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**LASS-II, COMPUTER PROGRAM FOR ANALYSIS  
OF SEISMIC RESPONSE AND LIQUEFACTION OF  
HORIZONTALLY LAYERED SANDS**

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LASS-II, COMPUTER PROGRAM FOR  
ANALYSIS OF SEISMIC RESPONSE AND LIQUEFACTION  
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1. INTRODUCTION

The problem of liquefaction of saturated soils during earthquakes has attracted considerable attention in recent years and extensive research has already been performed in; understanding the phenomenon; the process of development of liquefaction during earthquakes; and, factors affecting this process. It is not intended here to give a complete literature survey in the area of liquefaction. However, few references cited here (2, 8, 10, 11, 12, 14, 15) represent some of many significant developments and various approaches to the problem. An excellent survey of the state of the art has been presented in a recent paper by Seed (16).

Presented here is a new approach to analysis of seismic response and evaluation of the liquefaction potential of saturated sands. A two phase fluid-solid model has been previously developed for quasi-static and dynamic analysis of saturated soils (3, 4, 5, 6). This work has been extended here by using a nonlinear material model to represent the behavior of solid granular medium.

The separate phases of solid granular skeleton and the pore water are modeled individually and the coupling between these two phases is taken into account. The pore water is allowed to flow with respect to granular solid and this process is assumed to be governed by Darcy flow law with the coefficient of permeability as the material constant. Dynamic analysis of this model allows direct determination of the time histories of pore water pressures and effective stresses. The seismic response of the system to earthquake base acceleration is also determined in the process of dynamic analysis.

The material model used in this study is defined in terms of effective stresses. Criteria for the occurrence of initial liquefaction and onset of liquefaction is defined in terms of effective stresses and are included in the material model. Initial liquefaction is considered as a condition of "near failure". Two different material models are used for the behavior of soil before and after the initial liquefaction. Cyclic effects are included in the material model.

All the material parameters needed for the material model used in this study can be determined from routine laboratory tests and possibly undrained triaxial test under monotonically increasing stress. Cyclic tests are not required for this model. Another feature of the method of analysis presented here is that the damping is not included as an independent parameter. The model inherently includes two effective damping mechanisms; hysteretic damping and dissipative damping. Thus the need for evaluation of damping ratio is eliminated.

## 2. METHOD OF ANALYSIS

The saturated granular soil system is treated as a two-phase medium with constituent materials being the granular solid skeleton and pore water. The two phases are coupled through volumetric strains. The method is general and has been applied to two dimensional cases in previous studies (3, 5). However, in the previous applications the linearly elastic material properties were used for modeling the behavior of the solid skeleton. With this type of material model the pore water pressures result only from elastic volumetric strains which neglect the reduction in effective pressures and increase in pore water pressure which is caused by dilatancy and contractancy of granular soils under shear deformations. An appropriate nonlinear material property has been used in this study which is capable of adequately representing the volumetric deformation under shear strains.

The horizontally layered system of saturated soils is assumed to consist of horizontal layers with specified thicknesses and material properties. Each layer is subdivided into a number of "layer elements" which consist of the medium contained between two horizontal planes a distance  $h$  apart. The plane separating two adjacent elements is referred to as "nodal plane". The motion of the system is described by nodal displacement degrees of freedom. In a general case each node has four displacement degrees of freedom; three components of displacement of solid portion,  $u_x$ ,  $u_y$ ,  $u_z$ , and a vertical displacement of pore water with respect to solid,  $w_z$ . A schematic representation of a layered system and a typical layer element are shown in Figures (1) and (2).

The nodal planes remain horizontal during the motion of the systems and they can only undergo parallel displacements. Torsional motion of the

system is neglected. As a result of these assumptions there are only three non-zero strain components. The strain-displacement relations are:

$$\begin{aligned}\epsilon_{zz} &= u_{z,z} \\ \epsilon_{xz} &= u_{x,z} \\ \epsilon_{yz} &= u_{y,z}\end{aligned}\quad (1)$$

and the volumetric strain of pore water is given by the following relation:

$$\zeta = w_{z,z} \quad (2)$$

For a typical layer element shown in Figure 2 the components of displacement are assumed to vary linearly between the nodal planes i and j. With this assumption on variation of displacements for each element the stiffness matrix, mass matrix, and "dissipation resistance" matrix can be computed. The matrices for the system result from direct assembly of the element matrices.

The matrix equation of motion for the system can be written as follows.

$$\begin{pmatrix} M_s & 0 \\ 0 & M_f \end{pmatrix} \begin{Bmatrix} \ddot{u} \\ \ddot{w} \end{Bmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & H \end{pmatrix} \begin{Bmatrix} \dot{u} \\ \dot{w} \end{Bmatrix} + \begin{pmatrix} K_{ss} & K_{sf} \\ K_{sf}^T & K_{ff} \end{pmatrix} \begin{Bmatrix} u \\ w \end{Bmatrix} = \begin{Bmatrix} M_s I \\ 0 \end{Bmatrix} \ddot{u}_g \quad (3)$$

The terms of equation 3 are as follows.

$u$  = vector of the displacements of the solid portion

$w$  = vector of the displacements of the pore water with respect to solid

$M_s$  = lumped mass matrix for the bulk of saturated soil

$M_f$  = lumped mass matrix for the fluid portion

$H$  = dissipation resistance matrix. The terms of this matrix are inversely proportional to the coefficient of permeability



$K_{ss}$  = stiffness matrix for the bulk of saturated soil

$K_{ff}$  = stiffness matrix for the fluid portion

$K_{sf}$  = stiffness matrix representing the coupling between solid and fluid portions.

$u_g^{\infty}$  = time history of base acceleration.

Equation 3 is a nonlinear system of equations. The source of nonlinearity is through the sub matrix  $K_{ss}$  which contains the nonlinear material behavior of the solid granular skeleton. This nonlinear matrix equation can be written symbolically as follows.

$$M \ddot{u}(t) + D \dot{u}(t) + K u(t) = ML \ddot{u}_g(t) \quad (4)$$

in which  $L$  is a vector containing ones and zeros at the appropriate locations.

Since it is only possible to develop a tangent stiffness matrix, the third term on the left hand side of Equation 4 has to be written in incremental form as follows

$$K u(t) = K_t \Delta u(t) + R(t - \Delta t) \quad (5)$$

in which

$$\Delta u(t) = u(t) - u(t - \Delta t) \quad (6)$$

and the vector  $R(t - \Delta t)$  is the vector of internal

resisting forces which is computed from the stresses computed at the end of the previous time step, as follows.

$$R(t - \Delta t) = \sum_v \int_v B^T(t - \Delta t) dv \quad (7)$$

The matrix  $B$  is the strain - displacement matrix and the integration is carried out over each element with the summation sign denoting direct assembly process.

Substitution of Equation (5) into Equation (4) yield the following incremental form of the equation of motion.

$$M \ddot{u}(t) + D \dot{u}(t) + K_t \Delta u(t) = ML \ddot{u}_g(t) - R(t - \Delta t) \quad (8)$$

This nonlinear matrix equation of motion is directly integrated in time by a time marching scheme, as described in reference (6).

Two types of energy absorption mechanism or equivalent damping effects are present in the analytical model used here. A hysteretic damping is introduced into the system by using the material model which will be discussed in the next section. The magnitude of energy absorbed with this damping mechanism is dependent on the history of shear strains which develop within each element. Another energy absorption mechanism is provided through the dissipation resistance matrix which represents dissipation of pore water pressure and flow of pore water through granular solid. It is difficult to evaluate these damping effects in terms of other conventional damping mechanisms used in dynamic analysis such as proportional and modal damping. However, the influence of the damping mechanisms used in this study can be shown through their effects on the response of the system. By studying such responses, as will be shown later, it appears that these two damping mechanisms adequately represent the energy absorption in the system.

### 3. MATERIAL MODEL

Two distinct material behavior models are required to cover the whole range possible during the stress history of an element of soil from insitu stress condition to final liquefaction. The first material model is to represent the soil behavior from insitu stress condition up to the initial liquefaction. After the onset of initial liquefaction the material behavior is quite different than the pre-initial liquefaction. A second material model is required to represent this behavior.

The initial liquefaction here is considered to be a condition of near failure in the soil element. After the initial liquefaction the granular structure of sand changes due to large strains developing in the near failure condition. The material model for the post initial liquefaction range is in effect the representation of the post failure behavior of sand in a cyclic stress environment.

The material model developed here and used in the computer program LASS - II is based on the observations of the soil behavior and the test results reported in literature (1,7,9,13,17).

#### 3.1 PRE-INITIAL - LIQUEFACTION MODEL

The shear stress-strain relation under monotonic loading is represented by following equation and shown in Fig. (3a).

$$\left(\frac{q}{p'}\right) = \frac{\gamma G_0 S_{\max}}{\gamma G_0 + S_{\max}} \quad (9)$$

in which  $q$  is the shear stress,  $p'$  is the effective pressure and  $\gamma$  is the shear strain. This relation is assumed to apply equally to shear stress in positive or negative direction. The unloading is assumed to take place

linearly with the slope  $G_0$  until previous maximum or minimum value of  $q/p'$  is reached, whereupon the above stress-strain relation in Equation 9 becomes valid again. The stress-strain relation in shear as represented by the above equation is assumed to remain constant up to the onset of initial liquefaction. This is a reasonable assumption as no significant changes occur in the void ratio of saturated sands during the earthquake prior to liquefaction. In the  $p'$ - $q$  plane the shear yield loci (lines of equal shear strain) take the form of straight lines radiating from the origin, Fig. (3b). Within the low effective stress range encountered in earthquake analysis of soil deposits this appears to be a reasonable assumption. The existence of such yield loci for shear deformations has been experimentally verified and reported in References (7; 13). However, it has been shown that for higher values of effective pressure the yield loci approach a state parallel to  $p'$ -axis.

Under monotonic shear stress increase with this model the failure will occur as the stress point in  $p'$ - $q$  plane approaches a line corresponding to the asymptote of the shear stress-strain relation in Equation 9. This failure line which is also referred to as "critical state" line is given by the following equation

$$f_1 = q - p' \tan \phi = 0 \quad (10)$$

Initial liquefaction occurs as the stress point approaches the failure line but before reaching this line. Therefore, it is justified to assume that  $\tan \phi$  takes a value slightly smaller than  $S_{max}$ .

The initial effective pressures at each depth prior to application of shear stresses are denoted by  $p'_0$ . With the application of monotonically increasing shear stresses in undrained conditions, the stress point in  $p'$ - $q$  plane follows a path similar to the stress path shown in Fig. (3b) which intersects the failure line at effective pressure  $p'_f$ . This stress path has

been approximated by a quarter of an ellipse which is given by the following equation.

$$f_2 = (p' - p'_f)^2 + \frac{1}{\lambda^2} q^2 - (p'_0 - p'_f)^2 = 0 \quad (11)$$

The material parameter  $\lambda$  is the ratio of the major and minor axes of the ellipse, as given by the following relation.

$$\lambda = \frac{p'_f}{p'_0 - p'_f} \tan \phi \quad (12)$$

The stress path given in Equation 11 is completely defined by two material parameters  $\lambda$  and  $\phi$  and the insitu effective pressure  $p'_0$ . Equation 11 can be written in terms of these parameters as follows.

$$f_2 = q^2 + \lambda^2 \left[ p'^2 - \left( \frac{2\lambda}{\lambda + \tan \phi} \right) p' p'_0 + \left( \frac{\lambda - \tan \phi}{\lambda + \tan \phi} \right) p'^2_0 \right] = 0 \quad (13)$$

As can be seen from Fig. (3b) under monotonic increase in shear stress the effective pressure  $p'$  decreases and as a result the pore water pressure increases in undrained condition. In unloading the effective pressure is assumed to remain constant until the stress path reaches the previous maximum or minimum value of  $q/p'$  in  $p' - q$  plane. After the stress point has reached the previous maximum or minimum value of  $q/p'$ , it continues along a stress path given by Equation 13 but computed with a new value of  $p'_0$  which is determined such that the stress path goes through the point just reached by the stress path. This process in effect corresponds to successive reduction in the value of initial effective pressure  $p'_0$  as a result of cyclic shear stress. When unloading occurs, the value of  $q/p'$  just prior to unloading becomes the current value of the so called previous maximum or minimum value of  $q/p'$ .

The original concept of the "state boundary surface" has been extended by Ishihara and his co-workers (7,17,18) by introducing the concept of the "multiplicity of state boundary surface" which helps in explaining a number of aspects of the behavior of sands under cyclic shear stress. As a result of this concept it is postulated that the loading stress paths on each side of the  $p'$ -axis are independent of the other side. In a cyclic stress situation therefore, at each instant two current values of  $p'_0$  exist associated with stress paths for positive and negative values of  $q$ .

It is important to relate the model material parameters to relative density which is recognized to be an important factor in determining the liquefaction potential of saturated sands.

The values of  $\lambda$  determined from various reported experimental results are shown in Fig. (4) versus the relative density. The data appears to fall within a narrow band for low and medium densities. The value of  $\lambda$  increases with relative density and the value of  $\lambda = 1$  occurs at about 35% relative density. This corresponds to a circular stress path  $f_2 = 0$ . Below 35% relative density the major axis of  $f_2$  falls along  $p'$ -axis and above this relative density the major axis of  $f_2$  is parallel to  $q$ -axis. From the data in Figure (4), which are for fairly uniform sands with rounded particles, it appears that  $\lambda$  is only dependent on relative density and the effective pressure has little effect on the value of  $\lambda$ . Data from tests at various effective pressures,  $p'_0 = 1.0, 4.0$  and  $10.0 \text{ kg/cm}^2$  do not differ appreciably. As a result of this observation it can be concluded that, for fairly uniform sands with rounded particles, the shape of the stress path  $f_2$  remains constant and only its size changes with  $p'_0$ , since  $\lambda$  is independent of  $p'_0$ . However, Castro also has reported the results of experiments on two types of sands

with angular and subangular particles. The values of  $\lambda$  determined from these results are shown in Figure (5) and it is evident that the effective pressure  $p'_0$  has a great deal of influence on  $\lambda$ . Therefore, for these types of sands the shape of the stress path  $f_2$  must also be dependent on the effective pressure. However, at the present there is not sufficient data to justify quantification of this phenomenon and it is not included in computer program LASS-II.

### 3.2 POST INITIAL LIQUEFACTION BEHAVIOR

After the stress path has reached a level very close to failure line or monotonic strain has reached a certain level, it is said that the soil element is at initial liquefaction. When using a strain criteria for initial liquefaction it is important to distinguish between the actual strain in cyclic environment and its monotonic strain equivalent. The later must be used. After initial liquefaction the material behavior of the soil element changes abruptly. Although this material behavior change is gradual in cyclic tests, especially for dense sands, under monotonic loading for low relative densities very abrupt material behavior changes have been observed. In any case, for the purpose of material modeling, this material behavior change must be considered an abrupt and discrete phenomenon.

There appears to be very little experimental data to provide insight as to the mechanism of post initial liquefaction behavior of saturated sands. Limited experimental data does point to certain general material behavior characteristics for this range. However, development of accurate material postulates based on acceptable material mechanism must await further experimental evidence. Ishihara, et al. (8) have used a specific stress path for post initial liquefaction behavior which appears justified based

on limited experimental data. This specified stress path is sufficient for the type of application reported in Ref. (8). However, a general material model needed for a systematic dynamic stress analysis requires information as to the deformational characteristics of sand at post initial liquefaction range. Sufficient experimental data for development of such a material model does not exist at the present.

All sands do not lose their strength after the initial liquefaction. It appears that only at very loose states and low densities complete liquefaction almost instantaneously follows the initial liquefaction; the effective stress point in  $p'$ - $q$  plane instantaneously follows the failure line down to origin. At higher values of relative densities, additional stress cycles are required to further reduce the effective pressure and achieve complete liquefaction. It appears reasonable to assume that shear loading and unloading characteristic does not change appreciably after initial liquefaction. From cyclic tests it seems that the pore pressures and effective pressures start oscillating after initial liquefaction, which is due to the fact that the stress point must move up along failure line upon loading which reduces pore pressure and upon unloading the pore pressure increases. The magnitude of pore pressure increase in each cycle of loading will depend on relative density of sand and the highest magnitude of the shear stress in that cycle. It seems the higher shear stresses after initial liquefaction cause an interlocking of particles resulting in higher effective pressure which upon unloading is transferred to pore pressures. A possible mechanism for explaining this phenomenon is a change in compressibility of solid skeleton.



## 4. POST EARTHQUAKE ANALYSIS

After the completion of the earthquake analysis excess pore water pressures are computed throughout the layered system. This excess pore water pressure dissipates with time after the termination of the earthquake strong shaking. In the process, the excess pore pressure distribution through the depth changes which may cause some unliquefied portions to liquify. Some significant ground settlements may result after the dissipation of the excess pore water pressure.

The differential equation governing the dissipation of excess pore pressure is as follows.

$$k \frac{\partial^2 \pi}{\partial z^2} = c_v \frac{\partial \pi}{\partial t} \quad (14)$$

in which  $\pi$  is the excess pore pressure,  $k$  is the coefficient of permeability and  $c_v$  is the coefficient of compressibility. The discrete form of the dissipation equation for the same mesh as used during the earthquake analysis is as follows.

$$[A] \{\pi\} + [B] \{\dot{\pi}\} = 0 \quad (15)$$

in which  $\{\pi\}$  is the vector of excess pore pressures and the matrices  $[A]$  and  $[B]$  are obtained from direct assembly of element matrices  $[A_m]$  and  $[B_m]$ , respectively. For the one-dimensional elements used here, it is assumed that the excess pore pressure varies linearly between the nodal values of excess pore pressure. The element matrices are as follows.

$$[A_m] = \frac{k}{L} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} \quad (16)$$

$$[B_m] = \frac{C_v L}{6} \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} \quad (17)$$

The matrix equation of dissipation, Equation 15, is integrated in time using Crank-Nicolson (mid-difference) scheme which reduces Equation 15 to the following form.

$$[D] \{\pi_n\} = [E] \{\pi_{n-1}\} \quad (18)$$

in which  $\{\pi_n\}$  is the vector of excess pore pressures at time  $n\Delta t$  and  $\Delta t$  is the integration time step. The matrices D and E are computed from the matrices A and B as follows.

$$[D] = \frac{1}{\Delta t} [B] + \frac{1}{2} [A] \quad (19)$$

$$[E] = \frac{1}{\Delta t} [B] - \frac{1}{2} [A] \quad (20)$$

Equation 18 is applied successively to compute the time history of the excess pore pressures. The starting vector (initial conditions) contains the value of excess pore pressures computed at the termination of the earthquake analysis.

Due to the logarithmic nature of variation of excess pore pressure with time, usually a smaller time step is used at the beginning of the analysis and later the value of the time step is increased. The time integration method used is unconditionally stable and therefore there is no restriction on the size of the time step for stability considerations.

## 5. EFFECTIVE DAMPING

Two types of energy absorbing mechanisms which act as effective damping are available in the method of analysis presented in this report. These damping mechanisms are as follows.

1. Hysteretic damping which is inherent in the material model used in this study.
2. Dissipative damping which is the result of modeling the two phase nature of the soil and is caused by flow of pore water with respect to the granular solid.

The first damping mechanism is independent of the velocity whereas the second is a velocity dependent damping mechanism.

The magnitude of the effect of these two damping mechanisms are determined automatically in the process of analyses by the behavior of the system. This eliminates the need for determining the damping ratio which is one, the most critical, at the same time difficult, steps in a dynamic analysis. The hysteretic damping at each point in the system is dependent on the effective pressure and the level of cyclic shear stresses. This can be seen from shear stress-strain diagrams shown in Fig. 11.

In order to study the influence of these damping mechanisms the following three cases were analyzed.

- Case 1. The soil is modeled as one phase solid with linearly elastic material property. No damping is present in this case.
- Case 2. The soil is modeled as one phase solid. But in this case nonlinear material properties are used. This case has only the hysteretic damping.

Case 3. The soil is modeled as two phase medium and nonlinear material properties are used. In this case both damping mechanisms are present.

For all the cases 100 ft layer was assumed and all the properties, except those which were mentioned above, were the same. The El Centro earthquake record was used as the base motion. The response spectra at ground surface for these three cases are shown in Fig. 6. The effect of the two damping mechanisms is quite clear from this figure. In Case 1, in absence of any damping, very high peak spectral velocities are present at the natural frequencies of the system. Hysteretic type damping has considerably reduced the surface response spectrum of case 2. The differences between surface response spectra of cases 2 and 3 is solely due to dissipative types damping which appears to be considerable. Furthermore, the hysteretic damping appears to be almost uniformly effective over the whole frequency range whereas the dissipative damping has little effect in the low frequency range but is very effective in the high frequency range.

The observations made in this section appear to confirm the authors belief that close modeling of the behavior and physical make up of soil to a great degree eliminates the need for specifying the damping as an additional material property.

## 6. CASE STUDIES

In this section the results of the application of the method of analysis described in previous sections to two cases are presented and discussed. The first case studied is a 100 ft layer of sand with water table at 2 ft below ground surface. This layer is subjected to N-S component of El Centro earthquake of May 1940 as horizontal base acceleration. The material properties used in this analysis are shown in Fig. 7. It is assumed that the initial shear modulus increases with depth. Other parameters are constant through the depth.

Shown in Fig. 8 are the time histories of excess pore pressures and effective stresses normalized with respect to in situ effective stresses. It can be seen that major pore pressure increases occur within the first 2.5 seconds of the earthquake. Initial liquefaction occurs when the excess pore pressures have reached a value of about 60 % of the in situ effective pressure. After the initial liquefaction the material properties change to a post failure condition causing the excess pore pressures to oscillate according to shear stresses. The oscillations in the excess pore pressure continue until final liquefaction has occurred, whereupon the pore pressures remain constant with time. The first element liquefies at 2.7 seconds. The liquefaction of other elements follow and the liquefied zone increases with time. The pattern of development of liquefaction with time is shown in Fig. 9. It can be seen that the last element has liquefied at 6.0 seconds. The zone of liquefaction extends from the water table to a depth of 20 feet below ground surface and the zone of liquefaction does not expand after 6 seconds. The variation of excess pore pressure with depth is shown in Fig. 10 at various times. It can be seen that

before liquefaction the excess pore pressure, as a percentage of in situ effective pressure, has the highest value near the ground surface. The time rate of increase of this pore pressure ratio is also much higher near the ground surface and it rapidly decreases with depth. Below a depth of 60 feet the excess pore pressures vary between 20 to 35 per cent of the in situ effective pressures.

Shown in Fig. 11 are typical shear stress-strain plots at several depths. It is evident from this figure that the increase in effective pressure with depth has a great deal of influence on the maximum shear stresses, equivalent shear moduli and the hysteretic damping.

The dynamic analysis due to earthquake base motion was carried out for 30 seconds. The excess pore pressure ratios at the end of 30 seconds of earthquake are shown in Fig. 12. Also shown in this figure are the pore pressure ratios at different elapsed times after the earthquake. The dissipation of excess pore pressure after the earthquake are obtained by post-earthquake analysis.

The second case studied here is a soil profile similar to Niigata sites where extensive liquefaction occurred during the June 16, 1964 earthquake. No attempt is made here to directly model the Niigata site. The properties used in this analysis, as shown in Fig. 13, are chosen to coincide with those used by Seed and Idriss in Ref. (14). The initial shear modulus is assumed to increase linearly with depth. The relative densities and the corresponding values for  $\lambda$  are also shown in Fig. 13. The depth of the layer used in the analysis is 250 feet. Below 100 feet the rate of increase of shear moduli with depth was gradually reduced and a constant relative density of 0.9 was used.

Two base motions were used in the analysis; the El Centro earthquake record with half the amplitude; and, a sine wave with an amplitude of 0.15 g and a period of 0.5 seconds. The pattern of the development of liquefaction for these two cases are shown in Figures 14 and 16 and the variation of excess pore pressures with depth are shown in Figures 15 and 17. It can be seen that the pattern of the development of liquefaction for both the base motions is very similar and the main differences are in the fact that for sine wave base motion liquefaction occurs earlier and also a larger zone liquefies. However, in both cases liquefaction starts in the second layer which is assigned the lowest relative density of 40 percent.

The sine wave base motion is probably the most severe condition from liquefaction point of view, since the soil is subjected to sustained levels of cyclic shear stress, whereas, when earthquake record is used as the base motion, only a few cycles of high shear stresses occur. It is reasonable to conclude that the peak acceleration and earthquake duration play a more important role in the liquefaction potential than other properties of any earthquake.

In summary, it is observed that for base accelerations used, with peak values typical of Niigata earthquake and regardless of earthquake type, the method shows that liquefaction does occur in the upper 30 feet of the soil profile used in this analysis.

