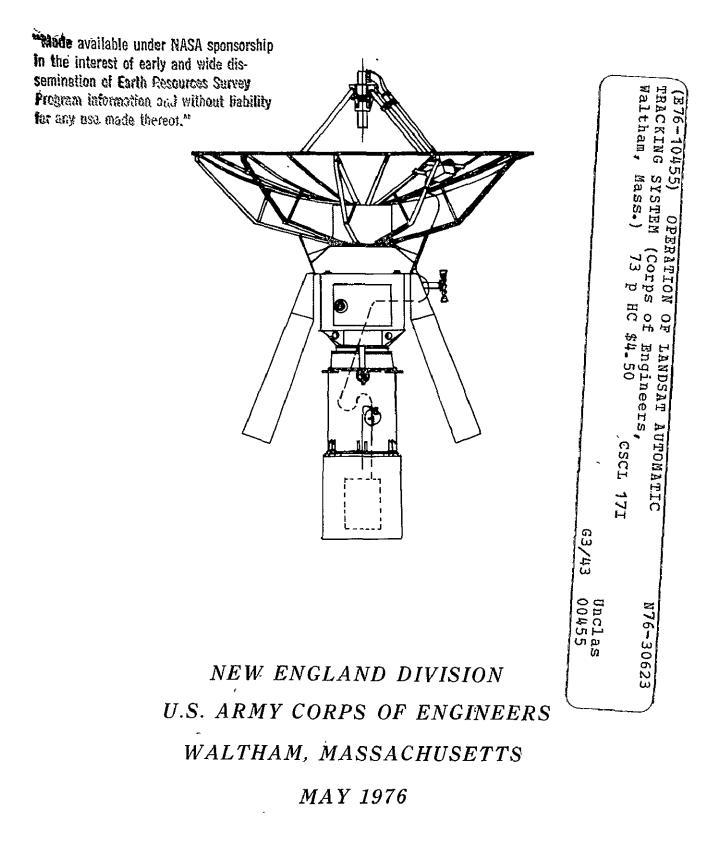
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CR-148586OPERATION OF THE LANDSATAUTOMATIC TRACKING SYSTEM



Operation of LANDSAT Automatic Tracking System

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by

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ORIGINAL CONTAINS COLOR ILLUSTRATIONS

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March 1976

Original'photography may be purchased from: EROS Data Center 10th and Dakota Avenue Sioux Falis, SD 57198

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FOREWORD

The purpose of this manual is to document the procedures and theory of operation of the LANDSAT tracking system at New England Division, U.S. Army Corps of Engineers, Waltham, Massachusetts.

The manual is arranged generally by degree of detail, with the simplest operating procedures first; instructions for normal day-to-day operation are given in Section I, while information needed for program modification, file maintenance, and troubleshooting is in Sections II τ VII and the Appendices. All figures referred to in the text are in Appendix B.

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I. AUTOMATIC TRACKING SYSTEM OPERATION - OVERVIEW

The Automatic Tracking System for receiving LANDSAT³ data at -New England Division, Waltham, consists of a 15-foot dish antenna, a tracking pedestal, some pedestal control equipment, and a Data General NOVA minicomputer with various accessories. The relationship of all these parts is shown in the subsystems diagram, Figure 1. Most day-to-day operation of the system will require very little action by operators, but full control of it and the handling of unusual situations require some knowledge of the programs and various information files that are kept on disc. Most operator action is taken at the computer terminal (Figure 7). (No card decks are needed, and the system is almost entirely separate from the IBM 1130 and Motorola equipment which are in the same room.) The operator may have to power up the NOVA computer (see section II) and start execution of the programs which track the LANDSAT and store incoming data. Once the NOVA has the correct time of day and is executing the tracking programs, it should do so continually until the operator interrupts it. These programs are cyclical, and if one of them is interrupted, it may be restarted later; that is, the operator may re-enter the cycle at one of several points.

The simplest procedure for tracking is as follows (refer to Figure 3):

1. Power up the NOVA (sée Section II).

2. Set the NOVA's real time clock precisely (see Section III).

3. Turn on all required control equipment (see Section V).

4. Execute the program TRACK by typing "TRACK" followed by a carriage return.

II: ROUTINE TO POWER UP THE NOVA

SWITCHES ARE LABELLED WITH RED TAPES. (SEE FIGURE 7).

1. TURN CONSOLE POWER SWITCH TO "ON".

2. TURN ON POWER SWITCH ON TEKTRONIX TERMINÀL

3. TURN TELETYPE SWITCH TO "LINE".

4. TURN DISC POWER SWITCH TO "ON" (clockwise).

5. PUSH WHITE KEY ("POWER ON") ON MOVING HEAD DISC CABINET

6. SET CONSOLE SWITCHES 0, 11, 12, 14, and 15 UP; ALL OTHER NUMBERED SWITCHES STAY DOWN.

7. WHEN GREEN LIGHT ON DISC CABINET COMES ON, LIFT "RESET" SWITCH AND THEN "PROGRAM LOAD" SWITCH ON THE CONSOLE. THE FOLLOWING DIALOGUE ENSUES:

> FILENAME ? ANTSYS) RDOS REV 3.02 DATE (M/D/Y) ? 3 15 76) TIME (HIMIS) ? 13 15 0) R GLEAR/A/V) DIR USER) GLEAR/A/V) SYS.DR R SYS.DR R

NOTES:

1. ") " means "RETURN". You type in the underlined characters.

2. WHEN RDOS SYSTEM CRASHES, PUSH WHITE KEY ON DISC CABINET (OFF) AND GO TO STEP 5 ABOVE.

ROUTINE TO POWER DOWN THE NOVA (SEE FIGURE 7)

1. TYPE RELEASE DP0). ("0" IS A ZERO: ")" IS A RETURN).

2. PUSH WHITE KEY ON DISC CABINET (WHITE LIGHT GOES OUT).

- 3. TURN OFF FHD SWITCH.
- 4. TURN DISC POWER SWITCH TO DFF (counter clockwise),

5. TURN TELETYPE SWITCH FROM "LINE" TO "OFF",

6. TURN TEKTRONIX TERMINAL SWITCH TO "OFF".

NOTE: NOVA IS NORMALLY LEFT RUNNING ALL THE TIME.

III. SETTING NOVA'S REAL TIME CLOCK

To track LANDSAT accuratley the NOVA's Real Time clock must be set to Coordinated Universal Time (UTC). Accuracy of one-fourth second is sufficient. Two methods may be used; a manual one and (eventually) an automatic one.

<u>Automatic Method</u>. Execute the program CL. Within 2-3 minutes the computer will signify completion by typing "R". If it doesn't it means that it probably won't. In this case, use the manual method. <u>Manual Method</u>. The NOVA provides for its clock to be set by the teletype command <u>STOD hh mm ss</u>

Where <u>hh</u>, <u>mm</u>, and <u>ss</u> stand for hour, minute, and second.

Dial up the FTS number 8-323-4245 to get the National Bureau of Standards' audio time signal. When you have found out what time mark will be coming soon (e.g., the next minute), use the STOD command to prepare to enter that upcoming time, and hit CARRIAGE RETURN exactly when the time marker occurs.

Before hanging up the telephone, you may check the NOVA's time by executing the program PU which will send an audible pulse to the terminal every 15 seconds.

This annotated sample of operator/computer dialog illustrates the method:

STOD 13 10 30At this time, NBS signal is coming in by
telephone. Return is pressed at exactly 13:10:30.R,
PU1Continue listening to NBS and compare teletype
pulses to telephone signal.60
INT
R
PU1IT'S NOW 13:11:12
15
INT
R
LSI)NEXT PASS AT 14:28:10

IV. HOW TO ENTER ORBITAL ELEMENTS INTO TRACKING SYSTEM

To track LANDSAT, the system must be able to predict when the satellite will rise over the horizon and what azimuth and elevation angles to send to the tracking pedestal. To predict those times and angles the system is given a description of LANDSAT's orbit by means of the teletype or CRT terminal. This orbital information is contained in the element set provided by the North American Air Defense Command, Ent AFB, Colorado* The element set comes via TWX twice a week and looks like the example in Figure 5. Eight of the elements in Figure 5 are important to our system. Their meanings, formats, and units are as follows:

 EPOCH - - An arbitrarily chosen recent instant expressed as a Julian date, at which the rest of this element set was determined.

XXX.XXXXXXXX (DAYS)

2. NDOTØ** - - First derivative of mean motion + or - .XXXXXXXXX (REVS/DAY/DAY)

*Questions about NORDADC elements can be addressed to:

SPACE DEFENSE CENTER (Cheyenne Mountain Office) ENT AFB, Colorado

As of 9 December 1975, our contact person there was Capt.

Tohlen, FTS 8-327-0111 635-8911, ask for ext. 3549

** "Ø" stands for zero; "O" is the 15th character of the alphabet.

3. IØ - - Inclination. XX.XXXX (DEGREES)

 NODEØ - - Right Ascension of the Ascending Node, XX.XXXX (DEGREES)

5. EØ - - Eccentricity. XXXXXXX (NO UNITS)

Notice that the decimal point is not printed on NORAD message, but must be supplied to system when you type it in.

6. OMEGØ - - Argument of Perigee. XXX.XXXX (DEGREES)

7. MØ - - Mean Anomaly. XXX.XXXX (DEGREES)

8. NØ - - Mean Motion. XX.XXXXXXXXXXX(REVS/DAY)

The orbital element set is entered into the system by executing a program called "ELW", which stands for "Element Writer". ELW is an interactive program which guides the operator in entering the numbers correctly. Because the numbers have many digits, it is easy to mistype them on the teletype keyboard. Therefore, ELW echoes each number as it is entered and allows revision of that one number. If no correction is needed, the operator types \underline{Y} after "OK?" and enters the next number. If a correction is needed, the operator types \underline{N} and retypes the same number. An example of the operator/computer dialog for the element set of Figure 5 is given in Figure 6.

V. POWERING UP TRACKING EQUIPMENT

* Power switches for the Data General equipment, the Scientific/ Atlanta equipment and associated devices are shown on the photographs in Figure 7. The order of turning switches ON is as follows:

Data General:

- 1. Console power
 - 2. Disk power on console
 - 3. Disk power on disk cabinet
 - 4. CRT Teletype
 - 5.
 - 6. Decoder

Scientific/Atlanta:

- 7. Receiver
- 8. Synchro Display
- 9. Servo Control
- 10. Digital Comparator

' În addition, the main power switch on the antenna pedestal concrete foundation must be ON, and any interlock switches in the pedestal itself must be closed. • . *

There is one power switch on a plug strip inside the S/A cabinet of which you should be aware.

VI. IF SOMETHING FAILS ...

Occasionally, a device will malfunction and cause tracking to cease. Here are a few things to notice as you recover from the malfunction:

1. Is the computer still up and running?

If the lights are glowing softly, it is probably still running and should respond to commands from the terminal. If the console lights have stopped with some on and some off,or if no lights are on it has crashed. Go to Section II, Step 2, in the footnotes.

2. Is the dish in the stow position (pointed straight up)?

If not, tracking is either in progress or has ended abnormally. If it has ended abnormally, the command equipment must be returned to STANDBY mode. Go to next item.

3, Are the two tiny (5/16") red lights (LED'S) on the Servo Control Unit lit?

If so, the equipment is in PROGRAM mode. Put it in STANDBY, by typing "OFF" at the terminal followed by carriage return. The tiny red lights should go off. If that doesn't work, turn off the power switch on the DECODER (see Section IV) for 2 or 3 seconds.

To put the antenna in the stow position, use the manual command unit, the cabinet immediately above the Servo Control Unit. Push the two square buttons on the manual command unit. The antenna should go to the position indicated on the two round dials on this unit. If it doesn't respond to the manual commands, something has

blown out - probably a fuse. Finally, push the STANDBY buttons on the Servo Control Unit.

4. If it looks like a fuse has blown, zero in on the difficulty by the equipment's behavior and appearance (e.g., lights out, movement in azimuth but not elevation, or <u>vice versa</u>), lost power in Servo Amps, etc.). Most commonly the center (30 amp) fuse on the concrete foundation supply box is the one that is blown.

Fuses have also blown in the Digital Synchro Display Unit (back panel) and in the Servo Amplifier in the pedestal itself.

5. The root cause of these fuse troubles seems to be back in the NOVA computer. When it sends bad data, the pedestal equipment gets overloaded. The NOVA runs into difficulties when RDOS is not functioning right, and recently it has appeared that RDOS gives problems when the files CLI.OL and TLOG are not "cleared". That is, their user counts in the system directory are greater than zero. This is remedied by the commands "CLEAR TLOG" and "CLEAR CLI.OL" at the terminal.

6. If the equipment all seems to work, but no signal comes in during a satellite pass, the system time may be set wrong. Also, check the system date. Perhaps the satellite has not been turned on by NASA at Goddard Space Flight Center. Usually, they turn it on by the time it reaches 10° elevation.

7. If the equipment has failed so badly that it can't be fixed

by NED, the following service groups are available:

Data General Corporation Field Service 237 Riverview Waltham, MA _02154 891-7024

Tektronix, Inc. Field Service 482 Bedford Lexington, MA 861-6800

Scientific/Atlanta Bud Lydon, Fred Leavett, or Dan Pioli Burlington, MA 272-1256

VII. SYSTEM DESIGN AND OPERATION, IN-DEPTH VIEW

The LANDSAT tracking system integrates a set of about twenty programs or subroutines (software), about ten disk data files, and several pieces of equipment (hardware). The inter-relationships of the programs and data files can be seen in the flowchart in Figure 4. The hardware configuration is shown in Figure 1. In the flowchart, an information flow can be seen as well as a cycle of program executions. Essentially, the system predicts the satellite's position, tracks the satellite, stores and prints the data, returns to the predicting program, and so forth. This cycle can be entered by the method given in Section I. However, from time to time, other operator action will be necessary.

For example, the computer's real-time clock must be accurately set (see Section III). As of this writing, only a manual method is available, and it has to be performed at least once a day for various reasons such as clock inaccuracy and system crashes. A better, automatic method of imputting time from a standard clock is being developed by the writer.

The operator must also inform the tracking system of the latest description of the LANDSAT's orbit. This must be stored in a file called "ELEMENTS". The orbital information is contained in an eight-number set which is supplied to WCB under a standing arrangement with the North American Air Defence Command (NORADC) in

]3 `

Colorado. Twice a week, NORADC sends the element set to the TWX machine in Building 115S. A detailed description of how to enter the elements into the system is given in Section IV.

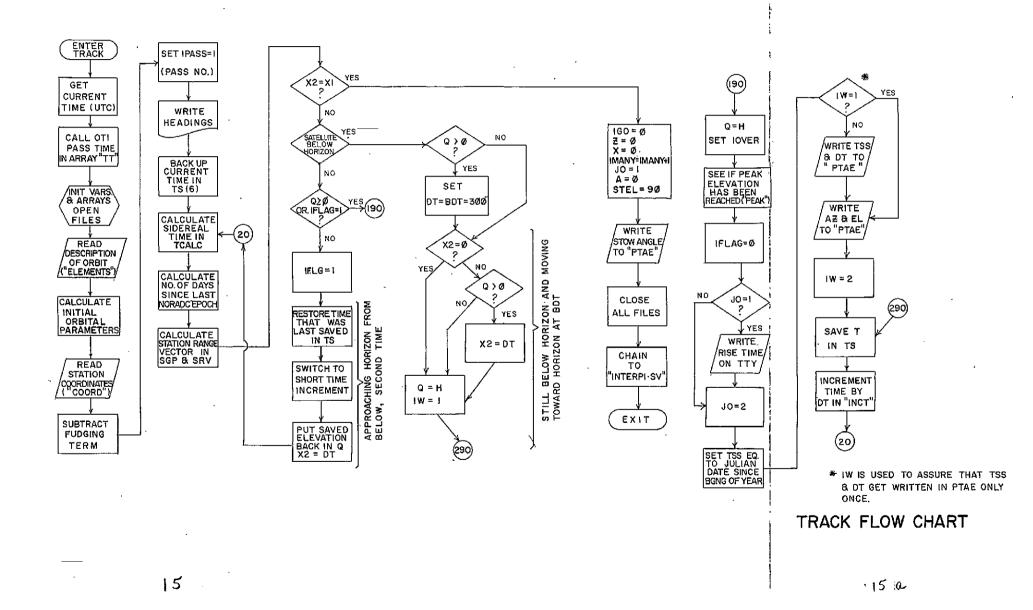
Normally, entry to the tracking system is by execution of the program TRACK, a FORTRAN program which calculates pairs of azimuth and elevation angles to LANDSAT from NED. TRACK starts with the current time and keeps incrementing it until it calculates that the satellite would be above the horizon. In other words, it projects into the future from the current time in the computer's real-time clock.

