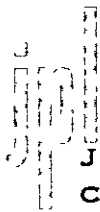
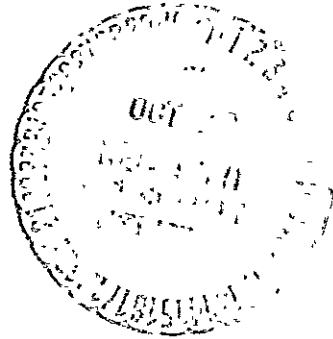


N166-23501

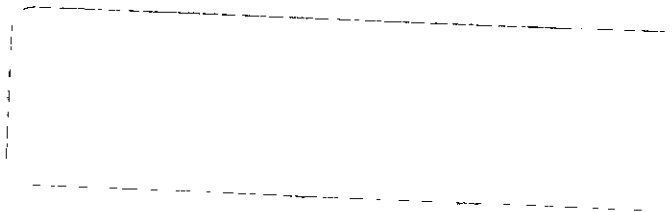
Technical Memorandum No. 33-204
***SPODP - Single Precision Orbit
Determination Program***

Michael R. Warner
Melba W. Nead



**JET PROPULSION LABORATORY
CALIFORNIA INSTITUTE OF TECHNOLOGY
PASADENA, CALIFORNIA**

February 15, 1965



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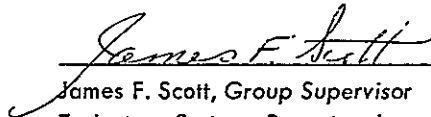
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Technical Memorandum No. 33-204

*SPODP – Single Precision Orbit
Determination Program*

Michael R. Warner

Melba W. Nead


James F. Scott, Group Supervisor
Trajectory Systems Programming


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**JET PROPULSION LABORATORY
CALIFORNIA INSTITUTE OF TECHNOLOGY
PASADENA, CALIFORNIA**

February 15, 1965

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California Institute of Technology

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National Aeronautics & Space Administration

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ABSTRACT

This Technical Memorandum describes the Single Precision Orbit Determination Program which was developed for operation under the data processing system of the Space Flight Operations Facility. Included are sections containing flow diagrams, load maps, the common storage map, input and output descriptions, subroutine writeups, operating instructions, and check cases. The computational methods employed by the program are described in the subroutine documentation.

I. INTRODUCTION

The Single Precision Orbit Determination Program (SPODP; more commonly expressed as ODP) for the IBM 7094 computer was written to meet the specifications of the Jet Propulsion Laboratory for a reliable and accurate method of tracking and predicting the motion of lunar and interplanetary spacecraft. The uses of the ODP may conveniently be separated into real-time and nonreal-time applications.

Real-time applications:

1. To establish a reliable set of orbital elements for the spacecraft.
2. To provide an acquisition ephemeris for the world-wide network of tracking stations.
3. To assist JPL engineers in evaluating the performance of tracking stations and the quality of tracking data.

Nonreal-time applications:

1. To provide a high-speed computing method necessary for orbit determination and tracking data accuracy studies (pre-mission).
2. To provide a high-speed computing method necessary for a sophisticated orbital analysis based on large numbers of observations (post-mission).

In addition to solving for the six initial conditions of the spacecraft's motion, the ODP has the capability of solving for 14 physical constants and the Earth radius, latitude, and longitude of 15 tracking stations. From this set of 66 parameters, a subset containing from one to twenty is extracted by the user. The ODP obtains solutions for the parameters in this subset.

The ODP, since it must have initial estimates of the parameters, is an orbit improvement program. It differentially connects the estimates by means of an over-determined system of equations, employing a modified least-squares method. This procedure may be briefly outlined as follows:

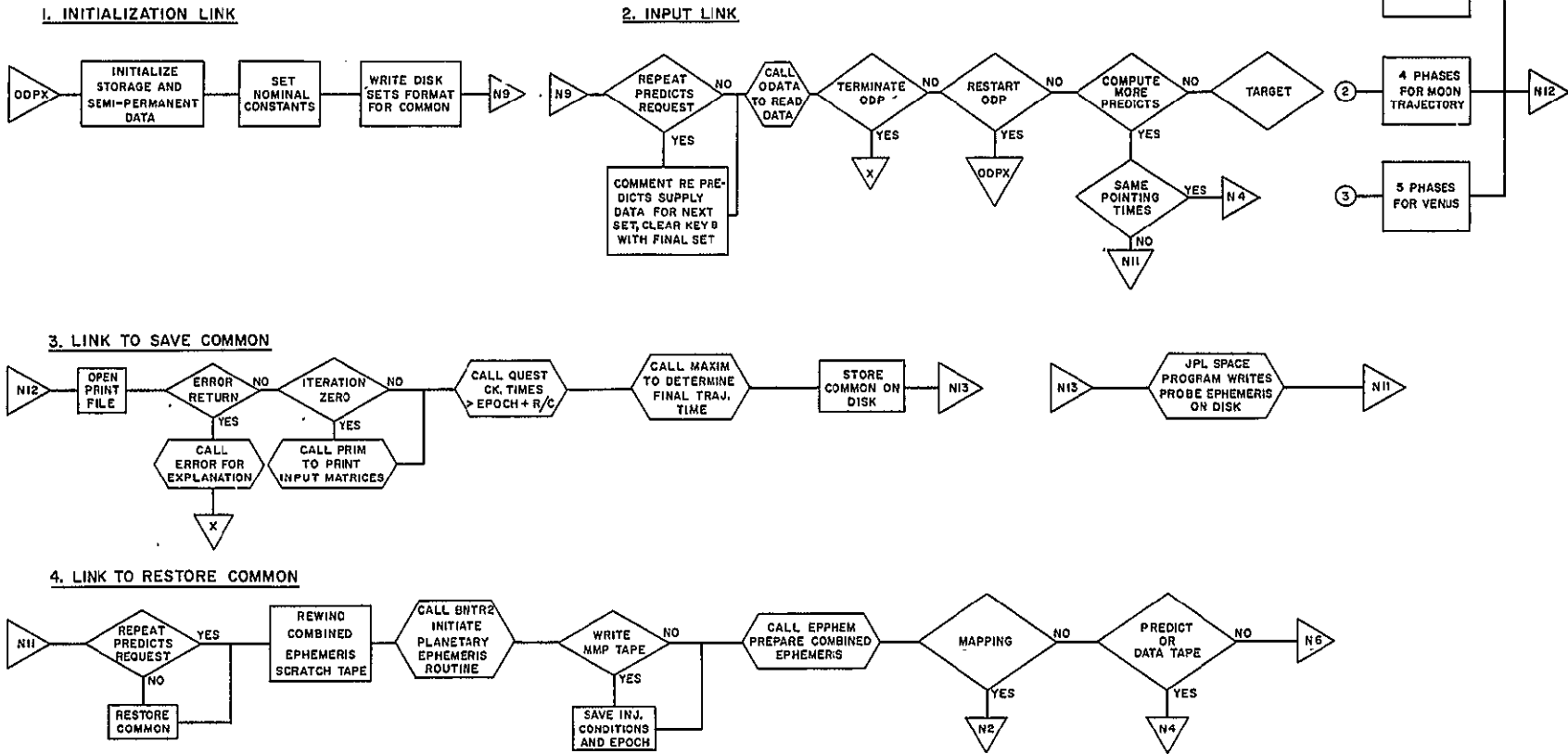
1. Input parameter estimates.
2. Write probe ephemeris file on disk based on orbit estimate.
3. Read i^{th} observation from data file, G_i . This observation may be slant range, range rate, one of four angle types, one of four doppler types, or DSIF ranging.
4. Using probe ephemeris, determine the value of the observation based on orbit estimate, F_i .
5. Obtain the residual $\Delta F_i = G_i - F_i$.
6. Calculate the partials of the observations with respect to the n parameters to be estimated, $\partial F_i / \partial Q_1, \dots, \partial F_i / \partial Q_n$.
7. Multiply the column matrix of partials by itself to form a matrix J_i^* .
8. Add J_i^* to the accumulated matrix $J^* = J_1^* + J_2^* + \dots, + J_{i-1}^*$.
9. Multiply the column matrix of partials by the residual to form a column matrix R_i .
10. Add R_i to the accumulated column matrix $R = R_1 + R_2 + \dots, + R_{i-1}$.
11. Repeat steps 3 through 10 until all observations are processed.
12. Obtain the final J matrix by adding in the a priori uncertainties. $J = J^* + \tilde{\Gamma}^{-1}$.
13. Solve the normal equations $J\Delta Q = R$ for the column matrix of changes to the parameter estimates, ΔQ .
14. Repeat steps 2 through 13 until the procedure converges.

The ODP is written on disk in thirteen links. Each link constitutes a logical section of the overall orbit determination. The linking is accomplished by use of the JPTRAJ source program, which is also used to pass certain information between links.

II. FLOW CHARTS

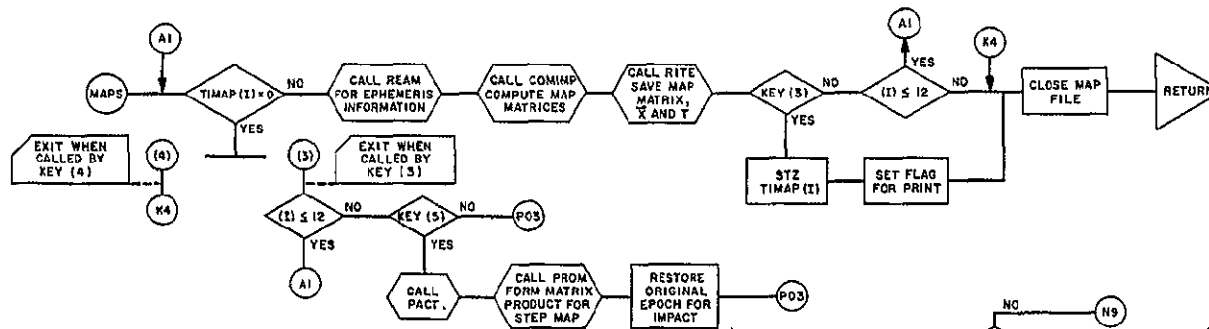
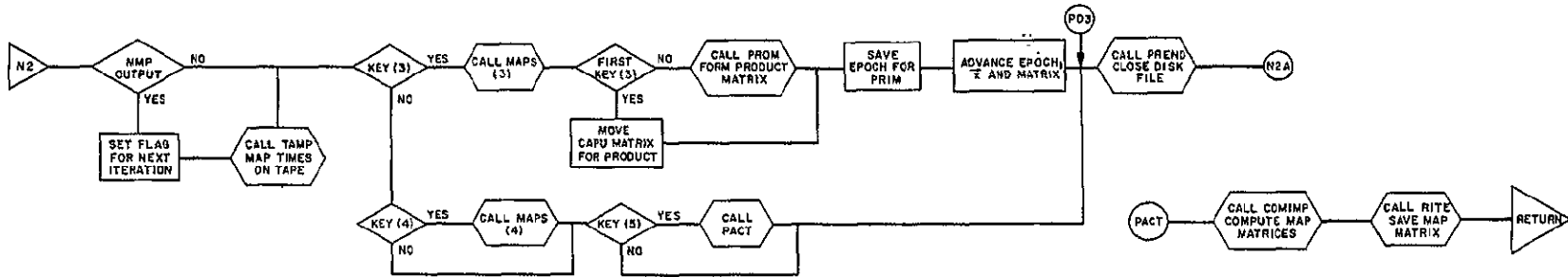
A. LINKS

1. Initialization Link
2. Input Link
3. Link to Save COMMON
4. Link to Restore COMMON
5. Link to Compute Mapping Matrices
6. Link to Output Mapping Matrices
7. Link to Compute Closest Approach Parameters
8. Predictions or Data Simulation Link
9. Link to Sort Predictions
10. Data Fitting Link
11. Link to Output Solution
12. Link to Output Residuals and Statistics
13. Link to Output Auxiliary Quantities

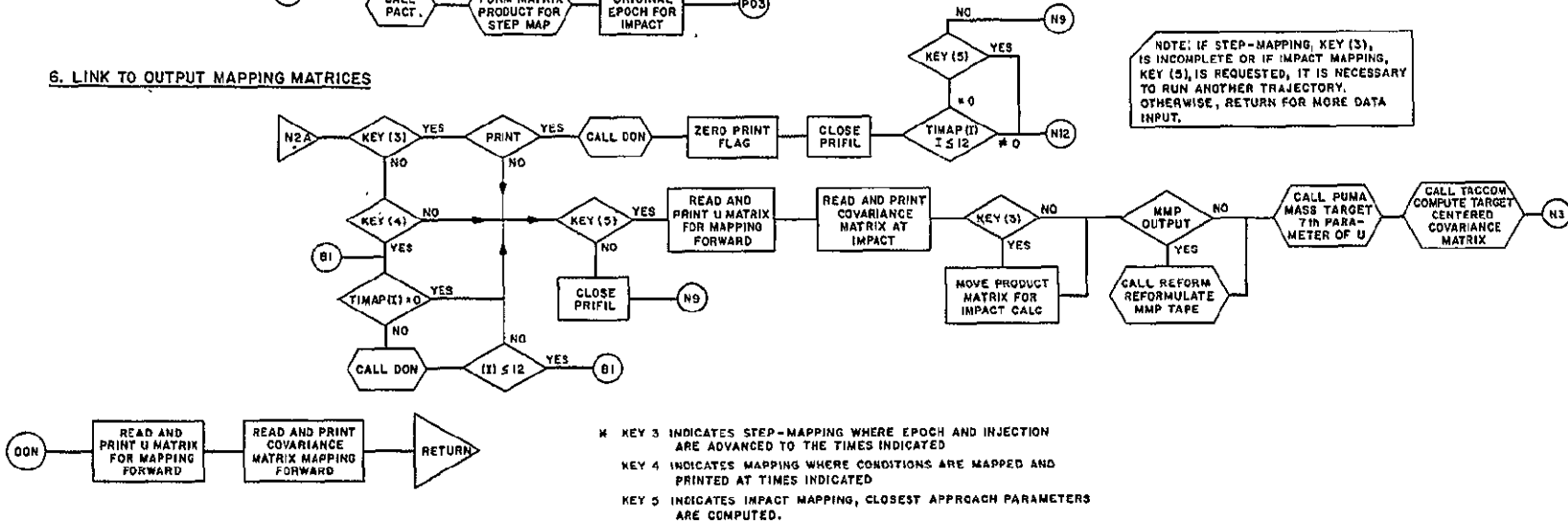


5

5. LINK TO COMPUTE MAPPING MATRICES



6. LINK TO OUTPUT MAPPING MATRICES



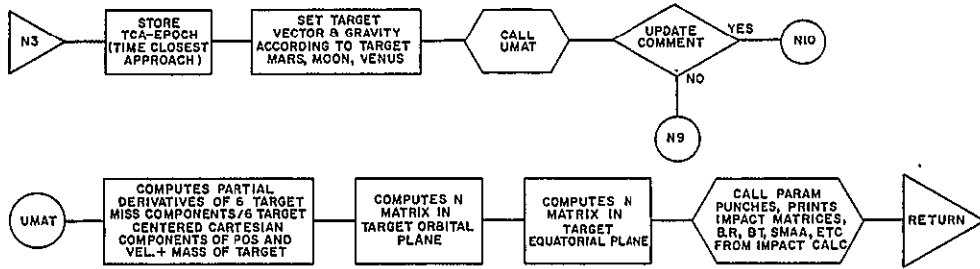
NOTE: IF STEP-MAPPING, KEY (3), IS INCOMPLETE OR IF IMPACT MAPPING, KEY (5), IS REQUESTED, IT IS NECESSARY TO RUN ANOTHER TRAJECTORY. OTHERWISE, RETURN FOR MORE DATA INPUT.

* KEY 3 INDICATES STEP-MAPPING WHERE EPOCH AND INJECTION ARE ADVANCED TO THE TIMES INDICATED

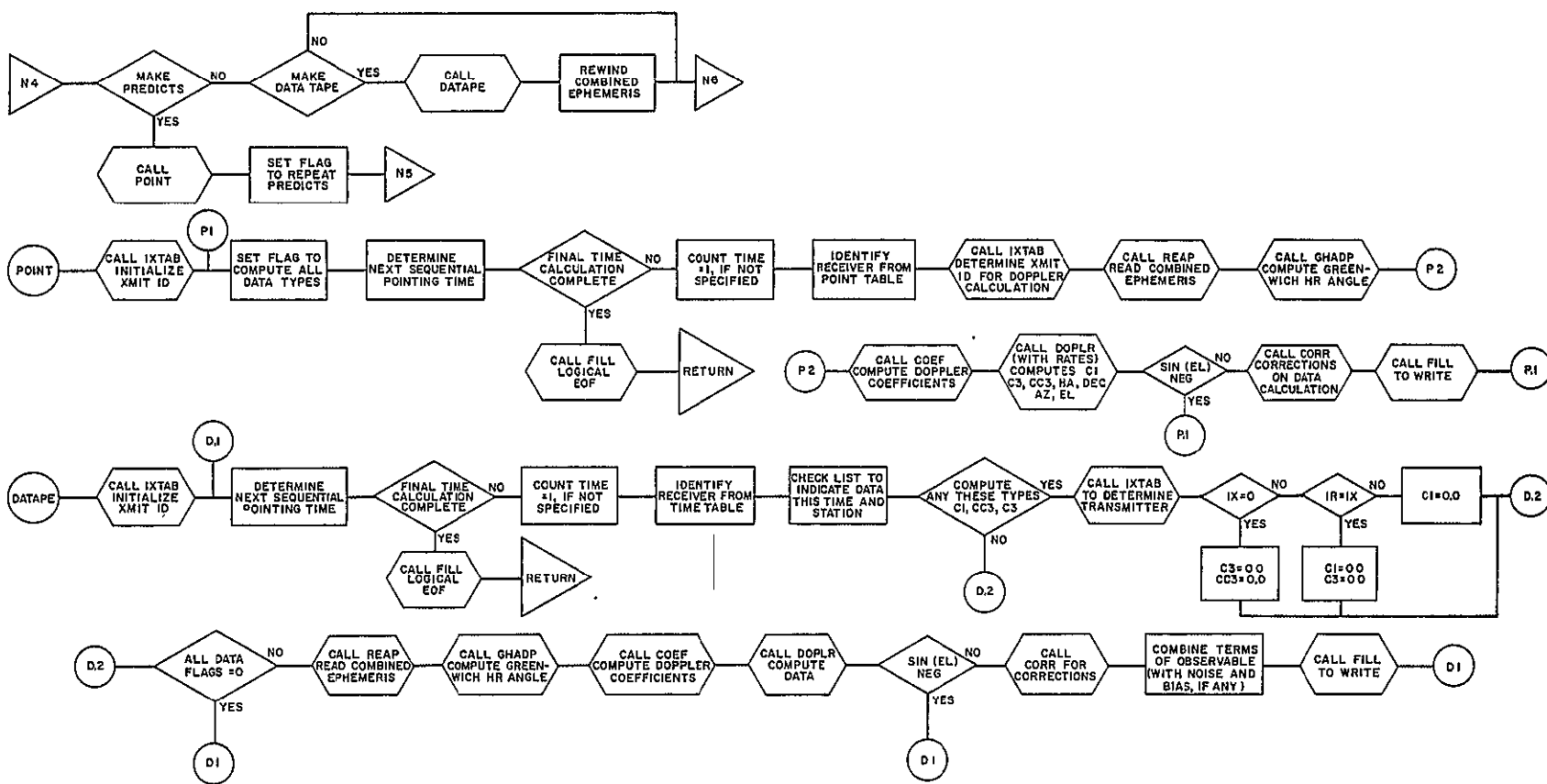
KEY 4 INDICATES MAPPING WHERE CONDITIONS ARE MAPPED AND PRINTED AT TIMES INDICATED

KEY 5 INDICATES IMPACT MAPPING, CLOSEST APPROACH PARAMETERS ARE COMPUTED.

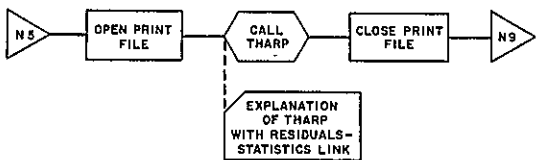
7. LINK TO COMPUTE CLOSEST APPROACH PARAMETERS



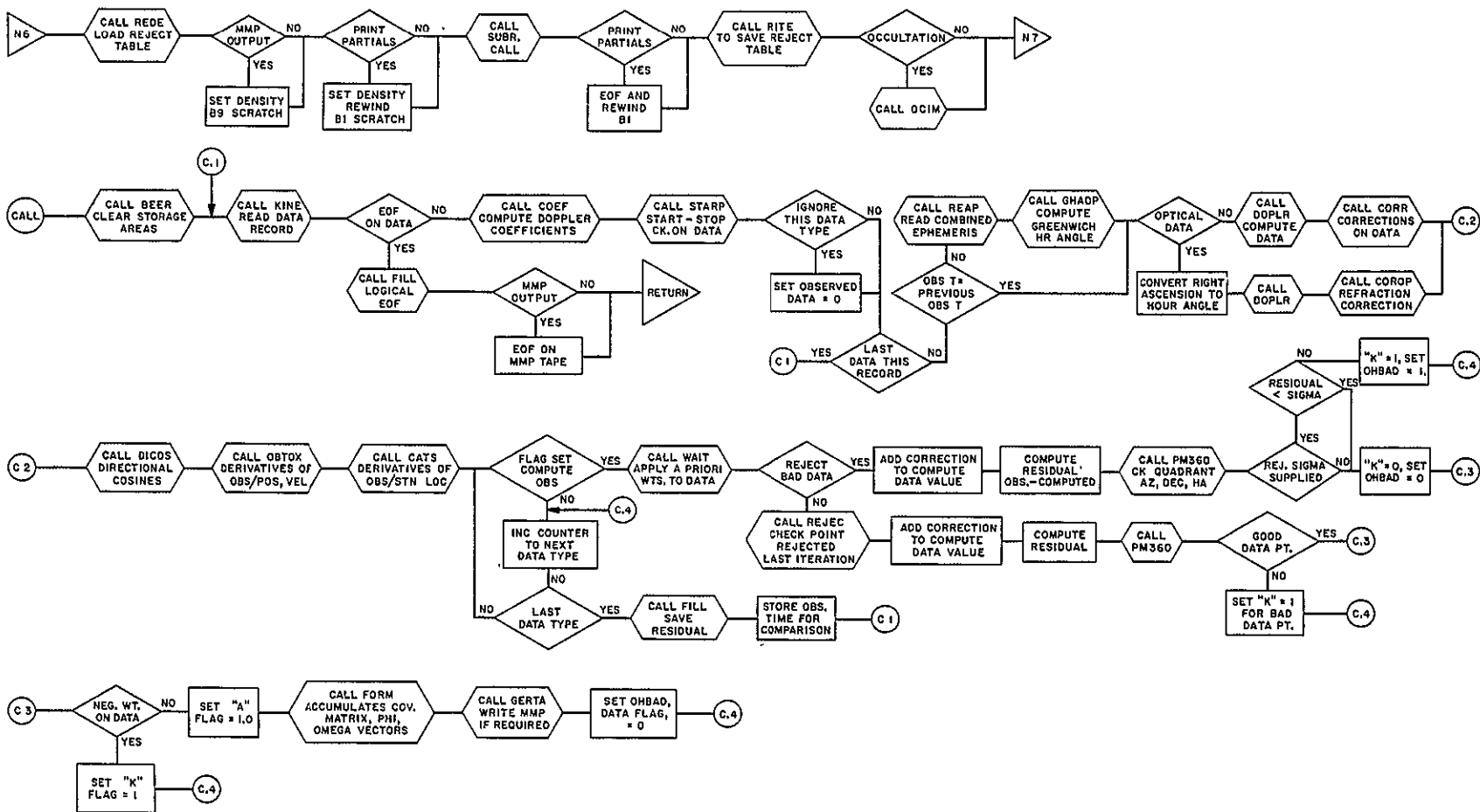
8. PREDICTIONS OR DATA SIMULATION LINK



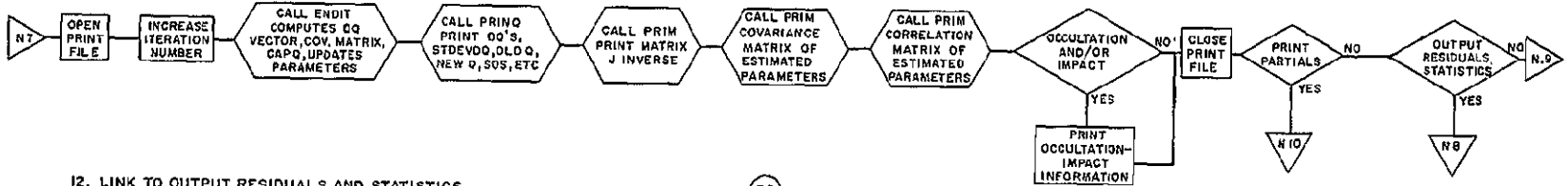
9. LINK TO SORT PREDICTIONS



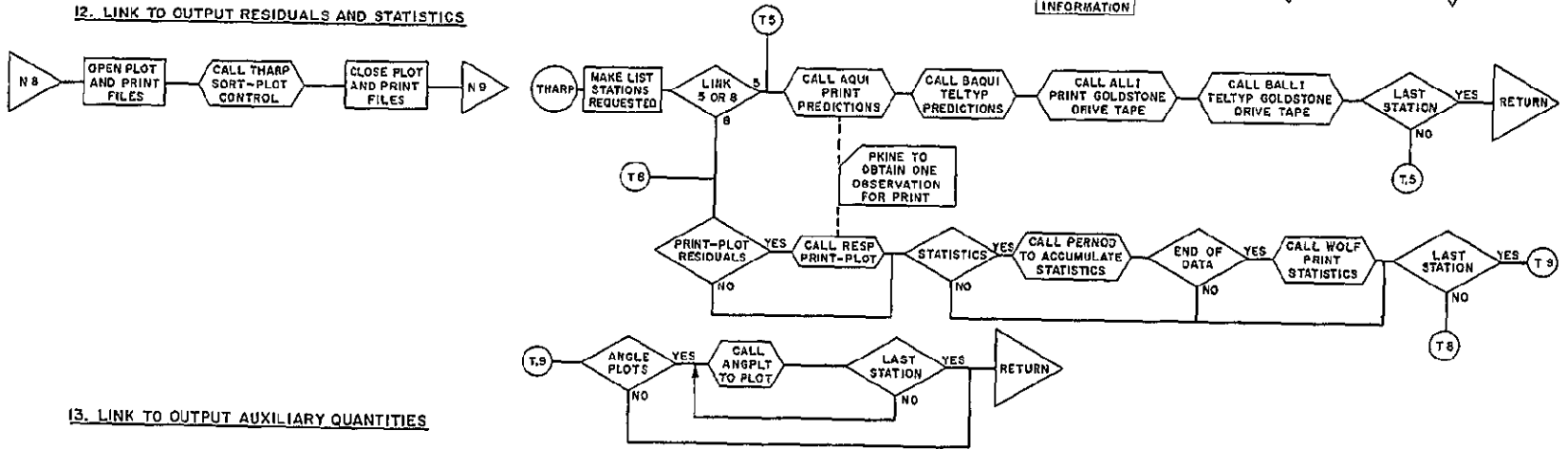
10. DATA FITTING LINK



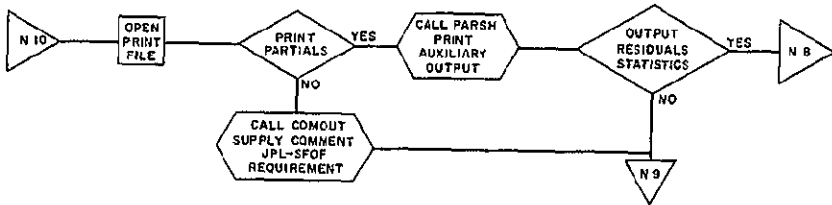
11. LINK TO OUTPUT SOLUTION



12. LINK TO OUTPUT RESIDUALS AND STATISTICS



13. LINK TO OUTPUT AUXILIARY QUANTITIES

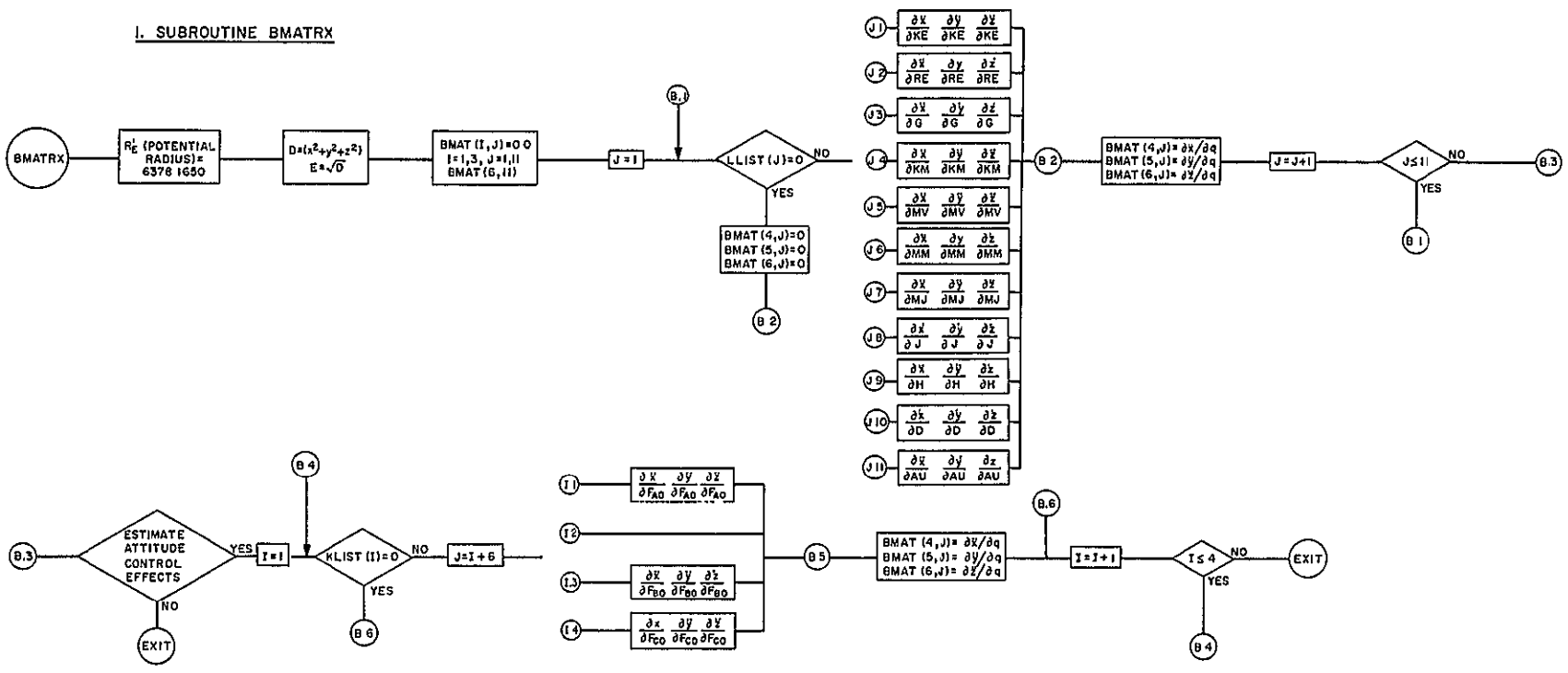


6

B. SUBROUTINES

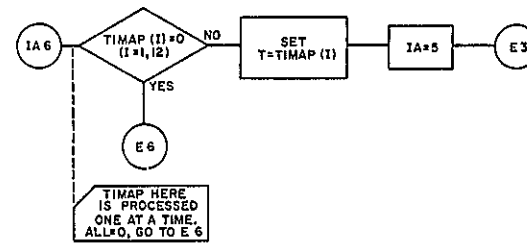
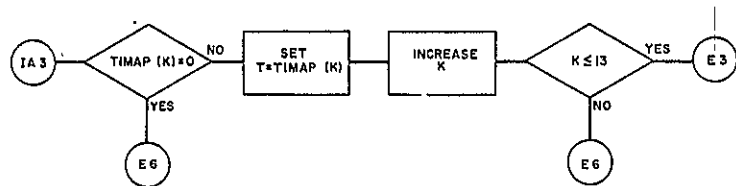
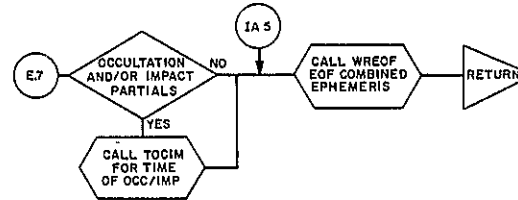
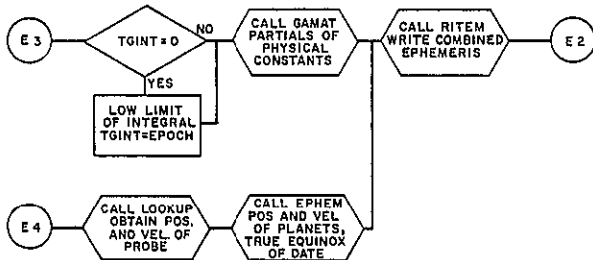
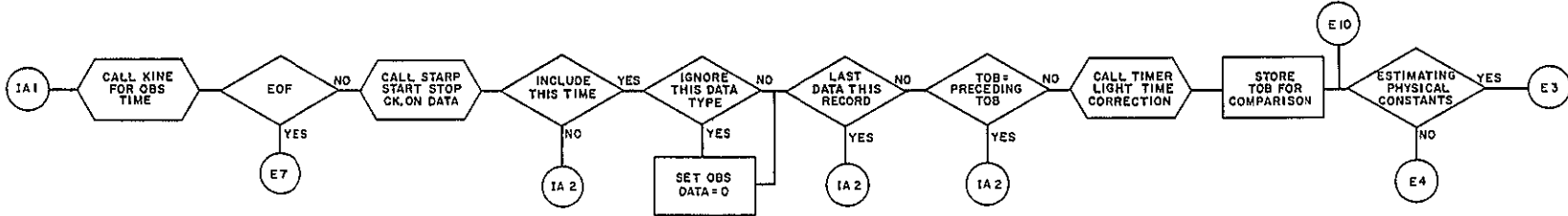
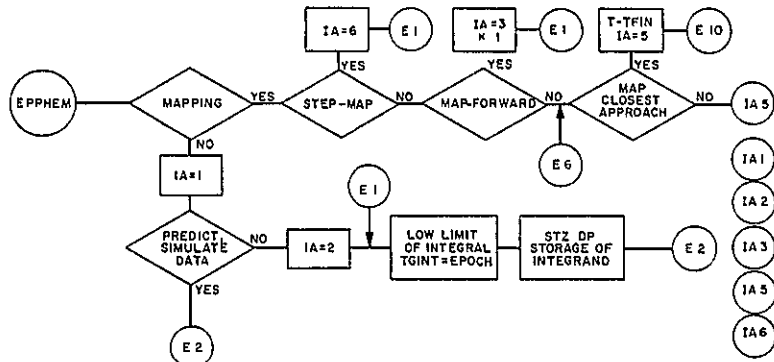
1. BMATRX
2. EPPHEM
3. GAMAT
4. LOOKUP
5. MAXIM

I. SUBROUTINE BMATRIX

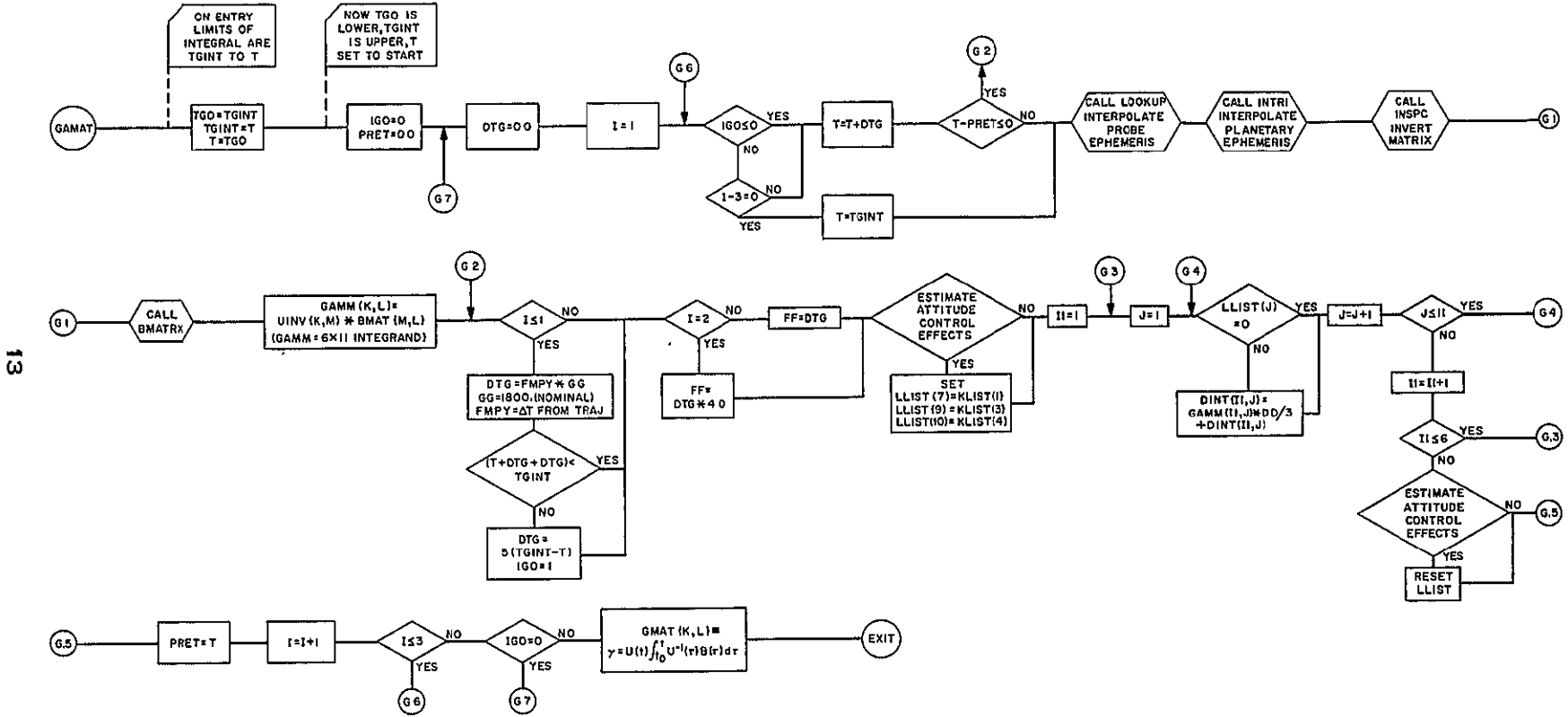


11

2. SUBROUTINE EPPHEM

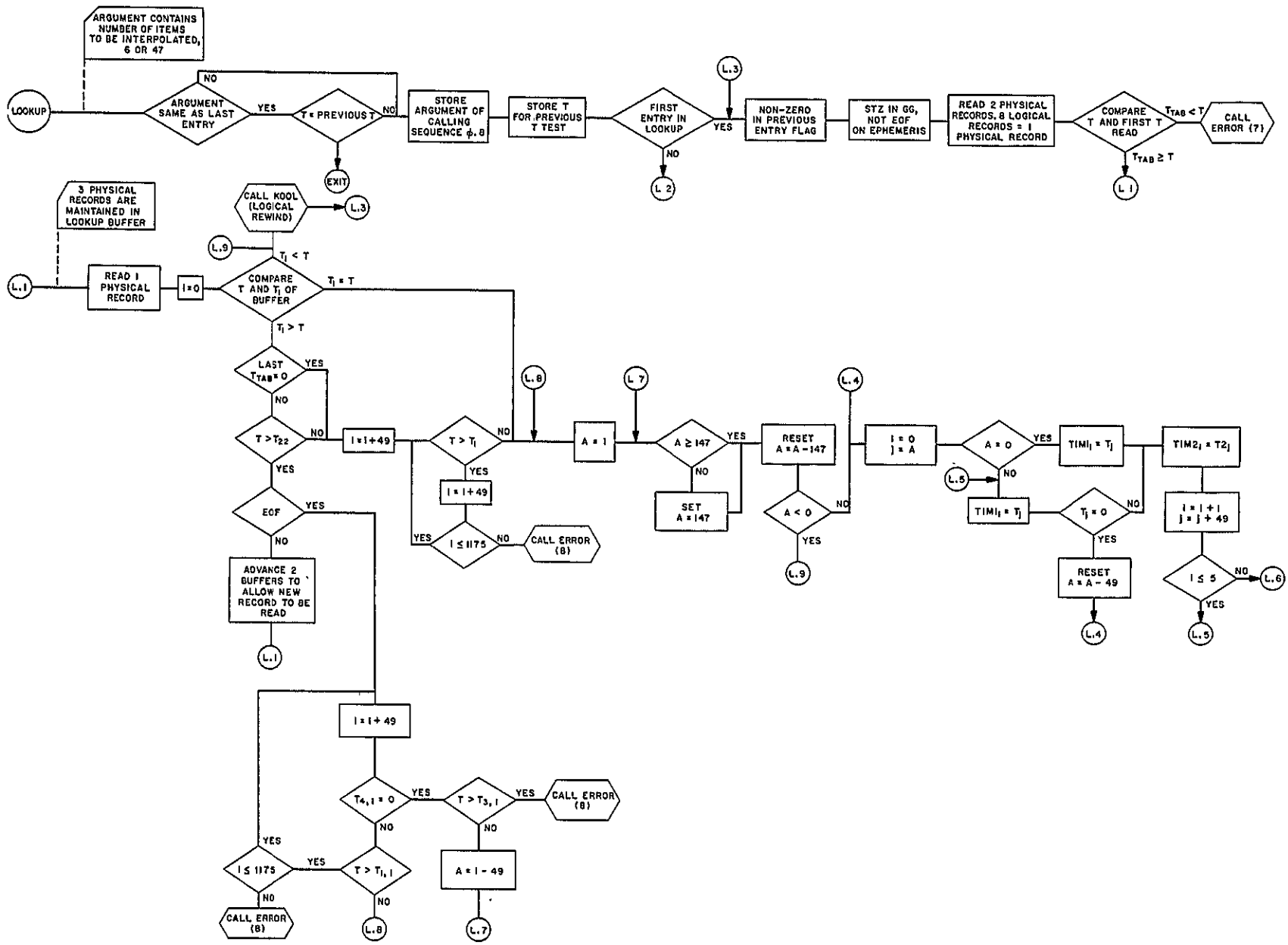


3. SUBROUTINE GAMAT

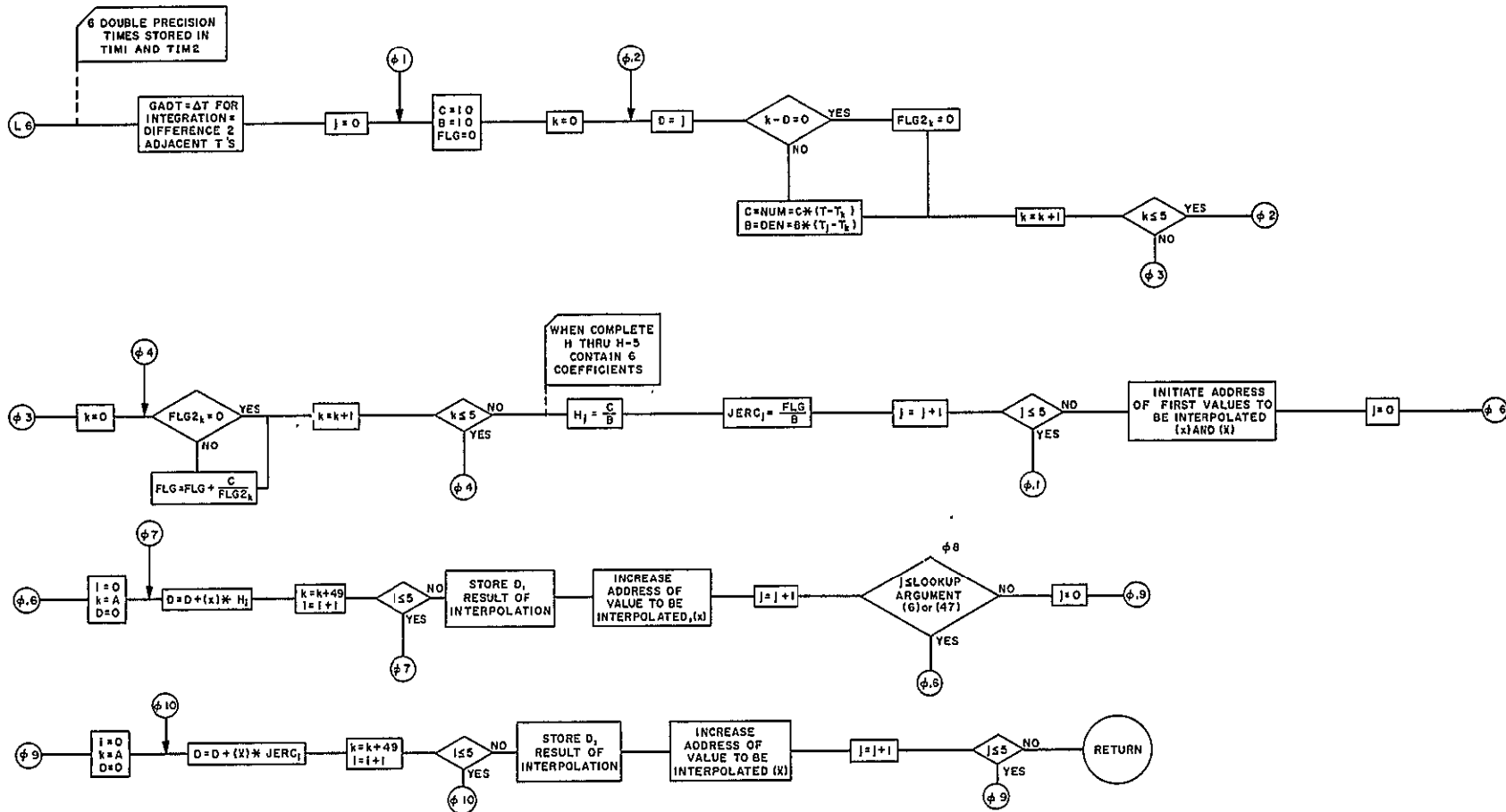


13

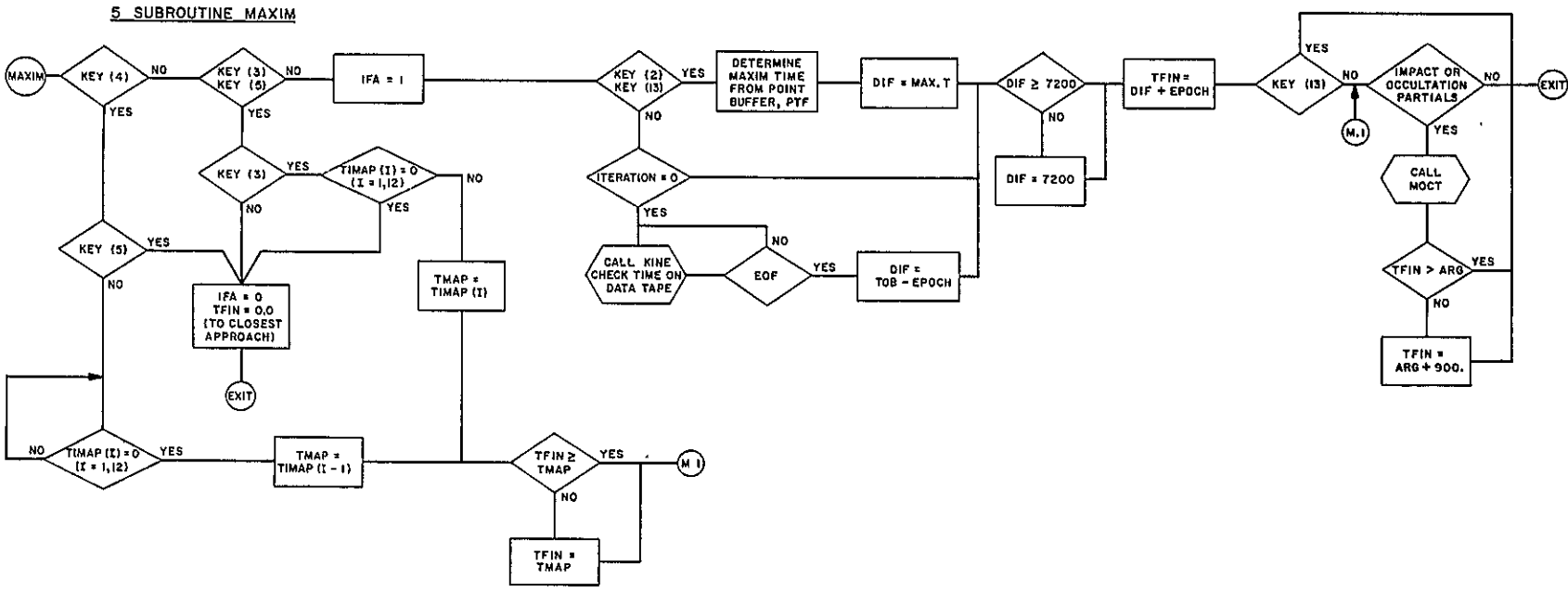
4. SUBROUTINE LOOKUP



4. SUBROUTINE LOOKUP p 2



15



III. PHYSICAL LIMITATIONS

A. DISK AND TAPE USAGE UNDER SFOF

The ODP uses tape unit B6 for the planetary ephemeris (EPHEM) tape and tape unit A4 for the combined ephemeris scratch tape. Disk allocation is restricted to the 2800 record block named JPLODP.

B. DEBUGGING FACILITIES

Snaps may be inserted in links ODPX, LA2A, LA3, LA5, LA7, LA8, LA10, and LA12, as these links contain subroutine PROUT.

Octal correctors may be inserted in any link through the JPTRAJ source deck.

IV. INPUT AND STORAGE ALLOCATION

Primary input to the ODP is a deck of control and data cards, which are described in detail in Section IV. A. These cards contain the parameter estimates, the desired options, and all variables which are not a function of each observation. Subroutine CARDS is used for card input.

Also input to the ODP is a file on disk containing the tracking data, and a planetary ephemeris tape. The data file is written on disk by the Orbit Data Generator Program, ODG, while the ephemeris tape is the standard JPL EPHEM system tape. The system routine DCP is used for disk reading and subroutine TAPIO is used for reading the planetary ephemeris tape.

A. CARD INPUT

JPL TECHNICAL MEMORANDUM NO. 33-204

```

EPOCH
01
*
* EPOCH ASSOCIATED WITH THE TRAJECTORY, WHERE
M YY= LAST TWO DIGITS OF THE YEAR
* MM= MONTH OF THE YEAR
* 0= ZERO
* DD= DAYS
* HH= HOURS
* NN= MINUTES
* SS= SECONDS
* FFF= MILLISECONDS
YHM00DHH,N4SSFF

GEOCENTRIC POSITION AND VELOCITY AT EPOCH
102
*
* SYMBOLS ALLOWED
X,Y,Z,DX,DY,DZ

INPUT OTHER OPTIONS AND CONSTANTS
103
*
* SYMBOL ALLOWED EXPLANATION AND/OR NOMINAL
KE (EARTH) (398603.2KM3/SEC2)
RE EARTH RADIUS (6378.3149KM)
KM KINOMIN
MV MASS RATIO VENUS (2.447118E-6)
MH MASS RATIO MARS (3.2303420E-7)
MJ MASS RATIO JUPITER (9.5475420E-4)
J CJEF. SECOND HARMONIC (1.62345E-3)
H CJEF. THIRD HARMONIC (-.575E-5)
Q CJEF. FOURTH HARMONIC (1.7875E-5)
AJ ASTRONOMICAL UNIT (1.4959986KM)
C VELOCITY OF LIGHT (299792.5KM/SEC)
RI(1) STATION RANGE
LA(1) STATION LATITUDE (GEOCENTRIC)
LJ(1) STATION LONGITUDE
* RI(1)=6372.2599 LA(1)=-35.066620 LJ(1)=243.20507
* RI(2)=6372.0341 LA(2)=35.20807 LJ(2)=243.15082
* RI(3)=6371.6686 LA(3)=-35.219630 LJ(3)=148.98028
* RI(4)=6372.6040 LA(4)=-31.211875 LJ(4)=136.88727
* RI(5)=6375.4980 LA(5)=-25.739277 LJ(5)=27.685181
* RI(6)=6376.3091 LA(6)=17.0355 LJ(6)=298.2072
* RI(7)=6377.8013 LA(7)=-7.8991 LJ(7)=345.5876
* RI(8)=6376.1150 LA(8)=18.064939 LJ(8)=292.91122
* RI(9)=6375.6810 LA(9)=-25.7904 LJ(9)=28.3580
* RI(10)=6374.05 LA(10)=-24.75336 LJ(10)=113.71605
* RI(11)=6372.05 LA(11)=32.1709 LJ(11)=295.3465
* RI(12)=6371.6586 LA(12)=-35.21963 LJ(12)=148.98028
* RI(13)=6370.0868 LA(13)=40.23800 LJ(13)=355.7505
* RI(14)=6375.9450 LA(14)=-18.823066 LJ(14)=204.31472
* RI(15)=6180.1990 LA(15)=10.668 LJ(15)=0.0

NSDISP(1) NORTH-SOUTH DISPLACEMENT, DEG
EWDISP(1) EAST-WEST DISPLACEMENT, DEG
INDEX(1) INDEX OF REFRACTION (340.0)
DRIFT TRANSDUCER DRIFT, CPS/SEC
STEP INITIAL TRAJECTORY STEP SIZE, SEC
ENERGY POWERED FLIGHT ENERGY
DTBURV POWERED FLIGHT DURATION
MOTOR MOTOR COUNT
JETON JETON FOR A.C.
JETOFF JETOFF FOR A.C.
PREDID IDENTIFICATION FOR PREDICTS
READ ORBIT FROM DISK ORBIT STORED ON DISK IN LINK 6
READ MATRIX FROM DISK MATRIX STORED ON DISK IN LINK 6
SOLAR PRESSURE OFF
LIGHT TIME OFF
REFRACTION AND VERTICAL OFF
IMP OUTPUT
PHI VECTOR OUTPUT
UPDATE COMEVI TO WRITE DISK FOR M/C AND SPACE
DJT L.T.-U.T., SEC (35.)
FJELMT WEIGHT OF FUEL, LB.
RFUPL FLOW RATE, LB/SEC
THRUST THRUST, LB
BRNNG BIAS ANGLE, DEG
RSTOP TARGET RADIUS, KM (MARS,3400.0)
* (VENUS,1738.09)
* (EARTH,6200.0)
RAND INPUT FOR RANDOM NUMBER, OCTAL (1)
RMXZ MAXIMUM SLANT RANGE FOR DATA, DEG
ELMIN MINIMUM ELEVATION ANGLE FOR DATA, DEG
DATA SIGMA INPUT RESIDUAL PRINT REPLACED BY
* STANDARD DEVIATIONS
REM CONSTRAINT RE IS DETERMINED BY THE RELATION
* KEM= CODE H001 (86.315745(KC+KM))
* KC AND KM INITIALS ARE CONSISTENT
* WITH THE CONSTRAINT
RADOP? RADIATION PRESSURE OPTION (1.031E8)

FLRES NON-ZERO, RESIDUALS IN FLOATING PT.

PJMAT PUNCH MATRIX, N
1 INPUT J MATRIX OF ESTIMATED PARAMETERS
2 INPUT COVARIANCE MATRIX OF CONSIDERED PARAMETERS
3 J INVERSE
4 COVARIANCE MATRIX OF ESTIMATED PARAMETERS
5 CORRELATION MATRIX OF ESTIMATED PARAMETERS
6 COVARIANCE MATRIX AT IMPACT
7 (ALREADY PUNCHED)
8 J MATRIX
9 INPUT COVARIANCE MATRIX OF ESTIMATED PARAMETERS
10 CORRELATIONS BASED ON J MATRIX
11 U PRODUCT MATRIX

*
* TO CHANGE AREA, MASS, GAMMA B OF SPACECRAFT
ARMARS (11.12)
MSMARS (259.00)
GSMARS (1.076)
ARMHON (2.789)
MSHMON (340.20)

```

JPL TECHNICAL MEMORANDUM NO. 33-204

```

G0K00N          (3.0)
ARVEN           (3.83)
MSVEN          (198.22)
GBVEN          (1.383)

*
* THE FOLLOWING ARE DOPPLER COEFFICIENTS AND
* FREQUENCIES WHICH ARE A FUNCTION OF THE
* BAND. NOMINALLY, STATIONS 1,2, AND 3 ARE
* S BAND, 4 AND 5 ARE L-S BAND.
*
*          L-BAND          L-S BAND          S BAND
TFREQ  TRANSPONDER FREQ  960.0E6        20.00E6        20.00E6
XFREQ  TRANSMITTER FREQ  29.66E6        2290.0E6       2290.0E6

DDP1(1)  (C1)   930.15E6        9.375E6        1.0E6
DDP1(2)  (C1)   -96875         -3125          1.0
DDP1(3)  (CC3)  -1E6          9.375E6        1.0E6
DDP1(4)  (CC3)  32.359559561  32.57918552   104.25339367
DDP1(5)  (C3)   930.15         9.375E6        1.0E6
DDP1(6)  (C3)   31.348314605  32.57918552   104.25339367

DDP2(1)  SAME AS ABOVE FOR STATION 2
DDP3(1)  SAME AS ABOVE FOR STATION 3
DDP4(1)  SAME AS ABOVE FOR STATION 4
DDP5(1)  SAME AS ABOVE FOR STATION 5

INFRQ  GROUND STATION INJECTION FREQUENCY, CPS (23.6279142E6)
SYNFRQ  GROUND STATION SYNTHESIZER FREQUENCY, CPS (22.04209265E6)

L       FOLLOWED BY STATION ID TO ALTER STATION BAND
S       FOLLOWED BY STATION ID TO ALTER STATION BAND
LS      FOLLOWED BY STATION ID TO ALTER STATION BAND

ESTIMATE THESE PARAMETERS                                (04)
CONSIDER THESE PARAMETERS                               (05)

*
* THESE CARDS ARE FOLLOWED BY LISTS OF PARAMETER NAMES
* WHICH TELL THE DDP TO ESTIMATE (CONSIDER) THE
* CORRESPONDING PARAMETER. NO NUMERIC DATA REQUIRED.
* LIST OF PARAMETER NAMES WHICH CAN BE ESTIMATED
* (CONSIDERED).
*
* SYMBOLS ALLOWED
*
X,Y,Z,DX,DY,DZ,KE,RE,G,KM,MV,MM,MJ,J,H,D,AU,C,RI(1),LA(1),LO(1)
*
OR
X1,Y1,Z1,DX1,DY1,DZ1,KE1,RE1,G1,KM1,MV1,MM1,MJ1,J1,H1,D1,AU1,C1,RI1(1),LA1(1),LO1(1)

REJECTION SIGMAS                                       (06)

*
* THE ABOVE CARD IS FOLLOWED BY DATA INDICATING WHICH OF
* THE OBSERVABLES ARE TO BE CHECKED FOR POSSIBLE REJECTION
* OF BAD POINTS. IF A SYMBOL IS ACCOMPANIED BY A NUMERICAL
* VALUE THE OBSERVATION WILL BE REJECTED IF THE ABSOLUTE
* VALUE OF THE RESIDUAL EXCEEDS THE INPUT VALUE.
*
* SYMBOLS ALLOWED

R(1),DR(1),EL(1),AZ(1),DEC(1),HA(1),C(1),CC3(1),
C3(1),DI(1),RU(1)

INVERSE COVARIANCE MATRIX OF ESTIMATED PARAMETERS    (07)
COVARIANCE MATRIX OF ESTIMATED PARAMETERS           (10)
COVARIANCE MATRIX OF CONSIDERED PARAMETERS           (11)

*
* PROVISION IS MADE TO ENTER ONE OF THREE
* MATRICES IN ONE OF THREE WAYS
*
* TO ENTER THE DIAGONAL TERM OF THE MATRIX
DIAG=
*
* TO ENTER THE MATRIX BY ROW
R01=
*
*(CONTINUE ON FOLLOWING CARD, IF NECESSARY)
R02=
R03=
*
* TO ENTER WITH NO SYMBOLS SUPPLY A
* FORTRAN TYPE ARRAY FOR A 20X20 MATRIX

DELETE THESE DATA TYPES                               (13)

*
* SYMBOLS ALLOWED AS IN 106 ABOVE

STATISTICS AND RESIDUALS FOR THESE DATA TYPES         (14)

*
* DESIGNATION OF AT LEAST ONE DATA TYPE PER
* STATION IS NECESSARY FOR THE CALCULATION OF
* STATISTICS. INCLUDE ALL DATA TYPES FOR WHICH
* STATISTICS AND RESIDUALS ARE DESIRED. THE
* VERTICAL PLOTTING SCALE CAN BE DEFINED AS
* R(1)=10., THE HORIZONTAL SCALE CAN BE DEFINED
* AS NHR=1.5. THIS LATTER IS NOMINALLY 1. HOUR
* A MAXIMUM OF 8 DATA TYPES PER STATION MAY BE
* REQUESTED.
*
* SYMBOLS ALLOWED AS FOLLOWS

R(1),DR(1),EL(1),AZ(1),DEC(1),HA(1),C(1),CC3(1)
C3(1),DI(1),RU(1),NHR

NOMINAL VALUES CORRESPONDING TO COVARIANCE MATRIX    (15)

*
* IF A COVARIANCE MATRIX FOR THE ESTIMATED PARAMETERS
* OR ITS INVERSE IS ENTERED THE VALUES OF THE
* ESTIMATED PARAMETERS ASSOCIATED WITH MATRIX MAY
* ALSO BE ENTERED. THESE VALUES FOLLOW THIS CONTROL
* CARD AND MUST BE IN THE SAME ORDER AS THE
* PARAMETERS IN THE MATRIX.
*
* IF NOMINAL VALUES FOR THE PARAMETERS ARE NOT
* ENTERED THE PROGRAM WILL SET THE NOMINAL
* VALUES TO THE INITIAL ESTIMATE OF THE PARAMETERS.
*
* NO SYMBOLS ARE ALLOWED.

```

WEIGHTS BY DATA TYPE AND STATION (116)

* NOMINALLY THE ODP COMPUTES THE WEIGHT FOR EACH DATA TYPE FROM INFORMATION THE ODP PUTS ON THE TRACKING DATA FILE. THE OPERATOR CAN OVERRIDE THIS FEATURE BY FOLLOWING THE ABOVE CARD WITH WEIGHTS (SIGMA RATHER THAN SIGMA SQUARED) FOR ANY OR ALL OF THE DATA TYPES. WEIGHTS MUST BE SPECIFIED IN THIS MANNER WHEN FITTING AN ODP-SIMULATED DATA FILE.

* THE USER MAY ALSO INPUT OCTAL WEIGHT CODES, E.G., CC3(2)=314333/8

* SYMBOLS ALLOWED

R(1),DR(1),EL(1),AZ(1),DEC(1),HA(1),CL(1),CC3(1)
C3(1),DI(1),RU(1)

POINTING TIMES, SAMPLE RATE, COUNT TIMES (117)

* AS THE NAME SUGGESTS, DATA FOLLOWING THIS CONTROL CARD DEFINES THE AMOUNT OF OUTPUT OBTAINED WHEN THE PROGRAM IS PREPARING A DATA FILE OR COMPUTING POINTING PREDICTIONS. A SYMBOLIC NAME IS ASSOCIATED WITH EACH OF THE 15 POSSIBLE TRACKING STATIONS, AND EACH NAME MAY BE FOLLOWED BY ONE, TWO, OR THREE GROUPS OF DATA. THE FORMAT OF EACH GROUP IS AS FOLLOWS: FIRST TIME, LAST TIME, SAMPLE RATE, COUNT TIME. POINTING PREDICTIONS (OR A DATA FILE) WILL BE GENERATED FOR THE INDICATED STATION IF THE PROBE IS ABOVE STATION'S HORIZON ANYTIME BETWEEN THE FIRST TIME AND THE LAST TIME. THE INTERVAL BETWEEN PREDICTIONS IS DEFINED BY THE SAMPLE RATE AND ANY REQUESTED DOPPLER CALCULATIONS WILL BE BASED ON THE INDICATED COUNT TIME. THE TWO TIMES ARE GREENWICH TIME AND ARE COMPOSED OF TWO WORDS EACH, AS DEFINED ELSEWHERE. THE SAMPLE RATE AND THE COUNT TIME ARE GIVEN AS FLOATING POINT SECONDS. AS AN EXAMPLE,

JETMTS=620702103,0,620702104,0,10,5,620702107,0,620702109,0,30,30.

* INSTRUCTS THE PROGRAM TO GENERATE POINTING PREDICTS FOR THE MTS EVERY 10 SEC BETWEEN 030000Z AND 040000Z ON JULY 21, 1962 WITH A DOPPLER AVERAGING TIME OF 5 SEC. POINTING PREDICTIONS WILL ALSO BE GENERATED FOR 070000Z TO 090000Z ON THE SAME DAY BUT WITH A 30-SEC SAMPLE RATE AND 30-SEC DOPPLER AVERAGING TIME.

* SYMBOLS ALLOWED

JETGLV,JETGL2,CANJET,DDHJET,JOBJET,ANTGUA,ASCENS,PUERTO,PRETRJ,JDDREL,T3CAPE,BAHAMA,SANSAL,HAWAII,TRINID

DATA FILE SIGMA (121)

* IF A DATA FILE IS BEING PREPARED THE DATA TYPES FOLLOWING THIS CARD WILL BE ENTERED ON THE ODP DATA FILE. IF NUMERIC FIELD APPEARS WITH A SYMBOL THE PROGRAM WILL PUT A NORMALLY DISTRIBUTED RANDOM NUMBER WITH MEAN ZERO ON THE CALCULATED VALUE OF THE DATA

TYPE. THE ONE-SIGMA VALUE OF THE DISTRIBUTION IS SET TO THE VALUE FOLLOWING THE SYMBOLIC NAME OF THE DATA TYPE. IF NO NUMERIC FIELD FOLLOWS A SYMBOL THE ONE-SIGMA VALUE OF THE DISTRIBUTION IS SET TO ZERO.

* SYMBOLS ALLOWED

R(1),DR(1),EL(1),AZ(1),DEC(1),HA(1),CL(1),CC3(1)
C3(1),DI(1),RU(1)

DATA FILE BIAS (122)

* SAME AS THE ABOVE EXCEPT THAT THE NUMERIC FIELD INDICATES THE CONSTANT THE ODP WILL ADD TO THE CALCULATED VALUE OF EACH DATA TYPE.

PAGE HEADING (123)

* UP TO 11 BCD WORDS MAY FOLLOW THIS CONTROL CARD. THE COMMENT MUST BE INITIATED WITH A LEFT PARENTHESIS AND CLOSED WITH RIGHT PARENTHESIS. THE COMMENT WILL BE PRINTED ABOVE VARIOUS OUTPUT GROUPS.

MAP COVARIANCE MATRIX TO (124)

* THIS CARD IS FOLLOWED BY UP TO 12 MONOTONICALLY INCREASING GREENWICH TIMES. THE COVARIANCE MATRIX FROM THE PREVIOUS ITERATION WILL BE MAPPED FORWARD TO THESE TIMES.

* SYMBOLS ALLOWED, NONE

TRANSMITTER ID TABLE (126)

* THE DATA FOLLOWING THIS CONTROL CARD DEFINES THE TRANSMITTING STATION AS A FUNCTION OF TIME. THIS DATA IS REQUIRED ONLY WHEN GENERATING DATA FILES OR POINTING PREDICTIONS SINCE THE ODP IDENTIFIES THE TRANSMITTER FOR EACH TIME POINT APPEARING ON THE ODP DATA FILE. THE FORMAT OF THE TRANSMITTER TABLE IS, IX(1),FREQ(1),TIME(1),IX(2),FREQ(2),....IX IS A FIXED NUMBER, FREQ IS A FLOATING POINT NUMBER.

* THE INTERPRETATION OF THE TABLE IS AS FOLLOWS:

* STATION IX(1) IS TRANSMITTING WITH A FREQ(1) UNTIL TIME(1), THEN STATION IX(1)+1 IS TRANSMITTING WITH A FREQ(1)+1 UNTIL TIME(1)+1, ETC. IX(1)=0 IS INTERPRETED AS THE TRANSPONDER AND TIME(1)=0 IS INTERPRETED AS INFINITY. WHEN GENERATING A DATA FILE ONLY ONE TYPE OF DOPPLER WILL BE ALLOWED PER TIME POINT. IF ALL THREE DOPPLER TYPES ARE REQUESTED FOR A RECEIVING STATION (SEE DATA FILE SIGMA CONTROL CARDS), THE FOLLOWING RULES DETERMINE THE DOPPLER TYPE THAT WILL APPEAR.