## 7. CONCLUDING REMARKS

Presented in this report is a general method for analysis of seismic response and liquefaction of horizontally layered saturated soils. The saturated soil below water table is modeled as a coupled two phase medium with solid granular skeleton and pore water as the constituent materials. Above the water table soil is modeled as a one phase solid. A nonlinear material model was used in the analysis which includes yielding, failure, volume change characteristics, cyclic effects and criteria for initial and final liquefaction.

Under cyclic shear stress the effective pressure decreases and as a result the resistance and the shear strength of sand decreases, allowing larger shear strains to develop. If this process continues under sustained shear stress, the sand will approach a condition of "near failure". This condition here is considered as initial liquefaction. Following initial liquefaction sand is in a state of post-failure and the behavior is quite different than the behavior of sand prior to initial liquefaction. A post-initial liquefaction model is developed for this range up to the final liquefaction.

This method of seismic analysis is applied in some case studies. The results appear to be reasonable and in agreement with field observations.



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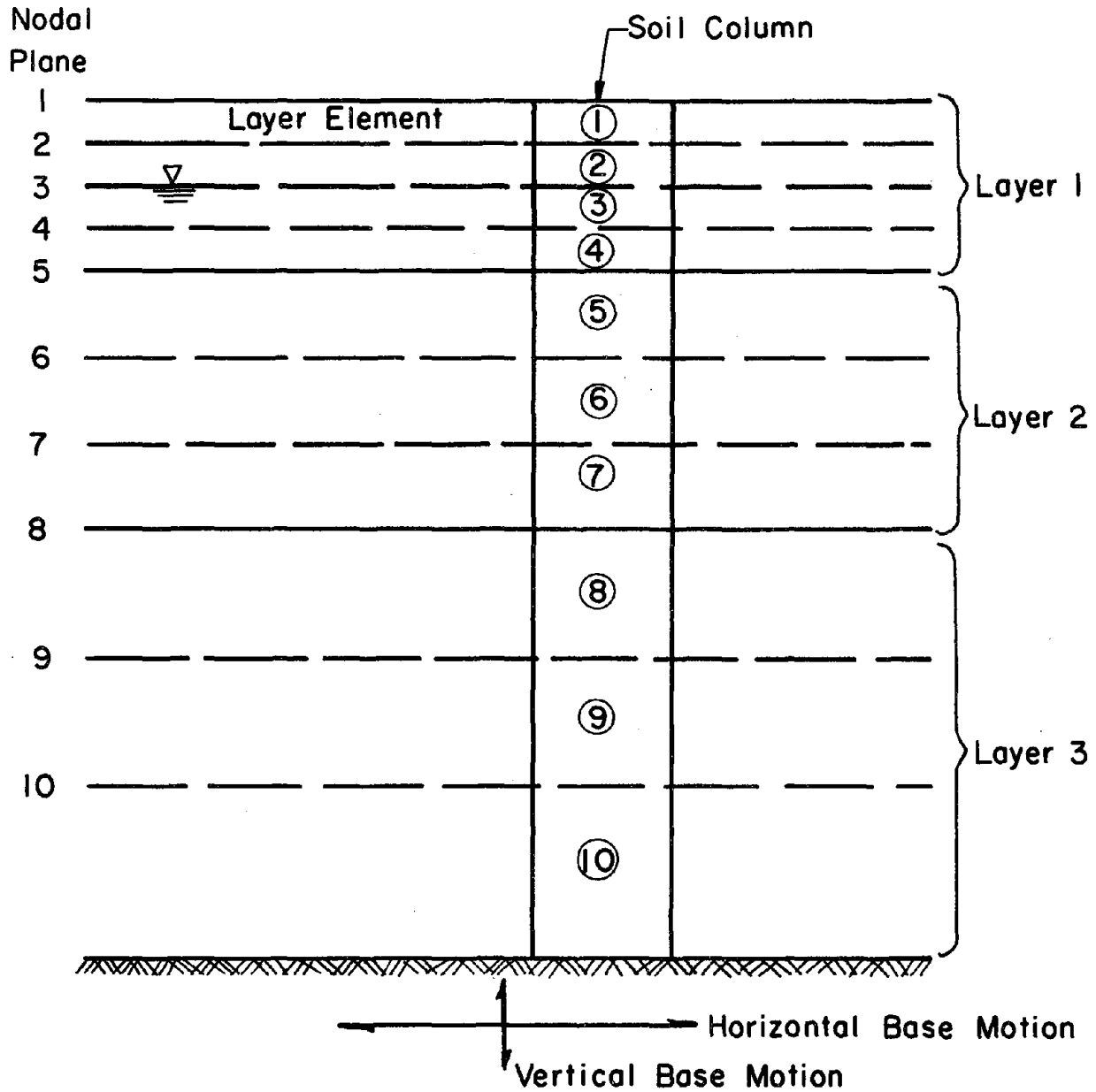


FIG. 1.—Schematic Representation of Layered System

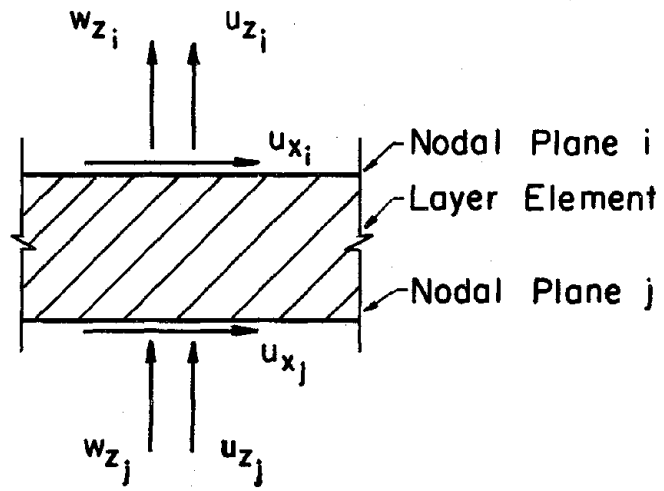
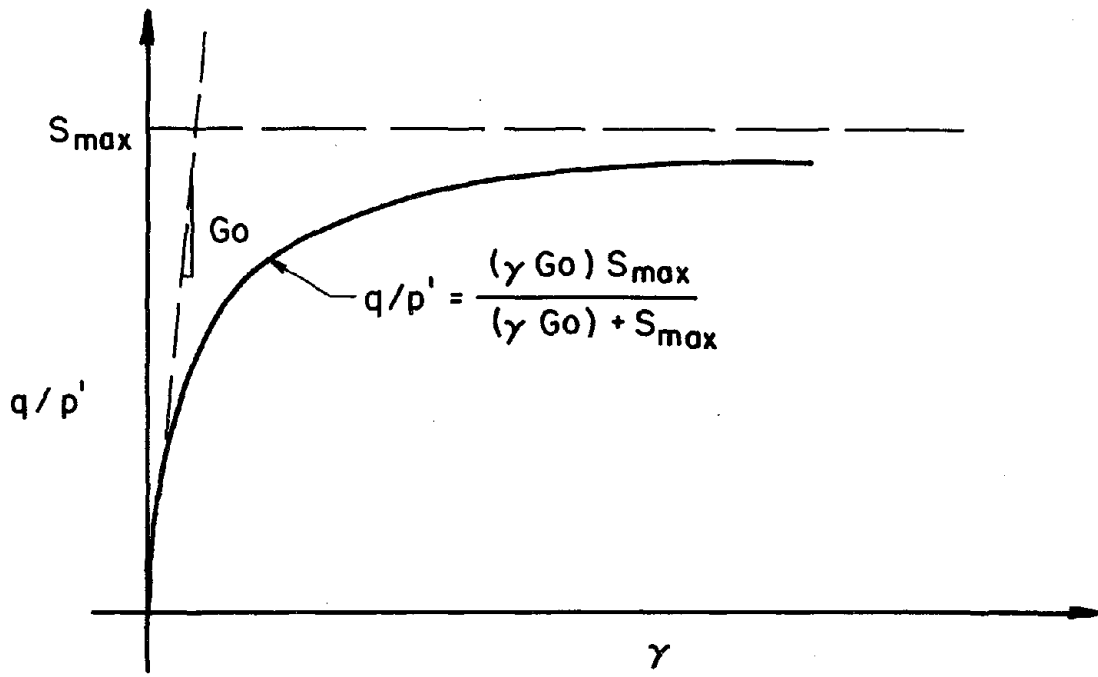
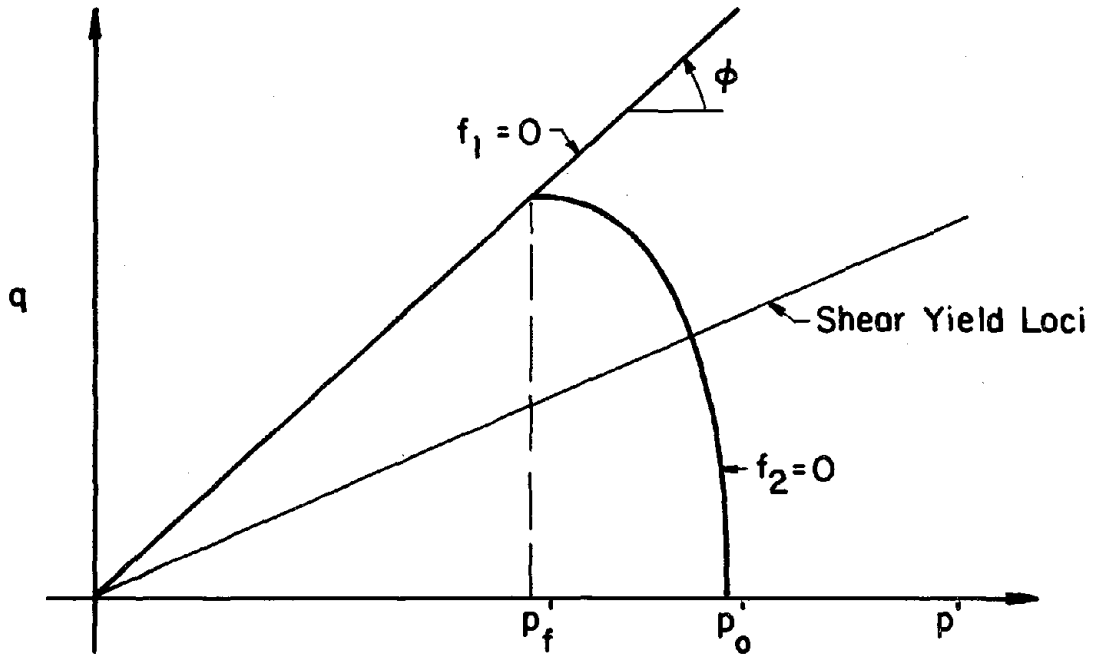


FIG. 2.—Layer Element



(a)



(b)

FIG. 3.—Material Model

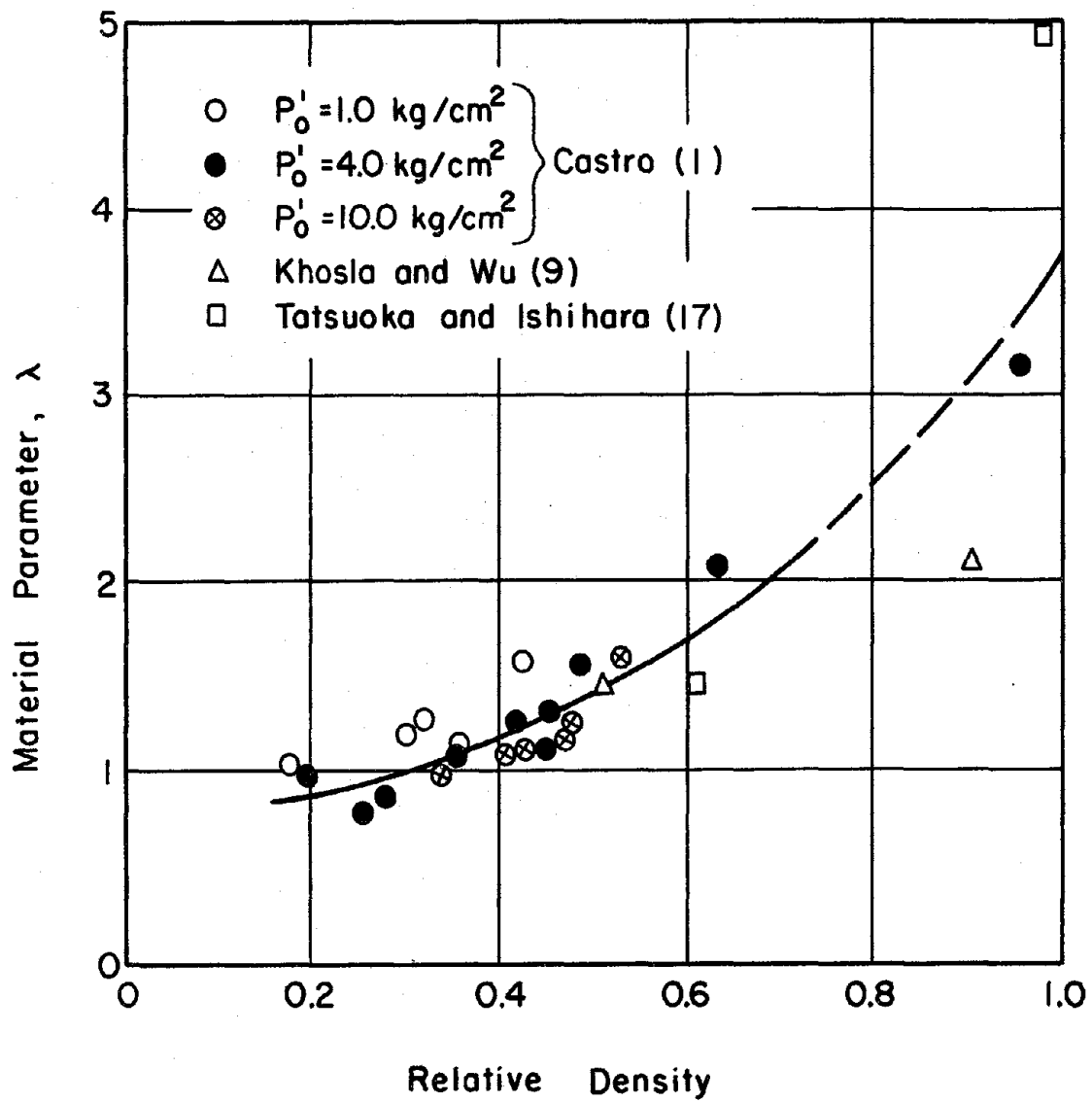


FIG. 4.—Relationship Between Material Parameter  $\lambda$  and Relative Density

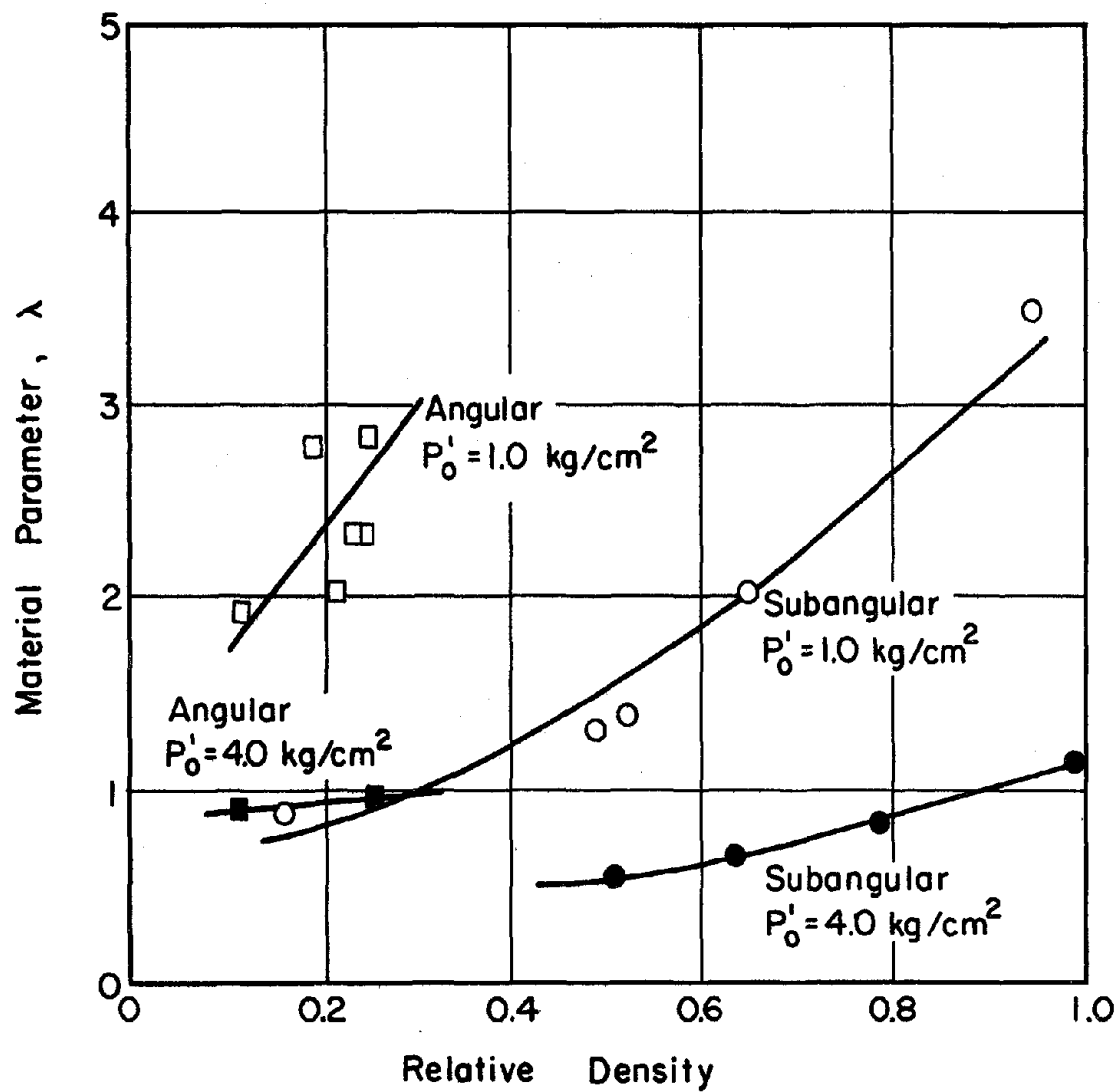
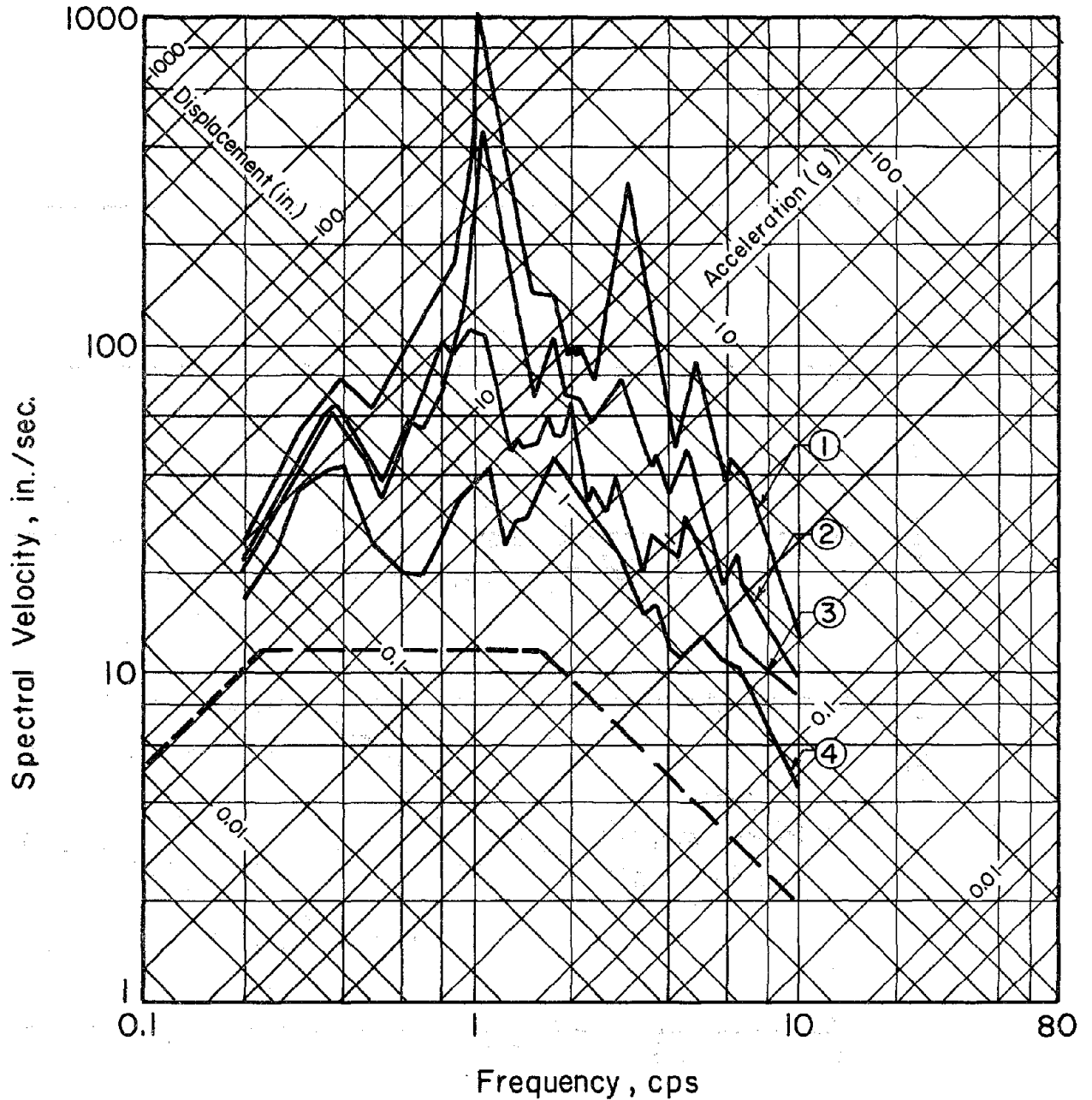


FIG. 5.—Influence of Grain Shape on Material Parameter  $\lambda$



- ① One Phase Solid, Linear
- ② One Phase Solid, Non-Linear
- ③ Two Phase, Non-Linear (Water Table at 5 ft.)
- ④ El Centro

