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FINAL REPORT

**DIGITAL ADAPTIVE
CONTROLLERS FOR
VTOL VEHICLES**

II. Software Documentation

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and S.G. Pratt**

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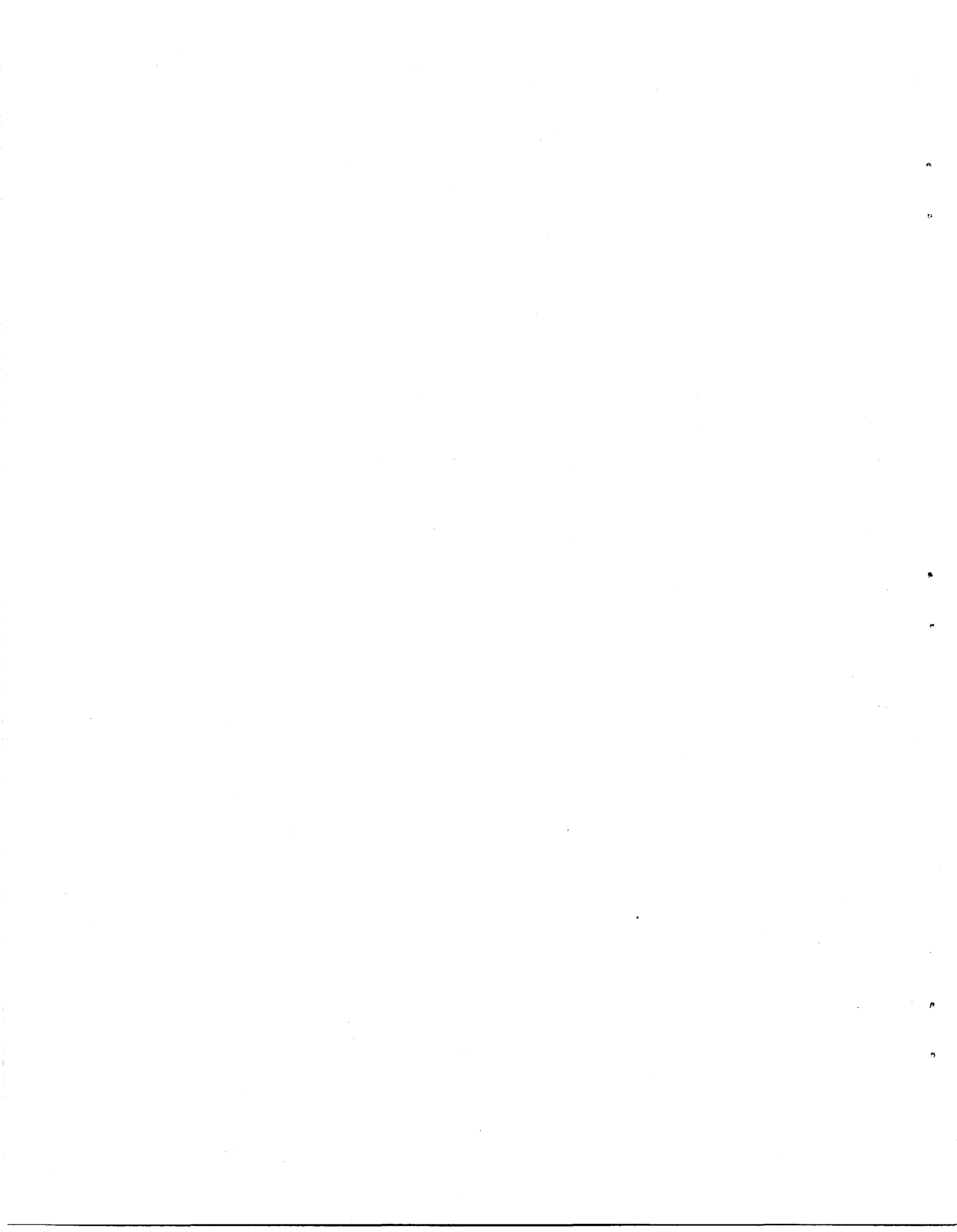
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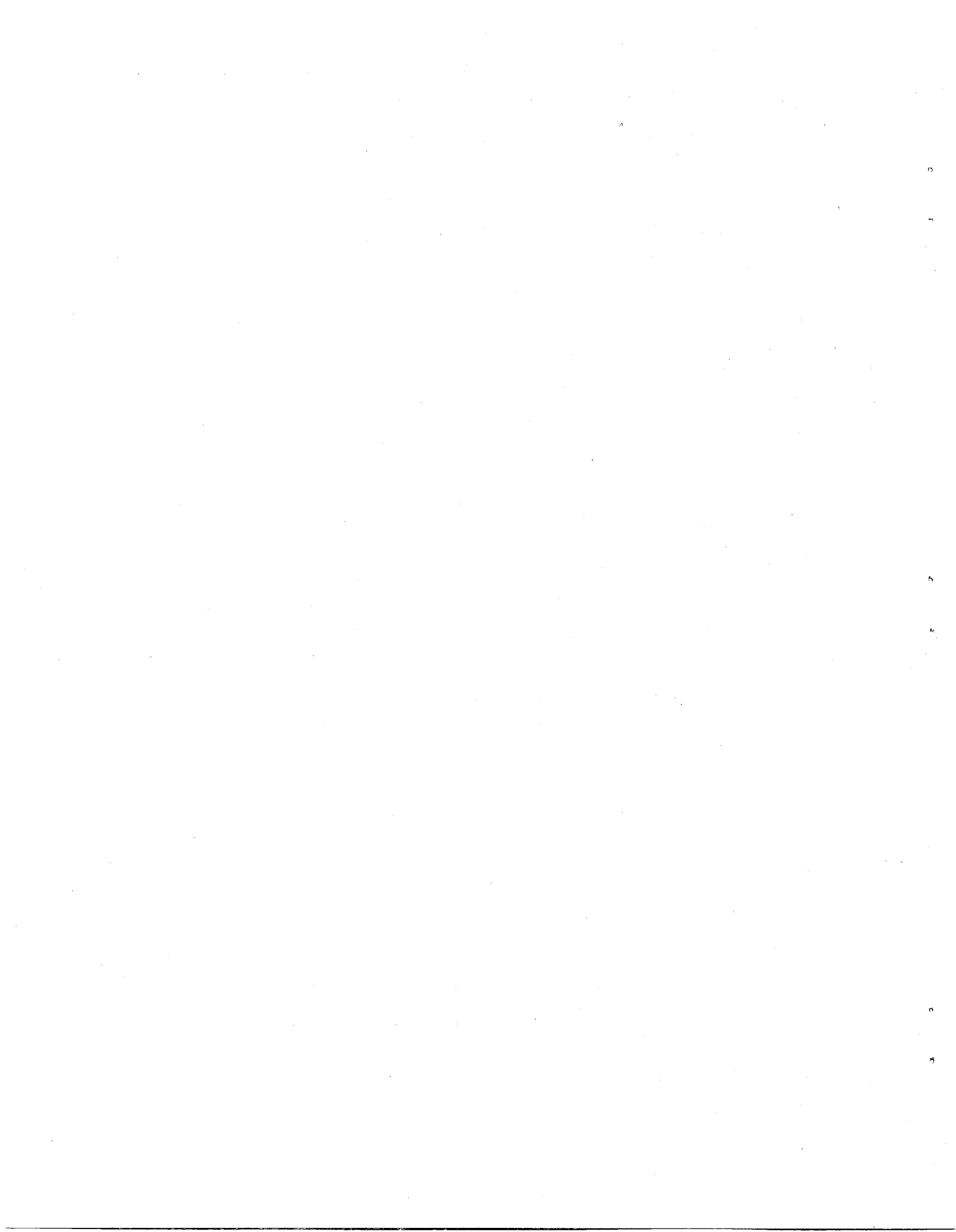
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16. Abstract <p>The VTOL Approach and Landing Technology (VALT) Program of the National Aeronautics and Space Administration is conducting research in navigation, guidance, control display, and flight management for future VTOL aircraft. As part of the research in advanced control technology, Honeywell designed a digital self-adaptive flight control system for flight test in the VALT research aircraft -- a tandem-rotor, medium-transport helicopter (a modified CH-47).</p> <p>The control laws accept commands from an automatic on-board guidance system. The primary objective of the control laws is to provide good command-following with a minimum cross-axis response. Three attitudes and vertical velocity are separately commanded. Adaptation of the control laws is based on information from rate and attitude gyros and a vertical velocity measurement. The final design resulted from a comparison of two different adaptive concepts -- one based on explicit parameter estimates from a real-time Maximum-Likelihood Estimation algorithm, the other based on an implicit Model Reference adaptive system. The two designs were compared on the basis of performance and complexity.</p>					
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DIGITAL ADAPTIVE CONTROLLERS
FOR VTOL VEHICLES--VOLUME II

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SECTION 1
INTRODUCTION

This volume documents the VALT adaptive software developed for NASA Langley Research Center under Contract NAS1-14921. Two self-adaptive algorithms were evaluated on NASA's VALT (VTOL Approach and Landing Technology) simulation. One is based on an implicit model reference design,¹ the other on an explicit parameter estimation technique.² The latter was recommended for flight test in the VALT research helicopter. The remainder of this volume presents the organization of the software, user options, and a nominal set of input data. This volume also contains a flow chart and program listing of each algorithm. For a discussion of the design theory of these algorithms, the reader is referred to Volume I.

¹ Referred to as the Model Reference (MR) algorithm.

² Referred to as the Maximum Likelihood Estimation (MLE) algorithm.

SECTION 2

OVERVIEW OF VALT ADAPTIVE SOFTWARE

The VALT adaptive software consists of separate longitudinal and lateral-directional controllers plus an adaptive gain adjustment algorithm for the longitudinal controller. The two controllers were designed to accept independent commands from a guidance algorithm. The guidance commands are the three attitudes plus vertical velocity. The primary objective of the control law is to provide good command-following with minimal cross-axis response. The control laws provides differential collective and collective servocommands for the longitudinal axis. Cyclic and differential cyclic commands are provided for lateral-directional control.

The Honeywell-supplied software consists of separate subroutines written in standard FORTRAN for the CDC computer facility at NASA LRC. All data required by the real-time subroutines are stored in labeled arrays. The subroutines are listed in Table 1 and the arrays (common blocks) in Table 2.

The interface between the adaptive control software and NASA's VALT simulation on the CDC CYBER computer is contained in subroutine CONTRL3. A flow chart of this subroutine is shown in Figure 1. The data interface between the NASA simulation and the Honeywell-supplied subroutines is the VARDAT array.

Two different adaptive algorithms were evaluated for the gain adjustment function. The dashed line in Figure 1 shows the call statement to the MR algorithm. The algorithm that was selected adjusts the gain based on explicit parameter estimates from a parallel-channel Maximum-Likelihood Estimator (PCMLE). Consequently, the dashed line path does not exist in the current CONTRL3 subroutine.

TABLE 1. - LIST OF SUBROUTINES

Subroutine	Function
CONTRL3	Real-time interface between VALT adaptive software and simulation on CDC CYBER computer.
HCON1	Pitch-axis control law.
HCON2	Lateral-directional control law.
GAIN1	Gain schedule for pitch axis.
GAIN2	Gain table for pitch axis.
PCMLE FH TSIG FILT SENS ACUM	} Real-time subroutines for MLE algorithm.
NRTIC MODEL DISC FHIC DIAK CAL MP INPT	} Initialization and filter design software for the MLE algorithm.
RFMOD INTEGRAL	Real-time MR algorithm.
RMIC	Initialization for MR algorithm.

TABLE 2. -COMMON BLOCKS USED BY VALT
ADAPTIVE SOFTWARE

Common Block	Function
CI	Stores four integrator values for control laws.
VARDAT	Contains UX and LX arrays. Used for all data transfer and mode logic.
DAT SENSP IPIC MEAS	} Data storage used by MLE algorithm.
SUBR	Data storage used by MLE initialization.
SUBRH	Stores frequency and damping constants for highpass filters.
UTEST	Stores test signal parameters.
DEVICE	Stores logical assignment of card reader and line printer.
MRINT MRDAT	} Data storage for MR algorithm.

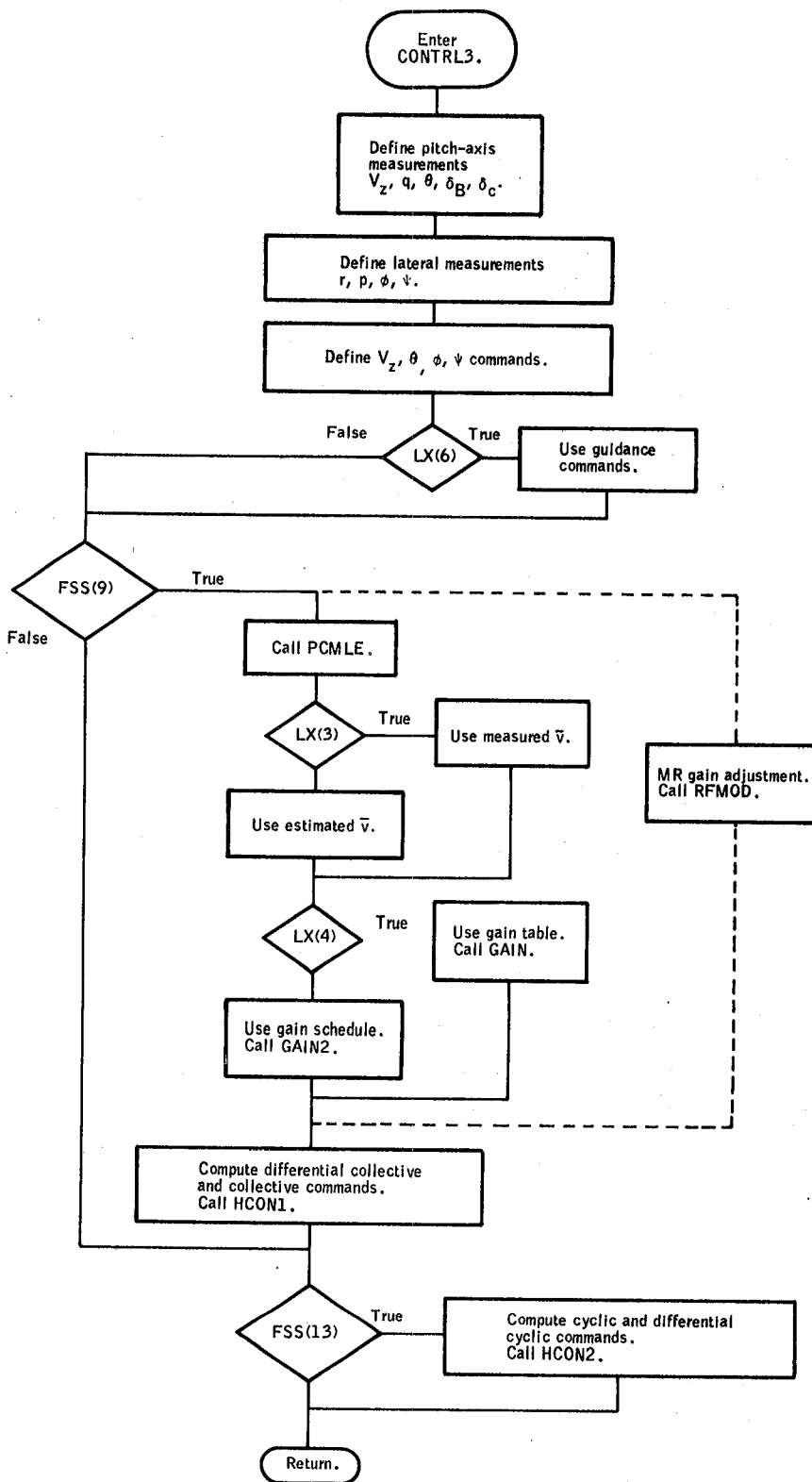


Figure 1. -Flow chart of subroutine CONTRL3.

SECTION 3 THE VALT ADAPTIVE CONTROL LAWS

Description

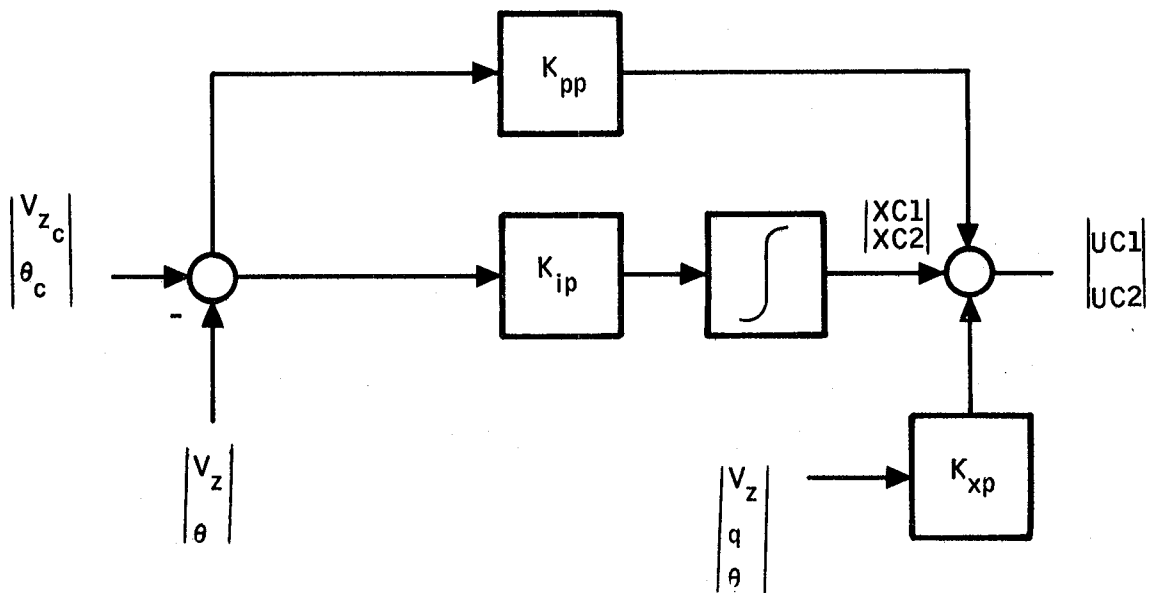
Separate longitudinal and lateral-directional controllers are implemented in subroutines HCON1 and HCON2. Each of the controllers forms servocommands from a combination of guidance commands and measured responses. Program listings are continued in Appendix A.

The longitudinal controller determines the differential collective command (UC1) and the collective command (UC2) from the θ and V_z measurements. Proportional plus integral shaping is applied to each command. The two command integrators are denoted XC1 and XC2 in the CI array.

The functional block diagram of the longitudinal controller is shown in Figure 2, which also shows the various gains stored in the UX array. The computation of these gain elements is discussed later. The variables used in HCON1 are defined in Table 3.

The lateral-directional controller determines the cyclic (UC3) and differential cyclic commands (UC4). The controller assumes guidance commands in the form of ϕ and ψ attitude commands. The controller uses proportional plus integral control for each command and uses measurements of p , r , ϕ , and ψ as feedback. The two command integrators are XC3 and XC4 in the CI array.

The functional block diagram of the lateral controller is shown in Figure 3, and the symbols are defined in Table 4.



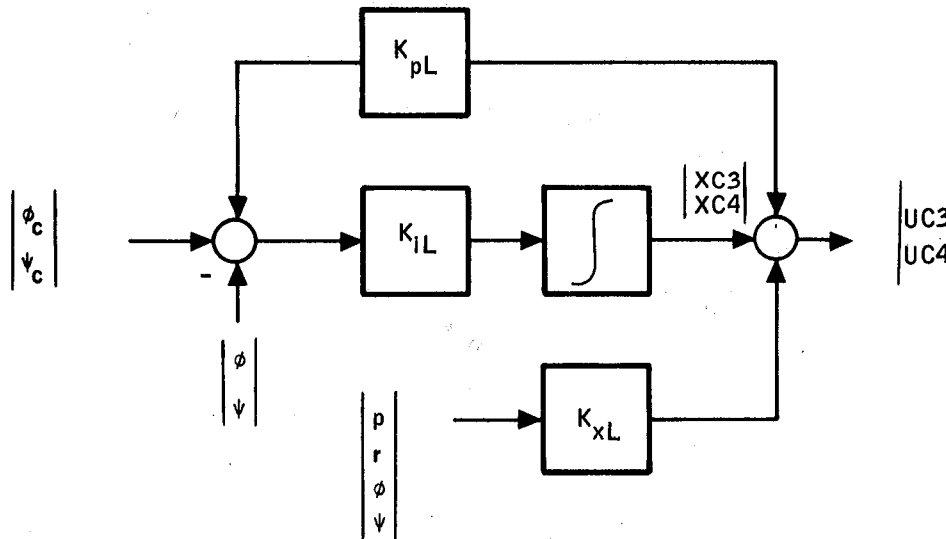
Gain matrix elements

$$\begin{aligned}
 K_{pp} &= \begin{bmatrix} UX(51) & 0.8UX(52) \\ UX(53) & 0.8UX(54) \end{bmatrix} \\
 K_{ip} &= \begin{bmatrix} UX(44) & 0.8UX(45) \\ UX(49) & 0.8UX(50) \end{bmatrix} \\
 K_{xp} &= \begin{bmatrix} UX(41) & UX(42) & UX(43) \\ UX(46) & UX(47) & UX(48) \end{bmatrix}
 \end{aligned}$$

Figure 2. - Functional block diagram for pitch-axis control.

TABLE 3. -HCON1 VARIABLES

Variable	Definition	
UX(1)	Total V_z command, ft/s	
2	Total θ command, rad	
11	V_z , measured vertical velocity, ft/s	
12	q , measured pitch rate, rad/s	
13	θ , measured pitch attitude, rad	
19	Δt , sample rate, sec	
41 • • • 50	} 10 gain values used by pitch-axis controller.	
XC1		Integral for differential collective command.
XC2		Integral for collective command.



Subscript c denotes commanded value.

UC3 = Cyclic command (in.)

UC4 = Differential cyclic command (in.)

Gain matrices K_{pL} , K_{iL} , K_{xL} are constant.

Figure 3. - Functional block diagram for lateral-directional control.

TABLE 4. -HCON2 VARIABLES

Variable	Definition
UX(3)	ϕ command, rad
4	ψ command, rad
19	DT, sample time, s
37	p, measured roll rate, rad/s
38	r, measured yaw rate, rad/s
39	ϕ , measured roll attitude, rad
40	ψ , measured yaw attitude, rad

Initialization

The four integrators in the CI array must be initialized using trim values to prevent transients when the controllers are engaged. The appropriate initial values for XC1, XC2, XC3, and XC4 are determined with the following relations from Figures 2 and 3:

$$\begin{bmatrix} v \\ z_t \\ \theta_t \end{bmatrix} \begin{bmatrix} K_{pp} \\ \\ \end{bmatrix} + \begin{bmatrix} XC1 \\ XC2 \end{bmatrix} + \begin{bmatrix} v \\ 0 \\ \theta_t \end{bmatrix} \begin{bmatrix} K_{xp} \\ \\ \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} \phi_t \\ \psi_t \end{bmatrix} \begin{bmatrix} K_{pl} \\ \\ \end{bmatrix} + \begin{bmatrix} XC3 \\ XC4 \end{bmatrix} + \begin{bmatrix} 0 \\ \phi_t \\ \psi_t \end{bmatrix} \begin{bmatrix} K_{xl} \\ \\ \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

where the subscript "t" denotes a trim value existing prior to engaging the control law and the rates are assumed zero.

The variable UX(19) must be initialized with the appropriate sample time. The remaining program initialization is specific to either the MR or the MLE adaptive algorithm and will be discussed in later sections.

Real-Time Operations

The VALT adaptive system is structured to require a call to subroutine CONTRL3 at each sample time. This subroutine controls all the signals sent to the various subroutines and contains all the logic for exercising the various user options discussed below. A program listing is given in Appendix A. The listing for the gain computation is given in Appendix B.

User Inputs and Options

The interface between the Honeywell adaptive software resides in subroutine CONTRL3. Data are exchanged via the UX array. Various options for using the software have been provided by a set of logical variables (LX) and five panel switches, FSS(9) through FSS(13), located on the CDC console. The various options are defined below:

- Panel Switches:

- 9 - Engages the pitch-axis controller and continually updates PCMLE highpass filters.
- 10 - Positive command.
- 11 - Negative command.
- 12 - Engages the PCMLE estimator [requires FSS(9) to be on].
- 13 - Engages the lateral controller.

- LX Array:

- 1 - T fixes the PCMLE algorithm on the channel determined by starting value of JS.
 - F uses likelihood select logic to determine channel used.
- 2 - T sets NOEST logic which skips parameter updates in PCMLE.
 - F nominal operation.
- 3 - T replaces measured \bar{v} with \bar{v} estimate from PCMLE for gain schedule.
- 4 - T uses table lookup in GAIN subroutine.
 - F uses schedule in GAIN2 subroutine.
- 5 - T = PRINT prints out selected PCMLE variables. This can only be used in a batch mode.

- LX:

- 6 - T selects commands from automatic guidance.
- 7 - Not used.
- 8 - Controls printout in NRTIC subroutine.
- 9 - T engages the estimation computation set by switch 12.
- 10 - T causes pitch controller to use a fixed set of gains from subroutine GAIN2.
- 11 - T applies step command via FSS(10) and FSS(11) to V_z input.
- 12 - T applies step command via FSS(10) and FSS(11) to θ input.

- 13 - T applies step command via FSS(10) and FSS(11) to ϕ input.
- 14 - T applies step command via FSS(10) and FSS(11) to ψ input.

As previously discussed, the logic to select the MR algorithm was deleted following selection of the MLE algorithm for flight evaluation. For completeness, the MR algorithm is documented in a later section of this report.

Outputs From VALT Adaptive Software

The primary outputs from the software are the four servocommands (UC1, UC2, UC3, UC4) previously discussed. For purposes of checkout, eight variables are output on a strip chart for real-time plots. Other selected variables are available in the UX array for monitoring from the CDC console.

The variables plotted are variables from the MLE algorithm and are defined in Section 4 (Table 12).

SECTION 4
THE PARALLEL CHANNEL MAXIMUM LIKELIHOOD
ESTIMATION ALGORITHM

Description

This algorithm uses measurements of vertical velocity, pitch rate, and pitch attitude together with the collective and differential collective positions to estimate the dominant parameters of the VALT helicopter. The estimation is based on a maximum-likelihood method using parallel processing of the data by Kalman filters. Each filter is a four-state representation of the longitudinal dynamics.

The explicit parameter estimates are used to algebraically adjust the feedback and feedforward gains of the pitch-axis control law.

The estimation software is organized as shown in Figure 4. It consists of a non-real-time segment (definition and initialization of Kalman filter channels) and the real-time parameter identification. The initialization program permits different designs by providing the following flexibility:

- Variable number and location of Kalman filter channels
- Variable sample rates
- Variable number of identified parameters (up to four)
- Significance tests to monitor data validity

The computations have been divided among a number of subroutines. The subroutines are listed in Table 5 together with their use in either initialization or real time. For fast execution, most of the data exchanged between subroutines is done via labeled common blocks. Seven blocks are used in the estimation software. They are defined in Table 6.

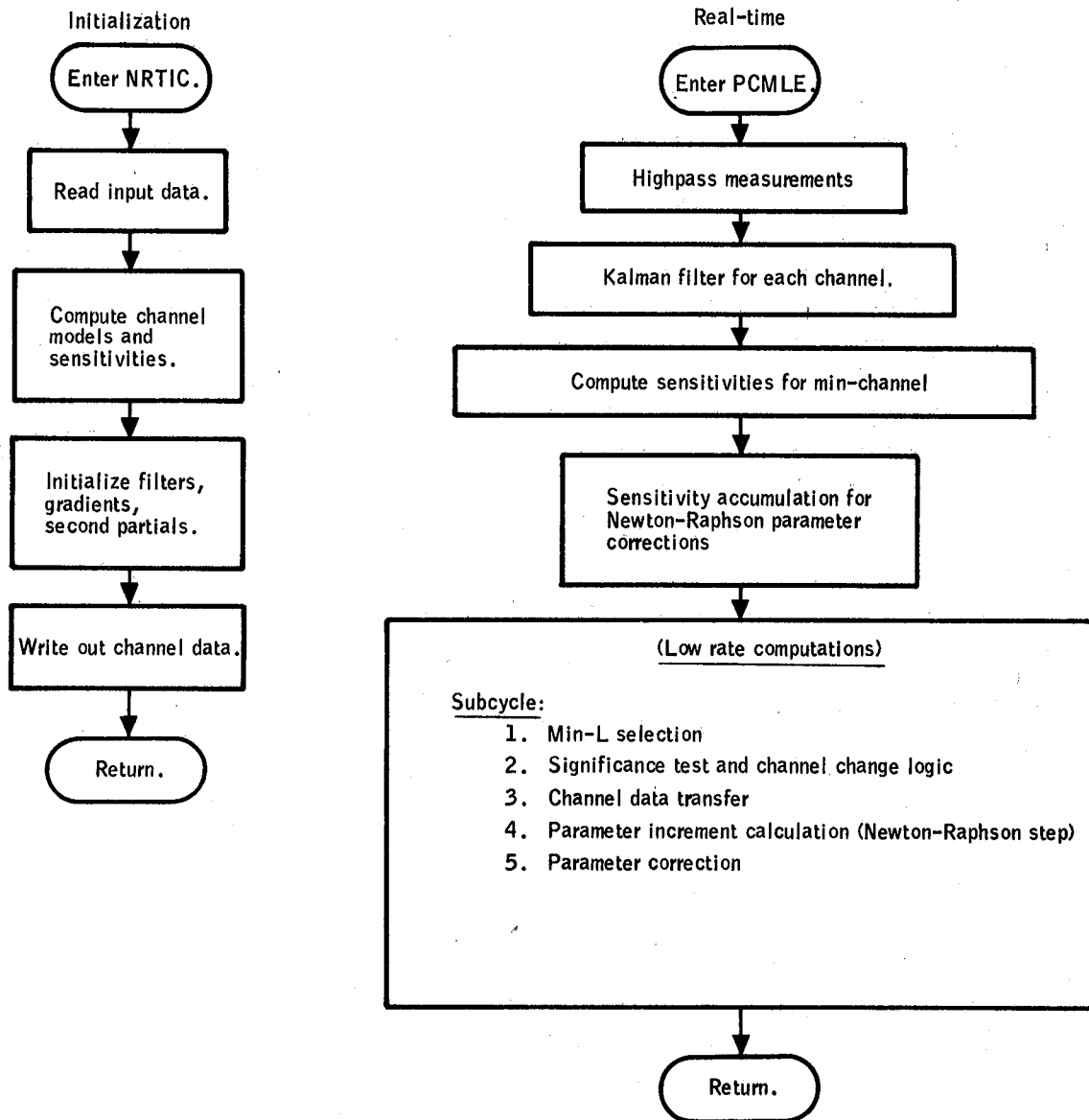


Figure 4. -PCMLE software structure.

