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UTILIZATION REPORT ON
STATISTICAL TRAJECTORY ESTIMATION PROGRAMS

By William E. Wagner and Arno C. Serold

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Prepared under Contract No. NAS1-8500 by
MARTIN MARIETTA CORPORATION
Denver, Colorado

for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

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FOREWORD

This report describing the utilization of the Statistical Trajectory Estimation Programs is provided in accordance with Part IV.A.4 of NASA Contract NAS1-8500. An additional report, provided in accordance with this same contract, is presented in NASA CR-1482 to describe the formulation of the Statistical Trajectory Estimation Program.

This work was conducted under the direction of Robert J. Mayhue, Technical Monitor; Sherwood Hoffman, Alternate Monitor (both of the Applied Materials and Physics Division); and George B. Boyles, Computer Analyst, Analysis and Computation Division, Langley Research Center, National Aeronautics and Space Administration.

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Martin Marietta Corporation

SUMMARY

This volume documents the computer program logic, subroutine arrangement, input and output formats, and other information concerning the Statistical Trajectory Estimation Programs (STEP) of interest to the user and programmer. These programs were originally developed and used on the U.S. Air Force Precision Recovery Including Maneuvering Entry (PRIME) program to perform the post-flight trajectory reconstruction and analysis of the SV-5D maneuverable lifting reentry vehicle. Subsequently, the programs have been considerably improved under NASA Contract NAS1-8500.

STEP uses the recursive Kalman minimum variance filtering algorithms to fit the equations of motion to trajectory measurement data. The programs are formulated to process position radar tracking and airborne gyro and accelerometer measurements. The equations of motion account for three dimensional trajectories in the vicinity of an oblate rotating planet. Vehicle maneuvers in pitch, roll, and yaw within the atmosphere are acceptable. STEP1 is restricted to nonthrusting vehicles; STEP2 is applicable to any vehicle recording accelerations and inertial angular rates and having at least partial radar coverage.

In addition to postflight reconstruction, the programs are useful for solving preflight trajectory simulation and error analysis problems.

I. INTRODUCTION

The Statistical Trajectory Estimation Programs (STEP1 and STEP2) were originally developed, validated, and successfully used to reconstruct the trajectories of the SV-5D maneuverable lifting reentry vehicles on the U.S. Air Force PRIME program. The original formulation is presented in reference 1.

Subsequently, under NASA Contract NAS1-8500 with Langley Research Center, the original formulation for STEP was modified, and the programs were rebuilt. The modifications consist of changing the translational equations of motion to inertial axes and using quaternions to describe the vehicle attitude. Several additional options to improve utility were also included. The improved formulation is presented in Volume I of this report.

From their first conception, the following six rules have served as guidelines for the development of STEP:

- 1) Keep all user/program interfaces simple and logical;
- 2) Use FORTRAN IV or FORTRAN 2.0 coding throughout to facilitate modifications and conversion to various computers;
- 3) Keep STEP1 and STEP2 as identical as possible;
- 4) Minimize logic that limits program applications to specific vehicles;
- 5) Use an executive program structure wherein the main program controls logic flow to and from numerous subordinate subroutines;
- 6) Be continually concerned with minimizing program execution time and computer core requirements.

As a consequence of these guidelines, the original programs were operated on the IBM 7094/2, GE-635, IBM-360/65, and CDC-6400 computers. The majority of subroutines in the two programs are identical, program input and output are nearly alike, and both programs can interface with the same data tapes.

In the following sections; information pertinent to the user and programmer are presented. This includes descriptions of the input and output, checkout procedures, program logic, FORTRAN symbols, flow diagrams, and listings. Reference will be made frequently to the variables, equations, modes of operation, and computational procedures described in Volume I of this report. It is recommended that the reader be familiar with this material before proceeding into this volume--the Utilization Report.

II. PROGRAM INPUT AND OUTPUT

In Volume I of this report, the mathematical techniques and procedures used in STEP are described. Briefly, the concept consists of fitting the equations of motion to trajectory data in a minimum variance sense. The equations of motion in STEP1 require the inertial angular rate data, P_M , Q_M , and R_M ; and, in STEP2 the inertial angular rate data and accelerometer data, a_{XM} , a_{YM} , and a_{ZM} . These data are satisfied exactly by the equations of motion, so obviously they must be excluded from the data to which the equations of motion are fit. As a result of the two different ways in which data are used, STEP interfaces with two magnetic tapes. The first tape, the PQR tape, contains the inertial angular rate and accelerometer data required by the equations of motion in STEP2. The second tape, the FIT tape, contains the radar tracking and accelerometer data as well as any additional data to which the equations of motion in STEP1 are to be fit. Note that the PQR tape can be used in STEP1, and the FIT tape in STEP2 if the accelerations are neglected.

STEP also requires a priori estimates, covariances, and correlations of the state variables and model parameters; program controls and numerical integration information; geophysical and gravitational constants; vehicle physical and aerodynamic data; atmospheric data; etc. These data are input by cards. Figure 1 is a schematic of the input and output information for STEP1 and STEP2. The figure shows the data required by the equations of motion entering from the left, the data to which the equations of motion are fit in a minimum variance sense entering from the top, and the output exiting toward the right. Also shown are those data obtained from cards and those from tape. In the following subsections, these inputs and outputs are described.

A. Card Input

The program card inputs have been divided into 20 logical categories. The quantities input in each of these categories are discussed below. The categories should be input in numerical order. They contain data consisting of both fixed and floating point numbers. The fixed point numbers, designated by an asterisk in the following description, must be rightmost justified within the column field specified. Floating point numbers must be rightmost justified only if the E-mode is used, e.g., .2574532E+3.

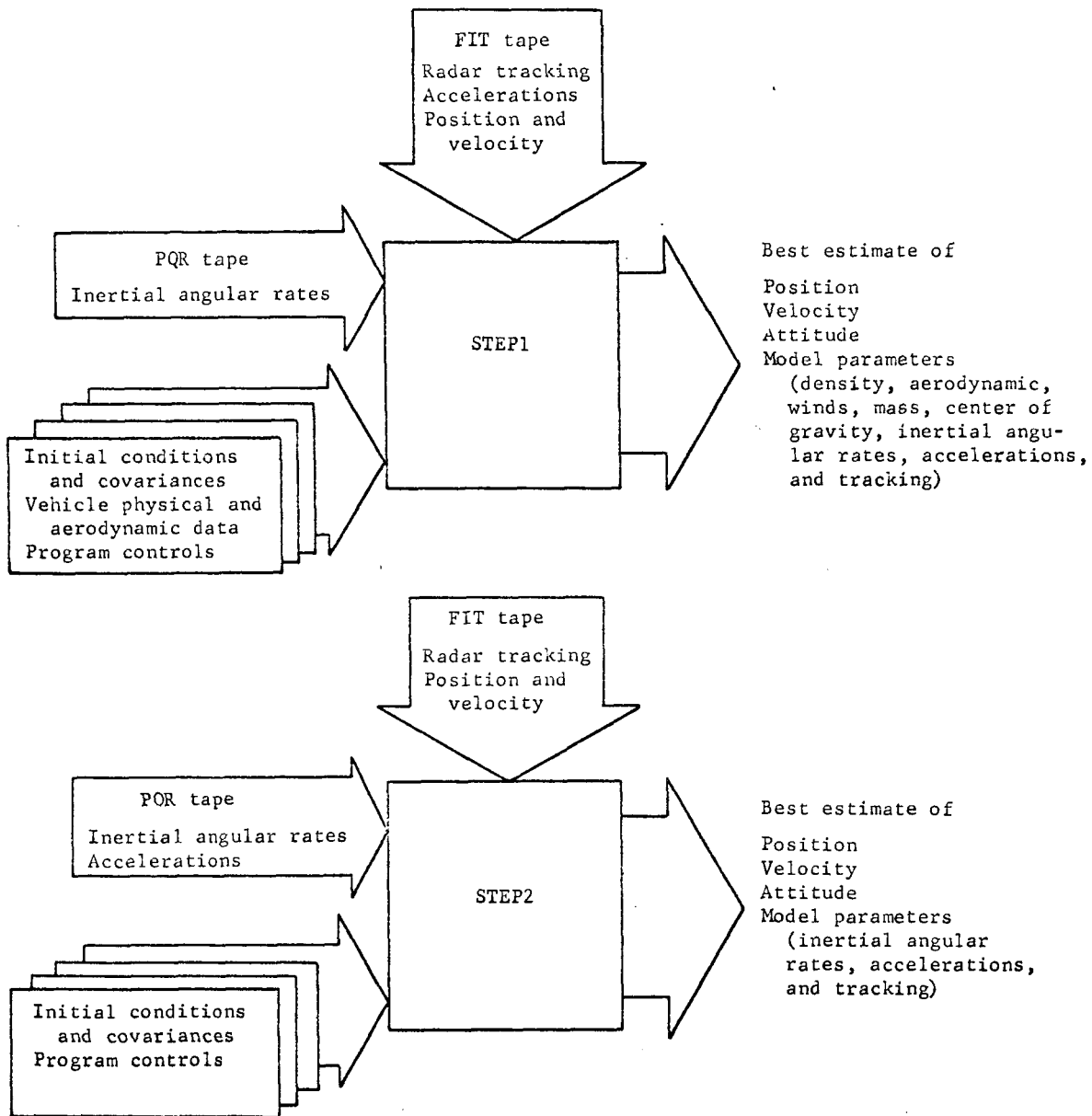


Figure 1.- Schematic of STEP Inputs and Outputs

When floating point numbers are input in the F-mode, e.g., 257.4532, they can lie anywhere within the column field specified. Linear interpolation and extrapolation are used on all tabular input data. Therefore, at least two points must be specified for each table. Curves to be maintained constant at zero need not be input.

1. Input categories.- Those input categories common only to STEP1 will be noted in the description that follows.

Category 1 comment card (STEP1 and STEP2):

<u>Variables</u>	<u>Columns</u>	<u>Description</u>
1* [¶]	2	Identifies category 1 input
"comment"	3-72	Comment containing alphabetic and numerical characters to describe the problem, date, etc.

As many comment cards as desired may be input, each however, requiring a 1 in column 2 (a 0 or blank will also work). The comment cards will be printed on the tab printout.

Category 2 program controls (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
2*	2	Identifies category 2 input
NPC(1)*	6	= 0 filtering, = 1 deterministic, = 2 error analysis
NPC(2)*	10	= 0 metric units, = 1 English units
NPC(3)*	14	= 0, 1, or 2 for input/output in internal variables or types 1 or 2 variables, respectively
NPC(4)*	18	= 0 updated reference, = 1 nonupdated reference
NPC(5)*	22	= 0 print fitting data schedule, = 1 do not print
NPC(6)*	26	= 0 do not print covariance and correlation matrices, = 1 print covariance and correlation matrices during smoothing on last iteration = 2 print covariance and correlation matrices during filtering and smoothing on last iteration
NPC(7)*	30	Number of iterations
NPC(8)*	34	= 0 smooth state only, no residual or loss function calculations = 1 smooth state only, calculate residuals and loss function = 2 smooth state and covariances, no residuals or loss function calculations = 3 smooth state and covariances, calculate residuals and loss function = 4 do not smooth
NPC(9)*	38	= 0 vector process, = 1 scalar process
NPC(10)*	42	= 0 do not write STATE tape during smoothing, = 1 write tape

[¶]A variable followed by an asterisk indicates a fixed point integer which must be rightmost justified.

These program controls pertain to entire program operation. For more complete definitions, see Subsection A.2. Program controls common to a specific input category are input with that category.

Category 3 state variables and model parameters (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
3*	2	Identifies category 3 input
IPC ₁ *	4	Variable in X=1, W=2, U=3, V=4, Const=5
IDN*	5-8	Variable identification number, see Subsection A.4, page 21
VALUE	9-20	Mean values of state variable or model parameter, see Subsection A.4 for units
SIG	21-32	Standard deviation of state or model parameter if IPC ₁ = 1-4, see Subsection A.4 for units

One category 3 card is required for each state variable and model parameter desired in the problem. Should no card be input for a specific model parameter, it assumes a preset value of 1 or 0 to bypass the error model. For example, in the accelerometer error model, equation (159), $C_{61} = C_{65} = C_{69} = 1$ all other C_s are zero. For uncertain variables, the standard deviations are squared and constitute the variance of the diagonal covariance matrix. Should off-diagonal elements be required, they can be input in category 10. The maximum number of components in X is 10; in W is 20, in U is 5; in V is 5.

Category 4 numerical integration (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
4*	2	Identifies category 4 input
T0	9-20	Initial problem time, sec
DET	21-32	Time interval between block printouts, sec
DCOMP	33-44	Fixed computing interval, sec
TFINAL	45-56	Final problem time, sec

Category 5 geophysical and gravitational (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
5*	2	Identifies category 5 input
1*	4	Identifies remaining variables on card as GO, XMU, and XJ2
GO	9-20	Acceleration of gravity at sea level for use in STEP1 atmosphere equations, m/sec ² , ft/sec ²
XMU	21-32	Coefficient of first gravitational harmonic, m ³ /sec ² , ft ³ /sec ²
XJ2	33-44	Coefficient of second gravitational harmonic
and/or		
5*	2	Identifies category 5 input
2*	4	Identifies remaining variables on card as R _P , R _E , and OMEGA
RPO	9-20	Polar radius of planet, m, ft
REO	21-32	Equatorial radius of planet, m, ft
OMEGA	33-44	Planet rotation rate, rad/sec

Category 5 cards need be input only if a change is desired from the built-in data. The values of the category 5 data that are built-in are from reference 2:

$$GO = g_0 = 9.80665 \text{ m/sec}^2 = 32.174048 \text{ ft/sec}^2$$

$$XMU = \mu = 3.985992 \times 10^{14} \text{ m}^3/\text{sec}^2 = 1.407639 \times 10^{16} \text{ ft}^3/\text{sec}^2$$

$$XJ2 = J_2 = 1082.645 \times 10^{-6}$$

$$RPO = R_P = 6\,356\,173 \text{ m} = 20\,853\,599 \text{ ft}$$

$$REO = R_E = 6\,378\,163 \text{ m} = 20\,925\,731 \text{ ft}$$

$$OMEGA = \Omega_P = 7.292116 \times 10^{-5} \text{ rad/sec}$$

Category 6 center-of-gravity/IMU distances (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
6*	2	Identifies category 6 input
IPC ₂ *	4	Identifies table to follow = 1 x _p (t), = 2 y _p (t), = 3 z _p (t)
NPTS*	5-8	Number of points on table
[Read in x _p (t), y _p (t), or z _p (t) (m, ft), depending on IPC ₂ , using table input format 1 in Subsection A.3; NPTS must be no larger than 20]		

A separate category 6 card precedes each of the tables. Zero tables are omitted.

Category 7 fitting data controls (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
7*	2	Identifies category 7 input
MTYP*	4	Identifies type of data = 1, 2, 3, 4, 5 tracking stations = 6 airborne radar, = 7 position, = 8 velocity, = 9 accelerometer
TI	5-14	Initial time to process MTYP data, sec
TF	15-24	Final time to process MTYP data, sec
DT	25-34	Minimum time span between MTYP data points, sec
MR(1,MTYP)*	35-36	= 0 do not process component 1, = 1 process component 1
MR(2,MTYP)*	37-38	= 0 do not process component 2, = 1 process component 2
MR(3,MTYP)*	39-40	= 0 do not process component 3, = 1 process component 3
SIG(1,MTYP)	41-50	Incremental standard deviation on component 1, m, ft, rad
SIG(2,MTYP)	51-60	Incremental standard deviation on component 2, m, ft, rad
SIG(3,MTYP)	61-70	Incremental standard deviation on component 3, m, ft, rad

Input one category 7 card for each type (MTYP) of data to be processed. Category 7 cards are used to control the frequency and time span of data on the FIT tape. Specified components of the data triples can be edited out (even though on the FIT tape) by specifying its corresponding MR input equal to 0. The incremental standard deviations are added to the standard deviations on the FIT tape to yield the total standard deviations used in the filtering equations. All angular standard deviations (e.g., A_M and E_M) are in radians.

In error analysis problems, the category 7 cards provide all the fitting data information necessary, i.e., time span, frequency, and standard deviation. Therefore, no FIT tape is used.

Category 8 FIT tape (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
8*	2	Identifies category 8 input
IPC ₃ *	4	= 0 no print of FIT tape, = 1 print FIT tape
IPC ₄ *	8	= 1 input FIT data from cards, = 0 do not enter FIT data from cards

(If IPC₄ = 1, read in FIT data from cards using table input format 2 in Subsection A.3)

The category 8 cards permit printing of the FIT tape and/or input of the FIT data from cards. When card input is used, a tape is written from the card inputs and later used in problem execution. If a prepared FIT tape is to be used and no printout of the tape is desired, omit category 8 input.

Category 9 POR tape (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
9*	2	Identifies category 9 input
IPC ₅ *	4	= 0 no print of PQR tape, = 1 print PQR tape
IPC ₆ *	8	= 1 input PQR data from cards, = 0 do not enter PQR data from cards

(If IPC₆ = 1, read PQR data from cards using table format 3 in Subsection A.3)

The category 9 cards permit printing of the PQR tape and/or input of the PQR data from cards. When card input is used, a tape is written from the card inputs and later used in problem execution. If a prepared PQR tape is desired, omit category 9 input.

Category 10 covariance and correlation matrices (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
10*	1-2	Identifies category 10 input
IPC ₇ *	4	Identifies matrix or matrix elements to follow = 1 P, =2 CUZ, =3 CVZ = 4 P(i,j), = 5 CUZ(i,j) = 6 CVZ(i,j)
NPTS*	8	Number of single point cards to follow if IPC ₇ > 3
<p>[Read in P, CUZ, or CVZ (m, ft, rad) if IPC₇ = 1, 2, or 3, respectively, by means of table format 4 in Subsection A.3]</p> <p>or input NPTS cards each containing a single point formatted as follows</p>		
i*	5-8	} if IPC ₇ = 4
j*	9-12	
P(i,j)	13-24	
or		
i*	5-8	} if IPC ₇ = 5
j*	9-12	
CUZ(i,j)	13-24	
or		
i*	5-8	} if IPC ₇ = 6
j*	9-12	
CVZ(i,j)	13-24	

The category 10 data must be input after all category 3 cards have been input. This is necessary to allow the program to determine the number of components in the expanded state vector Z, model parameters U, and measurement parameters V. The size of P, CUZ, and CVZ require that these vector sizes be known. Care should be exercised in assuring that the matrices input in category 10 are compatible both in size and the order of variables input in category 3. The category 10 input can be omitted if the diagonal matrix P input in category 3 and null correlation matrices CUZ and CVZ are acceptable.

Category 11 aerodynamic coefficients (STEP1 only):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
11*	1-2	Identifies category 11 input
IPC ₈ *	4	Aerodynamic input option indicator = -1 C _D , C _Y , C _L ; = 0 C _A , C _Y , C _N ; = 1 C _A , C _{Y_η} , C _{N_η}
SREF	9-21	Reference area for aerodynamic coefficients
XLREF	22-33	Reference length in Reynolds number

(Input all three tables of aerodynamic coefficients by means of table input format 5 in Subsection A.3)

Category 12 mass (STEP1 only):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
12*	1-2	Identifies category 12 input
NPTS*	8	Number of points on table, the mass table to follow
TØNE	9-20	Time t ₁ to commence mass error model correction
TTWO	21-32	Time t ₂ at which mass error model correction is stopped

[Read in m(t) (kg, slugs) by means of table input format 1 in Subsection A.3]

Category 13 atmospheric winds (STEP1 only):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
13*	1-2	Identifies category 13 input
IPC ₁₀ *	4	Identifies wind profile to follow = 0 u _{WM} (h _o), = 1 v _{WM} (h _o)
NPTS*	8	Number of points on table

[Read in u_{WM}(h) or v_{WM}(h) (mps or fps), depending on IPC₁₀, by means of table input format 1 of Subsection A.3]

Category 14 atmosphere (STEPl only):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
14	1-2	Identifies category 14 input
IPC ₁₁ *	4	Identifies atmosphere option = 0 1962 U.S. standard, = 1 1959 ARDC, = 2 arbitrary atmosphere to be input as function of geopotential alti- tude, = 3 arbitrary atmosphere to be input as function of geometric altitude
If $IPC_{11} \geq 2$ input the following		
NPTS*	3-4	Number of base points on attitude profile to be input
APO	5-15	Sea level pressure, nt/m ² or lb _f /ft ²
AMO	16-26	Mean molecular weight of atmos- phere constituents
AR	27-37	Gas constant, J/(°K) (kg-mol) or ft/lb _f (°R) (slug-mol)
AGAM	38-48	Specific heat ratio of atmos- phere constituents
ABET	49-59	} Sutherlands constants β and S used to calculate atmosphere viscosity, see units on data below
AS	60-70	
[Input HB(i) (m, ft) and TMB(i) (°K, °R), i=1, NPTS by means of table input format 6 in Subsection A.3]		

The data entered in category 14 input (if $IPC_{11} \geq 2$) must be dimensionally compatible with that specified in other categories. The values of AMO, APO, AR, AGAM, ABET, and AS built-in the program for use in the 1959 ARDC and 1962 U.S. Standard atmospheres are the following:

$$APO = 1.013250 \times 10^5 \text{ nt/m}^2 = 2116.2166 \text{ lb}_f/\text{ft}^2$$

$$AMO = 28.9644$$

$$AR = 8.31432 \times 10^3 \text{ J}/(\text{°K}) (\text{kg-mol}) = 49.7192 \times 10^3 \text{ ft-lb}_f/\text{(\text{°R})} (\text{slug-mol})$$

$$AGAM = 1.40$$

$$ABET = 1.458 \times 10^{-6} \text{ kg/sec m} (\text{°K})^{\frac{1}{2}} = 2.269 \times 10^{-8} \text{ slugs/ft-sec} (\text{°R})^{\frac{1}{2}}$$

$$AS = 110.4 \text{ °K} = 198.72 \text{ °R}$$

Category 20 end card:

<u>Variable</u>	<u>Column</u>	<u>Description</u>
20*	1-2	Identifies category 20 card

The category 20 card must always be input last.

2. Program control definitions.- Definitions of the program controls used in the previous section follow:

- NPC(1) = 0 Filtering mode of operation;
 1 Deterministic mode of operation;
 2 Error analysis mode of operation.
- NPC(2) = 0 Input and output in metric units (kg, m, sec);
 1 Input and output in English units (slug, ft, sec).
- NPC(3) Input and output the following state variables, their standard deviations, covariance and correlation matrices;
 = 0 $u, v, w, h_o, \varphi_D, \theta, e_o, e_1, e_2, e_3$;
 1 $V_A, \gamma_A, \lambda_A, h_o, \varphi_D, \theta, \bar{\psi}, \bar{\theta}, \bar{\varphi}$;
 2 $V_A, \gamma_A, \lambda_A, h_o, \varphi_D, \theta, \sigma, \beta, \alpha$.
- NPC(4) = 0 Update reference after each measurement processed;
 1 Do not update reference until final time is met.
- NPC(5) = 0 Print schedule of processed fitting data;
 1 Do not print schedule of processed fitting data.

- NPC(6) = 0 Do not print covariance and correlation matrices;
- 1 Print covariance and correlation matrices P, CUZ, and CVZ after each block printout during smoothing on last iteration;
 - 2 Print covariance and correlation matrices P, CUZ, and CVZ after each block printout during filtering and smoothing on last iteration.
- NPC(7) = Number of filtering and smoothing iterations.
- NPC(8) = 0 Smooth state only, no residuals nor loss function;
- 1 Smooth state only, calculate residuals and loss function;
 - 2 Smooth state, covariance, and correlation matrices, no residuals nor loss function calculations;
 - 3 Smooth state, covariance, and correlation matrices, calculate residuals, and loss function;
 - 4 Do not smooth.
- [Before the last iteration, only the state is smoothed if NPC(8) = 2 or 3]
- NPC(9) = 0 Process data as vectors where possible;
- 1 Process data as scalars at all times.
- NPC(10) = 0 Do not write STATE tape;
- 1 Write STATE tape on backward smoothing of last iteration.
- IPC₁ = 1 Variable is a component of the state vector, X;
- 2 Variable is a model parameter to be estimated in the expanded state vector, Z;
 - 3 Variable is an uncertain model parameter not to be estimated, U;
 - 4 Variable is an uncertain measurement parameter not to be estimated, V;
 - 5 Variable is a model parameter known with absolute certainty, C.
- IPC₂ = 1 Indicates the $x_p(t)$ table will follow category 6 card;
- 2 Indicates the $y_p(t)$ table will follow category 6 card;

- 3 Indicates the $z_p(t)$ table will follow category 6 card.
- IPC₃(IPC₅) = 0 Do not print out the data on the FIT (PQR) tape;
 1 Print out the data on the FIT (PQR) tape in tabular form before commencing the problem execution.
- IPC₄(IPC₆) = 0 Write the FIT (PQR) tape from input cards;
 1 The FIT (PQR) tape has already been prepared and need not be written from cards.
- IPC₇ = 1 The covariance matrix P follows the category 10 card;
 2 The covariance matrix CUZ follows the category 10 card;
 3 The covariance matrix CVZ follows the category 10 card;
 4 Single points P(i,j) follows the category 10 card;
 5 Single points CUZ(i,j) follows the category 10 card;
 6 Single points CVZ(i,j) follows the category 10 card.
- IPC₈ = -1 Aerodynamic coefficient inputs are $C_D(\alpha, \beta, M)$, $C_Y(\alpha, \beta, M)$ and $C_L(\alpha, \beta, M)$;
 0 Aerodynamic coefficient inputs are $C_A(\alpha, \beta, M)$, $C_Y(\alpha, \beta, M)$ and $C_N(\alpha, \beta, M)$;
 1 Aerodynamic coefficient inputs are $C_A(\xi, \eta, M)$, $C_Y(\xi, \eta, M)$ and $C_N(\xi, \eta, M)$.
- IPC₁₀ = 0 Indicates the $u_W(h_o)$ table follows category 13 card;
 1 Indicates the $v_W(h_o)$ table follows category 13 card.
- IPC₁₁ = 0 Use a 1962 U.S. Standard atmosphere;
 1 Use a 1959 ARDC atmosphere;
 2 Input an arbitrary atmosphere as a function of geopotential altitude;
 3 Input an arbitrary atmosphere as a function of geometric altitude.

- MTYP = 1 Tracking station 1 with components 1, 2, and 3 being R, A, and E, respectively;
- 2 Tracking station 2 with components 1, 2, and 3 being R, A, and E, respectively;
- 3 Tracking station 3 with components 1, 2, and 3 being R, A, and E, respectively;
- 4 Tracking station 4 with components 1, 2, and 3 being R, A, and E, respectively;
- 5 Tracking station 5 with components 1, 2, and 3 being R, A, and E, respectively;
- 6 Airborne radar with component 1 being R_R (components 2 and 3 are currently unused);
- 7 Velocity of vehicle with components 1, 2, and 3 being u, v, and w, respectively;
- 8 Position of vehicle with components 1, 2, and 3 being h, ϕ , and θ , respectively;
- 9 Accelerometer with components 1, 2, and 3 being a_{XM} , a_{YM} , and a_{ZM} , respectively.

3. Table input formats.- The formats described below are used to input tables in STEP.

a. Format 1: For a table, $X(t_i)$, having NPTS discrete values of the independent variable, t_i , and the dependent variable, $X(t_i)$, the following format is used.

Col Card	1-12	13-24	25-36	37-48	49-60	61-72
1	t_1	$X(t_1)$	t_2	$X(t_2)$	t_3	$X(t_3)$
2	t_4	$X(t_4)$
.
.
.	t_{NPTS-1}	$X(t_{NPTS-1})$	t_{NPTS}	$X(t_{NPTS})$.	.

The number of points on the table NPTS is entered on the category card preceding the table.

b. Format 2: This format corresponds to the data on the FIT tape. The data can be input on cards in category 8 using the following format.

Card \ Col	1-2	3-4	5-14	15-24	25-34	35-44	45-54	55-64	65-74
1	K*								
2	MTP(1)*	TYM(1)	DAT(1,1)	DAT(2,1)	DAT(3,1)	SIG(1,1)	SIG(2,1)	SIG(3,1)	
3	MTP(2)*	TYM(2)	DAT(1,2)	DAT(2,2)	DAT(3,2)	SIG(1,2)	SIG(2,2)	SIG(3,2)	
.									
.									
.									
K+1	MTP(K)*	TYM(K)	DAT(1,K)	DAT(2,K)	DAT(3,K)	SIG(1,K)	SIG(2,K)	SIG(3,K)	
	(The last record of input must contain zeros)								

Each record of the FIT tape corresponds to the K points described above. The number of points per record, K, must never exceed 20. As many records (with $K \leq 20$) as desired may be input. The last record must always consist of a single card having $K = 0$.

c. Format 3: This format corresponds to the data on the PQR tape. The data can be input on cards in category 9 using the following format.

Card \ Col	1-2	3-12	13-22	23-32	33-42	43-52	53-62	63-72
1	K*							
2		TT(1)	TP(1)	TQ(1)	TR(1)	AX(1)	AY(1)	AZ(1)
.	
.	
.	
K+1		TT(K)	TP(K)	TQ(K)	TR(K)	AX(K)	AY(K)	AZ(K)
	(The last record of input must contain zeros)							

Each record on the PQR tape corresponds to the K points described above. The number of points per record, K , must never exceed 20. As many records (with $K \leq 20$) as desired may be input. The last record must always consist of a single card having $K = 0$.

d. Format 4: This format corresponds to the covariance and correlation matrices input in category 10. These matrices are input by rows using the following format.

Card \ Col	1-12	13-24	25-36	37-48	49-60	61-72
1	P(1,1)	P(1,2)	P(1,3)	P(1,4)	P(1,5)	P(1,6)
.	P(1,7)	.	.	P(1,m)	P(2,1)	P(2,2)
.	.	.	.			
.	.	.	.			
.	.	.	P(m,m)			
1	CUZ(1,1)	CUX(1,2)	CUZ(1,3)	...	CUZ(1,q)	CUZ(2,1)
.	.	.	.			
.	.	.	.			
.	.	.	.			
.	.	.	CUZ(m,q)			
1	CVZ(1,1)	CVZ(1,2)	CVZ(1,3)	...	CVZ(1,r)	CVZ(2,1)
.	.	.	.			
.	.	.	.			
.	.	.	.			
.	.	.	CVZ(m,r)			

The number of components of the expanded state vector, m , uncertain model parameters, q , and measurement parameters, r , are determined by counting the category 3 cards as they are input.

e. Format 5: This format is used to input the tables of aerodynamic coefficients in category 11. Each table commences with the following control card

Col Card	1-4	5-8	9-12	13-16	17-20
1	NT*	NV*	N ₁ *	N ₂ *	N ₃ *

where

NT = Table identification number = 1 for C_D or C_A ,
 = 2 for C_Y or $C_{Y\eta}$,
 = 3 for C_L , C_N or $C_{N\eta}$;

NV = Number of independent variables for the table,
 $0 \leq NV \leq 3$;

N₁ = Number of points in the first independent variable,
 α or η ;

N₂ = Number of points in the second independent variables,
 β or ξ ;

N₃ = Number of point in the third independent variable,
 M.

The tabular entries follow. The first three cards list the N₁, α , or η values, the N₂, β , or ξ values and the N₃ M values. This is followed by the aerodynamic coefficients, specified by NT, which will be denoted by C below.

Card \ Col	1-6	7-12	13-18	23-24	25-30	31-36	37-42	43-48	49-54	55-60	61-66	67-72
1	α_1	α_2	α_3	α_4	α_5	.	.	.	α_{N1}			
2	β_1	β_2	.	.	.	β_{N2}						
3	M_1	M_2	M_3	M_4	.	.	.	M_{N3}				
4	$C(\alpha_1, \beta_1, M_1)$	$C(\alpha_2, \beta_1, M_1)$	$C(\alpha_3, \beta_1, M_1)$.	.	.	$C(\alpha_{N1}, \beta_1, M_1)$	$C(\alpha_1, \beta_2, M_1)$	$C(\alpha_2, \beta_2, M_1)$.	.	.
.	.	.	$C(\alpha_{N1}, \beta_2, M_1)$	$C(\alpha_1, \beta_1, M_2)$
.
.	$C(\alpha_{N1}, \beta_{N2}, M_{N3})$

For $NT = 3$, replace α and β by η and ξ in the above table. The trivariate table is size limited to $N_1 \times N_2 \times N_3 \leq 512$, which amounts to eight values of α , eight values of β , and eight values of M . By specifying N_1 and/or N_2 and/or N_3 equal to zero, the trivariate table can be collapsed to a bivariate or monovariate table or a point. For bivariate or monovariate tables, the size limitation is still 512. However $N_i \times N_j \leq 512$ for monovariate tables allowing more points per curve to be specified.

f. Format 6: This format is used to input the base geopotential or geometric altitudes and molecular scale temperatures in category 14.

Col Card	1-12	13-24	25-36	37-48	49-60	61-72
1	HB(1)	HB(2)	HB(3)	HB(4)	HB(5)	HB(6)
2	HB(7)	.	.	.	HB(NPTS)	
.	TMB(1)	TMB(2)	TMB(3)	TMB(4)	TMB(5)	TMB(6)
.	TMB(7)	.	.	.	TMB(NPTS)	

The number of points in each table, NPTS, is input on the category 14 card. In the above table, HB(i) are the base geopotential attitudes and TMB(i) the base molecular scale temperature. The maximum number of points in these tables is $NPTS \leq 23$.

4. Variable identification numbers and input/output units.-
Variable identification numbers and input/output units are given in table 1.

TABLE 1.- VARIABLE IDENTIFICATION NUMBERS AND INPUT UNITS

IDN	Variable	Reference equation from vol. I	Vector component		Input units ^a		Output units ^a		
			STEP1	STEP2	Variable	Standard deviation	Variable	Standard deviation	
State									
1	u	$\left. \begin{array}{l} V_A \\ \gamma_A \\ \lambda_A \\ h_o \\ \phi_D \\ \theta \\ e_o \\ e_1 \\ e_2 \\ e_3 \end{array} \right\} \begin{array}{l} \text{for NPC(3) = 0} \\ \text{for NPC(3) = 1} \\ \text{for NPC(3) = 2} \end{array}$	X	X	mps	mps	mps	mps	
2	v		(127) thru (129)	X	X	mps(deg)	mps(rad)	mps(deg)	mps(rad)
3	w		(219)	X	X	mps(deg)	mps(rad)	mps(deg)	mps(rad)
4	h_o		(229)	X	X	m	m	m	m
5	ϕ_D			X	X	deg (geod) ^b	rad (geoc) ^b	deg (geod) ^b	rad (geoc) ^b
6	θ			X	X	deg	rad	deg	rad
7	e_o			X	X	- (deg)	- (rad)	- (deg)	- (rad)
8	e_1			X	X	- (deg)	- (rad)	- (deg)	- (rad)
9	e_2			X	X	- (deg)	- (rad)	- (deg)	- (rad)
10	e_3			X	X	----	----	----	----
Model parameters									
1	C_1 Aerodynamic	(147)	Z,U,C	↑ Not included ↓	----	----	----	----	
2	C_2 Error coefficients	↓	Z,U,C		----	----	----	----	
3	C_3	↓	Z,U,C		----	----	----	----	
4	C_4	↓	Z,U,C		rad ⁻²	rad ⁻²	rad ⁻²	rad ⁻²	
5	C_5	↓	Z,U,C		rad ⁻¹	rad ⁻¹	rad ⁻¹	rad ⁻¹	
6	C_6	↓	Z,U,C		rad ⁻¹	rad ⁻¹	rad ⁻¹	rad ⁻¹	
7	C_7	↓	Z,U,C		----	----	----	----	
8	C_8	↓	Z,U,C		----	----	----	----	
9	C_9	↓	Z,U,C		----	----	----	----	
10	C_{10}	↓	Z,U,C		----	----	----	----	
11	C_{11}	↓	Z,U,C		----	----	----	----	
12	C_{12}	↓	Z,U,C		----	----	----	----	
13	C_{13} Unused	↓							
14	C_{14}	↓							
15	C_{15}	↓							
16	C_{16} Mass error	(149)	Z,U,C		kg	kg	kg	kg	
17	C_{17} Coefficients	↓	Z,U,C		kg/sec	kg/sec	kg/sec	kg/sec	
18	C_{18}	↓	Z,U,C		kg/sec ²	kg/sec ²	kg/sec ²	kg/sec ²	
19	C_{19} Unused	↓							
20	C_{20} Unused	↓							
21	C_{21} Density error	(151)	Z,U,C		----	----	----	----	
22	C_{22} Coefficients	↓	Z,U,C		kg/m ³	kg/m ³	kg/m ³	kg/m ³	
23	C_{23}	↓	Z,U,C		1/m	1/m	1/m	1/m	
24	C_{24} Unused	↓							
25	C_{25} Unused	↓							
26	C_{26} Atmosphere winds	(152)	Z,U,C		m/sec	m/sec	m/sec	m/sec	
27	C_{27} Error coefficient	↓	Z,U,C		m/sec	m/sec	m/sec	m/sec	
28	C_{28} Unused	↓							
29	C_{29} Unused	↓							
30	C_{30} Unused	↓							
31	C_{31} Center of gravity	(153)	Z,V,C		Z,U,C	m	m	m	m

^aOnly metric SI units are presented. For English units replace m by ft and kg by slugs.

^bgeod refers to geodetic latitude, geoc refers to geocentric latitude.

TABLE 1- VARIABLE IDENTIFICATION NUMBERS AND INPUT UNITS - Continued

IDN	Variable	Reference equation from vol. I	Vector component		Input units ^a		Output units ^a	
			STEP1	STEP2	Variable	Standard deviation	Variable	Standard deviation
Model parameters								
32	C ₃₂ Error coefficients	↓	Z,V,C	Z,U,C	m	m	m	m
33	C ₃₃ ↓	↓	Z,V,C	Z,U,C	m	m	m	m
34	C ₃₄ Unused							
35	C ₃₅ Unused							
36	C ₃₆ Inertial	(154)	Z,U,C	Z,U,C	----	----	----	----
37	C ₃₇ Angular rate	↓	Z,U,C	Z,U,C	----	----	----	----
38	C ₃₈ Error coefficients	↓	Z,U,C	Z,U,C	----	----	----	----
39	C ₃₉ ↓	↓	Z,U,C	Z,U,C	----	----	----	----
40	C ₄₀ ↓	↓	Z,U,C	Z,U,C	----	----	----	----
41	C ₄₁ ↓	↓	Z,U,C	Z,U,C	----	----	----	----
42	C ₄₂ ↓	↓	Z,U,C	Z,U,C	----	----	----	----
43	C ₄₃ ↓	↓	Z,U,C	Z,U,C	----	----	----	----
44	C ₄₄ ↓	↓	Z,U,C	Z,U,C	----	----	----	----
45	C ₄₅ ↓	↓	Z,U,C	Z,U,C	rad/sec	rad/sec	rad/sec	rad/sec
46	C ₄₆ ↓	↓	Z,U,C	Z,U,C	rad/sec	rad/sec	rad/sec	rad/sec
47	C ₄₇ ↓	↓	Z,U,C	Z,U,C	rad/sec	rad/sec	rad/sec	rad/sec
48	C ₄₈ ↓	↓	Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m
49	C ₄₉ ↓	↓	Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m
50	C ₅₀ ↓	↓	Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m
51	C ₅₁ ↓	↓	Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m
52	C ₅₂ ↓	↓	Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m
53	C ₅₃ ↓	↓	Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m
54	C ₅₄ ↓	↓	Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m
55	C ₅₅ ↓	↓	Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m
56	C ₅₆ ↓	↓	Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m
57	C ₅₇ ↓	↓	Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m
58	C ₅₈ Unused	↓	Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m
59	C ₅₉ Unused							
60	C ₆₀ Unused							
61	C ₆₁ Acceleration	(159)	Z,V,C	Z,U,C	----	----	----	----
62	C ₆₂ Error coefficients	↓	Z,V,C	Z,U,C	----	----	----	----
63	C ₆₃ ↓	↓	Z,V,C	Z,U,C	----	----	----	----
64	C ₆₄ ↓	↓	Z,V,C	Z,U,C	----	----	----	----
65	C ₆₅ ↓	↓	Z,V,C	Z,U,C	----	----	----	----
66	C ₆₆ ↓	↓	Z,V,C	Z,U,C	----	----	----	----
67	C ₆₇ ↓	↓	Z,V,C	Z,U,C	----	----	----	----
68	C ₆₈ ↓	↓	Z,V,C	Z,U,C	----	----	----	----
69	C ₆₉ ↓	↓	Z,V,C	Z,U,C	----	----	----	----
70	C ₇₀ ↓	↓	Z,V,C	Z,U,C	m/sec ²	m/sec ²	m/sec ²	m/sec ²
71	C ₇₁ ↓	↓	Z,V,C	Z,U,C	m/sec ²	m/sec ²	m/sec ²	m/sec ²
72	C ₇₂ ↓	↓	Z,V,C	Z,U,C	m/sec ²	m/sec ²	m/sec ²	m/sec ²

^aOnly metric SI units are presented. For English units replace m by ft and kg by slugs.

TABLE 1.- VARIABLE IDENTIFICATION NUMBERS AND INPUT UNITS - Concluded

IDN	Variable	Reference equation from vol. I	Vector component		Input units ^a		Output units ^a	
			STEP1	STEP2	Variable	Standard deviation	Variable	Standard deviation
Model parameters								
73	C ₇₃ Unused							
74	C ₇₄ Unused							
75	C ₇₅ Unused							
76	C ₇₆ Tracking	(239)	Z,V,C	Z,V,C	----	----	----	----
77	C ₇₇ Station 1	and	Z,V,C	Z,V,C	----	----	----	----
78	C ₇₈ Error coefficients	table 11	Z,V,C	Z,V,C	---	---	---	---
79	C ₇₉	↓	Z,V,C	Z,V,C	m	m	m	m
80	C ₈₀		Z,V,C	Z,V,C	rad	rad	rad	rad
81	C ₈₁		Z,V,C	Z,V,C	rad	rad	rad	rad
82	C ₈₂		Z,V,C	Z,V,C	sec	sec	sec	sec
83	C ₈₃		Z,V,C	Z,V,C	sec	sec	sec	sec
84	C ₈₄		Z,V,C	Z,V,C	sec	sec	sec	sec
85	C ₈₅		Z,V,C	Z,V,C	ft	ft	ft	ft
86	C ₈₆		Z,V,C	Z,V,C	rad	rad	rad	rad
87	C ₈₇ Unused							
88	C ₈₈ Latitude of station 1		Z,V,C	Z,V,C	deg(geod) ^b	rad(geoc) ^b	rad(geoc) ^b	rad(geoc) ^b
89	C ₈₉ Longitude of station 1		Z,V,C	Z,V,C	deg	rad	rad	rad
90	C ₉₀ Altitude of station 1		Z,V,C	Z,V,C	m	m	m	m
91	C ₉₁ Error coefficients	table 11	Z,V,C	Z,V,C				
.	.	for tracking sta-	.	.				
.	.	tion 2,3,4, & 5	.	.				
.	.	See table 11, vol. I to correspond with C ₇₆ - C ₉₀	.	.				
150	C ₁₅₀							
151	δ _P Orientation of airborne radar	(269)	C	C	deg	----	----	----
152	δ _Y	and figure 7	C	C	deg	----	----	----

^aOnly metric SI units are presented. For English units replace m by ft and kg by slugs.

^bgeod refers to geodetic latitude, geoc refers to geocentric latitude.

5. Sample input. - The card inputs for STEP1 and STEP2, which correspond to the sample output in Section II.C.5 follow.

a. STEP1 input:

```

1  STEP1 FILTERING CHECK PROBLEM (FEB. 1969) WAGNER AND SEROLD
2  0 1 2 0 0 2 1 3 0 0
3 1 1 10001.2000 100. (SIG=100. ,RN=.55)
3 1 2 -6.7508000 .035 (SIG=2 DEG ,RN=-.81)
3 1 3 63.0352000 .018 (SIG=1 DEG ,RN=-.33)
3 1 4 100584.000 1000. (SIG=1000. ,RN=-.96)
3 1 5 16.7583977 .0003 (SIG=.0170DEG,RN=1.69)
3 1 6 28.0418380 .0003 (SIG=.0170DEG,RN=.05)
3 1 7 29.8270000 .0530 (SIG=3 DEG ,RN=1.10)
3 1 8 -4.4320000 .0350 (SIG=2 DEG ,RN=-1.72)
3 1 9 19.3930000 .0530 (SIG=3 DEG ,RN=-1.37)
3 2 46 -.000108 .0002 (SIG=.0002 ,RN=-.54)
3 2 103 16.6055454 .000375 (SIG=.0214 DEG) MOD.PARA. - Z
3 2 104 31.0 .000375 (SIG=.0214 DEG) MOD.PARA. - Z
3 3 45 0. .0001 MOD.PARA. - U
3 3 47 0. .0001 MOD.PARA. - U
3 5 31 -1.0 CONSTANT
3 5 33 0.5 CONSTANT
3 5 88 15.09690377 CONSTANT
3 5 89 27.0 CONSTANT
4 70.0 5.0 0.5 90. NUMERICAL INTEG.
6 1 2 CG/IMU
0.0 1.0 100.0 1.0
6 3 2 CG/IMU
0.0 -0.5 100.0 -0.5
5 1 32.174046 1.407690E16 1092.055E-4 GRAV. DATA
5 2 20855970. 20926430. .7292115E-4 GEOPH.DATA
7 1 70.0 82.0 .99 1 1 1 20.0 .00003 .00003 MEAS.CDS.
7 2 78.0 88.0 1.99 1 1 1 20.0 .00003 .00003 MEAS.CDS.
12 3 -1. 400. MASS(T)
-1. 25.57031 200. 24.8013 400. 24.0262
14 1 ATMOSPHERE
11-1 AERO TABLES
1 3 8 5 8 CD(ALPHA,BETA,M)
0. 4. 8. 12. 16. 20. 24. 28.
-8. -4. 0. 4. 8.
2. 3. 4. 5. 6. 6.5 7. 30.
.2247 .2266 .2404 .2602 .2886 .3261 .3730 .4297 .2220 .2265 .2386 .2589
.2675 .3252 .3724 .4294 .2188 .2252 .2381 .2584 .2871 .3249 .3722 .4293
.2220 .2205 .2388 .2589 .2875 .3252 .3724 .4294 .2247 .2286 .2404 .2602
.2886 .3261 .3730 .4297 .2086 .2121 .2228 .2410 .2672 .3020 .3460 .3997
.2004 .2048 .2170 .2364 .2634 .2989 .3434 .3976 .1915 .2006 .2146 .2347
.2621 .2978 .3425 .3969 .2004 .2048 .2170 .2364 .2634 .2989 .3434 .3976
.2086 .2121 .2228 .2410 .2672 .3020 .3460 .3997 .1660 .1700 .1817 .2006
.2270 .2613 .3043 .3566 .1527 .1565 .1729 .1938 .2214 .2566 .3003 .3531
.1387 .1522 .1692 .1911 .2193 .2549 .2988 .3519 .1527 .1585 .1729 .1938
.2214 .2566 .3003 .3531 .1660 .1700 .1817 .2006 .2270 .2613 .3043 .3566
.1226 .1275 .1410 .1618 .1896 .2250 .2685 .3210 .1058 .1135 .1306 .1537
.1830 .2194 .2637 .3169 .0886 .1061 .1263 .1507 .1807 .2174 .2621 .3154
.1058 .1135 .1306 .1537 .1830 .2194 .2637 .3169 .1226 .1275 .1410 .1618
.1896 .2250 .2685 .3210 .0994 .1051 .1203 .1431 .1728 .2099 .2550 .3090
.0812 .0901 .1095 .1347 .1660 .2041 .2501 .3048 .0625 .0826 .1051 .1317
.1636 .2021 .2484 .3033 .0812 .0901 .1095 .1347 .1660 .2041 .2501 .3048
.0994 .1051 .1203 .1431 .1728 .2099 .2550 .3090 .0969 .1026 .1179 .1408
.1706 .2076 .2532 .3073 .0785 .0876 .1070 .1324 .1638 .2021 .2482 .3030
.0597 .0799 .1027 .1293 .1614 .2001 .2465 .3016 .0785 .0876 .1070 .1324
.1638 .2021 .2482 .3030 .0969 .1026 .1179 .1408 .1706 .2076 .2532 .3073
.0965 .1023 .1176 .1405 .1703 .2075 .2529 .3070 .0782 .0873 .1067 .1321
.1635 .2018 .2480 .3028 .0594 .0796 .1024 .1290 .1611 .1998 .2463 .3013

```

.0782	.0873	.1067	.1321	.1635	.2018	.2480	.3028	.0965	.1023	.1176	.1405
.1703	.2075	.2529	.3070	.0965	.1023	.1176	.1405	.1703	.2075	.2529	.3070
.0782	.0873	.1067	.1321	.1635	.2018	.2480	.3028	.0594	.0796	.1024	.1290
.1611	.1998	.2463	.3013	.0782	.0873	.1067	.1321	.1635	.2018	.2480	.3028
.0965	.1023	.1176	.1405	.1703	.2075	.2529	.3070				

CY (ALPHA, BETA, M)

0.	4.	8.	12.	16.	20.	24.	28.				
-8.	-4.	0.	4.	8.							
2.	3.	4.	5.	6.	6.5	7.	30.				
.1117	.1129	.1163	.1209	.1262	.1319	.1379	.1442	.0538	.0545	.0566	.0593
.0622	.0652	.0684	.07160	0	0	0	0	0	0	0	0
-.0538	-.0545	-.0566	-.0593	-.0622	-.0652	-.0684	-.0716	-.1117	-.1129	-.1163	-.1209
-.1262	-.1319	-.1379	-.1442	.0575	.0623	.0722	.0826	.0924	.1017	.1108	.1197
.0100	.0206	.0312	.0386	.0444	.0496	.0544	.05910	0	0	0	0
0	0	0	0	-.0106	-.0206	-.0312	-.0386	-.0444	-.0496	-.0544	-.0591
-.0575	-.0623	-.0722	-.0826	-.0924	-.1017	-.1108	-.1197	.0345	.0394	.0497	.0607
.0713	.0814	.0913	.1011	.0011	.0089	.0198	.0275	.0337	.0393	.0446	.0497
0	0	0	0	0	0	0	0	.0011	-.0089	-.0198	-.0275
-.0337	-.0393	-.0446	-.0497	-.0345	-.0394	-.0497	-.0607	-.0713	-.0814	-.0913	-.1011
.0354	.0386	.0461	.0548	.0639	.0733	.0827	.0923	.0077	.0128	.0194	.0250
.0303	.0353	.0403	.04530	0	0	0	0	0	0	0	0
-.0077	-.0128	-.0194	-.0250	-.0303	-.0353	-.0403	-.0453	-.0354	-.0386	-.0461	-.0548
-.0639	-.0733	-.0827	-.0923	.0481	.0495	.0538	.0600	.0674	.0755	.0841	.0931
.0228	.0228	.0248	.0283	.0323	.0366	.0411	.04570	0	0	0	0
0	0	0	0	-.0228	-.0228	-.0248	-.0283	-.0323	-.0366	-.0411	-.0457
-.0481	-.0495	-.0538	-.0600	-.0674	-.0755	-.0841	-.0931	.0484	.0499	.0540	.0602
.0675	.0756	.0842	.0932	.0232	.0230	.0250	.0284	.0324	.0367	.0411	.0458
0	0	0	0	0	0	0	0	-.0232	-.0230	-.0250	-.0284
-.0324	-.0367	-.0411	-.0458	-.0484	-.0499	-.0540	-.0602	-.0675	-.0756	-.0842	-.0932
.0484	.0499	.0540	.0602	.0675	.0756	.0842	.0932	.0232	.0230	.0250	.0284
.0324	.0367	.0411	.04580	0	0	0	0	0	0	0	0
-.0232	-.0230	-.0250	-.0284	-.0324	-.0367	-.0411	-.0458	-.0484	-.0499	-.0540	-.0602
-.0675	-.0756	-.0842	-.0932	.0484	.0499	.0540	.0602	.0675	.0756	.0842	.0932
.0232	.0230	.0250	.0284	.0324	.0367	.0411	.04580	0	0	0	0
0	0	0	0	-.0232	-.0230	-.0250	-.0284	-.0324	-.0367	-.0411	-.0458
-.0484	-.0499	-.0540	-.0602	-.0675	-.0756	-.0842	-.0932				

CL (ALPHA, BETA, M)

0.	4.	8.	12.	16.	20.	24.	28.				
-8.	-4.	0.	4.	8.							
2.	3.	4.	5.	6.	6.5	7.	30.				
0	.0402	.0825	.1275	.1747	.2230	.2709	.31700		.0387	.0802	.1251
.1726	.2212	.2697	.3163	.0020	.0382	.0793	.1242	.1718	.2206	.2692	.3160
0	.0387	.0802	.1251	.1726	.2212	.2697	.31630		.0402	.0825	.1275
.1747	.2230	.2709	.31700		.0162	.0409	.0737	.1119	.1536	.1969	.2402
0	.0063	.0323	.0670	.1067	.1495	.1937	.2379	-.0288	.0034	.0279	.0643
.1048	.1480	.1920	.23710		.0063	.0323	.0670	.1067	.1495	.1937	.2379
0	.0162	.0409	.0737	.1119	.1536	.1969	.24020		.0077	.0242	.0492
.0803	.1158	.1538	.19290		-.0022	.0154	.0423	.0748	.1112	.1502	.1901
-.0282	-.0118	.0110	.0395	.0727	.1096	.1489	.18910		-.0022	.0154	.0423
.0748	.1112	.1502	.19010		.0077	.0242	.0492	.0803	.1158	.1538	.1929
0	.0103	.0262	.0485	.0761	.1078	.1424	.17840		.0049	.0206	.0434
.0716	.1040	.1392	.1758	.0109	.0003	.0180	.0415	.0700	.1026	.1380	.1749
0	.0049	.0206	.0434	.0716	.1040	.1392	.17580		.0103	.0262	.0485
.0761	.1078	.1424	.17840		.0173	.0369	.0603	.0879	.1191	.1528	.1879
0	.0165	.0345	.0573	.0847	.1161	.1502	.1857	.0067	.0171	.0338	.0562
.0830	.1151	.1493	.18500		.0165	.0345	.0573	.0847	.1161	.1502	.1857
0	.0173	.0369	.0603	.0879	.1191	.1528	.18790		.0176	.0375	.0611
.0888	.1202	.1541	.18920		.0169	.0352	.0581	.0857	.1172	.1515	.1871
.0071	.0177	.0345	.0571	.0847	.1162	.1506	.18630		.0169	.0352	.0581
.0857	.1172	.1515	.18710		.0176	.0375	.0611	.0888	.1202	.1541	.1892
0	.0177	.0375	.0611	.0889	.1203	.1542	.18940		.0169	.0352	.0582
.0858	.1173	.1516	.1872	.0071	.0177	.0345	.0571	.0847	.1163	.1507	.1865
0	.0169	.0352	.0582	.0858	.1173	.1516	.18720		.0177	.0375	.0611
.0889	.1203	.1542	.18940		.0177	.0375	.0611	.0889	.1203	.1542	.1894
0	.0169	.0352	.0582	.0858	.1173	.1516	.1872	.0071	.0177	.0345	.0571
.0847	.1163	.1507	.18650		.0169	.0352	.0582	.0858	.1173	.1516	.1872
0	.0177	.0375	.0611	.0889	.1203	.1542	.1894				

END CARD

-1 END OF JOB

b. STEP2 input:

```

1  STEP2 FILTERING CHECK PROBLEM (FEB. 1969) WAGNER AND SEROLD
2  0  1  2  0  0  2  1  3  0  0
3  1  1  16001.2000  100. (SIG=100. ,RN=.55)
3  1  2  -0.75088000  .035 (SIG=2 DEG ,RN=-.81)
3  1  3  63.0352000  .018 (SIG=1 DEG ,RN=-.33)
3  1  4  100584.000  1000. (SIG=1000. ,RN=-.96)
3  1  5  16.7583977  .0003 (SIG=.017DEG,RN=1.69)
3  1  6  28.0418380  .0003 (SIG=.017DEG,RN=.05)
3  1  7  29.8270000  .0530 (SIG=3 DEG ,RN=1.10)
3  1  8  -4.43200000  .0350 (SIG=2 DEG ,RN=-1.72)
3  1  9  19.3930000  .0530 (SIG=3 DEG ,RN=-1.37)
3  2  72  .092200000  .2000 (SIG=.20 ,RN=-.54)
3  2  103  16.6055454  .000375 (SIG=.0214 DEG) MOD.PARA. - Z
3  2  104  31.0  .000375 (SIG=.0214 DEG) MOD.PARA. - Z
3  3  70  0.  .20 MOD.PARA. - U
3  3  71  0.  .20 MOD.PARA. - U
3  4  76  1.0  .000030 MOD.PARA. - U
3  4  81  0.  .000030 MEAS.PARA. - V
3  5  31  -1.0
3  5  33  0.5 CONSTANT
3  5  88  15.09690377 CONSTANT
3  5  89  27.0 CONSTANT
6  1  2 CONSTANT
0.0 1.0 100.0 1.0 CG/IMU
6  3  2 CG/IMU
0.0 -0.5 100.0 -0.5
4 70.0 5.0 0.5 90.0
5 1 32.174048 1.407690E16 1092.055E-6 GRAV. DATA
5 2 20855970. 20926430. .7292115E-4 GEOPH. DATA
7 1 70.0 82.0 .99 1 1 1 20.0 .00003 .00003 MEAS.CDS.
7 2 78.0 88.0 1.99 1 1 1 20.0 .00003 .00003 MEAS.CDS.
20 END CARD
-1 END OF JOB

```

B. Tape Input and Output

STEP always requires the PQR tape containing data used by the equations of motion. When operating in the filtering mode, the programs also require a FIT tape containing data to which the equations of motion are fit. Formats for these tapes are presented in the previous section under input format 2 and 3.

On filtering problems, optional capability has been included to write a tape containing the 10-state variables u , v , w , h , ϕ , θ , e_0 , e_1 , e_2 , and e_3 versus time. This tape, called STATE, is written on the backward smoothing of the last iteration so that it contains the best estimate of the variables after processing all data. Because it is written on the backward smoothing, the first points on the tape are at final time, the last points at initial time. The tape can be used to print the state time history in tabular form, or to prepare STEP2 position and velocity estimates for processing on STEP1. All angular data on the tape are in radians, the remainder in the m, kg, sec or slug, ft, sec systems of units.

<u>FORTTRAN</u> <u>name</u>	<u>Logical tape</u> <u>unit</u>	<u>Description</u>
IN	5	Input tape
OUT	6	Output tape
PQR	2	PQR tape
FIT	1	FIT tape
STATE	4	STATE tape
SCRACH	3	Scratch tape used for temporary storage during problem execu- tion

C. Tab Output

The tab printout from STEP is divided into four parts -- Part 1, the printout of input variables and controls; Part 2, the block printout during the forward and backward integration; Part 3, the printout of the measurement schedule; and Part 4, the printout of the residuals and loss function. Each of these printouts will be described. The sample outputs in Subsection C.5 will aid in the discussion.

1. Printout of input data and controls.- As data are input to STEP, they are immediately printed for later verification. This printout, shown on the first page of the sample output, is unlabeled and exactly duplicates the data on the input cards. If the user requests printout of the PQR and/or FIT tapes, it occurs during this part of the output. After all input data have been loaded from cards, subroutine SETUP is called to transform and convert units (e.g., degrees to radians) on the data to prepare for the problem execution. From SETUP, a summary of the problem operating mode, options, and controls is printed in the form of phrases and data. The data consist primarily of geophysical, gravitational, and atmosphere constants, state variables, and tracking station locations. The units on these data are consistent with metric or English system specified. All angular data are in degrees.

The components of the expanded state variables transformed to internal units are next tabulated along with uncertain model parameters and their variances. In this tabulation, all angles are in radians.

2. Block printout.- During execution of a problem, labeled block printouts occurs during both the forward filtering and backward smoothing at a frequency specified by input. The variables in the block printout on the forward integration correspond to the reference trajectory. In STEP2, this block printout appears as follows:

```

TIME --
V(A) -- G(A) -- L(A) -- ALT -- LATD -- LON --
U(I) -- V(I) -- W(I) -- PSI -- THE -- PHI --
U(B) -- V(B) -- W(B) -- SIG -- BET -- ALF --
XP -- YP -- ZP -- V(T) -- XZI -- ETA --
P -- Q -- R -- AX -- AY -- AZ --
PM -- QM -- RM -- AXM -- AYM -- AZM --
EO -- E1 -- E2 -- E3 -- LATC -- A(T) --

```


where

$V(A), G(A), L(A)$ = Atmosphere relative velocity vector V_A , γ_A , and λ_A . In STEP2, there is no atmosphere; therefore, the velocity vector is relative to planet surface. Units are m/sec or ft/sec and deg.

$U(I), V(I), W(I)$ = Inertial velocity vector Cartesian components, u , v , and w . Units are m/sec or ft/sec.

$U(B), V(B), W(B)$ = Components of V_A in body axes directions, u_B , v_B , and w_B . Units are m/sec or ft/sec.

ALT = Altitude above oblate planet surface, h_0 .
Units are in m or ft.

LATD = Geodetic latitude in degrees.

LON = Longitude in degrees.

PSI, THE, PHI = Euler angles $\bar{\psi}$, $\bar{\theta}$, $\bar{\phi}$ and in degrees.

SIG, BET, ALF = Roll angle σ about the velocity vector V_A , sideslip angle β and angle of attack α . Units are degrees.

XP, YP, ZP = Distances from center of gravity to the IMU as measured along body axes directions, and corrected for systematic error, x_p , y_p , and z_p . Units are in m or ft.

$V(T)$ = Magnitude of the inertial velocity vector in m/sec or ft/sec.

XZI = Steering angle ξ in degrees. See figure 4 of vol. I.

ETA = Steering angle η in degrees. See figure 4 of vol. I.

P, Q, R = Inertial angular rates about the roll, pitch, and yaw axes and corrected for systematic error. Units are in rad/sec.

PM, QM, RM = Inertial angular rates about the roll, pitch, and yaw axes as interpolated from the PQR tape. Units are in rad/sec.

AX, AY, AZ = Accelerations a_{XB} , a_{YB} , and a_{ZB} , along the body axes direction and corrected for systematic error. Units are in m/sec^2 or ft/sec^2 .

AXM, AYM, AZM = Accelerations, a_{XM} , a_{YM} , and a_{ZM} , along the body axes directions as interpolated from the PQR tape. Units are in m/sec^2 or ft/sec^2 .

EO, E1, E2, E3 = Euler parameters e_0 , e_1 , e_2 , and e_3 .

LATC = Geocentric latitude in degrees.

A(T) = Total acceleration in m/sec^2 or ft/sec^2 .

In STEP1, the last two lines of output are replaced by the following:

```
PM -- QM -- RM -- CA -- CY -- CN --  
DP -- M -- RHO -- C1 -- C2 -- C3 --  
EO -- E1 -- E2 -- E3 -- LATC -- RE --  
UW -- VW --
```

where

C_A , C_Y , C_N = Axial, lateral, and normal aerodynamic coefficients.

$C1$, $C2$, $C3$ = Aerodynamic coefficients interpolated from input tables, either C_A , C_Y , C_N , or C_D , C_Y , C_L , or C_A , C_{Y_η} , C_{N_η} , respectively.

DP = Dynamic pressure q in nt/m^2 or lb_f/ft^2 .

M = Mach number, M.

RHO = Atmospheric density ρ in kg/m^3 or slugs/ft^3 .

RE = Reynolds number, R_e .

UW, VW = Atmospheric winds corrected for systematic error, u_w
and v_w . Units are in m/sec or ft/sec.

On filtering problems during the forward integration the reference values of the model parameters being estimated are printed in the order that they were input. The print format is as follows:

```
C(24) -- C(28) -- C(43) -- C(40) -- C(77) -- C(88) --  
C( . ) -- . . .
```

The argument of C(.) are the variable identification numbers and their units are as described in Subsection II.A.4.

On nonupdated nominal filtering problems during the forward integration, the accumulated minimum variance corrections, $\hat{Z}(t/t)$, to be added to the reference, $Z_{ref}(t)$, are next printed:

```
Z(1) -- Z(2) -- Z(3) -- Z(4) -- Z(5) -- Z(6) --  
Z(7) -- Z(8) -- Z(9) -- Z(24) -- Z(28) -- Z(43) --  
Z(88) -- . . .
```

The first 9 or 10 variables correspond to the transformed state variables specified by NPC(3). The remaining variables correspond to the estimated model parameters whose identification numbers and units are specified in Subsection II.A.4.

The standard deviations of the expanded state vector components are printed next on error analysis and filtering problems according to the following format:

```
S(1) -- S(2) -- S(3) -- S(4) -- S(5) -- S(6) --  
S(7) -- S(8) -- S(9) -- S(23) -- S(19) --.
```

The first 9 or 10 standard deviations correspond to the basic state variables, transformed as specified by NPC(3). These are followed by the standard deviation of model parameters being estimated in the order that they were input. The argument in S() is the identification number of the estimated model parameter which, along with the units for the standard deviations,

are shown in Subsection II.A.4. These standard deviations are printed on the backward smoothing on the last iteration only if NPC(8) equals 2 or 3.

On error analysis or filter problems, the entire covariance and correlation matrices P, CUZ, and CVZ, can be printed during the last iteration if NPC(6) is properly specified. These matrices correspond to the output units designated by NPC(3). Units for the covariance and correlation elements are as described for the standard deviations in Subsection II.A.4. Because the covariance matrix P is symmetrical, only its lower left triangle is printed as follows:

COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)

```

P(1,1)
P(2,1) P(2,2)
P(3,1) P(3,2) P(3,3)
.      .      .      .
.      .      .      .      .
.      .      .      .      .      .

```

The correlation matrices CUZ and CVZ are printed as shown below.

CORRELATION MATRIX (CVZ) TRANSPOSE

```

CUZ(1,1) CUZ(2,1) . . . . . CUZ(12,1)
CUZ(13,1) CUZ(14,1) . . .
CUZ(1,2) CUZ(2,2) . . . . . CUZ(12,2)
CUZ(13,2) CUZ(14,2) . . .
.
.
CUZ(1,q) CUZ(2,q) . . . . . CUZ(12,q)
CUZ(13,q) CUZ(14,q) . . .

```

CORRELATION MATRIX (CVZ) TRANSPOSE

```

CVZ(1,1) CVZ(2,1) . . . . . CVZ(12,1)
CVZ(13,1) CVZ(14,1) . . .

```

CVZ(1,2) CVZ(2,2) CVZ(12,2)
 CVZ(13,2) CVZ(14,2) . . .

CVZ(1,r) CVZ(2,r) CVZ(12,r)
 CVZ(13,4) CVZ(14,4) . . .

3. Measurement schedule.- Between block printing on the forward integration, a schedule of the measurements processed can be printed if NPC(5) equals 0. The following format is used for this printout:

```
POINTS  TYPE  TIME  COMP1  COMP2  COMP3  SIG1  SIG2  SIG3
x, x, x   x   xxx   xxx   xxx   xxx   xxx   xxx   xxx
x, x, x   x   xxx   xxx   xxx   xxx   xxx   xxx   xxx
```

The number of scalar data points processed is counted and printed under the heading POINTS. The three numbers correspond to the three scalar components accounted for on each line of data. If a zero is printed under the POINTS heading, then the component corresponding to the zero was not processed. Under TYPE, the type of data (MTYP) is printed. Definitions of MTYP are presented in Subsection II.A.2. The time of the data is next printed under TIME and followed by the values for the three components. Units for these data are shown below.

. . .	TYP	TIME	COMP1	COMP2	COMP3	SIG1	SIG2	SIG3
Tracking	1-5	(sec)	R(m,ft)	A(rad)	E(rad)	σ_R (m,ft)	σ_A (rad)	σ_E (rad)
Airborne radar	6	(sec)	R_R (m,ft)	unused	unused	σ_{R_R} (m,ft)	unused	unused
Velocity	7	(sec)	u(m/sec ft/sec)	v(m/sec ft/sec)	w(m/sec ft/sec)	σ_u (m/sec ft/sec)	σ_v (m/sec ft/sec)	σ_w (m/sec ft/sec)
Position	8	(sec)	h(m,ft)	φ (rad)	θ (rad)	σ_h (m,ft)	σ_φ (rad)	σ_θ (rad)
Accelerations	9	(sec)	a_x (m/sec ² ft/sec ²)	a_y (m/sec ² ft/sec ²)	a_z (m/sec ² ft/sec ²)	σ_{a_x} (m/sec ² ft/sec ²)	σ_{a_y} (m/sec ² ft/sec ²)	j_{a_z} (m/sec ² ft/sec ²)

The values for the measurement that are printed under columns COMP1. . COMP3 are the values corresponding to the reference trajectory and not the actual data from the FIT tape. The standard deviations under columns SIG1. . SIG3 are the sum of the standard deviations from the FIT tape and those input in category 7. These are the standard deviations used in the filter equations.

4. Residuals and loss function.- During the backward smoothing on the last iteration, best estimates of the measurements are calculated. The value of the measurement from the FIT tape is then subtracted from that calculated to form a residual. The residual is then divided by the standard deviation to form a weighted residual, and its square accumulated with all previously calculated weighted residuals to form the sum of the weighted residuals squared or loss function. These are tabulated between block prints as follows:

POINT	TYPE	TIME	RES1	RES2	RES3	WGT.	RES1	WGT.	RES2	WGT.	RES3	LOSS FCTN
x, x, x	x	xx	xx	xx	xx	xx		xx		xx		xx
x, x, x	x	xx	xx	xx	xx	xx		xx		xx		xx

The quantities under POINT, TYPE, and TIME are the same as in the measurement schedule in Subsection 3 above. RES1 .. RES3 are the unweighted residuals in m, ft, and rad; WGT. RES1 ... WGT. RES3 are the weighted residuals; and LOSS FCTN is the loss function. Three components of data per line is maintained. Only those components processed on the forward integration are accumulated in the loss function.

5. Sample output.- The sample outputs presented below were obtained on STEP1 and STEP2. They correspond to 20 sec of the check problem between 70 and 90 sec.

CONTROLS ARE SPECIFIED FOR
 *FILTERING RUN FROM TIME T0= 70.0000 TO TFINAL= 90.0000

- *UPDATED REFERENCE
- *SMOOTH COVARIANCE, CALCULATE RESIDUALS AND LOSS FUNCTION
- *FILTER FOR 1 ITERATIONS
- *VECTOR PROCESS FITTING DATA TRIPLES
- *INPUT AND OUTPUT IN ENGLISH UNITS (FT, FT/SEC, FT/SEC², LB, SLUG)
- *PLANET PARAMETERS

EQUIT_RAD.= 2.09264300E+07 POLAR_RAD.= 2.08559700E+07 ROTATION = 7.29211500E-05
 MU(GRAV.) = 1.40769000E+16 J2(GRAV.) = 1.09205500E-03 G(0) = 3.21740480E+01

*ATMOSPHERE IS 1959 ARDC
 MO = 2.89644000E+01 R(STAR) = 4.97192198E+04 CP/CV = 1.40000000E+00
 P(0) = 2.11621667E+03 BETA = 2.26960110E-08 S = 1.98720000E+02
 3.60892389E+04 A.20209974E+04 1.54199475E+05 1.73884514E+05
 3.44488189E+05 5.24934383E+05 5.57742782E+05 6.56167979E+05
 3.89988000E+02 3.89988000E+02 5.08788000E+02 5.08788000E+02
 4.06188000E+02 2.38618800E+03 2.56618800E+03 2.83618800E+03
 4.72708961E+02 5.19844194E+01 2.51625139E+00 1.21846395E+00
 1.55768677E-04 7.56734675E-06 5.90259850E-06 2.97981080E-06
 2.118258255E-03 2.1846395E+00 2.10938433E-02 2.03048103E-09

*INITIAL STATE ESTIMATE IS
 VELOCITY = 1.60012000E+04 GAMMA = -6.75088000E+00 LAMBDA = 6.30352000E+01
 ALTITUDE = 1.00584000E+05 GEOD.LAT. = 1.67583977E+01 LONGITUDE = 2.80418380E+01
 SIGMA = 2.98270000E+01 BETA = -4.43200000E+00 ALPHA = 1.93930000E+01

*FITTING DATA IS FROM 2 SOURCES

- 1. TRACKING STATION 1, GEOD.LAT.= 15.096904 LONGITUDE= 27.000000 ALTITUDE = 0. ABOVE REF. SURFACE
- 2. TRACKING STATION 2, GEOD.LAT.= 16.605545 LONGITUDE= 31.000000 ALTITUDE = 0. ABOVE REF. SURFACE

STATE VECTOR COMPONENTS

COMP.	ID.NO.	EST.VALUE	VARIANCE
1	1	7.20532663E+03	6.79079215E+04
2	2	1.56313582E+04	2.80981835E+04
3	3	1.88098346E+03	3.09451057E+05
4	4	9.87712173E+04	1.00000000E+06
5	5	2.90632098E-01	9.00000000E-08
6	6	4.89422401E-01	9.00000000E-08
7	7	7.69645202E-01	2.08169635E-04
8	8	1.55940474E-01	7.90725687E-04
9	9	2.08732405E-01	8.18646927E-04
10	10	5.82889025E-01	2.80457751E-04
11	46	-1.08000000E-04	4.00000000E-08
12	103	2.87979327E-01	1.40625000E-07
13	104	5.41052068E-01	1.40625000E-07
RANDOM MODEL PARAMETERS NOT BEING ESTIMATED (U-VECTOR)			
1	45	0.	1.00000000E-08
2	47	0.	1.00000000E-08

ITERATION NUMBER 1

TIME 7.0000000E+01
 V(R) 1.60012000E+04 G(R) -6.7508000E+00 L(R) 6.30322000E+01 ALT 1.00584000E+05 LAT 1.6783977E+01 LON 2.80418380E+01
 U(I) 7.20532669E+03 V(I) 1.56313582E+04 W(I) 1.68098344E+03 PSI 7.63702516E+01 THE 8.01936612E+00 PHI 2.92188573E+01
 U(B) 1.50482107E+04 V(B) -1.23650674E+03 W(B) 5.29724514E+03 SIG 2.98270000E+01 BET -4.43200000E+00 ALF 1.93930000E+01
 YP 0. 5.93691552E-03 R 8.82155972E-04 AX -1.16901563E+02 AY 3.17431021E+01 AZ -1.35669291E+02
 X 0. 6.4491552E-03 R 8.62155972E-04 CX -1.16901563E+02 CY 4.01463966E-02 CZ -1.71730420E+01
 PH -8.75453186E-04 QM 6.04491552E-03 RH 3.12280675E-05 C1 1.96621603E-01 C2 4.01463966E-02 C3 1.12845514E-01
 DP 3.99728017E+03 M 1.59317207E+01 RHO 1.59317207E+01 E1 1.59317207E+01 E2 2.08732405E-01 E3 5.82889025E-01 RE 2.37465225E+07
 FO 7.69645202E-01 EI 1.59340474E-01 E2 2.08732405E-01 E3 5.82889025E-01
 UW 0. 0.
 C 46-1.0800000E-04 C103 2.87979327E-01 C104 5.41052068E-01 C 3.0000000E-04 S(6) 3.0000000E-04
 S(1) 1.0000000E+02 S(2) 3.5000000E-02 S(3) 1.8000000E-02 S(4) 1.0000000E+03 S(5) 3.0000000E-04 S(6) 3.0000000E-04
 S(7) 5.3000000E+02 S(8) 3.5000000E-02 S(9) 5.3000000E-02 S(45) 0. S(103) 0. S(104) 3.7500000E-04
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)
 1.000E+04
 -4.796E-14 1.225E-03
 -1.954E-14 2.074E-26 3.240E-04
 -2.274F-13 0. 1.388E-17 1.000E+06
 2.168E-19 1.654E-24 6.617E-24 0. 9.000E-08
 0. 0. 0. 0. 0. 9.000E-08
 8.281E-15 0. 0. 0. -8.272E-25 0. 2.809E-03
 7.317E-15 -1.041E-17 0. 0. 0. 3.339E-17 1.225E-03
 7.855F-15 -1.843E-17 -4.337E-19 0. 0. 3.567E-17 -5.204E-18 2.809E-07
 0. 0. 0. 0. 0. 0. 0. 0.
 0. 0. 0. 0. 0. 0. 0. 0.
 0. 0. 0. 0. 0. 0. 0. 0.
 0. 0. 0. 0. 0. 0. 0. 0.
 0. 0. 0. 0. 0. 0. 0. 0.
 CORRELATION MATRIX (CUZ) TRANPOSE
 0. 0. 0. 0. 0. 0. 0. 0.
 0. 0. 0. 0. 0. 0. 0. 0.
 0. 0. 0. 0. 0. 0. 0. 0.
 1.406E-07
 0. 0. 0. 0. 0. 0. 0. 0.
 0. 0. 0. 0. 0. 0. 0. 0.
 0. 0. 0. 0. 0. 0. 0. 0.

POINTS	TYPE	TIME	COMP1	COMP2	COMP3	SIG1	SIG2	SIG3
1	3	70.0000	714184.53	.543024	.124359	20.000000	.000030	.000030
4	5	71.0000	720631.04	.560080	.121736	20.000000	.000030	.000030
7	9	72.0000	733673.53	.571235	.113737	20.000000	.000030	.000030
10	11	73.0000	746633.46	.581933	.113474	20.000000	.000030	.000030
13	14	74.0000	759455.28	.592182	.109513	20.000000	.000030	.000030
16	17	75.0000	772261.98	.602009	.105594	20.000000	.000030	.000030

POINTS	TYPE	TIME	COMP1	COMP2	COMP3	SIG1	SIG2	SIG3
1	3	70.0000	714184.53	.543024	.124359	20.000000	.000030	.000030
4	5	71.0000	720631.04	.560080	.121736	20.000000	.000030	.000030
7	9	72.0000	733673.53	.571235	.113737	20.000000	.000030	.000030
10	11	73.0000	746633.46	.581933	.113474	20.000000	.000030	.000030
13	14	74.0000	759455.28	.592182	.109513	20.000000	.000030	.000030
16	17	75.0000	772261.98	.602009	.105594	20.000000	.000030	.000030

TIME 7.5000000E+01
 V(R) 1.43660941E+04 G(R) -3.60307847E+00 L(R) 6.45375594E+01 ALT 9.57092856E+04 LAT 1.68297030E+01 LON 2.82380330E+01
 U(I) 6.42149491E+03 V(I) 1.49534045E+04 W(I) 1.49534045E+04 PSI 7.71482732E+01 THE 1.62568183E+00 PHI 2.77237382E+01
 U(B) 1.37299621E+04 V(B) -5.68174499E+02 W(B) 5.92868369E+03 V(I) 5.92868369E+03 SIG 2.67566182E+01 BET -2.17570634E+00 ALF 2.33549896E+01
 YP 0. 7.62858852E-03 R 9.62154065E-04 AX -1.42289431E+02 AY 1.92525840E+01 AZ -2.00471913E+02
 X 0. 9.42614974E-04 QM 7.73459373E-03 RH 3.95681893E-05 C1 2.99752742E-01 C2 2.19494605E-02 C3 1.45651215E-01
 PH -9.42614974E-04 QM 7.73459373E-03 RH 3.95681893E-05 C1 2.99752742E-01 C2 2.19494605E-02 C3 1.45651215E-01
 DP 4.43132000E+03 M 1.50442336E+01 RHO 1.50442336E+01 E1 1.50442336E+01 E2 2.55214946E-01 E3 5.72798761E-01 RE 2.85923201E+07
 FO 7.7529879E-01 EI 1.50442336E+01 E2 2.55214946E-01 E3 5.72798761E-01
 UW 0. 0.
 C 46-1.06005212E-04 C103 2.87979327E-01 C104 5.41052068E-01 C 3.0000000E-04 S(6) 3.0000000E-04
 S(1) 1.663637E+01 S(2) 7.496498E-04 S(3) 9.200352E-04 S(4) 1.794065E+01 S(5) 8.503151E-07 S(6) 9.186861E-07
 S(7) 4.8771634E-02 S(8) 2.262644E-02 S(9) 1.034877E-02 S(45) 0. S(103) 0. S(104) 3.7500000E-04
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)

2.768E+02
-5.954E-03 5.620E-07
-8.856E-04 4.365E-07 8.465E-07
-8.104E+01 9.490E-03 4.393E-03 3.219E+02
4.808E-06 1.160E-10 5.272E-10 6.334E-07 7.230E-13
1.000E-05 2.445E-10 2.230E-10 3.270E-06 1.626E-14 8.440E-13
-2.163E-02 0. -1.325E-01 4.733E-09 1.759E-09 2.277E-03
-5.133E-02 0. 7.933E-02 5.634E-09 3.897E-09 5.180E-04 5.120E-04
-1.583E-01 4.644E-06 1.277E-06 5.610E-02 1.496E-09 4.909E-09 7.118E-05 9.860E-05 1.071E-04
1.254E-09 6.114E-10 6.157E-06 6.157E-06 4.268E-13 7.340E-13 4.509E-10 1.302E-09 9.956E-08 0.
0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
CORRELATION MATRIX (CZ) TRANSPOSE
-9.179E-07 6.431E-11 8.773E-12 5.485E-07 4.716E-16 1.870E-14 4.622E-08 1.743E-08 2.666E-09 4.422E-14 0.
-1.108E-06 3.918E-10 7.323E-10 2.585E-06 2.056E-13 8.836E-14 5.053E-09 3.208E-08 1.330E-09 2.372E-13 0.
POINTS TYPE TIME COMP1 COMP2 COMP3 SIG1 SIG2 SIG3
19 20 21 76.0000 78423.14 .611442 .102442 20.000000 .000030 .000030
22 23 24 77.0000 797463.16 .620511 .099300 20.000000 .000030 .000030
25 26 27 78.0000 809871.47 .629241 .096400 20.000000 .000030 .000030
28 29 30 78.0000 938712.82 -1.456932 .077468 20.000000 .000030 .000030
31 32 33 79.0000 82141.49 .637645 .093739 20.000000 .000030 .000030
34 35 36 80.0000 834266.85 .645753 .091282 20.000000 .000030 .000030
37 38 39 80.0000 914525.81 -1.441376 .079653 20.000000 .000030 .000030

TIME 8.0000000E+01
V(R) 1.38836925E+04 G(R) -1.60029376E+00 L(R) 6.58255320E+01 ALT 9.25467048E+04 LAT 1.69127035E+01 LON 2.84242341E+01
U(I) 5.66338413E+03 V(I) 1.41280452E+04 W(I) 3.87722660E+02 PSI 7.74209018E+01 THE 1.94219603E+01 PHI 2.48472847E+01
U(B) 1.26924924E+04 Y(B) -4.78055747E+02 W(B) 5.60615836E+03 SIG 2.34308855E+01 BEI 1.97324971E+00 ALF 2.38306109E+01
V(A) 0.0000000E+00 Z(P) 0.0000000E+00 V(T) 5.62850414E+03 X(Z) -4.87401043E+00 ETA 2.20607403E+01
R(M) 1.01728525E-03 R(I) 1.01728525E-03 R(O) 1.01728525E-03 R(H) 1.01728525E-03 R(C) 1.01728525E-03
P(M) -1.09490584E-03 Q(M) 4.46949424E-03 R(M) 1.01728525E-03 CX -1.63793344E-01 CY 2.01832228E-02 CZ -2.08512031E+02
D(P) 4.45810372E+03 M 1.40844332E+01 RHO 4.62562257E-05 C1 2.45175750E-01 C2 2.01832228E-02 C3 1.496689324E-01
E(0) 7.73819629E+01 E1 6.24517880E-02 E2 2.61156707E-01 E3 5.73672494E-01 LATC 1.668054335E+01 RE 3.13326526E+07
UW 0.
C 45 -1.0277545E-04 C103 2.87979531E-01 C104 5.41051790E-01 C
S(1) 6.806074E+00 S(2) 3.300555E-04 S(3) 4.771417E-04 S(4) 1.288265E+01 S(5) 7.332071E-07 S(6) 7.759604E-07
S(7) 4.093697E-02 S(8) 1.459723E-02 S(9) 2.853961E-03 S(46) 0.
COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)
4.632E+01
-5.890E-04 1.089E-07
-2.145E-04 -1.143E-07 2.277E-07
-1.505E-01 2.982E-03 -2.258E-03 1.660E+02
1.485E-06 7.328E-11 -2.544E-10 1.199E+06 5.376E-13
3.603E-06 8.456E-11 1.121E-10 -2.073E-06 -5.626E-14 6.021E-13
-8.365E-02 0. -1.157E-01 -2.752E-09 -2.992E-09 1.676E-03
-3.227E-02 1.228E-06 0. -1.933E-02 7.623E-10 -2.040E-09 5.704E-04 2.131E-04
-1.603E-02 4.278E-08 9.668E-08 2.819E-03 3.029E-10 9.979E-10 8.261E-05 3.089E-05 8.145E-04
4.763E-09 2.556E-09 3.913E-05 3.913E-05 3.947E-12 4.821E-12 1.661E-07 6.849E-08 1.723E-07 0.
3.251E-11 1.437E-10 4.702E-07 4.702E-07 3.462E-13 -5.573E-14 6.539E-12 8.623E-10 6.971E-11 0.
-4.287E-11 6.902E-11 -1.391E-08 -1.391E-08 -4.833E-14 4.377E-13 -1.059E-09 -8.475E-10 -4.561E-10 0.
CORRELATION MATRIX (CZ) TRANSPOSE
-2.405E-06 -1.702E-10 1.069E-10 2.505E-06 -3.881E-14 9.020E-14 8.502E-08 3.220E-08 3.723E-09 4.151E-12 1.328E-14 2.894E-14
-3.407E-06 -6.545E-10 1.878E-09 -3.313E-06 -7.820E-13 2.513E-13 -1.833E-08 5.619E-08 1.412E-09 -1.022E-11 -1.284E-13 4.060E-14
POINTS TYPE TIME COMP1 COMP2 COMP3 SIG1 SIG2 SIG3
40 41 42 81.0000 846245.26 .653569 .089040 20.000000 .000030 .000030
43 44 45 82.0000 858073.13 .661114 .086983 20.000000 .000030 .000030
46 47 48 82.0000 891213.20 -1.425722 .082282 20.000000 .000030 .000030
49 50 51 84.0000 868752.44 .085290 .085290 20.000000 .000030 .000030

TIME R 500000000E+01
 V(R) 1.2AA87472E+04 G(R) 3.56572674E-01 L(R) 6.71560707E+01 ALT 9.18874943E+04 LAT 1.69A57162E+01 LON 2.859870662E+01
 W(I) 4.98R02448E+03 V(I) -7.99619558E+01 PSI 1.787793574E+01 THE 2.16030459E+01 PHI 2.39315366E+01
 U(R) 1.17232323E+04 V(R) -5.09210095E+07 W(R) 5.23408451E+03 SIG 2.21462941E+01 RET -2.71179007E+00 ALF 2.40592889E+01
 YP 0. 9.9728523E-04 AX -1.28680039E+02 AY 1.8263956E+01 AZ -1.87312083E+02
 P -1.27096441E-03 O 7.93022881E-03 R 8.01514722E-03 RM 9.95728523E-04 CX -1.64665135E-01 CY 2.33770624E-02 CZ -2.39699465E-01
 PH -1.27096441E-03 OM 8.01514722E-03 RH 4.30187285E+01 RHO 4.77989548E-05 C1 -2.48078837E-01 C2 2.33770624E-02 C3 1.51739993E-01
 DP 3.94557200E+03 M 1.30187285E+01 RHO 4.77989548E-05 C1 -2.48078837E-01 C2 2.33770624E-02 C3 1.51739993E-01
 FW 7.67306422E-01 F1 4.05479111E-02 F2 2.71491173E-01 E3 5.79559544E-01 LA1C 1.68780381E+01 RE 3.00299192E+07
 HW 0.
 C 46-R 49194054E-05 C103 2.87979609E-01 C104 5.41051854E-01 C1 3) 5.0348955E-04 S1 4) 1.800481E+01 S1 5) 1.286662E-06 S1 6) 1.182860E-06
 S1 7) 3.450444E-02 S1 8) 1.153834E-02 S1 9) 2.241204E-03 S1 46) 0. S1(103) 0.
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY
 4.543E+01
 1.794E-04 1.165E-07
 -1.245E-03 -1.136E-07 2.536E-07
 5.300E+00 5.166E-03 -5.670E-03 3.242E+02
 4.500E-06 2.064E-10 -5.534E-10 8.552E-06 1.456E-12
 6.030E-06 7.612E-11 6.074E-11 4.132E-06 1.741E-13 1.399E-12
 -1.013E-01 0.
 -3.258E-01 -1.463E-03 -8.065E-09 1.191E-03
 -3.262E-02 -2.597E-06 0.
 -9.048E-02 -2.094E-09 -3.323E-09 3.909E-04 1.331E-04
 -1.132E-02 -1.934E-07 4.504E-07 -6.162E-03 -1.143E-09 -1.43E-09 5.128E-05 1.709E-05 5.023E-04
 -1.584E-08 5.073E-09 3.868E-04 3.868E-04 -3.211E-11 -4.638E-11 -5.719E-07 -2.107E-07 2.535E-07 0.
 1.248E-11 -1.378E-10 1.330E-06 1.330E-06 5.782E-13 -2.665E-14 -9.795E-10 1.214E-10 -1.404E-10 0.
 -1.178E-11 2.827E-11 1.023E-06 -1.023E-06 -1.743E-14 5.240E-13 -1.516E-09 -6.190E-10 -2.390E-10 0.
 CORRELATION MATRIX (CUT) TRANSPOSE
 -4.674E-06 -4.841E-10 3.943E-10 -1.413E-05 -5.152E-13 -3.370E-13 1.159E-07 4.375E-08 4.608E-09 -1.703E-11 -3.266E-14 -5.133E-14
 -8.273E-06 -1.504E-09 5.207E-09 -2.339E-05 -6.240E-12 1.696E-12 -6.365E-08 -9.993E-08 -3.572E-09 -2.294E-11 -6.500E-13 7.410E-15

POINTS	TYPE	TIME	COMPI	COMP2	COMP3	SIG1	SIG2	SIG3
52	53	54	2	86.0000	847113.19	0.088741	0.000000	0.000030
55	56	57	2	88.0000	826256.65	-1.378174	20.060000	0.000030

TIME 9.00000000E+01
 V(R) 1.19954237E+04 G(R) 2.66815112E+00 L(R) 6.03780005E+01 ALT 9.32692875E+04 LAT 1.70498580E+01 LON 2.87620795E+01
 W(I) 4.40248317E+03 V(I) 1.25778101E+04 W(I) -4.31449824E+02 PSI 8.01089906E+01 THE 2.371172370E+01 PHI 2.35771291E+01
 U(R) 1.08836235E+04 V(R) -5.02356181E+02 W(R) 4.92204576E+03 SIG 2.14226721E+01 BET 2.40822620E+00 ALF 2.43345424E+01
 YP 0. 9.9728523E-04 AX -1.28680039E+02 AY 1.8263956E+01 AZ -1.87312083E+02
 P -1.0626441E-03 O 6.71335984E-03 R 9.56333835E-04 CX -1.04926882E+02 AY 1.57921351E+01 AZ -1.54454736E+02
 PH -1.40626441E-03 OM 6.75272832E-03 RM 9.59339335E-04 CX -1.65981227E-01 CY 2.8911850E-02 CZ -2.44320105E-01
 DP 3.18930794E+03 M 1.20763478E+01 RHO 4.46268781E-05 C1 8.019E-10 6.185E-10 6.185E-10 6.185E-10 6.185E-10 6.185E-10
 FW 7.60313690E-01 E1 2.35892890E-02 E2 2.82641664E-01 E3 5.64363181E-01 LA1C 1.69418189E+01 RE 2.596882438E+07
 HW 0.
 C 46-3 93684637E-05 C103 2.87979615E-01 C104 5.41051857E-01 C1 3) 5.0348955E-04 S1 4) 1.800481E+01 S1 5) 1.286662E-06 S1 6) 1.182860E-06
 S1 7) 3.450444E-02 S1 8) 1.153834E-02 S1 9) 2.241204E-03 S1 46) 0. S1(103) 0.
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY
 4.294E+01
 -1.985E-05 1.188E-07
 -1.159E-03 -1.178E-07 2.083E-07
 6.822E+00 6.451E-03 -6.811E-03 4.808E+02
 9.972E-06 2.024E-10 -6.362E-10 1.315E-05 2.910E-12
 7.282E-06 -6.841E-11 -7.031E-12 -3.621E-06 4.863E-13 2.225E-12
 -4.454E-02 0.
 -3.893E-01 -1.189E-03 -5.486E-09 6.867E-04
 -1.139E-02 -2.385E-06 0.
 -1.176E-01 -2.453E-09 -2.049E-09 2.247E-05 7.586E-05
 -1.79E-08 1.190E-09 9.588E-04 9.588E-04 -1.217E-09 -1.612E-09 1.890E-05 6.124E-06 3.825E-04
 2.664E-08 1.190E-09 9.588E-04 9.588E-04 -4.986E-11 -8.796E-11 -9.120E-07 -3.126E-07 2.755E-07 0.
 9.829E-12 1.279E-10 9.246E-07 9.246E-07 9.4135E-13 2.454E-14 9.819E-10 6.185E-10 6.185E-10 6.185E-10 6.185E-10
 1.193E-11 1.279E-10 9.246E-07 9.246E-07 1.523E-07 1.523E-07 1.523E-07 1.523E-07 1.523E-07 1.523E-07 1.523E-07
 CORRELATION MATRIX (CUT) TRANSPOSE
 -4.651E-06 -7.411E-10 5.259E-10 -2.669E-05 -6.480E-13 -4.007E-13 1.376E-07 5.301E-08 4.996E-09 -2.850E-11 6.562E-14 -4.483E-14
 -6.933E-06 -1.867E-09 8.239E-09 -1.603E-05 -1.240E-11 4.332E-12 -1.361E-07 -1.497E-07 -6.644E-09 -2.112E-11 -1.392E-13 -2.952E-13

*****BEGIN BACKWARDS SHOOTING*****

TIME 9.0000000E+01
 V(R) 1.19554237E+04 G(R) 2.06815112E+00 L(R) 6.83780005E+01 ALT 9.32692875E+04 LAT 1.70498551E+01 LON 2.87620795E+01
 U(I) 4.40248317E+03 V(I) 1.25727819E+04 W(I) -4.31449824E+02 PSI 8.01089906E+01 THE 2.37172370E+01 PHI 2.33571291E+01
 U(R) 1.088362235E+04 V(R) -5.02356181E+02 W(R) 4.92204576E+03 SIG 2.14226721E+01 BET -2.40822629E+00 ALF 2.43345424E+01
 XP 0.0
 P -1.40626441E+03 Q 6.71335986E+03 R 9.56333835E+04 AX -1.04922688E+02 AY 1.57921351E+01 AZ -1.54454736E+02
 PM -1.40826441E+03 QM 6.75272832E+03 RM 9.456333835E+04 CX -1.65981272E+01 CY 2.49811859E+02 CZ -2.444328108E+01
 DP 3.18930794E+03 M 1.20763478E+01 RHO 4.46268781E+05 C1 2.51913384E+01 C2 2.49811859E+02 C3 1.54225935E+01
 E0 7.60313690E+01 E1 2.35892890E+02 E2 2.82641664E+01 E3 5.84363181E+01 LATC 1.69418189E+01 RE 2.59682338E+07
 UW 0.0
 S(1) 6.552922E+00 S(2) 3.447435E+04 S(3) 4.563711E+03 S(4) 2.192707E+01 S(5) 1.705938E+06 S(6) 1.491527E+06
 S(7) 2.820497E+02 S(8) 8.709750E+03 S(9) 1.955745E+03 S(46) 0.0
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)
 4.294E+01
 -8.985E-05 1.188E-07
 -1.159E-03 -1.175E-07 2.083E-07
 6.822E+00 6.515E-03 6.811E-03 4.808E+02
 5.907E-06 2.8024E-10 6.362E-10 1.315E-05 2.910E-12
 7.282E-06 6.4861E-11 7.031E-12 -3.621E-06 4.863E-13 2.225E-12
 -4.456E-02 0.0 -3.893E-01 -1.189E-08 -5.486E-09 6.867E-04
 -1.329E-02 -2.385E+06 0.0 -1.176E-01 -2.453E-09 -2.048E-09 2.247E-04 7.586E-05
 -1.117E-02 -8.329E+09 3.167E-07 -2.636E-03 -1.217E-09 -1.612E-09 1.890E-05 6.124E-06 3.825E-04
 2.664E-08 1.190E+10 9.588E-04 9.588E-04 4.986E-11 -8.796E-11 -9.120E-07 -3.126E-07 2.735E-07 0.0
 9.632E-12 -1.279E+10 9.246E-07 9.246E-07 9.135E-13 2.455E-14 9.819E-10 6.185E-10 -6.777E-11 0.0
 1.191E-11 7.2747E-12 1.523F-07 1.523E-07 2.435E-14 6.842E-13 -1.456E-09 -4.826E-10 -8.534E-11 0.0
 CORRELATION MATRIX (CUZ) TRANSPOSE
 -4.651E-06 -7.411E-10 5.259E-10 2.869E-05 6.680E-13 -4.007E-13 1.376F-07 5.301E-08 4.996E-09 -2.850E-11 6.562E-14 -4.483E-14
 -8.993E-06 -1.867E-09 8.239E-09 -1.603E-05 -1.240E-11 4.332E-12 -1.361E-07 -1.497E-07 -6.644E-09 -2.112E-11 -1.392E-13 -2.952E-13