1. IF ELEVATION AT STATION IX IS NEGATIVE SET IX=0

2. IF IX=0 OMIT CC3 AND C3

3. IF IX#0 OMIT C1 AND CC3 WHERE IR IS THE RECEIVER

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- * 4. IF IX=IR OMIT C1 AND C3
- * SYMBOLS ALLOWED, NONE
- * RESTRICTIONS
- * A MAXIMUM OF 134 IX-TIME PAIRS IS ALLOWED

OFFLINE CONTROL 127

- * WHEN ANY OPTION OTHER THAN A DATA FITTING
- * ITERATION IS DESIRED KEY CONTROL IS NECESSARY
- * THIS CONTROL CARD MUST BE PRESENT EACH ITERATION TO SET
- * THE KEYS FOR THAT ITERATION. THE CARDS FOR EACH
- * ITERATION MUST BE FOLLOWED BY AN END DATA CARD.
- * SYMBOL ALLOWED OPTION NEED CONTROL CARDS
- KEY(2) SIMULATE ODP DATA FILE 1,2,17,21
- KEY(3) STEP-MAP, FORWARDS EPOCH 1,2,24
- KEY(4) MAP FORWARD TO INPUT TIME 1,2,24
- KEY(5) MAP TO ENCOUNTER 1,2
- KEY(6) REJECT BAD POINTS 1,2,6
- KEY(8) REPEAT PREDICTS
- KEY(12) PREDICTS PREPARED FOR TELETYPE 1,2,17,KEY(13)
- TRANSMISSION
- KEY(13) POINTING PREDICTIONS 1,2,17
- KEY(14) STATISTICS 1,2,14
- KEY(15) ANGLE PLOTS 1,2
- KEY(16) RESIDUALS 1,2,14
- KEY(17) TIME PLOTS 1,2,14
- TERMINATE JOB MUST BE INCLUDED TO END JOB
- RESTART ODP TO INITIALIZE ODP FROM BEGINNING

BURN START TIME 130

- * THIS TIME, IN THE USUAL GREENWICH FORMAT, DENOTES THE
- * BEGINNING OF THE POWERED FLIGHT.

SPHERICAL INJECTION CONDITIONS 131

- * IN PLACE OF CARTESIAN INJECTION CONDITIONS, THE USER
- * MAY INPUT SPHERICAL CONDITIONS UNDER THIS CONTROL
- * CARD. THE SPHERICAL CONDITIONS ARE TRANSFORMED TO
- * CARTESIAN CONDITIONS AT INPUT TIME.
- * SYMBOLS ALLOWED
- RAD,LAT, LONG, VE, ELE, AZE

OCCULTATION TIMES 132

- * THIS DATA TYPE IS INPUT BY CARD, RATHER THAN THROUGH
- * THE JOB. TWO OCCULTATION TIMES APPEAR ON EACH CARD.
- * THE FORMAT IS OCCX=T1,T2,WEIGHT,REJECTION SIGMA, WHERE
- * T1 AND T2 ARE GREENWICH TIMES IN THE USUAL FORMAT.
- * RESTRICTIONS
- * ONLY STATIONS 1 THROUGH 5 PERMITTED. IF ONLY ONE
- * TIME IS TO BE USED THEN T2 MUST BE 0,0.
- * SYMBOLS ALLOWED

OCC1,OCC2,OCC3,OCC4,OCC5

IMPACT TIMES 133

- * SAME AS OCCULTATION TIME, EXCEPT THAT ONLY ONE TIME
- * PER STATION IS INPUT. THE FORMAT IS IMPX=T,WEIGHT,
- * REJECTION SIGMA.
- * RESTRICTIONS
- * ONLY STATIONS 1 THROUGH 5 PERMITTED
- * SYMBOLS ALLOWED
- IMP1,IMP2,IMP3,IMP4,IMP5

START AND STOP TIMES 134

- * THIS INPUT PERMITS THE FITTING OF DATA ONLY DURING THE
- * INTERVAL BETWEEN T-START AND T-STOP. UP TO THREE PAIRS
- * MAY BE INPUT IN THE USUAL GMT FORMAT.

END DATA 130

- * THIS CARD MUST TERMINATE EACH SET OF CONTROL DATA
- * READ BY THE ODP.

B. LOAD MAPS AND COMMON STORAGE MAP

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| ENTRY POINTS TO SUBROUTINES REQUESTED FROM LIBRARY. | | | | | | |
|--|------------|------------------|-----------|--------------|----------------|--------------|
| (DFMP) | (DFAD) | (DFSB) | READS | WRITES | | |
| THE NAME OF THIS PROGRAM IS *LA2 2/22/65 | | | | | | |
| ENTRY NAME | ENTRY ADD. | TRANSFER VECTORS | LOAD ADD. | OCTAL LENGTH | DECIMAL LENGTH | COMMON BREAK |
| **PCB | 22302 | EPDX | 22300 | 00011 | 00009 | |
| CDMAP | 22322 | CDMAP | 22311 | 00273 | 00187 | |
| | | OFFSYS | | | | |
| | | TYPRYT | | | | |
| | | TAMP | | | | |
| | | PRDM | | | | |
| | | FLOT | | | | |
| | | REAM | | | | |
| | | COMIMP | | | | |
| | | DCP | | | | |
| | | FLAX | | | | |
| PRAMS | 22606 | DCP | 22604 | 00043 | 00035 | |
| COMIMP | 22660 | FLAX | 22647 | 01357 | 00751 | 47055 |
| | | PRAMS | | | | |
| | | (DFMP) | | | | |
| | | (DFAD) | | | | |
| | | MANUL | | | | |
| | | (DFSB) | | | | |
| ADD | 24226 | *NONE* | 24226 | 00050 | 00040 | |
| ARCSIN | 24306 | *NONE* | 24276 | 00144 | 00100 | 77152 |
| ARCCOS | 24302 | | | | | |
| QARCSIN | 24300 | | | | | |
| QARCCOS | 24276 | | | | | |
| ERRARS | 24427 | | | | | |
| ERRARC | 24433 | | | | | |
| ARTAN | 24442 | *NONE* | 24442 | 00103 | 00067 | 77152 |
| DAYS | 24550 | FIX | 24545 | 00041 | 00033 | |
| | | FLOT | | | | |
| | | ADD | | | | |
| ERRDR | 24606 | *NONE* | 24606 | 00011 | 00009 | |
| FIXT | 24620 | FIXT | 24617 | 00007 | 00007 | |
| FLOT | 24626 | *NONE* | 24626 | 00312 | 00202 | 50031 |
| FIX | 24734 | | | | | |
| FLOT | 25115 | | | | | |
| DAYE | 25121 | | | | | |
| FLAT | 25131 | | | | | |
| FLAPR | 25142 | ERRDR | 25140 | 00102 | 00066 | |
| FLAK | 25170 | TYPRYT | | | | |
| INSPEC | 25246 | *NONE* | 25242 | 00310 | 00200 | 50031 |
| MANUL | 25556 | *NONE* | 25552 | 00130 | 00088 | 77461 |
| PNUT | 25710 | SIN | 25702 | 00336 | 00222 | 50001 |
| | | COS | | | | |
| PRDM | 26244 | *NONE* | 26240 | 00156 | 00110 | 77461 |
| QUIZ | 26416 | *NONE* | 26416 | 00003 | 00003 | |
| REAP | 26424 | READS | 26421 | 02543 | 01379 | |
| REAM | 26424 | FLAT | | | | |
| | | ERRDR | | | | |
| ROT | 31170 | *NONE* | 31164 | 00266 | 00182 | 50031 |
| OFFSYS | 31452 | *NONE* | 31452 | 00010 | 00008 | |
| ENDSYS | 31453 | | | | | |
| FINSYS | 31454 | | | | | |
| SCHAIN | 31455 | | | | | |
| PGSTRAT | 31456 | | | | | |
| PGSTOP | 31457 | | | | | |
| DCP | 31460 | | | | | |
| TYPRYT | 31461 | | | | | |
| SIN | 31462 | *NONE* | 31462 | 00242 | 00162 | |
| COS | 31465 | | | | | |
| QSIN | 31471 | | | | | |
| QCOS | 31473 | | | | | |
| TAMP | 31736 | WRITES | 31724 | 00126 | 00086 | |
| EPDX | 32032 | FLAT | | | | |
| (DFAD) | 32052 | *NONE* | 32052 | 00121 | 00081 | 77776 |
| (DFSB) | 32072 | | | | | |
| (DFMP) | 32112 | | | | | |
| (DFDP) | 32140 | | | | | |
| READD | 32174 | (IOU) | 32173 | 00365 | 00245 | |
| READS | 32176 | | | | | |
| WRITES | 32201 | | | | | |
| WRITES | 32203 | | | | | |
| BSREC | 32412 | | | | | |
| BSFILE | 32415 | | | | | |
| REWIND | 32420 | | | | | |
| UNLOAD | 32423 | | | | | |
| EMOFILE | 32426 | | | | | |
| SETLBN | 32404 | | | | | |
| SETHI | 32407 | | | | | |
| (UNIT) | 32555 | | | | | |
| TAPEIO | 32555 | | | | | |
| (IOU) | 32563 | *NONE* | 32560 | 00030 | 00024 | |
| *LA2 * JUST LOADED. | | | | | | |
| UNUSED CORE LIES FROM 32610 THROUGH 47055, LEAVING 14246 OCTAL OR 05310 DECIMAL LOCATIONS. | | | | | | |

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STASH 37441
 CLOCK 43733
 MINUTE 43730
 XMIN 43730

'LAZA ' JUST LOADED.

UNUSED CORE LIES FROM 44036 THROUGH 47055, LEAVING 03020 OCTAL OR 01552 DECIMAL LOCATIONS.

| ENTRY POINTS TO DEFINE | SUBROUTINES ATTACH | REQUESTED FROM LIBRARY, OPEN | CLOSE | WRITEB | ENDFIL | FGDOUT | SQRT | PROUT | LOC |
|--|--------------------|---|-----------|--------|--------------|--------|----------------|--------------|-----|
| THE NAME OF THIS PROGRAM IS 'LA3 ' 2/22/65 | | | | | | | | | |
| ENTRY NAME | ENTRY ADD. | TRANSFER VECTORS | LOAD ADD. | | OCTAL LENGTH | | DECIMAL LENGTH | COMMON BREAK | |
| *PCB | 22302 | OZ | 22301 | | 00006 | | 00006 | | |
| OZ | 22316 | DEFINE ATTACH OPEN TYPRYT OFFSYS UMAT CLOSE | 22307 | | 01367 | | 00759 | | |
| ARTAN | 23676 | 'NONE' | 23676 | | 00103 | | 00067 | 77152 | |
| FIXT | 24002 | FIXTT | 24001 | | 00007 | | 00007 | | |
| FIXTT | 24010 | 'NONE' | 24010 | | 00312 | | 00202 | 50031 | |
| FLOT | 24116 | | | | | | | | |
| FIX | 24277 | | | | | | | | |
| FLOAT | 24303 | | | | | | | | |
| DAYE | 24313 | | | | | | | | |
| ERROR | 24322 | 'NONE' | 24322 | | 00012 | | 00010 | | |
| FLAT | 24336 | ERROR | 24334 | | 00101 | | 00065 | | |
| FLAPR | 24364 | TYPRYT | | | | | | | |
| FLAK | 24373 | | | | | | | | |
| GERPU | 24440 | WRITEB FLAT | 24435 | | 00100 | | 00064 | | |
| ORBEQ | 24544 | ENDFIL ARTAN COS | 24535 | | 00167 | | 00119 | 77461 | |
| PARAM | 24732 | SIN FGDOUT SORT FIXT PROUT INORM ORBEQ | 24724 | | 01320 | | 00720 | | |
| QUIZ | 26244 | 'NONE' | 26244 | | 00002 | | 00002 | | |
| OFFSYS | 26246 | 'NONE' | 26246 | | 00010 | | 00008 | | |
| ENDSYS | 26247 | | | | | | | | |
| FINSYS | 26250 | | | | | | | | |
| SCHAIN | 26251 | | | | | | | | |
| PGSTRP | 26252 | | | | | | | | |
| PGSTDP | 26253 | | | | | | | | |
| DCP | 26254 | | | | | | | | |
| TYPRYT | 26255 | | | | | | | | |
| SIN | 26256 | 'NONE' | 26256 | | 00243 | | 00163 | | |
| COS | 26261 | | | | | | | | |
| QSIN | 26265 | | | | | | | | |
| QCOS | 26267 | | | | | | | | |
| INORM | 26526 | SORT | 26521 | | 00252 | | 00170 | 77461 | |
| UMAT | 27004 | SORT SORT LOG GERPU ARTAN PARAM | 26773 | | 03221 | | 01681 | 77461 | |
| LOG | 32222 | 'NONE' | 32214 | | 00066 | | 00054 | 77774 | |
| LOG10 | 32214 | | | | | | | | |
| SORT | 32302 | 'NONE' | 32302 | | 00054 | | 00044 | 77773 | |
| PROUT | 32332 | OUTS | 32356 | | 03031 | | 01561 | | |
| FGDOUT | 33636 | ACTIND | | | | | | | |
| PRCON | 32537 | BFLG | | | | | | | |
| PROUT2 | 32510 | RESTKA | | | | | | | |
| PROUT3 | 32523 | REQIND | | | | | | | |
| TSXA | 34545 | WRITE | | | | | | | |
| TSXB | 35335 | PRCON RGGSAV RGGSTR CKACT IDOU) | 35407 | | 00365 | | 00245 | | |
| READD | 35410 | | | | | | | | |
| READ8 | 35412 | | | | | | | | |
| WRITED | 35415 | | | | | | | | |
| WRITEB | 35417 | | | | | | | | |
| BSREC | 35626 | | | | | | | | |
| BSFILE | 35631 | | | | | | | | |
| REWIND | 35634 | | | | | | | | |
| UNLOAD | 35637 | | | | | | | | |
| ENDFIL | 35642 | | | | | | | | |
| SETLOW | 35620 | | | | | | | | |
| SETHI | 35623 | | | | | | | | |
| (UNIT) | 35771 | | | | | | | | |
| TAPEIO | 35771 | | | | | | | | |
| IDOU) | 35777 | 'NONE' | 35774 | | 00030 | | 00024 | | |
| OUTUS | 36026 | RGGSAV | 36024 | | 02320 | | 01232 | | |
| BFLG | 36662 | RGGSTR | | | | | | | |
| ENDOUT | 36413 | | | | | | | | |
| CKIND | 40295 | | | | | | | | |
| CKACT | 40320 | | | | | | | | |
| REQIND | 40254 | | | | | | | | |
| ACTIND | 40253 | | | | | | | | |
| RESTKA | 40251 | | | | | | | | |
| PLICON | 40334 | | | | | | | | |
| PL2CON | 40335 | | | | | | | | |
| PL3CON | 40336 | | | | | | | | |
| PRCON | 40337 | | | | | | | | |
| AGGSAV | 40344 | 'NONE' | 40344 | | 00133 | | 00091 | | |
| RGGSTR | 40426 | | | | | | | | |
| IDCS | 40500 | CLOCK | 40477 | | 04335 | | 02269 | | |
| DEFINE | 40501 | | | | | | | | |
| JOIN | 40504 | | | | | | | | |
| ATTACH | 40507 | | | | | | | | |

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CLOSE      40512
OPEN       40515
READ       40520
WRITE      40523
COPY       40526
REW        40531
WEP        40534
BSR        40537
BSF        40542
STASH      40545
CLOCK      45037      *NONE*      45034      00106      00070
MINUTE     45034
XMIN       45034
    
```

*LA3 * JUST LOADED.

UNUSED CORE LIES FROM 45142 THROUGH 50031, LEAVING 02670 OCTAL OR 01464 DECIMAL LOCATIONS.

| ENTRY POINTS TO SUBROUTINES REQUESTED FROM LIBRARY, | REMINO | (DFAD) | (DFMP) | (DFSB) | SQRT | DMDD | (DFOP) | EXP(3) | READB |
|---|------------|------------------|-----------|--------------|----------------|--------------|--------|--------|-------|
| THE NAME OF THIS PROGRAM IS *LA4 * | | | | | | | | | |
| 2/22/65 | | | | | | | | | |
| ENTRY NAME | ENTRY ADD. | TRANSFER VECTORS | LOAD ADD. | OCTAL LENGTH | DECIMAL LENGTH | COMMON BREAK | | | |
| *PCB | 22302 | PRED | 22301 | 00007 | 00007 | | | | |
| PRED | 22314 | TYPRY | 22310 | 00050 | 00040 | | | | |
| | | POINT | | | | | | | |
| | | DATAPE | | | | | | | |
| | | REMINO | | | | | | | |
| ABOD | 22360 | *NONE* | 22360 | 00030 | 00024 | | | | |
| ADD | 22410 | *NONE* | 22410 | 00050 | 00040 | | | | |
| ARSIN | 22470 | *NONE* | 22460 | 00144 | 00100 | 77152 | | | |
| ARCOS | 22464 | | | | | | | | |
| QARSIN | 22462 | | | | | | | | |
| QARCOS | 22460 | | | | | | | | |
| ERRARC | 22611 | | | | | | | | |
| ERRARC | 22615 | | | | | | | | |
| ARTAN | 22624 | *NONE* | 22624 | 00102 | 00066 | 77152 | | | |
| COEF | 22736 | (DFAD) | 22726 | 00770 | 00504 | 50031 | | | |
| | | (DFMP) | | | | | | | |
| | | (DFSB) | | | | | | | |
| | | QUIZ | | | | | | | |
| CORR | 23724 | SQRT | 23716 | 00274 | 00188 | 47675 | | | |
| | | SIN | | | | | | | |
| DATAPE | 24230 | IXTAB | 24212 | 00447 | 00295 | 50031 | | | |
| | | OFFSYS | | | | | | | |
| | | (DFAD) | | | | | | | |
| | | REAP | | | | | | | |
| | | GHADP | | | | | | | |
| | | COEF | | | | | | | |
| | | DDPLR | | | | | | | |
| | | CORR | | | | | | | |
| | | NDZF | | | | | | | |
| | | FILT | | | | | | | |
| DAYS | 24664 | FIX | 24661 | 00041 | 00033 | | | | |
| | | FLOAT | | | | | | | |
| | | ADD | | | | | | | |
| DNAME | 24735 | *NONE* | 24722 | 00014 | 00012 | | | | |
| SIPREG | 24736 | *NONE* | 24736 | 00003 | 00003 | | | | |
| ODOFF | 24737 | | | | | | | | |
| SPHX | 24740 | | | | | | | | |
| DDPLR | 24756 | RATES | 24741 | 01313 | 00715 | 50031 | | | |
| | | DMDD | | | | | | | |
| | | VEC | | | | | | | |
| | | ABOD | | | | | | | |
| | | (DFMP) | | | | | | | |
| | | (DFAD) | | | | | | | |
| | | SORT | | | | | | | |
| | | ARTAN | | | | | | | |
| | | ARSIN | | | | | | | |
| ERROR | 26254 | *NONE* | 26254 | 00012 | 00010 | | | | |
| FILL | 26270 | RITE | 26266 | 00277 | 00191 | 50001 | | | |
| FILT | 26552 | PISA | | | | | | | |
| FIXT | 26566 | FIXTT | 26565 | 00007 | 00007 | | | | |
| FIXIT | 26574 | *NONE* | 26574 | 00312 | 00202 | 50031 | | | |
| FLOT | 26702 | | | | | | | | |
| FIX | 27063 | | | | | | | | |
| FLOAT | 27067 | | | | | | | | |
| DAYE | 27077 | | | | | | | | |
| FLAT | 27110 | ERRDR | 27106 | 00102 | 00066 | | | | |
| FLAPR | 27136 | TYPRY | | | | | | | |
| FLAK | 27145 | | | | | | | | |
| GHADP | 27222 | (DFOP) | 27210 | 00320 | 00208 | 50031 | | | |
| | | (DFSB) | | | | | | | |
| | | (DFMP) | | | | | | | |
| | | (DFAD) | | | | | | | |
| | | DMDD | | | | | | | |
| | | COS | | | | | | | |
| IXTAB | 27530 | *NONE* | 27530 | 00066 | 00054 | | | | |
| NDZF | 27616 | *NONE* | 27616 | 00050 | 00040 | | | | |
| PNUT | 27674 | SIN | 27666 | 00337 | 00223 | 50001 | | | |
| | | COS | | | | | | | |
| POINT | 30242 | IXTAB | 30225 | 00305 | 00197 | 50031 | | | |
| | | COEF | | | | | | | |
| | | OFFSYS | | | | | | | |
| | | (DFAD) | | | | | | | |
| | | REAP | | | | | | | |
| | | GHADP | | | | | | | |
| | | DDPLR | | | | | | | |
| | | CORR | | | | | | | |
| | | FILL | | | | | | | |
| QUIZ | 30532 | *NONE* | 30532 | 00003 | 00003 | | | | |
| RATES | 30546 | COS | 30535 | 00662 | 00434 | 50031 | | | |
| | | SIN | | | | | | | |
| | | SQRT | | | | | | | |
| | | ARSIN | | | | | | | |
| REAP | 31422 | EXP(3) | 31417 | 02543 | 01379 | | | | |
| REAM | 31422 | READB | | | | | | | |
| | | FLAT | | | | | | | |
| | | ERRDR | | | | | | | |
| RDT | 34166 | *NONE* | 34162 | 00266 | 00182 | 50031 | | | |
| OFFSYS | 34450 | *NONE* | 34450 | 00010 | 00008 | | | | |
| ENDSYS | 34451 | | | | | | | | |
| FINSYS | 34452 | | | | | | | | |
| SENATH | 34453 | | | | | | | | |

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| | | | | | | |
|--------|-------|--------|-------|-------|-------|-------|
| PGSTRT | 34454 | | | | | |
| PGSTOP | 34455 | | | | | |
| DCP | 34456 | | | | | |
| TYPRYT | 34457 | | | | | |
| SIN | 34460 | 'NONE' | 34460 | 00242 | 00162 | |
| COS | 34463 | | | | | |
| QSIN | 34467 | | | | | |
| QCOS | 34471 | | | | | |
| VEC | 34722 | 'NONE' | 34722 | 00017 | 00015 | 50031 |
| REDE | 34742 | DCP | 34741 | 00421 | 00273 | |
| RITE | 34745 | | | | | |
| PISA | 35171 | | | | | |
| EXPI3 | 35362 | 'NONE' | 35362 | 00136 | 00094 | 77773 |
| (OFAD) | 35520 | 'NONE' | 35520 | 00120 | 00080 | 77776 |
| (OFSB) | 35540 | | | | | |
| (DFMP) | 35560 | | | | | |
| (OFDP) | 35506 | | | | | |
| OMD | 35640 | 'NONE' | 35640 | 00060 | 00048 | 77776 |
| SQRT | 35720 | 'NONE' | 35720 | 00055 | 00045 | 77773 |
| READD | 35776 | (IOU) | 35775 | 00365 | 00245 | |
| READB | 36000 | | | | | |
| WRITED | 36003 | | | | | |
| WRITEB | 36005 | | | | | |
| BSREC | 36214 | | | | | |
| BSFILE | 36217 | | | | | |
| REWIND | 36222 | | | | | |
| UNLOAD | 36225 | | | | | |
| ENDFIL | 36230 | | | | | |
| SELDW | 36206 | | | | | |
| SETH | 36211 | | | | | |
| (UNIT) | 36357 | | | | | |
| TAPEIO | 36357 | | | | | |
| (IOU) | 36365 | 'NONE' | 36362 | 00030 | 00024 | |

'LA4 * JUST LOADED.

UNUSED CORE LIES FROM 36412 THROUGH 47675, LEAVING 11264 OCTAL OR 04788 DECIMAL LOCATIONS.

| ENTRY NAME | ENTRY ADD. | TRANSFER VECTORS | LOAD ADD. | OCTAL LENGTH | DECIMAL LENGTH | COMMON BREAK |
|------------|------------|------------------|-----------|--------------|----------------|--------------|
| PCB | 22302 | SORT | 22301 | 00006 | 00006 | |
| SORT | 22316 | TYPRYT | 22307 | 02055 | 01069 | |
| | | DEFINE | | | | |
| | | ATTACH | | | | |
| | | OPEN | | | | |
| | | THARP | | | | |
| | | CLOSE | | | | |
| | | FLAK | | | | |
| BIBCO | 24411 | 'NONE' | 24364 | 00054 | 00044 | |
| DNAME | 24453 | 'NONE' | 24440 | 00014 | 00012 | |
| AQUI | 24512 | PROUT | 24454 | 00741 | 00481 | 50031 |
| ALLI | 24472 | FGDDUT | | | | |
| BALLI | 24467 | PKINE | | | | |
| BAQUI | 24464 | FIXT | | | | |
| | | DAYE | | | | |
| | | TELTYP | | | | |
| | | ENDDUT | | | | |
| PERNOD | 25421 | KINE | 25415 | 00007 | 00007 | |
| WOLF | 25420 | | | | | |
| RESP | 25416 | | | | | |
| ANGPLT | 25417 | | | | | |
| MONRED | 25424 | 'NONE' | 25424 | 00002 | 00002 | |
| ERRDR | 25426 | 'NONE' | 25426 | 00012 | 00010 | |
| FILL | 25442 | RITE | 25440 | 00277 | 00191 | 50001 |
| FILT | 25724 | PISA | | | | |
| FIXT | 25740 | FIXTT | 25737 | 00007 | 00007 | |
| FIXTT | 25746 | 'NONE' | 25746 | 00312 | 00202 | 50031 |
| FLOT | 26054 | | | | | |
| FIX | 26235 | | | | | |
| FLOAT | 26241 | | | | | |
| DAYE | 26251 | | | | | |
| FLAT | 26262 | ERRDR | 26260 | 00102 | 00066 | |
| FLAPR | 26310 | TYPRYT | | | | |
| FLAK | 26317 | | | | | |
| KINE | 26364 | REDE | 26362 | 00216 | 00142 | 50001 |
| | | ERRDR | | | | |
| QUIT | 26400 | 'NONE' | 26400 | 00002 | 00002 | |
| OFFSYS | 26402 | 'NONE' | 26602 | 00010 | 00008 | |
| ENDSYS | 26603 | | | | | |
| FINSYS | 26604 | | | | | |
| SCHATT | 26605 | | | | | |
| PGSTRT | 26606 | | | | | |
| PGSTOP | 26607 | | | | | |
| UCP | 26610 | | | | | |
| TYPRYT | 26611 | | | | | |
| THARP | 26626 | OFFSYS | 26612 | 00573 | 00379 | |
| PKINE | 26733 | KINE | | | | |
| | | AQUI | | | | |
| | | ALLI | | | | |
| | | BAQUI | | | | |
| | | BALLI | | | | |
| | | PERNOD | | | | |
| | | RESP | | | | |
| | | WOLF | | | | |

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| ROUTINE NAME | ADDRESS | ROUTINE NAME | ADDRESS | DECIMAL | DECIMAL |
|--------------|---------|--------------|---------|---------|---------|
| REDE | 27406 | ANGPLT | 27405 | 00422 | 00274 |
| RITE | 27411 | BIBCD | | | |
| PISA | 27635 | TYPRYT | | | |
| TELTYP | 30036 | DCP | | | |
| SCCTTY | 30253 | PROUT2 | 30027 | 01101 | 00577 |
| | | ACTIND | | | |
| | | PROUT3 | | | |
| | | TSXA | | | |
| | | RGCSAV | | | |
| | | RGGSTR | | | |
| | | TSXB | | | |
| PROUT | 31144 | OUTUS | 31130 | 03032 | 01562 |
| FGDOUT | 32410 | ACTIND | | | |
| PRGNV | 31311 | BFLC | | | |
| PROUT2 | 31262 | RESTKA | | | |
| PROUT3 | 31275 | REQIND | | | |
| TSXA | 33317 | WRITE | | | |
| TSXB | 34107 | PRCON | | | |
| | | RGCSAV | | | |
| | | RGGSTR | | | |
| | | CKIND | | | |
| | | CACT | | | |
| | | RGCSAV | 34162 | 02320 | 01232 |
| | | RGGSTR | | | |
| OUTUS | 34164 | | | | |
| BFLC | 35020 | | | | |
| ENDOUT | 34551 | | | | |
| CKIND | 36413 | | | | |
| CACT | 36456 | | | | |
| REQIND | 36412 | | | | |
| ACTIND | 36411 | | | | |
| RESTKA | 36407 | | | | |
| PLICDN | 36472 | | | | |
| PL2CDN | 36473 | | | | |
| PL3CDN | 36474 | | | | |
| PRCON | 36475 | *NONE* | 36502 | 00133 | 00091 |
| RGCSAV | 36502 | | | | |
| RGGSTR | 36564 | | | | |
| ICCS | 36636 | CLOCK | 36635 | 04335 | 02269 |
| DEFINE | 36637 | | | | |
| JOIN | 36642 | | | | |
| ATTACH | 36645 | | | | |
| CLOSE | 36650 | | | | |
| OPEN | 36653 | | | | |
| READ | 36656 | | | | |
| WRITE | 36661 | | | | |
| COPY | 36664 | | | | |
| REW | 36667 | | | | |
| HEF | 36672 | | | | |
| BSR | 36675 | | | | |
| BSF | 36700 | | | | |
| STASH | 36703 | | | | |
| CLOCK | 43175 | *NONE* | 43172 | 00106 | 00070 |
| MINUTE | 43172 | | | | |
| AMIN | 43172 | | | | |

*LA5 * JUST LOADED.

UNUSED CORE LIES FROM 43300 THROUGH 50001, LEAVING 04502 OCTAL OR 02370 DECIMAL LOCATIONS.

| ENTRY POINTS TO SUBROUTINES REQUESTED FROM LIBRARY, SETHI WRITEN | REWIND READD | ENDFIL | (DFSB) | (DFAD) | (DFNP) | SQRT | EXPI3 | DNDD | (DFDP) |
|---|--------------|------------------|-----------|--------------|----------------|--------------|-------|------|--------|
| THE NAME OF THIS PROGRAM IS *LA6 * 2/22/65 | | | | | | | | | |
| ENTRY NAME | ENTRY ADD. | TRANSFER VECTORS | LOAD ADD. | OCTAL LENGTH | DECIMAL LENGTH | COMMON BREAK | | | |
| **PCB | 22302 | FIT | 22301 | 00006 | 00006 | | | | |
| FIT | 22320 | REDE | 22307 | 00735 | 00477 | | | | |
| | | TYPRYT | | | | | | | |
| | | SETHI | | | | | | | |
| | | REWIND | | | | | | | |
| | | CALL | | | | | | | |
| | | ENDFIL | | | | | | | |
| | | RITE | | | | | | | |
| | | OCIM | | | | | | | |
| | | FLAK | | | | | | | |
| ABDD | 23244 | *NONE* | 23244 | 00030 | 00024 | | | | |
| ADD | 23274 | *NONE* | 23274 | 00050 | 00040 | | | | |
| ARSHN | 23354 | *NONE* | 23344 | 00144 | 00100 | 77152 | | | |
| ARCOS | 23350 | | | | | | | | |
| QARSHN | 23346 | | | | | | | | |
| QARCOS | 23344 | | | | | | | | |
| ERRARS | 23475 | | | | | | | | |
| ERRARC | 23501 | | | | | | | | |
| ARTAN | 23510 | *NONE* | 23510 | 00103 | 00067 | 77152 | | | |
| BEER | 23614 | REJEC | 23613 | 00071 | 00057 | 47675 | | | |
| CALL | 23736 | BEER | 23704 | 00523 | 00339 | 51235 | | | |
| | | KINE | | | | | | | |
| | | COEF | | | | | | | |
| | | STARP | | | | | | | |
| | | (DFSB) | | | | | | | |
| | | REAP | | | | | | | |
| | | GHADP | | | | | | | |
| | | DDPLK | | | | | | | |
| | | COROP | | | | | | | |
| | | CORR | | | | | | | |
| | | DICDS | | | | | | | |
| | | DBTOX | | | | | | | |
| | | CATS | | | | | | | |
| | | OFFSYS | | | | | | | |
| | | WAIT | | | | | | | |
| | | QUIZ | | | | | | | |
| | | REJEC | | | | | | | |
| | | PM360 | | | | | | | |
| | | FORM | | | | | | | |
| | | CERTA | | | | | | | |
| | | FILL | | | | | | | |
| | | GREDF | | | | | | | |
| CATS | 24436 | VEC | 24427 | 00645 | 00421 | 47675 | | | |
| | | ABDD | | | | | | | |
| | | CDS | | | | | | | |
| COEF | 25304 | (DFAD) | 25274 | 00770 | 00504 | 50031 | | | |
| | | (DFNP) | | | | | | | |
| | | (DFSB) | | | | | | | |
| | | QUIZ | | | | | | | |
| CDL | 26272 | CDS | 26264 | 00406 | 00262 | 50031 | | | |
| | | SQRT | | | | | | | |
| COROP | 26702 | SORT | 26672 | 00170 | 00120 | 50031 | | | |
| | | EXPI3 | | | | | | | |
| | | ARTAN | | | | | | | |

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| | | | | | | |
|--------|-------|--------|-------|-------|-------|-------|
| CORR | 27070 | SIN | 27062 | 00275 | 00189 | 47675 |
| DAYS | 27362 | SORT | 27357 | 00041 | 00033 | |
| DECDD | 27420 | SIN | 27420 | 00040 | 00032 | 50031 |
| DICOS | 27466 | SIN | 27460 | 00173 | 00123 | 50031 |
| DOPLR | 27670 | COS | 27653 | 01313 | 00715 | 50031 |
| | | RATES | | | | |
| | | DMOD | | | | |
| | | VEC | | | | |
| | | ARDD | | | | |
| | | (DFMP) | | | | |
| | | (DFAD) | | | | |
| | | SQRT | | | | |
| | | ARTAN | | | | |
| | | ARSIN | | | | |
| ERROR | 31166 | *NONE* | 31166 | 00012 | 00010 | |
| FILL | 31202 | RITE | 31200 | 00277 | 00191 | 50001 |
| FILT | 31464 | PISA | | | | |
| FIXT | 31500 | FIXTT | 31477 | 00007 | 00007 | |
| FIXTT | 31506 | *NONE* | 31506 | 00312 | 00202 | 50031 |
| FLOT | 31614 | | | | | |
| FIX | 31775 | | | | | |
| FLOAT | 32001 | | | | | |
| DAYE | 32011 | | | | | |
| FLAT | 32022 | ERROR | 32020 | 00101 | 00065 | |
| FLAPR | 32050 | TYPRYT | | | | |
| FLAK | 32057 | | | | | |
| FORM | 32132 | PARLEY | 32121 | 01066 | 00566 | 50031 |
| | | (DFMP) | | | | |
| | | (DFAD) | | | | |
| | | (DFOP) | | | | |
| | | SORT | | | | |
| | | WRITB | 33207 | 00215 | 00141 | |
| GERTA | 33212 | FLAT | | | | |
| GRODF | 33332 | ENDFIL | | | | |
| | | (DFDP) | 33424 | 00321 | 00209 | 50031 |
| | | (DFSB) | | | | |
| | | (DFMP) | | | | |
| | | (DFAD) | | | | |
| | | DMOD | | | | |
| | | COS | | | | |
| | | FORM | 33745 | 00177 | 00127 | 50031 |
| IMPAR | 33752 | *NONE* | 34144 | 00310 | 00200 | 50031 |
| INSPC | 34150 | REDE | 34454 | 00216 | 00142 | 50001 |
| KINE | 34456 | ERRDR | | | | |
| | | *NONE* | 34672 | 00275 | 00189 | 50031 |
| DBTOX | 34676 | IMPAR | 35167 | 00222 | 00146 | |
| OCIM | 35174 | DCPAR | | | | |
| | | READB | | | | |
| | | FLAT | | | | |
| | | ERROR | 35411 | 00515 | 00333 | 50031 |
| DCPAR | 35416 | FORM | 36126 | 00044 | 00036 | |
| PARLEY | 36130 | WRITB | | | | |
| | | FLAT | | | | |
| | | *NONE* | 36172 | 00050 | 00040 | 50001 |
| PH360 | 36176 | SIN | 36242 | 00336 | 00222 | 50001 |
| PHUI | 36250 | COS | | | | |
| | | *NONE* | 36600 | 00003 | 00003 | |
| QUIZ | 36600 | COS | 36603 | 00662 | 00434 | 50031 |
| RATES | 36614 | SIN | | | | |
| | | SORT | | | | |
| | | ARSIN | | | | |
| | | EXPL3 | | | | |
| REAP | 37470 | READB | 37465 | 02543 | 01379 | |
| REAN | 37470 | FLAT | | | | |
| | | ERROR | | | | |
| | | *NONE* | 42230 | 00056 | 00046 | 46711 |
| REJEC | 42230 | | | | | |
| RECO | 42302 | | | | | |
| ROT | 42312 | *NONE* | 42306 | 00266 | 00182 | 50031 |
| OFFSYS | 42574 | *NONE* | 42574 | 00010 | 00008 | |
| ENDSYS | 42575 | | | | | |
| FINSYS | 42576 | | | | | |
| SCHATN | 42577 | | | | | |
| PGSTRT | 42600 | | | | | |
| PGSTOP | 42601 | | | | | |
| DCP | 42602 | | | | | |
| TYPRYT | 42603 | | | | | |
| SIN | 42604 | *NONE* | 42604 | 00242 | 00162 | |
| COS | 42607 | | | | | |
| QSIN | 42813 | | | | | |
| OCOS | 42615 | | | | | |
| STARP | 43046 | *NONE* | 43046 | 00030 | 00024 | |
| VEC | 43076 | *NONE* | 43076 | 00020 | 00016 | 50031 |
| WAIT | 43130 | CUL | 43116 | 00346 | 00230 | 50031 |
| | | DECDD | | | | |
| | | SORT | | | | |
| | | WDCT | | | | |
| | | COS | | | | |
| | | ERROR | 43464 | 00013 | 00011 | |
| WDCT | 43464 | *NONE* | 43477 | 00421 | 00273 | |
| REDE | 43500 | DCP | | | | |
| RITE | 43503 | | | | | |
| PISA | 43727 | | | | | |
| EXPI3 | 44120 | *NONE* | 44120 | 00136 | 00094 | 77773 |
| (DFAD) | 44256 | *NONE* | 44256 | 00120 | 00080 | 77776 |
| (DFSB) | 44276 | | | | | |
| (DFMP) | 44316 | | | | | |
| (DFDP) | 44344 | | | | | |
| DMOD | 44376 | *NONE* | 44376 | 00050 | 00048 | 77776 |
| SQRT | 44456 | *NONE* | 44456 | 00055 | 00045 | 77773 |
| READO | 44534 | (IDU) | 44533 | 00365 | 00245 | |
| READB | 44536 | | | | | |
| WRITB | 44541 | | | | | |
| WRITB | 44543 | | | | | |
| BSREC | 44752 | | | | | |
| BSFILE | 44755 | | | | | |
| REWIND | 44760 | | | | | |
| UNLOAD | 44763 | | | | | |
| ENDFIL | 44766 | | | | | |
| SETLOW | 44744 | | | | | |
| SETHI | 44747 | | | | | |
| (UNIT) | 45115 | | | | | |
| TAPEIO | 45115 | | | | | |
| (IDU) | 45123 | *NONE* | 45120 | 00030 | 00024 | |

*LA6 * JUST LOADED.

UNUSED CORE LIES FROM 45150 THROUGH 46711. LEAVING 01542 OCTAL OR 00866 DECIMAL LOCATIONS.

JPL TECHNICAL MEMORANDUM NO. 33-204

| ENTRY POINTS TO SUBROUTINES REQUESTED FROM LIBRARY | | | | | | | | | |
|--|---------------|---|-----------|----------------|----------------|--------------|--------|--------|---------|
| ENTRY POINTS TO DEFINE CLOCK | ATTACH (DFDP) | OPEN | CLOSE | FGDDUT | PROUT | SURT | IDFSB) | IDFMP) | (IDFAD) |
| THE NAME OF THIS PROGRAM IS 'LAT' 2/22/65 | | | | | | | | | |
| ENTRY NAME | ENTRY ADD. | TRANSFER VECTORS | LOAD ADD. | DECIMAL LENGTH | DECIMAL LENGTH | COMMON BREAK | | | |
| ++PCB | 22302 | | 22300 | 00012 | 00010 | | | | |
| PRINT | 22330 | PRINT DEFINE ATTACH OPEN ENDIT RITE OFFSYS PRINQ PRIN CLOSE REDE FGDDUT FIXT PROUT FLAK | 22312 | 02514 | 01356 | | | | |
| BIRCD | 25053 | *NONE* | 25026 | 00055 | 00045 | | | | |
| DIAG | 25110 | SQRT | 25103 | 00106 | 00070 | 50031 | | | |
| DIAGO | 25216 | SQRT | 25211 | 00105 | 00069 | 50031 | | | |
| DNAME | 25331 | *NONE* | 25316 | 00014 | 00012 | | | | |
| ENDIT | 25346 | (DFSB) (DFMP) (DFAD) | 25332 | 01474 | 00828 | 50031 | | | |
| | | PRIN SQRT STPREG REVRT NDUT | | | | | | | |
| ERRUR | 27026 | *NONE* | 27026 | 00011 | 00009 | | | | |
| FIXT | 27040 | FIXT | 27037 | 00007 | 00007 | | | | |
| FIXIT | 27046 | *NONE* | 27046 | 00912 | 00202 | 50031 | | | |
| FLOT | 27154 | | | | | | | | |
| FIX | 27335 | | | | | | | | |
| FLOAT | 27341 | | | | | | | | |
| DAYE | 27351 | | | | | | | | |
| FLAT | 27352 | | | | | | | | |
| FLAPR | 27410 | EARDR TYPRYT | 27360 | 00101 | 00065 | | | | |
| FLAK | 27417 | | | | | | | | |
| NORMAY | 27456 | SQRT | 27461 | 00251 | 00169 | 77461 | | | |
| NDUT | 27734 | PROUT | 27732 | 00100 | 00064 | | | | |
| BLEW | 27776 | TYPRYT | | | | | | | |
| BUKEY | 30032 | *NONE* | 30032 | 00040 | 00032 | | | | |
| OPKEY | 30036 | | | | | | | | |
| COKEY | 30053 | | | | | | | | |
| AFKEY | 30060 | | | | | | | | |
| PRIM | 30113 | FGDDUT | 30072 | 01424 | 00760 | 50001 | | | |
| PRAN | 30102 | PROUT BIRCD FLAPR PRIME NORMAY PRIF DIAGO | | | | | | | |
| | | *NONE* | | | | | | | |
| TAMP | 31517 | | | | | | | | |
| PRIME | 31520 | | | | | | | | |
| TAPR | 31521 | | | | | | | | |
| DIAGO | ***** | | | | | | | | |
| PRINQ | 31532 | FGDDUT | 31523 | 00435 | 00285 | 50031 | | | |
| PRIT | 31763 | DIAG CLOCK PROUT FLAPR FIXT BIRCD | | | | | | | |
| APRIOR | 32154 | *NONE* | | | | | | | |
| | | COKEY BLEW | | | | | | | |
| QUIZ | 32160 | *NONE* | 32160 | 00002 | 00032 | | | | |
| REVRT | 32170 | COKEY BLEW | 32162 | 00206 | 00134 | 50031 | | | |
| | | *NONE* | | | | | | | |
| OFFSYS | 32370 | | | | | | | | |
| ENDSYS | 32371 | | | | | | | | |
| FINSYS | 32372 | | | | | | | | |
| SCHAIN | 32373 | | | | | | | | |
| PGSTRT | 32374 | | | | | | | | |
| PGSTOP | 32375 | | | | | | | | |
| DCP | 32376 | | | | | | | | |
| TYPRYT | 32377 | | | | | | | | |
| STPREG | 32410 | (DFAD) (DFDP) DSQRT (DFMP) | 32400 | 02055 | 01069 | 71757 | | | |
| | | ERROR | | | | | | | |
| DSQRT | 34456 | | | | | | | | |
| REDE | 34564 | OCF | 34563 | 00421 | 00273 | 77776 | | | |
| RITE | 34567 | | | | | | | | |
| PISA | 35013 | | | | | | | | |
| (DFAD) | 35204 | *NONE* | 35204 | 00120 | 00080 | 77776 | | | |
| (DFSB) | 35224 | | | | | | | | |
| (DFMP) | 35244 | | | | | | | | |
| (DFDP) | 35272 | | | | | | | | |
| SQRT | 35324 | *NONE* | 35324 | 00054 | 00044 | 77773 | | | |
| CLOCK | 35403 | *NONE* | 35400 | 00106 | 00070 | | | | |
| MINUTE | 35400 | | | | | | | | |
| XMIN | 35400 | | | | | | | | |
| PROUT | 35522 | | | | | | | | |
| FGDDUT | 36766 | DUTUS | 35506 | 03032 | 01562 | | | | |
| PRCNV | 36667 | ACTIND | | | | | | | |
| PROUT2 | 36640 | BFLG | | | | | | | |
| PROUT3 | 36653 | RESTKA | | | | | | | |
| TSXA | 37675 | REQIND | | | | | | | |
| TSXB | 40465 | WRITE PRCON RGGSAV RGGSTR | | | | | | | |
| | | CKIND CKACT | | | | | | | |
| DUTUS | 40542 | RGGSAV RGGSTR | 40540 | 02320 | 01232 | | | | |
| BFLG | 41376 | | | | | | | | |
| ENDOUT | 41127 | | | | | | | | |
| CKIND | 42771 | | | | | | | | |
| CKACT | 43034 | | | | | | | | |
| REQIND | 42770 | | | | | | | | |
| ACTIND | 42767 | | | | | | | | |
| RESTKA | 42765 | | | | | | | | |
| PLICON | 43050 | | | | | | | | |
| PLCON | 43051 | | | | | | | | |
| PLCON | 43052 | | | | | | | | |
| PRCON | 43053 | | | | | | | | |
| RGGSAV | 43060 | *NONE* | 43060 | 00133 | 00091 | | | | |
| RGGSTR | 43142 | | | | | | | | |
| IOCS | 43214 | | | | | | | | |
| DEFINE | 43215 | CLOCK | 43213 | 04335 | 02269 | | | | |
| JOIN | 43220 | | | | | | | | |
| ATTACH | 43223 | | | | | | | | |

JPL TECHNICAL MEMORANDUM NO. 33-204

```

RESTKA      42021
PL1CON      42104
PL2CON      42105
PL3CON      42106
PRCON       42107
RGGSAV      42114      *NONE*      42114      00133      00091
RGGSTR      42176
IGCS        42250      CLOCK      42247      04335      02269
DEFINE      42251
JDIN        42254
ATTACH      42257
CLOSE       42262
OPEN        42265
READ        42270
WRITE       42273
COPY        42276
REW         42301
WEP         42304
BSR         42307
BSF         42312
STASH       42315
    