Fig. 6.—Ground Surface Response Spectra for Different Models



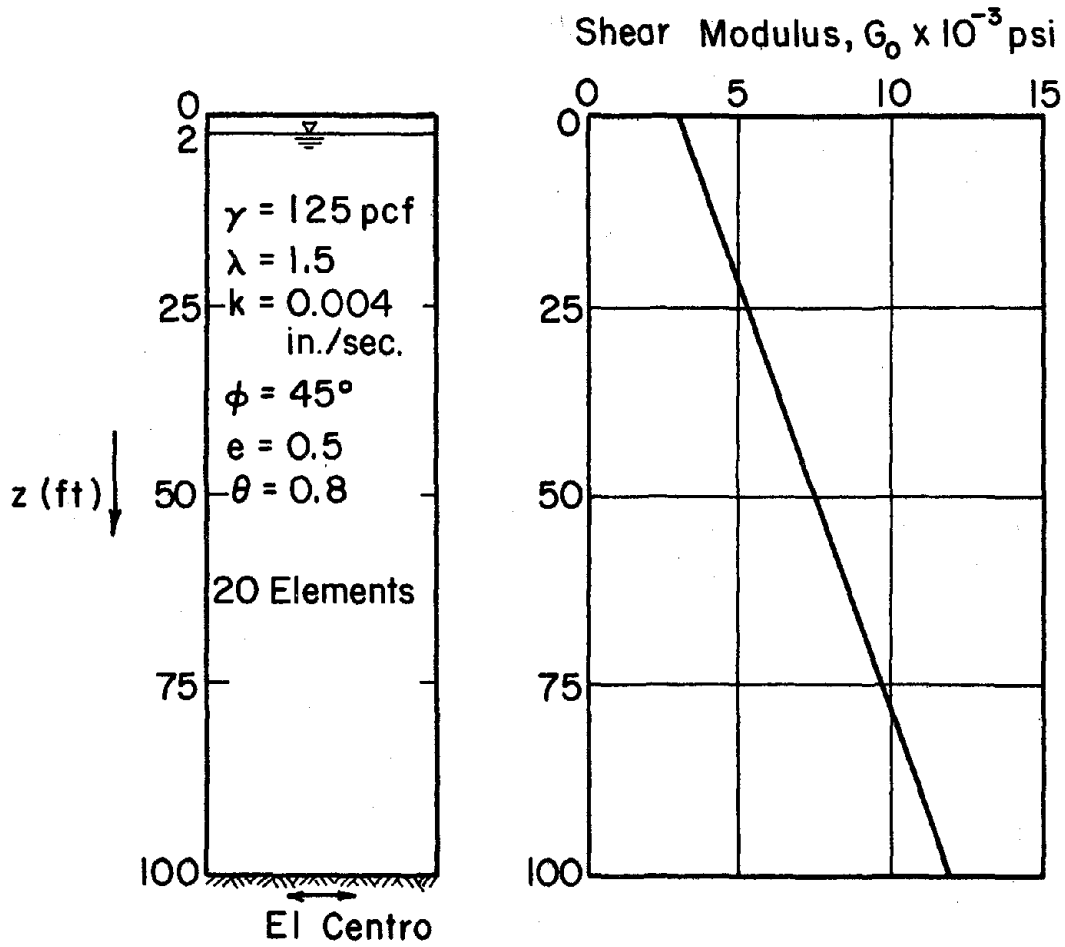


FIG. 7.—Properties Used in Example No. 1

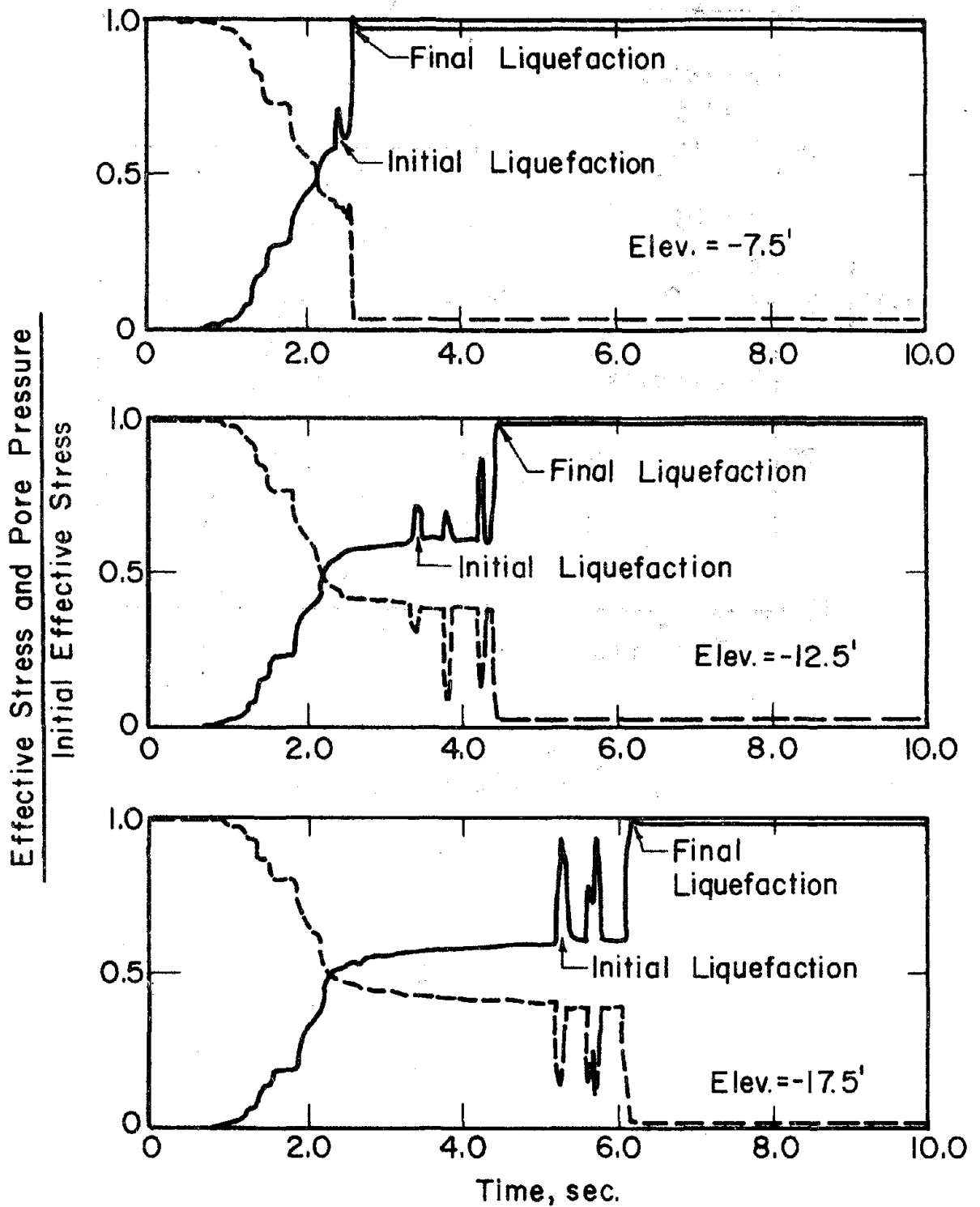


FIG. 8.—Excess Pore Pressure Time Histories,  
Example No. 1

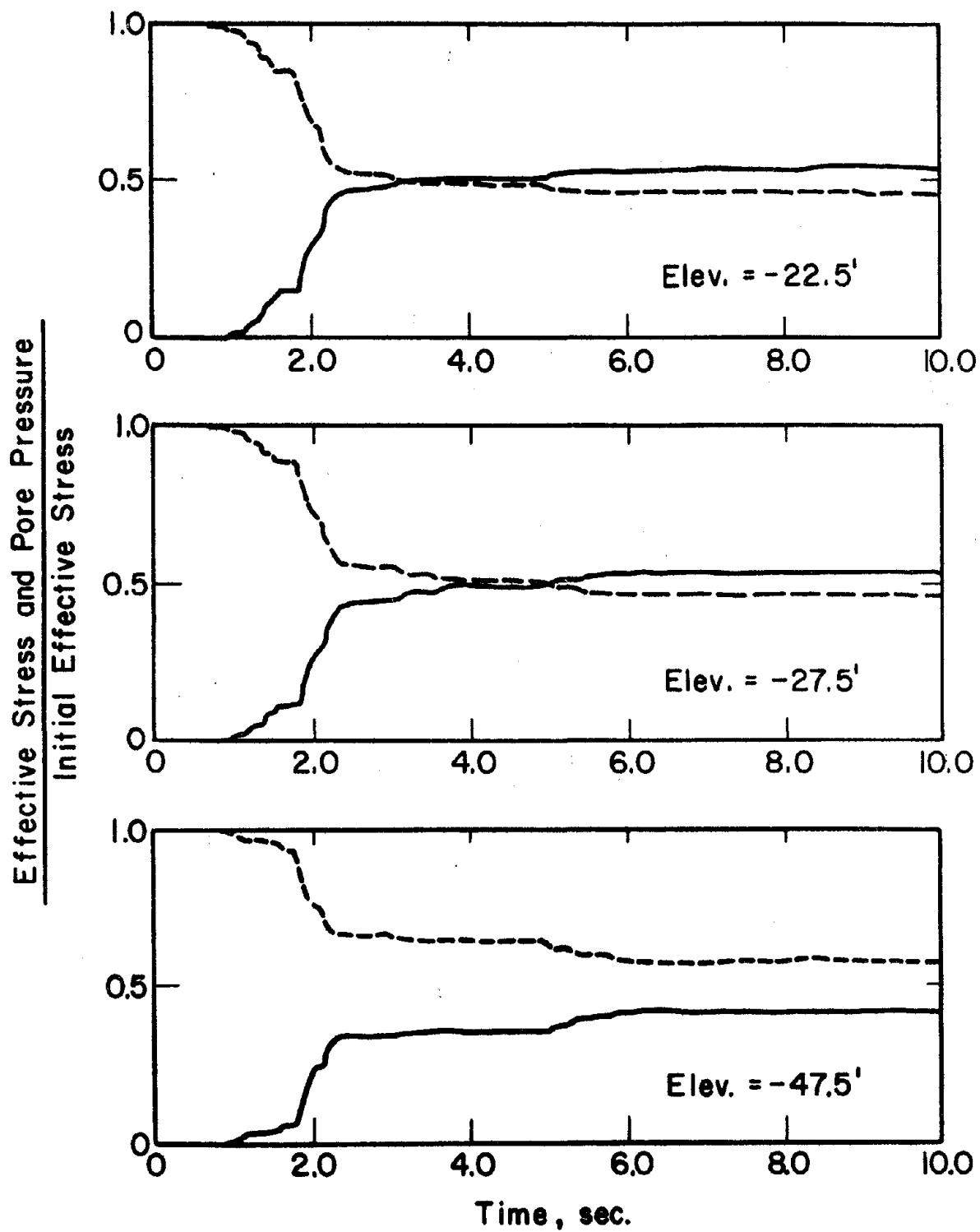


FIG. 8.—(Continued)