PNTS TYPE TIME WGT.REC1 RES2 WGT.REC2 WGT.REC3 LOSS FCIN
 54, 53, 52 86.000 8.61116E+00 2.2948E-05 -2.66269E-05 4.80858E-01 7.64943E-01 -8.87564E-01 1.56726E+00
 86.000 2.51242E+00 6.01273E-06 -2.07197E-05 1.25621E-01 2.00424E-01 -6.90657E-01 2.10022E+00

TIME 9.0000000E+01
 V(R) 1.28472466E+04 G(R) 3.58006627E-01 L(R) 6.71738030E+01 ALT 9.18954818E+04 LAT 1.69856578E+01 LON 2.85987195E+01
 U(I) 4.98382560E+03 V(I) 1.33071388E+04 W(I) -8.02741411E+01 PSI 7.88483700E+01 THE 2.17031346E+01 PHI 2.34676792E+01
 U(R) 1.17190580E+04 V(R) -5.461520723E+02 W(R) 5.23451228E+03 SIG 2.17211533E+01 BET -2.50505191E+00 ALF 2.40687220E+01
 XP 0.0
 P -1.27096643E-03 Q 7.97577875E-03 R 9.96728523E-04 AX -1.28658787E+02 AY 2.01413029E+01 AZ -1.87386647E+02
 PM -1.27096643E-03 QM 8.01514722E-03 RM 9.96728523E-04 CX -1.64778691E+01 CY 2.57499783E-02 CZ -2.39939670E-01
 DP 3.94309308E+03 M 1.30130111E+01 RHO 4.77400832E-05 C1 2.448307423E-01 C2 2.57499783E-02 C3 1.51876547E-01
 E0 7.67113067E-01 E1 3.72231288E-02 E2 2.69228703E-01 E3 5.81091978E-01 LATC 1.68779800E+01 RE 3.00137644E+07
 UW 0.0
 S(1) 3.186541E+00 S(2) 1.767405E-04 S(3) 2.4400212E-04 S(4) 1.007031E+01 S(5) 8.053660E-07 S(6) 7.548484E-07
 S(7) 2.591052E+02 S(8) 9.202198E+03 S(9) 1.494262E-03 S(46) 0.0
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)
 1.015E+01
 6.031E-06 3.124E-08
 -2.296E-04 -2.145E-08 5.761E-08
 2.197E-01 9.328E-04 -4.879E-04 1.014E+02
 8.783E-07 7.988E-12 -1.371E-10 1.615E-07 6.486E-13
 1.300E-06 3.493E-12 2.862E-11 -3.619E-07 -2.735E-14 5.698E-13
 -2.162E-02 0.0 -4.177E-02 2.699E-09 -2.909E-09 6.714E-04
 -6.995E-03 -1.064E-06 0.0 -1.243F-02 1.365E-09 -1.078E-09 2.358E-04 8.448E-05
 -3.266E-03 -8.000E-07 7.837E-08 -7.836F-04 1.466E-11 -1.667E-10 2.617E-05 9.173E-06 2.233E-04
 8.152E-09 -2.845E-09 -3.738E-05 -3.738E-05 -8.469E-13 2.107E-11 -9.028E-07 -3.526E-07 1.328E-07 0.0
 9.951E-12 -1.062E-10 2.032E-07 2.032E-07 5.185E-13 -2.938E-14 9.618E-10 6.687E-10 -5.106E-11 0.0
 1.513E-12 1.929E-11 -3.536F-07 -3.536E-07 -2.595E-07 2.595E-07 1.439E-09 -5.157E-10 -1.236E-10 0.0
 CORRELATION MATRIX (CUZ) TRANSPOSE
 -8.058F-07 -1.999E-10 -6.729E-12 -3.093E-07 1.893E-13 -8.682E-14 9.055E-08 3.547E-08 3.646E-09 -2.850E-11 6.562E-14 -4.483E-14
 -8.075E-07 3.813E-11 2.001E-09 3.505E-05 1.077E-12 -5.946E-13 -1.525E-07 -1.152E-07 -7.449E-09 -2.112E-11 -1.392E-13 -2.952E-13

POINTS TYPE TIME RES1 RES2 RES3 WGT.REC2 WGT.RES3 LOSS.FCTN
 51, 50, 49 2 86.000 -1.11081E+00 -4.93179E-06 -1.31905E-05 -5.55840E-02 -1.64393E-01 -4.39682E-01 2.32365E+00
 4R, 47, 46 2 82.000 -3.15169E+00 -1.02173E-05 -4.68689E-06 -2.45758E-01 -3.40571E-01 -1.56230E-01 2.48889E+00
 45, 44, 43 1 82.000 -4.92528E+00 -3.05394E-07 -4.59258E-06 -2.44626E-01 -1.61799E-02 -1.53086E-01 2.57307E+00
 42, 41, 40 1 81.000 -4.46644E+00 1.42205E-06 -2.28316E-07 -2.23232E-01 -4.74017E-02 -7.61052E-03 2.62525E+00
 39, 38, 37 2 80.000 -4.56577E+00 -1.06611E-05 3.96539E-06 -2.27287E-01 -3.55368E-01 -1.32180E-01 2.82067E+00
 36, 35, 34 1 80.000 -3.19663E+00 7.55063E-06 4.18142E-06 -1.45932E-01 8.50211E-02 1.39381E-01 2.87287E+00

TIME R.00000000E+01
 (V(R) 1.38827931E+04 G(R) 1.58868337E+00 L(R) 6.58464283E+01 ALT 9.25656539E+04 LAT 1.69126709E+01 LON 2.84242584E+01
 U(T) 5.67843029E+03 V(T) 1.4129398E+04 W(T) 3.86488937E+02 PSI 7.74884300E+01 THE 1.94402355E+01 PHI 2.33182576E+01
 U(B) 1.26889643E+04 YP (R) 6.37336577E+02 W(F) 5.45960640E+03 Z(I) 5.63224025E+03 X(Z) -6.44974288E+00 ETA 2.20823630E+01
 XP 0.0
 S.426112495E-03 R 1.01728525E-03 AX -1.44444596E+02 AY 2.37001913E+01 AZ -2.07771837E+02
 PM -1.09490564E-03 QM 8.46549342E-03 RM 1.01728525E-03 CX -1.63894121E-01 CY 2.68905034E-02 CZ -2.35740259E-01
 DP 4.45333027E+03 M 1.40429897E+01 PHO 4.62126663E-05 C1 2.65084086E-01 C2 2.68905034E-02 C3 1.49561178E-01
 E0 7.74243329E-01 E1 5.18706093E-02 E2 2.53627120E-01 E3 5.77520823E-01 LATC 1.68054011E+01 RE 3.12991604E+07
 UW 0.0
 S(1) 2.047869E+00 S(2) 9.251443E-05 S(3) 1.815181E-04 S(4) 7.039200E+00 S(5) 4.096122E-07 S(6) 4.495324E-07
 S(7) 2.556625E-02 S(8) 9.891964E-03 S(9) 1.413456E-03 S(46) 0.
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY
 4.194E+00
 -2.191E-05 8.559E-07
 -1.278E-04 4.197E-09 3.295E-08
 8.881E-01 1.812E-04 9.247E-05 4.955E+01
 1.018E-07 3.161E-12 1.863E-11 4.234E-06 1.478E-13
 2.994E-07 3.493E-12 1.472E-11 3.852E-07 2.965E-14 2.021E-10
 1.762E-02 0.0 4.462E-02 5.926E-10 3.708E-10 6.536E-04
 7.024E-03 2.278E-07 0.0 1.442E-02 3.230E-10 5.081E-11 2.504E-04 9.785E-05
 5.357E-04 3.306E-08 1.4563E-07 2.058E-03 2.382E-11 4.170E-11 3.329E-05 1.2881E-05 1.998E-06
 -4.012E-09 4.032E-09 1.093E-04 1.093E-04 7.236E-12 1.212E-11 8.903E-07 3.596E-07 1.405E-08 0.
 6.333E-12 7.593E-11 3.349E-07 3.349E-07 1.964E-13 4.162E-14 9.359E-10 7.319E-10 3.401E-11 0.
 -4.401E-12 2.830E-11 1.780E-07 1.780E-07 -3.094E-14 2.218E-13 1.418E-09 5.591E-10 1.652E-10 0.
 CORRELATION MATRIX (CUZ) TRANSPOSE
 2.523E-06 1.236E-10 2.763E-10 7.782E-07 3.630E-13 5.830E-14 4.383E-08 1.727E-08 2.024E-09 2.850E-11 6.562E-14 4.483E-14
 -4.960E-06 6.066E-10 6.446E-10 4.135E-06 2.157E-12 5.896E-13 1.692E-07 7.811E-08 8.789E-09 2.112E-11 1.392E-11 2.952E-13

POINTS TYPE TIME RES1 RES2 RES3 WGT.REC2 WGT.RES3 LOSS.FCTN
 33, 32, 31 1 79.000 -1.16035E+00 3.22292E-06 8.49005E-06 -5.80173E-02 -1.07431E-01 2.83002E-01 2.96787E+00
 30, 29, 28 2 78.000 -6.19738E+00 -7.37602E-06 1.18344E-05 -3.09269E-01 -2.445867E-01 3.94492E-01 3.27999E+00
 27, 26, 25 1 78.000 1.58505E+00 3.60155E-06 1.25344E-05 7.92527E-02 1.20052E-01 4.17819E-01 3.47523E+00
 24, 23, 22 1 77.000 4.96830E+00 3.86681E-06 1.61388E-05 2.48415E-01 1.28894E-01 5.37960E-01 3.84295E+00
 21, 20, 19 1 76.000 8.90346E+00 4.21347E-06 1.91174E-05 4.45173E-01 1.40449E-01 6.37248E-01 4.46694E+00
 18, 17, 16 1 75.000 1.32897E+01 4.84690E-06 2.12810E-05 6.64487E-01 1.61563E-01 7.09367E-01 5.43779E+00

TIME R.50000000E+01
 (V(R) 1.49620564E+04 G(R) -3.50931506E+00 L(R) 6.45270147E+01 ALT 9.57506942E+04 LAT 1.68297235E+01 LON 2.82280703E+01
 U(T) 6.42289484E+03 V(T) 1.49499584E+04 W(T) 9.15839650E+02 PSI 7.61662630E+01 THE 1.71041290E+01 PHI 2.31785239E+01
 U(B) 1.37024886E+04 YP (R) -7.23500048E+02 W(F) 5.896502176E+03 Z(I) 5.496502176E+03 X(Z) -6.9116555E+00 ALF 2.35246470E+01
 XP 0.0
 S.426114978E-04 R 7.69522527E-03 R 9.882154965E-04 AX -1.463094206E-01 AY 2.45761403E+01 AZ -2.02428760E+02
 PM -9.42614978E-04 QM 7.73459373E-03 RM 9.882154965E-04 CX -1.63094206E-01 CY 2.81164473E-02 CZ -2.31589565E-01
 DP 4.41994124E+03 M 1.50399447E+01 PHO 3.94878889E-05 C1 2.41976679E-01 C2 2.81164473E-02 C3 1.47243821E-01
 E0 7.80928947E-01 E1 6.60275258E-02 E2 2.37783293E-01 E3 5.73802825E-01 LATC 1.67229182E+01 RE 2.85227348E+07
 UW 0.0
 S(1) 3.744827E+00 S(2) 1.340256E-04 S(3) 2.379396E-04 S(4) 7.285943E+00 S(5) 8.890707E-07 S(6) 3.943657E-07
 S(7) 2.521082E-02 S(8) 1.068616E-02 S(9) 1.842794E-03 S(46) 0.
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY

1.402E+01
 3.002E-04 1.796E-08
 -6.631E-04 -2.258E-08 5.662E-08
 -9.842E-00 -3.92E-04 4.251E-04 5.308E+01
 -2.543E-06 -7.351E-11 1.553E-10 2.019E+06 6.857E-13
 -6.281E-07 -2.079E-11 4.141E-11 1.667E-07 1.437E-13 1.555E-13
 8.363E-02 0. -6.582E-02 1.915E-08 4.79E-09 6.356E-04
 3.535E-02 1.018E-06 0. -3.076E-02 6.213E-09 1.948E-09 2.663E-04 1.142E-04
 5.737E-03 1.516E-07 -3.221E-07 -5.235E-03 -1.152E-09 -1.739E-10 4.077E-05 1.726E-05 3.396E-04
 -3.677E-09 5.946E-09 2.686E-04 2.686E-04 1.434E-11 -1.375E-11 -8.764E-07 -3.899E-07 -1.726E-07 0.
 -1.057E-12 3.860E-11 -4.702E-07 -4.702E-07 -1.537E-14 3.001E-14 9.067E-10 8.014E-10 -1.641E-11 0.
 -2.829E-12 3.328E-11 2.333E-07 2.333E-07 1.728E-14 6.438E-14 -1.395E-09 -6.073E-10 -2.121E-10 0.
 CORRELATION MATRIX (CUZ) TRANSPOSE
 4.995E-06 2.028E-10 4.410E-10 1.147E-05 -1.829E-12 -3.886E-13 -2.295E-09 -2.194E-09 1.389E-10 -2.850E-11 6.562E-14 -4.483E-14
 -2.490E-05 -4.975E-10 1.193E-09 -1.227E-05 3.186E-12 2.518E-12 -1.873E-07 -3.660E-08 -1.066E-08 -2.112E-11 -1.392E-13 -2.952E-13

POINTS TYPE TIME RES1 RES2 RES3 MGT.RES1 MGT.RES2 MGT.RES3 LOSS FCN
 15, 14, 1 74.000 1.80118E+01 5.97803E-06 2.24414E-05 9.00589E-01 1.99288E-01 7.48046E-01 6.84814E+00
 12, 11, 10 73.000 2.29408E+01 7.82160E-06 2.24174E-05 1.14704E+00 2.60720E-01 7.47246E-01 8.79018E+00
 9, 8, 7 72.000 2.79360E+01 1.05855E-05 2.10403E-05 1.39680E+00 3.52849E-01 7.01343E-01 1.13578E+01
 6, 5, 4 71.000 3.28470E+01 1.64720E-05 1.81588E-05 1.64235E+00 4.82400E-01 6.05294E-01 1.46540E+01
 3, 2, 1 70.000 3.75168E+01 1.96710E-05 1.36433E-05 1.87584E+00 6.55699E-01 4.54777E-01 1.88096E+01

TIME 7.00000000E+01
 U(R) 1.593297314E+04 G(R) -5.12193481E+00 L(R) 6.33688559E+01 ALT 1.01564920E+05 LAT 1.67368207E+01 LON 2.80410136E+01
 U(I) 7.11637590E+03 V(I) 1.56606403E+04 W(I) 1.42302923E+03 PSI 7.50264493E+01 THE 1.525544851E+01 PHI 2.30996772E+01
 U(B) 1.46262669E+04 V(B) -8.07034828E+02 W(B) 6.28458815E+03 SIG 2.26472466E+01 BET -2.90214852E+00 ALF 2.32521428E+01
 XP 0. -8.75453184E-04 YP 0. -9.609572E-04 AX -1.21334273E+02 AY 2.18520195E+01 AZ -1.70094573E+02
 P -8.75453184E-04 Q 6.00554706E-03 R 8.82155972E-04 CX -1.62262032E+01 CY 2.92227180E-02 CZ -2.27467569E+01
 PM -8.75453184E-04 OM 6.04491552E-03 RH 8.82155972E-04 CX -1.62262032E+01 CY 2.92227180E-02 CZ -2.27467569E+01
 DP 3.78412316E+03 M 1.58403752E+01 RHO 2.97874455E-05 CI 2.38880268E-01 C2 2.92227180E-02 C3 1.44934976E-01
 EP 7.86457630E-01 EI 7.82195103E-02 E2 2.24000367E-01 E3 5.70254276E-01 LATC 1.66305368E+01 RE 2.24965894E+07
 UW 0.
 S(1) 8.670439E+00 S(2) 1.820709E-04 S(3) 3.083126E-04 S(4) 1.431983E+01 S(5) 2.099586E-06 S(6) 1.207621E-06
 S(7) 2.490332E-02 S(8) 1.144140E-02 S(9) 2.606191E-03 S(46) 0.
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY
 7.618E*01
 2.820E-04 3.315E-08
 -1.568E-03 -3.792E-08 9.506E-08
 -4.768E+01 -2.095E-03 2.421E-03 2.051E+02
 -1.522E-05 -2.198E-10 5.204E-10 1.826E-05 4.408E-12
 -9.391E-06 -5.010E-11 1.5554E-10 6.848E-06 1.993E-12 1.458E-12
 1.752E-01 0. -2.2241E-01 -4.997E-08 -2.474E-08 6.202E-04
 7.957E-02 1.000E-06 0. -9.6095E-02 -2.205E-08 -1.159E-08 2.805E-04 1.309E-04
 2.153E-02 4.123E-08 -4.245E-07 -1.194E-02 4.138E-09 -2.483E-09 4.870E-05 2.238E-05 6.792E-06
 9.504E-09 9.401E-09 -6.632E-05 -6.632E-05 8.421E-11 6.859E-11 -8.640E-07 -4.181E-07 -3.428E-07 0.
 -1.015E-11 5.171E-13 -8.492E-09 -8.492E-09 -8.421E-11 6.859E-11 -8.640E-07 -4.181E-07 -3.428E-07 0.
 5.360E-12 3.451E-11 1.366E-07 1.366E-07 1.354E-13 1.806E-14 -1.375E-09 -6.521E-10 -2.624E-10 0.
 CORRELATION MATRIX (CUZ) TRANSPOSE
 7.232E-06 1.219E-10 -5.978E-10 -2.221E-05 -4.136E-12 -9.635E-13 -4.787E-08 -2.289E-08 -2.011E-09 -2.850E-11 6.562E-14 -4.483E-14
 6.720E-05 -2.872E-09 7.083E-09 9.597E-05 2.880E-11 6.144E-12 -2.071E-07 9.780E-09 -1.318E-08 -2.112E-11 -1.392E-13 -2.952E-13

CONTROLS ARE SPECIFIED FOR
 *FILTERING RUN FROM TIME IO= 70.0000 TO FINAL= 90.0000
 *UPDATED REFERENCE
 *SMOOTH COVARIANCE, CALCULATE RESIDUALS AND LOSS FUNCTION
 *FILTER FOR 1 ITERATIONS
 *VECTOR PROCESS FITTING DATA TRIPLES
 *INPUT AND OUTPUT IN ENGLISH UNITS (FT, FT/SEC, FT/SEC², LR, SLUG)
 *PLANET PARAMETERS

EQUIT, RAD. = 2.09264300E+07 POLAR RAD. = 2.08559700E+07 ROTATION = 7.29211500E-05
 MU(GRAV.) = 1.40769000E+16 J2(GRAV.) = 1.09205500E+03
 *INITIAL STATE ESTIMATE IS
 VELOCITY = 1.60012000E+04 GAMMA = -6.75088000E+00 LAMBDA = 6.30352000E+01
 ALTITUDE = 1.00584000E+05 GEOD-LAT. = 1.67583977E+01 LONGITUDE = 2.80418380E+01
 SIGMA = 2.98270000E+01 BETA = -0.43200000E+00 ALPHA = 1.93930000E+01
 *FITTING DATA IS FROM 2 SOURCES
 1. TRACKING STATION 1, GEOD.LAT. = 15.096904 LONGITUDE = 27.000000 ALTITUDE = 0. ABOVE REF. SURFACE
 2. TRACKING STATION 2, GEOD.LAT. = 16.605545 LONGITUDE = 31.000000 ALTITUDE = 0. ABOVE REF. SURFACE

STATE VECTOR COMPONENTS

COMP.	ID, NU.	EST. VALUE	VARIANCE
1	1	7.20532863E+03	6.79079215E+04
2	2	1.56313582E+04	2.80981835E+04
3	3	1.88098346E+03	3.09451057E+05
4	4	9.4712173E+04	1.00000000E+06
5	5	2.90632098E-01	9.00000000E-08
6	6	4.89422401E-01	9.00000000E-08
7	7	7.69645202E-01	2.08169635E-04
8	8	1.55940474E-01	7.90725687E-04
9	9	3.98732405E-01	8.18646927E-04
10	10	5.82889025E-01	2.80457751E-04

MODEL PARAMETERS IN EXPANDED STATE VECTOR

11	11	9.22000000E-02	4.00000000E-02
12	12	2.87979327E-01	1.40625000E-07
13	13	5.41052068E-01	1.40625000E-07

RANDOM MODEL PARAMETERS NOT BEING ESTIMATED (U-VECTOR)

1	70	0.	4.00000000E-02
2	71	0.	4.00000000E-02

RANDOM MEASUREMENT PARAMETERS NOT BEING ESTIMATED (V-VECTOR)

1	76	1.00000000E+00	9.00000000E-10
2	81	0.	9.00000000E-10

ITERATION NUMBER 1

TIME 7.00000000E+01
 V(A) 1.60012000E+04 G(A) -6.75088000E+00 L(A) 6.30352000E+01 ALI 1.00584000E+05 LATD 1.67583977E+01 LON 2.80418380E+01
 V(I) 7.20532630E+03 V(I) 1.56913582E+04 W(I) 1.85098346E+03 PSI 7.63702516E+01 THE 8.01936612E+00 PHI 2.92188575E+01
 U(B) 1.50482107E+04 V(B) -1.23650674E+03 W(B) 5.29724514E+03 SIG 2.98270000E+01 BET -4.43200000E+00 ALF 1.93930000E+01
 XP 0.0 YP 0.0 ZP 0.0
 P -8.75453186E-04 Q 6.04491552E-03 R 8.82155972E-04 AX -1.21200856E+02 AY 7.53823858E+00 AZ -1.72113726E+02
 PM -8.75453186E-04 QM 6.04491552E-03 RM 8.82155972E-04 AXM -1.21200856E+02 AYM 7.53823858E+00 AZM -1.72113726E+02
 E0 7.69645202E-01 EI 1.55940474E-01 E2 2.08732405E-01 E3 5.828889025E-01 LATC 1.66519926E+01 A(T) 2.10640913E+02
 C 72 9.42200000E-02 C103 2.87979372E-01 C104 5.41052068E-01 C
 S(1) 1.000000E+02 S(2) 3.500000E-02 S(3) 1.800000E-02 S(4) 1.000000E+03 S(5) 3.000000E-04 S(6) 3.000000E-04
 S(7) 5.300000E-02 S(8) 3.500000E-02 S(9) 5.300000E-02 S(10) 3.750000E-04 S(104) 3.750000E-04
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)
 1.000E+04
 -4.885E-14 1.225E-03
 -1.325E-14 0.0 3.240E-04
 -2.274E-13 0.0 0.0 1.000E+06
 0.0 0.0 0.0 0.0
 0.0 0.0 0.0 0.0 9.000E-08 9.000E-08
 8.809E-15 0.0 0.0 0.0 0.0 0.0 2.809E-03
 3.986E-15 -1.561E-17 0.0 0.0 0.0 0.0 1.475E-17 1.225E-03
 7.855E-15 -1.171E-17 -1.301E-18 0.0 0.0 0.0 4.510E-17 -5.204E-18 2.809E-03
 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 4.000E-02
 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 1.406E-07
 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0
 CORRELATION MATRIX (CVZ) TRANSPOSE
 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0
 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0
 CORRELATION MATRIX (CVZ) TRANSPOSE
 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0
 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0

POINTS	TYPE	TIME	COMPI	COMPI2	COMPI3	SIG1	SIG2	SIG3
1, 2, 3	1	70.0000	714184.53	543024	.124359	20.000000	.000030	.000030
4, 5, 6	1	71.0000	720629.03	560073	.121768	20.000000	.000030	.000030
7, 8, 9	1	72.0000	73667.87	571218	.117803	20.000000	.000030	.000030
10, 11, 12	1	73.0000	746636.75	581913	.113572	20.000000	.000030	.000030
13, 14, 15	1	74.0000	759519.00	592172	.109626	20.000000	.000030	.000030
16, 17, 18	1	75.0000	772294.05	602013	.105952	20.000000	.000030	.000030

TIME 7.50000000E+01
 V(A) 1.49754064E+04 G(A) -3.44307998E+00 L(A) 6.45442767E+01 ALI 9.57405774E+04 LATD 1.68297058E+01 LON 2.82380568E+01
 V(I) 6.42501306E+03 V(I) 1.49848714E+04 W(I) 8.99376795E+02 PSI 7.86629984E+01 THE 1.30357921E+01 PHI 3.09555216E+01
 U(B) 1.39205091E+04 V(B) -9.94830937E+02 W(B) 5.43073466E+03 SIG 3.04737058E+01 BET -3.80825304E+00 ALF 2.13120036E+01
 XP -1.00000000E+00 YP 0.0 ZP 0.0
 P -9.42614978E-04 Q 7.73859373E-03 R 9.82154065E-04 AX -1.42491976E+02 AY 8.87341034E+00 AZ -2.04646052E+02
 PM -9.42614978E-04 QM 7.73859373E-03 RM 9.82154065E-04 AXM -1.42491976E+02 AYM 8.87341034E+00 AZM -2.04646052E+02
 E0 7.59820572E-01 EI 1.35757782E-01 E2 2.52652023E-01 E3 5.83446209E-01 LATC 1.67229007E+01 A(T) 4.82360201E-02
 C 72 9.36035097E-02 C103 2.87979372E-01 C104 5.41052068E-01 C
 S(1) 1.002884E+02 S(2) 9.443782E-04 S(3) 1.0478044E-03 S(4) 2.965420E+01 S(5) 1.219798E-06 S(6) 1.116628E-09
 S(7) 4.249156E+02 S(8) 3.040992E-02 S(9) 2.732858E-02 S(10) 3.750000E-04 S(104) 3.750000E-04
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)
 1.130E+02
 6.880E-03 8.919E-07

POINTS	TYPE	TIME	COMPL	COMP2	COMP3	SIG1	SIG2	SIG3
19	20	21	1	76.0000	784951.02	611460	.000030	.000030
22	23	24	1	77.0000	797484.21	.620538	.000030	.000030
25	26	27	1	78.0000	809886.84	.629272	.000030	.000030
28	29	30	2	78.0000	938702.81	-1.456939	20.000000	20.000000
31	32	33	1	79.0000	822150.95	.637681	20.000000	20.000000
34	35	36	1	80.0000	834275.20	.645785	20.000000	20.000000
37	38	39	2	80.0000	914516.24	-1.441382	20.000000	20.000000

COORDINATION MATRIX (CVZ) TRANSPOSE

POINTS	TYPE	TIME	COMPL	COMP2	COMP3	SIG1	SIG2	SIG3				
5	998E-02	1.506E-06	3.366E-07	1.774E-02	8.735E-10	1.590E-09	3.962E-07	8.394E-06	1.135E-04	1.233E-05	0.	0.
-3	542E-03	9.435E-07	1.932E-06	-1.005E-02	9.453E-10	3.219E-10	-1.067E-04	6.311E-05	-6.671E-06	1.242E-06	0.	0.

CORRELATION MATRIX (CVZ) TRANSPOSE

POINTS	TYPE	TIME	COMPL	COMP2	COMP3	SIG1	SIG2	SIG3				
-1	335E-05	7.485E-11	4.611E-11	9.832E-05	-2.587E-11	1.951E-11	2.496E-09	1.758E-09	-1.466E-10	-5.361E-10	0.	0.
-3	693E-07	8.119E-10	7.776E-11	6.879E-04	3.787E-12	2.784E-12	1.007E-09	8.710E-10	2.730E-09	4.320E-10	0.	0.

COORDINATION MATRIX (CVZ) TRANSPOSE

POINTS	TYPE	TIME	COMPL	COMP2	COMP3	SIG1	SIG2	SIG3				
6	119E-01	1.289E-02	9.150E-04	8.794E+02	0.	0.	0.	0.	1.406E-07	1.406E-07	0.	0.
7	726E-07	1.283E-10	5.545E-10	1.039E-06	1.488E-12	0.	0.	0.	0.	0.	0.	0.
6	977E-06	2.203E-10	4.622E-10	1.731E-06	4.334E-13	1.247E-12	0.	0.	0.	0.	0.	0.
2	500E-03	0.	0.	-1.035E-01	8.533E-09	4.112E-09	1.806E-03	0.	0.	0.	0.	0.
-1	401E-02	8.676E-06	0.	-8.749E-02	6.079E-09	2.289E-09	-3.996E-04	9.248E-04	0.	0.	0.	0.
-2	564E-01	2.001E-05	1.302E-05	1.951E-01	2.077E-09	1.200E-08	1.779E-05	5.497E-04	7.469E-04	0.	0.	0.
-3	925E-06	1.716E-06	4.415E-02	1.470E-09	1.180E-09	6.893E-06	3.548E-09	-6.074E-05	3.997E-02	0.	0.	0.
0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.

CORRELATION MATRIX (CVZ) TRANSPOSE

POINTS	TYPE	TIME	COMPL	COMP2	COMP3	SIG1	SIG2	SIG3
19	20	21	1	76.0000	784951.02	611460	.000030	.000030
22	23	24	1	77.0000	797484.21	.620538	.000030	.000030
25	26	27	1	78.0000	809886.84	.629272	.000030	.000030
28	29	30	2	78.0000	938702.81	-1.456939	20.000000	20.000000
31	32	33	1	79.0000	822150.95	.637681	20.000000	20.000000
34	35	36	1	80.0000	834275.20	.645785	20.000000	20.000000
37	38	39	2	80.0000	914516.24	-1.441382	20.000000	20.000000

CORRELATION MATRIX (CVZ) TRANSPOSE

POINTS	TYPE	TIME	COMPL	COMP2	COMP3	SIG1	SIG2	SIG3				
9	099E-04	3.623E-08	2.871E+07	0.	0.	0.	0.	0.	2.842+2587E+01	2.842+2587E+01	0.	0.
-2	23E-01	4.714E-03	5.926E-04	3.390E+02	0.	0.	0.	0.	3.15467356E+01	3.15467356E+01	0.	0.
3	605E-07	7.410E-11	2.858E-10	1.069E-06	1.418E-12	0.	0.	0.	2.35428038E+01	2.35428038E+01	0.	0.
2	892E-06	9.944E-11	2.137E-10	1.364E-06	5.413E-13	1.153E-12	0.	0.	2.19901799E+01	2.19901799E+01	0.	0.
1	757E-03	0.	0.	-7.971E-03	-1.216E-09	6.232E-10	1.387E-03	0.	-2.09648954E+02	-2.09648954E+02	0.	0.
-3	540E-03	-2.497E-06	0.	-2.949E-02	-2.409E-09	8.314E-10	-9.353E-04	6.889E-04	0.	0.	0.	0.
-2	633E-02	2.524E-06	1.454E-06	3.890E-02	5.965E-10	2.145E-09	2.520E-05	1.444E-05	4.143E-05	3.946E-02	0.	0.
-7	724E-06	-2.848E-06	1.273E-01	-1.273E-01	5.668E-09	6.045E-09	1.221E-05	2.549E-06	-6.375E-05	3.946E-02	0.	0.
3	172E-11	1.637E-10	4.611E-07	6.11E-07	1.270E-12	5.972E-13	1.018E-09	-9.085E-10	3.381E-10	2.570E-09	2.045E-12	0.
3	964E-11	1.129E-10	2.673E-07	6.73E-07	6.061E-13	9.907E-13	4.922E-10	2.724E-10	-1.092E-09	2.706E-09	6.898E-13	1.401E-12

CORRELATION MATRIX (CVZ) TRANSPOSE

POINTS	TYPE	TIME	COMPL	COMP2	COMP3	SIG1	SIG2	SIG3				
6	08E-05	5.645E-06	1.839E-06	1.94E-02	3.832E-09	4.252E-09	9.956E-07	1.342E-05	1.504E-04	3.691E-04	1.745E-09	1.941E-09
-5	186E-03	2.998E-07	1.574E-07	4.42E-03	3.633E-10	-2.062E-10	-1.470E-04	0.300E-05	7.630E-06	2.396E-05	-2.049E-10	7.027E-11

CORRELATION MATRIX (CVZ) TRANSPOSE

POINTS	TYPE	TIME	COMPL	COMP2	COMP3	SIG1	SIG2	SIG3				
-1	237E-05	6.218E-11	1.529E-10	3.481E-05	-2.827E-11	2.235E-11	9.172E-10	1.250E-09	-1.059E-09	6.508E-09	-2.799E-11	-2.210E-11
-2	583E-06	5.934E-10	1.359E-10	2.855E-04	3.331E-12	2.636E-12	3.208E-10	4.447E-09	4.482E-09	5.027E-09	3.382E-12	3.550E-12

CORRELATION MATRIX P (LOWER TRIANGLE ONLY)

POINTS	TYPE	TIME	COMPL	COMP2	COMP3	SIG1	SIG2	SIG3
40	41	42	1	81.0000	846248.87	.653599	.000030	.000030
43	44	45	1	82.0000	858076.10	.661143	.000030	.000030

46: 47: 48 2 82.0000 891202.76 -1.425735 20.000000 0.000030 0.000030
49: 50: 51 2 84.0000 868737.84 -1.409996 20.000000 0.000030 0.000030

TYPE 8.50000000E+01
V(A) 1.28495774E+04 G(A) 3.94523293E-01 L(A) 6.71947614E+01 ALI 9.19217852E+04 LATO 1.69856431E+01 LON 2.85987537E+01
U(I) 4.98037651E+03 V(I) 1.33110620E+04 W(I) -8.84780272E+01 PSI 8.28770173E+01 THE 1.91879217E+01 PHI 3.17612396E+01
U(B) 1.17127844E+04 V(B) -8.56830552E+02 W(B) 5.21422709F+03 SIG 2.98544615E+01 BET -3.8234119E+00 ALF 2.39973852E+01
XP 0.0
P -1.27098643E-03 Q 8.01514722E-03 R 9.96728523E-04 AX 1.42125420E+04 XZI -9.33175991E+00 ETA 2.23560342E+01
PH -1.27098643E-03 QM 8.01514722E-03 RM 9.96728523E-04 AX -1.28517050E+02 AY 8.02340547E+00 AZ -1.88684021E+02
E0 7.41151859E+01 E1 9.61734110E-02 E2 2.98736819E-01 E3 5.93465171E-01 LATC 1.68779655E+01 A(T) 7.03240615E+05
C 72 1.07250206E+01 C103 2.87979360E-01 C104 5.41052036E-01 C
S (1) 4.033931E+00 S (2) 4.975702E-04 S (3) 5.135601E-04 S (4) 2.365175E+01 S (5) 1.540886E+06 S (6) 1.375152E+09
S (7) 3.609172E+02 S (8) 2.641984E-02 S (9) 3.494534E-03 S (10) 1.951266E-01 S (11) 1.264449E+06 S (12) 1.060568E+06
COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)

1.627E+01
1.305E+03 2.476E-07
4.446E+04 -6.113E-08 2.638E-07
4.893E+01 9.826E-03 -1.947E-03 5.594E+02
5.446E-07 1.765E-10 -5.298E-10 6.200E-06 2.374E-12
2.222E+04 1.575E-10 3.032E-10 5.974E-06 3.505E-13 1.891E-12
1.018E+02 0.0 7.673E-02 5.283E-09 -1.139E-09 1.303E-03
-9.949E-03 -4.231E-06 0.0 -1.029E-01 7.587E-09 1.909E-09 -9.4407E-04 6.980E-04
-1.148E-02 1.266E-06 -6.538E-07 -4.933E-02 6.026E-10 2.304E-09 1.409E-05 -8.568E-06 1.221E-05
-1.265E-05 -7.433E-06 -4.774E-01 2.564E-08 2.141E+08 3.092E-05 -2.810E-05 -5.634E-05 3.808E-02
2.907E-11 -1.548E-10 1.025E-06 1.486E-12 6.216E-13 -2.695E-11 -9.157E-10 2.172E-10 4.582E-09 1.599E-12
2.572E-11 5.930E-11 4.655E-07 4.655E-07 6.526E-13 1.117E-12 2.891E-10 -6.389E-11 -3.637E-10 2.565E-09 7.091E-13 1.125E-12
CORRELATION MATRIX (CVZ) TRANSPOSE
1.385E-01 -0.210E-06 -4.622E-06 -3.192E-01 1.764E-08 1.551E+08 1.655E-05 -1.281E-05 1.527E-04 -1.363E-03 3.241E-09 1.944E-09
-9.127E-03 1.076E-07 9.333E-07 1.351E-02 -1.589E-09 -7.951E-10 -1.502E-04 -8.754E-05 -7.833E-06 8.303E-05 -2.778E-10 -8.897E-11
CORRELATION MATRIX (CVZ) TRANSPOSE
-7.099E-06 4.107E-10 4.235E-10 -4.769E-06 -2.868E-11 -2.364E-11 3.330E-09 -1.113E-09 -4.161E-09 5.413E-08 -2.841E-11 -2.275E-11
3.617E-06 4.348E-10 -1.777E-10 -1.535E-04 3.892E-12 3.247E-12 1.861E-08 -1.683E-08 -3.027E-09 -5.273E-08 3.485E-12 3.325E-12

POINTS TYPE TIME SIG1 SIG2 SIG3
52: 53: 54 2 86.0000 847097.12 -1.1394159 20.000000 0.000030 0.000030
55: 56: 57 2 88.0000 826239.40 -1.1374211 20.000000 0.000030 0.000030

TYPE 9.00000000E+01
V(A) 1.19574508E+04 G(A) 2.09463749E+00 L(A) 6.84176801F+01 ALI 9.33074086E+04 LATO 1.70497522E+01 LON 2.87621416E+01
U(I) 4.39544143E+03 V(I) 1.25775287E+04 W(I) -4.37046954E+02 PSI 8.42001745E+01 THE 2.12640452E+01 PHI 3.17535862E+01
U(B) 1.8746202E+04 V(B) -7.83248880E+02 W(B) 4.91016861E+03 SIG 2.93025729E+01 BET -3.75583042E+00 ALF 2.43003910E+01
XP 0.0
P -1.40626441E-03 Q 6.75272832E-03 R 9.56333033E-04 AX -1.04580147E+02 AY -1.04580147E+02 AZ -1.55212335E+02
PH -1.40626441E-03 QM 6.75272832E-03 RM 9.56333033E-04 AX -1.04580147E+02 AY -1.04580147E+02 AZ -1.55212335E+02
E0 7.35257124E+01 E1 8.05213741E-02 E2 3.11932821E-01 E3 5.96331543E-01 LATC 1.69417167E+01 A(T) 3.45543744E+05
C 72 1.11171555E+01 C103 2.87979338E-01 C104 5.41051991E-01 C
S (1) 3.427940E+00 S (2) 4.405705E-04 S (3) 4.786468E-04 S (4) 2.645112E+01 S (5) 1.873405E+06 S (6) 1.567973E+09
S (7) 3.382445E-02 S (8) 2.574473E-02 S (9) 2.149743E-03 S (10) 1.864880E-01 S (11) 1.256231E-06 S (12) 1.053415E+06
COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)

1.175E+01
7.711E-04 1.941E-07
-2.908E-05 -8.050E-08 2.291E-07
4.115E-01 1.026E-02 -2.961E-03 6.997E+02
1.359E+06 2.047E-10 -6.412E-10 6.267E-06 3.510E-12
3.654E-06 1.082E-10 2.422E-10 6.748E-06 3.733E-13 2.459E-12
1.799E-02 0.0 2.007E-01 1.147E+09 -2.208E-09 1.144E-03
-1.520E-02 -5.848E-06 0.0 -1.846E-01 -1.155E-08 2.235E-09 -8.659E-04 6.628E-04

-4.745E-03-6.142E-07-2.540E-07-3.504E-02 4.085E-10-1.378E-09 5.473E-07 3.086E-07 4.621E-06
 -1.58E-05-1.181E-05-7.795E-01-7.795E-01 5.981E-08 3.860E-08 1.832E-05-2.902E-05-5.675E-05 3.478E-02
 1.355E-11-1.512E-10 6.381E-07 8.381E-07 1.814E-12 6.424E-13-1.090E-09 1.734E-10 1.668E-10 7.181E-09 1.578E-12
 1.824E-11 2.130E-11 7.001E-07 7.001E-07 7.260E-13 1.272E-12 6.699E-10-5.276E-10-1.169E-10 9.155E-10 7.171E-13 1.110E-12
 CORRELATION MATRIX (CVZ) TRANSPOSE
 1.893E-01-8.256E-06-6.220E-06-4.765E-01 3.629E-08 2.995E-08 1.060E-05-1.587E-05 1.538E-04-3.626E-03 5.135E-09 5.637E-10
 -1.261E-02-1.050E-05 3.212E-06-7.048E-03-5.088E-09-7.642E-10-1.396E-04-9.347E-05-7.736E-06 2.243E-04-2.337E-10-7.590E-11
 -3.465E-07 8.337E-10 3.936E-10 3.483E-05-2.998E-11-2.303E-11 7.758E-09-6.153E-09-5.492E-09 1.741E-07-2.849E-11-2.269E-11
 1.140E-05 2.659E-09-6.078E-10 4.663E-05 5.757E-12 4.779E-12 2.500E-08-2.848E-08-9.757E-09-2.340E-07 3.657E-12 3.338E-12

*****BEGIN BACKWARDS SMOOTHING*****

TIME 9.0000000E+01
 V(A) 1.19574508E+04 G(A) 2.09463749E+00 L(A) 6.84176801E+01 ALI 9.33074086E+04 LATD 1.70497522E+01 LON 2.87621416E+01
 U(I) 4.39546193E+03 V(I) 1.25775287E+04 W(I) 1.437046954E+02 PSI 8.42001745E+01 THE 2.12684045E+01 PHI 3.17535862E+01
 U(B) 1.08746202E+04 V(B) 7.89268880E+02 M(B) 4.91016861E+03 SIG 2.93025729E+01 BET -3.75583042E+00 ALF 2.43003910E+01
 XP 0.0
 YP 0.0
 ZP 0.0
 P 1.40526441E-03 Q 6.75272832E-03 R 9.56333835E-04 AX -1.04586147E+02 AY 6.53780171E+00 AZ -1.55232352E+02
 PM -1.40526441E-03 OM 6.75272832E-03 RM 9.56333835E-04 AXM -1.04586147E+02 AYM 6.53780171E+00 AZM -1.55232352E+02
 EO 7.35257144E-01 EI 8.05213741E-02 E2 3.11932621E-01 E3 5.98331943E-01 LATC 1.69417167E+01 A(T) 3.45543794E-05
 S(1) 3.8279480E+00 S(2) 4.4405705E-04 S(3) 4.7864668E-04 S(4) 2.645112E+01 S(5) 1.873405E-06 S(6) 1.567973E-09
 S(7) 3.382445E-02 S(8) 2.574473E-02 S(9) 2.149743E-03 S(10) 2.149743E-03 S(11) 1.864480E-01 S(12) 1.864480E-01 S(13) 1.256231E-06 S(14) 1.053415E-06
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)
 1.175E+01
 7.711E-04 1.941E-07
 -2.908E-05-8.050E-08 2.291E-07
 4.116E-01 1.026E-02-2.961E-03 6.997E+02
 1.359E+06 2.047E-10-6.412E-10 9.267E-06 3.510E+12
 3.652E-06 1.082E-10 2.422E-10 6.748E-06 3.733E-13 2.459E-12
 1.799E-02 0.0 2.007E-01 1.147E-08-2.208E-09 1.144E-03
 -1.520E-02-5.848E-06 0.0 -1.846E-01-1.155E-08 2.235E-09-8.659E-04 6.628E+04
 -4.745E-03-6.142E-07-2.540E-07-3.504E-02 4.085E-10-1.378E-09 5.473E-07 3.086E-07 4.621E-06
 -1.584E-05-1.181E-05-7.795E-01-7.795E-01 5.981E-08 3.860E-08 1.832E-05-2.902E-05-5.675E-05 3.478E-02
 1.355E-11-1.512E-10 6.381E-07 8.381E-07 1.814E-12 6.424E-13-1.090E-09 1.734E-10 1.668E-10 7.181E-09 1.578E-12
 1.824E-11 2.130E-11 7.001E-07 7.001E-07 7.260E-13 1.272E-12 6.699E-10-5.276E-10-1.169E-10 9.155E-10 7.171E-13 1.110E-12
 CORRELATION MATRIX (CVZ) TRANSPOSE
 1.893E-01-8.256E-06-6.220E-06-4.765E-01 3.629E-08 2.995E-08 1.060E-05-1.587E-05 1.538E-04-3.626E-03 5.135E-09 5.637E-10
 -1.261E-02-1.050E-05 3.212E-06-7.048E-03-5.088E-09-7.642E-10-1.396E-04-9.347E-05-7.736E-06 2.243E-04-2.337E-10-7.590E-11
 -3.465E-07 8.337E-10 3.936E-10 3.483E-05-2.998E-11-2.303E-11 7.758E-09-6.153E-09-5.492E-09 1.741E-07-2.849E-11-2.269E-11
 1.140E-05 2.659E-09-6.078E-10 4.663E-05 5.757E-12 4.779E-12 2.500E-08-2.848E-08-9.757E-09-2.340E-07 3.657E-12 3.338E-12

POINTS TYPE TIME RES1 RES2 RES3 RES4 RES5 RES6 RES7 RES8 RES9 RES10 RES11 RES12 RES13 RES14 RES15 RES16 RES17 RES18 RES19 RES20
 57, 53, 55 2 88.000 -1.37444E+00 3.15725C-06 8.48743E-06 -6.87221E-02 1.05242E-01 -5.36814E-02 2.58796E-02 1.01593E-01
 54, 53, 52 2 86.000 -9.38659E-01 -1.61044E+06 7.76388E-07 -4.69329E-02 -5.36814E-02 2.58796E-02 1.01593E-01

TIME 8.5000000E+01
 V(A) 1.28475913E+04 G(A) 3.77934747E-01 L(A) 6.71955546E+01 ALT 9.19084577E+04 LATD 1.69856348E+01 LON 2.85987338E+01
 U(I) 4.97945246E+03 V(I) 1.33092324E+04 W(I) 1.84747400E+01 PSI 8.26846784E+01 THE 1.94174705E+01 PHI 3.15896660E+01
 U(B) 1.17046872E+04 V(B) 8.08358670E+02 M(B) 5.23521426E+03 SIG 2.99442133E+01 BET -3.60734503E+00 ALF 2.4077755E+01
 XP 0.0
 YP 0.0
 ZP 0.0
 P 1.27096643E-03 Q 8.01514722E-03 R 9.96728523E-04 AX -1.28517050E+02 AY 8.02340547E+00 AZ -1.88680099E+02
 PM -1.27096643E-03 OM 8.01514722E-03 RM 9.96728523E-04 AXM -1.28517050E+02 AYM 8.02340547E+00 AZM -1.88791271E+02

50 7.42403300E-01 E1 9.42395292E-02 E2 2.99054249E-01 E3 5.92049676E-01 LATC 1.68779572E+01 A(1) 2.16550637E-05
 S(1) 2.326724E+00 S(2) 2.447078E-04 S(3) 2.529354E-04 S(4) 1.130819E-01 S(5) 1.237032E-06 S(6) 1.065748E-08
 S(7) 3.467664E-02 S(8) 2.6432409E-02 S(9) 2.058628E-03 S(10) 1.256231E-06 S(11) 1.864880E-01 S(12) 1.053415E-06
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)
 5.414E+00
 2.533E-04 5.988E-08
 2.360E-05 9.940E-09 6.398E-08
 2.384E-07 9.990E-08 1.442E-05 1.279E+02
 5.888E-07 1.478E-11 1.411E-10 1.568E-07 1.530E-12
 1.245E-06 1.926E-11 4.326E-11 1.005E-07 6.853E-13 1.134E-12
 -5.209E-03 0 0
 -4.012E-02 2.885E-09 1.252E-09 1.202E-03
 2.475E-02 1.206E-09 8.312E-10 8.390E-04 5.917E-04
 -2.741E-03 3.256E-07 1.604E-07 4.258E-03 1.632E-10 2.549E-10 1.285E-05 8.387E-06 4.239E-06
 1.987E-06 6.523E-06 7.726E-02 7.726E-02 1.198E-08 4.963E-09 1.948E-05 2.793E-05 6.594E-05 3.478E-02
 9.490E-12 1.171E-10 6.216E-08 6.216E-08 1.413E-12 6.864E-13 1.094E-09 1.739E-10 1.446E-10 7.181E-09 1.578E-12
 9.248E-12 2.408E-11 2.497E-07 2.497E-07 7.023E-13 1.024E-12 6.884E-10 4.987E-10 1.043E-10 9.155E-10 7.171E-13 1.110E-12
 CORRELATION MATRIX (CVZ) TRANSPOSE
 0.130000 0.392000 0.045000 8.724E-09 3.4070E-09 9.987E-06 1.469E-05 1.506E-04 3.628E-03 5.135E-09 5.637E-10
 -6.422E-03 2.390E-07 4.036E-07 1.041E-02 4.246E-12 4.196E-10 1.364E-04 -1.012E-04 7.499E-06 2.243E-04 2.337E-10 7.590E-11
 CORRELATION MATRIX (CVZ) TRANSPOSE
 -3.601E-06 5.135E-10 2.850E-10 6.673E-06 2.885E-11 2.291E-11 8.006E-09 5.849E-09 5.082E-09 1.741E-07 2.849E-11 2.268E-11
 6.629E-06 1.584E-09 2.599E-10 8.533E-05 3.831E-12 3.318E-12 2.602E-08 2.683E-08 6.696E-09 2.340E-07 3.657E-12 3.348E-12

POINTS	TYPE	TIME	RES1	RES2	RES3	WGT,RES1	WGT,RES2	WGT,RES3	WGT,RES3	LOSS FCIN
51, 50, 49	84.000	-5.12041E-02	3.22509E-06	-3.25728E-06	-2.56020E-03	-1.07510E-01	-1.08574E-01	-1.08574E-01	-1.08574E-01	1.249.7E=01
48, 47, 46	82.000	7.61788E-01	-2.61999E-06	-4.37501E-06	3.80894E-02	-8.73331E-02	-1.45834E-01	-1.45834E-01	-1.45834E-01	1.55292E=01
45, 44, 43	82.000	-3.85934E+00	-2.07474E-06	-3.85684E-06	1.92967E-01	-4.78823E-02	-1.28561E-01	-1.28561E-01	-1.28561E-01	2.11349E=01
42, 41, 40	81.000	-3.31497E+00	-2.07174E-06	-3.72869E-06	-1.65948E-01	-6.90580E-02	-1.24290E-01	-1.24290E-01	-1.24290E-01	2.59105E=01
39, 38, 37	80.000	9.56986E-01	-8.31592E-07	-3.42725E-06	4.78498E-02	-2.77197E-02	-1.14242E-01	-1.14242E-01	-1.14242E-01	2.75214E=01
36, 35, 34	80.000	-2.45734E+00	-2.55421E-06	-3.23101E-06	-1.22867E-01	-8.51404E-02	-1.07700E-01	-1.07700E-01	-1.07700E-01	3.09195E=01

TIME 0.00000000E+01
 V(A) 1.5084265E+04 G(A) 1.57588294E+00 L(A) 6.58493837F+01 ALI 9.25594200E+04 LATD 1.69126813E+01 LON 2.84242515E+01
 U(I) 5.6780710E+03 V(I) 1.41303178E+04 W(I) 1.4303178E+04 W(I) 3.61880415F+02 PSI 8.10394337E+01 PHE 1.73383116E+01 PHI 3.1384917E+01
 U(B) 1.26709482E+04 V(B) 8.35588008E+02 W(B) 5.81229911E+03 SIG 2.99915750E+01 BET -3.45169713E+00 ALF 2.38898236E+01
 XP 0 0
 P -1.09490564E-03 U 8.46549342E-03 R 1.0172825E-03 AX -1.44364809E+02 AY 9.00133960E+00 AZ -2.0963738E+02
 PM -1.09490564E-03 UM 8.46549342E-03 RM 1.0172825E-03 AXH -1.44364809E+02 AYM 9.00133960E+00 AZM -2.09748555E+02
 EU 7.49974636E-01 E1 1.08980567E-01 E2 2.84032250F-01 E3 5.87355904E-01 LATC 1.68054115E+01 A(1) 8.11571593E-06
 S(1) 1.503867E+00 S(2) 1.305393E-04 S(3) 1.434049E-04 S(4) 1.205780E-01 S(5) 1.019882E-06 S(6) 8.614057E-07
 S(7) 3.557583E-02 S(8) 2.244125E-02 S(9) 2.011421E-03 S(10) 1.864830E-01 S(11) 1.256231E-06 S(12) 1.053415E-06
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)
 2.65E+00
 2.369E-05 1.704E-08
 -2.803E-06 3.940E-09 2.059E-08
 -2.669E-00 6.170E-04 5.402E-05 1.464E+02
 3.56E-07 3.912E-12 2.625E-11 3.969E-07 1.040E-12
 4.68E-07 5.580E-12 5.696E-12 4.387E-07 6.518E-13 7.420E-13
 -3.752E-04 0 0
 -6.329E-03 5.088E-10 1.266E+03
 -2.925E-04 1.029E-05 0 1.295E-02 4.525E-10 3.064E-11 8.085E-04 5.217E-04
 -8.068E-04 1.239E-07 9.880E-09 9.619E-03 6.268E-11 2.544E-10 2.377E-05 1.473E-05 4.046E-06
 -2.021E-06 2.341E-06 2.485E-01 2.485E-01 9.286E-09 1.033E+08 2.064E-05 2.674E-05 7.295E-05 3.478E-02
 2.919E-12 6.977E-11 3.349E-07 3.349E-07 1.099E-12 6.861E-13 1.107E-09 1.729E-10 1.235E-10 7.181E-09 1.578E-12
 1.725E-12 2.469E-11 5.575E-07 5.575E-07 6.897E-13 7.880E-13 7.079E-10 4.684E-10 9.245E-11 9.155E-10 7.171E-13 1.110E-12
 CORRELATION MATRIX (CVZ) TRANSPOSE
 1.496E-02 1.934E-06 2.032E-06 1.911E-01 5.844E-09 5.129E-09 9.275E-06 1.354E-05 1.463E-04 3.626E-03 5.135E-09 5.637E-10
 -1.371E-03 2.231E-07 1.573E-07 1.032E-02 3.218E-10 4.644E-10 1.324E-04 1.067E-04 7.189E-06 2.243E-04 2.337E-10 7.590E-11
 CORRELATION MATRIX (CVZ) TRANSPOSE
 -7.117E-06 1.969E-10 1.448E-10 3.044E-05 2.771E-11 2.196E-11 8.274E-09 5.523E-09 4.666E-09 1.741E-07 2.849E-11 2.268E-11

1.526E-06 5.743E-10 1.846E-12 1.561E-04 3.084E-12 2.495E-12 2.710E-08 2.513E-08 7.683E-09 2.340E-07 3.657E-12 3.338E-12

POINTS	TYPE	TIME	RES1	RES2	RES3	WGT.RES1	WGT.RES2	WGT.RES3	LOSS FCIM
33	32	1	-1.35924E+00	-2.74801E-06	-2.45315E-06	-6.79622E-02	-9.16004E-02	-8.17716E-02	3.28855E-01
30	29	2	79.000	1.06657E-06	-1.30329E-06	6.77751E-04	3.55524E-02	-4.34429E-02	3.32007E-01
27	26	5	78.000	-1.51783E-01	-2.51061E-06	-1.49191E-06	-8.36871E-02	-4.97303E-02	3.41517E-01
44	23	1	77.000	1.17701E-01	-1.69556E-06	-4.49689E-07	5.88505E-02	-5.65187E-02	3.48399E-01
21	20	1	76.000	2.41976E+00	-1.55493E-07	5.67658E-07	1.62098E-01	-1.89219E-02	3.63422E-01
18	17	16	75.000	3.51146E+00	2.25499E-06	1.45315E-06	1.75573E-01	7.51564E-02	4.02243E-01

TIME 7.50000000E+01
 V(A) 1.49641593E+04 G(A) -3.450509731E+00 L(A) 6.45148280E-01 ALI 9.57341473E+04 LATD 1.68297096E+01 LON 2.82380534E+01
 U(I) 6.42669410E+03 V(I) 1.49505475E+04 W(I) 1.48486865E+02 PSI 7.94380945E+01 THE 1.52710090E+01 PHI 3.11967081E+01
 U(B) 1.36818354E+04 V(B) 8.64092941E+02 W(B) 5.99889883E+03 SIG 3.03316550E+01 BET -3.31033857E+00 ALF 2.36753928E+01
 X P C -9.22614978E-04 Y P 0
 Z P 0
 PH -9.42614978E-04 Q 7.73459373E-03 R 9.82154065E-04 AX -1.42491786E+02 AY 8.87341895E+00 AZ -2.04662823E+02
 E0 -9.42614978E-04 QM 7.73459373E-03 RM 9.82154065E-04 AXM -1.42491786E+02 AYM 8.87341895E+00 AZM -2.04662823E+02
 S(1) 1.630148E+00 S(2) 1.23214203E-01 E2 2.68743155E-01 E3 5.82549803E-01 LATC 1.67229044E+01 A(T) 5.56835867E+05
 S(7) 3.640269E-02 S(8) 2.449621E-02 S(9) 2.000494E-03 S(10) 1.528436E+01 S(11) 9.632247E-07 S(12) 7.644826E-07
 S(13) 1.864880E-01 S(14) 1.2566231E-06 S(15) 1.053415E-09
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)
 2.657E+00
 2.585E+05 1.851E-08
 4.225E-05 3.703E-09 2.230E-08
 2.770E+00 -6.414E-04 1.998E-04 2.336E+02
 3.008E-07 -6.374E-12 2.163E-11 1.349E+06 9.667E-13
 1.675E-07 9.013E-12 -7.549E-12 1.443E-07 5.513E-13 5.844E-13
 3.221E-03 0.0 1.276E-01 9.515E-09 4.978E-09 1.325E-03
 -2.020E-03 9.360E-07 0.0 -6.806E-02 -5.465E-09 2.875E-09 7.782E-04 4.621E-04
 1.021E-03 6.536E-07 1.131E-02 1.226E-07 1.131E-02 1.110E-10 8.321E-11 3.315E-05 -1.911E-05 4.002E-06
 2.732E-06 9.941E-07 2.125E-01 2.125E-01 2.125E-01 2.125E-01 2.125E-01 2.125E-01 2.125E-01 2.125E-01 2.125E-01
 -5.428E-12 2.958E-11 1.198E-07 1.198E-07 1.198E-07 1.198E-07 1.198E-07 1.198E-07 1.198E-07 1.198E-07 1.198E-07
 3.572E-12 2.699E-11 -2.939E-07 2.939E-07 2.939E-07 2.939E-07 2.939E-07 2.939E-07 2.939E-07 2.939E-07 2.939E-07
 CORRELATION MATRIX (CZ) TRANSPOSE
 -6.479E-02 1.459E-06 2.200E-07 1.955E-01 -5.997E-09 1.673E-09 8.471E-06 -1.260E-05 1.423E-04 -3.626E-03 5.135E-09 5.637E-10
 3.214E-03 -2.157E-07 2.667E-08 -9.467E-03 6.524E-11 3.389E-10 -1.283E-04 -1.112E-04 -6.920E-06 2.243E-04 -2.337E-10 -7.590E-11
 CORRELATION MATRIX (CZ) TRANSPOSE
 -1.054E-05 -7.400E-11 -1.270E-11 -3.639E-05 -2.663E-11 -2.005E-11 8.531E-09 -5.223E-09 -4.287E-09 1.741E-07 -2.849E-11 -2.269E-11
 -1.000E-08 -2.000E-10 1.412E-10 -1.659E-04 3.419E-12 2.534E-12 2.809E-08 -2.358E-08 -6.789E-09 -2.340E-07 3.657E-12 3.338E-12

POINTS	TYPE	TIME	RES1	RES2	RES3	WGT.RES1	WGT.RES2	WGT.RES3	LOSS FCIM
15	14	13	1	74.000	4.935127E+00	5.67465E-06	2.10114E-06	2.17563E-01	4.90262E-01
12	11	10	1	73.000	4.44013E+00	1.02358E-05	2.44097E-06	1.89155E-01	4.90262E-01
9	8	7	1	72.000	4.48237E+00	1.60575E-05	2.28321E-06	3.44186E-01	6.03250E-02
6	5	4	1	71.000	4.38496E+00	2.36471E-05	1.63398E-06	2.44118E-01	7.61072E-02
3	2	1	1	70.000	3.26856E+00	3.18956E-05	3.84540E-07	1.63428E-01	5.44660E-02

TIME 7.00000000E+01
 V(A) 1.59437078E+04 G(A) -5.12693675E+00 L(A) 6.33489928E+01 ALI 1.01550176E+05 LATD 1.67367329E+01 LON 3.80409860E+01
 U(I) 7.12301619E+03 V(I) 1.56616007E+04 W(I) 1.42477056E+03 PSI 7.80639211E+01 THE 1.34842333E+01 PHI 3.10808133E+01
 U(B) 1.46034724E+04 V(B) 8.49045016E+02 W(B) 6.33620712E+03 SIG 3.06531017E+01 BET -3.20159537E+00 ALF 2.34552310E+01
 X P 0
 Y P 0
 Z P 0
 PH -8.75453186E-04 Q 6.04491552E-03 R 8.82155972E-04 AX -1.22842135E+02 AY 7.53623858E+00 AZ 2.18663951E+01
 E0 -8.75453186E-04 QM 6.04491552E-03 RM 8.82155972E-04 AXM -1.22842135E+02 AYM 7.53623858E+00 AZM -1.72094754E+02
 S(1) 2.4494760E+00 S(2) 2.200619E-04 S(3) 2.084418E+01 S(4) 2.084418E+01 S(5) 5.78102211E-01 LATC 1.6630495E+01 A(T) 1.60671336E-05
 S(6) 1.62098E-01 S(7) 1.89219E-02 S(8) 3.63422E-01 S(9) 1.75573E-01 S(10) 7.51564E-02 S(11) 1.276101E-06 S(12) 9.169253E-07

52 S(7) 3.705445E-02 S(8) 2.045858E-02 S(9) 2.027214F-03 S(103) 1.864880E-01 S(104) 1.256231E-06 S(105) 1.053415E-06
COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)

6.224E+00
2.052E-04 4.843E-08
1.246E-04 3.287E-09 4.344E-08
-1.392E+00 -2.487E-03 1.391E-04 4.345E+02
3.009E-07 -2.478E-12 1.023E-10 2.265E-06 1.272F-12
-1.070E-06 -3.376E-11 -6.918E-11 1.880E-08 3.152F-13 8.408E-13
1.430E-02 0. 0. 1.474E-01 1.537E-08 -1.021E-08 1.373E-03
-7.694E-03 -5.232E-07 0. -8.602E-02 -8.993E-09 5.845E-09 -7.545E-04 4.186E-04
2.652E-03 2.683E-07 1.240E-07 -1.635E-04 6.000E-10 -6.374E-10 4.139E-05 -2.244E-05 4.110E-06
7.224E-06 3.973E-06 -2.161E-01 -2.161E-01 9.337E-09 1.237E-08 2.228E-05 -2.489E-05 -8.364E-05 3.478E-02
-1.392E-11 4.267E-12 8.624E-07 8.624E-07 7.893E-13 5.187E-13 -1.126E-09 1.696E-10 8.951E-11 7.181E-09 1.578E-12
-6.656E-12 1.994E-11 3.973E-07 3.973E-07 6.768E-13 3.862E-13 7.405E-10 -4.197E-10 -7.313E-11 9.155E-10 7.171E-13 1.110E-12
CORRELATION MATRIX (CZ) TRANSPOSE
-1.552E-01 3.648E-06 1.631E-06 -5.451E-02 8.401E-09 2.337E-08 7.690E-06 -1.192E-05 1.397E-04 -3.626E-03 5.135E-09 5.637E-10
8.265E-03 -6.898E-08 -6.970E-07 1.013E-02 -1.180E-09 -5.081E-10 -1.247E-04 -1.158E-04 -6.755E-06 2.243E-04 -2.337E-10 -7.590E-11
CORRELATION MATRIX (CVZ) TRANSPOSE
-1.349E-05 -2.700E-10 -1.583E-10 -2.713E-05 -2.4564E-11 -1.714E-11 8.744E-09 -4.992E-09 -3.983E-09 1.741E-07 -2.849E-11 -2.269E-11
-7.098E-06 -8.871E-10 1.734E-10 -1.217E-04 4.577E-12 3.561E-12 2.888E-08 -2.238E-08 -6.055E-09 -2.340E-07 3.657E-12 3.338E-12

III. PROGRAM CHECKOUT AND VALIDATION

STEP checkout consisted of four separate phases -- checking the nonlinear differential equations of motion; checking the linear equations of motion; checking the measurement equations; and checking the overall system operation. Before preceding with the checkout, a check trajectory was synthesized and PQR and FIT tapes generated using a separate trajectory program. In the following discussion, the check trajectory is described and the results of the various checkout phases discussed.

A. Check Trajectory

The check trajectory corresponded to the flight of a maneuverable lifting reentry vehicle, having a hypersonic L/D of approximately 0.6. The vehicle had the following physical characteristics:

Mass versus time (linear)

m, slugs	25.5763	24.8013	24.0262
t, sec	0.0	200.0	400.0

Reference area, $S = 5.0 \text{ ft}^2$.

The aerodynamic characteristics correspond to an axisymmetric vehicle where

$$C_{N_{\eta}} = N_1(M) \sin [\eta + N_2(M)] + N_3(M)$$

$$C_{Y_{\eta}} = 0$$

$$C_A = A_1(M) \cos [\eta + A_2(M)] + A_3(M)$$

The coefficients $N_1(M)$, $N_2(M)$, $N_3(M)$, $A_1(M)$, $A_2(M)$, and $A_3(M)$ are characterized by the following second-degree polynomials:

$$\begin{aligned}
N_1(M) &= 1.5900 + 0.0300M - 0.4200M^2 \quad (0 \leq M \leq .8) \\
&2.5879 - 2.4649M + 1.1393M^2 \quad (0.8 < M < 1.2) \\
&0.9058 + 0.3386M - 0.0288M^2 \quad (1.2 \leq M \leq 5.874) \\
N_2(M) &= -71.500 - 2.500M + 27.000M^2 \quad (0 \leq M \leq 0.8) \\
&-132.98 + 151.21M - 69.068M^2 \quad (0.8 < M < 1.2) \\
&-31.285 - 18.289M + 1.5561M^2 \quad (1.2 \leq M \leq 5.877) \\
N_3(M) &= 1.5100 + 0.0100M - 0.5800M^2 \quad (0 \leq M \leq 0.8) \\
&2.8984 - 3.4611M + 1.5894M^2 \quad (0.8 < M < 1.2) \\
&0.5577 + 0.4401M - 0.0361M^2 \quad (1.2 \leq M \leq 6.101) \\
A_1(M) &= 0.3450 + 0.1250M - 0.4700M^2 \quad (0 \leq M \leq 0.8) \\
&1.2228 - 2.0695M + 0.9016M^2 \quad (0.8 < M < 1.2) \\
&-0.0885 + 0.1161M - 0.0091M^2 \quad (1.2 \leq M \leq 6.368) \\
A_2(M) &= -50.000 + 22.000M + 28.000M^2 \quad (0 \leq M \leq 0.8) \\
&-143.64 + 256.11M - 118.32M^2 \quad (0.8 < M < 1.2) \\
&30.823 - 34.668M + 2.8385M^2 \quad (1.2 \leq M \leq 6.107) \\
A_3(M) &= -0.1300 + 0.0100M + 0.3200M^2 \quad (0 \leq M \leq 0.8) \\
&-0.8065 + 1.7013M - 0.7371M^2 \quad (0.8 < M < 1.2) \\
&0.2637 - 0.0823M + 0.0061M^2 \quad (1.2 \leq M \leq 6.722)
\end{aligned}$$

Above the upper Mach number limit in the above inequalities the coefficients are constant. C_A and C_N are then transformed to C_A , C_Y , and C_N or C_D , C_Y , and C_L versus α and β . A plot of C_L , C_D , and C_Y is presented in figure 2 for Mach number 0., 1.0, 2.5, and 7.0.

The check trajectory has the following initial conditions at $t = 0$.

$$V_R = 18\,000.0 \text{ fps}, \quad \gamma_R = -6.0^\circ, \quad \lambda_R = 30.0^\circ$$

$$h_o = 250\,000.0 \text{ ft}, \quad \phi_D = 15.0^\circ, \quad \theta = 25.0^\circ$$

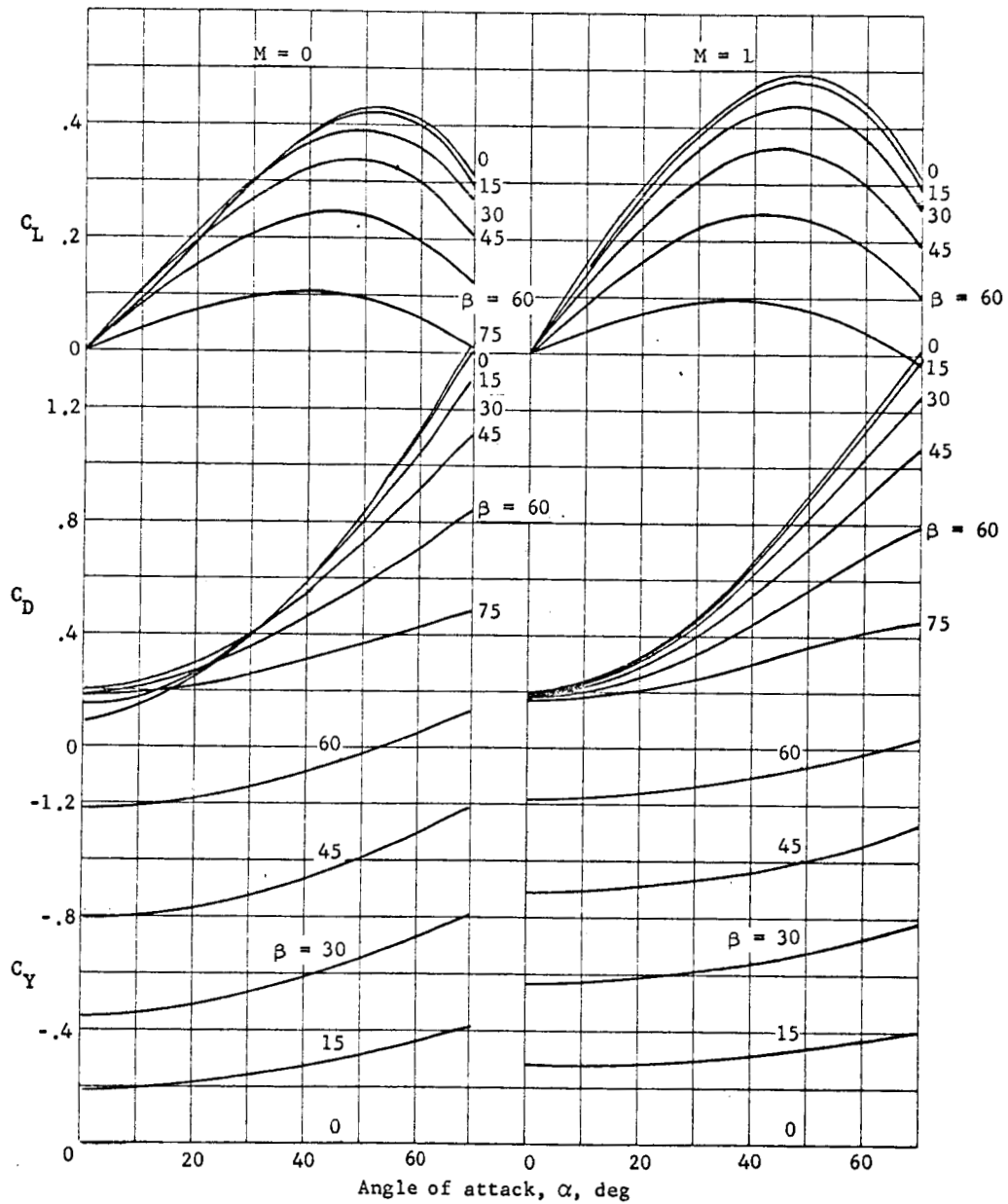


Figure 2.- Aerodynamic Coefficients of Checkout Vehicle

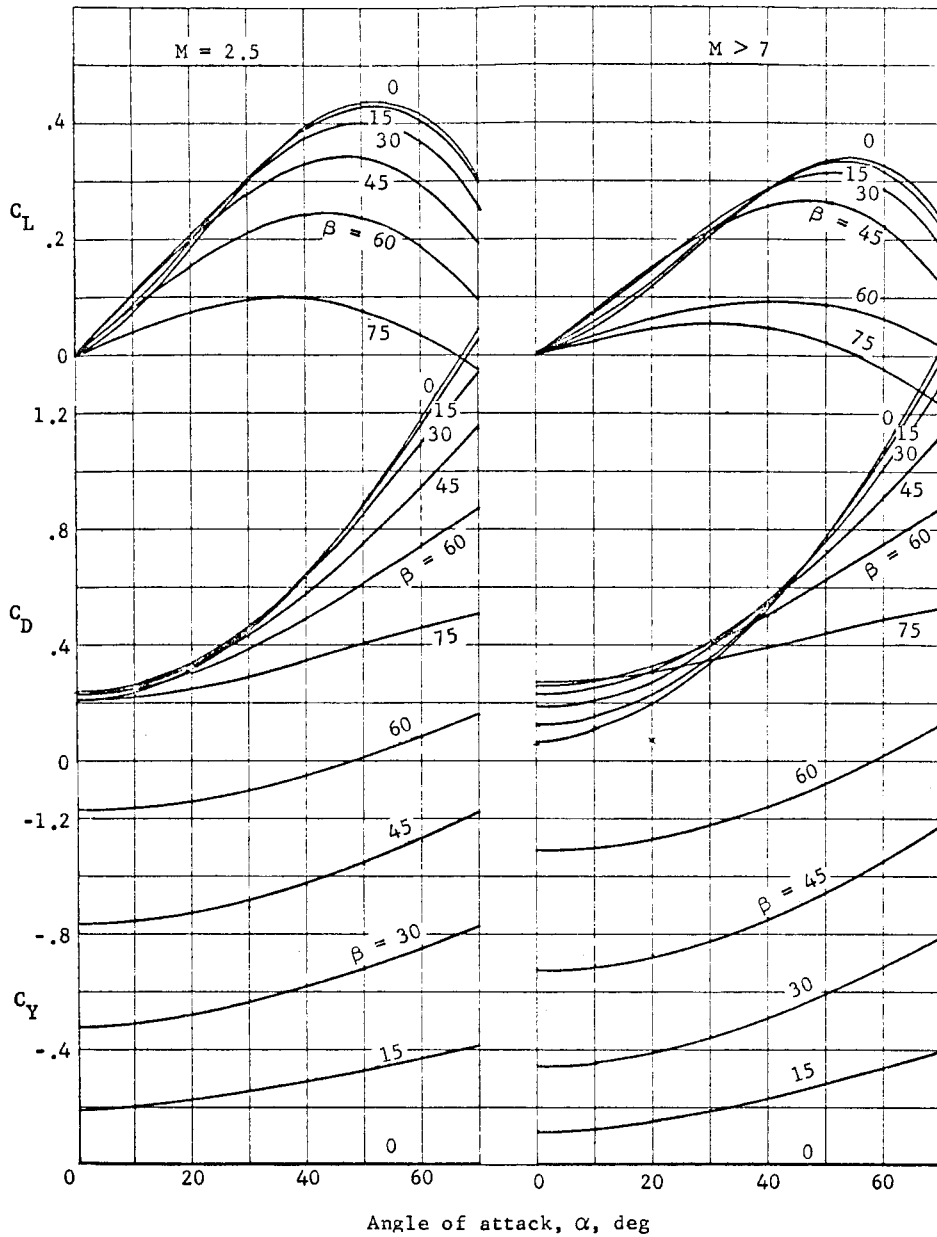
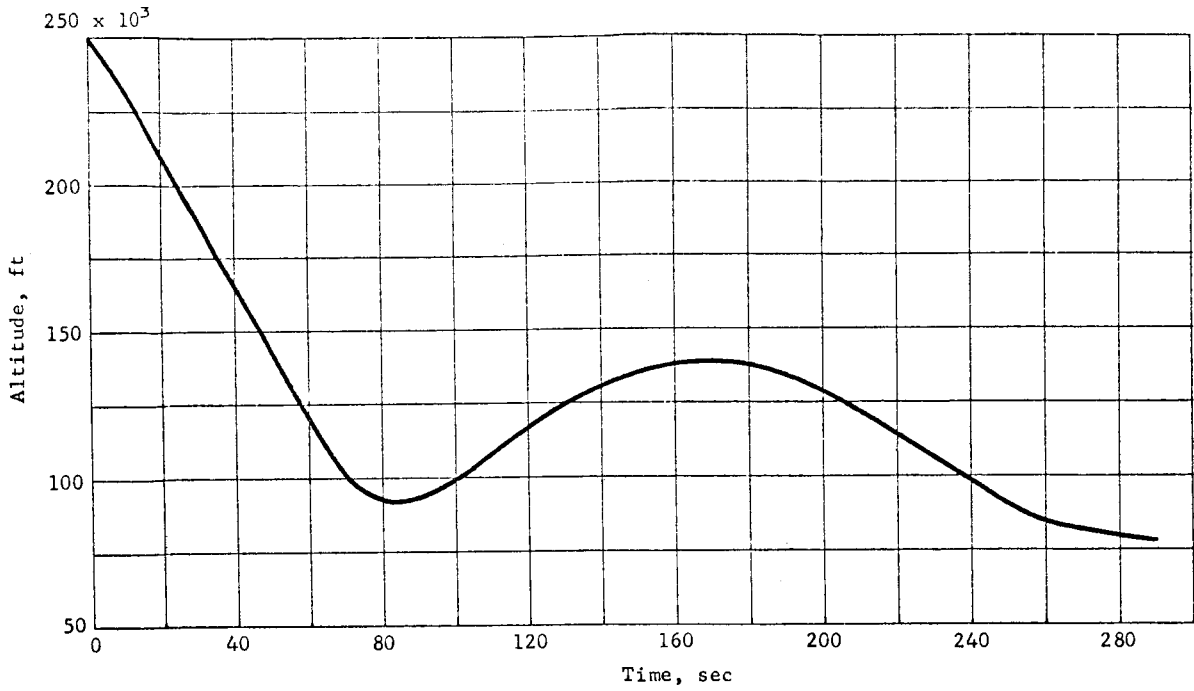


Figure 2.- Concluded

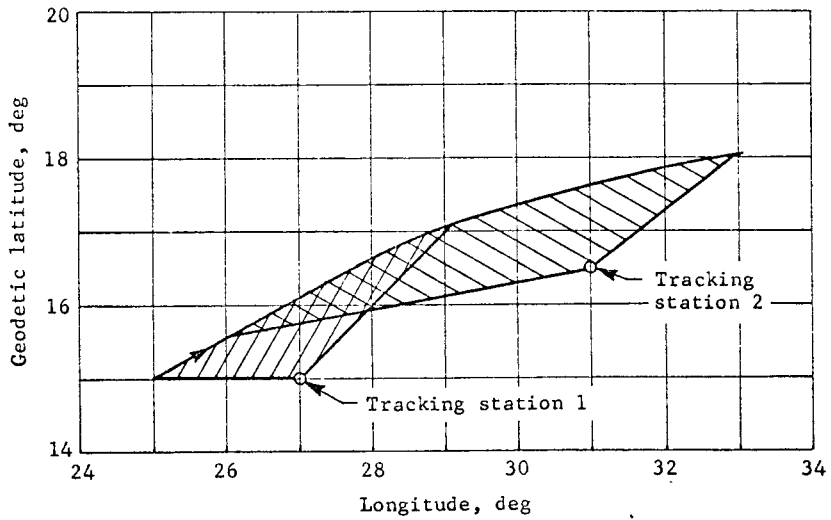
The angle of attack, α , sideslip angle, β , and roll angle, σ , varied linearly with time as follows:

<u>t, sec</u>	<u>0</u>	<u>200.0</u>	<u>400.0</u>
α , deg	20.0	30.0	40.0
β , deg	-1.0	-1.0	-1.0
σ , deg	30.0	20.0	10.0

The altitude versus time and latitude versus longitude are presented in figures 3(a) and 3(b). The PQR tape generated for the check trajectory contained data every 0.25 sec. Tracking stations were located at latitudes and longitudes of 15.0, 27.0 and 16.5, 31.0. The tracking spans, during which time the evaluation angle is larger than 4° is shown in figure 3(b). The tracking data were stored on the FIT tape at a rate of two points per second.



(a) Altitude vs Time



(b) Latitude vs Longitude

Figure 3.- Checkout Trajectory

B. Checkout of Nonlinear Equations of Motion

To check the nonlinear equations of motion, the inertial angular rates (and accelerometers for STEP2) were integrated from $t = 0$ to $t = 250.0$ sec with a computing interval of 0.5 sec. The state time history was then compared with the known check trajectory and agreement to at least six significant digits was obtained. This accuracy is, no doubt, limited by the 0.25-sec interval of the PQR tape data. Several 50-sec problems were solved using different computing intervals for the numerical integration. These results are tabulated below.

	v	h	α	β
Check	17 791.5507	141 872.977	22.5000000	-1.00000000
STEP2 ($\Delta t = 0.25$)	17 791.5337	141 873.085	22.4999995	-1.00000006
STEP2 ($\Delta t = 0.50$)	17 791.5515	141 872.975	22.5000000	-1.00000001
STEP2 ($\Delta t = 5.0$)	17 791.4553	141 873.334	22.5000023	- .99999864

A rather interesting result is exhibited in the above comparison. As the computing interval gets large, errors are introduced as a result of truncation. As the computing interval is reduced, errors are reduced until the computing interval becomes smaller than twice the PQR tape data interval (0.25 sec for this check problem). At this point, the PQR tape requires interpolation. The linear interpolation introduces errors because the data are not linear. Normally, a computing interval twice the PQR tape data interval is most satisfactory because each PQR tape data point is then used in the fourth-order Runge Kutta integration and interpolation is not required. For very nonlinear problems where the threshold for truncation error forces the computing interval to be smaller than the PQR tape data interval, one must either live with the error or increase the frequency at which the PQR tape data are recorded.

C. Checkout of Linear Equations of Motion

The checkout of the linear equations of motion is a very cumbersome task. The solution to the linear equations of motion is the state transition matrix for the expanded state vector. Because any of the model parameters can potentially be components

of the expanded state vector, it is necessary to check a vector solution for each state and model parameter or equivalently, a 9x160 matrix.

The elements of the state transition matrix are partial derivatives of the expanded state vector, Z , at time t_1 with respect to Z components at t_0 . Therefore, the elements can be checked by approximating the partial derivatives by finite differences. This is done by generating a reference nonlinear solution between t_0 and t_1 . A perturbed nonlinear solution is next calculated wherein Z_i , the i^{th} component of Z , is perturbed from the nominal at t_0 . The response of the state variables at t_1 divided by the perturbation in Z_i , which caused them provides a one-sided finite difference approximation to the partial derivative

$$\frac{\Delta Z(t_1)}{\Delta Z_i(t_0)} \approx \frac{\partial Z(t_1)}{\partial Z_i(t_0)}$$

The programs were checked by calculating two-sided finite difference approximations to the state transition matrix. The variable Z_i was perturbed first by $+\Delta Z_i$ then by $-\Delta Z_i$. The difference between the + and - responses in Z at t_1 , divided by $2\Delta Z_i$ yield the desired finite difference approximation.

All state variables and model parameters were perturbed in this manner. A checkout subroutine was mechanized into the STEP decks to do the bookkeeping. It controlled the variable perturbations, recorded the responses, performed the differencing, and printed the finite difference approximation along with its analytically calculated counterpart. The finite difference approximation required only that the nonlinear equations of motion be correct. Agreement with the state transition matrix elements calculated by integrating the linear equations of motion assured that the linear equations of motion were formulated correctly and were being solved correctly. In all cases, the finite difference approximation agreed with its analytical counterpart to at least six significant digits. When disagreement occurred during checkout, it was difficult to determine which coefficient in the linear differential equations was the cause. Therefore, finite difference approximations of the F matrix, equation (6a), were

simultaneously calculated by the check subroutines. Comparison of the finite difference approximation and its analytical counterpart immediately disclosed the erroneous coefficient.

D. Checkout of Measurement Equations

Checking the nonlinear measurement equations was accomplished by comparison with solutions known to be correct. The coefficients in the linear measurement equations, G in equation (4), were checked by comparing the analytically obtained partial derivatives with a finite difference approximation. This comparison study was performed simultaneously with the state transition matrix checkout and was automated by a checkout subroutine discussed previously.

E. Checkout of Input/Output Transformations

The transformations presented in Section VI of Volume I for transforming the input and output were checked by the finite difference approximation comparison technique. Agreement to better than six significant digits were obtained.

F. Checkout Complete STEP

Having assured that the nonlinear and linear state and measurement equations were being solved correctly, the matrix propagation and minimum variance estimation logic was next checked.

1. Matrix propagation.- Two 20-sec problems were solved using the error analysis operating mode. In the first problem, five model parameters were included in the expanded state vector, thus yielding a 15x15 covariance matrix P . In the second problem, three of the model parameters were removed from the expanded state vector Z and placed in the uncertain model parameter vector U . Thus, the second problem has a 12x12 covariance matrix P and a 12x3 correlation matrix CVZ . As indicated in equation (50) of Volume I, CUZ from the second problem should be a submatrix in the 15x15 covariance matrix, P , of the first problem, as indeed it was. Thus, this check confirmed that the covariance and correlation matrices P and CUZ were being propagated correctly.

The next check runs used the filtering mode of operation to test the minimum variance recursive updating equations, equations (53). In the first problem several tracking points from station 1 were processed with infinite variances. As expected, no change in the state variables occurred. In the second problem, tracking data from station 1 were processed with zero variances. The initial covariance matrix of state P was specified to be very large. While attempting to process the ninth tracking point, a variance element in P became negative causing the run to terminate. Because the dynamic model in STEP is a ninth-order system (nine independent first-order differential equations), after processing nine data points of absolute certainty (zero variance), the covariance matrix P should be zero if it is initially specified to be infinity. In the check problem, a finite initial covariance matrix P was specified. Therefore, processing the ninth tracking point produces the expected result of causing a variance of P to become slightly negative in attempting to seek zero.

In the next check runs, the smoothing option was tested. Operating in the error analysis mode with no tracking data, the covariance matrix was input using input/output option 1 and 2. The covariance matrix P was transformed to internal units, propagated forward in time for 20 sec, propagated back to initial time, and transformed back to the output variable of option 1 and 2. The state and covariance matrix at the completion of the run matched those inputted to better than eight significant digits.

The final series of tests checked the filtering mode of operation. Twenty-second problems were run, during which tracking data from stations 1 and 2 were discretely selected from the FIT tape and processed. The problems ran for as many as three iterations using both the updated and nonupdated references, and both vector and scalar data processing options. Typical of the convergence of these runs is the two iteration problems presented in table 2 for STEP2. The expanded state vector was randomly noised at initial time by an amount consistent with the initial covariance. The random noise was normally distributed with zero mean. Table 2 shows the correct state at initial time, the noised state at initial time and the converged state at initial time after two iterations. Also shown are the estimated standard deviations at initial time after the second iteration. Comparing these residuals with their calculated variances, 83% lie within one-sigma and 100% within two-sigma. Theoretically, 68.3% should be within one-sigma, 95.5% within two sigma, and 99.7% within three sigma.

TABLE 2.- THREE ITERATION PROBLEMS, STEP 2

Iter	V	γ	λ	h	ϕ	θ	σ	β	α
Nom	15 946.18	-5.13088	63.3697	101 549.4	16.736757	28.040927	26.50	-1.0000	23.5000
0	16 001.20	-6.75088	63.0352	100 584.0	16.758397	28.041838	29.8270	-4.4320	19.3930
1	15 943.70	-5.12694	63.3490	101 550.2	16.736733	28.040986	30.6531	-3.2016	23.4552
2	15 945.99	-5.12227	63.3601	101 547.5	16.736749	28.040935	30.2796	-3.0292	23.5244
Iter	δV	$\delta \gamma$	$\delta \lambda$	δh	$\delta \phi$	$\delta \theta$	$\delta \sigma$	$\delta \beta$	$\delta \alpha$
0	55.02	-1.6200	-.3345	-965.4	.02164	.00091	3.327	-3.432	-4.107
1	-2.48	.0039	-.0207	- .8	.00002	.00005	4.153	-2.202	- .045
2	- .19	.0086	-.0096	- 1.9	.00001	.00000	3.779	-2.029	.024
Est. σ	(2.52)	(.0135)	(.0128)	(20.59)	(.00006)	(.00005)	(2.254)	(1.210)	(.112)

IV. PROGRAM STRUCTURE AND LOGIC

STEP is completely coded in FORTRAN 2.0 using an executive structure wherein the MAIN program controls logic to and from the various subordinate subroutines. Each of the subroutines performs a specific logical task. Because of the versatility of the programs, the logic is somewhat complex. This is necessary to accommodate the numerous options described in the input section. STEP contains the following contractor-developed subroutines

<u>STEP1</u>	<u>STEP2</u>
MAIN (called ST1)	MAIN (called ST2)
AERO	DATAB
AEROIN	FXXU
ATMDAT	INDAT
CRV	INTAG
DATAB	MINVAR
DERIVE	MOTION
FUNCT	OBSERV
FXXU	OUTPUT
INDAT	PRESET
INTAG	PROP
MINVAR	RKUTTA
MOTION	SETUP
OBSERV	SMOOTH
OUTPUT	STAT
PRESET	TAB
PROP	
RKUTTA	
SETUP	
SMOOTH	
STAT	
TAB	

The subroutines common to STEP1 and STEP2 are nearly identical.

A. Overall Program Logic

The overall program logic for filtering, error analysis, and deterministic problems is described below with the aid of figure 4.

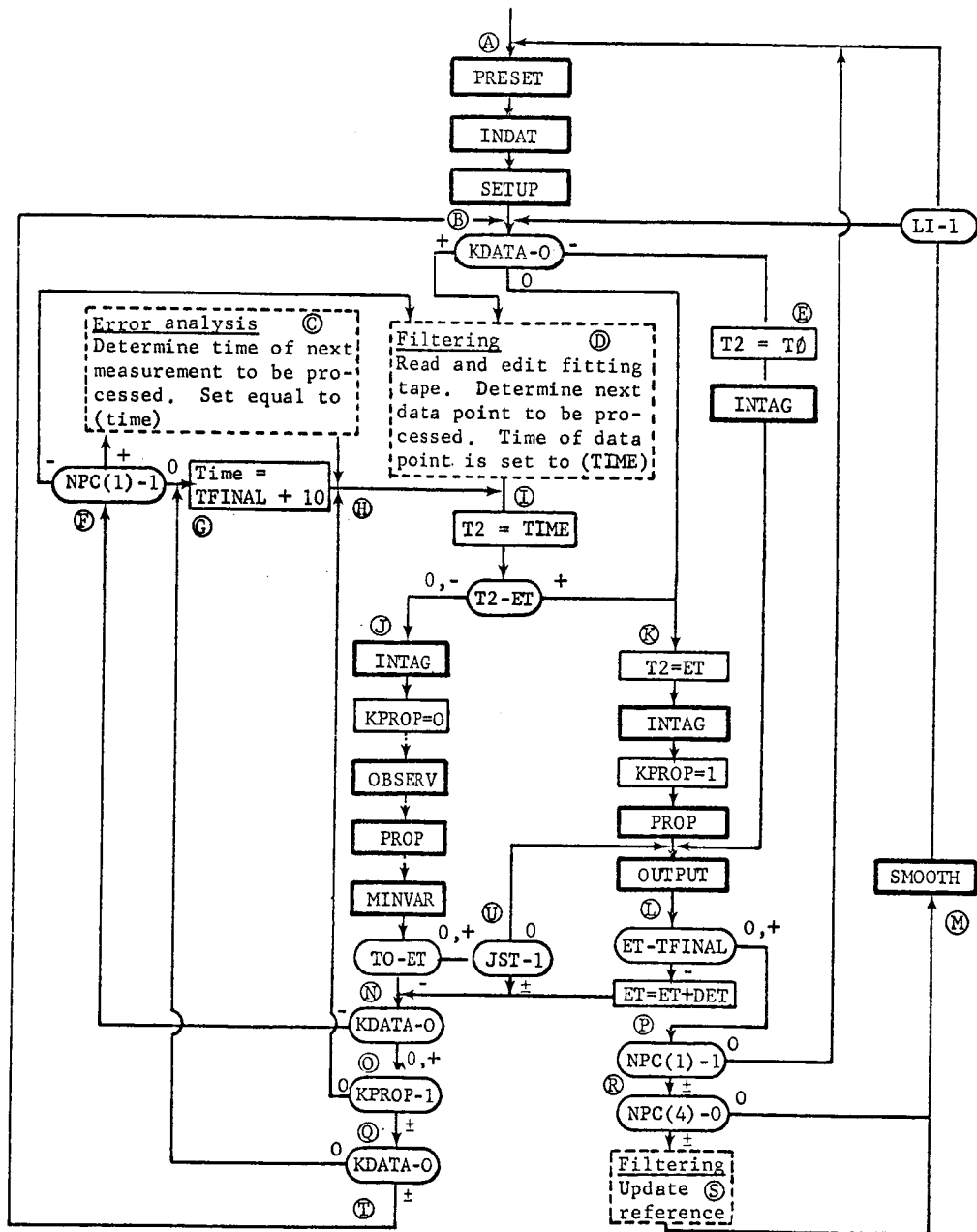


Figure 4.- Overall Program Logic

1. Filtering problems $[NPC(1) = 0]$. - Referring to figure 4, the program commences at (A) by calling PRESET, INDAT, and SETUP. PRESET specifies values for variables and triggers. INDAT reads all input data from cards. SETUP performs all necessary calculations on the input data and controls in preparation for the processing that follows. In SETUP, the fixed point triggers KDATA and KPROP are set equal to -1, and T_0 is set equal to the initial problem time. From (B) the logic transfers to (E) where INTAG is called. INTAG always integrates the nonlinear and linear differential equations of motion from T_0 to T_2 to yield the nonlinear state at T_2 and the state transition matrix that relates variables between T_0 and T_2 . Obviously, when INTAG is called at (E), $T_0 = T_2$ so that the computation involves only an evaluation of the differential equations and auxiliary variables. The logic then proceeds to OUTPUT where the state variables and auxiliary parameters are block printed at the initial time. The time at which the block print occurs is called ET. Thus, after OUTPUT, ET is compared with final problem time TFINAL, at (L), and, because it is smaller, it is updated by the print interval DET. Logic then proceeds to (N) where KDATA is tested. Because it is negative, the logic transfers to (F) where $NPC(1)$ is tested. For filtering problems, $NPC(1)$ equals zero so the logic branches to (D) where the FIT tape is read and edited to determine the next data point to be processed. The time corresponding to the data point is called TIME. If more than one data point is to be processed at TIME, the trigger JST is set to 2, otherwise JST equals 1. At (I) T_2 is set equal to TIME and is then compared with the next block print time. If TIME is less than or equal to ET, the logic proceeds to (J) where, in INTAG, the nonlinear state and state transition matrix are calculated between T_0 and T_2 . After INTAG, T_0 is equated to T_2 (although not shown in fig. 4). OBSERV then calculates the nonlinear measurement variables and their partial derivatives with respect to the expanded state vector components. PROP next propagates the covariance and correlation matrices, P, CUZ, and CVZ to T_2 , and MINVAR performs the minimum variance update of the expanded state, its covariance, and correlation matrices. T_0 is then compared with ET, and, if smaller, the logic goes to the KDATA test at (N). Because KDATA corresponds to the number of points per record on the FIT tape, it is now a positive integer. Therefore, the logic drops to (O) where KPROP is tested. However, KPROP was set to 1 in the processing path (J) - (N), so the logic drops to (Q), then to (T) and back to (D) to determine the next point to be processed. As long as data are available on the FIT tape, the program loops through the circuit (D) - (I) - (J) - (N) - (T) - (B) - (D). If a block print time intervenes the logic forks after

(I) to (K). From (K) to (L) the state, covariance and correlation matrices are propagated to time ET, the print occurs in output, and the logic transfers back to (N). Because KPROP is set zero in the propagation path (K) - (L), the test below (O) now transfers back to (H) then to (I). Because during propagation (K) - (L) no data are processed, it is not necessary to determine another data point at (D). If a data time, TIME, equals the print time, ET, the processing path (J) - (N) is traversed until the last point at time TIME is processed (JST = 1). Then the logic branches through (U) to output to perform the block printing. When final time, TFINAL, is ultimately equaled or exceeded, the test below (L) transfers the logic to (P) and then to (R) because NPC(1) = 0. Below (R) the reference is updated and logic returns to (M) where SMOOTH is called. SMOOTH performs the backward smoothing from final time to initial time as well as calculation of residuals and loss function. After SMOOTH, the logic transfers to (B) where the next iteration is commenced. On the last iteration, logic is transferred back to (A) to begin the next problem. If the FIT tape runs out of data at any time during the processing, the program will read a zero record (having KDATA = 0) last from the tape. Subsequently the transfer from (Q) goes to (G) where TIME is set to exceed the final problem time. This forces the program to traverse the circuit (H) - (I) - (K) - (L) - (N) - (O) - (H) thereafter.

