AIOF3_BRUSHED Flight Control Board Built-in OSD Frsky Receiver

The AIOF3_BRUSHED flight controller is a Highly integrated F3 flight controller both for Indoor FPV flight and outdoor FPV.

The flight controller integrate OSD and Receiver, run Betaflight firmware. It's amazing, you only just get ready your VTX and camera, it's simple to DIY a whole FPV racing Quadcopter with brushed motor.

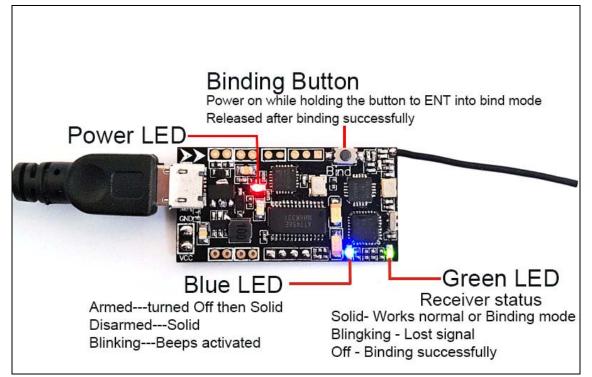
1. Specification:

Brand Name: Eachine Size: 38mm*19mm Weight: 3g Processor: STM32 F303 MCU Sensor: SPI Sensor MPU6000 Target: Omnibus

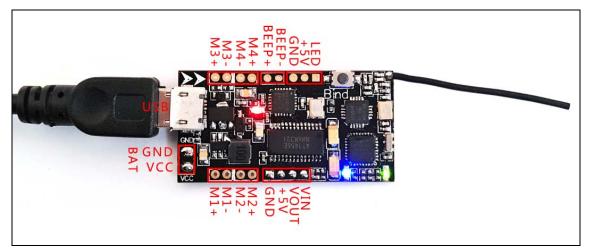
Firmware Version: Betaflight 3.0.1

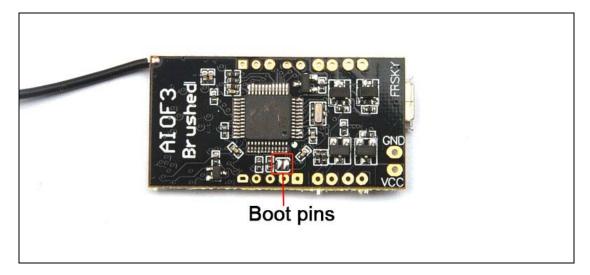
Receiver: Frsky D8 mode SBUS Output 8ch With RSSI output (OSD display Channle9 / X9D telemetry)

2. Connector and LED Definition:



3. Installation and Connection diagram:





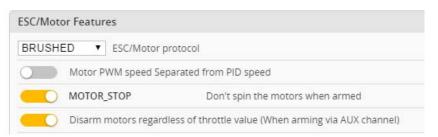
4. Betaflight configuration:

All the configuration was set up before shipping, if you need to flash firmware and select "Full chip erase", you should reconfigure for the AIOF3 Flight controller board according to the bellowing diagram.

After you flashed firmware and do the "Full chip erase" option, Please remove the propeller from the motor and plug your battery ,otherwise it maybe can't connected to the Betaflight configurator.

Reconfigure steps:

Go to Configure Tab and set ESC/Motor protocol to BRUSHED



*This step is in order to avoid motor auto-spinning when connect the battery

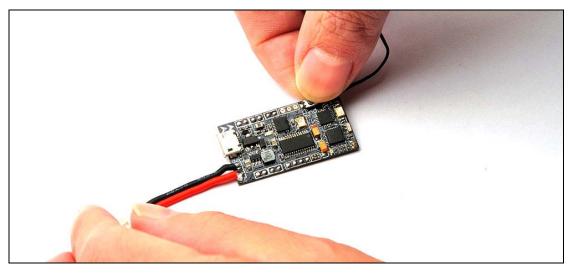
 Ports and receiver mode sets like the bellowing diagram: First Enable Seria_RX for uart3 and Set Receiver mode RX_SERIAL, Select SBUS signal in Betaflight configurator.

