

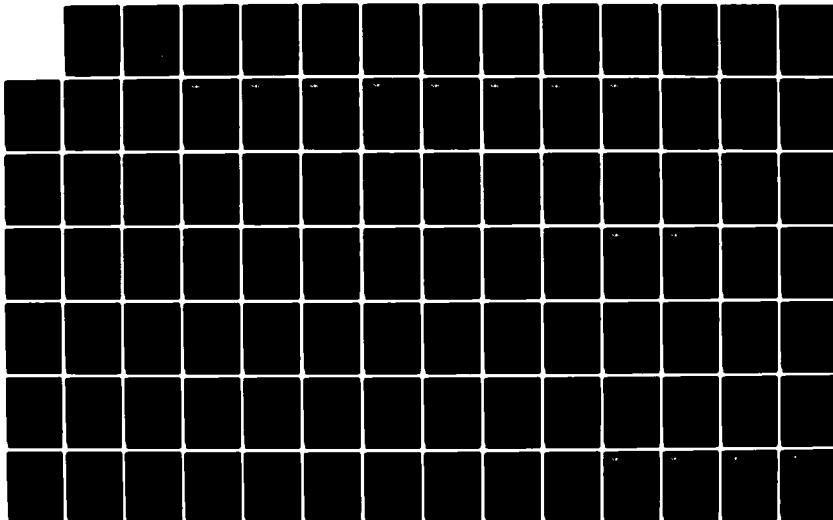
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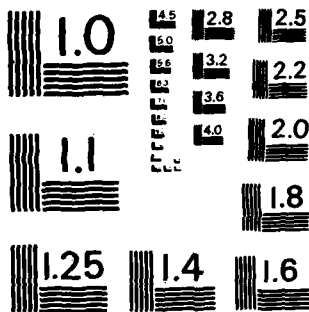
FINGER PIER/SPINE PIER CONNECTION FOR THE EXPEDITIONARY
PIER(U) LIN (T Y) INTERNATIONAL SAN FRANCISCO CA
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NATIONAL BUREAU OF STANDARDS-1963-A

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NAVY PIER CONCEPTS
REPORT NO. 2/84

ENGINEERING SUPPORT PIER

CONNECTION POINT

EXPERIMENTAL PIER

AD-A146 144

SUBMITTED TO:

DEPARTMENT OF THE NAVY

OFFICE OF NAVAL RESEARCH

ARLINGTON, VIRGINIA

SUBMITTED BY:

T.Y. LIN INTERNATIONAL

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**FINGER PIER/SPINE PIER CONNECTION
FOR THE EXPEDITIONARY PIER**

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| 20. ABSTRACT (Continue on reverse side if necessary and identify by block number) A critical component of the floating expeditionary pier concept is the connection between the finger piers and the main body or spine. This report provides an assessment of the present design capabilities for such a structure. Shock absorbing system and hinge pin design are identified as particularly difficult design problems. | | |

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FINGER PIER/SPINE PIER CONNECTION FOR

THE EXPEDITIONARY PIER

1. INTRODUCTION

The connection between the finger pier and the spine pier in the expeditionary pier concept was selected for further development in the current contract year with the Office of Naval Research, mainly because it represents one of the more serious technological obstacles that had to be overcome before the expeditionary pier could become a reality in the form it was originally conceived. To recap, the expeditionary pier that provides berthing facilities to 6 combatant ships of the destroyer class has the shape of an arrow on plan, and moored by a *single-point mooring*, partly to reduce wave and current forces to a minimum. The finger piers form the extensions to the arrow head, attached at about 45 degrees with the axis of the spine pier by means of a connecting structure, which is the subject of this report (referred to as the finger/spine hinge joint in previous reports). During tow, the finger piers are retracted and stowed alongside the spine pier. The general arrangement showing the relationship between the finger pier and the spine pier is presented in Figure 1.

As indicated above, the purpose of this report is to test the feasibility of the retractable finger pier concept, and to assess the technological gap, if any, that separates it from the state of the art. The undertaking proved to be more formidable than expected. However, enough had been accomplished within the limited time for the study to understand the problem better, and to produce a set of reasonable figures for the preliminary design of the connection.

2. DESIGN CONSIDERATIONS

In order to quantify the forces that can be used in the design of the connection structure, it is first necessary to establish the conditions for which the connection is to be designed. In fact, there is only one such condition that needs to be considered for the purpose of this report; namely, the environment conditions under which the finger piers will operate. There are other conditions, but they are not expected to be of significant magnitude to influence the outcome of the order-of-magnitude assessment, and may be disregarded to simplify the procedure.

Since the finger pier will be in operation only when the expeditionary pier is safely anchored in sheltered waters, it is reasonable to assume that the connection structure will not be subjected to environmental conditions more severe than Sea State 4. This, therefore, has been assumed as the basis for the connection design.

3. THE ABBREVIATED ANALYTICAL SOLUTION

It is recognized at the outset that an in-depth analysis of the connection with its multiple degree of movement under exciting conditions that can emanate from a dozen sources would be an extremely complex, exacting and time-consuming exercise. An abbreviated, or a short-cut solution must be found that will produce reasonable answers within the available time. As explained below, the abbreviated method consists simply of considering the most significant factors in the analysis, ignoring the rest, and of making broad assumptions on boundary conditions that are not unreasonable for the purpose of getting some quick answers.

The abbreviated method was partly based on the following observations about the connecting elements (links and shear key), see Figures 2 and 3.

- a. The system is extremely rigid in restraining horizontal movements, huge forces will be developed in the elements as a consequence to inhibiting the pier against wave induced motion.
- b. The relative size difference between the finger pier and the spine pier is such that the analysis could justifiably be simplified by considering the finger pier to be connected to a fixed rather than another floating body. This assumption presupposes that the effect due to phase differences in the motion of the finger and the spine piers will be small and can be neglected in this evaluation. An analytical model has been constructed on this basis. If a more exact analysis is required, the above mentioned behavior can be determined by modelling the finger and the spine piers together and then obtain a time history of motions for the desired sea state. It is also observed that the forces due to wind current and wave drift should be more or less constant, much lower than the transient wave forces induced by the vehicle motion.

Based on the above observations and assumptions, an appropriate model and approach were developed. The approach is to determine the free floating equations of motion (dynamic matrix, and displacement and force vectors), and then by including the stiffness of the connection system in the free-floating dynamic matrix, solve the equations of motion for displacements. The forces in the connection elements are calculated based on the determined displacements.

The analysis began with determining the free floating motions of the finger pier for various sea headings. The connection elements are so configured that they resist forces in the horizontal plane, tension in the links is expected to be caused mainly by yaw moments. Forces due to surge will not be as significant because of the small beam of the pier relative to its length. Additional forces will be caused by pitching of the finger pier relative to the spine pier. These forces could be controlled to a great extent by narrowing the contact depth between the 2 piers.

Strip theory was used to compute the free floating motions of the pier, modelled as a stationary vessel, and a Sea State 4 spectrum having 6 feet significant wave height, and mean period of 5.5 seconds. Figure 1-A (Appendix A) illustrates the analytical model description.

A description of the mathematical model of the connection structure is shown in Figure B-1 (Appendix B). The model assumes that all vertical motions at the connection interface are unconstrained for pitch and heave motions. The connector, or link, is designed to resist forces generated by yaw, surge, and pitch, and the shear key is designed to resist forces due to sway.

Tolerance at shear key interface and the hinges in the links will provide the freedom of movement in the vertical direction.

A detailed explanation of the analytical model and its limitations are given in greater details in the Appendeses following this report.

4. DISCUSSION OF RESULTS

The magnitude of the free floating motions for various headings can indicate the critical loading conditions for the connection elements. A wave heading of 110° (from the longitudinal axis) was found to produce the maximum motions for the imposed irregular sea. Hence, further analysis was done only for the above wave heading.

The drift forces due to wind, current and wave drift were added to the calculated transient forces. The forces in the links were determined to be in the order of 6,000 kips tension, or a reversible tension and compression of 5,000 kips based on the system design. The force in the shear key was found to be 1,300 kips.

If the links are absolutely rigid, a tension-compression couple of 5,000 kips is developed in the links in order to resist the yaw moments. It is structurally undesirable to develop compression in a slender member such as the link. The compression could be eliminated if the link was allowed to displace when in compression and the finger pier could contact (or bear against) the spine pier. This effect somewhat shortens the couple arm resisting the yaw moments, the tension is estimated to be 6,000 kips and the compression component of the couple is provided by the bearing stresses developed by the contact of the two piers.

The analysis showed considerable heave (5 ft. relative to spine pier) and pitch displacements. In order to keep the link forces low and to conform with the assumptions of the analytical model, the heave and pitch displacements should be allowed. For instance, considering a total length of 30 ft. for the link, a 5 ft. vertical displacement requires an axial extension of about 5 inches in the link.

The preceding discussion indicates that the link should have a "shock absorbing" ability or in other words an "extendable" link is desired. For design purposes, the object will be to provide an axial extension of up to 18 inches before the load capacity of the system is exceeded. A proposed design for an "extendable" link is discussed in the following section.

The shape and dimensions of the finger pier may be altered to ensure efficient behavior. The effects of pitching can be minimized by reducing the depth of the contact area of the finger and spine piers. See Figure 6. The forces in the links can be reduced by increasing the distance between the two links. The effect of the forces in the links for a particular value of yaw moment, versus the distance is illustrated in Figure 8.

5. THE CONNECTING SYSTEM

An obvious first solution is represented by the pinned joint used by the offshore industry to connect the "Stinger" to the barge in the pipe-laying operation. The difference is however the magnitude of the forces that the joint has to deal with. For the stinger-type connection, the pin would have to be much larger and heavier, making connection in the relatively open sea difficult. It is also not possible for the finger pier to be swung around a pinned joint, with the pin aligned in the horizontal direction. If this method of connection is used, it will be necessary to disengage the connection completely when the finger pier is not in use, and to attach it to the spine pier by other means.

The following considerations therefore govern the design.

- a. A system that lends itself to rapid installation and disengagement. This means the system should preferably be located on top of the deck for easy access, control and operation.

- b. A system that provides restraint in the horizontal direction, but relative freedom of movement in the vertical direction.
- c. A system that incorporates "shock-absorbing" capabilities to reduce the huge forces generated by pier motions, and thereby bringing the design of the connection closer to the state of the art.

The design that had resulted from the above described constraints and considerations is shown in Figure 4. The member has a length of about 30 feet. There are two hinges at each end (labeled as horizontal hinge and vertical hinge), that provide vertical and horizontal rotational freedom. To avoid any moments on the vertical hinge due to inclined loads on the horizontal hinge, the "frame leaf" or the stationary part of the horizontal hinge is restrained by an anchor which is free to slide in a circular guide track. By an appropriate alignment of the two hinges (as shown in Figure 4), it is assumed that the vertical component of the inclined load will be taken by the "sliding anchor" and the horizontal component will be uniformly distributed over the height of the vertical hinge.

Another unusual feature of the link is the hydraulic tension "shock-absorber". A shock-absorber to meet our requirements, such as a capacity of 6,000 kips, stroke of 12" to 18", and a smaller compressive stiffness compared to a tensile stiffness is not readily available but can be specially fabricated. If a single shock absorber is used, the cylinder size is estimated to be 32 inches O.D. and ultra high strength, aircraft quality materials would have to be used. A survey of the industry, indicates that a 32 inch shock-absorber can be fabricated within the state-of-the-art technology with some upgrading of existing manufacturing facilities. Another approach could be to use a cluster of two smaller shock-absorbers in parallel. Details of a proposed design by Taylor Devices Inc., New York, are shown in Figure 4-a.

The amount of steel estimated for each link is about 88 tons. The member

was designed using stress levels recommended by the American Welding Society code (AWS code). Grade 36 steel can be used for the members, but ultra-high strength steel, having higher stress levels than the AWS code recommended values, has to be used for the hinge pins in order to obtain practical dimensions. A total cost of \$360,000 is estimated for each link. This price includes the cost of the hydraulic shock-absorber which is about \$100,000.

6. ALTERNATIVE SOLUTION

The finger pier must be modified to better cope with the large forces, particularly the force generated by yaw moments on the two-point link connection. Having identified this as the prime force generator, one method to deal with it would be to spread the distance between the two connection points as much as possible. Thus if it is possible to increase this distance by 100%, the effect would be to reduce the yaw-induced force in the links by half. One might also taper the plan shape of the finger pier to that of perhaps half its present width of 80 feet, toward the end of the pier. The advantage of this modification is to bring the centre of gravity of the pier closer to the connection, thereby reducing the effects due to rotational forces.

Displacements at deck level due to pitching can be reduced by narrowing the depth of the contact area between the spine and finger piers. For a particular pitching angle the displacement at the deck level is directly proportional to the distance to the point of "pivoting".

The widening of the contact face at the connection, and the tapering of the pier have been combined in an alternative system shown in Figure 5. A proposed longitudinal section for the finger pier is shown in Figure 6. These modifications would be the first direct result of the further development of the retractable finger pier as described in this report.

7. PROBLEM AREAS

The design of the connection is generally within the state of the art. It would however take considerable time and effort to develop this concept to the application stage.

The biggest problem area is due to the escalation of scale as represented by the exceedingly large forces that must safely be handled by the connecting link structure, the shock-absorbing capacity, and the articulating mechanism in the connection system. The analysis part should therefore present the least problem. There is no shortage of computer software capable of solving dynamic problems connected with the pier. The program OSCAR has been used here only because it was readily available.

The problem pertaining to the design has to do with the development of equipment, particularly the hydraulic shock-absorbers. The fabrication of a large (32"O.D.) shock-absorber is not feasible within the present state of the art. The major portion of the total cost (100,000) of each shock absorber, is the cost of special high-strength, corrosion resistant materials. Further research may be feasible to develop more economical materials for our application.

It was felt that practical dimensions for the hinge pins could not be obtained by using the available design guidelines for fatigue loadings. The only way to obtain a reasonable design is to use ultra-high strength steel, with higher allowable fatigue stresses.

Figures 6 and 4 illustrate some rather unusual features of the connecting system. The proposed rub-strips and fenders at the interface of the finger and spine piers perform unusual functions and require to be developed. The

rub-strips need to have a low coefficient of friction, and at the same time durable enough to justify its use and cost. The design of the sliding anchor will also be complex. It is required to provide constraint in the vertical plane but is relatively free in the horizontal plane.

We would also require auxiliary equipment for extending and retracting the pier, e.g. large capacity winches with which to move the pier. These are not so unusual that they are not already available commercially.

8. CONCLUDING REMARKS

In the generic sense, the flexible connecting system as envisaged in this study, may be adapted to other purposes. For example, they could be used to join several barge-like vessels to form:

- a. Floating roadway to offshore installations.
- b. Floating platform for offshore installations.
- c. Floating breakwater for offshore harbour.

These possibilities are shown in Figure 7.

The constraint of time is particularly telling in a heavily analytical undertaking such as this report. Unlike some of the previous efforts, this report cannot therefore lay claim to any development or discovery of significance. It does however contribute to a better understanding of the problem connected with the hitching of the pier, therefore representing another step toward building up the technology for the retractable finger pier.

APPENDIX A

FREE FLOATING BEHAVIOR

Appendix A: FREE FLOATING BEHAVIOR

In order to determine the critical, wave loading conditions for the finger/spine joint, free floating response amplitude operators were calculated for sea headings of 180° , 160° , 135° , 110° and 100° . Motions were also calculated for a sea spectrum with a significant height of 6 ft. and mean period of 5.5 seconds. Fig. A-1 illustrated the orientation of the heading angles.

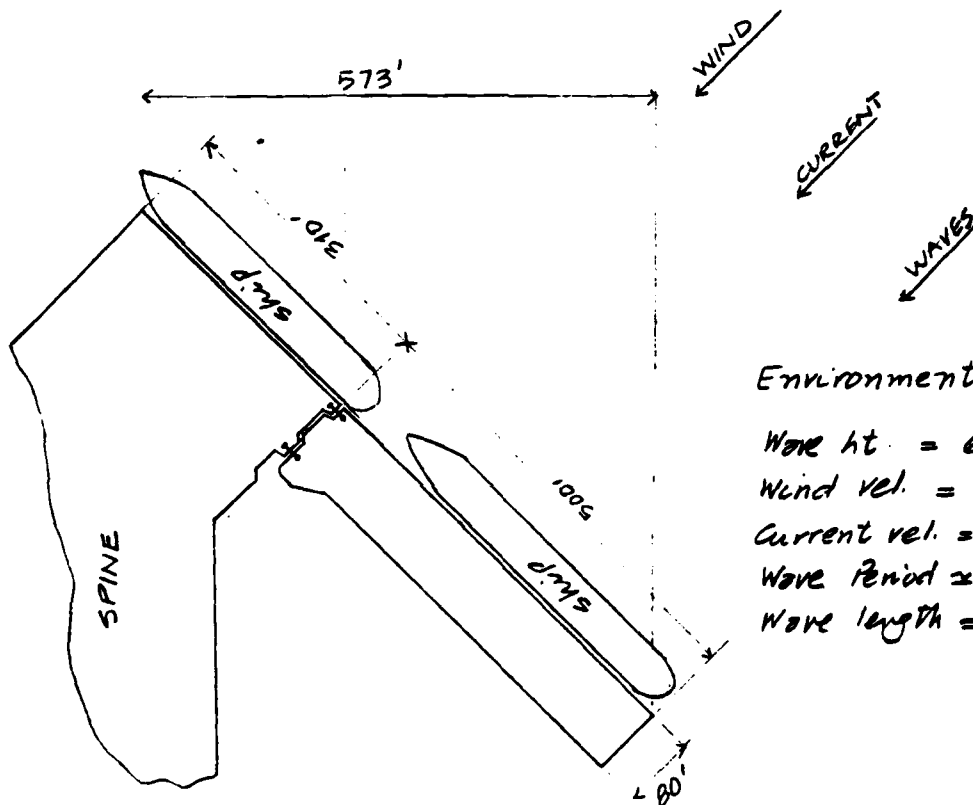
Strip theory was used to estimate the vessel motions, the pier was divided into thirty-two stations (strips), the distribution of the stations over the length is shown in Fig. 1-A. The pier was modelled as a free floating stationary vessel.

The response amplitude operators, and the statistics of motion for the specified sea spectrum are included in Pages A-8 to A-17. The response reported in the outputs is for the local origin specified for the mathematical model (see Fig. A-1). Or, the motions represent the displacements of the joint end of the finger pier.

It is seen that a wave heading of 110° is most severe for the imposed sea spectrum, except for sway and roll motions which are greater for a heading of 100° . (See p. A-6)

A computer program, Ocean Systems Computer Analysis Routines (OSCAR), compiled by Ultramarine Inc., of Houston, Texas was used for the free floating analysis.

Forces on Spine/finger joint. Most severe loading condition.
@ service mode.



Environment:

Wave ht. = 6'
Wind vel. = 18 knots
Current vel. = 1 knot
Wave Period = 5.5 sec
Wave length = 150'

Calculate forces on joint:

Wind: (@ 18 knots or 30.4 F/s)

Assume 1 DD--- type ship is berthed against finger pier
Appx. draft = 35' and projected surface area = 25000 FT²; L = 500 FT.

$$F_w = \frac{1}{2} \rho C A_p V^2$$

$$F_w = \frac{1}{2} \times 0.00237 \times 1 \times 25000 \times 30.4^2$$

$$F_w = 30 \text{ kips} \quad \text{acting at } 333 \text{ FT from joint}$$

Surge:

$$F_s \approx 0.33 F_w = 10 \text{ kips}$$

Current: (@ 1 knot or 1.69 F/S)

$$F_{c0} = \frac{1}{2} \rho C_D A V^2$$

$$F_{c0} = \frac{1}{2} \times 1.99 \times 1.2 \times 500 \times 35 \times 1.69^2$$

$$F_{c0} = 60 \text{ Kips.}$$

$$F_{cs} = \frac{1}{2} \rho C_s A_s V^2$$

$$F_{cs} = \frac{1}{2} \times 1.99 \times 0.01 \times 40000 \times 1.69^2$$

$$F_{cs} = 2 \text{ Kips.}$$

$$C_s = 0.01$$

$$A_s \approx 40000 \text{ FT}^2$$

Wave Forces: ($h = 6'$, $L = 150'$, $T = 5.5 \text{ s}$)

- For conservative estimate use Sainflou's Formula
(DM 26-2-16)

Assume water depth of 80 FT.

$$\therefore \frac{d}{L} = \frac{80}{150} = 0.5$$

FROM DM 26 Fig 2-14

$P = 2.8 \text{ lbs/FT}^2$ acting on broadside

$$\therefore F_{wave} = 2.8 \times 35 \times 500 = 49 \text{ Kips.}$$

\therefore Total lateral force on Finger pier

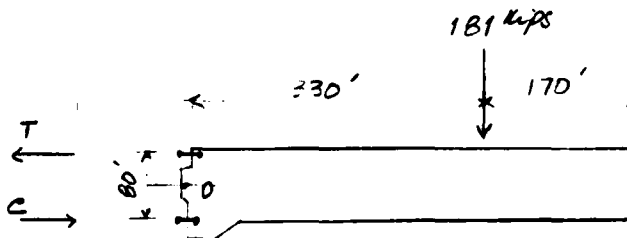
$$F = 30 + 10 + 62 + 49 = 151 \text{ Kips.}$$

acting @ 330 FT from joint.

$$\sum M @ 0 = 0$$

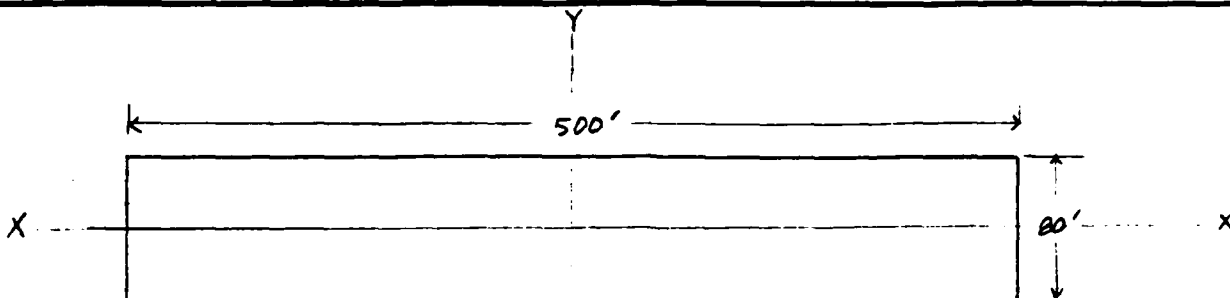
$$181 \times 330 = T \times 80$$

$$\Rightarrow T = 746 \text{ K} = C$$



OR if compression is provided by finger pier bearing against spine pier, say moment arm is 60 FT.

$$\therefore T = \frac{181 \times 330}{60} = 1000 \text{ K.}$$

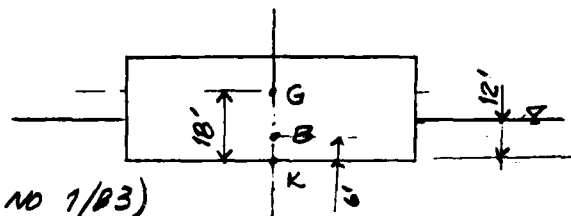


PLAN

$$A_p = 40000 \text{ FT}^2$$

$$I_{xx} = 21.33 \times 10^6 \text{ FT}^4$$

$$I_{yy} = 833.33 \times 10^6 \text{ FT}^4$$



$$KG = 18 \text{ FT} \quad (\text{P. A-27 Report NO 1/83})$$

$$KB = 6 \text{ FT.}$$

Transverse metacenter:

$$GM_T = \frac{21.33 \times 10^6}{(40,000 \times 12)} - (18 - 6) = 32.4 \text{ FT.}$$

$$r_x \approx \left(\frac{21.33 \times 10^6}{40,000} \right)^{1/2} = 23.1 \text{ FT} \Rightarrow T_r = \frac{1.108 r_x}{\sqrt{GM_T}} = 4.5 \text{ sec}$$

Longitudinal metacenter:

$$GM_L = \frac{833.33 \times 10^6}{(40000 \times 12)} - (18 - 6) = 1720 \text{ FT.}$$

$$r_y \approx \left(\frac{833.33 \times 10^6}{40000} \right)^{1/2} = 144 \text{ FT} \Rightarrow T_L = \frac{1.108 r_y}{\sqrt{GM_L}} = 3.8 \text{ sec}$$

For typical barge type vessels:

$$R_{ROLL} = 0.32 B = 25.6 \text{ FT.}$$

$$R_{PITCH} = 0.29 L = 145 \text{ FT.}$$

$$R_{YAW} = 0.29 L = 145 \text{ FT.}$$

Finger Pier analytical model.

