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Volume II - Appendixes



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OUTER PLANET DATA PRESENTATION  
COMPUTER PROGRAM

Model Description Report

July 1971

Volume II - Appendixes

MARTIN MARIETTA CORPORATION  
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FOREWORD

This report has been prepared in accordance with requirements of Contract JPL 953058 to present a description of a computer program resulting from a four-month development effort performed for the Jet Propulsion Laboratory by the Martin Marietta Corporation, Denver Division. The report is submitted in two volumes. Volume I is a description of the program and its operation, Volume II contains the appendixes, which include sample data cases to aid initial input setup and program checkout.

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INTRODUCTION

This volume consists of the following appendixes:

- Appendix A, which contains three validation missions, representing partial fulfillment of the contract. Tabular and plotted data are presented as samples to confirm program operation by showing that numerous mission and experiment options have been used;
- Appendix B, which is a card listing of the Univac 1108 version of the subroutines developed during the contract period;
- Appendix C, which is a partial reproduction of the documentation provided by JPL. This documentation is included to aid the user in determining the proper input for card numbers 2, 3, 4, and 6 through 12. Because this documentation is for subroutines maintained by JPL, the user is advised to determine if the documentation has been updated before attempting to run the program.

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APPENDIX A

COMPUTER PROGRAM VALIDATION MISSIONS



Validation missions provide the user with sample data to confirm program operation by exercising numerous mission and experiment options. Table A-1 shows the variations for nine computer cases. The Mission 1 objective is to check out geometry associated with imaging at Jupiter. The Mission 2 objective extends check-out to Saturn, and exercises considerable more pointing, experiment characteristics, and satellite modes. Mission 3 is an orbiting mission at Jupiter adding spinning spacecraft comparison, and particle and field measurements. Discussion of the options listed in Table A-1 are given in each validation mission that follows.

The order of presentation for Mission 1, 2, and 3 is shown in the appendix contents. A discussion of input and output listings is provided for each mission. Following the discussion, tabular input, tabular output, and graphic output are presented for each case.

Table A-1

## Validation Missions Index

	<u>CASE</u>	<u>PLANET</u>	<u>SATELLITE OPTION</u>	<u>CAMERA CHARACTERISTICS</u>	<u>POINTING</u>
MISSION 1	1	Jupiter	NA	Canned Wide Angle	Radius Vector
	2-1, 2-2 & 2-3	Jupiter	NA	Input Wide Angle	Cone and Clock
MISSION 2	5	Jupiter	NA	Canned Narrow Angle	Radius Vector
	4	Jupiter	One Satellite	Canned Narrow Angle	Radius Vector
	6	Saturn	NA	Canned Wide Angle	Radius Vector
	7	Saturn	NA	Canned Narrow Angle	Radius Vector
MISSION 3	8	Jupiter-Orbiter	NA	Pioneer	Radius Vector
	9	Jupiter-Orbiter	NA	Input Narrow Angle	Radius Vector
	10	Jupiter-Orbiter	NA	NA (Particle & Field)	NA

A. MISSION 1

The specific objective of Mission 1 is to provide the data required to check out the geometry associated with the imaging science evaluation capability. Thus, the mission description herein is limited to that required to fulfill this objective. As an example, the trajectory data used are the Jupiter encounter conditions from a total Earth-Jupiter-Saturn-Pluto outer planet mission.

The mission description and results are contained in the following sections. The spacecraft is considered to be a TOPS configuration, with Earth/Canopus attitude control.

1. Science Mode

To check out the imaging-associated geometry subroutines, the target is the planet disk of Jupiter with terminator; i.e., no local geography, such as the red spot, is shown. The following measurement modes are used:

- Align Camera to Radius Vector -

<u>Timing</u> <u>Encounter</u>	<u>Frame</u> <u>Sequence</u>	<u>Data</u> <u>Display</u>
-1.5 to +1.5 days	1 @ 5 minutes	Plot at 30 minute intervals

- Input Discrete Cone and Clock (Table A-2) -

<u>Timing</u> <u>Encounter</u>	<u>Frame</u> <u>Sequence</u>	<u>Data</u> <u>Display</u>
-5 <sup>h</sup> 20 <sup>m</sup> to +5 <sup>h</sup> 20 <sup>m</sup>	1 @ 5 minutes	Plot at 1 <sup>h</sup> 0 <sup>m</sup> intervals

The first clock position at each time point is a limb pointing direction; the second clock position is an intermediate direction; the third clock position is a radius vector (or planet center) direction. These pointings are referred to as case 2-1, 2-2, and 2-3 respectively. The input and output with the above measurement mode variations are shown on Missions 1 and 2 for the radial alignment and discrete cone/clock, respectively.

Table A-2 Cone and Clock Angles for Mission 1

<u>TIME</u>	<u>CONE</u>	<u>CLOCK</u>	<u>TIME</u>	<u>CONE</u>	<u>CLOCK</u>
-5 <sup>h</sup> 20 <sup>m</sup>	151.65	247.70	+1 <sup>h</sup> 19 <sup>m</sup>	30.44	233.18
	151.65	254.70		30.44	247.18
	151.65	261.70		30.44	261.18
-4 <sup>h</sup> 0 <sup>m</sup>	141.34	247.62	+2 <sup>h</sup> 39 <sup>m</sup>	5.71	189.92
	141.34	254.62		5.71	224.92
	141.34	261.62		5.71	259.92
-2 <sup>h</sup> 40 <sup>m</sup>	125.66	247.54	+3 <sup>h</sup> 59 <sup>m</sup>	9.96	14.30
	125.66	254.54		9.96	38.30
	125.66	261.54		9.96	82.30
-1 <sup>h</sup> 20 <sup>m</sup>	100.92	247.46	+5 <sup>h</sup> 19 <sup>m</sup>	20.27	59.05
	100.92	254.46		20.27	70.05
	100.92	261.46		20.27	81.05
0 <sup>h</sup> 0 <sup>m</sup>	65.68	247.37	0 <sup>h</sup> 0 <sup>m</sup> = time at radius of closest approach		
	65.68	254.37			
	65.68	261.37			

2. Instrument Characteristics

The TV characteristics for Mission 1 are as follows:

<u>DIRECTION</u>	<u>FIELD OF VIEW (deg)</u>	
	<u>NARROW- ANGLE LENS</u>	<u>WIDE- ANGLE LENS</u>
Vertical	1.0	10.0
Horizontal	1.0	10.0

The input and output of the above wide-angle lens are shown on cases 1 and 2. The narrow-angle lens is used in Missions 2 and 3.

3. Trajectory Data

The Jupiter encounter data were taken from a 1977 Jupiter-Saturn-Pluto mission, which has a total flight time to Pluto of approximately eight years. The data are as follows:

JUPITER ENCOUNTER

Calendar Date/Hr/Min/Sec	14 JAN 79/10/48/3.27
Julian Date	2443887.950038
Periapse State (km)	1.2706446432E+05 (x)
(Earth Ecliptic Ref)	2.1321885366E+05 (y)
	1.3387051602E+04 (z)
(km/sec)	2.9431552532E+01 (x)
	1.7610963316E+01 (y)
	1.1418359371E+00 (z)

4. Case 1

a. Input Data - The tabular input listing is shown in Table A-3. Tabular listings of TV instrument characteristics, planetary and satellite albedos, and other values used in the imaging subroutine are shown in Table A-4. For the TV characteristics, the user inputs are labeled to distinguish them from canned values. The pointing mode is planet-centered (radius vector).

Table A-3 Case 1 Input Listing

## JUPITER CHECK OUT CASE 1

2	5.0000000	PLANET
3	2.0000000	SATEL
4	790114.69	JATE JD AT ENCOUNTER
6	15.000000	
7	127064.46	STATE1
8	213218.85	STATE2
9	-13387.052	STATE3
10	-29.431552	STATE4
11	17.610963	STATE5
12	1.1418359	STATE6
22	120.00000	INSTID
61	-1.5000000	TSTAR TIME FROM PERIAPSIS
62	1.5000000	TSTOP TIME FROM PERIAPSIS
63	5.0000000	JTINSTPICTURE TAKING INTERVAL (MIN)
69	6.0000000	CALCSTPICTURES PER CALC STEP
81	3.0000000	DPLOT
82	3.0000000	DPRNT
90	1111111.0	
98		

## JUPITER CHECK OUT CASE 1

## XZ(I) VALUES IN STORAGE

1	0	0.	2	1	5.0000000000E+00
3	1	2.0000000000E+00	4	1	7.9011469200E+05
5	0	0.	6	1	1.5000000000E+01
7	1	1.2706446400E+05	8	1	2.1321885300E+05
9	1	-1.3387051600E+04	10	1	-2.9431552500E+01
11	1	1.7610963100E+01	12	1	1.1418359000E+00
13	0	0.	14	0	0.
15	0	3.0000000000E+00	16	0	0.
17	0	0.	18	0	0.
19	0	0.	20	0	0.
21	0	0.	22	1	1.2000000000E+02
23	0	0.	24	0	-7.1738305547E+57
25	0	-7.1738305547E+57	26	0	0.
27	0	0.	28	0	0.
29	0	0.	30	0	0.
31	0	0.	32	0	0.
33	0	0.	34	0	0.
35	0	0.	36	0	0.
37	0	0.	38	0	0.
39	0	0.	40	0	0.
41	0	0.	42	0	0.
43	0	0.	44	0	0.
45	0	0.	46	0	0.
47	0	0.	48	0	0.
49	0	0.	50	0	0.
51	0	0.	52	0	0.
53	0	0.	54	0	0.
55	0	0.	56	0	0.
57	0	0.	58	0	0.
59	0	0.	60	0	0.
61	1	-1.5000000000E+00	62	1	1.5000000000E+00
63	1	5.0000000000E+00	64	0	0.
65	0	0.	66	0	0.
67	0	0.	68	0	0.
69	1	6.0000000000E+00	70	0	0.
71	0	0.	72	0	0.
73	0	0.	74	0	0.
75	0	0.	76	0	0.
77	0	0.	78	0	0.
79	0	0.	80	0	0.
81	1	3.0000000000E+00	82	1	3.0000000000E+00
83	0	0.	84	0	0.
85	0	0.	86	0	0.
87	0	0.	88	0	0.
89	0	0.	90	1	1.1111100000E+06
91	0	0.	92	0	0.
93	0	0.	94	0	0.
95	0	0.	96	0	0.

Table A-4 Case I TV Characteristics, Albedos, and Imaging Values

JUPITER CHECK OUT CASE 1

TV CHARACTERISTICS FOR SIT WIDE ANGLE CAMERA (CAND)

6	FOC LN=	2.0000000E+01			
7	DIAM =	5.0000000E+00			
8	QB3CUR=	0.			
9	TRANS =	8.5000000E-01			
10	SIZE-V=	1.6000000E+00			
11	SIZE-H=	1.6000000E+00			
12	LINE=	8.0000000E+02			
13	PIXELS=	8.0000000E+02			
14	BIT/PIX=	8.0000000E+00			
15	MINEXP=	8.0000000E-06			
16	MAXEXP=	2.0000000E-03			
17	RESO-1=	3.0000000E+02			
18	RESO-2=	1.0000000E+02			
19	RESO-3=	5.0000000E+01			
20	RESO-4=	1.0000000E+01			
21	SENSOR=	1.0000000E+00			
22	B FILT=	1.0000000E+00			
23	G FILT=	1.0000000E+00			
24	R FILT=	1.0000000E+00			
25	P FILT=	-1.0000000E+00			
26	DT EXP=	1.0000000E-04			
27	OPEN =	1.0000000E-03			
28	OPEN =	1.0000000E-02			
29	T READ=	4.0000000E+01			
30	ERASET=	1.0000000E-01			
31	TSTART=	-1.5000000E+00	USER INPUT		
32	TSTOP =	1.5000000E+00	USER INPUT		
33	DEL T =	5.0000000E+00	USER INPUT		
34	BULK =	1.0000000E+09			
35	BULK-0=	0.			
36	BITRAT=	4.7400000E+04			
37	SCIBPS=	1.0000000E+02			
38	BUFFER=	5.1200000E+06			
39	PIC/ST=	6.0000000E+00	USER INPUT		
40	DEL TF=	5.0000000E+00			
41	F/STOP=	4.0000000E+00	COMPUTED VALUES		
42	A BLOC=	0.	COMPUTED VALUES		
43	DIF LM=	1.3420000E-05	COMPUTED VALUES		
44	FOV-V =	4.58122395E+00	COMPUTED VALUES		
45	FOV-H =	4.58122395E+00	COMPUTED VALUES		
46	RES-C =	1.0000000E-04	COMPUTED VALUES		
47	RES-V =	1.71053277E-06	COMPUTED VALUES		
48	RES-H =	1.71053277E-06	COMPUTED VALUES		
49	BIT/PC=	5.1200000E+06	COMPUTED VALUES		
50	RR-BPS=	1.2800000E+05	COMPUTED VALUES		
51	T/NUM=	4.33860316E+00	COMPUTED VALUES		
52	T/NUMF=	4.33860316E+00	COMPUTED VALUES		
53	OPEN =	0.	COMPUTED VALUES		
54	OPEN =	0.	COMPUTED VALUES		
55	OPEN =	0.	COMPUTED VALUES		
56	OPEN =	0.	COMPUTED VALUES		
57	OPEN =	0.	COMPUTED VALUES		
58	OPEN =	0.	COMPUTED VALUES		
59	OPEN =	0.	COMPUTED VALUES		
60	OPEN =	0.	COMPUTED VALUES		

JUPITER CHECK OUT CASE 1

TV ENERGY DATA FOR SIT WIDE ANGLE CAMERA (CAND)

PLANET 5 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF (W/SQCM)
.2500	.0070	.2030	0	1.0000	5.250000E-05	0.
.2750	.0204	.2820	.0020	1.0000	1.438200E-04	2.876400E-07
.3000	.0514	.2700	.0950	1.0000	3.463500E-04	3.295025E-05
.3250	.0971	.2650	.4760	1.0000	5.432375E-04	3.62049E-04
.3500	.1093	.2630	.7620	1.0000	7.350425E-04	5.631024E-04
.3750	.1157	.2720	.9530	1.0000	7.867600E-04	7.497323E-04
.4000	.1429	.2850	.9840	1.0000	1.031862E-03	1.001872E-03
.4250	.1693	.3150	1.0000	1.0000	1.333237E-03	1.333237E-03
.4500	.2006	.3540	.9840	1.0000	1.825460E-03	1.795253E-03
.4750	.2044	.3850	.9530	1.0000	1.967350E-03	1.974385E-03
.5000	.1942	.4360	.7940	1.0000	1.971130E-03	1.965077E-03
.5250	.1852	.4300	.7620	1.0000	1.930300E-03	1.917066E-03
.5500	.1725	.4500	.6820	1.0000	1.946625E-03	1.923506E-03
.5750	.1719	.4600	.5550	1.0000	1.976850E-03	1.997152E-03
.6000	.1666	.4650	.4760	1.0000	1.936725E-03	3.213811E-04
.6250	.1586	.4630	.4450	1.0000	1.853585E-03	8.275153E-04
.6500	.1511	.4700	.3600	1.0000	1.775425E-03	6.391930E-04
.6750	.1442	.4630	.2540	1.0000	1.693745E-03	4.294492E-04
.7000	.1369	.4530	.2060	1.0000	1.567535E-03	3.223960E-04
.7250	.1302	.4400	.1530	1.0000	1.432200E-03	2.277138E-04
.7500	.1235	.4100	.0950	1.0000	1.265875E-03	1.202581E-04
.7750	.1171	.3900	.0400	1.0000	1.112450E-03	4.443800E-05
.8000	.1167	.3550	.0240	1.0000	7.824625E-04	2.357310E-05
.8250	.1048	.3310	.0100	1.0000	8.645030E-04	8.645030E-05
.8500	.0988	.3150	.0030	1.0000	7.785000E-04	2.331500E-05
.8750	.0939	.3000	.0220	1.0000	7.042500E-04	1.549350E-05
.9000	.0889	.2820	0	1.0000	6.267450E-04	0.
.9250	.0862	.2640	0	1.0000	5.633200E-04	0.
.9500	.0835	.2460	0	1.0000	5.135250E-04	0.
.9750	.0791	.2320	0	1.0000	4.587300E-04	0.
1.0000	.0746	.2220	0	1.0000	4.140300E-04	0.

Table A-4 (cont)

## JUPITER CHECK OUT CASE 1

## TV ENERGY DATA FOR SIT WIDE ANGLE CAMERA (CAND)

## SATELLITE 1 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF (W/SQCM)
.2500	.0070	.0450	0	1.0000	3.150000E-05	0.
.2750	.0204	.0500	.0020	1.0000	1.020000E-04	2.040000E-07
.3000	.0514	.0550	.0950	1.0000	2.827000E-04	2.685650E-05
.3250	.0971	.0600	.4760	1.0000	5.826000E-04	2.773176E-04
.3500	.1093	.0650	.7620	1.0000	7.104500E-04	5.413629E-04
.3750	.1157	.0700	.9530	1.0000	8.099000E-04	7.718347E-04
.4000	.1429	.0750	.9840	1.0000	1.071750E-03	1.054602E-03
.4250	.1693	.0800	1.0000	1.0000	1.354400E-03	1.354400E-03
.4500	.2006	.0850	.9840	1.0000	1.705100E-03	1.677818E-03
.4750	.2044	.1000	.9530	1.0000	2.044000E-03	1.947932E-03
.5000	.1942	.1050	.7940	1.0000	2.039100E-03	1.619045E-03
.5250	.1852	.1130	.7620	1.0000	2.092760E-03	1.594683E-03
.5500	.1725	.1200	.6820	1.0000	2.070000E-03	1.411740E-03
.5750	.1719	.1250	.5550	1.0000	2.148750E-03	1.192556E-03
.6000	.1666	.1300	.4760	1.0000	2.165800E-03	1.030921E-03
.6250	.1586	.1350	.4450	1.0000	2.141100E-03	9.527895E-04
.6500	.1511	.1450	.3600	1.0000	2.190950E-03	7.887420E-04
.6750	.1442	.1550	.2540	1.0000	2.235100E-03	5.677154E-04
.7000	.1369	.1650	.2060	1.0000	2.258850E-03	4.653231E-04
.7250	.1302	.1700	.1590	1.0000	2.213400E-03	3.519306E-04
.7500	.1235	.1750	.0950	1.0000	2.161250E-03	2.053187E-04
.7750	.1171	.1800	.0400	1.0000	2.107800E-03	8.431200E-05
.8000	.1107	.1850	.0240	1.0000	2.047950E-03	4.915080E-05
.8250	.1048	.2900	.0100	1.0000	3.039200E-03	3.033200E-05
.8500	.0988	.2950	.0030	1.0000	2.914600E-03	8.743800E-06
.8750	.0939	.2000	.0220	1.0000	1.878000E-03	4.131600E-05
.9000	.0889	.2000	0	1.0000	1.778000E-03	0.
.9250	.0862	.2000	0	1.0000	1.724000E-03	0.
.9500	.0835	.2050	0	1.0000	1.711750E-03	0.
.9750	.0791	.2080	0	1.0000	1.645280E-03	0.
1.0000	.0746	.2100	0	1.0000	1.566600E-03	0.

## JUPITER CHECK OUT CASE 1

## TV ENERGY DATA FOR SIT WIDE ANGLE CAMERA (CAND)

## SATELLITE 2 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF (W/SQCM)
.2500	.0070	.0450	0	1.0000	3.150000E-05	0.
.2750	.0204	.0500	.0020	1.0000	1.020000E-04	2.040000E-07
.3000	.0514	.0550	.0950	1.0000	2.827000E-04	2.685650E-05
.3250	.0971	.0600	.4760	1.0000	5.826000E-04	2.773176E-04
.3500	.1093	.0650	.7620	1.0000	7.104500E-04	5.413629E-04
.3750	.1157	.0700	.9530	1.0000	8.099000E-04	7.718347E-04
.4000	.1429	.0750	.9840	1.0000	1.071750E-03	1.054602E-03
.4250	.1693	.0800	1.0000	1.0000	1.354400E-03	1.354400E-03
.4500	.2006	.0850	.9840	1.0000	1.705100E-03	1.677818E-03
.4750	.2044	.1000	.9530	1.0000	2.044000E-03	1.947932E-03
.5000	.1942	.1050	.7940	1.0000	2.039100E-03	1.619045E-03
.5250	.1852	.1130	.7620	1.0000	2.092760E-03	1.594683E-03
.5500	.1725	.1200	.6820	1.0000	2.070000E-03	1.411740E-03
.5750	.1719	.1250	.5550	1.0000	2.148750E-03	1.192556E-03
.6000	.1666	.1300	.4760	1.0000	2.165800E-03	1.030921E-03
.6250	.1586	.1350	.4450	1.0000	2.141100E-03	9.527895E-04
.6500	.1511	.1450	.3600	1.0000	2.190950E-03	7.887420E-04
.6750	.1442	.1550	.2540	1.0000	2.235100E-03	5.677154E-04
.7000	.1369	.1650	.2060	1.0000	2.258850E-03	4.653231E-04
.7250	.1302	.1700	.1590	1.0000	2.213400E-03	3.519306E-04
.7500	.1235	.1750	.0950	1.0000	2.161250E-03	2.053187E-04
.7750	.1171	.1800	.0400	1.0000	2.107800E-03	8.431200E-05
.8000	.1107	.1850	.0240	1.0000	2.047950E-03	4.915080E-05
.8250	.1048	.2900	.0100	1.0000	3.039200E-03	3.033200E-05
.8500	.0988	.2950	.0030	1.0000	2.914600E-03	8.743800E-06
.8750	.0939	.2000	.0220	1.0000	1.878000E-03	4.131600E-05
.9000	.0889	.2000	0	1.0000	1.778000E-03	0.
.9250	.0862	.2000	0	1.0000	1.724000E-03	0.
.9500	.0835	.2050	0	1.0000	1.711750E-03	0.
.9750	.0791	.2080	0	1.0000	1.645280E-03	0.
1.0000	.0746	.2100	0	1.0000	1.566600E-03	0.

Table A-4 (concl)

## JUPITER CHECK OUT CASE 1

## TV ENERGY DATA FOR SIT WIDE ANGLE CAMERA (CAND)

## SATELLITE 3 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF (W/SQCM)
.2500	.0070	.0450	0	1.0000	1.567125E-05	0.
.2750	.0204	.0500	.0020	1.0000	5.074500E-05	1.014900E-07
.3000	.0514	.0550	.0950	1.0000	1.406432E-04	1.336111E-05
.3250	.0971	.0600	.4760	1.0000	2.898435E-04	1.373655E-04
.3500	.1093	.0650	.7620	1.0000	3.534489E-04	2.693280E-04
.3750	.1157	.0700	.9530	1.0000	4.029252E-04	3.833378E-04
.4000	.1429	.0750	.9840	1.0000	5.331956E-04	5.246645E-04
.4250	.1693	.0800	1.0000	1.0000	6.738140E-04	6.738140E-04
.4500	.2006	.0850	.9840	1.0000	8.482872E-04	8.347147E-04
.4750	.2044	.1000	.9530	1.0000	1.016390E-03	9.690962E-04
.5000	.1942	.1050	.7940	1.0000	1.014452E-03	8.054751E-04
.5250	.1852	.1130	.7620	1.0000	1.041148E-03	7.933549E-04
.5500	.1725	.1200	.6820	1.0000	1.029825E-03	7.023406E-04
.5750	.1719	.1250	.5550	1.0000	1.069003E-03	5.932967E-04
.6000	.1666	.1300	.4760	1.0000	1.077485E-03	5.123831E-04
.6250	.1586	.1350	.4450	1.0000	1.065197E-03	4.740128E-04
.6500	.1511	.1450	.3600	1.0000	1.089398E-03	3.923391E-04
.6750	.1442	.1550	.2540	1.0000	1.111962E-03	2.824384E-04
.7000	.1369	.1650	.2060	1.0000	1.123778E-03	2.314382E-04
.7250	.1302	.1700	.1590	1.0000	1.101166E-03	1.750855E-04
.7500	.1235	.1750	.0950	1.0000	1.075222E-03	1.021461E-04
.7750	.1171	.1800	.0400	1.0000	1.048630E-03	4.194522E-05
.8000	.1107	.1850	.0240	1.0000	1.018355E-03	2.445252E-05
.8250	.1048	.2900	.0100	1.0000	1.512002E-03	1.512002E-05
.8500	.0988	.2350	.0030	1.0000	1.450013E-03	4.350040E-06
.8750	.0939	.2000	.0220	1.0000	9.343050E-04	2.055471E-05
.9000	.0889	.2000	0	1.0000	8.845550E-04	0.
.9250	.0862	.2000	0	1.0000	8.576900E-04	0.
.9500	.0835	.2050	0	1.0000	8.515956E-04	0.
.9750	.0791	.2080	0	1.0000	8.185268E-04	0.
1.0000	.0746	.2100	0	1.0000	7.793835E-04	0.

## JUPITER CHECK OUT CASE 1

## TV ENERGY DATA FOR SIT WIDE ANGLE CAMERA (CAND)

## SATELLITE 4 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF (W/SQCM)
.2500	.0070	.0450	0	1.0000	1.779750E-05	0.
.2750	.0204	.0500	.0020	1.0000	5.763000E-05	1.152600E-07
.3000	.0514	.0550	.0950	1.0000	1.597255E-04	1.517392E-05
.3250	.0971	.0600	.4760	1.0000	3.291690E-04	1.566844E-04
.3500	.1093	.0650	.7620	1.0000	4.014042E-04	3.058700E-04
.3750	.1157	.0700	.9530	1.0000	4.575935E-04	4.360866E-04
.4000	.1429	.0750	.9840	1.0000	6.055387E-04	5.958501E-04
.4250	.1693	.0800	1.0000	1.0000	7.652360E-04	7.652360E-04
.4500	.2006	.0850	.9840	1.0000	9.633815E-04	9.479674E-04
.4750	.2044	.1000	.9530	1.0000	1.154860E-03	1.100582E-03
.5000	.1942	.1050	.7940	1.0000	1.152091E-03	9.147607E-04
.5250	.1852	.1130	.7620	1.0000	1.182409E-03	9.003960E-04
.5500	.1725	.1200	.6820	1.0000	1.169550E-03	7.976331E-04
.5750	.1719	.1250	.5550	1.0000	1.214044E-03	6.737943E-04
.6000	.1666	.1300	.4760	1.0000	1.223677E-03	5.824703E-04
.6250	.1586	.1350	.4450	1.0000	1.209721E-03	5.383261E-04
.6500	.1511	.1450	.3600	1.0000	1.237887E-03	4.456392E-04
.6750	.1442	.1550	.2540	1.0000	1.262831E-03	3.207592E-04
.7000	.1369	.1650	.2060	1.0000	1.276250E-03	2.623076E-04
.7250	.1302	.1700	.1590	1.0000	1.250571E-03	1.983408E-04
.7500	.1235	.1750	.0950	1.0000	1.221106E-03	1.160051E-04
.7750	.1171	.1800	.0400	1.0000	1.190907E-03	4.763628E-05
.8000	.1107	.1850	.0240	1.0000	1.157092E-03	2.777020E-05
.8250	.1048	.2900	.0100	1.0000	1.717148E-03	1.717148E-05
.8500	.0988	.2950	.0030	1.0000	1.646749E-03	4.940247E-06
.8750	.0939	.2000	.0220	1.0000	1.061070E-03	2.334354E-05
.9000	.0889	.2000	0	1.0000	1.004570E-03	0.
.9250	.0862	.2000	0	1.0000	9.740600E-04	0.
.9500	.0835	.2050	0	1.0000	9.671387E-04	0.
.9750	.0791	.2080	0	1.0000	9.295832E-04	0.
1.0000	.0746	.2100	0	1.0000	8.851290E-04	0.



b. Output Data - For any imaging case run there is a set of general calculations made and the results printed. These data are "computations for minimum picture taking interval," "picture numbering and associated times," and "exposure/exposure-time check and adjustments" (Table A-5). The remaining tab print (Table A-6) is associated directly with the graphic output discussed below. Each requested print set consists of two pages.

The first graphic output (Fig. A-1) shows overall flyby encounter geometry with planet and satellite positions, and trajectory with hourly time markings. Figure A-2 shows scenes both before and after closest approach. (When the planet fills the field of view, the field of view is shown by a rectangular area on the planet.) Figure A-3 shows summary cone and clock plots. The circles represent the main planet; the plus signs indicate that the distance from the satellite to the spacecraft is greater than the distance from the planet to the spacecraft; the asterisks indicate that the distance from the satellite to the spacecraft is less than the distance from the planet to the spacecraft.

Table A-5 Results of General Calculations

JUPITER CHECK OUT CASE 1

COMPUTATIONS FOR MINIMUM PICTURE TAKING INTERVAL

PICTURE START TIME (DAYS) = -1.50000000E+00
PICTURE STOP TIME (DAYS) = 1.50000000E+00
DELTA T REQUESTED (SEC) = 3.00000000E+02
FRAME READ TIME (SEC) = 4.00000000E+01
FRAME READ RATE (FPS) = 1.20000000E+05

BULK DATA STORAGE CAPACITY (BITS) = 1.10000000E+09
PICTURE SIZE (BITS) = 5.12000000E+06
BULK DATA STORAGE CAPACITY (PICS) = 1.15312500E+02
BULK CONTENTS IN USE (BITS) = 0.
BUFFER STORAGE CAPACITY (BITS) = 5.12000000E+06

DATA TRANSMISSION RATE (BPS) = 4.74000000E+04
RATE FROM OTHER INSTRUMENTS (BPS) = 1.00000000E+02
REAL TIME PICTURE RATE (BPS) = 4.73000000E+04

MINIMUM PICTURE INTERVAL (SEC) = 1.00245243E+02
MAXIMUM PICTURE RATE (PICS/HR) = 3.32579125E+01
MAXIMUM PICTURE RATE (PIC/JAY) = 7.30107500E+02
MAXIMUM NUMBER OF PICTURES = 2394
ACTUAL PICTURE RATE (PIC/JAY) = 2.36000000E+02
ACTUAL NUMBER OF PICTURES = 064

PERIAPSIS STATE VECTOR

1.27064424E+05 2.13219877E+05 -1.33070500E+04
-2.94315539E+01 1.76103607E+01 1.14193605E+00

VIEW FROM INPUT VIEWPOINT

JUPITER CHECK OUT CASE 1

PLOT INTERVAL = 3 CALC STEPS = 90.00 MINUTES
PRNT INTERVAL = 3CALC STEPS = 90.00 MINUTES

TIME INTERVAL FOR CALCULATIONS = 30.00 MINUTES

Table with 4 columns: PICTURE CALC, TIME (DAYS), TIME (HRS), TIME (MIN). Contains 313 rows of data.

Main data table with 4 columns: Line number, X coordinate, Y coordinate, Z coordinate. Contains 313 rows of data.

JUPITER CHECK OUT CASE 1
SIT WIDE ANGLE CAMERA (CANO)

EXPOSURE TOO HIGH 8.860E-03 (ERGS/CM\*\*2)
EXPOSURE TIME REDUCED TO 1.920E-05 SEC
EXPOSURE IS 1.701E-03 (ERG/CM\*\*2)

CHG 1
EXPOSURE TIME SET TO 0.1 MILLISEC
REQUIRED FILTER FACTOR IS 5.200E+00
CHG 1
VIEW FROM SPACECRAFT

Table A-6 Printout Associated with Graphic Output

JUPITER CHECK OUT CASE 1

PICTURE NUMBER 1 -1 DAYS 12 HRS 0 MIN TO ENCOUNTER JD 2443886.692

PLANET JUPITE	SATELLITE EUROP
RANGE (KM) = 2.44010834E+06	RANGE (KM) = 2.40077098E+06
CONE (DEG) = 168.45	CONE (DEG) = 152.48
CLOCK (DEG) = 80.70	CLOCK (DEG) = 83.76
PHASE (DEG) = 9.11	PHASE (DEG) = 25.08
DIAM (DEG) = 3.35	DIAM (DEG) = .07

RESOLUTION OF PLANET  
 CENTER = 236.87 KM/PIXEL  
 LIMB = 243.91 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITE (PICTURE CENTERED AT 1.74 DEG LAT 97.42 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 235.87 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 9.18 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 645.53 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .07 KM  
 NUMBER OF PIXELS SMEARED .00028 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 181.812 MILLISEC

EFFECTIVE RESOLUTION WITH SMEAR  
 AT SPECIFIED LOCATION 236.9 KM/PIXEL  
 AT SUBSPACECRAFT POINT 236.9 KM/PIXEL  
 AT LIMB OF TARGET BODY 244.0 KM/PIXEL

EXPOSURE TIME FOR SIT WIDE ANGLE CAMERA (CAND) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 8.8599E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.7612E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 85.000  
 DIGITAL NUMBER OF EXPOS = 217 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN RESOLUTION LEVELS	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	1.0	0.	0.	0.	
SATELLITE 1	1.0000	0.	0.	0.	
SATELLITE 2	1.0000	0.	0.	0.	
SATELLITE 3	0.	0.	0.	0.	
SATELLITE 4	0.	0.	0.	0.	

SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	2.78976597E+06	14.29	163.27	83.30
2	2.40077098E+06	25.08	152.48	83.76
3	3.31513930E+06	21.54	156.03	84.75
4	4.32575521E+06	5.95	171.61	83.64

NUM	EARTH-SAT-S/G ANG	SATELLITE ANG DIAM
1	1.42930608E+01	6.85964046E-02
2	2.50775989E+01	6.96874829E-02
3	2.15370295E+01	8.81436580E-02
4	5.95468279E+00	6.25176598E-02

RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	2.78809601E+02	2.78976551E+02
2	2.39331102E+02	2.40077057E+02
3	3.31258935E+02	3.31513837E+02
4	4.32339529E+02	4.32575464E+02

SMEAR DATA FOR SATELLITES

SMEAR DUE TO VEL (KM/SEC)	SMEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
1.67361634E+01	7.34089223E+02	2.84626911E-04	1.75668562E-01
8.20284742E-01	7.08367738E+02	2.35013473E-04	1.69480339E-01
9.47394473E+00	9.64335622E+02	2.92595717E-04	1.70484251E-01
1.25685210E+01	1.14862876E+03	2.67398834E-04	1.86986604E-01

VIEW FROM SPACECRAFT

Table A-6 (cont)

JUPITER CHECK OUT CASE 1

PICTURE NUMBER 361 J DAYS 0 HRS 0 MIN TO ENCOUNTER JD 2443887.942

PLANET JUPITE	SATELLITE EUROP
RANGE (KM) = 5.72306335E+05	RANGE (KM) = 1.23328999E+06
CONE (DEG) = 155.47	CONE (DEG) = 160.43
CLOCK (DEG) = 261.79	CLOCK (DEG) = 262.33
PHASE (DEG) = 26.65	PHASE (DEG) = 21.68
DIAM (DEG) = 14.33	DIAM (DEG) = .14

RESOLUTION OF PLANET  
 CENTER = 50.09 KM/PIXEL  
 LIMB = 56.78 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITE (PICTURE CENTERED AT -1.62 DEG LAT 115.74 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 50.09 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 2.58 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 91.46 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .01 KM  
 NUMBER OF PIXELS SMEARED .00018 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 277.321 MILLISEC

EFFECTIVE RESOLUTION WITH SMEAR  
 AT SPECIFIED LOCATION 50.1 KM/PIXEL  
 AT SUBSPACE-CFT POINT 50.1 KM/PIXEL  
 AT LIMB OF TARGET BODY 56.9 KM/PIXEL

EXPOSURE TIME FOR SIT WIDE ANGLE CAMERA (CAND) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.7775E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.7775E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 33.830  
 DIGITAL NUMBER OF EXPOS = 227 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-05 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN RESOLUTION LEVELS	RESOLUTION LEVELS				KM/PIXEL
	300.0	100.0	50.0	10.0	
PLANET	351.0	85.0	0.	0.	
SATELLITE 1	361.0000	109.0000	49.0000	0.	
SATELLITE 2	361.0000	0.	0.	0.	
SATELLITE 3	271.0000	0.	0.	0.	
SATELLITE 4	97.0000	0.	0.	0.	

SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	1.53315945E+05	23.13	158.96	248.68
2	1.23328999E+06	21.68	160.43	262.33
3	1.63058411E+05	16.93	165.18	262.46
4	2.46899823E+06	25.28	156.83	264.60

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	2.36976143E+01	1.24821778E+00
2	2.16837591E+01	1.35656429E-01
3	1.69308402E+01	1.79204858E-01
4	2.52815548E+01	1.09532732E-01

RESOLUTION (KM/PIX) DATA FOR SATELLITES  
 NUM RES ALONG RADIUS VECTOR RES AT SATELLITE LIMB

1	1.51645947E+01	1.53306852E+01
2	1.23183011E+02	1.23328914E+02
3	1.62803414E+02	1.63058214E+02
4	2.46663827E+02	2.46899714E+02

SMEAR DATA FOR SATELLITES

SMEAR DUE TO VEL (KM/SEC)	SMEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
4.85481854E+00	2.73420799E+01	1.48417411E-04	3.36887699E-01
2.69766284E+01	2.41557681E+02	2.13702817E-04	2.33963775E-01
2.22241117E+01	3.34973567E+02	2.19099538E-04	2.28206718E-01
2.26730036E+01	4.68356606E+02	1.97543887E-04	2.53108314E-01

SATELLITE OBSCURED BY PLANET -.23DAYS FROM ENCOUNTER  
 SATELLITE OBSCURED BY PLANET -.21DAYS FROM ENCOUNTER  
 SATELLITE OBSCURED BY PLANET -.19DAYS FROM ENCOUNTER



Table A-6 (concl)

JUPITER CHECK OUT CASE 1

PICTURE NUMBER 865 1 DAYS 11 HRS 59 MIN TO ENCOUNTER JD 2443889.692

PLANET JUPITE	SATELLITE EUROP
RANGE (KM) = 2.44010854E+06	RANGE (KM) = 2.93926958E+06
CONE (DEG) = 60.10	CONE (DEG) = 50.27
CLOCK (DEG) = 81.55	CLOCK (DEG) = 81.60
PHASE (DEG) = 117.94	PHASE (DEG) = 127.77
DIAM (DEG) = 3.35	DIAM (DEG) = .06

RESOLUTION OF PLANET  
 CENTER = 236.87 KM/PIXEL  
 LIMB = 243.91 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITE (PICTURE CENTERED AT 4.94 DEG LAT 293.26 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 240.32 KM/PIXEL  
 SHEAR DUE TO RELATIVE VELOCITIES 2.53 KM/SEC  
 SHEAR DUE TO S/C ATTITUDE RATES 369.36 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .04 KM  
 NUMBER OF PIXELS SMEARED .00015 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SHEAR 323.125 MILLISEC

EFFECTIVE RESOLUTION WITH SHEAR  
 AT SPECIFIED LOCATION 240.4 KM/PIXEL  
 AT SUBSPACECRAFT POINT 236.9 KM/PIXEL  
 AT LIMB OF TARGET BODY 243.9 KM/PIXEL

EXPOSURE TIME FOR SIT WIDE ANGLE CAMERA (CAND) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.3955E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.3955E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 69.654  
 DIGITAL NUMBER OF EXPOS = 178 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-06 ERGS/SQ CM

	NUMBER OF PICTURES WITH RESOLUTION BETTER THAN				
	RESOLUTION LEVELS	300.0	100.0	50.0	10.0
PLANET	865.0	313.0	133.0	0.	
SATELLITE 1	865.0000	403.0000	157.0000	11.0000	
SATELLITE 2	865.0000	211.0000	43.0000	0.	
SATELLITE 3	775.0000	307.0000	157.0000	0.	
SATELLITE 4	601.0000	301.0000	181.0000	0.	

SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	2.78313516E+06	123.28	54.77	81.83
2	2.93926958E+06	127.77	50.27	81.60
3	1.72829623E+06	140.04	38.02	76.37
4	5.67946095E+05	117.88	60.24	64.81

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	1.23275797E+02	6.87598352E-02
2	1.27772229E+02	5.69201560E-02
3	1.40036566E+02	1.69073204E-01
4	1.17881802E+02	4.76166418E-01

RESOLUTION (KM/PIX) DATA FOR SATELLITES -

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	2.78146521E+02	2.78313471E+02
2	2.93780963E+02	2.93926926E+02
3	1.72574626E+02	1.72829438E+02
4	5.65586104E+01	5.67941201E+01

SHEAR DATA FOR SATELLITES

SHEAR DUE TO VEL (KM/SEC)	SHEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SHEAR 1/2 PIXEL (SEC)
1.96056250E+01	4.18503561E+02	1.57280779E-04	3.17902800E-01
1.69056770E+01	4.32232616E+02	1.52841459E-04	3.27136369E-01
3.96769902E+00	2.43645019E+02	1.43430593E-04	3.48473185E-01
5.72318634E+00	5.15943588E+01	8.11782522E-05	6.15923511E-01

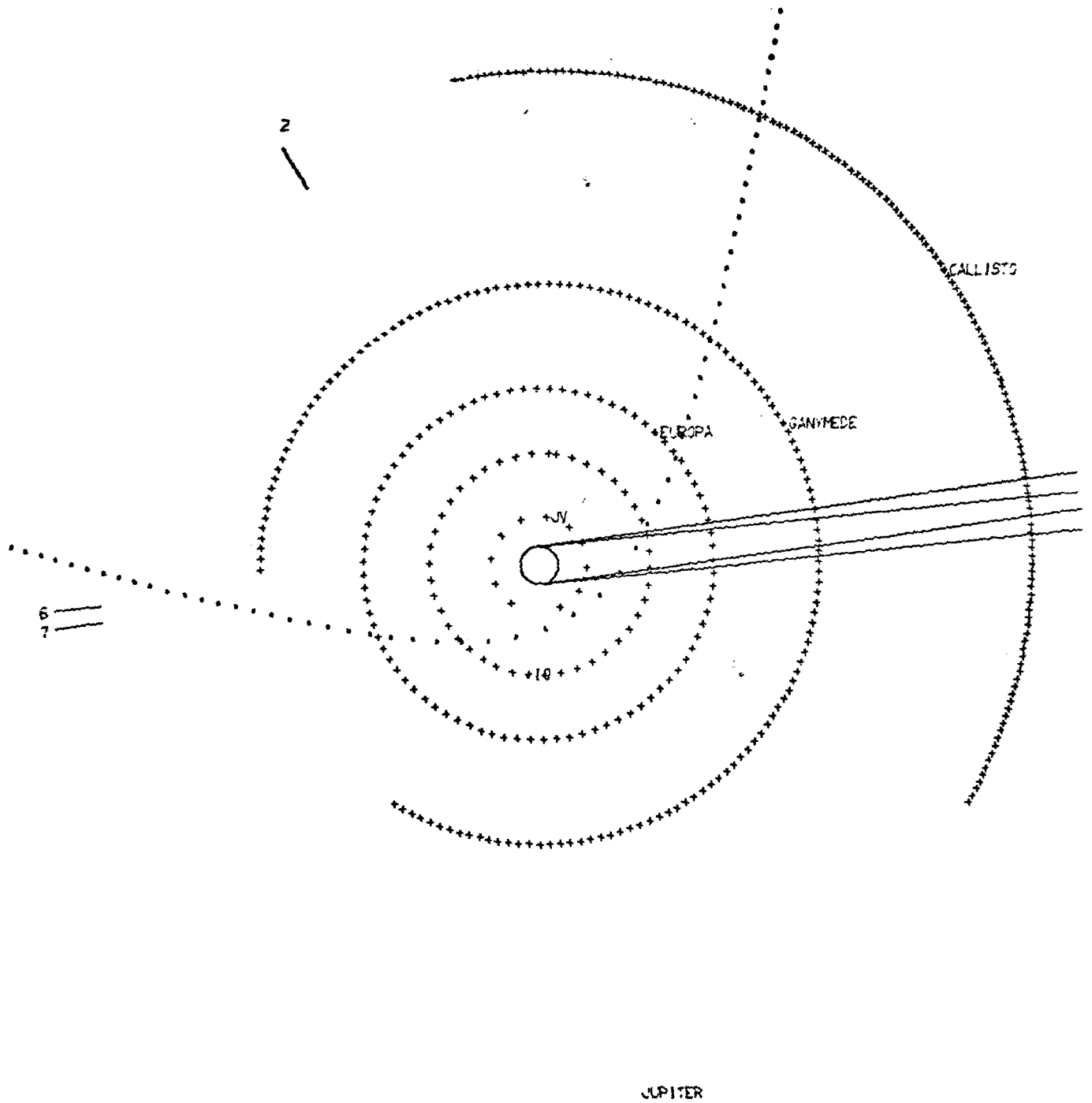
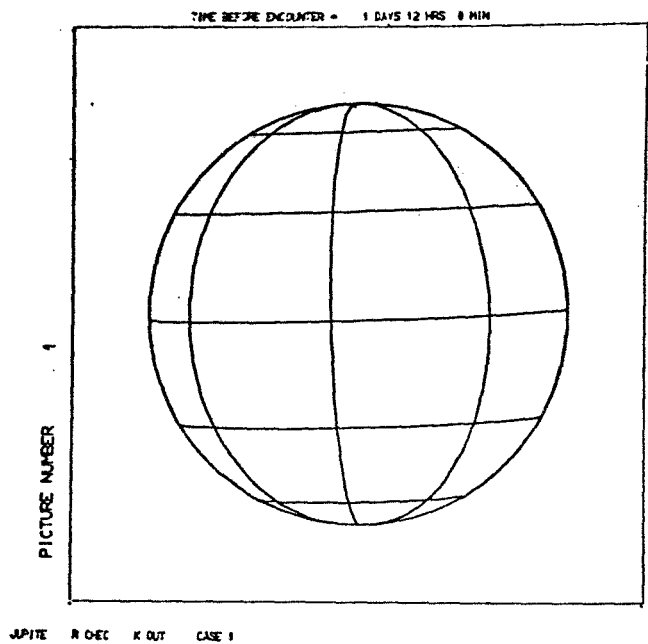
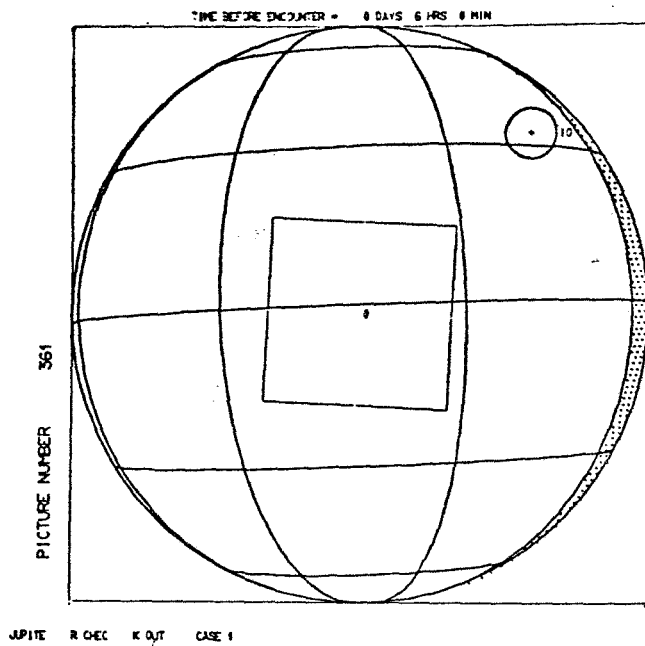


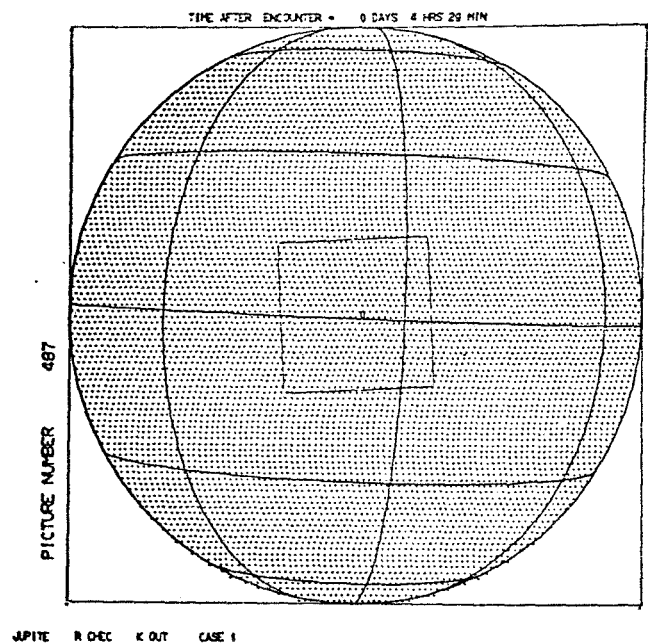
Fig. A-1 Flyby Encounter Geometry



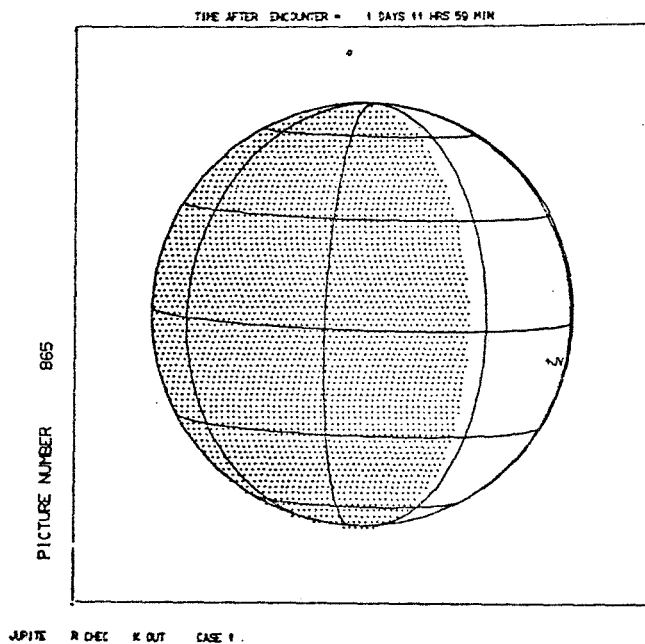
JUPITER



JUPITER



JUPITER



JUPITER

Fig. A-2 Scenes Before and After Closest Approach



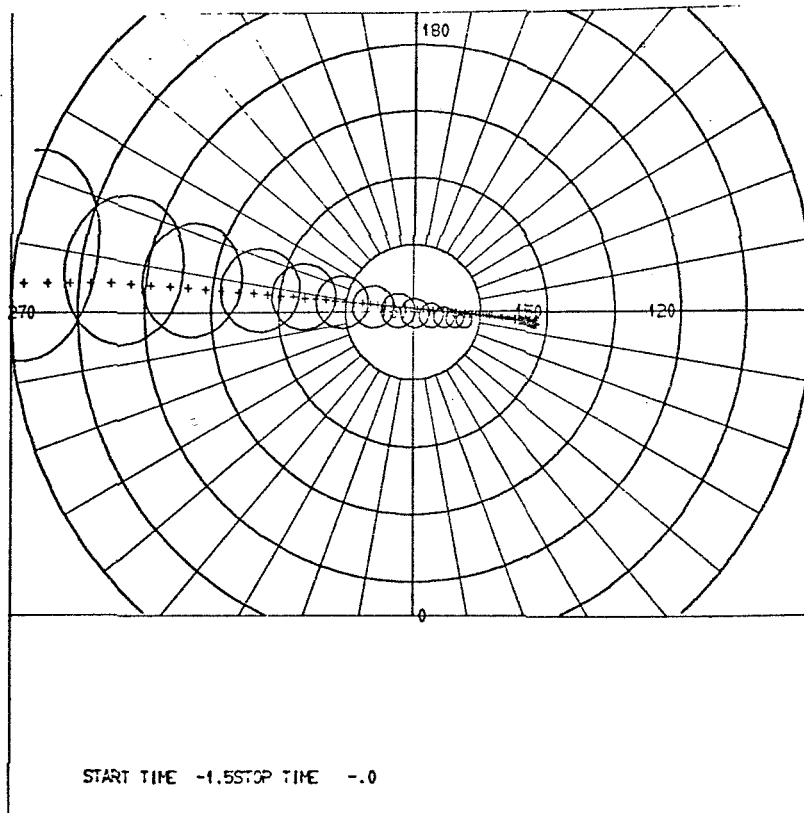
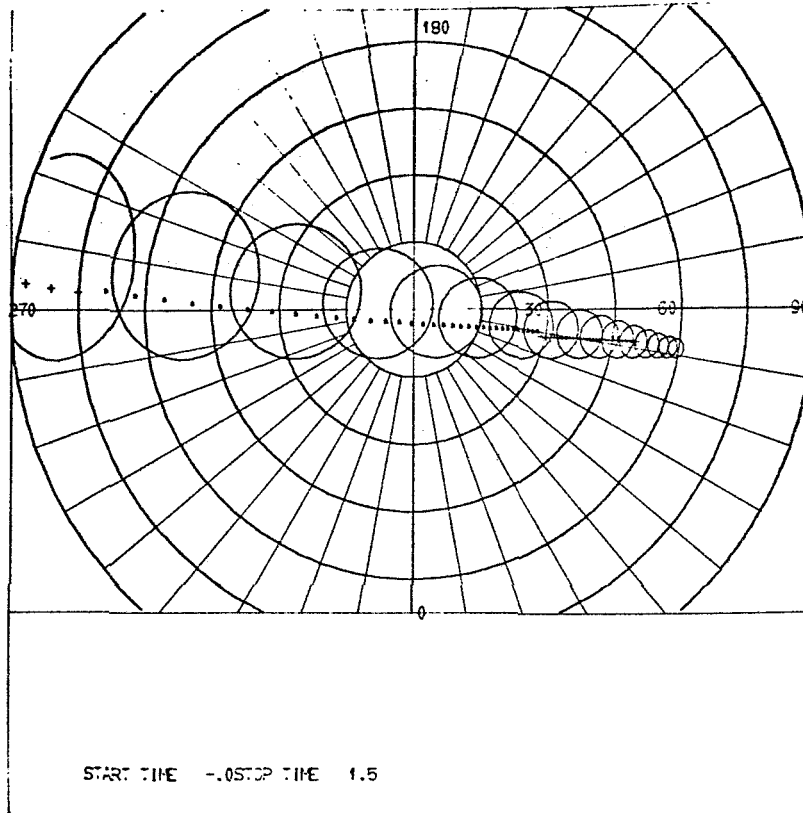


Fig. A-3 Summary Cone and Clock Plots

5. Case 2

a. Input Data - The tabular input data are shown on Table A-7 with input control 23 equal to 1.0, signifying cone and clock user option. There are three sets of discrete cone and clock positions corresponding to pointing modes of nonlimb, intermediate, and radius vector (planet center). These are designated cases 2-1, 2-2, and 2-3, respectively.

Table A-7 Case 2 Input Listing

JUPITER CHECK OUT CASE 2

```

2 5.000000 PLANET JUPITER (J-S-P) WIDE ANGLE SIT (10 DEG) TOPS
3 20000000 SATCL EUROPA (J-II)
4 736114.69 JATE JD AT ENCOUNTER
6 15.000000
7 127364.46 STATE1
8 213215.95 STATE2 PERIAPSIS VECTOR FROM LEADLETTERS
9 -13387.652 STATE3 79 JSP RJN TO MAXIMIZE SATELLITE
10 -29.43152 STATE4 ENCOUNTER
11 17.61363 STATE5
12 1.1410353 STATE6
22 120.30000 INSTI INSTRUMENT ID (TV, WIDE ANGLE SIT)
23 1.6300000
26 -.2220000
24 151.65000
25 247.70000
26 -.1670000
24 141.34000
25 247.62000
26 -.1110000
24 125.66000
25 247.54000
26 -55.00000000E-03
24 100.92000
25 247.46000
26 0.
24 65.68000
25 247.37000
26 55.00000000E-03
24 30.44000
25 233.18000
26 .1110000
24 5.7100000
25 189.92000
26 .1670000
24 3.9600000
25 14.30000
26 .2220000
24 26.27000
25 59.05000
26 -.2220000
24 151.65000
25 254.76000
26 -.1670000
24 141.34000
25 254.62000
26 -.1110000
24 125.66000
25 254.54000
26 -55.00000000E-03
24 100.92000
25 247.46000
26 0.
24 65.68000
25 247.37000
26 55.00000000E-03
24 30.44000
25 247.18000
26 .1110000
24 5.7100000
25 224.92000
26 .1670000
24 3.9600000
25 34.34000
26 .2220000
24 26.27000
25 75.05000
26 -.2220000
24 151.65000
25 261.70000
26 -.1670000
24 141.34000
25 261.62000
26 -.1110000
24 125.66000
25 261.54000
26 -55.00000000E-03
24 100.92000
25 261.46000
26 0.
24 65.68000
25 261.37000
26 55.00000000E-03
24 30.44000
25 261.18000
26 .1110000
24 5.7100000
25 259.92000
26 .1670000
24 3.9600000
25 32.30000
26 .2220000
24 26.27000
25 81.05000
45 81.00000000E-07 CHAR10 SIT MIN DLECTABLE EXP
46 20.00000000E-14 CHAR11 SIT HIGH-LIGHT EXP
51 1.0000000 NO
61 -1.5000000 TSTAR TIME FROM PERIAPSIS
62 1.5000000 TSTOP TIME FROM PERIAPSIS
63 3.0000000 DTINSTPICTURE TAKING INTERVAL (MIN)
64 10000000E+01 TORAGE CAPACITY
65 0. BULK STORAGE ZERO STATE
66 47400.000 BITRAT TRANSMIT BIT RATE HALF FOR EACH CAMERA
67 540.00000 DATA RATE FROM OTHER INSTRUMENTS
68 2000000.0 BUFFER STORAGE CAPACITY
69 6.0000000 CALCSTPICTURES PER CALC STEP 30 MIN PER CALC STEP
81 1.0000000 DPL0T
82 1.0000000 UPRNT
90 1111111.0
98

```

D 2443867.970

11 DEG LONG )

IXEL

(CASE 2-1)

(CASE 2-2)

(CASE 2-2)

(CASE 2-3)

(CASE 2-3)

b. Output Data - Tabular output (Table A-8) is in three parts: near limb, intermediate, and radius vector cone and clock pointing. Two tabular picture frame summaries, given for each pointing case, correspond to the first and last time points for the cone and clock runs. By comparing the resolution numbers between cases, it can be seen that the cone and clock input is exercised.

Graphic output was selected for the radius vector case 2-3 showing start and stop times of 5<sup>h</sup> 19<sup>m</sup> from closest approach (Fig. A-4). Summary cone and clock plots before and after closest approach are shown in Fig. A-5.

Table A-8 (cont)

JUPITER CHECK OUT CASE 2-1; NEAR LIMB CONE &amp; CLOCK POINTING

PICTURE NUMBER 49 0 DAYS 5 HRS 19 MIN TO ENCOUNTER JD 2443888.414

PLANET JUPITE	SATELLITE EUROP
RANGE (KM) = 5.25260368E+05	RANGE (KM) = 4.62866579E+05
CONE (DEG) = 20.32	CONE (DEG) = 64.60
CLOCK (DEG) = 81.89	CLOCK (DEG) = 268.01
PHASE (DEG) = 157.63	PHASE (DEG) = 117.44
DIAM (DEG) = 15.62	DIAM (DEG) = .36

RESOLUTION OF PLANET  
 CENTER = 45.39 KM/PIXEL  
 LIMB = 52.04 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITE (PICTURE CENTERED AT -71.71 DEG LAT 297.16 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 52.03 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 15.10 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 90.93 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .01 KM  
 NUMBER OF PIXELS SMEARED .00015 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 327.102 MILLISEC

EFFECTIVE RESOLUTION WITH SMEAR  
 AT SPECIFIED LOCATION 52.0 KM/PIXEL  
 AT SUBSPACECRAFT POINT 45.4 KM/PIXEL  
 AT LIMB OF TARGET BODY 52.0 KM/PIXEL

EXPOSURE TIME FOR SIT WIDE ANGLE CAMERA (CAND) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 3.7531E+00 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 3.7531E-04 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 18.439  
 DIGITAL NUMBER OF EXPOS = 47 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN	RESOLUTION LEVELS					KM/PIXEL
	300.0	100.0	50.0	10.0		
PLANET	49.0	49.0	49.0	0.		
SATELLITE 1	49.0000	49.0000	37.0000	7.0000		
SATELLITE 2	49.0000	37.0000	7.0000	0.		
SATELLITE 3	49.0000	19.0000	0.	0.		
SATELLITE 4	49.0000	0.	0.	0.		

## SATELLITE DATA (CASE 2-1; NEAR LIMB CONE &amp; CLOCK POINTING)

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	6.01258871E+05	114.26	63.69	85.43
2	4.62866579E+05	117.44	64.60	268.01
3	5.71829026E+05	47.52	134.52	267.60
4	1.38983254E+06	39.76	142.29	266.84

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	1.14263260E+02	3.18279129E-01
2	1.17444529E+02	3.61451791E-01
3	4.75178101E+01	5.11008414E-01
4	3.97587436E+01	1.94581867E-01

RESOLUTION (KM/PIX) DATA FOR SATELLITES		RES AT SATELLITE LIMB
NUM	RES ALONG RADIUS VECTOR	
1	5.99588881E+01	6.01256562E+01
2	4.61406586E+01	4.62864284E+01
3	5.69279036E+01	5.71823350E+01
4	1.38747256E+02	1.38983056E+02

SMEAR DATA FOR SATELLITES			
SMEAR DUE TO VEL (KM/SEC)	SMEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
7.66707959E+00	1.05641013E+02	1.88681975E-04	2.64996166E-01
2.93291698E+01	1.33810723E+02	3.26972393E-04	1.52918109E-01
4.83290033E+00	9.53904715E+01	1.75208333E-04	2.85374473E-01
2.49213573E+00	2.34774236E+02	1.68580207E-04	2.96594725E-01

SATELLITE OBSERVED BY PLANET -.220DAYS FROM ENCOUNTER  
 VIEW FROM SPACECRAFT

Table A-8 (cont)

JUPITER CHECK OUT CASE 2-2 INTERMEDIATE CONE & CLOCK POINTING

PICTURE NUMBER 55 0 DAYS 5 HRS 19 MIN TO ENCOUNTER JD 2443887.370

PLANET JUPITE RANGE (KM) = 5.25260868E+05 SATELLITE EUROP RANGE (KM) = 1.18556282E+06  
 CONE (DEG) = 151.53 CONE (DEG) = 157.28  
 CLOCK (DEG) = 261.74 CLOCK (DEG) = 262.61  
 PHASE (DEG) = 30.58 PHASE (DEG) = 24.83  
 DIAM (DEG) = 15.62 DIAM (DEG) = .14

RESOLUTION OF PLANET

CENTER = 45.39 KM/PIXEL  
 LIMB = 52.04 KM/PIXEL

INSTRUMENT DATA FOR PLANET JUPITE

(PICTURE CENTERED AT 13.51 DEG LAT 98.97 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 45.98 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 4.78 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 74.35 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .01 KM  
 NUMBER OF PIXELS SMEARED .00016 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 318.551 MILLISEC

EFFECTIVE RESOLUTION WITH SMEAR

AT SPECIFIED LOCATION 46.0 KM/PIXEL  
 AT SUBSPACECRAFT POINT 45.4 KM/PIXEL  
 AT LIMB OF TARGET BODY 52.0 KM/PIXEL

EXPOSURE TIME FOR SIT WIDE ANGLE CAMERA (CAND) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.2637E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.2637E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 63.036  
 DIGITAL NUMBER OF EXPOS = 161 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN		RESOLUTION LEVELS				KM/PIXEL
		300.0	100.0	50.0	10.0	
PLANET	35.0	55.0	55.0	55.0	0.	
SATELLITE 1	55.0000	55.0000	43.0000	7.0000	7.0000	
SATELLITE 2	55.0000	37.0000	7.0000	0.	0.	
SATELLITE 3	55.0000	19.0000	0.	0.	0.	
SATELLITE 4	55.0000	0.	0.	0.	0.	

SATELLITE DATA CASE 2-2 (CONTINUED)

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	1.09803488E+05	19.77	162.10	233.15
2	1.18556282E+06	24.83	157.28	262.61
3	1.57983912E+06	18.87	163.24	262.66
4	2.42053945E+06	26.56	155.53	264.60

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	1.97743957E+01	1.74288891E+00
2	2.48314665E+01	1.41117549E-01
3	1.88707342E+01	1.84960986E-01
4	2.65764770E+01	1.11725559E-01

RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	1.08133490E+01	1.09790790E+01
2	1.18410284E+02	1.18556194E+02
3	1.57728915E+02	1.57983709E+02
4	2.41817949E+02	2.42053834E+02

SMEAR DATA FOR SATELLITES

SMEAR DUE TO VEL (KM/SEC)	SMEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
6.52377351E+00	2.00073108E+01	1.26869103E-04	3.94106987E-01
2.80201480E+01	2.23070245E+02	2.08156334E-04	2.40204076E-01
2.27720538E+01	3.21505967E+02	2.14970246E-04	2.32590328E-01
2.30808932E+01	4.91932016E+02	1.35000773E-04	2.56403241E-01

SATELLITE OBSCURED BY PLANET -.170 DAYS FROM ENCOUNTER VIEW FROM SPACECRAFT

SUBROUTINE FIND HAD TROUBLE









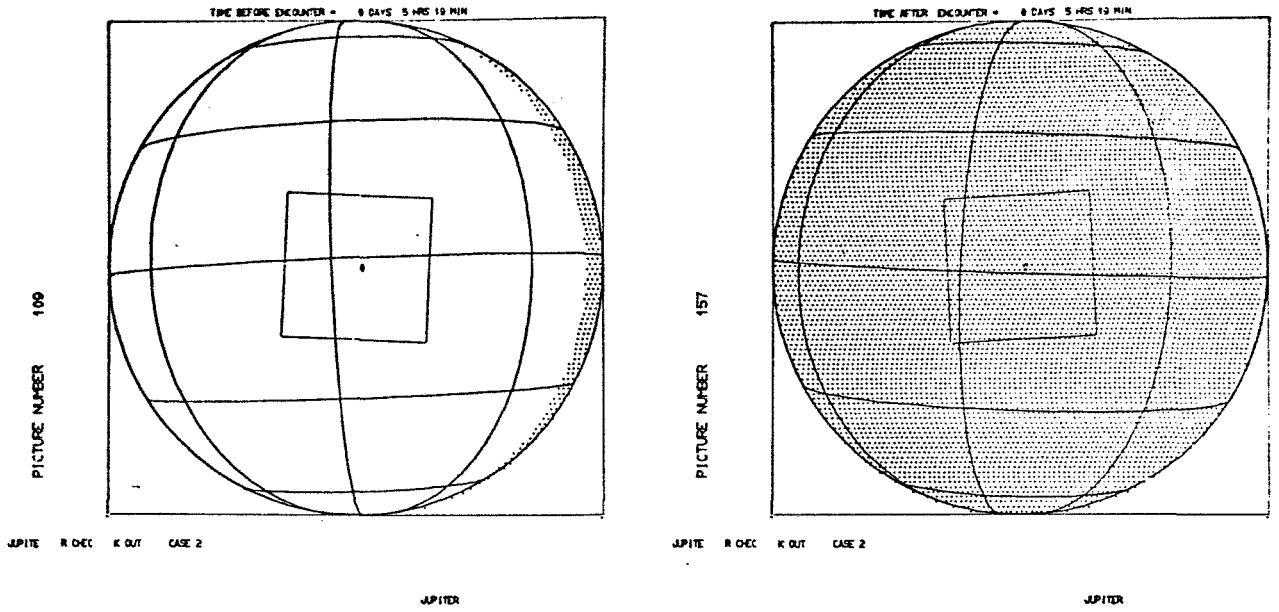


Fig. A-4 Scenes Before and After Closest Approach (Case 2-3)

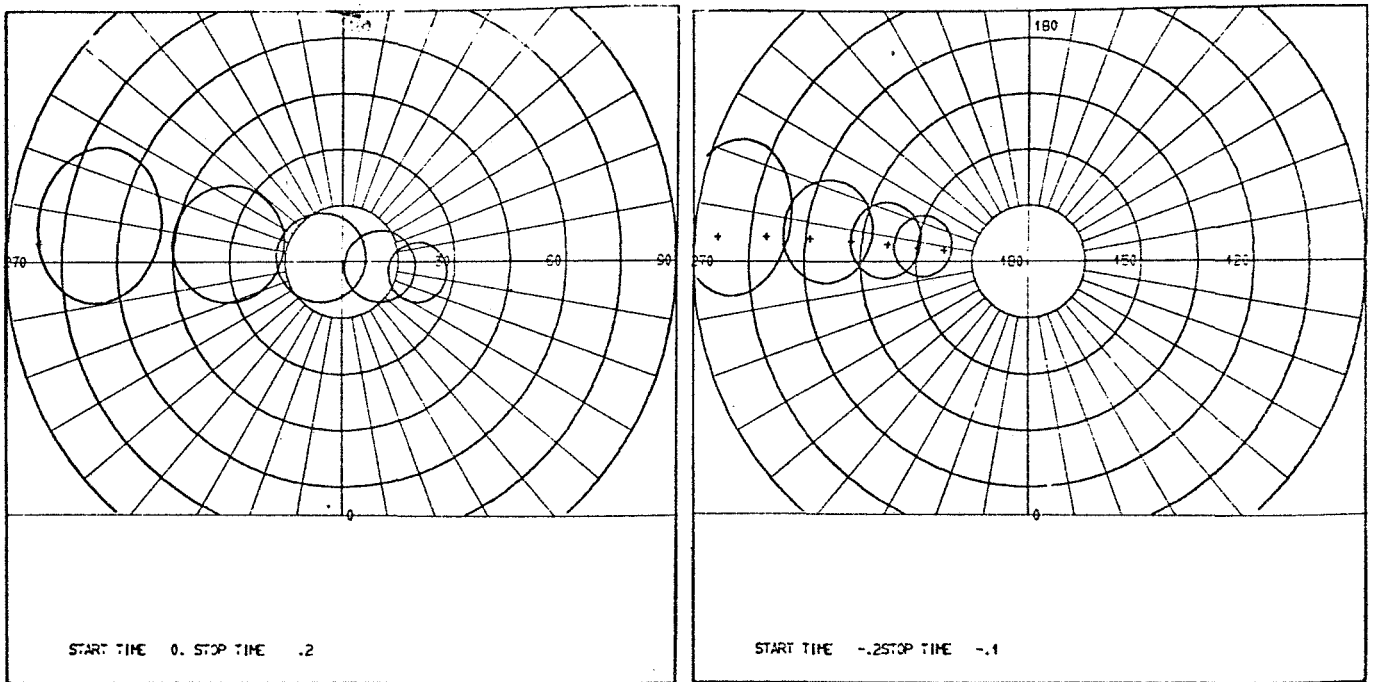


Fig. A-5 Summary Cone and Clock Plots

## B. MISSION 2

The specific objective of Mission 2 is to provide the data required to validate the "imaging" analysis capability. This mission includes the cases shown in Table A-1. Mission 2 exercises two cameras, two planet flybys, and natural satellite encounters.

The spacecraft is a TOPS configuration, with Earth/Canopus attitude control.

1. Science Mode

Data are provided to check out the imaging mission analysis capability, (i.e., the interface between instrument module, trajectory geometry, summary calculations, and data display) with targets of Jupiter, Jupiter-natural satellites, and Saturn. The complete set of measurement mode capabilities is used via combinations of instrument pointing and frame timing modes. The total number of runs is four, with variations as follows:

POINTING

Align to Radius Vector

Input Discrete Cone/Clock

CAMERA FOR

Wide-angle Field of View

Narrow-angle Field of View

CAMERA CHARACTERISTICS

Command Instrument Values

User Input Values

SATELLITE

None

One

Multinumber

PLANETS

Jupiter

Saturn

2. Instrument Characteristics

The imaging system characteristics for Mission 2 are shown in Table A-9. The majority of logic flow through the equations is validated by switching from the narrow- to the wide-angle camera, and by switching between command instrument values and user instrument values. The matrix of runs and associated values that exercise the two cameras and other variations are presented in the "Input Data" paragraphs for each case.

Table A-9 Imaging System Characteristics

<u>PARAMETER</u>	<u>SYMBOL</u>	<u>UNITS</u>	<u>NARROW-ANGLE CAMERA</u>	<u>WIDE-ANGLE CAMERA</u>
Focal Length	F	cm	200	20
Aperture (diam)	D	cm	23	5
Obscuration	OBSC	%	0.0	0.0
Optics Transmission	Trans	%	85.0	85.0
Horizontal		cm	1.6x1.6	1.6x1.6
No. of Scan Lines	NLINES		800	800
No. of Pixels per Scan Line	NPIXEL		800	800
No. of Bits per Pixel	BPPIX	bits	8	8
Minimum Detectable Exposure		ft-ca-sec	0.003	0.003
Maximum or High Light Exposure		ft-ca-sec	0.3	0.3
Sensor Response Curve			S-20	S-20
Filter Transmission	ft	%		
Blue			47.0	47.0
Green			58.0	58.0
Red			25.0	25.0
Exposure Times				
		sec	0.05	0.1
			0.1	0.5
			0.5	1.0
Frame Read Time	TREAD	sec	40.0	40.0
Frame Erase Time	TERASE	sec	0.5	0.5

3. Trajectory Data

The encounter data were obtained from a 1977 Jupiter-Saturn-Pluto mission. The Jupiter encounter time was specified such that multiple encounters would occur; the data are as follows:

PARAMETER	PLANET ENCOUNTER	
	JUPITER	SATURN
Calendar Date/Hr/Min/Sec	14 JAN 79/10/48/3.27	1 AUG 80/20/19/56.54
Julian Date	2443887.950038	2444453.347182
Periapse State		
(km), (X)	1.2706446432E+05	-1.4122713896E+05
(Y)	2.1321885366E+05	9.7650652979E+04
(Z)	-1.3387051602E+04	-4.2083846991E+05
(Earth Ecliptic Ref).		
(km/sec), (X)	-2.9431552532E+01	-2.0131197330E+01
(Y)	1.7610963316E+01	-6.1481658560E+00
(Z)	1.1418359371E+00	5.3291218577E+00

4. Case 4

a. Input Data - The ability of the program to switch from planet to satellite and back to planet is demonstrated. (See Table A-10 for input listing.)

Table A-10 Case 4 Input Listing

## JUPITER CHECK OUT CASE 4

```

2      5.0000000    PLANET
3      2.0000000    SATEL  EUROPA (J-II)
4      790114.69   DATE   JD AT ENCOUNTER
6      15.0000000
7      127064.46   STATE1
8      213218.85   STATE2    PERIAPSIS VECTOR FROM LEADBETTERS
9      -13387.052  STATE3    79 JSP RUN TO MAXIMIZE SATELLITE
10     -29.431552  STATE4    ENCOUNTER
11     17.610963  STATE5
12     1.1418359  STATE6
22     110.000000  INSTIO
61     -1.5000000  TSTAR TIME FROM PERIAPSIS
62     1.5000000  TSTOP TIME FROM PERIAPSIS
63     5.0000000  DTINSTPICTURE TAKING INTERVAL (MIN)
69     6.0000000  CALCSTPICTURES PER CALC STEP      30 MIN PER CALC STEP
81     3.0000000  DPLOT
82     3.0000000  DPRNT
86     100000.00E+01SATRNG
90     1111111.0
98

```

b. Output Data - The objective in case 4 was to show the geometry and analysis capability associated with switching from planet to satellite and return. The tabular output (Table A-11) gives several frames of Europa before, at, and after closest approach. Frames are also given to indicate a completely dark disk (occultation) of Europa, and the next printout frame switches back to Jupiter and its associated field of view compared with Europa.

The graphic output (Fig. A-6) shows the overall view of encounter. Figure A-7 presents geometry frames of Europa and Jupiter, as discussed in Table A-11. Figure A-8 presents resolution and smear summaries that show the effect of switching from Jupiter to Europa and back to Jupiter.

