)=2.*HIF/(HI+1.)*(HI-1.)-.5*((HI+1.)*.3/4.3)	BLC 12
C		BLC 13
	G1=(GAM-1.)/2.	BLC 14
	G2=GAM/(1.-GAM)	BLC 15
	DSTAR(1)=HIX*THRR	BLC 16
	THR=THRR	BLC 17
	IF (THR,LT,.00001) THR=.00001	BLC 18
	DO 10 I=1,NN	BLC 19
	X(I)=XV(I)/Z	BLC 20
	AM(I)=V(I)/49./SQRT(TT=V(I)**2/.48/776./32.17)	BLC 21
10	Y(I)=YV(I)/Z	BLC 22
	IF (AM(1),LE,0.00001) AM(1)=AM(2)	BLC 23
	PT=PT*Z*Z	BLC 24
	L=1	BLC 25
	HIF=1.3	BLC 26
	U=2.27E-08*TT**1.5/(TT+198.6)	BLC 27
	AU=SQRT(1.4/1716./TT)*PT/U	BLC 28
	M=NN-1	BLC 29
	THTR=THR/TF(AM(1))**3/Z	BLC 30
	HM=1.	BLC 31
	DRAG=0.0	BLC 32
	THT=0.	BLC 33
	HD=0.	BLC 34
	IF (HIX) 20,20,30	BLC 35
20	HI=1.3	BLC 36
	GO TO 40	BLC 37
30	HI=HIX	BLC 38
40	DO 230 I=1,M	BLC 39
	DM=AM(I+1)-AM(I)	BLC 40
	DY=Y(I+1)-Y(I)	BLC 41
	DX=X(I+1)-X(I)	BLC 42
	XXN=N	BLC 43
	DLM=ABS(DM/AM(I)+DM/AM(I+1))+.001*DX/THR*Z+XXN*HD	BLC 44
	IF (Y(I+1)) 50,60,50	BLC 45
50	DLM=DLM+ABS(DY/Y(I+1))	BLC 46
60	N=30.*DLM	BLC 47
	IF (N=10) 70,70,80	BLC 48
70	N=10	BLC 49
80	IF (30=N) 90,100,100	BLC 50
90	N=30	BLC 51
100	S=N	BLC 52
	DX=DX/S	BLC 53
	YY=Y(I)-DY/2./S	BLC 54
	DY=DY/S	BLC 55
	AA=AM(I)-DM/2./S	BLC 56
	DM=DM/S	BLC 57
	DL=SQRT(DX**2+DY**2)	BLC 58

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	N=8	BLC 59
	DO 220 J=1,N	BLC 60
	YY=YY+DY	BLC 61
	AA=AA+DM	BLC 62
	TE=TT/TF(AA)	BLC 63
	TAW=TE*TAWC(AA)	BLC 64
	IF (TWW) 110,110,120	BLC 65
110	TW=TAW	BLC 66
	GO TO 130	BLC 67
120	TW=TWW	BLC 68
130	TR=(TAW+TE)/2,+22*TE*(TAWC(AA)=1,)	BLC 69
	TR=TR+(TW-TAW)/2,	BLC 70
	THH=THTR	BLC 71
	HH=HI	BLC 72
	THTR=(THH+THT/2,)	BLC 73
	HI=HD/2,+HH	BLC 74
	AY=ABS(THTR)	BLC 75
	A=.123*EXP(-1.561*HI)*(AA*AU*AY)**(=.268)*(TE/TR)**.732*(TE/TT)**3	BLC 76
	1.268	BLC 77
	AA*(TT/TR)**.0645	BLC 78
	THT=+A*DL=THTR*DM/AA*(2,+HI+(TW/TT=1,)*HIF/HM)	BLC 79
	THT=(THTR*(=DY/YY)+THT)	BLC 80
	THTR=(THH+THT/2,)	BLC 81
	HD=DM/AA*H2(HI)*(HI=1,+(TW/TT=1,)*H3(HI)/HM)	BLC 82
	HF=(HI=(HI+1,)*.36*(EXP(2.9*(HI=1,))=1./HI))	BLC 83
	HF=HF*(HI**2=1,+EXP(20.=20,*HI)*.1)	BLC 84
	HD=HD+HF/THTR*A*DL	BLC 85
	IF (ABS(HD)/HI=.2) 150,150,140	BLC 86
140	HD=.2*HD/ABS(HD)*HI	BLC 87
150	HI=HH+HD	BLC 88
	THTR=(THH+THT)	BLC 89
	IF (HI) 160,160,170	BLC 90
160	HI=.5	BLC 91
	HD=0.	BLC 92
	GO TO 190	BLC 93
170	CONT=2.0	BLC 94
	IF (HI=CONT) 190,190,180	BLC 95
180	HI=CONT	BLC 96
	HH=CONT	BLC 97
	HD=0.	BLC 98
190	TFA=TF(AA)	BLC 99
	THR=THTR*TFA**3	BLC 100
	CF=2,*A*TFA**3	BLC 101
	IF (J+I=2) 200,200,210	BLC 102
200	RV=PT/PF(AA)*SQRT(1.4/TE/1716,)*AA	BLC 103
210	HEAD=0.7*(AA*AA)*PT	BLC 104
	HEAD=HEAD/((1.0+(0.2*(AA*AA)))*3.5)	BLC 105
	CFQ=CF*HEAD	BLC 106
	DRAG=DRAG+(6.2832*CFQ*YY*DX)	BLC 107
	RV=PT/PF(AA)*SQRT(1.4/TE/1716,)*AA	BLC 108
	HTR=HI+(TW/TT=1,)*HIF/HM	BLC 109
	H=HTR*TFA+.2*AA**2	BLC 110
	U=2.27E=08*TE**1.5/(TE+198.6)	BLC 111
	RE=RV*THR/U	BLC 112
	THR=THR*Z	BLC 113
	DEL=THR*H	BLC 114
	DSTAR(I+1)=DEL	BLC 115
220	CONTINUE	BLC 116
	FNN=2.0/(HI=1,)	BLC 117
	FM1=1,+G1*(AM(I+1)**2)	BLC 118
	FM2=FM1-1.0	BLC 119
	FM3=GAM*(AM(I+1)**2)/2,	BLC 120
	TTT=THR/FM1**3	BLC 121
	DDD=TTT*(1,+FNN)*(2,+FNN)/FNN	BLC 122
	DSTA=DEL/FM1**3	BLC 123
	AGB=TTT+DSTA=DDD	BLC 124

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DEL1(I+1)=DDD*(FM1**4)+AGB*FM2*(FM1**3)
PTBAR=FM1**G2*(1,+FM3*(1,=(DEL+THR)/DEL1(I+1)))
L=L+1
DELS1(L)=DEL
H51(L)=H
TAW51(L)=TAW
PTB51(L)=PTBAR
FNNS1(L)=FNNS
CFA(I+1)=CF
HICH(I+1)=HI
RET(I+1)=RE
THR(I+1)=THR
230 CONTINUE
CFA(1)=CFA(2)
RETURN
END
SUBROUTINE FIX (NMIN,NN,CP,MI)
C
C DIMENSION CP(1)
C
MI=NMIN
PMIN=CP(NMIN)
DO 20 I=NMIN,NN
IF (CP(I)=PMIN) 10,20,20
10 PMIN=CP(I)
MI=I
20 CONTINUE
RETURN
END
SUBROUTINE SEPA (X,R,CP,EMI,CF1,DEL1,THETA1,RETH1,CP1,NBN,NEN,CPRTSPA
1)
C
C DIMENSION X(201), R(201), CP(201), CPD(201), C1(201), C2(201), C3(SPA
1201), CPRT(4), YY(201), PSP1(201), E(201)
COMMON /COEFF/ X2(201),X3(201),X4(201)
COMMON /BCB/ TTRAT(201),PTRAT(201),PTRNS(201),URAT(201),EM(201),WRSPA
1(201),PHIR(201),TWTTE,GAMMA,BLMN,BLMON,VWVE1,C,DSD,DDSD,BK,EME1,SHSPA
2FAC,SIG1,SIGMA1,SIGS1
C
ASIN(X)=ATAN(X/SQRT(1-X*X))
C
EMI=0.0
BTAIL=0.0
ELLBT=0.0
ENTMAS=0.0
ENPRES=3.0
CFWCF1=1.0
GAMMA=1.4
GAM=GAMMA
EMI=SQRT(5,*(1,+2*EMI*EMI)*(1,+7*EMI*EMI*CP1)**((1,-GAM)/GAM)-1SPA
1.))
EME1=EMI
EMIEMI=EMI/EMI
CP8G=CP1+200,*CF1*(1,+(GAM/2,)*EMI*EMI*CP1)*EMIEMI*EMIEMI
C
C CALCULATE CP(SEP) AND P(SEP)/PI USING GOLDSCHMEID METHOD
C
PSPIG=1,+5*GAM*CP8G*EMI*EMI
PSPIG=PSPIG/(1,+5*GAM*CP1*EMI*EMI)
C
C STRATFORDS SEPARATION CALCULATION
C
NX=NBN+2
NY=NEN+2
LZ=5
L=1

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BLC 125
BLC 126
BLC 127
BLC 128
BLC 129
BLC 130
BLC 131
BLC 132
BLC 133
BLC 134
BLC 135
BLC 136
BLC 137
BLC 138
BLC 139
BLC 140
FIX 1
FIX 2
FIX 3
FIX 4
FIX 5
FIX 6
FIX 7
FIX 8
FIX 9
FIX 10
FIX 11
FIX 12
FIX 13
SPA 1
SPA 2
SPA 3
SPA 4
SPA 5
SPA 6
SPA 7
SPA 8
SPA 9
SPA 10
SPA 11
SPA 12
SPA 13
SPA 14
SPA 15
SPA 16
SPA 17
SPA 18
SPA 19
SPA 20
SPA 21
SPA 22
SPA 23
SPA 24
SPA 25
SPA 26
SPA 27
SPA 28
SPA 29
SPA 30
SPA 31
SPA 32
SPA 33
SPA 34
SPA 35
SPA 36
SPA 37

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APPENDIX

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CALL SUMA (NX,NY,LZ,X,CP,C1,C2,C3,CPD,L) SPA 38
RE=RETH1*(X(NSN)/THETA1) SPA 39
SS=DEL1/(.37*RE**(-.2)) SPA 40
RHS=.39*(10.**(-6.)*RE)**(+.1) SPA 41
DIF=0 SPA 42
JK=0 SPA 43
DO 100 I=NSN,NEN SPA 44
DX=X(I)-X(NSN) SPA 45
S=SS+DX SPA 46
IF (CPD(I)) 90,90,10 SPA 47
10 CONTINUE SPA 48
HLS=CP(I)*(8*CPD(I))**.5 SPA 49
DIF=RHS-HLS SPA 50
IF (JK=1) 20,40,40 SPA 51
20 CONTINUE SPA 52
JK=1 SPA 53
LNZ=0 SPA 54
IF (DIF) 30,30,40 SPA 55
LNZ=1 SPA 56
40 CONTINUE SPA 57
IF (LNZ) 50,50,70 SPA 58
50 IF (DIF) 60,60,90 SPA 59
60 IA=I SPA 60
GO TO 110 SPA 61
70 IF (DIF) 90,80,80 SPA 62
80 IA=I SPA 63
GO TO 110 SPA 64
90 CONTINUE SPA 65
100 CONTINUE SPA 66
GO TO 120 SPA 67
110 CONTINUE SPA 68
CPSS=CP(IA=1) SPA 69
CPRT(4)=CPSS SPA 70
120 CONTINUE SPA 71
C SPA 72
C CALCULATE CP(SEP) AND P(SEP)/PI USING MODIFIED PAGE METHOD SPA 73
C SPA 74
CPSP=CP1+.38*(1.+(GAM/2.)*EMI*EMI*CP1)*EMI*EMI SPA 75
C SPA 76
C EVALUATE PROFILE PARAMETERS AT STATION 1 SPA 77
C SPA 78
BK=.4 SPA 79
C=.5,1 SPA 80
TWYTE=1. SPA 81
SIG1=.2*EMI*EMI SPA 82
SIGMA1=SIG1/(1.+.SIG1) SPA 83
SIGS1=SQRT(SIGMA1) SPA 84
FSIG1=(ASIN(SIGS1))/SIGS1 SPA 85
VWVE1=(1.+.SIG1)**1.76 SPA 86
UTUES1=SQRT((CF1/2.)*(SIGMA1/(1.-SIGMA1)))/ASIN(SQRT(SIGMA1)) SPA 87
REDEL1=RETH1*DEL1/THETA1 SPA 88
PX1=.5*(1.-UTUES1)*((1./BK)*ALOG(REDEL1*ABS(UTUES1)*FSIG1/VWVE1)+C) SPA 89
1) SPA 90
C SPA 91
C DETERMINE B,L. PROFILE PROPERTIES AT STATION 1 SPA 92
C SPA 93
CALL PRFL (UTUES1,PX1,EM1,1,0,2,YY) SPA 94
C SPA 95
C DETERMINE UPSTREAM BOUNDARY LAYER INTEGRAL PROPERTIES SPA 96
C SPA 97
CALL FLUX (101,YY,EM1) SPA 98
RETH1=REDEL1*DDSD SPA 99
AMASS1=BLMN SPA 100
AMOM1=BLMON SPA 101
C SPA 102
C START SOLUTION PROCEDURE, ASSUME P8/PI SPA 103

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APPENDIX

	DOD=DDSD	SPA 104
	DDOD=DDSD	SPA 105
	UTUESB=0.	SPA 106
	PSP1(1)=PSP1G	SPA 107
	P1PT=(1.+2*EM1*EM1)**(GAM/(1.=GAM))	SPA 108
	FEMS1=(PSP1(1)*P1PT)**((1.=GAM)/GAM)=1.	SPA 109
	FEMS2=P1PT**((1.=GAM)/GAM)=1.	SPA 110
	FMS=EM1*SQRT(FEMS1/FEMS2)	SPA 111
	PXS=0.5	SPA 112
	J=1	SPA 113
	GO TO 140	SPA 114
130	J=J+1	SPA 115
	IF (J.EQ.80) GO TO 290	SPA 116
	PSP1(J)=PSP1(J-1)=0.1	SPA 117
	FEMS1=(PSP1(J)*P1PT)**((1.=GAM)/GAM)=1.	SPA 118
	FEMS2=P1PT**((1.=GAM)/GAM)=1.	SPA 119
	FMS=EM1*SQRT(FEMS1/FEMS2)	SPA 120
	PXS=0.5	SPA 121
C		SPA 122
C	ENTRAINMENT AND FRICTION CONSTANTS	SPA 123
C		SPA 124
	IF (ENTMAS.GT.0.) GO TO 270	SPA 125
C		SPA 126
C	CALCULATE ENTRAINMENT FROM GREENS THEOREM	SPA 127
C		SPA 128
140	ELDEL1=ELLBT*BTAIL/DEL1	SPA 129
	APIPI=1.0+.7*EM1*EM1*CP1	SPA 130
	PGX=(1.0+.7*EM1*EM1*CP(NSN=1))/APIPI	SPA 131
	IJR=NEN	SPA 132
	DO 230 II=NSN,NEN	SPA 133
	PGX1=PGX	SPA 134
	PGX=(1.0+.7*EM1*EM1*CP(II))/APIPI	SPA 135
	IF (II=NSN) 150,150,160	SPA 136
150	PGX1=PGX	SPA 137
	GO TO 230	SPA 138
160	CONTINUE	SPA 139
	DPG=PGX-PSP1(J)	SPA 140
	IF (DPG) 190,170,170	SPA 141
170	IF (PGX1-PSP1(J)) 180,220,220	SPA 142
180	DBG=ABS(PSP1(J)-PGX1)	SPA 143
	DTG=ABS(PGX-PGX1)	SPA 144
	GO TO 210	SPA 145
190	IF (PGX1-PSP1(J)) 220,220,200	SPA 146
200	DBG=ABS(PSP1(J)-PGX1)	SPA 147
	DTG=ABS(PGX-PGX1)	SPA 148
210	AL=X(II=1)-X(NSN)+(DBG/DTG)*(X(II)-X(II=1))	SPA 149
	IJB=II-1	SPA 150
	GO TO 240	SPA 151
220	CONTINUE	SPA 152
230	CONTINUE	SPA 153
	AL=X(NEN)-X(NSN)	SPA 154
240	ELDEL1=AL/DEL1	SPA 155
	IF (J.LE.2) GO TO 260	SPA 156
	TOTAL=0.	SPA 157
	DO 250 II=NSN,IJB	SPA 158
250	TOTAL=TOTAL+CP(II)	SPA 159
	CPAVE=TOTAL/(IJB-NSN+1)	SPA 160
	CPCV=(PSP1(J)*(1.+7*EM1*EM1*CP1)=1.)/(7*EM1*EM1)	SPA 161
	ENPRES=(CPCV=CP1)/(CPAVE=CP1)	SPA 162
260	CONTINUE	SPA 163
	FENT1=(1.-DOD)/DDOD=3.	SPA 164
	FENT2=FENT1**(-0.6169)	SPA 165
	FENT3=1.-DOD	SPA 166
	AMEMBL=ELDEL1*.0299+FENT2/FENT3	SPA 167
	GO TO 280	SPA 168
270	AMEMBL=ENTMAS	SPA 169

APPENDIX

280	CONTINUE	SPA 170
	CALL PRFL (UTUESS,PXS,EMS,PSP1(J),1,YY)	SPA 171
	CALL FLUX (101,YY,EMS)	SPA 172
	AMASSS=BLMN	SPA 173
	AMOMS=BLMON	SPA 174
	ALHS1=(1./PSP1(J))*(1.+AMEMBL)*EM1/EMS	SPA 175
	ALHS2=SQRT((1.+2*EM1*EM1)/(1.+2*EMS*EMS))	SPA 176
	ALHS3=AMASSS1/AMASSS	SPA 177
	ALHS=ALHS1+ALHS2*ALHS3	SPA 178
	RHS1=(1./ENPRES)*(PSP1(J)=1.)	SPA 179
	RHS2=1.4*EM1*EM1*AMOM1	SPA 180
	RHS3=1.4*AMEMBL*EM1*EM1*AMASSS1	SPA 181
	RHS4=.5*CF1*CFWCF1*.70*EM1*EM1*ELDEL1	SPA 182
	RHS5=1.+(1./ENPRES)*(PSP1(J)=1.)=PSP1(J)	SPA 183
	RHS6=PSP1(J)*1.4*EMS*EMS*AMOMS	SPA 184
	RHS=(RHS1-RHS2-RHS3+RHS4)/(RHS5-RHS6)	SPA 185
	E(J)=RHS=ALHS	SPA 186
	TEST=ABS(E(J))	SPA 187
	IF (TEST,LE,0.00001) GO TO 300	SPA 188
	IF (J,EG,1) GO TO 130	SPA 189
	IF (ABS(E(J)-E(J=1)),LE,.001*ABS((E(J)+E(J=1))*5)) GO TO 300	SPA 190
	SLOPE=(E(J=1)-E(J))/(PSP1(J=1)-PSP1(J))	SPA 191
	PSP1(J+1)=PSP1(J)+E(J)/SLOPE	SPA 192
	IF (PSP1(J+1),LT,0.) GO TO 130	SPA 193
	FEMS1=(PSP1(J+1)*PIPT)**((1.=GAM)/GAM)=1.	SPA 194
	IF (FEMS1,LE,0.) GO TO 130	SPA 195
	EMS=EM1*SQRT(FEMS1/FEMS2)	SPA 196
	J=J+1	SPA 197
	IF (J,EG,80) GO TO 290	SPA 198
	GO TO 140	SPA 199
290	CONTINUE	SPA 200
	GO TO 310	SPA 201
C		SPA 202
C	SOLUTION OBTAINED	SPA 203
C		SPA 204
C	DETERMINE B,L, PROPERTIES AT SEPARATION	SPA 205
300	CALL PRFL (UTUESS,PXS,EMS,PSP1(J),2,YY)	SPA 206
C		SPA 207
C	DETERMINE DOWNSTREAM B,L, INTEGRAL PROPERTIES	SPA 208
C		SPA 209
C	CALL FLUX (101,YY,EMS)	SPA 210
C		SPA 211
C	DETERMINE DEL3/DEL1 AND SEPARATION PRESSURES	SPA 212
C		SPA 213
C	PSP1F=PSP1(J)	SPA 214
C	CPCV=(PSP1F*(1.+7*EM1*EM1*CP1)=1.)/(7*EM1*EM1)	SPA 215
C		SPA 216
C	RESULTS FROM CONTROL VOLUME APPROACH	SPA 217
C		SPA 218
C	CPRT(1)=CPCV	SPA 219
C		SPA 220
C	RESULTS FROM GOLDSCHMEID	SPA 221
C		SPA 222
C	CPRT(2)=CPSG	SPA 223
C		SPA 224
C	RESULTS FROM MODIFIED PAGE METHOD	SPA 225
C		SPA 226
C	CPRT(3)=CPSP	SPA 227
310	CONTINUE	SPA 228
	RETURN	SPA 229
	END	SPA 230
	SUBROUTINE PRFL (UTUEST,PX,EME,PKP1,IOPT,YY)	PRF 1
C		PRF 2
C	SUBROUTINE TO CALCULATE DISTRIBUTIONS OF PROPERTIES	PRF 3
C		PRF 4
C	DIMENSION YY(201)	PRF 5

APPENDIX

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COMMON /BCB/ TTRAT(201),PTRAT(201),PTRNS(201),URAT(201),EM(201),WRPRF 6
1(201),PHIR(201),TWTTE,GAMMA,BLMN,BLMON,VWVE1,C,DSD,DDSD,BK,EME1,SHPRF 7
2FAC,SIG1,SIGMA1,SIGS1 PRF 8
C PRF 9
PI=3.1415927 PRF 10
EXP2=GAMMA/(GAMMA-1.) PRF 11
EXP3=1./(GAMMA-1.) PRF 12
GAM1=(GAMMA-1.)/2. PRF 13
GAM2=GAMMA+1. PRF 14
GAM3=GAMMA-1. PRF 15
G1=EME*EME PRF 16
SIGMA=GAM1*G1/(1.+GAM1*G1) PRF 17
SIGG1=SQRT(SIGMA) PRF 18
SIGG2=1./SIGG1 PRF 19
SIGG3=ATAN(SIGG1/SQRT(1-SIGG1*SIGG1)) PRF 20
URAT(1)=0. PRF 21
TTRAT(1)=TWTTE PRF 22
EM(1)=0. PRF 23
YY(1)=0. PRF 24
PTRAT(1)=(1./(1.+GAM1*EME1*EME1))*EXP2*PKP1 PRF 25
PTRNS(1)=PTRAT(1) PRF 26
DO 40 I=2,101 PRF 27
AI=I-1 PRF 28
YY(I)=AI/100. PRF 29
URAT(I)=SIGG2*8IN(SIGG3=SIGG3*PX*(1.+COS(PI*YY(I)))+(1./BK)*UTUESTPRF 30
1*SIGG3*ALOG(YY(I))) PRF 31
TTRAT(I)=TWTTE+(1.-TWTTE)*ABS(URAT(I)) PRF 32
U2=URAT(I)*URAT(I) PRF 33
EM(I)=SQRT(U2/((1./G1+GAM1)*TTRAT(I)+GAM1*U2)) PRF 34
IF (URAT(I).LE.0.) EM(I)=1.*EM(I) PRF 35
IF (IOPT=1) 40,40,10 PRF 36
C PRF 37
C CALCULATION OF TOTAL PRESSURE DOWNSTREAM OF NORMAL SHOCK PRF 38
C PRF 39
C 10 PTRAT(I)=((1.+GAM1*EM(I)*EM(I))/(1.+GAM1*EME1*EME1))*EXP2*PKP1 PRF 40
IF (EM(I)=1.) 20,20,30 PRF 41
20 PTRNS(I)=PTRAT(I) PRF 42
GO TO 40 PRF 43
30 PTRNS(I)=(GAM2*EM(I)*EM(I)/2./((1.+GAM1*EME1*EME1))*EXP2*(GAM2/(2,PRF 44
1+GAMMA*EM(I)*EM(I)=GAM3))*EXP3*PKP1 PRF 45
40 CONTINUE PRF 46
RETURN PRF 47
END PRF 48
SUBROUTINE FLUX (K,Y,EME) FLU 1
C FLU 2
C SUBROUTINE TO CALCULATE MASS AND MOMENTUM FLUX OF B,L. FLU 3
C ALSO CALCULATES DISPLACEMENT AND MOMENTUM THICKNESSES FLU 4
C FLU 5
DIMENSION Y(201),YY(201),BLMR(201),BLMOR(201) FLU 6
COMMON /BCB/ TTRAT(201),PTRAT(201),PTRNS(201),URAT(201),EM(201),WRFLU 7
1(201),PHIR(201),TWTTE,GAMMA,BLMN,BLMON,VWVE1,C,DSD,DDSD,BK,EME1,SHFLU 8
2FAC,SIG1,SIGMA1,SIGS1 FLU 9
C FLU 10
DO 10 I=1,K FLU 11
PRAT=1. FLU 12
TTOT=1.+(GAMMA-1.)*EM(I)*EM(I)/2. FLU 13
YTOTE=1.+(GAMMA-1.)*EME*EME/2. FLU 14
TOTE=TTOTE*TTRAT(I)/TTOT FLU 15
RHRAT=PRAT/TOTE FLU 16
BLMR(I)=RHRAT*URAT(I) FLU 17
BLMOR(I)=BLMR(I)*URAT(I) FLU 18
IF (URAT(I).LE.0.) BLMOR(I)=BLMOR(I) FLU 19
YY(I)=Y(I) FLU 20
CONTINUE FLU 21
DO 20 I=1,K FLU 22
CALL INTEG (I,YY,BLMR,AREA1) FLU 23