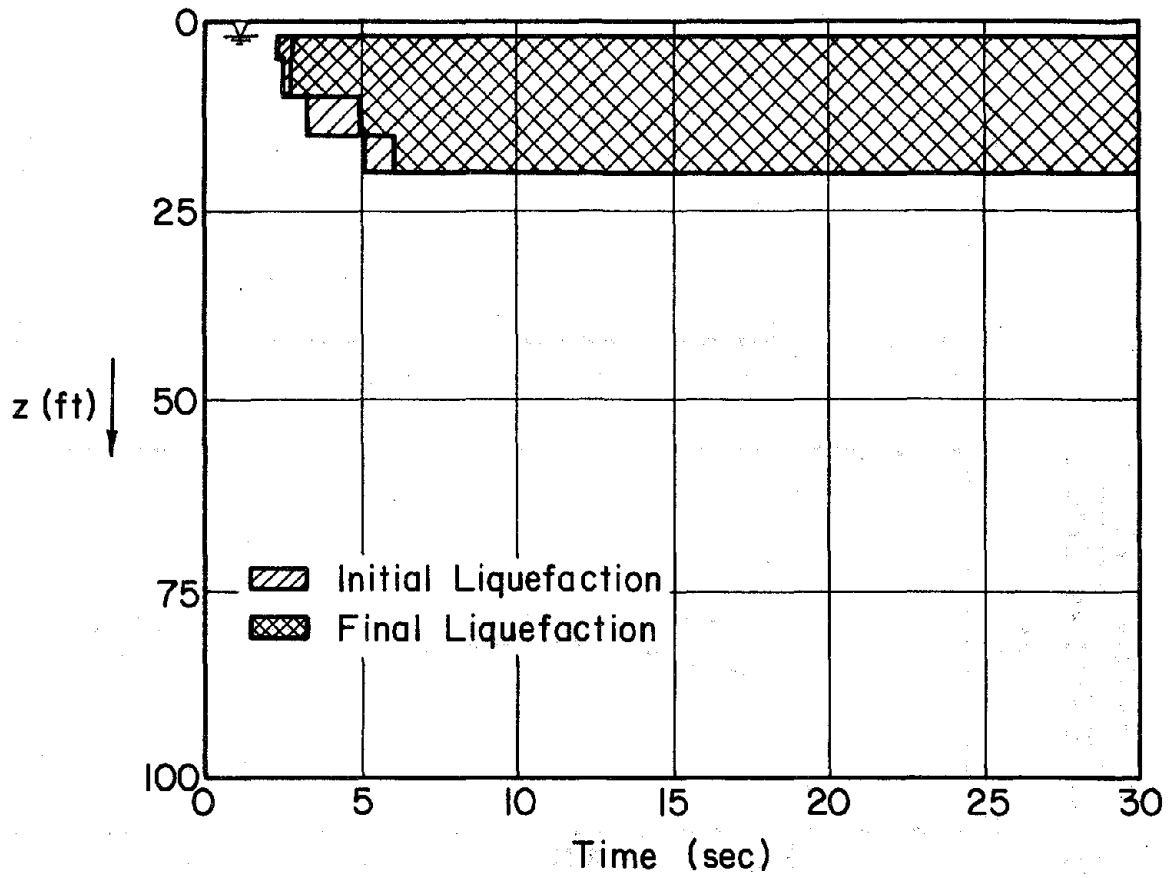


FIG. 9.—Development of Liquefaction with Time,  
Example No. 1

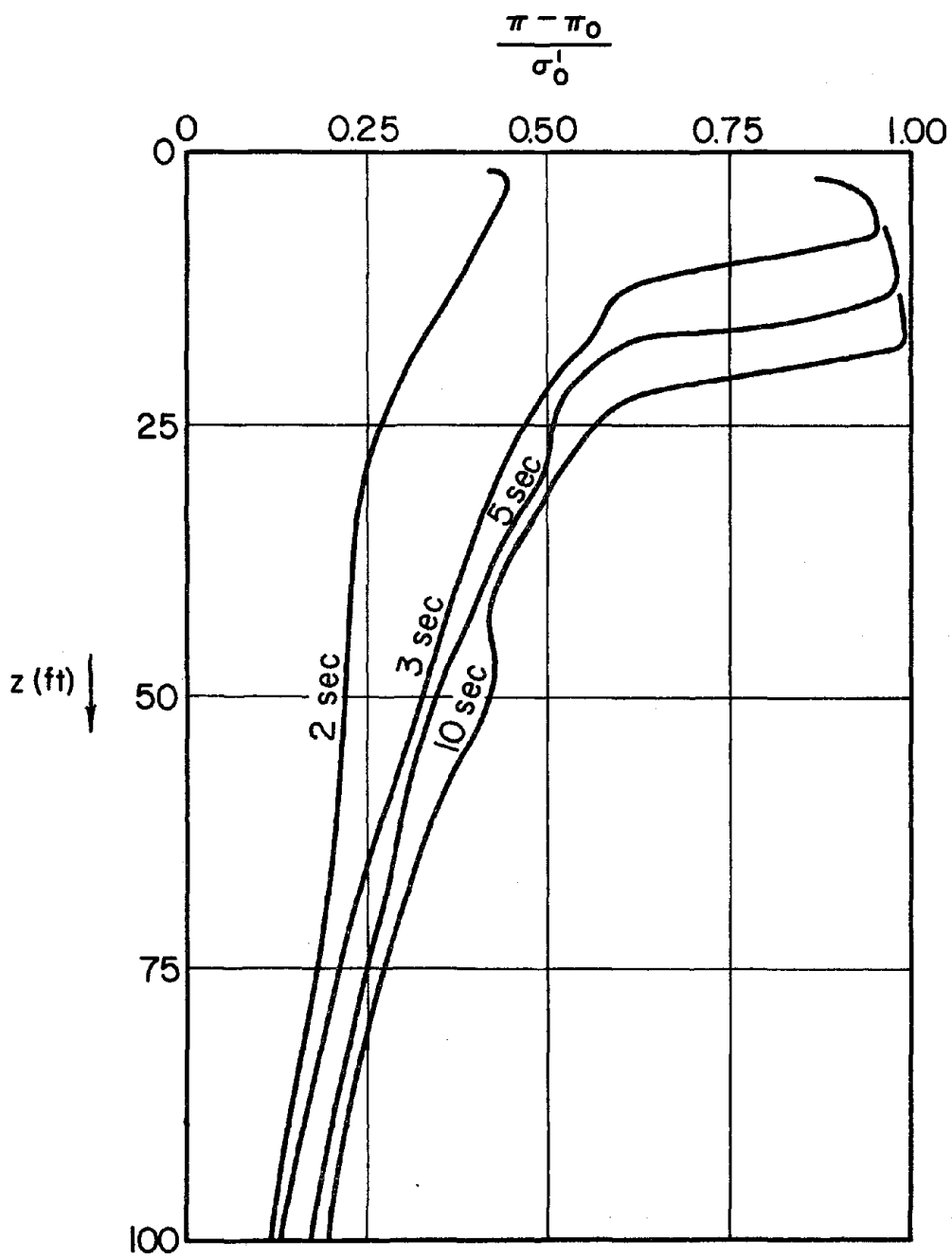


FIG. 10.—Pore Pressure Distribution at Various Times, Example No. 1

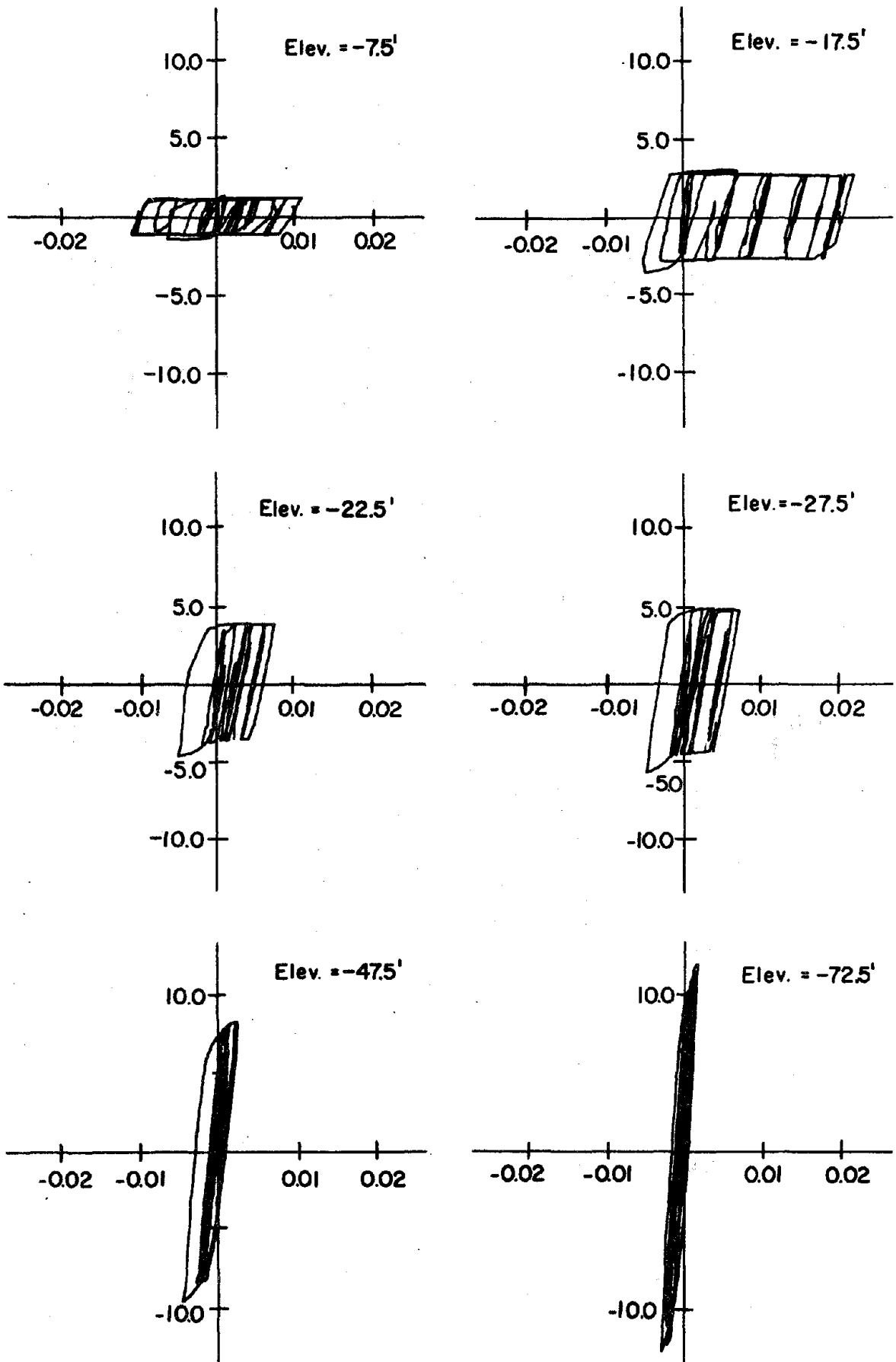


FIG. 11.—Shear Stress-Strain Plots, Example No. 1

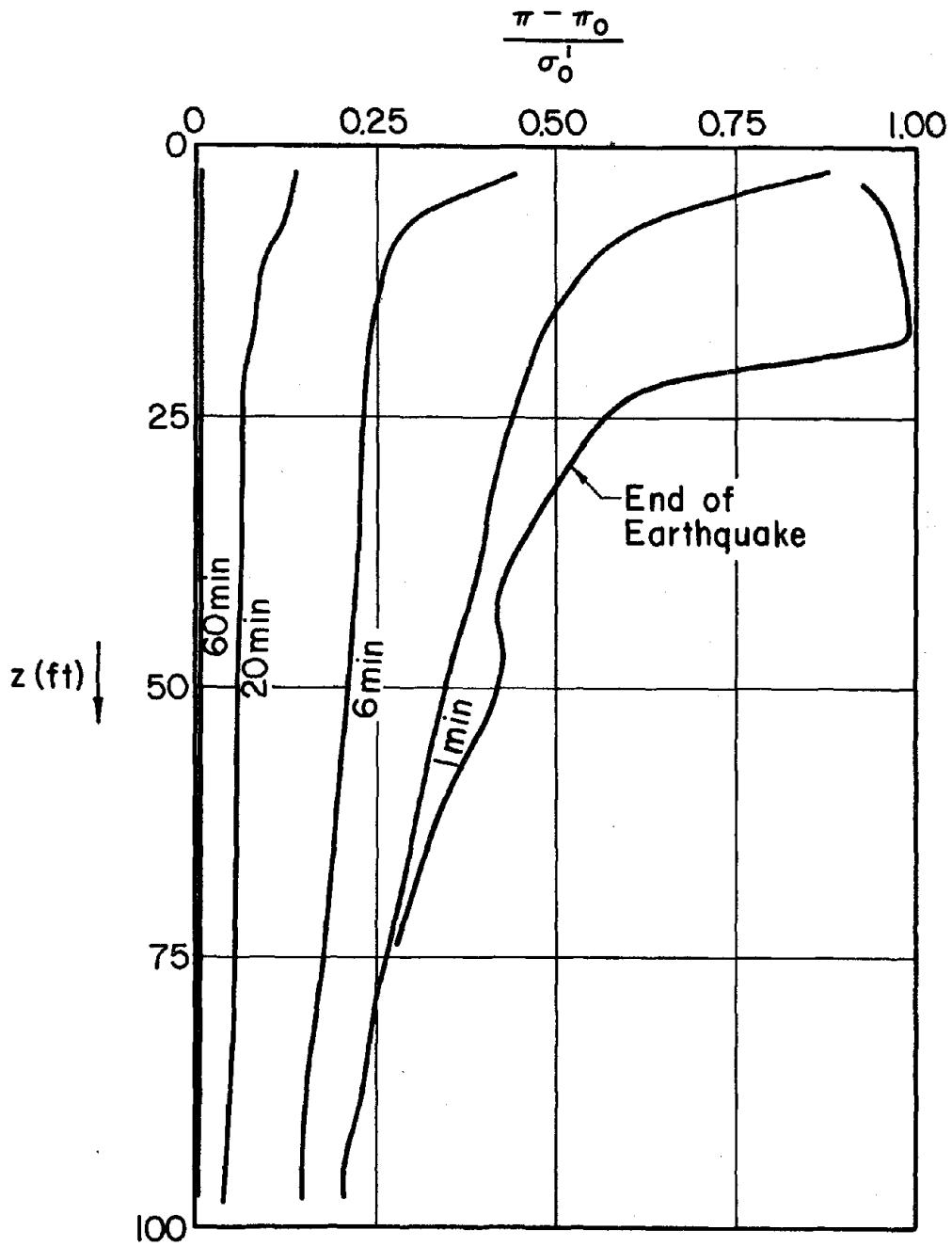


FIG. 12.—Post-Earthquake Dissipation of Excess Pore Pressures, Example No. 1

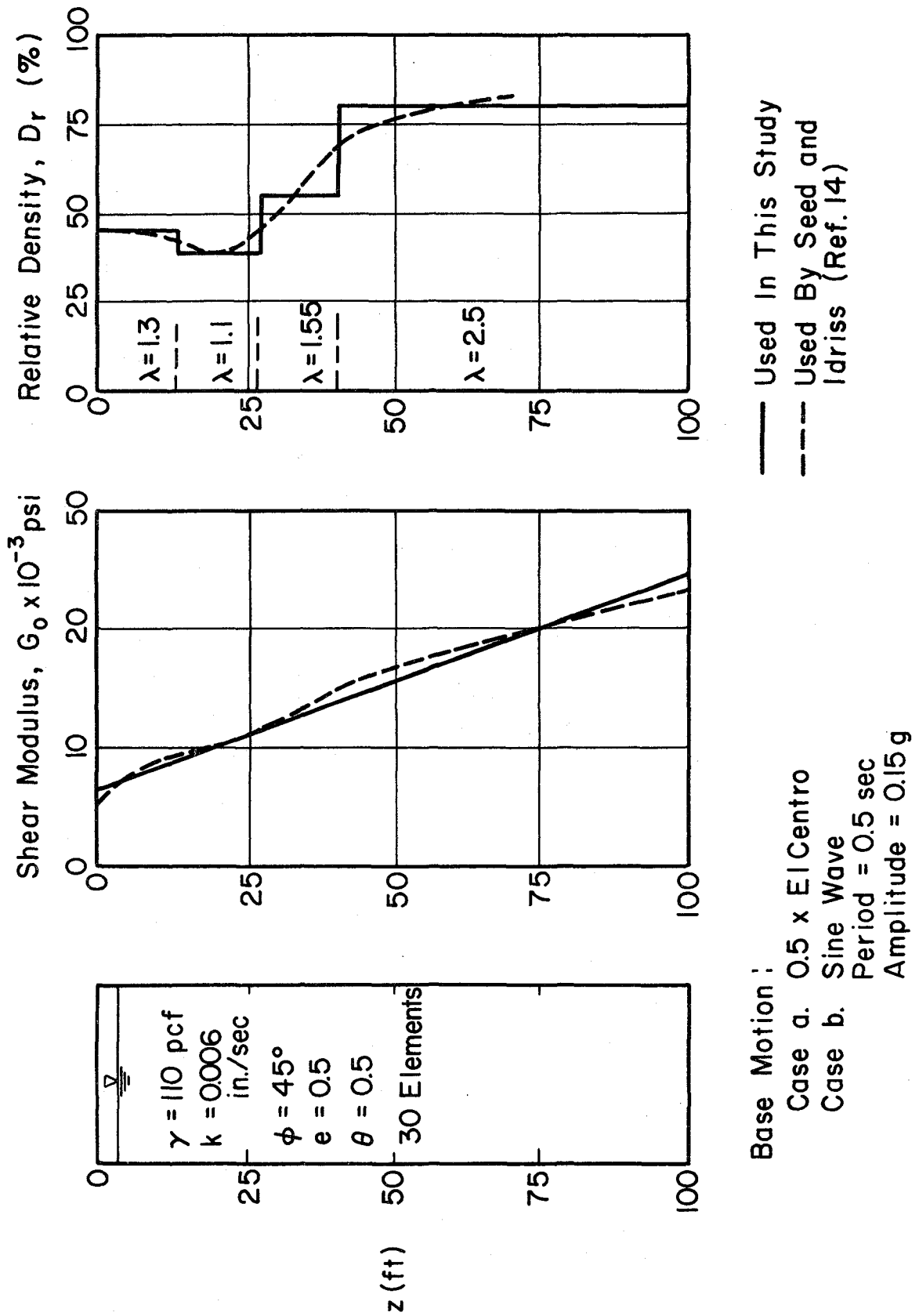


FIG. 13.—Properties Used in Example No. 2; Niigata Like Soil Profile



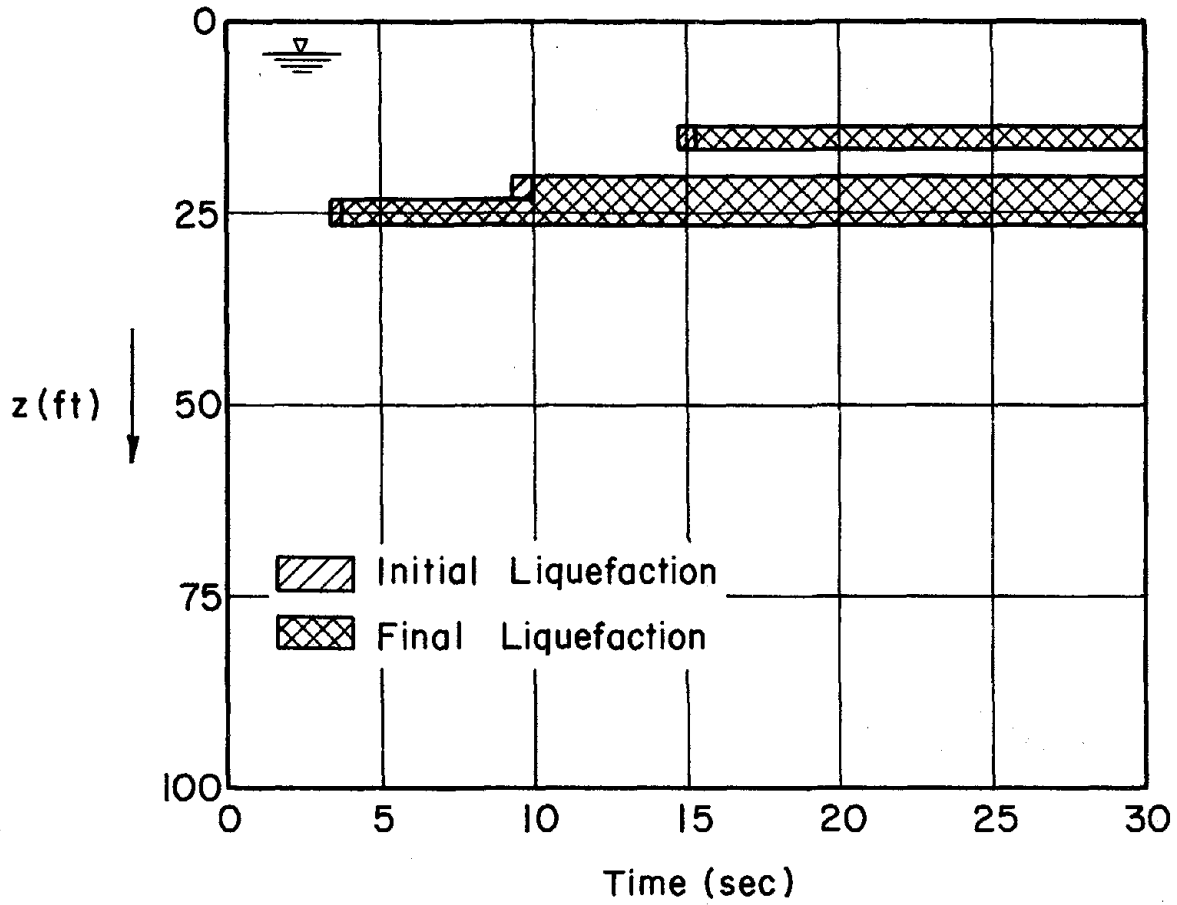


FIG. 14.—Development of Liquefaction with Time for Base Motion of 0.5 x El Centro Earthquake Record, Example No. 2

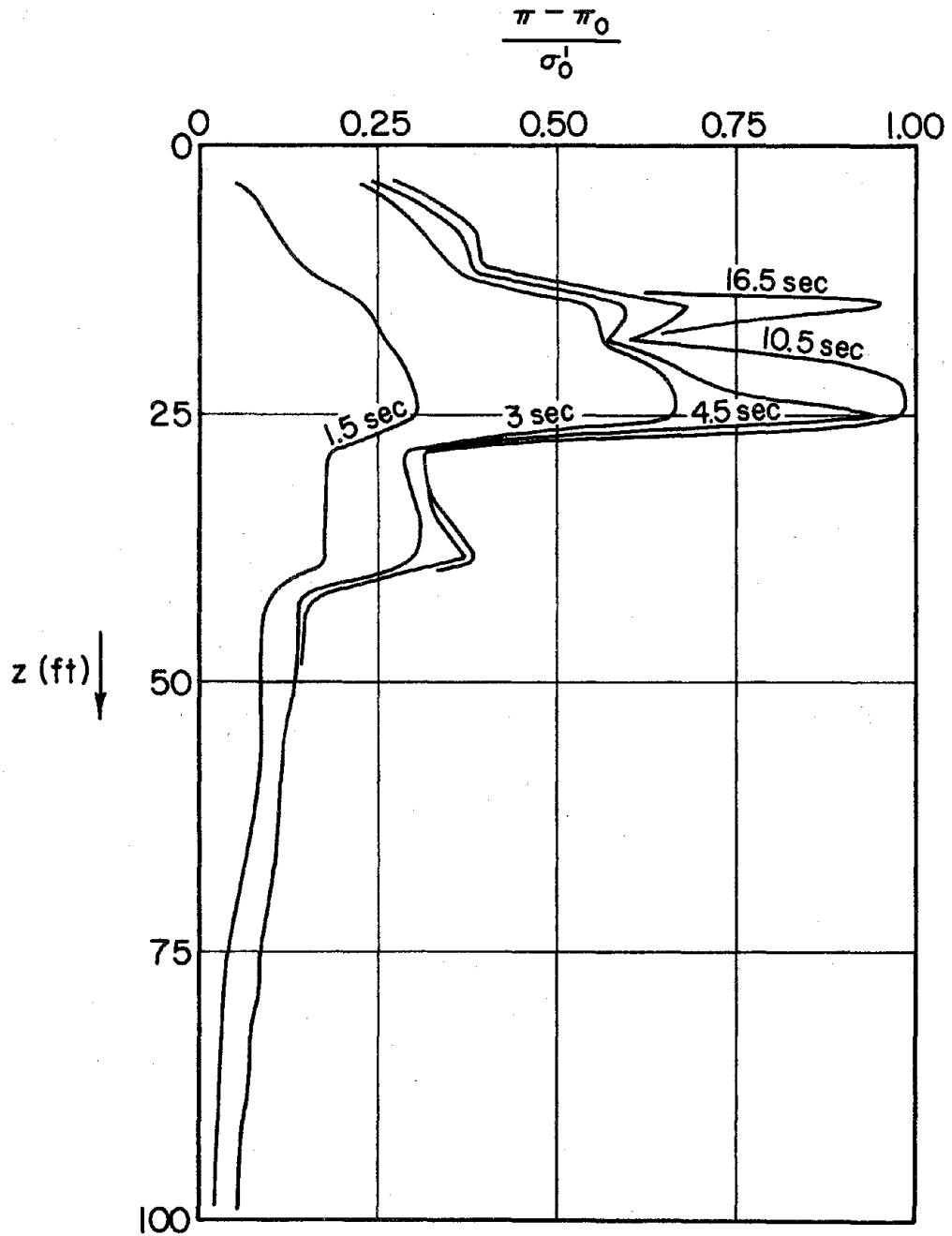


FIG. 15.—Variation of Pore Pressure with Depth for Base Motion of 0.5 x El Centro Earthquake Record, Example No. 2

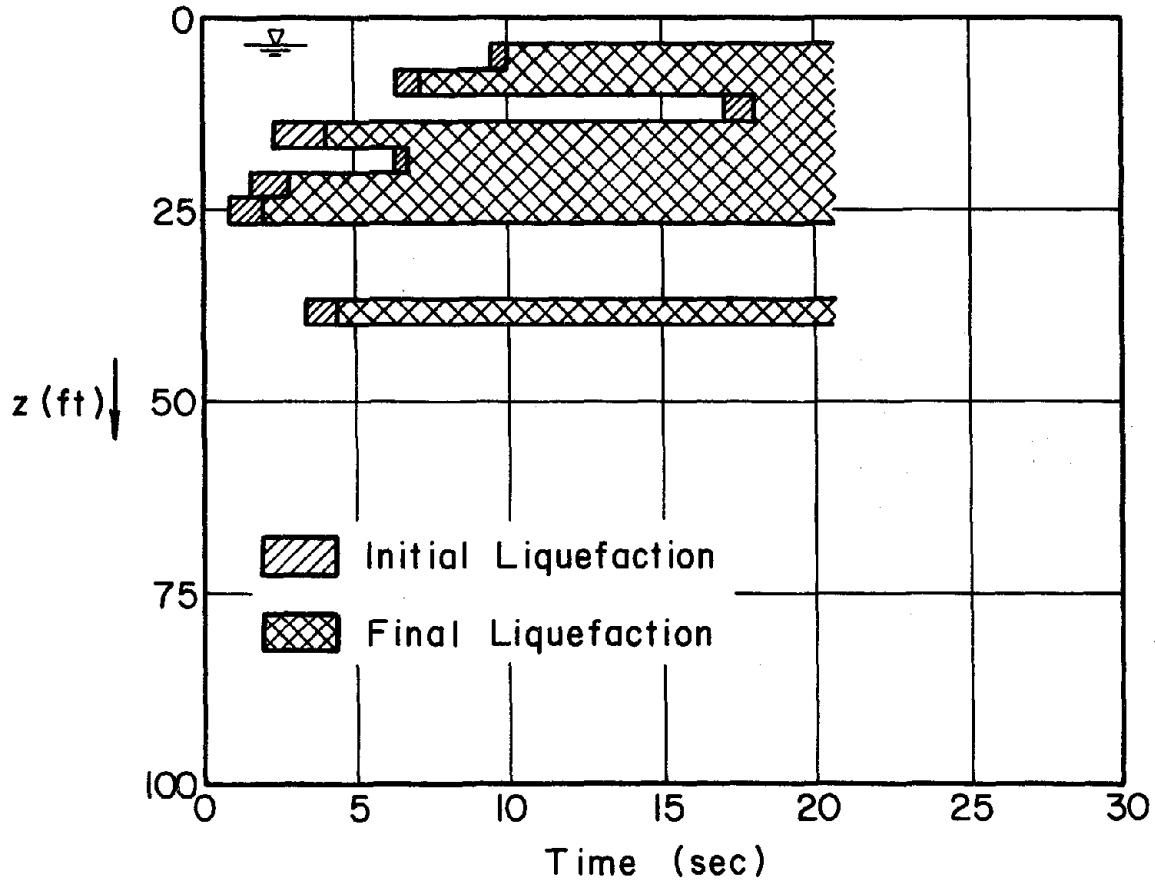


FIG. 16.—Development of Liquefaction with Time for Base Motion of Sine Wave, Example No. 2

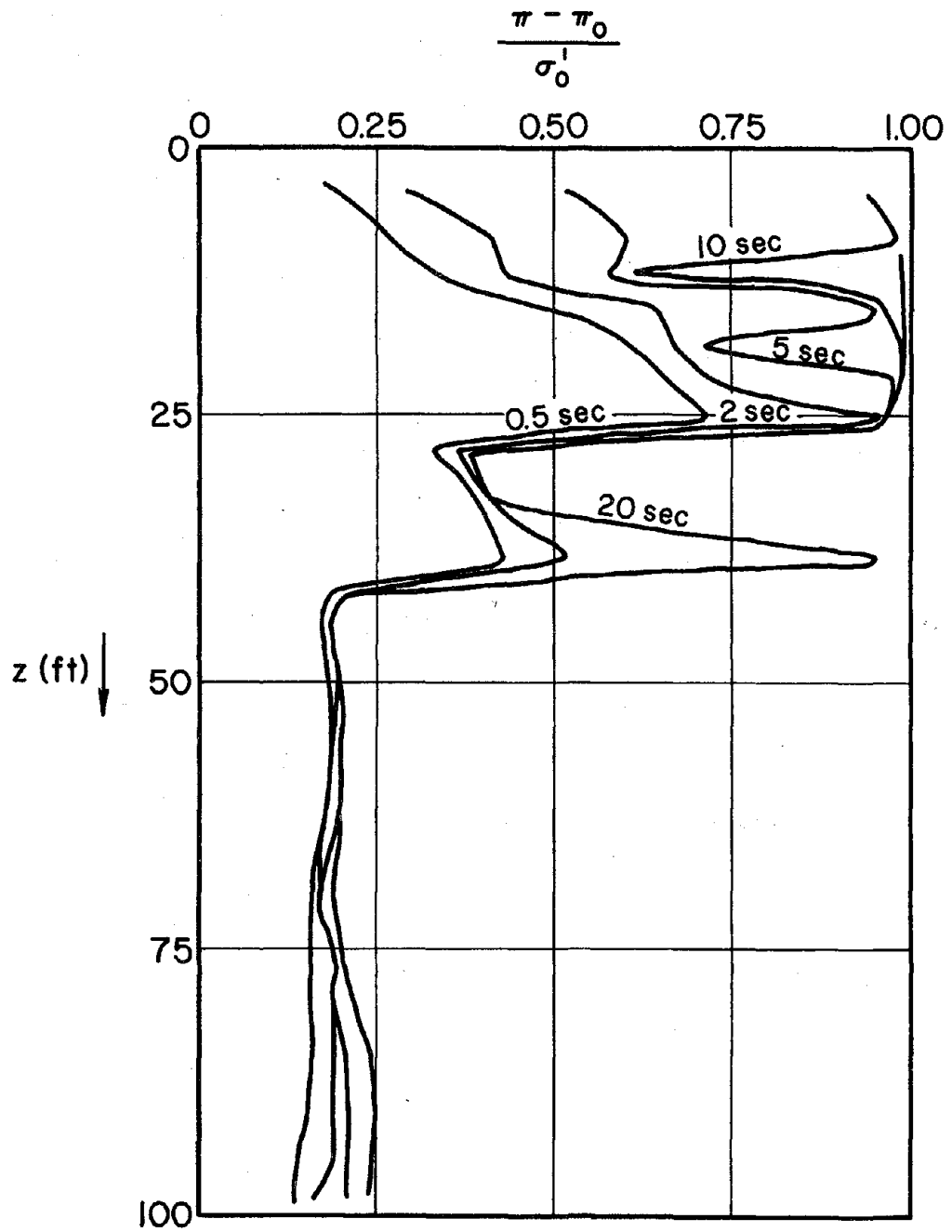


FIG. 17.—Variation of Pore Pressure with Depth for Base Motion of Sine Wave, Example No. 2

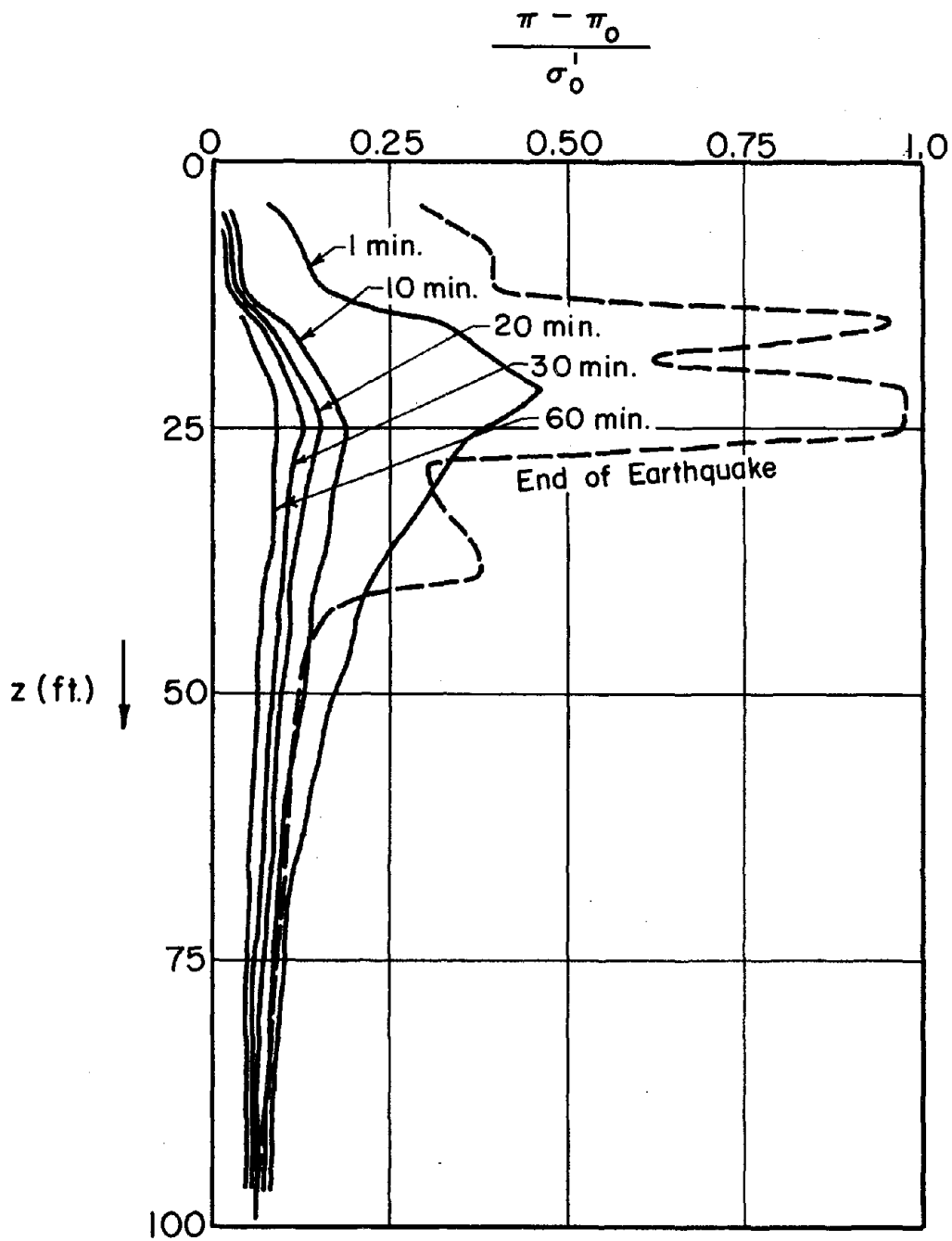


FIG. 18.—Post Earthquake Dissipation of Excess Pore Pressures for Base Motion of 0.5x El Centro Earthquake Record, Example No. 2



APPENDIX - I

INPUT DATA FOR COMPUTER

PROGRAM LASS-II





APPENDIX I  
INPUT DATA FOR  
COMPUTER PROGRAM LASS-II

The computer program LASS-II is for Liquefaction Analysis of Saturated Soil deposits. This first version is capable of dynamic analysis of horizontally layered saturated cohesionless soil deposits.

I. CONTROL CARDS

Card 1 (18A4)

Columns 1-72 Problem title (To be printed in output)

Card 2 (3I5, F10.0)

Columns 1-5 Number of layers

6-10 Number of different material properties

11-15 Number of dynamic time steps

16-20 Dynamic time step ( $\Delta t$ )

Card 3 (4I5)

Columns 1-5 Interval of steps for printing of response  
(displacements, velocities, accelerations, strains  
and stresses).

6-10 Interval of steps for saving of response at  
selected points to be specified later for the  
purpose of plotting.

- Columns 11-15 Step number for starting printing of response at intervals indicated in columns 1-5 of this card.
- 16-20 Interval of steps for updating of stiffness matrix.

## Card 4 (3I5, 6F10.0)

- Columns 1-5 Number of nodes for which the time histories of acceleration, velocity and displacement are to be plotted.
- 6-10 Number of elements for which the time histories of shear stress and shear strain, and the shear stress vs. the shear strain are to be plotted.
- 11-15 Number of elements at which the time histories of effective stress and pore water pressure are to be plotted.
- 16-25 Height of the plotter paper in inches, (Default value is 10).
- 26-35 Height of the stress and strain time history diagrams in inches, (Default value is 2).
- 36-45 Length of the time axis in inches, (Default value is 10).
- 46-55 Size (height = length) of the stress vs strain diagrams in inches, (Default value is 8).
- 56-65 Height of the pore pressure and effective stress history diagrams in inches, (Default value is 4).
- 66-75 Maximum time value to be plotted in seconds, (Default value is 10).

## Card 5 (4I5)

- Columns 1-5 A non-zero value indicates a request for the computation of response spectras (Acceleration, velocity and displacement).
- 6-10 A non-zero value indicates a request for the plot of response spectras.
- 11-15 Number of damping values to be used in the computation of response spectra, (Default value is 3). Maximum value that can be specified is 10.
- 16-20 Number of nodes for which the response spectras to be computed. Maximum value that can be specified is 10.

## Card Group 6 (8F10.0)

This card is required if a non-zero value is specified in columns 11-15 of Card 5. In the above format give the damping values as percent of critical damping. If a zero is specified in columns 11-15 of Card 5, program computes spectras for .02, .05, .1 damping.

## Card 7 (10I5)

This card is required if the computation of response spectra is requested. In the above format give the node numbers.

## Card 8 (2I5)

- Columns 1-5 A non-zero value indicates a request for the post-earthquake analysis.

Columns 6-10 If a non-zero value is specified in the column 1-5 of this card, give the number of different time steps which will be used in post-earthquake analysis. Maximum value that can be specified is 10.

Card Group 9 (F10.0, 2I5)

One card must be provided for each time step indicated in columns 6-10 of card 8.

Columns 1-10 Time step.  
 11-15 Number of times that this time step is to be repeated.  
 16-20 Print interval of the time step.

Card 10 (2F10.0)

Columns 1-10 Depth of water table.  
 11-20 Gravity, g, (Default value is  $386.2 \text{ in/sec}^2$ ).

II. SOIL DEPOSIT DATA

Card Group 11 (F10.0, 2I5)

One card required for each layer of soil.

Columns 1-10 Depth of the base of the layer.  
 11-15 Number of elements the layer is to be subdivided.  
 16-20 Material number of layer. This number is to identify the type of material properties in the sequence given in the next card group to be assigned to this layer.

This data is provided for the layers in the sequence of increasing depth starting at the layer at the ground surface.

## Card Group 12 (8F10.0)

The following cards must be provided for each material type as indicated in columns 6-10 of Card 2.

## Card 12.1

Columns 1-10	Bulk modulus for effective stresses.
11-20	Shear modulus at the top of the layer.
21-30	Change in shear modulus per unit of depth.
31-40	Bulk modulus of fluid.
41-50	Permeability.
51-60	Mass density of solid.
61-70	Mass density of fluid.
71-80	$S_{\max}$

## Card 12.2

Columns 1-10	$1/\lambda$
11-20	$\phi$
21-30	$\alpha$
31-40	Constant for the direction of stress vector in $p'$ - $q$ stress plane for post-initial liquefaction calculation.
41-50	Effective stress at final liquefaction.
51-60	Void ratio

III. PLOT DATA

## Card Group 13 (16I5)

This card group is required if a non-zero value is specified in

columns 1-5 of Card 4. In the above format give the node numbers of the nodes where the motion plots are required.