TABLE 5. - PCMLE SUBROUTINES

Subroutine	Function
Non-real-time:	
NRTIC	Main executive routine for non-real-time operation. Reads data to define number and location of channels, number of parameters estimated, sample rate, etc. Performs all initialization with calls to other subroutines.
MODEL	Defines the system matrices and sensitivities for a discrete four-state model for each channel.
DISC	Computes discrete model from a continuous-time model.
FHIC	Computes filter coefficients and initializes high-pass filter applied to measurements.
DIAK CAL	Solves for the Kalman filter gains for a discrete system. It uses an iterative procedure.
INPT	Reads card input for starting value of filter gains.
MP	Prints out matrix.
Real-time:	
PCMLE	Main executive routine for parallel-channel MLE real-time computations.
FH	Highpass filter applied to measurements.
TSIG	Produces test signal and two random numbers for simulated sensor noise.
FILT	Performs a fourth-order Kalman filter computation for each pitch channel.
SENS	Performs a sensitivity filter for a given parameter.
ACUM	Accumulates likelihood gradients and approximate second partials for a Newton-Raphson parameter update.

TABLE 6. - LABELED COMMON BLOCKS FOR DATA TRANSFER

Common block	Function
VARDAT	Contains UX and LX arrays. Used to input user data and output selected real-time parameters. Defined in Tables 8 and 9.
DAT	Main arrays for storing channel model parameters. Defined in MODEL and used in NRTIC, PCMLE, SENS, ACUM, and FILT subroutines. The X, F, and D arrays of this common block are defined in Tables 3, 4, and 5.
IPIC	Contains all the parameter initialization defined by NRTIC and transferred to the real-time routine PCMLE.
MEAS	Stored current value of high-passed measurements. Initialized in NRTIC, defined in PCMLE and used in FILT, and SENS subroutines.
SUBR	Transmits model data to DIAK and CAL for solving a Ricatti equation to determine Kalman filter gains. Used in NRTIC, PCMLE, MODEL, DIAK, and CAL subroutines.
SUBRH	Stores highpass filter constants. Used in NRTIC, PCMLE, MODEL, FHIC, and FH subroutines.
SENSP	Stores the sensitivity of each channel model variable with respect to each of the four parameters estimated. See Table 10 for details. Used by NRTIC, PCMLE, MODEL, SENS, and ACUM subroutines.

Definitions of the arrays used in the MLE software are given in Tables 7, 8, 9, and 10.

Initialization

The initialization of PCMLE is performed out of real time with a call to subroutine NRTIC. This subroutine reads a data file containing all the common blocks used by the PCMLE software. This data file is generated by a separate batch program which is discussed later in this section.

TABLE 7. -DEFINITION OF X-ARRAY IN DAT COMMON BLOCK

X (IC, I)

IC = 1, 5 for channel index

I = 1, 19 for variable

Index (I)	Variable
1	V_{x_k}
2	V_{z_k}
3	q_k
4	θ_k
5	$V_{x_{k+1}}$
6	$V_{z_{k+1}}$
7	q_{k+1}
8	θ_{k+1}
9	v_{v_z}
10	v_q
11	v_θ
12	$v^t R^{-1} v$
13	$v^t R^{-1} v + \text{Indet } R$
14	$\text{sum } v^t R^{-1}$
15	$\text{sum } v^t R^{-1} v + \text{Indet } R$
16	---
17	---
18	---
19	---

TABLE 8. -DEFINITION OF F-ARRAY IN DAT COMMON BLOCK

F (IC, I)

IC = 1, 5 filter (channel) index

I = 1, 22 for parameter index

Index (I)	Variable
1	KF(1, 1)
2	KF(2, 1)
3	KF(3, 1)
4	KF(4, 1)
5	KF(1, 2)
6	KF(2, 2)
7	KF(3, 2)
8	KF(4, 2)
9	KF(1, 3)
10	KF(2, 3)
11	KF(3, 3)
12	KF(4, 3)
13	Ln Det R
14	$R^{-1}(1, 1)$
15	$R^{-1}(1, 2)$
16	$R^{-1}(1, 3)$
17	$R^{-1}(2, 1)$
18	$R^{-1}(2, 2)$
19	$R^{-1}(2, 3)$
20	$R^{-1}(3, 1)$
21	$R^{-1}(3, 2)$
22	$R^{-1}(3, 3)$

Kalman filter gains

Inverse of residual co-
variance matrix

TABLE 9. -DEFINITION OF D-ARRAY IN DAT COMMON BLOCK

D (IC, I)

IC = 1, 5 for channel index

I = 1, 22 for parameter

For the model:

$$x_{n+1} = Ax_n + Bu_n$$

Index (I)	Variable
1	A (1, 1)
2	A (1, 2)
3	A (1, 3)
4	A (1, 4)
5	A (2, 1)
6	A (2, 2)
7	A (2, 3)
8	A (2, 4)
9	A (3, 1)
10	A (3, 2)
11	A (3, 3)
12	A (3, 4)
13	A (4, 1)
14	A (4, 2)
15	A (4, 3)
16	A (4, 4)
17	B (1, 1)
18	B (1, 2)
19	B (2, 1)
20	B (2, 2)
21	B (3, 1)
22	B (3, 2)

Non-zero elements of discrete A matrix

Non-zero elements of discrete B matrix

TABLE 10. DEFINITION OF XS AND DS ARRAY IN SENSP
COMMON BLOCK

Array	Definition
XS	(IP, I) IP = 1, 4 parameter index I = 1, 19 variable index for sensitivity filter quantities Same list for I as Table 3.
DS	(IC, IP, I) IC = 1, 5 for channel index IP = 1, 4 for parameter index I = 1, 22 for sensitivity quantities In general $DS(IC, IP, I) = \frac{\Delta D(IC, I)}{\Delta \text{parameter } IP}$ where I is as given in Table 5.

Real-Time Operation

The real-time computations are executed with a call to subroutine PCMLE. PCMLE is called once per sample time. The sampled values of pitch rate, pitch attitude, down velocity, and collective and differential collective position are highpassed, and residuals and likelihood functions are computed for each Kalman filter (fixed in parameter space). Gradients and second partials are accumulated for a Newton-Raphson parameter update. The remaining real-time operations are spread over five subcycles as shown in Figure 4. During real-time operation, selected variables can be monitored using the UX array.

The real-time data that are input to the algorithm at each sample time are defined in Table 11. The data are transferred from the VALT simulation via the UX array.

TABLE 11. -REAL-TIME INPUT VARIABLE ASSIGNMENT

User variables	Description	Mnemonic expression	Units
UX(11)	Down velocity	ZDOTE	ft/s
12	Pitch rate	QI	rad/s
13	Pitch attitude	THEI	rad
14	Differential collective	DC(1)	in.
15	Collective	DC(2)	in.
16	Forward velocity ^a	XDOTE	ft/s

^aNot used by controller. Used for evaluation only.

Selected output variables are available for monitoring performance. They are contained in the UX array and are defined in Table 12.

A flow chart of the real-time computations is contained in Appendix C. A complete program listing appears in Appendix D.

User Inputs and Options

Five logical variables (LX) are used in the software as switches to control various PCMLE user options. These variables are defined in Table 13. The nominal settings are LX(9) = True, all others false.

The other modes are used for checkout and debugging purposes. LX(1) = T eliminates the channel switching logic so the fit of any of the Kalman filters can be checked against the input data. LX(2) = T skips the parameter estimation steps. LX(5) and LX(8) control line printer output. LX(9) is the logical used to engage the PCMLE algorithm for normal operation.

TABLE 12. -PCMLE OUTPUT VARIABLES

User variable	Description	Mnemonic expression	Units
UX(20)	Channel indicator	0.25JS-.5	
21	V_z estimate (highpassed)	X(JS, 2)/20	20 ft/s
22	q estimate (highpassed)	X(JS, 3)*5.73	10°/s
23	Scaled-likelihood function, filter 1	TJ(1)/400	
24	Scaled-likelihood function, filter 2	TJ(2)/400	
25	Scaled-likelihood function, filter 3	TJ(3)/400	
26	\bar{v} estimate	ZP1	-
27	\bar{v} accuracy	SQRT(C1/DET)	-
28	b_{31} estimate	ZP2	
29	b_{32} estimate	ZP3	
30	a_{33} estimate	ZP4	
31	V_x estimate	X(JS, 1)	ft/s
32	θ estimate	X(JS, 4)	rad
33	Residual ratio	S1GSQ	-

TABLE 13. -USER LOGICAL ASSIGNMENTS^a

User logicals	Function	Mnemonic expression
LX(1)	Disables automatic channel changes.	NOCHC
2	Disables Newton-Raphson parameter step.	NOEST
5	Enables printout from PCMLE (use in batch mode only).	PRINT
8	Disables initialization printout in subroutine model.	
9	Enables PCMLE algorithm.	MLE

^aDefault values: LX(I) = .F.

Generation of PCMLE Data File

The parameters used by the real-time PCMLE software are computed off-line and stored in a data file. This program reads the input data deck and defines the specified number of channels at the specified parameter values. Each channel is a four-state Kalman filter for the longitudinal dynamics. The states are forward and down velocity, pitch rate, and the pitch attitude. The measurements are down velocity, pitch rate, and pitch attitude. The initialization program discretizes the Kalman filter model for the specified sample rate and solves a Ricatti equation for the steady-state filter gains. Parameter sensitivities are computed for each channel using a numerical differencing method by individually perturbing each of four parameters to be estimated.

A flow chart of this program is contained in Appendix E. A complete program listing is contained in Appendix F.

The various input parameters are defined in Table 14. A nominal set of input data and the resulting initialization file is contained in Appendix G.

If a stable Kalman filter is not found for the given set of input data, a STOP 41 or STOP 31 will be encountered. These are defined in Table 15.

TABLE 14. - PCMLE INPUT PARAMETERS

Input	Description
NX	Number of states in Kalman filters
NR	Number of measurements in Kalman filters
NN	Number of noise sources in Kalman filters
NTER	Number of terms used in series to compute discrete model
NRM	Maximum number of measurements
EE	Convergence criteria in DIAK for Ricatti solution
ITER	Maximum number of iterations in DIAK for Ricatti solution
DT0	Nominal sample time (automatically increased if samples skipped)
DT PRINT	Print interval when LX(5) is true (available in batch mode only)
NC	Number of channels
NP0	Number of parameters estimated
JS0	Starting channel location
WUT0	Natural frequency of shaping filter on random test signal:
DUT0	- Damping of shaping filter on random test signal
SIGUT0	- Gain of shaping filter on random test signal
UT10	- Initial state of shaping filter on random test signal
UT20	- Initial state of shaping filter on random test signal
	(Above state initialization is useful for generating deterministic square waves or sine waves with TSIG subroutine.)
UTMAX	Limits size of filtered test signal
TAUP0	Time constant of likelihood accumulation filter
TAUP2	Time constant of lowpass filter on L, ∇L , $\nabla^2 L$ inputs
WHP	Frequency of second-order highpass on measurements
DHP	Damping of second-order highpass on measurements
SIGVZ	RMS noise statistic assumed for down-velocity measurement
SIGQ	RMS noise statistic assumed for pitch-rate measurement
SIGTH	RMS noise statistic assumed for pitch-attitude measurement
SIGXG	RMS statistic assumed for forward wind gusts

TABLE 14. -Concluded

Input	Description
SIGZG	RMS statistic assumed for vertical wind gusts
RTJC0	} Threshold parameters controlling channel switch
THRTJC0	
RTJZ0	} Threshold parameters controlling Z1MIN selection
THRTJZ0	
RTJS0	Ratio test parameter for significance of likelihood function
ZP1 MAX	Maximum value of parameter 1 estimate
ZP2 MAX	Maximum value of parameter 2 estimate
ZP3 MAX	Maximum value of parameter 3 estimate
ZP4 MAX	Maximum value of parameter 4 estimate
ZP1 MIN	Minimum value of parameter 1 estimate
ZP2 MIN	Minimum value of parameter 2 estimate
ZP3 MIN	Minimum value of parameter 3 estimate
ZP4 MIN	Minimum value of parameter 4 estimate
GSQL0	Elements of $\sqrt{2}L_0$ matrix
ZP	Matrix defining location of channels (four parameters per channel times five channels maximum = 20 parameters)

TABLE 15. -PCMLE STOP CODES

STOP code	Condition
41	Initialization
31	
	Ricatti equation not converging in subroutine CAL during initialization (unstable model).
	Inverse does not exist in subroutine DIAK for computing filter gains. Check Data Deck.

SECTION 5
THE MODEL REFERENCE ADAPTIVE ALGORITHM

Description

The model reference algorithm adjusts the pitch-axis gains to reduce the error vector between the model response for V_z , q and θ . The resulting gain values are stored in the UX array for use with subroutine HCON1. All the data required by this algorithm are stored in the MRDAT common block.

Initialization

This algorithm is initialized with a call to subroutine RMIC. This call defines the A and B matrices for a three-state continuous-time model and the parameters required by the integration subroutine INTEGRAL which are stored in common block MRINT. The INTEGRAL subroutine contains three integration routines. The first-order Euler method is used to integrate the thirteenth-order system composed of three model states plus 10 gains. The parameters used in the MRDAT array are defined in Table 16.

The X-array stores the current state. The components are:

X(1) = V_z model

X(2) = q model

X(3) = θ model

X(4)
through } 10 gain values
X(13)

TABLE 16. -DEFINITION OF MODEL REFERENCE VARIABLES

Variable	Definition
X	Current state
DX	Current derivative
THR1	Threshold on V_z error in gain adjustment
THR2	Threshold on q error in gain adjustment
THR3	Threshold on θ error in gain adjustment
G11	} Elements of B^{-1} in gain adjustment
G12	
G21	
G22	
T1	Scaling parameter for the P-matrix
T2 - T11	Set to 1 or 0 depending on which of the gains are to be adjusted
EVZ	V_z error (ft/s)
EQ	q error (rad/s)
ETH	θ error (rad)
FAC	} Error quantities used for monitoring only
FAC1	
P11	} Elements of negative definite matrix satisfying Liapunov equation
P22	
P23	
P33	

The DX-array stores the current derivative. The equation for the third-order model is:

$$\frac{d}{dt} \begin{bmatrix} V_z \\ q \\ \theta \end{bmatrix} = [A] \begin{bmatrix} V_z \\ q \\ \theta \end{bmatrix} + [B] \begin{bmatrix} U(1) \\ U(2) \end{bmatrix}$$

where

$$U(1) = V_z \text{ command}$$

$$U(2) = \theta \text{ command}$$

$$A = \begin{bmatrix} -2 & 0 & 0 \\ 0 & -4 & -7 \\ 0 & 1 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 2 & 0 \\ 0 & 7 \\ 0 & 0 \end{bmatrix}$$

When the controller is added to this model, the closed-loop model has uncoupled V_z and θ responses with the following transfer functions:

$$\frac{V_z}{V_{z_c}} = \frac{2(s+1)}{(s+2)(s+1)}$$

$$\frac{\theta}{\theta_c} = \frac{7(s+0.8)}{(s+0.8)(s^2+4s+7)}$$

The gains consist of a feedback matrix, K_x , plus a command input, K_u . Thus, the commands are determined as:

$$\begin{bmatrix} UC1 \\ UC2 \end{bmatrix} = \begin{bmatrix} K_x \end{bmatrix} \begin{bmatrix} V_z \\ q \\ \theta \end{bmatrix} + \begin{bmatrix} K_u \end{bmatrix} \begin{bmatrix} V_c + \int (V_{z_c} - V_z) \\ \theta_c + \int (\theta_c - \theta) \end{bmatrix}$$

These matrices are initialized as:

$$K_x = \begin{bmatrix} 0 & -7.6 & -27 \\ 0.3 & 0 & 0 \end{bmatrix}$$

$$K_u = \begin{bmatrix} 0 & 17.5 \\ -0.23 & 0 \end{bmatrix}$$

Real-Time Operation

The gain adjustment is done with a call to subroutine RFMOD. This routine defines the command inputs, measurements, error vector, and time derivatives for the gains. The actual integration of the model and the gain element is done with subroutine INTGRAL. The integration is performed for the sample-time defined for the controller.

The derivatives of the gain matrices are defined by the following relations:

$$\frac{d}{dt} K_x = -\bar{B}^{-1} P e^T x$$

$$\frac{d}{dt} K_u = -\bar{B}^{-1} P e^T u$$

where

e = error vector of V_z , q , θ errors

x = measured V_z , q , θ states

A flow chart of RFMOD is shown in Figure 5. A program listing of RMIC, RFMOD, and INTGRAL is contained in Appendix H.

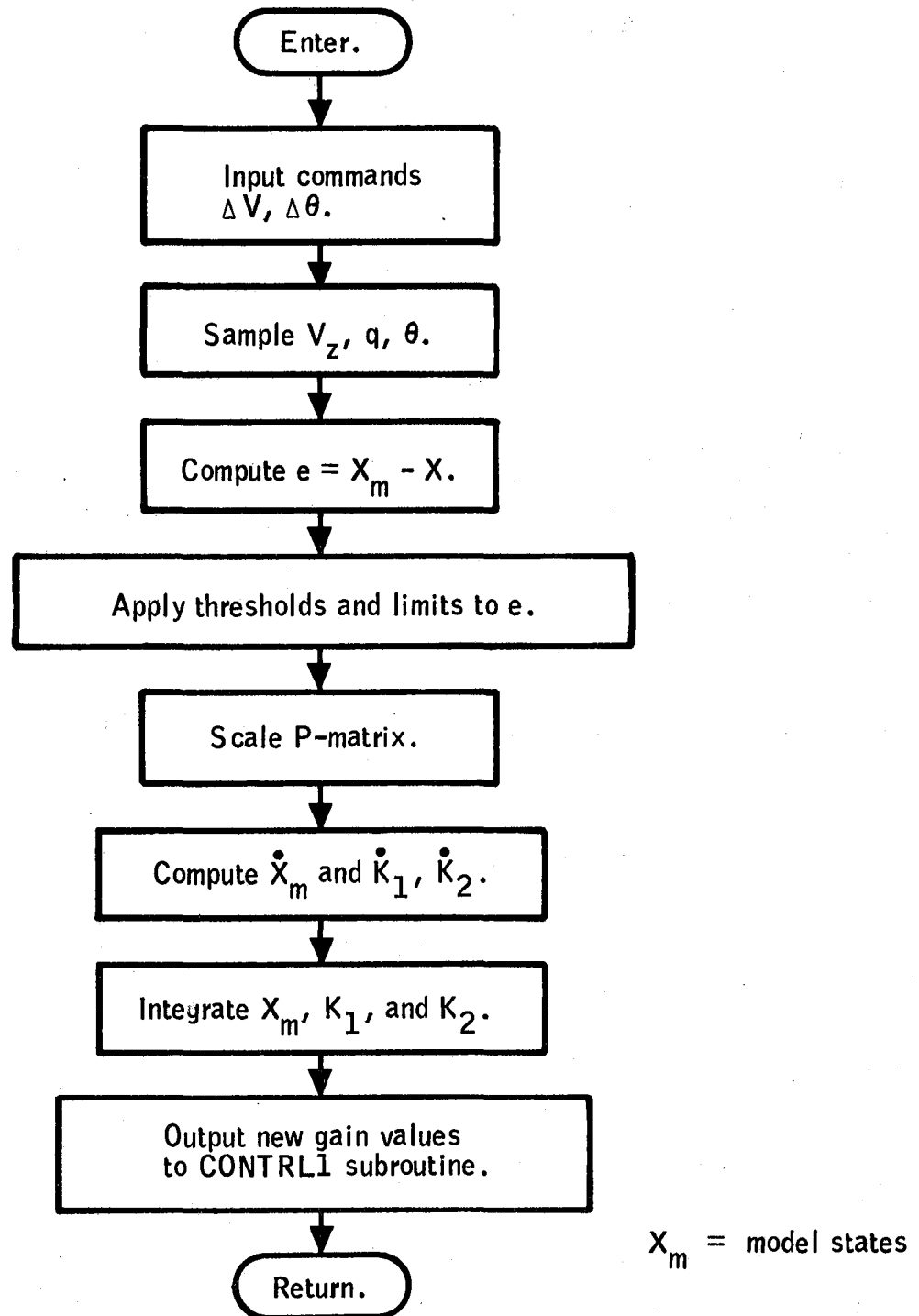


Figure 5. - Flow chart for subroutine REMOD.

APPENDIX A
PROGRAM LISTING OF CONTROLLERS

This appendix consists of the program listings of subroutines CONTRL3 (Fig. 6), HCON1 (Fig. 7), and HON2 (Fig. 8).

```

SUBROUTINE CONTRL3      73/74   OPT=1                FTN 4.6+452      78/04/06. 08.36.47

1          SUBROUTINE CONTRL3                                RTVALT      4035
C
C          THIS SUBROUTINE COMPUTES CONTROLLER COMMANDS. ALL VARIABLES          HON09      259
C          ENDING WITH I ARE INERTIAL MEASUREMENTS. THOSE ENDING WITH          HON09      260
C          G ARE FROM THE GUIDANCE COUPLER. THEN AND PHIN ARE FROM STABDER.    HON09      261
5          UNITS OF DCC ARE IN INCHES. CT IS THE ITERATION PERIOD FOR THE     HON09      262
C          CONTROL MODULE. ALL PAST VALUES ARE INITIALIZED IN ICONTR.        HON09      263
C
C          COMMON/EST/LATE, LONE, ZE, XDOTE, YDOTE, ZDOTE, SSVELWE, SSTHWE, XDTADE,
10          A YDTADE, ZDTADE, XE, YE                                HON09      266
C          COMMON/AR/DAH( 4), DLH( 4), DA1H( 4), DL1H( 4), DA2H( 4), DL2H( 4),  HON09      267
1          DRLH( 4), DRL1H( 4), DCMIN(4), DCMAX(4), ORLMAX(4), WAH(4),        HON09      268
2          ZAH(4), WRH(4), ZRH( 4), CON1(6, 4), CON2(6, 4), DTRL, FAR,        HON09      269
3          DHH( 4), DH1H( 4), DH2H( 4), VAR2( 4), VAR12( 4), VAR22( 4),      HON09      270
15          DC(4), DCN(4), GAINH(4)                                         HON09      271
C          COMMON/CONST/NC, G, RE, RE2, PP, SCHULER, ERATE, PP180, PP180I, PP2  HON09      272
C          COMMON/CONTROL/DCC(4), DC1C2, W1G, DPL(4), PSIIYC, PSIIYG          HON09      273
C          COMMON/FREQ/RGT, ALT, RIGT, ADT, GST, GCT, GPT, GRT, CT, PT, HRT, AAT, ENV1,  HON09      274
1          ENV2, ENV3, ENV4, ENV5, ENV6, ENV7, ENV8, ENV9, XLNT, ANAT,        HON09      275
20          FKT, ATCT, PTCT, GNDMT, GSLT, DT, TIMEH                        HON09      276
C          COMMON/GUIDE/UG, VG, WG, XDOTG, YDOTG, ZDOTG, UAG, VAG, WAG, ZRG, PSIIHRG  HON09      277
C          COMMON/HELCOF/THEH, PHIH, PSIH, DUODTH, VDOOTH, DWODTH, UH, VH, WH, PDOOTH,  HON09      278
1          QDOOTH, RDOOTH, PH, QH, RH, PSIIHR, ALPHAH, BETAH, FXH, FYH,        HON09      279
2          2FZH, PPH, QQH, RRR, XDTAVH                                       HON09      280
25          COMMON/INERT/THEI, PHII, PSII, UDOTI, VDOTI, WDOTI, PI, QI, RI, PDI, QDI,  HON09      281
1          RDI, SIGBRII, SIGRRII, SIGFRII, SIGBRI, SIGRRI, SIGSFRI,          HON09      282
2          SIGBLAI, SIGRLAI, RRII(3), RRI(3), RLAI(3), BRII(3),            HON09      283
3          SFRII(3), BRI(3), SFRI(3), BLAI(3)                                HON09      284
C          COMMON/NOM/THEN, PHIN, UN, VN, WN, UAN, VAN, WAN                HON09      285
30          COMMON/SPRNT/DUNOUT(15), IDUM                                    HON09      286
C          COMMON/TRAJECT/XDDGSN, XDDAGSN, XDOTGSN, XDTAGSN, ZDDGSN, ZDOTGSN,    HON09      287
A          ZDTIGSN, ZGSN, XDTNGSN, VNGSN, YDTEGSN, VEGSN, LATGSN,          HON09      288
B          LONGSN, XGSN, YGSN, PGSN, QGSN, RGSN, R1GSN, THEGSN,            HON09      289
C          PHIGSN, PSIGSN, PSIIHRN, TGSN, XDDGSC, XDDAGSC, XDOTGSC,          HON09      290
35          D          XDTAGSC, ZDDGSC, ZDJTGSC, ZGSC, ZDTLGSC, LATGSC, LONGSC,  HON09      291
E          XGSC, YGSC, PGSC, QGSC, RGSC, THEGSC, PHIGSC, PSIGSC,          HON09      292
F          PSIIHR, TEMGSC, TIMGSC, TIMAGSC, TIMBGSC, TIMCGSC, TGSC,        HON09      293
G          FIGSC, GAINGSC, PMAX, PHIMAX, ZDTMAX, XDDMAX, YDOTGSC, YDOTGSN    HON09      294
C          COMMON/VARDAT/UX(55), LX(15)                                     HON09      295
40          COMMON/VEL/UAD, VAD, WAD, ZBAD, XDOTGS, YDOTGS, ZDOTGS, PSIIHR, ZAA, HTER,  HON09      296
1          ZAAC, ZAAG, ALPHAD, BAD                                           HON09      297
C          COMMON/WIND/NW, HW(4), THW(4), VELW(4), QTHCW, QVELCW, QZCW, THTW, VELTW,  HON09      298
1          ZTW, SIGVRW, SIGZRW, SSTHW, WVELRW, WZRW, XTHW, THCW, XVELW, SSVELW,  HON09      299
2          VELCW, ZCW, SIGTHCW, SIGVCW, SIGZCW, SIGW, THC1W, VELC1W,        HON09      300
45          3          VELDTW, WTHCW, WTHC1W, WVELCW, WVELC1W, WZCW, WZC1W, ZC1W,  HON09      301
4          UW, VW, WW                                                       HON09      302
C          COMMON/REALTIM/VARCHNG, INTABLS, IVARBUF(5), ITYPE, FSS(16)      HON09      303
C          LOGICAL FSS, LX                                                  HON09      304
C          DIMENSION OUT(4), GN(2, 10)                                       HON09      305
50          DCC(1)=-7.5013*QI-10.*(THEI-THEN)-0.16116*UG                    HON09      306
          DCC(2)=0.99872*DC1C2-0.37068*WG+0.31519*W1G                      HON09      307
          DC1C2=DCC(2)                                                       HON09      308
          W1G=WG                                                               HON09      309
C          LATERAL CHANNELS                                                 HON09      310
55          C          ROLL (CYCLIC)                                          HON09      311
          DCC(3)=7.5*(PGSC-PI)+15.*(PHIGSC+PHIN-PHII)+0.23*VG              HON09      312
          YAW (DIFFERENTIAL CYCLIC)                                          HON09      313
          YAW (DIFFERENTIAL CYCLIC)                                          HON09      314
          YAW (DIFFERENTIAL CYCLIC)                                          HON09      315
          YAW (DIFFERENTIAL CYCLIC)                                          HON09      316

```

Figure 6. -Program listing of subroutine CONTRL3.

Appendix A

60	C		H0N09	317
		PSIYG=PSIYG	H0N09	318
		PSIYG=PSIGSC-PSII	H0N09	319
		IF(PSIYG.GT.PP) PSIYG=PSIYG-PP2	H0N09	320
		IF(PSIYG.LT.-PP) PSIYG=PSIYG+PP2	H0N09	321
65		PSIYC=PSIYC+1.4*CT*(PSIYG+PSIYG)	H0N09	322
		DCC(4)=15.*(RGSC-RI)+17.*PSIYG+PSIYC	H0N09	323
		DPL(1)=DCN(1)	H0N09	324
		DPL(2)=DCN(2)	H0N09	325
70		DPL(3)=DCN(3)	H0N09	326
		DPL(4)=DCN(4)	H0N09	327
	C		H0N09	328
	C*****	HONEYWELL ADAPTIVE CONTROL LAWS	H0N09	329
	C	PITCH AXIS SENSOR INPUTS	H0N09	330
	C		H0N09	331
75		UX(16)=SQRT(XDDOTE*XDDOTE+YDDOTE*YDDOTE)	H0N09	332
		UX(11)=ZDDOTE	H0N09	333
		UX(12)=QI	H0N09	334
		UX(13)=THEI	H0N09	335
		UX(14)=DC(1)	H0N09	336
80		UX(15)=DC(2)	H0N09	337
		UX(19)=CT	H0N09	338
		VBAR=UX(16)/270.	H0N09	339
		UX(10)=VBAR	H0N09	340
	C		H0N09	341
85	C*****	LATERAL SENSOR INPUTS	H0N09	342
	C		H0N09	343
		UX(37)=PI	H0N09	344
		UX(38)=RI	H0N09	345
		UX(39)=PHII	H0N09	346
90		UX(40)=PSII	H0N09	347
	C		H0N09	348
	C*****	COMMAND INPUTS	H0N09	349
	C		H0N09	350
		CALL TSIG(C1,C2,UTS)	H0N09	351
95		VZC=0.+UX(6)*UTS	H0N09	352
		THC=THEN+UX(7)*UTS	H0N09	353
		PHIC=0.	H0N09	354
		PSIC=0.	H0N09	355
	C		H0N09	356
100	C*****	COMMAND DOUBLET	H0N09	357
	C		H0N09	358
		SDB=0.	H0N09	359
		IF(FSS(10)) SDB=UX(17)	H0N09	360
105		IF(FSS(11)) SDB=-UX(17)	H0N09	361
	C		H0N09	362
	C*****	LOGIC TO APPLY STEP COMMANDS AS PERTURBATIONS	H0N09	363
	C	(CONVERTED TO RAD. FOR ATTITUDE COMMANDS)	H0N09	364
	C		H0N09	365
		IF(LX(11)) VZC=SDB	H0N09	366
110		IF(LX(12)) THC=THEN+SDB*0.01745	H0N09	367
		IF(LX(13)) PHIC=SDB*0.01745	H0N09	368
		IF(LX(14)) PSIC=SDB*0.01745	H0N09	369
		UX(1)=VZC	H0N09	370
		UX(2)=THC	H0N09	371
115		UX(3)=PHIC	H0N09	372
		UX(4)=PSIC	H0N09	373
	C		H0N09	374
	C*****	LOGIC TO APPLY GUIDANCE	H0N09	375
	C		H0N09	376
120		IF(.NOT.LX(6)) GO TO 400	H0N09	377
	C		H0N09	378
	C*****	COMMANDS VZ,THETA,PHI,PSI GO TO UX 1,2,3,4	H0N09	379
	C		H0N09	380
		UX(1)=ZDDTGSC	H0N09	381
125		UX(2)=THEGSC	H0N09	382
		UX(3)=PHIGSC	H0N09	383
		UX(4)=PSIGSC	H0N09	384
	400	CONTINUE	H0N09	385
	C		H0N09	386
130		IF(.NOT.FSS(9)) GO TO 500	H0N09	387
		LX(9)=FSS(12)	H0N09	388
		CALL PCMLE	H0N09	389
	C		H0N09	390
		IF(LX(3)) VBAR=UX(26)	H0N09	391
135		CALL GAIN2(VBAR)	H0N09	392
		IF(LX(4)) CALL GAIN(VBAR)	H0N09	393
	C		H0N09	394
	C*****	PITCH CONTROLLER	H0N09	395
	C		H0N09	396

Figure 6. -Continued.