After the current date and time are input to TRACK, they are converted to Sideral time. This is done by a subroutine called TCALC. Sidereal time is a relationship between the constellation ARIES (γ) and the Greenwich prime meridian. Specifically, it is an angle between the Greenwich prime meridian and the inertial X-axis which points toward the first point of ARIES (Escobal, p. 20)*. This angle is denoted by θ . This angle is called the local sidereal time. Knowing the east longitude (λ e) of an observer's station and, θ g (Greenwich Sidereal time) θ can be easily determined. This is given by $\theta = \theta g - \lambda e$, where $\theta < \theta \leq 2\pi$ (Escobal, p. 20, Eq. 1.26).

*See Appendix F for literature cited.

FOLDOUT FRAME

SULLIT FRAME 2



To find the sidereal time, the Julian Date (J.D.) must be calculated. The Julian Date is a continuing count of each day elapsed since some arbitrarily selected epoch. The epoch selected for LANDSAT orbital predictions in TCALC is January 1. 4713 B.C. Each Julian Date is measured from noon to noon; hence, it is an integer 12 hours after every midnight (Escobal, page 17). After the Julian Date and sidereal time are calculated, the next thing found is TSINCE, the number of days since the most recent NORAD EPOCH. TSINCE is then used to determine the unit vector pointing toward the satellite (see SGP of this text). These unit vectors are in turn converted to azimuth and elevation angles at the observer's station (degrees clockwise from north and degrees above the horizon, respectively) (see SRV of this text). These two values and the times at which they occur are then written on the disc under the file name PTAE. The Time of interest is then incremented seconds or minutes by the routine INCT, and the next values of AZ and EL are determined, etc. In this incremental fashion, the computer is able to predict the path of the satellite across the sky at the observer's site.

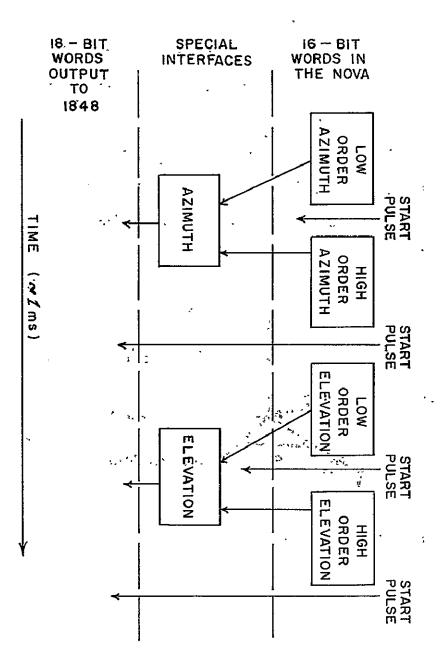
The name PTAE stands for <u>Paper Tape Azimuth Elevation</u>. The file can be transferred as it is to the paper tape punch by the teletype command, "XFER/A PTAE \$TTP". This will cause a paper tape to be generated that is suitable for input to the paper tape reader on the pedestal control equipment.

PTAE is a disk file which comprises a time, a time increment, and many pairs of azimuth and elevation angles. The file is ended with a special file terminator. An example of PTAE is shown in Appendix C.

TRACK calculates azimuths and elevations at 10-second increments, so the angle pairs in PTAE are pointing angles for instants 10 seconds apart. If these angles were fed to the tracking pedestal, the antenna would jump quickly to the next position every 10 seconds. The progress of the satellite is smoother than this jumpy motion, and it has been found that one-second incrementing is sufficiently small for constant satellite acquisition. Therefore, the program INTERP1 is executed right after TRACK to interpolate ten angle pairs for every one pair in PTAE. Furthermore, INTERP1 recodes the angles from ASCII characters to a binary coded decimal (BCD) format suitable for the electronic interface enroute to the command equipment. The new angles are stored in a binary file called BCDAZEL, and the number of angles in BCDAZEL is stored in the file NANGLES.

The recoding is done by bit-mapping in the program INTERP1 (q.v.); the assignment of angular values to bit positions is shown in Figure 8. A set of special interfaces, built by Robert Snyder of NASA Wallops, is used to route the BCD angles from the NOVA to the 1848 Digital Comparator (see Figure 1). Input to the 1848 is

in the form of Two 18-bit BCD words representing azimuth and elevation. However, the NOVA can output only <u>16-bit</u> words, by way of the 4065 Digital Interface. For this reason, it was ______ necessary to concatenate two pairs of 16-bit words into two 18-bit; words as shown below (see also Figure 8):



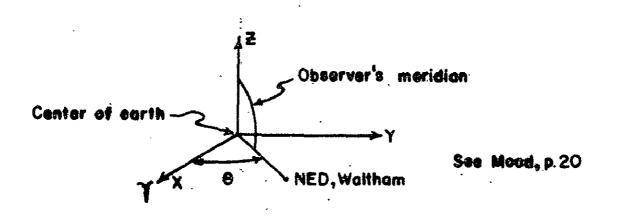
· TCALC. ·

TCALC is a time handling routine which calculates the following three variables:

1. XJD - No. Julian days; it is used to find TSINCE and THETA (Escobal, Pgs. 20, 21, 22).

2. TSINCE - No. of days since most recent NORAD EPOCH. This is used by SGP to find the unit vector pointing toward the satellite (RDOT).

3. THETA, $\underline{0}$ - Sidereal time (measured in radians) - the angle between a line from the center of the earth to the first point of the constellation ARIES (γ), and the plane of observer's meridian.



THETA is used by SRV in determining Azimuth (A) and elevation (H).

EXPLANATION OF TCALC VARIABLES

EP = 2442413.5 = Number of Julian days from an original EPOCH to January 1, 1975. This EPOCH is January 1, 4713 B.C. (days).

TWOPI = $2 \mathbf{n} = 6.2831853072$ (no units).

LAMBDA E = East longitude from Greenwich to NED = 288.784332° (degrees). $\langle \lambda_e \rangle$

DTHDT = .25068447 - Constant used to account for one extra sidereal day for every tropical year (degrees/mim).

EPYR = DFLOAT (75) = An arbitrary year used as a reference (years).

XJD = Number of Julian days (days).

N = T(2)-1 = Number of months in year up to last month (months).DAYS IN MO (I) = Number of days in each month (days).

N = T(1)-1 = Number of years up to last year (years).

TSINCE = Number of Julian days at INSTANT, the time of interest (days).

INSTANT = Future prediction times, or the times of interest
(year, month, day, hour, minute, second).

DT = The number of hours, minutes, seconds which T, the time of interest, is incremented for successive executions of TRACK.

TU = Time since January 1, 4713 B.C.; used to find THETA G \emptyset (centuries).

THETA GØ = Greenwich Sidereal time at Ø hour of a particular date (degrees).

THETA G = Greenwich Sidereal time (degrees).

THETA - Sidereal time at NED, Waltham. (degrees).

SAMPLE CALCULATION OF SIDEREAL TIME

August 23, 1975, at 10 hours, 15 minutes, Ø seconds; Number of hours, minutes, seconds expressed in minutes: DT = 615 minutes. XJD = 2442648.5 DTHDT = .25068447 TU = (XJD-2415Ø2Ø)/36525 = .7564271Ø47227926 THETA GØ = 99.6909833 + (36ØØØ.7689) (TU) + (.ØØØ38708) (TU)² = 331.6485916Ø1549Ø

THETA G = THETAGØ + (DT) (DTHDT) = $125.81954\emptyset651549\emptyset^{\circ}$

THETA = (THETA G + LAMBDAE) $\binom{21}{360}$ = .9530184529430946

radians

SGP is a FORTRAN subroutine embodying a truncated simplified general perturbation theory for use in the determination of i LANDSAT pointing elements. SGP computes osculating position, velocity and mean classical elements. SGP is a first order analytical integration of the equations of motion including perturbations caused by the first two zonal harmonics of the geopotential. The zonal harmonic constants account for the effects of the non-circularity of the meridian cross sections of the earth. The perturbations caused by these harmonics are independent of the longitude of the satellite. SGP is based on the orbital elements a, AXN, Ayn, i, Ω , and L which are well defined for all elliptic orbits except those that are nearly equatorial. For equatorial satellites, the elements Axn and Ayn are ill-defined because of the indeterminacy of the node angle ${\cal N}$ to which they are referred. The SGP mathematical model is adequate to handle a majority of routine cataloguing. Accuracy is said to be better than one part in 10⁹.

SGP

SRV

SRV (Slant Range Vector) is a FORTRAN subroutine of TRACK which transforms the orthogonal vectors and the time angle, THETA, from subroutine SGP into an azimuth/elevation coordinate system with the observer's station as the origin. Files of azimuth and elevation angles in this coordinate system describe the path of LANDSAT over a particular station during some interval.

TRACKING THE SATELLITE: PROGRAM LS1

After TRACK has predicted the satellite's path across the sky and prepared a file of pointing angles, it chains automatically to the program LSI which will perform any of over six main functions. It is a complex multi-tasking program which defies flowcharting, because program internal control shifts according to time as counted down by the Real Time Disc Operating System (RDOS) and according to real events in the outside world.

Typically, LS1 carries out the following main tasks:

1. Schedules itself by looking at the starting time of the upcoming pass. This time is the first number stored in the disk file BCDAZEL.

 Orients the antenna 1-1/2 minutes before the satellite rises.

3. Starts repositioning the antenna second by second beginning at the instant the satellite rises; and simultaneously logs any data that arrives by way of the antenna/receiver/decoder pathway (see Figure 1); and also simultaneously will accept corrections from the terminal to advance or retard some number of seconds. These corrections are made to improve antenna position.

4. Restores the antenna to the stow (upright) position when the last angle pair in file BCDAZEL has been sent.

5. Dumps the field data that have come in from core buffer to a temporary disk file called "SDF" (Satellite Data File).

6. Finally chains to a program called QD3 which will decode field data from binary to an octal format similar to one used by NASA at Goddard.

Note that once TRACK and INTERPI have been executed for an upcoming pass, LSI can be run at any time up to one minute, 40 seconds before satellite rise time. Execution of LSI after that causes problems which are signalled by a "W" being printed at the terminal. One then has to quickly reset the system clock; execute LSI; and when the computer eventually types ":", enter positive corrections that stand for numbers of seconds to enable LSI to catch up with real time.

If further knowledge of LS1 is desired, the program itself is the best source. The original source code is copiously annotated with explanations of individual steps.

OUTPUTTING DATA: QD3 and P3

QD3 and P3 are programs that condition the raw field data received by the ground receive antenna for disk storage or legible output.

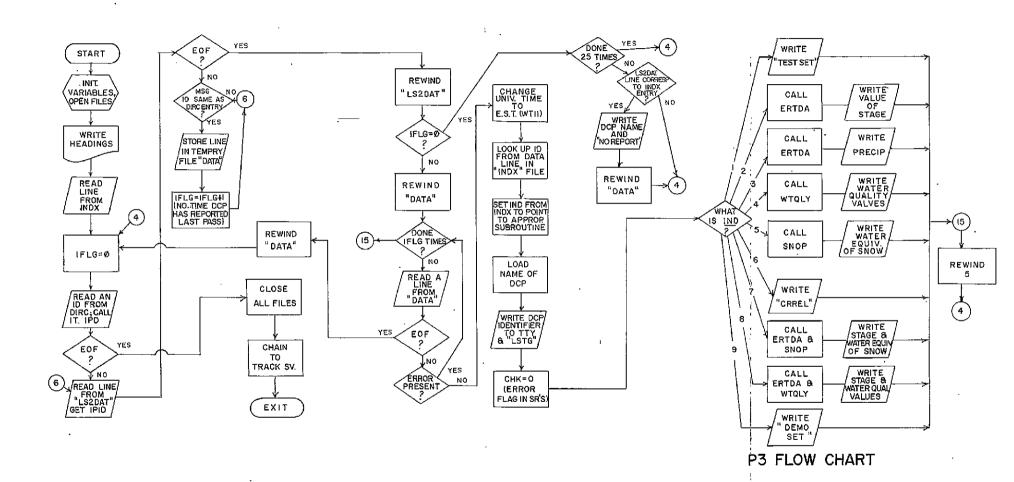
QD3

Output to QD3 is the disk file "SDF" which was produced by LS1 immediately after the last satellite pass. Output from QD3 goes to a temporary file "LS2DAT" and a permanent file "STORAGE". These file formats are shown in Appendix C.

The arrival time of each DCP message is recorded by LS1 by storing a seconds counter with each message. This number of seconds is accumulated from the beginning of each pass, and QD3 calculates a message arrival time by adding the number of elapsed seconds to the starting time. The arrival time (Y, M, D, H, M, S) is then stored with each message. The time used is Coordinated Universal Time.

P3

Legible output of DCS data is obtained by executing P3. Input to P3 is from temporary disk file "LS2DAT". Essentially, the program examines each message for the platform ID number. looks up the ID in a table, and decides how to interpret the data on the basis of indices in the table. These indices then direct program control to appropriate subroutines for calculating decimal numbers and attaching labels. The kinds of parameters handled by P3 are shown in the sitelist, Figure 9.



FOLDOUT FRAME

 $\gamma_{\rm c}$

APPENDICES

- A. History and Background of LANDSAT Program at NED[,]
- B. Figures
- C. Computer File Formats
- D. Glossary
- E. Program Listings
- F. . Literature Cited and Related Documents

APPENDIX A

HISTORY AND BACKGROUND OF LANDSAT PROGRAM AT NED

Since the Industrial Revolution in the 1800's, the rivers of New England have been developed to supply water for power and transportation. As new means of transportation became more economical, both railroad and highway systems were built along the banks of the rivers to service the expanding needs of the industrial, commercial and urban centers. Structures, such as buildings, roads, bridges and dams have restricted floodways to such an extent that considerable property and environmental damages have occurred during moderate and major floods. Notable floods of November 1927, March 1936, September 1938 and August 1955 have demonstrated the need for flood control to prevent these natural catastrophes.

At the direction of Congress, the U.S. Army Corps of Engineers developed a comprehensive plan of protection for each river basin after a careful analysis of all water resources. Protective works generally consist of a combination of channel improvements, dikes and/or floodwalls at major damage centers augmented by upstream flood control reservoirs. Many of these reservoirs contain additional storage reserved for other uses such as water supply, conservation and recreation. The Corps has built 35 flood control reservoirs, 37 local protection projects and four hurricane barriers in New England at a total investment of some \$300 million.

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To achieve optimum operating benefits from this comprehensive protection system, the New England Division requires hydrologic data such as river, reservoir and tidal levels, wind velocity and direction, barometric pressure and precipitation.

In the past this data was collected from field observation and relayed via telephone or voice radio. It took several hours to compile and assess the data in this manner. With the need for timely and reliable information increasing, the Corps began development of new methods of data collection.

In 1970, the Automatic Hydrologic Radio Reporting Network was placed in operation. This ground-based radio relay system consists of 41 remote reporting stations, and a central control at Division Headquarters in Waltham, Massachusetts. This network, under computer programmed control, collects and analyzes, in real time mode, information which is essential for flood regulation. The remote reporting stations are strategically located in five major river basins and at key coastal points, with each contributing to a detailed, comprehensive hydrologic picture. LANDSAT

In June 1972, NASA entered into a contract with the Corps for an experiment to study the feasibility of using the Earth Resources Technology Satellite (ERTS or LANDSAT) for collection environmental

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data from Data Collection Platforms (DCP's) which are installed at 27 locations throughout New England. Many are situated at " existing U.S. Geological Survey gaging stations.

Since July 1972, LANDSAT has been relaying river stage, precipitation, and water quality data from DCP's via the Goddard Space Flight Center to the U.S. Army Corps of Engineers, New England Division, in near real time. This is the first resources satellite designed to obtain data from the planet Earth exclusively for planning, design, operations and research of land and water resources.

THE NED GROUND RECEIVE STATION

Since any operational satellite configuration serving an urgent function like flood control should include ground receiving stations at all major user locales, NED, with NASA support, constructed and is now operating an inexpensive semiautomatic and easily maintained ground receive station as a follow-up to its original study. The Division is now able to receive hydro-meteorological data from data collection platforms in the field directly at its headquarters in Waltham, Massachusetts with no time delays. The software to drive the antenna system has been developed with the intention that the antenna operate in an unattended mode automatically over nights and during weekends and holidays, with a computer controlling all processes. The major objective of the program has been to compare the effectiveness of the LANDSAT Data Collection System (DCS) with existing systems in aiding our watershed management functions.