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APPENDIX

	CALL INTEG (I,YY,BLMOR,AREA2)	FLU 24
	WR(I)=AREA1	FLU 25
	PHIR(I)=AREA2	FLU 26
20	CONTINUE	FLU 27
	BLMN=AREA1	FLU 28
	BLMON=AREA2	FLU 29
	DSO=1.=BLMN	FLU 30
	DDSD=BLMN=BLMON	FLU 31
	SHFAC=DSO/DDSD	FLU 32
	RETURN	FLU 33
	END	FLU 34
	SUBROUTINE INTEG (K,Y,Z,AREA)	INT 1
C		INT 2
C	INTEGRATION USING SIMPSON'S RULE	INT 3
C		INT 4
	DIMENSION Y(201), Z(201)	INT 5
C		INT 6
	IF (K,GE,5) GO TO 10	INT 7
	IF (K,EQ,1) GO TO 80	INT 8
	IF (K,EQ,2) GO TO 90	INT 9
	IF (K,EQ,3) GO TO 100	INT 10
	IF (K,EQ,4) GO TO 110	INT 11
10	AK=K	INT 12
	BK=AK/2.	INT 13
	KK=BK	INT 14
	CK=KK	INT 15
	IF (BK=CK) 30,20,30	INT 16
C		INT 17
C	K IS EVEN	INT 18
C		INT 19
20	N=K-1	INT 20
	GO TO 40	INT 21
C		INT 22
C	K IS ODD	INT 23
C		INT 24
30	N=K	INT 25
40	ODD=0.	INT 26
	EVEN=0.	INT 27
	J=N/3	INT 28
	DO 50 I=2,J,2	INT 29
	EVEN=EVEN+Z(I)	INT 30
	ODD=ODD+Z(I+1)	INT 31
50	CONTINUE	INT 32
	AREA=(Y(2)-Y(1))/3.*(Z(1)+Z(N)+4.*(EVEN+Z(N-1))+2.*ODD)	INT 33
	IF (BK=CK) 70,60,70	INT 34
C		INT 35
C	K IS EVEN	INT 36
C		INT 37
60	AREA=AREA+(Y(K)-Y(K-1))*(Z(K)+Z(K-1))/2.	INT 38
	RETURN	INT 39
C		INT 40
C	K IS ODD	INT 41
C		INT 42
70	RETURN	INT 43
80	AREA=0.	INT 44
	RETURN	INT 45
90	AREA=(Y(2)-Y(1))*(Z(2)+Z(1))/2.	INT 46
	RETURN	INT 47
100	AREA=(Y(2)-Y(1))*(Z(3)+4.*Z(2)+Z(1))/3.	INT 48
	RETURN	INT 49
110	AREA=(Y(2)-Y(1))*(Z(4)+Z(3))/2.+(Z(3)+4.*Z(2)+Z(1))/3.)	INT 50
	RETURN	INT 51
	END	INT 52
	SUBROUTINE SEP (NN,XA,RAD,CP,XSEP,AMIN,GAMMA,TTO,PT,RADO,DBSTAR,Y,ASEP	SEP 1
C	INA,IJET,NEXT,RI,UJ,C)	SEP 2
		SEP 3

APPENDIX

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DIMENSION DSTAR(1), RADO(1), XA(1), RAD(1), CP(1), Y(1), X834(201)SEP 4
1, Y834(201), RI(1), UJ(1) SEP 5
COMMON /SAVE/ SB(201),SC(201),YJB(201),XINS,XSEPSV(20),DELSV(20),YSEP 6
1OUT(201) SEP 7
C SEP 8
DO 10 I=1,NN SEP 9
10 Y(I)=RAD(I) SEP 10
IF (XSEP.GT,0.) GO TO 30 SEP 11
DO 20 I=1,NN SEP 12
20 RADO(I)=Y(I)+DSTAR(I) SEP 13
GO TO 120 SEP 14
30 CONTINUE SEP 15
DO 40 I=1,NN SEP 16
IS=I SEP 17
IF (XSEP=XA(I)) 50,40,40 SEP 18
40 RADO(I)=Y(I)+DSTAR(I) SEP 19
GO TO 120 SEP 20
50 RTAN=(Y(IS=1)-Y(IS))/(XA(IS)-XA(IS=1)) SEP 21
RTAN=ATAN(RTAN) SEP 22
YSEP=Y(IS)+(XSEP-XA(IS))*((Y(IS=1)-Y(IS))/(XA(IS=1)-XA(IS))) SEP 23
IC=1 SEP 24
X834(1)=XSEP SEP 25
Y834(1)=YSEP SEP 26
DO 60 I=IS,NN SEP 27
IC=IC+1 SEP 28
60 X834(IC)=XA(I) SEP 29
Y834(IC)=Y(I) SEP 30
RADDEG=180./3.1415926 SEP 31
RTAN=RTAN*RADDEG SEP 32
NEIN=NEXT=IS+2 SEP 33
IJJB=0 SEP 34
IF (ANA,GE,1.) IJJB=IJET SEP 35
IF (ANA,GE,9.) GO TO 70 SEP 36
CALL B834 (IC,AMIN,GAMMA,TTO,PT,RTAN,X834,Y834,CP(IS=1),YOUT,IJJB,SEP 37
1NEIN,RI,UJ,C,ANA) SEP 38
70 CONTINUE SEP 39
IF (ANA,EQ,1) GO TO 100 SEP 40
JB=2 SEP 41
DO 90 I=IS,NN SEP 42
Y(I)=YOUT(JB) SEP 43
RADO(I)=YOUT(JB)+DSTAR(I) SEP 44
IF (Y(I),LT,Y(I=1)) GO TO 80 SEP 45
IF (RADO(I),GT,RADO(I=1)+Y(I)-Y(I=1)) RADO(I)=RADO(I=1)+Y(I)-Y(I=1)SEP 46
1) SEP 47
GO TO 90 SEP 48
80 IF (RADO(I),GT,RADO(I=1)) RADO(I)=RADO(I=1) SEP 49
90 JB=JB+1 SEP 50
GO TO 120 SEP 51
100 CONTINUE SEP 52
JB=2 SEP 53
API=2.*Y(IS)+DSTAR(IS)+DSTAR(IS)**2 SEP 54
DO 110 I=IS,NN SEP 55
Y(I)=YOUT(JB) SEP 56
ARGF=4.0*Y(I)**2+4.0*API SEP 57
DSTAR(I)=(=2.*Y(I)+8GRT(ARGF))/2.0 SEP 58
RADO(I)=YOUT(JB)+DSTAR(I) SEP 59
IF (RADO(I),GT,RADO(I=1)) RADO(I)=RADO(I=1) SEP 60
110 JB=JB+1 SEP 61
120 CONTINUE SEP 62
C WRITE (6,150) ANA SEP 63
C WRITE (6,130) XSEP,YSEP SEP 64
C WRITE (6,140) (I,XA(I),RAD(I),Y(I),DSTAR(I),RADO(I),I=1,NN) SEP 65
RETURN SEP 66
C SEP 67
C SEP 68
END SEP 69=

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APPENDIX

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SUBROUTINE B834 (NST,FMS,GAMMA,TTO,PT,ABOD,XL,RAD,CPIN,YSTR,IJET,NB83 1
1EXT,RI,UJ,C,ANA) 883 2
C 883 3
C 883 4
C 883 5
COMMON /SAVE/ SB(201),SC(201),Y(201),XINS 883 6
DIMENSION XSTR(201), YSTR(201), H1V(201), UEV(201), UBUEV(201), PSB83 7
1IV(201), P1V(201), AME1V(201), XJET(201), CPIN(1), RI(1), UJ(1), X883 8
2L(201), RAD(201) 883 9
C 883 10
NSEP=1 883 11
NPT=101 883 12
EPBLN=.00001 883 13
DRJDX=.05 883 14
DUMDX=400. 883 15
DELLOC=0. 883 16
ILSV=0 883 17
SLOPL=0. 883 18
DO 10 I=1,20 883 19
10 H1V(I)=0. 883 20
DEGRAD=3.1415926/180. 883 21
DO 20 I=1,NST 883 22
20 XSTR(I)=XL(I) 883 23
YSTR(I)=RAD(I) 883 24
ABOD=ABOD*DEGRAD 883 25
ABODSV=ABOD 883 26
AT=SQRT(GAMMA*32.174*53.35*TTO) 883 27
ISTOP=0 883 28
P8=PT*(1.+(GAMMA=1.)*.5*FMS**2)**(GAMMA/(1.=GAMMA)) 883 29
IF (NSEP.LE.0) NSEP=1 883 30
IL=NSEP=1 883 31
IUE=0 883 32
PSISV=0. 883 33
DO 30 I=NSEP,NST 883 34
30 P1V(I)=P8*(1.+GAMMA*.5*CPIN(I)*FMS**2) 883 35
POWER=(1.=GAMMA)/GAMMA 883 36
AME1V(I)=((P1V(I)/PT)**POWER=1.)*2./((GAMMA=1.)) 883 37
AME1V(I)=SQRT(AME1V(I)) 883 38
40 UEV(I)=AME1V(I)*AT/SQRT(1.+.5*(GAMMA=1.)*AME1V(I)**2) 883 39
DELPSI=.05 883 40
C 883 41
C 883 42
C 883 43
C 883 44
C 883 45
IL=IL+1 883 46
IUE=IUE+1 883 47
P1=P1V(IL) 883 48
P2=P8*(1.+GAMMA*.5*CPIN(IL)*FMS**2) 883 49
POWER=(1.=GAMMA)/GAMMA 883 50
AME1=AME1V(IL) 883 51
AME2=((P2/PT)**POWER=1.)*2./((GAMMA=1.)) 883 52
AME2=SQRT(AME2) 883 53
UE=UEV(IL) 883 54
SIGMA=12.*(1.+.2298*AME1) 883 55
IBAD=0 883 56
I=0 883 57
PSIOLD=.0 883 58
IF (IL.GT.1) PSIOLD=PSIV(IL-1)=DELPSI 883 59
PSIOLD=PSIOLD+DELPSI 883 60
50 CONTINUE 883 61
I=I+1 883 62
C 883 63
C 883 64
C 883 65
CALCULATE M1 883 66
IF (IL.GT.1.OR.I.GT.1) GO TO 60 883 67
XSTR(IL)=XL(IL) 883 68

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YSTR(IL)=RAD(IL)
60 CONTINUE
IF (IL=2) 70,80,90
70 H1=0.
GO TO 90
80 ANGLE1=PSIV(1)
H1=TAN(ANGLE1)*SQRT((XL(2)=XL(1))**2+(RAD(2)=RAD(1))**2)
90 CONTINUE
RHO0=1.
RHO1=1.
RHO2=1.
IF (I,GE,100) GO TO 260
UBUE=0.
ALPJ=(.2090+.0226*AME1+.308*URUE)/SIGMA
ALPHA=PSIOLD=ALPJ
DELTA=PSIOLD/FLOAT(NPT=1)
ICNT=0
100 ICNT=ICNT+1
UBUEO=UBUE
SUM1=0.
SUM2=0.
INTJB=NPT=1

C
C      USE SIMPSON'S RULE TO INTEGRATE THE CONTINUITY EQUATION
C      FOR UB/UE
C
DO 120 J=2,INTJB,2
THETO=DELTA*(J=2)
THET1=DELTA*(J=1)
THET2=DELTA*(J=0)
ARG0=SIGMA*(THETO=ALPHA)
ARG1=SIGMA*(THET1=ALPHA)
ARG2=SIGMA*(THET2=ALPHA)
XERF0=.5*(1.+ERT(ARG0))
XERF1=.5*(1.+ERT(ARG1))
XERF2=.5*(1.+ERT(ARG2))
IF (ICNT,EQ,1) GO TO 110
ANUM1.=(GAMMA=1.)*.5*((1.+UBUE)*XERF0=UBUE)**2*(UE/AT)**2
POWER1./.(GAMMA=1.)
DEN1.=(GAMMA=1.)*.5*(UE/AT)**2
RHO0=(ANUM/DEN)**POWER
ANUM1.=(GAMMA=1.)*.5*((1.+UBUE)*XERF1=UBUE)**2*(UE/AT)**2
RHO1=(ANUM/DEN)**POWER
ANUM1.=(GAMMA=1.)*.5*((1.+UBUE)*XERF2=UBUE)**2*(UE/AT)**2
RHO2=(ANUM/DEN)**POWER
110 CONTINUE
AX0=1.+H1*THETO/(RAD(IL)*PSIOLD)
AX1=1.+H1*THET1/(RAD(IL)*PSIOLD)
AX2=1.+H1*THET2/(RAD(IL)*PSIOLD)
SUM1=SUM1+(DELTA/3.)*(RHO0*XERF0*AX0+4.*RHO1*XERF1*AX1+RHO2*XERF2*
1AX2)
SUM2=SUM2+(DELTA/3.)*(RHO0*(XERF0=1.)*AX0+4.*RHO1*(XERF1=1.)*AX1+R
1HO2*(XERF2=1.)*AX2)
120 CONTINUE
UBUEO=SUM1/SUM2
IF (ICNT,GT,10) GO TO 130
IF (ABS(UBUEO=UBUE),GT,ABS(.001*(UBUEO+UBUE)*.5)) GO TO 100

C
C      THETA ITERATION
C
130 THETA=0.
IF (UBUE,GT,1.0) UBUE=1.0
ICNT=0
DELTH=DELTA
RIGHT=2.*UBUE/(1.+URUE)=1.
140 ARG=SIGMA*(THETA=ALPHA)

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	ALEFT=ERT(ARG)	883	133
	IF (ICNT,GE,100) GO TO 170	883	134
	IF (ABS(ALEFT),GT,ABS(RIGHT)) GO TO 150	883	135
	IF (ABS(RIGHT-ALEFT),LE,ABS(.01*(RIGHT+ALEFT)*.5)) GO TO 160	883	136
	THETA=THETA-DELTH	883	137
	DELTH=DELTH/10,	883	138
150	THETA=THETA+DELTH	883	139
	ICNT=ICNT+1	883	140
	IF (THETA,GE,P8IOLD) GO TO 160	883	141
	GO TO 140	883	142
160	CONTINUE	883	143
	ICNT=THETA/P8IOLD*100	883	144
	IF (ICNT/2*2,NE,ICNT) ICNT=ICNT+1	883	145
170	CONTINUE	883	146
	SUM3=0.	883	147
C		883	148
C	USE SIMPSON'S RULE TO INTEGRATE THE MOMENTUM EQUATION	883	149
C		883	150
	DO 180 J=2,ICNT,2	883	151
	THET0=DELTA*(J=2)	883	152
	THET1=DELTA*(J=1)	883	153
	THET2=DELTA*(J=0)	883	154
	ARG0=SIGMA*(THET0=ALPHA)	883	155
	ARG1=SIGMA*(THET1=ALPHA)	883	156
	ARG2=SIGMA*(THET2=ALPHA)	883	157
	XERF0=.5*(1.+ERT(ARG0))	883	158
	XERF1=.5*(1.+ERT(ARG1))	883	159
	XERF2=.5*(1.+ERT(ARG2))	883	160
	ANUM1,=(GAMMA=1,)*.5*((1.+UBUE)*XERF0=UBUE)**2*(UE/AT)**2	883	161
	POWER=1./(GAMMA=1,)	883	162
	DEN1,=(GAMMA=1,)*.5*(UE/AT)**2	883	163
	RHO0=(ANUM/DEN)**POWER	883	164
	ANUM1,=(GAMMA=1,)*.5*((1.+UBUE)*XERF1=UBUE)**2*(UE/AT)**2	883	165
	RHO1=(ANUM/DEN)**POWER	883	166
	ANUM1,=(GAMMA=1,)*.5*((1.+UBUE)*XERF2=UBUE)**2*(UE/AT)**2	883	167
	RHO2=(ANUM/DEN)**POWER	883	168
	AX0=1.+(H1*THET0)/(RAD(IL)*P8IOLD)	883	169
	AX1=1.+(H1*THET1)/(RAD(IL)*P8IOLD)	883	170
	AX2=1.+(H1*THET2)/(RAD(IL)*P8IOLD)	883	171
	TEMP=(DELTA/3,)*(RHO0*COB(THET0)*((1.+UBUE)*XERF0=UBUE)**2*AX0+4,*(883	883	172
	1RHO1*COB(THET1)*((1.+UBUE)*XERF1=UBUE)**2*AX1+RHO2*COB(THET2)*((1,883	883	173
	2+UBUE)*XERF2=UBUE)**2*AX2)	883	174
	SUM3=SUM3+TEMP	883	175
180	CONTINUE	883	176
	SUM4=0.	883	177
	IF (ICNT,GE,100) GO TO 200	883	178
	ICNT=ICNT+2	883	179
	DO 190 J=ICNT,INTJB,2	883	180
	THET0=DELTA*(J=2)	883	181
	THET1=DELTA*(J=1)	883	182
	THET2=DELTA*(J=0)	883	183
	ARG0=SIGMA*(THET0=ALPHA)	883	184
	ARG1=SIGMA*(THET1=ALPHA)	883	185
	ARG2=SIGMA*(THET2=ALPHA)	883	186
	XERF0=.5*(1.+ERT(ARG0))	883	187
	XERF1=.5*(1.+ERT(ARG1))	883	188
	XERF2=.5*(1.+ERT(ARG2))	883	189
	ANUM1,=(GAMMA=1,)*.5*((1.+UBUE)*XERF0=UBUE)**2*(UE/AT)**2	883	190
	POWER=1./(GAMMA=1,)	883	191
	DEN1,=(GAMMA=1,)*.5*(UE/AT)**2	883	192
	RHO0=(ANUM/DEN)**POWER	883	193
	ANUM1,=(GAMMA=1,)*.5*((1.+UBUE)*XERF1=UBUE)**2*(UE/AT)**2	883	194
	RHO1=(ANUM/DEN)**POWER	883	195
	ANUM1,=(GAMMA=1,)*.5*((1.+UBUE)*XERF2=UBUE)**2*(UE/AT)**2	883	196
	RHO2=(ANUM/DEN)**POWER	883	197
	AX0=1.+(H1*THET0)/(RAD(IL)*P8IOLD)	883	198

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AX1=1.+(H1*THET1)/(RAD(IL)*PSIOLD)      883 199
AX2=1.+(H1*THET2)/(RAD(IL)*PSIOLD)      883 200
TEMP=(DELTA/3.)*(RHO0*COS(THET0)*((1,+UBUE)*XERF0=UBUE)**2*AX0+4.+883 201
1RHO1*COS(THET1)*((1,+UBUE)*XERF1=UBUE)**2*AX1+RHO2*COS(THET2)*((1,883 202
2+URUE)*XERF2=UBUE)**2*AX2)
SUM4=SUM4+TEMP                          883 203
190 CONTINUE                             883 204
200 CONTINUE                             883 205
SUM5=SUM3+SUM4                          883 206
ANUM=1.-(GAMMA=1.)*.5*(1,+UBUE)**2*(UE/AT)**2 883 207
DEN=1.-(GAMMA=1.)*.5*(UE/AT)**2        883 208
RHOT=.0005821*PT/TTO                    883 209
RHORT=(1.+(GAMMA=1.)*.5*AME1**2)**(1./(1.-GAMMA)) 883 210
RHOE=RHORT*RHOT                         883 211
ANUM=1.-(GAMMA=1.)*.5*UBUE**2*(UE/AT)**2 883 212
RHORT=(ANUM/DEN)**(1./(GAMMA=1.))     883 213
AMACB=RHORT*URUE**2                     883 214
C CF                                      883 215
IF (IJET.EQ.0) GO TO 210                 883 216
IF (IL.LT.NEXT) GO TO 210                883 217
CF=0.                                     883 218
GO TO 220                                 883 219
210 CONTINUE                             883 220
ENU=.56/3600.                            883 221
XX=1.                                     883 222
REX=UBUE*UE/(ENU*XX)                    883 223
CF=1.328/SQRT(REX)                       883 224
220 SKIN=CF*.5*AMACB                      883 225
OPDX=(P2=P1)/(XL(IL+1)-XL(IL))          883 226
H2=H1                                     883 227
HA=H1                                     883 228
DIST=SQRT((XL(IL+1)-XL(IL))**2+(RAD(IL+1)-RAD(IL))**2) 883 229
IF (IL.EQ.1) GO TO 230                   883 230
H2=H1*TAN(PSIOLD)/TAN(PSIV(IL=1))+DIST*TAN(PSIOLD) 883 231
C DB PERPENDICULAR DISTANCE FROM SEPARATION SLOPE LINE TO CONTOUR 883 232
C DB DISTANCE ALONG SLOPE LINE AT SEPARATION 883 233
C DB ABS(H2-H1)/TAN(PSIOLD)              883 234
C SLOPL=(RAD(IL)-RAD(IL+1))/(XL(IL+1)-XL(IL)) 883 235
C SLOPL=ATAN(SLOPL)                      883 236
C AMUS=SLOPL-ABODSV                      883 237
C AB=DB*TAN(AMUS)                        883 238
C HA=H1                                   883 239
230 PRESS=OPDX/(RHOE*UE**2)*(HA+HA**2/(2.*RAD(IL)))*COS(SLOPL) 883 240
IF (PRESS.LT.0.) PRESS=0.                883 241
SHEAR=(1.+HA/RAD(IL))*(.1481+.0478*AME1+.1278*UBUE+.1632*AME1*URUE 883 242
+.399*UBUE**2+.0239*EXP(-5.0*AME1))/SIGMA 883 243
SHEAR=SHEAR+COS(PSIOLD)                 883 244
SHRJT=0.                                  883 245
OLDANS=SHEAR*PRESS*SKIN+SHRJT           883 246
C COMPARE THE RIGHT AND LEFT SIDE OF MOMENTUM EQUATION 883 247
C AMULT=P2*AME2**2/(P1*AME1**2)         883 248
C SUM5NW=SUM5*AMULT                      883 249
C IF (IL.EQ.1) GO TO 240                  883 250
C X01=H1/PSIV(IL=1)                      883 251
C X02=H2/PSIOLD                          883 252
C RATIO=(1.+H1/RAD(IL))/(1.+H1V(IL=1)/RAD(IL=1)) 883 253
C SUM5NW=(X02*AMULT*SUM5-X01*RATIO*SUM5V)/(X02=X01) 883 254
240 CONTINUE                             883 255
GLI=OLDANS*SUM5NW                       883 256
IF (IBAD.EQ.0) GO TO 250                 883 257
IJR=1                                     883 258
GO TO 300                                 883 259