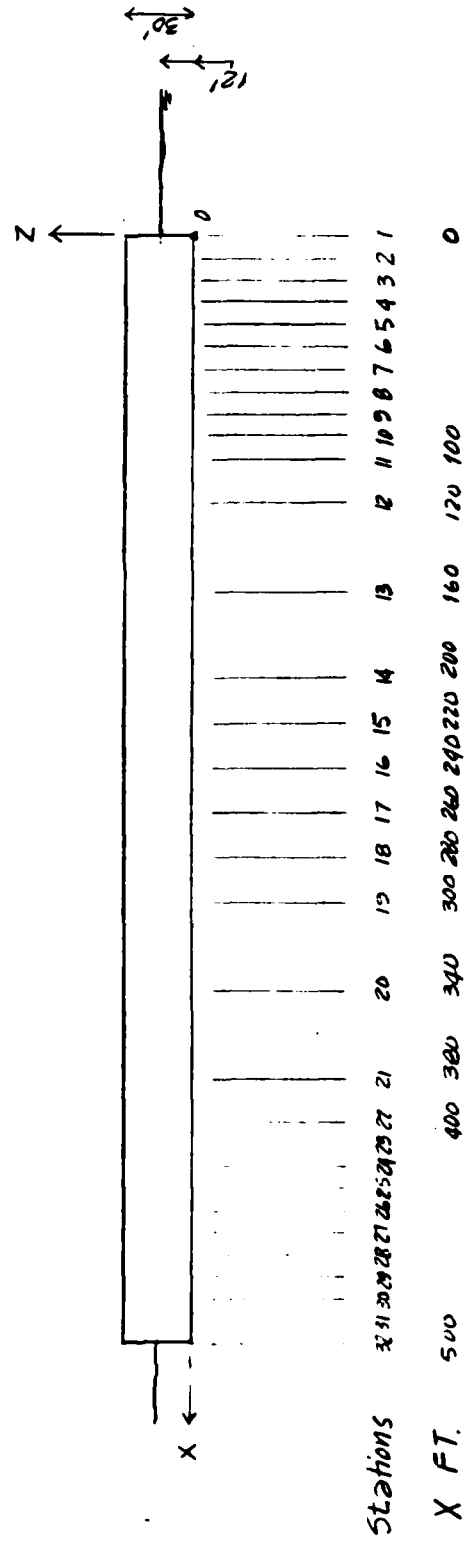
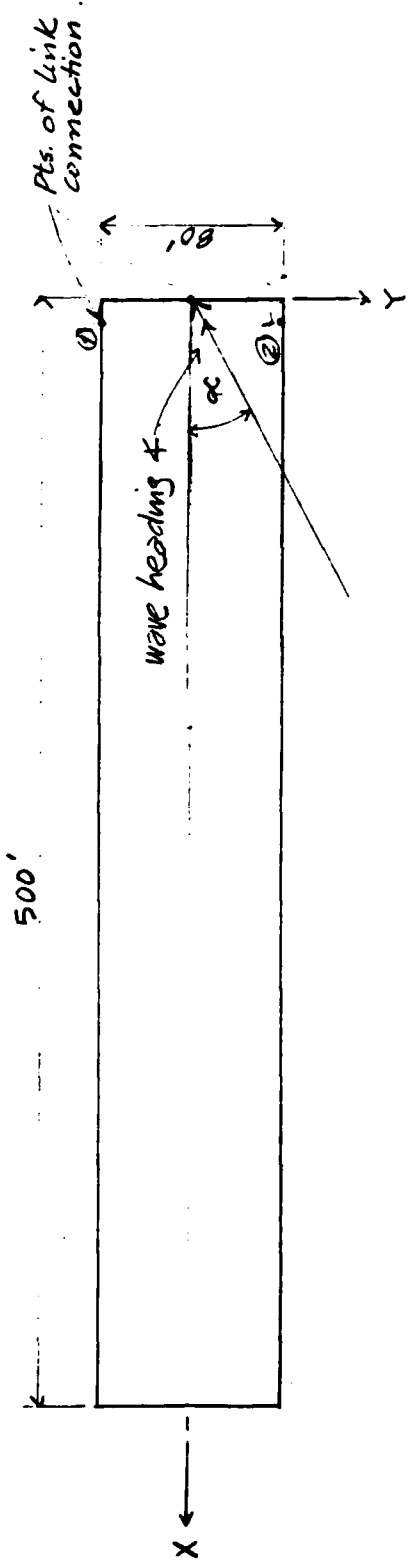


Fig A-1

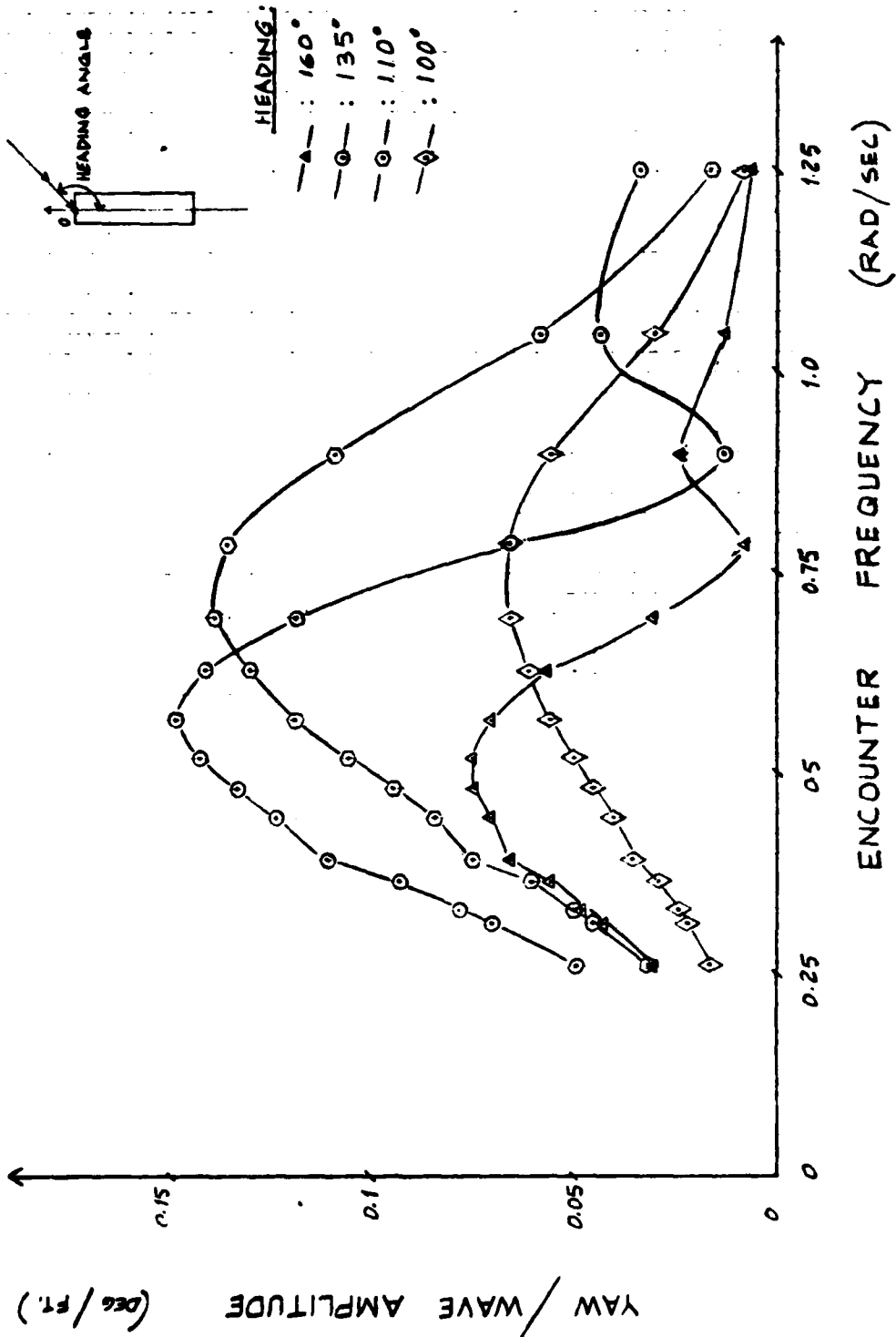
SUMMARY OF FREE-FLOATING MOTIONS:
 Motions for Average of 1/3 of spectral peaks.
 Significant wave height = 6.0ft., Mean period = 5.5 sec.

| Heading (deg) | Surge (ft) | Sway (ft) | Heave (ft) | Roll (deg) | Pitch (deg) | Yaw (deg) |
|---------------|------------|-----------|------------|------------|-------------|-----------|
| 180 | 0.268 | 0.0 | 0.399 | 0.0 | 0.091 | 0.0 |
| 160 | 0.260 | 0.25 | 0.844 | 0.003 | 0.191 | 0.057 |
| 135 | 0.253 | 0.629 | 1.182 | 0.614 | 0.270 | 0.144 |
| 110 | 0.296 | 1.368 | 2.314 | 0.812 | 0.483 | 0.260 |
| 100 | 0.147 | 1.503 | 1.848 | 1.913 | 0.216 | 0.126 |

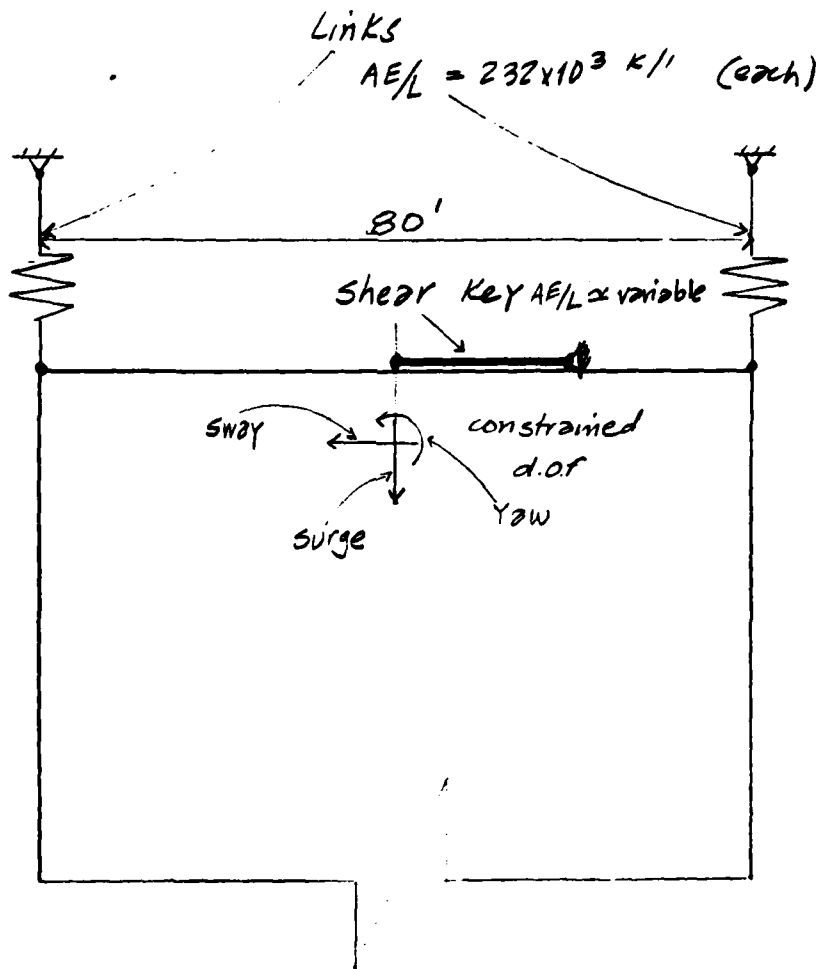
Note: To obtain values that have a probability to be exceeded of 0.001, the above values should be multiplied by 1.92

YAW: RESPONSE AMPLITUDE OPERATORS
(AT POINT 'O')

FREE FLOATING



Finger/spine connection: Analytical Model.



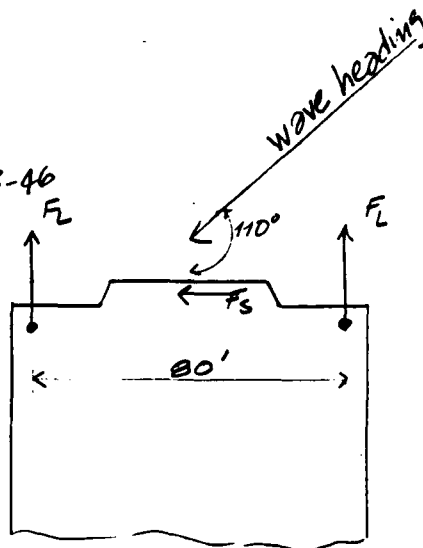
Note: all motions in vertical plane are unconstrained.

Fig. B-1

Connection Loading:

Linear motion (wave) 110° heading from p. B-46

Surge: $440/2 = 220 \text{ K} / \text{Link}$
Sway: 1137 K
Yaw: $\frac{323400 \text{ K-F}}{80 \text{ F}} = \pm 4040 \text{ K/Link}$



Wave Drift: (110° heading) from p. _____

Surge: $7.7/2 = 3.85 \text{ K} / \text{Link}$
Sway: 42.7 K
Yaw: $\frac{10900 \text{ K-F}}{80 \text{ F}} = \pm 136 \text{ K/Link}$

Wind and current: (broadside)

Total lateral force = $30 + 62 = 92 \text{ K}$ @ 333 FT. from conn.
(calculated on pp. A-1 & A-2)

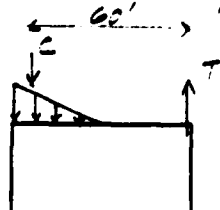
\therefore Sway: $= 92 \text{ K}$
Yaw: $= \frac{92 \times 333}{80} = \pm 383 \text{ K/Link}$

$\therefore F_S = 1137 + 42.7 + 92 = 1272 \text{ kips}$

$F_L = 220 + 4 + 4040 + 136 + 383 \approx 4800 \text{ kips}$

Tension or Comp.
in each link.

If finger pier is allowed to bear against the spine pier at the compression end. The moment arm will be reduced.



Assume moment arm is 60'

$\therefore F_L = 224 + (4557) \frac{80}{60} \approx 6300 \text{ kips}$
Tension.

*** OSCAR ***

DRAFT = 12.0 FEET TRIM ANGLE = 9.00 DEG.
 HEADING = 180.00 DEG. FORWARD SPEED = 0.00 KNOT
 ROLL CY. RADIUS = 25.00 FEET PITCH CY. RADIUS = 145.0 F

V E S S E L R E S P O N S E

OF BODY POINT

| E N C O U N T E R | | SURGE/ | | SLAY/ | | HEAVE/ | |
|-------------------|---------|------------|--------|------------|--------|----------|------|
| ----- | | WAVE AMPL. | | WAVE AMPL. | | WAVE AMP | |
| FREQUENCY | PERIOD | AMPL. | PHASE | AMPL. | PHASE | AMPL. | PHAS |
| -(RAD/SEC)- | -(SEC)- | | | | | | |
| .2513 | 25.000 | .9863 | -119.3 | .0000 | -88.8 | .7474 | -11 |
| .3142 | 20.000 | .9099 | -134.8 | .0000 | -90.6 | .8284 | -10 |
| .3307 | 19.000 | .8889 | -139.6 | .0000 | -91.4 | .8545 | -23 |
| .3491 | 18.000 | .8628 | -145.4 | .0000 | -92.7 | .8850 | -27 |
| .3696 | 17.000 | .8292 | -152.2 | .0000 | -94.8 | .9196 | -32 |
| .3927 | 16.000 | .7851 | -160.5 | .0000 | -97.3 | .9573 | -37 |
| .4189 | 15.000 | .7265 | -170.5 | .0000 | -101.0 | .9958 | -42 |
| .4333 | 14.500 | .6902 | -176.4 | .0000 | -103.5 | 1.0137 | -52 |
| .4488 | 14.000 | .6483 | 177.0 | .0000 | -106.2 | 1.0293 | -58 |
| .4654 | 13.500 | .5998 | 169.7 | .0000 | -109.2 | 1.0407 | -65 |
| .4833 | 13.000 | .5439 | 161.4 | .0000 | -113.0 | 1.0461 | -72 |
| .5027 | 12.500 | .4798 | 151.9 | .0000 | -117.6 | 1.0422 | -81 |
| .5236 | 12.000 | .4068 | 140.9 | .0000 | -122.5 | 1.0246 | -90 |
| .5464 | 11.500 | .3247 | 127.9 | .0000 | -128.5 | .9883 | -102 |
| .5712 | 11.000 | .2342 | 111.9 | .0000 | -135.8 | .9264 | -114 |
| .5984 | 10.500 | .1384 | 89.4 | .0000 | -143.8 | .8306 | -129 |
| .6283 | 10.000 | .0520 | 35.1 | .0000 | -153.5 | .6927 | -145 |
| .6614 | 9.500 | .0788 | -78.5 | .0000 | -164.0 | .5062 | -163 |
| .6981 | 9.000 | .1517 | -119.4 | .0000 | -174.8 | .2756 | -178 |
| .7342 | 8.500 | .1939 | -153.2 | .0000 | -175.7 | .1108 | -120 |
| .7854 | 8.000 | .1813 | 168.9 | .0000 | -99.9 | .3115 | -107 |
| .8378 | 7.500 | .1023 | 118.5 | .0000 | -96.8 | .4647 | -145 |
| .8976 | 7.000 | .0385 | -49.9 | .0000 | -125.2 | .3755 | -162 |
| .9666 | 6.500 | .1028 | -146.4 | .0000 | -156.3 | .1368 | 169 |
| 1.0472 | 6.000 | .0440 | 152.1 | .0000 | -89.7 | .2962 | 112 |
| 1.1424 | 5.500 | .0628 | -137.4 | .0000 | -144.2 | .1336 | 11 |
| 1.2566 | 5.000 | .0101 | 146.5 | .0000 | -137.8 | .1192 | -44 |
| 1.3963 | 4.500 | .0127 | 129.5 | .0000 | 127.0 | .0244 | -37 |
| 1.5708 | 4.000 | .0191 | -113.3 | .0000 | -86.6 | .0915 | -41 |
| 2.0444 | 3.000 | .0005 | 9.7 | .0000 | -149.9 | .0634 | -127 |

(1)

*** OSCAR ***

DATE 84/02/1

ANGLE = 0.00 DEG. G-METACENTER = 32.4 FEET
 D SPEED = 0.00 KNOTS WAVE STEEPNESS = 1/ 20
 GY. RADIUS = 145.0 FEET YAW GY. RADIUS = 145.0 FEET

RESPONSE OPERATORS

OF BODY PIER

| HEAVE/ | | ROLL/ | | PITCH/ | | YAW/ | | |
|--------|------------|------------|------------|------------|------------|------------|------------|-------|
| AMPL. | WAVE AMPL. | WAVE AMPL. | WAVE AMPL. | WAVE AMPL. | WAVE AMPL. | WAVE AMPL. | WAVE AMPL. | |
| PHASE | AMPL. | PHASE | AMPL. | PHASE | AMPL. | PHASE | AMPL. | |
| -88.8 | .7474 | -11.0 | .0000 | -90.0 | .0911 | 54.0 | .0000 | 158.7 |
| -90.6 | .8284 | -19.9 | .0000 | -90.0 | .1327 | 30.3 | .0000 | 143.6 |
| -91.4 | .8545 | -23.1 | .0000 | -90.0 | .1445 | 23.4 | .0000 | 139.4 |
| -92.7 | .8850 | -27.2 | .0000 | -90.0 | .1576 | 15.4 | .0000 | 134.3 |
| -94.8 | .9196 | -32.4 | .0000 | -90.0 | .1721 | 6.0 | .0000 | 128.3 |
| -97.3 | .9573 | -39.0 | .0000 | -90.0 | .1875 | -5.0 | .0000 | 121.4 |
| -101.0 | .9958 | -47.5 | .0000 | -90.0 | .2032 | -18.1 | .0000 | 113.2 |
| -103.5 | 1.0137 | -52.6 | .0000 | -90.0 | .2109 | -25.6 | .0000 | 108.3 |
| -106.2 | 1.0293 | -58.4 | .0000 | -90.0 | .2180 | -33.8 | .0000 | 103.1 |
| -109.2 | 1.0407 | -65.0 | .0000 | -90.0 | .2241 | -42.9 | .0000 | 97.5 |
| -113.0 | 1.0461 | -72.5 | .0000 | 175.0 | .2288 | -53.0 | .0000 | 90.0 |
| -117.6 | 1.0422 | -81.1 | .0000 | 90.0 | .2313 | -64.3 | .0000 | 83.6 |
| -122.5 | 1.0246 | -90.9 | .0000 | 90.0 | .2304 | -77.0 | .0000 | 75.8 |
| -128.5 | .9883 | -102.0 | .0000 | 90.0 | .2250 | -91.2 | .0000 | 66.7 |
| -135.8 | .9264 | -114.9 | .0000 | 90.0 | .2133 | -107.5 | .0000 | 56.0 |
| -143.8 | .8306 | -129.4 | .0000 | 90.0 | .1933 | -126.1 | .0000 | 44.2 |
| -153.5 | .6927 | -145.9 | .0000 | 90.0 | .1627 | -147.8 | .0000 | 29.9 |
| -164.0 | .5062 | -163.7 | .0000 | -90.0 | .1197 | -173.5 | .0000 | 13.3 |
| -174.8 | .2756 | -178.0 | .0000 | -90.0 | .0639 | 153.4 | .0000 | -7.7 |
| -175.7 | .1108 | -128.5 | .0000 | -161.0 | .0106 | 21.7 | .0000 | -38.4 |
| -99.9 | .3115 | -107.9 | .0000 | 142.9 | .0691 | -85.4 | .0000 | 148.4 |
| -96.8 | .4647 | -145.2 | .0000 | 90.0 | .1102 | -141.7 | .0000 | 99.1 |
| -125.2 | .3755 | -162.5 | .0000 | -90.0 | .0924 | 148.0 | .0000 | 53.3 |
| -156.3 | .1368 | 165.3 | .0000 | 90.0 | .0055 | -14.8 | .0000 | -6.3 |
| -89.7 | .2962 | 112.1 | .0000 | 90.0 | .0652 | 120.1 | .0000 | 124.1 |
| -144.2 | .1336 | 11.0 | .0000 | -90.0 | .0247 | -27.8 | .0000 | 27.4 |
| -137.8 | .1192 | -44.2 | .0000 | 90.0 | .0260 | -21.0 | .0000 | 109.1 |
| 127.0 | .0244 | -37.8 | .0000 | -90.0 | .0057 | .1 | .0000 | -70.6 |
| -86.6 | .0915 | -41.3 | .0000 | -90.0 | .0117 | -76.2 | .0000 | 76.6 |
| -149.9 | .0634 | -127.6 | .0000 | -90.0 | .0064 | -74.3 | .0000 | -22.7 |



```

*****
*                                     *** OSCAR
*
*
*
* DRAFT = 12.0 FEET           TRIM ANGLE = 0.00 DEG.
* HEADING = 180.00 DEG.       FORWARD SPEED = 0.00 KN
* ROLL GY. RADIUS = 25.60 FEET  PITCH GY. RADIUS = 145.0
*****
    
```

STATISTICS OF MOTIONS
 =====
 OF BODY PITCH

SEA SPECTRUM

ISSC --- SIGNIFICANT HEIGHT = 6.0 FEET

SINGLE AMPLITUDE

| | SURGE -(FEET)- | SWAY -(FEET)- |
|----------------------|---------------------|--------------------|
| ROOT MEAN SQUARE | .134 | .000 |
| AVE OF 1/3 HIGHEST | .268 | .000 |
| AVE OF 1/10 HIGHEST | .341 | .000 |
| AVE OF 1/100 HIGHEST | .447 | .000 |

STATISTICS OF ACCELERATION

SINGLE AMPLITUDE

| | SURGE (FEET /SEC**2) | SWAY (FEET /SEC**2) | HEAVE (FEET /SE |
|----------------------|--------------------------|-------------------------|---------------------|
| ROOT MEAN SQUARE | .100 | .000 | .33 |
| AVE OF 1/3 HIGHEST | .200 | .000 | .67 |
| AVE OF 1/10 HIGHEST | .255 | .000 | .88 |
| AVE OF 1/100 HIGHEST | .334 | .000 | 1.18 |

(1)

*** OSCAR ***

DATE 84/02/1

HEAVE ANGLE = 0.00 DEG. G-METACENTER = 32.4 FEET
 FORWARD SPEED = 0.00 KNOTS WAVE STEEPNESS = 1/20
 METACENTER GY. RADIUS = 145.0 FEET YAW GY. RADIUS = 145.0 FEET

MOTIONS IN IRREGULAR SEAS
 OF BODY POINT

SEA SPECTRUM

HEIGHT = 6.0 FEET MEAN PERIOD = 5.5 SECONDS

LINEAR AMPLITUDE MOTIONS

| HEIGHT (FEET) | SWAY (FEET) | HEAVE (FEET) | ROLL (DEG) | PITCH (DEG) | YAW (DEG) |
|---------------|-------------|--------------|------------|-------------|-----------|
| .134 | .000 | .399 | .000 | .091 | .000 |
| .268 | .000 | .797 | .000 | .182 | .000 |
| .341 | .000 | 1.017 | .000 | .231 | .000 |
| .447 | .000 | 1.332 | .000 | .303 | .000 |

ACCELERATION IN IRREGULAR SEAS

SINGLE AMPLITUDES

| HEIGHT (FEET) | HEAVE (FEET/SEC**2) | ROLL (DEG/SEC**2) | PITCH (DEG/SEC**2) | YAW (DEG/SEC**2) |
|---------------|---------------------|-------------------|--------------------|------------------|
| .000 | .338 | .000 | .072 | .000 |
| .000 | .675 | .000 | .144 | .000 |
| .000 | .861 | .000 | .184 | .000 |
| .000 | 1.128 | .000 | .241 | .000 |

(2)

*** OSCAR ***

DRAFT = 12.0 FEET TRIM ANGLE = 0.00 DEG.
 HEADING = 160.00 DEG. FORWARD SPEED = 0.00 KNO
 ROLL GY. RADIUS = 25.60 FEET PITCH GY. RADIUS = 145.0

VESSEL RESPONSE OF BODY PIER

| E-N-C-O-U-N-T-E-R | | SURGE/ WAVE AMPL. | | SWAY/ WAVE AMPL. | | HEAVE/ WAVE AM | |
|------------------------|-----------------|----------------------|--------|---------------------|-------|-------------------|-----|
| FREQUENCY (RAD/SEC) | PERIOD (SEC) | AMPL. | PHASE | AMPL. | PHASE | AMPL. | PHA |
| .2513 | 25.000 | .9249 | -117.3 | .2453 | 91.2 | .7378 | -1 |
| .3142 | 20.000 | .8599 | -131.8 | .2491 | 89.4 | .8114 | -1 |
| .3307 | 19.000 | .8427 | -136.3 | .3051 | 88.6 | .8357 | -2 |
| .3491 | 18.000 | .8213 | -141.7 | .3122 | 87.3 | .8644 | -2 |
| .3696 | 17.000 | .7938 | -148.1 | .3203 | 85.2 | .8977 | -3 |
| .3927 | 16.000 | .7575 | -155.8 | .3293 | 82.7 | .9352 | -3 |
| .4189 | 15.000 | .7091 | -165.2 | .3383 | 79.0 | .9752 | -4 |
| .4333 | 14.500 | .6789 | -170.7 | .3422 | 76.5 | .9950 | -4 |
| .4488 | 14.000 | .6437 | -176.8 | .3455 | 73.8 | 1.0136 | -5 |
| .4654 | 13.500 | .6029 | 176.3 | .3477 | 70.8 | 1.0296 | -6 |
| .4833 | 13.000 | .5555 | 168.6 | .3480 | 67.0 | 1.0414 | -6 |
| .5027 | 12.500 | .5006 | 159.8 | .3457 | 62.4 | 1.0463 | -7 |
| .5236 | 12.000 | .4375 | 149.7 | .3398 | 57.5 | 1.0407 | -8 |
| .5464 | 11.500 | .3654 | 137.9 | .3288 | 51.5 | 1.0200 | -9 |
| .5712 | 11.000 | .2843 | 123.8 | .3110 | 44.2 | .9780 | -10 |
| .5984 | 10.500 | .1956 | 105.8 | .2845 | 36.2 | .9067 | -11 |
| .6283 | 10.000 | .1037 | 77.8 | .2468 | 26.5 | .7971 | -13 |
| .6614 | 9.500 | .0422 | -10.3 | .1964 | 16.0 | .6399 | -15 |
| .6981 | 9.000 | .0095 | -95.2 | .1329 | 5.2 | .4302 | -17 |
| .7392 | 8.500 | .1596 | -132.6 | .0618 | 4.3 | .1865 | -17 |
| .7854 | 8.000 | .1780 | -169.0 | .0423 | 80.1 | .1862 | -17 |
| .8378 | 7.500 | .1338 | 147.3 | .0985 | 83.2 | .4092 | -17 |
| .8976 | 7.000 | .0348 | 67.9 | .1183 | 54.8 | .4628 | -17 |
| .9666 | 6.500 | .0773 | -115.0 | .0669 | 23.7 | .2160 | 17 |
| 1.0472 | 6.000 | .0751 | -179.1 | .0601 | 90.3 | .2388 | 17 |
| 1.1424 | 5.500 | .0248 | -133.0 | .1012 | 35.8 | .1985 | 17 |
| 1.2566 | 5.000 | .0477 | 164.1 | .0428 | 42.2 | .0926 | -17 |
| 1.3963 | 4.500 | .0393 | -174.3 | .0199 | -53.0 | .0265 | -17 |
| 1.5708 | 4.000 | .0246 | 162.9 | .0376 | 93.4 | .0620 | -17 |
| 2.0944 | 3.000 | .0068 | -91.3 | .0218 | 30.1 | .0266 | -17 |