Data collection platforms tested by the Corps have performed successfully in all seasons including the winter months and also during significant flood events, transmitting near real time operationally useful data for our flood fighting missions.

The satellite proved invaluable in April and early May of 1973 and 1974, monitoring flooding in Maine Rivers. LANDSAT relayed data from five river points in that State to aid the New England Division in the coordination of the flood emergencies.

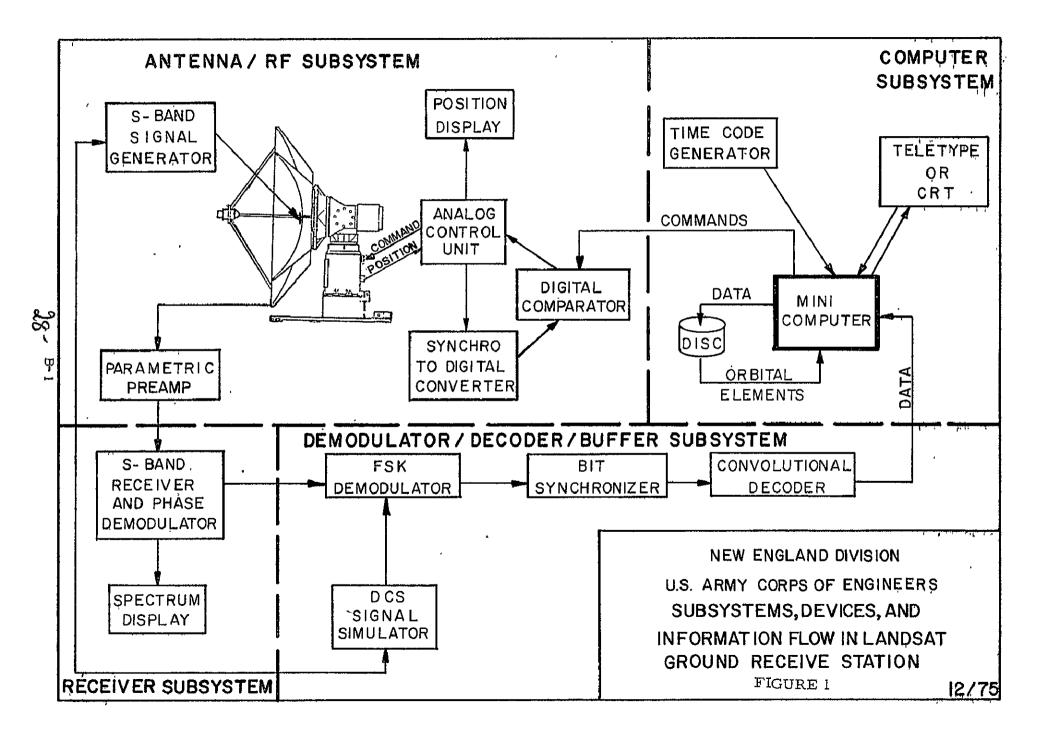
The successful testing of the LANDSAT Data Collection System at the New England Division should encourage serious consideration of the institution of an operational satellite data relay system on a Corps-wide basis. Such a system appears to be more costeffective than conventional ground-based data relay.

The New England Division is also making a study of satellite imagery to determine its usefulness in planning, designing and managing water resource systems. To obtain an overall broad coverage of ground conditions, imagery studies and measurements are being made of fluctuations in river, lake, and reservoir stages as well as tidal changes, icing of water surfaces, location and depth of snow cover, moisture content of the soil, and water quality para-

FLOOD CONTROL OPERATIONS

Data received at the New England Division's Reservoir Control Center from either the Automatic Hydrologic Radio Reporting Network or the LANDSAT Data Collection System is compiled by computer. This is augmented by information from other sources such as the National Weather Service Meteorologic and River Forecast Offices and the U.S. Geological Survey. Experienced engineers and hydrologists at the Reservoir Control Center analyze the data for timely operation of dams and hurricane barriers, and then issue instructions to operating field personnel.

Flood Control reservoirs, local protection projects and hurricane barriers built by the Corps in New England have been responsible for prevention of almost \$300 million in flood and storm damage.





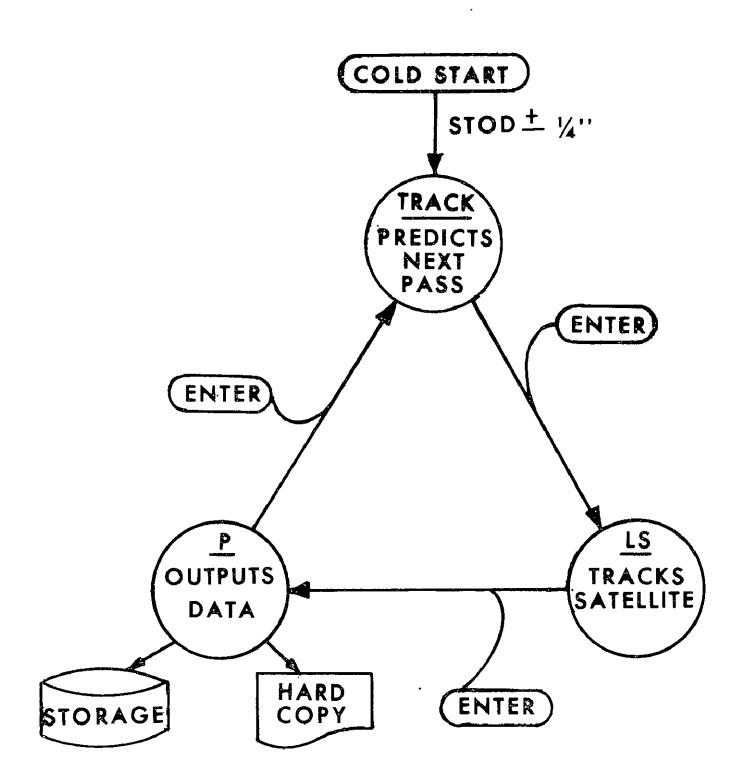
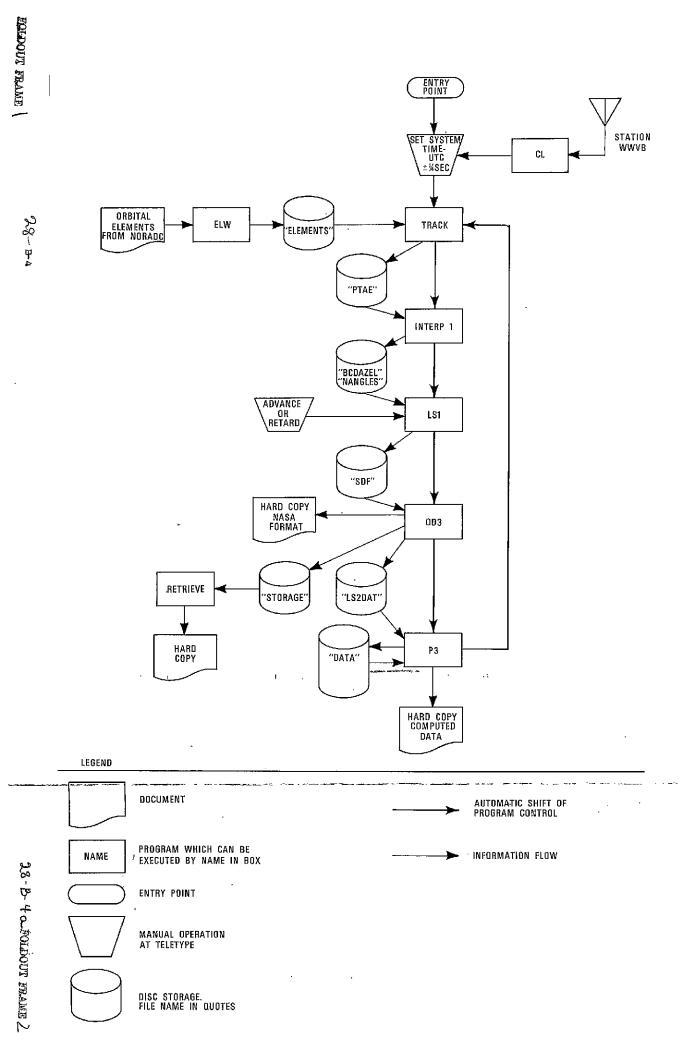


FIGURE 3



HOW TO ENTER ORBITAL ELEMENTS INTO SYSTEM

ARMY ENGRS WAL

GRIFFISS ROME S-9 710-324-6949 VIA 315-337-6275 MSG NBR 050857 R 050857Z DEC 75 FM SPACE DEFENSE CENTER ENT AFB COLO TO USA ENDE WALTHAM MA BT UNCLAS SDC-0 F050851 0819 DEC 75 NEDED-W/ATTN COOPER

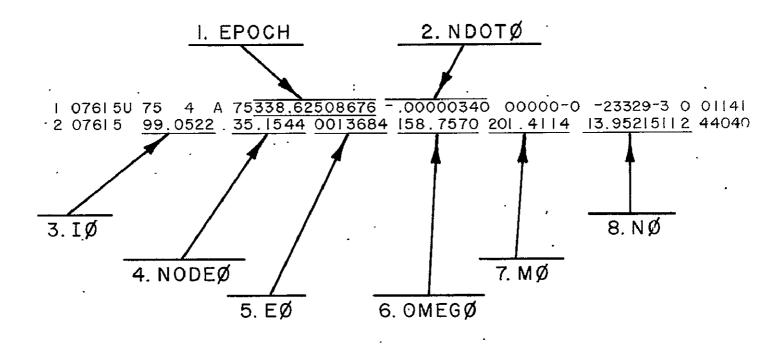


FIGURE 5 FORMAT OF ORBITAL ELEMENTS PROVIDED BY NORADC.

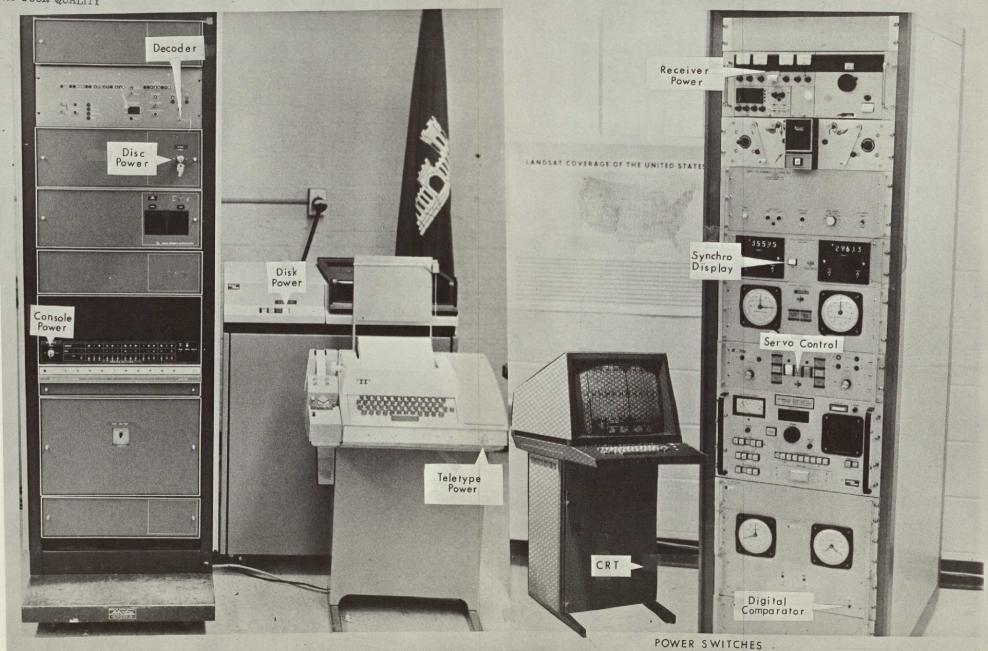
28- B-5

ELW) ENTER EPOCH, NDOTØ, 10, NODEØ, EØ, OMEGØ, MØ, NØ DO YOU NEED FURTHER EXPLANATION? YES OR NO NU ANSWER YES(Y) OR NO(N) TO OK? 71.22545099 71.225450990 OK?Y - 00000327 -Ø•ØØØØØ327Ø OK?Y) 99 . 0355 99-035500000 0K?Y} 130.8772 130-877200000 OK3A) •0011596 🏹 0.001159600 0K3A) 260 • 78 35 🕽 260- 783500000 OKTY) 99 • 1966 🆓 🗂 99.196600000 OK?Y 13.95212232 13.952122320 OK?Y) R

FI GURE 6.

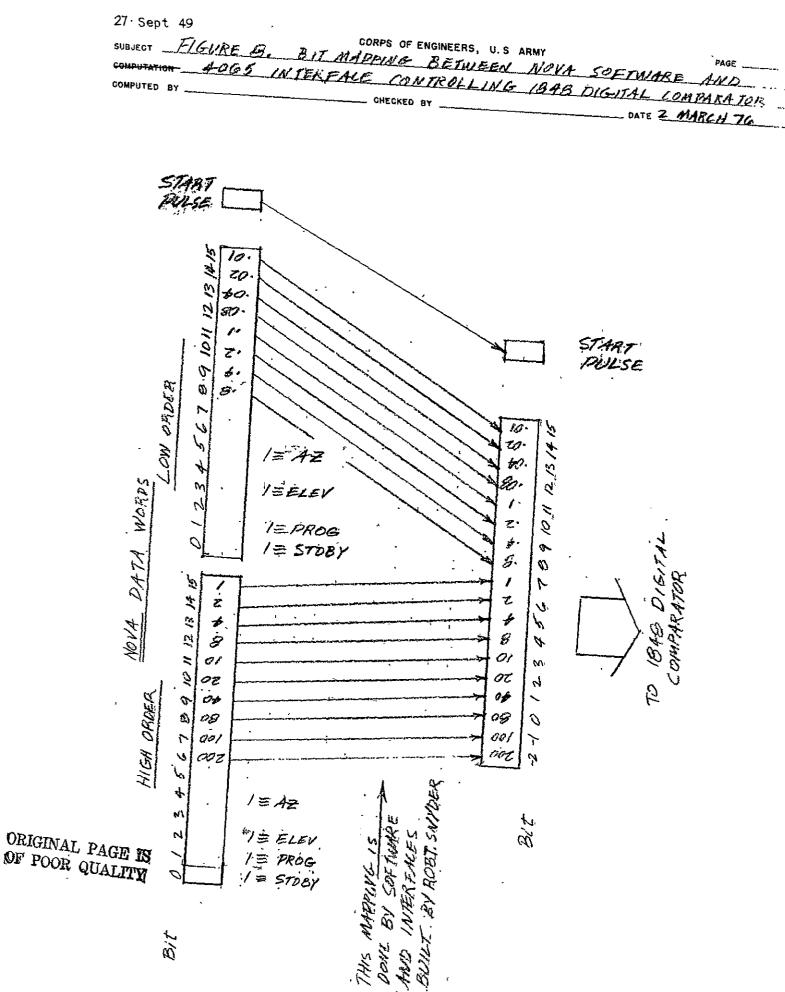
DIALOGUE BETWEEN OPERATOR AND COMPUTER DURING EXECUTION OF ELW. NOTE: "]" STANDS FOR RETURN.