Table A-11 Case 4 Tabular Output

JUPITER CHECK OUT CASE 4

PICTURE NUMBER 415

0 DAYS 1 HRS 30 MIN TO ENCOUNTER

JD 2443888.129

## PLANET JUPITER

RANGE (KM) = 2.84442318E+05  
 CONE (DEG) = 104.55  
 CLOCK (DEG) = 261.50  
 PHASE (DEG) = 77.52  
 DIAM (DEG) = 29.06

## SATELLITE EUROP

RANGE (KM) = 9.00197697E+05  
 CONE (DEG) = 133.44  
 CLOCK (DEG) = 263.65  
 PHASE (DEG) = 48.63  
 DIAM (DEG) = .19

## RESOLUTION OF PLANET

CENTER = 8.29 KM/PIXEL  
 LIMB = 8.97 KM/PIXEL  
 INSTRUMENT DATA FOR SATELLITE EUROP

RESOLUTION AT SPECIFIED LOCATION = 3.99 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 33.89 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 138.63 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .02 KM  
 NUMBER OF PIXELS SMEARED .00192 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 26.050 MILLISEC

## EFFECTIVE RESOLUTION WITH SMEAR

AT SPECIFIED LOCATION 9.0 KM/PIXEL  
 AT SUBSPACECRAFT POINT 8.3 KM/PIXEL  
 AT LIMB OF TARGET BODY 9.0 KM/PIXEL

EXPOSURE TIME FOR SIT NARROW ANGLE CAMERA (CAND) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.7421E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.7421E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 87.055  
 DIGITAL NUMBER OF EXPOS = 222 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN	RESOLUTION LEVELS					KM/PIXEL
	300.0	100.0	50.0	10.0		
PLANET	415.0	415.0	415.0	139.0		
SATELLITE 1	415.0000	415.0000	415.0000	163.0000		
SATELLITE 2	415.0000	415.0000	415.0000	13.0000		
SATELLITE 3	415.0000	415.0000	415.0000	0.		
SATELLITE 4	415.0000	415.0000	415.0000	0.		

## SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	1.54475603E+05	133.50	44.53	99.63
2	9.00197697E+05	48.63	133.44	263.65
3	1.25077004E+06	32.07	150.00	263.49
4	2.09581488E+06	34.73	147.34	264.70

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	1.33498385E+02	1.23884696E+00
2	4.86296758E+01	1.85852230E-01
3	3.20692822E+01	2.33623022E-01
4	3.47332730E+01	1.29036271E-01

## RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	1.52805603E+00	1.54466576E+00
2	8.98737697E+00	9.00196513E+00
3	1.24822004E+01	1.25076744E+01
4	2.09345488E+01	2.09581355E+01

## SMEAR DATA FOR SATELLITES

SMEAR DUE TO VEL (KM/SEC)	SMEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
4.32332668E+00	3.12179724E+01	1.85585280E-03	2.69417919E-02
3.38863834E+01	1.38626344E+02	1.91946592E-03	2.60489125E-02
2.29996789E+01	2.16450517E+02	1.90146472E-03	2.62955181E-02
2.19048678E+01	3.57582797E+02	1.80585517E-03	2.76877132E-02

VIEW FROM SPACECRAFT

Table A-11 (cont)

JUPITER CHECK OUT CASE 4

PICTURE NUMBER 433 0 DAYS 0 HRS 0 MIN TO ENCOUNTER JD 2443888.192

PLANET JUPITE	SATELLITE EUROP
RANGE (KM) = 2.48569649E+J5	RANGE (KM) = 7.74638729E+05
CONE (DEG) = 65.59	CONE (DEG) = 121.02
CLOCK (DEG) = 261.38	CLOCK (DEG) = 264.11
PHASE (DEG) = 116.47	PHASE (DEG) = 61.04
DIAM (DEG) = 33.37	DIAM (DEG) = .22

RESOLUTION OF PLANET  
 CENTER = 7.03 KM/PIXEL  
 LIMB = 7.71 KM/PIXEL  
 INSTRUMENT DATA FOR SATELLITE EUROP

RESOLUTION AT SPECIFIED LOCATION = 7.73 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 32.65 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 126.64 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .02 KM  
 NUMBER OF PIXELS SMEARED .00204 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 24.519 MILLISEC

EFFECTIVE RESOLUTION WITH SMEAR  
 AT SPECIFIED LOCATION 7.7 KM/PIXEL  
 AT SUBSPACECRAFT POINT 7.0 KM/PIXEL  
 AT LIMB OF TARGET BODY 7.7 KM/PIXEL

EXPOSURE TIME FOR SIT NARROW ANGLE CAMERA (CANU) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.8958E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.8958E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 94.769  
 DIGITAL NUMBER OF EXPOS = 242 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-05 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN RESOLUTION LEVELS	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	433.0	433.0	433.0	157.0	
SATELLITE 1	433.0000	433.0000	433.0000	181.0000	
SATELLITE 2	433.0000	433.0000	433.0000	31.0000	
SATELLITE 3	433.0000	433.0000	433.0000	0.	
SATELLITE 4	433.0000	433.0000	433.0000	0.	

SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	2.70681833E+05	134.37	43.60	93.23
2	7.74638729E+05	61.64	121.02	264.11
3	1.08974550E+05	37.47	144.59	263.90
4	1.92926939E+06	37.61	144.44	264.90

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	1.34373429E+02	7.06989145E-01
2	6.10436294E+01	2.15975518E-01
3	3.74869818E+01	2.68144023E-01
4	3.76148093E+01	1.40175376E-01

RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	2.69011833E+00	2.70676681E+00
2	7.73178729E+00	7.74637354E+00
3	1.08719550E+01	1.08974251E+01
4	1.92690399E+01	1.92926855E+01

SMEAR DATA FOR SATELLITES

SMEAR DUE TO VEL (KM/SEC)	SMEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
4.29772783E+00	4.37669602E+01	1.96567815E-03	2.54365142E-02
3.26490986E+01	1.26642547E+02	2.03952547E-03	2.4515065E-02
1.71740645E+01	1.79163869E+02	1.80012426E-03	2.77753604E-02
1.48031350E+01	3.21471898E+02	1.74313508E-03	2.86839503E-02



Table A-11 (cont)

JUPITER CHECK OUT CASE 4

PICTURE NUMBER 451 0 DAYS 1 HRS 29 MIN TO ENCOUNTER JD 2443888.254

PLANET JUPITE	SATELLITE EUROP
RANGE (KM) = 2.84442918E+05	RANGE (KM) = 6.49097659E+05
CONE (DEG) = 26.63	CONE (DEG) = 107.55
CLOCK (DEG) = 261.14	CLOCK (DEG) = 264.79
PHASE (DEG) = 155.43	PHASE (DEG) = 74.50
DIAM (DEG) = 29.06	DIAM (DEG) = .26

RESOLUTION OF PLANET  
 CENTER = 5.78 KM/PIXEL  
 LIMB = 6.45 KM/PIXEL  
 INSTRUMENT DATA FOR SATELLITE EUROP

RESOLUTION AT SPECIFIED LOCATION = 6.48 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 29.38 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 124.48 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .01 KM  
 NUMBER OF PIXELS SMEARED .00230 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 21.776 MILLISEC

EFFECTIVE RESOLUTION WITH SMEAR  
 AT SPECIFIED LOCATION 6.5 KM/PIXEL  
 AT SUBSPACECRAFT POINT 5.3 KM/PIXEL  
 AT LIMB OF TARGET BODY 6.5 KM/PIXEL

EXPOSURE TIME FOR SIT NARROW ANGLE CAMERA (CAND) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.7956E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.7956E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 89.740  
 DIGITAL NUMBER OF EXPOS = 229 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN RESOLUTION LEVELS	RESOLUTION LEVELS				KH/PIXEL
	300.0	100.0	50.0	10.0	
PLANET	451.0	451.0	451.0	175.0	
SATELLITE 1	451.0000	451.0000	451.0000	199.0000	
SATELLITE 2	451.0000	451.0000	451.0000	49.0000	
SATELLITE 3	451.0000	451.0000	451.0000	7.0000	
SATELLITE 4	451.0000	451.0000	451.0000	0.	

## SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	3.89778905E+05	128.76	49.20	89.34
2	6.49097659E+05	74.50	107.55	264.79
3	9.23034406E+05	41.49	140.57	264.55
4	1.75460228E+06	39.31	142.74	265.28

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	1.28755630E+02	4.90966768E-01
2	7.45017513E+01	2.57746299E-01
3	4.14895022E+01	3.16574166E-01
4	3.93095393E+01	1.54129608E-01

## RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	3.88108905E+00	3.89775327E+00
2	6.47637659E+00	6.49096017E+00
3	9.20484467E+00	9.23030884E+00
4	1.75224228E+01	1.75460069E+01

## SMEAR DATA FOR SATELLITES

SMEAR DUE TO VEL (KM/SEC)	SMEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
8.94909572E+00	6.74534833E+01	1.96416674E-03	2.54560872E-02
2.93837799E+01	1.24478042E+02	2.2971177E-03	2.17674113E-02
9.71221427E+00	1.48635430E+02	1.72000164E-03	2.90697397E-02
6.20061016E+00	2.90182266E+02	1.69144587E-03	2.95605084E-02

Table A-11 (cont)

JUPITER CHECK OUT CASE 4

PICTURE NUMBER 613

0 DAYS 14 HRS 59 MIN TO ENCOUNTER

JD 2443889.317

PLANET JUPITER	SATELLITE EUROP
RANGE (KM) = 1.17972717E+06	RANGE (KM) = 3.97074490E+05
CONE (DEG) = 47.46	CONE (DEG) = 13.33
CLOCK (DEG) = 81.68	CLOCK (DEG) = 66.52
PHASE (DEG) = 136.52	PHASE (DEG) = 164.71
DIAM (DEG) = 6.94	DIAM (DEG) = .17

RESOLUTION OF PLANET  
 CENTER = 9.26 KM/PIXEL  
 LIMB = 9.95 KM/PIXEL  
 INSTRUMENT DATA FOR SATELLITE EUROP

RESOLUTION AT SPECIFIED LOCATION = 3.98 KM/PIXEL  
 SHEAR DUE TO RELATIVE VELOCITIES 16.53 KM/SEC  
 SHEAR DUE TO S/C ATTITUDE RATES 203.73 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .02 KM  
 NUMBER OF PIXELS SMEARED .00216 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SHEAR 23.117 MILLISEC

EFFECTIVE RESOLUTION WITH SHEAR  
 AT SPECIFIED LOCATION 10.0 KM/PIXEL  
 AT SUBSPACECRAFT POINT 9.3 KM/PIXEL  
 AT LIMB OF TARGET BODY 10.0 KM/PIXEL

EXPOSURE TIME FOR SIT NARROW ANGLE CAMERA (CANJ) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.6514E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.6514E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 82.502  
 DIGITAL NUMBER OF EXPOS = 211 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-05 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	613.0	613.0	613.0	337.0	
SATELLITE 1	613.0000	613.0000	613.0000	361.0000	
SATELLITE 2	613.0000	613.0000	613.0000	211.0000	
SATELLITE 3	613.0000	613.0000	613.0000	169.0000	
SATELLITE 4	613.0000	613.0000	613.0000	49.0000	

SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	8.10471148E+05	118.38	59.59	80.64
2	3.97074490E+05	164.71	13.33	66.52
3	1.78837773E+05	156.33	23.35	359.34
4	7.38139742E+05	34.76	147.21	276.21

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	1.16378018E+02	2.36119496E-01
2	1.64706911E+02	1.67794621E-01
3	1.56301948E+02	1.63393578E+00
4	3.47617541E+01	3.66375802E-01

RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	8.08801148E+00	8.10469428E+00
2	9.95614490E+00	9.97073421E+00
3	1.76287773E+00	1.78813592E+00
4	7.35779742E+00	7.38135969E+00

SHEAR DATA FOR SATELLITES

SHEAR DUE TO VEL (KM/SEC)	SHEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SHEAR 1/2 PIXEL (SEC)
1.07718452E+01	1.22883396E+02	1.40179956E-03	3.56684375E-02
1.65340451E+01	2.33723163E+02	2.16902567E-03	2.30513249E-02
1.21483579E+01	3.53941617E+01	2.35328316E-03	1.95825302E-02
4.66945377E+00	1.44270280E+02	1.93131631E-03	2.58891592E-02

VIEW FROM SPACECRAFT

Table A-11 (concl)

JUPITER CHECK OUT CASE 4

PICTURE NUMBER 631 0 DAYS 16 HRS 29 MIN TO ENCOUNTER JD 2443888.379

PLANET JUPITE		SATELLITE EUROP
RANGE (KM) = 1.27576863E+06		RANGE (KM) = 1.13084785E+06
CONE (DEG) = 49.21		CONE (DEG) = 17.81
CLOCK (DEG) = 81.60		CLOCK (DEG) = 71.75
PHASE (DEG) = 128.77		PHASE (DEG) = 160.19
DIAM (DEG) = 6.41		DIAM (DEG) = .15

RESOLUTION OF PLANET  
 CENTER = 12.04 KM/PIXEL  
 LIMB = 12.74 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITE (PICTURE CENTERED AT 5.09 DEG LAT 280.29 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 12.45 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 2.41 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 183.30 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .02 KM  
 NUMBER OF PIXELS SMEARED .00145 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 34.406 MILLISEC

EFFECTIVE RESOLUTION WITH SMEAR  
 AT SPECIFIED LOCATION 12.5 KM/PIXEL  
 AT SUBSPACECRAFT POINT 12.1 KM/PIXEL  
 AT LIMB OF TARGET BODY 12.3 KM/PIXEL

EXPOSURE TIME FOR SIT NARROW ANGLE CAMERA (CAND) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 9.8751E+00 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 9.8751E-04 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 49.172  
 DIGITAL NUMBER OF EXPOS = 125 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN RESOLUTION LEVELS	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	631.0	631.0	631.0	337.0	
SATELLITE 1	631.0000	631.0000	631.0000	379.0000	
SATELLITE 2	631.0000	631.0000	631.0000	211.0000	
SATELLITE 3	631.0000	631.0000	631.0000	187.0000	
SATELLITE 4	631.0000	631.0000	631.0000	67.0000	

## SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	8.69015744E+05	122.52	55.45	80.02
2	1.13084785E+06	160.19	17.81	71.75
3	2.69154279E+05	155.86	22.68	36.27
4	6.50250387E+05	33.33	148.54	279.49

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	1.22522642E+02	2.20212376E-01
2	1.60189686E+02	1.47945387E-01
3	1.55856419E+02	1.08567045E+00
4	3.33887894E+01	4.15896212E-01

## RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	8.67345744E+00	8.69014140E+00
2	1.12938785E+01	1.13084691E+01
3	2.66604279E+00	2.69142199E+00
4	6.47890387E+00	6.50246104E+00

## SMEAR DATA FOR SATELLITES

SMEAR DUE TO VEL (KM/SEC)	SMEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
1.16323071E+01	1.25393992E+02	1.31881809E-03	3.79127344E-02
1.57660618E+01	2.16923602E+02	2.02981951E-03	2.46327320E-02
8.22446291E+00	4.36613153E+01	1.91532614E-03	2.61052146E-02
5.18908762E+00	1.32110254E+02	2.00393843E-03	2.49508663E-02

VIEW FROM SPACECRAFT

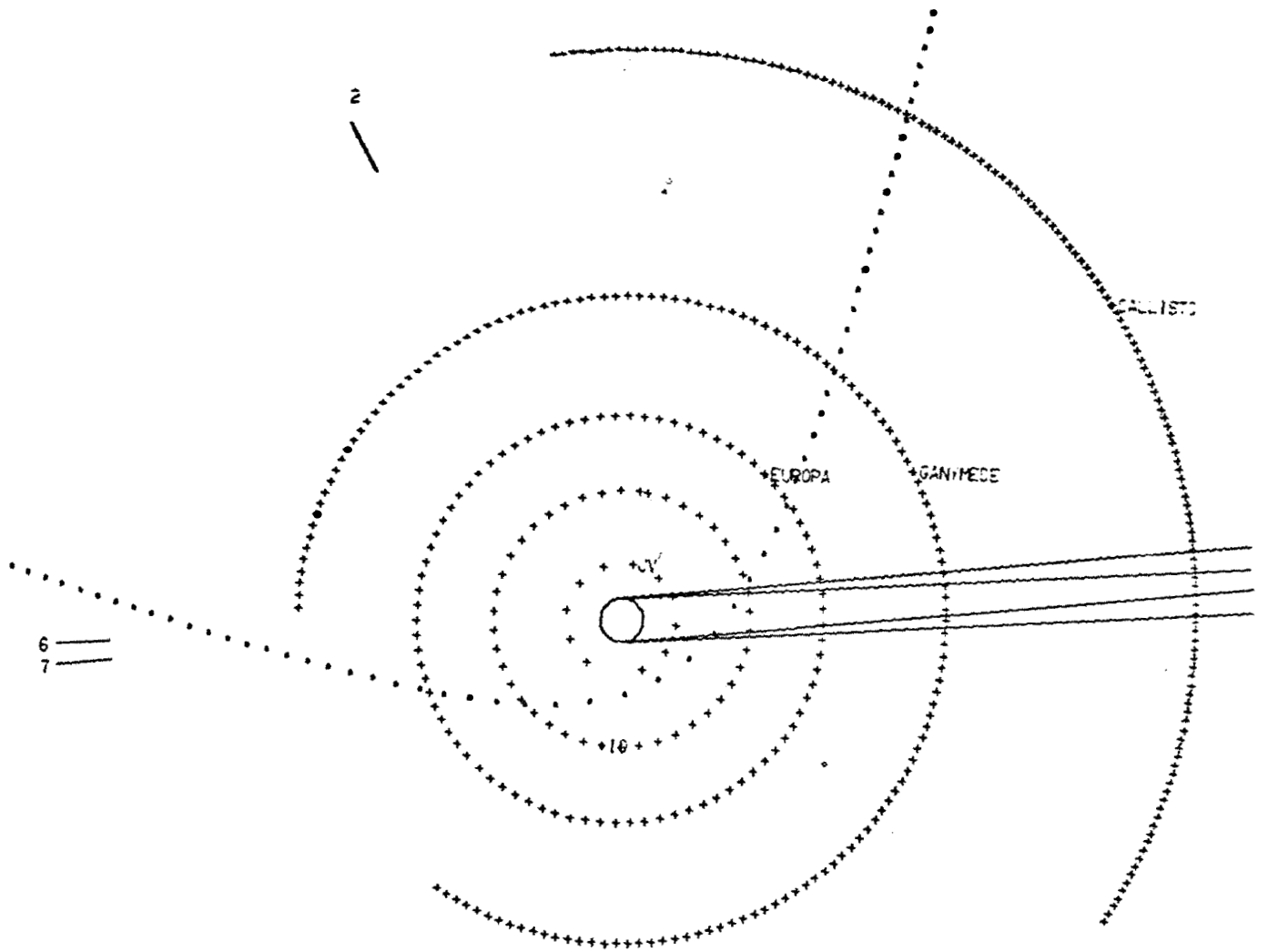
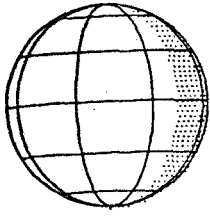


Fig. A-6 Overall View of Encounter

TIME BEFORE ENCOUNTER = 8 DAYS 1 HRS 38 MIN

PICTURE NUMBER 415

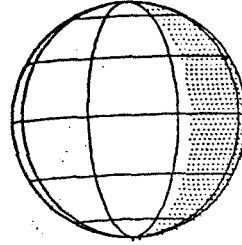


JUPITER R DEC K DLT CASE 4

EUROPA

TIME BEFORE ENCOUNTER = 8 DAYS 1 HRS 9 MIN

PICTURE NUMBER 433

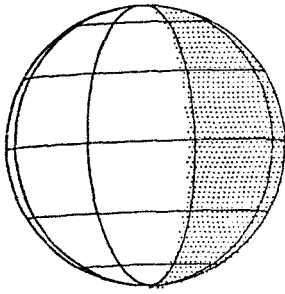


JUPITER R DEC K DLT CASE 4

EUROPA

TIME AFTER ENCOUNTER = 8 DAYS 1 HRS 29 MIN

PICTURE NUMBER 451

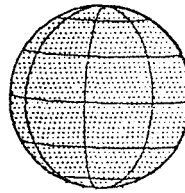


JUPITER R DEC K DLT CASE 4

EUROPA

TIME AFTER ENCOUNTER = 8 DAYS 14 HRS 59 MIN

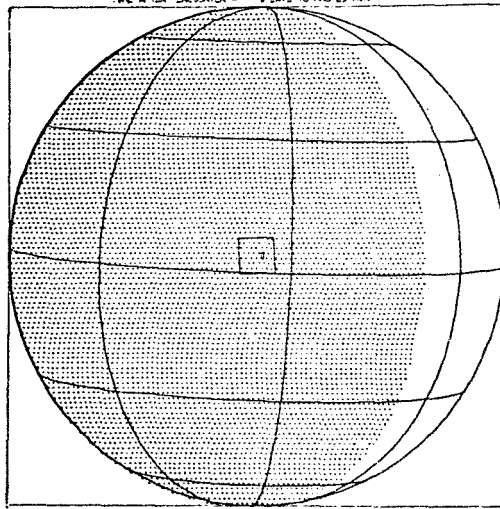
PICTURE NUMBER 613



JUPITER R DEC K DLT CASE 4

TIME AFTER ENCOUNTER = 8 DAYS 16 HRS 29 MIN

PICTURE NUMBER 631



JUPITER R DEC K DLT CASE 4

JUPITER

Fig. A-7 Geometry Frames - Europa and Jupiter

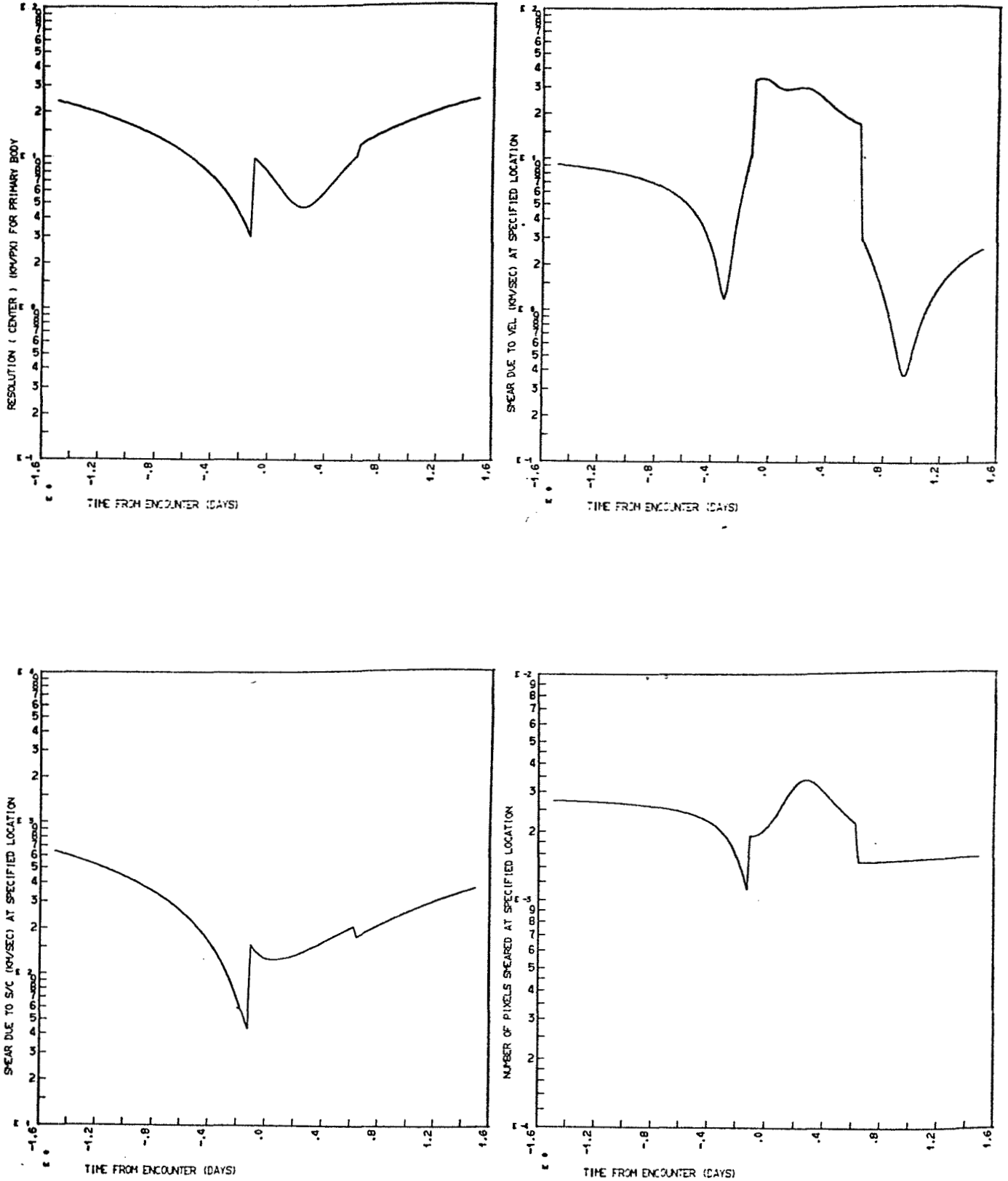


Fig. A-8 TV Summaries

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5. Case 5

- a. Input Data - The TOPS, SIT narrow-angle camera is demonstrated in this case. See Table A-12 for input listing.

Table A-12 Case 5 Input Listing

## JUPITER CHECK OUT CASE 5

2	5.0000000	PLANET	
3	0.	SATEL	
4	790114.69	DATE	JD AT ENCOUNTER
6	15.000000		
7	127064.46	STATE1	
8	213218.85	STATE2	PERIAPSIS VECTOR FROM LEADBETTERS
9	-13387.052	STATE3	79 JSP RUN TO MAXIMIZE SATELLITE
10	-29.431552	STATE4	ENCOUNTER
11	17.610963	STATE5	
12	1.1418359	STATE6	
22	110.00000	INSTID	
61	-1.5000000	TSTAR TIME FROM PERIAPSIS	
62	1.5000000	TSTOP TIME FROM PERIAPSIS	
63	5.0000000	DTINSTPICTURE TAKING INTERVAL (MIN)	
69	6.0000000	CALCSTPICTURES PER CALC STEP	30 MIN PER CALC STEP
81	3.0000000	DPLOT	
82	3.0000000	OPRNT	
86	100000.00E+01	SATRNG	
90	1111111.0		
98			

- b. Output Data - Output for the narrow-angle camera consists of the same frame timing for geometry as was used for case 1, with the wide-angle camera for comparison. Tabular output of the selected frames is given in Table A-13.

The graphic output (Fig. A-9 through A-11) shows the frames mentioned above for the narrow-angle camera, and provides a complete set of analysis frames to check the variety of summary data available for the imaging system.

## JUPITER CHECK OUT CASE 5

Table A-13 Case 5 Tabular Output

PICTURE NUMBER 1 -1 DAYS 12 HRS 0 MIN TO ENCOUNTER JD 2443886.692

PLANET JUPITE	SATELLITE JUPITE
RANGE (KM) = 2.44010854E+06	RANGE (KM) = 2.40077098E+06
CONE (DEG) = 168.45	CONE (DEG) = 152.48
CLOCK (DEG) = 80.73	CLOCK (DEG) = 93.76
PHASE (DEG) = 9.11	PHASE (DEG) = 0.
DIAM (DEG) = 3.35	DIAM (DEG) = 0.

RESOLUTION OF PLANET  
 CENTER = 23.69 KM/PIXEL  
 LIMB = 24.39 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITE (PICTURE CENTERED AT 1.74 DEG LAT 97.42 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 23.69 KM/PIXEL  
 SHEAR DUE TO RELATIVE VELOCITIES 9.18 KM/SEC  
 SHEAR DUE TO S/C ATTITUDE RATES 645.93 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .87 KM  
 NUMBER OF PIXELS SHEARED .00275 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SHEAR 18.181 MILLISEC

EFFECTIVE RESOLUTION WITH SHEAR  
 AT SPECIFIED LOCATION 23.8 KM/PIXEL  
 AT SUBSPACECRAFT POINT 23.8 KM/PIXEL  
 AT LIMB OF TARGET BODY 24.5 KM/PIXEL

EXPOSURE TIME FOR SIT NARROW ANGLE CAMERA (CAND) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.8748E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.7012E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 85.000  
 DIGITAL NUMBER OF EXPOS = 217 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN RESOLUTION LEVELS	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	1.0	1.0	1.0	0.	
SATELLITE 1	1.0000	1.0000	1.0000	0.	
SATELLITE 2	1.0000	1.0000	1.0000	0.	
SATELLITE 3	1.0000	1.0000	1.0000	0.	
SATELLITE 4	1.0000	1.0000	1.0000	0.	

## SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	2.78976597E+06	14.29	163.27	83.30
2	2.40077098E+06	25.08	152.48	83.76
3	3.31513930E+06	21.54	156.03	84.75
4	4.32575521E+06	5.95	171.61	83.64

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	1.42930608E+01	6.85964046E-02
2	2.50775989E+01	6.96874329E-02
3	2.15370295E+01	8.81436580E-02
4	5.95468279E+00	6.25176598E-02

RESOLUTION (KM/PIX) DATA FOR SATELLITES	RES AT SATELLITE LIMB
NUM RES ALONG RADIUS VECTOR	
1 2.78809597E+01	2.78976547E+01
2 2.39931098E+01	2.40077053E+01
3 3.31258930E+01	3.31513832E+01
4 4.32339522E+01	4.32575457E+01

SHEAR DATA FOR SATELLITES	SHEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SHEARED	TIME TO SHEAR 1/2 PIXEL (SEC)
SHEAR DUE TO VEL (KM/SEC)			
1.67361694E+01	7.84089228E+02	2.84626915E-03	1.75664559E-02
8.20284742E-01	7.09367738E+02	2.95019478E-03	1.69483335E-02
9.47094473E+00	9.64335622E+02	2.92595721E-03	1.70884249E-02
1.25685210E+01	1.14862876E+03	2.67398839E-03	1.86986601E-02

VIEW FROM SPACECRAFT  
 LAT 2 , LONG 137 NOT VISIBLE



Table A-13 (cont)

JUPITER CHECK OUT CASE 5

PICTURE NUMBER 487

8 DAYS 4 HRS 29 MIN TO ENCOUNTER

JD 2443888.379

PLANET JUPITE

RANGE (KM) = 4.67695251E+05  
 CONE (DEG) = 14.39  
 CLOCK (DEG) = 82.08  
 PHASE (DEG) = 163.55  
 DIAM (DEG) = 17.56

SATELLITE JUPITE

RANGE (KM) = 4.80329228E+05  
 CONE (DEG) = 75.19  
 CLOCK (DEG) = 267.08  
 PHASE (DEG) = 0.  
 DIAM (DEG) = 0.

RESOLUTION OF PLANET

CENTER = 3.96 KM/PIXEL  
 LIMB = 4.62 KM/PIXEL

INSTRUMENT DATA FOR PLANET JUPITE

(PICTURE CENTERED AT 4.84 DEG LAT 338.94 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 4.57 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 20.10 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 106.42 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .01 KM  
 NUMBER OF PIXELS SMEARED .00208 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 24.047 MILLISEC

EFFECTIVE RESOLUTION WITH SMEAR

AT SPECIFIED LOCATION 4.6 KM/PIXEL  
 AT SUBSPACECRAFT POINT 4.0 KM/PIXEL  
 AT LIMB OF TARGET BODY 4.6 KM/PIXEL

EXPOSURE TIME FOR SIT NARROW ANGLE CAMERA (CAND) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 3.6933E+00 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 3.6933E-04 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 18.139  
 DIGITAL NUMBER OF EXPOS = 46 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN  
 RESOLUTION LEVELS 300.0 100.0 50.0 10.0 KM/PIXEL

	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	487.0	487.0	487.0	211.0	
SATELLITE 1	487.0000	487.0000	487.0000	235.0000	
SATELLITE 2	487.0000	487.0000	487.0000	85.0000	
SATELLITE 3	487.0000	487.0000	487.0000	43.0000	
SATELLITE 4	487.0000	487.0000	487.0000	0.	

SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	5.67248438E+05	116.63	61.32	85.96
2	4.80329228E+05	106.86	75.19	267.08
3	6.39428596E+05	46.30	135.75	266.73
4	1.45924482E+06	39.90	142.15	266.45

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	1.16628695E+02	3.37362198E-01
2	1.06857516E+02	3.48310958E-01
3	4.63088073E+01	4.56984958E-01
4	3.98987635E+01	1.85326131E-01

RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	5.65578439E+00	5.67245980E+00
2	4.78869228E+00	4.80327010E+00
3	6.36878596E+00	6.39423511E+00
4	1.45688482E+01	1.45924291E+01

SHEAR DATA FOR SATELLITES

SHEAR DUE TO VEL (KM/SEC)	SHEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
8.80260494E+00	9.84695527E+01	1.89429988E-03	2.63949761E-02
2.91506135E+01	1.30456644E+02	3.09742457E-03	1.61424431E-02
4.88299590E+00	1.05093345E+02	1.72168136E-03	2.90413784E-02
2.15891863E+00	2.44780461E+02	1.67791356E-03	2.97989110E-02

VIEW FROM SPACECRAFT

JUPITER CHECK OUT CASE 5

Table A-13 (concl)

PICTURE NUMBER 361

0 DAYS 6 HRS 0 MIN TO ENCOUNTER

JO 2443337.942

## PLANET JUPITE

RANGE (KM) = 5.72306385E+05  
 CONE (DEG) = 155.47  
 CLOCK (DEG) = 261.79  
 PHASE (DEG) = 26.65  
 DIAM (DEG) = 14.33

## SATELLITE JUPITE

RANGE (KM) = 1.53315945E+05  
 CONE (DEG) = 158.96  
 CLOCK (DEG) = 248.68  
 PHASE (DEG) = 0.  
 DIAM (DEG) = 0.

## RESOLUTION OF PLANET

CENTER = 5.01 KM/PIXEL  
 LIMB = 5.68 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITE

(PICTURE CENTERED AT -1.62 DEG LAT 115.74 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 5.01 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 2.58 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 91.46 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .01 KM  
 NUMBER OF PIXELS SMEARED .00180 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 27.732 MILLISEC

## EFFECTIVE RESOLUTION WITH SMEAR

AT SPECIFIED LOCATION 5.0 KM/PIXEL  
 AT SUBSPACECRAFT POINT 5.0 KM/PIXEL  
 AT LIMB OF TARGET BODY 5.7 KM/PIXEL

EXPOSURE TIME FOR SIT NARROW ANGLE CAMERA (CAND) = .100 MILLISEC

POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.7775E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.7775E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 88.830  
 DIGITAL NUMBER OF EXPOS = 227 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7912E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN

RESOLUTION LEVELS	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	361.0	361.0	361.0	85.0	
SATELLITE 1	361.0000	361.0000	361.0000	109.0000	
SATELLITE 2	361.0000	361.0000	361.0000	0.	
SATELLITE 3	361.0000	361.0000	361.0000	0.	
SATELLITE 4	361.0000	361.0000	361.0000	0.	

## SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	1.53315945E+05	23.10	158.96	248.68
2	1.23328999E+06	21.68	160.43	262.33
3	1.63058411E+06	16.93	165.18	262.46
4	2.46899823E+06	25.28	156.83	264.60

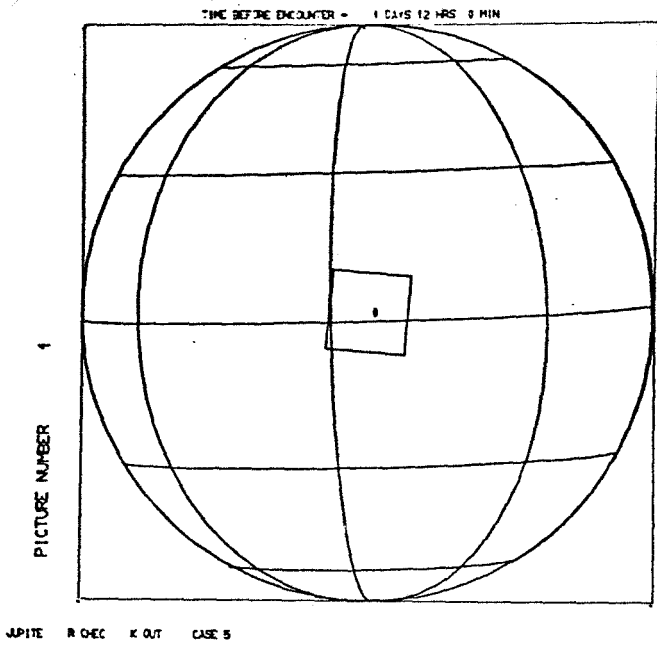
NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	2.30976149E+01	1.24821778E+00
2	2.16837591E+01	1.35656429E-01
3	1.69308482E+01	1.79204858E-01
4	2.52815548E+01	1.09532732E-01

## RESOLUTION (KM/PIX) DATA FOR SATELLITES

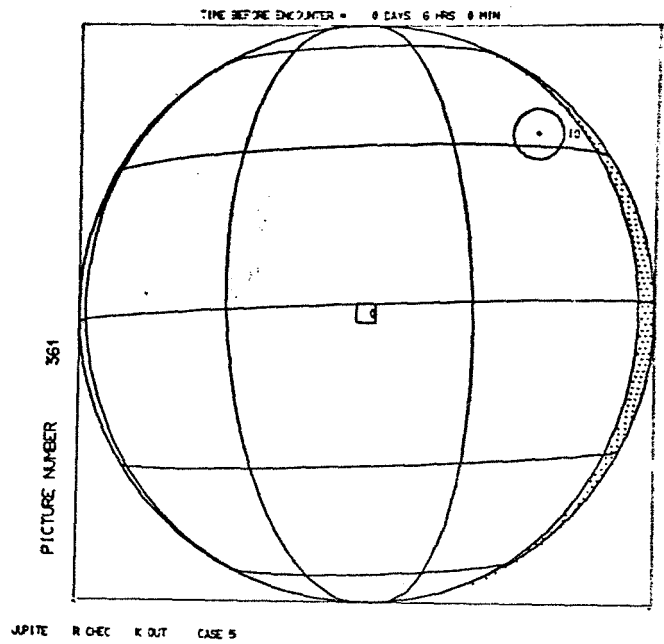
NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	1.51645945E+00	1.53306849E+00
2	1.23182999E+01	1.23328912E+01
3	1.62803411E+01	1.63058212E+01
4	2.46663823E+01	2.46899710E+01

## SMEAR DATA FOR SATELLITES

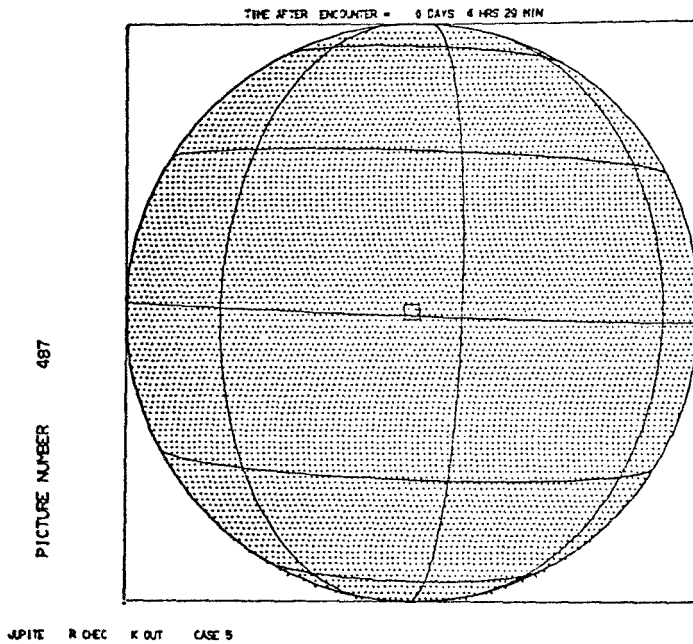
SMEAR DUE TO VEL (KM/SEC)	SMEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
4.85481854E+00	2.73420799E+01	1.48417413E-03	3.36887694E-02
2.69766284E+01	2.41557691E+02	2.13702820E-03	2.33969772E-02
2.22241117E+01	3.39973567E+02	2.19099601E-03	2.28206714E-02
2.26730036E+01	4.68356606E+02	1.97543990E-03	2.53108309E-02



JUPITER



JUPITER



JUPITER

Fig. A-9 Scenes Before and After Closest Approach

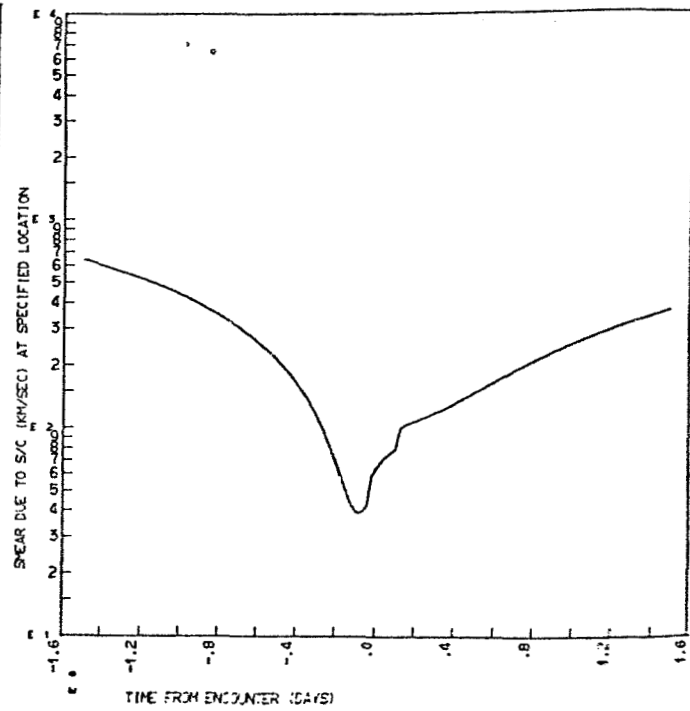
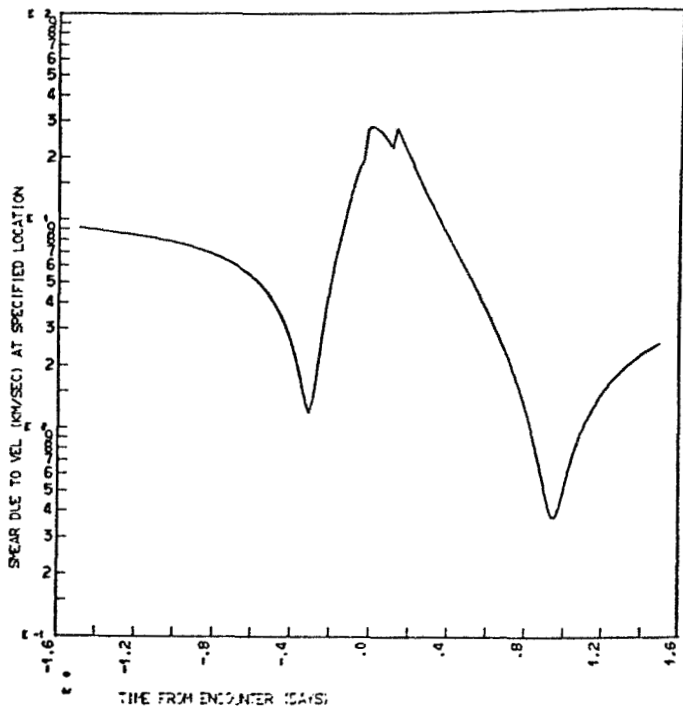
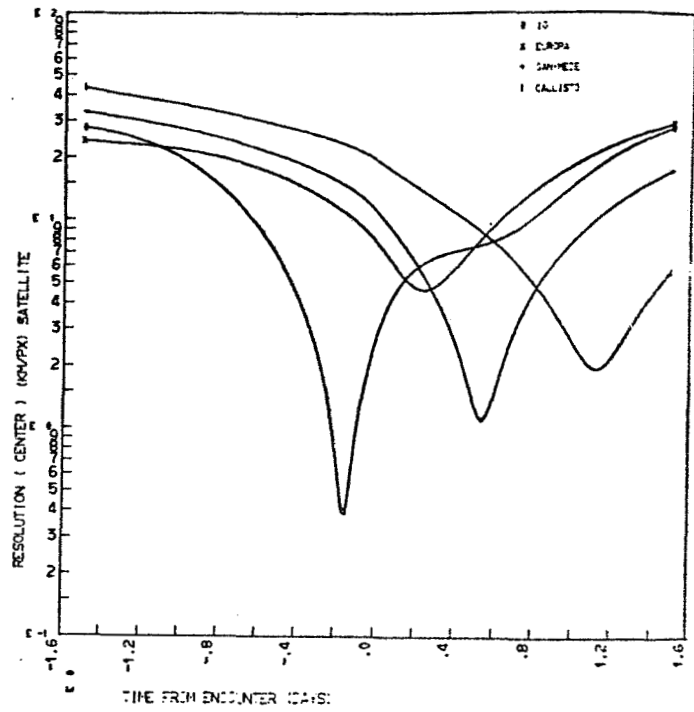
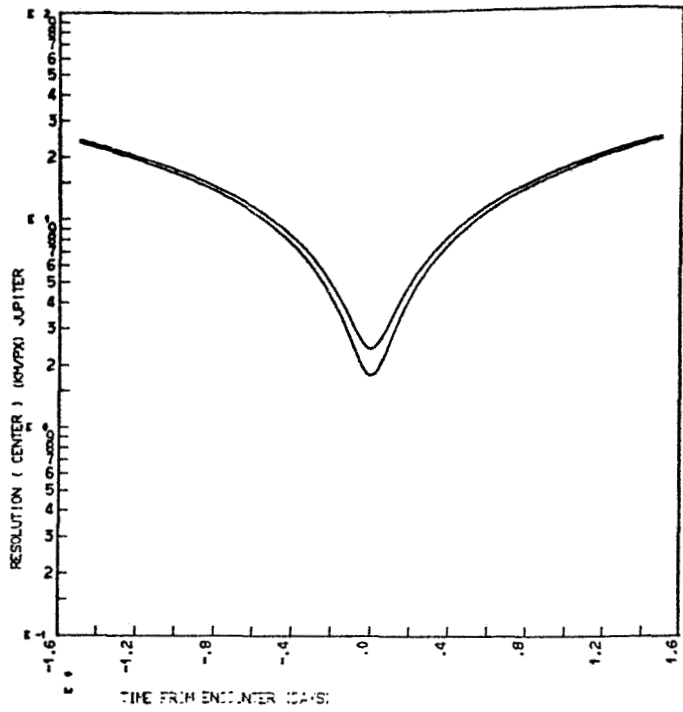


Fig. A-10 TV Summaries

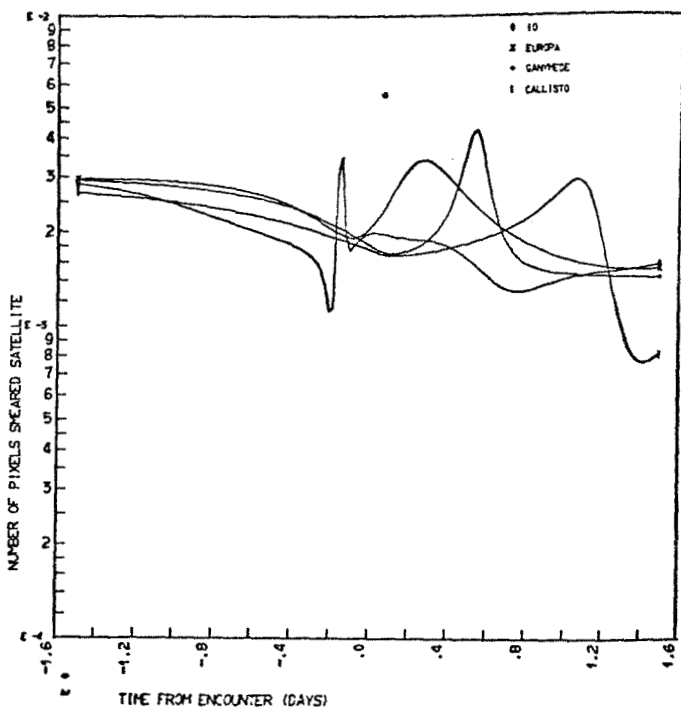
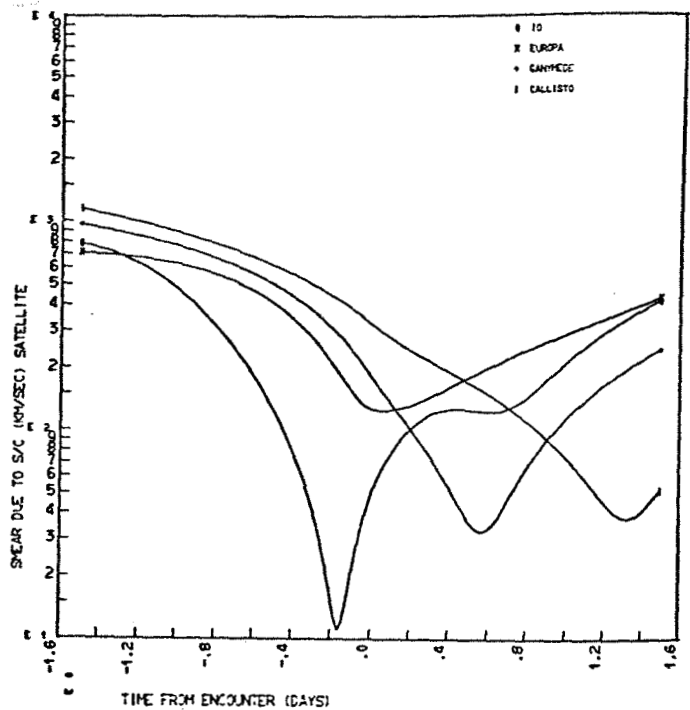
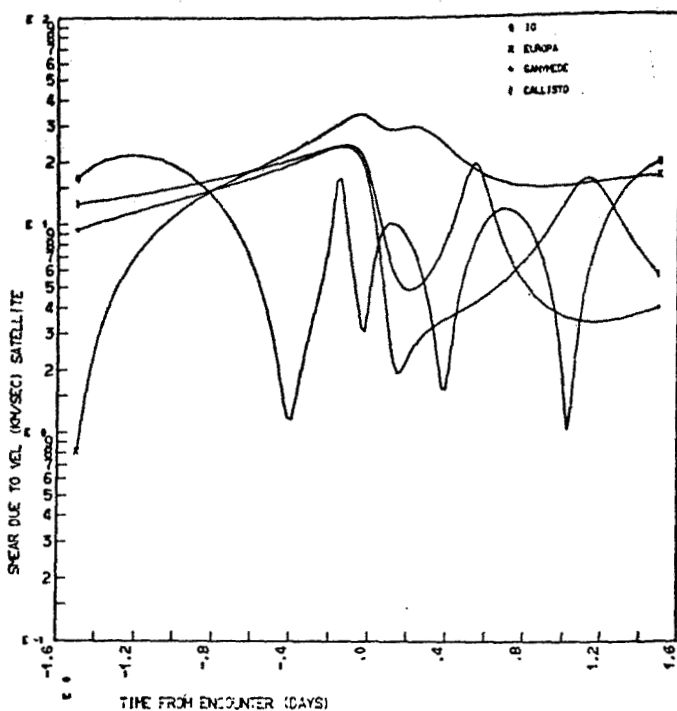
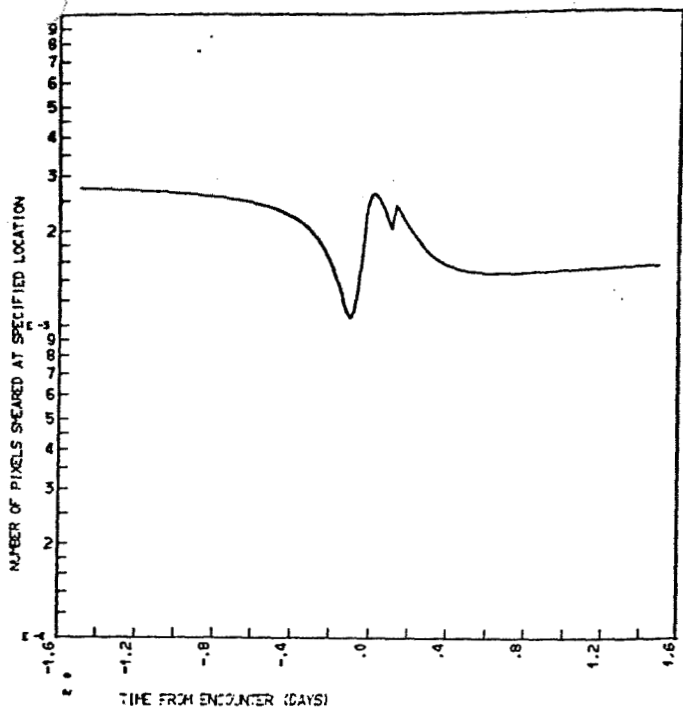


Fig. A-10 (cont)

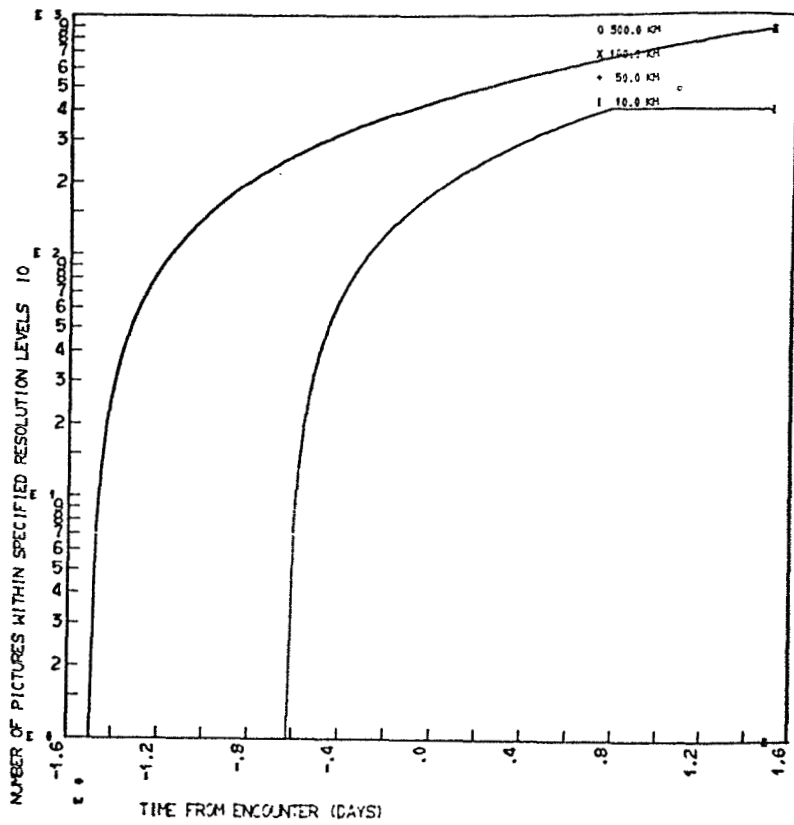
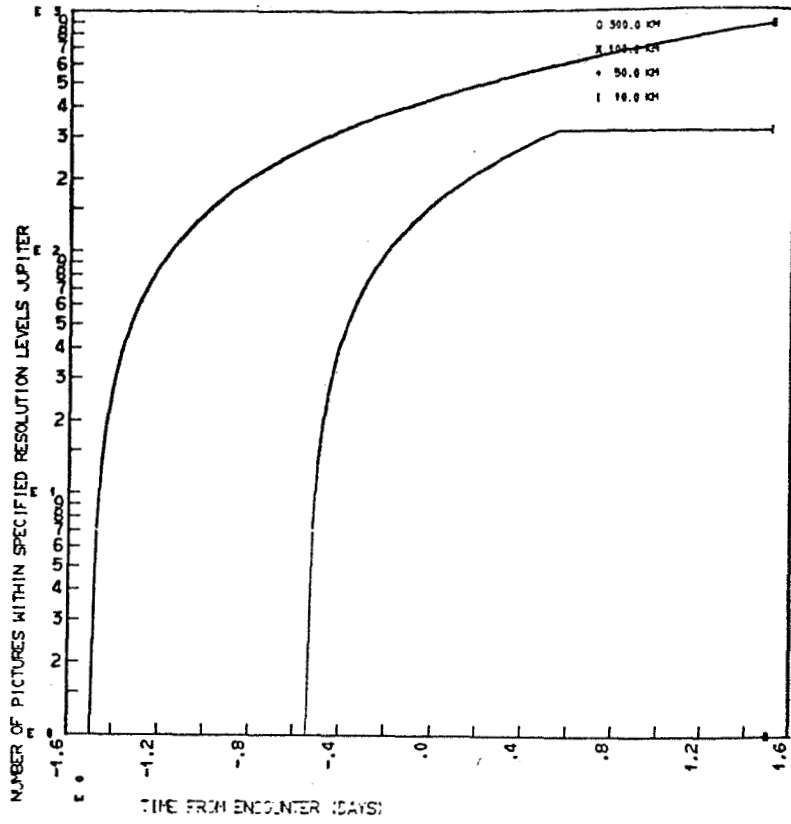


Fig. A-10 (concl)

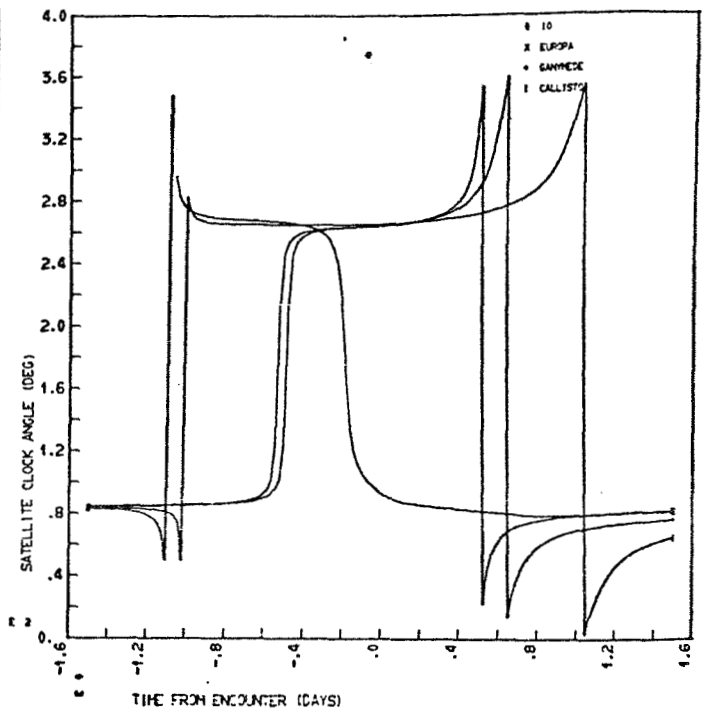
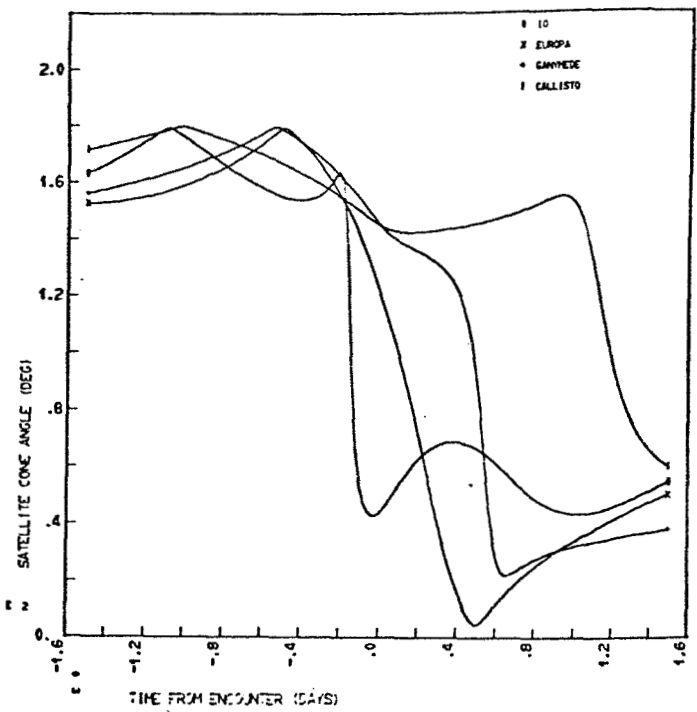
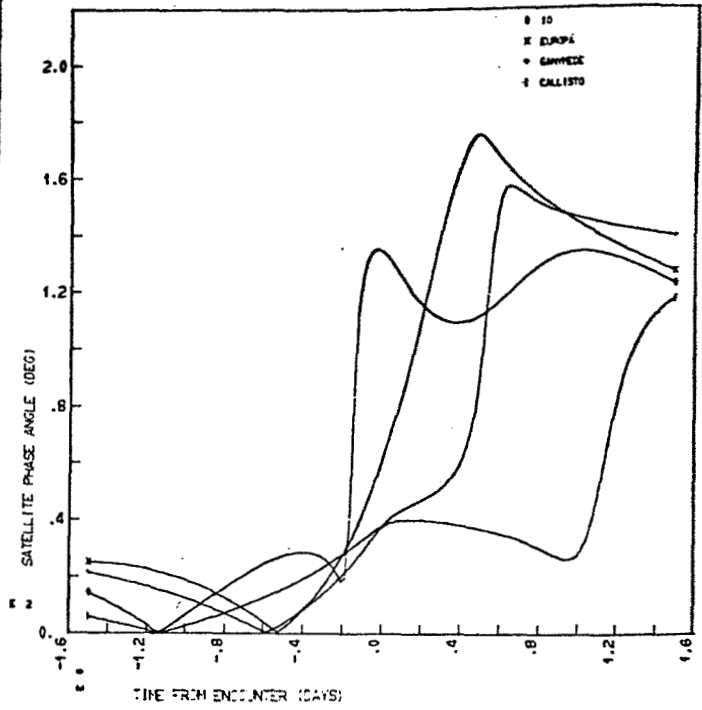
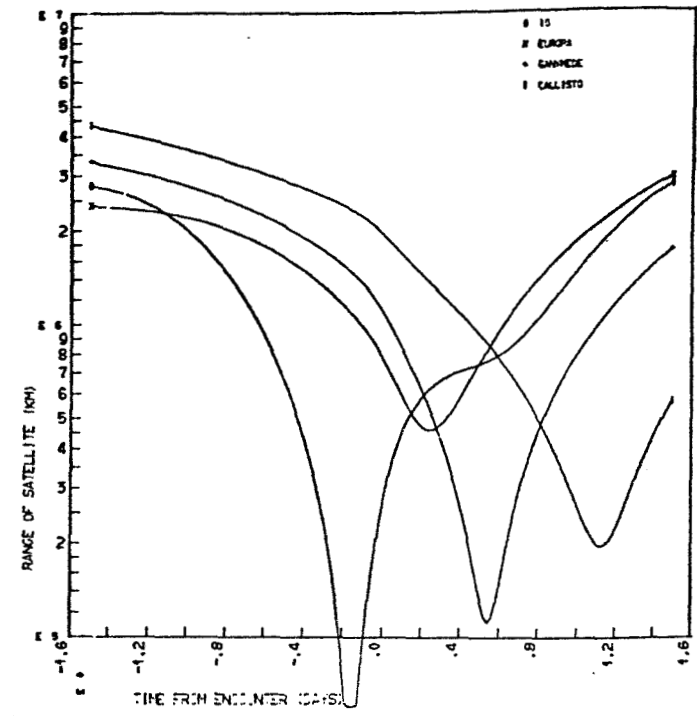


Fig. A-11 Satellite Geometry Summaries

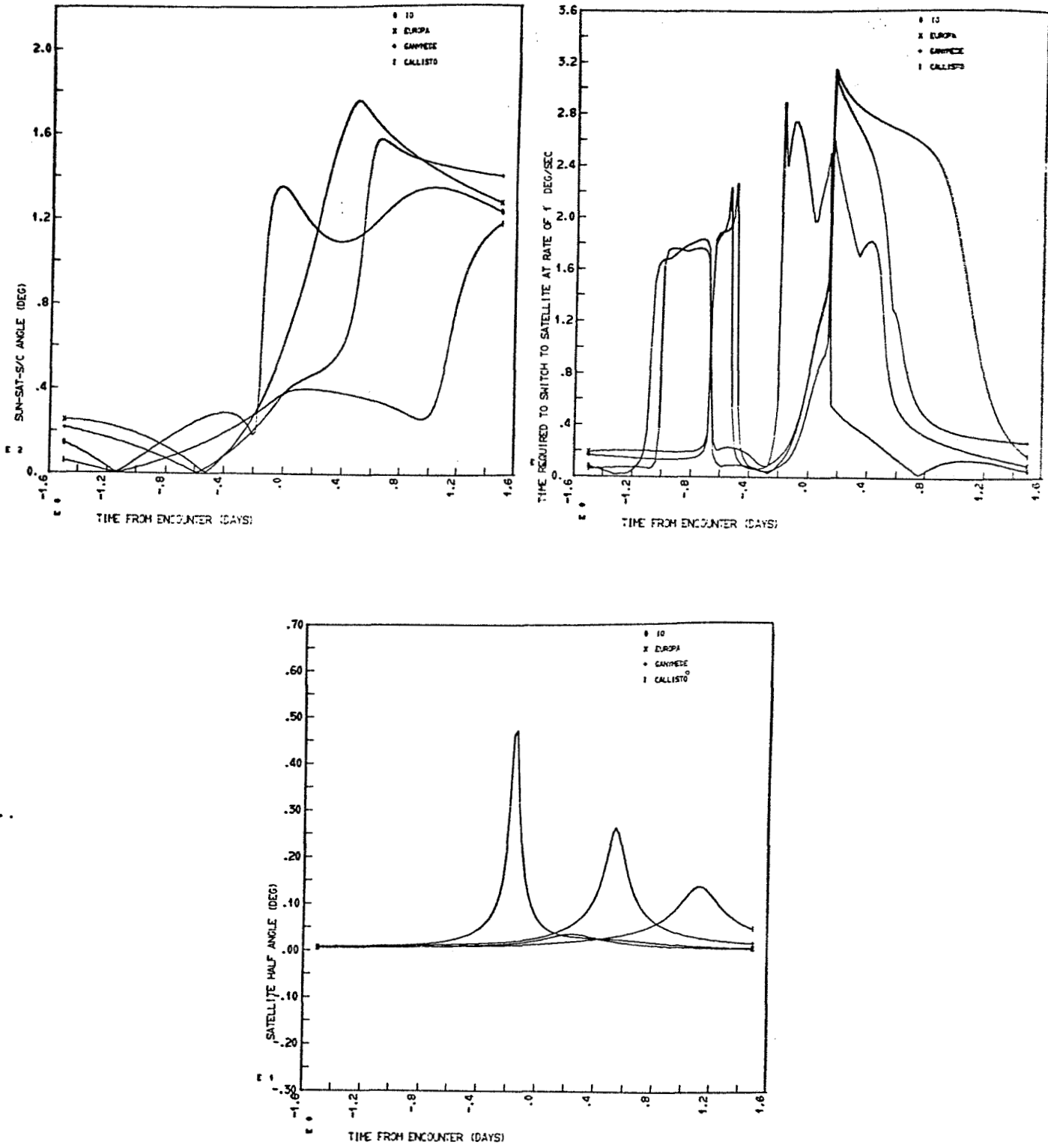


Fig. A-11 (concl)



6. Case 6

a. Input Data - The Saturn tabular input listing, for a wide-angle camera is shown in Table A-14. Table A-15 provides tabular listings of TV characteristics, planet and satellite albedos, and other values used in the imaging subroutine.

Table A-14 Case 6 Input Listing

## SATURN CHECK OUT CASE NO 6

2	6.0000000	PLANET
3	6.0000000	SATEL TITAN (VI)
4	800801.81	DATE
6	15.000000	
7	-141227.14	STATE1
8	97650.653	STATE2
9	-420838.47	STATE3
10	-20.131197	STATE4
11	-6.1481659	STATE5
12	5.3291219	STATE6
22	120.00000	INSTIDINSTRUMENT ID (TV, WIDE ANGLE SIT)
61	-1.5000000	TSTAR TIME FROM PERIAPSIS
62	1.5000000	TSTOP TIME FROM PERIAPSIS
63	5.0000000	DTINSTPICTURE TAKING INTERVAL (MIN)
69	6.0000000	CALCSTPICTURES PER CALC STEP 30 MIN PER CALC STEP
81	3.0000000	DPLOT
82	3.0000000	DPRNT
90	1111111.0	
98		

## SATURN CHECK OUT CASE NO 6

## XZ(I) VALUES IN STORAGE

1	0	0.	2	1	6.0000000000E+00
3	1	6.0000000000E+00	4	1	8.0080181250E+05
5	0	0.	6	1	1.5000000000E+01
7	1	-1.4122713896E+05	8	1	9.7650652972E+04
9	1	-4.2083846991E+05	10	1	-2.0131197330E+01
11	1	-6.1481658560E+00	12	1	5.3291218577E+00
13	0	0.	14	0	0.
15	0	3.0000000000E+00	16	0	0.
17	0	0.	18	0	0.
19	0	0.	20	0	0.
21	0	0.	22	1	1.2000000000E+02
23	0	0.	24	0	-7.1738305547E+57
25	0	-7.1738305547E+57	26	0	0.
27	0	0.	28	0	0.
29	0	0.	30	0	0.
31	0	0.	32	0	0.
33	0	0.	34	0	0.
35	0	0.	36	0	0.
37	0	0.	38	0	0.
39	0	0.	40	0	0.
41	0	0.	42	0	0.
43	0	0.	44	0	0.
45	0	0.	46	0	0.
47	0	0.	48	0	0.
49	0	0.	50	0	0.
51	0	0.	52	0	0.
53	0	0.	54	0	0.
55	0	0.	56	0	0.
57	0	0.	58	0	0.
59	0	0.	60	0	0.
61	1	-1.5000000000E+00	62	1	1.5000000000E+00
63	1	5.0000000000E+00	64	0	0.
65	0	0.	66	0	0.
67	0	0.	68	0	0.
69	1	6.0000000000E+00	70	0	0.
71	0	0.	72	0	0.
73	0	0.	74	0	0.
75	0	0.	76	0	0.
77	0	0.	78	0	0.
79	0	0.	80	0	0.
81	1	3.0000000000E+00	82	1	3.0000000000E+00
83	0	0.	84	0	0.
85	0	0.	86	0	0.
87	0	0.	88	0	0.
89	0	0.	90	1	1.1111110000E+06
91	0	0.	92	0	0.
93	0	0.	94	0	0.
95	0	0.	96	0	0.

Table A-15 TV Characteristics, Albedos, and Imaging Values

## SATURN CHECK OUT CASE NO 6

## TV CHARACTERISTICS FOR SIT WIDE ANGLE CAMERA (CANO)

6	FOC LM=	2.0000000E+01	
7	DIAM =	5.0000000E+00	
8	OBSCUR=	0.	
9	TRANS =	8.5000000E-01	
10	SIZE-V=	1.6000000E+00	
11	SIZE-H=	1.6000000E+00	
12	LINES =	8.0000000E+02	
13	PIXELS=	8.0000000E+02	
14	BIT/PIX=	8.0000000E+03	
15	TIMEXP=	8.0000000E-06	
16	MAXEXP=	2.0000000E-03	
17	RESO-1=	3.0000000E+02	
18	RESO-2=	1.0000000E+02	
19	RESO-3=	5.0000000E+01	
20	RESO-4=	1.0000000E+01	
21	SENSOR=	1.0000000E+00	
22	B FILT=	1.0000000E+00	
23	G FILT=	1.0000000E+00	
24	R FILT=	1.0000000E+00	
25	P FILT=	-1.0000000E+00	
26	OT EXP=	1.0000000E-04	
27	OPEN =	1.0000000E-03	
28	OPEN =	1.0000000E-02	
29	T READ=	4.0000000E+01	
30	ERASET=	1.0000000E-01	
31	TSTART=	-1.5000000E+00	USER INPUT
32	TSTOP =	1.5000000E+00	USER INPUT
33	DEL T =	5.0000000E+00	USER INPUT
34	BULK =	1.0000000E+09	
35	BULK-0=	0.	
36	BITRAT=	4.7400000E+04	
37	SCI9PS=	1.0000000E+02	
38	BUFFER=	5.1200000E+06	
39	PIC/ST=	6.0000000E+00	USER INPUT
40	DEL TF=	5.0000000E+03	
41	F/STOP=	4.0000000E+00	COMPUTED VALUES
42	A BLOC=	0.	COMPUTED VALUES
43	DIF LM=	1.3420000E-05	COMPUTED VALUES
44	FOV-V =	4.58122395E+00	COMPUTED VALUES
45	FOV-H =	4.58122395E+00	COMPUTED VALUES
46	RES-C =	1.0000000E-04	COMPUTED VALUES
47	RES-V =	1.71058277E-06	COMPUTED VALUES
48	RES-H =	1.71058277E-06	COMPUTED VALUES
49	BIT/PC=	5.1200000E+09	COMPUTED VALUES
50	RR-BPS=	1.2800000E+05	COMPUTED VALUES
51	T/NUM=	4.33860916E+03	COMPUTED VALUES
52	T/NUMF=	4.33860916E+03	COMPUTED VALUES
53	OPEN =	0.	COMPUTED VALUES
54	OPEN =	0.	COMPUTED VALUES
55	OPEN =	0.	COMPUTED VALUES
56	OPEN =	0.	COMPUTED VALUES
57	OPEN =	0.	COMPUTED VALUES
58	OPEN =	0.	COMPUTED VALUES
59	OPEN =	0.	COMPUTED VALUES
60	OPEN =	0.	COMPUTED VALUES

## SATURN CHECK OUT CASE NO 6

## TV ENERGY DATA FOR SIT WIDE ANGLE CAMERA (CANO)

## PLANET 6 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO(N/SQCM)	BEFF(N/SQCM)
.2500	.0070	.3000	0	1.0000	5.460000E-05	0.
.2750	.0204	.2820	.0020	1.0000	1.495728E-04	2.991456E-07
.3000	.0514	.2700	.0950	1.0000	3.608280E-04	3.427366E-05
.3250	.0971	.2650	.4760	1.0000	6.690190E-04	3.184570E-04
.3500	.1093	.2690	.7620	1.0000	7.644442E-04	5.825065E-04
.3750	.1157	.2720	.9530	1.0000	8.132334E-04	7.797736E-04
.4000	.1429	.2850	.9440	1.0000	1.005839E-03	1.041947E-03
.4250	.1693	.3150	1.0000	1.0000	1.386567E-03	1.336567E-03
.4500	.2006	.3640	.9840	1.0000	1.898478E-03	1.868103E-03
.4750	.2344	.3850	.9530	1.0000	2.046044E-03	1.949880E-03
.5000	.1942	.4060	.7940	1.0000	2.049975E-03	1.627680E-03
.5250	.1852	.4300	.7620	1.0000	2.070536E-03	1.577443E-03
.5500	.1725	.4500	.6820	1.0000	2.018250E-03	1.376466E-03
.5750	.1719	.4600	.5550	1.0000	2.055924E-03	1.141039E-03
.6000	.1666	.4650	.4760	1.0000	2.014194E-03	9.579035E-04
.6250	.1586	.4690	.4450	1.0000	1.933768E-03	9.606159E-04
.6500	.1511	.4700	.3600	1.0000	1.846442E-03	6.647191E-04
.6750	.1442	.4690	.2540	1.0000	1.758375E-03	4.466272E-04
.7000	.1369	.4580	.2060	1.0000	1.630205E-03	3.358223E-04
.7250	.1302	.4400	.1590	1.0000	1.489488E-03	2.368286E-04
.7500	.1235	.4100	.0950	1.0000	1.316510E-03	1.250644E-04
.7750	.1171	.3880	.0400	1.0000	1.156948E-03	4.627792E-05
.8000	.1107	.3550	.0240	1.0000	1.021761E-03	2.452226E-05
.8250	.1048	.3300	.0100	1.0000	8.914400E-04	6.991340E-06
.8500	.0988	.3150	.0030	1.0000	8.091720E-04	2.427516E-06
.8750	.0939	.3000	.0220	1.0000	7.324200E-04	1.611324E-05
.9000	.0889	.2820	0	1.0000	6.518148E-04	0.
.9250	.0862	.2640	0	1.0000	5.916768E-04	0.
.9500	.0835	.2460	0	1.0000	5.340660E-04	0.
.9750	.0791	.2320	0	1.0000	4.771312E-04	0.
1.0000	.0746	.2220	0	1.0000	4.305912E-04	0.