```

*LAB * JUST LOADED.

UNUSED CORE LIES FROM 46604 THROUGH 50001, LEAVING 01176 OCTAL OR 00638 DECIMAL LOCATIONS.

| ENTRY POINTS TO SUBROUTINES REQUESTED FROM LIBRARY, | | | | | | | | | |
|---|------------|----------|---------|-----------|--------------|----------------|------|--------|--------|
| REWINDE | ENDFIL | SQRT | {DFDP} | {DFS8} | {DFMP} | {DFAD} | DMDD | DEFINE | ATTACH |
| OPEN | CLOSE | EXP(3) | RGGSAV | RGGSTR | CLOCK | READ | | | |
| THE NAME OF THIS PROGRAM IS *LA9 * 2/22/65 | | | | | | | | | |
| ENTRY NAME | ENTRY ADD. | TRANSFER | VECTORS | LOAD ADD. | OCTAL LENGTH | DECIMAL LENGTH | | COMMON | BREAK |
| KODPH1 | 22460 | TYPRYT | | 22300 | 01322 | 00722 | | | |
| ODOFF | 22414 | ODATA | | | | | | | |
| READS | 22306 | REKIND | | | | | | | |
| | | OFFSYS | | | | | | | |
| | | ENDFIL | | | | | | | |
| | | ERRDR | | | | | | | |
| TELTYP | 23624 | *NONE* | | 23622 | 00005 | 00003 | | | |
| TELTP | 23623 | | | | | | | | |
| IUNIT) | 23622 | | | | | | | | |
| FIXT | 23526 | FIXIT | | 23625 | 00010 | 00008 | | | |
| DIAG | 23642 | SQRT | | 23635 | 00105 | 00089 | | | 50031 |
| ERRDR | 23744 | TYPRYT | | 23742 | 00442 | 00290 | | | |
| | | ONLIN | | | | | | | |
| | | *NONE* | | 24404 | 00312 | 00202 | | | 50031 |
| FIXTT | 24404 | | | | | | | | |
| FLOT | 24512 | | | | | | | | |
| FIX | 24673 | | | | | | | | |
| FLOAT | 24677 | | | | | | | | |
| DAYE | 24707 | | | | | | | | |
| GHADP | 24730 | | | 24716 | 00320 | 00208 | | | 50031 |
| | | {DFDP} | | | | | | | |
| | | {DFS8} | | | | | | | |
| | | {DFMP} | | | | | | | |
| | | {DFAD} | | | | | | | |
| | | DMDD | | | | | | | |
| | | COS | | | | | | | |
| QUIZ | 25236 | *NONE* | | 25236 | 00002 | 00002 | | | |
| OFFSYS | 25240 | *NONE* | | 25240 | 00010 | 00008 | | | |
| ENDSYS | 25241 | | | | | | | | |
| FINSYS | 25242 | | | | | | | | |
| SCHATN | 25243 | | | | | | | | |
| PGSTR | 25244 | | | | | | | | |
| PGSTOP | 25245 | | | | | | | | |
| DCP | 25246 | | | | | | | | |
| TYPRYT | 25247 | | | | | | | | |
| SIN | 25250 | *NONE* | | 25250 | 00243 | 00163 | | | |
| COS | 25253 | | | | | | | | |
| QSIN | 25257 | | | | | | | | |
| QCOS | 25261 | | | | | | | | |
| SPHK | 25522 | | | 25513 | 00323 | 00211 | | | 50031 |
| | | COS | | | | | | | |
| | | SIN | | | | | | | |
| | | GHADP | | | | | | | |
| STPREG | 26046 | {DFAD} | | 26036 | 02055 | 01069 | | | 71757 |
| | | {DFDP} | | | | | | | |
| | | DSORT | | | | | | | |
| | | {DFMP} | | | | | | | |
| DSQRT | 30114 | ERRDR | | 30113 | 00106 | 00070 | | | 77776 |
| REDE | 30222 | DCP | | 30221 | 00422 | 00274 | | | |
| RTE | 30225 | | | | | | | | |
| PISA | 30451 | | | | | | | | |
| ODATA | 30566 | TYPRYT | | 30643 | 03305 | 01733 | | | 50001 |
| ONLIN | 30770 | DEFINE | | | | | | | |
| ***** | 31136 | ATTACH | | | | | | | |
| | | OPEN | | | | | | | |
| | | CARDS | | | | | | | |
| | | OFFSYS | | | | | | | |
| | | ERRDR | | | | | | | |
| | | FINSYS | | | | | | | |
| | | CLOSE | | | | | | | |
| | | ODOFF | | | | | | | |
| | | READS | | | | | | | |
| | | KODPH1 | | | | | | | |
| | | FLOT | | | | | | | |
| | | SPHK | | | | | | | |
| | | STPREG | | | | | | | |
| | | DIAG | | | | | | | |
| | | REDE | | | | | | | |
| | | DCP | | | | | | | |
| CARDS | 34154 | EXP13 | | 34150 | 02266 | 01206 | | | |
| CROCON | 34430 | RGGSAV | | | | | | | |
| CROCNV | 34450 | RGGSTR | | | | | | | |
| | | CLOCK | | | | | | | |
| | | READ | | | | | | | |
| EXP13 | 36436 | *NONE* | | 36436 | 00136 | 00094 | | | 77773 |
| {DFAD} | 36574 | *NONE* | | 36574 | 00120 | 00080 | | | 77776 |
| {DFS8} | 36614 | | | | | | | | |
| {DFMP} | 36634 | | | | | | | | |
| {DFDP} | 36662 | | | | | | | | |
| DMDD | 36714 | *NONE* | | 36714 | 00060 | 00048 | | | 77776 |
| SQRT | 36774 | *NONE* | | 36774 | 00054 | 00044 | | | 77773 |
| CLOCK | 37053 | *NONE* | | 37050 | 00107 | 00071 | | | |
| MINUTE | 37050 | | | | | | | | |
| MIN | 37050 | | | | | | | | |
| READD | 37160 | {IDU} | | 37157 | 00365 | 00245 | | | |
| READB | 37162 | | | | | | | | |
| WRITEO | 37165 | | | | | | | | |

JPL TECHNICAL MEMORANDUM NO. 33-204

| | | | | | |
|---------|--------|--------|-------|-------|-------|
| WRITB | 37167 | | | | |
| BSREC | 37376 | | | | |
| BSFILE | 37401 | | | | |
| REWIND | 37404 | | | | |
| UNLOAD | 37407 | | | | |
| ENDFIL | 37412 | | | | |
| SETLOW | 37370 | | | | |
| SETHI | 37373 | | | | |
| (UNIT) | **4444 | | | | |
| TAPEIO | 37541 | | | | |
| (IOU) | 37547 | *NONE* | 37544 | 00030 | 00024 |
| RGGSAY | 37574 | *NONE* | 37574 | 00133 | 00091 |
| RGGSSTR | 37656 | | | | |
| IDCS | 37730 | CLOCK | 37727 | 04335 | 02269 |
| DEFINE | 37731 | | | | |
| JOIN | 37734 | | | | |
| ATTACH | 37737 | | | | |
| CLOSE | 37742 | | | | |
| OPEN | 37745 | | | | |
| READ | 37750 | | | | |
| WRITE | 37753 | | | | |
| COPY | 37756 | | | | |
| REW | 37761 | | | | |
| WEF | 37764 | | | | |
| BSR | 37767 | | | | |
| BSF | 37772 | | | | |
| STASH | 37775 | | | | |

'LA9 * JUST LOADED.

UNUSED CORE LIES FROM 44264 THROUGH 50001, LEAVING 03516 OCTAL OR 01870 DECIMAL LOCATIONS.

ENTRY POINTS TO SUBROUTINES REQUESTED FROM LIBRARY.

| FGDDUT | DEFINE | ATTACH | OPEN | CLOSE | COMENT | READB | PROUT | |
|---|------------|------------------|-----------|--------------|----------------|--------------|-------|--|
| THE NAME OF THIS PROGRAM IS 'LA10 ' 2/22/65 | | | | | | | | |
| ENTRY NAME | ENTRY ADD. | TRANSFER VECTORS | LOAD ADD. | OCTAL LENGTH | DECIMAL LENGTH | COMMON BREAK | | |
| **PCB | 22302 | PARSH | 22301 | 00006 | 00006 | | | |
| PARSH | 22316 | FGDDUT | 22307 | 01226 | 00662 | | | |
| | | DEFINE | | | | | | |
| | | ATTACH | | | | | | |
| | | OPEN | | | | | | |
| | | CONDUT | | | | | | |
| | | WASH | | | | | | |
| | | CLOSE | | | | | | |
| COMOUT | 23536 | COMMENT | 23535 | 00016 | 00014 | | | |
| FIXT | 23554 | FIXTT | 23553 | 00007 | 00007 | | | |
| FIXTT | 23562 | *NONE* | 23562 | 00312 | 00202 | 50031 | | |
| FLOT | 23670 | | | | | | | |
| FIX | 24051 | | | | | | | |
| FLOAT | 24055 | | | | | | | |
| DAYE | 24065 | | | | | | | |
| FLAT | 24076 | ERROR | 24074 | 00102 | 00066 | | | |
| FLAPR | 24124 | TYPRYT | | | | | | |
| FLAK | 24133 | | | | | | | |
| ERROR | 24176 | *NONE* | 24176 | 00011 | 00009 | | | |
| WASH | 24214 | READB | 24207 | 00623 | 00403 | | | |
| | | FLAT | | | | | | |
| | | FIXT | | | | | | |
| | | PROUT | | | | | | |
| | | FLAPR | | | | | | |
| OFFSYS | 25032 | *NONE* | 25032 | 00010 | 00008 | | | |
| ENDSYS | 25033 | | | | | | | |
| FINSYS | 25034 | | | | | | | |
| SCHAIN | 25035 | | | | | | | |
| PGSTRF | 25036 | | | | | | | |
| PGSTOP | 25037 | | | | | | | |
| DCP | 25040 | | | | | | | |
| TYPRYT | 25041 | | | | | | | |
| PROUT | 25056 | OUTUS | 25042 | 03031 | 01561 | | | |
| FGDDUT | 26322 | ACTIND | | | | | | |
| PRCNY | 25423 | BFLC | | | | | | |
| PROUT2 | 25174 | RESTKA | | | | | | |
| PROUT3 | 25207 | REQIND | | | | | | |
| TSXA | 27231 | WRITE | | | | | | |
| TSXB | 30021 | PRCON | | | | | | |
| | | RGGSAY | | | | | | |
| | | RGGSSTR | | | | | | |
| | | CKIND | | | | | | |
| | | EXACT | | | | | | |
| | | (IOU) | 30073 | 00365 | 00245 | | | |
| READD | 30074 | | | | | | | |
| READB | 30076 | | | | | | | |
| WRITB | 30101 | | | | | | | |
| WRITB | 30103 | | | | | | | |
| BSREC | 30312 | | | | | | | |
| BSFILE | 30315 | | | | | | | |
| REWIND | 30320 | | | | | | | |
| UNLOAD | 30323 | | | | | | | |
| ENDFIL | 30326 | | | | | | | |
| SETLOW | 30304 | | | | | | | |
| SETHI | 30307 | | | | | | | |
| (UNIT) | 30355 | | | | | | | |
| TAPEIO | 30455 | | | | | | | |
| (IOU) | 30463 | *NONE* | 30460 | 00030 | 00024 | | | |
| OUTUS | 30512 | RGGSAY | 30510 | 02320 | 01232 | | | |
| BFLC | 31346 | RGGSSTR | | | | | | |
| ENDOUT | 31977 | | | | | | | |
| CKIND | 32741 | | | | | | | |
| CKACT | 33004 | | | | | | | |
| REQIND | 32740 | | | | | | | |
| ACTIND | 32737 | | | | | | | |
| RESTKA | 32735 | | | | | | | |
| PLICON | 33020 | | | | | | | |
| PL2CON | 33021 | | | | | | | |
| PL3CON | 33022 | | | | | | | |
| PRCON | 33023 | | | | | | | |
| RGGSAY | 33030 | *NONE* | 33030 | 00133 | 00091 | | | |
| RGGSSTR | 33112 | | | | | | | |
| IDCS | 33164 | CLOCK | 33163 | 04336 | 02270 | | | |
| DEFINE | 33165 | | | | | | | |
| JOIN | 33170 | | | | | | | |
| ATTACH | 33173 | | | | | | | |
| CLOSE | 33176 | | | | | | | |
| OPEN | 33201 | | | | | | | |
| READ | 33204 | | | | | | | |
| WRITE | 33207 | | | | | | | |

JPL TECHNICAL MEMORANDUM NO. 33-204

COPY 33212
 REM 33215
 WEF 33220
 BSR 33223
 BSF 33226
 STASH 33231
 COMMENT 37522
 CLOCK 37521 03177 01663
 NONE 42720 00106 00070
 MINUTE 42720
 XMIN 42720

*LA10 * JUST LOADED.

UNUSED CORE LIES FROM 43026 THROUGH 50031, LEAVING 05004 OCTAL OR 02564 DECIMAL LOCATIONS.

| ENTRY POINTS TO SUBROUTINES REQUESTED FROM LIBRARY, REWINO SORT (DFSB) READS BSREC (DFAD) (DFMP) (DFDP) DRDD WRITEB | ENDFIL | THE NAME OF THIS PROGRAM IS 'LA11 ' | 2/22/65 | | | | |
|--|------------|---|-----------|--------------|----------------|--------------|--|
| ENTRY NAME **PCB | ENTRY ADD. | TRANSFER VECTORS | LOAD ADD. | OCTAL LENGTH | DECIMAL LENGTH | COMMON BREAK | |
| | 22304 | EPOX TRAPE TAPEX LOGO REDE REWINO KOOL DNTR2 DNTR1 TYPRYT EPPHEM FLAK SORT SORT GIG2 RCAL RCOM RSIG ACE | 22300 | 00022 | 00018 | | |
| LOGO | 22332 | | 22322 | 00165 | 00117 | | |
| TRAPE | 22455 | | | | | | |
| EPOX | 22466 | | | | | | |
| ACE | 22514 | | 22507 | 00067 | 00055 | 47675 | |
| BNATRX | 22610 | | 22576 | 01432 | 00794 | 47675 | |
| ERROR | 24230 | *NONE* | 24230 | 00012 | 00010 | | |
| ADD | 24242 | *NONE* | 24242 | 00050 | 00040 | | |
| ARSIN | 24322 | *NONE* | 24312 | 00144 | 00100 | 77152 | |
| ARCCOS | 24316 | | | | | | |
| QARSIN | 24314 | | | | | | |
| QARCCOS | 24312 | | | | | | |
| ERRARS | 24443 | | | | | | |
| ERRARC | 24447 | | | | | | |
| ARTAN | 24456 | *NONE* | 24456 | 00103 | 00067 | 77152 | |
| DAYS | 24564 | FIX FLOAT ADD | 24561 | 00042 | 00034 | | |
| EPPHEM | 24644 | QUIZ PONT KINE STARP (DFSB) TIMER LOOKUP INTR1 KOOL GAMAT RITEM TDCIM WREDF | 24623 | 00604 | 00388 | 47675 | |
| FIXT | 25430 | | 25427 | 00007 | 00007 | | |
| FIXTT | 25436 | *NONE* | 25436 | 00312 | 00202 | 50031 | |
| FLOT | 25544 | | | | | | |
| FIX | 25725 | | | | | | |
| FLOAT | 25731 | | | | | | |
| DAYE | 25741 | | | | | | |
| FLAT | 25752 | ERRDR | 25750 | 00102 | 00066 | | |
| FLAPR | 26000 | TYPRYT | | | | | |
| FLAK | 26007 | | | | | | |
| GIG2 | 26056 | *NONE* | 26052 | 00266 | 00182 | 50001 | |
| EPHEM | 26344 | REWINO | 26340 | 01452 | 00810 | | |
| TAPEX | 27524 | READB BSREC SIN COS | 30012 | 00336 | 00222 | 50001 | |
| PHUT | 30020 | | | | | | |
| ROT | 30354 | *NONE* | 30350 | 00266 | 00182 | 50031 | |
| GAMAT | 30652 | (DFAD) (DFSB) LOOKUP INTR1 INSPC BNATRX (DFMP) (DFDP) (DFDP) (DFMP) (DFAD) DRDD COS | 30636 | 00614 | 00396 | 47675 | |
| GHADP | 31464 | | 31452 | 00320 | 00208 | 50031 | |
| INSPC | 31776 | *NONE* | 31772 | 00310 | 00200 | 50031 | |
| DNTR2 | 36365 | EPHEM | 32302 | 04214 | 02188 | | |
| INTR1 | 36406 | PHUT ROT ERROR | | | | | |
| KINE | 36520 | REDE ERROR | 36516 | 00200 | 00128 | 50001 | |
| LOOKUP | 36720 | ERROR | 36716 | 00463 | 00307 | 47777 | |
| KOOL | 37250 | REDE | | | | | |
| PONT | 37414 | DFESYS (DFAD) TIMER LOOKUP INTR1 GAMAT RITEM | 37401 | 00311 | 00201 | 51235 | |

JPL TECHNICAL MEMORANDUM NO. 33-204

| | | | | | | |
|--------|-------|---|-------|-------|-------|-------|
| QUIZ | 37712 | *NONE* | 37712 | 00003 | 00003 | |
| RCAL | 37722 | SQRT | 37715 | 00240 | 00160 | 50031 |
| RCOM | 40162 | SQRT | 40155 | 00133 | 00091 | 50031 |
| WREOF | 40431 | FLAT | 40310 | 02520 | 01360 | |
| RITEH | 40314 | WRITEB ENDFIL REHIND | | | | |
| RSIG | 43034 | *NONE* | 43030 | 00064 | 00052 | 47675 |
| OFFSYS | 43114 | *NONE* | 43114 | 00010 | 00008 | |
| ENDSYS | 43115 | | | | | |
| FJNSYS | 43116 | | | | | |
| SCHAIN | 43117 | | | | | |
| PGSTRY | 43120 | | | | | |
| PGSTOP | 43121 | | | | | |
| DCP | 43122 | | | | | |
| TYPRYT | 43123 | | | | | |
| SIN | 43124 | *NONE* | 43124 | 00242 | 00162 | |
| COS | 43127 | | | | | |
| OSIN | 43133 | | | | | |
| QCOS | 43135 | | | | | |
| STARP | 43366 | *NONE* | 43366 | 00031 | 00025 | |
| TIMER | 43426 | (DFSB) LOOKUP SQRT | 43417 | 00142 | 00098 | 50031 |
| TOCIM | 43600 | OFFSYS TIMER LOOKUP INTR1 SQRT KODL CAHAT CHADP COS SIN ARSIN ARCOS WRITEB FLAT RITE DCP | 43561 | 01126 | 00598 | |
| REDE | 44710 | | | | | |
| RITE | 44713 | | | | | |
| PI5A | 45137 | | | | | |
| (DFAD) | 45330 | *NONE* | 45330 | 00120 | 00080 | 77776 |
| (DFSB) | 45350 | | | | | |
| (DFMP) | 45370 | | | | | |
| (DFDP) | 45416 | | | | | |
| DMDD | 45450 | *NONE* | 45450 | 00060 | 00048 | 77776 |
| SQRT | 45530 | *NONE* | 45530 | 00055 | 00045 | 77773 |
| READD | 45606 | (IDU) | 45605 | 00365 | 00245 | |
| READB | 45610 | | | | | |
| WRITED | 45613 | | | | | |
| WRITEB | 45615 | | | | | |
| BSREG | 46024 | | | | | |
| BSFILE | 46027 | | | | | |
| REHIND | 46032 | | | | | |
| UNLOAD | 46035 | | | | | |
| ENDFIL | 46040 | | | | | |
| SETLOW | 46016 | | | | | |
| SETHI | 46021 | | | | | |
| (UWIT) | 46167 | | | | | |
| TAPEID | 46167 | | | | | |
| (IDU) | 46175 | *NONE* | 46172 | 00030 | 00024 | |

*LA11 * JUST LOADED.

UNUSED CORE LIES FROM 46222 THROUGH 47675, LEAVING 01454 OCTAL OR 00812 DECIMAL LOCATIONS.

| ENTRY POINTS TO SUBROUTINES REQUESTED FROM LIBRARY, | DEFINE | ATTACH | OPEN | CLOSE | SQRT | PROUT | (DFSB) | (DFAD) | FGOUT | EXIT |
|---|------------|----------|---------|-----------|--------------|----------------|--------------|--------|-------|------|
| THE NAME OF THIS PROGRAM IS *LA12 * | | | | | | | | | | |
| 2/22/65 | | | | | | | | | | |
| ENTRY NAME | ENTRY ADD. | TRANSFER | VECTORS | LOAD ADD. | OCTAL LENGTH | DECIMAL LENGTH | COMMON BREAK | | | |
| **PCB | 22302 | SAVCOM | | 22301 | 00123 | 00083 | | | | |
| SAVCOM | 22440 | DEFINE | | 22424 | 02154 | 01132 | | | | |
| | | ATTACH | | | | | | | | |
| | | OPEN | | | | | | | | |
| | | PRIM | | | | | | | | |
| | | UUFST | | | | | | | | |
| | | MAXIM | | | | | | | | |
| | | OFFSYS | | | | | | | | |
| | | TYPRYT | | | | | | | | |
| | | RITE | | | | | | | | |
| | | CLOSE | | | | | | | | |
| | | ERROR | | | | | | | | |
| | | FLAK | | | | | | | | |
| BIRCD | 24025 | *NONE* | | 24600 | 00055 | 00045 | | | | |
| DIAGO | 24662 | SQRT | | 24655 | 00105 | 00069 | | 50031 | | |
| ERROR | 24766 | TYPRYT | | 24762 | 00544 | 00356 | | | | |
| | | PROJT | | | | | | | | |
| | | ENDSYS | | | | | | | | |
| FLAT | 25530 | RECOV | | 25526 | 00102 | 00066 | | | | |
| FLAPR | 25556 | ERROR | | | | | | | | |
| FLAK | 25565 | TYPRYT | | | | | | | | |
| KTIME | 25632 | | | | | | | | | |
| MAXIM | 26056 | REDE | | 25630 | 00215 | 00141 | | 50001 | | |
| | | ERROR | | 26045 | 00473 | 00315 | | 50001 | | |
| | | QUIZ | | | | | | | | |
| | | XJNE | | | | | | | | |
| | | (DFSB) | | | | | | | | |
| | | (DFAD) | | | | | | | | |
| MOCT | 26544 | MOCT | | 26540 | 00107 | 00071 | | | | |
| NORMAY | 26654 | *NONE* | | 26647 | 00252 | 00170 | | 77461 | | |
| APRED | 27204 | SORT | | 27121 | 00143 | 00099 | | | | |
| UPREJ | 27231 | FIXT | | | | | | | | |
| OPERA | 27122 | | | | | | | | | |
| DUKEY | 27246 | | | | | | | | | |
| OPKEY | 27270 | *NONE* | | 27264 | 00040 | 00032 | | | | |
| COKEY | 27305 | | | | | | | | | |
| AFKEY | 27312 | | | | | | | | | |
| PRIM | 27345 | | | 27324 | 01424 | 00788 | | 50001 | | |
| PRAM | 27334 | FGOUT | | | | | | | | |
| | | PROUT | | | | | | | | |
| | | BIRCD | | | | | | | | |
| | | FLAPR | | | | | | | | |
| | | PRIME | | | | | | | | |
| | | NORMAY | | | | | | | | |
| | | PRIT | | | | | | | | |
| | | DIAGO | | | | | | | | |
| TAMP | 30751 | *NONE* | | 30750 | 00004 | 00004 | | | | |
| PRIME | 30752 | | | | | | | | | |
| TAPR | 30753 | | | | | | | | | |
| DIAGO | ***** | | | | | | | | | |

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| | | | | | | |
|--------|-------|--------|-------|-------|-------|-------|
| PRIT | 30756 | FIXT | 30754 | 00035 | 00029 | |
| QUEST | 31020 | BIFCO | 31031 | 00165 | 00117 | 47675 |
| | | ERRRQ | | | | |
| | | EXIT | | | | |
| QUIZ | 31176 | *NONE* | 31176 | 00002 | 00002 | |
| RECOV | 31200 | *NONE* | 31200 | 00002 | 00002 | |
| SETUP | 31204 | RITE | 31202 | 00105 | 00069 | 50031 |
| | | ENDSYS | | | | |
| FIXT | 31310 | FIXTT | 31307 | 00007 | 00007 | |
| FIXTT | 31316 | *NONE* | 31316 | 00312 | 00202 | 50031 |
| FLOT | 31424 | | | | | |
| FIX | 31605 | | | | | |
| FLOAT | 31611 | | | | | |
| DAYE | 31621 | | | | | |
| OFFSYS | 31630 | *NONE* | 31630 | 00011 | 00009 | |
| ENDSYS | 31631 | | | | | |
| FINSYS | 31632 | | | | | |
| SCHAIN | 31633 | | | | | |
| PGSTRT | 31634 | | | | | |
| PGSTOP | 31635 | | | | | |
| DCP | 31636 | | | | | |
| TYPRYT | 31637 | | | | | |
| REDE | 31642 | DCP | 31641 | 00421 | 00273 | |
| RITE | 31645 | | | | | |
| PISA | 32071 | | | | | |
| EXIT | 32263 | *NONE* | 32262 | 00210 | 00136 | |
| EXSEL | 32366 | | | | | |
| EXITFN | 32274 | | | | | |
| ERRDMP | 32262 | | | | | |
| (DFAD) | 32472 | *NONE* | 32472 | 00120 | 00080 | 77776 |
| (DFSB) | 32512 | | | | | |
| (DFMP) | 32532 | | | | | |
| (DFDP) | 32560 | | | | | |
| SQRT | 32612 | *NONE* | 32612 | 00054 | 00044 | 77773 |
| PROUT | 32702 | DUTUS | 32666 | 03032 | 01562 | |
| FGDOUT | 34146 | ACTIND | | | | |
| PRCNV | 33047 | BFLC | | | | |
| PRDUT2 | 33020 | RESTKA | | | | |
| PROUT3 | 33033 | REGIND | | | | |
| TSXA | 35055 | WRITE | | | | |
| TSXB | 35645 | PACON | | | | |
| | | RGGSAV | | | | |
| | | RGGSTR | | | | |
| | | CKIND | | | | |
| | | CXACT | | | | |
| DUTUS | 35722 | RGGSAV | 35720 | 02320 | 01232 | |
| BFLC | 36954 | RGGSTR | | | | |
| ENDOUT | 36307 | | | | | |
| CKIND | 40151 | | | | | |
| CXACT | 40214 | | | | | |
| REGIND | 40150 | | | | | |
| ACTIND | 40147 | | | | | |
| RESTKA | 40145 | | | | | |
| PLICON | 40230 | | | | | |
| PL2CON | 40231 | | | | | |
| PL3CON | 40232 | | | | | |
| PRCON | 40233 | | | | | |
| RGGSAV | 40240 | *NONE* | 40240 | 00133 | 00091 | |
| RGGSTR | 40322 | | | | | |
| IOCS | 40374 | CLOCK | 40373 | 04335 | 02269 | |
| DEFINE | 40375 | | | | | |
| JOIN | 40400 | | | | | |
| ATTACH | 40403 | | | | | |
| CLOSE | 40406 | | | | | |
| OPEN | 40411 | | | | | |
| READ | 40414 | | | | | |
| WRITE | 40417 | | | | | |
| COPY | 40422 | | | | | |
| REW | 40525 | | | | | |
| WEP | 40430 | | | | | |
| BSR | 40433 | | | | | |
| BSF | 40436 | | | | | |
| STASH | 40441 | | | | | |
| CLOCK | 44733 | *NONE* | 44730 | 00106 | 00070 | |
| MINUTE | 44730 | | | | | |
| XMIN | 44730 | | | | | |

*LA12 * JUST LOADED.

UNUSED CORE LIES FROM 45036 THROUGH 47675, LEAVING 02640 OCTAL OR 01440 DECIMAL LOCATIONS.

ENTRY POINTS TO SUBROUTINES REQUESTED FROM LIBRARY.

| DEFINE | ATTACH | OPEN | PROUT | CLOSE | (DFDP) | (DFSB) | (DFMP) | (DFAD) | DNOD |
|---|------------|------------------|-----------|--------------|----------------|--------------|--------|--------|------|
| THE NAME OF THIS PROGRAM IS *ODPX * 2/22/65 | | | | | | | | | |
| ENTRY NAME | ENTRY ADD. | TRANSFER VECTORS | LOAD ADD. | OCTAL LENGTH | DECIMAL LENGTH | COMMON BREAK | | | |
| FIRST | 22312 | DATA | 22301 | 02070 | 01080 | | | | |
| | | DEFINE | | | | | | | |
| | | ATTACH | | | | | | | |
| | | OPEN | | | | | | | |
| | | PROUT | | | | | | | |
| | | NOHML | | | | | | | |
| | | RITE | | | | | | | |
| | | CLOSE | | | | | | | |
| | | FLAX | | | | | | | |
| **PCB | 24372 | FIRST | 24371 | 00007 | 00007 | | | | |
| ERROR | 24400 | *NONE* | 24400 | 00012 | 00010 | | | | |
| DATA | 24412 | *NONE* | 24412 | 01117 | 00591 | | | | |
| FIXT | 25532 | FIXTT | 25531 | 00007 | 00007 | | | | |
| FIXTT | 25540 | *NONE* | 25540 | 00312 | 00202 | 50031 | | | |
| FLOT | 25646 | | | | | | | | |
| FIX | 26027 | | | | | | | | |
| FLOAT | 26039 | | | | | | | | |
| DAYE | 26043 | | | | | | | | |
| GHADP | 26064 | (DFDP) | 26052 | 00320 | 00208 | 50031 | | | |
| | | (DFSB) | | | | | | | |
| | | (DFMP) | | | | | | | |
| | | (DFAD) | | | | | | | |
| | | DNOD | | | | | | | |
| | | CDS | | | | | | | |
| NOHML | 26376 | *NONE* | 26372 | 00763 | 00499 | 47777 | | | |
| NORMAY | 27362 | SQRT | 27355 | 00251 | 00169 | 77461 | | | |
| QUIZ | 27626 | *NONE* | 27626 | 00002 | 00002 | | | | |
| OFFSYS | 27630 | *NONE* | 27630 | 00010 | 00008 | | | | |
| ENDSYS | 27631 | | | | | | | | |
| FINSYS | 27632 | | | | | | | | |

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| | | | | | |
|--------|-------|--------|-------|-------|-------|
| SCHAIN | 27633 | | | | |
| PGSTRT | 27634 | | | | |
| PGSTOP | 27635 | | | | |
| QCP | 27636 | | | | |
| TYPRYT | 27637 | | | | |
| SIN | 27640 | 'NONE' | 27640 | 00243 | 00163 |
| COS | 27643 | | | | |
| QSIN | 27647 | | | | |
| QCOS | 27651 | | | | |
| REDS | 30104 | DCP | 30103 | 00421 | 00273 |
| RITE | 30107 | | | | |
| PISA | 30333 | | | | |
| FLAT | 30526 | ERROR | 30524 | 00102 | 00066 |
| FLAPR | 30554 | TYPRYT | | | |
| FLAK | 30563 | | | | |
| IDFAD1 | 30626 | 'NONE' | 30626 | 00120 | 00080 |
| IDFS1 | 30646 | | | | 77776 |
| IDFMP1 | 30666 | | | | |
| IDFDP1 | 30714 | | | | |
| ORBO | 30746 | 'NONE' | 30746 | 00060 | 00048 |
| ORBT | 31026 | 'NONE' | 31026 | 00054 | 00044 |
| PRDUT | 31116 | DOTUS | 31102 | 03032 | 01562 |
| FDDUT | 32262 | ACTIND | | | |
| PRCNV | 31263 | BFLC | | | |
| PRDUT2 | 31234 | RESTKA | | | |
| PRDUT3 | 31247 | REQIND | | | |
| TSXA | 33271 | WRITE | | | |
| TSXB | 34061 | PRCON | | | |
| | | RGGSAY | | | |
| | | RUGSTR | | | |
| | | CKIND | | | |
| | | CKACT | | | |
| | | RGGSAY | 34134 | 02320 | 01232 |
| | | RUGSTR | | | |
| DUTUS | 34136 | | | | |
| BFLC | 34772 | | | | |
| ENDOUT | 34523 | | | | |
| CKIND | 36365 | | | | |
| CKACT | 36430 | | | | |
| REQIND | 36364 | | | | |
| ACTIND | 36363 | | | | |
| RESTKA | 36361 | | | | |
| PL1CON | 36444 | | | | |
| PL2CON | 36445 | | | | |
| PL3CON | 36446 | | | | |
| PRCON | 36447 | | | | |
| RGGSAY | 36454 | 'NONE' | 36454 | 00133 | 00091 |
| RUGSTR | 36536 | | | | |
| IGCS | 36610 | CLOCK | 36607 | 04335 | 02269 |
| DEFINE | 36611 | | | | |
| JOIN | 36614 | | | | |
| ATTACH | 36617 | | | | |
| CLOSE | 36622 | | | | |
| OPEN | 36625 | | | | |
| READ | 36630 | | | | |
| WRITE | 36633 | | | | |
| COPY | 36636 | | | | |
| REW | 36641 | | | | |
| WFF | 36644 | | | | |
| BSR | 36647 | | | | |
| BSF | 36652 | | | | |
| STASH | 36659 | | | | |
| CLOCK | 43147 | 'NONE' | 43144 | 00106 | 00070 |
| MINUTE | 43144 | | | | |
| XMIN | 43144 | | | | |

*DDPX * JUST LOADED.

UNUSED CORE LINES FROM 43252 THROUGH 47777. LEAVING 04526 OCTAL OR 02390 DECIMAL LOCATIONS.

QCP COMMON MAP, JANUARY 4, 1965.

| | | | | |
|-------|-------------|--------|-----|--------------------------------------|
| 77461 | T | COLUMN | 2 | RUNNING TIME |
| 77457 | EPOCH | COLUMN | 2 | EPOCH |
| 77455 | FINAL | COLUMN | 2 | FINAL TRAJECTORY TIME |
| 77453 | OBSERVATION | COLUMN | 2 | OBSERVATION TIME |
| 77451 | DELTA | COLUMN | 2 | LIGHT TIME CORRECTION |
| 77447 | LOWER | COLUMN | 2 | LOWER LIMIT OF LINE INTEGRATION |
| 77445 | DELTA | COLUMN | 2 | SECOND LIGHT TIME CORRECTION |
| | | | | FILE TRANS CARD 02 |
| 77443 | GHA | COLUMN | 1 | GREENWICH HOUR ANGLE |
| 77442 | GHA | COLUMN | 1 | INJECTION GHA |
| 77441 | RUTMX | COLUMN | 3+1 | PRED. OF PRECESSION AND NUTATION MX. |
| 77430 | ORIG | COLUMN | 36 | |
| 77430 | ORIG | COLUMN | 36 | |
| 77427 | ORIG | COLUMN | 36 | |
| 77426 | ORIG | COLUMN | 36 | |
| 77425 | ORIG | COLUMN | 36 | |
| 77424 | ORIG | COLUMN | 36 | |
| 77423 | ORIG | COLUMN | 36 | |
| 77422 | ORIG | COLUMN | 36 | |
| 77421 | ORIG | COLUMN | 36 | |
| 77420 | ORIG | COLUMN | 36 | |
| 77417 | ORIG | COLUMN | 36 | |
| 77416 | ORIG | COLUMN | 36 | |
| 77415 | ORIG | COLUMN | 36 | |
| 77414 | ORIG | COLUMN | 36 | |
| 77413 | ORIG | COLUMN | 36 | |
| 77412 | ORIG | COLUMN | 36 | |
| 77411 | ORIG | COLUMN | 36 | |
| 77410 | ORIG | COLUMN | 36 | |
| 77407 | ORIG | COLUMN | 36 | |
| 77406 | ORIG | COLUMN | 36 | |
| 77405 | ORIG | COLUMN | 36 | |
| 77404 | ORIG | COLUMN | 36 | |
| 77403 | ORIG | COLUMN | 36 | |
| 77402 | ORIG | COLUMN | 36 | |
| 77401 | ORIG | COLUMN | 36 | |
| 77400 | ORIG | COLUMN | 36 | |
| 77377 | ORIG | COLUMN | 36 | |
| 77376 | ORIG | COLUMN | 36 | |
| 77375 | ORIG | COLUMN | 36 | |
| 77374 | ORIG | COLUMN | 36 | |
| 77373 | ORIG | COLUMN | 36 | |
| 77372 | ORIG | COLUMN | 36 | |
| 77371 | ORIG | COLUMN | 36 | |
| 77370 | ORIG | COLUMN | 36 | |
| 77367 | ORIG | COLUMN | 36 | |
| 77366 | ORIG | COLUMN | 36 | |
| 77365 | ORIG | COLUMN | 36 | |
| | | | | FILE TRANS CARD 03 |
| 77364 | RVEC | COLUMN | 1 | SLANT RANGE |
| 77363 | RDOT | COLUMN | 1 | SLANT RANGE RATE |
| 77362 | EL | COLUMN | 1 | ELEVATION ANGLE |
| 77361 | AZI | COLUMN | 1 | AZIMUTH ANGLE |

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| | | | | |
|-------------------|-------|--------|------|-----------------------------------|
| 77360 | DEC | COMMON | 1 | LOCAL DECLINATION ANGLE |
| 77357 | HA | COMMON | 1 | LOCAL HOUR ANGLE |
| 77356 | C1 | COMMON | 1 | 1 WAY DOPPLER |
| 77355 | CC3 | COMMON | 1 | COHERENT 3 WAY DOPPLER |
| 77354 | C3 | COMMON | 1 | 3 WAY DOPPLER |
| 77353 | CO1 | COMMON | 1 | DIFFERENCED 1 WAY DOPPLER |
| 77352 | CO3 | COMMON | 1 | DSIF RANGING |
| 77351 | XXX | COMMON | 1 | EXTRA DATA TYPE |
| * FORTRAN CARD 04 | | | | |
| 77350 | DRVEC | COMMON | 1 | CORRECTIONS |
| 77347 | DRDDT | COMMON | 1 | |
| 77346 | DEL | COMMON | 1 | |
| 77345 | DAZ | COMMON | 1 | |
| 77344 | DDEC | COMMON | 1 | |
| 77343 | DHA | COMMON | 1 | |
| 77342 | DC1 | COMMON | 1 | |
| 77341 | DC3 | COMMON | 1 | |
| 77340 | DC3 | COMMON | 1 | |
| 77337 | DC01 | COMMON | 1 | |
| 77336 | DC03 | COMMON | 1 | |
| 77335 | DXXX | COMMON | 1 | |
| * FORTRAN CARD 05 | | | | |
| 77334 | RVEC0 | COMMON | 1 | OBSERVED VALUES |
| 77333 | RDDTU | COMMON | 1 | |
| 77332 | ELU | COMMON | 1 | |
| 77331 | AZIU | COMMON | 1 | |
| 77330 | DECU | COMMON | 1 | |
| 77327 | HAD | COMMON | 1 | |
| 77326 | C1U | COMMON | 1 | |
| 77325 | CC3U | COMMON | 1 | |
| 77324 | C3U | COMMON | 1 | |
| 77323 | CO1U | COMMON | 1 | |
| 77322 | CO3U | COMMON | 1 | |
| 77321 | XXU | COMMON | 1 | |
| * FORTRAN CARD 06 | | | | |
| 77320 | RVEC0 | COMMON | 1 | RESIDUALS (OBSERVED-CALCULATED) |
| 77317 | RDDTD | COMMON | 1 | |
| 77316 | ELU | COMMON | 1 | |
| 77315 | AZIU | COMMON | 1 | |
| 77314 | DECU | COMMON | 1 | |
| 77313 | HAD | COMMON | 1 | |
| 77312 | C1U | COMMON | 1 | |
| 77311 | CC3U | COMMON | 1 | |
| 77310 | C3U | COMMON | 1 | |
| 77307 | CO1U | COMMON | 1 | |
| 77306 | CO3U | COMMON | 1 | |
| 77305 | XXU | COMMON | 1 | |
| * FORTRAN CARD 07 | | | | |
| 77304 | RVEC0 | COMMON | 1 | WEIGHTS |
| 77303 | RDDTD | COMMON | 1 | |
| 77302 | ELU | COMMON | 1 | |
| 77301 | AZIU | COMMON | 1 | |
| 77300 | DECU | COMMON | 1 | |
| 77277 | HAD | COMMON | 1 | |
| 77276 | C1U | COMMON | 1 | |
| 77275 | CC3U | COMMON | 1 | |
| 77274 | C3U | COMMON | 1 | |
| 77273 | CO1U | COMMON | 1 | |
| 77272 | CO3U | COMMON | 1 | |
| 77271 | XXU | COMMON | 1 | |
| * FORTRAN CARD 08 | | | | |
| 77270 | IX | COMMON | 1 | RECEIVER I.O. |
| 77267 | IX | COMMON | 1 | EMITTER I.O. |
| 77266 | ID | COMMON | 1 | CURRENT DATA TYPE |
| 77265 | PASS | COMMON | 1 | PASS IDENTIFICATION |
| 77246 | XJUP | COMMON | 6 | JUPITER VECTOR |
| 77240 | XERS | COMMON | 6 | SATURN VECTOR |
| 77232 | XMAR | COMMON | 6 | MARS VECTOR |
| 77224 | XVEN | COMMON | 6 | VENUS VECTOR |
| 77216 | XSN | COMMON | 6 | SUN VECTOR |
| 77210 | XMO | COMMON | 6 | MOON VECTOR |
| * FORTRAN CARD 09 | | | | |
| 77202 | X | COMMON | 1 | PROBE VECTOR |
| 77201 | Y | COMMON | 1 | |
| 77200 | Z | COMMON | 1 | |
| 77177 | XDUT | COMMON | 1 | |
| 77176 | YDUT | COMMON | 1 | |
| 77175 | ZDUT | COMMON | 1 | |
| 77174 | U | COMMON | 36 | VARIATIONAL EQUATIONS |
| 77130 | DL0 | COMMON | 1 | NUTATION IN LONGITUDE |
| 77127 | DL8 | COMMON | 1 | NUTATION IN OBLIQUITY |
| * FORTRAN CARD 10 | | | | |
| 77126 | XAC | COMMON | 1 | PROBE ACCELERATION |
| 77125 | YAC | COMMON | 1 | |
| 77124 | ZAC | COMMON | 1 | |
| 77123 | XJERK | COMMON | 1 | PROBE JERK (THIRD DERIVATIVE) |
| 77122 | YJERK | COMMON | 1 | |
| 77121 | ZJERK | COMMON | 1 | |
| 77120 | UINV | COMMON | 36 | INVERSE OF VARIATIONAL EQUATIONS |
| 77054 | PUBX | COMMON | 6*12 | PARTIALS(OBSERVABLES/CARTESIAN) |
| 76744 | BMAT | COMMON | 6*11 | B MATRIX OF PARTIALS |
| * FORTRAN CARD 11 | | | | |
| 76642 | ELX | COMMON | 1 | DIRECTION COSINES |
| 76641 | ELY | COMMON | 1 | |
| 76640 | ELZ | COMMON | 1 | |
| 76637 | AX | COMMON | 1 | DIRECTION COSINES |
| 76636 | AY | COMMON | 1 | |
| 76635 | AZ | COMMON | 1 | |
| 76634 | DX | COMMON | 1 | DIRECTION COSINES |
| 76633 | DY | COMMON | 1 | |
| 76632 | DZ | COMMON | 1 | |
| 76631 | TAX | COMMON | 1 | DIRECTION COSTINES |
| 76630 | TAY | COMMON | 1 | |
| 76627 | TAZ | COMMON | 1 | |
| 76626 | TDX | COMMON | 1 | DIRECTION COSINES |
| 76625 | TDY | COMMON | 1 | |
| 76624 | TDZ | COMMON | 1 | |
| * FORTRAN CARD 12 | | | | |
| 76623 | TAU | COMMON | 1 | DOPPLER AVERAGING TIME |
| 76622 | LLIST | COMMON | 6 | POSITION AND VELOCITY FLAGS |
| 76614 | MLIST | COMMON | 11 | PHYSICAL CONSTANTS PARTIALS FLAGS |
| 76601 | HLIST | COMMON | 1 | VELOCITY OF LIGHT FLAG |

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| | | | | |
|-------|--------|--------|---------|--------------------------------------|
| 76600 | MLIST | COMMON | 3=15 | STATION LOCATION FLAGS |
| 76523 | NEST | COMMON | 1 | NO. ESTIMATED PARAMETERS |
| 76522 | NCUM | COMMON | 1 | NO. CONSIDERED PARAMETERS |
| 76521 | EP | COMMON | 100 | E.T.-U.T. |
| 76520 | EGU | | EP-1 | |
| 76513 | EGU | | EP-6 | BAND(-1017=LS 0=L 1017=S) |
| 76512 | EGU | | EP-7 | K1 FREQUENCY |
| 76511 | EGU | | EP-4 | K5 FREQUENCY |
| 76510 | EGU | | EP-9 | BAND DESIGNATION (15 WORDS) |
| 76471 | EGU | | EP-24 | START TIME, ATTITUDE CONTROL |
| 76470 | EGU | | EP-25 | UP |
| 76467 | EGU | | EP-26 | STOP TIME, ATTITUDE CONTROL |
| 76466 | EGU | | EP-27 | DP |
| 76465 | EGU | | EP-28 | |
| 76457 | EGU | | EP-34 | MCIM COMMENT BUFFER (30 WORDS) |
| 76421 | EGU | | EP-64 | NOT ZERO TO READ CARDS FROM A2 |
| 76420 | EGU | | EP-65 | ID FOR PREDICTS |
| 76417 | EGU | | EP-66 | POWERED FLIGHT PARAMETERS (10 WORDS) |
| 76375 | ELU | | EP-84 | STEP MAP FLAG=U PRODUCE |
| 76374 | EGU | | EP-95 | START TIME, STEP MAP PRINTOUT |
| 76373 | EGU | | EP-96 | DP |
| 76372 | EGU | | EP-97 | FLAG TO REPEAT TRAJ FOR STEP MAP |
| 76371 | ELU | | EP-98 | SPACE COMMENT BUFFER (17 WORDS) |
| 76350 | ELU | | EP-105 | MAPPLD FORWARD EPU.LH |
| 76347 | EGU | | EP-106 | DP |
| 76346 | EGU | | EP-107 | FLAG FOR PUNCHING MATRICES |
| 76345 | EGU | | EP-108 | NOT ZERO TO BYPASS LALL |
| 76344 | EGU | | EP-109 | |
| 76235 | SIGM3 | COMMON | 12=15 | REJECTION SIGMAS |
| | | | | FORTRAN CARD 13. |
| 75751 | A | COMMON | 1 | COMMON |
| 75750 | B | COMMON | 1 | STORAGE |
| 75747 | C | COMMON | 1 | AVAILABLE |
| 75746 | D | COMMON | 1 | FOR |
| 75745 | E | COMMON | 1 | FAP |
| 75744 | F | COMMON | 1 | OR |
| 75743 | G | COMMON | 1 | FORTRAN |
| 75742 | H | COMMON | 1 | USAGE |
| 75741 | D | COMMON | 1 | |
| 75740 | P | COMMON | 1 | |
| 75737 | Q | COMMON | 1 | |
| 75736 | R | COMMON | 1 | |
| 75735 | S | COMMON | 1 | |
| | | | | FORTRAN CARD 14 |
| 75734 | RNJ | COMMON | 2 | SPHERICAL INJECTION CONDITIONS |
| 75733 | PHINJ | COMMON | 2 | |
| 75730 | ITHAJ | COMMON | 2 | |
| 75726 | VNJ | COMMON | 2 | |
| 75724 | ELNJ | COMMON | 2 | |
| 75722 | AZNJ | COMMON | 2 | |
| 75720 | XNJ | COMMON | 6 | GAUSSIAN INJECTION CONDITIONS |
| 75712 | XNDP | COMMON | 6 | |
| | | | | FORTRAN CARD 15 |
| 75704 | GRAV | COMMON | 1 | K(EARTH) |
| 75703 | RE | COMMON | 1 | EARTH RADIUS |
| 75702 | GMB | COMMON | 1 | RADIATION PRESSURE CONSTANT |
| 75701 | GRAV | COMMON | 1 | K(MOON) |
| 75700 | RVEN | COMMON | 1 | MASS RATIO VENUS |
| 75677 | RMAR | COMMON | 1 | MASS RATIO MARS |
| 75676 | RJUP | COMMON | 1 | MASS RATIO JUPITER |
| 75675 | UJ | COMMON | 1 | Coefficient SECOND HARMONIC |
| 75674 | UH | COMMON | 1 | Coefficient THIRD HARMONIC |
| 75673 | UD | COMMON | 1 | Coefficient FOURTH HARMONIC |
| 75672 | AU | COMMON | 1 | ASTRONOMICAL UNIT |
| 75671 | VELC | COMMON | 1 | VELOCITY OF LIGHT |
| | | | | FORTRAN CARD 16 |
| 75670 | RI | COMMON | 15 | STATION RANGE |
| 75651 | PHI1 | COMMON | 15 | STATION LATITUDE (GEOCENTRIC) |
| 75632 | THETA1 | COMMON | 15 | STATION LONGITUDE |
| | | | | FORTRAN CARD 17 |
| 75613 | GRAVS | COMMON | 1 | K(SUN) |
| 75612 | GRAVV | COMMON | 1 | K(venus) |
| 75611 | GRAVA | COMMON | 1 | K(MARS) |
| 75610 | GRAVJ | COMMON | 1 | K(JUPITER) |
| 75607 | OMEGA | COMMON | 1 | ANGULAR ROTATION RATE OF EARTH |
| 75606 | XI | COMMON | 1 | STATION X(1) |
| 75605 | YI | COMMON | 1 | STATION Y(1) |
| 75604 | ZI | COMMON | 1 | STATION Z(1) |
| 75603 | RAI | COMMON | 1 | STATION RIGHT ASCENSION |
| | | | | FORTRAN CARD 18 |
| 75602 | UI | COMMON | 15 | NORTH SOUTH DISPLACEMENT (GEO-GEOC) |
| 75563 | VI | COMMON | 15 | EAST WEST DISPLACEMENT |
| 75544 | FNI | COMMON | 15 | LOCAL INDEX OF REFRACTION |
| 75525 | TAB | COMMON | 1000 | |
| 75525 | EGU | | TAB | DATA FILE INPUT BUFFER (400 WORDS) |
| 74705 | EGU | | TAB=400 | DATA FILE OUTPUT BUFFER (400 WORDS) |
| 74065 | EGU | | TAB=800 | SCRATCH AREA, LAB (200 WORDS) |
| 73555 | YI | COMMON | 4*24 | PROBE EPHEMERIS INTERPOLATION BUFFER |
| 71325 | RESK | COMMON | 8*15 | SCALE FACTORS |
| 71135 | IREK | COMMON | 8*15 | PLOT FLAGS |
| 70745 | NHR | COMMON | 1 | PLOT STEP |
| | | | | FORTRAN CARD 19 |
| 70744 | DRBL | COMMON | 12 | VELOCITY OF LIGHT PARTIALS |
| 70730 | DIM3 | COMMON | 12=3*15 | STATION PARTIALS BY DATA TYPE |
| 67674 | CPPH1 | COMMON | 20 | CAP PHI MATRIX OF PARTIALS |
| 67650 | CPPH2 | COMMON | 20 | UP |
| 67624 | CPHI1 | COMMON | 20 | CAP THETA MATRIX OF PARTIALS |
| 67600 | CPHI2 | COMMON | 20 | DP |
| 67554 | XJ | COMMON | 20*20 | J MATRIX |
| 66734 | XJ2 | COMMON | 20*20 | DP |
| 66114 | XK | COMMON | 400 | SCRATCH 20*20 MATRIX |
| 65274 | XK2 | COMMON | 400 | SCRATCH 20*20 MATRIX |
| 64454 | RIGH1 | COMMON | 20 | RESIDUAL=CPPH1 ACCUMULATED |
| 64430 | RITE2 | COMMON | 20 | DP |
| | | | | FORTRAN CARD 20 |
| 64404 | CPGAM | COMMON | 20*20 | COVARIANCE MATRIX |
| 63564 | CPGM2 | COMMON | 20*20 | UP |
| 62744 | GFLP? | COMMON | 400 | INPUT COVARIANCE MATRIX (11 WERSE) |
| 62124 | GFLP? | COMMON | 400 | DP |
| 61304 | GAM1 | COMMON | 20*20 | COV PX OF UNADJUSTED PARAMETERS |
| 60464 | DIAT | COMMON | 60 | V MATRIX 1*VEGARD |

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| | | | | |
|-------|--------|---------|-----------------|--|
| 60362 | DIN2 | COMMON | 66 | DP |
| 60260 | DIG | COMMON | 48 | |
| 60260 | EDU | | DIG | |
| 60231 | PLOFIL | EQU | DIG-23 | IOCS PLOT CONTROL (12 WORDS FORWARD) |
| 60215 | PUNFIL | EQU | DIG-35 | IOCS PUNCH CONTROL (12 WORDS FORWARD) |
| 60201 | PRIFIL | EQU | DIG-47 | IOCS PRINT CONTROL (12 WORDS FORWARD) |
| | | | FORTRAN CARD 21 | |
| 60200 | YEAR | COMMON | 1 | 7-WORD TIME BLOCK |
| 60177 | MONTH | COMMON | 1 | INTEGERS IN ADDRESS PART |
| 60176 | DAY | COMMON | 1 | FAP USE ONLY |
| 60175 | HOUR | COMMON | 1 | |
| 60174 | MIN | COMMON | 1 | |
| 60173 | SEC | COMMON | 1 | |
| 60172 | FRAC | COMMON | 1 | |
| | | | FORTRAN CARD 22 | |
| 60171 | IF1 | COMMON | 1 | |
| 60170 | IF2 | COMMON | 1 | |
| 60167 | IF3 | COMMON | 1 | CONTENTS OF KEYS 10-17 |
| 60166 | IF4 | COMMON | 1 | |
| 60165 | IF5 | COMMON | 1 | ZERO TO CLOSE DATA FILE/PREDICT OUTPUT |
| 60164 | IF6 | COMMON | 1 | DATA FILE READ 1617=EQF 2017=NORMAL |
| 60163 | IF7 | COMMON | 1 | |
| 60162 | IF8 | COMMON | 1 | NOT ZERO TO CHECK RESIDUAL REJECTION |
| 60161 | IF9 | COMMON | 1 | |
| 60160 | IF10 | COMMON | 1 | NOT ZERO TO PRINT PHI VECTORS |
| | | | FORTRAN CARD 23 | |
| 60157 | KLIST | COMMON | 4 | FLAGS FOR ATTITUDE CONTROL ESTIMATION |
| 60153 | FABC | COMMON | 9 | ATTITUDE CONTROL COEFFICIENTS |
| 60142 | ELMIN | COMMON | 1 | MINIMUM ELEVATION ANGLE |
| 60141 | RMAX | COMMON | 1 | MAXIMUM SLANT RANGE |
| 60140 | RUN | COMMON | 1 | DATA FILE OUTPUT COUNTER |
| 60137 | BEFOR | COMMON | 1 | |
| 60136 | CA | COMMON | 11 | PARTIALS DF/DQ |
| 60123 | QB | COMMON | 6 | PARTIALS DF/DX0 |
| 60115 | TOBL | COMMON | 2 | PREVIOUS TUB |
| 60113 | XMU | COMMON | 20 | SCRATCH COLUMN VECTOR |
| 60067 | XX | COMMON | 400 | SCRATCH 20*20 MATRIX |
| 57247 | XC | COMMON | 400 | SCRATCH 20*20 MATRIX |
| | | | FORTRAN CARD 24 | |
| 56427 | IGNA2 | COMMON | 12*15 | NOT ZERO TO IGNORE DATA POINT |
| 56143 | SOUR | COMMON | 2 | SUM OF SQUARED RESIDUALS |
| 56141 | BU225 | COMMON | 15*15 | INPUT BUFFER |
| 56000 | BU12 | COMMON | 12 | DP INPUT BUFFER |
| | | | FORTRAN CARD 25 | |
| 55564 | XN | COMMON | 3 | CORRECTED PROBE COORDINATES |
| 55561 | DXN | COMMON | 3 | |
| 55556 | DOXN | COMMON | 3 | |
| 55553 | DDOXN | COMMON | 3 | |
| 55550 | IS | COMMON | 1 | DATA SAMPLE INTERVAL |
| 55547 | SSQ | COMMON | 12*6*4 | S=2 WEIGHTING TABLE |
| 55107 | TL | COMMON | 12*6*4 | T WEIGHTING TABLE |
| 54447 | GSQ | COMMON | 6 | G WEIGHTING TABLE |
| 54441 | OHBA0 | COMMON | 12 | NOT ZERO IF DATA TYPE REJECTED LAST |
| | | | FORTRAN CARD 26 | |
| 54425 | QTILD | COMMON | 20 | A PRIORI ESTIMATE |
| 54401 | QTP | COMMON | 20 | DP |
| 54355 | QP | COMMON | 20 | ESTIMATED CONDITIONS AND CONSTANTS |
| 54331 | QPDQ | COMMON | 20 | |
| 54305 | CZ1 | COMMON | 1 | DOPPLER COEFFICIENTS |
| 54304 | CZ2 | COMMON | 1 | |
| 54303 | CZ3 | COMMON | 1 | |
| 54302 | CZ4 | COMMON | 1 | |
| 54301 | CZ5 | COMMON | 1 | |
| 54300 | CZ6 | COMMON | 1 | |
| 54277 | PI | COMMON | 45 | INITIAL POINTING TIMES |
| 54222 | PID | COMMON | 45 | POINTING COUNT INTERVALS |
| 54145 | PIF | COMMON | 45 | FINAL POINTING TIMES |
| 54070 | PTFD | COMMON | 45 | |
| 54070 | EQU | PTFD | | OCULTATION-IMPACT TIMES (30 WORDS) |
| 54032 | EQU | PTFD-30 | | START-STOP TIMES (12 WORDS) |
| 54016 | EQU | PTFD-42 | | |
| 54013 | PINT | COMMON | 45 | POINTING SAMPLE INTERVAL |
| 53736 | PINTU | COMMON | 45 | CURRENT POINTING TIME |
| 53661 | BALN | COMMON | 12*15 | INPUT WEIGHTS |
| | | | FORTRAN CARD 27 | |
| 53375 | COSRA1 | COMMON | 1 | COS(RA1) |
| 53374 | SINRA1 | COMMON | 1 | SIN(RA1) |
| 53373 | COSPH1 | COMMON | 1 | COS(PHI1) |
| 53372 | SINPH1 | COMMON | 1 | SIN(PHI1) |
| 53371 | SINEL | COMMON | 1 | SIN(EL) |
| 53370 | CL37 | COMMON | 1 | NOT ZERO TO BYPASS LAL3 |
| 53367 | GADT | COMMON | 1 | PHYSICAL CONSTANTS INTEGRATION STEP |
| 53366 | CAPQ | COMMON | 1 | Q SUM OF SQUARES |
| 53365 | CAPQL | COMMON | 1 | |
| 53364 | DCQ | COMMON | 1 | |
| | | | FORTRAN CARD 28 | |
| 53363 | NTDT | COMMON | 1 | NUMBER OF POINTS IN SOUR |
| 53362 | QNU | COMMON | 20 | NEW Q-S (QP+RIGHT) |
| 53336 | QNUD | COMMON | 20 | DP |
| 53312 | ITRU | COMMON | 1 | ITERATION NUMBER |
| 53311 | COSEL | COMMON | 1 | COS(EL) |
| 53310 | SINAZ | COMMON | 1 | SIN(AZ) |
| 53307 | COSAZ | COMMON | 1 | COS(AZ) |
| | | | FORTRAN CARD 29 | |
| 53306 | CORR | COMMON | 400 | SCRATCH 20*20 MATRIX |
| 52466 | GTPP | COMMON | 400 | SCRATCH 20*20 MATRIX |
| 51646 | GMAI | COMMON | 66 | V MATRIX OF PARTIALS |
| 51544 | IFA | COMMON | 10 | ZERO TO INTEGRATE TO ENCOUNTER |
| 51544 | EQU | IFA | | |
| 51543 | EQU | IFA-1 | | |
| 51542 | EQU | IFA-2 | | |
| 51541 | EQU | IFA-3 | | |
| 51540 | EQU | IFA-4 | | |
| 51537 | EQU | IFA-5 | | NOT ZERO FOR DATA SIGMA OUTPUT |
| 51536 | EQU | IFA-6 | | RADIUS OF TARGET |
| 51535 | EQU | IFA-7 | | NOT ZERO TO TURN OFF SOLAR PRESSURE |
| 51534 | EQU | IFA-8 | | NOT ZERO TO TURN OFF LIGHT TIME |
| 51533 | EQU | IFA-9 | | NOT ZERO TO TURN OFF REFRACTION |
| 51532 | XFREW | COMMON | 1 | XMITTER FREQUENCY |
| 51531 | IFREU | COMMON | 1 | XPONDER FREQUENCY |
| 51530 | KEYS | COMMON | 1 | CONTENTS OF KEYS |
| 51527 | XPBUX | COMMON | 6 | XMITTER ROOT PARTIALS |
| 51521 | FXCN | COMMON | 6*15 | FREQUENCY COEFFICIENTS |
| 51367 | FXCNZ | COMMON | 6*15 | DP |
| | | | FORTRAN CARD 30 | |
| 51235 | COMTS | COMMON | 11 | PAGE HEADING |
| 51222 | SIGMA | COMMON | 12*15 | DATA FILE SIGMA |
| 50736 | BIAS | COMMON | 12*15 | DATA FILE BIAS |
| 50452 | IMAP | COMMON | 2 | CURRENT MAPPING TIME |
| 50450 | ITERAT | COMMON | 1 | |
| 50447 | YY1 | COMMON | 6*45 | TRANSMITTER ID TABLE |
| 50031 | IMAP | COMMON | 24 | MAPPING TIMES |
| 50001 | AREA | COMMON | 1 | S/C AREA |
| 50000 | FMASS | COMMON | 1 | S/C MASS |
| 47777 | GAMM | COMMON | 66 | PHYSICAL CONSTANTS INTEGRATION MATRIX |
| 47675 | CAPU | COMMON | 400 | MAPPING MATRIX TO ENCOUNTER |
| | | | END | |

V. OUTPUT

Primary output from the ODP is in the form of a BCD tape which may be listed on the IBM 1401. This listing contains the following items:

1. List of card input
2. A priori covariance matrix
3. Inverse of a priori covariance matrix
4. Trajectory information
5. J matrix
6. J matrix correlations
7. Parameter estimates and statistics
8. Inverse of J matrix
9. Covariance matrix
10. Covariance matrix correlations

The following items are output on option:

1. Residuals, computed observables, weights, and frequencies
2. Residual statistics
3. Pointing ephemeris
4. Mapping matrix
5. Mapped covariance matrix
6. Position and velocity of probe at mapping times
7. Encounter parameters and statistics
8. Supplementary printout at data times--vectors and partials

All items, with the exception of the supplementary partials printout, may be printed on the SC-3070 in SFOF Mode II operation.

Any matrix which is printed by the ODP may also be punched on option. In this case the card images are written on the same BCD output tape for punching by the 1401.

The ODP also writes a plotting tape for the SC-4020 plotter, containing plots of residuals versus time, and angle residuals versus angles.

A binary tape for the Matrix Manipulation Program, containing data partials and mapping matrices, is generated on option. This capability does not exist in Mode II operation.

Error comments and status-of-program messages are printed on the administrative printer in Mode II and the on-line printer in Mode IV. Refer to Subroutine 28, ERROR, for a listing of these comments.

A. DISK AND TAPE FORMATS

The Planetary Ephemeris format is presented in Ref. 4, and the Matrix Manipulation Program tape format in Ref. 11 (Section IX). The other formats are covered in Section VI; the Prediction File is presented in Subroutine 30, FILL; the Data File in Subroutine 43, KINE; the Probe Ephemeris in Subroutine 45, LOOKUP; and the Combined Ephemeris in Subroutine 86, RITEM.

B. OUTPUT SYMBOLS AND DEFINITIONS

The following symbols appear on the output listings. The corresponding symbols used in this report and the definitions are given:

| Output symbol | Report symbol | Definition |
|---------------|---|---|
| X | x } y } z } | position of probe, geocentric equatorial true of date, km |
| Y | | |
| Z | | |
| DX | \dot{x} } \dot{y} } \dot{z} } | velocity of probe, geocentric equatorial true of date, km/sec |
| DY | | |
| DZ | | |
| KE | GM_e | gravitational constant of Earth, km^3/sec^2 |
| RE | R_e | equatorial radius of Earth, km |
| G | γ_B | solar pressure constant |
| KM | GM_m | gravitational constant of Moon, km^3/sec^2 |
| MV | M_v | mass of Venus, solar masses |
| MM | M_r | mass of Mars, solar masses |

| Output symbol | Report symbol | Definition |
|---------------|---|---|
| MJ | M_j | mass of Jupiter, solar masses |
| J | J | second harmonic coefficient |
| H | H | third harmonic coefficient |
| D | D | fourth harmonic coefficient |
| AU | a_e | astronomical unit, km |
| FA | $\left. \begin{array}{l} F_{ao} \\ F_{bo} \\ F_{co} \end{array} \right\}$ | attitude |
| FB | | control |
| FC | | coefficients |
| C | c | speed of light, km/sec |
| RI(I) | R_i | radius of Earth at station i, km |
| LA(I) | ϕ_i | geocentric latitude of station i, deg |
| LO(I) | λ_i | longitude of station i, deg |
| R | ρ | slant range, km |
| DR | $\dot{\rho}$ | slant range rate, km/sec |
| EL | γ | elevation angle, deg |
| AZ | σ | azimuth angle, deg |
| DEC | δ | declination, deg |
| HA | α | hour angle, deg |
| C1 | f_1 | one-way integrated doppler frequency, cps |
| CC3 | f_{c3} | coherent three-way integrated doppler frequency, cps |
| C3 | f_3 | three-way integrated doppler frequency, cps |
| D1 | f_{d1} | differenced one-way integrated doppler frequency, cps |

| Output symbol | Report symbol | Definition |
|---------------|---|--|
| RU | ρ DSIF | DSIF ranging |
| B | $ \underline{B} $ | vector from target center of mass perpendicular to probe asymptote, km |
| B·RO | $\underline{B} \cdot \underline{R}_0$ | dot products, target orbital plane, km |
| B·TO | $\underline{B} \cdot \underline{T}_0$ | |
| B·RT | $\underline{B} \cdot \underline{R}_T$ | dot products, target equatorial plane, km |
| B·TT | $\underline{B} \cdot \underline{T}_T$ | |
| TL | t_L | linearized time of flight, hours (lunar missions) or days |
| TF | t_f | true time of flight, hours (lunar missions) or days |
| SMAA | a | semi-major axis of dispersion ellipse at target, km |
| SMIA | b | semi-minor axis, km |
| THETA | θ | inclination of dispersion ellipse to target orbital plane, deg |
| DEL T | σ_t | standard deviation of linearized time of flight, sec |
| DEL B | σ_B | standard deviation of \underline{B} vector, km |
| DEL S | σ_S | standard deviation of asymptote unit vector, km |
| DEL BR | $\sigma_{\underline{B} \cdot \underline{R}}$ | standard deviation of $\underline{B} \cdot \underline{R}$, km |
| DEL BT | $\sigma_{\underline{B} \cdot \underline{T}}$ | standard deviation of $\underline{B} \cdot \underline{T}$, km |
| C3 | c_3 | vis viva energy, km^2/sec^2 |
| TC | τ | doppler count time, sec |
| Q | q | transmitter index |
| FRQ | $\left\{ \begin{array}{l} f_q \\ f_T \end{array} \right.$ | if $q \neq 0$, station frequency less 29.66×10^6 cps |
| | | if $q = 0$, probe frequency less 960×10^6 cps |

VI. SUBROUTINES

Section VI contains the documentation for the 104 Subroutines which were written primarily for use by the SPODP. Documentation is not included for JPL general-purpose routines and SFOF routines.

IDENTIFICATION

1

AAT

Melba Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

This subroutine forms the matrix product of two vectors.

RESTRICTIONS

Standard Fortran II arrays.

USE

CALL AAT (X, Y, PRO)

X (1, 6) P

Y (6, 1) P^T

PRO (6, 6) Product matrix

CODING INFORMATION

Length of subroutine is 77 (10) or 115 (8) words.

IDENTIFICATION

2

ABDD

Charles Coltharp, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

ABDD computes the function.

$$S = \frac{Z_i(ax + by) - cz}{d},$$

the form of which has frequent application in ODP station location partial expressions.

RESTRICTIONS

COMMON break: 47675

USE

CALL ABDD

PZE D d

PZE R x, y, z (1 x 3)

COMMON input:

O a

B b

C c

Z_i Z - component of geocentric station vector, km.

COMMON output:

S s

CODING INFORMATION

Length of subroutine is 24 (10) or 30 (8) words.

IDENTIFICATION

3

ACE

Melba Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

To compute the unit vector as needed in calculation of the attitude control effects partials in BMATRIX.

RESTRICTIONS

- a. COMMON from ODP
- b. Subroutines used:
 SQRT

USE

CALL ACE (DDX)

Computes R, X/R etc, and stores the result in DDX(I).

CODING INFORMATION

Length of subroutine is 57 (10) or 71 (8) words.

IDENTIFICATION

4

ANGPLT

Alfred Schoepke, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

ANGPLT plots hour angle residuals versus hour angle, and declination residuals versus declination. A tape containing the plotting information is written for the SC-4020.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutine used:

PKINE

FIXT

BIBCD

CXPLOT

USE

CALL ANGPLT

COMMON input:

IR station identification

RVECD residual array

RVEC data type array

CODING INFORMATION

Length of subroutine is 383 (10) or 577 (8) words.

IDENTIFICATION

5

AQUI/ALLI/BAQUI/BALLI
Melba W. Nead, JPL
IBM 7094 Fap
January 4, 1965

PURPOSE

To format, list, and send, via TELTYP, predictions needed by the tracking stations.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:
 - PROUT
 - FGDOUT
 - PKINE
 - FIXT
 - TELTYP
 - ENDOUT
 - BIBCD

In MODE 2, the predictions are transmitted in real time by TELTYP. In MODE 4, a magnetic tape (A9) is written by TELTYP. This tape is then processed to punch paper tape acceptable to the teleprinters.

USE

CALL AQUI to list predictions
CALL BAQUI to prepare for transmission
CALL ALLI to list drive tape for Goldstone
CALL BALLI to prepare drive tape for transmission

CODING INFORMATION

Length of subroutine is 460 (10) or 714 (8) words.

REFERENCE

Heller, J., IOM to F. Curl, Nominal Predict Format, June 10, 1963.

IDENTIFICATION

6

BEER

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

BEER stores zeroes in certain ODP common locations prior to the data fit. It also executes the reset entry of REJEC.

RESTRICTIONS

- a. COMMON break: 46711
- b. Subroutine called:
REJEC

USE

CALL BEER

COMMON output: zeroes in DINT, DIN2, QA, QB, TOBL, TOBL-1, TGINT, TGINT-1, XMU, RIGHT, RITE2, XX, XC, XJ, XJ2, XK, XK2, IF2, IF4. BIGNO in IF1 and IF5.

CODING INFORMATION

Length of subroutines is 57 (10) or 71 (8) words.

IDENTIFICATION

7

BIBCD

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

To convert the binary equivalent of 2 digit decimal numbers to BCD for print-out.

RESTRICTION

Range of numbers: $1 \leq n \leq 99$

USE

With argument in the accumulator

CALL BIBCD

The BCD equivalent is in the accumulator on return.

CODING INFORMATION

Length of subroutine is 45 (10) or 55 (8) words.

IDENTIFICATION

8-1 of 4

BMATRIX

Melba Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

BMATRIX is written to compute the analytic partials of the physical constants when these parameters are being estimated or considered in the ODP.

RESTRICTIONS

- a. COMMON break: 47675
- b. When computing partials of the attitude control effects, partials of MJ, H, and D are inhibited, thus a maximum of 11 of the possible 14 can be computed at one time.
- c. Subroutines used:

ACE
GIG2
RCAL
RCOM
RSIG
SQRT

METHOD

Formulas for the partial derivatives of acceleration with respect to physical constants, $\partial \ddot{r}/\partial q$, are derived from the equations of motion. These are integrated to obtain $\partial r/\partial q$.

The equations for these partials follow:

$$\frac{\partial \ddot{x}}{\partial GM_e} = \frac{-xg_1}{r^3}$$

$$\frac{\partial \ddot{y}}{\partial GM_e} = \frac{-yg_1}{r^3}$$

$$\frac{\partial \ddot{z}}{\partial GM_e} = \frac{-zg_2}{r^3}$$

$$\frac{\partial \ddot{x}}{\partial R_e} = \frac{-GM_m}{R_e} \left\{ 2x_m \left[\frac{1}{|r_m - r|^3} - \frac{1}{r_m^3} \right] - 3 \frac{(r \cdot r_m - r^2)(x - x_m)}{|r_m - r|^5} - \frac{3x}{|r_m - r|^3} \right\} \quad x \rightarrow y, z$$

8-2 of 4

$$\frac{\partial \ddot{x}}{\partial \gamma_B} = \frac{c_1 A_p (x - x_s)}{M_p |r - r_s|^3}$$

x → y, z

where

$$c_1 = 1.031 \times 10^8$$

A_p = surface area of probe, m^2

M_p = mass of probe, kg

$$\frac{\partial \ddot{x}}{\partial GM_m} = - \left[\frac{x_m}{r_m^3} + \frac{(x - x_m)}{|r_m - r|^3} \right]$$

x → y, z

$$\frac{\partial \ddot{x}}{\partial M_v} = -GM_s \left[\frac{x_v}{r_v^3} + \frac{(x - x_v)}{|r_v - r|^3} \right]$$

x → y, z

$$\frac{\partial \ddot{x}}{\partial M_r} = -GM_s \left[\frac{x_r}{r_r^3} + \frac{(x - x_r)}{|r_r - r|^3} \right]$$

x → y, z

$$\frac{\partial \ddot{x}}{\partial M_j} = -GM_s \left[\frac{x_j}{r_j^3} + \frac{(x - x_j)}{|r_j - r|^3} \right]$$

x → y, z

$$\frac{\partial \ddot{x}}{\partial J} = -x \left[1 - 5 \left(\frac{z}{r} \right)^2 \right] \frac{GM_e R_e^2}{r^2 r^3}$$

x → y

$$\frac{\partial \ddot{z}}{\partial J} = -z \left[3 - 5 \left(\frac{z}{r} \right)^2 \right] \frac{GM_e R_e^2}{r^2 r^3}$$

$$\frac{\partial \ddot{x}}{\partial H} = x \left[7 \left(\frac{z}{r} \right)^2 - 3 \right] \frac{z}{r} \frac{GM_e R_e^3}{r^3 r^3}$$

x → y

$$\frac{\partial \ddot{z}}{\partial H} = \left[1 - 10 \left(\frac{z}{r} \right)^2 + \frac{35}{3} \left(\frac{z}{r} \right)^4 \right] \frac{3z}{5} \frac{GM_e R_e^3}{r^3 r^3}$$

$$\frac{\partial \ddot{x}}{\partial D} = -x \left[3 - 42 \left(\frac{z}{r} \right)^2 + 63 \left(\frac{z}{r} \right)^4 \right] \frac{GM_e R_e^4}{7r^3 r^4}$$

x → y

$$\frac{\partial \ddot{z}}{\partial D} = -z \left[15 - 70 \left(\frac{z}{r} \right)^2 + 63 \left(\frac{z}{r} \right)^4 \right] \frac{GM_e R_e^4}{7r^3 r^4}$$

$$\frac{\partial \ddot{x}}{\partial a_e} = \frac{1}{a_e} \sum_{k=1}^4 GM_k \left[x_k \left(\frac{1}{|r_k - r|^3} - \frac{1}{r_k^3} \right) - \frac{3(r^2 - r \cdot r_k)(x - x_k)}{|r_k - r|^5} \right] \quad x \rightarrow y, z$$

where

- k = 1 = Sun
- k = 2 = Venus
- k = 3 = Mars
- k = 4 = Jupiter

The partial derivatives of acceleration with respect to the attitude control effects are given by

$$\begin{bmatrix} \frac{\partial \ddot{x}}{\partial F_{AO}} & \frac{\partial \ddot{x}}{\partial F_{BO}} & \frac{\partial \ddot{x}}{\partial F_{CO}} \\ \frac{\partial \ddot{y}}{\partial F_{AO}} & & \vdots \\ \frac{\partial \ddot{z}}{\partial F_{AO}} & \dots & \frac{\partial \ddot{z}}{\partial F_{CO}} \end{bmatrix} = \frac{10^{-8}}{m} \begin{bmatrix} A_x & B_x & C_x \\ A_y & B_y & C_y \\ A_z & B_z & C_z \end{bmatrix}$$

where the unit vectors along the three body fixed axes are defined by

$$\bar{A} = \frac{-\bar{H}(\bar{E} \cdot \bar{H}) + \bar{E}}{|\bar{H}(\bar{E} \cdot \bar{H}) - \bar{E}|} = A_x, A_y, A_z$$

$$\bar{B} = \frac{\bar{E} \times \bar{H}}{|\bar{E} \times \bar{H}|} = B_x, B_y, B_z$$

$$\bar{C} = -\bar{H} = C_x, C_y, C_z$$

and

$\bar{E} = E_x, E_y, E_z$ = Unit vector directed from the probe toward Canopus

$\bar{H} = H_x, H_y, H_z$ = Unit vector directed from the probe toward the Sun

USE

8-4 of 4

CALL BMATRX

The subroutine checks lists in the COMMON area to determine what is required.

CODING INFORMATION

Length of subroutine is 794(10) or 1432(8) words.

REFERENCES

- a. Anderson, John D., RFP 312-37, August 29, 1961.
- b. Null, George W., RFP 312-179, Addendum 3, December 11, 1963.

IDENTIFICATION

9-1 of 2

CALL

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

CALL serves as the logical control routine for the data fitting link, LA6. All steps from reading the ODG data file through computation of partials and residuals to writing the residual file are initiated by this routine.

RESTRICTIONS

a. COMMON break: 46711

b. Subroutines called:

BEER

KINE

COEF

STARP

(DFSB)

REAP

CHADP

DOPLR

COROP

CORR

DICOS

OBTOX

CATS

OFFSYS

WAIT

QUIZ

REJEC

PM360

FORM

GERTA/GREOF

FILL

USE

9-2 of 2

CALL CALL

COMMON input:

IGNAZ data type delete flags (12 × 15)
PTFD-30 data start and stop times
LLIST physical constants solve flags (11)
EPOCH ODP epoch, d. p. sec past 1950.0
THETAI station longitude, deg
SIGX3 rejection sigmas (12 × 15)
DXDR-27 occultation-impact data flag

COMMON output:

HAO observed hour angle from observed optical right ascension
RVECD residual array
TOBL previous observation time

CODING INFORMATION

Length of subroutine is 339 (10) or 528 (8) words.

IDENTIFICATION

10-1 of 5

CATS

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

CATS computes the partials of the ODP data types with respect to the station locations. Such a partial may be non-zero only if the tracking datum is from the same station as the specified station location.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines called:
 - VEC
 - ABDD
 - COS

METHOD

$$\left. \begin{aligned} X_i &= R_i \cos(a_G + \lambda_i) \cos \phi_i \\ Y_i &= R_i \sin(a_G + \lambda_i) \cos \phi_i \\ Z_i &= R_i \sin \phi_i \end{aligned} \right\} \text{(station coordinates)}$$

$$\frac{\partial \rho_i}{\partial R_i} = \frac{1}{R_i} (\underline{R}_i \cdot \underline{L})$$

$$\frac{\partial \rho_i}{\partial \phi_i} = Z_i \left\{ [L_x \cos(a_G + \lambda_i) + L_y \sin(a_G + \lambda_i)] - L_z R_i \cos \phi_i \right\} \left. \vphantom{\frac{\partial \rho_i}{\partial \phi_i}} \right\} \text{(slant range partials)}$$

$$\frac{\partial \rho_i}{\partial \lambda_i} = Y_i L_x - X_i L_y$$

where

10-2 of 5

$$\underline{L} = \frac{\rho + r_s}{\rho}$$

λ_i = station longitude

ϕ_i = station geocentric latitude

R_i = station Earth radius

$$\frac{\partial \dot{\rho}_i}{\partial R_i} = \frac{1}{R_i} (R_i \cdot \underline{L}')$$

$$\frac{\partial \dot{\rho}_i}{\partial \phi_i} = -Z_i \left\{ [L'_x \cos(a_G + \lambda_i) + L'_y \sin(a_G + \lambda_i)] + L'_z R_i \cos \phi_i \right\}$$

$$\frac{\partial \dot{\rho}_i}{\partial \lambda_i} = -Y_i L'_x + X_i L'_y$$

(range
rate
partials)

where

$$L'_x = \frac{1}{\rho_i} (-\dot{x} - 2\omega Y_i + \dot{\rho}_i L_x + \omega y)$$

$$L'_y = \frac{1}{\rho_i} (-\dot{y} + 2\omega X_i + \dot{\rho}_i L_y - \omega x)$$

$$L'_z = \frac{1}{\rho_i} (-\dot{z} + \rho_i L_z)$$

$$\frac{\partial \gamma_i}{\partial R_i} = \frac{-1}{R_i \rho_i} (R_i \cdot \underline{\tilde{D}})$$

$$\frac{\partial \gamma_i}{\partial \phi_i} = \frac{1}{\rho_i} \left\{ Z_i [\tilde{D}_x \cos(a_G + \lambda_i) + \tilde{D}_y \sin(a_G + \lambda_i)] - \tilde{D}_z R_i \cos \phi_i \right\}$$

$$\frac{\partial \gamma_i}{\partial \lambda_i} = \frac{1}{\rho_i} (Y_i \tilde{D}_x - X_i \tilde{D}_y)$$

(elevation
angle
partials)

$$\left. \begin{aligned} \frac{\partial \sigma_i}{\partial R_i} &= \frac{-1}{R_i \rho_i} (R_i \cdot \tilde{A}) \\ \frac{\partial \sigma_i}{\partial \phi_i} &= \frac{1}{\rho_i} \left\{ Z_i [\tilde{A}_x \cos(a_G + \lambda_i) + \tilde{A}_y \sin(a_G + \lambda_i)] - \tilde{A}_z R_i \cos \phi_i \right\} \\ \frac{\partial \sigma_i}{\partial \lambda_i} &= \frac{1}{\rho_i} (Y_i \tilde{A}_x - X_i \tilde{A}_y) \end{aligned} \right\} \begin{array}{l} 10-3 \text{ of } 5 \\ \\ \text{(azimuth} \\ \text{angle} \\ \text{partials)} \end{array}$$

$$\frac{\partial \gamma_i}{\partial S_i} (\tilde{D}) \rightarrow \frac{\partial \delta_i}{\partial S_i} (D) \quad \text{(declination partials)}$$

$$\frac{\partial \sigma_i}{\partial S_i} (\tilde{A}) \rightarrow \frac{\partial a_i}{\partial S_i} (A) \quad \text{(hour angle partials)}$$

where

$$D_x = -\sin \delta_i \cos(a_G + \lambda_i)$$

$$D_y = -\sin \delta_i \sin(a_G + \lambda_i)$$

$$D_z = \cos \delta_i$$

$$A_x = -\sin(a_G + \lambda_i)$$

$$A_y = \cos(a_G + \lambda_i)$$

$$A_z = 0$$

$$\begin{aligned} \tilde{D}_x &= \sin \gamma_i [\sin \sigma_i \sin(a_G + \lambda_i) + \cos \sigma_i \sin \phi_i \cos(a_G + \lambda_i)] \\ &\quad + \cos \phi_i \cos(a_G + \lambda_i) \cos \gamma_i \end{aligned}$$

$$\begin{aligned} \tilde{D}_y &= -\sin \gamma_i [\sin \sigma_i \cos(a_G + \lambda_i) - \cos \sigma_i \sin \phi_i \sin(a_G + \lambda_i)] \\ &\quad + \cos \phi_i \sin(a_G + \lambda_i) \cos \gamma_i \end{aligned}$$

$$\tilde{D}_z = -\cos \sigma_i \cos \phi_i \sin \gamma_i + \sin \phi_i \cos \gamma_i$$

10-4 of 5

$$\tilde{A}_x = -\cos \sigma_i \sin(\alpha_G + \lambda_i) + \sin \sigma_i \sin \phi_i \cos(\alpha_G + \lambda_i)$$

$$\tilde{A}_y = \cos \sigma_i \cos(\alpha_G + \lambda_i) + \sin \sigma_i \sin \phi_i \sin(\alpha_G + \lambda_i)$$

$$\tilde{A}_z = -\sin \sigma_i \cos \phi_i$$

The vectors \underline{A} , \underline{D} , $\tilde{\underline{A}}$, and $\tilde{\underline{D}}$, defined above, are computed by subroutine DICOS.

$$\frac{\partial f_{li}}{\partial S_i} = \frac{\Omega_2}{c} \frac{\partial \dot{\rho}_i}{\partial S_i} \quad (\text{one-way doppler partials})$$

$$\frac{\partial f_{c3i,q}}{\partial S_i} = \frac{\Omega_4}{c} \frac{\partial \dot{\rho}_i}{\partial S_i} \quad (\text{two-way doppler receiver partials})$$

$$\frac{\partial f_{3i,q}}{\partial S_i} = \frac{\Omega_6}{c} \frac{\partial \dot{\rho}_i}{\partial S_i} \quad (\text{three-way doppler receiver partials})$$

$$\frac{\partial f_{dli,j}}{\partial S_i} = \frac{\Omega_2}{c} \frac{\partial \dot{\rho}_i}{\partial S_i} \quad (\text{differenced one-way doppler receiver i partials})$$

$$\frac{\partial f_{c3i,q}}{\partial S_q} = \frac{\Omega_4}{c} \frac{\partial \dot{\rho}_q}{\partial S_q} \quad (\text{two-way doppler transmitter partials})$$

$$\frac{\partial f_{3i,q}}{\partial S_q} = \frac{\Omega_6}{c} \frac{\partial \dot{\rho}_q}{\partial S_q} \quad (\text{three-way doppler transmitter partials})$$

$$\frac{\partial f_{dli,j}}{\partial S_j} = \frac{\Omega_2}{c} \frac{\partial \dot{\rho}_j}{\partial S_j} \quad (\text{differenced one-way doppler receiver j partials})$$

where

Ω_2 = one-way multiplier

Ω_4 = two-way multiplier

Ω_6 = three-way multiplier

USE

10-5 of 5

CALL CATS

COMMON inputs:

RI R_i , km
 PHII ϕ_i , deg
 THETA I λ_i , deg
 GHA α_G , deg
 ELX \underline{L}
 AX \underline{A}
 DX \underline{D}
 TAX $\underline{\tilde{A}}$
 TDX $\underline{\tilde{D}}$
 RVEC ρ_i , km
 OMEGA ω , deg/sec
 X \underline{r} , km
 XDOT $\underline{\dot{r}}$, km/sec
 CZ2 Ω_2
 CZ4 Ω_4
 CZ6 Ω_6

COMMON output:

DIM3 partials $\frac{\partial F}{\partial S_i}$ (12 x 3 x 15)

CODING INFORMATION

Length of subroutine is 421 (10) or 645 (8) words.

REFERENCES

- a. Warner, M. R., Nead, M. W., Hudson, R. H., TM33-168, March 18, 1964.
- b. Anderson, John D., RFP 312-37, August 29, 1961.

IDENTIFICATION

11-1 of 5

COEF

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

COEF calculates the coefficients used by the ODP in doppler calculations. The subroutine is cognizant of band differences. All intermediate calculations are in double precision.

RESTRICTIONS

COMMON break: 47675

Subroutines used:

(DFAD)

(DFMP)

(DFSB)

QUIZ

METHOD

$$f_T = f_{T \text{ base}} + \Delta f_T \quad (\text{transponder frequency})$$

$$f_q = f_{q \text{ base}} + \Delta f_q \quad (\text{transmitter frequency})$$

$$\Omega_2 = \omega_2 [f_T + D(t_{ob} - t_0)]$$

$$\Omega_1 = \omega_1 + \Delta\omega_1 - \Omega_2$$

$$\Omega_4 = \omega_4 f_q$$

$$\Omega_3 = \omega_3 + \Delta\omega_3 \text{ for predicts} \quad \Omega_3 = 0 \text{ for data fitting}$$

$$\Omega_6 = \omega_6 f_q$$

$$\Omega_5 = \omega_5 + \Delta\omega_5 - \Omega_6 \text{ for predicts} \quad \Omega_5 = 0 \text{ for data fitting}$$

where for L to S band,

11-2 of 5

$$f_{T \text{ base}} = 2290.0 \times 10^6 \text{ cps}$$

$$f_{q \text{ base}} = 20.00 \times 10^6 \text{ cps}$$

$$k_1 = f_{q \text{ base}} + \Delta k_1$$

$$\omega_2 = 0.3125$$

$$\omega_1 = 9.375 \times 10^6 \text{ cps}$$

$$\omega_4 = 32.579185520$$

$$\omega_3 = 9.375 \times 10^6 \text{ cps}$$

$$\omega_6 = 32.579185520$$

$$\omega_5 = 9.375 \times 10^6 \text{ cps}$$

$$\Delta\omega_1 = 30 k_1$$

$$\Delta\omega_3 = 30 k_1$$

$$\Delta\omega_5 = 30 k_1$$

for L band,

$$f_{T \text{ base}} = 960.0 \times 10^6 \text{ cps}$$

$$f_{q \text{ base}} = 29.66 \times 10^6 \text{ cps}$$

$$\omega_2 = 0.96875$$

$$\omega_1 = 930.15 \times 10^6 \text{ cps}$$

$$\omega_4 = 32.359550561$$

11-3 of 5

$$\omega_3 = 100000. \text{ cps}$$

$$\omega_6 = 31.348314605$$

$$\omega_5 = 930.15 \times 10^6 \text{ cps}$$

$$\Delta\omega_1 = \Delta\omega_3 = \Delta\omega_5 = 0$$

for S band,

$$f_{T \text{ base}} = 2290.0 \times 10^6 \text{ cps}$$

$$f_{q \text{ base}} = 20.00 \times 10^6 \text{ cps}$$

$$k_s = f_{q \text{ base}} + \Delta k_s$$

$$\omega_2 = 1.0$$

$$\omega_1 = 1000000.$$

$$\omega_4 = 104.25339367$$

$$\omega_3 = 1000000.$$

$$\omega_6 = 104.25339367$$

$$\omega_5 = 1000000.$$

$$\Delta\omega_1 = \omega_6 k_s$$

$$\Delta\omega_3 = 0$$

$$\Delta\omega_5 =$$

also

11-4 of 5

D = transponder (beacon) drift

t_{ob} = observation time

t_0 = ODP epoch

USE

CALL COEF

COMMON input:

EP-6 band indication
 EP-7 Δk_1 , cps
 EP-8 Δk_s , cps
 TXCON 6×15 array of $\omega_1, \omega_2, \dots, \omega_6$ coefficients for each station, d. p.
 TFREQ Δf_T , cps
 XFREQ Δf_q , cps
 DXDR-4 D , cps/sec
 TOB observation time, d. p. sec past 1950.0
 EPOCH ODP epoch, d. p. sec past 1950.0
 C10 observed one-way doppler (flag)
 CD10 observed differenced one-way doppler (flag)
 CC30 observed two-way doppler (flag)
 C30 observed three-way doppler (flag)
 CD30 observed DSIF ranging (flag)

COMMON output:

CZ1 Ω_1
 CZ2 Ω_2
 CZ3 Ω_3
 CZ4 Ω_4
 CZ5 Ω_5
 CZ6 Ω_6
 RNJ Ω_5 , d. p.
 PHINJ Ω_6 , d. p.

CODING INFORMATION

11-5 of 5

Length of subroutine is 503 (10) or 767 (8) words.

REFERENCES

- a. Warner, M. R., Nead, M. W., Hudson, R. H., TM 33-168, March 18, 1964.
- b. Wollenhaupt, Wilber R., RFP 312-268, April 16, 1964.
- c. Wollenhaupt, Wilber R., RFP 312-319, September 3, 1964.

IDENTIFICATION

12-1 of 3

COL

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

COL calculates the G^2 terms in the weighting function

$$\sigma_j^2 = \sum_{p=1}^6 S_{pjk}^2 G_{pj}^2 \max\left(\frac{t_{pjk}}{\tau}, 1\right)$$

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:
 - COS
 - SQRT

METHOD

The computation of the g value depends on the value of the weight code group (p) and the data type (j). The following table indicates the g term for each of the p, j combinations:

| P Group index | | 1 | 2 | 3 | 4 | 5 | 6 |
|-----------------------|----|------------------------------------|--|--|--|---|----------------------|
| Data type index | j | | | | | | |
| ρ_i | 1 | 1 | 1 | $\dot{\rho}_i$ | ρ_i | $\Delta_r \rho_i$ | 1 |
| $\dot{\rho}_i$ | 2 | 1 | ρ_i | ρ_i | $\Delta_r \dot{\rho}_i$ | 1 | |
| γ_i | 3 | 1 | 1 | 1 | $\Delta_r \gamma_i$ | | |
| σ_i | 4 | $\frac{1}{\cos \gamma_i}$ | 1 | 1 | | | |
| δ_i | 5 | 1 | 1 | 1 | $\Delta_r \delta_i$ | | |
| a_i | 6 | $\frac{1}{\cos \delta_i}$ | 1 | 1 | $\Delta_r a_i$ | | |
| f_{li} | 7 | Ω_2 | Ω_2 | $\frac{1}{r}$ | $\frac{\Omega_2}{c}$ | | |
| f_{c3i} | 8 | $\frac{\Omega_4}{c}$ | $\frac{1}{r}$ | $\frac{\Omega_4}{c} \frac{(\rho_i + \rho_q)}{2}$ | $\frac{1}{\sqrt{3r}}$ | $\frac{\Omega_4}{rc} (\Delta_r \dot{\rho}_i + \Delta_r \dot{\rho}_q)$ | $\frac{\Omega_4}{c}$ |
| f_{3i} | 9 | $\frac{\Omega_6}{c}$ | $\frac{1}{r}$ | Ω_6 | $\frac{\Omega_6}{c} (\Delta_r \dot{\rho}_i + \Delta_r \dot{\rho}_q)$ | $\frac{\Omega_6}{c}$ | |
| f_{dli} | 10 | $\frac{\Omega_2}{c} \rho_i \rho_j$ | $\frac{\Omega_2}{c} (\rho_i - \rho_j)$ | $\frac{1}{r}$ | $\frac{\Omega_2}{c} (\Delta_r \dot{\rho}_i + \Delta_r \dot{\rho}_j)$ | $\frac{\Omega_2}{c}$ | |
| ρ_{DSIF} | 11 | 1 | 1 | $\dot{\rho}$ | ρ | $\Delta_r \rho$ | 1 |

where

12-3 of 3

ρ = slant range
 $\dot{\rho}$ = range rate
 γ = elevation angle
 δ = declination
 $\Delta_r \rho$ = refraction correction to slant range
 $\Delta_r \dot{\rho}$ = refraction correction to range rate
 $\Delta_r \delta$ = refraction correction to declination
 $\Delta_r a$ = refraction correction to hour angle
 Ω_2 = one-way doppler multiplier
 Ω_4 = two-way doppler multiplier
 Ω_6 = three-way doppler multiplier
 τ = doppler averaging time
 c = velocity of light

USE

CALL COL

COMMON input:

RVEC ρ , km
 RDOT $\dot{\rho}$, km/sec
 EL γ , deg
 DEC δ , deg
 DRVEC $\Delta_r \rho$, km
 DRDOT $\Delta_r \dot{\rho}$, km/sec
 DRDEC $\Delta_r \delta$, deg
 DRHA $\Delta_r a$, deg
 CZ2 Ω_2
 CZ4 Ω_4
 CZ6 Ω_6
 TAU τ , sec
 VELC c , km/sec

COMMON output:

GSQ $g^2 (1 \times 6)$

CODING INFORMATION

Length of subroutine is 262 (10) or 406 (8) words

IDENTIFICATION

13

COMAP

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

COMAP checks the mapping requests which are made of the ODP. When step-mapping the product of the U matrices for mapping is computed, thus the U matrix which is used in the calculation of the closest approach parameters is:

$$U = U_{IMP} * U_{T_N} * \dots * U_{T_2} * U_{T_1}$$

where U_{T_N} are the matrices computed for each step-map time and U_{IMP} is evaluated at time of closest approach. Results of the mapping matrix calculations are stored on disk to be printed in a subsequent link.

RESTRICTIONS

- a. ERROR condition: disk error indicated by $DC_{\bar{r}}$
- b. COMMON break: 47055
- c. Subroutines used:

TAMP
PROM
REAM
COMIMP
FLAK
FLOT
DCP
OFFSYS
TYPRYT

USE

This link is called under control of the JPTRAJ Source Deck.

CODING INFORMATION

Length of subroutine is 186(10) or 272(8) words.

IDENTIFICATION

14-1 of 2

COMIMP

Melba W. Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

To project the statistical information contained in the covariance matrix $\Gamma(t_0)$ to any later time.

RESTRICTIONS

a. COMMON break: 47055

b. Subroutines used:

MAMUL

PRAMS

(DFAD)

(DFSB)

(DFMP)

METHOD

The procedure employs a mapping matrix

$$U_{t_0, t} = \frac{\partial Q_t}{\partial Q_{t_0}}$$

which is an extended matrix of variational partials representing all estimated parameters Q_{t_0} . If the parameter set Q_{t_0} consists only of the six initial conditions, then this matrix is identical to the familiar U matrix. A similar mapping matrix is employed for including the effect of the considered parameter set \tilde{Q}_{t_0} :

$$V_{t_0, t} = \frac{\partial Q_t}{\partial \tilde{Q}_{t_0}}$$

The mapping operation is then accomplished by

$$\Gamma_t = U \Gamma_{t_0} U^T - V \Gamma_{\tilde{Q}} V^T J^{-1} U^T - U J^{-1} V \Gamma_{\tilde{Q}} V^T + V \Gamma_{\tilde{Q}} V^T$$

If no parameters are being considered, this reduces to

14-2 of 2

$$\Gamma_t = U\Gamma_{t_0}U^T$$

The covariance matrix of estimated parameters is defined as

$$\Gamma = J^{-1} + J^{-1}KJ^{-1}$$

where

$$J^{-1} = (J^* + \tilde{\Gamma}^{-1})^{-1}$$

and

$$K = v\Gamma_{\tilde{Q}}v^T$$

where

$\Gamma_{\tilde{Q}}$ = a priori covariance matrix of the m considered parameters

$$v = \sum_{i=1}^N \phi_i w_i^{-1} \theta_i^T \quad (\theta_i \text{ is the analogous vector of partials of considered parameters})$$

USE

CALL COMIMP

The matrix thus generated is used in the calculation of the target centered covariance matrix (TACCOM) and the closest approach parameters.

CODING INFORMATION

Length of subroutine is 750(10) or 1356(8) words.

REFERENCE

Anderson, John D., RFP 312-37, August 29, 1961.

IDENTIFICATION

15

COMOUT

Michael R. Warner, JPL

IMB 7094 Fap

January 4, 1965

PURPOSE

COMOUT writes the midcourse and trajectory information on the COMENT region of disk.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:
 COMENT

USE

CALL COMOUT

COMMON input:

- EP-63 midcourse COMENT buffer (29 words forward)
- EP-104 trajectory COMENT buffer (17 words forward)

CODING INFORMATION

Length of subroutine is 14(10) or 16(8) words.

IDENTIFICATION

16-1 of 2

COROP

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

COROP computes the refraction corrections to optically obtained hour angle and declination.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

SQRT

EXP(3)

ARTAN

SIN

METHOD

$$\Delta_r \gamma = \tan^{-1} \left(\frac{A}{\rho - B} \right) \quad (\text{correction to elevation angle})$$

where

$$A = \frac{0.00211}{(\gamma/57.2957795 + 0.0598)^{2.42}}$$

$$B = \sqrt{C^2 - R_e^2 + R_e^2 \sin^2 \gamma} - R_e \sin \gamma$$

$$C = R_e + 51.2064$$

ρ = slant range

R_e = earth equatorial radius

The program then uses $\Delta_r \gamma$ to obtain $\Delta_r \alpha$ and $\Delta_r \delta$ in the same manner as subroutine CORR (q. v.).

USE

16-2 of 2

CALL COROP

COMMON input:

RVEC ρ , km

EL γ , deg

RE R_e , km

COMMON output:

DHA $\Delta_r \alpha$, deg

DDEC $\Delta_r \delta$, deg

CODING INFORMATION

Length of subroutine is 120(10) or 170(8) words.

REFERENCES

- a. Warner, M. R., Nead, M. W., Hudson, R. H., TM 33-168, March 18, 1964.
- b. Cain, Dan L., TM 312-275, February 14, 1963.

IDENTIFICATION

17-1 of 3

CORR

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

CORR calculates the refraction corrections and the vertical displacements for angular tracking data.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines called:

SIN

SQRT

METHOD

$$\Delta_r \gamma = 57.2957795 \frac{n}{340.0} b_1 b_2 \quad \gamma < 0.3 \text{ radians}$$

$$\Delta_r \gamma = 57.2957795 n \times 10^{-6} \frac{\cos \gamma}{\sin \gamma} \quad \gamma \geq 0.3 \text{ radians}$$

$$\Delta_r \alpha = \frac{\Delta_r \gamma \cos \phi \sin^2 \alpha}{\cos^2 \gamma \sin \sigma} \quad \delta < 87^\circ$$

$$\Delta_r \delta = \frac{(\sin \phi \cos \gamma - \sin \gamma \cos \phi \cos \sigma) \Delta_r \gamma}{\cos \delta} \quad \delta < 87^\circ$$

$$\Delta_r \alpha = \Delta_r \delta = 0 \quad \delta \geq 87^\circ$$

$$b_1 = 1.0 - (1.216 \times 10^5 b_3 \gamma_{\text{rad}}) - (51.0 - 300.0 \gamma_{\text{rad}}) \sqrt{b_3}$$

$$b_2 = \left[7.0 \times 10^{-4} / (0.0589 + \gamma_{\text{rad}}) \right] - 1.26 \times 10^{-3}$$

$$b_3 = \frac{1}{10^3 (r - R_1)}$$

$$\Delta_v \alpha = \frac{v}{\cos \phi}$$

$$\Delta_v \gamma = u \cos \sigma$$

$$\Delta_v \sigma = u \sin \sigma \frac{\sin \gamma}{\cos \gamma}$$

$$\Delta_v \delta = 0$$

where

- γ = elevation angle ($\gamma_{\text{rad}} = \gamma$ in radians)
- σ = azimuth angle
- α = hour angle
- δ = declination
- Δ_r = refraction correction
- Δ_v = vertical correction
- n = index of refraction (nominally 340.0)
- ϕ = geocentric latitude of station
- r = geocentric probe distance
- R_i = Earth radius at station i
- u = north-south displacement of vertical
- v = east-west displacement of vertical

USE

CALL CORR

COMMON input:

SINEL $\sin \gamma$
 IFA-9 $\neq 0$ to bypass Δ_r and Δ_v calculation
 EL γ
 ELZ $\sin \delta$
 X, Y, Z geocentric probe vector
 RI(i) Earth radius at station i
 FNI(i) index of refraction at station i
 COSEL $\cos \gamma$
 HA α
 COSPHI $\cos \phi$
 SINAZ $\sin \sigma$

COSAZ $\cos \sigma$
 UI(i) north-south displacement, station i
 VI(i) east-west displacement, station i

17-3 of 3

COMMON output:

DEL $\Delta_r \gamma + \Delta_v \gamma$
 DHA $\Delta_r a + \Delta_v a$
 DAZ $\Delta_v \sigma$
 DDEC $\Delta_r \delta$

CODING INFORMATION

Length of subroutine is 188(10) or 274(8) words.

REFERENCES

- a. Warner, M. R., Nead, M. W., Hudson, R. H., TM 33-168, March 18, 1964.
- b. Cain, Dan L., IOM to W. Hoover, July 6, 1960.
- c. Cain, Dan L., IOM to W. Hoover, October 4, 1960.

IDENTIFICATION

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CXPLOT/XXXFSR/CDC

John R. Schoeni, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

To generate on the computer plotting tapes to be displayed on the SC-4020 microfilm recorder. Controlled by a set of pseudo-operations, the routine will scale data, generate and label grid lines, and annotate the plotted information.

RESTRICTIONS

- a. ERROR return when incorrect calling sequence is given.
- b. Subroutine used:
IOCS

USE

CXPLOT uses IOCS to control I/O buffering and the user before calling CXPLOT must open a reserve file for the subroutine's use. In defining the buffer pool to be attached to the plotting file, it is recommended that at least two buffers of up to 200 words in length be assigned. The entry into CXPLOT is from a FAP calling sequence and consists of a call CXPLOT followed by pseudo-operations which specify the operations to be performed. The calling sequence is terminated by an error exit of the form, PZE A, where A is the location of the users error routine. Normal return is to the location following the error return. The following pseudo-operations are recognized.

| | | |
|---|---|---|
| <p>FVE N, T, D FVE O, O, O</p> | } | Selection of tape unit and indication of film advance |
| <p>SIX SX, L, SY SIX F, SIZE, D</p> | } | Printing horizontal titles |
| <p>SVN SX, L, Sy SVN F, SIZE, D</p> | } | Printing vertical titles |
| <p>PON Rx₀, Rx_n PON Ry₀, Ry_n PON n, e, p PON m, e, q PON Fx, Fy PON X₀, X_n PON Y₀, Y_n</p> | } | Generation and labelling of grid |

| | | |
|---|---|-----------|
| PTW Lx ₀ , EX, Ly ₀ } PTW N, A, CHAR } | Generation of graph | 18-2 of 6 |
| PTH X, t, Y | Generation of special grid line or form flash | |
| MZE O, t, N | Termination of plot | |
| PZE A, | Error return | |

CONTROL PSEUDO-OPERATIONS

FVE N, T, D

An FVE pseudo-operation must be the first pseudo-operation encountered in the first calling sequence to CXPLOT in a program because it causes various addresses throughout the subroutine to be initialized.

N In the FVE pseudo-operation, N indicates that every Nth point will be plotted.

N = 0 = 1

T T = 1 will cause a film advance command to be generated.

T = 0 indicates no frame advance.

D is the symbolic location of the File Control Block that has been opened for this file.

FVE O, O, O

A second FVE pseudo-operation is used when the output is to be written on the IBM 7094 using a packed format and high density tape mode. The plot tape generated by the use of this option requires processing on the 1401 before being plotted on the SC-4020. The Standard SFOF mode of operation is high density and packed.

MZE O, T, N

The MZE pseudo-operation gives information required to terminate a particular plot or set of plots.

If N is zero, the instruction is treated as a skip, and control will pass to the next pseudo-operation.

If N is non-zero, STOP PRINT and ADVANCE FRAME commands will be generated and written on the tape previously specified.

T not used.

PZE A

The PZE pseudo-operation indicates the end of the calling sequence. Normal exit is to the instruction following this pseudo-operation. "A" is the address of a user supplied error routine.

HORIZONTAL TITLES

18-3 of 6

SIX SX, L, SYSIX F, SIZE, D

The SIX pseudo-operations give information required for printing horizontal titles. The first operation in the pair describes where the title is to be located. The second operation tells the location of the format statement and the letter size. Six pseudo-operations must always occur in pairs.

L = 1 SX and SY designate the X and Y coordinates locating the center of the title.

L = 0 SX and SY designate the X and Y coordinates locating the position at which the first character of the title is to be centered.

F designates the location of the format statement to be used for the title. The format statement starting at location F must be of the form

(xHyz -----).

x an integer indicating the number of hollerith characters which follow the H.

y if blank the current frame will be used. This is the normal case.

y if equal to 1, a film advance command is generated before printing this title.

z is always a blank character.

SIZE designates the letter size and may have the values 0, 1, 2, 3 specifying that letters of 1, 2, 4, or 8 times normal size are to be used. (Caution: a character 8 times normal size is 64 by 128 units in size.)

D When printing normal size letters, SIZE is zero, D indicates whether the letters will be generated by the vector generator or by the plotting matrix.

D = 0: plotting matrix.

D = 1: vector generator.

VERTICAL TITLES

SVN SX, L, SYSVN F, SIZE, D

The SVN pseudo-operations give information required for printing titles vertically. They are analogous to the SIX pseudo-operations in format.

GRIDS & LABELS

PON

The PON pseudo-operations specify the grid lines to be drawn, the exposure to be used in drawing them, the formats to control their labelling and the scaling to be used in the plot.

The first five PON pseudo-operations must be used as a group.

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PON Rx_0, Rx_n
 PON Ry_0, Ry_n
 PON n, e, p
 PON m, e, q
 PON Fx, Fy

PON Rx_0, Rx_n

Rx_0 is the location of the lower end of the range of x values.

Rx_n is the location of the upper end of the range of x values.

The limits for the range will be in floating point form.

PON Ry_0, Ry_n

is analogous to the PON Rx_0, Rx_n for the range of y.

PON n, e, p

contains an integer n specifying the number of uniform intervals in the x-direction (vertical grids) to be bounded by grid lines, and an integer p indicating that the first grid line and every pth grid line following will be labelled. If e = 1, the labelled grid lines will be drawn heavy; otherwise they will be light (vertical grids).

PON m, e, q

This is analogous to the third PON but refers to the y-direction (horizontal grids).

PON Fx, Fy

contains the locations of format statements to be used in labelling the horizontal and vertical grid lines, respectively. These should be of the form:

FX BCI , (F c. d),

where

F indicates that a conversion from a floating point number to fixed point number should be performed, and that the fixed point number should be printed.

c designates the "column width." ($c \leq 9$)

d designates the number of digits to be retained to the right of the decimal point.
 $d < (c-1)$

PON X_0, X_n

PON Y_0, Y_n

The sixth and seventh PON pseudo-operations specify the area of the character on surface (1023 x 1023) to be used for plotting. These two PON pseudo-operations may be omitted, and if so the standard case of

PON 96,, 992
 PON 0,, 896

18-5 of 6

will be assumed by the subroutine.

PON X₀, , X_n

is the range of the horizontal positions to be used

$$(0 \leq X_0 < X_n \leq 1023).$$

PON Y₀, , Y_n

contains the range of vertical positions to be used for the graph

$$(0 \leq Y_0 < Y_n \leq 1023).$$

GENERATION OF GRAPH

PTW Lx₀, EX, Ly₀

PTW N, A, CHAR

The PTW pseudo-operations specify the character and the exposure to be used in plotting, the memory area containing the sets of (x, y) values to be plotted, and the scaling factors to be used.

Lx₀ designates the starting memory location for the sequence of values of x to be plotted.

Ly₀ designates the starting location for the corresponding values of y.

N designates the number of pairs of values of x and y to be plotted.

Thus, locations Lx₀ to Lx₀+N - 1 contain the values of x corresponding to the values of y found in locations Ly₀ to Ly₀+N - 1.

Note the special case where the data are in x, y pairs. N is the number of x and y values, and the address of the FVE pseudo-operation is set to 2. The same type of logic applies to triplets, etc.

EX designates the exposure to be used in plotting. If EX = 0, the exposure will be heavy; otherwise, the light mode will be used.

A=0 The scaling factors computed from the previous set of PON pseudo-operations will be used.

A≠0 The four locations following the pair of PTW instructions should contain the location of floating point values of a, b, c, and d in that order.

For each pair of values, x, y, a corresponding pair of coordinates (X, Y) is computed by the subroutine as follows:

$$X = ax + b$$

$$Y = cy + d$$

where

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a, b, c and d are the scaling parameters. They depend upon the range of coordinates to be used when plotting the range of values specified.

If, in scaling, a point is either $0 > X > 1024$ or $0 > Y > 1024$, the point is discarded.

CHAR The Hollerith character to be used for the plot is given in the six bit positions 30 to 35 of location CHAR.

JOINING POINTS BY VECTORS

If the character specified is the space the vector generator will be used for the plot, and successive points will be connected using straight line segments.

PTH X, t, Y

The PTH pseudo-operation allows the programmer two options: one to draw grid lines directly in either the x or y direction, and one to control usage of the form flash.

t = 0 A horizontal grid line will be drawn beginning at X, Y and extending to the right edge of the frame.

t = 1 A vertical grid line will be drawn from X, Y to the upper edge of the frame.

t = 4 A form flash command will be generated. Care must be taken not to generate more than one form flash on the same plot.

CODING INFORMATION

Length of subroutine is 1744(10) or 3320(8) words.

IDENTIFICATION

19-1 of 2

DATAPE

Melba W. Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

To generate a simulated data file for checking and for study programs.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

IXTAB
 OFFSYS
 (DFAD)
 TIMER
 LOOKUP
 INTR1
 GHADP
 COEF
 DOPLR
 CORR
 ND2F
 FILT

Types of doppler are limited as follows:

If IX (transmitter) = 0, C3 and CC3 are zero.

If IX ≠ 0, IR (receiver) ≠ IX, C1 and CC3 are zero.

If IX ≠ 0, IR = IX, C1 and C3 are zero.

METHOD

Data identified under the control card DATA TAPE SIGMA will be included on the file.

Weights for each data type must be included under WEIGHTS BY DATA TYPE AND STATION. The equation for the computation of the data value in the file is:

$$R(I) = R_c(I) + \Delta R(I) + F(I, IR) * A + B(I, IR)$$

where

R(I) = the array of data where I references the data type

R_c(I) = calculated value of the data point

$\Delta R(I)$ = correction on calculated value

19-2 of 2

$F(I, IR)$ = noise factor on data by type and station. This provided by setting the data type under DATA TAPE SIGMA to a floating point number.

A = random number

$B(I, IR)$ = bias. Obtained by value under DATA TAPE BIAS according type.

Data is calculated by the same routines employed in the fitting of data.

USE

CALL DATAPE

CODING INFORMATION

Length of subroutine is 301(10) or 455(8) words.

IDENTIFICATION

20

DECOD

Michael R. Warner, JPL
 IBM 7094 Fap
 January 4, 1965

PURPOSE

DECOD determines the group value for the given group number of the weight code word. This word consists of six 3-bit groups from bit 5 through bit 17. Each group may have a value from 0 through 7. DECOD also floats the data sample rate, which occupies the address portion of the weight code word.

RESTRICTION

COMMON break: 47675

USE

CALL DECOD

PZE J group number

PZE K group value

COMMON input:

RVECW weight code array (1 × 11)

ID data type identification

COMMON output:

TS sample rate, sec.

CODING INFORMATION

Length of subroutine is 32 (10) or 40 (8) words.

IDENTIFICATION

21

DIAG/DIAGO

Melba W. Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

To compute standard deviation of the mapped forward covariance matrix or standard deviation of input covariance matrix.

RESTRICTIONS

- a. COMMON break: 47675
- b. Each subroutine computes the square root of the diagonal of a specific matrix.
- c. Subroutines used:
 SQRT

USE

CALL DIAG Standard deviation of input covariance matrix

CALL DIAGO Standard deviation of mapped forward covariance matrix

CODING INFORMATION

Length of each subroutine is 105 (10) or 151 (8) words.

IDENTIFICATION

22

DICOS

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

DICOS computes the direction cosine vectors \underline{A} , \underline{D} , $\tilde{\underline{A}}$, and $\tilde{\underline{D}}$, which are defined in the documentation of subroutine CATS.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:
SIN/COS

USE

CALL DICOS

COMMON input:

| | |
|--------|-------------------|
| DEC | δ , deg |
| GHA | α_G , deg |
| THETA1 | λ_1 , deg |
| EL | γ , deg |
| AZI | σ , deg |
| PHI1 | ϕ_1 , deg |

COMMON output:

| | |
|-----|-------------------------|
| AX | \underline{A} |
| DX | \underline{D} |
| TAX | $\tilde{\underline{A}}$ |
| TDX | $\tilde{\underline{D}}$ |

CODING INFORMATION

Length of subroutine is 123 (10) or 173 (8) words.

IDENTIFICATION

23-1 of 4

(DISCBU) REDE/RITE/PISA
Charles Coltharp, JPL
IBM 7094 Fap
January 4, 1965

PURPOSE

DISCBU provides elementary buffering for reading and writing scratch information on disk.

RESTRICTIONS

Subroutines used:
DCP

METHOD

DISCBU uses DCP for reading and writing the disk. All physical records are 200 words in length. Each logical record is preceded on the disk by a control word,

PZE O, ,L

where L is the number of words in the logical record. L may be zero, but L will never be greater than 200.

A control word of

MZE O, ,O

denotes a logical end of file.

USE

| | | | |
|----------|------|---------|--------|
| To write | CALL | RITE | |
| | PZE | FILE, , | ERREOF |
| | IOXY | A, , | N |

To read CALL REDE
PZE FILE,, ERREOF
IOXY A,, N
.
.
.

23-2 of 4

A is the location into which information is read, or from which it is written.

TCH, transfer in channel, will be recognized by both read and write operations.

The tag portion of all IO commands is ignored.

The address and decrement portions of IOCD commands are ignored.

Closed or unopened files are opened automatically by the first read or write operation requested.

Read Operation

- IOCD Rewind file; close file. When IOCD is used it must be the only command in the command list.
- IOCP Read N words, ignoring logical record marks, and proceed to next command. If this command precisely finishes a record, the logical end of record may be recognized by the next command.
- IOCT Read N words, ignoring logical record marks, and terminate IO. Unread words in a partially read record will be lost.
- IORP Read to logical record mark (read one whole record, or finish a record already started), and proceed to next command. Put number of words read into the decrement portion of the IORP command. N is not interpreted.
- IORT Same as IORP, but terminate IO.
- IOSP Same as IORP if the number of words in the record is less than or equal to N. Otherwise, transmission is stopped after N words have been read. Unread words in this record will be lost. Control proceeds to the next command.
- IOST Same as IOSP, but terminate IO.

Write Operation

- IOCD Write logical EOF, rewind file; close file. When IOCD is used it must be the only command in the command list.
- IOCP Write N words, and proceed to next command.
- IOCT Write N words followed by a logical record mark, and terminate IO
- IORP Write N words followed by a logical record mark, and proceed to next command.

IORT Same as IOCT.

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IOSP Same as IORP.

IOST Same as IORT.

If at any time in writing, a record reaches a length of 200 words before a logical record mark is indicated by the user, DISCBU will insert a logical record mark before continuing the transmission.

File Block