2. Error analysis problems [NPC(1) = 2]. - The error analysis logic proceeds the same as the filtering logic with the following exceptions. The data processing time TIME is determined at (C) from card inputs rather than at (D) from the FIT tape. In MINVAR, the expanded state vector is not updated. At (S) the reference need not be updated.

3. Deterministic problems [NPC(1) = 1]. - On deterministic problems the logic flows through (A) - (B) - (E) - (L) - (N) - (F) - (G). At (G), TIME is set larger than final time and the logic continues through (I) - (K) - (L) - (N) - (F) - (I) until final time is equaled or exceeded at (L). From (L) the logic branches to (P) and then to (A) to commence the next problem.

B. Subroutine Logic

The logic and equations solved in each of the subroutines will next be described with the aid of the flow diagrams and source listings in Sections VI and VII. The subroutines are grouped into five classifications -- initialization and problem setup; integration of differential equations; measurement calculations and minimum variance updating; smoothing; and output.

1. Initialization and problem setup.- The initialization and problem setup is performed by subroutines PRESET, INDAT, and SETUP. These subroutines are only called once per problem. Therefore, they have been arranged to form an overlay. After SETUP has completed its execution, the remainder of the program is read into core overlaying the cells previously occupied by PRESET, INDAT, and SETUP.

a. PRESET: The first operations performed by STEP during an execution are to preset variables. These operations are performed in subroutine PRESET, and consist of prespecifying values for variables, counters, and triggers. Should values for these variables not be input, the prespecified values will be used in the problem execution.

b. INDAT: All card inputs are read from subroutine INDAT. The unique inputting logic divides the card input data into 20 categories described in Subsection II.A.1. As each category is input, the category number on the lead card is read as a fixed point number. The remaining data on the lead card is read in the A-mode to preclude the computer from transforming the data to binary numbers immediately. By means of the category number, logic is transferred, through a computed GO TO to the category specified. Here, the A-mode numbers are decoded into binary numbers and equated to specific variables in this category. Note that the decoding of the A-mode numbers is the one feature in STEP that limits the use to CDC computers. If more data are required for the particular category, they are input by standard READ instructions. In STEP1, subroutine AEROIN is called to input the trivariate tables containing the aerodynamic coefficients. Logic is then transferred back to the beginning of INDAT where the next category input is read.

Insofar as INDAT is concerned, the order in which the categories are input makes no difference. However, some data are required before others, and it is a good rule to input the categories in numerical order, especially categories 2, 3, 5, 10, and 14. When all data have been input, the category 20 card is read to end the input loop and return to PRESET.

Note how the expanded state vector components, uncertain model and measurement vector components, and other model parameters are stored. The nonlinear state variables are input into an array called ZO(i). These are later transformed into internal variables and stored into the array X(i), $i = 1, 10$ in SETUP. All model parameters, whether to be estimated or not, are stored

in the array $C(i)$, the argument (i) being their identification number. The model parameters to be estimated are counted as they are input, the counter being $NSTC$, and their identification numbers loaded into the array $NC(i)$. If at any later time these model parameters are required, their identification numbers are stored in $NC(i)$, $i = 1, NSTC$, and their values are stored in the $C(i)$ array. The uncertain model parameters not to be estimated, U , are counted by NPU , their identification numbers stored in $MC(i)$, and their values stored in the $C(i)$ array. Uncertain measurement parameters not to be estimated, V , are counted by NPV , their identification numbers stored in $MCC(i)$, and their values in $C(i)$. All constants known with absolute certainty are stored in the $C(i)$ array. The number of fitting data sources or types is counted by $NSTA$.

c. **SETUP:** After all data have been input, subroutine **SETUP** is called to set up the problem to be executed. **SETUP** commences by interrogating the program controls and printing comments to inform the user of the options he has selected. In the process of doing this, the gravitational, geophysical, and atmospheric (**STEP1** only) data are printed in units either specified by the user via $NPC(2)$ or in units in which the data were input.

In **STEP1**, all atmospheric data are calculated in subroutine **ATMDAT** during problem execution. This subroutine requires base pressure and temperature/altitude slope data. These are calculated in **SETUP** using the built-in altitude and temperature base points and sea-level pressure corresponding to the 1962 U.S. Standard or 1959 ARDC atmospheres or data provided by the user in **INDAT**.

The fitting data sources are next listed. For tracking stations, the geodetic latitude is transformed to geocentric and subroutine **STAT** called to calculate tracking station related information to be used during the execution. Tests are also performed to determine if rate terms on tracking station k are to be estimated [$M\emptyset(k) = 1$] or not estimated [$M\emptyset(k) = 0$]. Also, the number of tracking stations whose station locations are to be estimated (KSS) are determined and their station numbers ($MTYP = 1, 2, \dots, 5$) are stored in the array $NSS(i)$, $i = 1, KSS$.

The inputted state variables are next transformed into internal variables $u, v, w, h, \phi, \theta, e_0, e_1, e_2,$ and e_3 as are their covariance and correlation matrices. The transformations are presented in Section VI of Volume 1. The transformation matrix $N_I(i,j)$ is stored in the array **DUB**(i,j).

All angles at this point are in radians. SETUP next prints tables of the internal state variables and model parameters and their standard deviations. Finally, near the end of SETUP, the number of differential equations to be integrated is determined (NALL), and counters, triggers, arrays, and variables are set to their required values to commence the forward integration.

2. Integration of differential equations.- All linear and nonlinear differential equations are integrated in subroutine INTAG. Supporting subroutines required by INTAG to perform the integration are RKUTTA, DATAB, MOTION, FXXU, and in STEP1 AERO and DERIVE are also required.

a. INTAG: When subroutine INTAG is called, it will integrate the nonlinear differential equation in filtering and error analysis problems, from time T_0 to time T_2 . Initial conditions must have been specified for the linear and nonlinear equation dependent variables before calling INTAG. The equations are integrated by a fourth-order Runge Kutta integration scheme as one large system. The dependent variables in this system are stored in the array $X(i)$. Consider a problem where only the basic state variables are to be estimated. INTAG would then integrate the 10 nonlinear differential equations plus 10 independent vector solutions for the 10 linear differential equation, or 110 differential equations in all. In the array $X(i)$; $X(1-10)$ contains the solution to the nonlinear equations; $X(11-20)$ contains the first solution to the linear equations (the first column of the state transition matrix ϕ); $X(21-30)$ contains the second solution to the linear equations; ... $X(101-110)$ contains the tenth solution to the linear equations. Note that there is but one system of linear differential equations, having time varying coefficients. Ten separate solutions to this system must be obtained. At the beginning of a problem, the initial conditions for the state variables, $X(1-10)$, are provided from SETUP. The initial conditions for the linear equations are specified in SETUP to be the identity matrix, i.e., $X(11-110) = 0$ except $X(11) = X(22) = X(33) = \dots = X(99) = X(110) = 1$. Inspection of the flow diagrams and listing of INTAG reveals that the array $PH(i,j)$ is frequently used instead of $X(10-110)$ discussed previously. This is possible because, in common INTGRL, $X(i)$ is dimensioned 10 and is followed by $PH(i,j)$ dimensioned 10 x 30. Thus, $X(11)$ is equivalent to $PH(1,1)$, $X(12)$ equivalent to $PH(2,1)$ and so on. $PH(i,j)$ is therefore the state transition matrix ϕ .

The numerical integration logic is contained in subroutine RKUTTA. RKUTTA relies on the fixed point indicator LRK. The integration is commenced by setting $LRK = 4$ and calling RKUTTA. Upon returning from RKUTTA, LRK will equal 1, 2 or 3. When $LRK = 1$, the differential equations must be evaluated and logic returned to RKUTTA. $LRK = 2$ each time RKUTTA has completed an integration cycle. Thus, upon returning from RKUTTA with $LRK = 2$, the state can be printed if a printout is desired at a frequency dictated by the fixed computing interval DCOMP. The STATE tape is written during the backward integration whenever $LRK = 2$. RKUTTA returns with $LRK = 3$ when it has integrated to exactly the time T2. Because INTAG only integrates to T2, logic is returned to the main program whenever $LRK = 3$ on the return from RKUTTA.

b. RKUTTA: RKUTTA is a general numerical integration subroutine developed specifically for use in STEP. Its internal variables differ from those in the rest of STEP, thus through common block INTGRL, the RKUTTA variables are made equivalent to the STEP variables. As discussed above, LRK (or L in RKUTTA) is the indicator that RKUTTA uses to communicate with INTAG.

c. DATAB: Subroutine DATAB contains the logic for reading the PQR tape, writing a scratch tape containing the PQR data and interpolating tables to obtain P_M, Q_M, R_M and $a_{X_M}, a_{Y_M}, a_{Z_M}$

(STEP2 only). At the beginning of a problem, DATAB reads the PQR tape until the last time on a PQR tape record exceeds the initial problem time. It then stores between 20 and 40 of the PQR data points in core. As the integration proceeds the core stored tables are interpolated until time exceeds that of the second to the last point in core. All points in core are then transferred to the SCRACH tape, the last two points in core are transferred to the beginning of the table, and more PQR tape data is read into core until between 20 and 40 points are in core. The integration again proceeds until time exceeds that of the second to last point in core. Again, the core-stored points are transferred to the SCRACH tape, the last two core-stored points moved to the beginning of the table and more PQR tape data read. This continues until final time is exceeded and the backward integration (smoothing) commenced. Before commencing the backward integration, a false record is written on the SCRACH tape so that later, in DATAB, two backspaces will position the tape to read the last valid record. At final time, sufficient data are already in core to commence the backward integration. When time becomes smaller than that of the second point in core, the

SCRACH tape is backspaced twice and a record is read into core. This record already contains tie-in points, i.e., the first two points previously in core. Whenever time becomes smaller than the second point in core, the SCRACH tape is backspaced twice and read. In this manner the integration proceeds to initial time. During all remaining iterations, the PQR tape is used on the forward integration and the SCRACH tape used on the backward integration.

On filter problems, capability is included to calculate residuals of the measurements and a loss function on the backward integration. To do this requires that the data from the FIT tape, which were processed on the forward integration, be stored. This storage is accomplished without requiring an additional tape unit, by having logic included in DATAB to store the processed FIT data on the SCRACH tape also. Therefore, when the SCRACH tape is written on the forward integration, all but the last two good (not edited, eligible to be processed) FIT data points in core are written on the SCRACH tape simultaneously with the PQR data. The two FIT data points, which are held back, will be written on the next SCRACH record. Therefore, during the backward smoothing, the core always contains a FIT data point at a time smaller than the PQR data in core. Subsequently it will be seen that this is necessary in subroutine SMOOTH.

d. MOTION: In subroutine MOTION, the nonlinear differential equations of motion are calculated. The state variables $X(1-10)$ are used to calculate the state variable time derivatives $DX(1-10)$ presented in equations (127) thru (129) of Volume I. The major portion of MOTION is used in calculating the auxiliary equations, equations (130) thru (160). In STEP1, MOTION calls subroutine ATMDAT to determine the atmosphere data, and subroutine AERO to determine the aerodynamic coefficients.

An entry point AUXIL is provided to calculate quantities needed by subroutine OUTPUT. These quantities are altered whenever the nominal is changed (i.e., when a data point is processed during an updated nominal filter problem); thus, OUTPUT must evaluate these equations immediately before printing. Entry point AUXIL is used only by subroutine OUTPUT.

e. FXXU: Subroutine FXXU calculates the coefficients in the linear differential equations of motion, equation (165). These coefficients are presented in Section V of Volume I.

Subroutine FXXU always evaluates the equations in table 4 of vol. 1. The STEP1 program calculates the equation in table 5 also. Logic is included, which determines if the state vector has been augmented to include model parameters or if any model parameters have been included in the U array (uncertain, but not to be estimated). If so, the partial derivatives associated with these model parameters are evaluated.

For STEP1, entry point PAXPC is included in subroutine FXXU. This allows equations that are common to the linearized equations of motion and the linearized model for the accelerometers to be coded only once. Entry point PAXPC is used only by subroutine OBSERV.

f. ATMOS (STEP1 only): In subroutine ATMOS, all atmospheric parameters are calculated. These quantities are presented in equations (121) thru (126) in Volume I.

g. AERO (STEP1 only): Subroutine AERO determines all aerodynamic coefficients for the vehicle. The trivariate tables are linearly interpolated by subroutine FCTN. The interpolated coefficients are either C_A, C_Y, C_N ; C_D, C_Y, C_L ; or C_A, C_Y, C_N .

In AERO, these coefficients are then transformed to $-C_A, C_Y, -C_N$ by equations (134) and the error model, equation (147), solved before returning to MOTION.

Subroutine AERO has a seven-variable argument list. The first two arguments are determined by IPC_8 in category II (α, β if $IPC_8 = 0$ or -1 ; η, ξ if $IPC_8 = 1$). Arguments 3 and 4 are Mach and Reynolds numbers, respectively. Arguments 5, 6, and 7 are $C_X, C_Y,$ and C_Z , which are returned to the calling program by AERO. Note that $C_X = -C_A$ and $C_Z = -C_N$.

Subroutine AERO has been written to facilitate its removal and replacement by a subroutine specialized to the particular vehicle being analyzed. The tables interpolated by subroutine AERO are the only quantities in common block AERTAB; after reading the category 11 card, subroutine INDAT transfers control to subroutine AEROIN, which reads in the tables, and then returns control to INDAT, which then continues to read in the remaining input data.

If subroutine AERO is replaced with a subroutine written for a specific vehicle, several facts should be considered. The input control IPC_8 in category 11 should be specified so the correct angles are passed to AERO; these angles are in radians, not degrees. The coefficients calculated must be transformed to C_X , C_Y , and C_Z . The error model, equation (147), must be included in subroutine AERO. Subroutine AEROIN may be modified to simplify any inputs to the new subroutine AERO.

h. TAB and FCTN: Subroutine FCTN is used solely for interpolating the trivariate aerodynamic coefficients tables. All other interpolations are performed by TAB. TAB was specifically developed for STEP and is limited to linear interpolation of monovariate tables. Each table contains an array of three fixed point numbers, $N(i)$, $i = 1, 3$, which TAB requires. $N(1)$ is the number of points in the table, $N(2)$ is the argument of the tabular array which bounds the last interpolated value on the lower side. TAB commences searching the table from this point the next time interpolation is required. $N(3)$ is zero for an increasing independent variable, and one for decreasing independent variable.

3. Measurement calculations and minimum variance updating.-
On filtering and error analysis problems, the calculation of the nonlinear measurements, $Y(t_i)$, and their partial derivatives with respect to state variables and model parameters, G and H , are performed in OBSERV. In subroutine PROP, the covariance and correlation matrices, P , C_{uz} , and C_{vz} , are propagated to the measurement time by equation (54). In subroutine MINVAR, the minimum variance updating by means of equation (53) is accomplished.

The logic controlling the execution of OBSERV, PROP, and MINVAR is located in MAIN and is complicated by the optional ways that the data can be processed, i.e., scalar or vector processing with an updated or nonupdated reference of a one-, two-, or three-component measurement. The options are tested in MAIN and the flag KK is set to 1 if only one circuit through the OBSERV, PROP, and MINVAR loop is required. The only time more than one circuit is required is when processing a multicomponent vector, scalar point at a time in the updated reference mode for which case KK equals the number of vector components to be processed.

KN is set to 0 if only one component of the measurement vector and its partial derivatives need be specified in OBSERV. If more than one component must be calculated $KN = 1$. A loop is then commenced through OBSERV, PROP, and MINVAR with index KAR going from 1 to KK.

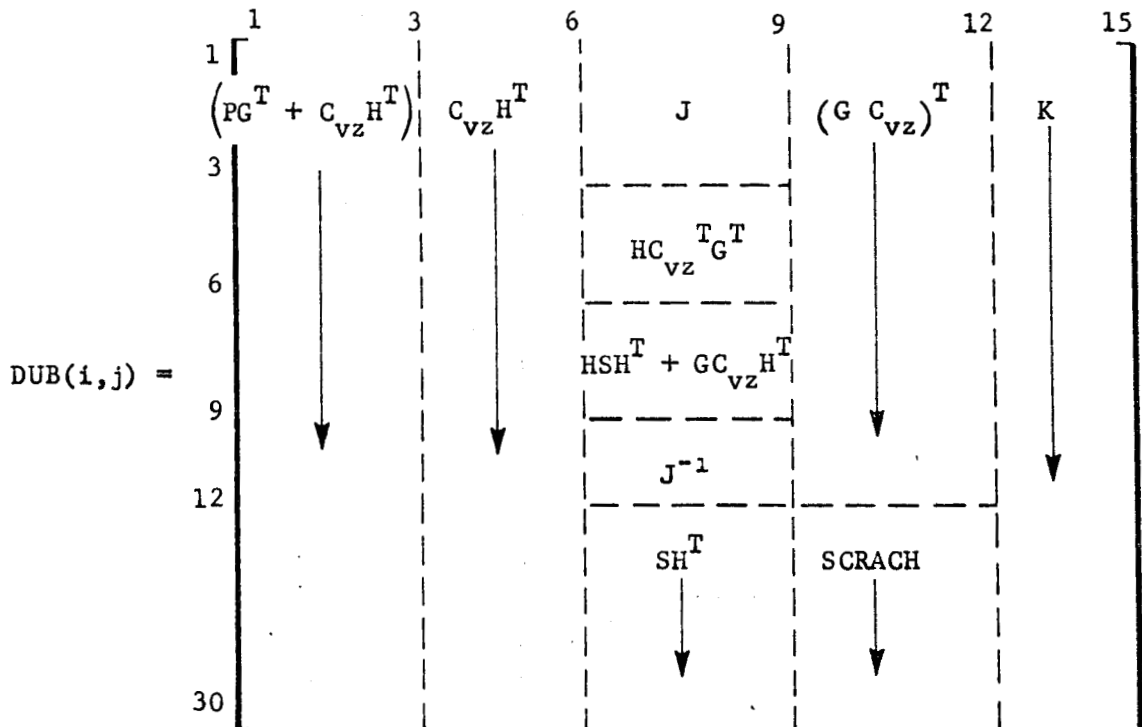
a. OBSERV: Subroutine OBSERV commences by testing the measurement type indicator, MTYP, and then branches the logic to calculate the nonlinear measurement specified. These measurement equations are presented in Volume I, Section VII. Measurements from all five tracking stations as solved from the same equations with the model parameters symbolically specified as a function of MTYP.

The three components of the measurement vector are stored in the array DFM(1-3). If only one component is to be processed ($KN = 0$), it is stored in DATC(KAR). If more than one component is to be processed, they are stored sequentially in DATC(i). Thus, if the second component of the measurement vector has been edited out by input controls, DATC(1) equals component one and DATC(2) equals component three. The integer KOB is set to KAR if only one component is to be processed or to JNBR if multiple components are to be processed. Thus, looping on i from KAR to KOB sequentially specifies the components of DATC(i) to be processed.

OBSERV next calculate the G and H matrices in equations (51a) and (51b). The matrices contain the partial derivative of the measurement components to be processed with respect to state variables and model parameters. The equations for these partial derivatives are presented in Section VII of Volume I. The partial derivatives are located in an array G(i,j) where i denotes the measurement vector components or rows. The rows of G are arranged similar to the elements of DATC(i), not necessarily sequentially with component number.

b. PROP: Subroutine PROP propagates the covariance and correlation matrices to the current measurement time by means of equations (54). Because the covariance matrix P is symmetric, only its upper right triangle is propagated. Before returning from PROP, the state transition matrix ϕ is reinitialized to the identity matrix.

c. MINVAR: Subroutine MINVAR next solves the minimum variance equations, equations (53). Rather than introduce additional FORTRAN variables, the dummy array DUB(i,j) is used throughout MINVAR. The order in which equations are solved and the location in DUB where the matrices are solved are as follows. Equation (53f) is first synthesized. The matrix product PG^T and GPG^T are calculated (using only the upper right triangle of P) and stored in DUB(1-3, 1-3) and DUB(1-3, 7-9), respectively. For convenience, a mapping of DUB is shown below. If uncertain measurement parameters are included ($NPV > 0$) then $GC_{vz}H^T$ and SH^T are calculated and stored in DUB (1-3, 7-9) and DUB (13-15, 7-9). $C_{vz}H^T$ is also added to PG^T in DUB (1-3, 1-3). Inspection of equations (53e) and (53f) reveals the J is being accumulated in DUB (1-3, 7-9) and the matrix $PG^T + C_{vz}H^T$ in DUB (1-3, 1-3). MINVAR continues to calculate matrix products and accumulating matrix sums using DUB as shown below.



The matrix J is inverted by means of the Gauss-Jordan reduction method coded in MINVAR. The 3×3 matrices shown in DUB are only calculated when a three-component vector is being processed. When the measurement vector contains fewer components, the matrices are smaller (2×2 or 1×1).

Because of the dependency of e_3 on e_0 , e_1 , and e_2 the tenth column of G , and the tenth row and column of P and the tenth rows of C_{uz} and C_{vz} are set to zero before their calculations in MINVAR. This produces the same results as not having the rows and columns to begin with. Before returning from MINVAR, these rows and columns of P , C_{vz} , and C_{uz} are calculated by equations (163) and (164). The correction for e_3 , is calculated from equation (162).

4. Smoothing.- When the forward integration is completed, subroutine SMOOTH is called to integrate the best estimate of the state, and possibly covariance, back to initial time. SMOOTH commences by testing program controls to determine if the residuals and loss function are to be calculated, if the linear equations of motion are to be integrated to propagate the covariance and correlation matrices, or if smoothing is even to be performed. The flag KSM is set to zero if the residuals and loss function are not to be calculated, and to one if they are to be calculated. NPC(1) is temporarily reset to 1 if the linear equations are not to be integrated. SMOOTH then proceeds to integrate backwards in INTAG to either a block print time, ET, or a measurement data time TIME. The measurement data are obtained from the SCRACH tape. OBSERV is called to calculate the best estimate of the measurement. During the backward integration, OBSERV returns after calculating only the nonlinear measurements. After SMOOTH has integrated back to the initial time, it resets counters, triggers, and tapes for the next iteration or problem before returning.

5. Output.- Subroutine OUTPUT performs all the block printing on both the forward and backward integration. The variables printed are described in Subsection II.C.2. If a state update has occurred before OUTPUT, MOTION is called, via entry point AUXIL, to recalculate auxiliary variables needed for outputting. After the state and auxiliary variables have been printed, the covariance and correlation matrices are transformed to output variables specified by NPC(3). This transformation is described in Section VI of Volume I. The transformation matrix N_0 is

stored in the DUB(i,j) array as follows:

$$N_0^T(1-3, 1-10) = \text{DUB}(1-10, 1-3)$$

$$N_0^T(7-9, 1-10) = \text{DUB}(1-10, 4-6)$$

The middle three rows of N_0 contain only the identity matrix for h , φ , and θ so they are not stored.

V. DEFINITION OF FORTRAN SYMBOLS

A(i, j)	Transformation matrix G between the G-frame and B-frame, see equation (133).
AB(i), AC(i)	Accelerations a_{XB} , a_{YB} , a_{ZB} acting through the center of gravity in body axes directions, see equations (134) and (146).
AG(i)	Accelerations a_{XG} , a_{YG} , a_{ZG} in the G-frame axes directions, see equation (132).
ALPH	Angle of attack, α , see equation (135).
AM(i)	Accelerations a_{XM} , a_{YM} , a_{ZM} modeled or measured at the inertial measuring unit in body axes directions with systematic error included, see equations (159) and (258).
AMDOT(i)	Time derivative of a_{XM} , a_{YM} , a_{ZM} , see equation (160).
AP(i)	AP(1-3) are accelerations a_{XP} , a_{YP} , a_{ZP} acting at the inertial measuring unit in body axes directions without systematic error; AP(4) is \bar{a}_p , see equations (158) and (159).
APDOT(i)	Time derivatives of a_{XP} , a_{YP} , a_{ZP} , and \bar{a}_p , see equations (160) and (157).
AS	Speed of sound c_s , see equation (125).
ASU	Sutherland constant, S, see equation (126).
AX(i), AY(i), AZ(i)	Tabular array of the accelerations a_{XM} , a_{YM} , a_{ZM} from the PQR tape.
B(i)	Array used in INDAT to input A-format information.
BETA	Sideslip angle, β , see equation (136).

C(i) Model parameters C_1, C_2, \dots, C_{152} .

CALP Cosine of the angle of attack, α , in equation (135).

CBET Cosine of the sideslip angle, β , in equation (136).

CCAPHI(i) Cos Φ corresponding to tracking station i , see equation (236).

CDP Cosine pitch angle δ_P in equation (269).

CDY Cosine yaw angle δ_Y in equation (269).

CETA Cosine of total angle of attack, η in equations (137) and (187).

CF(i) Array containing the aerodynamic coefficients $-C_A, C_Y, -C_N$.

CGR Cosine γ_R in equation (271b).

CGM(i) Modeled distances, $x_{PM}, y_{PM},$ and z_{PM} , from the center of gravity to the IMU along the body axes directions.

CI(i,j) Matrix inverse, C^{-1} calculated in OBSERV, see equation (266).

CJ(i,j) Product of matrix inverse in equation (259) times the transformation matrix involving P, Q, and R in equation (260); calculated in OBSERV.

CLR Cos λ_R in equation (271a).

CONRD Conversion from degrees to radians; equal to 0.017453292.

CPH Cosine of geocentric latitude φ .

CPHIDT(i) Cos φ_{DT} corresponding to tracking station i , see equation (237).

CT(i) Dummy array of cosines used in SETUP and OUTPUT for $\cos \gamma_A$, $\cos \lambda_A$, $\cos \frac{\psi}{2}$, or $\cos \frac{\sigma}{2}$, $\cos \frac{\theta}{2}$, $\cos \frac{\beta}{2}$, and $\cos \frac{\phi}{2}$ or $\cos \frac{\alpha}{2}$.

CTM(i) Used in OBSERV for calculating R_c , A_c , E_c , \dot{R}_c , \dot{A}_c , and \dot{E}_c , respectively from equations (238) and (240).

CUZ(i,j), CVZ(i,j) Correlation matrices C_{uz} and C_{vz} , see equations (53) and (54).

CXZI Cosine of the steering angle, ξ , in equations (138) and (187).

D(i) Variances of uncertain model parameters not being estimated, see equations (41) and (54).

DADX(i,j) Partial derivatives of α and β with respect to state variables, see equation (186).

DAT(i,j) Array of data from FIT tape that is stored in core; subscript i indicates component.

DATA(i) Components of the current measurement vector being processed; see MAIN and MINVAR.

DATAS(i) Components of the next measurement vector to be processed; see MAIN.

DATC(i) Measurement vector calculated in OBSERV; note that DATC(1), DATC(2), and DATC(3) do not correspond to the components of the data vector but to only those components to be processed, e.g., $DATC(1) = E_M$, $DATC(2) = A_M$ if R_M is edited out.

DCDY(i,j) Partial of $-C_A$, C_Y , $-C_N$ with respect to V_A , h_o , α , and β , see equation (186).

DCOMP	Fixed computing interval for the numerical integration.
DERIV(i,j)	Partial of a_{XB} , a_{YM} , a_{ZB} with respect to state variables, see equations (182) and (184).
DET	Print interval for block output.
DFIT(i)	Minimum time span between data points processed from the FIT tape of measurement type i.
DFM(i)	Components 1, 2, and 3 of the calculated measurement vector in OBSERV.
DPH(i,j)	Time derivative of the dependent variable in the linear differential equations of motion; equivalently the time derivative of the state transition matrix.
DRDH	Partial derivative of ρ with respect to h_o in equation (185).
DRDP	Partial derivative of r with respect to ϕ .
DTI(i)	Time to commence processing data of type i.
DTF(i)	Time to stop processing data of type i.
DTRAN(i,j)	Transformation matrix in equation (189).
DUB(i,j)	Dummy array used throughout program; especially in SETUP and OUTPUT for input/output transformations N_I and N_o , and in MINVAR.
DUD(i)	Dummy array.
DUE(i)	Dummy array.
DUF(i)	Dummy array.
DWDH(i)	Array containing du_{WM}/dh_o and dv_{WM}/dh_o calculated in DERIV.

DX(i) Time derivatives of the internal state variables and state transition matrix.

DZ(i) Expanded state variable perturbations $\hat{z}(t_i | t_1)$ calculated in MINVAR, see equation (54a).

ET Time to print block output.

F1(i,j) Coefficients of first three linear differential equations of motion calculated in MOTION and FXXU; also used in OBSERV for calculating adjoint matrix in equation (264).

F2(i,j) Coefficients of middle three linear differential equations of motion.

F3(i,j) Coefficients of last four linear differential equations of motion.

FIT Logical tape number of the FIT tape, Fit = 1.

FLOS Loss function calculated in SMOOTH.

G(i,j) Partial derivative of the measurement vector with respect to expanded state vector components, G, see equation (6b).

GG(i) Temporary storage for each column of G(i,j) as they are calculated in OBSERV.

H(i,j) Partial derivative of the measurement vector with respect to uncertain measurement vector components, see equations (51a) and (51b).

HI(i) Dummy array.

HO Altitude above an oblate planet surface.

ICOUNT Iteration counter.

IDN Dummy integer variable used in INDAT.

II Dummy integer variable.

IN Logical input tape number, IN = 5.

IP	Dummy integer variable.
IPC	Temporary storage for input controls.
JJ	Dummy integer variable.
JN	Dummy integer variable.
JNBR	Number of components to be processed in the current measurement vector.
JNBRS	Number of components to be processed in the next measurement vector.
JST	Specified in MAIN to be 1 if only one measurement is to be processed at time TIME; JST > 1 if more than one vector measurement is to be processed at TIME.
KA	Dummy variable.
KAR	Index on loop through OBSERV, PROP, and MINVAR, see MAIN program.
KC(i)	Point numbering array used when printing the measurement schedule in OBSERV.
KD(i)	Point numbering array used in SMOOTH for printing the residuals.
KDAP	Number of points on PQR tape record, see DATAB.
KDATA	Number of points on previous FIT tape record, see MAIN.
KDATAS	Number of points on present FIT tape record, see MAIN.
KDUM	Dummy variable in INDAT.
KG	Counter for acceptable data points read from the FIT tape, which are stored in core and either have been or are to be processed.

: KG2 Number of measurement points from FIT tape
 that are written on the SCRACH tape in
 DATAB.

: KK Number of times loop is traversed between
 OBSERV and MINVAR in MAIN.

KN Flag set in MAIN to 0 if the reference is
 updated between processing of the measure-
 ment components; KN = 1 if state is not
 updated between component processing.

KØB Largest measurement vector component to be
 processed in MINVAR; loop goes from
 KAR to KØB; KØB is set in OBSERV.

KPROP Indicator that is initialized -1 in SETUP,
 is set to 0 after each minimum variance up-
 date, and set to 1 after each propagation;
 see figure 4.

KS Number of FIT tape measurement vectors
 stored in core; updated in MAIN.

: KSS Number of tracking stations whose location
 is being estimated.

: KSM Indicator in SMOOTH; if KSM = 0, do not
 calculate residuals; if KSM = 1, calculate
 residuals and loss function.

K1 Dummy variable.

LC(i) Array containing the component numbers of
 the current measurement vector DATA(j)
 to be processed, e.g., LC(1) = 2, LC(2) =
 3 if component 1 is edited out.

LCS(i) Same as LC(i), but corresponding to the
 next data vector DATAS(j).

: LS Number of PQR tape points that are stored
 in the arrays TT(i), TP(i) . . . AZ(i);
 counter is updated in DATAB.

: LT Dummy variable.

L1 Flag used to determine if fitting schedule title should be printed from OBSERV; print titles if $L1 = 2$, do not print if $L1 \neq 2$; also used to print residual schedule titles in SMOOTH if $L1 \neq 0$, and used as a transfer flag at return from SMOOTH; If $L1 = 0$, start next problem, if $L1 = 1$, start next iteration.

MC(i) Array containing the identification numbers for variables in U, the uncertain model parameters not to be estimated.

MCC(i) Array containing the identification numbers for variables in V, the uncertain measurement parameters not to be estimated.

MØ(i) Flag set to 1 if rate terms are included in the radar tracking error model, equation (239), from station i; otherwise zero.

MR(i,j) Flag equal to 1 if component i of measurement type j of the FIT tape data is to be processed; flag equals 0 if not to be processed.

MTP(i) Array containing the data type identification number corresponding the FIT tape data that has been read into core.

MTP Measurement data type identification number for current measurement to be processed MTP = 1, 2, 3, 4, 5 for radar tracking from stations 1, 2, 3, 4, 5; = 6 for airborne radar; = 9 for accelerations; = 8 for position vector; and = 7 for velocity vector.

MTYPS Same as MTP, but corresponds to next data vector to be processed.

NC(i) Array containing the identification numbers for model parameters to be estimated.

NCOUNT Processing measurement point counter.

NNN Dummy variable.

NPC(i) Program controls specified in INDAT, see Section II.A.2.

NPTS Dummy variable used in INDAT to denote the number of points on a table; one point consists of two scalar numbers, the independent variable and dependent variable.

NPU Number of components in U, the uncertain model parameter vector not to be estimated.

NPV Number of component in V, the uncertain measurement parameters not to be estimated.

NS(i) Array containing the measurement type indicators (MTYP) for measurement to be processed from FIT tape; NS(i) is set in INDAT.

NSS(i) Array containing the station numbers of radar stations whose location is to be estimated.

NST Counter for state variable components input in INDAT.

NSTA Measurement data type counter input in INDAT.

NSTC Counter for model parameters which are to be estimated.

NSTX Number of components in expanded state vector to be estimated; NSTX = 10 + NSTC.

NT Dummy variable.

NTR(i) Flag used in editing measurement type i in MAIN; NTR(i) is initialized to zero at beginning of problem; thereafter, NTR(i) = 2 indicates the last fitting point was accepted, = 3 indicates the last fitting point was rejected.

N4(i) Array used by TAB for interpolating $m_M(t)$ table.

N5(i)	Array used by TAB for interpolating $u_{WM}(h)$ table.
N6(i)	Array used by TAB for interpolating $v_{WM}(h)$ table.
NS(i)	Array used by TAB for interpolating $x_{PM}(t)$ table.
N9(i)	Array used by TAB for interpolating $y_{PM}(t)$ table.
N10(i)	Array used by TAB for interpolating $z_{PM}(t)$ table.
N11(i)	Array used by TAB for interpolating $P_M(t)$, $Q_M(t)$, $R_M(t)$ tables.
OMEGA	Planet rotation rate Ω_P .
ØUT	Logical output tape number, ·OUT = 6.
P(i, j)	Covariance matrix P.
PA(i)	Inertial angular rates, P, Q, R calculated in MOTION.
PAR(i)	Parameters calculated in MOTION and subsequently used in other subroutines.
PAXP(i, j)	Partial of a_{XP} , a_{YP} , a_{ZP} with respect to state variables, see equation (189).
PDOT(i)	Time derivative of P, Q, and R calculated in MOTION.
PE	Atmospheric pressure calculated in ATMDAT from equation (123).
PH(i, j)	State transition matrix ϕ .
PHIDT(i)	Geodetic latitude of tracking station i.
PM(i)	Measured inertial angular rates P_M , Q_M , and R_M .

PMDOT(i) Time derivatives of P_M , Q_M , and R_M .

PQR Logical tape number of the PQR tape, PQR = 2.

R Radial distance from planet center to vehicle, r .

RCC(i) Partial derivatives of R_c , A_c , E_c with respect to C_i calculated in OBSERV from equation (250).

RCDC(i) Partial derivatives of \dot{R}_c , \dot{A}_c , \dot{E}_c with respect to C_i , calculated in OBSERV from equation (251).

RCDX(i,j) Partial derivatives of \dot{R}_c , \dot{A}_c , \dot{E}_c with respect to u , v , w , h , ϕ , θ calculated in OBSERV from equation (245).

RCX(i,j) Partial derivative of R_c , A_c , E_c with respect to h , ϕ , θ calculated in OBSERV from equation (244).

RØ Equatorial radius of planet, R_E .

RERP2 Parameter $(R_E/R_P)^2$.

RES(i) Residuals and weighted residuals in SMOOTH.

RØ Radius of oblate planet, R_O .

RØE Atmospheric density corrected for systematic error in MOTION from equation (151).

RØEC The exponential portion of the atmospheric density correction; calculated in MOTION from equation (151).

RØEM Modeled atmospheric density ρ_M , transferred to MOTION from ATMDAT where it is calculated via equation (124).

RPØ	Polar radius of planet.
RT(i)	Radial distance from planet center to tracking station i.
ROT(i)	Radius of oblate planet at latitude of tracking station i.
S(i)	Variances of uncertain measurement parameters not being estimated, see equations (44) and (53).
SALP	Sine of angle of attack α , see equation (135).
SBET	Sine of sideslip angle β , see equation (136).
SCAPHI(i)	Cos ϕ corresponding to tracking station i.
SCRACH	Logical tape number of the SCRACH tape, SCRACH = 3.
SDP	Sine of pitch angle δ_p in equation (269).
SDY	Sine of yaw angle δ_y in equation (269).
SETA	Sine of total angle of attack η , see equation (137).
SGR	Sin γ_R in equation (271b).
SI(i)	Standard deviations of the fitting measurements processed in MINVAR.
SIG(i,j)	Array of standard deviations from FIT tape, which are stored in core.
SIGM(i)	Standard deviations of measurement vector currently being processed.
SIGMS(i)	Standard deviations of next measurement vector to be processed.

SLR	Sin λ_R in equation (271a).
SP(i)	Scratch pad or dummy variable used throughout program.
SPD(i)	Scratch pad or dummy variable used throughout program.
SPH	Sine of the geocentric latitude ϕ .
SPHIDT(i)	Sin ϕ_{DT} corresponding to tracking station i, see equation (237).
SREF	Reference area for aerodynamic coefficients.
ST(i)	Dummy array of sines used in SETUP and OUTPUT for $\sin \gamma_A$, $\sin \lambda_A$, $\sin \frac{\psi}{2}$, or $\sin \frac{\sigma}{2}$. $\sin \frac{\bar{\theta}}{2}$, or $\sin \frac{\beta}{2}$, and $\sin \frac{\bar{\phi}}{2}$, or $\sin \frac{\alpha}{2}$.
STATE	Logical tape number for STATE tape, STATE = 4.
SUM	Dummy variable use primarily for accumulating matrix products.
SUM2	Dummy variable used similarly to SUM.
SXZI	Sine of steering angle ξ , see equation (138).
SYG(i,j)	Incremental standard deviations on component i of measurement type j input in category 7 input.
T	Running variable for time used in RKUTTA.
TABLES(i,j)	Array containing all three aerodynamic coefficient tables in AERO.
TAU	Time increment $t-t_1$ calculated in MOTION from equation (150).
TCX(i)	First aero table C_A or C_D in AERO; note TCX(i) is equivalent to TABLE(i,1).

TCY(i)	Second aero table C_Y in AERO; note TCY(i) is equivalent to TABLE (i,2).
TCZ(i)	Third aero table C_N or C_L in AERO; note TCZ(i) is equivalent to TABLE(i,3),
TFIT(i)	Minimum time for processing the next type i measurement in MAIN; all type i data before TFIT(i) will be rejected.
TFINAL	Final problem time; stop the forward integration after the first block printout that equals or exceeds TFINAL.
TIME	Time corresponding to the current measurement vector being processed.
TIMES	Time corresponding to the next measurement vector to be processed.
TMAS(i)	Independent variable on the vehicle mass table $m_M(t)$.
TØ	Time to initiate integration in INTAG
STONE	Time t_1 at which mass correction commences, see equations (149) and (150).
TP(i)	Table containing the inertial angular rate data, P_M , read from the PQR tape.
TPH	Tangent of geocentric latitude ϕ .
TQ(i)	Table containing the inertial angular rate data, Q_M , read from the PQR tape.
TR(i)	Table containing the inertial angular rate data, R_M , read from the PQR tape.
TRAN(i,j)	Transformation matrix containing P, Q, and R in equation (146).
TT(i)	Table containing the independent variable (time) for TP(i), TQ(i), TR(i) and AX(i), AY(i), AZ(i) (STEP2 only).

TTWO Time t_2 at which mass correction stops, see equation (149) and (150).

TUW(i) Independent variable on atmospheric wind table $u_{WM}(h_o)$.

TVW(i) Independent variable on atmospheric wind table $v_{WM}(h_o)$.

TXCG(i) Table containing the independent variable (time) for $x_{PM}(t)$.

TYCG(i) Table containing the independent variable (time) for $y_{PM}(t)$.

TYM(i) Table containing the measurement data times from the FIT tape.

TZCG(i) Table containing the independent variable (time) for $z_{PM}(t)$.

TZERØ Initial problem time.

T2 Time to stop the integration in INTAG and return to the point where INTAG was called.

UW Atmospheric wind component u_w calculated in MOTION from equation (152).

VA(i) Array containing u_A , v_A , w_A , V_A , and V_A^2 , calculated in MOTION from equations (140) and (141).

VB(i) Components of V_A in body axes directions, u_B , v_B , w_B ; calculated in MOTION from equation (139).

VØ(i) Dummy array used for temporary storage.

VW Atmospheric wind component v_w calculated in MOTION from equation (152).

X(i) Dependent variables in the nonlinear differential equations of motion.

XA(i) Array containing a_1, a_2, \dots, a_5 in equation (277).

XAX(i,j) Partial derivatives of a_1, a_2, \dots, a_5 with respect to $h, \varphi, \theta, e_0, e_1, e_2, e_3$; calculated in OBSERV from equation (283).

XC(i) Array containing C_1, C_2, C_3 ; calculated in OBSERV from equation (276).

XCX(i,j) Partial derivatives of C_1, C_2, C_3 with respect to $h, \varphi, \theta, e_0, e_1, e_2, e_3$; calculated in OBSERV from equation (282).

XIND1 } Independent variable α, β or η, ξ
XIND2 } used in AERO to calculate aerodynamic coefficients.

XJ2 Coefficient of the second gravitational harmonic, J_2 , see equation (106).

XLB(i) Direction cosines l_B, m_B, n_B ; calculated in OBSERV from equation (269).

XLG(i) Direction cosines l_G, m_G, n_G ; calculated in OBSERV from equation (270).

XLGE(i,j) Partial derivatives of l_G, m_G, n_G with respect to e_0, e_1, e_2, e_3 ; calculated in OBSERV from equation (286).

XLGX(i,j) Partial derivatives of λ_R and γ_R with respect to e_0, e_1, e_2, e_3 ; calculated in OBSERV from equations (284) and (285).

XLREF Vehicle reference length, l , used in calculating Reynolds number, see equation (148).

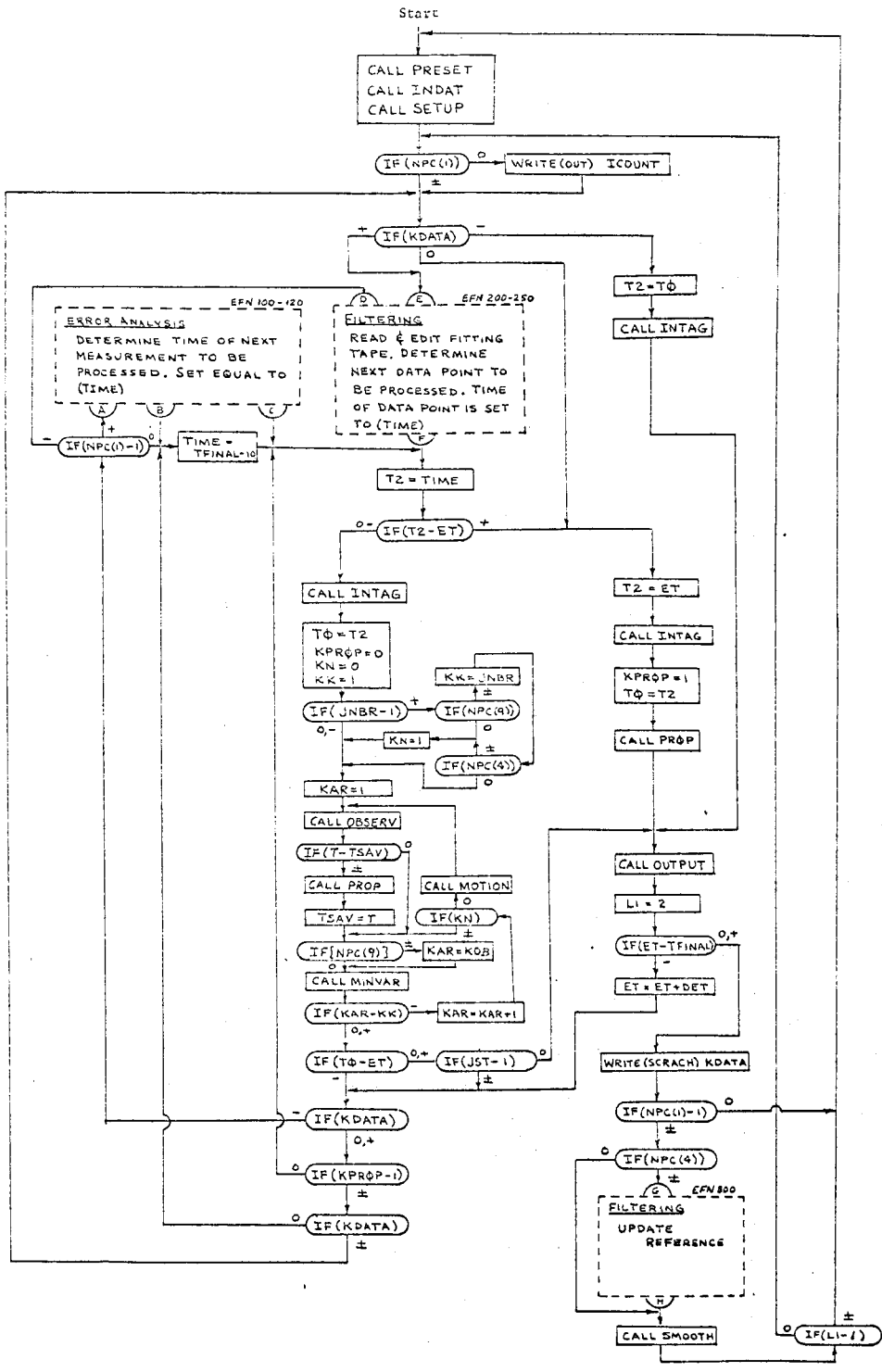
XM Mach number, M ; calculated in MOTION from equation (143).
 :
 XMAS(i) Dependent variable on the $m_M(t)$ table.
 :
 XMU Coefficient of the first gravitational harmonic μ ; see equation (106).
 XMUJ The product $2 \mu J$; see equation (106).
 XNU Atmospheric viscosity μ_A ; transferred to MOTION from ATMDAT where it is calculated via equation (126).
 XP(i) The center-of-gravity/IMU distances x_p , y_p , z_p in equation (153).
 XQ Dynamic pressure, q ; calculated in MOTION from equation (142).
 XQSM Parameter equal to $XQ*SREF/YMAS$ calculated in MOTION.
 XRE Reynolds number, R_E ; calculated in MOTION from equation (148).
 :
 XS(i) Cartesian components of the radar tracking vector, x_s , y_s , z_s ; calculated in OBSERV from equation (235).
 :
 XSC(i) Partial derivatives of x_s , y_s , z_s with respect to C_{88} , C_{89} or C_{90} ; calculated in OBSERV from equation (252).
 XSD(i) Time derivatives \dot{x}_s , \dot{y}_s , \dot{z}_s calculated in OBSERV from equation (241).
 XSDC(i) Partial derivatives of \dot{x}_s , \dot{y}_s , \dot{z}_s with respect to C_{88} , C_{89} , or C_{90} ; calculated in OBSERV from equation (253).
 :

XDSX(i,j)	Partial derivatives of \dot{x}_s , \dot{y}_s , \dot{z}_s with respect to u , v , w , h , ϕ , θ ; calculated in OBSERV from equation (247).
XSX(i,j)	Partial derivatives of x_s , y_s , z_s with respect to h , ϕ , θ calculated in OBSERV from equation (246).
XTEMP	Atmospheric temperature transferred to MOTION from ATMDAT.
XUW(i)	Dependent variable on atmospheric wind table $u_{WM}(h_o)$.
XVW(i)	Dependent variable on atmospheric wind table $v_{WM}(h_o)$.
XXCG(i)	Dependent variable on $x_{PM}(t)$ table, see equation (153).
XYCG(i)	Dependent variable on $y_{PM}(t)$ table, see equation (153).
XZCG(i)	Dependent variable on $z_{PM}(t)$ table, see equation (153).
XZI	Steering angle ξ , see equations (138) and (187).
YMAS	Vehicle mass, m , corrected for systematic error; calculated in MOTION from equation (149).
YMASM	Vehicle mass as interpolated from the model mass table.
ZØ(i)	Dummy array used for temporary storage.

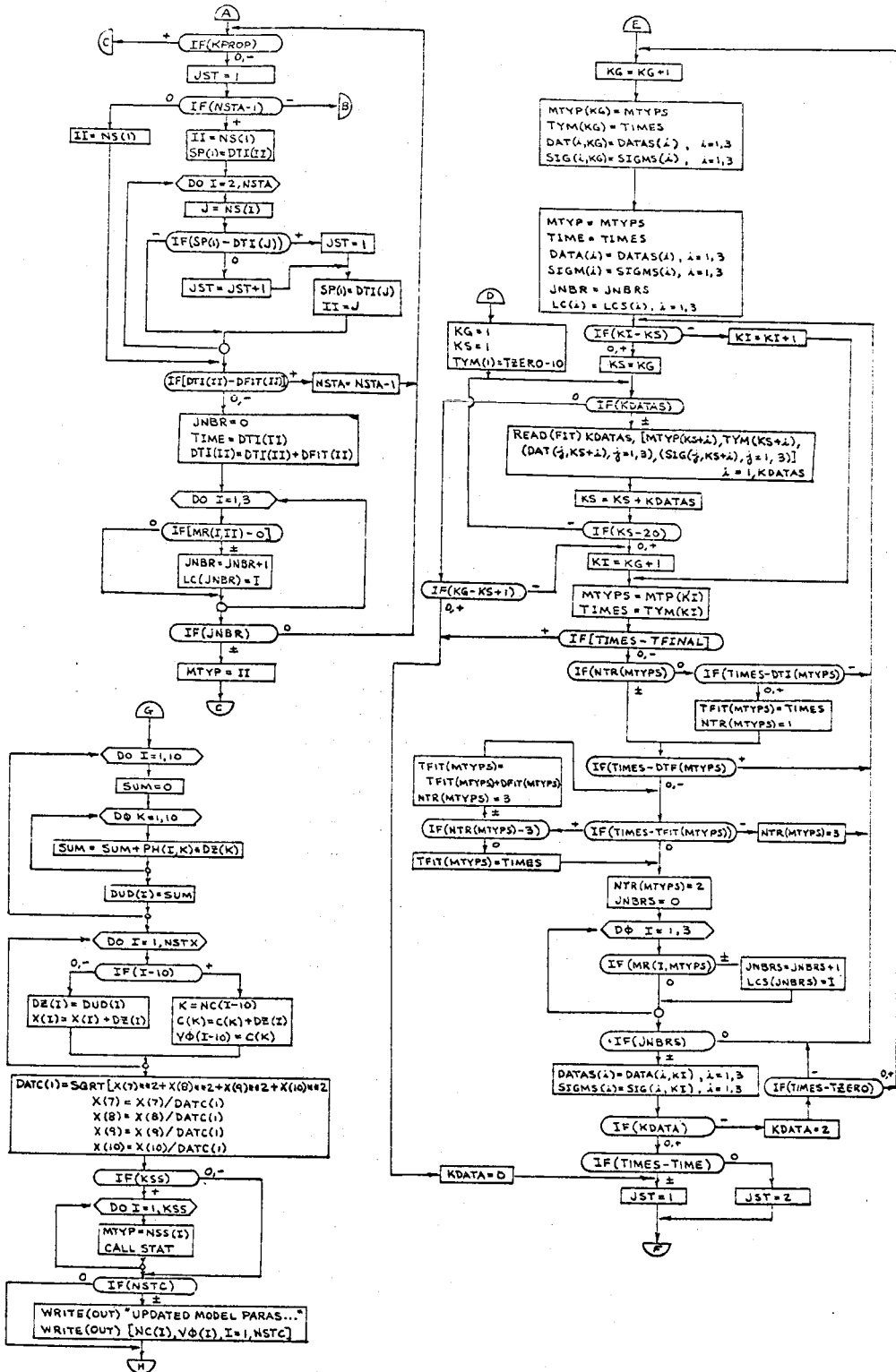
VI. FLOW DIAGRAMS

Subroutine flow diagrams are presented in this section. The following listing indicates the page on which the various flow diagrams appear.

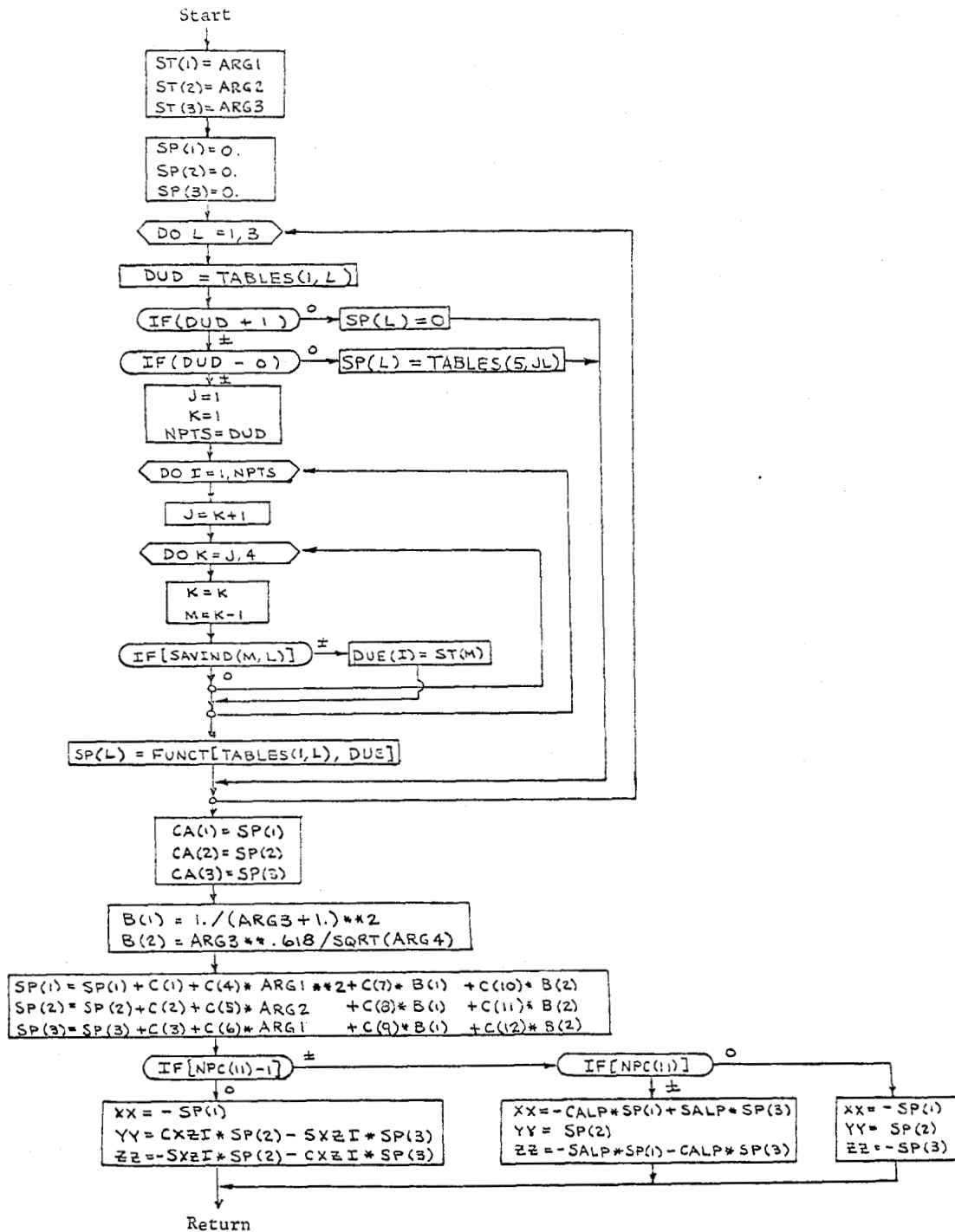
<u>Subroutine</u>	<u>Page</u>
MAIN	98
AERO	100
AEROIN	101
ATMDAT	102
DATAB	103
DERIVE	104
FXXU	105
INDAT	111
INTAG	114
MINVAR	115
MOTION	118
OBSERV	120
OUTPUT	124
PRESET	127
PROP	128
RKUTTA	129
SETUP	130
SMOOTH	134
STAT	135
CRV	136
FUNCT	136
TAB	136



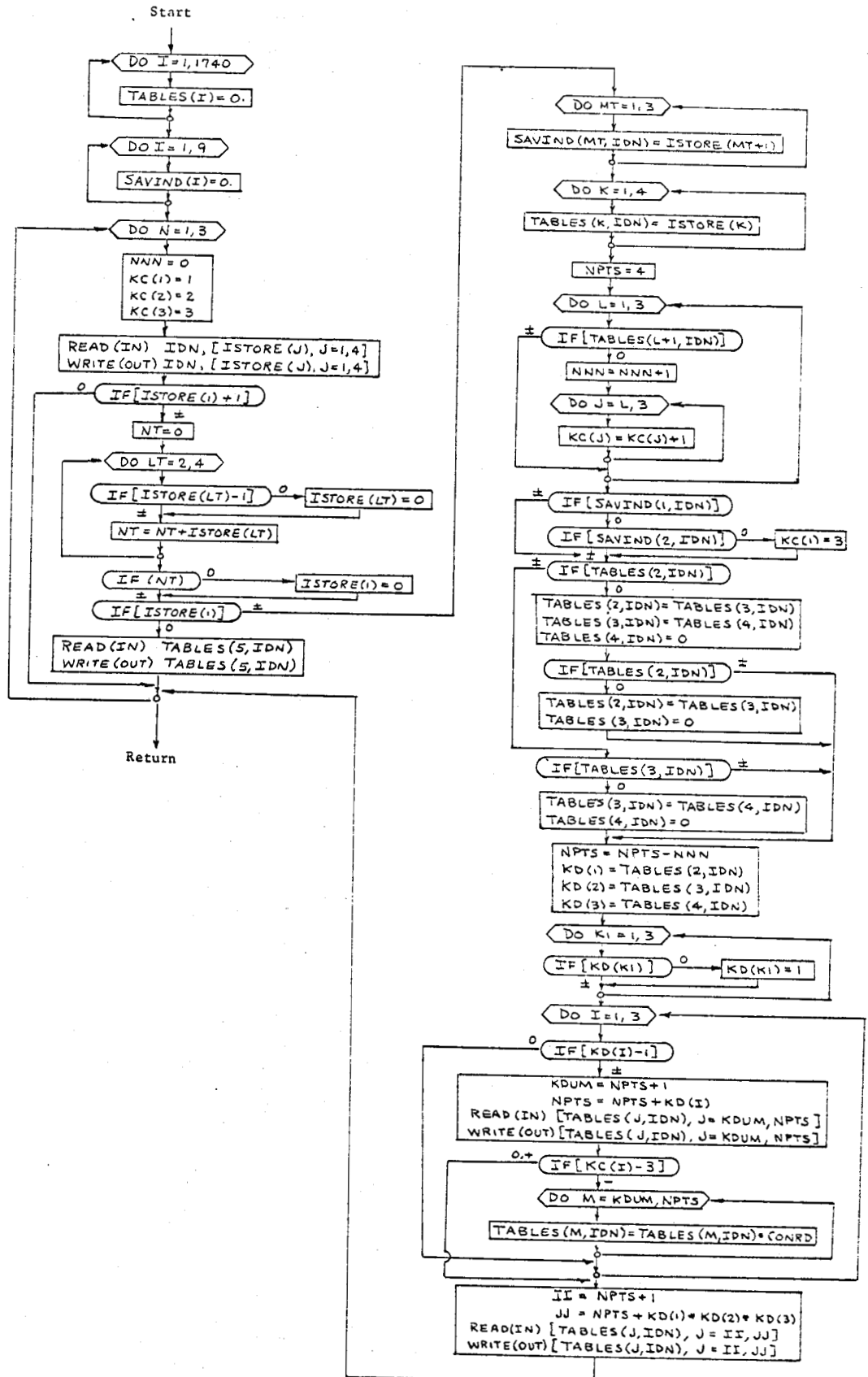
MAIN Program

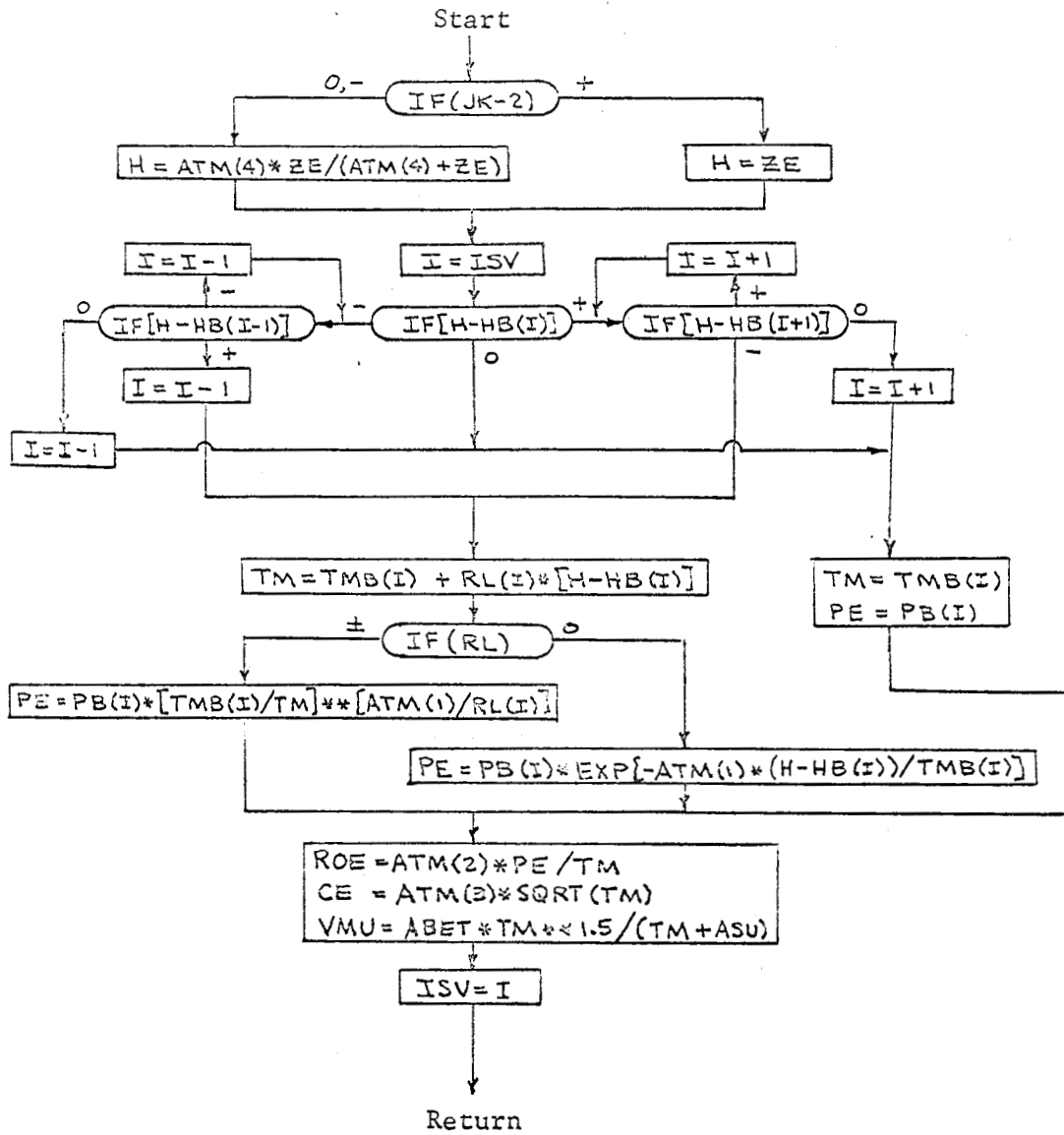


MAIN Program - Concluded

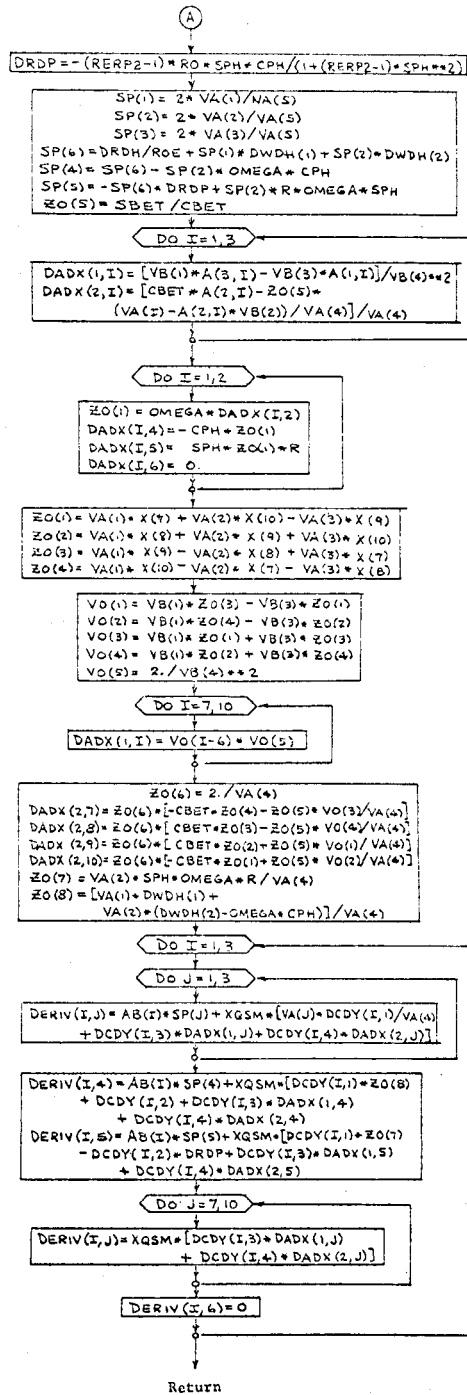
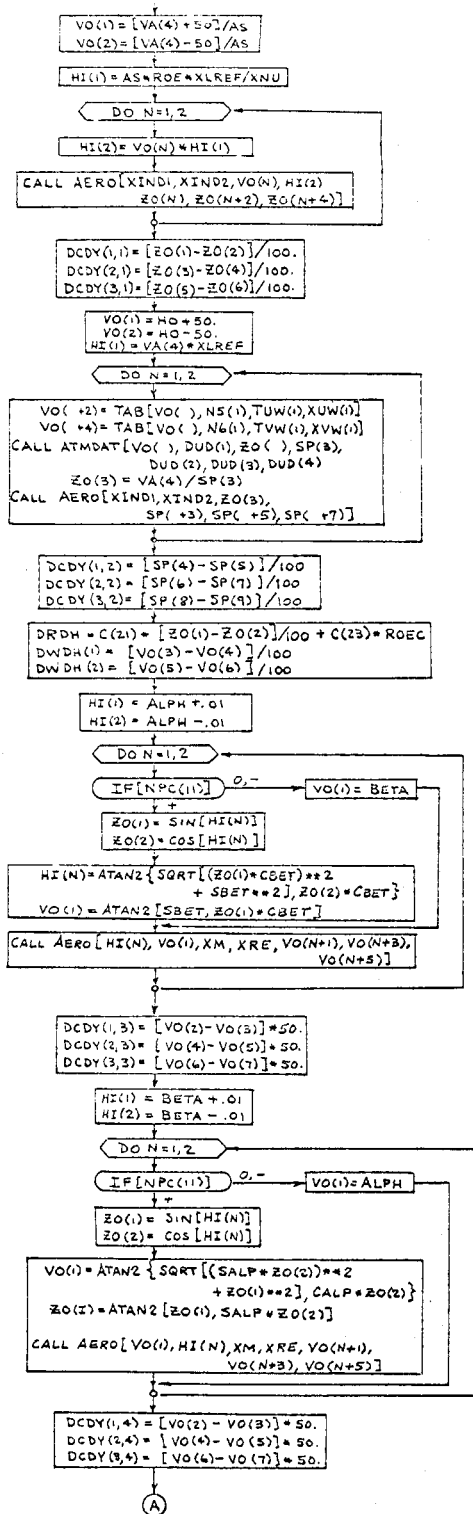


Subroutine AERO (ARG1, ARG2, ARG3, ARG4, XX, YY, ZZ)





Subroutine ATMDAT (ZE, PE, ROE, CE, TM, VMU, ISV)



Subroutine DERIVE

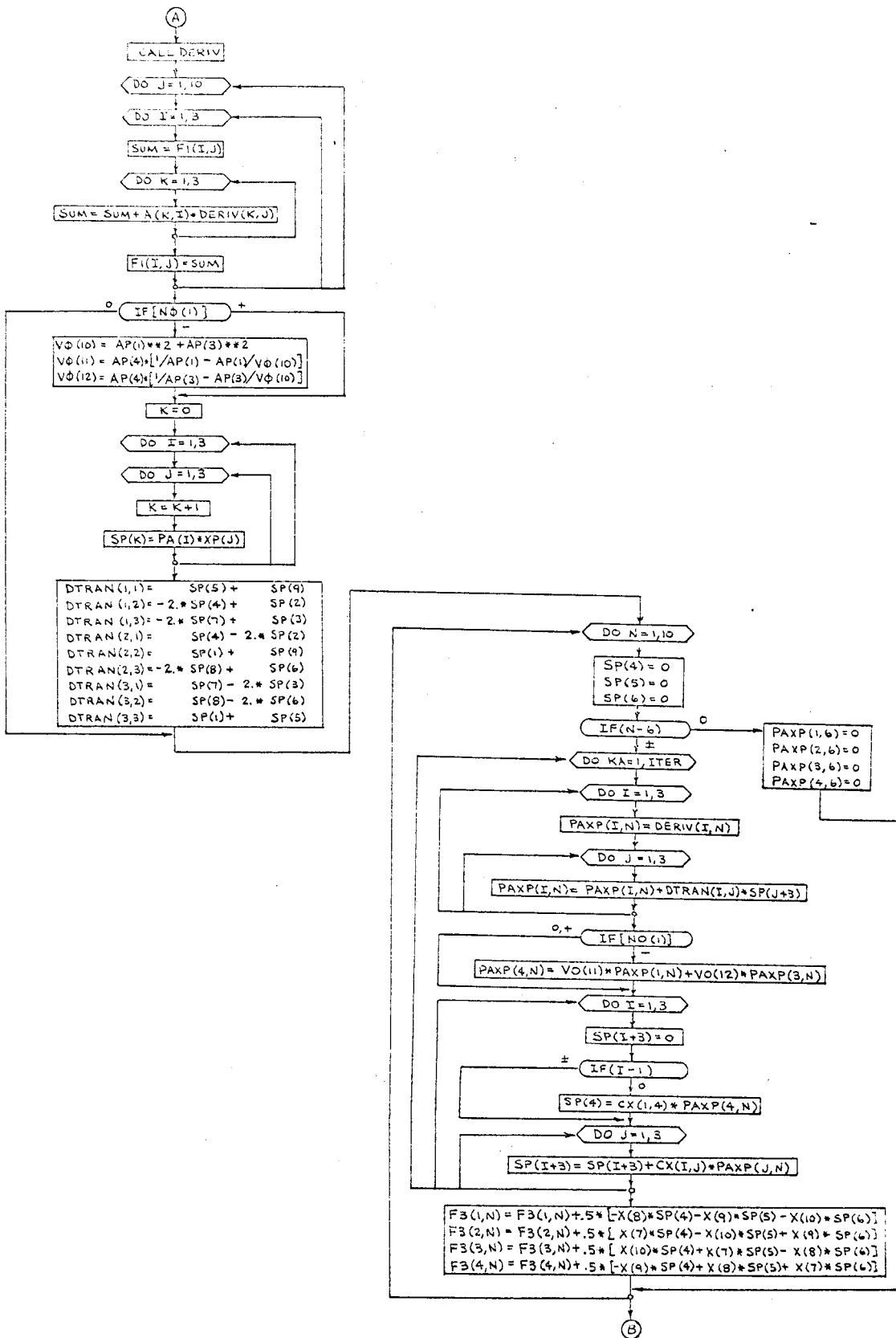
Start

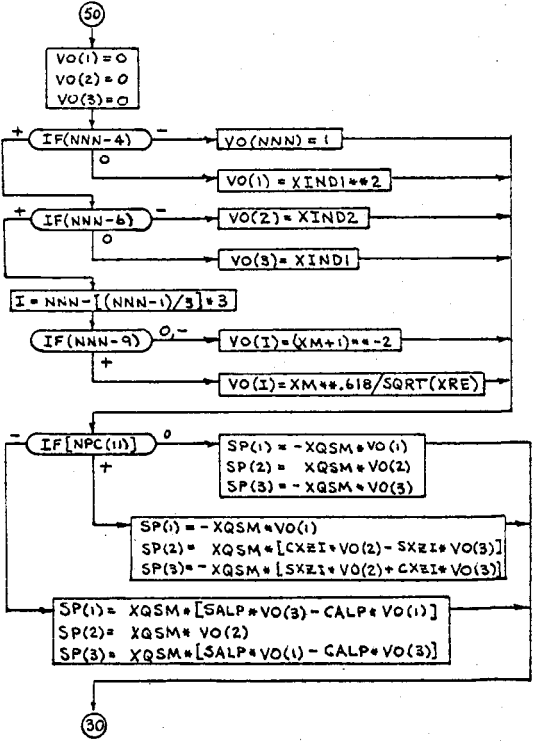
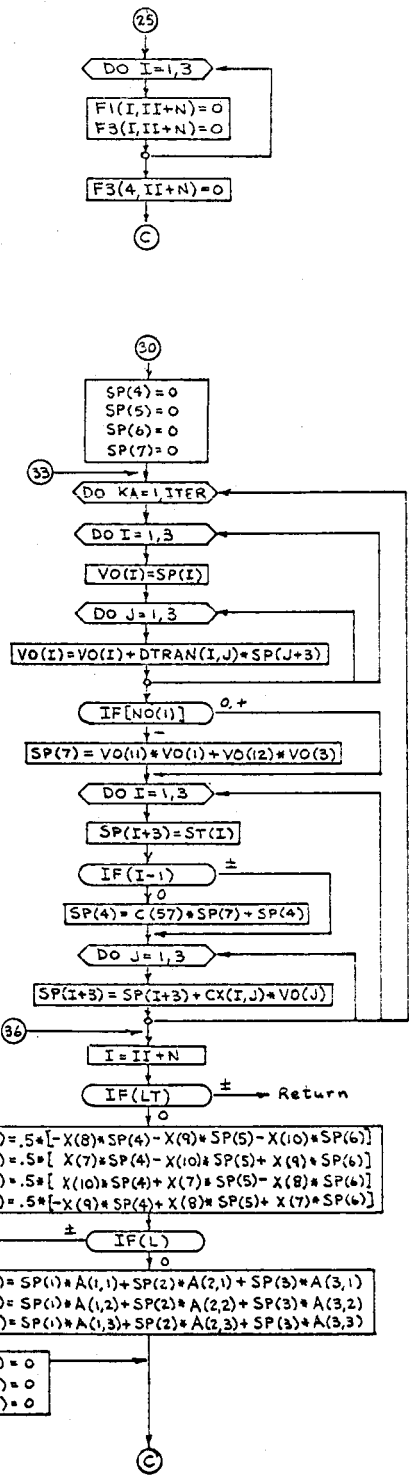
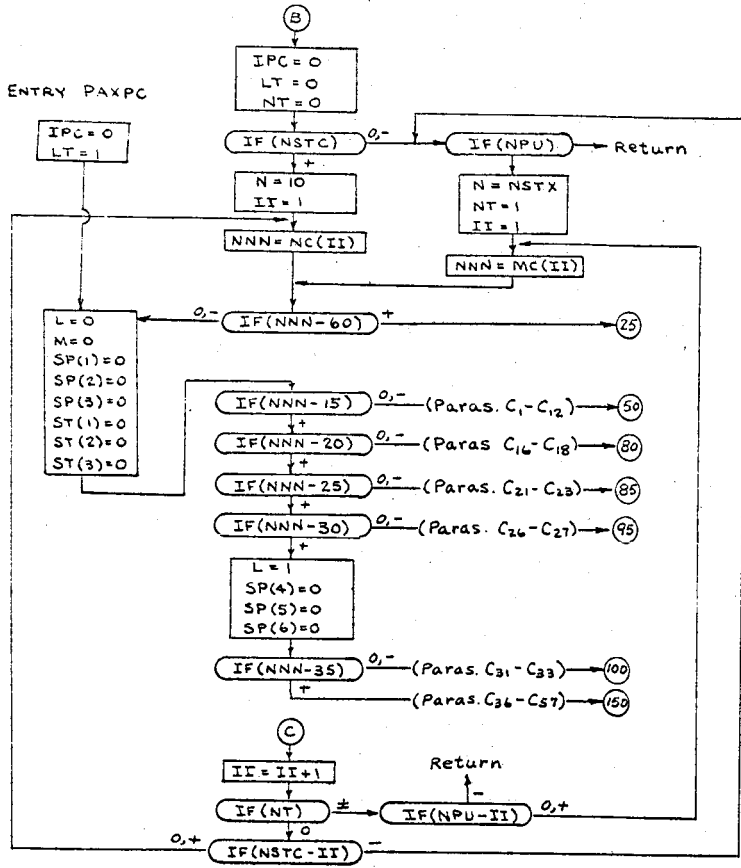
```
SP(1) = PAR(4)*X(2)/CPH**2
F2(2,1) = 1./R
F1(1,3) = F2(2,1)*X(1)
F1(3,1) = -F1(1,3) - F1(1,3)
F1(3,2) = -F1(2,3) - F1(2,3)
F1(1,1) = F2(2,1)*X(3)
F1(1,2) = -F1(2,1) - F1(2,1)
F1(1,4) = [-PAR(5)*F2(2,1)
+ 4*PAR(3)*SPH*CPH]*F2(2,1)
F1(1,5) = SP(1)*F1(3,2)*R
- PAR(3)*(CPH+SPH)*(CPH-SPH)
F1(2,4) = -F1(2,2)*F1(2,3)
F1(2,5) = -SP(1)*F1(3,1)*R
F1(3,4) = [PAR(1)*F2(2,1)-PAR(2)
- PAR(2)+4*PAR(3)*PAR(6)]*F2(2,1)
F1(3,5) = -3.*PAR(3)*SPH*CPH
F2(2,4) = -F1(1,3)+F2(2,1)
F2(3,2) = F2(2,1)/CPH
F2(3,4) = -F1(2,3)*F2(3,2)
F2(3,5) = F1(2,1)/CPH
F3(1,1) = -X(9)*PAR(4)
F3(2,1) = X(10)*PAR(4)
F3(3,1) = X(7)*PAR(4)
F3(4,1) = -X(8)*PAR(4)
F3(1,2) = [X(8)-X(10)*TPH]*PAR(4)
F3(2,2) = -[X(7)+X(9)*TPH]*PAR(4)
F3(3,2) = [X(10)+X(8)*TPH]*PAR(4)
F3(4,2) = -[X(9)-X(7)*TPH]*PAR(4)
F3(1,4) = -F1(1,3)*F3(1,1) - F1(2,3)*F3(1,2)
F3(2,4) = -F1(1,3)*F3(2,1) - F1(2,3)*F3(2,2)
F3(3,4) = -F1(1,3)*F3(3,1) - F1(2,3)*F3(3,2)
F3(4,4) = -F1(1,3)*F3(4,1) - F1(2,3)*F3(4,2)
F3(1,5) = -X(10)*SP(1)
F3(2,5) = -X(9)*SP(1)
F3(3,5) = X(8)*SP(1)
F3(4,5) = X(7)*SP(1)
F1(1,7) = 2.*[X(7)*AB(1)-X(10)*AB(2)+X(9)*AB(3)]
F1(1,8) = 2.*[X(8)*AB(1)+X(9)*AB(2)+X(10)*AB(3)]
F1(1,9) = 2.*[-X(9)*AB(1)+X(8)*AB(2)+X(7)*AB(3)]
F1(1,10) = 2.*[X(10)*AB(1)+X(7)*AB(2)-X(8)*AB(3)]
F1(2,7) = -F1(1,10)
F1(2,8) = -F1(1,9)
F1(2,9) = F1(1,8)
F1(2,10) = F1(1,7)
F1(3,7) = F1(1,9)
F1(3,8) = -F1(1,10)
F1(3,9) = -F1(1,7)
F1(3,10) = F1(1,8)
F3(2,7) = -F3(1,8)
F3(3,7) = -F3(1,9)
F3(3,8) = -F3(2,9)
F3(4,7) = -F3(1,10)
F3(4,8) = -F3(2,10)
F3(4,9) = -F3(3,10)
F2(1,3) = -1.
```

```
F1(1,6) = 0.
F1(2,6) = 0
F1(3,6) = 0
F1(3,3) = 0
F2(1,1) = 0
F2(1,2) = 0
F2(1,4) = 0
F2(1,5) = 0
F2(2,2) = 0
F2(2,3) = 0
F2(2,5) = 0
F2(3,1) = 0
F2(3,3) = 0
F3(1,3) = 0
F3(2,3) = 0
F3(3,3) = 0
F3(4,3) = 0
F3(1,4) = 0
F3(2,4) = 0
F3(3,4) = 0
F3(4,4) = 0
F3(1,7) = 0
F3(2,8) = 0
F3(3,9) = 0
F3(4,10) = 0
```

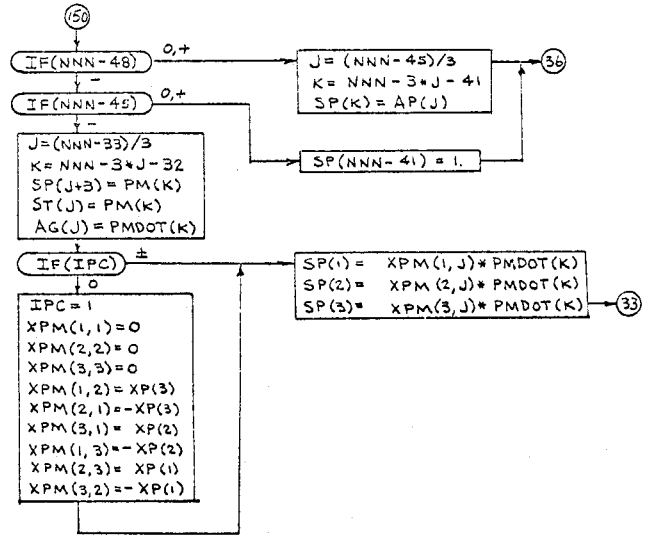
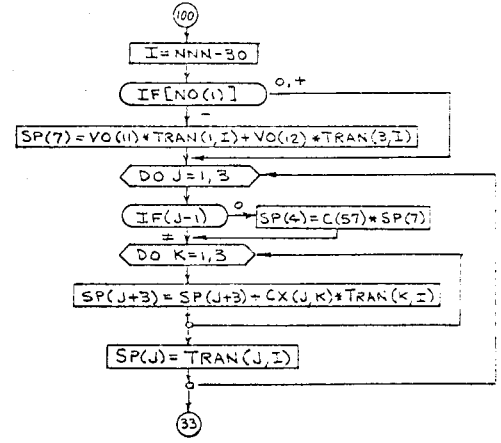
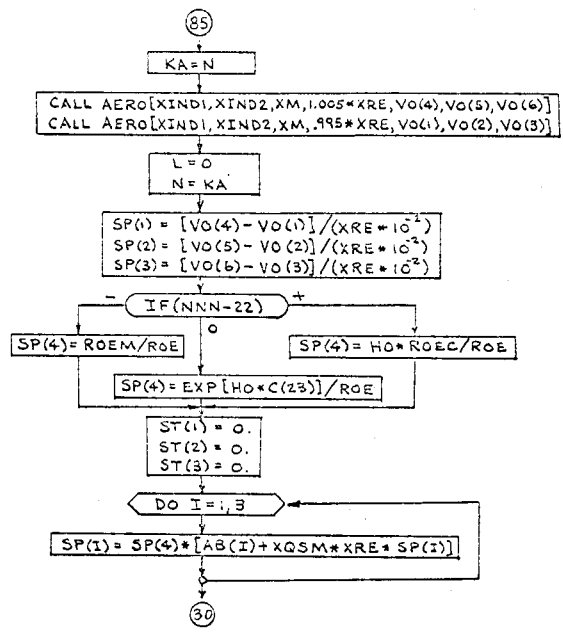
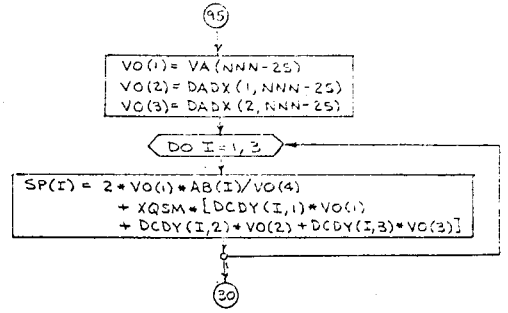
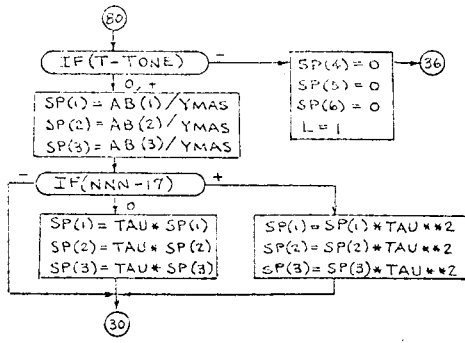
A

Subroutine FXXU (STEP1, STEP2)

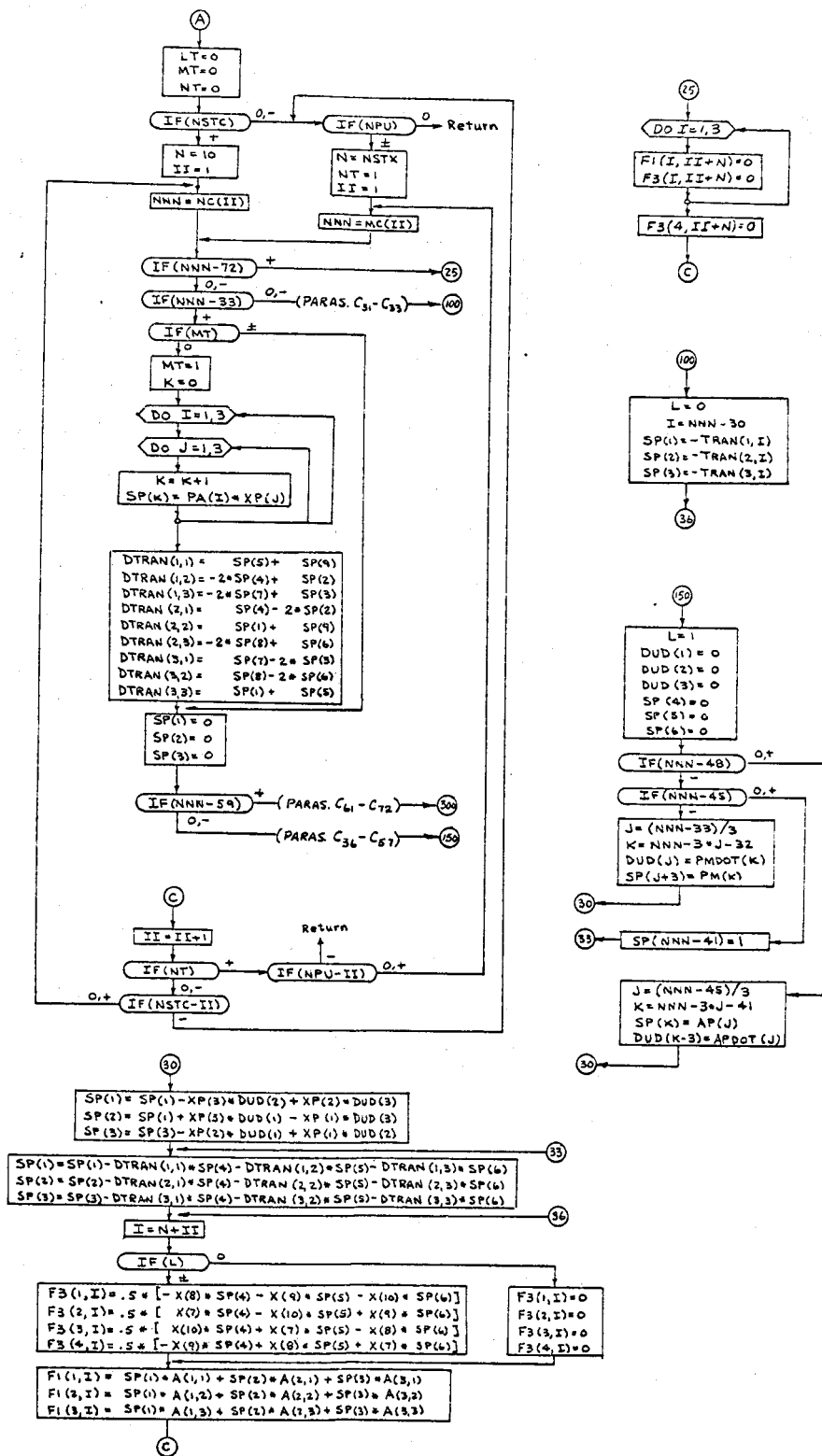




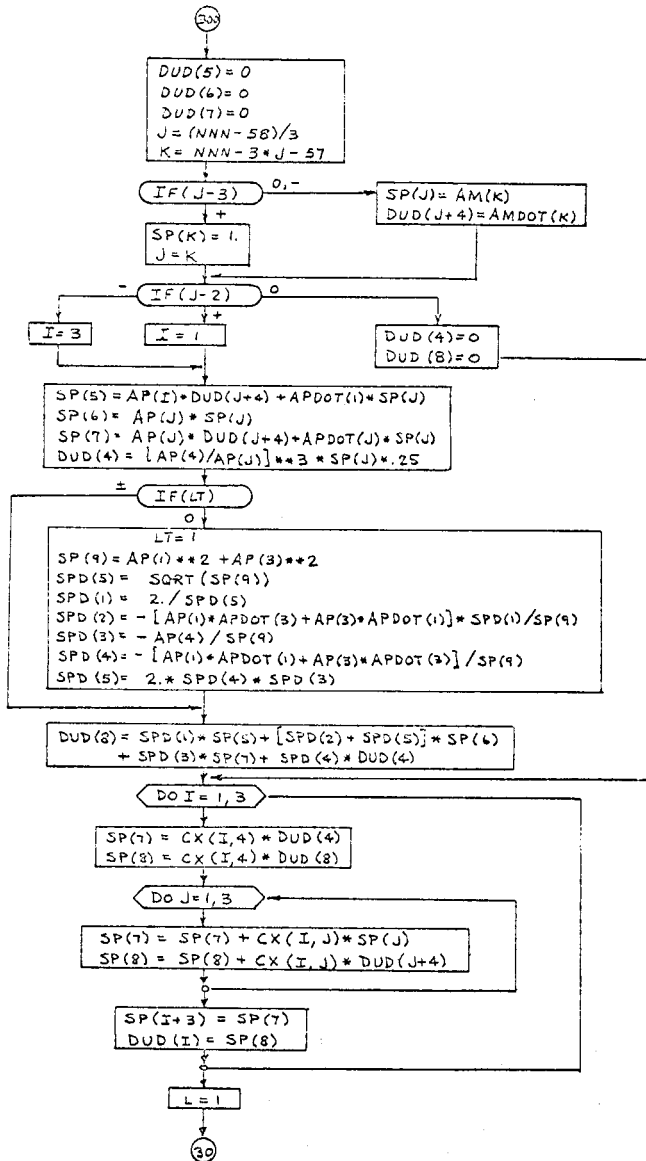
Subroutine FAXU (STEP1) - Continued



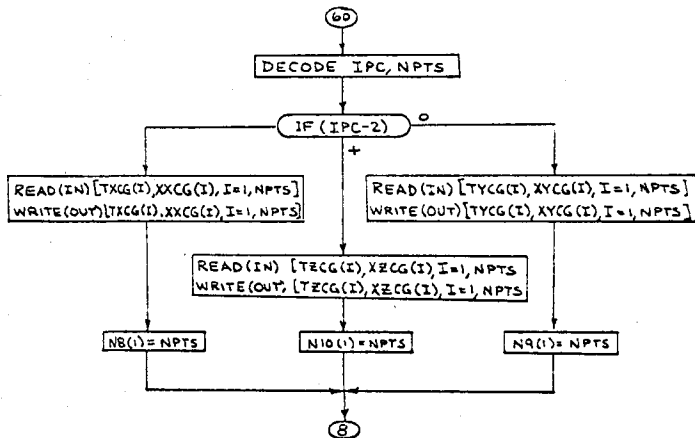
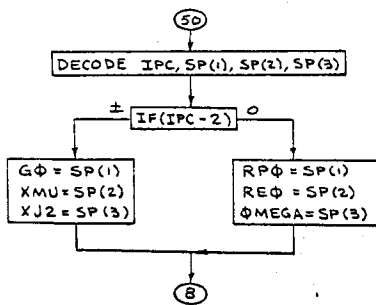
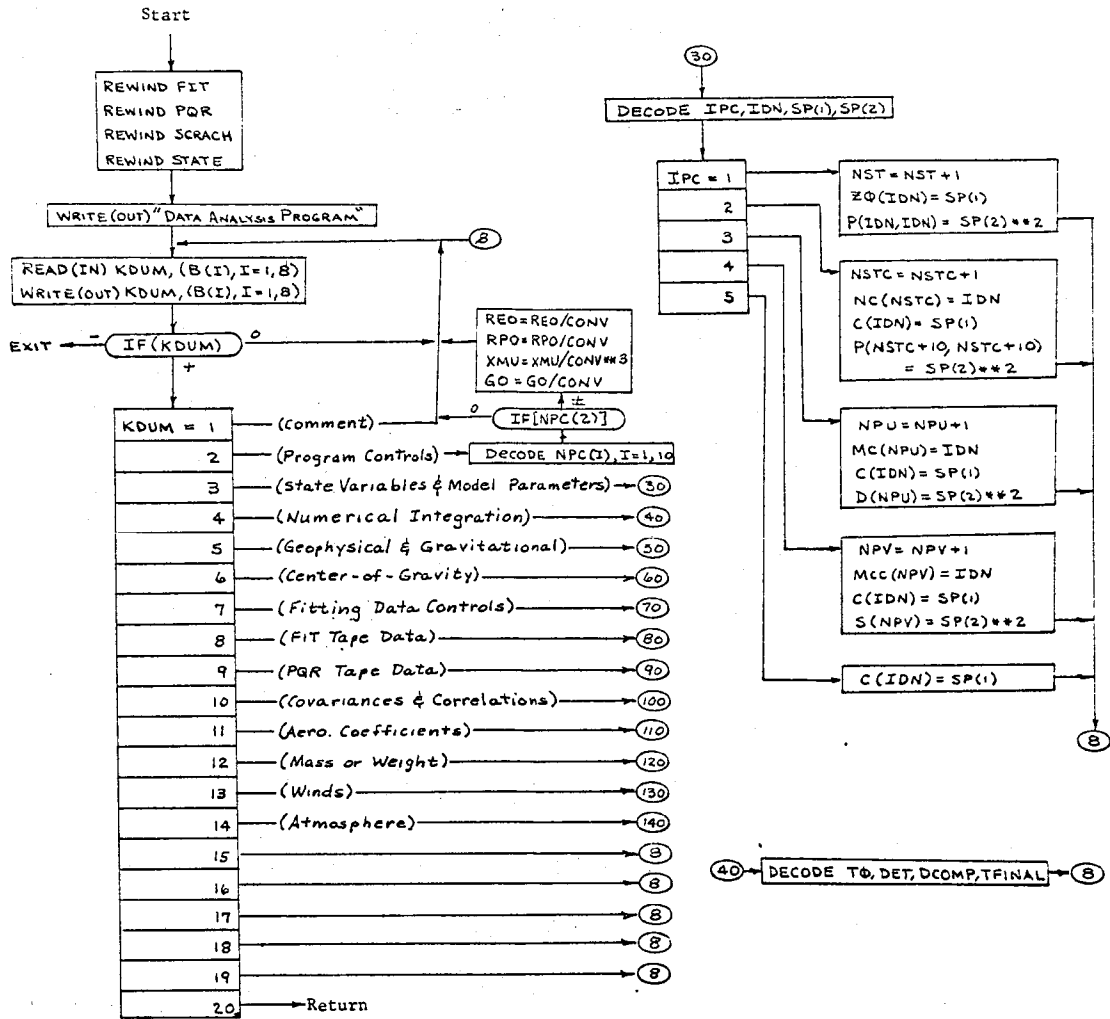
Subroutine FXXU (STEP1) - Continued