Appendix A

140	CALL HCON1(DCC(1),DCC(2))	HON09	397
	DCC(1)=DCC(1)*(UX(8)+1.)	HON09	398
	DCC(2)=DCC(2)*(UX(9)+1.)	HON09	399
	500 CONTINUE	HON09	400
	C***** LATERAL*****	HON09	401
145	IF(FSS(13)) CALL HCON2(DCC(3),DCC(4))	HON09	402
	C	HON09	403
	RETURN	RTVALT	4036
	END	RTVALT	4037

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
1 CONTRL3

VARIABLES	SN	TYPE	RELOCATION					
13	AAT	REAL	FREQ	3	ADT	REAL	FREQ	
14	ALPHAD	REAL	VEL	20	ALPHAH	REAL	HELCOF	
1	ALT	REAL	FREQ	26	ANAT	REAL	FREQ	
30	ATCT	REAL	FREQ	15	BAD	REAL	VEL	
21	BETAH	REAL	HELCOF	51	BLAI	REAL	ARRAY	INERT
43	BRI	REAL	ARRAY	35	BRII	REAL	ARRAY	INERT
74	CON1	REAL	ARRAY	124	CON2	REAL	ARRAY	AR
10	CT	REAL	FREQ	243	C1	REAL		
244	C2	REAL		0	DAH	REAL	ARRAY	AR
10	DA1H	REAL	ARRAY	20	DA2H	REAL	ARRAY	AR
206	UC	REAL	ARRAY	0	DCC	REAL	ARRAY	CONTROL
44	DCMAX	REAL	ARRAY	40	DCMIN	REAL	ARRAY	AR
212	DCN	REAL	ARRAY	4	DC1C2	REAL		CONTRJL
156	DHH	REAL	ARRAY	162	DH1H	REAL	ARRAY	AR
166	DH2H	REAL	ARRAY	4	DLH	REAL	ARRAY	AR
14	DL1H	REAL	ARRAY	24	DL2H	REAL	ARRAY	AR
6	DPL	REAL	ARRAY	30	DRLH	REAL	ARRAY	AR
50	DRLMAX	REAL	ARRAY	34	DRL1H	REAL	ARRAY	AR
34	DT	REAL	FREQ	154	DTRL	REAL		AR
3	DUODTH	REAL	HELCOF	0	DUMOUT	REAL	ARRAY	SPRNT
5	DWODTH	REAL	HELCOF	14	ENV1	REAL		FREQ
15	ENV2	REAL	FREQ	16	ENV3	REAL		FREQ
17	ENV4	REAL	FREQ	20	ENV5	REAL		FREQ
21	ENV6	REAL	FREQ	22	ENV7	REAL		FREQ
23	ENV8	REAL	FREQ	24	ENV9	REAL		FREQ
6	ERATE	REAL	CONST	155	FAR	REAL		AR
62	FIGSC	REAL	TRAJECT	27	FKT	REAL		FREQ
10	FSS	LOGICAL	ARRAY	22	FXH	REAL		HELCOF
23	FYH	REAL	HELCOF	24	FZH	REAL		HELCOF
1	G	REAL	CONST	63	GAINGSC	REAL		TRAJECT
216	GAINH	REAL	ARRAY	5	GCT	REAL		FREQ
257	GN	REAL	*UNDEF	32	GNOHT	REAL		FREQ
6	GPT	REAL	FREQ	7	GRT	REAL		FREQ
33	GSLT	REAL	FREQ	4	GST	REAL		FREQ
12	HRT	REAL	FREQ	11	HTER	REAL		VEL
1	HW	REAL	ARRAY	17	IDUM	INTEGER		SPRNT
1	INTABLS	INTEGER	REALTIM	7	ITYPE	INTEGER		REALTIM
2	IVARBUF	INTEGER	ARRAY	0	LATE	INTEGER		EST
41	LATGSC	INTEGER	TRAJECT	14	LATGSN	INTEGER		TRAJECT
1	LONE	INTEGER	EST	42	LONGSC	INTEGER		TRAJECT
15	LONGSN	INTEGER	TRAJECT	67	LX	LOGICAL	ARRAY	VARDAT
0	NC	INTEGER	CONST	0	NW	INTEGER		WIND
253	OUT	REAL	*UNDEF	11	PD1	REAL		INERT
11	PDOTH	REAL	HELCOF	45	PGSC	REAL		TRAJECT
20	PGSN	REAL	TRAJECT	14	PH	REAL		HELCOF
250	PHIC	REAL		51	PHIGSC	REAL		TRAJECT
25	PHIGSN	REAL	TRAJECT	1	PHIH	REAL		HELCOF
1	PHII	REAL	INERT	65	PHIMAX	REAL		TRAJECT
1	PHIN	REAL	NOM	6	PI	REAL		INERT
64	PMAX	REAL	TRAJECT	4	PP	REAL		CONST
25	PPH	REAL	HELCOF	7	PP180	REAL		CONST
10	PP1801	REAL	CONST	11	PP2	REAL		CONST
251	PSIC	REAL		52	PSIGSC	REAL		TRAJECT
26	PSIGSN	REAL	TRAJECT	2	PSIH	REAL		HELCOF
7	PSIHR	REAL	VEL	53	PSIHRC	REAL		TRAJECT
12	PSIHRG	REAL	GUIDE	27	PSIHRN	REAL		TRAJECT
2	PSII	REAL	INERT	17	PSIIHR	REAL		HELCOF
12	PSIYC	REAL	CONTROL	13	PSIYG	REAL		CONTROL
241	PSIY1G	REAL		11	PT	REAL		FREQ
31	PTCT	REAL	FREQ	12	QDI	REAL		INERT

Figure 6. -Continued.

Appendix A

12	QDOTH	REAL		HELCOPI	46	QGSC	REAL		TRAJECT
21	QGSN	REAL		TRAJECT	15	QH	REAL		HELCOPI
7	QI	REAL		INERT	26	QQH	REAL		HELCOPI
15	QTHCW	REAL		WIND	16	QVELCW	REAL		WIND
17	QZCW	REAL		WIND	13	RDI	REAL		INERT
13	RDOOTH	REAL		HELCOPI	2	RE	REAL		CONST
3	RE2	REAL		CJNST	47	RGSC	REAL		TRAJECT
22	RGSN	REAL		TRAJECT	0	RGT	REAL		FREQ
16	RH	REAL		HELCOPI	10	RI	REAL		INERT
2	RIGT	REAL		FREQ	32	RLAI	REAL	ARRAY	INERT
27	RRH	REAL		HELCOPI	27	RRI	REAL	ARRAY	INERT
24	RRII	REAL	ARRAY	INERT	23	RIGSN	REAL		TRAJECT
5	SCHULER	REAL		CONST	252	SDB	REAL		
46	SFRI	REAL	ARRAY	INERT	40	SFRII	REAL	ARRAY	INERT
22	SIGBLAI	REAL		INERT	17	SIGBRI	REAL		INERT
14	SIGBRII	REAL		INERT	16	SIGFRII	REAL		INERT
23	SIGRLAI	REAL		INERT	20	SIGRRI	REAL		INERT
15	SIGRRII	REAL		INERT	21	SIGSFRI	REAL		INERT
36	SIGTHCW	REAL		WIND	37	SIGVCW	REAL		WIND
23	SIGVRW	REAL		WIND	41	SIGW	REAL		WIND
40	SIGZCW	REAL		WIND	24	SIGZRW	REAL		WIND
25	SSTHW	REAL		WIND	7	SSTHWE	REAL		EST
33	SSVELW	REAL		WIND	6	SSVELWE	REAL		EST
54	TEMGSC	REAL		TRAJECT	61	TGSC	REAL		TRAJECT
30	TGSN	REAL		TRAJECT	247	THC	REAL		
31	THCW	REAL		WIND	42	THC1W	REAL		WIND
50	THEGSC	REAL		TRAJECT	24	THEGSN	REAL		TRAJECT
0	THEH	REAL		HELCOPI	0	THEI	REAL		INERT
0	THEN	REAL		NOM	20	THTW	REAL		WIND
5	THW	REAL	ARRAY	WIND	56	TIMAGSC	REAL		TRAJECT
57	TIMBGSC	REAL		TRAJECT	60	TIMCGSC	REAL		TRAJECT
35	TIMEH	REAL		FREQ	55	TIMGSC	REAL		TRAJECT
0	UAD	REAL		VEL	6	UAG	REAL		GUIDE
5	UAN	REAL		NJM	3	UDOTI	REAL		INERT
0	UG	REAL		GUIDE	6	UH	REAL		HELCOPI
2	UN	REAL		NOM	245	UTS	REAL		
54	UW	REAL		WIND	0	UX	REAL	ARRAY	VARDAT
1	VAD	REAL		VEL	7	VAG	REAL		GUIDE
6	VAN	REAL		NOM	0	VARCHNG	REAL		REALTIM
176	VAR12	REAL	ARRAY	AR	172	VAR2	REAL	ARRAY	AR
202	VAR22	REAL	ARRAY	AR	242	VBAR	REAL		
4	VDOOTH	REAL		HELCOPI	4	VDOTI	REAL		INERT
13	VEGSN	REAL		TRAJECT	34	VELCW	REAL		WIND
43	VELC1W	REAL		WIND	44	VELDTH	REAL		WIND
21	VELTW	REAL		WIND	11	VELW	REAL	ARRAY	WIND
1	VG	REAL		GUIDE	7	VH	REAL		HELCOPI
3	VN	REAL		NOM	11	VNGSN	REAL		TRAJECT
55	VW	REAL		WIND	246	VZC	REAL		
2	WAD	REAL		VEL	10	WAG	REAL		GUIDE
54	WAH	REAL	ARRAY	AR	7	WAN	REAL		NOM
5	WDOTI	REAL		INERT	2	WG	REAL		GUIDE
10	WH	REAL	ARRAY	HELCOPI	4	WN	REAL		NOM
64	WRH	REAL		AR	45	WTHCW	REAL		WIND
46	WTHC1W	REAL		WIND	47	WVELCW	REAL		WIND
50	WVELC1W	REAL		WIND	26	WVELRW	REAL		WIND
56	WW	REAL		WIND	51	WZCW	REAL		WIND
52	WZC1W	REAL		WIND	27	WZRW	REAL		WIND
5	WIG	REAL		CONTROL	32	XDDAGSC	REAL		TRAJECT
1	XDDAGSN	REAL		TRAJECT	31	XDDGSC	REAL		TRAJECT
0	XDDGSN	REAL		TRAJECT	67	XDDMAX	REAL		TRAJECT
3	XDOTI	REAL		EST	3	XDOTG	REAL		GUIDE
4	XDOTGS	REAL		VEL	33	XDOTGSC	REAL		TRAJECT
2	XDOTGSN	REAL		TRAJECT	10	XDTADE	REAL		EST
34	XDTAGSC	REAL		TRAJECT	3	XDTAGSN	REAL		TRAJECT
30	XDTAVH	REAL		HELCOPI	10	XDTNGSN	REAL		TRAJECT
13	XE	REAL		EST	43	XGSC	REAL		TRAJECT
16	XGSN	REAL		TRAJECT	25	XLNT	REAL		FREQ
30	XTHW	REAL		WIND	32	XVELW	REAL		WIND
4	YDOTI	REAL		EST	4	YDOTG	REAL		GUIDE
5	YDOTGS	REAL		VEL	70	YDOTGSC	REAL		TRAJECT
71	YDOTGSN	REAL		TRAJECT	11	YDTADE	REAL		EST
12	YOTEGSN	REAL		TRAJECT	14	YE	REAL		EST
44	YGSC	REAL		TRAJECT	17	YGSN	REAL		TRAJECT
10	ZAA	REAL		VEL	12	ZAAC	REAL		VEL
13	ZAAG	REAL		VEL	60	ZAH	REAL	ARRAY	AR
3	ZBAU	REAL		VEL	11	ZBG	REAL		GUIDE
35	ZCW	REAL		WIND	53	ZC1W	REAL		WIND
35	ZDDGSC	REAL		TRAJECT	4	ZDDGSN	REAL		TRAJECT
5	ZDOTE	REAL		EST	5	ZDOTG	REAL		GUIDE
6	ZDOTGS	REAL		VEL	36	ZDOTGSC	REAL		TRAJECT

Figure 6. -Continued.

Appendix A

5	ZDOTGSN	REAL		TRAJECT	12	ZDTADE	REAL		EST
40	ZDTLGSC	REAL		TRAJECT	66	ZDTMAX	REAL		TRAJECT
6	ZDT1GSN	REAL		TRAJECT	2	ZE	REAL		EST
37	ZGSC	REAL		TRAJECT	7	ZGSN	REAL		TRAJECT
70	ZRH	REAL	ARRAY	AR	22	ZTW	REAL		WIND
EXTERNALS		TYPE	ARGS						
	GAIN		1			GAIN2			1
	HCON1		2			HCOM2			2
	PCMLE		0			SORT	REAL		1 LIBRARY
	TSIG		3						
STATEMENT LABELS									
155	400			200	500				
COMMON	BLOCKS	LENGTH							
	EST	13							
	AR	146							
	CONST	10							
	CONTROL	12							
	FREQ	30							
	GUIDE	11							
	HELCOF	25							
	INERT	44							
	NDM	8							
	SPRNT	16							
	TRAJECT	58							
	VARDAT	70							
	VEL	14							
	WIND	47							
	REALTIM	24							
STATISTICS									
	PROGRAM LENGTH		3038	195					
	CM LABELED COMMON LENGTH		10208	528					
	730008 CM USED								

Figure 6. -Concluded.

Appendix A

```

SUBROUTINE HCON1      73/74   OPT=1                FTN 4.6+452      78/04/06. 08.36.47

1          SUBROUTINE HCON1(UC1,UC2)                HDN09      740
          C                                          HDN09      741
          COMMON/CI/ XC1,XC2                        HDN09      742
          COMMON/VARDAT/ UX(55),LX(15)             HDN09      743
5          LOGICAL LX                               HDN09      744
          VZ=UX(11)                                 HDN09      745
          Q=UX(12)                                  HDN09      746
          TH=UX(13)                                 HDN09      747
          VZC=UX(1)                                 HDN09      748
10         THC=UX(2)                                HDN09      749
          DT=UX(19)                                 HDN09      750
          C                                          HDN09      751
          PITCH CONTROL                            HDN09      752
          UC1=XC1 + UX(51)*VZC + UX(52)*0.8*THC   HDN09      753
          UC2=XC2 + UX(53)*VZC + UX(54)*0.8*THC   HDN09      754
15         UC1=JC1 + UX(41)*VZ + UX(42)*Q + UX(43)*TH HDN09      755
          UC2=UC2 + UX(46)*VZ + UX(47)*Q + UX(48)*TH HDN09      756
          DXC1=UX(44)*(VZC-VZ) + UX(45)*0.8*(THC-TH) HDN09      757
          DXC2=LX(49)*(VZC-VZ) + UX(50)*0.8*(THC-TH) HDN09      758
20         C                                          HDN09      759
          XC1= XC1 + DXC1*DT                        HDN09      760
          XC2= XC2 + DXC2*DT                        HDN09      761
          RETURN                                    HDN09      762
          END                                        HDN09      762
    
```

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
3 HCON1

VARIABLES	SN	TYPE	RELLOCATION				
62 DT		REAL		63 DXC1	REAL		
64 DXC2		REAL		67 LX	LOGICAL	ARRAY	VARDAT
56 Q		REAL		57 TH	REAL		
61 THC		REAL		0 UC1	REAL		F.P.
0 UC2		REAL	F.P.	0 UX	REAL	ARRAY	VARDAT
55 VZ		REAL		60 VZC	REAL		
0 XC1		REAL	CI	1 XC2	REAL		CI

```

SUBROUTINE HCON1      73/74   OPT=1                FTN 4.6+452      78/04/06. 08.36.47

COMMON BLOCKS   LENGTH
CI               2
VARDAT          70

STATISTICS
PROGRAM LENGTH      658      53
CM LABELED COMMON LENGTH 1108  72
730008 CM USED
    
```

Figure 7. -Program listing of subroutine HCON1.

Appendix A

```

SUBROUTINE HCON2      73/74  OPT=1      FTN 4,6+452      78/04/06, 08,36,47

1      C      SUBROUTINE HCON2(UC3,UC4)
      C      COMMON/CONST/NC,G,RE,RE2,PP,SCHULER,ERATE,PP180,PP180I,PP2
5      C      COMMON/CI/XC1,XC2,XC3,XC4
      C      COMMON/VARDAT/UX(55),LX(15)
      C      LOGICAL LX
10     C      PHIC=UX(3)
      C      PSIC=UX(4)
      C      P=UX(37)
      C      R=UX(38)
      C      PHI=UX(39)
      C      PSI=UX(40)
15     C      DT=UX(19)
      C      DUM=PSIC-PSI
      C      IF (ABS(DUM).LT.PP) GO TO 100
      C      IF (DUM.GT.PP.AND.PSI.LT.0.) XC3=XC3-7.*PP2
20     C      IF (DUM.GT.PP.AND.PSI.LT.0.) XC4=XC4-50.*PP2
      C      IF (DUM.GT.PP.AND.PSIC.GT.0.) XC3=XC3-4.5*0.8*PP2
      C      IF (DUM.GT.PP.AND.PSIC.GT.0.) XC4=XC4-34.38*0.8*PP2
      C      IF (DUM.LT.-PP.AND.PSI.GT.0.) XC3=XC3+7.*PP2
      C      IF (DUM.LT.-PP.AND.PSI.GT.0.) XC4=XC4+50.*PP2
25     C      IF (DUM.LT.-PP.AND.PSIC.LT.0.) XC3=XC3+4.5*0.8*PP2
      C      IF (DUM.LT.-PP.AND.PSIC.LT.0.) XC4=XC4+34.38*0.8*PP2
      C      IF (DUM.GT.PP) DUM=DUM-PP2
      C      IF (DUM.LT.-PP) DUM=DUM+PP2
30     C      100 CONTINUE
      C      UC3=XC3+15.94*0.8*PHIC+4.5*0.8*PSIC
      C      UC4=XC4+3.31*0.8*PHIC+34.38*0.8*PSIC
      C      UC3=UC3-9.*P-3.*R-23.5*PHI-7.*PSI
      C      UC4=UC4+2.375*P-24.*R+4.9*PHI-50.*PSI
35     C      S1=(PHIC-PHI)*.8
      C      S2=DUM*.8
      C      XC3=XC3+(15.94*S1+4.5*S2)*DT
      C      XC4=XC4+(3.31*S1+34.38*S2)*DT
40     C      RETURN
      C      END
      C      HDN09      764
      C      HDN09      765
      C      HDN09      766
      C      HDN09      767
      C      HDN09      768
      C      HDN09      769
      C      HDN09      770
      C      HDN09      771
      C      HDN09      772
      C      HDN09      773
      C      HDN09      774
      C      HDN09      775
      C      HDN09      776
      C      HDN09      777
      C      HDN09      778
      C      HDN09      779
      C      HDN09      780
      C      HDN09      781
      C      HDN09      782
      C      HDN09      783
      C      HDN09      784
      C      HDN09      785
      C      HDN09      786
      C      HDN09      787
      C      HDN09      788
      C      HDN09      789
      C      HDN09      790
      C      HDN09      791
      C      HDN09      792
      C      HDN09      793
      C      HDN09      794
      C      HDN09      795
      C      HDN09      796
      C      HDN09      797
      C      HDN09      798
      C      HDN09      799
      C      HDN09      800
      C      HDN09      801
      C      HDN09      802
      C      HDN09      803
      C      HDN09      804
      C      HDN09      805

```

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
3 HCON2

VARIABLES	SN	TYPE	RELOCATION					
203 DT		REAL		204 DUM	REAL			
6 ERATE		REAL	CONST	1 G	REAL		CONST	
67 LX		LOGICAL	ARRAY VARDAT	0 NC	INTEGER		CONST	
177 P		REAL		201 PHI	REAL			
175 PHIC		REAL		4 PP	REAL		CONST	
7 PP180		REAL	CONST	10 PP180I	REAL		CONST	
11 PP2		REAL	CONST	202 PSI	REAL			
176 PSIC		REAL		200 R	REAL			
2 RE		REAL	CONST	3 RE2	REAL		CONST	
5 SCHULER		REAL	CONST	205 S1	REAL			
206 S2		REAL		0 UC3	REAL		F.P.	
0 UC4		REAL	F.P.	0 UX	REAL	ARRAY	VARDAT	
0 XC1		REAL	CI	1 XC2	REAL		CI	
2 XC3		REAL	CI	3 XC4	REAL		CI	

INLINE FUNCTIONS TYPE ARGS
ABS REAL 1 INTRIN

STATEMENT LABELS
111 100

COMMON BLOCKS	LENGTH
CONST	10
CI	4
VARDAT	70

STATISTICS	PROGRAM LENGTH	2078	135
CM LABELED COMMON LENGTH	1248		84
730008 CM USED			

Figure 8. -Program listing of subroutine HCON2,

APPENDIX B
PROGRAM LISTING OF EXPLICIT-GAIN COMPUTATION

This appendix consists of the program listings of subroutine GAIN (Fig. 9) and GAIN2 (Fig. 10).

```

SUBROUTINE GAIN      73/74   OPT=1                FTN 4.6+452      78/04/06. 06.36.47

1          /SUBROUTINE GAIN(2)
           COMMON/GTAB/GN(14,13)
           COMMON/VARDAT/UX(55),LX(15)
           LOGICAL LX
5          C
           C***** TABLE LOOK-UP FOR PITCH AXIS GAIN
           C      UX(27)=ACCURACY
           C
           C      IS=3
           IF(UX(27).LT.0.6) IS=1
           IF(UX(27).LT.0.3) IS=2
           IF(.NOT.LX(3)) IS=2
           VB=4.*Z+2.5
           IVB=VB
15         IF(IVB.LT.1) IVB=1
           IF(IVB.GT.6) IVB=6
           I=IVB*6*(IS-1)+1
           IF(IS.EQ.3) I=1
           IF(LX(10)) I=1
20         UX(41)=GN(1,I)
           UX(42)=GN(2,I)
           UX(43)=GN(3,I)
           UX(44)=GN(4,I)
           UX(45)=GN(5,I)
25         UX(51)=GN(6,I)
           UX(52)=GN(7,I)
           UX(46)=GN(8,I)
           UX(47)=GN(9,I)
           UX(48)=GN(10,I)
30         UX(49)=GN(11,I)
           UX(50)=GN(12,I)
           UX(53)=GN(13,I)
           UX(54)=GN(14,I)
           RETURN
35        END

```

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
3 GAIN

VARIABLES	SN	TYPE	RELLOCATION						
0 GN		REAL	ARRAY	GTAB	74	I	INTEGER		
71 IS		INTEGER			73	IVB	INTEGER		
67 LX		LOGICAL	ARRAY	VARDAT	0	UX	REAL	ARRAY	VARDAT
72 VB		REAL			0	Z	REAL		F.P.

COMMON BLOCKS	LENGTH
GTAB	182
VARDAT	70

STATISTICS			
PROGRAM LENGTH	798	61	
CM LABELED COMMON LENGTH	3748	292	
730008 CM USED			

Figure 9. -Program listing of subroutine GAIN1.

Appendix B

```

SUBROUTINE GAIN2      73/74   OPT=1          PTN 4.6+452      78/04/06. 08.36.47

1          SUBROUTINE GAIN2(Z1)
           COMMON/VARDAT/ UX(55),LX(15)
           LOGICAL LX
           UX(41)=-0.25*Z1
5          IF(Z1.GE.0.5) UX(41)=-0.125
           UX(42)=-7.6+1.5*Z1
           UX(43)=-27.+6.*Z1
           UX(44)=0.14*Z1
           IF(Z1.GE.0.5) UX(44)=0.07
10         UX(45)=17.5-5.*Z1
           UX(46)=0.3-0.12*Z1
           UX(47)=-1.*Z1
           IF(Z1.GE.0.5) UX(47)=-.5
15         UX(48)=-18.*Z1
           UX(49)=-0.23+0.08*Z1
           UX(50)=2.*Z1
           UX(51)=UX(44)
           UX(52)=UX(45)
           UX(53)=UX(49)
20        UX(54)=UX(50)
           RETURN
           END
           HON09      704
           HON09      705
           HON09      706
           HON09      707
           HON09      708
           HON09      709
           HON09      710
           HON09      711
           HON09      712
           HON09      713
           HON09      714
           HON09      715
           HON09      716
           HON09      717
           HON09      718
           HON09      719
           HON09      720
           HON09      721
           HON09      722
           HON09      723
           HON09      724
           HON09      725

```

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
3 GAIN2

VARIABLES	SN	TYPE	RELOCATION					
67 LX		LOGICAL	ARRAY	VARDAT	0 UX	REAL	ARRAY	VARDAT
0 Z1		REAL		F.P.				

COMMON BLOCKS LENGTH
VARDAT 70

STATISTICS
PROGRAM LENGTH 738 59
CM LABELED COMMON LENGTH 1068 70

Figure 10. -Program listing of subroutine GAIN2.

APPENDIX C
 FLOW CHART FOR REAL-TIME PORTION OF
 PCMLE PROGRAM

This appendix consists of the flowchart for subroutine PCMLE (Fig. 11).

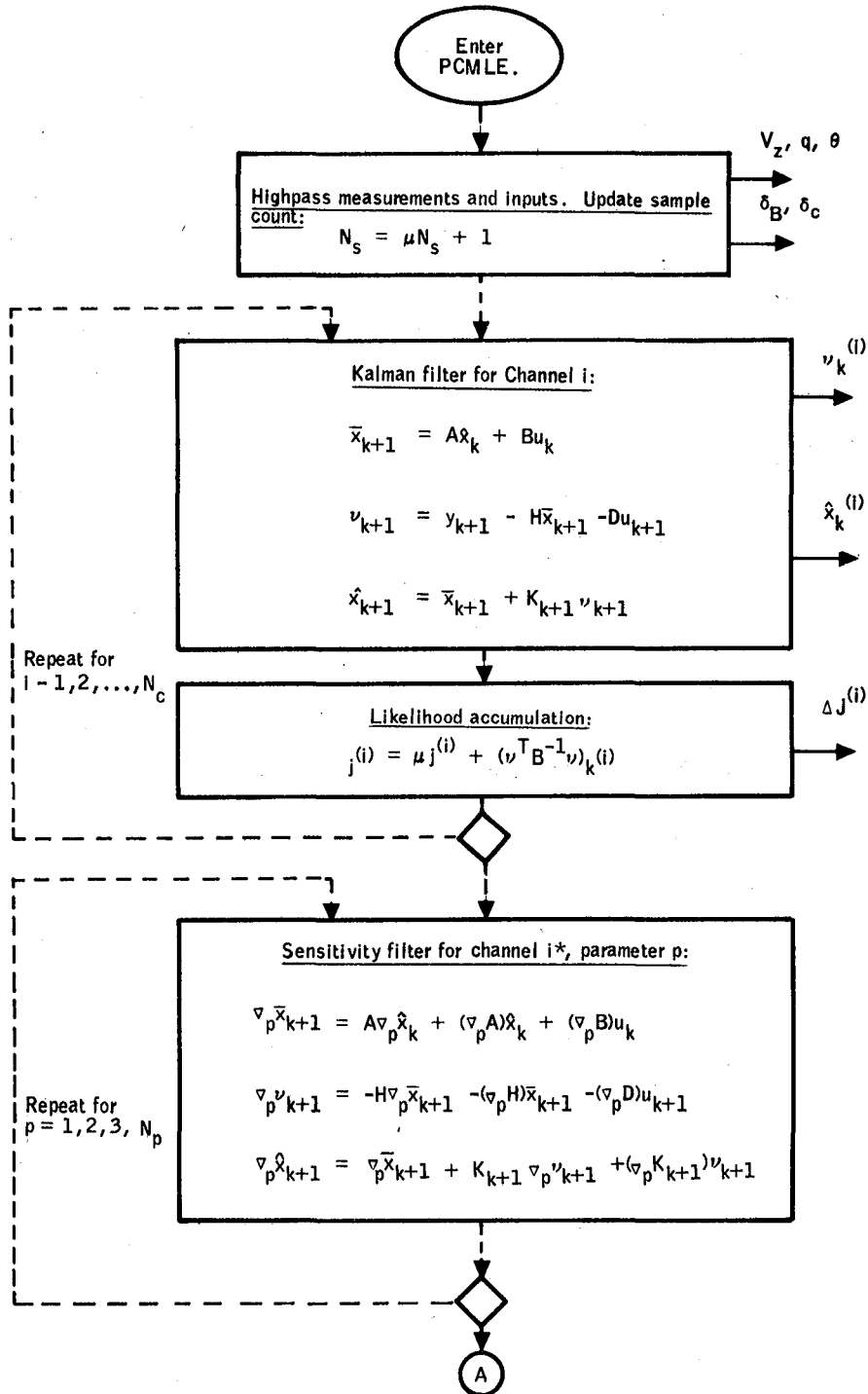


Figure 11. - Flowchart for subroutine PCMLE.

Appendix C

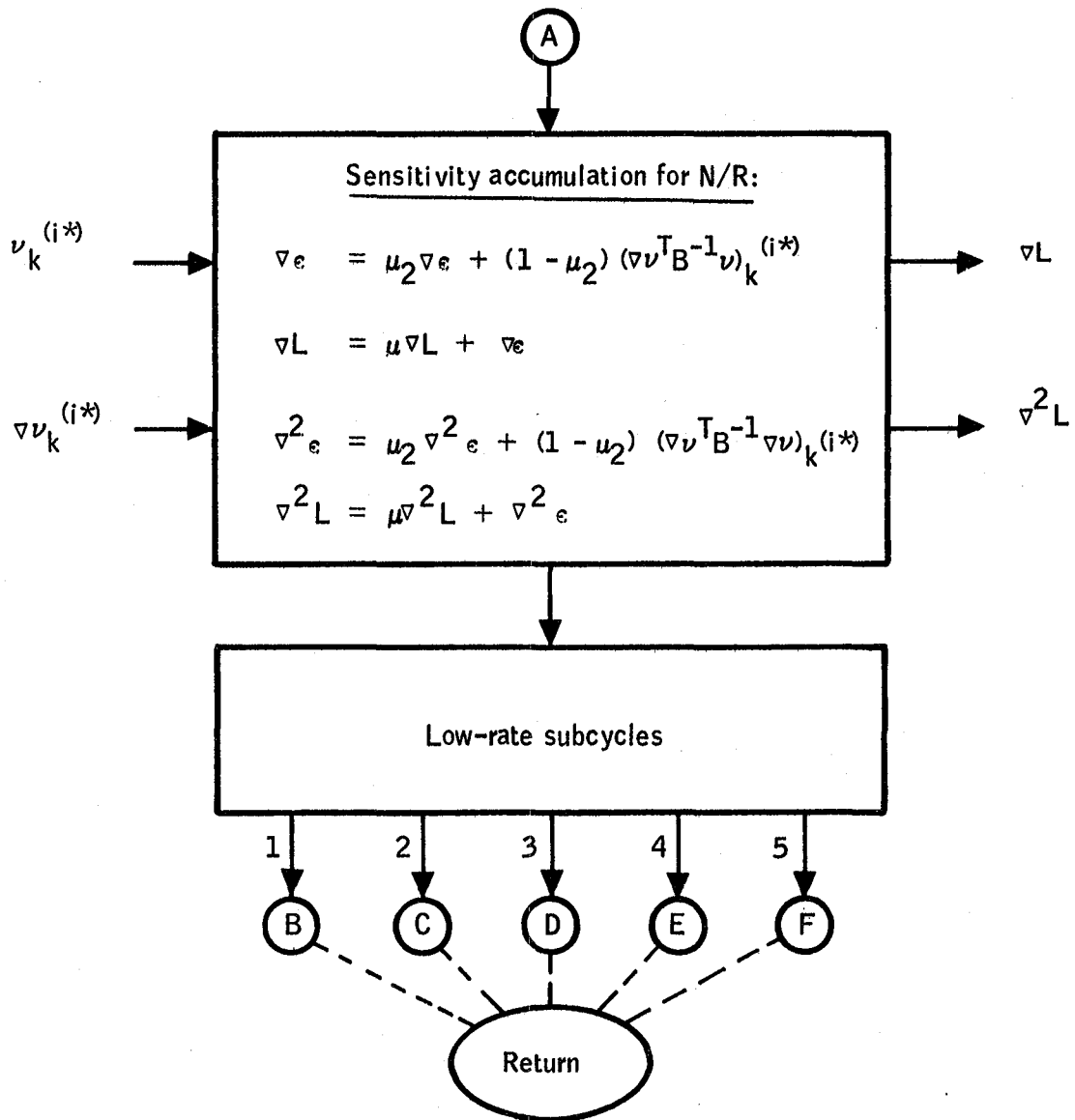


Figure 11. -Continued.