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28-B.7

BOLDOUT FRAME 2 28-B-70



28- B-8

LANDSAT-2 - DCP INFORMATION SHEET U.S. ARMY CORPS OF ENGINEERS, NEW ENGLAND DIVISION 15 APRIL 1976 DCP STATION NAME PARA-LAT LONG METER(S)* NO. 7147 ST. JOHN RIVER AT NINEMILE BRIDGE, ME. 7101 ST. JOHN RIVER AT DICKEY, ME. 7355 MICHAUD FARM AT ALLAGASH FALLS, ME. 7273 ST. JOHN RIVER AT FORT KENT, ME. 7071 PENOBSCOT RIVER AT WEST ENFIELD, ME. 7272 CARABASSETT RIVER NEAR NORTH ANSON, ME. 7356 SACO RIVER AT CORNISH, ME. RS WES RS WG WES RS RS RS RS RS 46 42 00 47 06 44 46 57 05 47 15 27 45 14 12 44 52 09 43 48 35 699 425 699 11 699 11 758 699 57 66 699 46 -25 . 43 20 53 43 50 06 42 58 59 43 45 33 42 56 54 71 46 49 71 35 21 71 41 10 71 27 52 7271 STINSON MOUNTAIN, N.H. 7127 SOUTH MOUNTAIN, N.H. 7201 PEMIGEWASSET RIVER AT PLYMOUTH, N.H. 7233 MERRIMACK RIVER NEAR GOFFS FALLS, N.H. 7214,7331 COLD REGIONS LAB, HANOVER,N.H. ₽ Þ RS RS ŬÁRIÁBLE Ť 7246 WACHUSETT MOUNTAIN, MA. 6063 IPSWICH RIVER NEAR IPSWICH, MA. (1) 7106 NORTH NASHUA RIVER AT FITCHBURG, MA. 7142 CHICOPEE RIVER AT CHICOPEE FALLS, MA. 7021 WESTFIELD RIVER AT WEST SPRINGFIELD, MA. 7207 FRENCH RIVER AT WEBSTER, MA. ---- NED HEADQUARTERS, WALTHAM, MA. 299495333 444495333 444449 71 53 15 70 53 39 71 47 19 72 34 52 72 38 28 71 53 08 71 12 56 Þ. 24 35 RS RS UQ 34 37 UQ UQ 59 03 46 7012 BRANCH RIVER AT FORESTDALE, R.I. 7345 PAUTUXET RIVER AT CRANSTON, R.I. RS RS 41 59 47 41 45 83 71 33 47 71 26 44 7254 CONNECTICUT RIVER AT HARTFORD, CT. 7242 CONNECTICUT RIVER NEAR MIDDLETOUN, CT. 7206 PORTER BROOK NEAR MANCHESTER,CT.(2) 41 46 18 41 33 40 41 45 55 72 40 72 36 72 39 RS 84 RS 45 12 7124,6216 7042,7325 (3) RL AT GST GT WP (3,4) 7010,7304,7171,7220,7207,7335 SPARES P - PRECIPITATION WES - WATER EQUIVALENT OF SNOWPACK RS - RIVER STAGE RL - RESERVOIR LEVEL WG - WATER GUALITY (TEMPERATURE, CONDUCTIVITY, PH AND DISSOLVED OXYGEN) AT - AIR TEMPERATURE(S) GST - GROUND SURFACE TEMPERATURE GT - GROUND TEMPERATURE(S) WP - WIND PASSAGE PV - PARAMETERS VARIABLE T - TEST SET ×

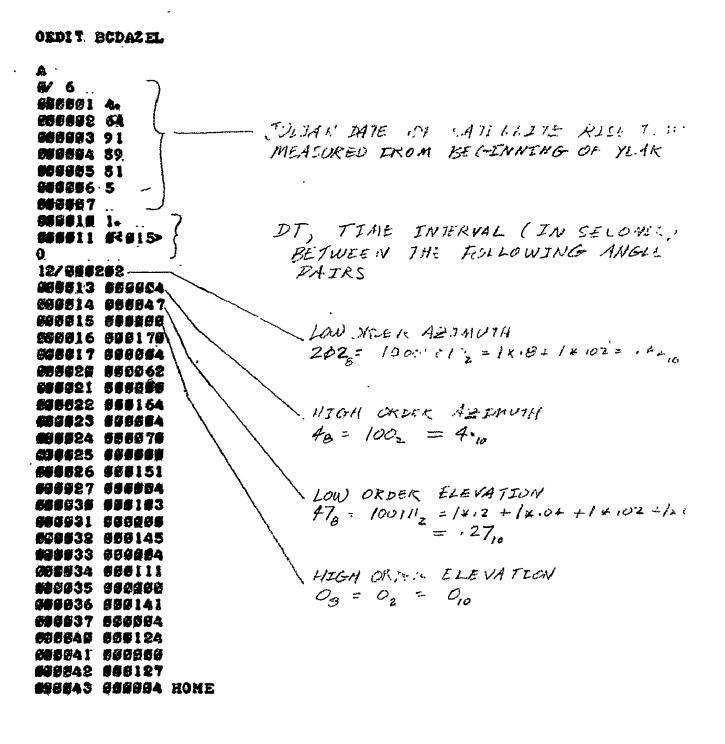
- (1) DCP BELONGS TO U.S. GEOLOGICAL SURVEY, BOSTON, MA.
 (2) DCP ON LOAN TO U.S. GEOLOGICAL SURVEY, HARTFORD, C1 -ON DEMONSTRATION AT THE MANCHESTER NATURE CENTER
 (3) DCP ON LOAN TO U.S. ARMY COLD REGIONS RESEARCH AND ENGINEERING LAB, HANOUER, N.H.
 (4) NOT YET INSTALLED MA. D. CT.-

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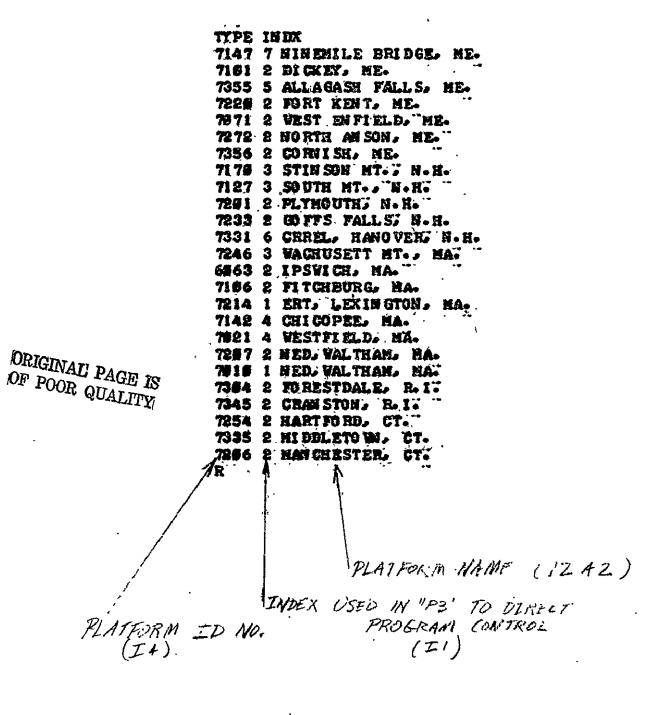
R

FIGURE 70. FILE FPE PTAE 54. 549159815	ORPS OF ENGINEERS, U.S. ARMY <u>FORMATS</u> <u>FILE</u> CHECKED BY <u>JULIAN DATE</u> OF <u>MEASURED</u> FROME CALENDAR YEAR.	DATE <u>BMARCH</u> 7 SATELLITE RISE TTO
PE PTAE 54- 549159815	JULIAN DATE OF MEASURES FROM E	DATE <u>BMARCH</u> 7 SATELLITE RISE TTO
PE PTAE 64- 649189815	JULIAN DATE OF MEASURED FROM E	SATELLITE RISE TTO
PE PTAE 64- 649189815	JULIAN DATE OF MEASURED FROM E	SATELLITE RISE TTO
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3-11E 2-52: 8-64E 3-16:	\backslash	
E-14E 3-751		
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NED FURM 220	NEW ENGLAND DIVISION	
,27 Sept 49	CORPS OF ENGINEERS, U.S ARMY	PAGE
SUBJECT FIGURE 76.	CORPS OF ENGINEERS, U.S. ARMY FILE FORMATS, FILE	"BCDAZEL"
COMPUTATION		
COMPUTED BY	CHECKED BY	DATE 5 MARCH 76

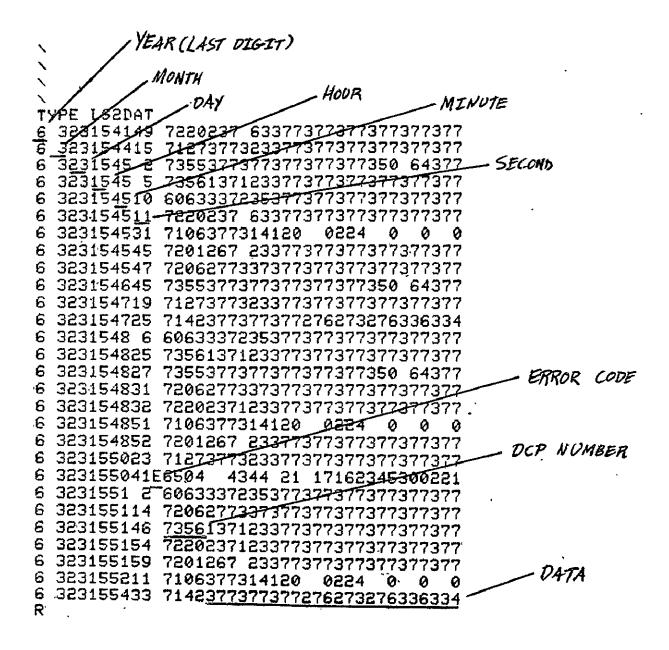


NED FORM 223 .	NEW ENGLAND DIVISION		
27 Sept 49	CORPS OF ENGINEERS, U.S. ARMY	H Telman H	PAGE
SUBJECT FIGURE TC.	CORPS OF ENGINEERS, U.S. ARMY FILE FORMATS. FILE	LNDX	
COMPUTATION		la a	An Sal
COMPUTED BY	CHECKED BY	DATE	MARY 1 - 100



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APPENDIX D - GLOSSARY

- ADR Anlog to digital recorder. Typically a Fisher-Porter or Leupold-Stevens recorder, equipped with a telekit.
- Azimuth Horizontal angle measured clockwise from north.
- BCD Binary Coded Decimal.
- Chain in programming, a call from one program to execute another, thereby terminating its own execution.
- Coordinated Universal Time an observer's local mean solar time plus the number of time zones the observer is <u>west</u> of Greenwich observatory, corrected for aberrations in the spin of the Earth.

Crash - (v.i.) - to cease functioning. Syn. bomb.

- CRT Cathode Ray Tube Specifically, the Tektronix 4014 terminal connected to the NOVA.
- DCP Data Collection Platform Field installation used for sensing parameters, encoding data, and transmitting data to satellite.
- Disc (or disk) medium for storage of data in the Data General Computer. Refers to twenty-surface disc pack and drive which is a peripheral device to the computer. Files on the disk are divided into two directories, "DPØ" and "USER". Most system programs are in DPØ, and most user programs are in USER.
- Elevation angle above the plane of the observer's horizon.
- Flowchart diagram that shows flow of control in a computer program. Elements shown are input, output, initializations, processes, decisions, and connectors.
- Julian Date an arbitrary benchmark that is a continuing count of each day elapsed since some particular epoch.
- Multi-tasking in a computer several program tasks competing for devices and the contral processor on a priority or queued basis.

Octal - refers to a number system that has 8 as a base.

- Sidereal Time the relationship between an observer's meridian and some inertial coordinate system, for example, one based on the constellation ARIES.
- Real Time Clock device in the Data General Nova Computer that consists of a crystal controlled clock and associated DG system software that are used (1) to keep track of date and time of day and (2) to provide for low resolution timing.
- Tracking keeping the antenna pointed at the satellite, and in conjunction with that, logging any incoming data.

Universal Time - see Coordinated Universal Time.

	50	READ(7,51)IT1(2) ;NG. TIMES TO EXECUTE
	ς	NOTE THAT IT1(2) IS THE LOC THAT IS MODIFIED BY TS
YPE LS1 LS1 CALLED BY INTERP1 OR EXEC'D BY ITSELF HAITS FOR SATELLITE RISE TIME - ZMIN, ORIENTS ANTENNA, TRACKS SATELLITE, LOGS DATA ACCEPTS CORRECTIONS, DUMPS DATA AT END OF PASS, STOWS ANTENNA IN UPRIGHT POSITION TURNS ON AND OFF CIRCUITRY IN COMMAND EQUIPMENT, CHAINS TO OD3 TDB 14 NOV 75 COMPLER DOUBLE PRECISION DIMENSION ID(3),IT(3),IT2(11),IT3(11),IT5(11), COMMON/KBL/IT1(11) EXTERNAL T1,T2,T3,T5 COMMON/KEY/KEY1,KEY2,KEY3,KEY4	51	FORMAT(16) XTIME=(TSINCE-IDINT(TSINCE))#24. IT1(4)-XTIME _STAPTING HOUR IT1(5)-(XTIME-DFLOAT(IT1(4)))#3600. ;SECOND WITHIN HOU IT1(6)-3 IT1(1)-100 CALL FOTASK(DUM,T1,IT1,IER,-1) IF(IER.NE.1)TYPE "F01",IEP IMIN-IT1(5)'60 ISEC+IT1(5)-IMIN#60+.1 WRITE(10,60)IT1(4),IMIN,ISEC WRITE(15,60)IT1(4),IMIN,ISEC
	60	FORMAT(* NEXT PASS AT *12.*:*.12.*:*.12)
KEY-'S APE USED TO PASS MESSAGES AS FOLLOWS: KEY1 T1 TO LS1 KEY2 T1 TO UG WG BACK TO T1 KEY3 T5 TO T1		IT2(2)=1;()PIENT ANTENNA ONCE XTIME=()TSINCE-ZMIN)-IDINT(T3INCE-ZMIH))*24. IT2(4)=IDINT(XTIME; IT2(5)==XTIME=DFL(AT(IT2(4)))*3600. IT2(6)=3
KEY4 TI TO UG TINE COUNTER		IT2/7)=0 IT2(11)=200
COMMON/IBLK/DAVSINMO(12) DATA DAYSINMO/31.,28.,31.,30.,31.,30.,31.,31.,30.,31., \$30.,31./		CALL FOTASK(DUN.T2.IT2,IEP,-1: IF(IER.NE.1)TYPE "FQ2',IEP IT3(2)=1 IT3(4)=IT1:4)
2MIN=1.5/1440. CALL DFILW(*SDF*,IER) CALL CFILW(*SDF*,2,IER) CALL OPEN(5,*BCDAZEL*,1,IER) CALL APPEND(15,*TLOG*,3,IER) CALL OPEN(12,*STARTANGLE*,1,IER) CALL OPEN(12,*STARTANGLE*,1,IER) CURDATE=0. CURTIME=0.		113(3)=111(5) 113(8)=0 113(1)=300 CALL FOTASK(DUM,T3,IT3.IER,-1) IF(LER.NE.1)TYPE "FO3',IER 1T5(2)=1 IT5(4)=IT1 4)
KEY2=0 KEY4=0 CALL TIME(IT,IER) IF(IER.NE.1)TYPE "TINERR".IER		IT5(5)=IT1(5) IT5(6)=10 IT5(7)=0 IT5(11)=500
CURTIME=DFLOAT(IT(1))+(DFLOAT(IT(2))/60.)+(DFLOAT(IT(3))/ #3600.) CALL DATE(ID,IEP)		CALL FOTASK(DUM,T5,IT5,IER,-1) IF(IER.HE.1)TYPE 'FOS',IEP IONE+0
IF(IEP.NE.1)TYPE *DE*,IER II=ID(1)-1		CALL REC(KEY1,IONE) CALL FDELY(120) _;WAIT FOP ANT TO RCH STOU POS.
D0.6 J=1,II CUPDTE=CURDTE+DAYSINM0(J) CURDTE=CURDTE+DFLOAT(ID(2)) IF((ID(3)/4x4.EQ.ID(3)).AND.(ID(1).GT.2))CURDTE+CURPTE+1. CURDTE=CURDTE+CURTINE/24. :CURPENT JUL TIME SINCE 1 JAN READ(5.10.END=100)TSINCE.DT		II+1 CALL ANT(II,II,II,II,II) ;TURN OFF CIRCUITRY CALL CLOSE(5,IER) CALL CLOSE(7,IER) CALL CLOSE(12,IER) URITE(10,70)
READ(5, 10, END=100) TSINCE, DT 9 FORMAT(F13.9, FG.1) IF(CURDTE.GT.364.) TYPE "RESET EP AND EPYR IN TCALC ON \$JAN, 1 SEE MOOD PAGE FOR MORE INFO" IF(CURDTE.LE.(TSINCE-ZMIN)) GO TO 50 ;TASK SCHEDULING TYPE UP OF OT THE STATE TO STATE TO STATE TO STATE TYPE	70	URITE(15,70* FORMAT(*) CALL CHAIN("QD3.SV",IER)
IF (CURDTE.LE. (TSINCE-ZMIN))GO TO 50 ,TASK SCHEDULING TYPE "U" ;TOO LATE FOR CURRENT PASS CALL CHAIN(TRACK.SU , IER)	100	IF(IER.NE.1)TYPE *CHER*,IER CALL EXIT
IF (IER.NE.1) TYPE *LSIRD', IER CALL EXIT		CALL CLOSE(15, IER) END
. VIII 6/641	R	