1

*** OSCAR ***

DATE 84/02/1

BLE = 0.00 DEG. G-METACENTER = 32.4 FEET
 SPEED = 0.00 KNOTS WAVE STEEPNESS = 1/ 20
 Y. RADIUS = 145.0 FEET YAW GY. RADIUS = 145.0 FEET

RESPONSE OPERATORS

OF BODY PIER

| CASE | HEAVE/ WAVE AMPL. | | ROLL/ WAVE AMPL. | | PITCH/ WAVE AMPL. | | YAW/ WAVE AMPL. | |
|------|----------------------|--------|---------------------|--------|----------------------|--------|--------------------|--------|
| | AMPL. | PHASE | AMPL. | PHASE | AMPL. | PHASE | AMPL. | PHASE |
| 91.2 | .7378 | -10.9 | .0006 | 63.0 | .0854 | 56.4 | .0311 | -21.3 |
| 89.4 | .8114 | -19.1 | .0009 | 49.4 | .1248 | 33.6 | .0436 | -36.4 |
| 88.6 | .8357 | -22.1 | .0009 | 45.3 | .1362 | 27.0 | .0473 | -40.6 |
| 87.3 | .8644 | -25.8 | .0010 | 40.4 | .1489 | 19.3 | .0515 | -45.7 |
| 85.2 | .8977 | -30.6 | .0011 | 34.4 | .1630 | 10.3 | .0561 | -51.7 |
| 82.7 | .9352 | -36.7 | .0012 | 27.4 | .1784 | -.2 | .0609 | -58.6 |
| 79.0 | .9752 | -44.6 | .0013 | 18.9 | .1946 | -12.7 | .0659 | -66.8 |
| 76.5 | .9950 | -49.3 | .0014 | 13.8 | .2028 | -19.9 | .0683 | -71.7 |
| 73.8 | 1.0136 | -54.7 | .0014 | 8.3 | .2107 | -27.7 | .0706 | -76.9 |
| 70.8 | 1.0296 | -60.8 | .0014 | 2.1 | .2180 | -36.4 | .0725 | -82.5 |
| 67.0 | 1.0414 | -67.9 | .0015 | -5.0 | .2243 | -46.0 | .0741 | -89.0 |
| 62.4 | 1.0463 | -75.9 | .0015 | -13.1 | .2289 | -56.8 | .0749 | -96.4 |
| 57.5 | 1.0407 | -85.1 | .0014 | -22.3 | .2311 | -68.8 | .0749 | -104.2 |
| 51.5 | 1.0200 | -95.6 | .0013 | -33.2 | .2296 | -82.3 | .0736 | -113.3 |
| 44.2 | .9780 | -107.8 | .0011 | -46.4 | .2229 | -97.8 | .0705 | -124.0 |
| 36.2 | .9067 | -121.7 | .0008 | -63.0 | .2091 | -115.3 | .0653 | -135.8 |
| 26.5 | .7971 | -137.7 | .0004 | -89.8 | .1857 | -135.7 | .0571 | -150.1 |
| 16.0 | .6399 | -155.6 | .0003 | 104.7 | .1505 | -159.6 | .0456 | -166.7 |
| 5.2 | .4302 | -174.3 | .0012 | 60.9 | .1014 | 171.5 | .0305 | 172.3 |
| 4.3 | .1865 | 179.5 | .0023 | -19.0 | .0393 | 131.0 | .0125 | 141.6 |
| 30.1 | .1862 | -111.3 | .0028 | -37.1 | .0332 | -61.0 | .0078 | -31.6 |
| 33.2 | .4092 | -132.7 | .0017 | -108.0 | .0934 | -120.9 | .0232 | -80.9 |
| 54.8 | .4628 | 176.8 | .0003 | 76.9 | .1109 | 172.5 | .0282 | -126.7 |
| 23.7 | .2160 | 125.0 | .0010 | -45.0 | .0483 | 83.6 | .0148 | 173.7 |
| 90.3 | .2388 | 126.0 | .0006 | -126.9 | .0433 | 151.6 | .0131 | -55.9 |
| 35.8 | .1985 | 28.5 | .0001 | -12.2 | .0439 | 16.4 | .0237 | -152.6 |
| 42.2 | .0926 | -20.9 | .0001 | -96.5 | .0124 | 28.8 | .0068 | -70.9 |
| 53.0 | .0265 | -120.1 | .0001 | 36.7 | .0065 | -145.1 | .0054 | 109.4 |
| 93.4 | .0620 | 1.1 | .0002 | 140.6 | .0110 | -15.3 | .0074 | -103.4 |
| 30.1 | .0266 | -59.8 | .0006 | 86.8 | .0046 | -94.8 | .0038 | 157.3 |

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*****
*                                     *** USCAP
*
*
*
* DRAFT = 12.0 FEET          TRIM ANGLE = 0.00 DE
* HEADING = 100.00 DEG.     FORWARD SPEED = 0.00
* ROLL GY. RADIUS = 25.60 FEET  PITCH GY. RADIUS = 145
*****
  
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STATISTICS OF MOTIONS
 =====
 OF BODY PIER

SEA SPECT

ISSC --- SIGNIFICANT HEIGHT = 6.0 FEET

SINGLE AMPLITU

| | SURGE --(FEET)-- | SWAY --(FEET)-- |
|----------------------|-----------------------|----------------------|
| ROOT MEAN SQUARE | .130 | .125 |
| AVE OF 1/3 HIGHEST | .260 | .250 |
| AVE OF 1/10 HIGHEST | .332 | .319 |
| AVE OF 1/100 HIGHEST | .434 | .418 |

STATISTICS OF ACCELERATION

SINGLE AMP.

| | SURGE (FEET /SEC**2) | SWAY (FEET /SEC**2) | HEAV (FEET / |
|----------------------|--------------------------|-------------------------|------------------|
| ROOT MEAN SQUARE | .106 | .117 | .1 |
| AVE OF 1/3 HIGHEST | .211 | .235 | .6 |
| AVE OF 1/10 HIGHEST | .269 | .299 | .8 |
| AVE OF 1/100 HIGHEST | .352 | .392 | 1.1 |

*** USCAF ***

DATE . 84/02/1

ANGLE = 0.00 DEG. G-METACENTER = 32.4 FEET
 FORWARD SPEED = 0.00 KNOTS WAVE STEEPNESS = 1/20
 ROLL GY. RADIUS = 145.0 FEET YAW GY. RADIUS = 145.0 FEET

MOTIONS IN IRREGULAR SEAS

OF BODY PIER

SEA SPECTRUM

HEIGHT = 6.0 FEET MEAN PERIOD = 5.5 SECONDS

LINEAR AMPLITUDE MOTIONS

| PERIOD (SEC) | SWAY (FEET) | HEAVE (FEET) | ROLL (DEG) | PITCH (DEG) | YAW (DEG) |
|--------------|-------------|--------------|------------|-------------|-----------|
| 130 | .125 | .422 | .002 | .096 | .029 |
| 260 | .250 | .844 | .003 | .191 | .057 |
| 332 | .319 | 1.076 | .004 | .244 | .073 |
| 434 | .418 | 1.410 | .006 | .319 | .096 |

ACCELERATION IN IRREGULAR SEAS

SINGLE AMPLITUDES

| PERIOD (SEC) | HEAVE (FEET/SEC**2) | ROLL (DEG/SEC**2) | PITCH (DEG/SEC**2) | YAW (DEG/SEC**2) |
|--------------|---------------------|-------------------|--------------------|------------------|
| 17 | .339 | .001 | .074 | .026 |
| 35 | .677 | .003 | .148 | .052 |
| 99 | .864 | .003 | .188 | .066 |
| 192 | 1.131 | .004 | .247 | .087 |


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*****
OSCAR ***
-----
DATE 84/02/1.
*
*
*
0.00 DEG. G-METACENTER = 32.4 FEET *
= 0.00 KNOTS WAVE STEEPNESS = 1/ 20 *
US = 145.0 FFFT YAW GY. RADIUS = 145.0 FEET *
*****

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UNSE OPERATORS
=====

BY FPIEM

| LEAVE/ | | ROLL/ | | PITCH/ | | YAW/ | |
|------------|--------|------------|--------|------------|--------|------------|--------|
| WAVE AMPL. | | WAVE AMPL. | | WAVE AMPL. | | WAVE AMPL. | |
| AMPL. | PHASE | AMPL. | PHASE | AMPL. | PHASE | AMPL. | PHASE |
| .7090 | -10.7 | .0593 | 69.4 | .0661 | 65.4 | .0500 | -13.3 |
| .7571 | -17.1 | .0877 | 59.1 | .0975 | 45.2 | .0710 | -25.6 |
| .7742 | -19.3 | .0959 | 56.1 | .1069 | 39.4 | .0774 | -29.0 |
| .7953 | -22.1 | .1052 | 52.4 | .1176 | 32.8 | .0847 | -32.9 |
| .8212 | -25.6 | .1156 | 47.9 | .1299 | 25.1 | .0930 | -37.6 |
| .8527 | -30.1 | .1270 | 42.8 | .1440 | 16.2 | .1023 | -42.8 |
| .8905 | -35.9 | .1391 | 36.6 | .1599 | 5.6 | .1124 | -49.1 |
| .9118 | -39.5 | .1452 | 32.9 | .1685 | -.4 | .1178 | -52.8 |
| .9344 | -43.5 | .1512 | 28.9 | .1776 | -7.0 | .1232 | -56.7 |
| .9581 | -48.2 | .1569 | 24.6 | .1869 | -14.3 | .1286 | -60.8 |
| .9825 | -53.5 | .1619 | 19.6 | .1965 | -22.3 | .1339 | -65.7 |
| 1.0066 | -59.8 | .1657 | 13.9 | .2061 | -31.3 | .1388 | -71.2 |
| 1.0288 | -66.9 | .1678 | 7.8 | .2153 | -41.3 | .1430 | -77.0 |
| 1.0472 | -75.2 | .1672 | .6 | .2236 | -52.6 | .1462 | -83.7 |
| 1.0588 | -84.9 | .1627 | -7.8 | .2303 | -65.4 | .1476 | -91.6 |
| 1.0584 | -96.2 | .1525 | -17.2 | .2342 | -79.9 | .1467 | -100.2 |
| 1.0396 | -109.6 | .1346 | -28.6 | .2338 | -96.7 | .1423 | -110.7 |
| .9928 | -125.3 | .1059 | -42.5 | .2265 | -116.1 | .1334 | -122.8 |
| .9051 | -144.0 | .0635 | -61.4 | .2094 | -139.2 | .1182 | -137.5 |
| .7602 | -166.1 | .0103 | -149.4 | .1784 | -167.0 | .0958 | -155.3 |
| .5413 | 168.5 | .0805 | 93.2 | .1287 | 158.5 | .0651 | -178.1 |
| .2482 | 148.2 | .1854 | 58.6 | .0574 | 110.9 | .0275 | 149.1 |
| .2098 | -149.9 | .3213 | 13.9 | .0341 | -97.2 | .0138 | -31.8 |
| .4722 | 165.8 | .4746 | -89.6 | .1051 | 176.0 | .0427 | -90.3 |
| .3716 | 87.8 | .0895 | -19.2 | .0876 | 78.1 | .0437 | -148.0 |
| 1.008 | -49.8 | .0449 | -116.0 | .0062 | -40.9 | .0067 | -110.2 |
| .1558 | 14.0 | .0067 | 127.0 | .0357 | 20.0 | .0343 | -125.8 |
| .0522 | -52.1 | .0119 | 32.7 | .0036 | -140.9 | .0052 | 80.2 |
| .0276 | -121.1 | .0032 | 106.1 | .0070 | -124.5 | .0089 | 104.2 |
| .0007 | -168.9 | .0047 | -51.0 | .0000 | 52.7 | .0013 | -41.3 |

2

*** OSCAR ***

DATE 84/02/1

ANGLE = 0.00 DEG. G-METACENTER = 32.4 FEET
 D SPEED = 0.00 KNOTS WAVE STEEPNESS = 1/20
 GY. RADIUS = 145.0 FEET YAW GY. RADIUS = 145.0 FEET

MOTIONS IN IRREGULAR SEAS
 OF BODY PIER

SEA SPECTRUM

HGT = 6.0 FEET MEAN PERIOD = 5.5 SECONDS

AMPLITUDE MOTIONS

| SWAY -- (FEET) -- | HEAVE -- (FEET) -- | ROLL -- (DEG) -- | PITCH -- (DEG) -- | YAW -- (DEG) -- |
|------------------------|-------------------------|---------------------|----------------------|--------------------|
| .314 | .591 | .307 | .135 | .072 |
| .629 | 1.182 | .614 | .270 | .144 |
| .801 | 1.507 | .783 | .344 | .184 |
| 1.050 | 1.974 | 1.025 | .450 | .241 |

ACCELERATION IN IRREGULAR SEAS

ANGLE AMPLITUDES

| HEAVE **2) (FEET /SEC**2) | ROLL (DEG/SEC**2) | PITCH (DEG/SEC**2) | YAW (DEG/SEC**2) |
|-------------------------------|----------------------|-----------------------|---------------------|
| .428 | .274 | .096 | .053 |
| .856 | .548 | .193 | .106 |
| 1.091 | .699 | .245 | .135 |
| 1.429 | .915 | .322 | .177 |

(2)

 * *** OSCAR ***
 *
 *
 *
 * DRAFT = 12.0 FEET TRIM ANGLE = 0.00 DEG.
 * HEADING = 110.00 DEG. FORWARD SPED = 0.00 KNOTS
 * ROLL CY. RADIUS = 25.60 FEET PITCH CY. RADIUS = 145.0 FEET
 *

V E S S E L R E S P O N S E O P
 =====

OF BODY PITCH

| E N C O U N T E R | | SURGE/ | | SWAY/ | | HEAVE/ | |
|-------------------|--------|------------|--------|------------|-------|------------|-------|
| ----- | | WAVE AMPL. | | WAVE AMPL. | | WAVE AMPL. | |
| FREQUENCY | PERIOD | AMPL. | PHASE | AMPL. | PHASE | AMPL. | PHASE |
| (RAD/SEC) | (SEC) | | | | | | |
| .2513 | 25.000 | .3493 | -100.9 | .7637 | 91.0 | .6765 | -11. |
| .3142 | 20.000 | .3391 | -107.2 | .7574 | 91.4 | .6894 | -16. |
| .3307 | 19.000 | .3381 | -109.1 | .7614 | 91.6 | .6945 | -18. |
| .3491 | 18.000 | .3371 | -111.5 | .7666 | 91.7 | .7013 | -20. |
| .3696 | 17.000 | .3359 | -114.3 | .7733 | 91.6 | .7103 | -22. |
| .3927 | 16.000 | .3341 | -117.7 | .7817 | 91.7 | .7224 | -25. |
| .4189 | 15.000 | .3315 | -121.8 | .7917 | 91.7 | .7388 | -28. |
| .4333 | 14.500 | .3297 | -124.2 | .7971 | 91.5 | .7492 | -30. |
| .4488 | 14.000 | .3275 | -126.9 | .8029 | 91.3 | .7612 | -33. |
| .4654 | 13.500 | .3247 | -129.9 | .8090 | 91.3 | .7751 | -35. |
| .4833 | 13.000 | .3212 | -133.3 | .8151 | 90.9 | .7913 | -38. |
| .5027 | 12.500 | .3168 | -137.2 | .8212 | 90.3 | .8103 | -42. |
| .5236 | 12.000 | .3113 | -141.5 | .8267 | 89.9 | .8322 | -46. |
| .5464 | 11.500 | .3044 | -146.6 | .8313 | 89.1 | .8576 | -51. |
| .5712 | 11.000 | .2956 | -152.4 | .8344 | 87.8 | .8870 | -56. |
| .5984 | 10.500 | .2845 | -159.1 | .8343 | 86.5 | .9204 | -63. |
| .6283 | 10.000 | .2702 | -167.1 | .8303 | 84.3 | .9587 | -71. |
| .6614 | 9.500 | .2521 | -176.6 | .8197 | 81.7 | 1.0013 | -80. |
| .6981 | 9.000 | .2288 | 171.9 | .8001 | 77.7 | 1.0480 | -92. |
| .7392 | 8.500 | .1990 | 157.4 | .7679 | 72.6 | 1.0969 | -107. |
| .7854 | 8.000 | .1610 | 138.7 | .7184 | 65.4 | 1.1431 | -125. |
| .8378 | 7.500 | .1134 | 112.1 | .6459 | 55.7 | 1.1722 | -150. |
| .8976 | 7.000 | .0595 | 65.5 | .5464 | 43.5 | 1.1420 | -175. |
| .9666 | 6.500 | .0366 | -45.4 | .4871 | 30.7 | .9392 | 129. |
| 1.0472 | 6.000 | .0495 | -118.0 | .2796 | -7.3 | .4955 | 73. |
| 1.1424 | 5.500 | .0510 | -140.2 | .0749 | -30.6 | .1374 | -44. |
| 1.2566 | 5.000 | .0539 | -173.3 | .0931 | 65.1 | .1144 | 49. |
| 1.3963 | 4.500 | .0192 | 128.7 | .1220 | 4.3 | .0911 | -14. |
| 1.5708 | 4.000 | .0267 | -149.6 | .0347 | -7.6 | .0186 | -18. |
| 2.0944 | 3.000 | .0079 | -115.7 | .0200 | 160.8 | .0024 | 119. |

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*****
*
*                                     *** USCAP ***
*
*
*-----
*
*   DRAFT = 12.0 FEET                TRIM ANGLE = 0.00 DEG.
*   HEADING = 110.00 DEG.            FORWARD SPEED = 0.00 KNOTS
*   ROLL GY. RADIUS = 25.60 FEET     PITCH GY. RADIUS = 145.0 FEET
*
*****

```

STATISTICS OF MOTIONS IN
=====

SEA SPECTRUM

ISSC --- SIGNIFICANT HEIGHT = 6.0 FEET

SINGLE AMPLITUDE

| | SURGE -(FEET)- | SWAY -(FEET)- | HEAVE -(FEET)- |
|--------------------------|---------------------|--------------------|---------------------|
| ROOT MEAN SQUARE | .148 | .684 | 1.111 |
| 1.92X AVE OF 1/3 HIGHEST | .296 | 1.368 | 2.222 |
| AVE OF 1/10 HIGHEST | .377 | 1.744 | 2.778 |
| AVE OF 1/100 HIGHEST | .494 | 2.284 | 3.704 |

STATISTICS OF ACCELERATION IN

SINGLE AMPLITUDE

| | SURGE (FEET /SEC**2) | SWAY (FEET /SEC**2) | HEAVE (FEET /SEC**2) |
|----------------------|--------------------------|-------------------------|--------------------------|
| ROOT MEAN SQUARE | .105 | .497 | .876 |
| AVE OF 1/3 HIGHEST | .209 | .995 | 1.751 |
| AVE OF 1/10 HIGHEST | .267 | 1.268 | 2.233 |
| AVE OF 1/100 HIGHEST | .349 | 1.661 | 2.925 |

1

 *** USCAR ***

DATE 84/02/1

ANGLE = 0.00 DEG. G-METACENTER = 32.4 FEET
 DRD SPEED = 0.00 KNOTS WAVE STEEPNESS = 1/ 20
 GY. RADIUS = 145.0 FEET YAW GY. RADIUS = 145.0 FEET

MOTIONS IN IRREGULAR SEAS

=====

OF BODY PIERC

SEA SPECTRUM

HEIGHT = 6.0 FEET MEAN PERIOD = 5.5 SECONDS

E AMPLITUDE MOTIONS

| | SWAY (FEET) | HEAVE (FEET) | ROLL (DEG) | PITCH (DEG) | YAW (DEG) |
|----|------------------|-------------------|-----------------|------------------|----------------|
| 48 | .684 | 1.157 | .406 | .241 | .130 |
| 96 | 1.368 | 2.314 | .812 | .483 | .260 |
| 77 | 1.744 | 2.951 | 1.035 | .616 | .331 |
| 94 | 2.284 | 3.865 | 1.356 | .806 | .434 |

ACCELERATION IN IRREGULAR SEAS

SINGLE AMPLITUDES

| | HEAVE (FEET / SEC**2) | ROLL (DEG / SEC**2) | PITCH (DEG / SEC**2) | YAW (DEG / SEC**2) |
|----|----------------------------|--------------------------|---------------------------|-------------------------|
| 97 | .876 | .329 | .187 | .097 |
| 95 | 1.751 | .658 | .373 | .194 |
| 98 | 2.233 | .839 | .476 | .247 |
| 91 | 2.925 | 1.099 | .623 | .324 |

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*****
*                                     *** OSCAR ***
*
*
*
*   DRAFT = 12.0 FEET           TRIM ANGLE = 0.00 DEG.
*   HEADING = 100.00 DEG.       FORWARD SPEED = 0.00 KNOTS
*   ROLL CY. RADIUS = 25.60 FEET  PITCH CY. RADIUS = 145.0 FEET
*****
    
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V E S S E L R E S P O N S E O P E
=====

OF BODY PIER

| F N C O U N T E R | | SURGE/ | | SWAY/ | | HEAVE/ | |
|-------------------|--------|------------|--------|------------|--------|------------|--------|
| ----- | | WAVE AMPL. | | WAVE AMPL. | | WAVE AMPL. | |
| FREQUENCY | PERIOD | AMPL. | PHASE | AMPL. | PHASE | AMPL. | PHASE |
| (RAD/SEC) | (SEC) | | | | | | |
| .2513 | 25.000 | .1749 | -100.3 | .7863 | 90.7 | .6696 | -12.1 |
| .3142 | 20.000 | .1699 | -106.5 | .7744 | 91.3 | .6741 | -17.7 |
| .3307 | 19.000 | .1695 | -108.5 | .7768 | 91.6 | .6760 | -19.3 |
| .3491 | 18.000 | .1690 | -110.8 | .7799 | 91.9 | .6786 | -21.2 |
| .3696 | 17.000 | .1684 | -113.6 | .7837 | 92.0 | .6824 | -23.5 |
| .3927 | 16.000 | .1675 | -117.0 | .7889 | 92.4 | .6878 | -26.2 |
| .4189 | 15.000 | .1663 | -121.1 | .7949 | 92.7 | .6954 | -29.5 |
| .4333 | 14.500 | .1654 | -123.5 | .7980 | 92.8 | .7004 | -31.4 |
| .4488 | 14.000 | .1643 | -126.2 | .8013 | 92.9 | .7063 | -33.5 |
| .4654 | 13.500 | .1629 | -129.2 | .8048 | 93.2 | .7131 | -35.8 |
| .4833 | 13.000 | .1611 | -132.6 | .8081 | 93.4 | .7213 | -38.5 |
| .5027 | 12.500 | .1590 | -136.4 | .8113 | 93.3 | .7311 | -41.6 |
| .5236 | 12.000 | .1562 | -140.8 | .8139 | 93.5 | .7423 | -45.1 |
| .5464 | 11.500 | .1527 | -145.8 | .8159 | 93.5 | .7556 | -49.1 |
| .5712 | 11.000 | .1483 | -151.5 | .8166 | 93.2 | .7710 | -53.9 |
| .5984 | 10.500 | .1428 | -158.2 | .8152 | 93.1 | .7885 | -59.4 |
| .6283 | 10.000 | .1356 | -166.1 | .8112 | 92.4 | .8084 | -66.0 |
| .6614 | 9.500 | .1266 | -175.5 | .8032 | 91.6 | .8301 | -73.9 |
| .6961 | 9.000 | .1149 | -173.1 | .7901 | 89.9 | .8531 | -83.6 |
| .7392 | 8.500 | .0999 | -159.0 | .7714 | 87.7 | .8749 | -95.4 |
| .7854 | 8.000 | .0808 | -140.9 | .7483 | 84.4 | .8910 | -110.4 |
| .8378 | 7.500 | .0569 | -115.8 | .7299 | 79.5 | .8902 | -129.7 |
| .8976 | 7.000 | .0291 | -73.7 | .7471 | 69.2 | .8460 | -154.8 |
| .9666 | 6.500 | .0139 | -39.0 | .5185 | 41.4 | .7166 | 173.8 |
| 1.0472 | 6.000 | .0216 | -114.7 | .2610 | -20.4 | .5188 | 138.7 |
| 1.1424 | 5.500 | .0251 | -137.4 | .0497 | 28.5 | .3159 | -105.3 |
| 1.2566 | 5.000 | .0270 | -172.6 | .1268 | 65.6 | .1965 | 64.9 |
| 1.3963 | 4.500 | .0096 | 129.1 | .1364 | 26.6 | .1103 | 17.0 |
| 1.5708 | 4.000 | .0134 | -149.6 | .0878 | 6.5 | .0404 | -.1 |
| 2.0944 | 3.000 | .0040 | -115.7 | .0380 | -141.7 | .0038 | -157.2 |

*** OSCAR ***

DATE 84/02/1

ANGLE = 0.00 DEG. G-METACENTER = 32.4 FEET
 WIND SPEED = 0.00 KNOTS WAVE STEEPNESS = 1/20
 CY. RADIUS = 145.0 FEET YAW CY. RADIUS = 145.0 FEET

RESPONSE OPERATORS

OF BODY PITCH

| E AMPL. | HEAVE/ WAVE AMPL. | | ROLL/ WAVE AMPL. | | PITCH/ WAVE AMPL. | | YAW/ WAVE AMPL. | |
|---------|----------------------|--------|---------------------|--------|----------------------|--------|--------------------|--------|
| | AMPL. | PHASE | AMPL. | PHASE | AMPL. | PHASE | AMPL. | PHASE |
| 90.7 | .6696 | -12.1 | .0824 | 85.4 | .0193 | 102.2 | .0169 | 18.2 |
| 91.3 | .6741 | -17.7 | .1242 | 83.5 | .0260 | 80.1 | .0226 | 3.9 |
| 91.6 | .6760 | -19.3 | .1370 | 83.1 | .0281 | 74.3 | .0245 | .7 |
| 91.9 | .6786 | -21.2 | .1519 | 82.5 | .0306 | 67.9 | .0268 | -2.9 |
| 92.0 | .6824 | -23.5 | .1693 | 81.7 | .0336 | 60.8 | .0294 | -6.9 |
| 92.4 | .6878 | -26.2 | .1897 | 80.9 | .0371 | 52.9 | .0325 | -10.9 |
| 92.7 | .6954 | -29.5 | .2137 | 80.1 | .0414 | 43.9 | .0361 | -15.4 |
| 92.8 | .7004 | -31.4 | .2272 | 79.5 | .0438 | 38.8 | .0381 | -17.9 |
| 92.9 | .7063 | -33.5 | .2418 | 79.0 | .0465 | 33.4 | .0403 | -20.5 |
| 93.2 | .7131 | -35.8 | .2576 | 78.6 | .0495 | 27.6 | .0426 | -23.0 |
| 93.4 | .7213 | -38.5 | .2748 | 78.0 | .0527 | 21.2 | .0450 | -26.0 |
| 93.3 | .7311 | -41.6 | .2933 | 77.2 | .0563 | 14.2 | .0477 | -29.4 |
| 93.5 | .7423 | -45.1 | .3131 | 76.7 | .0603 | 6.6 | .0504 | -32.6 |
| 93.5 | .7556 | -49.1 | .3342 | 76.1 | .0647 | -1.9 | .0532 | -36.3 |
| 93.2 | .7710 | -53.9 | .3568 | 75.3 | .0695 | -11.5 | .0561 | -40.8 |
| 93.1 | .7885 | -59.4 | .3802 | 74.9 | .0747 | -22.1 | .0590 | -45.3 |
| 92.4 | .8084 | -66.0 | .4050 | 74.2 | .0805 | -34.4 | .0617 | -51.0 |
| 91.6 | .8301 | -73.9 | .4307 | 73.8 | .0857 | -48.4 | .0641 | -57.3 |
| 89.9 | .8531 | -83.6 | .4588 | 73.5 | .0933 | -64.9 | .0658 | -65.2 |
| 87.7 | .8749 | -95.4 | .4930 | 73.7 | .1001 | -84.5 | .0665 | -74.7 |
| 84.4 | .8910 | -110.4 | .5471 | 74.6 | .1064 | -108.6 | .0656 | -86.7 |
| 79.5 | .8902 | -129.7 | .6652 | 75.3 | .1107 | -139.1 | .0623 | -102.0 |
| 69.2 | .8460 | -154.8 | .9819 | 66.0 | .1087 | -179.4 | .0557 | -121.9 |
| 41.4 | .7166 | 173.8 | .8306 | 13.8 | .0894 | 125.4 | .0454 | -148.3 |
| -20.4 | .5188 | 138.7 | 1.0489 | -58.2 | .0469 | 56.1 | .0304 | 176.1 |
| 28.5 | .3159 | 105.3 | .4311 | -90.6 | .0079 | -22.9 | .0113 | 123.0 |
| 65.6 | .1965 | 64.9 | .1663 | -110.4 | .0098 | 74.3 | .0068 | -90.8 |
| 26.6 | .1103 | 17.0 | .0603 | -124.2 | .0096 | -24.3 | .0122 | 170.1 |
| 6.5 | .0404 | -.1 | .0090 | 165.8 | .0004 | 86.7 | .0017 | -6.1 |
| -141.7 | .0038 | -157.2 | .0117 | -121.1 | .0003 | 106.9 | .0024 | -45.4 |

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*****
*
*
*
*
*   DRAFT = 12.0 FEET           TRIM ANGLE = 0.00 DEG
*   HEADING = 100.00 DEG.      FORWARD SPEED = 0.00 K
*   ROLL GY. RADIUS = 25.60 FEET  PITCH GY. RADIUS = 145.
*****
    
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STATISTICS OF MOTIONS
 =====
 OF BODY FITR

SEA SPECT

ISSC --- SIGNIFICANT HEIGHT = 6.0 FEET

SINGLE AMPLITU

| | SURGE -(FEET) - | SWAY -(FEET) - |
|----------------------|----------------------|---------------------|
| ROOT MEAN SQUARE | .074 | .751 |
| AVE OF 1/3 HIGHEST | .147 | 1.503 |
| AVE OF 1/10 HIGHEST | .188 | 1.916 |
| AVE OF 1/100 HIGHEST | .246 | 2.510 |

STATISTICS OF ACCELERATION

SINGLE AMP

| | SURGE (FEET /SEC**2) | SWAY (FEET /SEC**2) | HEAVY (FEET /S |
|----------------------|--------------------------|-------------------------|--------------------|
| ROOT MEAN SQUARE | .052 | .565 | .7 |
| AVE OF 1/3 HIGHEST | .103 | 1.129 | 1.4 |
| AVE OF 1/10 HIGHEST | .132 | 1.440 | 1.8 |
| AVE OF 1/100 HIGHEST | .172 | 1.886 | 2.4 |

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A-17

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*****
*** OSCAR ***
-----
DATE 84/02/1
*
*
*
ANGLE = 0.00 DEG. G-METACENTER = 32.4 FEET *
WD SPFFD = 0.00 KNOTS WAVE STEEPNESS = 1/20 *
GY. RADIUS = 145.0 FEET YAW GY. RADIUS = 145.0 FEET *
*****