Subroutine FXXU (STEP2) - Continued



Subroutine FXXU (STEP2) - Concluded



Subroutine INDAT

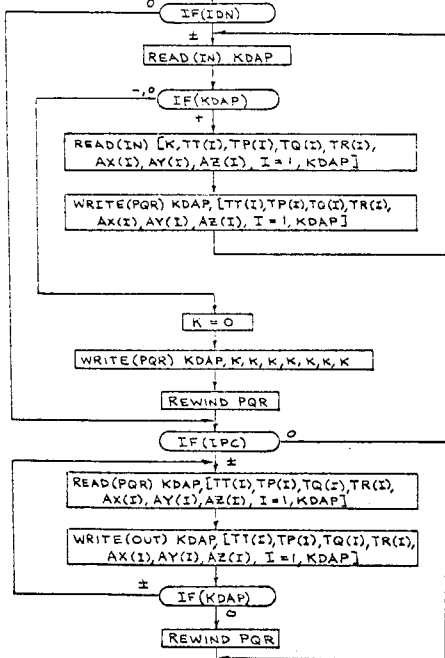
70
 DECODE IDN, SP(1), SP(2), SP(3), LT, MT, NT,
 SP(4), SP(5), SP(6)

```

NSTA = NSTA + 1
NS(NSTA) = IDN
DTI(IDN) = SP(1)
DTF(IDN) = SP(2)
DFIT(IDN) = SP(3)
MR(1, IDN) = LT
MR(2, IDN) = MT
MR(3, IDN) = NT
SYG(1, IDN) = SP(4)
SYG(2, IDN) = SP(5)
SYG(3, IDN) = SP(6)
  
```

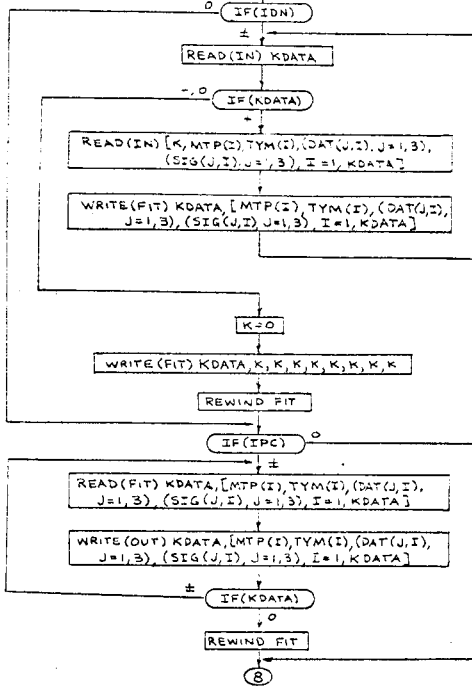
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90
 DECODE IPC, IDN



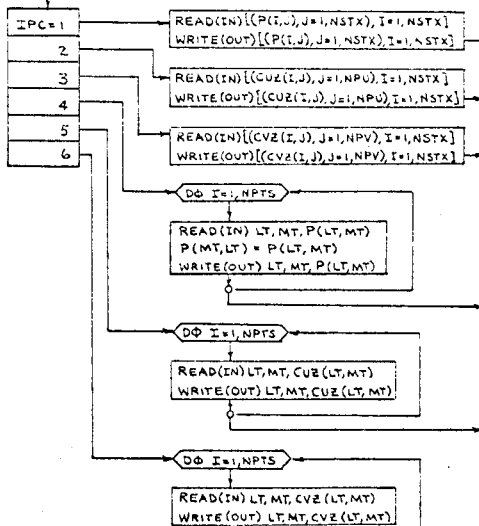
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80
 DECODE IPC, IDN



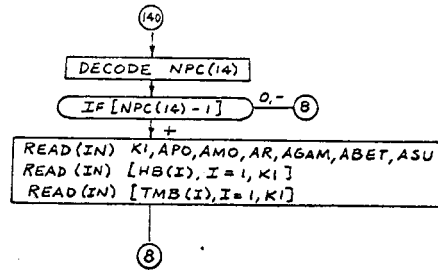
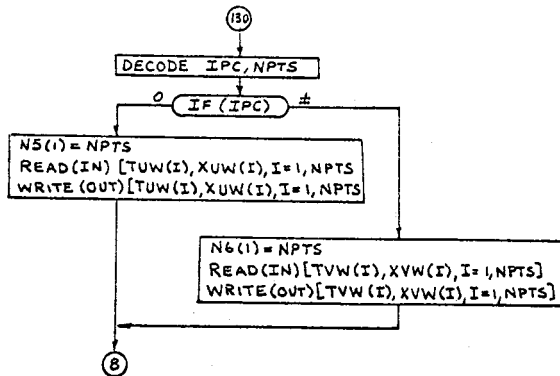
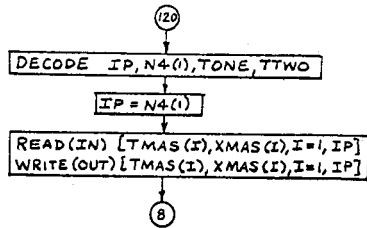
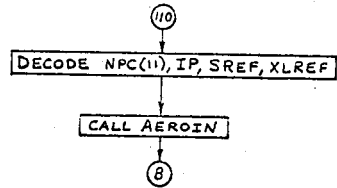
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100
 DECODE IPC, NPTS

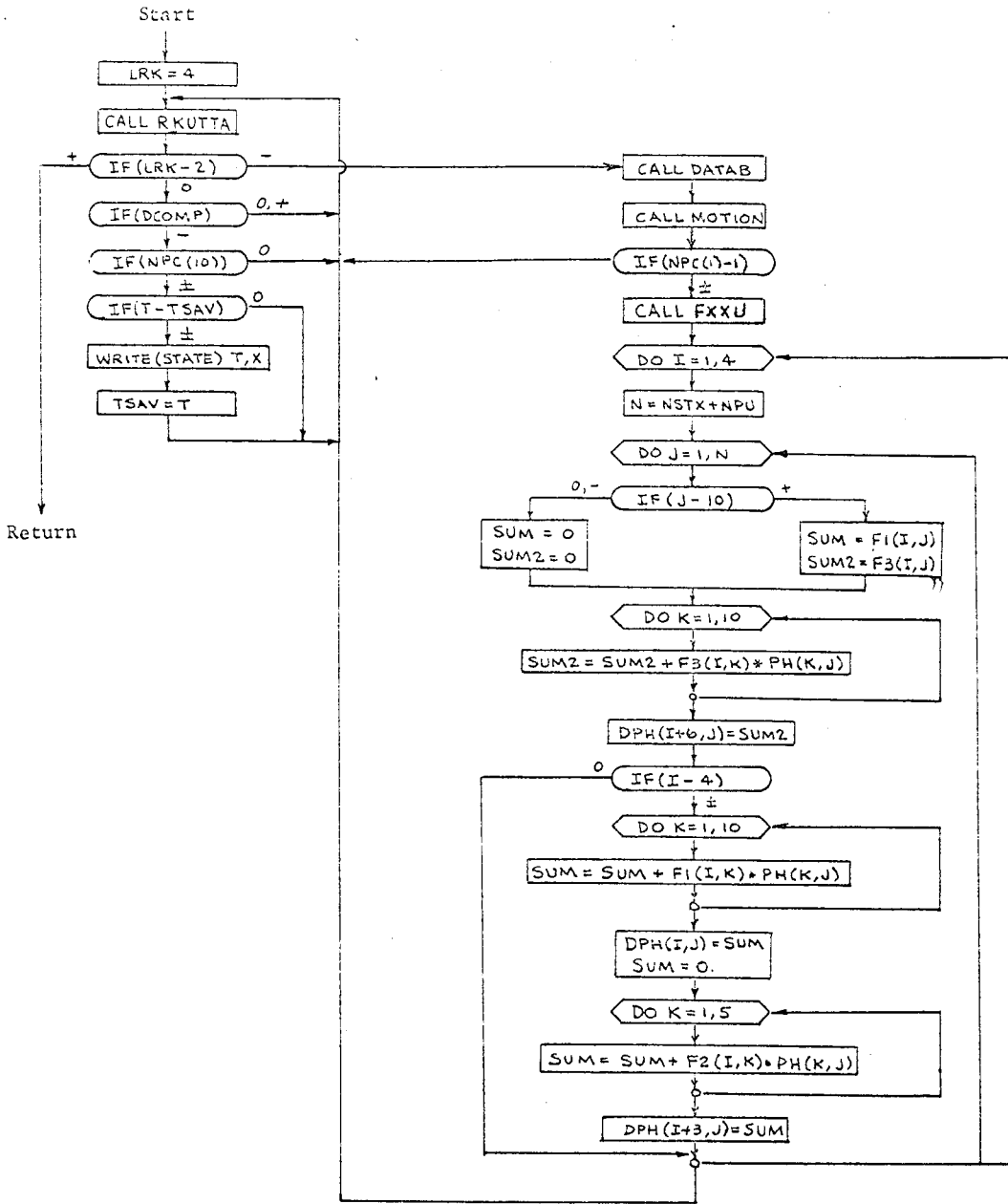


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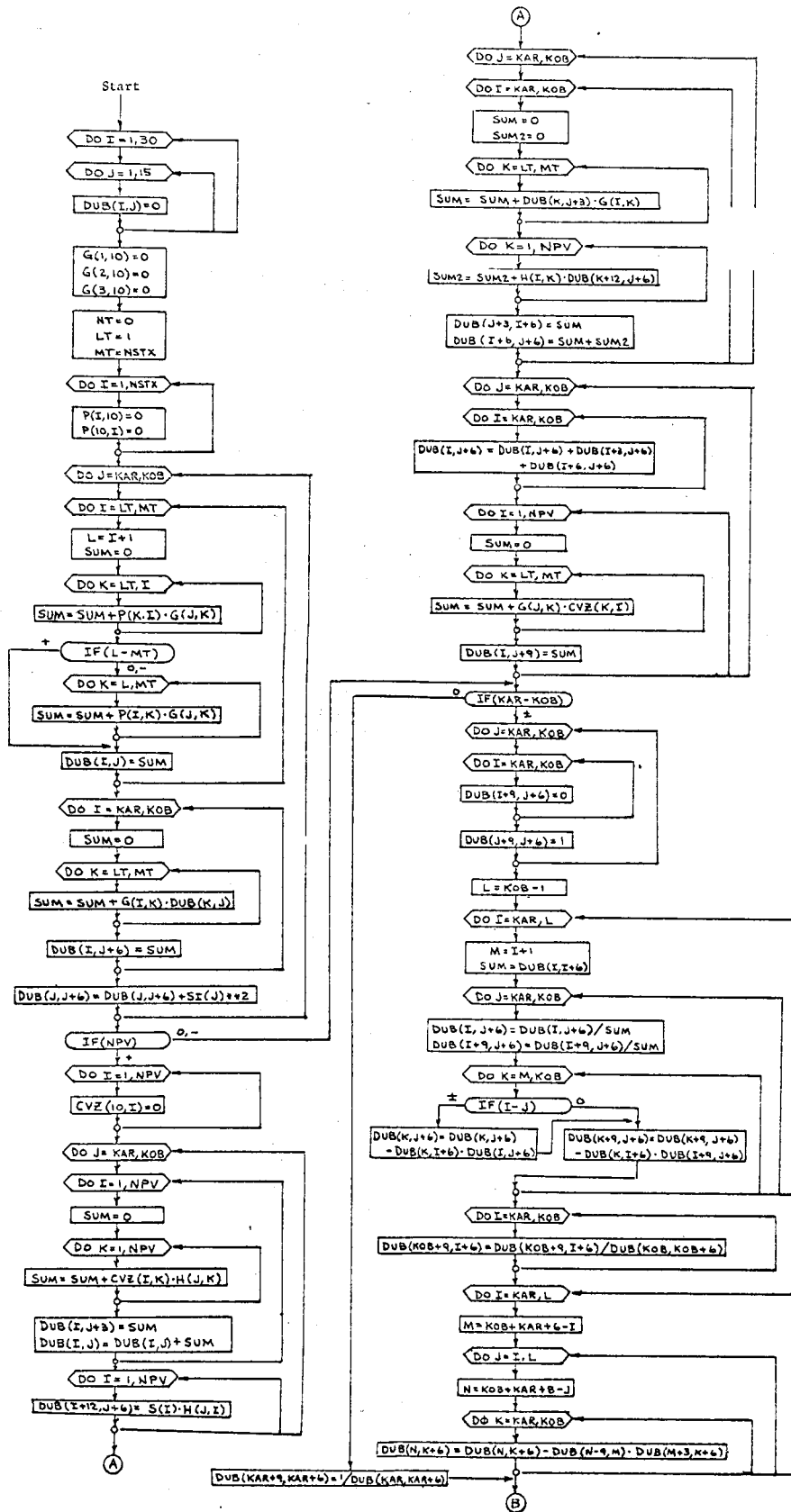
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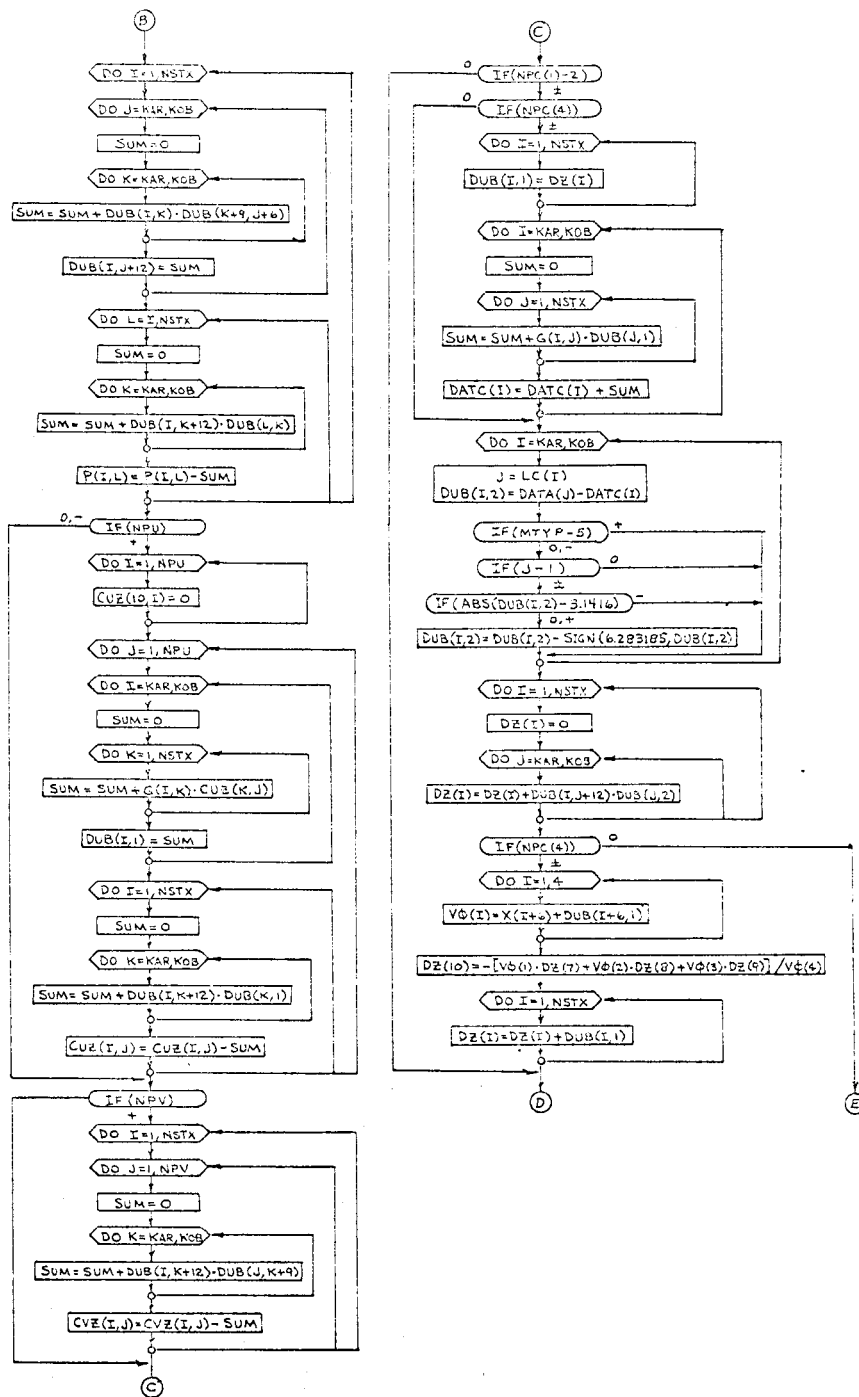
Subroutine INDAT - Concluded



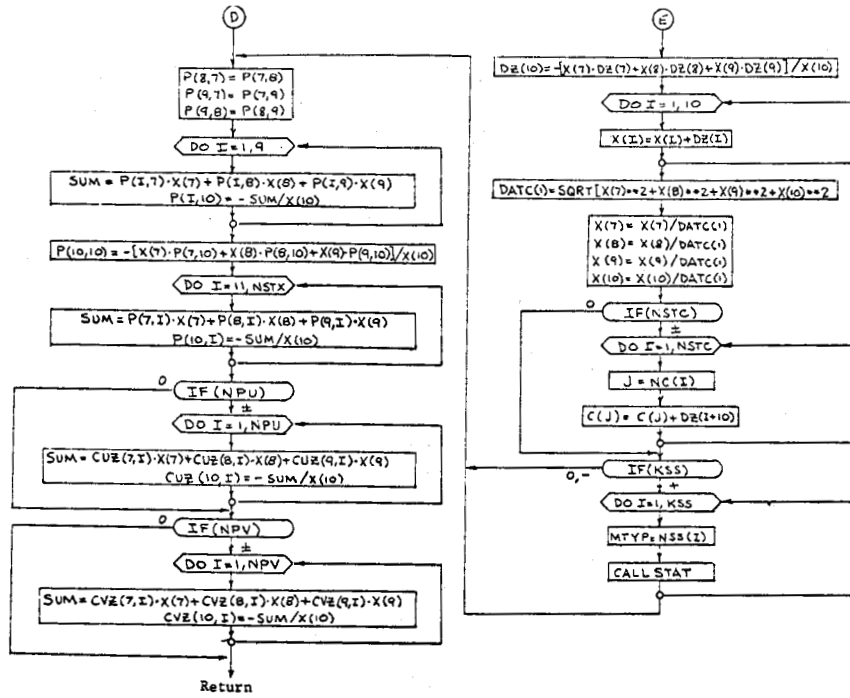
Subroutine INTAG



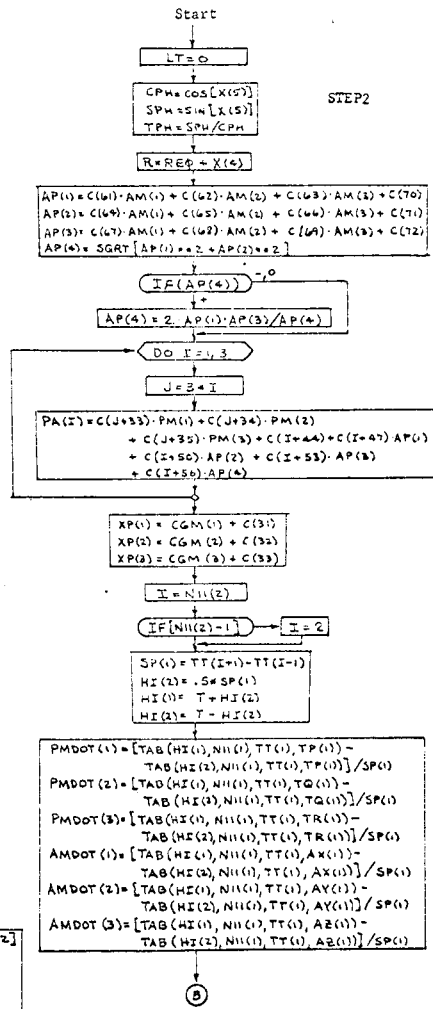
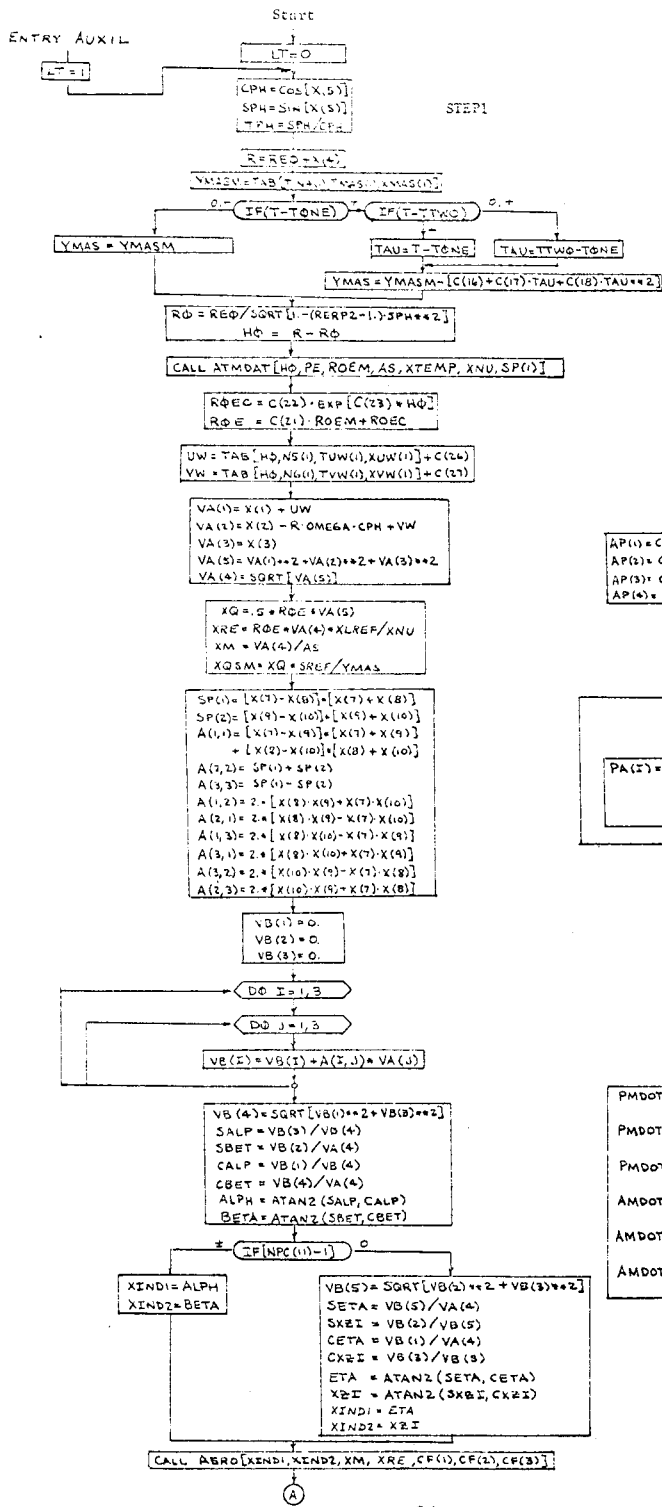
Subroutine MINVAR



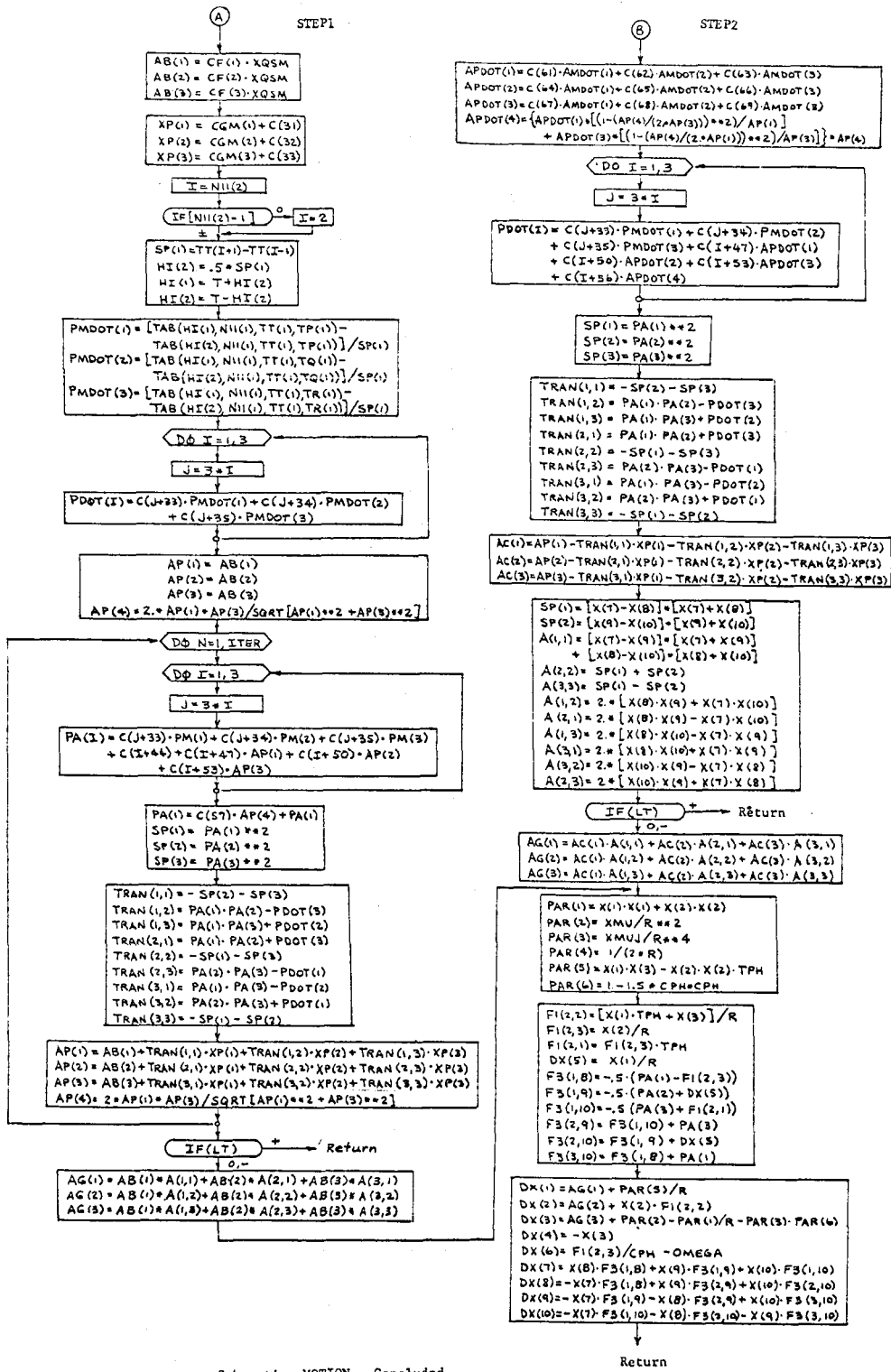
Subroutine MINVAR - Continued



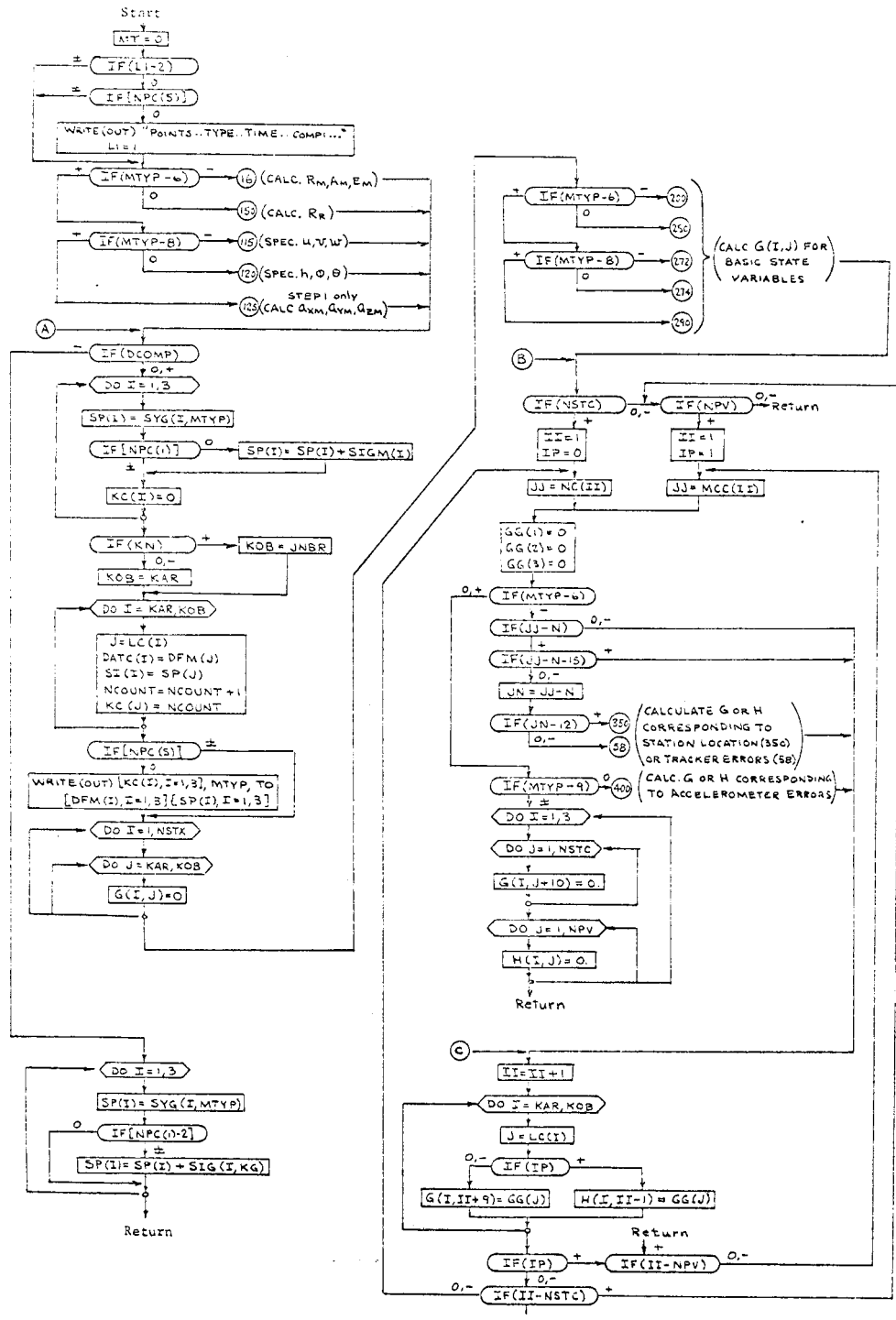
Subroutine MINVAR - Concluded



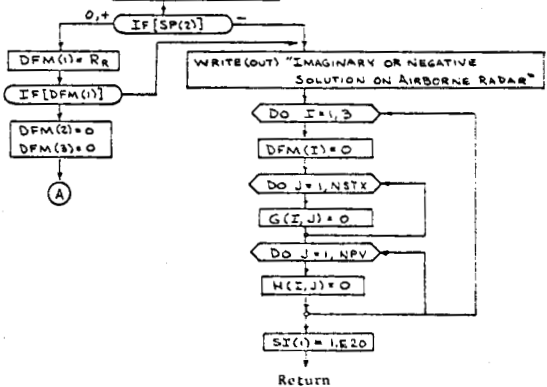
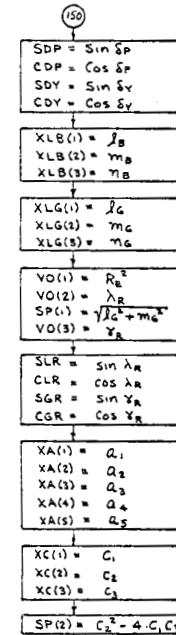
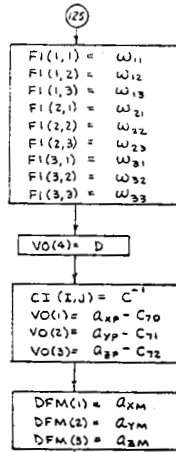
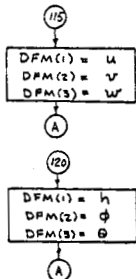
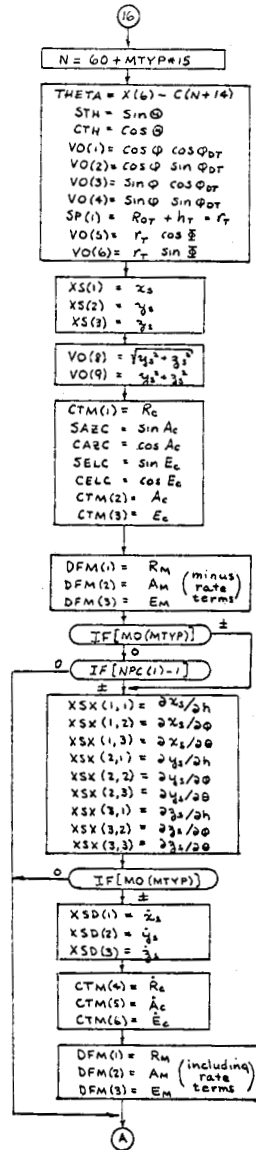
Subroutine MOTION

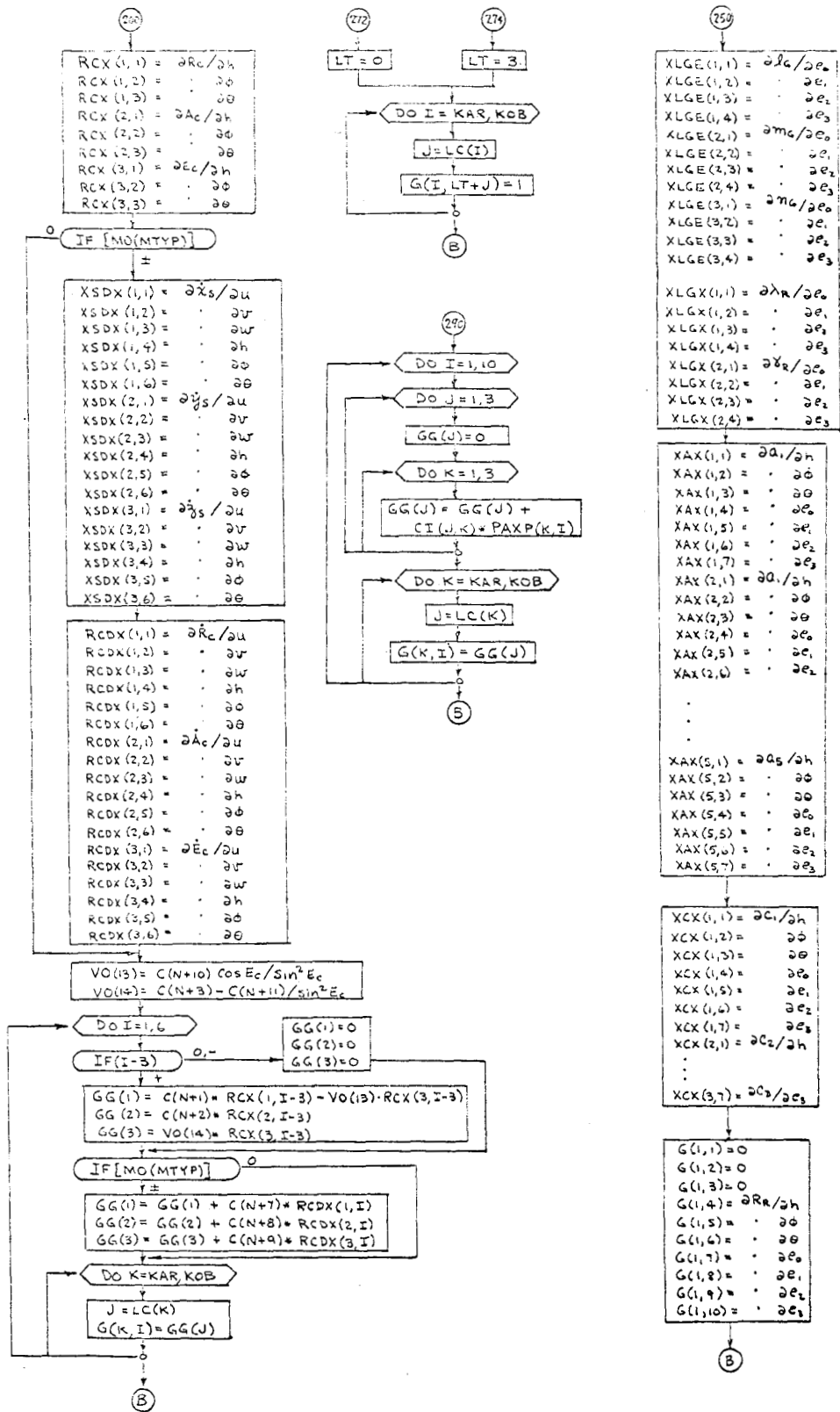


Subroutine MOTION - Concluded

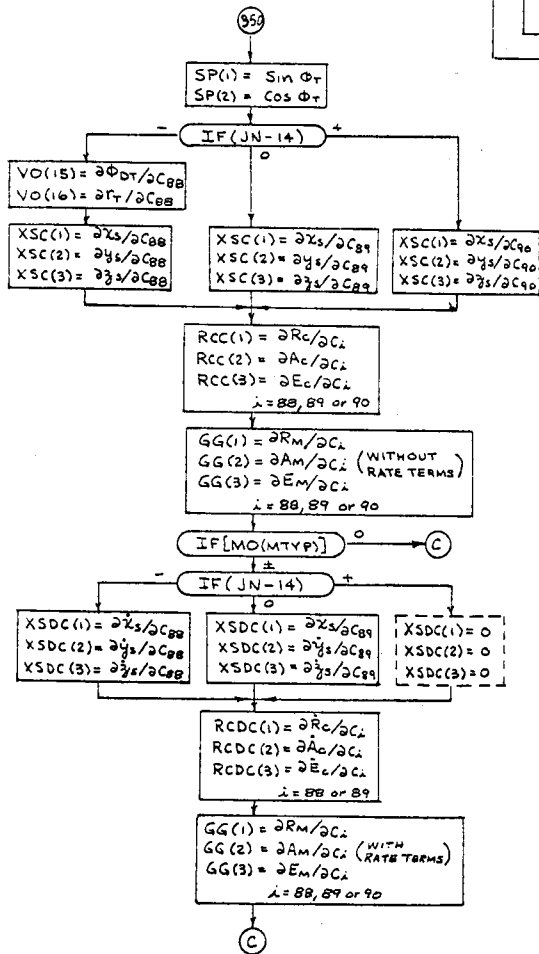
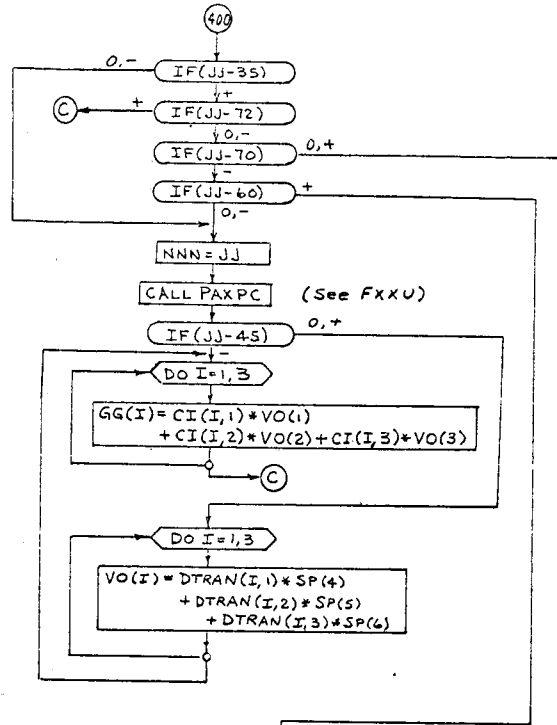
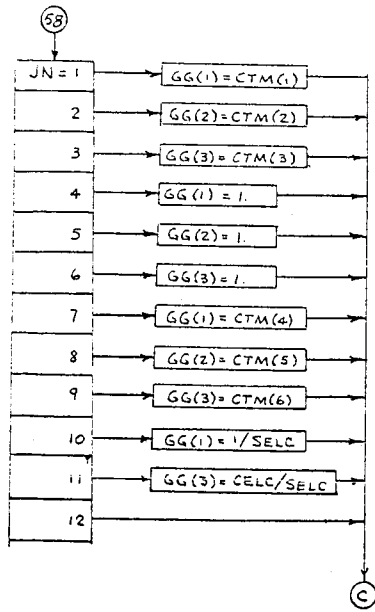


Subroutine OBSERV





Subroutine OBSERV - Continued



Subroutine OBSERV - Concluded

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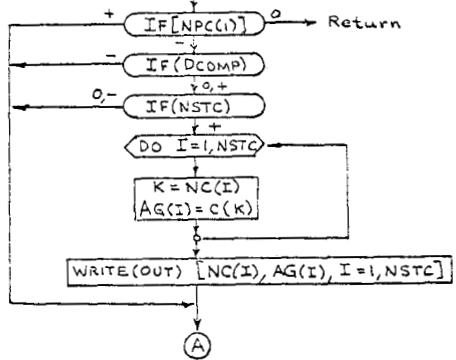
Start
↓
CALL AUXIL
ZO(1) =  $\gamma_A$ 
ZO(2) =  $\sqrt{u_A^2 + v_A^2}$ 
VO(1) =  $v_A$ 
ST(1) =  $\sin \gamma_A$ 
CT(1) =  $\cos \gamma_A$ 
VO(2) =  $\gamma_A$  (deg)
ST(2) =  $\sin \lambda_A$ 
CT(2) =  $\cos \lambda_A$ 
VO(3) =  $\lambda_A$  (deg)
RO =  $R_o$ 
VO(4) =  $h_o$ 
VO(5) =  $\Phi_b$  (deg)
VO(6) =  $\Theta$  (deg)
SP(1) =  $\sqrt{u^2 + v^2}$ 
VO(7) =  $v_x$ 
VO(8) =  $\gamma_x$ 
VO(9) =  $\lambda_x$ 
VO(10) =  $\overline{v}$  (deg)
SP(1) =  $\sqrt{1 - g_2^2}$ 
VO(11) =  $\frac{\overline{v}}{\overline{\Phi}}$  (deg)
VO(12) =  $\frac{\overline{\Phi}}{\overline{\Phi}}$  (deg)
VO(13) =  $u_b$ 
VO(14) =  $v_b$ 
VO(15) =  $w_b$ 
ZO(3) =  $\sqrt{u_b^2 + w_b^2}$ 
ST(4) =  $\sin \beta$ 
CT(4) =  $\cos \beta$ 
VO(17) =  $\beta$  (deg)
ST(5) =  $\sin \alpha$ 
CT(5) =  $\cos \alpha$ 
VO(18) =  $\alpha$  (deg)
ZO(4) =  $g_{23} + \sin \beta \sin \gamma_A = D_1$ 
ZO(5) =  $(g_{22} \cos \lambda_A - g_{21} \sin \lambda_A) \cos \gamma_A = D_2$ 
ZO(9) =  $\sqrt{D_1^2 + D_2^2}$ 
ST(3) =  $\sin \sigma$ 
CT(3) =  $\cos \sigma$ 
VO(16) =  $\sigma$  (deg)
SP(1) =  $v_x$ 
SP(3) =  $\eta$  (deg)
SP(2) =  $\xi$  (deg)
VO(19) =  $\psi$  (deg)

```

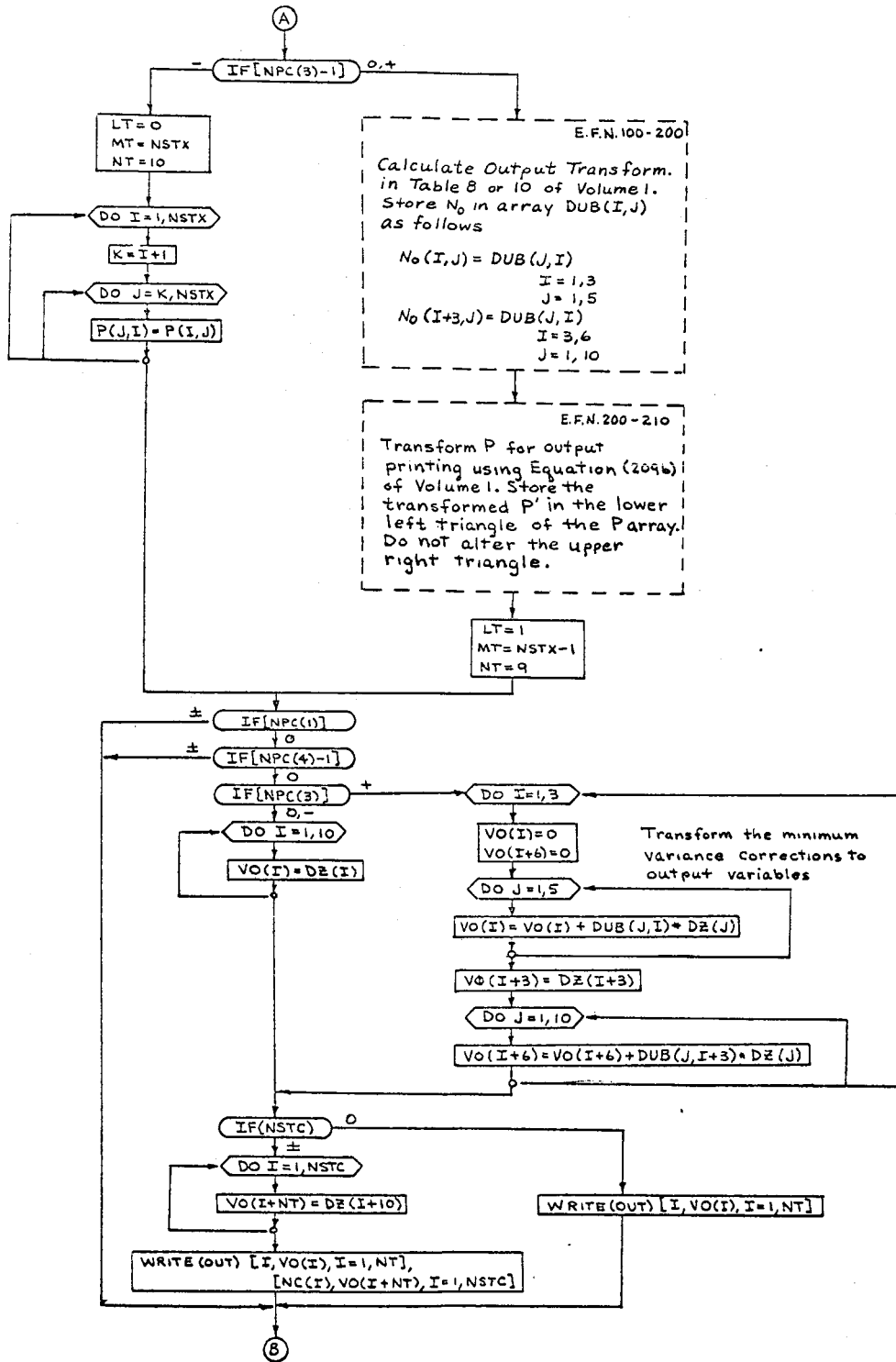
```

WRITE(OUT) TO
WRITE(OUT) [VO(I), I=1,6]
WRITE(OUT) [X(I), I=1,3], [VO(I), I=10,12]
WRITE(OUT) [VO(I), I=13,18]
WRITE(OUT) [XP(I), I=1,3], [SP(I), I=1,3]
WRITE(OUT) [PA(I), I=1,3], [AB(I), I=1,3]
WRITE(OUT) [PM(I), I=1,3], [CF(I), I=1,3] STEP1
[PM(I), I=1,3], [AM(I), I=1,3] STEP2
WRITE(OUT) XQ, XM, ROE, [CA(I), I=1,3] STEP1 only
WRITE(OUT) [X(I), I=7,10], VO(19), XRE STEP1
[X(I), I=7,10], VO(19), VO(20) STEP2

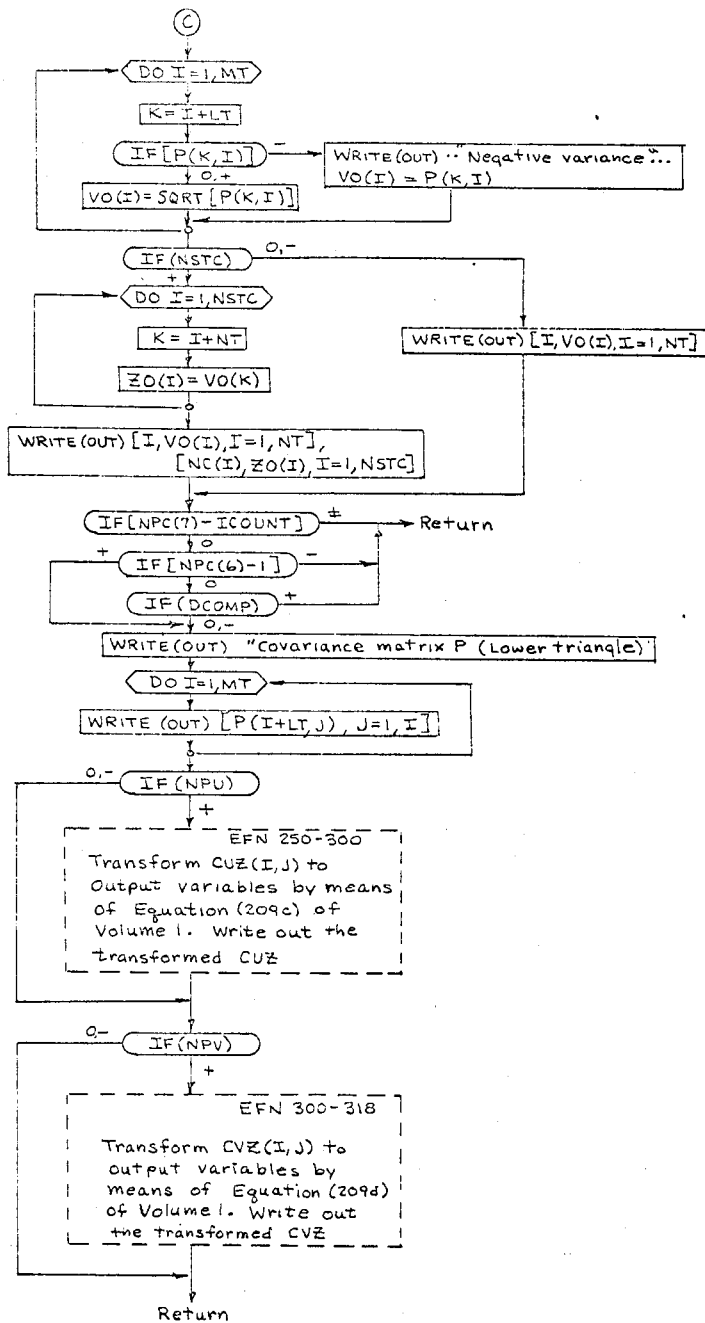
```



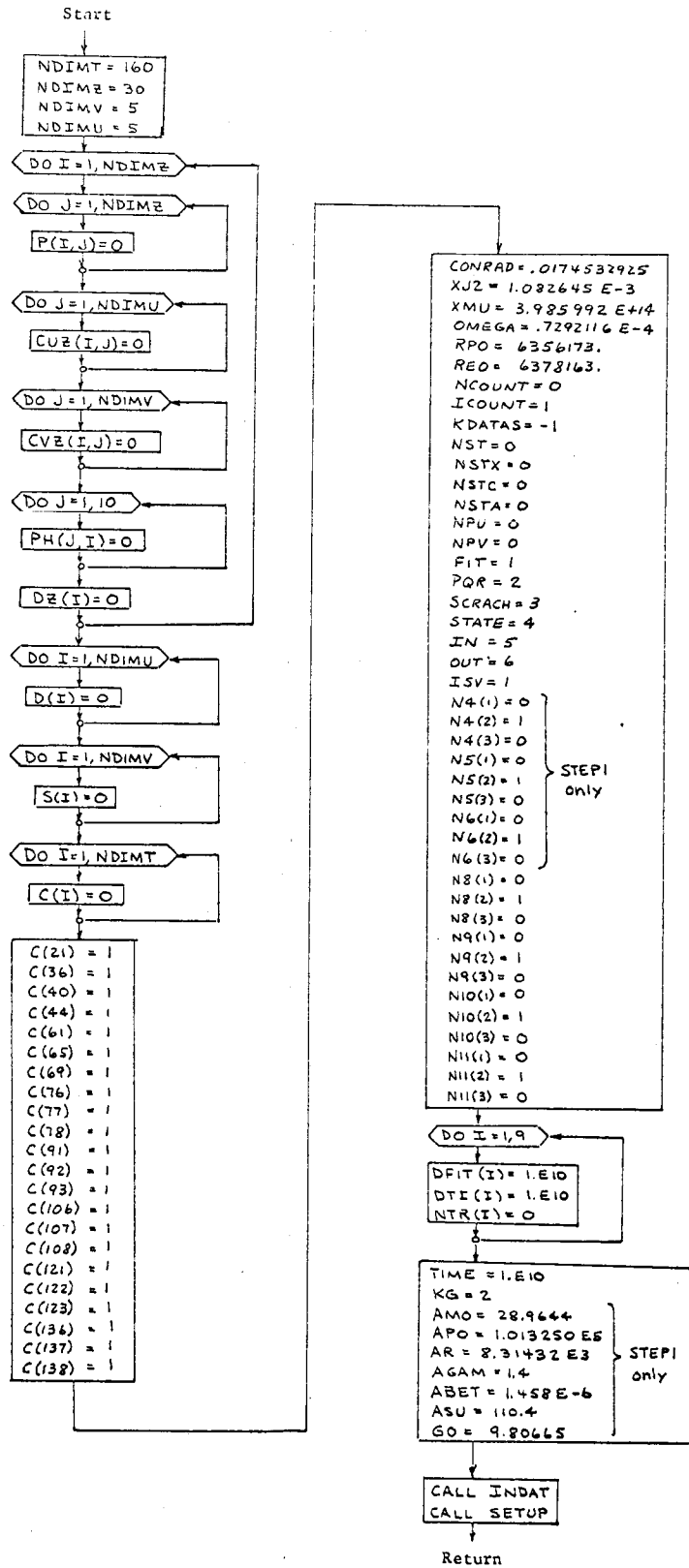
Subroutine OUTPUT



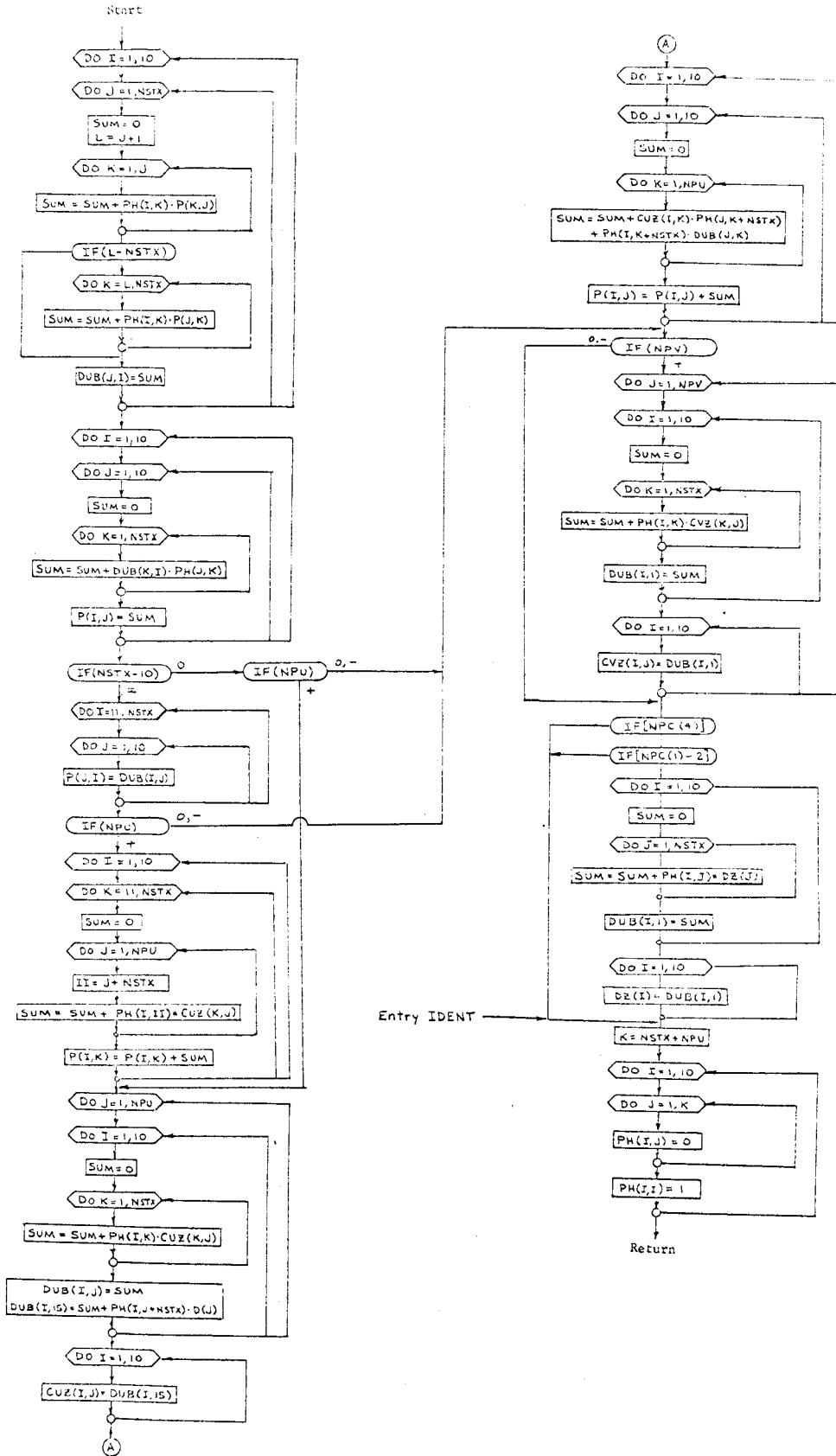
Subroutine OUTPUT - Continued



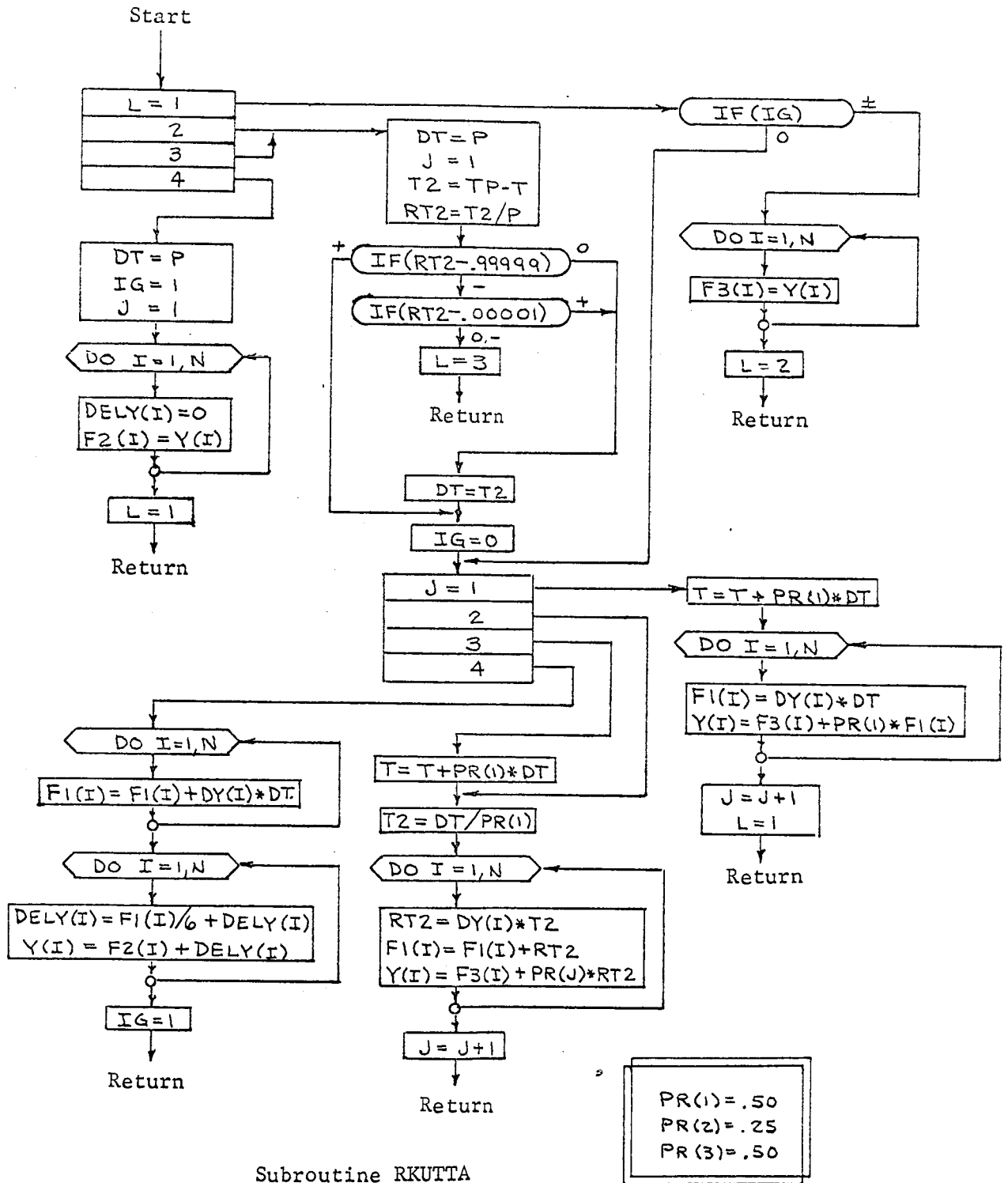
Subroutine OUTPUT - Concluded

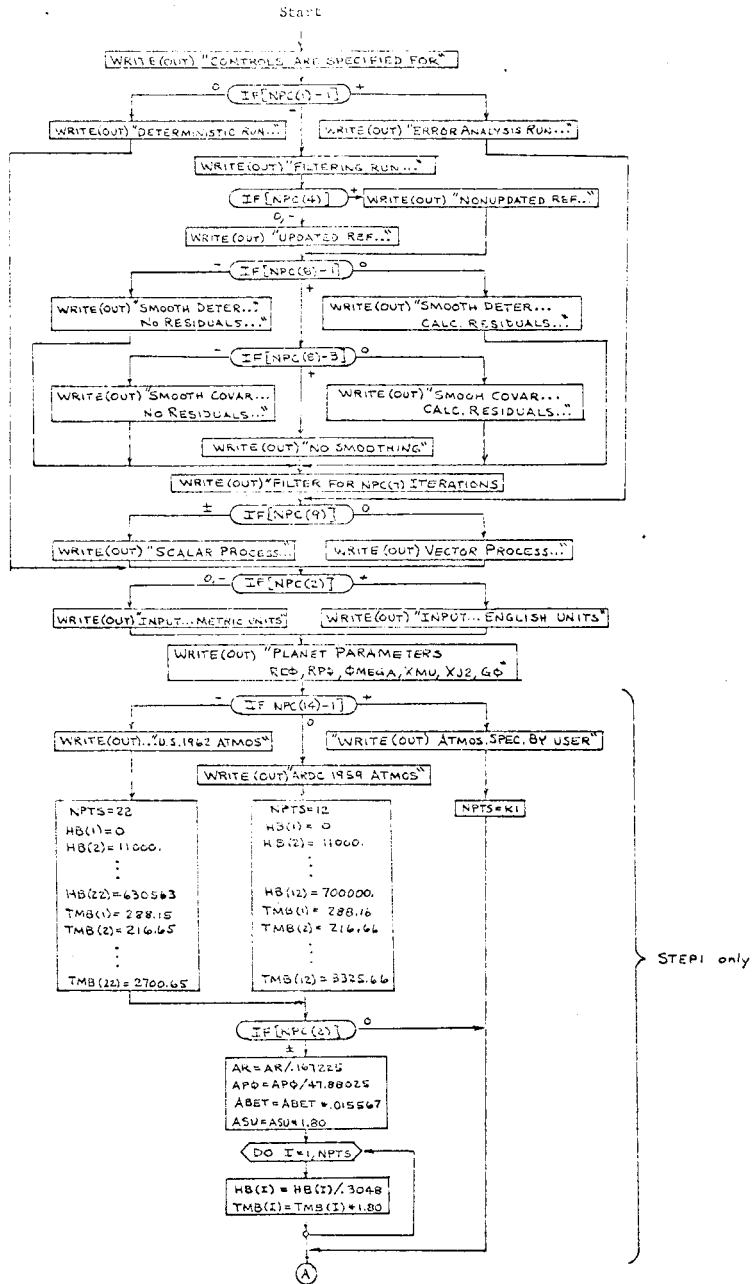


Subroutine PRESET

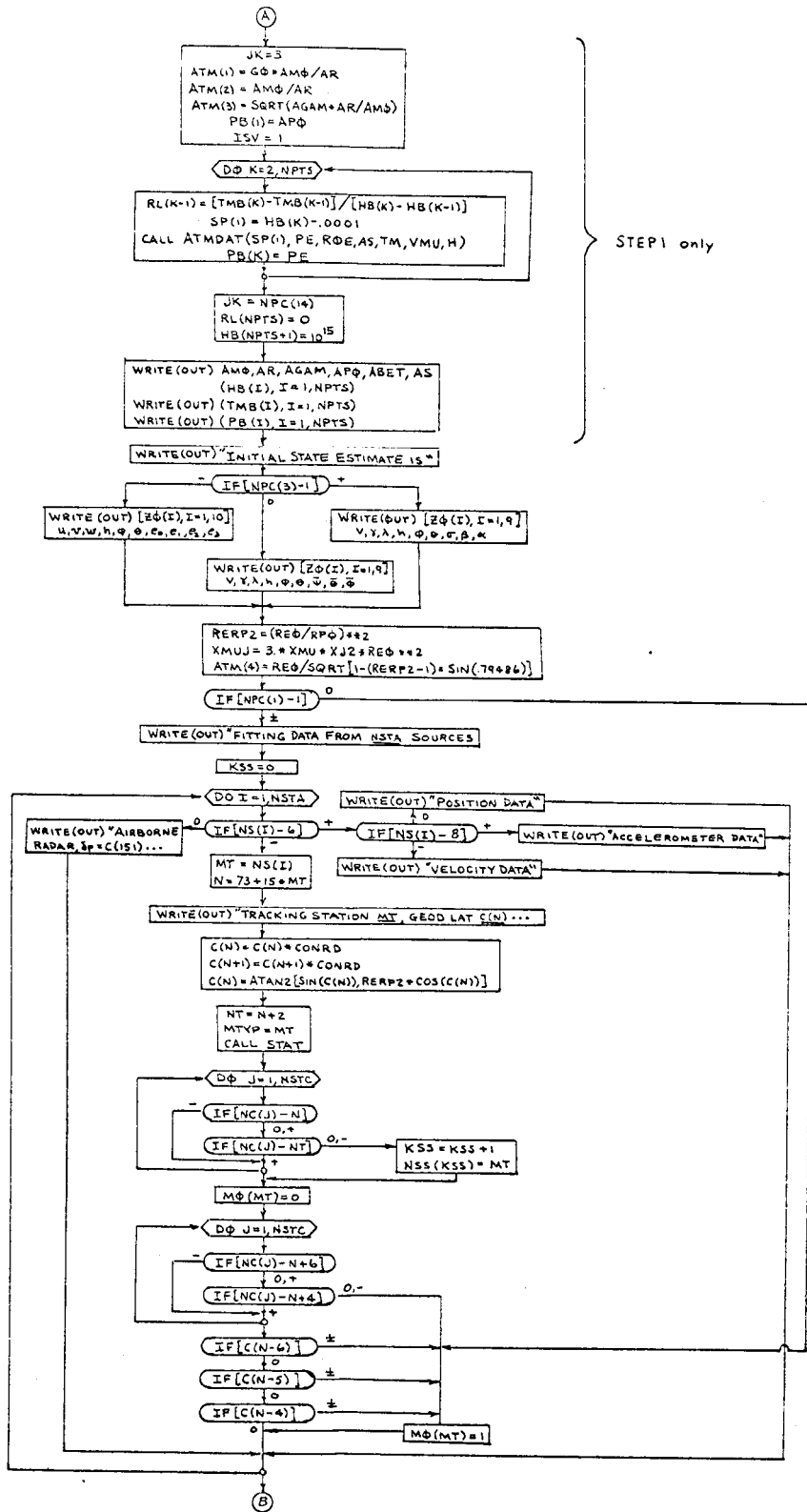


Entry IDENT

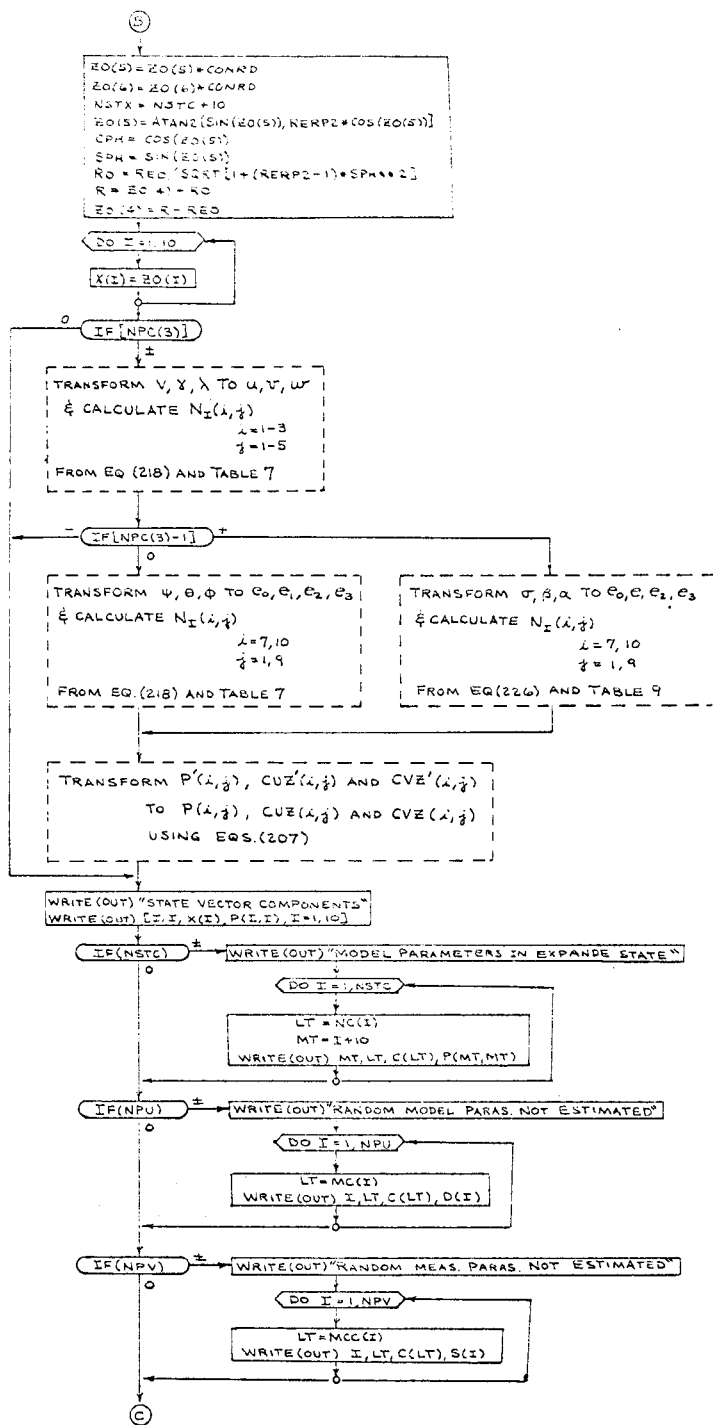




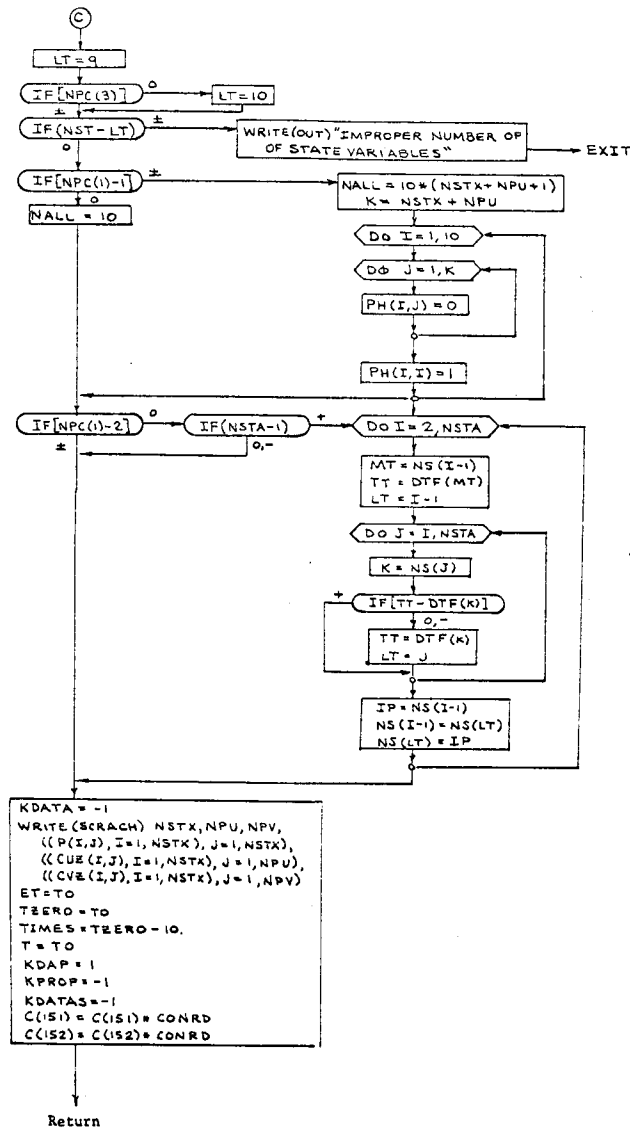
Subroutine SETUP



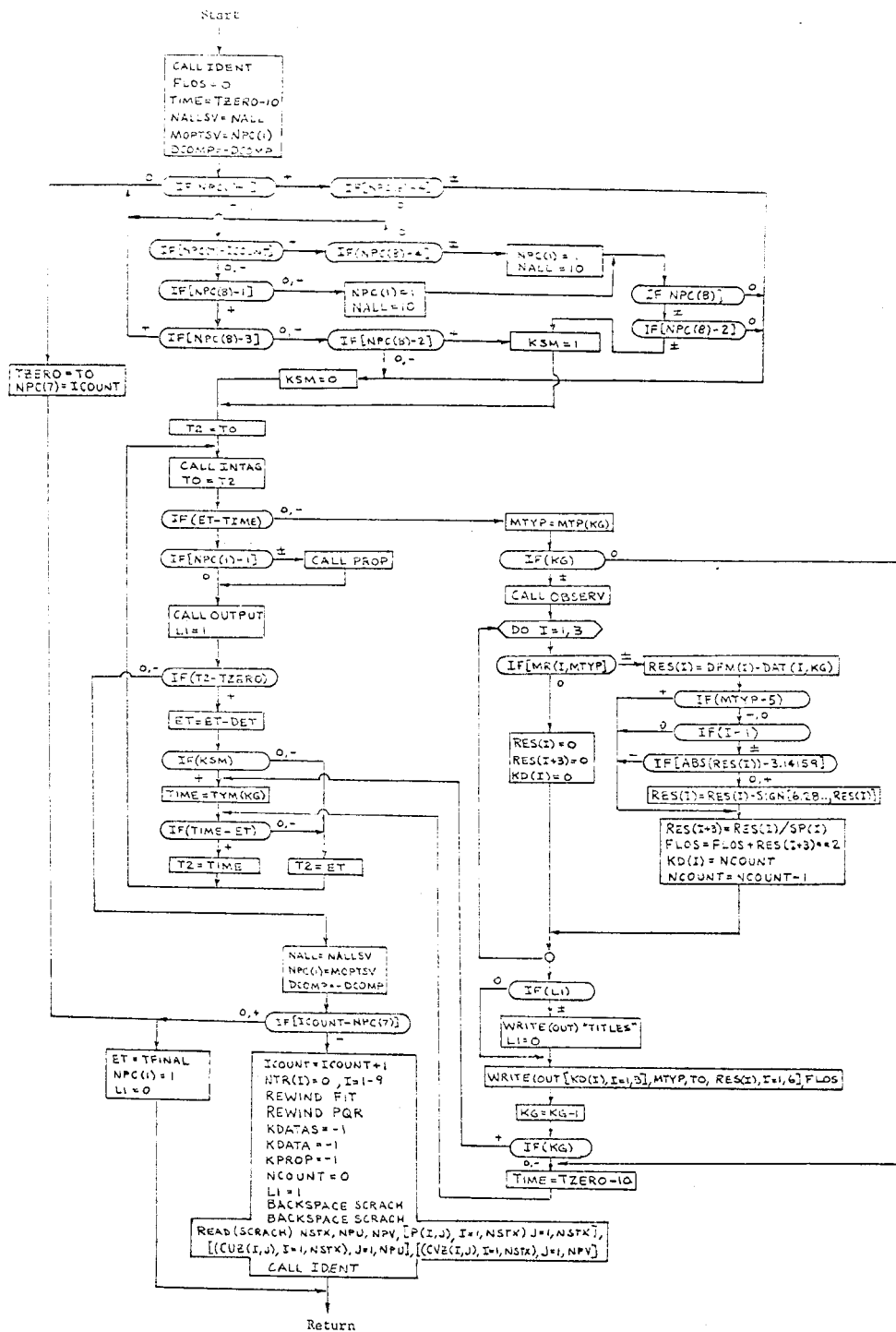
Subroutine SETUP - Continued



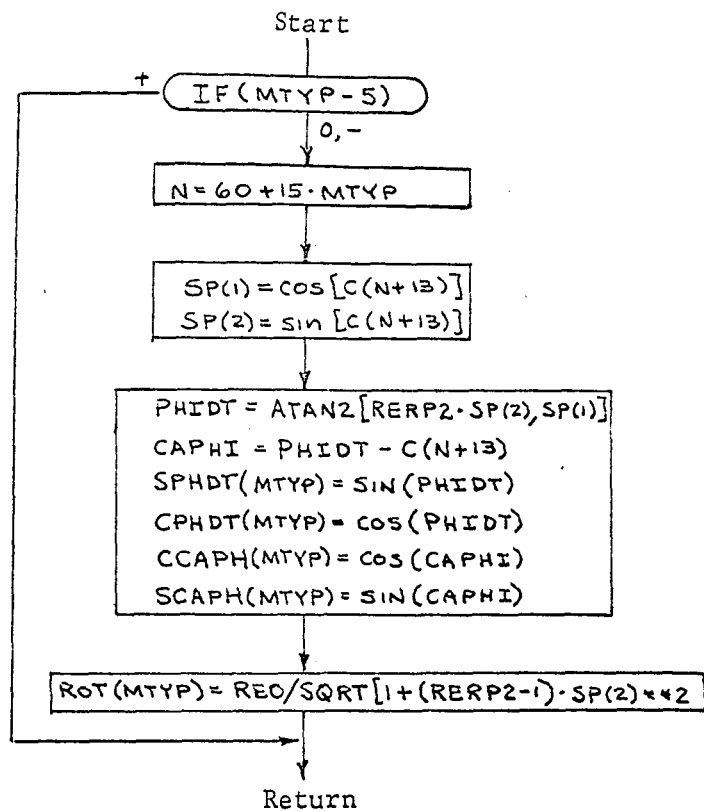
Subroutine SETUP - Continued



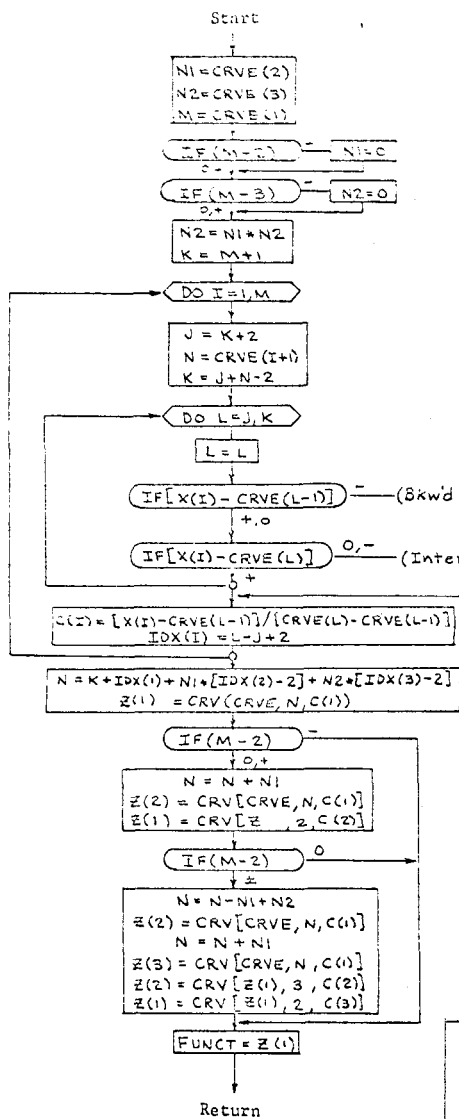
Subroutine SETUP - Concluded



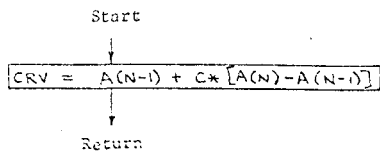
Subroutine SMOOIII



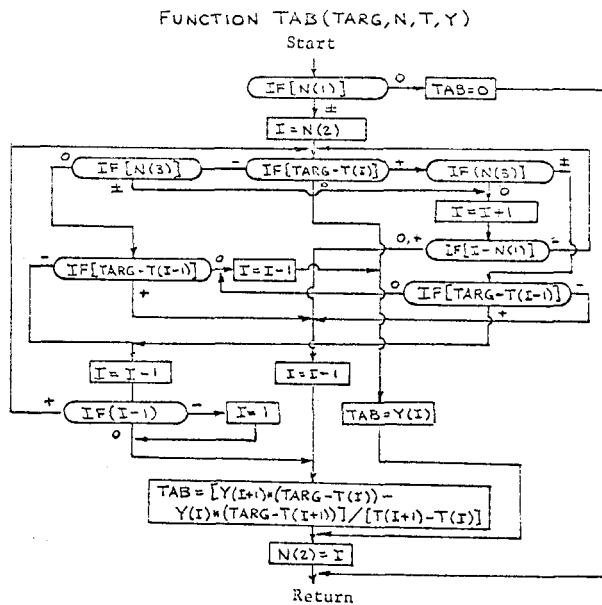
Subroutine STAT



Function FUNC (CRVE, X)



Function CRV (A, N, C)



Function TAB (TARG, N, T, Y)

VII. SOURCE LISTING

A. STEP1 Listing

The STEP1 source listing is presented in the following subsection. The following listing indicates the pages on which the STEP1 subroutine listings appear:

MAIN	138
AERO	143
AEROIN	145
ATMDAT	148
DATAB	149
DERIVE	152
FUNCT & CRV	155
FXXU	156
INDAT	163
INTAG	168
MINVAR	170
MOTION	174
OBSERV	178
OUTPUT	188
PRESET	195
PROP	198
RKUTTA	201
SETUP	202
SMOOTH	211
STAT	214
TAB	215

The STEP2 listings commence on page 216.

