

Simplifying the Temporal Analysis of Products Reactor

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Abstract

The Temporal Analysis of Products (TAP) experiment provides an unparalleled level of kinetic insight into heterogenous catalytic materials, but due to the complex and expensive instrumentation required, its application has been limited to a small group of dedicated researchers. Herein we demonstrate through a series of designs that precisely defined TAP experiments can be performed on systems far smaller and simpler than previously imagined. The pulse reactors described in this work utilise readily available components and so can be assembled, operated, and maintained with minimal training. Using the case study of CO oxidation over a Pt/SiO₂ catalyst we show that precise kinetic, mechanistic, and surface composition information is feasible using our single-valve design. With the developments outlined in this work we aim to decrease the activation barrier to TAP and open up the technique to a new generation of researchers.

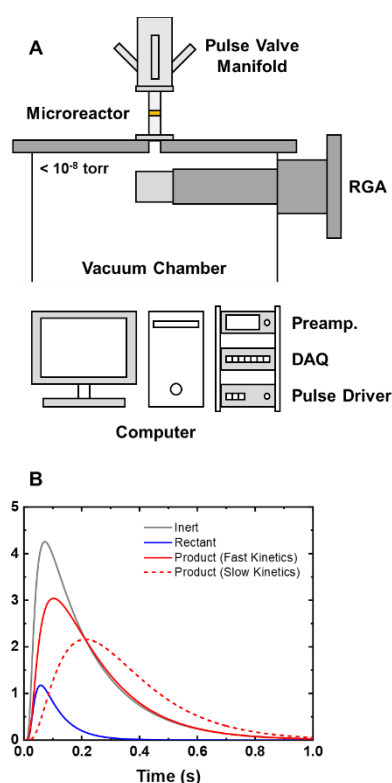
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1. Introduction

The ability to resolve fine kinetic features of heterogenous (gas-solid) catalytic systems is of great importance when it comes to designing new catalysts. By precisely determining reaction mechanisms and kinetic coefficients, it becomes possible to rationalise, predict, and potentially enhance catalytic behaviour [1–3]. Steady-state kinetic studies have been employed extensively and successfully, but they are often limited in their scope, as fine kinetic features can be obfuscated by mass-transport effects, rapid decomposition of intermediates, or by the reaction network collapsing to a small number of rate limiting steps [4,5]. Non-steady-state techniques such as Steady State Isotopic Transient Kinetic Analysis (SSITKA) [6], Molecular Beam Scattering (MBS) [7], or Temporal Analysis of Products (TAP) [8] provide information on time-resolved catalytic activity, circumventing some of the limitations of steady-state experiments. Specifically, the TAP experiment combines the benefits of both SSITKA and MBS experiments as it does not require large amounts of expensive isotopes, can resolve kinetic features with sub-millisecond time resolution, utilises precisely defined transport phenomena [9,10], and bridges the so-called pressure and materials gaps [11]. In particular, the TAP experiment has been successful in elucidating the kinetics for HCl oxidation [12], methanol oxidation [13], and propane dehydrogenation [14], alongside many others [15,16]. Further, due to its molecular level precision, the TAP experiment has more recently found use as a structural/composition characterisation tool [17–19]. However, the significant cost and expertise required to build, maintain, and operate the reactors used to perform the TAP experiment means that even after over forty years of application it has largely been limited to a small number of dedicated research groups, struggling to gain mainstream appeal.

In this work, we demonstrate that precisely defined TAP experiments are achievable in smaller and simpler systems than was previously thought possible. We identify the limiting conditions where TAP experiments transfer out of this precisely defined regime but find that the pulses can still provide in-depth qualitative insight. With this analysis, we aim to reduce the significant activation barrier to TAP experiments and open up the field of transient kinetics to an entirely new generation of researchers.

51 **2. Overview of the TAP experiment**
52



53 **Figure 1.** (A) Schematic overview of the pulse reactor used in TAP experiments. (B) Representative
54 TAP exit flux curves for the irreversible adsorption and reaction of a reactant compared to the response
55 of an inert gas. The reactant (blue) is consumed during the pulse to create the product (red) and as such
56 has a decreased magnitude and thinner shape than the inert curve (grey). The product curves for a
57 corresponding fast (solid line) and slow (dashed line) kinetic process show that the shape of the product
58 curve provides insight into the speed at which the surface reaction takes place.
59

60
61 First published by Gleaves in 1988 [20] and refined by Gleaves and Yablonsky in 1997 [8], the
62 TAP experiment, outside of some modernisation and automation [11], has remained largely unchanged
63 in the last 26 years. Approximately 22 groups have worked with TAP reactors, of which, 17 groups use
64 systems developed by Gleaves with an additional 5 groups using home-built versions [21]. All these
65 systems contain the same three components. A pulse valve (or pulse valve manifold), a microreactor
66 containing a powdered catalyst (typically a thin zone of catalyst sandwiched between two layers of inert
67 material), and a Residual Gas Analyser (RGA) that is housed in an ultra-high vacuum (UHV) chamber,
68 all of which are controlled by a computer and external components (Figure 1A). Conceptually the TAP
69 experiment is very simple: a short sharp pulse of gas is sent into the microreactor and the flux of gas at
70 the reactor exit is recorded. When the pulse size is kept small ($< 10^{15} - 10^{16}$ molecules) the transport
71 occurs via Knudsen diffusion. Under these conditions the gas phase interactions are minimised, and the
72 shape of the exit flux curve is defined by the gas-surface interactions, and by extension, the underlying
73 physical and chemical processes. Therefore, by comparing the shape and magnitude of the exit flux
74 curve for a reactant / product to that of an inert gas, detailed kinetic and mechanistic insight into catalytic
75 processes becomes possible (Figure 1B). The exit flux response curves in a TAP experiment are often
76 reported as “normalised exit flux” or “normalised exit flow” which is the measured exit flux/flow
77 normalised to amount of the species in the inlet pulse:

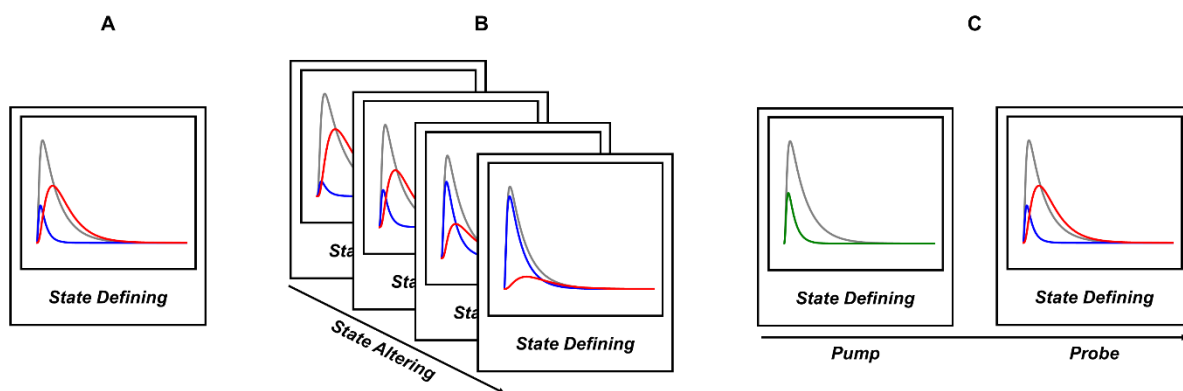
$$F_A^{norm} = \frac{F_A}{(N_A/A)} \quad (1)$$

78 where F_A^{norm} is the normalised exit flux of A (1/s), F_A is the exit flux of A (mol/cm²/s), N_A is the
 79 number of molecules of A in the inlet pulse (mol), and A is the cross-sectional area of the reactor (cm²).
 80 Products not included in the inlet pulse are normalised to the corresponding reactant inlet pulse.