```
FILE  BCI  1,  XXXXXX
      +1  PZE  J  (decrement = P)
      +2  PZE  K  (decrement = Q)
      +3  PZE  BUFFER  (decrement = R)
      +4  PZE  200
```

XXXXXX an entry in the disk directory, defined as scratch

J that record in XXXXXX with which this file begins

K that record in XXXXXX with which this file ends

BUFFER the location of a 400 word block of core storage

The decrements of FILE +1 through FILE +3 (the items in parentheses, above) will be used by DISCBU for bookkeeping. These items will be zero when the file is not open, and they should be set zero initially by the user.

P last disk record transmitted

Q buffer designation

0 = next disk transmission will be from (or into) BUFFER + 0

1 = next disk transmission will be from (or into) BUFFER + 200

R location of next word in BUFFER to be read or written.

FILE +4 is the location given to DCP for the flag word. Initially this must be a positive, non-zero number.

Error - End of File Return

Control is returned to ERREOF under the conditions described below.

If an error is indicated by DCP, that indication will be in the AC on return. The error codes are described in the design specifications for DCP.

If the user tries to exceed the self-imposed file bounds (K is the largest usable disk record in XXXXXX), the AC on return will be MZE 0,0,-1.

No provision is made for continuing if the condition occurs on a read operation.

Before the file may be used again, the user must issue the sequence