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TS ACCEPTS CORRECTIONS 2 ONIENTS, T3 GATHERS DATA č

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TYPE TI		35
C TDB 9	DEC 75	33
• • • • •	TASK T1	13
	COMMON/KEY/KEY1.KEY2.KEY3.KEY4	
	COMMON/KBLK/IT1(11)	
	DIMENSION I(4)	
	10-0	R
	KEY4-KEY4+1	Th
	IF(KEY3.GE.0)GO TO 10 KEY3+KEY3+1	
	IT1(2)*IT1(2)+1	
	GO TO 25	
18	READ BINARY(5)I(1)	R
	IF(I(1).EQ1)GO TO 30 ;EHD OF FILE?	÷Ϋγ
	READ BINARY(S)(I(J), J+2, 4) ;NO, GET 3 MORE \$'5 CALL ANT(I(1), I(2), I(3), I(4), I0) ;SEND THEM TO ANT	.1
	CALL ANT(1(1),1(2),1(3),1(4),10) ;SEND THEM TO ANT	
	IF(KEY3.LE.0)GO TO 25 JADJUST IF NECESSARY	- 18
	KEY3-KEY3-1	t
	IT1(2)-IT1(2)-1 G0 TO 10	1
25	CALL KILL	Ĵ,
30	CALL XMT (KEY2, 1, \$50) ; TELL UG TO DUMP TO DISC	κ L
50	IONE=0	
	CALL REC/KEY2, IONE: ; WAIT FOP WG TO FINISH	59
	CALL XMT(KEY1,1,\$50) ;TELL LSI EOF HAS BEEN REACHED	FS
	CALL KILL	άĥ –
50	TYPE "XMTERRI"	- S1
	CALL EXIT	L
	END	M.
R TYPE T2		JP
C TDB 8/	17 /75	LI
C 100 G/	TASK T2	- 51
	DIMENSION J(4)	L
	CALL APPEND(15, "TLOG", 2, IER)	- 840
	10-0	- LI - C(
	READ BINARY(12)J ;GET FIRST ANGLE PAIR	- ĂĤ
C	FROM "STAPTANGLE"	- Öč
	IPOINT=1	Ĩ
10	GO TO 100 ; GO SENIE PAIR	
10	CALL FDELY(30) ; WAIT FOR ANTENNA TO GET THERE	D D C
	DO 20 I-1,21 ;SEND ANTENNA CCU TUICE	I
	READ BINARY 121J IPOINT+2	Ĩ
	GO TO 100	าเ
15	CALL FDELY(21)	B
29	CONTINUE	38
	GO TO 21	OF
		ĎC
100	CALL ANT(J(1), J(2), J(3), J(4), I0)	ĴĨ
	WKIE(15,120)	
120	WRITE(10,120) FORMAT(2,12)	_ jI
~~~	FORMAT(2 . (.2) 60 TO (10.15 PE 25) TROINT	- Þi
21	GO TO (10,15,25,35), IPOINT DO 39 I-1,9 , SEND ANTENNA CU ONCE	- A1
•	DO 30 I-1.9 SEND ANTENNA CU ONCE READ BINARY(12)J	89 84
	IPOINT-3	83
36	GO TO 100	Ba
3	CALL FDELY(21) CONTINUE	Be
~	READ BINARY(5) J +FIRST LOOK ANGLE.	
¢	READ BINARY(S)J FIRST LOOK ANGLE, THEN CONTROL GOES TO TI	R
	IPOINT-4	<u>i</u>
	GO TO 100	T
		1.

WRITE(10,130) WRITE(15,130) FORMAT(* 1*) 35 30 CALL KILL CALL CLOSE(15, IER) END YPE T3 TASK T3 CALL UG CALL KILL END TYPE ANT .TITL ANT .ENT ANT .EXTD .CPYL,.FRET -HREL I=-167 :LO AZ J=I+1 :HI AZ K=I+2 :LO EL L=I+3 :HIEL • 9=]+4 S.=5 ;PROG STDBY SUITCH ANTIJSR O.CPYL STA 3 RTN ida o em 3 NOU Ó Ó SZR ;TUPN OFF PELESTAL? JMP OFF ;YES LDA O ATE ;NO, SEND ANGLES STA 0 TTB LDA 2 CN4 MOR: LDA 0 EI 3 DA 1 GTTB 0M 0 0 AND 1 0 COM 0 0 SZ TTB . DOAS O DUC INC 3 3 INC 2 2 SIR JMP MOR BKI LDA 3 PTH ISR C.FRET FF: LDA 0 BC IMP BK DATA AREA VC=42 TB: +1 85: 135777 ;081+085 84: 133777 ;081+084 83: 127777 ;081+083 82: 117777 ;081+083 82: 117777 ;081+082 80: 180+182 ₹TN#.-. . N41 -4 TB:--

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TYPE HG TITL UG ENT UG EXTN .UIEX, REC, IXMT, TASK, AKILL, XMT .COMM KEY 4 JLABELLED COMMON AS IN LS TXTM 1 NREL DEVICE CONTROL TABLE------DCT:.-. 187 15042 _____ INTERRUPT SERVICE ROUTINE RESPONDS TO ONLY ONE INTERRUPT FROM 4065 INTEC. LOADS 5 WORDS IN A ROW AS FAST AS DECODER PROVIDES THEM. TIMING MATCHES DECODER'S EXACTLY ISR42: NIOC DUC STA 2 URTH2 STA 3 URTH3 LDA 0 SYNC JSR C. TOBUF LDA 1 CNS MOR: DIA 0 DVC JSP 0.TOBUF JSR TMP INC 1 1 SZR JMP MOR .TOBUE: TOBUE TOBUF: LDA 2 0.MEP STA 0 0 2 INC 2 2 STA 2 C.MEP JMP 0 3 TMR: LDA 2 CN15 INC 2 2 SZR JMP .-1 JMP 0 3 OUT: LDA @ OBNESS ;GET TIME COUNTER . LDA 2 C.MBP STA 0 0 2 ;STORE TIME WITH MSG INC 2 2 STA 2 0.MBP SUB 1 1 LDA 2 URTN2 LDA 3 URTN3 NIOS DUC -UIEX *********** URTN2: .-. URTH3: .-.

SYNC: 12214 CN5: -5. CN15: -15. CN2100:-2100. CTR: -.MEP: MBP UGIJSR 8.CPYL STA 2 AC2 STA 3 AC3 SUB 0 0 :GEN A Ø LDA 2 CN2100 STA 2 CTR LDA 2 PBUF STA 0 0 2 ; INIT BUFFEP TO ALL 0'S 192 CTP JMP .--5 LDA Ø DVCN DEFINE 4065 DIGITAL I O BOARD TO SYSTEM LDA 1 IDDCT .SYSTM IDEF JMP E.ERT SYSTM • GDAY JIAP .EPT MOU 2 3 ;NEXT 7 LINES STUPE VP,MO.DAV IN SDF LDA 2 PBUF STA 2 NEP STA 1 0 2 INC 2 2 STA 0 0 2 INC 2 2 STA 2 MBP .57571 GTOD JMP @.EPT MOU 2 3 :NEXT 7 LINES STOPE HR,MIH,SEC IN SDF LDA 2 8.MEP STA 3 0.2 THC 5.5 STA 1 0 2 INC 2 2 STA 0 0 2 INC 2 2 STH 2 C.MEP LDA 0 AMESS SUB 1 1 NIOS DUC REC WAIT HERE FOR LAST LOOK ANGLE TO BE SENT .SVSTN .IRMU JNP C.EPT LDA 0 ASDF ; POINT TO FILE NAME SUB 1 1 ; DEVICE CHARS .SYSTM APPEND 6 INP 0.ERT LDA.0 PBUF NOVZL 0 0 ;BYTE POINTER LDA.1 C4200 ;BYTE COUNT .SYSTN URS 6 ; DUMP THE BUFFER

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JMP C.ERT TPRI .SUSP - JSR e. .SYSTM TPEHD .CLOSE 6 JMP C.ERT LDA 2 AC2 LDA 3 AC3 .IDST - JSR @. TIDST .TIDS = JSR . LDA 0 AMESS SUBZL 1 1 STID TIDR - JSP 6. -XNT RTID JHP 6.ERT TIDE - JSR 8. JSR 0 FRET KTID .TIDP - JSR 8. IDATA AREA-----.AKILL - JSR 0. AC2:.-. TAKIL .ASUSP - JSR . AC3: .-. .ARDY = JSR @. ASDF: .+1#2 .TXT 'USER:SDF' ;SATELLITE DATA OUTPUT FILE TAUNP C4200: 4200. :EQUIVALENT RDOS CALLS .PEND * .SUSP DUCN:42 .APEND = .ASUSP DVC=42 MBP:0 ;MOUABLE BUFFEP POINTER .AUNPD - .ARDY MBP:0 .END ERT: .SYSTM R .ERTN ١ PBUF:BUF ٩. BUF: .BLK 2100. : BUFFER FOR 300 MSG#7HDS/MSG .END UG GTOD R 3/23 76 16:4:50 R TYPE TASKCALL .TITL TASKCALL .ENT .TASK,.XMT,.XMTW,.REC,.KILL,.OVEX,.TOULD .ENT .OVREL,.OUKIL,.ATSK,.PRI,.SUSP,.PEND,.IDST .ENT .TIDS,.TIDR..TIDK,.TIDP,.AKILL,.ASUSP ₽ .ENT .ARDY, .APEND, .AUNPD .EXTN CTASK, XMTT, XMTTU, RECC, KILL, TOVEX, TOULD. TOURL, TOUKL .EXTN TGTSK, TPRI, TPEND, TIDST, STID, RTID, KTID, TIDP .EXTN TAKIL, TAPEN, TAUNP .ZREL .TASK = JSR . CTASK .XMT - JSR e. XIIIT .XMTU . JSR . XMITTU REC - JSR C. RECC .KILL . JSR 0. KILL OVEX JSR Q. .TOULD = JSR 0. TOULD .OUREL = JSR G. TOURL .OVKIL . JSR . TOUKL .QTSK = JSR 4. TOTSK .PRI + JSR 0.

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28-E-4

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XMU=11467.25298 TYPE TRACKLOAD RLDR TRACK OTI TOALO SGP SRV INCT SEMI EXANN PEAK / AH=(XMU/XHN**3)**Y/ DD=-1.5#XJ2#((1./AA)##2//((DSOPT(1.-EE##2))##3) GARB/L FORT.LB;DELETE/C GARB DD=DD#(1.-1.5#(DSIN(XII))##2) SEMI = AA#(1.+YY*DD-YY*DD**2) TYPE TRACK PETURN TDB 4DEC75 C END OF POOR OF COMPILER DOUBLE PRECISION DIMENSION TT(6), ID(3) TYPE INCT C TOB 2 28,75 CALL FGTIM(I,J,K) TT(4)=1 COMPILER DOUBLE PRECISION TT(5)=J SUBROUTINE INCT(T, DT) TT(6)-0 DIMENSION T(6) CALL DATE(ID, IER) COMMON/IBLK/DAYSINMG(12) TT(1)=ID(3) QUALITY IF(DT.GE.60.)CO TO 600 TT(2)=ID(1) T(6)*T(6)+DT : INCR SECONDS IF(T(6).LT.60.)GO TO 350 TT(3)=ID(2) CALL OT1(TT) T(6)=T(8)-60. RESET SECONDS IF(DT.GE.60.)T(5)=T(5)+DT.60. END 600 R IF(DT.GE.60. 000 TO 700 -T(5)-T(5)+1 :100 MINUTES TYPE TCALC C TDB 2/28/75 700 IF(T(5).LT.60. 000 TO 350 COMPILEP DOUBLE PRECISION T(S)-T(S)-60. RESET HINUTES SUBROUTINE TCALC(T, TSINCE, THETA, LAMEDA E) T(4)=T(4)+1. ; INCR HOUP IF(T(4).LT.24. GO TO 350 REAL LAMBDAE DIMENSION T(6) COMMON / IBLK / DAYSINMO(12) -EP=2442778.5 ,1 JAN 76 TUOPI=6.2831853072 T(4 -T(4 -24 ;PESET HPS 1=T(2) ;PTP TO MO T(3)=T(3)+1. ; INCP DAY IVR=T(1) DTHDT*.25068447 ;DTHETA/UT ILEAP=0 EPYR*DFLOAT(76) IF(I.EO.2.HND.IYP 4#4.EQ.IYP ILEAP+1 DAYSINHOU2 =28+ILEHP XJD=EP+(T(1)-EPYR)#365. ;ADD 365 DA/YE THRU LAST YR H=T(2)-1. IF:T(3).LE.DAVSINNO:1()G0 T0 350 DO 50 I=1,N ;DAYS IN MONTH THRU LAST MO T:3:1:1. ;PESET DAYS DAYSINMO:2:=28. ;PESET FEP T/2:=T:2:+1. ;INCR MO IF(T:2:.LE.12.:GO TO 350 KJD+XJD+DAYSINMO(I) 50 . CONTINUE N=T(1)-1. ;N=LAST VR DO 100 1=75,N ;CHECK FOR LEAP VPS THPU LHST VR T(2)=1. ;RESET NO T 1)=T(1)+1. ;INCR VR IF(1/4#4.NE.1 GO TO 100 XJD=XJD+1. RETURN 100 CONTINUE 354 N-T(1) NOU LOOK AT THIS VR IF(N/4*4-NE-N)GO TO 200 :IS THIS NOT H LEAP (P? END IF(T(2).LE.2.)GO TO 200 ;ARE WE BEYOND 2/294 XJD-XJD+1. ;YES, ADD A LEAP DAY TYPE EXANN TDB 2/28 75 COMPILER DOUBLE PPECISION 200 XJD=XJD+T(3) JULIAN DATE AT INSTANT DOUBLE PRECISION FUNCTION EXAND: XMM, ECC) COMPUTES ECCENTRIC ANOMALY USING KEPLER'S EQUATION TSINCE+XJD+T(4)/24.+(T(5)+T(6)/60.)/1440.-EF TUOP1+6.2831853072 DT=T(4)*60. + T(5)+T(6)/60. ;(HR,HIN,SECS' AS MINS TU-(XJD-2415020.0)/36525. THETA_G0-DHOD((99.6909833+(36000.7659*TU)+.00033702* EXAMM*DHOD(XMM, TWOPI) DO 10 I+1,50 \$TU\$\$27,360.) AA=ECCXDSIN(EXANM) THETA G=DMOD((THETA G0+DT*DTHDT),360.) DELM=XMM-EXANM+AA С SIDEREAL TIME IN RADIANS ZZ=1.-ECC*DCCS(EXANM DELE'=DELM '(ZZ+((.5+DELM)/ZZ)#AA) IF(DABS(DELE)-1. )30,30,20 THETA=(DMOD((THETA G+LAMBDA E),360.))*TUOPI/360. RETURN END 20 DELE=DELE/DABS(DELE) 9ê EXANM-EXANM+DELE TYPE SENI IF(DARS(DELE)-.000001)40,10,10 TDS 2/28/75 C CONTINUE 10 COMPILER DOUBLE PRECISION CONTINUE 40 DOUBLE PRECISION FUNCTION SEMI(EE, XNN, XII) RETURN COMPUTES THE REAN (KOZAI) SENI-MAJOR AXIS OF A SATELLITE END YY=.33333333333 R XJ2=.00108248 GTOD

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TYPE OT 1 TDB 4DEC75 C COMPILER DOUBLE PRECISION SUBROLLTINE OTI(T) DIMENSION T(6).TS(6) REAL 10, IM, NO. NDOTO, NO. NODEO, NOBEM, LM, NM, NBOTM, LLONG, ... EXTERNAL SEMI EXTERNAL SENI INTEGER VR COMMON EPOCH, YR, NO, NODEJ, OMEGO, NDOTO, SAM, EM, IM, NODEM, OMEGH, LM, NM, NDOTM, EO, NO, IO, LO, AO, SELONG, LLONG, EXLNG, OMEGL, TRUEU, RMAG, RDOT, NODDT, OMGDT, SUX, UY, UZ, PX, RY, RZ, RDOTX, RDOTY, RDOTZ COMMON/IELK/DAYSINMO(12) DATA DAYSINH0.'31.,28.,31.,30.,31.,30.,31.,31.,31.,30.,31., \$30..31./ CONV-.01745329251 1DEGREES TO PADS ICOUNT .0 J2- 00108248 0=-1. J0=1 AE+t. TMANY-9 X2-0. 2-0 X=0 IU=1 IW-1 TWOPI-6.2831853072 CALL APPEND(15, "TLOG',3, IER) IF(IER.NE.1)TYPE 'TLER', IER CALL OFEN(5, "ELEMENTS',1, IER) CALL OFILW('PTAE', IER) CALL (FILW('PTAE',2, IER) CALL OPEN(4, "PTAE',3, IER) IF(IER.NE.1)TYPE 'DE', IER FROM NOPED C INPUT FPOM NORAD READ(5)EPOCH, NDOTO, 10, NODEO, EO, OMEGO, NO, NO ONEGO-OMEGOTCONY IO=IOACONU HODEO-HODEO+CONU M0=M0*CONU NO-HOTTUOPI NDOTO-NDOTO*TUOPI CALL CLOSE 5, IEP) IF(IER.NE.1 TVPE *CE*,IER L0*M0+NODE0+ONEG0 H0-SENI(E0,10,10) TEMP+1.54N0* J2*(HE/(A0*(1.-E0**2)) **2 NODDT -- TEMP (DCOS (TO) ONGDT-TEMP*(2.-2.5*(DSIN(10))**2) BDT-300. SD7 10. DT+BDT X1=DT CALL OPEN(8, COORD , 1, IER) IF (IER.NE.1) TYPE 'COE', IER READ(8) LANBDA E, GICSPHI, G2CSPHI, SMPHI, CSPHI, G2SNPHI LANBDA E-LAMBDA E-.99077 ;E.L. CORR TO COINCIDE UITH ĉ NORAD PREDICTION IPASS=1 WRITE(10,69) URITE(15,69) FORMAT( SATELLITE RISE TIME 69 PASS 8 PERK DURATION*) DO 25 1-1.6