Appendix C

Subcycle 1: Min-L select

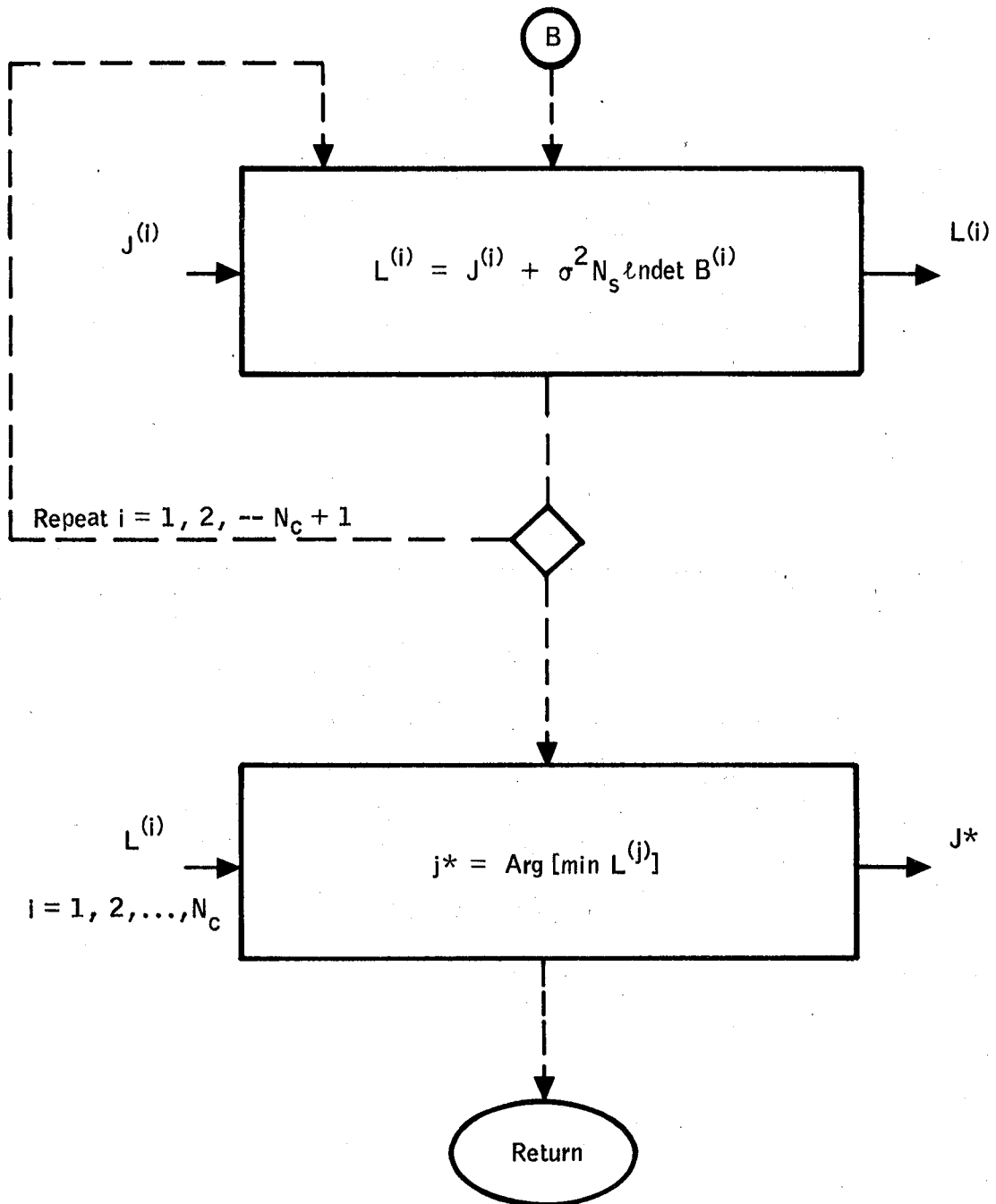


Figure 11. -Continued.

Appendix C

Subcycle 2: Significance tests and change logic

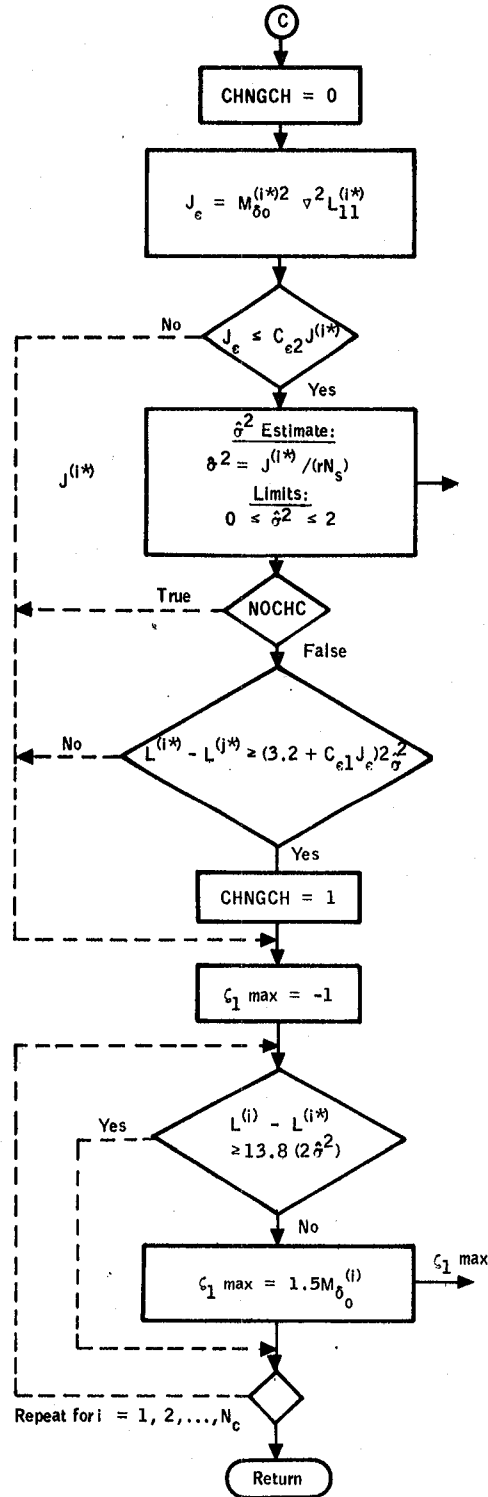


Figure 11. -Continued.

Appendix C

Subcycle 3: Channel data transfer

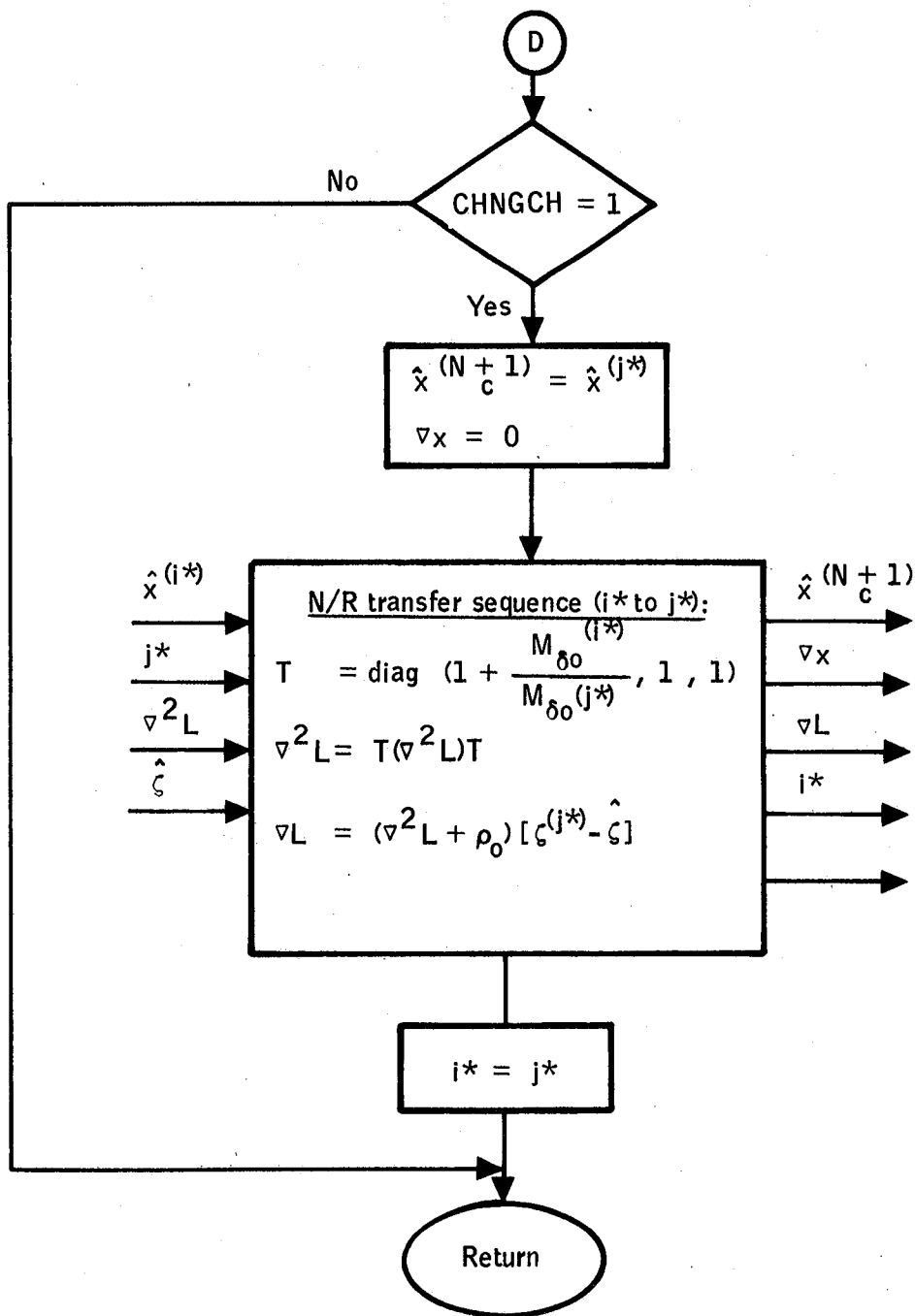
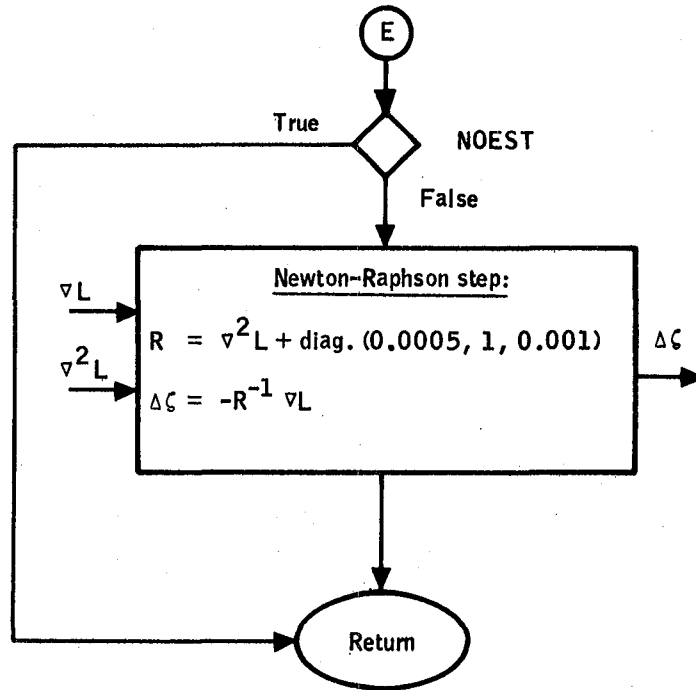


Figure 11. -Continued.

Appendix C

Subcycle 4: Parameter increment



Subcycle 5: Parameter estimates

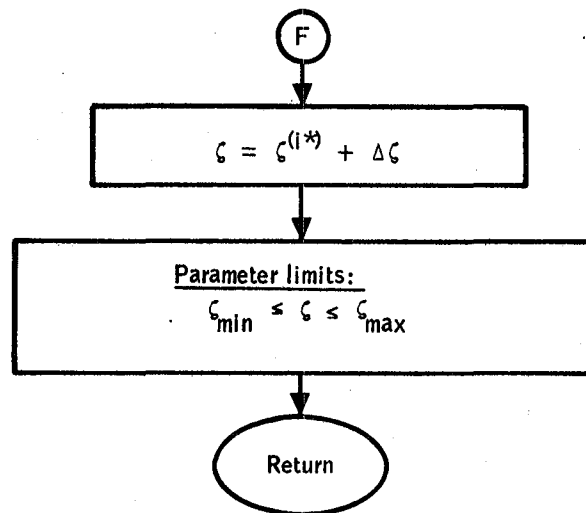


Figure 11. -Concluded.

APPENDIX D
LISTING OF PCMLE REAL-TIME SOFTWARE

This appendix is comprised of the program listings of PCMLE, FILT, SENS, ACUM, FH, and TSIG, as presented in Figures 12 through 17, respectively.

SUBROUTINE PCMLE	7/3/74 OPT=1	FTN 4,6+452	78/04/06. 08.36.47
1	SUBROUTINE PCMLE		HON09 1213
	COMMON/VARDAT/UX(55),LX(15)		HON09 1214
	COMMON/DAT/X(5,19), F(5,22),D(5,22),E1P,E2P,SIGSQ		HON09 1215
	COMMON/SENSP/XS(4,19),DS(5,4,22),GE(4),GL(4),GSQE(10),GSQL(10)		HON09 1216
5	1 ,GK(5,4,12)		HON09 1217
	COMMON/IPIC/ NC,NP,JS,CHNGCH,CHSIG,ANS		HON09 1218
	1 ,TPRINT,MODE,SIGUTO,ZP1,ZP2,ZP3,ZP4,TIME,RTJS		HON09 1219
	2 ,RTJG,THRTJG,RTJC,THRTJC,RTJZ,THRTJZ,DTPRIN		HON09 1220
	3 ,ZP1MAX,ZP2MAX,ZP3MAX,ZP4MAX		HON09 1221
10	4 ,ZP1MIN,ZP2MIN,ZP3MIN,ZP4MIN		HON09 1222
	5 ,ZP(5,4),GSQL0(4),Y(3),U(2)		HON09 1223
	6 ,XVZ(2),XQ(2),XTH(2),XDB(2),XDC(2),PRTIME		HON09 1224
	COMMON/MEAS/YP(3),UP(2)		HON09 1225
	COMMON/SUBRH/DTHP,DHP,WHP,C1HP,C2HP		HON09 1226
15	COMMON/UTEST/DTU,SEED,WUT,DUT,SIGUT,UT10,UT20,UTMAX,W2UT,TZWUT,		HON09 1227
	1 UT1,UT2,GAMUTO		HON09 1228
	COMMON/DEVICE/NREAD,MFILE		HON09 1229
	COMMON/REALTIM/VARCHNG,INTABLS,IVARBUF(5),ITYPE,FSS(16)		HON09 1230
20	DIMENSION TL(5),TJ(5),DZP(4),SS(5)		HON09 1231
	LOGICAL FSS		HON09 1232
	LOGICAL LX, NOCHC,NOEST,PRINT,MLE		HON09 1233
	INTEGER CHNGCH,CHSIG		HON09 1234
	C		HON09 1235
	EQUIVALENCE (TL(1),X(1,15)),(TJ(1),X(1,14))		HON09 1236
25	EQUIVALENCE (R2,GSQL(2)),(R3,GSQL(3)),(R4,GSQL(4))		HON09 1237
	1 , (R6,GSQL(6)),(R7,GSQL(7)),(R9,GSQL(9))		HON09 1238
	C		HON09 1239
	TMINCH=2.		HON09 1240
	C		HON09 1241
30	C		HON09 1242
	C		HON09 1243
	C		HON09 1244
	REAL TIME MODS		HON09 1245
	NOCHC=LX(1)		HON09 1246
	NOEST=LX(2)		HON09 1247
35	PRINT=LX(5)		HON09 1248
	MLE=LX(9)		HON09 1249
	C		HON09 1250
	SIGUT=SIGUTO		HON09 1251
	C		HON09 1252
40	Y(1)=UX(11)		HON09 1253
	Y(2)=UX(12)		HON09 1254
	Y(3)=UX(13)		HON09 1255
	U(1)=UX(14)		HON09 1256
	U(2)=UX(15)		HON09 1257
45	C		HON09 1258
	C		HON09 1259
	UX(20)=-.5+.25*JJ		HON09 1260
	UX(21)=X(JS,2)/20.		HON09 1261
	UX(22)=X(JS,3)*5.73		HON09 1262
50	UX(23)=TJ(1)/400.		HON09 1263
	UX(24)=TJ(2)/400.		HON09 1264
	UX(25)=TJ(3)/400.		HON09 1265
	UX(26)=ZP1		HON09 1266
	UX(28)=ZP2		HON09 1267
55	UX(29)=ZP3		HON09 1268
	UX(30)=ZP4		HON09 1268

Figure 12. -Program listing of subroutine PCMLE.

Appendix D

	UX(31)=X(JS,1)	HON09 1269
	UX(32)=X(JS,4)	HON09 1270
60	C	HON09 1271
	C	HON09 1272
	OUTPUT VARIABLES IN RUNNING MODE (BATCH ONLY)	HON09 1273
	IF(.NOT.PRINT) GO TO 1100	HON09 1274
	PRTIME=PRTIME+DTHP	HON09 1275
	IF(PRTIME.LT.TPRINT) GO TO 1100	HON09 1276
65	WRITE(MFILE,630) PRTIME,JS,SIGSQ	HON09 1277
	WRITE(MFILE,631) (TL(I),I=1,NC)	HON09 1278
	WRITE(MFILE,632) (TJ(I),I=1,NC)	HON09 1279
	WRITE(MFILE,642) (SS(I),I=1,NC)	HON09 1280
	WRITE(MFILE,643) ZLMIN	HON09 1281
70	WRITE(MFILE,636) YP(1),YP(2),YP(3),UP(1),UP(2)	HON09 1282
	WRITE(MFILE,633)	HON09 1283
	WRITE(MFILE,634)(X(JS,I), I=1,17)	HON09 1284
	WRITE(MFILE,637)	HON09 1285
	WRITE(MFILE,634) (XS(1,I),I=1,11)	HON09 1286
75	WRITE(MFILE,634) (XS(2,I),I=1,11)	HON09 1287
	WRITE(MFILE,634) (XS(3,I),I=1,11)	HON09 1288
	WRITE(MFILE,634) (XS(4,I),I=1,11)	HON09 1289
	WRITE(MFILE,638)	HON09 1290
	WRITE(MFILE,634) (GL(I),I=1,NP)	HON09 1291
80	WRITE(MFILE,634) (GSQL(I),I=1,10)	HON09 1292
	IF(NOEST) GO TO 1090	HON09 1293
	IF(TIME.LT.TMINCH) GO TO 1090	HON09 1294
	C1 = SQRT(C1/DET)	HON09 1295
	C5 = SQRT(C5/DET)	HON09 1296
85	C8 = SQRT(C8/DET)	HON09 1297
	C10 = SQRT(C10/DET)	HON09 1298
	C2 = C2 / (C1*C5 *DET)	HON09 1299
	C3 = C3 / (C1*C8 *DET)	HON09 1300
	C4 = C4 / (C1*C10*DET)	HON09 1301
90	C6 = C6 / (C5*C8 *DET)	HON09 1302
	C7 = C7 / (C5*C10*DET)	HON09 1303
	C9 = C9 / (C8*C10*DET)	HON09 1304
	1092 WRITE(MFILE,640)	HON09 1305
	WRITE(MFILE,634) C1,C2,C3,C4,C5,C6,C7,C8,C9,C10	HON09 1306
95	1090 CONTINUE	HON09 1307
	WRITE(MFILE,639) ZP1,ZP2,ZP3,ZP4	HON09 1308
	C	HON09 1309
	606 FORMAT(6E20.5)	HON09 1310
100	630 FORMAT(///1X,11HTIME = ,E12.5, 6H JS = ,I2, 1 4X,8HSIGSQ = ,E12.5,2X,2H** , /)	HON09 1311
	631 FORMAT(1X,11HTL = ,9E12.5)	HON09 1312
	632 FORMAT(1X,11HTJ = ,9E12.5)	HON09 1313
	633 FORMAT(1H0,22HSTATE ESTIMATES X(JS))	HON09 1314
	634 FORMAT(10E12.5)	HON09 1315
105	636 FORMAT(1H0,16HY1,Y2,Y3,U1,U2 =,6E12.5)	HON09 1316
	637 FORMAT(1X,13HSENSITIVITIES)	HON09 1317
	638 FORMAT(1X,5HGRADS)	HON09 1318
	639 FORMAT(1H0,11HZP = ,9E12.5)	HON09 1319
	640 FORMAT(1X,8HACCURACY)	HON09 1320
110	642 FORMAT(1X,11HPR = ,9F12.9)	HON09 1321
	643 FORMAT(1X,11HZMIN = ,E12.5)	HON09 1322
	1099 CONTINUE	HON09 1323
	TPRINT=TPRINT+ DTPRIN	HON09 1324
115	1100 CONTINUE	HON09 1325
	C	HON09 1326
	TEST SIGNAL	HON09 1327
	CALL TSIG(ETA1,ETA2,UT)	HON09 1328
	C	HON09 1329
	C	HON09 1330
	C	HON09 1331
120	C	HON09 1332
	HIGH PASS INPUTS	HON09 1333
	CALL FH(Y(1),YP(1),XVZ)	HON09 1334
	CALL FH(Y(2),YP(2),XQ)	HON09 1335
	CALL FH(Y(3),YP(3),XTH)	HON09 1336
	CALL FH(U(1),UP(1),XDB)	HON09 1337
125	CALL FH(U(2),UP(2),XDC)	HON09 1338
	C	HON09 1339
	C	HON09 1340
	PARALLEL CHANNELS	HON09 1341
	IF(.NOT.MLE) RETURN	HON09 1342
	TIME=TIME + DTHP	HON09 1343
130	ANS=EIP*ANS + 1.	HON09 1344
	GO TO (1210,1209,1208,1207,1206), NC	HON09 1345
	1206 CALL FILT(5)	HON09 1346
	1207 CALL FILT(4)	HON09 1347
	1208 CALL FILT(3)	HON09 1348
135	1209 CALL FILT(2)	HON09 1349

Figure 12. -Continued.

Appendix D

	1210 CALL FILT(1)	HON09	1348
	C	HON09	1349
	C SENSITIVITIES	HON09	1350
	GO TO (1304,1303,1302,1301), NP	HON09	1351
140	1301 CALL SENS(JS,4)	HON09	1352
	1302 CALL SENS(JS,3)	HON09	1353
	1303 CALL SENS(JS,2)	HON09	1354
	1304 CALL SENS(JS,1)	HON09	1355
	C	HON09	1356
145	C LIKELIHOOD ACCUMULATION	HON09	1357
	CALL ACUM(JS)	HON09	1358
	C	HON09	1359
	900 CONTINUE	HON09	1360
	C	HON09	1361
150	C BRANCH TO LOW RATE OPERATIONS *****	HON09	1362
	C	HON09	1363
	GO TO (910,920,930,940,950), MODE	HON09	1364
	C	HON09	1365
155	C CYCLE 1. MIN-L CHANNEL SELECTION	HON09	1366
	C	HON09	1367
	910 CONTINUE	HON09	1368
	TLMAX = -1.E10	HON09	1369
	TLMIN = 1.E10	HON09	1370
160	TJMIN=1.E10	HON09	1371
	DO 911 I=1,NC	HON09	1372
	S1=TJ(I) + SIGSQ*ANS*F(I,13)	HON09	1373
	TL(I)= S1	HON09	1374
	IF(S1.GT.TLMAX) TLMAX=S1	HON09	1375
165	IF(S1.LT.TLMIN) TLMIN=S1	HON09	1376
	IF(TJ(I).GT.TJMIN) GO TO 911	HON09	1377
	TJMIN = TJ(I)	HON09	1378
	JSTEMP = I	HON09	1379
	911 CONTINUE	HON09	1380
170	MODE = 2	HON09	1381
	RETURN	HON09	1382
	C	HON09	1383
	C CYCLE 2. SIGNIFICANCE TESTS AND CHANGE LOGIC	HON09	1384
	C	HON09	1385
175	920 CONTINUE	HON09	1386
	CHNGCH=0	HON09	1387
	TJE=0.01*GSQL(1)	HON09	1388
	C	HON09	1389
	IF(TJE.GT.RTJS*TJ(JS)) GO TO 925	HON09	1390
180	SIGSQ= TJ(JS)/(ANS + ANS)	HON09	1391
	IF(SIGSQ.GT.2.) SIGSQ=2.	HON09	1392
	IF(SIGSQ.LT.1.0E-04) SIGSQ=1.0E-04	HON09	1393
	C	HON09	1394
185	925 IF(NOCHC) GO TO 926	HON09	1395
	IF((TL(JS) - TL(JSTEMP)).GT.(THRTJC+RTJC+TJE)) CHNGCH=1	HON09	1396
	C	HON09	1397
	926 CONTINUE	HON09	1398
	DO 927 I=1,NC	HON09	1399
	IF((TL(I) - TL(JS)).LT.(THRTJZ + RTJZ+TJE)) ZIMIN=ZP(I,1)	HON09	1400
190	SS(I)= (TL(JS)- TL(I))*0.5	HON09	1401
	IF(SS(I).GT.0.) SS(I)=0.	HON09	1402
	IF(SS(I).LT.-23.) SS(I)=-23.	HON09	1403
	1094 SS(I)=EXP(SS(I))	HON09	1404
195	927 CONTINUE	HON09	1405
	UX(33)=SIGSQ	HON09	1406
	MODE= 3	HON09	1407
	RETURN	HON09	1408
	C	HON09	1409
	C CHANNEL TRANSFERS	HON09	1410
200	C	HON09	1411
	930 CONTINUE	HON09	1412
	IF(CHNGCH.EQ.0) GO TO 939	HON09	1413
	IF(TIME.GT.TMINCH) GO TO 9301	HON09	1414
205	DO 9303 I=1,10	HON09	1415
	GSQL(I)=0.	HON09	1416
	GSQL(I)=0.	HON09	1417
	9303 DO 9302 I=1,4	HON09	1418
	DZP(I)=0.	HON09	1419
	GL(I)=0.	HON09	1420
210	9302 GE(I)=0.	HON09	1421
	GO TO 934	HON09	1422
	9301 CONTINUE	HON09	1423
	C	HON09	1424
	C CHANNEL TRANSFER SEQUENCE (NR)	HON09	1425
	C	HON09	1426

Figure 12. -Continued.

Appendix D

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215      C      SCALE GRAD SQ L                                HON09      1427
          S1=1. + ZP(JS,1)/ZP(JSTEMP,1)                    HON09      1428
          GSQL(1)= GSQL(1)*S1                               HON09      1429
          GSQL(2)= GSQL(2)*S1                               HON09      1430
          GSQL(3)= GSQL(3)*S1                               HON09      1431
220      C      GSQL(4)= GSQL(4)*S1                           HON09      1432
          S1=GSQL(1) + GSQLO(1)                             HON09      1433
          S2=GSQL(5) + GSQLO(2)                             HON09      1434
          S3=GSQL(8) + GSQLO(3)                             HON09      1435
          S4=GSQL(10)+ GSQLO(4)                             HON09      1436
225      C      NEW GRAD L                                    HON09      1437
          DZP(1)=-ZP1 + ZP(JSTEMP,1)                       HON09      1438
          DZP(2)=-ZP2 + ZP(JSTEMP,2)                       HON09      1439
          DZP(3)=-ZP3 + ZP(JSTEMP,3)                       HON09      1440
          DZP(4)=-ZP4 + ZP(JSTEMP,4)                       HON09      1441
230      C      GL(1)=S1 *DZP(1)+GSQL(2)*DZP(2)+GSQL(3)*DZP(3)+GSQL(4)*DZP(4) HON09      1442
          GL(2)=GSQL(2)+DZP(1)+S2 *DZP(2)+GSQL(6)*DZP(3)+GSQL(7)*DZP(4) HON09      1443
          GL(3)=GSQL(3)+DZP(1)+GSQL(6)*DZP(2)+S3 *DZP(3)+GSQL(9)*DZP(4) HON09      1444
          GL(4)=GSQL(4)+DZP(1)+GSQL(7)*DZP(2)+GSQL(9)+DZP(3)+S4 *DZP(4) HON09      1445
235      C      934 JS=JSTEMP                                  HON09      1446
          939 CONTINUE                                       HON09      1447
          MODE= 4                                           HON09      1448
          RETURN                                             HON09      1449
240      C      CYCLE 4. PARAMETER INCREMENTS                HON09      1450
          C      940 CONTINUE                                  HON09      1451
          IF(NDEST) GO TO 948                                HON09      1452
          C      NR INCREMENTS                                HON09      1453
          R1=GSQL(1) + GSQLO(1)                             HON09      1454
          R5=GSQL(5) + GSQLO(2)                             HON09      1455
          R8=GSQL(8) + GSQLO(3)                             HON09      1456
          R10=GSQL(10)+GSQLO(4)                             HON09      1457
245      C      CDFACTORS FOR EXPLICIT INVERSE                HON09      1458
          R81099=R8*R10-R9*R9                               HON09      1459
          R61097=R6*R10-R9*R7                               HON09      1460
          R6978= R6*R9-R7*R8                               HON09      1461
          R3764=R3*R7-R6*R4                                 HON09      1462
          R2754=R2*R7-R5*R4                                 HON09      1463
          R2653=R2*R6-R5*R3                                 HON09      1464
          R21047=R2*R10 -R4*R7                             HON09      1465
          R2937=R2*R9 -R3*R7                               HON09      1466
          R2836=R2*R8-R3*R6                                 HON09      1467
250      C      INVERSE                                        HON09      1468
          C1= R5*R81099 - R6*R61097 + R7*R6978            HON09      1469
          C2=- (R2*R81099 - R3*R61097 + R4*R6978)         HON09      1470
          C3=R7*R3764 - R9*R2754 + R10*R2653              HON09      1471
          C4=- (R6*R3764 - R8*R2754 + R9*R2653)           HON09      1472
          C5=R1*R81099 - R3*(R3*R10 - R4*R9) + R4*(R3*R9 - R4*R8) HON09      1473
          C6=- (R1*R61097 - R3*R21047 + R4*(R2*R9 - R4*R6)) HON09      1474
          C7=R1*R6978 - R3*R2937 + R4*R2836               HON09      1475
          C8=R1*(R5*R10 - R7*R7) - R2*R21047 + R4*R2754  HON09      1476
          C9=- (R1*(R5*R9 - R6*R7) - R2*R2937 + R4*R2653) HON09      1477
          C10=R1*(R5*R8 - R6*R6) - R2*R2836 + R3*R2653   HON09      1478
          DET= R1*C1 + R2*C2 + R3*C3 + R4*C4              HON09      1479
          IF(DET.EQ.0.0) STOP 21                             HON09      1480
255      C      INCREMENTS                                    HON09      1481
          DZP(1)= -(C1*GL(1)+C2*GL(2)+C3*GL(3)+C4*GL(4))/DET HON09      1482
          DZP(2)= -(C2*GL(1)+C5*GL(2)+C6*GL(3)+C7*GL(4))/DET HON09      1483
          DZP(3)= -(C3*GL(1)+C6*GL(2)+C8*GL(3)+C9*GL(4))/DET HON09      1484
          DZP(4)= -(C4*GL(1)+C7*GL(2)+C9*GL(3)+C10*GL(4))/DET HON09      1485
          UX(27)=SORT(C1/DET)                                HON09      1486
260      C      948 MODE = 5                                  HON09      1487
          RETURN                                             HON09      1488
          C      CYCLE 5. PARAMETER UPDATES                  HON09      1489
          C      950 CONTINUE                                  HON09      1490
          UPDATE ZP                                          HON09      1491
          ZP1= ZP(JS,1) + DZP(1)                            HON09      1492
          ZP2= ZP(JS,2) + DZP(2)                            HON09      1493
          ZP3= ZP(JS,3) + DZP(3)                            HON09      1494
          ZP4= ZP(JS,4) + DZP(4)                            HON09      1495
          IF(ZP1.GT.ZP1MAX) ZP1=ZP1MAX                     HON09      1496
          IF(ZP2.GT.ZP2MAX) ZP2=ZP2MAX                     HON09      1497
          IF(ZP3.GT.ZP3MAX) ZP3=ZP3MAX                     HON09      1498
          IF(ZP4.GT.ZP4MAX) ZP4=ZP4MAX                     HON09      1499
          HON09      1500
          HON09      1501
          HON09      1502
          HON09      1503
          HON09      1504
          HON09      1505
          HON09      1506

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Figure 12. -Continued.