81

82 If the pulse size is sufficiently small that the number of molecules is significantly less than the
 83 total number of active sites on the catalyst surface, a single pulse should not modify the catalyst surface
 84 by any appreciable amount. Under these conditions, the pulse acts as a *kinetic snapshot* of the catalyst
 85 surface at that given state, defined as a *state-defining* [8] experiment (Figure 2A). By repeatedly pulsing,
 86 it becomes possible to induce finite changes in the catalyst surface through a series of small infinitesimal
 87 steps such that the experiment becomes *state-altering*, known as *chemical calculus* [22] (Figure 2B).
 88 By utilising a multi-valve system, it becomes possible to perform a *dynamic state-defining* experiment
 89 where a pump molecule is sent into to the reactor, then after a time delay, a probe molecule is sent into
 90 the reactor (Figure 2C). The pump and probe pulses should not alter the underlying catalyst state, and
 91 by altering the time delay between the pump and probe molecules, this allows dynamic understanding
 92 of kinetics at a fixed catalysts state [15]. While the microreactor is at UHV between pulses, during a
 93 pulse the pressure over the catalyst in the reactor at the peak of the pulse is in the range of 0.1 – 1 mbar
 94 [16], placing the TAP experiment in the same category as other *operando* methods. A more recent
 95 development of the technique involves increasing the pulse size such that the transport leaves the
 96 Knudsen regime and that gas-gas collisions can occur. This makes it possible to “switch on” gas phase
 97 collisions, potentially allowing deconvolution of gas phase and surface reactions [23,24]. The examples
 98 referenced here are only a small sample of the applications of the TAP technique, with extensive reviews
 99 published elsewhere [11,15,16,25].

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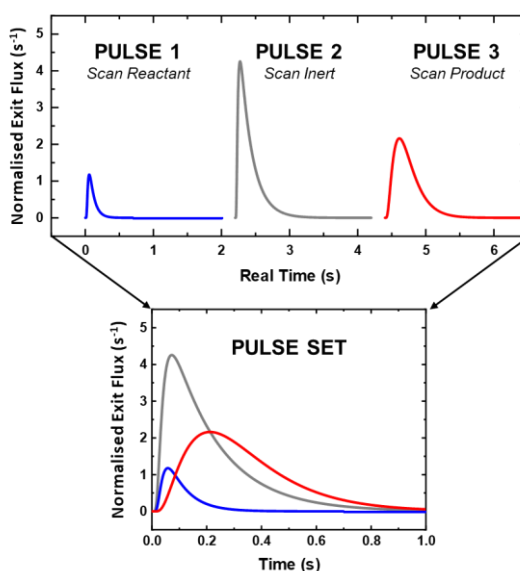
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102 **Figure 2.** Schematic outlining the three most popular types of TAP experiments. A) In a single pulse
 103 experiment, the catalyst surface is unperturbed such that the resulting exit flux acts as a *kinetic snapshot*
 104 of the catalyst state. B) By repeatedly pulsing it becomes possible to incrementally modify the catalyst
 105 state. By recording a series of snapshots as a function of evolving catalyst state, it is possible to watch
 106 the evolution of the catalyst surface. C) By pulsing a pump molecule, followed by a probe molecule
 107 after a certain time delay, it is possible to record the evolution of dynamic species on the catalyst surface
 108 at a fixed catalyst state.

109

110 As a RGA is commonly used to measure the exit flux in a TAP experiment, the pulsing sequence
 111 is limited to scanning only one M/Z value for the duration of the pulse. When a pulse experiment is
 112 performed under *state defining* conditions, multiple pulses are combined together into a *pulse set* which
 113 is then taken as a static catalyst state and is used to calculate reaction kinetics. The pulse set contains

114 the reactant(s), the inert tracer, and the product(s), which in one of the simplest cases contains three
115 individual pulses (Figure 3), but in more complex cases can consist of many pulses. It's important to
116 note that while the entire suite of chemical processes occur in each pulse, only one species can be
117 recorded at a time. The TAP reactor has been combined with a Time-of-Flight (TOF) mass spectrometer
118 [26] to circumvent the requirement to combine data into a pulse set, but these TAP-TOF instruments
119 have rarely seen application. Unfortunately, the terms pulse and pulse set are often used interchangeably
120 which can cause confusion, but in almost all circumstances TAP exit flux curves are represented in the
121 pulse set format.
122



123
124 **Figure 3.** Description of a “pulse set”. As most RGAs can only record one mass over the timescale of
125 a pulse, multiple pulses are required to record a single point. In the example shown three pulses (M/Z
126 values) are required to probe the reactant, inert, and the product. These three pulses are then combined
127 to make a pulse set.
128

129 3. Defining the TAP model

130
131 From simply studying the shape and magnitude of the exit flux curves the TAP experiment can
132 provide in-depth insight into both reaction kinetics and mechanisms. However, it is the precise
133 modelling of the experiment that makes TAP a uniquely powerful kinetic tool for determining rate
134 constants [13,27–29] and mechanisms [23,30]. The exact conditions required for quantitative modelling
135 of the TAP experiment were outlined by Yablonsky in 1997 [8] and are:
136

- 137 1. The governing transport phenomena is Knudsen Diffusion.
- 138 2. The pulse size is sufficiently small that the experiment is *state defining*.
- 139 3. The transport (and as such, the shape of the exit flux curve for an inert gas) is solely defined by
140 the characteristics of the microreactor’s packed bed, with no pre- or post-diffusive zones affecting the
141 shape of the exit flux.

142
143 The first two requirements are relatively easy to achieve, and have been implemented in many other
144 TAP-like systems [31–34] but so far only the systems developed by Gleaves [8,11] have ever been
145 shown to rigorously verify the third requirement.
146

147 The series of equations and boundary conditions that describe a precise TAP experiment have been
148 discussed extensively in the previous literature [8,9,35,36], but they are summarised here for reference.

149 The TAP reactor model is often partitioned into *zones*, where each zone represents a different part of
 150 the catalyst bed (*e.g.*, inert zone, catalyst zone) with the typical setup being an inert zone, a thin catalyst
 151 zone, followed by another inert zone [35]. *It is important to note that the zones in this model all exist*
 152 *within the packed bed of the microreactor*, and that while zones outside of the packed bed may be
 153 included in a model, these are poorly defined and difficult to rigorously isolate. For each zone, a one-
 154 dimensional diffusion/reaction equation is utilised, which for a reversibly adsorbing gas is:

$$\varepsilon_b \frac{\partial C_A}{\partial t} = D_{eA} \frac{\partial^2 C_A}{\partial z^2} - \alpha_s S_V (1 - \varepsilon_b) (k_a C_A \theta_* - k_d \theta_A) \quad (2)$$

155 where ε_b represents the void fraction of the reactor, C_A represents the concentration of the gaseous
 156 species A (mol/cm³), t is the time relative to the triggering of the pulse (s), D_{eA} is the effective Knudsen
 157 diffusivity of gas A (cm²/s), z is the axial coordinate of the reactor (cm), α_s is the concentration of
 158 active sites on the catalyst surface (mol/cm²), S_V is the surface area of catalyst per volume of catalyst
 159 (cm²/cm³), k_a is the adsorption rate constant (cm³/mol/s), θ_* is coverage of free sites, k_d is the
 160 desorption rate constant (1/s), and θ_A is coverage of adsorbed A. For noninteracting cases (*i.e.*, over
 161 inert packing) the terms relating to the kinetics are set to zero, such that only diffusion occurs. Most
 162 commonly, the surface species are modelled using a mean-field microkinetic model, which for the
 163 reversibly adsorbing species would be:

$$\frac{\partial \theta_A}{\partial t} = k_a C_A \theta_* - k_d \theta_A \quad (3)$$

164 When gas travels between two zones within the packed bed, both flux and concentration are conserved
 165 such that:

$$C_A^n(1, t) = C_A^{n+1}(0, t) \quad (4)$$

$$-D_{eA}^n \frac{\partial C_A^n}{\partial z}(1, t) = -D_{eA}^{n+1} \frac{\partial C_A^{n+1}}{\partial z}(0, t) \quad (5)$$

166 for a given zone n the concentration of A and the flux of A conserved when transitioning to from zone
 167 n to zone $n + 1$. For a gas being pulsed into the reactor the initial condition is defined as:

$$C_A(z, 0) = \delta(z, 0) \quad (6)$$

168 where $\delta(z, 0)$ represents a delta function introduced into the reactor inlet at a time $t = 0$. After
 169 introducing the pulse into the microreactor, the pulse valve is closed, and so the boundary at the entrance
 170 to the packed bed can be defined as:

$$\frac{\partial C_A(0,t)}{\partial z} = 0 \quad (7)$$

171 As the exit of the microreactor is attached to a vacuum, the exit condition at the end of the packed bed
172 is defined as:

$$C_A(L,t) = 0 \quad (8)$$

173 where L is the total length of the reactor (cm). Finally, the flux of gas leaving the reactor, which
174 recorded during the experiment, is defined as

$$F_A = -D_{eA} \frac{\partial C_A(L,t)}{\partial z} \quad (9)$$

175 Generalised analytical solutions exist for first-order (or pseudo first-order) state defining experiments
176 [9,35,37,38], with numerical simulation utilised for non-linear experiments [13,39,40].