Table A-15 (cont)

## SATURN CHECK OUT CASE NO 6

## TV ENERGY DATA FOR SIT WIDE ANGLE CAMERA (CAND)

## SATELLITE 1 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF (W/SQCM)
.2500	.0070	.0450	0	1.0000	3.150000E-05	0.
.2750	.0204	.0500	.0020	1.0000	1.020000E-04	2.040000E-07
.3000	.0514	.0550	.0950	1.0000	2.827000E-04	2.685550E-05
.3250	.0971	.0600	.4760	1.0000	5.826000E-04	2.773176E-04
.3500	.1093	.0650	.7620	1.0000	7.104500E-04	5.413529E-04
.3750	.1157	.0700	.9530	1.0000	8.099000E-04	7.713347E-04
.4000	.1429	.0750	.9840	1.0000	1.071750E-03	1.054602E-03
.4250	.1693	.0800	1.0000	1.0000	1.354400E-03	1.354400E-03
.4500	.2006	.0850	.9840	1.0000	1.705100E-03	1.677313E-03
.4750	.2044	.1000	.9530	1.0000	2.044000E-03	1.947932E-03
.5000	.1942	.1050	.7940	1.0000	2.039100E-03	1.619045E-03
.5250	.1852	.1130	.7620	1.0000	2.092760E-03	1.594683E-03
.5500	.1725	.1200	.6820	1.0000	2.070000E-03	1.411740E-03
.5750	.1719	.1250	.5550	1.0000	2.148750E-03	1.192556E-03
.6000	.1666	.1300	.4760	1.0000	2.165000E-03	1.031921E-03
.6250	.1586	.1350	.4450	1.0000	2.141100E-03	9.527395E-04
.6500	.1511	.1450	.3600	1.0000	2.190950E-03	7.887420E-04
.6750	.1442	.1550	.2540	1.0000	2.235100E-03	5.677154E-04
.7000	.1369	.1650	.2060	1.0000	2.258850E-03	4.853231E-04
.7250	.1302	.1700	.1590	1.0000	2.213400E-03	3.519306E-04
.7500	.1235	.1750	.0950	1.0000	2.161250E-03	2.053187E-04
.7750	.1171	.1800	.0400	1.0000	2.107800E-03	8.431200E-05
.8000	.1107	.1850	.0240	1.0000	2.047950E-03	4.915080E-05
.8250	.1048	.2900	.0100	1.0000	3.039200E-03	3.039200E-05
.8500	.0988	.2950	.0030	1.0000	2.914600E-03	8.743300E-06
.8750	.0939	.2000	.0220	1.0000	1.878000E-03	4.131500E-05
.9000	.0889	.2000	0	1.0000	1.778000E-03	0.
.9250	.0862	.2000	0	1.0000	1.724000E-03	0.
.9500	.0835	.2050	0	1.0000	1.711750E-03	0.
.9750	.0791	.2080	0	1.0000	1.645280E-03	0.
1.0000	.0746	.2100	0	1.0000	1.566600E-03	0.

## SATURN CHECK OUT CASE NO 6

## TV ENERGY DATA FOR SIT WIDE ANGLE CAMERA (CAND)

## SATELLITE 2 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF (W/SQCM)
.2500	.0070	.0450	0	1.0000	3.150000E-05	0.
.2750	.0204	.0500	.0020	1.0000	1.020000E-04	2.040000E-07
.3000	.0514	.0550	.0950	1.0000	2.827000E-04	2.685550E-05
.3250	.0971	.0600	.4760	1.0000	5.826000E-04	2.773176E-04
.3500	.1093	.0650	.7620	1.0000	7.104500E-04	5.413529E-04
.3750	.1157	.0700	.9530	1.0000	8.099000E-04	7.713347E-04
.4000	.1429	.0750	.9840	1.0000	1.071750E-03	1.054602E-03
.4250	.1693	.0800	1.0000	1.0000	1.354400E-03	1.354400E-03
.4500	.2006	.0850	.9840	1.0000	1.705100E-03	1.677313E-03
.4750	.2044	.1000	.9530	1.0000	2.044000E-03	1.947932E-03
.5000	.1942	.1050	.7940	1.0000	2.039100E-03	1.619045E-03
.5250	.1852	.1130	.7620	1.0000	2.092760E-03	1.594683E-03
.5500	.1725	.1200	.6820	1.0000	2.070000E-03	1.411740E-03
.5750	.1719	.1250	.5550	1.0000	2.148750E-03	1.192556E-03
.6000	.1666	.1300	.4760	1.0000	2.165000E-03	1.031921E-03
.6250	.1586	.1350	.4450	1.0000	2.141100E-03	9.527395E-04
.6500	.1511	.1450	.3600	1.0000	2.190950E-03	7.887420E-04
.6750	.1442	.1550	.2540	1.0000	2.235100E-03	5.677154E-04
.7000	.1369	.1650	.2060	1.0000	2.258850E-03	4.853231E-04
.7250	.1302	.1700	.1590	1.0000	2.213400E-03	3.519306E-04
.7500	.1235	.1750	.0950	1.0000	2.161250E-03	2.053187E-04
.7750	.1171	.1800	.0400	1.0000	2.107800E-03	8.431200E-05
.8000	.1107	.1850	.0240	1.0000	2.047950E-03	4.915080E-05
.8250	.1048	.2900	.0100	1.0000	3.039200E-03	3.039200E-05
.8500	.0988	.2950	.0030	1.0000	2.914600E-03	8.743300E-06
.8750	.0939	.2000	.0220	1.0000	1.878000E-03	4.131500E-05
.9000	.0889	.2000	0	1.0000	1.778000E-03	0.
.9250	.0862	.2000	0	1.0000	1.724000E-03	0.
.9500	.0835	.2050	0	1.0000	1.711750E-03	0.
.9750	.0791	.2080	0	1.0000	1.645280E-03	0.
1.0000	.0746	.2100	0	1.0000	1.566600E-03	0.

Table A-15 (cont)

## SATURN CHECK OUT CASE NO 6

## TV ENERGY DATA FOR SIT WIDE ANGLE CAMERA (CAND)

## SATELLITE 3 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF(W/SQCM)
.2500	.0070	.0450	0	1.0000	3.150000E-05	0.
.2750	.0204	.0500	.0020	1.0000	1.020000E-04	2.040000E-07
.3000	.0514	.0550	.0950	1.0000	2.827000E-04	2.685650E-05
.3250	.0971	.0600	.4760	1.0000	5.826000E-04	2.773176E-04
.3500	.1093	.0650	.7620	1.0000	7.104500E-04	5.413629E-04
.3750	.1157	.0700	.9530	1.0000	8.099000E-04	7.718347E-04
.4000	.1429	.0750	.9840	1.0000	1.071750E-03	1.054602E-03
.4250	.1693	.0800	1.0000	1.0000	1.354400E-03	1.354400E-03
.4500	.2006	.0850	.9840	1.0000	1.705100E-03	1.677818E-03
.4750	.2044	.1000	.9530	1.0000	2.044000E-03	1.947932E-03
.5000	.1942	.1050	.7940	1.0000	2.039100E-03	1.619045E-03
.5250	.1852	.1130	.7620	1.0000	2.092760E-03	1.594683E-03
.5500	.1725	.1200	.6820	1.0000	2.070000E-03	1.411740E-03
.5750	.1719	.1250	.5550	1.0000	2.148750E-03	1.192556E-03
.6000	.1666	.1300	.4760	1.0000	2.165800E-03	1.030921E-03
.6250	.1586	.1350	.4450	1.0000	2.141100E-03	9.527995E-04
.6500	.1511	.1450	.3600	1.0000	2.190950E-03	7.887420E-04
.6750	.1442	.1550	.2540	1.0000	2.235100E-03	5.677154E-04
.7000	.1369	.1650	.2060	1.0000	2.258950E-03	4.653231E-04
.7250	.1302	.1700	.1590	1.0000	2.213400E-03	3.519306E-04
.7500	.1235	.1750	.0950	1.0000	2.161250E-03	2.053187E-04
.7750	.1171	.1800	.0400	1.0000	2.107800E-03	8.431200E-05
.8000	.1107	.1850	.0240	1.0000	2.047950E-03	4.915080E-05
.8250	.1048	.2900	.0100	1.0000	3.039200E-03	3.039200E-05
.8500	.0988	.2950	.0030	1.0000	2.914600E-03	8.743800E-06
.8750	.0939	.2000	.0220	1.0000	1.878000E-03	4.131600E-05
.9000	.0889	.2000	0	1.0000	1.778000E-03	0.
.9250	.0862	.2000	0	1.0000	1.724000E-03	0.
.9500	.0835	.2050	0	1.0000	1.711750E-03	0.
.9750	.0791	.2080	0	1.0000	1.645280E-03	0.
1.0000	.0746	.2100	0	1.0000	1.566600E-03	0.

## SATURN CHECK OUT CASE NO 6

## TV ENERGY DATA FOR SIT WIDE ANGLE CAMERA (CAND)

## SATELLITE 4 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF(W/SQCM)
.2500	.0070	.0450	0	1.0000	3.150000E-05	0.
.2750	.0204	.0500	.0020	1.0000	1.020000E-04	2.040000E-07
.3000	.0514	.0550	.0950	1.0000	2.827000E-04	2.685650E-05
.3250	.0971	.0600	.4760	1.0000	5.826000E-04	2.773176E-04
.3500	.1093	.0650	.7620	1.0000	7.104500E-04	5.413629E-04
.3750	.1157	.0700	.9530	1.0000	8.099000E-04	7.718347E-04
.4000	.1429	.0750	.9840	1.0000	1.071750E-03	1.054602E-03
.4250	.1693	.0800	1.0000	1.0000	1.354400E-03	1.354400E-03
.4500	.2006	.0850	.9840	1.0000	1.705100E-03	1.677818E-03
.4750	.2044	.1000	.9530	1.0000	2.044000E-03	1.947932E-03
.5000	.1942	.1050	.7940	1.0000	2.039100E-03	1.619045E-03
.5250	.1852	.1130	.7620	1.0000	2.092760E-03	1.594683E-03
.5500	.1725	.1200	.6820	1.0000	2.070000E-03	1.411740E-03
.5750	.1719	.1250	.5550	1.0000	2.148750E-03	1.192556E-03
.6000	.1666	.1300	.4760	1.0000	2.165800E-03	1.030921E-03
.6250	.1586	.1350	.4450	1.0000	2.141100E-03	9.527995E-04
.6500	.1511	.1450	.3600	1.0000	2.190950E-03	7.887420E-04
.6750	.1442	.1550	.2540	1.0000	2.235100E-03	5.677154E-04
.7000	.1369	.1650	.2060	1.0000	2.258950E-03	4.653231E-04
.7250	.1302	.1700	.1590	1.0000	2.213400E-03	3.519306E-04
.7500	.1235	.1750	.0950	1.0000	2.161250E-03	2.053187E-04
.7750	.1171	.1800	.0400	1.0000	2.107800E-03	8.431200E-05
.8000	.1107	.1850	.0240	1.0000	2.047950E-03	4.915080E-05
.8250	.1048	.2900	.0100	1.0000	3.039200E-03	3.039200E-05
.8500	.0988	.2950	.0030	1.0000	2.914600E-03	8.743800E-06
.8750	.0939	.2000	.0220	1.0000	1.878000E-03	4.131600E-05
.9000	.0889	.2000	0	1.0000	1.778000E-03	0.
.9250	.0862	.2000	0	1.0000	1.724000E-03	0.
.9500	.0835	.2050	0	1.0000	1.711750E-03	0.
.9750	.0791	.2080	0	1.0000	1.645280E-03	0.
1.0000	.0746	.2100	0	1.0000	1.566600E-03	0.

Table A-15 (cont)

## SATURN CHECK OUT CASE NO 6

## TV ENERGY DATA FOR SIT WIDE ANGLE CAMERA (CANO)

## SATELLITE 5 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO(W/SQCM)	BEFF(W/SQCM)
.2500	.0070	.0450	0	1.0000	1.409625E-05	0.
.2750	.0204	.0500	.0020	1.0000	4.564500E-05	9.129000E-08
.3000	.0514	.0550	.0950	1.0000	1.265032E-04	1.201323E-05
.3250	.0971	.0600	.4760	1.0000	2.607135E-04	1.240996E-04
.3500	.1093	.0650	.7620	1.0000	3.179264E-04	2.422599E-04
.3750	.1157	.0700	.9530	1.0000	3.624302E-04	3.453960E-04
.4000	.1429	.0750	.9840	1.0000	4.796031E-04	4.719344E-04
.4250	.1693	.0800	1.0000	1.0000	6.050940E-04	6.060940E-04
.4500	.2006	.0850	.9840	1.0000	7.630322E-04	7.508237E-04
.4750	.2044	.1000	.9530	1.0000	9.146900E-04	8.716996E-04
.5000	.1942	.1050	.7940	1.0000	9.124972E-04	7.245223E-04
.5250	.1852	.1130	.7620	1.0000	9.365101E-04	7.136207E-04
.5500	.1725	.1200	.6820	1.0000	9.263250E-04	6.317536E-04
.5750	.1719	.1250	.5550	1.0000	9.615656E-04	5.336633E-04
.6000	.1666	.1300	.4760	1.0000	9.691955E-04	4.613371E-04
.6250	.1586	.1350	.4450	1.0000	9.581422E-04	4.263733E-04
.6500	.1511	.1450	.3600	1.0000	9.834901E-04	3.529620E-04
.6750	.1442	.1550	.2540	1.0000	1.000207E-03	2.540526E-04
.7000	.1369	.1650	.2060	1.0000	1.010835E-03	2.082321E-04
.7250	.1302	.1700	.1590	1.0000	9.904965E-04	1.574339E-04
.7500	.1235	.1750	.0950	1.0000	9.671594E-04	9.138014E-05
.7750	.1171	.1800	.0400	1.0000	9.432405E-04	3.772962E-05
.8000	.1107	.1850	.0240	1.0000	9.164576E-04	2.199498E-05
.8250	.1048	.2900	.0100	1.0000	1.360042E-03	1.360042E-05
.8500	.0988	.2950	.0030	1.0000	1.304283E-03	3.912850E-06
.8750	.0939	.2000	.0220	1.0000	8.404050E-04	1.848391E-05
.9000	.0889	.2000	0	1.0000	7.956550E-04	0.
.9250	.0862	.2000	0	1.0000	7.714900E-04	0.
.9500	.0835	.2050	0	1.0000	7.660031E-04	0.
.9750	.0791	.2080	0	1.0000	7.362628E-04	0.
1.0000	.0746	.2100	0	1.0000	7.010535E-04	0.

## SATURN CHECK OUT CASE NO 6

## TV ENERGY DATA FOR SIT WIDE ANGLE CAMERA (CANO)

## SATELLITE 6 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO(W/SQCM)	BEFF(W/SQCM)
.2500	.0070	.0450	0	1.0000	1.031525E-05	0.
.2750	.0204	.0500	.0020	1.0000	3.340500E-05	6.681000E-08
.3000	.0514	.0550	.0950	1.0000	9.258425E-05	8.795504E-06
.3250	.0971	.0600	.4760	1.0000	1.908015E-04	9.082151E-05
.3500	.1093	.0650	.7620	1.0000	2.326724E-04	1.772963E-04
.3750	.1157	.0700	.9530	1.0000	2.652422E-04	2.527759E-04
.4000	.1429	.0750	.9840	1.0000	3.509931E-04	3.453322E-04
.4250	.1693	.0800	1.0000	1.0000	4.435660E-04	4.435660E-04
.4500	.2006	.0850	.9840	1.0000	5.584202E-04	5.494855E-04
.4750	.2044	.1000	.9530	1.0000	6.694100E-04	6.379477E-04
.5000	.1942	.1050	.7940	1.0000	6.678052E-04	5.302374E-04
.5250	.1852	.1130	.7620	1.0000	6.853789E-04	5.222587E-04
.5500	.1725	.1200	.6820	1.0000	6.779250E-04	4.623449E-04
.5750	.1719	.1250	.5550	1.0000	7.037156E-04	3.905522E-04
.6000	.1666	.1300	.4760	1.0000	7.032995E-04	3.378266E-04
.6250	.1586	.1350	.4450	1.0000	7.012102E-04	3.120386E-04
.6500	.1511	.1450	.3600	1.0000	7.175361E-04	2.583130E-04
.6750	.1442	.1550	.2540	1.0000	7.319952E-04	1.859263E-04
.7000	.1369	.1650	.2060	1.0000	7.397734E-04	1.523933E-04
.7250	.1302	.1700	.1590	1.0000	7.248335E-04	1.152573E-04
.7500	.1235	.1750	.0950	1.0000	7.078094E-04	6.724183E-05
.7750	.1171	.1800	.0400	1.0000	6.903045E-04	2.761218E-05
.8000	.1107	.1850	.0240	1.0000	6.707036E-04	1.609689E-05
.8250	.1048	.2900	.0100	1.0000	9.953380E-04	9.953380E-06
.8500	.0988	.2950	.0030	1.0000	9.545315E-04	2.863594E-06
.8750	.0939	.2000	.0220	1.0000	6.150450E-04	1.353099E-05
.9000	.0889	.2000	0	1.0000	5.822953E-04	0.
.9250	.0862	.2000	0	1.0000	5.646100E-04	0.
.9500	.0835	.2050	0	1.0000	5.605981E-04	0.
.9750	.0791	.2080	0	1.0000	5.388292E-04	0.
1.0000	.0746	.2100	0	1.0000	5.130615E-04	0.

Table A-15 (cont)

SATURN CHECK OUT CASE NO 6

TV ENERGY DATA FOR SIT WIDE ANGLE CAMERA (CAND)

SATELLITE 7 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO(W/SQCM)	BEFF(W/SQCM)
.2500	.0070	.0450	0	1.0000	2.953125E-05	0.
.2750	.0204	.0500	.0020	1.0000	9.562500E-05	1.912500E-07
.3000	.0514	.0550	.0950	1.0000	2.650312E-04	2.517797E-05
.3250	.0971	.0600	.4760	1.0000	5.461875E-04	2.599852E-04
.3500	.1093	.0650	.7620	1.0000	6.660469E-04	5.075277E-04
.3750	.1157	.0700	.9530	1.0000	7.592812E-04	7.235950E-04
.4000	.1429	.0750	.9840	1.0000	1.004766E-03	9.886894E-04
.4250	.1693	.0800	1.0000	1.0000	1.269750E-03	1.269750E-03
.4500	.2006	.0850	.9840	1.0000	1.598531E-03	1.572955E-03
.4750	.2044	.1000	.9530	1.0000	1.916250E-03	1.826186E-03
.5000	.1942	.1050	.7940	1.0000	1.911656E-03	1.517855E-03
.5250	.1852	.1130	.7620	1.0000	1.961962E-03	1.495015E-03
.5500	.1725	.1200	.6820	1.0000	1.940625E-03	1.323506E-03
.5750	.1719	.1250	.5550	1.0000	2.014453E-03	1.118021E-03
.6000	.1666	.1300	.4760	1.0000	2.030437E-03	9.664882E-04
.6250	.1586	.1350	.4450	1.0000	2.007281E-03	8.932462E-04
.6500	.1511	.1450	.3600	1.0000	2.054016E-03	7.394456E-04
.6750	.1442	.1550	.2540	1.0000	2.095406E-03	5.322332E-04
.7000	.1369	.1650	.2060	1.0000	2.117672E-03	4.362404E-04
.7250	.1302	.1700	.1590	1.0000	2.075062E-03	3.299349E-04
.7500	.1235	.1750	.0950	1.0000	2.026172E-03	1.924863E-04
.7750	.1171	.1800	.0400	1.0000	1.976062E-03	7.904250E-05
.8000	.1107	.1850	.0240	1.0000	1.919953E-03	4.607887E-05
.8250	.1048	.2900	.0100	1.0000	2.849250E-03	2.849250E-05
.8500	.0988	.2950	.0030	1.0000	2.732437E-03	8.197312E-06
.8750	.0939	.2000	.0220	1.0000	1.760625E-03	3.873375E-05
.9000	.0889	.2000	0	1.0000	1.666875E-03	0.
.9250	.0862	.2000	0	1.0000	1.616250E-03	0.
.9500	.0835	.2050	0	1.0000	1.604766E-03	0.
.9750	.0791	.2080	0	1.0000	1.542450E-03	0.
1.0000	.0746	.2100	0	1.0000	1.468687E-03	0.

SATURN CHECK OUT CASE NO 6

COMPUTATIONS FOR MINIMUM PICTURE TAKING INTERVAL

PICTURE START TIME (DAYS) = -1.50000000E+00  
 PICTURE STOP TIME (DAYS) = 1.50000000E+00  
 DELTA T REQUESTED (SEC) = 3.00000000E+02  
 FRAME READ TIME (SEC) = 4.00000000E+01  
 FRAME READ RATE (BPS) = 1.28000000E+05

BULK DATA STORAGE CAPACITY (BITS) = 1.00000000E+09  
 PICTURE SIZE (BITS) = 5.12000000E+06  
 BULK DATA STORAGE CAPACITY (PICS) = 1.95312500E+02  
 BULK CONTENTS IN USE (BITS) = 0.  
 BUFFER STORAGE CAPACITY (BITS) = 5.12000000E+06

DATA TRANSMISSION RATE (BPS) = 4.74000000E+04  
 RATE FROM OTHER INSTRUMENTS (BPS) = 1.00000000E+02  
 REAL TIME PICTURE RATE (BPS) = 4.73000000E+04

MINIMUM PICTURE INTERVAL (SEC) = 1.08245243E+02  
 MAXIMUM PICTURE RATE (PICS/HR) = 3.32578125E+01  
 MAXIMUM PICTURE RATE (PIC/DAY) = 7.98187500E+02  
 MAXIMUM NUMBER OF PICTURES = 2394  
 ACTUAL PICTURE RATE (PIC/DAY) = 2.88000000E+02  
 ACTUAL NUMBER OF PICTURES = 864

PERIAPSIS STATE VECTOR  
 -1.41227165E+05      9.76506451E+04      -4.20838463E+05  
 -2.01311973E+01      -6.14816591E+00      5.32912208E+00  
 VIEW FROM INPUT VIEWPOINT

Table A-15 (cont)

## SATURN CHECK OUT CASE NO 6

PLOT INTERVAL = 3 CALC STEPS = 90.00MINUTES  
 PRNT INTERVAL = 3CALC STEPS = 90.00 MINUTES

TIME INTERVAL FOR CALCULATIONS = 30.00 MINUTES

PICTURE	CALC	TIME (DAYS)	TIME (HRS)	TIME (MIN)
1	1	-1.5000000E+00	-3.6000000E+01	-2.1600000E+03
7	2	-1.4791667E+00	-3.5500000E+01	-2.1300000E+03
13	3	-1.4583333E+00	-3.5000000E+01	-2.1000000E+03
19	4	-1.4375000E+00	-3.4500000E+01	-2.0700000E+03
25	5	-1.4166667E+00	-3.4000000E+01	-2.0400000E+03
31	6	-1.3958333E+00	-3.3500000E+01	-2.0100000E+03
37	7	-1.3750000E+00	-3.3000000E+01	-1.9800000E+03
43	8	-1.3541667E+00	-3.2500000E+01	-1.9500000E+03
49	9	-1.3333333E+00	-3.2000000E+01	-1.9200000E+03
55	10	-1.3125000E+00	-3.1500000E+01	-1.8900000E+03
61	11	-1.2916667E+00	-3.1000000E+01	-1.8600000E+03
67	12	-1.2708333E+00	-3.0500000E+01	-1.8300000E+03
73	13	-1.2500000E+00	-3.0000000E+01	-1.8000000E+03
79	14	-1.2291667E+00	-2.9500000E+01	-1.7700000E+03
85	15	-1.2083333E+00	-2.9000000E+01	-1.7400000E+03
91	16	-1.1875000E+00	-2.8500000E+01	-1.7100000E+03
97	17	-1.1666667E+00	-2.8000000E+01	-1.6800000E+03
103	18	-1.1458333E+00	-2.7500000E+01	-1.6500000E+03
109	19	-1.1250000E+00	-2.7000000E+01	-1.6200000E+03
115	20	-1.1041667E+00	-2.6500000E+01	-1.5900000E+03
121	21	-1.0833333E+00	-2.6000000E+01	-1.5600000E+03
127	22	-1.0625000E+00	-2.5500000E+01	-1.5300000E+03
133	23	-1.0416667E+00	-2.5000000E+01	-1.5000000E+03
139	24	-1.0208333E+00	-2.4500000E+01	-1.4700000E+03
145	25	-1.0000000E+00	-2.4000000E+01	-1.4400000E+03
151	26	-9.7916667E-01	-2.3500000E+01	-1.4100000E+03
157	27	-9.5833333E-01	-2.3000000E+01	-1.3800000E+03
163	28	-9.3750000E-01	-2.2500000E+01	-1.3500000E+03
169	29	-9.1666667E-01	-2.2000000E+01	-1.3200000E+03
175	30	-8.9583333E-01	-2.1500000E+01	-1.2900000E+03
181	31	-8.7500000E-01	-2.1000000E+01	-1.2600000E+03
187	32	-8.5416667E-01	-2.0500000E+01	-1.2300000E+03
193	33	-8.3333333E-01	-2.0000000E+01	-1.2000000E+03
199	34	-8.1250000E-01	-1.9500000E+01	-1.1700000E+03
205	35	-7.9166667E-01	-1.9000000E+01	-1.1400000E+03
211	36	-7.7083333E-01	-1.8500000E+01	-1.1100000E+03
217	37	-7.5000000E-01	-1.8000000E+01	-1.0800000E+03
223	38	-7.2916667E-01	-1.7500000E+01	-1.0500000E+03
229	39	-7.0833333E-01	-1.7000000E+01	-1.0200000E+03
235	40	-6.8750000E-01	-1.6500000E+01	-9.9000000E+02
241	41	-6.6666667E-01	-1.6000000E+01	-9.6000000E+02
247	42	-6.4583333E-01	-1.5500000E+01	-9.3000000E+02
253	43	-6.2500000E-01	-1.5000000E+01	-9.0000000E+02
259	44	-6.0416667E-01	-1.4500000E+01	-8.7000000E+02
265	45	-5.8333333E-01	-1.4000000E+01	-8.4000000E+02
271	46	-5.6250000E-01	-1.3500000E+01	-8.1000000E+02
277	47	-5.4166667E-01	-1.3000000E+01	-7.8000000E+02
283	48	-5.2083333E-01	-1.2500000E+01	-7.5000000E+02
289	49	-5.0000000E-01	-1.2000000E+01	-7.2000000E+02
295	50	-4.7916667E-01	-1.1500000E+01	-6.9000000E+02
301	51	-4.5833333E-01	-1.1000000E+01	-6.6000000E+02
307	52	-4.3750000E-01	-1.0500000E+01	-6.3000000E+02
313	53	-4.1666667E-01	-1.0000000E+01	-6.0000000E+02
319	54	-3.9583333E-01	-9.5000000E+00	-5.7000000E+02
325	55	-3.7500000E-01	-9.0000000E+00	-5.4000000E+02
331	56	-3.5416667E-01	-8.5000000E+00	-5.1000000E+02
337	57	-3.3333333E-01	-8.0000000E+00	-4.8000000E+02
343	58	-3.1250000E-01	-7.5000000E+00	-4.5000000E+02
349	59	-2.9166667E-01	-7.0000000E+00	-4.2000000E+02
355	60	-2.7083333E-01	-6.5000000E+00	-3.9000000E+02
361	61	-2.5000000E-01	-6.0000000E+00	-3.6000000E+02
367	62	-2.2916667E-01	-5.5000000E+00	-3.3000000E+02
373	63	-2.0833333E-01	-5.0000000E+00	-3.0000000E+02
379	64	-1.8750000E-01	-4.5000000E+00	-2.7000000E+02
385	65	-1.6666667E-01	-4.0000000E+00	-2.4000000E+02
391	66	-1.4583333E-01	-3.5000000E+00	-2.1000000E+02
397	67	-1.2500000E-01	-3.0000000E+00	-1.8000000E+02
403	68	-1.0416667E-01	-2.5000000E+00	-1.5000000E+02
409	69	-8.3333333E-02	-2.0000000E+00	-1.2000000E+02
415	70	-6.2500000E-02	-1.5000000E+00	-9.0000000E+01
421	71	-4.1666667E-02	-1.0000000E+00	-6.0000000E+01
427	72	-2.0833333E-02	-5.0000000E-01	-3.0000000E+01
433	73	-7.1054274E-15	-1.7053026E-13	-1.0231815E-11
439	74	2.0833333E-02	5.0000000E-01	3.0000000E+01
445	75	4.1666667E-02	1.0000000E+00	6.0000000E+01
451	76	6.2500000E-02	1.5000000E+00	9.0000000E+01
457	77	8.3333333E-02	2.0000000E+00	1.2000000E+02
463	78	1.0416667E-01	2.5000000E+00	1.5000000E+02
469	79	1.2500000E-01	3.0000000E+00	1.8000000E+02
475	80	1.4583333E-01	3.5000000E+00	2.1000000E+02
481	81	1.6666667E-01	4.0000000E+00	2.4000000E+02
487	82	1.8750000E-01	4.5000000E+00	2.7000000E+02
493	83	2.0833333E-01	5.0000000E+00	3.0000000E+02
499	84	2.2916667E-01	5.5000000E+00	3.3000000E+02



Table A-15 (concl)

505	85	2.5000000E-01	6.0000000E+00	3.6000000E+02
511	86	2.7083333E-01	6.5000000E+00	3.9000000E+02
517	87	2.9166667E-01	7.0000000E+00	4.2000000E+02
523	88	3.1250000E-01	7.5000000E+00	4.5000000E+02
529	89	3.3333333E-01	8.0000000E+00	4.8000000E+02
535	90	3.5416667E-01	8.5000000E+00	5.1000000E+02
541	91	3.7500000E-01	9.0000000E+00	5.4000000E+02
547	92	3.9583333E-01	9.5000000E+00	5.7000000E+02
553	93	4.1666667E-01	1.0000000E+01	6.0000000E+02
559	94	4.3750000E-01	1.0500000E+01	6.3000000E+02
565	95	4.5833333E-01	1.1000000E+01	6.6000000E+02
571	96	4.7916667E-01	1.1500000E+01	6.9000000E+02
577	97	5.0000000E-01	1.2000000E+01	7.2000000E+02
583	98	5.2083333E-01	1.2500000E+01	7.5000000E+02
589	99	5.4166667E-01	1.3000000E+01	7.8000000E+02
595	100	5.6250000E-01	1.3500000E+01	8.1000000E+02
601	101	5.8333333E-01	1.4000000E+01	8.4000000E+02
607	102	6.0416667E-01	1.4500000E+01	8.7000000E+02
613	103	6.2500000E-01	1.5000000E+01	9.0000000E+02
619	104	6.4583333E-01	1.5500000E+01	9.3000000E+02
625	105	6.6666667E-01	1.6000000E+01	9.6000000E+02
631	106	6.8750000E-01	1.6500000E+01	9.9000000E+02
637	107	7.0833333E-01	1.7000000E+01	1.0200000E+03
643	108	7.2916667E-01	1.7500000E+01	1.0500000E+03
649	109	7.5000000E-01	1.8000000E+01	1.0800000E+03
655	110	7.7083333E-01	1.8500000E+01	1.1100000E+03
661	111	7.9166667E-01	1.9000000E+01	1.1400000E+03
667	112	8.1250000E-01	1.9500000E+01	1.1700000E+03
673	113	8.3333333E-01	2.0000000E+01	1.2000000E+03
679	114	8.5416667E-01	2.0500000E+01	1.2300000E+03
685	115	8.7500000E-01	2.1000000E+01	1.2600000E+03
691	116	8.9583333E-01	2.1500000E+01	1.2900000E+03
697	117	9.1666667E-01	2.2000000E+01	1.3200000E+03
703	118	9.3750000E-01	2.2500000E+01	1.3500000E+03
709	119	9.5833333E-01	2.3000000E+01	1.3800000E+03
715	120	9.7916667E-01	2.3500000E+01	1.4100000E+03
721	121	1.0000000E+00	2.4000000E+01	1.4400000E+03
727	122	1.0208333E+00	2.4500000E+01	1.4700000E+03
733	123	1.0416667E+00	2.5000000E+01	1.5000000E+03
739	124	1.0625000E+00	2.5500000E+01	1.5300000E+03
745	125	1.0833333E+00	2.6000000E+01	1.5600000E+03
751	126	1.1041667E+00	2.6500000E+01	1.5900000E+03
757	127	1.1250000E+00	2.7000000E+01	1.6200000E+03
763	128	1.1458333E+00	2.7500000E+01	1.6500000E+03
769	129	1.1666667E+00	2.8000000E+01	1.6800000E+03
775	130	1.1875000E+00	2.8500000E+01	1.7100000E+03
781	131	1.2083333E+00	2.9000000E+01	1.7400000E+03
787	132	1.2291667E+00	2.9500000E+01	1.7700000E+03
793	133	1.2500000E+00	3.0000000E+01	1.8000000E+03
799	134	1.2708333E+00	3.0500000E+01	1.8300000E+03
805	135	1.2916667E+00	3.1000000E+01	1.8600000E+03
811	136	1.3125000E+00	3.1500000E+01	1.8900000E+03
817	137	1.3333333E+00	3.2000000E+01	1.9200000E+03
823	138	1.3541667E+00	3.2500000E+01	1.9500000E+03
829	139	1.3750000E+00	3.3000000E+01	1.9800000E+03
835	140	1.3958333E+00	3.3500000E+01	2.0100000E+03
841	141	1.4166667E+00	3.4000000E+01	2.0400000E+03
847	142	1.4375000E+00	3.4500000E+01	2.0700000E+03
853	143	1.4583333E+00	3.5000000E+01	2.1000000E+03
859	144	1.4791667E+00	3.5500000E+01	2.1300000E+03
865	145	1.5000000E+00	3.6000000E+01	2.1600000E+03

SATURN CHECK OUT CASE NO 6  
SIT WIDE ANGLE CAMERA (CAND)

EXPOSURE TOO HIGH 3.258E-03 (ERGS/CM\*\*2)  
EXPOSURE TIME REDUCED TO 5.221E-05 SEC  
EXPOSURE IS 1.701E-03 (ERG/CM\*\*2)

CHG 1  
EXPOSURE TIME SET TO 0.1 MILLISEC  
REQUIRED FILTER FACTOR IS 1.915E+00  
CHG 1  
VIEW FROM SPACECRAFT

b. Output Data - The tabular output is given in Table A-16 for select frames before, and after, closest approach.

The graphic output consists of the geometry of the frames mentioned above (Fig. A-12), an overview of closest approach (Fig. A-13), summary cone and clock plots (Fig. A-14), and a complete set of analysis frames (Fig. A-15 and A-16).

Table A-16 Case 6 Tabular Output

SATURN CHECK OUT CASE NO 6

PICTURE NUMBER 37 -1 DAYS 9 HRS 0 MIN TO ENCOUNTER JD 2444451.937

PLANET SATURN	SATELLITE RMEA
RANGE (KM) = 2.28133755E+06	RANGE (KM) = 2.53819693E+06
CONE (DEG) = 153.10	CONE (DEG) = 164.07
CLOCK (DEG) = 225.00	CLOCK (DEG) = 222.89
PHASE (DEG) = 23.11	PHASE (DEG) = 12.35
DIAM (DEG) = 3.03	DIAM (DEG) = .03

RESOLUTION OF PLANET  
 CENTER = 222.09 KM/PIXEL  
 LIMB = 224.05 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET SATURN (PICTURE CENTERED AT -1.23 DEG LAT 231.64 DEG LONG )

RESOLUTION AT SPECIFIED LOCATION = 222.09 KM/PIXEL  
 SHEAR DUE TO RELATIVE VELOCITIES 8.09 KM/SEC  
 SHEAR DUE TO S/C ATTITUDE RATES 313.52 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .03 KM  
 NUMBER OF PIXELS SHEARED .00014 PIXELS

- EXPOSURE TIME FOR ONE-HALF PIXEL SHEAR 349.985 MILLISEC

EFFECTIVE RESOLUTION WITH SHEAR  
 AT SPECIFIED LOCATION 222.1 KM/PIXEL  
 AT SUBSPACECRAFT POINT 222.1 KM/PIXEL  
 AT LIMB OF TARGET BODY 228.1 KM/PIXEL

EXPOSURE TIME FOR SIT WIDE ANGLE CAMERA (CAND) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.7143E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.7143E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 85.660  
 DIGITAL NUMBER OF EXPOS = 219 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN	RESOLUTION LEVELS	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET		37.0	0.	0.	0.	
SATELLITE 1		37.0000	37.0000	37.0000	37.0000	
SATELLITE 2		37.0000	0.	0.	0.	
SATELLITE 3		37.0000	0.	0.	0.	
SATELLITE 4		37.0000	0.	0.	0.	
SATELLITE 5		37.0000	0.	0.	0.	
SATELLITE 6		37.0000	0.	0.	0.	
SATELLITE 7		0.	0.	0.	0.	

## SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	0.	0.	0.	0.
2	2.43905148E+06	20.61	155.63	224.86
3	2.23830930E+06	17.30	159.00	223.88
4	2.57570823E+06	23.36	152.83	225.49
5	2.11313188E+06	14.52	161.87	222.86
6	2.53819693E+06	12.35	164.07	222.89
7	3.51807200E+06	20.54	155.66	225.71

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	0.	0.
2	2.06100867E+01	1.19804144E-02
3	1.73015552E+01	1.63325980E-02
4	2.33643558E+01	2.26895635E-02
5	1.45153547E+01	2.41315956E-02
6	1.23509508E+01	3.16027951E-02
7	2.05350039E+01	7.94763230E-02

## RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	0.	0.
2	2.43879652E+02	2.43905151E+02
3	2.23798933E+02	2.23830931E+02
4	2.57519828E+02	2.57570823E+02
5	2.11268692E+02	2.11313187E+02
6	2.53749698E+02	2.53819688E+02
7	3.51563206E+02	3.51807121E+02

## SHEAR DATA FOR SATELLITES

SHEAR DUE TO VEL (KM/SEC)	SHEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SHEARED	TIME TO SHEAR 1/2 PIXEL (SEC)
0.	0.	0.	0.
1.43468795E+01	3.72675942E+02	1.51878327E-04	3.29210895E-01
3.04159664E+00	3.75876440E+02	1.56612523E-04	3.00097490E-01
1.46226746E+01	3.60324727E+02	1.39256303E-04	3.59024393E-01
4.76103655E+00	3.81054637E+02	1.78861974E-04	2.79545165E-01
5.17315803E+00	4.80976805E+02	1.88461848E-04	2.65305963E-01
8.14138711E+00	5.38191636E+02	1.52390088E-04	3.28109328E-01

VIEW FROM SPACECRAFT

Table A-16 (cont)

SATURN CHECK OUT CASE NO 6

PICTURE NUMBER 289 0 DAYS 12 HRS 0 MIN TO ENCOUNTER JD 244452.812

PLANET SATURN	SATELLITE RHEA
RANGE (KM) = 9.51764992E+05	RANGE (KM) = 1.45998684E+06
CONE (DEG) = 136.89	CONE (DEG) = 142.10
CLOCK (DEG) = 204.49	CLOCK (DEG) = 211.32
PHASE (DEG) = 40.40	PHASE (DEG) = 34.81
DIAM (DEG) = 7.28	DIAM (DEG) = .05

RESOLUTION OF PLANET  
 CENTER = 89.14 KM/PIXEL  
 LIMB = 94.98 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET SATURN (PICTURE CENTERED AT -15.35 DEG LAT 226.49 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 89.14 KM/PIXEL  
 SHEAR DUE TO RELATIVE VELOCITIES = 7.97 KM/SEC  
 SHEAR DUE TO S/C ATTITUDE RATES = 86.90 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES = .01 KM  
 NUMBER OF PIXELS SHEARED = .00010 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SHEAR 479.515 MILLISEC

EFFECTIVE RESOLUTION WITH SHEAR  
 AT SPECIFIED LOCATION 89.1 KM/PIXEL  
 AT SUBSPACECRAFT POINT 89.1 KM/PIXEL  
 AT LIMB OF TARGET BODY 95.0 KM/PIXEL

EXPOSURE TIME FOR SIT WIDE ANGLE CAMERA (CAND) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.7736E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.7736E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 88.633  
 DIGITAL NUMBER OF EXPOS = 226 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7312E-06 ERGS/SQ CM

RESOLUTION LEVELS	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	289.0	19.0	0.	0.	
SATELLITE 1	289.0000	289.0000	289.0000	289.0000	
SATELLITE 2	289.0000	0.	0.	0.	
SATELLITE 3	289.0000	13.0000	0.	0.	
SATELLITE 4	289.0000	43.0000	0.	0.	
SATELLITE 5	289.0000	0.	0.	0.	
SATELLITE 6	289.0000	0.	0.	0.	
SATELLITE 7	151.0000	0.	0.	0.	

SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	0.	0.	0.	0.
2	1.01925018E+06	30.85	146.76	200.31
3	8.93709732E+05	94.27	122.77	205.10
4	7.08269117E+05	51.92	125.54	201.23
5	1.30456977E+06	33.74	143.34	205.41
6	1.45998684E+06	34.81	142.10	211.32
7	2.16328630E+06	36.63	139.95	217.43

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	0.	0.
2	3.08470508E+01	2.8668951E-02
3	5.42654803E+01	4.10304357E-02
4	5.19178741E+01	8.25134101E-02
5	3.37445551E+01	3.90831698E-02
6	3.48135716E+01	5.49416557E-02
7	3.66294122E+01	1.29249403E-01

RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	0.	0.
2	1.01899520E+02	1.01925017E+02
3	8.93389747E+01	5.93709589E+01
4	7.07759129E+01	7.08269345E+01
5	1.30412479E+02	1.30456972E+02
6	1.45928687E+02	1.45998670E+02
7	2.16094633E+02	2.16328496E+02

SHEAR DATA FOR SATELLITES

SHEAR DUE TO VEL (KM/SEC)	SHEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SHEARED	TIME TO SHEAR 1/2 PIXEL (SEC)
0.	0.	0.	0.
1.09968979E+01	1.40843424E+02	1.30461567E-04	3.83254632E-01
1.46359769E+01	6.64237343E+01	6.49859141E-05	7.69397522E-01
1.11803183E+01	7.09397433E+01	9.69073415E-05	5.15978079E-01
1.62424327E+01	1.44651572E+02	1.02710704E-04	4.86304190E-01
1.54669222E+01	1.47027174E+02	9.38831830E-05	5.32576711E-01
1.32932331E+01	1.76977103E+02	7.84514970E-05	6.37336550E-01

VIEW FROM SPACECRAFT

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Table A-16 (cont)

SATURN CHECK OUT CASE NO 6

PICTURE NUMBER 415 0 DAYS 1 HRS 30 MIN TO ENCOUNTER JD 244453.250

PLANET SATURN	SATELLITE RHEA
RANGE (KM) = 4.66786399E+05	RANGE (KM) = 8.88154877E+05
CONE (DEG) = 86.46	CONE (DEG) = 102.77
CLOCK (DEG) = 182.45	CLOCK (DEG) = 205.93
PHASE (DEG) = 92.19	PHASE (DEG) = 74.37
DIAM (DEG) = 14.87	DIAM (DEG) = .09

## RESOLUTION OF PLANET

CENTER = 40.64 KM/PIXEL  
 LIMB = 46.29 KM/PIXEL

INSTRUMENT DATA FOR PLANET SATURN

(PICTURE CENTERED AT -31.54 DEG LAT 219.03 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 42.41 KM/PIXEL  
 SHEAR DUE TO RELATIVE VELOCITIES 19.10 KM/SEC  
 SHEAR DUE TO S/C ATTITUDE RATES 111.09 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .01 KM  
 NUMBER OF PIXELS SHEARED .00027 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SHEAR 186.521 MILLISEC

## EFFECTIVE RESOLUTION WITH SHEAR

AT SPECIFIED LOCATION 42.4 KM/PIXEL  
 AT SUBSPACECRAFT POINT 40.6 KM/PIXEL  
 AT LIMB OF TARGET BODY 46.3 KM/PIXEL

EXPOSURE TIME FOR SIT WIDE ANGLE CAMERA (CAND) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.5957E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.5957E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 79.706  
 DIGITAL NUMBER OF EXPOS = 204 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	415.0	145.0	37.0	0.	
SATELLITE 1	415.0000	415.0000	415.0000	415.0000	415.0000
SATELLITE 2	415.0000	115.0000	0.	0.	0.
SATELLITE 3	415.0000	139.0000	67.0000	0.	0.
SATELLITE 4	415.0000	169.0000	85.0000	0.	0.
SATELLITE 5	415.0000	61.0000	0.	0.	0.
SATELLITE 6	415.0000	31.0000	0.	0.	0.
SATELLITE 7	277.0000	0.	0.	0.	0.

## SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	0.	0.	0.	0.
2	5.92551824E+05	102.36	75.56	192.50
3	3.49321210E+05	96.94	83.91	152.90
4	3.45013617E+05	38.24	93.28	143.95
5	7.71910084E+05	83.95	93.36	202.78
6	8.88154877E+05	74.37	102.77	205.93
7	1.50660531E+06	55.38	121.39	213.40

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	0.	0.
2	1.02364226E+02	4.93135744E-02
3	9.69368172E+01	1.04973025E-01
4	8.82411614E+01	1.69389594E-01
5	8.39524234E+01	6.60611224E-02
6	7.43731142E+01	9.03154413E-02
7	5.53807945E+01	1.85585119E-01

## RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	0.	0.
2	5.92296834E+01	5.92551779E+01
3	3.49001216E+01	3.49321070E+01
4	3.44503623E+01	3.45013246E+01
5	7.71465097E+01	7.71903969E+01
6	8.87454892E+01	8.88154616E+01
7	1.50416534E+02	1.50660336E+02

## SHEAR DATA FOR SATELLITES

SHEAR DUE TO VEL (KM/SEC)	SHEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SHEARED	TIME TO SHEAR 1/2 PIXEL (SEC)
0.	0.	0.	0.
3.50135632E+01	1.52714990E+02	2.51407481E-04	1.98880319E-01
1.16053585E+01	1.03718754E+02	2.35671511E-04	1.67497999E-01
1.09829378E+01	1.02962245E+02	2.91840635E-04	1.71326382E-01
2.93489399E+01	1.43590292E+02	1.74381507E-04	2.86727651E-01
2.58409203E+01	1.27477559E+02	1.32037345E-04	3.78680743E-01
1.60131014E+01	8.26309999E+01	4.50349365E-05	1.11024915E+00

VIEW FROM SPACECRAFT

Table A-16 (concl)

## SATURN CHECK OUT CASE NO 6

PICTURE NUMBER 629 1 DAYS 8 HRS 59 MIN TO ENCOUNTER JD 244454.657

PLANET SATURN	SATELLITE RHEA
RANGE (KM) = 2.28133755E+06	RANGE (KM) = 2.76709249E+06
CONE (DEG) = 24.46	CONE (DEG) = 19.81
CLOCK (DEG) = 49.91	CLOCK (DEG) = 49.69
PHASE (DEG) = 159.29	PHASE (DEG) = 163.91
DIAM (DEG) = 3.03	DIAM (DEG) = .03

RESOLUTION OF PLANET  
 CENTER = 222.09 KM/PIXEL  
 LIMB = 228.05 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET SATURN (PICTURE CENTERED AT 3.96 DEG LAT 326.54 DEG LONG )

RESOLUTION AT SPECIFIED LOCATION = 227.05 KM/PIXEL  
 SHEAR DUE TO RELATIVE VELOCITIES 3.83 KM/SEC  
 SHEAR DUE TO S/C ATTITUDE RATES 162.75 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .04 KM  
 NUMBER OF PIXELS SMEARED .00016 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SHEAR 310.167 MILLISEC

EFFECTIVE RESOLUTION WITH SHEAR  
 AT SPECIFIED LOCATION 227.1 KM/PIXEL  
 AT SUBSPACECRAFT POINT 222.1 KM/PIXEL  
 AT LIMB OF TARGET BODY 223.1 KM/PIXEL

EXPOSURE TIME FOR SIT WIDE ANGLE CAMERA (CAND) = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 6.2487E+00 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 6.2487E-14 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 30.967  
 DIGITAL NUMBER OF EXPOS = 73 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7312E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN  
 RESOLUTION LEVELS 300.0 100.0 50.0 10.0 KM/PIXEL

PLANET	829.0	325.0	109.0	0.
SATELLITE 1	829.0000	829.0000	829.0000	829.0000
SATELLITE 2	829.0000	313.0000	0.	0.
SATELLITE 3	829.0000	325.0000	175.0000	0.
SATELLITE 4	829.0000	373.0000	205.0000	0.
SATELLITE 5	829.0000	175.0000	0.	0.
SATELLITE 6	829.0000	163.0000	0.	0.
SATELLITE 7	691.0000	61.0000	0.	0.

## SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	0.	0.	0.	0.
2	2.19703894E+06	155.01	28.75	49.72
3	2.32949463E+06	153.52	30.24	49.72
4	2.57125912E+06	160.53	23.21	49.74
5	2.4750034E+06	151.51	32.25	49.58
6	2.76709249E+06	163.91	19.81	49.69
7	1.90345946E+06	168.65	7.49	225.49

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	0.	0.
2	1.55919551E+02	1.33001046E-02
3	1.53521652E+02	1.57413108E-02
4	1.60530761E+02	2.27283238E-02
5	1.51509316E+02	2.05991666E-02
6	1.63910498E+02	2.89885336E-02
7	1.68647793E+02	1.46892270E-01

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	0.	0.
2	2.19678397E+02	2.19703896E+02
3	2.32947467E+02	2.32949465E+02
4	2.57074917E+02	2.57125912E+02
5	2.47505839E+02	2.47500357E+02
6	2.76639254E+02	2.76709245E+02
7	1.90101949E+02	1.90345793E+02

SHEAR DATA FOR SATELLITES	SHEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SHEAR 1/2 PIXEL (SEC)
0.	0.	0.	0.
4.93179574E+00	2.92819503E+02	1.31824704E-04	3.79291578E-01
5.22722331E+00	2.94107435E+02	1.25296714E-04	3.99052764E-01
1.47749469E+01	4.07820928E+02	1.58212501E-04	3.15990509E-01
6.88065591E+00	2.88657411E+02	1.15639946E-04	4.31630253E-01
1.26824039E+01	4.80005935E+02	1.72839957E-04	2.89201291E-01
1.23638126E+01	5.09128730E+02	2.66573146E-04	1.87565780E-01

VIEW FROM SPACECRAFT

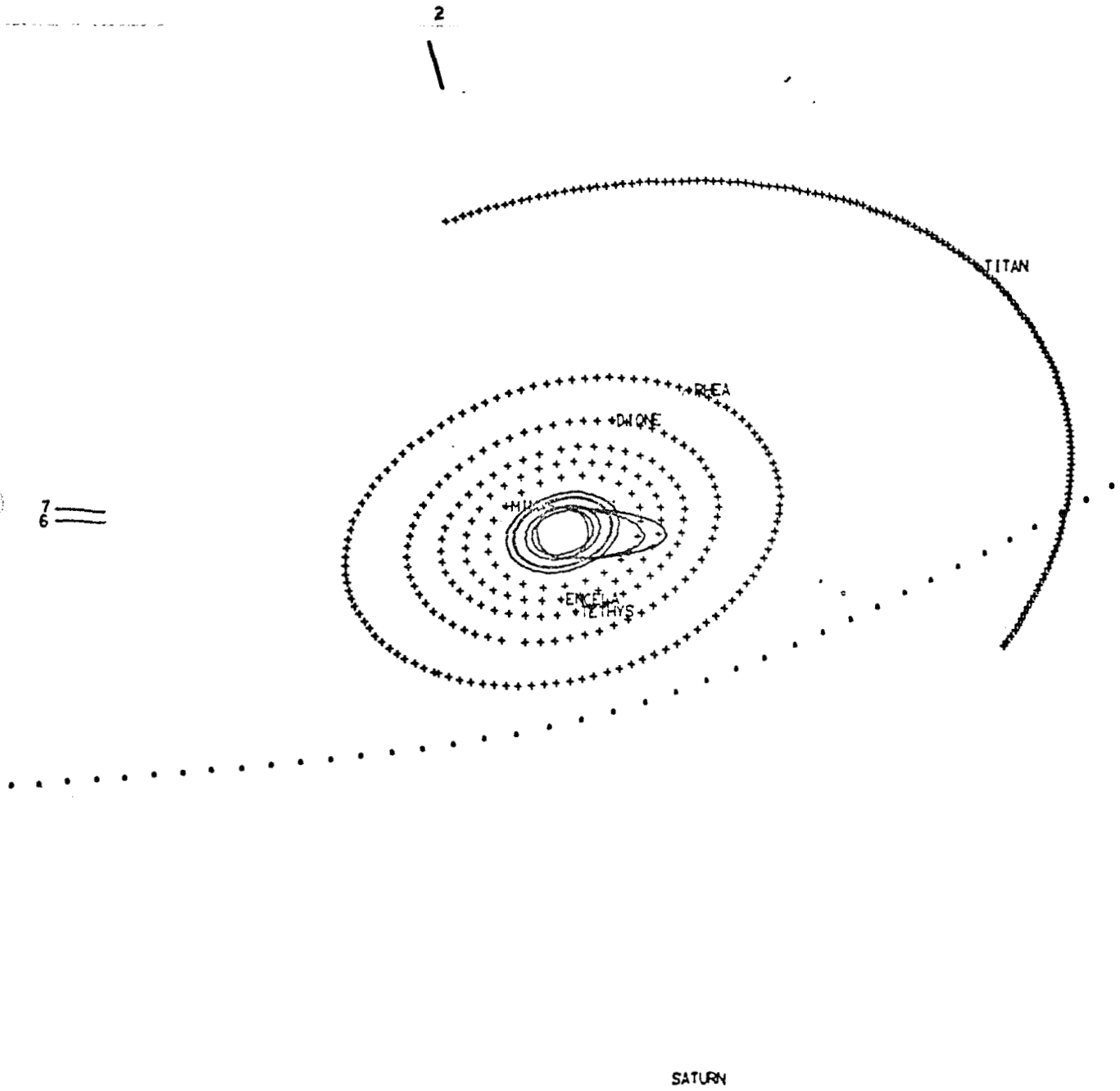
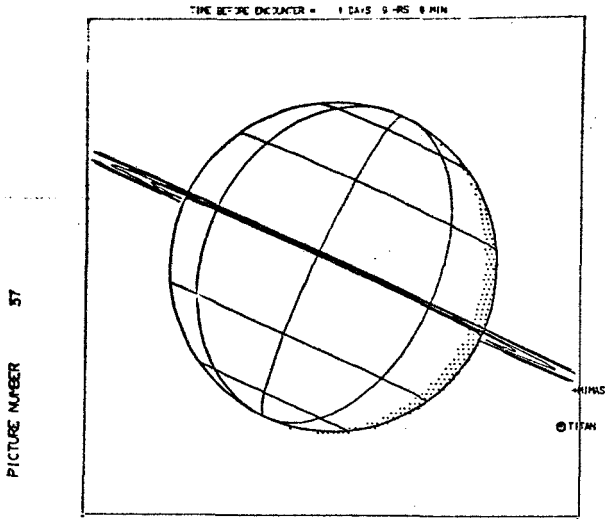
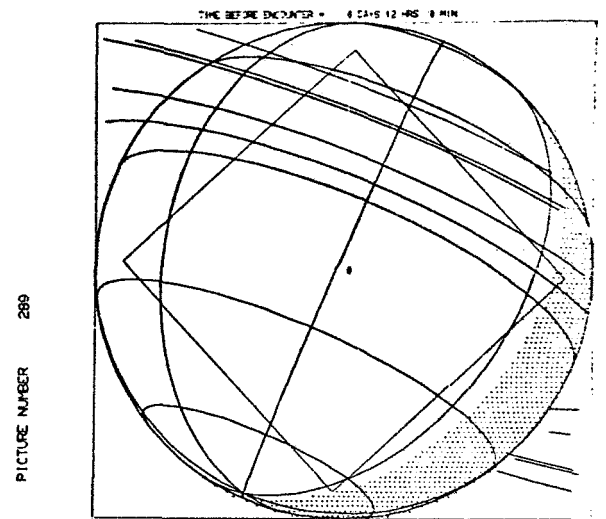


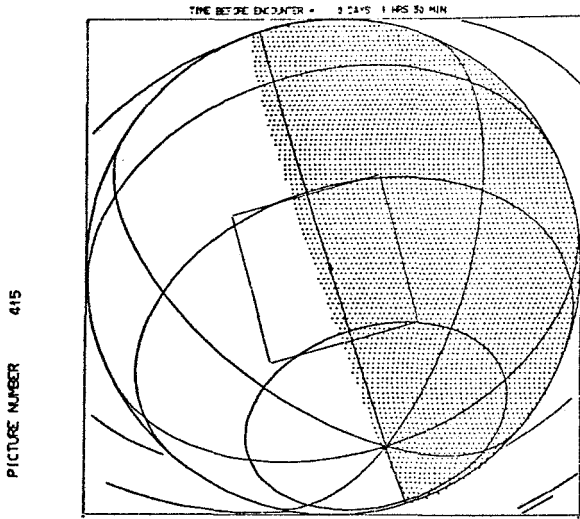
Fig. A-12 Flyby Encounter Geometry



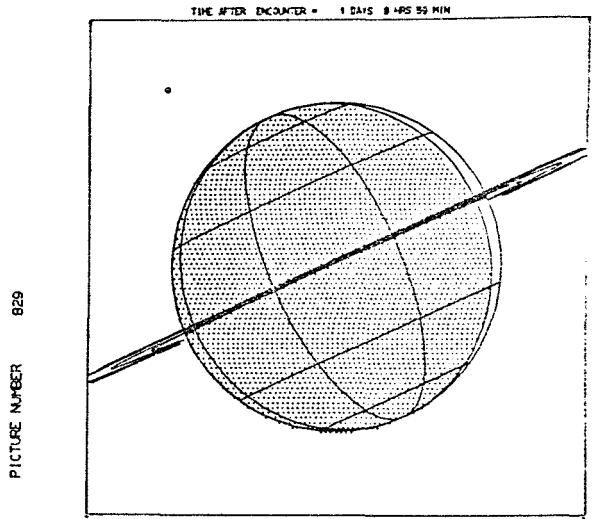
SATURN



SATURN



SATURN



SATURN

Fig. A-13 Scenes Before and After Closest Approach



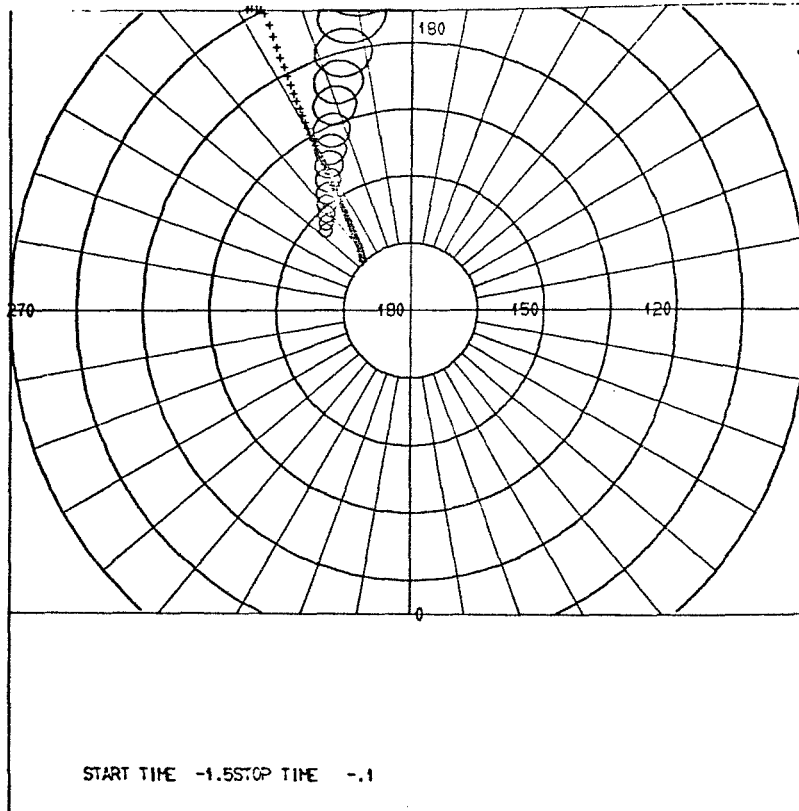
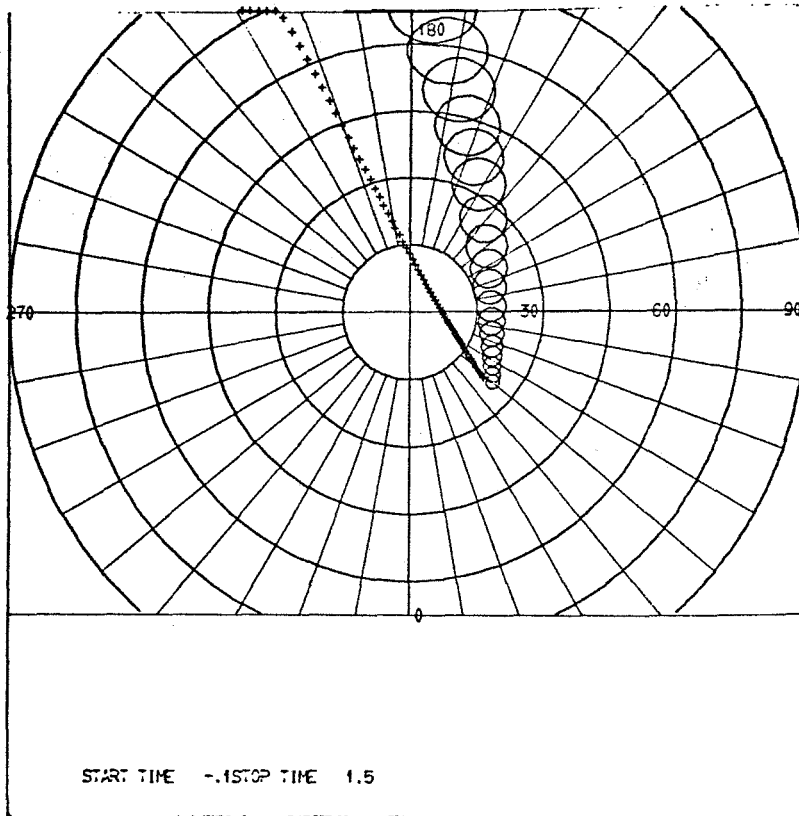


Fig. A-14 Summary Cone and Clock Plots

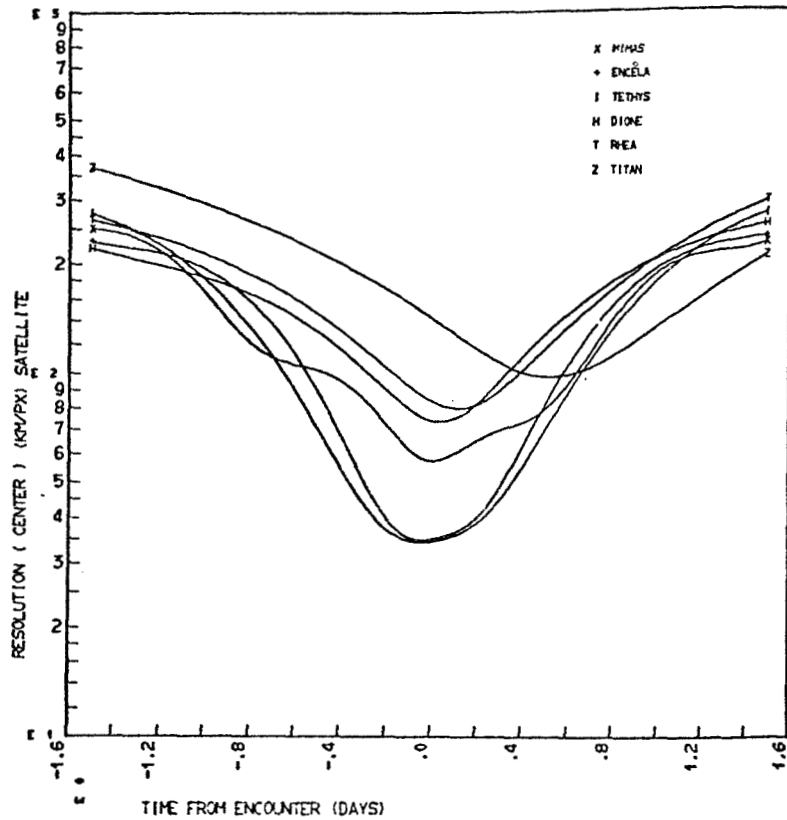
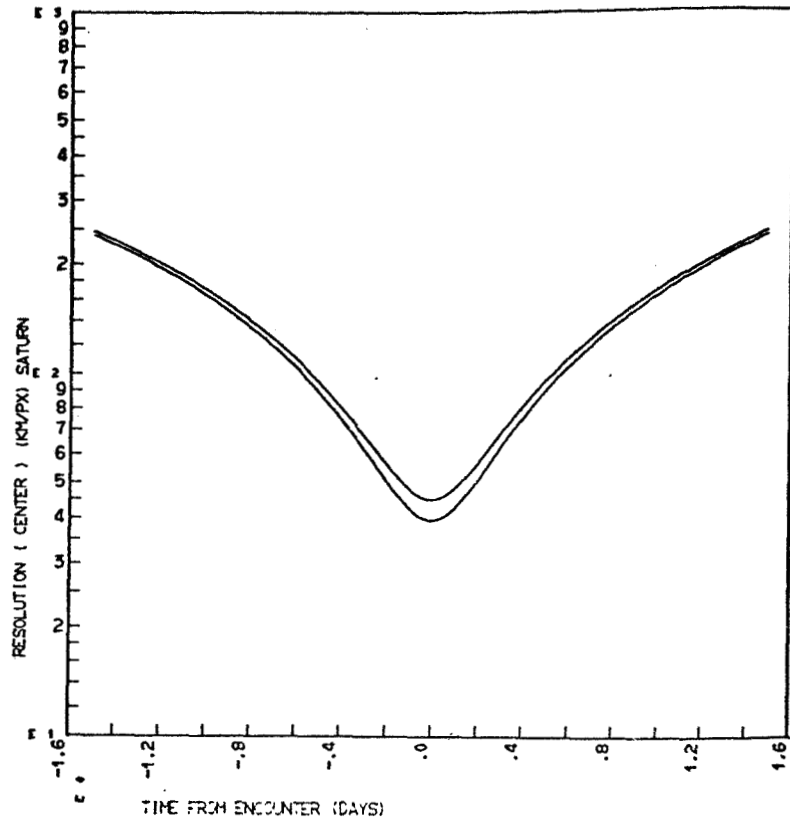


Fig. A-15 TV Summaries

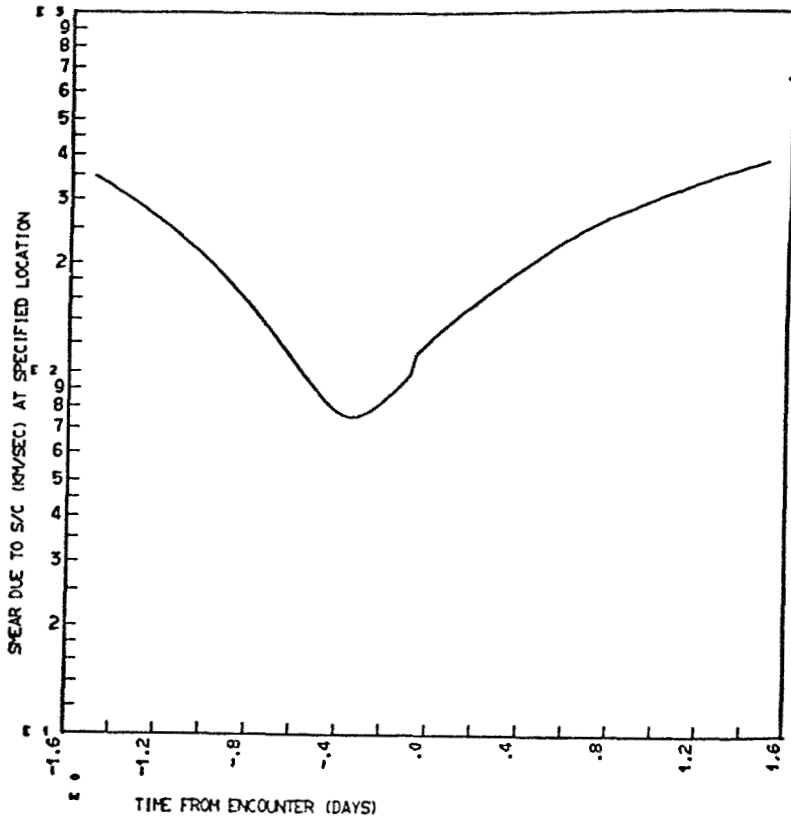
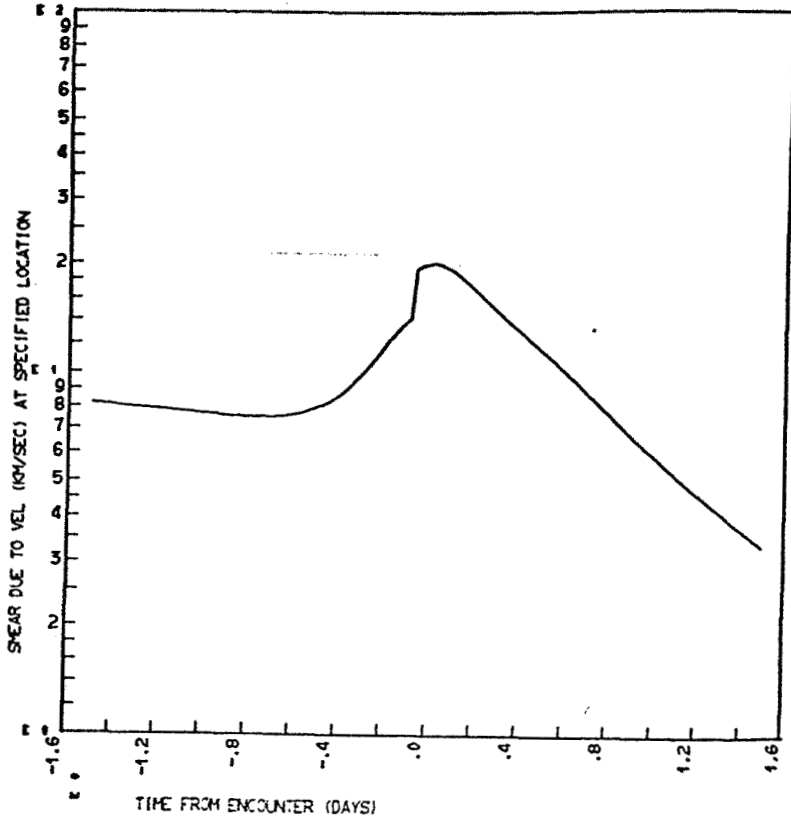


Fig. A-15 (cont)

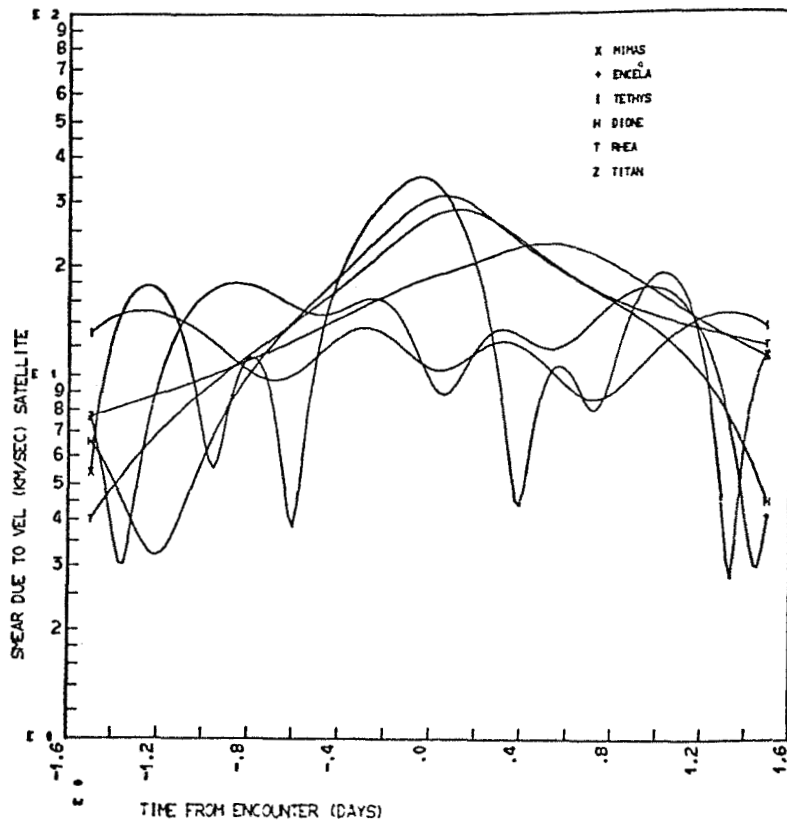
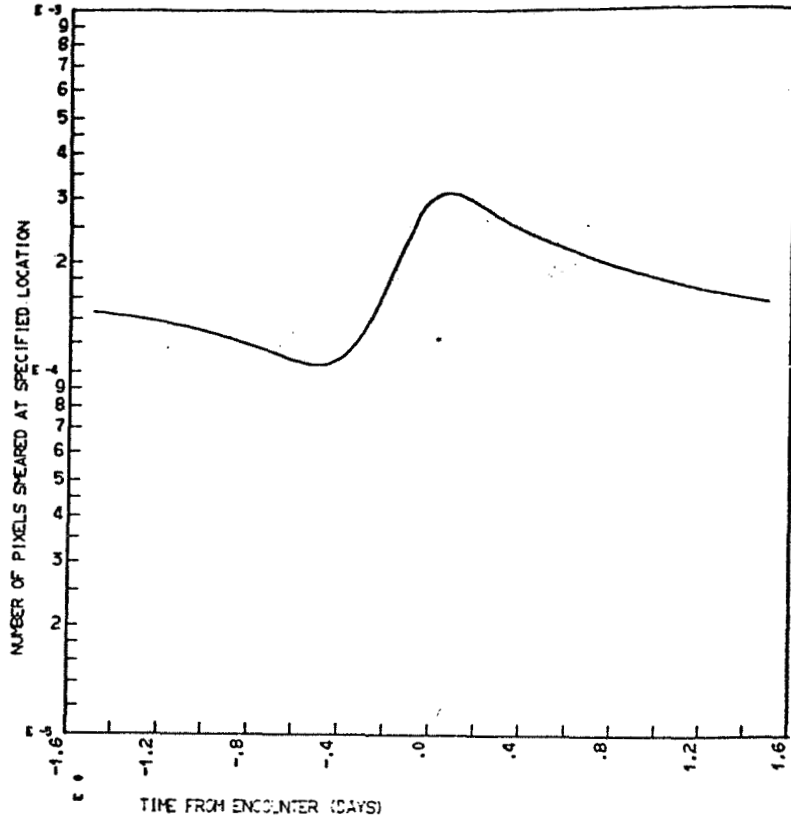


Fig. A-15 (cont)