```
CALL  REDE
PZE  FILE,,  ERREOF
IOCD
```

to close and rewind the file.

23-4 of 4

If the condition occurs on a write operation, the user may continue, provided all seven index registers are preserved, by executing

TRA $\$PISA$.

However, K should be increased if the user wishes to read the material back at a later time.

If a logical EOF is encountered by a read operation, the AC will be plus zero.

CODING INFORMATION

Length of subroutine is 273 (10) or 421 (8) words.

IDENTIFICATION

24

DNAME

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

DNAME contains a list of the BCD names of the eleven ODP data types.

USE

The BCD names, one per word, are stored backward. The entry point, DNAME, is assigned to the first logical location (last physical location).

CODING INFORMATION

Length of subroutine is 12 (10) or 14 (8) words.

IDENTIFICATION

25-1 of 5

DOPLR
 Michael R. Warner, JPL
 Fortran II, Version 3
 January 4, 1965

PURPOSE

DOPLR obtains the calculated values of the ODP data types.

RESTRICTIONS

COMMON break: 47675

Subroutines called:

ABDD
 ARSIN
 ARTAN
 DMOD
 RATES
 SQRT
 VEC
 (DFAD)
 (DFMP)

METHOD

DOPLR first obtains the fine light-time correction in a two-iteration procedure:

$$\epsilon = 0$$

$$\underline{r}_t = \underline{r}_t' + \epsilon \underline{\dot{r}}_t'$$

$$\underline{\dot{r}}_t = \underline{\dot{r}}_t' + \epsilon \underline{\ddot{r}}_t'$$

$$\underline{\ddot{r}}_t = \underline{\ddot{r}}_t' + \epsilon \underline{\overset{\cdot\cdot}{r}}_t'$$

$$\underline{\overset{\cdot\cdot}{r}}_t = \underline{\overset{\cdot\cdot}{r}}_t'$$

$$\Delta t = \frac{\rho + \Delta t' \dot{\rho}}{C + \dot{\rho}}$$

$\epsilon = \Delta t' - \Delta t$; the procedure is then repeated.

where

25-2 of 5

$\Delta t'$ = coarse correction from subroutine TIMER

t' = $t_{ob} - \Delta t'$

ρ = slant range at t'

$\dot{\rho}$ = range rate at t'

c = speed of light

The eleven ODP data types are then obtained. DOPLR calls subroutine RATES to obtain slant range and its derivatives and all other leg-dependent quantities:

$$\rho = \left| \underline{r}_t - \underline{R}_{it_{ob}} \right| \quad (\text{slant range})$$

where

\underline{r} = geocentric position vector of probe

\underline{R}_i = geocentric position vector of station i

$$\dot{\rho} = \frac{\underline{\rho} \cdot \dot{\underline{\rho}}}{\rho} \quad (\text{range rate})$$

where

$\underline{\rho}$ = topocentric position vector of probe

$\dot{\underline{\rho}}$ = topocentric velocity vector of probe

$$\gamma = \sin^{-1} \frac{\underline{R}_i \cdot \underline{L}}{R_i} \quad (\text{elevation angle})$$

where

$$\underline{L} = \frac{\underline{\rho} + \underline{r}_s}{\rho}$$

R_i = Earth radius at station i

\underline{r}_s = geocentric position vector of Sun

$$\sigma = \tan^{-1} \frac{\sin \gamma}{\cos \gamma} \quad (\text{azimuth angle}).$$

where

25-3 of 5

$$\sin \sigma = \frac{L_y \cos(a_G + \lambda_i) - L_x \sin(a_G + \lambda_i)}{\cos \lambda_i}$$

$$\cos \sigma = \frac{-L_x \sin \phi_i \cos(a_G + \lambda_i) - L_y \sin(a_G + \lambda_i) \sin \phi_i + L_z \cos \phi_i}{\cos \gamma_i}$$

a_G = Greenwich hour angle

λ_i = longitude of station i

ϕ_i = geocentric latitude of station i

$$a = a_G + \lambda_i - \tan^{-1} \left(\frac{\rho_y}{\rho_x} \right) \quad (\text{hour angle})$$

$$\delta = \sin^{-1} L_z \quad (\text{declination})$$

$$f_1 = \Omega_1 + \Omega_2 \phi_1 \quad (\text{one-way integrated doppler frequency})$$

$$f_{c3} = \Omega_3 + \Omega_4 \phi_3 \quad (\text{coherent three-way integrated doppler frequency})$$

$$f_3 = \Omega_5 + \Omega_6 \phi_3 \quad (\text{three-way integrated doppler frequency})$$

where

$\Omega_1, \Omega_2, \dots, \Omega_6$ are defined in COEF writeup.

$$\phi_1 = \frac{\dot{\rho}_i}{c} - \frac{1}{c^2} h_1 - \frac{\ddot{\rho}_i}{c} \frac{\tau^2}{24}$$

$$\phi_3 = \frac{1}{c} (\dot{\rho}_i + \dot{\rho}_q) - \frac{1}{c^2} h_3 - \frac{1}{c} (\ddot{\rho}_i + \ddot{\rho}_q) \frac{\tau^2}{24}$$

τ = doppler counting interval

q = transmitter index

i = receiver index

$$h_1 = \frac{\dot{\rho}}{\rho} \underline{\rho} \cdot (\underline{r} - \underline{r}_s) + \frac{1}{2} \left(\dot{R}_{it_{ob}} - \dot{r}_t^2 \right)$$

$$h_3 = \dot{\rho}_i^2 + \dot{\rho}_q \dot{\rho}_i + \frac{\dot{\rho}_i}{\rho_i} \underline{\rho}_i \cdot \left(\dot{R}_{it_{ob}} - \dot{r}_{st} \right)$$

$$- \frac{\dot{\rho}_q}{\rho_q} \underline{\rho}_q \cdot \left(\dot{R}_{qt_{tr}} - \dot{r}_{st} \right) + \frac{1}{2} \left(\dot{R}_{it_{ob}}^2 - \dot{R}_{qt_{tr}}^2 \right)$$

$$f_{dl} = f_{li} - f_{lj} \quad \text{(differenced one-way doppler from stations i and j)}$$

where f_{li} and f_{lj} are one-way doppler values which must be taken simultaneously at stations i and j

$$\rho_{DSIF} = \frac{\Omega_6(\rho_q + \rho_i)}{16c} + \epsilon \quad \text{(DSIF ranging)}$$

where

ϵ = ranging system bias

USE

CALL DOPLR

COMMON input:

| | |
|----------------|---|
| DELTA | Δt^1 , d. p. sec past 1950.0 |
| X | $\underline{r}(1 \times 3)$, km |
| XDOT | $\underline{\dot{r}}(1 \times 3)$, km/sec |
| XAC | $\underline{\ddot{r}}(1 \times 3)$, km/sec ² |
| XJERK | $\underline{\dddot{r}}(1 \times 3)$, km/sec ³ |
| VELC | c, km/sec |
| CZ1, . . . CZ6 | $\Omega_1, \dots, \Omega_6$ |
| RVECO | observed values of ODP data types (1 x 11) |
| OMEGA | Earth rotation rate, deg/sec |

COMMON output:

| | |
|--------|--|
| RVEC | calculated values of ODP data types (1 x 11) |
| DELTA2 | Δt , d. p. sec past 1950.0 |

CODING INFORMATION

25-5 of 5

Length of subroutine is 715 (10) or 1313 (8) words.

REFERENCE

Warner, M. R., Nead, M. W., Hudson, R. H., TM 33-168, March 18, 1964.

IDENTIFICATION

26-1 of 2

ENDIT

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

ENDIT sets up and solves the normal equations. The covariance matrix

$$\Gamma = J^{-1} + J^{-1} KJ^{-1}$$

is obtained from the matrices accumulated by subroutine FORM. The ΔQ vector is retained for subsequent output.

RESTRICTIONS

COMMON break: 47675

Subroutines used:

(DFSB)/(DFMP)/(DFAD)

PRIM

SQRT

STPREG

REVRT

NOUT

METHOD

The matrix inversion is accomplished by subroutine STPREG (q.v.).

USE

CALL ENDIT

COMMON input:

KLST attitude control estimate flags

FABC attitude control coefficients

| | | |
|-------|---------------------------------------|-----------|
| ILIST | initial conditions estimate flags | 26-2 of 2 |
| XNJ | initial conditions | |
| LLIST | physical constants estimate flags | |
| GRAVE | physical constants | |
| MLIST | velocity of light estimate flag | |
| VELC | velocity of light | |
| NLIST | station locations estimate flags | |
| RI | station locations | |
| GFLIP | a priori Γ^{-1} | |
| QTILD | nominal values corresponding to QTILD | |
| NEST | number of estimated parameters | |
| NCON | number of considered parameters | |
| RIGHT | accumulated right-hand side | |
| XJ | accumulated normal matrix | |
| SOUR | sum of squares | |
| NTOT | number of data points | |
| XX | accumulated consider matrix | |
| XMU | accumulated consider vector | |

COMMON output: .

| | |
|-------|------------------------|
| QNU | updated parameter list |
| RIGHT | ΔQ vector |
| XJ | J inverse |
| CPGAM | covariance matrix |
| XNJ | } updated parameters |
| GRAVE | |
| RI | |
| FABC | |
| CAPQ | Q sum of squares |

CODING INFORMATION

Length of subroutine is 828 (10) or 1474 (8) words.

IDENTIFICATION

27

EPPHEM

Melba W. Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

To prepare an ephemeris tape with complete information required from the planetary ephemeris and the probe ephemeris for each time point of the ODP. This program checks the requirements of each iteration and interpolates and if necessary integrates the partials of the physical constants. The information is written on tape A-4.

RESTRICTIONS

a. COMMON break: 47055

b. Subroutines used:

GAMAT

LOOKUP

RITEM

TOCIM

INTR1

PONT

STARP

WREOF

KINE

QUIZ

TIMER

(DFSB)

METHOD

EPPHEM is primarily a logical decision box, which accomplishes its task through the use of subroutines. A flow chart is given to supply further clarification.

USE

CALL EPPHEM

CODING INFORMATION

Length of subroutine is 361 (10) or 551 (8) words.

IDENTIFICATION

28-1 of 2

ERROR

Michael R. Warner, JPL
 IBM 7094 Fap
 January 4, 1965

PURPOSE

ERROR prints ODP error condition messages. There are three versions of this subroutine in the ODP; the version in link LA9 prints recoverable error condition messages, the version in link LA12 prints unrecoverable error messages, and the version in the other links stores the calling sequence for subsequent action by LA12.

RESTRICTIONS

COMMON break: 47675
 Subroutines used: (LA9)
 TYPRYT
 ONLIN
 Subroutines used: (LA12)
 TYPRYT
 PROUT
 ENDSYS
 RECOV

USE

CALL ERROR
 PZE I }
 PZE J } Decrement integers
 PZE K }

| <u>I</u> | <u>Error message</u> | <u>Version</u> |
|----------|--|----------------|
| 1 | INCORRECT RECORD NUMBER IN DISK CALLING SEQUENCE | LA12 |
| 2 | WEIGHT (J = ID) FOR STATION (K = IR) = 0 | LA12 |
| 3 | DISK STORAGE NOT ALLOCATED FOR THIS JOB | LA9 |

| | | |
|----|--|-----------|
| 4 | ESTIMATE OR CONSIDER LIST EXCEEDS 20 PARAMETERS | LA9 |
| 5 | NO INPUT RECEIVED WITHIN TIME LIMIT | LA9 |
| 6 | PROGRAM UNABLE TO READ/WRITE PROBE EPHEMERIS | LA12 |
| 7 | FIRST PROBE EPHEMERIS TIME GREATER THAN LOOKUP ARGUMENT | LA12 |
| 8 | LAST PROBE EPHEMERIS TIME LESS THAN LOOKUP ARGUMENT | LA12 |
| 9 | INJECTION CONDITION = 0 | LA9 |
| 10 | INPUT J MATRIX NOT N*N | LA9 |
| 11 | INADMISSIBLE SYMBOL OR DATA FIELD | LA9 |
| 12 | INPUT CONSIDER MATRIX NOT M*M | LA9 |
| 13 | POINTING TIME LESS THAN EPOCH + R/C | LA9 |
| 14 | MAPPING TIME LESS THAN EPOCH | LA9 |
| 15 | DISK TRANSMISSION ERROR | LA12, LA9 |
| 16 | DISK BUFFER ALLOCATION INSUFFICIENT | LA12 |
| 17 | PLANETARY EPHEMERIS ERROR | LA12 |
| 18 | DATA POINT OUT OF TIME SORT | LA12 |
| 19 | ERROR IN CXPLOT CALLING SEQUENCE | LA12 |
| 20 | ERROR IN DP SQRT SUBROUTINE | LA12, LA9 |
| 21 | LOOKUP TIME FAILS TO MATCH TIME ON EPHEMERIS TAPE | LA12 |

The second line of messages 1, 2, 3, 6, 7, 8, 15, 16, 17, 18, 19, 20, 21, is
RECOVERY IMPOSSIBLE. JOB ABORTED.

The second line of messages 4, 5, 9, 11, 13, 14, is
USER MUST CORRECT AND RELOAD INPUT DECK WITHIN 3 MINUTES.

The second line of messages 10, 12, is
CONDITION IGNORED. JOB WILL CONTINUE.

CODING INFORMATION

Length of the LA9 version is 286 (10) or 436 (8) words.

Length of the LA12 version is 326 (10) or 506 (8) words.

Length of the dummy version is 9 (10) or 11 (8) words.

IDENTIFICATION

29

FDATA

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

FDATA stores the nominal values of the S and T weighting tables in COMMON arrays SSQ and TL, respectively. The S values are squared prior to their storage in SSQ.

RESTRICTIONS

COMMON break: 47675

USE

CALL FDATA

CODING INFORMATION

Length of subroutine is 591 (10) or 1117 (8) words.

REFERENCE

Hamilton, Thomas W., Inter-Office Memorandum to M. Warner, June 1962.

IDENTIFICATION

30-1 of 2

FILL/FILT

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

FILL writes the ODP residual file on disk in the same physical format as the ODG-generated data file. It is also used to write the tracking predictions on disk for subsequent output. FILT writes a simulated ODG data file on disk. Both entries use the RITE entry of the buffered disk routine DISCBU.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:
 - RITE
 - PISA

USE

CALL FILL

PZE

CALL FILT

PZE

COMMON input:

| | |
|-------|--|
| TOB | time of observation, d. p. sec past 1950.0 |
| RVEC | array of computed data types (1 × 11) |
| RVECD | array of residuals (1 × 11) |
| RVECW | array of weights (1 × 11) |
| IF5 | ≠ 0 normal entry, = 0 end-of-file entry |
| EP-6 | band designation |
| XFREQ | transmitter frequency |
| TFREQ | transponder frequency |
| IR | receiver ID, B17 |
| IX | transmitter ID, B17 |
| TAU | doppler averaging time, sec |

COMMON output:

30-2 of 2

TAB-799 400 word output buffer for DISCBU

The disk logical record format is as follows:

| | | |
|------|--------|---|
| Word | 0 | word count (2N + 5, B17) or - 0 for EOF |
| | 1 | TOB |
| | 2 | TOB-1 |
| | 3 | XFREQ if IX \neq 0 TFREQ if IX = 0 |
| | 4 | 0 |
| | 5 | <u>bit</u> S 1 if L - S band 0 if L or S band |
| | | 1 1 if RVEC \neq 0 |
| | | 2 1 if RVEC - 1 \neq 0 |
| | | 3 1 if RVEC - 2 \neq 0 |
| | | · · |
| | | · · |
| | | · · |
| | 11 | 1 if RVEC - 10 \neq 0 |
| | 12-15 | not used |
| | 16 | 1 if L - S or S band 0 if L band |
| | 17 | not used |
| | 18-21 | IX |
| | 22-25 | IR |
| | 26-35 | TAU |
| | 6 | first member of RVEC which is non-zero |
| | 7 | <u>bits</u> S-17 RVECD corresponding to word 6 18-35 RVECW corresponding to word 6 |
| | 8 | second member of RVEC which is non-zero |
| | 9 | second RVECD - RVECW word |
| | | · |
| | | · |
| | | · |
| | 2N + 4 | Nth member of RVEC which is non-zero |
| | 2N + 5 | Nth RVECD - RVECW word |

CODING INFORMATION

Length of subroutine is 191 (10) or 277 (8) words.

IDENTIFICATION

31

FIRST

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

Main program for link 1 of SFOF-JPTRAJ version of the JPL Orbit Determination Program. FIRST clears COMMON and formats the rejection table on the disk.

RESTRICTIONS

- a. ERROR condition: disk error indicated by DCP
- b. COMMON break: 46711
- c. Subroutines used:
 - FDATA
 - NOMNL
 - FLAK
 - DISCBU

USE

Initiates ODP by clearing COMMON and calling subroutines to store the permanent or semi-permanent information. This link is called only once per "run" of the ODP.

CODING INFORMATION

Length of subroutine is 427 (10) or 653 (8) words.

IDENTIFICATION

32

FIT

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

Main program for link 6. The purpose of the routine is to control calculation of the observables and the linkage.

RESTRICTIONS

- a. ERROR condition: disk error indicated by DCP
- b. COMMON break: 46711
- c. Subroutines used:
 - CALL
 - OCIM
 - FLAK
 - DISCBU
 - TAPIO

USE

When fitting data, this link is called by the JPTRAJ monitor.

CODING INFORMATION

Length of subroutine is 476 (10) or 734 (8) words.

IDENTIFICATION

33

FLAT/FLAPR/FLAK

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

Subroutine to check the I/O activity flags.

RESTRICTIONS

a. ERROR exit to indicate disk I/O error

b. Subroutines used:

ERROR

TYPRYT

USE

| | |
|------------|-------------------------------|
| CALL FLAT | To check TAPIO flag |
| CALL FLAPR | To check PROUT flag |
| CALL FLAK | To identify disk error return |

CODING INFORMATION

Length of subroutine is 64 (10) or 100 (8) words.

REFERENCE

EPD - 125, Rev. 1, April 1, 1964

IDENTIFICATION

34-1 of 2

FORM

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

FORM sets up the column matrix of partials $\partial F/\partial Q$ and accumulates the normal matrix J.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:
 - PARLEY
 - (DFMP)/(DFAD)/(DFSB)
 - SQRT

METHOD

The partials $\partial F/\partial Q$ are obtained by the chain rule when Q is an initial condition or physical constant:

$$\frac{\partial F}{\partial Q} = \frac{\partial F}{\partial \underline{r}} \frac{\partial \underline{r}}{\partial Q}$$

If Q is the velocity of light or a station parameter, $\partial F/\partial Q$ are computed analytically and input to FORM.

USE

A = 1.0 to execute entire routine
 CALL FORM
 A = -1.0 to bypass chain rule section (occultation or impact time partials)
 CALL FORM

COMMON input:

RVECW weight for data type ID
 ID data type identification
 POBX partials $\partial F/\partial \underline{r}$ (6 × 12)
 GMAT partials $\partial \underline{r}/\partial q$ (6 × 11)
 U partials $\partial \underline{r}/\partial r_0$ (6 × 6)
 ILLIST initial conditions flags (6)
 LLLIST physical constants flags (11)

| | | |
|---------|--|-----------|
| MLIST | velocity of light flag (1) | 34-2 of 2 |
| NLIST | station locations flags (3 x 15) | |
| QA | partials $\partial F/\partial q$ from occultation-impact | |
| QB | partials $\partial F/\partial r_0$ from occultation-impact | |
| DRDC | partials $\partial F/\partial c$ | |
| DIM3 | partials $\partial F/\partial S_i$ | |
| NEST | number of estimated parameters | |
| NCON | number of considered parameters | |
| RVECD | residual, data type ID | |
| IF10 | phi vector output flag | |
| DXDR-13 | MMP output flag | |

COMMON output:

| | |
|-------|---|
| CPPHI | ordered partials $\partial F/\partial Q$ |
| CPTHT | ordered partials $\partial F/\partial \tilde{Q}$ (considered) |
| XJ | J matrix |
| RIGHT | right-hand side of normal equations |
| XX | J matrix for considered parameters |
| NTOT | number of data points |
| SOUR | sum of squares |

CODING INFORMATION

Length of subroutine is 566 (10) or 1066 (8) words.

IDENTIFICATION

35

G1G2

Melba W. Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

G1G2 computes the gravity equations g_1 and g_2 .

RESTRICTION

COMMON break: 47675

METHOD

$$g_1 = 1 + \left[3 - 42 \left(\frac{z}{r} \right)^2 + 63 \left(\frac{z}{r} \right)^4 \right] \left[\frac{D}{7} \left(\frac{R_e}{r} \right)^4 \right] + \left[H \left(\frac{R_e}{r} \right)^3 \right] \left[3 - 7 \left(\frac{z}{r} \right)^2 \right] \frac{z}{r}$$

$$+ \left[J \left(\frac{R_e}{r} \right)^2 \right] \left[1 - 5 \left(\frac{z}{r} \right)^2 \right]$$

$$g_2 = 1 + \left[15 - 70 \left(\frac{z}{r} \right)^2 + 63 \left(\frac{z}{r} \right)^4 \right] \left[\frac{D}{7} \left(\frac{R_e}{r} \right)^4 \right] - \left[H \left(\frac{R_e}{r} \right)^3 \right] \left[1 - 10 \left(\frac{z}{r} \right)^2 \right]$$

$$+ \frac{35}{3} \left(\frac{z}{r} \right)^4 \frac{3}{5} \frac{r}{z} + \left[J \left(\frac{R_e}{r} \right)^2 \right] \left[3 - 5 \left(\frac{z}{r} \right)^2 \right]$$

USE

CALL G1G2 (G1, G2) Results are stored in G1 and G2.

CODING INFORMATION

Length of subroutine is 182 (10) or 266 (8) words.

REFERENCE

Anderson, John D., TM 312-131, August 23, 1961.

IDENTIFICATION

36-1 of 4

GAMAT

Melba W. Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

To obtain the partials $\partial r/\partial q$ from the following integral using Simpson's rule:

$$\Upsilon(t) = U(t) \int_{t_0}^{t_U^{-1}} (t^*)B(t^*) dt^*$$

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

BMATRIX

INSPC

INTR1

LOOKUP

(DFAD)

(DFDP)

(DFMP)

(DFSB)

METHOD

The partials of acceleration with respect to physical constants $\partial \ddot{r}/\partial q$ are evaluated in BMATRIX. These partials are then numerically integrated to obtain $\partial r/\partial q$.

Using the acceleration partials as evaluated in BMATRIX, if

36-2 of 4

$$B = \left\{ \begin{array}{cccc} 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ \frac{\partial \ddot{x}}{\partial q_1} & \frac{\partial \ddot{x}}{\partial q_2} & \dots & \frac{\partial \ddot{x}}{\partial q_n} \\ \frac{\partial \ddot{y}}{\partial q_1} & \frac{\partial \ddot{y}}{\partial q_2} & \dots & \frac{\partial \ddot{y}}{\partial q_n} \\ \frac{\partial \ddot{z}}{\partial q_1} & \frac{\partial \ddot{z}}{\partial q_2} & \dots & \frac{\partial \ddot{z}}{\partial q_n} \end{array} \right\}$$

$$U = \left\{ \begin{array}{ccc} \frac{\partial x}{\partial x_0} & \dots & \frac{\partial x}{\partial z_0} \\ \frac{\partial y}{\partial x_0} & \dots & \frac{\partial y}{\partial z_0} \\ \frac{\partial z}{\partial x_0} & \dots & \frac{\partial z}{\partial z_0} \\ \frac{\partial \dot{x}}{\partial x_0} & \dots & \frac{\partial \dot{x}}{\partial z_0} \\ \frac{\partial \dot{y}}{\partial x_0} & \dots & \frac{\partial \dot{y}}{\partial z_0} \\ \frac{\partial \dot{z}}{\partial x_0} & \dots & \frac{\partial \dot{z}}{\partial z_0} \end{array} \right\}$$

and

36-3 of 4

$$r = \left\{ \begin{array}{ccc} \frac{\partial x}{\partial q_1} & \dots & \frac{\partial x}{\partial q_n} \\ \frac{\partial y}{\partial q_1} & \dots & \frac{\partial y}{\partial q_n} \\ \frac{\partial z}{\partial q_1} & \dots & \frac{\partial z}{\partial q_n} \\ \frac{\partial \dot{x}}{\partial q_1} & \dots & \frac{\partial \dot{x}}{\partial q_n} \\ \frac{\partial \dot{y}}{\partial q_1} & \dots & \frac{\partial \dot{y}}{\partial q_n} \\ \frac{\partial \dot{z}}{\partial q_1} & \dots & \frac{\partial \dot{z}}{\partial q_n} \end{array} \right\}$$

then the partials $\partial r/\partial q$ are obtained from the following integral using Simpson's method:

$$r(t) = U(t) \int_{t_0}^{t_U^{-1}} (t^*)B(t^*) dt^*$$

The Simpson procedure uses an integration step based on the data times; if no data times exist in the interval, the time steps employed in the trajectory integration are used. The inverse of the U matrix is obtained not by the usual numerical methods but by an inspection method as defined in the subroutine INSPC.

USE

CALL GAMAT Result of the integration is placed on the combined ephemeris tape for use as needed.

CODING INFORMATION

36-4 of 4

Length of subroutine is 369 (10) or 561 (8) words.

REFERENCE

Anderson, John D., RFP 312-37, August 29, 1961.

IDENTIFICATION

37

GERTA/GREOF

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

GERTA writes the partials $\partial F/\partial Q$ (the "phi vector") on the MMP output tape, B7-SYSUT9. Each set of partials is tagged by time, receiver, transmitter, and data type.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:
 WRITEB/ENDFIL
 FLAT

USE

CALL GERTA

CALL GREOF for end-of-file

COMMON input:

| | |
|-------|---|
| CPPHI | partials $\partial F/\partial Q$ (1 x 20) |
| TOB | time, d. p. sec past 1950.0 |
| IR | receiver ID |
| IX | transmitter ID |
| ID | data type ID |

CODING INFORMATION

Length of subroutine is 141 (10) or 215 (8) words.

IDENTIFICATION

38-1 of 2

GHADP

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

GHADP calculates the Greenwich hour angle for the time given in COMMON location TOB. Intermediate calculations are in double precision. Output is in COMMON location GHA.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

(DFDP)

(DFAD)

(DFMP)

(DFSB)

DMOD

COS

METHOD

$$\alpha_G = 100^\circ.0755426 + 0^\circ.985647346d + 2^\circ.9015 \\ \times 10^{-13} d^2 + \omega s + \Delta\lambda \cos \bar{\epsilon} \pmod{360^\circ}$$

where α_G = Greenwich hour angle

d = integer days past 1950.0

s = sec past 0^h of dth day

ω = Earth rotation rate

$\bar{\epsilon}$ = mean obliquity

$\Delta\lambda$ = nutation in longitude

The mean obliquity is given by

$$\bar{\epsilon} = 23^\circ.445759 - 0^\circ.1309404T - 0^\circ.88 \times 10^{-6} T^2 + 0^\circ.5 \times 10^{-6} T^3$$

where T = Julian centuries past 1950.0

USE

38-2 of 2

CALL GHADP

COMMON input:

TOB observation time, d. p. sec past 1950.0

OMEGA Earth rotation rate, deg/sec

DLO nutation in longitude, deg

COMMON output:

GHA Greenwich hour angle, deg

CODING INFORMATION

Length of subroutine is 208 (10) or 320 (8) words.

REFERENCE

Holdridge, D. B., TR 32-223, March 2, 1962.

IDENTIFICATION

39

IMPAR

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

IMPAR computes the partials of impact time with respect to the estimated and considered parameters.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

FORM

METHOD

$$\frac{\partial T_I}{\partial Q} = \frac{-1}{\underline{\rho} \cdot \underline{\dot{\rho}}} \left(\underline{\rho} \cdot \frac{\partial \underline{\rho}}{\partial Q} \right)$$

where

T_I = impact time

Q = parameter

$\underline{\rho}$ = target centered probe position

$\underline{\dot{\rho}}$ = target centered probe velocity

USE

CALL IMPAR

PZE XTAR geocentric target position and velocity

COMMON input:

X geocentric probe position and velocity (1 × 6)

U partials $\partial \underline{\rho} / \partial \mathbf{r}_0$ (6 × 6)

GMAT partials $\partial \underline{\rho} / \partial \mathbf{q}$ (6 × 11)

LLIST physical constants flags (11)

COMMON output:

QA partials $\partial T_I / \partial \mathbf{q}$ (1 × 11)

QB partials $\partial T_I / \partial \mathbf{r}_0$ (1 × 6)

CODING INFORMATION

Length of subroutine is 127 (10) or 177 (8) words.

IDENTIFICATION

40

INSPC

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

INSPC inverts the U matrix of variational partials by inspection.

RESTRICTIONS

COMMON break: 47675

METHOD

If the U matrix is partitioned

$$U = \begin{bmatrix} U_{11} & | & U_{12} \\ \hline U_{21} & | & U_{22} \end{bmatrix}$$

then its inverse may be written as

$$U^{-1} = \begin{bmatrix} U_{22}^T & | & -U_{12}^T \\ \hline -U_{21}^T & | & U_{11}^T \end{bmatrix}$$

USE

CALL INSPC

COMMON input:

U U matrix of variational partials (6 x 6)

COMMON output:

UINV U⁻¹

CODING INFORMATION

Length of subroutine is 200 (10) or 310 (8) words.

REFERENCE

Anderson, John D., TM 312-409, March 24, 1964.

IDENTIFICATION

41

INTR1/BNTR2

Alan D. Rosenberg and Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

This version of INTR1 uses the latest version of the JPL Ephemeris routines, EPHEM, to obtain the necessary planetary information. INTR1 adjusts this output so it matches output from the original INTR1 rotated to true of date for the ODP.

RESTRICTIONS

- a. Portions of the ODP COMMON storage must be made available to the routine. ERROR return for planetary ephemeris tape error.
- b. Subroutines used:
 - EPHEM
 - PNUT
 - ROT
 - ERROR

USE

- CALL BNTR2 Enter one time to set up blocks of storage necessary to EPHEM
- CALL INTR1 Time is used from COMMON

CODING INFORMATION

Length of subroutine is 2188 (10) or 4214 (8) words.

REFERENCES

- a. Holdridge, D. B., TR 32-223, Space Trajectories Program for the IBM 7090 Computer, March 2, 1962.
- b. Peabody, P. R., Scott, J. F., Orozco, E. G., TR 32-580, User's Description of JPL Ephemeris Tapes, March 2, 1964.

IDENTIFICATION

42

IXTAB

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

IXTAB does a lookup in the table of transmitter ID's and frequencies by means of a time argument.

RESTRICTION

COMMON break: 47675

USE

CALL IXTAB

PZE N

N is the location of a flag which is zero for the initialization entry and non-zero for the normal entry. The initialization entry returns the lookup pointer to the first point in the table.

COMMON input:

TOB lookup time, d.p. sec past 1950.0
 EPOCH ODP epoch, d.p. sec past 1950.0
 YY1 table of times, sec past epoch (1 × 90)
 YY1-90 table of transmitter ID's (1 × 90)
 YY1-180 table of frequencies (1 × 90)

COMMON output:

IX transmitter ID
 XFREQ transmitter frequency if IX ≠ 0
 TFREQ transponder frequency if IX ≠ 0

CODING INFORMATION

Length of subroutine is 54 (10) or 66 (8) words.

IDENTIFICATION

43-1 of 2

KINE

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

KINE reads the ODG data file or the ODP residual file from disk. Each entry loads COMMON with the contents of the next sequential logical record. KINE uses the REDE entry of the buffered disk routine DISCBU.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:
 - REDE
 - ERROR
- c. Error conditions:
 - Disk parity error
 - Attempted read outside of file limits

USE

| | | | | | |
|------|--------|------------------------------|-----|--------|----------------------------------|
| CALL | KINE | | | | |
| PZE | RVECO | } for ODG data reading | PZE | RVEC | } for ODP residual reading |
| PZE | RVECW | | PZE | RVECD | |
| PZE | = 1001 | | PZE | = 1 | |
| PZE | = 2000 | | PZE | = 1000 | |
| PZE | IF6 | 1B17 = EOF, 2B17 = normal | | | |

COMMON output:

| | |
|-------|---|
| TOB | observation time, d. p. sec past 1950.0 |
| RVEC | array of computed data types |
| RVECO | array of observed data types |
| RVECW | array of weight code-words |
| RVECD | array of residual-weight words |
| PASS | pass identification |
| XFREQ | transmitter frequency, cps |
| TFREQ | transponder frequency, cps |
| IR | receiver identification |
| IX | transmitter identification |
| TAU | doppler averaging time, sec |

The ODG logical record format is as follows:

43-2 of 2

| | | |
|-------------|-------|---|
| <u>Word</u> | 0 | word count (2N + 5, B17) or -0 for EOF |
| | 1 | TOB |
| | 2 | TOB - 1 |
| | 3 | XFREQ if IX \neq 0 TFREQ if IX \neq 0 |
| | 4 | PASS |
| | 5 | <u>bit</u> S 1 if L - S band 0 if L or S band |
| | | 1 1 if RVECO \neq 0 |
| | | 2 1 if RVECO - 1 \neq 0 |
| | | 3 1 if RVECO - 2 \neq 0 |
| | | . |
| | | . |
| | | . |
| | 11 | 1 |
| | 12-15 | not used |
| | 16 | 1 if L - S or S band 0 if L band |
| | 17 | 1 if optical data |
| | 18-21 | IX |
| | 22-25 | IR |
| | 26-35 | TAU. |
| | 6 | first member of RVECO which is non-zero |
| | 7 | <u>bits</u> S-17 weight codeword corresponding to word 6 18-35 data sample rate, sec |
| | 8 | second member of RVECO which is non-zero |
| | 9 | second weight-sample rate word |

2N + 4 Nth member of RVECO which is non-zero

2N + 5 Nth weight-sample rate word

The corresponding residual record format is found in the documentation of subroutine FILL.

CODING INFORMATION

Length of subroutine is 142 (10) or 216 (8) words.

IDENTIFICATION

44

LOCO

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

This is the control routine for the link which restores the ODP COMMON from disk following computation of the trajectory. In addition it controls preparation of the combined ephemeris on tape A4.

RESTRICTIONS

- a. ERROR condition: disk error indicated by DCP
- b. COMMON break: 47675
- c. Subroutines used:

KOOL

TAPIO

INTR1

EPPHEM

FLAK

TYPRYT

USE

This is one of the basic links of the ODP in that it restores COMMON and prepares the ephemeris. It is called under control of the JPTRAJ monitor.

CODING INFORMATION

Length of subroutine is 116 (10) or 164 (8) words.

IDENTIFICATION

45-1 of 2

LOOKUP/KOOL

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

To perform look-up on the probe ephemeris generated by SPACE.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

 ERROR Called when time incompatible with the ephemeris which has been generated.

 REDE

METHOD

The subroutine computes the coefficients for a 5th degree Lagrangian interpolation and provides values for the position, velocity, acceleration and jerk (3rd derivative) of the probe, variational equations, nutation in longitude and nutation in obliquity. (Flow chart is included)

$$y(x) = \sum_{k=0}^w l_k(x) f(x_k)$$

where

$$l_i(x) = \frac{\pi(x)}{(x - x_1) \pi'(x_1)}$$

$$= \frac{(x - x_0) \cdots (x - x_{i-1})(x - x_{i+1}) \cdots (x - x_n)}{(x_i - x_0) \cdots (x_i - x_{i-1})(x_i - x_{i+1}) \cdots (x_i - x_n)}$$

For each time that LOOKUP is called the following information is stored in COMMON

| | | |
|--|-----------------------|-----------------------------|
| X | } | Probe vector |
| Y | | |
| Z | | |
| XDOT | | |
| YDOT | | |
| ZDOT | } | (36) Variational equations |
| U | | |
| | | |
| $\partial x/\partial x_0, \partial x/\partial y_0, \partial x/\partial z_0, \partial x/\partial \dot{x}_0 \dots \partial z/\partial x_0 \dots \partial z/\partial \dot{z}_0$ | | |
| DLO | Nutation in longitude | |
| DOB | Nutation in obliquity | |
| XAC | } | Probe acceleration |
| YAC | | |
| ZAC | | |
| XJERK | } | Probe jerk (3rd derivative) |
| YJERK | | |
| ZJERK | | |

USE

CALL LOOKUP (n) n = number of items to be interpolated, 6 or 49. When 6, the probe vector only is given.

CALL KOOL to provide a logical reset on the probe ephemeris file and to set flag for LOOKUP to read 3 physical records needed on first entry to the subroutine.

CODING INFORMATION

Length of subroutine is 314 (10) or 472 (8) words.

REFERENCE

Hildebrand, F. B., Introduction to Numerical Analysis, McGraw-Hill, New York, 1956.

IDENTIFICATION

46

MAMUL

Melba W. Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

To multiply two matrices and store in a third array.

RESTRICTION

Maximum array: 20 x 20

USE

CALL MAMUL (A, B, C, M, N, L)
A(M, L) * B(L, N) = C (M, N)

CODING INFORMATION

Length of subroutine is 87 (10) or 127 (8) words.

IDENTIFICATION

47

MAPOUT

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

MAPOUT reads all matrices which were computed and stored on disk in Link 2. Here they are printed and in some cases punched. Also, the mapping information is saved for the MMP (MATRIX MANIPULATOR PROGRAM) input tape.

RESTRICTIONS

a. ERROR condition: disk error indicated by DCP

b. COMMON break: 47055

c. Subroutines used:

PRIM

FLAK

REFORM

PUMA

PRAM

DCP

IOCS

TYPRYT

OFFSYS

TACCOM

USE

This link is called under control of the JPTRAJ Source Deck.

CODING INFORMATION

Length of subroutine is 866 (10) or 1542 (8) words.

IDENTIFICATION

48

MAXIM

Melba Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

Checks data tape, mapping times, predictions, pointing times, etc. so that the trajectory can be run a minimum length of time and still satisfy all demands on the probe ephemeris.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

KINE

MOCT

QUIZ

(DFAD)

(DFSB)

METHOD

Flow chart is included.

USE

CALL MAXIM

CODING INFORMATION

Length of subroutine is 315 (10) or 473 (8) words.

IDENTIFICATION

49

MOCT

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

MOCT obtains the latest occultation or impact time for determining the trajectory link time stop.

RESTRICTION

COMMON break: 47675

USE

CALL MOCT

PZE LAST latest occultation/impact time, d. p. sec past 1950.0

COMMON input:

PTFD occultation/impact input area

DXDR-27 occultation/impact flag

CODING INFORMATION

Length of subroutine is 71 (10) or 107 (8) words.

IDENTIFICATION

50

ND2F

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

This is a SHARE routine which has been modified so that it is possible to start at a pre-determined portion of the random number generator.

RESTRICTION

COMMON break: 47675

METHOD

RANO, an octal number, can be input into the ODP data.

This number is chosen from a pre-calculated set.

USE

To provide noise on a simulated data tape.

CODING INFORMATION

Length of subroutine is 39 (10) or 47 (8) words.

IDENTIFICATION

51

NOMNL

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

NOMNL stores the nominal values of all constants, other than the weighting tables and the target-dependent solar pressure constants.

RESTRICTION

COMMON break: 47675

USE

CALL NOMNL

This subroutine outputs into approximately 150 COMMON locations.

CODING INFORMATION

Length of subroutine is 499 (10) or 1051 (8) words.

REFERENCES

- a. Clarke, Victor C., TR 32-604, March 6, 1964.
- b. Scott, James F., IOM 317.21/318, September 1, 1964.

IDENTIFICATION

52

NORMAY

Melba Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

To normalize a matrix on its diagonal terms.

RESTRICTIONS

- a. Maximum matrix: 20×20
- b. Subroutines used:

SQRT

USE

CALL NORMAY (XMAT, YMAT, N)

XMAT = matrix A to be normalized

YMAT = location to store normalized matrix

N = order of matrix

CODING INFORMATION

Length of subroutine is 169 (10) or 251 (8) words.

IDENTIFICATION

53

NOUT

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

NOUT prints comments indicating the rows and columns of the normal matrix which were deleted by subroutine STPREG during inversion:

VARIABLE NO. XX REJECTED BY DIAGONAL TEST.

RESTRICTION

Subroutines used:

PROUT

USE

CALL NOUT

PZE INOUT

INOUT is a 1×20 array in which STPREG has indicated the status of each variable.

COMMON input:

PRIFIL PROUT file control block for printing.

CODING INFORMATION

Length of subroutine is 64 (10) or 100 (8) words.

IDENTIFICATION

54-1 of 3

OBTOX

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

OBTOX computes the partials of the ODP data types with respect to the probe position and velocity at the observation time.

RESTRICTION

COMMON break: 47675

METHOD

$$\begin{array}{l}
 \frac{\partial \rho_i}{\partial \underline{x}} = \underline{L} \\
 \frac{\partial \rho_i}{\partial \underline{\dot{x}}} = 0 \\
 \frac{\partial \dot{\rho}_i}{\partial x} = \frac{1}{\rho_i} (\dot{x} + \omega y_1 - \dot{\rho}_i L_x) \\
 \frac{\partial \dot{\rho}_i}{\partial y} = \frac{1}{\rho_i} (\dot{y} - \omega x_1 - \dot{\rho}_i L_y) \\
 \frac{\partial \dot{\rho}_i}{\partial z} = \frac{1}{\rho_i} (\dot{z} - \dot{\rho}_i L_z) \\
 \frac{\partial \dot{\rho}_i}{\partial \underline{\dot{x}}} = \underline{L} \\
 \frac{\partial \gamma_i}{\partial \underline{x}} = \frac{\underline{D}}{\rho_i} \\
 \frac{\partial \gamma_i}{\partial \underline{\dot{x}}} = 0
 \end{array}
 \left. \begin{array}{l} \\ \\ \\ \\ \\ \\ \\ \\ \end{array} \right\}
 \begin{array}{l}
 \text{(slant range partials)} \\
 \\
 \text{(range rate partials)} \\
 \\
 \\
 \text{(elevation angle partials)}
 \end{array}$$

$$\left. \begin{aligned} \frac{\partial \sigma_i}{\partial \underline{r}} &= \frac{\tilde{A}}{\rho_i} \\ \frac{\partial \sigma_i}{\partial \underline{t}} &= 0 \end{aligned} \right\} \text{(azimuth angle partials)}$$

$$\left. \begin{aligned} \frac{\partial \delta_i}{\partial x} &= \frac{-\cos \alpha_{ri} \sin \delta_i}{\rho_i} \\ \frac{\partial \delta_i}{\partial y} &= \frac{-\sin \alpha_{ri} \sin \delta_i}{\rho_i} \\ \frac{\partial \delta_i}{\partial z} &= \frac{\cos \delta_i}{\rho_i} \\ \frac{\partial \delta_i}{\partial \underline{t}} &= 0 \end{aligned} \right\} \text{(declination partials)}$$

$$\left. \begin{aligned} \frac{\partial \alpha_i}{\partial x} &= \frac{\sin \alpha_{ri}}{\rho_i \cos \delta_i} \\ \frac{\partial \alpha_i}{\partial y} &= \frac{-\cos \alpha_{ri}}{\rho_i \cos \delta_i} \\ \frac{\partial \alpha_i}{\partial z} &= 0 \\ \frac{\partial \alpha_i}{\partial \underline{t}} &= 0 \end{aligned} \right\} \text{(hour angle partials)}$$

$$\frac{\partial f_{\underline{h}}}{\partial \underline{r}} = \frac{\Omega_2}{c} \frac{\partial \dot{\rho}_i}{\partial \underline{r}} \quad \underline{r} \rightarrow \underline{i} \quad \text{(one-way doppler partials)}$$

$$\frac{\partial f_{c3i,q}}{\partial \underline{r}} = \frac{\Omega_4}{c} \left(\frac{\partial \dot{\rho}_i}{\partial \underline{r}} + \frac{\partial \dot{\rho}_q}{\partial \underline{r}} \right) \quad \underline{r} \rightarrow \underline{i} \quad \text{(two-way doppler partials)}$$

$$\frac{\partial f_{3i,q}}{\partial \underline{r}} = \frac{\Omega_6}{c} \left(\frac{\partial \dot{\rho}_i}{\partial \underline{r}} + \frac{\partial \dot{\rho}_q}{\partial \underline{r}} \right) \quad \underline{r} \rightarrow \dot{\underline{r}} \quad (\text{three-way doppler partials})$$

$$\frac{\partial f_{d1i,j}}{\partial \underline{r}} = \frac{\Omega_2}{c} \left(\frac{\partial \dot{\rho}_i}{\partial \underline{r}} - \frac{\partial \dot{\rho}_j}{\partial \underline{r}} \right) \quad \underline{r} \rightarrow \dot{\underline{r}} \quad (\text{differenced one-way partials})$$

(all symbols used here are defined in the subroutine CATS documentation)

USE

CALL OBTOX

COMMON input:

ELX \underline{L}
 TAX $\underline{\tilde{A}}$
 TDX $\underline{\tilde{D}}$
 RVEC ODP computed data type array
 X $\underline{r}, \dot{\underline{r}}$
 OMEGA ω , deg/sec
 RAI α_{ri} , deg
 CZ2 Ω_2
 CZ4 Ω_4
 CZ6 Ω_6
 VELC c , km/sec

COMMON output:

POBX $\partial F / \partial \underline{r}, \partial F / \partial \dot{\underline{r}}$

CODING INFORMATION

Length of subroutine is 189 (10) or 275 (8) words.

REFERENCES

- a. Warner, M. R., Nead, M. W., Hudson, R. H., TM 33-168, March 18, 1964.
- b. Anderson, John D., TM 312-409, March 24, 1964.

IDENTIFICATION

55

OCIM

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

OCIM reads the ODP combined ephemeris tape, extracting occultation and impact time parameters necessary for partials calculation.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines called:

IMPAR

OCPAR

READB

FLAT

ERROR

c. Error conditions:

Ephemeris tape permanent redundancy

USE

CALL OCIM

COMMON input:

| | |
|---------|--|
| DXDR-6 | target (1 = Mars 2 = Moon 3 = Venus) |
| DXDR-27 | 1B17 = occultation time 2B17 = impact time |
| XMOO | geocentric Moon vector |
| XVEN | geocentric Venus vector |
| XMAR | geocentric Mars vector |
| PTFD | occultation-impact times input array |
| X | geocentric probe vector |
| XAC | geocentric probe accelerations |
| XJERK | geocentric probe jerks |
| RVECD | residual |
| RVECW | weight |
| DINT | physical constants partials |
| T | corrected occultation/impact time |

IDENTIFICATION

56-1 of 3

OCPAR

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

OCPAR computes the partials of occultation time with respect to the estimated and considered parameters.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

FORM

METHOD

$$\frac{\partial T_0}{\partial Q} = \frac{\rho \cdot \rho_m \left(\frac{\rho_m \cdot \frac{\partial \rho_m}{\partial Q}}{\rho_m^2} + \frac{\rho \cdot \frac{\partial \rho}{\partial Q}}{\rho^2} \right) - \rho \cdot \frac{\partial \rho_m}{\partial Q} - \rho_m \cdot \frac{\partial \rho}{\partial Q} + \frac{|\rho| |\rho_m| \sin \phi_p R_m}{\rho_m^2 \sqrt{\rho_m^2 - R_m^2}} \rho_m \cdot \frac{\partial \rho_m}{\partial Q}}{\rho \cdot \rho_m \left(\frac{\rho_m \cdot \dot{\rho}_m}{\rho_m^2} + \frac{\rho \cdot \dot{\rho}}{\rho^2} \right) - \rho \cdot \rho_m - \rho_m \cdot \rho + \frac{|\rho| |\rho_m| \sin \phi_p R_m}{\rho_m^2 \sqrt{\rho_m^2 - R_m^2}} (\rho_m \cdot \rho_m)}$$

where

$$\rho_m = r_m - R_i$$

R_m = radius of target

r_m = geocentric target vector

$$\phi_p = \cos^{-1} \frac{\underline{\rho} \cdot \underline{\rho}_m}{|\underline{\rho}| |\underline{\rho}_m|}$$

$\underline{\rho}$ = topocentric probe vector

\underline{R}_i = geocentric station vector

USE

CALL OCPAR

PZE XTAR \underline{r}_m , km

PZE AA $A = \underline{\Gamma} \cdot \underline{\dot{\Gamma}}$

PZE AB $B = \underline{\beta} \cdot \underline{\dot{\beta}}$

PZE AC $C = \sqrt{\Gamma^2 \beta^2 - (\underline{\Gamma} \cdot \underline{\beta})^2}$

PZE AK $K = \underline{\Gamma} \cdot \underline{\dot{\beta}} + \underline{\beta} \cdot \underline{\dot{\Gamma}}$

PZE AM $M = R_m C / \beta^2 \sqrt{\beta^2 - R_m^2}$

PZE GDB $\underline{\Gamma} \cdot \underline{\beta}$

PZE BETA $|\underline{\beta}|$ ($\underline{\beta} = \underline{\rho}_m$)

PZE GAMMA $|\underline{\Gamma}|$ ($\underline{\Gamma} = \underline{r} - \underline{R}_i$)

PZE XMX $\underline{\rho}_m \cdot \underline{r}$

PZE XXI $\underline{r} \cdot \underline{R}_i$

PZE SI \underline{R}_i

COMMON input:

U partials $\partial \rho / \partial \underline{r}_0$ (6 × 6)

GMAT partials $\partial \underline{\rho} / \partial \underline{q}$ (6 × 11)

LLIST physical constants flags (11)

RI $|\underline{R}_i|$, km

NLIST station locations flags (3 × 15)

COSRAI $\cos a_{ri}$

SINRAI $\sin a_{ri}$

COSPHI $\sin \phi_i$

COMMON output:

56-3 of 3

QA partials $\partial T_0 / \partial q$
QB partials $\partial T_0 / \partial \underline{r}_0$
DIM3 partials $\partial T_0 / \partial s_i$

CODING INFORMATION

Length of subroutine is 333 (10) or 515 (8) words.

REFERENCES

- a. Warner, M. R., Nead, M. W., Hudson, R. H., TM 33-168, March 18, 1964.
- b. Liu, Anthony, RFP 312-136, May 20, 1963.

IDENTIFICATION

57-1 of 2

ODATA/ONLIN/.....
 Michael R. Warner, JPL
 IBM 7094 Fap
 January 4, 1965

PURPOSE

ODATA performs the following functions:

- a. In conjunction with the conversion subroutine CARDS, reads ODP control cards and the symbolic and/or numeric data cards. The cards may be read from the on-line reader or input tape A2 (mode 4) or the user area reader (mode 2).
- b. Manipulates the symbolic and numeric data and stores them in the appropriate COMMON locations for subsequent ODP use.
- c. Under sense switch (or console key) control, terminates ODP execution.
- d. Prints the trajectory target on the administrative (or on-line) printer.
- e. Stores the target-dependent solar pressure constants.
- f. On option, reads the previously computed injection conditions, constants, and covariance matrix from disk.
- g. Applies Gauss' constraint to the planetary masses:

$$GM_s = 3.9640160 \times 10^{-14} a_e^3$$

$$GM_v = \frac{M_v}{M_s} GM_s$$

$$GM_r = \frac{M_r}{M_s} GM_s$$

$$GM_j = \frac{M_j}{M_s} GM_s$$

where

a_e = astronomical unit

s, v, r, j = subscripts denoting the Sun, Venus, Mars, Jupiter.

- h. On option, applies the scaling constraint to the Earth radius:

$$R_{em} = 86.315745 (GM_e + GM_m)^{1/3}$$

where

57-2 of 2

R_{em} = earth radius for scaling the lunar ephemeris.

RESTRICTIONS

- a. If any of the following error conditions are detected, ODATA calls subroutine ERROR for the appropriate comment printout and subsequent action:
 1. Error in symbolic or numeric input.
 2. Checksum or redundancy error.
 3. Cards not received within time limit (mode 2).
 4. Illegal card in deck (mode 2)
 5. End-of-file indication (mode 4)
 6. Data on input card inconsistent with ODP requirements.
 7. Error in reading disk.
- b. COMMON break: 47675
- c. Subroutines called:

TYPRYT
 IOCS - DEFINE/ATTACH/OPEN/CLOSE
 CARDS
 OFFSYS
 ERROR
 FINSYS
 READS/MOOPH1/ODOFF
 FLOT
 SPHX
 STPREG
 DIAG
 DISCBU - REDE
 EXP(3)

USE

CALL ODATA

ODATA uses most of the ODP COMMON map. Section IVB has the COMMON listing. The input descriptions are in Section IVA.

ONLIN is used for returning to ODATA after a corrected card input error (TTR \$ONLIN).

..... represents the entry point for the JPTRAJ program control block of LA9.

CODING INFORMATION

Length of subroutine is 1723 (10) or 3273 (8) words.

IDENTIFICATION

58

ORBEQ

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

ORBEQ rotates the encounter noise moment matrix from the ODP R, T plane to the midcourse program R, T plane.

RESTRICTIONS

a. COMMON break: 47055

b. Subroutines used

ARTAN

COS

SIN

METHOD

$$\theta = \tan^{-1} \frac{\underline{B} \cdot \underline{R}_{m/c}}{\underline{B} \cdot \underline{T}_{m/c}} - \tan^{-1} \frac{\underline{B} \cdot \underline{R}_{odp}}{\underline{B} \cdot \underline{T}_{odp}}$$

$$R = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

USE

CALL ORBEQ
 PZE BRO ODP B · R, km
 PZE BTO ODP B · T, km
 PZE BRM M/C B · T, km
 PZE BTM M/C B · T, km
 PZE CNO ODP noise moment matrix (6 × 6)
 PZE CNM M/C noise moment matrix (3 × 3)

CODING INFORMATION

Length of subroutine is 119 (10) or 167 (8) words.

IDENTIFICATION

59

OZ

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

OZ is the control program for the calculation of the closest approach parameters.

RESTRICTIONS

a. COMMON break: 47055

b. Subroutines used:

UMAT

TYPRYT

IOCS

OFFSYS

USE

When impact or closest approach parameters are requested, this link is called under control of the JPTRAJ Source Deck.

CODING INFORMATION

Length of subroutine is 766 (10) or 1376 (8) words.

IDENTIFICATION

60-1 of 2

PARAM

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

PARAM outputs the encounter parameters page of the ODP printout. It also loads the buffers for COMENT output.

RESTRICTIONS

- a. COMMON break: 47055
- b. Subroutines called:

SQRT
 FIXT
 PROUT
 TNORM
 ORBEQ

USE

CALL PARAM

PZE CNO noise moment matrix of encounter parameters (6×6)

PZE BRO $\underline{B} \cdot \underline{R}$, km (ODP plane)

PZE BTO $\underline{B} \cdot \underline{T}$, km (ODP plane)

PZE ELPS miss ellipse configuration (1×3 - semi-major axis, semi-minor axis, orientation angle)

PZE A semi-major axis of encounter conic

PZE UNJ $\partial M / \partial Q_0$ matrix of encounter partials

PZE TL linearized time of flight, days

PZE UT $\partial M / \partial Q$ matrix of encounter partials

COMMON input:

DXDR-6 target identification

DXDR-21 $\underline{B} \cdot \underline{R}$ (midcourse plane)

DXDR-20 $\underline{B} \cdot \underline{T}$ (midcourse plane)

DXDR-2 COMENT update flag

GRAVE GM_{Earth} , km^3/sec^2

GRAVR GM_{Mars}

GRAVV GM_{Venus}

| | | |
|--------|---|-----------|
| GRAVM | GM_{Moon} | 60-2 of 2 |
| GRAVS | GM_{Sun} | |
| TFIN | time of impact/closest approach, d.p. seconds past 1950.0 | |
| COMTS | ODP page heading, BCD | |
| PRIFIL | PROUT file control block | |
| XNJ | ODP initial conditions (1×6), d.p. | |
| EPOCH | ODP epoch, d.p. sec past 1950.0 | |
| XDOT | probe velocity at encounter, km/sec (1×3) | |

COMMON output:

| | |
|-------|--------------------------------------|
| COMBU | midcourse program COMENT parameters |
| COMBW | trajectory program COMENT parameters |

CODING INFORMATION

Length of subroutine is 720 (10) or 1320 (8) words.

IDENTIFICATION

61-1 of 2

PARLEY
 Melba W. Nead, JPL
 IBM 7094 Fap
 January 4, 1965

PURPOSE

To write time, partials, position and velocity of probe and planets, etc., on tape for each data point while the data is being processed.

RESTRICTIONS

- a. COMMON break: 47675
- b. Cannot be used in SFOF MODE 2 (real-time mode).
- c. Subroutines used:

FLAT
 TAPIO

USE

CALL PARLEY

The following items are written on a scratch tape to be read and printed in a subsequent link:

| | | |
|-------|------|-----------------------------|
| TOB | | Observation time |
| GHA | | Greenwich Hour Angle |
| X | } | Probe vector |
| Y | | |
| Z | | |
| XDOT | | |
| YDOT | | |
| ZDOT | | |
| U | (36) | Variational equations |
| DLO | | Nutation in longitude |
| DOB | | Nutation in obliquity |
| XAC | } | Probe Acceleration |
| YAC | | |
| ZAC | | |
| XJERK | } | Probe jerk (3rd derivative) |
| YJERK | | |
| ZJERK | | |
| XSUN | (6) | Sun vector |

| | | | | |
|-------|------|------------------------------|---------------------|-----------|
| XVEN | (6) | Venus vector | } XTARG vector only | 61-2 of 2 |
| XMOO | (6) | Moon vector | | |
| XMAR | (6) | Mars vector | | |
| CPPHI | (20) | CAP PHI matrix of partials | | |
| CPTHT | (20) | CAP THETA matrix of partials | | |
| DELT | | Light time correction | | |
| DELT2 | | Second light time correction | | |
| DHA | | } Refraction corrections | | |
| DDEC | | | | |
| DAZ | | | | |
| DEL | | | | |
| DRDOT | | | | |
| DRVEC | | | | |

CODING INFORMATION

Length of subroutine is 30 (10) or 36 (8) words.

REFERENCE

Null, George, W., RFP 312-179, August 15, 1963.

IDENTIFICATION

62

PARSH

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

This link is called only when the COMENT region is to be updated, or when in MODE 4, the printing of the partials is requested. The program is called under control of the JPTRAJ monitor.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutine used:

COMOUT

WASH

FGDOUT

DISCBU

USE

Control program for writing COMENT on disk or printing partials.

CODING INFORMATION

Length of subroutine is 662 (10) or 1226 (8) words.

IDENTIFICATION

63

PERNOD/WOLF

Charles Coltharp/Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

PERNOD accumulates statistics on data residuals. It is called during the processing of each residual. WOLF is called at the end-of-file for each station's residuals. It obtains the standard deviation, root-mean-square, mean, and second moment for each data type and each pass identification.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:

FIXT

PROUT/FGDOUT

SQRT

COLA

USE

CALL PERNOD after each residual is read

CALL WOLF after each station is completed

COMMON input:

TOB observation time, d. p. seconds past 1950.0

RVECD residual array (1 × 11)

ITNO iteration number

PASS pass identification

IR receives identification

PRIFIL IOCS printing file control block

CODING INFORMATION

Length of subroutine is 323 (10) or 503 (8) words.

IDENTIFICATION

64

PM360

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

PM360 adjusts angle residuals by 360 deg if they are greater than 180 deg or less than -180 deg.

RESTRICTIONS

COMMON break: 47675

USE

CALL PM360

COMMON input:

DECD declination residual

HAD hour angle residual

AZID azimuth residual

COMMON output:

DECD }
HAD } residuals adjusted by 360 deg if necessary
AZID }

CODING INFORMATION

Length of subroutine is 40 (10) or 50 (8) words.

IDENTIFICATION

65-1 of 2

PNUT

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

PNUT calculates the rotation matrix for nutation-precession.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

SIN

COS

METHOD

$$N = \begin{bmatrix} 1 & -\Delta\lambda \cos \bar{\epsilon} & -\Delta\lambda \sin \bar{\epsilon} \\ \Delta\lambda \cos \bar{\epsilon} & 1 & -\Delta\epsilon \\ \Delta\lambda \sin \bar{\epsilon} & \Delta\epsilon & 1 \end{bmatrix}$$

$$a_{11} = 1 - 0.29697 \times 10^{-3} T^2 - 0.13 \times 10^{-6} T^3$$

$$a_{12} = -0.02234988T - 0.676 \times 10^{-5} T^2 + 0.221 \times 10^{-5} T^3$$

$$a_{13} = -0.00971711T + 0.207 \times 10^{-5} T^2 + 0.96 \times 10^{-6} T^3$$

$$a_{21} = -a_{12}$$

$$a_{22} = 1 - 0.24976 \times 10^{-3} T^2 - 0.15 \times 10^{-6} T^3$$

$$a_{23} = -0.10859 \times 10^{-3} T^2 - 0.3 \times 10^{-7} T^3$$

$$a_{31} = -a_{13}$$

$$a_{32} = a_{23}$$

65-2 of 2

$$a_{33} = 1 - 0.4721 \times 10^{-4} T^2 + 0.2 \times 10^{-7} T^3$$

where

$\Delta\lambda$ = nutation in longitude

$\Delta\epsilon$ = nutation in obliquity

$\bar{\epsilon}$ = mean obliquity (see writeup for GHADP)

T = Julian centuries past 1950.0

USE

CALL PNUT

COMMON input:

T time, d.p. sec past 1950.0

DOB nutation in obliquity, deg

DLO nutation in longitude, deg

COMMON output:

ROTMX nutation-precession matrix (NA)

CODING INFORMATION

Length of subroutine is 222 (10) or 336 (9) words.

REFERENCE

Holdridge, D. B., TR 32-223, March 2, 1962.

IDENTIFICATION

66

POINT

Melba W. Nead, JPL
Fortran II, Version 3
January 4, 1965

PURPOSE

To generate the pointing predictions for the tracking stations.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:

- COEF
- FILL
- OFFSYS
- CORR
- GHADP
- REAP
- DOPLR
- IXTAB
- (DFAD)

USE

CALL POINT

CODING INFORMATION

Length of subroutine is 196 (10) or 304 (8) words.

REFERENCE

Trask, D.W., RFP 312-37, Addendum 6, April 4, 1962.

IDENTIFICATION

67

PONT

Melba W. Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

To compute the times at which the combined ephemeris shall be written for a simulated data tape or predictions.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

GAMAT

INTR1

LOOKUP

OFFSYS

RITEM

TIMER

(DFAD)

Flow chart included

USE

CALL PONT

CODING INFORMATION

Length of subroutine is 201 (10) or 311 (8) words.

IDENTIFICATION

68

PRAMS

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

To save the U matrix when it is calculated by COMIMP. Core space forces the calculation and the print-out of these matrices to be done in separate links.

RESTRICTIONS

a. ERROR condition: disk error indicated by DCP

b. Subroutines used:

FLAK

DCP

USE

CALL PRAMS

CODING INFORMATION

Length of subroutine is 18 (10) or 22 (8) words. —

IDENTIFICATION

69

PREDA

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

This is the main program of the link which computes predictions for the DSIF stations or prepares a simulated data tape.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:

POINT
DATAPE
TYPRYT
TAPIO

USE

This link is called under control of the JPTRAJ Source Deck when predictions or a data tape are requested.

CODING INFORMATION

Length of subroutine is 39 (10) or 47 (8) words.

IDENTIFICATION

70-1 of 2

PRIM/PRAM

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

To print any matrix up to 20×20 from a possible list of 63. Included is the capability of punching the array in a format acceptable as input back into the ODP. When step-mapping, probe position and velocity and the mapping matrix are automatically punched.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:

BIBCD
FLAPR
PRIME
NORMAY
PRIT
DIAGO
FGDOUT
PROUT

USE

CALL PRIM
PZE , , N

where N is as follows:

1. Input J matrix of estimated parameters
2. Input covariance matrix of considered parameters
3. J inverse
4. Covariance matrix of estimated parameters
5. Correlation matrix of estimated parameters
6. Covariance matrix at impact
7. Covariance matrix mapped forward
8. J matrix
9. Input covariance matrix of estimated parameters
10. Correlations based on J matrix
11. U product matrix in step-mapping

CALL PRAM
TSX CAPU

70-2 of 2

Prints U matrix for mapping forward

To punch a matrix PUNCH=n under OTHER PARAMETER VALUES in the data input. This will punch the matrix only one time.

CODING INFORMATION

Length of subroutine is 787 (10) or 1423 (8) words.

REFERENCE

Trask, D.W., REP 312-37, Addendum 6, April 4, 1962.

IDENTIFICATION

71

PRIME/REFORM

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

To write impact times, probe and target vectors and the mapping matrices on the MATRIX MANIPULATOR PROGRAM input tape.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:

TAPIO

FLAT

USE

CALL REFORM To read mapping times from preliminary storage tape. TFIN is added to those originally saved and all are written on the final MMP tape.

CALL PRIME To write the mapping matrices on the MMP tape.____

CODING INFORMATION

Length of subroutine is 98 (10) or 142 (8) words.

REFERENCE

Peterson, G. E., ED 218, May 15, 1964.

IDENTIFICATION

72

PRINQ/PRIT/APRIOR

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

To print DQ's, new Q's, old Q's, standard deviation of covariance matrix of estimated parameters, etc.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:

FGDOUT

DIAG

CLOCK

PROUT

FLAPR

FIXT

BIBCD

USE

| | |
|------------|---|
| CALL PRINQ | Prints DQ's etc. of estimated parameter. |
| CALL PRIT | Entered with double precision time in seconds in ACC and MQ. These are converted to year, month, day, hour, minute, second, and stored in COMMON. |
| APRIOR | Buffer in which the standard deviation of the aprior covariance matrix is stored through the "WANT" capability of the JPTRAJ monitor. |

CODING INFORMATION

Length of subroutine is 259 (10) or 403 (8) words.

REFERENCE

Trask, D.W., RFP 312-37, Addendum 6, April 4, 1962.

IDENTIFICATION

73

PRINT

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

PRINT controls the printing of the DQ's and the matrices which have been computed in the preceding link. Also, when occultation calculations are requested it reads this information from disk and prepares it for printing.

RESTRICTIONS

- a. ERROR condition: disk error indicated by DCP
- b. COMMON break: 47675
- c. Subroutines used:

- PRINQ
- PRIM
- FIXT
- PROUT
- FGDOUT
- FLAK
- DISCBU
- IOCS
- ENDIT
- OFFSYS

USE

Upon completion of the calculation of the data fitting link, the print link is called under control of the JPTRAJ MONITOR.

CODING INFORMATION

Length of subroutine is 1352 (10) or 2510 (8) words.

IDENTIFICATION

74

PROM

Melba W. Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

To multiply two square matrices and store in a third array.

RESTRICTION

Maximum array: 20×20

USE

CALL PROM (A, B, C, N)

$A(N, N) * B(N, N) = C(N, N)$

CODING INFORMATION

Length of subroutine is 110 (10) or 156 (8) words.

IDENTIFICATION

75

QUEST

Melba W. Nead, JPL
Fortran II, Version 3
January 4, 1965

PURPOSE

Checks to ascertain that the times specified are greater than EPOCH plus light time correction. Exits with an error return if time is not compatible.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:
 - ERROR
 - SQRT
 - EXIT

USE

CALL QUEST

CODING INFORMATION

Length of subroutine is 117 (10) or 165 (8) words.

IDENTIFICATION

76

QUIZ

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

QUIZ allows a Fortran program to interrogate the COMMON location KEYS, which contains the "key settings" specified by the input deck.

RESTRICTION

COMMON break: 47675

USE

In Fortran,

B A = (octal representation of desired key setting)

IF (QUIZF (A)) S₁, S₂, S₁

where

S₁ is the normal return indicating that the key is set

S₂ is the normal return indicating that the key is not set

COMMON input:

KEYS key setting word

CODING INFORMATION

Length of subroutine is 2 (10) or 2 (8) words.

IDENTIFICATION

77-1 of 4

RATES

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

RATES obtains the topocentric slant range and its first three derivatives. Both the up-leg and down-leg are calculated using the light-time correction supplied by subroutine DOPLR. Four other range-dependent quantities are also obtained.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines called:

COS

SIN

SQRT

ARSIN

EXP(3

METHOD

$$a_{ri} = \lambda_i + a_G - 2\omega\Delta t \quad (\text{station right ascension})$$

$$X_i = R_i \cos \phi_i \cos a_{ri}$$

$$Y_i = R_i \cos \phi_i \sin a_{ri}$$

$$Z_i = R_i \sin \phi_i$$

$$\dot{X}_i = -\omega Y_i$$

$$\dot{Y}_i = \omega X_i$$

$$\ddot{X}_i = -\omega Y_i$$

$$\ddot{Y}_i = \omega X_i$$

(station coordinates and derivatives)

$$\begin{aligned} \ddot{X}_i &= -\omega Y_i \\ \ddot{Y}_i &= \omega X_i \end{aligned} \left. \vphantom{\begin{aligned} \ddot{X}_i &= -\omega Y_i \\ \ddot{Y}_i &= \omega X_i \end{aligned}} \right\} \begin{array}{l} \text{(station coordinates} \\ \text{and derivatives)} \end{array}$$

$$\begin{aligned} \underline{\rho}_i &= \underline{r} - \underline{R}_i \\ \dot{\underline{\rho}}_i &= \dot{\underline{r}} - \dot{\underline{R}}_i \\ \ddot{\underline{\rho}}_i &= \ddot{\underline{r}} - \ddot{\underline{R}}_i \end{aligned} \left. \vphantom{\begin{aligned} \underline{\rho}_i &= \underline{r} - \underline{R}_i \\ \dot{\underline{\rho}}_i &= \dot{\underline{r}} - \dot{\underline{R}}_i \\ \ddot{\underline{\rho}}_i &= \ddot{\underline{r}} - \ddot{\underline{R}}_i \end{aligned}} \right\} \text{(topocentric coordinates)}$$

$$\begin{aligned} A &= \underline{\rho}_i \cdot \dot{\underline{r}} \\ B &= \dot{\underline{R}}_i \cdot \dot{\underline{r}}_s \\ C &= \dot{X}_i^2 + \dot{Y}_i^2 \\ D &= \underline{\rho}_i \cdot (\dot{\underline{R}}_i - \dot{\underline{r}}_s) \\ a &= |\underline{\rho}| \\ b &= \underline{\rho} \cdot \dot{\underline{\rho}} \\ c &= \underline{\rho} \cdot \ddot{\underline{\rho}} + \dot{\underline{\rho}} \cdot \dot{\underline{\rho}} \\ d &= \underline{\rho} \cdot \ddot{\underline{\rho}} + 3\dot{\underline{\rho}} \cdot \dot{\underline{\rho}} \end{aligned} \left. \vphantom{\begin{aligned} A &= \underline{\rho}_i \cdot \dot{\underline{r}} \\ B &= \dot{\underline{R}}_i \cdot \dot{\underline{r}}_s \\ C &= \dot{X}_i^2 + \dot{Y}_i^2 \\ D &= \underline{\rho}_i \cdot (\dot{\underline{R}}_i - \dot{\underline{r}}_s) \\ a &= |\underline{\rho}| \\ b &= \underline{\rho} \cdot \dot{\underline{\rho}} \\ c &= \underline{\rho} \cdot \ddot{\underline{\rho}} + \dot{\underline{\rho}} \cdot \dot{\underline{\rho}} \\ d &= \underline{\rho} \cdot \ddot{\underline{\rho}} + 3\dot{\underline{\rho}} \cdot \dot{\underline{\rho}} \end{aligned}} \right\} \text{(four output quantities)}$$

$$\begin{aligned} \rho &= a \\ \dot{\rho} &= \frac{b}{a} \\ \ddot{\rho} &= \frac{c - \dot{\rho}^2}{a} \\ \ddot{\underline{\rho}} &= \frac{d - 3\dot{\rho}\ddot{\rho}}{a} \end{aligned} \left. \vphantom{\begin{aligned} \rho &= a \\ \dot{\rho} &= \frac{b}{a} \\ \ddot{\rho} &= \frac{c - \dot{\rho}^2}{a} \\ \ddot{\underline{\rho}} &= \frac{d - 3\dot{\rho}\ddot{\rho}}{a} \end{aligned}} \right\} \text{(slant range)}$$

$$\Delta_{r\rho} = \frac{0.0018958}{(\sin \gamma + 0.06483)^{1.4}} \frac{n_i}{340.0}$$

$$\Delta_{r\rho} = \frac{0.0018958}{\tau} \left[\frac{1}{(\sin F + 0.06483)^{1.4}} - \frac{1}{(\sin G + 0.06483)^{1.4}} \right] \frac{n}{340.0}$$

77-3 of 4
(slant range)

where

- λ_i = longitude station i
- α_G = Greenwich hour angle
- ω = Earth rotation rate
- Δt = light time correction
- ϕ_i = geocentric latitude, station i
- R_i = Earth radius at station i
- \underline{r} = geocentric probe coordinates
- \underline{r}_s = geocentric sun coordinates
- γ = elevation angle
- n_i = index of refraction, station i
- τ = doppler averaging time
- $F = \gamma + \frac{\tau \dot{\gamma}}{2}$
- $G = \gamma - \frac{\tau \dot{\gamma}}{2}$

USE

| CALL | RATES | |
|------|--------|--|
| PZE | RHO | ρ , km |
| PZE | DRHO | $\dot{\rho}$, km/sec |
| PZE | DDRHO | $\ddot{\rho}$, km/sec ² |
| PZE | DDDRHO | $\dddot{\rho}$, km/sec ³ |
| PZE | A | A |
| PZE | B | B |
| PZE | C | C |
| PZE | D | D |
| PZE | DT | Δt , sec |
| PZE | I | station index (IX for up-leg, IR for down-leg) |

COMMON input:

77-4 of 4

| | | |
|--------|---|------------------------|
| THETAI | θ_i , deg | |
| GHA | $\dot{\alpha}_G$, deg | |
| OMEGA | ω , deg/sec | |
| PHI | ϕ_i , deg | |
| RI | R_i , km | |
| XN | \underline{r} , km | } light time corrected |
| DXN | $\underline{\dot{r}}$, km/sec | |
| DDXN | $\underline{\ddot{r}}$, km/sec ² | |
| DDDXN | $\underline{\dddot{r}}$, km/sec ³ | |
| XSUN | $\underline{r}_s, \underline{\dot{r}}_s$ | |
| EL | γ , deg | |
| FNI | n_i | |
| TAU | τ , sec | |

COMMON output:

| | |
|-------|--------------------------------|
| RVEC | ρ , km |
| RDOT | $\dot{\rho}$, km/sec |
| DRVEC | $\Delta_x \rho$, km |
| DRDOT | $\Delta_x \dot{\rho}$, km/sec |

CODING INFORMATION

Length of subroutine is 435 (10) or 663 (8) words.

REFERENCES

- a. Warner, M. R., Nead, M. W., Hudson, R. H., TM 33-168, March 18, 1964.
- b. Anderson, John D., TM 312-409, March 24, 1964.

IDENTIFICATION

78

RCAL

Melba W. Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

RCAL is to be used to compute the coefficients as required in BMATRIX:

$$A = \left(\frac{1}{|\overline{RV} - \overline{R}|^3} - \frac{1}{RV^3} \right)$$

$$B = \left(\frac{3(\overline{RV} \cdot \overline{R} - R^2)}{|\overline{RV} - \overline{R}|^5} \right)$$

$$C = \left(\frac{3}{|\overline{RV} - \overline{R}|^3} \right)$$

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutine used:
SQRT

USE

CALL RCAL(RV) RV, location of the body vector. Results are stored in COMMON locations A, B, and C.

CODING INFORMATION

Length of subroutine is 159 (10) or 237 (8) words.

IDENTIFICATION

79

RCOM

Melba W. Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

RCOM computes the coefficients as defined in BMATRIX:

$$A = \left(\frac{1}{\left| \vec{RV} - \vec{R} \right|^3} \right)$$

$$B = \left(\frac{1}{RV^3} \right)$$

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:
SQRT

USE

CALL RCOM(RV) RV, location of the body vector. Results are stored in
COMMON locations A and B.

CODING INFORMATION

Length of subroutine is 91 (10) or 133 (8) words.

IDENTIFICATION

80

READS/ODOFF/MOOPH1
 Melba W. Nead, JPL
 IBM 7094 Fap
 January 4, 1965

PURPOSE

READS is the main program of the link of the ODP which reads data. The routine also includes phasing for all three possible targets, Moon, Mars, and Venus. The target is checked and the phasing is moved so as to be available to the trajectory through the WANT capability of the JPTRAJ monitor.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:
 - ODATA
 - TAPIO
 - OFFSYS
 - ERROR

USE

Upon the completion of each iteration, the logic of the program causes it to cycle back through READS, all under control of the Source Deck and the JPTRAJ monitor.

| | |
|------------|--|
| CALL ODOFF | To end ODP and return to system as called from ODATA. |
| MOOPH1 | Entry to allow JPTRAJ "WANT" feature to save information from this area of READS, namely, the phasing for SPACE. |

CODING INFORMATION

Length of subroutine is 704 (10) or 1300 (8) words.

IDENTIFICATION

81

REAP/REAM

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

To read the combined ephemeris tape as it is written by the subroutine RITEM.

RESTRICTIONS

a. ERROR indication received by encountering EOF on tape

b. Subroutines used:

TAPIO

FLAT

ERROR

METHOD

REAP-REAM read the combined ephemeris tape which has been written by RITEM. The subroutine uses two buffers for efficiency of operation.

USE

CALL REAP Compares TOB with that saved on tape

CALL REAM Compares T with that saved on tape

CODING INFORMATION

Length of subroutine is 1375(10) or 2537(8) words.

IDENTIFICATION

82

REJEC

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

REJEC keeps a record of those residuals which were rejected by the 3-sigma test. Each bit in the rejection table represents a residual. The table is ordered sequentially.

RESTRICTION

COMMON break: 46711

USE

CALL REJEC

PZE I

PZE J

PZE K

where

I = 0 to initialize (set pointer at first bit)

= 1 for normal entry

J = 0 to determine rejection status of current point

= 1 to update rejection status of current point

| | | |
|-------|--------------------|-----------------------------------|
| K = 0 | point not rejected | } input if J = 1, output if J = 0 |
| = 1 | point rejected | |

COMMON input and output:

CAPU 500 word rejection table, with recording capability for 18,000 residuals

CODING INFORMATION

Length of subroutine is 46 (10) or 56 (8) words.

IDENTIFICATION

83

RESID

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

Control program for the link which prints and plots residuals and prints statistics.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

THARP

TYPRYT

IOCS

USE

Upon request for residuals and statistics, this link is called by the JPTRAJ monitor.

CODING INFORMATION

Length of subroutine is 704 (10) or 1300 (8) words.

IDENTIFICATION

84

RESP/COLA
Melba W. Nead, JPL
IBM 7094 Fap
January 4, 1965

PURPOSE

This subroutine is designed to provide both listings and plots of information from the receiving stations. The plots are the residuals, observed minus calculated values, for one, two, or three types versus time. Date, station number, time at start of frame, and pass number are included on each frame. In addition to the above, the listings contain count time, sample time, computed values for the data, and weights. Rejected data points are starred. It is possible to list the residual in fixed (nominal) or floating point (FLRES = 1.0).

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:

FGDOUT
CXPLLOT
PKINE
PERNOD
STATID
FIXT
PROUT
FLAPR
BIBCD
ERROR
CDC

A maximum of 8 data residuals can be plotted or listed on one iteration.

USE

CALL RESP With each call to RESP a maximum of 3 residuals is plotted or listed.
The routine must be called again for more; the maximum number is 8.

CODING INFORMATION

Length of subroutine is 883 (10) or 1563 (8) words.

REFERENCE

Trask, D.W., RFP 312-37, Addendum 6, April 4, 1962.

IDENTIFICATION

85-1 of 2

RITEM/WREOF
 Melba W. Nead, JPL
 IBM 7094 Fap
 January 4, 1965

PURPOSE

To write the combined ephemeris tape.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:
 FLAT
 TAPIO

METHOD

RITEM uses TAPIO to write the combined ephemeris tape. The subroutine uses two buffers alternately to provide efficient timing. Each buffer contains four logical records of 156 words each.

USE

CALL RITEM Writes logical record on tape A4. Each record contains the following information:

| | | |
|----------|---|-----------------------|
| T (2) | | Time of data point |
| TOB (2) | | Observation time |
| XJUP (6) | | Jupiter vector |
| XERM (6) | | |
| XMAR (6) | | Mars vector |
| XVEN (6) | | Venus vector |
| XSUN (6) | | Sun vector |
| XMOO (6) | | Moon vector |
| X | } | Probe vector |
| Y | | |
| Z | | |
| XDOT | | |
| YDOT | | |
| ZDOT | | |
| U (36) | | Variational equations |
| DLO | | Nutation in longitude |
| DOB | | Nutation in obliquity |

| | | | |
|-----------|---|--------------|-----------------------------|
| XAC | } | | 85-2 of 2 |
| YAC | | | |
| ZAC | | | Probe acceleration |
| XJERK | } | | |
| YJERK | | | Probe jerk (3rd derivative) |
| ZJERK | | | |
| GMAT (66) | | Gamma matrix | |

CALL WREOF To write end of file and rewind tape A4 when ephemeris is complete.

CODING INFORMATION

Length of subroutine is 1350(10) or 2506(8) words.

IDENTIFICATION

86

ROT

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

ROT rotates the planetary ephemerides from the mean equator and equinox of 1950.0 to the true equator of equinox of date.

RESTRICTION

COMMON break: 47675

METHOD

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix}_{\text{of date}} = \text{NA} \begin{pmatrix} x \\ y \\ z \end{pmatrix}_{1950.0}$$

where

NA = nutation-precession matrix obtained by subroutine PNUT

USE

CALL ROT

COMMON input:

ROTMX NA

XSUN geocentric position and velocity of Sun, 1950.0

XVEN geocentric position and velocity of Venus

XMAR geocentric position and velocity of Mars

XJUP geocentric position and velocity of Jupiter

XMOO geocentric position and velocity of Moon

COMMON output:

XSUN, XVEN, XMAR, XJUP, XMOO rotated to true-of-date

CODING INFORMATION

Length of subroutine is 182 (10) or 266 (8) words.

IDENTIFICATION

87

RSIG

Melba W. Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

The partial of AU is expressed as a sum of terms evaluated for SUN, VENUS, MARS, and JUPITER. RSIG evaluates and sums these terms as they are needed in BMATRIX.

$$\sum_{k=1}^4 GM_k \left[x_k \left(\frac{1}{|r_k - r|^3} - \frac{1}{r_k^3} \right) - \frac{3(r^2 - r \cdot r_k)(x - x_k)}{|r_k - r|^5} \right]$$

where

k = 1 = Sun

k = 2 = Venus

k = 3 = Mars

k = 4 = Jupiter

RESTRICTION

COMMON break: 47675

USE

CALL RSIG(GRA, XPL, SIGX) where GRA is gravity of the body, XPL position of body, and SIGX is the sum. The routine is called for the four bodies and SIGX is accumulated.

CODING INFORMATION

Length of subroutine is 51 (10) or 63 (8) words.

IDENTIFICATION

88

SAVCOM

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

Control for the program to save COMMON. This routine also prints the input matrices when the ODP is initiated and checks the times supplied so the trajectory can be run only for the required period.

RESTRICTIONS

- a. ERROR condition; disk error indicated by DCP
- b. COMMON break: 47675
- c. Subroutines used:

PRIM

TYPRYT

QUEST

MAXIM

ERROR

FLAK

DISCBU

OFFSYS

USE

To save COMMON during the trajectory link, this routine is under control of the JPTRAJ monitor.

CODING INFORMATION

Length of subroutine is 1118 (10) or 2136 (8) words.

IDENTIFICATION

89

SCALE

Melba W. Nead, JPL
Fortran II, Version 3
January 4, 1965

PURPOSE

When the target is Mars or Venus, the target vector is divided by AU as required in calculation of the target centered covariance matrix.

USE

CALL SCALE (XPOS, P) XPOS is the target vector, the quotient is stored in P.

CODING INFORMATION

Length of subroutine is 34 (10) or 42 (8) words.

IDENTIFICATION

90

SORT

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

Time sorted predictions are prepared in Link 4. This is the main program in which these predicts are station sorted and prepared for transmission to the tracking stations.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

THARP

FLAK

TYPRYT

IOCS

USE

Link 5 is called under control of the JPTRAJ Source Deck.

CODING INFORMATION

Length of subroutine is 1069 (10) or 2055 (8) words.

IDENTIFICATION

91-1 of 2

SPHX

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

SPHX converts Earth-fixed spherical coordinates to geocentric equatorial cartesian coordinates. No provision is made for nutations; thus, the output is in the mean equator and equinox of date.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

SIN

COS

GHADP

METHOD

$$x_0 = r_0 \cos \phi_0 \cos(a_G + \lambda_0)$$

$$y_0 = r_0 \cos \phi_0 \sin(a_G + \lambda_0)$$

$$z_0 = W$$

$$\dot{x}_0 = (\dot{U} - \omega V) \cos a_G - (\dot{V} + \omega U) \sin a_G$$

$$\dot{y}_0 = (\dot{U} - \omega V) \sin a_G + (\dot{V} + \omega U) \cos a_G$$

$$\dot{z}_0 = \dot{W}$$

$$U = r_0 \cos \phi_0 \cos \lambda_0$$

$$V = r_0 \cos \phi_0 \sin \lambda_0$$

$$W = r_0 \sin \phi_0$$

$$\dot{U} = v_0(\sin \gamma_0 \cos \phi_0 \cos \lambda_0 - \cos \gamma_0 \sin \gamma_0 \sin \sigma_0 - \cos \gamma_0 \sin \phi_0 \cos \lambda_0 \cos \sigma_0)$$

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$$\dot{V} = v_0(\sin \gamma_0 \cos \phi_0 \sin \lambda_0 + \cos \gamma_0 \cos \gamma_0 \sin \sigma_0 - \cos \gamma_0 \sin \phi_0 \sin \lambda_0 \cos \sigma_0)$$

$$\dot{W} = v_0(\sin \gamma_0 \sin \phi_0 + \cos \gamma_0 \cos \phi_0 \cos \sigma_0)$$

where

$x_0, y_0, z_0, \dot{x}_0, \dot{y}_0, \dot{z}_0$ = geocentric equatorial position and velocity

$r_0, \phi_0, \lambda_0, v_0, \gamma_0, \sigma_0$ = Earth-fixed spherical coordinates

a_G = Greenwich hour angle

ω = Earth rotation rate

USE

CALL SPHX

COMMON input:

RNJ r_0 , km

PHINJ ϕ_0 , deg

THTNJ λ_0 , deg

VNJ v_0 , km/sec

ELNJ γ_0 , deg

AZNJ σ_0 , deg

EPOCH epoch of state vector, d. p. sec past 1950.0

OMEGA ω , deg/sec

COMMON output:

XNJ $x_0, y_0, z_0, \dot{x}_0, \dot{y}_0, \dot{z}_0$ (1 x 6)

CODING INFORMATION

Length of subroutine is 211 (10) or 323 (8) words.

IDENTIFICATION

92

STARP

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

STARP determines whether an observed time point should be deleted or retained on the basis of input data start and stop times.

RESTRICTION

COMMON break: 47675

USE

CALL STARP

PZE I I = 0 for point outside allowed range
= 1 for point within allowed range

COMMON input:

TOB observation time, d. p. sec past 1950.0
PTFD-30 start-stop times

CODING INFORMATION

Length of subroutine is 24 (10) or 30 (8) words.

IDENTIFICATION

93-1 of 3

STPREG

Charles L. Lawson/Terry Kinney, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

Double precision solution of the normal equations of a linear least squares regression problem using the stepwise procedure of M. A. Efroymsen.

This subroutine is particularly intended for use in least-squares problems in which the user is aware of a large number of basic functions which might bear a linear relationship to the object function but expects that only some of these basic functions make a significant contribution to the determination of the object function.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:
(DFAD)/(DFMP)/(DFDP)
DSQRT

METHOD

In an n-parameter problem this subroutine provides successively a 1-parameter fit, a 2-parameter fit, . . . , a k-parameter fit, where the new parameter introduced at each step is the one which will make the greatest reduction in the sum of squares of residuals. This criterion is equivalent to the requirement that the new parameter be selected as the one which will have the highest statistical significance in the sense that the ratio of its magnitude to its standard deviation will be largest or equivalently its "F" value will be largest (see Ref. c). The termination level k, which will be $\leq n$, is determined by the subroutine on the basis of tolerance parameters SDIN, SDOUT, and CD provided by the user.

For an exposition of this procedure, see Ref. a of this subroutine. For a complete single precision regression package which incorporates this procedure in its system solving subroutine, see Ref. b. For a discussion of this procedure including details of its implementation in this program see Ref. c.

USE

Let the overdetermined system of linear equations which expresses the linear regression problem be denoted by

$$Gc = f$$

where G is an m by n matrix ($m > n$), c is an n-vector, f is an m-vector. The elements of G and f are known and the coefficient vector c is to be computed as a weighted least squares solution.

The normal equations $Ac = b$ are formed from the overdetermined system by pre-multiplication by G^*W , (*denotes transposition) where W is an m by m non-negative definite weighting matrix (W may be the identity matrix).

This computation, as well as the computation of the scalar quantity $s = f^*Wf$, is to be done by the user's program. STPREG may then be called as follows:

```
D  DIMENSION A (20, 20), B (20), S (1)
   DIMENSION INOUT (20)
   CALL STPREG (A, B, S, N, M, SDIN, SDOUT,
               CD, NIN, INOUT)
```

The parameters are defined as follows:

A(I, J), I = 1, N; J = 1, N

On entry: The matrix A, computed by the user as $A = G^*WG$.

A is normalized by STPREG before inversion.

On return: A^{-1} if $NIN = N$. If $NIN < N$ then only an NIN by NIN submatrix of A will have been inverted and the elements of this inverse will be in the locations A (I, J) corresponding to those values of I and J for which both $INOUT(I) = +1$ and $INOUT(J) = +1$. The other A (I, J) locations for $I \leq N, J \leq N$ will contain zero. A^{-1} is unnormalized before the return.

B(I), I = 1, N

On entry: The vector b, computed by the user as $b = G^*Wf$.

On return: The solution vector c if $NIN = N$. If $NIN < N$ then only NIN components of c will have been computed and they will be those in the locations B (I) for which $INOUT(I) = +1$. The other B (I) locations for $I \leq N$ will contain zero.

S

On entry: The scalar s, computed by the user as $s = f^*Wf$.

On return: The weighted sum of squares of residuals:

$$\begin{aligned} (f - Gc)^*W(f - Gc) &= (f - Gc)^*Wf \\ &= f^*Wf - (Gc)^*Wf = f^*Wf - c^*b \end{aligned}$$

N The dimension, n, of the normal system.

M The dimension, m, of the f vector.

SDIN, SDOUT

If $DSIN > 0.$, these two numbers will be used by the "significance" logic of the program. A coefficient will be permitted to enter the solution if the ratio of its

magnitude to its standard deviation will exceed SDIN. If this ratio subsequently drops below SDOUT this coefficient will be removed from the solution. To avoid looping, SDIN should exceed SDOUT.

Typical values for SDIN and SDOUT might be SDIN = 1.96, SDOUT = 1.64, which could be interpreted as meaning that a coefficient will be permitted to enter the solution if there is a 95% probability that it is different from zero and will later be removed from the solution if this probability falls below 90%.

If $SDIN \leq 0$ all significance tests will be skipped. This permits use of the program with meaningless data in B and S, as may be the case when only matrix inversion is desired.

CD Tolerance for relative reduction in magnitude of diagonal elements. The i^{th} coefficient will not be entered into the solution if the i^{th} diagonal element becomes smaller than CD times the original i^{th} diagonal element of the matrix A. For example if CD = 10. **(-12) then a potential pivot element will not be used if it has lost more than its first 12 significant decimal places.

NIN On return: The number of coefficients in the final solution. INOUT (I), I = 1, N
On return: Flags to indicate final status of each coefficient.

- +1 Included in solution.
- 1 Rejected by diagonal test.
- 2 Rejected by significance tests.

CODING INFORMATION

Length of subroutine is 1069 (10) or 2055 (8) words.

REFERENCES

- a. Efroymson, M. A., Multiple Regression Analysis, Mathematical Methods for Digital Computers, ed. Ralston and Wilf, Wiley, 1960, pp. 191-203.
- b. Efroymson, M. A., Stepwise Multiple Regression with Variable Transformations, SHARE Distribution No. 1194, October, 1961.
- c. Lawson, C.L., Computation of the Most Significant Coefficients in Least-Squares Estimation, JPL Section Report No. 372-5, August, 1962.

IDENTIFICATION

94-1 of 2

TACCOM

Melba W. Nead, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

To evaluate the target-centered cartesian Covariance Matrix.

RESTRICTIONS

a. COMMON break: 47055

b. Subroutines used:

AAT

SCALE

(DFAD)

(DFMP)

(DFSB)

METHOD

In the following, A will represent the ephemeris scaling factor. Thus, A = REM when target = MOON, and A = AU when target = MARS or VENUS.

a. When A is among the estimated parameters, compute the target centered covariance matrix as

$$\Gamma_E = \Gamma_X + PP^T \sigma_A^2 - \Gamma_{XA} P^T - P \Gamma_{XA}^T$$

where

Γ_X = upper left hand 6×6 sub-matrix of the geocentric covariance matrix Γ

P = 6-vector giving the geocentric position and velocity of the target in units of A and A/sec, referred to the Earth equatorial system

σ_A^2 = diagonal element of Γ corresponding to A

Γ_{XA} = first 6 elements of the column of Γ corresponding to A

b. When A is not among the estimated parameters

94-2 of 2

$$\Gamma_E = \Gamma_X$$

USE

CALL TACCOM (GAME, ITAR)
GAME contains Γ_E as calculated in TACCOM
ITAR contains the target reference
 ITAR = 1 MARS
 ITAR = 2 MOON
 ITAR = 3 VENUS

CODING INFORMATION

Length of subroutine is 938 (10) or 1652 (8) words.

REFERENCE

Carey, C., RFP 312-252, March 5, 1964.

IDENTIFICATION

95

TAMP/EPOX

Melba W. Nead, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

Writes mapping times on scratch tape A7 to be saved for matrix manipulation program input tape.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

TAPIO

FLAT

USE

CALL TAMP

EPOX

provides space for storage of injection conditions which are saved through the WANT cards feature of JPTRAJ

CODING INFORMATION

Length of subroutine is 87 (10) or 127 (8) words.

IDENTIFICATION

96

THARP/PKINE

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

THARP serves as the logical control routine for the predictions and residuals output links, LA5 and LA8. It sets up lists of desired stations and calls the output subroutines AQU, PERIOD, RESP, and ANGPLT. PKINE is called by these output routines in order to obtain a meaningful logical record from the disk read routine KINE.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:
 - OFFSYS
 - KINE
 - AQU/ALLI/BAQU/BALLI
 - PERIOD/WOLF
 - RESP
 - ANGPLT
 - BIBCD
 - TYPRYT

USE

CALL THARP
 CALL PKINE
 PZE SUBR = 1 if called from ANGPLT
 = 2 if called from AQU
 = 3 if called from PERIOD
 = 4 if called from RESP

COMMON input:

IF3 ODP option flags
 IRES residual output flags (8 × 15)
 RESR plotting scale factors (8 × 15)
 ITNO iteration number
 PT pointing times (used as flags)

CODING INFORMATION

Length of subroutine is 379 (10) or 573 (8) words.

IDENTIFICATION

97-1 of 2

TIMER

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

TIMER obtains the primary light time correction which adjusts the observation time for ephemeris lookup purposes.

RESTRICTIONS

- a. COMMON break: 47675
- b. Subroutines used:
 - (DFSB)
 - LOOKUP
 - SQRT

METHOD

$$\Delta t = 0$$

$$t = t_{ob} - \Delta t$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\Delta t = \frac{r - R_e}{C}$$

The procedure is then repeated with the new Δt .

USE

CALL TIMER

COMMON input:

TOB t_{ob} , d. p. sec past 1950.0

RE R_e , km

VELC c , km/sec

COMMON output:

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T t, d. p. sec past 1950.0

DELT Δt , d. p. sec

CODING INFORMATION

Length of subroutine is 98 (10) or 142 (8) words.

IDENTIFICATION

98

TNORM

Melba W. Nead/Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

TNORM normalizes an $N \times N$ matrix on its diagonal terms. N may be 2, 3, 4, 5, or 6 but the matrix must be stored in a 6×6 array.

RESTRICTION

Subroutine called:

 SORT

USE

CALL TNORM

PZE YMAT input matrix

PZE XMAT output normalized matrix

PZE N N

CODING INFORMATION

Length of subroutine is 170 (10) or 252 (8) words.

IDENTIFICATION

99-1 of 3

TOCIM

Michael R. Warner, JPL

IBM 7094, Fap

January 4, 1965

PURPOSE

TOCIM computes occultation time and impact time, and obtains the residual. It writes a record on the combined ephemeris tape for each observable, and outputs on disk for subsequent printing.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

OFFSYS

TIMER

LOOKUP/KOOL

INTRI

SQRT

COS/SIN

GAMAT

GHADP

ARCOS/ARSIN

FLAT

RITE

WRITEB

METHOD

TOCIM uses a Newton-Raphson formula for both data types:

For occultation time,

$$\left[T_0^{(r)} - T_0^{(r-1)} \right] \frac{d(\phi_p - \phi_m)}{dt} \Big|_{T_0^{(r-1)}} = \phi_m - \phi_p$$

where

$$\phi_m = \sin^{-1} \frac{R_m}{\rho_m}$$

$$\phi_p = \cos^{-1} \frac{\underline{\rho} \cdot \underline{\rho}_m}{|\underline{\rho}| |\underline{\rho}_m|}$$

$$\frac{d(\phi_p - \phi_m)}{dt} = \frac{\underline{\rho} \cdot \underline{\rho}_m}{a_1} \left[\left(\frac{a_2}{\rho^2} + \frac{a_3}{\rho_m^2} \right) - a_4 \right] + \frac{a_3 R_m}{\rho_m^2 \sqrt{\rho_m^2 - R_m^2}}$$

$$a_1 = |\underline{\rho}| |\underline{\rho}_m| \sin \phi_p$$

$$a_2 = \underline{\rho} \cdot \dot{\underline{\rho}}_m$$

$$a_3 = \underline{\rho}_m \cdot \dot{\underline{\rho}}_m$$

$$a_4 = \underline{\rho} \cdot \dot{\underline{\rho}}_m + \underline{\rho}_m \cdot \dot{\underline{\rho}}$$

For impact time,

$$\left[T_I^{(r)} - T_I^{(r-1)} \right] \left| \dot{\underline{r}} - \dot{\underline{r}}_m \right| = \left| \underline{r} - \underline{r}_m \right| - R_m$$

(all quantities are defined in the subroutine OCPAR documentation)

USE

CALL TOCIM

COMMON input:

| | |
|---------|-----------------------------------|
| DXDK-6 | target identification |
| IFA-4 | R_m , km |
| PTFD | occultation-impact data buffer |
| DXDR-27 | occultation-impact buffer |
| LLIST | physical constants estimate flags |
| RI | station Earth radius, km |
| PHI | station geocentric latitude, deg |
| THETA | station longitude, deg |
| EPOCH | ODP epoch, d. p. sec past 1950.0 |
| OMEGA | Earth rotation rate, deg/sec |

CODING INFORMATION

99-3 of 3

Length of subroutine is 998 (10) or 1746 (8) words.

REFERENCE

Warner, M. R., Nead, M. W., Hudson, R. H., TM 33-168, March 18, 1964.

IDENTIFICATION

100-1 of 9

UMAT

Kenneth Oslund/Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

UMAT computes the encounter conic, rotating from the geocentric equatorial system to the target-centered \underline{R} , \underline{T} system. All encounter parameters and statistics are obtained by this routine.

RESTRICTIONS

Subroutines called:

SQRT

LOG

GERPU

ARTAN

PARAM

METHOD

The following inputs are in the UMAT calling sequence:

\underline{r}'_{tp} , $\underline{\dot{r}}'_{tp}$ target centered probe position and velocity at time of encounter

\underline{r}_{ct} , $\underline{\dot{r}}_{ct}$ position and velocity of target, centered at that body's primary, at time of encounter

Γ_e covariance matrix at encounter (7×7)

U_e mapping matrix to encounter (7×7)

μ GM_{target}

t_f time of flight

First, the rotation matrix is obtained:

$$\underline{r}'^2 = \underline{r}_{ct} \cdot \underline{r}_{ct}$$

$$\underline{\dot{s}}'^2 = \underline{\dot{r}}_{ct} \cdot \underline{\dot{r}}_{ct}$$

$$\mathbf{r}' \dot{\mathbf{r}}' = \mathbf{r}_{ct} \cdot \dot{\mathbf{r}}_{ct}$$

$$\underline{u}_p = \frac{\mathbf{r}_{ct}}{r'}$$

$$\underline{v}_p = \frac{r' \dot{\mathbf{r}}_{ct} - \dot{r}' \mathbf{r}_{ct}}{r' \sqrt{\dot{s}'^2 - \dot{r}'^2}}$$

$$a_{33} = \sqrt{(u_{pr} + v_{py})^2 + (u_{py} - v_{px})^2} - 1$$

$$a_{23} = \sqrt{u_{pz}^2 + v_{pz}^2}$$

$$a_{11} = \frac{\frac{1}{1 + a_{33}} [v_{pz}(u_{px} + v_{py}) + u_{pz}(u_{py} - v_{px})]}{a_{23}}$$

$$a_{12} = \frac{\frac{1}{1 + a_{33}} [v_{pz}(u_{py} - v_{px}) - u_{pz}(u_{px} + v_{py})]}{a_{23}}$$

$$a_{21} = -a_{12} a_{33}$$

$$a_{22} = a_{11} a_{33}$$

$$a_{31} = a_{12} a_{23}$$

$$a_{32} = -a_{11} a_{23}$$

The target-centered probe vector is then rotated:

$$\underline{\mathbf{r}}_{tp} = A \underline{\mathbf{r}}'_{tp}$$

$$\underline{\dot{\mathbf{r}}}_{tp} = A \underline{\dot{\mathbf{r}}}'_{tp}$$

and the following column vectors are formed:

100-3 of 9

$$\underline{X}_p = \begin{pmatrix} r_{tp} \\ 0 \end{pmatrix} \quad \dot{\underline{X}}_p = \begin{pmatrix} \dot{r}_{tp} \\ 0 \end{pmatrix}$$

$$\underline{X}_v = \begin{pmatrix} 0 \\ r_{tp} \end{pmatrix} \quad \dot{\underline{X}}_v = \begin{pmatrix} 0 \\ \dot{r}_{tp} \end{pmatrix}$$

(the seventh member of these vectors is in each case zero)

The encounter conic is then obtained:

$$r^2 = \underline{X}_p \cdot \underline{X}_p$$

$$\dot{s}^2 = \dot{\underline{X}}_p \cdot \dot{\underline{X}}_p$$

$$r \dot{r} = \underline{X}_p \cdot \dot{\underline{X}}_p$$

$$a = \frac{1}{\frac{2}{r} - \frac{\dot{s}^2}{\mu}} \quad (\text{semi-major axis})$$

$$e^2 = 1 - \frac{r^2 \dot{s}^2 - (r \dot{r})^2}{\mu/a} \quad (\text{eccentricity})^2$$

$$e \sinh F = \frac{r \dot{r}}{\sqrt{-\mu/a}}$$

$$e \cosh F = 1 - \frac{r}{a}$$

$$e \exp F = e \sinh F + e \cos F$$

$$F = \log (\exp F) \quad (\text{hyperbolic anomaly})$$

$$e p_z = X_{pz} \frac{e \cosh F}{r} - \dot{X}_{pz} e \sinh F \sqrt{-\frac{a}{\mu}}$$

$$e \sin \phi_s = \left(\frac{X_{pz}}{r} - X_{pz} \sqrt{-\frac{a}{\mu}} \right) \exp F + \dot{X}_p e \sqrt{-\frac{a}{\mu}}$$

$$\underline{B} \cdot \underline{T} \cos \phi_s = \sqrt{-\frac{a}{\mu}} (X_{pz} \dot{X}_{py} - X_{py} \dot{X}_{pz})$$

$$\underline{B} \cdot \underline{R} \cos \phi_s = a(\sin \phi_s - e p_z)$$

$$T_a = \frac{3}{2} \sqrt{-\frac{a}{\mu}} (e \sinh F - F + \log e)$$

$$T_e = \left(\frac{e \sinh F + 1}{e} \right) a \sqrt{-\frac{a}{\mu}}$$

$$T_F = -r \sqrt{-\frac{a}{\mu}}$$

$$v_\infty = \frac{1}{\sqrt{-\frac{a}{\mu}}}$$

$$n = \frac{-v_\infty}{a}$$

$$t_L = t_f + \frac{(F - e \sinh F - \log e)}{n} \quad (\text{linearized time of flight})$$

The next step is to obtain the encounter partials. The encounter parameter set (M) is

$\underline{B} \cdot \underline{R}$ as defined above

$\underline{B} \cdot \underline{T}$ as defined above

t_L linearized time of flight

$\left. \begin{array}{l} \underline{S} \cdot \underline{R}_s \\ \underline{S} \cdot \underline{T}_s \end{array} \right\}$ dot products of incoming asymptote unit vector \underline{S}
 with standard \underline{R} and \underline{T} vectors

C_3 vis-viva energy

These parameters are related to the position and velocity of the probe at encounter and the target gravitational constant. This set is called Q.

$$F_{az} = \frac{\exp F}{r}$$

$$F_{a\dot{z}} = -\sqrt{-\frac{a}{\mu}} (\exp F - e)$$

$$F_{bz} = \frac{e \cosh F}{r}$$

$$F_{b\dot{z}} = -\sqrt{-\frac{a}{\mu}} e \sinh F$$

$$F_{cx} = -\dot{X}_{py}$$

$$F_{cy} = \dot{X}_{px}$$

$$F_{c\dot{x}} = X_{py}$$

$$F_{c\dot{y}} = -X_{px}$$

$$S_x = \left[\left(\frac{X_{px}}{r} - \sqrt{-\frac{a}{\mu}} \dot{X}_{px} \right) \exp F + e \sqrt{-\frac{a}{\mu}} \dot{X}_{px} \right] \frac{1}{e} x \rightarrow y$$

$$S_z = \sin \phi_s$$

$$T_{sx} = \frac{S_y}{\cos \phi_s}$$

$$T_{sy} = -\frac{S_x}{\cos \phi_s}$$

$$R_{sx} = T_{sy} S_z$$

$$R_{sy} = -T_{sx} S_z$$

$$R_{sz} = \cos \phi_s$$

$$\underline{\delta a} = 2a^2 \left(\frac{X_p}{r^3} + \frac{\dot{X}_n}{\mu} \right)$$

$$\delta a_\mu = - \frac{a^2(1 + e \cosh F)}{r\mu}$$

$$\left[\delta \underline{e}; \delta' e_\mu \right] = \frac{1}{e} \left[- \frac{\frac{e}{a} \cosh F \underline{X}_p}{r} - \frac{e \sinh F (\dot{\underline{X}}_p + \underline{X}_v)}{\sqrt{-\frac{\mu}{a}}} \right. \\ \left. + \delta \underline{a} \left(\frac{1}{2} \frac{e^2 \sinh^2 F}{a} + \frac{r e \cosh F}{a^2} \right) \right]$$

$$\delta e_\mu = \delta' e_\mu + \frac{1}{e} \left[- \frac{1}{\mu} \left(\frac{1}{2} e^2 \sinh^2 F + \frac{r}{a} e \cosh F \right) + \frac{r^2}{2a^2} + \frac{r^2 \delta a_\mu}{2a^3} \right]$$

$$\left[\delta \underline{F}; \delta' F_\mu \right] = \frac{1}{e} \left[\frac{\frac{e}{a} \sinh F \underline{X}_p}{r} + \frac{e \cosh F (\dot{\underline{X}}_p + \underline{X}_v)}{\sqrt{-\frac{\mu}{a}}} \right. \\ \left. - \delta \underline{a} \left(\frac{1}{2} \frac{e^2 \cosh^2 F}{a} + \frac{r e \sinh F}{a^2} \right) \right]$$

$$\delta F_\mu = \delta' F_\mu + \frac{1}{e} \left(- \frac{e \sinh F}{2\mu e \cosh F} - \frac{r^2 e \sinh F \delta a_\mu}{2 e \cosh F a^3} \right)$$

$$\left[\delta \underline{\Phi}_s; \delta' \Phi_{s\mu} \right] = \left[- \frac{\underline{X}_{pz} \underline{X}_p \exp F}{r^3} - \frac{\frac{1}{2} \dot{\underline{X}}_{pz} (e - \exp F) \partial \underline{a}}{\sqrt{-\frac{\mu}{a}}} \left(- \frac{\dot{\underline{X}}_{pz} a}{\sqrt{-\frac{\mu}{a}}} + \sin \Phi_s \right) \delta \underline{e} \right. \\ \left. - \left(\dot{\underline{X}}_{pz} \sqrt{-\frac{a}{\mu}} - \frac{\underline{X}_{pz}}{r} \right) \delta \underline{F} \exp F + \frac{F}{a} \right] \frac{1}{e \cos \Phi_s}$$

$$\left[\delta \underline{S}_x; \delta' S_{x\mu} \right] = \frac{1}{e} \left[- \frac{\underline{X}_{px} \exp F \underline{X}_p}{r^3} + \frac{\dot{\underline{X}}_{px} (\exp F - e)}{2 \sqrt{-\frac{\mu}{a}}} \delta \underline{a} \right. \\ \left. + \left(\sqrt{-\frac{a}{\mu}} \dot{\underline{X}}_{px} - S_x \right) \delta \underline{e} - \left(\frac{\sqrt{-\frac{a}{\mu}} \dot{\underline{X}}_{px} - \underline{X}_{px}}{r} \right) \exp F \delta \underline{F} + \frac{F}{a} \right]$$

$$\left[\underline{\delta S}_y \vdots \delta' S_{y\mu} \right] = \left[\underline{\delta S}_x \vdots \delta' S_{x\mu} \right] \quad x \rightarrow y$$

$$\left[\underline{\delta S}_z \vdots \delta' S_{z\mu} \right] = \cos \phi_s \underline{\delta \phi_s}$$

$$\underline{E}_p = - \frac{e \sinh F \sqrt{-\frac{a}{\mu}} \dot{X}_p}{2\mu}$$

$$\underline{\delta S}_\mu = \underline{\delta' S}_\mu + \left[\underline{E}_p - (e \cosh F - e^2) \frac{\dot{X}_p \sqrt{-\frac{a}{\mu}}}{2\mu} \right] \frac{1}{e \cos \phi_s}$$

$$\delta \phi_{s\mu} = \delta' \phi_{s\mu} + \delta' S_{z\mu}$$

$$\left[e \delta P_z \vdots (e \delta P_{z\mu}) \right] = - \frac{X_{pz} e \cosh F X_p}{r^3} + \frac{X_{pz} e \sinh F \delta a}{2 \sqrt{-\frac{\mu}{a}}}$$

$$\left(- \dot{X}_{pz} e \cosh F \sqrt{-\frac{a}{\mu}} - \frac{e \sinh F}{r} \right) \underline{\delta F} + \underline{F}_b$$

$$e \delta P_{z\mu} = (e \delta P_{z\mu}) + E_{pz}$$

The program now computes the variational matrix $V = \left(\frac{\partial M}{\partial Q} \right)$:

$$\left[\underline{v}_1 \vdots v'_{1\mu} \right] = \left[\left(e \sin \phi_p - e^2 P_z \right) \underline{\delta a} - a e P_z \underline{\delta e} - (\underline{B} \cdot \underline{R} e \sin \phi_p a e \cos \phi_p) \underline{\delta \phi_s} - a e^2 \underline{\delta P_z} \right] \frac{1}{e \cos \phi_p}$$

$$\left[\underline{v}_2 \vdots v'_{2\mu} \right] = \left(\frac{e \cos \phi_p \underline{B} \cdot \underline{T}}{2a} \underline{\delta a} + \underline{B} \cdot \underline{T} e \sin \phi_p \underline{\delta \phi_s} - e \sqrt{-\frac{a}{\mu}} \underline{F}_c \right) \frac{1}{e \cos \phi_p}$$

$$\left[\underline{v}_3 \vdots v'_{3\mu} \right] = T_a \underline{\delta a} + T_e \underline{\delta e} + T_F \underline{\delta F}$$

$$\left[\underline{v}_4 \vdots v'_{4\mu} \right] = \frac{\mu}{a^2} \underline{\delta a}$$

$$\left[\underline{v}_5 \vdots v'_{5\mu} \right] = T_{sx} \underline{\delta S}_x + T_{sy} \underline{\delta S}_y$$

$$\begin{bmatrix} v_6 \\ v_6' \end{bmatrix} = R_{sx} \delta S_x + R_{sy} \delta S_y + R_{sz} \delta S_z$$

100-8 of 9

$$v_{1\mu} = v_{1\mu}'$$

$$v_{2\mu} = v_{2\mu}' + \frac{\underline{B} \cdot \underline{T}}{2\mu}$$

$$v_{3\mu} = v_{3\mu}' - \frac{\sqrt{-\frac{a^3}{\mu}} (F - e \sinh F - \log e)}{2\mu}$$

$$v_{4\mu} = v_{4\mu}' - \frac{1}{a}$$

$$v_{5\mu} = v_{5\mu}'$$

$$v_{6\mu} = v_{6\mu}'$$

The following matrix manipulations are then performed:

$$N = V^T A \Gamma_e A^T V \quad (\text{noise moment matrix})$$

$$V_0 = V A U_e \quad \left(V_0 = \frac{\partial M}{\partial Q_0} \text{ matrix} \right)$$

Finally, the configuration of the miss ellipse is obtained:

$$r = \sqrt{\left(\frac{n_{11} - n_{22}}{2} \right)^2 + n_{12}^2}$$

$$s = \frac{n_{11} + n_{22}}{2}$$

$$a_m = \sqrt{s + r} \quad (\text{semi-major axis})$$

$$b_m = \sqrt{s - r} \quad (\text{semi-minor axis})$$

$$\theta = \frac{1}{2} \tan^{-1} \left(\frac{2n_{12}}{n_{22} - n_{11}} \right) \quad (\text{inclination})$$

USE

100-9 of 9

| CALL | UMAT | | |
|------|------|------------------------------|----------------------------|
| PZE | XT | $\dot{r}_{tp}, \dot{i}_{tp}$ | (1 × 6) |
| PZE | XH | $\dot{r}_{ct}, \dot{i}_{ct}$ | (1 × 6) |
| PZE | G | Γ_e | (7 × 7) |
| PZE | U | U_e | (7 × 7) in (20 × 20) array |
| PZE | TMU | μ of target | |
| PZE | TF | t_f , sec | |

CODING INFORMATION

Length of subroutine is 1681 (10) or 3221 (8) words.

REFERENCES

- a. Warner, M. R., Nead, M. W., Hudson, R. H., TM 33-168, March 18, 1964.
- b. Anderson, John D., RFP 312-83, October 1962.
- c. Null, George W., RFP 312-179, Addendum 2, September 19, 1963.

IDENTIFICATION

101

VEC

Charles Coltharp, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

VEC computes the standard dot product of two 1×3 vectors, $A = \underline{X} \cdot \underline{Y}$.

RESTRICTION

COMMON break: 47675

USE

CALL VEC

PZE X

PZE Y

COMMON output:

A dot product

CODING INFORMATION

Length of subroutine is 15 (10) or 17 (8) words.

IDENTIFICATION

102-1 of 2

WAIT

Michael R. Warner, JPL

Fortran II, Version 3

January 4, 1965

PURPOSE

WAIT obtains the a priori weight for each data point used in the normal equations.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

COL

DECOD

SQRT

WOCT

COS

ERROR

Error condition:

If the weight obtained is less than 10^{-20} , the program will abort.

METHOD

Method a1.

If a priori coefficients $\sqrt{\tilde{\omega}_j}$ are input to the program, the calculated weight is

$$\sqrt{\omega_j} = \sqrt{\tilde{\omega}_j} \beta_1 \beta_2 \sqrt{\frac{60}{\tau_s}}$$

where

$\beta_1 = 1$ when not weighting azimuth or hour angle

$= \frac{1}{\cos \gamma}$ when weighting azimuth angle

$= \frac{1}{\cos \delta}$ when weighting hour angle

$\beta_2 = 1$ when weighting azimuth angle

$= 1 + \frac{18}{(\gamma + 1)^2}$ when not weighting azimuth angle

τ_s = data sample rate

102-2 of 2

δ = declination

γ = elevation angle

Method a2.

If octal weight codes are input to the ODP a priori coefficient table, the program uses Method b.

Method b.

If octal weight codes are input by the ODG data file, and if no input was made to the ODP coefficient array, the calculated sigma is

$$\omega_j = \sum_{i=1}^6 S_{pjk}^2 g_{pj}^2 \max \left(\frac{T_{pjk}}{\tau}, 1 \right)$$

(see documentation for subroutines DECOD and COL).

USE

CALL WAIT

COMMON input:

BALNC $\sqrt{\omega_j}$ (12 x 15)

ID data type identification

IR receiver identification

SSQ S_{pjk}^2 (12 x 6 x 4)

TL T_{pjk} (12 x 6 x 4)

GSQ g_{pjk}^2 (6)

TAU τ (doppler averaging time, sec)

IF10 phi vector output flag

DEC δ , deg

EL γ , deg

TS τ_s , sec

COMMON output:

RVECW array of weights

CODING INFORMATION

Length of subroutine is 230 (10) or 346 (8) words.

REFERENCE

Hamilton, Thomas W., TM 312-182, April 12, 1962.

IDENTIFICATION

103

WASH

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

WASH prints certain time-dependent quantities which are calculated by the ODP (see list below). The subroutine is operative only in Mode-IV or the JPTRAJ production mode.

RESTRICTIONS

a. COMMON break: 47675

b. Subroutines used:

READB

FLAT/FLAPR

FIXT

PROUT

USE

CALL WASH

COMMON input:

TOB observation time, d. p. sec past 1950.0

GHA Greenwich hour angle, deg

X geocentric probe vector

XSUN geocentric Sun vector

XMOO geocentric Moon vector

XVEN geocentric Venus vector

XMAR geocentric Mars vector

CPPHI partials $\partial F/\partial Q$

CPTHT partials $\partial F/\partial \tilde{Q}$

U partials $\partial \underline{r}/\partial \underline{r}_0$

GMAT partials $\partial \underline{r}/\partial q$

DRVEC refraction corrections

CODING INFORMATION

Length of subroutine is 401 (10) or 621 (8) words.

IDENTIFICATION

104

WOCT

Michael R. Warner, JPL

IBM 7094 Fap

January 4, 1965

PURPOSE

WOCT determines whether an input a priori weight represents a floating point quantity or an octal weight code.

USE

| | | |
|------|------|--|
| CALL | WOCT | |
| PZE | WT | a priori weight word |
| PZE | CODE | output if octal code |
| PZE | TEST | = 0 if floating point ≠ 0 if octal code |

CODING INFORMATION

Length of subroutine is 11 (10) or 13 (8) words.

VII. OPERATING INSTRUCTIONS

The ODP may be operated in three modes: SFOF Mode II, SFOF Mode IV, and the JPTRAJ Production Mode. Mode II requires the full SFOF hardware configuration, namely, the 7094-disk-7040, with associated user-area equipment. Mode IV requires the 7094 and disk, properly initialized for SFOF operation. The JPTRAJ Production Mode is independent of the SFOF system, requiring only the 7094 and disk.

A. MODE II OPERATION

1. After the system has been initialized and the user programs loaded on disk, ask the operator to mount the following tapes:
 - A3 scratch for 1401 output
 - A4 scratch for combined ephemerides
 - B6 EPHEM system tape
 - B9 scratch for 4020 plot output (optional)
2. Type PS1X\$ at the user area 7 console.
3. Depress the TURN ON button, then the TRANSMIT MESSAGE button.
4. When requested by the administrative printer, enter the ODPX source deck via the user area card reader.
5. At the conclusion of PS1X, type ODPX\$ at the user-area 5 console.
6. Depress the TURN ON button, then the TRANSMIT MESSAGE button.
7. At the beginning of ODPX execution, the message ENTER SWITCHES. 22 = TERMINATE, 23 = DELAY, NONE = PROCEED will be printed by the administrative printer. To proceed, clear the switches and type ODPX\$ at the user area console.
8. Depress the OPTION SWITCH ENTRY button, then the TRANSMIT MESSAGE button.
9. When requested by the administrative printer, enter the input deck, as described in Section IV A, via the user area card reader. The program will then execute the options requested by the input deck.

10. To obtain the full SC-3070 printout, type 1\$ at the console, depress the AUTO ON button, then the TRANSMIT MESSAGE button.

11. The message described in step 7 will be printed between iterations. The user has the opportunity to read a new deck for the next iteration, or terminate ODP execution.

B. MODE IV OPERATION

1. After the system has been initialized and the user programs loaded on disk, mount the following tapes:

- A3 scratch for 1401 output
- A4 scratch for combined ephemeris
- B6 EPHEM system tape
- B7 scratch for MMP output (optional)
- B1 scratch for supplementary partials output (optional)
- B9 scratch for 4020 plot output (optional)

2. While the system is at the idle stop, depress sense switch 1 and depress START at the 7094 console.

3. At the card reader select, enter the card TURN ON, PS1X\$.

4. Raise sense switch 1.

5. At the card reader select, enter the ODPX source deck.

6. At the conclusion of PS1X (idle stop), depress sense switch 1 and depress START.

7. At the card reader select, enter the card TURN ON, ODPX\$.

8. Raise sense switch 1.

9. At the card reader select, enter the input deck, as described. The program will then execute the options requested by the input deck.

10. To obtain on-line printout, depress sense switch 6.

11. The card reader will select between iterations for additional input. If console key 22 is depressed at the end of an iteration, the execution will be terminated.

C. JPTRAJ PRODUCTION MODE OPERATION

1. Mount the following tapes:

- A1 JPTRAJ system tape
- A2 input tape (see below)
- A3 scratch for 1401 output
- A4 scratch for combined ephemeris
- A5 JPTRAJ program tape
- B1 scratch for system operation
- B6 EPHEM system tape
- B7 scratch for MMP output (optional)
- B9 scratch for 4020 plot output (optional)

2. The input tape should contain the following card images:

```

$JOB MRW, 2116000, 542-70285-1-3170, FC (example of
      JPL job card)
*      JPTRAJ
$RESTORE
*      DATA
      [ ODPX source deck ]
      [ ODPX input deck ]
      [ for iteration 1 ]
      .
      .
      .
      .
      .
      [ ODPX input deck ]
      [ for iteration n ]
      EOF card
$PAUSE
    
```

3. To start the system, depress the LOAD TAPE button at the 7094 console.
4. Once the program has been restored on disk, the ~~RESTORE~~ card and the A5 tape need not be used.

D. SOURCE DECK LISTING

JPL TECHNICAL MEMORANDUM NO. 33-204

ANALYSIS OF THE JPTRAJ SOURCE PROGRAM FOR THE ODP PROVIDES THE BASIC LOGIC OF THE PROGRAM. IN THE FOLLOWING THE STARRED ITEMS ARE DIRECTLY FROM THE SOURCE PROGRAM WHICH IS GIVEN IN COMPLETE FORM IN THE APPENDIX. NON-STANDARD EXITS FOR EACH LINK ARE EXPLAINED. THE STANDARD EXIT IS IN SEQUENCE.

```

*V1  ODPX  N9
      N9

*V9  LA9   X,N11,N1,N4
      X    TERMINATE JOB
      N11  USE SAME PROBE EPHEMERIS, SKIP TRAJ THIS PASS
      N1   RESTART FEATURE, TO RESET TO NOMINAL INPUT
      N4   USE SAME COMBINED EPHEMERIS, SKIP TO LINK 4
           THE CARD SWS=1 WILL CAUSE THE ODP TO READ THE INPUT
           DECK FROM TAPE A2. NORMAL INPUT IS BY ONLINE READER.

*V12 LA12  X
      X    TERMINATE JOB

*V13 SPACE X
      X    TERMINATE JOB

*V11 LA11  N6,N6,N12
      N4   EXIT TO PREDICT-DATA TAPE LINK
      N6   EXIT TO DATA FITTING LINK
      N12  EXIT TO LINK 12 FOR ERROR, THEN TO X

*V2  LA2   N12, X
      N12  EXIT TO LINK 12 FOR ERROR COMMENT, THEN TO X
      X    TERMINATE JOB

*V2A LA2A  N9,N12
      N9   STEP MAP COMPLETED, CHECK FOR MORE INPUT
      N12  EXIT TO LINK 12 FOR ERROR, THEN TO X

*V3  LA3   N9,N10
           (NO EXIT TO LINK 4)
      N9   IMPACT MAPPING COMPLETE, CHECK FOR MORE INPUT
      N10  COMMENT OUTPUT REQUESTED

*V4  LA4   N6,N12
      N6   NO SORTING NECESSARY, GO TO DATA FITTING LINK
      N12  EXIT TO LINK 12 FOR ERROR

*V5  LA5   N9,N12
           (NO EXIT TO LINK 6)
      N9   PREDICTS SORTED CHECK FOR MORE INPUT
      N12  EXIT TO LINK 12 FOR ERROR

*V6  LA6   N12
      N12  EXIT TO LINK 12 FOR ERROR

*V7  LA7   N9,N10,N12

      N9   RETURN FOR MORE INPUT, NO RESIDUALS, STATISTICS REQUESTED
      N10  EXIT HERE TO PRINT PARTIALS
      N12  ERROR EXIT

*V8  LA8   N9,N12
           (NO EXIT TO LINK 10)
      N9   RETURN FOR MORE INPUT
      N12  ERROR EXIT

*V10 LA10  N8,N9
           (NO EXIT TO LINK X)
      N8   AFTER PARTIALS PRINT RETURN TO LINK 8 FOR RESIDUALS
           AND STATISTICS
      N9   NO OTHER REQUESTS, RETURN TO INPUT LINK

*X   END
    
```

VIII. CHECK CASES

JPL TECHNICAL MEMORANDUM NO. 33-204

SOURCE PROGRAM LISTING

```

*N1  DDPX  N9
*N5  LA9   X,N11,N1,N4
55164/1.D516
*N12 LA12  X
*N13 SPACE X
      SCFORF=2
*   WANT  N9,(HOBPH11,200,(HOTOR,BROPT),18
*   WANT  N11,(TAPEX),5
*   WANT  N12,(XN1,INJX),1,(XN2-1,INJY),1
*   ETC    (XN2-2,INJZ),1,(XN3-3,INJX),1
*   ETC    (XN4-4,INJY),1,(XN5-5,INJZ),1
*   ETC    (EPOCH,INJT),1,(EPOCH-1,INJT+1),1
*   ETC    (DUT,GRAY-2),1,(AU,SCALE1),1
*   ETC    (RE,SCALE1),1,(PORE,HARMH+5),1
*   ETC    (OD,HARMH+4),1,(OH,HARMH+3),1
*   ETC    (OJ,HARMH+2),1,(ORAVE,GRAY),1
*   ETC    (GRAVM,GRAY+1),1,(GRAVS,GRAY+2),1
*   ETC    (GRAVV,GRAY+3),1,(GRAVR,GRAY+4),1
*   ETC    (GRAVJ,GRAY+6),1,(STEP,H),1
*   ETC    (TARGET,TARBCD),1,(AREH,RADDPF+3),1
*   ETC    (GMS,RADDPF+4),1,(FMSS,RADDPF+5),1
*   ETC    (FAD,GASOPT+9),1,(FBO,GASOPT+12)
*   ETC    (FCO,GASOPT+15),1,(FAL,GASOPT+8)
*   ETC    (FBI,GASOPT+11),1,(FCL,GASOPT+14)
*   ETC    (FAZ,GASOPT+7),1,(FBZ,GASOPT+10)
*   ETC    (FCZ,GASOPT+13),1,(JETON,GASOPT),1
*   ETC    (JETON,GASOPT+2),1,(JETON-1,GASOPT+3),1
*   ETC    (JETOFF,GASOPT+5),1,(JETOFF-1,GASOPT+6),1
*   ETC    (TFIN,SECP50),1,(TFIN-1,SECP50+1),1
*   ETC    (FMSS,GASOPT+16),1
GASOPT+1=(CANOPU)
INJBCO=(EARTH)
RADDPF=.103169
*N11  LA11  N4,N6,N12
*   WANT  N9,(C137),1
*   WANT  N13,(CLPT,TRADE+1),1,(CLPT+1,TRADE),1
*   ETC    (CLPBT,TRADE+2),1,(CLPBR,TRADE+3),1
*   ETC    (CLPBT,TRADE+4),1,(CLPBR,TRADE+5),1
*   ETC    (TAPEX),6
*N2   LA2   N12,X
*   WANT  N11,(EPOX),14
*N2A  LA2A  N9,N12
*N3   LA3   N9,N10
*N4   LA4   N6,N12
*N5   LA5   N9,N12
*N6   LA6   N12
*N7   LA7   N9,N10,N12
*   WANT  N9,(APRIDR-19,APRIDR-19),20
*N8   LA8   N9,N12
*N10  LA10  N8,N9
*x    END
    
```

THERE WERE NO GLARING SOURCE DECK ERRORS.
 THE OBJECT STRING HAS 00516 OCTAL OR 334 DECIMAL WORDS.

```

0000 134501 PAGE HEADING (23
0000 13450 IMARS CHECK CASE - FIT SIMULATED DATA, THEN MAP)
0000 13450 EPOCH (01
0000 13450 061102015.0757000
0000 13450 GEODETRIC POSITION AND VELOCITY AT EPOCH (02
0000 13450 X=.56082222E4 Y=.21966726E4 Z=-.32403740E4
0000 13450 DX=-.18839477E1 DY=-.10978654E2 DZ=-.12280548E1
0000 13450 OTHER OPTIONS AND CONSTANTS (03
0000 13450 TARGET=(IMARS)
0000 13450 INFO=3624200
0000 13450 ESTIMATE THESE PARAMETERS (04
0000 13450 X Y Z DX DY DZ MM AU
0000 13450 COVARIANCE MATRIX OF ESTIMATED PARANTERS (10
0000 13450 DIAG=10.,10.,10.,.01.,.01.,.01.,.1E-17,25.
0000 13450 POINTING TIMES, SAMPLE RATE, COUNT TIME (17
0000 13450 POINT=641102016,0,641103016,0,3600.,60.
0000 13450 JOBSET=641102016,0,641103016,0,3600.,60.
0000 13450 DATA FILE SIGMA (21
0000 13450 HA(4)=.001 DEC(4)=.002 CC(4)=.001
0000 13450 HA(5)=.002 DEC(5)=.001 CC(5)=.002
0000 13450 STATISTICS AND RESIDUALS FOR THESE DATA TYPES (14
0000 13450 HA(4)=.01 DEC(4)=.01 CC(4)=.01
0000 13450 HA(5)=.01 DEC(5)=.01 CC(5)=.01
0000 13450 WEIGHTS BY DATA TYPE AND STATION (16
0000 13450 HA(4)=.5 DEC(4)=.5 CC(4)=.1
0000 13450 HA(5)=.5 DEC(5)=.5 CC(5)=.1
0000 13450 TRANSMITTER ID TABLE (26
0000 13450 4,2038516,,641102916,0,5,2038516.
0000 13450 DEFINE CONTROL (27
0000 13450 KEY(2) KEY(14) KEY(16)
0000 13450 END DATA (0
    
```

JPL TECHNICAL MEMORANDUM NO. 33-204

INPUT COVARIANCE MATRIX OF ESTIMATED PARAMETERS ITERATION NUMBER 0

| | X | Y | Z | DX | DY | DZ | MN | AU |
|----|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| X | .10000000 02 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 |
| Y | -.00000000 00 | .10000000 02 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 |
| Z | -.00000000 00 | -.00000000 00 | .10000000 02 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 |
| DX | -.00000000 00 | -.00000000 00 | -.00000000 00 | .99999998-02 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 |
| DY | -.00000000 00 | .00000000 00 | .00000000 00 | -.00000000 00 | .99999998-02 | -.00000000 00 | -.00000000 00 | -.00000000 00 |
| DZ | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | .99999998-02 | -.00000000 00 | -.00000000 00 |
| MN | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | .00000000 00 | -.00000000 00 |
| AU | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.25000000 02 |

INPUT J MATRIX OF ESTIMATED PARAMETERS ITERATION NUMBER 0

| | X | Y | Z | DX | DY | DZ | MN | AU |
|----|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| X | .99999999-01 | .00000000 00 | -.00000000 00 | .00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 |
| Y | -.00000000 00 | .99999999-01 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 |
| Z | -.00000000 00 | -.00000000 00 | .99999999-01 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 |
| DX | -.00000000 00 | -.00000000 00 | -.00000000 00 | .10000000 03 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 |
| DY | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | .10000000 03 | -.00000000 00 | -.00000000 00 | -.00000000 00 |
| DZ | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | .10000000 03 | -.00000000 00 | -.00000000 00 |
| MN | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | .99999998 18 | -.00000000 00 |
| AU | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | -.00000000 00 | .99999999-01 |

CASE 1 IBSYS-JPTRAJ-SPACE 022265

DOUBLE PRECISION EPHEMERIS TAPE - EPHEM1

GME .39860063 06 J .16234500-02 H -.57499999-05 D .78749999-05 RE .63781650 04 REM .63783112 04
G .66709998-19 A .88781796 29 B -.8000194 29 C .8836976 29 GME .41780741-02 AU .14959850 09
GMH .49026293 04 GMS .13271611 12 GMV .32476627 04 GHA .42977368 05 GMC .37918700 08 GMJ .12670935 09
EGM .39860320 06 MGM .49027779 04 JA .29200000-02 HA .00000000 00 DA .00000000 00 RA .34170000 04
RADIATION PRESSURE INPUT
ARA .11120000 02 GB .95999999-01 MAS .25900000 03 G81 .00000000 00 G82 .00000000 00 SC .10310000 09

INJECTION CONDITIONS MARS 23570055142320220000000 J.D.= 2438728.13052083 NOV. 28,1964 15 07 57.000

GEOCENTRIC X0 .56682222 04 Y0 -.21466726 04 Z0 -.32403748 04 DX0 -.18839476 01 DY0 .10978654 02 DZ0 -.12280547 01
CARTESIAN T0 .54476999 05 GHA -.29452970 03 GHD -.66920765 02
DATE OF RUN 022265A 13660 EARTH IS THE CENTRAL BODY FOR INTEGRATION COWELL EQUATIONS OF MOTION

PROBE IS IN EARTH'S SHADOW

0 DAYS 0 HRS. 0 MIN. 0.000 SEC. 23570055142320220000000 J.D.= 2438728.13052083 NOV. 28,1964 15 07 57.000

GEOCENTRIC

| X | Y | Z | DX | DY | DZ | PTM | PTL | PTE | AZE | AZE | DZE | DZE | DZE | DZE | DZE | DZE | DZE | DZE |
|-----|---------------|-------------------|------------------|------------------|-------------------|-------------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| X | .56682219 04 | -.21466724 04 | -.32403747 04 | -.18839476 01 | .10978653 02 | -.12280547 01 | | | | | | | | | | | | |
| R | .68729157 04 | DEC -.28129771 02 | RA -.20742711 02 | V -.11206614 02 | PTH .12650650 02 | AL .90421379 02 | | | | | | | | | | | | |
| R | .68729154 04 | LAT -.28129772 02 | LMN .86213015 02 | VE .10775808 02 | PTE .13165318 02 | AZE .90439129 02 | | | | | | | | | | | | |
| XS | -.58995549 08 | YS -.12408705 09 | ZS -.53810146 08 | DXS .27792202 02 | DYS -.10840364 02 | DZS -.47011071 01 | | | | | | | | | | | | |
| XM | -.38253466 06 | YM -.44736395 05 | ZM .18645579 05 | DXM .37058146-01 | DYM -.92038371 00 | DZM -.41497853 00 | | | | | | | | | | | | |
| XT | -.19750066 09 | YT .58811766 08 | ZT .33854926 08 | DXT .87298950 01 | DYT -.21590059 02 | DZT -.91209471 01 | | | | | | | | | | | | |
| RS | -.14755881 09 | VS .30199675 02 | RH .38827148 06 | VH .10102904 01 | RT .20883364 09 | VT .25010665 02 | | | | | | | | | | | | |
| QED | -.28291871 02 | ALT .49950940 03 | LOS .31004216 03 | RAS .24457186 03 | RAM .18662395 03 | LDM .25209425 03 | | | | | | | | | | | | |
| QUT | -.35000000 02 | DT .37500000 01 | DR .24543145 01 | SHA .62358861 04 | DES -.21387223 02 | DEM .27525167 01 | | | | | | | | | | | | |
| CCL | .11901304 03 | MCL .21144471 03 | ICL .21574659 03 | | | | | | | | | | | | | | | |

EQUATORIAL COORDINATES

GEOCENTRIC CONIC

EPOCH OF PERICENTER PASSAGE 235700551326202356442400 J.D.= 2438728.12770659 NOV. 28,1964 15 03 53.850
SMA -.41536075 05 ECC .11580720 01 B .24259727 05 SLR .14169237 05 APO .00000000 00 RCA .65656922 04
VH .30978206 01 C3 .95964924 01 G1 .75152290 05 TFP .24314986 03 TF .28142345-02 LTF .25588951-01
TA .23551647 02 MTA .14971233 03 EA .64722201 01 MA .10390285 01 TFI .00000000 00

ALL VECTORS REFERENCED TO EARTH EQUATOR PLANE

| X | Y | Z | DX | DY | DZ | PTM | PTL | PTE | AZE | AZE | DZE | DZE | DZE | DZE | DZE | DZE | DZE | DZE |
|-----|---------------|------------------|-------------------|-------------------|-----------------------------------|-----------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| X | .56682219 04 | -.21466724 04 | -.32403747 04 | -.18839476 01 | .10978653 02 | -.12280547 01 | | | | | | | | | | | | |
| IHC | .28132666 02 | LAM .11163641 03 | APF .24556020 03 | MK -.35740510 00 | MY .93392694 00 | MZ .64857359-02 | | | | | | | | | | | | |
| WX | .43829295 00 | WY .17385475 00 | WZ .88185818 00 | PX .89883014 00 | PY .86854662-01 | PZ .42920527 00 | | | | | | | | | | | | |
| QX | .19040406-02 | QY .98093365 00 | QZ -.19433341 00 | RX .21994247 00 | RY .16164777 00 | RZ .96220662 00 | | | | | | | | | | | | |
| BX | .45496172 00 | BY .80323618 00 | BZ -.38447559 00 | TX .59221295 00 | TY .80578151 00 | TZ .00000000 00 | | | | | | | | | | | | |
| SX1 | -.77710383 00 | SY .41972693 00 | SZ1 -.46897637 00 | DAL -.27967872 02 | RAI .28374231 02 | | | | | | | | | | | | | |
| SX0 | -.77518326 00 | SY0 .56972462 00 | SZ0 .27295548 00 | OAO .15840210 02 | RAO .14368579 03 | | | | | | | | | | | | | |
| BTQ | .24222576 05 | BRQ .13420740 04 | B .24259727 05 | THA .31712828 01 | T V VECTOR IN EARTH EQUATOR PLANE | | | | | | | | | | | | | |

ALL VECTORS REFERENCED TO ECLIPTIC PLANE

| X | Y | Z | DX | DY | DZ | PTM | PTL | PTE | AZE | AZE | DZE | DZE | DZE | DZE | DZE | DZE | DZE | DZE |
|-----|--------------|------------------|------------------|------------------|-----------------|------------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| X | .56682219 04 | -.21466724 04 | -.32403747 04 | -.18839476 01 | .10978653 02 | -.12280547 01 | | | | | | | | | | | | |
| IHC | .42277832 02 | LAM .13934368 03 | APF .21231137 03 | MK -.35740509 00 | MY .85425011 00 | MZ -.37751597 00 | | | | | | | | | | | | |
| WX | .43829294 00 | WY .51035282 00 | WZ .78980141 00 | PX .89883011 00 | PY .25060393 00 | PZ .35958584 00 | | | | | | | | | | | | |
| QX | .19040406-02 | QY .82264062 00 | QZ -.56855842 00 | RX .18420546-01 | RY .15001224-01 | RZ .99971770 00 | | | | | | | | | | | | |
| 8X | .45496171 00 | 8Y .58396360 00 | 8Z -.67230674 00 | TX .63146777 00 | TY .77540212 00 | TZ .00000000 00 | | | | | | | | | | | | |

JPL TECHNICAL MEMORANDUM NO. 33-204

CASE 1

IBSYS-JPIRAJ-SPACE 022265

SX1 .77710380 00 SY1 .19849447 00 SZ1 -.59725159 00 DAI -.36673309 02 RA1 .14328600 02
 SX0 -.77518323 00 SY0 .63128952 00 SZ0 -.23756120-01 DAO .13612515 01 RAO .14084150 03
 BTC .22379497 05 BRC -.93644235 04 B .24259727 05 THA .33729373 03 T VECTOR IN ECLIPTIC PLANE
 HELIOCENTRIC ECLIPTIC COORDINATES
 X .59001217 08 Y .13525276 09 Z -.41570000 04 DX -.29676149 02 DY .21399603 02 DZ -.56944124 01
 A .14756169 09 LAT -.16140947-02 LON .66431758 02 V .36997370 02 PTH .12089898 02 AZ .98735356 02
 XE .58995549 08 YE .13525209 09 ZE -.33000000 03 DXE -.27792202 02 DYE .11815832 02 DZE .15556812-03
 XT -.13850512 09 YT .20267817 09 ZT -.76614060 07 DXT -.19052307 02 DYT -.11620746 02 DZT .22182012 00
 LTE -.12813608-03 LOE .66433669 02 LTT .17875885 01 LDT .12434771 03 RST .24560294 09 VST .22326273 02
 EPS .65134214 02 ESP .13988227-01 SEP .11486336 03 EPH .28249721 02 EMP .48000350 00 MEP .15127023 03
 MPS .61567036 02 MSP .13507880 00 SHP .11829015 03 SEM .61571418 02 EMS .11829583 03 ESM .13270400 00
 EPT .39785299 02 ETP .27453512-18 TEP .14021349 03 TSP .85283946 02 TYP .57933486 02 STP .36782563 02
 SET .85286588 02 STE .36781888 02 EST .57931519 02 RPM .39431215 06 RPT .20883893 09 SPN .-29894790 01
 SAC .22280601-09
 GCE .24098695 03 GCT .27673355 03 SIP .85283019 02 CPT .34329569 02 SIN .84328642 02
 REP .68729157 04 VFP .11206614 02 CPE .12085570 03 CPS .10111911 03
 0 DAYS 0 HRS. 9 MIN. 49.244 SEC. 235700551646202437164374 J.D.= 2438728.13734078 NOV. 28,1964 15 17 46.244
 PROBE IS LEAVING EARTH'S SHADOW
 2 DAYS 0 HRS. 52 MIN. 3.000 SEC. 235700677340202000000000 J.D.= 2438730.16666666 NOV. 30,1964 16 00 00.000
 0 DAYS 0 HRS. 52 MIN. 18.000 SEC. 23570067734320260000000000 J.D.= 2438730.16684028 NOV. 30,1964 16 00 15.000
 215542322602 214412016141 614626031437 601731456722 204537405524 601471557132 EARTH
 21149808915 17481059072 000000000000 INITIAL
 623733473151 223571732535 222507660544 602504407717 201741457741 200715435157 EARTH
 235700677343 202600000000 END

J MATRIX ITERATION NUMBER 1

| | X | Y | Z | DX | DY | DZ | MM | AU |
|----|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| X | .86586481 07 | .34045452 07 | -.50691355 07 | -.21792881 10 | .13770335 11 | -.15816493 10 | .23125263 07 | -.77185333-04 |
| Y | .34045452 07 | .13396596 07 | -.19929949 07 | -.85587537 09 | .54135596 10 | -.62224241 09 | .91247442 06 | -.30475400-04 |
| Z | -.50691355 07 | -.19929949 07 | .29680390 07 | .12758964 10 | -.80622930 10 | -.92586914 09 | -.13449765 07 | .45040778-04 |
| DX | -.21792881 10 | -.85587537 09 | -.12758964 10 | .54958336 12 | -.34665872 13 | .39774309 12 | -.58092013 09 | .19371962-01 |
| DY | .13770335 11 | .54135596 10 | .80622930 10 | -.34665872 13 | .21901237 14 | -.25151332 13 | .36716555 10 | -.12253934 00 |
| DZ | -.15816493 10 | -.62224241 09 | .92586914 09 | .39774309 12 | -.25151332 13 | .28909285 12 | -.42327558 09 | .14149069-01 |
| MM | .23125263 07 | .91247442 06 | -.13449765 07 | -.58092013 09 | .36716555 10 | -.42327558 09 | .99999998 18 | -.29593198-04 |
| AU | -.77185333-04 | -.30475400-04 | .45040778-04 | -.19371962-01 | -.12253934 00 | .14149069-01 | -.29593198-04 | .39999999-01 |

CORRELATIONS BASED ON J MATRIX ITERATION NUMBER 1

| | X | Y | Z | DX | DY | DZ | MM | AU |
|----|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| X | -.10000000 01 | -.99962436 00 | .99994028 00 | -.99901687 00 | -.99996582 00 | .99969255 00 | -.78588977-06 | .13115346-06 |
| Y | -.99962436 00 | -.10000000 01 | .99948009 00 | -.99746235 00 | -.99942768 00 | .99987035 00 | -.78835797-06 | .13116504-06 |
| Z | .99994028 00 | .99948009 00 | -.99999999 00 | -.99899622 00 | .99997574 00 | -.99953067 00 | .78359453-06 | -.13071971-06 |
| DX | .99901687 00 | .99746235 00 | -.99899622 00 | -.10000000 01 | .99919678 00 | -.99785440 00 | .78360940-06 | -.13065524-06 |
| DY | -.99996582 00 | -.99942768 00 | .99997574 00 | .99919678 00 | -.10000000 01 | .99955799 00 | -.78456262-06 | .13092157-06 |
| DZ | .99969255 00 | .99948009 00 | -.99953067 00 | -.99785440 00 | .99955799 00 | -.10000000 01 | .78723525-06 | -.13157676-06 |
| MM | -.78588977-06 | -.78835797-06 | .78359453-06 | .78360940-06 | -.78456262-06 | .78723525-06 | -.10000000 01 | -.14796599-12 |
| AU | .13115346-06 | .13116504-06 | -.13071971-06 | -.13065524-06 | .13092157-06 | -.13157676-06 | .14796599-12 | -.10000000 01 |

MARS CHECK CASE - FIT SIMULATED DATA, THEN MAP

| ITERATION NUMBER | 1 | EPOCH 64/11/28 150757.000 | CLOCK 135150 | SOS .20501 00 | QSOS .20501 00 | | |
|------------------|---------------|---------------------------|----------------|---------------|----------------|---------------|---------------|
| Q | DD | STDEVQ | APRIORI STDEVQ | OLD Q | NEW Q | NOMINAL Q | DOINGM |
| X | -.11623597-01 | .75099736 00 | .31622776 01 | -.56682222 04 | .56682105 04 | -.56682222 04 | -.11596680-01 |
| Y | .13752168-01 | .25575302 00 | .31622776 01 | -.21465726 04 | .21466863 04 | -.21466726 04 | -.13763428-01 |
| Z | -.57554049-02 | .77465767 00 | .31622776 01 | -.32403748 04 | -.32403805 04 | -.32403748 04 | -.57678223-02 |
| DX | -.15225409-04 | .57259488-03 | .99999999-01 | -.18839477 01 | -.18839629 01 | -.18839477 01 | -.15228987-04 |
| DY | -.74521106-06 | .78780906-03 | .99999999-01 | -.10978654 02 | .10978653 02 | -.10978654 02 | -.71525574-06 |
| DZ | -.12002572-05 | .75434680-03 | .99999999-01 | -.12280548 01 | -.12280560 01 | -.12280548 01 | -.12069941-05 |
| MM | -.34015613-17 | .99999997-09 | .99999997-09 | -.32383419-06 | .32383419-06 | -.32383419-06 | -.35527136-14 |
| AU | .28060658-08 | .50000000 01 | .50000000 01 | -.14959850 09 | .14959850 09 | -.14959850 09 | -.00000000 00 |

JPL TECHNICAL MEMORANDUM NO. 33-204

| J INVERSE | | ITERATION NUMBER 1 | | | | | | |
|-----------|---------------|--------------------|---------------|---------------|---------------|---------------|---------------|---------------|
| | X | Y | Z | DX | DY | DZ | HM | AU |
| X | -.62999675-01 | -.59524518-01 | -.11556153 00 | -.11487003-03 | -.47341748-04 | -.10028577-03 | -.12224223-16 | -.16363926-07 |
| Y | -.59524518-01 | -.65409607-01 | -.67366365-01 | -.88619571-04 | -.22914837-04 | -.46559043-04 | -.28395455-16 | -.18269573-07 |
| Z | -.11556153 00 | -.67366365-01 | -.60009450 00 | -.42117713-03 | -.29749136-03 | -.57407415-03 | -.27951063-15 | -.26668629-06 |
| DX | -.11487003-03 | -.88619571-04 | -.42117713-03 | -.32786490-06 | -.20192139-06 | -.39447369-06 | -.14904260-18 | -.14775477-09 |
| DY | -.47341748-04 | -.22914837-04 | -.29749136-03 | -.20192139-06 | -.15039588-06 | -.28756925-06 | -.14411435-18 | -.13669769-09 |
| DZ | -.10028577-03 | -.46559043-04 | -.57407415-03 | -.39447369-06 | -.28756925-06 | -.56903910-06 | -.28010333-18 | -.25951601-09 |
| HM | -.12224223-16 | -.28395455-16 | -.27951063-15 | -.14904260-18 | -.14411435-18 | -.28010333-18 | -.99999998-18 | -.21195486-22 |
| AU | -.16363926-07 | -.18269573-07 | -.26668629-06 | -.14775477-09 | -.13669769-09 | -.25951601-09 | -.21195486-22 | -.25000000 02 |

| COVARIANCE MATRIX OF ESTIMATED PARAMETERS | | ITERATION NUMBER 1 | | | | | | |
|---|---------------|--------------------|---------------|---------------|---------------|---------------|---------------|---------------|
| | X | Y | Z | DX | DY | DZ | HM | AU |
| X | -.62999675-01 | -.59524518-01 | -.11556153 00 | -.11487003-03 | -.47341748-04 | -.10028577-03 | -.12224223-16 | -.16363926-07 |
| Y | -.59524518-01 | -.65409607-01 | -.67366365-01 | -.88619571-04 | -.22914837-04 | -.46559043-04 | -.28395455-16 | -.18269573-07 |
| Z | -.11556153 00 | -.67366365-01 | -.60009450 00 | -.42117713-03 | -.29749136-03 | -.57407415-03 | -.27951063-15 | -.26668629-06 |
| DX | -.11487003-03 | -.88619571-04 | -.42117713-03 | -.32786490-06 | -.20192139-06 | -.39447369-06 | -.14904260-18 | -.14775477-09 |
| DY | -.47341748-04 | -.22914837-04 | -.29749136-03 | -.20192139-06 | -.15039588-06 | -.28756925-06 | -.14411435-18 | -.13669769-09 |
| DZ | -.10028577-03 | -.46559043-04 | -.57407415-03 | -.39447369-06 | -.28756925-06 | -.56903910-06 | -.28010333-18 | -.25951601-09 |
| HM | -.12224223-16 | -.28395455-16 | -.27951063-15 | -.14904260-18 | -.14411435-18 | -.28010333-18 | -.99999998-18 | -.21195486-22 |
| AU | -.16363926-07 | -.18269573-07 | -.26668629-06 | -.14775477-09 | -.13669769-09 | -.25951601-09 | -.21195486-22 | -.25000000 02 |

| CORRELATION MATRIX OF ESTIMATED PARAMETERS | | ITERATION NUMBER 1 | | | | | | |
|--|---------------|--------------------|---------------|---------------|---------------|---------------|---------------|---------------|
| | X | Y | Z | DX | DY | DZ | HM | AU |
| X | .99999999 00 | -.92726948 00 | -.59433910 00 | -.79926371 00 | -.48635924 00 | -.52966234 00 | -.48702594-07 | .13039122-07 |
| Y | -.92726948 00 | 1.00000000 01 | -.34002631 00 | -.60514773 00 | -.23103514 00 | -.24133051 00 | -.11102686-06 | -.14286888-07 |
| Z | -.59433910 00 | -.34002631 00 | 1.00000000 01 | -.94952738 00 | -.94025392 00 | -.98239720 00 | -.36031826-06 | -.68852682-07 |
| DX | -.79926371 00 | -.60514773 00 | -.94952738 00 | 1.00000000 01 | -.90932032 00 | -.91327070 00 | -.26029327-06 | -.51608834-07 |
| DY | -.48635924 00 | -.23103514 00 | -.94025392 00 | -.90932032 00 | 1.00000000 01 | -.98299978 00 | -.37161160-06 | -.70497417-07 |
| DZ | -.52966234 00 | -.24133051 00 | -.98239720 00 | -.91327070 00 | -.98299978 00 | 1.00000000 01 | -.37131904-06 | -.68805492-07 |
| HM | -.48702594-07 | -.11102686-06 | -.36031826-06 | -.26029327-06 | -.37161160-06 | -.37131904-06 | 1.00000000 01 | -.99999999 00 |
| AU | .13039122-07 | -.14286888-07 | -.68852682-07 | -.51608834-07 | -.70497417-07 | -.68805492-07 | -.99999999 00 | 1.00000000 01 |

STATION NUMBER 41 64/11/28 ITERATION NUMBER 1 PASS NUMBER 000000 PAGE 1
 FREQUENCY Z038516.0

| TIME | TC | Q | DEC | HA | CC3 |
|--------|----|----|-----------------------|-----------------------------|-----------------------------|
| 160000 | 60 | 41 | -.78431416 01 .652-01 | -.0009 .32882011 03 .659-01 | .0012 .28456650 05 .130-01 |
| 170000 | 60 | 41 | 1.0831269 02 .652-01 | -.0016 .33477567 03 .664-01 | .0007 .23700862 05 .130-01 |
| 180000 | 60 | 41 | -.12099763 02 .652-01 | -.0016 .34648760 03 .667-01 | .0015 .21835252 05 .130-01 |
| 190000 | 60 | 41 | -.12798196 02 .652-01 | -.0012 .35971234 03 .667-01 | -.0025 .20948827 05 .130-01 |
| 200000 | 60 | 41 | 1.3218797 02 .652-01 | .0010 .13594732 02 .669-01 | .0000 .20512531 05 .130-01 |
| 210000 | 60 | 41 | -.13479367 02 .654-01 | -.0007 .27772787 02 .671-01 | -.0011 .20302005 05 .131-01 |
| 220000 | 60 | 41 | -.13639556 02 .657-01 | -.0013 .42085743 02 .676-01 | -.0001 .20195438 05 .132-01 |
| 230000 | 60 | 41 | -.13732021 02 .674-01 | -.0003 .56446052 02 .693-01 | .0006 .20116875 05 .135-01 |

64/11/29

| | | | | | |
|--------|----|----|-----------------------|-----------------------------|-----------------------------|
| 000000 | 60 | 41 | 1.3762374 02 .774-01 | -.0016 .70780797 02 .796-01 | .0010 .20016154 05 .155-01 |
| 150000 | 60 | 41 | 1.14855666 02 .784-01 | .0005 .28953924 03 .813-01 | -.0007 .14764306 05 .157-01 |
| 160000 | 60 | 41 | 1.14977514 02 .674-01 | .0024 .30453431 03 .696-01 | .0001 .14926591 05 .135-01 |

FREQUENCY .0

| | | | | | |
|--------|----|---|-----------------------|-----------------------------|--------|
| 170000 | 60 | 0 | 1.15058219 02 .657-01 | -.0033 .31962313 03 .681-01 | -.0019 |
| 180000 | 60 | 0 | 1.15117300 02 .654-01 | -.0001 .33475542 03 .676-01 | -.0007 |
| 190000 | 60 | 0 | 1.15157664 02 .652-01 | -.0009 .34909000 03 .676-01 | .0006 |
| 200000 | 60 | 0 | 1.15180484 02 .652-01 | -.0009 .50660299 01 .674-01 | .0013 |
| 210000 | 60 | 0 | 1.15187077 02 .652-01 | .0027 .20210603 02 .678-01 | .0010 |

FREQUENCY Z038516.0

| | | | | | |
|--------|----|----|-----------------------|-----------------------------|--------|
| 220000 | 60 | 51 | 1.15178905 02 .657-01 | -.0023 .35328527 02 .679-01 | -.0004 |
| 230000 | 60 | 51 | 1.15156356 02 .667-01 | -.0012 .50405889 02 .691-01 | .0006 |

64/11/30

| | | | | | |
|--------|----|----|-----------------------|-----------------------------|--------|
| 000000 | 60 | 51 | 1.15119074 02 .715-01 | .0000 .65427979 02 .740-01 | -.0003 |
| 010000 | 60 | 51 | 1.14819789 02 .111 01 | -.0010 .79978701 02 .115 01 | -.0003 |

FREQUENCY .0

| | | | | | |
|--------|----|---|-----------------------|-----------------------------|--------|
| 150000 | 60 | 0 | 1.15275558 02 .798-01 | -.0010 .28933294 03 .828-01 | -.0008 |
| 160000 | 60 | 0 | 1.15356074 02 .674-01 | -.0035 .30433643 03 .698-01 | -.0008 |

JPL TECHNICAL MEMORANDUM NO. 33-204

| MARINER STATISTICS | | | STATION 41 | | | | ITERATION 1 | | |
|--------------------|-----------|----------------|--------------|------------------|---------|---------|--------------|---------------|--|
| PASS | DATA TYPE | BEGINNING TIME | END TIME | NUMBER OF POINTS | STD DEV | RMS | FIRST MOMENT | SECOND MOMENT | |
| 000000 | CC3 | 11/28-160000 | 11/29-160000 | 11 | .574-03 | .589-03 | .133-03 | .347-06 | |
| | HA | 11/28-160000 | 11/30-160000 | 22 | .101-02 | .101-02 | -.461-04 | .103-05 | |
| | DEC | 11/28-160000 | 11/30-160000 | 22 | .158-02 | .165-02 | -.459-03 | .271-05 | |

STATION NUMBER 51 64/11/28 ITERATION NUMBER 1 PASS NUMBER 000000 PAGE 2

FREQUENCY2038516.0

| TIME | TC | Q | DEC | HA | CC3 | | | |
|--------------------|----|----|----------------------|--------|-----------------------|--------|-----------------------|--------|
| 220000 | 60 | 41 | .13129207 02 .735-01 | .0017 | -28861228 03 .754-01 | .0004 | | |
| 230000 | 60 | 41 | .13532427 02 .667-01 | .0005 | -30329097 03 .686-01 | .0046 | | |
| 64/11/29 | | | | | | | | |
| 000000 | 60 | 41 | .13838208 02 .654-01 | -.0009 | -31818084 03 .674-01 | -.0044 | | |
| FREQUENCY .0 | | | | | | | | |
| 010000 | 60 | 0 | .14068252 02 .652-01 | .0010 | .33319524 03 .671-01 | .0026 | | |
| 020000 | 60 | 0 | .14235436 02 .649-01 | -.0008 | .34827475 03 .671-01 | .0005 | | |
| 030000 | 60 | 0 | .14349870 02 .649-01 | .0002 | .33738108 01 .671-01 | .0035 | | |
| 040000 | 60 | 0 | .14420789 02 .652-01 | .0005 | .18457121 02 .671-01 | -.0048 | | |
| 050000 | 60 | 0 | .14456847 02 .652-01 | .0009 | .33498143 02 .674-01 | .0005 | | |
| 060000 | 60 | 0 | .14465484 02 .659-01 | -.0010 | .48477208 02 .681-01 | .0005 | | |
| 070000 | 60 | 0 | .14461425 02 .684-01 | .0015 | .63393088 02 .706-01 | .0007 | | |
| 080000 | 60 | 0 | .14359558 02 .112 00 | -.0004 | .78067596 02 .116 00 | .0057 | | |
| FREQUENCY2038516.0 | | | | | | | | |
| 220000 | 60 | 51 | .14953242 02 .857-01 | -.0002 | .28509123 03 .886-01 | -.0014 | .14302250 05 .172-01 | .0009 |
| 230000 | 60 | 51 | .15068582 02 .676-01 | .0000 | .30005508 03 .698-01 | .0017 | -.14459947 05 .135-01 | .0001 |
| 64/11/30 | | | | | | | | |
| 000000 | 60 | 51 | .15137918 02 .657-01 | -.0019 | .31513791 03 .681-01 | -.0009 | .14735132 05 .132-01 | -.0002 |
| 010000 | 60 | 51 | .15189322 02 .652-01 | -.0002 | .33026529 03 .676-01 | -.0031 | -.15106839 05 .131-01 | .0021 |
| 020000 | 60 | 51 | .15225421 02 .649-01 | .0009 | .34541624 03 .674-01 | .0017 | .15546990 05 .130-01 | -.0020 |
| 030000 | 60 | 51 | .15246021 02 .649-01 | .0002 | .57495905 00 .674-01. | .0012 | .16022491 05 .130-01 | .0007 |
| 040000 | 60 | 51 | .15254266 02 .652-01 | .0004 | .15727202 02 .674-01 | .0012 | .16497762 05 .130-01 | -.0017 |
| 050000 | 60 | 51 | .15248872 02 .652-01 | .0009 | .30859974 02 .676-01 | -.0003 | .16937468 05 .131-01 | .0029 |
| 060000 | 60 | 51 | .15231617 02 .659-01 | -.0003 | .45960994 02 .681-01 | .0005 | .17309181 05 .132-01 | .0002 |
| 070000 | 60 | 51 | .15206400 02 .679-01 | -.0001 | .61013895 02 .703-01 | -.0045 | -.17585710 05 .135-01 | -.0012 |
| 080000 | 60 | 51 | .15120052 02 .925-01 | -.0006 | .75933573 02 .959-01 | -.0002 | .17746981 05 .185-01 | .0010 |

| MARINER STATISTICS | | | STATION 51 | | | | ITERATION 1 | | |
|--------------------|-----------|-----------------|--------------|------------------|---------|---------|--------------|---------------|--|
| PASS | DATA TYPE | BEGINNING TIME | END TIME | NUMBER OF POINTS | STD DEV | RMS | FIRST MOMENT | SECOND MOMENT | |
| 000000 | CC3 | 11/29-220000 | 11/30-080000 | 11 | .144-02 | .146-02 | .255-03 | .213-05 | |
| | HA | 11/28-220000 | 11/30-080000 | 22 | .267-02 | .269-02 | .334-03 | .722-05 | |
| | DEC | 11/28-220000 | 11/30-080000 | 22 | .794-03 | .850-03 | .303-03 | .723-06 | |
| 0000 | 135231 | OFFLINE CONTROL | | | | 127 | | | |
| 0000 | 13523 | KEY(5) | | | | | | | |
| 0000 | 13523 | END DATA | | | | ID | | | |

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DOUBLE PRECISION EPHEMERIS TAPE - EPHEM1
GME .39800063 06 J .16234500-02 H -.57499989-05 D .78749999-05 RE .63781650 04 REN .63783112 04
G .66709998-19 A .88781796 29 B .88800194 29 C .88836976 29 DHE .41780741-02 AU .14959850 09
GMN .49026293 04 GMS .13271411 12 GNV .32476627 06 GHA .42977367 05 GMC .37918700 08 GMJ .12670935 09
EGM .39863020 06 EGM .49027779 04 JA .29200000-02 HA .00000000 00 DAK .00000000 00 RA .34170000 04
RADIATION PRESSURE INPUT
ARA .11120000 02 GB .95999999-01 MAS .25900000 03 G81 .00000000 00 G82 .00000000 00 SC .10310000 09
INJECTION CONDITIONS MARS 23570055142320220000000 J.D.= 2438728.13052083 NOV. 28,1964 15 07 57.000
GEOCENTRIC X0 .56682105 04 Y0 .21466863 04 Z0-.32403805 04 DX0-.18839629 01 DY0 .10978653 02 DZ0-.12280559 01
CARTESIAN T0 .54476999 05 GHA .29452970 03 GHD .66920765 02
DATE OF RUN 022265A 13525 EARTH IS THE CENTRAL BODY FOR INTEGRATION COMWELL EQUATIONS OF MOTION

PROBE IS IN EARTH'S SHADOW
0 DAYS 0 HRS. 0 MIN. 0.000 SEC. 23570055142320220000000 J.D.= 2438728.13052083 NOV. 28,1964 15 07 57.000
GEOCENTRIC EQUATORIAL COORDINATES
X .56682103 04 Y .21466862 04 Z -.32403804 04 DX -.18839629 01 DY .10978653 02 DZ -.12280559 01
R .68729131 04 DEC -.28129837 02 RA .20742872 02 V .11206616 02 PTH .12650726 02 AZ .90421329 02
R .68729129 04 LAT -.28129838 02 LON .862131175 02 VE .10775811 02 PTE .13165397 02 AZE .90439077 02
XS -.58995549 08 YS -.12408705 09 ZS -.53810146 08 OXS .27792202 02 OYS -.10840364 02 OZS -.47810171 01
XM -.38523466 06 YM -.44736395 05 ZM .18645579 05 OXM .37058146-01 OYM -.92038371 00 OZM -.41497853 00
XT -.19750066 09 YT .58811766 08 ZT .33854926 08 OXT .87298950 01 OYT -.21590059 02 OZT -.91209471 01
RS .14755881 09 VS .30199675 02 RM .38827148 06 VM .10102904 01 RT .20885304 09 VT .25010665 02
GEO .-28291938 02 ALT .49950689 03 LOS .31004216 03 RAS .24451186 03 RAH .18662395 03 LDH .25209425 03
DUT .35000000 02 DT .37500000 01 DR .24543294 01 SHA .62358811 04 DES .-21387223 02 DEM .27525167 01
CCL .11901320 03 NCL .21144487 03 TCL .21574675 03

GEOCENTRIC CUNIC
EPOCH OF PERICENTER PASSAGE 23570055132620235632500 J.D.= 2438728.12770658 NOV. 28,1964 15 03 53.849
SMA -.41536060 05 ECC .11580719 01 B .24259711 05 SLR .14169223 05 APO .00000000 00 RCA .65658662 04
VH .30978211 01 C3 .95864959 01 CL .75152253 05 TFP .24315096 03 TF .-28142471-02 LTF .-25588937-01
TA .23551788 02 MTA .14971234 03 EA .64722590 01 MA .10390338 01 TF1 .00000000 00

ALL VECTORS REFERENCED TO EARTH EQUATOR PLANE
X .56682103 04 Y .21466862 04 Z -.32403804 04 DX -.18839629 01 DY .10978653 02 DZ -.12280559 01
INC .28132733 02 LAN .11163647 03 APF .24566016 03 WK .-35740735 00 PY .-86854203-01 PZ .-42960603 00
MX .43829371 00 MY .17385584 00 WZ .88185763 00 PX .89882977 00 RY .16164795 00 RZ .96202654 00
GX .19036569-02 QY .98093352 00 QZ .-19433418 00 RX .-21994273 00 RY .16164795 00 RZ .96202654 00
BX .45496110 00 BY .00323605 00 BZ .-38447660 00 TX .59221295 00 TY .80578150 00 TZ .00000000 00
SXI .77710339 00 SYI .41972664 00 SZI .-46897743 00 DAI .-27967940 02 RAI .28374228 02
SDX .-77518320 00 SYD .56972458 00 STD .27295579 00 DAD .15840229 02 RAD .14368579 03
BTQ .24222561 05 BRQ .13420647 04 B .24259711 05 THA .31712632 01 T VECTOR IN EARTH EQUATOR PLANE
ALL VECTORS REFERENCED TO ECLIPTIC PLANE
X .56682103 04 Y .68028036 03 Z -.38269499 04 DX -.18839629 01 DY .95837699 01 DZ -.54945689 01
INC .42277902 02 LAN .13934386 03 APF .21231139 03 MX .-35740735 00 MY .85424963 00 MZ .-37751494 00
WX .43829370 00 WY .51035333 00 WZ .73989060 00 PX .89882980 00 PY .25060437 00 PZ .-35958650 00
GX .19036569-02 QY .82264020 00 QZ .-56855910 00 RX .-18420855-01 RY .15001476-01 RZ .99971775 00
BX .45496101 00 BY .58376315 00 BZ .-67230762 00 TX .63146777 00 TY .77540213 00 TZ .00000000 00

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SXI .77710346 00 SYI .19849367 00 SZI .-59725243 00 DAI .-36673369 02 RAI .14328550 02
SDX .-77518328 00 SYD .63128954 00 STD .23756519-01 DAD .13612746 01 RAD .14084150 03
BTC .22379481 05 BRC .-93644400 04 B .24259718 05 THA .33729368 03 T VECTOR IN ECLIPTIC PLANE
HELIOCENTRIC ECLIPTIC COORDINATES
X .59901217 08 Y .13525276 09 Z -.41570000 04 DX -.29676165 02 DY .21399602 02 DZ -.54944132 01
R .14750169 09 LAT .-16140947-02 LON .66643178 02 V .36997382 02 PTH .12089884 02 AZ .98735355 02
XE .58995549 08 YE .13525209 09 ZE .-33000000 03 DXE .-27792202 02 DYE .11815832 02 DZE .15556812-03
XT .-13850512 09 YT .20267817 09 ZT .76614060 07 DXT .-19062307 02 DYT .-11620746 02 DZT .22182012 00
LTE .12813608-03 LDE .66493669 02 LTF .17875885 01 LDT .12644771 03 RST .24560294 09 VST .22326273 02
EPS .65134159 02 ESP .13988227-01 SEP .11486342 03 EPH .28249846 02 EHP .47990158 00 MEP .15127010 03
MPS .61567035 02 MWP .13507800 00 SPP .11829816 03 SEP .61571418 02 EHS .11829583 03 ESM .13270400 00
EPT .39785456 02 ETP .27453512-18 TEP .14021333 03 TPS .85283946 02 TSP .57933486 02 STP .36782563 02
SET .85286588 02 STE .36781888 02 EST .57931519 02 RPM .39431214 06 RPT .20883893 09 SPN .-29895868 01
SAC .22280601-09 GCT .27673355 03 SIP .85283019 02 CPT .84329569 02 SIN .84328642 02
GCE .24098679 03 VEP .11206616 02 CPE .12085585 03 CPS .10111911 03
REP .68729131 04
0 DAYS 0 HRS. 9 MIN. 49.241 SEC. 23570055166202436644705 J.D.= 2438728.13734075 NOV. 28,1964 15 17 46.241
PROBE IS LEAVING EARTH'S SHADOW
8 DAYS 19 HRS. 24 MIN. 2.979 SEC. 235701335107202775352514 J.D.= 2438736.93888865 DEC. 7,1964 10 31 59.980
8 DAYS 19 HRS. 24 MIN. 2.979 SEC. 235701335107202775352514 J.D.= 2438736.93888865 DEC. 7,1964 10 31 59.980
CHANGE OF PHASE OCCURS AT THIS POINT SUN IS THE CENTRAL BODY FOR INTEGRATION COMWELL EQUATIONS OF MOTION
225 DAYS 2 HRS. 44 MIN. 31.060 SEC. 235723202427202007527522 J.D.= 2438953.24476920 JULY 11,1965 17 52 28.060

GEOCENTRIC EQUATORIAL COORDINATES
X .-20952635 09 Y .-22337826 08 Z .-94661789 07 DX .-13367881 02 DY .-23273616 02 DZ .-10141585 02
R .21092624 09 DEC .-25722458 01 RA .18600537 03 V .28691692 02 PTH .34373873 02 AZ .11345038 03
R .21092624 09 LAT .-25722458 01 LON .34854236 03 VE .15343772 05 PTE .60490716-01 AZE .26996480 03
XS .-50004426 08 YS .13176278 09 ZS .57140097 08 OXS .-27634650 02 OYS .-88887630 01 OZS .-38558931 01
XM .-16125000 05 YM .36611200 06 ZM .-16854550 06 OXM .97207475 00 OYM .-20357370-01 OZM .10283720 00
XT .-21150188 09 YT .-22632994 08 ZT .-93652949 07 DXT .-92234842 01 DYT .-22096207 02 DZT .10412922 02
RS .15207919 09 VS .29283887 02 RM .40336781 06 VM .97271122 00 RT .21291549 09 VT .26110227 02
GEO .-25897513 01 ALT .21091986 09 LOS .27323891 03 RAS .11078193 03 RAM .26747809 03 LOM .69935081 02
DUT .35000000 02 DT .86399999 05 DR .16199062 02 SHA .-20585269 09 DES .22069798 02 DEM .-24698652 02
CCL .10206468 03 NCL .18000385 03 TCL .92811081 01

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Table with columns for HELIOCENTRIC and ECLIPTIC COORDINATES. Includes data for X, Y, Z, DX, DY, DZ, etc.

HELIOCENTRIC CONIC

Table with columns for EPOCH OF PERICENTER PASSAGE, SMA, YH, and VA. Includes J.D. and other orbital parameters.

Table with columns for ALL VECTORS REFERENCED TO EARTH EQUATOR PLANE. Includes X, Y, Z, DX, DY, DZ, etc.

BTO .18165617 09 BRQ .38467694 08 B .18568449 09 THA .11956381 02 T VECTOR IN EARTH EQUATOR PLANE

Table with columns for ALL VECTORS REFERENCED TO ECLIPTIC PLANE. Includes X, Y, Z, DX, DY, DZ, etc.

BTC .18568398 09 BRC .42323416 06 B .18568446 09 THA .13059492 00 T VECTOR IN ECLIPTIC PLANE

Table with columns for ALL VECTORS REFERENCED TO ORBIT PLANE OF TARGET. Includes X, Y, Z, DX, DY, DZ, etc.

BTO .18560465 09 BRD .54442254 07 B .18568448 09 THA .35831986 03 T VECTOR IN ORBIT PLANE OF TARGET

225 DAYS 2 HRS. 44 MIN. 31.060 SEC. 235723202427202007527522 J.D.= 2438953.24476920 JULY 11, 1965 17 52 28.060 MARS IS THE CENTRAL BODY FOR INTEGRATION COWELL EQUATIONS OF MOTION

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225 DAYS 2 HRS. 44 MIN. 31.060 SEC. 235723202427202007527522 J.D.= 2438953.24476920 JULY 11, 1965 17 52 28.060

Table with columns for GEOCENTRIC and EQUATORIAL COORDINATES. Includes X, Y, Z, DX, DY, DZ, etc.

Table with columns for HELIOCENTRIC and ECLIPTIC COORDINATES. Includes X, Y, Z, DX, DY, DZ, etc.

Table with columns for AREOCENTRIC and ECLIPTIC COORDINATES. Includes X, Y, Z, DX, DY, DZ, etc.

Table with columns for AREOCENTRIC EQUATORIAL COORDINATES. Includes X, Y, Z, DX, DY, DZ, etc.

AREOCENTRIC CONIC

Table with columns for EPOCH OF PERICENTER PASSAGE, SMA, YH, and VA. Includes J.D. and other orbital parameters.

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        ALL VECTORS REFERENCED TO EARTH EQUATOR PLANE
X -67905585 05 Y -24283757 06 Z +24835528 05 DX -41859201 01 DY -11426220 01 DZ +27282742 00
INC -17331446 03 LAM -34281734 03 APF +57372230 02 MX -96280351 00 MY -26281448 00 MZ +62753035-01
WX -34382493-01 WY -11191720 00 WZ -95920403 00 PX -26800503 00 PY -95841794 00 PZ +98019490-01
QX -96280351 00 QY -26281449 00 QZ +62753035-01 RX -61238094-01 RY -27311628-01 RZ -97197304 00
BX +27671320 00 BY -95599888 00 BZ -97447246-01 TX -27203356 00 TY +96228777 00 TZ +00000000 00
SXI -96033725 00 SYI -27140216 00 SZI -63638020-01 DAI -36485554 01 RAI +19578531 03
SKD -96519082 00 SYD -25412526 00 SZD +61862898-01 DAO +35467473 01 RAD +19675065 03
ETE +46388492 02 ETS +14413840 03 ETC +23280735 03

BTH -25445431 06 BRQ -24965733 05 B +25567811 06 THA +18560358 03 T VECTOR IN EARTH EQUATOR PLANE

        ALL VECTORS REFERENCED TO ECLIPTIC PLANE
X +67905585 05 Y -21290933 06 Z +11940061 06 DX -41859201 01 DY -93974701 00 DZ +70490804 00
INC -15010870 03 LAM +35604388 03 APF +71013729 02 MX -96280351 00 MY -21615121 00 MZ -16213590 00
WX -34382493-01 WY -49715855 00 WZ -86697247 00 PX -26800602 00 PY -84029880 00 PZ +47124377 00
QX -96280351 00 QY -21615121 00 QZ +16213590 00 RX -16205584 00 RY -37757772-01 RZ -98605894 00
BX +27671319 00 BY -83830711 00 BZ +46975632 00 TX -22691466 00 TY +97391465 00 TZ +00000000 00
SXI -96033725 00 SYI -22375123 00 SZI +16639635 00 DAI -95783617 01 RAI +19311549 03
SKD -96519082 00 SYD -20853347 00 SZD +15786215 00 DAO -90828306 01 RAD +19219159 03
ETE +69235305 02 ETS +16698522 03 ETC +25565417 03

BTC -22479983 06 BRC -12180449 06 B +25567811 06 THA +20845039 03 T VECTOR IN ECLIPTIC PLANE

        ALL VECTORS REFERENCED TO ORBIT PLANE OF TARGET
X +20844761 06 Y +70722138 05 Z +12548319 06 DX +10420693 01 DY -41748402 01 DZ +62189034 00
INC -14896956 03 LAM +90114076 02 APF +73889917 02 MX +23968636 00 MY -96025503 00 MZ +14304100 00
WX +51549237 00 WY +10263728-02 WZ -85689357 00 PX -86268951 00 PY +27942224 00 PZ +49925014 00
QX +23968636 00 QY -96025502 00 QZ +14304100 00 RX +36859198-01 RY -14284059 00 RZ -98905911 00
BX +82048545 00 BY +28780589 00 BZ +49393461 00 TX -96828207 00 TY -24985965 00 TZ +00000000 00
SXI +24712597 00 SYI +95768820 00 SZI -14751961 00 DAI -84832127 01 RAI +28446920 03
SKD +23222710 00 SYD -96274309 00 SZD +13855065 00 DAO -79639885 01 RAD +28356148 03
ETE +70745116 02 ETS +16849503 03 ETC +25716398 03

BTD -22151246 06 BTD -12768525 06 B +25567811 06 THA +20996021 03 T VECTOR IN ORBIT PLANE OF TARGET

        ALL VECTORS REFERENCED TO AREOCENTRIC EQUATOR PLANE
X +20844761 06 Y +13609502 05 Z +14339664 06 DX +10420693 01 DY -40671214 01 DZ -11289647 01
INC -14148794 03 LAM +12412029 03 APF +11464696 03 MX +23968636 00 MY -93547864 00 MZ +25967318 00
WX +51549237 00 WY +34928090 00 WZ -78247774 00 PX -86268953 00 PY +53689554-01 PZ +56594977 00
QX +23968636 00 QY +48548663 00 QZ +16484100 00 RX +36859198-01 RY -14284059 00 RZ -98905911 00
BX +82048545 00 BY +62158088-01 BZ +56827810 00 TX -96679774 00 TY -24985965 00 TZ +00000000 00
SXI +24712597 00 SYI +93495411 00 SZI -25453787 00 DAI -14746201 02 RAI +28446920 03
SKD +23222710 00 SYD -93592642 00 SZD -26478719 00 DAO -15354307 02 RAD +28393511 03
ETE +76774132 02 ETS +17452404 03 ETC +26319299 03

BTT -20687620 06 BRT -15024492 06 B +25567811 06 THA +21598922 03 T VECTOR IN TRUE TARGET EQU. PLANE

230 DAYS 10 HRS. 28 MIN. 31.060 SEC.      235723542666202651705722 J.D.= 2438958.56699143 JULY 17, 1965 01 36 28.060
    
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GEOCENTRIC
X -21528519 09 Y -33381530 08 Z -14278223 08 DX -11676525 02 DY -24714124 02 DZ -10780385 02
R -21832523 09 DEC -37497550 01 RA +18881394 03 V +29382748 02 PTH +32987712 02 AZ +11331638 03
R -21832523 09 LAT -37497550 01 LON +23002497 03 VE +15863822 05 PTE +57779984-01 AZE +26996476 03
XS +62497325 08 YS +12715759 09 ZS +55142802 08 DXS +26663893 02 DYS -11127437 02 DES -49258068 01
XM +35195200 06 YM -16540250 06 ZM -11039887 06 DXM +45305043 00 UVM +79657050 00 DM +32755005 00
XT -21535122 09 YT -33138180 08 ZT -14303181 08 DXT -74905242 01 DYT -23571790 02 DZT -11053182 02
RS +15203847 09 VS +29292856 02 RM +40424757 06 VM +97317924 00 RT +21835491 09 VT +27090775 02
GED -37752351 01 ALT +21831886 09 LOS +13738492 03 RAS +11617388 03 KAM +33482846 03 LMT +16039750 02
DUU +35000000 02 DT +95999999 03 DR +15997706 02 SHA -21111798 09 DES +21265476 02 DEM -15848649 02
GCL -10175268 03 MCL +18001457 03 TCL +32779482 03

HELIOCENTRIC
X -15278787 09 Y -17490584 09 Z +18204450 06 DX -14987368 02 DY -14834343 02 DZ -57407438-01
R -23224173 09 LAT +44973615-01 LON +22886137 03 V -21087349 02 PTH +35668485 01 AZ +90159081 02
XE +62497325 08 YE -13859936 09 ZE +36950000 03 DXE +26663893 02 DYE +12128819 02 DZE -25391578-03
XT -15285389 09 YT +17469252 09 ZT +62328000 05 DXT +19173369 02 DYT -13894648 02 DZT -76217318 00
LTE +13924627-03 LDE +9427160 03 LDT +15184845-01 LDT +22881448 03 LST +23212452 09 VST +23690931 02
EPS +39288859 02 ESP +65410233 02 SEP +75300904 02 EPM +66351990-01 EMP +38847295 02 EPM +14108616 03
HPS +39354758 02 HSP +65500652 02 SMP +75144586 02 SEM +14304783 03 EHS +36860782 02 EHS -91192092-01
EPT +96693188 02 ETP +83240775 02 TEP +66351990-01 TPS +62418076 02 YSP +59514057-01 STP +11752649 03
SET -75242820 02 STE +39300033 02 EST +65457144 02 RPH +21863992 09 RPT +25338079 06 SPN +39287185 02
SAC +89948448-10 GCE +25824731 03 GGT +46042143 02 SFP +61654202 02 CPT +47651963 02 SIN +46888088 02
RGP -21032523 09 VEP +29382748 02 CPE +91153933 02 CPS +82009314 02

AREOCENTRIC
X -66027186 05 Y -21333097 06 Z +11971690 06 DX -41860009 01 DY -93949461 00 DZ +70476573 00
R +25338079 06 DEC +34328284 02 RA +28719760 03 V +43476370 01 PTH +43719955 00 AZ +28036057 03
ALT +25000279 06 SHA +22469740 06 ALP +16379697 03 DR +33174608-01 DP +98308158-03 ASD +76387384 00
HGE +32071114 03 SVL -28189059 02 HNG +58310008 02 STA +95929314 02

AREOCENTRIC EQUATORIAL COORDINATES
X +20891517 06 Y -11778436 05 Z +14289000 06 DX +10418224 01 DY +40671375 01 DZ -11291355 01
R +25338080 06 DEC +34328284 02 RA +32268656 01 V +43476371 01 PTH +43719955 00 AZ +25135458 03
R +25338079 06 LAT +34328284 02 LON +51903006 02 VP +19002142 02 PTP +10002983 00 AZP +26580524 03
RAE -10225037-03 DRE +24671581 02 RAS +14292172 03 DES +15016530 02 LDE +15092650 03 LOS +19159786 03

AREOCENTRIC CONIC
EPDCH OF PERICENTER PASSAGE      235723542666202651705722 J.D.= 2438958.56179777 JULY 17, 1965 01 28 59.327
SMA -23152520 04 ECC +11043662 03 B +25567811 06 SLR +28235069 08 APD +00000000 00 RCA +25337335 06
VH +63084471 01 C3 +18662716 02 C1 +11015757 07 TFP +44873269 08 TFO +23043127 00 LTF +23040201 03
TA +44115593 00 HFA +90518817 02 EA +43718589 00 MA +47844590 02 TFI +23043647 03
ZAE +16978623 03 ZAP +14320822 03 ZAC +98950570 02 DEF +10378332 01 FR +52012236 04 GP +84832033 01
    
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ALL VECTORS REFERENCED TO EARTH EQUATOR PLANE
 X .66027186 05 Y -.24335024 06 Z .24957948 05 DX -.41860009 01 DY -.11423338 01 DZ -.27279727 00
 INC .17331641 03 LAN .34281740 03 APF .57372299 02 MX -.96483854 00 MY -.25542721 00 MZ .61996301-01
 WX -.34382542-01 WY -.11119166 00 WZ -.99320404 00 PX .26800593 00 PY -.95841796 00 PZ -.98019493-01
 QX -.96280352 00 QY -.26281441 00 QZ .62752869-01 RX -.61237934-01 RY -.17311628-01 RZ -.99797302 00
 SX .27671310 00 SY -.95599890 00 SZ .97447249-01 TX -.27203348 00 TY .96228779 00 TZ .00000000 00
 SXI -.9603726 00 SYI -.27148208 00 SZI .63637859-01 DAI .36486460 01 RAI .19578530 03
 SXO -.96519083 00 SYO -.25412519 00 SZO .61862732-01 DAD .35466730 01 RAD .19475064 03
 EYE .46403853 02 ETS .14413949 03 ETC .23280735 03

BTQ -.25445630 06 BRD -.24965732 05 B .25567811 06 THA .18560358 03 T VECTOR IN EARTH EQUATOR PLANE
 ALL VECTORS REFERENCED TO ECLIPTIC PLANE
 X .66027186 05 Y -.21333097 06 Z .11971690 06 DX -.41860009 01 DY -.93949461 00 DZ .70476573 00
 INC .15010870 03 LAN .35604390 03 APF .71013749 02 MX -.96483853 00 MY -.20967486 00 MZ .15850254 00
 WX -.34382543-01 WY -.49716853 00 WZ -.86697250 00 PX .26800593 00 PY -.84029881 00 PZ .47124378 00
 QX -.96280353 00 QY -.21615121 00 QZ .16213572 00 RX -.16205567 00 RY -.37757728-01 RZ -.98605895 00
 SX .27671310 00 SY -.03830713 00 SZ .46975694 00 TX .22691465 00 TY .97391465 00 TZ .00000000 00
 SXI -.9603727 00 SYI -.22375123 00 SZI .16639617 00 DAI .95783515 01 RAI .19311549 03
 SXO -.96519084 00 SYO .20853347 00 SZO .15786198 00 DAD .90828213 01 RAD .19219159 03
 ETE .69250666 02 ETS .16698631 03 ETC .25565417 03

BTC -.22479982 06 BRC -.12180449 06 B .25567811 06 THA .20845039 03 T VECTOR IN ECLIPTIC PLANE
 ALL VECTORS REFERENCED TO ORBIT PLANE OF TARGET
 X .20891516 06 Y .68848766 05 Z .12576220 06 DX .10418234 01 DY -.41749240 01 DZ .62174067 00
 INC .14896956 03 LAN .90114108 02 APF .73889938 02 MX .23334517 00 MY -.96237565 00 MZ .13922333 00
 WX .51549223 00 WY .10266641-02 WZ -.85689364 00 PX .82268954 00 PY .27912237 00 PZ .49525006 00
 QX .23968664 00 QY -.96025498 00 QZ .14304079 00 RX .36859183-01 RY .14284037 00 RZ .98905915 00
 DX .82048546 00 DY .28786000 00 DZ .49393454 00 TX .96828200 00 TY .24985992 00 TZ .00000000 00
 SXI .24712624 00 SYI .95768817 00 SZI .14751939 00 DAI .84831998 01 RAI .28446922 03
 SXO .23222739 00 SYO .96274305 00 SZO .13855045 00 DAD .79639766 01 RAD .28356149 03
 ETE .70760472 02 ETS .16849611 03 ETC .25716397 03

BTU -.22151248 06 BRU -.12768523 06 B .25567811 06 THA .20996020 03 T VECTOR IN ORBIT PLANE OF TARGET
 ALL VECTORS REFERENCED TO AREOCENTRIC EQUATOR PLANE
 X .20891516 06 Y .11778488 05 Z .14289000 06 DX .10418234 01 DY -.40671372 01 DZ .11291355 01
 INC .14148793 03 LAN .12412032 03 APF .11464695 03 MX .23334517 00 MY .93586417 00 MZ .26402324 00
 WX .51549222 00 WY .34928120 00 WZ -.78247710 00 PX .82268953 00 PY .53689705-01 PZ .56594993 00
 QX .23968664 00 QY .93547851 00 QZ .25967335 00 RX .65045446-01 RY .24608678 00 RZ .96786273 00
 DX .82048546 00 DY .62159233-01 DZ .56827807 00 TX .96679766 00 TY .25554313 00 TZ .00000000 00
 SXI .24712624 00 SYI .93495399 00 SZI .25453804 00 DAI .14746214 02 RAI .28480576 03
 SXO .23222738 00 SYO .93592631 00 SZO .26478736 00 DAD .15354317 02 RAD .28393513 03
 ETE .76789494 02 ETS .17452513 03 ETC .26319299 03

BTU -.20687620 06 BRT -.15024491 06 B .25567811 06 THA .21598922 03 T VECTOR IN TRUE TARGET EQU. PLANE
 215542322304 214412017045 614626031734 601731460721 204537405516 601471557251 EARTH
 21189808915 17481859072 000000000000 INITIAL
 220775513340 622733565354 217604377240 603414100141 601440622006 177435553167 MARS
 235723543047 202007527522 END

U MATRIX FOR MAPPING FORWARD

ITERATION NUMBER 1

| | X | Y | Z | DX | DY | DZ | MM | AU |
|----|---------------|---------------|---------------|---------------|---------------|---------------|--------------|---------------|
| X | -.14240628 06 | .32833775 05 | -.12743440 05 | -.32201795-01 | -.18749275-01 | -.67970214-02 | .00000000 00 | .00000000 00 |
| Y | -.55073909 05 | .15447656 05 | .55764404 04 | -.12770882-01 | -.73212989-02 | -.26537464-02 | .00000000 00 | .00000000 00 |
| Z | .82201993 05 | -.21762468 05 | -.91111089 04 | .18877931-01 | -.10989078-01 | .43940406-02 | .00000000 00 | .00000000 00 |
| DX | .37202730 08 | -.51210248 07 | -.23455938 07 | .80190345 01 | -.47951245 01 | .16743353 01 | .00000000 00 | .00000000 00 |
| DY | -.22529723 09 | .54473221 08 | .21533065 08 | -.51212858 02 | .29795080 02 | -.11093539 02 | .00000000 00 | .00000000 00 |
| DZ | .25683868 08 | -.66539341 07 | -.19942635 07 | .59071261 01 | -.33589278 01 | .10381906 01 | .00000000 00 | .00000000 00 |
| MM | .21474836 11 | -.18468359 12 | .74625055 11 | -.14336000 06 | .82944000 05 | -.17536000 05 | .00000000 01 | .00000000 00 |
| AU | -.46875000 00 | -.71875000 00 | -.29687500 00 | .13411045-06 | -.29429793-06 | -.58207661-08 | .00000000 00 | -.10000000 01 |

COVARIANCE MATRIX AT IMPACT

ITERATION NUMBER 1

| | X | Y | Z | DX | DY | DZ | MM | AU |
|----|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| X | .10637680 05 | -.22420325 05 | .12501384 05 | -.29614010-02 | -.15642850-02 | -.28561890-02 | -.21474894-07 | -.11718800 02 |
| Y | .22420325 05 | .88347057 05 | -.47340614 05 | -.28379472-01 | .16219363-01 | -.11518833-01 | .18468361-06 | -.17968771 02 |
| Z | .12501384 05 | -.47340614 05 | .34772597 05 | -.11713876-01 | .75178238-02 | -.98098615-02 | .74625093-07 | -.74219149 01 |
| DX | -.29614010-02 | -.28379472-01 | -.11713876-01 | .20777808-07 | -.12004298-07 | .27655606-08 | -.14335999-12 | .33527526-05 |
| DY | .15642850-02 | .16219363-01 | .75178238-02 | -.12004298-07 | .70263182-08 | -.19162602-08 | .82943994-13 | -.73574456-05 |
| DZ | -.28561890-02 | -.11518833-01 | -.98098615-02 | .27655606-08 | -.19162602-08 | .29285971-08 | -.17536011-13 | -.14550667-06 |
| MM | -.21474894-07 | .18468361-06 | .74625093-07 | -.14335999-12 | .82943994-13 | -.17536011-13 | .99999998-18 | .21195486-22 |
| AU | -.11718800 02 | -.17968771 02 | -.74219149 01 | .33527526-05 | -.73574456-05 | -.14550667-06 | .21195486-22 | .25000000 02 |

JPL TECHNICAL MEMORANDUM NO. 33-204

ENCOUNTER PARAMETERS AND STATISTICS 65/07/17 012859.322

B .25568130 06 SMAA .32174637 03
 B.RD -.12768892 06 SMIA .83507688 02
 B.YD -.22151403 06 DEL T .37226349 02
 B.RC -.12180449 06 DEL B .33240677 03
 B.TC -.22479983 06 DEL S .16038767 03
 TL .23040207 03 DEL BR .10149567 03
 THETA .10699438 02 DEL BT .31653260 03

N MATRIX

| | B.RD | B.TO | TL | C3 | S.TS | S.RS |
|------|---------------|---------------|---------------|---------------|---------------|---------------|
| B.RD | .10301371 05 | -.17613031 05 | -.17042226 04 | .14831570-01 | .10897963-02 | .74349552-03 |
| B.YD | -.17613032 05 | .10019289 06 | .10369679 05 | .95422841-01 | -.69411049-02 | -.30035637-02 |
| TL | -.17042227 04 | .10369679 05 | .13858011 04 | .51374437-02 | -.62122480-03 | -.24740746-03 |
| C3 | .14831570-01 | .95422841-01 | .51374439-02 | .66149723-06 | -.11622786-07 | -.69983611-08 |
| S.TS | .10897963-02 | -.69411049-02 | -.62122480-03 | -.11622786-07 | .53718767-09 | .25609643-09 |
| S.RS | .74349549-03 | -.30035638-02 | -.24740745-03 | -.69983607-08 | .25609644-09 | .15636082-09 |

NORMALIZED N MATRIX

| | B.RD | B.TO | TL | C3 | S.TS | S.RS |
|------|---------------|---------------|---------------|---------------|---------------|---------------|
| B.RD | .99999999 00 | -.54823672 00 | -.45105381 00 | .17967000 00 | .46327063 00 | .58582360 00 |
| B.YD | -.54823674 00 | .10000000 01 | .88002785 00 | .37065500 00 | -.94612197 00 | -.75884733 00 |
| TL | -.45105381 00 | .88002785 00 | .10000000 01 | .16968076 00 | -.72000467 00 | -.53149401 00 |
| C3 | .17967001 00 | .37065500 00 | .16968077 00 | .99999998 00 | -.01657117 00 | -.68812661 00 |
| S.TS | .46327065 00 | -.94612197 00 | -.72000467 00 | -.61657117 00 | .99999999 00 | .88364239 00 |
| S.RS | .58582357 00 | -.75884738 00 | -.53149399 00 | -.68812657 00 | .88364241 00 | .99999999 00 |

DM/DOO MATRIX

| | B.RD | B.TO | TL | C3 | S.TS | S.RS |
|----|---------------|---------------|---------------|---------------|---------------|---------------|
| X | .24330516 05 | .64995540 05 | -.29677574 05 | .13145920 00 | -.11157073-01 | .56606676-03 |
| Y | .98666986 04 | .27841637 05 | -.11310281 05 | .49878439-01 | -.44800132-02 | .25911632-03 |
| Z | -.13503961 05 | -.40737256 05 | .16973777 05 | -.74298253-01 | .66583250-02 | -.28822134-03 |
| DX | -.59392066 07 | -.13507410 08 | .79610852 07 | -.35645702 02 | .26993601 01 | -.10983936 00 |
| DY | .38196933 08 | .10563821 09 | -.46808109 08 | .20666396 03 | -.17838378 02 | .87565422 00 |
| DZ | -.49480323 07 | -.12244892 08 | .53021018 07 | -.23715798 02 | .20346128 01 | -.14765713 00 |
| MU | .24638750 01 | -.72774732 01 | .14250950 00 | .43780724-03 | .10143746-04 | -.60035930-05 |

DM/UQ MATRIX

| | B.RD | B.TO | TL | C3 | S.TS | S.RS |
|----|---------------|---------------|---------------|---------------|---------------|---------------|
| X | -.14297395 00 | -.16182701 00 | .22580654 00 | .28314228-06 | .43595943-07 | -.25130324-07 |
| Y | -.28136354-01 | .98867121 00 | .40707545-01 | -.11281551-05 | -.47139432-07 | .27172928-07 |
| Z | -.99584158 00 | .32882216-02 | -.35173765-01 | .66306711-06 | .55314040-07 | .26337118-07 |
| DX | -.63716973 04 | -.16846420 04 | .91028766 04 | -.84913467 01 | -.36826590-03 | -.21228334-03 |
| DY | -.85946945 04 | .40625272 04 | .13368759 05 | -.13992037 01 | .15366673-02 | -.88579189-03 |
| DZ | .10419841 05 | -.11039756 03 | -.84511326 04 | .12437810 01 | .18654026 00 | .26722055 00 |
| MU | .24778832 01 | -.87136382 01 | .23160733-01 | .43191793-03 | .10281612-04 | -.59267003-05 |

N MATRIX FOR MANEUVER CALCULATIONS

| | B.RC | B.TC | TL |
|------|---------------|---------------|---------------|
| B.RC | .11291969 05 | -.19957052 05 | -.22881360-01 |
| B.TC | -.19957053 05 | .99202292 05 | .11945784 00 |
| TL | -.22881360-01 | .11945784 00 | .18564079-06 |

0000 140311 OFFLINE CONTROL I (27
 0000 14031 TERMINATE JOB
 0000 14031 END DATA - 10

JPL TECHNICAL MEMORANDUM NO. 33-204