25 TS(I)+T(I) žă CALL TCALCIT, TSINCE, THETA, LANEDA E) TSINCE-TSINCE-EPOCH ; NO. OF DAYS SINCE MOST RECENT NORAD Ċ ้รอดกม้ CALL SGP(TSINCF) CALL SRV THETA, H, A, GL(SPHI, G20SPHI, SNPHI, CSPHI, G2SNPHI) IF (X2.NE.X1)GO TO 889 TGD=0 Z=0 X=Ã IMANY=IMANY+1 J0 1 A-0.0 STEL-90.00 ;STON ANGLE URITE(4,339)H.STEL IF (IMANY .NE. IPHSS GO TO SOA CALL CLOSE 4. IEP / CALL CLOSE(8, IER) CALL CLOSE(15, IER) CALL CHAIN INTERPI.SUT, IEP. IF (IER ,NE.1)TYPE "LSCE" CALL EXIT CHECK TO SEE IF SATELLITE IS ABOVE THE HORIZON 339 X2-0 IF(H.LT.0.)60 TO 250 IF(0.GE.C.. OF. IFLAG.EQ. 1)60 TO 190 IFL4Ge1 DO 150 I-1 6 150 T(I)-TS(I) DT=SDT H=0 X2-nT GO TO 20 130 Q=H IOUER+1 CALL PEAK(IMANY, H, Z, Y, ICOUNT, 4, 5T, IGUER) IFLAG=0 IF(J0.EQ.1 (WRITE(15,135)T(4),T(5),T(6) IF(J0.EQ.1)WRITE(10,125)T(4),T(5),T(6) FORMAT(1X,2(F3.&***),F3.0,2) 135 30=2 TSS=TSINCE+EPOCH IF ( IU. EQ. 1 ) URITE (4,333) TSS, DT 333 FORMAT(1%,F14.9/12,F6.1) URITE(4,322)A.H 339 FORNAT (2H 4, F6.2, 1HE, F6.2, ': ') IN-5 530 DÖ 300 I-1.6 300 TS(I +T(I) CALL INCT(T.DT) 05 07 00 250 IF(G.GT.O.)DT-BDT IF(X2.E0.0)G0 TO 887 IF(0.GT.0)X2=DT 887 Q=H IU-1 60 70 250 ËND R GTOD 3/23/76 16:6:16

<u>98-Е-6</u>

OF POOR (	TYPE SCP C SGP BY TDB REU 2 14 75 AT 1430 COMPILER DOUBLE PRECISION SUBROUTINE SGP(TSINCE) CTHIS ROUTINE COMPUTES SATELLITE POSITION USING A SIMPLIFIED C GENERAL PERTURBATIONS METHOD, CLASSICAL MEAN ELEMENTS APE C INPUT; AND POSITION, VELOCITY, & OSCULATING ELEMENTS APE C RETAINED REAL IO, IM.NO, NDOTO, MO, NODEO, NODEM, LM, NM, NDOTM, LLONG, \$NDOTG, LO, NODDT, J2, J3, MU, IS, NODES EXTERNAL EXANM INTEGER YR	TEMPS=.25#J2#(AE/(HM*(1ELONG##2)))##2 ;PERTURBATION SIN2U=DSIN(2.#TRUEU) ;CONSTANT COS2U=DCOS(2.#TRUEU) RMAG=RMAGHTEMPS#SINI##2#COS2U#(AM#(1.~ELONG##2)) TRUEU=DMOD((TRUEU5#TEMPS#\67.#SINI##2)#SIN2U+,TWOPI) IS=IM+3.#TEMPS#SINI#COSI#COS2U NODES=NODEM+3.#TEMPS#COSI#SIN2U
PAGE IS QUALTER.	<pre>C INPUT PAPAMETEPS COMMON EPOCH, YR, M0, NODE0, OMEG0, NDOT0, SAM, EM, IM, NODEM, OMEGN, LM, NM, NDOTM, E0, N0, I0, L0, A0, SELONG, LLONG, EXLNG, OMEGL, TRUEU, RMAG, RDOT, NODDT, OMGDT, SUX, UY, UZ, PX, RY, RZ, RDOTX, RDOTY, RDOTZ J2=.00103248 J3=000002562 NDOTG=0. AE=1. MU=1. TWOPI=6.2831253072</pre>	UZ · SINU#SINI
282 ⁻ E−7	COMPUTE TIME UARIANT MEAN ELEMENTS AT TSINCE TT=TSINCE ,TIME SINCE EPOCH (DAYS) DM=NOATT+NDOTO#TT*X2+NDOTG*TT*X3 ;CHG IN MEAN ANOMAL? DOMEG=ONGDT*TT ;D ARG PER DNODE=NODDT*TT ;D ARG PER UM=DMOD(:L0+DN+DOMEG+INNODE:,TWOPI) ;MEAN ORBITAL LMGTUDE OMEGN=DNOD:(UMEG0+DOMEG),TWOPI) ;MEAN ORBITAL LMGTUDE OMEGN=DNOD:(HUDE0+DNODE),TWOPI) ;MEAN ORBITAL LMGTUDE OMEGN=DNOD:(HUDE0+DNODE),TWOPI) ;MEAN OF AN IM=I0 ;INCLINATION UNCHNGD SINI=DSIN:IM) NM=N0+2.TNDOTO*TT+3.*NDOT6*TT**2 AM*A0*((H0/NM)**.3333333333333)**2) EN=1A0'AM*(1E0) IF(EN)10,10,20 10 EM=0.00001	<pre>C</pre>
	<pre>COMPUTE AND APPLY LONG PERIODIC TERMS (SUBSRCPTD *L*) 20 TEMPL = \J3/J2/#(AE/AM/#SINI/(1EM##2) AXNL=EM#DCOS(OMEGM) AYNL=EM#DSIN(OMEGN)=.5#TEMPL ELONG=DSGRT:AXNL##2#AYNL##2) OMEGL=DMOD((DATAN2(AYNL,AXNL/),TWOPI); PRESERVE QUAD C LONG PERIODIC ON &amp; IS: LLONG=DMOD((LM=.25#TEMPL#AXNL#(3.+5.#COSI)/(1.+COSI)), #TWOPI); C 'SOLVE KEPLER'S EQUATION AND OTHER TWO-BODY FORMULAE</pre>	
	C LONG PERIODIC ECC ANOM: EXLNG=EXANM(LLONG-OMEGL-NODEM,ELONG) C TRUE ARG OF LATITUDE: TRUEU=2.*DATAN(DSGRT((1.+ELONG)/(1ELONG))*(DSIN(.5* SEXLNG)/DCOS(.5*EXLNG))+OMEGL RHAG-AN*(1ELONG*DCOS(EXLNG));R SUB L C TRANSVERSE COMPONENT OF VEL VECTOR	

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TYPE C C C	SRU (SLANT RANGE, VECTOR) TDB (6/27/15) COMMENTS AFTER LINES IN THIS SUBROUTINE ARE EQUATIONS IN APPENDIX OF ESCOBAL, "METHODS OF GRBIT DETERMINATION" COMPILER DOUBLE PRECISION SUBROUTINE SRV(THETA,H,A,GICSPHI,G2CSPHI,SMPHI,CSPHI,	TYPE PE	AK 6/30/75 COMPILEP DOUBLE PRECISION SUBROUTINE PEAK(IMANY,H,Z,X,ICOUNT,A,DT,IOVER) CALL APPEND:15,"TLOG",3,IEP: ICOUNT=ICOUNT+1 IF(H,LT,Z)G0 T9,333 Z=H
	\$G2SNPHI) REAL 10, IM, NO, NDOTO, MO, NODEO, NODEM, LM, NM, NDOTM, LLONG, \$LO, NODDT, LX, LY, LZ, LXH, LYH, LZH INTEGER YR COMMON EPOCH, YR, MO, NODEO, OMEGO, NDOTO, \$AM, EM, IM, NODEM, OMEGM, LM, NM, NDOTM, EO, NO, IO, LO, HO, \$AM, EM, IM, NODEM, OMEGM, LM, NM, NDOTM, EO, NO, IO, LO, HO, \$AM, EM, IM, NODEM, OMEGM, LM, NM, NDOTM, EO, NO, IO, LO, HO, \$AM, EM, IM, NODEM, OMEGM, TRUEU, RMAG, RDOT, NODDT, OMGDT, \$UX, UY, UZ, PX, RY, RZ, RDOTX, PDOTY; RDOTZ	333	RETURN IF(*.E0.1)GO TO 1 IM=IMANY+1 NUM=ICOUNT-1 ZNUM=NZMM XNUM=(ZHUM*2*DT+60. IF:ICOUFR.F0.0.000 TO 10
	TWOPI=6.2831853072 x=(G1CSPHI#DCOS(THETA);10.62 Y=(G1CSPHI)#DSIN(THETA);10.63 RH0X=RY+X;10.63 RH0Y=RY+Y;10.69	10 222 1	IF(2.20.0 .0R.X.EG.000RITE(15,222 IN,2,3000 IF(2.20.0 .0R.X.EG.000RITE(10,222 IN,2,3000 FOPMAT(11x,13,5%,F7.2,2%,F5.0,4.) X=1 IF(2.11T.TSTAND.H.LT.00CALL FCHAN(*UAIT20.50*) CONTINUE
	RH02*RZ+G2SNPHI ;14.70 RH0H-DSORT/RH0X#X2+PH0Y#X2+RH02#42) ;14.71 L/*RH0X/RH0H ;UHIT "ECTOR FROM SITE 1A.72 TO SATELLITE LY=RH0Y/RH0H ;DITTO 1A.73 £2*PH0Z RH0H; DITTO 1A.74 COSTH=DCOS(THETA)	P STOD	CALL CLOSE(15, IER) . RETURN END
	SINTH=DSIN(THETA) LXH+LX#SNPHI#COSTH+LY#SNPHI#SINTH-L2#CSPHI ;iH.75 LYH=-LX#SINTH+LY#COSTH ;DITTO L2H=LY#COSTH#CSPHI+LY#SINTH#CSPHI+L2#SNPHI ;DITTO COSH=DSORT(1,-L2H##2) H=DATAN(L2H-COSH) ;iH.76 IN NOOD	3, 23, 76 F	5 16:20:9
CORPI	INTION FOR PEFRACTION FOLLOWS (COURTESY OF PALPH PASS (35FC) H+H+.0007*DCUS(H) (DSIN(H)+DSORT).04+(DSIN(H)****2)) H=360.4H/TWOPI (+ 0P - DEGREES FROM HOPICON A=DHTAN2(LYH.+LXH) (1H.77 A=360.*A TWOPI (DEGREES GW FROM HOPTH IE(A.LT.0.)A=A+360. (HDJUST COOPDINATE SYSTEMS PETURN		
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28-E-8

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28- E-9

TYPE	P3		WRITE(6,55)S URITE(10,55)S
~ •	NO D IAN 76	55	FOPMAT(3%,"PRC=",F6.2) GO TO 15
C R	MC 8 JAN 76 DINENSION IDX(14,25),ITEMP1(6),ITEMP2(12)	64	COND*0
	CONFION/JBLK/NUM(24),SUM(12),X(8),JBIN(9),LBIN(3) CONFION/JBLK/J,K,S,F,JX,IX,NAME(12),CHK		DÓX≖0 ·
	COMMON/JBEK/COND,DOX,TEMP,PH		
	CALL DFILW("DATA", IER) CALL CFILW("DATA",2,IER)		TEMP=0
	CALL CFILW("DATA", C, IEK)		PH=0 CALL UTQLY
	CALL APPEND(5, DATA , 3, IER) CALL APPEND(6, TLOG , 3, IER)		IF(CHK.EQ.1.)GO TO 125
	CALL OPEN(7, "INDX",1, IER) CALL OPEN(8, DIRC",1, IER) CALL OPEN(9, LS2DAT",1, IER)		WRITE(6,56)COND,DOX,TEMP,PH
	CALL OPEN(8, DIRC', 1, IER)		WRITE(10.56)COND.BOX.TEMP.PH
	CALL OPEN(9,"LS2DAT",1,IER) IF(IER.NE.1)TYPE"OE= ",IER	56	FORMAT(3%, "CD-", F6.1,2%, DO-", F6.3, -,
	URITE(6,21)		?43X, "WT+", F6.2, 2X, 'PH+", F6.3) G0 T0 15
	WRITE(10.21)	65	CALL SHOP(NUM, IND, BEPTH)
21	FORMAT(1X, "PID ",2X, "STATION NAME",9X, "DATE",6%, "EST",/)	C	IF (CHK.E0.1)60 TO 125 URITE(10,57)DEPTH
	IX=8		URITE(10,57)DEPTH
16	READ(7,16)IDX FORMAT(14,1X,11,1X,12A2)	57	WRITE(6,57)DEPTH FORMAT( <u>3</u> %,"WES=",F7.3)
4	IFLG#0	51	GO TO 15
	READ(8,10,END-150)IPD	66	URITE(6,58)
10	FORMAT(I4)		URITE(10,58)
6	READ(9,12,END+11)ITEMP1, IPID, ITEMP2	58	FORMAT(3X, *CRREL")
18	FORMAT(6A2,14,12A2) IF(IPID.EQ.IPD)WRITE(5,19)ITEMP1,IPID,ITEMP2	67	GO TO 15 CALL ERTDA
	IFUIPID.EQ.IPD)IFLG=IFLG+1	0,	CALL SNOP(HUM, IND.DEPTH)
19	FORNAT(1X,6A2,14,12A2)	C	IF (CHK.EQ.1)60 TO 125
	GO TO 6		WRITE(6,59)S, DEPTH
11	PEUIND 9 IF(IFLG.EQ.0)GO TO 39	59	WRITE(10,59)S, DEPTH
	CALL CLOSE(5, IER)	28	FORMAT(3%,*STG**,F6.2,2%,*UES=*,F7.3) 90 TO 15
	CALL OPEN(5, "DATA", 1, IER)	68	CALL ERTDA
	DG 15 Id=1,IFLG		COND=0
74	READ(5,20,END+145)IY,IMO,IDD,IHH,NM,ISS,IEPF,IPID,NUM FORMAT(I1,5I2,A1,I4,2411)		004-0
20	IF(IERP.E9.17696)90 TO 15		TEMP=0 54-0
	CALL UTII(IY, INO, IDD, IHH, MM, ISS)		PH-0 Call Utoly
	DO 30 I-1,25	C	IF (CHK.E0.1)G0 TO 125
~~	. IF(IDX(1,I).E0.1PID)60 TO 40		WRITE(6,60)S,COND,DOX,TEMP,PH
30 40		~~	URITE(10,60 S, COND, DOX, TEMP, PH
ΨŲ	IND=IDX(2,I) D0_45_J=3,12	60	FORMAT()%,*STG=*,F6.2,%,43%,*CD+*,F6.1,2%,*D0**,F6.3, -?/,43%,*UT+*,F6.2,2%,*PH+*,F6.3)
	K=J-2		GO TO 15
45	MAME(K) = IDX(J,I)	69	WRITE(6,52)
	WRITE(6,48)IPID,NAME,INO,IDD,IY,IHH,MM		UPITE(10,52)
48	URITE(10,48) IPID, NAME, IMO, IDD, IY, IHH, MM	52	FORMAT(3X, "DEMO. SET")
τŲ	FORMAT(1X,14,1X,12A2,1X,12,*/*,12,*/*,12,1%,12,***,12,2) CHK+0.	125	GO TO 15 Vrite.6,130/
	GO TO(61,62,63,64,65,66,67,68,69)IND	167	UPITE(10,130)
61	W(1)E(0,51)	130	FORMAT(SX, "INVALID")
51	WRITE(10,51)	15	CONTINUE
	FORMAT(3X, *TEST SET*) GO TO 15	39	D9 152 10-1,25 TE(TDV/) T0 F0 T00 100 T0 154
65	CALL ERTDA	152	IF(IDX(1,IQ).EQ.IPD)GO TO 154 CONTINUE
C	IF(CHK.EQ.1.)GO TO 125 URITE(6,54)5		GOTO 4
	WRITE(5,54)S	154	DO 156 JQ-3,12
54	URITE(10,54)5 FORMAT(3X,*STG=*,F6.2)	156	
	GO TO 15	120	NAME(KQ)-IDX(JQ,IQ) IF(IFLG.EQ.0)WPITE(6,160)IPD,NAME
63	CALL ERTDA		IF(IFLG.EG.O)WRITE(10,160)IPD, NAME
C	IF(CHK.EQ.1)GO TO 125	160	FORMAT(1X, 14, 1X, 12A2, 4X, "NO REPOPT")

145	REVIND 5
150	GO TO 4 CONTINUE
150	CALL CLOSE(5,IER)
	ČALL DFILU('DATA',IER) CALL CFILU('DATA',2,IER)
	CALL CLOSE(6, IER)
	CALL CLOSE(7,IER) CALL CLOSE(8,IER)