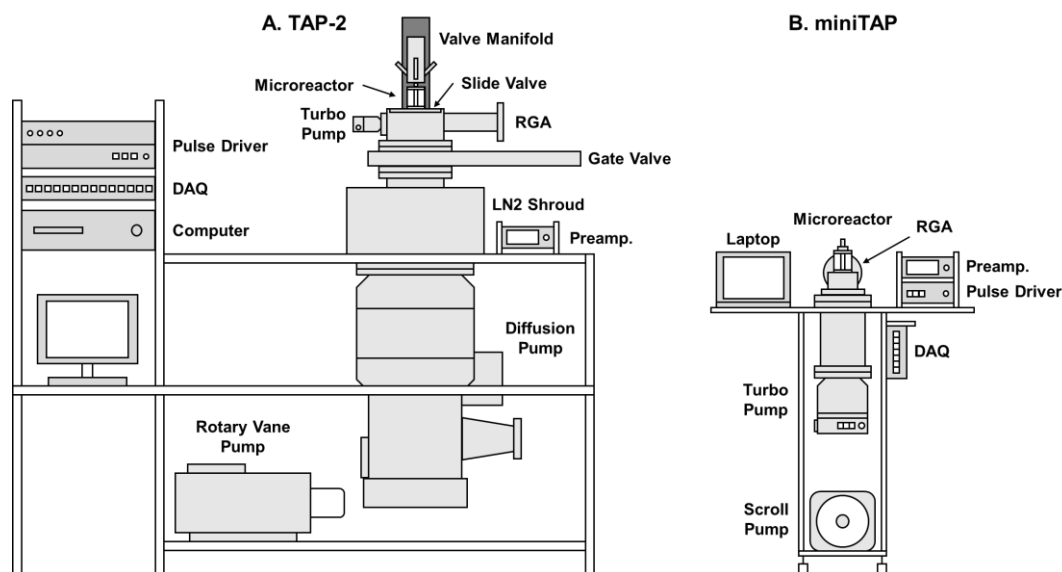
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178 **4. The Gleaves TAP system design**

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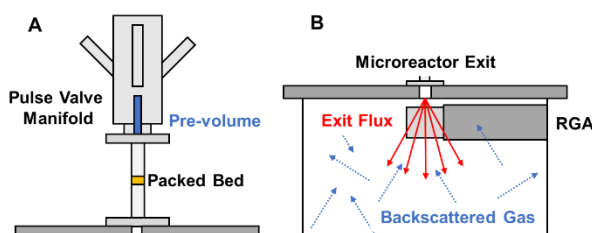
180 The TAP systems developed by Gleaves have been described extensively in the previous literature
181 [8,15,25] but the core components are highlighted here. The TAP-2 (and TAP-3) systems consists of an
182 oil diffusion pump (e.g., Varian VHS-10) that is mounted to a large liquid nitrogen cooled chamber that
183 can be isolated from the rest of the system using a gate valve. A vacuum chamber containing a
184 turbomolecular pump (e.g., Varian Turbo-V70) and an RGA (e.g., Stanford Research Systems RGA300)
185 is attached to the other side of the gate valve. A custom-built microreactor is attached to the top of the
186 vacuum chamber via an O-ring seal, which can be isolated using a slide valve assembly, allowing the
187 user to rapidly change samples. The inclusion of a vent line and needle valve within the slide valve
188 assembly also allows the user to perform atmospheric pressure flow treatments of catalysts by flowing
189 gas through the pulse valve manifold with the gas being sampled by the RGA using the needle valve.
190 Finally, a pulse valve manifold containing multiple (2-4) solenoid valves and a continuous flow valve
191 is mounted above the system, which can be lowered and raised as needed (Figure 4A). During operation
192 the pulse valve manifold is lowered and sealed to the microreactor via an O-ring, the liquid nitrogen
193 cooled chamber is filled, the gate valve is opened, and then the microreactor is exposed to the vacuum
194 ($\sim 1 \times 10^{-8}$ torr base pressure) via the slide valve assembly.

195



196
197 **Figure 4.** Schematic illustration of A) The TAP-2 system developed by Gleaves and B) The miniTAP
198 developed as part of this work. Drawings are approximately to scale.
199

200 The Gleaves system has been specifically designed so that at the entrance of the packed bed the
201 flux is zero, and at the exit of the packed bed the concentration is zero and only the exit flux is being
202 measured (equations 6 and 7). Practically speaking what these two terms relate to is that there should
203 be no measurable pre-volume before the packed bed in which gas can reside (Figure 5A), and that once
204 the gas leaves the microreactor and enters the vacuum chamber it should be instantaneously detected
205 by the RGA and then pumped out such that it does not reside in the chamber and get detected multiple
206 times (Figure 5B). To remove the pre-volume, custom solenoid valves with extended stems were
207 designed such that the tips of the valve stems met at the exit of the pulse valve manifold [8]. To ensure
208 that the gas was instantaneously detected after leaving the microreactor, the RGA was mounted so that
209 the filament and ioniser were directly below the exit of the microreactor (which also has the added
210 benefit of significantly increasing detection sensitivity). Finally, to ensure that any gas leaving the
211 microreactor was not backscattered and only detected by the RGA once, the vacuum is generated using
212 a high pumping speed oil diffusion pump (> 3500 L/s pumping speed) and the top chamber was
213 differentially pumped using a small turbomolecular pump (70 L/s pumping speed).
214



215
216 **Figure 5.** Schematic representations of the two limiting conditions for well-defined TAP experiments.
217 A) That no pre-volume exists before the packed bed in the microreactor such that it acts as an extra
218 “zone” within the TAP model. B) That when the gas exits the microreactor it is instantaneously detected
219 and pumped away so that no backscattering gas exists that can be detected by the RGA.
220

221 While the Gleaves system’s capabilities are highly desirable, the increased complexity of the
222 design meant that it took a significant level of skill to operate and maintain the system and perform the
223 TAP experiment. The bespoke nature of many of the parts in the system meant that it was not simple to
224 fix and/or replace the components as they age. Further the oil diffusion pump meant that contamination
225 of the vacuum components (e.g., the RGA) with residual pump oil would cause shortened lifespans and

226 drifting signals. This resulted in the TAP technique having a significant barrier to entry as reliable
227 operation requires a highly trained and dedicated user. To rectify these issues, we have designed a
228 simplified TAP reactor system that is oil free and consists of minimal components all of which are
229 readily available.

230

231 **5. Simplifying and Miniaturising the TAP reactor**

232

233 In an effort to simplify the TAP reactor we have developed the miniTAP (Figures 4B, S1, 8B) which
234 was influenced by both the Gleaves TAP-2 design [8] and the Delft TAP (Multitrack) system [33].
235 When designing the miniTAP reactor four core principles were laid out:

236

- 237 1. All components must be commercially available or easily sourced.
- 238 2. All components must be easy to repair and/or replace if damaged.
- 239 3. The system should be operable with minimal training.
- 240 4. The system must contain minimal contaminants to ensure consistent results.