Card Group 14 (16I5)

This card group is required if a non-zero value is specified in columns 6-10 of Card 4. In the above format give the element numbers of the elements for which the time histories of shear stresses and shear strains, and the stress-strain diagrams are to be plotted.

Card Group 15 (16I5)

This card group is required if a non-zero value is specified in columns 11-14 of Card 4. In the above format give the element numbers of the elements for which the time histories of effective stresses and pore water pressures are to be plotted.

IV. EARTHQUAKE DATA

Card 16 (12A6)

Columns 1-72 Earthquake identification title (to be printed in output).

Card 17 (2F10.0, 2I5)

Columns 1-10 Time scale factor. Earthquake time points are multiplied by this time scale factor. (If zero or blank, a value of one is used). This is not required if a non-zero value is specified in columns 26-30 of this card.

- Columns 11-20 Amplitude scale factor. Earthquake amplitudes are multiplied by this scale factor (If zero or blank, a value of one is used).
- 21-25 Number of time points to define the time history of base acceleration.
- 26-30 Base acceleration data type: zero or blank when the base acceleration data are given at irregular time intervals; any non-zero value when the base acceleration is given at equal intervals with the same time step as specified in columns 21-30 of Card 2.

If the value in columns 26-30 of Card 14 is zero provide Card group 15, otherwise provide Card group 16.

Card Group 18 (8F10.0)

In the above format for each base acceleration time point give sequentially the values of time and corresponding base acceleration. The program interpolates to determine the value of base acceleration at intervals of time step  $\Delta t$ .

Card Group 19 (8F9.0)

In the above format for each base acceleration time point give sequentially the values of base acceleration at intervals of time step  $\Delta t$ .





APPENDIX - II

LISTING OF COMPUTER

PROGRAM LASS-II



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PROGRAM IASS2

PROGRAM FOR EARTHQUAKE ANALYSIS OF HORIZONTALLY LAYERED  
SATURATED SOILS WITH EVALUATION OF LIQUEFACTION POTENTIAL

DEVELOPED BY JAMSHID GHABOUSSI  
CIVIL ENGINEERING DEPARTMENT  
UNIVERSITY OF ILLINOIS AT URBANA-CHAMPAIGN  
OCTOBER 1975

MODIFIED BY JAMSHID GHABOUSSI AND UNIT DIRKEN  
CIVIL ENGINEERING DEPARTMENT  
UNIVERSITY OF ILLINOIS AT URBANA-CHAMPAIGN  
MARCH 1977

COMMON A (40000)  
COMMON/CONTL/HED (10), NCYCL, DT, NDI, NPRNT, NSAVE, LOUT, SC, NUPDAT, NPLT  
\* , NSTAT, NINCR, NSIPRT  
COMMON/WIVL/ WTABLS, GRAV  
COMMON/PLTNG/ NPLOTM, NPLTSS, NSETS, HPAP, HPLOT, BPLOT, DPLOT, EPLOT,  
\* TEND  
COMMON/SPEC/DV (10), NODE (10), NNODE, IRS, IRSP  
COMMON/POSEQ/NIBEP (10), IS (10), ILIMIT, NTS, NPLQPT (10)

MEOT=40000  
READ (5,1000) HED  
READ (5,1001) N1AYER, NMAT, NCYCL, NDI, DT, NSTAT, NINCR  
WRITE (6,2000) HED, N1AYER, NMAT, NCYCL, NDI, DT  
READ (5,1003) NPRNT, NSAVE, NSTPRT, NUPDAT, NWRITE  
WRITE (6,2001) NPRNT, NSAVE, NSTPRT, NUPDAT, NWRITE  
READ (5,1004) NPLOTM, NPLTSS, NSETS, HPAP, HPLOT, BPLOT, DPLOT, EPLOT, TEND  
IF (NPLOTM.LE.0.AND.NPLTSS.LE.0.AND.NSETS.LE.0) GO TO 200  
IF (HPAP.LT.1..OR.HPLOT.LT.1..OR.BPLOT.LT.1..OR.DPLOT.LT.1..OR.TEN  
\* .LT.1..OR.EPLOT.LT.1.) WRITE (6,2004)  
IF (HPAP.LT.1.) HPAP=10.  
IF (HPLOT.LT.1.) HPLOT=2.  
IF (BPLOT.LT.1.) BPLOT=10.  
IF (DPLOT.LT.1.) DPLOT=8.  
IF (EPLOT.LT.1.) EPLOT=4.  
IF (TEND.LT.1.) TEND=10.  
WRITE (6,2003) NPLOTM, NPLTSS, NSETS, HPAP, HPLOT, BPLOT, DPLOT, EPLOT,  
\* TEND  
200 READ (5,1005) IRS, IRSP, NDV, NNODE  
IF (IRS.EQ.0) GO TO 215  
WRITE (6,2005)  
IF (NDV.LE.0) GO TO 230  
READ (5,1006) (DV (L), L=1, NDV)  
GO TO 240  
230 NDV=3  
WRITE (6,2006)  
DV (1)=0.02  
DV (2)=0.05  
DV (3)=0.1  
240 WRITE (6,2007) (DV (L), L=1, NDV)  
READ (5,1007) (NODE (L), L=1, NNODE)  
WRITE (6,2008) (NODE (L), L=1, NNODE)  
215 READ (5,1007) IPOSEQ, NTS  
IF (IPOSEQ.EQ.0) GO TO 210

```

WRITE (6,2009)
READ (5,1008) (TS (I), NTREP (I), NPEQPR (I), I=1, NTS)
WRITE (6,2010) (TS (I), NTREP (I), NPEQPR (I), I=1, NTS)
210 IF (NDI.EQ.0) NDI=1
NC=NDI+1
IF (NDI.EQ.1) NC=NC+1
READ (5,1002) WTABLE, GRAV
IF (GRAV.LE.0.0) GRAV=386.2
WRITE (6,2002) WTABLE, GRAV
N1=1
N2=N1+N LAYER
N3=N2+N LAYER
N4=N3+N LAYER
N5=N4+35*NMAT
IF (NDI.EQ.0) NDI=1
N6=N5+NDI*NCYCL
KK1=N6
KK2=KK1+N PLOTM
KK3=KK2+N P L T S S
KK4=KK3+N S E T S
K1=KK4
CALL REED (A (N1), A (N2), A (N3), A (N4), A (N5), A (KK1), A (KK2), A (KK3),
* N LAYER, NMAT, NUMNP, NCYCL, NDI, A (K1))
K2=K1+NUMNP
K3=K2+NUMNP
K4=K3+NUMNP
CALL MESH (A (N1), A (N2), A (N3), A (K1), A (K2), A (K3), WTABLE, NUMNP,
* N LAYER)
NEQ=NC*NUMNP
MBAND=2*NC
K5=K4+NEQ*MBAND
K6=K5+NEQ*MBAND
K7=K6+NEQ
K8=K7+NEQ
K9=K8+NEQ
K10=K9+NEQ
K11=K10+NEQ
K12=K11+NEQ
K13=K12+NEQ
K14=K13+11*NUMNP
K15=K14+11*NUMNP
KK15=K15+NEQ
KK16=KK15+2*NUMNP
K16=KK16+N N O D E * N C Y C L
NTLL=K16-K4+1
NCCY=NCYCL
CALL SZERO (A (K4), NTLL)
NTSAVE=(NCYCL+1)/NSAVE
KN1=K16
KN2=KN1+NTSAVE+2
K16=KN2+NTSAVE+2
NBLK=NTSAVE
NPTOT=3*N P L O T M + 2 * N P L T S S + 2 * N S E T S + 3
IF (NDI.GT.1) NPTOT=NPTOT+3*N P L O T M
IF (NPTOT.LE.0) GO TO 100
NLEFT=MTOT-K16-1
NEED=NPTOT*NTSAVE
IF (NEED.LE.NLEFT) GO TO 100
NUM=(NEED-1)/NLEFT+1
NBLK=NLEFT/NPTOT
REWIND LOU T

```

```

130 CONTINUE
  NPTOT=NPTOT*NBLK
  K17=K16+NPLL
  K18=K17+NDV*130
  K19=K18+NDV*130
  K20=K19+NDV*130
  K21=K20+130
  K22=K21+NUMNP*2
  K23=K22+NUMNP*2
  K24=K23+NUMNP*2
  K25=K24+NUMNP*2
  K26=K25+NUMNP
  K27=K26+NUMNP
  K28=K27+NUMNP
  K29=K28+NUMNP
  K30=K29+NUMNP
  WRITE(6,2012) MTOT,K30
  IF(K30.LT.MTOT) GO TO 140
  WRITE(6,2011)
  STOP

140 CONTINUE
  CALL SZPRO (A(K16),NELL)
  CALL MASSMT (A(K10),A(K1),A(K2),A(K3),A(N4),NUMNP,NC)
  CALL SELFLD (A(K1),A(K2),A(K3),A(N4),A(K13),A(K15),NUMNP,NC)
  CALL SOLVE (A(K1),A(K2),A(K3),A(N4),A(N5),A(K4),A(K5),A(K6),A(K7)
  * A(K8),A(K9),A(K10),A(K11),A(K12),A(K13),A(K14),A(K15),A(KK1),
  * A(KK2),A(KK3),A(K16),A(KK15),A(KK16),NBLK,NPTOT,NUMNP,
  * NMAT,NREQ,NBAND,NCCY)
  IF(NSAVE.LE.0) GO TO 150
  CALL OUTP (A(KK1),A(KK2),A(KK3),A(KK1),A(KN2),A(K16),A(KK15),
  * NUMNP,LUN,NBLK,NPTOT,NISAVE,NDI)

150 CONTINUE
  IF(NNODE.LE.0) GO TO 160
  CALL RESPEC(A(KK16),NCYCL,A(K17),A(K18),A(K19),A(K23),NDV,DT)
160 IF(IPOSEQ.EQ.7) GO TO 170
  IF(IPOSEQ.GE.1) CALL SOLPEQ (A(N4),A(K1),A(K2),A(K3),A(K13),
  * A(K21),A(K22),A(K23),A(K24),A(K25),A(K26),A(K27),A(K28),A(K29),
  * NUMNP)

170 CONTINUE
  STOP

1000 FORMAT (18A4)
1001 FORMAT (4I5,F10.0,2I5)
1002 FORMAT (8F10.0)
1003 FORMAT (16I5)
1004 FORMAT (3I5,6F10.0)
1005 FORMAT (4I5)
1006 FORMAT (8F10.0)
1007 FORMAT (16I5)
1008 FORMAT (F10.0,2I5)
2000 FORMAT (1H1/18A4////
  * 35H NUMBER OF LAYERS ..... = ,I5//
  * 35H NUMBER OF MATERIALS ..... = ,I5//
  * 35H NUMBER OF CYCLES ..... = ,I5//
  * 35H NUMBER OF INPUT DIRECTIONS .. = ,I5//
  * 35H TIME STEP (DT) ..... = ,E12.4 )
2001 FORMAT (// 35H PRINT INTERVAL ..... = ,I5//
  * 35H INTERVAL FOR SAVING RESPONSE = ,I5//
  * 35H STEP FOR STARTING PRINT ..... = ,I5//
  * 35H STIFFNESS UPDAT CYCLE ..... = ,I5//
  * 35H OUTPUT TAPE FLAG ..... = ,I5//)
2002 FORMAT (//

```

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```

* 35H DEPTH OF WATER TABLE ..... = ,F10.3//
* 35H GRAVITY ..... = ,F10.3//
2003 FORMAT (//25H ..... PLOT DATA ..... //
* 55H NUMBER OF MOTION PLOTS ..... = ,I5,/
* 55H NUMBER OF STRESS, STRAIN, TIME PLOTS ..... = ,I5,/
* 55H NUMBER OF PORE PRESS., EFF. STRESS VS. TIME PLOTS = ,I5,/
* 55H HEIGHT OF THE PLOT PAPER (INCHES) ..... = ,F5.1,
* 55H HEIGHT OF THE STRESS AND STRAIN HISTORY PLOTS (IN) = ,F5.1,
* 55H LENGTH OF THE TIME AXIS (INCHES) ..... = ,F5.1,
* 55H SIZE OF THE STRESS VS. STRAIN PLOTS (INCHES) ... = ,F5.1,
* 55H HEIGHT OF THE PORE PRESSURE AND EFFECTIVE STRESS = ,/,
* 55H HISTORY PLOTS (INCHES) ..... = ,F5.1,
* 55H MAX. TIME VALUE TO BE PLOTTED (SECONDS) ..... = ,F5.1,
* //)
2004 FORMAT (//,50H DEFAULT VALUE(S) ASSUMED FOR PLOT PARAMETER(S)
2005 FORMAT (30H .....RESPONSE SPECTRA DATA... /)
2006 FORMAT (50H DEFAULT VALUES WILL BE ASSUMED FOR DAMPING VALUES
2007 FORMAT (16H DAMPING VALUES= ,10F10.5)
2008 FORMAT (45H RESPONSE SPECTRA WILL CALCULATED FOR NODES ,10I5//)
2009 FORMAT (//40H ...DATA FOR POST EARTHQUAKE ANALYSIS... //
* 11H TIME STEPS ,3X,10H NO. REP. ,3X,11H PRINT INT. )
2010 FORMAT (F10.5,9Y,I5,9X,I5)
2011 FORMAT (45H PROBLEM DEFINED IS TOO LARGE TO BE COMPUTED )
2012 FORMAT (//22H STORAGE INFORMATION //
* 23H CORE SPACE AVAILABLE= ,I6,
* 23H CORE SPACE REQUESTED= ,I6)
END

```

```

SUBROUTINE REED (DEPTH,NEL,MATYP,EMATL,BACC,JPLTM,JPLTSS,
* JSETS,NLAYER,NMAT,NUMNP,NCYCL,NDI,ACC)

```

```

C
C   DIMENSION DEPTH(NLAYER),NEL(NLAYER),MATYP(NLAYER),EMATL(35,NMAT),
*   BACC(NCYCL,NDI),ACC(2,1),TITLE(18),JPLTM(1),JPLTSS(1),JSETS(1)

```

```

C
C   COMMON/CONTL/ HED(18),DUMMM,DT
COMMON/PLTING/ NPLOTM,NPLTSS,NSETS,HPAP,HPL0T,BPLOT,DPLOT,EPL0T,
* TEND
C   COMMON/WLVL/ WTABLE,GRAV

```

```

C
C   READ (5,1000) (DEPTH(I),NEL(I),MATYP(I),I=1,NLAYER)
WRITE (6,2000)
WRITE (6,2001) (I,DEPTH(I),NEL(I),MATYP(I),I=1,NLAYER)
WRITE (6,2002)
DO 100 L=1,NMAT
100 READ (5,1001) (EMATL(I,L),I=1,3),(EMATL(I,L),I=12,24)
CONTINUE
WRITE(6,2016)
DO 101 L=1,NMAT
WRITE(6,2003) L,(EMATL(I,L),I=1,3),(EMATL(I,L),I=12,16)
101 CONTINUE
WRITE(6,2017)
DO 102 L=1,NMAT
WRITE(6,2006) L,(EMATL(I,L),I=17,22)
102 CONTINUE
NUMNP=0
DO 110 I=1,NLAYER
110 NUMNP=NUMNP+NEL(I)
IF (NPLOTM.LE.0) GO TO 130
READ (5,1005) (JPLTM(I),I=1,NPLOTM)
WRITE (6,2008)
WRITE (6,2013) (JPLTM(I),I=1,NPLOTM)
130 IF (NPLTSS.LE.0) GO TO 140
READ (5,1005) (JPLTSS(I),I=1,NPLTSS)
WRITE (6,2010)
WRITE (6,2013) (JPLTSS(I),I=1,NPLTSS)
140 IF (NSETS.LE.0) GO TO 150
READ (5,1005) (JSETS(I),I=1,NSETS)
WRITE (6,2011)
WRITE (6,2013) (JSETS(I),I=1,NSETS)
150 CONTINUE

```

```

C
C   READ AND INTERPOLATE BASE ACCEL.

```

```

C
C   DO 400 LL=1,NDI
READ (5,1002) TITLE,TSCAL,ASCAL,NPOINT,NTYPE
WRITE (6,2004) TITLE,TSCAL,ASCAL
IF (NTYPE.NE.0) GO TO 162
WRITE(6,2014)
READ (5,1003) (ACC(1,I),ACC(2,I),I=1,NPOINT)
WRITE (6,2005) (ACC(1,I),ACC(2,I),I=1,NPOINT)
IF (TSCAL.LE.0.0) GO TO 170
DO 160 I=1,NPOINT
160 ACC(1,I)=ACC(1,I)*TSCAL
GO TO 170
162 READ (5,1004) (ACC(2,I),I=1,NPOINT)
WRITE(6,2015)
WRITE (6,2005) (ACC(2,I),I=1,NPOINT)
170 IF (ASCAL.LE.0.0) GO TO 190

```

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```

DO 180 I=1,NPOINT
180 ACC(2,I)=ACC(2,I)*ASCAL
190 CONTINUE
IF (NTYPE.NE.0) GO TO 300
GA1=0
I=1
T=DT
K=0
200 IF (ACC(1,I).GE.T) GO TO 250
220 I=I+1
IF (I.LE.NPOINT) GO TO 200
WRITE (6,2007)
STOP
250 SLOPE=(ACC(2,I)-ACC(2,I-1))/(ACC(1,I)-ACC(1,I-1))
280 K=K+1
IF (K.GT.NCYCL) GO TO 400
BACC(K,LL)=ACC(2,I-1)+SLOPE*(T-ACC(1,I-1))
T=T+DT
IF (ACC(1,I).GE.T) GO TO 280
GO TO 220
300 GRAVY=GRAV
DO 320 I=1,NCYCL
320 BACC(I,LL)=ACC(2,I)*GRAVY
400 CONTINUE
500 RETURN
1000 FORMAT (F10.0,2I5)
1001 FORMAT (8F10.0)
1002 FORMAT (18A4/2F10.0,2I5)
1003 FORMAT (8F10.0)
1004 FORMAT (8F9.0)
1005 FORMAT (16I5)
2000 FORMAT (1H1/45H ----- PROPERTIES OF LAYERS ----- ,//
* 5X,5HLAYER,15X,5HDEPTH,11X,9HNUMBER OF,12X,8HMATERIAL /4X,
* 6HNUMBER,32X,8HELEMENTS,14X6HNUMBER//)
2001 FORMAT (I10,F20.3,2I20)
2002 FORMAT (1H1/45H ----- MATERIAL PROPERTIES ----- ,//
2003 FORMAT (I5,8E15.6)
2004 FORMAT (1H1//18A4//
* 29H TIME SCALE ----- =,F10.4 //
* 29H AMPLITUDE SCALE ----- =,F10.4 //)
2005 FORMAT (8E15.6)
2006 FORMAT (I5,6E15.6)
2007 FORMAT (////////
* 60H ----- INPUT BASE ACCEL. IS LESS THAN REQUESTED RESPONSE /
* 21H EXECUTION TERMINATED /)
2008 FORMAT (/30H MOTION PLOT REQUEST FOR NODES /)
2009 FORMAT (/40H STRESS-STRAIN PLOT REQUEST FOR ELEMENTS /)
2010 FORMAT (/60H PORE PRESSURE AND EFFECTIVE STRESS PLOTS FOR ELEMENT
* :
)
2013 FORMAT (10I5)
2014 FORMAT (4(11X,4HTIME,10X,5HACCEL)//)
2015 FORMAT (15H ACCELERATION :.//)
2016 FORMAT (10H MAT. NO. ,
* 10H BULK MOD. 2X,
* 11H SHEAR MOD. ,2X,
* 15H SH. MOD. CHGE. ,
* 15H BULK MOD. (FL.) ,
* 13H PERMEABILITY ,2X,
* 17H MASS DEN. (TOTAL) ,
* 15H MASS DEN. (FL.) ,
* 8H S (MAX) )

```



2017 FORMAT (10H MAT. NO.

\* 10H 1./LAMBDA ,  
\* 4H PHI,10X,  
\* 6H ALPHA ,9X,  
\* 6H THETA ,9X,  
\* 16H RES. EFF. STRS. )  
\* 10H VOID FAT. )

END

```

SUBROUTINE MESH (DEPTH,NEL,MATYP,XLENT,MATNUM,IWTBL,WTABLE,NUMNF
* N LAYER)

```

C

```

DIMENSION DEPTH(1),NEL(1),MATYP(1),XLENT(1),MATNUM(1),IWTBL(1)

```

C

```

ZCOORD=0.0

```

```

NUM=0

```

```

DO 200 I=1,NLAYER

```

```

  NTL=NEL(I)

```

```

  IF (I.EQ.1) XL=DEPTH(I)/NTL

```

```

  IF (I.GT.1) XL=(DEPTH(I)-DEPTH(I-1))/NTL

```

```

  DO 150 J=1,NTL

```

```

    NUM=NUM+1

```

```

    ZCOORD=ZCOORD+XL

```

```

    XLENT(NUM)=XL

```

```

    MATNUM(NUM)=MATYP(I)

```

```

    IF (ZCOORD.LE.WTABLE) IWTBL(NUM)=0

```

```

    IF (ZCOORD.GT.WTABLE) IWTBL(NUM)=1

```

```

150 CONTINUE

```

```

200 CONTINUE

```

```

  RETURN

```

```

END

```

```

SUBROUTINE SELFCD (XLENT, MATNUM, IWTBL, EMATL, STRS, SLVCT, NUMNP, NC)
C
C
C
DIMENSION XLENT(1), MATNUM(1), IWTBL(1), EMATL(35,1), STRS(11,1),
* SLVCT(1)

COMMON/WLVL/WTABLE, GRAV

DEPT=0.
SYN=-1.0
DO 500 LL=1, NUMNP
ZLENT=XLENT(LL)
NUM=MATNUM(LL)
IW=IWTBL(LL)
GMA=GRAV*EMATL(14, NUM)
GMAW=GRAV*EMATL(15, NUM)
DEPT=DEPT+0.5*ZLENT
STRS2=0.5*SYN*GMA*ZLENT
IF(IW.EQ.0) GO TO 100
STRS(6, LL)=(DEPT-WTABLE)*GMAW*SYN
STRS2=STRS2+0.5*GMAW*ZLENT
100 CONTINUE
IL2=LL*NC+1
IL1=IL2-NC
SLVCT(IL1+1)=SLVCT(IL1+1)+STRS2
IF(LL.EQ.NUMNP) GO TO 150
SLVCT(IL2+1)=SLVCT(IL2+1)+STRS2
150 CONTINUE
DEPT=DEPT+0.5*ZLENT
500 CONTINUE
RETURN
END

```

SUBROUTINE MASSMT (EM,XLENT,MATNUM,IWTBL,EMATL,NUMNP,NC)

DIMENSION EM(1),XLENT(1),MATNUM(1),IWTBL(1),EMATL(35,1)

NCC=NC-1

K=0

L=NC

DO 300 LL=1,NUMNP

NUM=MATNUM(LL)

RHO=EMATL(14,NUM)

RHOF=EMATL(15,NUM)

ZLENT=XLENT(LL)

EMAS=0.5\*RHO\*ZLENT

DO 100 I=1,NC

EM(K+I)=EMAS+EM(K+I)

IF (LL.GE.NUMNP) GO TO 100

FM(I+I)=EMAS

100 CONTINUE

IF (IWTBL(LL).EQ.0) GO TO 200

EMAS=0.5\*RHOF\*ZLENT

EM(K+NC)=EMAS+EM(K+NC)

IF (LL.GE.NUMNP) GO TO 200

EM(L+NC)=EMAS

200 CONTINUE

K=L

L=L+NC

300 CONTINUE

RETURN

END

SUBROUTINE GSTIF (A,C,NC,NEQ,LFLAG)

DIMENSION A(7),C(6,6)

NCC=NC+NC  
DO 400 N=1,NC  
L=N  
DO 100 K=N,NC  
A(L)=A(L)+C(N,K)  
100 L=L+NEQ  
IF (LFLAG.EQ.0) GO TO 400  
DO 200 K=1,NC  
A(L)=-C(N,K)  
200 L=L+NEQ  
L=NC+N  
DO 300 K=N,NC  
A(L)=C(N,K)  
300 L=L+NEQ  
400 CONTINUE  
RETURN  
END

SUBROUTINE SOLVE (XLENT, MATNUM, IWTBL, EMATL, BACC, ST, DD, DI, VE, AC,  
 \* DU, EM, ELD, NBW, STRS, STRN, SLVCT, JPLTM, JPLTSS, JSETS,  
 \* PL, TLIO, AHIST, NBLK, NPTOT, NUMNP, NMAT, NEQ, NBAND, NCCY)