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250	CALL NEWRAP (I,PSIOLD,GLI,EPSLN,PSINEM,IJB)	883 265
	IF (PSINEM.LT.,0.) GO TO 260	883 266
	IF (PSINEM.GT.,ABODSV) GO TO 260	883 267
	IF (I.GE.,100) GO TO 260	883 268
	GO TO 300	883 269
C		883 270
C	ITERATION FAILED, USE ANGLE FROM PREVIOUS ITERATION	883 271
C		883 272
260	CONTINUE	883 273
	IF (AME1.LT.,.2) GO TO 280	883 274
	IF (AME1.LT.,.5) GO TO 270	883 275
	SLOPE=(8.4-15.625)/(1.,.5)	883 276
	PSINEM=15.625+SLOPE*(AME1-.5)	883 277
	GO TO 290	883 278
270	SLOPE=(15.625-17.5)/(1.5-.2)	883 279
	PSINEM=17.5+SLOPE*(AME1-.2)	883 280
	GO TO 290	883 281
280	PSINEM=17.5	883 282
290	WRITE (6,370) PSINEM	883 283
	PSINEM=PSINEM*DEGRAD	883 284
	IF (PSINEM.GT.,ABODSV) PSINEM=ABODSV	883 285
	PSIOLD=PSINEM	883 286
	IBAD=1	883 287
	IF (ANA.GE.,8.) WRITE (6,380)	883 288
	GO TO 30	883 289
300	PSIOLD=PSINEM	883 290
	IF (IJB.EQ.,0) GO TO 50	883 291
	DELOLD=DELLOC	883 292
	IF (IL.GT.,1) DELLOC=ABS(H2-H1)/DB	883 293
	DELLOC=ATAN(DELLOC)	883 294
	IF (IL.EQ.,1) DELLOC=PSIOLD	883 295
	IF (IL.EQ.,1) DELOLD=0.	883 296
	ASTR=ABOD-(DELLOC-DELOLD)	883 297
C		883 298
C	CALCULATE DISCRIMINATING STREAMLINE	883 299
C		883 300
	XSTR(IL+1)=XL(IL+1)	883 301
	A=SQRT((XL(IL+1)-XL(IL))**2)	883 302
	B=ATAN(ASTR)*A	883 303
	YSTR(IL+1)=YSTR(IL)+B	883 304
	H1P=YSTR(IL)-RAD(IL)	883 305
	XIN=XSTR(NST)*1.001	883 306
	IX=NST	883 307
	IF (YSTR(IL+1).GT.,RAD(IL+1)) GO TO 320	883 308
	H2P=ABS(YSTR(IL+1)-RAD(IL+1))	883 309
	AX=(XL(IL+1)-XL(IL))/(1.+H2P/H1P)	883 310
	XSTR(IL+1)=XSTR(IL)+AX	883 311
	XIN=XSTR(IL+1)	883 312
	XINS=XIN	883 313
	CX=(RAD(IL)-RAD(IL+1))/(1.+H2P/H1P)	883 314
	YSTR(IL+1)=RAD(IL)+CX	883 315
	ISTOP=1	883 316
	IX=IL+1	883 317
	IF (IX.GT.,NST) GO TO 320	883 318
	DO 310 JB=IX,NST	883 319
	XSTR(JB+1)=XL(JB)	883 320
310	YSTR(JB+1)=RAD(JB)	883 321
320	CONTINUE	883 322
	SUMSV=SUMS	883 323
	UBUEV(IL)=UBUE	883 324
	H1V(IL)=H1	883 325
	PSIV(IL)=PSIOLD	883 326
	ABOD=ASTR	883 327
	PSISV=PSIOLD	883 328
	IF (ISTOP.EQ.,1) GO TO 360	883 329
	IF (IJET.EQ.,0) GO TO 340	883 330

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IF (IL+1,LT,NEXT) GO TO 340                                B03 331
C                                                            B03 332
C CALL JET ENTRAINMENT IF OPTION TURNED ON                B03 333
C                                                            B03 334
RJ=RAD(IL+1)                                               B03 335
RD=YSTR(IL+1)                                              B03 336
NSIN=NST=NEXT+1                                           B03 337
DO 330 I=NEXT,NST                                         B03 338
330 XJET(I)=XL(I)-XL(NEXT)                                 B03 339
UM=UBUEV(IL)*UE                                           B03 340
DRDDX0=(YSTR(NEXT)-YSTR(NEXT=1))/(XL(NEXT)-XL(NEXT=1))  B03 341
CALL JET (RJ,UM,C,DRJDX,DUMDX,RD,NSIN,XJET(NEXT),UEV(NEXT),YSTR(NEXT),RI,UJ,DRDDX0) B03 342
GO TO 360                                                  B03 343
340 CONTINUE                                              B03 344
C                                                            B03 345
C DETERMINE IF ITERATION COMPLETE                          B03 346
C                                                            B03 347
IF (IL,EQ,1) GO TO 350                                    B03 348
DB=ABS(H2-H1)/TAN(PSIOLD)                                  B03 349
AMUS=8LOPL=ABODSV                                         B03 350
AR=DB*TAN(AMUS)                                           B03 351
H1=H2+AR                                                  B03 352
IF (H1,GT,0.) GO TO 350                                   B03 353
IF (ILSV,EQ,0) ILSV=IL                                    B03 354
H1=H1V(ILSV)*.01                                         B03 355
350 IF (IL+1,LT,NST) GO TO 40                             B03 356
360 RETURN                                                B03 357
C                                                            B03 358
C                                                            B03 359
C                                                            B03 360
370 FORMAT (1H,6HPSIN,EW,F12.4)                           B03 361
380 FORMAT (1H0,46HITERATION FOR DISCRIMINATING STREAMLINE ANGLE ,20HF B03 362
1AILED, USING DEFAULT VALUE.,/17H TRY DECREASING ,36HSTEP SIZE (MO B03 363
2RE POINTS ON AFTERBODY))                                B03 364
END                                                        B03 365
FUNCTION ERT (X)
C                                                            ERT 1
C THIS FUNCTION ROUTINE OBTAINS VALUE OF THE ERROR FUNCTION ERT 2
C WITH ARGUMENT X USING LIBRARY SUBROUTINE ERF           ERT 3
C                                                            ERT 4
C                                                            ERT 5
CALL ERF (X,Y)                                           ERT 6
ERT=Y                                                      ERT 7
RETURN                                                    ERT 8
END                                                        ERT 9
SUBROUTINE NEWRAP (ICNT,X,FUNC,TOLL,XZERO,IE)
C                                                            NEW 1
C                                                            NEW 2
IE=0                                                       NEW 3
IF (ICNT,GT,100) STOP                                     NEW 4
IF (ICNT=2) 10,20,30                                     NEW 5
10 FUN1=FUNC                                              NEW 6
X1=X                                                       NEW 7
IF (X,EQ,0.) X=100.*TOLL                                  NEW 8
XZERO=X+.1*X                                              NEW 9
GO TO 90                                                  NEW 10
20 CONTINUE                                              NEW 11
FUN2=FUNC                                                 NEW 12
X2=X                                                       NEW 13
GO TO 80                                                  NEW 14
30 CONTINUE                                              NEW 15
IF (FUN1*FUNC) 50,40,40                                  NEW 16
40 FUN1=FUNC                                              NEW 17
FUN2=FUNC                                                 NEW 18
X1=X2                                                     NEW 19
X2=X                                                       NEW 20
GO TO 80                                                  NEW 21
50 CONTINUE                                              NEW 22

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        IF (PUNC*FUN2) 70,60,60
60     FUN2=FUNC
        X2=X
        GO TO 80
70     FUN1=FUNC
        X1=X
C
C     CALCULATE DERIVATIVE
C
80     DERV=(FUN2-FUN1)/(X2-X1)
        XZERO=X2-FUN2/DERV
        IF (ABS(XZERO-X).LT,ABS((XZERO+X)*.5)*TOLL) IE=1
90     RETURN
        END
SUBROUTINE JET (RJ,UM,C,DRJDX,DUMDX,RD,NBIN,XIN,UE,YSTR,RJA,UJA,DRJET
10DX0)
C
C     DIMENSION XIN(201), YSTR(201), RJA(201), UJA(201), UE(201)
        REAL LO,L1,L2
C
        TOL=.001
        DRDX=.1
        ICNT=0
        ISTA=1
        RDSV=RD
        X=XIN(ISTA)
        DL2DX=.25
        DRCDX=DRJDX+DL2DX
        DREDX=.0
        UE0=UE(1)
        R0=RJ
        A=(.3714*RD+.2286*R0)/(2.*(1.2*RD+.05*R0))
        B=(RD+R0)*UM/(2.*(1.2*RD+.05*R0)*(UE0-UM))
        XI=A*SQRT(A**2+B)
        ETA=XI**(1./1.5)
        ETA2=(1.-SQRT(UE0/(UE0-UM)))*(1./1.5)
        IF (ETA.LT,ETA2) ETA=ETA2
        L0=(RD-R0)/ETA
        RE=R0+L0
10     CONTINUE
        UE1=UE(ISTA)
        UJ=UJA(ISTA)
        DUEDX=(UE(ISTA+1)-UE(ISTA))/(XIN(ISTA+1)-XIN(ISTA))
        DUJDX=(UJA(ISTA+1)-UJA(ISTA))/(XIN(ISTA+1)-XIN(ISTA))
        ISTA=ISTA+1
        L2=.25*X
        RC=RJ+L2
        DELUE=UE1-UM
        L1=RE-RJ=L2
C
C     DUMDX LOOP
C
        ICNT=0
20     CONTINUE
        ICNT=ICNT+1
        DL1DX=C
        DDUEDX=DUEDX-DUMDX
        DLEUJ=UJ-UM
        DDUJXX=DUJDX-DUMDX
        AJB=L2*(UM+.55*DLEUJ)+UJ*RJ
        BJB=(RJ*(UM+.55*DLEUJ)+.3572*DLEUJ*L2)*DL2DX+(RC*L2+.5*L2**2)*DUMDX
        IX=(.55*RC*L2+.3714*L2**2)*DDUJXX
        DRJDX=(.043*UJ*RC-BJB)/AJB
        IF (ISTA.GT,2) GO TO 30
        DRDX=DRDX+DREDX
        TRM1=(RC*(UM+DELUE*(2.*ETA**1.5-ETA**3))+L1*ETA*(UM+DELUE*(2.*ETA**1.5-ETA**3)))/L1*ETA*(UM+DELUE*(2.*ETA**1.5-ETA**3))

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1*1.5*ETA**3))*(DRDDX=DL2DX=ETA*DL1DX)+(RC*(UM*ETA+DELUE*(2./2.5*EJET 53
2TA**2.5=1./4.*ETA**4))+2.*L1*(.5*UM*ETA**2+DELUE*(2./3.5*ETA**3.5=JET 54
31./5.*ETA**5)))*DL1DX JET 55
TRM2=L1*(UM*ETA+DELUE*(2./2.5*ETA**2.5=1./4.*ETA**4))*DL2DX+(RC*L1JET 56
1*ETA+.5*L1**2*ETA**2)*DUMDX+(RC*L1*(2./2.5*ETA**2.5=1./4.*ETA**4)+JET 57
2L1**2*(2./3.5*ETA**3.5=1./5.*ETA**5))*DDUEDX JET 58
B=TRM1+TRM2 JET 59
A=L1*(UM*ETA+DELUE*(2./2.5*ETA**2.5=1./4.*ETA**4))*RC*(UM+DELUE*(2JET 60
1.*ETA**1.5=ETA**3))-L1*ETA*(UM+DELUE*(2.*ETA**1.5=ETA**3)) JET 61
XZ=(BJB=(AJB*(BJB+B))/(AJB+A))/(UJ*RC) JET 62
CONTINUE JET 63
DRJDX=(UJ*XZ*RC=BJB)/AJB JET 64
DRCOX=DRJDX+DL2DX JET 65
DDUEDX=DUEDX=DUMDX JET 66
TRM1=(RC*(UM+.55*DLEUJ)=2.*L2*(.5*UM+.3714*DLEUJ))*DL2DX JET 67
TRM2=L2*(UM+.55*DLEUJ)*DRCOX+(RC*L2=.5*L2**2)*DUMDX JET 68
TRM3=(.55*RC*L2=.3714*L2**2)*DDUJXX JET 69
UDR1X=TRM1+TRM2+TRM3 JET 70
DREDX=DRJDX+C+DL1DX JET 71
IF (ISTA.GT.2) GO TO 40 JET 72
B1=L1*(UM+DELUE*(2./2.5*ETA**1.5=1./4.*ETA**3))*ETA*DRCOX+(RC*L1*EJET 73
1TA+.5*L1**2*ETA**2)*DUMDX+(RC*L1*(2./2.5*ETA**2.5=1./4.*ETA**4)+L1JET 74
2**2*(2./3.5*ETA**3.5=1./5.*ETA**5))*DDUEDX JET 75
ZZZ=RC*L1*(UM+DELUE*(2.*ETA**1.5=ETA**3))+L1**2*ETA*(UM+DELUE*(2.*JET 76
1ETA**1.5=ETA**3)) JET 77
G1=(UJ*RJ*DRJDX+UDR1X+B1)/ZZZ JET 78
P1=(RC*(UM*ETA+DELUE*(2./2.5*ETA**2.5=1./4.*ETA**4))+2.*L1*(.5*UMJET 79
1*ETA**2+DELUE*(2./3.5*ETA**3.5=1./5.*ETA**5)))/ZZZ JET 80
DL1DX=(DRDDX=DRJDX=DL2DX=L1*G1)/(ETA+P1*L1) JET 81
DREDX=DRJDX+C+DL1DX JET 82
DL1DX=C JET 83
DREDX=DRJDX+C+DL1DX JET 84
IF (DRDDX.EQ.0.) ETA=(1.-SQRT(UE1/DELUE))*(.1/1.5) JET 85
TRM1=(RC*(UM*ETA+DELUE*(2./2.5*ETA**2.5=ETA**4/4.))+2.*L1*(.5*UM*EJET 86
1TA**2+DELUE*(2./3.5*ETA**3.5=ETA**5/5.))*DL1DX JET 87
TRM2=L1*(UM+DELUE*(2./2.5*ETA**1.5=ETA**3/4.))*ETA*DRCOX+(RC*L1*EJET 88
1A+.5*L1**2*ETA**2)*DUMDX JET 89
TRM3=(RC*L1*(2./2.5*ETA**2.5=ETA**4/4.))+L1**2*(2./3.5*ETA**3.5=ETAJET 90
1**5/5.))*DDUEDX JET 91
WWW=TRM1+TRM2+TRM3 JET 92
ZZZ=RC*L1*(UM+DELUE*(2.*ETA**1.5=ETA**3))+L1**2*ETA*(UM+DELUE*(2.*JET 93
1ETA**1.5=ETA**3)) JET 94
DLEUJ=UJ=UM JET 95
DDUJXX=DUJDX=DUMDX JET 96
TRM1=(RC*(UM+.55*DLEUJ)=2.*L2*(.5*UM+.3714*DLEUJ))*DL2DX JET 97
TRM2=L2*(UM+.55*DLEUJ)*DRCOX+(RC*L2=.5*L2**2)*DUMDX JET 98
TRM3=(.55*RC*L2=.3714*L2**2)*DDUJXX JET 99
UDR1X=TRM1+TRM2+TRM3 JET 100
UDR2X=(2.*L1*(.5*UM+.3714*DELUE)+RC*(UM+.55*DELUE))*DL1DX+L1*(UM+.JET 101
155*DELUE)*DRCOX+(.5*L1**2+RC*L1)*DUMDX+(.3714*L1**2+.55*RC*L1)*DDUJET 102
2EDX JET 103
IF (DRDDX.EQ.0.) GO TO 50 JET 104
DEDX=(XZ*UJ*RC+WWW)/ZZZ JET 105
DRDDX=ETA*DREDX+(1.=ETA)*DRCOX+L1*DEDX JET 106
CONTINUE JET 107
DLEUJ=UJ=UM JET 108
DDUJXX=DUJDX=DUMDX JET 109
TRM1=L2*(UM**2+1.1*UM*DLEUJ+.4156*DLEUJ**2)*DRCOX JET 110
TRM2=(RC*(UM**2+1.1*UM*DLEUJ+.4156*DLEUJ**2)=2.*L2*(.5*UM**2+.7428JET 111
1*UM*DLEUJ+.3096*DLEUJ**2))*DL2DX JET 112
TRM3=(RC*L2*(2.*UM+1.1*DLEUJ)=L2**2*(UM+.7428*DLEUJ))*DUMDX JET 113
TRM4=(RC*L2*(1.1*UM+.8312*DLEUJ)=L2**2*(.7428*UM+.6192*DLEUJ))*DDUJET 114
1JXX JET 115
U2DR1X=TRM1+TRM2+TRM3+TRM4 JET 116
TRM1=(UM**2+1.4856*UM*DELUE+.6192*DELUE**2)*L1+(UM**2+1.1*UM*DELUJET 117
1E+.4156*DELUE**2)*RC)*DL1DX JET 118

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TRM2=L1*(UM**2+1,1*UM*DELUE+.4156*DELUE**2)*DRCDX+L1**2*(UM+.7428*JET 119
1DELUE)*DUMDX JET 120
TRM3=L1*RC*(2,*UM+1,1*DELUE)*DUMDX+L1**2*(.6192*DELUE+.7428*UM)*DDJET 121
1UEDX+RC*L1*(.8312*DELUE+1,1*UM)*DDUEDX JET 122
U2DR2X=TRM1+TRM2+TRM3 JET 123
AMRHO=UJ*RJ*DRJDX+(UDR1X+UOR2X) JET 124
XMOHNT=UJ**2*RJ*DRJDX+(U2DR1X+U2DR2X)=RE**2*.5*UE1*DUEDX=UE1*AMRHOJET 125
CALL NEWRAP (ICNT,DUMDX,XMOHNT,TOL,DUMDXN,IE) JET 126
IF (ICNT,LE,30) GO TO 60 JET 127
ISTA=ISTA-1 JET 128
GO TO 130 JET 129
60 CONTINUE JET 130
IF (IE,NE,0) GO TO 70 JET 131
DUMDX=DUMDXN JET 132
GO TO 20 JET 133
70 CONTINUE JET 134
C SOLVE FOR THE RADIUS OF THE DISCRIMINATING STREAMLINE JET 135
C JET 136
C JET 137
X=XIN(ISTA) JET 138
DX=XIN(ISTA)-XIN(ISTA-1) JET 139
L2=C*X JET 140
IF (ETA,LE,ETA2) GO TO 80 JET 141
IF (DRDDX,EG,0,) GO TO 80 JET 142
RD=DRDDX*DX+RD JET 143
ETA=DEDX*DX+ETA JET 144
DELUE=UE(ISTA)=(DUMDX*DX+UM) JET 145
ETA2=(1,=SQRT(UE(ISTA)/DELUE))**(1,/.15) JET 146
IF (ETA,LT,ETA2) GO TO 80 JET 147
GO TO 90 JET 148
80 CONTINUE JET 149
DRDDX=0, JET 150
90 UM=DUMDX*DX+UM JET 151
IF (UM,GE,0,) GO TO 170 JET 152
RJ=RJ+DRJDX*DX JET 153
DREDX=DRJDX+2,*C JET 154
RE=RE+DREDX*DX JET 155
IF (DRDDX,NE,0,) GO TO 100 JET 156
L1=RE-RJ=L2 JET 157
IF (L1,LE,0,) GO TO 170 JET 158
DELUE=UE(ISTA)=UM JET 159
ETA=(1,=SQRT(UE(ISTA)/DELUE))**(1,/.15) JET 160
RD=RJ+L2+ETA*L1 JET 161
IF (RD,GT,RDSV) GO TO 170 JET 162
100 CONTINUE JET 163
YSTR(ISTA)=RD+RJA(ISTA)=R0=L2 JET 164
RDSV=RD JET 165
ICNT=0 JET 166
IF (RD,LE,R0) GO TO 110 JET 167
IF (YSTR(ISTA),LE,RJA(ISTA)) GO TO 110 JET 168
GO TO 190 JET 169
110 ISRT=ISTA JET 170
DO 120 I=ISRT,NSIN JET 171
120 YSTR(I)=RJA(I) JET 172
GO TO 200 JET 173
130 SLOPE=(YSTR(ISTA=1)-YSTR(ISTA=2))/DX JET 174
IF (SLOPE,GT,0,) GO TO 150 JET 175
ISRT=ISTA JET 176
DO 140 I=ISRT,NSIN JET 177
140 YSTR(I)=SLOPE*(XIN(I)-XIN(I=1))+YSTR(I=1) JET 178
IF (YSTR(I),LT,RJA(I)) YSTR(I)=RJA(I) JET 179
GO TO 200 JET 180
150 DO 160 I=ISTA,NSIN JET 181
160 YSTR(I)=YSTR(I=1) JET 182
GO TO 200 JET 183
170 DO 180 I=ISTA,NSIN JET 184

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	L2=C*XIN(I)	JET 185
	YSTR(I)=RDSV+RJA(I)-R0=L2	JET 186
180	IF (YSTR(I),LT,RJA(I)) YSTR(I)=RJA(I)	JET 187
	GO TO 200	JET 188
190	CONTINUE	JET 189
	IF (ISTA,LT,NSIN) GO TO 10	JET 190
200	RETURN	JET 191
	END	JET 192=
	SUBROUTINE SMINT (XA,YA,NA,NMIN,NMAX)	SMI 1
C		SMI 2
C	INTERFACE ROUTINE FOR VISCOUS PACKAGE AND SMOOTHING ROUTINES	ISMI 3
C		SMI 4
	COMMON /SAVE/ SB(201),SC(201),YJB(201),XIN	SMI 5
	DIMENSION X1(201), X2(201), Y1(201), Y2(201), XA(1), YA(1), S(201)	SMI 6
	1, S1(201), Y22(201), Y22S(201), Y(201), Z(201), DDY(201), DY(201),	SMI 7
	2 DZ(201), DDZ(201), Z1(201)	SMI 8
C		SMI 9
	NA1=NA-1	SMI 10
	DO 10 I=1,NA1	SMI 11
	X1(I)=XA(I)	SMI 12
	X2(I)=XA(I+1)	SMI 13
	Y1(I)=YA(I)	SMI 14
10	Y2(I)=YA(I+1)	SMI 15
	K9=1	SMI 16
	NSMTH1=NMIN-4	SMI 17
	IF (NSMTH1,LT,2) NSMTH1=2	SMI 18
	NSMTH2=NA-1	SMI 19
	DO 20 I=NMAX,NA	SMI 20
	IF (XIN,LT,XA(I)) GO TO 30	SMI 21
	NSMTH2=I+6	SMI 22
20	CONTINUE	SMI 23
30	IF (NSMTH2.GT,NA-1) NSMTH2=NA-1	SMI 24
	IVSM=0	SMI 25
	K11=10	SMI 26
	CALL SMOOTH (X1,X2,Y1,Y2,K9,K11,NSMTH1,NSMTH2,IVSM,NA,S,S1,Y22,	SMI 27
	1S,Y,Z,DDY,DY,DZ,DDZ,Z1)	SMI 28
	DO 40 I=1,NA1	SMI 29
	XA(I)=X1(I)	SMI 30
40	YA(I)=Y1(I)	SMI 31
	RETURN	SMI 32
	END	SMI 33=
	SUBROUTINE SMOOTH (X1,X2,Y1,Y2,K9,K11,NSMTH1,NSMTH2,IVSM,NA,S,S1,YSMO	SMO 1
	122,Y22S,Y,Z,DDY,DY,DZ,DDZ,Z1)	SMO 2
C		SMO 3
	DIMENSION X1(NA), Y1(NA), Y2(NA), S(NA), S1(NA), X2(NA), Y22(NA),	SMO 4
	1Y22S(NA), Y(NA), Z(NA), NSMTH1(5), NSMTH2(5), DDY(NA), DY(NA), DZ(SMO 5
	2NA), DDZ(NA), Z1(NA)	SMO 6
C		SMO 7
	DO 170 I=1,K9	SMO 8
	N5=NSMTH1(I)	SMO 9
	N6=NSMTH2(I)	SMO 10
	I1=MINO(N5,N6)	SMO 11
	I2=MAXO(N5,N6)	SMO 12
	S(I1-1)=0.0	SMO 13
	IF (IVSM,EQ,1) GO TO 20	SMO 14
	DO 10 J=I1,I2	SMO 15
10	S(J)=S(J-1)+SQRT((X2(J)-X1(J))**2+(Y2(J)-Y1(J))**2)	SMO 16
	GO TO 40	SMO 17
20	DO 30 J=I1,I2	SMO 18
30	S(J)=S(J-1)+SQRT((X1(J)-X1(J-1))**2+(X2(J)-X2(J-1))**2)	SMO 19
40	CONTINUE	SMO 20
	I1=I2+1	SMO 21
	DEL8=S(I2)/I1	SMO 22
	I3=I2-1	SMO 23
	S1(I1-1)=0.0	SMO 24
	DO 50 J=I1,I3	SMO 25