```

0000 141001 PAGE HEADING (23
0000 14100 IVENUS CHECK CASE - STEP MAP1
0000 14100 EPOCH (01
0000 14100 620900500,2332000
0000 14100 GEOCENTRIC POSITION AND VELOCITY AT EPOCH (02
0000 14100 X=-.14245297E7 Y=-.19398640E7 Z=-.10071723E6
0000 14100 DX=-.17446099E1 DY=-.24232877E1 DZ=-.11048412E0
0000 14100 OTHER OPTIONS AND CONSTANTS (03
0000 14100 ESTIMATE THESE PARAMETERS (04
0000 14100 X Y Z DX DY DZ MV AU
0000 14100 COVARIANCE MATRIX OF ESTIMATED PARAMETERS (10
0000 14100 DIAG=.1,.1,.1,.0001,.0001,.0001,.1E-17,25.
0000 14100 MAP COVARIANCE MATRIX TO (24
0000 14100 621200700,0
0000 14100 OFFLINE CONTROL (27
0000 14100 KEY(3) KEY(5)
0000 14100 END DATA (10
    
```

```

INPUT COVARIANCE MATRIX OF ESTIMATED PARAMETERS ITERATION NUMBER 0
X Y Z DX DY DZ MV AU
X .99999999-01 -.00000000 00 .00000000 00 .00000000 00 .00000000 00 .00000000 00
Y .00000000 00 .99999999-01 .00000000 00 .00000000 00 .00000000 00 .00000000 00
Z .00000000 00 .00000000 00 .99999999-01 .00000000 00 .00000000 00 .00000000 00
DX .00000000 00 .00000000 00 .00000000 00 .99999999-04 .00000000 00 .00000000 00
DY .00000000 00 .00000000 00 .00000000 00 .00000000 00 .99999999-04 .00000000 00
DZ .00000000 00 .00000000 00 .00000000 00 .00000000 00 .00000000 00 .99999999-04
MV .00000000 00 .00000000 00 .00000000 00 .00000000 00 .00000000 00 .99999998-18
AU .00000000 00 .00000000 00 .00000000 00 .00000000 00 .00000000 00 .25000000 02
    
```

```

INPUT J MATRIX OF ESTIMATED PARAMETERS ITERATION NUMBER 0
X Y Z DX DY DZ MV AU
X .10000000 02 .00000000 00 .00000000 00 .00000000 00 .00000000 00 .00000000 00
Y .00000000 00 .10000000 02 .00000000 00 .00000000 00 .00000000 00 .00000000 00
Z .00000000 00 .00000000 00 .10000000 02 .00000000 00 .00000000 00 .00000000 00
DX .00000000 00 .00000000 00 .00000000 00 .10000000 05 .00000000 00 .00000000 00
DY .00000000 00 .00000000 00 .00000000 00 .00000000 00 .10000000 05 .00000000 00
DZ .00000000 00 .00000000 00 .00000000 00 .00000000 00 .00000000 00 .10000000 05
MV .00000000 00 .00000000 00 .00000000 00 .00000000 00 .00000000 00 .99999998 18
AU .00000000 00 .00000000 00 .00000000 00 .00000000 00 .00000000 00 .39999999-01
    
```

CASE 1 IBSYS-JPTRAJ-SPACE D22265 1

DOUBLE PRECISION EPHEMERIS TAPE - EPHEM1

```

GME .39880063 06 J .16234500-02 H -.57499999-05 D .78749999-05 RE .63781650 04 REM .63783112 04
G .65709998-19 A .88781796 29 a .88800194 29 C .88836976 29 OME .41780741-02 AU .14959850 09
GMM .49026293 04 GMS .13271411 12 GMV .32476627 06 GMA .42977368 05 GMC .37918700 08 GMJ .12670935 09
EGH .39880320 06 EGM .49027779 04 JA .29200000-02 HA .00000000 00 DA .00000000 00 RA .34170000 04
RADIATION PRESSURE INPUT
ARA .38300000 01 GB .38300000 00 MAS .19822000 03 GB1 .00000000 00 GB2 .00000000 00 SC .10310000 09
    
```

```

INJECTION CONDITIONS VENUS 2355740064120200000000 J.D.= 2437912.51634260 SEPT. 5, 1962 00 23 32.000
GEOCENTRIC X0=-.14245297 07 Y0=-.19398640 07 Z0=-.10071723 06 DX0=-.17446099 01 DY0=-.24232877 01 DZ0=-.11048412 00
CARTESIAN TD .14120000 04 GHA .34951873 03 GHD .34361929 03
DATE OF RUN D22265A 14103 EARTH IS THE CENTRAL BODY FOR INTEGRATION COWELL EQUATIONS OF MOTION
    
```

```

PROBE IS OUT OF EARTH'S SHADOW
0 DAYS 0 HRS. 0 MIN. 0.000 SEC. 2355740064120200000000 J.D.= 2437912.51634260 SEPT. 5, 1962 00 23 32.000
    
```

```

EQUATORIAL COORDINATES
X -.14245296 07 Y -.19398639 07 Z -.10071723 06 DX -.17446098 01 DY -.24232875 01 DZ -.11048412 00
R .24088380 07 DEC -.23963223 01 RA .23370847 03 Y .29880081 01 PTH .89393198 02 AZ .62816414 02
R .24088380 07 LAT -.23963223 01 LUN .24418974 03 VE .17549891 03 PTE .97549786 00 AZE .27000472 03
XS -.14343227 09 YS .42810504 08 ZS .18564279 08 DXS -.87218607 01 DYS -.25899198 02 DZS -.11230749 02
XW -.27632510 06 YW .27943325 06 ZW .81923071 05 DWS .72016653 00 DVS -.58854660 00 DWS .27195625 00
MW -.08139502 08 YW .41412272 08 ZW .22861356 08 DWT .21205738 02 DWT .90988722 01 DWT .55559090 01
RS .15083166 09 VS .29546049 02 RW .40143479 06 VW .97560880 00 RT .10003094 09 VT .23734804 02
GED -.24126335 01 ALT .24024598 07 LOS .17386238 03 RAS .16338111 03 RAM .22532043 03 LDM .23580169 03
DUT .35000000 02 DT .19200000 04 DR .29878406 01 SHA .-22750333 07 DES .70698621 01 OEM .-11775395 02
CCL .60702505 02 MCL .18217293 03 TCL .33869367 03
    
```

```

GEOCENTRIC CNVIC 235574612773202330000000 J.D.= 2437903.65534361 AUG. 27, 1962 03 43 41.688
EPHCH OF PERICENTER PASSAGE
SHA -.46363768 05 EGC .11464198 01 B .25992350 05 SLR .14571132 05 APD .00000000 00 RCA .67885751 04
YH .29321057 01 EC .85972439 01 C1 .76210645 05 IFP .76559031 06 TF .-88609980 01 LTF .-08860057 01
TA .15011236 03 NTA .15072477 03 EA .25993107 03 MA .-27740861 04
    
```

```

ALL VECTORS REFERENCED TO EARTH EQUATOR PLANE
X -.14245296 07 Y -.19398639 07 Z -.10071723 06 DX -.17446098 01 DY -.24232875 01 DZ -.11048412 00
INV .-27271914 02 LAN .23836288 03 APF .20465420 03 MX .70574093 00 MY .54195777 00 MZ .45648036 00
INC .-43960422 02 LAN .21470263 03 APF .23385448 03 MX .70574097 00 MY .-31562129 00 MZ .63441003 00
WX .-39026905 00 MY .57429661 00 WZ .71981946 00 PX .16105420 00 PY .81227206 00 PZ .-58063743 00
BX .-71196439 00 BY .-30790167 00 BZ .-63130772 00 FX .-79257140 00 FY .60977912 00 FZ .00000000 00
SX1 .-30283033 00 SY1 .87814137 00 SZ1 .-37051435 00 DAI .-21747342 02 RAI .10902694 03
SX0 .-58379930 00 SY0 .-81105764 00 SZ0 .-36930149-01 DAD .-21164212 01 RAD .-23425365 03
    
```

```

ALL VECTORS REFERENCED TO ECLIPTIC PLANE
X -.14245296 07 Y -.18198130 07 Z .67933540 06 DX -.17446098 01 DY -.22672196 01 DZ .86269591 00
INC .-43960422 02 LAN .21470263 03 APF .23385448 03 MX .70574097 00 MY .-31562129 00 MZ .63441003 00
WX .-39026905 00 MY .57429661 00 WZ .71981946 00 PX .16105420 00 PY .81227206 00 PZ .-58063743 00
BX .-71196439 00 BY .-30790167 00 BZ .-63130772 00 FX .-79257140 00 FY .60977912 00 FZ .00000000 00
    
```

JPL TECHNICAL MEMORANDUM NO. 33-204

CASE 1

1BSYS-JPTRAJ-SPACE 022265

2

SXI -30283033 00 SYI -65825499 00 SZ1 -68928400 00 DAI -43573456 02 RAI .11470480 03
 SXO -58379930 00 SYO -75880365 00 SZO -28878253 00 DAO -16785081 02 KAO .23242646 03
 BTC .25821250 05 BRC -.29777056 04 B -.25992357 05 THA .35342171 03 T VECTOR IN ECLIPTIC PLANE
 ALL VECTORS REFERENCED TO ORBIT PLANE OF TARGET
 X -21047606 07 Y .99300253 06 Z .62163449 06 DX -26151033 01 DY -12088622 01 DZ .79251463 00
 INC .46529416 02 LAN .14007295 03 APF .23072292 03 MX -.14000245 00 MY -.72132412 00 MZ .67822014 00
 QX .46573257 00 QY .55647604 00 WZ .68798206 00 PX .82730393 00 PY .20775199-02 PZ -.56172740 00
 RX -.31406365 00 RY .83080683 00 OZ -.45939320 00 KX -.24082291 00 RY .11130159 00 RZ -.96416608 00
 BK .13064194 00 BY .72572865 00 BZ -.67545940 00 TX .41053216 00 TY .90774047 00 TZ .00000000 00
 SX1 .56802335 00 SY1 .40812293 00 SZ1 -.71463701 00 DAI -.45613458 02 RAI .35697122 02
 SXO -.87521258 00 SYO .40449869 00 SZO -.26529930 00 DAO .15384736 02 RAO .15519494 03
 BYO .25564948 05 BRD -.46834718 04 B -.25994920 05 THA .34962039 03 T VECTOR IN ORBIT PLANE OF TARGET
 0 DAYS 8 HRS. 28 MIN. 56.404 SEC. 235575417563202063552055 J.D. = 2437912.86977319 SEPT. 5, 1962 08 52 28.404
 0 DAYS 8 HRS. 28 MIN. 56.404 SEC. 235575417563202063552055 J.D. = 2437912.86977319 SEPT. 5, 1962 08 52 28.404
 CHANGE OF PHASE OCCURS AT THIS POINT SUN IS THE CENTRAL BODY FOR INTEGRATION COMELL EQUATIONS OF MOTION
 95 DAYS 14 HRS. 14 MIN. 19.059 SEC. 23560530151720260740611 J.D. = 2438008.10961873 DEC. 9, 1962 14 37 51.059
 HELIOCENTRIC EQUATORIAL COORDINATES
 X -.51022567 07 Y .99263157 08 Z .46385104 08 DX -.36494257 02 DY -.58201960 01 DZ -.33262712 01
 R .10968494 09 LAT .25017435 02 LON .92942489 02 V .37104845 02 PTH -.77073126 01 AZ .92101531 02
 XE .33012548 08 YE .13172989 09 ZE .57121301 08 DKE -.29507273 02 DYE .60187031 01 DZE .26093425 01
 XT -.57926326 07 YT .97856442 08 ZT .44437148 08 DKT -.35091492 02 DYT -.26941798 01 DYT .10045215 01
 LTE .22812463 02 LOE .75930981 02 LTT .24385356 02 LDT .93387681 02 RST .10762945 09 VST .35209096 02
 EPS .12889057 03 ESP .15695704 02 SEP .35413715 02 EPM .78819662-01 EMP .11190031 02 MEP .16873061 03
 HPS .12896821 03 HSP .15754195 02 SMP .35277587 02 SEM .15551567 03 EMS .24425661 02 ESM .57674939-01
 EPT .13652545 03 ETP .41616422 02 TEP .18581345 01 TPS .34321386 02 TSP .75043170 00 STP .14492821 03
 SET .34151904 02 STE .12978488 03 EST .16063212 02 RPM .51564817 08 RPT .25000001 07 SPN .12888343 03
 GCE .87219501 02 GCT .32905271 03 SIP .34179292 02 CPT .72719279 02 SIN .72577188 02
 REP .51206375 08 VEP .14973609 02 CPE .80195375 02 CPS .10226691 03

CASE 1

1BSYS-JPTRAJ-SPACE 022265

3

EPOCH OF PERICENTRAL PASSAGE 235607605023202427404611 J.D. = 2438037.01349749 JAN. 7, 1963 12 19 26.184
 SMA .12722493 09 ECC .19144548 00 B .12487168 09 SLR .12256496 02 SLE .12487168 09 SLR .12256496 02 SLE .12487168 09
 VA .26606638 02 C3 -.10431455 04 EA .40330759 10 TFP -.24972951 07 TF .12449715 03 PER .28646125 03
 TA .52176583 02 MTA .18000000 03 EI -.41914634 02 MA -.36123921 02 MA -.36123921 02 IFI .95593274 02
 ALL VECTORS REFERENCED TO EARTH EQUATOR PLANE
 X -.51022567 07 Y .99263157 08 Z .46385104 08 DX -.36494257 02 DY -.58201960 01 DZ -.33262712-01
 INC .18528344 01 LAN .35798326 03 APF .17232764 03 MX -.99880594 00 MY -.46875705-01 MZ .16240131 00
 QX -.14928005-01 QY -.42393483 00 WZ .90556966 00 PX -.81748708 00 PY .52667570 00 PZ .23028281 00
 BX .57575346 00 BY .73681204 00 OZ -.35442347 00 KX -.19593895 00 RY .12623598 00 RZ -.97245689 00
 QX .57575346 00 QY .73681204 00 BZ .35442346 00 TX .54159204 00 TY .84064094 00 TZ .00000000 00
 DAP .13478637 02 RAP .14720786 03
 BTQ .11628279 09 BRQ .45510967 08 B .12487168 09 THA .33862552 03 T VECTOR IN EARTH EQUATOR PLANE
 ALL VECTORS REFERENCED TO ORBIT PLANE OF TARGET
 X -.10522015 09 Y .30951192 08 Z .12362223 07 DX -.15093336 02 DY .3785281 02 DZ -.27414238 01
 INC .42377940 01 LAN .20514100 03 APF .22340356 03 MX -.28065725 00 MY .95702555 00 MZ -.73031397-01
 QX -.31394514-01 QY .66895422-01 WZ .99726595 00 PX .36657532 00 PY .92400173 00 PZ .50776334-01
 BX .42985851 00 BY .36397699 00 QZ -.53687768-01 KX -.18637393-01 RY .47232232-01 RZ .99871001 00
 DAP .42985854 00 BY .36397699 00 BZ .53687770-01 TX .93020169 00 TY .36704081 00 TZ .00000000 00
 RAP .68466271 02
 BTD .12469110 09 BRD .67127396 07 B .12487166 09 THA .35691845 03 T VECTOR IN ORBIT PLANE OF TARGET
 95 DAYS 14 HRS. 14 MIN. 19.059 SEC. 23560530151720260740611 J.D. = 2438008.10961873 DEC. 9, 1962 14 37 51.059
 CHANGE OF PHASE OCCURS AT THIS POINT VENUS IS THE CENTRAL BODY FOR INTEGRATION COMELL EQUATIONS OF MOTION
 95 DAYS 14 HRS. 14 MIN. 19.059 SEC. 23560530151720260740611 J.D. = 2438008.10961873 DEC. 9, 1962 14 37 51.059
 GEOCENTRIC EQUATORIAL COORDINATES
 X -.38114804 08 Y -.32466730 08 Z -.10736197 08 DX -.69869830 01 DY -.11838899 02 DZ -.59356160 01
 R .51206375 08 DEC .12102736 02 RA .22082483 03 VA .14973609 02 PTH .68707168 02 AZ .12448867 03
 XE .51206373 08 YE .12102736 02 LON .28310597 03 VE .36465705 04 PTE .21920980 00 AZE .26995161 03
 XS -.33012548 08 YS .13172989 09 ZS .57121301 08 DKS -.29507273 02 DYS .60187031 01 DZS .26093425 01
 XM .21915150 06 YM .27889500 06 ZM .87959625 05 UXM -.85011053 00 DYM .95271705 00 DZM .29599153 00
 XT .38080518 08 YT .33873445 09 ZT .12684154 08 DXT .55842184 01 DYT .87128830 01 DZT .16048215 01
 RS .14732764 09 VS .30227680 02 RM .36544041 06 VM .10777812 01 RT .53048469 08 VT .10472501 02
 GED .12182757 02 ALT .51199996 08 LBS .31861212 03 RAS .25593098 03 RAM .51842267 02 LDM .11452140 03
 DIT .35000000 02 DT .36400000 04 DR .13951461 02 SRA .29672879 08 DES .22812463 02 DEM .13927554 02
 CCL .27278050 03 MCL .17997891 03 TCL .61833203 02
 HELIOCENTRIC EQUATORIAL COORDINATES
 X -.51022567 07 Y .99263157 08 Z .46385104 08 DX -.36494256 02 DY -.58201960 01 DZ -.33262711 01
 R .10968494 09 LAT .25017435 02 LON .92942489 02 V .37104845 02 PTH -.77073126 01 AZ .92101531 02
 XE .33012548 08 YE .13172989 09 ZE .57121301 08 DKE -.29507273 02 DYE .60187031 01 DZE .26093425 01
 XT -.57926326 07 YT .97856442 08 ZT .44437148 08 DKT -.35091492 02 DYT -.26941798 01 DYT .10045215 01
 LTE .22812463 02 LOE .75930981 02 LTT .24385356 02 LDT .93387681 02 RST .10762945 09 VST .35209096 02
 EPS .12889057 03 ESP .15695704 02 SEP .35413715 02 EPM .78819662-01 EMP .11190031 02 MEP .16873057 03
 HPS .12896821 03 HSP .15754195 02 SMP .35277587 02 SEM .15551567 03 EMS .24425661 02 ESM .57674939-01
 EPT .13652545 03 ETP .41616422 02 TEP .18581345 01 TPS .34321389 02 TSP .75039911 00 STP .14492821 03
 SET .34151904 02 STE .12978488 03 EST .16063212 02 RPM .51564818 08 RPT .25000000 07 SPN .12888343 03
 GCE .87219499 02 GCT .32905271 03 SIP .34179292 02 CPT .72719279 02 SIN .72577188 02
 REP .51206374 08 VEP .14973609 02 CPE .80195375 02 CPS .10226691 03

JPL TECHNICAL MEMORANDUM NO. 33-204

CASE 1

IBSYS-JPTRAJ-SPACE 022265

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APHRODOCENTRIC

| | | | | | |
|------------------|------------------|------------------|------------------|-------------------|------------------|
| X .69037591 06 | Y .14067148 07 | Z .19479566 07 | DX -.14027647 01 | DY -.31260163 01 | DZ -.43307926 01 |
| R -25000000 07 | DEC .51187596 02 | RA .63859499 02 | V .55222722 01 | PTH -.88648416 02 | AZ .24853760 03 |
| ALT .24930001 07 | SHA .14365062 07 | ALP .50235695 02 | DR -.55208174 01 | DP .29047796-05 | ASD .14209440 00 |
| HGE .23110942 03 | SVL .29805915 02 | HNG .17862165 02 | SIA .13638335 03 | | |
| SAC .22900140-09 | | | | | |

EQUATORIAL COORDINATES

APHRODOCENTRIC CONIC

| | | | | | |
|-----------------------------|---|------------------|-------------------|------------------|------------------|
| EPOCH OF PERICENTER PASSAGE | 23560563423202757046611 J.D.= 2438013.29235961 DEC. 14, 1962 19 00 59.871 | | | | |
| SMA -.10741161 05 | ECC .54573169 01 | B .57624974 05 | SLR .30915540 06 | APD .00000000 00 | RCA .47876758 05 |
| VH .54986978 01 | C3 .30235677 02 | C1 .31688472 06 | IFP -.44778881 06 | TF .10077602 03 | LTf .10073765 03 |
| TA .99240591 02 | MTA .10055855 03 | EA -.25498362 03 | HA -.13134227 05 | | TF1 .95593274 02 |
| LAE .13728729 03 | LAP .34431163 02 | ZAC .72681574 02 | DEF .21117187 02 | IR .13100778 05 | GP .-29764390 02 |

| | | | | | |
|-------------------|-------------------|-------------------|-------------------|------------------|------------------|
| X .69037591 06 | Y .14067148 07 | Z .19479566 07 | DX -.14027647 01 | DY -.31260163 01 | DZ -.43307926 01 |
| INC .12568504 03 | LAN .18063363 03 | APF .20564144 03 | MX .96106519 00 | MY -.15408769 00 | MZ .-22933716 00 |
| WX -.89823426-02 | WY .81217684 00 | WZ -.58332922 00 | PX .90424851 00 | PY .-24244515 00 | PZ .-35148387 00 |
| QX -.42689400 00 | QY -.53064020 00 | QZ -.73224367 00 | RX .32102521 00 | RY .71553693 00 | RZ .-62044313 00 |
| BX .96716951 00 | BY -.14110654 00 | BZ -.21135770 00 | TX .-91238207 00 | TY .40933966 00 | TZ .00000000 00 |
| SXI .-25397198 00 | SYI .-56608119 00 | SZI .-78425141 00 | DAI .-51651496 02 | RAI .24583663 03 | |
| SXD .-58536138 00 | SYD .-47722978 00 | SZD .-65543945 00 | DAO .-40952978 02 | RAO .21918946 03 | |
| ETE .30676850 03 | ETS .41834750 02 | ETC .25151733 03 | | | |

B1Q -.54178344 05 B1R .19630194 05 B .57624974 05 THA .16008325 03 T VECTOR IN EARTH EQUATOR PLANE

| | | | | | |
|-------------------|-------------------|-------------------|-------------------|------------------|------------------|
| X .69037591 06 | Y .20655587 07 | Z .12275376 07 | DX -.14027647 01 | DY -.45909108 01 | DZ -.27297031 01 |
| INC .14912599 03 | LAM .18100294 03 | APF .20613286 03 | MX .96107515 00 | MY -.23260884 00 | MZ .-14910819 00 |
| WX -.89822391-02 | WY .51307865 00 | WZ -.85829789 00 | PX .90425774 00 | PY .-36226754 00 | PZ .-22602173 00 |
| QX -.42689838 00 | QY -.77814811 00 | QZ -.46059866 00 | RX .-14442028 00 | RY .47274711 00 | RZ .-86928300 00 |
| BX .96716951 00 | BY .-21354347 00 | BZ .13717493 00 | TX .-95636865 00 | TY .29216109 00 | TZ .00000000 00 |
| SXI .-25397199 00 | SYI .-83135503 00 | SZI .-49431472 00 | DAI .-29624573 02 | RAI .25301252 03 | |
| SXD .-58536812 00 | SYD .-69858971 00 | SZD .-41148134 00 | DAO .-24297925 02 | RAO .23003940 03 | |
| ETE .31756582 03 | ETS .52632071 02 | ETC .26231466 03 | | | |

B1C -.56896602 05 B1R .19331112 06 B .57624970 05 THA .17088060 03 T VECTOR IN ECLIPTIC PLANE

| | | | | | |
|-------------------|-------------------|-------------------|-------------------|------------------|------------------|
| X .21701731 07 | Y .-11002964 06 | Z .12362209 07 | DX .-47923321 01 | DY .11675437 00 | DZ .-27414251 01 |
| INC .14982375 03 | LAN .99025410 03 | APF .19958971 03 | MX .96519880-03 | MY .-99591691 00 | MZ .-90300711-01 |
| WX .49643364 00 | WY .78854661-01 | WZ .-86448325 00 | PX .-13846385 00 | PY .-97592482 00 | PZ .-16853506 00 |
| QX .-85695557 00 | QY .20336746 00 | QZ .-47357037 00 | RX .49628792 00 | RY .-12062966-01 | RZ .-86807415 00 |
| BX .20910910-01 | BY .-96666294 00 | BZ .-78931403-01 | TX .-89910473 00 | TY .95910473 00 | TZ .00000000 00 |
| SXI .-25397199 00 | SYI .-21093512-01 | SZI .49643450 00 | DAI .-29764388 02 | RAI .17860762 03 | |
| SXD .-81707303 00 | SYD .37875450 00 | SZD .-43466907 00 | DAO .-25764239 02 | RAO .15512990 03 | |
| ETE .31229757 03 | ETS .71005011 02 | ETC .27321265 03 | | | |

B1O -.57386433 05 B1R .52377827 04 B .57624970 05 THA .17478494 03 T VECTOR IN ORBIT PLANE OF TARGET

100 DAYS 19 HRS. 23 MIN. 26.074 SEC. 235605635514202411434156 J.D.= 2438013.32428326 DEC. 14, 1962 19 46 58.075

CASE 1

IBSYS-JPTRAJ-SPACE 022265

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GEOCENTRIC

| | | | | | |
|-------------------|-------------------|------------------|-------------------|-------------------|-------------------|
| X .-41051080 08 | Y .-38291325 08 | Z .-13671191 08 | DX .-76626395 01 | DY .-14910036 02 | DZ .-72400016 0 |
| R .57778180 08 | DEC .-13686847 02 | RA .22300789 03 | V .18117798 02 | PTH .468362926 02 | AZ .11985724 01 |
| ALT .57778180 08 | LAT .13686847 02 | LON .20326984 03 | VE .-6088328 04 | PTF .23682742 00 | AZE .26995322 01 |
| XS .19597573 08 | YS .-13388624 09 | ZS .58055864 08 | DXS .29999834 02 | OYS .-35449458 01 | D1S .-15359250 01 |
| XM .-22533850 06 | YM .28651450 06 | ZM .12794737 06 | DXM .-85853022 00 | OYM .-53210795 00 | D2M .-13040216 00 |
| XI .-41081809 08 | YI .-38295325 08 | ZI .-13647311 08 | DXI .-44356766 01 | OYI .-10890376 02 | DZI .-26676137 01 |
| RS .14724155 09 | VS .30247574 02 | VM .38631403 06 | VM .10184389 01 | RT .57797029 08 | VI .12057847 02 |
| GED .-13776577 02 | ALT .57771803 08 | LDS .24193441 03 | RAS .28167247 03 | RAM .12818941 03 | LDM .10844636 03 |
| DUT .-35000000 02 | B1 .24000000 03 | B2 .16899584 02 | SHA .-35380548 08 | DES .-23221698 02 | DEM .19341652 02 |
| ECL .-27338213 03 | MCL .-17998010 03 | TCL .32543668 03 | | | |

EQUATORIAL COORDINATES

HELIOCENTRIC

| | | | | | |
|------------------|------------------|------------------|-------------------|-------------------|-------------------|
| X .-21453306 08 | Y .95549416 08 | Z .44384672 08 | DX .-37462473 02 | DY .-11365090 02 | DZ .-57040765 01 |
| R .10755761 09 | LAT .24372012 02 | LDM .10264880 03 | V .39561833 02 | PTH .-72353166 01 | AZ .95856804 01 |
| XE .19597573 08 | YE .13388624 09 | ZE .58055864 08 | DXE .-29999834 02 | DYE .35449458 01 | DZE .15359250 01 |
| XI .-21484235 08 | YI .79590916 06 | ZI .44408532 08 | DXI .-34435511 02 | OYI .-73454299 01 | DZI .-11316886 01 |
| LTE .23221698 02 | LOE .81672475 02 | LOT .24382966 02 | LOT .10266685 03 | RST .10757004 09 | VST .35228003 02 |
| EPS .12302097 03 | ESP .19209271 02 | SEP .37769753 02 | EPH .37800648 00 | EMP .80678812 02 | HEP .98943153 02 |
| NPS .12339864 03 | HSP .19106508 02 | SMP .37494848 02 | SEM .13666413 03 | EMS .43232903 02 | ESM .10231907 00 |
| EP1 .11879526 03 | ETP .61110761 02 | TEP .33542591-01 | TPS .10851589 03 | FSP .18504685-01 | SIP .71464353 02 |
| SET .37795759 02 | STE .12297788 03 | EST .19225541 02 | RPM .57839493 08 | RPT .39109093 05 | SPN .12301465 03 |
| SAC .23814957-09 | | | | | |
| GCE .86617870 07 | LCT .23205454 03 | SIP .99394255 02 | CPT .11492423 03 | SIN .11080259 03 | |
| REP .57781800 08 | VEP .18177348 02 | CPE .80314971 02 | LPS .10271893 03 | | |

EQUATORIAL COORDINATES

APHRODOCENTRIC

| | | | | | |
|------------------|-------------------|------------------|------------------|------------------|------------------|
| X .30728787 05 | Y .40000217 04 | Z .-23859226 05 | DX .-30269631 01 | DY .-40196605 01 | DZ .-45723879 01 |
| R .39109093 05 | DEC .-37594455 02 | RA .74165933 01 | V .67990372 01 | PTH .75343634-06 | AZ .21192412 03 |
| ALT .32909093 05 | SHA .-37080350 05 | ALP .12618129 02 | DR .74910647-07 | DP .99607556-02 | ASD .91216356 01 |
| HGE .23697902 03 | SVL .-32544486 02 | HNG .11213077 03 | SIA .10967362 03 | | |
| SAC .23814957-09 | | | | | |

EQUATORIAL COORDINATES

APHRODOCENTRIC CONIC

| | | | | | |
|-----------------------------|--|------------------|------------------|------------------|------------------|
| EPOCH OF PERICENTER PASSAGE | 235605635514202411425970 J.D.= 2438013.32428326 DEC. 14, 1962 19 46 58.075 | | | | |
| SMA .-10964912 05 | ECC .45667493 01 | B .48858741 05 | SLR .21771052 06 | APD .00000000 00 | RCA .39109093 05 |
| VH .54423050 01 | C3 .29618684 02 | C1 .26590418 06 | IFP .98913489-04 | TF .10080794 03 | LTf .10077252 03 |
| TA .25133208-05 | MTA .14264878 03 | EA .00000000 00 | HA .28129103-05 | | TF1 .10000794 03 |
| LAE .13776038 03 | LAP .39971175 02 | ZAC .71965344 02 | DEF .25297576 02 | IR .13206245 05 | GP .-30444610 02 |

| | | | | | |
|-------------------|-------------------|-------------------|-------------------|------------------|------------------|
| X .30728787 05 | Y .40000217 04 | Z .-23859226 05 | DX .-30269631 01 | DY .-40196605 01 | DZ .-45723879 01 |
| INC .11477088 03 | LAN .20822792 03 | APF .22221299 03 | MX .-44520467 00 | MY .-59121025 00 | MZ .-67250520 00 |
| WX .-42946162 00 | WY .80000596 00 | WZ .-41809068 00 | PX .78157195 00 | PY .-10227857 00 | PZ .-61006449 00 |
| QX .44520466 00 | QY .22925609 00 | QZ .-67250520 00 | RX .33778184 00 | RY .71389431 00 | RZ .-61339898 00 |
| BX .86413916 00 | BY .22925609 00 | BZ .-44800129 00 | TX .-90392323 00 | TY .42769475 00 | TZ .00000000 00 |
| SXI .-26234753 00 | SYI .-55446560 00 | SZI .-78977317 00 | DAI .-52164318 02 | RAI .24467864 03 | |
| SXD .-60645214 00 | SYD .59929832 00 | SZD .-52259473 00 | DAO .-31506402 02 | RAO .22465815 03 | |
| EYE .30229105 03 | ETS .29230400 02 | ETC .25078851 03 | | | |

JPL TECHNICAL MEMORANDUM NO. 33-204

CASE 1

IS95S-JPTRAJ-SPACE 022265

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BTQ -33373639 05 BRQ .35684405 05 B .48858741 05 THA .13308353 03 T VECTOR IN EARTH EQUATOR PLANE

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X .30728787 05 Y -.58220504 04 Z -.23481196 05 DX -.30269631 01 DY -.55069064 01 DZ -.25958396 01
INC .13464185 03 LAN .21172739 03 APF .23754776 03 HY -.44520466 00 HV -.80995385 00 HZ -.38179517 00
WX -.42964161 00 WY .56728598 00 WZ -.70267300 00 PX -.78571975 00 PY -.14886692 00 PZ -.60040245 00
QX -.44520467 00 QY -.80995385 00 QZ -.38179519 00 RX -.15308934 00 RY -.48018908 00 RZ -.86370255 00
BX .86413918 00 BY .32104934-01 BZ -.50222781 00 TX -.95275295 00 TY .30374755 00 TZ .00000000 00
SX1 -.26234763 00 SY1 -.82289482 00 SZ1 -.50400189 00 DAI -.30265119 02 RAI -.25231716 03
SXD -.60645215 00 SYD -.75769880 00 SZD -.24105668 00 DAD -.13948913 02 RAD .23132667 03
ETE .31365265 03 ETS .40592002 02 ETC .26213010 03

BTQ -39749469 05 BRQ .28410497 05 B .48858742 05 THA .14444512 03 T VECTOR IN ECLIPTIC PLANE

-

X .15995859 04 Y -.32570000 05 Z -.21990682 05 DX -.60659888 01 DY -.14842515 01 DZ -.26884349 01
INC .13722957 03 LAN .13091610 03 APF .23438793 03 HY -.89218352 00 HV -.21803320 00 HZ -.39541406 00
WX .44981742 00 WY .50871417 00 WZ -.73408052 00 PX -.40900621-01 PY -.83279864 00 PZ -.55206295 00
QX -.89218351 00 QY .21803318 00 QZ -.39541406 00 RX -.50638494 00 RY -.18010652-01 RZ -.86211938 00
RX .23527313 00 RY -.86038996 00 RZ -.45207930 00 TX .35544639-01 TY .99936808 00 TZ .00000000 00
SX1 -.86157462 00 SY1 .30643724-01 SZ1 .50670514 00 DAI -.30444610 02 RAI .17796301 03
SXD -.87948699 00 SYD .39538650 00 SZD -.26493010 00 DAD -.15362798 02 RAD .15579407 03
ETE .30926123 03 ETS .61084647 02 ETC .27339349 03

BTQ -41602414 05 BRQ .25620609 05 B .48858741 05 THA .14837340 03 T VECTOR IN ORBIT PLANE OF TARGET

100 DAYS 19 HRS. 26 MIN. 19.059 SEC. 235605635567202607404611 J.D.= 2438013.32628540 DEC. 14,1962 19 49 51.059

GEOCENTRIC

EQUATORIAL COORDINATES

X -.41052372 08 Y -.38293904 08 Z -.13672441 08 DX -.74907017 01 DY -.14914270 02 DZ -.72176348 01
R .57701104 08 DEC -.13687417 02 RA .22200891 03 V .18183518 02 PTH .68464816 02 AZ .11972255 03
R .57781103 08 LAT .13687417 02 LON .20254812 03 VE .40880465 04 PTE .23706050 00 ALE .26999361 05
XS -.19592383 08 YS -.13388685 09 ZS -.58056129 08 DXS .29999978 02 DYS .35439873 01 DZS .15355094 01
XM -.22548650 08 YM .28642300 08 ZM .12192500 08 DXM -.85825494 00 DYM .53245151 00 DZM .13055575 00
XT -.41082576 08 YT -.38292208 08 ZT -.13647793 08 DAT -.44354135 01 OYT .10891180 02 OZT .26680171 01
RS .14724152 09 VS .30247584 02 RM .38632512 06 VM .10184061 01 RT .57798931 08 VT .12058464 02
GEO -.13777151 02 ALT .57774127 08 LOS .24121388 03 RAS .26167468 03 HAM .12821159 03 LOM .10775079 03
OUT .35000000 02 DT .24000000 03 OR .16914169 02 SHM .35391055 08 DES .23221815 02 DEH .19337558 02
CCL .27338252 03 MCL .17998012 03 ICL .32423100 03

HELIOCENTRIC

EQUATORIAL COORDINATES

X -.21549989 08 Y .9592949 08 Z .44383888 08 DX -.37490680 02 DY -.11370283 02 DZ -.56021254 01
R .10755675 09 LAT .24371643 02 LON .10265275 03 V .39958879 02 PTH .72124065 01 AZ .9582815 02
XE .19592383 08 YE .13388685 09 ZE .58056129 08 DXE .29999978 02 DYE .35439873 01 DZE .15355094 01
XT -.21490192 08 YT .95589645 08 ZT .44408336 08 DXT .34435114 02 DYT .17341930 01 DZT .11325077 01
LPS .23221815 02 LDE .81646807 02 LTT .24382856 02 LDT .10267041 03 RST .10757002 09 VST .35228410 02
MFE .12301850 03 ESP .19210847 02 SEP .37770653 02 EPM .37800648 00 EHP .80703614 02 MEP .98918331 01
HPS .12339419 03 MSP .19108037 02 SMP .37495776 02 SEM .13664028 03 EHS .43256699 02 ESM .10326686 00
EPT .11708922 03 ETP .62876250 02 TEP .33542591-01 FPS .10981217 03 TSP .15639313-01 STP .70168220 01
SET .37797812 02 STE .12297543 03 EST .19226755 02 RPH .57842256 08 RPT .39123598 05 SPN .12301217 03
SAC .23815338-09
GCE .86617480 02 GCT .23084848 03 SGP .10069395 03 CPT .12031818 03 SIM .11119995 03
SAC .23815338-09
TEP .17761104 08 TEP .18183518 02 CPA .80314-079 02 CPE .10271903 03

CASE 1

IS95S-JPTRAJ-SPACE 022265

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APHRODICENTRIC

EQUATORIAL COORDINATES

X .30202689 05 Y .33043787 04 Z -.24648217 05 DX -.30555658 01 DY -.40230900 01 DZ -.45496177 01
R .39123598 05 DEC .39050781 02 RA .64237123 01 V .67985849 01 PTH .14131968 01 AZ .12651649 03
ALT .29225999 05 SHA .36803285 02 ALP .14175582 02 DR .16766977 00 DP .99533717-02 ASD .91182247 01
HGE .23698150 03 SWL .33361545 02 HWG .11394177 03 SIA .10797099 03

APHRODICENTRIC CONIC

EPOCH OF PERICENTER PASSAGE 235605635514202411466611 J.D.= 2438013.32428326 DEC. 14,1962 19 46 58.075

SNA -.10964909 05 ECC .45667502 01 B .48858736 05 SLR .21771055 06 APD .00000000 00 RCA .39100092 05
VH .54423057 01 ECJ .29618692 02 C1 .26590420 06 EPF .17271361 03 TF .10080794 03 LTF .10077252 03
TA .17226236 01 HTA .10264878 03 CPA .13790468 01 HA .49193246 01 RA .49193246 01
ZAE .13776068 03 ZAP .39943169 02 ZAC .71965352 02 DEF .25297576 02 IR .13206244 05 GP .30444603 02

X .30202689 05 Y .33043787 04 Z -.24648217 05 DX -.30555658 01 DY -.40230900 01 DZ -.45496177 01
INC .11477088 03 LAN .20822792 03 APF .22221299 03 HY -.46862293 00 HV -.59401770 00 HZ -.65386199 00
WX .42964161 00 WY .56728598 00 WZ -.70267300 00 PX -.78571975 00 PY -.14886692 00 PZ -.60040245 00
QX -.44520467 00 QY -.80995385 00 QZ -.38179519 00 RX -.15308934 00 RY -.48018908 00 RZ -.86370255 00
BX .86413912 00 BY .32104934-01 BZ -.50222781 00 TX -.95275295 00 TY .30374755 00 TZ .00000000 00
SX1 -.26234762 00 SY1 -.82289483 00 SZ1 -.50400189 00 DAI -.30265119 02 RAI -.25231716 03
SXD -.60645213 00 SYD .39538650 00 SZD -.24105668 00 DAD .13948913 02 RAD .23132667 03
ETE .30228987 03 ETS .29226401 02 ETC .25076850 03

BTQ -33373633 05 BRQ .35684404 05 B .48858736 05 THA .13308352 03 T VECTOR IN EARTH EQUATOR PLANE

X .30202689 05 Y .33043787 04 Z -.24648217 05 DX -.30555658 01 DY -.40230900 01 DZ -.45496177 01
INC .13464185 03 LAN .21712739 03 APF .23754777 03 HY -.44520466 00 HV -.80995385 00 HZ -.38179517 00
WX .42964161 00 WY .56728598 00 WZ -.70267300 00 PX -.78571975 00 PY -.14886692 00 PZ -.60040245 00
QX -.44520467 00 QY -.80995385 00 QZ -.38179519 00 RX -.15308934 00 RY .48018908 00 RZ -.86370255 00
BX .86413913 00 BY .32104941-01 BZ -.50222789 00 TX -.95275253 00 TY .30374763 00 TZ .00000000 00
SX1 -.26234761 00 SY1 -.82289483 00 SZ1 -.50400177 00 DAI -.30265111 02 RAI .25231716 03
SXD -.60645214 00 SYD .39538648 00 SZD -.24105658 00 DAD -.13948908 02 RAD .23132667 03
ETE .31365147 03 ETS .40588005 02 ETC .26213010 03

BTQ -39749463 05 BRQ .28410495 05 B .48858736 05 THA .14444512 03 T VECTOR IN ECLIPTIC PLANE

X .59016583 03 Y -.32310610 05 Z -.22053972 05 DX -.60669888 01 DY .15147077 01 DZ -.2679470 01
INC .13722957 03 LAN .13091610 03 APF .23438794 03 HY -.89300985 00 HV .24323921 00 HZ -.37863977 00
WX .44981735 00 WY .50871418 00 WZ .73408053 00 PX .40900556-01 PY .83279862 00 PZ -.55206300 00
QX -.89218354 00 QY .21803321 00 QZ -.39541396 00 RX .50638483 00 RY -.18010669-01 RZ -.86211945 00
BX .86413913 00 BY .32104941-01 BZ -.50222789 00 TX .35544721-01 TY .99936808 00 TZ .00000000 00
SX1 -.86157468 00 SY1 .30643796-01 SZ1 .50670503 00 DAI -.30444602 02 RAI .17796300 03
SXD .87948700 00 SYD .39538648 00 SZD -.26493001 00 DAD -.15362798 02 RAD .15579407 03
ETE .30926022 03 ETS .61081146 02 ETC .27339349 03

BTQ -41602410 05 BRQ .25620611 05 B .48858738 05 THA .14837339 03 T VECTOR IN ORBIT PLANE OF TARGET

JPL TECHNICAL MEMORANDUM NO. 33-204

CASE 1 IBSYS-JPTRAJ-SPACE D22265 8

| | | | | | | |
|--------------|-----------------------------|--------------|-----------------------------|------------------------------|------------------------------|------------------|
| 625535100735 | 625730503775 21172191649 | 621602710213 | 601700276504 17448304640 | 602465436600 | 575674117131 000000000000 | EARTH INITIAL |
| 21727454543 | 214522350406 | 617601552025 | 602611220703 | 603400724620 235605635567 | 603442741665 202607404611 | VENUS END |

U MATRIX FOR MAPPING FORWARD

| | X | Y | Z | DX | DY | DZ | MV | AU |
|----|---------------|---------------|---------------|---------------|---------------|---------------|--------------|--------------|
| X | .39773183 01 | -.21087921 01 | .10280934 01 | .40090036-06 | -.12381001-05 | .60017031-06 | .00000000 00 | .00000000 00 |
| Y | -.42917053 00 | .30646667 00 | -.21520492 00 | -.14571548-06 | -.55214985-08 | -.10965675-06 | .00000000 00 | .00000000 00 |
| Z | -.15201560 00 | -.16763731 00 | -.13895442 00 | .55276687-07 | -.73585203-07 | -.18714900-06 | .00000000 00 | .00000000 00 |
| DX | -.13987192 08 | -.68392637 07 | -.33544449 07 | -.16401137 01 | -.40547289 01 | .19595122 01 | .00000000 00 | .00000000 00 |
| DY | -.36523107 07 | -.79537667 07 | -.19422097 07 | -.14248229 01 | -.25076387 01 | -.14931677 01 | .00000000 00 | .00000000 00 |

DDPX*14130

621200700.0000000

| | | | | | | | |
|-----|----------------------------|-----|----------------------------|-----|----------------|----|----------|
| X* | -.36497317E+08 | Y* | -.29912202E+08 | Z* | -.94567338E+07 | \$ | 0 0 0 1 |
| DX* | -.73404306E+01 | DY* | -.10826458E+02 | DZ* | -.54166483E+01 | \$ | 0 0 0 2 |
| R01 | 243474261372210626001145/8 | | 242576315205207014363212/8 | | | \$ | 0 0 0 3 |
| | 241566472073206622212017/8 | | 214557475024161672110320/8 | | | \$ | 0 0 0 4 |
| | 21565461634015260352574/8 | | 214635656735161265311433/8 | | | \$ | 0 0 0 5 |
| | 54303671621510360007741/8 | | 177573736517144520000000/8 | | | \$ | 0 0 0 6 |
| R02 | 242576315205207014363212/8 | | 242523635265207430612242/8 | | | \$ | 0 0 0 7 |
| | 241435426012206550201533/8 | | 214453020170161507154504/8 | | | \$ | 0 0 0 8 |
| | 215474360771162436676672/8 | | 214477343136161731064435/8 | | | \$ | 0 0 0 9 |
| | 544502533776511164214012/8 | | 200507013020145560000000/8 | | | \$ | 0 0 0 10 |

DDPX*14130

| | | | | | | | |
|-----|-----------------------------|--|----------------------------|--|--|----|----------|
| R03 | 241566472073206622272011/8 | | 241435426012206550201534/8 | | | \$ | 0 0 0 11 |
| | 240714243507205560127535/8 | | 213443050761160413054706/8 | | | \$ | 0 0 0 12 |
| | 214501770732161554051315/8 | | 212772213025157172636427/8 | | | \$ | 0 0 0 13 |
| | 5445506524675110635912227/8 | | 200406075474145460000000/8 | | | \$ | 0 0 0 14 |
| R04 | 214557475024161672110322/8 | | 214453020170161507154504/8 | | | \$ | 0 0 0 15 |
| | 213443050767160413054706/8 | | 166420613606133125331104/8 | | | \$ | 0 0 0 16 |
| | 167447242664134104655056/8 | | 166434734635133525462314/8 | | | \$ | 0 0 0 17 |
| | 51755136273446464233410/8 | | 550774612640515700000000/8 | | | \$ | 0 0 0 18 |
| R05 | 21565461634016260352574/8 | | 215474360771162436676673/8 | | | \$ | 0 0 0 19 |
| | 214501770732161554051315/8 | | 167447242664134104655056/8 | | | \$ | 0 0 0 20 |

DDPX*14130

| | | | | | | | | |
|-----|-----------------------------|---------------|----------------------------|---------------|---------------|---------------|--------------|--------------|
| | 170507327007135360406204/8 | | 167467560104134725552126/8 | | | \$ | 0 0 0 21 | |
| | 520724131133465015437024/8 | | 154513072266121140000000/8 | | | \$ | 0 0 0 22 | |
| R06 | 214695656135161265311473/8 | | 214477343136161731064435/8 | | | \$ | 0 0 0 23 | |
| | 212772213025157172636427/8 | | 166434734635133525462314/8 | | | \$ | 0 0 0 24 | |
| | 167467560104134725552126/8 | | 166477114443133230565525/8 | | | \$ | 0 0 0 25 | |
| | 5212423551405466611542605/8 | | 153566167242120740000000/8 | | | \$ | 0 0 0 26 | |
| R07 | 54303671621510360007741/8 | | 544502533776511164214012/8 | | | \$ | 0 0 0 27 | |
| | 544550652467511063531222/8 | | 51755136273446464233410/8 | | | \$ | 0 0 0 28 | |
| | 520724131133465015437024/8 | | 52142355140546611542605/8 | | | \$ | 0 0 0 29 | |
| | 10544711354052351103530/8 | | 0000000000000000000000/8 | | | \$ | 0 0 0 30 | |
| DZ | -.18190670 07 | -.19553291 07 | -.48569464 07 | .69472166 00 | .15003603 01 | .13430120 00 | .00000000 00 | .00000000 00 |
| MV | -.94537556 09 | -.23478037 10 | -.26254072 10 | -.12541165 04 | -.32486109 04 | -.38261904 04 | .10000000 01 | .00000000 00 |
| AU | -.14841206-01 | .25948558-01 | -.20478152-01 | -.23691501-08 | -.24669914-07 | -.16027430-07 | .00000000 00 | .10000000 01 |

CONDITIONS AFTER FORWARD MAPPING 62/09/05 002332.000 TD 62/12/07 000000.000

X* -.36497317 08 Y* -.29912202 08 Z* -.94567338 07 DX* -.73404306 01 DY* -.10826458 02 DZ* -.54166483 01

STANDARD DEVIATIONS

X* .14570403 06 Y* .10678034 06 Z* .62140492 05 DX* .22809497-01 DY* .49980155-01 DZ* .24672443-01

COVARIANCE MATRIX AFTER MAPPING

| | X | Y | Z | DX | DY | DZ | MV | AU |
|----|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| X | -.21229665 11 | -.12831745 11 | -.62849716 10 | .29409537 04 | -.68604511 04 | -.33107333 04 | -.94537555-09 | -.37103015 00 |
| Y | -.12831245 11 | -.11402042 11 | -.47906166 10 | -.23922537 04 | -.50635308 04 | -.2555497 04 | -.23478037-08 | -.63871396 00 |
| Z | -.62849716 10 | -.47906166 10 | -.38614407 10 | .11643202 04 | -.25758895 04 | -.10125431 04 | -.26254072-08 | -.51195380 00 |
| DX | .29409537 04 | .23922537 04 | -.11643202 04 | -.52027313-03 | .11265490-02 | .54346325-03 | -.12541165-14 | -.59228753-07 |
| DY | -.68604511 04 | -.50635308 04 | -.25758895 04 | .11265490-02 | -.24980159-02 | .11891137-02 | -.32486109-14 | .61674783-06 |
| DZ | -.33107333 04 | -.2555497 04 | -.10125431 04 | .54346325-03 | -.11891137-02 | -.68872945-03 | -.38261903-14 | -.40068574-06 |
| MV | -.94537555-09 | -.23478037-08 | -.26254072-08 | -.12541165-14 | -.32486109-14 | -.38261903-14 | .99999998-18 | .00000000 00 |
| AU | -.37103015 00 | -.63871396 00 | -.51195380 00 | -.59228753-07 | .61674783-06 | .40068574-06 | .00000000 00 | .25000000 02 |

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CASE 1 IBSYS-JPTRAJ-SPACE 022265

DOUBLE PRECISION EPHEMERIS TAPE - EPHE41

GME .39860063 06 J .16234500-02 H -.57499999-05 D .78749999-05 RE .63781650 04 REM .63783112 04
 G .66710998-19 A .80781796 29 B .88800194 29 C .88836975 29 DME .41780741-02 AU .14959050 09
 'GMH .49026293 04 GMS .13271411 12 GNV .32476627 06 GMA .42977368 05 GMC .37918700 08 GMJ .12670935 09
 EGM .39860320 06 YGM .49027779 04 JA .29200000-02 HA .00000000 00 DA .00000000 00 RA .34170000 04
 RADIATION PRESSURE INPUT
 ARA .38300000 01 GB .38300000 00 HAS .19822000 03 GBI .00000000 00 S02 .00000000 00 SC .10310000 09

INJECTION CONDITIONS VENUS 235605123440202000000000 J.D.= 2438009.50000000 DEC. 7.1962 00 00 00.000

GEOCENTRIC TD-.36497317 08 YO-.29912202 08 Z0-.94567338 07 DXD-.73404306 01 DYD-.10826458 02 DZD-.54166483 01
 CARTESIAN TD .00000000 00 DHA .75283983 02 GHD .75283983 02
 DATE OF RUN 022265A 1435 SUN IS THE CENTRAL BODY FOR INTEGRATION COWELL EQUATIONS OF MOTION

2 DAYS 14 HRS. 37 MIN. 51.431 SEC. 235605301517202667117775 J.D.= 2438008.10962304 DEC. 9.1962 14 37 51.431

HELIOCENTRIC EQUATORIAL COORDINATES

X -.51022667 07 Y .99263156 08 Z .46385103 08 DX -.36494255 02 DY -.58201981 01 DZ -.33262720 01
 R .10968849 09 LAT .25017435 02 LON .92942495 02 V .37104844 02 PTH .77073117 01 AZ .92101534 02
 XE .33012537 08 YE .13172989 09 ZE .57121303 08 DXE -.29507275 02 DYE .60187012 01 DZE .26093421 01
 XT -.57926456 07 YT .97856441 08 ZT .44437148 08 DXT -.35091491 02 DYT .26941837 01 DZT .10045197 01
 LTE .22812464 02 LOE .75930985 02 LIT .24385356 02 LOT .93387689 02 RST .10762945 09 VST .35209096 02
 EPS .12889057 03 ESP .15695705 02 SEP .35413716 02 EPM .79129368-01 EMP .11190247 02 MEP .16873040 03
 MPS .12896821 03 MSP .15754197 02 SMP .35277589 02 SEM .15951569 03 EMS .24425447 02 ESM .57674939-01
 EPT .13652552 03 ETP .41616357 02 TEP .18581082 01 TPS .34321416 02 TSP .75039911 00 STP .14492818 03
 SET .34151907 02 STE .12978487 03 EST .16063214 02 RPM .51564819 08 RPT .25000001 07 SPW .12888343 03
 S4C .22900140-09
 GCE .87219449 02 GCT .32905258 03 S1P .34179322 02 CPT .72719294 02 S1N .72577199 02
 REP .51206376 08 VEP .14973609 02 CPE .80195375 02 CPS .10226691 03

HELIOCENTRIC CONIC

EPOCH OF PERICENTER PASSAGE 235607605023202607117775 J.D.= 2438037.01350758 JAN. 7.1963 12 19 27.056
 SMA .12722491 09 FCC .19144538 00 B .12487167 09 SLR .12256195 09 APD .15158153 09 RCA .10288829 09
 VHI .26606642 02 C3 .10431457 04 C1 .40330757 10 TFP .24972956 07 TF .31513507 02 PER .28646119 03
 TA -.52176596 02 MTA .18000000 03 EA -.43934648 02 MA -.36323937 02 TFI .26096230 01

ALL VECTORS REFERENCED TO EARTH EQUATOR PLANE

X -.51022667 07 Y .99263156 08 Z .46385103 08 DX -.36494255 02 DY -.58201981 01 DZ -.33262720 01
 INC .25099881 02 LAN .35794326 03 APF .14656952 03 MX .-99880594 00 MY .-35811855-01 MZ .-33229988-01
 MX .-14928002-01 MY .-42393484 00 WZ .90556967 00 PX .-81748733 00 PY .52667545 00 PZ .23302869 00
 OX .-57575317 00 OY .-73681227 00 OZ .-35442357 00 RX .-19593890 00 RY .12623585 00 RZ .-97245697 00
 BX .-57575314 00 BY .73681223 00 BZ .35442355 00 TX .54159255 00 TY .84064113 00 TZ .00000000 00
 DAP .13478631 02 RAP .14720788 03

BTQ .11628278 09 BRO .-45510973 08 B .12487167 09 THA .33862552 03 T VECTOR IN EARTH EQUATOR PLANE

ALL VECTORS REFERENCED TO ECLIPTIC PLANE

X -.51022667 07 Y .10952327 09 Z .30665980 07 DX -.36494255 02 DY .-66630846 01 DZ .-73627058 00
 INC .18528344 01 LAN .33250317 03 APF .17232766 03 MX .-99880594 00 MY .-46075798-01 MZ .16240136-01
 MX .-14928002-01 MY .-28680308-01 WZ .99947717 00 PX .-81748730 00 PY .57593041 00 PZ .43166661-02
 OX .-57575309 00 OY .-81695466 00 OZ .-32043278-01 RX .-35288931-02 RY .24861228-02 RZ .-99999066 00
 BX .-57575310 00 BY .81695467 00 BZ .32043278-01 TX .57593579 00 TY .81749494 00 TZ .00000000 00

CASE 1 IBSYS-JPTRAJ-SPACE 022265

DAP .24732883 00 RAP .14483480 03

BIC .12480753 09 URC .-40013344 07 B .12487165 09 THA .35816372 03 T VECTOR IN ECLIPTIC PLANE

ALL VECTORS REFERENCED TO ORBIT PLANE OF TARGET

X .10522014 09 Y .30951206 08 Z .12362214 07 DX .-69869809 01 DY .-11838899 02 DZ .-59356140 01
 INC .62377892 01 LAN .20514101 03 APF .22340358 03 MX .28065739 00 MY .95702552 00 MZ .-73031394-01
 XE .31394514-01 YE .66895417-01 WZ .99726596 00 PX .36657501 00 PY .92900175 00 PZ .-50776340-01
 OX .-92985853 00 OY .36397868 00 OZ .-53687747-01 RX .-18637381-01 RY .-47232243-01 RZ .-99870991 00
 BX .92985865 00 BY .-36397873 00 BZ .53687754-01 TX .93020180 00 TY .-36704854 00 TZ .00000000 00
 DAP .-29105203 01 RAP .68466288 02

BTQ .12469108 09 BRO .-67127359 07 B .12487163 09 THA .35691845 03 T VECTOR IN ORBIT PLANE OF TARGET

2 DAYS 14 HRS. 37 MIN. 51.431 SEC. 235605301517202667117775 J.D.= 2438008.10962304 DEC. 9.1962 14 37 51.431
 CHANGE OF PHASE OCCURS AT THIS POINT
 PROBE IS LEAVING VENUS* SHADOW

2 DAYS 14 HRS. 37 MIN. 51.431 SEC. 235605301517202667117775 J.D.= 2438008.10962304 DEC. 9.1962 14 37 51.431

GEOCENTRIC EQUATORIAL COORDINATES

X .-38114804 08 Y .-32466733 08 Z .-10736199 08 DX .-69869809 01 DY .-11838899 02 DZ .-59356140 01
 R .51206376 08 DEC .-12102737 02 RA .22042483 03 V .14973609 02 PTH .68707164 02 AZ .12448867 03
 R .51206376 08 LAT .-12102737 02 LON .28310441 03 VE .36465785 04 PTE .21920980 00 ALE .26995161 03
 XS .-33012537 08 YS .-13172989 09 ZS .-57121302 08 DXS .-29507274 02 DYS .-60187012 01 DZS .-26093421 01
 XM .21915100 06 YM .27889500 06 ZM .87959750 05 DXM .-85011119 00 DYM .59271622 00 DZM .29599127 00
 YT .-38805183 08 YT .-33873448 08 ZT .-12684155 08 DYT .-55842176 01 DYT .-87128849 01 DZT .-16048224 01
 RS .14732764 09 VS .30227679 02 RM .36544016 06 VM .10777812 01 RT .53048472 08 VT .10472502 02
 GED .-12182759 02 ALT .91199998 08 LOS .31861057 03 RAS .25593098 03 RAM .51840329 02 LHM .11451991 03
 DUT .35000000 02 DT .38400000 04 DR .13951460 02 SHA .-29672880 08 DES .-22812463 02 DEB .13927585 02
 CCL .27278050 03 HCL .17997891 03 TCL .61833074 02

HELIOCENTRIC EQUATORIAL COORDINATES

X -.51022667 07 Y .99263156 08 Z .46385103 08 DX -.36494255 02 DY -.58201981 01 DZ -.33262720 01
 R .10968849 09 LAT .25017435 02 LON .92942495 02 V .37104844 02 PTH .77073117 01 AZ .92101534 02
 XE .33012537 08 YE .13172989 09 ZE .57121302 08 DXE .-29507274 02 DYE .60187012 01 DZE .26093421 01
 XT -.57926456 07 YT .97856441 08 ZT .44437148 08 DXT -.35091491 02 DYT .26941837 01 DZT .10045197 01
 LTE .22812464 02 LOE .75930985 02 LIT .24385356 02 LOT .93387689 02 RST .10762945 09 VST .35209096 02
 EPS .12889057 03 ESP .15695707 02 SEP .35413716 02 EPM .79129368-01 EMP .11190247 02 MEP .16873051 03
 MPS .12896821 03 MSP .15754197 02 SMP .35277589 02 SEM .15951569 03 EMS .24425447 02 ESM .58516955-01
 EPT .13652552 03 ETP .41616357 02 TEP .18581082 01 TPS .34321416 02 TSP .75039911 00 STP .14492818 03
 SET .34151907 02 STE .12978487 03 EST .16063214 02 RPM .51564819 08 RPT .25000001 07 SPW .12888343 03
 S4C .22900140-09
 GCE .87219449 02 GCT .32905258 03 S1P .34179322 02 CPT .72719294 02 S1N .72577199 02
 REP .51206376 08 VEP .14973609 02 CPE .80195375 02 CPS .10226691 03

JPL TECHNICAL MEMORANDUM NO. 33-204

CASE 1

IBSYS-JPTRAJ-SPACE D22263

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APHRHOICENTRIC EQUATORIAL COORDINATES
X .69037884 06 Y -14067148 07 Z -19479564 07 DX -14027633 01 DY -31260145 01 DZ -43307917 01
R .25000001 07 DEC .91185798 02 RA .63859482 02 V -.55222701 01 PTH -.80684723 02 AZ .24853656 03

APHRHOICENTRIC CONIC

EPOCH OF PERICENTR PASSAGE 235405634233202077171775 J.D.= 2438013.27238062 DEC. 14, 1962 19 01 00.493
SMA -.10761169 05 ECC .94575904 01 B .57628458 05 SLR .30918769 06 APD .00000000 00 RCA .47879731 05

X .69037884 06 Y -14067148 07 Z -19479564 07 DX -14027633 01 DY -31260145 01 DZ -43307917 01
INC .12568510 03 LAN .18063479 03 APF .20564165 03 MX .96107231 00 MY -15407576 00 MZ -22934989 00

BTQ -.54181293 05 BRQ .19632282 05 B .57628458 05 THA .16008230 03 T VECTOR IN EARTH EQUATOR PLANE

X .69037884 06 Y -20655583 07 Z -12275367 07 DX -14027633 01 DY -45999088 01 DZ -27297030 01
INC .14912548 03 LAN .18100483 03 APF .20613378 03 MX .96107233 00 MY -23260024 00 MZ -14912356 00

BTC -.56899888 05 BRC .91346706 04 B .57628458 05 THA .17087959 03 T VECTOR IN ECLIPTIC PLANE

X .21701734 07 Y -11003277 06 Z -12362202 07 DX -47923297 01 DY -11075377 00 DZ -27414250 01
INC .14982230 03 LAN .99027389 02 APF .19959053 03 MX .95282394 03 MY -99930256 00 MZ -90315392 01

BTQ -.57309813 05 BRQ .52309864 04 B .57628455 05 THA .17478394 03 T VECTOR IN ORBIT PLANE OF TARGET

7 DAYS 19 HRS. 46 MIN. 58.744 SEC. 235605635514202537267173 J.D.= 2438013.32429101 DEC. 14, 1962 19 46 58.745

CASE 1

IBSYS-JPTRAJ-SPACE D22265

GEOCENTRIC EQUATORIAL COORDINATES
X -.41051080 08 Y -.38291332 08 Z -.13671194 08 DX -.74625149 01 DY -.14909948 02 DZ -.72400025 01
R .57778186 08 DEC -.13688449 02 RA .22300790 03 V .18177275 02 PTH .68362656 02 AZ .11985742 03

Heliocentric EQUATORIAL COORDINATES
X -.21653526 08 Y .95949411 08 Z -44384671 08 DX -37462349 02 DY -11365006 02 DZ -.57040790 01
R .10755761 09 LAT .24372011 02 LON .10264881 03 V .39561692 02 PTH -.72352603 01 AZ .95858868 02

APHRHOICENTRIC EQUATORIAL COORDINATES
X .30731973 05 Y .40003297 04 Z -.23860705 05 DX .30268405 01 DY -.40195693 01 DZ -.45723873 01
R .39112531 05 DEC -.3793313 02 RA .74163977 01 V .67980284 01 PTH .50229894 06 AZ .21192407 03

EPOCH OF PERICENTR PASSAGE 235605635514202537267173 J.D.= 2438013.32429101 DEC. 14, 1962 19 46 58.745
SMA -.10964920 05 ECC .45670502 01 B .48862287 05 SLR .21774191 06 APD .00000000 00 RCA .39112530 05

X .30731973 05 Y .40003297 04 Z -.23860705 05 DX .30268405 01 DY -.40195693 01 DZ -.45723873 01
INC .11477124 03 LAN .20822719 03 APF .22221180 03 MX -.44519378 00 MY -.59120630 00 MZ -.67251588 00

JPL TECHNICAL MEMORANDUM NO. 33-204

CASE 1

IBSYS-JPTRAJ-SPACE 022265

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BTQ -33376521 05 BRQ .35686536 05 B .48862267 05 THA -13308429 03 T VECTOR IN EARTH EQUATOR PLANE

X .30731973 05 Y -.58223563 04 Z -.23482676 05
 INC -13464238 03 LAN .21712663 03 APF .23754634 03
 MX -.42945021 00 MY .56728648 00 WZ -.70267956 00
 OX -.44519377 00 OY -.80995446 00 OZ -.38180655 00
 BX -.86414488 00 BY .32097549 01 BZ -.50221853 00
 SXI -.26234738 00 SVI -.82289474 00 SZI -.50400203 00
 SXO -.60643401 00 SYO -.75770547 00 SZO -.24108124 00
 ETE .31365265 03 ETS .40592005 02 ETC .26213010 03

ALL VECTORS REFERENCED TO ECLIPTIC PLANE
 DX -.30268405 01 DY -.55068224 01 DZ -.25958754 01
 MX -.44519377 00 MY -.80995448 00 MZ -.38180656 00
 PX -.78573216 00 PY -.14888166 00 PZ -.60038753 00
 RX -.15308931 00 RY .48018924 00 RZ -.86730243 00
 TX -.30374752 00 TY .03374752 00 TZ .00000000 00
 DAI -.30265128 02 DAI -.25231717 03
 DAO -.13950363 02 RAD .23132775 03

BTC -.39752716 05 BRC .28412022 05 B .48862270 05 THA .14444588 03 T VECTOR IN ECLIPTIC PLANE

X .16000420 04 Y -.32573250 05 Z -.21591972 05
 INC -13723007 03 LAN .13851527 03 APF -.23438643 03
 MX .44982056 00 MY .50870284 00 WZ -.73408642 00
 OX -.89218155 00 OY .21829177 00 OZ -.39542477 00
 BX .23526740 00 BY -.86039665 00 BZ -.45206955 00
 SXI -.86157454 00 SVI .30643560 01 SZI -.50670528 00
 SXO -.87968921 00 SYO .39543584 00 SZO -.26495350 00
 ETE .30926123 03 ETS .61084645 02 ETC .27339349 03

ALL VECTORS REFERENCED TO DRBIT PLANE OF TARGET
 DX -.60658784 01 DY .14841501 01 DZ -.26884667 01
 MX -.89218155 00 MY -.21829178 00 MZ -.39542477 00
 PX -.40908683 01 PY -.83280857 00 PZ -.55204743 00
 RX -.50638509 00 RY -.18010562 01 RZ -.86211930 00
 TX .35444553 01 TY .99936869 00 TZ .00000000 00
 DAI -.30444619 02 DAI .17796302 03
 DAO -.15364189 02 RAD .15579524 03

BTD -.41605749 05 BRD .25621909 05 B .48862269 05 THA -14837416 03 T VECTOR IN ORBIT PLANE OF TARGET

7 DAYS 19 HRS. 49 MIN. 51.431 SEC. 235605635567202667117775 J.D.= 2438013.32628971 DEC. 14, 1967 19 49 51.431

GEOCENTRIC EQUATORIAL COORDINATES

X -.41052371 08 Y -.38293907 08 Z -.13672442 08
 RA -22300892 03 DEC -13687418 02
 LON -13687418 02 LAT -13687418 02
 XS -.19592373 08 YS -.13388685 09 ZS -.58056130 08
 XM -.22548700 06 YM .28642250 06 ZM .12792487 06
 XI -.41082577 08 YI .38297212 08 ZI -.13647794 08
 RS .14726152 09 VS .30247584 02
 GED -.13777152 02 ALT .57774727 08
 DUT -13500000 02 DT .24000000 03
 CCL .27338252 03 MCL .17998012 03 TCL .32423443 03

DX -.74905246 01 DY -.14916115 02 DZ -.72176794 01
 VE .40884644 04 VE .40884644 04
 OXS .29999978 02 OYS .35439852 01 OZS .15355085 01
 OXM -.85825437 00 OYM .53245234 00 OZM -.13056008 00
 OXT -.44351348 01 OYT .10891182 02 OZT .26680179 01
 VM .10184061 01 RT .57798935 08 VT .12058465 02
 RAS .26167468 03 RAM .12821110 03 LDM .10774934 03
 SHA -.35391056 04 DES -.23221815 02 DEH .19337945 02

HELIOCENTRIC EQUATORIAL COORDINATES

X -.21459998 08 Y .95592947 08 Z .44383687 08
 LAF .24371643 02 LDM -10265216 03
 VE .13388685 09 VE .13388685 09
 XT -.21490205 08 YI .95596642 08 ZI .44408336 08
 LIE .23221815 02 LOE .81674692 02 LIT .24382856 02
 EPS .12301850 03 ESP .19210845 02 SEP .37770653 02
 MPS .12339618 03 MSP .19108037 02 SMP .37495777 02
 EPT .11709311 03 ETP .62872362 02 TEP .34970568 01
 SET .37797815 02 STE .12297542 03 EST .19226759 02
 SAC .23815338 09
 GCL .86617479 02 GCT .23085190 03
 REP .57781104 08 VEP .18183384 02 CPE .80314978 02

SIP .10069221 03 CPT .12031658 03
 CPS .10271903 03

CASE 1

IBSYS-JPTRAJ-SPACE 022265

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APHRODITICENTRIC EQUATORIAL COORDINATES

X .30206808 05 Y .33059017 04 Z -.24648340 05
 DEC -.39049491 02 RA .49862266 05
 ALI .32924984 05 SMA .26807055 05 ALP .16171916 02
 HGE .23698150 03 SVL -.33359017 02 HNG .11393792 03
 SAC .23815338 09

DX -.30553899 01 DY -.40229929 01 DZ -.45496615 01
 PTH .14108130 01 AZE .26995601 03
 DYE .35439852 01 DZE .15355085 01
 OYT .17347198 01 OZT .11325095 01
 RST .10757002 09 VST .35228410 02
 EMP .80703716 02 MEP .98918229 02
 EMS .43258800 02 ESM .10231507 00
 TSP .18504695 01 SIP .70170748 02
 RPT .39126494 05 SPN .12301217 03

APHRODITICENTRIC CONIC

EPDCH OF PERICENTER PASSAGE 2356056355614207537325475 J.D.= 2438013.32429103 DEC. 14, 1967 19 46 58.745

SMA -.10964917 05 ECC .45670611 01 B .49862266 05 SLR .2176185 06 APO .00000000 00
 YH .54423037 01 C3 .29618670 02 C1 .26592331 06 TFP .17268546 03 TF .78242908 01
 VA .17194770 01 PTA .10264791 03 EA .13765490 01 MA .49108403 01
 ZAE .13776067 03 ZAP .39973174 02 ZAC .71965343 02 DEF .25295826 02 IR .13206248 05

ALL VECTORS REFERENCED TO EARTH EQUATOR PLANE
 DX -.30553899 01 DY -.40229929 01 DZ -.45496615 01
 MX -.46857002 00 MY -.59400908 00 MZ -.63390773 00
 PX -.78573216 00 PY .10227740 00 PZ -.61005274 00
 RX .33778181 00 RY .71389436 00 RZ -.81339893 00
 TX .90492326 00 TY .42763471 00 TZ .00000000 00
 DAI .52164319 02 DAI .24647864 03
 DAI -.31508153 02 RAD .22465883 03

BTQ -33376518 05 BRQ .35686538 05 B .48862266 05 THA -13308428 03 T VECTOR IN EARTH EQUATOR PLANE

X .30206808 05 Y .33059017 04 Z -.24648340 05
 INC -13464238 03 LAN .21712663 03 APF .22221180 03
 MX -.42945024 00 MY .80000898 00 WZ -.41899656 00
 OX -.44519382 00 OY -.80995450 00 OZ -.38180645 00
 BX .86414484 00 BY .22924561 00 BZ -.44719571 00
 SXI -.26234749 00 SVI -.55445595 00 SZI -.78977310 00
 SXO .60643400 00 SYO .59925471 00 SZO -.52261987 00
 ETE .30228987 03 ETS .29228412 02 ETC .25076851 03

ALL VECTORS REFERENCED TO ECLIPTIC PLANE
 DX -.30553899 01 DY -.55009224 01 DZ -.25736633 01
 MX -.46857002 00 MY -.80512304 00 MZ -.36361931 00
 PX .78573209 00 PY .14888163 00 PZ -.60038754 00
 RX .15308932 00 RY .48018912 00 RZ -.86730243 00
 TX .95275257 00 TY .30374750 00 TZ .00000000 00
 DAI .30265120 02 DAI .25231716 03
 DAO -.13950360 02 RAD .23132775 03

BTC -.39752710 05 BRC .28412022 05 B .48862266 05 THA .14444588 03 T VECTOR IN ECLIPTIC PLANE

X .16000420 04 Y -.32314327 05 Z -.22054476 05
 INC -13723007 03 LAN .13851527 03 APF -.23438645 03
 MX .44982048 00 MY .50870296 00 WZ -.73408640 00
 OX -.89218161 00 OY .21829185 00 OZ -.39542464 00
 BX .23526730 00 RY -.86039658 00 BZ -.45206972 00
 SXI -.86157462 00 SVI .30643707 01 SZI -.50670516 00
 SXO -.87948925 00 SYO .39543587 00 SZO -.26495338 00
 ETE .30926021 03 ETS .61081140 02 ETC .27339348 03

ALL VECTORS REFERENCED TO DRBIT PLANE OF TARGET
 DX -.60658877 01 DY .15145495 01 DZ -.26680164 01
 MX -.89300706 00 MY .24318280 00 MZ -.37888185 00
 PX .40908606 01 PY .83280846 00 PZ -.55204755 00
 RX .50638496 00 RY .18010642 01 RZ -.86211938 00
 TX .3544620 01 TY .99936808 00 TZ .00000000 00
 DAI .17796301 03 DAI .17796301 03
 DAO -.15364182 02 RAD .15579524 03

BTD -.41605749 05 BRD .25621916 05 B .48862266 05 THA -14837414 03 T VECTOR IN ORBIT PLANE OF TARGET

JPL TECHNICAL MEMORANDUM NO. 33-204

CASE 1 105Y5-JPTRAJ-SPACE 022265 7

| | | | | | | |
|--------------|--------------|--------------|--------------|--------------|--------------|---------|
| 632427135666 | 631706661666 | 630437201056 | 603730124337 | 604531616254 | 603532066024 | EARTH |
| | 21174200096 | | 17448304640 | | 000000000000 | INITIAL |
| 217727515530 | 214622511174 | 617601553043 | 602611205256 | 603400721472 | 603442741230 | VENUS |
| | | | | 235605635567 | 202667111775 | END |

U MATRIX FOR MAPPING FORWARD ITERATION NUMBER 0

| | X | Y | Z | DX | DY | DZ | HV | AU |
|----|---------------|---------------|---------------|---------------|---------------|---------------|--------------|--------------|
| X | .10966738 01 | .22628337 00 | .95824143-01 | .38971570-04 | .29859219-04 | -.13719305-04 | .00000000 00 | .00000000 00 |
| Y | .26846167 00 | .10270700 01 | .15922670 00 | .38408640-04 | -.12657212-04 | -.40772528-05 | .00000000 00 | .00000000 00 |
| Z | .14890519 00 | .18058750 00 | .92539933 00 | -.46092930-07 | -.31993660-05 | -.22687172-04 | .00000000 00 | .00000000 00 |
| DX | .75527639 06 | .15126123 06 | .61127321 05 | -.27719612 02 | .20412752 02 | -.94570449 01 | .00000000 00 | .00000000 00 |
| DY | .16940998 06 | .67661268 06 | .87107397 05 | .25112386 02 | -.75215715 01 | -.23777418 01 | .00000000 00 | .00000000 00 |
| DZ | .90707747 05 | .10145706 06 | .62498159 06 | -.10337408 01 | -.21220986 01 | -.14140570 02 | .00000000 00 | .00000000 00 |
| HV | -.11663469 11 | -.12298978 11 | -.11436336 11 | -.11459670 07 | -.46888873 06 | .27653503 06 | .10000000 01 | .00000000 00 |
| AU | .10846571 00 | .76123472-01 | .54280288-01 | .20273964-04 | .53912774-05 | -.67916350-05 | .00000000 00 | .10000000 01 |

COVARIANCE MATRIX AT IMPACT ITERATION NUMBER 0

| | X | Y | Z | DX | DY | DZ | HV | AU |
|----|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| X | .47125286 11 | .38625947 11 | .20113070 11 | .24072435 07 | .73161593 06 | -.88647863 06 | -.15561391-07 | .34610615 01 |
| Y | .38625947 11 | .34565694 11 | .17722058 11 | .20495190 07 | .54127742 06 | -.74744181 06 | -.18174269-07 | .31844926 01 |
| Z | .20113070 11 | .17722058 11 | .10110164 11 | .10488527 07 | .28992393 06 | -.41058659 06 | -.17080953-07 | .22685311 01 |
| DX | .24072435 07 | .20495190 07 | .10488527 07 | .10488527 07 | .35761035 02 | -.45555512 02 | -.13852334-11 | .55924926-03 |
| DY | .73161593 06 | .54127742 06 | .28992393 06 | .35761035 02 | .12467717 02 | -.13385001 02 | -.48508475-12 | .13441655-03 |
| DZ | -.88647863 06 | -.74744181 06 | -.41058659 06 | -.45555512 02 | -.13385001 02 | .17365259 02 | .43232970-12 | -.19567239-03 |
| HV | -.15561391-07 | -.18174269-07 | -.17080953-07 | -.13852334-11 | -.48508475-12 | .43232970-12 | .99999998-18 | .00000000 00 |
| AU | .34610615 01 | .31844926 01 | .22685311 01 | .55924926-03 | .13441655-03 | -.19567239-03 | .00000000 00 | .25000000 02 |

U PRODUCT MATRIX OF STEP MAPPING ITERATION NUMBER 0

| | X | Y | Z | DX | DY | DZ | HV | AU |
|----|---------------|---------------|--------------|---------------|---------------|---------------|--------------|--------------|
| X | .56437986 01 | .42107851 01 | .21757652 01 | .27753481-03 | .95502073-04 | -.10171062-03 | .00000000 00 | .00000000 00 |
| Y | .42107851 01 | .48017091 00 | .36603342 00 | .32273659-04 | .12672889-04 | -.14935375-04 | .00000000 00 | .00000000 00 |
| Z | .21757652 01 | .36603342 00 | .19477862 00 | .15886207-04 | .21757187-05 | .23402609-05 | .00000000 00 | .00000000 00 |
| DX | .27753481-03 | .32273659-04 | .15886207-04 | .15886207-04 | .34895230 03 | -.34874327 03 | .00000000 00 | .00000000 00 |
| DY | .95502073-04 | .12672889-04 | .15886207-04 | .34895230 03 | .27889194 02 | -.16720472 03 | .00000000 00 | .00000000 00 |
| DZ | -.10171062-03 | -.14935375-04 | .23402609-05 | -.34874327 03 | -.34874327 03 | .00000000 00 | .00000000 00 | .00000000 00 |
| HV | .00000000 00 | .00000000 00 | .00000000 00 | .00000000 00 | .00000000 00 | .00000000 00 | .00000000 00 | .00000000 00 |
| AU | .00000000 00 | .00000000 00 | .00000000 00 | .00000000 00 | .00000000 00 | .00000000 00 | .00000000 00 | .10000000 01 |

ENCOUNTER PARAMETERS AND STATISTICS 62/12/14 194658.745

| | | | |
|-------|---------------|--------|--------------|
| B | .48R63381 05 | SHAA | .13827722 06 |
| B.NO | .25623516 05 | SHIA | .46249093 05 |
| B.TO | -.41606075 05 | DEL T | .31379607 05 |
| B.RC | .28412022 05 | DEL B | .14581931 06 |
| B.TC | -.39752716 05 | DEL S | .17077879 06 |
| TL | .10077253 03 | DEL DR | .92950071 05 |
| THETA | .37570843 02 | DEL SF | .11317444 06 |

N MATRIX

| | B-RO | B-TO | TL | C3 | S-TS | S-RS |
|------|---------------|---------------|---------------|---------------|---------------|---------------|
| B-RO | .84548154 10 | -.82051087 10 | .26191344 10 | -.59891937 05 | .22538312 06 | -.11646524 06 |
| B-TO | -.82051090 10 | .12808455 11 | -.30171756 10 | -.64743844 05 | -.28456252 06 | -.14590043 06 |
| TL | .26191345 10 | -.30171755 10 | .98467973 09 | -.20929726 05 | .80506390 05 | .41782426 05 |
| C3 | -.59891386 05 | .64743775 05 | -.20929769 05 | .45701790 00 | -.17441461 01 | -.90371404 00 |
| S-TS | .22538311 06 | -.28456251 06 | .80506391 05 | -.17441487 01 | .70437215 01 | .36340358 01 |
| S-RS | .11646524 06 | -.14590043 06 | -.41782426 05 | -.90371227 00 | .36340358 01 | .18758385 01 |

NONNORMALIZED N MATRIX

| | B-RO | B-TO | TL | C3 | S-TS | S-RS |
|------|---------------|---------------|---------------|---------------|---------------|---------------|
| B-RO | .10000000 01 | -.78846768 00 | .90773319 00 | -.96349549 00 | .92356662 00 | -.92479722 00 |
| B-TO | -.78846771 00 | .99999999 00 | -.84958083 00 | .84622042 00 | -.94738878 00 | -.94126186 00 |
| TL | .90777323 00 | -.84958081 00 | .10000000 01 | -.98661894 00 | .96657782 00 | .97218390 00 |
| C3 | -.96348663 00 | .84621952 00 | -.98662093 00 | .10000000 01 | -.97219049 00 | -.97603794 00 |
| S-TS | .92356665 00 | -.94738875 00 | .96657784 00 | -.97211093 00 | .10000000 01 | .99974760 00 |
| S-RS | .92479726 00 | -.94126187 00 | .97218390 00 | -.97603603 00 | .99974765 00 | .99999999 00 |

JPL TECHNICAL MEMORANDUM NO. 33-204

DM/DOO MATRIX

| | B.RD | B.TD | TL | C3 | S.TS | S.RS |
|----|---------------|---------------|---------------|---------------|---------------|---------------|
| X | .19432538 01 | -.30687803 01 | .71810839 00 | -.15502912-04 | .67870250-04 | -.34794829-04 |
| Y | .12661832 00 | -.37872949 00 | -.99066247-01 | -.15491778-05 | .79940872-05 | -.41622495-05 |
| Z | .34317390 00 | -.17255082 00 | -.66687256-02 | .86614341-06 | .37648641-05 | -.17358850-05 |
| DX | .64180771 07 | -.11189817 08 | -.23966677 07 | -.51176269 02 | .23588366 03 | -.12053721 03 |
| DY | .65818714 07 | -.15729188 07 | .16748565 07 | -.41920920 02 | -.11365567 03 | .60119785 02 |
| DZ | -.18816308 06 | -.63123703 05 | .11391386 07 | -.15014267 02 | -.43341703 02 | -.24794701 02 |
| HU | -.56560495-01 | -.96096551-01 | -.26623533-01 | .14224868-03 | .50777522-06 | -.40448822-06 |

DM/DOO MATRIX

| | B.RD | B.TD | TL | C3 | S.TS | S.RS |
|----|---------------|---------------|---------------|---------------|---------------|---------------|
| X | -.21496986 00 | -.71465895 00 | .55341266-01 | .33640446-03 | -.10118067-04 | -.62313123-05 |
| Y | .60157931 00 | .64188397 00 | .14796535 00 | -.11025433-03 | .20058079-05 | -.12722463-05 |
| Z | -.91472661 00 | -.98744307-01 | .97671857-01 | -.23437026-03 | -.56003876-05 | -.51622475-06 |
| DX | -.11462816 04 | -.42096133 04 | -.67860414 03 | -.71121789 01 | -.20354437-01 | -.12535791-01 |
| DY | .42021899 04 | -.25239673 04 | .46801974 03 | -.10264800 02 | -.17521200-01 | -.10790601-01 |
| DZ | -.82683492 04 | -.68900916 03 | .67421384 03 | -.53769287 01 | -.57946112-01 | -.42589667-01 |
| HU | -.33843363-01 | -.14002395 00 | -.17583676-02 | .91201498-04 | .18249393-05 | -.11239068-05 |

N MATRIX FOR MANEUVER CALCULATIONS

| | B.RC | B.TC | TL |
|------|---------------|---------------|---------------|
| B.RC | .95964167 10 | -.84255963 10 | -.32634384 05 |
| B.TC | -.84255966 10 | .11666853 11 | -.32763030 05 |
| TL | .32634384 05 | -.32763030 05 | .13190690 00 |

0000 141631 OFFLINE CONTROL
 0000 14163 TERMINATE JOB
 0000 14163 END DATA

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SOURCE PROGRAM LISTING