COMMON/CONTL/HED(18), NCYCL, DT, NDI, NPRINT, NSAVE, LUN, NC, NUPDAT, WRITE  
 \* , NSTAT, NINCR, NSTPRT  
 COMMON/PLTING/ NPLOTE, NPLTSS, NSETS, HPAP, HPLOT, RPLOT, DPLOT, EPLOT,  
 \* TFND  
 COMMON/SPEC/DV(10), NODE(10), NNODE, IRS, IRSP

DIMENSION XLENT(1), MATNUM(1), IWTBL(1), EMATL(35,1), BACC(NCCY,1),  
 \* ST(NEQ,1), DD(NEQ,1), DI(1), VE(1), AC(1), DU(1), EM(1), ELD(1), NBW(1)  
 \* STRN(11,1), STRS(11,1), C(4,4), DEPSL(6), SK(6,5), SLVCT(1),  
 \* JPLTM(1), JPLTSS(1), JSETS(1), PL(NBLK,1), TLIO(NUMNP,1),  
 \* AHIST(NCCY,1)

INTEGRATION CONSTANT

TETA=2.0  
 TAU=2.0\*DT  
 A0=6.0/(TAU\*TAU)  
 A1=6.0/TAU  
 A2=2.0  
 A3=A0/TETA  
 A4=-6.0/(TETA\*TAU)  
 A5=1.0-3.0/TETA  
 A6=DT/2.0  
 A7=DT\*DT/6.0  
 B0=3.0/TAU  
 B1=2.0  
 B2=TAU/2.0

TIME=0.0  
 NDYNST=NSTAT+1  
 NPRINT=NCCY\*NDI  
 NOB=NEQ\*NRAND  
 KPRINT=0  
 KSAVE=0  
 KUPDAT=0  
 NCVST=NCYCL+NSTAT+1  
 YINCBT=0.0  
 NFIRST=0  
 CALL SZERO (SK(1,1),36)  
 AST=0.0  
 NM=0  
 DO 40 I=1, NUMNP  
 J=NC\*(I-1)+2  
 AST=AST+SLVCT(J)  
 SLVCT(J+1)=SLVCT(J+1)+STRS(6,I)  
 SLVCT(J)=SLVCT(J)+SLVCT(J+1)  
 IF (I.NE.NUMNP) SLVCT(J+NC+1)=-STRS(6,I)  
 STRS(2,I)=AST  
 IF (MATNUM(I).EQ.NM) GO TO 20  
 NM=MATNUM(I)  
 DPT=0.0  
 GZRO=EMATL(2,NM)  
 DG=EMATL(3,NM)  
 20 CONTINUE  
 DPT=DPT+0.5\*XLENT(I)  
 G=GZRO+DG\*DPT

```

STPS (1, I) = -G / STRS (2, I)
DPT = DPT + .5 * XLENT (I)
40 CONTINUE
DO 45 I = 1, NUMNP
  TLIO (I, 1) = -1.0
45 TLIO (I, 2) = -1.0
DO 800 NCNT = 1, NCRYST
  LFLAG = 1
  KUPDAT = KUPDAT + 1
  IF (NCNT.EQ.NDYNST) KUPDAT = NUPDAT
  IF (KUPDAT.EQ.NUPDAT) CALLSZERO (ST (1, 1), NQB)
  IF (NCNT.LE.NINCR) KINCRT = KINCRT + 1.0
  NUMYLD = 1
  DO 200 LL = 1, NUMNP
    ZLENT = XLENT (LL)
    IL2 = LL * NC + 1
    IL1 = IL2 - NC
    IF (LL.EQ.NUMNP) LFLAG = 0
    IF (LFLAG.EQ.0) GO TO 50
    DEPSL (1) = 0.0
    DEPSL (2) = (DU (IL1 + 1) - DU (IL2 + 1)) / ZLENT
    DEPSL (3) = 0.0
    DEPSL (4) = (DU (IL1) - DU (IL2)) / ZLENT
    DEPSL (5) = (DU (IL1 + 2) - DU (IL2 + 2)) / ZLENT
    GO TO 60
50 CONTINUE
    DEPSL (1) = 0.0
    DEPSL (2) = DU (IL1 + 1) / ZLENT
    DEPSL (3) = 0.0
    DEPSL (4) = DU (IL1) / ZLENT
    DEPSL (5) = DU (IL1 + 2) / ZLENT
60 CONTINUE
    NM = MATNUM (LL)
    DO 100 I = 1, 4
100 STRN (I, LL) = STRN (I, LL) + DEPSL (I)
    STRN (11, LL) = STRN (11, LL) + DEPSL (5)
    IW = IWTR1 (LL)
    CALL MATPAC (STRN (1, LL), STRS (1, LL), DEPSL, C, SK, EMATL (1, NM),
    * EMATL (16, NM), TLIO, TIME, LL, NC, NFIRST, IW, NUMNP)
    IF (NCNT.LE.NDYNST) GO TO 110
    IF (IW.EQ.0) GO TO 110
    BULKF = EMATL (12, NM)
    STRS (6, LL) = STRS (6, LL) + BULKF * (DEPSL (5) + DEPSL (2))
110 CONTINUE
    ELD (IL1) = ELD (IL1) - STRS (4, LL)
    ELD (IL1 + 1) = ELD (IL1 + 1) - STRS (2, LL)
    ELD (IL1 + 1) = ELD (IL1 + 1) - STRS (6, LL)
    ELD (IL1 + 2) = ELD (IL1 + 2) - STRS (6, LL)
    IF (LFLAG.EQ.0) GO TO 120
    ELD (IL2) = ELD (IL2) + STRS (4, LL)
    ELD (IL2 + 1) = ELD (IL2 + 1) + STRS (2, LL)
    ELD (IL2 + 1) = ELD (IL2 + 1) + STRS (6, LL)
    ELD (IL2 + 2) = ELD (IL2 + 2) + STRS (6, LL)
120 CONTINUE
    IF (NCNT.EQ.1) GO TO 145
    IF (KUPDAT.NE.NUPDAT) GO TO 180
145 CONTINUE
    DO 150 I = 1, 6
    DO 150 J = 1, 6
150 SK (I, J) = SK (I, J) / ZLENT
    NPOS = NC * (LL - 1) + 1

```

```

CALL GSTIF (ST(NPOS,1),SK,NC,NEQ,LFLAG)
IF (IW.EQ.0) ST(NPOS+2,1)=1.0
IF (NCNT.LE.NSTAT) GO TO 160
PERM=EMATL(13,NM)
FAC=ZLENT/(5.0*PEBM)
NPOS=NPOS+NC-1
ST(NPOS,1)=ST(NPOS,1)+2.0*FAC*BO
IF (LFLAG.EQ.0) GO TO 160
ST(NPOS,NC+1)=ST(NPOS,NC+1)+FAC*BO
ST(NPOS+NC,1)=ST(NPOS+NC,1)+2.0*FAC*BO
160 CONTINUE
IF (NCNT.NE.NDYNST) GO TO 180
IF (IW.EQ.0) GO TO 180
DD(LL,1)=DD(LL,1)+2.0*FAC
DD(LL,2)=FAC
DD(LL+1,1)=2.0*FAC
180 CONTINUE
200 CONTINUE
IF (NCNT.LE.NDYNST) GO TO 201
IF (NFIRST.EQ.0) GO TO 201
IF (NSAVE.LE.0) GO TO 201
KSAVE=KSAVE+1
IF (KSAVE.LT.NSAVE) GO TO 201
CALL SAVE (JPLTM,JPLTSS,JSETS,PL,AC,VE,DI,STRN,STRS,
* NUMNP,NBLK,TIME,NPTOT,LUN,RACFLX,BACFLY,NDI)
KSAVE=0
201 CONTINUE
IF (KPRNT.NE.0) GO TO 205
IF (NFIRST.NE.0) GO TO 202
WRITE (6,2004)
WRITE (6,2005) (I,STRS(2,I),STRS(6,I),I=1,NUMNP)
DO 203 I=1,NUMNP
PL(I,NPTOT-1)=STRS(6,I)
203 PL(I,NPTOT)=STRS(2,I)
GO TO 205
202 CONTINUE
IF (NCNT.LT.NSTPRT) GO TO 205
WRITE (6,2006) TIME
WRITE (6,2007) (I,STRN(2,I),STRN(4,I),STRN(11,I),STRS(2,I),STRS(4
*I),STRS(6,I),I=1,NUMNP)
205 CONTINUE
NFIRST=1
NDL=0
IF (NCNT.EQ.NCYSF) GO TO 800
C
IF (KUPDAT.NE.NUPDAT) GO TO 230
210 DO 220 I=1,NEQ
220 ST(I,1)=ST(I,1)+AQ*EM(I)
230 CONTINUE
DO 250 I=1,NEQ
AA=A1*VE(I)+A2*AC(I)
250 ELD(I)=FLD(I)+EM(I)*AA+SLVCT(I)
DO 280 I=NC,NEQ,NC
L=1
AA=B1*VE(I)+B2*AC(I)
IF (L) 260,260,255
255 ELD(I-NC)=ELD(I-NC)+DD(L,2)*AA
260 L=L+1
FLD(I)=ELD(I)+DD(L,1)*AA
IF (L.EQ.NEQ) GO TO 280
FLD(I+NC)=ELD(I+NC)+DD(L,2)*AA

```





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```

2001 FORMAT (I3,9E13.4)
2002 FORMAT (I10,E20.5)
2004 FORMAT (//40H ----- INSITU STRESS CONDITION ----- /
* 3Y,7HELEMENT,5X,9HEFFECTIVE,6X,4HPORE/3X,6HNUMBER,6X,8HPRESSURE
* 7Y,8HPRESSURE//)
2005 FORMAT (5X,I5,5X,2E15.4)
2006 FORMAT (//45H ----- STRAINS AND STRESSES AT TIME ----- = ,P10.5/
* 3Y,7HELEMENT,5X,6HVOLUME,9X,5HSHEAR,10X,3HFLUID VOL,6X,
* 3HEFFECTIVE,6X,5HSHEAR,10X,4HPORE/3X,6HNUMBER,6X,5HSTRAIN,9X,
* 6HSTRAIN,9X,6HCHANGE,9X,8HPRESSURE,7X,6HSTRESS,9X,8HPRESSURE//)
2007 FORMAT (5Y,I5,5X,6E15.4)
      END

```

SUBROUTINE MATPAC (STRN,STRS,DEPSL,C,SK,EMATLA,EMATLB,TLIQ,TIME,  
 \* LL,NC,NFIRST,IW,NUMNP)

DIMENSION STRN(11),STRS(11),DEPSL(6),C(4,4),SK(6,6),EMATLA(1),  
 \* EMATLB(1),TLIQ(NUMNP,1)

BLKF=EMATLA(12)  
 BLK=EMATLA(1)  
 GZRO=STRS(10)  
 IF (NFIRST.NE.0) GO TO 100  
 GG=GZRO  
 PE=-STRS(2)  
 TAU=0.0  
 ISP=0  
 TAUP=0.0  
 PMTPP=0.0  
 PMTPN=0.0  
 PMGP=0.0  
 PMGN=0.0  
 GSHFTP=0.0  
 GSHFTN=0.0  
 EXP=PE  
 EXN=PE  
 GO TO 800

100 CONTINUE  
 SMAX=EMATLB(1)  
 ELAMDA=EMATLB(2)  
 PHI=EMATLB(3)  
 FAIL=EMATLB(4)\*TAN(PHI)  
 DGAMA=DEPSL(4)  
 PE=-STRS(2)  
 IF (TLIQ(LL,1).GT.0.0) PE=-STRS(1)  
 ISP=STRS(5)  
 PMTPP=STRS(7)  
 PMTPN=STRS(8)  
 TAUP=STRS(9)  
 GAMA=STRN(4)  
 GSHFTP=STRN(5)  
 GSHFTN=STRN(6)  
 PMGP=STRN(7)  
 PMGN=STRN(8)  
 EXP=STRN(9)  
 EXN=STRN(10)  
 TAUP=TAUP+DGAMA\*GZRO

IF (ISP) 240,180,220  
 180 IF (TAUP.LT.PMTPP) GO TO 200  
 190 CONTINUE  
 GEL=GAMA-(TAUP-PMTPP)/GZRO  
 GSHFTP=PMGP-GEL+GSHFTP  
 CALL FINDX (PE,PMTPP,ELAMDA,PHI,EXP)  
 GO TO 400  
 200 IF (TAUP.GT.PMTPN) GO TO 300  
 210 CONTINUE  
 GEL=GAMA-(TAUP-PMTPN)/GZRO  
 GSHFTN=PMGN-GEL+GSHFTN  
 CALL FINDX (PE,PMTPN,ELAMDA,PHI,EXN)  
 GO TO 500  
 220 IF (GAMA.GT.PMGP) GO TO 400  
 TAUP=PMTPP+DGAMA\*GZRO

```

      IF (TAUP.LT.PMTPN) GO TO 210
      GO TO 300
240  IF (GAMA.LT.PMGN) GO TO 500
      TAUP=PMTPN+DGAMA*GZRO
      IF (TAUP.GT.PMTRF) GO TO 190
      GO TO 300
300  CONTINUE
      ISP=0
      GG=GZRO
      GO TO 700
400  CONTINUE
      GA=GAMA+GSHFTE
      TAUP=GA*GZRO
      TAUP=(TAUP*SMAX)/(TAUP+SMAX)
      PMTRF=TAUP
      PMGP=GAMA
      ISP=2
      GG=SMAX+GA*GZRO
      GG=GZRO*SMAX*SMAX/(GG*GG)
      EX=EYP
      GO TO 600
500  CONTINUE
      GA=GAMA+GSHFTM
      TAUP=GA*GZRO
      TAUP=(TAUP*SMAX)/(SMAX-TAUP)
      PMTPN=TAUP
      PMGN=GAMA
      ISP=-2
      GG=SMAX-GA*GZRO
      GG=GZRO*SMAX*SMAX/(GG*GG)
      EX=EYN
600  CONTINUE
      ETA=ELAMDA*TAN(PHI)
      ELLAA=ELAMDA*TAUP
      ELLAA=ELLAA*ELLAA
      AA=1.0+ELLAA
      BB=ETA*ETA
      BB=BB*AA-ELLAA
      BB=ABS(BB)
      BB=1.0+BB
      AA=1.0/AA
      IF (IW.EQ.0) GO TO 700
      PE=EY*AA*BB/(1.0+ETA)
700  TAU=PE*TAUP
      IF (ABS(TAUP).LT.FAIL) GO TO 800
      IF (TLIQ(LL,1).GT.0.0) GO TO 800
      TLIQ(LL,1)=TIME
      STRS(1)=-PE
      Y=TAU/ABS(TAU)
      STRS(3)=Y*FAIL*PE
      STRS(11)=TAU
800  CONTINUE
      GG=GG*PE
      IF (TLIQ(LL,1).LE.0.0) GO TO 1000
      IF (TLIQ(LL,2).LE.0.0) GO TO 890
      PENW=-STRS(2)
      GO TO 970
890  BK=EMATLB(5)
      QT=STRS(3)
      QR=STRS(11)
      IF (QR.LT.0.0) GO TO 910

```

```

IF (TAU.GT.QR) GO TO 900
PR=EK*QT*QT/(FAIL*QR)
PENEW=TAU/FAIL+PR*(1.0-TAU/QR)
AB=TAU/PENEW
IF (ABS (AB) .LE. FAIL) GO TO 950
BETA=QT/QR
BETA=FAIL/(1.0-EK*BETA*BETA)
QF=FAIL*BETA*PR/(BETA+FAIL)
PENEW=ABS (TAU)/FAIL
QT=-QF
QR=TAU
GO TO 950
910 IF (TAU.LT.QR) GO TO 900
PR=-EK*QT*QT/(FAIL*QR)
PENEW=-TAU/FAIL+PR*(1.0-TAU/QR)
AB=TAU/PENEW
IF (ABS (AB) .LE. FAIL) GO TO 950
BETA=QT/QR
BETA=FAIL/(1.0-EK*BETA*BETA)
QF=FAIL*BETA*PR/(BETA+FAIL)
PENEW=ABS (TAU/FAIL)
QT=QF
QR=TAU
GO TO 950
920 CONTINUE
PENEW=ABS (TAU/FAIL)
QR=TAU
950 CONTINUE
CL=EMATLB (6)
IF (PENEW.GT.CL) GO TO 960
IF ((QT/FAIL) .GT. CL) GO TO 960
IF (TLIO (LL, 2) .GT. 0.0) GO TO 960
TLIO (LL, 2) =TIME
PENEW=CL
960 CONTINUE
STRS (3) =QT
STRS (11) =QR
970 CONTINUE
STRS (2) =-PENEW
STRS (1) =-PE
GO TO 1100
1000 CONTINUE
STRS (2) =-PE
1100 CONTINUE
STRS (4) =TAU
STRS (5) =ISP
STRS (7) =PMTTP
STRS (8) =PMTPN
STRS (9) =TAUP
STRN (5) =GSHFTP
STRN (6) =GSHFTM
STRN (7) =PMGP
STRN (8) =PMGN
STRN (9) =FXP
STRN (10) =EYN

IF (IW.EQ.0) BLKF=0.0
SK (1, 1) =GG
SK (1, 2) =0.0
SK (1, 3) =0.0
SK (2, 1) =0.0

```

SK (2, 2) = BLK + BLKF  
SK (2, 3) = BLKF  
SK (3, 1) = 0.0  
SK (3, 2) = BLKF  
SK (3, 3) = BLKF

C

RETURN  
END

SUBROUTINE SAVE (JPLEM,JPLTSS,JSETS,PL,AC,VE,DI,STRN,  
 \* STRS,NUMNP,NBLK,TIME,NPTOT,LUN,BACELX,BACELY,NDI)

DIMENSION JPLTM(1),JPLTSS(1),JSETS(1),PL(NBLK,  
 \* NPTOT),AC(1),VE(1),DI(1),STRN(11,1),STRS(11,1)

COMMON/PLTING/ NPLOTM,NPLTSS,NSETS,HPAP,HPLT,BPLOT,DPLOT,TEND

DATA IR/0/

IF (IR.LE.NBLK) GO TO 600  
 IR=0  
 WRITE (LUN) PL  
 N=NPTOT\*NBLK  
 CALL SZERO (PL,N)  
 600 CONTINUE  
 IC=1  
 IR=IR+1  
 PL (IR, IC) =TIME  
 IF (NPLOTM.LE.0) GO TO 120  
 DO 100 N=1,NPLOTM  
 JL=JPLTM(N)  
 JL=3\*JL-2  
 IC=IC+1  
 PL (IR, IC) =AC (JL) +BACELX  
 IC=IC+1  
 PL (IR, IC) =VE (JL)  
 IC=IC+1  
 PL (IR, IC) =DI (JL)  
 IF (NDI.LE.1) GO TO 100  
 IC=IC+1  
 PL (IR, IC) =AC (JL+1) +BACELY  
 IC=IC+1  
 PL (IR, IC) =VE (JL+1)  
 IC=IC+1  
 PL (IR, IC) =DI (JL+1)  
 100 CONTINUE  
 120 CONTINUE  
 IF (NPLTSS.LE.0) GO TO 320  
 DO 300 N=1,NPLTSS  
 JL=JPLTSS(N)  
 IC=IC+1  
 PL (IR, IC) =STRS (4, JL)  
 IC=IC+1  
 PL (IR, IC) =STRN (4, JL)  
 300 CONTINUE  
 320 CONTINUE  
 IF (NSETS.LE.0) GO TO 420  
 DO 400 N=1,NSETS  
 JL=JSETS (N)  
 PIO=PL (JL, NPTOT-1)  
 SIG=PL (JL, NPTOT)  
 IC=IC+1  
 PL (IR, IC) =+STRS (2, JL) /SIG  
 IC=IC+1  
 PL (IR, IC) =+ (STRS (6, JL) -PIO) /SIG  
 400 CONTINUE  
 420 CONTINUE  
 RETURN  
 END

```

SUBROUTINE PLTLAS (PL,JPLTM,JPLTSS,JSETS,X,Y,NBLK,NCYCL,LUN,NDI)
COMMON/PLTING/ NPLOTM,NPLTSS,NSETS,HPAP,HPLOT,BPLOT,DPLOT,EPLOT,
* TEND

```

```

DIMENSION PL(NBLK,1),JPLEM(1),JPLESS(1),JSETS(1)
DIMENSION Y(1),Y(1),DMAX(3),SCA(6,2)

```

```

SCALE DETERMINATION FOR THE MOTION DIAGRAMS

```

```

CALL LOADXY(Y,Y,1,0,PL,NBLK,NCYCL,LUN)

```

```

DO 100 I=1,NCYCL

```

```

IF (Y(I).GT.TEND) GO TO 24

```

```

N=I

```

```

100 CONTINUE

```

```

GO TO 25

```

```

24 NCYCL=N

```

```

25 CONTINUE

```

```

SCC=TEND/BPLOT

```

```

IIN=0

```

```

IF (NPLOTM.NE.0) GO TO 23

```

```

CALL PLOT(0.0,HPAP,-3)

```

```

GO TO 200

```

```

23 CONTINUE

```

```

DO 1 I=1,3

```

```

1 DMAX(I)=-9999.

```

```

N=1

```

```

DO 2 I=1,NPLOTM

```

```

DO 2 J=1,3

```

```

N=N+1

```

```

CALL LOADXY(Y,Y,N,0,PL,NBLK,NCYCL,LUN)

```

```

YMAX=-9999.

```

```

YMIN=+9999.

```

```

DO 3 K=1,NCYCL

```

```

IF (Y(K).GT.YMAX) XMAX=Y(K)

```

```

3 IF (Y(K).LT.YMIN) YMIN=Y(K)

```

```

DX=XMAX

```

```

IF (ABS(YMIN).GT.DX) DX=ABS(XMIN)

```

```

IF (DX.LE.DMAX(J)) GO TO 2

```

```

DMAX(J)=DX

```

```

2 CONTINUE

```

```

DO 4 I=1,3

```

```

4 CALL SCAL(DMAX(I),HPLOT,SCA(I,1),SCA(I,2))

```

```

PLOTTING OF THE MOTION DIAGRAMS

```

```

HGAP=(HPAP-HPLOT*3)/4.

```

```

CALL PLOT(0.0,HPAP,-3)

```

```

HTIT=HGAP/3.

```

```

N=1

```

```

DO 5 I=1,NPLOTM

```

```

DO 50 III=1,NDI

```

```

CALL PLOT(1.0,0.0,-3)

```

```

YY=-(2./3.)*HGAP

```

```

CALL SYMBOL(0.0,YY,HTIT,'NODE N. ',0.0,8)

```

```

CALL NUMBER(0.0,0.0,-HTIT,FLOAT(JPLTM(I)),0.0,-1)

```

```

IF (III.EQ.2) GO TO 110

```

```

CALL SYMBOL(0.0,0.0,-HTIT,' X-DIR.',0.0,7)

```

```

GO TO 120

```



```

110 CALL SYMBOL(0.0,0.0,-HTIT,'Y-DIR.',0.0,7)
120 CONTINUE
    ILN=ILN+1

```

C

```

    DO 10 J=1,3
    YY=-(HGAP+HPLOT)
    CALL PLOT(0.0,YY,-3)
    N=N+1
    CALL LOADXY(X,Y,1,N,PL,NBLK,NCYCL,LUN)
    X(NCYCL+1)=0.0
    X(NCYCL+2)=SCC
    Y(NCYCL+1)=SCA(J,1)
    Y(NCYCL+2)=SCA(J,2)
    CALL AXIS(0.0,0.0,'TIME (SEC)',-10,BPLOT,0.0,0.0,SCC)
    GO TO (6,7,8),J
  6 CALL AXIS(0.0,0.0,'ACC.',4,HPLOT,90.,SCA(J,1),SCA(J,2))
    GO TO 9
  7 CALL AXIS(0.0,0.0,'VPL.',4,HPLOT,90.,SCA(J,1),SCA(J,2))
    GO TO 9
  8 CALL AXIS(0.0,0.0,'DISPL.',6,HPLOT,90.,SCA(J,1),SCA(J,2))
  9 CALL PLOT(0.0,HPLOT,3)
    CALL PLOT(BPLOT,HPLOT,2)
    CALL PLOT(BPLOT,0.0,2)
    YY=HPLOT/2.
    CALL PLOT(BPLOT,YY,3)
    CALL PLOT(0.0,YY,2)
10 CALL LINE(X,Y,NCYCL,1,0,0)

```

C

```

    YY=HPAP-HGAP
    CALL PLOT(BPLOT,YY,-3)
  50 CONTINUE
    WRITE(6,2000) JPLTM(I)
  5 CONTINUE
200 CONTINUE

```

C

C

C

SCALE DETERMINATION FOR THE STRESS AND STRAIN DIAGRAMS