241

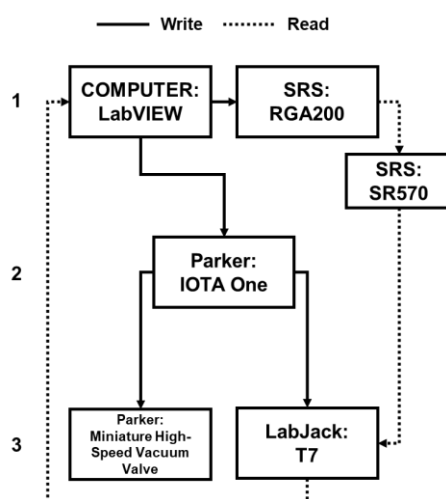
242 **5.1 The Vacuum system.** The miniTAP consists of a medium sized turbomolecular pump (Pfeiffer
243 HiPace 700, ~700 L/s pumping speed) that is connected to a standard DN160CF nipple (9" OAL). A
244 DN160CF to DN35CF reducer tee could also be used to mount a pressure gauge if desired. The use of
245 a turbomolecular pump coupled with a dry scroll pump (Edwards XDS 5) means that the vacuum
246 chamber remains oil free (minimising contaminants) and can reliably reach base pressures $\ll 1 \times 10^{-9}$
247 torr during operation. The contaminant free operation of the system means that consistent signals in the
248 RGA are possible over the course of weeks to months, with little re-calibration of the system required.
249 The nipple is attached to a DN100CF "hat" which has a DN63CF arm in the correct orientation so that
250 an RGA can be mounted directly beneath the microreactor exit (Figure S2). The microreactor utilised
251 is based on the Gleaves TAP-2 design (Figure S3.1). A quartz tube (6.35 mm OD, 4 mm ID) is
252 connected to a modified DN35CF ConFlat flange which contains a removable stainless screen to hold
253 the packing in place and is sealed via an O-ring (Kalrez, -010). The top of the microreactor is a custom-
254 built assembly that is also connected to the quartz tube via O-ring that has a small 0.020" side hole that
255 allows a thermocouple to be fed through into the packed bed. The top of microreactor also has a 4 mm
256 ID opening so that the packing is extended all the way to the top of the microreactor. A solenoid pulse
257 valve (Parker Miniature High-Speed Vacuum Valve) is directly mounted to the top of the microreactor
258 assembly which is also sealed using an O-ring (Figure S3.2). The reactor is packed upside down and is
259 designed so that the packing extends all the way to the exit of the pulse valve. A small extension cylinder
260 is also attached to the vacuum side of the microreactor to assist directing the exit flux to the RGA
261 (Figure S3.3). The vacuum chamber, turbopump and pulse valve are standard parts, that are attainable
262 without any modifications from commercial sources. The "hat" uses standardised vacuum components
263 that can be readily assembled by any vacuum company. Finally, while the microreactor consists of
264 bespoke machined components, we have found that acceptable quality and tolerances for all of the parts
265 was attainable using online machine shops.

266

267 The miniTAP system does lack some of the benefits of the Gleaves design. First, the removal
268 of the slide valve means that it is not possible to isolate the microreactor from the vacuum equipment
269 for rapid sample transfer or atmospheric pressure pre-treatments. We consider this an acceptable loss
270 as sample transfer is rarely the time-limiting factor in TAP experiments. Further, we have found that
271 atmospheric pressure pre-treatments can be mimicked by turning off the RGA and sending large pulses
272 of pre-treatment gas through the reactor. Second, the lack of a multi-valve system means that pump-
273 probe experiments are not possible. While many would find this a significant drawback of the miniTAP
274 system, experiments that can be precisely modelled using analytical functions such as single pulse,
275 multi-pulse, and titration style experiments are still accessible (see section 7). Further, other groups
276 [23,33] have successfully designed a multi-valve manifold with minimal pre-volume using commercial

277 solenoid valves. Finally, the use of a turbomolecular pumping system can cause problems with
278 efficiently pumping hydrogen from the vacuum system. While we do find that hydrogen does not fit the
279 idealised pulse response shape (see section 6, Figure S4) we see no significant build-up of H₂ base
280 pressure during our experiments. Further, due to water (and all hydrocarbons) containing a cracking
281 fragment at M/Z of 2 any precise modelling of the H₂ pulse shape is often not feasible due to the
282 imperfect nature of subtracting cracking fragments.

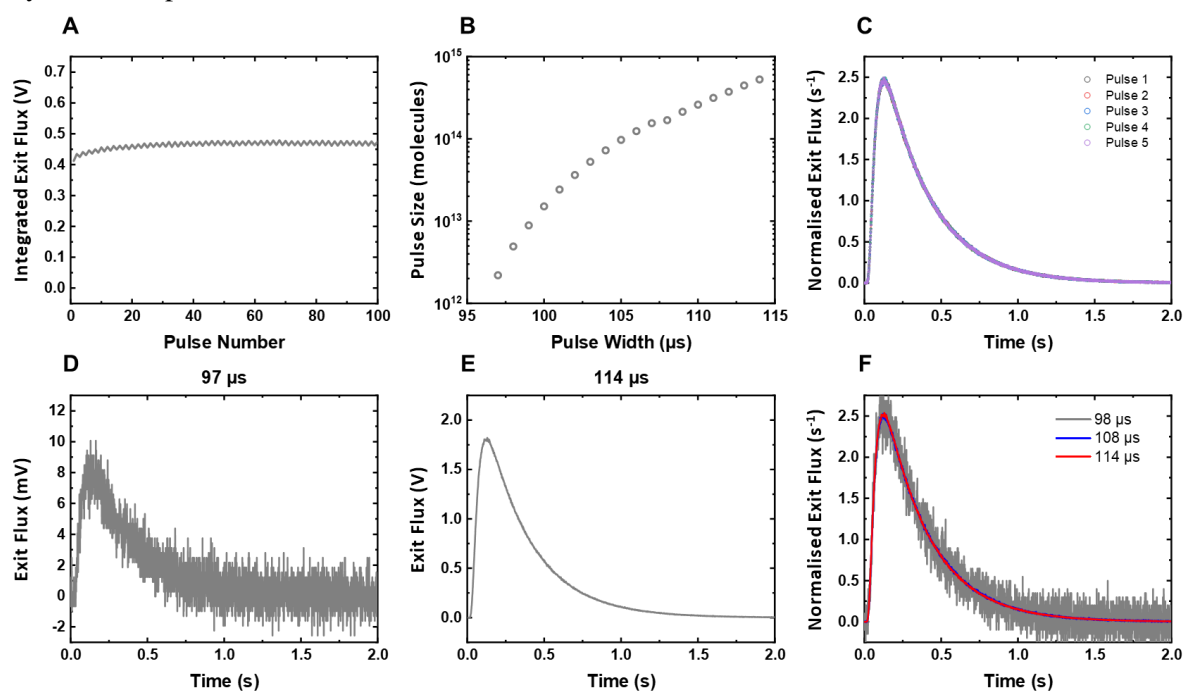
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284 **5.2 The Pulsing System.** In order to correctly perform a TAP experiment, the pulsing system must be
285 able to precisely time the simultaneous triggering of the valve and data collection, such that the valve
286 opening can be aligned to $t = 0$. Further, as the reactant and product curves are normalised to the inert
287 tracer during each pulse set (Figure 3), the pulsing system must also be designed such that the pulse-to-
288 pulse deviation is minimised. For valve firing and data acquisition a number of systems have already
289 been developed. The Gleaves systems combines the custom built solenoid pulse valve manifold with a
290 home-built driver [8,11] with the timing, triggering, and data collection performed using commercial
291 DAQ devices (National Instruments) controlled using home-built LabVIEW software. The system
292 developed at Delft University [33] uses a custom pulse valve manifold that houses multiple commercial
293 ultra-high speed solenoid valves (Parker Series 9) that are triggered using the corresponding commercial
294 driver (Parker IOTA One), with the timing performed using a commercial DAQ device (National
295 Instruments). A system at Ulm University [32] opted for custom piezoelectric valves [41,42] driven by
296 home-built electronics that are controlled using LabVIEW software. All systems report pulse-to-pulse
297 deviations between 2-8%, which allows for consistent collapsing of the data into pulse sets.
298



299
300 **Figure 6.** The workflow and components utilised in this work for performing a TAP Experiment. Solid
301 lines indicate writing of data, with dashed lines indicating the reading of signals or data.

302
303 The workflow and components for a pulse experiment used in this work are outlined in Figure
304 6 and follows a three-step procedure. First, the computer sets the RGA (Stanford Research Systems
305 RGA200) to the desired M/Z value to be recorded during the pulse. The selection of RGA is highly
306 important, and two systems were tested as part of this work: a Hiden 3F PIC and the Stanford Research
307 Systems (SRS) RGA200 both of which have been used in TAP systems developed by Gleaves [25]. It
308 was found that the radial asymmetry that is present in the Hiden 3F PIC ioniser caused the signal
309 response to be modified as a function of RGA orientation, whereas the SRS RGA200 is radially
310 symmetric, and orientation had no effect on the signal. The SRS RGA200 also has the benefit of being
311 lower cost while maintaining a wide dynamic range of detection, and also being simpler to interface
312 with via freely available LabVIEW drivers. Based on the four core principles outlined earlier for the
313 development of the miniTAP it was decided that the SRS RGA200 was the optimal RGA for this system.
314

315 In the second step, after a short settle time required by the RGA to allow the M/Z value to be
 316 set, the computer simultaneously records a timestamp and sends a command to the pulse valve driver
 317 (Parker IOTA One) to initiate the pulse. The commercial pulse valve driver was found to be able to
 318 reliably generate pulses with $< 3\%$ pulse-to-pulse deviation (Figure 7A) similar to other systems and
 319 was able to vary the pulse intensity with microsecond precision (Figure 7B) with typical operation in
 320 the $\sim 105 \mu\text{s}$ range. It should be noted that we have found that the pulse width required to get an
 321 equivalent pulse size will vary slightly from valve to valve (and even from driver to driver). The pulse
 322 valve driver is simple to interface with using standard serial communication in LabVIEW, and outputs
 323 a corresponding +5V TTL signal when the valve is triggered. The Parker IOTA One driver has also
 324 been successfully used in the Delft TAP system [33]. While the driver is easily sourced, it remains one
 325 of the most expensive components in the miniTAP system, meaning that, if possible, a home-built driver
 326 may be more optimal.