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50	S1(J)=S1(J-1)+DELS	SMO	26
	S1(I2)=S(I2)	SMO	27
	DO 90 J=I1,I3	SMO	28
	DO 60 K=I1,I3	SMO	29
	IF (S(K)=S1(J)) 60,70,70	SMO	30
60	CONTINUE	SMO	31
70	IF (IVSM,EQ,1) GO TO 80	SMO	32
	Y22(J)=Y1(K)+(Y2(K)-Y1(K))*(S1(J)-S(K-1))/(S(K)-S(K-1))	SMO	33
	GO TO 90	SMO	34
80	Y22(J)=Y1(K-1)+(Y1(K)-Y1(K-1))*(S1(J)-S(K-1))/(S(K)-S(K-1))	SMO	35
90	CONTINUE	SMO	36
	Y22(I2)=Y2(I2)	SMO	37
	IF (IVSM,EQ,1) Y22(I2)=Y1(I2)	SMO	38
	DO 100 J=I1,I3	SMO	39
100	Y(J)=Y22(J+I1-1)	SMO	40
	CALL MSMTM (Y,Z,I1,K11,NA,DDY,DY,DZ,DDZ,Z1)	SMO	41
	DO 110 J=I1,I2	SMO	42
110	Y228(J)=Z(J=I1+1)	SMO	43
	Y228(I1-1)=Y2(I1-1)	SMO	44
	IF (IVSM,EQ,1) Y228(I1-1)=Y1(I1-1)	SMO	45
	DO 160 J=I1,I3	SMO	46
	DO 120 K=I1,I3	SMO	47
	IF (S1(K)=S(J)) 120,130,130	SMO	48
120	CONTINUE	SMO	49
130	IF (IVSM,EQ,1) GO TO 140	SMO	50
	Y2(J)=Y228(K-1)+(Y228(K)-Y228(K-1))*(S(J)-S1(K-1))/(S1(K)-S1(K-1))	SMO	51
	GO TO 150	SMO	52
140	CONTINUE	SMO	53
	Y1(J)=Y228(K-1)+(Y228(K)-Y228(K-1))*(S(J)-S1(K-1))/(S1(K)-S1(K-1))	SMO	54
150	CONTINUE	SMO	55
	IF (IVSM,EQ,0) Y1(J)=Y2(J-1)	SMO	56
160	CONTINUE	SMO	57
170	CONTINUE	SMO	58
	RETURN	SMO	59
	END	SMO	60
	SUBROUTINE MSMTM (Y,Z,N,K,NA,DDY,DY,DZ,DDZ,Z1)	MSM	1
C		MSM	2
	DIMENSION Y(NA), Z(NA), DY(NA), DZ(NA), DDY(NA), DDZ(NA), Z1(NA)	MSM	3
C		MSM	4
	IF (N=5) 40,10,10	MSM	5
10	CALL RSMTH (Y,N,K,Z,NA,Z1)	MSM	6
	NM1=N-1	MSM	7
	NM2=N-2	MSM	8
	DO 20 I=1,NM1	MSM	9
	DY(I)=Y(I+1)-Y(I)	MSM	10
	DZ(I)=Z(I+1)-Z(I)	MSM	11
20	CONTINUE	MSM	12
	DO 30 I=1,NM2	MSM	13
	DDY(I)=DY(I+1)-DY(I)	MSM	14
	DDZ(I)=DZ(I+1)-DZ(I)	MSM	15
30	CONTINUE	MSM	16
40	RETURN	MSM	17
	END	MSM	18
	SUBROUTINE RSMTH (Y,N,K,Z,NA,Z1)	RSM	1
C		RSM	2
	DIMENSION Y(NA), Z(NA), Z1(NA)	RSM	3
C		RSM	4
	J=0	RSM	5
	DO 10 I=1,N	RSM	6
	Z1(I)=Y(I)	RSM	7
10	CONTINUE	RSM	8
	Z(1)=Y(1)	RSM	9
	Z(N)=Y(N)	RSM	10
20	J=J+1	RSM	11
	CALL SMTH (Z1,N,U,Z,NA)	RSM	12
	IF (U) 60,60,30	RSM	13

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30  IF (J=K) 40,60,60                                RSM 14
40  DO 50 I=1,N                                       RSM 15
    Z1(I)=Z(I)                                        RSM 16
50  CONTINUE                                          RSM 17
    GO TO 20                                          RSM 1A
60  RETURN                                            RSM 19
    END                                              RSM 20
    SUBROUTINE SMTH (Y,N,U,Z,NA)                    SMT 1
C
    DIMENSION Y(NA), Z(NA)                          SMT 2
C
    F(ETA)=(1.0-ETA*ETA)**2                          SMT 3
    G(ET)=0.5*ET*(1.0+ET)                            SMT 4
C
    U=0.0                                             SMT 5
    J=3                                               SMT 6
10  A=ABS(Y(J-2)-2.0*Y(J-1)+2.0*Y(J+1)-Y(J+2))    SMT 7
    D=-Y(J-2)+4.0*Y(J-1)+10.0*Y(J)+4.0*Y(J+1)-Y(J+2) SMT 8
    IF (A=ABS(D)) 20,40,40                            SMT 9
20  FS=F(A/D)                                         SMT 10
    A=ABS(-Y(J-2)+Y(J-1)+Y(J+1)-Y(J+2))            SMT 11
    B=ABS(3.0*(Y(J-1)-2.0*Y(J)+Y(J+1)))             SMT 12
    IF (A=B) 30,40,40                                 SMT 13
30  GS=G(1.0-A/B)                                     SMT 14
    Z(J)*Y(J)=0.1*FS*GS*D                            SMT 15
    U=1.0                                             SMT 16
    GO TO 50                                          SMT 17
40  Z(J)=Y(J)                                         SMT 18
50  J=J+1                                             SMT 19
    IF (J=(N-2)) 10,10,60                            SMT 20
60  A=0.4*ABS(Y(4)-Z(4))                             SMT 21
    D=-0.2*(-6.0*Y(1)+10.0*Y(2)-2.0*Y(3)-Y(4)-Z(4)) SMT 22
    IF (A=ABS(D)) 70,80,80                            SMT 23
70  FS=F(A/D)                                         SMT 24
    GS=G(A/ABS(D))                                    SMT 25
    Z(2)*Y(2)=0.5*FS*GS*D                            SMT 26
    GO TO 90                                          SMT 27
80  Z(2)=Y(2)                                         SMT 28
90  A=0.4*ABS(Y(N-3)-Z(N-3))                         SMT 29
    D=-0.2*(-Y(N-3)+Z(N-3)-2.0*Y(N-2)+10.0*Y(N-1)-6.0*Y(N)) SMT 30
    IF (A=ABS(D)) 100,110,110                        SMT 31
100 FS=F(A/D)                                         SMT 32
    GS=G(A/ABS(D))                                    SMT 33
    Z(N-1)*Y(N-1)=0.5*FS*GS*D                       SMT 34
    GO TO 120                                         SMT 35
110 Z(N-1)=Y(N-1)                                    SMT 36
120 RETURN                                            SMT 37
    END                                              SMT 38
    SUBROUTINE IUNI(NMAX,N,X,NTAB,Y,IORDER,X0,Y0,IPT,IERR) IUNI0010
C*****IUNI0020
C*
C*  PURPOSE:
C*          SUBROUTINE IUNI USES FIRST OR SECOND ORDER
C*          LAGRANGIAN INTERPOLATION TO ESTIMATE THE VALUES
C*          OF A SET OF FUNCTIONS AT A POINT X0. IUNI
C*          USES ONE INDEPENDENT VARIABLE TABLE AND A DEPENDENT
C*          VARIABLE TABLE FOR EACH FUNCTION TO BE EVALUATED.
C*          THE ROUTINE ACCEPTS THE INDEPENDENT VARIABLES SPACED
C*          AT EQUAL OR UNEQUAL INTERVALS. EACH DEPENDENT
C*          VARIABLE TABLE MUST CONTAIN FUNCTION VALUES CORRES-
C*          PONDING TO EACH X(I) IN THE INDEPENDENT VARIABLE
C*          TABLE. THE ESTIMATED VALUES ARE RETURNED IN THE Y0
C*          ARRAY WITH THE N-TH VALUE OF THE ARRAY HOLDING THE
C*          VALUE OF THE N-TH FUNCTION VALUE EVALUATED AT X0.
C*
C*  USE:
C*          IUNI0030
C*          IUNI0040
C*          IUNI0050
C*          IUNI0060
C*          IUNI0070
C*          IUNI0080
C*          IUNI0090
C*          IUNI0100
C*          IUNI0110
C*          IUNI0120
C*          IUNI0130
C*          IUNI0140
C*          IUNI0150
C*          IUNI0160
C*          IUNI0170
C*          IUNI0180

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APPENDIX

C*		*IUNY0850
C*	REQUIRED ROUTINES	NONE
C*		*IUNY0860
C*	SOURCE	CMPB ROUTINE MTLUP MODIFIED
C*		*IUNY0870
C*		*IUNY0880
C*		*IUNY0890
C*	LANGUAGE	FORTRAN
C*		*IUNY0900
C*		*IUNY0910
C*		*IUNY0920
C*	DATE RELEASED	AUGUST 1, 1973
C*		*IUNY0930
C*		*IUNY0940
C*	LATEST REVISION	JUNE 9, 1975
C*		*IUNY0950
C*		*IUNY0960
C*		*IUNY0970
C*	*****	*IUNY0980
C	DIMENSION X(1),Y(NMAX,1),YO(1)	IUNY0990
C	NM1=N-1	IUNY1000
C	IERR=0	IUNY1010
C	J=1	IUNY1020
C		IUNY1030
C	TEST FOR ZERO ORDER INTERPOLATION	IUNY1040
C		IUNY1050
C	DELX=X(2)-X(1)	IUNY1060
C	IF (IORDER .EQ. 0) GO TO 10	IUNY1070
C	IF (N.LT. 2) GO TO 20	IUNY1080
C	GO TO 50	IUNY1090
C	10 IERR=1	IUNY1100
C	GO TO 30	IUNY1110
C	20 IERR=2	IUNY1120
C	30 DO 40 NT=1,NTAB	IUNY1130
C	YO(NT)=Y(1,NT)	IUNY1140
C	40 CONTINUE	IUNY1150
C	RETURN	IUNY1160
C	50 IF (IPT .GT. -1) GO TO 65	IUNY1170
C		IUNY1180
C	CHECK FOR TABLE OF NODE POINTS BEING STRICTLY MONOTONIC	IUNY1190
C	THE SIGN OF DELX SIGNIFIES WHETHER TABLE IS IN	IUNY1200
C	INCREASING OR DECREASING ORDER.	IUNY1210
C		IUNY1220
C	IF (DELX .EQ. 0) GO TO 190	IUNY1230
C	IF (N .EQ. 2) GO TO 65	IUNY1240
C		IUNY1250
C	CHECK FOR SIGN CONSISTENCY IN THE DIFFERENCES OF	IUNY1260
C	SUBSEQUENT PAIRS	IUNY1270
C		IUNY1280
C	DO 60 J=2,NM1	IUNY1290
C	IF (DELX * (X(J+1)-X(J))) 190,190,60	IUNY1300
C	60 CONTINUE	IUNY1310
C		IUNY1320
C	IPT IS INITIALIZED TO BE WITHIN THE INTERVAL	IUNY1330
C		IUNY1340
C	65 IF (IPT .LT. 1) IPT=1	IUNY1350
C	IF (IPT .GT. NM1) IPT=NM1	IUNY1360
C	IN= SIGN (1,0,DELX *(X0=X(IPT)))	IUNY1370
C	70 P= X(IPT) - X0	IUNY1380
C	IF (P*(X(IPT+1)-X0)) 90,180,80	IUNY1390
C	80 IPT =IPT +IN	IUNY1400
C		IUNY1410
C	TEST TO SEE IF IT IS NECESSARY TO EXTRAPOLATE	IUNY1420
C		IUNY1430
C	IF (IPT.GT.0 .AND. IPT .LT. N) GO TO 70	IUNY1440
C	IERR=4	IUNY1450
C	IPT=IPT- IN	IUNY1460
C		IUNY1470
C	TEST FOR ORDER OF INTERPOLATION	IUNY1480
C		IUNY1490
C		IUNY1500

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90	IF (IORDER .GT. 1) GO TO 120	IUNT1510
C		IUNT1520
C	FIRST ORDER INTERPOLATION	IUNT1530
C		IUNT1540
	IPT1=IPT+1	IUNT1550
	XTMP1=X0-X(IPT)	IUNT1560
	XTMP2=X(IPT1)-X(IPT)	IUNT1570
	XTMP1=XTMP1/XTMP2	IUNT1580
	DO 100 NT=1,NTAB	IUNT1590
	YTMP=Y(IPT1,NT)-Y(IPT,NT)	IUNT1600
	Y0(NT)=Y(IPT,NT)+YTMP*XTMP1	IUNT1610
100	CONTINUE	IUNT1620
	IF (IERR .EQ. =4) IPT=IPT+IN	IUNT1630
	RETURN	IUNT1640
C		IUNT1650
C	SECOND ORDER INTERPOLATION	IUNT1660
C		IUNT1670
120	IF (N .EQ. 2) GO TO 200	IUNT1680
C		IUNT1690
C	CHOOSING A THIRD POINT SO AS TO MINIMIZE THE DISTANCE	IUNT1700
C	BETWEEN THE THREE POINTS USED TO INTERPOLATE	IUNT1710
C		IUNT1720
	IF (IPT .EQ. NM1) GO TO 140	IUNT1730
	IF (IPT .EQ. 1) GO TO 130	IUNT1740
	A1=ABS(X0-X(IPT=1))	IUNT1750
	A2=ABS(X(IPT+2)-X0)	IUNT1760
	IF (A1=A2) 140,130,130	IUNT1770
130	L=IPT	IUNT1780
	GO TO 150	IUNT1790
140	L=IPT +1	IUNT1800
150	V1=X(L)-X0	IUNT1810
	V2=X(L+1)-X0	IUNT1820
	V3=X(L+2)-X0	IUNT1830
	DO 160 NT=1,NTAB	IUNT1840
	YY1=(Y(L,NT) * V2 - Y(L+1,NT) * V1)/(X(L+1) - X(L))	IUNT1850
	YY2=(Y(L+1,NT)*V3-Y(L+2,NT) *V2)/(X(L+2)-X(L+1))	IUNT1860
	Y0(NT)=(YY1*V3+YY2*V1)/(X(L+2)-X(L))	IUNT1870
160	CONTINUE	IUNT1880
	IF (IERR .EQ. =4) IPT=IPT + IN	IUNT1890
	RETURN	IUNT1900
180	IF (P .NE. 0) IPT=IPT +1	IUNT1910
	DO 185 NT=1,NTAB	IUNT1920
	Y0(NT)=Y(IPT,NT)	IUNT1930
185	CONTINUE	IUNT1940
	RETURN	IUNT1950
C		IUNT1960
C	IERR IS SET TO THE SUBSCRIPT OF THE MEMBER OF THE TABLE	IUNT1970
C	WHICH IS OUT OF ORDER	IUNT1980
C		IUNT1990
190	IERR=J +1	IUNT2000
	RETURN	IUNT2010
200	IERR=3	IUNT2020
	RETURN	IUNT2030
	END	IUNT2040

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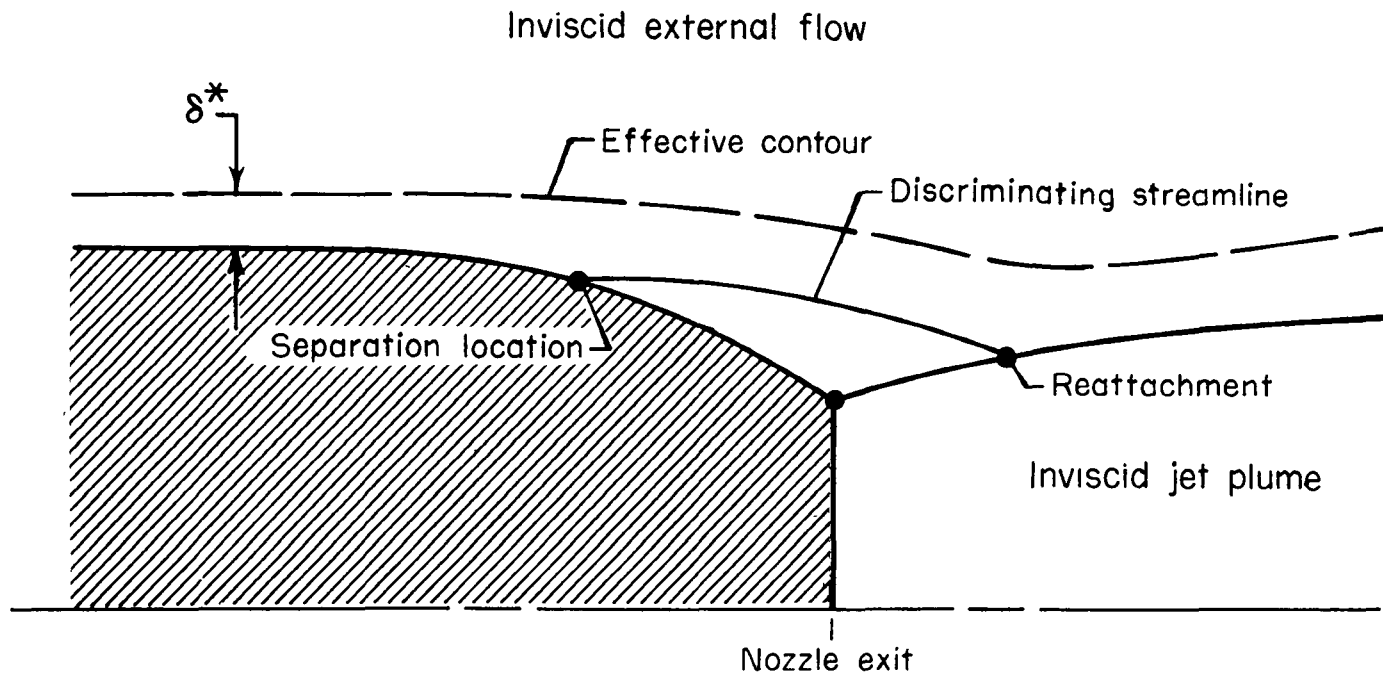


Figure 1.- Analytical model of flow over nozzle boattail.

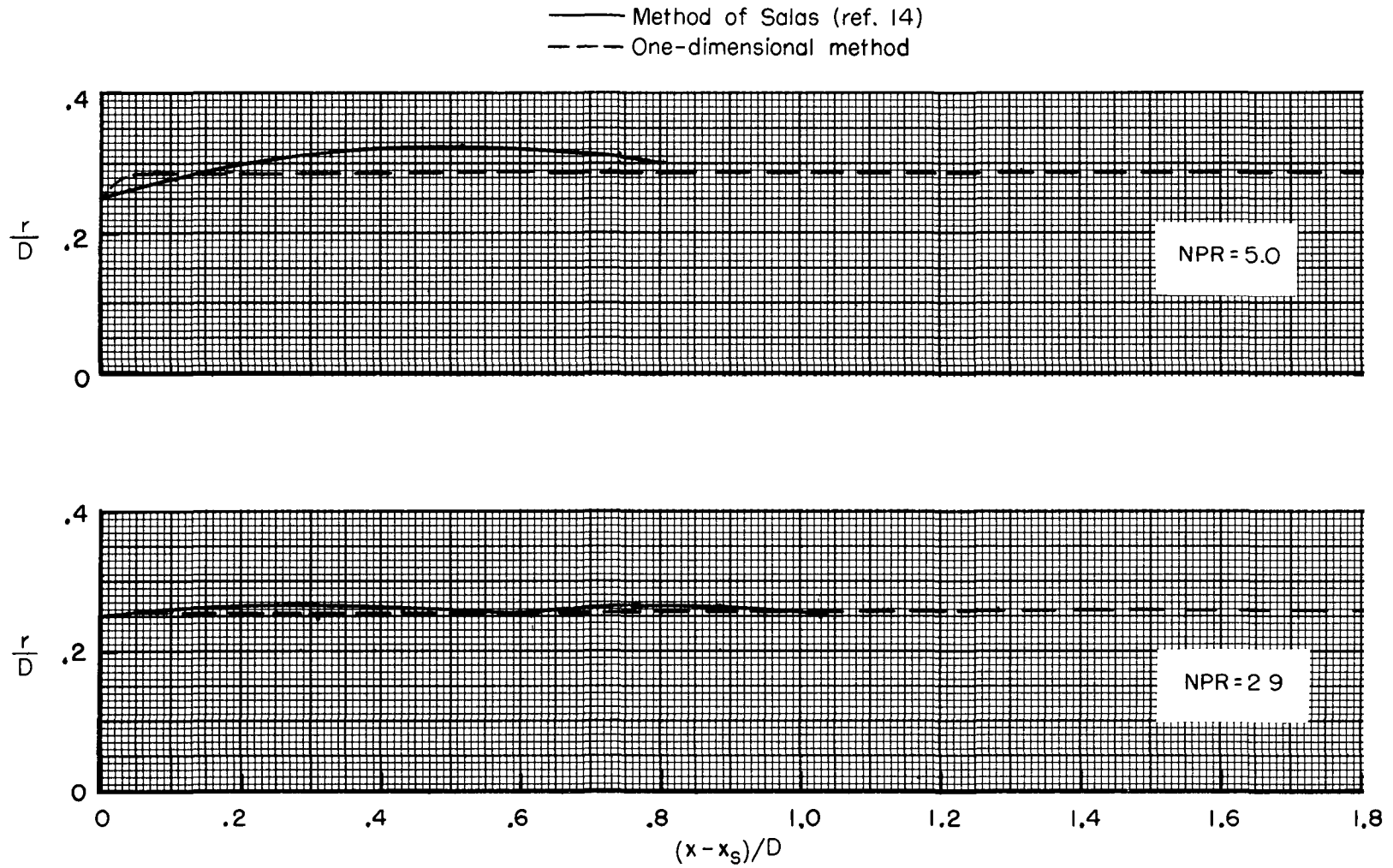
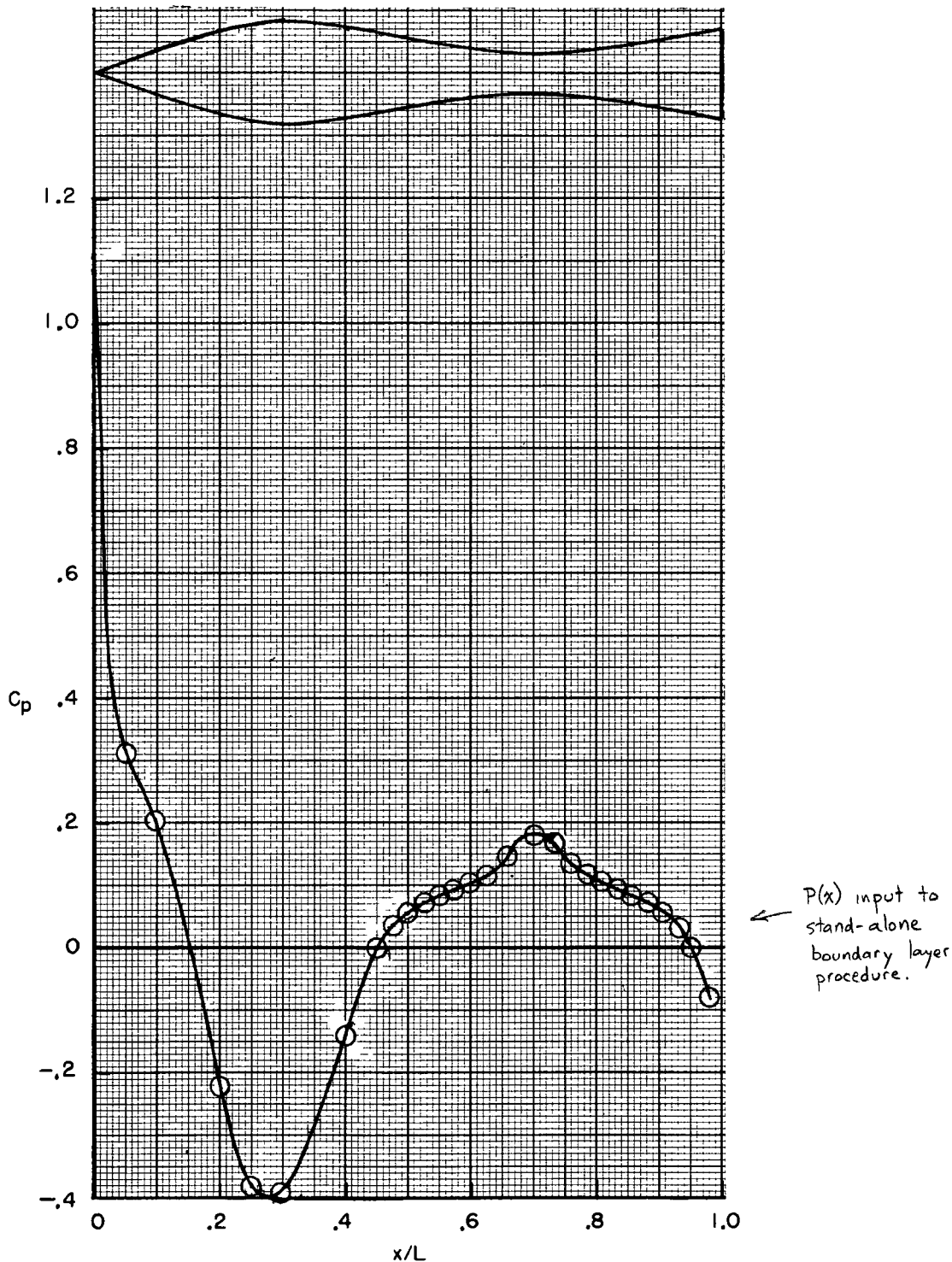
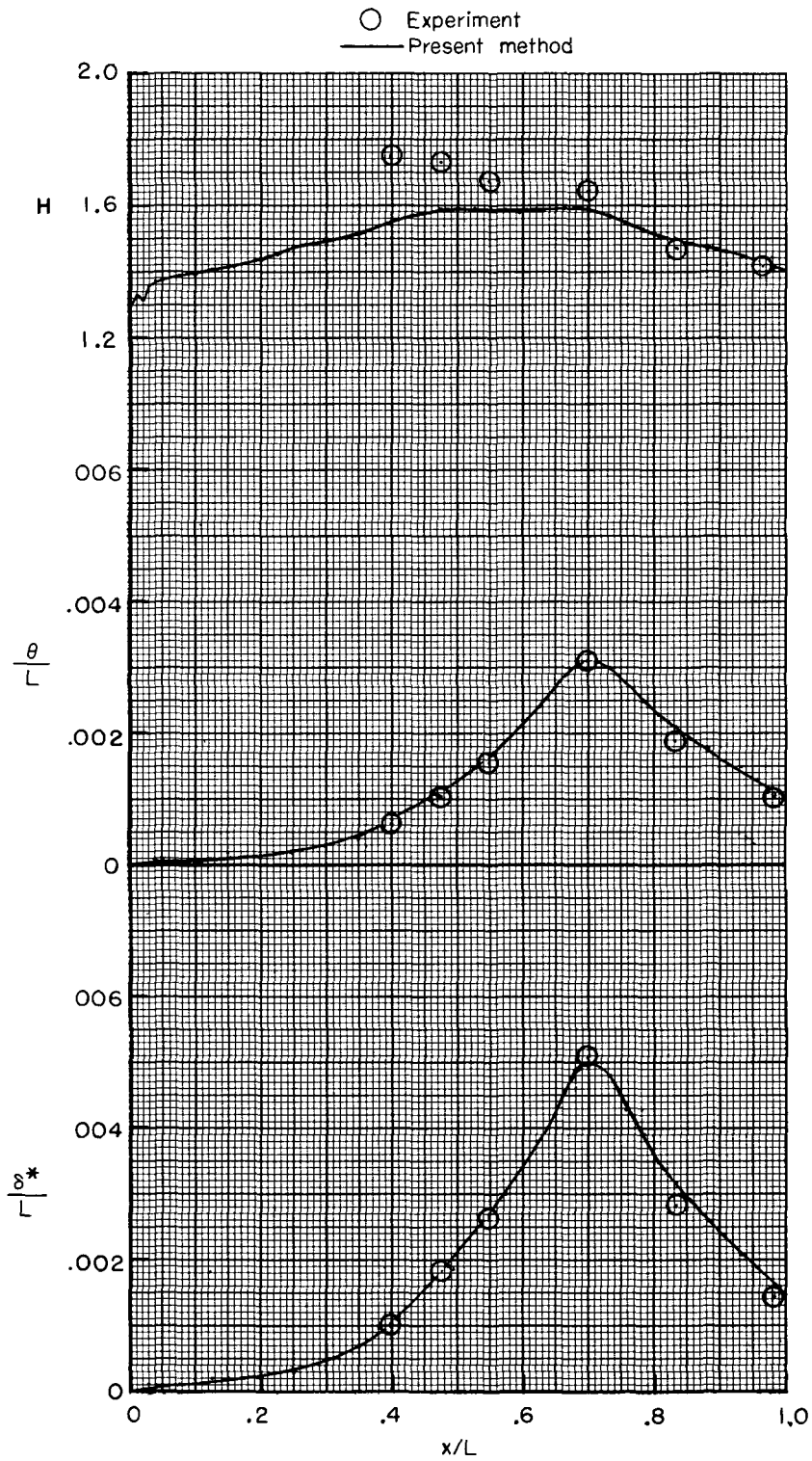