```

MOTIONS IN IRREGULAR SEAS

OF BODY FITK

SEA SPECTRUM

HEIGHT = 6.0 FEET MEAN PERIOD = 5.5 SECONDS

AMPLITUDE MOTIONS

| | SWAY -- (FEET) -- | HEAVE -- (FEET) -- | ROLL -- (DEG) -- | PITCH -- (DEG) -- | YAW -- (DEG) -- |
|----|------------------------|-------------------------|---------------------|----------------------|--------------------|
| 74 | .751 | .924 | .957 | .108 | .063 |
| 47 | 1.503 | 1.848 | 1.913 | .216 | .126 |
| 88 | 1.916 | 2.356 | 2.440 | .276 | .161 |
| 46 | 2.510 | 3.086 | 3.195 | .361 | .211 |

ACCELERATION IN IRREGULAR SEAS

SINGLE AMPLITUDES

| | HEAVE (FEET /SEC**2) | ROLL (DEG/SEC**2) | PITCH (DEG/SEC**2) | YAW (DEG/SEC**2) |
|----|--------------------------|----------------------|-----------------------|---------------------|
| 65 | .736 | .894 | .082 | .048 |
| 29 | 1.472 | 1.788 | .165 | .095 |
| 40 | 1.877 | 2.280 | .210 | .122 |
| 66 | 2.459 | 2.987 | .275 | .159 |

(2)

APPENDIX B

CONNECTION ANALYSIS

Appendix B: FINGER/SPINE CONNECTION ANALYSIS

A description of the mathematical model of the connection is shown in Fig. B-1. The links are modelled as struts with an axial stiffness of 232,000 kips/ft. The shear key is also modelled as a strut, the stiffness of this strut can be assumed to have a value which represents the stiffness of the fendering at the key interface. In actuality the stiffness will not be linear and will be effective for a certain displacement equivalent to the maximum displacement the fender can withstand. The non-linearity of the stiffness will be neglected in this analysis. The effect of increased stiffness can be determined by varying the stiffness of the structural components relative to each other.

The model assumes that all vertical motions due to roll, pitch and heave at the connection interface are unconstrained. The links resist yaw and surge and the shear key resists sway. It is assumed that the tolerance and low friction at the shear key, and the hinges in the links will provide the freedom of movement in the vertical plane.

The most significant limitation is due to the assumption that neglects the effect of pitch. Pitching can cause axial deformation in the links which are placed at the deck level. The displacements at the deck level will be increased if the bottom of the finger pier pivots against the hull of the spine pier. This effect can be reduced by tapering the connection end of the finger pier, shown in Fig. 6. Or in other words the depth of the area bearing against the spine pier should be minimized.

From the summary of motions (p.A-6) it is evident that a wave heading of 110 degrees will impose the most severe forces on the links. The forces in the links are caused by surge and the yaw moment. The contribution from surge will not be very significant, but the yaw moment has to be resisted by a tension-compression couple in the links.

OSCAR could not be used to model the connection as described above. Another approach was taken to estimate the forces in the links. The theoretical justification of the approach taken to analyze the forces in the connection structure is as follows:

Virtual Mass Matrix

The virtual (added) mass and damping co-efficients for various frequencies for the finger pier are reported in the OSCAR output.

If the mass coefficients are multiplied by M_I .

$$M_I = \text{inherent vessel mass}$$

The results represent the diagonal of the virtual mass matrix evaluated 250 ft. from the centroid of the vessel. The actual virtual mass matrix is nearly diagonal when evaluated at the centroid. If:

$$M'_i = \text{diagonal from OSCAR.}$$

$$M_{oi} = \text{diagonal at centroid.}$$

$$\text{Surge : } M_{01} = M'_1$$

$$\text{Sway : } M_{02} = M'_2$$

$$\text{Heave : } M_{03} = M'_3$$

$$\text{Roll : } M_{04} = M'_4$$

$$\text{Pitch : } M_{05} + M_{03}(250)^2 = M'_5$$

$$M_{05} = M'_5 - M_{03}(250)^2$$

$$\text{Yaw : } M_{06} + M_{02}(250)^2 = M'_6$$

$$M_{06} = M'_6 - M_{02}(250)^2$$

The computed mass properties at centroid are included in Appendix B., P. B-13.

Inherent Mass Matrix

The inherent mass matrix is diagonal at the centeroid.

$$\begin{aligned}
 M &= \text{total vessel mass} \\
 M &= \text{displacement}/g = 12 \times 80 \times 500 \times 0.064 / 32.2 = 954 \text{ kip} \cdot \text{s}^2/\text{ft} \\
 M_1 &= M = 954 \text{ kip} \cdot \text{s}^2/\text{ft} \quad \text{surge} \\
 M_2 &= M = 954 \quad \text{sway} \\
 M_3 &= M = 954 \quad \text{heave} \\
 M_4 &= \frac{1}{2} M (30^2 + 80^2) = 580 \times 10^3 \text{ kip} \cdot \text{ft}^2 \cdot \text{s}^2/\text{ft} \quad \text{roll} \\
 M_5 &= \frac{1}{2} M (500^2 + 30^2) = 642.3 \times 10^6 \quad \text{pitch} \\
 M_6 &= \frac{1}{2} M (80^2 + 500^2) = 656.4 \times 10^6 \quad \text{yaw}
 \end{aligned}$$

Damping Matrix

Assume if the added damping coefficients^o reported in OSCAR are multiplied by M_1 , the results represent the diagonal the damping matrix evaluated 250 feet from the centeroid of the vessel. The actual damping matrix at the centeroid is nearly diagonal. If:

$$\begin{aligned}
 C_i' &= \text{diagonal from OSCAR} \\
 C_{oi} &= \text{diagonal at centeroid} \\
 \text{Surge} : C_{o1} &= C_1' \\
 \text{Sway} : C_{o2} &= C_2' \\
 \text{Heave} : C_{o3} &= C_3' \\
 \text{Roll} : C_{o4} &= C_4' \\
 \text{Pitch} : C_{o5} &= C_5' - C_{o3} (250)^2 \\
 \text{Yaw} : C_{o6} &= C_6' - C_{o2} (250)^2
 \end{aligned}$$

Stiffness Matrix

At the centroid of the vessel, the stiffness matrix is diagonal.

$$K_{11} = 0 \quad \text{surge}$$

$$K_{22} = 0 \quad \text{sway}$$

$$K_{33} = 500 \times 80 \times 0.064 = 2560 \text{ Kip/ft.} \quad \text{heave}$$

$$K_{44} = GM \times \text{displacement} = 32.4 \times 30720 = 995 \times 10^3 \text{ Kip-ft.} \quad \text{roll}$$

$$K_{55} = \frac{1}{12} \times 80 \times 500^3 \times 0.064 = 53.3 \times 10^6 \text{ Kip-ft} \quad \text{pitch}$$

$$K_{66} = 0 \quad \text{YAW}$$

Dynamic Equations:

The equation of motion is:

$$M\ddot{V} + C\dot{V} + KV = P$$

where:

$$V = V_c \cos(\omega t) + V_s \sin(\omega t)$$

$$V_c = V \cos(\theta)$$

$$V_s = V \sin(\theta)$$

$$\dot{V} = -\omega V_c \sin(\omega t) + \omega V_s \cos(\omega t)$$

$$\ddot{V} = -\omega^2 V_c \cos(\omega t) - \omega^2 V_s \sin(\omega t)$$

$$P = P_c \cos(\omega t) + P_s \sin(\omega t)$$

$$-\omega^2 M V_c + \omega C V_s + K V_c = P_c$$

$$-\omega^2 M V_s - \omega C V_c + K V_s = P_s$$

expressing in complex numbers.

$$-\omega^2 M V_c - i \omega C V_s + K V_c = P_c$$

$$-\omega^2 M V_s - i \omega C V_c + K V_s = i P_s$$

$$\begin{array}{ccc}
 [-\omega^2 M - i\omega C + K] & [V_c + i V_s] & = & [P_c + i P_s] \\
 \text{dynamic matrix} & \text{displ. vector} & & \text{force vector} \\
 (6 \times 6) & (6 \times 1) & & (6 \times 1)
 \end{array}$$

(*for each encounter frequency)

The dynamic matrix was evaluated at the joint end of the finger pier. Then for a heading of 110° the RAO's reported for the free-floating case were converted to V_c and V_s for the respective phase angles. These were multiplied with the dynamic matrix to obtain the force vectors. After the force vectors were computed the system of equations was solved for displacements, with the joint stiffness included in the stiffness component of the dynamic matrix.

The forces in the structural components were calculated from the computed displacement for each wave frequency. Then a force amplitude spectrum was obtained for an irregular sea with 6 feet significant wave height and a mean period of 5.5 seconds. Results were reported for average of 1/3 of spectral peak values times 1.92, to give a value which has a probability of being exceeded of 0.001.

A parametric study was done to determine the effect of varying the stiffness of the connection components relative to each other. The response of the system (RAO's) was calculated for the following structural stiffnesses:

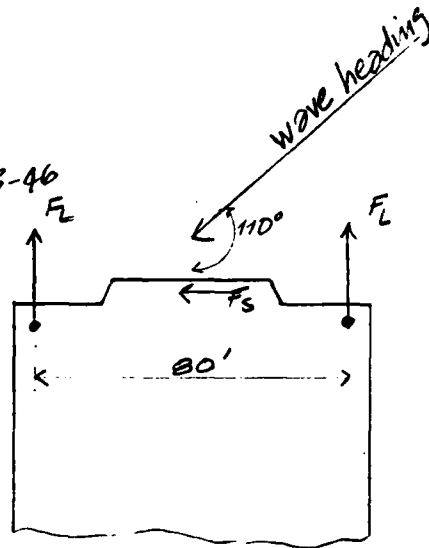
| | <u>Surge (k/f)</u> | <u>Sway (k/f)</u> | <u>Yaw (k-f/f)</u> |
|--------|--------------------|-------------------|--------------------|
| Case 1 | 4.64E5 | 1.0E5 | 7.4E8 |
| Case 2 | 2.32E5 | 1.0E5 | 3.712E8 |
| Case 3 | 2.3E5 | 0.5E5 | 3.712E8 |
| Case 4 | ∞ | ∞ | ∞ |

An insignificant difference was observed in the response for the above four trials see pp. B-36 to B-44. Hence, it can be concluded that for the range of stiffness and wave frequencies studied, the system was insignificant dynamic amplification and the forces generated in the connection components are essentially due to resisting the motions of the pier.

Connection Loading:

Linear motion (wave) 110° heading from p. B-46

Surge: $440/2 = 220 \text{ K} / \text{Link}$
Sway: 1137 K
Yaw: $\frac{323400 \text{ K-F}}{80 \text{ F}} = \pm 4040 \text{ K} / \text{Link}$



Wave Drift: (110° heading) from p. _____

Surge: $7.7/2 = 3.85 \text{ K} / \text{Link}$
Sway: 42.7 K
Yaw: $\frac{10900 \text{ K-F}}{80 \text{ F}} = \pm 136 \text{ K} / \text{Link}$

Wind and current: (broadside)

Total lateral force = $30 + 62 = 92 \text{ K}$ @ 333 FT. from conn.
(calculated on pp. A-1 & A-2)

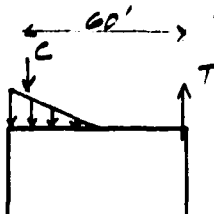
\therefore Sway: = 92 K
Yaw: = $\frac{92 \times 333}{80} = \pm 383 \text{ K} / \text{Link}$

$\therefore F_S = 1137 + 42.7 + 92 = 1272 \text{ kips}$

$F_L = 220 + 4 + 4040 + 136 + 383 \approx 4800 \text{ kips}$

Tension or comp.
in each link.

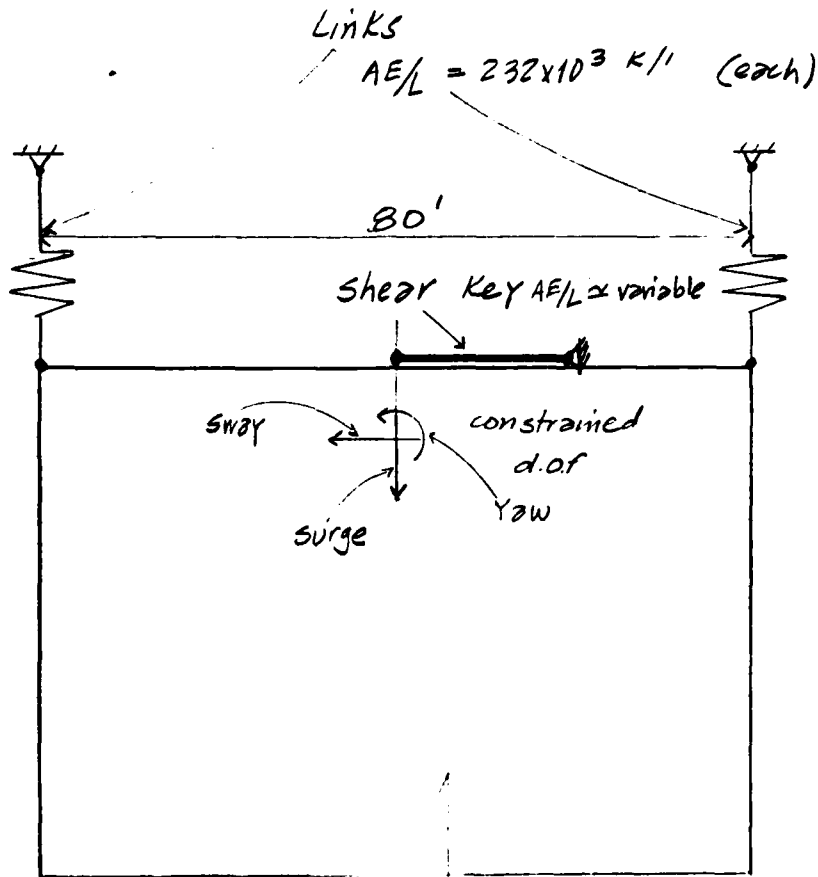
If finger pier is allowed to bear against the spine pier at the compression end. The moment arm will be reduced.



Assume moment arm is 60'

$\therefore F_L = 224 + (4559) \frac{80}{60} \approx 6300 \text{ kips}$
Tension.

Finger/spine connection: Analytical Model.



Note: all motions in vertical plane are unconstrained.

Fig. B-1

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COEFFICIENT VERIFICATION - VIRTUAL MASS COEFFICIENTS FOR 110° HEADING

| FREQ | SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|--------|--------|--------|--------|---------|----------|----------|
| 0.2510 | 0.0434 | 0.3750 | 3.8341 | 26.5903 | 580.9455 | 181.8438 |
| 0.3140 | 0.0434 | 0.3931 | 3.2452 | 26.9235 | 534.4749 | 186.0253 |
| 0.3310 | 0.0434 | 0.4024 | 3.1210 | 27.1247 | 524.1480 | 188.2109 |
| 0.3490 | 0.0434 | 0.4092 | 2.9930 | 27.2469 | 513.2859 | 189.7797 |
| 0.3700 | 0.0434 | 0.4128 | 2.8609 | 27.2763 | 501.8358 | 190.6207 |
| 0.3930 | 0.0434 | 0.4211 | 2.7291 | 27.4037 | 490.1402 | 192.5225 |
| 0.4190 | 0.0434 | 0.4300 | 2.5954 | 27.5311 | 477.9800 | 194.5601 |
| 0.4330 | 0.0434 | 0.4328 | 2.5267 | 27.5458 | 471.6106 | 195.1736 |
| 0.4470 | 0.0434 | 0.4368 | 2.4592 | 27.5814 | 465.2771 | 196.0856 |
| 0.4650 | 0.0434 | 0.4427 | 2.3935 | 27.6483 | 459.0080 | 197.3986 |
| 0.4830 | 0.0434 | 0.4470 | 2.3261 | 27.6737 | 452.4993 | 198.3503 |
| 0.5030 | 0.0434 | 0.4496 | 2.2570 | 27.6578 | 445.7342 | 198.9460 |
| 0.5240 | 0.0434 | 0.4535 | 2.1934 | 27.6440 | 439.4028 | 199.7877 |
| 0.5450 | 0.0434 | 0.4559 | 2.1286 | 27.5920 | 432.8659 | 200.3213 |
| 0.5710 | 0.0434 | 0.4564 | 2.0624 | 27.4905 | 426.0876 | 200.4254 |
| 0.5980 | 0.0434 | 0.4539 | 2.0040 | 27.3034 | 420.0075 | 199.8947 |
| 0.6280 | 0.0434 | 0.4498 | 1.9422 | 27.0726 | 413.4803 | 198.9768 |
| 0.6610 | 0.0434 | 0.4386 | 1.8895 | 26.6858 | 407.8318 | 196.4976 |
| 0.6980 | 0.0434 | 0.4250 | 1.8349 | 26.2537 | 401.9000 | 193.4205 |
| 0.7390 | 0.0434 | 0.4011 | 1.7923 | 25.5880 | 397.2019 | 187.9106 |
| 0.7830 | 0.0434 | 0.3712 | 1.7546 | 24.8302 | 393.0046 | 180.7531 |
| 0.8380 | 0.0434 | 0.3343 | 1.7249 | 23.9575 | 389.6655 | 171.5365 |
| 0.8930 | 0.0434 | 0.2904 | 1.7077 | 23.0037 | 387.7215 | 159.8926 |
| 0.9670 | 0.0434 | 0.2418 | 1.7071 | 22.0523 | 387.6496 | 145.8831 |
| 1.0470 | 0.0434 | 0.1916 | 1.7253 | 21.2008 | 389.7071 | 129.8768 |
| 1.1420 | 0.0434 | 0.1433 | 1.7621 | 20.5260 | 393.8479 | 112.3184 |
| 1.2570 | 0.0434 | 0.0995 | 1.9255 | 20.1459 | 411.7032 | 93.5830 |
| 1.3260 | 0.0434 | 0.0628 | 2.1588 | 20.0510 | 435.9280 | 74.3735 |
| 1.5710 | 0.0434 | 0.0354 | 2.2974 | 20.2431 | 449.7080 | 55.7999 |
| 2.0940 | 0.0434 | 0.0119 | 2.2909 | 21.0149 | 449.0621 | 32.4328 |

COEFFICIENT VERIFICATION - DAMPING COEFFICIENTS

| FREQ | SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|--------|---------|--------|--------|----------|-------------|------------|
| 0.2510 | 0.0000 | 0.0016 | 0.9006 | 2.3815 | 79270.7031 | 140.5000 |
| 0.3140 | 0.0000 | 0.0049 | 1.0133 | 7.0537 | 89191.7969 | 428.9000 |
| 0.3310 | 0.0000 | 0.0070 | 1.0364 | 9.9071 | 91224.7031 | 613.6000 |
| 0.3490 | 0.0000 | 0.0091 | 1.0595 | 12.8482 | 93259.7969 | 804.1000 |
| 0.3700 | 0.0000 | 0.0113 | 1.0826 | 15.7893 | 95294.8984 | 994.5000 |
| 0.3930 | 0.0000 | 0.0136 | 1.1036 | 21.3721 | 97140.2969 | 1373.0000 |
| 0.4170 | 0.0000 | 0.0213 | 1.1231 | 28.6838 | 98861.5000 | 1874.4000 |
| 0.4330 | 0.0000 | 0.0241 | 1.1329 | 32.3396 | 99722.1016 | 2125.1001 |
| 0.4470 | 0.0000 | 0.0285 | 1.1409 | 37.6575 | 100427.0000 | 2505.5000 |
| 0.4650 | 0.0000 | 0.0347 | 1.1466 | 45.1498 | 100929.2031 | 3055.5000 |
| 0.4830 | 0.0000 | 0.0410 | 1.1523 | 52.6421 | 101431.0000 | 3605.5000 |
| 0.5010 | 0.0000 | 0.0472 | 1.1580 | 60.1344 | 101932.8984 | 4155.5000 |
| 0.5240 | 0.0000 | 0.0581 | 1.1581 | 72.2529 | 101943.1016 | 5113.6001 |
| 0.5460 | 0.0000 | 0.0697 | 1.1573 | 85.1342 | 101872.1016 | 6139.0000 |
| 0.5710 | 0.0000 | 0.0820 | 1.1558 | 98.4902 | 101736.2969 | 7214.8999 |
| 0.5980 | 0.0000 | 0.1006 | 1.1460 | 117.1492 | 100874.8984 | 8854.7998 |
| 0.6280 | 0.0000 | 0.1192 | 1.1362 | 135.8082 | 100013.5000 | 10494.5996 |
| 0.6610 | 0.0000 | 0.1440 | 1.1166 | 157.9806 | 98289.1016 | 12674.9004 |
| 0.6980 | 0.0000 | 0.1700 | 1.0948 | 180.7265 | 96368.8984 | 14963.7998 |
| 0.7390 | 0.0000 | 0.2010 | 1.0602 | 203.8295 | 93324.5000 | 17696.0996 |
| 0.7850 | 0.0000 | 0.2332 | 1.0175 | 224.7739 | 89563.5000 | 20529.4004 |
| 0.8380 | 0.0000 | 0.2661 | 0.9636 | 241.9033 | 84821.1016 | 23419.5996 |
| 0.8980 | 0.0000 | 0.2973 | 0.8952 | 251.9104 | 78798.6016 | 26169.0996 |
| 0.9470 | 0.0000 | 0.3240 | 0.8099 | 251.9838 | 71292.1016 | 28521.0996 |
| 1.0470 | 0.0000 | 0.3439 | 0.7072 | 241.0362 | 62247.8984 | 30268.1992 |
| 1.1420 | 0.0000 | 0.3554 | 0.5882 | 219.6012 | 51777.6016 | 31282.5000 |
| 1.2570 | 0.0000 | 0.3556 | 0.4676 | 187.6325 | 41159.8984 | 31301.6992 |
| 1.3960 | 0.0000 | 0.3445 | 0.3614 | 149.1666 | 31808.5996 | 30322.1992 |
| 1.5710 | -0.0000 | 0.3202 | 0.2551 | 108.0222 | 22457.1992 | 28186.0000 |
| 2.0940 | 0.0000 | 0.2293 | 0.0427 | 40.0080 | 3754.5000 | 20183.5996 |