327 **Figure 7.** Characterisation of the pulsing system used in miniTAP. A) Integrated raw signal as a
 328 function of pulse number for Ar pulsing at $108 \mu\text{s}$. B) Pulse size as a function of pulse width. C)
 329 Overlaid normalised exit flux for 5 Ar pulses at $108 \mu\text{s}$ pulse width. D) Raw signal for a single pulse
 330 of Ar with a pulse width of $97 \mu\text{s}$. E) Raw signal for a single pulse of Ar with a pulse width of $114 \mu\text{s}$.
 331 F) Normalised exit flux for pulses ranging from $98 - 114 \mu\text{s}$. Pulses are consistent with $< 3\%$ pulse-to-
 332 pulse deviation and no change in pulse shape. Signals across 200x dynamic range are clearly measurable
 333 and no change in pulse shape occurs with increasing pulse intensity.
 334
 335

336 In the final step, upon receipt of the command from the computer, the pulse valve driver
 337 simultaneously fires the pulse valve (Parker Miniature High Speed Vacuum Valve) and triggers the data
 338 collection on the data acquisition (DAQ, LabJack T7) device. The Parker Miniature High Speed
 339 Vacuum (MHSV) valves pair easily with their corresponding drivers (Parker IOTA One) and require
 340 no external tuning or modification. The valves are simple to repair, but we have found that the
 341 operational lifetime of the valve when used with the IOTA One driver is significant such that a single
 342 valve has been used for > 3 years for $> 100 \text{ K}$ pulses with no maintenance or drifting of the pulse
 343 intensity. The synchronisation and normalisation of the data (such that $t = 0$ is set upon receipt of the
 344 trigger) is all performed by the LabJack T7 DAQ device. The LabJack can be triggered in “stream”
 345 mode using the external 5V TTL signal from the IOTA One, which is reliably triggered so that $t = 0$ is
 346 consistently set between pulses (Figure 7C). The LabJack will then sample the corresponding stream at

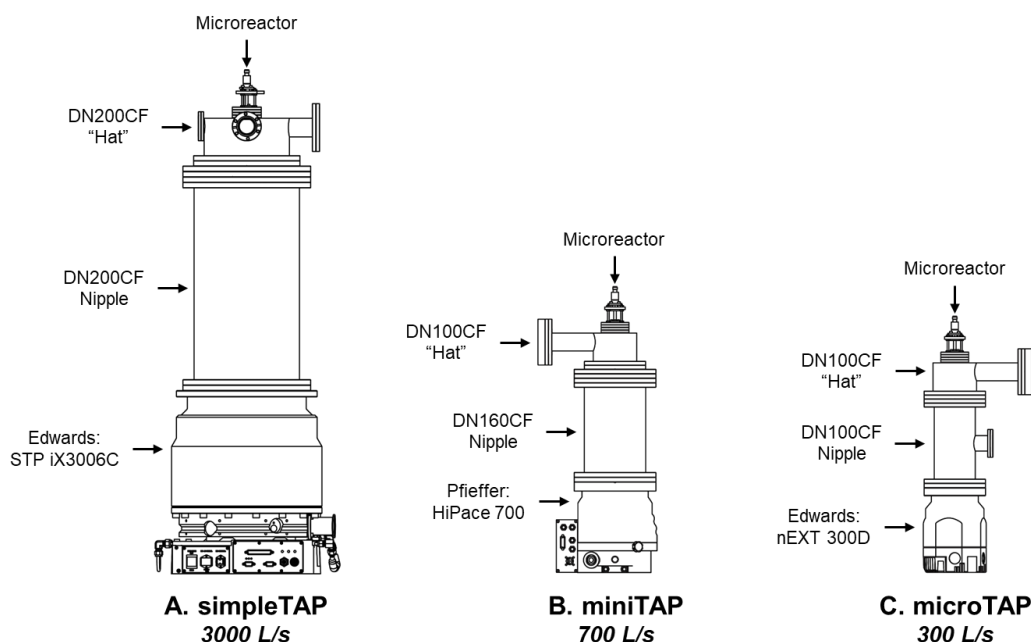
347 the pre-set frequency with minimal noise. The LabJack also interfaces to the computer via freely
348 available LabVIEW drivers. The signal from the RGA is first passed through a SRS SR570 current
349 preamplifier set to 100 nA/V gain, high bandwidth mode, with a 300 Hz 6dB lowpass filter. Extreme
350 care must be taken when using a current preamplifier, as if the bandwidth of the preamplifier is
351 sufficiently low it can broaden the exit flux response, causing misinterpretations of results. Other current
352 preamplifiers (Ithaco 2111, Keithly 427) were also tested, but it was found that the SR570 provided the
353 highest signal to noise when paired with the SRS RGA200, providing > 200x dynamic range of
354 detection (Figure 7D-F) at a fixed gain with no change in pulse shape. Once the signal from the
355 preamplifier has been recorded by the DAQ device for the given collection time, the recorded data is
356 sent to the computer and is saved and exported. The pulsing sequence can then be repeated as many
357 times as desired.

358
359

360 6. Confirming the TAP experiment

361

362 As part of this work, three TAP systems were developed utilising the same core components as the
363 miniTAP. First, the simpleTAP (Figure 8A) was built, which uses a large turbomolecular pump
364 (Edwards STP iX3006C, 3000 L/s pumping speed) that is connected to a DN250CF nipple (20.5" OAL)
365 which is connected to a DNCF200 hat chamber. The simpleTAP was developed to be analogous in size
366 and pumping efficiency to the Gleaves TAP system, but instead uses a turbomolecular pump and the
367 simplified pulsing system. Second, the miniTAP (Figure 8B) was built which has been described in the
368 previous section. Finally, the microTAP (Figure 8C) was built which uses a small turbomolecular pump
369 (Edwards nEXT 300D, 300 L/s pumping speed) that is connected to a standard DN100CF nipple or
370 DN100CF to DN35CF reducer tee (8.5" OAL) and uses the same DN100CF hat as the miniTAP. The
371 goal was to identify if precisely defined TAP experiments were feasible on simplified turbomolecular
372 pumping systems, and if so, to identify the minimum pumping speed required to ensure that the
373 precisely defined TAP conditions can be met.



374

375 **Figure 8.** The three TAP systems developed as part of this work. A) The simpleTAP which uses a large
376 3000 L/s turbomolecular pump. B) The miniTAP which uses the medium sized 700 L/s turbomolecular
377 pump. C) The microTAP which uses a small 300 L/s turbomolecular pump. All TAP systems utilise the
378 same pulsing system and microreactor.