Figure 2.- Comparison of one-dimensional jet exhaust flow calculation with method of Salas (ref. 14).



(a) Pressure distribution and body geometry.

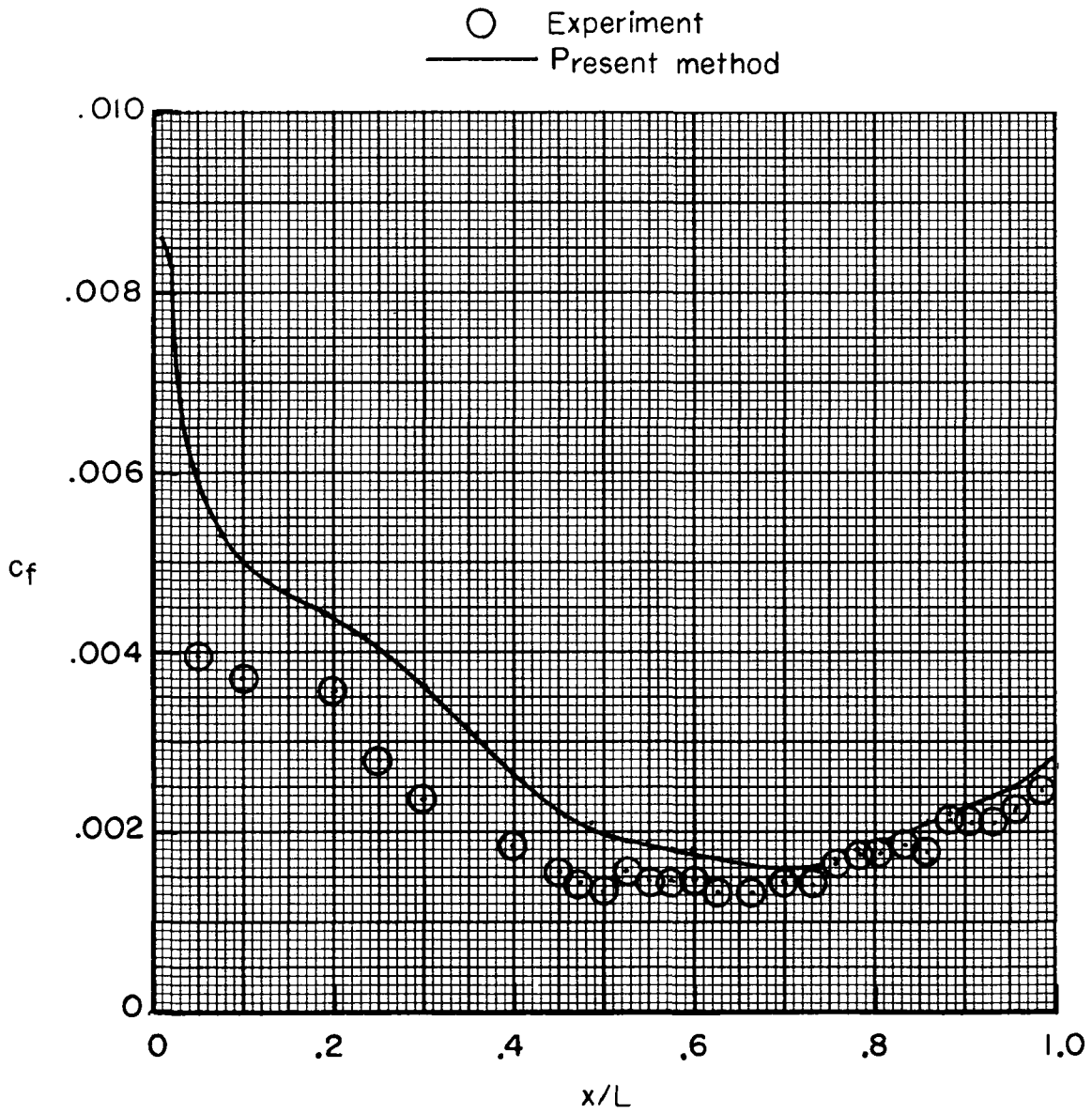
Figure 3.- Comparison of predicted boundary-layer characteristics with experiment of Winter, Rotta, and Smith (ref. 17). $M_\infty = 0.6$ and Reynolds number based on body length of 9.85×10^6 .



(b) Displacement thickness, momentum thickness, and shape factor.

Figure 3.- Continued.

These are results from a stand-alone boundary-layer procedure (also next page).



(c) Skin friction.

Figure 3.- Concluded.

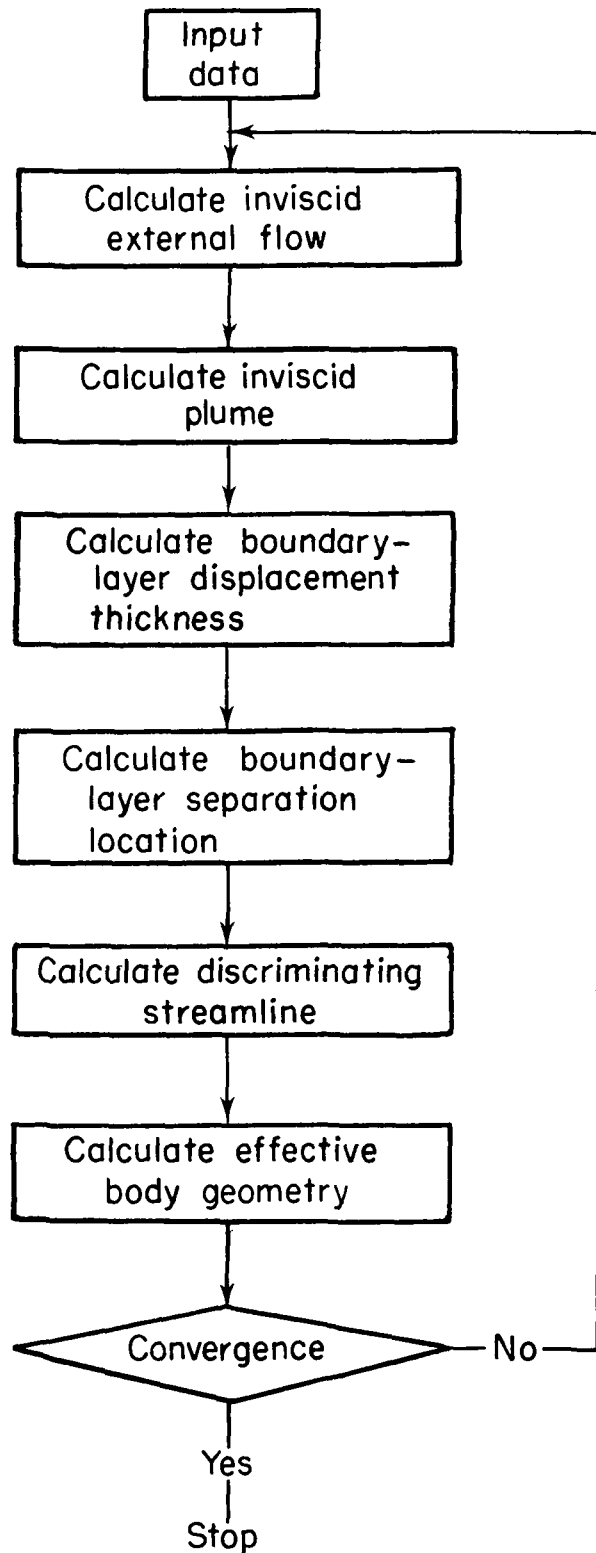


Figure 4.- Flow diagram of interaction procedure.

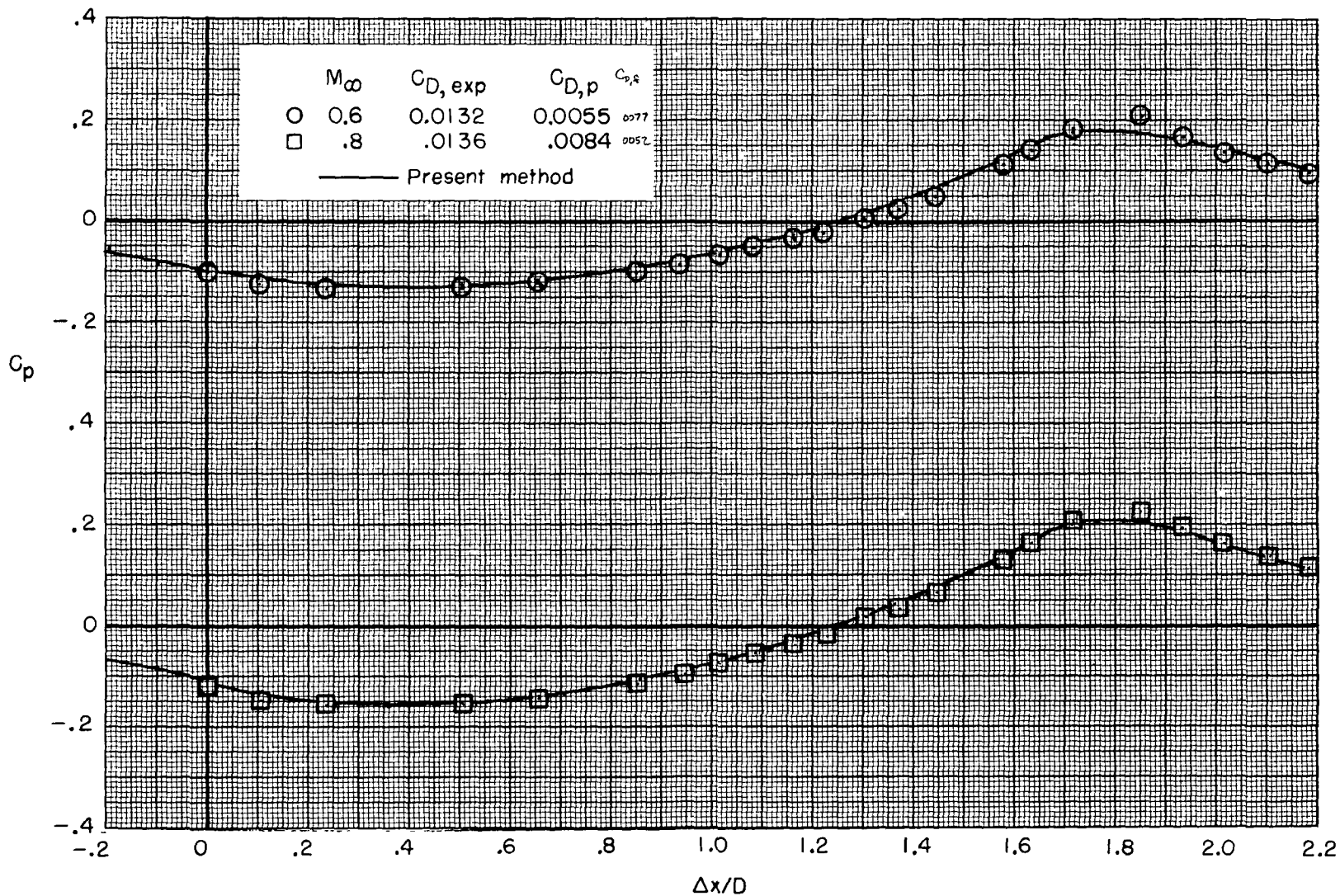
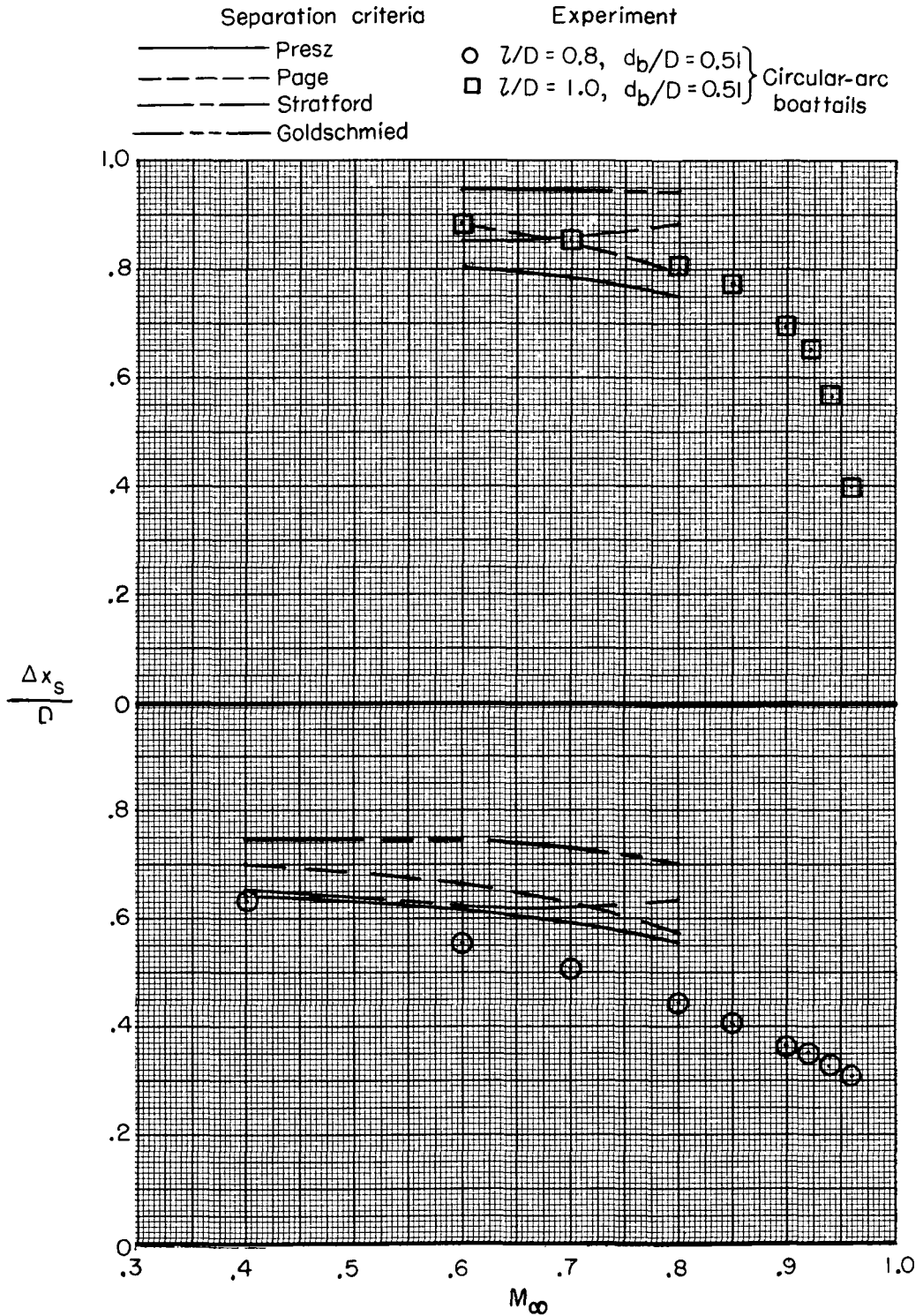


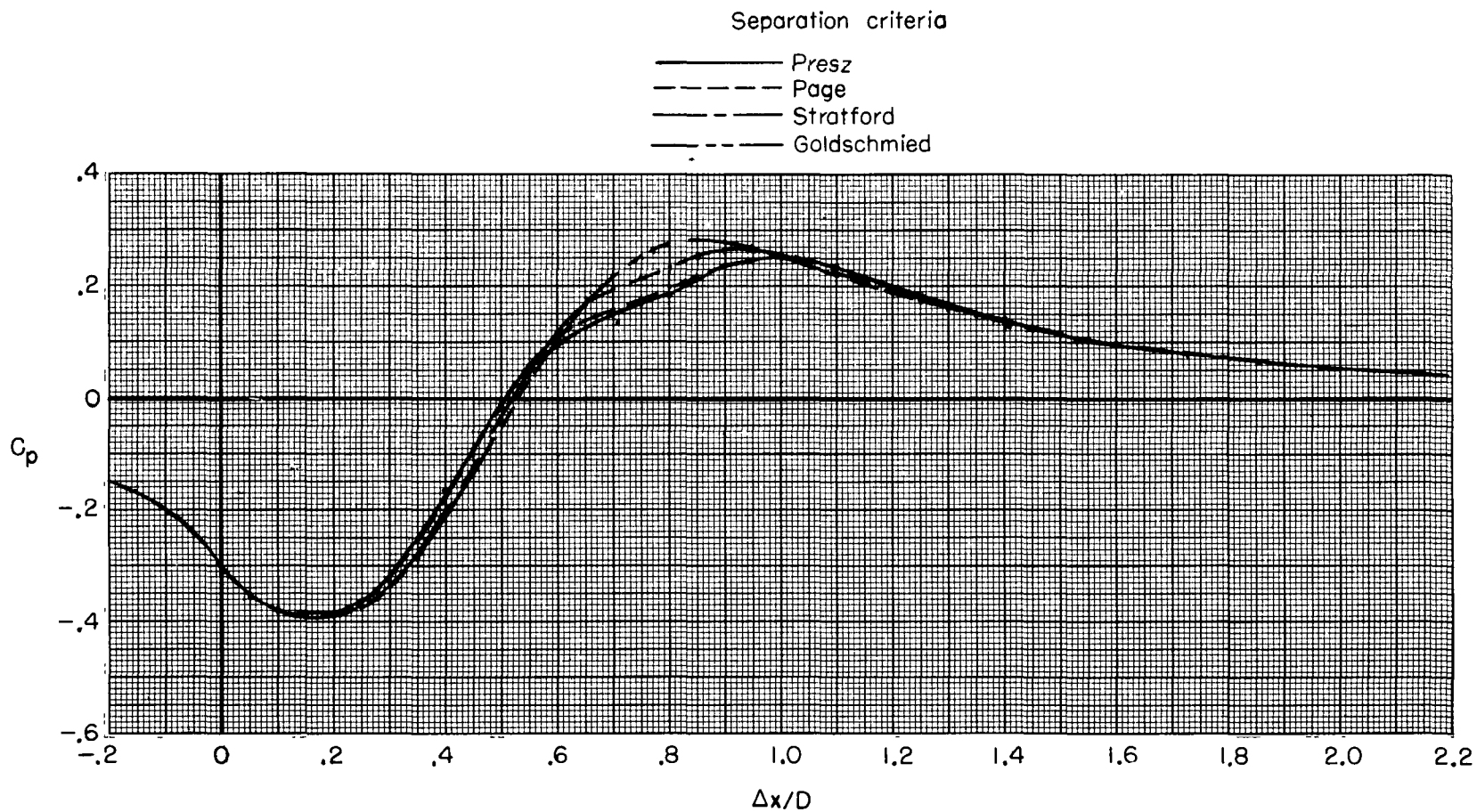
Figure 5.- Comparison of theory and experiment for flow over unseparated $l/D = 1.768$, $d_p/D = 0.51$ circular-arc nozzle with solid jet plume simulator. (Experimental data from ref. 22.)

TN-D-7192
Config #3



(a) Separation location.