```

    IF(NPLTSS.EQ.0) GO TO 400
    NF=NPLTSS
    N=1+NPLTM*NDI*3
  13 DMAX(1)=-9999.
    DMAX(2)=-9999.
    DO 12 I=1,NF
    N=N+2
    CALL LOADXY(X,Y,N-1,N,PL,NBLK,NCYCL,LUN)
    XMAX=-9999.
    YMIN=9999.
    YMAX=-9999.
    YMIN=9999.
    DO 11 J=1,NCYCL
    IF(Y(J).GT.XMAX) XMAX=X(J)
    IF(Y(J).GT.YMAX) YMAX=Y(J)
    IF(Y(J).LT.XMIN) XMIN=X(J)
  11 IF(Y(J).LT.YMIN) YMIN=Y(J)
    DX=YMAX
    IF(ABS(XMIN).GT.DX) DX=ABS(XMIN)
    IF(DX.GT.DMAX(1)) DMAX(1)=DX
    DY=YMAX
    IF(ABS(YMIN).GT.DY) DY=ABS(YMIN)
    IF(DY.GT.DMAX(2)) DMAX(2)=DY
  12 CONTINUE

```

```

C
CALL SCAL(DMAX(1),HPLOT,SCA(5,1),SCA(6,2))
CALL SCAL(DMAX(2),HPLOT,SCA(5,1),SCA(5,2))
CALL SCAL(DMAX(1),DPLOT,SCA(4,1),SCA(4,2))
CALL SCAL(DMAX(2),DPLOT,SCA(3,1),SCA(3,2))
E
400 CONTINUE
C
C
C
PLOTTING OF THE STRESS AND STRAIN DIAGRAMS
C
MAYS=0
MAXP=0
IF(NPLTSS.EQ.0) GO TO 500
DO 16 I=1,NPLTSS
16 IF(JPLTSS(I).GT.MAXP) MAXP=JPLTSS(I)
500 IF(NSETS.EQ.0) GO TO 600
DO 17 I=1,NSETS
17 IF(JSETS(I).GT.MAYS) MAYS=JSETS(I)
600 IF(MAYS.EQ.0.AND.MAXP.EQ.0) GO TO 102
I=0
C
18 I=I+1
IF(I.GT.MAYS.AND.I.GT.MAXP) GO TO 102
KP=0
JS=0
IF(NSETS.EQ.0) GO TO 800
DO 19 J=1,NSETS
IF(JSETS(J).NE.I) GO TO 19
JS=JSETS(J)
GO TO 800
19 CONTINUE
800 IF(NPLTSS.EQ.0) GO TO 900
DO 20 K=1,NPLTSS
IF(JPLTSS(K).NE.I) GO TO 20
KP=JPLTSS(K)
GO TO 900
20 CONTINUE
900 IF(KP.EQ.0.AND.JS.EQ.0) GO TO 18
C
ILN=ILN+1
IF(KP.EQ.0) GO TO 101
CALL PLOT(1.0,0.0,-3)
HGAP=(HPAP-HPLOT*2.)/3.
HTIT=HGAP/3.
YY=-2.*HTIT
CALL SYMBOL(0.0,YY,HTIT,'ELEM. N. ',0.0,9)
DY=FLOAT(KP)
CALL NUMBER(0.0,0.0,-HTIT,DX,0.0,-1)
C
N=NPLOTM*NDI*3+K*2
DO 21 L=1,2
YY=-(HGAP+HPLOT)
CALL PLOT(0.0,YY,-3)
N=N+L-1
CALL LOADY(X,Y,1,N,PL,NBLK,NCYCL,LUN)
Y(NCYCL+1)=SCA(6-L+1,1)
Y(NCYCL+2)=SCA(6-L+1,2)
X(NCYCL+1)=0.0
Y(NCYCL+2)=SCC
CALL AYIS(0.0,0.0,'TIME (SEC)',-10,BPLOT,0.0,0.0,SCC)
IF(L.EQ.1) CALL AXIS(0.0,0.0,'SH. STRESS',10,HPLOT,90.,SCA(6,1),

```

```

*   SCA(6,2)
IF(L.EQ.2) CALL AXIS(0.0,0.0,'SH. STRAIN',10,HPLOT,90.,SCA(5,1),
*   SCA(5,2))
CALL PLOT(0.0,HPLOT,3)
CALL PLOT(BPLOT,HPLOT,2)
CALL PLOT(BPLOT,0.0,2)
YY=HPLOT/2.
CALL PLOT(BPLOT,YY,3)
CALL PLOT(0.0,YY,2)
21 CALL LINE(X,Y,NCYCL,1,0,0)

C
YY=HGAP
HGAP=(HPAP-DPLOT)/2.
YY=HGAP-YY
CALL PLOT(BPLOT+1,YY,-3)
N=NPLOTM*NDI*3+K*2
CALL LOADYY(X,Y,N+1,N,PL,NBLK,NCYCL,LUN)
Y(NCYCL+1)=SCA(3,1)
X(NCYCL+2)=SCA(3,2)
Y(NCYCL+1)=SCA(4,1)
Y(NCYCL+2)=SCA(4,2)
CALL AXIS(0.0,0.0,'SH. STRAIN',-10,DPLOT,0.0,SCA(3,1),SCA(3,2))
CALL AXIS(0.0,0.0,'SH. STRESS',10,DPLOT,90.,SCA(4,1),SCA(4,2))
CALL PLOT(0.0,DPLOT,3)
CALL PLOT(DPLOT,DPLOT,2)
CALL PLOT(DPLOT,0.0,2)
YY=DPLOT/2.
CALL PLOT(DPLOT,YY,3)
CALL PLOT(0.0,YY,2)
CALL PLOT(YY,DPLOT,3)
CALL PLOT(YY,0.0,2)
CALL LINE(X,Y,NCYCL,1,0,0)
YY=HPAP-HGAP
CALL PLOT(DPLOT,YY,-3)
IF(JS.EQ.0) WRITE(6,3000) KP
101 IF(JS.EQ.0) GO TO 18
CALL PLOT(1.0,0.0,-3)
HGAP=(HPAP-EPLLOT)/2.
IF(KP.NE.0) GO TO 300
HTIT=HGAP/3.
YY=-2.*HTIT
CALL SYMBOL(0.0,YY,HTIT,'ELEM. N. ',0.0,9)
DX=FLOAT(JS)
CALL NUMBER(0.0,0.0,-HTIT,DX,0.0,-1)
300 YY=- (HGAP+EPLLOT)
CALL PLOT(0.0,YY,-3)
DX=1./EPLLOT
CALL AXIS(0.0,0.0,'TIME (SEC) ',-10,BPLOT,0.0,0.0,SCC)
CALL AXIS(0.0,0.0,'EFF. STRESS AND PORE PRESS.',27,EPLLOT,90.,0.0,
*   DX)
CALL PLOT(0.0,EPLLOT,3)
CALL PLOT(BPLOT,EPLLOT,2)
CALL PLOT(BPLOT,0.0,2)
N=NPLOTM*NDI*3+NPLTSS*2+J*2
DO 22 L=1,2
N=N+L-1
CALL LOADXY(X,Y,1,N,PL,NBLK,NCYCL,LUN)
Y(NCYCL+1)=0.0
Y(NCYCL+2)=DX
Y(NCYCL+1)=0.0
X(NCYCL+2)=SCC

```

```
22 CALL LINE(X,Y,NCYCL,1,0,0)
   YY=HPAP-HGAP
   CALL PLOT(BPLOT,YY,-3)
   WRITE(6,3000) JS
   GO TO 18
C
102 WRITE(6,1000) ILN
   YY=-HPAP
   CALL PLOT(BPLOT,YY,-3)
   RETURN
C
1000 FORMAT(//,I5,' SETS OF PLOTS COMPLETED')
2000 FORMAT(//,' PLOTS FOR NODE NO.',I4,' COMPLETED')
3000 FORMAT(//,' PLOTS FOR ELEM. NO.',I4,' COMPLETED')
END
```

```

SUBROUTINE OUIP (JPLTM,JPLTSS,JSETS,X,Y,PL,TLIQ,NUMNP,LUN,
* NBLK,NPTOT,NCYCL,NDI)
C
DIMENSION JPLTM(1),JPLTSS(1),JSETS(1),X(1),Y(1),PL(NBLK,NPTOT),
* TLIQ(NUMNP,1)
C
COMMON/PLTING/ NPLOTM,NPLTSS,NSETS,HPAP,HPLT,BPLOT,DPLOT,EPLT,
* TEND
C
WRITE (6,2002)
DO 100 I=1,NUMNP
  TT=TLIQ(I,1)
  IF(TT.GT.0.0) GO TO 40
  WRITE(6,2003) I
  GO TO 100
40  TTT=TLIQ(I,2)
  IF(TTT.GT.0.0) GO TO 50
  WRITE(6,2018) I,TT
  GO TO 100
50  CONTINUE
  WRITE(6,2004) I,TT,TTT
100  CONTINUE
  NT=NBLK
  N=1
  NN=NPLOTM+NPLTSS+NSETS
  IF(NN.LE.0) GO TO 600
  IF (NPLOTM.EQ.0) GO TO 200
  DO 150 I=1,NPLOTM
  DO 140 K=1,NDI
  N=N+1
  IF(K.EQ.2) GO TO 141
  WRITE(6,2005) JPLTM(I)
  GO TO 142
141  WRITE(6,2015) JPLTM(I)
142  WRITE (6,2001) (PL(J,N),J=1,NT)
143  CONTINUE
  DO 147 K=1,NDI
  N=N+1
  IF(K.EQ.2) GO TO 143
  WRITE (6,2006) JPLTM(I)
  GO TO 144
143  WRITE(6,2016) JPLTM(I)
144  WRITE (6,2001) (PL(J,N),J=1,NT)
147  CONTINUE
  DO 148 K=1,NDI
  N=N+1
  IF(K.EQ.2) GO TO 145
  WRITE (6,2007) JPLTM(I)
  GO TO 146
145  WRITE(6,2017) JPLTM(I)
146  WRITE (6,2001) (PL(J,N),J=1,NT)
148  CONTINUE
150  CONTINUE
200  CONTINUE
  IF (NPLTSS.EQ.0) GO TO 400
  DO 350 I=1,NPLTSS
  N=N+1
  WRITE (6,2010) JPLTSS(I)
  WRITE (6,2001) (PL(J,N),J=1,NT)
  N=N+1

```

```

WRITE (6,2009) JPLTSS(I)
WRITE (6,2001) (PL(J,N),J=1,NT)
350 CONTINUE
400 CONTINUE
IF (NSETS.EQ.0) GO TO 500
DO 450 I=1,NSETS
N=N+1
WRITE (6,2011) JSETS(I)
WRITE (6,2001) (PL(J,N),J=1,NT)
N=N+1
WRITE (6,2012) JSETS(I)
WRITE (6,2001) (PL(J,N),J=1,NT)
450 CONTINUE
500 CONTINUE
CALL PULFAS (PL,JPLEM,JPLTSS,JSETS,Y,Y,NBLK,NCYCL,LUN,NDI)
600 RETURN
2001 FORMAT (10F12.4)
2002 FORMAT (//30H ELEMENT LIQUEFACTION DATA //10H EL. NO. /)
2003 FORMAT (3X,I5,5X,25H NO LIQUEFACTION )
2004 FORMAT (3X,I5,5X,26H INITIAL LIQUEF. AT TIME = ,F10.4,18H LIQUEF
* AT TIME = ,F10.4)
2005 FORMAT (// 45H ----- ACCELERATION TIME HISTORY FOR NODE NO ,I4,
* 12H Y-DIRECTION /)
2006 FORMAT (// 45H ----- VELOCITY TIME HISTORY FOR NODE NO ,I4,
* 12H Y-DIRECTION /)
2007 FORMAT (// 45H ----- DISPLACEMENT TIME HISTORY FOR NODE NO ,I4,
* 12H X-DIRECTION /)
2009 FORMAT (// 45H ----- SHEAR STRAIN TIME HISTORY FOR ELEM NO ,I4 /)
2010 FORMAT (// 45H ----- SHEAR STRESS TIME HISTORY FOR ELEM NO ,I4 /)
2011 FORMAT (// 50H ----- EFFECTIVE STRESS TIME HISTORY FOR ELEM NO. ,
* I4 /)
2012 FORMAT (// 45H ----- PORE PRESSURE TIME HISTORY FOR ELEM NO ,I4 /)
2015 FORMAT (// 45H ----- ACCELERATION TIME HISTORY FOR NODE NO ,I4,
* 12H Y-DIRECTION /)
2016 FORMAT (// 45H ----- VELOCITY TIME HISTORY FOR NODE NO ,I4,
* 12H Y-DIRECTION /)
2017 FORMAT (// 45H ----- DISPLACEMENT TIME HISTORY FOR NODE NO ,I4,
* 12H Y-DIRECTION /)
2018 FORMAT (3X,I5,5X,26H INITIAL LIQUEF. AT TIME = ,F10.4,
* 18H NO FINAL LIQUEF. )
END

```

```

SUBROUTINE RESPEC (ACC, NP, R1, R2, R3, R4, NDV, DT)
  DIMENSION R1(130, NDV), R2(130, NDV), R3(130, NDV), R4(1, ACC(NP, 1)),
  * DW(5), NM(5), SDISP(10), SVP(10), SACC(10), SI(10), SAMAX(10)

  COMMON/SPEC/DV(10), NODE(10), NNODE, IRS, IRSP
  COMMON/WLVL/ WTABLE, GRAV

  DATA DW(1)/.05/, DW(2)/.01/, DW(3)/.05/, DW(4)/.1/, DW(5)/.2/
  DATA NM(1)/2/, NM(2)/80/, NM(3)/21/, NM(4)/20/, NM(5)/5/

  THIS SUBROUTINE COMPUTES RESPONSE SPECTRA BY
  SIMPSON'S RULE FOR PERIODS .1 TO 5.0 SECONDS

  SORT THE GIVEN DAMPING VALUES IN INCREASING ORDER

  INDV=NDV-1
  DO 100 IK=1, INDV
  IP=IK+1
  DO 100 IJ=IP, NDV
  IF (DV(IK) .LE. DV(IJ)) GO TO 100
  TDV=DV(IK)
  DV(IK)=DV(IJ)
  DV(IJ)=TDV
100 CONTINUE

  COMPUTE SPECTRAL VALUES

190 DO 160 K=1, NNODE
  NNOD=NODE(K)
200 WRITE(6, 2002) NODE(K)
  WRITE(6, 2000)
  IND=0
  PERIO=0.05
  DO 150 L=1, 5
  M=VM(L)
  DO 150 LOOP=1, M
  IND=IND+1
  PERIO=PERIO+DW(L)
  W=6.2831853/PERIO
  DO 140 J=1, NDV
  SVP(J)=0.0
  TIME=0.0
110 AMULT=EXP(-2.0*DV(J)*W*DT)
  BMULT=4.0*EXP(-DV(J)*W*DT)
  W=SQRT(1-DV(J)*DV(J))*W
  WT=TIME*W
  A11=COS(WT)*ACC(1, K)
  B11=SIN(WT)*ACC(1, K)
  AA=0.0
  BB=0.0
  DO 130 N=2, NP, 2
  A21=AA+A11
  B21=BB+B11
  A31=AMULT*A21
  B31=BMULT*B21
  SV=(AA*SIN(WT)-BB*COS(WT))*(DT/3.0)
  IF (ABS(SV) .GT. SVP(J)) SVP(J)=ABS(SV)

```

```

TIME=TIME+DT
WT=W*TIME
A12=COS(WT)*ACC(N,K)
A32=A12*BMULT
B12=SIN(WT)*ACC(N,K)
B32=B12*BMULT
TIME=TIME+DT
WT=W*TIME
120 I=1+N
A11=COS(WT)*ACC(I,K)
B11=SIN(WT)*ACC(I,K)
AA=A31+B32+A11
BB=B31+B32+B11
130 CONTINUE
SACC(J)=SVP(J)*W/GRAV
SDISP(J)=SVP(J)/W
R1(IND,J)=SDISP(J)
R2(IND,J)=SVP(J)
R3(IND,J)=SACC(J)
R4(IND)=PERIO
140 CONTINUE
WRITE(6,2001) PERIO,(DV(J),SDISP(J),SVP(J),SACC(J),J=1,NDV)
150 CONTINUE
C
C
C
COMPUTE SPECTRUM INTENSITIES
DO 155 J=1,NDV
SI(J)=0.0
DO 155 IN=1,127
IN=INT
SI(J)=(R2(IN,J)+R2(IN+1,J))/2*(R4(IN+1)-R4(IN))+SI(J)
155 CONTINUE
C
C
C
AMAX=0.0
DO 157 M=1,NP
157 IF(ABS(ACC(M,K)).GT.ABS(AMAX)) AMAX=ACC(M,K)
WRITE(6,2004) AMAX
C
C
C
FIND MAXIMUMS OF SPECTRAL VALUES
DO 156 N=1,NDV
SAMAX(N)=0.0
DO 156 M=1,IND
156 IF(R3(M,N).GT.SAMAX(N)) SAMAX(N)=R3(M,N)
WRITE(6,2005) (DV(J),SAMAX(J),J=1,NDV)
WRITE(6,2003) (DV(J),SI(J),J=1,NDV)
IF(IPSP.LE.0) GO TO 160
C
C
C
PLOT RESPONSE SPECTRA IF REQUESTED
CALL PLORES(NNOD,IND,R1,R2,R3,R4,NDV)
160 CONTINUE
RETURN
2000 FORMAT(27X,11H DAMP. RAT.,7X,11H SPEC. DIS.,9X,11H SPEC. VEL.,10X
* 20H SPEC. ACC.(/GRAV.) )
2001 FORMAT(8H PERIOD=,F8.5/(27X,F10.5,3X,3(E15.6,5X)))
2002 FORMAT(37X,31H ***RESPONSE SPECTRA OF NODE N.,I5,4H ***//)
2003 FORMAT(//,35H * RESPONSE SPECTRUM INTENSITIES * ,/6X,11H DAMP. R
*T.,5X,11H SPEC. INT./ (4X,F10.5,3X,E15.6))
2004 FORMAT(/20 H MAX. ACCELERATION= ,E15.6)
2005 FORMAT(/11H DAMP. RAT.,5X,25H MAX. SPEC. ACCELERATION / (3X,F10.5,

```



```

SUBROUTINE PLORES (NNOD,IND,R1,R2,R3,R4,NDV)
C
C
DIMENSION R1 (130,1),R2 (130,1),R3 (130,1),R4 (1)

CALL SYMBOL (1.0,8.3,0.5,'RESPONSE SPECTRA',0.0,16)
CALL SYMBOL (1.0,7.3,0.5,'NODE N.',0.0,7)
CALL NUMBER (4.5,7.3,0.5,FLOAT (NNOD),0.0,-1)
R1MAX=0.0
R2MAX=0.0
R3MAX=0.0
DO 100 K=1,IND
IF (R1 (K,1) .GT. R1MAX) R1MAX=R1 (K,1)
IF (R2 (K,1) .GT. R2MAX) R2MAX=R2 (K,1)
IF (R3 (K,1) .GT. R3MAX) R3MAX=R3 (K,1)
100 CONTINUE
IS1=R1MAX*1.05
IS2=R2MAX*1.05
IS3=R3MAX*1.05
YINC1=IS1/4.0
YINC2=IS2/4.0
YINC3=IS3/4.0
DO 350 J=1,NDV
R1 (IND+1,J)=0.0
R1 (IND+2,J)=YINC1
R2 (IND+1,J)=0.0
R2 (IND+2,J)=YINC2
R3 (IND+1,J)=0.0
R3 (IND+2,J)=YINC3
350 CONTINUE
R4 (IND+1)=0.0
R4 (IND+2)=1.0
DO 400 LOOP=1,3
CALL PLOT (1.0,2.3,-3)
CALL AXIS (0.0,0.0,'PERIOD (SEC)',-12,5.0,0.0,0.0,1.0)
IF (LOOP.EQ.1) CALL AXIS (0.0,0.0,'SPEC. DISP.',11,4.0,90.0,0.0,YINC
* )
IF (LOOP.EQ.2) CALL AXIS (0.0,0.0,'SPEC. VEL.',11,4.0,90.0,0.0,
* YINC2)
IF (LOOP.EQ.3) CALL AXIS (0.0,0.0,'SPEC. ACC.',11,4.0,90.0,0.0,
* YINC3)
CALL PLOT (0.0,4.0,3)
CALL PLOT (5.0,4.0,2)
CALL PLOT (5.0,0.0,2)
DO 500 J=1,NDV
IF (LOOP.EQ.1) CALL LINE (R4,R1 (1,J),128,1,0,0)
IF (LOOP.EQ.2) CALL LINE (R4,R2 (1,J),128,1,0,0)
IF (LOOP.EQ.3) CALL LINE (R4,R3 (1,J),128,1,0,0)
500 CONTINUE
CALL PLOT (5.0,-2.3,-3)
400 CONTINUE
RETURN
END

```

```

SUBROUTINE SOLPEQ (EMATL,XLENT,MATNUM,IWTBL,STRS,A,B,C,D,E,PPO,
* PI,MB,PPE,NUM)

```

```

COMMON/WLVL/ WTABLE,GRAV
COMMON/POSEQ/NTRP(10),DT(10),TLIMIT,NIS,NPEQPR(10)

```

```

DIMENSION EMATL(35,1),MATNUM(1),IWTBL(1),XLENT(1),A(NUM,1),
* B(NUM,1),C(NUM,1),D(NUM,1),E(1),PPO(1),PI(1),MB(1)
* ,PPE(1),STRS(11,1)

```

```

WRITE(6,2000)
DO 850 I=1,NUM
PPE(I)=-STRS(6,I)
850 CONTINUE
TLIMIT=0.0
DO 800 I=1,NTS
M=NTRP(I)
DO 800 J=1,M
TLIMIT=TLIMIT+DT(I)
800 CONTINUE
GMAW=EMATL(15,1)*GRAV
TIME=0.0
WTCH=0.0
SETEL=0.0
KONTR=1
KOUNT=0
DO 500 J=1,2
DO 500 I=1,NUM
A(I,J)=0.0
B(I,J)=0.0
500 CONTINUE
DO 550 I=1,NUM
C(I,1)=1.0
C(I,2)=0.0
D(I,1)=1.0
D(I,2)=0.0
E(I)=0.0
550 CONTINUE
CALL MATAB (A,B,NDRY,NSEL,EMATL,XLENT,MATNUM,IWTBL,NUM)
NDRY=NDRY

```

```

CALCULATE HYDROSTATIC WATER PRESSURES

```

```

DEPT=0.0
DO 100 I=1,NUM
PPO(I)=0.0
MI=MATNUM(I)
DEPT=DEPT+0.5*XLENT(I)
IF(IWTBL(I).EQ.0) GO TO 95
PPO(I)=(DEPT-WTABLE)*EMATL(15,MI)*GRAV
95 DEPT=DEPT+0.5*XLENT(I)
100 CONTINUE

```

```

CALCULATE EXCESS PORE PRESSURE AFTER EQ

```

```

DO 90 I=1,NSEL
PI(I)=PPE(NDRY+I)-PPO(NDRY+I)
90 CONTINUE
WRITE(6,2010)
IF(NDRY.EQ.0) GO TO 120

```

```

DO 110 I=1,NDRY
WRITE(6,2011) I,PPO(I),PPE(I)
110 CONTINUE
120 I1=NDRY+1
DO 130 I=I1,NUM
WRITE(6,2012) I,PPO(I),PPE(I),PI(I-NDRY)
130 CONTINUE

C
C   CALCULATE EXCESS PORE PRESSURE DISSIPATION
C

WRITE(6,2008) TLIMIT
DO 400 I=1,NTS
M=NTREP(I)
DO 400 J=1,M
NSEL=NUM-NDRY
DO 200 K=1,2
DO 200 L=1,NSEL
C(L,K)=A(L,K)/2.+B(L,K)/DT(I)
D(L,K)=P(L,K)/DT(I)-A(L,K)/2.0
200 CONTINUE
NSE=NSEL-1
E(1)=D(1,1)*PI(1)+D(1,2)*PI(2)
DO 210 K=2,NSE
E(K)=D(K,1)*PI(K)+D(K,2)*PI(K+1)+D(K-1,2)*PI(K-1)
210 CONTINUE
E(NSEL)=D(NSEL,1)*PI(NSEL)+D(NSEL-1,2)*PI(NSEL-1)
CALL TRIA(C,MB,NUM,2)
CALL BACKS(C,E,MB,NUM,2)
TIME=TIME+DT(I)

C
C   CALCULATE SETTLEMENT
C

DO 230 K=1,NSEL
M1=MATNUM(NDRY+K)
SETTL=SETTL+XLENT(NDRY+K)/EMATL(1,M1)*(PI(K)-E(K))
230 CONTINUE

C
C   CALCULATE WATER TABLE RISE
C

M1=MATNUM(NDRY+1)
DWTCH=DT(I)*EMATL(13,M1)*P(1)/XLENT(NDRY+1)/EMATL(22,M1)
WTCH=WTCH+DWTCH
WTABLE=WTABLE-DWTCH
DO 220 K=1,NSEL
PI(K)=E(K)
220 CONTINUE
KOUNT=KOUNT+1
IF(KOUNT.LT.NPEQPR(I)) GO TO 261
KOUNT=0
WRITE(6,2001) TIME,SETTL,WTABLE
WRITE(6,2002)
IF(NDRY.EQ.0) GO TO 257
Z=0.0
DO 250 K=1,NDRY
250 WRITE(6,2003) K,Z
257 IF(NDRY.EQ.MDRY) GO TO 256
DO 255 K=NDRY,MDRY
IND=K+1
WRITE(6,2003) IND,E(IND-NDRY)
255 CONTINUE
256 K1=NDRY+1

```