```

PROGRAM MAIN(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT,
  2 TAPE7, TAPE1,TAPE2,TAPE3,TAPE4)
COMMON /INTGKL/ JCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRR
COMMON /MOD1/ ALPH,AS ,BETA,CA(6),CALP ,CBET ,CETA ,
1 CF(3),JCS ,CXZI ,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH ,
2 DRDP,DADH(2),ETA,HO,N4(3) ,N5(3) ,N6(3) ,PAXP(3,30),
3 PE ,ROE ,ROEC ,ROEM ,SALP ,SBET ,
4 SETA ,SREF ,SXZI ,TAU ,TMAS(20) ,TONE ,
5 TWG ,TOW(20) ,TVW(20) ,UW ,VA(5) ,VB(5) ,
6 VW ,XIND1 ,XIND2 ,XLREF ,XM ,
7 XMAS(20) ,XNU ,XQ ,XOSM ,XRE ,XTEMP ,
8 XDW(20) ,XVW(20) ,XZI ,YMAS ,YMASM
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,P(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,I1 ,IP ,IPC ,JU ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NIN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RC ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG ,KI ,KK
6 ,KN ,KOL ,KPRCP ,KS ,KSM ,KSS ,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,LI ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,NIP(40) ,NTYP ,NTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPG ,RCT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TH1(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TK(40) ,TI(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERC ,XU2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPEN0/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON /ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A ,PB(23),RL(23),TM8(23)
COMMON /EXTRA / GO
-----STATISTICAL TRAJECTORY ESTIMATION PROGRAM, STEP1
C DEVELOPED BY W.E.WAGNER AND A.C.SEROLD
C MARTIN MARIETTA CORPORATION
C DENVER, COLORADO
2 CONTINUE
CALL PRESET
4 WRITE(OUT,1001)
IF(NPC(1).EQ.0) WRITE(OUT,1000) ICOUNT
1000 FORMAT(19H ITERATION NUMBER I2//)
1001 FORMAT(1H1)
10 IF(KDATA) 12,42,202
12 T2=TC
CALL INTAG
GO TO 44
STP10020
STP10030
STP10040
STP10050
STP10060
STP10070
STP10080
STP10090
STP10100
STP10110
STP10120
STP10130
STP10140
STP10150

```

24	T2=TIME		
	IF(T2-ET)260,260,42		STP10160
30	IF(TO-ET) 34,32,32		STP10170
32	IF(JST.EQ.1) GO TO 44		STP10180
34	IF(KDATA) 38,36,36		STP10190
36	IF(KPROP.EQ.1) GO TO 24		STP10200
	IF(KDATA) 10,40,10		STP10210
38	IF(NPC(1)-1) 200,40,100		STP10220
40	TIME=TFINAL+100.		STP10230
	GO TO 24		STP10240
42	T2=ET		STP10250
C-----PROPGATION LOOP, TO EFN 44			
	CALL INTAG		STP10260
	KPROP=1		STP10270
	TO=T2		STP10280
	CALL PROP		STP10290
44	CALL OUTPUT		STP10300
	L1=2		STP10310
	IF(ET-TFINAL) 46,50,50		STP10320
46	ET=ET+DET		STP10330
	GO TO 34		STP10340
50	WRITE(SCRACH) KDATA		STP10350
	IF(NPC(1).EQ.1) GO TO 2		STP10360
56	IF(NPC(4)) 300,58,300		STP10370
58	CALL SMOOTH		STP10380
	IF(L1-1) 2,4,2		STP10390
C-----DETERMINE MEASUREMENT TIME FOR ERROR			
C ANALYSIS PROBLEMS, THRU EFN 118--			
100	IF(KPROP.GT.0) GO TO 24		STP10400
	JST=1		STP10410
	IF(NSTA-1) 40,102,104		STP10420
102	II = NS(1)		STP10430
	GO TO 112		STP10432
104	II = NS(1)		STP10434
	SP(1) = DTI(II)		STP10440
	DO 110 I=2,NSTA		STP10450
	J = NS(I)		STP10460
	IF(SP(1)-DTI(J)) 110,106,107		STP10470
106	JST=JST+1		STP10480
	GO TO 108		STP10500
107	JST=1		STP10510
108	SP(1) = DTI(J)		STP10520
	II = J		STP10530
110	CONTINUE		STP10540
112	IF(DTI(II)-DTF(II)) 116,116,114		STP10550
114	NSTA=NSTA-1		STP10560
	GO TO 100		STP10570
116	JNBR=0		STP10580
	TIME=DTI(II)		STP10590
	DTI(II)=DTI(II)+DFII(II)		STP10600
	DO 118 I=1,3		STP10610
	IF(MR(I,II).EQ.0) GO TO 118		STP10620
	JNBR=JNBR+1		STP10630
	LC(JNBR)=I		STP10640
118	CONTINUE		STP10650
	IF(JNBR.EQ.0) GO TO 100		STP10660
	MTYP = II		STP10670
	GO TO 24		STP10680
C-----DATA EDITING LOGIC FOR FILTER PROBLEMS, THRU EFN 250-----			
200	KG = 1		STP10690
			STP10700
			STP10710
			STP10720
			STP10730
			STP10740

KS = 1	STP10750
TYM(1) = TZERO - 10.	STP10760
GO TO 211	STP10770
202 KG=KG+1	STP10780
MTP(KG)=MTYPS	STP10790
TYM(KG)=TIMES	STP10800
DAT(1,KG)=DATAS(1)	STP10810
DAT(2,KG)=DATAS(2)	STP10820
DAT(3,KG)=DATAS(3)	STP10830
SIG(1,KG)=SIGMS(1)	STP10840
SIG(2,KG)=SIGMS(2)	STP10850
SIG(3,KG)=SIGMS(3)	STP10860
KDATA=KDATAS	STP10870
MTYP=MTYPS	STP10880
TIME=TIMES	STP10890
DATA(1)=DATAS(1)	STP10900
DATA(2)=DATAS(2)	STP10910
DATA(3)=DATAS(3)	STP10920
SIGM(1)=SIGMS(1)	STP10930
SIGM(2)=SIGMS(2)	STP10940
SIGM(3)=SIGMS(3)	STP10950
LC(1)=LCS(1)	STP10960
LC(2)=LCS(2)	STP10970
LC(3)=LCS(3)	STP10980
JNBR=JNBR5	STP10990
204 IF(K1-KS) 206,208,208	STP11000
206 K1=K1+1	STP11010
GO TO 216	STP11020
208 KS=KG	STP11030
210 CONTINUE	STP11040
211 IF(KDATAS.EQ.0) GO TO 212	STP11050
READ(FIT) KDATAS,(MTP(KS+I),TYM(KS+I),(DAT(J,K1+I),J=1,3),(SIG(J	STP11060
X,K1+I),J=1,3),I=1,KDATAS)	STP11070
KS=KS+KDATAS	STP11080
IF(KS-20) 210,215,215	STP11090
212 IF(KG+1-KS) 215,213,213	STP11100
213 KDATA=0	STP11110
GO TO 248	STP11120
215 K1=KG+1	STP11130
216 MTYPS=MTP(K1)	STP11140
TIMES=TYM(K1)	STP11150
IF(TIMES.GT.7FINAL) GO TO 213	STP11160
IF(NTR(MTYPS)) 220,218,220	STP11170
218 IF(TIMES.LT.DII(MTYPS)) GO TO 204	STP11180
TFIT(MTYPS)=TIMES	STP11190
NTR(MTYPS)=1	STP11200
220 CONTINUE	STP11210
222 IF(TIMES-DIF(MTYPS)) 224,224,204	STP11220
224 IF(TIMES-TFIT(MTYPS)) 226,234,228	STP11230
226 NTR(MTYPS)=J	STP11240
GO TO 204	STP11250
228 IF(NTR(MTYPS)-3) 230,232,230	STP11260
230 TFIT(MTYPS)=TFIT(MTYPS)+DIF(MTYPS)	STP11270
NTR(MTYPS)=3	STP11280
GO TO 224	STP11290
232 TFIT(MTYPS)=TIMES	STP11300
234 NTR(MTYPS)=2	STP11310
JNBR5=0	STP11320
DO 238 I=1,3	STP11330
IF(MR(I,MTYPS)) 236,238,236	STP11340

236	JNBRS=JNBRS+1	STP11350
	LCS(JNBRS)=1	STP11360
238	CONTINUE	STP11370
	IF(JNBRS) 240,204,240	STP11380
240	DATAS(1)=DAT(1,K1)	STP11390
	DATAS(2)=DAT(2,K1)	STP11400
	DATAS(3)=DAT(3,K1)	STP11410
	SIGMS(1)=SIG(1,K1)	STP11420
	SIGMS(2)=SIG(2,K1)	STP11430
	SIGMS(3)=SIG(3,K1)	STP11440
	IF(KDATA) 242,244,244	STP11450
242	KDATA=2	STP11455
	IF(TIMES-TZERO) 204,202,202	STP11460
244	IF(TIMES-TIME) 248,246,248	STP11470
246	JST=2	STP11480
	GO TO 250	STP11490
248	JST=1	STP11500
250	GO TO 24	STP11510
C-----PROCESSING LOOP, THRU EFN 278-----		STP11520
260	CALL INTAG	STP11530
	T0=T2	STP11540
	KPROP=0	STP11550
	KN=0	STP11560
	KK = 1	STP11570
	IF(JNBR-1) 270,270,262	STP11580
262	IF(NPC(9)) 268,264,268	STP11590
264	KN=1	STP11600
	GO TO 270	STP11610
268	KK=JNBR	STP11620
	IF(NPC(4)) 264,270,264	STP11630
270	KAR=1	STP11640
272	CALL OBSERV	STP11650
273	IF(T-TSAV) 274,276,274	STP11660
274	CALL PROP	STP11670
	TSAV=T	STP11680
276	IF(NPC(9).NE.0) KOB = KAR	STP11690
	CALL MINVAR	STP11700
	IF(KAR-KK) 278,30,30	STP11710
278	KAR=KAR+1	STP11720
	IF(KN.NE.0) GO TO 276	STP11730
	CALL MOTION	STP11740
	GO TO 272	STP11750
C-----UPDATE STATE, EQ.(55A), THRU EFN 312-----		STP11760
300	DO 306 I=1,10	STP11770
	SUM=0.	STP11780
	DO 304 K=1,10	STP11790
304	SUM=SUM+PH(I,K)*DZ(K)	STP11800
306	DUD(I)=SUM	STP11810
	DO 312 I=1,NSTX	STP11820
	IF(I-10) 308,308,310	STP11830
308	DZ(I)=DUD(I)	STP11840
	X(I)=X(I)+DZ(I)	STP11850
	GO TO 312	STP11860
310	K=NC(I-10)	STP11870
	C(K)=C(K)+DZ(1)	STP11880
	VO(I-10)=C(K)	STP11890
312	CONTINUE	STP11900
C-----NORMALIZE QUATERNION-----		STP11910
	DATC(1)= X(7)**2 + X(8)**2 + X(9)**2 + X(10)**2	STP11920
	X(7) = X(7)/DATC(1)	STP11930

x(8) = x(8)/DATC(1)	STP11940
x(9) = x(9)/DATC(1)	STP11950
x(10)=x(10)/DATC(1)	STP11960
C-----UPDATE TRACKING STATION LOCATIONS-----	STP11970
IF(KSS.LE.0) GO TO 316	STP11980
DO 314 I=1,KSS	STP11990
MTYP=NSS(I)	STP12000
314 CALL STAT	STP12010
316 WRITE(OUT,1003)	STP12020
1003 FORMAT(39H UPDATED MODEL PARAMETERS AT FINAL TIME)	STP12030
WRITE(OUT,1002) (NC(I),VO(I),I=1,NSTC)	STP12040
1002 FORMAT(6(2F 0.13,E15.8))	STP12050
GO TO 58	STP12060
END	STP12070

```

SUBROUTINE AERO (ARG1,ARG2,ARG3,ARG4,XX,YY,ZZ)
COMMON /INTGRL/ LCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS ,BETA,CA(6),CALP ,CBET ,CETA ,
1 CF(3),JCS ,CAZ1 ,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH ,
2 DRCP,DRDH(2),ETA,HO,N4(3) ,N5(3) ,N6(3) ,PAXP(3,30),
3 PE ,ROE ,ROEC ,ROEM ,SALP ,SBET ,
4 SETA ,SREF ,SXZI ,TAU ,TMAS(20) ,TONE ,
5 TTWO ,TUW(20) ,TVW(20) ,Uw ,VA(5) ,VB(5) ,
6 VW ,XIND1 ,XIND2 ,XLREF ,XM ,
7 XMAS(20) ,XNU ,XQ ,XCSM ,XRE ,XTEMP ,
8 XUV(20) ,XVW(20) ,XZI ,YMAS ,YMASM
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VC(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,LUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JU ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NWN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,LET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENC/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A ,PB(23),RL(23),TMB(23)
COMMON /EXTRA / GO
COMMON /AERTAB/ TABLES(580,3),SAVIND(3,3)
DIMENSION TCX(580),TCY(580),TCZ(580),ISTORE(1)
EQUIVALENCE (TCX,TABLES(1,1)),(TCY,TABLES(1,2)),(TCZ,TABLES(1,3)),
1 (ISTORE(1),KD(1))
C *** STORE THE INDEPENDENT ARGUMENTS
ST(1)=ARG1
ST(2)=ARG2
ST(3)=ARG3
C *** INITIALIZE TABLE-LOOKUP-VALUES ARRAY
60 SP(1)=0.
SP(2)=0.
SP(3)=0.
C *** FIND ALL AERODYNAMIC COEFFICIENTS
DO 90 L=1,3
DUD=TABLES(1,L)

```

IF(DUD.NE.-1.) GO TO 10	AER00160
SP(L)=0.	AER00170
GO TO 90	AER00180
10 IF(DUD.NE.0) GO TO 15	AER00190
SP(L)=TABLES(5,L)	AER00200
GO TO 90	AER00210
15 J=1	AER00220
K=1	AER00230
NPTS=DUD	AER00240
C *** DELETE INDEPENDENT ARGUMENTS HAVING VALUE ZERO - - -	AER00250
C *** FOR PURPOSES OF TABLE LOOK-UP	AER00260
DO 40 I=1,NPTS	AER00270
J=K+1	AER00280
C IF(J.GT.4) * * * * * ERROR MESSAGE	AER00290
DO 20 K=J,4	AER00300
K=K	AER00310
M=K-1	AER00320
IF(SAVIND(M,L).EQ.0) GO TO 20	AER00330
DUE(I)=ST(M)	AER00340
GO TO 40	AER00350
20 CONTINUE	AER00360
40 CONTINUE	AER00370
SP(L)=FUNCT(TABLES(1,L),DUE)	AER00380
90 CONTINUE	AER00390
CA(1) = SP(1)	AER00400
CA(2) = SP(2)	AER00410
CA(3) = SP(3)	AER00420
C *** ADJUST THE COEFFICIENTS JUST FOUND	AER00430
B(1)=1./(ARG3+1.)**2	AER00440
B(2)=ARG3**.618/SQRT(ARG4)	AER00450
SP(1)=SP(1)+C(1)+C(4)*ARG1**2+C(7)*B(1)+C(10)*B(2)	AER00460
SP(2)=SP(2)+C(2)+C(5)*ARG2 +C(8)*B(1)+C(11)*B(2)	AER00470
SP(3)=SP(3)+C(3)+C(6)*ARG1 +C(9)*B(1)+C(12)*B(2)	AER00480
C *** ADJUST CF VECTOR ACCORDING TO NPC(11) LOGIC CONTROL	AER00490
IF(NPC(11).NE.1) GO TO 100	AER00500
XX=-SP(1)	AER00510
YY= CXZ1*SP(2)-SXZ1*SP(3)	AER00520
ZZ=-SXZ1*SP(2)-CXZ1*SP(3)	AER00530
GO TO 120	AER00540
100 IF(NPC(11).EQ.0) GO TO 110	AER00550
XX=-CALP*SP(1)+SALP*SP(3)	AER00560
YY= SP(2).	AER00570
ZZ=-SALP*SP(1)-CALP*SP(3)	AER00580
GO TO 120	AER00590
110 XX=-SP(1)	AER00600
YY= SP(2)	AER00610
ZZ=-SP(3)	AER00620
120 RETURN	AER00630
END	AER00640

```

SUBROUTINE AEROIN
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),      COMM0010
* NALL,LRK                                                         COMM0020
COMMON /MOD1/ ALPH,AS ,BETA,CA(6),CALP ,CBET ,CETA ,              COMM0030
1 CF(3),JCS ,CXZI ,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH ,      COMM0040
2 DRDP,BWDH(2),ETA,HO,N4(3) ,N5(3) ,N6(3) ,PAXP(3,30),          COMM0050
3 PE ,ROE ,ROEC ,ROEM ,SALP ,SBET ,              COMM0060
4 SETA ,SREF ,SXZI ,TAU ,TAS(20) ,TONE ,              COMM0070
5 TTWO ,TUW(20) ,TVW(20) ,UW ,VA(5) ,VB(5) ,              COMM0080
6 VW ,XIND1 ,XIND2 ,XLREF ,XM ,              COMM0090
7 XMAS(20) ,XNU ,XG ,XGSM ,XRE ,XTEMP ,              COMM0100
8 XOW(20) ,XVW(20) ,XZI ,YMAS ,YMASM              COMM0110
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)              COMM0120
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)              COMM0130
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3) ,DUD(10,1) ,DUE(4)          COMM0140
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)          COMM0150
4 ,IDN ,I1 ,IP ,IPC ,JJ ,JN ,KA ,KD(3) ,KDUM ,KG2              COMM0160
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PBOT(3) ,PMDOT(3) ,RES(6)            COMM0170
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3) ,XX(50)                          COMM0180
DIMENSION DUB(30,15)                                             COMM0190
EQUIVALENCE (AG(1),DUB(1,1))                                     COMM0200
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)              COMM0210
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)          COMM0220
2 ,CVZ(30,5) ,D(5) ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)        COMM0230
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET                      COMM0240
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST          COMM0250
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG ,KI ,KK              COMM0260
6 ,KN ,KOB ,KPROP ,KS ,KSM ,KSS ,L ,LC(3) ,LCS(3) ,LS ,LT          COMM0270
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT                      COMM0280
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCCOUNT ,NPC(15)            COMM0290
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)      COMM0300
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)                COMM0310
B ,PA(3) ,PM(3) ,R ,REC ,RERP2 ,                                COMM0320
C ,RPC ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)                COMM0330
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL      COMM0340
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)                    COMM0350
F ,TK(40) ,TI(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)        COMM0360
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)                       COMM0370
H ,XYCG(20) ,XZCG(20)                                             COMM0380
INTEGER OUT,FIT,STATE,SCRACH,PGR                                 COMM0390
COMMON /TAPCON/ IN,OUT,FIT,STATE,SCRACH,PGR                      COMM0400
COMMON /ATMCON /ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK    COMM0410
A ,PB(23),RL(23),TMB(23)                                          COMM0420
COMMON /EXTRA / GO                                               COMM0430
COMMON /AERTAB/ TABLES(580,3),SAVIND(3,3)                       ARIN0010
DIMENSION TCX(580),TCY(580),TCZ(580),ISTORE(1)                   ARIN0020
EQUIVALENCE (TCX, TABLES(1,1)), (TCY, TABLES(1,2)), (TCZ, TABLES(1,3)), ARIN0030
1 (ISTORE(1),KC(1))                                               ARIN0040
C *** ZERO TABLES ARRAY                                         ARIN0050
DO 10 I=1,1740                                                    ARIN0060
10 TABLES(I)=0.                                                  ARIN0070
DO 20 I=1,9                                                       ARIN0080
20 SAVING(I)=0.                                                  ARIN0090
C *** READ IN ALL THREE AERODYNAMIC-COEFFICIENT TABLES        ARIN0100
DO 200 N=1,3                                                      ARIN0110
NNN=0                                                            ARIN0120
KC(1)=1                                                           ARIN0130
KC(2)=2                                                           ARIN0140
KC(3)=3                                                           ARIN0150

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```

C   *** READ IN TABLE IDENTIFIER AND INDEPENDENT
C   *** VARIABLE-AND-VALUE COUNTERS
      READ ( IN,30) IDN,(ISTORE(J),J=1,4)
      WRITE(OUT,30) IDN,(ISTORE(J),J=1,4)
30  FORMAT(5I4)
      IF(ISTORE(1).EQ.-1) GO TO 200
      NT=J
C   *** (ONE) OR (NO) INDEPENDENT VALUES FOR A GIVEN
C   *** INDEPENDENT VARIABLE ARE SPECIAL CASES
      DO 40 LT=2,4
      IF(ISTORE(LT).EQ.1) ISTORE(LT)=0
40  NT=NT+ISTORE(LT)
      IF(NT.EQ.0) ISTORE(1)=0
      IF(ISTORE(1).NE.0) GO TO 70
      READ ( IN,50) TABLES(5,IDN)
      WRITE(OUT,60) TABLES(5,IDN)
50  FORMAT(12E6.4)
60  FORMAT(12F10.6)
      GO TO 200
C   *** SAVE INDEPENDENT VALUE INFORMATION FOR USE IN SUBROUTINE AERO
70  DO 80 MT=1,3
80  SAVIND(MT,IDN)=ISTORE(MT+1)
      DO 90 K=1,4
90  TABLES(K,IDN)=ISTORE(K)
      NPTS=4
C   *** COUNT INDEPENDENT VARIABLES TO BE ENTERED AND
C   *** SET UP CONVERSION INDICATORS
      DO 110 L=1,3
      IF(TABLES(L+1,IDN).NE.0.) GO TO 110
      NNN=NNN+1
      DO 100 J=L,3
100  KC(J)=KC(J)+1
110  CONTINUE
C   *** COMPRESS INPUT WHEN ENTERING MONOVARIATE OR BIVARIATE TABLES
      IF(SAVIND(1,IDN).EQ.0.AND.SAVIND(2,IDN).EQ.0) KC(1)=3
      IF(TABLES(2,IDN).NE.0) GO TO 120
      TABLES(2,IDN)=TABLES(3,IDN)
      TABLES(3,IDN)=TABLES(4,IDN)
      TABLES(4,IDN)=0.
      IF(TABLES(2,IDN).NE.0) GO TO 130
      TABLES(2,IDN)=TABLES(3,IDN)
      TABLES(3,IDN)=0.
      GO TO 130
120  IF(TABLES(3,IDN).NE.0) GO TO 130
      TABLES(3,IDN)=TABLES(4,IDN)
      TABLES(4,IDN)=0.
130  NPTS=NPTS-NNN
      KD(1)=TABLES(2,IDN)
      KD(2)=TABLES(3,IDN)
      KD(3)=TABLES(4,IDN)
C   *** SET FACTORS TO BE USED IN COMPUTING LOOP LIMITS BELOW
      DO 140 K1=1,3
      IF(KD(K1).EQ.0) KD(K1)=1
140  CONTINUE
C   *** READ IN ALL INDEPENDENT VALUES AND CONVERT WHERE NECESSARY
      DO 170 I=1,3
      IF(KD(I).NE.1) GO TO 150
      GO TO 170
150  KDUM=NPTS+1
      NPTS=NPTS+KD(I)

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ARIN0160
ARIN0170
ARIN0180
ARIN0190
ARIN0200
ARIN0210
ARIN0220
ARIN0230
ARIN0240
ARIN0250
ARIN0260
ARIN0270
ARIN0280
ARIN0290
ARIN0300
ARIN0310
ARIN0320
ARIN0330
ARIN0340
ARIN0350
ARIN0360
ARIN0370
ARIN0380
ARIN0390
ARIN0400
ARIN0410
ARIN0420
ARIN0430
ARIN0440
ARIN0450
ARIN0460
ARIN0470
ARIN0480
ARIN0490
ARIN0500
ARIN0510
ARIN0520
ARIN0530
ARIN0540
ARIN0550
ARIN0560
ARIN0570
ARIN0580
ARIN0590
ARIN0600
ARIN0610
ARIN0620
ARIN0630
ARIN0640
ARIN0650
ARIN0660
ARIN0670
ARIN0680
ARIN0690
ARIN0700
ARIN0710
ARIN0720
ARIN0730
ARIN0740
ARIN0750

```

READ (IN,50) (TABLES(J, IDN),J=KDUM,NPTS)	ARIN0760
WRITE(OUT,60) (TABLES(J, IDN),J=KDUM,NPTS)	ARIN0770
IF(KC(I).GE.3) GO TO 180	ARIN0780
DO 100 M=KDUM,NPTS	ARIN0790
160 TABLES(M, IDN)=TABLES(M, IDN)*CONRD	ARIN0800
170 CONTINUE	ARIN0810
C *** READ IN ALL DEPENDENT VALUES FOR ONE TABLE	ARIN0820
180 II=NPTS+1	ARIN0830
JJ=NPTS+KD(1)*KD(2)*KD(3)	ARIN0840
READ (IN,50) (TABLES(J, IDN),J=II, JJ)	ARIN0850
WRITE(OUT,60) (TABLES(J, IDN),J=II, JJ)	ARIN0860
200 CONTINUE	ARIN0870
RETURN	ARIN0880
END	ARIN0890

SUBROUTINE ATMDAT(ZE,PE,ROE,CE,TM,VMU,H,ISVX)	
COMMON /ATMCON /ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK	
A ,PB(23),RL(23),TMB(23)	ATMD0010
COMMON /EXTRA / GO	ATMD0020
IF(JK-2) 20,20,22	ATMD0030
20 H= ATM(4)*ZE/(ATM(4)+ZE)	ATMD0040
GO TO 24	ATMD0050
22 H= ZE	ATMD0060
24 CONTINUE	ATMD0070
3 I = ISV	ATMD0080
IF(H-HB(I))4,5,6	ATMD0090
4 IF(H-HB(I-1))7,8,9	ATMD0100
5 TM = TMB(I)	ATMD0110
PE = PB(I)	ATMD0120
GO TO 15	ATMD0130
6 IF(H -HB(I+1))10,11,12	ATMD0140
7 I = I-1	ATMD0150
GO TO 4	ATMD0160
8 I = I - 1	ATMD0170
GO TO 5	ATMD0180
9 I = I - 1	ATMD0190
GO TO 10	ATMD0200
11 I = I + 1	ATMD0210
GO TO 5	ATMD0220
12 I = I + 1	ATMD0230
GO TO 6	ATMD0240
10 TM = TMB(I) + RL(I)*(H-HB(I))	ATMD0250
IF(RL(I))13,14,13	ATMD0260
13 PE = PB(I)*(TMB(I)/TM)**(ATM(1)/RL(I))	ATMD0270
GO TO 15	ATMD0280
14 PE = PB(I)*EXP(-ATM(1)*(H-HB(I))/TMB(I))	ATMD0290
15 ROE= ATM(2)*PE/TM	ATMD0300
CE = ATM(3)*SGRT(TM)	ATMD0310
VMU= ABET*TM**1.5/(TM+ASU)	ATMD0320
ISV = I	ATMD0330
99 RETURN	ATMD0340
END	ATMD0350
	ATMD0360


```

SUBROUTINE DATAB
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZI,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,HO,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TTWO,TUW(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XQSM,XRE,XTEMP,
8 XUW(20),XVW(20),XZI,YMAS,YMASM
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VO(20),ZO(20),AG(3),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),QTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,II,IP,IPC,JJ,JN,KA,KD(3),KDUM,KG2
5 K1,NNN,NPTS,PAR(6),PDOT(3),PMDOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHOT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRS,JST
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A N8(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHOT(5),SUM,SUM2,SYG(3,9),TFINAL
E TF11(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERC,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A PB(23),RL(23),TMB(23)
COMMON /EXTRA / GO
IF(DCOMP.LT.0.) GO TO 20
IF(KPROP.GE.0.) GO TO 10
2 CONTINUE
4 LS = 0
6 IF(KDAP.EQ.0) GO TO 14
READ(PQR) KDAP,(TT(LS+1),TP(LS+1),TQ(LS+1),TR(LS+1),AX(LS+1),
* AY(LS+1),AZ(LS+1),I=1,KDAP)
LS = LS+KDAP
IF(LS.EQ.1) GO TO 6
IF(T.GT.TT(LS)) GO TO 11
IF(LS.LE.20) GO TO 6
N11(2)=3
10 IF(T.LT.TT(LS-1)) GO TO 14
IF(KDAP.EQ.0) GO TO 14
KG2 = KG-2

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WRITE(SCRACH) LS,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),
* I=1,LS),KG2,(MTP(I),TYM(I),DAT(1,I),DAT(2,I),DAT(3,I),
* SIG(1,I),SIG(2,I),SIG(3,I),I=1,KG2)
IF(KG2.LE.0) GO TO 11
KG = 2
DO 13 I=1,2
LT = KG2 + I
MTP(I)= MTP(LT)
TYM(I)= TYM(LT)
DAT(1,I)= DAT(1,LT)
DAT(2,I) = DAT(2,LT)
DAT(3,I) = DAT(3,LT)
SIG(1,I) = SIG(1,LT)
SIG(2,I) = SIG(2,LT)
SIG(3,I) = SIG(3,LT)
13 CONTINUE
11 CONTINUE
DO 12 I=1,2
MT = LS + I - 2
TT(I) = TT(MT)
TP(I) = TP(MT)
TQ(I) = TQ(MT)
TR(I) = TR(MT)
AX(I) = AX(MT)
AY(I) = AY(MT)
AZ(I) = AZ(MT)
12 CONTINUE
LS = 2
GO TO 6
14 N11(1) = LS
IF(KPROP.LT.0) TRCD=TT(1)
KPROP = 1
PM(1) = TAB(T,N11(1),TT(1),TP(1))
PM(2)=TAB(T,N11(1),TT(1),TQ(1))
PM(3)=TAB(T,N11(1),TT(1),TR(1))
CGM(1) = TAB(T,N8(1),TXCG(1),XXCG(1))
CGM(2) = TAB(T,N9(1),TYCG(1),XYCG(1))
CGM(3) = TAB(T,N10(1),TZCG(1),XZCG(1))
99 RETURN
20 IF(T.GT.TT(2)) GO TO 14
IF(TT(1).EQ.TRCD) GO TO 14
BACKSPACE SCRACH
BACKSPACE SCRACH
LT = 40-KG
DO 22 I=1,KG
MT = LT+I
MTP(MT) = MTP(I)
TYM(MT) = TYM(I)
DAT(1,MT) = DAT(1,I)
DAT(2,MT) = DAT(2,I)
DAT(3,MT) = DAT(3,I)
SIG(1,MT) = SIG(1,I)
SIG(2,MT) = SIG(2,I)
22 SIG(3,MT) = SIG(3,I)
READ(SCRACH) KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),
* I=1,KDAP),KDATA,(MTP(I),TYM(I),DAT(1,I),DAT(2,I),DAT(3,I),
* SIG(1,I),SIG(2,I),SIG(3,I),I=1,KDATA)
LS=KDAP
N11(2)=LS-2
IF(KDATA.LT.0) GO TO 26

```

```

DATB0160
DATB0170
DATB0180
DATB0190
DATB0200
DATB0210
DATB0220
DATB0230
DATB0240
DATB0250
DATB0260
DATB0270
DATB0280
DATB0290
DATB0300
DATB0310
DATB0320
DATB0330
DATB0340
DATB0350
DATB0360
DATB0370
DATB0380
DATB0390
DATB0400
DATB0410
DATB0420
DATB0430
DATB0440
DATB0450
DATB0460
DATB0470
DATB0480
DATB0490
DATB0500
DATB0510
DATB0520
DATB0530
DATB0540
DATB0550
DATB0560
DATB0570
DATB0580
DATB0590
DATB0600
DATB0610
DATB0620
DATB0630
DATB0640
DATB0650
DATB0660
DATB0670
DATB0680
DATB0690
DATB0700
DATB0710
DATB0720
DATB0730
DATB0740
DATB0750

```

```
LT = LT - KDATA
I = KDATA+1
J = KDATA+KG
DC 24 I=I,J
MT = LT + I
MTP(I) = MTP(MT)
TYM(I) = TYM(MT)
DAT(1,I) = DAT(1,MT)
DAT(2,I) = DAT(2,MT)
DAT(3,I) = DAT(3,MT)
SIG(1,I) = SIG(1,MT)
SIG(2,I) = SIG(2,MT)
24 SIG(3,I) = SIG(3,MT)
KG = KG + KDATA
GO TO 14
26 KG = 1
GO TO 14
END
```

```
DATB0760
DATB0770
DATB0780
DATB0790
DATB0800
DATB0810
DATB0820
DATB0830
DATB0840
DATB0850
DATB0860
DATB0870
DATB0880
DATB0890
DATB0900
DATB0910
DATB0920
DATB0930
```

```

SUBROUTINE DERIVE
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS ,BETA,CA(6),CALP ,CBET ,CETA ,
1 CF(3),JCS ,CXZI ,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH ,
2 DRDP,DWDH(2),ETA,HO,N4(3) ,N5(3) ,N6(3) ,PAXP(3,30),
3 PE ,ROE ,ROEC ,ROEM ,SALP ,SBET ,
4 SETA ,SREF ,SXZI ,TAU ,TMAS(20) ,TONE ,
5 TTWO ,TUW(20) ,TVW(20) ,UW ,VA(5) ,VB(5) ,
6 VW ,XIND1 ,XIND2 ,XLREF ,XM ,
7 XMAS(20) ,XNU ,XQ ,XQSM ,XRE ,XTEMP ,
8 XUW(20) ,XVW(20) ,XZI ,YMAS ,YMASM
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5) ,D(5) ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,LI ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TI(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PGR
COMMON /TAPENC/ IN,OUT,FIT,STATE,SCRACH,PGR
COMMON /ATMCON /ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A ,PB(23),RL(23),TMB(23)
COMMON /EXTRA / GO
VO(1) = (VA(4)+50.)/AS
VO(2) = (VA(4)-50.)/AS
HI(1) = AS*ROE*XLREF/XNU
DO 2 N=1,2
HI(2) = VO(N)*HI(1)
2 CALL AERO(XIND1,XIND2,VO(N),HI(2),ZO(N),ZO(N+2),ZO(N+4))
DCDY(1,1) = (ZO(1)-ZO(2))*1.E-2
DCDY(2,1) = (ZO(3)-ZO(4))*1.E-2
DCDY(3,1) = (ZO(5)-ZO(6))*1.E-2
VO(1) = HO+50.
VO(2) = HO-50.
HI(1)=VA(4)*XLREF
DO 6 N=1,2
VO(N+2) = TAB(VO(N),N5(1),TUW(1),XUW(1))
VO(N+4) = TAB(VO(N),N6(1),TVW(1),XVW(1))
COMM0010
COMM0020
COMM0030
COMM0040
COMM0050
COMM0060
COMM0070
COMM0080
COMM0090
COMM0100
COMM0110
COMM0120
COMM0130
COMM0140
COMM0150
COMM0160
COMM0170
COMM0180
COMM0190
COMM0200
COMM0210
COMM0220
COMM0230
COMM0240
COMM0250
COMM0260
COMM0270
COMM0280
COMM0290
COMM0300
COMM0310
COMM0320
COMM0330
COMM0340
COMM0350
COMM0360
COMM0370
COMM0380
COMM0390
COMM0400
COMM0410
COMM0420
COMM0430
DERI0010
DERI0020
DERI0030
DERI0040
DERI0050
DERI0060
DERI0070
DERI0080
DERI0090
DERI0100
DERI0110
DERI0120
DERI0130
DERI0140
DERI0150

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CALL ATMDAT(VO(N),DUD(1),ZO(N),SP(3),DUD(2),DUD(3),DUD(4))	DERI0160
HI(2)=HI(1)*(C(21)*ZO(N)+C(22)*EXP(C(23)*VO(N)))/DUD(3)	DERI0170
ZO(3) = VA(4)/SP(3)	DERI0180
CALL AERO(XIND1,XIND2,ZO(3),HI(2),SP(N+3),SP(N+5),SP(N+7))	DERI0190
6 CONTINUE	DERI0200
DCDY(1,2) =(SP(4)-SP(5))*1.E-2	DERI0210
DCDY(2,2) =(SP(6)-SP(7))*1.E-2	DERI0220
DCDY(3,2) =(SP(8)-SP(9))*1.E-2	DERI0230
DRDH = C(21)*(ZO(1)-ZO(2))*1.E-2 + C(23)*ROEC	DERI0240
DWDH(1) = (VO(3)-VO(4))*1.E-2	DERI0250
DWDH(2) = (VO(5)-VO(6))*1.E-2	DERI0260
HI(1) = ALPH + .01	DERI0270
HI(2) = ALPH - .01	DERI0280
DO 14 N=1,2	DERI0290
IF(NPC(11)) 10,10,12	DERI0300
10 VO(1) = BETA	DERI0310
GO TO 14	DERI0320
12 ZO(1) = SIN(HI(N))	DERI0330
ZO(2) = COS(HI(N))	DERI0340
HI(N) = ATAN2(SQRT((ZO(1)*CBET)**2+SBET**2),ZO(2)*CBET)	DERI0350
VO(1) = ATAN2(SBET,ZO(1)*CBET)	DERI0360
14 CALL AERO(HI(N),VO(1),XM,XRE,VO(N+1),VO(N+3),VO(N+5))	DERI0370
DCDY(1,3) =(VO(2)-VO(3))*5E+2	DERI0380
DCDY(2,3) =(VO(4)-VO(5))*5E+2	DERI0390
DCDY(3,3) =(VO(6)-VO(7))*5E+2	DERI0400
HI(1) = BETA + .01	DERI0410
HI(2) = BETA - .01	DERI0420
DO 22 N=1,2	DERI0430
IF(NPC(11)) 18,18,20	DERI0440
18 VO(1) = ALPH	DERI0450
GO TO 22	DERI0460
20 ZO(1) = SIN(HI(N))	DERI0470
ZO(2) = COS(HI(N))	DERI0480
VO(1) = ATAN2(SQRT((SALP*ZO(2))**2+ZO(1)**2),CALP*ZO(2))	DERI0490
HI(N) = ATAN2(ZO(1),SALP*ZO(2))	DERI0500
22 CALL AERO(VO(1),HI(N),XM,XRE,VO(N+1),VO(N+3),VO(N+5))	DERI0510
DCDY(1,4) =(VO(2)-VO(3))*5E+2	DERI0520
DCDY(2,4) =(VO(4)-VO(5))*5E+2	DERI0530
DCDY(3,4) =(VO(6)-VO(7))*5E+2	DERI0540
DRDP = -(RERP2-1.)*RO*SPH*CPH/(1.+(RERP2-1.)*SPH**2)	DERI0550
SP(1) = 2.*VA(1)/VA(5)	DERI0560
SP(2) = 2.*VA(2)/VA(5)	DERI0570
SP(3) = 2.*VA(3)/VA(5)	DERI0580
SP(6) = DRDH/ROE + SP(1)*DWDH(1) + SP(2)*DWDH(2)	DERI0590
SP(4) = SP(6) - SP(2)*OMEGA*CPH	DERI0600
SP(5) =-SP(6)*DRDP + SP(2)*R*OMEGA*SPH	DERI0610
ZO(5) = SBET/CBET	DERI0620
DO 28 I=1,3	DERI0630
DADX(1,I) = (VB(1)*A(3,I)-VB(3)*A(1,I))/VB(4)**2	DERI0640
DADX(2,I) = (CBET*A(2,I)-ZO(5)*(VA(I)-A(2,I)*VB(2))/VA(4))/VA(4)	DERI0650
28 CONTINUE	DERI0660
DO 30 I=1,2	DERI0670
ZO(1) = OMEGA*DADX(I,2)	DERI0680
DADX(I,4) =-CPH*ZO(1)	DERI0690
DADX(I,5) = SPH*ZO(1)*R	DERI0700
30 DADX(I,6) = 0.	DERI0710
ZO(1) = VA(1)*X(7) + VA(2)*X(10) - VA(3)*X(9)	DERI0720
ZO(2) = VA(1)*X(8) + VA(2)*X(9) + VA(3)*X(10)	DERI0730
ZO(3) = VA(1)*X(9) - VA(2)*X(8) + VA(3)*X(7)	DERI0740
ZO(4) = VA(1)*X(10) - VA(2)*X(7) - VA(3)*X(8)	DERI0750

VO(1) = VB(1)*ZO(3) - VB(3)*ZO(1)	DERI0760
VO(2) = VB(1)*ZO(4) - VB(3)*ZO(2)	DERI0770
VO(3) = VB(1)*ZO(1) + VB(3)*ZO(3)	DERI0780
VO(4) = VB(1)*ZO(2) + VB(3)*ZO(4)	DERI0790
VO(5) = 2./VB(4)**2	DERI0800
DO 32 I=7,10	DERI0810
32 DADX(1,I) = VO(I-6)*VO(5)	DERI0820
ZO(6) = 2./VA(4)	DERI0830
DADX(2,7) = ZO(6)*(-CBET*ZO(4)-ZO(5)*VO(3)/VA(4))	DERI0840
DADX(2,8) = ZO(6)*(-CBET*ZO(3)-ZO(5)*VO(4)/VA(4))	DERI0850
DADX(2,9) = ZO(6)*(-CBET*ZO(2)+ZO(5)*VO(1)/VA(4))	DERI0860
DADX(2,10) = ZO(6)*(-CBET*ZO(1)+ZO(5)*VO(2)/VA(4))	DERI0870
ZO(7) = VA(2)*SPH*OMEGA*R/VA(4)	DERI0880
ZO(8) = (VA(1)*DWDH(1) + VA(2)*(DWDH(2)-OMEGA*CPH))/VA(4)	DERI0890
DO 36 I=1,3	DERI0900
DO 34 J=1,3	DERI0910
34 DERIV(I,J) = AB(I)*SP(J) + XGSM*(VA(J)*DCDY(I,1) /VA(4)	DERI0920
1 + DCDY(I,3)*DADX(1,J) + DCDY(I,4)*DADX(2,J)	DERI0930
DERIV(I,4) = AB(I)*SP(4) + XGSM*(DCDY(I,1)*ZO(8) + DCDY(I,2)	DERI0940
1 + DCDY(I,3)*DADX(1,4) + DCDY(I,4)*DADX(2,4)	DERI0950
DERIV(I,5) = AB(I)*SP(5) + XGSM*(DCDY(I,1)*ZO(7) - DCDY(I,2)*DRDP	DERI0960
1 + DCDY(I,3)*DADX(1,5) + DCDY(I,4)*DADX(2,5)	DERI0970
DO 35 J=7,10	DERI0980
35 DERIV(I,J) = XGSM*(DCDY(I,3)*DADX(1,J) + DCDY(I,4)*DADX(2,J))	DERI0990
36 DERIV(I,6) = 0.	DERI1000
RETURN	DERI1010
END	DERI1020

FUNCTION FUNCT(CRVE,X)	
DIMENSION C(3),IDX(3),CRVE(2),X(3),Z(3)	FUNC0010
DATA IERCNT /0/	FUNC0020
DATA IDX/3*0/	FUNC0030
N1 = CRVE(2)	FUNC0040
N2 = CRVE(3)	FUNC0050
M = CRVE(1)	FUNC0060
IF(M.LT.2) N1 = 0	FUNC0070
IF(M.LT.3) N2 = 0	FUNC0080
N2 = N1*N2	FUNC0090
K = M + 1	FUNC0100
DO 25 I=1,M	FUNC0110
J = K + 2	FUNC0120
N = CRVE(I+1)	FUNC0130
K = J + N - 2	FUNC0140
DO 10 L = J,K	FUNC0150
L=L	FUNC0160
IF(X(I).GE.CRVE(L-1)) GO TO 8	FUNC0170
C *** EXTRAPOLATE BACKWARDS	FUNC0180
C(I)=(X(I)-CRVE(L-1))/(CRVE(L)-CRVE(L-1))	FUNC0190
GO TO 25	FUNC0200
8 IF(X(I).LE.CRVE(L)) GO TO 20	FUNC0210
10 CONTINUE	FUNC0220
C *** EXTRAPOLATE FORWARDS	FUNC0230
C(I)=(X(I)-CRVE(L-1))/(CRVE(L)-CRVE(L-1))	FUNC0240
GO TO 25	FUNC0250
15 CONTINUE	FUNC0260
Z(1) = 0.0	FUNC0270
GOTO 100	FUNC0280
20 C(I) = (X(I)-CRVE(L-1))/(CRVE(L)-CRVE(L-1))	FUNC0290
25 IDX(I) = L - J + 2	FUNC0300
N = K + IDX(1) + N1*(IDX(2)-2) + N2*(IDX(3)-2)	FUNC0310
Z(1) = CRV(CRVE,N,C(1))	FUNC0320
IF(M.LT.2) GO TO 100	FUNC0330
N = N + N1	FUNC0340
Z(2) = CRV(CRVE,N,C(1))	FUNC0350
Z(1) = CRV(Z,2,C(2))	FUNC0360
IF(M.EQ.2) GO TO 100	FUNC0370
N = N - N1 + N2	FUNC0380
Z(2) = CRV(CRVE,N,C(1))	FUNC0390
N = N + N1	FUNC0400
Z(3) = CRV(CRVE,N,C(1))	FUNC0410
Z(2) = CRV(Z(1),3,C(2))	FUNC0420
Z(1) = CRV(Z(1),2,C(3))	FUNC0430
100 FUNCT = Z(1)	FUNC0440
RETURN	FUNC0450
END	FUNC0460
FUNCTION CRV(A,N,C)	
DIMENSION A(2)	CRVT0010
CRV = A(N-1) + C*(A(N)-A(N-1))	CRVT0020
RETURN	CRVT0030
END	CRVT0040

```

SUBROUTINE FXXU
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),      COMM0010
* NALL,LRK                                                              COMM0020
COMMON /MOD1/ ALPH,AS ,BETA,CA(6),CALP ,CBET ,CETA ,                COMM0030
1 CF(3),JCS ,CXZ1 ,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH ,        COMM0040
2 DRDP,DWDH(2),ETA,HO,N4(3) ,N5(3) ,N6(3) ,PAXP(3,30),            COMM0050
3 PE ,ROE ,ROEC ,ROEM ,SALP ,SBET ,                COMM0060
4 SETA ,SREF ,SXZI ,TAU ,TMAS(20) ,TONE ,                COMM0070
5 TTWO ,TUW(20) ,TVW(20) ,UW ,VA(5) ,VB(5) ,                COMM0080
6 VW ,XIND1 ,XIND2 ,XLREF ,XM ,                COMM0090
7 XMAS(20) ,XNU ,XG ,XGSM ,XRE ,XTEMP ,                COMM0100
8 XUW(20) ,XVW(20) ,XZI ,YMAS ,YMASM                    COMM0110
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)                COMM0120
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)                COMM0130
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUO(10,1),DUE(4)            COMM0140
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)           COMM0150
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2                COMM0160
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PMDOT(3) ,RES(6)                    COMM0170
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)                          COMM0180
DIMENSION DUB(30,15)                                              COMM0190
EQUIVALENCE (AG(1),DUB(1,1))                                     COMM0200
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)              COMM0210
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,GPHOT(5) ,CUZ(30,5)        COMM0220
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)         COMM0230
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET                    COMM0240
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST       COMM0250
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK                COMM0260
6 ,KN ,KOB ,KPROP,KS ,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT         COMM0270
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT                    COMM0280
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)            COMM0290
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)   COMM0300
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)               COMM0310
B ,PA(3) ,PM(3) ,R ,REO ,RERP2 ,                COMM0320
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)               COMM0330
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL     COMM0340
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)                   COMM0350
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)       COMM0360
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)                     COMM0370
H ,XYCG(20) ,XZCG(20)                                          COMM0380
INTEGER OUT,FIT,STATE,SCRACH,PQR                                  COMM0390
COMMON /TAPENC/ IN,OUT,FIT,STATE,SCRACH,PQR                      COMM0400
COMMON /ATMCON /ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK   COMM0410
A ,PB(23),RL(23),TMB(23)                                        COMM0420
COMMON /EXTRA / GO                                              COMM0430
DIMENSION CX(3,4)                                               FXXU0010
DIMENSION XPM(3,3)                                              FXXU0020
EQUIVALENCE (XPM(1,1),DPH(1,1))                                 FXXU0030
EQUIVALENCE (C(48),CX(1,1))                                    FXXU0040
DIMENSION NO(1)                                                 FXXU0050
DATA NO(1) /-1/                                                FXXU0060
DATA ITER /5/                                                  FXXU0070
SP(1) = PAR(4)*X(2)/CPH**2                                     FXXU0080
F2(2,1) = 1./R                                                FXXU0090
F1(1,3) = F2(2,1)*X(1)                                        FXXU0100
F1(3,1) = -F1(1,3)-F1(1,3)                                    FXXU0110
F1(3,2) = -F1(2,3)-F1(2,3)                                    FXXU0120
F1(1,1) = F2(2,1)*X(3)                                        FXXU0130
F1(1,2) = -F1(2,1)-F1(2,1)                                    FXXU0140
F1(1,4) = (-PAR(5)*F2(2,1)+4.*PAR(3)*SPH*CPH)*F2(2,1)        FXXU0150

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F1(1,5) = SP(1)*F1(3,2)*R - PAR(3)*(CPH+SPH)*(CPH-SPH)	FXXU0160
F1(2,4) = -F1(2,2)*F1(2,3)	FXXU0170
F1(2,5) = -SP(1)*F1(3,1)*R	FXXU0180
F1(3,4) = (PAR(1)*F2(2,1)-PAR(2)-PAR(2) + 4.*PAR(3)*PAR(6))*	FXXU0190
* F2(2,1)	FXXU0200
F1(3,5) = -3.*PAR(3)*SPH*CPH	FXXU0210
F2(2,4) = -F1(1,3)*F2(2,1)	FXXU0220
F2(3,2) = F2(2,1)/CPH	FXXU0230
F2(3,4) = -F1(2,3)*F2(3,2)	FXXU0240
F2(3,5) = F1(2,1)/CPH	FXXU0250
F3(1,1) = -X(9)*PAR(4)	FXXU0260
F3(2,1) = X(10)*PAR(4)	FXXU0270
F3(3,1) = X(7)*PAR(4)	FXXU0280
F3(4,1) = -X(8)*PAR(4)	FXXU0290
F3(1,2) = (X(8)-X(10)*TPH)*PAR(4)	FXXU0300
F3(2,2) = -(X(7)+X(9)*TPH)*PAR(4)	FXXU0310
F3(3,2) = (X(10)+X(8)*TPH)*PAR(4)	FXXU0320
F3(4,2) = -(X(9)-X(7)*TPH)*PAR(4)	FXXU0330
F3(1,4) = -F1(1,3)*F3(1,1) - F1(2,3)*F3(1,2)	FXXU0340
F3(2,4) = -F1(1,3)*F3(2,1) - F1(2,3)*F3(2,2)	FXXU0350
F3(3,4) = -F1(1,3)*F3(3,1) - F1(2,3)*F3(3,2)	FXXU0360
F3(4,4) = -F1(1,3)*F3(4,1) - F1(2,3)*F3(4,2)	FXXU0370
F3(1,5) = -X(10)*SP(1)	FXXU0380
F3(2,5) = -X(9)*SP(1)	FXXU0390
F3(3,5) = X(8)*SP(1)	FXXU0400
F3(4,5) = X(7)*SP(1)	FXXU0410
F1(1,7) = 2.*(X(7)*AB(1)-X(10)*AB(2)+X(9)*AB(3))	FXXU0420
F1(1,8) = 2.*(X(8)*AB(1)+X(9)*AB(2)+X(10)*AB(3))	FXXU0430
F1(1,9) = 2.*(-X(9)*AB(1)+X(8)*AB(2)+X(7)*AB(3))	FXXU0440
F1(1,10) = -2.*(X(10)*AB(1)+X(7)*AB(2)-X(8)*AB(3))	FXXU0450
F1(2,7) = -F1(1,10)	FXXU0460
F1(2,8) = -F1(1, 9)	FXXU0470
F1(2,9) = F1(1, 8)	FXXU0480
F1(2,10) = F1(1, 7)	FXXU0490
F1(3,7) = F1(1, 9)	FXXU0500
F1(3,8) = -F1(1,10)	FXXU0510
F1(3,9) = -F1(1, 7)	FXXU0520
F1(3,10) = F1(1, 8)	FXXU0530
F3(2,7) = -F3(1,8)	FXXU0540
F3(3,7) = -F3(1, 9)	FXXU0550
F3(3,8) = -F3(2, 9)	FXXU0560
F3(4,7) = -F3(1,10)	FXXU0570
F3(4,8) = -F3(2,10)	FXXU0580
F3(4,9) = -F3(3,10)	FXXU0590
F2(1,3) = -1.	FXXU0600
F1(1,6) = 0.	FXXU0610
F1(2,6) = 0.	FXXU0620
F1(3,6) = 0.	FXXU0630
F1(3,3) = 0.	FXXU0640
F2(1,1) = 0.	FXXU0650
F2(1,2) = 0.	FXXU0660
F2(1,4) = 0.	FXXU0670
F2(1,5) = 0.	FXXU0680
F2(2,2) = 0.	FXXU0690
F2(2,3) = 0.	FXXU0700
F2(2,5) = 0.	FXXU0710
F2(3,1) = 0.	FXXU0720
F2(3,3) = 0.	FXXU0730
F3(1,3) = 0.	FXXU0740
F3(2,3) = 0.	FXXU0750

F3(3,3) = 0.	FXXU0760
F3(4,3) = 0.	FXXU0770
F3(1,6) = 0.	FXXU0780
F3(2,6) = 0.	FXXU0790
F3(3,6) = 0.	FXXU0800
F3(4,6) = 0.	FXXU0810
F3(1,7) = 0.	FXXU0820
F3(2,8) = 0.	FXXU0830
F3(3,9) = 0.	FXXU0840
F3(4,10)= 0.	FXXU0850
CALL DERIVE	FXXU0860
DO 410 J=1,10	FXXU0870
DO 410 I=1,3	FXXU0880
SUM=F1(I,J)	FXXU0890
DO 400 K=1,3	FXXU0900
SUM=SUM+A(K,I)*DERIV(K,J)	FXXU0910
400 CONTINUE	FXXU0920
F1(I,J)=SUM	FXXU0930
410 CONTINUE	FXXU0940
IF(NO(1)) 415,425,420	FXXU0950
415 VO(10)=AP(1)**2+AP(3)**2	FXXU0960
VO(11)=AP(4)*(1./AP(1)-AP(1)/VO(10))	FXXU0970
VO(12)=AP(4)*(1./AP(3)-AP(3)/VO(10))	FXXU0980
420 CONTINUE	FXXU0990
K = 0	FXXU1000
DO 422 I=1,3	FXXU1010
DO 422 J=1,3	FXXU1020
K = K+1	FXXU1030
422 SP(K) = PA(I)*XP(J)	FXXU1040
DTRAN(1,1) = SP(5) + SP(9)	FXXU1050
DTRAN(1,2) = -2.*SP(4) + SP(2)	FXXU1060
DTRAN(1,3) = -2.*SP(7) + SP(3)	FXXU1070
DTRAN(2,1) = SP(4) - 2.*SP(2)	FXXU1080
DTRAN(2,2) = SP(1) + SP(9)	FXXU1090
DTRAN(2,3) = -2.*SP(8) + SP(6)	FXXU1100
DTRAN(3,1) = SP(7) - 2.*SP(3)	FXXU1110
DTRAN(3,2) = SP(8) - 2.*SP(6)	FXXU1120
DTRAN(3,3) = SP(1) + SP(5)	FXXU1130
425 DO 500 N=1,10	FXXU1140
SP(4)=0.	FXXU1150
SP(5)=0.	FXXU1160
SP(6)=0.	FXXU1170
IF(N.NE.6) GO TO 440	FXXU1180
PAXP(1,6) = 0.	FXXU1190
PAXP(2,6) = 0.	FXXU1200
PAXP(3,6) = 0.	FXXU1210
PAXP(4,6) = 0.	FXXU1220
GO TO 500	FXXU1230
440 DO 470 KA=1,ITER	FXXU1240
DO 450 I=1,3	FXXU1250
PAXP(I,N)=DERIV(I,N)	FXXU1260
DO 450 J=1,3	FXXU1270
PAXP(I,N) = PAXP(I,N) + DTRAN(I,J)*SP(J+3)	FXXU1280
450 CONTINUE	FXXU1290
IF(NO(1)) 455,460,460	FXXU1300
455 PAXP(4,N)=VO(11)*PAXP(1,N)+VO(12)*PAXP(3,N)	FXXU1310
460 DO 470 I=1,3	FXXU1320
SP(I+3)=0.	FXXU1330
IF(I.EQ.1) SP(4) = CX(1,4)*PAXP(4,N)	FXXU1340
DO 470 J=1,3	FXXU1350

	SP(I+3)=SP(I+3)+CX(I,J)*PAXP(J,N)	FXXU1360
470	CONTINUE	FXXU1370
	F3(1,N)=F3(1,N)+.5*(-X(8)*SP(4)-X(9)*SP(5)-X(10)*SP(6))	FXXU1380
	F3(2,N)=F3(2,N)+.5*(X(7)*SP(4)-X(10)*SP(5)+X(9)*SP(6))	FXXU1390
	F3(3,N)=F3(3,N)+.5*(X(10)*SP(4)+X(7)*SP(5)-X(8)*SP(6))	FXXU1400
	F3(4,N)=F3(4,N)+.5*(-X(9)*SP(4)+X(8)*SP(5)+X(7)*SP(6))	FXXU1410
500	CONTINUE	FXXU1420
	IPC = 0	FXXU1430
	LT = 0	FXXU1440
	NT = 0	FXXU1450
	IF(NSTC) 1,1,6	FXXU1460
1	IF(NPU) 2,99,2	FXXU1470
2	N = NSTX	FXXU1480
	NT = 1	FXXU1490
	II = 1	FXXU1500
3	NNN = MC(II)	FXXU1510
	GO TO 18	FXXU1520
6	N = 10	FXXU1530
	II = 1	FXXU1540
9	NNN = NC(II)	FXXU1550
	GO TO 18	FXXU1560
12	II = II+1	FXXU1570
	IF(NT) 15,13,15	FXXU1580
13	IF(NSTC-II) 1,9,9	FXXU1590
15	IF(NPU -II) 99,3,3	FXXU1600
18	CONTINUE	FXXU1610
	IF(NNN-60) 19,19,25	FXXU1620
19	L=0	FXXU1630
	M = 0	FXXU1640
	SP(1) = 0.	FXXU1650
	SP(2) = 0.	FXXU1660
	SP(3) = 0.	FXXU1670
	ST(1) = 0.	FXXU1680
	ST(2) = 0.	FXXU1690
	ST(3) = 0.	FXXU1700
	IF(NNN-15) 50,50,20	FXXU1710
20	IF(NNN-20) 80,80,21	FXXU1720
21	IF(NNN-25) 85,85,22	FXXU1730
22	IF(NNN-30) 95,95,23	FXXU1740
23	L=1	FXXU1750
	SP(4) = 0.	FXXU1760
	SP(5) = 0.	FXXU1770
	SP(6) = 0.	FXXU1780
	IF(NNN-35) 100,100,150	FXXU1790
25	DO 26 I=1,3	FXXU1800
	F1(I,II+N) = 0.	FXXU1810
	F3(I,II+N) = 0.	FXXU1820
26	CONTINUE	FXXU1830
	F3(4,II+N) = 0.	FXXU1840
	GO TO 12	FXXU1850
30	SP(4)=0.	FXXU1860
	SP(5)=0.	FXXU1870
	SP(6)=0.	FXXU1880
	SP(7) = 0.	FXXU1890
33	CONTINUE	FXXU1900
	DO 32 KA=1,ITER	FXXU1910
	DO 31 I=1,3	FXXU1920
	VO(I)=SP(I)	FXXU1930
	DO 31 J=1,3	FXXU1940
	VO(I) = VO(I) +DTRAN(I,J)*SP(J+3)	FXXU1950

31 CONTINUE	FXXU1960
IF(NO(1)) 600,610,610	FXXU1970
600 SP(7) = VO(11)*VO(1)+VO(12)*VO(3)	FXXU1980
610 DO 32 I=1,3	FXXU1990
SP(I+3)=ST(I)	FXXU2000
IF(I-1) 630,620,630	FXXU2010
620 SP(4)=C(57)*SP(7) + SP(4)	FXXU2020
630 DO 32 J=1,3	FXXU2030
SP(I+3)=SP(I+3)+CX(I,J)*VO(J)	FXXU2040
32 CONTINUE	FXXU2050
36 I=II+N	FXXU2060
IF(LT.NE.0) RETURN	FXXU2070
39 F3(1,I) = .5*(-X(8)*SP(4)-X(9)*SP(5)-X(10)*SP(6))	FXXU2080
F3(2,I) = .5*(X(7)*SP(4)-X(10)*SP(5)+X(9)*SP(6))	FXXU2090
F3(3,I) = .5*(X(10)*SP(4)+X(7)*SP(5)-X(8)*SP(6))	FXXU2100
F3(4,I) = .5*(-X(9)*SP(4)+X(8)*SP(5)+X(7)*SP(6))	FXXU2110
IF(L) 46,45,46	FXXU2120
45 F1(1,I) = SP(1)*A(1,1) + SP(2)*A(2,1) + SP(3)*A(3,1)	FXXU2130
F1(2,I) = SP(1)*A(1,2) + SP(2)*A(2,2) + SP(3)*A(3,2)	FXXU2140
F1(3,I) = SP(1)*A(1,3) + SP(2)*A(2,3) + SP(3)*A(3,3)	FXXU2150
GO TO 12	FXXU2160
46 F1(1,I)=0.	FXXU2170
F1(2,I)=0.	FXXU2180
F1(3,I)=0.	FXXU2190
GO TO 12	FXXU2200
50 VO(1)=0.	FXXU2210
VO(2)=0.	FXXU2220
VO(3)=0.	FXXU2230
IF(NNN-4) 51,52,53	FXXU2240
51 VO(NNN)=1.	FXXU2250
GO TO 60	FXXU2260
52 VO(1)=XIND1**2	FXXU2270
GO TO 60	FXXU2280
53 IF(NNN-6) 54,55,56	FXXU2290
54 VO(2)=XIND2	FXXU2300
GO TO 60	FXXU2310
55 VO(3)=XIND1	FXXU2320
GO TO 60	FXXU2330
56 I=NNN-((NNN-1)/3)*3	FXXU2340
IF(NNN-9) 57,57,58	FXXU2350
57 VO(I)=(XM+1)**-2	FXXU2360
GO TO 60	FXXU2370
58 VO(I)=XM**.618/SQRT(XRE)	FXXU2380
60 CONTINUE	FXXU2390
IF(NPC(11)) 61,62,63	FXXU2400
61 SP(1) =-XQSM*(CALP*VO(1)-SALP*VO(3))	FXXU2410
SP(2)= XQSM* VO(2)	FXXU2420
SP(3) =-XQSM*(SALP*VO(1)+CALP*VO(3))	FXXU2430
GO TO 30	FXXU2440
62 SP(1)=-XQSM*VO(1)	FXXU2450
SP(2)= XQSM*VO(2)	FXXU2460
SP(3)=-XQSM*VO(3)	FXXU2470
GO TO 30	FXXU2480
63 SP(1)=-XQSM*VO(1)	FXXU2490
SP(2) = XQSM*(CXZI*VO(2)-SXZI*VO(3))	FXXU2500
SP(3) =-XQSM*(SXZI*VO(2)+CXZI*VO(3))	FXXU2510
GO TO 30	FXXU2520
80 IF(T.LT.TONE) GO TO 84	FXXU2530
SP(1)=AB(1)/YMAS	FXXU2532
SP(2)=AB(2)/YMAS	FXXU2534

SP(3)=AB(3)/YMAS	FXXU2536
IF(NNN-17) 30,81,82	FXXU2538
81 SP(1)=TAU*SP(1)	FXXU2540
SP(2)=TAU*SP(2)	FXXU2542
SP(3)=TAU*SP(3)	FXXU2544
GO TO 30	FXXU2546
82 SP(1)=SP(1)*TAU**2	FXXU2548
SP(2)=SP(2)*TAU**2	FXXU2550
SP(3)=SP(3)*TAU**2	FXXU2552
GO TO 30	FXXU2554
84 SP(4)=0.	FXXU2556
SP(5)=0.	FXXU2558
SP(6)=0.	FXXU2560
L=1	FXXU2562
GO TO 36	FXXU2564
85 CONTINUE	FXXU2566
KA = N	FXXU2568
CALL AERO(XIND1,XIND2,XM,1.005*XRE,VO(4),VO(5),VO(6))	FXXU2600
CALL AERO(XIND1,XIND2,XM,0.995*XRE,VO(1),VO(2),VO(3))	FXXU2610
L = 0	FXXU2620
N = KA	FXXU2630
SP(1)= (VO(4)-VO(1))/(XRE+E-2)	FXXU2640
SP(2)= (VO(5)-VO(2))/(XRE+E-2)	FXXU2650
SP(3)= (VO(6)-VO(3))/(XRE+E-2)	FXXU2660
IF(NNN-22) 86,87,90	FXXU2670
86 SP(4) = ROEM/ROE	FXXU2680
GO TO 92	FXXU2690
87 SP(4) = EXP(HO*C(23))/ROE	FXXU2700
GO TO 92	FXXU2710
90 SP(4) = HO*ROEC/ROE	FXXU2720
92 CONTINUE	FXXU2730
ST(1)=0.	FXXU2740
ST(2)=0.	FXXU2750
ST(3)=0.	FXXU2760
93 CONTINUE	FXXU2810
DO 94 I=1,3	FXXU2820
94 SP(I) = SP(4)*(AB(I)+XQSM*XRE*SP(I))	FXXU2830
GO TO 30	FXXU2840
95 VO(1)=VA(NNN-25)	FXXU2850
VO(2)=DADX(1,NNN-25)	FXXU2860
VO(3)=DADX(2,NNN-25)	FXXU2870
DO 98 I=1,3	FXXU2880
98 SP(I) =2.*VO(1)*AB(I)/VA(4)+XQSM*(DCDY(I,1)*VO(1)+DCDY(I,2)*VO(2)+DCDY(I,3)*VO(3))	FXXU2890
GO TO 30	FXXU2900
100 I=NNN-30	FXXU2910
IF(N0(I)) 102,103,103	FXXU2920
102 SP(7) = VO(11)*TRAN(1,I)+VO(12)*TRAN(3,I)	FXXU2930
103 DO 112 J=1,3	FXXU2940
IF(J.EQ.1) SP(4) = C(57)*SP(7)	FXXU2950
106 DO 110 K=1,3	FXXU2960
SP(J+3) =SP(J+3)+CX(J,K)*TRAN(K,I)	FXXU2970
110 CONTINUE	FXXU2980
112 SP(J) = TRAN(J,I)	FXXU2990
GO TO 33	FXXU3000
150 CONTINUE	FXXU3010
IF(NNN-48) 160,250,250	FXXU3020
160 IF(NNN-45) 170,200,200	FXXU3030
170 J = (NNN-33)/3	FXXU3040
K = NNN - 3*J - 32	FXXU3050
	FXXU3060

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SP(J+3) = PM(K)
ST(J) = PM(K)
AG(J) = PMDOT(K)
IF(IPC.EQ.0) GO TO 175
172 SP(1) = XPM(1,J)*PMDOT(K)
SP(2) = XPM(2,J)*PMDOT(K)
SP(3) = XPM(3,J)*PMDOT(K)
GO TO 33
175 IPC = 1
XPM(1,1) = 0.
XPM(2,2) = 0.
XPM(3,3) = 0.
XPM(1,2) = XP(3)
XPM(2,1) = -XP(3)
XPM(3,1) = XP(2)
XPM(1,3) = -XP(2)
XPM(2,3) = XP(1)
XPM(3,2) = -XP(1)
GO TO 172
200 SP(NNN-41) = 1.
GO TO 36
250 J = (NNN-45)/3
K = NNN - 3*J - 41
SP(K) = AP(J)
GO TO 36
99 RETURN
ENTRY PAXPC
IPC = 0
LT = 1
GO TO 19
END

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FXXU3070
FXXU3080
FXXU3090
FXXU3100
FXXU3110
FXXU3120
FXXU3130
FXXU3140
FXXU3150
FXXU3160
FXXU3170
FXXU3180
FXXU3190
FXXU3200
FXXU3210
FXXU3220
FXXU3230
FXXU3240
FXXU3250
FXXU3260
FXXU3270
FXXU3280
FXXU3290
FXXU3300
FXXU3310
FXXU3320
FXXU3330
FXXU3340
FXXU3350
FXXU3360
FXXU3370

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SUBROUTINE INDAT
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA
1 CF(3),JCS,CXZI,DADX(2,10),DCOY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,HO,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TTWC,TUW(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XQSM,XRE,XTEMP,
8 XUW(20),XVW(20),XZI,YMAS,YMASM
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VO(20),ZO(20),AG(3),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),DTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,II,IP,IPC,JJ,JN,KA,KD(3),KDUM,KG2
5 K1,NNN,NPTS,PAR(6),PDOT(3),PMDOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHDT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRS,JST
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A NB(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHDT(5),SUM,SUM2,SYG(3,9),TFINAL
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,AP0,AR,ASU,ATM(4),HB(23),ISV,JK
A Pb(23),RL(23),TMB(23)
COMMON /EXTRA / GO
DATA CONV / .3048 /
REWIND FIT
REWIND PQR
REWIND SCRACH
REWIND STATE
WRITE(OUT,1030)
1030 FORMAT(1H1,22H DATA ANALYSIS PROGRAM//11H INPUT DATA//)
8 READ(IN,1000) KDUM,(B(I),I=1,8)
1000 FORMAT(I2,7A10,A8)
WRITE(OUT,1001) KDUM,(B(I),I=1,8)
1001 FORMAT(5X,I2,5X,7A10,5X,A8)
IF(KDUM) 7,8,9
7 CALL EXIT
9 GO TO ( 8,20,30,40,50,60,70,80,90,100,110,120,130,140,150,160,170,
A180,190,200),KLUM

```

20	DECODE(40,1002,B) (NPC(I),I=1,10)	INDT0160
1002	FORMAT(10I4)	INDT0170
	IF(NPC(2).EQ.0) GO TO 8	INDT0180
	XMU = XMU/CONV**3	INDT0190
	REO = REO/CONV	INDT0200
	RPO = RPO/CONV	INDT0210
	GO = GO/CONV	INDT0220
	GO TO 8	INDT0230
30	DECODE(30,1003,B) IPC,IDN,SP(1),SP(2)	INDT0240
1003	FORMAT(I2,I4,E12.4,E12.4)	INDT0250
	GO TO (32,34,36,38,39),IPC	INDT0260
32	NST=NST+1	INDT0270
	ZO(IDN)=SP(1)	INDT0280
	P(IDN,IDN)=SP(2)**2	INDT0290
	GO TO 8	INDT0300
34	NSTC = NSTC + 1	INDT0310
	NC(NSTC) = IDN	INDT0320
	C(IDN)=SP(1)	INDT0330
	P(NSTC+10,NSTC+10) = SP(2)**2	INDT0340
	GO TO 8	INDT0350
36	NPU=NPU+1	INDT0360
	MC(NPU)=IDN	INDT0370
	C(IDN)=SP(1)	INDT0380
	D(NPU)=SP(2)**2	INDT0390
	GO TO 8	INDT0400
38	NPV=NPV+1	INDT0410
	MCC(NPV)=IDN	INDT0420
	C(IDN)=SP(1)	INDT0430
	S(NPV)=SP(2)**2	INDT0440
	GO TO 8	INDT0450
39	C(IDN) = SP(1)	INDT0460
	GO TO 8	INDT0470
40	DECODE(54,1004,B) TO,DET,DCOMP,TFINAL	INDT0480
1004	FORMAT(6X,4E12.4)	INDT0490
	GO TO 8	INDT0500
50	DECODE(42,1005,B) IPC,SP(1),SP(2),SP(3)	INDT0510
1005	FORMAT(I2,4X,3E12.4)	INDT0520
	IF(IPC.EQ.2) GO TO 54	INDT0530
52	GO = SP(1)	INDT0540
	XMU=SP(2)	INDT0550
	XJ2 = SP(3)	INDT0560
	GO TO 8	INDT0570
54	KPO = SP(1)	INDT0580
	REO = SP(2)	INDT0590
	OMEGA=SP(3)	INDT0600
	GO TO 8	INDT0610
60	DECODE(6,1006,B) IPC,NPTS	INDT0620
1006	FORMAT(I2,I4)	INDT0630
	GO TO(62,64,66),IPC	INDT0640
62	READ(IN,1031) (TXCG(I),XXCG(I),I=1,NPTS)	INDT0650
	WRITE(OUT,1031)(TXCG(I),XXCG(I),I=1,NPTS)	INDT0660
1031	FORMAT(6E12.4)	INDT0670
	N8(1)=NPTS	INDT0680
	GO TO 8	INDT0690
64	READ(IN,1031) (TYCG(I),XYCG(I),I=1,NPTS)	INDT0700
	WRITE(OUT,1031)(TYCG(I),XYCG(I),I=1,NPTS)	INDT0710
	N9(1)=NPTS	INDT0720
	GO TO 8	INDT0730
66	READ(IN,1031) (TZCG(I),XZCG(I),I=1,NPTS)	INDT0740
	WRITE(OUT,1031)(TZCG(I),XZCG(I),I=1,NPTS)	INDT0750

	N10(1)=NPTS	INDT0760
	GO TO 8	INDT0770
70	DECODE(68,1007,B) IDN,SP(1),SP(2),SP(3),LT,MT,NT,SP(4),SP(5),SP(6)	INDT0780
1007	FORMAT(I2,3E10.4,3I2,3E10.4)	INDT0790
	NSTA=NSTA+1	INDT0800
	NS(NSTA) = IDN	INDT0810
	DTI(IDN)=SP(1)	INDT0820
	DTF(IDN)=SP(2)	INDT0830
	DFIT(IDN)=SP(3)	INDT0840
	MR(1,IDN)=LT	INDT0850
	MR(2,IDN)=MT	INDT0860
	MR(3,IDN)=NT	INDT0870
	SYG(1,IDN)=SP(4)	INDT0880
	SYG(2,IDN)=SP(5)	INDT0890
	SYG(3,IDN)=SP(6)	INDT0900
	GO TO 8	INDT0910
80	DECODE(6,1006,B) IPC,IDN	INDT0920
	IF(IDN) 81,83,81	INDT0930
81	READ(IN,1032) KDATA	INDT0940
	IF(KDATA.LE.0) GO TO 82	INDT0950
	READ(IN,1032) (K,MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1,3),	INDT0960
	* I=1,KDATA)	INDT0970
	WRITE(FIT) KDATA,(MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1,	INDT0980
	X3),I=1,KDATA)	INDT0990
	GO TO 81	INDT1000
1032	FORMAT(2I2,7E10.2)	INDT1010
82	CONTINUE	INDT1020
	K = 0	INDT1030
	WRITE(FIT)KDATA,K,K,K,K,K,K,K,K	INDT1040
	REWIND FIT	INDT1050
83	IF(IPC) 84,8,84	INDT1060
84	READ(FIT) KDATA,(MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1,	INDT1070
	X3),I=1,KDATA)	INDT1080
	WRITE(OUT,1033)KDATA,(MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1	INDT1090
	X,3),I=1,KDATA)	INDT1100
1033	FORMAT(2I4,7E16.7/(4X,I4,7E16.7))	INDT1110
	IF(KDATA) 84,85,84	INDT1120
85	REWIND FIT	INDT1130
	GO TO 8	INDT1140
90	DECODE(6,1006,B) IPC,IDN	INDT1150
	IF(IDN) 91,93,91	INDT1160
91	READ(IN,1034) KDAP	INDT1170
	IF(KDAP.LE.0) GO TO 92	INDT1180
	READ(IN,1034) (K,TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=1,	INDT1190
	* KDAP)	INDT1200
	WRITE(PQR)KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=1,	INDT1210
	* KDAP)	INDT1220
	GO TO 91	INDT1230
1034	FORMAT(I2,7E10.2)	INDT1240
92	CONTINUE	INDT1250
	K = 0	INDT1260
	WRITE(PQR) KDAP,K,K,K,K,K,K,K,K	INDT1270
	REWIND PQR	INDT1280
93	IF(IPC) 94,8,94	INDT1290
94	READ(PQR) KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=1,KDAP	INDT1300
	X)	INDT1310
	WRITE(OUT,1035) KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=	INDT1320
	X1,KDAP)	INDT1330
1035	FORMAT(I4,7E16.7/(4X,7E16.7))	INDT1340
	IF(KDAP) 94,95,94	INDT1350

95 REWIND PQR	INDT1360
GO TO 8	INDT1370
100 DECODE(6,1006,B) IPC,NPTS	INDT1380
NSTX = NST+NSTC	INDT1390
GO TO (101,102,103,104,106,108),IPC	INDT1400
101 READ(IN,1031) ((P(I,J),J=1,NSTX),I=1,NSTX)	INDT1410
WRITE(OUT,1031) ((P(I,J),J=1,NSTX),I=1,NSTX)	INDT1420
GO TO 8	INDT1430
102 READ(IN,1031) ((CUZ(I,J),J=1,NPU),I=1,NSTX)	INDT1440
WRITE(OUT,1031) ((CUZ(I,J),J=1,NPU),I=1,NSTX)	INDT1450
GO TO 8	INDT1460
103 READ(IN,1031) ((CVZ(I,J),J=1,NPV),I=1,NSTX)	INDT1470
WRITE(OUT,1031) ((CVZ(I,J),J=1,NPV),I=1,NSTX)	INDT1480
GO TO 8	INDT1490
104 DO 105 I=1,NPTS	INDT1500
READ(IN,1036) LT,MT,P(LT,MT)	INDT1510
P(MT,LT)=P(LT,MT)	INDT1520
1036 FORMAT(4X,2I4,E12.4)	INDT1530
105 WRITE(OUT,1037) LT,MT,P(LT,MT)	INDT1540
1037 FORMAT(10X,2HP(,I3,1H,I3,3H) =E15.6)	INDT1550
GO TO 8	INDT1560
106 DO 107 I=1,NPTS	INDT1570
READ(IN,1036) LT,MT,CUZ(LT,MT)	INDT1580
107 WRITE(OUT,1038) LT,MT,CUZ(LT,MT)	INDT1590
1038 FORMAT(8X,4HCUZ(,I3,1H,I3,3H) =E15.8)	INDT1600
GO TO 8	INDT1610
108 DO 109 I=1,NPTS	INDT1620
READ(IN,1036) LT,MT,CVZ(LT,MT)	INDT1630
109 WRITE(OUT,1039) LT,MT,CVZ(LT,MT)	INDT1640
1039 FORMAT(8X,4HCVZ(,I3,1H,I3,3H) =E15.8)	INDT1650
GO TO 8	INDT1660
1008 FORMAT(I2,I4,2E12.4)	INDT1670
110 DECODE(32,1006,B) NPC(11),IP,SREF,XLREF	INDT1680
CALL AEROIN	INDT1690
GO TO 8	INDT1700
120 DECODE(32,1006,B)IP,N4(1),TONE,TTWO	INDT1710
IP = N4(1)	INDT1720
READ(IN,1031) (TMAS(I),XMAS(I),I=1,IP)	INDT1730
WRITE(OUT,1041) (TMAS(I),XMAS(I),I=1,IP)	INDT1740
1041 FORMAT(5(F10.2,E14.5))	INDT1750
GO TO 8	INDT1760
130 DECODE(6,1006,B) IPC,NPTS	INDT1770
IF(IPC) 134,132,134	INDT1780
132 N5(1) = NPTS	INDT1790
READ(IN,1031) (TUW(I),XUW(I),I=1,NPTS)	INDT1800
WRITE(OUT,1041)(TUW(I),XUW(I),I=1,NPTS)	INDT1810
GO TO 8	INDT1820
134 N6(1) = NPTS	INDT1830
READ(IN,1031) (TVW(I),XVW(I),I=1,NPTS)	INDT1840
WRITE(OUT,1041)(TVW(I),XVW(I),I=1,NPTS)	INDT1850
GO TO 8	INDT1860
140 DECODE(2,1006,B) NPC(14)	INDT1870
IF(NPC(14)-1) 8,8,142	INDT1880
142 READ(IN,1048) K1,APO,AMO,AR,AGAM,ABET,ASU	INDT1890
1048 FORMAT(I4,6E11.4)	INDT1900
READ(IN,1031) (HB(I),I=1,K1)	INDT1910
READ(IN,1031) (TMB(I),I=1,K1)	INDT1920
GO TO 8	INDT1930
150 GO TO 8	INDT1940
160 GO TO 8	INDT1950

170 GO TO 8
180 GO TO 8
190 GO TO 8
200 RETURN
END

INDT1960
INDT1970
INDT1980
INDT1990
INDT2000

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SUBROUTINE INTAG
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS ,BETA,CA(6),CALP ,CBET ,CETA ,
1 CF(3),JCS ,CXZI ,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH ,
2 DRDP,DWDH(2),ETA,HO,N4(3) ,N5(3) ,N6(3) ,PAXP(3,30),
3 PE ,ROE ,ROEC ,ROEM ,SALP ,SBET ,
4 SFTA ,SREF ,SXZI ,TAU ,TMAS(20) ,TONE ,
5 TFWO ,TUV(20) ,TVW(20) ,UW ,VA(5) ,VB(5) ,
6 VW ,XIND1 ,XIND2 ,XLREF ,XM ,
7 XMAS(20) ,XNU ,XQ ,XQSM ,XRE ,XTEMP ,
8 XUV(20) ,XVW(20) ,XZI ,YMAS ,YMASM
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3) ,DUD(10,1) ,DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,ION ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3) ,KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3) ,XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5) ,D(5) ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,NB(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPC ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON /ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A ,PB(23),RL(23),TMB(23)
COMMON /EXTRA / GO
2 LRK = 4
6 CALL RKUTTA
IF(LRK=2) 8,10,99
8 CALL DATAB
CALL MOTION
IF(NPC(1)-1) 12,6,12
10 IF(DCOMP.GE.0..OR.NPC(10).EQ.0.OR.T.EQ.TSAV) GO TO 6
WRITE(STATE) T,X
TSAV=T
GO TO 6
12 CALL FXXU
DO 22 I=1,4
N = NSTX+NPU
DO 22 J=1,N
IF(J=10) 13,13,14

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13 CONTINUE	INTG0160
SUM = 0.	INTG0170
SUM2= 0.	INTG0180
GO TO 15	INTG0190
14 SUM = F1(I,J)	INTG0200
SUM2= F3(I,J)	INTG0210
15 DO 16 K=1,10	INTG0220
16 SUM2 = SUM2 + F3(I,K)*PH(K,J)	INTG0230
DPH(I+6,J) = SUM2	INTG0240
IF(I.EQ.4) GO TO 22	INTG0250
DO 18 K=1,10	INTG0260
18 SUM = SUM + F1(I,K)*PH(K,J)	INTG0270
DPH(I,J) = SUM	INTG0280
SUM = 0.	INTG0290
DO 20 K=1,5	INTG0300
20 SUM = SUM + F2(I,K)*PH(K,J)	INTG0310
DPH(I+3,J) = SUM	INTG0320
22 CONTINUE	INTG0330
GO TO 6	INTG0340
99 RETURN	INTG0350
END	INTG0360