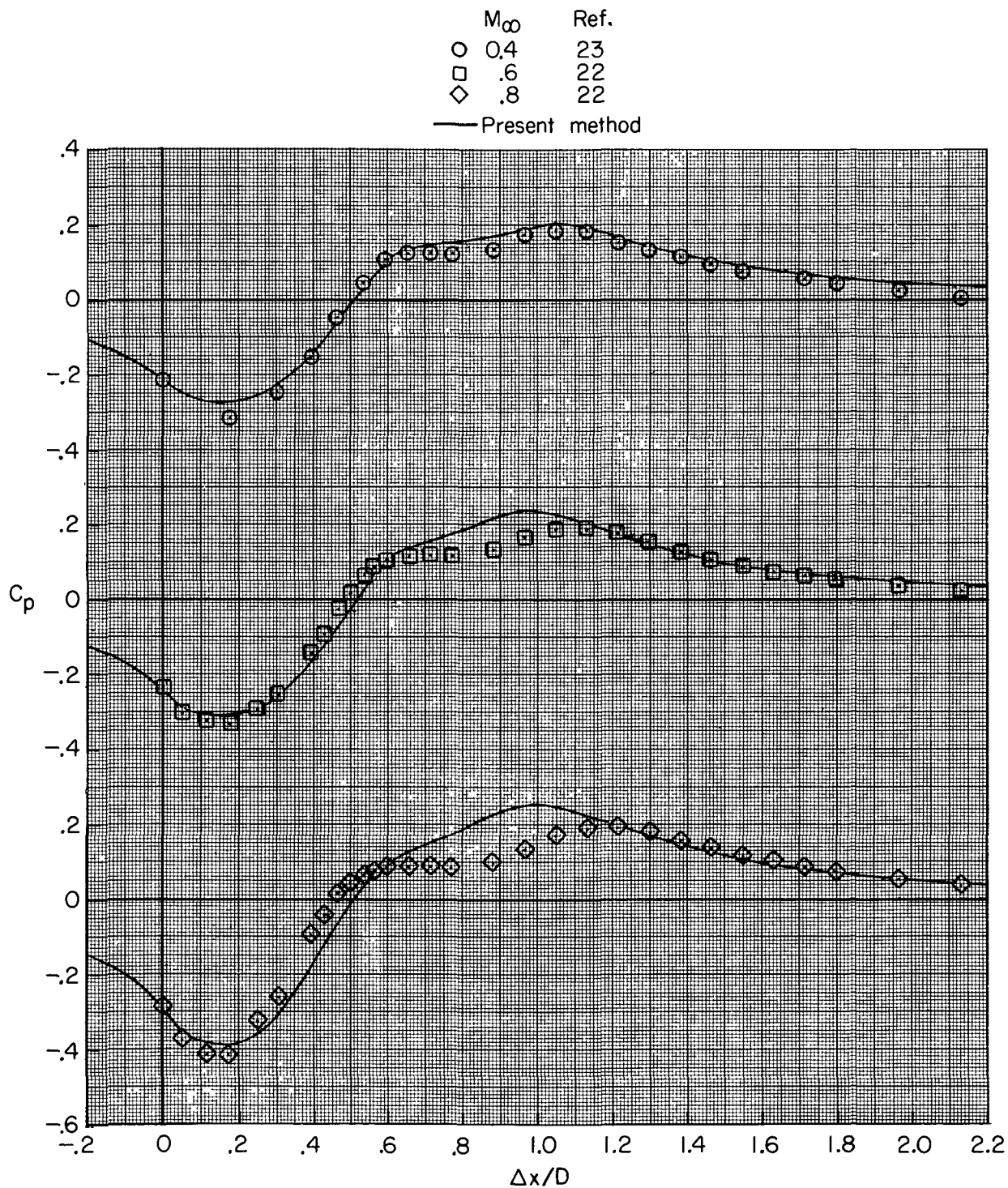
Figure 6.- Effect of separation location criteria. (Experimental data from ref. 21.)



(b) Predicted pressure distributions on $l/D = 0.8$, $d_b/D = 0.51$ circular-arc boattail at $M_\infty = 0.8$.

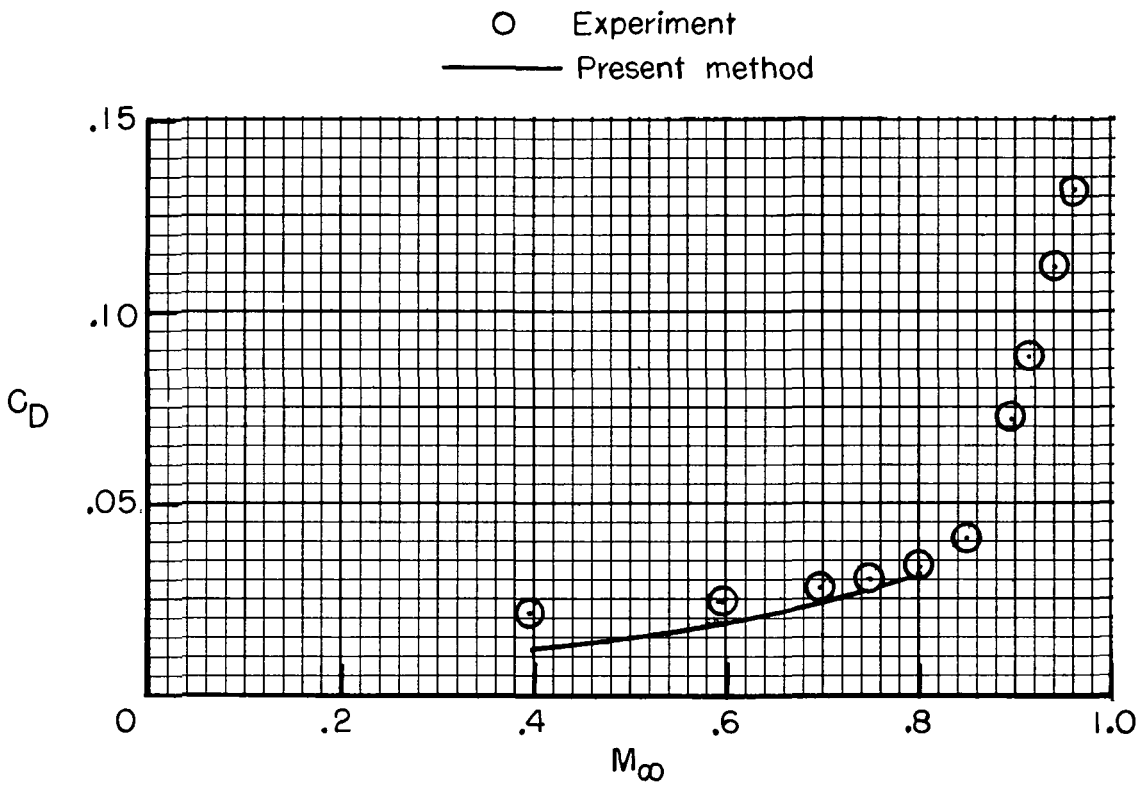
Figure 6.- Concluded.

- you can get any pressure drag you want by altering this assumption!!



(a) Pressure distribution.

Figure 7.- Effect of Mach number on flow over $l/D = 0.8$, $d_b/D = 0.51$ circular-arc boattail with solid jet plume simulator.



(b) Pressure drag coefficient.

Figure 7.- Concluded.

d_b/D	$C_{D, \text{exp}}$	$C_{D, p}$	
○ 0.51	0.020	0.022	- Config 2 (7795)
□ .61	.019	.015	- Config 4

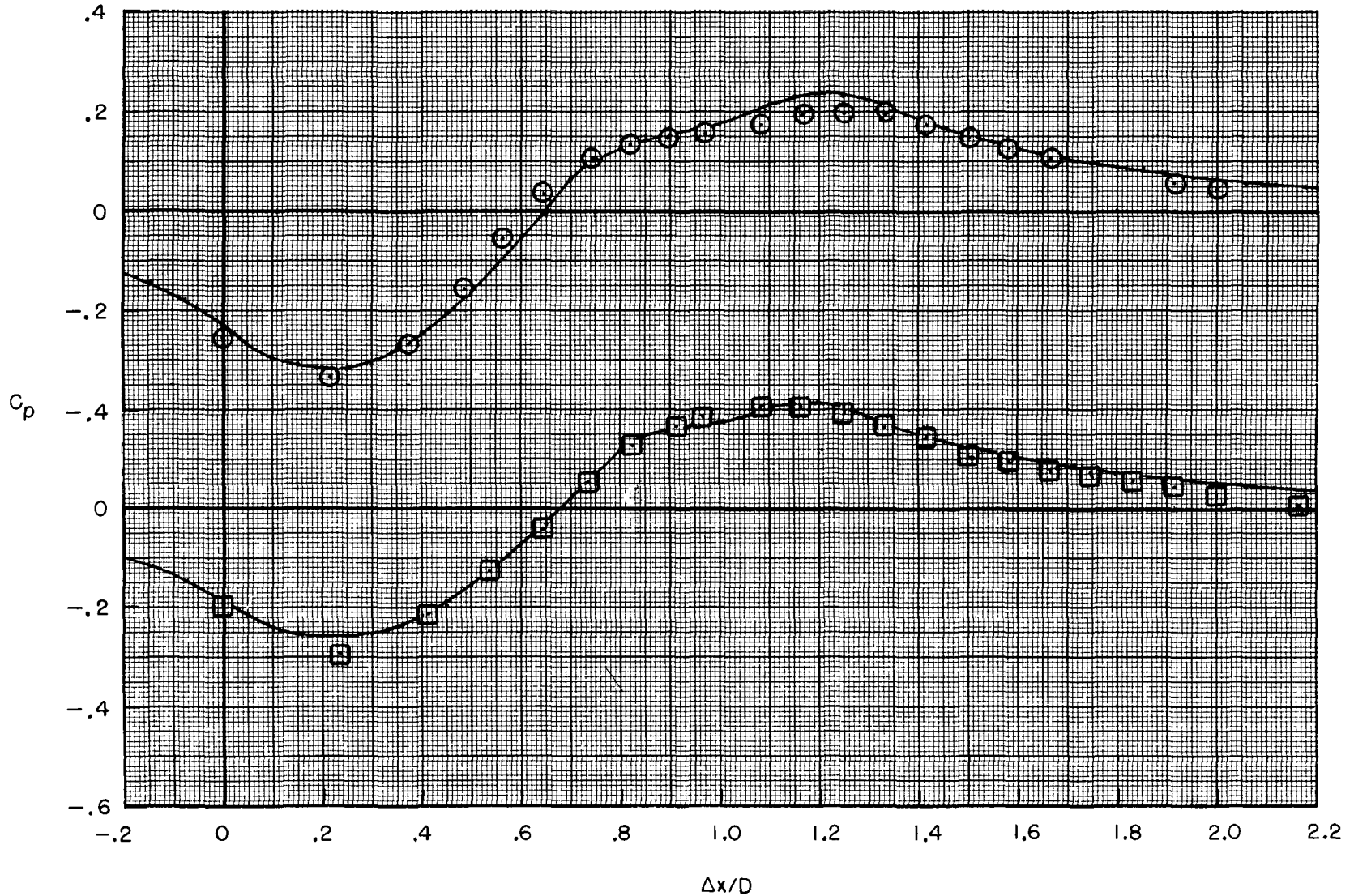
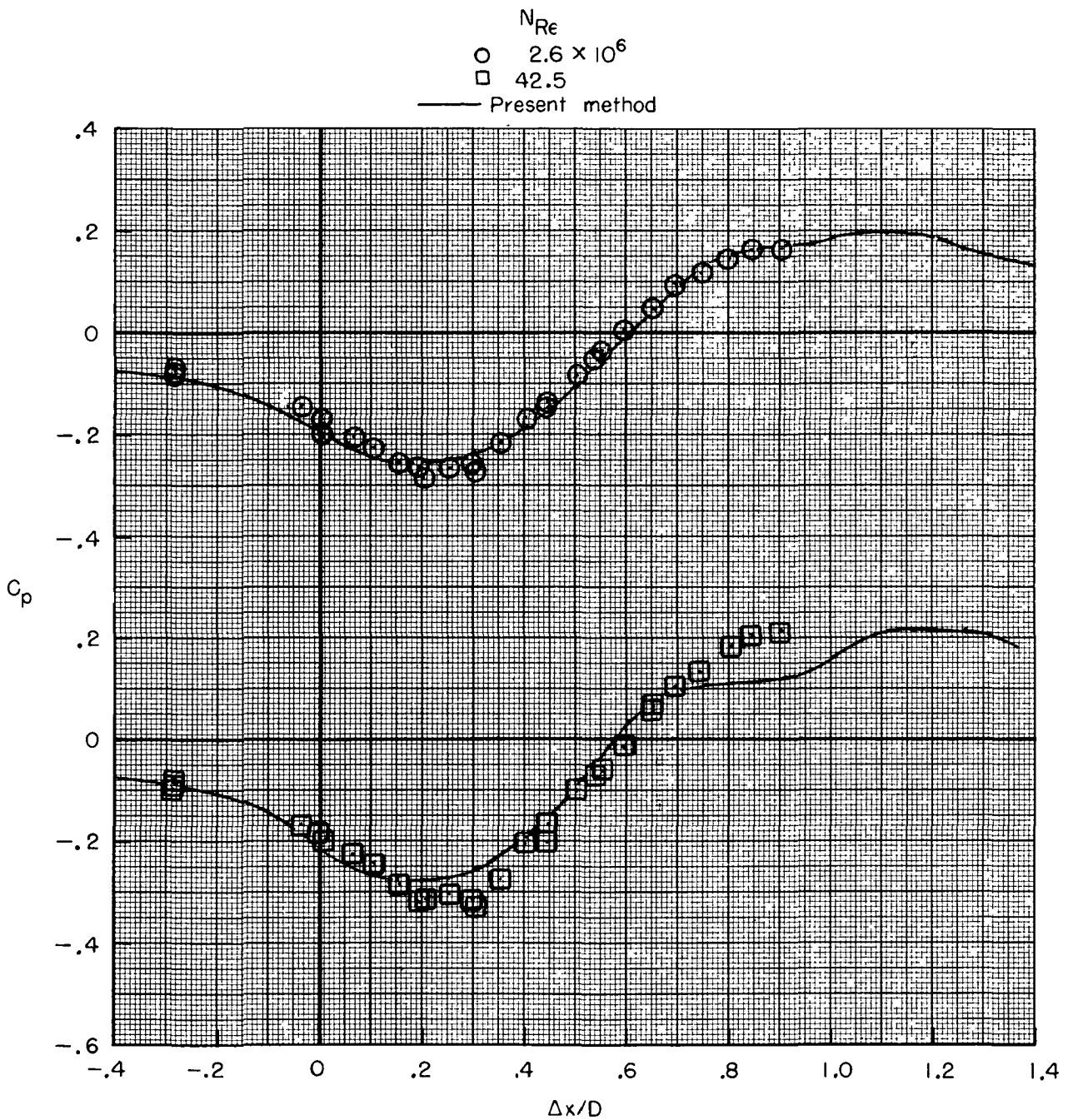


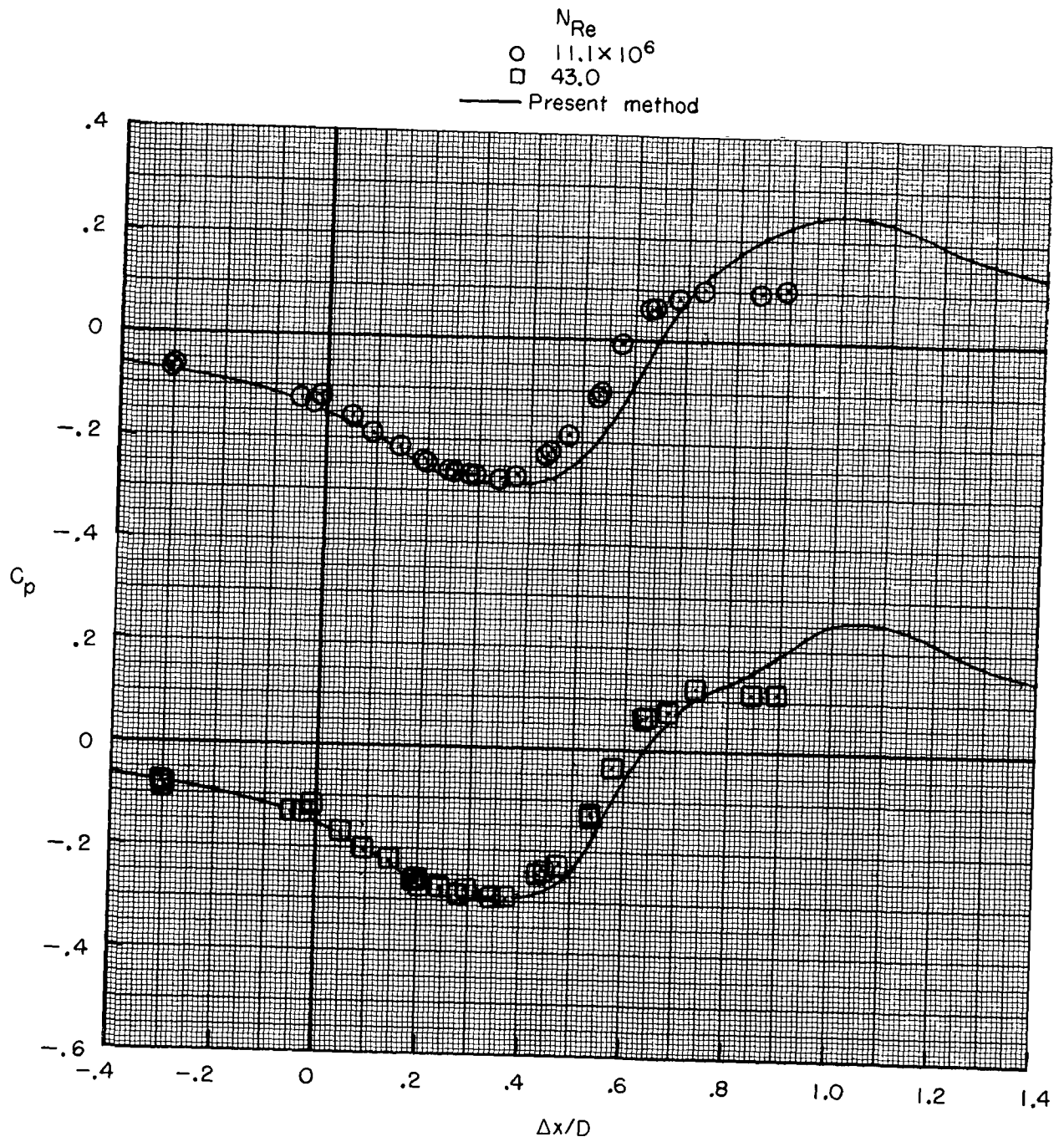
Figure 8.- Effect of afterbody closure on flow over $\lambda/D = 1.0$ circular-arc boattails with solid jet plume simulators. $M_\infty = 0.8$. (Experimental data from ref. 23.)



(a) Pressure distributions for $l/D = 0.961$, $d_b/D = 0.51$ circular-arc conic boattail.

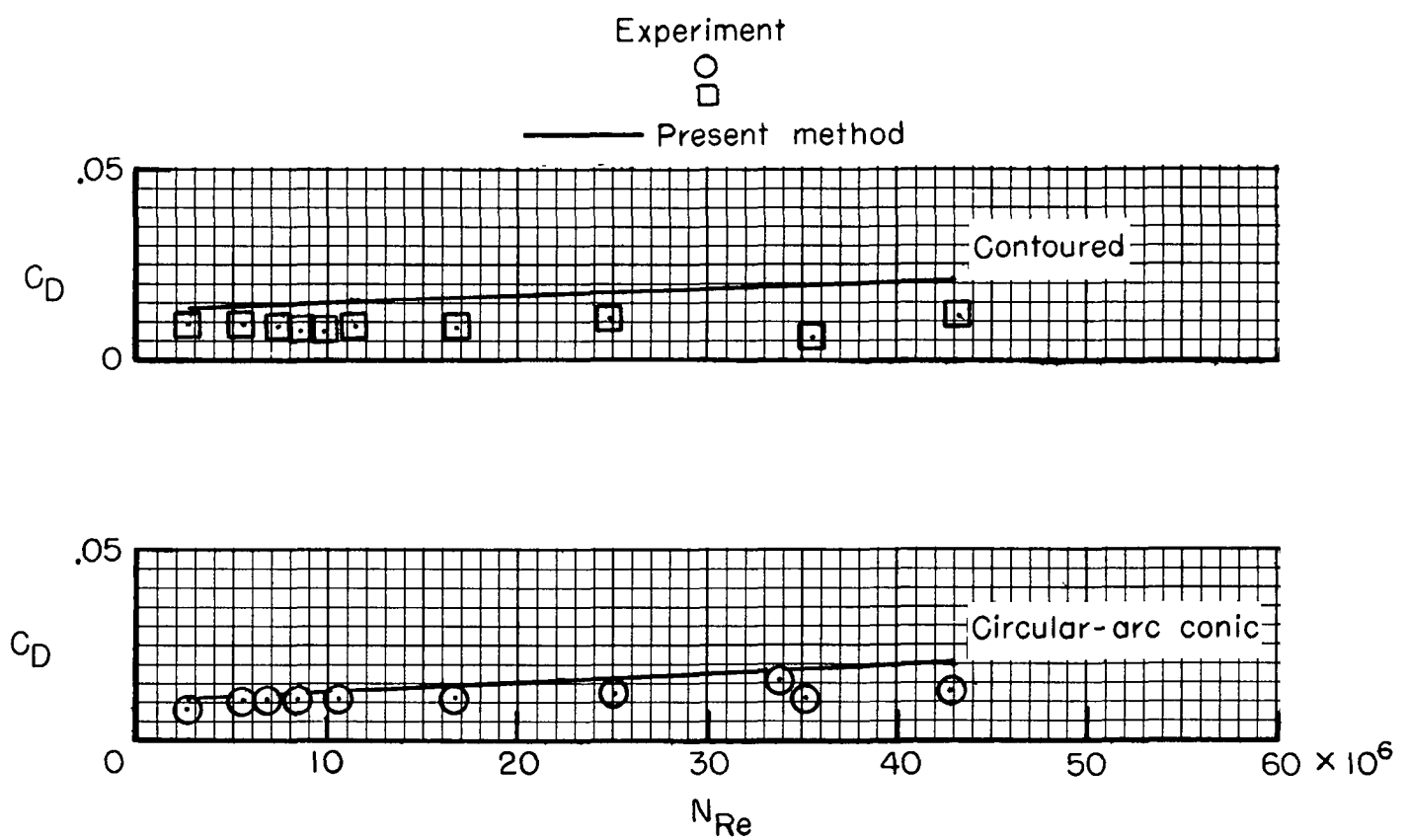
Figure 9.- Effect of Reynolds number on pressures and drag of afterbodies with solid jet plume simulators. $M_\infty = 0.6$. (Experimental data from ref. 1.)

TN-D-8210
 "Circular-arc conic"



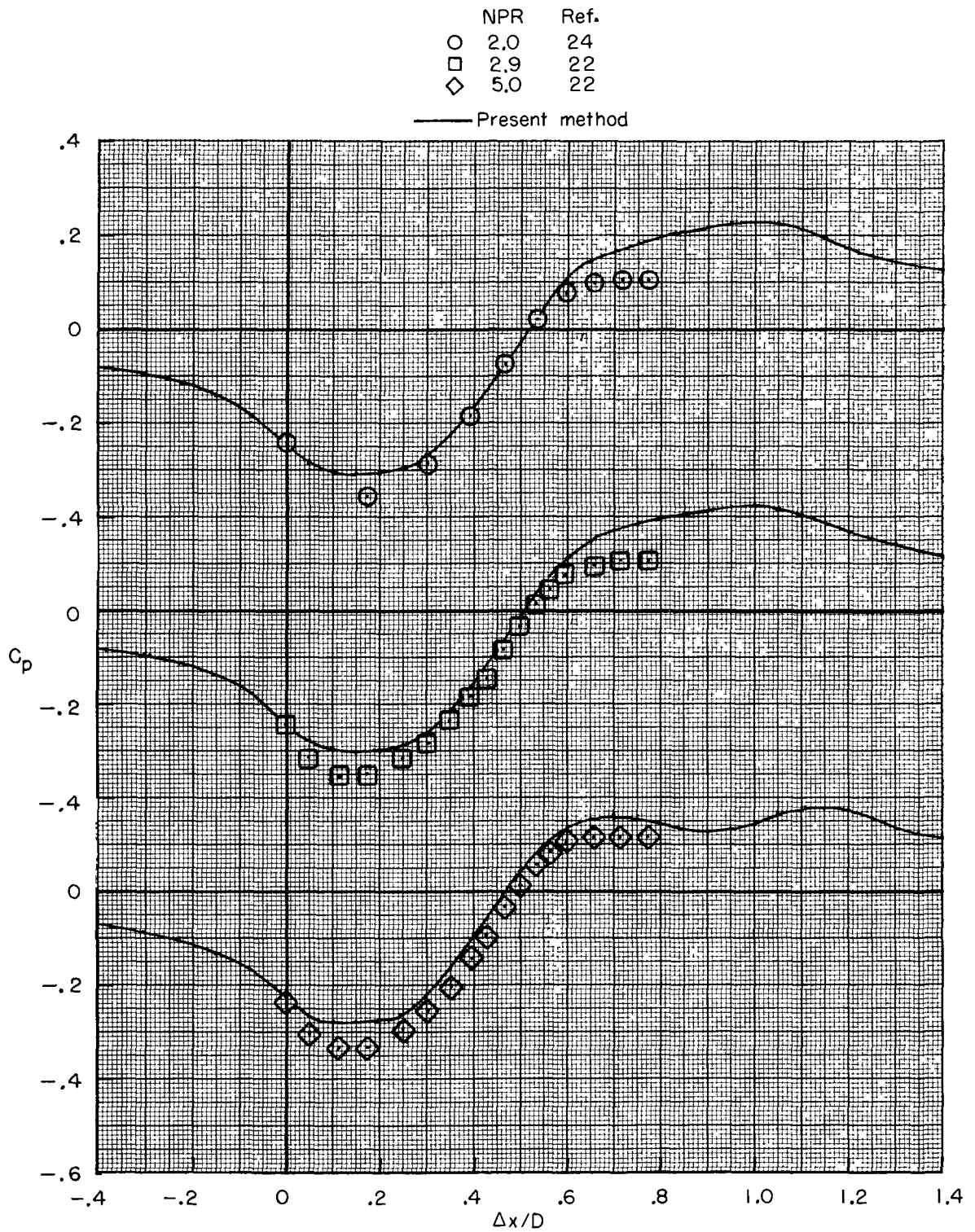
(b) Pressure distributions for $\lambda/D = 0.95$, $d_b/D = 0.544$ contoured boattail.