PROPERTIES AT CENTROID - VIRTUAL MASS / VESSEL MASS

| FREQ | SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|--------|--------|--------|--------|----------|------------|------------|
| 0.2510 | 0.0434 | 0.3750 | 3.8341 | 707.0440 | 97866.3984 | 9629.6699 |
| 0.3140 | 0.0434 | 0.3931 | 3.2452 | 724.8749 | 82838.4375 | 10036.6621 |
| 0.3310 | 0.0434 | 0.4024 | 3.1210 | 735.7494 | 79668.6172 | 10273.3447 |
| 0.3490 | 0.0434 | 0.4092 | 2.9930 | 742.3936 | 76399.9141 | 10441.3320 |
| 0.3700 | 0.0434 | 0.4128 | 2.8609 | 743.9966 | 73032.9219 | 10536.2480 |
| 0.3930 | 0.0434 | 0.4211 | 2.7291 | 750.9628 | 69668.6563 | 10746.1670 |
| 0.4190 | 0.0434 | 0.4300 | 2.5954 | 757.9614 | 66252.4063 | 10978.6299 |
| 0.4330 | 0.0434 | 0.4328 | 2.5267 | 758.7711 | 64497.7891 | 11042.7314 |
| 0.4490 | 0.0434 | 0.4368 | 2.4592 | 760.7336 | 62782.7695 | 11149.5625 |
| 0.4650 | 0.0434 | 0.4427 | 2.3935 | 764.4285 | 61094.6016 | 11297.4639 |
| 0.4830 | 0.0434 | 0.4470 | 2.3261 | 765.8337 | 59374.3516 | 11405.3379 |
| 0.5030 | 0.0434 | 0.4496 | 2.2570 | 764.9539 | 57616.4805 | 11479.5137 |
| 0.5240 | 0.0434 | 0.4535 | 2.1934 | 764.1907 | 55987.3477 | 11571.3740 |
| 0.5460 | 0.0434 | 0.4559 | 2.1286 | 761.3184 | 54335.3945 | 11634.8721 |
| 0.5710 | 0.0434 | 0.4564 | 2.0624 | 755.7275 | 52650.6211 | 11645.3418 |
| 0.5980 | 0.0434 | 0.4539 | 2.0040 | 745.4756 | 51156.3242 | 11589.1377 |
| 0.6280 | 0.0434 | 0.4498 | 1.9422 | 732.9257 | 49578.4492 | 11479.2686 |
| 0.6610 | 0.0434 | 0.4386 | 1.8895 | 712.1320 | 48233.0156 | 11198.8076 |
| 0.6980 | 0.0434 | 0.4250 | 1.8349 | 689.2568 | 46842.3711 | 10848.9932 |
| 0.7390 | 0.0434 | 0.4011 | 1.7923 | 654.7457 | 45750.6133 | 10241.6436 |
| 0.7850 | 0.0434 | 0.3712 | 1.7546 | 616.5388 | 44790.1250 | 9471.6797 |
| 0.8380 | 0.0434 | 0.3343 | 1.7249 | 573.9619 | 44032.9453 | 8531.0186 |
| 0.8980 | 0.0434 | 0.2904 | 1.7077 | 529.1702 | 43596.7109 | 7415.6411 |
| 0.9670 | 0.0434 | 0.2418 | 1.7071 | 486.3039 | 43578.4492 | 6169.3784 |
| 1.0470 | 0.0434 | 0.1916 | 1.7253 | 449.4739 | 44040.3828 | 4892.9829 |
| 1.1420 | 0.0434 | 0.1433 | 1.7621 | 421.3166 | 44984.9180 | 3659.1724 |
| 1.2570 | 0.0434 | 0.0995 | 1.9255 | 405.8573 | 49155.7656 | 2539.0281 |
| 1.3960 | 0.0434 | 0.0628 | 2.1588 | 402.0426 | 55108.2422 | 1606.4170 |
| 1.5710 | 0.0434 | 0.0354 | 2.2974 | 409.7831 | 58649.8008 | 901.1288 |
| 2.0940 | 0.0434 | 0.0119 | 2.2909 | 441.6260 | 58475.5156 | 308.1364 |

PROPERTIES AT CENTROID - DAMPING / VESSEL MASS

| FREQ | SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|--------|--------|--------|--------|----------|------------|------------|
| 0.2510 | 0.0434 | 0.3750 | 3.8341 | 707.0440 | 97866.3984 | 9629.6699 |
| 0.3140 | 0.0434 | 0.3931 | 3.2452 | 724.8749 | 82838.4375 | 10036.6621 |
| 0.3310 | 0.0434 | 0.4024 | 3.1210 | 735.7494 | 79668.6172 | 10273.3447 |
| 0.3490 | 0.0434 | 0.4092 | 2.9930 | 742.3936 | 76399.9141 | 10441.3320 |
| 0.3700 | 0.0434 | 0.4128 | 2.8409 | 743.9966 | 73032.9219 | 10536.2480 |
| 0.3930 | 0.0434 | 0.4211 | 2.7291 | 750.9628 | 69668.6563 | 10746.1670 |
| 0.4190 | 0.0434 | 0.4300 | 2.5954 | 757.9614 | 66252.4063 | 10978.6299 |
| 0.4330 | 0.0434 | 0.4328 | 2.5267 | 758.7711 | 64497.7891 | 11042.7314 |
| 0.4490 | 0.0434 | 0.4368 | 2.4592 | 760.7336 | 62782.7695 | 11149.5625 |
| 0.4650 | 0.0434 | 0.4427 | 2.3935 | 764.4285 | 61094.6016 | 11297.4639 |
| 0.4830 | 0.0434 | 0.4470 | 2.3261 | 765.8337 | 59374.3516 | 11405.3379 |
| 0.5030 | 0.0434 | 0.4496 | 2.2570 | 764.9539 | 57616.4805 | 11479.5137 |
| 0.5240 | 0.0434 | 0.4535 | 2.1934 | 764.1907 | 55987.3477 | 11571.3740 |
| 0.5460 | 0.0434 | 0.4559 | 2.1286 | 761.3184 | 54335.3945 | 11634.8721 |
| 0.5710 | 0.0434 | 0.4564 | 2.0624 | 755.7275 | 52650.6211 | 11645.3418 |
| 0.5980 | 0.0434 | 0.4539 | 2.0040 | 745.4756 | 51156.3242 | 11589.1377 |
| 0.6280 | 0.0434 | 0.4498 | 1.9422 | 732.9257 | 49578.4492 | 11479.2686 |
| 0.6610 | 0.0434 | 0.4386 | 1.8895 | 712.1320 | 48233.0156 | 11198.8076 |
| 0.6980 | 0.0434 | 0.4250 | 1.8349 | 689.2568 | 46842.3711 | 10848.9932 |
| 0.7390 | 0.0434 | 0.4011 | 1.7923 | 654.7457 | 45750.6133 | 10241.6436 |
| 0.7850 | 0.0434 | 0.3712 | 1.7546 | 616.5388 | 44790.1250 | 9471.6797 |
| 0.8380 | 0.0434 | 0.3343 | 1.7249 | 573.9619 | 44032.9453 | 8531.0186 |
| 0.8980 | 0.0434 | 0.2904 | 1.7077 | 529.1702 | 43596.7109 | 7415.6411 |
| 0.9670 | 0.0434 | 0.2418 | 1.7071 | 486.3039 | 43578.4492 | 6169.3784 |
| 1.0470 | 0.0434 | 0.1916 | 1.7253 | 449.4739 | 44040.3828 | 4892.9829 |
| 1.1420 | 0.0434 | 0.1433 | 1.7621 | 421.3166 | 44984.9180 | 3659.1724 |
| 1.2570 | 0.0434 | 0.0995 | 1.9255 | 405.8573 | 49155.7656 | 2539.0281 |
| 1.3960 | 0.0434 | 0.0628 | 2.1588 | 402.0426 | 55108.2422 | 1606.4170 |
| 1.5710 | 0.0434 | 0.0354 | 2.2974 | 409.7831 | 58649.8008 | 901.1288 |
| 2.0940 | 0.0434 | 0.0119 | 2.2909 | 441.6260 | 58475.5156 | 308.1364 |

DYNAMIC MATRICES

K(REAL) - FREQ = 0.251

| | | | | | | | |
|-------------|-------------|-------------|------------|------------|------------|------------|-------------|
| -6.2714E+01 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -8.2645E+01 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -2.0661E+04 |
| 0.0000E+00 | 0.0000E+00 | 2.2694E+03 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -9.5785E+01 |
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 9.1627E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | -5.6736E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 1.8803E+08 | 0.0000E+00 |
| 0.0000E+00 | -2.0661E+04 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -7.0283E+06 |

K(IMAGINARY) - FREQ = 0.251

| | | | | | | | |
|------------|-------------|-------------|-------------|------------|------------|-------------|-------------|
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -3.8314E-01 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | -2.1566E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -9.5785E+01 |
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -5.7028E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 5.3915E+04 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -1.8982E+07 | 0.0000E+00 |
| 0.0000E+00 | -9.5785E+01 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -3.3645E+04 |

K(REAL) - FREQ = 0.314

| | | | | | | | |
|-------------|-------------|-------------|------------|------------|------------|------------|-------------|
| -9.6147E+01 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -1.3104E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -3.2760E+04 |
| 0.0000E+00 | 0.0000E+00 | 2.1607E+03 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 8.6992E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | -5.4017E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 1.7862E+08 | 0.0000E+00 |
| 0.0000E+00 | -3.2760E+04 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -1.1144E+07 |

K(IMAGINARY) - FREQ = 0.314

| | | | | | | | |
|------------|-------------|-------------|-------------|------------|------------|-------------|-------------|
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -1.4679E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | -3.0355E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -3.6697E+02 |
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -2.1131E+03 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 7.5888E+04 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -2.6719E+07 | 0.0000E+00 |
| 0.0000E+00 | -3.6697E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -1.2848E+05 |

K(REAL) - FREQ = 0.331

| | | | | | | | |
|-------------|-------------|-------------|------------|------------|------------|------------|-------------|
| -1.0706E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -1.4659E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -3.6647E+04 |
| 0.0000E+00 | 0.0000E+00 | 2.1293E+03 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 8.5484E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | -5.3231E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 1.7590E+08 | 0.0000E+00 |
| 0.0000E+00 | -3.6647E+04 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -1.2469E+07 |

K(IMAGINARY) - FREQ = 0.331

| | | | | | | | |
|------------|-------------|-------------|-------------|------------|------------|-------------|-------------|
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -2.2105E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | -3.2728E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -5.5263E+02 |
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -3.1285E+03 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 8.1820E+04 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -2.8808E+07 | 0.0000E+00 |

0.0000E+00 -5.5263E+02 0.0000E+00 0.0000E+00 0.0000E+00 -1.9377E+05

K(REAL) - FREQ = 0.349

-1.2125E+02 0.0000E+00
0.0000E+00 -1.6375E+02
0.0000E+00 0.0000E+00
0.0000E+00 0.0000E+00
0.0000E+00 0.0000E+00
0.0000E+00 -4.0738E+04

K(IMAGINARY) - FREQ = 0.349

0.0000E+00 0.0000E+00
0.0000E+00 -3.0299E+00
0.0000E+00 0.0000E+00
0.0000E+00 0.0000E+00
0.0000E+00 -3.5277E+02
0.0000E+00 8.8193E+04
0.0000E+00 8.8193E+04
0.0000E+00 -7.5748E+02

K(REAL) - FREQ = 0.370

-1.3628E+02 0.0000E+00
0.0000E+00 -1.8452E+02
0.0000E+00 0.0000E+00
0.0000E+00 0.0000E+00
0.0000E+00 0.0000E+00
0.0000E+00 -5.1393E+05
0.0000E+00 8.1870E+05
0.0000E+00 1.6955E+08
0.0000E+00 -1.5699E+07

K(IMAGINARY) - FREQ = 0.370

0.0000E+00 0.0000E+00
0.0000E+00 -3.9888E+00
0.0000E+00 0.0000E+00
0.0000E+00 0.0000E+00
0.0000E+00 -3.8215E+02
0.0000E+00 9.5538E+04
0.0000E+00 9.5538E+04
0.0000E+00 -9.9721E+02

K(REAL) - FREQ = 0.393

-1.5375E+02 0.0000E+00
0.0000E+00 -2.0940E+02
0.0000E+00 0.0000E+00
0.0000E+00 0.0000E+00
0.0000E+00 2.0105E+03
0.0000E+00 7.9504E+05
0.0000E+00 1.6564E+08
0.0000E+00 -1.7819E+07

K(IMAGINARY) - FREQ = 0.393

0.0000E+00 0.0000E+00
0.0000E+00 -5.8490E+00
0.0000E+00 0.0000E+00
0.0000E+00 0.0000E+00
0.0000E+00 -4.1378E+02
0.0000E+00 0.0000E+00
0.0000E+00 0.0000E+00
0.0000E+00 -8.0132E+03

0.0000E+00 -5.5263E+02 0.0000E+00 0.0000E+00 0.0000E+00 -1.9377E+05

K(REAL) - FREQ = 0.349

-1.2125E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -1.6375E+02 0.0000E+00 0.0000E+00 0.0000E+00 -4.0938E+04
 0.0000E+00 0.0000E+00 2.0960E+03 0.0000E+00 -5.2400E+05 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 8.3837E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -5.2400E+05 0.0000E+00 1.7303E+08 0.0000E+00
 0.0000E+00 -4.0938E+04 0.0000E+00 0.0000E+00 0.0000E+00 -1.3931E+07

K(IMAGINARY) - FREQ = 0.349

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -3.0299E+00 0.0000E+00 0.0000E+00 0.0000E+00 -7.5748E+02
 0.0000E+00 0.0000E+00 0.0000E+00 -3.5277E+02 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 8.8193E+04 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 8.8193E+04 0.0000E+00 -3.1052E+07 0.0000E+00
 0.0000E+00 -7.5748E+02 0.0000E+00 0.0000E+00 0.0000E+00 -2.6773E+05

K(REAL) - FREQ = 0.370

-1.3628E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -1.8452E+02 0.0000E+00 0.0000E+00 0.0000E+00 -4.6131E+04
 0.0000E+00 0.0000E+00 2.0557E+03 0.0000E+00 -5.1393E+05 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 8.1870E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -5.1393E+05 0.0000E+00 1.6755E+08 0.0000E+00
 0.0000E+00 -4.6131E+04 0.0000E+00 0.0000E+00 0.0000E+00 -1.5699E+07

K(IMAGINARY) - FREQ = 0.370

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -3.9888E+00 0.0000E+00 0.0000E+00 0.0000E+00 -9.9721E+02
 0.0000E+00 0.0000E+00 0.0000E+00 -3.8215E+02 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 9.5538E+04 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 9.5538E+04 0.0000E+00 -3.3639E+07 0.0000E+00
 0.0000E+00 -9.9721E+02 0.0000E+00 0.0000E+00 0.0000E+00 -3.5105E+05

K(REAL) - FREQ = 0.393

-1.5375E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -2.0940E+02 0.0000E+00 0.0000E+00 0.0000E+00 -5.2350E+04
 0.0000E+00 0.0000E+00 2.0105E+03 0.0000E+00 -5.0263E+05 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 7.9504E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -5.0263E+05 0.0000E+00 1.6564E+08 0.0000E+00
 0.0000E+00 -5.2350E+04 0.0000E+00 0.0000E+00 0.0000E+00 -1.7819E+07

K(IMAGINARY) - FREQ = 0.393

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -5.8490E+00 0.0000E+00 0.0000E+00 0.0000E+00 -1.4623E+03
 0.0000E+00 0.0000E+00 -4.1378E+02 0.0000E+00 1.0345E+05 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 -8.0132E+03 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00

0.0000E+00 0.0000E+00 1.0345E+05 0.0000E+00 -3.6421E+07 0.0000E+00 0.0000E+00
 0.0000E+00 -1.4623E+03 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -5.1479E+05

K(REAL) - FREQ = 0.419

-1.7476E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -2.3951E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 1.9378E+03 0.0000E+00 -4.8945E+05 0.0000E+00 -5.9878E+04
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 7.6649E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -4.8945E+05 0.0000E+00 0.0000E+00 1.6110E+08 0.0000E+00
 0.0000E+00 -5.9878E+04 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -2.0387E+07

K(IMAGINARY) - FREQ = 0.419

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -8.5145E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+02 0.0000E+00 1.1224E+05 0.0000E+00 -2.1286E+03
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -1.1466E+04 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 1.1224E+05 0.0000E+00 0.0000E+00 -3.9519E+07 0.0000E+00
 0.0000E+00 -2.1286E+03 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -7.4928E+05

K(REAL) - FREQ = 0.433

-1.8663E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -2.5629E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -6.4072E+04
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 1.9292E+03 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 7.5079E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -4.8229E+05 0.0000E+00 0.0000E+00 1.5863E+08 0.0000E+00
 0.0000E+00 -6.4072E+04 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -2.1815E+07

K(IMAGINARY) - FREQ = 0.433

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -9.9557E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -2.4889E+03
 0.0000E+00 0.0000E+00 0.0000E+02 0.0000E+00 -4.6800E+04 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -1.3359E+04 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 1.1700E+05 0.0000E+00 0.0000E+00 -4.1195E+07 0.0000E+00
 0.0000E+00 -2.4889E+03 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -8.7787E+05

K(REAL) - FREQ = 0.449

-2.0068E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -2.7635E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -6.9087E+04
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 1.8947E+03 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 7.3201E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -4.7367E+05 0.0000E+00 0.0000E+00 1.5645E+08 0.0000E+00
 0.0000E+00 -6.9087E+04 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -2.3526E+07

K(IMAGINARY) - FREQ = 0.449

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -1.2208E+01 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -3.0521E+03
 0.0000E+00 0.0000E+00 0.0000E+02 0.0000E+00 -4.8872E+02 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 1.2218E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -2.3526E+07

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 1.2218E+05 0.0000E+00 -1.6131E+04 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -3.0521E+03 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -4.3019E+07 0.0000E+00 -1.0733E+06

K(REAL) - FREQ = 0.465

-2.1524E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -2.9761E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 1.8600E+03 0.0000E+00 0.0000E+00 0.0000E+00 -4.6499E+05 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 7.1215E+05 0.0000E+00 1.5267E+08 0.0000E+00 -2.5339E+07
 0.0000E+00 -7.4402E+04 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00

K(IMAGINARY) - FREQ = 0.465

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -1.5394E+01 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 -5.0866E+02 0.0000E+00 0.0000E+00 1.2717E+05 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -2.0030E+04 0.0000E+00 -4.4775E+07 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 1.2717E+05 0.0000E+00 0.0000E+00 0.0000E+00 -1.3555E+06

K(REAL) - FREQ = 0.483

-2.3223E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -3.2205E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 1.8197E+03 0.0000E+00 0.0000E+00 -4.5493E+05 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 6.8948E+05 0.0000E+00 1.4920E+08 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 -4.5493E+05 0.0000E+00 0.0000E+00 0.0000E+00 -2.7422E+07
 0.0000E+00 -8.0513E+04 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00

K(IMAGINARY) - FREQ = 0.483

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -1.8893E+01 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 -5.3098E+02 0.0000E+00 0.0000E+00 1.3274E+05 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -2.4257E+04 0.0000E+00 -4.6739E+07 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 1.3274E+05 0.0000E+00 0.0000E+00 0.0000E+00 -1.6614E+06
 0.0000E+00 -4.7232E+03 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00

K(REAL) - FREQ = 0.503

-2.5186E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -3.4990E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 1.7738E+03 0.0000E+00 0.0000E+00 -4.4346E+05 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 6.6384E+05 0.0000E+00 1.4524E+08 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 -4.4346E+05 0.0000E+00 0.0000E+00 0.0000E+00 -2.9797E+07
 0.0000E+00 -8.7476E+04 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00

K(IMAGINARY) - FREQ = 0.503

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -2.2650E+01 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -5.6626E+03

0.0000E+00 0.0000E+00 -5.5570E+02 0.0000E+00 0.0000E+00 1.3893E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 -2.8857E+04 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 1.3893E+05 0.0000E+00 0.0000E+00 -4.8916E+07 0.0000E+00 0.0000E+00
 0.0000E+00 -5.6626E+03 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -1.9941E+06

K(REAL) - FREQ = 0.524

-2.7332E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -3.8075E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 1.7235E+03 0.0000E+00 0.0000E+00 -4.3087E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 6.3579E+05 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -4.3087E+05 0.0000E+00 0.0000E+00 0.0000E+00 1.4091E+08 0.0000E+00 0.0000E+00
 0.0000E+00 -9.5188E+04 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -3.2425E+07

K(IMAGINARY) - FREQ = 0.524

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -2.9045E+01 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 -5.7895E+02 0.0000E+00 1.4474E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -3.6120E+04 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 1.4474E+05 0.0000E+00 0.0000E+00 0.0000E+00 -5.0963E+07 0.0000E+00 0.0000E+00
 0.0000E+00 -7.2613E+03 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -2.5564E+06

K(REAL) - FREQ = 0.546

-2.9676E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -4.1408E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 1.6702E+03 0.0000E+00 0.0000E+00 -4.1755E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 6.0578E+05 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -4.1755E+05 0.0000E+00 0.0000E+00 0.0000E+00 1.3632E+08 0.0000E+00 0.0000E+00
 0.0000E+00 -1.0352E+05 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -3.5266E+07

K(IMAGINARY) - FREQ = 0.546

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -3.6307E+01 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 -6.0284E+02 0.0000E+00 1.5071E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -4.4347E+04 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 1.5071E+05 0.0000E+00 0.0000E+00 0.0000E+00 -5.3066E+07 0.0000E+00 0.0000E+00
 0.0000E+00 -9.0768E+03 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -3.1978E+06

K(REAL) - FREQ = 0.571

-3.2456E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -4.5302E+02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 1.6074E+03 0.0000E+00 0.0000E+00 -4.0186E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 5.7103E+05 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -4.0186E+05 0.0000E+00 0.0000E+00 0.0000E+00 1.3092E+08 0.0000E+00 0.0000E+00
 0.0000E+00 -1.1326E+05 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 -3.8582E+07

K(IMAGINARY) - FREQ = 0.571

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00

0.0000E+00 -4.4670E+01 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -6.2763E+02 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 -5.3653E+04
 0.0000E+00 0.0000E+00 1.5741E+05 0.0000E+00
 0.0000E+00 -1.1167E+04 0.0000E+00 0.0000E+00
 -1.1167E+04 0.0000E+00 1.5741E+05 0.0000E+00
 0.0000E+00 0.0000E+00 -5.3653E+04 0.0000E+00
 0.0000E+00 0.0000E+00 1.5741E+05 0.0000E+00
 0.0000E+00 -3.9304E+06 0.0000E+00 0.0000E+00

K(REAL) - FREQ = 0.598

-3.5397E+02 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -4.9602E+02 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 1.5351E+03 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 5.3345E+05
 0.0000E+00 0.0000E+00 -3.8378E+05 0.0000E+00
 0.0000E+00 -1.2401E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 1.2469E+08 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -1.2401E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 1.2469E+08 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00

K(IMAGINARY) - FREQ = 0.598

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -5.7394E+01 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -6.5381E+02 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 -6.6835E+04
 0.0000E+00 0.0000E+00 1.6345E+05 0.0000E+00
 0.0000E+00 -1.4348E+04 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -5.7394E+01 0.0000E+00
 0.0000E+00 0.0000E+00 -6.5381E+02 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 -6.6835E+04
 0.0000E+00 0.0000E+00 1.6345E+05 0.0000E+00
 0.0000E+00 -5.7551E+07 0.0000E+00 0.0000E+00
 0.0000E+00 -1.4348E+04 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -5.7551E+07 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00

K(REAL) - FREQ = 0.628

-3.9259E+02 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -5.4550E+02 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 1.4530E+03 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 4.9067E+05
 0.0000E+00 0.0000E+00 -3.6324E+05 0.0000E+00
 0.0000E+00 -1.3637E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -5.4550E+02 0.0000E+00
 0.0000E+00 0.0000E+00 1.4530E+03 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 4.9067E+05
 0.0000E+00 0.0000E+00 -3.6324E+05 0.0000E+00
 0.0000E+00 0.0000E+00 1.1762E+08 0.0000E+00
 0.0000E+00 -1.3637E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -5.4550E+02 0.0000E+00
 0.0000E+00 0.0000E+00 1.1762E+08 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00

K(IMAGINARY) - FREQ = 0.628

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -7.1417E+01 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -6.8074E+02 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 -8.1368E+04
 0.0000E+00 0.0000E+00 1.7018E+05 0.0000E+00
 0.0000E+00 -1.7854E+04 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -7.1417E+01 0.0000E+00
 0.0000E+00 0.0000E+00 -6.8074E+02 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 -8.1368E+04
 0.0000E+00 0.0000E+00 1.7018E+05 0.0000E+00
 0.0000E+00 0.0000E+00 -5.9923E+07 0.0000E+00
 0.0000E+00 -1.7854E+04 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -5.9923E+07 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00

K(REAL) - FREQ = 0.661

-4.3493E+02 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -5.9966E+02 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 1.3555E+03 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 4.4491E+05
 0.0000E+00 0.0000E+00 -3.3889E+05 0.0000E+00
 0.0000E+00 -1.4992E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -5.9966E+02 0.0000E+00
 0.0000E+00 0.0000E+00 1.3555E+03 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 4.4491E+05
 0.0000E+00 0.0000E+00 -3.3889E+05 0.0000E+00
 0.0000E+00 0.0000E+00 1.0923E+08 0.0000E+00
 0.0000E+00 -1.4992E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -5.9966E+02 0.0000E+00
 0.0000E+00 0.0000E+00 1.0923E+08 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00

K(IMAGINARY) - FREQ = 0.661

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 -1.4992E+05 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -3.3889E+05 0.0000E+00
 0.0000E+00 0.0000E+00 4.4491E+05 0.0000E+00
 0.0000E+00 0.0000E+00 -3.3889E+05 0.0000E+00
 0.0000E+00 -5.1054E+07 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -1.4992E+05 0.0000E+00
 0.0000E+00 0.0000E+00 -3.3889E+05 0.0000E+00
 0.0000E+00 0.0000E+00 4.4491E+05 0.0000E+00
 0.0000E+00 0.0000E+00 -3.3889E+05 0.0000E+00
 0.0000E+00 0.0000E+00 -5.0518E+06 0.0000E+00
 0.0000E+00 -5.1054E+07 0.0000E+00 0.0000E+00
 0.0000E+00 0.0000E+00 -5.0518E+06 0.0000E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00

| | | | | | | | | | |
|------------|-------------|-------------|-------------|------------|-------------|-------------|------------|------------|-------------|
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -9.0809E+01 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -2.2702E+04 |
| 0.0000E+00 | 0.0000E+00 | -7.0415E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 1.7604E+05 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -9.9626E+04 | 0.0000E+00 | -9.9626E+04 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 1.7604E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -6.1983E+07 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -2.2702E+04 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -7.9930E+06 |