	CALL CLOSE(8,IER) CALL CLOSE(9,IER)
200	WRITE(10,200) Format(/////)
	CALL CHAIN("TPACK.SU", IEP) IF(IER.NE.L)TYPE"CE= ",IER
	STOP
R	END
TYPE EF	
•	SUBROUTINE EPTDA COMMON/JBLK/NUM(24),LBIN(3+,JBIN(9),X(3+,SUM(12)
	COMMON/JBLK/J,K,S,F,JX,IX,NAME(12),CHK
	COMMON/JBLK/COHD,DOX.TEMP,PH JJ*3
	5=0
	F=1. J1=1
30	J2+J1+2
	K=-3 T=0.005
	DO 10 I -J1,J2 IF(NUM(I),GT.7) GV TO 40
	IF(NUM(I),GT.7) GO TO 40 K∗K+3
	CALL D(EPY(LEIN,NUM(I),JJ)
	DO 10 L+1,3 J=L+K
10	JBIN(J)*LPIN(L)
	1.1-2 D0 20 1-2,9
32	IF(1-6)31,32,31 F=10,*F
96	T=0.005
31	K1=6 IF(JBIN(1))20,25,20
31 25	T1=F#2.**(I-K1)
	T=T+T1 IF(F#10T)40,26,26
26	S=C+T1
50	CONTINUE J1=4
	F*.01
	IF(J2~4)30,40,40 Return
40	CHK ×1.
	RETURN END
R TYPE B	19441
CDC	1/1/75
	SUBROUTINE BINA1 COMMON/JBLK/NUM(24),SUM(12),X(8),JBIN(9),LEIN(3)
	CONTROLVING CITY CONTROL C
	CONNON/JBLK/COND, DOX, TERP, PH
	D0 10 I+1,3

IX=3*JX-(3-I)+6 IF(NUM(IX)-7)45,45,55 K + K + 3 CALL DCBRY(LBIN, NUM(IY), 3) 45 DO 10 L=1.3 J-L+K JEIN(J)=LBIN(L) CONTINUE RETURN 10 55 END R TYPE BINE1 NEI SUBROUTINE BINEI COMMON/JELK/NUM/24),SUM(12+,X(3),JEIN+9),LEIN+3) COMMON/JELK/J.K.S.F.JX,IY,NAME(12),CHK COMMON/JELK-COHD,DOX,TEMP,PH D0_45_I=2,9 M=I-1 IF(JPIN(1))40,10,40 IF(I-6)20,30,30 X(M1=241(5-1) . 10 <u>5</u>0 GO TO 45 X(M)=211(9-1) 30 GO TO 45 Dim +0 40 45 CONTINUE M=0 00 00 N×1.2 N×24 J%=(2+N) SUMINIE DO 60 L-1,4 LX=41N-(4-L) SUM(M)=SUM(M)+F(LK) XILX.>=0 CONTINUE 60 IF(SUM(M-10)80,70.70 K-2 CONTINUE 70 30 PETUPN . END R TYPE DOLPY C D C 1/1 75 SUPPORTINE DEBRY LBIN.NUM, JJ + DIMENSION LBIN.4) DG 10 I-1, JJ LEIN(I)-0 10 LEIN(1)+0 IF(NUM)5,5,35 DC 30 KK+1,NUM DG 15 I+1.JJ J+JJ-I+1 IF(LEIN(J))20,20,15 CONTINUE DD 30 L+1 JJ 35 15 DO 25 1-J.JJ LEIN(1)-0 20 LBIN(J)=1 CONTINUE 30 ŝ PETURN R

26-E-10

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2	TYPE UTQLY SUBROUTINE UTQLY COMMON/JBLK/NUM(24),SUM(12),X(8),JBIN(9),LBIN(3) COMMON/JBLK/J,K,S,F,JX,IX,NAME(12),CHK	TYPE LETGE C SUBROUTINE TO CALCULATE DISCHARGES AND VALIDITY FROM C VALUES OF STAGE AND STATION NUMBEP
NOTCINIAT.	COMMON/JBLK/CÓND, DOX, TÉMP, PH D0 25 JX-1,6 CALL BINA1 CALL BINB1 25 CONTINUE IF(K-6)10,30,30 30 COND-0	SUPROUTINE_LSTGE(ISH,STAGE.0,HAME.DA,J) DIMENSION_DISCH(44),NAME(10) COMMON/KBLK/LS1(16) DATA_LS1/7147,7101,7220,7071,7272,7356,7201,7233, #6063,7106,7304,7345,7254,7335,7206,6504/
PAGE	30 COND-0 DOX=0 PH=0 TEMP=0 COND=1.Sx(100#SUM(4)+10#SUM(1)+SUM(2)) DOX=0.02*(100#SUM(11)+10#SUM(12)+SUM(3)) PH=0.014%(100#SUM(5)+10#SUM(6)+SUM(7)) TEMP=0.04**(100#SUM(8)+10#SUM(9)+SUM(10)) RETURN	DO 85 N=1,16 IF(LS1(N).EQ.ISN)GO TO 8 S5 CONTINUE GO TO 235 S NN-N-1 CALL FSEEK(13,NN)
	10 CHK-1. RETURN END R TYPE WIII	C T-INITIAL STAGE IN TABLE; 9-STAGE INCPEMENT IN 2ND LINE READ(13,3)NAME,DA,T,0,DISCH 3 FORMATIGX,10A2,24%,F6.0,12%,F6.0,6%((3X,9F8.0)) C J-0 FOR VALID OR J-1 FOR NON VALID STAGE
, 98~Е-11	<pre>C RMC 13 JAN 76 C CONVERTS ZULU TIME TO EASTERN STANDARD TIME (EST) SUBROUTINE UTII(IY,IMO,IDD,IHH,MM,ISS) INTEGER DAYSINMO COMMON.IBLK.DAYSINMO(12) DATA DAYSINMO(31,29,31,30,31,30,31,30,31, IHH=HH+5 IF(ISS.GE.30)MM=MM+1 IF(ISS.GE.30)MM=MM+1 IF(ISS.GE.30)MM=MM+6 IF(ISS.GE.30)MM=MM+6 IF(IHH.LT.0)IHH=IHH+1 IF(MM.GE.60)MM=MM-60 IF(IHH.LT.0)IHH=IHH+24 IF(IDD.LT.1)IMO=IMO+1 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)IMO=IMO+12 IF(IDD.LT.1)I</pre>	J-0 IF(0)50,50,21;FOP LUMMY FILE, INCRMAT (G) WILL BE 0 21 IF(STAGE-T)51,22,22 51 G=005 GO TO 285 22 DO 60 N=1,43 S=STAGE -T-NYO R=(S+Q)/Q Z=DISCH(N) P=DISCH(N) P=DISCH(N)+1)-Z IF(P)24,60,65 65 IF(S)70,70,60 C INTERPOLATE ON PATING TAPLE 70 IF(2)52,52.700 52 IF(P)51,152,152 152 G=Pt(Pt+1.5) GO TO 50 700 G=Z+PP+P+,005
	R TYPE SNOP SUBROUTINE SNOP(NUM,I,DEPTH) DIMENSION NUM(24) CRCT=6.98 IF(I.E0.5)CRCT=3.92 D6=641NUM(16)+STNUM(17)+NUM(18) D7=641NUM(16)+STNUM(20)+NUM(21) DFTH=(D7/D6)+55.36-CRCT RETURN END	GO TO 50 60 CONTINUE 0 EXTRAPOLATE ON RATING TABLE 24 O-Z+P*(Z-DISCH(N-1))+.005 235 J-1 50 RETUPN END P
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98~E-11

	ç	PE 0D3 TDB 10 MARCH 76 PROGRAM TO CONVERT LANDSAT MSGS TO NASA-LIKE FORMAT. THIS PROVIDES INPUT TO "P" OR "P3" PROGRAM ACCEPTS MSGS FROM ALL DCP'S AND SCPEENS OUT THOSE UHICH ARE NOT NED'S DIMENSION IA(6), IB(12)	E,12) =5,12) =5,12)	IF(ICHK.GT.1)IER-17696 ; IF ERR IS FLAGGED OUTPUT AN *E* WRITE(6,35)IYF,IMONTH,IDAY,IHR,IMIN,ISC,IER,IA(2),(IB(K),K* WRITE(10,35)IYR,IMONTH,IDAY,IHP,IMIN,ISC,IER,IA(2),(IB(K),K WRITE(15,35)IYF,IMONTH,IDAY,IHP,IMIN,ISC,IER,IA(2),(IB(K),K
		CALL APPEND(15, *TLOG*,3,IER) IF(IER.NE.1)TYPE "QLER',IER CALL OPEN(5, 'USER:SDF',1,IER) CALL DFILU(*LS2DAT*,IER) CALL CFILU(*LS2DAT*,2,IER) CALL OPEN(6,*LS2DAT*,3,IER) CALL APPEND (7,*STORAGE*,3,IER)	5,12) 35 100 [.]	<pre>WRITE(7,35)IVR,IMONTH,IDAY,IHR,IMIH,ISC,IER,IA(2),(IB(K),K= CONTINUE FORMAT(1X,I1,5I2,A1,0I4,60I3) G0 T0 1 CALL GLOSE(5,IEP) CALL GLO</pre>
	10	ICOUNT=0 ICT=0 IYR=6	120` 110	CALL CLOSE(6,IER) WRITE(10,120)ICOUNT WRITE(15,120)ICOUNT FORMAT(" TOTAL HUMPER OF MESSAGES = ",I3) WRITE(10,110) FORMAT(/ ///) CALL CHAIN("P3.SU",IER) CALL CHAIN("P3.SU",IER)
·	ĩ	READ BINARY (5)IMONTH, IDAY, IHR, IMIN, ISEC ;GET STARTING ISEC-ISEC+60*IMIN READ BINARY(5)IA, ISC ;GET DATA AND SECONDS COUNTER ISC-ISC+ISEC-ICT*3600 IF(ISC.LT.3600)GO TO 4 ICT=ICT+1 ISC-ISC-ICT*3600 IHP-IHP+1	R	IF(IER.NE.1)TVPE "ODER",IEP CALL EXIT END
Q8−E-12	4	IF(IHR.GE.24)IHR+IHR-24 IMIN+(ISC:60) ISC-ISC-GOXIMIN IF(IMIN.LT.60)GO TO 5 IMIN-0 IHP-IHR+1 IF(IHF.LT.24)GO TO 5 ILOY-IDAY+1		
	5	THR:0 CONTINUE IF(IA(I).EQ.0)GO TO 100 ICOUNT-ICOUNT+1 DO 20 I=3,6.		
	20	ID=IA(I),AND.377K IC=ISHET(IA(I),-8) IC=IC=AND.377K J=I#2-1 IB(J)=IC J=J+1 IB(J)=ID		
		ICHK-IA(2).AND.20000K IA(2)-IA(2).AND.7777K ;STRIP EVERTHING BUT THE DCP # IF(IA(2).EQ.6063K.OR.IA(2).EQ.6504K)GO TO 25		
		IF(IA(2),LT.7000K)GO TO 1 IF(IA(2),EQ.7627K)GO TO 1 IF(IA(2),EQ.7627K)GO TO 1 IF(IA(2),EQ.7514K)GO TO 1 IF(IA(2),EQ:7346K)GO TO 1		
	8	IER-8224 JASSUME NO ERROR, OUTPUT A BLANK		

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3 3 3	416 1549 0	530 1680 0	650 1820 0	770 1980	- 890 2140 0	1010	1130	1260	148
3 N.NF	6.6	0 FITCHBUI 17	8G 31	0 52	0 80	0 63.6 120	0 175	0 . S+S	38
2222	174 1150 2065	240 1240 2175	325 1340 2290	430 1440 2410	550 1540 2530	685 1640 2670	825 1740 2810	950 1845 0	105 195
2 1950 2 2 2	ICH R, 0.2	IPSUICH 0	0.76	3.39	17.5	124. 32	52	85 82	18
9 10 9 15		70040.0 (13000.0) 0.0	74800.0 (18000.0 0.0	79400.0 123000.0: 0.0	84000.0 (128000.0 0.0	0:08880 0.00003 0.0	93690.0 138000.01 0.0	98400.0: 143000.0: 0.0	103200. 148000. 0.
9 9 2	1.0	115.0	454.0	1110.0	2330.0 41240.0 84000.0	4780.0	2200.0	12500.0	17240.
32 2	8570.0 9100.0 S FALLS	19670.0	20770.0 31650.0 4 2 3	21900.0 32960.0 7	23050.0 34310.0	24200.0 35710.0 3992.0	25400.0 37110 0.0	26500.0 33510	27850 3991
22	3250 9480	3750 10410	50 4290 11362	193 4360 12350.0	430 5430 13350.0	980 6160 14350.0	1780 6900 15370.0	2340 7710 16420-0	279 858 17470
51 B2 PLYM	36700 OUTH	38100	39500 323	40300	42400	43800 622.0	45300	46300 Li.0 -1.	4830
51 51 51	3240 12900 24500	4040 14100 25800	4950 15400 27200	5950 16600 23600	7000 17900 23900	8130 19200 31200	9360 20500 32600	10600 21300	117( 2320 353(
51 SACO	R, COR 0.5	22500 NISH 215	29800 351	31000 _531	32300 761	1292. 1060	1440	1. 1930	259
50 50 50	8520 17000 27200	9400 18100	10300 19200	11200 20300	12200 21400	13100 22600	14100 23700	15000 24800	160 260
50 CARA 50 50	BASSET 0.5 2030	P, N.AN9 0 2590	50N 52 3230	128 3880	270 4530	354. 490 5270	795 6070	2. 1160 6870	15 76
49 49	60000 97000	63900 101500	67800 106200	71800	75900	30000 121000	84000 126000	88200 131000	925 1365
19 19 19	0.5 11200 30700	1860 12900 33500	2660 14600 36500	3590 16600 39 <b>500</b>	4630 18600 42500	5750 20700 45500	6960 23000 49000	8270 25500 52500	97) 280) 562)
48 48 49 PENO	BSCOT,	U.ENFIE	LD			6670.		1.	
18 18 18	1.0 16000 63500	450 19700 71000	1280 23700 79000	2280 28000 57000	3600 33000 95000	5310 38090 140090	7499 44000 113000	10100 50000 123000	1 304 5654 1 3304
17 17	67700 0 10hn R,	72200 0 FORT KEI	76700 0 11	81500 0	85700 0	90200 0 5630	94700 0	99200 0 0.5	
47 47 47	9800 9800 32900	160 11800 36200	560 13800 39400	1140 16100 42700	2020 18600 46600	3120 21000 50100	,4450 23600 54200	6050 26400 58700	78) 297) 632)
46 46	17800 31600 OHN P.	19200 33200 DICKEY	20600 35000	22100 35600	23600 36200	25200 36800 2700.	26700 37400	28300 38000 3.5	299) 386(
46 46 46	0.3 1420 7380	NINEMILE 43 1810 8410	84 2240 9520	147 2720 19709	243 3290 11900	375 3950 13000	546 4700 14200	766 5540 15400	10) 64) 166)

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56 56	1765	1835	1910	1990	2670	2150	9655	2310	53
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	DB 4 DEC 75 PROGRAM TO CONVERT DECIMAL AZIMUTH AND .	40	X=X-BCDLOU(3) II=J+6-(J-1)#2BIT MAPPING
	ELEVATION ANGLES TO BCD SUITABLE FOR INPUT TO Interface	50	CALL ISET(ILOW,II) CONTINUE
2	TO 1845 DIGITAL COMPARATOR		IBCDH(Î)=IHIGH IBCDL(I)=ILOÙ
	CONFILER DOUBLE PRECISION DINENSION X1(2),X2(2),IBCDH(2),IBCDL(2)	100	CONTINUE
	CONMON IBLE/BCDHIGH(10), BCDLOU(8), ISTOU(5) DATA BCDHIGH/200., 100., 80., 40., 20., 10., 8., 4., 2., 1./		URITE BINARY(6)IBCDL(1),IBCDH(1),IBCDL(2),IECDH(2 ICT+ICT+1
•	ECD TABLE		X1(1)=X1(1)+X1INC
	DATH BCDLOU/.S,.4,.2,.1,.08,.04,.02,.01/		IF(X1(1).GE.0)GO TO 201 X1(1)=X1(1)+360.
	STOW ANGLES AND FILE ENDER	201	X1(2)+X1(2)+X2INC
	Data Istow/0,0,200K,211K,-1/	UT	IF(X1(1).GT.360.)X1(1)=X1(1)=360. ;PROB NOT NEEDE
		<b>U</b>	