Figure 9.- Continued.



(c) Drag coefficient.

Figure 9.- Concluded.



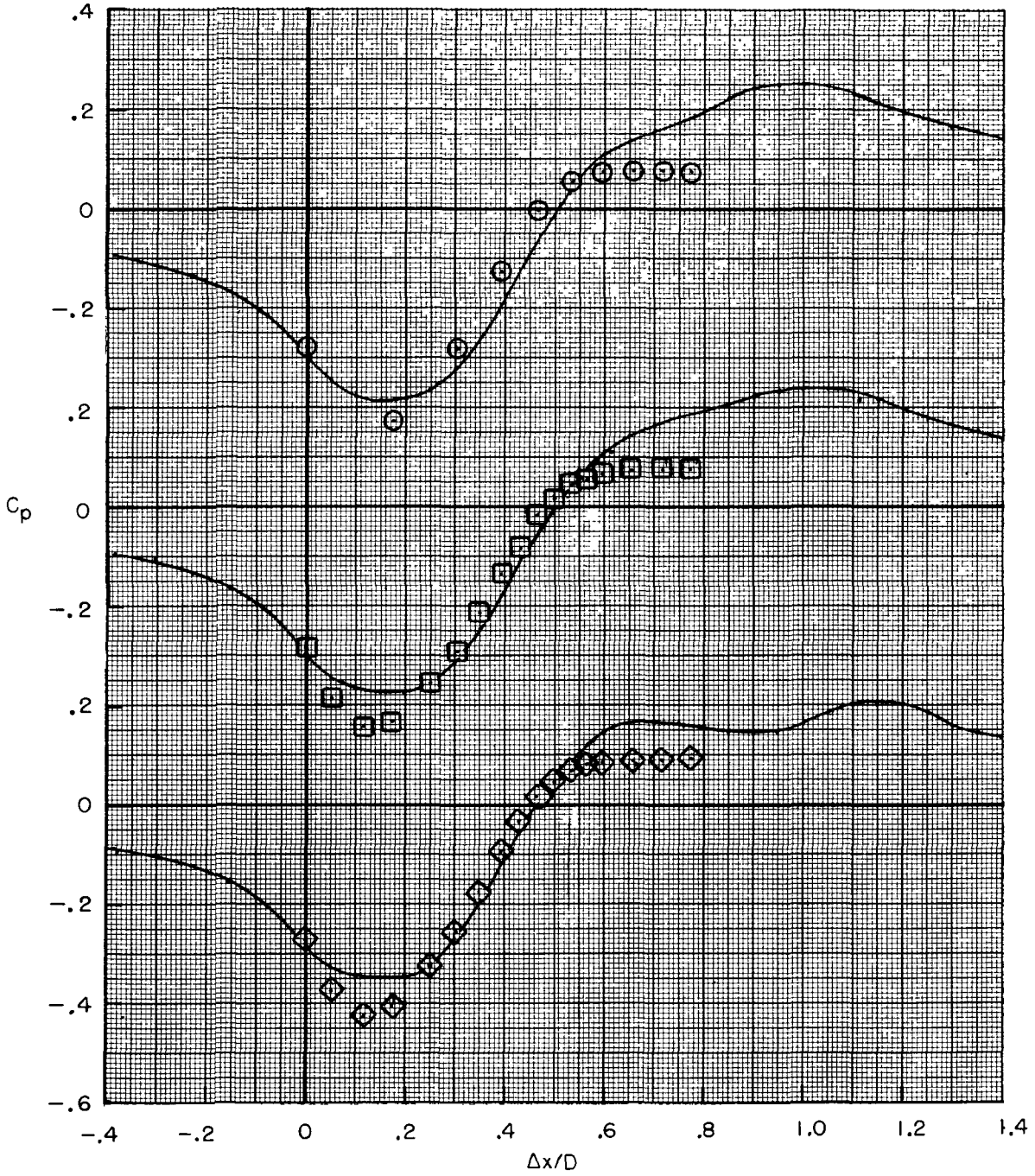
(a) Pressure distribution at $M_\infty = 0.6$.

Figure 10.- Effect of NPR on pressures and drag for $l/D = 0.8$, $d_b/D = 0.51$ circular-arc nozzle.

prediction is far more sensitive to NPR than the data

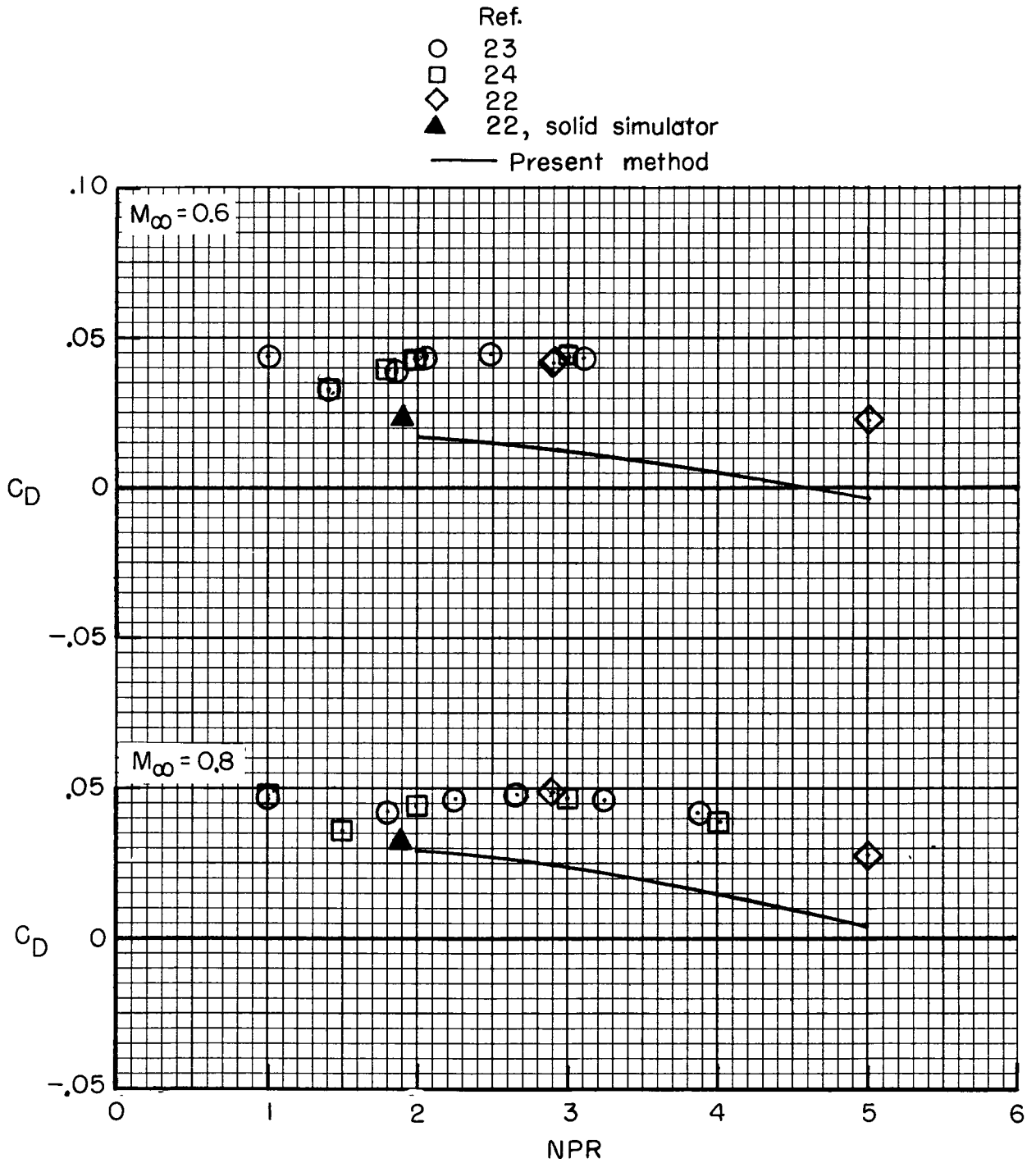
	NPR	Ref.
○	2.0	24
□	2.9	22
◇	5.0	22

— Present method



(b) Pressure distribution at $M_\infty = 0.8$.

Figure 10.- Continued.



(c) Drag coefficient.

Figure 10.- Concluded.

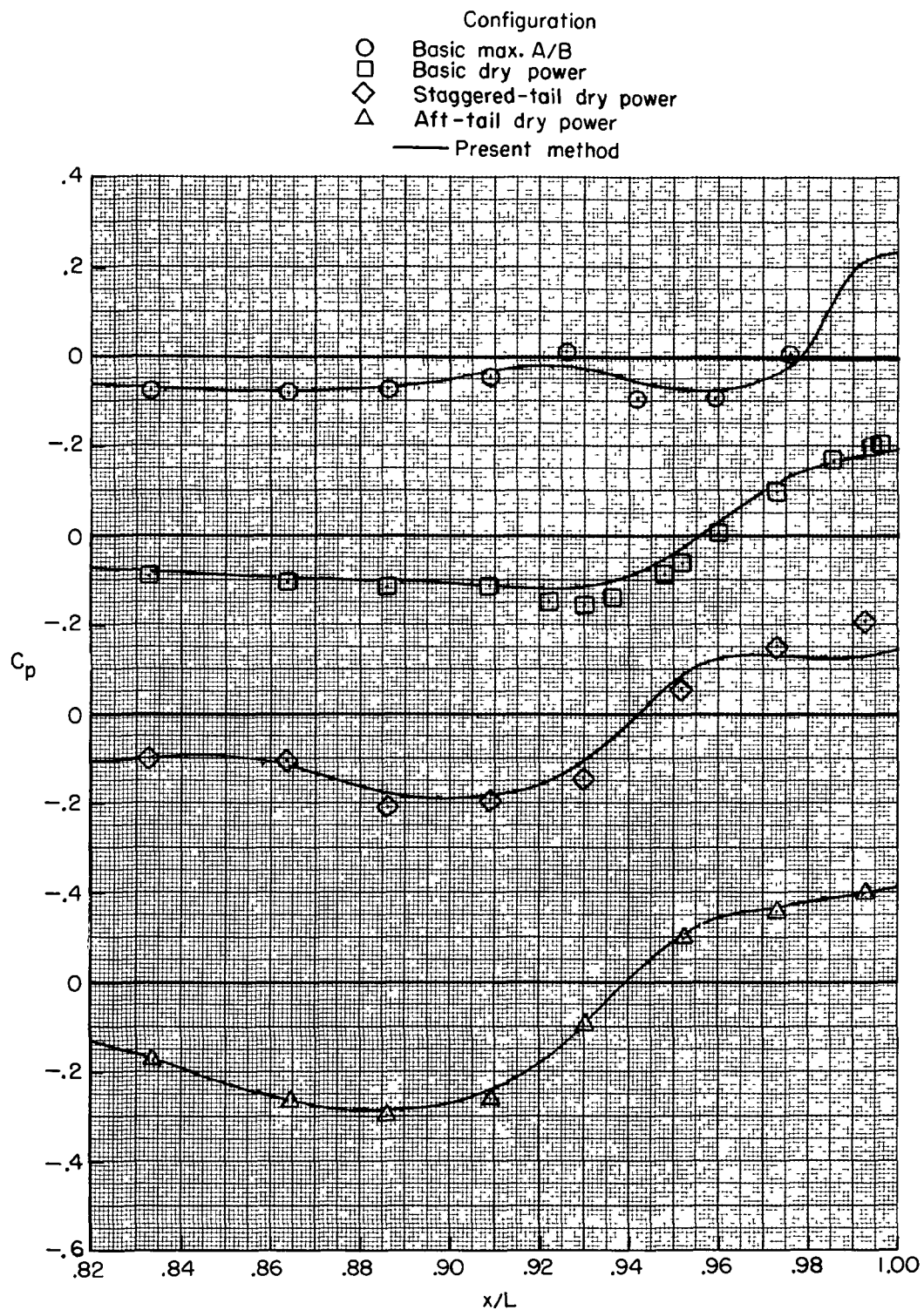


Figure 11.- Comparison of experimental and predicted pressures for equivalent bodies of Berrier (ref. 25). $M_\infty = 0.8$ and $NPR = 2.5$.

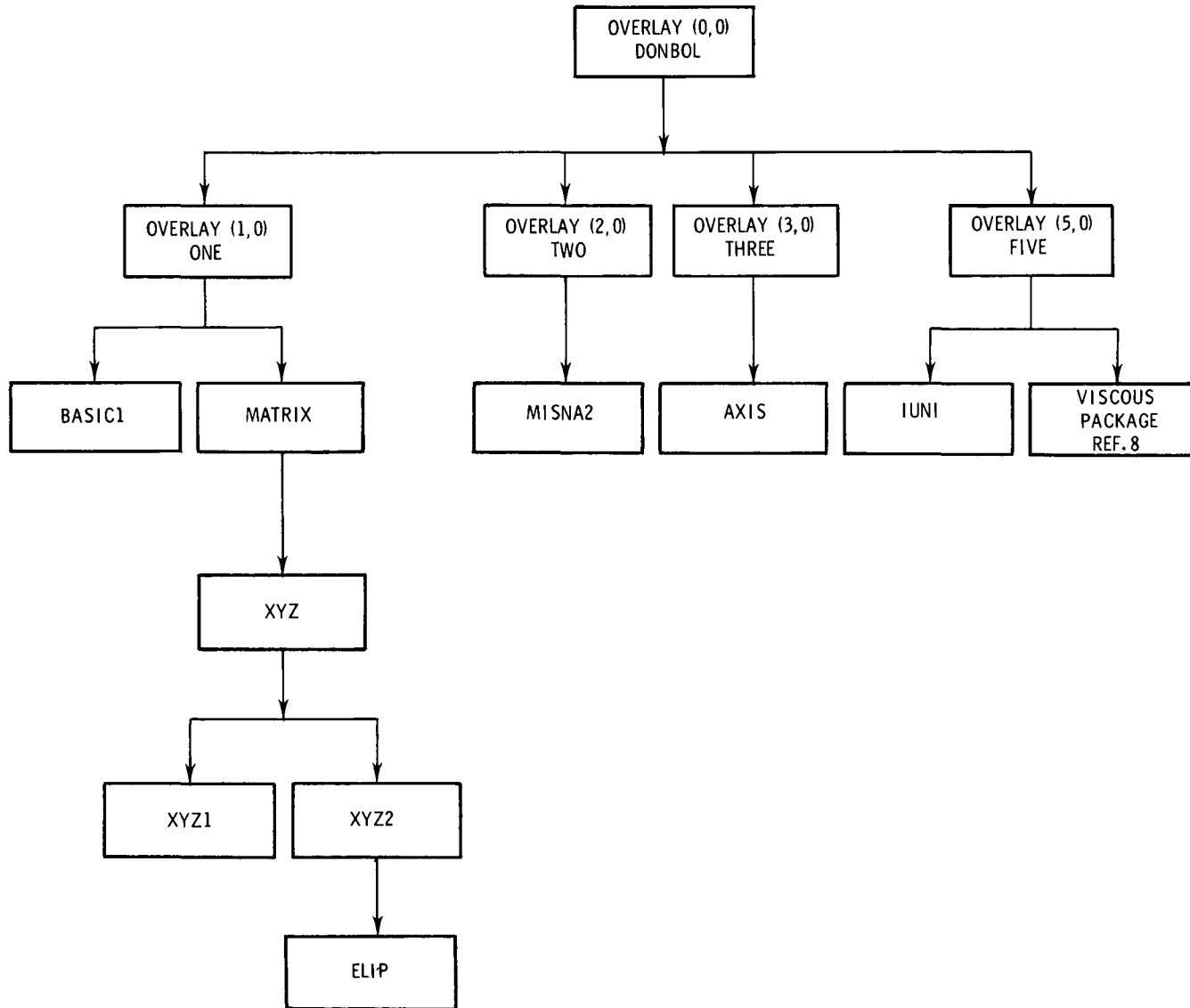


Figure 12.- Flow chart for program DONBOL.

DONBOL *** AN AXISYMMETRIC INVISCID/VISCID INTERACTION PROGRAM

BY LAWRENCE E. PUTNAM, NASA, LANGLEY RESEARCH CENTER

CASE TITLE = **TEST CASE** L/D=9 FOREBODY L/D=0.8 DB/D=0.51 CIRCULAR ARC NOZZLE NPR=5.03

***** CASE CONTROL DATA *****

OFF-BODY POINTS
 LABRUJERE COMPRESSIBILITY CORRECTION
 MODIFIED RESHOTKO TUCKER BOUNDARY LAYER SOLUTION
 PRESZ MODIFIED CONTROL VOLUME DISCRIMINATING STREAMLINE SOLUTION
 PRESZ CONTROL VOLUME SEPARATION LOCATION CRITERIA
 START SEARCH FOR SEPARATION AT I = 113
 END SEARCH FOR SEPARATION AT I = 135
 JET EXHAUST PLUME CALCULATION
 NOZZLE EXIT AT I = 135
 SMOOTH AERODYNAMIC CONTOUR
 SMOOTH PRESSURE DISTRIBUTION

FREE STREAM CONDITIONS

MACH NUMBER	=	.800	
TOTAL PRESSURE	=	100720,000	PASCALS
TOTAL TEMPERATURE	=	324,440	KELVIN
REYNOLDS NUMBER	=	12,182	MILLION PER METER

JET EXHAUST CONDITIONS AT NOZZLE EXIT

MACH NUMBER	=	1,000	
TOTAL PRESSURE	=	332342,700	PASCALS
TOTAL TEMPERATURE	=	295,560	KELVIN
NPR	=	5,030	

(a) Page 1.

Figure 14.- Sample output data.

FOR ITER# 0	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2
FOR ITER# 1	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2
FOR ITER# 2	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2
FOR ITER# 3	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2
FOR ITER# 4	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2
FOR ITER# 5	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2
FOR ITER# 6	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2
FOR ITER# 7	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2
FOR ITER# 8	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2
FOR ITER# 9	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2
FOR ITER# 10	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2
FOR ITER# 11	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2
FOR ITER# 12	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2
FOR ITER# 13	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2
FOR ITER# 14	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2
FOR ITER# 15	8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2

(b) Page 2.

Figure 14.- Continued.

TEST CASE L/D=9 FOREBODY L/D=0.8 DB/D=0.51 CIRCULAR ARC NOZZLE NPR=5.03

ITERATION NO 15

MO = .8000 TT = 324.44 KELVIN PT = 100720.0 PASCALS L = .192400 METERS GREP = .018242 SQ METERS

BOUNDARY LAYER SEPARATION AT X/L = 9.529286

BOUNDARY LAYER REATTACHMENT AT X/L = 11.633000

X/L	R/L	CP	CF	CDP	CDF	CDT	RD8/L	RC/L	DEL*/L	DEL/L	THETA/L	H
0.0000	0.0000	1.1704	.0095	0.0000	0.0000	0.0000	0.0000	.0001	0.0000	0.0000	0.0000	0.0000
.0763	.0190	.4430	.0095	.0006	.0000	.0007	.0190	.0191	.0001	.0010	.0001	1.3777
.1525	.0380	.2840	.0067	.0021	.0001	.0022	.0380	.0383	.0003	.0023	.0002	1.4627
.2288	.0570	.2635	.0058	.0041	.0003	.0043	.0570	.0575	.0005	.0035	.0003	1.4864
.3051	.0760	.2465	.0054	.0066	.0005	.0071	.0760	.0767	.0006	.0045	.0004	1.4909
.3814	.0951	.2318	.0051	.0097	.0007	.0104	.0951	.0958	.0008	.0054	.0005	1.4944
.4576	.1141	.2183	.0049	.0133	.0009	.0142	.1141	.1150	.0009	.0063	.0006	1.4974
.5339	.1331	.2052	.0047	.0173	.0013	.0185	.1331	.1341	.0010	.0071	.0007	1.5003
.6102	.1521	.1922	.0046	.0216	.0016	.0232	.1521	.1532	.0011	.0079	.0007	1.5030
.6864	.1711	.1788	.0045	.0261	.0020	.0281	.1711	.1724	.0012	.0086	.0008	1.5056
.7627	.1901	.1644	.0044	.0308	.0024	.0332	.1901	.1915	.0013	.0093	.0009	1.5082
.8390	.2091	.1484	.0043	.0356	.0029	.0385	.2091	.2106	.0014	.0100	.0009	1.5108
.9153	.2281	.1282	.0043	.0401	.0034	.0436	.2281	.2297	.0015	.0107	.0010	1.5131
.9915	.2471	.1023	.0042	.0443	.0040	.0483	.2471	.2488	.0016	.0113	.0010	1.5158
1.0678	.2659	.0722	.0042	.0476	.0046	.0522	.2659	.2675	.0016	.0118	.0011	1.5197
1.1441	.2839	.0472	.0041	.0500	.0053	.0552	.2839	.2856	.0017	.0124	.0011	1.5262
1.2203	.3011	.0259	.0041	.0514	.0060	.0574	.3011	.3029	.0018	.0130	.0012	1.5332
1.2966	.3176	.0066	.0040	.0521	.0067	.0588	.3176	.3195	.0019	.0136	.0012	1.5398
1.3729	.3333	-.0111	.0039	.0520	.0075	.0595	.3333	.3354	.0020	.0143	.0013	1.5460
1.4492	.3484	-.0274	.0039	.0512	.0084	.0595	.3484	.3505	.0021	.0150	.0014	1.5517
1.5254	.3627	-.0427	.0038	.0498	.0092	.0590	.3627	.3649	.0022	.0157	.0014	1.5571
1.6017	.3762	-.0569	.0038	.0478	.0101	.0579	.3762	.3786	.0023	.0164	.0015	1.5620
1.6780	.3891	-.0701	.0037	.0452	.0110	.0563	.3891	.3916	.0024	.0171	.0016	1.5667
1.7542	.4012	-.0823	.0037	.0423	.0119	.0543	.4012	.4038	.0025	.0178	.0016	1.5711
1.8305	.4127	-.0935	.0036	.0391	.0129	.0520	.4127	.4153	.0027	.0185	.0017	1.5753
1.9068	.4234	-.1038	.0036	.0355	.0139	.0494	.4234	.4262	.0028	.0193	.0018	1.5792
1.9831	.4334	-.1130	.0035	.0318	.0149	.0467	.4334	.4363	.0029	.0201	.0018	1.5829
2.0593	.4427	-.1214	.0035	.0280	.0159	.0439	.4427	.4457	.0030	.0208	.0019	1.5864
2.1356	.4512	-.1287	.0034	.0241	.0169	.0410	.4512	.4544	.0032	.0217	.0020	1.5897
2.2119	.4591	-.1351	.0034	.0204	.0179	.0383	.4591	.4624	.0033	.0225	.0021	1.5928
2.2881	.4663	-.1403	.0033	.0167	.0190	.0357	.4663	.4698	.0034	.0233	.0021	1.5957
2.3644	.4728	-.1445	.0033	.0132	.0200	.0332	.4728	.4764	.0036	.0242	.0022	1.5984
2.4407	.4786	-.1475	.0033	.0100	.0211	.0311	.4786	.4823	.0037	.0251	.0023	1.6009
2.5169	.4837	-.1492	.0032	.0071	.0221	.0292	.4837	.4876	.0039	.0260	.0024	1.6032
2.5932	.4881	-.1496	.0032	.0045	.0232	.0277	.4881	.4921	.0040	.0270	.0025	1.6054

(c) Page 3.