Appendix D

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295      IF(ZP1.LT.ZP1MIN) ZP1=ZP1MIN
          IF(ZP2.LT.ZP2MIN) ZP2=ZP2MIN
          IF(ZP3.LT.ZP3MIN) ZP3=ZP3MIN
          IF(ZP4.LT.ZP4MIN) ZP4=ZP4MIN
          C   OTHER VARIABLES
          C   MODE= 1
          C   RETURN
          C
          END
          HON09 1507
          HON09 1508
          HON09 1509
          HON09 1510
          HON09 1511
          HON09 1512
          HON09 1513
          HON09 1514
          HON09 1515
    
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SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS

1 PCMLE

VARIABLES	SN	TYPE	RELOCATION					
5	ANS	REAL	IPIC	3	CHNGCH	INTEGER		IPIC
4	CHSIG	INTEGER	IPIC	1362	C1	REAL		
3	C1MP	REAL	SUBRH	1366	C10	REAL		
1367	C2	REAL		4	C2HP	REAL		SUBRH
1370	C3	REAL		1371	C4	REAL		
1364	C5	REAL		1372	C6	REAL		
1373	C7	REAL		1365	C8	REAL		
1374	C9	REAL		315	D	REAL	ARRAY	DAT
1363	DET	REAL		1	DHP	REAL		SUBRH
114	DS	REAL	ARRAY	0	DTHP	REAL		SUBRH
25	DTPRIN	REAL	IPIC	0	DTU	REAL		UTEST
3	DUT	REAL	UTEST	1426	DZP	REAL	ARRAY	
1375	ETA1	REAL		1376	ETA2	REAL		
473	E1P	REAL	DAT	474	E2P	REAL		DAT
137	F	REAL	ARRAY	10	FSS	LOGICAL	ARRAY	REALTIM
14	GAMUTO	REAL	UTEST	1004	GE	REAL	ARRAY	SENSP
1040	GK	REAL	ARRAY	1010	GL	REAL	ARRAY	SENSP
1014	GSQE	REAL	ARRAY	1026	GSQL	REAL	ARRAY	SENSP
62	GSQLO	REAL	ARRAY	1360	I	INTEGER		
1	INTABLS	INTEGER	REALTIM	7	ITYPE	INTEGER		REALTIM
2	IVARBUF	INTEGER	ARRAY	2	JS	INTEGER		IPIC
1404	JSTEMP	INTEGER		67	LX	LOGICAL	ARRAY	WARDAT
1	MFILE	INTEGER	DEVICE	1356	MLE	LOGICAL		
7	MODE	INTEGER	IPIC	0	NC	INTEGER		IPIC
1353	NOCHC	LOGICAL		1354	NOEST	LOGICAL		
1	NP	INTEGER	IPIC	0	NREAD	INTEGER		DEVICE
1355	PRINT	LOGICAL		105	PRTIME	REAL		IPIC
21	RTJC	REAL	IPIC	17	RTJG	REAL		IPIC
16	RTJS	REAL	IPIC	23	RTJZ	REAL		IPIC
1411	R1	REAL		1414	R10	REAL		
1027	R2	REAL	SENSP	1423	R21047	REAL		
1422	R2653	REAL		1421	R2754	REAL		
1425	R2836	REAL		1424	R2937	REAL		
1030	R3	REAL	SENSP	1420	R3764	REAL		
1031	R4	REAL	SENSP	1412	R5	REAL		
1033	R6	REAL	SENSP	1416	R61097	REAL		
1417	R6978	REAL		1034	R7	REAL		SENSP
1413	R8	REAL		1415	R81099	REAL		
1036	R9	REAL	SENSP	1	SEED	REAL		UTEST
475	SIGSQ	REAL	DAT	4	SIGUT	REAL		UTEST
10	SIGUTO	REAL	IPIC	1432	SS	REAL	ARRAY	
1403	S1	REAL		1406	S2	REAL		
1407	S3	REAL		1410	S4	REAL		
22	THRTJC	REAL	IPIC	20	THRTJG	REAL		IPIC
24	THRTJZ	REAL	IPIC	15	TIME	REAL		IPIC
101	TJ	REAL	ARRAY	1405	TJE	REAL		
1402	TJMIN	REAL		106	TL	REAL	ARRAY	DAT
1400	TJMAX	REAL		1401	TLMIN	REAL		
1357	TJMINCH	REAL		6	TPRINT	REAL		IPIC
11	TZWUT	REAL	UTEST	71	U	REAL	ARRAY	IPIC
3	UP	REAL	ARRAY	1377	UT	REAL		
7	UTMAX	REAL	UTEST	12	UT1	REAL		UTEST
5	UT10	REAL	UTEST	13	UT2	REAL		UTEST
6	UT20	REAL	UTEST	0	UX	REAL	ARRAY	WARDAT
0	VARCHNG	REAL	REALTIM	2	WHP	REAL		SUBRH
2	WUT	REAL	UTEST	10	W2UT	REAL		UTEST
0	X	REAL	ARRAY	101	XDB	REAL	ARRAY	IPIC
103	XDC	REAL	ARRAY	75	XQ	REAL	ARRAY	IPIC
0	XS	REAL	ARRAY	77	XTH	REAL	ARRAY	IPIC

Figure 12. -Continued.

Appendix D

73	XVZ	REAL	ARRAY	IPIC	66	Y	REAL	ARRAY	IPIC	
0	YP	REAL	ARRAY	MEAS	36	ZP	REAL	ARRAY	IPIC	
11	ZP1	REAL		IPIC	26	ZP1MAX	REAL		IPIC	
32	ZP1MIN	REAL		IPIC	12	ZP2	REAL		IPIC	
27	ZP2MAX	REAL		IPIC	33	ZP2MIN	REAL		IPIC	
13	ZP3	REAL		IPIC	30	ZP3MAX	REAL		IPIC	
34	ZP3MIN	REAL		IPIC	14	ZP4	REAL		IPIC	
31	ZP4MAX	REAL		IPIC	35	ZP4MIN	REAL		IPIC	
1361	Z1MIN	REAL								
EXTERNALS		TYPE	ARGS							
	ACUM		1		EXP	REAL		1	LIBRARY	
	FH		3		FILT			1		
	SENS		2		SQRT	REAL		1	LIBRARY	
	TSIG		3							
STATEMENT LABELS										
1246	606	FMT	NO REFS	1250	630	FMT		1260	631	FMT
1264	632	FMT		1270	633	FMT		1274	634	FMT
1276	636	FMT		1302	637	FMT		1305	638	FMT
1310	639	FMT		1314	640	FMT		1317	642	FMT
1323	643	FMT			0	900	INACTIVE		352	910
	377	911			403	920			417	925
	427	926				0	927		462	930
	562	934			564	939			566	940
	763	948			765	950			244	1090
	0	1092	INACTIVE		0	1094	INACTIVE		0	1099
	250	1100			303	1206			305	1207
	307	1208			311	1209			313	1210
	326	1301			330	1302			332	1303
	334	1304			503	9301			0	9302
	0	9303								
LOOPS	LABEL	INDEX	FROM-TO	LENGTH	PROPERTIES					
105		* I	72 72	11B	EXT REFS					
124		* I	74 74	7B	EXT REFS					
137		* I	75 75	7B	EXT REFS					
152		* I	76 76	7B	EXT REFS					
165		* I	77 77	7B	EXT REFS					
363	911	I	161 169	15B	DPT					
430	927	* I	188 194	27B	EXT REFS					
470	9303	I	204 206	3B	INSTACK					
476	9302	I	207 210	3B	INSTACK					
COMMON	BLOCKS	LENGTH								
	VARDAT	70								
	DAT	318								
COMMON	BLOCKS	LENGTH								
	SENSP	784								
	IPIC	70								
	MEAS	5								
	SUBRH	5								
	UTEST	13								
	DEVICE	2								
	REALTIM	24								
STATISTICS										
	PROGRAM LENGTH		14418	801						
	CM LABELED COMMON LENGTH		24138	1291						
	730008 CM USED									

Figure 12, -Concluded.

Appendix D

```

SUBROUTINE FILT      73/74  OPT=1      FTN 4.6+439      78/02/14. 08.28.50

1      SUBROUTINE FILT(K)
COMMON/DAT/X(5,19), F(5,22),D(5,22),E1P,E2P,SIGSQ
COMMON/MEAS/YP(3),UP(2)
C      K=CHANNEL INDEX
5      C      SAVE X
      X(K,1)=X(K,5)
      X(K,2)=X(K,5)
      X(K,3)=X(K,7)
      X(K,4)=X(K,8)
10     C      RESIDUALS
      X(K,9)= YP(1) - X(K,2)
      X(K,10)=YP(2) - X(K,3)
      X(K,11)=YP(3) - X(K,4)
15     C      UPDATE X
      X(K,5)=D(K, 1)*X(K,5) + D(K, 2)*X(K,6) + D(K, 3)*X(K,7) +
1      D(K, 4)*X(K,8) + D(K,17)*UP(1) + D(K,18)*UP(2) +
2      F(K,1)*X(K,9) + F(K,5)*X(K,10) + F(K,9)*X(K,11)
      X(K,6)=D(K, 5)*X(K,5) + D(K, 6)*X(K,6) + D(K, 7)*X(K,7) +
1      D(K, 8)*X(K,8) + D(K,19)*UP(1) + D(K,20)*UP(2) +
20     2      F(K,2)*X(K,9) + F(K,6)*X(K,10) + F(K,10)*X(K,11)
      X(K,7)=D(K, 9)*X(K,5) + D(K,10)*X(K,6) + D(K,11)*X(K,7) +
1      D(K,12)*X(K,8) + D(K,21)*UP(1) + D(K,22)*UP(2) +
2      F(K,3)*X(K,9) + F(K,7)*X(K,10) + F(K,11)*X(K,11)
      X(K,8)=D(K,13)*X(K,5) + D(K,14)*X(K,6) + D(K,15)*X(K,7) +
25     1      D(K,16)*X(K,8) +
2      F(K,4)*X(K,9) + F(K,8)*X(K,10) + F(K,12)*X(K,11)
30     C      (NU)(RI)(NU)
      X(K,12)=F(K,14)*X(K,9)*X(K,9) + F(K,18)*X(K,10)*X(K,10) +
1      F(K,22)*X(K,11)*X(K,11) + (F(K,15)+F(K,17))*X(K,9)*X(K,10) +
2      (F(K,16)+F(K,20))*X(K,9)*X(K,11) + (F(K,19)+F(K,21))*X(K,10)*
3      X(K,11)
C      SUM
      X(K,14)=E1P*X(K,14) + X(K,12)
C      (NU)(RI)(NU) + LNDETR
      X(K,13)=X(K,12) + SIGSQ*F(K,13)
35     RETURN
      END
HON09      589
HON09      590
HON09      591
HON09      592
HON09      593
HON09      594
HON09      595
HON09      596
HON09      597
HON09      598
HON09      599
HON09      600
HON09      601
HON09      602
HON09      603
HON09      604
HON09      605
HON09      606
HON09      607
HON09      608
HON09      609
HON09      610
HON09      611
HON09      612
HON09      613
HON09      614
HON09      615
HON09      616
HON09      617
HON09      618
HON09      619
HON09      620
HON09      621
HON09      622
HON09      623
HON09      624
HON09      625

```

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
3 FILT

VARIABLES	SN	TYPE	RELOCATION						
315 D		REAL	ARRAY	DAT	473	E1P	REAL		DAT
474 E2P		REAL		DAT	137	F	REAL	ARRAY	DAT
0 K		INTEGER		F.P.	475	SIGSQ	REAL		DAT
3 UP		REAL	ARRAY	MEAS	0	X	REAL	ARRAY	DAT
0 YP		REAL	ARRAY	MEAS					

COMMON BLOCKS LENGTH
JAT 318
MEAS 5

STATISTICS
PROGRAM LENGTH 1728 122
CM LABELED COMMON LENGTH 5038 323

Figure 13. -Program listing of subroutine FILT.

Appendix D

```

SUBROUTINE SENS      73/74  OPT=1                      FTN 4.6+439      78/02/14. 08.28.50

1      SUBROUTINE SENS(K,J)                                HON09      1679
COMMON/DAT/X(5,19), F(5,22),D(5,22),E1P,E2P,SIGSQ      HON09      1680
COMMON/MEAS/YP(3),UP(2)                                HON09      1681
COMMON/SENSP/XS(4,19),DS( 5,4,22),GE(4),GL(4),GSQE(10),GSQL(10) HON09      1682
5      1,GK(5,4,12)                                       HON09      1683
C      J=PARAMETER INDEX                                HON09      1684
C      K=CHANNEL INDEX                                  HON09      1685
C      SAVE GRAD X                                       HON09      1686
10     XS(J,1)=XS(J,5)                                    HON09      1687
      XS(J,2)=XS(J,6)                                    HON09      1688
      XS(J,3)=XS(J,7)                                    HON09      1689
      XS(J,4)=XS(J,8)                                    HON09      1690
C      GRAD NU=-1*(GX)                                    HON09      1691
      XS(J, 9)=-XS(J,2)                                  HON09      1692
15     XS(J,10)=-XS(J,3)                                  HON09      1693
      XS(J,11)=-XS(J,4)                                  HON09      1694
C      GRAD X UPDATE                                      HON09      1695
      XS(J,5)=D(K, 1)*XS(J,5) + D(K, 2)*XS(J,6) + D(K, 3)*XS(J,7) + HON09      1696
20     1 D(K, 4)*XS(J,8) + DS(K,J, 1)*X(K,5) + DS(K,J, 2)*X(K,6) + HON09      1697
      2 DS(K,J, 3)*X(K,7) + DS(K,J, 4)*X(K,8) + DS(K,J,17)*UP(1) HON09      1698
      3 + DS(K,J,18)*UP(2) + F(K, 1)*XS(J,9) + F(K, 5)*XS(J,10) + HON09      1699
      4 F(K, 9)*XS(J,11) + GK(K,J, 1)*X(K,9) + GK(K,J, 5)*X(K,10) HON09      1700
      5 + GK(K,J, 9)*X(K,11)                                HON09      1701
      XS(J,6)=D(K, 5)*XS(J,5) + D(K, 6)*XS(J,6) + D(K, 7)*XS(J,7) + HON09      1702
25     1 D(K, 8)*XS(J,8) + DS(K,J, 5)*X(K,5) + DS(K,J, 6)*X(K,6) + HON09      1703
      2 DS(K,J, 7)*X(K,7) + DS(K,J, 8)*X(K,8) + DS(K,J,19)*UP(1) HON09      1704
      3 + DS(K,J,20)*UP(2) + F(K, 2)*XS(J,9) + F(K, 6)*XS(J,10) + HON09      1705
      4 F(K,10)*XS(J,11) + GK(K,J, 2)*X(K,9) + GK(K,J, 6)*X(K,10) HON09      1706
      5 + GK(K,J,10)*X(K,11)                                HON09      1707
30     XS(J,7)=D(K, 9)*XS(J,5) + D(K,10)*XS(J,6) + D(K,11)*XS(J,7) + HON09      1708
      1 D(K,12)*XS(J,8) + DS(K,J, 9)*X(K,5) + DS(K,J,10)*X(K,6) + HON09      1709
      2 DS(K,J,11)*X(K,7) + DS(K,J,12)*X(K,8) + DS(K,J,21)*UP(1) HON09      1710
      3 + DS(K,J,22)*UP(2) + F(K, 3)*XS(J,9) + F(K, 7)*XS(J,10) + HON09      1711
      4 F(K,11)*XS(J,11) + GK(K,J, 3)*X(K,9) + GK(K,J, 7)*X(K,10) HON09      1712
35     5 + GK(K,J,11)*X(K,11)                                HON09      1713
      XS(J,8)=D(K,13)*XS(J,5) + D(K,14)*XS(J,6) + D(K,15)*XS(J,7) + HON09      1714
      1 D(K,16)*XS(J,8) + DS(K,J,13)*X(K,5) + DS(K,J,14)*X(K,6) + HON09      1715
      2 DS(K,J,15)*X(K,7) + DS(K,J,16)*X(K,8)                                HON09      1716
      3 + F(K, 4)*XS(J,9) + F(K, 8)*XS(J,10) + HON09      1717
40     4 F(K,12)*XS(J,11) + GK(K,J, 4)*X(K,9) + GK(K,J, 8)*X(K,10) HON09      1718
      5 + GK(K,J,12)*X(K,11)                                HON09      1719
      RETURN                                              HON09      1720
      END                                                HON09      1721

```

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
3 SENS

VARIABLES	SN	TYPE	RELOCATION					
315 D		REAL	ARRAY	DAT	114	DS	REAL	ARRAY
473 E1P		REAL		DAT	474	E2P	REAL	DAT
137 F		REAL	ARRAY	DAT	1004	GE	REAL	ARRAY
1040 GK		REAL	ARRAY	SENSP	1010	GL	REAL	ARRAY
1014 GSQE		REAL	ARRAY	SENSP	1026	GSQL	REAL	ARRAY
0 J		INTEGER		F.P.	0	K	INTEGER	F.P.
475 SIGSQ		REAL		DAT	3	UP	REAL	ARRAY
0 X		REAL	ARRAY	DAT	0	XS	REAL	ARRAY
0 YP		REAL	ARRAY	MEAS				SENSP

COMMON BLOCKS	LENGTH
DAT	318
MEAS	5
SENSP	784

STATISTICS		
PROGRAM LENGTH	4028	258
CM LABELED COMMON LENGTH	21238	1107

Figure 14. -Program listing of subroutine SENS.

Appendix D

SUBROUTINE ACUM	73/74 DPT=1	FTN 4.6+439	78/02/14. 08.28.50
1	SUBROUTINE ACUM(K)		HON09 81
	COMMON/DAT/X(5,19), F(5,22),D(5,22),E1P,E2P,SIGSQ		HON09 82
	COMMON/SENSP/XS(4,19),DS(5,4,22),GE(4),GL(4),GSQE(10),GSQL(10)		HON09 83
	1 , GK(5,4,12)		HON09 84
5	C K=CHANNEL INDICATOR		HON09 85
	T11=XS(1,9)*F(K,14) + XS(1,10)*F(K,17) + XS(1,11)*F(K,20)		HON09 86
	T12=XS(1,9)*F(K,15) + XS(1,10)*F(K,18) + XS(1,11)*F(K,21)		HON09 87
	T13=XS(1,9)*F(K,16) + XS(1,10)*F(K,19) + XS(1,11)*F(K,22)		HON09 88
	T21=XS(2,9)*F(K,14) + XS(2,10)*F(K,17) + XS(2,11)*F(K,20)		HON09 89
10	T22=XS(2,9)*F(K,15) + XS(2,10)*F(K,18) + XS(2,11)*F(K,21)		HON09 90
	T23=XS(2,9)*F(K,16) + XS(2,10)*F(K,19) + XS(2,11)*F(K,22)		HON09 91
	T31=XS(3,9)*F(K,14) + XS(3,10)*F(K,17) + XS(3,11)*F(K,20)		HON09 92
	T32=XS(3,9)*F(K,15) + XS(3,10)*F(K,18) + XS(3,11)*F(K,21)		HON09 93
	T33=XS(3,9)*F(K,16) + XS(3,10)*F(K,19) + XS(3,11)*F(K,22)		HON09 94
15	T41=XS(4,9)*F(K,14) + XS(4,10)*F(K,17) + XS(4,11)*F(K,20)		HON09 95
	T42=XS(4,9)*F(K,15) + XS(4,10)*F(K,18) + XS(4,11)*F(K,21)		HON09 96
	T43=XS(4,9)*F(K,16) + XS(4,10)*F(K,19) + XS(4,11)*F(K,22)		HON09 97
	C S=(GRAD NU)(RI)(NU)		HON09 98
	C		HON09 99
20	S1=T11*X(K,9) + T12*X(K,10) + T13*X(K,11)		HON09 100
	S2=T21*X(K,9) + T22*X(K,10) + T23*X(K,11)		HON09 101
	S3=T31*X(K,9) + T32*X(K,10) + T33*X(K,11)		HON09 102
	S4=T41*X(K,9) + T42*X(K,10) + T43*X(K,11)		HON09 103
25	GE(1)=E2P*(GE(1) - S1) + S1		HON09 104
	GE(2)=E2P*(GE(2) - S2) + S2		HON09 105
	GE(3)=E2P*(GE(3) - S3) + S3		HON09 106
	GE(4)=E2P*(GE(4) - S4) + S4		HON09 107
	C		HON09 108
30	GL(1)= E1P*GL(1) + GE(1)		HON09 109
	GL(2)= E1P*GL(2) + GE(2)		HON09 110
	GL(3)= E1P*GL(3) + GE(3)		HON09 111
	GL(4)= E1P*GL(4) + GE(4)		HON09 112
	C		HON09 113
35	C S = (GRAD NU)(RI)(GRAD NU)		HON09 114
	C		HON09 115
	S11=T11*XS(1,9) + T12*XS(1,10) + T13*XS(1,11)		HON09 116
	S12=T11*XS(2,9) + T12*XS(2,10) + T13*XS(2,11)		HON09 117
	S13=T11*XS(3,9) + T12*XS(3,10) + T13*XS(3,11)		HON09 118
40	S14=T11*XS(4,9) + T12*XS(4,10) + T13*XS(4,11)		HON09 119
	S22=T21*XS(2,9) + T22*XS(2,10) + T23*XS(2,11)		HON09 120
	S23=T21*XS(3,9) + T22*XS(3,10) + T23*XS(3,11)		HON09 121
	S24=T21*XS(4,9) + T22*XS(4,10) + T23*XS(4,11)		HON09 122
	S33=T31*XS(3,9) + T32*XS(3,10) + T33*XS(3,11)		HON09 123
45	S34=T31*XS(4,9) + T32*XS(4,10) + T33*XS(4,11)		HON09 124
	S44=T41*XS(4,9) + T42*XS(4,10) + T43*XS(4,11)		HON09 125
	GSQE(1)=E2P*(GSQE(1) - S11) + S11		HON09 126
	GSQE(2)=E2P*(GSQE(2) - S12) + S12		HON09 127
	GSQE(3)=E2P*(GSQE(3) - S13) + S13		HON09 128
50	GSQE(4)=E2P*(GSQE(4) - S14) + S14		HON09 129
	GSQE(5)=E2P*(GSQE(5) - S22) + S22		HON09 130
	GSQE(6)=E2P*(GSQE(6) - S23) + S23		HON09 131
	GSQE(7)=E2P*(GSQE(7) - S24) + S24		HON09 132
	GSQE(8)=E2P*(GSQE(8) - S33) + S33		HON09 133
55	GSQE(9)=E2P*(GSQE(9) - S34) + S34		HON09 134
	GSQE(10)=E2P*(GSQE(10) - S44) + S44		HON09 135
	C		HON09 136
	GSQL(1) = E1P*GSQL(1) + GSQE(1)		HON09 137
	GSQL(2) = E1P*GSQL(2) + GSQE(2)		HON09 138
60	GSQL(3) = E1P*GSQL(3) + GSQE(3)		HON09 139
	GSQL(4) = E1P*GSQL(4) + GSQE(4)		HON09 140
	GSQL(5) = E1P*GSQL(5) + GSQE(5)		HON09 141
	GSQL(6) = E1P*GSQL(6) + GSQE(6)		HON09 142
	GSQL(7) = E1P*GSQL(7) + GSQE(7)		HON09 143
	GSQL(8) = E1P*GSQL(8) + GSQE(8)		HON09 144
65	GSQL(9) = E1P*GSQL(9) + GSQE(9)		HON09 145
	GSQL(10)= E1P*GSQL(10)+ GSQE(10)		HON09 146
	RETURN		HON09 147
	END		HON09 148
			HON09 149

SYMBOLIC REFERENCE MAP (P=1)

ENTRY POINTS
3 ACUM

Figure 15. -Program listing of subroutine ACUM.

Appendix D

VARIABLES	SN	TYPE	RELOCATION					
319	D	REAL	ARRAY DAT	114	DS	REAL	ARRAY	SENSP
473	E1P	REAL	DAT	474	E2P	REAL		DAT
137	F	REAL	ARRAY DAT	1004	GE	REAL	ARRAY	SENSP
1040	GK	REAL	ARRAY SENSP	1010	GL	REAL	ARRAY	SENSP
1014	GSJE	REAL	ARRAY SENSP	1026	GSQL	REAL	ARRAY	SENSP
0	K	INTEGER	F.P.	475	SIGSQ	REAL		DAT
344	S1	REAL		350	S11	REAL		
251	S12	REAL		352	S13	REAL		
353	S14	REAL		345	S2	REAL		
354	S22	REAL		355	S23	REAL		
356	S24	REAL		346	S3	REAL		
357	S33	REAL		360	S34	REAL		
347	S4	REAL		361	S44	REAL		
330	T11	REAL		331	T12	REAL		
332	T13	REAL		333	T21	REAL		
334	T22	REAL		335	T23	REAL		
336	T31	REAL		337	T32	REAL		
340	T33	REAL		341	T41	REAL		
342	T42	REAL		343	T43	REAL		
0	X	REAL	ARRAY DAT	0	XS	REAL	ARRAY	SENSP

COMMON BLOCKS	LENGTH
DAT	318
JENSP	784

STATISTICS	PROGRAM LENGTH	CM LABELED COMMON LENGTH
	3628	242
	21168	1102

Figure 15. -Concluded.

```

SUBROUTINE FH          73/74  OPT=1                                FTN 4.6+439          78/02/14. 08.28.50

1          SUBROUTINE FH(U,Y,X)                                HON09          567
          COMMON/SUBRH/ DT ,D,W,C1,C2                        HON09          568
          DIMENSION X(2)                                     HON09          569
          C          FILTER                                   HON09          570
          C          Y/U= (S*S)/(S*S + 2*D*W*S + W*W)        HON09          571
          C          2 Y=U - X(2)*C2 - X(1)*C1              HON09          572
          X(1)=X(1) + DT*X(2)                                HON09          573
          X(2)=X(2) + DT*Y                                   HON09          574
          RETURN                                             HON09          575
10         END                                              HON09          576

          SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
3 FH

VARIABLES      SN  TYPE          RELOCATION
3 C1           REAL          SUBRH          4 C2           REAL          SUBRH
1 D            REAL          SUBRH          0 DT           REAL          SUBRH
0 U            REAL          F.P.          2 W            REAL          SUBRH
0 X            REAL          ARRAY F.P.    0 Y            REAL          F.P.

STATEMENT LABELS
C 2           INACTIVE

COMMON BLOCKS  LENGTH
SUBRH         5

STATISTICS
PROGRAM LENGTH      168      14
CM LABELED COMMON LENGTH      58      5
    
```

Figure 16. -Program listing of subroutine FH.

Appendix D

```

SUBROUTINE TSIG      74774   OPT=1                FTN 4.6+439      77/12/14. 18.57.02

1      SUBROUTINE TSIG(ETA1,ETA2,UT)
C      UT/INPUT = S*SIGUT/(S*S + 2*DLT*WUT*S + WUT*WUT)
C      INPUT = RANDOM NO WITH G MEAN UNIFORM -0.5 TO 0.5
C      UT1,UT2 STATES IN SECOND ORDER FILTER
5      COMMON/UTEST/DT,SEED,WUT,DT,SIGUT,UT1,UT20,UTMAX,W2UT,TZWUT,
1      UT1,UT2,GAMUTO
2      SEED=AMOD(3125.*SEED,34359738368.)
S=0.291038304567E-10*SEED - 0.5
S=W2UT*UT1 + 1ZWUT*UT2 + GAMUTO*SIGUT*S
10     UT1=UT1 + DT*UT2
UT2=UT2 + S
UT=UT2
IF(ABS(UT).GE.UTMAX) UT=SIGN(UTMAX,UT)
SEED=AMOD(3125.*SEED,34359738368.)
15     S=0.291038304567E-10*SEED - 0.5
ETA1=S
SEED=AMOD(3125.*SEED,34359738368.)
S=0.291038304567E-10*SEED - 0.5
ETA2=S
20     RETURN
END

```

```

HON09 1720
HON09 1721
HON09 1722
HON09 1723
HON09 1724
HON09 1725
HON09 1726
HON09 1727
HON09 1728
HON09 1729
HON09 1730
HON09 1731
HON09 1732
HON09 1733
HON09 1734
HON09 1735
HON09 1736
HON09 1737
HON09 1738
HON09 1739
HON09 1740

```

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
3 TSIG

VARIABLES	SN	TYPE	RELOCATION				
0 DT		REAL	UTEST	3	DUT	REAL	UTEST
0 ETA1		REAL	F.P.	0	ETA?	REAL	F.P.
14 GAMUTO		REAL	UTEST	46	S	REAL	
1 SEED		REAL	UTEST	4	SIGUT	REAL	UTEST
11 TZWUT		REAL	UTEST	0	UT	REAL	F.P.
7 UTMAX		REAL	UTEST	12	UT?	REAL	UTEST
5 UT1		REAL	UTEST	13	UT?	REAL	UTEST
6 UT20		REAL	UTEST	2	WUT	REAL	UTEST
10 W2UT		REAL	UTEST				

INLINE FUNCTIONS	TYPE	ARGS			
ABS	REAL	1	INTRIN	AMOD	PEAL
SIGN	REAL	2	INTRIN		2 INTRIN

STATEMENT LABELS
0 2 INACTIVE

COMMON BLOCKS LENGTH
UTEST 13

STATISTICS			
PROGRAM LENGTH	478	39	
CM LABELED COMMON LENGTH	158	13	

Figure 17. -Program listing of subroutine TSIG.