K(REAL) - FREQ = 0.698

| | | | | | | | | | |
|-------------|-------------|-------------|------------|------------|------------|-------------|------------|------------|-------------|
| -4.8498E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -6.6236E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -1.6559E+05 |
| 0.0000E+00 | 0.0000E+00 | 1.2423E+03 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -3.1058E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 3.9219E+05 | 0.0000E+00 | 3.9219E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | -3.1058E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 9.9486E+07 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -1.6559E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -5.6371E+07 |

K(IMAGINARY) - FREQ = 0.698

| | | | | | | | | | |
|------------|-------------|-------------|-------------|------------|-------------|-------------|------------|------------|-------------|
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -1.1321E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -2.8302E+04 |
| 0.0000E+00 | 0.0000E+00 | -7.2905E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 1.8226E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -1.2035E+05 | 0.0000E+00 | -1.2035E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 1.8226E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -6.4174E+07 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -2.8302E+04 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -9.9647E+06 |

K(REAL) - FREQ = 0.739

| | | | | | | | | | |
|-------------|-------------|-------------|------------|------------|------------|-------------|------------|------------|-------------|
| -5.4363E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -7.3000E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -1.8250E+05 |
| 0.0000E+00 | 0.0000E+00 | 1.1052E+03 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -2.7629E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 3.3724E+05 | 0.0000E+00 | 3.3724E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | -2.7629E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 8.7675E+07 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -1.8250E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -6.2094E+07 |

K(IMAGINARY) - FREQ = 0.739

| | | | | | | | | | |
|------------|-------------|-------------|-------------|------------|-------------|-------------|------------|------------|-------------|
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -1.4171E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -3.5428E+04 |
| 0.0000E+00 | 0.0000E+00 | -7.4748E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 1.8687E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -1.4371E+05 | 0.0000E+00 | -1.4371E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 1.8687E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -6.5797E+07 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -3.5428E+04 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -1.2476E+07 |

K(REAL) - FREQ = 0.785

| | | | | | | | | | |
|-------------|-------------|-------------|------------|------------|------------|-------------|------------|------------|-------------|
| -6.1342E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -8.0613E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -2.0153E+05 |
| 0.0000E+00 | 0.0000E+00 | 9.4057E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -2.3514E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 2.7522E+05 | 0.0000E+00 | 2.7522E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | -2.3514E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 7.3494E+07 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -2.0153E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -6.8513E+07 |

K(IMAGINARY) - FREQ = 0.785

K(IMAGINARY) - FREQ = 2.094

| | | | | | |
|------------|-------------|-------------|-------------|-------------|-------------|
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | -4.5809E+02 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -1.1452E+05 |
| 0.0000E+00 | 0.0000E+00 | -8.5304E+01 | 0.0000E+00 | 2.1326E+04 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -7.9926E+04 | 0.0000E+00 | 0.0000E+00 |
| 0.0000E+00 | 0.0000E+00 | 2.1326E+04 | 0.0000E+00 | -7.5006E+06 | 0.0000E+00 |
| 0.0000E+00 | -1.1452E+05 | 0.0000E+00 | 0.0000E+00 | 0.0000E+00 | -4.0322E+07 |

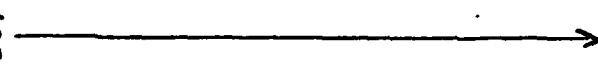
| RAD VERIFICATION - AMPLITUDES | | AT LOCAL ORIGIN | | | | |
|-------------------------------|--------|-----------------|--------|------------|-------------|-----------|
| FREQ # | SURGE | SWAY | HEAVE | ROLL (deg) | PITCH (deg) | YAW (deg) |
| 0.251 | 0.3493 | 0.7637 | 0.6765 | 0.0794 | 0.0340 | 0.0323 |
| | 0.3391 | 0.7574 | 0.6894 | 0.1198 | 0.0495 | 0.0457 |
| | 0.3381 | 0.7614 | 0.6945 | 0.1321 | 0.0543 | 0.0500 |
| | 0.3371 | 0.7668 | 0.7013 | 0.1464 | 0.0599 | 0.0550 |
| | 0.3359 | 0.7733 | 0.7103 | 0.1631 | 0.0665 | 0.0608 |
| | 0.3341 | 0.7817 | 0.7224 | 0.1826 | 0.0744 | 0.0675 |
| | 0.3315 | 0.7919 | 0.7388 | 0.2055 | 0.0838 | 0.0753 |
| | 0.3297 | 0.7971 | 0.7492 | 0.2184 | 0.0892 | 0.0796 |
| | 0.3275 | 0.8029 | 0.7612 | 0.2323 | 0.0951 | 0.0843 |
| | 0.3247 | 0.8090 | 0.7751 | 0.2473 | 0.1015 | 0.0893 |
| | 0.3212 | 0.8151 | 0.7913 | 0.2634 | 0.1087 | 0.0945 |
| | 0.3148 | 0.8212 | 0.8103 | 0.2807 | 0.1166 | 0.1001 |
| | 0.3113 | 0.8267 | 0.8322 | 0.2989 | 0.1253 | 0.1059 |
| | 0.3044 | 0.8313 | 0.8576 | 0.3181 | 0.1349 | 0.1119 |
| | 0.2956 | 0.8344 | 0.8870 | 0.3380 | 0.1455 | 0.1180 |
| | 0.2845 | 0.8343 | 0.9204 | 0.3577 | 0.1572 | 0.1240 |
| | 0.2702 | 0.8303 | 0.9587 | 0.3768 | 0.1701 | 0.1296 |
| | 0.2521 | 0.8197 | 1.0013 | 0.3934 | 0.1841 | 0.1344 |
| | 0.2288 | 0.8001 | 1.0480 | 0.4058 | 0.1992 | 0.1377 |
| | 0.1990 | 0.7679 | 1.0969 | 0.4103 | 0.2151 | 0.1388 |
| | 0.1610 | 0.7184 | 1.1431 | 0.4020 | 0.2308 | 0.1364 |
| | 0.1134 | 0.6459 | 1.1722 | 0.3715 | 0.2434 | 0.1289 |
| | 0.0595 | 0.5464 | 1.1420 | 0.2952 | 0.2444 | 0.1144 |
| | 0.0366 | 0.4871 | 0.9392 | 0.2733 | 0.2087 | 0.0911 |
| | 0.0495 | 0.2796 | 0.4955 | 0.3274 | 0.1151 | 0.0583 |
| | 0.0510 | 0.0749 | 0.1374 | 0.1715 | 0.0238 | 0.0188 |
| | 0.0539 | 0.0931 | 0.1144 | 0.0502 | 0.0176 | 0.0171 |
| | 0.0192 | 0.1220 | 0.0911 | 0.0124 | 0.0191 | 0.0256 |
| 0.0267 | 0.0347 | 0.0186 | 0.0055 | 0.0008 | 0.0019 | |
| 0.0079 | 0.0200 | 0.0024 | 0.0017 | 0.0006 | 0.0047 | |

* same increments as on P. B-11

2.094

RAD VERIFICATION - PHASE ANGLES (deg)

| REF | SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|-------|--------|-------|--------|--------|--------|--------|
| 0.251 | -100.9 | 91.0 | -11.4 | 80.3 | 85.0 | 3.6 |
| | -107.2 | 91.4 | -16.8 | 75.6 | 66.6 | -6.3 |
| | -109.1 | 91.6 | -18.4 | 74.3 | 61.7 | -8.6 |
| | -111.5 | 91.7 | -20.3 | 72.7 | 56.3 | -11.4 |
| | -114.3 | 91.6 | -22.6 | 70.7 | 50.1 | -14.1 |
| | -117.7 | 91.7 | -25.4 | 68.5 | 43.1 | -17.2 |
| | -121.8 | 91.7 | -28.8 | 65.9 | 35.1 | -20.8 |
| | -124.2 | 91.5 | -30.9 | 64.2 | 30.5 | -22.9 |
| | -126.9 | 91.3 | -33.2 | 62.5 | 25.6 | -25.0 |
| | -129.9 | 91.3 | -35.8 | 60.7 | 20.2 | -27.1 |
| | -133.3 | 90.9 | -38.8 | 58.6 | 14.3 | -29.6 |
| | -137.2 | 90.3 | -42.3 | 56.1 | 7.8 | -32.5 |
| | -141.5 | 89.9 | -46.3 | 53.6 | 0.6 | -35.3 |
| | -146.6 | 89.1 | -51.1 | 50.6 | -7.5 | -38.6 |
| | -152.4 | 87.8 | -56.7 | 47.0 | -16.6 | -42.6 |
| | -159.1 | 86.5 | -63.2 | 43.2 | -26.8 | -46.7 |
| | -167.1 | 84.3 | -71.2 | 38.3 | -38.6 | -52.0 |
| | -176.6 | 81.7 | -80.7 | 32.6 | -52.2 | -57.8 |
| | 171.9 | 77.7 | -92.6 | 25.4 | -68.3 | -65.3 |
| | 157.4 | 72.6 | -107.2 | 16.7 | -87.4 | -74.2 |
| | 138.7 | 65.4 | -125.9 | 5.6 | -110.9 | -85.8 |
| | 112.1 | 55.7 | -150.5 | -8.4 | -140.9 | -100.6 |
| | 65.5 | 43.5 | 175.9 | -24.9 | 179.2 | -120.0 |
| | -45.4 | 30.7 | 129.0 | 13.3 | 124.0 | -145.8 |
| | -118.0 | -7.3 | 73.1 | -64.7 | 53.0 | -179.3 |
| | -140.2 | -30.6 | 44.2 | -109.2 | -26.1 | -226.5 |
| | -173.3 | 65.1 | 49.1 | -153.3 | 73.0 | -91.4 |
| | 128.7 | 4.3 | -14.4 | -115.6 | -25.4 | 176.1 |
| | -149.6 | -7.6 | -18.3 | 79.6 | 89.0 | -39.7 |
| 2.094 | -115.7 | 160.8 | 119.1 | -104.9 | 108.1 | -34.4 |



RAD VERIFICATION - COSINE COMPONENTS

| FRFR | SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|-------|----------|----------|----------|----------|----------|----------|
| 0.251 | -0.06594 | -0.01310 | 0.66316 | 0.00023 | 0.00005 | 0.00056 |
| | -0.10016 | -0.01828 | 0.65999 | 0.00052 | 0.00034 | 0.00079 |
| | -0.11052 | -0.02103 | 0.65901 | 0.00062 | 0.00045 | 0.00086 |
| | -0.12343 | -0.02252 | 0.65776 | 0.00076 | 0.00058 | 0.00094 |
| | -0.13811 | -0.02136 | 0.65578 | 0.00094 | 0.00074 | 0.00103 |
| | -0.15519 | -0.02295 | 0.65260 | 0.00117 | 0.00095 | 0.00113 |
| | -0.17457 | -0.02325 | 0.64745 | 0.00146 | 0.00120 | 0.00123 |
| | -0.18521 | -0.02063 | 0.64290 | 0.00166 | 0.00134 | 0.00128 |
| | -0.19653 | -0.01797 | 0.63699 | 0.00187 | 0.00150 | 0.00133 |
| | -0.20817 | -0.01811 | 0.62871 | 0.00211 | 0.00166 | 0.00139 |
| | -0.22018 | -0.01256 | 0.61675 | 0.00240 | 0.00184 | 0.00143 |
| | -0.23235 | -0.00406 | 0.59940 | 0.00273 | 0.00202 | 0.00147 |
| | -0.24354 | 0.00169 | 0.57504 | 0.00310 | 0.00219 | 0.00151 |
| | -0.25405 | 0.01330 | 0.53865 | 0.00352 | 0.00233 | 0.00153 |
| | -0.26189 | 0.03227 | 0.48712 | 0.00402 | 0.00243 | 0.00152 |
| | -0.26573 | 0.05117 | 0.41516 | 0.00455 | 0.00245 | 0.00148 |
| | -0.26335 | 0.08269 | 0.30917 | 0.00516 | 0.00232 | 0.00139 |
| | -0.25165 | 0.11855 | 0.16208 | 0.00578 | 0.00197 | 0.00125 |
| | -0.22650 | 0.17065 | -0.04722 | 0.00640 | 0.00129 | 0.00100 |
| | -0.18368 | 0.22981 | -0.32399 | 0.00686 | 0.00017 | 0.00066 |
| | -0.12090 | 0.29920 | -0.66990 | 0.00698 | -0.00144 | 0.00017 |
| | -0.04263 | 0.36408 | -1.01994 | 0.00641 | -0.00329 | -0.00041 |
| | 0.02469 | 0.39640 | -1.13903 | 0.00467 | -0.00426 | -0.00100 |
| | 0.02570 | 0.41886 | -0.59075 | 0.00464 | -0.00204 | -0.00131 |
| | -0.02322 | 0.27733 | 0.14416 | 0.00244 | 0.00121 | -0.00102 |
| | -0.03917 | 0.06447 | 0.09652 | -0.00098 | 0.00037 | -0.00020 |
| | -0.05353 | 0.03922 | 0.07492 | -0.00078 | 0.00009 | -0.00001 |
| | -0.01200 | 0.12166 | 0.08824 | -0.00009 | 0.00030 | -0.00045 |
| | -0.02302 | 0.03440 | 0.01766 | 0.00002 | 0.00000 | 0.00003 |
| 2.094 | -0.00342 | -0.01888 | -0.00117 | -0.00001 | 0.00000 | 0.00007 |

RAD VERIFICATION - SIN COMPONENTS

| FREQ | SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|-------|----------|----------|----------|----------|----------|----------|
| 0.251 | -0.34302 | 0.76359 | -0.13369 | 0.00137 | 0.00059 | 0.00004 |
| | -0.32397 | 0.75718 | -0.19922 | 0.00202 | 0.00079 | -0.00009 |
| | -0.31953 | 0.76111 | -0.21918 | 0.00232 | 0.00083 | -0.00013 |
| | -0.31369 | 0.76647 | -0.24326 | 0.00244 | 0.00087 | -0.00019 |
| | -0.30619 | 0.77300 | -0.27292 | 0.00269 | 0.00089 | -0.00026 |
| | -0.29587 | 0.78136 | -0.30981 | 0.00296 | 0.00089 | -0.00035 |
| | -0.28181 | 0.79156 | -0.35586 | 0.00327 | 0.00084 | -0.00047 |
| | -0.27276 | 0.79683 | -0.38468 | 0.00343 | 0.00079 | -0.00054 |
| | -0.26198 | 0.80270 | -0.41674 | 0.00360 | 0.00072 | -0.00062 |
| | -0.24919 | 0.80880 | -0.45333 | 0.00376 | 0.00061 | -0.00071 |
| | -0.23386 | 0.81500 | -0.49575 | 0.00392 | 0.00047 | -0.00081 |
| | -0.21535 | 0.82119 | -0.54526 | 0.00407 | 0.00028 | -0.00094 |
| | -0.19390 | 0.82670 | -0.60157 | 0.00420 | 0.00002 | -0.00107 |
| | -0.16769 | 0.83119 | -0.66733 | 0.00429 | -0.00031 | -0.00122 |
| | -0.13708 | 0.83378 | -0.74127 | 0.00431 | -0.00073 | -0.00139 |
| | -0.10163 | 0.83273 | -0.82145 | 0.00427 | -0.00124 | -0.00157 |
| | -0.06047 | 0.82617 | -0.90748 | 0.00407 | -0.00185 | -0.00178 |
| | -0.01510 | 0.81108 | -0.98810 | 0.00370 | -0.00254 | -0.00198 |
| | 0.03237 | 0.78169 | -1.04694 | 0.00304 | -0.00323 | -0.00218 |
| | 0.07657 | 0.73271 | -1.04796 | 0.00206 | -0.00375 | -0.00233 |
| | 0.10632 | 0.65313 | -0.92624 | 0.00068 | -0.00376 | -0.00237 |
| | 0.10508 | 0.53351 | -0.57772 | -0.00095 | -0.00268 | -0.00221 |
| | 0.05414 | 0.37606 | 0.08231 | -0.00217 | 0.00006 | -0.00173 |
| | -0.02606 | 0.24864 | 0.73015 | 0.00110 | 0.00302 | -0.00089 |
| | -0.04371 | -0.03552 | 0.47407 | -0.00516 | 0.00160 | 0.00001 |
| | -0.03266 | -0.03812 | 0.09578 | -0.00283 | -0.00018 | 0.00026 |
| | -0.00632 | 0.08444 | 0.08646 | -0.00039 | 0.00029 | -0.00030 |
| | 0.01499 | 0.00915 | -0.02265 | -0.00020 | -0.00014 | 0.00003 |
| | -0.01352 | -0.00459 | -0.00584 | 0.00009 | 0.00001 | -0.00002 |
| | -0.00712 | 0.00659 | 0.00210 | -0.00003 | 0.00001 | -0.00005 |

2.094

LOADS - COSINE COMPONENTS

| FREQ | SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|-------|-------------|-------------|-------------|-------------|-------------|-------------|
| 0.251 | 4.1354E+00 | -1.0191E+01 | 1.4160E+03 | 2.1152E+02 | -3.4844E+05 | -3.5907E+03 |
| | 9.8304E+00 | -2.2407E+01 | 1.1219E+03 | 4.5663E+02 | -2.5955E+05 | -7.9386E+03 |
| | 1.2053E+01 | -2.6823E+01 | 1.0240E+03 | 5.3694E+02 | -2.2980E+05 | -9.5571E+03 |
| | 1.4965E+01 | -3.2765E+01 | 9.1220E+02 | 6.4760E+02 | -1.9584E+05 | -1.1643E+04 |
| | 1.8821E+01 | -4.0749E+01 | 7.7847E+02 | 7.8457E+02 | -1.5555E+05 | -1.4505E+04 |
| | 2.3860E+01 | -5.0291E+01 | 6.1431E+02 | 9.5391E+02 | -1.1797E+05 | -1.7972E+04 |
| | 3.0308E+01 | -6.2342E+01 | 4.2619E+02 | 1.1566E+03 | -5.0441E+04 | -2.2351E+04 |
| | 3.8567E+01 | -7.0136E+01 | 3.2153E+02 | 1.2921E+03 | -1.9951E+04 | -2.5092E+04 |
| | 3.9440E+01 | -7.9012E+01 | 2.0475E+02 | 1.4269E+03 | 1.3649E+04 | -2.8263E+04 |
| | 4.4806E+01 | -8.8312E+01 | 8.9330E+01 | 1.5779E+03 | 4.6040E+04 | -3.1723E+04 |
| | 5.1131E+01 | -9.9517E+01 | -4.0382E+01 | 1.7499E+03 | 8.1721E+04 | -3.5699E+04 |
| | 5.9519E+01 | -1.1389E+02 | -1.7445E+02 | 1.9297E+03 | 1.1703E+05 | -4.0672E+04 |
| | 6.5565E+01 | -1.2814E+02 | -3.0371E+02 | 2.1226E+03 | 1.4891E+05 | -4.5856E+04 |
| | 7.5391E+01 | -1.4479E+02 | -4.2881E+02 | 2.3226E+03 | 1.7684E+05 | -5.1691E+04 |
| | 8.4798E+01 | -1.6504E+02 | -5.4532E+02 | 2.5268E+03 | 1.9860E+05 | -5.8452E+04 |
| | 9.4593E+01 | -1.8364E+02 | -6.3733E+02 | 2.7126E+03 | 2.0907E+05 | -6.4851E+04 |
| | 1.0339E+02 | -2.0745E+02 | -6.9642E+02 | 2.8630E+03 | 2.0417E+05 | -7.2287E+04 |
| | 1.0945E+02 | -2.2978E+02 | -6.9653E+02 | 2.9402E+03 | 1.7677E+05 | -7.9002E+04 |
| | 1.0785E+02 | -2.5183E+02 | -6.3387E+02 | 2.8759E+03 | 1.2654E+05 | -8.4229E+04 |
| | 9.5854E+01 | -2.6697E+02 | -4.8760E+02 | 2.6095E+03 | 5.3513E+04 | -8.6034E+04 |
| | 7.4162E+01 | -2.6487E+02 | -2.8100E+02 | 2.0355E+03 | -2.4061E+04 | -7.9867E+04 |
| | 2.9800E+01 | -2.3788E+02 | -7.3911E+01 | 1.1190E+03 | -6.6546E+04 | -6.3251E+04 |
| | -1.9819E+01 | -1.5971E+02 | 1.6321E+01 | 9.3017E+01 | -1.8698E+04 | -2.9032E+04 |
| | -2.3722E+01 | -9.3397E+01 | -3.0274E+01 | 3.4291E+02 | 7.3226E+04 | 2.0399E+03 |
| | 2.5338E+01 | -3.9171E+01 | 9.8271E+01 | -1.5131E+03 | -1.3380E+04 | 1.8307E+04 |
| | 5.0851E+01 | -1.0176E+01 | 8.4941E+01 | -3.9703E+02 | -3.4781E+04 | 6.2529E+03 |
| | 8.4195E+01 | -5.6835E+01 | -8.9147E+01 | 3.2837E+02 | 2.1733E+04 | -1.7114E+04 |
| | 2.3279E+01 | -1.0461E+01 | -3.7919E+01 | 3.9756E+01 | -1.8639E+04 | 1.6957E+04 |
| | 5.6555E+01 | -1.0675E+02 | -9.5093E+01 | -1.3467E+01 | 2.3871E+04 | -2.8506E+04 |
| 2.094 | 1.4928E+01 | 3.1344E+00 | 1.3078E+01 | 3.1572E+01 | -3.2478E+03 | -6.1480E+03 |

LOADS - SINE COMPONENTS

| FREQ | SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|-------|-------------|-------------|-------------|-------------|-------------|-------------|
| 0.251 | 2.1512E+01 | -6.3982E+01 | -7.7847E+02 | 1.2552E+03 | 2.2160E+05 | -1.6075E+04 |
| | 3.1797E+01 | -9.6536E+01 | -1.0317E+03 | 1.7561E+03 | 2.8972E+05 | -2.3897E+04 |
| | 3.4848E+01 | -1.0723E+02 | -1.0874E+03 | 1.8958E+03 | 3.0363E+05 | -2.6426E+04 |
| | 3.8034E+01 | -1.1838E+02 | -1.1466E+03 | 2.0424E+03 | 3.1800E+05 | -2.8966E+04 |
| | 4.1266E+01 | -1.3158E+02 | -1.1984E+03 | 2.1971E+03 | 3.2892E+05 | -3.1917E+04 |
| | 4.5189E+01 | -1.4681E+02 | -1.2420E+03 | 2.3439E+03 | 3.3605E+05 | -3.5215E+04 |
| | 4.9249E+01 | -1.6387E+02 | -1.2638E+03 | 2.4897E+03 | 3.3474E+05 | -3.8687E+04 |
| | 5.3706E+01 | -1.7260E+02 | -1.2672E+03 | 2.5530E+03 | 3.3086E+05 | -4.0347E+04 |
| | 5.8775E+01 | -1.8283E+02 | -1.2587E+03 | 2.6051E+03 | 3.2277E+05 | -4.2243E+04 |
| | 5.3636E+01 | -1.9295E+02 | -1.2335E+03 | 2.6354E+03 | 3.0954E+05 | -4.4001E+04 |
| | 5.4308E+01 | -2.0377E+02 | -1.1992E+03 | 2.6446E+03 | 2.9152E+05 | -4.5723E+04 |
| | 5.8237E+01 | -2.1334E+02 | -1.1438E+03 | 2.6231E+03 | 2.6693E+05 | -4.6733E+04 |
| | 5.2998E+01 | -2.2393E+02 | -1.0613E+03 | 2.5583E+03 | 2.3364E+05 | -4.7869E+04 |
| | 4.6763E+01 | -2.3225E+02 | -9.5869E+02 | 2.4427E+03 | 1.9392E+05 | -4.8033E+04 |
| | 4.4490E+01 | -2.3871E+02 | -8.2239E+02 | 2.2455E+03 | 1.4432E+05 | -4.7135E+04 |
| | 3.6178E+01 | -2.4254E+02 | -6.5612E+02 | 1.9737E+03 | 8.7499E+04 | -4.5150E+04 |
| | 2.3740E+01 | -2.3865E+02 | -4.6218E+02 | 1.5772E+03 | 2.5632E+04 | -4.0200E+04 |
| | 6.5674E+00 | -2.2869E+02 | -2.4598E+02 | 1.0703E+03 | -3.6175E+04 | -3.3191E+04 |
| | -1.5699E+01 | -2.0439E+02 | -2.7915E+01 | 4.2204E+02 | -8.7576E+04 | -2.1344E+03 |
| | -4.1626E+01 | -1.6560E+02 | 1.5187E+02 | -2.9112E+02 | -1.1097E+05 | -5.4177E+03 |
| | -6.5218E+01 | -1.0855E+02 | 2.4909E+02 | -9.8784E+02 | -8.9573E+04 | 1.5072E+04 |
| | -7.3455E+01 | -3.8673E+01 | 2.1988E+02 | -1.4327E+03 | -1.6604E+04 | 3.6824E+04 |
| | -4.3460E+01 | 1.8742E+01 | 8.8874E+01 | -1.2687E+03 | 6.1393E+04 | 4.9494E+04 |
| | 2.4257E+01 | -5.6267E+01 | 5.6732E+01 | -1.0580E+03 | 1.2053E+04 | 1.7792E+04 |
| | 4.7697E+01 | 3.3479E+01 | 9.0358E+01 | -1.4954E+01 | -6.7750E+04 | 1.7035E+04 |
| | 4.2400E+01 | -4.3840E+01 | -1.2727E+02 | 1.0432E+03 | 3.0923E+04 | -1.7079E+04 |
| | 9.9404E+00 | -3.1305E+01 | -5.5221E+01 | 3.8357E+02 | -2.6451E+03 | 3.0934E+03 |
| | -2.9080E+01 | -3.7103E+01 | -4.7388E+01 | 1.9452E+02 | 2.0458E+04 | -5.2885E+03 |
| | 3.3216E+01 | 3.2716E+00 | 3.6650E+01 | -1.2941E+02 | -1.0502E+04 | 1.4990E+03 |
| | 3.1078E+01 | 2.5650E+01 | 4.5825E+00 | 1.0271E+02 | -3.9332E+03 | 1.0128E+04 |