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SUBROUTINE MINVAR
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS ,BETA,CA(6),CALP ,CBET ,CETA ,
1 CF(3),JCS ,CXZI ,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH ,
2 DRDP,DWDH(2),ETA,HO,N4(3) ,N5(3) ,N6(3) ,PAXP(3,30),
3 PE ,ROE ,ROEC ,ROEM ,SALP ,SBET ,
4 SETA ,SREF ,SXZI ,TAU ,TMAS(20) ,TONE ,
5 TTWO ,TUV(20) ,TVW(20) ,UW ,VA(5) ,VB(5) ,
6 VW ,XIND1 ,XIND2 ,XLREF ,XM ,
7 XMAS(20) ,XNU ,XQ ,XQSM ,XRE ,XTEMP ,
8 XUW(20) ,XVW(20) ,XZI ,YMAS ,YMASM
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR,JNBRS,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TG(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,APQ,AR,ASU,ATM(4),HB(23),ISV,JK
A ,PB(23),RL(23),TMB(23)
COMMON /EXTRA / GO
G(1,10) = 0.
G(2,10) = 0.
G(3,10) = 0.
NT = 0
LT = 1
MT = NSTX
DO 1 I=1,NSTX
P(I,10) = 0.
1 P(10,I) = 0.
2 DO 12 J=KAR,KCB
DO 6 I=LT,MT
L = I+1
SUM = 0.
DO 3 K=LT,I
3 SUM = SUM + P(K,I)*G(J,K)

```

IF(L.GT.MT) GO TO 6	MINV0160
DO 4 K=L,MT	MINV0170
4 SUM = SUM+P(I,K)*G(J,K)	MINV0180
6 DUB(I,J) = SUM	MINV0190
C-----CALCULATE EQ.(54F) -----	MINV0200
DO 10 I=KAR,KOB	MINV0210
SUM = 0.	MINV0220
DO 8 K=LT,MT	MINV0230
8 SUM = SUM+G(I,K)*DUB(K,J)	MINV0240
10 DUB(I,J+6) = SUM	MINV0250
12 DUB(J,J+6) = DUB(J,J+6)+SI(J)**2	MINV0260
IF(NPV) 36,36,14	MINV0270
14 CONTINUE	MINV0280
DO 15 I=1,NPV	MINV0290
15 CVZ(10,I) = 0.	MINV0300
DO 20 J=KAR,KOB	MINV0310
DO 17 I=1,NSTX	MINV0320
SUM= 0.	MINV0330
DO 16 K=1,NPV	MINV0340
16 SUM= SUM+CVZ(I,K)*H(J,K)	MINV0350
DUB(I,J+3) = SUM	MINV0360
17 DUB(I,J) = DUB(I,J)+SUM	MINV0370
DO 18 I=1,NPV	MINV0380
18 DUB(I+12,J+6) = S(I)*H(J,I)	MINV0390
20 CONTINUE	MINV0400
DO 26 J=KAR,KOB	MINV0410
DO 24 I=KAR,KOB	MINV0420
SUM = 0.	MINV0430
SUM2= 0.	MINV0440
DO 22 K=LT,MT	MINV0450
22 SUM = SUM + DUB(K,J+3)*G(I,K)	MINV0460
DO 23 K=1,NPV	MINV0470
23 SUM2= SUM2+ H(I,K)*DUB(K+12,J+6)	MINV0480
DUB(J+3,I+6) = SUM	MINV0490
24 DUB(I+6,J+6) = SUM + SUM2	MINV0500
26 CONTINUE	MINV0510
DO 34 J=KAR,KOB	MINV0520
DO 28 I=KAR,KOB	MINV0530
28 DUB(I,J+6) = DUB(I,J+6) + DUB(I+3,J+6) + DUB(I+6,J+6)	MINV0540
DO 32 I=1,NPV	MINV0550
SUM = 0.	MINV0560
DO 30 K=LT,MT	MINV0570
30 SUM = SUM + G(J,K)*CVZ(K,I)	MINV0580
32 DUB(I,J+9) = SUM	MINV0590
34 CONTINUE	MINV0600
36 CONTINUE	MINV0610
IF(KAR=KOB) 37,46,37	MINV0620
37 CONTINUE	MINV0630
DO 39 J=KAR,KOB	MINV0640
DO 38 I=KAR,KOB	MINV0650
38 DUB(I+9,J+6) = 0.	MINV0660
39 DUB(J+9,J+6) = 1.	MINV0670
L = KOB-1	MINV0680
DO 42 I=KAR,L	MINV0690
M = I+1	MINV0700
SUM = DUB(I,I+6)	MINV0710
DO 42 J=KAR,KOB	MINV0720
DUB(I ,J+6) = DUB(I ,J+6)/SUM	MINV0730
DUB(I+9,J+6) = DUB(I+9,J+6)/SUM	MINV0740
DO 42 K=M,KOB	MINV0750

IF(I-J) 40,41,40	MINV0760
40 DUB(K ,J+6) = DUB(K ,J+6)-DUB(K,I+6)*DUB(I ,J+6)	MINV0770
41 DUB(K+9,J+6) = DUB(K+9,J+6)-DUB(K,I+6)*DUB(I+9,J+6)	MINV0780
42 CONTINUE	MINV0790
DO 44 I=KAR,KOB	MINV0800
44 DUB(KOB+9,I+6) = DUB(KOB+9,I+6)/DUB(KOB,KOB+6)	MINV0810
DO 45 I=KAR,L	MINV0820
M = KOB+KAR+6-I	MINV0830
DO 45 J=1,L	MINV0840
N = KOB+KAR+8-J	MINV0850
DO 45 K=KAR,KOB	MINV0860
45 DUB(N,K+6) = DUB(N,K+6)-DUB(N-9 ,M)*DUB(M+3,K+6)	MINV0870
GO TO 48	MINV0880
46 DUB(KAR+9,KAR+6) = 1./DUB(KAR,KAR+6)	MINV0890
48 CONTINUE	MINV0900
C-----CALCULATE EQ.(54E) -----	MINV0910
DO 54 I=1,NSTX	MINV0920
DO 51 J=KAR,KOB	MINV0930
SUM = 0.	MINV0940
DO 50 K=KAR,KOB	MINV0950
50 SUM = SUM + DUB(I,K)*DUB(K+9,J+6)	MINV0960
51 DUB(I,J+12) = SUM	MINV0970
DO 54 L=I,NSTX	MINV0980
SUM = 0.	MINV0990
C-----CALCULATE EQ.(54B) -----	MINV1000
DO 52 K=KAR,KOB	MINV1010
52 SUM = SUM + DUB(I,K+12)*DUB(L,K)	MINV1020
P(I,L) = P(I,L) - SUM	MINV1030
54 CONTINUE	MINV1040
IF(NPU) 66,66,56	MINV1050
C-----CALCULATE EQ.(54C) -----	MINV1060
56 CONTINUE	MINV1070
DO 57 I=1,NPU	MINV1080
57 CUZ(10,I) = 0.	MINV1090
DO 64 J=1,NPU	MINV1100
DO 60 I=KAR,KOB	MINV1110
SUM = 0.	MINV1120
DO 58 K=1,NSTX	MINV1130
58 SUM = SUM + G(I,K)*CUZ(K,J)	MINV1140
60 DUB(I,1) = SUM	MINV1150
DO 64 I=1,NSTX	MINV1160
SUM = 0.	MINV1170
DO 62 K=KAR,KOB	MINV1180
62 SUM = SUM + DUB(I,K+12)*DUB(K,1)	MINV1190
64 CUZ(I,J) = CUZ(I,J)-SUM	MINV1200
66 IF(NPV) 72,72,67	MINV1210
C-----CALCULATE EQ.(54D) -----	MINV1220
67 DO 70 I=1,NSTX	MINV1230
DO 70 J=1,NPV	MINV1240
SUM = 0.	MINV1250
DO 68 K=KAR,KOB	MINV1260
68 SUM = SUM + DUB(I,K+12)*DUB(J,K+9)	MINV1270
70 CVZ(I,J) = CVZ(I,J) - SUM	MINV1280
72 IF(NPC(1)-2) 74,108,74	MINV1290
74 IF(NPC(4)) 75,88,75	MINV1300
75 DO 82 I=1,NSTX	MINV1310
80 DUB(I,1) = OZ(I)	MINV1320
82 CONTINUE	MINV1330
C-----CALCULATE EQ.(54A) -----	MINV1340
DO 86 I=KAR,KOB	MINV1350

	SUM = 0.	MINV1360
	DO 84 J=1,NSTX	MINV1370
84	SUM = SUM + G(I,J)*DUB(J,1)	MINV1380
86	DATC(I) = DATC(I)+SUM	MINV1390
88	DO 90 I=KAR,KOB	MINV1400
	J = LC(I)	MINV1410
	DUB(I,2) = DATA(J)-DATC(I)	MINV1420
	IF(MTYP.GT.5) GO TO 90	MINV1430
	IF(J.EQ.1) GO TO 90	MINV1440
	IF(ABS(DUB(I,2)).LT.3.1416) GO TO 90	MINV1450
	DUB(I,2) = DUB(I,2)-SIGN(6.283185307179586,DUB(I,2))	MINV1460
90	CONTINUE	MINV1470
	DO 92 I=1,NSTX	MINV1480
	DZ(I) = 0.	MINV1490
	DO 92 J=KAR,KOB	MINV1500
92	DZ(I) = DZ(I)+DUB(I,J+12)*DUB(J,2)	MINV1510
	IF(NPC(4)) 294,298,294	MINV1520
294	DO 296 I=1,4	MINV1530
296	VO(I) = X(I+6) + DUB(I+6,1)	MINV1540
	DZ(I) = -(VO(1)*DZ(7)+VO(2)*DZ(8)+VO(3)*DZ(9))/VO(4)	MINV1550
94	DO 96 I=1,NSTX	MINV1560
96	DZ(I) = DZ(I)+DUB(I,1)	MINV1570
	GO TO 108	MINV1580
298	DZ(10) = -(X(7)*DZ(7)+X(8)*DZ(8)+X(9)*DZ(9))/X(10)	MINV1590
98	DO 100 I=1,10	MINV1600
100	X(I) = X(I)+DZ(I)	MINV1610
	DATC(1) = SORT(X(7)**2 + X(8)**2 + X(9)**2 + X(10)**2)	MINV1620
	X(7) = X(7)/DATC(1)	MINV1630
	X(8) = X(8)/DATC(1)	MINV1640
	X(9) = X(9)/DATC(1)	MINV1650
	X(10) = X(10)/DATC(1)	MINV1660
	IF(NSTC.EQ.0) GO TO 103	MINV1670
	DO 102 I=1,NSTC	MINV1680
	J = NC(I)	MINV1690
102	C(J) = C(J)+DZ(I+10)	MINV1700
103	CONTINUE	MINV1710
	IF(KSS) 108,108,104	MINV1720
104	DO 106 I=1,KSS	MINV1730
	MTYP = NSS(I)	MINV1740
106	CALL STAT	MINV1750
108	P(8,7) = P(7,8)	MINV1760
	P(9,7) = P(7,9)	MINV1770
	P(9,8) = P(8,9)	MINV1780
	DO 110 I=1,9	MINV1790
	SUM = P(I,7)*X(7) + P(I,8)*X(8) + P(I,9)*X(9)	MINV1800
110	P(I,10) = -SUM/X(10)	MINV1810
	P(10,10) = -(X(7)*P(7,10)+X(8)*P(8,10)+X(9)*P(9,10))/X(10)	MINV1820
	DO 114 I=11,NSTX	MINV1830
	SUM = P(7,I)*X(7) + P(8,I)*X(8) + P(9,I)*X(9)	MINV1840
114	P(10,I) = -SUM/X(10)	MINV1850
	IF(NPU.EQ.0) GO TO 117	MINV1860
115	DO 116 I=1,NPU	MINV1870
	SUM = CUZ(7,I)*X(7) + CUZ(8,I)*X(8) + CUZ(9,I)*X(9)	MINV1880
116	CUZ(10,I) = -SUM/X(10)	MINV1890
117	IF(NPV.EQ.0) GO TO 99	MINV1900
	DO 118 I=1,NPV	MINV1910
	SUM = CVZ(7,I)*X(7) + CVZ(8,I)*X(8) + CVZ(9,I)*X(9)	MINV1920
118	CVZ(10,I) = -SUM/X(10)	MINV1930
99	CONTINUE	MINV1940
	RETURN	MINV1950
	END	MINV1960

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SUBROUTINE MOTION
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS ,BETA,CA(6),CALP ,CBET ,CETA ,
1 CF(3),JCS ,CXZI ,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH ,
2 DRDP,DWDH(2),ETA,HO,N4(3) ,N5(3) ,N6(3) ,PAXP(3,30),
3 PE ,ROE ,ROEC ,ROEM ,SALP ,SBET ,
4 SETA ,SREF ,SXZI ,TAU ,TMAS(20) ,TONE ,
5 TTWO ,TUW(20) ,TVW(20) ,UW ,VA(5) ,VB(5) ,
6 VW ,XIND1 ,XIND2 ,XLREF ,XM ,
7 XMAS(20) ,XNU ,XQ ,XQSM ,XRE ,XTEMP ,
8 XUW(20) ,XVW(20) ,XZI ,YMAS ,YMASM
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
COMMON /TIMEZ/ X(3) ,Y(3) ,ZF(6) ,ZX(40) ,ZY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRO ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG ,KI ,KK
6 ,KN ,KOB ,KPROP ,KS ,KSM ,KSS ,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPV ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N3(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON /ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A ,PB(23),RL(23),TMB(23)
COMMON /EXTRA / GO
DATA ITER /5/
LT = 0
1 CONTINUE
CPH = COS(X(5))
SPH = SIN(X(5))
TPH = SPH/CPH
R = REO + X(4)
-----CALCULATE EQ.(149)-----
YMASM=TAB(T,N4(1),TMAS(1),XMAS(1))
IF(T.GT.TONE) GO TO 3
YMAS =YMASM
GO TO 6
3 IF(T.LT.TTWO) GO TO 4
TAU=TTWO-TONE
GO TO 5

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4 TAU=T -TONE
5 CONTINUE
YMAS=YMASM-(C(16)+C(17)*TAU+C(18)*TAU**2)
C-----CALCULATE EQ.(145)-----
6 RO=REO/SQRT(1.+(RERP2-1.)*SPH**2)
C-----CALCULATE EQ.(144)-----
HO = R-RO
CALL ATMDAT(HO,PE,ROEM,AS,XTEMP,XNU,SP(1))
C-----CALCULATE EQ.(151)-----
ROEC=C(22)*EXP(C(23)*HO)
ROE =C(21)*ROEM+ROEC
C-----CALCULATE EQ.(152)-----
UW = TAB(HO,N5(1),TUW(1),XUW(1)) + C(26)
VW = TAB(HO,N6(1),TVW(1),XVW(1)) + C(27)
C-----CALCULATE EQ.(140)-----
VA(1)=X(1)+UW
VA(2)=X(2)-R*OMEGA*CPH+VW
VA(3)=X(3)
C-----CALCULATE EQ.(141)-----
VA(5)=VA(1)**2+VA(2)**2+VA(3)**2
VA(4)=SQRT(VA(5))
C-----CALCULATE EQ.(142)-----
XQ=.5*ROE*VA(5)
C-----CALCULATE EQ.(148)-----
XRE=ROE*VA(4)*XLREF/XNU
C-----CALCULATE EQ.(143)-----
XM=VA(4)/AS
XQSM=XQ*SREF/YMAS
C-----CALCULATE EQ.(133)-----
SP(1) = (X( 7)-X( 8))*(X( 7)+X( 8))
SP(2) = (X( 9)-X(10))*(X( 9)+X(10))
A(1,1) = (X( 7)-X( 9))*(X( 7)+X( 9)) + (X( 8)-X(10))*(X( 8)+X(10))
A(2,2) = SP(1) + SP(2)
A(3,3) = SP(1) - SP(2)
A(1,2) = 2.*(X( 8)*X( 9)+X( 7)*X(10))
A(2,1) = 2.*(X( 8)*X( 9)-X( 7)*X(10))
A(1,3) = 2.*(X( 8)*X(10)-X( 7)*X( 9))
A(3,1) = 2.*(X( 8)*X(10)+X( 7)*X( 9))
A(3,2) = 2.*(X(10)*X( 9)-X( 7)*X( 8))
A(2,3) = 2.*(X(10)*X( 9)+X( 7)*X( 8))
C-----CALCULATE EQ.(139)-----
VB(1)=0.
VB(2)=0.
VB(3)=0.
DO 7 I=1,3
DO 7 J=1,3
7 VB(I)=VB(I)+A(I,J)*VA(J)
VB(4)=SQRT(VB(1)**2+VB(3)**2)
C-----CALCULATE EQ.(135)-----
SALP=VB(3)/VB(4)
CALP=VB(1)/VB(4)
C-----CALCULATE EQ.(136)-----
SBET=VB(2)/VA(4)
CBET=VB(4)/VA(4)
ALPH =ATAN2(SALP,CALP)
BETA =ATAN2(SBET,CBET)
IF(NPC(11).EQ.1) GO TO 8
XIND1=ALPH
XIND2=BETA
GO TO 9
MOTN0160
MOTN0170
MOTN0180
MOTN0190
MOTN0200
MOTN0210
MOTN0220
MOTN0230
MOTN0240
MOTN0250
MOTN0260
MOTN0270
MOTN0280
MOTN0290
MOTN0300
MOTN0310
MOTN0320
MOTN0330
MOTN0340
MOTN0350
MOTN0360
MOTN0370
MOTN0380
MOTN0390
MOTN0400
MOTN0410
MOTN0420
MOTN0430
MOTN0440
MOTN0450
MOTN0460
MOTN0470
MOTN0480
MOTN0490
MOTN0500
MOTN0510
MOTN0520
MOTN0530
MOTN0540
MOTN0550
MOTN0560
MOTN0570
MOTN0580
MOTN0590
MOTN0600
MOTN0610
MOTN0620
MOTN0630
MOTN0640
MOTN0650
MOTN0660
MOTN0670
MOTN0680
MOTN0690
MOTN0700
MOTN0710
MOTN0720
MOTN0730
MOTN0740
MOTN0750

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      8 VB(5)=SQRT(VB(2)**2+VB(3)**2)
C-----CALCULATE EQ.(137) -----
      SETA=VB(5)/VA(4)
      CETA=VB(1)/VA(4)
C-----CALCULATE EQ.(138) -----
      SXZI=VB(2)/VB(5)
      CXZI=VB(3)/VB(5)
      ETA =ATAN2(SETA,CETA)
      XZI =ATAN2(SXZI,CXZI)
      XIND1=ETA
      XIND2=XZI
      9 CALL AERO(XIND1,XIND2,XM,XRE,CF(1),CF(2),CF(3))
      AB(1)=CF(1)*XQSM
      AB(2)=CF(2)*XQSM
      AB(3)=CF(3)*XQSM
      XP(1) = CGM(1) + C(31)
      XP(2) = CGM(2) + C(32)
      XP(3) = CGM(3) + C(33)
C-----CALCULATE EQ.(153) -----
      I=N11(2)
      IF(N11(2)-1)12,10,12
      10 I = 2
      12 CONTINUE
      SP(1)= TT(I+1)-TT(I-1)
      HI(2)= .5*SP(1)
      HI(1)= T + HI(2)
      HI(2)= T - HI(2)
      PMDOT(1)= (TAB(HI(1),N11(1),TT(1),TP(1))-TAB(HI(2),N11(1),TT(1),TP
      X(1)))/SP(1)
      PMDOT(2)= (TAB(HI(1),N11(1),TT(1),TQ(1))-TAB(HI(2),N11(1),TT(1),TQ
      X(1)))/SP(1)
      PMDOT(3)= (TAB(HI(1),N11(1),TT(1),TR(1))-TAB(HI(2),N11(1),TT(1),TR
      X(1)))/SP(1)
C-----CALCULATE EQ.(156) -----
      13 DO 14 I=1,3
      J = 3*I
      PDOT(I) = C(J+33)*PMDOT(1) + C(J+34)*PMDOT(2) + C(J+35)*PMDOT(3)
      14 CONTINUE
C
      SOLVE EQ.(III.114)
      AP(1)=AB(1)
      AP(2)=AB(2)
      AP(3)=AB(3)
      AP(4) = 2.*AP(1)*AP(3)/SQRT(AP(1)**2+AP(3)**2)
C-----CALCULATE EQ.(158) -----
      DO 16 N = 1,ITER
      DO 11 I=1,3
      J = 3*I
      PA(I)=C(J+33)*PM(1)+C(J+34)*PM(2)+C(J+35)*PM(3)+C(I+44)+C(I+47)*
      X AP(1) + C(I+50)*AP(2) + C(I+53)*AP(3)
      11 CONTINUE
      PA(1) = C(57)*AP(4)+PA(1)
      SP(1) = PA(1)**2
      SP(2) = PA(2)**2
      SP(3) = PA(3)**2
      TRAN(1,1)=-SP(2)-SP(3)
      TRAN(1,2)= PA(1)*PA(2)-PDOT(3)
      TRAN(1,3)= PA(1)*PA(3)+PDOT(2)
      TRAN(2,1)= PA(1)*PA(2)+PDOT(3)
      TRAN(2,2)=-SP(1)-SP(3)
      TRAN(2,3)= PA(2)*PA(3)-PDOT(1)

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MOTN0760
MOTN0770
MOTN0780
MOTN0790
MOTN0800
MOTN0810
MOTN0820
MOTN0830
MOTN0840
MOTN0850
MOTN0860
MOTN0870
MOTN0880
MOTN0890
MOTN0900
MOTN0910
MOTN0920
MOTN0930
MOTN0940
MOTN0950
MOTN0960
MOTN0970
MOTN0980
MOTN0990
MOTN1000
MOTN1010
MOTN1020
MOTN1030
MOTN1040
MOTN1050
MOTN1060
MOTN1070
MOTN1080
MOTN1090
MOTN1100
MOTN1110
MOTN1120
MOTN1130
MOTN1140
MOTN1150
MOTN1160
MOTN1170
MOTN1180
MOTN1190
MOTN1200
MOTN1210
MOTN1220
MOTN1230
MOTN1240
MOTN1250
MOTN1260
MOTN1270
MOTN1280
MOTN1290
MOTN1300
MOTN1310
MOTN1320
MOTN1330
MOTN1340
MOTN1350

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TRAN(3,1)= PA(1)*PA(3)-PDOT(2)	MOTN1360
TRAN(3,2)= PA(2)*PA(3)+PDOT(1)	MOTN1370
TRAN(3,3)=-SP(1)-SP(2)	MOTN1380
AP(1)=AB(1)+TRAN(1,1)*XP(1)+TRAN(1,2)*XP(2)+TRAN(1,3)*XP(3)	MOTN1390
AP(2)=AB(2)+TRAN(2,1)*XP(1)+TRAN(2,2)*XP(2)+TRAN(2,3)*XP(3)	MOTN1400
AP(3)=AB(3)+TRAN(3,1)*XP(1)+TRAN(3,2)*XP(2)+TRAN(3,3)*XP(3)	MOTN1410
AP(4) = 2.*AP(1)*AP(3)/SQRT(AP(1)**2+AP(3)**2)	MOTN1420
16 CONTINUE	MOTN1430
IF(LT) 15,15,99	MOTN1440
15 CONTINUE	MOTN1450
C-----CALCULATE EQ.(132) -----	MOTN1460
AG(1) = AB(1)*A(1,1)+AB(2)*A(2,1)+AB(3)*A(3,1)	MOTN1470
AG(2) = AB(1)*A(1,2)+AB(2)*A(2,2)+AB(3)*A(3,2)	MOTN1480
AG(3) = AB(1)*A(1,3)+AB(2)*A(2,3)+AB(3)*A(3,3)	MOTN1490
C PARAMETERS USED FREQUENTLY IN REMAINING SUBROUTINES	MOTN1500
PAR(1) = X(1)*X(1) + X(2)*X(2)	MOTN1510
PAR(2)=XMU/R**2	MOTN1520
PAR(3)=XMUJ/R**4	MOTN1530
PAR(4) = 1./(2.*R)	MOTN1540
PAR(5) = X(1)*X(3)-X(2)*X(2)*TPH	MOTN1550
PAR(6) = 1. - 1.5*CPH*CPH	MOTN1560
F1(2,2)= (X(1)*TPH+X(3))/R	MOTN1570
F1(2,3)= X(2)/R	MOTN1580
F1(2,1)= F1(2,3)*TPH	MOTN1590
DX(5) = X(1)/R	MOTN1600
F3(1,8) = -.5*(PA(1)-F1(2,3))	MOTN1610
F3(1,9) = -.5*(PA(2)+DX(5))	MOTN1620
F3(1,10)=-.5*(PA(3)+F1(2,1))	MOTN1630
F3(2,9) = F3(1,10) + PA(3)	MOTN1640
F3(2,10)= F3(1,9) + DX(5)	MOTN1650
F3(3,10)= F3(1,8) + PA(1)	MOTN1660
C-----CALCULATE EQ.(127) -----	MOTN1670
DX(1) = AG(1) + PAR(5)/R - PAR(3)*SPH*CPH	MOTN1680
DX(2) = AG(2) + X(2)*F1(2,2)	MOTN1690
DX(3) = AG(3) + PAR(2) - PAR(1)/R - PAR(3)*PAR(6)	MOTN1700
C-----CALCULATE EQ.(128) -----	MOTN1710
DX(4) = -X(3)	MOTN1720
DX(6) = F1(2,3)/CPH - OMEGA	MOTN1730
C-----CALCULATE EQ.(129) -----	MOTN1740
DX(7) = X(8)*F3(1, 8) + X(9)*F3(1, 9) + X(10)*F3(1,10)	MOTN1750
DX(8) =-X(7)*F3(1, 8) + X(9)*F3(2, 9) + X(10)*F3(2,10)	MOTN1760
DX(9) =-X(7)*F3(1, 9) - X(8)*F3(2, 9) + X(10)*F3(3,10)	MOTN1770
DX(10) =-X(7)*F3(1,10) - X(8)*F3(2,10) - X(9)*F3(3,10)	MOTN1780
99 RETURN	MOTN1790
ENTRY AUXIL	MOTN1800
LT = 1	MOTN1810
GO TO 1	MOTN1820
END	MOTN1830

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SUBROUTINE OBSERV
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),      COMM0010
*   NALL,LRK                                                         COMM0020
COMMON /MOD1/ ALPH,AS ,BETA,CA(6),CALP ,CBET ,CETA ,                COMM0030
1  CF(3),JCS ,CXZI ,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH ,        COMM0040
2  DRDP,DWDH(2),ETA,HO,N4(3) ,N5(3) ,N6(3) ,PAXP(3,30),            COMM0050
3  PE ,ROE ,ROEC ,ROEM ,SALP ,SBET ,                                COMM0060
4  SETA ,SREF ,SXZI ,TAU ,TMAS(20) ,TONE ,                          COMM0070
5  TTWO ,TUW(20) ,TVW(20) ,UW ,VA(5) ,VB(5) ,                       COMM0080
6  VW ,XIND1 ,XIND2 ,XLREF ,XM ,                                  COMM0090
7  XMAS(20) ,XNU ,XQ ,XGSM ,XRE ,XTEMP ,                           COMM0100
8  XUW(20) ,XVW(20) ,XZI ,YMAS ,YMASM ,                            COMM0110
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)                   COMM0120
1  ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)                 COMM0130
2  ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)             COMM0140
3  ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)           COMM0150
4  ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2                  COMM0160
5  ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)             COMM0170
6  ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)                              COMM0180
DIMENSION DUB(30,15)                                               COMM0190
EQUIVALENCE (AG(1),DUB(1,1))                                       COMM0200
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)                 COMM0210
1  ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)          COMM0220
2  ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)          COMM0230
3  ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET                      COMM0240
4  ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST         COMM0250
5  ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK                  COMM0260
6  ,KN ,KOB ,KPROP ,KS ,KSM ,KSS ,L ,LC(3) ,LCS(3) ,LS ,LT        COMM0270
7  ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT                      COMM0280
8  ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)             COMM0290
9  ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)    COMM0300
A  ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)                 COMM0310
B  ,PA(3) ,PM(3) ,R ,REO ,RERP2 ,                                COMM0320
C  ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)                COMM0330
L  ,SIGM(3) ,SIGMS(3) ,SPHOT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL     COMM0340
E  ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)                    COMM0350
F  ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)       COMM0360
G  ,TZERC ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)                       COMM0370
H  ,XYCG(20) ,XZCG(20)                                             COMM0380
INTEGER OUT,FIT,STATE,SCRACH,PQR                                    COMM0390
COMMON /TAPENC/ IN,OUT,FIT,STATE,SCRACH,PQR                        COMM0400
COMMON /ATMCON /ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK    COMM0410
A  ,PB(23),RL(23),TMB(23)                                          COMM0420
COMMON /EXTRA / GO                                                 COMM0430
DIMENSION CTM(6) ,RCC(3) ,RCDC(3) ,RCDX(3,6),RCX(3,6) ,          OBSV0010
A  ,XA(5) ,XAX(5,7) ,XC(3) ,XCX(3,7) ,XLB(3) ,XLG(3) ,           OBSV0020
B  ,XLGE(3,4),XLGX(2,4),XS(3) ,XSC(3) ,XSD(3) ,XSDC(3) ,        OBSV0030
C  ,XSDX(3,6),XSX(3,3) ,CI(3,3) ,CJ(3,3)                          OBSV0040
EQUIVALENCE (DPH(1,1) ,CTM(1) ) , (DPH(7,1) ,RCC(1) ) ,          OBSV0050
N  (DPH(10,1),RCDC(1) ) , (DPH(3,2) ,RCDX(1,1)) ,                OBSV0060
O  (DPH(1,4) ,RCX(1,1) ) , (DPH(9,5) ,XA(1) ) ,                  OBSV0070
P  (DPH(4,6) ,XAX(1,1) ) , (DPH(9,9) ,XC(1) ) ,                  OBSV0080
G  (DPH(2,10),XCX(1,1) ) , (DPH(3,12),XLB(1) ) ,                 OBSV0090
R  (DPH(6,12),XLG(1) ) , (DPH(9,12),XLGE(1,1)) ,                 OBSV0100
S  (DPH(1,14),XLGX(1,1)) , (DPH(9,14),XS(1) ) ,                  OBSV0110
T  (DPH(2,15),XSC(1) ) , (DPH(5,15),XSD(1) ) ,                  OBSV0120
U  (DPH(8,15),XSDC(1) ) , (DPH(1,16),XSDX(1,1)) ,               OBSV0130
V  (DPH(9,17),XSX(1,1) ) , (DPH(8,18),CI(1,1) ) ,               OBSV0140
W  (DPH(7,19),CJ(1,1) ) , (DPH(6,20),CAZC ) ,                    OBSV0150

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X          (DPH(7,20),CDP      ), (DPH(8,20),CDY      ), OBSV0160
Y          (DPH(9,20),CELC     ), (DPH(10,20),CGR     ), OBSV0170
Z          (DPH(1,21),CLR      ), (DPH(2,21),CTH      ), OBSV0180
1          (DPH(3,21),SAZC     ), (DPH(4,21),SDP      ), OBSV0190
2          (DPH(5,21),SDY      ), (DPH(6,21),SELC     ), OBSV0200
3          (DPH(7,21),SGR      ), (DPH(8,21),SLR      ), OBSV0210
4          (DPH(9,21),STH      ), (DPH(10,21),THETA   ), OBSV0220
MT = 0
IF(L1-2) 14,10,14 OBSV0230
10 IF(NPC(5)) 14,12,14 OBSV0240
12 WRITE(OUT,1000) OBSV0250
1000 FORMAT(5X,6HPOINTS,5X,4HTYPE,4X,4HTIME,8X,5HCOMP1,10X,5HCOMP2,10X, OBSV0270
15HCOMP3,10X,4HSIG1,11X,4HSIG2,11X,4HSIG3) OBSV0280
L1=1 OBSV0290
14 IF(MTYP-6) 16,150,15 OBSV0300
15 IF(MTYP-8) 115,120,125 OBSV0310
16 N = 60+MTYP*15 OBSV0320
C-----CALCULATE EQ.(236) ----- OBSV0330
100 THETA=X(6)-C(N+14) OBSV0340
STH=SIN(THETA) OBSV0350
CTH=COS(THETA) OBSV0360
VO(1)= CPH*CPHDT(MTYP) OBSV0370
VO(2)= CPH*SPHDT(MTYP) OBSV0380
VO(3)= SPH*CPHDT(MTYP) OBSV0390
VO(4)= SPH*SPHDT(MTYP) OBSV0400
SP(1) = ROT(MTYP) + C(N+15) OBSV0410
VO(5) = SP(1)*CCAPH(MTYP) OBSV0420
VO(6) = SP(1)*SCAPH(MTYP) OBSV0430
C-----CALCULATE EQ.(235) ----- OBSV0440
102 XS(1)= R*(CTH*VO(1)+VO(4))-VO(5) OBSV0450
XS(2)= R*STH*CPH OBSV0460
XS(3)=-R*(CTH*VO(2)-VO(3))+VO(6) OBSV0470
VO(8)= SGRT(XS(2)**2+XS(3)**2) OBSV0480
VO(9)= VO(8)**2 OBSV0490
C-----CALCULATE EQ.(238A)----- OBSV0500
CTM(1)= SQRT(XS(1)**2+VO(9)) OBSV0510
C-----CALCULATE EQ.(238B)----- OBSV0520
SAZC= XS(2)/VO(8) OBSV0530
CAZC= XS(3)/VO(8) OBSV0540
C-----CALCULATE EQ.(238C)----- OBSV0550
SELC= XS(1)/CTM(1) OBSV0560
CELC= VO(8)/CTM(1) OBSV0570
CTM(2)= ATAN2(XS(2),XS(3)) OBSV0580
CTM(3)= ATAN2(XS(1),VO(8)) OBSV0590
C-----CALCULATE EQ.(239) ----- OBSV0600
DFM(1)= C(N+1)*CTM(1)+C(N+4)+C(N+10)/SELC OBSV0610
DFM(2)= C(N+2)*CTM(2)+C(N+5) OBSV0620
DFM(3)= C(N+3)*CTM(3)+C(N+6)+C(N+11)*CELC/SELC OBSV0630
IF(MO(MTYP)) 106,104,106 OBSV0640
104 IF(NPC(1)-1) 106,18,106 OBSV0650
C-----CALCULATE EQ.(246) ----- OBSV0660
106 XSX(1,1)= (XS(1)+VO(5))/R OBSV0670
XSX(1,2)= R*(VO(2)-CTH*VO(3)) OBSV0680
XSX(1,3)= -XS(2)*CPHDT(MTYP) OBSV0690
XSX(2,1)= XS(2)/R OBSV0700
XSX(2,2)= -R*STH*SPH OBSV0710
XSX(2,3)= R*CTH*CPH OBSV0720
XSX(3,1)= (XS(3)-VO(6))/R OBSV0730
XSX(3,2)= R*(CTH*VO(4)+VO(1)) OBSV0740
XSX(3,3)= XS(2)*SPHDT(MTYP) OBSV0750

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IF(MO(MTYP)) 108,18,108	OBSV0760
C-----CALCULATE EQ.(241) -----	OBSV0770
108 DO 112 I=1,3	OBSV0780
SUM=0.	OBSV0790
DO 110 J=1,3	OBSV0800
110 SUM=SUM+XSX(I,J)*DX(J+3)	OBSV0810
112 XSD(I)=SUM	OBSV0820
C-----CALCULATE EQ.(240) -----	OBSV0830
CTM(4)= (XS(1)*XSD(1)+XS(2)*XSD(2)+XS(3)*XSD(3))/CTM(1)	OBSV0840
CTM(5)= (XS(3)*XSD(2)-XS(2)*XSD(3))/VO(9)	OBSV0850
CTM(6)= (CTM(1)*XSD(1)-XS(1)*CTM(4))/(CTM(1)*VO(8))	OBSV0860
DFM(1)= DFM(1)+C(N+7)*CTM(4)	OBSV0870
DFM(2)= DFM(2)+C(N+8)*CTM(5)	OBSV0880
DFM(3)= DFM(3)+C(N+9)*CTM(6)	OBSV0890
GO TO 18	OBSV0900
115 DFM(1) =X(1)	OBSV0910
DFM(2)= X(2)	OBSV0920
DFM(3)= X(3)	OBSV0930
GO TO 18	OBSV0940
120 DFM(1) =X(4)	OBSV0950
DFM(2)= X(5)	OBSV0960
DFM(3)= X(6)	OBSV0970
GO TO 18	OBSV0980
C-----CALCULATE EQ.(264) -----	OBSV0990
125 F1(1,1)= C(65)*C(69)-C(66)*C(68)	OBSV1000
F1(1,2)=-C(62)*C(69)+C(63)*C(68)	OBSV1010
F1(1,3)= C(62)*C(66)-C(63)*C(65)	OBSV1020
F1(2,1)=-C(64)*C(69)+C(66)*C(67)	OBSV1030
F1(2,2)= C(61)*C(69)-C(63)*C(67)	OBSV1040
F1(2,3)=-C(61)*C(66)+C(63)*C(64)	OBSV1050
F1(3,1)= C(64)*C(68)-C(65)*C(67)	OBSV1060
F1(3,2)=-C(61)*C(68)+C(62)*C(67)	OBSV1070
F1(3,3)= C(61)*C(65)-C(62)*C(64)	OBSV1080
C-----CALCULATE EQ.(265) -----	OBSV1090
VO(4)= C(61)*F1(1,1)+C(62)*F1(2,1)+C(63)*F1(3,1)	OBSV1100
DO 128 I=1,3	OBSV1110
DO 127 J=1,3	OBSV1120
C-----CALCULATE EQ.(266) -----	OBSV1130
127 CI(I,J)= F1(I,J)/VO(4)	OBSV1140
128 VO(I)= AP(I)- C(69+I)	OBSV1150
C-----CALCULATE EQ.(258) -----	OBSV1160
DO 130 I=1,3	OBSV1170
DFM(I) = 0.	OBSV1180
DO 130 J=1,3	OBSV1190
130 DFM(I) = DFM(I) + CI(I,J)*VO(J)	OBSV1200
GO TO 18	OBSV1210
C 150 CALCULATE AMR	OBSV1220
150 SDP= SIN(C(151))	OBSV1230
CDP= COS(C(151))	OBSV1240
SDY= SIN(C(152))	OBSV1250
CDY= COS(C(152))	OBSV1260
C-----CALCULATE EQ.(269) -----	OBSV1270
XLB(1)= CDY*CDP	OBSV1280
XLB(2)= SDY	OBSV1290
XLB(3)= CDY*SDP	OBSV1300
C-----CALCULATE EQ.(270) -----	OBSV1310
DO 152 I=1,3	OBSV1320
XLG(I)=0.	OBSV1330
DO 152 J=1,3	OBSV1340
152 XLG(I)=XLG(I)+A(J,I)*XLB(J)	OBSV1350

	VO(1)= REO**2	OBSV1360
C-----	-----CALCULATE EQ.(271A)-----	OBSV1370
	VO(2)= ATAN2(XLG(2),XLG(1))	OBSV1380
C-----	-----CALCULATE EQ.(271B)-----	OBSV1390
	SP(1)= SQRT(XLG(1)**2+XLG(2)**2)	OBSV1400
	VO(3)=-ATAN2(XLG(3),SP(1))	OBSV1410
	SLR= SIN(VO(2))	OBSV1420
	CLR= COS(VO(2))	OBSV1430
	SGR= SIN(VO(3))	OBSV1440
	CGR= COS(VO(3))	OBSV1450
C-----	-----CALCULATE EQ.(277) -----	OBSV1460
	XA(1)= SLR*CGR	OBSV1470
	XA(2)= R*CPH	OBSV1480
	XA(3)= CPH*SGR-SPH*CLR*CGR	OBSV1490
	XA(4)= R*SPH	OBSV1500
	XA(5)= SPH*SGR+CPH*CLR*CGR	OBSV1510
C-----	-----CALCULATE EQ.(276) -----	OBSV1520
	XC(1)= XA(1)**2 + XA(3)**2 + RERP2*XA(5)**2	OBSV1530
	XC(2)= 2.*(XA(2)*XA(3)+ RERP2*XA(4)*XA(5))	OBSV1540
	XC(3)= XA(2)**2 + RERP2*XA(4)**2 - VO(1)	OBSV1550
	SP(2)= XC(2)**2 - 4.*XC(1)*XC(3)	OBSV1560
	IF(SP(2)) 154,156,156	OBSV1570
	154 WRITE(OUT,5022)	OBSV1580
	5022 FORMAT(49H IMAGINARY OR NEGATIVE SOLUTION ON AIRBORNE RADAR)	OBSV1590
	DO 160 I=1,3	OBSV1600
	DFM(I) = 0.	OBSV1610
	DO 158 J=1,NSTX	OBSV1620
	158 G(I,J) = 0.	OBSV1630
	DO 160 J=1,NPV	OBSV1640
	H(I,J) = 0.	OBSV1650
	160 CONTINUE	OBSV1660
	SI(1) = 1.E20	OBSV1670
	RETURN	OBSV1680
C-----	-----CALCULATE EQ.(273) -----	OBSV1690
	156 DFM(1)= -.5*(XC(2)+SQRT(SP(2)))/XC(1)	OBSV1700
	IF(DFM(1).LT.0.) GO TO 154	OBSV1710
	DFM(2)= 0.	OBSV1720
	DFM(3)= 0.	OBSV1730
	18 IF(DCOMP.LT.0.) GO TO 80	OBSV1740
	DO 20 I=1,3	OBSV1750
	SP(I) = SYG(I,MTYP)	OBSV1760
	IF(NPC(1).EQ.0) SP(I) = SP(I)+SIGM(I)	OBSV1770
	20 KC(I)=0	OBSV1780
	IF(KN) 22,22,24	OBSV1790
	22 KOB=KAR	OBSV1800
	GO TO 26	OBSV1810
	24 KOB=JNBR	OBSV1820
	26 DO 28 I=KAR,KOB	OBSV1830
	J=LC(I)	OBSV1840
	DATC(I)=DFM(J)	OBSV1850
	SI(I)=SP(J)	OBSV1860
	NCOUNT=NCOUNT+1	OBSV1870
	28 KC(J) = NCOUNT	OBSV1880
	30 IF(NPC(5)) 34,32,34	OBSV1890
	32 CONTINUE	OBSV1900
	WRITE(OUT,1002) (KC(I),I=1,3),MTYP,TO,(DFM(I),I=1,3),(SP(I),I=1,3)	OBSV1910
	1002 FORMAT(1X,I4,1H,I4,1H,I4,2X,I2,1X,F10.4,F15.2,5F15.6)	OBSV1920
	34 DO 36 I=1,NSTX	OBSV1930
	DO 36 J=KAR,KOB	OBSV1940
	36 G(J,I)=0.	OBSV1950

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IF(MTYP-6) 200,250,270
C 200 CALCULATE G(1-10) FOR R,A,E
C-----CALCULATE EQ.(244)-----
200 DO 202 I=1,3
   RCX(1,I)= (XSX(1,I)*XS(1)+XSX(2,I)*XS(2)+XSX(3,I)*XS(3))/CTM(1)
   RCX(2,I)= (XSX(2,I)*XS(3)-XSX(3,I)*XS(2))/VO(9)
202 RCX(3,I)= (XSX(1,I)-RCX(1,I)*SELC)/VO(8)
   IF(MO(MTYP)) 204,218,204
204 SP(1)= R*CPH
   SP(2)= DX(5)/R
   SP(3)= X(2)/(R*SP(1))
   SP(4)= X(2)*TPH/SP(1)
C-----CALCULATE EQ.(247)-----
DO 206 I=1,3
   XSDX(I,1)= XSX(I,2)/R
   XSDX(I,2)= XSX(I,3)/SP(1)
   XSDX(I,3)=-XSX(I,1)
   XSDX(I,4)=-XSX(I,2)*SP(2)-XSX(I,3)*SP(3)
206 XSDX(I,5)= XSX(I,3)*SP(4)
   VO(10)=-X(3)/R
   SP(4)= DX(6)/R
   SP(5)= DX(5)/R
   SP(6)=-TPH*DX(6)
   SP(7)=-R*DX(5)
   SP(1)= CTH*DX(6)/STH - TPH*DX(5)
   SP(3)= SP(1)
   SP(2)=-STH*DX(6)/CTH - TPH*DX(5)
DO 208 I=1,3
   XSDX(I,4)= XSDX(I,4)+XSX(I,3)*SP(4)+XSX(I,2)*SP(5)
   XSDX(I,5)= XSDX(I,5)+XSX(I,2)*VO(10)+XSX(I,3)*SP(6)+XSX(I,1)*SP(7)
208 XSDX(I,6)= XSX(I,3)*VO(10)+XSX(I,3)*SP(1)
   VO(11)=-XSD(3)+2.*CTM(5)*XS(2)
   VO(12)= XSD(2)-2.*CTM(5)*XS(3)
   SP(1)= -CTM(6)*XS(2)/CELC
   SP(2)= -CTM(6)*XS(3)/CELC
   SP(3)= XSD(1)-CTM(6)*VO(8)
C-----CALCULATE EQ.(245)-----
DO 216 I=1,6
   IF(I-3) 210,210,212
210 RCDX(1,I)=0.
   RCDX(2,I)=0.
   RCDX(3,I)=0.
   GO TO 214
212 RCDX(1,I)=XSX(1,I-3)*XSD(1)+XSX(2,I-3)*XSD(2)+XSX(3,I-3)*XSD(3)
   X
   -RCX(1,I-3)*CTM(4)
   RCDX(2,I)=XSX(3,I-3)*VO(12)+XSX(2,I-3)*VO(11)
   RCDX(3,I)=-XSX(1,I-3)*CTM(4)+XSX(2,I-3)*SP(1)+XSX(3,I-3)*SP(2)
   X
   +RCX(1,I-3)*SP(3)
214 RCDX(1,I)=(RCDX(1,I)+XSDX(1,I)*XS(1)+XSDX(2,I)*XS(2)
   X
   +XSDX(3,I)*XS(3))/CTM(1)
   RCDX(2,I)=(RCDX(2,I)+XSDX(2,I)*XS(3)-XSDX(3,I)*XS(2))/VO(9)
216 RCDX(3,I)=((RCDX(3,I)-RCDX(1,I)*XS(1))/CTM(1)+XSDX(1,I))/VO(8)
218 VO(13)= C(N+10)*CELC/SELC**2
   VO(14)= C(N+3)-C(N+11)/SELC**2
DO 230 I=1,6
   IF(I-3) 220,220,222
220 GG(1)=0.
   GG(2)=0.
   GG(3)=0.
   GO TO 224
OBSV1960
OBSV1970
OBSV1980
OBSV1990
OBSV2000
OBSV2010
OBSV2020
OBSV2030
OBSV2040
OBSV2050
OBSV2060
OBSV2070
OBSV2080
OBSV2090
OBSV2100
OBSV2110
OBSV2120
OBSV2130
OBSV2140
OBSV2150
OBSV2160
OBSV2170
OBSV2180
OBSV2190
OBSV2200
OBSV2210
OBSV2220
OBSV2230
OBSV2240
OBSV2250
OBSV2260
OBSV2270
OBSV2280
OBSV2290
OBSV2300
OBSV2310
OBSV2320
OBSV2330
OBSV2340
OBSV2350
OBSV2360
OBSV2370
OBSV2380
OBSV2390
OBSV2400
OBSV2410
OBSV2420
OBSV2430
OBSV2440
OBSV2450
OBSV2460
OBSV2470
OBSV2480
OBSV2490
OBSV2500
OBSV2510
OBSV2520
OBSV2530
OBSV2540
OBSV2550

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C-----CALCULATE EQ.(243)-----
222 GG(1)= C(N+1)*RCX(1,I-3)-VO(13)*RCX(3,I-3)
GG(2)= C(N+2)*RCX(2,I-3)
GG(3)= VO(14)*RCX(3,I-3)
224 IF(MO(MTYP)) 226,228,226
226 GG(1)= GG(1)+ C(N+7)*RCDX(1,I)
GG(2)= GG(2)+ C(N+8)*RCDX(2,I)
GG(3)= GG(3)+ C(N+9)*RCDX(3,I)
228 DO 230 K=KAR,KOB
J=LC(K)
230 G(K,I)=GG(J)
232 CONTINUE
GO TO 38
OBSV2560
OBSV2570
OBSV2580
OBSV2590
OBSV2600
OBSV2610
OBSV2620
OBSV2630
OBSV2640
OBSV2650
OBSV2660
OBSV2670
OBSV2680
OBSV2690

C-----CALCULATE EQ.(286)-----
250 XLGE(1,1)= 2.*( X( 7)*XLB(1)-X(10)*XLB(2)+X( 9)*XLB(3))
XLGE(1,2)= 2.*( X( 8)*XLB(1)+X( 9)*XLB(2)+X(10)*XLB(3))
XLGE(1,3)= 2.*(-X( 9)*XLB(1)+X( 8)*XLB(2)+X( 7)*XLB(3))
XLGE(1,4)= 2.*(-X(10)*XLB(1)-X( 7)*XLB(2)+X( 8)*XLB(3))
XLGE(2,1)= 2.*( X(10)*XLB(1)+X( 7)*XLB(2)-X( 8)*XLB(3))
XLGE(2,2)= 2.*( X( 9)*XLB(1)-X( 8)*XLB(2)-X( 7)*XLB(3))
XLGE(2,3)= 2.*( X( 8)*XLB(1)+X( 9)*XLB(2)+X(10)*XLB(3))
XLGE(2,4)= 2.*( X( 7)*XLB(1)-X(10)*XLB(2)+X( 9)*XLB(3))
XLGE(3,1)= 2.*(-X( 9)*XLB(1)+X( 8)*XLB(2)+X( 7)*XLB(3))
XLGE(3,2)= 2.*( X(10)*XLB(1)+X( 7)*XLB(2)-X( 8)*XLB(3))
XLGE(3,3)= 2.*(-X( 7)*XLB(1)+X(10)*XLB(2)-X( 9)*XLB(3))
XLGE(3,4)= 2.*( X( 8)*XLB(1)+X( 9)*XLB(2)+X(10)*XLB(3))
SP(4)= SGR/CGR
SP(3)= XLG(1)**2 + XLG(2)**2
SP(1)= SQRT(SP(3))
DO 258 I=1,4
OBSV2700
OBSV2710
OBSV2720
OBSV2730
OBSV2740
OBSV2750
OBSV2760
OBSV2770
OBSV2780
OBSV2790
OBSV2800
OBSV2810
OBSV2820
OBSV2830
OBSV2840
OBSV2850

C-----CALCULATE EQ.(284)-----
XLGX(1,I) = (XLG(1)*XLGE(2,I)-XLG(2)*XLGE(1,I))/SP(3)
OBSV2860
OBSV2870

C-----CALCULATE EQ.(285)-----
258 XLGX(2,I) =-SP(1)*XLGE(3,I)-SP(4)*(XLG(1)*XLGE(1,I)+XLG(2)*XLGE(2,
1))
VO(4)= -SLR*SGR
VO(5)= CLR*CGR
VO(6)= CPH*CGR+SPH*CLR*SGR
VO(7)= SPH*XA(1)
VO(9)= SPH*CGR-CPH*CLR*SGR
VO(10)= CPH*XA(1)
OBSV2880
OBSV2890
OBSV2900
OBSV2910
OBSV2920
OBSV2930
OBSV2940
OBSV2950
OBSV2960

C-----CALCULATE EQ.(283)-----
DO 260 I=1,5
DO 260 J=1,7
260 XAX(I,J)= 0.
DO 262 I=1,4
XAX(1,I+3) = VO(4)*XLGX(2,I) + VO(5)*XLGX(1,I)
XAX(3,I+3) = VO(6)*XLGX(2,I) + VO(7)*XLGX(1,I)
262 XAX(5,I+3) = VO(9)*XLGX(2,I) - VO(10)*XLGX(1,I)
XAX(2,1) = CPH
XAX(2,2) =-XA(4)
XAX(3,2) =-XA(5)
XAX(4,1) = SPH
XAX(4,2) = XA(2)
XAX(5,2) = XA(3)
OBSV2970
OBSV2980
OBSV2990
OBSV3000
OBSV3010
OBSV3020
OBSV3030
OBSV3040
OBSV3050
OBSV3060
OBSV3070
OBSV3080
OBSV3090
OBSV3100

C-----CALCULATE EQ.(282)-----
DO 264 I=1,7
XCX(1,I)= 2.*(XA(1)*XAX(1,I)+XA(3)*XAX(3,I)+RERP2*XA(5)*XAX(5,I))
XCX(2,I)= 2.*(XA(2)*XAX(3,I)+XA(3)*XAX(2,I)+RERP2*(XA(4)*XAX(5,I)
+ XA(5)*XAX(4,I)))
OBSV3110
OBSV3120
OBSV3130
OBSV3140
OBSV3150

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264	XCX(3,I) = 2.*(XA(2)*XAX(2,I)+RERP2*XA(4)*XAX(4,I))	OBSV3160
	G(1,1) = 0.	OBSV3170
	G(1,2) = 0.	OBSV3180
	G(1,3) = 0.	OBSV3190
	VO(11) = 2.*XC(1)*DFM(1)+XC(2)	OBSV3200
	VO(12) = (DFM(1)+XC(3)/VO(11))/XC(1)	OBSV3210
	VO(13) = (.5-.5*XC(2)/VO(11))/XC(1)	OBSV3220
	VO(14) = 1./VO(11)	OBSV3230
C-----CALCULATE EQ.(281)-----		OBSV3240
	DO 266 I=1,7	OBSV3250
266	G(1,I+3) = -VO(12)*XCX(1,I)-VO(13)*XCX(2,I)-VO(14)*XCX(3,I)	OBSV3260
	GO TO 38	OBSV3270
270	IF(MTYP-8) 272,274,290	OBSV3280
272	LT=0	OBSV3290
	GO TO 276	OBSV3300
274	LT=3	OBSV3310
276	DO 284 I=KAR,KOB	OBSV3320
	J=LC(I)	OBSV3330
284	G(I,LT+J) = 1.	OBSV3340
	GO TO 38	OBSV3350
290	DO 296 I=1,10	OBSV3360
	DO 292 J=1,3	OBSV3370
	GG(J)=0.	OBSV3380
	DO 292 K=1,3	OBSV3390
292	GG(J) = GG(J)+CI(J,K)*PAXP(K,I)	OBSV3400
	DO 294 K=KAR,KOB	OBSV3410
	J=LC(K)	OBSV3420
294	G(K,I)=GG(J)	OBSV3430
296	CONTINUE	OBSV3440
38	CONTINUE	OBSV3450
	IF(NSTC) 40,40,46	OBSV3460
40	IF(NPV) 99,99,42	OBSV3470
42	II=1	OBSV3480
	IP=1	OBSV3490
44	JJ=MCC(II)	OBSV3500
	GO TO 50	OBSV3510
46	II=1	OBSV3520
	IP=0	OBSV3530
48	JJ=NC(II)	OBSV3540
50	GG(1)=0.	OBSV3550
	GG(2)=0.	OBSV3560
	GG(3)=0.	OBSV3570
	IF(MTYP.GE.6) GO TO 375	OBSV3580
	IF(JJ-N) 60,60,54	OBSV3590
54	IF(JJ-N-15) 56,56,60	OBSV3600
56	JN=JJ-N	OBSV3610
	IF(JN-12) 58,58,350	OBSV3620
58	GO TO(300,301,302,303,304,305,306,307,308,309,310,311),JN	OBSV3630
60	II=II+1	OBSV3640
	DO 66 I=KAR,KOB	OBSV3650
	J=LC(I)	OBSV3660
	IF(IP) 62,62,64	OBSV3670
62	G(I,II+9) = GG(J)	OBSV3680
	GO TO 66	OBSV3690
64	H(I,II-1) = GG(J)	OBSV3700
66	CONTINUE	OBSV3710
	IF(IP) 68,68,70	OBSV3720
68	IF(II-NSTC) 48,48,40	OBSV3730
70	IF(II-NPV) 44,44,99	OBSV3740
C-----CALCULATE EQ.(248)-----		OBSV3750

300	GG(1) = CTM(1)	OBSV3760
	GO TO 60	OBSV3770
301	GG(2) = CTM(2)	OBSV3780
	GO TO 60	OBSV3790
302	GG(3) = CTM(3)	OBSV3800
	GO TO 60	OBSV3810
303	GG(1) = 1.	OBSV3820
	GO TO 60	OBSV3830
304	GG(2) = 1.	OBSV3840
	GO TO 60	OBSV3850
305	GG(3) = 1.	OBSV3860
	GO TO 60	OBSV3870
306	GG(1) = CTM(4)	OBSV3880
	GO TO 60	OBSV3890
307	GG(2) = CTM(5)	OBSV3900
	GO TO 60	OBSV3910
308	GG(3) = CTM(6)	OBSV3920
	GO TO 60	OBSV3930
309	GG(1) = 1./SELC	OBSV3940
	GO TO 60	OBSV3950
310	GG(3) = CELC/SELC	OBSV3960
311	GO TO 60	OBSV3970
350	SP(1) = SIN(C(N+13))	OBSV3980
	SP(2) = COS(C(N+13))	OBSV3990
	IF(JN-14) 352,354,356	OBSV4000
352	VO(15) = RERP2*(CPHDT(MTYP)/SP(2))**2	OBSV4010
	VO(16) = -(ROT(MTYP)/RE0)**2*(RERP2-1.)*SP(1)*SP(2)*ROT(MTYP)	OBSV4020
	C-----CALCULATE EQ.(252)-----	OBSV4030
	XSC(1) = XS(3)*VO(15)-VO(16)-VO(16)*CCAPH(MTYP)	OBSV4040
	XSC(2) = 0.	OBSV4050
	XSC(3) = -XS(1)*VO(15)-VO(16)+ VO(16)*SCAPH(MTYP)	OBSV4060
	GO TO 358	OBSV4070
354	XSC(1) = -XSX(1,3)	OBSV4080
	XSC(2) = -XSX(2,3)	OBSV4090
	XSC(3) = -XSX(3,3)	OBSV4100
	GO TO 358	OBSV4110
356	XSC(1) = -CCAPH(MTYP)	OBSV4120
	XSC(2) = 0.	OBSV4130
	XSC(3) = SCAPH(MTYP)	OBSV4140
	C-----CALCULATE EQ.(250)-----	OBSV4150
358	RCC(1) = (XSC(1)*XS(1)+XSC(2)*XS(2)+XSC(3)*XS(3))/CTM(1)	OBSV4160
	RCC(2) = (XSC(2)*XS(3)-XSC(3)*XS(2))/VO(9)	OBSV4170
	RCC(3) = (XSC(1)-RCC(1)*SELC)/VO(8)	OBSV4180
	C-----CALCULATE EQ.(249)-----	OBSV4190
	GG(1) = C(N+1)*RCC(1)-VO(13)*RCC(3)	OBSV4200
	GG(2) = C(N+2)*RCC(2)	OBSV4210
	GG(3) = VO(14)*RCC(3)	OBSV4220
	IF(MO(MTYP)) 360,60,360	OBSV4230
360	IF(JN-14) 362,364,366	OBSV4240
362	SP(3) = VO(15)-1.	OBSV4250
	SP(5) = XS(2)*DX(6)	OBSV4260
	C-----CALCULATE EQ.(253A)-----	OBSV4270
	XSDC(1) = VO(10)*(XSC(1)+VO(16)*CCAPH(MTYP)-VO(6)*SP(3))	OBSV4280
	X + VO(15)*(XSX(3,2)*DX(5)+SP(5)*SPHDT(MTYP))	OBSV4290
	XSDC(2) = 0.	OBSV4300
	XSDC(3) = VO(10)*(XSC(3)-VO(16)*SCAPH(MTYP)-VO(5)*SP(3))	OBSV4310
	X + VO(15)*(-XSX(1,2)*DX(5)+SP(5)*CPHDT(MTYP))	OBSV4320
	GO TO 368	OBSV4330
364	SP(1) = XSX(2,3)*DX(6)+XSX(2,2)*DX(5)	OBSV4340
	C-----CALCULATE EQ.(253B)-----	OBSV4350

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XSDC(1)= VO(10)*XSC(1)+ SP(1)*CPHDT(MTYP)
XSDC(2)= VO(10)*XSC(2)+ XS(2)*DX(6)+R*CTH*SPH*DX(5)
XSDC(3)= VO(10)*XSC(3)- SP(1)*SPHDT(MTYP)
GO TO 368
366 RCDC(1)= 0.
RCDC(2)= 0.
RCDC(3)= 0.
GO TO 370
-----CALCULATE EQ.(251)-----
368 RCDC(1)= XSDC(1)*XS(1)+XSDC(2)*XS(2)+XSDC(3)*XS(3)
RCDC(2)= XSDC(2)*XS(3)-XSDC(3)*XS(2)
RCDC(3)= XSDC(1)*CTM(1)
370 SP(1)= CTM(6)*XS(2)/CELC
SP(2)= CTM(6)*XS(3)/CELC
SP(3)= XSD(1)-CTM(6)*VO(8)
SP(4)= CTM(1)*VO(8)
RCDC(1)=(RCDC(1)+XSC(1)*XSD(1)+XSC(2)*XSD(2)+XSC(3)*XSD(3)
X -RCC(1)*CTM(4))/CTM(1)
RCDC(2)=(RCDC(2)+XSC(2)*VO(11)+XSC(3)*VO(12))/VO(9)
RCDC(3)=(RCDC(3)-RCDC(1)*XS(1)-XSC(1)*CTM(4)-XSC(2)*SP(1)
X -XSC(3)*SP(2)+RCC(1)*SP(3))/SP(4)
GG(1)= GG(1) + C(N+7)*RCDC(1)
GG(2)= GG(2) + C(N+8)*RCDC(2)
GG(3)= GG(3) + C(N+9)*RCDC(3)
GO TO 60
375 IF(MTYP.EQ.9) GO TO 400
DO 390 I=1,3
DO 385 J=1,NSTC
385 G(I,J+10) = 0.
DO 390 J=1,NPV
390 H(I,J) = 0.
RETURN
400 IF(JJ.LE.35) GO TO 405
IF(JJ.GT.72) GO TO 60
IF(JJ.GE.70) GO TO 435
IF(JJ.GT.60) GO TO 440
405 NNN = JJ
CALL PAXPC
IF(JJ.GE.45) GO TO 415
407 DO 410 I=1,3
410 GG(I) = CI(1,1)*VO(1) + CI(I,2)*VO(2) + CI(I,3)*VO(3)
C OBSV4770 THRU OBSV4880 HAVE BEEN DELETED
GO TO 60
415 DO 420 I=1,3
420 VO(I) = DTRAN(I,1)*SP(4)+DTRAN(I,2)*SP(5)+DTRAN(I,3)*SP(6)
GO TO 407
435 GG(1) =-CI(1,JJ-69)
GG(2) =-CI(2,JJ-69)
GG(3) =-CI(3,JJ-69)
GO TO 60
440 I = (JJ-58)/3
J = JJ - 3*I - 57
SP(4) = CI(J,1)*(C(70)-AP(1)) + CI(J,2)*(C(71)-AP(2))
+ CI(J,3)*(C(72)-AP(3))
GG(1) = CI(1,I)*SP(4)
GG(2) = CI(2,I)*SP(4)
GG(3) = CI(3,I)*SP(4)
GO TO 60
80 DO 82 I=1,3
SP(I)=SYG(I,MTYP)

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OBSV4360
OBSV4370
OBSV4380
OBSV4390
OBSV4400
OBSV4410
OBSV4420
OBSV4430
OBSV4440
OBSV4450
OBSV4460
OBSV4470
OBSV4480
OBSV4490
OBSV4500
OBSV4510
OBSV4520
OBSV4530
OBSV4540
OBSV4550
OBSV4560
OBSV4570
OBSV4580
OBSV4590
OBSV4600
OBSV4610
OBSV4620
OBSV4630
OBSV4640
OBSV4650
OBSV4660
OBSV4670
OBSV4680
OBSV4690
OBSV4700
OBSV4710
OBSV4720
OBSV4730
OBSV4740
OBSV4750
OBSV4760
OBSV4770
OBSV4890
OBSV4900
OBSV4910
OBSV4920
OBSV4930
OBSV4940
OBSV4950
OBSV4960
OBSV4970
OBSV4980
OBSV4990
OBSV5000
OBSV5010
OBSV5020
OBSV5030
OBSV5040
OBSV5050
OBSV5060

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IF(NPC(1).NE.2) SP(I)=SP(I)+SIG(I,K6)
82 CONTINUE
99 CONTINUE
RETURN
END
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OBSV5070
OBSV5080
OBSV5090
OBSV5100
OBSV5110
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SUBROUTINE OUTPUT
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40), COMM0010
* NALL,LRK COMM0020
COMMON /MOD1/ ALPH,AS ,BETA,CA(6),CALP ,CBET ,CETA , COMM0030
1 CF(3),JCS ,CXZI ,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH , COMM0040
2 DRDP,DWDH(2),ETA,HO,N4(3) ,N5(3) ,N6(3) ,PAXP(3,30), COMM0050
3 PR ,ROE ,ROEC ,ROEM ,SALP ,SBET , COMM0060
4 SFA ,SREF ,SXZI ,TAU ,TMAS(20) ,TONE , COMM0070
5 TMO ,TUW(20) ,TVW(20) ,UW ,VA(5) ,VB(5) , COMM0080
6 VW ,XIND1 ,XIND2 ,XLREF ,XM , COMM0090
7 XMAS(20) ,XNU ,XO ,XGSM ,XRE ,XTEMP , COMM0100
8 XUW(20) ,XVW(20) ,XZI ,YMAS ,YMASM COMM0110
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5) COMM0120
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4) COMM0130
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4) COMM0140
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2) COMM0150
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,K62 COMM0160
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6) COMM0170
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50) COMM0180
DIMENSION DUB(30,15) COMM0190
EQUIVALENCE (AG(1),DUB(1,1)) COMM0200
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40) COMM0210
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5) COMM0220
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3) COMM0230
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET COMM0240
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST COMM0250
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK COMM0260
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT COMM0270
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT COMM0280
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15) COMM0290
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9) COMM0300
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30) COMM0310
B ,PA(3) ,PM(3) ,R ,REO ,RERP2 COMM0320
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40) COMM0330
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL COMM0340
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40) COMM0350
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20) COMM0360
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20) COMM0370
H ,XYCG(20) ,XZCG(20) COMM0380
INTEGER OUT,FIT,STATE,SCRACH,PQR COMM0390
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR COMM0400
COMMON /ATMCON /ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK COMM0410
A ,PB(23),RL(23),TMB(23) COMM0420
COMMON /EXTRA / GO COMM0430
2 CALL AUXIL OUTP0010
4 ZO(1) = VA(2) OUTP0020
ZO(2) = SQRT(VA(1)**2+VA(2)**2) OUTP0030
VO(1) = VA(4) OUTP0040
IF(VO(1).EQ.0.) VO(1)=.00001 OUTP0050
ST(1)=-X(3)/VG(1) OUTP0060
CT(1)= ZO(2)/VO(1) OUTP0070
VO(2)=ATAN2(ST(1),CT(1))/CONRD OUTP0080
IF(ZO(2).EQ.0.) ZO(2)=.00001 OUTP0090
ST(2)= ZO(1)/ZO(2) OUTP0100
CT(2) = VA(1)/ZO(2) OUTP0110
VO(3)=ATAN2(ST(2),CT(2))/CONRD OUTP0120
RO=REO/SQRT(1.-(1.-RERP2)*SPH**2) OUTP0130
VO(4)= X(4)+REO-RO OUTP0140
VO(5)=ATAN2(RERP2*SPH,CPH)/CONRD OUTP0150

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VO(6)= X(6)/CONRD
SP(1)=SQRT(X(1)**2+X(2)**2)
VO(7)= SQRT(SP(1)**2+X(3)**2)
IF(SP(1).EQ.0.) SP(1)=.00001
VO(8)=ATAN2(-X(3),SP(1))/CONRD
VO(9)=ATAN2(X(2),X(1))/CONRD
VO(10)=ATAN2(A(1,2),A(1,1))/CONRD
SP(1) =SQRT(1.-A(1,3)**2)
VO(11)=-ATAN2(A(1,3),SP(1))/CONRD
VO(12)=ATAN2(A(2,3),A(3,3))/CONRD
VO(13) = VB(1)
VO(14) = VB(2)
VO(15) = VB(3)
ZO(3) = VB(4)
ST(4) = VB(2)/VA(4)
CT(4) = VB(4)/VA(4)
VO(17)=ATAN2(ST(4),CT(4))/CONRD
ST(5) = VB(3)/VB(4)
CT(5) = VB(1)/VB(4)
VO(18)=ATAN2(ST(5),CT(5))/CONRD
ZO(4)=A(2,3)+ST(4)*ST(1)
ZO(5)=(A(2,2)*CT(2)-A(2,1)*ST(2))*CT(1)
ZO(9)=SQRT(ZO(4)**2+ZO(5)**2)
IF(ZO(9).EQ.0.) ZO(9)=.000001
ST(3)=ZO(4)/ZO(9)
CT(3)=ZO(5)/ZO(9)
VO(16)=ATAN2(ST(3),CT(3))/CONRD
SP(1)=SQRT(VO(14)**2+VO(15)**2)
SP(3)=ATAN2(SP(1),VO(1))/CONRD
SP(2)=ATAN2(VO(14),VO(15))/CONRD
VO(19)=X(5)/CONRD
WRITE(OUT,1001)
1001 FORMAT(//)
WRITE(OUT,1000) TO
WRITE(OUT,1002) (VO(I),I=1,6)
WRITE(OUT,1004) X(1),X(2),X(3),VO(10),VO(11),VO(12)
WRITE(OUT,1006) (VO(I),I=13,18)
WRITE(OUT,1008) (XP(I),I=1,3),(SP(I),I=1,3)
WRITE(OUT,1010) (PA(I),I=1,3),(AB(I),I=1,3)
WRITE(OUT,1012) (PM(I),I=1,3),(CF(I),I=1,3)
WRITE(OUT,1011) XQ,XM,ROE,(CA(I),I=1,3)
WRITE(OUT,1014) (X(I),I=7,10),VO(19),XRE
WRITE(OUT,1015) Uw,Vw
1000 FORMAT(5H TIME,E15.8)
1002 FORMAT(5H V(R),E15.8,5H G(R)E15.8,5H L(R)E15.8,5H ALT E15.8,5H LATOUTP0600
1 E15.8,5H LON E15.8)
1004 FORMAT(5H U(1),E15.8,5H V(I)E15.8,5H W(I)E15.8,5H PSI E15.8,5H THEOUTP0620
2 E15.8,5H PHI E15.8)
1006 FORMAT(5H U(B),E15.8,5H V(B)E15.8,5H W(B)E15.8,5H SIG E15.8,5H BETOUTP0640
3 E15.8,5H ALF E15.8)
1008 FORMAT(5H XP ,E15.8,5H YP E15.8,5H ZP E15.8,5H V(T)E15.8,5H XZIOUTP0660
4 E15.8,5H ETA E15.8)
1010 FORMAT(5H P ,E15.8,5H Q E15.8,5H R E15.8,5H AX E15.8,5H AY OUTP0680
5 E15.8,5H AZ E15.8)
1011 FORMAT(5H DP ,E15.8,5H M ,E15.8,5H RHO ,E15.8,5H C1 ,E15.8,5H OUTP0700
1C2 ,E15.8,5H C3 ,E15.8)
1012 FORMAT(5H PM ,E15.8,5H QM E15.8,5H RM E15.8,5H CX E15.8,5H CY OUTP0720
6 E15.8,5H CZ E15.8)
1014 FORMAT(5H EU ,E15.8,5H E1 E15.8,5H E2 E15.8,5H E3 E15.8,5H LATOUTP0740
7CE15.8,5H RE E15.8)

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1015 FORMAT(5H UW ,E15.8,5H VW E15.8)
      IF(NPC(1)-1) 20,99,28
20  IF(DCOMP) 28,22,22
22  IF(NSTC) 28,28,24
24  DO 26 I=1,NSTC
      K=NC(I)
26  AG(I) = C(K)
      WRITE(OUT,1016) (NC(I),AG(I),I=1,NSTC)
1016 FORMAT(6(2H C,I3,E15.8))
28  IF(NPC(3)-1) 30,100,100
100 DO 102 I=1,6
      DO 102 K=1,10
102  DUB(K,I)=0.
      ZO(6) = VA(5)
      ZO(7)=ZO(6)*ZO(2)
      ZO(8) =-DWDH(2)+OMEGA*CPH
      DUB(1,1) = VA(1)/VA(4)
      DUB(2,1) = VA(2)/VA(4)
      DUB(3,1)= X(3)/VO(1)
      DUB(4,1) = DUB(1,1)*DWDH(1) - DUB(2,1)*ZO(8)
      DUB(5,1) =-(DUB(1,1)*DWDH(1)+DUB(2,1)*DWDH(2))*DRDP+DUB(2,1)*R*
1      OMEGA*SPH
      SP(1)= X(3)/(VO(1)*ZO(2))
      DUB(1,2)= SP(1)*DUB(1,1)
      DUB(2,2)= SP(1)*DUB(2,1)
      DUB(3,2)=-ZO(2)/ZO(6)
      DUB(4,2)= SP(1)*DUB(4,1)
      DUB(5,2)= SP(1)*DUB(5,1)
      SP(1)=ZO(2)**2
      SP(2) = VA(2)*DWDH(1) - VA(1)*DWDH(2)
      DUB(1,3) = -VA(2)/SP(1)
      DUB(2,3) = VA(1)/SP(1)
      DUB(4,3) = -(SP(2)+VA(1)*OMEGA*CPH)/SP(1)
      DUB(5,3) = (SP(2)*DRDH+VA(1)*R*OMEGA*SPH)/SP(1)
      IF(NPC(3)-1) 120,110,120
110 SP(1)= 2./(A(1,1)**2+A(1,2)**2)
      DUB(7,4)=SP(1)*(X(10)*A(1,1)-X(7)*A(1,2))
      DUB(8,4)=SP(1)*(X(9)*A(1,1)-X(8)*A(1,2))
      DUB(9,4)=SP(1)*(X(8)*A(1,1)+X(9)*A(1,2))
      DUB(10,4)=SP(1)*(X(7)*A(1,1)+X(10)*A(1,2))
      SP(1)= 2./SQRT(1.-A(1,3)**2)
      DUB(7,5)= X(9)*SP(1)
      DUB(8,5)=-X(10)*SP(1)
      DUB(9,5)= X(7)*SP(1)
      DUB(10,5)=-X(8)*SP(1)
      SP(1)= 2./(A(3,3)**2+A(2,3)**2)
      DUB(7,6)=SP(1)*(X(8)*A(3,3)-X(7)*A(2,3))
      DUB(8,6)=SP(1)*(X(7)*A(3,3)+X(8)*A(2,3))
      DUB(9,6)=SP(1)*(X(10)*A(3,3)+X(9)*A(2,3))
      DUB(10,6)=SP(1)*(X(9)*A(3,3)-X(10)*A(2,3))
      GO TO 200
120 SP(1)= X(1)*X(7) + ZO(1)*X(10) - X(3)*X(9)
      SP(2)= X(1)*X(8) + ZO(1)*X(9) + X(3)*X(10)
      SP(3)= X(1)*X(9) - ZO(1)*X(8) + X(3)*X(7)
      SP(4)= X(1)*X(10) - ZO(1)*X(7) - X(3)*X(8)
      SP(5)= ST(4)/(CT(4)*VO(1))
      SP(6)= 2./VO(1)
      DUB(1,5)= (CT(4)*A(2,1)-SP(5)*(X(1) -A(2,1)*VO(14)))/VO(1)
      DUB(2,5)= (CT(4)*A(2,2)-SP(5)*(ZO(1)-A(2,2)*VO(14)))/VO(1)
      DUB(3,5)= (CT(4)*A(2,3)-SP(5)*(X(3) -A(2,3)*VO(14)))/VO(1)
      OUTP0760
      OUTP0770
      OUTP0780
      OUTP0790
      OUTP0800
      OUTP0810
      OUTP0820
      OUTP0830
      OUTP0840
      OUTP0850
      OUTP0860
      OUTP0870
      OUTP0880
      OUTP0890
      OUTP0900
      OUTP0910
      OUTP0920
      OUTP0930
      OUTP0940
      OUTP0950
      OUTP0960
      OUTP0970
      OUTP0980
      OUTP0990
      OUTP1000
      OUTP1010
      OUTP1020
      OUTP1030
      OUTP1040
      OUTP1050
      OUTP1060
      OUTP1070
      OUTP1080
      OUTP1090
      OUTP1100
      OUTP1110
      OUTP1120
      OUTP1130
      OUTP1140
      OUTP1150
      OUTP1160
      OUTP1170
      OUTP1180
      OUTP1190
      OUTP1200
      OUTP1210
      OUTP1220
      OUTP1230
      OUTP1240
      OUTP1250
      OUTP1260
      OUTP1270
      OUTP1280
      OUTP1290
      OUTP1300
      OUTP1310
      OUTP1320
      OUTP1330
      OUTP1340
      OUTP1350

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DUB(4,5) = -Z0(8)*DUB(2,5)                                OUTP1360
DUB(5,5) = -DUB(4,5)*R*TPH                                OUTP1370
DUB(7,5) = (-CT(4)*SP(4)-SP(5)*(V0(13)*SP(1)+V0(15)*SP(3)))*SP(6)  OUTP1380
DUB(8,5) = (CT(4)*SP(3)-SP(5)*(V0(13)*SP(2)+V0(15)*SP(4)))*SP(6)  OUTP1390
DUB(9,5) = (CT(4)*SP(2)+SP(5)*(V0(13)*SP(3)-V0(15)*SP(1)))*SP(6)  OUTP1400
DUB(10,5) = (-CT(4)*SP(1)+SP(5)*(V0(13)*SP(4)-V0(15)*SP(2)))*SP(6) OUTP1410
SP(6) = Z0(3)**2                                           OUTP1420
DUB(1,6) = (V0(13)*A(3,1)-V0(15)*A(1,1))/SP(6)           OUTP1430
DUB(2,6) = (V0(13)*A(3,2)-V0(15)*A(1,2))/SP(6)           OUTP1440
DUB(3,6) = (V0(13)*A(3,3)-V0(15)*A(1,3))/SP(6)           OUTP1450
DUB(4,6) = -Z0(8)*DUB(2,6)                                OUTP1460
DUB(5,6) = -DUB(4,6)*R*TPH                                OUTP1470
SP(6) = 2./SP(6)                                           OUTP1480
DUB(7,6) = (V0(13)*SP(3)-V0(15)*SP(1))*SP(6)            OUTP1490
DUB(8,6) = (V0(13)*SP(4)-V0(15)*SP(2))*SP(6)            OUTP1500
DUB(9,6) = (V0(13)*SP(1)+V0(15)*SP(3))*SP(6)            OUTP1510
DUB(10,6) = (V0(13)*SP(2)+V0(15)*SP(4))*SP(6)           OUTP1520
SP(1) = CT(3)*ST(4)*CT(1)+ST(3)*ST(1)*Z0(5)/CT(1)       OUTP1530
SP(2) = ST(3)*CT(1)*A(2,2)*ST(2)+A(2,1)*CT(2)           OUTP1540
SP(3) = CT(3)*CT(4)*ST(1)                                  OUTP1550
DUB(1,4) = (SP(1)*DUB(1,2)+SP(2)*DUB(1,3)+SP(3)*DUB(1,5))/Z0(9)  OUTP1560
DUB(2,4) = (SP(1)*DUB(2,2)+SP(2)*DUB(2,3)+SP(3)*DUB(2,5))/Z0(9)  OUTP1570
DUB(3,4) = (SP(1)*DUB(3,2)+SP(2)*DUB(3,3)+SP(3)*DUB(3,5))/Z0(9)  OUTP1580
DUB(4,4) = (SP(1)*DUB(4,2)+SP(2)*DUB(4,3)+SP(3)*DUB(4,5))/Z0(9)  OUTP1590
DUB(5,4) = (SP(1)*DUB(5,2)+SP(2)*DUB(5,3)+SP(3)*DUB(5,5))/Z0(9)  OUTP1600
SP(6) = ST(3)*CT(1)                                        OUTP1610
SP(5) = SP(6)*CT(2)                                       OUTP1620
SP(6) = SP(6)*ST(2)                                        OUTP1630
DUB(7,4) = (SP(3)*DUB(7,5)+2.*(CT(3)*X(8)-SP(5)*X(7)-SP(6)*X(10)  OUTP1640
X))/Z0(9)                                                    OUTP1650
DUB(8,4) = (SP(3)*DUB(8,5)+2.*(CT(3)*X(7)+SP(5)*X(8)+SP(6)*X(9)  OUTP1660
X))/Z0(9)                                                    OUTP1670
DUB(9,4) = (SP(3)*DUB(9,5)+2.*(CT(3)*X(10)-SP(5)*X(9)+SP(6)*X(8)  OUTP1680
X))/Z0(9)                                                    OUTP1690
DUB(10,4) = (SP(3)*DUB(10,5)+2.*(CT(3)*X(9)+SP(5)*X(10)-SP(6)*X(7)  OUTP1700
X))/Z0(9)                                                    OUTP1710
200 DO 205 I=1,3                                           OUTP1720
    DO 205 J=1,NSTX                                         OUTP1730
        DUB(J,I+6)=0.                                       OUTP1740
        DUB(J,I+9)=P(I+3,J)                                   OUTP1750
        DUB(J,I+12)=0.                                       OUTP1760
        DO 202 K=1,5                                         OUTP1770
            DUM=P(K,J)                                       OUTP1780
            IF(K-J) 202,202,201                                OUTP1790
201 DUM=P(J,K)                                               OUTP1800
202 DUB(J,I+6)=DUB(J,I+6)+DUB(K,I)*DUM                       OUTP1810
        DO 204 K=1,10                                        OUTP1820
            DUM=P(K,J)                                       OUTP1830
            IF(K-J) 204,204,203                                OUTP1840
203 DUM=P(J,K)                                               OUTP1850
204 DUB(J,I+12)=DUB(J,I+12)+DUB(K,I+3)*DUM                 OUTP1860
205 CONTINUE                                                OUTP1870
        DO 218 I=1,3                                         OUTP1880
        DO 208 J=I,3                                         OUTP1890
            P(J+1,I)=0.                                       OUTP1900
            P(J+7,I)=0.                                       OUTP1910
            DO 206 K=1,5                                       OUTP1920
206 P(J+1,I)=P(J+1,I)+DUB(K,I+6)*DUB(K,J)                 OUTP1930
            DO 207 K=1,10                                       OUTP1940
207 P(J+7,I)=P(J+7,I)+DUB(K,I+6)*DUB(K,J+3)               OUTP1950

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208	CONTINUE	OUTPUT1960
	DO 212 J=1,3	OUTPUT1970
	P(J+7,I+6)=0.	OUTPUT1980
	P(J+4,I+3)=P(I+3,J+3)	OUTPUT1990
	DO 212 K=1,10	OUTPUT2000
212	P(J+7,I+6)=P(J+7,I+6)+DUB(K,I+12)*DUB(K,J+3)	OUTPUT2010
	DO 214 J=1,3	OUTPUT2020
	P(K+9,I)= DUB(J+3,I+6)	OUTPUT2030
214	P(K+7,I+3)= DUB(I+3,J+12)	OUTPUT2040
	DO 216 J=1,NSTC	OUTPUT2050
	P(J+10,I)= DUB(J+10,I+7)	OUTPUT2060
	P(J+10,I+6)= DUB(J+10,I+12)	OUTPUT2070
216	P(J+10,I+3)= P(I+3,J+10)	OUTPUT2080
218	CONTINUE	OUTPUT2090
	DO 210 J=1,NSTC	OUTPUT2100
210	P(J+10,I+9)= P(I+10,J+10)	OUTPUT2110
	LT=1	OUTPUT2120
	MT=NSTX-1	OUTPUT2130
	NT=9	OUTPUT2140
	GO TO 34	OUTPUT2150
30	LT=0	OUTPUT2160
	MT=NSTX	OUTPUT2170
	NT=10	OUTPUT2180
	DO 32 I=1,NSTX	OUTPUT2190
	K=I+1	OUTPUT2200
	DO 32 J=K,NSTX	OUTPUT2210
32	P(J,I)=P(I,J)	OUTPUT2220
34	IF(NPC(1)) 35,130,35	OUTPUT2230
130	IF(NPC(4)-1) 35,132,35	OUTPUT2240
132	IF(NPC(3)) 134,134,138	OUTPUT2250
134	DO 136 I=1,10	OUTPUT2260
136	VO(I)= DZ(I)	OUTPUT2270
	GO TO 146	OUTPUT2280
138	DO 144 I=1,3	OUTPUT2290
	VO(I)=0.	OUTPUT2300
	VO(I+6)=0.	OUTPUT2310
	DO 140 J=1,5	OUTPUT2320
140	VO(I)=VO(I)+ DUB(J,I)*DZ(J)	OUTPUT2330
	VO(I+3)= DZ(I+3)	OUTPUT2340
	DO 142 J=1,10	OUTPUT2350
142	VO(I+6)=VO(I+6)+ DUB(J,I+3)*DZ(J)	OUTPUT2360
144	CONTINUE	OUTPUT2370
146	IF(NSTC) 148,147,148	OUTPUT2380
147	WRITE(OUT,1028) (I,VO(I),I=1,NT)	OUTPUT2390
	GO TO 35	OUTPUT2400
148	DO 150 I=1,NSTC	OUTPUT2410
150	VO(I+NT)= DZ(I+10)	OUTPUT2420
	WRITE(OUT,1028) (I,VO(I),I=1,NT),(NC(I),VO(I+NT),I=1,NSTC)	OUTPUT2430
1028	FORMAT(6(3H Z(I3,1H)E13.6))	OUTPUT2440
35	DO 40 I=1,MT	OUTPUT2450
	K=I+LT	OUTPUT2460
	IF(P(K,I)) 36,38,38	OUTPUT2470
36	WRITE(OUT,1030) I,I,I,P(K,I)	OUTPUT2480
1030	FORMAT(26H ****NEGATIVE VARIANCE ON I3,31HRD TRANSFORMED VARIABLE,	OUTPUT2490
	A SIGMA(I3,1H,I3,4H) = E15.8)	OUTPUT2500
	GO TO 40	OUTPUT2510
38	VO(I)=SQRT(P(K,I))	OUTPUT2520
40	CONTINUE	OUTPUT2530
	IF(NSTC.GT.0) GO TO 50	OUTPUT2540
	WRITE(OUT,1032) (I,VO(I),I=1,NT)	OUTPUT2550

GO TO 52	OUTP2560
50 DO 39 I=1,NSTC	OUTP2570
K=I+NT	OUTP2580
39 ZO(I)=VO(K)	OUTP2590
WRITE(OUT,1032) (I,VO(I),I=1,NT),(NC(I),ZO(I) ,I=1,NSTC)	OUTP2600
1032 FORMAT(6(3H S(I3,1H)E13.6))	OUTP2610
52 IF(NPC(7).NE.ICOUNT) RETURN	OUTP2620
IF(NPC(6)-1) 99,41,42	OUTP2630
41 IF(DCOMP.GT.0) RETURN	OUTP2640
42 WRITE(OUT,1033)	OUTP2650
1033 FORMAT(41H COVARIANCE MATRIX P (UPPER TRIANGLE ONLY)	OUTP2660
DO 43 I=1,MT	OUTP2670
43 WRITE(OUT,1034) (P(I+LT,J),J=1,I)	OUTP2680
1034 FORMAT(X,12E10,3)	OUTP2690
IF(NPU) 44,44,250	OUTP2700
44 IF(NPV) 46,46,300	OUTP2710
46 CONTINUE	OUTP2720
99 RETURN	OUTP2730
250 IF(LT) 256,252,256	OUTP2740
252 DO 254 I=1,NSTX	OUTP2750
DO 254 J=1,NPU	OUTP2760
254 DUB(I,J+6)=CUZ(I,J)	OUTP2770
GO TO 266	OUTP2780
256 DO 262 I=1,3	OUTP2790
DO 262 J=1,NPU	OUTP2800
DUB(I,J+6)=0.	OUTP2810
DUB(I+6,J+6)=0.	OUTP2820
DO 258 K=1,5	OUTP2830
258 DUB(I,J+6)=DUB(I,J+6)+DUB(K,I)*CUZ(K,J)	OUTP2840
DO 260 K=1,10	OUTP2850
260 DUB(I+6,J+6)=DUB(I+6,J+6)+DUB(K,I+3)*CUZ(K,J)	OUTP2860
262 DUB(I+3,J+6)=CUZ(I+3,J)	OUTP2870
DO 264 I=1,NSTC	OUTP2880
DO 264 J=1,NPU	OUTP2890
264 DUB(I+9,J+6)=CUZ(I+10,J)	OUTP2900
266 WRITE(OUT,1035)	OUTP2910
1035 FORMAT(34H CORRELATION MATRIX (CUZ)TRANSPPOSE)	OUTP2920
MT=NSTX-LT	OUTP2930
DO 268 J=1,NPU	OUTP2940
268 WRITE(OUT,1034) (DUB(I,J+6),I=1,MT)	OUTP2950
GO TO 44	OUTP2960
300 IF(LT) 306,302,306	OUTP2970
302 DO 304 I=1,NSTX	OUTP2980
DO 304 J=1,NPV	OUTP2990
304 DUB(I,J+6)=CVZ(I,J)	OUTP3000
GO TO 316	OUTP3010
306 DO 312 I=1,3	OUTP3020
DO 312 J=1,NPV	OUTP3030
DUB(I,J+6)=0.	OUTP3040
DUB(I+6,J+6)=0.	OUTP3050
DO 308 K=1,5	OUTP3060
308 DUB(I,J+6)=DUB(I,J+6)+DUB(K,I)*CVZ(K,J)	OUTP3070
DO 310 K=1,10	OUTP3080
310 DUB(I+6,J+6)=DUB(I+6,J+6)+DUB(K,I+3)*CVZ(K,J)	OUTP3090
312 DUB(I+3,J+6)=CVZ(I+3,J)	OUTP3100
DO 314 I=1,NSTC	OUTP3110
DO 314 J=1,NPV	OUTP3120
314 DUB(I+9,J+6)=CVZ(I+10,J)	OUTP3130
316 WRITE(OUT,1036)	OUTP3140
1036 FORMAT(34H CORRELATION MATRIX (CVZ)TRANSPPOSE)	OUTP3150

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MT=NSTX-LT
DO 318 J=1, NPV
318 WRITE(OUT,1034) (OUB(I,J+6), I=1, MT)
GO TO 46
END
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OUTP3160
OUTP3170
OUTP3180
OUTP3190
OUTP3200
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SUBROUTINE PRESET
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),      COMM0010
*   NALL,LRK                                                         COMM0020
COMMON /MOD1/ ALPH,AS ,BETA,CA(6),CALP      ,CBET      ,CETA      ,      COMM0030
1  CF(3),JCS ,CXZI      ,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH ,      COMM0040
2  DRDP,DWDH(2),ETA,H0,N4(3)      ,N5(3)      ,N6(3)      ,PAXP(3,30),      COMM0050
3  PE      ,ROE      ,ROEC      ,ROEM      ,SALP      ,SBET      ,      COMM0060
4  SETA      ,SREF      ,SXZI      ,TAU      ,TMAS(20) ,TONE      ,      COMM0070
5  TTWO      ,TUW(20) ,TVW(20) ,UW      ,VA(5)      ,VB(5)      ,      COMM0080
6  VW      ,XIND1      ,XIND2      ,XLREF      ,XM      ,      COMM0090
7  XMAS(20) ,XNU      ,XQ      ,XQSM      ,XRE      ,XTEMP      ,      COMM0100
8  XUW(20) ,XVW(20) ,XZI      ,YMAS      ,YMASM      ,      COMM0110
COMMON /TWICE/ A(3,3)      ,CPH      ,CT(5)      ,SP(10) ,ST(5)      COMM0120
1  ,TPH      ,VO(20) ,ZO(20) ,AG(3)      ,AMDOT(3) ,APDOT(4)      COMM0130
2  ,B(8)      ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)      COMM0140
3  ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3)      ,HI(2)      COMM0150
4  ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2      COMM0160
5  ,K1 ,NNN ,NPTS ,PAR(6) ,PDOOT(3) ,PMDOT(3) ,RES(6)      COMM0170
6  ,RO      ,SPD(5) ,SPH      ,TRAN(3,3),XX(50)      COMM0180
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3)      ,AM(3)      ,AP(4)      ,AX(40) ,AY(40)      COMM0210
1  ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD      ,CPHDT(5) ,CUZ(30,5)      COMM0220
2  ,CVZ(30,5) ,D(5)      ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)      COMM0230
3  ,DET      ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET      COMM0240
4  ,FLOS      ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST      COMM0250
5  ,K      ,KAR ,KC(3) ,KDAP      ,KDATA      ,KDATAS      ,KG,KI,KK      COMM0260
6  ,KN ,KOB ,KPROP,KS,KSM,KSS,L      ,LC(3)      ,LCS(3) ,LS      ,LT      COMM0270
7  ,L1 ,M      ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT      COMM0280
8  ,MTP(40) ,MTYP      ,MTYPS      ,N ,NC(30) ,NCOUNT ,NPC(15)      COMM0290
9  ,NPU ,NPV ,NS(9) ,NSS(5) ,NST      ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)      COMM0300
A  ,NB(3)      ,N9(3)      ,N10(3) ,N11(3) ,OMEGA      ,P(30,30)      COMM0310
B  ,PA(3)      ,PM(3)      ,R      ,REO      ,RERP2      COMM0320
C  ,RPC      ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)      COMM0330
D  ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL      COMM0340
E  ,TFIT(9) ,TIME      ,TIMES      ,TO      ,TP(40) ,TQ(40)      COMM0350
F  ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)      COMM0360
G  ,TZERO      ,XJ2      ,XMU      ,XMUJ      ,XP(3)      ,XXCG(20)      COMM0370
H  ,XYCG(20) ,XZCG(20)      COMM0380
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON /ABET,AGAM,AMO,AP0,AR,ASU,ATM(4),HB(23),ISV,JK      COMM0410
A  ,PB(23),RL(23),TMB(23)      COMM0420
COMMON /EXTRA / GO
NDIMT = 160
NDIMZ = 30
NDIMV = 5
NDIMU = 5
DO 12 I=1,NDIMZ
DO 4 J=1,NDIMZ
4 P(I,J)=0.
DO 6 J=1,NDIMU
6 CUZ(I,J) = 0.
DO 8 J=1,NDIMV
8 CVZ(I,J) = 0.
DO 10 J=1,10
10 PH(J,I)=0.
12 DZ(I) = 0.
DO 16 I=1,NDIMU
PRES0010
PRES0020
PRES0030
PRES0040
PRES0050
PRES0060
PRES0070
PRES0080
PRES0090
PRES0100
PRES0110
PRES0120
PRES0130
PRES0140
PRES0150

```

```
16 D(I)=0.  
DO 18 I=1,NDIMV  
18 S(I)=0.  
DO 26 I=1,NDIMT  
26 C(I) = 0.  
C(21) = 1.  
C(36) = 1.  
C(40) = 1.  
C(44) = 1.  
C(61) = 1.  
C(65) = 1.  
C(69) = 1.  
C(76) = 1.  
C(77) = 1.  
C(78) = 1.  
C(91) = 1.  
C(92) = 1.  
C(93) = 1.  
C(106) = 1.  
C(107) = 1.  
C(108) = 1.  
C(121) = 1.  
C(122) = 1.  
C(123) = 1.  
C(136) = 1.  
C(137) = 1.  
C(138) = 1.  
CONRD = .0174532925  
XJ2 = 1.082645E-3  
XMU = 3.985992E+14  
OMEGA = .7292116E-4  
RPO = 6356173.  
REO = 6378163.  
NCOUNT = 0  
ICOUNT = 1  
KDATAS = -1  
NST = 0  
NSTX = 0  
NSTC = 0  
NSTA = 0  
NPU = 0  
NPV = 0  
FIT = 1  
PQR = 2  
SCRACH = 3  
STATE = 4  
IN = 5  
OUT = 6  
ISV = 1  
N4(1) = 0  
N4(2) = 1  
N4(3) = 0  
N5(1) = 0  
N5(2) = 1  
N5(3) = 0  
N6(1) = 0  
N6(2) = 1  
N6(3) = 0  
N8(1) = 0  
N8(2) = 1
```

```
PRES0160  
PRES0170  
PRES0180  
PRES0190  
PRES0200  
PRES0210  
PRES0220  
PRES0230  
PRES0240  
PRES0250  
PRES0260  
PRES0270  
PRES0280  
PRES0290  
PRES0300  
PRES0310  
PRES0320  
PRES0330  
PRES0340  
PRES0350  
PRES0360  
PRES0370  
PRES0380  
PRES0390  
PRES0400  
PRES0410  
PRES0420  
PRES0430  
PRES0440  
PRES0450  
PRES0460  
PRES0470  
PRES0480  
PRES0490  
PRES0500  
PRES0510  
PRES0520  
PRES0530  
PRES0540  
PRES0550  
PRES0560  
PRES0570  
PRES0580  
PRES0590  
PRES0600  
PRES0610  
PRES0620  
PRES0630  
PRES0640  
PRES0650  
PRES0660  
PRES0670  
PRES0680  
PRES0690  
PRES0700  
PRES0710  
PRES0720  
PRES0730  
PRES0740  
PRES0750
```



```
N8(3) = 0
N9(1) = 0
N9(2) = 1
N9(3) = 0
N10(1) = 0
N10(2) = 1
N10(3) = 0
N11(1) = 0
N11(2) = 1
N11(3) = 0
DO 200 I=1,9
DFIT(I) = 1.E10
DTI(I) = 1.E10
200 NTR(I) = 0
TIME = 1.E+10
KG = 2
AMO = 28.9644
APO = 1.013250E5
AR = 8.31432E3
AGAM = 1.4
ABET = 1.458E-6
ASU= 110.4
GO=9.80665
CALL INDAT
CALL SETUP
99 RETURN
END
```

```
PRES0760
PRES0770
PRES0780
PRES0790
PRES0800
PRES0810
PRES0820
PRES0830
PRES0840
PRES0850
PRES0860
PRES0870
PRES0880
PRES0890
PRES0900
PRES0910
PRES0920
PRES0930
PRES0940
PRES0950
PRES0960
PRES0970
PRES0980
PRES0990
PRES1000
PRES1010
PRES1020
```

```

SUBROUTINE PROP
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),      COMM0010
*   NALL,LRK                                                         COMM0020
COMMON /MOD1/ ALPH,AS ,BETA,CA(6),CALP      ,CBET      ,CETA      ,      COMM0030
1  CF(3),JCS ,CXZI      ,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH ,      COMM0040
2  DRDP,DWDH(2),ETA,HO,N4(3)      ,N5(3)      ,N6(3)      ,PAXP(3,30),      COMM0050
3  PE      ,ROE      ,ROEC      ,ROEM      ,SALP      ,SBET      ,      COMM0060
4  SETA      ,SREF      ,SXZI      ,TAU      ,TMAS(20) ,TONE      ,      COMM0070
5  TTWO      ,TUW(20) ,TVW(20) ,UW      ,VA(5)      ,VB(5)      ,      COMM0080
6  VW      ,XIND1      ,XIND2      ,XLREF      ,XM      ,      COMM0090
7  XMAS(20) ,XNU      ,XG      ,XGSM      ,XRE      ,XTEMP      ,      COMM0100
8  XUW(20) ,XVW(20) ,XZI      ,YMAS      ,YMASM      ,      COMM0110
COMMON /TWICE/ A(3,3)      ,CPH      ,CT(5)      ,SP(10)      ,ST(5)      COMM0120
1  ,TPH      ,VO(20)      ,ZO(20)      ,AG(3)      ,AMDOT(3) ,APDOT(4)      COMM0130
2  ,B(8)      ,CGM(3)      ,DFM(3)      ,DTRAN(3,3),DUD(10,1),DUE(4)      COMM0140
3  ,DUF(4)      ,F1(3,40) ,F2(3,5)      ,F3(4,40) ,GG(3)      ,HI(2)      COMM0150
4  ,IDN ,II      ,IP ,IPC      ,JJ ,JN      ,KA ,KD(3),KDUM ,KG2      COMM0160
5  ,K1 ,NNN ,NPTS      ,PAR(6)      ,PDOT(3) ,PMDOT(3) ,RES(6)      COMM0170
6  ,RO      ,SPD(5)      ,SPH      ,TRAN(3,3),XX(50)      COMM0180
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3)      ,AM(3)      ,AP(4)      ,AX(40)      ,AY(40)      COMM0210
1  ,AZ(40) ,C(160)      ,CCAPH(5) ,CONRD      ,CPHDT(5) ,CUZ(30,5)      COMM0220
2  ,CVZ(30,5),D(5)      ,DAT(3,40) ,DATA(3)      ,DATAS(3) ,DATC(3)      COMM0230
3  ,DET      ,DFIT(9)      ,DTF(9)      ,DTI(9)      ,DZ(30)      ,ET      COMM0240
4  ,FLOS      ,G(3,30)      ,H(3,5)      ,I      ,ICOUNT ,J      ,JNBR ,JNBRS ,JST      COMM0250
5  ,K      ,KAR      ,KC(3)      ,KDAP      ,KDATA      ,KDATAS      ,KG,KI,KK      COMM0260
6  ,KN ,KOB ,KPROP,KS ,KSM ,KSS,L      ,LC(3)      ,LCS(3)      ,LS      ,LT      COMM0270
7  ,L1 ,M      ,MC(5)      ,MCC(5)      ,MO(5)      ,MR(3,9)      ,MT      COMM0280
8  ,MTP(40) ,MTYP      ,MTYPS      ,N      ,NC(30) ,NCOUNT ,NPC(15)      COMM0290
9  ,NPU ,NPV      ,NS(9)      ,NSS(5)      ,NST      ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)      COMM0300
A  ,N8(3)      ,N9(3)      ,N10(3)      ,N11(3)      ,OMEGA      ,P(30,30)      COMM0310
B  ,PA(3)      ,PM(3)      ,R      ,REO      ,RERP2      ,      COMM0320
C  ,RPO      ,ROT(5)      ,S(5)      ,SCAPH(5) ,SI(3)      ,SIG(3,40)      COMM0330
D  ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL      COMM0340
E  ,TFIT(9) ,TIME      ,TIMES      ,TO      ,TP(40)      ,TQ(40)      COMM0350
F  ,TR(40) ,TT(40)      ,TXCG(20) ,TYCG(20) ,TYM(40)      ,TZCG(20)      COMM0360
G  ,TZERO      ,XJ2      ,XMU      ,XMUJ      ,XP(3)      ,XXCG(20)      COMM0370
H  ,XYCG(20) ,XZCG(20)      ,      ,      ,      ,      ,      COMM0380
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON /ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A  ,PB(23),RL(23),TMB(23)
COMMON /EXTRA / GO
-----CALCULATE EQ.(55B) -----
DO 4 I=1,10
DO 4 J=1,NSTX
SUM = 0.
L = J+1
DO 2 K=1,J
2 SUM = SUM + PH(I,K)*P(K,J)
IF(L.GT.NSTX) GO TO 4
DO 3 K=L,NSTX
3 SUM = SUM + PH(I,K)*P(J,K)
4 DUB(J,I) = SUM
DO 10 I=1,10
DO 8 J=1,10
SUM = 0.
DO 6 K=1,NSTX
PROP0010
PROP0020
PROP0030
PROP0040
PROP0050
PROP0060
PROP0070
PROP0080
PROP0090
PROP0100
PROP0110
PROP0120
PROP0130
PROP0140
PROP0150

```

6	SUM = SUM + DUB(K,I)*PH(J,K)	PROP0160
8	P(I,J) = SUM	PROP0170
10	CONTINUE	PROP0180
	IF(NSTX=10) 12,16,12	PROP0190
12	DO 14 I=11,NSTX	PROP0200
	DO 14 J=1,10	PROP0210
14	P(J,I) = DUB(I,J)	PROP0220
	IF(NPU) 38,38,60	PROP0230
60	DO 64 I=1,10	PROP0240
	DO 64 K=11,NSTX	PROP0250
	SUM = 0.	PROP0260
	DO 62 J=1,NPU	PROP0270
	II=J+NSTX	PROP0280
62	SUM = SUM + PH(I,II)*CUZ(K,J)	PROP0290
64	P(I,K) = P(I,K) + SUM	PROP0300
	GO TO 20	PROP0310
16	IF(NPU,LE.0) GO TO 38	PROP0320
	C-----CALCULATE EQ.(55C) -----	PROP0330
20	DO 25 J=1,NPU	PROP0340
	DO 24 I=1,10	PROP0350
	SUM = 0.	PROP0360
	DO 22 K=1,NSTX	PROP0370
	SUM = SUM + PH(I,K)*CUZ(K,J)	PROP0380
22	CONTINUE	PROP0390
	DUB(I,J) = SUM	PROP0400
24	DUB(I,15) = SUM + PH(I,J+NSTX)*D(J)	PROP0410
	DO 25 I=1,10	PROP0420
25	CUZ(I,J) = DUB(I,15)	PROP0430
26	CONTINUE	PROP0440
30	DO 34 I=1,10	PROP0450
	DO 34 J=1,10	PROP0460
	SUM = 0.	PROP0470
	DO 32 K=1,NPU	PROP0480
32	SUM = SUM + CUZ(I,K)*PH(J,K+NSTX) + PH(I,K+NSTX)*DUB(J,K)	PROP0490
34	P(I,J) = P(I,J) + SUM	PROP0500
36	CONTINUE	PROP0510
38	IF(NPV) 99,99,40	PROP0520
	C-----CALCULATE EQ.(55D) -----	PROP0530
40	DO 48 J=1,NPV	PROP0540
	DO 44 I=1,10	PROP0550
	SUM = 0.	PROP0560
	DO 42 K=1,NSTX	PROP0570
42	SUM = SUM + PH(I,K)*CVZ(K,J)	PROP0580
44	DUB(I,1) = SUM	PROP0590
	DO 46 I=1,10	PROP0600
46	CVZ(I,J) = DUB(I,1)	PROP0610
48	CONTINUE	PROP0620
99	IF(NPC(4).EQ.0) GO TO 75	PROP0630
	IF(NPC(1).EQ.2) GO TO 75	PROP0640
	C-----CALCULATE EQ.(55A) -----	PROP0650
	DO 72 I=1,10	PROP0660
	SUM = 0.	PROP0670
	DO 70 J=1,NSTX	PROP0680
70	SUM = SUM + PH(I,J)*DZ(J)	PROP0690
72	DUB(I,1) = SUM	PROP0700
	DO 74 I=1,10	PROP0710
74	DZ(I) = DUB(I,1)	PROP0720
75	CONTINUE	PROP0730
	ENTRY IDENT	PROP0740
	K = NSTX+NPU	PROP0750

```
DO 52 I=1,10
DO 50 J=1,K
50 PH(I,J)=0.
52 PH(I,I)=1.
RETURN
END
```

```
PROP0760
PROP0770
PROP0780
PROP0790
PROP0800
PROP0810
```

	SUBROUTINE RKUTTA	RKUT0010
	DIMENSION PR(3)	RKUT0020
	DIMENSION F1(410),F2(410),F3(410),DELY(410)	RKUT0030
	COMMON /INTGRL/ P,T,TP,Y(410),DY(410),N,L	RKUT0040
	DATA PR /,5, .25, .5/	RKUT0050
	GO TO (1,2,2,4),L	RKUT0060
	1 IF(IG.EQ.0) GO TO 30	RKUT0070
	DO 10 I = 1,N	RKUT0080
10	F3(I)=Y(I)	RKUT0090
	L = 2	RKUT0100
	RETURN	RKUT0110
	2 DT = P	RKUT0120
	J = 1	RKUT0130
	T2 = TP - T	RKUT0140
	RT2=T2/P	RKUT0150
	IF(RT2-.99999)22,26,29	RKUT0160
22	IF(RT2.GT..00001) GO TO 26	RKUT0170
20	L=3	RKUT0180
	RETURN	RKUT0190
26	DT=T2	RKUT0200
29	IG=0	RKUT0210
30	GO TO(31,32,33,34),J	RKUT0220
31	T = T+PR(1)*DT	RKUT0230
	DO 310 I=1,N	RKUT0240
	F1(I)=DY(I)*DT	RKUT0250
310	Y(I)=F3(I)+PR(1)*F1(I)	RKUT0260
	J = J+1	RKUT0270
	GO TO 38	RKUT0280
33	T = T+PR(1)*DT	RKUT0290
32	T2=DT/PR(1)	RKUT0300
	DO 320 I=1,N	RKUT0310
	RT2=DY(I)*T2	RKUT0320
	F1(I)=F1(I)+RT2	RKUT0330
320	Y(I)=F3(I)+PR(J)*RT2	RKUT0340
35	J = J + 1	RKUT0350
	RETURN	RKUT0360
34	DO 340 I=1,N	RKUT0370
340	F1(I)=F1(I)+DY(I)*DT	RKUT0380
37	DO 39 I = 1,N	RKUT0390
	DELY(I)=F1(I)/6.+DELY(I)	RKUT0400
39	Y(I)=F2(I)+DELY(I)	RKUT0410
	IG = 1	RKUT0420
	RETURN	RKUT0430
	4 DT=P	RKUT0440
	IG = 1	RKUT0450
	J = 1	RKUT0460
	DO 40 I = 1,N	RKUT0470
	DELY(I) = 0.D0	RKUT0480
40	F2(I)=Y(I)	RKUT0490
38	L = 1	RKUT0500
	RETURN	RKUT0510
	END	

```

SUBROUTINE SETUP
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),      COMM0010
*   NALL,LRK                                                         COMM0020
COMMON /MOD1/ ALPH,AS ,BETA,CA(6),CALP ,CBET ,CETA ,              COMM0030
1  CF(3),JCS ,CXZI ,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH ,      COMM0040
2  DRDP,DWDH(2),ETA,HO,N4(3) ,N5(3) ,N6(3) ,PAXP(3,30),          COMM0050
3  PE ,ROE ,ROEC ,ROEM ,SALP ,SBET ,                      COMM0060
4  SETA ,SREF ,SXZI ,TAU ,TMAS(20) ,TONE ,                  COMM0070
5  TIWO ,TUV(20) ,TVW(20) ,UW ,VA(5) ,VB(5) ,                COMM0080
6  VW ,XIND1 ,XIND2 ,XLREF ,XM ,                          COMM0090
7  XMAS(20) ,XNU ,XQ ,XGSM ,XRE ,XTEMP ,                    COMM0100
8  XUW(20) ,XVW(20) ,XZI ,YMAS ,YMASM                      COMM0110
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)              COMM0120
1  ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)            COMM0130
2  ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)         COMM0140
3  ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)        COMM0150
4  ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2             COMM0160
5  ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)         COMM0170
6  ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)                        COMM0180
DIMENSION DUB(30,15)                                           COMM0190
EQUIVALENCE (AG(1),DUB(1,1))                                   COMM0200
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)            COMM0210
1  ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)      COMM0220
2  ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)       COMM0230
3  ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET                 COMM0240
4  ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST     COMM0250
5  ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK              COMM0260
6  ,KN ,KOB ,KPROP,KS ,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT       COMM0270
7  ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT                 COMM0280
8  ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)        COMM0290
9  ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9) COMM0300
A  ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)             COMM0310
B  ,PA(3) ,PM(3) ,R ,REO ,RERP2                               COMM0320
C  ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)            COMM0330
D  ,SIGM(3) ,SIGMS(3) ,SPHOT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL  COMM0340
E  ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)                 COMM0350
F  ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)   COMM0360
G  ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)                  COMM0370
H  ,XYCG(20) ,XZCG(20)                                       COMM0380
INTEGER OUT,FIT,STATE,SCRACH,PQR                               COMM0390
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR                   COMM0400
COMMON /ATMCON /ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK COMM0410
A  ,PB(23),RL(23),TMB(23)                                     COMM0420
COMMON /EXTRA / GO                                             COMM0430
DIMENSION DUA(10,10)                                          SETP0010
WRITE(OUT,1000)                                               SETP0020
1000 FORMAT(1H1,27H CONTROLS ARE SPECIFIED FOR)              SETP0030
IF(NPC(1)-1) 10,11,12                                         SETP0040
10 WRITE(OUT,1001) TO,TFINAL                                   SETP0050
1001 FORMAT(5X,28H*FILTERING RUN FROM TIME TO=F9.4,11H TO TFINAL=F9.4) SETP0060
GO TO 13                                                        SETP0070
11 WRITE(OUT,1002) TO,TFINAL                                   SETP0080
1002 FORMAT(5X,32H*DETERMINISTIC RUN FROM TIME TO=F9.4,11H TO TFINAL=F9.4) SETP0090
1.4)                                                           SETP0100
GO TO 24                                                       SETP0110
12 WRITE(OUT,1003) TO,TFINAL                                   SETP0120
1003 FORMAT(5X,33H*ERROR ANALYSIS RUN FROM TIME TO=F9.4,11H TO TFINAL=F9.4) SETP0130
19.4)                                                         SETP0140
GO TO 21                                                       SETP0150

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13 IF(NPC(4))14,14,15 SETP0160
14 WRITE(OUT,1004) SETP0170
1004 FORMAT(5X,15H*UPDATED REFERENCE) SETP0180
GO TO 18 SETP0190
15 WRITE(OUT,1005) SETP0200
1005 FORMAT(5X,21H*NONUPDATED REFERENCE) SETP0210
16 IF(NPC(8)-1) 17,18,19 SETP0220
17 WRITE(OUT,1006) SETP0230
1006 FORMAT(5X,57H*SMOOTH DETERMINISTICALLY, NO RESIDUALS NOR LOSS FUNCSETP0240
XTION) SETP0250
GO TO 20 SETP0260
18 WRITE(OUT,1007) SETP0270
1007 FORMAT(5X,64H*SMOOTH DETERMINISTICALLY, CALCULATE RESIDUALS AND LOSETP0280
XSS FUNCTION) SETP0290
GO TO 20 SETP0300
19 IF(NPC(8)-3) 170,172,174 SETP0310
170 WRITE(OUT,1027) SETP0320
1027 FORMAT(5X,49H*SMOOTH COVARIANCE,NO RESIDUALS NOR LOSS FUNCTION) SETP0330
GO TO 20 SETP0340
172 WRITE(OUT,1028) SETP0350
1028 FORMAT(5X,56H*SMOOTH COVARIANCE,CALCULATE RESIDUALS AND LOSS FUNCTSETP0360
XION) SETP0370
GO TO 20 SETP0380
174 WRITE(OUT,1029) SETP0390
1029 FORMAT(5X,13H*NO SMOOTHING) SETP0400
20 WRITE(OUT,1009) NPC(7) SETP0410
1009 FORMAT(5X,12H*FILTER FOR I2,11H ITERATIONS) SETP0420
21 IF(NPC(9).EQ.0) GO TO 23 SETP0430
22 WRITE(OUT,1010) SETP0440
1010 FORMAT(5X,28H*SCALAR PROCESS FITTING DATA) SETP0450
GO TO 24 SETP0460
23 WRITE(OUT,1011) SETP0470
1011 FORMAT(5X,36H*VECTOR PROCESS FITTING DATA TRIPLES) SETP0480
24 IF(NPC(2)) 25,25,26 SETP0490
25 WRITE(OUT,1012) SETP0500
1012 FORMAT(5X,52H*INPUT AND OUTPUT IN METRIC UNITS(M,M/SEC,M/SEC2,KG))SETP0510
GO TO 27 SETP0520
26 WRITE(OUT,1013) SETP0530
1013 FORMAT(5X,62H*INPUT AND OUTPUT IN ENGLISH UNITS (FT,FT/SEC,FT/SEC2SETP0540
X,LB,SLUG)) SETP0550
27 WRITE(OUT,1014) REO,RPO,OMEGA,XMU,XJ2,GO SETP0560
1014 FORMAT(5X,18H*PLANET PARAMETERS/20X,11HEGUIT.RAD.=E15.8,13H POLARSETP0570
1 RAD.=E15.8,13H ROTATION =E15.8/20X,11HMU(GRAV.) =E15.8,13H J2(GSETP0580
2RAV. ) =E15.8,7X,6HG(0) =E15.8) SETP0590
IF(NPC(14)-1) 280,282,284 SETP0600
280 WRITE(OUT,1040) SETP0610
1040 FORMAT(5X,32H*ATMOSPHERE IS 1962 U.S.STANDARD) SETP0620
NPTS=22 SETP0630
HB( 1) = 0. SETP0640
HB( 2) = 11000. SETP0650
HB( 3) = 20000. SETP0660
HB( 4) = 32000. SETP0670
HB( 5) = 47000. SETP0680
HB( 6) = 52000. SETP0690
HB( 7) = 61000. SETP0700
HB( 8) = 79000. SETP0710
HB( 9) = 88743. SETP0720
HB(10) = 98451.235 SETP0730
HB(11) = 108128.89 SETP0740
HB(12) = 117776.67 SETP0750

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HB(13) = 146542.06
HB(14) = 156071.67
HB(15) = 165572.08
HB(16) = 184485.82
HB(17) = 221968.74
HB(18) = 286479.92
HB(19) = 376320.01
HB(20) = 463539.66
HB(21) = 548251.81
HB(22) = 630563.08
TMB(1) = 288.15
TMB(2) = 216.65
TMB(3) = 216.65
TMB(4) = 228.65
TMB(5) = 270.65
TMB(6) = 270.65
TMB(7) = 252.65
TMB(8) = 180.65
TMB(9) = 180.65
TMB(10) = 210.65
TMB(11) = 260.65
TMB(12) = 360.65
TMB(13) = 960.65
TMB(14) = 1110.65
TMB(15) = 1210.65
TMB(16) = 1350.65
TMB(17) = 1550.65
TMB(18) = 1830.65
TMB(19) = 2160.65
TMB(20) = 2420.65
TMB(21) = 2590.65
TMB(22) = 2700.65
GO TO 286

282 WRITE(OUT,1041)
1041 FORMAT(5X,24H*ATMOSPHERE IS 1959 ARDC)
NPTS= 12

HB(1)= 0.
HB(2)= 11000.
HB(3)= 25000.
HB(4)= 47000.
HB(5)= 53000.
HB(6)= 79000.
HB(7)= 90000.
HB(8)= 105000.
HB(9)= 160000.
HB(10)= 170000.
HB(11)= 200000.
HB(12)= 700000.
TMB(1)= 288.16
TMB(2)= 216.66
TMB(3)= 216.66
TMB(4)= 282.66
TMB(5)= 282.66
TMB(6)= 165.66
TMB(7)= 165.66
TMB(8)= 225.66
TMB(9)= 1325.66
TMB(10)= 1425.66
TMB(11)= 1575.66
TMB(12)= 3325.66

SETP0760
SETP0770
SETP0780
SETP0790
SETP0800
SETP0810
SETP0820
SETP0830
SETP0840
SETP0850
SETP0860
SETP0870
SETP0880
SETP0890
SETP0900
SETP0910
SETP0920
SETP0930
SETP0940
SETP0950
SETP0960
SETP0970
SETP0980
SETP0990
SETP1000
SETP1010
SETP1020
SETP1030
SETP1040
SETP1050
SETP1060
SETP1070
SETP1080
SETP1090
SETP1100
SETP1110
SETP1120
SETP1130
SETP1140
SETP1150
SETP1160
SETP1170
SETP1180
SETP1190
SETP1200
SETP1210
SETP1220
SETP1230
SETP1240
SETP1250
SETP1260
SETP1270
SETP1280
SETP1290
SETP1300
SETP1310
SETP1320
SETP1330
SETP1340
SETP1350


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      GO TO 286
284 WRITE(OUT,1042)
1042 FORMAT(5X,29H*ATMOSPHERE SPECIFIED BY USER)
      NPTS=K1
      GO TO 292
286 IF(NPC(2)) 288,292,288
288 AR= AR/.167225472
      APO = APO/47.880258
      ABET= ABET*.01556708573
      ASU = ASU*1.8
      DO 290 I=1,NPTS
      HB(I)=HB(I)/.3048
290 TMB(I)=TMB(I)*1.8
292 JK=3
      ATM(1)= GO*AMC/AR
      ATM(2)= AMO/AR
      ATM(3)= SQRT(AGAM*AR/AMO)
      PB(1)=APO
      ISV=1
      DO 294 K=2,NPTS
      RL(K-1)=(TMB(K)-TMB(K-1))/(HB(K)-HB(K-1))
      SP(1)= HB(K)-.0001
      CALL ATMDAT(SP(1),PE,ROE,AS,TM,VMU,H)
294 PB(K)=PE
      JK=NPC(14)
      RL(NPTS)=0
      HB(NPTS+1)=1.E15
      WRITE(OUT,1043) AMO,AR,AGAM,APO,ABET,ASU,(HB(I),I=1,NPTS)
1043 FORMAT(26X,5H MO =E15.8,13H R(STAR) =E15.8,13H CP/CV =E15.8,13H
      18/25X,6HP(0) =E15.8,7X,6HBETA =E15.8,10X,3HS =E15.8/8X,4HHB =6E18,
      28/(12X,6E18.8))
      WRITE(OUT,1044) (TMB(I),I=1,NPTS)
1044 FORMAT(7X,5HTMB =6E18.8/(12X,6E18.8))
      WRITE(OUT,1046) (PB(I),I=1,NPTS)
1046 FORMAT(8X,4HPB =6E18.8/(12X,6E18.8))
      WRITE(OUT,1047)
1047 FORMAT(5X,26H*INITIAL STATE ESTIMATE IS)
      IF(NPC(3)-1) 28,29,30
      28 WRITE(OUT,1015) (ZO(I),I=1,10)
1015 FORMAT(20X,1HU,9X,1H=E15.8,3H V,9X,1H=E15.8,3H W,9X,1H=E15.8/20X
      1,11HALTITUDE =E15.8,13H GEOD.LAT. =E15.8,13H LONGITUDE =E15.8/2
      20X,2HEO,8X,1H=E15.8,4H E1,8X,1H=E15.8,4H E2,8X,1H=E15.8/20X,2
      3,8X,1H=E15.8)
      GO TO 31
      29 WRITE(OUT,1016) (ZO(I),I=1,9)
1016 FORMAT(20X,11HVELOCITY =E15.8,13H GAMMA =E15.8,13H LAMBDA SETP1810
      1 =E15.8/20X,11HALTITUDE =E15.8,13H GEOD.LAT. =E15.8,13H LONGIT
      2UDE =E15.8/20X,11HPSI(BAR) =E15.8,13H THETA(BAR)=E15.8,13H PHI
      3BAR) =E15.8)
      GO TO 31
      30 WRITE(OUT,1017) (ZO(I),I=1,9)
1017 FORMAT(20X,11HVELOCITY =E15.8,13H GAMMA =E15.8,13H LAMBDA SETP1870
      1 =E15.8/20X,11HALTITUDE =E15.8,13H GEOD.LAT. =E15.8,13H LONGIT
      2UDE =E15.8/20X,11HSIGMA =E15.8,13H BETA =E15.8,13H ALPH
      3A =E15.8)
      31 RERP2=(REO/RPO)**2
      XMUJ = 3.*XMU*XJ2*REO**2
      ATM(4)= REO/SQRT(1.-(RERP2-1.)*SIN(.79486646)**2)
      IF(NPC(1)-1)32,40,32
32 WRITE(OUT,1018) NSTA

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1018	FORMAT(5X,22H*FITTING DATA IS FROM 12.8H SOURCES)	SETP1960
	KSS=0	SETP1970
	DO 42 I=1,NSTA	SETP1980
	IF(NS(I)-6) 33,44,45	SETP1990
33	MT=NS(I)	SETP2000
	N = 73 +15*MT	SETP2010
	WRITE(OUT,1019) I,MT,C(N),C(N+1),C(N+2)	SETP2020
1019	FORMAT(10X,I1,19H. TRACKING STATION I1,12H, GEOD.LAT.=F11.6,12H L	SETP2030
	XONGITUDE=F11.6,12H ALTITUDE =F11.4,19H ABOVE REF. SURFACE)	SETP2040
	C(N)=C(N)*CONRD	SETP2050
	C(N+1)=C(N+1)*CONRD	SETP2060
	C(N) = ATAN2(SIN(C(N)),RERP2*COS(C(N)))	SETP2070
	NT=N+2	SETP2080
	MTYP = MT	SETP2090
	CALL STAT	SETP2100
	DO 36 J=1,NSTC	SETP2110
	IF(NC(J)-N) 36,35,35	SETP2120
35	IF(NC(J)-NT)37,37,36	SETP2130
36	CONTINUE	SETP2140
	GO TO 38	SETP2150
37	KSS=KSS+1	SETP2160
	NSS(KSS) = MT	SETP2170
38	MO(MT) = 0	SETP2180
	DO 39 J=1,NSTC	SETP2190
	IF(NC(J).LT.N-6) GO TO 39	SETP2200
	IF(NC(J).LE.N-4) GO TO 40	SETP2210
39	CONTINUE	SETP2220
	IF(C(N-6).NE.0.) GO TO 40	SETP2230
	IF(C(N-5).NE.0.) GO TO 40	SETP2240
	IF(C(N-4).NE.0.) GO TO 40	SETP2250
	GO TO 42	SETP2260
44	WRITE(OUT,1020) I,C(151),C(152)	SETP2270
1020	FORMAT(10X,I1,27H. AIRBORNE RADAR, DELTA(P)=F11.6,11H DELTA(Y)=F1	SETP2280
	X1.6)	SETP2290
	GO TO 42	SETP2300
45	IF(NS(I)-8) 43,41,47	SETP2310
47	WRITE(OUT,1032) I	SETP2320
1032	FORMAT(10X,I1,20H. ACCELEROMETER DATA)	SETP2330
	GO TO 42	SETP2340
41	WRITE(OUT,1030) I	SETP2350
1030	FORMAT(I11,15H. POSITION DATA)	SETP2360
	GO TO 42	SETP2370
43	WRITE(OUT,1031) I	SETP2380
1031	FORMAT(I11,15H. VELOCITY DATA)	SETP2390
	GO TO 42	SETP2400
40	MO(MT) = 1	SETP2410
42	CONTINUE	SETP2420
46	ZO(5) = ZO(5)*CONRD	SETP2430
	ZO(6)=ZO(6)*CONRD	SETP2440
	NSTX = NSTC + 10	SETP2450
	ZO(5) = ATAN2(SIN(ZO(5)),RERP2*COS(ZO(5)))	SETP2460
	CPH=COS(ZO(5))	SETP2470
	SPH=SIN(ZO(5))	SETP2480
	RO =REO/SGRT(1.+(RERP2-1.)*SPH**2)	SETP2490
	R= ZO(4)+RO	SETP2500
	ZO(4)=R-RO	SETP2510
	DO 48 I=1,10	SETP2520
48	X(I)=ZO(I)	SETP2530
	IF(NPC(3).EQ.0) GO TO 100	SETP2540
50	DO 51 I=7,9	SETP2550

51	ZO(I)=ZO(I)*CONRD	SETP2560
	DO 52 I=1,2	SETP2570
	ZO(I+1) = ZO(I+1)*CONRD	SETP2580
	ST(I)=SIN(ZO(I+1))	SETP2590
52	CT(I)=COS(ZO(I+1))	SETP2600
	DO 53 I=3,5	SETP2610
	ST(I)=SIN(ZO(I+4)/2.)	SETP2620
53	CT(I)=COS(ZO(I+4)/2.)	SETP2630
	X(3)=ZO(1)*CT(1)	SETP2640
	X(1)=X(3)*CT(2)	SETP2650
	X(2)=X(3)*ST(2)+R*OMEGA*CPH	SETP2660
	X(3)=-ZO(1)*ST(1)	SETP2670
	UW = TAB(ZO(4),NS(1),TUV(1),XUV(1))	SETP2680
	VW = TAB(ZO(4),N6(1),TVW(1),XVW(1))	SETP2690
	X(1) = X(1)-UW	SETP2700
	X(2) = X(2)-VW	SETP2710
	DO 54 I=1,10	SETP2720
	DO 54 J=1,9	SETP2730
54	DUB(I,J)=0.	SETP2740
	DUB(1,1)= CT(1)*CT(2)	SETP2750
	DUB(2,1)= CT(1)*ST(2)	SETP2760
	DUB(3,1)=-ST(1)	SETP2770
	SP(1)= ZO(1)*ST(1)	SETP2780
	DUB(1,2)=-SP(1)*CT(2)	SETP2790
	DUB(2,2)=-SP(1)*ST(2)	SETP2800
	SP(1)= ZO(1)*CT(1)	SETP2810
	DUB(3,2)=-SP(1)	SETP2820
	DUB(1,3)=-SP(1)*ST(2)	SETP2830
	DUB(2,3)= SP(1)*CT(2)	SETP2840
	DUB(2,4)= OMEGA*CPH	SETP2850
	DUB(2,5)=-R*OMEGA*SPH	SETP2860
	DUB(4,4)=1.	SETP2870
	DUB(5,5)=1.	SETP2880
	DUB(6,6)=1.	SETP2890
	IF(NPC(3)-1) 100, 50, 60	SETP2900
56	DUA(1,1)= CT(3)*CT(4)*CT(5)	SETP2910
	DUA(2,1)= CT(3)*CT(4)*ST(5)	SETP2920
	DUA(3,1)= CT(3)*ST(4)*CT(5)	SETP2930
	DUA(4,1)= ST(3)*CT(4)*CT(5)	SETP2940
	DUA(1,2)= ST(3)*ST(4)*ST(5)	SETP2950
	DUA(2,2)= ST(3)*ST(4)*CT(5)	SETP2960
	DUA(3,2)= ST(3)*CT(4)*ST(5)	SETP2970
	DUA(4,2)= CT(3)*ST(4)*ST(5)	SETP2980
	X(7) = DUA(1,1)+DUA(1,2)	SETP2990
	X(8) = DUA(2,1)-DUA(2,2)	SETP3000
	X(9) = DUA(3,1)+DUA(3,2)	SETP3010
	X(10)= DUA(4,1)-DUA(4,2)	SETP3020
	IF(NPC(1).EQ.1) GO TO 100	SETP3030
	DUB(7,7) = -X(10)/2.	SETP3040
	DUB(8,7) = -X(9)/2.	SETP3050
	DUB(9,7) = X(8)/2.	SETP3060
	DUB(10,7) = X(7)/2.	SETP3070
	DUB(7,8) = -(DUA(3,1) - DUA(3,2))/2.	SETP3080
	DUB(8,8) = -(DUA(4,1) + DUA(4,2))/2.	SETP3090
	DUB(9,8) = (DUA(1,1) - DUA(1,2))/2.	SETP3100
	DUB(10,8) = -(DUA(2,1) + DUA(2,2))/2.	SETP3110
	DUB(7,9) = -X(8)/2.	SETP3120
	DUB(8,9) = X(7)/2.	SETP3130
	DUB(9,9) = X(10)/2.	SETP3140
	DUB(10,9) = -X(9)/2.	SETP3150

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GO TO 70
60 ST(1) = SIN(.5*Z0(2))
CT(1) = COS(.5*Z0(2))
ST(2) = SIN(.5*Z0(3))
CT(2) = COS(.5*Z0(3))
DUE(1) = CT(1)*CT(2)
DUE(2) = -ST(1)*ST(2)
DUE(3) = ST(1)*CT(2)
DUE(4) = CT(1)*ST(2)
DUA(1,1) = CT(3)*CT(4)*CT(5)
DUA(2,1) = ST(3)*CT(4)*CT(5)
DUA(3,1) = CT(3)*CT(4)*ST(5)
DUA(4,1) = ST(3)*CT(4)*ST(5)
DUA(1,2) = ST(3)*ST(4)*ST(5)
DUA(2,2) = CT(3)*ST(4)*ST(5)
DUA(3,2) = ST(3)*ST(4)*CT(5)
DUA(4,2) = CT(3)*ST(4)*CT(5)
DUF(1) = DUA(1,1) - DUA(1,2)
DUF(2) = DUA(2,1) + DUA(2,2)
DUF(3) = DUA(3,1) + DUA(3,2)
DUF(4) = DUA(4,1) - DUA(4,2)
X(7) = DUE(1)*DUF(1) - DUE(2)*DUF(2) - DUE(3)*DUF(3) - DUE(4)*DUF(4)
X(8) = DUE(1)*DUF(2) + DUE(2)*DUF(1) + DUE(3)*DUF(4) - DUE(4)*DUF(3)
X(9) = DUE(1)*DUF(3) - DUE(2)*DUF(4) + DUE(3)*DUF(1) + DUE(4)*DUF(2)
X(10) = DUE(1)*DUF(4) + DUE(2)*DUF(3) - DUE(3)*DUF(2) + DUE(4)*DUF(1)
IF(NPC(1).EQ.1) GO TO 100
DUB(7,2) = -X(9)/2. - DUE(2)*DUF(4) + DUE(4)*DUF(2)
DUB(8,2) = X(10)/2. - DUE(2)*DUF(3) - DUE(4)*DUF(1)
DUB(9,2) = X(7)/2. + DUE(2)*DUF(2) + DUE(4)*DUF(4)
DUB(10,2) = -X(8)/2. + DUE(2)*DUF(1) - DUE(4)*DUF(3)
DUB(7,3) = -X(10)/2.
DUB(8,3) = -X(9)/2.
DUB(9,3) = X(8)/2.
DUB(10,3) = X(7)/2.
DUB(7,7) = -X(8)/2. + DUE(3)*DUF(4) - DUE(4)*DUF(3)
DUB(8,7) = X(7)/2. + DUE(3)*DUF(3) + DUE(4)*DUF(4)
DUB(9,7) = -X(10)/2. - DUE(3)*DUF(2) + DUE(4)*DUF(1)
DUB(10,7) = X(9)/2. - DUE(3)*DUF(1) - DUE(4)*DUF(2)
DUF(1) = DUA(1,1) + DUA(1,2)
DUF(2) = DUA(2,1) - DUA(2,2)
DUF(3) = DUA(3,1) - DUA(3,2)
DUF(4) = DUA(4,1) + DUA(4,2)
DUB(7,8) = (-DUE(1)*DUF(4) - DUE(2)*DUF(3) - DUE(3)*DUF(2) + DUE(4)*DUF(
X1))/2.
DUB(8,8) = (DUE(1)*DUF(3) - DUE(2)*DUF(4) - DUE(3)*DUF(1) - DUE(4)*DUF(
X2))/2.
DUB(9,8) = (DUE(1)*DUF(2) + DUE(2)*DUF(1) - DUE(3)*DUF(4) + DUE(4)*DUF(
X3))/2.
DUB(10,8) = (-DUE(1)*DUF(1) + DUE(2)*DUF(2) - DUE(3)*DUF(3) - DUE(4)*DUF(
X4))/2.
DUB(7,9) = -X(9)/2.
DUB(8,9) = -X(10)/2.
DUB(9,9) = X(7)/2.
DUB(10,9) = X(8)/2.
70 DO 74 I=1,10
DO 74 J=1,NSTX
SUM = 0.
DO 72 K=1,9
72 SUM = SUM + DUB(I,K)*P(K,J)
74 PH(I,J) = SUM
SETP3160
SETP3170
SETP3180
SETP3190
SETP3200
SETP3210
SETP3220
SETP3230
SETP3240
SETP3250
SETP3260
SETP3270
SETP3280
SETP3290
SETP3300
SETP3310
SETP3320
SETP3330
SETP3340
SETP3350
SETP3360
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SETP3650
SETP3660
SETP3670
SETP3680
SETP3690
SETP3700
SETP3710
SETP3720
SETP3730
SETP3740
SETP3750

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DO 80 I=1,10	SETP3760
DO 78 J=I,10	SETP3770
SUM = 0.	SETP3780
DO 76 K=1,10	SETP3790
76 SUM = SUM + PH(I,K)*DUB(J,K)	SETP3800
78 P(I,J) = SUM	SETP3810
DO 80 J=11,NSTX	SETP3820
80 P(I,J) = PH(I,J)	SETP3830
IF(NPU.EQ.0) GO TO 88	SETP3840
DO 84 I=1,10	SETP3850
DO 84 J=1,NPU	SETP3860
SUM = 0.	SETP3870
DO 82 K=1,9	SETP3880
82 SUM = SUM + DUB(I,K)*CUZ(K,J)	SETP3890
84 PH(I,J) = SUM	SETP3900
DO 86 I=1,10	SETP3910
DO 86 J=1,NPU	SETP3920
86 CUZ(I,J) = PH(I,J)	SETP3930
88 IF(NPV.EQ.0) GO TO 100	SETP3940
DO 92 I=1,10	SETP3950
DO 92 J=1,NPV	SETP3960
SUM = 0.	SETP3970
DO 90 K=1,9	SETP3980
90 SUM = SUM + DUB(I,K)*CVZ(K,J)	SETP3990
92 PH(I,J) = SUM	SETP4000
DO 94 I=1,10	SETP4010
DO 94 J=1,NPV	SETP4020
94 CVZ(I,J) = PH(I,J)	SETP4030
100 WRITE(OUT,3021)	SETP4040
WRITE(OUT,1021) (I,I,X(I),P(I,I),I=1,10)	SETP4050
3021 FORMAT(//,24H STATE VECTOR COMPONENTS/43H COMP. ID.NO. EST.	SETP4060
*VALUE VARIANCE)	SETP4070
1021 FORMAT(1X,I4,4X,I4,5X,2E15.8)	SETP4080
IF(NSTC) 102,104,102	SETP4090
102 WRITE(OUT,1022)	SETP4100
1022 FORMAT(42H MODEL PARAMETERS IN EXPANDED STATE VECTOR)	SETP4110
DO 103 I=1,NSTC	SETP4120
LT=NC(I)	SETP4130
MT=I+10	SETP4140
103 WRITE(OUT,1023) MT,LT,C(LT),P(MT,MT)	SETP4150
1023 FORMAT(1X,I4,4X,I4,5X,2E15.8)	SETP4160
104 IF(NPU) 106,108,106	SETP4170
106 WRITE(OUT,1024)	SETP4180
1024 FORMAT(55H RANDOM MODEL PARAMETERS NOT BEING ESTIMATED (U-VECTOR))	SETP4190
DO 107 I=1,NPU	SETP4200
LT=MC(I)	SETP4210
107 WRITE(OUT,1023) I,LT,C(LT),D(I)	SETP4220
108 IF(NPV) 110,112,110	SETP4230
110 WRITE(OUT,1025)	SETP4240
1025 FORMAT(61H RANDOM MEASUREMENT PARAMETERS NOT BEING ESTIMATED (V-VECTOR))	SETP4250
DO 111 I=1,NPV	SETP4260
LT=MCC(I)	SETP4270
111 WRITE(OUT,1023) I,LT,C(LT),S(I)	SETP4280
112 LT=9	SETP4290
IF(NPC(3).EQ.0) LT = 10	SETP4300
IF(NST-LT) 114,120,114	SETP4310
114 WRITE(OUT,1026)	SETP4320
1026 FORMAT(48H IMPROPER NUMBER OF STATE VARIABLES ARE INPUTTED)	SETP4330
CALL EXIT	SETP4340
	SETP4350

120 IF(NPC(1)-1) 124,122,124	SETP4360
122 NALL=10	SETP4370
GO TO 128	SETP4380
124 NALL = 10*(NSTX+NPU+1)	SETP4390
K = NSTX + NPU	SETP4400
DO 126 I =1,10	SETP4410
DO 125 J=1,K	SETP4420
125 PH(I,J) = 0.	SETP4430
126 PH(I,I) = 1.	SETP4440
128 IF(NPC(1)-2) 144,130,144	SETP4450
130 IF(NSTA-1) 144,144,132	SETP4460
132 DO 142 I=2,NSTA	SETP4470
MT=NS(I-1)	SETP4480
TT=DTF(MT)	SETP4490
DO 136 J=1,NSTA	SETP4510
K=NS(J)	SETP4520
IF(TT-DTF(K)) 135,135,136	SETP4530
135 TT=DTF(K)	SETP4540
LT=J	SETP4550
136 CONTINUE	SETP4560
137 IP=NS(I-1)	SETP4570
138 NS(I-1)=NS(LT)	SETP4580
139 NS(LT)=IP	SETP4590
142 CONTINUE	SETP4600
144 KDATA=-1	SETP4760
WRITE(SCRACH) NSTX,NPU,NPV,((P(I,J),I=1,NSTX),J=1,NSTX),	SETP4770
1 ((CUZ(I,J),I=1,NSTX),J=1,NPU),((CVZ(I,J),I=1,NSTX),J=1,NPV)	SETP4780
ET = TO	SETP4790
TZERO = TC	SETP4800
TIMES=TZERO-10.	SETP4810
T = TO	SETP4820
KDAP = 1	SETP4830
KPROP=-1	SETP4840
KDATAS =-1	SETP4850
C(151) = C(151)*CONRD	SETP4860
C(152) = C(152)*CONRD	SETP4870
RETURN	SETP4880
END	SETP4890