Figure 14.- Continued.

MO = .8000 TT = 324.44 KELVIN PT = 100720.0 PASCALS L = .152400 METERS SREF = .010242 SQ METERS

BOUNDARY LAYER SEPARATION AT X/L = 9.529286

BOUNDARY LAYER REATTACHMENT AT X/L = 11.633000

X/L	R/L	CP	CF	CDP	CDF	CDT	RDS/L	RC/L	DEL*/L	DEL/L	THETA/L	H
2.6695	.4918	-.1484	.0031	.0024	.0242	.0266	.4918	.4960	.0042	.0280	.0026	1.6075
2.7458	.4948	-.1492	.0031	.0006	.0252	.0258	.4948	.4992	.0044	.0290	.0027	1.6095
2.8220	.4972	-.1397	.0030	-.0007	.0262	.0255	.4972	.5018	.0046	.0301	.0029	1.6116
2.8983	.4988	-.1314	.0030	-.0016	.0272	.0256	.4988	.5036	.0048	.0313	.0030	1.6138
2.9746	.4997	-.1173	.0029	-.0021	.0282	.0261	.4997	.5048	.0051	.0325	.0032	1.6169
3.0508	.5000	-.0979	.0028	-.0022	.0291	.0270	.5000	.5054	.0054	.0339	.0033	1.6209
3.1271	.5000	-.0790	.0028	-.0022	.0300	.0279	.5000	.5058	.0058	.0353	.0035	1.6240
3.2034	.5000	-.0665	.0027	-.0022	.0309	.0288	.5000	.5060	.0060	.0366	.0037	1.6244
3.2797	.5000	-.0576	.0027	-.0022	.0318	.0296	.5000	.5063	.0063	.0380	.0039	1.6234
3.3559	.5000	-.0508	.0027	-.0022	.0326	.0305	.5000	.5065	.0065	.0393	.0040	1.6217
3.4322	.5000	-.0454	.0026	-.0022	.0335	.0313	.5000	.5067	.0067	.0406	.0041	1.6196
3.5085	.5000	-.0411	.0026	-.0022	.0343	.0321	.5000	.5069	.0069	.0419	.0043	1.6174
3.5847	.5000	-.0374	.0026	-.0022	.0351	.0329	.5000	.5071	.0071	.0432	.0044	1.6152
3.6610	.5000	-.0343	.0026	-.0022	.0359	.0338	.5000	.5073	.0073	.0444	.0045	1.6130
3.7373	.5000	-.0317	.0026	-.0022	.0367	.0346	.5000	.5074	.0074	.0457	.0046	1.6108
3.8136	.5000	-.0294	.0026	-.0022	.0375	.0354	.5000	.5076	.0076	.0469	.0047	1.6087
3.8898	.5000	-.0275	.0026	-.0022	.0383	.0362	.5000	.5078	.0078	.0481	.0048	1.6068
3.9661	.5000	-.0257	.0025	-.0022	.0391	.0370	.5000	.5079	.0079	.0493	.0050	1.6049
4.0424	.5000	-.0242	.0025	-.0022	.0399	.0377	.5000	.5081	.0081	.0504	.0051	1.6031
4.1186	.5000	-.0229	.0025	-.0022	.0407	.0385	.5000	.5083	.0083	.0516	.0052	1.6015
4.1949	.5000	-.0217	.0025	-.0022	.0415	.0393	.5000	.5084	.0084	.0528	.0053	1.5999
4.2712	.5000	-.0206	.0025	-.0022	.0423	.0401	.5000	.5086	.0086	.0539	.0054	1.5985
4.3475	.5000	-.0197	.0025	-.0022	.0430	.0409	.5000	.5088	.0088	.0550	.0055	1.5971
4.4237	.5000	-.0188	.0025	-.0022	.0438	.0416	.5000	.5089	.0089	.0562	.0056	1.5958
4.5000	.5000	-.0180	.0025	-.0022	.0446	.0424	.5000	.5091	.0091	.0573	.0057	1.5946
4.5763	.5000	-.0173	.0025	-.0022	.0453	.0432	.5000	.5092	.0092	.0584	.0058	1.5935
4.6525	.5000	-.0167	.0025	-.0022	.0461	.0439	.5000	.5094	.0094	.0595	.0059	1.5924
4.7288	.5000	-.0161	.0025	-.0022	.0469	.0447	.5000	.5095	.0095	.0605	.0060	1.5914
4.8051	.5000	-.0156	.0025	-.0022	.0476	.0455	.5000	.5097	.0097	.0616	.0061	1.5905
4.8814	.5000	-.0152	.0024	-.0022	.0484	.0462	.5000	.5098	.0098	.0627	.0062	1.5896
4.9576	.5000	-.0148	.0024	-.0022	.0491	.0470	.5000	.5100	.0100	.0638	.0063	1.5888
5.0339	.5000	-.0144	.0024	-.0022	.0499	.0477	.5000	.5101	.0101	.0648	.0064	1.5880
5.1102	.5000	-.0141	.0024	-.0022	.0506	.0485	.5000	.5103	.0103	.0658	.0065	1.5872
5.1864	.5000	-.0138	.0024	-.0022	.0514	.0492	.5000	.5104	.0104	.0669	.0066	1.5865
5.2627	.5000	-.0135	.0024	-.0022	.0521	.0500	.5000	.5106	.0106	.0679	.0067	1.5859

(d) Page 4.

Figure 14.- Continued.

TEST CASE L/D=9 FOREBODY L/D=0.8 DB/D=0.51 CIRCULAR ARC NOZZLE NPR=5.03

ITERATION NO 15

MO = .8000 TT = 324.44 KELVIN PT = 100720.0 PASCALS L = .152400 METERS BREF = .018242 SQ METERS

BOUNDARY LAYER SEPARATION AT X/L = 9.529286

BOUNDARY LAYER REATTACHMENT AT X/L = 11.633000

X/L	R/L	CP	CF	COP	COF	CDT	RDS/L	RC/L	DEI*/L	DEL/L	THETA/L	H
5.3390	.5000	-.0133	.0024	-.0022	.0529	.0507	.5000	.5107	.0107	.0689	.0067	1.5852
5.4153	.5000	-.0131	.0024	-.0022	.0536	.0514	.5000	.5108	.0108	.0700	.0068	1.5846
5.4915	.5000	-.0130	.0024	-.0022	.0543	.0522	.5000	.5110	.0110	.0710	.0069	1.5841
5.5678	.5000	-.0128	.0024	-.0022	.0551	.0529	.5000	.5111	.0111	.0720	.0070	1.5835
5.6441	.5000	-.0127	.0024	-.0022	.0558	.0536	.5000	.5113	.0113	.0730	.0071	1.5830
5.7203	.5000	-.0127	.0024	-.0022	.0565	.0544	.5000	.5114	.0114	.0740	.0072	1.5825
5.7966	.5000	-.0126	.0024	-.0022	.0573	.0551	.5000	.5116	.0116	.0750	.0073	1.5820
5.8729	.5000	-.0126	.0024	-.0022	.0580	.0558	.5000	.5117	.0117	.0760	.0074	1.5816
5.9492	.5000	-.0126	.0023	-.0022	.0587	.0566	.5000	.5118	.0118	.0769	.0075	1.5812
6.0254	.5000	-.0127	.0023	-.0022	.0594	.0573	.5000	.5120	.0120	.0779	.0076	1.5807
6.1017	.5000	-.0127	.0023	-.0022	.0602	.0580	.5000	.5121	.0121	.0789	.0077	1.5803
6.1780	.5000	-.0128	.0023	-.0022	.0609	.0587	.5000	.5122	.0122	.0799	.0077	1.5800
6.2542	.5000	-.0130	.0023	-.0022	.0616	.0594	.5000	.5124	.0124	.0808	.0078	1.5796
6.3305	.5000	-.0131	.0023	-.0022	.0623	.0602	.5000	.5125	.0125	.0818	.0079	1.5793
6.4068	.5000	-.0133	.0023	-.0022	.0630	.0609	.5000	.5126	.0126	.0827	.0080	1.5789
6.4831	.5000	-.0135	.0023	-.0022	.0637	.0616	.5000	.5128	.0128	.0837	.0081	1.5786
6.5593	.5000	-.0138	.0023	-.0022	.0645	.0623	.5000	.5129	.0129	.0846	.0082	1.5783
6.6356	.5000	-.0141	.0023	-.0022	.0652	.0630	.5000	.5130	.0130	.0855	.0083	1.5779
6.7119	.5000	-.0144	.0023	-.0022	.0659	.0637	.5000	.5132	.0132	.0865	.0083	1.5776
6.7881	.5000	-.0148	.0023	-.0022	.0666	.0644	.5000	.5133	.0133	.0874	.0084	1.5773
6.8644	.5000	-.0153	.0023	-.0022	.0673	.0651	.5000	.5134	.0134	.0883	.0085	1.5770
6.9407	.5000	-.0157	.0023	-.0022	.0680	.0658	.5000	.5135	.0135	.0892	.0086	1.5767
7.0169	.5000	-.0163	.0023	-.0022	.0687	.0665	.5000	.5137	.0137	.0901	.0087	1.5764
7.0932	.5000	-.0169	.0023	-.0022	.0694	.0672	.5000	.5138	.0138	.0911	.0087	1.5762
7.1695	.5000	-.0176	.0023	-.0022	.0701	.0679	.5000	.5139	.0139	.0920	.0088	1.5759
7.2458	.5000	-.0184	.0023	-.0022	.0708	.0686	.5000	.5140	.0140	.0928	.0089	1.5756
7.3220	.5000	-.0192	.0023	-.0022	.0715	.0693	.5000	.5141	.0141	.0937	.0090	1.5753
7.3983	.5000	-.0202	.0023	-.0022	.0722	.0700	.5000	.5143	.0143	.0946	.0091	1.5749
7.4746	.5000	-.0213	.0023	-.0022	.0729	.0707	.5000	.5144	.0144	.0955	.0091	1.5746
7.5508	.5000	-.0225	.0023	-.0022	.0736	.0714	.5000	.5145	.0145	.0963	.0092	1.5743
7.6271	.5000	-.0239	.0022	-.0022	.0743	.0721	.5000	.5146	.0146	.0972	.0093	1.5739
7.7034	.5000	-.0255	.0022	-.0022	.0750	.0728	.5000	.5147	.0147	.0981	.0093	1.5735
7.7797	.5000	-.0273	.0022	-.0022	.0757	.0735	.5000	.5148	.0148	.0989	.0094	1.5731
7.8559	.5000	-.0294	.0022	-.0022	.0764	.0742	.5000	.5149	.0149	.0997	.0094	1.5727
7.9322	.5000	-.0317	.0022	-.0022	.0771	.0749	.5000	.5149	.0149	.1005	.0095	1.5722

(e) Page 5.

Figure 14.- Continued.

MO = .8000 TT = 324.44 KELVIN PT = 100720.0 PASCALS L = .152400 METERS SREF = .018242 80 METERS

BOUNDARY LAYER SEPARATION AT X/L = 9.529286

BOUNDARY LAYER REATTACHMENT AT X/L = 11.633000

X/L	R/L	CP	CF	CDP	CDF	CDT	RD8/L	RC/L	DEL*/L	DEL/L	THETA/L	H
8.0085	.5000	-.0344	.0022	-.0022	.0778	.0756	.5000	.5150	.0150	.1013	.0095	1.5716
8.0847	.5000	-.0376	.0022	-.0022	.0785	.0763	.5000	.5151	.0151	.1021	.0096	1.5710
8.1610	.5000	-.0413	.0022	-.0022	.0792	.0770	.5000	.5151	.0151	.1029	.0096	1.5703
8.2373	.5000	-.0457	.0023	-.0022	.0799	.0777	.5000	.5151	.0151	.1036	.0097	1.5695
8.3136	.5000	-.0512	.0023	-.0022	.0806	.0784	.5000	.5152	.0152	.1043	.0097	1.5688
8.3898	.5000	-.0570	.0023	-.0022	.0813	.0792	.5000	.5151	.0152	.1050	.0097	1.5677
8.4661	.5000	-.0652	.0023	-.0022	.0820	.0799	.5000	.5151	.0151	.1056	.0096	1.5663
8.5424	.5000	-.0745	.0023	-.0022	.0828	.0806	.5000	.5150	.0150	.1062	.0096	1.5650
8.6186	.5000	-.0868	.0023	-.0022	.0835	.0813	.5000	.5149	.0149	.1067	.0095	1.5633
8.6949	.5000	-.1029	.0023	-.0022	.0843	.0821	.5000	.5147	.0147	.1071	.0094	1.5613
8.7712	.5000	-.1246	.0024	-.0022	.0850	.0829	.5000	.5144	.0144	.1074	.0092	1.5590
8.8475	.5000	-.1538	.0024	-.0022	.0858	.0837	.5000	.5139	.0140	.1076	.0090	1.5566
8.9237	.5000	-.2017	.0025	-.0022	.0867	.0845	.5000	.5132	.0133	.1074	.0086	1.5543
9.0000	.5000	-.2803	.0026	-.0022	.0876	.0854	.5000	.5120	.0123	.1069	.0079	1.5546
9.0500	.4991	-.3242	.0027	-.0011	.0882	.0871	.4991	.5103	.0118	.1071	.0076	1.5587
9.1000	.4965	-.3423	.0027	.0024	.0888	.0912	.4965	.5075	.0118	.1078	.0075	1.5623
9.1500	.4921	-.3434	.0027	.0083	.0895	.0978	.4921	.5033	.0120	.1090	.0077	1.5647
9.2000	.4859	-.3422	.0026	.0166	.0901	.1067	.4859	.4978	.0123	.1106	.0078	1.5668
9.2500	.4780	-.3230	.0026	.0268	.0907	.1175	.4780	.4908	.0129	.1129	.0082	1.5682
9.3000	.4681	-.2700	.0025	.0379	.0913	.1291	.4681	.4823	.0141	.1162	.0090	1.5700
9.3500	.4565	-.1939	.0023	.0479	.0918	.1397	.4565	.4725	.0160	.1206	.0102	1.5763
9.4000	.4429	-.1081	.0021	.0553	.0922	.1475	.4429	.4617	.0187	.1266	.0118	1.5915
9.4500	.4273	-.0254	.0019	.0590	.0926	.1516	.4273	.4502	.0222	.1342	.0137	1.6177
9.5000	.4096	.0471	.0017	.0584	.0929	.1513	.4096	.4387	.0265	.1435	.0160	1.6543
9.5500	.3899	.1034	.0015	.0537	.0931	.1468	.3899	.4275	.0311	.1533	.0184	1.6952
9.6000	.3679	.1426	.0014	.0453	.0933	.1388	.3679	.4170	.0352	.1617	.0203	1.7320
9.6500	.3436	.1621	.0013	.0350	.0935	.1285	.3436	.4073	.0382	.1694	.0218	1.7521
9.7000	.3168	.1632	.0013	.0235	.0937	.1171	.3168	.3986	.0396	.1761	.0226	1.7496
9.7500	.2873	.1619	.0013	.0119	.0938	.1057	.2873	.3914	.0408	.1829	.0234	1.7444
9.8000	.2550	.1518	.0013	.0009	.0939	.0948	.2550	.3851	.0412	.1893	.0238	1.7288
9.8500	.2267	.1418	.0014	-.0006	.0940	.0935	.2267	.3790	.0379	.1984	.0221	1.7147
9.9000	.2071	.1391	.0014	-.0006	.0942	.0936	.2071	.3730	.0390	.1853	.0228	1.7093
9.9500	.2069	.1395	.0014	-.0006	.0943	.0937	.2069	.3666	.0406	.1933	.0238	1.7074
10.0000	.2061	.1538	.0013	-.0006	.0944	.0938	.2061	.3599	.0438	.2038	.0255	1.7208
10.0500	.2049	.1899	.0012	-.0006	.0945	.0939	.2049	.3531	.0503	.2180	.0285	1.7645

attached

separated

(f) Page 6.

Figure 14.- Continued.

↑
C_f > 0 in
separated
region

TEST CASE L/D=9 FOREBODY L/D=0.8 DB/D=0.51 CIRCULAR ARC NOZZLE NPR=5.03

ITERATION NO 15

MO = .8000 TT = 324.44 KELVIN PT = 100720.0 PASCALS L = .152400 METERS SREF = .018242 SQ METERS

BOUNDARY LAYER SEPARATION AT X/L = 9.529286

BOUNDARY LAYER REATTACHMENT AT X/L = 11.633000

Separated

X/L	R/L	CP	CF	CDP	CDF	CDT	RDS/L	RC/L	DEL*/L	DEL/L	THETA/L	H
10.1000	.2840	.2065	.0011	-.0006	.0946	.0940	.2858	.3469	.0552	.2312	.0309	1.7863
10.1500	.2839	.2083	.0011	-.0006	.0947	.0941	.2835	.3422	.0558	.2340	.0313	1.7858
10.2000	.2843	.2037	.0011	-.0006	.0948	.0942	.2839	.3389	.0550	.2338	.0310	1.7753
10.2500	.2850	.1863	.0012	-.0006	.0949	.0943	.2845	.3366	.0523	.2317	.0299	1.7471
10.3000	.2857	.1634	.0013	-.0006	.0950	.0944	.2853	.3349	.0492	.2292	.0286	1.7163
10.3500	.2862	.1458	.0013	-.0006	.0952	.0946	.2859	.3334	.0470	.2276	.0277	1.6957
10.4000	.2866	.1322	.0014	-.0006	.0953	.0947	.2864	.3322	.0455	.2266	.0271	1.6811
10.4500	.2869	.1201	.0014	-.0006	.0954	.0948	.2868	.3312	.0443	.2259	.0265	1.6691
10.5000	.2872	.1085	.0015	-.0006	.0955	.0950	.2872	.3303	.0431	.2252	.0260	1.6584
10.5500	.2875	.0981	.0015	-.0006	.0957	.0951	.2875	.3297	.0422	.2248	.0256	1.6496
10.6000	.2878	.0888	.0015	-.0006	.0958	.0952	.2877	.3292	.0414	.2244	.0252	1.6420
10.6646	.2881	.0785	.0015	-.0006	.0960	.0954	.2881	.3286	.0405	.2241	.0248	1.6342
10.7291	.2884	.0696	.0016	-.0006	.0962	.0956	.2883	.3282	.0398	.2240	.0245	1.6277
10.7937	.2886	.0621	.0016	-.0006	.0964	.0958	.2886	.3279	.0393	.2241	.0242	1.6225
10.8583	.2888	.0555	.0016	-.0006	.0966	.0960	.2888	.3276	.0388	.2242	.0240	1.6180
10.9228	.2889	.0500	.0016	-.0006	.0968	.0962	.2889	.3274	.0385	.2244	.0238	1.6144
10.9874	.2891	.0447	.0016	-.0006	.0970	.0964	.2891	.3272	.0381	.2246	.0237	1.6111
11.0519	.2892	.0407	.0016	-.0006	.0972	.0966	.2892	.3271	.0379	.2250	.0236	1.6085
11.1165	.2893	.0368	.0016	-.0006	.0974	.0968	.2893	.3270	.0377	.2253	.0235	1.6061
11.1811	.2894	.0335	.0017	-.0006	.0976	.0970	.2894	.3269	.0375	.2257	.0234	1.6040
11.2456	.2895	.0306	.0017	-.0006	.0978	.0972	.2895	.3269	.0374	.2262	.0233	1.6022
11.3102	.2896	.0277	.0017	-.0006	.0980	.0974	.2896	.3269	.0373	.2266	.0233	1.6005
11.3748	.2897	.0254	.0017	-.0006	.0982	.0976	.2896	.3268	.0372	.2271	.0233	1.5990
11.4393	.2897	.0232	.0017	-.0006	.0985	.0979	.2897	.3268	.0371	.2276	.0232	1.5977
11.5039	.2898	.0211	.0017	-.0006	.0987	.0981	.2898	.3268	.0370	.2281	.0232	1.5964
11.5684	.2898	.0191	.0017	-.0006	.0989	.0983	.2898	.3268	.0370	.2286	.0232	1.5952
11.6330	.2899	.0171	.0017	-.0006	.0991	.0985	.2899	.3268	.0369	.2290	.0232	1.5940

FOR ITERA= 16 8 ITERATIONS REQUIRED FOR CONVERGENCE IN MISNA2

(g) Page 7.

Figure 14.- Continued.

POTENTIAL FLOW SOLUTION

TEST CASE L/D=9 FOREBODY L/D=0.8 DB/D=0.51 CIRCULAR ARC NOZZLE NPR=5.03

OFF-BODY UNIFORM AXISYMMETRIC FLOW

	X/L	R/L	VX	VR	VT	ETA	ML	CP
1	8.800000	.600000	1.062181	-.009934	1.062227	-.535866	.856848	-.125713
2	9.000000	.600000	1.111166	-.035165	1.111723	-1.812641	.903119	-.227155
3	9.200000	.600000	1.119641	-.109287	1.124962	-5.574925	.915665	-.254448
4	9.400000	.600000	1.029521	-.147716	1.040064	-8.165084	.836438	-.080670
5	9.600000	.600000	.956023	-.118833	.963380	-7.085490	.767182	.072730
6	9.800000	.600000	.943930	-.082651	.947542	-5.004080	.753125	.103845
7	9.800000	.550000	.937734	-.089026	.941950	-5.423231	.748182	.114777
8	9.800000	.500000	.931133	-.095801	.936049	-5.874312	.742975	.126285
9	9.800000	.450000	.924368	-.102942	.930082	-6.354575	.737722	.137886
10	9.800000	.400000	.917520	-.110636	.924166	-6.875620	.732524	.149355

(h) Page 8.

Figure 14.- Concluded.

1 Report No NASA TM-78779	2 Government Accession No	3 Recipient's Catalog No	
4 Title and Subtitle DONBOL: A COMPUTER PROGRAM FOR PREDICTING AXISYMMETRIC NOZZLE AFTERBODY PRESSURE DISTRIBUTIONS AND DRAG AT SUBSONIC SPEEDS		5 Report Date May 1979	6 Performing Organization Code
		7 Author(s) Lawrence E. Putnam	8 Performing Organization Report No L-12658
9 Performing Organization Name and Address NASA Langley Research Center Hampton, VA 23665		10 Work Unit No 505-04-13-01	11 Contract or Grant No
		12 Sponsoring Agency Name and Address National Aeronautics and Space Administration Washington, DC 20546	
		13 Type of Report and Period Covered Technical Memorandum	14 Sponsoring Agency Code
15 Supplementary Notes			
16 Abstract <p>A Neumann solution for inviscid external flow has been coupled to a modified Reshotko-Tucker integral boundary-layer technique, the control volume method of Presz for calculating flow in the separated region, and an inviscid one-dimensional solution for the jet exhaust flow in order to predict axisymmetric nozzle afterbody pressure distributions and drag. The viscous and inviscid flows are solved iteratively until convergence is obtained. A computer algorithm of this procedure has been written and is called DONBOL. This paper provides a description of the computer program and a guide to its use. Comparisons of the predictions of this method with experiment show that the method accurately predicts the pressure distributions of boattail afterbodies which have the jet exhaust flow simulated by solid bodies. For nozzle configurations which have the jet exhaust simulated by high-pressure air, the present method significantly underpredicts the magnitude of nozzle pressure drag. This deficiency results because the method neglects the effects of jet plume entrainment. This method is limited to subsonic free-stream Mach numbers below that for which the flow over the body of revolution becomes sonic.</p>			
17 Key Words (Suggested by Author(s)) Nozzle drag Pressure drag Body of revolution Jet exhaust flow		18 Distribution Statement FEDD Distribution Subject Category 02	
19 Security Classif (of this report) Unclassified	20 Security Classif (of this page) Unclassified	21 No of Pages 97	22 Price

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