2.094

RAD RE-VERIFICATION - COSINE COMPONENTS

| FRFQ | SURGE | SMAY | HEAVE | ROLL | PITCH | YAW |
|-------|-------------|-------------|-------------|-------------|-------------|-------------|
| 0.251 | -6.5940E-02 | -1.3100E-02 | 6.6316E-01 | 2.3000E-04 | 5.0000E-05 | 5.6000E-04 |
| | -1.0016E-01 | -1.8280E-02 | 6.5999E-01 | 5.2000E-04 | 3.4000E-04 | 7.9000E-04 |
| | -1.1052E-01 | -2.1030E-02 | 6.5901E-01 | 7.2000E-04 | 4.5000E-04 | 8.6000E-04 |
| | -1.2343E-01 | -2.2520E-02 | 6.5776E-01 | 7.6000E-04 | 5.8000E-04 | 9.4000E-04 |
| | -1.3811E-01 | -2.1360E-02 | 6.5578E-01 | 9.4000E-04 | 7.4000E-04 | 1.0300E-03 |
| | -1.5519E-01 | -2.2950E-02 | 6.5260E-01 | 1.1700E-03 | 9.5000E-04 | 1.1300E-03 |
| | -1.7457E-01 | -2.3250E-02 | 6.4745E-01 | 1.4600E-03 | 1.2000E-03 | 1.2300E-03 |
| | -1.8521E-01 | -2.0630E-02 | 6.4290E-01 | 1.6600E-03 | 1.3400E-03 | 1.2800E-03 |
| | -1.9653E-01 | -1.7970E-02 | 6.3699E-01 | 1.8700E-03 | 1.5000E-03 | 1.3300E-03 |
| | -2.0817E-01 | -1.8110E-02 | 6.2871E-01 | 2.1100E-03 | 1.6600E-03 | 1.3900E-03 |
| | -2.2018E-01 | -1.2560E-02 | 6.1675E-01 | 2.4000E-03 | 1.8400E-03 | 1.4300E-03 |
| | -2.3235E-01 | -4.0599E-03 | 5.9940E-01 | 2.7300E-03 | 2.0200E-03 | 1.4700E-03 |
| | -2.4354E-01 | 1.6901E-03 | 5.7504E-01 | 3.1000E-03 | 2.1900E-03 | 1.5100E-03 |
| | -2.5405E-01 | 1.3300E-02 | 5.3865E-01 | 3.5200E-03 | 2.3300E-03 | 1.5300E-03 |
| | -2.6189E-01 | 3.2270E-02 | 4.8712E-01 | 4.0200E-03 | 2.4300E-03 | 1.5200E-03 |
| | -2.6573E-01 | 5.1170E-02 | 4.1516E-01 | 4.5500E-03 | 2.4500E-03 | 1.4800E-03 |
| | -2.6335E-01 | 8.2690E-02 | 3.0917E-01 | 5.1600E-03 | 2.3200E-03 | 1.3900E-03 |
| | -2.5165E-01 | 1.1855E-01 | 1.6208E-01 | 5.7800E-03 | 1.9700E-03 | 1.2500E-03 |
| | -2.2650E-01 | 1.7065E-01 | -4.7220E-02 | 6.4000E-03 | 1.2900E-03 | 1.0000E-03 |
| | -1.8348E-01 | 2.2981E-01 | -3.2399E-01 | 6.8600E-03 | 1.7000E-04 | 6.6000E-04 |
| | -1.2090E-01 | 2.9920E-01 | -6.6990E-01 | 6.9800E-03 | -1.4400E-03 | 1.7000E-04 |
| | -4.2630E-02 | 3.6408E-01 | -1.0199E+00 | 6.4100E-03 | -3.2900E-03 | -4.1000E-04 |
| | 2.4690E-02 | 3.9640E-01 | -1.1390E+00 | 4.6700E-03 | -4.2600E-03 | -1.0000E-03 |
| | 2.5700E-02 | 4.1886E-01 | -5.9075E-01 | 4.6400E-03 | -2.0400E-03 | -1.3100E-03 |
| | -2.3220E-02 | 2.7733E-01 | 1.4416E-01 | 2.4400E-03 | 1.2100E-03 | -1.0200E-03 |
| | -3.9170E-02 | 6.4470E-02 | 9.8520E-02 | -9.8000E-04 | 3.7000E-04 | -2.0000E-04 |
| | -5.3530E-02 | 3.9220E-02 | 7.4920E-02 | -7.8000E-04 | 9.0000E-05 | -1.0000E-05 |
| | -1.2000E-02 | 1.2166E-01 | 8.8240E-02 | -9.0000E-05 | 3.0000E-04 | -4.5000E-04 |
| | -2.3020E-02 | 3.4400E-02 | 1.7660E-02 | 2.0000E-05 | 2.9537E-11 | 3.0000E-05 |
| | -3.4200E-03 | -1.8880E-02 | -1.1700E-03 | -1.0000E-05 | 1.5418E-12 | 7.0000E-05 |

V

2.094

Ac.

RAD RE-VERIFICATION - SINE COMPONENTS

| FREQ | SURGE | SWAY | HEAVE | ROLL(εmms) | PITCH (εmms) | YAW (CRADS) |
|-------|-------------|-------------|-------------|-------------|--------------|-------------|
| 0.251 | -3.4302E-01 | 7.6359E-01 | -1.3369E-01 | 1.3700E-03 | 5.9000E-04 | 4.0000E-05 |
| | -3.2397E-01 | 7.5718E-01 | -1.9922E-01 | 2.0200E-03 | 7.9000E-04 | -9.0000E-05 |
| | -3.1953E-01 | 7.6111E-01 | -2.1918E-01 | 2.2200E-03 | 8.3000E-04 | -1.3000E-04 |
| | -3.1369E-01 | 7.6647E-01 | -2.4326E-01 | 2.4400E-03 | 8.7000E-04 | -1.9000E-04 |
| | -3.0619E-01 | 7.7300E-01 | -2.7292E-01 | 2.6900E-03 | 8.9000E-04 | -2.6000E-04 |
| | -2.9587E-01 | 7.8136E-01 | -3.0981E-01 | 2.9600E-03 | 8.9000E-04 | -3.5000E-04 |
| | -2.8181E-01 | 7.9156E-01 | -3.5586E-01 | 3.2700E-03 | 8.4000E-04 | -4.7000E-04 |
| | -2.7275E-01 | 7.9833E-01 | -3.8468E-01 | 3.4300E-03 | 7.9000E-04 | -5.4000E-04 |
| | -2.6198E-01 | 8.0270E-01 | -4.1674E-01 | 3.6000E-03 | 7.2000E-04 | -6.2000E-04 |
| | -2.4919E-01 | 8.0880E-01 | -4.5333E-01 | 3.7600E-03 | 6.1000E-04 | -7.1000E-04 |
| | -2.3386E-01 | 8.1500E-01 | -4.9575E-01 | 3.9200E-03 | 4.7000E-04 | -8.1000E-04 |
| | -2.1535E-01 | 8.2119E-01 | -5.4526E-01 | 4.0700E-03 | 2.8000E-04 | -9.4000E-04 |
| | -1.9390E-01 | 8.2670E-01 | -6.0157E-01 | 4.2000E-03 | 2.001E-05 | -1.0700E-03 |
| | -1.6769E-01 | 8.3119E-01 | -6.6733E-01 | 4.2900E-03 | -3.1000E-04 | -1.2200E-03 |
| | -1.3708E-01 | 8.3378E-01 | -7.4127E-01 | 4.3100E-03 | -7.3000E-04 | -1.3900E-03 |
| | -1.0163E-01 | 8.3273E-01 | -8.2145E-01 | 4.2700E-03 | -1.2400E-03 | -1.5700E-03 |
| | -6.0470E-02 | 8.2617E-01 | -9.0748E-01 | 4.0700E-03 | -1.8500E-03 | -1.7800E-03 |
| | -1.5100E-02 | 8.1108E-01 | -9.8810E-01 | 3.7000E-03 | -2.5400E-03 | -1.9800E-03 |
| | -3.2370E-02 | 7.8169E-01 | -1.0469E+00 | 3.0400E-03 | -3.2300E-03 | -2.1800E-03 |
| | -7.6570E-02 | 7.3271E-01 | -1.0480E+00 | 2.0600E-03 | -3.7500E-03 | -2.3300E-03 |
| | 1.0632E-01 | 6.5313E-01 | -9.2624E-01 | 6.8000E-04 | -3.7600E-03 | -2.3700E-03 |
| | 1.0508E-01 | 5.3351E-01 | -5.7772E-01 | -9.5000E-04 | -2.6800E-03 | -2.2100E-03 |
| | 3.4140E-02 | 3.7606E-01 | 8.2310E-02 | -2.1700E-03 | 6.0001E-05 | -1.7300E-03 |
| | -2.6060E-02 | 2.4844E-01 | 7.3015E-01 | 1.1000E-03 | 3.0200E-03 | -8.9000E-04 |
| | -4.3710E-02 | -3.5520E-02 | 4.7407E-01 | -5.1600E-03 | 1.6000E-03 | 1.0000E-05 |
| | -3.2660E-02 | -3.8120E-02 | 9.5780E-02 | -2.8300E-03 | -1.8000E-04 | 2.6000E-04 |
| | -6.3200E-03 | 8.4400E-02 | 8.6460E-02 | -3.9000E-04 | 2.9000E-04 | -3.0000E-04 |
| | 1.4990E-02 | 9.1500E-03 | -2.2650E-02 | -2.0000E-04 | -1.4000E-04 | 3.0000E-05 |
| | -1.3520E-02 | -4.5900E-03 | -5.8400E-03 | 9.0000E-05 | 1.0000E-05 | -2.0000E-05 |
| | -7.1200E-03 | 6.5900E-03 | 2.1000E-03 | -3.0000E-05 | 1.0000E-05 | -5.0000E-05 |

2.094

CASE 1

CONSTRAINED RAD - COSINE COMPONENTS

FRFR
0.251

| SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|-------------|-------------|-------------|-------------|-------------|-------------|
| 8.9136E-06 | -1.0299E-04 | 6.6316E-01 | 2.3000E-04 | 5.0000E-05 | -4.9007E-06 |
| 2.1191E-05 | -2.2780E-04 | 6.5999E-01 | 5.2000E-04 | 3.4000E-04 | -1.0896E-05 |
| 2.5983E-05 | -2.7322E-04 | 6.5901E-01 | 6.2000E-04 | 4.5000E-04 | -1.3140E-05 |
| 3.2261E-05 | -3.3293E-04 | 6.5776E-01 | 7.6000E-04 | 5.8000E-04 | -1.6039E-05 |
| 4.0575E-05 | -4.1701E-04 | 6.5578E-01 | 9.4000E-04 | 7.4000E-04 | -2.0030E-05 |
| 5.1439E-05 | -5.1622E-04 | 6.5260E-01 | 1.1700E-03 | 9.5000E-04 | -2.4885E-05 |
| 6.5775E-05 | -6.4726E-04 | 6.4745E-01 | 1.4600E-03 | 1.2000E-03 | -3.1052E-05 |
| 7.4527E-05 | -7.2401E-04 | 6.4290E-01 | 1.6600E-03 | 1.3400E-03 | -3.4928E-05 |
| 8.5037E-05 | -8.1758E-04 | 6.3699E-01 | 1.8700E-03 | 1.5000E-03 | -3.9430E-05 |
| 9.6610E-05 | -9.1616E-04 | 6.2871E-01 | 2.1100E-03 | 1.6600E-03 | -4.4357E-05 |
| 1.1025E-04 | -1.0354E-03 | 6.1675E-01 | 2.4000E-03 | 1.8400E-03 | -5.0051E-05 |
| 1.2617E-04 | -1.1889E-03 | 5.9940E-01 | 2.7300E-03 | 2.0200E-03 | -5.7210E-05 |
| 1.4354E-04 | -1.3424E-03 | 5.7504E-01 | 3.1000E-03 | 2.1900E-03 | -6.4717E-05 |
| 1.6259E-04 | -1.5229E-03 | 5.3865E-01 | 3.5200E-03 | 2.3300E-03 | -7.3228E-05 |
| 1.8331E-04 | -1.7439E-03 | 4.8712E-01 | 4.0200E-03 | 2.4300E-03 | -8.3194E-05 |
| 2.0402E-04 | -1.9502E-03 | 4.1516E-01 | 4.5500E-03 | 2.4500E-03 | -9.2760E-05 |
| 2.2301E-04 | -2.2161E-03 | 3.0917E-01 | 5.1600E-03 | 2.5200E-03 | -1.0406E-04 |
| 2.3611E-04 | -2.4708E-03 | 1.6208E-01 | 5.7800E-03 | 1.9700E-03 | -1.1455E-04 |
| 2.3699E-04 | -2.7285E-03 | -4.7220E-02 | 6.4000E-03 | 1.2900E-03 | -1.2329E-04 |
| 2.1546E-04 | -2.9167E-03 | -3.2399E-01 | 6.8600E-03 | 1.7000E-04 | -1.2740E-04 |
| 1.6004E-04 | -2.9208E-03 | -6.6990E-01 | 6.9800E-03 | -1.4400E-03 | -1.2018E-04 |
| 6.4323E-05 | -2.6477E-03 | -1.0199E+00 | 6.4100E-03 | -3.2900E-03 | -9.7584E-05 |
| -4.2788E-05 | -1.7806E-03 | -1.1390E+00 | 4.6700E-03 | -4.2400E-03 | -4.7498E-05 |
| -5.1660E-05 | -9.5882E-04 | -5.9075E-01 | 4.6400E-03 | -2.0400E-03 | 1.6922E-06 |
| 3.4738E-05 | -3.3681E-04 | 1.4416E-01 | 2.4400E-03 | 1.2100E-03 | 2.7271E-05 |
| 1.0590E-04 | -3.2389E-05 | 9.8520E-02 | -9.8000E-04 | 3.7000E-04 | 1.1647E-05 |
| 1.8207E-04 | -7.0234E-04 | 7.4920E-02 | -7.8000E-04 | 9.0000E-05 | -2.9115E-05 |
| 5.0381E-05 | 5.5915E-05 | 8.8240E-02 | -9.0000E-05 | 3.0000E-04 | 3.0198E-05 |
| 1.2254E-04 | -1.4335E-03 | 1.7660E-02 | 2.0000E-05 | 2.9557E-11 | -5.4734E-05 |
| 3.2477E-05 | -2.1507E-04 | -1.1700E-03 | -1.0000E-05 | 1.5418E-12 | -1.9418E-05 |

2.094

CASE 1

CONSTRAINED RAD - SINE COMPONENTS

FREQ
0.251

| SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|-------------|-------------|-------------|-------------|-------------|-------------|
| 4.6369E-05 | -6.4489E-04 | -1.3369E-01 | 1.3700E-03 | 5.9000E-04 | -2.1950E-05 |
| 6.8542E-05 | -9.7744E-04 | -1.9922E-01 | 2.0200E-03 | 7.9000E-04 | -3.2833E-05 |
| 7.5122E-05 | -1.0873E-03 | -2.1918E-01 | 2.2200E-03 | 8.3000E-04 | -3.6382E-05 |
| 8.1990E-05 | -1.2022E-03 | -2.4326E-01 | 2.4400E-03 | 8.7000E-04 | -3.9968E-05 |
| 8.9754E-05 | -1.3389E-03 | -2.7292E-01 | 2.6900E-03 | 8.9000E-04 | -4.4162E-05 |
| 9.8068E-05 | -1.4972E-03 | -3.0981E-01 | 2.9600E-03 | 8.9000E-04 | -4.8890E-05 |
| 1.0518E-04 | -1.6757E-03 | -3.5586E-01 | 3.2700E-03 | 8.4000E-04 | -5.3935E-05 |
| 1.0976E-04 | -1.7676E-03 | -3.8468E-01 | 3.4300E-03 | 7.9000E-04 | -5.6381E-05 |
| 1.1336E-04 | -1.8575E-03 | -4.1674E-01 | 3.6000E-03 | 7.2000E-04 | -5.9202E-05 |
| 1.1565E-04 | -1.9833E-03 | -4.5333E-01 | 3.7600E-03 | 6.1000E-04 | -6.1864E-05 |
| 1.1710E-04 | -2.0990E-03 | -4.9575E-01 | 3.9200E-03 | 4.7000E-04 | -6.4526E-05 |
| 1.1695E-04 | -2.2056E-03 | -5.4526E-01 | 4.0700E-03 | 2.8000E-04 | -6.6244E-05 |
| 1.1429E-04 | -2.3182E-03 | -6.0157E-01 | 4.2000E-03 | 2.0001E-05 | -6.8212E-05 |
| 1.0732E-04 | -2.4110E-03 | -6.6733E-01 | 4.2900E-03 | -3.1000E-04 | -6.8864E-05 |
| 9.5951E-05 | -2.4856E-03 | -7.4127E-01 | 4.3100E-03 | -7.3000E-04 | -6.8095E-05 |
| 7.8029E-05 | -2.5340E-03 | -8.2145E-01 | 4.2700E-03 | -1.2400E-03 | -6.5869E-05 |
| 5.1706E-05 | -2.5014E-03 | -9.0748E-01 | 4.0700E-03 | -1.8500E-03 | -5.9455E-05 |
| 1.4167E-05 | -2.4046E-03 | -9.8810E-01 | 3.7000E-03 | -2.5400E-03 | -5.0109E-05 |
| -3.3869E-05 | -2.1519E-03 | -1.0469E+00 | 3.0400E-03 | -3.2300E-03 | -3.3653E-05 |
| -8.9816E-05 | -1.7380E-03 | -1.0480E+00 | 2.0600E-03 | -3.7500E-03 | -1.0957E-05 |
| -1.4074E-04 | -1.1134E-03 | -9.2624E-01 | 6.8000E-04 | -3.7600E-03 | 1.9169E-05 |
| -1.5855E-04 | 3.3017E-04 | -5.7772E-01 | -9.5000E-04 | -2.6800E-03 | 5.2375E-05 |
| -9.3826E-05 | 3.3918E-04 | 8.2310E-02 | -2.1700E-03 | 6.0001E-05 | 7.3802E-05 |
| 5.2384E-05 | -4.9419E-04 | 7.3015E-01 | 1.1000E-03 | 3.0200E-03 | 2.7280E-05 |
| 1.0304E-04 | 4.5089E-04 | 4.7407E-01 | -5.1600E-03 | 1.6000E-03 | 2.8317E-05 |
| 9.1635E-05 | -5.3162E-04 | 9.5780E-02 | -2.8300E-03 | -1.8000E-04 | -2.7219E-05 |
| 2.1496E-05 | -3.4041E-04 | 8.6460E-02 | -3.9000E-04 | 2.9000E-04 | 2.9724E-06 |
| -6.2935E-05 | -3.8025E-04 | -2.2650E-02 | -2.0000E-04 | -1.4000E-04 | -7.4077E-06 |
| 7.1967E-05 | -5.2702E-05 | -5.8400E-03 | 9.0000E-05 | 1.0000E-05 | -1.9008E-06 |
| 6.7614E-05 | 5.2729E-04 | 2.1000E-03 | -3.0000E-05 | 1.0000E-05 | -2.5673E-05 |

2.094

CASE 1

CONSTRAINT FORCES Kips & Kip-FT.

| REQ | SURGE-C | SURGE-S | SWAY-C | SWAY-S | YAW-C | YAW-S |
|-------|-------------|-------------|-------------|-------------|-------------|-------------|
| 0.251 | 4.1359E+00 | 2.1515E+01 | -1.0299E+01 | -6.4489E+01 | -3.6265E+03 | -1.6243E+04 |
| | 9.8324E+00 | 3.1803E+01 | -2.2780E+01 | -9.7744E+01 | -8.0639E+03 | -2.4297E+04 |
| | 1.2056E+01 | 3.4857E+01 | -2.7322E+01 | -1.0873E+02 | -9.7233E+03 | -2.6922E+04 |
| | 1.4969E+01 | 3.8044E+01 | -3.3293E+01 | -1.2022E+02 | -1.1869E+04 | -2.9576E+04 |
| | 1.8827E+01 | 4.1739E+01 | -4.1701E+01 | -1.3389E+02 | -1.4822E+04 | -3.2680E+04 |
| | 2.3848E+01 | 4.5504E+01 | -5.1622E+01 | -1.4972E+02 | -1.8415E+04 | -3.6179E+04 |
| | 3.0519E+01 | 4.9268E+01 | -6.4226E+01 | -1.6757E+02 | -2.2979E+04 | -3.9912E+04 |
| | 3.4580E+01 | 5.0927E+01 | -7.2401E+01 | -1.7676E+02 | -2.5847E+04 | -4.1722E+04 |
| | 3.9457E+01 | 5.2597E+01 | -8.1758E+01 | -1.8757E+02 | -2.9178E+04 | -4.3810E+04 |
| | 4.4327E+01 | 5.3660E+01 | -9.1616E+01 | -1.9833E+02 | -3.2824E+04 | -4.5779E+04 |
| | 5.1157E+01 | 5.4336E+01 | -1.0354E+02 | -2.0990E+02 | -3.7038E+04 | -4.7749E+04 |
| | 5.6551E+01 | 5.4267E+01 | -1.1889E+02 | -2.2026E+02 | -4.2336E+04 | -4.9021E+04 |
| | 6.6605E+01 | 5.3029E+01 | -1.3424E+02 | -2.3182E+02 | -4.7891E+04 | -5.0477E+04 |
| | 7.5439E+01 | 4.9795E+01 | -1.5229E+02 | -2.4110E+02 | -5.4189E+04 | -5.0959E+04 |
| | 8.5057E+01 | 4.4521E+01 | -1.7439E+02 | -2.4856E+02 | -6.1564E+04 | -5.0390E+04 |
| | 9.4666E+01 | 3.6205E+01 | -1.9502E+02 | -2.5340E+02 | -6.8642E+04 | -4.8743E+04 |
| | 1.0348E+02 | 2.3760E+01 | -2.2161E+02 | -2.5014E+02 | -7.7007E+04 | -4.3997E+04 |
| | 1.0935E+02 | 6.5736E+00 | -2.4708E+02 | -2.4046E+02 | -8.4766E+04 | -3.7081E+04 |
| | 1.0996E+02 | -1.5715E+01 | -2.7285E+02 | -2.1519E+02 | -9.1235E+04 | -2.4903E+04 |
| | 9.9271E+01 | -4.1675E+01 | -2.9167E+02 | -1.7380E+02 | -9.4279E+04 | -8.1081E+03 |
| | 7.4260E+01 | -6.5305E+01 | -2.9208E+02 | -1.1134E+02 | -8.8936E+04 | 1.4185E+04 |
| | 2.9845E+01 | -7.3566E+01 | -2.6477E+02 | -3.3017E+01 | -7.2212E+04 | 3.8758E+04 |
| | -1.9854E+01 | -4.3535E+01 | -1.7806E+02 | 3.3918E+01 | -3.5149E+04 | 5.4614E+04 |
| | -2.3779E+01 | 2.4306E+01 | -9.5882E+01 | -4.9419E+01 | 1.2522E+03 | 2.0187E+04 |
| | 2.5398E+01 | 4.7809E+01 | -3.3681E+01 | 4.5089E+01 | 2.0180E+04 | 2.0954E+04 |
| | 5.0994E+01 | 4.2519E+01 | -3.2389E+00 | -5.3162E+01 | 8.6187E+03 | -2.0142E+04 |
| | 8.4481E+01 | 9.9747E+00 | -7.0234E+01 | -3.4041E+01 | -2.1545E+04 | 2.1996E+03 |
| | 2.3377E+01 | -2.9202E+01 | 5.5915E+00 | -3.8025E+01 | 2.2346E+04 | -5.4817E+03 |
| | 5.6856E+01 | 3.3393E+01 | -1.4335E+02 | -5.2702E+00 | -4.0503E+04 | -1.4066E+03 |
| | 1.5070E+01 | 3.1373E+01 | -2.1507E+01 | 5.2729E+01 | -1.4369E+04 | 1.8998E+04 |

2.094

CONSTRAINT STIFFNESSES

| | K/F | K/F | K/F |
|-------|------------|-----|-----|
| SURGE | 4.6400E+05 | | |
| SWAY | 1.0000E+05 | | |
| YAW | 7.4000E+08 | | |

CASE 2

CONSTRAINED RAD - COSINE COMPONENTS

FKER

0.251

| SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|-------------|-------------|-------------|-------------|-------------|-------------|
| 1.7830E-05 | -1.0400E-04 | 6.6316E-01 | 2.3000E-04 | 5.0000E-05 | -9.8942E-06 |
| 4.2390E-05 | -2.3136E-04 | 6.5999E-01 | 5.2000E-04 | 3.4000E-04 | -2.2118E-05 |
| 5.1979E-05 | -2.7799E-04 | 6.5901E-01 | 6.2000E-04 | 4.5000E-04 | -2.6717E-05 |
| 6.4540E-05 | -3.3944E-04 | 6.5776E-01 | 7.6000E-04 | 5.8000E-04 | -3.2675E-05 |
| 8.1173E-05 | -4.2619E-04 | 6.5578E-01 | 9.4000E-04 | 7.4000E-04 | -4.0903E-05 |
| 1.0191E-04 | -5.2914E-04 | 6.5260E-01 | 1.1700E-03 | 9.5000E-04 | -5.0956E-05 |
| 1.3160E-04 | -6.6070E-04 | 6.4745E-01 | 1.4600E-03 | 1.2000E-03 | -6.3796E-05 |
| 1.4911E-04 | -7.4626E-04 | 6.4290E-01 | 1.6600E-03 | 1.3400E-03 | -7.1897E-05 |
| 1.7615E-04 | -8.4468E-04 | 6.3699E-01 | 1.8700E-03 | 1.5000E-03 | -8.1346E-05 |
| 1.9331E-04 | -9.4892E-04 | 6.2871E-01 | 2.1100E-03 | 1.6600E-03 | -9.1719E-05 |
| 2.2662E-04 | -1.0754E-03 | 6.1675E-01 | 2.4000E-03 | 1.8400E-03 | -1.0378E-04 |
| 2.5211E-04 | -1.2390E-03 | 5.9940E-01 | 2.7300E-03 | 2.0200E-03 | -1.1902E-04 |
| 2.8224E-04 | -1.4042E-03 | 5.7504E-01 | 3.1000E-03 | 2.1900E-03 | -1.3510E-04 |
| 3.2038E-04 | -1.5922E-03 | 5.3865E-01 | 3.5200E-03 | 2.3300E-03 | -1.5346E-04 |
| 3.6888E-04 | -1.8398E-03 | 4.8712E-01 | 4.0200E-03 | 2.4300E-03 | -1.7519E-04 |
| 4.0834E-04 | -2.0683E-03 | 4.1516E-01 | 4.5500E-03 | 2.4500E-03 | -1.9634E-04 |
| 4.4637E-04 | -2.3647E-03 | 3.0917E-01 | 5.1600E-03 | 2.3200E-03 | -2.2175E-04 |
| 4.7651E-04 | -2.6549E-03 | 1.6208E-01 | 5.7800E-03 | 1.9700E-03 | -2.4597E-04 |
| 4.7448E-04 | -2.9560E-03 | -4.7220E-02 | 6.4000E-03 | 1.2900E-03 | -2.6744E-04 |
| 4.3112E-04 | -3.1899E-03 | -3.2399E-01 | 6.8600E-03 | 1.7000E-04 | -2.7986E-04 |
| 3.2051E-04 | -3.2295E-03 | -6.6990E-01 | 6.9800E-03 | -1.4400E-03 | -2.6869E-04 |
| 1.2894E-04 | -2.9645E-03 | -1.0199E+00 | 6.4100E-03 | -3.2900E-03 | -2.2429E-04 |
| -8.5725E-05 | -2.0116E-03 | -1.1390E+00 | 4.6700E-03 | -4.2600E-03 | -1.1631E-04 |
| -1.6553E-04 | -9.9027E-04 | -5.9073E-01 | 4.6400E-03 | -2.0400E-03 | 4.2134E-07 |
| 1.0973E-04 | -2.7065E-04 | 1.4416E-01 | 2.4400E-03 | 1.2100E-03 | 6.0441E-05 |
| 2.2042E-04 | 8.6037E-05 | 9.8520E-02 | -9.8000E-04 | 3.7000E-04 | 3.4190E-05 |
| 3.6538E-04 | -8.9508E-04 | 7.4920E-02 | -7.8000E-04 | 9.0000E-05 | -7.5701E-05 |
| 1.0115E-04 | 3.3977E-04 | 8.8240E-02 | -9.0000E-05 | 3.0000E-04 | 8.6093E-05 |
| 2.4638E-04 | -2.1106E-03 | 1.7660E-02 | 2.0000E-05 | 2.9557E-11 | -1.7043E-04 |
| 6.5578E-05 | -2.5970E-03 | -1.1700E-03 | -1.0000E-05 | 1.5418E-12 | -2.5204E-04 |