379

380 To ensure that the exit flux curves can be precisely defined, the three characteristics outlined
 381 by Yablonsky in 1997 must be met (see section 3). The first characteristic is that: *The governing*
 382 *transport phenomena is Knudsen Diffusion*. The requirements are that the pulse size is sufficiently small
 383 that only diffusive transport occurs which typically requires pulse sizes in the range of $\leq 10^{16}$ molecules
 384 per pulse. This has the added benefit of also enforcing condition two: *The pulse size is sufficiently small*
 385 *that the experiment is state defining*. The pulse size can be reliably calculated by simply pulsing gas
 386 from a small fixed pre-defined volume and measuring the pressure drop as a function of pulse number.
 387 By isolating the valve and continuously pulsing Ar, the pulse size in our system under typical pulsing
 388 conditions was determined to be $\sim 5 \times 10^{14}$ molecules per pulse (Figure 7B). However, to confirm
 389 Knudsen Diffusion is the primary transport phenomena two parameters can be used. First, the pulse
 390 shape must be independent of the size of the pulse (Figure 7F), and second, the mean residence time of
 391 the reactor must be linearly dependent on the mass and the temperature. For a noninteracting gas (e.g.,
 392 an inert gas, or a reactive gas through a bed packed with inert powder) equation 1 can be redefined
 393 using:

$$\varepsilon_b \frac{\partial C_A}{\partial t} = D_{eA} \frac{\partial^2 C_A}{\partial z^2} \quad (10)$$

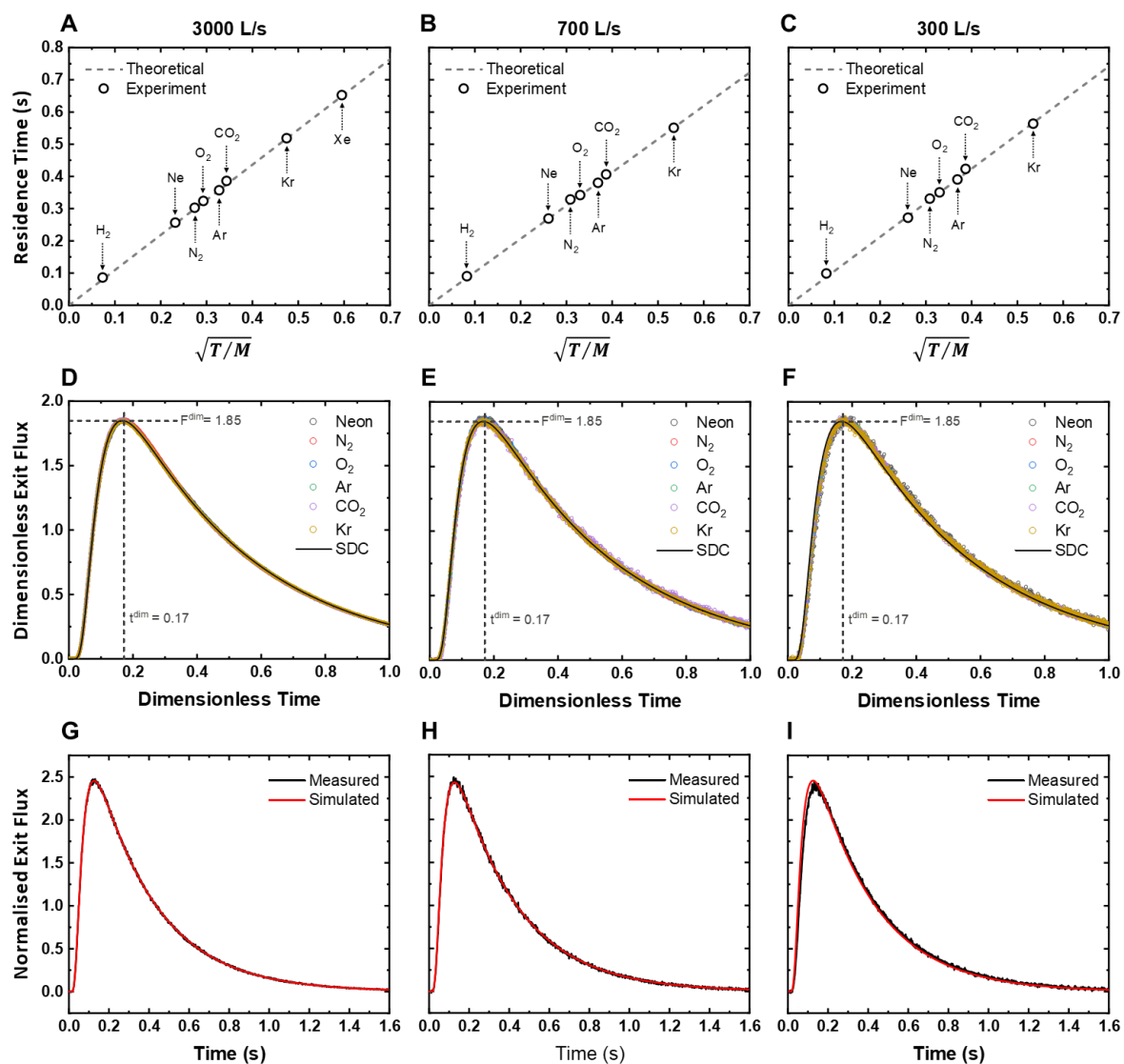
394 with the Knudsen Diffusivity being linearly dependent on the mass and temperature of the gas through
 395 the following relationship [43]:

$$D_{eA} = \frac{\varepsilon_b d_i}{3\tau} \sqrt{\left(\frac{8RT}{\pi M}\right)} \approx \sqrt{\frac{T}{M}} \quad (11)$$

396 where d_i is the diameter of the interstitial voids (cm), τ is the tortuosity (cm/cm), T is the temperature
 397 (K), and M is the molar mass of the gas (kg/mol). The mean residence time (t_{res}) in the reactor can be
 398 calculated by taking the ratio of the first moment to the zeroth moment for the exit flux response, and
 399 is correlated to the Knudsen Diffusivity in a TAP system via the following relationship [8,44]:

$$t_{res} = \frac{M_1}{M_0} = \frac{\int_0^\infty tF(t) dt}{\int_0^\infty F(t) dt} \approx \frac{1}{D_{eA}} \approx \sqrt{\frac{M}{T}} \quad (12)$$

400 Therefore, if Knudsen diffusion is present, and the bed is noninteracting, the residence time of the gas
 401 is linearly dependent on the mass of the gas and the temperature of the bed. As there are often minor
 402 temperature gradients in the TAP reactor system, the linear relationship with temperature is often less
 403 well defined, therefore the temperature was fixed at 100 °C for the simpleTAP and room temperature
 404 for mini and microTAP experiments and only the mass of the gas was varied. The increased temperature
 405 for the simpleTAP measurements was due to normalisation with a separate set of data and does not
 406 affect the discussion here. In Figures 9A-C the residence time for a series of gases (H₂, Ne, N₂, O₂, Ar,
 407 CO₂, Kr, Xe) pulsed through a microreactor packed with sand (sieved between 50-70 mesh, 5.881 cm
 408 length, 0.464 void fraction) as a function of mass are recorded. For all reactors we find that Knudsen
 409 diffusion is the primary transport mechanism as a precise linear relationship between the residence time
 410 and the mass of the gas was found (Figures 9A-C). Some minor deviation from the linear relationship
 411 was seen for CO₂ which we prescribe to some small interaction between CO₂ and the sand, as at higher
 412 temperatures the deviation was removed.
 413



414
 415 **Figure 9.** A-C) Mean residence time recorded as a function of the mass and temperature of the gas. The
 416 theoretical curve is calculated by scaling the residence time measured for Argon at room temperature.
 417 D-F) Dimensionless exit flux curves plotted against the standard diffusion curve (SDC) with the key
 418 time and flux characteristics overlaid. G-I) Normalised exit flux compared to the fit of a one-zone (1Z)
 419 model. All exit flux curves were taken as the average of 5-10 curves to minimise noise. All pulses were
 420 performed using the same microreactor packed with sand (sieved between 50-70 mesh). Pulses were
 421 performed using the A), D), G) SimpleTAP, B), E), H) miniTAP, and C), F), I) microTAP systems.
 422 Knudsen diffusion is the dominant transport phenomena in all systems tested, but only for the
 423 simpleTAP and miniTAP systems was the transport solely defined by the packed bed of the
 424 microreactor.