```

TDSPP=0.0
TYLENT=0.0
DO 260 K=K1,NUM
DSPP=1.0-E(K-NDRY)/(PPE(K)-PPO(K))
TDSPP=XLENT(K)*DSPP+TDSPP
TYLENT=TYLENT+XLENT(K)
WRITE(6,2004) K, E(K-NDRY),DSPP
260 CONTINUE
ODSPP=TDSPP/TYLENT
WRITE(6,2009) ODSPP
261 CONTINUE
IF(NDRY.EQ.0) GO TO 400
IF(KONTR.NE.1) GO TO 900
IF(WTCH.LT.XDUM) GO TO 950
WTCH=WTCH-XDUM
XLENT(NDRY)=XDUM
KONTR=2
CALL MATAB(A,B,NDRY,NSEL,EMATL,XLENT,MATNUM,IWTBL,NUM)
GO TO 950
900 WTCR=WTCH/XLENT(NDRY)
IF(WTCR.LT.2.5) GO TO 950
XDUM=XLENT(NDRY)
XLENT(NDRY)=WTCH
IWTBL(NDRY)=1
CALL MATAB(A,B,NDRY,NSEL,EMATL,XLENT,MATNUM,IWTBL,NUM)
KONTR=1
NSE=NSEL-1
DO 295 K=1,NSE
PI(K+1)=E(K)
295 CONTINUE
PI(1)=WTCH*GMAW/2.
GO TO 400
950 IF(NDRY.EQ.0) GO TO 951
M0=MATNUM(NDRY)
951 M1=MATNUM(NDRY+1)
M2=MATNUM(NDRY+2)
AEMAT=(EMATL(1,M0)*WTCH+EMATL(1,M1)*XLENT(NDRY+1))/(WTCH+
*XLENT(NDRY+1))
A(1,1)=EMATL(1,M2)/XLENT(NDRY+2)+AEMAT/(WTCH+XLENT(NDRY+1))
B(1,1)=B(1,1)+DWTCH/EMATL(1,M0)/3.
400 CONTINUE
RETURN
2000 FORMAT(1H1,37Y,35H *** POST-EARTHQUAKE ANALYSIS *** //)
2001 FORMAT(// 15H -----TIME----- ,F10.5/
* 12H SETTLEMENT= ,F10.5/
* 20H WATER TABLE DEPTH= ,F10.5//)
2002 FORMAT(3Y,12H NODE N. ,5X11H EXCESS PP. ,5Y,14H DISSIP. RAT.
2003 FORMAT(5X,15,5X,F15.6,5X,10H UNDEFINED )
2004 FORMAT(5X,15,5X,F15.6,5X,F10.5)
2008 FORMAT(5X,37H TOTAL TIME FOR DISSIPATION ANALYSIS= ,F10.5)
2009 FORMAT(3Y,28H OVERALL DISSIPATION RATIO= ,F10.5)
2010 FORMAT(30Y,15H PORE PRESSURES /
* 8H NODE N. ,
* 7Y,8H IN SITU ,
* 9Y,10H AFTER EQ. ,
* 7Y,7H EXCESS )
2011 FORMAT(2Y,15,3Y,F15.6,3X,F15.6,10H (0.0 )
2012 FORMAT(2Y,15,3Y,F15.6,3X,F15.6,3X,F15.6)
END

```

SUBROUTINE MATAB (AM,BM,NDRY,NSEL,EMATL,XLENT,MATNUM,IWTBL,NUM)

C

```

DIMENSION AM(NUM,1),BM(NUM,1),EMATL(35,1),XLENT(1),MATNUM(1),
* IWTBL(1)
NSEL=0
DO 100 I=1,NUM
IF(IWTBL(I).LE.0) GO TO 100
NSEL=NSEL+1
MN=MATNUM(I)
AM(NSEL,1)=EMATL(1,MN)/XLENT(I)
BM(NSEL,1)=XLENT(I)/EMATL(13,MN)/3.
100 CONTINUE
N=NSEL-1
DO 200 K=1,N
AM(K,1)=AM(K,1)+AM(K+1,1)
AM(K,2)=-AM(K+1,1)
BM(K,1)=BM(K,1)+BM(K+1,1)
BM(K,2)=BM(K+1,1)/2.
200 CONTINUE
AM(NSEL,2)=0.0
BM(NSEL,2)=0.0
NDRY=NUM-NSEL
RETURN
END

```

```
SUBROUTINE SZERO (A,NTLLL)
```

```
C  
C  
DIMENSION A(NTLLL)
```

```
DO 100 I=1,NTLLL
```

```
100 A(I)=0.0
```

```
RETURN
```

```
END
```

```

SUBROUTINE TRIA (A,MB,NEQ,M)
C
DIMENSION A(1),MB(1)
C
NE=NEQ-1
MN=M-1
MM=MN*NEQ
MK=NEQ-MN
DO 300 N=1,NE
NT=N-MK
IF (NT.GT.0) MM=MM-NEQ
MB(N)=0
IF (A(N).EQ.0.0) GO TO 300
L=N
IL=N+NEQ
IH=N+MM
JB=0
IB=0
DO 200 I=IL,IH,NEQ
L=L+1
J=L
IB=IB+1
C=A(I)/A(N)
IF (C.EQ.0.0) GO TO 200
DO 100 K=I,IH,NEQ
A(J)=A(J)-C*A(K)
100 J=J+NEQ
A(I)=C
JB=IB
200 CONTINUE
MB(N)=JB
300 CONTINUE
MB(NEQ)=0
RETURN
END

```

```

SUBROUTINE BACKS (A,B,MB,NN,MM)
C
DIMENSION A(1),B(1),MB(1)
C
MMM=MM-1
N=0
270 N=N+1
C=B(N)
IF (A(N).NE.0.0) B(N)=B(N)/A(N)
IF (N.EQ.NN) GO TO 300
IL=N+1
IH=N+MB(N)
M=N
DO 285 I=IL,IH
M=M+NN
285 B(I)=B(I)-A(M)*C
GO TO 270
C
300 IL=N
N=N-1
IF (N.EQ.0) RETURN
IH=N+MB(N)
M=N
C=B(N)
DO 400 I=IL,IH
M=M+NN
400 C=C-A(M)*B(I)
B(N)=C
GO TO 300
C
END

```



C  
SUBROUTINE FINDX (PE,A,ELAMDA,PHI,EX)

```
ETA=ELAMDA*TAN (PHI)
EX=ELAMDA*A
FY=EX*EX
EX=ETA*ETA*(1.0+EX)-EX
FY=1.0-SQRT (EX)
EX=PE*FY/(1.0-ETA)
RETURN
END
```

SUBROUTINE SCAL(CX,DIST,SCA1,SCA2)

C  
DX=CX\*2.  
A=10.E+11  
DO 1 I=1,20  
A=A/10.  
B=1/10.  
IF(DY,LT,A.AND,DX,GE,B) GO TO 2  
1 CONTINUE  
SCA1=-DX/2.  
SCA2=DX/DIST  
RETURN  
2 ID=INT((DX/B)+0.99)  
SCA1=- (FLOAT(ID)/2.)\*B  
SCA2=-2.\*SCA1/DIST  
RETURN  
END

```
SUBROUTINE LOADXY(X,Y,IX,IY,PL,NBLK,NCYCL,LUN)
```

```
DIMENSION X(1),Y(1),PL(NBLK,1)
```

```
NB=NCYCL/NBLK
```

```
IF(NB.LT.1) NB=1
```

```
IF(NCYCL.LE.NBLK) GO TO 4
```

```
REWIND LUN
```

```
4 N=-NBLK
```

```
DO 1 I=1,NB
```

```
N=N+NBLK
```

```
IF(NCYCL.GT.NBLK) READ(LUN) PL
```

```
IF(IX.EQ.0) GO TO 3
```

```
DO 2 J=1,NBLK
```

```
2 Y(J+N)=PL(J,IX)
```

```
3 IF(IY.EQ.0) GO TO 1
```

```
DO 5 J=1,NBLK
```

```
6 Y(J+N)=PL(J,IY)
```

```
1 CONTINUE
```

```
IF(NCYCL.LE.NBLK) RETURN
```

```
READ(LUN) PL
```

```
N=NB*NBLK
```

```
NB=NCYCL-N
```

```
N=N+1
```

```
IF(IY.EQ.0) GO TO 8
```

```
DO 7 J=1,NB
```

```
7 X(N+J)=PL(J,IX)
```

```
8 IF(IY.EQ.0) RETURN
```

```
DO 9 J=1,NB
```

```
9 Y(N+J)=PL(J,IY)
```

```
RETURN
```

```
END
```



APPENDIX - III

EXAMPLE INPUT AND OUTPUT



EXAMPLE INPUT

100 FT LAYER, EXAMPLE PROBLEM

1 1 1000 1 0.01  
 400 5 100 1

1 5  
 0.1 5 5  
 0.5 5 5  
 5.0 12 12  
 10.0 50 50  
 60.0 50 50

60.  
 1200. 20 1  
 8000. 2000. 5.0 10000000. 0.108 0.0001873 .0000974 1.0  
 0.9 .7854 0.95 0.05 0.1 0.5

HORIZONTAL BASE ACCELERATION, EL CENTRO

1.0 1.0 1008 1  
 (EARTHQUAKE DATA CODED BY 8F9.0 FORMAT, 126 CARDS)

EXAMPLE OUTPUT

100 FT LAYER, EXAMPLE PROBLEM

NUMBER OF LAYERS ..... = 1  
 NUMBER OF MATERIALS ..... = 1  
 NUMBER OF CYCLES ..... = 1000  
 NUMBER OF INPUT DIRECTIONS .. = 1  
 TIME STEP (DT) ..... = 0.1000E-01  
 PRINT INTERVAL ..... = 400  
 INTERVAL FOR SAVING RESPONSE = 5  
 STEP FOR STARTING PRINT .... = 100  
 STIFFNESS UPDAT CYCLE ..... = 1  
 OUTPUT TAPE FLAG ..... = 0

...DATA FOR POST EARTHQUAKE ANALYSIS...

TIME STEPS	NO. REP.	PRINT INT.
0.10000	5	5
0.50000	5	12
5.00000	12	50
10.00000	50	50
60.00000	50	

DEPTH OF WATER TABLE ..... = 60.000  
 GRAVITY ..... = 386.200



----- PROPERTIES OF LAYERS -----

LAYER NUMBER	DEPTH	NUMBER OF ELEMENTS	MATERIAL NUMBER
1	1200.000	20	1

----- MATERIAL PROPERTIES -----

MAT. NO.	BULK MOD.	SHEAR MOD.	SH. MOD. CHGE.	BULK MOD. (PL.)	PERMEABILITY	MASS DEN. (TOTAL)	MASS DEN. (PL.)	S (MAX)
1	0.800000E 04	0.200000E 04	0.500000E 01	0.100000E 08	0.108000E 00	0.187300E-03	0.974000E-04	0.100000E 01
MAT. NO.	1./LAMBDA	PHI	ALPHA	THETA	RES. EFF. STRS.	VOID RAT.		
1	0.900000E 00	0.785400E 00	0.950000E 00	0.500000E-01	0.100000E 00	0.500000E 00		







----- RESPONSE AT TIME ----- = 3.99978

N	DX	DY	DW	VX	VY	VW	AX	AY	AW
1	0.694E-02	0.000E-00	0.260E-02	0.178E-02	0.202E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
2	0.677E-02	0.000E-00	0.229E-02	0.159E-02	0.165E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
3	0.719E-02	0.000E-00	0.174E-02	0.158E-02	0.154E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
4	0.155E-01	0.000E-00	0.644E-02	0.127E-02	0.130E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
5	0.108E-01	0.000E-00	0.504E-02	0.123E-02	0.128E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
6	0.949E-01	0.000E-00	0.805E-02	0.113E-02	0.108E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
7	0.842E-01	0.000E-00	0.643E-02	0.109E-02	0.102E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
8	0.525E-01	0.000E-00	0.494E-02	0.889E-03	0.159E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
9	0.432E-01	0.000E-00	0.491E-02	0.758E-03	0.152E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
10	0.522E-01	0.000E-00	0.334E-02	0.534E-03	0.149E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
11	0.321E-01	0.000E-00	0.409E-02	0.449E-03	0.152E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
12	0.257E-01	0.000E-00	0.492E-02	0.390E-03	0.148E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
13	0.174E-01	0.000E-00	0.259E-02	0.341E-03	0.148E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
14	0.119E-01	0.000E-00	0.166E-02	0.254E-03	0.145E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
15	0.731E-01	0.000E-00	0.119E-02	0.176E-03	0.147E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
16	0.431E-01	0.000E-00	0.202E-02	0.109E-03	0.117E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
17	0.238E-01	0.000E-00	0.294E-02	0.506E-03	0.117E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
18	0.108E-01	0.000E-00	0.194E-02	0.169E-03	0.117E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
19	0.108E-01	0.000E-00	0.156E-02	0.133E-03	0.117E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00
20	0.421E-01	0.000E-00	0.156E-02	0.133E-03	0.117E-03	0.000E-00	0.000E-00	0.000E-00	0.000E-00

----- STRAINS AND STRESSES AT TIME ----- = 3.99978

ELEMENT NUMBER	VOLUME STRAIN	SHFAR STRAIN	FLUID VOL CHANGE	EFFECTIVE PRESSURE	SHEAR STRESS	PORE PRESSURE
1	0.948E-07	0.000E-00	0.130E-03	0.000E-00	0.000E-00	0.000E-00
2	0.659E-04	0.000E-00	0.605E-03	0.000E-00	0.000E-00	0.000E-00
3	0.359E-05	0.000E-00	0.495E-03	0.000E-00	0.000E-00	0.000E-00
4	0.191E-05	0.000E-00	0.336E-03	0.000E-00	0.000E-00	0.000E-00
5	0.885E-05	0.000E-00	0.716E-03	0.000E-00	0.000E-00	0.000E-00
6	0.181E-05	0.000E-00	0.106E-03	0.000E-00	0.000E-00	0.000E-00
7	0.813E-06	0.000E-00	0.870E-03	0.000E-00	0.000E-00	0.000E-00
8	0.276E-05	0.000E-00	0.345E-03	0.000E-00	0.000E-00	0.000E-00
9	0.166E-06	0.000E-00	0.881E-03	0.000E-00	0.000E-00	0.000E-00
10	0.166E-06	0.000E-00	0.881E-03	0.000E-00	0.000E-00	0.000E-00
11	0.166E-06	0.000E-00	0.881E-03	0.000E-00	0.000E-00	0.000E-00
12	0.166E-06	0.000E-00	0.881E-03	0.000E-00	0.000E-00	0.000E-00
13	0.166E-06	0.000E-00	0.881E-03	0.000E-00	0.000E-00	0.000E-00
14	0.166E-06	0.000E-00	0.881E-03	0.000E-00	0.000E-00	0.000E-00
15	0.166E-06	0.000E-00	0.881E-03	0.000E-00	0.000E-00	0.000E-00
16	0.166E-06	0.000E-00	0.881E-03	0.000E-00	0.000E-00	0.000E-00
17	0.166E-06	0.000E-00	0.881E-03	0.000E-00	0.000E-00	0.000E-00
18	0.166E-06	0.000E-00	0.881E-03	0.000E-00	0.000E-00	0.000E-00
19	0.166E-06	0.000E-00	0.881E-03	0.000E-00	0.000E-00	0.000E-00
20	0.166E-06	0.000E-00	0.881E-03	0.000E-00	0.000E-00	0.000E-00

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RESPONSE AT TIME = 7.99949									
N	DX	DY	DW	VX	VY	VW	AX	AY	AZ
1	0.2528E-01	1833E-01	8922E-02	0.6572E-01	0.0000	0.0000	0.0000	0.0000	0.0000
2	0.2532E-01	1014E-01	1702E-02	0.6718E-01	0.0000	0.0000	0.0000	0.0000	0.0000
3	0.1983E-01	0.6613E-01	1604E-02	0.8509E-01	0.0000	0.0000	0.0000	0.0000	0.0000
4	0.1933E-01	1.0167E-01	1601E-02	0.8322E-01	0.0000	0.0000	0.0000	0.0000	0.0000
5	0.4233E-01	1.4619E-01	1638E-02	0.6655E-01	0.0000	0.0000	0.0000	0.0000	0.0000
6	0.3703E-01	1.2953E-01	1401E-02	0.5512E-01	0.0000	0.0000	0.0000	0.0000	0.0000
7	0.3807E-01	1.1487E-01	1098E-02	0.3240E-01	0.0000	0.0000	0.0000	0.0000	0.0000
8	0.3387E-01	1.5575E-01	1408E-02	0.2295E-01	0.0000	0.0000	0.0000	0.0000	0.0000
9	0.3392E-01	1.3733E-01	1540E-02	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
10	0.3392E-01	1.7799E-01	1408E-02	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
11	0.3392E-01	0.8729E-01	1004E-02	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
12	0.3392E-01	0.6529E-01	1004E-02	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
13	0.3392E-01	0.8529E-01	1004E-02	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
14	0.3392E-01	0.6194E-01	1004E-02	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
15	0.3392E-01	0.8194E-01	1004E-02	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
16	0.3392E-01	0.6194E-01	1004E-02	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
17	0.3392E-01	0.8194E-01	1004E-02	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
18	0.3392E-01	0.6194E-01	1004E-02	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
19	0.3392E-01	0.8194E-01	1004E-02	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
20	0.3392E-01	0.6194E-01	1004E-02	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000

----- STRAINS AND STRESSES AT TIME = 7.99949

ELEMENT NUMBER	VOLUME STRAIN	SHEAR STRAIN	FLUID VOL CHANGE	EFFECTIVE PRESSURE	SHEAR STRESS	PORE PRESSURE	PORE PRESSURE
1	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
2	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
3	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
4	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
5	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
6	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
7	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
8	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
9	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
10	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
11	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
12	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
13	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
14	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
15	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
16	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
17	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
18	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
19	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
20	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000

ELEMENT LIQUEFACTION DATA

EL. NO. 1 NO LIQUEFACTION  
 2 NO LIQUEFACTION

3 NO LIQUEFACTION  
 4 NO LIQUEFACTION  
 5 INITIAL LIQUEF. AT TIME = 5.8296  
 6 NO LIQUEFACTION  
 7 NO LIQUEFACTION  
 8 NO LIQUEFACTION  
 9 NO LIQUEFACTION  
 10 NO LIQUEFACTION  
 11 NO LIQUEFACTION  
 12 NO LIQUEFACTION  
 13 NO LIQUEFACTION  
 14 NO LIQUEFACTION  
 15 NO LIQUEFACTION  
 16 NO LIQUEFACTION  
 17 NO LIQUEFACTION  
 18 NO LIQUEFACTION  
 19 NO LIQUEFACTION  
 20 NO LIQUEFACTION



\*\*\* POST-EARTHQUAKE ANALYSIS \*\*\*

NODE N.	IN SITU	PORE PRESSURES AFTER EQ.	EXCESS
1	0.0	0.0	0.0
2	0.0	0.0	0.0
3	0.0	0.0	0.0
4	0.0	0.0	0.0
5	0.0	0.0	0.0
7	0.0	0.0	0.0
8	0.0	0.0	0.0
9	0.0	0.0	0.0
10	0.0	0.0	0.0
11	0.0	0.0	0.0
12	0.0	0.0	0.0
13	0.0	0.0	0.0
14	0.0	0.0	0.0
15	0.0	0.0	0.0
16	0.0	0.0	0.0
17	0.0	0.0	0.0
18	0.0	0.0	0.0
19	0.0	0.0	0.0
20	0.0	0.0	0.0

TOTAL TIME FOR DISSIPATION ANALYSIS=3562.99976

---TIME---= 0.50000  
 SETTLEMENT= 0.0321  
 WATER TABLE DEPTH= 59.99420

NODE N.	EXCESS PP.	DISSIPATED RATIO
1	0.0	0.0
2	0.0	0.0
3	0.0	0.0
4	0.0	0.0
5	0.0	0.0
7	0.0	0.0
8	0.0	0.0
9	0.0	0.0
10	0.0	0.0
11	0.0	0.0
12	0.0	0.0
13	0.0	0.0
14	0.0	0.0
15	0.0	0.0
16	0.0	0.0
17	0.0	0.0
18	0.0	0.0
19	0.0	0.0
20	0.0	0.0

OVERALL DISSIPATION RATIO= 0.00029

---TIME---= 3.00000  
 SETTLEMENT= 0.01649  
 WATER TABLE DEPTH= 59.96999

NODE N.  
 1  
 2  
 3  
 4  
 5  
 6  
 7  
 8  
 9  
 10  
 11  
 12  
 13  
 14  
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 16  
 17  
 18  
 19  
 20  
 OVERALL DISSIPATION RATIO= 0.01291

EXCESS PP.	DISSIP. RAT.
0.25266E01	UNDEFINED
0.48926E01	0.23070
0.65283E01	0.03442
0.82383E01	0.20599
0.93576E01	0.25816
0.89991E01	0.01522
0.87749E01	0.01788
0.86731E01	0.02095
0.87661E01	0.02375
0.90243E01	0.00272
0.97487E01	0.01020
0.77668E02	0.00767
0.10044E02	0.00763
0.10276E02	0.00322
0.10449E02	0.00224
0.10568E02	0.00224
0.10612E02	0.00672
0.10612E02	0.00746

TIME=== 62.99998  
 SETTLEMENT= 0.20448  
 WATER TABLE DEPTH= 59.61452

NODE N.  
 1  
 2  
 3  
 4  
 5  
 6  
 7  
 8  
 9  
 10  
 11  
 12  
 13  
 14  
 15  
 16  
 17  
 18  
 19  
 20  
 OVERALL DISSIPATION RATIO= 0.18726

EXCESS PP.	DISSIP. RAT.
0.12316E01	UNDEFINED
0.24297E01	0.62280
0.35682E01	0.52047
0.46082E01	0.38328
0.52355E01	0.59923
0.62689E01	0.34529
0.76583E01	0.33477
0.85457E01	0.15233
0.88957E01	0.01033
0.91276E01	0.01835
0.93401E01	0.02352
0.95120E01	0.03056
0.97349E01	0.04667
0.98297E01	0.05389
0.98750E01	0.05956
0.98901E01	0.07198
0.98901E01	0.07498

TIME=== 562.99976  
 SETTLEMENT= 0.81084  
 WATER TABLE DEPTH= 58.45691

NODE N. 1  
 EXCESS PP. 0.0  
 DISSIP. RAT. UNDEFINED

0.88104  
 0.84473  
 0.79694  
 0.86503  
 0.77497  
 0.76250  
 0.72739  
 0.62343  
 0.58497  
 0.55168  
 0.55404  
 0.55380  
 0.54916  
 0.55251  
 0.55318  
 0.5557  
 0.65857

394730E  
 0.786755E  
 0.117339E  
 0.155194E  
 0.197476E  
 0.221399E  
 0.293366E  
 0.351572E  
 0.377080E  
 0.402108E  
 0.437538E  
 0.453134E  
 0.463122E  
 0.471228E  
 0.47736E  
 0.477736E  
 0.477736E  
 OVERALL DISSIPATION RATIO=

OVERALL DISSIPATION RATIO=

--- TIME --- = 3562.99976  
 --- SETTLEMENT --- = 1.25832  
 --- WATER TABLE DEPTH --- = 57.63962

DISSIP. RAT.  
 UNDERMINED  
 0.99914  
 0.99888  
 0.99853  
 0.99902  
 0.99827  
 0.99828  
 0.99798  
 0.99766  
 0.99727  
 0.99689  
 0.99666  
 0.99675  
 0.99677  
 0.99677  
 0.99675  
 0.99673  
 0.99676  
 0.99676  
 0.99752

EXCESS PP.  
 0.285843E-02  
 0.569740E-02  
 0.849735E-01  
 0.113904E-01  
 0.134749E-01  
 0.169322E-01  
 0.212607E-01  
 0.234668E-01  
 0.273158E-01  
 0.304991E-01  
 0.327388E-01  
 0.335556E-01  
 0.341496E-01  
 0.346144E-01  
 0.346144E-01  
 OVERALL DISSIPATION RATIO=

OVERALL DISSIPATION RATIO=

NODE N.  
 1  
 2  
 3  
 4  
 5  
 6  
 7  
 8  
 9  
 10  
 11  
 12  
 13  
 14  
 15  
 16  
 17  
 18  
 19  
 20  
 OVERALL DISSIPATION RATIO=