```

SUBROUTINE SMOOTH
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZI,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,HO,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TTWO,TUW(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XQSM,XRE,XTEMP,
8 XUW(20),XVW(20),XZI,YMAS,YMASM
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VO(20),ZO(20),AG(3),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),DTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,II,IP,IPC,JJ,JN,KA,KD(3),KDUM,KG2
5 K1,NNN,NPTS,PAR(6),PDOT(3),PMDOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHDT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRS,JST
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A N8(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHDT(5),SUM,SUM2,SYG(3,9),TFINAL
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AM0,AP0,AR,ASU,ATM(4),HB(23),ISV,JK
A PB(23),RL(23),TMB(23)
COMMON /EXTRA / GO
CALL IDENT
FLOS = 0.
TIME = TZERO - 10.
NALLSV=NALL
MOPTSV=NPC(1)
DCOMP=-DCOMP
IF(NPC(1)-1) 4,6,2
2 IF(NPC(8)-4) 12,6,12
4 IF(NPC(7).GT.1COUNT) IF(NPC(8)-4) 16,6,16
IF(NPC(8).LE.1) GO TO 8
IF(NPC(6).LE.3) GO TO 14
6 TZERO = TO
NPC(7) = 1COUNT
GO TO 62
8 NPC(1) = 1

```

NALL=10	SMTH0160
9 IF(NPC(8).EQ.0) GO TO 12	SMTH0170
IF(NPC(8).EQ.2) GO TO 12	SMTH0180
10 KSM = 1	SMTH0190
GO TO 18	SMTH0200
12 KSM = 0	SMTH0210
GO TO 18	SMTH0220
14 IF(NPC(8)-2) 12,12,10	SMTH0230
16 NPC(1) = 1	SMTH0240
NALL=10	SMTH0250
GO TO 9	SMTH0260
18 T2 = TO	SMTH0270
WRITE(OUT,1004)	SMTH0280
20 CALL INTAG	SMTH0290
TO=T2	SMTH0300
IF(ET.LE.TIME) GO TO 150	SMTH0310
IF(NPC(1).NE.1) CALL PROP	SMTH0320
24 CALL OUTPUT	SMTH0330
L1=1	SMTH0340
28 IF(T2-TZERO) 60,60,30	SMTH0350
30 ET=ET-DET	SMTH0360
IF(KSM.LE.0) GO TO 38	SMTH0370
36 TIME = TYM(KG)	SMTH0380
37 IF(TIME.LE.ET) GO TO 38	SMTH0390
T2 = TIME	SMTH0400
GO TO 20	SMTH0410
38 T2 = ET	SMTH0420
GO TO 20	SMTH0430
60 NALL=NALLSV	SMTH0440
NPC(1)=MOPTSV	SMTH0450
DCOMP=-DCOMP	SMTH0460
IF(ICOUNT-NPC(7)) 64,62,62	SMTH0470
62 ET=TFINAL	SMTH0480
NPC(1)=1	SMTH0490
L1=0	SMTH0500
GO TO 99	SMTH0510
64 ICOUNT=ICOUNT+1	SMTH0520
DO 66 I=1,9	SMTH0530
66 NTR(I) = 0	SMTH0540
REWIND FIT	SMTH0550
REWIND PQR	SMTH0560
KDATAS=-1	SMTH0570
KDATA=-1	SMTH0580
KPROP=-1	SMTH0590
NCOUNT=0	SMTH0600
L1=1	SMTH0610
BACKSPACE SCRACH	SMTH0620
BACKSPACE SCRACH	SMTH0630
READ (SCRACH) NSTX,NPU,NPV,((P(I,J),I=1,NSTX),J=1,NSTX),	SMTH0640
1 ((CUZ(I,J),I=1,NSTX),J=1,NPU),((CVZ(I,J),I=1,NSTX),J=1,NPV)	SMTH0650
CALL IDENT	SMTH0660
99 RETURN	SMTH0670
150 MTP=MTP(KG)	SMTH0680
IF(KG.EQ.0) GO TO 158	SMTH0690
CALL OBSERV	SMTH0700
DO 156 I=1,3	SMTH0710
IF(MR(I,MTP)) 152,154,152	SMTH0720
152 RES(I)=DFM(I)-DAT(I,KG)	SMTH0730
IF(MTP.GT.5) GO TO 153	SMTH0740
IF(I.EQ.1) GO TO 153	SMTH0750

	IF (ABS(RES(I)).LT.3.1416) GO TO 153	SMTH0760
	RES(I)=RES(I)-SIGN(6.283185307179586,RES(I))	SMTH0770
153	CONTINUE	SMTH0780
	RES(I+3)= RES(I)/SP(I)	SMTH0790
	FLOS= FLOS + RES(I+3)**2	SMTH0800
	KD(I)=NCOUNT	SMTH0810
	NCOUNT=NCOUNT-1	SMTH0820
	GO TO 156	SMTH0830
154	RES(I)=0.	SMTH0840
	RES(I+3)=0.	SMTH0850
	KD(I) = 0	SMTH0860
156	CONTINUE	SMTH0870
	IF (L1.NE.0) WRITE(OUT,1000)	SMTH0880
	L1=0	SMTH0890
	WRITE(OUT,1002) (KD(I),I=1,3),MTYP,TO,(RES(I),I=1,6),FLOS	SMTH0900
	KG=KG-1	SMTH0910
	IF (KG.GT.0) GO TO 36	SMTH0920
158	TIME=TZERO-10.	SMTH0930
	GO TO 37	SMTH0940
1000	FORMAT(//5X6HPOINTS4X,4HTYPE,3X,4HTIME,6X,4HRES1,9X,4HRES2,9X,4HRES3,9X,8HWGT.RES1,5X,8HWGT.RES2,5X,8HWGT.RES3,5X,9HLOSS FCTN)	SMTH0950
1002	FORMAT(1X,I4,1H,I4,1H,I4,1X,I2,1X,F10.3,7(1X,E12.5))	SMTH0960
1004	FORMAT(//20(1H*),25HBEGIN BACKWARDS SMOOTHING,75(1H*))	SMTH0970
	END	SMTH0980
		SMTH0990

```

SUBROUTINE STAT
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS ,BETA,CA(6),CALP ,CBET ,CETA ,
1 CF(3),JCS ,CXZI ,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH ,
2 DRDP,DWDH(2),ETA,HO,N4(3) ,N5(3) ,N6(3) ,PAXP(3,30),
3 PE ,ROE ,ROEC ,ROEM ,SALP ,SBET ,
4 SETA ,SREF ,SXZI ,TAU ,TMAS(20) ,TONE ,
5 TTWO ,TUW(20) ,TVW(20) ,UW ,VA(5) ,VB(5) ,
6 VW ,XIND1 ,XIND2 ,XLREF ,XM ,
7 XMAS(20) ,XNU ,XG ,XQSM ,XRE ,XTEMP ,
8 XUW(20) ,XVW(20) ,XZI ,YMAS ,YMASM
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDO(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS ,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON /ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A ,PB(23),RL(23),TMB(23)
COMMON /EXTRA / GC
EQUIVALENCE (SP(3),PHIDT),(SP(4),CAPHI)
IF(MTYP.GT.5) RETURN
N = 60 + 15*MTYP
SP(1) = COS(C(N+13))
SP(2) = SIN(C(N+13))
PHIDT = ATAN2(RERP2*SP(2),SP(1))
CAPHI= PHIDT - C(N+13)
SPHDT(MTYP)=SIN(PHIDT)
CPHDT(MTYP)=COS(PHIDT)
CCAPH(MTYP)= COS(CAPHI)
SCAPH(MTYP)= SIN(CAPHI)
ROT(MTYP) = REC/SQRT(1.+(RERP2-1.)*SP(2)**2)
99 RETURN
END

```

FUNCTION TAB(TARG,N,T,Y)	
DIMENSION N(1),T(1),Y(1)	
IF(N(1))111,14,111	TABT0010
111 CONTINUE	TABT0020
I = N(2)	TABT0030
6 IF(TARG - T(I))3,2,1	TABT0040
1 IF(N(3))9,5,9	TABT0050
5 I = I+1	TABT0060
IF(I-N(1)) 6,4,4	TABT0070
4 I = I - 1	TABT0080
8 TAB = (Y(I+1)*(TARG - T(I)) - Y(I)*(TARG - T(I+1)))/(T(I+1)-T(I))	TABT0090
7 N(2) = I	TABT0100
99 RETURN	TABT0110
11 I = I - 1	TABT0120
2 TAB = Y(I)	TABT0130
GO TO 7	TABT0140
9 IF(TARG - T(I-1)) 4,11,12	TABT0150
3 IF(N(3))5,10,5	TABT0160
10 IF(TARG - T(I-1))12,11,4	TABT0170
12 I = I - 1	TABT0180
IF(I-1)18,8,6	TABT0190
18 I=1	TABT0200
GO TO 8	TABT0210
14 TAB = 0.	TABT0220
RETURN	TABT0230
END	TABT0240
	TABT0250

B. STEP2 Listing

The STEP2 source listing is presented in the following subsection. The following listing indicates the pages on which the STEP2 subroutine listings appear:

MAIN	217
DATAB	221
FXXU	224
INDAT	229
INTAG	233
MINVAR	235
MOTION	239
OBSERV	242
OUTPUT	250
PRESET	256
PROP	258
RKUTTA	260
SETUP	261
SMOOTH	268
STAT	271
TAB	272

```

PROGRAM MAIN(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT,
2 TAPE7, TAPE1,TAPE2,TAPE3,TAPE4)
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS ,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MQ(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
C-----STATISTICAL TRAJECTORY ESTIMATION PROGRAM, STEP2
C DEVELOPED BY W.E.WAGNER AND A.C.SEROLD
C MARTIN MARIETTA CORPORATION
C DENVER, COLORADO
2 CONTINUE
CALL PRESET
4 WRITE(OUT,1001)
IF(NPC(1).EQ.0) WRITE(OUT,1000) ICOUNT
1000 FORMAT(19H ITERATION NUMBER I2//)
1001 FORMAT(1H1)
10 IF(KDATA) 12,42,202
12 T2=TO
CALL INTAG
GO TO 44
24 T2=TIME
IF(T2-ET)260,260,42
30 IF(TO-ET) 34,32,32
32 IF(JST.EQ.1) GO TO 44
34 IF(KLATA) 36,36,36
36 IF(KPROP.EQ.1) GO TO 24
IF(KDATA) 10,40,10
38 IF(NPC(1)-1) 200,40,100
40 TIME=TFINAL+100.
GO TO 24
42 T2=ET
C-----PROPAGATION LOOP, TO EFN 44

```

CALL INTAG	STP20280
KPROP=1	STP20290
TO=T2	STP20300
CALL PROP	STP20310
44 CALL OUTPUT	STP20320
L1=2	STP20340
IF(ET-TFINAL) 46,50,50	STP20350
46 ET=ET+DET	STP20360
GO TO 34	STP20370
50 WRITE(SCRACH) KDATA	STP20380
IF(NPC(1).EQ.1) GO TO 2	STP20390
56 IF(NPC(4)) 300,58,300	STP20400
58 CALL SMOOTH	STP20410
IF(L1-1) 2,4,2	STP20420
C-----DETERMINE MEASUREMENT TIME FOR ERROR	STP20430
C ANALYSIS PROBLEMS, THRU EFN 118--	STP20440
100 IF(KPROP.GT.0) GO TO 24	STP10432
JST=1	STP10434
IF(NSTA-1) 40,102,104	STP10440
102 II=NS(1)	STP20460
GO TO 112	STP20470
104 II = NS(1)	STP20480
SP(1) = DTI(II)	STP20490
DO 110 I=2,NSTA	STP20510
J=NS(I)	STP20520
IF(SP(1)-DTI(J)) 110,106,107	STP20530
106 JST=JST+1	STP20540
GO TO 108	STP20550
107 JST=1	STP20560
108 SP(1) = DTI(J)	STP20570
II=J	STP20580
110 CONTINUE	STP20590
112 IF(DTI(II)-DTF(II)) 116,116,114	STP20600
114 NSTA=NSTA-1	STP20610
GO TO 100	STP20620
116 JNBR=0	STP20630
TIME=DTI(II)	STP20640
DTI(II)=DTI(II)+DFIT(II)	STP20650
DO 118 I=1,3	STP20660
IF(MR(I,II).EQ.0) GO TO 118	STP20670
JNBR=JNBR+1	STP20680
LC(JNBR)=I	STP20690
118 CONTINUE	STP20700
IF(JNBR.EQ.0) GO TO 100	STP20710
MTYP=II	STP20720
GO TO 24	STP20730
C-----DATA EDITING LOGIC FOR FILTER PROBLEMS, THRU EFN 250-----	STP20740
200 KG = 1	STP20750
KS = 1	STP20760
TYM(1) = TZERO - 10.	STP20770
GO TO 211	STP20780
202 KG=KG+1	STP20790
MTP(KG)=MTYPS	STP20800
TYM(KG)=TIMES	STP20810
DAT(1,KG)=DATAS(1)	STP20820
DAT(2,KG)=DATAS(2)	STP20830
DAT(3,KG)=DATAS(3)	STP20840
SIG(1,KG)=SIGMS(1)	STP20850
SIG(2,KG)=SIGMS(2)	STP20860
SIG(3,KG)=SIGMS(3)	STP20870

MTYP=MTYPS	STP20890
TIME=TIMES	STP20900
DATA(1)=DATAS(1)	STP20910
DATA(2)=DATAS(2)	STP20920
DATA(3)=DATAS(3)	STP20930
SIGM(1)=SIGMS(1)	STP20940
SIGM(2)=SIGMS(2)	STP20950
SIGM(3)=SIGMS(3)	STP20960
LC(1)=LCS(1)	STP20970
LC(2)=LCS(2)	STP20980
LC(3)=LCS(3)	STP20990
JNBR=JNBRS	STP21000
204 IF(KI-KS) 206,208,208	STP21010
206 KI=KI+1	STP21020
GO TO 216	STP21030
208 KS=KG	STP21040
210 CONTINUE	STP21050
211 IF(KDATAS.EQ.0) GO TO 212	STP21060
READ(FIT) KDATAS, (MTP(KS+I), TYM(KS+I), (DAT(J,KS+I), J=1,3), (SIG(J	STP21070
X,KS+I), J=1,3), I=1, KDATAS)	STP21080
KS=KS+KDATAS	STP21090
IF(KS=20) 210,215,215	STP21100
212 IF(KG+1-KS) 215,213,213	STP21110
213 KDATA=0	STP21120
GO TO 248	STP21130
215 KI=KG+1	STP21140
216 MTYPS=MTP(KI)	STP21150
TIMES=TYM(KI)	STP21160
IF(TIMES.GT.TFINAL) GO TO 213	STP21170
IF(NTR(MTYPS)) 220,218,220	STP21180
218 IF(TIMES.LT.DTI(MTYPS)) GO TO 204	STP21190
TFIT(MTYPS)=TIMES	STP21200
NTR(MTYPS)=1	STP21210
220 CONTINUE	STP21220
222 IF(TIMES-DTF(MTYPS)) 224,224,204	STP21230
224 IF(TIMES-TFIT(MTYPS)) 226,234,228	STP21240
226 NTR(MTYPS)=3	STP21250
GO TO 204	STP21260
228 IF(NTR(MTYPS)-3) 230,232,230	STP21270
230 TFIT(MTYPS)=TFIT(MTYPS)+DFIT(MTYPS)	STP21280
NTR(MTYPS)=3	STP21290
GO TO 224	STP21300
232 TFIT(MTYPS)=TIMES	STP21310
234 NTR(MTYPS)=2	STP21320
JNBR=0	STP21330
DO 238 I=1,3	STP21340
IF(MR(I,MTYPS)) 236,238,236	STP21350
236 JNBR=JNBR+1	STP21360
LCS(JNBR)=I	STP21370
238 CONTINUE	STP21380
IF(JNBR) 240,204,240	STP21390
240 DATAS(1)=DAT(1,KI)	STP21400
DATAS(2)=DAT(2,KI)	STP21410
DATAS(3)=DAT(3,KI)	STP21420
SIGMS(1)=SIG(1,KI)	STP21430
SIGMS(2)=SIG(2,KI)	STP21440
SIGMS(3)=SIG(3,KI)	STP21450
IF(KDATA) 242,244,244	STP21460
242 KDATA=2	STP21465
IF(TIMES-TZERO) 204,202,202	STP21465

244	IF(TIMES-TIME) 248,246,248	STP21480
246	JST=2	STP21490
	GO TO 250	STP21500
248	JST=1	STP21510
250	GO TO 24	STP21520
C-----PROCESSING LOOP, THRU EFN 278-----		STP21530
260	CALL INTAG	STP21540
	TO=T2	STP21550
	KPROP=0	STP21560
	KN=0	STP21570
	KK = 1	STP21580
	IF(JNBR-1) 270,270,262	STP21590
262	IF(NPC(9)) 268,264,268	STP21600
264	KN=1	STP21610
	GO TO 270	STP21620
268	KK=JNBR	STP21630
	IF(NPC(4)) 264,270,264	STP21640
270	KAR=1	STP21650
272	CALL OBSERV	STP21660
273	IF(T-TSAV) 274,276,274	STP21670
274	CALL PROP	STP21680
	TSAV=T	STP21690
276	IF(NPC(9),NE.0) KOB = KAR	STP21700
	CALL MINVAR	STP21710
	IF(KAR-KK) 278,30,30	STP21720
278	KAR=KAR+1	STP21730
	IF(KN,NE.0) GO TO 276	STP21740
	CALL MOTION	STP21750
	GO TO 272	STP21760
C-----UPDATE STATE, EQ.(55A), THRU EFN 312-----		STP21770
300	DO 306 I=1,10	STP21780
	SUM=0.	STP21790
	DO 304 K=1,10	STP21800
304	SUM=SUM+PH(I,K)*DZ(K)	STP21810
306	UUD(1)=SUM	STP21820
	DO 312 I=1,NSTX	STP21830
	IF(I-10) 308,308,310	STP21840
308	DZ(I)=UUD(I)	STP21850
	X(I)=X(I)+DZ(I)	STP21860
	GO TO 312	STP21870
310	K=NC(I-10)	STP21880
	C(K)=C(K)+DZ(I)	STP21890
	VO(I-10)=C(K)	STP21900
312	CONTINUE	STP21910
C-----NORMALIZE QUATERNION-----		STP21920
	DATC(1)= SQRT(X(7)**2 + X(8)**2 + X(9)**2 + X(10)**2)	STP21930
	X(7) = X(7)/DATC(1)	STP21940
	X(8) = X(8)/DATC(1)	STP21950
	X(9) = X(9)/DATC(1)	STP21960
	X(10)=X(10)/DATC(1)	STP21970
C-----UPDATE TRACKING STATION LOCATIONS-----		STP21980
	IF(KSS,LE.0) GO TO 316	STP21990
	DO 314 I=1,KSS	STP22000
	MTYP=NSS(I)	STP22010
314	CALL STAT	STP22020
316	WRITE(OUT,1003)	STP22030
1003	FORMAT(39H UPDATED MODEL PARAMETERS AT FINAL TIME)	STP22040
	WRITE(CUT,1002) (NC(I),VO(I),I=1,NSTC)	STP22050
1002	FORMAT(6(2H C,I3,E15.8))	STP22060
	GO TO 58	STP22070
	END	STP22080


```

SUBROUTINE DATAB
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3) ,KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHOT(5) ,CUZ(30,5)
2 ,CVZ(30,5) ,D(5) ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBR5 ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG ,KI ,KK
6 ,KN ,KOB ,KPROP ,KS ,KSM ,KSS ,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENC/ IN,OUT,FIT,STATE,SCRACH,PQR
IF(DCOMP.LT.0.) GO TO 20
IF(KPROP.GE.0) GO TO 10
2 CONTINUE
4 LS = 0
6 IF(KDAP.EQ.0) GO TO 14
READ(PQR) KDAP,(TT(LS+1),TP(LS+1),TQ(LS+1),TR(LS+1),AX(LS+1),
* AY(LS+1),AZ(LS+1),I=1,KDAP)
LS = LS+KDAP
IF(LS.EQ.1) GO TO 6
IF(T.GT.TT(LS)) GO TO 11
IF(LS.LE.20) GO TO 6
N11(2)=3
10 IF(T.LT.TT(LS-1)) GO TO 14
IF(KDAP.EQ.0) GO TO 14
KG2 = KG-2
WRITE(SCRACH) LS,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),
* I=1,LS),KG2,(MTP(I),TYM(I),DAT(1,I),DAT(2,I),DAT(3,I),
* SIG(1,I),SIG(2,I),SIG(3,I),I=1,KG2)
IF(KG2.LE.0) GO TO 11
KG = 2
DO 13 I=1,2
LT = KG2 + I
MTP(I) = MTP(LT)
TYM(I) = TYM(LT)
DAT(1,I) = DAT(1,LT)
DAT(2,I) = DAT(2,LT)

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DAT(3,I) = DAT(3,LT)
SIG(1,I) = SIG(1,LT)
SIG(2,I) = SIG(2,LT)
SIG(3,I) = SIG(3,LT)
13 CONTINUE
11 CONTINUE
DO 12 I=1,2
  MT = LS + I - 2
  TT(I) = TT(MT)
  TP(I) = TP(MT)
  TQ(I) = TQ(MT)
  TR(I) = TR(MT)
  AX(I) = AX(MT)
  AY(I) = AY(MT)
  AZ(I) = AZ(MT)
12 CONTINUE
LS = 2
GO TO 6
14 N11(1) = LS
  IF(KPROP.LT.0) TRCD=TT(1)
  KPROP = 1
  PM(1) = TAB(T,N11(1),TT(1),TP(1))
  PM(2)=TAB(T,N11(1),TT(1),TQ(1))
  PM(3)=TAB(T,N11(1),TT(1),TR(1))
  AM(1) = TAB(T,N11(1),TT(1),AX(1))
  AM(2) = TAB(T,N11(1),TT(1),AY(1))
  AM(3) = TAB(T,N11(1),TT(1),AZ(1))
  CGM(1) = TAB(T,N8(1) ,TXCG(1),XXCG(1))
  CGM(2) = TAB(T,N9(1) ,TYCG(1),XYCG(1))
  CGM(3) = TAB(T,N10(1),TZCG(1),XZCG(1))
99 RETURN
20 IF(T.GT.TT(2)) GO TO 14
  IF(TT(1).EQ.TRCD) GO TO 14
  BACKSPACE SCRACH
  BACKSPACE SCRACH
  LT = 40-KG
  DO 22 I=1,KG
  MT = LT+I
  MTP(MT) = MTP(I)
  TYM(MT) = TYM(I)
  DAT(1,MT) = DAT(1,I)
  DAT(2,MT) = DAT(2,I)
  DAT(3,MT) = DAT(3,I)
  SIG(1,MT) = SIG(1,I)
  SIG(2,MT) = SIG(2,I)
  SIG(3,MT) = SIG(3,I)
22 READ(SCRACH) KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),
* I=1,KDAP),KDATA,(MTP(I),TYM(I),DAT(1,I),DAT(2,I),DAT(3,I),
* SIG(1,I),SIG(2,I),SIG(3,I),I=1,KDATA)
LS=KDAP
N11(2)=LS-2
IF(KDATA.LT.0) GO TO 26
LT = LT - KDATA
I = KDATA+1
J = KDATA+KG
DO 24 I=I,J
  MT = LT + I
  MTP(I) = MTP(MT)
  TYM(I) = TYM(MT)
  DAT(1,I) = DAT(1,MT)

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DATB0270
DATB0280
DATB0290
DATB0300
DATB0310
DATB0320
DATB0330
DATB0340
DATB0350
DATB0360
DATB0370
DATB0380
DATB0390
DATB0400
DATB0410
DATB0420
DATB0430
DATB0440
DATB0450
DATB0460
DATB0470
DATB0480
DATB0490
DATB0500
DATB0510
DATB0520
DATB0530
DATB0540
DATB0550
DATB0560
DATB0570
DATB0580
DATB0590
DATB0600
DATB0610
DATB0620
DATB0630
DATB0640
DATB0650
CATB0660
DATB0670
DATB0680
DATB0690
DATB0700
DATB0710
DATB0720
DATB0730
DATB0740
DATB0750
DATB0760
DATB0770
DAT20780
DATB0790
DATB0800
DATB0810
DATB0820
DATB0830
DATB0840
DATB0850
DATB0860

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```
    DAT(2,I) = DAT(2,MT)
    DAT(3,I) = DAT(3,MT)
    SIG(1,I) = SIG(1,MT)
    SIG(2,I) = SIG(2,MT)
24  SIG(3,I) = SIG(3,MT)
    KG = KG + KDATA
    GO TO 14
26  KG = 1
    GO TO 14
    END
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DAT80870
DAT80880
DAT80890
DAT80900
DAT80910
DAT80920
DAT80930
DAT80940
DAT80950
DAT80960
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SUBROUTINE FXXU
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR,JNBRS,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA,NSTC,NSTX,NT,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
DIMENSION CX(3,4)
EQUIVALENCE (C(48),CX(1,1))
C-----CALCULATE EGS. IN TABLE 4 -----
SP(1) = PAR(4)*X(2)/CPH**2
F2(2,1) = 1./R
F1(1,3) = F2(2,1)*X(1)
F1(3,1) = -F1(1,3)-F1(1,3)
F1(3,2) = -F1(2,3)-F1(2,3)
F1(1,1) = F2(2,1)*X(3)
F1(1,2) = -F1(2,1)-F1(2,1)
F1(1,4) = (-PAR(5)*F2(2,1)+4.*PAR(3)*SPH*CPH)*F2(2,1)
F1(1,5) = SP(1)*F1(3,2)*R - PAR(3)*(CPH+SPH)*(CPH-SPH)
F1(2,4) = -F1(2,2)*F1(2,3)
F1(2,5) = -SP(1)*F1(3,1)*R
F1(3,4) = (PAR(1)*F2(2,1)-PAR(2)-PAR(2) + 4.*PAR(3)*PAR(6))*
* F2(2,1)
F1(3,5) = -3.*PAR(3)*SPH*CPH
F2(2,4) = -F1(1,3)*F2(2,1)
F2(3,2) = F2(2,1)/CPH
F2(3,4) = -F1(2,3)*F2(3,2)
F2(3,5) = F1(2,1)/CPH
F3(1,1) = -X( 9)*PAR(4)
F3(2,1) = X(10)*PAR(4)
F3(3,1) = X( 7)*PAR(4)
F3(4,1) = -X( 8)*PAR(4)
F3(1,2) = (X( 8)-X(10)*TPH)*PAR(4)
F3(2,2) = -(X( 7)+X( 9)*TPH)*PAR(4)

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F3(3,2) = (X(10)+X(8)*TPH)*PAR(4)	FXXU0280
F3(4,2) =-(X(9)-X(7)*TPH)*PAR(4)	FXXU0290
F3(1,4) =-F1(1,3)*F3(1,1) - F1(2,3)*F3(1,2)	FXXU0300
F3(2,4) =-F1(1,3)*F3(2,1) - F1(2,3)*F3(2,2)	FXXU0310
F3(3,4) =-F1(1,3)*F3(3,1) - F1(2,3)*F3(3,2)	FXXU0320
F3(4,4) =-F1(1,3)*F3(4,1) - F1(2,3)*F3(4,2)	FXXU0330
F3(1,5) =-X(10)*SP(1)	FXXU0340
F3(2,5) =-X(9)*SP(1)	FXXU0350
F3(3,5) = X(8)*SP(1)	FXXU0360
F3(4,5) = X(7)*SP(1)	FXXU0370
F1(1,7) = 2.*(X(7)*AB(1)-X(10)*AB(2)+X(9)*AB(3))	FXXU0380
F1(1,8) = 2.*(X(8)*AB(1)+X(9)*AB(2)+X(10)*AB(3))	FXXU0390
F1(1,9) = 2.*(-X(9)*AB(1)+X(8)*AB(2)+X(7)*AB(3))	FXXU0400
F1(1,10)=-2.*(X(10)*AB(1)+X(7)*AB(2)-X(8)*AB(3))	FXXU0410
F1(2,7) =-F1(1,10)	FXXU0420
F1(2,8) =-F1(1, 9)	FXXU0430
F1(2,9) = F1(1, 8)	FXXU0440
F1(2,10) = F1(1, 7)	FXXU0450
F1(3,7) = F1(1, 9)	FXXU0460
F1(3,8) =-F1(1,10)	FXXU0470
F1(3,9) =-F1(1, 7)	FXXU0480
F1(3,10) = F1(1, 8)	FXXU0490
F3(2,7) =-F3(1,8)	FXXU0500
F3(3,7) =-F3(1, 9)	FXXU0510
F3(3,8) =-F3(2, 9)	FXXU0520
F3(4,7) =-F3(1,10)	FXXU0530
F3(4,8) =-F3(2,10)	FXXU0540
F3(4,9) =-F3(3,10)	FXXU0550
F2(1,3) = -1.	FXXU0560
F1(1,6) = 0.	FXXU0570
F1(2,6) = 0.	FXXU0580
F1(3,6) = 0.	FXXU0590
F1(3,3) = 0.	FXXU0600
F2(1,1) = 0.	FXXU0610
F2(1,2) = 0.	FXXU0620
F2(1,4) = 0.	FXXU0630
F2(1,5) = 0.	FXXU0640
F2(2,2) = 0.	FXXU0650
F2(2,3) = 0.	FXXU0660
F2(2,5) = 0.	FXXU0670
F2(3,1) = 0.	FXXU0680
F2(3,3) = 0.	FXXU0690
F3(1,3) = 0.	FXXU0700
F3(2,3) = 0.	FXXU0710
F3(3,3) = 0.	FXXU0720
F3(4,3) = 0.	FXXU0730
F3(1,6) = 0.	FXXU0740
F3(2,6) = 0.	FXXU0750
F3(3,6) = 0.	FXXU0760
F3(4,6) = 0.	FXXU0770
F3(1,7)=0.	FXXU0780
F3(2,8)=0.	FXXU0790
F3(3,9)=0.	FXXU0800
F3(4,10)=0.	FXXU0810
LT= 0	FXXU0820
MT=0	FXXU0830
NT = 0	FXXU0840
IF(NSTC) 1,1,6	FXXU0850
1 IF(NPU) 2,99,2	FXXU0860
2 N = NSTX	FXXU0870

NT = 1	FXXU0880
II = 1	FXXU0890
3 NNN = MC(II)	FXXU0900
GO TO 18	FXXU0910
6 N = 10	FXXU0920
II = 1	FXXU0930
9 NNN = NC(II)	FXXU0940
GO TO 18	FXXU0950
12 II = II+1	FXXU0960
IF(NT) 13,13,15	FXXU0970
13 IF(II-NSTC) 9,9,1	FXXU0980
15 IF(II-NPU) 3,3,99	FXXU0990
18 CONTINUE	FXXU1000
IF(NNN.GT.72) GO TO 25	FXXU1010
19 IF(NNN-33) 100,100,20	FXXU1020
20 IF(MT) 21,24,21	FXXU1030
21 CONTINUE	FXXU1040
SP(1) = 0.	FXXU1050
SP(2) = 0.	FXXU1060
SP(3) = 0.	FXXU1070
IF(NNN-59) 150,150,300	FXXU1080
25 DO 26 I=1,3	FXXU1090
F1(I,II+N) = 0.	FXXU1100
F3(I,II+N) = 0.	FXXU1110
26 CONTINUE	FXXU1120
F3(4,II+N) = 0.	FXXU1130
GO TO 12	FXXU1140
24 CONTINUE	FXXU1150
MT=1	FXXU1160
K = 0	FXXU1170
DO 27 I=1,3	FXXU1180
DO 27 J=1,3	FXXU1190
K = K+1	FXXU1200
27 SP(K) = PA(I)*XP(J)	FXXU1210
DTRAN(1,1) = SP(5) + SP(9)	FXXU1220
DTRAN(1,2) = -2.*SP(4) + SP(2)	FXXU1230
DTRAN(1,3) = -2.*SP(7) + SP(3)	FXXU1240
DTRAN(2,1) = SP(4) -2.*SP(2)	FXXU1250
DTRAN(2,2) = SP(1) + SP(9)	FXXU1260
DTRAN(2,3) = -2.*SP(8) + SP(6)	FXXU1270
DTRAN(3,1) = SP(7) -2.*SP(3)	FXXU1280
DTRAN(3,2) = SP(8) - 2.*SP(6)	FXXU1290
DTRAN(3,3) = SP(1) + SP(5)	FXXU1300
GO TO 21	FXXU1310
30 CONTINUE	FXXU1320
SP(1) = SP(1)-XP(3)*DUD(2)+XP(2)*DUD(3)	FXXU1330
SP(2) = SP(2)+XP(3)*DUD(1)-XP(1)*DUD(3)	FXXU1340
SP(3) = SP(3)-XP(2)*DUD(1)+XP(1)*DUD(2)	FXXU1350
33 CONTINUE	FXXU1360
C-----CALCULATE EQ.(172) -----	FXXU1370
SP(1) = SP(1)-DTRAN(1,1)*SP(4)-DTRAN(1,2)*SP(5)-DTRAN(1,3)*SP(6)	FXXU1380
SP(2) = SP(2)-DTRAN(2,1)*SP(4)-DTRAN(2,2)*SP(5)-DTRAN(2,3)*SP(6)	FXXU1390
SP(3) = SP(3)-DTRAN(3,1)*SP(4)-DTRAN(3,2)*SP(5)-DTRAN(3,3)*SP(6)	FXXU1400
36 I = N + II	FXXU1410
IF(L) 39,42,39	FXXU1420
C-----CALCULATE EQ.(169) -----	FXXU1430
39 F3(1,I) = .5*(-X(8)*SP(4)-X(9)*SP(5)-X(10)*SP(6))	FXXU1440
F3(2,I) = .5*(X(7)*SP(4)-X(10)*SP(5)+X(9)*SP(6))	FXXU1450
F3(3,I) = .5*(X(10)*SP(4)+X(7)*SP(5)-X(8)*SP(6))	FXXU1460
F3(4,I) = .5*(-X(9)*SP(4)+X(8)*SP(5)+X(7)*SP(6))	FXXU1470

GO TO 45	FXXU1480
42 F3(1,I) = 0.	FXXU1490
F3(2,I) = 0.	FXXU1500
F3(3,I) = 0.	FXXU1510
F3(4,I) = 0.	FXXU1520
C-----CALCULATE EQ.(167) -----	FXXU1530
45 F1(1,I) = SP(1)*A(1,1) + SP(2)*A(2,1) + SP(3)*A(3,1)	FXXU1540
F1(2,I) = SP(1)*A(1,2) + SP(2)*A(2,2) + SP(3)*A(3,2)	FXXU1550
F1(3,I) = SP(1)*A(1,3) + SP(2)*A(2,3) + SP(3)*A(3,3)	FXXU1560
GO TO 12	FXXU1570
100 CONTINUE	FXXU1580
C-----CALCULATE EQ.(170) -----	FXXU1590
L = 0	FXXU1600
I = NNN - 30	FXXU1610
SP(1) = -TRAN(1,I)	FXXU1620
SP(2) = -TRAN(2,I)	FXXU1630
SP(3) = -TRAN(3,I)	FXXU1640
GO TO 36	FXXU1650
C-----CALCULATE EQ.(173) -----	FXXU1660
C-----CALCULATE EQ.(174) -----	FXXU1670
150 L = 1	FXXU1680
DUD(1) = 0.	FXXU1690
DUD(2) = 0.	FXXU1700
DUD(3) = 0.	FXXU1710
SP(4) = 0.	FXXU1720
SP(5) = 0.	FXXU1730
SP(6) = 0.	FXXU1740
IF(NNN.GE.48) GO TO 250	FXXU1750
IF(NNN.GE.45) GO TO 200	FXXU1760
J = (NNN-33)/3	FXXU1770
K = NNN - 3*J - 32	FXXU1780
DUD(J) = PMDOT(K)	FXXU1790
SP(J+3) = PM(K)	FXXU1800
GO TO 30	FXXU1810
200 CONTINUE	FXXU1820
SP(NNN-41) = 1.	FXXU1830
GO TO 33	FXXU1840
250 J = (NNN-45)/3	FXXU1850
K = NNN - 3*J - 41	FXXU1860
SP(K) = AP(J)	FXXU1870
DUD(K-3) = APDOT(J)	FXXU1880
GO TO 30	FXXU1890
C-----CALCULATE EQ.(176) -----	FXXU1900
300 CONTINUE	FXXU1910
C-----CALCULATE EQ.(175) -----	FXXU1920
DUD(5) = 0.	FXXU1930
DUD(6) = 0.	FXXU1940
DUD(7) = 0.	FXXU1950
J = (NNN-58)/3	FXXU1960
K = NNN - 3*J - 57	FXXU1970
IF(J-3) 301,301,302	FXXU1980
301 SP(J) = AM(K)	FXXU1990
DUD(J+4) = AMDOT(K)	FXXU2000
GO TO 304	FXXU2010
302 SP(K) = 1.	FXXU2020
J = K	FXXU2030
304 CONTINUE	FXXU2040
IF(J-2) 306,308,310	FXXU2050
306 CONTINUE	FXXU2060
I = 3	FXXU2070

GO TO 312	FXXU2080
308 DUD(4) = 0.	FXXU2090
DUD(8) = 0.	FXXU2100
GO TO 316	FXXU2110
310 CONTINUE	FXXU2120
I = 1	FXXU2130
312 CONTINUE	FXXU2140
SP(5) = AP(I)*DUD(J+4) + APDOT(I)*SP(J)	FXXU2150
SP(6) = AP(J)*SP(J)	FXXU2160
SP(7) = AP(J)*DUD(J+4) + APDOT(J)*SP(J)	FXXU2170
DUD(4) = (AP(4)/AP(J))**3*SP(J)*.25	FXXU2180
IF(LT) 314,313,314	FXXU2190
313 CONTINUE	FXXU2200
LT=1	FXXU2210
SP(9) = AP(1)**2 + AP(3)**2	FXXU2220
SPD(5) = SQRT(SP(9))	FXXU2230
SPD(1) = 2./SPD(5)	FXXU2240
SPD(2) = -(AP(1)*APDOT(3)+AP(3)*APDOT(1))*SPD(1)/SP(9)	FXXU2250
SPD(3) = -AP(4)/SP(9)	FXXU2260
SPD(4) = -(AP(1)*APDOT(1)+AP(3)*APDOT(3))/SP(9)	FXXU2270
SPD(5) = 2.*SPD(4)*SPD(3)	FXXU2280
C-----CALCULATE EQ.(181) -----	FXXU2290
314 DUD(8) = SPD(1)*SP(5) + (SPD(2)+SPD(5))*SP(6) + SPD(3)*SP(7) +	FXXU2300
* SPD(4)*DUD(4)	FXXU2310
316 CONTINUE	FXXU2320
DO 320 I=1,3	FXXU2330
SP(7) = CX(I,4)*DUD(4)	FXXU2340
SP(8) = CX(I,4)*DUD(8)	FXXU2350
DO 318 J=1,3	FXXU2360
SP(7) = SP(7)+CX(I,J)*SP(J)	FXXU2370
318 SP(8) = SP(8)+CX(I,J)*DUD(J+4)	FXXU2380
SP(I+3) = SP(7)	FXXU2390
320 DUD(I) = SP(8)	FXXU2400
L = 1	FXXU2410
GO TO 30	FXXU2420
99 RETURN	FXXU2430
END	FXXU2440


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SUBROUTINE INDAT
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG ,KI ,KK
6 ,KN ,KOB ,KPROP ,KS ,KSM ,KSS ,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TG(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
DATA CONV /.3648/
REWIND FIT
REWIND PQR
REWIND SCRACH
REWIND STATE
WRITE(OUT,1030)
1030 FORMAT(1H1,22H DATA ANALYSIS PROGRAM//11H INPUT DATA//)
8 READ(IN,1000) KDUM,(B(I),I=1,8)
1000 FORMAT(I2,7A10,A8)
WRITE(OUT,1001) KDUM,(B(I),I=1,8)
1001 FORMAT(5X,I2,5X,7A10,5X,A8)
IF(KDUM) 7,8,9
7 CALL EXIT
9 GO TO ( 8,20,30,40,50,60,70,80,90,100,110,120,130,140,150,160,170,
X180,190,200),KDUM
20 DECODE(40,1002,B) (NPC(I),I=1,10)
1002 FORMAT(10I4)
IF(NPC(2).EQ.0) GO TO 8
XMU = XMU/CONV**3
REO = REO/CONV
RPO = RPO/CONV
GO TO 8
30 DECODE(30,1003,B) IPC,IDN,SP(1),SP(2)
1003 FORMAT(I2,I4,E12.4,E12.4)
GO TO (32,34,36,38,39),IPC
32 NST=NST+1
ZO(IDN)=SP(1)

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	P(IDN, IDN)=SP(2)**2	INDT0280
	GO TO 8	INDT0290
34	NSTC = NSTC + 1	INDT0300
	NC(NSTC) = IDN	INDT0310
	C(IDN)=SP(1)	INDT0320
	P(NSTC+10, NSTC+10) = SP(2)**2	INDT0330
	GO TO 8	INDT0340
36	NPU=NPU+1	INDT0350
	MC(NPU)=IDN	INDT0360
	C(IDN)=SP(1)	INDT0370
	D(NPU)=SP(2)**2	INDT0380
	GO TO 8	INDT0390
38	NPV=NPV+1	INDT0400
	MCC(NPV)=IDN	INDT0410
	C(IDN)=SP(1)	INDT0420
	S(NPV)=SP(2)**2	INDT0430
	GO TO 8	INDT0440
39	C(IDN) = SP(1)	INDT0450
	GO TO 8	INDT0460
40	DECODE(54, 1004, B) TO, DET, DCOMP, TFINAL	INDT0470
1004	FORMAT(6X, 4E12.4)	INDT0480
	GO TO 8	INDT0490
50	DECODE(42, 1005, B) IPC, SP(1), SP(2), SP(3)	INDT0500
1005	FORMAT(12, 4X, 3E12.4)	INDT0510
	IF(IPC.EQ.2) GO TO 54	INDT0520
52	XMU=SP(2)	INDT0530
	XJ2 = SP(3)	INDT0540
	GO TO 8	INDT0550
54	RPO = SP(1)	INDT0560
	REQ = SP(2)	INDT0570
	OMEGA=SP(3)	INDT0580
	GO TO 8	INDT0590
60	DECODE(6, 1006, B) IPC, NPTS	INDT0600
1006	FORMAT(12, I4)	INDT0610
	GO TO(62, 64, 66), IPC	INDT0620
62	READ(IN, 1031) (TXCG(I), XXCG(I), I=1, NPTS)	INDT0630
	WRITE(OUT, 1031) (TXCG(I), XXCG(I), I=1, NPTS)	INDT0640
1031	FORMAT(6E12.4)	INDT0650
	N8(1)=NPTS	INDT0660
	GO TO 8	INDT0670
64	READ(IN, 1031) (TYCG(I), XYCG(I), I=1, NPTS)	INDT0680
	WRITE(OUT, 1031) (TYCG(I), XYCG(I), I=1, NPTS)	INDT0690
	N9(1)=NPTS	INDT0700
	GO TO 8	INDT0710
66	READ(IN, 1031) (TZCG(I), XZCG(I), I=1, NPTS)	INDT0720
	WRITE(OUT, 1031) (TZCG(I), XZCG(I), I=1, NPTS)	INDT0730
	N10(1)=NPTS	INDT0740
	GO TO 8	INDT0750
70	DECODE(68, 1007, B) IDN, SP(1), SP(2), SP(3), LT, MT, NT, SP(4), SP(5), SP(6)	INDT0760
1007	FORMAT(12, 3E10.4, 3I2, 3E10.4)	INDT0770
	NSTA=NSTA+1	INDT0780
	NS(NSTA) = IDN	INDT0790
	DTI(NSTA)=SP(1)	INDT0800
	DTF(NSTA)=SP(2)	INDT0810
	DFIT(NSTA)=SP(3)	INDT0820
	MR(1, NSTA)=LT	INDT0830
	MR(2, NSTA)=MT	INDT0840
	MR(3, NSTA)=NT	INDT0850
	SYG(1, NSTA)=SP(4)	INDT0860
	SYG(2, NSTA)=SP(5)	INDT0870

SYG(3,NSTA)=SP(6)	INDT0880
GO TO 8	INDT0890
80 DECODE(6,1006,B) IPC,IDN	INDT0900
IF(IDN) 81,83,81	INDT0910
81 READ(IN,1032) KDATA	INDT0920
IF(KDATA.LE.0) GO TO 82	INDT0930
READ(IN,1032) (K,MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1,3),	INDT0940
* I=1,KDATA)	INDT0950
WRITE(FIT) KDATA,(MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1,	INDT0960
X3),I=1,KDATA)	INDT0970
GO TO 81	INDT0980
1032 FORMAT(2I2,7E10.2)	INDT0990
82 CONTINUE	INDT1000
K = 0	INDT1010
WRITE(FIT)KDATA,K,K,K,K,K,K,K,K	INDT1020
REWIND FIT	INDT1030
83 IF(IPC) 84,8,84	INDT1040
84 READ(FIT) KDATA,(MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1,	INDT1050
X3),I=1,KDATA)	INDT1060
WRITE(OUT,1033)KDATA,(MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1	INDT1070
X,3),I=1,KDATA)	INDT1080
1033 FORMAT(2I4,7E16.7/(4X,I4,7E16.7))	INDT1090
IF(KDATA) 84,85,84	INDT1100
85 REWIND FIT	INDT1110
GO TO 8	INDT1120
90 DECODE(6,1006,B) IPC,IDN	INDT1130
IF(IDN) 91,93,91	INDT1140
91 READ(IN,1034) KDAP	INDT1150
IF(KDAP.LE.0) GO TO 92	INDT1160
READ(IN,1034) (K,TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=1,	INDT1170
* KDAP)	INDT1180
WRITE(PQR)KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=1,	INDT1190
* KDAP)	INDT1200
GO TO 91	INDT1210
1034 FORMAT(I2,7E10.2)	INDT1220
92 CONTINUE	INDT1230
K = 0	INDT1240
WRITE(PQR) KDAP,K,K,K,K,K,K,K,K	INDT1250
REWIND PQR	INDT1260
93 IF(IPC) 94,8,94	INDT1270
94 READ(PQR) KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=1,KDAP	INDT1280
X)	INDT1290
WRITE(OUT,1035) KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=	INDT1300
X1,KDAP)	INDT1310
1035 FORMAT(I4,7E16.7/(4X,7E16.7))	INDT1320
IF(KDAP) 94,95,94	INDT1330
95 REWIND PQR	INDT1340
GO TO 8	INDT1350
100 DECODE(6,1006,B) IPC,NPTS	INDT1360
NSTX = NST+NSTC	INDT1370
GO TO (101,102,103,104,106,108),IPC	INDT1380
101 READ(IN,1031) ((P(I,J),J=1,NSTX),I=1,NSTX)	INDT1390
WRITE(OUT,1031) ((P(I,J),J=1,NSTX),I=1,NSTX)	INDT1400
GO TO 8	INDT1410
102 READ(IN,1031) ((CUZ(I,J),J=1,NPU),I=1,NSTX)	INDT1420
WRITE(OUT,1031) ((CUZ(I,J),J=1,NPU),I=1,NSTX)	INDT1430
GO TO 8	INDT1440
103 READ(IN,1031) ((CVZ(I,J),J=1,NPV),I=1,NSTX)	INDT1450
WRITE(OUT,1031) ((CVZ(I,J),J=1,NPV),I=1,NSTX)	INDT1460
GO TO 8	INDT1470

104 DO 105 I=1,NPTS	
READ(IN,1036) LT,MT,P(LT,MT)	INDT1480
P(MT,LT)=P(LT,MT)	INDT1490
1036 FORMAT(4X,2I4,E12.4)	INDT1500
105 WRITE(OUT,1037) LT,MT,P(LT,MT)	INDT1510
1037 FORMAT(10X,2HP(,I3,1H,I3,3H) =E15.8)	INDT1520
GO TO 8	INDT1530
106 DO 107 I=1,NPTS	INDT1540
READ(IN,1036) LT,MT,CUZ(LT,MT)	INDT1550
107 WRITE(OUT,1038) LT,MT,CUZ(LT,MT)	INDT1560
1038 FORMAT(8X,4HCUZ(,I3,1H,I3,3H) =E15.8)	INDT1570
GO TO 8	INDT1580
108 DO 109 I=1,NPTS	INDT1590
READ(IN,1036) LT,MT,CVZ(LT,MT)	INDT1600
109 WRITE(OUT,1039) LT,MT,CVZ(LT,MT)	INDT1610
1039 FORMAT(8X,4HCVZ(,I3,1H,I3,3H) =E15.8)	INDT1620
GO TO 8	INDT1630
110 GO TO 8	INDT1640
120 GO TO 8	INDT1650
130 GO TO 8	INDT1660
140 GO TO 8	INDT1670
150 GO TO 8	INDT1680
160 GO TO 8	INDT1690
170 GO TO 8	INDT1700
180 GO TO 8	INDT1710
190 GO TO 8	INDT1720
200 RETURN	INDT1730
END	INDT1740
	INDT1750

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SUBROUTINE INTAG
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUK ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR,JNBRS,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
2 LRK = 4
6 CALL RKUTTA
IF(LRK-2) 8,10,99
8 CALL DATAB
CALL MOTION
IF(NPC(1)-1) 12,6,12
10 IF(DCOMP.GE.0..OR.NPC(10).EQ.0.OR.T.EQ.TSAV) GO TO 6
WRITE(STATE) T,X
TSAV=T
GO TO 6
12 CALL FXXU
DO 22 I=1,4
N = NSTX+NPU
DO 22 J=1,N
IF(J-10) 13,13,14
13 CONTINUE
SUM = 0.
SUM2= 0.
GO TO 15
14 SUM = F1(I,J)
SUM2= F3(I,J)
15 DO 16 K=1,10
16 SUM2 = SUM2 + F3(I,K)*PH(K,J)
DPH(I+6,J) = SUM2
IF(I.EQ.4) GO TO 22
DO 18 K=1,10
18 SUM = SUM + F1(I,K)*PH(K,J)

```

```
DPH(I,J) = SUM
SUM = 0.
DO 20 K=1,5
20 SUM = SUM + F2(I,K)*PH(K,J)
DPH(I+3,J) = SUM
22 CONTINUE
GO TO 6
99 RETURN
END
```

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INTG0280
INTG0290
INTG0300
INTG0310
INTG0320
INTG0330
INTG0340
INTG0350
INTG0360
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SUBROUTINE MINVAR
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA,NSTC,NSTX ,NT,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
G(1,10) = 0.
G(2,10) = 0.
G(3,10) = 0.
NT = 0
LT = 1
MT = NSTX
DO 1 I=1,NSTX
P(I,10) = 0.
1 P(10,I) = 0.
2 DO 12 J=KAR,KOB
DO 6 I=LT,MT
L = I+1
SUM = 0.
DO 3 K=LT,I
3 SUM = SUM + P(K,I)*G(J,K)
IF(L.GT.MT) GO TO 6
DO 4 K=L,MT
4 SUM = SUM+P(I,K)*G(J,K)
6 DUB(I,J) = SUM
C-----CALCULATE EQ.(54F) -----
DO 10 I=KAR,KOB
SUM = 0.
DO 8 K=LT,MT
8 SUM = SUM+G(I,K)*DUB(K,J)
10 DUB(I,J+6) = SUM
12 DUB(J,J+6) = DUB(J,J+6)+SI(J)**2
IF(NPV) 36,36,14

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```

COMM0010
COMM0020
COMM0030
COMM0040
COMM0050
COMM0060
COMM0070
COMM0080
COMM0090
COMM0100
COMM0110
COMM0120
COMM0130
COMM0140
COMM0150
COMM0160
COMM0170
COMM0180
COMM0190
COMM0200
COMM0210
COMM0220
COMM0230
COMM0240
COMM0250
COMM0260
COMM0270
COMM0280
COMM0290
COMM0300
COMM0310
MINV0010
MINV0020
MINV0030
MINV0040
MINV0050
MINV0060
MINV0070
MINV0080
MINV0090
MINV0100
MINV0110
MINV0120
MINV0130
MINV0140
MINV0150
MINV0160
MINV0170
MINV0180
MINV0190
MINV0200
MINV0210
MINV0220
MINV0230
MINV0240
MINV0250
MINV0260
MINV0270

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14 CONTINUE	MINV0280
DO 15 I=1,NPV	MINV0290
15 CVZ(10,I) = 0.	MINV0300
DO 20 J=KAR,KOB	MINV0310
DO 17 I=1,NSTX	MINV0320
SUM= 0.	MINV0330
DO 16 K=1,NPV	MINV0340
16 SUM= SUM+CVZ(I,K)*H(J,K)	MINV0350
DUB(I,J+3) = SUM	MINV0360
17 DUB(I,J) = DUB(I,J)+SUM	MINV0370
DO 18 I=1,NPV	MINV0380
18 DUB(I+12,J+6) = S(I)*H(J,I)	MINV0390
20 CONTINUE	MINV0400
DO 26 J=KAR,KOB	MINV0410
DO 24 I=KAR,KOB	MINV0420
SUM = 0.	MINV0430
SUM2= 0.	MINV0440
DO 22 K=LT,MT	MINV0450
22 SUM = SUM + DUB(K,J+3)*G(I,K)	MINV0460
DO 23 K=1,NPV	MINV0470
23 SUM2= SUM2+ H(I,K)*DUB(K+12,J+6)	MINV0480
DUB(J+3,I+6) = SUM	MINV0490
24 DUB(I+6,J+6) = SUM + SUM2	MINV0500
26 CONTINUE	MINV0510
DO 34 J=KAR,KOB	MINV0520
DO 28 I=KAR,KOB	MINV0530
28 DUB(I,J+6) = DUB(I,J+6) + DUB(I+3,J+6) + DUB(I+6,J+6)	MINV0540
DO 32 I=1,NPV	MINV0550
SUM = 0.	MINV0560
DO 30 K=LT,MT	MINV0570
30 SUM = SUM + G(J,K)*CVZ(K,I)	MINV0580
32 DUB(I,J+9) = SUM	MINV0590
34 CONTINUE	MINV0600
36 CONTINUE	MINV0610
IF(KAR-KOB) 37,46,37	MINV0620
37 CONTINUE	MINV0630
DO 39 J=KAR,KOB	MINV0640
DO 38 I=KAR,KOB	MINV0650
38 DUB(I+9,J+6) = 0.	MINV0660
39 DUB(J+9,J+6) = 1.	MINV0670
L = KOB-1	MINV0680
DO 42 I=KAR,L	MINV0690
M = I+1	MINV0700
SUM = DUB(I,I+6)	MINV0710
DO 42 J=KAR,KOB	MINV0720
DUB(I ,J+6) = DUB(I ,J+6)/SUM	MINV0730
DUB(I+9,J+6) = DUB(I+9,J+6)/SUM	MINV0740
DO 42 K=M,KOB	MINV0750
IF(I-J) 40,41,40	MINV0760
40 DUB(K ,J+6) = DUB(K ,J+6)-DUB(K,I+6)*DUB(I ,J+6)	MINV0770
41 DUB(K+9,J+6) = DUB(K+9,J+6)-DUB(K,I+6)*DUB(I+9,J+6)	MINV0780
42 CONTINUE	MINV0790
DO 44 I=KAR,KOB	MINV0800
44 DUB(KOB+9,I+6) = DUB(KOB+9,I+6)/DUB(KOB,KOB+6)	MINV0810
DO 45 I=KAR,L	MINV0820
M = KOB+KAR+6-I	MINV0830
DO 45 J=1,L	MINV0840
N = KOB+KAR+8-J	MINV0850
DO 45 K=KAR,KOB	MINV0860
45 DUB(N,K+6) = DUB(N,K+6)-DUB(N-9 ,M)*DUB(M+3,K+6)	MINV0870

GO TO 48	MINV0880
46 DUB(KAR+9,KAR+6) = 1./DUB(KAR,KAR+6)	MINV0890
48 CONTINUE	MINV0900
C-----CALCULATE EQ.(54E)-----	MINV0910
DO 54 I=1,NSTX	MINV0920
DO 51 J=KAR,KCB	MINV0930
SUM = 0.	MINV0940
DO 50 K=KAR,KCB	MINV0950
50 SUM = SUM + DUB(I,K)*DUB(K+9,J+6)	MINV0960
51 DUB(I,J+12) = SUM	MINV0970
DO 54 L=I,NSTX	MINV0980
SUM = 0.	MINV0990
C-----CALCULATE EQ.(54B)-----	MINV1000
DO 52 K=KAR,KCB	MINV1010
52 SUM = SUM + DUB(I,K+12)*DUB(L,K)	MINV1020
P(I,L) = P(I,L) - SUM	MINV1030
54 CONTINUE	MINV1040
IF(NPU) 66,66,56	MINV1050
C-----CALCULATE EQ.(54C)-----	MINV1060
56 CONTINUE	MINV1070
DO 57 I=1,NPU	MINV1080
57 CUZ(10,I) = 0.	MINV1090
DO 64 J=1,NPU	MINV1100
DO 60 I=KAR,KCB	MINV1110
SUM = 0.	MINV1120
DO 58 K=1,NSTX	MINV1130
58 SUM = SUM + G(I,K)*CUZ(K,J)	MINV1140
60 DUB(I,1) = SUM	MINV1150
DO 64 I=1,NSTX	MINV1160
SUM = 0.	MINV1170
DO 62 K=KAR,KCB	MINV1180
62 SUM = SUM + DUB(I,K+12)*DUB(K,1)	MINV1190
64 CUZ(I,J) = CUZ(I,J)-SUM	MINV1200
66 IF(NPV) 72,72,67	MINV1210
C-----CALCULATE EQ.(54D)-----	MINV1220
67 DO 70 I=1,NSTX	MINV1230
DO 70 J=1,NPV	MINV1240
SUM = 0.	MINV1250
DO 68 K=KAR,KCB	MINV1260
68 SUM = SUM + DUB(I,K+12)*(DUB(J,K+9)+DUB(J+12,K+6))	MINV1270
70 CVZ(I,J) = CVZ(I,J) - SUM	MINV1280
72 IF(NPC(1)-2) 74,108,74	MINV1290
74 IF(NPC(4)) 75,88,75	MINV1300
75 DO 82 I=1,NSTX	MINV1310
80 DUB(I,1) = DZ(I)	MINV1320
82 CONTINUE	MINV1330
C-----CALCULATE EQ.(54A)-----	MINV1340
DO 86 I=KAR,KCB	MINV1350
SUM = 0.	MINV1360
DO 84 J=1,NSTX	MINV1370
84 SUM = SUM + G(I,J)*DUB(J,1)	MINV1380
86 DATC(1) = DATC(I)+SUM	MINV1390
88 DO 90 I=KAR,KCB	MINV1400
J = LC(I)	MINV1410
DUB(I,2) = DATA(J)-DATC(I)	MINV1420
IF(MTYP.GT.5) GO TO 90	MINV1430
IF(J.EQ.1) GO TO 90	MINV1440
IF(ABS(DUB(I,2)).LT.3.1416) GO TO 90	MINV1450
DUB(I,2) = DUB(I,2)-SIGN(6.283185307179586,DUB(I,2))	MINV1460
90 CONTINUE	MINV1470

DO 92 I=1,NSTX	MINV1480
DZ(I) = 0.	MINV1490
DO 92 J=KAR,KCB	MINV1500
92 DZ(I) = DZ(I)+DUB(I,J+12)*DUB(J,2)	MINV1510
IF(NPC(4)) 294,298,294	MINV1520
294 DO 296 I=1,4	MINV1530
296 V0(I) = X(I+6) + DUB(I+6,1)	MINV1540
DZ(10) = -(V0(1)*DZ(7)+V0(2)*DZ(8)+V0(3)*DZ(9))/V0(4)	MINV1550
94 DO 96 I=1,NSTX	MINV1560
96 DZ(I) = DZ(I)+DUB(I,1)	MINV1570
GO TO 108	MINV1580
298 DZ(10) = -(X(7)*DZ(7)+X(8)*DZ(8)+X(9)*DZ(9))/X(10)	MINV1590
98 DO 100 I=1,10	MINV1600
100 X(I) = X(I)+DZ(I)	MINV1610
DATC(1) = SQRT(X(7)**2 + X(8)**2 + X(9)**2 + X(10)**2)	MINV1620
X(7) = X(7)/DATC(1)	MINV1630
X(8) = X(8)/DATC(1)	MINV1640
X(9) = X(9)/DATC(1)	MINV1650
X(10) = X(10)/DATC(1)	MINV1660
IF(NSTC.EQ.0) GO TO 103	MINV1670
DO 102 I=1,NSTC	MINV1680
J = NC(I)	MINV1690
102 C(J) = C(J)+DZ(I+10)	MINV1700
103 CONTINUE	MINV1710
IF(KSS) 108,108,104	MINV1720
104 DO 106 I=1,KSS	MINV1730
MTYP = NSS(I)	MINV1740
106 CALL STAT	MINV1750
108 P(8,7) = P(7,8)	MINV1760
P(9,7) = P(7,9)	MINV1770
P(9,8) = P(8,9)	MINV1780
DO 110 I=1,9	MINV1790
SUM = P(I,7)*X(7) + P(I,8)*X(8) + P(I,9)*X(9)	MINV1800
110 P(I,10) = -SUM/X(10)	MINV1810
P(10,10) = -(X(7)*P(7,10)+X(8)*P(8,10)+X(9)*P(9,10))/X(10)	MINV1820
DO 114 I=11,NSTX	MINV1830
SUM = P(7,I)*X(7) + P(8,I)*X(8) + P(9,I)*X(9)	MINV1840
114 P(10,I) = -SUM/X(10)	MINV1850
IF(NPU.EQ.0) GO TO 117	MINV1860
115 DO 116 I=1,NPU	MINV1870
SUM = CUZ(7,I)*X(7) + CUZ(8,I)*X(8) + CUZ(9,I)*X(9)	MINV1880
116 CUZ(10,I) = -SUM/X(10)	MINV1890
117 IF(NPV.EQ.0) GO TO 99	MINV1900
DO 118 I=1,NPV	MINV1910
SUM = CVZ(7,I)*X(7) + CVZ(8,I)*X(8) + CVZ(9,I)*X(9)	MINV1920
118 CVZ(10,I) = -SUM/X(10)	MINV1930
99 CONTINUE	MINV1940
RETURN	MINV1950
END	MINV1960

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SUBROUTINE MOTION
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,I1 ,IP ,IPC ,JU ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG ,KI ,KK
6 ,KN ,KOB ,KPROP ,KS ,KSM ,KSS ,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
LT = 0
1 CONTINUE
CPH = COS(X(5))
SPH = SIN(X(5))
TPH = SPH/CPH
R = REO + X(4)
C-----CALCULATE EQ.(159) -----
AP(1) = C(61)*AM(1)+C(62)*AM(2)+C(63)*AM(3)+C(70)
AP(2) = C(64)*AM(1)+C(65)*AM(2)+C(66)*AM(3)+C(71)
AP(3) = C(67)*AM(1)+C(68)*AM(2)+C(69)*AM(3)+C(72)
C-----CALCULATE EQ.(155) -----
AP(4) = SQRT(AP(1)**2+ AP(3)**2)
IF(AP(4)) 9,9,7
7 CONTINUE
AP(4) = 2.*AP(1)*AP(3)/AP(4)
9 CONTINUE
C-----CALCULATE EQ.(154) -----
DO 11 I=1,3
J = 3*I
PA(I)=C(J+33)*PM(1)+C(J+34)*PM(2)+C(J+35)*PM(3)+C(I+44)+C(I+47)*
X AP(1) + C(I+50)*AP(2) + C(I+53)*AP(3) + C(I+56)*AP(4)
11 CONTINUE
C-----CALCULATE EQ.(153) -----
XP(1) = CGM(1) + C(31)
XP(2) = CGM(2) + C(32)
XP(3) = CGM(3) + C(33)
I=N11(2)

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IF(N11(2)-1)10,10,12
10 I = 2
12 CONTINUE
SP(1)= TT(I+1)-TT(I-1)
HI(2)= .5*SP(1)
HI(1)= T + HI(2)
HI(2)= T - HI(2)
PMDOT(1)= (TAB(HI(1),N11(1),TT(1),TP(1))-TAB(HI(2),N11(1),TT(1),TP(1)))/SP(1)
PMDOT(2)= (TAB(HI(1),N11(1),TT(1),TQ(1))-TAB(HI(2),N11(1),TT(1),TQ(1)))/SP(1)
PMDOT(3)= (TAB(HI(1),N11(1),TT(1),TR(1))-TAB(HI(2),N11(1),TT(1),TR(1)))/SP(1)
AMDOT(1)= (TAB(HI(1),N11(1),TT(1),AX(1))-TAB(HI(2),N11(1),TT(1),AX(1)))/SP(1)
AMDOT(2)= (TAB(HI(1),N11(1),TT(1),AY(1))-TAB(HI(2),N11(1),TT(1),AY(1)))/SP(1)
AMDOT(3)= (TAB(HI(1),N11(1),TT(1),AZ(1))-TAB(HI(2),N11(1),TT(1),AZ(1)))/SP(1)
C-----CALCULATE EQ.(156) -----
APDOT(1) = C(61)*AMDOT(1) + C(62)*AMDOT(2) + C(63)*AMDOT(3)
APDOT(2) = C(64)*AMDOT(1) + C(65)*AMDOT(2) + C(66)*AMDOT(3)
APDOT(3) = C(67)*AMDOT(1) + C(68)*AMDOT(2) + C(69)*AMDOT(3)
C-----CALCULATE EQ.(157) -----
APDOT(4) = (APDOT(1))*((1.-(AP(4)/(2.*AP(3)))**2)/AP(1))
X + APDOT(3))*((1.-(AP(4)/(2.*AP(1)))**2)/AP(3))*AP(4)
C-----CALCULATE EQ.(156) -----
13 DO 14 I=1,3
J = 3*I
PDOT(I) = C(J+33)*PMDOT(1) + C(J+34)*PMDOT(2) + C(J+35)*PMDOT(3)
X + C(I+47)*APDOT(1) + C(I+50)*APDOT(2) + C(I+53)*APDOT(3)
Y + C(I+56)*APDOT(4)
14 CONTINUE
C-----CALCULATE EQ.(146) -----
SP(1) = PA(1)**2
SP(2) = PA(2)**2
SP(3) = PA(3)**2
TRAN(1,1)=-SP(2)-SP(3)
TRAN(1,2)= PA(1)*PA(2)-PDOT(3)
TRAN(1,3)= PA(1)*PA(3)+PDOT(2)
TRAN(2,1)= PA(1)*PA(2)+PDOT(3)
TRAN(2,2)=-SP(1)-SP(3)
TRAN(2,3)= PA(2)*PA(3)-PDOT(1)
TRAN(3,1)= PA(1)*PA(3)-PDOT(2)
TRAN(3,2)= PA(2)*PA(3)+PDOT(1)
TRAN(3,3)=-SP(1)-SP(2)
AB(1) = AP(1)-TRAN(1,1)*XP(1)-TRAN(1,2)*XP(2)-TRAN(1,3)*XP(3)
AB(2) = AP(2)-TRAN(2,1)*XP(1)-TRAN(2,2)*XP(2)-TRAN(2,3)*XP(3)
AB(3) = AP(3)-TRAN(3,1)*XP(1)-TRAN(3,2)*XP(2)-TRAN(3,3)*XP(3)
C-----CALCULATE EQ.(133) -----
SP(1) = (X( 7)-X( 8))*(X( 7)+X( 8))
SP(2) = (X( 9)-X(10))*(X( 9)+X(10))
A(1,1) = (X( 7)-X( 9))*(X( 7)+X( 9)) + (X( 8)-X(10))*(X( 8)+X(10))
A(2,2) = SP(1) + SP(2)
A(3,3) = SP(1) - SP(2)
A(1,2) = 2.*(X( 8)*X( 9)+X( 7)*X(10))
A(2,1) = 2.*(X( 8)*X( 9)-X( 7)*X(10))
A(1,3) = 2.*(X( 8)*X(10)-X( 7)*X( 9))
A(3,1) = 2.*(X( 8)*X(10)+X( 7)*X( 9))
A(3,2) = 2.*(X(10)*X( 9)-X( 7)*X( 8))

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MOTN0280
MOTN0290
MOTN0300
MOTN0310
MOTN0320
MOTN0330
MOTN0340
MOTN0350
MOTN0360
MOTN0370
MOTN0380
MOTN0390
MOTN0400
MOTN0410
MOTN0420
MOTN0430
MOTN0440
MOTN0450
MOTN0460
MOTN0470
MOTN0480
MOTN0490
MOTN0500
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MOTN0680
MOTN0690
MOTN0700
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MOTN0770
MOTN0780
MOTN0790
MOTN0800
MOTN0810
MOTN0820
MOTN0830
MOTN0840
MOTN0850
MOTN0860
MOTN0870

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A(2,3) = 2.*(X(10)*X(9)+X(7)*X(8))	MOTN0880
IF(LT) 15,15,99	MOTN0890
15 CONTINUE	MOTN0900
C-----CALCULATE EQ.(132)-----	MOTN0910
AG(1) = AB(1)*A(1,1)+AB(2)*A(2,1)+AB(3)*A(3,1)	MOTN0920
AG(2) = AB(1)*A(1,2)+AB(2)*A(2,2)+AB(3)*A(3,2)	MOTN0930
AG(3) = AB(1)*A(1,3)+AB(2)*A(2,3)+AB(3)*A(3,3)	MOTN0940
C PARAMETERS USED FREQUENTLY IN REMAINING SUBROUTINES	MOTN0950
PAR(1) = X(1)*X(1) + X(2)*X(2)	MOTN0960
PAR(2)=XMU/R**2	MOTN0970
PAR(3)=XMUJ/R**4	MOTN0980
PAR(4) = 1./(2.*R)	MOTN0990
PAR(5) = X(1)*X(3)-X(2)*X(2)*TPH	MOTN1000
PAR(6) = 1. - 1.5*CPH*CPH	MOTN1010
F1(2,2)= (X(1)*TPH+X(3))/R	MOTN1020
F1(2,3)= X(2)/R	MOTN1030
F1(2,1)= F1(2,3)*TPH	MOTN1040
DX(5) = X(1)/R	MOTN1050
F3(1,8) =-.5*(PA(1)-F1(2,3))	MOTN1060
F3(1,9) =-.5*(PA(2)+DX(5))	MOTN1070
F3(1,10)=-.5*(PA(3)+F1(2,1))	MOTN1080
F3(2,9) = F3(1,10) + PA(3)	MOTN1090
F3(2,10)= F3(1,9) + DX(5)	MOTN1100
F3(3,10)= F3(1,8) + PA(1)	MOTN1110
C-----CALCULATE EQ.(127)-----	MOTN1120
DX(1) = AG(1) + PAR(5)/R - PAR(3)*SPH*CPH	MOTN1130
DX(2) = AG(2) + X(2)*F1(2,2)	MOTN1140
DX(3) = AG(3) + PAR(2) - PAR(1)/R - PAR(3)*PAR(6)	MOTN1150
C-----CALCULATE EQ.(128)-----	MOTN1160
DX(4) = -X(3)	MOTN1170
DX(6) = F1(2,3)/CPH - OMEGA	MOTN1180
C-----CALCULATE EQ.(129)-----	MOTN1190
DX(7) = X(8)*F3(1, 8) + X(9)*F3(1, 9) + X(10)*F3(1,10)	MOTN1200
DX(8) =-X(7)*F3(1, 8) + X(9)*F3(2, 9) + X(10)*F3(2,10)	MOTN1210
DX(9) =-X(7)*F3(1, 9) - X(8)*F3(2, 9) + X(10)*F3(3,10)	MOTN1220
DX(10) =-X(7)*F3(1,10) - X(8)*F3(2,10) - X(9)*F3(3,10)	MOTN1230
99 RETURN	MOTN1240
ENTRY AUXIL	MOTN1250
LT = 1	MOTN1260
GO TO 1	MOTN1270
END	MOTN1280

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SUBROUTINE OBSERV
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR,JNBRS,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
DIMENSION CTM(6) ,RCC(3) ,RCDC(3) ,RCDX(3,6),RCX(3,6) ,
A XA(5) ,XAX(5,7) ,XC(3) ,XCX(3,7) ,XLB(3) ,XLB(3) ,
B XLGE(3,4),XLGX(2,4),XS(3) ,XSC(3) ,XSD(3) ,XSDC(3) ,
C XSDX(3,6),XSX(3,3) ,CI(3,3) ,CJ(3,3)
EQUIVALENCE (DPH(1,1) ,CTM(1) ) , (DPH(7,1) ,RCC(1) ) ,
N (DPH(10,1),RCDC(1) ) , (DPH(3,2) ,RCDX(1,1)) ,
O (DPH(1,4) ,RCX(1,1) ) , (DPH(9,5) ,XA(1) ) ,
P (DPH(4,6) ,XAX(1,1) ) , (DPH(9,9) ,XC(1) ) ,
G (DPH(2,10),XCX(1,1) ) , (DPH(3,12),XLB(1) ) ,
R (DPH(6,12),XLG(1) ) , (DPH(9,12),XLGE(1,1)) ,
S (DPH(1,14),XLGX(1,1)) , (DPH(9,14),XS(1) ) ,
T (DPH(2,15),XSC(1) ) , (DPH(5,15),XSD(1) ) ,
U (DPH(8,15),XSDC(1) ) , (DPH(1,16),XSDX(1,1)) ,
V (DPH(9,17),XSX(1,1) ) , (DPH(8,18),CI(1,1) ) ,
W (DPH(7,19),CJ(1,1) ) , (DPH(6,20),CAZC ) ,
X (DPH(7,20),CDP ) , (DPH(8,20),COY ) ,
Y (DPH(9,20),CELC ) , (DPH(10,20),CGR ) ,
Z (DPH(1,21),CLR ) , (DPH(2,21),CTH ) ,
1 (DPH(3,21),SAZC ) , (DPH(4,21),SDP ) ,
2 (DPH(5,21),SDY ) , (DPH(6,21),SELC ) ,
3 (DPH(7,21),SGR ) , (DPH(8,21),SLR ) ,
4 (DPH(9,21),STH ) , (DPH(10,21),THETA )
IF(L1-2) 14,10,14
10 IF(NPC(5)) 14,12,14
12 WRITE(OUT,1000)
1000 FORMAT(5X,6HPCINTS,5X,4HTYPE,4X,4HTIME,8X,5HCOMP1,10X,5HCOMP2,10X,
15HCOMP3,10X,4HSIG1,11X,4HSIG2,11X,4HSIG3)

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L1=1
14 IF(MTYP=6) 16,150,15
15 IF(MTYP=8) 115,120,125
16 N = 60+MTYP*15
C-----CALCULATE EQ.(236)-----
100 THETA=X(6)-C(N+14)
    STH=SIN(THETA)
    CTH=COS(THETA)
    VO(1)= CPH*CPHDT(MTYP)
    VO(2)= CPH*SPHDT(MTYP)
    VO(3)= SPH*CPHDT(MTYP)
    VO(4)= SPH*SPHDT(MTYP)
    SP(1) = ROT(MTYP) + C(N+15)
    VO(5) = SP(1)*CCAPH(MTYP)
    VO(6) = SP(1)*SCAPH(MTYP)
C-----CALCULATE EQ.(235)-----
102 XS(1)= R*(CTH*VO(1)+VO(4))-VO(5)
    XS(2)= R*STH*CPH
    XS(3)=-R*(CTH*VO(2)-VO(3))+VO(6)
    VO(8)= SQRT(XS(2)**2+XS(3)**2)
    VO(9)= VO(8)**2
C-----CALCULATE EQ.(238A)-----
    CTM(1)= SQRT(XS(1)**2+VO(9))
C-----CALCULATE EQ.(238B)-----
    SAZC= XS(2)/VC(8)
    CAZC= XS(3)/VC(8)
C-----CALCULATE EQ.(238C)-----
    SELC= XS(1)/CTM(1)
    CELC= VO(8)/CTM(1)
    CTM(2)= ATAN2(XS(2),XS(3))
    CTM(3)= ATAN2(XS(1),VO(8))
C-----CALCULATE EQ.(239)-----
    DFM(1)= C(N+1)*CTM(1)+C(N+4)+C(N+10)/SELC
    DFM(2)= C(N+2)*CTM(2)+C(N+5)
    DFM(3)= C(N+3)*CTM(3)+C(N+6)+C(N+11)*CELC/SELC
    IF(M0(MTYP)) 106,104,106
104 IF(NPC(1)-1) 106,18,106
C-----CALCULATE EQ.(246)-----
106 XSX(1,1)= (XS(1)+VO(5))/R
    XSX(1,2)= R*(VO(2)-CTH*VO(3))
    XSX(1,3)= -XS(2)*CPHDT(MTYP)
    XSX(2,1)= XS(2)/R
    XSX(2,2)= -R*STH*SPH
    XSX(2,3)= R*CTH*CPH
    XSX(3,1)= (XS(3)-VO(6))/R
    XSX(3,2)= R*(CTH*VO(4)+VO(1))
    XSX(3,3)= XS(2)*SPHDT(MTYP)
    IF(M0(MTYP)) 108,18,108
C-----CALCULATE EQ.(241)-----
108 DO 112 I=1,3
    SUM=0.
    DO 110 J=1,3
110 SUM=SUM+XSX(I,J)*DX(J+3)
112 XSD(I)=SUM
C-----CALCULATE EQ.(240)-----
    CTM(4)= (XS(1)*XSD(1)+XS(2)*XSD(2)+XS(3)*XSD(3))/CTM(1)
    CTM(5)= (XS(3)*XSD(2)-XS(2)*XSD(3))/VO(9)
    CTM(6)= (CTM(1)*XSD(1)-XS(1)*CTM(4))/(CTM(1)*VO(8))
    DFM(1)= DFM(1)+C(N+7)*CTM(4)
    DFM(2)= DFM(2)+C(N+8)*CTM(5)

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OBSV0280
OBSV0290
OBSV0300
OBSV0310
OBSV0320
OBSV0330
OBSV0340
OBSV0350
OBSV0360
OBSV0370
OBSV0380
OBSV0390
OBSV0400
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OBSV0830
OBSV0840
OBSV0850
OBSV0860
OBSV0870

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DFM(3)=DFM(3)+C(N+9)*CTM(6)	OBSV0880
GO TO 18	OBSV0890
115 DFM(1)=X(1)	OBSV0900
DFM(2)=X(2)	OBSV0910
DFM(3)=X(3)	OBSV0920
GO TO 18	OBSV0930
120 DFM(1)=X(4)	OBSV0940
DFM(2)=X(5)	OBSV0950
DFM(3)=X(6)	OBSV0960
GO TO 18	OBSV0970
125 WRITE(OUT,5000) MTP	OBSV0980
5000 FORMAT(35H ILLIGITIMATE MTP IN OBSERV, MTP=13)	OBSV0990
CALL EXIT	OBSV1000
C 150 CALCULATE AMR	OBSV1010
150 SDP= SIN(C(151))	OBSV1020
CDP= COS(C(151))	OBSV1030
SDY= SIN(C(152))	OBSV1040
CDY= COS(C(152))	OBSV1050
C-----CALCULATE EQ.(269)-----	OBSV1060
XLB(1)= CDY*CDP	OBSV1070
XLB(2)= SDY	OBSV1080
XLB(3)= CDY*SDP	OBSV1090
C-----CALCULATE EQ.(270)-----	OBSV1100
DO 152 I=1,3	OBSV1110
XLG(I)=0.	OBSV1120
DO 152 J=1,3	OBSV1130
152 XLG(I)=XLG(I)+A(J,I)*XLB(J)	OBSV1140
VO(1)= REO**2	OBSV1150
C-----CALCULATE EQ.(271A)-----	OBSV1160
VO(2)= ATAN2(XLG(2),XLG(1))	OBSV1170
C-----CALCULATE EQ.(271B)-----	OBSV1180
SP(1)= SQRT(XLG(1)**2+XLG(2)**2)	OBSV1190
VO(3)=-ATAN2(XLG(3),SP(1))	OBSV1200
SLR= SIN(VO(2))	OBSV1210
CLR= COS(VO(2))	OBSV1220
SGR= SIN(VO(3))	OBSV1230
CGR= COS(VO(3))	OBSV1240
C-----CALCULATE EQ.(277)-----	OBSV1250
XA(1)= SLR*CGR	OBSV1260
XA(2)= R*CPH	OBSV1270
XA(3)= CPH*SGR-SPH*CLR*CGR	OBSV1280
XA(4)= R*SPH	OBSV1290
XA(5)= SPH*SGR+CPH*CLR*CGR	OBSV1300
C-----CALCULATE EQ.(276)-----	OBSV1310
XC(1)= XA(1)**2 + XA(3)**2 + RERP2*XA(5)**2	OBSV1320
XC(2)= 2.*(XA(2)*XA(3)+ RERP2*XA(4)*XA(5))	OBSV1330
XC(3)= XA(2)**2 + RERP2*XA(4)**2 - VO(1)	OBSV1340
SP(2)= XC(2)**2 - 4.*XC(1)*XC(3)	OBSV1350
IF(SP(2)) 154,156,156	OBSV1360
154 WRITE(OUT,5022)	OBSV1370
5022 FORMAT(49H IMAGINARY OR NEGATIVE SOLUTION ON AIRBORNE RADAR)	OBSV1380
DO 160 I=1,3	OBSV1390
DFM(I)= 0.	OBSV1400
DO 158 J=1,NSTX	OBSV1410
158 G(I,J)= 0.	OBSV1420
DO 160 J=1,NPV	OBSV1430
H(I,J)= 0.	OBSV1440
160 CONTINUE	OBSV1450
SI(1)=1.E20	OBSV1460
GO TO 99	OBSV1470


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C-----CALCULATE EQ.(273) -----
156 DFM(1) = -.5*(XC(2)+SQRT(SP(2)))/XC(1)
    IF(DFM(1).LT.0.) GO TO 154
    DFM(2) = 0.
    DFM(3) = 0.
18  IF(DCOMP.LT.0.) GO TO 80
    DO 20 I=1,3
    SP(I) = SYG(I,MTYP)
    IF(NPC(1).EQ.0) SP(I) = SP(I)+SIGM(I)
20  KC(I)=0
    IF(KN) 22,22,24
22  KOB=KAR
    GO TO 26
24  KOB=JNBR
26  DO 28 I=KAR,KOB
    J=LC(I)
    DATC(I)=DFM(J)
    SI(I)=SP(J)
    NCOUNT=NCOUNT+1
28  KC(J) = NCOUNT
30  IF(NPC(5)) 34,32,34
32  CONTINUE
    WRITE(OUT,1002) (KC(I),I=1,3),MTYP,TO:(DFM(I),I=1,3),(SP(I),I=1,3)
1002 FORMAT(1X,I4,1H,I4,1H,I4,2X,I2,1X,F10.4,F15.2,5F15.6)
34  DO 36 I=1,NSTX
    DO 36 J=KAR,KOB
36  G(J,I)=0.
    IF(MTYP=6) 200,250,270
C 200 CALCULATE G(1-10) FOR R,A,E
C-----CALCULATE EQ.(244) -----
200 DO 202 I=1,3
    RCX(1,I) = (XSX(1,I)*XS(1)+XSX(2,I)*XS(2)+XSX(3,I)*XS(3))/CTM(1)
    RCX(2,I) = (XSX(2,I)*XS(3)-XSX(3,I)*XS(2))/VO(9)
202 RCX(3,I) = (XSX(1,I)-RCX(1,I)*SELC)/VO(8)
    IF(MO(MTYP)) 204,218,204
204 SP(1) = R*CPH
    SP(2) = DX(5)/R
    SP(3) = X(2)/(R*SP(1))
    SP(4) = X(2)*TPH/SP(1)
C-----CALCULATE EQ.(247) -----
DO 206 I=1,3
XSDX(I,1) = XSX(I,2)/R
XSOX(I,2) = XSX(I,3)/SP(1)
XSDX(I,3) = -XSX(I,1)
XSDX(I,4) = -XSX(I,2)*SP(2)-XSX(I,3)*SP(3)
206 XSDX(I,5) = XSX(I,3)*SP(4)
VO(10) = -X(3)/R
SP(4) = DX(6)/R
SP(5) = DX(5)/R
SP(6) = -TPH*DX(6)
SP(7) = -R*DX(5)
SP(1) = CTH*DX(6)/STH - TPH*DX(5)
SP(3) = SP(1)
SP(2) = -STH*DX(6)/CTH - TPH*DX(5)
DO 208 I=1,3
XSDX(I,4) = XSDX(I,4)+XSX(I,3)*SP(4)+XSX(I,2)*SP(5)
XSDX(I,5) = XSDX(I,5)+XSX(I,2)*VO(10)+XSX(I,3)*SP(6)+XSX(I,1)*SP(7)
208 XSDX(I,6) = XSX(I,3)*VO(10)+XSX(I,3)*SP(1)
VO(11) = -(XSD(3)+2.*CTM(5)*XS(2))
VO(12) = XSD(2)-2.*CTM(5)*XS(3)

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OBSV1480
OBSV1490
OBSV1500
OBSV1510
OBSV1520
OBSV1530
OBSV1540
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OBSV1560
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OBSV1580
OBSV1590
OBSV1600
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OBSV1930
OBSV1940
OBSV1950
OBSV1960
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OBSV1980
OBSV1990
OBSV2000
OBSV2010
OBSV2020
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OBSV2050
OBSV2060
OBSV2070

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SP(1)=-CTM(6)*XS(2)/CELC	OBSV2080
SP(2)=-CTM(6)*XS(3)/CELC	OBSV2090
SP(3)=XSD(1)-CTM(6)*VO(8)	OBSV2100
C-----CALCULATE EQ.(245)-----	OBSV2110
DO 216 I=1,6	OBSV2120
IF(I-3) 210,210,212	OBSV2130
210 RCDX(1,I)=0.	OBSV2140
RCDX(2,I)=0.	OBSV2150
RCDX(3,I)=0.	OBSV2160
GO TO 214	OBSV2170
212 RCDX(1,I)=XSX(1,I-3)*XSD(1)+XSX(2,I-3)*XSD(2)+XSX(3,I-3)*XSD(3)	OBSV2180
X -RCX(1,I-3)*CTM(4)	OBSV2190
RCDX(2,I)=XSX(3,I-3)*VO(12)+XSX(2,I-3)*VO(11)	OBSV2200
RCDX(3,I)=-XSX(1,I-3)*CTM(4)+XSX(2,I-3)*SP(1)+XSX(3,I-3)*SP(2)	OBSV2210
X +RCX(1,I-3)*SP(3)	OBSV2220
214 RCDX(1,I)=(RCDX(1,I)+XSDX(1,I)*XS(1)+XSDX(2,I)*XS(2)	OBSV2230
X +XSDX(3,I)*XS(3))/CTM(1)	OBSV2240
RCDX(2,I)=(RCDX(2,I)+XSDX(2,I)*XS(3)-XSDX(3,I)*XS(2))/VO(9)	OBSV2250
216 RCDX(3,I)=(RCDX(3,I)-RCDX(1,I)*XS(1))/CTM(1)+XSDX(1,I)/VO(8)	OBSV2260
218 VO(13)=C(N+10)*CELC/SELC**2	OBSV2270
VO(14)=C(N+3)-C(N+11)/SELC**2	OBSV2280
DO 230 I=1,6	OBSV2290
IF(I-3) 220,220,222	OBSV2300
220 GG(1)=0.	OBSV2310
GG(2)=0.	OBSV2320
GG(3)=0.	OBSV2330
GO TO 224	OBSV2340
C-----CALCULATE EQ.(243)-----	OBSV2350
222 GG(1)=C(N+1)*RCX(1,I-3)-VO(13)*RCX(3,I-3)	OBSV2360
GG(2)=C(N+2)*RCX(2,I-3)	OBSV2370
GG(3)=VO(14)*RCX(3,I-3)	OBSV2380
224 IF(MO(MTYP)) 226,228,226	OBSV2390
226 GG(1)=GG(1)+C(N+7)*RCDX(1,I)	OBSV2400
GG(2)=GG(2)+C(N+8)*RCDX(2,I)	OBSV2410
GG(3)=GG(3)+C(N+9)*RCDX(3,I)	OBSV2420
228 DO 230 K=KAR,KOB	OBSV2430
J=LC(K)	OBSV2440
230 G(K,I)=GG(J)	OBSV2450
232 CONTINUE	OBSV2460
GO TO 38	OBSV2470
C-----CALCULATE EQ.(286)-----	OBSV2480
250 XLGE(1,1)=2.*(X(7)*XLB(1)-X(10)*XLB(2)+X(9)*XLB(3))	OBSV2490
XLGE(1,2)=2.*(X(8)*XLB(1)+X(9)*XLB(2)+X(10)*XLB(3))	OBSV2500
XLGE(1,3)=2.*(-X(9)*XLB(1)+X(8)*XLB(2)+X(7)*XLB(3))	OBSV2510
XLGE(1,4)=2.*(-X(10)*XLB(1)-X(7)*XLB(2)+X(8)*XLB(3))	OBSV2520
XLGE(2,1)=2.*(X(10)*XLB(1)+X(7)*XLB(2)-X(8)*XLB(3))	OBSV2530
XLGE(2,2)=2.*(X(9)*XLB(1)-X(8)*XLB(2)-X(7)*XLB(3))	OBSV2540
XLGE(2,3)=2.*(X(8)*XLB(1)+X(9)*XLB(2)+X(10)*XLB(3))	OBSV2550
XLGE(2,4)=2.*(X(7)*XLB(1)-X(10)*XLB(2)+X(9)*XLB(3))	OBSV2560
XLGE(3,1)=2.*(-X(9)*XLB(1)+X(8)*XLB(2)+X(7)*XLB(3))	OBSV2570
XLGE(3,2)=2.*(X(10)*XLB(1)+X(7)*XLB(2)-X(8)*XLB(3))	OBSV2580
XLGE(3,3)=2.*(-X(7)*XLB(1)+X(10)*XLB(2)-X(9)*XLB(3))	OBSV2590
XLGE(3,4)=2.*(X(8)*XLB(1)+X(9)*XLB(2)+X(10)*XLB(3))	OBSV2600
SP(4)=SGR/CGR	OBSV2610
SP(3)=XLG(1)**2 + XLG(2)**2	OBSV2620
SP(1)=SQRT(SP(3))	OBSV2630
DO 258 I=1,4	OBSV2640
C-----CALCULATE EQ.(284)-----	OBSV2650
XLGX(1,I)=(XLG(1)*XLGE(2,I)-XLG(2)*XLGE(1,I))/SP(3)	OBSV2660
C-----CALCULATE EQ.(285)-----	OBSV2670

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258 XLGX(2,I) =-SP(1)*XLGE(3,I)-SP(4)*(XLG(1)*XLGE(1,I)+XLG(2)*XLGE(2, OBSV2680
1I)) OBSV2690
VO(4)= -SLR*SGR OBSV2700
VO(5)= CLR*CGR OBSV2710
VO(6)= CPH*CGR+SPH*CLR*SGR OBSV2720
VO(7)= SPH*XA(1) OBSV2730
VO(9)= SPH*CGR-CPH*CLR*SGR OBSV2740
VO(10)= CPH*XA(1) OBSV2750
C-----CALCULATE EQ.(283)----- OBSV2760
DO 260 I=1,5 OBSV2770
DO 260 J=1,7 OBSV2780
260 XAX(I,J)= 0. OBSV2790
DO 262 I=1,4 OBSV2800
XAX(1,I+3) = VO(4)*XLGX(2,I) + VO(5)*XLGX(1,I) OBSV2810
XAX(3,I+3) = VO(6)*XLGX(2,I) + VO(7)*XLGX(1,I) OBSV2820
262 XAX(5,I+3) = VO(9)*XLGX(2,I) - VO(10)*XLGX(1,I) OBSV2830
XAX(2,1) = CPH OBSV2840
XAX(2,2) =-XA(4) OBSV2850
XAX(3,2) =-XA(5) OBSV2860
XAX(4,1) = SPH OBSV2870
XAX(4,2) = XA(2) OBSV2880
XAX(5,2) = XA(3) OBSV2890
C-----CALCULATE EQ.(282) ----- OBSV2900
DO 264 I=1,7 OBSV2910
XCX(1,I)= 2.*(XA(1)*XAX(1,I)+XA(3)*XAX(3,I)+RERP2*XA(5)*XAX(5,I)) OBSV2920
XCX(2,I)= 2.*(XA(2)*XAX(3,I)+XA(3)*XAX(2,I)+RERP2*(XA(4)*XAX(5,I) OBSV2930
1 + XA(5)*XAX(4,I))) OBSV2940
264 XCX(3,I)= 2.*(XA(2)*XAX(2,I)+RERP2*XA(4)*XAX(4,I)) OBSV2950
G(1,1)= 0. OBSV2960
G(1,2)= 0. OBSV2970
G(1,3)= 0. OBSV2980
VO(11)= 2.*XC(1)*DFM(1)+XC(2) OBSV2990
VO(12)= (DFM(1)+ XC(3)/VO(11))/XC(1) OBSV3000
VO(13)= (.5-.5*XC(2)/VO(11))/XC(1) OBSV3010
VO(14)= 1./VO(11) OBSV3020
C-----CALCULATE EQ.(281) ----- OBSV3030
DO 266 I=1,7 OBSV3040
266 G(1,I+3)= -VO(12)*XCX(1,I)-VO(13)*XCX(2,I)-VO(14)*XCX(3,I) OBSV3050
GO TO 38 OBSV3060
270 IF(MTYP=8) 272,274,375 OBSV3070
272 LT=0 OBSV3080
GO TO 276 OBSV3090
274 LT=3 OBSV3100
276 DO 284 I=KAR,KOB OBSV3110
J=LC(I) OBSV3120
284 G(I,LT+J)=1. OBSV3130
38 CONTINUE OBSV3140
IF(NSTC) 40,40,46 OBSV3150
40 IF(NPV) 99,99,42 OBSV3160
42 II=1 OBSV3170
IP=1 OBSV3180
44 JJ=MCC(II) OBSV3190
GO TO 50 OBSV3200
46 II=1 OBSV3210
IP=0 OBSV3220
48 JJ=NC(II) OBSV3230
50 GG(1)=0. OBSV3240
GG(2)=0. OBSV3250
GG(3)=0. OBSV3260
IF(MTYP.GE.6) GO TO 375 OBSV3270

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IF(JJ-N) 60,60,54	OBSV3280
54 IF(JJ-N-15) 56,56,60	OBSV3290
56 JN=JJ-N	OBSV3300
IF(JN-12) 58,58,350	OBSV3310
58 GO TO(300,301,302,303,304,305,306,307,308,309,310,311),JN	OBSV3320
60 II=II+1	OBSV3330
DO 66 I=KAR,KOB	OBSV3340
J=LC(I)	OBSV3350
IF(IP) 62,62,64	OBSV3360
62 G(I,II+ 9) = GG(J)	OBSV3370
GO TO 66	OBSV3380
64 H(I,II-1) = GG(J)	OBSV3390
66 CONTINUE	OBSV3400
IF(IP) 68,68,70	OBSV3410
68 IF(II-NSTC) 48,48,40	OBSV3420
70 IF(II-NPV) 44,44,99	OBSV3430
C-----CALCULATE EQ.(248) -----	OBSV3440
300 GG(1) = CTM(1)	OBSV3450
GO TO 60	OBSV3460
301 GG(2) = CTM(2)	OBSV3470
GO TO 60	OBSV3480
302 GG(3) = CTM(3)	OBSV3490
GO TO 60	OBSV3500
303 GG(1) = 1.	OBSV3510
GO TO 60	OBSV3520
304 GG(2) = 1.	OBSV3530
GO TO 60	OBSV3540
305 GG(3) = 1.	OBSV3550
GO TO 60	OBSV3560
306 GG(1) = CTM(4)	OBSV3570
GO TO 60	OBSV3580
307 GG(2) = CTM(5)	OBSV3590
GO TO 60	OBSV3600
308 GG(3) = CTM(6)	OBSV3610
GO TO 60	OBSV3620
309 GG(1) = 1./SELC	OBSV3630
GO TO 60	OBSV3640
310 GG(3) = CELC/SELC	OBSV3650
311 GO TO 60	OBSV3660
350 SP(1)= SIN(C(N+13))	OBSV3670
SP(2)= COS(C(N+13))	OBSV3680
IF(JN-14) 352,354,356	OBSV3690
352 VO(15)=RERP2*(CPHDT(MTYP)/SP(2))**2	OBSV3700
VO(16)=-{ROT(MTYP)/REO)**2*(RERP2-1.)*SP(1)*SP(2)*ROT(MTYP)	OBSV3710
C-----CALCULATE EQ.(252) -----	OBSV3720
XSC(1)= XS(3)*VO(15)-VO(6)-VO(16)*CCAPH(MTYP)	OBSV3730
XSC(2)= 0.	OBSV3740
XSC(3)=-XS(1)*VO(15)-VO(5)+ VO(16)*SCAPH(MTYP)	OBSV3750
GO TO 358	OBSV3760
354 XSC(1)=-XSX(1,3)	OBSV3770
XSC(2)=-XSX(2,3)	OBSV3780
XSC(3)=-XSX(3,3)	OBSV3790
GO TO 358	OBSV3800
356 XSC(1)=-CCAPH(MTYP)	OBSV3810
XSC(2)= 0.	OBSV3820
XSC(3)= SCAPH(MTYP)	OBSV3830
C-----CALCULATE EQ.(250) -----	OBSV3840
358 RCC(1)=(XSC(1)*XS(1)+XSC(2)*XS(2)+XSC(3)*XS(3))/CTM(1)	OBSV3850
RCC(2)=(XSC(2)*XS(3)-XSC(3)*XS(2))/VO(9)	OBSV3860
RCC(3)=(XSC(1)-RCC(1)*SELC)/VO(8)	OBSV3870

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C-----CALCULATE EQ.(249)-----
      GG(1)= C(N+1)*RCC(1)-VO(13)*RCC(3)
      GG(2)= C(N+2)*RCC(2)
      GG(3)= VO(14)*RCC(3)
      IF(MO(MTYP)) 360,60,360
360 IF(JN-14) 362,364,366
362 SP(3)= VO(15)-1.
      SP(5)= XS(2)*DX(6)
C-----CALCULATE EQ.(253A)-----
      XSDC(1)= VO(10)*(XSC(1)+VO(16)*CCAPH(MTYP)-VO(6)*SP(3))
      X   +VO(15)*(XSX(3,2)*DX(5)+SP(5)*SPHDT(MTYP))
      XSDC(2)= 0.
      XSDC(3)= VO(10)*(XSC(3)-VO(16)*SCAPH(MTYP)-VO(5)*SP(3))
      X   +VO(15)*(-XSX(1,2)*DX(5)+SP(5)*CPHDT(MTYP))
      GO TO 368
364 SP(1)= XSX(2,3)*DX(6)+XSX(2,2)*DX(5)
C-----CALCULATE EQ.(253B)-----
      XSDC(1)= VO(10)*XSC(1)+ SP(1)*CPHDT(MTYP)
      XSDC(2)= VO(10)*XSC(2)+ XS(2)*DX(6)+R*CTH*SPH*DX(5)
      XSDC(3)= VO(10)*XSC(3)- SP(1)*SPHDT(MTYP)
      GO TO 368
366 RCDC(1)= 0.
      RCDC(2)= 0.
      RCDC(3)= 0.
      GO TO 370
C-----CALCULATE EQ.(251)-----
368 RCDC(1)= XSDC(1)*XS(1)+XSDC(2)*XS(2)+XSDC(3)*XS(3)
      RCDC(2)= XSDC(2)*XS(3)-XSDC(3)*XS(2)
      RCDC(3)= XSUC(1)*CTM(1)
370 SP(1)= CTM(6)*XS(2)/CELC
      SP(2)= CTM(6)*XS(3)/CELC
      SP(3)= XSD(1)-CTM(6)*VO(8)
      SP(4)= CTM(1)*VO(8)
      RCDC(1)=(RCDC(1)+XSC(1)*XSD(1)+XSC(2)*XSD(2)+XSC(3)*XSD(3)
      X   -RCC(1)*CTM(4))/CTM(1)
      RCDC(2)=(RCDC(2)+XSC(2)*VO(11)+XSC(3)*VO(12))/VO(9)
      RCDC(3)=(RCDC(3)-RCDC(1)*XS(1)-XSC(1)*CTM(4)-XSC(2)*SP(1)
      X   -XSC(3)*SP(2)+RCC(1)*SP(3))/SP(4)
      GG(1)= GG(1) + C(N+7)*RCDC(1)
      GG(2)= GG(2) + C(N+8)*RCDC(2)
      GG(3)= GG(3) + C(N+9)*RCDC(3)
      GO TO 60
375 DO 390 I=1,3
      DO 385 J=1,NSTC
385 G(I,J+10)= 0.
      DO 390 J=1,NPV
390 H(I,J)= 0.
      RETURN
80 DO 82 I=1,3
      SP(I)=SYG(I,MTYP)
      IF(NPC(1).NE.2) SP(I)=SP(I)+SIG(I,KG)
82 CONTINUE
99 CONTINUE
      RETURN
      END
OBSV3880
OBSV3890
OBSV3900
OBSV3910
OBSV3920
OBSV3930
OBSV3940
OBSV3950
OBSV3960
OBSV3970
OBSV3980
OBSV3990
OBSV4000
OBSV4010
OBSV4020
OBSV4030
OBSV4040
OBSV4050
OBSV4060
OBSV4070
OBSV4080
OBSV4090
OBSV4100
OBSV4110
OBSV4120
OBSV4130
OBSV4140
OBSV4150
OBSV4160
OBSV4170
OBSV4180
OBSV4190
OBSV4200
OBSV4210
OBSV4220
OBSV4230
OBSV4240
OBSV4250
OBSV4260
OBSV4270
OBSV4280
OBSV4290
OBSV4300
OBSV4310
OBSV4320
OBSV4330
OBSV4340
OBSV4350
OBSV4360
OBSV4370
OBSV4380
OBSV4390
OBSV4400
OBSV4410
OBSV4420

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SUBROUTINE OUTPUT
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA,NSTC,NSTX,NT,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PGR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PGR
2 CALL AUXIL
4 ZO(1)=X(2)-R*OMEGA*CPH
ZO(2)=SQRT(X(1)**2+ZO(1)**2)
VO(1)=SQRT(ZO(2)**2+X(3)**2)
IF(VO(1).EQ.0.) VO(1)=.00001
ST(1)=-X(3)/VO(1)
CT(1)= ZO(2)/VO(1)
VO(2)=ATAN2(ST(1),CT(1))/CONRD
IF(ZO(2).EQ.0.) ZO(2)=.00001
ST(2)= ZO(1)/ZO(2)
CT(2)= X(1)/ZO(2)
VO(3)=ATAN2(ST(2),CT(2))/CONRD
RO=REO/SQRT(1.-(1.-RERP2)*SPH**2)
VO(4)= X(4)+REO-RO
VO(5)=ATAN2(RERP2*SPH,CPH)/CONRD
VO(6)= X(6)/CONRD
SP(1)=SQRT(X(1)**2+X(2)**2)
VO(10)=ATAN2(A(1,2),A(1,1))/CONRD
SP(1) =SQRT(1.-A(1,3)**2)
VO(11)=-ATAN2(A(1,3),SP(1))/CONRD
VO(12)=ATAN2(A(2,3),A(3,3))/CONRD
SP(1)=X(1)
SP(2)=ZO(1)
SP(3)=X(3)
DO 10 I=1,3
VO(I+12)=0.
DO 10 J=1,3

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OUTPUT0000
OUTPUT0010
OUTPUT0020
OUTPUT0030
OUTPUT0040
OUTPUT0050
OUTPUT0060
OUTPUT0070
OUTPUT0080
OUTPUT0090
OUTPUT0100
OUTPUT0110
OUTPUT0120
OUTPUT0130
OUTPUT0140
OUTPUT0150
OUTPUT0160
OUTPUT0170
OUTPUT0180
OUTPUT0190
OUTPUT0200
OUTPUT0210
OUTPUT0220
OUTPUT0230
OUTPUT0240
OUTPUT0250
OUTPUT0260
OUTPUT0270
OUTPUT0280
OUTPUT0290
OUTPUT0300
OUTPUT0310
OUTPUT0320
OUTPUT0330
OUTPUT0340
OUTPUT0350
OUTPUT0360
OUTPUT0370
OUTPUT0380
OUTPUT0390
OUTPUT0400
OUTPUT0410
OUTPUT0420
OUTPUT0430
OUTPUT0440
OUTPUT0450
OUTPUT0460
OUTPUT0470
OUTPUT0480
OUTPUT0490
OUTPUT0500
OUTPUT0510
OUTPUT0520
OUTPUT0530
OUTPUT0540
OUTPUT0550
OUTPUT0560
OUTPUT0570
OUTPUT0580

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10 VO(I+12)=VO(I+12)+A(I,J)*SP(J)
ZO(3)=SQRT(VO(13)**2+VO(15)**2)
SP(1)=SQRT(ZO(3)**2+VO(14)**2)
IF(SP(1).EQ.0.) SP(1)=.00001
ST(4)=VO(14)/SP(1)
CT(4)=ZO(3)/SP(1)
VO(17)=ATAN2(ST(4),CT(4))/CONRD
IF(ZO(3).EQ.0.) ZO(3)=.00001
ST(5)= VO(15)/ZO(3)
CT(5)= VO(13)/ZO(3)
VO(18)=ATAN2(ST(5),CT(5))/CONRD
ZO(4)=A(2,3)+ST(4)*ST(1)
ZO(5)=(A(2,2)*CT(2)-A(2,1)*ST(2))*CT(1)
ZO(9)=SQRT(ZO(4)**2+ZO(5)**2)
IF(ZO(9).EQ.0.) ZO(9)=.000001
ST(3)=ZO(4)/ZO(9)
CT(3)=ZO(5)/ZO(9)
VO(16)=ATAN2(ST(3),CT(3))/CONRD
SP(1)=SQRT(VO(14)**2+VO(15)**2)
SP(3)=ATAN2(SP(1),VO(1))/CONRD
SP(2)=ATAN2(VO(14),VO(15))/CONRD
SP(1) = SQRT(X(1)**2+X(2)**2+X(3)**2)
VO(7) = SP(1)
VO(19)=X(5)/CONRD
VO(20)=SQRT(AG(1)**2+AG(2)**2+AG(3)**2)
WRITE(OUT,1001)
1001 FORMAT(//)
WRITE(OUT,1000) TO
WRITE(OUT,1002) (VO(I),I=1,6)
WRITE(OUT,1004) X(1),X(2),X(3),VO(10),VO(11),VO(12)
WRITE(OUT,1006) (VO(I),I=13,18)
WRITE(OUT,1008) (XP(I),I=1,3),(SP(I),I=1,3)
WRITE(OUT,1010) (PA(I),I=1,3),(AB(I),I=1,3)
WRITE(OUT,1012) (PM(I),I=1,3),(AM(I),I=1,3)
WRITE(OUT,1014) (X(I),I=7,10),VO(19),VO(20)
1000 FORMAT(5H TIME,E15.8)
1002 FORMAT(5H V(A),E15.8,5H G(A)E15.8,5H L(A)E15.8,5H ALT E15.8,5H LATOUTP0950
1DE15.8,5H LON E15.8)
1004 FORMAT(5H U(I),E15.8,5H V(I)E15.8,5H W(I)E15.8,5H PSI E15.8,5H THEOUTP0970
2 E15.8,5H PHI E15.8)
1006 FORMAT(5H U(B),E15.8,5H V(B)E15.8,5H W(B)E15.8,5H SIG E15.8,5H BETOUTP0990
3 E15.8,5H ALF E15.8)
1008 FORMAT(5H XP ,E15.8,5H YP E15.8,5H ZP E15.8,5H V(T)E15.8,5H XZIOUTP1010
4 E15.8,5H ETA E15.8)
1010 FORMAT(5H P ,E15.8,5H Q E15.8,5H R E15.8,5H AX E15.8,5H AY OUTP1030
5 E15.8,5H AZ E15.8)
1012 FORMAT(5H PM ,E15.8,5H QM E15.8,5H RM E15.8,5H AXM E15.8,5H AYMOUTP1050
6 E15.8,5H AZM E15.8)
1014 FORMAT(5H E0 ,E15.8,5H E1 E15.8,5H E2 E15.8,5H E3 E15.8,5H LATOUTP1070
7CE15.8,5H A(T)E15.8)
IF(NPC(1)-1) 20,99,28
20 IF(DCOMP) 28,22,22
22 IF(NSTC) 28,26,24
24 DO 26 I=1,NSTC
K=NC(I)
26 AG(I) = C(K)
WRITE(OUT,1016) (NC(I),AG(I),I=1,NSTC)
1016 FORMAT(6(2H C,I3,E15.8))
28 IF(NPC(3)-1) 30,100,100
100 DO 102 I=1,6

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```

DO 102 K=1,10
102 DUB(K,I)=0.
Z0(6)=V0(1)**2
Z0(7)=Z0(6)*Z0(2)
Z0(8)=OMEGA*CPH
DUB(1,1)= X(1)/V0(1)
DUB(2,1)= Z0(1)/V0(1)
DUB(3,1)= X(3)/V0(1)
DUB(4,1)= - DUB(2,1)*Z0(8)
DUB(5,1)= -DUB(4,1)*R*TPH
SP(1)= X(3)/(V0(1)*Z0(2))
DUB(1,2)= SP(1)*DUB(1,1)
DUB(2,2)= SP(1)*DUB(2,1)
DUB(3,2)=-Z0(2)/Z0(6)
DUB(4,2)= SP(1)*DUB(4,1)
DUB(5,2)= SP(1)*DUB(5,1)
SP(1)=Z0(2)**2
DUB(1,3)=-Z0(1)/SP(1)
DUB(2,3)= X(1)/SP(1)
DUB(4,3)=-X(1)*Z0(8)/SP(1)
DUB(5,3)=-DUB(4,3)*R*TPH
IF(NPC(3)-1) 120,110,120
110 SP(1)= 2./(A(1,1)**2+A(1,2)**2)
DUB(7,4)=SP(1)*(X(10)*A(1,1)-X(7)*A(1,2))
DUB(8,4)=SP(1)*(X(9)*A(1,1)-X(8)*A(1,2))
DUB(9,4)=SP(1)*(X(8)*A(1,1)+X(9)*A(1,2))
DUB(10,4)=SP(1)*(X(7)*A(1,1)+X(10)*A(1,2))
SP(1)= 2./SQRT(1.-A(1,3)**2)
DUB(7,5)= X(9)*SP(1)
DUB(8,5)=-X(10)*SP(1)
DUB(9,5)= X(7)*SP(1)
DUB(10,5)=-X(8)*SP(1)
SP(1)= 2./(A(3,3)**2+A(2,3)**2)
DUB(7,6)=SP(1)*(X(8)*A(3,3)-X(7)*A(2,3))
DUB(8,6)=SP(1)*(X(7)*A(3,3)+X(8)*A(2,3))
DUB(9,6)=SP(1)*(X(10)*A(3,3)+X(9)*A(2,3))
DUB(10,6)=SP(1)*(X(9)*A(3,3)-X(10)*A(2,3))
GO TO 200
120 SP(1)= X(1)*X(7) + Z0(1)*X(10) - X(3)*X(9)
SP(2)= X(1)*X(8) + Z0(1)*X(9) + X(3)*X(10)
SP(3)= X(1)*X(9) - Z0(1)*X(8) + X(3)*X(7)
SP(4)= X(1)*X(10) - Z0(1)*X(7) - X(3)*X(8)
SP(5)= ST(4)/(CT(4)*V0(1))
SP(6)= 2./V0(1)
DUB(1,5)= (CT(4)*A(2,1)-SP(5)*(X(1) -A(2,1)*V0(14)))/V0(1)
DUB(2,5)= (CT(4)*A(2,2)-SP(5)*(Z0(1)-A(2,2)*V0(14)))/V0(1)
DUB(3,5)= (CT(4)*A(2,3)-SP(5)*(X(3) -A(2,3)*V0(14)))/V0(1)
DUB(4,5)= -Z0(8)*DUB(2,5)
DUB(5,5)= -DUB(4,5)*R*TPH
DUB(7,5)=(-CT(4)*SP(4)-SP(5)*(V0(13)*SP(1)+V0(15)*SP(3)))*SP(6)
DUB(8,5)= (CT(4)*SP(3)-SP(5)*(V0(13)*SP(2)+V0(15)*SP(4)))*SP(6)
DUB(9,5)= (CT(4)*SP(2)+SP(5)*(V0(13)*SP(3)-V0(15)*SP(1)))*SP(6)
DUB(10,5)=(-CT(4)*SP(1)+SP(5)*(V0(13)*SP(4)-V0(15)*SP(2)))*SP(6)
SP(6)= Z0(3)**2
DUB(1,6) = (V0(13)*A(3,1)-V0(15)*A(1,1))/SP(6)
DUB(2,6) = (V0(13)*A(3,2)-V0(15)*A(1,2))/SP(6)
DUB(3,6) = (V0(13)*A(3,3)-V0(15)*A(1,3))/SP(6)
DUB(4,6) = -Z0(8)*DUB(2,6)
DUB(5,6) = -DUB(4,6)*R*TPH
SP(6)= 2./SP(6)