```

*H1  QDPX  Y9
*H9  L49  X,N11,N1,N4
55164/1.0E14
*H12 L412 X
*H13  SPACE X
* SCDFRF=2
* WANT  N9,(MDDPH1),Z0D,(INDTOR,BRDPT),18
* WANT  N11,(TAPEX),6
* WANT  N12,(XNJ,INJ),1,(XNJ-1,INJ),1
* ETC  (XNJ-2,INJ),1,(XNJ-3,INJ),1
* ETC  (XNJ-4,INJ),1,(XNJ-5,INJ),1
* ETC  (EPDCH,INJT),1,(EPDCH-1,INJT),1
* ETC  (DUP,GRAY-2),1,(DUP,SCALE1),1
* ETC  (RE,SCALE),1,(PORE,HARMN4),1
* ETC  (QU,HARMN+4),1,(QU,HARMN+3),1
* ETC  (QJ,HARMN+2),1,(GRAVE,GRAY),1
* ETC  (GRAVN,GRAY+1),1,(GRAVS,GRAY+2),1
* ETC  (GRAVV,GRAY+3),1,(GRAV4,GRAY+4),1
* ETC  (CHAVJ,GRAY+6),1,(STEP,H1),1
* ETC  (TANGFT,FARBCO),1,(AREA,RADDP),1
* ETC  (GM0,RADDP),1,(FMAS,RADDP),1
* ETC  (FAD,GASDP),1,(FBD,GASDP),1
* ETC  (FC0,GASDP),1,(FA1,GASDP),1
* ETC  (FB1,GASDP),1,(FC1,GASDP),1
* ETC  (FA2,GASDP),1,(FB2,GASDP),1
* ETC  (FC2,GASDP),1,(JETON,GASDP),1
* ETC  (JETON,GASDP),1,(JETON-1,GASDP),1
* ETC  (JETOFF,GASDP),1,(JETOFF-1,GASDP),1
* ETC  (IF14,SECP50),1,(IF1N-1,SECP50),1
* ETC  (FMAS,GASDP),1
GASDP=(CANOPU)
INJCO=(EARTH)
*H11 L411  Y4,N6,N12
* WANT  Y9,(IC137),1
* WANT  N13,(CLPT,TRAQE),1,(CLPT+1,TRAQE),1
* ETC  (CLPBT,TRAQE),1,(CLPBT,TRAQE),1
* ETC  (CLPBT,TRAQE),1,(CLPBT,TRAQE),1
* ETC  (TAPEX),6
*H2  L42  N12,X
* WANT  N11,(EPOX),14
*H2A L42A  Y9,N12
*H3  L43  Y9,N10
*H4  L44  Y6,N12
*H5  L45  Y9,N12
*H6  L46  N12
*H7  L47  Y9,N10,N12
* WANT  Y9,(APR1DR-19,APR1DR-19),20
*H8  L48  Y9,N12
*H10 L410  Y8,Y9
*H  END
    
```

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THERE WERE NO CLARIFY SOURCE DECK ERRORS.
 THE OBJECT STRING HAS 00514 OCTAL OR 332 DECIMAL WORDS.

JPL TECHNICAL MEMORANDUM NO. 33-204

0000 141751 PAGE HEADING (23
 0000 14175 (MOON CHECK CASE - PREDICTIONS)
 0000 14175 EPDCH (101
 0000 14175 640702910,2758000
 0000 14175 GEOCENTRIC POSITION AND VELOCITY AT EPDCH (102
 0000 14175 X=.156674536E Y=.63041615E Z=.80777204E
 0000 14175 DX=.14342616E DY=.97256996E DZ=.28116199E
 0000 14175 OTHER OPTIONS AND CONSTANTS (103
 0000 14175 SYNFRQ=2038516.
 0000 14175 TFREQ=7590330.
 0000 14175 POINTING TIMES, SAMPLE RATE, COUNT TIMES (117
 0000 14175 JEIDL2=640702911,0,640703011,0,1800.,60.
 0000 14175 TRANSMITTER ID TABLE (126
 0000 14175 2,2038516
 0000 14175 OFFLINE CONTROL (127
 0000 14175 KEY(8) KEY(13)
 0000 14175 END DATA (0

CASE 1 IBSYS-JPTRAJ-SPACE 022265 1

DOUBLE PRECISION EPHEMERIS TAPE - EPHEM1

GME .39860063 06 J .16234500-02 H -.57499999-05 D .78749999-05 RE .63781650 04 REM .63783112 04
 G .66709998-19 A .88781796 29 B .88800194 29 C .88836976 29 DME .41780741-02 AU .14959850 09
 GMM .49026293 04 GMS .13271411 12 GMY .32476627 05 GMA .42977368 05 GMC .37918700 08 GHJ .12670935 09
 EGM .39860320 06 MGH .49027779 04 JA .29200000-02 HA .00000000 00 DA .00000000 00 RA .34170000 04

INJECTION CONDITIONS MOON 235666506353202400000000 J.D.= 2438605.93608796 JULY 29,1964 10 27 58.000

GEOCENTRIC X0 .15667453 06 Y0 .63041615 05 Z0 .80777203 04 DX0 .14342616 01 DY0 .97256996 00 DZ0 .28116199 00
 CARTESIAN ID .37678000 05 GHA .10409373 03 GHD .30667227 03
 DATE OF RUN 022265A 14185 EARTH IS THE CENTRAL BODY FOR INTEGRATION COMELL EQUATIONS OF MOTION

0 DAYS 0 HRS. 0 MIN. 0.000 SEC. 235666506353202400000000 J.D.= 2438605.93608796 JULY 29,1964 10 27 58.000

GEOCENTRIC EQUATORIAL COORDINATES
 X .15667452 06 Y .63041612 05 Z .80777202 04 DX .14342615 01 DY .97256992 00 DZ .28116198 00
 R .16907513 06 DEC .27384004 01 RA .21918529 02 V .17555749 01 PTH .76231923 02 AZ .61412202 02
 B .16907512 06 LAT .27384004 01 LON .27782479 03 VE .12070910 02 PTE .81207508 01 AZE .27095862 03
 XS .89949372 08 YS .11227336 09 ZS .48886598 08 DXS -.23515989 02 DYS -.16077681 02 DZS -.69719988 01
 XM .38246410 06 YM .27456507 05 ZM -.26012551 05 DXM -.83439888-01 DYM .93230192 00 DZM .40985490 00
 XT .38246410 06 YT .27456507 05 ZT -.26012551 05 DXT -.83439888-01 DYT .93230192 00 DZT .40985490 00
 RS .15187686 09 VS .29327501 02 RM .38432968 06 VM .10218268 01 RT .38432968 06 VT .10218268 01
 GED .27570333 01 ALT .16626784 06 LOS .24408715 02 RAS .12870045 03 RAM .41061295 01 LDM .26001239 03
 DUT .35000000 02 DT .12000000 03 DR .17051340 01 SHA .16335718 06 DES .18697172 02 DEH -.38809109 01
 CCL .25840724 03 MCL .11052996 00 TCL .11052996 00

GEOCENTRIC CONIC

EPOCH OF PERICENTER PASSAGE 23566644500622026213000000 J.D.= 2438605.21642518 JULY 28,1964 17 11 39.136
 SHA .24408791 02 ECC .97401695 00 B .55279828 05 SLR .12519505 05 APD .48183367 06 RCA .63421468 04
 VH .14661061 00 C3 -.16330208 01 CI .70641933 05 TFP .62178864 05 TF -.17271907 02 PER .20002258 05
 TA .16192549 03 NTA .18000000 03 EA .71607988 02 MA .18651553 02 C3J -.20370820 01 TFI .00000000 00

ALL VECTORS REFERENCED TO EARTH EQUATOR PLANE
 X .15667452 06 Y .63041612 05 Z .80777202 04 DX .14342615 01 DY .97256992 00 DZ .28116198 00
 INC .28976671 02 LAN .17015325 02 APF .20329595 03 MX .45905374 00 MY .75220646 00 MZ .47271026 00
 MX .14176438 00 NY .66327417 00 WZ .87481701 00 PX .77702823 00 PY .55959958 00 PZ .19151913 00
 QX .61926389 00 QY .65062065 00 QZ .43955031 00 RX .15255788 00 RY .11936638 00 RZ .98147647 00
 BX .61926389 00 BY .65062065 00 BZ .43955031 00 TX .61622264 00 TY .79169463 00 TZ .00000000 00
 DAP -.11169176 02 RAP .21765584 03
 BTQ .49421011 05 BRQ -.24767379 05 B .55279828 05 THA .33338222 03 T VECTOR IN EARTH EQUATOR PLANE

CASE 1 IBSYS-JPTRAJ-SPACE 022265 2

HELIOCENTRIC EQUATORIAL COORDINATES

X .90106046 08 Y -.11221032 09 Z -.48678520 08 DX .24950250 02 DY .17050251 02 DZ .72531608 01
 R .15192055 09 LAT .18688381 02 LON .30876483 03 V .31077876 02 PTH .21988085 00 AZ .75813410 02
 XE .89949372 08 YE -.11227336 09 ZE -.48686598 08 DXE .23515989 02 DYE .16077681 02 DZE .69719988 01
 XT .90331836 08 YT .11224590 09 ZT -.48712610 08 DXT .23432549 02 DYT .17009983 02 DZT .73818538 01
 LTE .18697172 02 LDE .30870045 03 LTT .18690121 02 LDT .30882598 03 LST .15209175 09 YST .29881694 02
 EPS .74994993 02 ESP .61373100-01 SEP .10494339 03 SEH .14723381 03 EMP .13773981 02 MEP .18992403 02
 MPS .13777126 03 MSP .59933450-01 SMP .42170224 02 SEM .12399574 03 EMS .95944139 02 ESM .12012787 00
 RPM .23110470 06 SPV .72833120 02
 GCE .10159276 03 GCT .28170329 03 SIP .13734034 03 CPT .92025110 02 SIN .91594195 02
 REP .16907513 06 VEP .17555769 01 CPE .97484351 02 CPS .76877815 02

1 DAYS 0 HRS. 32 MIN. 2.000 SEC. 235666561454202000000000 J.D.= 2438606.95833333 JULY 30,1964 11 00 00.000

GEOCENTRIC EQUATORIAL COORDINATES
 X .25084050 06 Y .13402614 06 Z .30322890 05 DX .81614400 00 DY .67379618 00 DZ .22454298 00
 R .28601301 06 DEC .60858957 01 RA .28115954 02 V .10819020 01 PTH .77274393 02 AZ .61615284 02
 B .28601300 06 LAT .60858957 01 LON .27500634 03 VE .20556600 02 PTE .29427204 01 AZE .27031620 03
 XS .92013117 08 YS .11083678 09 ZS .48063650 08 DXS -.23214413 02 DYS -.16451548 02 DZS .71338363 01
 XM .36449540 06 YM .10819357 06 ZM .10548403 05 DXM -.32284243 00 DYM .88717703 00 DZM .41420339 01
 XT .36449540 06 YT .10819357 06 ZT .10548403 05 DXT -.32284243 00 DYT .88717703 00 DZT .41420339 01
 RS .15189594 09 VS .29333497 02 RM .38036037 06 VM .10309582 01 RT .38036037 06 VT .10309582 01
 GED .61270553 01 ALT .27963504 06 LOS .16588743 02 RAS .12969836 03 RAM .16532524 02 LDM .26342290 03
 DUT .35000000 02 DT .48000000 03 DR .10953263 01 SHA .28251917 06 DES .18451435 02 DEM .15891664 01
 CCL .25920166 03 MCL .11192516 01 TCL .11192516 01

GEOCENTRIC CONIC

EPOCH OF PERICENTER PASSAGE 23566645033320254440000000 J.D.= 2438605.22424520 JULY 28,1964 17 22 54.785
 SHA .24685405 06 ECC .97407359 00 B .53607772 05 SLR .11658495 05 APD .48718128 06 RCA .58981653 04
 VH .13991439 08 C3 .16161874 01 C1 .68163673 05 TFP .14982521 06 TF -.17084226 02 PER .20304432 05
 TA .16934513 03 NTA .18000000 03 EA .99441039 02 MA .44273647 02 C3J -.20471674 01 TFI .24533889 02

ALL VECTORS REFERENCED TO EARTH EQUATOR PLANE
 X .25084050 06 Y .13402614 06 Z .30322890 05 DX .81614400 00 DY .67379618 00 DZ .22454298 00
 INC .28976671 02 LAN .17015325 02 APF .20329595 03 MX .45905374 00 MY .75220646 00 MZ .47271026 00
 MX .14176438 00 NY .66327417 00 WZ .87481701 00 PX .77702823 00 PY .55959958 00 PZ .19151913 00
 QX .61926389 00 QY .65259664 00 QZ .44449580 00 RX .15168230 00 RY .11704677 00 RZ .98147647 00
 BX .61329438 00 BY .65259664 00 BZ .44449580 00 TX .61091702 00 TY .79169463 00 TZ .00000000 00
 DAP -.11045703 02 RAP .21765584 03
 BTQ .47782174 05 BRQ -.24303436 05 B .53607772 05 THA .33304076 03 T VECTOR IN EARTH EQUATOR PLANE

JPL TECHNICAL MEMORANDUM NO. 33-204

CASE 1

18SYS-JPTRAJ-SPACE 022265

3

HELIOCENTRIC EQUATORIAL COORDINATES

| | | | | | | | | | | | |
|-----|---------------|-----|---------------|-----|---------------|-----|--------------|-----|---------------|-----|--------------|
| X | .92263957 08 | Y | -.11070276 09 | Z | -.48033337 08 | DX | .24030557 02 | DY | .17125344 02 | DZ | .73583793 01 |
| R | .15190437 09 | LAT | -.18433738 02 | LDN | .30980913 03 | V | .30412018 02 | PTH | -.39832041 00 | AZ | .75367093 02 |
| XE | .92013117 08 | YE | -.11083678 09 | ZE | -.48063660 08 | DXE | .23214413 02 | DYE | .16451548 02 | DZE | .71338363 01 |
| XI | .92377612 08 | YI | -.11072859 09 | ZI | -.48053111 08 | DXI | .22891571 02 | DYI | .17335725 02 | DZI | .75480396 01 |
| LIE | -.18451435 02 | LOE | .30969936 03 | LIT | -.18429768 02 | LOT | .30983725 03 | RST | .15199850 09 | VST | .29692226 02 |
| EPS | .80928671 02 | ESP | .10653118 00 | SEP | .98964764 02 | EPH | .13630553 03 | EMP | .31295930 02 | MEP | .12399535 02 |
| MPS | .14275634 03 | MSP | .25217635-01 | SMP | .37216690 02 | SEM | .11136139 03 | EMS | .68505077 02 | ESH | .13343921 00 |
| RPM | .11821424 06 | SPN | .79650888 02 | | | | | | | | |
| GCE | .10079833 03 | GCT | .28191758 03 | SIP | .14191393 03 | CPT | .93302061 02 | SIN | .92459653 02 | | |
| REP | .28601301 06 | VEP | .10819020 01 | CPE | .98321564 02 | CPS | .76978757 02 | | | | |

I DAYS 0 HRS. 36 MIN. 7.000 SEC. 235666561550202000000000 J.D.= 2438606.96111111 JULY 30,1964 11 04 00.000

GEOCENTRIC EQUATORIAL COORDINATES

| | | | | | | | | | | | |
|-----|---------------|-----|---------------|-----|---------------|-----|---------------|-----|---------------|-----|---------------|
| X | .25103626 06 | Y | .13418778 06 | Z | .30376764 05 | DX | -.81519112 00 | DY | -.67322571 00 | DZ | .22440404 00 |
| R | .28626616 06 | DEC | .60913377 01 | RA | .28126092 02 | V | .10807990 01 | PTH | .77275751 02 | AZ | .61614519 02 |
| R | .28626615 06 | LAI | .60913377 01 | LDN | .27401373 03 | VE | .20574902 02 | PIE | .29371153 01 | AZE | .27031557 03 |
| XS | -.92018688 08 | YS | -.11083283 09 | ZS | -.48061947 08 | DXS | -.23213584 02 | DYS | -.16452559 02 | DZS | -.71342736 01 |
| XM | .36441784 06 | YM | -.10840647 06 | ZM | .10647809 05 | DXM | -.32348484 00 | DYM | .88698269 00 | DZM | -.41418345 00 |
| XI | .36441784 06 | YI | -.10840647 06 | ZI | .10647809 05 | DXI | -.32348484 00 | DYI | .88698269 00 | DZI | -.41418345 00 |
| RS | .15189590 09 | VS | .29333513 02 | RM | .38034944 06 | VM | .10309843 01 | RT | .38034944 06 | VT | .10309843 01 |
| GEU | .61325336 01 | ALT | -.27988819 06 | LOS | .15588715 02 | RAS | .12970107 03 | RAM | .16566608 02 | LOM | .26245425 03 |
| DUT | .35000000 02 | DT | .48000000 03 | DR | .10542562 01 | SHA | .28277598 06 | UES | .18450759 02 | DEH | .16041929 01 |
| CCL | -.25902071 03 | HCL | -.11199342 01 | TCL | .11199342 01 | | | | | | |

GEOCENTRIC COMIC

EPDM OF PERICENTER PASSAGE 235666450335202006000000 J.D.= 2438605.22430609 JULY 28,1964 17 23 00.047

| | | | | | | | | | | | |
|-----|---------------|-----|---------------|----|---------------|-----|--------------|-----|---------------|-----|---------------|
| SMA | .24655219 06 | ECC | .97608645 00 | B | .53596202 05 | SLR | .11650884 05 | APD | .48720843 06 | RCA | .58959386 04 |
| VA | .13987292 00 | C3 | -.16166988 01 | C1 | .68147266 05 | IFP | .15005995 06 | IF | -.17082765 02 | PER | .20305931 05 |
| TH | -.16935879 03 | HTA | .18000000 03 | EA | -.99498608 02 | MA | .44339739 02 | C3J | -.20471971 01 | TFI | -.24600555 02 |

ALL VECTORS REFERENCED TO EARTH EQUATOR PLANE

| | | | | | | | | | | | |
|-----|---------------|-----|---------------|-----|---------------|----|---------------|----|---------------|----|---------------|
| X | .25103626 06 | Y | .13418778 06 | Z | .30376764 05 | DX | -.81519112 00 | DY | -.67322571 00 | DZ | .22440404 00 |
| INC | .28978429 02 | LAM | .17016156 02 | APP | .20329300 03 | HX | -.45922455 00 | MY | .75209822 00 | MZ | .47271731 00 |
| HX | .14177917 00 | HY | -.46327196 00 | HZ | .87480215 00 | PX | -.77705276 00 | PY | -.59957162 00 | PZ | -.19154992 00 |
| QX | .61325999 00 | QY | -.65260538 00 | QZ | -.44449313 00 | KX | .15161722 00 | RY | .11703170 00 | RZ | -.98147700 00 |
| BX | -.61325984 00 | BY | .65260523 00 | BZ | .44449303 00 | TX | -.61088707 00 | FY | .79171775 00 | FZ | -.00000000 00 |
| OAP | -.11045001 02 | RAP | .21765367 03 | | | | | | | | |

BTQ .47770919 05 BRQ -.24300045 05 B .53596202 05 THA .33303853 03 T VECTOR IN EARTH EQUATOR PLANE

CASE 1

18SYS-JPTRAJ-SPACE 022265

HELIOCENTRIC EQUATORIAL COORDINATES

| | | | | | | | | | | | |
|-----|---------------|-----|---------------|-----|---------------|-----|---------------|-----|---------------|-----|---------------|
| X | -.92269724 08 | Y | -.11069865 09 | Z | -.48031570 08 | DX | -.24028775 02 | DY | .17125784 02 | DZ | -.73586777 01 |
| R | .15190432 09 | LAT | -.18433041 02 | LDN | .30981194 03 | V | .30410929 02 | PTH | -.39840322 00 | AZ | .75359724 02 |
| XE | .92018688 08 | YE | -.11083283 09 | ZE | -.48061947 08 | DXE | -.23213584 02 | DYE | .16452559 02 | DZE | .71342736 01 |
| XI | .92383105 08 | YI | -.11072443 09 | ZI | -.48051299 08 | DXI | -.22890099 02 | DYI | .17339541 02 | DZI | .75480471 01 |
| LIE | -.18450759 02 | LOE | .30970107 03 | LIT | -.18429081 02 | LOT | .30983999 03 | RST | .15199824 09 | VST | .29691674 02 |
| EPS | .80937248 02 | ESP | .10653118 00 | SEP | .98956090 02 | EPH | .13628907 03 | EMP | .31338244 02 | MEP | .12372679 02 |
| MPS | .14276421 03 | MSP | .25217635-01 | SMP | .37208808 02 | SEM | .11132686 03 | EMS | .68539587 02 | ESH | .13343921 00 |
| RPM | .11793766 06 | SPN | .79660594 02 | | | | | | | | |
| GCE | .10079728 03 | GCT | .28191721 03 | SIP | .14191979 03 | CPT | .93304393 02 | SIN | .92459974 02 | | |
| REP | .28626616 06 | VEP | .10807990 01 | CPE | .98322790 02 | CPS | .76979031 02 | | | | |

222462325467 220750470430 215753222173 201560037436 200757472061 177435677052 EARTH INITIAL
 21187169515 17515413504 000000000000

222753160271 222404413161 217725145467 200642503745 200527270151 176711206656 EARTH END
 235666561550 202000000000

JPL TECHNICAL MEMORANDUM NO. 33-204

| STATION NUMBER | 2 | 64/07/29 | PAGE | 1 | | | | | | |
|----------------|--------------|--------------|--------|---------|-------|---------|------------|------------|------------|---------------|
| TIME | R | DR | EL | AZ | DEC | HA | CI | CC3 | E3 | RU |
| 110000 | -16755796 06 | -15050596 01 | 47.636 | 136.455 | 1.705 | 332.326 | 1010789.13 | 1023069.11 | 1023069.11 | 0011442252115 |
| 113000 | -17028671 06 | -15274765 01 | 51.590 | 146.347 | 1.846 | 339.850 | 1010960.92 | 1023412.66 | 1023412.66 | 0011562336493 |
| 120000 | -17305866 06 | -15529082 01 | 54.596 | 157.866 | 1.982 | 347.384 | 1011155.81 | 1023802.44 | 1023802.44 | 0011703362333 |
| 123000 | -17587845 06 | -15804852 01 | 56.389 | 170.809 | 2.113 | 354.924 | 1011367.16 | 1024225.10 | 1024225.10 | 0012025722205 |
| 130000 | -17874913 06 | -16093108 01 | 56.767 | 184.497 | 2.238 | 2.466 | 1011588.06 | 1024666.91 | 1024666.91 | 0012151453753 |
| 133000 | -18167214 06 | -16384802 01 | 55.686 | 197.936 | 2.358 | 10.006 | 1011811.61 | 1025114.00 | 1025114.00 | 0012277225010 |
| 140000 | -18464729 06 | -16670989 01 | 53.281 | 210.238 | 2.473 | 17.540 | 1012030.93 | 1025552.64 | 1025552.64 | 0012426212373 |
| 143000 | -18767281 06 | -16943014 01 | 49.800 | 220.972 | 2.584 | 25.066 | 1012239.39 | 1025969.58 | 1025969.58 | 0012556551683 |
| 150000 | -19074539 06 | -17192679 01 | 45.509 | 230.131 | 2.690 | 37.500 | 1012430.72 | 1026352.23 | 1026352.23 | 0012718031953 |
| 153000 | -19386432 06 | -17442398 01 | 40.635 | 231.930 | 2.791 | 40.079 | 1012599.08 | 1026688.97 | 1026688.97 | 001304347341 |
| 160000 | -19701158 06 | -17595327 01 | 35.353 | 244.648 | 2.890 | 47.561 | 1012739.23 | 1026969.29 | 1026969.29 | 0013177575033 |
| 163000 | -20019198 06 | -17735484 01 | 29.790 | 250.542 | 2.985 | 55.024 | 1012846.56 | 1027183.99 | 1027183.99 | 0013334562733 |
| 170000 | -20339335 06 | -17827840 01 | 24.042 | 255.803 | 3.078 | 62.466 | 1012917.20 | 1027325.29 | 1027325.29 | 0013472242663 |
| 173000 | -20660669 06 | -17868442 01 | 18.179 | 260.665 | 3.171 | 69.884 | 1012948.01 | 1027366.99 | 1027366.99 | 0013620205051 |
| 180000 | -20982235 06 | -17854687 01 | 12.248 | 265.250 | 3.261 | 77.281 | 1012936.64 | 1027366.27 | 1027366.27 | 0013766213343 |
| 183000 | -21303024 06 | -17787053 01 | 6.368 | 269.642 | 3.392 | 84.596 | 1012881.63 | 1027254.27 | 1027254.27 | 0014124035111 |
| 190000 | -21622002 06 | -17707772 01 | 1.803 | 273.967 | 3.697 | 91.643 | 1012782.75 | 1027056.52 | 1027056.52 | 0014261237573 |

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| | | | | | | | | | | |
|--------|--------------|--|--------|---------|-------|---------|------------|------------|------------|---------------|
| 070000 | -27016468 06 | -74415302 00 | 1.327 | 84.522 | 5.232 | 267.906 | 1004988.50 | 1011468.10 | 1011468.10 | 0017333233605 |
| 073000 | -27150337 06 | -73977632 00 | 7.101 | 88.762 | 5.109 | 275.090 | 1004928.05 | 1011347.15 | 1011347.15 | 0017401444427 |
| 080000 | -27283360 06 | -73864767 00 | 13.138 | 93.055 | 5.125 | 282.487 | 1004916.70 | 1011324.41 | 1011324.41 | 0017450353411 |
| 083000 | -27416693 06 | -74363618 00 | 19.237 | 97.503 | 5.181 | 289.962 | 1004954.21 | 1011399.38 | 1011399.38 | 0017517341717 |
| 090000 | -27551468 06 | -75475478 00 | 25.283 | 102.228 | 5.234 | 297.453 | 1005039.15 | 1011569.20 | 1011569.20 | 0017566657355 |
| 093000 | -27688712 06 | -77173927 00 | 31.236 | 107.315 | 5.289 | 304.984 | 1005169.18 | 1011829.23 | 1011829.23 | 0017636767217 |
| 100000 | -27829430 06 | -79419018 00 | 37.030 | 113.131 | 5.344 | 312.493 | 1005341.17 | 1012173.16 | 1012173.16 | 0017710123733 |
| 103000 | -27974982 06 | -82159878 00 | 42.574 | 119.735 | 5.398 | 320.037 | 1005551.19 | 1012593.16 | 1012593.16 | 0017762520555 |
| 110000 | -28125670 06 | -85336002 00 | 47.745 | 127.498 | 5.450 | 327.594 | 1005794.57 | 1013079.91 | 1013079.91 | 0020036554023 |
| 0000 | 142044 | OFFLINE TIMES | | | | | | | | (17 |
| 0000 | 14204 | JETOLV640702911,0,640703011,0,1800,60. | | | | | | | | (16 |
| 0000 | 14204 | TRANSMITTER IO TABLE | | | | | | | | (12 |
| 0000 | 14204 | 1,2038516. | | | | | | | | (12 |
| 0000 | 14204 | OFFLINE CONTROL | | | | | | | | (12 |
| 0000 | 14204 | KEY113) | | | | | | | | (10 |
| 0000 | 14204 | END DATA | | | | | | | | (10 |

STATION NUMBER 1 64/07/29 PAGE 1

| TIME | R | DR | EL | AZ | DEC | HA | CI | CC3 | E3 | RU |
|--------|--------------|--------------|--------|---------|-------|---------|------------|------------|------------|---------------|
| 110000 | -16754786 06 | -19550839 01 | 47.774 | 136.409 | 1.709 | 332.381 | 1010789.32 | 1023069.48 | 1023069.48 | 0011442227211 |
| 113000 | -17027675 06 | -15274002 01 | 51.738 | 146.322 | 1.851 | 339.905 | 1010961.87 | 1023414.55 | 1023414.55 | 0011562111373 |
| 120000 | -17304902 06 | -15531298 01 | 54.750 | 157.878 | 1.986 | 347.439 | 1011157.52 | 1023805.83 | 1023805.83 | 0011703142053 |
| 123000 | -17586929 06 | -15808013 01 | 56.542 | 170.873 | 2.117 | 354.980 | 1011369.58 | 1024229.95 | 1024229.95 | 0012025511115 |
| 130000 | -17874062 06 | -16097161 01 | 56.911 | 184.619 | 2.242 | 2.522 | 1011591.17 | 1024673.13 | 1024673.13 | 0012151454445 |
| 133000 | -18166443 06 | -16389676 01 | 55.813 | 198.099 | 2.362 | 10.062 | 1011815.34 | 1025121.47 | 1025121.47 | 0012277041477 |
| 140000 | -18464053 06 | -16676600 01 | 53.386 | 210.424 | 2.477 | 17.597 | 1012035.23 | 1025541.24 | 1025541.24 | 0012426104517 |
| 143000 | -18766711 06 | -16949262 01 | 49.891 | 221.162 | 2.587 | 25.123 | 1012244.18 | 1025979.16 | 1025979.16 | 0012556434433 |
| 150000 | -19074087 06 | -17199454 01 | 45.568 | 230.310 | 2.693 | 32.637 | 1012435.91 | 1026362.62 | 1026362.62 | 0012710325753 |
| 153000 | -19385706 06 | -17419581 01 | 40.674 | 238.093 | 2.795 | 40.136 | 1012604.59 | 1026699.98 | 1026699.98 | 0013043412513 |
| 160000 | -19700963 06 | -17602795 01 | 35.374 | 244.791 | 2.893 | 47.614 | 1012744.95 | 1026980.73 | 1026980.73 | 0013177537753 |
| 163000 | -20019140 06 | -17743108 01 | 29.796 | 250.665 | 2.988 | 55.082 | 1012852.61 | 1027195.68 | 1027195.68 | 0013334552117 |
| 170000 | -20339415 06 | -17835493 01 | 24.034 | 255.933 | 3.081 | 62.524 | 1012923.06 | 1027337.02 | 1027337.02 | 0013472255633 |
| 173000 | -20660885 06 | -17875998 01 | 18.158 | 260.770 | 3.174 | 69.941 | 1012953.80 | 1027398.52 | 1027398.52 | 0013630246113 |
| 180000 | -20982585 06 | -17862029 01 | 12.216 | 265.317 | 3.264 | 77.338 | 1012942.27 | 1027375.51 | 1027375.51 | 0013766277777 |
| 183000 | -21303504 06 | -17794119 01 | 6.325 | 269.694 | 3.396 | 84.652 | 1012886.99 | 1027264.98 | 1027264.98 | 0014124144711 |
| 190000 | -21622604 06 | -17716328 01 | 1.759 | 274.003 | 3.705 | 91.691 | 1012787.76 | 1027066.60 | 1027066.60 | 0014261371161 |

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| | | | | | | | | | | |
|--------|--------------|-----------------|--------|---------|-------|---------|------------|------------|------------|---------------|
| 070000 | -27016126 06 | -74354145 00 | 1.353 | 84.548 | 5.231 | 267.956 | 1004983.37 | 1011457.84 | 1011457.84 | 0017332252673 |
| 073000 | -27149878 06 | -73919059 00 | 7.141 | 88.773 | 5.111 | 275.141 | 1004923.27 | 1011337.59 | 1011337.59 | 0017401327261 |
| 080000 | -27282795 06 | -73808231 00 | 13.190 | 93.050 | 5.128 | 282.540 | 1004912.85 | 1011315.72 | 1011315.72 | 0017450227355 |
| 083000 | -27416031 06 | -74313785 00 | 19.300 | 97.484 | 5.184 | 290.015 | 1004950.39 | 1011391.74 | 1011391.74 | 0017517176705 |
| 090000 | -27550723 06 | -75433312 00 | 25.358 | 102.194 | 5.237 | 297.506 | 1005035.91 | 1011562.73 | 1011562.73 | 0017566500153 |
| 093000 | -27687959 06 | -77140234 00 | 31.322 | 107.328 | 5.292 | 305.017 | 1005166.59 | 1011824.06 | 1011824.06 | 0017636576133 |
| 100000 | -27829764 06 | -79394454 00 | 37.128 | 113.072 | 5.347 | 312.547 | 1005339.29 | 1012169.40 | 1012169.40 | 0017707272225 |
| 103000 | -27974081 06 | -82144929 00 | 42.686 | 119.669 | 5.400 | 320.091 | 1005550.04 | 1012590.87 | 1012590.87 | 0017762231171 |
| 110000 | -28124751 06 | -85330990 00 | 47.870 | 127.430 | 5.453 | 327.648 | 1005794.19 | 1013079.13 | 1013079.13 | 0020036342363 |
| 0000 | 14211 | OFFLINE CONTROL | | | | | | | | (12 |
| 0000 | 14211 | TERMINATE JOB | | | | | | | | (10 |
| 0000 | 14211 | END DATA | | | | | | | | (10 |

IX. REFERENCES

1. Warner, M. R., Nead, M. W., Hudson, R. H., The Orbit Determination Program of the Jet Propulsion Laboratory. Technical Memorandum No. 33-168, Jet Propulsion Laboratory, Pasadena, March 18, 1964.
2. Holdridge, D. B. Space Trajectories Program for the IBM 7094 Computer. Technical Report No. 32-223, Jet Propulsion Laboratory, Pasadena, September 1, 1962.
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