425
 426 After confirming that Knudsen diffusion is the primary transport mechanism in the reactor, the
 427 final step to confirm if quantitative modelling of the TAP experiment is possible is to check if condition
 428 3 is met: *The transport (and as such, the shape of the exit flux curve for an inert gas) is solely defined*
 429 *by the characteristics of the microreactor's packed bed, with no pre- or post-diffusive zones affecting*
 430 *the shape of the exit flux.* In order to confirm that the transport is solely defined by the microreactors
 431 packed bed, two checks can be made. First, the microreactor must be packed in the “one-zone”
 432 configuration which is when the packed bed consists of solely a uniform sized inert powder. Next, the
 433 exit flux curves for pulses through the “one-zone” reactor can then be converted to dimensionless exit
 434 flux and dimensionless time as defined by Yablonsky [8]:

$$F_A^{dim} = F_A^{norm} 2t_{res} \quad (13)$$

$$t_A^{dim} = \frac{F_A^{norm}}{2t_{res}} \quad (14)$$

435 where F_A^{dim} is the dimensionless exit flux of A, and t_A^{dim} is the dimensionless time for species A. When
 436 plotted in dimensionless exit flux and dimensionless time, all the exit flux curves for a noninteracting
 437 packed bed collapse down to a “master” curve independent of mass and temperature. For a one-zone
 438 reactor the master curve has very well-defined properties and is known as the Standard Diffusion Curve
 439 (SDC) [8]. First, in the SDC the time of maximum intensity occurs at a dimensionless time of 0.17, and
 440 the maximum intensity of the dimensionless exit flux is 1.85. Any deviation from the SDC (while under
 441 Knudsen Diffusion conditions) can be directly related to the effect of pre- or post-diffusive zones on
 442 the shape of the exit flux. The exit flux curves used in the residence time experiment (Figures 9A-C)
 443 were converted to dimensionless exit flux and dimensionless time using equations 13 and 14 and are
 444 shown in Figures 9D-F. For the simpleTAP and miniTAP cases, the dimensionless curves lie exactly
 445 on the SDC, but for the microTAP system there is a slight delay between the measured dimensionless
 446 curves and SDC. This would indicate that some pre- or post-diffusive zone exists in the microTAP
 447 system. As the same microreactor and pulse valve is used in all three systems, we attribute this right-
 448 shifting of the response to a post-diffusive zone. This most likely arises as the small turbomolecular
 449 pump (300 L/s pumping speed) used in the microTAP is not sufficient to remove the gas from the
 450 system without it being backscattered (Figure 5). For all systems, the dimensionless exit flux curve for
 451 H₂ did not lie on the SDC (Figure S3) which was expected due to the difficulty that turbopumps have
 452 with pumping H₂, but as mentioned previously this is not considered a large downside due to the
 453 imprecise nature of the M/Z 2 response.

454

455 The final confirmation that the transport is solely defined by the microreactors packed bed can
 456 be made by fitting a model “one-zone” exit flux curve to the experimental data. The analytical form of
 457 the one-zone model in the Laplace domain has been derived as [9]:

$$F_{exit}(s) = \frac{1}{\cosh\sqrt{st_{res}}} \quad (15)$$

458 It is possible to express the Laplace function in the Fourier domain via the following relationship [45]:

$$s = \omega i \quad (16)$$

459 where:

$$\omega = \frac{2k\pi}{t_{max}} \quad (17)$$

460 with t_{max} being the sampling time (s) of the TAP pulse, and where:

$$k = \frac{-ft_{max}}{2} \dots + 1 \dots \frac{ft_{max}}{2} \quad (18)$$

461 Where f is the sampling frequency of the pulse (Hz). The full derivation of these equations is far outside
 462 the scope of this paper, but Equation 16 can then be inserted into equation 15 and the curve simulated
 463 in the Fourier domain, which can easily be converted into the time domain using an inverse Fast Fourier
 464 Transform algorithm. Using MATLAB, the one-zone model was fit to the normalised exit flux curves
 465 for an Argon pulse in each reactor system by varying t_{res} using the nonlinear least-square fitting
 466 function `fmincon`. The exit flux curves (and corresponding model fit) are shown in Figures 9G-I. It was
 467 found that the model is able to precisely recreate the normalised exit flux curves for Argon in the
 468 simpleTAP and the miniTAP reactors using the same simulated curve. However, for the microTAP
 469 reactor the same simulated curve from the simpleTAP and miniTAP reactors does not match the
 470 experimental exit flux.

471
 472 Based on the evidence from the residence time scaling, dimensionless exit flux, and the model
 473 fitting, the simpleTAP and miniTAP reactor systems fulfil all three requirements for the quantitative
 474 modelling of TAP experiments. We find that the microTAP reactor contains a post-diffusive zone,
 475 which means that it can still be used for TAP experiments qualitatively but cannot be used for
 476 quantitative modelling using currently existing methods in the TAP community. While this limits the
 477 scope, due to the primary transport method being Knudsen diffusion, qualitative insight into reaction
 478 kinetics is still possible as all the dimensionless curves collapse onto each other (Figure 9F). Further,
 479 due to the molecular level precision the microTAP can still be utilised for compositional site counting.
 480 The reactors in this work empirically demonstrate that the TAP experiment and modelling can be
 481 performed on systems much smaller and simpler than was previously imagined. Contrary to popular
 482 thinking, large pumping speeds and large vacuum systems are not required for the TAP experiment.
 483 From our development of the TAP systems in this work we have found anecdotally that excess volume
 484 can instead negatively affect the TAP pulse shape. When the simpleTAP was extended with a DN250CF
 485 nipple to increase the total volume of the vacuum chamber, we found that the pulse response was
 486 broadened, indicating that a post-diffusive zone was generated. Further, when the linear nipple was
 487 replaced with a spherical vacuum chamber to increase the volume, broadening was also detected. We
 488 postulate that the geometry and the aspect ratio of the vacuum system are instead more important,
 489 although we should note that these experiments were not performed methodically due to time and
 490 monetary constraints. As the deviation between the SDC and the dimensionless miniTAP curves is only
 491 minimal, it could be hypothesised that a microTAP system with precisely the correct geometry and
 492 aspect ratio could be designed such that no post-diffusive zone exists, but we were unable to design
 493 such a system.

494 495 **7. Application of the simplified TAP reactors**

496
 497 Although the TAP systems developed as part of this work utilise a single valve setup, through multi-
 498 pulse titration experiments precise kinetic and compositional information about catalytic systems is
 499 possible. By pre-covering a catalyst in a probe reagent (e.g., CO) and titrating it off with a reactant (e.g.,
 500 O₂) it becomes possible to simultaneously probe the intrinsic kinetics of different sites, while also
 501 quantifying their distribution on the surface. To demonstrate this capability, CO was preadsorbed over
 502 a Pt/SiO₂ (2 nm nanoparticle size, 0.7% Pt weight loading) catalyst at 80 °C and the resulting CO was
 503 sequentially titrated using O₂ pulsing at 80 °C (Figure 10A). The full details relating to the catalyst
 504 synthesis, characterisation, and modelling used here are provided in our previous publication [19]. As
 505 the preadsorbed CO is consumed by the O₂ pulses it becomes possible to generate a *kinetic snapshot*
 506 (Figure 2) of the CO oxidation reaction across the entire range of CO coverages probed in the titration

507 experiment. Assuming a stoichiometry of 1 CO₂ molecule produced by each adsorbed CO molecule,
 508 the relative CO coverage can be approximated by counting the total amount of CO₂ produced [17,19,29].
 509 By fitting a model to each individual pulse set throughout the experiment, the precise kinetics of the
 510 irreversible reaction of O₂ with adsorbed CO as a function of CO coverage and the amount of CO₂
 511 produced by each pathway can be resolved.