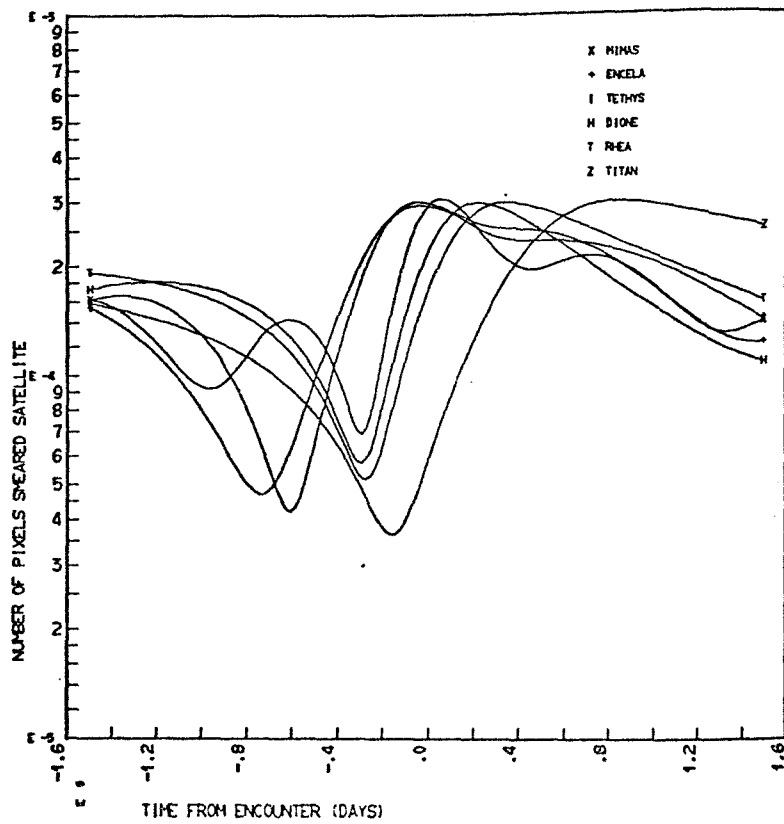
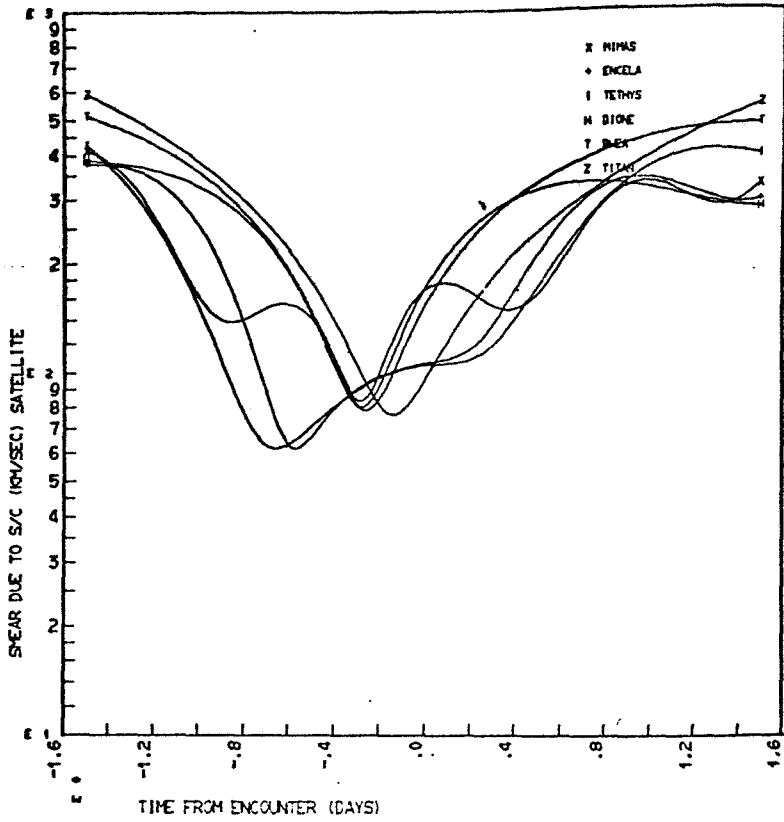


Fig. A-15 (cont)

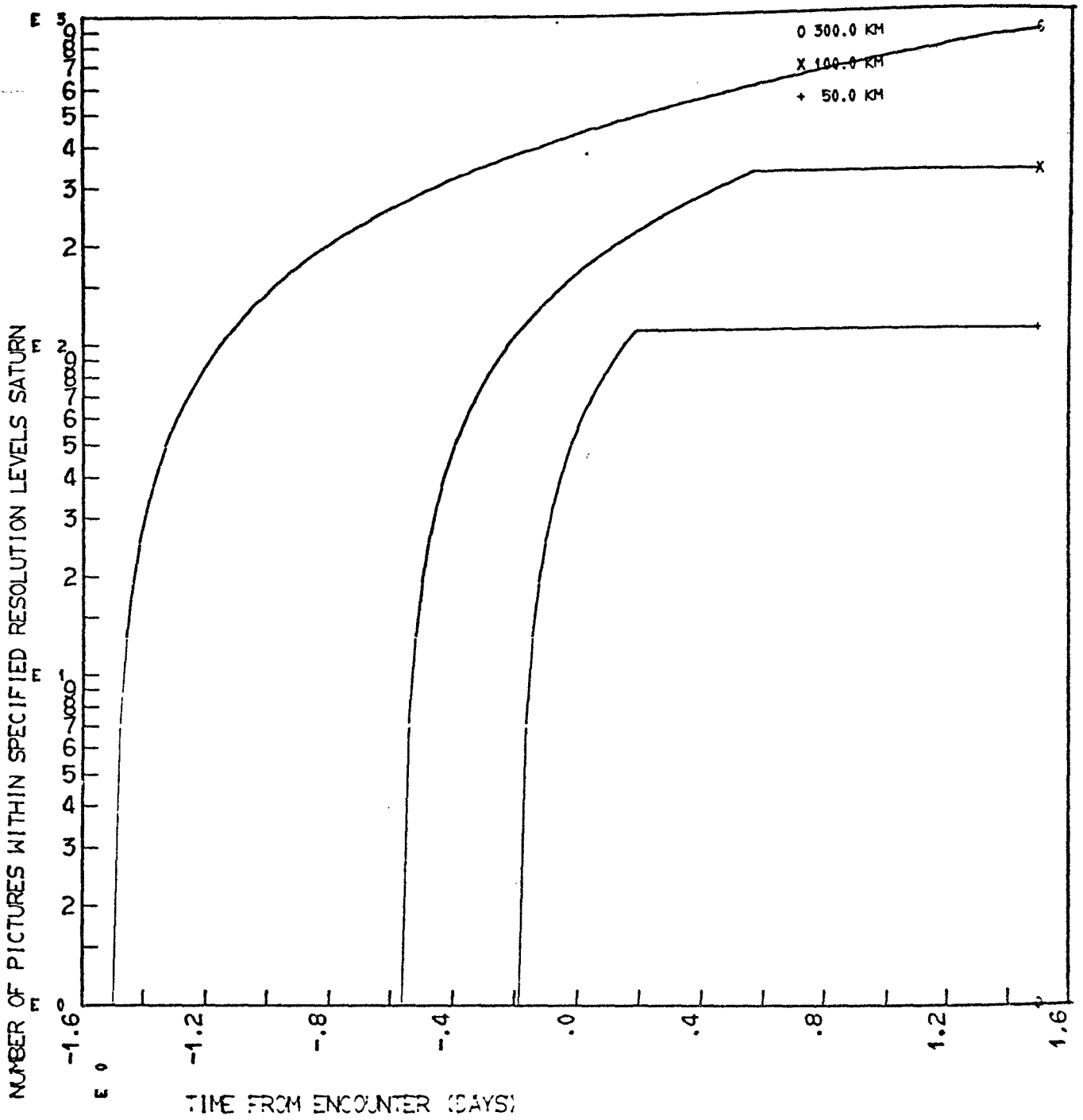


Fig. A-15 (concl)

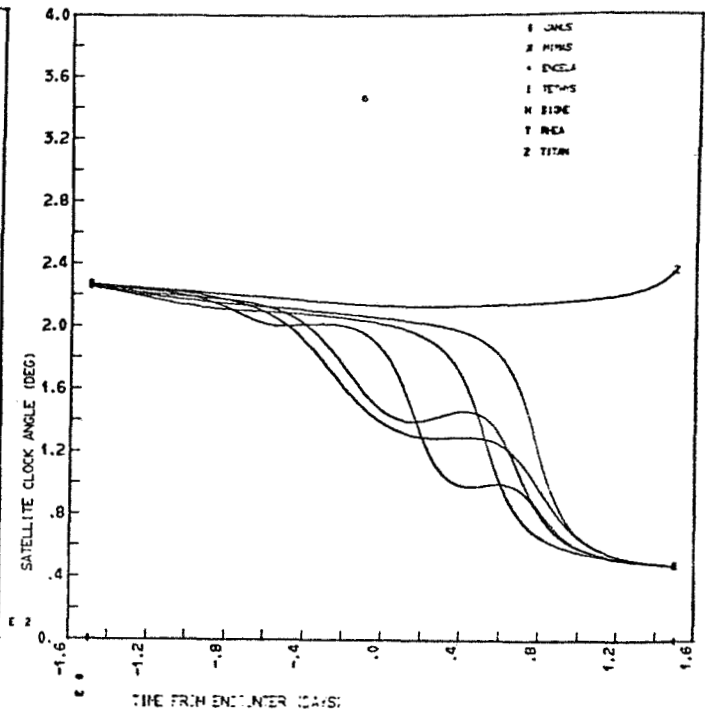
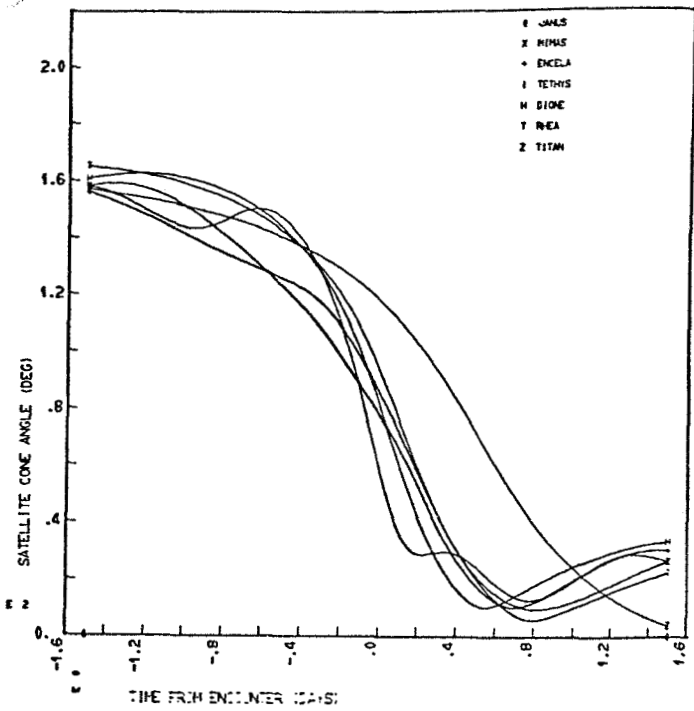
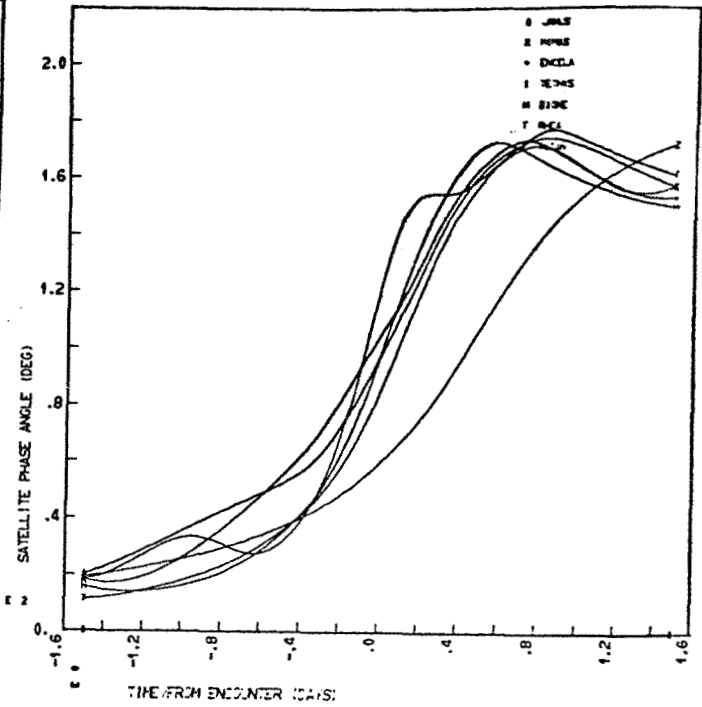
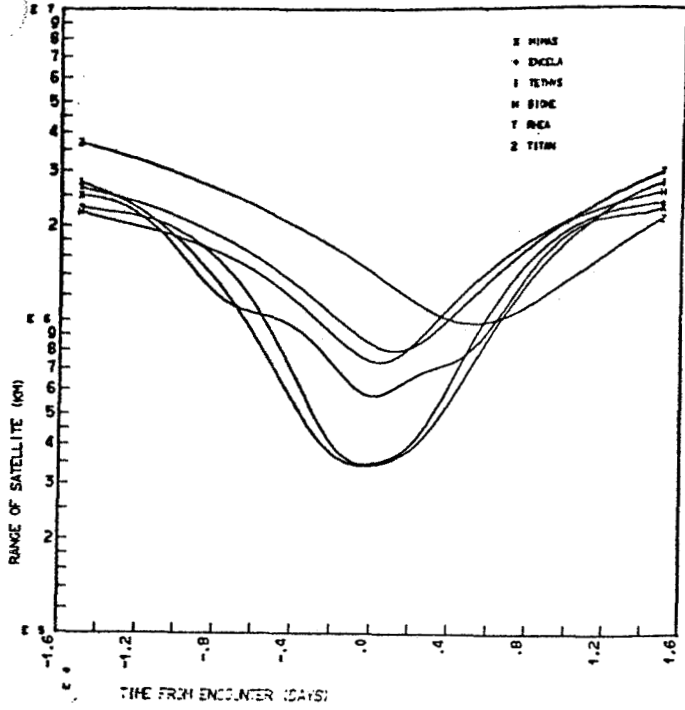


Fig. A-16 Satellite Geometry Summaries

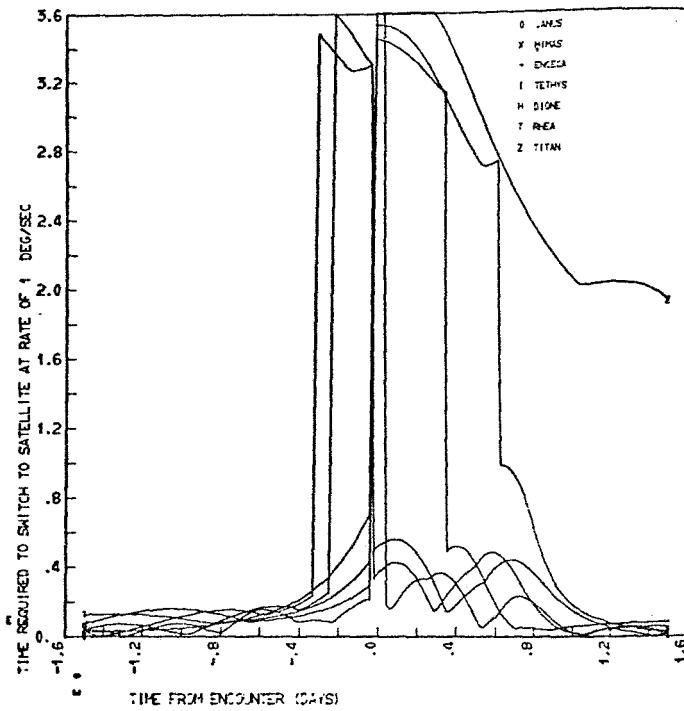
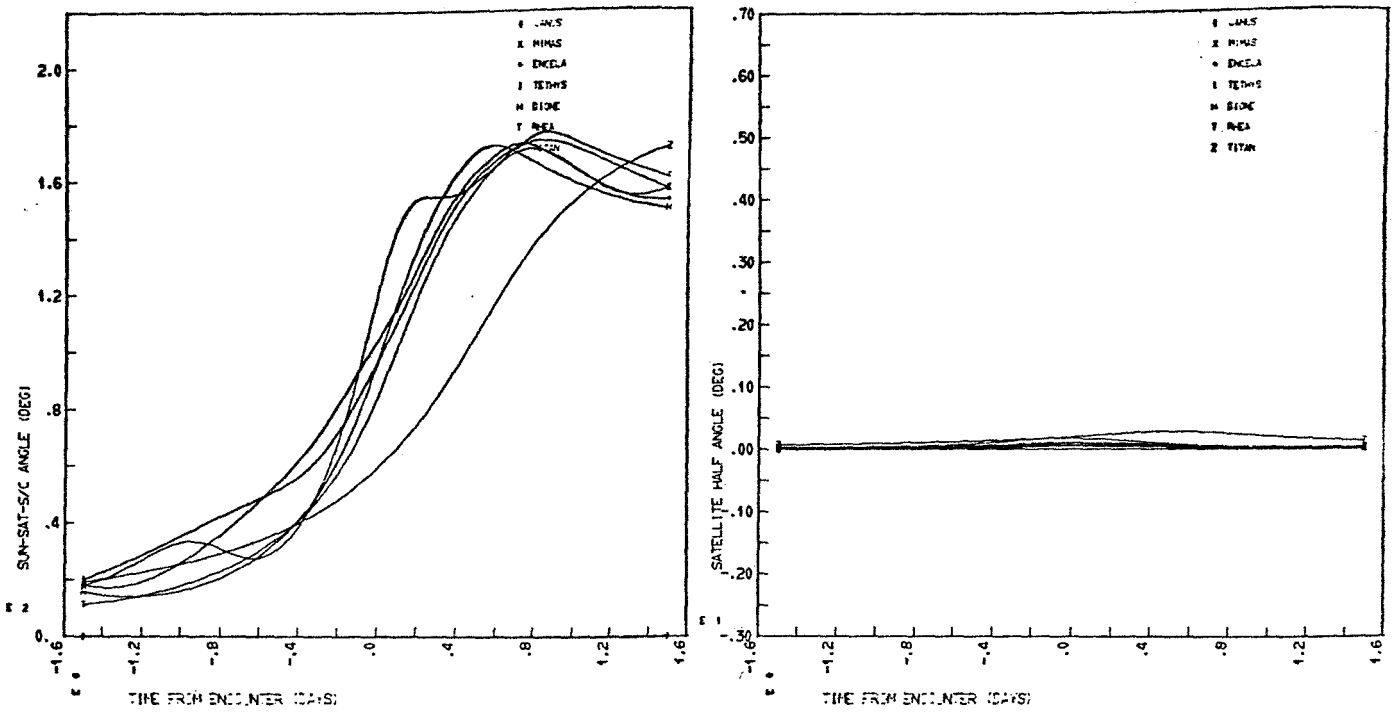


Fig. A-16 (concl)



7. Case 7

a. Input Data - The Saturn input listing, using a narrow-angle camera is given in Table A-17.

Table A-17 Case 7 Input Listing

## SATURN CHECK OUT CASE NO 7

2	6.0000000	PLANET SATURN	
3	6.0000000	SATEL TITAN (VI)	
4	800801.81	DATE	
6	15.0000000		
7	-141227.14	STATE1	
8	97650.653	STATE2	
9	-420838.47	STATE3	
10	-20.131197	STATE4	
11	-6.1481659	STATE5	
12	5.3291219	STATE6	
22	110.00000	INSTIDINSTRUMENT ID (TV,NARROW ANGLE SIT)	
61	-1.5000000	TSTAR	
62	1.5000000	TSTOP	
63	5.0000000	DTINST	
69	5.0000000	CALCSTPICTURES PER CALC STEP	60 MIN PER CALC STEP
81	3.0000000	DPLOT	
82	3.0000000	DPRNT	
90	1111111.0		
98			

b. Output Data - The tabular output, for a narrow-angle camera, is given in Table A-18. This output is for the same frame times as were used for Case 6, which provides a comparison between the narrow- and wide-angle cameras.

The graphic output consists of the geometry (Fig. A-17) of the selected frames, and resolution and smear summaries (Fig. A-18).

Table A-18 Case 7 Tabular Output

SATURN CHECK OUT CASE NO 7

PICTURE NUMBER 37 -1 DAYS 3 HRS 0 MIN TO ENCOUNTER JD 2444451.937

PLANET SATURN	SATELLITE RHEA
RANGE (KM) = 2.28132755E+06	RANGE (KM) = 2.53919693E+06
CONC (DEG) = 153.10	CONC (DEG) = 164.07
CLOCK (DEG) = 225.00	CLOCK (DEG) = 222.89
PHASE (DEG) = 23.11	PHASE (DEG) = 12.35
DIAM (DEG) = 3.03	DIAM (DEG) = .03

RESOLUTION OF PLANET  
 CENTER = 22.21 KM/PIXEL  
 LIMB = 24.81 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET SATURN (PICTURE CENTERED AT: -1.23 DEG LAT 231.64 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 22.21 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 8.09 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 113.52 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .09 KM  
 NUMBER OF PIXELS SMEARED 40352 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 34.999 MILLISEC

EFFECTIVE RESOLUTION WITH SMEAR  
 AT SPECIFIED LOCATION 22.3 KM/PIXEL  
 AT SUBSPACECRAFT POINT 22.3 KM/PIXEL  
 AT LIMB OF TARGET BODY 22.9 KM/PIXEL

EXPOSURE TIME FOR SIT NARROW ANGLE CAMERA (CAND) = .247 MILLISEC  
 POWER DENSITY = 6 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 6.9480E+00 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.7142E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 35.660  
 DIGITAL NUMBER OF EXPOS = 219 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-05 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN RESOLUTION LEVELS	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	37.0	37.0	37.0	0.	
SATELLITE 1	37.0000	37.0000	37.0000	37.0000	37.0000
SATELLITE 2	37.0000	37.0000	37.0000	37.0000	0.
SATELLITE 3	37.0000	37.0000	37.0000	37.0000	0.
SATELLITE 4	37.0000	37.0000	37.0000	37.0000	0.
SATELLITE 5	37.0000	37.0000	37.0000	37.0000	0.
SATELLITE 6	37.0000	37.0000	37.0000	37.0000	0.
SATELLITE 7	37.0000	37.0000	37.0000	37.0000	0.

## SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONC (DEG)	CLOCK (DEG)
1	0.	0.	0.	0.
2	2.43965148E+06	20.61	155.63	224.86
3	2.23830930E+06	17.30	159.00	223.88
4	2.57570823E+06	23.36	152.83	225.49
5	2.11313184E+06	14.52	161.87	222.86
6	2.53819684E+06	12.35	164.07	222.89
7	3.51807200E+06	20.54	155.66	225.71

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	0.	0.
2	2.06160867E+01	1.19804144E-02
3	1.73015582E+01	1.63825886E-02
4	2.33643559E+01	2.26895635E-02
5	1.45153547E+01	2.41315956E-02
6	1.23509568E+01	3.16027851E-02
7	2.05358039E+01	7.94763230E-02

## RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	0.	0.
2	2.42879648E+01	2.43905147E+01
3	2.23798930E+01	2.23830927E+01
4	2.57519823E+01	2.57570318E+01
5	2.11268689E+01	2.11313184E+01
6	2.53749694E+01	2.53819684E+01
7	3.51563200E+01	3.51807115E+01

## SMEAR DATA FOR SATELLITES

SMEAR DUE TO VEL (KM/SEC)	SMEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
0.	0.	0.	0.
1.43463736E+01	3.72675942E+02	3.74741517E-03	3.29213989E-02
3.04159644E+00	3.75873485E+02	4.11096374E-03	3.00097495E-02
1.46226746E+01	3.00324727E+02	3.43622864E-03	3.59024387E-02
4.76103695E+00	3.11084637E+02	4.41320421E-03	2.79545161E-02
5.17315803E+00	4.80976805E+02	4.65306463E-03	2.65309364E-02
8.14138711E+00	5.33191636E+02	3.76004226E-03	3.28105323E-02

VIEW FROM SPACECRAFT



Table A-18 (cont)

SATURN CHECK OUT CASE NO 7

PICTURE NUMBER 415 0 DAYS 1 HRS 30 MIN TO ENCOUNTER JD 244453.250

PLANET SATURN	SATELLITE RHEA
RANGE (KM) = 4.66786319E+05	RANGE (KM) = 8.8915+377E+05
CONE (DEG) = 86.46	CONE (DEG) = 102.77
CLOCK (DEG) = 152.45	CLOCK (DEG) = 205.33
PHASE (DEG) = 32.19	PHASE (DEG) = 74.37
DIAM (DEG) = 14.87	DIAM (DEG) = .09

RESOLUTION OF PLANET  
 CENTER = 4.66 KM/PIXEL  
 LIMB = 4.63 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET SATURN (PICTURE CENTERED AT -31.54 DEG LAT 219.03 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 4.24 KM/PIXEL  
 SHEAR DUE TO RELATIVE VELOCITIES 19.13 KM/SEC  
 SHEAR DUE TO S/C ATTITUDE RATES 111.09 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .02 KM  
 NUMBER OF PIXELS SMEARED 60466 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SKEAR 19.652 MILLISEC

EFFECTIVE RESOLUTION WITH SKEAR  
 AT SPECIFIED LOCATION 4.3 KM/PIXEL  
 AT SUBSPACECRAFT POINT 4.1 KM/PIXEL  
 AT LIMB OF TARGET BODY 4.6 KM/PIXEL

EXPOSURE TIME FOR SIT NARROW ANGLE CAMERA (CANO) = .174 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 3.174E+00 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.5957E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 79.706  
 DIGITAL NUMBER OF EXPOS = 204 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	415.0	415.0	415.0	145.0	
SATELLITE 1	415.0000	415.0000	415.0000	415.0000	
SATELLITE 2	415.0000	415.0000	415.0000	115.0000	
SATELLITE 3	415.0000	415.0000	415.0000	139.0000	
SATELLITE 4	415.0000	415.0000	415.0000	169.0000	
SATELLITE 5	415.0000	415.0000	415.0000	61.0000	
SATELLITE 6	415.0000	415.0000	415.0000	31.0000	
SATELLITE 7	415.0000	415.0000	415.0000	0.	

SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	0.	0.	0.	0.
2	5.92551824E+05	102.36	75.56	192.50
3	3.43321210E+05	96.94	83.31	152.96
4	3.45013617E+05	88.24	93.28	143.95
5	7.71910004E+05	83.95	93.36	202.7d
6	8.84154677E+05	74.37	102.77	205.93
7	1.50060531E+06	95.33	121.39	213.40

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	0.	0.
2	1.02364226E+02	4.93135744E-02
3	9.69368172E+01	1.04973025E-01
4	8.82411614E+01	1.69343594E-01
5	8.39524234E+01	6.60611224E-02
6	7.43731142E+01	9.03154413E-02
7	5.53907945E+01	1.85585119E-01

RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	0.	0.
2	5.92296824E+00	5.92551769E+00
3	3.49001211E+00	3.49321064E+00
4	3.44503617E+00	3.45013240E+00
5	7.71465085E+00	7.71909956E+00
6	8.87454877E+00	8.88154601E+00
7	1.50060334E+01	1.50060334E+01

SKEAR DATA FOR SATELLITES

SKEAR DUE TO VEL (KM/SEC)	SKEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SKEARED	TIME TO SKEAR 1/2 PIXEL (SEC)
0.	0.	0.	0.
3.50135632E+01	1.52714990E+02	4.37275032E-03	1.98440316E-02
1.16058535E+01	1.33719764E+02	5.19481737E-03	1.67407996E-02
1.09829378E+01	1.02962245E+02	5.07600739E-03	1.71326379E-02
2.93403333E+01	1.4350292E+02	3.33303144E-03	2.36727647E-02
2.58449203E+01	1.2747759E+02	2.29653635E-03	3.73640737E-02
1.80131014E+01	8.2630999E+01	7.33296235E-04	1.11024913E-01

VIEW FROM SPACECRAFT

Table A-18 (concl)

SATURN CHECK OUT CASE NO 7

PICTURE NUMBER 829 1 DAYS 8 HRS 59 MIN TO ENCOUNTER JD 244454.687

PLANET SATURN	SATELLITE RHEA
RANGE (KM) = 2.28133755E+05	RANGE (KM) = 2.7673249E+36
CONE (DEG) = 24.46	CONE (DEG) = 19.81
CLOCK (DEG) = 49.91	CLOCK (DEG) = 49.69
PHASE (DEG) = 159.29	PHASE (DEG) = 163.91
DIAM (DEG) = 3.03	DIAM (DEG) = .03

RESOLUTION OF PLANET  
 CENTER = 22.21 KM/PIXEL  
 LIMB = 22.81 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET SATURN (PICTURE CENTERED AT 3.96 DEG LAT 326.54 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 22.70 KM/PIXEL  
 SHEAR DUE TO RELATIVE VELOCITIES 3.83 KM/SEC  
 SHEAR DUE TO S/C ATTITUDE RATES 362.75 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .06 KM  
 NUMBER OF PIXELS SKEWED .00280 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SHEAR 31.017 MILLISEC

EFFECTIVE RESOLUTION WITH SHEAR  
 AT SPECIFIED LOCATION 22.8 KM/PIXEL  
 AT SUBSPACECRAFT POINT 22.3 KM/PIXEL  
 AT LIMB OF TARGET BODY 22.3 KM/PIXEL

EXPOSURE TIME FOR SIT NARROW ANGLE CAMERA (CAND) = .174 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 3.5926E+00 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 5.2487E-04 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 30.967  
 DIGITAL NUMBER OF EXPOS = 79 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-05 ERGS/SQ CM

RESOLUTION LEVELS	303.0	100.0	50.0	10.0	KM/PIXEL
PLANET	829.0	823.0	829.0	325.0	
SATELLITE 1	829.0000	823.0000	829.0000	329.0000	
SATELLITE 2	829.0000	823.0000	829.0000	313.0000	
SATELLITE 3	829.0000	823.0000	829.0000	325.0000	
SATELLITE 4	829.0000	823.0000	829.0000	373.0000	
SATELLITE 5	829.0000	823.0000	829.0000	175.0000	
SATELLITE 6	829.0000	823.0000	829.0000	163.0000	
SATELLITE 7	829.0000	823.0000	829.0000	61.0000	

## SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	0.	0.	0.	0.
2	2.19703894E+05	155.01	28.75	49.72
3	2.32949463E+06	153.52	30.24	49.72
4	2.57125312E+06	160.55	23.21	49.74
5	2.47550034E+06	151.51	32.25	49.58
6	2.7673249E+06	153.91	19.81	49.69
7	1.90345946E+06	168.63	7.49	229.49

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	0.	0.
2	1.55010551E+02	1.33001046E-02
3	1.53521652E+02	1.57413108E-02
4	1.60530761E+02	2.27288238E-02
5	1.51509316E+02	2.05991666E-02
6	1.63910498E+02	2.89885836E-02
7	1.68647793E+02	1.46892270E-01

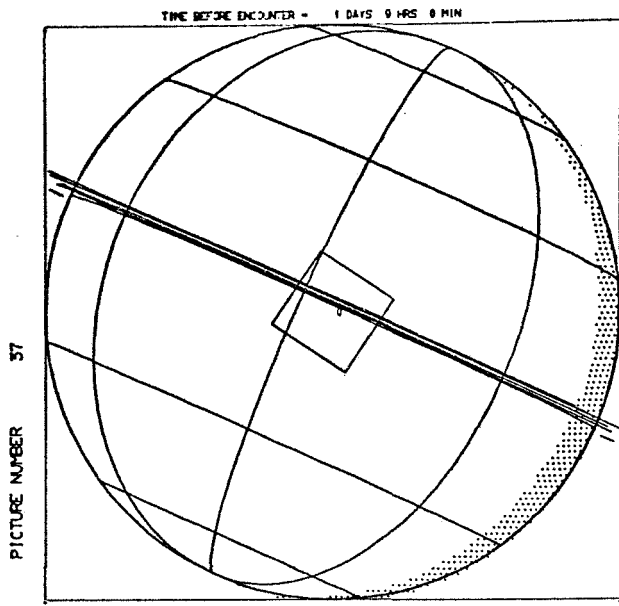
## RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	0.	0.
2	2.19678394E+01	2.19703892E+01
3	2.32917463E+01	2.32949461E+01
4	2.57074912E+01	2.57125307E+01
5	2.47505934E+01	2.47550030E+01
6	2.76639249E+01	2.76732490E+01
7	1.90101946E+01	1.90345790E+01

## SHEAR DATA FOR SATELLITES

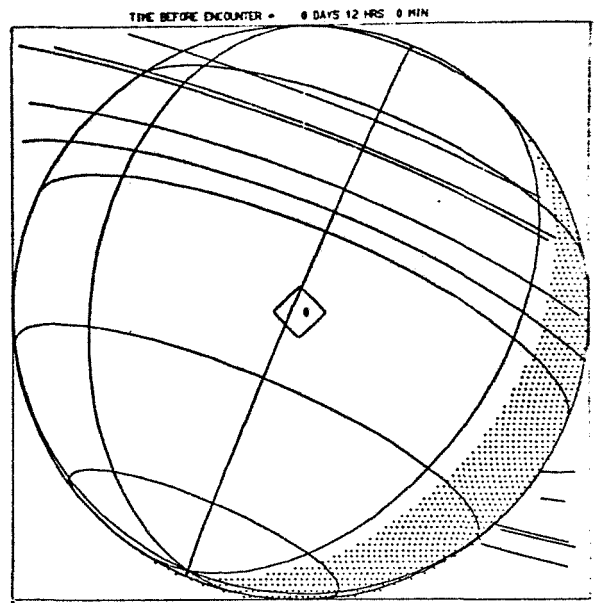
SHEAR DUE TO VEL (KM/SEC)	SHEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SKEWED	TIME TO SHEAR 1/2 PIXEL (SEC)
0.	0.	0.	0.
4.93179578E+00	2.92813503E+02	2.29283757E-03	3.79291572E-02
5.22722331E+04	2.34107435E+02	2.17329572E-03	3.99652757E-02
1.47740468E+01	4.37823928E+02	2.75215222E-03	3.15993504E-02
6.88365591E+00	2.88657091E+02	2.31481236E-03	4.31633251E-02
1.26424033E+01	4.40005995E+02	3.00708836E-03	2.89201277E-02
1.23638120E+01	5.09128790E+02	4.63652735E-03	1.87565776E-02

VIEW FROM SPACECRAFT



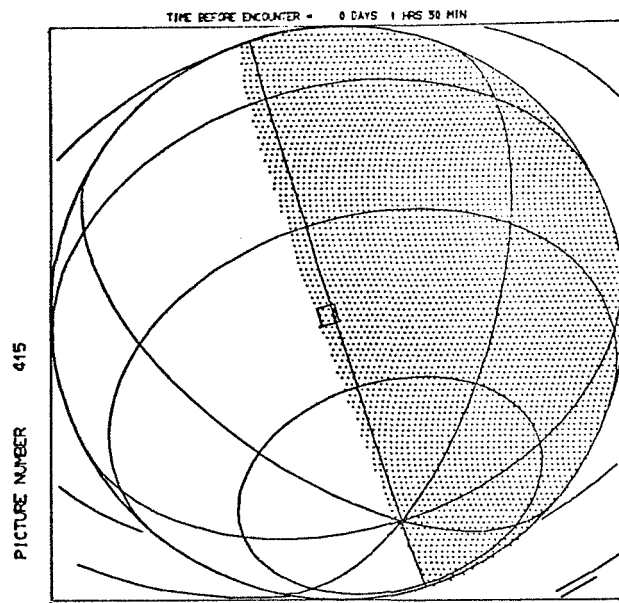
SA TURN C HECK 0 UT CAS E NO 7

SATURN



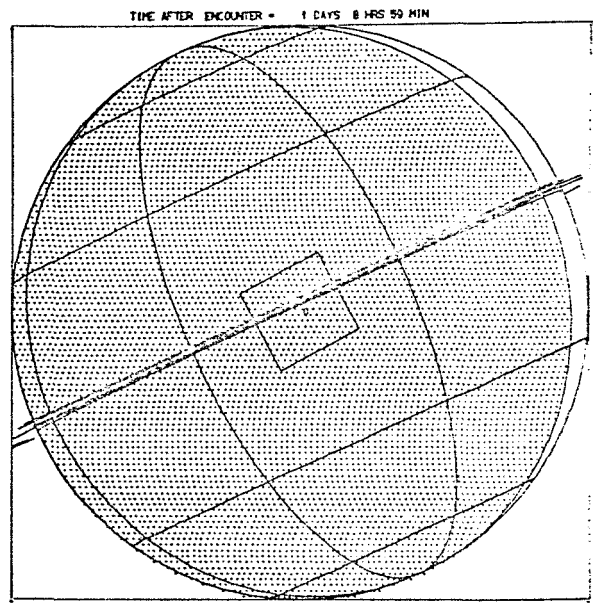
SA TURN C HECK 0 UT CAS E NO 7

SATURN



SA TURN C HECK 0 UT CAS E NO 7

SATURN



SA TURN C HECK 0 UT CAS E NO 7

SATURN

Fig. A-17 Scenes Before and After Closest Approach

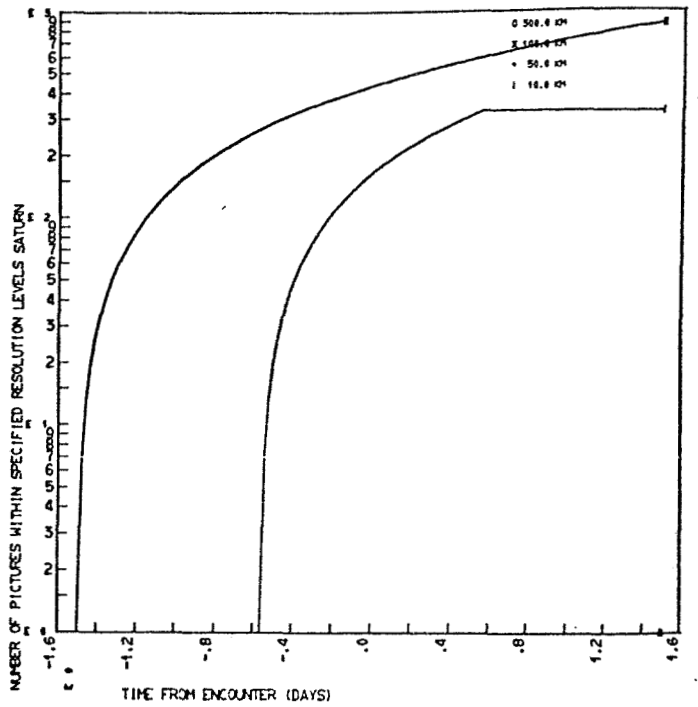
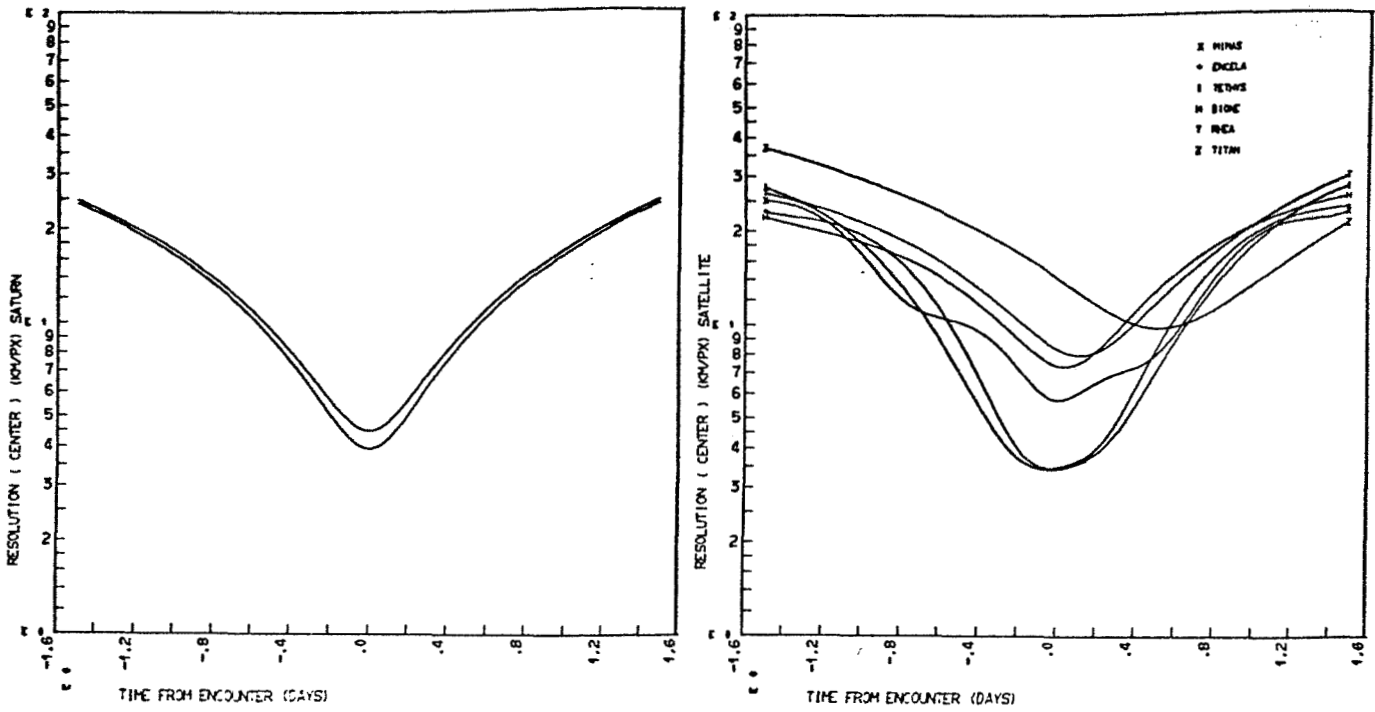


Fig. A-18 TV Summaries

### C. MISSION 3

The specific objective of Mission 3 is to provide the data and guidelines to validate spacecraft configuration, orbital trajectory, and to complete the science options. Mission 2 validated the imaging analysis capability in conjunction with a TOPS spacecraft configuration; Mission 3 considers a spinning type spacecraft, includes particle and field capability, and treats the orbiter mission.

#### 1. Science Mode

TV characteristics were discussed in previous missions; therefore, no detail is included here. The particle and field instruments are modeled at a system level--principally, sensitivity limits and data rate modes (Tables A-19 and A-20).

Table A-19 Magnetometer Characteristics

RATE	60 Bits/Sample	High Rate	25 Samples/Sec
	60 Bits/Sample	Low Rate	1 Sample/Sec
SENSITIVITY	High	0.02 Gamma	
	Low	0.2 Gamma	
RANGE	2.5, 10, 10 <sup>2</sup> , 10 <sup>3</sup> , 10 <sup>4</sup> Gamma 1, 10 Gauss		

Table A-20 Radiation Detector Characteristics

RATE	50 Bits/Sample	High	10 Samples/Sec
		Low	1 Sample/Sec
SENSITIVITY	Electrons	50 kev	
	Protons	0.5 Mev	
RANGE	Electrons	0.05, 0.1, 0.5, 1.0, 3, 5, 50, 100 Mev	
	Protons	0.05, 0.1, 0.5, 1.0, 5, 10, 50, 10 <sup>2</sup> , 10 <sup>3</sup> Mev	

#### 2. Trajectory Data

The trajectory represents a 1984 Jupiter encounter with a subsequent maneuver resulting in an orbit injection. The orbit chosen yields satellite encounters. The approach and subsequent inject conditions are as follows:



Arrival Date	1 Feb 84
Approach Asymptote	
VINF (km/sec)	7.26
Approach Asymptote Angle (deg)	129.8
Asymptote Declination (deg)	0.0
Orbit Periapse Angle (deg)	70.68 ( $0_p$ )
Orbit Period (days)	21.333
Periapse ( $R_J$ )	2.255
Apoapse ( $R_J$ )	59.884
Orbit Capture Impulse (km/sec)	1.384

### 3. Case 8

a. Input Data - This case treats a Jupiter orbital mission with a spinning spacecraft with Pioneer type camera. The input listing is given in Table A-21; additional camera specifications are given in Table A-22.

Table A-21 Case 8 Input Listing

JUPITER CHECK OUT CASE NO 8

2	5.000000	PLANET
3	+.000000	SATEL
4	340201.00	DATE
6	1.000000E+01	
7	2.255000	STATE1
8	59.884000	STATE2
9	70.660000	STATE3
22	110.00000	INST10
31	-0.	NAME-1R
32	-0.	NAME-2
33	-0.	NAME-3
34	-0.	NAME-4
35	-0.	NAME-5
36	25.400000	CHAR-1
37	15.120000	CHAR-2
40	2.500000	CHAR-5
41	2.500000	CHAR-6
42	500.00000	CHAR-7
43	500.00000	CHAR-8
44	6.000000	CHAR-9
51	1.000000	
56	12.70000000E-05	
61	1.000000	TSTAR
62	22.000000	TSTOP
63	720.00000	DTINST
64	-0.	
65	-0.	
66	2048.0000	BITRAT
67	64.000000	
68	150000.0	
69	1.000000	CALCST
81	1.000000	OPLOT
82	1.000000	DPRNT
86	15.000000	SATRNG
90	1111111.0	
98		

JUPITER CHECK OUT CASE NO 8

XZ(I) VALUES IN STORAGE

1	0	0.	2	1	5.0000000000E+00
3	1	4.0000000000E+00	4	1	8.4020100000E+05
5	0	0.	6	1	1.0000000000E+01
7	1	2.2550000000E+00	8	1	5.9884000000E+01
9	1	7.0660000000E+01	10	0	0.
11	0	0.	12	0	0.
13	0	0.	14	0	0.
15	0	3.0000000000E+00	16	0	0.
17	0	0.	18	0	0.
19	0	0.	20	0	0.
21	0	0.	22	1	1.1000000000E+02
23	0	0.	24	0	-7.1738305547E+57
25	0	-7.1738305547E+57	26	0	0.
27	0	0.	28	0	0.
29	0	0.	30	0	0.
31	1	-0.	32	1	-0.
33	1	-0.	34	1	-0.
35	1	-0.	36	1	2.5400000000E+01
37	1	1.5120000000E+01	38	0	0.
39	0	0.	40	1	2.5000000000E+00
41	1	2.5000000000E+00	42	1	5.0000000000E+02
43	1	5.0000000000E+02	44	1	6.0000000000E+00
45	0	0.	46	0	0.
47	0	0.	48	0	0.
49	0	0.	50	0	0.
51	1	1.0000000000E+00	52	0	0.
53	0	0.	54	0	0.
55	0	0.	56	1	1.2700000000E-04
57	0	0.	58	0	0.
59	0	0.	60	0	0.
61	1	1.0000000000E+00	62	1	2.2000000000E+01
63	1	7.2000000000E+02	64	1	-0.
65	1	-0.	66	1	2.0480000000E+03
67	1	6.4000000000E+01	68	1	1.5000000000E+06
69	1	1.0000000000E+00	70	0	0.
71	0	0.	72	0	0.
73	0	0.	74	0	0.
75	0	0.	76	0	0.
77	0	0.	78	0	0.
79	0	0.	80	0	0.
81	1	1.0000000000E+00	82	1	1.0000000000E+00
83	0	0.	84	0	0.
85	0	0.	86	1	1.5000000000E+01
87	0	0.	88	0	0.
89	0	0.	90	1	1.1111110000E+06
91	0	0.	92	0	0.
93	0	0.	94	0	0.
95	0	0.	96	0	0.

Table A-22 Additional Camera Specifications

JUPITER CHECK OUT CASE NO 8

## TV CHARACTERISTICS FOR PIONEER SIT CAMERA

6	FOC LN=	2.54000000E+01	USER INPUT
7	DIAM =	1.51200000E+01	USER INPUT
8	OBSCUR=	0.	
9	TRANS =	8.50000000E-01	
10	SIZE-V=	2.50000000E+00	USER INPUT
11	SIZE-H=	2.50000000E+00	USER INPUT
12	LINES =	5.00000000E+02	USER INPUT
13	PIXELS=	5.00000000E+02	USER INPUT
14	BIT/PX=	6.00000000E+00	USER INPUT
15	MINEXP=	8.00000000E-06	
16	MAXEXP=	2.00000000E-03	
17	RESO-1=	3.00000000E+02	
18	RESO-2=	1.00000000E+02	
19	RESO-3=	5.00000000E+01	
20	RESO-4=	1.00000000E+01	
21	SENSOR=	1.00000000E+00	USER INPUT
22	B FILT=	1.00000000E+00	
23	G FILT=	1.00000000E+00	
24	R FILT=	1.00000000E+00	
25	P FILT=	-1.00000000E+00	
26	DT EXP=	1.27000000E-04	USER INPUT
27	OPEN =	0.	
28	OPEN =	0.	
29	T READ=	4.00000000E+01	
30	ERASET=	1.00000000E-01	
31	TSTART=	1.00000000E+00	USER INPUT
32	TSTOP =	2.20000000E+01	USER INPUT
33	DEL T =	7.20000000E+02	USER INPUT
34	BULK =	-0.	USER INPUT
35	BULK-0=	-0.	USER INPUT
36	BITRAT=	2.04800000E+03	USER INPUT
37	SCIBPS=	6.40000000E+01	USER INPUT
38	BUFFER=	1.50000000E+06	USER INPUT
39	PIC/ST=	1.00000000E+00	USER INPUT
40	DEL TF=	7.20000000E+02	
41	F/STOP=	1.67989418E+00	COMPUTED VALUES
42	A BLOC=	0.	COMPUTED VALUES
43	DIF LM=	4.43783069E-06	COMPUTED VALUES
44	FOV-V =	5.63480713E+00	COMPUTED VALUES
45	FOV-H =	5.63480713E+00	COMPUTED VALUES
46	RES-C =	1.96850406E-04	COMPUTED VALUES
47	RES-V =	1.25061309E-04	COMPUTED VALUES
48	RES-H =	1.25061309E-04	COMPUTED VALUES
49	BIT/PC=	1.50000000E+06	COMPUTED VALUES
50	RR-BPS=	3.75000000E+04	COMPUTED VALUES
51	T/NUM =	1.82210107E+00	COMPUTED VALUES
52	T/NUMF=	1.82210107E+00	COMPUTED VALUES
53	OPEN =	0.	COMPUTED VALUES
54	OPEN =	0.	COMPUTED VALUES
55	OPEN =	0.	COMPUTED VALUES
56	OPEN =	0.	COMPUTED VALUES
57	OPEN =	0.	COMPUTED VALUES
58	OPEN =	0.	COMPUTED VALUES
59	OPEN =	0.	COMPUTED VALUES
60	OPEN =	0.	COMPUTED VALUES

Table A-22 (cont)

## JUPITER CHECK OUT CASE NO 8

## TV ENERGY DATA FOR PIONEER SIT CAMERA

## PLANET 5 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO(W/SQCM)	BEFF(W/SQCM)
.2500	.0070	.3030	0	1.0000	5.250000E-05	0.
.2750	.0204	.2320	.0020	1.0000	1.438200E-04	2.876400E-07
.3000	.0514	.2700	.0950	1.0000	3.469500E-04	3.296025E-05
.3250	.0971	.2550	.4760	1.0000	6.432875E-04	3.062043E-04
.3500	.1093	.2690	.7620	1.0000	7.350425E-04	5.601024E-04
.3750	.1157	.2720	.9530	1.0000	7.867600E-04	7.497823E-04
.4000	.1429	.2850	.9840	1.0000	1.018162E-03	1.001572E-03
.4250	.1693	.3150	1.0000	1.0000	1.333237E-03	1.333237E-03
.4500	.2006	.3630	.9340	1.0000	1.825460E-03	1.736253E-03
.4750	.2044	.3350	.9530	1.0000	1.967350E-03	1.874985E-03
.5000	.1942	.4060	.7940	1.0000	1.971130E-03	1.565077E-03
.5250	.1552	.4300	.7620	1.0000	1.990900E-03	1.517066E-03
.5500	.1725	.4500	.6820	1.0000	1.940625E-03	1.323506E-03
.5750	.1719	.4600	.5550	1.0000	1.976950E-03	1.097152E-03
.6000	.1666	.4650	.4760	1.0000	1.936725E-03	9.213411E-04
.6250	.1586	.4630	.4450	1.0000	1.853585E-03	8.275153E-04
.6500	.1511	.4700	.3600	1.0000	1.775925E-03	6.391530E-04
.6750	.1442	.4630	.2540	1.0000	1.690745E-03	4.294492E-04
.7000	.1369	.4530	.2060	1.0000	1.567505E-03	3.223060E-04
.7250	.1302	.4400	.1590	1.0000	1.432200E-03	2.277198E-04
.7500	.1235	.4100	.0950	1.0000	1.265875E-03	1.202581E-04
.7750	.1171	.3900	.0400	1.0000	1.112450E-03	4.443800E-05
.8000	.1107	.3550	.0240	1.0000	9.824625E-04	3.579100E-05
.8250	.1048	.3300	.0100	1.0000	8.646000E-04	8.646000E-06
.8500	.0988	.3150	.0030	1.0000	7.780500E-04	2.334150E-06
.8750	.0939	.3000	.0220	1.0000	7.042500E-04	1.549350E-05
.9000	.0889	.2820	0	1.0000	6.267450E-04	0.
.9250	.0862	.2640	0	1.0000	5.689200E-04	0.
.9500	.0835	.2430	0	1.0000	5.135250E-04	0.
.9750	.0791	.2320	0	1.0000	4.587800E-04	0.
1.0000	.0746	.2220	0	1.0000	4.140300E-04	0.

## JUPITER CHECK OUT CASE NO 8

## TV ENERGY DATA FOR PIONEER SIT CAMERA

## SATELLITE 1 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO(W/SQCM)	BEFF(W/SQCM)
.2500	.0070	.0450	0	1.0000	3.150000E-05	0.
.2750	.0204	.0500	.0020	1.0000	1.020000E-04	2.040000E-07
.3000	.0514	.0550	.0950	1.0000	2.827000E-04	2.685650E-05
.3250	.0971	.0600	.4760	1.0000	5.826000E-04	2.773176E-04
.3500	.1093	.0650	.7620	1.0000	7.104500E-04	5.413629E-04
.3750	.1157	.0700	.9530	1.0000	8.099000E-04	7.713347E-04
.4000	.1429	.0750	.9840	1.0000	1.071750E-03	1.054602E-03
.4250	.1693	.0800	1.0000	1.0000	1.354400E-03	1.354400E-03
.4500	.2006	.0850	.9840	1.0000	1.705100E-03	1.677818E-03
.4750	.2044	.1000	.9530	1.0000	2.044000E-03	1.947932E-03
.5000	.1942	.1050	.7940	1.0000	2.039100E-03	1.619045E-03
.5250	.1852	.1130	.7620	1.0000	2.092760E-03	1.594683E-03
.5500	.1725	.1200	.6820	1.0000	2.070000E-03	1.411740E-03
.5750	.1719	.1250	.5550	1.0000	2.148750E-03	1.192556E-03
.6000	.1666	.1300	.4760	1.0000	2.165800E-03	1.030921E-03
.6250	.1586	.1350	.4450	1.0000	2.141100E-03	9.527895E-04
.6500	.1511	.1450	.3600	1.0000	2.190350E-03	7.887420E-04
.6750	.1442	.1530	.2540	1.0000	2.235100E-03	5.677154E-04
.7000	.1369	.1630	.2060	1.0000	2.258850E-03	4.653231E-04
.7250	.1302	.1700	.1590	1.0000	2.213400E-03	3.513306E-04
.7500	.1235	.1750	.0950	1.0000	2.161250E-03	2.153187E-04
.7750	.1171	.1800	.0400	1.0000	2.107300E-03	3.431200E-05
.8000	.1107	.1850	.0240	1.0000	2.047950E-03	4.915080E-05
.8250	.1048	.2900	.0100	1.0000	3.039200E-03	3.039200E-05
.8500	.0988	.2950	.0030	1.0000	2.914600E-03	8.743600E-06
.8750	.0939	.2000	.0220	1.0000	1.878000E-03	4.131600E-05
.9000	.0889	.2000	0	1.0000	1.778000E-03	0.
.9250	.0862	.2000	0	1.0000	1.724000E-03	0.
.9500	.0835	.2050	0	1.0000	1.711750E-03	0.
.9750	.0791	.2080	0	1.0000	1.645280E-03	0.
1.0000	.0746	.2100	0	1.0000	1.566600E-03	0.

Table A-22 (cont)

## JUPITER CHECK OUT CASE NO 8

## TV ENERGY DATA FOR PIONEER SIT CAMERA

## SATELLITE 2 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF (W/SQCM)
.2500	.0070	.0450	0	1.0000	3.150000E-05	0.
.2750	.0204	.0500	.0020	1.0000	1.020000E-04	2.040000E-07
.3000	.0514	.0550	.0950	1.0000	2.827000E-04	2.689550E-05
.3250	.0971	.0600	.4760	1.0000	5.826000E-04	2.773176E-04
.3500	.1093	.0650	.7620	1.0000	7.104500E-04	5.413629E-04
.3750	.1157	.0700	.9530	1.0000	8.399000E-04	7.713347E-04
.4000	.1429	.0750	.9840	1.0000	1.071750E-03	1.054602E-03
.4250	.1693	.0800	1.0000	1.0000	1.354400E-03	1.354400E-03
.4500	.2006	.0850	.9840	1.0000	1.705100E-03	1.677818E-03
.4750	.2044	.1000	.9530	1.0000	2.044000E-03	1.947932E-03
.5000	.1942	.1050	.7940	1.0000	2.039100E-03	1.619045E-03
.5250	.1852	.1130	.7620	1.0000	2.092760E-03	1.594683E-03
.5500	.1725	.1200	.6820	1.0000	2.070000E-03	1.411740E-03
.5750	.1719	.1250	.5550	1.0000	2.143750E-03	1.192556E-03
.6000	.1666	.1300	.4760	1.0000	2.165800E-03	1.033921E-03
.6250	.1586	.1350	.4450	1.0000	2.141100E-03	9.527835E-04
.6500	.1511	.1450	.3600	1.0000	2.190950E-03	7.887420E-04
.6750	.1442	.1550	.2540	1.0000	2.235100E-03	5.677154E-04
.7000	.1369	.1650	.2060	1.0000	2.258850E-03	4.653231E-04
.7250	.1302	.1700	.1590	1.0000	2.213400E-03	3.513306E-04
.7500	.1235	.1750	.0950	1.0000	2.161250E-03	2.653187E-04
.7750	.1171	.1800	.0400	1.0000	2.107300E-03	8.431206E-05
.8000	.1107	.1850	.0240	1.0000	2.047950E-03	4.915030E-05
.8250	.1048	.2900	.0100	1.0000	3.039200E-03	3.039200E-05
.8500	.0988	.2950	.0030	1.0000	2.914600E-03	8.743300E-06
.8750	.0939	.2000	.0220	1.0000	1.878000E-03	4.131606E-05
.9000	.0889	.2000	0	1.0000	1.778000E-03	0.
.9250	.0862	.2000	0	1.0000	1.724000E-03	0.
.9500	.0835	.2050	0	1.0000	1.711750E-03	0.
.9750	.0791	.2030	0	1.0000	1.645280E-03	0.
1.0000	.0746	.2130	0	1.0000	1.566600E-03	0.

## JUPITER CHECK OUT CASE NO 8

## TV ENERGY DATA FOR PIONEER SIT CAMERA

## SATELLITE 3 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF (W/SQCM)
.2500	.0070	.0450	0	1.0000	1.567125E-05	0.
.2750	.0204	.0500	.0020	1.0000	5.074500E-05	1.014900E-07
.3000	.0514	.0550	.0950	1.0000	1.406432E-04	1.336111E-05
.3250	.0971	.0600	.4760	1.0000	2.898435E-04	1.373655E-04
.3500	.1093	.0650	.7620	1.0000	3.534489E-04	2.693280E-04
.3750	.1157	.0700	.9530	1.0000	4.029252E-04	3.833878E-04
.4000	.1429	.0750	.9840	1.0000	5.331956E-04	5.246645E-04
.4250	.1693	.0800	1.0000	1.0000	6.738140E-04	6.738140E-04
.4500	.2006	.0850	.9840	1.0000	8.482872E-04	8.347147E-04
.4750	.2044	.1000	.9530	1.0000	1.016890E-03	9.690362E-04
.5000	.1942	.1050	.7940	1.0000	1.014452E-03	8.054751E-04
.5250	.1852	.1130	.7620	1.0000	1.041148E-03	7.933549E-04
.5500	.1725	.1200	.6820	1.0000	1.029825E-03	7.023606E-04
.5750	.1719	.1250	.5550	1.0000	1.069003E-03	5.932967E-04
.6000	.1666	.1300	.4760	1.0000	1.077485E-03	5.123331E-04
.6250	.1586	.1350	.4450	1.0000	1.065197E-03	4.740128E-04
.6500	.1511	.1450	.3600	1.0000	1.089998E-03	3.923391E-04
.6750	.1442	.1550	.2540	1.0000	1.111962E-03	2.824384E-04
.7000	.1369	.1650	.2060	1.0000	1.123778E-03	2.314982E-04
.7250	.1302	.1700	.1590	1.0000	1.101166E-03	1.750855E-04
.7500	.1235	.1750	.0950	1.0000	1.075222E-03	1.021461E-04
.7750	.1171	.1800	.0400	1.0000	1.048630E-03	4.194522E-05
.8000	.1107	.1850	.0240	1.0000	1.018855E-03	2.445252E-05
.8250	.1048	.2900	.0100	1.0000	1.512002E-03	1.512002E-05
.8500	.0988	.2950	.0030	1.0000	1.450013E-03	4.350040E-06
.8750	.0939	.2000	.0220	1.0000	9.343050E-04	2.055471E-05
.9000	.0889	.2000	0	1.0000	8.845550E-04	0.
.9250	.0862	.2000	0	1.0000	8.576900E-04	0.
.9500	.0835	.2050	0	1.0000	8.515956E-04	0.
.9750	.0791	.2030	0	1.0000	8.185268E-04	0.
1.0000	.0746	.2100	0	1.0000	7.793835E-04	0.

Table A-22 (cont)

## JUPITER CHECK OUT CASE NO 8

## TV ENERGY DATA FOR PIONEER SIX CAMERA

## SATELLITE 4 DATA

MICRONS	SOLAR	ALREDO	SENSOR	FILTER	BO (W/SQCM)	DEFF (W/SQCM)
.2500	.0070	.0450	0	1.0000	1.779750E-05	0.
.2750	.0204	.0530	.0020	1.0000	5.763000E-05	1.152600E-07
.3000	.0514	.0550	.0950	1.0000	1.597255E-04	1.517392E-05
.3250	.0371	.0530	.4760	1.0000	3.291690E-04	1.566844E-04
.3500	.1093	.0650	.7620	1.0000	4.014042E-04	3.053700E-04
.3750	.1157	.0700	.9530	1.0000	4.575335E-04	4.360866E-04
.4000	.1429	.0750	.9840	1.0000	6.055387E-04	5.953501E-04
.4250	.1693	.0800	1.0000	1.0000	7.652360E-04	7.652360E-04
.4500	.2006	.0850	.9840	1.0000	9.633315E-04	9.473574E-04
.4750	.2044	.1000	.9530	1.0000	1.154360E-03	1.100582E-03
.5000	.1342	.1050	.7940	1.0000	1.152091E-03	9.147507E-04
.5250	.1852	.1130	.7620	1.0000	1.182409E-03	9.003360E-04
.5500	.1725	.1200	.6820	1.0000	1.169550E-03	7.976331E-04
.5750	.1719	.1250	.5550	1.0000	1.214444E-03	6.737943E-04
.6000	.1666	.1300	.4760	1.0000	1.223677E-03	5.824703E-04
.6250	.1586	.1350	.4450	1.0000	1.209721E-03	5.343261E-04
.6500	.1511	.1400	.3600	1.0000	1.237487E-03	4.455392E-04
.6750	.1442	.1550	.2540	1.0000	1.262931E-03	3.207592E-04
.7000	.1369	.1650	.2060	1.0000	1.276256E-03	2.623076E-04
.7250	.1342	.1700	.1590	1.0000	1.250571E-03	1.933403E-04
.7500	.1235	.1750	.0950	1.0000	1.221106E-03	1.150051E-04
.7750	.1171	.1800	.0400	1.0000	1.190907E-03	4.763628E-05
.8000	.1107	.1850	.0240	1.0000	1.157092E-03	2.777320E-05
.8250	.1048	.2900	.0100	1.0000	1.717148E-03	1.717148E-05
.8500	.0938	.2950	.0030	1.0000	1.646749E-03	4.943247E-06
.8750	.0939	.2000	.0220	1.0000	1.061070E-03	2.334354E-05
.9000	.0889	.2000	0	1.0000	1.004570E-03	0.
.9250	.0862	.2000	0	1.0000	3.740600E-04	0.
.9500	.0835	.2050	0	1.0000	3.671387E-04	0.
.9750	.0791	.2030	0	1.0000	3.295832E-04	0.
1.0000	.0746	.2100	0	1.0000	3.851299E-04	0.

## JUPITER CHECK OUT CASE NO 8

## COMPUTATIONS FOR MINIMUM PICTURE TAKING INTERVAL

PICTURE START TIME (DAYS) = 1.00000000E+00  
 PICTURE STOP TIME (DAYS) = 2.20000000E+01  
 DELTA T REQUESTED (SEC) = 4.32000000E+04  
 FRAME READ TIME (SEC) = 4.00000000E+01  
 FRAME READ RATE (BPS) = 3.75000000E+04

BULK DATA STORAGE CAPACITY (BITS) = 0.  
 PICTURE SIZE (BITS) = 1.50000000E+06  
 BULK DATA STORAGE CAPACITY (PICS) = 0.  
 BULK CONTENTS IN USE (BITS) = 0.  
 BUFFER STORAGE CAPACITY (BITS) = 1.50000000E+06

DATA TRANSMISSION RATE (BPS) = 2.04800000E+03  
 RATE FROM OTHER INSTRUMENTS (BPS) = 6.40000000E+01  
 REAL TIME PICTURE RATE (BPS) = 1.98400000E+03

PICTURE INTERVAL BASED ON ROLL RATE = 3.60000304E+04 SEC, NO OF ROLLS/PIC = 1

MINIMUM PICTURE INTERVAL (SEC) = 3.60000304E+04  
 MAXIMUM PICTURE RATE (PICS/HR) = 9.39999155E-02  
 MAXIMUM PICTURE RATE (PIC/DAY) = 2.39999797E+00  
 MAXIMUM NUMBER OF PICTURES = 50  
 ACTUAL PICTURE RATE (PIC/DAY) = 2.09000000E+00  
 ACTUAL NUMBER OF PICTURES = 41

PERIAPSIS STATE VECTOR  
 -1.55815045E+05      -4.33051226E+04      3.07916842E+02  
 9.75526852E+00      -3.77127648E+01      0.  
 VIEW FROM INPUT VIEWPOINT

Table A-22 (concl)

## JUPITER CHECK OUT CASE NO 8

PLOT INTERVAL = 1 CALC STEPS = 720.00 MINUTES  
 PRNT INTERVAL = 1 CALC STEPS = 720.00 MINUTES

TIME INTERVAL FOR CALCULATIONS = 720.00 MINUTES

PICTURE	CALC	TIME (DAYS)	TIME (HRS)	TIME (MIN)
1	1	1.000000E+00	2.400000E+01	1.440000E+03
2	2	1.500000E+00	3.600000E+01	2.160000E+03
3	3	2.000000E+00	4.800000E+01	2.880000E+03
4	4	2.500000E+00	6.000000E+01	3.600000E+03
5	5	3.000000E+00	7.200000E+01	4.320000E+03
6	6	3.500000E+00	8.400000E+01	5.040000E+03
7	7	4.000000E+00	9.600000E+01	5.760000E+03
8	8	4.500000E+00	1.080000E+02	6.480000E+03
9	9	5.000000E+00	1.200000E+02	7.200000E+03
10	10	5.500000E+00	1.320000E+02	7.920000E+03
11	11	6.000000E+00	1.440000E+02	8.640000E+03
12	12	6.500000E+00	1.560000E+02	9.360000E+03
13	13	7.000000E+00	1.680000E+02	1.008000E+04
14	14	7.500000E+00	1.800000E+02	1.080000E+04
15	15	8.000000E+00	1.920000E+02	1.152000E+04
16	16	8.500000E+00	2.040000E+02	1.224000E+04
17	17	9.000000E+00	2.160000E+02	1.296000E+04
18	18	9.500000E+00	2.280000E+02	1.368000E+04
19	19	1.000000E+01	2.400000E+02	1.440000E+04
20	20	1.050000E+01	2.520000E+02	1.512000E+04
21	21	1.100000E+01	2.640000E+02	1.584000E+04
22	22	1.150000E+01	2.760000E+02	1.656000E+04
23	23	1.200000E+01	2.880000E+02	1.728000E+04
24	24	1.250000E+01	3.000000E+02	1.800000E+04
25	25	1.300000E+01	3.120000E+02	1.872000E+04
26	26	1.350000E+01	3.240000E+02	1.944000E+04
27	27	1.400000E+01	3.360000E+02	2.016000E+04
28	28	1.450000E+01	3.480000E+02	2.088000E+04
29	29	1.500000E+01	3.600000E+02	2.160000E+04
30	30	1.550000E+01	3.720000E+02	2.232000E+04
31	31	1.600000E+01	3.840000E+02	2.304000E+04
32	32	1.650000E+01	3.960000E+02	2.376000E+04
33	33	1.700000E+01	4.080000E+02	2.448000E+04
34	34	1.750000E+01	4.200000E+02	2.520000E+04
35	35	1.800000E+01	4.320000E+02	2.592000E+04
36	36	1.850000E+01	4.440000E+02	2.664000E+04
37	37	1.900000E+01	4.560000E+02	2.736000E+04
38	38	1.950000E+01	4.680000E+02	2.808000E+04
39	39	2.000000E+01	4.800000E+02	2.880000E+04
40	40	2.050000E+01	4.920000E+02	2.952000E+04
41	41	2.100000E+01	5.040000E+02	3.024000E+04
42	42	2.150000E+01	5.160000E+02	3.096000E+04
43	43	2.200000E+01	5.280000E+02	3.168000E+04
44	44	2.250000E+01	5.400000E+02	3.240000E+04
45	45	2.300000E+01	5.520000E+02	3.312000E+04
46	46	2.350000E+01	5.640000E+02	3.384000E+04
47	47	2.400000E+01	5.760000E+02	3.456000E+04

JUPITER CHECK OUT CASE NO 8  
 PIONEER SIT CAMERA

EXPOSURE TOO HIGH 9.535E-02 (ERGS/CM\*\*2)  
 EXPOSURE TIME REDUCED TO 2.266E-06 SEC  
 EXPOSURE IS 1.701E-03 (ERG/CM\*\*2)  
 CHG 1  
 EXPOSURE TIME SET TO 0.1 MILLISEC  
 REQUIRED FILTER FACTOR IS 4.413E+01  
 CHG 1  
 VIEW FROM SPACECRAFT

b. Output Data - For this Jupiter orbiter case, several frames were selected to show geometry near periapsis, midway, and near apoapsis. Table A-23 presents the tabular output for the frames selected. Several satellites are shown on the frames along with the main planet.

The graphic output shows the orbit frames selected (Fig. A-19); the case time interval was run for slightly greater than one orbit. The overview plot (Fig. A-20) shows that the start time was at periapsis. In addition to geometry, several analysis plots summarize resolution of Jupiter and satellites, number of pixels smeared, and number of pictures within specified resolution levels for Jupiter and satellites (Fig. A-21).



Table A-23 Case 8 Tabular Output

JUPITER CHECK OUT CASE NO 8

PICTURE NUMBER 5 3 DAYS 0 HRS 0 MIN TO ENCOUNTER JD 2445734.500

PLANET JUPITE	SATELLITE CALLI
RANGE (KM) = 2.66269379E+06	RANGE (KM) = 1.19239507E+06
CONE (DEG) = 84.10	CONE (DEG) = 46.28
CLOCK (DEG) = 87.14	CLOCK (DEG) = 90.60
PHASE (DEG) = 88.63	PHASE (DEG) = 126.46
DIAM (DEG) = 3.07	DIAM (DEG) = .23

## RESOLUTION OF PLANET

CENTER = 510.10 KM/PIXEL  
 LIMB = 523.96 KM/PIXEL

INSTRUMENT DATA FOR PLANET JUPITE

(PICTURE CENTERED AT -.83 DEG LAT 130.07 DEG LONG )

RESOLUTION AT SPECIFIED LOCATION = 510.10 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 10.30 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 588.04 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .36 KM  
 NUMBER OF PIXELS SMEARED .00012 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 427.376 MILLISEC

## EFFECTIVE RESOLUTION WITH SMEAR

AT SPECIFIED LOCATION 510.2 KM/PIXEL  
 AT SUBSPACECRAFT POINT 510.2 KM/PIXEL  
 AT LIMB OF TARGET BODY 524.0 KM/PIXEL

EXPOSURE TIME FOR PIONEER SIT CAMERA = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 2.0449E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.7012E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 85.000  
 DIGITAL NUMBER OF EXPOS = 54 (OF 64 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 3.1125E-05 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN  
 RESOLUTION LEVELS 300.0 100.0 50.0 10.0 KM/PIXEL

	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	1.0	0.	0.	0.	*
SATELLITE 1	1.0000	0.	0.	0.	
SATELLITE 2	2.0000	0.	0.	0.	
SATELLITE 3	0.	0.	0.	0.	
SATELLITE 4	5.0000	2.0000	1.0000	0.	

## SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	2.85040788E+06	80.74	91.99	86.76
2	3.18056131E+06	96.97	75.76	87.45
3	3.72563611E+06	90.91	81.82	87.05
4	1.19239507E+06	126.46	46.28	90.60

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	8.07429149E+01	6.71370283E-02
2	9.69706902E+01	5.26019358E-02
3	9.09100043E+01	7.84318409E-02
4	1.26460415E+02	2.26686818E-01

## RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	5.60775210E+02	5.61103853E+02
2	6.25807386E+02	6.26094721E+02
3	7.32891013E+02	7.33392810E+02
4	2.34376997E+02	2.34841104E+02

## SMEAR DATA FOR SATELLITES

SMEAR DUE TO VEL (KM/SEC)	SMEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
1.02079370E+01	6.97139128E+02	1.25563682E-04	3.98204314E-01
1.44858817E+01	6.62074560E+02	1.07724596E-04	4.64146555E-01
1.34111532E+01	8.24296713E+02	1.13886635E-04	4.39033078E-01
1.37585854E+00	2.10885749E+02	9.05576683E-05	5.52134357E-01

VIEW FROM SPACECRAFT

Table A-23 (cont)

## JUPITER CHECK OUT CASE NO 8

PICTURE NUMBER 13 7 DAYS 0 HRS 0 MIN TO ENCOUNTER JD 2445736.500

PLANET JUPITE	SATELLITE CALLI
RANGE (KM) = 3.34298327E+06	RANGE (KM) = 4.61086320E+06
CONE (DEG) = 94.37	CONE (DEG) = 70.44
CLOCK (DEG) = 87.31	CLOCK (DEG) = 88.12
PHASE (DEG) = 77.82	PHASE (DEG) = 101.75
DIAM (DEG) = 2.07	DIAM (DEG) = .06

## RESOLUTION OF PLANET

CENTER = 762.13 KM/PIXEL  
 LIMB = 776.05 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITE (PICTURE CENTERED AT -1.22 DEG LAT 229.60 DEG LONG )

RESOLUTION AT SPECIFIED LOCATION = 762.13 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 11.07 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 971.85 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .10 KM  
 NUMBER OF PIXELS SMEARED .00013 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 389.016 MILLISEC

## EFFECTIVE RESOLUTION WITH SMEAR

AT SPECIFIED LOCATION 762.2 KM/PIXEL  
 AT SUBSPACECRAFT POINT 762.2 KM/PIXEL  
 AT LIMB OF TARGET BODY 776.1 KM/PIXEL

EXPOSURE TIME FOR PIONEER SIT CAMERA = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.6151E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.6151E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 80.676  
 DIGITAL NUMBER OF EXPOS = 51 (OF 64 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 3.1125E-05 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	1.0	0.	0.	0.	
SATELLITE 1	1.0000	0.	0.	0.	
SATELLITE 2	2.0000	0.	0.	0.	
SATELLITE 3	0.	0.	0.	0.	
SATELLITE 4	5.0000	2.0000	1.0000	0.	

## SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	3.58308793E+06	74.50	97.69	87.31
2	4.60161687E+06	79.07	93.12	87.19
3	2.87364462E+06	78.66	93.53	87.71
4	4.61086320E+06	101.75	70.44	88.12

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	7.45021165E+01	5.34086559E-02
2	7.90687476E+01	3.63575855E-02
3	7.86565142E+01	1.01685682E-01
4	1.01749057E+02	5.86519442E-02

## RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	7.05003576E+02	7.05332239E+02
2	9.05542749E+02	9.05830105E+02
3	5.65176144E+02	5.65677890E+02
4	9.07185728E+02	9.07650176E+02

## SMEAR DATA FOR SATELLITES

SMEAR DUE TO	SMEAR DUE TO	NUMBER OF	TIME TO SMEAR
VEL (KM/SEC)	S/C (KM/SEC)	PIXELS SMEARED	1/2 PIXEL (SEC)
1.31836430E+01	9.24994799E+02	1.29926415E-04	3.84833214E-01
1.53365216E+01	1.14125829E+03	1.27228663E-04	3.92993205E-01
9.23603441E+00	7.18333745E+02	1.25961697E-04	3.96946367E-01
6.66490743E+00	9.15573784E+02	1.01570152E-04	4.32270605E-01

VIEW FROM SPACECRAFT

Table A-23 (cont)

JUPITER CHECK OUT CASE NO 8

PICTURE NUMBER 24 12 DAYS 12 HRS 0 MIN TO ENCOUNTER JD 2445744.900

PLANET JUPITE	SATELLITE CALLI
RANGE (KM) = 4.19284240E+06	RANGE (KM) = 5.93924852E+06
CONE (DEG) = 103.04	CONE (DEG) = 111.33
CLOCK (DEG) = 87.53	CLOCK (DEG) = 86.81
PHASE (DEG) = 68.54	PHASE (DEG) = 60.25
DIAM (DEG) = 1.95	DIAM (DEG) = .05

RESOLUTION OF PLANET  
 CENTER = 811.31 KM/PIXEL  
 LIMB = 825.24 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITE (PICTURE CENTERED AT -1.51 DEG LAT 90.87 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 811.31 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES = 11.16 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES = 1109.46 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES = .11 KM  
 NUMBER OF PIXELS SMEARED = .00014 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 363.250 MILLISEC

EFFECTIVE RESOLUTION WITH SMEAR  
 AT SPECIFIED LOCATION 311.4 KM/PIXEL  
 AT SUBSPACECRAFT POINT 811.4 KM/PIXEL  
 AT LIMB OF TARGET BODY 825.4 KM/PIXEL

EXPOSURE TIME FOR PIONEER SIT CAMERA = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.5349E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.5349E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 76.652  
 DIGITAL NUMBER OF EXPOS = 49 (OF 64 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 3.1125E-05 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN	RESOLUTION LEVELS					KM/PIXEL
	300.0	100.0	50.0	10.0		
PLANET	1.0	0.	0.	0.	0.	
SATELLITE 1	1.0000	0.	0.	0.	0.	
SATELLITE 2	2.0000	0.	0.	0.	0.	
SATELLITE 3	0.	0.	0.	0.	0.	
SATELLITE 4	5.0000	2.0000	1.0000	0.	0.	

## SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	3.77295651E+06	68.56	103.02	87.70
2	3.51504093E+06	68.44	103.14	87.84
3	4.33942397E+06	54.27	117.31	86.99
4	5.93824852E+06	60.25	111.33	86.81

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	6.85627840E+01	5.07209425E-02
2	6.84429485E+01	4.75965100E-02
3	5.42704908E+01	6.73380833E-02
4	6.02534078E+01	4.55413891E-02

RESOLUTION (KM/PIX) DATA FOR SATELLITES	RES AT SATELLITE LIMB	
NUM	RES ALONG RADIUS VECTOR	
1	7.42379281E+02	7.42707949E+02
2	6.91649834E+02	6.91937176E+02
3	8.53715403E+02	8.54217224E+02
4	1.16848267E+03	1.16894654E+03

SMEAR DATA FOR SATELLITES	SMEAR DUE TO	NUMBER OF	TIME TO SMEAR
SMEAR DUE TO	S/C (KM/SEC)	PIXELS SMEARED	1/2 PIXEL (SEC)
VEL (KM/SEC)			
1.59155790E+01	1.01643258E+03	1.35531639E-04	3.68917413E-01
1.21244141E+01	9.48420615E+02	1.35976872E-04	3.67709590E-01
4.51957831E+00	1.26178601E+03	1.48089132E-04	3.37634499E-01
9.40183897E+00	1.67743003E+03	1.44043253E-04	3.47117959E-01

VIEW FROM SPACECRAFT

Table A-23 (cont)

JUPITER CHECK OUT CASE 40 8

PICTURE NUMBER 33 17 DAYS 0 HRS 0 MIN TO ENCOUNTER JD 2445748.500

PLANET JUPITE	SATELLITE CALLI
RANGE (KM) = 3.22745354E+06	RANGE (KM) = 2.99044792E+06
CONE (DEG) = 112.07	CONE (DEG) = 146.80
CLOCK (DEG) = 87.67	CLOCK (DEG) = 85.81
PHASE (DEG) = 59.12	PHASE (DEG) = 24.40
DIAM (DEG) = 2.53	DIAM (DEG) = .09

RESOLUTION OF PLANET  
 CENTER = 621.28 KM/PIXEL  
 LIMB = 635.17 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITE (PICTURE CENTERED AT -1.77 DEG LAT 110.10 DEG LONG )

RESOLUTION AT SPECIFIED LOCATION = 621.28 KM/PIXEL  
 SHEAR DUE TO RELATIVE VELOCITIES = 10.71 KM/SEC  
 SHEAR DUE TO S/C ATTITUDE RATES = 897.75 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES = .09 KM  
 NUMBER OF PIXELS SMEARED = .00015 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SHEAR 343.482 MILLISEC

EFFECTIVE RESOLUTION WITH SHEAR  
 AT SPECIFIED LOCATION 621.4 KM/PIXEL  
 AT SUBSPACECRAFT POINT 621.4 KM/PIXEL  
 AT LIMB OF TARGET BODY 635.3 KM/PIXEL

EXPOSURE TIME FOR PIONEER SIT CAMERA = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.4487E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.4487E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 72.323  
 DIGITAL NUMBER OF EXPOS = 46 (OF 64 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 3.1125E-05 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN RESOLUTION LEVELS	RESOLUTION LEVELS				KM/PIXEL
	300.0	100.0	50.0	10.0	
PLANET	1.0	0.	0.	0.	
SATELLITE 1	1.0000	0.	0.	0.	
SATELLITE 2	2.0000	0.	0.	0.	
SATELLITE 3	0.	0.	0.	0.	
SATELLITE 4	5.0000	2.0000	1.0000	0.	

SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	3.64362320E+06	58.43	112.77	87.42
2	3.23775087E+06	71.01	100.18	88.15
3	3.95108232E+06	71.81	99.39	87.79
4	2.99044792E+06	24.40	146.80	86.81

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	5.84280903E+01	5.24493486E-02
2	7.10135691E+01	5.16728089E-02
3	7.18057575E+01	7.39565699E-02
4	2.43999492E+01	9.04333111E-02

RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	7.17904220E+02	7.18232885E+02
2	6.37065172E+02	6.37352509E+02
3	7.77276192E+02	7.77771999E+02
4	5.88206322E+02	5.88670706E+02

SHEAR DATA FOR SATELLITES

SHEAR DUE TO VEL (KM/SEC)	SHEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
1.91862732E+01	1.04060414E+03	1.46584976E-04	3.41093076E-01
2.63472248E+00	8.56818946E+02	1.34835516E-04	3.70822180E-01
9.13962438E+00	1.03708316E+03	1.34224043E-04	3.72511504E-01
5.44711330E+00	8.93744593E+02	1.52435754E-04	3.28007038E-01

VIEW FROM SPACECRAFT

Table A-23 (concl)

JUPITER CHECK OUT CASE NO 8

PICTURE NUMBER 41 21 DAYS 0 HRS 0 MIN TO ENCOUNTER JD 2445752.500

PLANET JUPITE	SATELLITE CALLI
RANGE (KM) = 6.24472033E+05	RANGE (KM) = 1.32973119E+06
CONE (DEG) = 155.75	CONE (DEG) = 58.61
CLOCK (DEG) = 87.34	CLOCK (DEG) = 264.38
PHASE (DEG) = 15.25	PHASE (DEG) = 130.33
DIAM (DEG) = 13.13	DIAM (DEG) = .29

RESOLUTION OF PLANET  
 CENTER = 108.88 KM/PIXEL  
 LIMB = 122.12 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITE (PICTURE CENTERED AT -2.21 DEG LAT 242.73 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 103.88 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 2.61 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 160.56 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .02 KM  
 NUMBER OF PIXELS SMEARED .00015 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 335.937 MILLISEC

EFFECTIVE RESOLUTION WITH SMEAR  
 AT SPECIFIED LOCATION 108.9 KM/PIXEL  
 AT SUBSPACECRAFT POINT 108.9 KM/PIXEL  
 AT LIMB OF TARGET BODY 122.1 KM/PIXEL

EXPOSURE TIME FOR PIONEER SIT CAMERA = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.0133E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.0133E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 50.466  
 DIGITAL NUMBER OF EXPOS = 32 (OF 64 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 3.1125E-05 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN	RESOLUTION LEVELS				
	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	3.0	0.	0.	0.	
SATELLITE 1	3.0000	0.	0.	0.	
SATELLITE 2	6.0000	0.	0.	0.	
SATELLITE 3	2.0000	0.	0.	0.	
SATELLITE 4	10.0000	2.0000	1.0000	0.	

SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	9.29926477E+05	6.71	177.56	70.52
2	8.86088816E+05	63.84	107.16	87.92
3	1.11144736E+06	54.58	134.42	267.40
4	1.32873119E+06	130.33	58.61	264.38

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	6.71089378E+00	2.05788319E-01
2	6.38420790E+01	1.88811493E-01
3	5.45769709E+01	2.62908297E-01
4	1.30375269E+02	2.03529670E-01

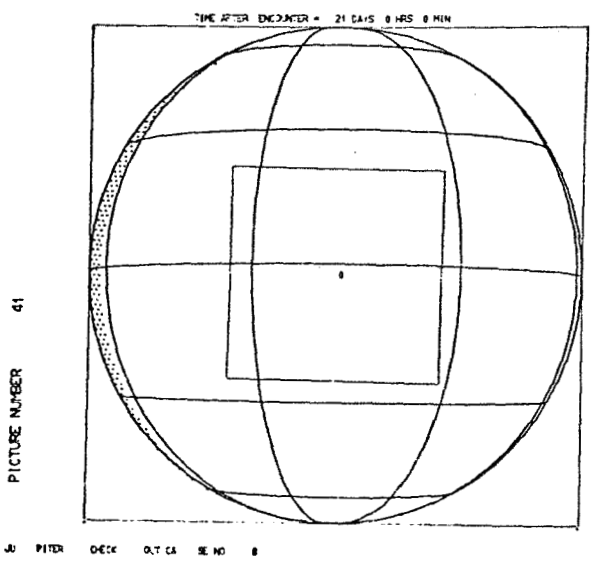
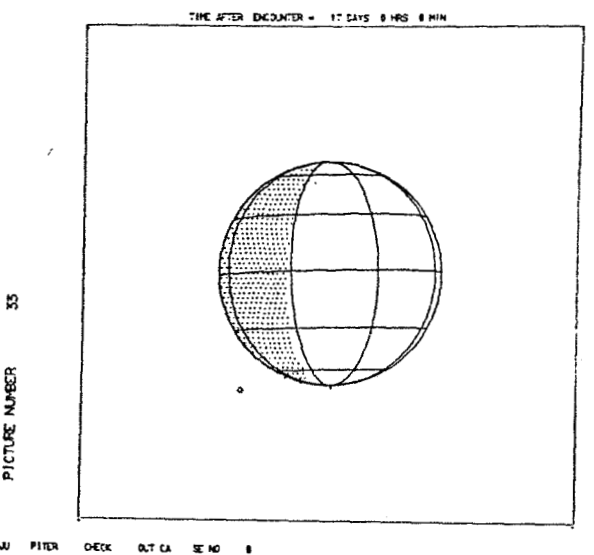
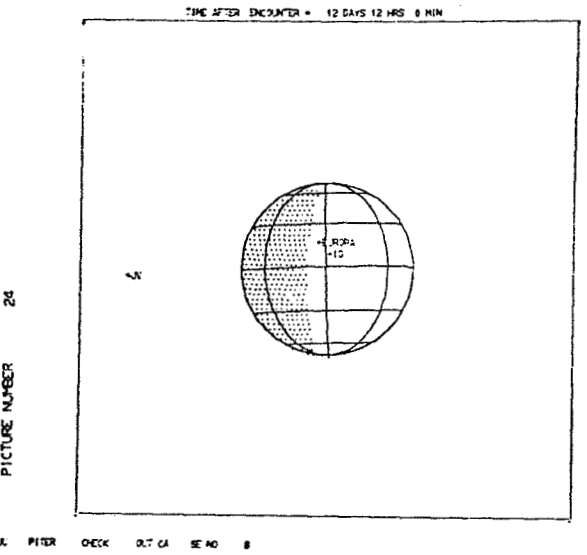
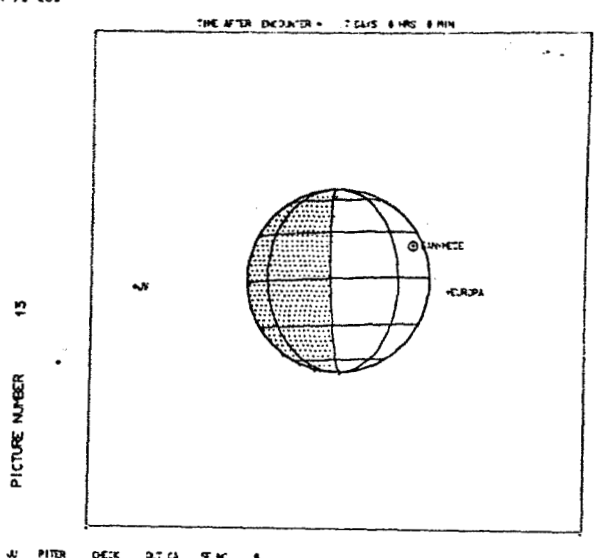
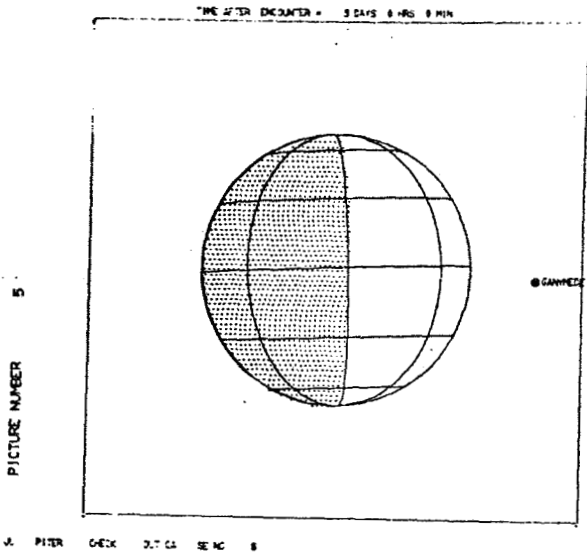
RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	1.82727665E+02	1.83056110E+02
2	1.74139542E+02	1.74426707E+02
3	2.18286890E+02	2.18788288E+02
4	2.61096709E+02	2.61560863E+02

SHEAR DATA FOR SATELLITES

SHEAR DUE TO VEL (KM/SEC)	SHEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
2.96176778E+01	2.35618103E+02	1.40198929E-04	3.56636106E-01
4.76016831E+00	2.45473165E+02	1.42921763E-04	3.49841751E-01
2.73423110E+01	1.85334015E+02	9.74254023E-05	5.13213175E-01
8.66284764E+00	3.90205470E+02	1.51097850E-04	3.30911393E-01

VIEW FROM SPACECRAFT  
 LAT 1, LONG 152 NOT VISIBLE



JUPITER

Fig. A-19 Scenes Before and After Closest Approach

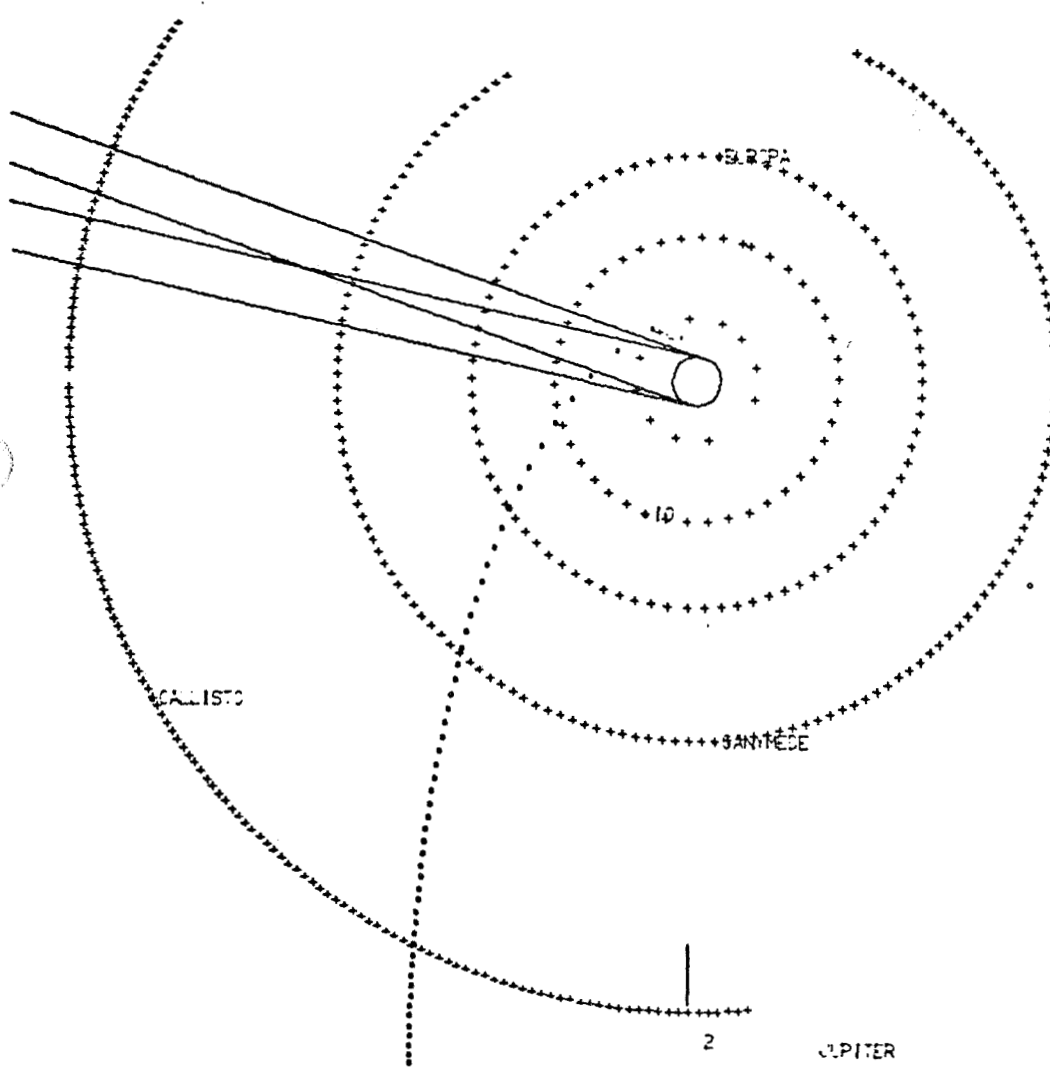


Fig. A-20 Flyby Encounter Geometry

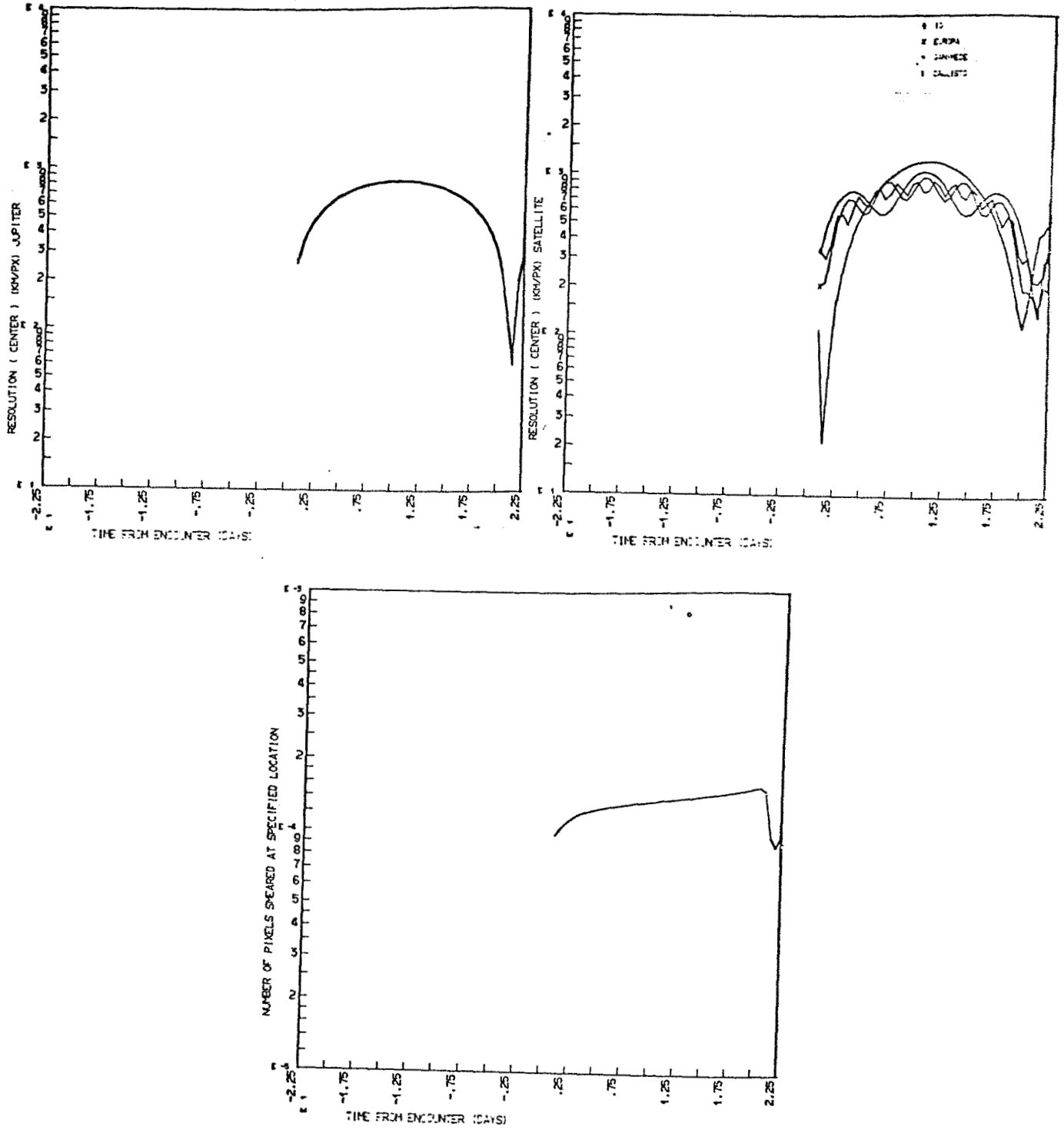


Fig. A-21 TV Summaries



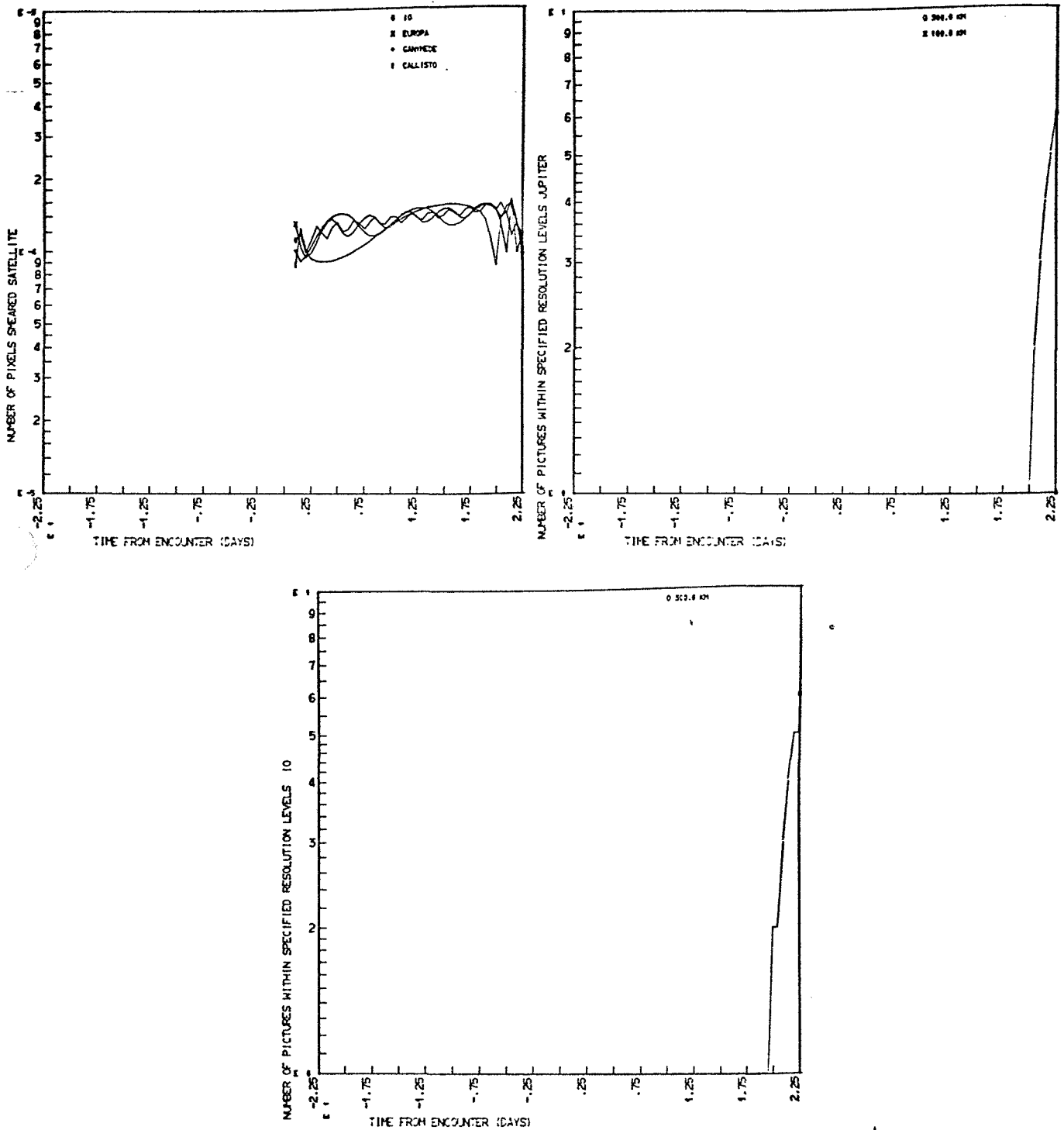


Fig. A-21 (concl)

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4. Case 9

a. Input Data - This case is the Jupiter orbiter mission with a TOPS narrow-angle camera. The input listing is given in Table A-24; narrow-angle camera specifications are given in Table A-25.

Table A-24 Case 9 Input Listing

JUPITER CHECK OUT CASE NO 9

2	5.0000000	PLANET
3	4.0000000	SATEL
4	840201.00	JATE
6	1.0000000E+01	
7	2.2550000	STATE1
8	59.884000	STATE2
9	70.630000	STATE3
22	110.00000	I1STIJ
31	-0.	NAME-1
32	-0.	NAME-2
33	-0.	NAME-3
34	-0.	NAME-4
35	-0.	NAME-5
51	1.0000000	
61	1.0000000	TSTAR
62	22.000000	TSIOP
63	720.00000	JTINST
64	20.0000000E+08	
65	0.	
66	28500.000	3ITRAT
67	640.00000	
68	2000000.0	
69	1.0000000	GALGST
81	1.0000000	3PLOT
82	1.0000000	3PRNT
90	1111111.0	
98		

JUPITER CHECK OUT CASE NO 9

XZ(I) VALUES IN STORAGE

1	0	0.	2	1	5.0000000000E+00
3	1	4.0000000000E+00	4	1	8.4020100000E+05
5	0	0.	6	1	1.0000000000E+01
7	1	2.2550000000E+00	8	1	5.9884000000E+01
9	1	7.0680000000E+01	10	0	0.
11	0	0.	12	0	0.
13	0	0.	14	0	0.
15	0	3.0000000000E+00	16	0	0.
17	0	0.	18	0	0.
19	0	0.	20	0	0.
21	0	0.	22	1	1.1000000000E+02
23	0	0.	24	0	-7.1738305547E+57
25	0	-7.1738305547E+57	26	0	0.
27	0	0.	28	0	0.
29	0	0.	30	0	0.
31	1	-0.	32	1	-0.
33	1	-0.	34	1	-0.
35	1	-0.	36	0	0.
37	0	0.	38	0	0.
39	0	0.	40	0	0.
41	0	0.	42	0	0.
43	0	0.	44	0	0.
45	0	0.	46	0	0.
47	0	0.	48	0	0.
49	0	0.	50	0	0.
51	1	1.0000000000E+00	52	0	0.
53	0	0.	54	0	0.
55	0	0.	56	0	0.
57	0	0.	58	0	0.
59	0	0.	60	0	0.
61	1	1.0000000000E+00	62	1	2.2000000000E+01
63	1	7.2000000000E+02	64	1	2.0000000000E+09
65	1	0.	66	1	2.8500000000E+04
67	1	6.4000000000E+02	68	1	2.0000000000E+06
69	1	1.0000000000E+00	70	0	0.
71	0	0.	72	0	0.
73	0	0.	74	0	0.
75	0	0.	76	0	0.
77	0	0.	78	0	0.
79	0	0.	80	0	0.
81	1	1.0000000000E+00	82	1	1.0000000000E+00
83	0	0.	84	0	0.
85	0	0.	86	0	0.
87	0	0.	88	0	0.
89	0	0.	90	1	1.1111100000E+06
91	0	0.	92	0	0.
93	0	0.	94	0	0.
95	0	0.	96	0	0.

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Table A-25 Narrow-Angle Camera Specifications

JUPITER CHECK OUT CASE NO 9

TV CHARACTERISTICS FOR TOPS NA SIT CAMERA

6	FOC LN=	2.00000000E+02	32	TSTOP =	2.26000000E+01	USER INPUT
7	DIAM =	2.30000000E+01	33	DEL T =	7.20000000E+02	USER INPUT
8	OBSCUR=	0.	34	BULK =	2.00000000E+09	USER INPUT
9	TRANS =	8.50000000E-01	35	BULK-0=	0.	USER INPUT
10	SIZE-V=	1.60000000E+00	36	BITRAT=	2.85000000E+04	USER INPUT
11	SIZE-H=	1.60000000E+00	37	SCIBPS=	6.40000000E+02	USER INPUT
12	LINES =	8.00000000E+02	38	BUFFER=	2.00000000E+06	USER INPUT
13	PIXELS=	8.00000000E+02	39	PIC/ST=	1.00000000E+00	USER INPUT
14	BIT/PX=	8.00000000E+00	40	DEL TF=	7.20000000E+02	
15	MINEXP=	8.00000000E-06	41	F/STOP=	3.69565217E+00	COMPUTED VALUES
16	MAXEXP=	2.00000000E-03	42	A BLOC=	0.	COMPUTED VALUES
17	RESO-1=	3.00000000E+02	43	DIF LM=	2.91739130E-06	COMPUTED VALUES
18	RESO-2=	1.00000000E+02	44	FOV-V =	4.58364179E-01	COMPUTED VALUES
19	RESO-3=	5.00000000E+01	45	FOV-H =	4.58364179E-01	COMPUTED VALUES
20	RESO-4=	1.00000000E+01	46	RES-C =	1.00000000E-05	COMPUTED VALUES
21	SENSOR=	1.00000000E+00	47	RES-V =	8.04209317E-06	COMPUTED VALUES
22	B FILT=	1.00000000E+00	48	RES-H =	8.04209317E-06	COMPUTED VALUES
23	G FILT=	1.00000000E+00	49	BIT/PC=	5.12000000E+06	COMPUTED VALUES
24	R FILT=	1.00000000E+00	50	RR-BPS=	1.28000000E+05	COMPUTED VALUES
25	P FILT=	-1.00000000E+00	51	T/NUM =	9.43175304E+00	COMPUTED VALUES
26	DT EXP=	1.00000000E-03	52	T/NUM=	9.43175304E+00	COMPUTED VALUES
27	OPEN =	0.	53	OPEN =	0.	COMPUTED VALUES
28	OPEN =	0.	54	OPEN =	0.	COMPUTED VALUES
29	T READ=	4.00000000E+01	55	OPEN =	0.	COMPUTED VALUES
30	ERASET=	1.00000000E-01	56	OPEN =	0.	COMPUTED VALUES
31	TSTART=	1.00000000E+00	57	OPEN =	0.	COMPUTED VALUES
			58	OPEN =	0.	COMPUTED VALUES
			59	OPEN =	0.	COMPUTED VALUES
			60	OPEN =	0.	COMPUTED VALUES

JUPITER CHECK OUT CASE NO 9

TV ENERGY DATA FOR TOPS NA SIT CAMERA

PLANET 5 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF (W/SQCM)
.2500	.0070	.3000	0	1.0000	5.250000E-05	0.
.2750	.0204	.2820	.0020	1.0000	1.433200E-04	2.870400E-07
.3100	.0514	.2700	.0950	1.0000	3.469500E-04	3.296025E-05
.3250	.0971	.2650	.4760	1.0000	6.432875E-04	3.062049E-04
.3500	.1093	.2690	.7620	1.0000	7.350425E-04	5.601024E-04
.3750	.1157	.2720	.9530	1.0000	7.867600E-04	7.497823E-04
.4000	.1429	.2850	.9840	1.0000	1.018162E-03	1.001372E-03
.4250	.1693	.3150	1.0000	1.0000	1.333237E-03	1.333237E-03
.4500	.2006	.3640	.9840	1.0000	1.825460E-03	1.796253E-03
.4750	.2044	.3350	.9530	1.0000	1.967350E-03	1.874885E-03
.5000	.1942	.4050	.7940	1.0000	1.971130E-03	1.565077E-03
.5250	.1852	.4300	.7620	1.0000	1.990900E-03	1.517066E-03
.5500	.1725	.4500	.6820	1.0000	1.940625E-03	1.323506E-03
.5750	.1719	.4600	.5550	1.0000	1.976350E-03	1.097152E-03
.6000	.1666	.4650	.4760	1.0000	1.936725E-03	9.213811E-04
.6250	.1586	.4690	.4450	1.0000	1.859585E-03	8.275153E-04
.6500	.1511	.4700	.3600	1.0000	1.775425E-03	6.331530E-04
.6750	.1442	.4630	.2540	1.0000	1.690745E-03	4.294492E-04
.7000	.1369	.4580	.2060	1.0000	1.567505E-03	3.223060E-04
.7250	.1302	.4400	.1590	1.0000	1.432200E-03	2.277193E-04
.7500	.1235	.4100	.0950	1.0000	1.265875E-03	1.202581E-04
.7750	.1171	.3800	.0400	1.0000	1.112450E-03	4.443800E-05
.8000	.1107	.3550	.0240	1.0000	9.824625E-04	2.357910E-05
.8250	.1048	.3300	.0100	1.0000	8.646000E-04	8.646000E-06
.8500	.0988	.3150	.0030	1.0000	7.780500E-04	2.334150E-06
.8750	.0939	.3000	.0220	1.0000	7.042500E-04	1.543350E-05
.9000	.0889	.2820	0	1.0000	6.267450E-04	0.
.9250	.0862	.2640	0	1.0000	5.689200E-04	0.
.9500	.0835	.2460	0	1.0000	5.135250E-04	0.
.9750	.0791	.2320	0	1.0000	4.587800E-04	0.
1.0000	.0746	.2220	0	1.0000	4.140300E-04	0.

Table A-25 (cont)

## JUPITER CHECK OUT CASE NO 9

## TV ENERGY DATA FOR TOPS NA SIT CAMERA

## SATELLITE 1 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF (W/SQCM)
.2500	.0370	.0450	0	1.0000	3.150000E-05	0.
.2750	.0204	.0500	.0020	1.0000	1.020000E-04	2.040000E-07
.3000	.0514	.0550	.0950	1.0000	2.827000E-04	2.685650E-05
.3250	.0971	.0600	.4760	1.0000	5.826000E-04	2.773176E-04
.3500	.1093	.0650	.7620	1.0000	7.104500E-04	5.413629E-04
.3750	.1157	.0700	.9530	1.0000	8.099000E-04	7.713347E-04
.4000	.1429	.0750	.9840	1.0000	1.071750E-03	1.054602E-03
.4250	.1693	.0800	1.0000	1.0000	1.354400E-03	1.354400E-03
.4500	.2006	.0850	.9840	1.0000	1.705100E-03	1.677818E-03
.4750	.2044	.1000	.9530	1.0000	2.044000E-03	1.947932E-03
.5000	.1942	.1050	.7940	1.0000	2.039100E-03	1.619045E-03
.5250	.1852	.1130	.7620	1.0000	2.092760E-03	1.594683E-03
.5500	.1725	.1200	.6820	1.0000	2.070000E-03	1.411740E-03
.5750	.1719	.1250	.5550	1.0000	2.148750E-03	1.192556E-03
.6000	.1666	.1300	.4760	1.0000	2.165800E-03	1.030921E-03
.6250	.1586	.1350	.4450	1.0000	2.141100E-03	9.527895E-04
.6500	.1511	.1450	.3600	1.0000	2.190350E-03	7.887420E-04
.6750	.1442	.1550	.2540	1.0000	2.235100E-03	5.677154E-04
.7000	.1369	.1650	.2060	1.0000	2.258350E-03	4.653231E-04
.7250	.1302	.1700	.1590	1.0000	2.213400E-03	3.519306E-04
.7500	.1235	.1750	.0950	1.0000	2.161250E-03	2.053187E-04
.7750	.1171	.1800	.0400	1.0000	2.107800E-03	8.431200E-05
.8000	.1107	.1850	.0240	1.0000	2.047950E-03	4.915086E-05
.8250	.1048	.2900	.0100	1.0000	3.039200E-03	3.039200E-05
.8500	.0988	.2950	.0030	1.0000	2.914600E-03	8.743800E-06
.8750	.0939	.2000	.0220	1.0000	1.878000E-03	4.131600E-05
.9000	.0889	.2000	0	1.0000	1.778000E-03	0.
.9250	.0862	.2000	0	1.0000	1.724000E-03	0.
.9500	.0835	.2050	0	1.0000	1.711750E-03	0.
.9750	.0791	.2080	0	1.0000	1.645280E-03	0.
1.0000	.0746	.2100	0	1.0000	1.566600E-03	0.

## JUPITER CHECK OUT CASE NO 9

## TV ENERGY DATA FOR TOPS NA SIT CAMERA

## SATELLITE 2 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF (W/SQCM)
.2500	.0070	.0450	0	1.0000	3.150000E-05	0.
.2750	.0204	.0500	.0020	1.0000	1.020000E-04	2.040000E-07
.3000	.0514	.0550	.0950	1.0000	2.827000E-04	2.685650E-05
.3250	.0971	.0600	.4760	1.0000	5.826000E-04	2.773176E-04
.3500	.1093	.0650	.7620	1.0000	7.104500E-04	5.413629E-04
.3750	.1157	.0700	.9530	1.0000	8.099000E-04	7.713347E-04
.4000	.1429	.0750	.9840	1.0000	1.071750E-03	1.054602E-03
.4250	.1693	.0800	1.0000	1.0000	1.354400E-03	1.354400E-03
.4500	.2006	.0850	.9840	1.0000	1.705100E-03	1.677818E-03
.4750	.2044	.1000	.9530	1.0000	2.044000E-03	1.947932E-03
.5000	.1942	.1050	.7940	1.0000	2.039100E-03	1.619045E-03
.5250	.1852	.1130	.7620	1.0000	2.092760E-03	1.594683E-03
.5500	.1725	.1200	.6820	1.0000	2.070000E-03	1.411740E-03
.5750	.1719	.1250	.5550	1.0000	2.148750E-03	1.192556E-03
.6000	.1666	.1300	.4760	1.0000	2.165800E-03	1.030921E-03
.6250	.1586	.1350	.4450	1.0000	2.141100E-03	9.527895E-04
.6500	.1511	.1450	.3600	1.0000	2.190350E-03	7.887420E-04
.6750	.1442	.1550	.2540	1.0000	2.235100E-03	5.677154E-04
.7000	.1369	.1650	.2060	1.0000	2.258350E-03	4.653231E-04
.7250	.1302	.1700	.1590	1.0000	2.213400E-03	3.519306E-04
.7500	.1235	.1750	.0950	1.0000	2.161250E-03	2.053187E-04
.7750	.1171	.1800	.0400	1.0000	2.107800E-03	8.431200E-05
.8000	.1107	.1850	.0240	1.0000	2.047950E-03	4.915086E-05
.8250	.1048	.2900	.0100	1.0000	3.039200E-03	3.039200E-05
.8500	.0988	.2950	.0030	1.0000	2.914600E-03	8.743800E-06
.8750	.0939	.2000	.0220	1.0000	1.878000E-03	4.131600E-05
.9000	.0889	.2000	0	1.0000	1.778000E-03	0.
.9250	.0862	.2000	0	1.0000	1.724000E-03	0.
.9500	.0835	.2050	0	1.0000	1.711750E-03	0.
.9750	.0791	.2080	0	1.0000	1.645280E-03	0.
1.0000	.0746	.2100	0	1.0000	1.566600E-03	0.

Table A-25 (cont)

## JUPITER CHECK OUT CASE NO 9

## TV ENERGY DATA FOR TOPS NA SIT CAMERA

## SATELLITE 3 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF (W/SQCM)
.2500	.0076	.0450	0	1.0000	1.567125E-05	0.
.2750	.0204	.0500	.0020	1.0000	5.074500E-05	1.014900E-07
.3000	.0514	.0550	.0950	1.0000	1.406432E-04	1.336111E-05
.3250	.0971	.0600	.4760	1.0000	2.898435E-04	1.373655E-04
.3500	.1093	.0650	.7620	1.0000	3.534489E-04	2.693280E-04
.3750	.1157	.0700	.9530	1.0000	4.029252E-04	3.833878E-04
.4000	.1429	.0750	.9840	1.0000	5.331956E-04	5.246645E-04
.4250	.1693	.0800	1.0000	1.0000	6.733146E-04	6.733140E-04
.4500	.2006	.0850	.9840	1.0000	8.482872E-04	8.347147E-04
.4750	.2044	.1000	.9530	1.0000	1.016890E-03	9.694962E-04
.5000	.1942	.1050	.7940	1.0000	1.014452E-03	8.054751E-04
.5250	.1852	.1130	.7620	1.0000	1.041148E-03	7.933549E-04
.5500	.1725	.1200	.6820	1.0000	1.029825E-03	7.023406E-04
.5750	.1719	.1250	.5550	1.0000	1.063003E-03	5.932967E-04
.6000	.1666	.1300	.4760	1.0000	1.077485E-03	5.123831E-04
.6250	.1586	.1350	.4450	1.0000	1.065197E-03	4.741128E-04
.6500	.1511	.1450	.3600	1.0000	1.084998E-03	3.923931E-04
.6750	.1442	.1550	.2540	1.0000	1.111962E-03	2.824384E-04
.7000	.1369	.1650	.2060	1.0000	1.123778E-03	2.314982E-04
.7250	.1302	.1700	.1590	1.0000	1.101166E-03	1.753055E-04
.7500	.1235	.1750	.0950	1.0000	1.075222E-03	1.021461E-04
.7750	.1171	.1800	.0400	1.0000	1.048630E-03	4.194522E-05
.8000	.1107	.1850	.0240	1.0000	1.018855E-03	2.445252E-05
.8250	.1048	.2900	.0100	1.0000	1.512002E-03	1.512002E-05
.8500	.0988	.2950	.0030	1.0000	1.450013E-03	4.353040E-06
.8750	.0939	.2000	.0220	1.0000	9.343050E-04	2.055471E-05
.9000	.0889	.2000	0	1.0000	8.845550E-04	0.
.9250	.0862	.2000	0	1.0000	8.576300E-04	0.
.9500	.0835	.2050	0	1.0000	8.515956E-04	0.
.9750	.0791	.2000	0	1.0000	9.135263E-04	0.
1.0000	.0746	.2100	0	1.0000	7.793835E-04	0.

## JUPITER CHECK OUT CASE NO 9

## TV ENERGY DATA FOR TOPS NA SIT CAMERA

## SATELLITE 4 DATA

MICRONS	SOLAR	ALBEDO	SENSOR	FILTER	BO (W/SQCM)	BEFF (W/SQCM)
.2500	.0070	.0450	0	1.0000	1.779750E-05	0.
.2750	.0204	.0500	.0020	1.0000	5.763000E-05	1.152600E-07
.3000	.0514	.0550	.0950	1.0000	1.597255E-04	1.517392E-05
.3250	.0971	.0600	.4760	1.0000	3.291690E-04	1.565844E-04
.3500	.1093	.0650	.7620	1.0000	4.014042E-04	3.053700E-04
.3750	.1157	.0700	.9530	1.0000	4.575935E-04	4.360966E-04
.4000	.1429	.0750	.9840	1.0000	6.055387E-04	5.953501E-04
.4250	.1693	.0800	1.0000	1.0000	7.652360E-04	7.652360E-04
.4500	.2006	.0850	.9840	1.0000	9.633815E-04	9.479574E-04
.4750	.2044	.1000	.9530	1.0000	1.154860E-03	1.103582E-03
.5000	.1942	.1050	.7940	1.0000	1.152091E-03	9.147607E-04
.5250	.1852	.1130	.7620	1.0000	1.182409E-03	9.009960E-04
.5500	.1725	.1200	.6820	1.0000	1.169550E-03	7.975331E-04
.5750	.1719	.1250	.5550	1.0000	1.214044E-03	6.737943E-04
.6000	.1666	.1300	.4760	1.0000	1.223677E-03	5.824703E-04
.6250	.1586	.1350	.4450	1.0000	1.209721E-03	5.383261E-04
.6500	.1511	.1450	.3600	1.0000	1.237387E-03	4.456392E-04
.6750	.1442	.1550	.2540	1.0000	1.262831E-03	3.207592E-04
.7000	.1369	.1650	.2060	1.0000	1.276250E-03	2.623076E-04
.7250	.1302	.1700	.1590	1.0000	1.250571E-03	1.983408E-04
.7500	.1235	.1750	.0950	1.0000	1.221106E-03	1.160051E-04
.7750	.1171	.1800	.0400	1.0000	1.190907E-03	4.763623E-05
.8000	.1107	.1850	.0240	1.0000	1.157092E-03	2.777020E-05
.8250	.1048	.2900	.0100	1.0000	1.717148E-03	1.717148E-05
.8500	.0988	.2950	.0030	1.0000	1.646749E-03	4.942472E-06
.8750	.0939	.2000	.0220	1.0000	1.061070E-03	2.334354E-05
.9000	.0889	.2000	0	1.0000	1.004570E-03	0.
.9250	.0862	.2000	0	1.0000	9.740600E-04	0.
.9500	.0835	.2050	0	1.0000	9.671387E-04	0.
.9750	.0791	.2080	0	1.0000	9.295832E-04	0.
1.0000	.0746	.2100	0	1.0000	8.851290E-04	0.

Table A-25 (concl)

## JUPITER CHECK OUT CASE NO 9

## COMPUTATIONS FOR MINIMUM PICTURE TAKING INTERVAL

PICTURE START TIME (DAYS) = 1.0000000E+00  
 PICTURE STOP TIME (DAYS) = 2.2000000E+01  
 DELTA T REQUESTED (SEC) = 4.3200000E+04  
 FRAME READ TIME (SEC) = 4.0000000E+01  
 FRAME READ RATE (BPS) = 1.2500000E+05

BULK DATA STORAGE CAPACITY (BITS) = 2.0000000E+09  
 PICTURE SIZE (BITS) = 5.1200000E+06  
 BULK DATA STORAGE CAPACITY (PICS) = 3.9062500E+02  
 BULK CONTENTS IN USE (BITS) = 0.  
 BUFFER STORAGE CAPACITY (BITS) = 2.0000000E+06

DATA TRANSMISSION RATE (BPS) = 2.9500000E+04  
 RATE FROM OTHER INSTRUMENTS (BPS) = 6.4000000E+02  
 REAL TIME PICTURE RATE (BPS) = 2.7860000E+04

BUFFER CAPACITY LESS THAN ONE PICTURE, CAPACITY SET TO 5.120E+06

MINIMUM PICTURE INTERVAL (SEC) = 1.83776023E+02  
 MAXIMUM PICTURE RATE (PICS/HR) = 1.35390625E+01  
 MAXIMUM PICTURE RATE (PIC/DAY) = 4.7013750E+02  
 MAXIMUM NUMBER OF PICTURES = 9972  
 ACTUAL PICTURE RATE (PIC/DAY) = 2.0000000E+00  
 ACTUAL NUMBER OF PICTURES = 41

PERIAPSIS STATE VECTOR  
 -1.5581544E+09 -4.33051226E+04 3.07916842E+02  
 9.75926932E+00 -3.77127648E+01 0.  
 VIEW FROM INPUT VIEWPOINT

## JUPITER CHECK OUT CASE NO 9

PLOT INTERVAL = 1 CALC STEPS = 720.00 MINUTES  
 PRINT INTERVAL = 1 CALC STEPS = 720.00 MINUTES

TIME INTERVAL FOR CALCULATIONS = 720.00 MINUTES

PICTURE	CALC	TIME (DAYS)	TIME (HRS)	TIME (MIN)
1	1	1.0000000E+00	2.4000000E+01	1.4400000E+03
2	2	1.5000000E+00	3.6000000E+01	2.1600000E+03
3	3	2.0000000E+00	4.8000000E+01	2.8800000E+03
4	4	2.5000000E+00	6.0000000E+01	3.6000000E+03
5	5	3.0000000E+00	7.2000000E+01	4.3200000E+03
6	6	3.5000000E+00	8.4000000E+01	5.0400000E+03
7	7	4.0000000E+00	9.6000000E+01	5.7600000E+03
8	8	4.5000000E+00	1.0800000E+02	6.4800000E+03
9	9	5.0000000E+00	1.2000000E+02	7.2000000E+03
10	10	5.5000000E+00	1.3200000E+02	7.9200000E+03
11	11	6.0000000E+00	1.4400000E+02	8.6400000E+03
12	12	6.5000000E+00	1.5600000E+02	9.3600000E+03
13	13	7.0000000E+00	1.6800000E+02	1.0080000E+04
14	14	7.5000000E+00	1.8000000E+02	1.0800000E+04
15	15	8.0000000E+00	1.9200000E+02	1.1520000E+04
16	16	8.5000000E+00	2.0400000E+02	1.2240000E+04
17	17	9.0000000E+00	2.1600000E+02	1.2960000E+04
18	18	9.5000000E+00	2.2800000E+02	1.3680000E+04
19	19	1.0000000E+01	2.4000000E+02	1.4400000E+04
20	20	1.0500000E+01	2.5200000E+02	1.5120000E+04
21	21	1.1000000E+01	2.6400000E+02	1.5840000E+04
22	22	1.1500000E+01	2.7600000E+02	1.6560000E+04
23	23	1.2000000E+01	2.8800000E+02	1.7280000E+04
24	24	1.2500000E+01	3.0000000E+02	1.8000000E+04
25	25	1.3000000E+01	3.1200000E+02	1.8720000E+04
26	26	1.3500000E+01	3.2400000E+02	1.9440000E+04
27	27	1.4000000E+01	3.3600000E+02	2.0160000E+04
28	28	1.4500000E+01	3.4800000E+02	2.0880000E+04
29	29	1.5000000E+01	3.6000000E+02	2.1600000E+04
30	30	1.5500000E+01	3.7200000E+02	2.2320000E+04
31	31	1.6000000E+01	3.8400000E+02	2.3040000E+04
32	32	1.6500000E+01	3.9600000E+02	2.3760000E+04
33	33	1.7000000E+01	4.0800000E+02	2.4480000E+04
34	34	1.7500000E+01	4.2000000E+02	2.5200000E+04
35	35	1.8000000E+01	4.3200000E+02	2.5920000E+04
36	36	1.8500000E+01	4.4400000E+02	2.6640000E+04
37	37	1.9000000E+01	4.5600000E+02	2.7360000E+04
38	38	1.9500000E+01	4.6800000E+02	2.8080000E+04
39	39	2.0000000E+01	4.8000000E+02	2.8800000E+04
40	40	2.0500000E+01	4.9200000E+02	2.9520000E+04
41	41	2.1000000E+01	5.0400000E+02	3.0240000E+04
42	42	2.1500000E+01	5.1600000E+02	3.0960000E+04
43	43	2.2000000E+01	5.2800000E+02	3.1680000E+04
44	44	2.2500000E+01	5.4000000E+02	3.2400000E+04
45	45	2.3000000E+01	5.5200000E+02	3.3120000E+04
46	46	2.3500000E+01	5.6400000E+02	3.3840000E+04
47	47	2.4000000E+01	5.7600000E+02	3.4560000E+04

JUPITER CHECK OUT CASE NO 9  
TOPS NA SIT CAMERA

EXPOSURE TOO HIGH 2.802E-02 (ERG/CM\*\*2)  
 EXPOSURE TIME REDUCED TO 3.071E-05 SEC  
 EXPOSURE IS 1.741E-03 (ERG/CM\*\*2)  
 CHG 1  
 EXPOSURE TIME SET TO 0.1 MILLISEC  
 REQUIRED FILTER FACTOR IS 1.647E+00  
 CHG 1  
 VIEW FROM SPACECRAFT

b. Output Data - The frame times used were the same as for case 8, which used a Pioneer type camera. Table A-26 presents the tabular output for the selected frames.

The graphic output presents closest approach geometry (Fig. A-22), TV summaries (Fig. A-23), and satellite geometry summaries (Fig. A-24).



Table A-26 Case 9 Tabular Output

JUPITER CHECK OUT CASE NO 9

PICTURE NUMBER 5 3 DAYS 0 HRS 0 MIN TO ENCOUNTER JD 2445734.500

PLANET JUPITE	SATELLITE CALLI
RANGE (KM) = 2.66269379E+06	RANGE (KM) = 1.19299507E+06
CONE (DEG) = 34.10	CONE (DEG) = 46.23
CLOCK (DEG) = 87.14	CLOCK (DEG) = 90.60
PHASE (DEG) = 98.63	PHASE (DEG) = 126.46
DIAM (DEG) = 3.07	DIAM (DEG) = .23

RESOLUTION OF PLANET  
 CENTER = 25.91 KM/PIXEL  
 LIMB = 26.62 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITE (PICTURE CENTERED AT -.83 DEG LAT 130.07 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 25.91 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 10.30 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 589.04 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .06 KM  
 NUMBER OF PIXELS SMEARED .00230 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 21.741 MILLISEC

EFFECTIVE RESOLUTION WITH SMEAR  
 AT SPECIFIED LOCATION 26.0 KM/PIXEL  
 AT SUBSPACECRAFT POINT 26.0 KM/PIXEL  
 AT LIMB OF TARGET BODY 26.7 KM/PIXEL

EXPOSURE TIME FOR TOPS NA SIT CAMERA = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 2.0449E+01 ERGS/SQ CM/SEC 0.4 SENSOR  
 EXPOSURE = 1.7612E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 85.000  
 DIGITAL NUMBER OF EXPOS = 217 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-03 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	5.0	5.0	5.0	0.	
SATELLITE 1	5.0000	5.0000	5.0000	0.	
SATELLITE 2	5.0000	5.0000	5.0000	0.	
SATELLITE 3	5.0000	5.0000	5.0000	0.	
SATELLITE 4	5.0000	5.0000	5.0000	4.0000	

SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	2.85040788E+05	80.74	91.99	85.76
2	3.18056131E+06	36.97	75.76	87.45
3	3.72563611E+06	30.91	81.82	87.05
4	1.19299507E+06	126.46	46.28	90.60

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	8.07429149E+01	6.71370283E-02
2	9.69706902E+01	5.26019358E-02
3	9.09100043E+01	7.84313409E-02
4	1.26460415E+02	2.26686818E-01

RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	2.84873768E+01	2.85040739E+01
2	3.17910131E+01	3.18056098E+01
3	3.72308611E+01	3.72563523E+01
4	1.19063507E+01	1.19299273E+01

SMEAR DATA FOR SATELLITES

SMEAR DUE TO VEL (KM/SEC)	SMEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
1.02079370E+01	6.37139128E+02	2.47172619E-03	2.02287778E-02
1.44858817E+01	6.62074560E+02	2.12056304E-03	2.35736435E-02
1.34111532E+01	8.24296713E+02	2.24166304E-03	2.23023789E-02
1.37585834E+00	2.10885749E+02	1.78263138E-03	2.80484235E-02

VIEW FROM SPACECRAFT

Table A-26 (cont)

JUPITER CHECK OUT CASE NO 9

PICTURE NUMBER 24 12 DAYS 12 HRS 0 MIN TO ENCOUNTER JD 2445744.000

PLANET JUPITER	SATELLITE CALLI
RANGE (KM) = 4.19284240E+06	RANGE (KM) = 5.93824852E+06
CONE (DEG) = 103.04	CONE (DEG) = 111.33
CLOCK (DEG) = 87.53	CLOCK (DEG) = 86.81
PHASE (DEG) = 68.54	PHASE (DEG) = 60.25
DIAM (DEG) = 1.95	DIAM (DEG) = .05

RESOLUTION OF PLANET  
 CENTER = 41.21 KM/PIXEL  
 LIMB = 41.92 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITER (PICTURE CENTERED AT -1.51 DEG LAT 90.87 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 41.21 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 11.16 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 1109.46 KM/SEC  
 OBJECT MOTION FROM ALL SCOPES .11 KM  
 NUMBER OF PIXELS SMEARED .00271 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 18.453 MILLISEC

EFFECTIVE RESOLUTION WITH SMEAR  
 AT SPECIFIED LOCATION 41.3 KM/PIXEL  
 AT SUBSPACECRAFT POINT 41.3 KM/PIXEL  
 AT LIMB OF TARGET BODY 42.0 KM/PIXEL

EXPOSURE TIME FOR TOPS NA SIT CAMERA = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.5349E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.5349E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 76.652  
 DIGITAL NUMBER OF EXPOS = 196 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-05 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN RESOLUTION LEVELS	KM/PIXEL				
	300.0	100.0	50.0	10.0	
PLANET	24.0	24.0	24.0	0.	
SATELLITE 1	24.0000	24.0000	24.0000	0.	
SATELLITE 2	24.0000	24.0000	24.0000	0.	
SATELLITE 3	24.0000	24.0000	20.0000	0.	
SATELLITE 4	24.0000	24.0000	14.0000	4.0000	

SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	3.77295651E+06	68.56	103.02	87.70
2	3.51504033E+06	68.44	103.14	87.84
3	4.33942397E+06	54.27	117.31	86.99
4	5.93824852E+06	60.25	111.33	86.81

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	6.85627840E+01	5.07209425E-02
2	6.84429485E+01	4.75965100E-02
3	5.42704908E+01	6.73380833E-02
4	6.02534073E+01	4.55413891E-02

RESOLUTION (KM/PIX) DATA FOR SATELLITES	RES AT SATELLITE LIMB
NUM	RES ALONG RADIUS VECTOR
1	3.77128651E+01
2	3.51358093E+01
3	4.33687397E+01
4	5.93588852E+01

SMEAR DATA FOR SATELLITES	SMEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SHEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
SMEAR DUE TO VEL (KM/SEC)			
1.59155730E+01	1.01643258E+03	2.66794640E-03	1.87410034E-02
1.21244141E+01	9.48423615E+02	2.67671026E-03	1.86795460E-02
4.51957831E+00	1.26173601E+03	2.91514059E-03	1.71519314E-02
9.40183837E+00	1.67743003E+03	2.83549729E-03	1.76335912E-02

VIEW FROM SPACECRAFT  
 LAT -2, LONG 167 NOT VISIBLE

Table A-26 (cont)

JUPITER CHECK OUT CASE NO 9

PICTURE NUMBER 13 7 DAYS 0 HRS 0 MIN TO ENCOUNTER JD 2445738.500

PLANET JUPITE	SATELLITE CALLI
RANGE (KM) = 3.94298327E+06	RANGE (KM) = 4.61086320E+06
CONE (DEG) = 94.37	CONE (DEG) = 70.44
CLOCK (DEG) = 87.31	CLOCK (DEG) = 88.12
PHASE (DEG) = 77.82	PHASE (DEG) = 101.75
DIAM (DEG) = 2.07	DIAM (DEG) = .06

RESOLUTION OF PLANET  
 CENTER = 38.72 KM/PIXEL  
 LIMB = 39.42 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITE (PICTURE CENTERED AT -1.22 DEG LAT 229.60 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 38.72 KM/PIXEL  
 SHEAR DUE TO RELATIVE VELOCITIES 11.07 KM/SEC  
 SHEAR DUE TO S/C ATTITUDE RATES 971.85 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .10 KM  
 NUMBER OF PIXELS SMEARED .00253 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SHEAR 19.762 MILLISEC

EFFECTIVE RESOLUTION WITH SHEAR  
 AT SPECIFIED LOCATION 38.3 KM/PIXEL  
 AT SUBSPACECRAFT POINT 38.3 KM/PIXEL  
 AT LIMB OF TARGET BODY 39.5 KM/PIXEL

EXPOSURE TIME FOR TOPS NA SIT CAMERA = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.6151E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.6151E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 80.676  
 DIGITAL NUMBER OF EXPOS = 206 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN RESOLUTION LEVELS	KH/PIXEL				
	300.0	100.0	50.0	10.0	0
PLANET	13.0	13.0	13.0	0.	
SATELLITE 1	13.0000	13.0000	13.0000	0.	
SATELLITE 2	13.0000	13.0000	13.0000	0.	
SATELLITE 3	13.0000	13.0000	13.0000	0.	
SATELLITE 4	13.0000	13.0000	13.0000	4.0000	

SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	3.58308793E+06	74.50	97.69	87.31
2	4.60161687E+06	79.07	93.12	97.19
3	2.87364462E+06	78.66	93.53	87.71
4	4.61086320E+06	101.75	70.44	88.12

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	7.45921165E+01	5.34086559E-02
2	7.90687476E+01	3.63575855E-02
3	7.86565142E+01	1.01685682E-01
4	1.01749057E+02	5.86519442E-02

RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	3.58141793E+01	3.58308754E+01
2	4.60015687E+01	4.60161664E+01
3	2.87109463E+01	2.87364349E+01
4	4.60850320E+01	4.61086259E+01

SHEAR DATA FOR SATELLITES

SHEAR DUE TO VEL (KM/SEC)	SHEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SHEAR 1/2 PIXEL (SEC)
1.31836480E+01	9.24994799E+02	2.55760677E-03	1.95495260E-02
1.53905216E+01	1.14125829E+03	2.50450140E-03	1.99640535E-02
9.23603441E+00	7.18333745E+02	2.47956112E-03	2.01648589E-02
6.66490743E+00	9.15573784E+02	1.99941256E-03	2.50673451E-02

VIEW FROM SPACECRAFT

Table A-26 (cont)

JUPITER CHECK OUT CASE NO 9

PICTURE NUMBER 33 17 DAYS 0 HRS 0 MIN TO ENCOUNTER JD 2445743.500

PLANET JUPITER	SATELLITE CALLI
RANGE (KM) = 3.22745354E+06	RANGE (KM) = 2.99044792E+06
CONE (DEG) = 112.07	CONE (DEG) = 146.80
CLOCK (DEG) = 87.67	CLOCK (DEG) = 86.81
PHASE (DEG) = 59.12	PHASE (DEG) = 24.40
DIAM (DEG) = 2.53	DIAM (DEG) = .09

RESOLUTION OF PLANET  
 CENTER = 31.56 KM/PIXEL  
 LIMB = 32.27 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITER (PICTURE CENTERED AT -1.77 DEG LAT 110.10 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 31.56 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 10.71 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 897.75 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .09 KM  
 NUMBER OF PIXELS SMEARED .00287 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 17.449 MILLISEC

EFFECTIVE RESOLUTION WITH SMEAR  
 AT SPECIFIED LOCATION 31.7 KM/PIXEL  
 AT SUBSPACECRAFT POINT 31.7 KM/PIXEL  
 AT LIMB OF TARGET BODY 32.4 KM/PIXEL

EXPOSURE TIME FOR TOPS NA SIT CAMERA = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.4487E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.4487E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 72.323  
 DIGITAL NUMBER OF EXPOS = 185 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN RESOLUTION LEVELS	KM/PIXEL			
	300.0	100.0	50.0	10.0
PLANET	33.0	33.0	33.0	0.
SATELLITE 1	33.0000	33.0000	33.0000	0.
SATELLITE 2	33.0000	33.0000	33.0000	0.
SATELLITE 3	33.0000	33.0000	29.0000	0.
SATELLITE 4	33.0000	33.0000	20.0000	4.0000

SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	3.64862320E+06	58.43	112.77	87.42
2	3.23775087E+06	71.01	100.18	83.15
3	3.35108232E+06	71.81	99.39	87.79
4	2.99044792E+06	24.40	146.80	86.81

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	5.84280909E+01	5.24493486E-02
2	7.10135691E+01	5.16728089E-02
3	7.18057575E+01	7.39565699E-02
4	2.43999492E+01	9.04353111E-02

RESOLUTION (KM/PIX) DATA FOR SATELLITES

NUM	RES ALONG RADIUS VECTOR	RES AT SATELLITE LIMB
1	3.64695323E+01	3.64862282E+01
2	3.23629087E+01	3.23775054E+01
3	3.94353232E+01	3.95108150E+01
4	2.98808792E+01	2.99044699E+01

SMEAR DATA FOR SATELLITES

SMEAR DUE TO VEL (KM/SEC)	SMEAR DUE TO S/C (KM/SEC)	NUMBER OF PIXELS SMEARED	TIME TO SMEAR 1/2 PIXEL (SEC)
1.91862732E+01	1.04060414E+03	2.38553122E-03	1.73278319E-02
2.83472248E+00	8.56813946E+02	2.65424261E-03	1.88377655E-02
9.13362430E+00	1.33708310E+03	2.64220573E-03	1.89235932E-02
5.44711330E+00	8.93744593E+02	3.00070401E-03	1.66627564E-02

VIEW FROM SPACECRAFT  
 LAT -2 , LONG 147 NOT VISIBLE

Table A-26 (concl)

JUPITER CHECK OUT CASE 10 9

PICTURE NUMBER 41 21 DAYS 0 HRS 0 MIN TO ENCOUNTER JD 2445752.500

PLANET JUPITE	SATELLITE CALLI
RANGE (KM) = 6.2447233E+05	RANGE (KM) = 1.32173119E+06
CONE (DEG) = 159.75	CONE (DEG) = 54.61
CLOCK (DEG) = 87.34	CLOCK (DEG) = 264.38
PHASE (DEG) = 15.25	PHASE (DEG) = 130.33
DIAM (DEG) = 13.13	DIAM (DEG) = .20

RESOLUTION OF PLANET  
 CENTER = 5.53 KM/PIXEL  
 LIMB = 6.20 KM/PIXEL  
 INSTRUMENT DATA FOR PLANET JUPITE (PICTURE CENTERED AT -2.21 DEG LAT 242.73 DEG LONG)

RESOLUTION AT SPECIFIED LOCATION = 5.53 KM/PIXEL  
 SMEAR DUE TO RELATIVE VELOCITIES 2.61 KM/SEC  
 SMEAR DUE TO S/C ATTITUDE RATES 160.96 KM/SEC  
 OBJECT MOTION FROM ALL SOURCES .02 KM  
 NUMBER OF PIXELS SMEARED .00293 PIXELS

EXPOSURE TIME FOR ONE-HALF PIXEL SMEAR 17.066 MILLISEC

EFFECTIVE RESOLUTION WITH SMEAR  
 AT SPECIFIED LOCATION 5.5 KM/PIXEL  
 AT SUBSPACECRAFT POINT 5.5 KM/PIXEL  
 AT LIMB OF TARGET BODY 6.2 KM/PIXEL

EXPOSURE TIME FOR TOPS NA SIT CAMERA = .100 MILLISEC  
 POWER DENSITY = 0 ERGS/SQ CM/SEC AT LENS  
 POWER DENSITY = 1.0133E+01 ERGS/SQ CM/SEC ON SENSOR  
 EXPOSURE = 1.0133E-03 ERGS/SQ CM

PERCENT OF DYNAMIC RANGE = 50.466  
 DIGITAL NUMBER OF EXPOS = 129 (OF 256 LEVELS)  
 ONE DIGITAL NUMBER EQUALS 7.7812E-06 ERGS/SQ CM

NUMBER OF PICTURES WITH RESOLUTION BETTER THAN	300.0	100.0	50.0	10.0	KM/PIXEL
PLANET	41.0	41.0	41.0	1.0	
SATELLITE 1	41.0000	41.0000	41.0000	1.0000	
SATELLITE 2	41.0000	41.0000	41.0000	3.0000	
SATELLITE 3	41.0000	41.0000	37.0000	0.	
SATELLITE 4	41.0000	41.0000	28.0000	7.0000	

SATELLITE DATA

NUM	RANGE (KM)	PHASE (DEG)	CONE (DEG)	CLOCK (DEG)
1	9.29926477E+05	6.71	177.56	70.52
2	8.86088816E+05	63.84	107.16	87.92
3	1.11144736E+06	54.53	134.42	267.40
4	1.32873119E+06	130.33	58.61	264.38

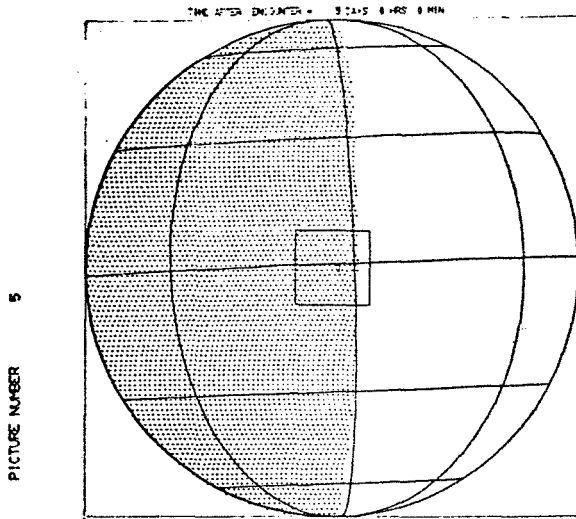
  

NUM	EARTH-SAT-S/C ANG	SATELLITE ANG DIAM
1	6.71069378E+00	2.05799319E-01
2	6.38420790E+01	1.88811493E-01
3	5.45769703E+01	2.62908297E-01
4	1.30375269E+02	2.03529670E-01

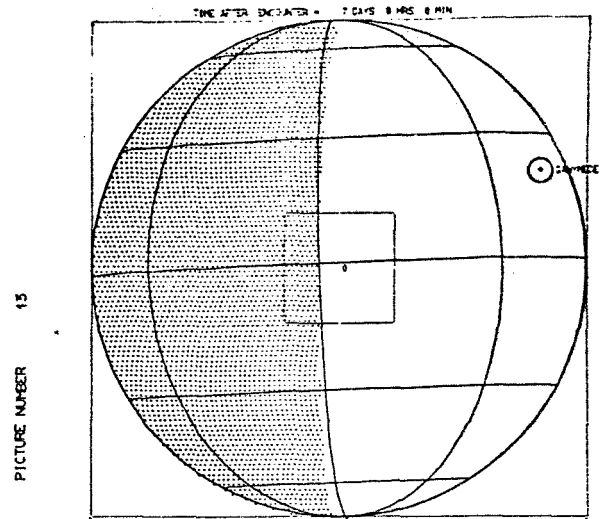
RESOLUTION (KM/PIX) DATA FOR SATELLITES	RES AT SATELLITE LIMB
NUM	RES ALONG RADIUS VECTOR
1	9.28256477E+00
2	8.84628816E+00
3	1.10889736E+01
4	1.32637119E+01

SMEAR DATA FOR SATELLITES	NUMBER OF	TIME TO SMEAR
SMEAR DUE TO	PIXELS SMEARED	1/2 PIXEL (SEC)
VEL (KM/SEC)	S/C (KM/SEC)	
2.96176778E+01	2.35618103E+02	2.75982161E-03
4.76316831E+00	2.45479165E+02	1.81171130E-02
2.73423113E+01	1.85334015E+02	2.81342072E-03
8.66294754E+00	3.90209470E+02	1.77713598E-02
		1.91782300E-03
		2.60712276E-02
		2.97436732E-03
		1.68102977E-02

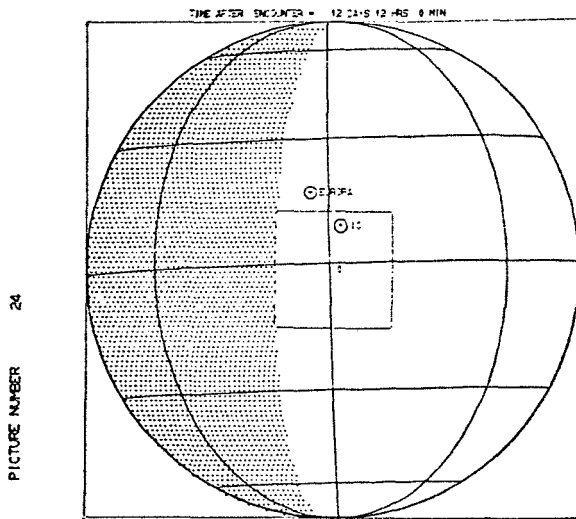
VIEW FROM SPACECRAFT  
 LAT 1 - LONG 152 NOT VISIBLE