```

```

OUTP1190
OUTP1200
OUTP1210
OUTP1220
OUTP1230
OUTP1240
OUTP1250
OUTP1260
OUTP1270
OUTP1280
OUTP1290
OUTP1300
OUTP1310
OUTP1320
OUTP1330
OUTP1340
OUTP1350
OUTP1360
OUTP1370
OUTP1380
OUTP1390
OUTP1400
OUTP1410
OUTP1420
OUTP1430
OUTP1440
OUTP1450
OUTP1460
OUTP1470
OUTP1480
OUTP1490
OUTP1500
OUTP1510
OUTP1520
OUTP1530
OUTP1540
OUTP1550
OUTP1560
OUTP1570
OUTP1580
OUTP1590
OUTP1600
OUTP1610
OUTP1620
OUTP1630
OUTP1640
OUTP1650
OUTP1660
OUTP1670
OUTP1680
OUTP1690
OUTP1700
OUTP1710
OUTP1720
OUTP1730
OUTP1740
OUTP1750
OUTP1760
OUTP1770
OUTP1780

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DUB(7,6) = (V0(13)*SP(3)-V0(15)*SP(1))*SP(6)          OUTPUT1790
DUB(8,6) = (V0(13)*SP(4)-V0(15)*SP(2))*SP(6)          OUTPUT1800
DUB(9,6) = (V0(13)*SP(1)+V0(15)*SP(3))*SP(6)          OUTPUT1810
DUB(10,6) = (V0(13)*SP(2)+V0(15)*SP(4))*SP(6)         OUTPUT1820
SP(1) = CT(3)*ST(4)*CT(1)+ST(3)*ST(1)*Z0(5)/CT(1)     OUTPUT1830
SP(2) = ST(3)*CT(1)*(A(2,2)*ST(2)+A(2,1)*CT(2))       OUTPUT1840
SP(3) = CT(3)*CT(4)*ST(1)                              OUTPUT1850
DUB(1,4) = (SP(1)*DUB(1,2)+SP(2)*DUB(1,3)+SP(3)*DUB(1,5))/Z0(9) OUTPUT1860
DUB(2,4) = (SP(1)*DUB(2,2)+SP(2)*DUB(2,3)+SP(3)*DUB(2,5))/Z0(9) OUTPUT1870
DUB(3,4) = (SP(1)*DUB(3,2)+SP(2)*DUB(3,3)+SP(3)*DUB(3,5))/Z0(9) OUTPUT1880
DUB(4,4) = (SP(1)*DUB(4,2)+SP(2)*DUB(4,3)+SP(3)*DUB(4,5))/Z0(9) OUTPUT1890
DUB(5,4) = (SP(1)*DUB(5,2)+SP(2)*DUB(5,3)+SP(3)*DUB(5,5))/Z0(9) OUTPUT1900
SP(6) = ST(3)*CT(1)                                     OUTPUT1910
SP(5) = SP(6)*CT(2)                                     OUTPUT1920
SP(6) = SP(6)*ST(2)                                     OUTPUT1930
DUB(7,4) = (SP(3)*DUB(7,5)+2.*(CT(3)*X(8)-SP(5)*X(7)-SP(6)*X(10) OUTPUT1940
X))/Z0(9)
DUB(8,4) = (SP(3)*DUB(8,5)+2.*(CT(3)*X(7)+SP(5)*X(8)+SP(6)*X(9) OUTPUT1960
X))/Z0(9)
DUB(9,4) = (SP(3)*DUB(9,5)+2.*(CT(3)*X(10)-SP(5)*X(9)+SP(6)*X(8) OUTPUT1980
X))/Z0(9)
DUB(10,4) = (SP(3)*DUB(10,5)+2.*(CT(3)*X(9)+SP(5)*X(10)-SP(6)*X(7) OUTPUT2000
X))/Z0(9)
200 DO 205 I=1,3                                         OUTPUT2020
    DO 205 J=1,NSTX                                       OUTPUT2030
        DUB(J,I+6)=0.                                     OUTPUT2040
        DUB(J,I+9)=P(I+3,J)                             OUTPUT2050
        DUB(J,I+12)=0.                                   OUTPUT2060
        DO 202 K=1,5                                       OUTPUT2070
            SUM=P(K,J)                                     OUTPUT2080
            IF(K-J) 202,202,201                             OUTPUT2090
201 SUM=P(J,K)                                           OUTPUT2100
202 DUB(J,I+6)=DUB(J,I+6)+DUB(K,I)*SUM                   OUTPUT2110
    DO 204 K=1,10                                         OUTPUT2120
        SUM=P(K,J)                                       OUTPUT2130
        IF(K-J) 204,204,203                             OUTPUT2140
203 SUM=P(J,K)                                           OUTPUT2150
204 DUB(J,I+12)=DUB(J,I+12)+DUB(K,I+3)*SUM              OUTPUT2160
205 CONTINUE                                             OUTPUT2170
    DO 218 I=1,3                                         OUTPUT2180
        DO 208 J=I,3                                       OUTPUT2190
            P(J+1,I)=0.                                     OUTPUT2200
            P(J+7,I)=0.                                    OUTPUT2210
            DO 206 K=1,5                                       OUTPUT2220
206 P(J+1,I)=P(J+1,I)+DUB(K,I+6)*DUB(K,J)               OUTPUT2230
            DO 207 K=1,10                                       OUTPUT2240
207 P(J+7,I)=P(J+7,I)+DUB(K,I+6)*DUB(K,J+3)            OUTPUT2250
208 CONTINUE                                             OUTPUT2260
            DO 212 J=I,3                                       OUTPUT2270
                P(J+7,I+6)=0.                                OUTPUT2280
                P(J+4,I+3)=P(I+3,J+3)                       OUTPUT2290
                DO 212 K=1,10                                       OUTPUT2300
212 P(J+7,I+6)=P(J+7,I+6)+DUB(K,I+12)*DUB(K,J+3)       OUTPUT2310
            DO 214 J=1,3                                       OUTPUT2320
                P(J+4,1)= DUB(J+3,I+6)                       OUTPUT2330
214 P(J+7,I+3)= DUB(I+3,J+12)                             OUTPUT2340
            DO 216 J=1,NSTC                                       OUTPUT2350
                P(J+10,1)= DUB(J+10,I+7)                   OUTPUT2360
                P(J+10,I+6)= DUB(J+10,I+12)                 OUTPUT2370
216 P(J+10,I+3)= P(I+3,J+10)                             OUTPUT2380

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218	CONTINUE	OUTP2390
	DO 210 I=1,NSTC	OUTP2400
	DO 210 J=I,NSTC	OUTP2410
210	P(J+10,I+9)= P(I+10,J+10)	OUTP2420
	LT=1	OUTP2430
	MT=NSTX-1	OUTP2440
	NT=9	OUTP2450
	GO TO 34	OUTP2460
30	LT=0	OUTP2470
	MT=NSTX	OUTP2480
	NT=10	OUTP2490
	DO 32 I=1,NSTX	OUTP2500
	K=I+1	OUTP2510
	DO 32 J=K,NSTX	OUTP2520
32	P(J,I)=P(I,J)	OUTP2530
34	IF(NPC(1)) 35,130,35	OUTP2540
130	IF(NPC(4)-1) 35,132,35	OUTP2550
132	IF(NPC(3)) 134,134,138	OUTP2560
134	DO 136 I=1,10	OUTP2570
136	VO(I)= DZ(I)	OUTP2580
	GO TO 146	OUTP2590
138	DO 144 I=1,3	OUTP2600
	VO(I)=0.	OUTP2610
	VO(I+6)=0.	OUTP2620
	DO 140 J=1,5	OUTP2630
140	VO(I)=VO(I)+ DUB(J,I)*DZ(J)	OUTP2640
	VO(I+3)= DZ(I+3)	OUTP2650
	DO 142 J=1,10	OUTP2660
142	VO(I+6)=VO(I+6)+ DUB(J,I+3)*DZ(J)	OUTP2670
144	CONTINUE	OUTP2680
146	IF(NSTC) 148,147,148	OUTP2690
147	WRITE(OUT,1028) (I,VO(I),I=1,NT)	OUTP2700
	GO TO 35	OUTP2710
148	DO 150 I=1,NSTC	OUTP2720
150	VO(I+NT)= DZ(I+10)	OUTP2730
	WRITE(OUT,1028) (I,VO(I),I=1,NT),(NC(I),VO(I+NT),I=1,NSTC)	OUTP2740
1028	FORMAT(6(3H Z(I3,1H)E13,6))	OUTP2750
35	DO 40 I=1,MT	OUTP2760
	K=I+LT	OUTP2770
	IF(P(K,I)) 36,38,38	OUTP2780
36	WRITE(OUT,1030) I,I,I,P(K,I)	OUTP2790
	VO(I) = P(K,I)	OUTP2800
1030	FORMAT(26H ****NEGATIVE VARIANCE ON I3,31HRD TRANSFORMED VARIABLE,	OUTP2810
	A SIGMA(I3,1H,I3,4H) = E15.8)	OUTP2820
	GO TO 40	OUTP2830
38	VO(I)=SQRT(P(K,I))	OUTP2840
40	CONTINUE	OUTP2850
	IF(NSTC.GT.0) GO TO 50	OUTP2860
	WRITE(OUT,1032) (I,VO(I),I=1,NT)	OUTP2870
	GO TO 52	OUTP2880
50	DO 39 I=1,NSTC	OUTP2890
	K=I+NT	OUTP2900
39	ZO(I)=VO(K)	OUTP2910
	WRITE(OUT,1032) (I,VO(I),I=1,NT),(NC(I),ZO(I) ,I=1,NSTC)	OUTP2920
1032	FORMAT(6(3H S(I3,1H)E13,6))	OUTP2930
52	IF(NPC(7).NE.ICOUNT) RETURN	OUTP2940
	IF(NPC(6)-1) 99,41,42	OUTP2950
41	IF(DCOMP.GT.0) RETURN	OUTP2960
42	WRITE(OUT,1033)	OUTP2970
1033	FORMAT(42H COVARIANCE MATRIX P (LOWER TRIANGLE ONLY))	OUTP2980

DO 43 I=1,MT	OUTP2990
43 WRITE(OUT,1034) (P(I+LT,J),J=1,I)	OUTP3000
1034 FORMAT(X,12E10,3)	OUTP3010
IF(NPU) 44,44,250	OUTP3020
44 IF(NPV) 46,46,300	OUTP3030
46 CONTINUE	OUTP3040
99 RETURN	OUTP3050
250 IF(LT) 256,252,256	OUTP3060
252 DO 254 I=1,NSTX	OUTP3070
DO 254 J=1,NPU	OUTP3080
254 DUB(I,J+6)=CUZ(I,J)	OUTP3090
GO TO 266	OUTP3100
256 DO 262 I=1,3	OUTP3110
DO 262 J=1,NPU	OUTP3120
DUB(I,J+6)=0.	OUTP3130
DUB(I+6,J+6)=0.	OUTP3140
DO 258 K=1,5	OUTP3150
258 DUB(I,J+6)=DUB(I,J+6)+DUB(K,I)*CUZ(K,J)	OUTP3160
DO 260 K=1,10	OUTP3170
260 DUB(I+6,J+6)=DUB(I+6,J+6)+DUB(K,I+3)*CUZ(K,J)	OUTP3180
262 DUB(I+3,J+6)=CUZ(I+3,J)	OUTP3190
DO 264 I=1,NSTC	OUTP3200
DO 264 J=1,NPU	OUTP3210
264 DUB(I+9,J+6)=CUZ(I+10,J)	OUTP3220
266 WRITE(OUT,1035)	OUTP3230
1035 FORMAT(34H CORRELATION MATRIX (CUZ)TRANSP0SE)	OUTP3240
MT=NSTX-LT	OUTP3250
DO 268 J=1,NPU	OUTP3260
268 WRITE(OUT,1034) (DUB(I,J+6),I=1,MT)	OUTP3270
GO TO 44	OUTP3280
300 IF(LT) 306,302,306	OUTP3290
302 DO 304 I=1,NSTX	OUTP3300
DO 304 J=1,NPV	OUTP3310
304 DUB(I,J+6)=CVZ(I,J)	OUTP3320
GO TO 316	OUTP3330
306 DO 312 I=1,3	OUTP3340
DO 312 J=1,NPV	OUTP3350
DUB(I,J+6)=0.	OUTP3360
DUB(I+6,J+6)=0.	OUTP3370
DO 308 K=1,5	OUTP3380
308 DUB(I,J+6)=DUB(I,J+6)+DUB(K,I)*CVZ(K,J)	OUTP3390
DO 310 K=1,10	OUTP3400
310 DUB(I+6,J+6)=DUB(I+6,J+6)+DUB(K,I+3)*CVZ(K,J)	OUTP3410
312 DUB(I+3,J+6)=CVZ(I+3,J)	OUTP3420
DO 314 I=1,NSTC	OUTP3430
DO 314 J=1,NPV	OUTP3440
314 DUB(I+9,J+6)=CVZ(I+10,J)	OUTP3450
316 WRITE(OUT,1036)	OUTP3460
1036 FORMAT(34H CORRELATION MATRIX (CVZ)TRANSP0SE)	OUTP3470
MT=NSTX-LT	OUTP3480
DO 318 J=1,NPV	OUTP3490
318 WRITE(OUT,1034) (DUB(I,J+6),I=1,MT)	OUTP3500
GO TO 46	OUTP3510
END	OUTP3520

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SUBROUTINE PRESET
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR,JNBR5,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA,NSTC,NSTX,NT,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2,SY6(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
NDIMT = 160
NDIMZ = 30
NDIMV = 5
NDIMU = 5
DO 12 I=1,NDIMZ
DO 4 J=1,NDIMZ
4 P(I,J)=0.
DO 6 J=1,NDIMU
6 CUZ(I,J) = 0.
DO 8 J=1,NDIMV
8 CVZ(1,J) = 0.
DO 10 J=1,10
10 PH(J,I)=0.
12 DZ(I) = 0.
DO 16 I=1,NDIMU
16 U(I)=0.
DO 18 I=1,NDIMV
18 S(I)=0.
DO 20 I=1,NDIMT
20 C(I) = 0.
C(36) = 1.
C(40) = 1.
C(44) = 1.
C(61) = 1.
C(65) = 1.
C(69) = 1.
C(76) = 1.

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C(77) = 1.
C(78) = 1.
C(91) = 1.
C(92) = 1.
C(93) = 1.
C(106) = 1.
C(107) = 1.
C(108) = 1.
C(121) = 1.
C(122) = 1.
C(123) = 1.
C(136) = 1.
C(137) = 1.
C(138) = 1.
CONRD = .0174532925
XJ2 = 1.082645E-3
XMU = 3.985992E+14
OMEGA = .7292116E-4
RPO = 6356173.
REO = 6378163.
NCOUNT = 0
ICOUNT = 1
KDATAS = -1
NST = 0
NSTX = 0
NSTC = 0
NSTA = 0
NPU = 0
NPV = 0
FIT = 1
PQR = 2
SCRACH = 3
STATE = 4
IN = 5
OUT = 6
N8(1) = 0
N8(2) = 1
N8(3) = 0
N9(1) = 0
N9(2) = 1
N9(3) = 0
N10(1) = 0
N10(2) = 1
N10(3) = 0
N11(1) = 0
N11(2) = 1
N11(3) = 0
DO 200 I=1,9
DFIT(I) = 1.E10
DTI(I) = 1.E10
200 NTR(I) = 0
TIME = 1.E+10
KG = 2
CALL INDAT
CALL SETUP
99 RETURN
END

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PRES0280
PRES0290
PRES0300
PRES0310
PRES0320
PRES0330
PRES0340
PRES0350
PRES0360
PRES0370
PRES0380
PRES0390
PRES0400
PRES0410
PRES0420
PRES0430
PRES0440
PRES0450
PRES0460
PRES0470
PRES0480
PRES0490
PRES0500
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PRES0590
PRES0600
PRES0610
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PRES0630
PRES0640
PRES0650
PRES0660
PRES0670
PRES0680
PRES0690
PRES0700
PRES0710
PRES0720
PRES0730
PRES0740
PRES0750
PRES0760
PRES0770
PRES0780
PRES0790
PRES0800
PRES0810
PRES0820
PRES0830
PRES0840

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SUBROUTINE PROP
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG ,KI ,KK
6 ,KN ,KOB ,KPROP ,KS ,KSM ,KSS ,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT ,FIT ,STATE ,SCRACH ,PGR
COMMON /TAPENO/ IN ,OUT ,FIT ,STATE ,SCRACH ,PGR
C-----CALCULATE EQ.(55B) -----
DO 4 I=1,10
DO 4 J=1,NSTX
SUM = 0.
L = J+1
DO 2 K=1,J
2 SUM = SUM + PH(I,K)*P(K,J)
IF(L.GT.NSTX) GO TO 4
DO 3 K=L,NSTX
3 SUM = SUM + PH(I,K)*P(J,K)
4 DUB(J,I) = SUM
DO 10 I=1,10
DO 8 J=1,10
SUM = 0.
DO 6 K=1,NSTX
6 SUM = SUM + DUB(K,I)*PH(J,K)
8 P(I,J) = SUM
10 CONTINUE
IF(NSTX-10) 12,16,12
12 DO 14 I=11,NSTX
DO 14 J=1,10
14 P(J,I) = DUB(I,J)
IF(NPU) 38,38,60
60 DO 64 I=1,10
DO 64 K=11,NSTX
SUM = 0.
DO 62 J=1,NPU

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II=J+NSTX	PROP0280
62 SUM = SUM + PH(I,II)*CUZ(K,J)	PROP0290
64 P(I,K) = P(I,K) + SUM	PROP0300
GO TO 20	PROP0310
16 IF(NPU) 38,38,20	PROP0320
C-----CALCULATE EQ.(55C) -----	PROP0330
20 DO 25 J=1,NPU	PROP0340
DO 24 I=1,10	PROP0350
SUM = 0.	PROP0360
DO 22 K=1,NSTX	PROP0370
SUM = SUM + PH(I,K)*CUZ(K,J)	PRCP0380
22 CONTINUE	PRCP0390
DUB(I,J) = SUM	PROP0400
24 DUB(I,15) = SUM + PH(I,J+NSTX)*D(J)	PROP0410
DO 25 I=1,10	PROP0420
25 CUZ(I,J) = DUB(I,15)	PROP0430
26 CONTINUE	PROP0440
30 DO 34 I=1,10	PROP0450
DO 34 J=1,10	PROP0460
SUM = 0.	PROP0470
DO 32 K=1,NPU	PROP0480
32 SUM = SUM + CUZ(I,K)*PH(J,K+NSTX) + PH(I,K+NSTX)*DUB(J,K)	PROP0490
34 P(I,J) = P(I,J) + SUM	PROP0500
36 CONTINUE	PROP0510
38 IF(NPV) 99,99,40	PROP0520
C-----CALCULATE EQ.(55D) -----	PROP0530
40 DO 48 J=1,NPV	PROP0540
DO 44 I=1,10	PROP0550
SUM = 0.	PROP0560
DO 42 K=1,NSTX	PROP0570
42 SUM = SUM + PH(I,K)*CVZ(K,J)	PROP0580
44 DUB(I,1) = SUM	PROP0590
DO 46 I=1,10	PRCP0600
46 CVZ(I,J) = DUB(I,1)	PRCP0610
48 CONTINUE	PROP0620
99 IF(NPC(4),EQ.0) GO TO 75	PROP0630
IF(NPC(1),EQ.2) GO TO 75	PROP0640
C-----CALCULATE EQ.(55A) -----	PROP0650
DO 72 I=1,10	PRCP0660
SUM = 0.	PROP0670
DO 70 J=1,NSTX	PROP0680
70 SUM = SUM + PH(I,J)*DZ(J)	PROP0690
72 DUB(I,1) = SUM	PROP0700
DO 74 I=1,10	PROP0710
74 DZ(I) = DUB(I,1)	PROP0720
75 CONTINUE	PRCP0730
ENTRY IDENT	PROP0740
K = NSTX+NPU	PRCP0750
DO 52 I=1,10	PROP0760
DO 50 J=1,K	PROP0770
50 PH(I,J)=0.	PROP0780
52 PH(I,I)=1.	PROP0790
RETURN	PROP0800
END	PROP0810

	SUBROUTINE RKUTTA	RKUT0000
	DIMENSION PR(3)	RKUT0010
	DIMENSION F1(410),F2(410),F3(410),DELY(410)	RKUT0020
	COMMON /INTGRL/ P,T,TP,Y(410),DY(410),N,L	RKUT0030
	DATA PR / .5, .25, .5/	RKUT0040
	GO TO (1,2,2,4),L	RKUT0050
	1 IF(IG.EQ.0) GO TO 30	RKUT0060
	DO 10 I = 1,N	RKUT0070
10	F3(I)=Y(I)	RKUT0080
	L = 2	RKUT0090
	RETURN	RKUT0100
	2 DT = P	RKUT0110
	J = 1	RKUT0120
	T2 = TP - T	RKUT0130
	RT2=T2/P	RKUT0140
	IF(RT2-.99999)22,26,29	RKUT0150
22	IF(RT2.GT..00001) GO TO 26	RKUT0160
20	L=3	RKUT0170
	RETURN	RKUT0180
26	DT=T2	RKUT0190
29	IG=0	RKUT0200
30	GO TO(31,32,33,34),J	RKUT0210
31	T = T+PR(1)*DT	RKUT0220
	DO 310 I=1,N	RKUT0230
	F1(I)=DY(I)*DT	RKUT0240
310	Y(I)=F3(I)+PR(1)*F1(I)	RKUT0250
	J = J+1	RKUT0260
	GO TO 38	RKUT0270
33	T = T+PR(1)*DT	RKUT0280
32	T2=DT/PR(1)	RKUT0290
	DO 320 I=1,N	RKUT0300
	RT2=DY(I)*T2	RKUT0310
	F1(I)=F1(I)+RT2	RKUT0320
320	Y(I)=F3(I)+PR(J)*RT2	RKUT0330
35	J = J + 1	RKUT0340
	RETURN	RKUT0350
34	DO 340 I=1,N	RKUT0360
340	F1(I)=F1(I)+DY(I)*DT	RKUT0370
37	DO 39 I = 1,N	RKUT0380
	DELY(I)=F1(I)/6.+DELY(I)	RKUT0390
39	Y(I)=F2(I)+DELY(I)	RKUT0400
	IG = 1	RKUT0410
	RETURN	RKUT0420
	4 DT=P	RKUT0430
	IG = 1	RKUT0440
	J = 1	RKUT0450
	DO 40 I = 1,N	RKUT0460
	DELY(I) = 0.00	RKUT0470
40	F2(I)=Y(I)	RKUT0480
38	L = 1	RKUT0490
	RETURN	RKUT0500
	END	RKUT0510


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SUBROUTINE SETUP
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUO(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
o ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TG(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PGR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PGR
DIMENSION DUA(4,2)
WRITE(OUT,1000)
1000 FORMAT(1H1,27H CONTROLS ARE SPECIFIED FOR)
IF(NPC(1)-1) 10,11,12
10 WRITE(OUT,1001) TO,TFINAL
1001 FORMAT(5X,28H*FILTERING RUN FROM TIME TO=F9.4,11H TO TFINAL=F9.4)
GO TO 13
11 WRITE(OUT,1002) TO,TFINAL
1002 FORMAT(5X,32H*DETERMINISTIC RUN FROM TIME TO=F9.4,11H TO TFINAL=F9.4)
1.4)
GO TO 24
12 WRITE(OUT,1003) TO,TFINAL
1003 FORMAT(5X,33H*ERROR ANALYSIS RUN FROM TIME TO=F9.4,11H TO TFINAL=F9.4)
19.4)
GO TO 21
13 IF(NPC(4))14,14,15
14 WRITE(OUT,1004)
1004 FORMAT(5X,18H*UPDATED REFERENCE)
GO TO 16
15 WRITE(OUT,1005)
1005 FORMAT(5X,21H*NONUPDATED REFERENCE)
16 IF(NPC(8)-1) 17,18,19
17 WRITE(OUT,1006)
1006 FORMAT(5X,57H*SMOOTH DETERMINISTICALLY, NO RESIDUALS NOR LOSS FUNCTION)
GO TO 20
18 WRITE(OUT,1007)

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1007 FORMAT(5X,64H*SMOOTH DETERMINISTICALLY, CALCULATE RESIDUALS AND LOSETP0280
      XSS FUNCTION) SETP0290
      GO TO 20 SETP0300
      19 IF(NPC(8)-3) 170,172,174 SETP0310
      170 WRITE(OUT,1027) SETP0320
1027 FORMAT(5X,49H*SMOOTH COVARIANCE,NO RESIDUALS NOR LOSS FUNCTION) SETP0330
      GO TO 20 SETP0340
      172 WRITE(OUT,1028) SETP0350
1028 FORMAT(5X,56H*SMOOTH COVARIANCE,CALCULATE RESIDUALS AND LOSS FUNCTSETP0360
      XION) SETP0370
      GO TO 20 SETP0380
      174 WRITE(OUT,1029) SETP0390
1029 FORMAT(5X,13H*NO SMOOTHING) SETP0400
      20 WRITE(OUT,1009) NPC(7) SETP0410
1009 FORMAT(5X,12H*FILTER FOR I2,11H ITERATIONS) SETP0420
      21 IF(NPC(9).EQ.0) GO TO 23 SETP0430
      22 WRITE(OUT,1010) SETP0440
1010 FORMAT(5X,28H*SCALAR PROCESS FITTING DATA) SETP0450
      GO TO 24 SETP0460
      23 WRITE(OUT,1011) SETP0470
1011 FORMAT(5X,36H*VECTOR PROCESS FITTING DATA TRIPLES) SETP0480
      24 IF(NPC(2)) 25,25,26 SETP0490
      25 WRITE(OUT,1012) SETP0500
1012 FORMAT(5X,52H*INPUT AND OUTPUT IN METRIC UNITS(M,M/SEC,M/SEC2,KG))SETP0510
      GO TO 27 SETP0520
      26 WRITE(OUT,1013) SETP0530
1013 FORMAT(5X,62H*INPUT AND OUTPUT IN ENGLISH UNITS (FT,FT/SEC,FT/SEC2SETP0540
      X,LB,SLUG)) SETP0550
      27 WRITE(OUT,1014) REO,RPO,OMEGA,XMU,XJ2 SETP0560
1014 FORMAT(5X,18H*PLANET PARAMETERS/20X,11HEQUIT,RAD.=E15.8,13H POLARSETP0570
      1 RAD.=E15.8,13H ROTATION =E15.8/20X,11HMU(GRAV.) =E15.8,13H J2(SETP0580
      2GRAV.) =E15.8/5X,26H*INITIAL STATE ESTIMATE IS) SETP0590
      IF(NPC(3)-1) 28,29,30 SETP0600
      28 WRITE(OUT,1015) (ZO(I),I=1,10) SETP0610
1015 FORMAT(20X,11HU,9X,1H=E15.8,3H V,9X,1H=E15.8,3H W,9X,1H=E15.8/20XSETP0620
      1,11HALTITUDE =E15.8,13H GEOD.LAT. =E15.8,13H LONGITUDE =E15.8/2SETP0630
      20X,2HE0,8X,1H=E15.8,4H E1,8X,1H=E15.8,4H E2,8X,1H=E15.8/20X,2HE3SETP0640
      3,8X,1H=E15.8) SETP0650
      GO TO 31 SETP0660
      29 WRITE(OUT,1016) (ZO(I),I=1,9) SETP0670
1016 FORMAT(20X,11HVELOCITY =E15.8,13H GAMMA =E15.8,13H LAMBDA SETP0680
      1 =E15.8/20X,11HALTITUDE =E15.8,13H GEOD.LAT. =E15.8,13H LONGITSETP0690
      2UDE =E15.8/20X,11HPSI(BAR) =E15.8,13H THETA(BAR)=E15.8,13H PHI(SETP0700
      3BAR) =E15.8) SETP0710
      GO TO 31 SETP0720
      30 WRITE(OUT,1017) (ZO(I),I=1,9) SETP0730
1017 FORMAT(20X,11HVELOCITY =E15.8,13H GAMMA =E15.8,13H LAMBDA SETP0740
      1 =E15.8/20X,11HALTITUDE =E15.8,13H GEOD.LAT. =E15.8,13H LONGITSETP0750
      2UDE =E15.8/20X,11HSIGMA =E15.8,13H BETA =E15.8,13H ALPHASETP0760
      3A =E15.8) SETP0770
      31 RERP2=(REO/RPO)**2 SETP0780
      XMUJ = 3.*XMU*XJ2*REO**2 SETP0790
      IF(NPC(1)-1)32,40,32 SETP0800
      32 WRITE(OUT,1018) NSTA SETP0810
1018 FORMAT(5X,22H*FITTING DATA IS FROM I2,8H SOURCES) SETP0820
      KSS=0 SETP0830
      DO 42 I=1,NSTA SETP0840
      IF(NS(I)-6) 33,44,45 SETP0850
      33 MT = NS(I) SETP0860
      N = 73 +15*VT SETP0670

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WRITE(OUT,1019) I,MT,C(N),C(N+1),C(N+2) SETP0880
1019 FORMAT(10X,I1,19H. TRACKING STATION I1,12H. GEOD.LAT.=F11.6,12H L SETP0890
XONGITUDE=F11.6,12H ALTITUDE =F11.4,19H ABOVE REF. SURFACE) SETP0900
C(N)=C(N)*CONRD SETP0910
C(N+1)=C(N+1)*CONRD SETP0920
C(N) = ATAN2(SIN(C(N)),RERP2*COS(C(N))) SETP0930
NT=N+2 SETP0940
MTYP = MT SETP0950
CALL STAT SETP0960
DO 36 J=1,NSTC SETP0970
IF(NC(J)-N) 36,35,35 SETP0980
35 IF(NC(J)-NT)37,37,36 SETP0990
36 CONTINUE SETP1000
GO TO 38 SETP1010
37 KSS=KSS+1 SETP1020
NSS(KSS) = MT SETP1030
38 MO(MT) = 0 SETP1040
DO 39 J=1,NSTC SETP1050
IF(NC(J).LT.N-6) GO TO 39 SETP1060
IF(NC(J).LE.N-4) GO TO 40 SETP1070
39 CONTINUE SETP1080
IF(C(N-6).NE.0.) GO TO 40 SETP1090
IF(C(N-5).NE.0.) GO TO 40 SETP1100
IF(C(N-4).NE.0.) GO TO 40 SETP1110
GO TO 42 SETP1120
44 WRITE(OUT,1020) I,C(151),C(152) SETP1130
1020 FORMAT(10X,I1,27H. AIRBORNE RADAR, DELTA(P)=F11.6,11H DELTA(Y)=F1 SETP1140
X1.6) SETP1150
GO TO 42 SETP1160
45 IF(NS(I)-7) 41,41,43 SETP1170
41 WRITE(OUT,1031) I SETP1180
GO TO 42 SETP1190
43 WRITE(OUT,1030) I SETP1200
GO TO 42 SETP1210
1030 FORMAT(I11,15H. POSITION DATA) SETP1220
1031 FORMAT(I11,15H. VELOCITY DATA) SETP1230
40 MO(MT) = 1 SETP1240
42 CONTINUE SETP1250
46 ZO(5) = ZO(5)*CONRD SETP1260
ZO(6)=ZO(6)*CONRD SETP1270
NSTX = NSTC + 10 SETP1280
ZO(5) = ATAN2(SIN(ZO(5)),RERP2*COS(ZO(5))) SETP1290
CPH=COS(ZO(5)) SETP1300
SPH=SIN(ZO(5)) SETP1310
RO =REO/SQRT(1.+(RERP2-1.)*SPH**2) SETP1320
R= ZO(4)+RO SETP1330
ZO(4)=R-REO SETP1340
DO 48 I=1,10 SETP1350
48 X(I)=ZO(I) SETP1360
IF(NPC(3).EQ.0) GO TO 100 SETP1370
50 DO 51 I=7,9 SETP1380
51 ZO(I)=ZO(I)*CONRD SETP1390
DO 52 I=1,2 SETP1400
ZO(I+1) = ZO(I+1)*CONRD SETP1410
ST(I)=SIN(ZO(I+1)) SETP1420
52 CT(I)=COS(ZO(I+1)) SETP1430
DO 53 I=3,5 SETP1440
ST(I)=SIN(ZO(I+4)/2.) SETP1450
53 CT(I)=COS(ZO(I+4)/2.) SETP1460
X(3)=ZO(1)*CT(1) SETP1470

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	X(1)=X(3)*CT(2)	SETP1480
	X(2)=X(3)*ST(2)+R*OMEGA*CPH	SETP1490
	X(3)=-Z0(1)*ST(1)	SETP1500
	DO 54 I=1,10	SETP1510
	DO 54 J=1,9	SETP1520
54	DUB(I,J)=0.	SETP1530
	DUB(1,1)= CT(1)*CT(2)	SETP1540
	DUB(2,1)= CT(1)*ST(2)	SETP1550
	DUB(3,1)=-ST(1)	SETP1560
	SP(1)= Z0(1)*ST(1)	SETP1570
	DUB(1,2)=-SP(1)*CT(2)	SETP1580
	DUB(2,2)=-SP(1)*ST(2)	SETP1590
	SP(1)= Z0(1)*CT(1)	SETP1600
	DUB(3,2)=-SP(1)	SETP1610
	DUB(1,3)=-SP(1)*ST(2)	SETP1620
	DUB(2,3)= SP(1)*CT(2)	SETP1630
	DUB(2,4)= OMEGA*CPH	SETP1640
	DUB(2,5)=-R*OMEGA*SPH	SETP1650
	DUB(4,4)=1.	SETP1660
	DUB(5,5)=1.	SETP1670
	DUB(6,6)=1.	SETP1680
	IF(NPC(3)-1) 100,56,60	SETP1690
56	DUA(1,1)= CT(3)*CT(4)*CT(5)	SETP1700
	DUA(2,1)= CT(3)*CT(4)*ST(5)	SETP1710
	DUA(3,1)= CT(3)*ST(4)*CT(5)	SETP1720
	DUA(4,1)= ST(3)*CT(4)*CT(5)	SETP1730
	DUA(1,2)= ST(3)*ST(4)*ST(5)	SETP1740
	DUA(2,2)= ST(3)*ST(4)*CT(5)	SETP1750
	DUA(3,2)= ST(3)*CT(4)*ST(5)	SETP1760
	DUA(4,2)= CT(3)*ST(4)*ST(5)	SETP1770
	X(7) = DUA(1,1)+DUA(1,2)	SETP1780
	X(8) = DUA(2,1)-DUA(2,2)	SETP1790
	X(9) = DUA(3,1)+DUA(3,2)	SETP1800
	X(10)= DUA(4,1)-DUA(4,2)	SETP1810
	IF(NPC(1).EQ.1) GO TO 100	SETP1820
	DUB(7,7) = -X(10)/2.	SETP1830
	DUB(8,7) = -X(9)/2.	SETP1840
	DUB(9,7) = X(8)/2.	SETP1850
	DUB(10,7) = X(7)/2.	SETP1860
	DUB(7,8) = -(DUA(3,1) - DUA(3,2))/2.	SETP1870
	DUB(8,8) = -(DUA(4,1) + DUA(4,2))/2.	SETP1880
	DUB(9,8) = (DUA(1,1) - DUA(1,2))/2.	SETP1890
	DUB(10,8) = -(DUA(2,1) + DUA(2,2))/2.	SETP1900
	DUB(7,9) = -X(8)/2.	SETP1910
	DUB(8,9) = X(7)/2.	SETP1920
	DUB(9,9) = X(10)/2.	SETP1930
	DUB(10,9) = -X(9)/2.	SETP1940
	GO TO 70	SETP1950
60	ST(1) = SIN(.5*Z0(2))	SETP1960
	CT(1) = COS(.5*Z0(2))	SETP1970
	ST(2) = SIN(.5*Z0(3))	SETP1980
	CT(2) = COS(.5*Z0(3))	SETP1990
	DUE(1)= CT(1)*CT(2)	SETP2000
	DUE(2)=-ST(1)*ST(2)	SETP2010
	DUE(3)= ST(1)*CT(2)	SETP2020
	DUE(4)= CT(1)*ST(2)	SETP2030
	DUA(1,1)= CT(3)*CT(4)*CT(5)	SETP2040
	DUA(2,1)= ST(3)*CT(4)*CT(5)	SETP2050
	DUA(3,1)= CT(3)*CT(4)*ST(5)	SETP2060
	DUA(4,1)= ST(3)*CT(4)*ST(5)	SETP2070

DUA(1,2)= ST(3)*ST(4)*ST(5)	SETP2080
DUA(2,2)= CT(3)*ST(4)*ST(5)	SETP2090
DUA(3,2)= ST(3)*ST(4)*CT(5)	SETP2100
DUA(4,2)= CT(3)*ST(4)*CT(5)	SETP2110
DUF(1)= DUA(1,1)-DUA(1,2)	SETP2120
DUF(2)= DUA(2,1)+DUA(2,2)	SETP2130
DUF(3)= DUA(3,1)+DUA(3,2)	SETP2140
DUF(4)= DUA(4,1)-DUA(4,2)	SETP2150
X(7) = DUE(1)*DUF(1)-DUE(2)*DUF(2)+DUE(3)*DUF(3)-DUE(4)*DUF(4)	SETP2160
X(8) = DUE(1)*DUF(2)+DUE(2)*DUF(1)+DUE(3)*DUF(4)-DUE(4)*DUF(3)	SETP2170
X(9) = DUE(1)*DUF(3)-DUE(2)*DUF(4)+DUE(3)*DUF(1)+DUE(4)*DUF(2)	SETP2180
X(10)= DUE(1)*DUF(4)+DUE(2)*DUF(3)-DUE(3)*DUF(2)+DUE(4)*DUF(1)	SETP2190
IF(NPC(1).EQ.1) GO TO 100	SETP2200
DUB(7,2) = -X(9)/2. - DUE(2)*DUF(4) + DUE(4)*DUF(2)	SETP2210
DUB(8,2) = X(10)/2.- DUE(2)*DUF(3) - DUE(4)*DUF(1)	SETP2220
DUB(9,2) = X(7)/2. + DUE(2)*DUF(2) + DUE(4)*DUF(4)	SETP2230
DUB(10,2)= -X(8)/2. + DUE(2)*DUF(1) - DUE(4)*DUF(3)	SETP2240
DUB(7,3) = -X(10)/2.	SETP2250
DUB(8,3) = -X(9)/2.	SETP2260
DUB(9,3) = X(8)/2.	SETP2270
DUB(10,3)= X(7)/2.	SETP2280
DUB(7,7) = -X(8)/2. + DUE(3)*DUF(4) - DUE(4)*DUF(3)	SETP2290
DUB(8,7) = X(7)/2. + DUE(3)*DUF(3) + DUE(4)*DUF(4)	SETP2300
DUB(9,7) = -X(10)/2.- DUE(3)*DUF(2) + DUE(4)*DUF(1)	SETP2310
DUB(10,7)= X(9)/2. - DUE(3)*DUF(1) - DUE(4)*DUF(2)	SETP2320
DUF(1) = DUA(1,1)+DUA(1,2)	SETP2330
DUF(2) = DUA(2,1)-DUA(2,2)	SETP2340
DUF(3) = DUA(3,1)-DUA(3,2)	SETP2350
DUF(4) = DUA(4,1)+DUA(4,2)	SETP2360
DUB(7,8) = (-DUE(1)*DUF(4)-DUE(2)*DUF(3)-DUE(3)*DUF(2)+DUE(4)*DUF(1))/2.	SETP2370
DUB(8,8) = (DUE(1)*DUF(3)-DUE(2)*DUF(4)-DUE(3)*DUF(1)-DUE(4)*DUF(2))/2.	SETP2380
DUB(9,8) = (DUE(1)*DUF(2)+DUE(2)*DUF(1)-DUE(3)*DUF(4)+DUE(4)*DUF(3))/2.	SETP2390
DUB(10,8)= (-DUE(1)*DUF(1)+DUE(2)*DUF(2)-DUE(3)*DUF(3)-DUE(4)*DUF(4))/2.	SETP2400
DUB(7,9) = -X(9)/2.	SETP2410
DUB(8,9) = -X(10)/2.	SETP2420
DUB(9,9) = X(7)/2.	SETP2430
DUB(10,9)= X(8)/2.	SETP2440
70 DO 74 I=1,10	SETP2450
DO 74 J=1,NSTX	SETP2460
SUM = 0.	SETP2470
DO 72 K=1,9	SETP2480
72 SUM = SUM + DUB(I,K)*P(K,J)	SETP2490
74 PH(I,J) = SUM	SETP2500
DO 80 I=1,10	SETP2510
DO 78 J=I,10	SETP2520
SUM = 0.	SETP2530
DO 76 K=1,10	SETP2540
76 SUM = SUM + PH(I,K)*DUB(J,K)	SETP2550
78 P(I,J) = SUM	SETP2560
DO 80 J=11,NSTX	SETP2570
80 P(I,J) = PH(I,J)	SETP2580
IF(NPU.EQ.0) GO TO 88	SETP2590
DO 84 I=1,10	SETP2600
DO 84 J=1,NPU	SETP2610
SUM = 0.	SETP2620
DO 82 K=1,9	SETP2630
	SETP2640
	SETP2650
	SETP2660
	SETP2670

82	SUM = SUM + DUB(I,K)*CUZ(K,J)	SETP2680
84	PH(I,J) = SUM	SETP2690
	DO 86 I=1,10	SETP2700
	DO 86 J=1,NPU	SETP2710
86	CUZ(I,J) = PH(I,J)	SETP2720
88	IF(NPV.EQ.0) GO TO 100	SETP2730
	DO 92 I=1,10	SETP2740
	DO 92 J=1,NPV	SETP2750
	SUM = 0.	SETP2760
	DO 90 K=1,9	SETP2770
90	SUM = SUM + DUB(I,K)*CVZ(K,J)	SETP2780
92	PH(I,J) = SUM	SETP2790
	DO 94 I=1,10	SETP2800
	DO 94 J=1,NPV	SETP2810
94	CVZ(I,J) = PH(I,J)	SETP2820
100	WRITE(OUT,3021)	SETP2830
	WRITE(OUT,1021) (I,I,X(I),P(I,I),I=1,10)	SETP2840
3021	FORMAT(//,24H STATE VECTOR COMPONENTS/43H COMP. ID.NO. EST.	SETP2850
	*VALUE VARIANCE)	SETP2860
1021	FORMAT(1X,I4,4X,I4,5X,2E15.8)	SETP2870
	IF(NSTC) 102,104,102	SETP2880
102	WRITE(OUT,1022)	SETP2890
1022	FORMAT(42H MODEL PARAMETERS IN EXPANDED STATE VECTOR)	SETP2900
	DO 103 I=1,NSTC	SETP2910
	LT=NC(I)	SETP2920
	MT=I+10	SETP2930
103	WRITE(OUT,1023) MT,LT,C(LT),P(MT,MT)	SETP2940
1023	FORMAT(1X,I4,4X,I4,5X,2E15.8)	SETP2950
104	IF(NPU) 106,108,106	SETP2960
106	WRITE(OUT,1024)	SETP2970
1024	FORMAT(55H RANDOM MODEL PARAMETERS NOT BEING ESTIMATED (U-VECTOR))	SETP2980
	DO 107 I=1,NPU	SETP2990
	LT=MC(I)	SETP3000
107	WRITE(OUT,1023) I,LT,C(LT),D(I)	SETP3010
108	IF(NPV) 110,112,110	SETP3020
110	WRITE(OUT,1025)	SETP3030
1025	FORMAT(61H RANDOM MEASUREMENT PARAMETERS NOT BEING ESTIMATED (V-VE	SETP3040
	XCTOR))	SETP3050
	DO 111 I=1,NPV	SETP3060
	LT=MCC(I)	SETP3070
111	WRITE(OUT,1023) I,LT,C(LT),S(I)	SETP3080
112	LT=9	SETP3090
	IF(NPC(3).EQ.0) LT=10	SETP3100
	IF(NST-LT) 114,120,114	SETP3110
114	WRITE(OUT,1026)	SETP3120
1026	FORMAT(48H IMPROPER NUMBER OF STATE VARIABLES ARE INPUTTED)	SETP3130
	CALL EXIT	SETP3140
120	IF(NPC(1)-1) 124,122,124	SETP3150
122	NALL=10	SETP3160
	GO TO 128	SETP3170
124	NALL = 10*(NSTX+NPU+1)	SETP3180
	K = NSTX + NPU	SETP3190
	DO 126 I =1,10	SETP3200
	DO 125 J=1,K	SETP3210
125	PH(I,J) = 0.	SETP3220
126	PH(I,I) = 1.	SETP3230
128	IF(NPC(1)-2) 144,130,144	SETP4450
130	IF(NSTA-1) 144,144,132	SETP4460
132	DO 142 I=2,NSTA	SETP4470
	MT=NS(I-1)	SETP4480

TT=DTF(MT)	SETP4490
LT=I-1	SETP4500
DO 136 J=1,NSTA	SETP4510
K=NS(J)	SETP4520
IF(TT-DTF(K)) 135,135,136	SETP4530
135 TT=DTF(K)	SETP4540
LT=J	SETP4550
136 CONTINUE	SETP4560
137 IP=NS(I-1)	SETP4570
138 NS(I-1)=NS(LT)	SETP4580
139 NS(LT)=IP	SETP4590
142 CONTINUE	SETP4600
144 KDATA=-1	SETP3550
WRITE(SCRACH) NSTX,NPU,NPV,((P(I,J),I=1,NSTX),J=1,NSTX),	SETP3560
1 ((CUZ(I,J),I=1,NSTX),J=1,NPU),((CVZ(I,J),I=1,NSTX),J=1,NPV)	SETP3570
ET = TO	SETP3580
TZERO = TO	SETP3590
T = TO	SETP3600
TIMES=TZERO-10.	SETP3610
KDAP = 1	SETP3620
KPROP=-1	SETP3630
KDATAS=-1	SETP3640
C(151)= C(151)*CONRD	SETP3650
C(152)= C(152)*CONRD	SETP3660
RETURN	SETP3670
END	SETP3680

```

SUBROUTINE SMOOTH
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RC ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR,JNBRS,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KQB ,KPROP,KS,KSM,KSSL ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA,NSTC,NSTX,NT,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
U ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2,SYG(3,9) ,TFINAL
E ,TFI1(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
CALL IDENT
FLOS = 0.
TIME = TZERO - 10.
NALLSV=NALL
MOPTSV=NPC(1)
DCOMP=-DCOMP
IF(NPC(1)-1) 4,6,2
2 IF(NPC(8)-4) 12,6,12
4 IF(NPC(7).GT.ICOUNT) IF(NPC(8)-4) 16,6,16
IF(NPC(8).LE.1) GO TO 8
IF(NPC(8).LE.3) GO TO 14
6 TZERO = TO
NPC(7) = ICOUNT
GO TO 62
8 NPC(1) = 1
NALL=10
9 IF(NPC(8).EQ.0) GO TO 12
IF(NPC(8).EQ.2) GO TO 12
10 KSM = 1
GO TO 18
12 KSM = 0
GO TO 18
14 IF(NPC(8)-2) 12,12,10
16 NPC(1) = 1
NALL=10
GO TO 9
18 T2 = TO

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WRITE(OUT,1004)	SMTH0280
20 CALL INTAG	SMTH0290
T0=T2	SMTH0300
IF(ET.LE.TIME) GO TO 150	SMTH0310
IF(NPC(1).NE.1) CALL PROP	SMTH0320
24 CALL OUTPUT	SMTH0330
L1=1	SMTH0340
28 IF(T2-TZERO) 60,60,30	SMTH0350
30 ET=ET-DET	SMTH0360
IF(KSM.LE.0) GO TO 38	SMTH0370
36 TIME = TYM(KG)	SMTH0380
37 IF(TIME.LE.ET) GO TO 38	SMTH0390
T2 = TIME	SMTH0400
GO TO 20	SMTH0410
38 T2 = ET	SMTH0420
GO TO 20	SMTH0430
60 NALL=NALLSV	SMTH0440
NPC(1)=MOPTSV	SMTH0450
DCOMP=-DCOMP	SMTH0460
IF(ICOUNT-NPC(7)) 64,62,62	SMTH0470
62 ET=TFINAL	SMTH0480
NPC(1)=1	SMTH0490
L1=0	SMTH0500
GO TO 99	SMTH0510
64 ICOUNT=ICOUNT+1	SMTH0520
DO 66 I=1,6	SMTH0530
66 NTR(I) = 0	SMTH0540
REWIND FIT	SMTH0550
REWIND PGR	SMTH0560
KDATAS=-1	SMTH0570
KDATA=-1	SMTH0580
KPROP=-1	SMTH0590
NCOUNT=0	SMTH0600
L1=1	SMTH0610
BACKSPACE SCRACH	SMTH0620
BACKSPACE SCRACH	SMTH0630
READ (SCRACH) NSTX,NPU,NPV,((P(I,J),I=1,NSTX),J=1,NSTX),	SMTH0640
1 ((CUZ(I,J),I=1,NSTX),J=1,NPU),((CVZ(I,J),I=1,NSTX),J=1,NPV)	SMTH0650
CALL IDENT	SMTH0660
99 RETURN	SMTH0670
150 MTYP=MTP(KG)	SMTH0680
IF(KG.EQ.0) GO TO 158	SMTH0690
CALL OBSERV	SMTH0700
DO 156 I=1,3	SMTH0710
IF(MR(I,MTYP)) 152,154,152	SMTH0720
152 RES(I)=OFM(1)-DAT(I,KG)	SMTH0730
IF(MTYP.GT.5) GO TO 153	SMTH0740
IF(I.EQ.1) GO TO 153	SMTH0750
IF(ABS(RES(I)).LT.3.1416) GO TO 153	SMTH0760
RES(I)=RES(I)-SIGN(6.283185307179586,RES(I))	SMTH0770
153 CONTINUE	SMTH0780
RES(I+3)= RES(I)/SP(I)	SMTH0790
FLOS= FLOS + RES(I+3)**2	SMTH0800
KD(I)=NCOUNT	SMTH0810
NCOUNT=NCOUNT-1	SMTH0820
GO TO 156	SMTH0830
154 RES(1)=0.	SMTH0840
RES(I+3)=0.	SMTH0850
KD(I) = 0	SMTH0860
156 CONTINUE	SMTH0870

IF(L1.NE.0) WRITE(OUT,1000)	SMTH0880
L1=0	SMTH0890
WRITE(OUT,1002) (KD(I),I=1,3),MTYP,TO,(RES(I),I=1,6),FLOS	SMTH0900
KG=KG-1	SMTH0910
IF(KG.GT.0) GO TO 36	SMTH0920
158 TIME=TZERO-10.	SMTH0930
GO TO 37	SMTH0940
1000 FORMAT(//5X6HPOINTS4X,4HTYPE,3X,4HTIME,6X,4HRES1,9X,4HRES2,9X,4HRES	SMTH0950
XS3,9X,8HWGT.RES1,5X,8HWGT.RES2,5X,8HWGT.RES3,5X,9HLOSS FCTN)	SMTH0960
1002 FORMAT(1X,I4,1H,I4,1H,I4,1X,I2,1X,F10.3,7(1X,E12.5))	SMTH0970
1004 FORMAT(///20(1H*),25HBEGIN BACKWARDS SMOOTHING,75(1H*))	SMTH0980
END	SMTH0990

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SUBROUTINE STAT
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3) ,KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP ,KS ,KSM ,KSS ,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,NB(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
EQUIVALENCE (SP(3),PHIDT),(SP(4),CAPHI)
IF(MTYP.GT.5) RETURN
N = 60 + 15*MTYP
SP(1) = COS(C(N+13))
SP(2) = SIN(C(N+13))
C-----CALCULATE EQ.(237) -----
PHIDT = ATAN2(RERP2*SP(2),SP(1))
CAPHI= PHIDT - C(N+13)
SPHDT(MTYP)=SIN(PHIDT)
CPHDT(MTYP)=COS(PHIDT)
CCAPH(MTYP)= COS(CAPHI)
SCAPH(MTYP)= SIN(CAPHI)
ROT(MTYP) = REO/SQRT(1.+(RERP2-1.)*SP(2)**2)
99 RETURN
END

```

FUNCTION TAB(TARG,N,T,Y)	TAB 0000
DIMENSION N(1),T(1),Y(1)	TABT0010
IF(N(1))111,14,111	TABT0020
111 CONTINUE	TABT0030
I = N(2)	TABT0040
6 IF(TARG - T(I))3,2,1	TABT0050
1 IF(N(3))9,5,9	TABT0060
5 I = I + 1	TABT0070
IF(I-N(1)) 6,4,4	TABT0080
4 I = I - 1	TABT0090
8 TAB = (Y(I+1)*(TARG - T(I)) - Y(I)*(TARG - T(I+1)))/(T(I+1)-T(I))	TABT0100
7 N(2) = I	TABT0110
99 RETURN	TABT0120
11 I = I - 1	TABT0130
2 TAB = Y(I)	TABT0140
GO TO 7	TABT0150
9 IF(TARG - T(I-1)) 4,11,12	TABT0160
3 IF(N(3))5,10,5	TABT0170
10 IF(TARG - T(I-1))12,11,4	TABT0180
12 I = I - 1	TABT0190
IF(I-1)18,8,6	TABT0200
18 I=1	TABT0210
GO TO 8	TABT0220
14 TAB = 0.	TABT0230
RETURN	TABT0240
END	TABT0250

Martin Marietta Corporation
 Denver, Colorado, June 6, 1969

APPENDIX

DATA CONDITIONING

During postflight analyses studies the measurement data must be conditioned before being used in STEP. The airborne measurements received from the telemetry signal must be decoded, digitized, calibrated, time corrected, edited, smoothed, and formatted for use on the PQR tape. The data are not smoothed if they are to be used on the FIT tape. The radar tracking data must be edited, and formatted for use on the FIT tape. Methods that were used on the PRIME program postflight analyses are presented for accomplishing these data conditioning tasks. These methods are certainly not unique, but nevertheless do suggest one way of performing the data conditioning.

Consider a single channel of telemetry data that has been decoded, calibrated, and digitized. For each data point, their corresponds a time. This time must be consistent with the range time that is recorded with the tracking data. If the telemetry time is obtained from an airborne clock, then time corrections on the telemetry data may be necessary. These time corrections can be obtained by comparing range time and telemetry time at points where discrete events occur. This comparison will yield corrections that can be made to the telemetry time bringing it into agreement with range time. The measurement data may appear as shown in figure A1.

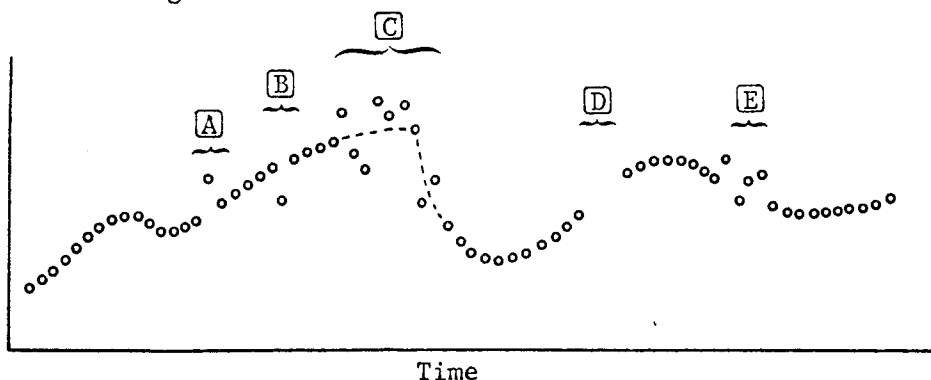


Figure A1.- Measurement Time History

Several types of anomalies are presented in figure A1. At A and B single wild points can be seen; at C is a series of approximately nine erroneous data points; at D is missing data, and at E another series of erroneous data points. The first problem encountered in the data conditioning task is that

APPENDIX

of determining where such anomalies occur. One must then decide if and how the data should be replaced. Finally, the data are smoothed if they are to be used on the PQR tape.

A. Determination of Anomalies

Erratic data can be manually identified by plotting the data. This, however, is very time consuming. Another way is to form a difference table for the data as tabulated below

<u>t</u>	<u>X</u>	<u>ΔX</u>	<u>Δ²X</u>	<u>Δ³X</u>
0	0.563	0.302		
0.1	0.865	0.310	0.008	-0.002
0.2	1.175	0.316	0.006	0.001
0.3	1.491	0.323	0.007	0.001
0.4	1.814	0.331	0.008	-0.001
0.5	2.145	0.338	0.007	-0.001
0.6	2.483	0.344	0.006	-0.006
0.7	2.827	0.344	0	0.005
0.8	3.171	0.349	0.005	
0.9	3.520			
⋮				
⋮				
⋮				

where
$$\Delta^n X_i = \Delta^{n-1} X_{i+1} - \Delta^{n-1} X_i$$

For well-behaved data the higher differences remain small. Should a wild point occur it can immediately be identified by a rapid change in the higher differences. For example, if at $t = 0.5$ let $X = 4.145$ instead of 2.145. The errors in the differences fan to the right as follows:

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t	X	ΔX	$\Delta^2 X$	$\Delta^3 X$
0	0.563			
0.1	0.865	0.302	0.008	
0.2	1.175	0.310	0.006	-0.002
0.3	1.491	0.316	0.007	0.001
0.4	1.814	0.323	2.008	2.000
0.5	4.145	2.331	-3.993	-6.001
0.6	2.483	-1.662	2.006	5.999
0.7	2.827	.344	0	-2.006
0.8	3.171	.344	.005	.005
0.9	3.520	.349		

Such errors can be detected by testing the second or higher differences. When an erratic change occurs, a wild point or abrupt change in the data is detected. Where abrupt changes are known to occur (e.g., engine ignition or shutdown) the difference test should be neglected.

The difference test is implemented in the data conditioning task as follows. The n data channels are stored in chronological order on magnetic tape where each record contains N data points formatted as follows

N	$T(1)$	$X(1,1)$	$X(1,2)$	$X(1,3)$. . .	$X(1,m)$
	$T(2)$	$X(2,1)$	$X(2,2)$	$X(2,3)$. . .	$X(2,m)$
	.					
	.					
	.					
	$T(N)$	$X(N,1)$	$X(N,2)$	$X(N,3)$. . .	$X(N,m)$

where m is the number of data channels (or separate measurements), and N is the number of time points per record. The data are then processed through a computer program that tests the second difference. When a difference exceeds a given value

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the erroneous point is flagged on a tab printout as well as on a magnetic tape on which the data are recorded using the following format:

```
N T(1)  I(1,1), I(1,2) . . . I(1,m)  X(1,1) X(1,2) . . . X(1,m)
T(2)  I(2,1), I(2,2) . . . I(2,m)  X(2,1) X(2,2) . . . X(2,m)
.
.
T(N)  I(N,1)  I(N,2) . . . I(N,m)  X(N,1) X(N,2) . . . X(N,m)
```

The m fixed point flags for each line of data $I(.,1)$ $I(.,2)$. . . $I(.,m)$ are normally zero. If a wild point is detected in channel k its flag $I(.,k)$ is set to one. Inspection of these flags on the tab printout allows immediate identification of the time and data channel for which an erratic point has been detected.

If unequally spaced time intervals occur in the data, divided differences can be used instead of the ordinary differences shown above. Should data gaps occur as in D of figure A1, the data should be replaced if they are to be used in the PQR tape. For data to be used in the FIT tape, the gap need not be replaced. Therefore, as the data are being tested for wild points, the time is simultaneously tested for gaps. When a gap is detected, the line of data is written on the tab printout and output tape. Because the missing data are unknown, zeros are written for the X s and the flags $I(i,j)$ set to one. The time is obtained by linear interpolation using points adjacent to the gap.

The output tape, called output tape 1, and tab printout, which are ultimately produced by this first stage of processing contains the times, flags and data. Where the data are correct, the flag is zero. Where data have been detected to be erroneous or missing, the flag is 1.

B. Data Replacement

Data to be used on the FIT tape requires no further processing. Final formatting will use only those points having zero flags on output tape 1 above. For data to be used on the PQR tape, replacement of wild points and gaps is performed next. The output tape 1, resulting from the processing in Subsection A

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above, is read into a program, which replaces all data with flags equal to one (wild points and gaps). The point replacement is accomplished by fitting a cubic polynomial to four "good" point bounding the gap or wild point. The points are then replaced by interpolating the cubic polynomial for the erroneous or missing data. The fitting points for the interpolating polynomial are spread as shown in figure A2 so that noise in the fitting data will not be exaggerated.

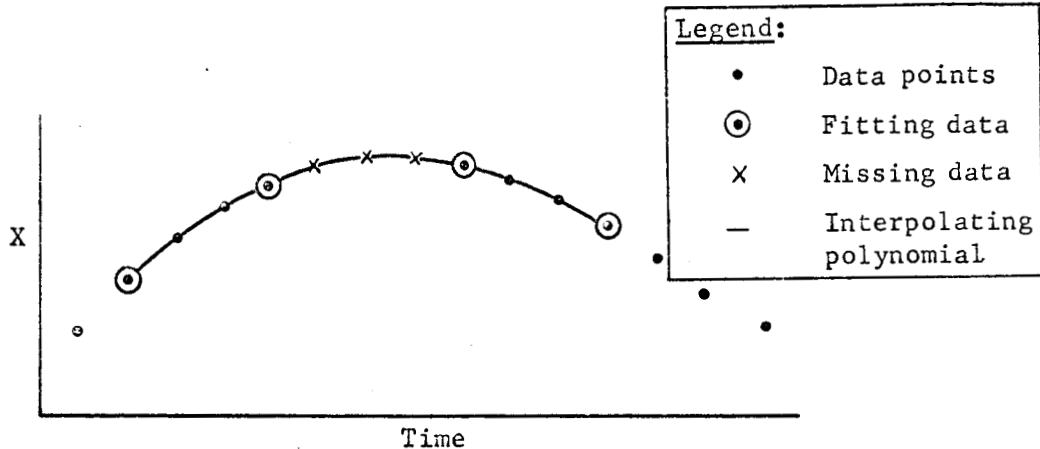


Figure A2.- Replacement by Interpolation

The points to which the polynomial are fit are circled in figure A2. If k points are to be interpolated in the gap, then the first and $k + 1$ st points on each side of the gap are used to fit the cubic polynomial. As the gaps and wild points are replaced by interpolation their flags are set to 2.

Occasionally, cubic polynomials cannot be used to replace wild points or gaps. In set C of figure A1, it can be seen that a cubic polynomial would undoubtedly replace the data improperly. However, an individual knowing what physically occurred during this time might be better able to fair a reasonable curve through the region. Therefore, a second way of replacing data is by card input. The user specifies the time, channel, and value for the data, and the program inserts it on output tape 2 flagged with a 3 to denote that it was provided by the user.

C. Smoothing

The data on output tape 2 resulting from the data replacement task above, is next inputted into a program that smoothes it. If

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time derivatives of the data are required (as is the case with strapped-down accelerometers and gyros), smoothing and differentiating occurs. Smoothing and differentiating formulas used on the PRIME program are classified as linear finite memory smoothing, and smoothing and differentiating formulas (see ref. 3). The smoothing formula assumes the form

$$C_n = \sum_{k=0}^{n-1} a_k r_{n-k} \quad (A1)$$

where C_n is the value of a smoothed parabola fit to n data points r_1, r_2, \dots, r_n and evaluated at the end point n . The a_k are the coefficients of the linear filter and are calculated as follows;

$$a_k = \mu_1 + \mu_2 k + \mu_3 k^2 \quad (A2)$$

with

$$\mu_1 = \frac{18(2n-1)\alpha + 30\alpha^2 + 3(3n^2 - 3n + 2)}{n(n+1)(n+2)} \quad (A3)$$

$$\mu_2 = -\frac{12(2n-1)(8n-11)\alpha}{n(n-1)(n+1)(n^2-4)} - \frac{180\alpha^2}{n(n+1)(n^2-4)} \quad (A4)$$

$$\mu_3 = \frac{180\alpha}{n(n+1)(n^2-4)} + \frac{180\alpha^2}{n(n^2-1)(n^2-4)} + \frac{30}{n(n+1)(n+2)} \quad (A5)$$

where α is the amount of lag or lead (i.e. $C_n = R_{n+\alpha}$). For an end point filter $\alpha = 0$, for a midpoint filter $\alpha = -\frac{n-1}{2}$ with n odd.

For smoothing and differentiating, C_n in equation (A1) is the first derivative of a smoothed parabola fit to the n data points r_1, r_2, \dots, r_n and evaluated at point n with lag or lead α . The coefficients are calculated from equation (A2) with

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$$\mu_1 = \frac{6(6n - 3 + 10\alpha)}{nT(n + 1)(n + 2)} \quad (A6)$$

$$\mu_2 = \frac{12[(8n - 11)(2n - 1) + 30(n - 1)\alpha]}{nT(n^2 - 1)(n^2 - 4)} \quad (A7)$$

$$\mu_3 = \frac{180(n - 1 + 2\alpha)}{nT(n^2 - 1)(n^2 - 4)} \quad (A8)$$

where T is the fixed time interval between adjacent data points.

Equation (A1) is an end point filter since to find C_n the n data points before and including r_n are used. By a simple transformation the end point filter can be converted to any other type filter by merely shifting the points being used to the right of C_n by means of α .

An obvious difficulty arises when attempting to apply the filter near the beginning, or end of a table or across a discrete such as thrust ignition or termination. At the beginning a table the filter is commenced as an end point filter and "grown" to a midpoint (or whatever is desired) filter as the filter is walked through the data. At the end of a table, a midpoint filter is grown into an end point filter. At discontinuities, the filter is changed from midpoint to endpoint at the discontinuity. Then it is restarted as an end point filter on the other side of the discontinuity and grown back to a midpoint filter. On the PRIME program, the filter span (number of points N) was decreased as the data nonlinearity increased. When the vehicle was out of atmosphere and the data very smooth an eleven point filter was used. This was reduced to a five-point filter during in-atmosphere maneuvers.

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