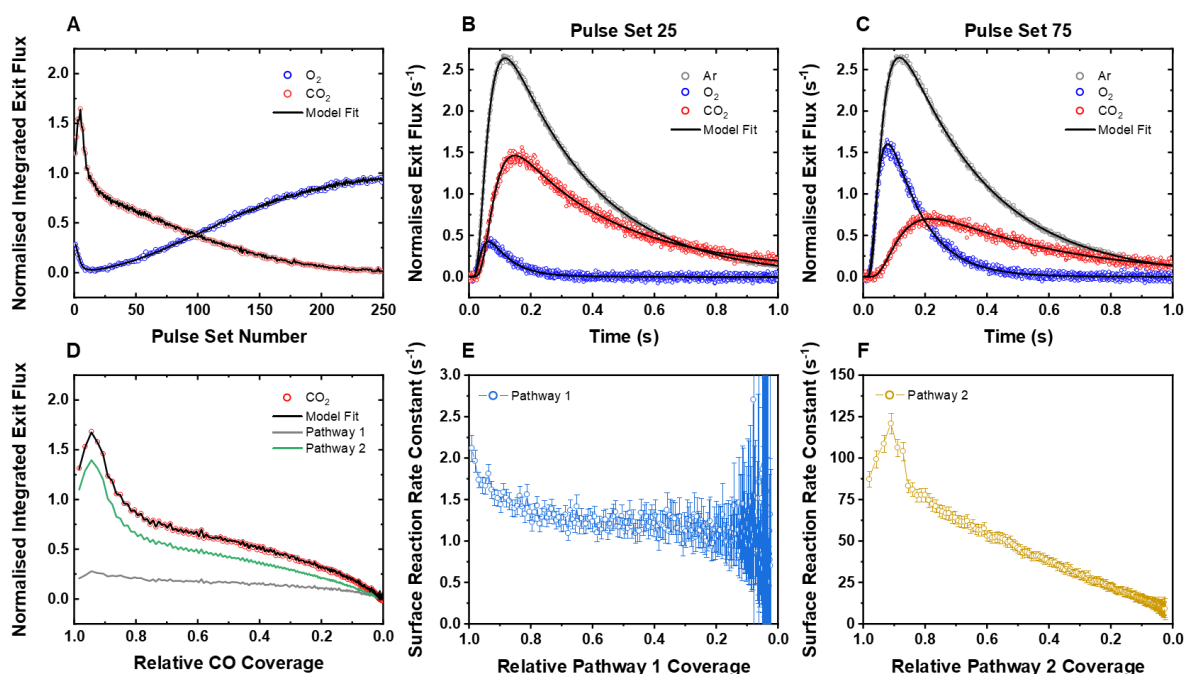
512

513 **Table 1.** Pathways included in the three-pathway model for irreversible adsorption/reaction of O₂ with
 514 the CO covered 2nm Pt/SiO₂ catalyst. The apparent adsorption/reaction constant is represented by $k'_{a,n}$
 515 and the intrinsic reaction constant for the surface reaction step is denoted by $k_{r,n}$ where n is the number
 516 of each pathway. IS represents an intermediate surface species.

517

Pathway	$k'_{a,n}$	$k_{r,n}$
1	O ₂ → IS1	→ CO ₂
2	O ₂ → IS2	→ CO ₂
3	O ₂ → 2O*	

518



519

520 **Figure 10.** Results from fitting the three-pathway model to the titration experiment where preadsorbed
 521 CO on a Pt/SiO₂ catalyst was sequentially reacted off with O₂ pulsing at 80 °C. A) The integrated
 522 normalised exit flux recorded for O₂ and CO₂ (open circles) and the corresponding model fit (solid line).
 523 B-C) Exit flux curves for Ar, O₂, and CO₂ and their corresponding model fit using the three-pathway
 524 model. D) Deconvoluted CO₂ production from each pathway as a function of relative CO coverage. E-
 525 F) The surface reaction rate constants and corresponding 95% confidence intervals (k_{r1} and k_{r2}
 526 respectively) for pathways 1 and 2 as a function of their respective coverages.

527

528 In our previous work, we identified two pathways for the reaction of adsorbed CO with gaseous O₂
 529 over the 2 nm Pt/SiO₂ catalyst [19]. A fast pathway, which we have correlated to well-coordinated CO
 530 binding sites (e.g., terrace sites), and a slow pathway, which we have correlated to under-coordinated
 531 CO binding sites (e.g., edge sites) respectively. A third pathway for the irreversible adsorption of O₂
 532 was also included in the model (Table 1). To calculate the kinetics, first a Thin-Zone TAP reactor model
 533 was generated using Multi-Zone TAP Reactor Theory [9,19,37] and that model was fit to the exit flux
 534 curves of every single pulse set in the experiment (Figures 10B, 10C). All data processing and

535 regression was performed in the MATLAB programming environment using the lsqcurve fit function,
536 with the 95% confidence intervals estimated using the nlparci function.

537

538 Using the calculated kinetic coefficients, it becomes possible to deconvolute the O₂ conversion from
539 each pathway in each pulse set with the following relationship [19]:

$$X_{O_2,n} = \frac{k'_{a,n}(L/2D_{eO_2})}{1 + (k'_{a,1} + k'_{a,2} + k'_{a,3})(L/2D_{eO_2})} \quad (19)$$

540 Where $k'_{a,n}$ is the adsorption/reaction rate constant for pathway n . By applying a carbon balance of 2
541 CO₂ molecules produced per O₂ consumed, it is simple to then calculate how much CO₂ is produced by
542 the under-coordinated sites (pathway 1) and the well-coordinated sites (pathway 2) individually (Figure
543 10C). By summing the total amount of CO₂ produced by each pathway the ratio of sites can be
544 calculated. For the 80 °C titration experiment we find that 29.1% of the sites are under-coordinated and
545 70.9% of the sites are well-coordinated. Interestingly, this is close to the ratio expected for a ~2 nm
546 truncated icosahedron shaped nanoparticle, but it should be stated that this alone does not provide
547 sufficient evidence of the nanoparticle shape. Further, each pathway's corresponding surface reaction
548 rate constant $k_{r,n}$ can be evaluated relative to the coverage of the CO species in each pathway (Figures
549 10E, 10F). Similar to our previous work [Kim preprint] we find no strong dependence on coverage for
550 the slow reaction with under-coordinated sites (pathway 1) at 80 °C. For the fast reaction with the well-
551 coordinated sites (pathway 2) we find a strong linear dependence on the relative coverage of the species
552 which indicates that adsorbate-adsorbate interactions are present, destabilising the adsorbed CO,
553 increasing the rate of reaction at higher coverages. This coverage dependent binding energy of CO has
554 been observed experimentally on Pt(111) single crystals [46], and from DFT simulations of CO covered
555 Pt nanoparticles [47].

556

557 8. Conclusion

558

559 In summary, we have designed a simplified Temporal Analysis of Products reactor that can be
560 assembled using low-cost and readily available components while still maintaining the majority of the
561 features present in the Gleaves system. Contrary to common thinking, we show that large vacuum
562 chambers and large pumping systems are not required to perform well-defined TAP experiments. When
563 only qualitative kinetic insight is required, less well-defined TAP experiments are possible on systems
564 using even smaller turbomolecular pumps. While the designs outlined in this work lack some of the
565 features of the more commonly used Gleaves systems, we find that precise kinetic, mechanistic, and
566 compositional insight is still feasible with a single-valve system using multi-pulse titration experiments
567 coupled with kinetic modelling. Using the case study of the oxidation of pre-adsorbed CO over 2nm
568 Pt/SiO₂ catalysts, we are able to precisely resolve the composition of sites, and the site and coverage
569 dependent kinetics using a Thin-Zone Multi-Zone TAP Reactor model.

570

571 It is our hope that with these systems the barrier to entry to the TAP experiment is significantly
572 decreased, allowing an entirely new generation of researchers to contribute to the field that was first
573 started by John Gleaves over forty years ago.

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583 **9. List of Symbols**

584

A	Cross-sectional area of the reactor (cm)
C_A	Concentration of gaseous species A (mol/cm ³)
D_{eA}	Knudsen diffusivity of gas A (cm ² /s)
F_A	Exit flux of gas A (mol/cm ² /s)
F_A^{dim}	Dimensionless exit flux
F_A^{norm}	Normalized exit flux of A (1/s)
N_A	Number of molecules of gas A in the inlet pulse (mol)
S_V	Surface area of catalyst per volume of catalyst (cm ² /cm ³)
$X_{O_2,n}$	Conversion of O ₂ from pathway n
d_i	Diameter of the interstitial voids (cm)
$k'_{a,n}$	Apparent adsorption/reaction constant for pathway n
k_a	Adsorption rate constant (cm ³ /mol/s)
k_d	Desorption rate constant (1/s)
$k_{r,n}$	Intrinsic surface reaction constant for pathway n
t_A^{dim}	Dimensionless time
t_{max}	Sampling time of the TAP pulse (s)
t_{res}	Mean residence time of gas in the reactor (s)
α_s	Concentration of active sites on the catalyst (cm ² /s)
ϵ_b	Reactor void fraction
θ_*	Coverage of free sites
θ_A	Coverage of adsorbed species A
L	Reactor length (cm)
M	Molar mass (kg/mol)
T	Temperature (K)
f	Sampling frequency of the pulse response (Hz)
s	Laplace variable
t	Time (s)
z	Axial coordinate of the reactor (cm)
τ	Tortuosity (cm ² /cm ²)

585

586

587 **Declaration of Competing Interests**

588

589 The authors declare that they have no known competing financial interests or personal relationships that
590 could have appeared to influence the work reported in this paper.

591

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593

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597 over the last 10 years. The authors would also like to acknowledge Samantha Le for generating some
598 replicate data.

599

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601

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