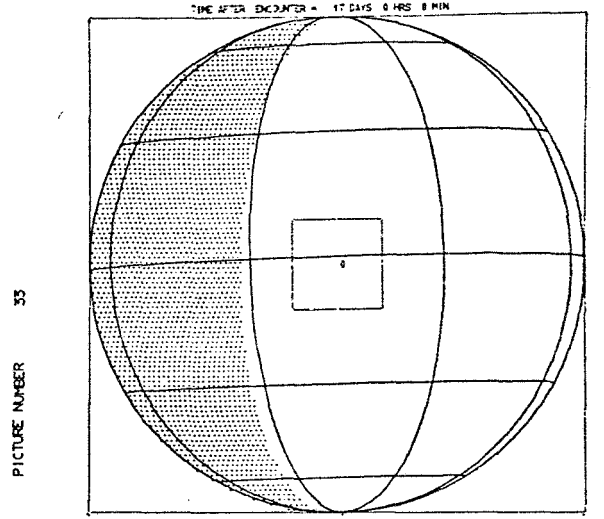
5: PITER CHECK OUT CA SE NO 9



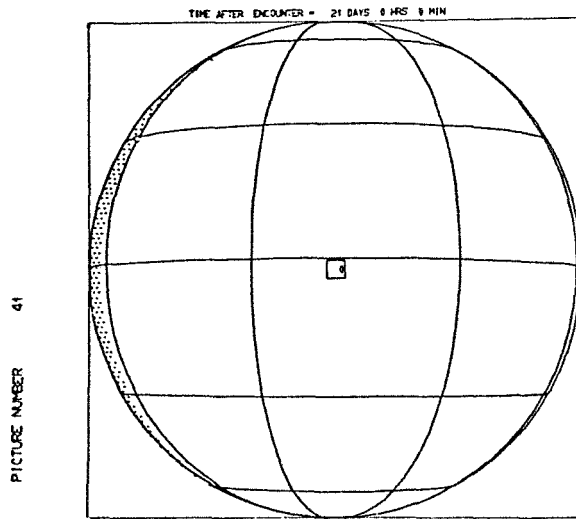
15: PITER CHECK OUT CA SE NO 9



24: PITER CHECK OUT CA SE NO 9



35: PITER CHECK OUT CA SE NO 9



41: PITER CHECK OUT CA SE NO 9

JUPITER

Fig. A-22 Scenes Before and After Closest Approach

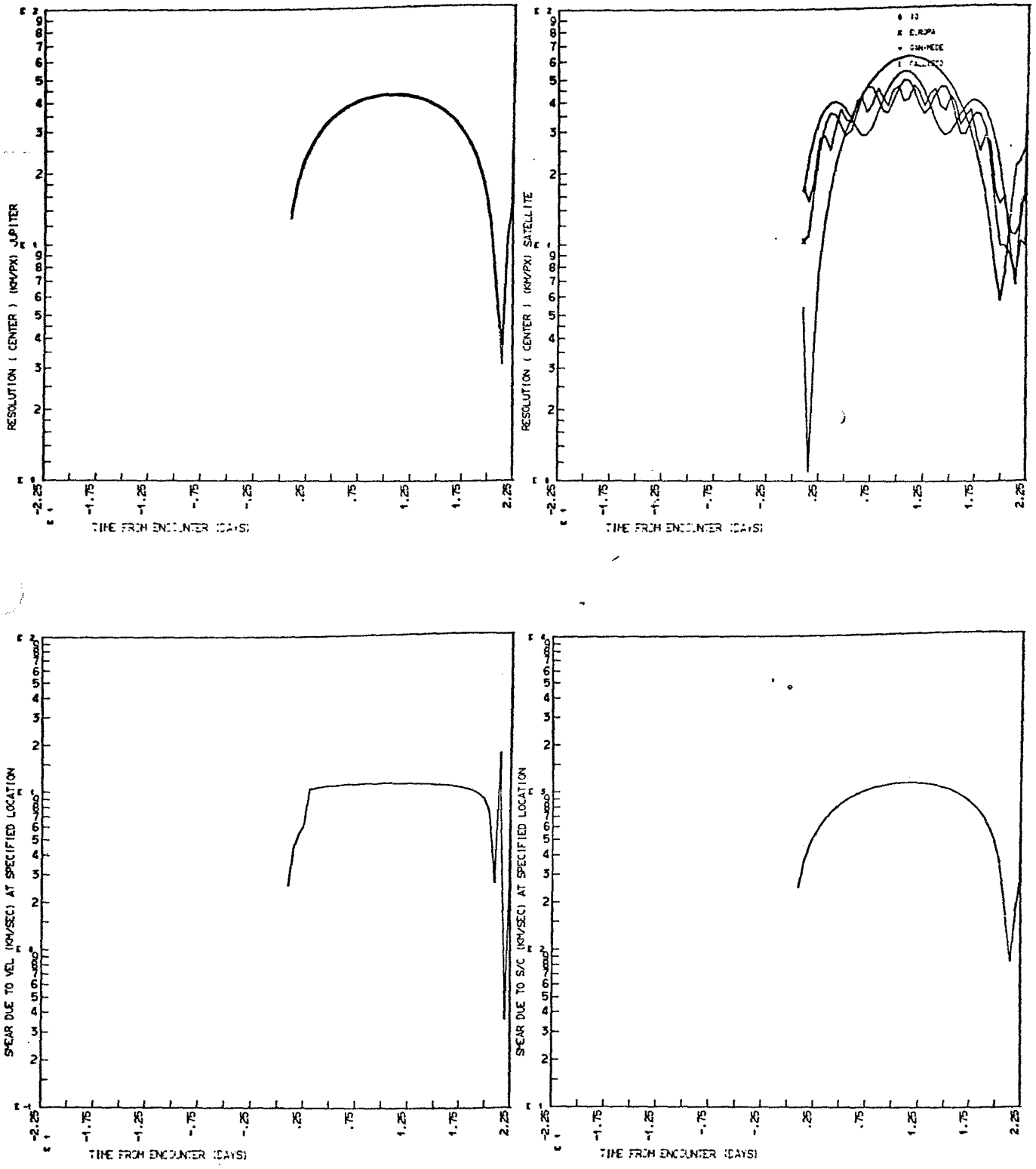


Fig. A-23 TV Summaries

110

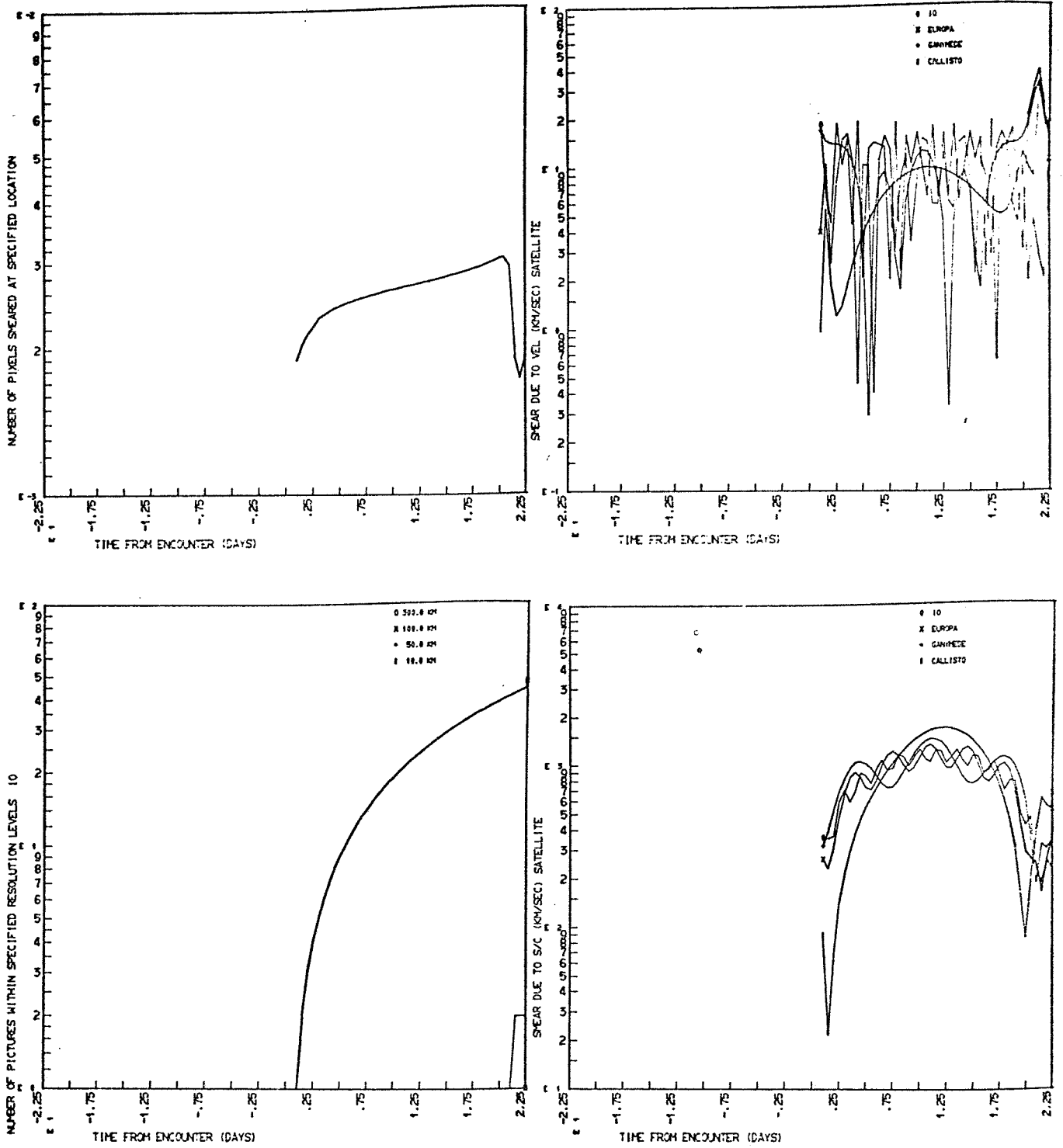


Fig. A-23 (cont)



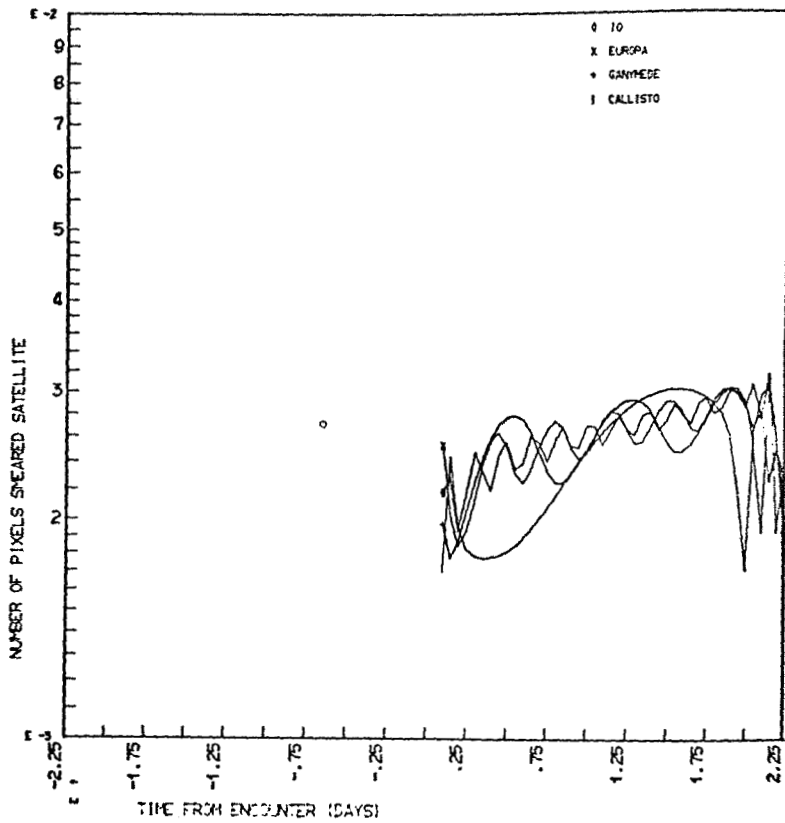
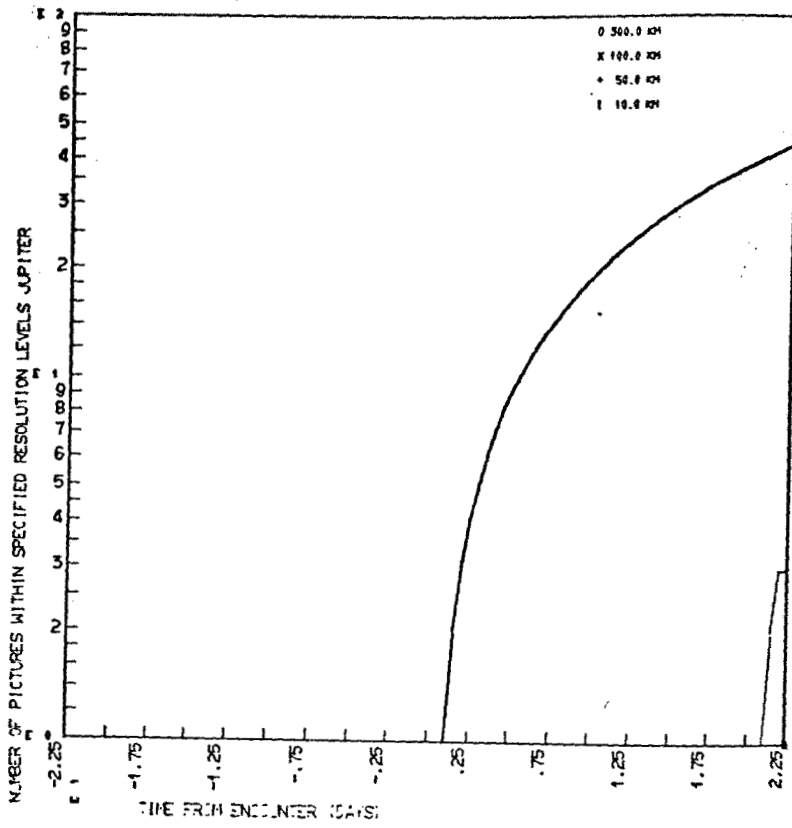


Fig. A-23 (concl)

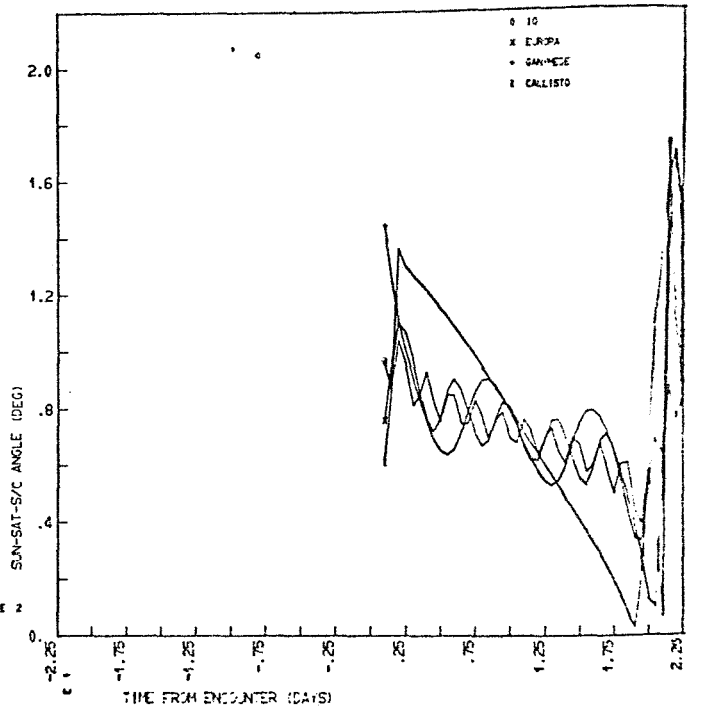
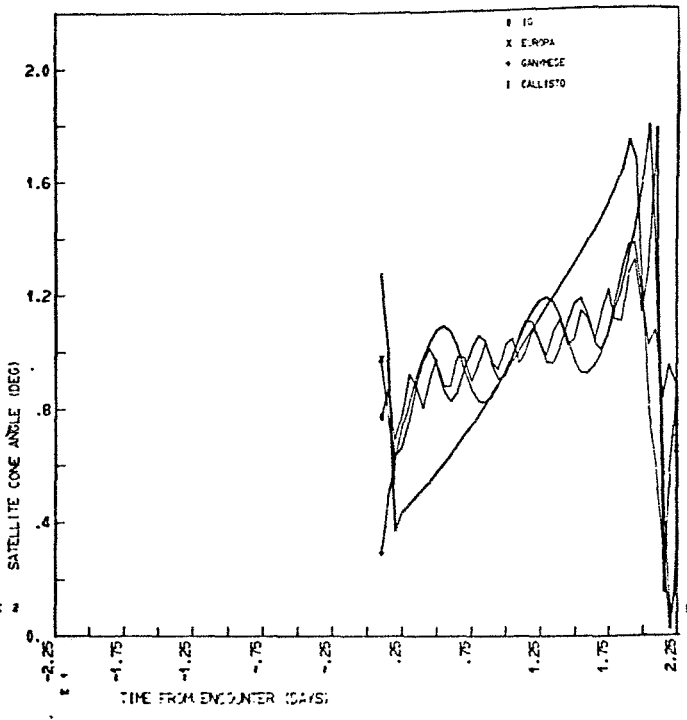
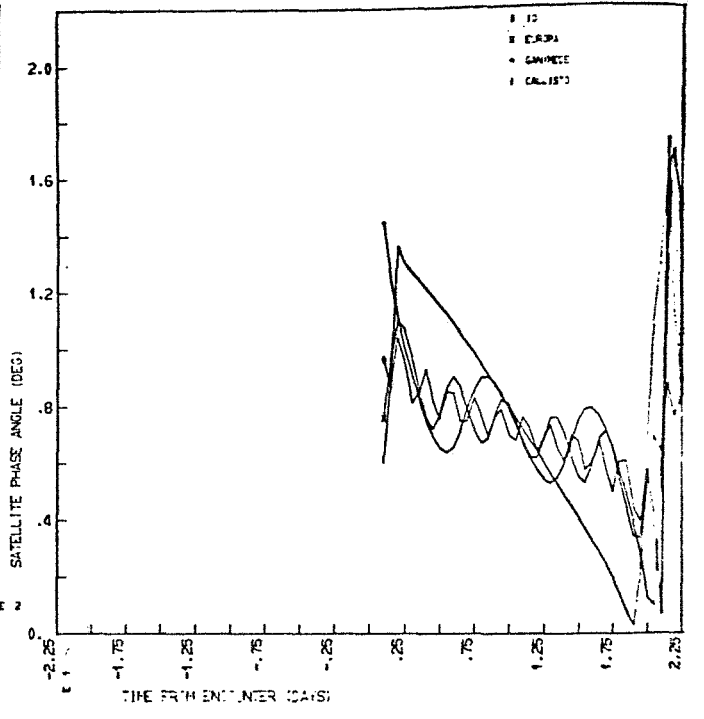
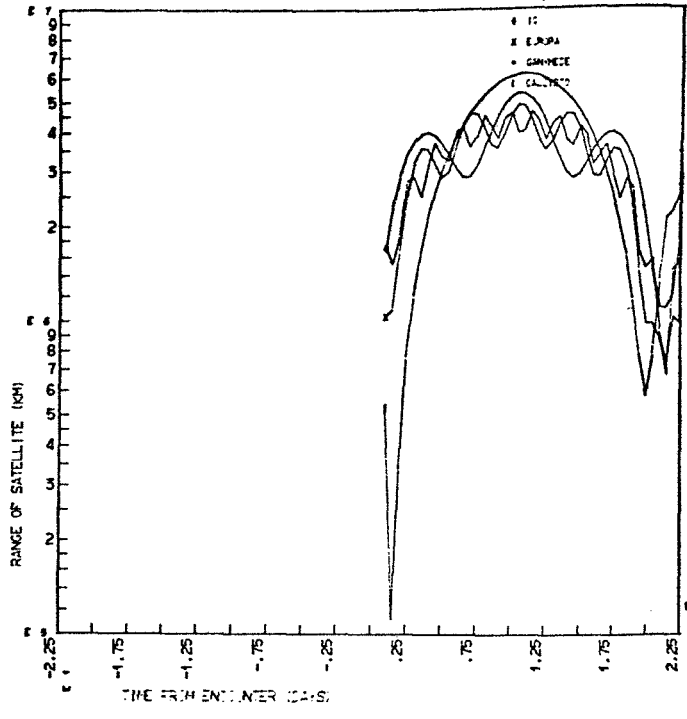


Fig. A-24 Satellite Geometry Summaries

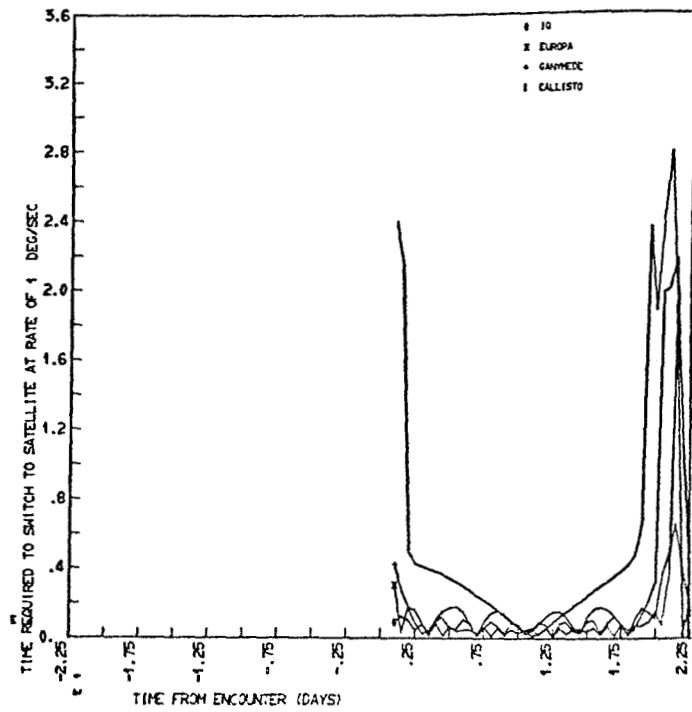
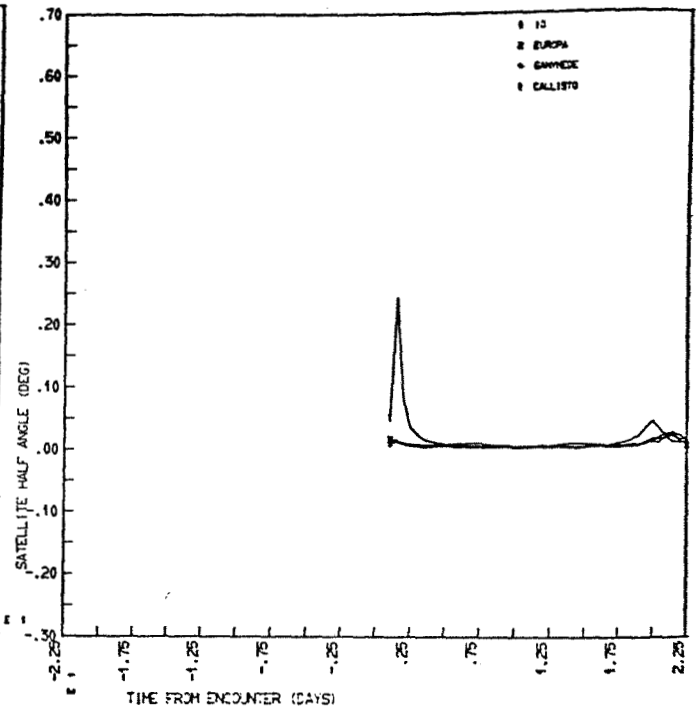
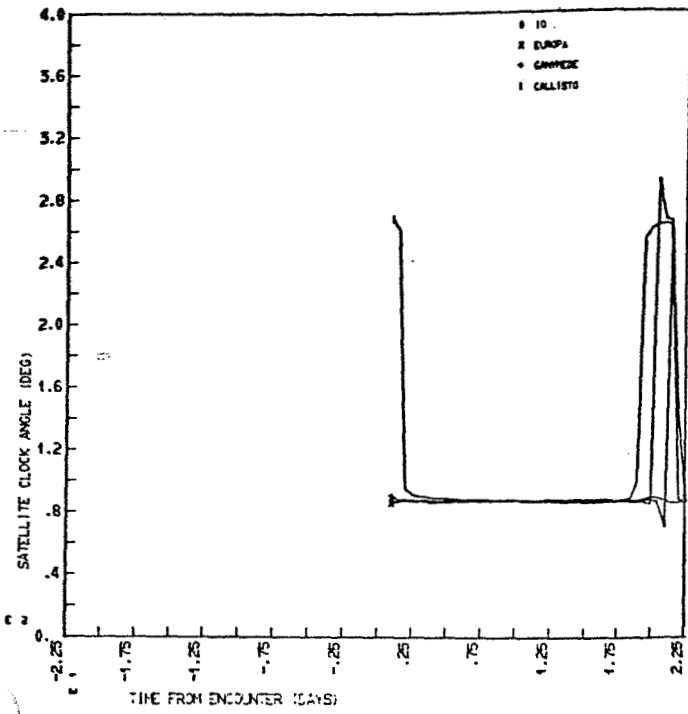


Fig. A-24 (concl)

5. Case 10

a. Input Data - This case is a Jupiter orbital mission that exercises the particle and field instrument subroutine. The input tabular listing and additional instrument values are given in Table A-27.

Table A-27 Case 10 Input Listing and Instrument Values

JUPITER CHECK OUT CASE NO 10

2	5.0000000	PLANET
3	4.0000000	SATEL
4	840201.00	DATE
6	1.0000000E+01	
7	2.2550000	STATE1
8	59.8840000	STATE2
9	70.6000000	STATE3
22	210.00000	INSTIT
61	0.	TSTAR
62	1.0000000	TSTOP
63	30.0000000	DTINST
69	2.0000000	CALCST
81	3.0000000	DPLQT
82	1.0000000	DPRNT
86	15.0000000	SATRNG
90	1111111.0	

JUPITER CHECK OUT CASE NO 10

FP CHARACTERISTICS FOR FIELDS AND PARTICLE INSTRUMENT

6	=	5.16000000E+01
7	=	6.58000000E+01
8	=	8.00000000E+01
9	=	1.90000000E+02
10	=	2.00000000E-06

PERIAPSIS STATE VECTOR

-1.55815045E+05	-4.03051226E+04	3.07916842E+02
9.75526852E+00	-3.77127648E+01	0.

VIEW FROM INPUT VIEWPOINT  
VIEW FROM INPUT VIEWPOINT

JUPITER CHECK OUT CASE NO 10

XZ(I) VALUES IN STORAGE

1	0	0.	2	1	5.000000000E+00
3	1	4.000000000E+00	4	1	8.402010000E+05
5	0	0.	6	1	1.000000000E+01
7	1	2.255000000E+00	8	1	5.988400000E+01
9	1	7.068000000E+01	10	0	0.
11	0	0.	12	0	0.
13	0	0.	14	0	0.
15	0	3.000000000E+00	16	0	0.
17	0	0.	18	0	0.
19	0	0.	20	0	0.
21	0	0.	22	1	2.100000000E+02
23	0	0.	24	0	-7.1738305547E+57
25	0	-7.1738305547E+57	26	0	0.
27	0	0.	28	0	0.
29	0	0.	30	0	0.
31	0	0.	32	0	0.
33	0	0.	34	0	0.
35	0	0.	36	0	0.
37	0	0.	38	0	0.
39	0	0.	40	0	0.
41	0	0.	42	0	0.
43	0	0.	44	0	0.
45	0	0.	46	0	0.
47	0	0.	48	0	0.
49	0	0.	50	0	0.
51	0	0.	52	0	0.
53	0	0.	54	0	0.
55	0	0.	56	0	0.
57	0	0.	58	0	0.
59	0	0.	60	0	0.
61	1	0.	62	1	1.000000000E+00
63	1	3.000000000E+01	64	0	0.
65	0	0.	66	0	0.
67	0	0.	68	0	0.
69	1	2.000000000E+00	70	0	0.
71	0	0.	72	0	0.
73	0	0.	74	0	0.
75	0	0.	76	0	0.
77	0	0.	78	0	0.
79	0	0.	80	0	0.
81	1	3.000000000E+00	82	1	1.000000000E+00
83	0	0.	84	0	0.
85	0	0.	86	1	1.500000000E+01
87	0	0.	88	0	0.
89	0	0.	90	1	1.111110000E+06
91	0	0.	92	0	0.
93	0	0.	94	0	0.
95	0	0.	96	0	0.

b. Output Data - Outputs are trajectory trace, showing bow shock and magnetopause input locations (Fig. A-25), dipole magnetic field lines for an input surface strength and magnetic pole tilt (Fig. A-26), minimum detectivity versus distance (Fig. A-27), and cone and clock angles versus time to look down the field line vector (Fig. A-28).

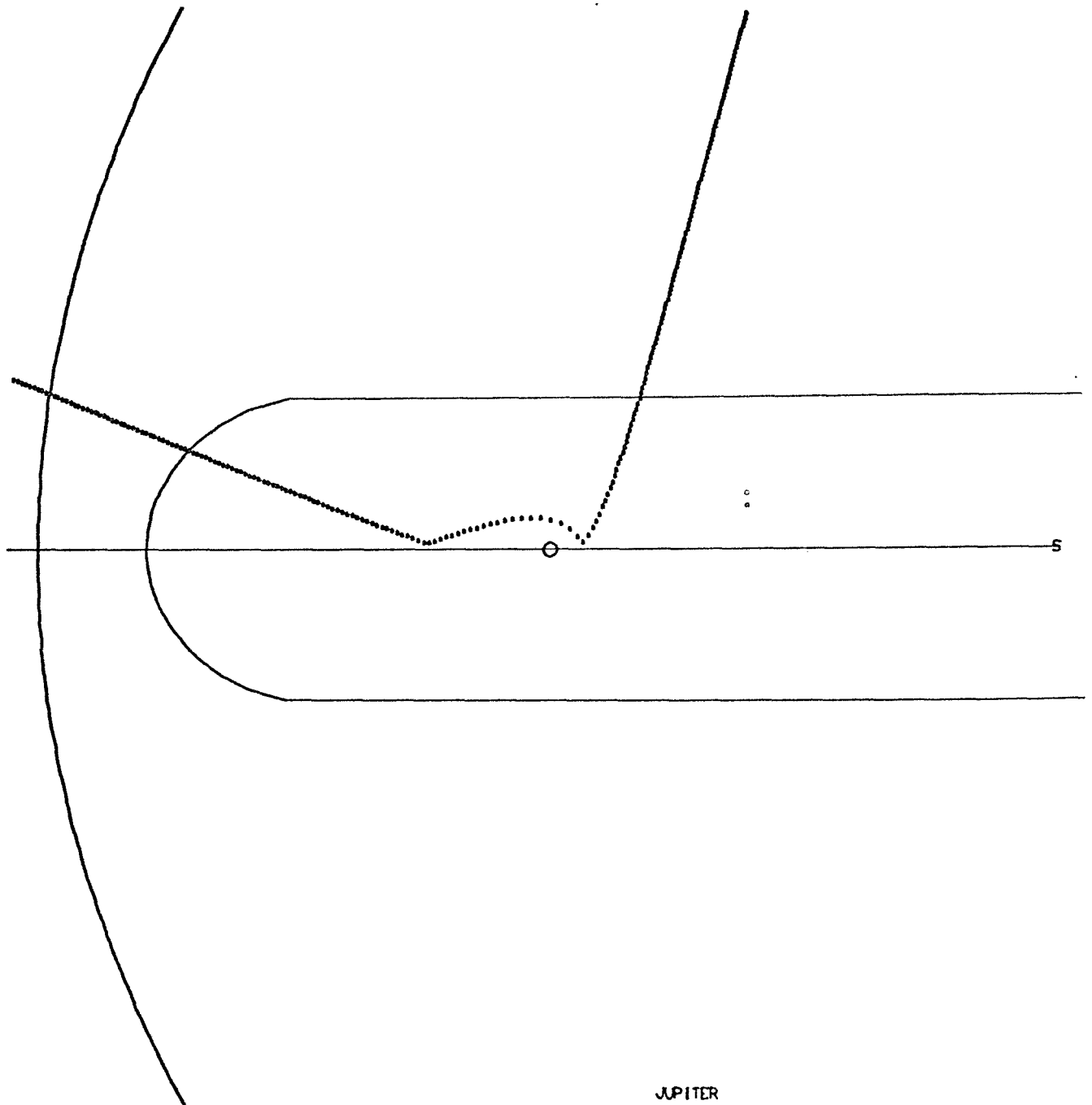


Fig. A-25 Bow Shock and Magnetopause Input Locations

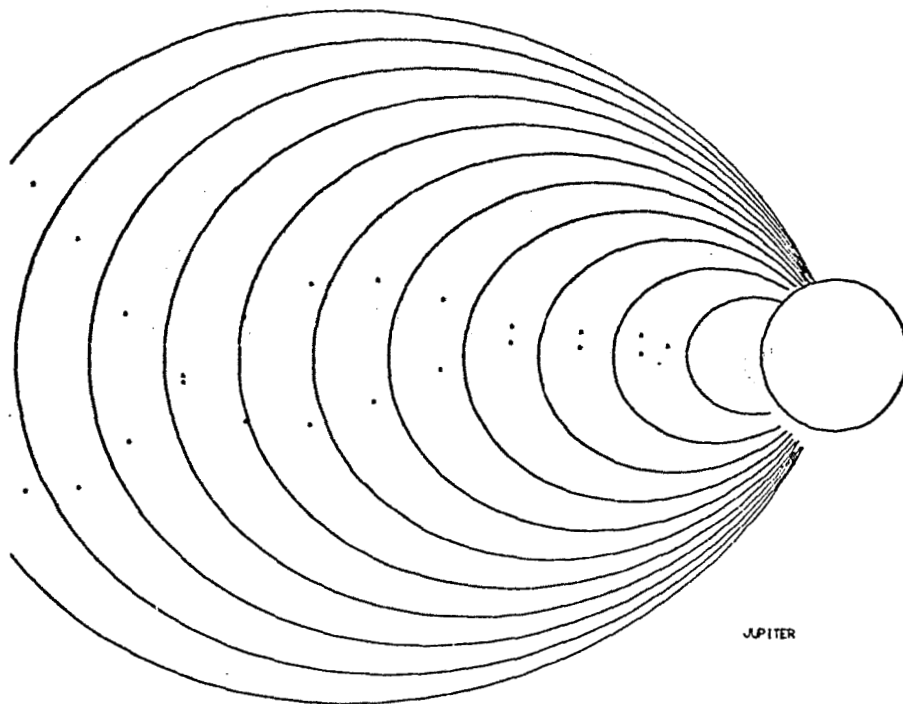


Fig. A-26 Dipole Magnetic Field

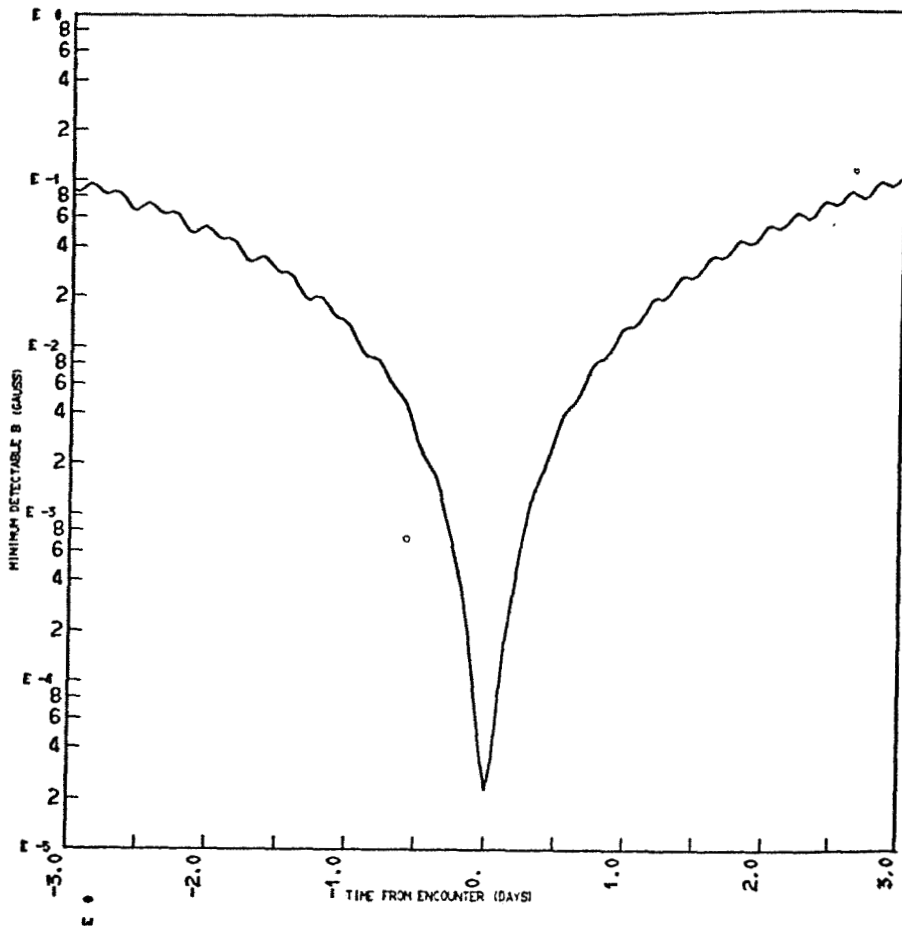


Fig. A-27 Minimum Detectivity

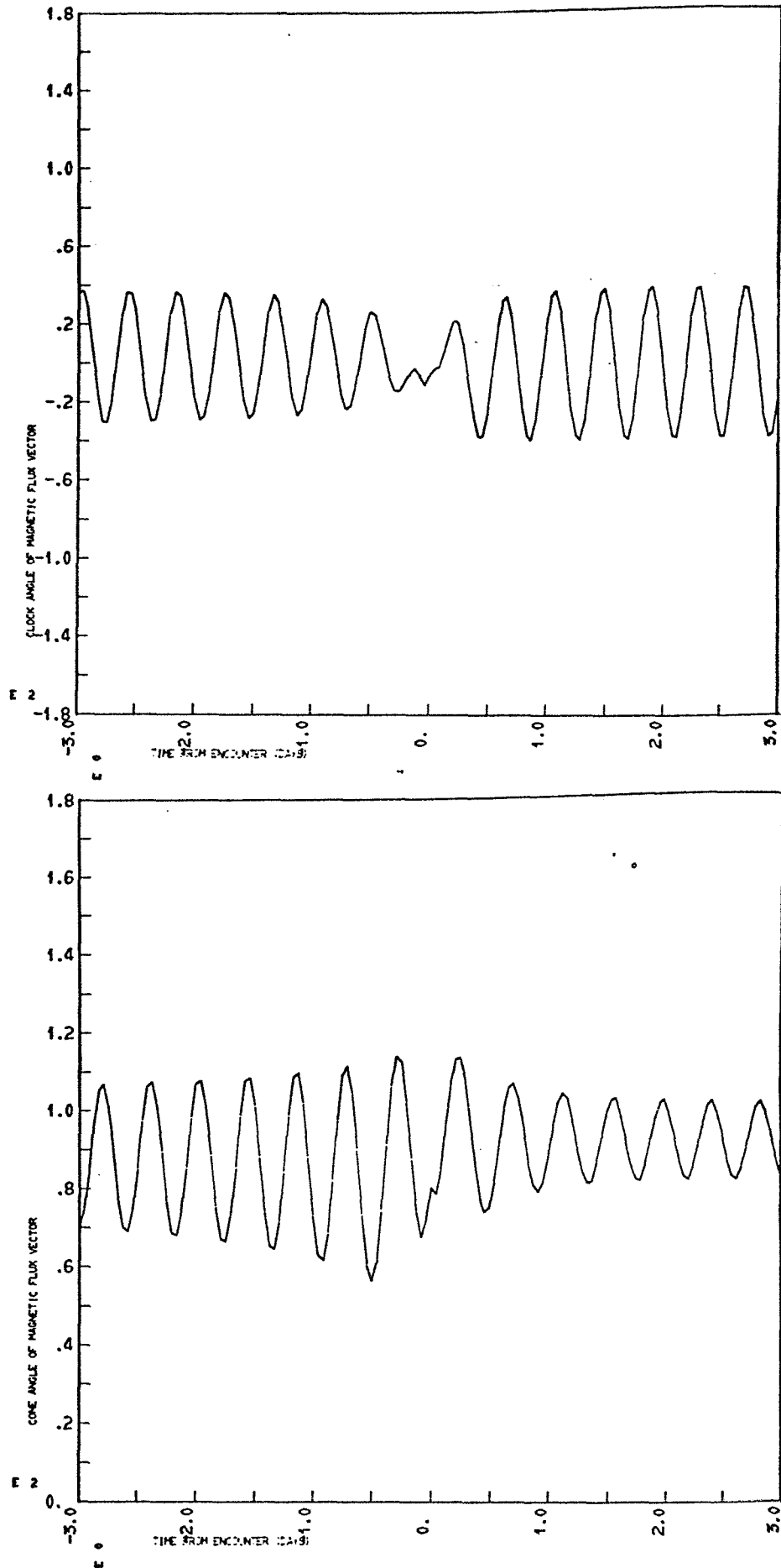


Fig. A-28 Cone and Clock Angles



MCR-71-181

APPENDIX B

COMPUTER PROGRAM CARD LISTING

```

MARTIN*GT.MAIN
1 COMMON/HEADING/TITLE(13)
2 COMMON/CHARLI /NCONF,NREC ,IP,IVS,NSC,IFLST,NCR
3 DOUBLE PRECISION JDE
4 DOUBLE PRECISION JOV, SAVE
5 COMMON/JDAYS/JOV,TT
6 COMMON /PLCONS/GVS,GVPL(12),PS,RPL(12),SNAMF(2),PLNAME(2,12),
7 X SPV(3),PLPV(3,12),SVE(3),PLVE(3,12),SROT,PLROT(12),SOBL,PLORL(12)
8 COMMON/REVER/ROTW(3)
9 COMMON/CHARAC/P(60)
10 COMMON/FOROUT/DUMMYB(13),IPCN,DUMMYC(6)
11 COMMON/CELEST/C(3),S(3),SN(3)
12 COMMON/STUFF/XN(3),DUMMF(110)
13 COMMON/STUFI/XSAT(3)
14 COMMON/GEOM/XE(3),XP(3)
15 COMMON/CAM/CCONF(200),CCLOCK(200)
16 COMMON/TEST/ITEST(97)
17 COMMON/FLAGS/IFLT,IFLPL,IFLPR
18 COMMON/TCONS/TCONS(200)
19 COMMON /TRA/TRACE,DUMMYA(13)
20 COMMON/XZ/XZ(97),IXZ6 /VAR/VAR(97)
21 COMMON/FLYBY/DUM1(6),X(3),DUM2(9)
22 DATA C/-.06034330,.23724160, -.96957469/
23 FLAG(A,B)=AMOD(A,B)
24
25 C
26 C INITIALIZATION AND ONE TIME CALCULATIONS
27 C
28 1000 CONTINUE
29 REWIND 13
30 REWIND 8
31 REWIND 9
32 REWIND 10
33 REWIND 11
34 REWIND 12
35 RPD=3.14159/180.0
36 I=1
37 NREC=1
38 NCB=0
39 IFLST=0
40 CALL PLANET(5HNOTRA)
41 CALL INPUT(NP)
42 IF(XZ(85).NE.0) IFLST=1
43 DATE=XZ(4)
44 IP=XZ(2)
45 NSC=XZ(18)
46 CALL CPLANN(IP)
47 CALL SCROT(ROTW)
48
49 C
50 C RETRIEVE INSTRUMENT CHARACTERISTICS
51 C
52 INST=1
53 IF(ITEST(22).NE.0) INST=XZ(22)+0.01
54 INSTR=INST/100 + 1
55 GO TO (10,11,12,13,14),INSTR
56 10 CALL NOCHAR(INST)
57 GO TO 20
58 11 CALL TVCHAR(INST)
59 GO TO 20
60 12 CALL FPCHAR(INST)
61 GO TO 20
62 13 CALL IRCHAR(INST)
63 GO TO 20
64 14 CALL UVCHAR(INST)
65
66 C
67 C SET UP TIME SEQUENCING FOR CALCULATIONS
68 C
69 20 CONTINUE
70 IF(DATE.GE.0) CALL CALNDR(JDE,2HJD,DATE,5HCAL19)
71 IF(DATE.LT.0) CALL CALNDR(JDE,2HJD,=DATE,5HMODJD)
72 IXZ6 = XZ(6) + .4
73 CALL ORBIN(XZ(7),IXZ6)
74 SAVE=JOV
75 JOV=JDE
76 CALL PSATP
77 JOV=JDE
78 IF(INSTR.EQ.3) CALL FIELDS
79 JOV=SAVE
80 IF(INSTR.EQ.3) GO TO 800
81 CALL TCON(NP)
82 INTPL=1
83 INTPR=1
84 IF(ITEST(81).EQ.1) INTPL=XZ(81)
85 IF(ITEST(82).EQ.1) INTPR=XZ(82)
86 RAPER=RPL(IP)
87 IF(ITEST(85).EQ.1) CALL PSCONS(RAPER,6HRADIUS,IVS,IP)
88 NPC=P(39)
89
90 C
91 C START LOOP
92 C
93 5 JOV=JDE+TCONS(I)
94 IVS=XZ(3)
95 IFLPL=0
96 IFLPR=0
97 IF((FLOAT((I-1)/INTPL)).EQ.(FLOAT(I)-1.0)/FLOAT(INTPL)) IFLPL=1
98 IF((FLOAT((I-1)/INTPR)).EQ.(FLOAT(I)-1.0)/FLOAT(INTPR)) IFLPR=1
99 CALL TCONV(TT,3HSEC,TCONS(I),3HDAY)

```

```

96      IF(NSC.GE.0) CALL PLPOS(XE,JDV,3)
97      CALL PLPOS(XP,JDV,IP)
98      B  IF(IVS.GT.0) CALL PLASAT(XSAT,JDV,IVS,IP)
99      CALL ORBIN(XZ(7),IXZ6)
100     CALL ORBPOS(X,TT)
101     CALL VEQUAL(XN,X)
102     TX=TT/86400.
103     IPCN=(I-1)*NPC+1
104     TMAGX=ABSV(X)
105     TANGLE=ASIN(RAPER/TMAGX)*RPD
106     IF(ITEST(83).EQ.1.AND.TMAGX.GT.XZ(83)) GO TO 102
107     IF(ITEST(84).EQ.1.AND.TANGL.LT.XZ(84)) GO TO 102
108     GO TO 50
109     102 IFLPL = 0
110     IFLPR = 0
111     50  CONTINUE
112     CALL VCOMB(S,XP,-1.0,X,-1.0)
113     CALL CACL
114     GO TO (800,210,220,230,240),INSTR
115     210 CONTINUE
116     C
117     C      TV ROUTINES
118     C
119     C      IF(IFLPL.EQ.1) CALL PIC2(P(44),P(45))
120     CALL RESO(4HCALC)
121     CALL SMEAR(4HCALC)
122     CALL MRLC(4HCALC)
123     GO TO 290
124     220 CONTINUE
125     C
126     C      FP ROUTINES
127     C
128     GO TO 290
129     230 CONTINUE
130     C
131     C      IR ROUTINES
132     C
133     GO TO 290
134     240 CONTINUE
135     C
136     C      UV ROUTINES
137     C
138     290 CONTINUE
139     CALL OTJAZ(4HCALC)
140     IF(IFLPR.EQ.1) CALL OUTS
141     I=I+1
142     NREC=NREC+1
143     IF(I.LT.NP+1) GO TO 5
144     C
145     C      END LOOP
146     END FILE 13
147     END FILE 12
148     END FILE 11
149     END FILE 10
150     END FILE 9
151     END FILE 8
152     C
153     ZOUT=XZ(90)
154     IF(FLAG(ZOUT,10.).GT.0.) CALL GEOPLT
155     CALL ADV
156     GO TO (800,310,320,330,340),INSTR
157     310 CONTINUE
158     C
159     C      TV ROUTINES
160     C
161     IF(FLAG(ZOUT,100.).GE.10.) CALL RESO(4HPLT)
162     IF(FLAG(ZOUT,1000.).GE.100.) CALL SMEAR(4HPLT)
163     GO TO 390
164     320 CONTINUE
165     C
166     C      FP ROUTINES
167     C
168     GO TO 390
169     330 CONTINUE
170     C
171     C      IR ROUTINES
172     C
173     GO TO 390
174     340 CONTINUE
175     C
176     C      UV ROUTINES
177     C
178     390 CONTINUE
179     IF(FLAG(ZOUT,10000.).GE.1000.) CALL MRLC(4HPLT)
180     IF(FLAG(ZOUT,100000.).GE.10000.) CALL OTJAZ(4HPLT)
181     IF(FLAG(ZOUT,1000000.).GE.100000.) CALL OTPLT
182     800 CONTINUE
183     IF(ITEST(96).EQ.0) GO TO 1000
184     IF(XZ(96).EQ.0.0) GO TO 1000
185     IF(XZ(96).NE.1.0) CALL STERM
186     DO 2000 I=1,96
187     ITEST(I)=0
188     XZ(I)=0.0
189     2000 CONTINUE
190     IFLST=0
191     NSC=0

```

```

192      NCB=0
193      NCODE=0
194      IFLT=0
195      IFLPL=1
196      IFLPR=1
197      GO TO 1000
198      900  FORMAT(3E25,R)
199      END

```

OPRT GT.CACL

MARTIN\*GT.CACL

```

1      SUBROUTINE CACL
2      C
3      C
4      C
5      C
6      COMMON/JUNK/R,EFB,SR(8),SEFB(R)
7      COMMON/POREAR/SSV(8),SAF(8),HANG2,DCNCLK(8)
8      COMMON/HEDING/TITLE(13)
9      COMMON/TNME/TVNAME(5)
10     DIMENSION ZSAT(3),VORB(3)
11     DATA AU/1.49599E08/
12     DATA WTERG/1.E+7/
13     DATA NCHGT/0/,NCHGF/0/
14     COMMON/TEST/ITEST(97)
15     COMMON/XZ/XZ(97)
16     COMMON/CHARAC/P(60)
17     COMMON/FLYBY/DUM(6),XN(3),DUMM(9)
18     COMMON/CELEST/C(3),S(3),SN(3)
19     COMMON/GEOM/XE(3),XP(3)
20     COMMON/PHASER/PHAS(R),SRAT(3,R)
21     COMMON/STUFF/X(3),TARGE(3),POTV(3),VSV(3,R),VVSAT(3,R),SVSV(3,8)
22     X,RCCL(3),DTARE(X),DPOTV(3)
23     COMMON/STUF1/XSAT(3)
24     COMMON /PLCONS/GVS,GMPL(12),RS,RPL(12),SNAME(2),PLNAME(2,12),
25     X SPV(3),PLPV(3,12),SVE(3),PLVE(3,12),SROT,PLROT(12),SOBL,PLOBL(12)
26     COMMON/PCOORD/PV(3),VE(3),PM(3)
27     COMMON/VCONS/UX(3),UY(3),UZ(3),PI
28     COMMON/REVER/ROTW(3)
29     COMMON/CHARLI /NCODE,NREC ,IP,IVS,NSC,IFLST,NCR
30     DIMENSION U(3),XSN(3),UXSS(3),TARG(3),XTFR(3)
31     X, XSAT1(3),RAMP(3),VV(3)
32     X,RAD1(3),C2(3),C1(3),XS(3),XSS(3),VSAT(3)
33     X,TARGV(3) ,UXP(3),ROTC(3)
34     COMMON/FOFOUT/PNXEP,ENERGY,PERCT,IDN,R(3),RSAT(3),TAPGP(3),IPCN
35     X,FRACT,PHASED,PHASEP ,POWLN,NDN,PPERDN
36     COMMON/FLAGS/IMODE,IFLPL,IFLPP
37     COMMON/CAV/CCONE(200),CCLOCK(200)
38     DOUBLE PRECISION JDV
39     COMMON/JDAYS/JDV,TT
40     DIMENSION NS(9)
41     DATA NS0/9/,NS/0,0,1,2,4,7,5,2,0/
42     T=TT/3600.
43     TTT=TT/86400.
44     XPM=(ABS(XP)/AU)**2
45     TS1=XZ(87)
46     TS2=XZ(88)
47     ISAVE=0
48     NCB=0
49     IDN=2.**P(14)+0.01
50     PI=3.1415926536
51     C
52     C
53     C
54     CALL VUNIT(UXP,XP)
55     IF(NSC.LT.0) GO TO 6
56     CALL VDIF (XP,XP,XE)
57     6 CALL VSCALE(XS,XP,-1.)
58     CALL VDIF (XS,XS,X)
59     CALL VSCALE(R,X,-1.)
60     CALL RCNCLK(R,XS)
61     CALL VUNIT(U ,X)
62     CALL VSCALE(UXP,UXP,-1.)
63     PHASE=ACOS(DOT(UXP,U ))
64     CALL PGLOBE(PM,JDV,IP)
65     CALL VSCALE(TARG,U , RPL(IP))
66     CALL VDIF (RADP,TARG,X)
67     HANG=ASIN(RPL(IP)/R(1))*180./PI
68     HANG2=2.*HANG
69     C
70     C
71     C
72     IF(IMODE.NE.0) GO TO 10
73     IF(PHASE.LT.PI/2.) GO TO 20
74     C
75     SUBVEHICLE POINT IN SHADOW
76     CALL VCROSS(XSN,UXP,U)
77     CALL UCROSS(XTER,XSN,UXP)
78     ANGL=90.-HANG
79     ANGL=PHASE*180./PI-ANGL
80     DEL=(90.-ANGL)/2.
81     ANGL=ANGL+DEL

```

```

81 C PICTURE CENTER BISECTS ANGLE BETWEEN LIT L1M + TERMINATOR
82 CALL VCOMB(TARG,UXP,COS(ANGL*PI/180.),XTER,SIN(ANGL*PI/180.))
83 CALL VSCALE(TARG,TARG,RPL(IP))
84 C RADP IS VECTOR FROM S/C TO PIC CENTER
85 CALL VDIF(RADP,TARG,X)
86 CALL VEQUAL(RAD1,RADP)
87 CALL RCNCLK(RAD1,XS)
88 GO TO 20
89 C
90 C
91 C
92 10 CALL VLOAD(RCCL,1.,CCONE(NREC),CLOCK(NRFC))
93 CALL SPHERE(RCCL,RCCL,4HFROM,5HPOLAR,6HDEGREE)
94 CALL VTRANS(RADP,RCCL,4HFROM,C,XS)
95 CALL VSCALE(U,U,-1.)
96 CA=DOT(U,RADP)
97 SROOT=RPL(IP)**2-R(1)**2*(1.-CA*CA)
98 C IF SROOT LE 0 CENTER OF FRAME IS OOF PLANET
99 IF(SROOT.LT.0.) SROOT=0.
100 TARGM=R(1)*CA-SORT(SROOT)
101 CALL VCOMB(TARG,RADP,TARGM,U,-R(1))
102 CALL VSCALE(RADP,RADP,TARGM)
103 C
104 C
105 C
106 20 CONTINUE
107 CALL VTRANS(TARGP,TARG,2HTO,PM,PV)
108 CALL VCROSS(TARGV,U7,TARGP)
109 CALL SPHERE(TARGP,TARGP,2HTO,6HLATLON,6HDEGREE)
110 CALL VSCALE(TARGV,TARGV,PLPOT(IP)/86400.*2.*PI)
111 CALL VTRANS(TARGE,TARGV,4HFROM,PM,PV)
112 CALL ORBVEL(VV,TT)
113 CALL VDIF(VV,TARGE,VV)
114 EM=180.-ANGV(RADP,TARG,6HDEGREE)
115 C
116 C
117 C
118 IF(IVS.EQ.0) GO TO 8
119 C XSS IS VECTOR FROM SATELLITE TO S/C
120 CALL VDIF(XSS,X,XSAT)
121 CALL VUNIT(UXSS,XSS)
122 C ASSUMES SUN VECTOR IS SAME AS PLANETS
123 PHASES=ACOS(DOT(UXP,UXSS))
124 CALL VSCALE(RSAT,XSS,-1.)
125 CALL RCNCLK(RSAT,XS)
126 C CHECK TO SEE IF PLANET OBSCURES SATELLITE
127 IF(ANGV(X,XSS,6HDEGREE).LT.HANG.AND.RSAT(1).GT.R(1))
128 XPRINT 999,TTT
129 8 CONTINUE
130 C
131 C
132 C
133 CALL ORBVEL(VORB,TT)
134 NSP=NS(IP)
135 IF(NSP.EQ.0) GO TO 106
136 ZAP=R(3)
137 IF(ZAP.GT.180.) ZAP=ZAP-360.
138 DO 500 I=1,NSP
139 IS=I
140 IF(IP.EQ.6.AND.IS.EQ.1) GO TO 500
141 CALL PLASAT(ZSAT,JOV,IS,IP)
142 CALL VDIF(VSV(1,IS),X,ZSAT)
143 SSV(I)=ANGV(VSV(1,I),XS,6HDEGREE)
144 CALL PSCONS(RPSAT,6HRADIUS,I,IP)
145 RPSC=ABSV(VSV(1,I))
146 600 SAF(I)=ASIN(RPSAT/RPSC)*(360./PI)
147 CALL VUNIT(UXSS,VSV(1,IS))
148 PHAS(I)=ACOS(DOT(UXP,UXSS))
149 CALL VSCALE(SRAT(1,IS),VSV(1,IS),-1.)
150 CALL RCNCLK(SRAT(1,IS),XS)
151 SAP=SRAT(3,IS)
152 IF(SAP.GT.180.) SAP=SAP-360.
153 DCNCLK(I)=ABS(SRAT(2,IS)-R(2)) + ABS(SAP-ZAP)
154 CALL PLASAT(XSAT1,JOV+1./8640.,IS,IP)
155 CALL VDIF(XSAT1,XSAT1,ZSAT)
156 CALL VSCALE(XSAT1,XSAT1,.1)
157 CALL VDIF(VVSAT(1,IS),VORB,XSAT1)
158 CALL VSCALE(VSV(1,IS),VSV(1,IS),-1.)
159 CALL UCROSS(C2,XS,VSV(1,IS))
160 CALL UCROSS(C1,C2,VSV(1,IS))
161 CALL VTRANS(VVSAT(1,IS),VVSAT(1,IS),2HTO,C1+VSV(1,IS))
162 CALL VTRANS(ROTC,ROTW,4HFROM,C,XS)
163 CALL VTRANS(ROTC,ROTC,2HTO,C1+VSV(1,IS))
164 CALL VTRANS(VSV(1,IS),VSV(1,IS),2HTO,C1+VSV(1,IS))
165 CALL VCROSS(SVSV(1,IS),ROTC,VSV(1,IS))
166 IF(IP.EQ.6.AND.I.EQ.1) GO TO 700
167 IF(ISAVE.NE.0) GO TO 650
168 PHASES=PHAS(I)
169 RMIN=SRAT(1,I)
170 CALL VEQUAL(XSAT,ZSAT)
171 ISAVE=I
172 650 IF(SRAT(1,I).GT.RMIN) GO TO 700
173 PHASES=PHAS(I)
174 RMIN=SRAT(1,I)
175 CALL VEQUAL(XSAT,ZSAT)
176 ISAVE=I

```

```

177 700 CONTINUE
178 500 CONTINUE
179 IF(XZ(3).NE.0) GO TO 106
180 CALL VEQUAL(RSAT,SPAT(1,ISAVF))
181 IF(RSAT(1).GT.XZ(R6).OR.(T.GT.TS1.AND.T.LT.TS2)) GO TO 105
182 IVS=ISAVF
183 CALL VUNIT(UXSS,VSV(1,ISAVE))
184 CALL VEQUAL(XSS,VSV(1,ISAVF))
185 C
186 C
187 C
188 106 IF(IFLST.EQ.1) GO TO 99
189 C RADP IS VECTOR FROM S/C TO PIC CENTER
190 IF(ITEST(R6).EQ.1.AND.RSAT(1).LT.XZ(R6)) GO TO 99
191 GO TO 105
192 99 CALL PSCONS(RADS,6HRADIUS,IVS,IP)
193 NCB=1
194 CALL VCOMB(RADP,XSS,-1.,UXSS,RADS)
195 CALL VSUM(TARG,XSS,RADP)
196 CALL VTRANS(TARGP,TARG,2HTO,PM,PV)
197 CALL SPHERE(TARGP,TARGP,2HTO,6HLATLON,6HDEGREE)
198 CALL PLASAT(XSAT1,JDV+1./8640.,IVS,IP)
199 CALL VDIF(VSAT,YSAT1,XSAT)
200 CALL VSCALE(VSAT,VSAT,.1)
201 CALL ORBVEL(VV,TT)
202 CALL VDIF(VV,VV,VSAT)
203 CALL VEQUAL(XN,XSS)
204 IF(IVS.NE.0) ISAVE=IVS
205 SSB=SB(ISAVE)/XPM
206 SBBEF=SEFB(ISAVE)/XPM
207 PZ=(SIN(PHASES)+(PI-PHASES*COS(PHASES))/PI)
208 POWER=SBBEF/(4.*P(51)**2)*PZ*WTERG
209 POWLN=SSB*PZ*WTERG
210 105 CONTINUE
211 C
212 C
213 C
214 C
215 IF(NCB.EQ.1) GO TO 101
216 BB=B/XPM
217 BBEF=EFB/XPM
218 C LAMBERT PLANET PHASE FUNCTION
219 PZ=(SIN(PHASE)+(PI-PHASE*COS(PHASE))/PI*ABS(COS(EM*PI/180.)))
220 POWLN=BB*PZ*WTERG
221 POWER=BBEF/(4.*P(51)**2)*PZ*WTERG
222 101 CONTINUE
223 ENERGY=POWER*P(26)
224 IF(ENERGY<0.95*P(16))2,2,1
225 1 DTMIN=(.85*(P(16)-P(15))+P(15))/POWER
226 P(26)=DTMIN
227 WRITE(6,1005)TITLE,TVNAME
228 WRITE(6,1000)ENERGY,DTMIN
229 ENERGY=0.85*(P(16)-P(15))+P(15)
230 WRITE(6,1001)ENERGY
231 NCHGT=NCHGT+1
232 WRITE(6,1004)NCHGT
233 IF(DTMIN<1.E-4)3,2,2
234 3 DTMIN=1.E-4
235 P(26)=DTMIN
236 POWXX=POWER*(P(51)**2)/(P(52)**2)
237 FILTF=DTMIN*POWXX/ENERGY
238 P(51)=P(52)*SQRT(FILTF)
239 WRITE(6,1002)FILTF
240 NCHGF=NCHGF+1
241 WRITE(6,1004)NCHGF
242 2 IF(ENERGY<P(15))4,5,5
243 4 IF(POWER.LT.1.E-8)GOTO11
244 DTMAX=P(15)/POWER
245 ENERGY=P(15)
246 P(26)=DTMAX
247 WRITE(6,1003)DTMAX
248 GO TO 5
249 11 WRITE(6,1006)POWER
250 5 CONTINUE
251 FRACT=0.0
252 IF(ENERGY.GT.P(15).AND.ENERGY.LT.P(16))FRACT=(ENERGY-P(15))/
253 (P(16)-P(15))
254 XDN=IDN
255 NDN=FRACT*XDN + 0.001
256 EPERDN=(P(16)-P(15))/XDN
257 PERCT=FRACT*100.
258 C
259 C
260 C
261 CALL UCROSS(C2, XS,RADP)
262 CALL UCROSS(C1,C2,RADP)
263 CALL VPOTAT(C1,C1,RADP,TWIST*PI/180.)
264 CALL VTRANS(TARGE,VV,2HTO,C1,RADP)
265 CALL VTRANS(RCCL,RADP,2HTO,C1,RADP)
266 CALL VTRANS(ROTC,ROTV,4HFROM,C,XS)
267 CALL VTRANS(ROTC,ROTC,2HTO,C1,RADP)
268 CALL VCROSS(ROTV,ROTC,RCCL)
269 SMEAR=ABSV(TARGE)
270 SCMER=ABSV(ROTV)
271 PHASEP=PHASES*180./PI
272 PHASED=PHASE*180./PI

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273      WRITE(13)TT,X,XP,XSAT,XE,R,PHASE,RADP,TARGF,TARGP,RSAT,PHASES,XSS,
274      XJDV,EM
275      C
276      C
277      C
278      CALL VEQUAL(DTAPE,TARGE)
279      IF(NCB.EQ.1) CALL VEQUAL(DTAPR,VVSAT(1,IVS))
280      CALL VEQUAL(DROTV,ROTV)
281      IF(NCB.EQ.1) CALL VEQUAL(DROTV,SVSV(1,IVS))
282      RETURN
283      901  FORMAT(5X,11HPLANET DATA,/)
284      904  FORMAT(5X,14HPICTURE LAT = ,F6.2,5X,6HLON = ,F6.2,8HSMEAP = ,
285      XE16.8,5X,12HSMEAR S/C = ,F16.8)
286      902  FORMAT(5X,14HSATELLITE DATA,/)
287      906  FORMAT(5X,8HRANGE = ,E16.8,5X,7HCONE = ,F6.2,5X,8HCLKCK = ,F6.2,5X
288      X,8HPPHASE = ,F6.2,/)
289      999  FORMAT(28HSATELLITE OBSCURED BY PLANET,F6.2,19HDAYS FROM ENCOUNTER
290      X)
291      1000 FORMAT(1X ,19HEXPOSURE TOO HIGH ,E10.3,13H (ERGS/CM**2),/
292      $ 26H EXPOSURE TIME REDUCED TO ,E10.3,4H SEC)
293      1003 FORMAT(47H EXPOSURE LESS THAN MINIMUM , EXP TIME SET TO ,E10.3,/)
294      1001 FORMAT(13H EXPOSURE IS ,E10.3,12H (ERG/CM**2),)
295      1002 FORMAT(34H EXPOSURE TIME SET TO 0.1 MILLISEC,/
296      $27H REQUIRED FILTER FACTOR IS ,E10.3)
297      1004 FORMAT(5X,3HCHG,15)
298      1005 FORMAT(1H1,13A6,/,5A6/)
299      1006 FORMAT(/,35H POWER DENSITY THRU LENS TOO LOW = ,E15.8,14H FRGS/SQC
300      *M/SEC ,/)
301      END

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MPRT GT,CIRC

MARTIN\*GT.CIRC

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1      SUBROUTINE CIRC(R,D)
2      TH=0
3      1    X1=R*COS(TH)
4      Y1=R*SIN(TH)
5      10   TH=TH+D
6      IF(ABS(Y1).GT.2.625) GO TO 1
7      X2=R*COS(TH)
8      Y2=R*SIN(TH)
9      IF( ABS(Y2).GT.2.625) GO TO 12
10     CALL LINE(X1,Y1,X2,Y2)
11     Y1=Y2
12     X1=X2
13     IF (TH-6.2832)10,11,11
14     11   RETURN
15     END

```

MPRT GT,FIELDS

MARTIN\*GT.FIELDS

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1      SUBROUTINE FIELDS
2      COMMON / XZ / XZ(97), IXZ6
3      DIMENSION DIRB(3),REF(3),XMA(3),YMA(3),ZMA(3),XE(3),XP(3)
4      COMMON/CHARAC/PF(60)
5      COMMON /PLTBUF/RUF(20)
6      COMMON /PLCONS/GMS,GMPL(12),RS,RPL(12),SNAME(2),PLNAME(2,12),
7      X SPV(3),PLPV(3,12),SVE(3),PLVE(3,12),SROT,PLROT(12),SOBL,PLORL(12)
8      COMMON/PLOTTER/PEN,RX(3),SCALE,R2,VT(3),VR(3),VW(3),RPP,TANR
9      COMMON/PCOORD/PV(3),VE(3),PM(3)
10     COMMON/CHARLI /ICODE,NREC ,IP,IVS,NSC,IFLST,NCB
11     COMMON/ORBITO/DUMZ(7),E,H,PP,AA,DUMZZ(4)
12     DOUBLE PRECISION JD,JDV
13     COMMON/JDAYS/JDV,TT
14     DIMENSION BLNK(10), BLNK2(10)
15     DATA BLNK / 3*1H , 15HMAGNETIC DIPOLE, 4*1H /
16     DATA BLNK2 / 3*1H , 30HMAGNETO-PAUSE AND 90W SHOCK , 2*1H /
17     DIMENSION XM(3),X(3),XF(3),V(3),XS(3),SN(3)
18     DIMENSION COORD(4)
19     GM = GMPL(IP)
20     PI=3.14159
21     RTD=57.295780
22     CALL ARCSTP(5,)
23     SENS=PF(10)
24     XLAT=PF(8)
25     XLON=PF(9)
26     DPAUSE=PF(6)*RPL(IP)
27     DINC=PF(7)*RPL(IP)
28     A=AA
29     ECC=E
30     AE=ECC
31     DPAUSE=64.*RPL(IP)
32     DINC=0.275*DPAUSE
33     DELANG=0.
34     DELTR=DELANG/RTD
35     R2=0.
36     CALL ORBIN(XZ(7),IXZ6)

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37      CALL ORBPOS(X,0.)
38      SCALE=ARSV(X)*5.
39      IF(SCALE.LT.11.*RPL(IP)) SCALE=11.*RPL(IP)
40      SCALE=SCALE+RPL(IP)*1.1
41      COORD(1) = SCALE - RPL(IP)*1.1
42      COORD(2) = RPL(IP)*1.1
43      COORD(3) = -SCALE/2.
44      COORD(4) = SCALE/2.
45      CALL MAP(COORD(1),COORD(2),COORD(3),COORD(4),0.,1.,0.,1.)
46      RPP=RPL(IP)
47      CALL UCROSS(VW,PV,X)
48      CALL VPROJ
49      CALL VVIEW(11,1,10,0,0,0,0)
50      DMDT=SQRT(GM/ARS(A)**3)
51      C      PLOT PLANET DISK
52      CALL DISK(IP,0,RLNK,0,0,0)
53      IJK=0
54      X(3)=0.
55      C      * * * * *
56      C      PLOT THE MAGNETIC FIELD
57      NMAX=SCALE/RPL(IP)
58      DO 101 I=2,NMAX
59      RO= I*RPL(IP)
60      DO 100 J=90,270,2
61      ALAT=(J-5)/RTD
62      ANG=ALAT-DELTR
63      RADIUS=RO*COS(ANG)**2
64      IF(RPL(IP) .GT. RADIUS) GO TO 50
65      C      X IS THE VECTOR TO THE SPACECRAFT
66      CALL VCOMB(X,VR,RADIUS*SIN(ALAT),VT,RADIUS*COS(ALAT))
67      IF(IJK .EQ. 1) GO TO 75
68      IF(J .EQ. 5) GO TO 75
69      C      PLOT MAGNETIC LINES OF FLUX
70      CALL VPLOT(X)
71      GO TO 100
72      50      IJK=1
73      C      LIFT THE PEN
74      CALL SINTRP(BUF)
75      GO TO 100
76      75      IJK=0
77      100      CONTINUE
78      CALL SINTRP(BUF)
79      C      LIFT THE PEN
80      101      CONTINUE
81      250      R=SCALE
82      C      * * * * *
83      C      COMPUTE TRAJECTORY PARAMETERS
84      CAT=(P/R-1.)/ECC
85      AT=ACOS(CAT)
86      T=ANOMLY(-AE,AT)/DMDT
87      N=ABS(T)/3600.
88      NN=-N
89      C      * * * * *
90      C      COMPUTE MAGNETIC POLE VECTOR (V)
91      CALL VLOAD(V,1.,XLAT,XLON)
92      CALL SPHERE(V,V,4HFROM,6HLATLON,6HDEGREE)
93      C      COMPUTE AND PLOT S/C TRAJECTORY
94      DO 300 I=NN,N
95      T=I*3600.
96      CALL ORBIN(XZ(7),IXZ6)
97      CALL ORBPOS(XS,T)
98      JD=JDV+ I*3600./86400.
99      CALL PGLOBE(PV,JD,IP)
100     CALL VTRANS(ZMA,V,4HFROM,PM,PV)
101     DEC= ANGV(ZMA,XS,6HRADIAN)
102     RADIUS=ARSV(XS)
103     TMP=90./RTD+DEC
104     CALL VCOMB(X,VR,RADIUS*SIN(TMP),VT,RADIUS*COS(TMP))
105     CALL VPLOT(X,1H*)
106     300 CONTINUE
107     CALL SINTRP(BUF)
108     310 CALLADV
109     C      * * * * *
110     C      * * * * *
111     SCALE=DINC*1.1
112     CALL PLPOS(XS,JDV,IP)
113     CALL VSCALE(XS,XS,-1.)
114     C      XS IS THE VECTOR POINTING TO THE SUN
115     CALL MAP(-SCALE,SCALE,-SCALE,SCALE,0,0,1,0,0,0,1,0)
116     C      PLOT PLANET DISK
117     CALL LINE(-SCALE,0.,.9*SCALE,0.)
118     CALL SYMBOL(3HS,.)
119     CALL DISK(IP,0,RLNK2,0,0,0)
120     N=30
121     NN=-N
122     C      * * * * *
123     C      PLOT MAGNETOPAUSE CONTOUR
124     DO 400 J=NN,N
125     ALAT=J/RTD
126     RPAUSE=DPAUSE*COS(ALAT)**2
127     CALL VCOMB(X,VR,RPAUSE*SIN(ALAT),VT,RPAUSE*COS(ALAT))
128     CALL VPLOT(X)
129     400 CONTINUE
130     C      LIFT THE PEN
131     CALL SINTRP(BUF)
132     RPAUSE=DPAUSE*COS(PI/6.)**2

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133      Y=RPAUSE*SIN(PI/6.)
134      XX=RPAUSE*COS(PI/6.)
135      CALL VCOMB(X,VR,Y,VT,XX)
136      CALL VPLOT(X)
137      CALL VCOMB(X,VR,Y,VT,-SCALE)
138      CALL VPLOT(X)
139      CALL SINTRP(BUF)
140      CALL VCOMB(X,VR,-Y,VT,XX)
141      CALL VPLOT(X)
142      CALL VCOMB(X,VR,-Y,VT,-SCALE)
143      CALL VPLOT(X)
144      CALL SINTRP(BUF)
145      C * * * * *
146      NN=90
147      NN=-N
148      C      PLOT BOW SHOCK CONTOUR
149      PP=2.*DINC
150      DO 500 J=NN,N
151      ALAT=J/RTD
152      RBOWS=PP/(1.+COS(ALAT))
153      CALL VCOMB(X,VR,RBOWS *SIN(ALAT),VT,RBOWS *COS(ALAT))
154      CALL VPLOT(X)
155      500 CONTINUE
156      CALL SINTRP(BUF)
157      C      LIFT THE PEN
158      R=SCALE
159      CAT=(P/R-1.)/ECC
160      AT=ACOS(CAT)
161      T=ANOMLY(-AE,AT)/DMDT
162      N=ABS(T)/3600.
163      NN=-N
164      C      PLOT TRAJECTORY
165      C * * * * *
166      DO 600 I=NN,N
167      T=I*3600.
168      C      X IS THE VECTOR TO THE SPACECRAFT
169      CALL ORBIN(XZ(7),IXZ6)
170      CALL ORBPOS(X,T)
171      JD=JDV+ I*3600./86400.
172      CALL PLPOS(XS,JD,IP)
173      CALL VSCALE(XS,XS,-1.)
174      CALL ORBIN(XZ(7),IXZ6)
175      CALL ORBPOS(X,T)
176      PHASE=ANGV(XS,X,6HRADIAN)
177      XM=ABSV(X)
178      CALL VCOMB(XF,VR,XM*SIN(PHASE),VT,XM*COS(PHASE))
179      CALL VPPLT(XF,1H*)
180      600 CONTINUE
181      C      LIFT THE PEN
182      CALL SINTRP(BUF)
183      CALL ADV
184      N=3.*24.
185      NN=-N
186      DO 612 I=NN,N
187      T=I*3600.
188      CALL ORBIN(XZ(7),IXZ6)
189      CALL ORBPOS(XS,T)
190      TX=T/86400.
191      IF(I.EQ.NN)TSTART=TX
192      IF(I.EQ.N)TSTOP=TX
193      JD=JDV+TX
194      CALL PGLOBE(PM,JD,IP)
195      CALL VTRANS(ZMA,V,4HFROM,PM,PV)
196      CALL PLPOS(XE,JD,3)
197      CALL PLPOS(XP,JD,IP)
198      CALL VDIF(REF,XE,XP)
199      RM=ABSV(XS)
200      ANGLE=ANGV(ZMA,XS,6HRADIAN)
201      ANGLE=PI/2. -ANGLE
202      BMINS=(SENS/((RPL(IP)/RM)**3*SQRT(1.+3.*SIN(ANGLE)**2)/COS(ANGLE)*
203      X*6))
204      IF(I.EQ.NN)XMIN=BMINS
205      XMIN=AMIN1(XMIN,BMINS)
206      XMAX=AMAX1(XMAX,BMINS)
207      CALL UCROSS(YMA,ZMA,XS)
208      CALL UCROSS(XMA,YMA,ZMA)
209      CALL VTRANS(XS,XS,2HTO,XMA,ZMA)
210      XX=XS(1)
211      YY=XS(3)
212      CALL SPHERE(XS,XS,2HTO,LATLON,6HRADIAN)
213      RIB=XS(1)/COS(XS(2))*2
214      IF(ABS(YY).LT.1.E-6) GO TO 610
215      SLOPE=(2.*XX*RIB-3.*XX*SQRT(XX**2 + YY**2))
216      X/(3.*YY*SQRT(XX**2 + YY**2))
217      Y1=YY-SLOPE*XX
218      IF(YY.LT.0.) CALL VLOAD(DIRB,XX,0.,(YY-Y1))
219      IF(YY.GT.0) CALL VLOAD(DIRB,-XX,0.,(Y1-YY))
220      GO TO 611
221      610 CALL VSCALE(DIRB,ZMA,-1.)
222      611 CALL VUNIT(DIRB,DIRB)
223      CALL VSCALE(DIRB,DIRB,-1.)
224      CALL VTRANS(DIRB,DIRB,4HFROM,XMA,ZMA)
225      CALL RCNCLK(DIRB,REF)
226      612 WRITE (8)TX,RMINS,DIRB
227      CALL MAPSSL(TSTART,TSTOP,XMIN,XMAX,.1,1.,1,1.)
228      CALL CHAROP (0,0,0,1,0)

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229      CALL ARSREM (.05,.4)
230      CALL SYMBOL(22HMINIMUM DFFECTABLE AS.)
231      CALL SYMBOL(10H (GAUSS)S.)
232      CALL ARSREM (.4,.05)
233      CALL CHAROP (0,0,0,0,0)
234      CALL SYMBOL(29H TIME FROM ENCOUNTER (DAYS)S.)
235      REWIND 8
236      READ(8,END=501)TX,BMINS
237      502 READ(8,END=501)TX2,BMINS2
238      503 CALL LINE(TX,BMINS,TX2,BMINS2)
239      TX=TX2
240      BMINS=BMINS2
241      GO TO 502
242      501 CONTINUE
243      CALL ADV
244      REWIND 8
245      CALL MAPS(TSTART,TSTOP=-180.,180.,.1,.1,.1,.1)
246      CALL CHAROP (0,0,0,1,0)
247      CALL ARSREM (.05,.2)
248      CALL SYMBOL(37HCLOCK ANGLE OF MAGNETIC FLUX VFCATORS.)
249      CALL CHAROP (0,0,0,0,0)
250      CALL ARSREM (.2,.05)
251      CALL SYMBOL(28HTIME FROM ENCOUNTER (DAYS)S.)
252      READ (8,END=622) TX,BMIN,DIRB
253      621 CLOCK=DIRB(3)
254      IF(CLOCK.GT.180.0) CLOCK=CLOCK-360.0
255      T=TX
256      624 READ (8,END=622) TX,BMIN,DIRB
257      623 ZAP=DIRB(3)
258      IF(ZAP.GT.180.) ZAP=ZAP-360.
259      CALL LINE(T,CLOCK,TX,ZAP)
260      T=TX
261      CLOCK=ZAP
262      GO TO 624
263      622 REWIND 8
264      CALL ADV
265      CALL MAPS(TSTART,TSTOP=0.,180.,.1,.1,.1,.1)
266      CALL CHAROP (0,0,0,1,0)
267      CALL ARSREM (.05,.2)
268      CALL SYMBOL(36HCONE ANGLE OF MAGNETIC FLUX VECTOR%.)
269      CALL CHAROP (0,0,0,0,0)
270      CALL ARSREM (.2,.05)
271      CALL SYMBOL(28HTIME FROM ENCOUNTER (DAYS)S.)
272      READ (8,END=626) TX,BMIN,DIRB
273      627 CONE=DIRB(2)
274      T=TX
275      628 READ (8,END=626) TX,BMIN,DIRB
276      629 CALL LINE(T,CONE,TX,DIRB(2))
277      CONE=DIRB(2)
278      T=TX
279      GO TO 628
280      626 CONTINUE
281      CALL ADV
282      RETURN
283      END