	CALL OPEN(S, "PTAE", 1, IER) CALL OPEN(G, "BCDAZEL", 3, IER) CALL OPEN(7, "NANGLES", 3, IER)	105 109	CONTINUE
	CALL OPEN(7, "NANGLES", 3, IER)	109	IF(IFLG.EQ.1)X2(1)=X2(1)+360. X1(1)=X2(1)
	LT (IER.NE.I)TYPE "OE", IER		X1(5)=X5(5)
	M1=−1 D1=1	110	READ(5,110)X2 FORMAT(2(1X,F6.2))
			IF(X2(1).EQ.0.AND.X2(2).EQ.90)GO TO 120
	READ(5,6,END*500)TSINCE ;READ 1ST REC ON FILE READ (5,7)DT,X2	120	GO TO 15 URITE BINARY (6)ISTÓU
	FORMAT(F14.9)		URITE(7,700)ICT
	FORMAT(F5.1/2(1X,F6.2)) IFIN=DT	700 500	FORMAT(1X,IG) CALL CLOSE(5,IER)
	WRITE(6,11)TSINCE,D1	200	CALL CLOSE (G, IER)
	ICT=1 IFLG=0		CALL CLOSE(7,IER)
1	FORNAT: F14.9, F6.1)		CALL CHAIN(*LS1.SV",IER) IF(IER.NE.1)TYPE"INTERP1ERR",IER
	GO 70 109		STOP
Ę	IFLG=0	x	END
	IF(AB5(X2(1)-X1(1)).GT.300)IFLG=1		
	IF(IFLG.EQ.1)X2(1)=X2(1)-360. X1INC=(X2(1)-X1(1))/DT		
	X2INC=(X2(2)-X1(2))/DT		
	105 INC-1.IFIN		
	DO 100 I+1,2 ;AZ ,EL		
	X*X1(I) IHIGH=0		
	ILOU=0		
	10 30 J=1.10		
	ÎÊ(ÊĴDŇIĜĤ(Ĵ).LÊ.X) <b>go to 20 ;check bod table</b> Go to 30 ;smaller than value in table		
0	A+11-BCDHIGH(J) ;>-VALUE IN TABLE		
	11*2+8-13-1322		
PRE	CHLL ISET(INIGH, II) ;BIT ORDER ON P.9-11 OF FORT I		
10 M	CONTINUE	<b>v</b>	
	DG 50 J=1.8		
	IF(BODLOU(J), LE, X)GO TO 40		
	GO TO 50		

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2% ~ E-15

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#### APPENDIX F - LITERATURE CITED AND RELATED DOCUMENTS

- Escobal, P.R.* "Methods of Orbit Determination".
   New York: John Wiley and Sons, 1965
- "How to Use the NOVA Computers". Data General Corporation Southboro, Massachusetts
- "Real Time Disc Operating System", Revision 3 or higher.
   Data General Corporation, Southboro, Massachusetts
- 4. "Fortran IV", Data General Corporation, Southboro, Massachusetts

*Referred to in text.



# Flood Control in NEW ENGLAND

DEPARTMENT OF THE ARMY . NEW ENGLAND DIVISION . CORPS OF ENGINEERS . WALTHAM, MA.

2

# THE LANDSAT SATELLITE

and

# FLOOD CONTROL IN NEW ENGLAND

#### **JUNE 1976**

### HISTORY AND BACKGROUND

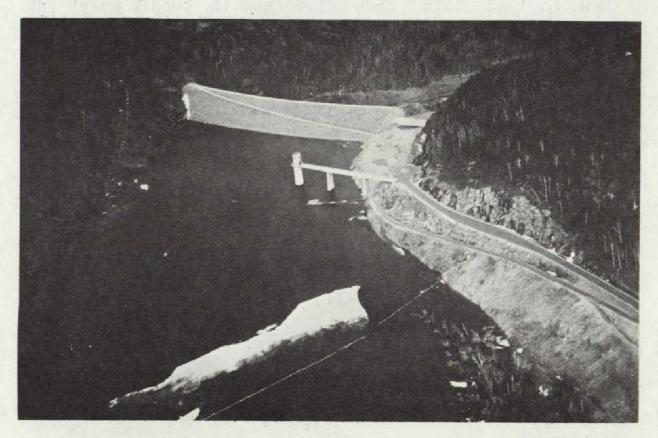
Since the Industrial Revolution in the 1800's, the rivers of New England have been developed to supply water for power and transportation. As new means of transportation became more economical both railroad and highway systems were built along the banks of the rivers to service the expanding needs of the industrial, commercial and urban centers. Structures, such as buildings, roads, bridges and dams have restricted floodways to such an extent that considerable property and environmental damages have occurred during moderate and major floods. Notable floods of November 1927, March 1936, September 1938 and August 1955 have demonstrated the need for flood control to prevent these natural catastrophes.



AUGUST 1955 FLOOD DAMAGE AT WINSTED, CONNECTICUT

28-F3

## At the direction of Congress, the U.S. Army Corps of Engineers developed a comprehensive plan of protection for each river basin after a careful analysis of all water resources. Protective works generally consist of a combination of channel improvements, dikes and / or floodwalls at major damage centers augmented by upstream flood control reservoirs. Many of these reservoirs contain additional storage reserved for other uses such as water supply, conservation and recreation. The Corps has built 35 flood control reservoirs, 37 local protection projects and 4 hurricane barriers in New England at a total investment of over \$350 million.



BALL MOUNTAIN DAM AND RESERVOIR JAMAICA, VERMONT

To achieve optimum operating benefits from this comprehensive protection system, the New England Division requires hydrologic data such as river, reservoir and tidal levels, wind velocity and direction, barometric pressure and precipitation.

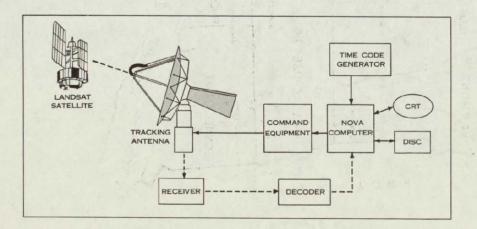
In the past this data was collected from field observation and relayed via telephone or voice radio. It took several hours to compile and assess the data in this manner. With the need for timely and reliable information increasing, the Corps began development of new methods of data collection.

#### LANDSAT

Since July 1972, LANDSAT has been relaying river stage, precipitation and water quality data from DCP's via the Goddard Space Flight Center to the U.S. Army Corps of Engineers, New England Division, in near real time. This is the first resources satellite designed to obtain data from the planet Earth exclusively for planning, design, operations and research of land and water resources.

#### THE NED GROUND RECEIVE STATION

Since any operational satellite configuration should include ground receiving stations at all major user locales, NED, with NASA support has constructed and is now operating an inexpensive semiautomatic and easily maintained ground receive station as a follow-up to its original study. The Division is now able to receive hydrometeorological data from data collection platforms in the field directly at its headquarters in Waltham, Massachusetts with no time delays. The software to drive the antenna system has been developed with the intention that the antenna operate in an unattended mode automatically over nights and during weekends and holidays, with a computer controlling all processes. A diagram of the overall facility is shown.

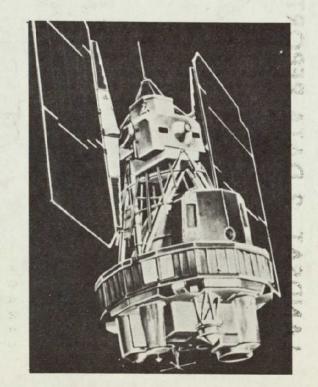


NED GROUND RECEIVING STATION DIAGRAM

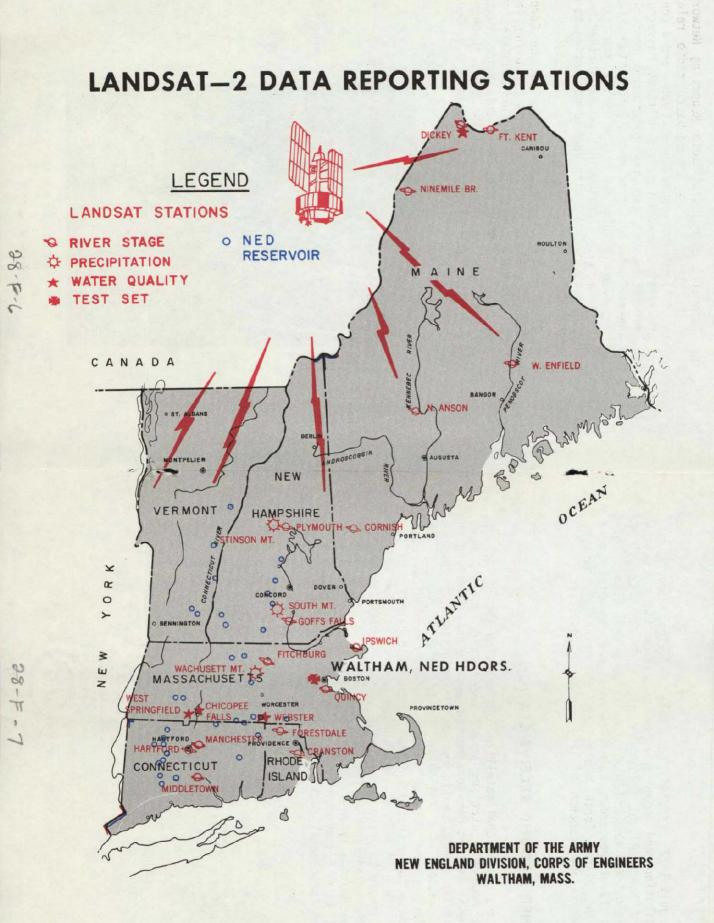
28-F-8

In 1970, the Automatic Hydrologic Radio Reporting Network was placed in operation. This ground-based radio relay system consists of 41 remote reporting stations, and a central control at Division Headquarters in Waltham, Massachusetts. This network, under computer programmed control, collects and analyzes, in real time mode, information which is essential for flood regulation. The remote reporting stations are strategically located in five major river basins and at key coastal points, with each contributing to a detailed, comprehensive hydrologic picture.

In June 1972, NASA entered into a contract with the Corps for an experiment to study the feasibility of using the Earth Resources Technology Satellite (ERTS or LANDSAT) for collecting environmental data from Data Collection Platforms (DCP's) which are installed at 27 locations throughout New England. Many are situated at existing U.S. Geological Survey gaging stations.



LANDSAT SATELLITE



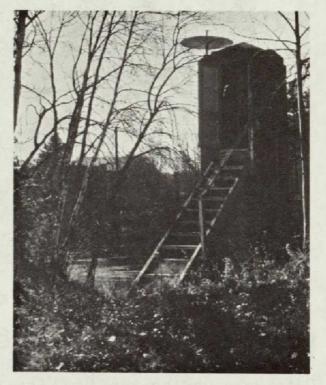
A major objective of the program has been to compare the cost, reliability, and operational effectiveness of the LANDSAT Data Collection System with the existing NED radio network.

THE HUGH WARREN CONTRACT AND A DEPENDENT AND FRANKING

Data collection platforms tested by the Corps have performed successfully in all seasons including the winter months and also during significant flood events, transmitting near real time operationally useful data for our flood fighting missions.



TRACKING ANTENNA AT NED WALTHAM, MA.

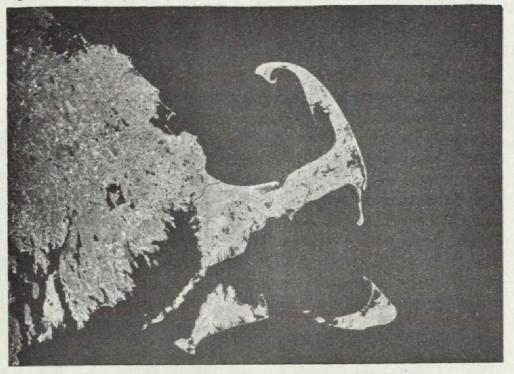


DATA COLLECTION PLATFORM SACO RIVER CORNISH, MAINE

The satellite proved invaluable in April and early May of 1973 and 1974, monitoring flooding in Maine Rivers. LANDSAT relayed data from five remote river points in that state to aid the New England Division in the coordination of the flood emergencies.

The successful testing of the LANDSAT Data Collection System at the New England Division should encourage serious consideration of the institution of an operational satellite data relay system on a Corps - wide basis. System analysis is being performed to refine cost data and to articulate the data collection needs of Corps users.

The New England Division is also studying imagery regularly collected by LANDSAT to determine the usefulness in planning, designing, and managing water resource systems. It is well established that such imagery is suited to measuring areal extent of ice, snow, and open water, and for estimating moisture regimes. Our studies involve computer analysis of scenes and will explore indirect methods of calculating other hydrologic parameters as well.



IMAGERY PHOTO TAKEN FROM LANDSAT

#### FLOOD CONTROL OPERATIONS

Data received at the New England Division's Reservoir Control Center from either the Automatic Hydrologic Radio Reporting Network or the LANDSAT Data Collection System is compiled by computer. This is augmented by information from other sources such as the National Weather Service Meteorologic and River Forecast Offices and the U.S. Geological Survey. Experienced engineers and hydrologists at the Reservoir Control Center analyze the data for timely operation of dams and hurricane barriers, and then issue instructions to operating field personnel.

Flood control reservoirs, local protection projects and hurricane barriers built by the Corps in New England have been responsible for prevention of about \$300 million in flood and storm damage.



Lieutenant General William C. Gribble, Jr. Chief of Engineers



Colonel John H. Mason Division Engineer

# **KEY OFFICIALS**

DEPARTMENT OF THE ARMY NEW ENGLAND DIVISION, CORPS OF ENGINEERS WALTHAM, MASSACHUSETTS

> COLONEL JOHN H. MASON New England Division Engineer

COLONEL RALPH T. GARVER Deputy Division Engineer

JOHN WM. LESLIE Chief, Engineering Division

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