APPENDIX E
 FLOW CHART FOR INITIALIZATION PORTION
 OF PCMLE SOFTWARE

This appendix consists of the flowcharts for subroutine NRTIC (Fig. 18) and MODEL (Fig. 19).

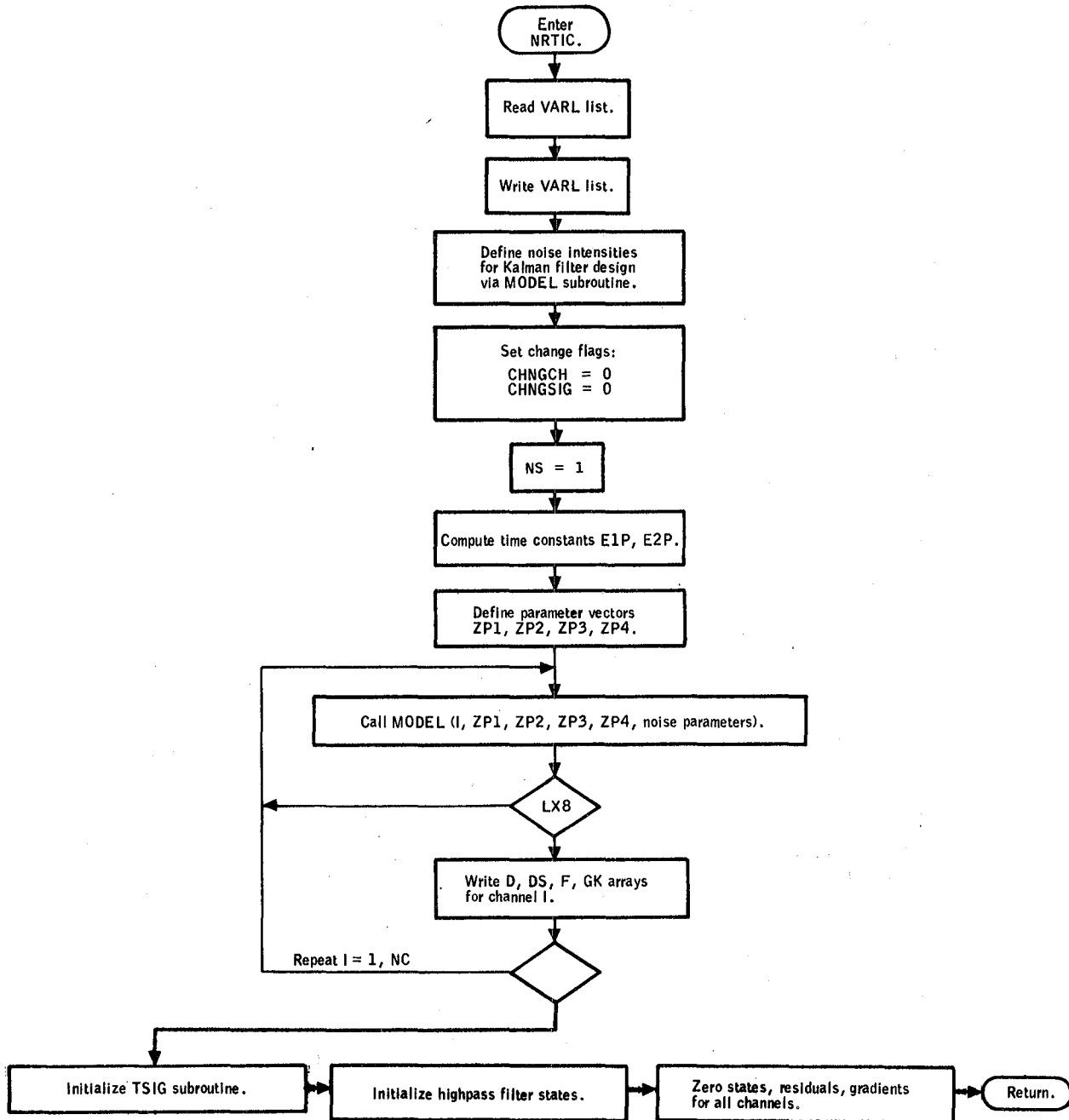


Figure 18. -Flowchart for subroutine NRTIC.

Appendix E

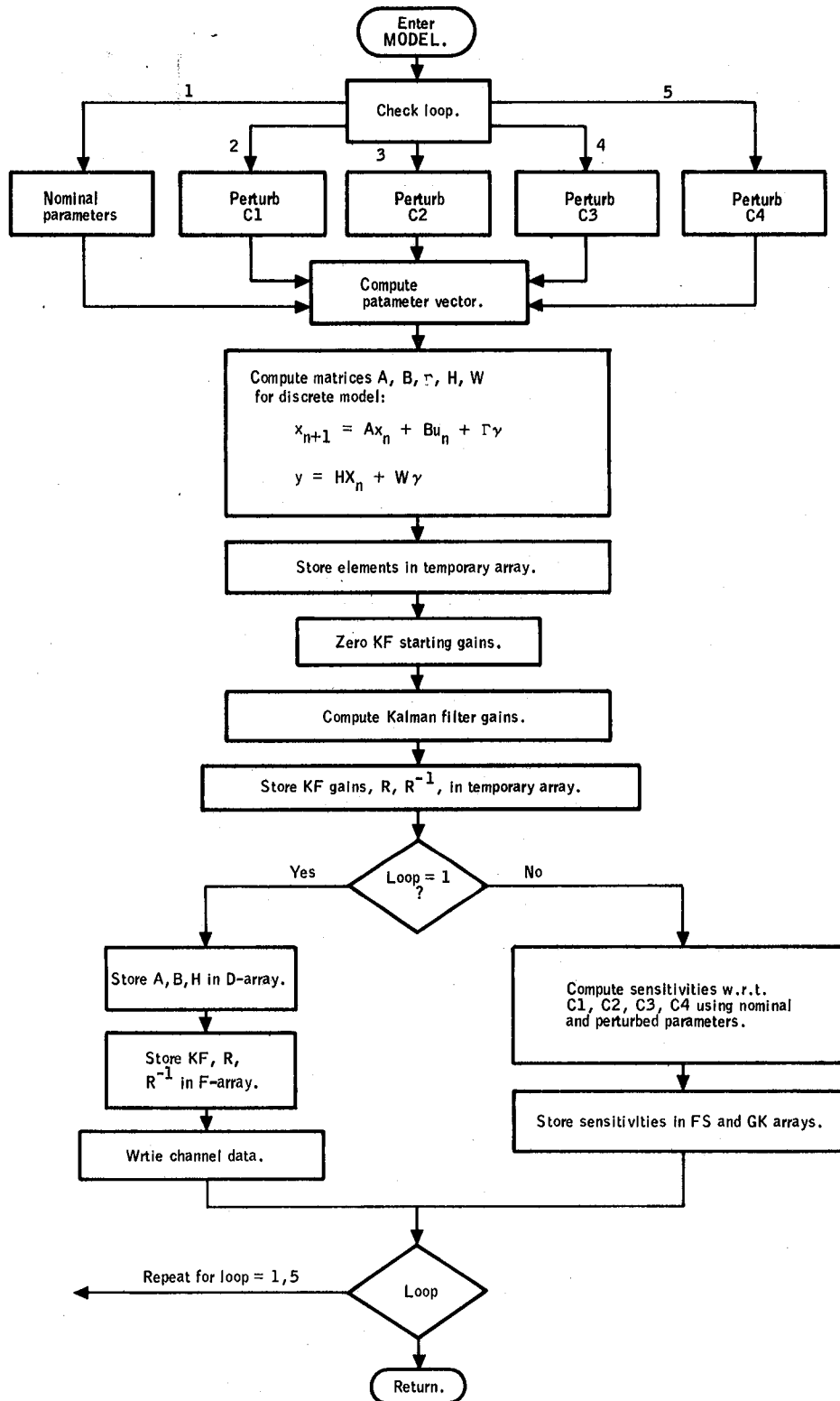


Figure 19. -Flowchart for subroutine MODEL.

APPENDIX F

LISTING OF PCMLE INITIALIZATION SOFTWARE

This appendix contains the program listings of subroutines NRTIC, MODEL, DISC, DIAK, CAL, MP, FHIC, and INPT, as presented in Figures 20 through 27, respectively.

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SUBROUTINE NRTIC      73/74  OPT=1                      FTN 4.6+452      78/04/06. 08.36.47

1      SUBROUTINE NRTIC                                HDN09      1163
      COMMON/PRSWTCH/IPSCH                            HDN09      1164
      COMMON/CI/XC1,XC2,XC3,XC4                      HDN09      1165
      COMMON/OFILE/MF                                HDN09      1166
5      COMMON/VARDAT/UX(55),LX(15)                   HDN09      1167
      COMMON/SENSP/XS(4,19),DS( 5,4,22),GE(4),GL(4),GSQE(10),GSQ(10) HDN09      1168
1      ,GK(5,4,12)                                    HDN09      1169
      COMMON/DAT/X(5,19), F(5,22),D(5,22),E1P,E2P,SIGSQ HDN09      1170
      COMMON/IPIC/  NC,NP,JS,CHNGCH,CHSIG,ANS        HDN09      1171
10     1      ,TPRINT,MODE,SIGUTO,ZP1,ZP2,ZP3,ZP4,TIME,RTJS HDN09      1172
      2      ,RTJG,THRTJG,RTJC,THRTJC,RTJZ,THRTJZ,DTPRIN HDN09      1173
      3      ,ZP1MAX,ZP2MAX,ZP3MAX,ZP4MAX           HDN09      1174
      4      ,ZP1MIN,ZP2MIN,ZP3MIN,ZP4MIN           HDN09      1175
      5      ,ZP( 5,4),GSQLO(4),Y(3),U(2)           HDN09      1176
15     6      ,XVZ(2),XQ(2),XTH(2),XDB(2),XDC(2),PRTIME HDN09      1177
      COMMON/MEAS/YP(3),UP(2)                        HDN09      1178
      COMMON/SUBR/  NX,NR,NN,NRM,EE,ITER,DT,DETR    HDN09      1179
1      ,DUMM(292)                                    HDN09      1180
      COMMON/SUBRH/DTHP,DHP,WHP,C1HP,C2HP           HDN09      1181
20     COMMON/UTEST/DTU,SEED,WUT,DUT,SIGUT,UT10,UT20,UTMAX,W2UT,TZWUT, HDN09      1182
      1      UT1,UT2,GAMUTO                          HDN09      1183
      COMMON/DEVICE/NREAD,MFILE                     HDN09      1184
      COMMON/NOM/THEN,PHIN,UN,VN,WN,UAN,VAN,WAN     HDN09      1185
      DIMENSION GN(2,10)                            HDN09      1186
25     INTEGER CHNGCH,CHSIG                          HDN09      1187
      LOGICAL LX                                    HDN09      1188
      C
      CALL RTHOLD1                                  HDN09      1189
      REWIND 10                                     HDN09      1190
30     READ(10) XS,DS,Gc,GL,GSQE,GSQ,LX,GK          HDN09      1191
      READ(10) X,F,D,E1P,E2P,SIGSQ                  HDN09      1192
      READ(10) NC,NP,JS,CHNGCH,CHSIG,ANS,PRTIME    HDN09      1194
1      ,TPRINT,MODE,SIGUTO,ZP1,ZP2,ZP3,ZP4,TIME,RTJS HDN09      1195
      2      ,RTJG,THRTJG,RTJC,THRTJC,RTJZ,THRTJZ,DTPRIN HDN09      1196
35     3      ,ZP1MAX,ZP2MAX,ZP3MAX,ZP4MAX           HDN09      1197
      4      ,ZP1MIN,ZP2MIN,ZP3MIN,ZP4MIN           HDN09      1198
      5      ,ZP,GSQLO,Y,U,XVZ,XQ,XTH,XDB,XDC       HDN09      1199
      READ(10) DTHP,DHP,WHP,C1HP,C2HP,DTU,SEED,WUT,DUT,SIGUT HDN09      1200
1      ,UT10,UT20,UTMAX,W2UT,TZWUT,UT1,UT2,GAMUTO HDN09      1201
40     READ(10) NREAD,MFILE                          HDN09      1202
      READ(10) UX,LX                                HDN09      1203
      C
      XC1=0.                                        HDN09      1204
      XC2=0.                                        HDN09      1205
45     XC3=0.                                        HDN09      1206
      XC4=0.                                        HDN09      1207
      CALL RTSRT                                    HDN09      1209
      RETURN                                        HDN09      1210
      END                                          HDN09      1211

```

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
1 NRTIC

VARIABLES	SN	TYPE	RELOCATION				
5 ANS		REAL	IPIC	3	CHNGCH	INTEGER	IPIC
4 CHSIG		INTEGER	IPIC	3	C1HP	REAL	SUBRH
4 C2HP		REAL	SUBRH	315	D	REAL	ARRAY DAT

Figure 20. -Program listing of subroutine NRTIC.

Appendix F

7	DETR	REAL		SUBR	1	DHP	REAL		SUBRH
114	DS	REAL	ARRAY	SENSP	6	DT	REAL		SUBR
0	DTHP	REAL		SUBRH	25	DTPRIN	REAL		IPIC
0	DFL	REAL		UTEST	10	DUMM	REAL	ARRAY	SUBR
3	DUT	REAL		UTEST	4	EE	REAL		SUBR
473	E1P	REAL		DAT	474	E2P	REAL		DAT
137	F	REAL	ARRAY	DAT	14	GAMUTO	REAL		UTEST
1004	GE	REAL	ARRAY	SENSP	1040	GK	REAL	ARRAY	SENSP
1010	GL	REAL	ARRAY	SENSP	167	GN	REAL	*UNDEF	
1014	GSQE	REAL	ARRAY	SENSP	1026	GSQL	REAL	ARRAY	SENSP
62	GSQLO	REAL	ARRAY	IPIC	0	IPSCH	INTEGER		PKSWTCH
5	ITER	INTEGER		SUBR	2	JS	INTEGER		IPIC
67	LX	LOGICAL	ARRAY	VARDAT	0	MF	INTEGER		OFILE
1	MFILE	INTEGER		DEVICE	7	MODE	INTEGER		IPIC
0	NC	INTEGER		IPIC	2	NN	INTEGER		SUBR
1	NP	INTEGER		IPIC	1	NR	INTEGER		SUBR
0	NREAD	INTEGER		DEVICE	3	NRM	INTEGER		SUBR
0	NX	INTEGER		SUBR	1	PHIN	REAL		NOM
105	PRTIME	REAL		IPIC	21	RTJC	REAL		IPIC
17	WTJG	REAL		IPIC	16	RTJS	REAL		IPIC
23	RTJZ	REAL		IPIC	1	SEED	REAL		UTEST
475	SIGSQ	REAL		DAT	4	SIGUT	REAL		UTEST
10	SIGUTO	REAL		IPIC	0	THEN	REAL		NOM
22	THRTJC	REAL		IPIC	20	THRTJG	REAL		IPIC
24	THRTJZ	REAL		IPIC	15	TIME	REAL		IPIC
6	TPPRINT	REAL		IPIC	11	TZWUT	REAL		UTEST
71	U	REAL	ARRAY	IPIC	5	UAN	REAL		NOM
2	UN	REAL		NJM	3	UP	REAL	ARRAY	MEAS
7	UTMAX	REAL		UTEST	12	UT1	REAL		UTEST
5	UT10	REAL		UTEST	13	UT2	REAL		UTEST
6	UT20	REAL		UTEST	0	UX	REAL	ARRAY	VARDAT
6	VAN	REAL		NOM	3	VN	REAL		NOM
7	WAN	REAL		NJM	2	WHP	REAL		SUBRH
4	WN	REAL		NJM	2	WUT	REAL		UTEST
10	WZUT	REAL		UTEST	0	X	REAL	ARRAY	DAT
0	XC1	REAL		CI	1	XC2	REAL		CI
2	XC3	REAL		CI	3	XC4	REAL		CI
101	XDB	REAL	ARRAY	IPIC	103	XDC	REAL	ARRAY	IPIC
75	XJ	REAL	ARRAY	IPIC	0	XS	REAL	ARRAY	SENSP
77	XTH	REAL	ARRAY	IPIC	73	XVZ	REAL	ARRAY	IPIC
66	Y	REAL	ARRAY	IPIC	0	YP	REAL	ARRAY	MEAS
36	ZP	REAL	ARRAY	IPIC	11	ZP1	REAL		IPIC
26	ZP1MAX	REAL		IPIC	32	ZP1MIN	REAL		IPIC
12	ZP2	REAL		IPIC	27	ZP2MAX	REAL		IPIC
33	ZP2MIN	REAL		IPIC	13	ZP3	REAL		IPIC
30	ZP3MAX	REAL		IPIC	34	ZP3MIN	REAL		IPIC
14	ZP4	REAL		IPIC	31	ZP4MAX	REAL		IPIC
35	ZP4MIN	REAL		IPIC					

FILE NAMES	MODE			
TAF10	UNFMT			

EXTERNALS	TYPE	ARGS	RTSRT	
RTHOLD1		0		0

COMMON BLOCKS	LENGTH			
PRSWTCH	1			
CI	4			
OFILE	1			
VARDAT	70			
SENSP	784			
DAT	318			
IPIC	70			
MEAS	5			
SUBR	300			
SUBRH	5			
UTEST	13			
DEVICE	2			
NOM	8			

STATISTICS				
PROGRAM LENGTH		2138	139	
CM LABELED COMMON LENGTH		30558	1581	
730008 CM USED				

Figure 20. -Concluded.

Appendix F

SUBROUTINE MODEL	73/74	DPT=1	FTN 4.6+439	7 ^A /02/14. 08.28.50
1			SUBROUTINE MODEL(ZP1,ZP2,ZP3,ZP4,SIGVZ,SIGQ,SIGTH, 1 SIGXG,SIGZG,ICH,INTER)	HON09 835
	C		ICH IS CHANNEL INDICATOR USED FOR DEFINING STORED DATA	HON09 836
			COMMON/VARDAT/LX(50),LX(50)	HON09 837
5			COMMON/DAT/X(5,19), F(5,22),D(5,22),E1P,E2P,SIGSQ	HON09 838
			COMMON/SENSP/XS(4,19),DS(5,4,22),GE(4),GL(4),GSQE(10),GSQL(10)	HON09 839
			1 ,GK(5,4,12)	HON09 840
			COMMON/SUBRH/DTHP,DHP,WHP,C1HP,C2HP	HON09 841
			COMMON /SUBR/	HON09 842
10			1 NX, NR, NN, NRM, EE, ITER, DT, DETR	HON09 843
			2 ,A(4,4),GM(4,6),H(4,4),m(4,6),B(4,2)	HON09 844
			3 ,AKH(4,4),GMKd(4,6),KF(4,4),P(4,4),P1(4,4),R(4,4)	HON09 845
			4 ,RI(4,4),HP(4,4),Q(4,4),WW(4,4),GMW(4,4),SS(4,4),SC(4)	HON09 846
			COMMON/DEVICE/NREAD,MFILE	HON09 847
15			DIMENSION DD(22),FD(22),GIC(4,4)	HON09 848
	C		LOGICAL LX	HON09 849
			REAL KF	HON09 850
			DATA L2/6HA /,L1/6HA - KH/	HON09 851
20			DATA NPD/22/,NPF/22/	HON09 852
			DATA DVBAR/.05/,DC2/.01/,DC3/.01/,DC4/.01/	HON09 853
	C			HON09 854
			DO 60 I=1,NX	HON09 855
			DO 60 J=1,NR	HON09 856
25			GO GIC(I,J)=0.	HON09 857
	GO		CALL INPT(GIC,4,4,NREAD)	HON09 858
			CALL MP(NX,NR,GIC,NX,4MKFIC,MFILE)	HON09 859
	C		LOOP COMPUTES NOMINAL FIRST, THEN SENSITIVITIES	HON09 860
			DO 999 LOOP=1,5	HON09 861
30				HON09 862
	C			HON09 863
	C		DEFINE PARAMETERS	HON09 864
			VBAR=ZP1	HON09 865
			C2=ZP2	HON09 866
			C3=ZP3	HON09 867
35			C4=ZP4	HON09 868
			GO TO (100,200,300,400,500),LOOP	HON09 869
	500		DELT=DC4	HON09 870
			IP=4	HON09 871
			C4=C4 + DC4	HON09 872
40			GO TO 100	HON09 873
	400		DELT=DC3	HON09 874
			IP=3	HON09 875
			C3=C3 + DC3	HON09 876
			GO TJ 100	HON09 877
45			300 DELT=DC2	HON09 878
			IP=2	HON09 879
			C2=C2 + DC2	HON09 880
			GO TO 100	HON09 881
	200		DELT=DVBAR	HON09 882
50			IP=1	HON09 883
			VBAR=VBAR + DVBAR	HON09 884
	100		CONTINUE	HON09 885
	C			HON09 886
			VBS=VBAR*VBAR	HON09 887
55			A(1,1)=-.018-.034*VBS	HON09 888
			A(1,2)=.048*VBS	HON09 889
			A(1,3)=2.4	HON09 890
			A(1,4)=-32.2 + 14.*VBS	HON09 891
			A(2,1)=.18*(VBAR-.75)/0.75	HON09 892
60			IF(VBAR.LT.0.0) A(2,1)=0.16*(.75+VBAR)/0.75	HON09 893
			A(2,2)=-.5	HON09 894
			A(2,3)=0.	HON09 895
			A(2,4)=-180.*VBAR	HON09 896
			A(3,1)=0.	HON09 897
65			A(3,2)=.02*VBAR	HON09 898
			A(3,3)=-1.5 + C4	HON09 899
			A(3,4)=4.*VBAR	HON09 900
			IF(VBAR.LT.0.0) A(3,4)=-4.*VBAR	HON09 901
			A(4,1)=0.	HON09 902
70			A(4,2)=0.	HON09 903
			A(4,3)=1.	HON09 904
			A(4,4)=0.	HON09 905
			B(1,1)=0.12	HON09 906
			B(1,2)=0.	HON09 907
75			B(2,1)=.7*VBAR	HON09 908
			B(2,2)=-7.8 - 3.*VBAR	HON09 909
			B(3,1)=.35 + .12*VBAR + C3	HON09 910
				HON09 911

Figure 21. -Program listing of subroutine MODEL.

Appendix F

	B(3,2)=.24*VBAR + C2	HON09	912
80	B(4,1)=0.	HON09	913
	B(4,2)=0.	HON09	914
	C	HON09	915
	DD 550 I=1,NR	HON09	916
	DD 550 J=1,NX	HON09	917
	550 H(I,J)=0.	HON09	918
95	H(1,2)=1.	HON09	919
	H(2,3)=1.	HON09	920
	H(3,4)=1.	HON09	921
	C	HON09	922
90	DJ 50 I=1,NX	HON09	923
	DD 50 J=1,NX	HON09	924
	W(I,J)=0.	HON09	925
	5C GM(I,J)=0.	HON09	926
	C	HON09	927
95	GM(1,1)=SQRT(2.)*SIGXG	HON09	928
	GM(2,2)=SQRT(2.)*SIGZG	HON09	929
	GM(3,6)=SQRT(2.)*(.02*SIGXG+.01*SIGZG)/A(3,3)	HON09	930
	C	HON09	931
	CALL DISC(INTER)	HON09	932
100	C	HON09	933
	W(1,3)=SIGVZ	HON09	934
	W(2,4)=SIGQ	HON09	935
	W(3,5)=SIGTH	HON09	936
	C	HON09	937
105	C	HON09	938
	DEFINE WORKING DATA ARRAYS	HON09	939
	DD(1)=A(1,1)	HON09	940
	DD(2)=A(1,2)	HON09	941
	DD(3)=A(1,3)	HON09	942
	DD(4)=A(1,4)	HON09	943
	DD(5)=A(2,1)	HON09	944
110	DD(6)=A(2,2)	HON09	945
	DD(7)=A(2,3)	HON09	946
	DD(8)=A(2,4)	HON09	947
	DD(9)=A(3,1)	HON09	948
	DD(10)=A(3,2)	HON09	949
115	DD(11)=A(3,3)	HON09	950
	DD(12)=A(3,4)	HON09	951
	DD(13)=A(4,1)	HON09	952
	DD(14)=A(4,2)	HON09	953
	DD(15)=A(4,3)	HON09	954
120	DD(16)=A(4,4)	HON09	955
	DD(17)=B(1,1)	HON09	956
	DD(18)=B(1,2)	HON09	957
	DD(19)=B(2,1)	HON09	958
	DD(20)=B(2,2)	HON09	959
125	DD(21)=B(3,1)	HON09	960
	DD(22)=B(3,2)	HON09	961
	C	HON09	962
	PROVIDE DIAP STARTING GAINS	HON09	963
130	DD 150 I=1,NX	HON09	964
	DD 150 J=1,NX	HON09	965
	150 KF(I,J)=GIC(I,J)	HON09	966
	C	HON09	967
	CALL DIAP	HON09	968
135	C	HON09	969
	FD(1)=KF(1,1)	HON09	970
	FD(2)=KF(2,1)	HON09	971
	FD(3)=KF(3,1)	HON09	972
	FD(4)=KF(4,1)	HON09	973
140	FD(5)=KF(1,2)	HON09	974
	FD(6)=KF(2,2)	HON09	975
	FD(7)=KF(3,2)	HON09	976
	FD(8)=KF(4,2)	HON09	977
	FD(9)=KF(1,3)	HON09	978
	FD(10)=KF(2,3)	HON09	979
145	FD(11)=KF(3,3)	HON09	980
	FD(12)=KF(4,3)	HON09	981
	IF(DETR.GT.0.0) FD(13)=ALOG(DETR)	HON09	982
	FD(14)=RI(1,1)	HON09	983
150	FD(15)=RI(1,2)	HON09	984
	FD(16)=RI(1,3)	HON09	985
	FD(17)=RI(2,1)	HON09	986
	FD(18)=RI(2,2)	HON09	987
	FD(19)=RI(2,3)	HON09	988
155	FD(20)=RI(3,1)	HON09	989
	FD(21)=RI(3,2)	HON09	990
	FD(22)=RI(3,3)	HON09	991
	C		

Figure 21. -Continued.

Appendix F

		IF(LOOP.NE.1) GO TO 900	HON09	992
	C		HON09	993
160		DO 115 I=1,NPD	HON09	994
		U(ICH,I)=DD(I)	HON09	995
		DO 120 I=1,NPF	HON09	996
		F(ICH,I)=FD(I)	HON09	997
	C		HON09	998
165		IF(LX(9)) GO TO 999	HON09	999
		WRITE(MFILE,1199) ICH	HON09	1000
		WRITE(MFILE,1201) SIGVZ,SIGQ,SIGTH,SIGXG,SIGZG	HON09	1001
		DO 1209 I=1,NX	HON09	1002
		P(I,I) = SORT(P(I,I))	HON09	1003
170		WRITE(MFILE,1202) (P(I,I),I=1,NX)	HON09	1004
		WRITE(MFILE,1205)	HON09	1005
		DO 1208 I=1,NX	HON09	1006
		WRITE(MFILE,1203) (A(I,J),J=1,NX)	HON09	1007
175	C	CALL POLES(4,A,4,SS,M,DT,L2)	HON09	1008
		WRITE(MFILE,1205)	HON09	1009
		DO 1207 I=1,NX	HON09	1010
		WRITE(MFILE,1204) (AKH(I,J),J=1,NX)	HON09	1011
	C	CALL POLES(4,AKH,4,SS,M,DT,L1)	HON09	1012
180		1199 FORMAT(1H1,19HFILTER DATA ICH = ,I2)	HON09	1013
		1201 FORMAT(1X ,11HSTATS IN ,9E12.5)	HON09	1014
		1202 FORMAT(1X ,11HSTATS OUT ,9E12.5)	HON09	1015
		1203 FORMAT(1X,11HA ,4E12.5)	HON09	1016
		1204 FORMAT(1X,11HAKH ,4E12.5)	HON09	1017
		1205 FORMAT(140)	HON09	1018
185	C		HON09	1019
		GO TO 999	HON09	1020
	C		HON09	1021
		900 CONTINUE	HON09	1022
190	C	SENSITIVITIES	HON09	1023
		DO 910 I=1,NPD	HON09	1024
		OS(ICH,IP,I) = (DD(I) - D(ICH,I))/DELT	HON09	1025
	C	GAIN SENSITIVITIES	HON09	1026
		DO 920 I=1,12	HON09	1027
195		GK(ICH,IP,I)=(FD(I) - F(ICH,I))/DELT	HON09	1028
		999 CONTINUE	HON09	1029
	C		HON09	1030
		RETURN	HON09	1031
		END	HON09	1032

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
3 MODEL

VARIABLES	SN	TYPE	RELOCATION						
10	A	REAL	ARRAY	SUBR	140	AKH	REAL	ARRAY	SUBR
130	B	REAL	ARRAY	SUBR	3	C1HP	REAL		SUBRH
677	C2	REAL			4	C2HP	REAL		SUBRH
700	C3	REAL			701	C4	REAL		
315	D	REAL	ARRAY	DAT	540	DC2	REAL		
541	DC3	REAL			542	DC4	REAL		
705	DD	REAL	ARRAY		702	DELT	REAL		
7	DETF	REAL		SUBR	1	DHP	REAL		SUBRH
114	DS	REAL	ARRAY	SENSP	6	DT	REAL		SUBR
0	DTHP	REAL		SUBRH	537	DVBAR	REAL		
4	EE	REAL		SUBR	473	E1P	REAL		DAT
474	E2P	REAL		DAT	137	F	REAL	ARRAY	DAT
733	FD	REAL	ARRAY		1004	GE	REAL	ARRAY	SENSP
761	GIC	REAL	ARRAY		1040	GK	REAL	ARRAY	SENSP
1010	GL	REAL	ARRAY	SENSP	30	GM	REAL	ARRAY	SUBR
160	GMLW	REAL	ARRAY	SUBR	410	GMW	REAL	ARRAY	SUBR
1014	GSQE	REAL	ARRAY	SENSP	1026	GSQI	REAL	ARRAY	SENSP
60	H	REAL	ARRAY	SUBR	330	HP	REAL	ARRAY	SUBR
673	I	INTEGER			0	ICH	INTEGER		F.P.
703	IP	INTEGER			5	ITER	INTEGER		SUBR
674	J	INTEGER			210	KF	REAL	ARRAY	SUBR
675	LOOP	INTEGER			62	LX	LOGICAL	ARRAY	VARDAT
534	L1	INTEGER			533	L2	INTEGER		
1	MFILE	INTEGER		DFVICE	2	NN	INTEGER		SUBR
535	NPD	INTEGER			536	NPF	INTEGER		
1	NR	INTEGER		SUBR	0	NREAD	INTEGER		DEVICE
3	NRM	INTEGER		SUBR	0	NTER	INTEGER		F.P.

Figure 21. -Continued.

Appendix F

0	NX	INTEGER		SUBR	230	P	REAL	ARRAY	SUBR		
250	P1	REAL	ARRAY	SUBR	350	Q	REAL	ARRAY	SUBR		
270	R	REAL	ARRAY	SUBR	310	RI	REAL	ARRAY	SUBR		
450	SC	REAL	APRAY	SUBR	0	SIGO	REAL		SUBR		
475	SIGSO	REAL		DAT	0	SIGTH	REAL		SUBR	F.P.	
0	SIGVZ	REAL		F.P.	0	SIGXG	REAL		SUBR	F.P.	
C	SIGZS	REAL		F.P.	430	SS	REAL	ARRAY	SUBR	F.P.	
0	UX	REAL	ARRAY	VARDAT	676	VBAR	REAL				
704	VBS	REAL			100	W	REAL	ARRAY	SUBR		
2	WHP	REAL		SUBRH	370	WW	REAL	ARRAY	SUBR		
0	X	REAL	ARRAY	FAT	0	XS	REAL	ARRAY	SENSP		
0	ZP1	REAL		F.P.	0	ZP2	REAL		SUBR	F.P.	
0	ZP3	REAL		F.P.	0	ZP4	REAL		SUBR	F.P.	

EXTERNALS	TYPE	ARGS	DIAG	REAL	LIBRARY
ALOG	REAL	1	LIBRARY		0
DISC		1	INPT		4
MP		6	SQRT	REAL	1

STATEMENT LABELS										
C	50			0	60			77	100	
G	115			0	120			0	150	
73	200			66	300			61	400	
54	500			0	550			457	900	
C	910			0	920			512	999	
607	1199	FMT		613	1201	FMT		617	1202	FMT
623	1203	FMT		627	1204	FMT		633	1205	FMT
0	1207			0	1208			0	1209	

LOOPS	LABEL	INDEX	FROM-TO	LENGTH	PROPERTIES
16	50	* I	23 25	138	INSTACK NOT INNER
23	60	J	24 25	28	
35	999	* LOOP	29 195	4608	EXT REFS NOT INNER
150	550	* I	82 84	138	NOT INNER
155	550	J	83 84	28	INSTACK
166	50	* I	89 92	138	NOT INNER
172	50	J	90 92	38	INSTACK
265	150	* I	129 131	138	NOT INNER
271	150	J	130 131	38	INSTACK
350	115	I	160 161	38	INSTACK
360	120	I	162 163	38	INSTACK
371	1209	* I	168 169	78	EXT REFS
403		* I	170 170	108	EXT REFS
417	1208	* I	172 173	178	EXT REFS NOT INNER
422		* J	173 173	108	EXT REFS
440	1207	* I	176 177	178	EXT REFS NOT INNER
443		* J	177 177	108	EXT REFS
467	910	I	190 191	58	INSTACK
504	920	I	193 194	58	INSTACK

COMMON	BLOCKS	LENGTH
	VARDAT	100
	DAT	318
	SENSP	784
	SUBRH	5
	SUBR	300
	DEVICE	2

STATISTICS			
PROGRAM LENGTH		19368	542
CM LABELED COMMON LENGTH		27458	1509

Figure 21. -Concluded.

Appendix F

SUBROUTINE DISC	73/74	OPT=1	FTN 4.6+439	78/02/14. 08.28.50
1	SUBROUTINE DISC(NTFR)			HON09 503
	COMMON /SUBR/			HON09 504
1	NX,NR,NN,NRM,EE,ITER,DT,DFTR			HON09 505
2	,A(4,4),GM(4,6),H(4,4),W(4,6),B(4,2)			HON09 506
3	,AKH(4,4),GMKW(4,6),KF(4,4),P(4,4),P1(4,4),R(4,4)			HON09 507
4	,RI(4,4),HP(4,4),Q(4,4),WW(4,4),GMW(4,4),SS(4,4),SC(4)			HON09 508
	REAL KF			HON09 509
	DATA NU/2/			HON09 510
C	P, P1, R, KI USED AS WORKING ARRAYS			HON09 511
10	A, B AND GM ARE REPLACED WITH DISCRETE VERSION			HON09 512
C				HON09 513
C	P1=I + (A*DT) + ((A*DT)**2)/2 + . . .			HON09 514
C				HON09 515
C	P=DT + ((A*DT)**2)/2 + . . .			HON09 516
15	B=P*B			HON09 517
C	GM=P*GM/SQRT(DT)			HON09 518
C				HON09 519
	DO 1 I=1,NX			HON09 520
	DO 1 J=1,NX			HON09 521
20	P(I,J)=0.			HON09 522
	R(I,J)=0.			HON09 523
	P1(I,J)=0.			HON09 524
	R(I,I)=1.			HON09 525
	P1(I,I)=1.			HON09 526
25	DO 100 II=1,NTFR			HON09 527
	DO 10 I=1,NX			HON09 528
	DO 10 J=1,NX			HON09 529
10	RI(I,J)=P(I,J)*DT/FLD(II)			HON09 530
	DO 11 I=1,NX			HON09 531
	DO 11 J=1,NX			HON09 532
30	11 P(I,J)=P(I,J) + RI(I,J)			HON09 533
	DO 12 I=1,NX			HON09 534
	DO 12 J=1,NX			HON09 535
	R(I,J)=0.			HON09 536
35	DO 12 K=1,NX			HON09 537
	12 R(I,J)=R(I,J) + A(I,K)*RI(K,J)			HON09 538
	DO 13 I=1,NX			HON09 539
	DO 13 J=1,NX			HON09 540
	13 P1(I,J)=P1(I,J) + R(I,J)			HON09 541
40	100 CONTINUE			HON09 542
C				HON09 543
	DO 15 I=1,NX			HON09 544
	DO 15 J=1,NX			HON09 545
45	15 A(I,J)=P1(I,J)			HON09 546
	S1=1./SQRT(DT)			HON09 547
	DO 16 I=1,NX			HON09 548
	DO 16 J=1,NN			HON09 549
	GMKW(I,J)=0.			HON09 550
	DO 16 K=1,NX			HON09 551
50	16 GMKW(I,J)=GMKW(I,J) + P(I,K)*GM(K,J)			HON09 552
	DO 18 I=1,NX			HON09 553
	DO 18 J=1,NN			HON09 554
	18 GM(I,J)=GMKW(I,J)*S1			HON09 555
	DO 17 I=1,NX			HON09 556
55	DO 17 J=1,NU			HON09 557
	P1(I,J)=0.			HON09 558
	DO 17 K=1,NX			HON09 559
	17 P1(I,J)=P1(I,J) + P(I,K)*B(K,J)			HON09 560
	DO 19 I=1,NX			HON09 561
60	DO 19 J=1,NU			HON09 562
	19 B(I,J)=P1(I,J)			HON09 563
	RETURN			HON09 564
	END			HON09 565

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
3 DISC

VARIABLES	SN	TYPE	RELOCATION					
10 A		REAL	ARRAY	SUBR	140	AKH	REAL	SUBR
130 B		REAL	ARRAY	SUBR	7	DETR	REAL	SUBR
6 DT		REAL		SUBR	4	EE	REAL	SUBR
30 GM		REAL	ARRAY	SUBR	160	GMKW	REAL	SUBR
410 GMW		REAL	ARRAY	SUBR	60	H	REAL	SUBR

Figure 22. -Program listing of subroutine DISC.

Appendix F

330	4P	REAL	ARRAY	SUBR	264	I	INTEGER		
266	II	INTEGER			5	ITER	INTEGER		SUBR
265	J	INTEGER			267	K	INTEGER		
210	KF	REAL	ARRAY	SUBR	2	NN	INTEGER		SUBR
1	NR	INTEGER		SUBR	3	NPM	INTEGER		SUBR
0	NTDR	INTEGER		F.P.	262	NU	INTEGER		
0	NX	INTEGER		SUBR	230	P	REAL	ARRAY	SUBR
250	P1	REAL	ARRAY	SUBR	350	Q	REAL	ARRAY	SUBR
270	Q	REAL	ARRAY	SUBR	310	RI	REAL	ARRAY	SUBR
450	SC	REAL	ARRAY	SUBR	430	SS	REAL	ARRAY	SUBR
270	SI	REAL			100	W	REAL	ARRAY	SUBR
370	W	REAL	ARRAY	SUBR					
EXTERNALS									
	SQPT	REAL		1 LIBRARY					
INLINE FUNCTIONS									
	FLOAT	REAL		1 INTRIN					
STATEMENT LABELS									
0	1				0	10			0 11
0	12				0	13			0 15
0	16				0	17			0 18
0	19				0	100			
LOGPS LABEL INDEX FROM-TO LENGTH PROPERTIES									
16	1	* I	18 24	168		NOT INNER			
23	1	J	19 24	58	INSTACK				
35	100	* II	25 40	1018		NOT INNER			
36	10	* I	26 28	168		NOT INNER			
45	10	J	27 28	48	INSTACK				
55	11	* I	29 31	148		NOT INNER			
62	11	J	30 31	38	INSTACK				
72	12	* I	32 36	258		NOT INNER			
73	12	* J	33 36	218		NOT INNER			
105	12	K	35 36	48	INSTACK				
120	13	* I	37 39	148		NOT INNER			
125	13	J	38 39	38	INSTACK				
137	15	* I	42 44	138		NOT INNER			
143	15	J	43 44	38	INSTACK				
156	16	* I	46 50	258		NOT INNER			
157	16	* J	47 50	218		NOT INNER			
171	16	K	49 50	48	INSTACK				
204	18	* I	51 53	138		NOT INNER			
210	18	J	52 53	48	INSTACK				
220	17	* I	54 58	258		NOT INNER			
221	17	* J	55 58	218		NOT INNER			
233	17	K	57 58	48	INSTACK				
245	19	* I	59 61	138		NOT INNER			
252	19	J	60 61	38	INSTACK				
COMMON BLOCKS									
	SUBR			300					
STATISTICS									
	PROGRAM LENGTH		2738	187					
	COMMON LABELED COMMON LENGTH		4543	300					

Figure 22. -Concluded.

Appendix F

SUBROUTINE DIAK	73/74 (PT=1)	FTN 4.6+439	78/02/14. 08.28.50
1	SUBROUTINE DIAK		HON09 383
	COMMON / SUBR /		HON09 384
	1 NX, NR, NN, NRM, EE, ITER, DT, DETR		HON09 385
	2 ,A(4,4), GM(4,6), H(4,4), W(4,6), B(4,2)		HON09 386
5	3 ,AK(4,4), GMKW(4,6), KF(4,4), P(4,4), P1(4,4), R(4,4)		HON09 387
	4 ,RI(4,4), HP(4,4), Q(4,4), WW(4,4), GMB(4,4), SS(4,4), SC(4)		HON09 388
	REAL KF		HON09 389
	C		HON09 390
	DO 101 I=1, NX		HON09 391
10	DO 101 J=1, NX		HON09 392
	101 P(I,J)=0.		HON09 393
	C GMW*, WW*		HON09 394
	DO 1 I=1, NR		HON09 395
	DO 2 J=1, NX		HON09 396
15	S=0.		HON09 397
	DO 3 K=1, NN		HON09 398
	3 S = S + GM(J,K)*W(I,K)		HON09 399
	2 GMW(J,I) = S		HON09 400
	DO 1 J=I, NR		HON09 401
20	S=0.		HON09 402
	DO 4 K=1, NN		HON09 403
	4 S = S + W(I,K)*W(J,K)		HON09 404
	WW(I,J) = S		HON09 405
	1 WW(J,I) = S		HON09 406
25	IT = 0		HON09 407
	C		HON09 408
	800 CONTINUE		HON09 409
	E1 = 0.		HON09 410
	IT = IT + 1		HON09 411
30	C		HON09 412
	C AKH = A - KH, GMKW = GM - KW, P1 = GMKW GMKW*		HON09 413
	DO 10 I=1, NX		HON09 414
	DO 12 J=1, NX		HON09 415
	S = A(I,J)		HON09 416
35	DO 14 K=1, NR		HON09 417
	14 S = S - KF(I,K)*H(K,J)		HON09 418
	12 AKH(I,J) = S		HON09 419
	DO 16 J=1, NN		HON09 420
	S = GM(I,J)		HON09 421
40	DO 18 K=1, NR		HON09 422
	18 S = S - KF(I,K)*W(K,J)		HON09 423
	16 GMKW(I,J) = S		HON09 424
	DO 10 J=1, I		HON09 425
	S=0.		HON09 426
45	DO 20 K=1, NN		HON09 427
	20 S = S + GMKW(I,K)*GMKW(J,K)		HON09 428
	P1(I,J) = S		HON09 429
	10 P1(J,I) = S		HON09 430
	C		HON09 431
50	C P = AKH P AKH* + GMKW GMKW*		HON09 432
	CALL CAL		HON09 433
	C		HON09 434
	C KF = (APH* + GMW*)(HPPH* + WW*)-1		HON09 435
	DO 36 I=1, NR		HON09 436
55	DO 32 J=1, NX		HON09 437
	S=C.		HON09 438
	DO 34 K=1, NX		HON09 439
	34 S = S + H(I,K)*P1(K,J)		HON09 440
	32 HP(I,J) = S		HON09 441
60	DO 36 J=1, I		HON09 442
	S = WW(I,J)		HON09 443
	DO 38 K=1, NX		HON09 444
	38 S = S + HP(I,K)*H(J,K)		HON09 445
	RI(I,J) = S		HON09 446
65	36 RI(J,I) = S		HON09 447
	C		HON09 448
	IF(NR .GT. 1) GO TO 333		HON09 449
	DETR = RI(1,1)		HON09 450
	RI(1,1) = 1./RI(1,1)		HON09 451
70	GO TO 334		HON09 452
	333 CONTINUE		HON09 453
	DO 39 I=1, NR		HON09 454
	DO 39 J=1, NR		HON09 455
75	39 R(I,J)=RI(I,J)		HON09 456
	C CALL T3INVR(1,J,NR,NR,RI,NRM,SC,DETR)		HON09 457
	C EXPLICIT 3x3 INVERSE		HON09 458
	DETR=R(1,1)*(P(2,2)*R(3,3)-R(3,2)*R(2,3))		HON09 459

Figure 23. -Program listing of subroutine DIAK.

Appendix F

		1 = P(2,1)*R(1,2)*R(3,3)-R(3,2)*R(1,3))	HON09	460
		2 + P(3,1)*R(1,2)*R(2,3)-R(2,2)*R(1,3))	HON09	461
90		IF(DETP.EQ.0.0) STDP 31	HON09	462
		RI(1,1)=(R(2,2)*R(3,3)-R(3,2)*R(2,3))/DETR	HON09	463
		RI(1,2)=(R(3,2)*R(1,3)-R(1,2)*R(3,3))/DETR	HON09	464
		RI(1,3)=(R(1,2)*R(2,3)-R(2,2)*R(1,3))/DETR	HON09	465
		RI(2,1)=(R(3,1)*R(2,3)-R(2,1)*R(3,3))/DETR	HON09	466
95		RI(2,2)=(R(1,1)*R(3,3)-R(1,3)*R(3,1))/DETR	HON09	467
		RI(2,3)=(R(2,1)*R(1,3)-R(1,1)*R(2,3))/DETR	HON09	468
		RI(3,1)=(R(2,1)*R(3,2)-R(3,1)*R(2,2))/DETR	HON09	469
		RI(3,2)=(R(3,1)*R(1,2)-R(1,1)*R(3,2))/DETR	HON09	470
90	C	RI(3,3)=(R(1,1)*R(2,2)-R(2,1)*R(1,2))/DETR	HON09	471
		334 CONTINUE	HON09	472
	C	DO 46 I=1,NX	HON09	473
		DO 30 J=1,NX	HON09	474
95		S = P(I,J)	HON09	475
		IF(S.EQ.0) GO TO 31	HON09	476
		S = ABS((P1(I,J)-S)/S)	HON09	477
		IF(E1.LT.S) E1 = S	HON09	478
100		31 P(I,J) = P1(I,J)	HON09	479
		30 P(J,I) = P(I,J)	HON09	480
		DO 42 J=1,NR	HON09	481
		S = GMW(I,J)	HON09	482
		DO 44 K=1,NX	HON09	483
105		44 S = S + A(I,K)*HP(J,K)	HON09	484
		42 SC(J) = S	HON09	485
		DO 46 J=1,NR	HON09	486
		S=0.	HON09	487
		DO 48 K=1,NR	HON09	488
110		48 S = S + SC(K)*PI(K,J)	HON09	489
		46 KF(I,J) = S	HON09	490
	C	IF(IT.LE.1) GO TO 800	HON09	491
		IF(E1.LT.EE) GO TO 220	HON09	492
115		IF(IT.GT.ITER) GO TO 220	HON09	493
		GO TO 800	HON09	494
		220 CONTINUE	HON09	495
	C	RETURN	HON09	496
		END	HON09	497
			HON09	498
			HON09	499
			HON09	500
			HON09	501

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS

1 DIAK

VARIABLES	SN	TYPE	RELOCATION						
10	A	REAL	ARRAY	SUBR	140	AKH	REAL	ARRAY	SUBR
130	J	REAL	ARRAY	SUBR	7	DETR	REAL	ARRAY	SUBR
6	DT	REAL		SUBR	4	EE	REAL		SUBR
453	E1	REAL			30	GM	REAL	ARRAY	SUBR
160	GMKW	REAL	ARRAY	SUBR	410	GMW	REAL	ARRAY	SUBR
60	H	REAL	ARRAY	SUBR	330	HP	REAL	ARRAY	SUBR
446	I	INTEGER			452	IT	INTEGER		
5	ITER	INTEGER		SUBR	447	J	INTEGER		
451	K	INTEGER			210	KF	REAL	ARRAY	SUBR
2	NN	INTEGER		SUBR	1	NR	INTEGER		SUBR
3	NRM	INTEGER		SUBR	0	NX	INTEGER		SUBR
230	P	REAL	ARRAY	SUBR	250	P1	REAL	ARRAY	SUBR
350	Q	REAL	ARRAY	SUBR	270	R	REAL	ARRAY	SUBR
310	RI	REAL	ARRAY	SUBR	450	S	REAL		
450	SC	REAL	ARRAY	SUBR	430	SS	REAL	ARRAY	SUBR
100	W	REAL	ARRAY	SUBR	370	WW	REAL	ARRAY	SUBR

EXTERNALS
CAL TYPE ARGS
0

INLINE FUNCTIONS
ABS REAL TYPE ARGS
1 INTRIN

Figure 23. -Continued.

Appendix F

STATEMENT LABELS