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OPRT GT,FOLDER

MARTIN\*GT,FOLDER

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1      SUBROUTINE FOLDFR(INST)
2      DIMENSION NS(9)
3      DATA NS/0,0,1,2,4,7,5,1,0/
4      DIMENSION PLNMUL(9),MOD(9),SATMUL(8,4)
5      REAL MULT
6      INTEGER CAMK
7      COMMON/HEDING/TITLE(13)
8      COMMON/TNME/TVNAME(5)
9      COMMON/TEST/ITEST(97)
10     COMMON/CHARLI /NCODE,NREC ,IP,IVS,NSC,IFLST,NCB
11     COMMON /JUNK/PR,EFAP,BS(8),EFBS(8)
12     COMMON/PHOTO/SOLAR(31),ALBDO(31,3),F(31,4),CAMEF(31,3)
13     COMMON/CHARAC/P(60)
14     DATA F / 31*1.0,
15     X .080,.030,.010,.015, 21*.0,
16     X .150,.010,.150,.020,.080,.500,.950,.930,.895,.500,.100,
17     X .027,.015,.013,18*.0,
18     X .005,.010,.020,.005,.005,.010,.025,.080,.500,.850,.930,
19     X .750,.800,.160,.050,.015,.005,.010,.010,.025,.005,.005,.010,.040,
20     X .030/
21     DATA SOLAR /.0070,.0204,.0514,.0971,.1093,.1157,.1429,.1693,.2006,
22     X.2044 .,1942,.1852,.1725,.1719,.1666,.1586,.1511,.1442,.1369,
23     X.1302,.1235,.1171,.1107,.1048,.0998,.0939,.0889,.0862,.0835,.0791,
24     X.0746/
25     DATA ALBDO/.300,.282,.270,.265,.269,.272,.285,.315,.364,.385,.406,
26     X.430,.450,.460,.465,.469,.470,.469,.458,.440,.410,.380,.355,.330,
27     X.315,.300,.282,.264,.246,.232,.222,
28     X.045,.050,.055,.060,.065,.070,.075,.080,.085,.100,.105,.113,.120,
29     X.125,.130,.135,.145,.155,.165,.170,.175,.180,.185,.290,.295,.200,
30     X.200,.200,.205,.209,.210,
31     X.075,.060,.047,.045,.040,.045,.050,.060,.075,.100,.120,.140,.155,
32     X.180,.210,.225,.250,.260,.275,.280,.290,.295,.300,.300,.302,.300,
33     X.300,.300,.298,.295,.290/
34     DATA CAMEF/.0 .,002,.095,.476,.762,.953,.984,1.00,.984,.953,.794,

```



```

26      90 CONTINUE
27      P(6)=63.0
28      P(7)=80.3
29      P(8)=90.0
30      P(9)=0.0
31      95 CONTINUE
32      P(10)=0.000002
33      IF(ITEST(1),EQ,0) GO TO 110
34      DO 100 I=1,5
35      P(I)=TVNAME(I)
36      100 CONTINUE
37      110 CONTINUE
38      DO 120 I=6,10
39      P(I)=XZ(I+30)
40      120 CONTINUE
41      DO 130 I=1,5
42      TVNAME(I)=P(I)
43      WRITE(6,1000) TITLE
44      WRITE(6,1010) (P(I),I=1,5)
45      DO 140 I=6,10
46      IF(ITEST(I+30),EQ,1) WRITE(6,1020) I,P(I)
47      IF(ITEST(I+30),NE,1) WRITE(6,1030) I,P(I)
48      140 CONTINUE
49      RETURN
50      1000 FORMAT(1H1,13A6/)
51      1010 FORMAT(5X,23HP CHARACTERISTICS FOR ,5A6/)
52      1020 FORMAT(5X,12,5X,6X,2H= ,E15.8,5X,10HUSER INPUT)
53      1030 FORMAT(5X,12,5X,6X,2H= ,E15.8)
54      END

```

QPRT GT.GEOPLT

MARTIN\*GT.GEOPLT

```

1      SUBROUTINE GEOPLT
2      DOUBLE PRECISION JDV
3      DIMENSION X(3),XP(3),XSAT(3),XE(3),RADP(3),TARGE(3),TARGP(3),
4      XRSAT(3),XSS(3)
5      DIMENSION A(3),V(3),V1(3)
6      DIMENSION NUM(8)
7      COMMON/PTLB/THA,R(3),DEI,K
8      COMMON/PLCONS/GMS,GMPL(12),RS,RPL(12),SNAME(2),PLNAME(2,12),
9      X SPV(3),PLPV(3,12),SVE(3),PLVE(3,12),SROT,PLROT(12),SQRL,PLOBL(12)
10     COMMON/CHARLI /NCODE,NREC ,IP,IVS,NSC,IFLST,NCB
11     DIMENSION SCUNIT(4)
12     DATA NUM/30,60,90,120,150,180,270,0/
13     DATA SCUNIT/0.,1.,0.,1./
14     SCAL2=2.625
15     CALL CHAROP (0,0,1,0,0)
16     K=1
17     KREC=0
18     PI=3.1415926536
19     RAD=57.2957795
20     STEP=2./RAD
21     SCALE=3.5
22     50 CALL MAP(-SCALE,SCALE,-SCALE,SCALE,SCUNIT(1),SCUNIT(2),SCUNIT(3),
23     XSCUNIT(4))
24     CALL LINE(-SCALE,-SCALE,SCALE,-SCALE)
25     CALL LINE(SCALE,-SCALE,SCALE,SCALE)
26     CALL LINE(SCALE,SCALE,-SCALE,SCALE)
27     CALL LINE(-SCALE,SCALE,-SCALE,-SCALE)
28     CALL LINE(-SCALE,-SCALE/2.,SCALE,-SCALE/2.)
29     CALL MAP(-3.5,3.5,-2.625,2.625,0.,1.,.25,1.)
30     CALL LINE(-3.5,0.,3.5,0)
31     CALL LINE(0.,-2.625,0.,2.625)
32     DEI=3.5/90.
33     RO=15.*DEI
34     DO 12 I=10,360,10
35     TH=I/RAD
36     SN=SIN(TH-PI/2.)
37     CS=COS(TH-PI/2.)
38     X1=RO*CS
39     Y1=RO*SN
40     RMAX=3.5
41     X2=RMAX*CS
42     Y2=RMAX*SN
43     IF(ABS(Y2),LT,2.625) GO TO 12
44     Y2=SIGN(2.625,Y2)
45     SL=SH/CS
46     X2=Y2/SL
47     12 CALL LINE (X1,Y1,X2,Y2)
48     DO 15 I=1,6
49     R=R0*I
50     15 CALL CIRC(R,STEP)
51     CALL SETBEM (.08,-SCAL2)
52     CALL NUMFR(NUM(8),2H11)
53     CALL SET BEM (.08,SCAL2-.17)
54     CALL NUMBER(NUM(6),2H13)
55     CALL SET BEM (-SCALE+.01,.0)
56     CALL NUMBER(NUM(7),2H13)
57     IF(K,EQ,2) GO TO 21
58     DO 20 I=1,3
59     RO=I*RO*2.-.25
60     CALL SET BEM (RO,0)

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61      20  CALL NUMBER(NUM(I),2HI3)
62      GO TO 23
63      21  DO 22 I=1,3
64      M=7-I
65      RO=2.*(I-1)*RO-.25
66      CALL SET BEM (RO,0)
67      22  CALL NUMBER(NUM(M),2HI3)
68      23  REWIND 13
69      10  READ(13,END=31)TT,X,XP,XSAT,XE,R,PHASE,RADP,TARGE,TARGP,PSAT,
70      X      PHASES,XSS,JDV,EM
71      11  KREC=KREC+1
72      TMAX=TT
73      TMIN=TT
74      IF(NCB .EQ.1) CALL VEQUAL(R,RSAT)
75      IF(K.EQ.1.AND.R(2).GT.90.) GO TO 10
76      IF(K.EQ.2.AND.R(2).LT.90.) GO TO 10
77      RPP=RPL(IP)
78      IF(IFLST.EQ.1.OR.NCB.EQ.1)CALL PSCONS(RPP,6HRADIUS,IVS,IP)
79      THA=ASIN(RPP/R(1))
80      CALL XLI'MR
81      CALL VLOAD(A,1.,R(2),R(3))
82      CALL SPHERE(V,A,4HFROM,5HPOLAR,6HDEGREE)
83      6    READ(13,END=30)TT,X,XP,XSAT,XE,R,PHASE,RADP,TARGE,TARGP,RSAT,
84      X      PHASES,XSS,JDV,EM
85      7    KREC=KREC+1
86      IF(NCB .EQ.1) CALL VEQUAL(R,RSAT)
87      IF(K.EQ.1.AND.RSAT(2).GT.90.) GO TO 40
88      IF(K.EQ.2.AND.RSAT(2).LT.90.) GO TO 40
89      CON=DEI*ARS(180.*(K-1)-RSAT(2))
90      ZON=PSAT(3)*PI/180.-PI/2.
91      X=CON*COS(ZON)
92      Y=CON*SIN(ZON)
93      CALL POINT(X,Y)
94      IF(RSAT(1).LT.R(1)) CALL SYMBOL(3H*$.)
95      IF(RSAT(1).GT.R(1)) CALL SYMBOL(3H*$.)
96      40  CONTINUE
97      IF(K.EQ.1.AND.R(2).GT.90.) GO TO 6
98      IF(K.EQ.2.AND.R(2).LT.90.) GO TO 6
99      TMAX=AMAX1(TMAX,TT)
100     TMIN=AMIN1(TMIN,TT)
101     CALL VLOAD(A,1.,R(2),R(3))
102     CALL SPHERE(V1,A,4HFROM,5HPOLAR,6HDEGREE)
103     CSA=DOT(V,V1)
104     SNA=SQRT(1.-CSA**2)
105     THA=RPP/R(1)
106     IF(SNA.LT.THA) GO TO 6
107     THA=ASIN(THA)
108     CALL XLI'MR
109     CALL VEQUAL(V,V1)
110     IF(KREC.EQ.NREC) GO TO 30
111     GO TO 6
112     31  CONTINUE
113     30  K=K+1
114     CALL ARSBEM (.1,.05)
115     CALL SYMBOL(14HSTART TIME $.)
116     CALL NUMBEF(TMIN/R6400., 4HF4.1)
117     CALL SYMBOL(13HSTOP TIME $.)
118     CALL NUMBEF(TMAX/R6400., 4HF4.1)
119     IF(K.GT.2) RETURN
120     CALL ADV
121     GO TO 50
122     END

```

QPRT GT,INPUT

MARTIN\*GT.INPUT

```

1  SUBROUTINE INPUT(NP)
2  COMMON/HEDING/TITLE(13)
3  COMMON/FLAGS/IFLT,IFLPL,IFLPR
4  COMMON/TCONS/TCONS(200)
5  COMMON/CAM/CCONE(200),CCLK(200)
6  COMMON/TEST/ITEST(97)
7  COMMON /TRA/TRACE,COVENT(13)
8  COMMON/TNME/TVNAME(5)
9  COMMON /PLTBUF/BUF(20)
10 C INPUT QUANTITIES
11 COMMON/XZ/XZ(97) /VAR/VAR(97)
12 DATA XZ/14*0.,3.,8*0.,2*1H,72*0./
13 DATA VAR/6H      ,6HPLANET,6HSATEL,6HDATE,6HORIENT,6H
14 *6HSTATE1,6HSTATE2,6HSTATE3,6HSTATE4,6HSTATES,6HSTATE6,6H
15 *6H      ,6H      ,6H      ,6H      ,6H      ,6H      ,6H
16 *6H      ,6HINSTID,6H      ,6H      ,6H      ,6H      ,6H
17 *6H      ,6H      ,6H      ,6HNAME-1,6HNAME-2,6HNAME-3,6HNAME-4,
18 *6HNAME-5,6HCHAR-1,6HCHAR-2,6HCHAR-3,6HCHAR-4,6HCHAR-5,6HCHAR-6,
19 *6HCHAR-7,6HCHAR-8,6HCHAR-9,6HCHAR10,6HCHAR11,6HCHAR12,6HCHAR13,
20 *6H      ,6H      ,6H      ,6H      ,6H      ,6H      ,6H
21 *6H      ,6H      ,6H      ,6H      ,6H      ,6H      ,6H
22 *6HDTINST,6H      ,6H      ,6HBITRAT,6H      ,6H      ,6H
23 *6H      ,6H      ,6H      ,6H      ,6H      ,6H      ,6H
24 *6H      ,6H      ,6H      ,6H      ,6HDPLOT,6HDPRT,6H
25 *6H      ,6H      ,6HSATRNG,6H      ,6H      ,6H      ,6H
26 *6H      ,6H      ,6H      ,6H      ,6H      ,6H      ,6H

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```

27      DATA TVNAME/5*6H
28      C
29      C EJECT PAGE AND READ TITLE CARD
30      PRINT 998
31      READ(5,1000)TITLE
32      1000 FORMAT(13A6)
33      WRITE(6,1001)TITLE
34      1001 FORMAT(5X,13A6,/)
35      C
36      N1=0
37      N2=0
38      NP=0
39      ITFLB=0
40      ITFLA=0
41      IFLT=0
42      IF(XZ(71).NE..0) GO TO 1
43      DO 10 I=1,97
44      10  ITEST (I)=0
45      250 CONTINUE
46      C
47      C READ INPUT CARDS
48      1  READ(5,994)          I,XV,WORD,(COMENT(J),J=1,10)
49      260 CONTINUE
50      IF(I.LT.1 .OR. I.GT.97) GO TO 2
51      PRINT 995, I,XV,VAR(I),(COMENT(J),J=1,10)
52      IF(I.GE.31.AND.I.LE.35) TVNAME(I-30)=WORD
53      XZ(I)=XV
54      ITEST(I)=1
55      IF(I.NE.22) GO TO 200
56      IF(IFIX(XV/100.).NE.3) ITFLB=1
57      200 CONTINUE
58      IF(I.EQ.23) GO TO 300
59      GO TO 1
60      300 CONTINUE
61      IFLT=XV
62      IF(XV.NE.1) GO TO 250
63      IF(ITFLB.EQ.1) GO TO 310
64      WRITE(6,993) COMENT
65      GO TO 250
66      310 ITFLA=1
67      320 READ(5,994) I,XV,WORD,(COMENT(J),J=1,10)
68      IF(I.LT.24.OR.I.GT.30) GO TO 260
69      IF(I.EQ.24) N1=N1+1
70      IF(I.EQ.25) N2=N2+1
71      IF(I.EQ.26) NP=NP+1
72      ITEST(I)=1
73      XZ(I)=XV
74      PRINT 995,I,XV,VAR(I),(COMENT(J),J=1,10)
75      IF(I.EQ.24) CCONE (N1)=XV
76      IF(I.EQ.25) CCLK(N2)=XV
77      IF(I.EQ.26) TCONS(NP)=XV
78      GO TO 320
79      2  PRINT 996, I,WORD,(COMENT(J),J=1,10)
80      IF(I.EQ.98) GO TO 5
81      IF(I.EQ.99) GO TO 4
82      DO 3 I=1,97
83      3  XZ(I) = 0.
84      XZ(15) = 3.
85      XZ(24) = 1H
86      XZ(25) = 1H
87      GO TO 1
88      C FINISHES PLOT TAPE
89      4  CALL STERM(BUF)
90      STOP
91      5  CALL VECTOR (WORD)
92      IF(TRACE.EQ.5HTRACE) PRINT 999
93      C
94      PRINT 998
95      WRITE(6,1001)TITLE
96      WRITE(6,1002)
97      1002 FORMAT(24H XZ(I) VALUES IN STORAGE,/)
98      DO 9 I=1,96,2
99      K=I+1
100     9  WRITE(6,1003)I,ITEST(I),XZ(I),K,ITEST(K),XZ(K)
101     1003 FORMAT(I4,I4,2X,E17.10,13X,I4,I4,2X,E17.10)
102      C
103      RETURN
104     991 FORMAT(5X,I2,3X,A6,11X,10A6,A2)
105     992 FORMAT(13A6)
106     993 FORMAT(' ERROR*****',13A6,'*****ERROR THIS CARD IGNORED')
107     994 FORMAT(I2,G15.8,10A6,A2)
108     995 FORMAT(5X,I2,1P,G20.8,10A6,A2)
109     996 FORMAT(5X,I2,20X,10A6,A2)
110     997 FORMAT(1P4(/1X,5(3X,A6,G15.8))/1X,3(3X,A6,G15.8),2(3X,A6,6X,A6,3X
111     X ),15(/1X,5(3X,A6,G15.8)))
112     998 FORMAT('1')
113     999 FORMAT('1INPUT SUBROUTINE')
114      END

```

MARTIN\*G.T.\*MRLC

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1      SUBROUTINE MRLC(DIREC)
2      COMMON/PLCONS/DUMMYD(2A), PLNAME(2,12),DUMMYE(104)
3      COMMON/RAZOR/PICS(4,9),SPPICS(4)
4      DIMENSION SYM(4)
5      DATA SYM/3H0%,3HXS.,3H+%,3HIS./
6      COMMON/HAND0/TIM,REC(9),REL(9),RES,SMR(9),SMRR(9),SMRS(9),TSMR(9)
7      X,SPSMR,SPSMRS,SPTSVR,SPSMRP
8      DIMENSION SDUNIT(4),NS(9),ACPIC(4,8),ION(4,8)      ,THING(3),PP(4)
9      DATA THING(3)/2HS./
10     DATA ION/32*0/
11     COMMON/FOROUT/DUMMYB(13),IPCN,DUMMYC(4)
12     COMMON/CHARLI /NCOFF,NREC ,IP,IVS,NSC,IFLST,NCR
13     COMMON/CHARAC/P(60)
14     COMMON/JDAYS/ J0V,TT
15     DOUBLE PRECISION J0V
16     DATA NS/0,0,1,2,4,7,5,2,0/
17     DATA SDUNIT/0,1,1,0,0,1,1,0/
18     IF(DIREC.EQ.4HPLOT) GO TO 300
19     IF(IFR.NE.0) GO TO 100
20     REWIND 12
21     PMAX=0.0
22     IFR=1
23
24     C
25     C      MINIMUM RESOLUTION LEVEL CALCULATION (MRLC) SUBROUTINE
26     C      WILL COMPUTE THE NUMBER OF PICTURES VS TIME WITHIN A
27     C      GIVEN RESOLUTION RANGE (SEE TVCHAR P(17) THPU P(20)).
28     C      BECAUSE CALCULATIONS TAKE PLACE DURING CALC STEPS ACCURACY
29     C      LIES WITHIN PLUS OR MINUS P(39).
30     C
31     NSP=NS(IP)
32     NSX=NSP+1
33     DO 140 I=1,NSX
34     DO 130 J=1,4
35     IF(ION(J,I).NE.0) GO TO 110
36     IF(REC(I).GT.P(16+J)) GO TO 130
37     ION(J,I)=IPCN
38     ACPIC(J,I)=1.
39     110 CONTINUE
40     IF(REC(I).GT.P(16+J)) GO TO 120
41     ACPIC(J,I)=ACPIC(J,I)+IPCN-ION(J,I)
42     120 ION(J,I)=IPCN
43     PICS(J,I)=ACPIC(J,I)
44     IF(PICS(J,I).GT.PMAX) PMAX=PICS(J,I)
45     130 CONTINUE
46     140 CONTINUE
47     TP=TT/86400.
48     WRITE(12) TP,PICS,SPPICS
49     RETURN
50
51     C
52     C      PLOT OF PICTURES PER MRL VS TIME
53     C
54     300 CONTINUE
55     DO 400 I=1,NSX
56     REWIND 12
57     IFR=0
58     CALL ADV
59     CALL MAPSSL(-TIM,TIM,1.0,PMAX,SDUNIT(1),SDUNIT(2),SDUNIT(3),SDUNIT
60     *(4))
61     CALL CHAROP (0,0,1,1,0)
62     CALL ARSBEM (0,05,0,02)
63     CALL SYMBOL(56HNUMBER OF PICTURES WITHIN SPECIFIED RESOLUTION LEVE
64     XLS 5.)
65     IF(I.NE.1) GO TO 310
66     DO 305 K=1,2
67     305 THING(K)=PLNAME(K,IP)
68     GO TO 315
69     310 CALL PSCONS(THING,4HNAME,I-1,IP)
70     315 CONTINUE
71     CALL SYMBOL(THING )
72     CALL CHAROP (0,0,1,0,0)
73     CALL ARSBEM (0,2,0,01)
74     CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS)$. )
75     CALL CHAROP (0,0,0,0,0)
76     320 READ(12,END=360) T,PICS,SPPICS
77     325 IF(IFR.EQ.0) GO TO 340
78     DO 330 J=1,4
79     IF(PP(J).LE.0,0,OR,PICS(J,I).LE.0,0) GO TO 330
80     CALL LINE(TP,PP(J),T,PICS(J,I))
81     330 CONTINUE
82     GO TO 350
83     340 CONTINUE
84     IFR=1
85     DO 345 J=1,4
86     IF(PICS(J,I).LE.0,0) GO TO 345
87     CALL POINT(TP,PICS(J,I))
88     CALL SYMBOL(SYM(J))
89     345 CONTINUE
90     350 CONTINUE
91     DO 355 J=1,4
92     PP(J)=PICS(J,I)
93     TP=T
94     GO TO 320
95     360 DO 365 J=1,4
96     IF(PP(J).LE.0,0) GO TO 365
97     CALL POINT(TP,PP(J))

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96      CALL SYMROL(SYM(J))
97      XHT=0.98-(J-1)*0.03
98      CALL ABSREM (0.75,XHT)
99      CALL SYMROL(SYM(J))
100     CALL SYMROL(3H %.)
101     CALL NUMBER(P(16+J), 4HF5.1)
102     CALL SYMROL(5H KMS.)
103     365 CONTINUE
104     400 CONTINUE
105     RETURN
106     END

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DPRT GT.OTJAZ

MARTIN\*GT.OTJAZ

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1      SUBROUTINE OTJAZ(DIREC)
2      COMMON /XZ/ XZ(97), IXZ6
3      COMMON/POBEAR/SSV(8),SAF(8),HANG2,DCNCLK(8).
4      DIMENSION DUMMYC(13)
5      COMMON/PHASER/PHASE(8),XRCC(3,8)
6      COMMON/CHARLI /NCODE,NREC ,IP,IVS,NSC,IFLST,NCR
7      COMMON/JDAYS/JDV,TT
8      DIMENSION NS(9),THING(3)
9      DIMENSION SYM(8)
10     DATA SYM/3H0%. ,3H%. ,3H+%. ,3HIS. ,3HHS. ,3HT%. ,3HZ%. ,3HPS./
11     DATA THING(3)/2H%. /
12     DATA IFR,ITR1/0.11/
13     DATA NS/0,0,1,2,4,7,5,2,0/
14     REALJDV
15     DIMENSION X(3),XP(3),XSAT(3),XE(3),R(3),      RADP(3),TARGE(3),
16     *TARGP(3),RSAT(3),      XSS(3),SDUNIT(4) ,RDMIN(3)
17     DATA SDUNIT/0.1,1.0,0.1,1.0/
18     COMMON/HANDO/TIM,REC(9),REL(9),RES,SMR(9),SMRR(9),SMRS(9),TSMR(9)
19     X,SPSMR,SPSMRS,SPTSVR,SPSVRR
20     IF(DIREC.EQ.4HPLOT) GO TO 120
21     IF(IFR.EQ.1) GO TO 100
22     REWIND 9
23     RPD=3.14159/180.
24     CALL ORBIN(XZ(7),IXZ6)
25     CALL ORBPOS(RDMIN,0.0)
26     RAMIN=ABSV(RDMIN)
27     NSP=NS(IP)
28     REWIND ITR1
29     IFR=1
30     100 CONTINUE
31     T=TT/86400.
32     WRITE(ITR1) T,PHASE,XRCC
33     WRITE(9) T,SSV,SAF,HANG2,DCNCLK
34     RETURN
35     120 CONTINUE
36     C
37     C  SATELLITE RANGE VS TIME PLOT
38     C
39     REWIND 13
40     READ(13)DUMMYC,R,A
41     RP=R(1)
42     REWIND 13
43     CALL ADV
44     CALL MAPSSL(-TIM,TIM,RAMIN,RP,SDUNIT(1),SDUNIT(2),SDUNIT(3),
45     *SDUNIT(4))
46     CALL CHAROP (0,0,1,1,0)
47     CALL ABSREM (0.05,0.2)
48     CALL SYMROL(25HRANGE OF SATELLITE (KM)%. )
49     CALL CHAROP (0,0,1,0,0)
50     CALL ABSREM (0.2,0.01)
51     CALL SYMROL(29HTIME FROM ENCOUNTER (DAYS) %.)
52     CALL CHAROP (0,0,0,0,0)
53     DO 150 ITR=1,NSP
54     REWIND ITR1
55     READ(ITR1) TP,PHASE,XRCC
56     RP=XRCC(1,ITR)
57     IF(RP.LE.0.0) GO TO 150
58     CALL POINT(TP,RP)
59     CALL SYMBOL(SYM(ITR))
60     130 CONTINUE
61     READ(ITR1,END=148) T,PHASE,XRCC
62     140 CONTINUE
63     CALL LINE(TP,RP,T,XRCC(1,ITR))
64     TP=T
65     RP=XRCC(1,ITR)
66     GO TO 130
67     148 CONTINUE
68     CALL POINT(TP,RP)
69     CALL SYMBOL(SYM(ITR))
70     XHT=0.98-(ITR-1)*0.03
71     CALL ABSREM (0.75,XHT)
72     CALL SYMBOL(SYM(ITR))
73     CALL SYMBOL(3H %.)
74     CALL PSCONS(THING,4HNAME,ITR,IP)
75     CALL SYMBOL(THING)

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76      150 CONTINUE
77      REWIND ITR1
78      CALL ADV
79
80      C
81      C   SATELLITE PHASE ANGLE VS TIME PLOT
82      C
83      CALL MAPS (-TIM,TIM,0.0,210.0,SDUNIT(1),SDUNIT(2),SDUNIT(3),SDUNIT
84      X(4))
85      CALL CHAROP (0,0,1,1,0)
86      CALL ABSBEM (0.05,0.2)
87      CALL SYMBOL(29HSATFLLITE PHASE ANGLE (DEG)%. )
88      CALL CHAROP (0,0,1,0,0)
89      CALL ABSREM (0.2,0.01)
90      CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS)%. )
91      CALL CHAROP (0,0,0,0,0)
92      DO 153 ITB=1,NSP
93      REWIND ITR1
94      READ(ITR1) TP,PHASE,XRCC
95      PHP=PHASE(ITB)/PPD
96      CALL POINT(TP,PHP)
97      CALL SYMBOL(SYM(ITB))
98      151 CONTINUE
99      READ (ITR1,END=1053) T,PHASF,XRCC
100     152 CONTINUE
101     PHASES=PHASE(ITB)/RPD
102     CALL LINE(TP,PHP,T,PHASES)
103     TP=T
104     PHP=PHASES
105     GO TO 151
106     1053 CONTINUE
107     CALL POINT(TP,PHP)
108     CALL SYMROL(SYM(ITB))
109     XHT=0.98-(ITB-1)*0.03
110     CALL ABSBEM (0.75,XHT)
111     CALL SYMBOL(SYM(ITB))
112     CALL SYMBOL(3H $.)
113     CALL PSCONS(THING,4HNAME,ITB,IP)
114     CALL SYMBOL(THING)
115     153 CONTINUE
116     CALL ADV
117
118     C
119     C   SATELLITE CONE ANGLE VS TIME PLOT
120     C
121     CALL MAPS(-TIM,TIM,0.0,210.0,SDUNIT(1),SDUNIT(2),SDUNIT(3),SDUNIT(
122     X4))
123     CALL CHAROP (0,0,1,1,0)
124     CALL ARSBEM (0.05,0.2)
125     CALL SYMBOL(28HSATELLITE CONE ANGLE (DEG)%. )
126     CALL CHAROP (0,0,1,0,0)
127     CALL ABSREM (0.2,0.01)
128     CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS) %. )
129     CALL CHAROP (0,0,0,0,0)
130     DO 156 ITB=1,NSP
131     REWIND ITR1
132     READ(ITR1) TP,PHASE,XRCC
133     RP=XRCC(2,ITB)
134     CALL POINT(TP,RP)
135     CALL SYMBOL(SYM(ITB))
136     154 CONTINUE
137     READ (ITR1,END=1056) T,PHASE,XRCC
138     155 CONTINUE
139     CALL LINE(TP,RP,T,XRCC(2,ITB))
140     TP=T
141     RP=XRCC(2,ITB)
142     GO TO 154
143     1056 CONTINUE
144     CALL POINT(TP,RP)
145     CALL SYMBOL(SYM(ITB))
146     XHT=0.98-(ITB-1)*0.03
147     CALL ARSBEM (0.75,XHT)
148     CALL SYMBOL(SYM(ITB))
149     CALL SYMBOL(3H $.)
150     CALL PSCONS(THING,4HNAME,ITB,IP)
151     CALL SYMBOL(THING)
152     156 CONTINUE
153     CALL ADV
154
155     C
156     C   SATELLITE CLOCK ANGLE VS TIME PLOT
157     C
158     CALL MAPS(-TIM,TIM,0.0,390.0,SDUNIT(1),SDUNIT(2),SDUNIT(3),SDUNIT(
159     X4))
160     CALL CHAROP (0,0,1,1,0)
161     CALL ABSREM (0.05,0.2)
162     CALL SYMBOL(29HSATELLITE CLOCK ANGLE (DEG)%. )
163     CALL CHAROP (0,0,1,0,0)
164     CALL ABSREM (0.2,0.01)
165     CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS)%. )
166     CALL CHAROP (0,0,0,0,0)
167     DO 159 ITB=1,NSP
168     REWIND ITR1
169     READ(ITR1) TP,PHASE,XRCC
170     RP=XRCC(3,ITB)
171     CALL POINT(TP,RP)
172     CALL SYMBOL(SYM(ITB))
173     157 CONTINUE

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171 READ (ITR1,END=1059) T,PHASE,XRCC
172 158 CONTINUE
173 CALL LINE(TP,RP,T,XRCC(3,ITB))
174 TP=T
175 RP=XRCC(3,ITR)
176 GO TO 157
177 1059 CONTINUE
178 CALL POINT(TP,RP)
179 CALL SYMBOL(SYM(IT9))
180 XHT=0.98-(IT9-1)*0.03
181 CALL ARSBEM (0.75,XHT)
182 CALL SYMBOL(SYM(ITB))
183 CALL SYMBOL(3H $.)
184 CALL PSCONS(THING,4HNAME,ITB,IP)
185 CALL SYMBOL(THING)
186 159 CONTINUE
187 REWIND ITR1
188 CALL ADV
189 CALL MAPS(-TIM,TIM, 0.0,210.0,SDUNIT(1),SDUNIT(2),SDUNIT(3),
190 XSDUNIT(4))
191 CALL CHAROP (0,0,1,1,0)
192 CALL ARSBEM (0.05,0.2)
193 CALL SYMBOL(25HSUN-SAT-S/C ANGLE (DEG)$.)
194 CALL CHAROP (0,0,1,0,0)
195 CALL ARSBEM (0.2,0.01)
196 CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS) $.)
197 CALL CHAROP (0,0,0,0,0)
198 DO 360 ITB=1,NSP
199 REWIND 9
200 IFR=0
201 310 CONTINUE
202 READ(9,END=350)T,SSV,SAF
203 320 IF(IFR.EQ.0) GO TO 330
204 CALL LINE(TP,SSP,T,SSV(ITB))
205 330 CONTINUE
206 IF(IFR.NE.0) GO TO 340
207 IFR=1
208 CALL POINT(T,SSV(ITR))
209 CALL SYMBOL(SYM(ITR))
210 340 CONTINUE
211 TP=T
212 SSP=SSV(ITB)
213 GO TO 310
214 350 CONTINUE
215 CALL POINT(TP,SSP)
216 CALL SYMBOL(SYM(ITB))
217 XHT=0.98-(IT9-1)*0.03
218 CALL ARSBEM (0.75,XHT)
219 CALL SYMBOL(SYM(ITR))
220 CALL SYMBOL(3H $.)
221 CALL PSCONS(THING,4HNAME,ITB,IP)
222 CALL SYMBOL(THING)
223 360 CONTINUE
224 CALL ADV
225 CALL MAPS(-TIM,TIM,-03.,07.,SDUNIT(1),SDUNIT(2),SDUNIT(3),
226 XSDUNIT(4))
227 CALL CHAROP (0,0,1,1,0)
228 CALL ARSBEM (0.05,0.2)
229 CALL SYMBOL(28HSATELLITE HALF ANGLE (DEG)$.)
230 CALL CHAROP (0,0,1,0,0)
231 CALL ARSBEM (0.2,0.01)
232 CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS) $.)
233 CALL CHAROP (0,0,0,0,0)
234 DO 460 ITB=1,NSP
235 REWIND 9
236 IFR=0
237 410 CONTINUE
238 READ(9,END=450) T,SSV,SAF
239 420 IF(IFR.EQ.0) GO TO 430
240 CALL LINE(TP,SSP,T,SAF(ITB))
241 IF(IFR.NE.0) GO TO 440
242 430 CONTINUE
243 IFR=1
244 CALL POINT(T,SAF(ITB))
245 CALL SYMBOL(SYM(ITR))
246 440 CONTINUE
247 TP=T
248 SSP=SAF(ITB)
249 GO TO 410
250 450 CONTINUE
251 CALL POINT(TP,SSP)
252 CALL SYMBOL(SYM(ITB))
253 XHT=0.98-(IT9-1)*0.03
254 CALL ARSBEM (0.75,XHT)
255 CALL SYMBOL(SYM(ITR))
256 CALL SYMBOL(3H $.)
257 CALL PSCONS(THING,4HNAME,ITB,IP)
258 CALL SYMBOL(THING)
259 460 CONTINUE
260 IFR=0
261 CALL ADV
262 CALL MAPS(-TIM,TIM,0.,360.,SDUNIT(1),SDUNIT(2),SDUNIT(3),SDUNIT
263 X(4))
264 CALL CHAROP (0,0,1,1,0)
265 CALL ARSBEM (0.05,0.05)
266 CALL SYMBOL(60HTIME REQUIRED TO SWITCH TO SATELLITE AT RATE OF 1

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267 XDEG/SECS.)
268 CALL CHAROP (0,0,1,0,0)
269 CALL ABSBEM (0,2,0,01)
270 CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS) %.)
271 CALL CHAROP (0,0,0,0,0)
272 DO 500 ITB=1,N5P
273 REWIND 9
274 IFR=0
275 465 CONTINUE
276 READ(9,END=485) T,SSV,SAF,HANG2,DCNCLK
277 470 IF(IFR.EQ.0) GO TO 475
278 CALL LINE(TP,DCNCL1,T,DCNCLK(ITB))
279 IF(IFR.NE.0) GO TO 480
280 475 CONTINUE
281 IFR=1
282 CALL POINT(T,DCNCLK(ITB))
283 CALL SYMBOL(SYM(ITB))
284 480 CONTINUE
285 TP=T
286 DCNCL1=DCNCLK(ITB)
287 GO TO 465
288 485 CONTINUE
289 CALL POINT(TP,DCNCL1)
290 CALL SYMROL(SYM(ITB))
291 XHT=0.98-(ITB-1)*0.03
292 CALL ABSBEM (0,75,XHT)
293 CALL SYMBOL(SYM(ITB))
294 CALL SYMBOL(3H %.)
295 CALL PSCONS(THING,4HNAME,ITB,IP)
296 CALL SYMBOL(THING)
297 500 CONTINUE
298 IFR=0
299 CALL ADV
300 RETURN
301 END

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QPRT GT,OTPLT

MARTIN\*GT.OTPLT

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1 SUBROUTINE OTPLT
2 COMMON / XZ / XZ(97), IXZ6
3 DIMENSION X(3),XP(3),XSAT(3),XE(3),R(3), RANP(3),TARGE(3),
4 *TARGP(3),RSAT(3), XSS(3),SDUNIT(4), RDMIN(3)
5 COMMON/HANDO/TIM,REC(9),REL(9),RES,SMR(9),SMRR(9),SMRS(9),TSMR(9)
6 X,SPSMR,SPSMRS,SPTSMR,SPSMRR
7 DATA SDUNIT/0.1,1.0,0.1,1.0/
8 RPD=3.14159/180.
9
10 C
11 C PLANET RANGE PLOT
12 C
13 REWIND 13
14 CALL ORBIN(XZ(7),IXZ6)
15 CALL ORBPOS(RDMIN,0,0)
16 RAMIN=ABSV(RDMIN)
17 READ(13)TX,X,XP,XSAT,XE,R
18 RP=R(1)
19 TP=TX/86400.
20 CALL MAPSSL(-TIM,TIM,RAMIN,RP,SDUNIT(1),SDUNIT(2),SDUNIT(3),
21 * SDUNIT(4))
22 CALL CHAROP (0,0,1,1,0)
23 CALL ABSBEM (0,05,0,2)
24 CALL SYMBOL(23HRANGE OF PLANET (KM) %.)
25 CALL CHAROP (0,0,1,0,0)
26 CALL ABSBEM (0,2,0,01)
27 CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS) %.)
28 100 CONTINUE
29 READ(13,END=120)TX,X,XP,XSAT,XE,R
30 110 T=TX/86400.
31 CALL LINE(TP,RP,T,R(1))
32 TP=T
33 RP=R(1)
34 GO TO 100
35 120 CONTINUE
36 REWIND 13
37 CALL ADV
38 C
39 C PLANET PHASE ANGLE VS TIME PLOT
40 C
41 CALL MAPS(-TIM,TIM,0,0,180,0,SDUNIT(1),SDUNIT(2),SDUNIT(3),SDUNIT(
42 X4))
43 CALL CHAROP (0,0,1,1,0)
44 CALL ABSBEM (0,05,0,2)
45 CALL SYMBOL(26HPLANET PHASE ANGLE (DEG)%.)
46 CALL CHAROP (0,0,1,0,0)
47 CALL ABSBEM (0,2,0,01)
48 CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS)%.)
49 READ(13) TX,X,XP,XSAT,XE,R,PHASE
50 TP=TX/86400.
51 PHP=PHASE/RPD
52 121 CONTINUE
53 READ(13,END=123)TX,X,XP,XSAT,XE,R,PHASE
54 122 CONTINUE
55 PHASE=PHASE/RPD

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55      T=TX/86400.
56      CALL LINE(TP,PHP,T,PHASE)
57      TP=T
58      PHP=PHASE
59      GO TO 121
60      123 CONTINUE
61      REWIND 13
62      CALL ADV
63      C
64      C PLANET CONE ANGLE VS TIME PLOT
65      C
66      CALL MAPS(-TIM,TIM,0.0,180.0,SDUNIT(1),SDUNIT(2),SDUNIT(3),SDUNIT(
67      X4))
68      CALL CHAROP (0,0,1,1,0)
69      CALL ARSREM (0.05,0.2)
70      CALL SYMBOL(25HPLANET CONE ANGLE (DEG)%)
71      CALL CHAROP (0,0,1,0,0)
72      CALL ARSREM (0.2,0.01)
73      CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS)%)
74      READ(13) TX,X,XP,XSAT,XE,R,PHASE
75      TP=TX/86400.
76      RP=R(2)
77      124 CONTINUE
78      READ(13,END=126)TX,X,XP,XSAT,XE,R,PHASE
79      125 CONTINUE
80      T=TX/86400.
81      CALL LINE(TP,RP,T,R(2))
82      TP=T
83      RP=R(2)
84      GO TO 124
85      126 CONTINUE
86      REWIND 13
87      CALL ADV
88      C
89      C PLANET CLOCK ANGLE VS TIME PLOT
90      C
91      CALL MAPS(-TIM,TIM,0.0,360.0,SDUNIT(1),SDUNIT(2),SDUNIT(3),SDUNIT(
92      X4))
93      CALL CHAROP (0,0,1,1,0)
94      CALL ARSREM (0.05,0.2)
95      CALL SYMBOL(26HPLANET CLOCK ANGLE (DEG)%)
96      CALL CHAROP (0,0,1,0,0)
97      CALL ARSREM (0.2,0.01)
98      CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS)%)
99      READ(13) TX,X,XP,XSAT,XE,R,PHASE
100     TP=TX/86400.
101     RP=R(3)
102     127 CONTINUE
103     READ(13,END=129)TX,X,XP,XSAT,XE,R,PHASE
104     128 CONTINUE
105     T=TX/86400.
106     CALL LINE(TP,RP,T,R(3))
107     TP=T
108     RP=R(3)
109     GO TO 127
110     129 CONTINUE
111     REWIND 13
112     CALL ADV
113     C
114     C SATELLITE RANGE VS TIME PLOT
115     C
116     READ(13)TX,X,XP,XSAT,XE,R,PHASE,RADP,TARGE,TARGP,RSAT
117     RP=RSAT(1)
118     TP=TX/86400.
119     CALL MAPSSL(-TIM,TIM,RAMIN,RP,SDUNIT(1),SDUNIT(2),SDUNIT(3),
120     *SDUNIT(4))
121     CALL CHAROP (0,0,1,1,0)
122     CALL ARSREM (0.05,0.2)
123     CALL SYMBOL(25HRANGE OF SATELLITE (KM)%)
124     CALL CHAROP (0,0,1,0,0)
125     CALL ARSREM (0.2,0.01)
126     CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS) %)
127     130 CONTINUE
128     READ(13,END=150)TX,X,XP,XSAT,XE,R,PHASE,RADP,TARGE,TARGP,RSAT
129     140 CONTINUE
130     T=TX/86400.
131     CALL LINE(TP,RP,T,RSAT(1))
132     TP=T
133     RP=RSAT(1)
134     GO TO 130
135     150 CONTINUE
136     REWIND 13
137     CALL ADV
138     C
139     C SATELLITE PHASE ANGLE VS TIME PLOT
140     C
141     CALL MAPS (-TIM,TIM,0.0,180.0,SDUNIT(1),SDUNIT(2),SDUNIT(3),SDUNIT
142     X(4))
143     CALL CHAROP (0,0,1,1,0)
144     CALL ARSREM (0.05,0.2)
145     CALL SYMBOL(29HSATELLITE PHASE ANGLE (DEG)%)
146     CALL CHAROP (0,0,1,0,0)
147     CALL ARSREM (0.2,0.01)
148     CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS)%)
149     READ(13) TX,X,XP,XSAT,XE,R,PHASE,RADP,TARGE,TARGP,RSAT,PHASES
150     TP=TX/86400.

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151      PHP=PHASES/RPD
152      151 CONTINUE
153      READ(13,END=153)TX,X,XP,XSAT,XE,R,PHASE,PADP,TARGE,TARGP,RSAT,PHAS
154      XES
155      152 CONTINUE
156      PHASES=PHASES/RPD
157      T=TX/86400.
158      CALL LINE(TP,PHP,T,PHASES)
159      TP=T
160      PHP=PHASES
161      GO TO 151
162      153 CONTINUE
163      REWIND 13
164      CALL ADV
165
166      C
167      C   SATELLITE CONE ANGLE VS TIME PLOT
168      C
169      CALL MAPS(-TIM,TIM,0.0,180.0,SDUNIT(1),SDUNIT(2),SDUNIT(3),SDUNIT(
170      X4))
171      CALL CHAROP (0.0,1,1,0)
172      CALL ABSBEM (0.05,0.2)
173      CALL SYMBOL(28HSATELLITE CONE ANGLE (DEG)$.)
174      CALL CHAROP (0.0,1,0,0)
175      CALL ABSBEM (0.2,0.01)
176      CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS)$.)
177      READ(13) TX,X,XP,XSAT,XE,R,PHASE,PADP,TARGE,TARGP,RSAT,PHASES
178      TP=T/86400.
179      RP=RSAT(2)
180      154 CONTINUE
181      READ(13,END=156)TX,X,XP,XSAT,XE,R,PHASE,PADP,TARGE,TARGP,RSAT,PHAS
182      XES
183      155 CONTINUE
184      T=TX/86400.
185      CALL LINE(TP,RP,T,RSAT(2))
186      TP=T
187      RP=RSAT(2)
188      GO TO 154
189      156 CONTINUE
190      REWIND 13
191      CALL ADV
192
193      C
194      C   SATELLITE CLOCK ANGLE VS TIME PLOT
195      C
196      CALL MAPS(-TIM,TIM,0.0,360.0,SDUNIT(1),SDUNIT(2),SDUNIT(3),SDUNIT(
197      X4))
198      CALL CHAROP (0.0,1,1,0)
199      CALL ABSBEM (0.05,0.2)
200      CALL SYMBOL(29HSATELLITE CLOCK ANGLE (DEG)$.)
201      CALL CHAROP (0.0,1,0,0)
202      CALL ABSBEM (0.2,0.01)
203      CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS)$. )
204      READ(13) TX,X,XP,XSAT,XE,R,PHASE,PADP,TARGE,TARGP,RSAT,PHASES
205      TP=TX/86400.
206      RP=RSAT(3)
207      157 CONTINUE
208      READ(13,END=159) TX,X,XP,XSAT,XE,R,PHASE,PADP,TARGE,TARGP,RSAT,
209      PHASES
210      T=TX/86400.
211      CALL LINE(TP,RP,T,RSAT(3))
212      TP=T
213      RP=RSAT(3)
214      GO TO 157
215      159 CONTINUE
216      REWIND 13
217      CALL ADV
218      RETURN
219      END

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DPRT GT.OUTS

MARTIN\*GT.OUTS

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1  SUBROUTINE OUTS
2  COMMON/RAZOR/PICS(4,9),SPPICS(4)
3  DIMENSION SATNAM(2),SATELL(2)
4  COMMON /PLCONS/GMS,GMPL(12),RS,RPL(12),SNAME(2),PLNAME(2,12),
5  X SPV(3),PLPV(3,12),SVE(3),PLVE(3,12),SROT,PLROT(12),SOBL,PLOBL(12)
6  COMMON/POBEAR/SSV(A),SAF(8),HANG2,DCNCLK(8)
7  COMMON/HEDING/TITLE(13)
8  COMMON/TNVE/TVNAME(5)
9  DOUBLE PRECISION TJDV
10 DIMENSION ICK(4)
11 COMMON/JDAYS/TJDV,TT
12 COMMON/FCROUT/POWER,ENERGY,PERCT,IND,R(3),RSAT(3),RAD1(3),IPCN
13 X,FRACT,PHASED,PHASEP,POWLN,NDN,EPERDN
14 COMMON/FLAGS/IFLT,IFLPL,IFLPR
15 COMMON/CHARLI /NCODE,NREC,IP,IVS,NSC,IFLST,NCR
16 COMMON/FLYBY/DUM1(6),X(3),DUM2(9)
17 COMMON/HANDO/TI4,REC(9),REL(9),RES,SMR(9),SMRR(9),SMRS(9),TSMR(9)
18 X,SPSMR,SPSMRS,SPTSVR,SPSVRR
19 COMMON/PHASER/PHASE(8),XRCC(3,8)
20 DIMENSION NS(9)
21 COMMON/CHARAC/P(60)

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22      DATA NS/0,0,1,2,4,7,5,1,0/
23      DATA JFP/0/
24      C
25      C OUTS-2                                OUTS-2
26      C
27      CALL TCONV(I CK,5HCLOCK,ABS(TT),3HSEC)
28      CLOCK=ICK(1)
29      CLOCK=SIGN(CLOCK,TT)
30      ICK(1)=CLOCK
31      WRITE(6,1001)TITLE
32      WRITE(6,1000)IPCN,(ICK(I),I=1,3),TJDV
33      CALL PSCONS(SATNAM,4HNAME,IVS,IP)
34      WRITE(6,1010)PLNAME(1,IP),PLNAME(2,IP),SATNAM
35      WRITE(6,1020)(R(I),RSAT(I),I=1,3)
36      WRITE(6,1030)PHASED,PHASEP,HANG2,SAF(IVS)
37      IF(NCR,EO,1)GO TO 100
38      WRITE(6,1040)PLNAME(1,IP),PLNAME(2,IP),RAD1(2),RAD1(3)
39      GO TO 110
40      100 WRITE(6,1045)SATNAM
41      110 CONTINUE
42      WRITE(6,1060)RES,REC(1),REL(1)
43      SMRKM=SPSMRR * RES
44      RESSMR=SMRKM + RES
45      RECSMR=SMRKM + REC(1)
46      RELSMR=SMRKM + REL(1)
47      WRITE(6,1070)SPSMRS,SPSMRS,SMRKM,SPSMRR
48      TSMRMS=SPTSMR*1.E+3
49      WRITE(6,1080)TSMRMS
50      WRITE(6,1081)RESSMR,RECSMR,RELSMR
51      TEXP=P(26)*1.E+3
52      WRITE(6,1090)TVNAME,TEXP,POWLN,POWER,ENERGY
53      WRITE(6,1091)PERCT,NDN,IND,EPERON
54      NSP=NS(IP)
55      WRITE(6,3000)(P(I),I=17,20)
56      WRITE(6,3010)(PICS(I,1),I=1,4)
57      NSP=NSP+1
58      DO 300 J=2,NSP
59      ISAT=J-1
60      300 WRITE(6,3020)ISAT,(PICS(I,J),I=1,4)
61      NSP=NSP-1
62      WRITE(6,5000)
63      WRITE(6,5010)
64      DO 500 I=1,NSP
65      PHASEZ=PHASE(I)*(180./3.14159)
66      500 WRITE(6,5020)I,XRCC(1,I),PHASEZ,XRCC(2,I),XRCC(3,I)
67      WRITE(6,5070)
68      DO 530 I=1,NSP
69      CALL PSCONS(SATELL,4HNAME,I,IP)
70      530 WRITE(6,5040)I,SSV(I),SAF(I)
71      NSP=NSP+1
72      WRITE(6,5030)
73      DO 510 I=2,NSP
74      NST=I-1
75      510 WRITE(6,5040)NST,REC(I),REL(I)
76      WRITE(6,5060)
77      DO 520 I=2,NSP
78      NST=I-1
79      520 WRITE(6,5050)SMR(I),SMRS(I),SMRR(I),TSMR(I)
80      RETURN
81      1000 FORMAT(5X,15HPICTURE NUMBER ,I5,19X,I3,6H DAYS ,I2,5H HRS ,
82      XI2,17H MIN TO ENCOUNTER,10X,3HJD ,F12.3,/)
83      1001 FORMAT(1H1,13A6,/)
84      1005 FORMAT(/5X,80(1H-)/,5X,15HPICTURE NUMBER ,I5,19X,I3,6H DAYS ,I2,
85      X5H HRS ,I2,17H MIN TO ENCOUNTER/)
86      1010 FORMAT(5X,7HPLANET ,2A6,20X,10HSATELLITE ,2A6)
87      1020 FORMAT(5X,13HRANGE (KM) =,E16.8,11X,13HRANGE (KM) =,E16.8/
88      X 5X,13HCONE (DEG) =,F7.2 ,20X,13HCONE (DEG) =,F7.2 /
89      X 5X,13CLOCK (DEG) =,F7.2 ,20X,13CLOCK (DEG) =,F7.2 /
90      1030 FORMAT(5X,13HPHASE (DEG) =,F7.2 ,20X,13HPHASE (DEG) =,F7.2/
91      $ 5X,13HDIAM (DEG) =,F7.2 ,20X,13HDIAM (DEG) =,F7.2//)
92      1040 FORMAT(5X,27HINSTRUMENT DATA FOR PLANET ,2A6,5X,
93      $ 21H(PICTURE CENTERED AT ,F6.2,9H DEG LAT ,F7.2,11H DEG LONG //)
94      1045 FORMAT(5X,30HINSTRUMENT DATA FOR SATELLITE ,2A6/)
95      1060 FORMAT(4X,26HRESOLUTION FOR TARGET BODY ,/
96      $ 5X,24HAT SPECIFIED LOCATION ,F8.1,9H KM/PIXEL /
97      $ 5X,24HAT SUBSPACECRAFT POINT ,F8.1,9H KM/PIXEL /
98      $ 5X,24HAT LIMB OF TARGET BODY ,F8.1,9H KM/PIXEL //)
99      1070 FORMAT(5X,34HSMFAR DUE TO RELATIVE VELOCITIES ,F8.2,7H KM/SEC /
100      $ 5X,34HSMFAR DUE TO S/C ATTITUDE RATFS ,F8.2,7H KM/SEC /
101      $ 5X,34HORJECT MOTION FROM ALL SOURCES ,F8.2,3H KM /
102      $ 5X,34HNUMBER OF PIXELS SMEARED ,F8.5,7H PIXELS //)
103      1080 FORMAT(4X,39HEXPOSURE TIME FOR ONE-HALF PIXEL SMEAR ,F8.3,
104      $ 9H MILLISEC //)
105      1081 FORMAT(4X,31HEFFECTIVE RESOLUTION WITH SMEAR /
106      $ 5X,24HAT SPECIFIED LOCATION ,F8.1,9H KM/PIXEL /
107      $ 5X,24HAT SUBSPACECRAFT POINT ,F8.1,9H KM/PIXEL /
108      $ 5X,24HAT LIMB OF TARGET BODY ,F8.1,9H KM/PIXEL //)
109      1090 FORMAT(4X,18HEXPOSURE TIME FOR ,5A6,3H = ,F8.3,9H MILLISEC /
110      $ 5X,16HPOWER DENSITY = ,E10.4,24H ERGS/SQ CM/SEC AT LFNS /
111      $ 5X,16HPOWER DENSITY = ,E10.4,26H ERGS/SQ CM/SEC ON SENSOR /
112      $ 5X,16HEXPOSURE = ,E10.4,11H ERGS/SQ CM //)
113      1091 FORMAT(5X,26HPERCENT OF DYNAMIC RANGE = ,F7.3 /
114      $ 5X,26HDIGITAL NUMBER OF EXPOS = ,I4,4H (OF,I4,4H LEVELS)/
115      $ 5X,26HONE DIGITAL NUMBER EQUALS ,F10.4,12H ERGS/SQ CM //)
116      3000 FORMAT(4X,46HNUMBER OF PICTURES WITH RESOLUTION BETTER THAN /
117      $ 5X,17HRESOLUTION LEVELS ,3X,4(F5.1,10X) ,9H KM/PIXEL //)

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118 3010 FORMAT(5X,064PLANET,11X,4(F10.1,5X))
119 3020 FORMAT(5X,10HSATELLITE ,11,9X,4(F10.4,5X))
120 5000 FORMAT(IH1)
121 5010 FORMAT( 5X,14HSATELLITE DATA//7X,3HNUM,5X,10HPRANGE (KM),10X,
122 X11HPHASE (DEG),4X,10HCONE (DFG),5X,11HCLOCK (DFG))
123 5020 FORMAT(8X,11,4X,E15.8,6X,F7.2,8X,F7.2,8X,F7.2)
124 5030 FORMAT( /5X,30HRESOLUTION (KM/PIX) DATA FOR SATELLITES /
125 X,7X,3HNUM,3X,23HRES ALONG RADIUS VECTOR,12X,21HRES AT SATELLITE LI
126 XMB/)
127 5040 FORMAT(8X,11,8X,E15.8,20X,E15.8)
128 5050 FORMAT(4(5X,E15.8))
129 5060 FORMAT( /5X,26HSMEAR DATA FOR SATELLITES /
130 X5X,12HSMEAR DUE TO ,8X,12HSMEAR DUE TO,10X,09HNUMBER OF,9X,13HTIME
131 X TO SMEAR/
132 X5X,12HVEL (KM/SEC),08X,12HS/C (KM/SEC),08X,14HPIXELS SMEARED,6X,
133 X15H1/2 PIXEL (SFC)/)
134 5070 FORMAT( /7X,3HNUM,7X,17HEARTH-SAT-S/C ANG ,
135 $ 17X,18HSATELLITE ANG DIAM/)
136 END

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DPRT GT,PICIN

MARTIN+GT,PICIN

```

1 SUBROUTINE PICIN
2 C
3 C ROUTINE FOR COMPUTING MIN PICTURE TAKING INTERVAL FROM BIT RATE
4 C
5 C
6 C INPUT BULK = BULK STORAGE CAPACITY, BITS
7 C INPUT BULK0 = BITS ALREADY IN BULK STORAGE
8 C INPUT DTUSE = USER INPUT PICTURE TAKING INTERVAL, MIN P(33)
9 C INPUT XBPS = TRANSMIT BIT RATE, BPS
10 C INPUT SCIBPS = BIT RATE FROM OTHER INSTRUMENTS, BPS
11 C INPUT BUFCAP = BUFFER STORAGE CAPACITY, BITS
12 C INPUT BPPIC = BITS PER PICTURE, P(49)
13 C INPUT TFRAM = FRAME READOUT TIME, SEC, P(29)
14 C INPUT TSTAR = PICTURE SEQUENCE START TIME, DAYS
15 C INPUT TSTOP = PICTURE SEQUENCE STOP TIME, DAYS
16 C INPUT RPM = S/C SPIN RATE, ROTW(3) IN RAD/SEC
17 C
18 COMMON/HEDING/TITLE(13)
19 COMMON/REVER/ROTW(3)
20 COMMON/CHARAC/P(60)
21 EQUIVALENCE (P(29),TFRAM),(P(49),BPPIC)
22 X,(P(34),BULK),(P(35),BULK0),(P(38),BUFCAP)
23 X,(P(36),XBPS),(P(37),SCIBPS)
24 DTUSE=P(33)*60.
25 RPM=ROTW(3)*57.2957795131/6.
26 TSTAR=P(31)
27 TSTOP=P(32)
28 WRITE(6,107)TITLE
29 WRITE(6,104) TSTAR,TSTOP,DTUSE,TFRAM,P(50)
30 DTTOT=(TSTOP-TSTAR)*86400.
31 TSTAR=TSTAR*86400.
32 TSTOP=TSTOP*86400.
33 STORD=BULK/BPPIC
34 WRITE(6,105)BULK,BPPIC,STORD,BULK0,BUFCAP
35 TVOUT=XBPS-SCIBPS
36 WRITE(6,108)XBPS,SCIBPS,TVOUT
37 IF(BUFCAP-BPPIC)10,11,11
38 10 BUFCAP=BPPIC
39 WRITE(6,100)BUFCAP
40 11 CONTINUE
41 TBUFO=BUFCAP/TVOUT
42 TBUFI=BUFCAP/P(50)
43 C
44 C TEST FOR TOPS OR PIONEER (BULK GREATER THAN 0 FOR TOPS)
45 C
46 IF(BULK)1,1,2
47 C
48 C SPINNING S/C WITH BUFFER FOR ONE PICTURE (IE, PIONEER)
49 1 DTPIC = TBUFO+ TFRAM
50 IF(RPM)8,8,9
51 8 WRITE(6,103)
52 DTPIC=DTTOT
53 GO TO 6
54 9 IF(DTPIC= 60./RPM)3,3,7
55 3 NROLL=1
56 DTPIC=60./RPM
57 WRITE(6,101)DTPIC,NROLL
58 GO TO 4
59 7 NROLL=DTPIC*RPM/60. +1
60 DTPIC=NROLL*60./RPM
61 WRITE(6,101)DTPIC,NROLL
62 GO TO 4
63 C
64 C THREE AXIS STABLE S/C WITH MORE THAN ONE PICTURE STORAGE (IE, TOPS)
65 C
66 2 DTPIC=BPPIC/TVOUT
67 C
68 C TEST IF USER INTERVAL LESS THAN MINIMUM
69 C
70 4 CONTINUE

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71      IF(DTUSE-DTPIC)5,6,6
72      5 DTUSE=DTPIC
73      P(33)=DTUSE/60.
74      WRITE(6,102) DTUSE
75      C
76      C MAXIMUM NO OF PICTURES/HOUR
77      6 PICPHR=3600./DTPIC
78      PICPDA=24.*PICPHR
79      C
80      C MAXIMUM NO OF PICTURES THAT CAN BE TAKEN
81      NPIC=DTTOT/DTPIC
82      ACTPIC=86400./DTUSE
83      NPICA=DTTOT/DTUSE
84      WRITE(6,106)DTPIC,PICPHR,PICPDA,NPIC,ACTPIC,NPICA
85      RETURN
86      100 FORMAT(5X,56HBUFFER CAPACITY LESS THAN ONE PICTURE, CAPACITY SET T
87      *0 ,E10.3,/)
88      101 FORMAT(5X,38HPICTURE INTERVAL BASED ON ROLL RATE = ,E15.8,4H SEC,
89      *20H, NO OF ROLLS/PIC = ,I4,/)
90      102 FORMAT(5X,36HREQUESTED DELTA T LESS THAN MINIMUM /
91      X ,5X,32HDELTA T (SEC) HAS BEEN RESET TO ,E15.8)
92      103 FORMAT(5X,21HROLL RATE EQUALS ZERO)
93      104 FORMAT( 5X,4RHCOMPUTATIONS FOR MINIMUM PICTURE TAKING INTERVAL
94      X, //5X,28HPICTURE START TIME (DAYS) = ,E15.8/
95      X, 5X,28HPICTURE STOP TIME (DAYS) = ,E15.8/
96      X, 5X,28HDELTA T REQUESTED (SEC) = ,E15.8/
97      X, 5X,28HFRAME READ TIME (SEC) = ,E15.8/
98      X, 5X,28HFRAME READ RATE (BPS) = ,E15.8//)
99      105 FORMAT(5X,36HBULK DATA STORAGE CAPACITY (BITS) = ,E15.8/
100      X 5X,36HPICTURE SIZE (BITS) = ,E15.8/
101      X 5X,36HBULK DATA STORAGE CAPACITY (PICS) = ,E15.8/
102      X 5X,36HBULK CONTENTS IN USE (BITS) = ,E15.8/
103      X 5X,36HBUFFER STORAGE CAPACITY (BITS) = ,E15.8//)
104      106 FORMAT(5X,36H MINIMUM PICTURE INTERVAL (SFC) = ,E15.8/
105      * 5X,36HMAXIMUM PICTURE RATE (PICS/HR) = ,E15.8/
106      * 5X,36HMAXIMUM PICTURE RATE (PIC/DAY) = ,E15.8/
107      * 5X,36HMAXIMUM NUMBER OF PICTURES = ,I6/
108      * 5X,36HACTUAL PICTURE RATE (PIC/DAY) = ,E15.8/
109      * 5X,36HACTUAL NUMBER OF PICTURES = ,I6//)
110      107 FORMAT(1H1,4X,13A6,/)
111      108 FORMAT(5X,36HDATA TRANSMISSION RATE (BPS) = ,E15.8/
112      X 5X,36HRATE FROM OTHER INSTRUMENTS (BPS) = ,E15.8/
113      X 5X,36HREAL TIME PICTUPE RATE (BPS) = ,E15.8//)
114      END

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OPRT GT.PIC2

MARTIN\*GT.PIC2

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1      SUBROUTINE PIC2(ANG2A,ANG2R)
2      COMMON/FOROUT/DUMMYB(13),IPCN,DUMMYC(4)
3      COMMON/HEDING/TITLE(13)
4      COMMON/CHARLI/NCODE,NREC ,IP,IVS,NSC,IFLST,NCR
5      COMMON/GEOM/XE(3),XP(3)
6      DIMENSION ICLK(3)
7      DIMENSION CLOCK(4),LABLE(8),SN(3)
8      DIMENSION UX(3),UPV(3),UPM(3)
9      COMMON/EXTRA/RPLP,ROT
10     COMMON/VW/VWP(3),RIP,ASDP
11     COMMON/POINT/VC(3,9),P(3,9)
12     COMMON/FLYBY/DUM1(6),X(3),DUM2(6),SV(3)
13     COMMON /PLCONS/GMS,GVPL(12),RS,RPL(12),SHAVE(2),PLNAME(2,12),
14     X SPV(3),PLPV(3,12),SVE(3),PLVE(3,12),SR0T,PLR0T(12),SORL,PLORL(12)
15     COMMON / PLOTER / PEN, R(3), SCALE, R2, VT(3), VR(3), VW(3),
16     RPP, TANR
17     COMMON/PCOORD/PV(3),VE(3),PM(3)
18     DIMENSION QL(3)
19     COMMON/PLTBUF/BUF(20)
20     DIMENSION UCK(8)
21     DIMENSION QZ(3)
22     COMMON/TRA/TRACE
23     REAL LAT, LONG
24     DIMENSION GOK(3)
25     DOUBLE PRECISION JDV
26     DIMENSION VQ(3,9)
27     COMMON/JDAYS/JDV,TT
28     DATA PI/3.1415926536/
29     DATA QZ/7.0,-90.0,30.0/
30     DATA QL/08.,-180.0,45.0/
31     ANG2=AMAX1(A*IG2A,ANG2R)
32     NSAT=0
33     CALL TCONV(CLOCK,5HCLOCK,ARS(TT),3HSEC)
34     884 FORMAT('TIME AFTER ENCOUNTER = 'I4,' DAYS 'I2,' HRS 'I2,' MIN')
35     883 FORMAT('TIME BEFORE ENCOUNTER = 'I4,' DAYS 'I2,' HRS 'I2,' MIN')
36     CALL ARCSTP(5.)
37     TWIST=0.0
38     IF(INCR.EQ.1) CALL PLASAT(SV,JDV,IVS,IP)
39     RPP=RPL(IP)
40     IF(NCB.EQ.1) CALL PSCONS(RPP,6HRADIUS,IVS,IP)
41     IF(RPP.LE.0.) GO TO 10
42     ANG3=ANG2/2.0
43     CALL VVIEW(0,0,0,0,0,0)
44     CALL VPROJ

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45      TANR=SQRT(RPP*RPP/(R2*R2-RPP*RPP))
46      TANK=ATAN(TANR)*(180.0/PI)
47      IF(TANK.GE.ANG3) ANG3=TANK
48      SCALE=TAN(ANG3*PI/180.0)
49      CALL SCLPLT(SCALE)
50      CALL LINE(SCALE,SCALE,SCALE,-SCALE)
51      CALL LINE(SCALE,-SCALE,-SCALE,-SCALE)
52      CALL LINE(-SCALE,-SCALE,-SCALE,SCALE)
53      CALL LINE(-SCALE,SCALE,SCALE,SCALE)
54      CALL CHAROP(0,0,1,1,0)
55      CALL ARSBEM(0.05,0.2)
56      C      CALL SYMBOL(17HPICTURE NUMBER %.)
57      CALL NUMBER(IPCH,2HI8)
58      IF(IFLST.NE.1.AND.NCR.NE.1) GO TO 1
59      NSAT=IVS
60      1      CALL SATS(1,0,IP,NSAT,JDV,0,0,0)
61      CALL DISK(IP,NSAT,TITLE,0,0,0)
62      C      CALL SHADER(20,0,SN,IP,NSAT)
63      CALL PGLOBE(PM,JDV,IP)
64      CALL PARLEL(PV,0Z)
65      CALL MERIDN(PV,PM,0L)
66      CALL VSCALE(SN,XP,-1.)
67      IF(TT.LE.0.) ENCODE(48,883,LABLE)(CLOCK(J),J=1,3)
68      IF(TT.GT.0.) ENCODE(48,884,LABLE)(CLOCK(J),J=1,3)
69      CALL SCPRNA(RUF,890,300,20,90.,LABLE,8)
70      GO TO 10
71      IF(TANK.LT.ANG2/2.0) GO TO 10
72      SAVE=TRACE
73      ASDP=TANK
74      CALL VUNIT(UX,X)
75      CALL VUNIT(UPV,PV)
76      CALL VUNIT(UPM,PM)
77      RPLP=RPP
78      ROT=PLROT(IP)
79      DO 5 I=1,3
80      5      VWP(I)=VW(I)
81      RIP=R2
82      ANG4A=ANG2A/2.0
83      ANG4B=ANG2B/2.0
84      CALL FRAME1(P,ANG4A,ANG4B)
85      LAT=90.0-ANGV(UPV,UX,6HDEGREE)
86      CALL VCROSS(GOK,UX,UPV)
87      LONG=90.0+ANGV(GOK,UPM,6HDEGREE)
88      CALL LOOK(DUM,CONE,CLOCK,LAT,LONG)
89      CALL LOCATE(VG,CONE,CLOCK,TWIST)
90      CALL FPLOT(VC)
91      TRACE=SAVE
92      10     CONTINUE
93      CALL ADV
94      RETURN
95      END

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DPRT 6T,PSATP

MARTIN\*GT,PSATP

```

1      SUBROUTINE PSATP
2      COMMON /XZ/ XZ(97), IXZ6
3      COMMON /HEDING / TITLE(13)
4      COMMON /FLYBY/DUMMYA(3),GUSY(3),DUMMYB(12)
5      COMMON /PLTRUF/RUF(20)
6      COMMON /PLCONS/GMS,GMP(12),RS,RPL(12),SNAME(2),PLNAME(2,12),
7      X SPV(3),PLPV(3,12),SVE(3),PLVE(3,12),SROT,PLROT(12),SOBL,PLOBL(12)
8      COMMON / PLOTTER / PEN, R(3), SCALE, R2, VT(3), VR(3), VW(3),
9      RPP, TANR
10     COMMON/PCOORD/PV(3),VE(3),PM(3)
11     COMMON/CHARLI /NCOE,NREC ,IP,IVS,NSC,IFLST,NCR
12     COMMON/JDAYS/JDV,TT
13     COMMON/PLAN/GM
14     DIMENSION XM(3),X(3),XF(3),V(3),XS(3)
15     COMMON/GEOM/XS,XM
16     DOUBLE PRECISION JD,JDV
17     EQUIVALENCE (JD,JDV)
18     DIMENSION NS(9)
19     DATA NS/0,9/
20     DATA NS/0,0,1,2,4,7,5,2,0/
21     C      NUMBER OF SATELLITES
22     RPP=RPL(IP)
23     R2=0.
24     S=5.
25     CALL ARCSTP(S)
26     CALL PLASAT(XM,JD,NS(IP),IP)
27     SCALE=ABSV(XM)*1.1
28     IF(NS(IP).EQ.0) SCALE=15.*RPL(IP)
29     CALL SCLPLT(SCALE)
30     CALL VPROJ
31     CALL ORBVEL(VR,.0)
32     CALL ORBIN(XZ(7),IXZ6)
33     CALL ORBPOS(VT,.0)
34     CALL UCROSS(VW,VT,VR)
35     CALL VEQUAL(GUSY,VW)
36     CALL VVIEW(11,1,10,0,0,0,0)
37     N=3.*24.

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38      N=2*N
39      CALL PLPOS(XS,JD,IP)
40      CALL PLPOS(XM,JD,3)
41      CALL VSCALE(XS,XS,-1.)
42      CALL VSUM(XM,XM,XS)
43      CALL ARROCC(3,32,5.,4)
44      CALL ARROCC(0,64,5.,4)
45      CALL SATS(N,0,IP,0,JD,3600.,0,0)
46      NN=N/2
47      NN=-N
48      DO 233 I=NN,N
49      T=I*3600.
50      CALL ORBIN(XZ(7),IXZ6)
51      CALL ORBPOS(XS,T)
52      233 CALL VPPLT(XS,1H*)
53      CALL DISK(IP,0,TITLE,0,0,0)
54      CALL SINTRP(BUF)
55      310 CALL ADV
56      30  RETURN
57      END

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OPRT GT.RESO

MARTIN\*GT.RESO

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1      SUBROUTINE RESO(DIREC)
2      COMMON/HAND0/TIM,PEC(9),REL(9),RES,SMR(9),SMRR(9),SMRS(9),TSMR(9)
3      X,SPSMR,SPSMRS,SPTSMR,SPSMR
4      DIMENSION SDUNIT(4)
5      COMMON/GEOM/XE(3),YP(3)
6      COMMON/STUFF/XPL(3),VPLV(3),VPLS(3),XSA(3,8),VSAV(3,8),VSAS(3,8),
7      XXCL(3),VCLV(3),VCLS(3)
8      COMMON/JDAYS/JDV,TT
9      DOUBLE PRECISION JDV
10     COMMON/FLAGS/IFLT,IFLPL,IFLPR
11     COMMON/CHARL/NCODE,NREC,IP,IVS,NSC,IFLST,NCR
12     COMMON /PLCONS/GMS,GMPL(12),RS,RPL(12),SNAME(2),PLNAME(2,12),
13     X SPV(3),PLPV(3,12),SVE(3),PLVE(3,12),SROT,PLROT(12),SORL,PLOBL(12)
14     COMMON/CHARAC/P(60)
15     COMMON/XZ/XZ(97)
16     COMMON/TRA/TRACE
17     DIMENSION NAME(4)
18     INTEGER CAMK
19     DATA NAME(3), NAME(4) /6H(KM/P,4HX)$. /
20     DIMENSION PLACE(2,3)
21     DIMENSION XTRA(3,9),XTRA1(3)
22     DIMENSION NS(9)
23     DIMENSION RPPS(9)
24     DIMENSION THING(3)
25     DATA THING(3)/2HS./
26     DATA NS/0,0,1,2,4,7,5,2,0/
27     DIMENSION SYM(8)
28     DATA SYM/3H0S.,3HXs.,3H+S.,3HS.,3HHS.,3HTs.,3HZs.,3HPS./
29     DATA PLACE/10H(CENTER),10H(VER EDGE),10H(HOR EDGE) /
30     DATA SDUNIT/0,1,1,0,0,1,1,0,0/
31     DATA PI,RPD/3.1415926535898,1.7453292519943209E-02/
32     DATA IFR/0/
33     PETE(RADIUS)=SORT(RADIUS*PADIUS-RPP*RPP)
34     IF(IFR.EQ.1) GO TO 60
35     ITR1=10
36     NSP=NS(IP)
37     NXTR=NSP+1
38     RPPS(1)=RPL(IP)
39     DO 50 I=1,NSP
40     CALL PSCONS(RPPS(I+1),6HRADIUS,I,IP)
41     50 CONTINUE
42     60 CONTINUE
43     IF(DIREC.EQ.4HPLOT) GO TO 200
44     DO 90 I=1,3
45     90 XTRA(I,1)=XPL(I)
46     DO 96 ITB=1,NSP
47     DO 94 I=1,3
48     94 XTRA(I,ITB+1)=XSA(I,ITB)
49     96 CONTINUE
50     DO 120 ITB=1,NXTR
51     CALL VEQUAL(XTRA1,XTRA(1,ITB))
52     RCEN=ABSV(XTRA1)
53     IF(RCEN.LE.0.0) GO TO 120
54     RPP=RPPS(ITB)
55     RLIM=PETE(RCEN)
56     RCEN=RCEN-RPP
57     IF(IFR.EQ.0) RMAX=RLIM
58     IF(IFR.EQ.0) RMIN=RCEN
59     IFR=1
60     RMAX1=AMAX1(RCEN,RLIM)
61     RMIN1=AMIN1(RCEN,RLIM)
62     IF(RMAX1.GT.RMAX) RMAX=RMAX1
63     IF(RMIN1.LT.RMIN) RMIN=RMIN1
64     I=1
65     REC(ITR)=RCEN*P(45+I)
66     REL(ITB)=RLIM*P(45+I)
67     100 CONTINUE
68     120 CONTINUE
69     RSPE=ABSV(XCL)

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70      RES=RSPE*P(46)
71      RETURN
72      200 CONTINUE
73      REWIND 13
74      REWIND ITR1
75      TIM=AMAX1(ABS(P(31)),ABS(P(32)))
76      I=1
77      RESMAX=RVAX*P(45+I)
78      RESMIN=RMIN*P(45+I)
79      DO 300 ITB=1,NXTR
80      CALL ADV
81      IF(ITB.GT.2) GO TO 204
82      CALL MAPSSL(-TIM,TIM,RESMIN,RESMAX,SDUNIT(1),SDUNIT(2),SDUNIT(3),
83      $SDUNIT(4))
84      CALL CHAROP (0,0,1,1,0)
85      CALL ABSREM (0,05,0.2)
86      CALL SYMBOL(12HRESOLUTIONS.)
87      CALL SYMBOL(3H $.)
88      NAME(1)=PLACE(1,I)
89      NAME(2) = PLACE(2,I)
90      CALL SYMBOL(NAME)
91      CALL SYMBOL(3H $.)
92      IF(ITB.EQ.2) GO TO 202
93      DO 201 J=1,2
94      201 THING(J)=PLNAME(J,IP)
95      GO TO 203
96      202 THING(1)= 6HSATELL
97      THING(2)=6HITE $.
98      203 CONTINUE
99      CALL SYMBOL(THING)
100     CALL CHAROP (0,0,1,0,0)
101     CALL ABSREM (0,2,0.01)
102     CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS) $.)
103     204 CONTINUE
104     IFR=0
105     REWIND ITP1
106     205 READ(ITR1,END=240)TT,REC,REL,RES,SMR,SMRR
107     210 CONTINUE
108     IF(IFR.EQ.0) GO TO 220
109     IF(REC(ITB).LE.0.0.OR,REL(ITR).LE.0.0) GO TO 300
110     CALL LINE(ITP,RFCP,TT,REC(ITR))
111     CALL LINE(ITP,REL,TT,REL(ITR))
112     220 CONTINUE
113     IF(ITB.EQ.1) GO TO 225
114     IF(IFR.EQ.1) GO TO 225
115     CALL CHAROP (0,0,0,0,0)
116     CALL POINT(TT,REC(ITB))
117     CALL SYMBOL(SYM(ITR-1))
118     225 CONTINUE
119     IFR=1
120     TTP=TT
121     RECP=REC(ITB)
122     RELP=REL(ITB)
123     GO TO 205
124     240 CONTINUE
125     REWIND ITR1
126     IF(ITB.EQ.1) GO TO 300
127     CALL POINT(TTP,RECP)
128     CALL SYMBOL(SYM(ITB-1))
129     XHT=0.98-(ITB-2)*0.03
130     CALL ABSREM (0.75,XHT)
131     CALL SYMBOL(SYM(ITB-1))
132     CALL SYMBOL(3H $.)
133     CALL PSCONS(THING,4HNAME,ITB-1,IP)
134     CALL SYMBOL(THING)
135     300 CONTINUE
136     CALL ADV
137     IFR=0
138     CALL MAPSSL(-TIM,TIM,RESMIN,RESMAX,SDUNIT(1),SDUNIT(2),SDUNIT(3),
139     $SDUNIT(4))
140     CALL CHAROP (0,0,1,1,0)
141     CALL ABSREM (0,05,0.2)
142     CALL SYMBOL(12HRESOLUTIONS.)
143     CALL SYMBOL(3H $.)
144     NAME(1)=PLACE(1,I)
145     NAME(2) = PLACE(2,I)
146     CALL SYMBOL(NAME)
147     CALL SYMBOL(19H FOR PRIMARY BODY$.)
148     CALL ABSREM (0,2,0.01)
149     CALL CHAROP (0,0,1,0,0)
150     CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS) $.)
151     305 READ(ITR1,END=340)TT,REC,RFL,RES,SMR,SMRR
152     310 CONTINUE
153     IF(IFR.EQ.0) GO TO 320
154     CALL LINE(TTP,RESP,TT,RES)
155     320 CONTINUE
156     IFR=1
157     TTP=TT
158     RESP=RES
159     GO TO 305
160     340 CONTINUE
161     CALL ADV
162     REWIND ITR1
163     IFR=0
164     RETURN
165     END