Ports					WIKI
		the flight controller firmware detects al port unless you know what you are	, 0		tion if you do.
Identifier	Data	Logging	Telemetry	RX	GPS
USB VCP	MSP 115200 V	Blackbox 115200 V	Disabled V AUTO V	Serial RX	57600 •
UART1	MSP 115200 V	Blackbox 115200 V	Disabled • AUTO •	Serial RX	57600 •
UART2	MSP 115200 V	Blackbox 115200 •	Disabled v AUTO v	Serial RX	57600 •
UART3	MSP 115200 V	Blackbox 115200 V	Disabled v AUTO v	Serial RX	57600 •

RX_PPM	PPM RX input
RX_SERIAL	Serial-based receiver (SPEKSAT, SBUS, SUMD)
RX_PARALLEL_PWM	PWM RX input (one wire per channel)
RX_MSP	MSP RX input (control via MSP port)
erial Receiver Provider	
Note: Remember to configure RX_SERIAL feature.	e a Serial Port (via Ports tab) and choose a Serial Receiver Provider when using
	e a Serial Port (via Ports tab) and choose a Serial Receiver Provider when using

2. Binding Procedure:

a)Power for the AIOF3_Brushed board while holding the Bind button, the Green LED will getting to be solid, this means the AIOF3_Brushed is in binding mode, then release the button.



b)Turn on your Radio and select D8 mode for the Receiver. Then Go to the Receiver [Bind] option, and ENT to Binding with the AIOF3_Brushed. The Green LED will turning off, this indicates binding successfully. Reconnect the battery to the AIOF3_Brushed board after Binding successfully.

1		DIGITAL TELEMET	RY RADIO SYSTEM		
	MENU	illiansialle Internal RF	2/12	÷	
	PAGE	Mode Channel Ran9e Receiver External RF	03 CH1-8 [Bind] [Range]	\odot	
	EXIT	Mode Trainer Port	OFF	ENT	
		ACCEST TAR	ANIS - plus		5

3. The default receiver channel map is TAER1234, please ensure your transmitter is matched with it, otherwise it can't be armed.

Channel Map	RSSI Channel
TAER1234	Disabled •

4. The Default Arm/Disarm switch is AUX1(Channel 5),and you can also customize it with Betaflight Configurator.

			ter and corresponding tings using the Save bi		. A receiver channel th	nat gives a reading bet	ween a range min/n	nax
ARM Add Range	AUX 1 • Min: 1300 Max: 2100	' 900 1000	1 1 1 1 1 1200	 1400 1	' ' ' 1500 1600	' ' ' 1800	2000 2100	C
AIR MODE	AUX 2 Min: 1300 Max: 1600	 ' 900 1000	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	· · · · · · · · · · · · · · · · · · ·	 500 1600	1 1 1 1800	¹ ¹ 2000 2100	¢
ANGLE	AUX 2 🔻							¢

5. Set Arm/Disarm switch for your TARANIS X9D: Move to the MIXER interface, Set "SA" or "SB" switch etc. for Ch5 to ARM/DISARM the motor.

	DIGITAL TELEMETRY RADIO SYSTEM		
MENU	112 5/64 -100.0 6/12 CH1 100 EThr	Ð	C
PAGE	CH3 100 HELE CH4 100 HELE CH4 100 HRud CH5 100 Harm	\odot	C
EXIT	CH6 CH7	ENT	C
	ACCET TARANIS - Plus	EN	

6. Toggle the AUX1 Switch and the blue LED on the board will first turning off and get be solid soon, this indicate the motor was armed. Be careful and enjoy your flight now!

5. OSD configuration:

Connect the AIOF3 board to the computer , open Betaflight Configurator , move to the OSD option

lements	Preview (drag to change position)	Logo: 🔍 Vi	deo Format	
🔘 Rssi Value		۲	AUTO 🔍 PAL	◎ NTSC
🔘 Main Batt Voltage	- Contraction of the second			
Crosshairs	S BETAFLI		nits	
🔾 Artificial Horizon		•	IMPERIAL 🔘 I	VETRIC
🔍 Horizon Sidebars	÷> • • • • • • • • • • •	A	arms	
💟 Ontime		20		Rssi
O Flytime	Carlo Carlos	And the second se	:00	Capacity
C Flymode		10		Minutes
Craft Name	STAB 	部 4:11 ¹⁰ 部 4:11	0	Altitude
Throttle Position		mb 4		
		and a second		

RSSI output use Channel 9, configure in Betaflight receiver option

Channel Map TAER1234 V			RSSI Channel 9	T
RC Deadband	0 \$	Yaw Deadband		0 🛊
RC Interpolation	RC Interpolation			0

Craft Name set in configuration option

1460 🜲 3D Neutral	
0 🔷 3D Deadband Throttle	
Misc	
Eachine AIOF3 Craft name	