```

0 1
0 4
0 14
0 20
0 32
0 3F
0 44
0 101
343 334
    
```

```

0 2
0 10
0 16
0 30
0 34
0 39
0 46
442 220
72 800
    
```

```

0 3
0 12
0 18
361 31
0 36
0 42
0 48
260 333
    
```

LOOPS	LABEL	INDEX	FROM-TO	LENGTH	PROPERTIES
3	101	* I	9 11	138	NOT INNER
10	101	J	10 11	28	INSTACK
17	1	* I	13 24	528	NOT INNER
20	2	* J	14 14	228	NCT INNER
30	3	K	15 17	48	INSTACK
43	1	* J	19 24	238	NOT INNER
53	4	K	21 22	48	INSTACK
75	10	* I	32 49	1008	NOT INNER
76	12	* J	33 37	248	NCT INNER
110	14	K	35 36	48	INSTACK
123	16	* J	38 42	248	NOT INNER
135	18	K	40 41	48	INSTACK
150	10	* J	43 48	238	NOT INNER
160	20	K	45 46	48	INSTACK
200	36	* I	54 65	538	NOT INNER
201	32	* J	55 59	228	NOT INNER
211	34	K	57 58	48	INSTACK
224	36	* J	60 65	258	NOT INNER
236	38	K	62 63	48	INSTACK
261	39	* I	72 74	138	NOT INNER
265	39	J	73 74	38	INSTACK
344	46	* I	93 110	708	NOT INNER
354	30	J	94 100	108	DPT
366	42	* J	101 105	238	NOT INNER
400	44	K	103 104	48	INSTACK
412	46	* J	106 110	208	NOT INNER
420	48	K	108 109	48	INSTACK

```

COMMON BLOCKS   LENGTH
SUBR             300
    
```

```

STATISTICS
PROGRAM LENGTH           4568      302
CM LABELED COMMON LENGTH 4548      300
    
```

Figure 23. -Concluded.

Appendix F

DEPARTMENT	CAL	73/74	CPT=1	FTN 4.6+439	78/02/14. 08.28.50
1	SUBROUTINE CAL				HON09 181
	COMMON / SUBR /				HON09 182
	1 NX, NR, NN, NRM, EE, ITER, DT, DETR				HON09 183
	2 ,A(4,4), GM(4,6), H(4,4), W(4,6), B(4,2)				HON09 184
5	3 ,AKH(4,4), GMKW(4,6), KF(4,4), P(4,4), P1(4,4), R(4,4)				HON09 185
	4 ,RI(4,4), HP(4,4), Q(4,4), WW(4,4), GMW(4,4), SS(4,4), SC(4)				HON09 186
	PEAL KF				HON09 187
	C				HON09 188
	C Q = AKF				HON09 189
10	DO 10 I=1, NX				HON09 190
	DO 10 J=1, NX				HON09 191
	10 J(I, J) = AKH(I, J)				HON09 192
	IT = 0				HON09 193
	C				HON09 194
15	800 CONTINUE				HON09 195
	E1 = G.				HON09 196
	IT = IT + 1				HON09 197
	C				HON09 198
	C P1 = Q P1 Q* + P1				HON09 199
20	DO 20 I=1, NX				HON09 200
	DO 20 J=1, NX				HON09 201
	S=0.				HON09 202
	DO 24 K=1, NX				HON09 203
	24 S = S + Q(I, K)*P1(K, J)				HON09 204
25	20 SS(I, J) = S				HON09 205
	DO 26 I=1, NX				HON09 206
	DO 26 J=1, NX				HON09 207
	S=0.				HON09 208
	DO 28 K=1, NX				HON09 209
30	28 S = S + SS(I, K)*Q(J, K)				HON09 210
	S3 = P1(I, J)				HON09 211
	IF(S3 .EQ. 0) GO TO 30				HON09 212
	S3 = ARS(S/S3)				HON09 213
	IF(.LT. S3) S1 = S3				HON09 214
35	30 P1(I, J) = P1(I, J) + S				HON09 215
	26 P1(J, I) = P1(I, J)				HON09 216
	C				HON09 217
	C Q = QQ				HON09 218
	S3 = 0.				HON09 219
40	DO 40 I=1, NX				HON09 220
	DO 40 J=1, NX				HON09 221
	S=0.				HON09 222
	DO 42 K=1, NX				HON09 223
	42 S = S + Q(I, K)*Q(K, J)				HON09 224
45	40 SS(I, J) = S				HON09 225
	DO 44 I=1, NX				HON09 226
	DO 44 J=1, NX				HON09 227
	44 J(I, J) = SS(I, J)				HON09 228
	45 S3 = S2 + SS(I, I)				HON09 229
50	C				HON09 230
	IF(IT .LE. 1) GO TO 800				HON09 231
	IF(S3 .GT. NX) GO TO 230				HON09 232
	IF(E1 .LT. EE) GO TO 220				HON09 233
	IF(IT .GT. ITER) GO TO 220				HON09 234
55	GO TO 800				HON09 235
	C				HON09 236
	220 CONTINUE				HON09 237
	RETURN				HON09 238
	230 CONTINUE				HON09 239
60	STOP 41				HON09 240
	END				HON09 241

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
1 CAL

VARIABLES	SN	TYPE	RELOCATION						
10 A		REAL	ARRAY	SUBR	140	AKH	REAL	ARRAY	SUBR
130 B		REAL	ARRAY	SUBR	7	DETR	REAL	SUBR	SUBR
6 DT		REAL		SUBR	4	EE	REAL	SUBR	SUBR
173 e1		REAL			30	GM	REAL	ARRAY	SUBR
160 GMKW		REAL	ARRAY	SUBR	410	GMW	REAL	ARRAY	SUBR
60 H		REAL	ARRAY	SUBR	330	HP	REAL	ARRAY	SUBR
170 I		INTEGER			172	IT	INTEGER		

Figure 24. - Program listing of subroutine CAL.

Appendix F

5	ITFR	INTEGER	SUBR	171	J	INTEGER		
175	K	INTEGER		210	KF	REAL	ARRAY	SUBR
2	NN	INTEGER	SUBR	1	NR	INTEGER		SUBR
3	NFM	INTEGER	SUBR	0	NX	INTEGER		SUBR
230	P	REAL	ARRAY	250	P1	REAL	ARRAY	SUBR
350	Q	REAL	ARRAY	270	R	REAL	ARRAY	SUBR
310	RI	REAL	ARRAY	174	S	REAL		
450	SL	REAL	ARRAY	430	SS	REAL	ARRAY	SUBR
176	S3	REAL		100	W	REAL	ARRAY	SUBR
370	NW	REAL	ARRAY					

INLINE FUNCTIONS	TYPE	ARGS					
ABS	REAL	1	INTRIN				

STATEMENT LABELS							
C	10			0	20		0 24
C	26			0	28		76 30
O	40			0	42		0 44
O	45			166	220		167 230
17	860						

LOOPS	LABEL	INDEX	FROM-TO	LENGTH	PROPERTIES	
3	10	* I	10 12	138		NOT INNER
7	10	J	11 12	38	INSTACK	
22	20	* I	20 25	258		NOT INNER
23	20	* J	21 25	228		NOT INNER
33	24	K	23 24	48	INSTACK	
50	26	* I	26 36	408		NOT INNER
52	26	* J	27 36	338		NOT INNER
62	28	K	29 30	48	INSTACK	
112	40	* I	40 45	258		NOT INNER
113	40	* J	41 45	228		NOT INNER
123	42	K	43 44	48	INSTACK	
140	45	* I	46 49	168		NOT INNER
144	44	J	47 48	38	INSTACK	

COMMON BLOCKS	LENGTH	
SUBR	300	

STATISTICS			
PRGGRAM LENGTH	2018	129	
CM LABELED COMMON LENGTH	4548	300	

Figure 24. -Concluded.

SUBROUTINE MP	73/74	OPT=1	FTN 4.6+439	78/02/14. 08.28.50
---------------	-------	-------	-------------	--------------------

1	SUBROUTINE MP(N1,N2,A,NP,LABEL,NO)		HON09	1034
	DIMENSION A(NP,1)		HON09	1035
	IF(N1.EQ.1) GO TO 20		HON09	1036
	IF(N2.EQ.1) GO TO 30		HON09	1037
5	WRITE(NO,600) LABEL		HON09	1038
	600 FJRMAT(140,7HMATRIX ,A4)		HON09	1039
	DO 100 I=1,N1		HON09	1040
	100 WRITE(NO,601) (A(I,J),J=1,N2)		HON09	1041
	601 FORMAT(1X,10E11.4)		HON09	1042
10	RETURN		HON09	1043
	20 WRITE(NO,610) LABEL		HON09	1044
	610 FORMAT(1H0,12HROW VECTOR ,A4)		HON09	1045
	WRITE(NO,601)(A(1,I),I=1,N2)		HON09	1046
	RETURN		HON09	1047
15	30 WRITE(NO,620) LABEL		HON09	1048
	620 FORMAT(1H0,12HCOL VECTOR ,A4)		HON09	1049
	WRITE(NO,601)(A(I,1),I=1,N1)		HON09	1050
	RETURN		HON09	1051
	END		HON09	1052

SYMBOLIC REFERENCE MAP (R=1)

Figure 25. -Program listing of subroutine MP.

Appendix F

```

ENTRY POINTS
3 MP

VARIABLES      SN  TYPE      RELOCATION
0 A            REAL      APRAY   F.P.      150 I      INTEGER
151 J          INTEGER   F.P.      0 LABEL   INTEGER
0 NM          INTEGER   F.P.      0 NO      INTEGER
C N1          INTEGER   F.P.      0 N2      INTEGER
                                     F.P.      F.P.      F.P.

STATEMENT LABELS
45 20          64 30
102 600       FMT      113 601   FMT      0 100
140 620       FMT                                     122 610   FMT

LOOPS  LABEL   INDEX   FROM-TO   LENGTH   PROPERTIES
25 100   * I      7 8      208      EXT REFS NOT INNER
30      * J      8 8      118      EXT REFS
52      * I      13 13   108      EXT REFS

STATISTICS
PROGRAM LENGTH      1708   120
  
```

Figure 25. -Concluded.

```

SUBROUTINE FHIC      73/74   OPT=1      FTN 4.6+439      78/02/14. 08.28.50

1      SUBROUTINE FHIC(U,Y,X)
      COMMON/SUBRH/ DT ,D,w,C1,C2
      DIMENSION X(2)
      1 C2=2.*D*w
      5 C1=w*w
      X(1)=U/C1
      X(2)=0.
      Y=0.
      RETURN
10     END

      SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
3 FHIC

VARIABLES      SN  TYPE      RELOCATION
3 C1           REAL      SUBRH    4 C2      REAL
1 J            REAL      SUBRH    0 DT      REAL
0 U            REAL      F.P.     2 W       REAL
0 X            REAL      ARRAY    F.P.     0 Y       REAL
                                     SUBRH    SUBRH    SUBRH
                                     F.P.     F.P.