```

QPRT GT.SCROT

MARTIN\*GT.SCROT

```

1      SUBROUTINE SCROT(ROTW)
2      COMMON/XZ/XZ(97)
3      DIMENSION ROT(6),ROTW(3)
4      DATA ROT/.01,.01,.01,.01,.01,.90./
5      DATA PI/3.14159/
6      NS=XZ(18)
7      IF(NS.LT.0) NS=0
8      NS=NS+1
9      GO TO (1,2,3,3,3),NS
10     1      DO 5 I=1,3
11     5      ROTW(I)=ROT(I)*(PI/180.)
12     RETURN
13     2      DO 6 I=4,6
14     6      ROTW(I-3)=ROT(I)*(PI/180.)
15     RETURN
16     3      DO 7 I=1,3
17     7      ROTW(I)=XZ(I+18)*(PI/180.)
18     RETURN
19     END

```

QPRT GT.SMEAR

MARTIN\*GT.SMEAR

```

1      SUBROUTINE SMEAR(DIPEC)
2      DATA INP/0/
3      DIMENSION NS(9)
4      DATA NS/0,0,1,2,4,7,5,2,0/
5      COMMON/CHARLI/NCOOF,NREC,IP,IVS,NSC,IFLST,NCR
6      DIMENSION DUMV(3),RUN(3),VIM(3)
7      COMMON/HANDO/TIM,REC(9),REL(9),RES,SMR(9),SMRR(9),SMRS(9),TSMR(9)
8      X,SPSMR,SPSMRS,SPSMRR,SPSMRR
9      COMMON/CHARAC/P(60)
10     DIMENSION SDUNIT(4)
11     DATA SDUNIT/0,1,1,0,0,1,1,0/
12     COMMON/JDAYS/JDV,TT
13     DOUBLE PRECISION JDV
14     COMMON/FLAGS/IFLT,IFLPL,IFLPR
15     COMMON/STUFF/XPL(3),VPLV(3),VPLS(3),YSA(3,8),VSAV(3,8),VSAS(3,8),
16     XXCL(3),VCLV(3),VCLS(3)
17     DIMENSION THING(3)
18     DATA THING(3)/2HS./
19     DIMENSION SYM(8)
20     DATA SYM/3HS.,3HX.,3H+.3HHS.,3HHS.,3HTS.,3HZS.,3HPS./
21     IF(DIPEC.EQ.4HPL0T) GO TO 200
22     ITR2=10
23     IF(INP.NE.0) GO TO 90
24     NST=NS(IP)
25     90 CONTINUE
26     SMR(1)=SQRT(VPLV(1)*VPLV(1)+VPLV(2)*VPLV(2))
27     SMRS(1)=SQRT(VPLS(1)*VPLS(1)+VPLS(2)*VPLS(2))
28     CALL VSUM(VIM,VPLS,VPLV)
29     SMRT=SQRT(VIM(1)*VIM(1)+VIM(2)*VIM(2))
30     TSMR(1)=REC(1)/(SMRT*2.0)
31     SMRR(1)=(SMRT/REC(1))*P(26)
32     DO 100 I=1,NST
33     IF(REC(I+1).LE.0.0) GO TO 100
34     SMR(I+1)=SQRT(VSAV(1,I)*VSAV(1,I)+VSAV(2,I)*VSAV(2,I))
35     SMRS(I+1)=SQRT(VSAS(1,I)*VSAS(1,I)+VSAS(2,I)*VSAS(2,I))
36     CALL VSUM(VIM,VSAS(1,I),VSAV(1,I))
37     SMRT=SQRT(VIM(1)*VIM(1)+VIM(2)*VIM(2))
38     TSMR(I+1)=REC(I+1)/(SMRT*2.0)
39     SMRR(I+1)=(SMRT/REC(I+1))*P(26)
40     100 CONTINUE
41     TX=TT/86400.
42     SPSMR =SQRT(VCLV(1)*VCLV(1)+VCLV(2)*VCLV(2))
43     SPSMRS =SQRT(VCLS(1)*VCLS(1)+VCLS(2)*VCLS(2))
44     CALL VSUM(VIM,VCLS,VCLV)
45     SMRT=SQRT(VIM(1)*VIM(1)+VIM(2)*VIM(2))
46     SPTSMR =RES/(SMRT*2.0)
47     SPSMRR =(SMRT/RES)*P(26)
48     WRITE(ITR2) TX,REC,REL,RES,SMR,SMRR,SMRS
49     X,SPSMR,SPSMRS,SPSMRR
50     IF(INP.GT.0) GO TO 120
51     INP=INP+1
52     SMRN=SPSMR
53     SMRX=SPSMR
54     SMRSN=SPSMRS
55     SMRSX=SPSMRS
56     SMRRN=SPSMRR
57     SMRRX=SPSMRR
58     NSX=NST+1
59     120 CONTINUE
60     DO 130 I=1,NSX
61     IF(SMR(I).LE.0.0) GO TO 130
62     SMRN=AMIN1(SMRN,SPSMR,SMR(I))
63     SMRX=AMAX1(SMRX,SPSMR,SMR(I))
64     SMRSN=AMIN1(SMRSN,SPSMRS,SMRS(I))
65     SMRSX=AMAX1(SMRSX,SPSMRS,SMRS(I))

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66      SMRRN=AMIN1(SMRRN,SPSMRR,SMRR(I))
67      SMRRX=AMAX1(SMRRX,SPSMRR,SMRR(I))
68      130 CONTINUE
69      RETURN
70      200 CONTINUE
71      REWIND ITR2
72      CALL MAPSSL(-TIM,TIM,SMRN,SMRX,SDUNIT(1),SDUNIT(2),SDUNIT(3),SDUNI
73      *T(4))
74      CALL ABSREM (0.05,0.2)
75      CALL CHAROP (0,0,1,1,0)
76      CALL SYMBOL(27HSWEAR DUE TO VEL (KM/SEC)$.)
77      CALL SYMBOL(24H AT SPECIFIED LOCATIONS.)
78      CALL ABSREM (0.2,0.01)
79      CALL CHAROP (0,0,1,0,0)
80      CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS) $.)
81      IFR=0
82      REWIND ITR2
83      210 CONTINUE
84      READ(ITR2,END=230)TT,REC,REL,RES,SMR,SMRR,SMRS
85      X,SPSMR,SPSMRS,SPSMRR
86      220 CONTINUE
87      IF(IFR.EQ.0) GO TO 225
88      CALL LINE(TTP,SMRP,TT,SPSMR)
89      225 CONTINUE
90      IFR=1
91      TTP=TT
92      SMRP=SPSMR
93      GO TO 210
94      230 CONTINUE
95      REWIND ITR2
96      CALL ADV
97      IFR=0
98      CALL MAPSSL(-TIM,TIM,SMRSN,SMRSX,SDUNIT(1),SDUNIT(2),SDUNIT(3),
99      *SDUNIT(4))
100     CALL CHAROP (0,0,1,1,0)
101     CALL ABSREM (0.05,0.2)
102     CALL SYMBOL(27HSWEAR DUE TO S/C (KM/SEC)$.)
103     CALL SYMBOL(24H AT SPECIFIED LOCATIONS.)
104     CALL CHAROP (0,0,1,0,0)
105     CALL ABSREM (0.2,0.01)
106     CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS) $.)
107     270 CONTINUE
108     READ(ITR2,END=290)TT,REC,REL,RES,SMR,SMRR,SMRS
109     X,SPSMR,SPSMPS,SPSMRR
110     280 CONTINUE
111     IF(IFR.EQ.0)GO TO 285
112     CALL LINE(TTP,SMRSP,TT,SPSMRS)
113     285 CONTINUE
114     IFR=1
115     TTP=TT
116     SMRSP=SPSMRS
117     GO TO270
118     290 CONTINUE
119     IFR=0
120     CALL ADV
121     REWIND ITR2
122     CALL MAPSSL(-TIM,TIM,SMRRN,SMRRX,SDUNIT(1),SDUNIT(2),SDUNIT(3),
123     *SDUNIT(4))
124     CALL ABSREM (0.05,0.2)
125     CALL CHAROP (0,0,1,1,0)
126     CALL SYMBOL(26HNUMBER OF PIXELS SWEARED$.)
127     CALL SYMBOL(24H AT SPECIFIED LOCATIONS.)
128     CALL ABSREM (0.2,0.01)
129     CALL CHAROP (0,0,1,0,0)
130     CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS) $.)
131     240 CONTINUE
132     READ(ITR2,END=260)TT,REC,REL,RES,SMR,SMRR,SMRS
133     X,SPSMR,SPSMRS,SPSMRR
134     250 CONTINUE
135     IF(IFR.EQ.0) GO TO 255
136     CALL LINE(TTP,SMRRP,TT,SPSMRR)
137     255 CONTINUE
138     IFR=1
139     TTP=TT
140     SMRRP=SPSMRR
141     GO TO 240
142     260 CONTINUE
143     CALL ADV
144     CALL MAPSSL(-TIM,TIM,SMRN,SMRX,SDUNIT(1),SDUNIT(2),SDUNIT(3),SDUNI
145     *T(4))
146     CALL ABSREM (0.05,0.2)
147     CALL CHAROP (0,0,1,1,0)
148     CALL SYMBOL(27HSWEAR DUE TO VEL (KM/SEC)$.)
149     CALL SYMBOL(3H $.)
150     CALL SYMBOL(11HSATELLITES.)
151     CALL CHAROP (0,0,1,0,0)
152     CALL ABSREM (0.2,0.01)
153     CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS) $.)
154     CALL CHAROP (0,0,0,0,0)
155     DO 330 I=1,NST
156     REWIND ITR2
157     IFR=0
158     310 CONTINUE
159     READ(ITR2,END=329)TT,REC,REL,RES,SMR,SMRR,SMRS
160     X,SPSMR,SPSMRS,SPSMRR
161     320 CONTINUE

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162         IF(IFR.EQ.0) GO TO 325
163         IF(SMRP.LE.0.0) GO TO 330
164         CALL LINE(TTP,SMRP,TT,SMR(I+1))
165     325 CONTINUE
166         IF(IFR.NE.0) GO TO 328
167         IF(SMR(I+1).LE.0.0) GO TO 330
168         CALL POINT(TT,SMR(I+1))
169         CALL SYMBOL(SYM(I))
170         IFR=1
171     328 CONTINUE
172         TTP=TT
173         SMRP=SMR(I+1)
174         GO TO 310
175     329 CONTINUE
176         CALL POINT(TTP,SMRP)
177         CALL SYMBOL(SYM(I))
178         XHT=0.98-(I-1)*0.03
179         CALL ABSBEM(0.75,XHT)
180         CALL SYMBOL(SYM(I))
181         CALL SYMBOL(3H $.)
182         CALL PSCONS(THING,4HNAME,I,IP)
183         CALL SYMBOL(THING)
184     330 CONTINUE
185         CALL ADV
186         CALL MAPSSL(-TIM,TIM,SMRSN,SMRSX,SDUNIT(1),SDUNIT(2),SDUNIT(3),
187         *SDUNIT(4))
188         CALL CHAROP (0,0,1,1,0)
189         CALL ABSBEM (0.05,0.2)
190         CALL SYMBOL(27HSMEAR DUE TO S/C (KM/SEC)$.)
191         CALL SYMBOL(3H $.)
192         CALL SYMBOL(11HSATELLITES.)
193         CALL CHAROP (0,0,1,0,0)
194         CALL ABSBEM (0.2,0.01)
195         CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS) $.)
196         CALL CHAROP (0,0,0,0,0)
197         DO 390 I=1,NST
198         REWIND ITR2
199         IFR=0
200     370 CONTINUE
201         READ(ITR2,END=388)TT,REC,REL,RES,SMR,SMRR,SMRS
202         X ,SPSMR,SPSMRS,SPSMRR
203     380 CONTINUE
204         IF(IFR.EQ.0)GO TO 385
205         IF(SMRSP.LE.0.0) GO TO 390
206         CALL LINE(TTP,SMRSP,TT,SMRS(I+1))
207     385 CONTINUE
208         IF(IFR.NE.0) GO TO 386
209         IF(SMRS(I+1).LE.0.0) GO TO 390
210         CALL POINT(TT,SMRS(I+1))
211         CALL SYMBOL(SYM(I))
212         IFR=1
213     386 CONTINUE
214         TTP=TT
215         SMRSP=SMRS(I+1)
216         GO TO 370
217     388 CONTINUE
218         CALL POINT(TTP,SMRSP)
219         CALL SYMBOL(SYM(I))
220         XHT=0.98-(I-1)*0.03
221         CALL ABSBEM(0.75,XHT)
222         CALL SYMBOL(SYM(I))
223         CALL SYMBOL(3H $.)
224         CALL PSCONS(THING,4HNAME,I,IP)
225         CALL SYMBOL(THING)
226     390 CONTINUE
227         CALL ADV
228         CALL MAPSSL(-TIM,TIM,SMRRN,SMRRX,SDUNIT(1),SDUNIT(2),SDUNIT(3),
229         XSDUNIT(4))
230         CALL ABSBEM(0.05,0.2)
231         CALL CHAROP (0,0,1,1,0)
232         CALL SYMBOL(26HNUMBER OF PIXELS SMEARED$.)
233         CALL SYMBOL(3H $.)
234         CALL SYMBOL(11HSATELLITES.)
235         CALL ABSBEM(0.2,0.05)
236         CALL CHAROP (0,0,1,0,0)
237         CALL SYMBOL(29HTIME FROM ENCOUNTER (DAYS) $.)
238         CALL CHAROP(0,0,0,0,0)
239         DO 360 I=1,NST
240         IFR=0
241         REWIND ITR2
242     340 CONTINUE
243         READ(ITR2,END=358)TT,REC,REL,RES,SMR,SMRR,SMRS
244         X,SPSMR,SPSMRS,SPSMRR
245     350 CONTINUE
246         IF(SMRR(I+1).LE.0) GO TO 360
247         IF(IFR.EQ.0) GO TO 355
248         IF(SMRRP.LE.0.0) GO TO 360
249         CALL LINE(TTP,SMRRP,TT,SMRR(I+1))
250     355 CONTINUE
251         IF(IFR.NE.0) GO TO 356
252         IF(SMRR(I+1).LE.0) GO TO 360
253         CALL POINT(TT,SMRR(I+1))
254         CALL SYMBOL(SYM(I))
255         IFR=1
256     356 CONTINUE
257         TTP=TT

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258      SMRRP=SMRR(I+1)
259      GO TO 340
260 358 CONTINUE
261      CALL POINT(TTP,SMRRP)
262      CALL SYMBOL(SYM(I))
263      XHT=0.98-(I-1)*0.03
264      CALL ABSREM (0.75,XHT)
265      CALL SYMBOL(SYM(I))
266      CALL SYMBOL(3H %)
267      CALL PSCONS(THING,4HNAME,I,IP)
268      CALL SYMBOL(THING)
269 360 CONTINUE
270      REWIND ITR2
271      CALL ADV
272      IFR=0
273      INP=0
274      RETURN
275      END

```

QPRT GT.TCON

MARTIN\*GT.TCON

```

1      SUBROUTINE TCON(NP)
2      COMMON/HEDING/TITLE(13)
3      COMMON/CHARAC/P(60)
4      COMMON/FLAGS/IFLT,IFLPL,IFLPR
5      COMMON/TCONS/TCONS(200)
6      COMMON/XZ/XZ(97)
7      COMMON/TEST/ITEST(97)
8
9      C
10     C P(31)=START TIME FROM PERIAPSIS IN DAYS
11     C P(32)= STOP TIME FROM PERIAPSIS IN DAYS
12     C P(39)=PICTURES PER CALC STEP
13     C P(40)=MINUTES/PICTURE
14         TCALC=P(39)*P(40)
15         DELT=TCALC/1440.
16         START=ABS(P(31))
17         STOP=P(32)
18     C NP=NUMBER OF CALC STEPS
19     C
20     C IFLPL=CALC STEPS PER PLOT
21         IFLPL=ABS(P(31))/DELT + 1
22         IF(ITEST(81).EQ.1) IFLPL=XZ(81)
23         DTPPL=IFLPL*DELT*1440.
24     C
25     C IFLPR=CALC STEPS PER PRNT
26         IFLPR=1
27         IF(ITEST(82).EQ.1) IFLPR=XZ(82)
28         DTPPR=IFLPR*DELT*1440.
29     C
30     WRITE(6,1001)TITLE
31     1001 FORMAT(1H1,13A6,/)
32     WRITE(6,1020) IFLPL,DTPPL,IFLPR,DTPPR
33     WRITE(6,1000)TCALC
34     C
35     IF(IFLT.EQ.1) GO TO 120
36     IF(ITEST(69).NE.1) GO TO 5
37     NP=1+IFIX((START+STOP)/DELT)
38     IF(NP.GT.200)NP=200
39     GO TO 100
40     5 CONTINUE
41     NP=39
42     DO 10 I=1,NP
43         S1=FLOAT(I-21)/20.
44         S2=FLOAT(I-21)
45         TCONS(I)=START*ARS(S1)*S1*S1*SIGN(1.0,S2)
46     GO TO 120
47     100 CONTINUE
48     DO 110 I=1,NP
49         TCONS(I)=FLOAT(I-1)*DELT+P(31)
50     110 CONTINUE
51     120 CONTINUE
52     WRITE(6,1030)
53     DO 130 I=1,NP
54         NPIC=(I-1)*P(39)+1
55         TH=TCONS(I)*24.
56         TM=TH*60.
57     130 WRITE(6,1010)NPIC,I,TCONS(I),TH,TM
58     RETURN
59     1000 FORMAT(/5X,33HTIME INTERVAL FOR CALCULATIONS = ,F7.2,8H MINUTES,/)
60     1010 FORMAT(5X,I4,2X,I4,3E16.7)
61     1020 FORMAT( 5X,16HPLOT INTERVAL = ,I2,14H CALC STEPS = ,F7.2,7HMINU
62     $TES,/,5X,16HPRNT INTERVAL = ,I2,13HCALC STEPS = ,F7.2,
63     $8H MINUTES,/)
64     1030 FORMAT(3X,56HPICTURE CALC TIME (DAYS) TIME (HRS) TIME (M
65     $IN))
66     END

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QPRT GT.TVCHAR

MARTIN\*GT.TVCHAR

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1  SUBROUTINE TVCHAR(INST)
2  DIMENSION TVAR(45)
3  COMMON/HEDING/TITLE(13)
4  COMMON/TNVE/TVNAME(5)
5  COMMON/XZ/XZ(97)
6  COMMON/CHARAC/P(60)
7  COMMON/TEST/ITEST(97)
8  DATA PI/3.14159/
9  DATA TVAR/ 6HFOC LN,6HDIAM ,6HOBSCUR,6HTRANS ,6HSIZE-V,6HSIZE-H,
10 X 6HLINES ,6HPIXELS,6HRIT/PX,6HMINEXP,6HMAXEXP,6HRESO-1,6HRESO-2,
11 X 6HRESO-3,6HRESO-4,6HSENSOR,6HB FILT,6HG FILT,6HR FILT,6HP FILT,
12 X 6HDT EXP,6H OPEN ,6H OPEN ,6HT READ,6HERASET,6HTSTART,6HTSTOP ,
13 X 6HDEL T ,6HRULK ,6HRULK-0,6HRITRAT,6HSCIRPS,6HDIFFER,6HPICT/ST,
14 X 6HDEL TF,6HF/STOP,6HA BLOC,6HDIF LV,6HFQV-V ,6HFQV-H ,6HRES-C ,
15 X 6HRES-V ,6HRES-H ,6HRIT/PC,6HRR-RPS,6HT/NUM ,6HT/NUMF,6H OPEN ,
16 X 6H OPEN ,6H OPEN ,6H OPEN ,6H OPEN ,6H OPEN ,6H OPEN /
17 C
18 C INSTR FROM INPUT ??=INST=IJK, I SPECIFIES INSTRUMENT TYPE, I=1 FOR TV
19 C J SPECIFIES WHICH TV IN SUBROUTINE
20 C INSTR = INST-100 = JK K IS UNUSED
21 C IF J=0, J IS SET TO 1
22 C USER MAY CHANGE TV-J VALUES WITH INPUTS NO 31 THRU 69
23 C
24 C 1 THRU 5, INSTRUMENT NAME (INPUTS 31 THRU 35)
25 C
26 C 6 FOCAL LENGTH, CM (36)
27 C 7 CLEAR APERTURE DIAMETER, CM (37)
28 C 8 OBSCURATION DIAMETER, CM (38)
29 C 9 OPTICS TRANSMISSION, REFL + ABSORP, FRACTION (39)
30 C SENSOR DIMENSIONS, CM
31 C 10 VERTICAL, ACROSS SCAN LINES (40)
32 C 11 HORIZONTAL, ALONG SCAN LINE (41)
33 C 12 NUMBER OF SCAN LINES (42)
34 C 13 NUMBER OF PIXELS PER SCAN LINE (43)
35 C 14 NUMBER OF BITS PER PIXEL (44)
36 C 15 MINIMUM DETECTABLE EXPOSURE, ERGS/CM (45)
37 C 16 MAXIMUM OR HIGHLIGHT EXPOSURE, ERGS/CM (46)
38 C 17 THRU 20, MINIMUM RESOLUTION LEVELS
39 C 21 SENSOR RESPONSE CURVE IDENTIFICATION (51)
40 C 22 BLUE FILTER TRANSMISSION CURVE ID (52)
41 C 23 GREEN FILTER (53)
42 C 24 RED FILTER (54)
43 C 25 POLARIZING FILTER (55)
44 C 26 EXPOSURE TIME (56)
45 C 27 THRU 28 OPEN (57 THRU 58)
46 C 29 FRAME READ TIME, SECONDS (59)
47 C 30 FRAME ERASE TIME, SECONDS (60)
48 C 31 PICTURE TAKING START TIME (DAYS) (61)
49 C 32 PICTURE TAKING STOP TIME (DAYS) (62)
50 C 33 DELTA T PER PICTURE (MIN) (63) CAN BE CHANGED BY PROGRAM
51 C 34 BULK STORAGE CAPACITY (BITS) (64)
52 C 35 BULK ZERO STATE (BITS) (65)
53 C 36 TRANSMISSION BIT RATE, BPS (66)
54 C 37 OTHER INSTRUMENT BIT RATES (67)
55 C 38 BUFFER CAPACITY (BITS) (68)
56 C 39 PICTURES PER CALCULATION STEP (69)
57 C
58 C P(40) THRU P(51) ARE COMPUTED
59 C 40 DELTA T PER PICTURE (MIN) (70) FIXED
60 C 41 F/NUMBER OF F/STOP
61 C 42 AREA BLOCKAGE, FRACTION
62 C 43 DIFFRACTION LIMIT, RADIANS
63 C 44 FIELD OF VIEW, VERTICAL, DEGREES
64 C 45 FIELD OF VIEW, HORIZONTAL, DEGREES
65 C ANGULAR RESOLUTION, RADIANS/PIXEL
66 C 46 AT CENTER
67 C 47 AT VERTICAL EDGE, CENTER
68 C 48 AT HORIZONTAL EDGE, CENTER
69 C 49 BITS PER PICTURE
70 C 50 READ RATE, BPS
71 C 51 T/NUMBER (CAN BE CHANGED BY PROGRAM)
72 C 52 T/NUMBER-FIXED
73 C
74 INSTR=INST-100
75 J=INSTR/10
76 IF(J.LT.1.OR.J.GT.6) J=1
77 GO TO (1,2,3,4,5,6),J
78 1 CONTINUE
79 C
80 C NARROW ANGLE SIT, INSTR=110
81 C
82 P(1)=6HSIT NA
83 P(2)=6HRROW A
84 P(3)=6HNGLE C
85 P(4)=6HAMERA
86 P(5)=6H(CAND)
87 P(6)=200.0
88 P(7)=23.0
89 P(15)=8.E-6
90 P(16)=P(15)*250.
91 P(21)=1.0
92 P(26)=0.001
93 P(27)=0.
94 P(28)=0.
95 P(29)=40.

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96          P(30)=0.0
97          GO TO 7
98          2 CONTINUE
99
100         C
101         C WIDE ANGLE SIT. INSTR=120
102         C
103         P(1)=6HSIT WI
104         P(2)=6HDE ANG
105         P(3)=6HLE CAM
106         P(4)=6HERA
107         P(5)=6H(CAND)
108         P(6)=20.
109         P(7)=5.0
110         P(15)=9.E-6
111         P(16)=P(15)*250.
112         P(26)=0.0001
113         P(27)=0.001
114         P(28)=0.010
115         GO TO 7
116         3 CONTINUE
117
118         C
119         C NARROW ANGLE SILICON VIDICON INSTR=130
120         C
121         P(1)=6HSI NAR
122         P(2)=6HROW AN
123         P(3)=6HGLE CA
124         P(4)=6HMER A
125         P(5)=6H
126         P(6)=200.0
127         P(7)=23.0
128         P(16)=0.5
129         P(15)=P(16)/250.
130         P(26)=.05
131         P(27)=.10
132         P(28)=.50
133         GO TO 7
134         4 CONTINUE
135
136         C
137         C WIDE ANGLE SILICON VIDICON INSTR=140
138         C
139         P(1)=6HSI WID
140         P(2)=6HE ANGL
141         P(3)=6HE CAME
142         P(4)=6HRA
143         P(5)=6H
144         P(6)=20.0
145         P(7)=5.0
146         P(16)=0.5
147         P(15)=P(16)/250.
148         P(26)=.1
149         P(27)=.5
150         P(28)=1.
151         GO TO 7
152         5 CONTINUE
153
154         C
155         C NARROW SEC VIDICON INSTR=150
156         C
157         P(1)=6HOPE 2
158         P(2)=6HDEG FO
159         P(3)=6HV CAME
160         P(4)=6HRA SEC
161         P(5)=6H TUBE
162         P(6)=50.8
163         P(7)=7.62
164         P(15)=0.0001
165         P(16)=0.01
166         P(26)=0.4
167         P(27)=.1
168         P(28)=.01
169         GO TO 7
170         6 CONTINUE
171
172         C
173         C WIDE SEC VIDICON INSTR=160
174         C
175         P(1)=6HSEC WI
176         P(2)=6HDE ANG
177         P(3)=6HLE CAM
178         P(4)=6HERA
179         P(5)=6H
180         P(7)=1.524
181         P(6)=10.16
182         P(15)=0.0001
183         P(16)=0.01
184         P(26)=.1
185         P(27)=0.01
186         P(28)=0.001
187         7 CONTINUE
188         P(8)=0.0
189         P(9)=0.85
190         P(10)=1.60
191         P(11)=1.60
192         P(12)=800.
193         P(13)=800.
194         P(14)=8.0
195         P(17)=300.
196         P(18)=100.0

```

```

192      P(19)= 50.0
193      P(20)=10.0
194      P(21) = 1.0
195      P(22) = 1.0
196      P(23)=1.
197      P(24)=1.0
198      P(25)=-1.0
199      P(29) =40.
200      P(30) = 0.1
201      P(31)=-1.5
202      P(32)=1.5
203      P(33)=15.0
204      P(34)=100000000n.
205      P(35)=0.0
206      P(36)=47400.
207      P(37)=100.
208      P(38)=P(14)*P(12)*P(13)
209      P(39)=4.
210
211      C
212      C OVERLAYS SYTEM VALUFS WITH USER INPUTS
213      DO 77 I=31,35
214      IF(ITEST(I).EQ.1) P(I-30)=TVNAME(I-30)
215      77 CONTINUE
216      DO 8 I=36,70
217      IF(ITEST(I).EQ.1) P(I-30)=XZ(I)
218      8 CONTINUE
219      P(40)=P(33)
220      P(41)=P(6)/P(7)
221      P(42)=(P(8)/P(7))**2)
222      P(43)=(6.71E-05)/P(7)
223      P(45)=2.*ATAN(P(11)/(2.*P(6)))*180./PI
224      P(44)=2.*ATAN(P(10)/(2.*P(6)))*180./PI
225      U=P(10)/(P(12)*P(6))
226      V=COS(P(44))**2
227      P(46)=ATAN(U/(1.-2.*(U**2)))
228      P(47)=ATAN(U*V/(1.-2.*(U*V)**2))
229      U=P(11)/(P(13)*P(6))
230      V=COS(P(45))**2
231      P(48)=ATAN(U*V/(1.-2.*(U*V)**2))
232      P(49)=P(14)*P(12)*P(13)
233      P(50) = P(49)/P(29)
234      P(51)=P(41)/SQRT((1.-P(42))*P(9))
235      P(52)=P(51)
236      DO 40 I=1,5
237      40 TVNAME(I)=P(I)
238      DO 10 I=53,60
239      10 P(I)=0.
240      WRITE(6,1040)TITLE
241      WRITE(6,1010) (P(I),I=1,5)
242      DO 20 I= 6,40
243      IF(ITEST(I+30).EQ.1) WRITE(6,1020)I,TVAR(I-5),P(I)
244      20 IF(ITEST(I+30).NE.1) WRITE(6,1000)I,TVAR(I-5),P(I)
245      DO 30 I=41,60
246      30 WRITE(6,1030)I,TVAR(I-5),P(I)
247      C
248      CALL FOLDER(INST)
249      CALL PICIN
250      C
251      RETURN
252      1000 FORMAT(5X,I2,5X,A6,2H= ,E15.8)
253      1010 FORMAT(5X, ,23HTV CHARACTERISTICS FOR ,5A6/)
254      1020 FORMAT(5X,I2,5X,A6,2H= ,F15.8,5X,11H USER INPUT )
255      1030 FORMAT(5X,I2,5X,A6,2H= ,E15.8,5X,16H COMPUTED VALUES )
256      1040 FORMAT(1H1,13A6,/)
257      END

```

DPRT GT.XLIMB

MARTIN\*GT.XLIMB

```

1      SUBROUTINE XLIMB
2      COMMON/PTLB/THA,R(3),DEI,K
3      DIMENSION FVL(3)
4      PI=3.1415926536
5      RTD=57.2957795
6      DTR=0.01745329
7      THE=-PI/18.
8      STHA=SIN(R(3)*DTR)
9      CTHA=COS(R(3)*DTR)
10     SPHI=SIN(R(2)*DTR)
11     CPHI=COS(R(2)*DTR)
12     PSI=THA
13     CPSI=COS(PSI)
14     SPSE=SIN(PSI)
15     DO 8I=1,37
16     THE=THE+PI/ 8.
17     CTHE=COS(THE)
18     STHE=SIN(THE)
19     AF=CTHA*CPSI*SPHI-STHA*SPSE*CTHE-CTHA*SPSE*CPHI*STHE
20     BF=STHA*CPSI*SPHI+CTHA*SPSE*CTHE-STHA*SPSE*CPHI*STHE
21     CF=CPSI*CPHI+SPSE*SPHI*STHE
22     FVL(1)=AF
23     FVL(2)=BF
24     FVL(3)=CF

```

```

3      CALL SPHERE(FVL,FVL,2HTO,5HPOLAR,6HDFGREF)
26     A=DEI*ABS(1A0.*(K-1)-FVL(2))
27     ZON=FVL(3)*DTR-PI/2.
28     X1 = A*COS(ZON)
29     Y1 = A*SIN(ZON)
30     IF(K.EQ.2.AND.FVL(2).LT.90.)GO TO 10
31     IF(K.EQ.1.AND.FVL(2).GT.90.) GO TO 10
32     IF(I.EQ.1) GO TO 10
33     CALL LINE(X1,Y1,X2,Y2)
34     10 X2=X1
35     Y2=Y1
36     8 CONTINUE
37     RETURN
38     END

```

QPRT GT,NOCHAR

```

MARTIN*GT.NOCHAR
1      SUBROUTINE NOCHAR(INST)
2      COMMON/HEDING/TITLE(13)
3      COMMON/CHARAC/P(60)
4      RETURN
5      END

```

QPRT GT,UVCHAR

```

MARTIN*GT.UVCHAR
1      SUBROUTINE UVCHAR(INST)
2      COMMON/HEDING/TITLE(13)
3      COMMON/CHARAC/P(60)
4      RETURN
5      END

```

QPRT GT,ABSDEM

```

MARTIN*GT.ABSDEM
1      SUBROUTINE ABSDEM(X,Y)
2      COMMON / PLTBUF / BUF(20)
3      COMMON / CHARF / NSFL
4      NX = X*1023.
5      NY = (1. - Y)*1023.
6      CALL SPRINT(NX,NY,NSFL,1H )
7      BUF(9) = NX
8      BUF(10) = NY
9      RETURN
10     END

```

QPRT GT,CHAROP

```

MARTIN*GT.CHAROP
1      SUBROUTINE CHAROP(DUM,DUM,ISIZE,IOR,DUM)
2      COMMON / CHARF / NSFL
3      ISIS = ISIZE + 1
4      GO TO (10, 20, 30, 40),ISIS
5      10 NSFL = 4
6      GO TO 50
7      20 NSFL = 8
8      GO TO 50
9      30 NSFL = 12
10     GO TO 50
11     40 NSFL = 16
12     50 IF(IOR .EQ. 1) NSFL = -NSFL
13     RETURN
14     END

```

QPRT GT,LINE

```

MARTIN*GT.LINE
1      SUBROUTINE LINE(X1,Y1,X2,Y2)
2      COMMON /PLTBUF / BUF(20)
3      CALL SINTRP(BUF)
4      CALL SDNPUT(X1,Y1,BUF,0)
5      CALL SDNPUT(X2,Y2,BUF,0)
6      RETURN
7      END

```

QPRT GT,MAP

```

MARTIN*GT,MAP
 1      SUBROUTINE MAP(XMIN,XMAX,YMIN,YMAX,XMI,XMA,YMI,YMA)
 2      COMMON / PLTRUF / RUF(20)
 3      DIMENSION X(4), S(4)
 4      X(1) = XVIN
 5      X(2) = YVIN
 6      X(3) = XMAX
 7      X(4) = YMAX
 8      S(1) = XMI*1023.
 9      S(2) = ABS(1.0 - YMI)*1023.
10      S(3) = XMA*1023.
11      S(4) = ABS(1.0 - YMA)*1023.
12      CALL SINIT(BUF,20,X,S)
13      RETURN
14      END

```

QPRT GT,MAPS

```

MARTIN*GT,MAPS
 1      SUBROUTINE MAPS(XMIN,XMAX,YMIN,YMAX,XMI,XMA,YMI,YMA)
 2      COMMON / PLTRUF / RUF(20)
 3      DIMENSION FMTX(3), FMTY(3)
 4      CALL SCALEK(XMIN,XMAX,C,D,KVAJX,KMINX)
 5      CALL FMTLAB(C,D,KVAJX,15,FMTX)
 6      CALL SCALEK(YMIN,YMAX,C,D,KVAJY,KMINY)
 7      CALL FMTLAB(C,D,KVAJY,15,FMTY)
 8      CALL MAP(XMIN,XMAX,YMIN,YMAX,XMI,XMA,YMI,YMA)
 9      CALL SGRID(BUF,KVAJX,0,FMTX,KVAJY,0,FMTY,1)
10      RETURN
11      END

```

QPRT GT,MAPSSL

```

MARTIN*GT,MAPSSL
 1      SUBROUTINE MAPSSL(XMIN,XMAX,YMIN,YMAX,XMI,XMA,YMI,YMA)
 2      COMMON / PLTRUF / RUF(20)
 3      DIMENSION FMTX(3), FMTY(3)
 4      CALL SCALEK(XMIN,XMAX,C,D,KVAJX,KMINX)
 5      CALL FMTLAB(C,D,KVAJX,15,FMTX)
 6      CALL SCALEK(YMIN,YMAX,C,D,KVAJY,KMINY)
 7      CALL FMTLAB(C,D,KVAJY,15,FMTY)
 8      CALL MAP(XMIN,XMAX,YMIN,YMAX,XMI,XMA,YMI,YMA)
 9      CALL SGRID(BUF,KVAJX,0,FMTX,-KVAJY,0,FMTY,1)
10      RETURN
11      END

```

QPRT GT,NUMBER

```

MARTIN*GT,NUMBER
 1      SUBROUTINE NUMBFR(N,FMT)
 2      COMMON / PLTRUF / RUF(20)
 3      COMMON / CHARF / NSFL
 4      ENCODE(4,900,LAR) N
 5      900  FORMAT(I4)
 6      NX = BUF(9)
 7      NY = BUF(10)
 8      CALL SPRNTA(NX,NY,NSFL,LAR,1)
 9      RETURN
10      END

```

QPRT GT,NUMBEF

```

MARTIN*GT,NUMBEF
 1      SUBROUTINE NUMBEF(F,FMT)
 2      COMMON / PLTRUF / RUF(20)
 3      COMMON / CHARF / NSFL
 4      ENCODE(4,900,FAR) F
 5      900  FORMAT(F4.1)
 6      NX = BUF(9)
 7      NY = BUF(10)
 8      CALL SPRNTA(NX,NY,NSFL,FAR,1)
 9      RETURN
10      END
11      I T
12      N

```

QPRT GT,POINT

```

MARTIN*GT,POINT
 1      SUBROUTINE POINT(X,Y)
 2      COMMON / PLTRUF / RUF(20)

```

```

3      CALL SINTRP(RUF)
4      CALL SDNPUT(X,Y,RUF,0)
5      CALL SDNPUT(X,Y,RUF,0)
6      CALL SINTRP(RUF)
7      RETURN
8      END

```

OPRT 6T,SETBEM

MARTIN\*GT,SETBEM

```

1      SUBROUTINE SETBFM(X,Y)
2      COMMON / PLTRUF / BUF(20)
3      CALL SINTRP(RUF)
4      CALL SDNPUT(X,Y,BUF,0)
5      RETURN
6      END

```

OPRT 6T,SYMBOL

MARTIN\*GT,SYMBOL

```

1      SUBROUTINE SYMBOL(A)
2      COMMON / CHARF / NSFL
3      COMMON / PLTRUF / RUF(20)
4      NX = BUF(9)
5      NY = BUF(10)
6      IF(NSFL .LT. 0) NY = 1023 - NY
7      CALL SPRINT(NX,NY,NSFL,A)
8      RETURN
9      END

```

```

00101 1*      SUBROUTINE ARC
00103 2*      REAL IV(3),IU(3)
00104 3*      DIMENSION VQ(3,9),L(9),V(3),OV(3),U(3),UZ(3),VN(3),VM(3)
00105 4*      COMMON/BRTC/IV,V
00106 5*      COMMON/PCOORD/PV(3),VE(3),PH(3)
00107 6*      COMMON/EXTRA/RPL,ROT
00110 7*      COMMON/VW/VW(3),R2,ASD
00111 8*      COMMON/FLAG/LL,DUM(2),NI,MFL
00112 9*      DATA UZ/D.,0.,1./
00114 10*     CALL PENUP
00115 11*     CALL VTRANS(VN,VW,2HTO,PH,PV)
00116 12*     CALL VCROSS(VH,VN,UZ)
00117 13*     CALL VTRANS(U,V,2HTO,VM,VN)
00120 14*     CALL VTRANS(IU,IV,2HTO,VM,VN)
00121 15*     CALL SPHERE(U,U,2HTO,5HPOLAR,6HDEGREE)
00122 16*     CALL SPHERE(IU,IU,2HTO,5HPOLAR,6HDEGREE)
00123 17*     S = U(3) -IU(3)
00124 18*     IF(S.LT.0.) S = S + 360.
00124 19*     CALL ARCSTP(4,)
00127 20*     CALL PLTARC(IV,VN,S)
00130 21*     RETURN
00131 22*     END

```

END OF COMPILATION: 3 DIAGNOSTICS.

```

00101 1*      SUBROUTINE EUREKA(VQ,VC,PC,P)
00103 2*      DIMENSION VQ(3),P(3),VC(3),PC(3)
00104 3*      COMMON/VW/VW(3),R2,ASD
00105 4*      COMMON/FAHE/C1(3),C3(3)
00106 5*      COMMON/PCOORD/PV(3),VE(3),PH(3)
00107 6*      COMMON/EXTRA/RPL,ROT
00110 7*      CALL VTRANS(PC,P,4HFROM,C1,C3)
00111 8*      CA=DOT(PC,VN)
00112 9*      SROOT=RPL**2+D-R2**2+D*(1.-CA**2+D)
00113 10*     IF(SROOT.LT.0.) SROOT=0+0
00115 11*     CALL VCOMB(VC,PC,R2*CA-SQRT(SROOT),VW,-R2)
00116 12*     CALL VTRANS(VQ,VC,2HTO,PH,PV)
00117 13*     RETURN
00120 14*     END

```

```

00101 1*      SUBROUTINE FIND(VQ1,LD,I)
00103 2*      REAL M,K
00104 3*      INTEGER F
00105 4*      DIMENSION L(9),VT(3),P(3),Q(3),R(3),VR(3),VC(3),VQ(3)
00106 5*      COMMON/TRA/TRACE
00107 6*      COMMON/PC/PC(3,9)
00110 7*      COMMON/PCOORD/PV(3),VE(3),PH(3)
00111 8*      COMMON/EXTRA/RPL,ROT
00112 9*      COMMON/VW/VW(3),R2,ASD
00113 10*     DATA L/1,2,3,6,9,8,7,4,1/
00115 11*     IF(TRACE.EQ.5HTRACE)PRINT 999
00120 12*     A = TAN(ASD)
00121 13*     N = L(I-1)
00122 14*     F = L(I)
00123 15*     CALL VEQUAL(P,PC(1,N))
00124 16*     CALL VEQUAL(Q,PC(1,F))
00125 17*     CALL UCROSS(VT,VW,P)

```

```

00126 18* CALL VCROSS(VH,VW,VT)
00127 19* XP=0.
00130 20* B=DOT(P,VR)/DOT(P,VW)
00131 21* QW=DOT(Q,VW)
00132 22* XQ=DOT(Q,VT)/QW
00133 23* YQ=DOT(Q,VR)/QW
00134 24* M=(YQ-B)/XQ
00135 25* SROOT=(M**2 + 1.)*A**2 - B**2
00136 26* IF(SROOT.LT.0.) GO TO 1
00140 27* K=SIGN(1.,LD*XQ)
00141 28* X = (-M*B + K *SQR(SROOT))/( M**2 + 1.)
00142 29* Y = M*X + B
00143 30* CALL VLOAD(K,X,Y,1.)
00144 31* CALL VUNIT(R,R)
00145 32* CALL VTRANS(R,R,MHFROM,VT,VW)
00146 33* CA=DOT(R,VW)
00147 34* CALL VCOMBIVC1,VW,-R2,R,R2*CA)
00150 35* CALL VTRANS(VQ1,VC1,2HTO,PH,PV)
00151 36* CALL VPLOT(VQ1)
00152 37* GO TO 3
00153 38* 1 PRINT 2
00155 *DIAGNOSTIC* * IS AN IMPROPER PUNCTUATION MARK.
00155 39* 2 FORMAT(1H0,*SUBROUTINE FIND HAD TROUBLE*)
00156 40* 3 IF(TRACE.EQ.5HTRACE) PRINT 999
00161 *DIAGNOSTIC* * IS AN IMPROPER PUNCTUATION MARK.
00161 41* 999 FORMAT(* FIND SUBROUTINE*)
00162 42* RETURN
00163 43* END

```

```

00101 1* SUBROUTINE FPLLOT(VQ)
00103 2* REAL IV(3),IU(3)
00104 3* DIMENSION VQ(3,9),L(9),V(3),OV(3),U(3),UZ(3),VN(3),VM(3)
00105 4* COMMON/BRTC/IV,V
00106 5* COMMON/PCOORD/PV(3),VE(3),PM(3)
00107 6* COMMON/EXTRA/RPL,ROT
00110 7* COMMON/VW/VW(3),R2,ASD
00111 8* COMMON/FLAG/LL,DUM(2),N1,MFL
00112 9* COMMON/TRA/TRACE
00113 10* DATA UZ/D.,D.,1./
00115 11* DATA L/1,2,3,6,9,8,7,4,1/
00117 12* IF(TRACE.EQ.5HTRACE) PRINT 999
00122 13* ENCODE(6,998,LABEL) N1
00125 14* CALL VPPLT(VQ(1,5),LABEL)
00126 15* IF(LL.EQ.1) GO TO 12
00130 16* MFL = 0
00131 17* CALL VZERO(IV)
00132 18* CALL VZERO(OV)
00133 19* CALL VPLOT(VQ(1,1))
00134 20* LO = 0
00135 21* IF(ABS(VQ(1,1)).GT.1.001*RPL) LO=1
00137 22* DO 10 I=2,9
00142 23* J=L(I)
00143 24* LN = 0
00144 25* IF(ABS(VQ(I,J)).GT.1.001*RPL) LN = 1
00146 26* LD = LN - LO
00147 27* LO = LN

```

```

00150 28* IF(LD.EQ.0) GO TO 10
00152 29* CALL FIND(V,LD,1)
00153 30* IF(LD.EQ.1) GO TO 6
00155 31* IF(ABS(VI),LE.0.) GO TO 8
00157 32* CALL ARC
00160 33* CALL VPLOT(V)
00161 34* GO TO 10
00162 35* 6 CALL VEQUAL(IV,V)
00163 36* GO TO 10
00164 37* 8 CALL VEQUAL(OV,V)
00165 38* 10 CALL VPLOT(VQ(1,J))
00167 39* CALL PENUP
00170 40* IF(ABS(VQ(1,J)).LE.0.) GO TO 12
00172 41* CALL VEQUAL(IV,OV)
00173 42* CALL ARC
00174 43* 12 IF(TRACE.EQ.5HTRACE) PRINT 999
00177 44* 998 FORMAT(12)
00200 *DIAGNOSTIC* * IS AN IMPROPER PUNCTUATION MARK.
00200 45* 999 FORMAT(* FPLLOT SUBROUTINE*)
00201 46* RETURN
00202 47* END

```

```

00101 1* SUBROUTINE FPRINT(VQ)
00103 2* REAL IN(9)
00104 3* DIMENSION VQ(3,9),EM(9),VS(3,9),PN(3),UT(3),CAL(6),TIME(4),CC(3)
00105 4* COMMON/VW/VW(3),R2,ASD
00106 5* COMMON/FAME/C1(3),C3(3)
00107 6* COMMON/FPRT/JDE,TSEC,CONE,CLOCK,U(3),PLNM(2)
00110 7* COMMON/CLLES7/C(3),S(3),SN(3)
00111 8* COMMON/POINT/VC(3,9),P(3,9)
00112 9* COMMON/PC/PC(3,9)
00113 10* COMMON/FLAG/LL,M,MH,DUM(2)
00114 11* COMMON/TRA/TRACE

```

```

00115 12*      DATA P1,F/3,1415925536,.017453293/
00120 13*      IF(TRACE.EQ.5HTRACE) PRINT 999
00123 14*      MM=6
00124 15*      IF(ILL.EQ.1) GO TO 8
00124 16*      DO 1 I=1,9
00131 17*      I CALL TOPO(EH(I),IN(I),VS(I,1),VQ(I,1),VC(I,1),PC(I,1))
00133 18*      J = 1
00134 19*      K = 9
00135 20*      GO TO 30
00136 21*      8 CALL TOPO(EH(5),IN(5),VS(1,5),VQ(1,5),VC(1,5),PC(1,5))
00137 22*      J = 5
00140 23*      K = 5
00140 24*      C COMPUTE SPACECRAFT VELOCITY W.R.T. THE ROTATING POINT OF 1
00141 25*      30 CALL VCROSS(PN,PV,PM)
00142 26*      CALL VCOMB(UT,PN,COS(VS(3,5)*F),PM,-SIN(VS(3,5)*F))
00143 27*      CALL VTRANS(UT,UT,4HFROM,PM,PV)
00144 28*      CALL VSCALE(UT,UT,COS(VS(2,5)*F)*RPL*2.*PI*ROT/86400.)
00145 29*      CALL VDIF(U,U,UT)
00146 30*      CALL VTRANS(U,U,2HTO,C1,C3)
00147 31*      VT=SQRT(U(1)**2 + U(2)**2)
00150 32*      CALL SPHERE(U,U,2HTO,5HPOLAR,6HDEGREE)
00151 33*      PSD=ASD/F
00152 34*      PHA=180.*CONE
00153 35*      CALL VTRANS(CC,VW,2HTO,C,5)
00154 36*      CALL SPHERE(CC,CC,2HTO,5HPOLAR,6HDEGREE)
00155 37*      JDV=JDE + TSEC/86400.
00156 38*      CALL CALNDR(CAL,4HMCALN,JDV,2HJD)
00157 39*      CALL TCONV(CAL(3),5HCLOCK,CAL(3),3HDAY)
00160 40*      CALL TCONV(TIME,5HCLOCK,ABS(TSEC),3HSEC)
00161 41*      IF(ILL.EQ.0.AND. MOD(M,2).EQ.0) WRITE(MM,10)
00164 42*      IF(ILL.EQ.1 .AND. MOD(M,3).EQ.0) WRITE(MM,10)
00167 43*      WRITE(MM,2) TIME,PLNM,CAL
00205 44*      IF(TSEC.LT.C) WRITE(MM,9)
00210 45*      IF(TSEC.GE.C) WRITE(MM,11)
00213 46*      WRITE(MM,3)
00215 47*      WRITE(MM,7)
00217 48*      WRITE(MM,4) R2,PSD,CC(2),CC(3),CONE,CLOCK,PHA,VT,U(3)
00232 49*      WRITE(MM,6)
00234 50*      WRITE(MM,5)(1,VS(1,1),VS(2,1),VS(3,1),EH(1),IN(1),I=J,K)
00247 51*      WRITE(MM,20)
00251 52*      M = M + 1
00252 53*      IF(TRACE.EQ.5HTRACE) PRINT 999
00255 54*      10 FORMAT(IH1)
00256 *DIAGNOSTIC* * IS AN IMPROPER PUNCTUATION MARK.
00256 55*      2 FORMAT(1H0,1X,12,*/,12,*/,12,*/,F5,2,21X,2A6,10X,15,1X,A3,13,
00256 56*      *2X,12,*/,12,*/,F5,2)
00257 *DIAGNOSTIC* * IS AN IMPROPER PUNCTUATION MARK.
00257 57*      9 FORMAT(IH,*,*)
00260 *DIAGNOSTIC* * IS AN IMPROPER PUNCTUATION MARK.
00260 58*      11 FORMAT(IH,*,*)
00261 *DIAGNOSTIC* * IS AN IMPROPER PUNCTUATION MARK.
00261 59*      3 FORMAT(1H0,12X*PLANET CENTER*,31X*INSTRUMENT AXIS*)
00262 *DIAGNOSTIC* A DIGIT IMPROPERLY FOLLOWS AN X OR H FIELD,OR A /OR X )
00262 *DIAGNOSTIC* * IS AN IMPROPER PUNCTUATION MARK.
00262 60*      7 FORMAT(1H0,2X*RANGE*,5X*ASD*,5X*CONE*,4X*CLOCK*,10X*CONE*,4
00262 61*      *,4X*PHASE*,5X*VSM*,4X*THETA*)
00263 62*      4 FORMAT(1H ,F8,0,2X,F6+2,2X,F7+2,2X,F7+2,7X,F7+2,2X,F7+2,2X,F7+2,
00263 63*      *2X,F6+2,2X,F7,2)
00264 *DIAGNOSTIC* * IS AN IMPROPER PUNCTUATION MARK.
00264 64*      6 FORMAT(1H0,11X,*RADIUS*,9X,*LATITUDE*,8X,*LONGITUDE*,8X,*EM ANGLE*
00264 65*      *,8X,*IN ANGLE*)
00265 66*      5 FORMAT(12,5(9XF7.2))
00266 67*      20 FORMAT(1H0/////)
00267 *DIAGNOSTIC* * IS AN IMPROPER PUNCTUATION MARK.
00267 68*      999 FORMAT(1H0,*FPRINT SUBROUTINE*)
00270 69*      RETURN
00271 70*      END

00101 1*      SUBROUTINE FRAME1(P,FOV1,FOV2)
00103 2*      DIMENSION P(3,9)
00104 3*      COMMON/FLAG/LL
00105 4*      COMMON/TRA/TRACE
00106 5*      DATA P1,F/3,1415926536,.017453293/
00111 6*      IF(TRACE.EQ.5HTRACE) PRINT 999
00114 7*      CALL VLOAD(P(1,5), 0., 0.,1.)
00115 8*      LL = 0
00116 9*      IF(FOV1**2+FOV2**2 .LT. .00001) LL=1
00120 10*     IF(ILL.EQ.1) GO TO 2
00122 11*     A1=TAN(FOV1*F)
00123 12*     A2=TAN(FOV2*F)
00124 13*     CALL VLOAD(P(1,1),-A1,-A2,1.)
00125 14*     CALL VLOAD(P(1,2), 0.,-A2,1.)
00126 15*     CALL VLOAD(P(1,3), A1,-A2,1.)
00127 16*     CALL VLOAD(P(1,4),-A1, 0.,1.)
00130 17*     CALL VLOAD(P(1,6), A1, 0.,1.)
00131 18*     CALL VLOAD(P(1,7),-A1, A2,1.)
00132 19*     CALL VLOAD(P(1,8), 0., A2,1.)
00133 20*     CALL VLOAD(P(1,9), A1, A2,1.)
00134 21*     DO 1 I=1,9
00137 22*     1 CALL VUNIT(P(1,I),P(1,1))
00141 23*     2 IF(TRACE.EQ.5HTRACE) PRINT 999
00144 24*     999 FORMAT(1H0,*FRAME SUBROUTINE*)
00145 25*     RETURN
00146 26*     END

```

```

00101 1* SUBROUTINE LOCATE(VQ,CONE,CLOCK,TWIST)
00103 2* DIMENSION VQ(3,9),C2(3)
00104 3* COMMON/VW/VQ(3),R2,ASD
00105 4* COMMON/CELEST/C(3),S(3),SN(3)
00106 5* COMMON/FAHE/C1(3),C3(3)
00107 6* COMMON/POINT/VQ(3,9),P(3,9)
00110 7* COMMON/PC/PC(3,9)
00111 8* COMMON/PCOORD/PV(3),VE(3),PH(3)
00112 9* COMMON/EXTRA/RPL,ROT
00113 10* COMMON/FLAG/LL,DUM(2),N1,HFL
00114 11* COMMON/TRA/TRACE
00115 12* DATA PI,F/3.1415926536,0.017453293/
00120 13* IF(TRACE.EQ.5HTRACE) PRINT 999
00123 14* CALL VLOAD(C3,1,CONE,CLOCK)
00124 15* CALL SPHERE(C3,C3,4HFROM,5HPOLAR,6HDEGREE)
00125 16* CALL VTRANS(C3,C3,4HFROM,C,S)
00126 17* CALL UCROSS(C2,S,C3)
00127 18* CALL VCROSS(C1,C2,C3)
00130 19* CALL VROTAT(C1,C1,C3,TWIST*F)
00131 20* IF(ILL.EQ.1) GO TO 2
00133 21* DO I 1=1,9
00136 22* 1 CALL EUREKA(VQ(I,1),VC(I,1),PC(I,1),P(I,1))
00140 23* GO TO 3
00141 24* 2 CALL EUREKA(VQ(I,5),VC(I,5),PC(I,5),P(I,5))
00142 25* 3 IF(TRACE.EQ.5HTRACE) PRINT 999
00145 *DIAGNOSTIC* * IS AN IMPROPER PUNCTUATION MARK.
00145 26* 999 FORMAT(*LOCATE SUBROUTINE*)
00146 27* RETURN
00147 28* END

```

```

00101 1* SUBROUTINE LOOKIDUM,CONE,CLOCK,LAT,LONG)
00103 2* REAL LAT,LONG
00104 3* DIMENSION R(3),UX(3),C3(3)
00105 4* COMMON/CELEST/C(3),S(3)
00106 5* COMMON/PCOORD/PV(3),VE(3),PH(3)
00107 6* COMMON/EXTRA/RPL,ROT
00110 7* COMMON/TRA/TRACE
00111 8* COMMON/VW/VQ(3),R2,ASD
00112 9* IF(TRACE.EQ.5HTRACE) PRINT 999
00115 10* CALL VSCALE(UX,VW,-1)
00116 11* CALL VLOAD(R,1,LAT,LONG)
00117 12* CALL SPHERE(R,R,4HFROM,6HLATLON,6HDEGREE)
00120 13* CALL VTRANS(R,R,4HFROM,PH,PV)
00121 14* IF(DOT(UX,R).LT.RPL/R2) GO TO 1
00123 15* CALL VCOMB(C3,VW,R2,R,RPL)
00124 16* CALL VTRANS(C3,C3,2HTO,C,S)
00125 17* CALL SPHERE(C3,C3,2HTO,5HPOLAR,6HDEGREE)
00126 18* CONE=C3(2)
00127 19* CLOCK=C3(3)
00130 20* IF(TRACE.EQ.5HTRACE) PRINT 999
00133 21* RETURN
00134 22* 1 PRINT 2,LAT,LONG
00140 *DIAGNOSTIC* COMMA IS MISSING BEFORE A, E, I, O, F, OR HOLLERITH FIELD.
00140 *DIAGNOSTIC* * IS AN IMPROPER PUNCTUATION MARK.
00140 *DIAGNOSTIC* N IS AN IMPROPER PUNCTUATION MARK.
00140 *DIAGNOSTIC* * IS AN IMPROPER PUNCTUATION MARK.
00140 23* 2 FORMAT(IH,*,LAT*,F5.0,*,*,LONG*,F5.0,*,*,NOT VISIBLE*)
00141 24* IF(TRACE.EQ.5HTRACE) PRINT 999
00144 25* RETURN
00145 *DIAGNOSTIC* * IS AN IMPROPER PUNCTUATION MARK.
00145 26* 999 FORMAT(IHD,*,LOOK SUBROUTINE*)
00146 27* END

```



MCR-71-181

APPENDIX C

SUPPORTING JPL MEMOS

.

JET PROPULSION LABORATORY

TECHNICAL MEMORANDUM

393-10

October 13, 1970

SUBJECT: ORBIT, A General Purpose Conic Orbit Program

Introduction

A general purpose conic orbit program called ORBIT has been written. It allows input of any central body with simplified input for the Sun and planets from the SUBROUTINE PLANET. It allows orbital elements to be input in over 100 different modes. Once the orbital elements are entered the subroutine can be called to give the position velocity or acceleration vectors in cartesian coordinates or to get classical orbital elements all as a function of time. This is accomplished through the use of multiple entry points and flags as explained below. ORBIT may be used by any program as a subroutine by putting the following control cards in the run stream:

```

      (a) COPY,P   PLANET*PLANET., TPF$.
      (a) COPY,P   VECTOR*VECTOR., TPF$.
  
```

The ORBIT program makes extensive use of the vector subroutines and requires the subroutines CTRANS, OBLATE, PLANET, and ANOMLY all of which are made available with the above statements.

Normal Usage

For ordinary use where units of kilometers, seconds, and degrees; and ecliptic coordinates are suitable; and the Sun or one of the 9 planets is the central body, then the following simple options will be useful.

Any symbol indicated as a vector by an arrow overhead (e.g.  $\vec{R}$ ,  $\vec{V}$ ) should be considered to have 3 components and to be associated with a dimension statement. (e.g. DIMENSION R(3), VV(3)) The notation  $\vec{R} = (X,Y,Z)$  is shorthand for  $R(1) = X$ ,  $R(2) = Y$ ,  $R(3) = Z$ . For vectors of more than 3 components dimensions will be explicit and no arrow used. Notation such as: DIMENSION X(7):  $X = (\vec{R}, \vec{V}, T)$  means  $X(1) = R(1)$ ,  $X(2) = R(2)$ ,  $X(3) = R(3)$ ,  $X(4) = V(1)$ ,  $X(5) = V(2)$ ,  $X(6) = V(3)$ , and  $X(7) = T$ .

Oct. 13, 1970

Option	Description
CALL CPLANN(IP)	IP is input planet number: 0 = Sun, 3 = Earth, etc. Causes planet IP to be the central body. This call must come before the ORBIN call.

Let DIMENSION X(6), R(3), V(3), A(3). ORBIN sets up the orbit of the spacecraft in the subroutine from initial conditions specified in X.

CALL ORBIN(X, 1)	X is input classical orbital elements (a, e, i, $\Omega$ , $\omega$ , M) at time = 0.
CALL ORBIN(X, 2)	X is input initial position and velocity ( $\hat{R}$ , $\hat{V}$ ) at time = 0. Sets up the orbit in the subroutine
CALL ORBIN(X, 3)	X is input hyperbolic parameters ( $h_p$ , $\theta$ , T, $V_\infty$ , $\beta$ , $\lambda$ ) $h_p$ = periapsis altitude $\theta$ = B-plane angle T = time elapsed from periapsis to time = 0 $V_\infty$ = incoming hyperbolic velocity at $\infty$ $\beta$ = ecliptic latitude of the incoming asymptote $\lambda$ = ecliptic longitude of the incoming asymptote Sets up hyperbolic orbit in subroutine.
CALL ORBPOS(R, T)	T is input time, $\hat{R}$ is output position vector of the orbiting body at that time.
CALL ORBVEL(V, T)	T is input time, $\hat{V}$ is output velocity vector of the orbiting body at time T
CALL ORBACC(A, T)	T is input time, $\hat{A}$ is output acceleration of orbiting body at that time.
CALL ORBELM(X, T)	T is input time, X is output classical orbital elements at that time. Heliocentric angles are referenced to the ecliptic; Planetocentric angles, to the planet equator. This call with time = 0 will give the same elements out that were put in with ORBIN(X,1),
CALL ORBTIM(T)	T is output time from periapsis to time = 0, which is time of initial conditions input by ORBIN. For initial conditions indicating the inbound portion of an orbit, T will be negative.

Table 1 Subroutine Orbit Input Options

Digit	6	5	4	3	2	1	Digit Value of Digit 1
Values of Digits 6 → 2	Effects of Digits 6 → 1 on Input Quantities						
0	Not Used	Not Used	Not Used	Not Used	Not Used	No Input	0
0	Not Used	Degrees	Mean Anomaly at time = 0	Longitude of Periapsis	Semi-major Axis	Input is based on classical orbital elements referred to planet equator and equinox*	1
1	Not Used	Radians	Time since Periapsis Passage	Argument of Periapsis	Period of Ellipse		1
0	Not Used	Not Used	Not Used	Not Used	Cartesian coordinates referred to base vectors**	Input is position and velocity	2
1	Not Used	Not Used	Not Used	Not Used	Spherical coordinates referred to planet		2
0	Incoming Asymptote	Periapsis Altitude	B-plane Aimpoint angle	Spherical Coordinates	$V_{\infty}$ referred to base vectors	Input is hyperbolic quantities	3
1	Outgoing Asymptote	Periapsis Radius	Orbit Inclination to Planet Equator $\hat{B} \cdot \hat{R}$ negative	Cartesian Coordinates	$V_{\infty}$ referred to Earth equator and equinox†		3
2	Not Used	Magnitude of B-vector	Orbit Inclination to Planet Equator $\hat{B} \cdot \hat{R}$ positive	Not Used	$V_{\infty}$ referred to planet equator and equinox		3

\* Except heliocentric orbit is referred to base vectors

\*\* Base vectors are usually ecliptic x, y, z.

† This option only valid if base vectors are ecliptic x, y, z.

Access:

The ANOMLY program is included in the file PLANET and may be accessed by putting the following card before the (a) XQT card:

(a) COPY,P PLANET\*PLANET.,TPF\$.

C A L N D RIntroduction:

It is often convenient to be able to use the calendar date for input or output purposes, but it necessary to use Julian date or modified Julian date for actual calculations. Where Julian date is used it is usually a double precision variable in order to have sufficient time resolution in fractions of a day. For input purposes it is convenient to be able to enter the calendar date as a single number of the form YYMMDD.FF. CALNDR is a subroutine to implement conversions between these forms.

Use:

The subroutine has only one entry whose calling sequence is:

```
CALL CALNDR(DOUT, IO, DIN, II)
```

DOUT is the output date, SIN is the input date.

IO describes the form of DOUT; and II, the form or DIN.

The following table gives the forms that DIN and II may take.

II	DIN
'JD'	DIN is double precision Julian date
'MODJD'	DIN is single precision modified Julian date
'CALcc'	DIN is single precision calendar date of the form YYMMDD.FF and cc is the century number to which the year is referenced (see examples)

The next table gives the forms that DOUT and IO may take.

<u>IO</u>	<u>DOUT</u>
'JD'	DOUT is double precision Julian date
'MODJD'	DOUT is single precision modified Julian date
'CAL'	DOUT is dimensioned DOUT(3) and DOUT(1) = year (integer) DOUT(2) = month number (integer) DOUT(3) = day number (real)
'ALPHA'	DOUT is dimensioned DOUT(3) and DOUT is an 18 character date suitable for printing on a 3A6 format.

Examples:

1. Problem: Find the Julian date and modified Julian date corresponding to August 13, 1976.  
 Solution: DOUBLE PRECISION JD  
 CALL CALNDR(JD, 'JD', 760813., 'CAL19')  
 CALL CALNDR(D, 'MODJD', JD, 'JD')  
 Results: JD = 2443003.5 DO  
 D = 9721.0 EO
  
2. Problem: Find the calendar date corresponding to modified Julian date 10000.5.  
 1st Solution: DIMENSION D(3)  
 EQUIVALENCE (IYR,D),(MO,D(2)),(DAY,D(3))  
 CALL CALNDR(D,'CAL',10000.1,'MODJD')  
 Results: IYR = 1977  
 MO = 5  
 DAY = 19.1  
 2nd Solution: CALL CALNDR(D,'ALPHA',10000.1,'MODJD')  
 Results: D(1) = '1977 M'  
 D(2) = 'AY 19.'  
 D(3) = '100000'

Limitations and Other Details:

Calendar Dates refer to the common Gregorian civil calendar, and therefore do not give the correct civil calendar date for times before 1582 to 1918 depending on when each country adopted the Gregorian calendar. This program is coupled to the trace feature of the vector subroutines. Improper input dates such as 11/45/66 or 38/16/72 will be interpreted as 12/15/66 and 2/16/75 respectively, making it simple to increment by months.

References:

1. P. H. Roberts, "A Set of Matrix Subroutines", IOM 393.1-37, September 10, 1970
2. Future TM describing ORBIT Program by P. H. Roberts.
3. P. H. Roberts, "An Improved Set of Vector Subroutines for the UNIVAC 1108", TM 393-2, August 3, 1970.

JET PROPULSION LABORATORY

TECHNICAL MEMORANDUM

393-5

September 24, 1970

SUBJECT: PLANET, An Analytic Ephemeris of the Planets for the UNIVAC 1108

PLANET is a program for computing the positions, velocities, accelerations, and rotation of the nine usual planets, the Sun, and three fictional planets. In addition to these outputs a common area called /PLCONS/ contains the gravitational constants, radii, names, rotation rates, pole vectors, prime meridian vectors (1900) vernal equinoxes, and oblateness terms for the Sun, usual planets and fictional planets. A standard means for setting up any of the three fictional planets allows convenient entry of the orbit and/or other physical properties of an asteroid or other body in a heliocentric orbit. Special debugging and error return features are also included.

PLANET may be made available to any 1108 user by inserting the cards

- Ⓐ COPY,P PLANET\*PLANET.,TPFS.
- Ⓐ COPY,P VECTOR\*VECTOR.,TPFS.

into the run stream before the @ XQT card. A listing may be obtained by inserting

- Ⓐ ELT,SL PLANET

in the run stream after the COPY,P statement.

For normal uses involving the Sun and nine planets, four calling sequences may be used without prior initialization. Let JD be a double precision Julian date (2415020.000 = 1900, Jan. 0.5 ET), let IP be an integer planet number (0 = Sun, 1 = Mercury, . . . etc.) and let  $\vec{X}$ ,  $\vec{V}$ ,  $\vec{A}$ , and  $\vec{PM}$  be single precision 3-vectors. The calling sequences and output description follows:

#### Calling Sequence

CALL PLPOS (X, JD, IP)	$\vec{X}$ is heliocentric ecliptic and equinox of date position in km.
CALL PLVEL (V, JD, IP)	$\vec{V}$ is heliocentric ecliptic velocity in km/sec
CALL PLACC(A, JD, IP)	$\vec{A}$ is heliocentric ecliptic acceleration in km/sec <sup>2</sup> .
CALL PGLOBE (PM, JD, IP)	PM is planetocentric ecliptic unit vector latitude = 0, longitude = 0 of planet.



Sept. 24, 1970

Rev. Nov. 13, 1970

Besides these time varying quantities, certain planet constants are available through the following common statement:

```
COMMON/PLCONS/SGM,PLGM(12), SR, PLR(12), SNAME(2), PLNAME(2, 12), SROT,
PLROT(12), SPV(3), PLPV(3, 12), SPM(3), PLPM(3, 12), SVE(3), PLVE(3, 12),
SOBL, PLOBL(12)
```

where

GM = gravitational constant  $\text{km}^3/\text{s}^2$   
R = radius km  
NAME = planet's name  
ROT = spherical rotation rate rev/day (day = 86400 sec)  
PV = pole vector referred to ecliptic  
PM = prime meridian vector referred to ecliptic  
VE = vernal equinox vector =  $\overrightarrow{PV} \times (\overrightarrow{\text{position}} \times \overrightarrow{\text{velocity}})$  referred to ecliptic  
OBL = planet oblateness

and where the prefix S = Sun and prefix PL = planet. For example, to use the rotation rate of the planet Mars include the above common statement in your program and refer to PLROT(4).

When it is desired to use a non-standard body as if it were a normal planet then it is necessary to enter the orbital elements and/or planet constants prior to using the calls or the common variables mentioned above. To set up the constants in the common area /PLCONS/ for a fictional planet, and to allow subsequent calls to PGLOBE, PLPOS, PLVEL, and PLACC, for the same, the following calling sequence is convenient:

CALL PLNPUT (X, IP, 0) where IP is the desired number for the new planet (10, 11, or 12 are allowed) and X has dimension X(13) and the values as follows:

X(1) = semi-major axis of orbit (A.U.)  
X(2) = eccentricity of orbit  
X(3) = inclination of orbit to ecliptic (degrees)  
X(4) = longitude of node (degrees)  
X(5) = longitude of perihelion (degrees)  
X(6) = mean anomaly at time,  $T_0$   
X(7) = time,  $T_0$ , to which mean anomaly refers  
X(8) = first six letters of planet's name  
X(9) = second six letters of planet's name  
X(10) = radius of planet (km)

- X(11) = gravity of planet ( $\text{km}^3/\text{s}^2$ )  
 X(12) = geo-equatorial declination of planet's pole (degrees)  
 X(13) = geo-equatorial right ascension of planet's pole (degrees)  
 X(14) = sidereal rotation rate (rev/solar day) = (rev/84600 sec)

If the usual orbital elements as described above are not accurate enough, time polynomials may be inserted as orbital elements. This is done by using the following three calls in any order where X has dimension X(6):

CALL PLNPUT(X, IP, 1)

where X(1) = a in A.U.

X(2) = e

X(3) = i in degrees

X(4) =  $\Omega$  in degrees

X(5) =  $\tilde{\omega}$  in degrees

X(6) = M in degrees

as of JD = 2415020.0

CALL PLNPUT(X, IP, 2)

where X(1) is not used

X(2) =  $\frac{de}{dt}$  in centuries<sup>-1</sup>

X(3) =  $\frac{di}{dt}$  in degrees/century

X(4) =  $\frac{d\Omega}{dt}$  in degrees/century

X(5) =  $\frac{d\tilde{\omega}}{dt}$  in degrees/century

X(6) =  $\frac{dM}{dt}$  in degrees/day

CALL PLNPUT(X, IP, 3)

where X(1) is not used

X(2) =  $d^2e/dt^2$  in centuries<sup>-2</sup>

X(3) =  $d^2i/dt^2$  in degrees/century<sup>2</sup>

X(4) =  $d^2\Omega/dt^2$  in degrees/century<sup>2</sup>

X(5) =  $d^2\tilde{\omega}/dt^2$  in degrees/century<sup>2</sup>

X(6) =  $d^2M/dt^2$  in degrees/(10000 days)<sup>2</sup>

Sept. 24, 1970

The call sequence CALL PLANET ('TRACE') is a useful debugging aid, especially for problems which can occur with fictional planets or whenever one wishes to monitor the operations of this subroutine. Wherever this call is used any of the subsequent calls to PLPOS, PLVEL, PLACC, PGLOBE or PLNPUT will cause them to print out their names and other important calculations. CALL PLANET('NOTRAC') stops further tracing.

Finally, the next call sequence causes error conditions to transfer to a chosen location in the main program rather than aborting the job. The sequence is CALL PLNERR(\$nn) where nn is the statement number in the main program to which error returns are made. The use of this call in a subroutine will cause the job to abort when the RETURN statement of the subroutine is executed. The walk back will be from a RETURN 0 in the PLANET subroutine. The coding for this error return involves some tricks possible with the 1108 system and should not be tampered with unless a systems engineer or other cognizant person is consulted.

This subroutine is on a catalogued file which may be accessed by the following card put before the (a) XQT card:

(a) COPY,P PLANET\*PLANET., TPF\$.

This subroutine requires the vector subroutines which may be accessed with the card:

(a) COPY,P VECTOR\*VECTOR., TPF\$.

and also the subroutines ANOMLY, and CALNDR which are also on the file PLANET\*PLANET