STATEMENT LABELS
C 1           INACTIVE

COMMON BLOCKS  LENGTH
SUBRH         5

STATISTICS
PROGRAM LENGTH      158   13
CM LABELED COMMON LENGTH      98   5
  
```

Figure 26. -Program listing of subroutine FHIC.

Appendix F

```

SUBROUTINE INPT      73/74  OPT=1          FTN 4.6+439      78/02/14. 08.28.50

1          SUBROUTINE INPT(A,II,JJ,N)
           DIMENSION A(II,JJ),ID(5),JD(5),YD(5)
           2  FORMAT(5(2I2,F12.5))
           1  READ(N,2)(ID(L),JD(L),YD(L),L=1,5)
5           IF(ID(1))3,10,3
           3  DO 5 L=1,5
           4  IF(ID(L))4,1,4
           4  I=ID(L)
           4  J=JD(L)
10          5  A(I,J)=YD(L)
           GO TO 1
           10 CONTINUE
           RETURN
           END
           HON09      735
           HON09      736
           HON09      737
           HON09      738
           HON09      739
           HON09      740
           HON09      741
           HON09      742
           HON09      743
           HON09      744
           HON09      745
           HON09      746
           HON09      747
           HON09      748

```

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
3 INPT

VARIABLES	SN	TYPE	RELOCATION					
0 A		REAL	ARRAY	F.P.	70	I	INTEGER	
72 ID		INTEGER	ARRAY		J	II	INTEGER	
71 J		INTEGER			77	JD	INTEGER	ARRAY
0 JJ		INTEGER		F.P.	67	L	INTEGER	
0 4		INTEGER		F.P.	104	YD	REAL	ARRAY

STATEMENT LABELS

17	1				53	2	FMT		0	3	INACTIVE
C	4	INACTIVE			0	5			50	10	

LOOPS	LABEL	INDEX	FROM-TO	LENGTH	PROPERTIES
22		* L	4 4	128	EXT REFS
37	5	* L	6 10	108	OPT EXITS

STATISTICS
PROGRAM LENGTH 1218 81

Figure 27. -Program listing of subroutine INPT.

APPENDIX G
SAMPLE RUN OF PCMLE INITIALIZATION SOFTWARE

This appendix consists of a sample run of PCMLE initialization software, as presented in Figure 28.

1=	T	2=	F	3=	F	4=	F	5=	F	6=	F	7=	F	8=	F	9=	F	10=	F
4	3	6	420	3	4	311													
	.0313		.5000		6.0000		1.2500		4.0000		0.0000		0.0000		10.0000				
	5.0000		.6000		2.0000		.7000												
	4.0000		.0026		.0175		1.0000		1.0000										
	.0100		3.2200		.1000		3.2200		.1000		13.8000		.2500						
	5.0000		5.0000		5.0000		5.0000												
	-1.0000		-1.0000		-1.0000		-1.0000												
	.0010		.1000		.0030		.0100												
	1.0000		.5000		0.0000		0.0000		0.0000										
	-.0700		.0532		.0190		0.0000		0.0000										
	-.0500		.0087		-.0208		0.0000		0.0000										
	-.0450		-.2368		.2707		0.0000		0.0000										
SAMPLE TIME=			.31250E-01																

```
MATRIX KFIC
.1200E-01 .4600E+02 -.1470E+00
.3000E-01 .8500E+02 -.1470E+01
0. .4600E+00 0.
0. .6800E-01 .7000E-02
```

```
FILTER DATA ICH = 1
STATS IN .40000E+01 .26080E+02 .17500E-01 .10000E+01 .10000E+01
STATS OUT .39599E+01 .87400E+00 .52811E-02 .11438E+02
```

```
A .99838E+00 .15082E-02 .64419E-01 -.56828E+00
A .18589E-02 .98448E+00 -.96007E-01 -.55854E+01
A .57349E-06 .60577E-03 .95474E+00 .12039E+00
A .60057E-08 .95634E-05 .30527E-01 .10019E+01
```

```
AKH .99838E+00 -.22130E-01 -.89325E+01 -.12767E+01
AKH .18589E-02 .93998E+00 -.14170E+02 -.51650E+01
AKH .57349E-06 .57348E-03 .17594E+00 .11967E+00
AKH .60057E-08 .16701E-04 -.15542E-01 .99769E+00
```

CHANNEL MODELS	1				
D ARRAY		GRAD D (VBAR)	GRAD D (C2)	GRAD D (C3)	GRAD D (C4)
.99838E+00		-.21654E-02	0.	0.	.10623E-09
.15082E-02		.30709E-02	0.	0.	.22323E-06
.64419E-01		.13622E-01	0.	0.	.10444E-02
-.56828E+00		.88825E+00	0.	0.	.44503E-04
.18589E-02		.74332E-02	0.	0.	-.52473E-10
.98448E+00		-.27754E-04	0.	0.	-.13938E-06
-.86007E-01		-.85836E-01	0.	0.	-.88999E-03
-.55854E+01		-.55897E+01	0.	0.	-.27807E-04
.57349E-06		.29819E-05	0.	0.	.59353E-08
.60577E-03		.60618E-03	0.	0.	.94146E-05
.95474E+00		.18562E-02	0.	0.	.29821E-01

Figure 28. -Sample run of PCMLE initialization software.

Appendix G

GRAD K (VBR)	GRAD K (C2)	GRAD K (C3)	GRAD K (C4)
.28919E-01	0.	0.	.30195E-02
-.20544E-02	0.	0.	.40119E-02
.29707E-04	0.	0.	-.25065E+05
-.43420E-05	0.	0.	.13207E-05
.21971E+02	0.	0.	-.83095E+01
.12838E+02	0.	0.	-.13942E+02
.25734E-01	0.	0.	.18329E+00
.96002E-03	0.	0.	.86257E-03
.21040E+01	0.	0.	.24581E+00
-.26237E+00	0.	0.	.74300E-01
.41086E-04	0.	0.	-.14309E-04
-.50711E-03	0.	0.	.18197E-03

MATRIX KFIC

-.2000E-01	-.6770E+02	-.4000E+00
.3500E-01	.8360E+02	-.1190E+01
0.	.3000E+00	0.
0.	.8000E-01	.7000E-02

FILTER DATA ICH = 2

STATS IN	.40000E+01	.26080E-02	.17500E-01	.10000E+01	.10000E+01
STATS OUT	.47797E+01	.89407E+00	.47435E-02	.11839E-02	

A	.99917E+00	.38194E-03	.59227E-01	-.89502E+00
A	-.18597E-02	.98449E+00	-.43003E-01	-.27907E+01
A	-.28621E-06	.30188E-03	.94811E+00	.60425E-01
A	-.29987E-08	.47714E-05	.30427E-01	.10010E+01

AKH	.99917E+00	.36462E-01	.86723E+01	.68505E+00
AKH	-.18597E-02	.93773E+00	-.92992E+01	-.26069E+01
AKH	-.28621E-06	.28394E-03	.21595E+00	.59747E-01
AKH	-.29987E-08	.78117E-05	-.14755E-01	.99643E+00

CHANNEL MODELS 2	GRAD D (VBAR)	GRAD D (C2)	GRAD D (C3)	GRAD D (C4)
D ARRAY				
.99917E+00	-.11144E-02	0.	0.	-.51870E-10
.38194E-03	.15827E-02	0.	0.	.10723E-06
.59227E-01	.70199E-02	0.	0.	.98836E-03
-.89502E+00	.46035E+00	0.	0.	.21454E-04
-.18597E-02	.74395E-02	0.	0.	.13122E-10
.98449E+00	-.18585E-04	0.	0.	-.34837E-07
-.43003E-01	-.85664E-01	0.	0.	-.44456E-03
-.27907E+01	-.55887E+01	0.	0.	-.69694E-05
-.28621E-06	.68691E-06	0.	0.	-.29588E-08
.30188E-03	.60398E-03	0.	0.	.46870E-05
.94811E+00	.18659E-02	0.	0.	.29623E-01
.60425E-01	.11995E+00	0.	0.	.93790E-03
-.29987E-08	.71971E-08	0.	0.	-.23259E-10
.47714E-05	.95446E-05	0.	0.	.49324E-07
.30427E-01	.19659E-04	0.	0.	.47117E-03
.10010E+01	.19000E-02	0.	0.	.98687E-05
.41721E-02	.16357E-03	0.	.10068E-02	.45078E-05
.11917E-03	.40414E-05	.10068E-02	0.	.18566E-05
.10660E-01	.21284E-01	0.	-.45055E-03	-.14633E-05
-.28844E+00	-.93294E-01	-.45055E-03	0.	-.60322E-06
.12741E-01	.36666E-02	0.	.30427E-01	.19730E-03
.52256E-02	.72016E-02	.30427E-01	0.	.81148E-04
F ARRAY				
-.36081E-01				
.46759E-01				
.17942E-04				
-.30403E-05				

Figure 28. -Continued.

Appendix G

-.86131E+01				
.92562E+01				
.73216E+00				
.45182E-01				
-.15801E+01				
-.16383E+00				
.67764E-03				
.45285E-02				
-.15703E+02				
.59536E-01				
-.59256E+00				
.11056E-01				
-.59256E+00				
.34135E+05				
-.71031E+02				
.11056E-01				
-.71031E+02				
.32506E+04				
.12039E+00	.11866E+00	0.	0.	.18750E-02
.60057E-08	.31227E-07	0.	0.	.46627E-10
.95634E-05	.95666E-05	0.	0.	.98962E-07
.30527E-01	.19583E-04	0.	0.	.47320E-03
.10019E+01	.18864E-02	0.	0.	.19730E-04
.42091E-02	.23582E-03	0.	.10612E-02	.47077E-05
-.73711E-04	-.31555E-03	.10612E-02	0.	.18858E-05
.21330E-01	.21228E-01	0.	-.90055E-03	-.29369E-05
-.33503E+00	-.93399E-01	-.90055E-03	0.	-.11790E-05
.12828E-01	.36854E-02	0.	.30527E-01	.19881E-03
.50864E-02	.71967E-02	.30527E-01	0.	.79376E-04

F ARRAY

.23638E-01
 .44496E-01
 .32284E-04
 -.71381E-05
 .89969E+01
 .14084E+02
 .77880E+00
 .46070E-01
 .70844E+00
 -.42041E+00
 .71363E-03
 .42178E-02
 -.15537E+02
 .59681E-01
 -.90503E+00
 .25283E-01
 -.90503E+00
 .28840E+05
 -.69719E+02
 .25283E-01
 -.69719E+02
 .32516E+04

GRAD K(VBH)
 .10498E+00
 -.10742E-01
 .30290E-04
 -.11735E-04
 .66867E+01
 .15404E+02
 .19018E-01
 .29000E-02
 .30052E+00
 -.66898E+00
 .27958E-03
 -.66070E-03

GRAD K(C2)
 0.
 0.
 0.
 0.
 0.
 0.
 0.
 0.
 0.
 0.
 0.
 0.
 0.
 0.

GRAD K(C3)
 0.
 0.
 0.
 0.
 0.
 0.
 0.
 0.
 0.
 0.
 0.
 0.
 0.

GRAD K(C4)
 -.17602E-02
 .14262E-02
 -.26322E-05
 .62656E-06
 .77239E+01
 -.84387E+01
 .18726E+00
 .10183E-02
 -.15239E+00
 .37392E-01
 -.64499E-04
 .73678E-04

Figure 28. -Continued.

Appendix G

MATRIX KFIC

```

0.      0.      0.
0.      0.      0.
0.      0.      0.
0.      .3000E-01 .1000E+00
    
```

FILTER DATA ICH = 3

```

STATS IN  .40000E+01 .26080E-02 .17500E-01 .10000E+01 .10000E+01
STATS OUT  .33367E+01 .93778E+00 .64211E-02 .12007E-02
    
```

```

A      .99944E+00 0.      .58037E-01 -.10060E+01
A      -.55797E-02 .98450E+00 -.17806E-03 .28149E-02
A      0.      0.      .96231E+00 0.
A      0.      0.      .30657E-01 .10000E+01
    
```

```

AKH     .99944E+00 .54521E-01 -.17043E-01 -.51563E+00
AKH     -.55797E-02 .93290E+00 .98787E-03 -.35488E-01
AKH     0.      .34183E-09 .13628E+00 -.37691E-03
AKH     0.      -.69170E-06 -.13294E-01 .99535E+00
    
```

CHANNEL MODELS 3

D ARRAY	GRAD D (VBAR)	GRAD D (C2)	GRAD D (C3)	GRAD D (C4)
.99944E+00	-.53327E-04	0.	0.	0.
0.	.94184E-04	0.	0.	0.
.58037E-01	.37844E-03	0.	0.	.98154E-03
-.10060E+01	.25862E-01	0.	0.	0.
-.55797E-02	.74398E-02	0.	0.	0.
.98450E+00	-.11306E-05	0.	0.	0.
-.17806E-03	-.86089E-01	0.	0.	-.19209E-05
.28149E-02	-.55853E+01	0.	0.	0.
0.	-.16111E-05	0.	0.	0.
0.	.60837E-03	0.	0.	0.
.96231E+00	.19029E-02	0.	0.	.30077E-01
0.	.12255E+00	0.	0.	0.
0.	-.16859E-07	0.	0.	0.
0.	.95917E-05	0.	0.	0.
.30657E-01	.19952E-04	0.	0.	.47600E-03
.10000E+01	.19275E-02	0.	0.	0.
.40764E-02	.12059E-03	0.	.99460F-03	.35272E-05
.18897E-04	.22784E-03	.99460E-03	0.	.20358E-06
-.11129E-04	.21417E-01	0.	-.19397E-05	-.50808E-08
-.24186E+00	-.93050E-01	-.19397E-05	0.	-.29328E-09
.10092E-01	.36859E-02	0.	.30657E-01	.15670E-03
.58249E-03	.72821E-02	.30657E-01	0.	.90441E-05

F ARRAY

```

-.54521E-01
.51597E-01
-.34183E-09
.69170E-06
.75080E-01
-.11659E-02
.82604E+00
.43951E-01
-.49033E+00
.38303E-01
.37691E-03
.46487E-02
-.15204E+02
.59244E-01
.52226E-04
-.22586E-02
.52226E-04
.20820E+05
-.57584E+02
-.22586E-02
-.57584E+02
.32502E+04
    
```

Figure 28. -Continued.

Appendix G

GRAD K(VBR)	GRAD K(C2)	GRAD K(C3)	GRAD K(C4)
.84841E-02	0.	0.	-.17092E-07
-.69648E-02	0.	0.	.13519E-08
.36441E-04	0.	0.	.10749E-09
-.37235E-05	0.	0.	.13869E-09
-.12869E+02	0.	0.	.10643E-01
.11445E+02	0.	0.	.26081E-03
.45135E-02	0.	0.	.19843E+00
.43564E-02	0.	0.	.35176E-02
-.24507E+01	0.	0.	-.11378E-03
-.24181E+00	0.	0.	.75688E-05
.67689E-03	0.	0.	-.39295E-04
.52702E-04	0.	0.	.15764E-05

Figure 28. -Concluded.

APPENDIX H
PROGRAM LISTING OF MODEL REFERENCE ALGORITHM

This appendix consists of the program listings of subroutines RFMOD (Fig. 29), INTGRAL (Fig. 30), and RMIC (Fig. 31).

SUBROUTINE RFMOD	73/74 OPT=1	FTN 4.6+439	78/02/15. 07.44.44
1	SUBROUTINE RFMOD		HON09 1564
	COMMON/MRDATA(3, 3),B(3,2),DX(39),X(13),U(2)		HON09 1565
	1, T1,T2,T3,T4,T5,T6,T7,T8,T9,T10,T11,THR1,THR2,THR3		HON09 1566
	2, G11,G12,G21,G22		HON09 1567
5	COMMON/VARDAT/ UX(50),LX(50)		HON09 1568
	COMMON/IPIC/DUM(59),XVZ(2),XQ(2),XTH(2),XDB(2),XDC(2)		HON09 1569
	LOGICAL LX		HON09 1570
	C		HON09 1571
	VZ=UX(11)		HON09 1572
10	Q=UX(12)		HON09 1573
	TH=UX(13)		HON09 1574
	U(1)=UX(1)		HON09 1575
	U(2)=UX(2)		HON09 1576
	DT=UX(19)		HON09 1577
15	CALL FH(Q,Q,XQ)		HON09 1578
	CALL FH(VZ,VZ,XVZ)		HON09 1579
	CALL FH(TH,TH,XTH)		HON09 1580
	CALL FH(U(1),U(1),XDB)		HON09 1581
	CALL FH(U(2),U(2),XDC)		HON09 1582
20	C		HON09 1583
	EVZ=X(1)-VZ		HON09 1584
	EQ=X(2)-Q		HON09 1585
	ETH=X(3)-TH		HON09 1586
	UX(24)=EVZ/10.		HON09 1587
25	UX(25)=EQ*5.73		HON09 1588
	UX(26)=ETH*5.73		HON09 1589
	IF(EQ.GT.1.) EQ=1.		HON09 1590
	IF(EQ.LT.-1.) EQ=-1.		HON09 1591
	IF(ETH.GT.1.) ETH=1.		HON09 1592
30	IF(ETH.LT.-1.) ETH=-1.		HON09 1593
	IF(EVZ.GT.10.) EVZ=10.		HON09 1594
	IF(EVZ.LT.-10.) EVZ=-10.		HON09 1595
	IF(ABS(EVZ).LT.THR1) EVZ=0.		HON09 1596
	IF(ABS(EQ).LT.THR2) EQ=0.		HON09 1597
35	IF(ABS(ETH).LT.THR3) ETH=0.		HON09 1598
	T1=UX(34)/(1. + U(1)*U(1)+U(2)*U(2))		HON09 1599
	T5=UX(35)		HON09 1600
	T6=UX(36)		HON09 1601
	T7=UX(37)		HON09 1602
40	T11=UX(38)		HON09 1603
	P11=T1*0.25		HON09 1604
	P22=T1*0.1944		HON09 1605
	P23=T1*0.08333		HON09 1606
	P33=T1*1.4167		HON09 1607
45	FAC=1.+P11*EVZ*EVZ+P22*EQ*EQ+2.*P23*EQ*ETH+P33*ETH*ETH		HON09 1608
	FAC1=SQRT(FAC)		HON09 1609
	S1=P22*EQ*VZ + P23*ETH*VZ		HON09 1610
	S2=P22*EQ*Q + P23*ETH*Q		HON09 1611
	S3=P22*EQ*TH + P23*ETH*TH		HON09 1612
50	S4=P22*EQ*U(1) + P23*ETH*U(1)		HON09 1613
	S5=P22*EQ*U(2) + P23*ETH*U(2)		HON09 1614
	C		HON09 1615
	DX(4)=(G11*P11*EVZ*VZ + G12*S1)*T2		HON09 1616
	DX(5)=(G11*P11*EVZ*Q + G12*S2)*T3		HON09 1617
55	DX(6)=(G11*P11*EVZ*TH + G12*S3)*T4		HON09 1618
	DX(7)=(G11*P11*EVZ*U(1) + G12*S4)*T5		HON09 1619
	DX(8)=(G11*P11*EVZ*U(2) + G12*S5)*T6		HON09 1620
	DX(9)=(G21*P11*EVZ*VZ + G22*S1)*T7		HON09 1621
	DX(10)=(G21*P11*EVZ*Q + G22*S2)*T8		HON09 1622

Figure 29. -Program listing of subroutine RFMOD.

Appendix H

60		DX(11)=(G21*P11*EVZ*TH + G22*S3)*T9	HON09	1623
		DX(12)=(G21*P11*EVZ*U(1) + G22*S4)*T10	HON09	1624
		DX(13)=(G21*P11*EVZ*U(2) + G22*S5)*T11	HON09	1625
	C		HON09	1626
		DO 100 I=1,3	HON09	1627
		S=0.	HON09	1628
65		DO 101 J=1,3	HON09	1629
	101	S=S + A(I,J)*X(J)	HON09	1630
		DO 102 J=1,2	HON09	1631
	102	S=S + B(I,J)*U(J)	HON09	1632
70	100	DX(I)=S	HON09	1633
		CALL INTGRAL(DX,X,DT,TIME,13,1)	HON09	1634
	C	OUTPUT GAINS	HON09	1635
		DO 200 I=1,10	HON09	1636
	200	UX(40+I)=X(3+I)	HON09	1637
75		UX(20)=U(1)/10.	HON09	1638
		UX(21)=U(2)*5.73	HON09	1639
		UX(22)=X(1)/10.	HON09	1640
		UX(23)=X(3)*5.73	HON09	1641
		UX(27)=X(13)	HON09	1642
80		UX(28)=DX(7)	HON09	1643
		UX(29)=DX(8)	HON09	1644
		UX(30)=DX(12)	HON09	1645
		UX(31)=DX(13)	HON09	1646
		UX(32)=FAC	HON09	1647
85		RETURN	HON09	1648
		END	HON09	1649

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
1 RFMOD

VARIABLES	SN	TYPE	RELOCATION						
0 A		REAL	ARRAY	MRDAT	11	B	REAL	ARRAY	MRDAT
355 DT		REAL			0	DUM	REAL	ARRAY	IPIC
17 DX		REAL	ARRAY	MRDAT	357	EQ	REAL		
360 ETH		REAL			356	EVZ	REAL		
365 FAC		REAL			366	FAC1	REAL		
123 G11		REAL		MRDAT	124	G12	REAL		MRDAT
125 G21		REAL		MRDAT	126	G22	REAL		MRDAT
374 I		INTEGER			376	J	INTEGER		
62 LX		LOGICAL	ARRAY	VARDAT	361	P11	REAL		
362 P22		REAL			363	P23	REAL		
364 P33		REAL			353	Q	REAL		
375 S		REAL			367	S1	REAL		
370 S2		REAL			371	S3	REAL		
372 S4		REAL			373	S5	REAL		
354 TH		REAL			120	THR1	REAL		MRDAT
121 THR2		REAL		MRDAT	122	THR3	REAL		MRDAT
377 TIME		REAL			105	T1	REAL		MRDAT
116 T10		REAL		MRDAT	117	T11	REAL		MRDAT
106 T2		REAL		MRDAT	107	T3	REAL		MRDAT
110 T4		REAL		MRDAT	111	T5	REAL		MRDAT
112 T6		REAL		MRDAT	113	T7	REAL		MRDAT
114 T8		REAL		MRDAT	115	T9	REAL		MRDAT
103 U		REAL	ARRAY	MRDAT	0	UX	REAL	ARRAY	VARDAT
352 VZ		REAL			66	X	REAL	ARRAY	MRDAT
101 XDB		REAL	ARRAY	IPIC	103	XDC	REAL	ARRAY	IPIC
75 XQ		REAL	ARRAY	IPIC	77	XTH	REAL	ARRAY	IPIC
73 XVZ		REAL	ARRAY	IPIC					

EXTERNALS TYPE ARGS INTGRAL 6

FH 3

SQRT REAL 1 LIBRARY

INLINE FUNCTIONS TYPE ARGS

ABS REAL 1 INTRIN

STATEMENT LABELS 0 101 0 102

0 100

0 200

Figure 29. -Continued.

Appendix H

LOOPS	LABEL	INDEX	FROM-TO	LENGTH	PROPERTIES
216	100	I	64 70	278	NOT INNER
224	101	J	66 67	48	INSTACK
235	102	J	68 69	48	INSTACK
252	200	I	73 74	38	INSTACK

COMMON BLOCKS	LENGTH
HRDAT	87
VARDAT	100
IPIC	69

STATISTICS		
PROGRAM LENGTH	4008	256
CM LABELED COMMON LENGTH	4008	256

Figure 29. -Concluded.

	SUBROUTINE INTEGRAL	73/74	OPT=1	FTN 4.6+439	78/02/15. 07.44.44
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1	SUBROUTINE INTEGRAL(DX,X,DT,TIME,NX,MINTG)	HON09	750
	COMMON/HRINT/XO(50),MINTGP,NX2,B0,B1,C0,C1,C2,TIME0	HON09	751
	C THIS SUBROUTINE INTEGRATES DX TO GET X.	HON09	752
	C	HON09	753
5	C DIMENSION DX(1), X(1)	HON09	754
	C	HON09	755
	C INITIALIZATION	HON09	756
	C	HON09	757
10	C IF(MINTG .GT. 0) GO TO 10	HON09	758
	NX2 = 2*NX	HON09	759
	B0 = 3.0*DT/2.0	HON09	760
	B1 = -DT/2.0	HON09	761
	C0 = 23.0*DT/12.0	HON09	762
15	C1 = -16.0*DT/12.0	HON09	763
	C2 = 5.0*DT/12.0	HON09	764
	MINTGP = 1	HON09	765
	TIME0 = TIME	HON09	766
	DO 5 I = 1, NX	HON09	767
20	5 XO(I) = X(I)	HON09	768
	RETURN	HON09	769
	C	HON09	770
	C STARTUP PROCEDURE	HON09	771
	C	HON09	772
25	10 IF(MINTGP - MINTG) 20, 60, 90	HON09	773
	20 GO TO (30, 40), MINTGP	HON09	774
	30 DO 35 I = 1, NX	HON09	775
	TEMP = DT*DX(I)	HON09	776
	X(I) = X(I) - TEMP	HON09	777
30	35 DX(NX+I) = DX(I)	HON09	778
	GO TO 50	HON09	779
	40 DO 45 I = 1, NX	HON09	780
	TEMP = B0*DX(I) + B1*DX(NX+I)	HON09	781
	X(I) = X(I) - TEMP	HON09	782
35	DX(NX2+I) = DX(NX+I)	HON09	783
	45 DX(NX+I) = DX(I)	HON09	784
	50 MINTGP = MINTGP + 1	HON09	785
	TIME = TIME - DT	HON09	786
	RETURN	HON09	787
40	C	HON09	788
	60 GO TO (87, 70, 80), MINTG	HON09	789
	70 DO 75 I = 1, NX	HON09	790
	X(I) = XO(I)	HON09	791
	TEMP = DX(I)	HON09	792
45	DX(I) = DX(NX+I)	HON09	793
		HON09	794

Figure 30. -Program listing of subroutine INTEGRAL.

Appendix H

		75 DX(NX+I) = TEMP	HON09	795
		GO TO 87	HON09	796
		80 DO 85 I = 1, NX	HON09	797
		X(I) = XO(I)	HON09	798
50		TEMP = DX(I)	HON09	799
		DX(I) = DX(NX2+I)	HON09	800
		85 DX(NX2+I) = TEMP	HON09	801
		87 MINTGP = MINTGP + 1	HON09	802
		TIME = TIMEO	HON09	803
55		90 GO TO (100, 200, 300), MINTG	HON09	804
	C		HON09	805
	C	EULER INTEGRATION (FIRST ORDER)	HON09	806
	C		HON09	807
		100 DO 150 I = 1, NX	HON09	808
60		TEMP = DT*DX(I)	HON09	809
		150 X(I) = X(I) + TEMP	HON09	810
		GO TO 1000	HON09	811
	C		HON09	812
	C	HARRY BEAN INTEGRATION (SECOND ORDER)	HON09	813
65	C		HON09	814
		200 DO 250 I = 1, NX	HON09	815
		TEMP = B0*DX(I) + B1*DX(NX+I)	HON09	816
		X(I) = X(I) + TEMP	HON09	817
		250 DX(NX+I) = DX(I)	HON09	818
70		GO TO 1000	HON09	819
	C		HON09	820
	C	GUNTER STEIN INTEGRATION (THIRD ORDER)	HON09	821
	C		HON09	822
		300 DO 350 I = 1, NX	HON09	823
75		TEMP = C0*DX(I) + C1*DX(NX+I) + C2*DX(NX2+I)	HON09	824
		X(I) = X(I) + TEMP	HON09	825
		DX(NX2+I) = DX(NX+I)	HON09	826
		350 DX(NX+I) = DX(I)	HON09	827
	C		HON09	828
80	C	INCREMENT TIME	HON09	829
	C		HON09	830
		1000 TIME = TIME + DT	HON09	831
		RETURN	HON09	832
		END	HON09	833

CARD NR. SEVERITY DETAILS DIAGNOSIS OF PROBLEM

26	I	AN IF STATEMENT MAY BE MORE EFFICIENT THAN A 2 OR 3 BRANCH COMPUTED GO TO STATEMENT.	
41	I	AN IF STATEMENT MAY BE MORE EFFICIENT THAN A 2 OR 3 BRANCH COMPUTED GO TO STATEMENT.	
55	I	AN IF STATEMENT MAY BE MORE EFFICIENT THAN A 2 OR 3 BRANCH COMPUTED GO TO STATEMENT.	

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
3 INTEGRAL

VARIABLES	SN	TYPE	RELOCATION	65	B1	REAL	MRINT
64	B0	REAL	MRINT	67	C1	REAL	MRINT
66	C0	REAL	MRINT	0	DT	REAL	F.P.
70	C2	REAL	MRINT	245	I	INTEGER	
0	DX	REAL	ARRAY	62	MINTGP	INTEGER	MRINT
0	MINTG	INTEGER	F.P.	63	NX2	INTEGER	MRINT
0	NX	INTEGER	F.P.	0	TIME	REAL	F.P.
246	TEMP	REAL	MRINT	0	X	REAL	ARRAY
71	TIMEO	REAL	MRINT				F.P.
0	XO	REAL	ARRAY				

STATEMENT LABELS

0 5	34 10	0 20	INACTIVE
45 30	0 35	61 40	
0 45	101 50	106 60	
116 70	0 75	132 80	
0 85	146 87	151 90	
161 100	0 150	174 200	
0 250	211 300	0 350	
232 1000			

Figure 30. -Continued.

Appendix H

LOOPS	LABEL	INDEX	FROM-TO	LENGTH	PROPERTIES
30	5	I	19 20	28	INSTACK
54	35	I	27 30	48	INSTACK
71	45	I	32 36	78	INSTACK
124	75	I	42 46	48	INSTACK
141	85	I	48 52	48	INSTACK
167	150	I	59 61	48	INSTACK
202	250	I	66 69	68	INSTACK
221	350	I	74 78	108	OPT

COMMON BLOCKS LENGTH
 MRINT 58

STATISTICS
 PROGRAM LENGTH 2478 167
 CM LABELED COMMON LENGTH 728 58

Figure 30. -Concluded.

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SUBROUTINE RMIC            73/74    OPT=1                    FTN 4.6+439            78/02/15. 07.44.44

1                    SUBROUTINE RMIC                                    HON09      1651
                    C                                                    HON09      1652
                    COMMON/VARDAT/ UX(50),LX(50)                    HON09      1653
                    COMMON/MRDAT/A( 3, 3),B( 3,2),DX(39),X(13),U(2)    HON09      1654
5                    1, T1,T2,T3,T4,T5,T6,T7,T8,T9,T10,T11,THR1,THR2,THR3    HON09      1655
                    2, G11,G12,G21,G22                                HON09      1656
                    LOGICAL LX                                        HON09      1657
                    C                                                    HON09      1658
                    C                                                    HON09      1659
10                    DO 20 I=1,3                                    HON09      1660
                    DO 10 J=1,3                                    HON09      1661
                    10 A(I,J)=0.                                    HON09      1662
                    DO 15 J=1,2                                    HON09      1663
                    15 B(I,J)=0.                                    HON09      1664
15                    20 CONTINUE                                    HON09      1665
                    A(1,1)=-2.                                    HON09      1666
                    A(2,2)=-4.                                    HON09      1667
                    A(2,3)=-7.                                    HON09      1668
                    A(3,2)= 1.                                    HON09      1669
20                    B(1,1)=2.                                    HON09      1670
                    B(2,2)=7.                                    HON09      1671
                    DO 30 I=1,39                                    HON09      1672
                    30 DX(I)=0.                                    HON09      1673
                    DT=UX(19)                                    HON09      1674
25                    CALL INTGRAL(DX,X,DT,0.,13,0)                HON09      1675
                    RETURN                                        HON09      1676
                    END                                                HON09      1677
  
```

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
 1 RMIC

VARIABLES	SN	TYPE	RELOCATION					
0 A		REAL	ARRAY	MRDAT	11 B	REAL	ARRAY	MRDAT
72 DT		REAL			17 DX	REAL	ARRAY	MRDAT
123 G11		REAL		MRDAT	124 G12	REAL		MRDAT
125 G21		REAL		MRDAT	126 G22	REAL		MRDAT
70 I		INTEGER			71 J	INTEGER		
62 LX		LOGICAL	ARRAY	VARDAT	120 THR1	REAL		MRDAT
121 THR2		REAL		MRDAT	122 THR3	REAL		MRDAT
105 T1		REAL		MRDAT	116 T10	REAL		MRDAT
117 T11		REAL		MRDAT	106 T2	REAL		MRDAT
107 T3		REAL		MRDAT	110 T4	REAL		MRDAT

Figure 31. -Program listing of subroutine RMIC.

Appendix H

111	T5	REAL		MRDAT	112	T6	REAL	MRDAT
113	T7	REAL		MRDAT	114	T8	REAL	MRDAT
115	T9	REAL		MRDAT	103	U	REAL	MRDAT
0	UX	REAL	ARRAY	VARDAT	66	X	REAL	MRDAT
EXTERNALS		TYPE	ARGS					
	INTGRAL		6					
STATEMENT LABELS								
0	10				0	15		
0	30						0	20
LOOPS	LABEL	INDEX	FROM-TO	LENGTH	PROPERTIES			
3	20	* I	10 15	238	NOT INNER			
10	10	J	11 12	28	INSTACK			
20	15	J	13 14	28	INSTACK			
41	30	I	22 23	28	INSTACK			
COMMON BLOCKS	LENGTH							
VARDAT	100							
MRDAT	67							
STATISTICS								
PROGRAM LENGTH			738	59				
CM LABELED COMMON LENGTH			2738	187				

Figure 31. -Concluded.



1

2

3