2.094

CASE 2

CONSTRAINED RAD - SINE COMPONENTS

| FREQ | SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|-------|-------------|-------------|-------------|-------------|-------------|-------------|
| 0.251 | 9.2750E-05 | -6.4952E-04 | -1.3369E-01 | 1.3700E-03 | 5.9000E-04 | -4.4326E-05 |
| | 1.3711E-04 | -9.8859E-04 | -1.9922E-01 | 2.0200E-03 | 7.9000E-04 | -6.6691E-05 |
| | 1.5028E-04 | -1.1012E-03 | -2.1918E-01 | 2.2200E-03 | 8.3000E-04 | -7.4041E-05 |
| | 1.6402E-04 | -1.2194E-03 | -2.4326E-01 | 2.4400E-03 | 8.7000E-04 | -8.1514E-05 |
| | 1.7796E-04 | -1.3604E-03 | -2.7222E-01 | 2.6900E-03 | 8.9000E-04 | -9.0305E-05 |
| | 1.9620E-04 | -1.5246E-03 | -3.0981E-01 | 2.9600E-03 | 8.9000E-04 | -1.0030E-04 |
| | 2.1244E-04 | -1.7107E-03 | -3.5586E-01 | 3.2700E-03 | 8.4000E-04 | -1.1109E-04 |
| | 2.1760E-04 | -1.8071E-03 | -3.8468E-01 | 3.4300E-03 | 7.9000E-04 | -1.1640E-04 |
| | 2.2681E-04 | -1.9209E-03 | -4.1674E-01 | 3.6000E-03 | 7.2000E-04 | -1.2356E-04 |
| | 2.3140E-04 | -2.0348E-03 | -4.5332E-01 | 3.7600E-03 | 6.1000E-04 | -1.2847E-04 |
| | 2.3432E-04 | -2.1581E-03 | -4.9575E-01 | 3.9200E-03 | 4.7000E-04 | -1.3449E-04 |
| | 2.3493E-04 | -2.2697E-03 | -5.4526E-01 | 4.0700E-03 | 2.8000E-04 | -1.3867E-04 |
| | 2.2371E-04 | -2.3953E-03 | -6.0157E-01 | 4.2000E-03 | 2.0001E-05 | -1.4353E-04 |
| | 2.1477E-04 | -2.4983E-03 | -6.6733E-01 | 4.2900E-03 | -3.1000E-04 | -1.4578E-04 |
| | 1.9204E-04 | -2.5837E-03 | -7.4127E-01 | 4.3100E-03 | -7.3000E-04 | -1.4524E-04 |
| | 1.5618E-04 | -2.6438E-03 | -8.2145E-01 | 4.2700E-03 | -1.2400E-03 | -1.4187E-04 |
| | 1.0550E-04 | -2.6191E-03 | -9.0748E-01 | 4.0700E-03 | -1.8500E-03 | -1.2979E-04 |
| | 2.8361E-05 | -2.5276E-03 | -9.8810E-01 | 3.7000E-03 | -2.5400E-03 | -1.1160E-04 |
| | -6.7810E-05 | -2.2672E-03 | -1.0469E+00 | 3.0400E-03 | -3.2300E-03 | -7.8015E-05 |
| | -1.7584E-04 | -1.8285E-03 | -1.0480E+00 | 2.0600E-03 | -3.7500E-03 | -3.0386E-05 |
| | -2.8186E-04 | -1.1471E-03 | -9.2624E-01 | 6.8000E-04 | -3.7600E-03 | 3.5054E-05 |
| | -3.1758E-04 | -2.6847E-04 | -5.7772E-01 | -9.5000E-04 | -2.6800E-03 | 1.1019E-04 |
| | -1.8798E-04 | 5.2057E-04 | 8.2310E-02 | -2.1700E-03 | 6.0001E-05 | 1.6405E-04 |
| | 1.0478E-04 | 3.9297E-04 | 7.3015E-01 | 1.1000E-03 | 3.0200E-03 | 6.3797E-05 |
| | 2.0656E-04 | 6.1750E-04 | 4.7407E-01 | -5.1600E-03 | 1.6000E-03 | 7.1912E-05 |
| | 1.8379E-04 | -6.4369E-04 | 9.5780E-02 | -2.8300E-03 | -1.8000E-04 | -6.4551E-05 |
| | 4.3137E-05 | -4.0448E-04 | 8.6460E-02 | -3.9000E-04 | 2.9000E-04 | -4.8916E-08 |
| | -1.2690E-04 | -3.2398E-04 | -2.2650E-02 | -2.0000E-04 | -1.4000E-04 | -9.4844E-06 |
| | 1.4470E-04 | -4.2130E-04 | -5.8400E-03 | 9.0000E-05 | 1.0000E-05 | -3.7596E-05 |
| 2.094 | 1.3652E-04 | -1.4200E-03 | 2.1000E-03 | -3.0000E-05 | 1.0000E-05 | -1.2434E-04 |

N

CASE 2

Kips \$ Kip - Ft.

CONSTRAINT FORCES

| FEER | SURGE-C | SURGE-S | SWAY-C | SWAY-S | YAW-C | YAW-S |
|-------|-------------|-------------|-------------|-------------|-------------|-------------|
| 0.251 | 4.136E+00 | 2.1518E+01 | -1.0400E+01 | -6.4952E+01 | -3.6609E+03 | -1.6401E+04 |
| | 9.834E+00 | 3.1810E+01 | -2.3136E+01 | -9.8859E+01 | -8.1837E+03 | -2.4676E+04 |
| | 1.209E+01 | 3.4865E+01 | -2.7799E+01 | -1.1012E+02 | -9.8855E+03 | -2.7395E+04 |
| | 1.4973E+01 | 3.8054E+01 | -3.3944E+01 | -1.2194E+02 | -1.2090E+04 | -3.0160E+04 |
| | 1.8832E+01 | 4.1751E+01 | -4.2619E+01 | -1.3604E+02 | -1.5134E+04 | -3.3413E+04 |
| | 2.3876E+01 | 4.5519E+01 | -5.2914E+01 | -1.5246E+02 | -1.8854E+04 | -3.7109E+04 |
| | 3.0531E+01 | 4.9286E+01 | -6.6070E+01 | -1.7107E+02 | -2.3605E+04 | -4.1104E+04 |
| | 3.4594E+01 | 5.0947E+01 | -7.4626E+01 | -1.8071E+02 | -2.6602E+04 | -4.3066E+04 |
| | 3.9474E+01 | 5.2620E+01 | -8.4468E+01 | -1.9209E+02 | -3.0098E+04 | -4.5349E+04 |
| | 4.4848E+01 | 5.3685E+01 | -9.4892E+01 | -2.0348E+02 | -3.3936E+04 | -4.7535E+04 |
| | 5.1183E+01 | 5.4363E+01 | -1.0754E+02 | -2.1581E+02 | -3.8398E+04 | -4.9762E+04 |
| | 5.8582E+01 | 5.4296E+01 | -1.2390E+02 | -2.2697E+02 | -4.4037E+04 | -5.1308E+04 |
| | 6.6444E+01 | 5.3060E+01 | -1.4042E+02 | -2.3953E+02 | -4.9985E+04 | -5.3107E+04 |
| | 7.5488E+01 | 4.9827E+01 | -1.5992E+02 | -2.4983E+02 | -5.6779E+04 | -5.3938E+04 |
| | 8.5117E+01 | 4.4552E+01 | -1.8398E+02 | -2.5837E+02 | -6.4820E+04 | -5.3741E+04 |
| | 9.4738E+01 | 3.6233E+01 | -2.0683E+02 | -2.6438E+02 | -7.2647E+04 | -5.2493E+04 |
| | 1.0354E+02 | 2.3780E+01 | -2.3647E+02 | -2.6191E+02 | -8.2047E+04 | -4.8023E+04 |
| | 1.0766E+02 | 6.5798E+00 | -2.6549E+02 | -2.5276E+02 | -9.1009E+04 | -4.1294E+04 |
| | 1.1008E+02 | -1.5732E+01 | -2.9560E+02 | -2.2672E+02 | -9.8953E+04 | -2.8866E+04 |
| | 1.009E+02 | -4.1724E+01 | -3.1899E+02 | -1.8285E+02 | -1.0355E+05 | -1.1243E+04 |
| | 7.4539E+01 | -6.5391E+01 | -3.2295E+02 | -1.1471E+02 | -9.9416E+04 | 1.2970E+04 |
| | 2.9890E+01 | -7.3677E+01 | -2.9645E+02 | -2.6847E+01 | -8.2986E+04 | 4.0771E+04 |
| | -1.9888E+01 | -4.3611E+01 | -2.0116E+02 | 5.2057E+01 | -4.3034E+04 | 6.0700E+04 |
| | -2.4019E+01 | 2.4355E+01 | -9.9027E+01 | -3.9297E+01 | 1.5589E+02 | 2.3605E+04 |
| | 2.5458E+01 | 4.7922E+01 | -2.7065E+01 | 6.1750E+01 | 2.2363E+04 | 2.6608E+04 |
| | 5.1137E+01 | 4.2638E+01 | 8.6037E+00 | -6.4369E+01 | 1.2650E+04 | -2.3884E+04 |
| | 8.4769E+01 | 1.0008E+01 | -8.9508E+01 | -4.0448E+01 | -2.8009E+04 | -1.8099E+01 |
| | 2.3476E+01 | -2.9325E+01 | 3.3977E+01 | -3.2398E+01 | 3.1854E+04 | -3.5092E+03 |
| | 5.7161E+01 | 3.3571E+01 | -2.1106E+02 | -4.2130E+01 | -6.3058E+04 | -1.3910E+04 |
| | 1.5214E+01 | 3.1674E+01 | -2.5970E+02 | -1.4200E+02 | -9.3255E+04 | -4.6004E+04 |

2.034

CONSTRAINT STIFFNESSES

| | | |
|-------|------------|------|
| SURGE | 2.3200E+05 | K/F |
| SWAY | 1.0000E+05 | K/F |
| YAW | 3.7000E+08 | Kr/F |

CASE 3

CONSTRAINED RAD - COSINE COMPONENTS

| FRER | SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|-------|-------------|-------------|-------------|-------------|-------------|-------------|
| 0.251 | 1.7830E-05 | -2.0814E-04 | 6.6316E-01 | 2.3000E-04 | 5.0000E-05 | -9.9000E-06 |
| | 4.5390E-05 | -4.6331E-04 | 6.5999E-01 | 5.2000E-04 | 3.4000E-04 | -2.2138E-05 |
| | 5.1979E-05 | -5.5677E-04 | 6.5901E-01 | 6.2000E-04 | 4.5000E-04 | -2.6744E-05 |
| | 6.4540E-05 | -6.5774E-04 | 6.5774E-01 | 7.6000E-04 | 5.8000E-04 | -3.2711E-05 |
| | 8.1173E-05 | -8.5390E-04 | 6.5578E-01 | 9.4000E-04 | 7.4000E-04 | -4.0955E-05 |
| | 1.0291E-04 | -1.0604E-03 | 6.5260E-01 | 1.1700E-03 | 9.5000E-04 | -5.1029E-05 |
| | 1.3160E-04 | -1.3244E-03 | 6.4745E-01 | 1.4600E-03 | 1.2000E-03 | -6.3899E-05 |
| | 1.4911E-04 | -1.4961E-03 | 6.4290E-01 | 1.6600E-03 | 1.3400E-03 | -7.2021E-05 |
| | 1.7615E-04 | -1.6938E-03 | 6.3699E-01 | 1.8700E-03 | 1.5000E-03 | -8.1497E-05 |
| | 1.9331E-04 | -1.9031E-03 | 6.2871E-01 | 2.1100E-03 | 1.6600E-03 | -9.1900E-05 |
| | 2.2062E-04 | -2.1573E-03 | 6.1675E-01 | 2.4000E-03 | 1.8400E-03 | -1.0400E-04 |
| | 2.5251E-04 | -2.4841E-03 | 5.9940E-01 | 2.7300E-03 | 2.0200E-03 | -1.1930E-04 |
| | 2.8726E-04 | -2.8183E-03 | 5.7504E-01 | 3.1000E-03 | 2.1900E-03 | -1.3544E-04 |
| | 3.2538E-04 | -3.2107E-03 | 5.3865E-01 | 3.5200E-03 | 2.3300E-03 | -1.5388E-04 |
| | 3.6688E-04 | -3.6951E-03 | 4.8712E-01 | 4.0200E-03 | 2.4300E-03 | -1.7572E-04 |
| | 4.0836E-04 | -4.1555E-03 | 4.1516E-01 | 4.5500E-03 | 2.4500E-03 | -1.9700E-04 |
| | 4.4639E-04 | -4.7535E-03 | 3.0917E-01 | 5.1600E-03 | 2.3200E-03 | -2.2258E-04 |
| | 4.7265E-04 | -5.3377E-03 | 1.6208E-01 | 5.7800E-03 | 1.9700E-03 | -2.4701E-04 |
| | 4.7448E-04 | -5.9500E-03 | -4.7220E-02 | 6.4000E-03 | 1.2900E-03 | -2.6876E-04 |
| | 4.5142E-04 | -6.4267E-03 | -3.2399E-01 | 6.8600E-03 | 1.7000E-04 | -2.8150E-04 |
| | 3.2951E-04 | -6.5145E-03 | -6.6990E-01 | 6.9800E-03 | -1.4400E-03 | -2.7065E-04 |
| | 1.2884E-04 | -5.9908E-03 | -1.0199E+00 | 6.4100E-03 | -3.2900E-03 | -2.2647E-04 |
| | -8.5725E-05 | -4.0760E-03 | -1.1390E+00 | 4.6700E-03 | -4.2600E-03 | -1.1820E-04 |
| | -1.0353E-04 | -2.0040E-03 | -5.9075E-01 | 4.6400E-03 | -2.0400E-03 | -4.1005E-07 |
| | 1.0973E-04 | -5.5722E-04 | 1.4416E-01 | 2.4400E-03 | 1.2100E-03 | 5.9831E-05 |
| | 2.2042E-04 | 1.8535E-04 | 9.8520E-02 | -9.8000E-04 | 3.7000E-04 | 3.4704E-05 |
| | 3.6538E-04 | -1.8244E-03 | 7.4920E-02 | -7.8000E-04 | 9.0000E-05 | -7.6936E-05 |
| | 1.0119E-04 | 7.0954E-04 | 8.8240E-02 | -9.0000E-05 | 3.0000E-04 | 8.7252E-05 |
| | 2.4638E-04 | -4.3954E-03 | 1.7660E-02 | 2.0000E-05 | 2.9557E-11 | -1.7708E-04 |
| | 6.5578E-05 | -4.0398E-03 | -1.1700E-03 | -1.0000E-05 | 1.5418E-12 | -1.9829E-04 |

2.09A

CASE 3

CONSTRAINED RAD - SINE COMPONENTS

| FREQ | SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|-------------|-------------|-------------|-------------|-------------|-------------|-----|
| 9.2750E-05 | -1.3001E-03 | -1.3369E-01 | 1.3700E-03 | 5.9000E-04 | -4.4363E-05 | |
| 1.3711E-04 | -1.9798E-03 | -1.9923E-01 | 2.0200E-03 | 7.9000E-04 | -6.6782E-05 | |
| 1.5028E-04 | -2.2058E-03 | -2.1918E-01 | 2.2200E-03 | 8.3000E-04 | -7.4154E-05 | |
| 1.6392E-04 | -2.4429E-03 | -2.4326E-01 | 2.4400E-03 | 8.7000E-04 | -8.1653E-05 | |
| 1.7796E-04 | -2.7261E-03 | -2.7292E-01 | 2.6900E-03 | 8.9000E-04 | -9.0484E-05 | |
| 1.9200E-04 | -3.0559E-03 | -3.0981E-01 | 2.8600E-03 | 8.9000E-04 | -1.0053E-04 | |
| 2.1244E-04 | -3.4301E-03 | -3.5586E-01 | 3.2700E-03 | 8.4000E-04 | -1.1139E-04 | |
| 2.1840E-04 | -3.6240E-03 | -3.8468E-01 | 3.4300E-03 | 7.9000E-04 | -1.1674E-04 | |
| 2.2481E-04 | -3.8532E-03 | -4.1674E-01 | 3.6000E-03 | 7.2000E-04 | -1.2296E-04 | |
| 2.3140E-04 | -4.0828E-03 | -4.5333E-01 | 3.7600E-03 | 6.1000E-04 | -1.2893E-04 | |
| 2.3432E-04 | -4.3314E-03 | -4.9575E-01 | 3.9200E-03 | 4.7000E-04 | -1.3502E-04 | |
| 2.3493E-04 | -4.5571E-03 | -5.4524E-01 | 4.0700E-03 | 2.8000E-04 | -1.3928E-04 | |
| 2.371E-04 | -4.8112E-03 | -6.0157E-01 | 4.2000E-03 | 2.0001E-05 | -1.4425E-04 | |
| 2.1477E-04 | -5.0205E-03 | -6.6733E-01 | 4.2900E-03 | -3.1000E-04 | -1.4661E-04 | |
| 1.9204E-04 | -5.1950E-03 | -7.4127E-01 | 4.3100E-03 | -7.3000E-04 | -1.4621E-04 | |
| 1.5418E-04 | -5.3194E-03 | -8.2145E-01 | 4.2700E-03 | -1.2400E-03 | -1.4299E-04 | |
| 1.0250E-04 | -5.2743E-03 | -9.0748E-01 | 4.0700E-03 | -1.8500E-03 | -1.3106E-04 | |
| 2.8361E-05 | -5.0956E-03 | -9.8810E-01 | 3.7000E-03 | -2.5400E-03 | -1.1303E-04 | |
| -6.7810E-05 | -4.5775E-03 | -1.0469E+00 | 3.0400E-03 | -3.2300E-03 | -7.9547E-05 | |
| -1.7984E-04 | -3.7003E-03 | -1.0480E+00 | 2.0600E-03 | -3.7500E-03 | -3.1935E-05 | |
| -2.8186E-04 | -2.3320E-03 | -9.2624E-01 | 6.8000E-04 | -3.7600E-03 | 3.3686E-05 | |
| -3.1758E-04 | -5.6144E-04 | -5.7772E-01 | -9.5000E-03 | -2.6800E-03 | 1.0928E-04 | |
| -1.8798E-04 | 1.0377E-03 | 8.2310E-02 | -2.1700E-03 | 6.0001E-05 | 1.6389E-04 | |
| 1.0498E-04 | -8.0667E-04 | 7.3015E-01 | 1.1000E-03 | 3.0200E-03 | 6.3029E-05 | |
| 2.0456E-04 | 1.2514E-03 | 4.7407E-01 | -5.1600E-03 | 1.6000E-03 | 7.2494E-05 | |
| 1.8379E-04 | -1.3106E-03 | 9.5780E-02 | -2.8300E-03 | -1.8000E-04 | -6.5391E-05 | |
| 4.3139E-05 | -8.4596E-04 | 8.6460E-02 | -3.9000E-04 | 2.9000E-04 | -1.4742E-06 | |
| -1.2640E-04 | -6.5883E-04 | -2.2650E-02 | -2.0000E-04 | -1.4000E-04 | -9.8583E-06 | |
| 1.4470E-04 | -9.7317E-04 | -3.8400E-03 | 9.0000E-05 | 1.0000E-05 | -4.2991E-05 | |
| 1.3652E-04 | -4.0116E-03 | 2.1000E-03 | -3.0000E-05 | 1.0000E-05 | -1.7452E-04 | |

0.251



0.094

CASE 3

CONSTRAINT FORCES kips & kip-ft.

| ITER | SURGE-C | SURGE-S | SWAY-C | SWAY-S | YAW-C | YAW-S |
|-------|-------------|-------------|-------------|-------------|-------------|-------------|
| 0.251 | 4.1365E+00 | 2.1518E+01 | -1.0408E+01 | -6.5007E+01 | -3.6630E+03 | -1.6414E+04 |
| | 9.8445E+00 | 3.1810E+01 | -2.3145E+01 | -9.8992E+01 | -8.1912E+03 | -2.4709E+04 |
| | 1.2059E+01 | 3.4865E+01 | -2.7839E+01 | -1.1029E+02 | -9.8954E+03 | -2.7437E+04 |
| | 1.4973E+01 | 3.8054E+01 | -1.2315E+02 | -1.1231E+02 | -1.2103E+04 | -3.0212E+04 |
| | 1.8832E+01 | 4.1751E+01 | -4.2695E+01 | -1.3311E+02 | -1.5153E+04 | -3.3479E+04 |
| | 2.3876E+01 | 4.5519E+01 | -5.3020E+01 | -1.5280E+02 | -1.8881E+04 | -3.7195E+04 |
| | 3.0531E+01 | 4.9286E+01 | -6.4219E+01 | -1.7151E+02 | -2.3642E+04 | -4.1214E+04 |
| | 3.4394E+01 | 5.0947E+01 | -7.4807E+01 | -1.8120E+02 | -2.6648E+04 | -4.5192E+04 |
| | 3.9474E+01 | 5.2620E+01 | -8.4688E+01 | -1.9266E+02 | -3.0154E+04 | -4.8494E+04 |
| | 4.4848E+01 | 5.3685E+01 | -9.5157E+01 | -2.0414E+02 | -3.4003E+04 | -4.7703E+04 |
| | 5.1183E+01 | 5.4363E+01 | -1.0787E+02 | -2.1657E+02 | -3.8480E+04 | -4.9957E+04 |
| | 5.852E+01 | 5.4296E+01 | -1.2431E+02 | -2.2785E+02 | -4.4140E+04 | -5.1534E+04 |
| | 6.6644E+01 | 5.3060E+01 | -1.4091E+02 | -2.4056E+02 | -5.0112E+04 | -5.3371E+04 |
| | 7.5488E+01 | 4.9827E+01 | -1.6053E+02 | -2.5102E+02 | -5.6935E+04 | -5.4244E+04 |
| | 8.5117E+01 | 4.4552E+01 | -1.8476E+02 | -2.5975E+02 | -6.5018E+04 | -5.4096E+04 |
| | 9.4738E+01 | 3.6233E+01 | -2.0778E+02 | -2.6597E+02 | -7.2890E+04 | -5.2905E+04 |
| | 1.0356E+02 | 2.3780E+01 | -2.3768E+02 | -2.6371E+02 | -8.2356E+04 | -4.8492E+04 |
| | 1.0766E+02 | 6.5798E+00 | -2.6699E+02 | -2.5478E+02 | -9.1395E+04 | -4.1821E+04 |
| | 1.1008E+02 | -1.5732E+01 | -2.9750E+02 | -2.2888E+02 | -9.9443E+04 | -2.9433E+04 |
| | 1.0099E+02 | -4.1724E+01 | -3.2134E+02 | -1.8502E+02 | -1.0416E+05 | -1.1816E+04 |
| | 7.4359E+01 | -6.5391E+01 | -3.2573E+02 | -1.1660E+02 | -1.0014E+05 | 1.2464E+04 |
| | 2.4890E+01 | -7.3677E+01 | -2.9954E+02 | -2.8072E+01 | -8.3795E+04 | 4.0434E+04 |
| | -1.9888E+01 | -4.3611E+01 | -2.0380E+02 | 5.1884E+01 | -4.3735E+04 | 6.0640E+04 |
| | -2.4019E+01 | 2.4355E+01 | -1.0020E+02 | -4.0334E+01 | -1.5172E+02 | 2.3321E+04 |
| | 2.5458E+01 | 4.7922E+01 | -2.7881E+01 | 6.2571E+01 | 2.2137E+04 | 2.6823E+04 |
| | 5.1137E+01 | 4.2638E+01 | 9.2673E+00 | -6.5528E+01 | 1.2840E+04 | -2.4195E+04 |
| | 8.4782E+01 | 1.0008E+01 | -9.1219E+01 | -4.2298E+01 | -2.8466E+04 | -5.4547E+02 |
| | 2.3476E+01 | -2.9325E+01 | 3.5477E+01 | -3.2941E+01 | 3.2283E+04 | -3.6476E+03 |
| | 5.7161E+01 | 3.3571E+01 | -2.1977E+02 | -4.8658E+01 | -6.5518E+04 | -1.5907E+04 |
| 2.094 | 1.5214E+01 | 3.1674E+01 | -2.0199E+02 | -2.0058E+02 | -7.3369E+04 | -6.4572E+04 |

CONSTRAINT STIFFNESSES

| | | |
|-------|------------|------|
| SURGE | 2.3200E+05 | k/f |
| SWAY | 5.0000E+04 | k/f |
| YAW | 3.7000E+08 | k/ff |

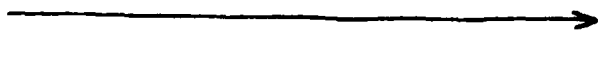
CASE 4

CONSTRAINED RAD - COSINE COMPONENTS

| ROLL | PITCH | YAW |
|-------------|-------------|-------------|
| 2.3000E-04 | 5.0000E-05 | -3.5907E-12 |
| 5.2000E-04 | 3.4000E-04 | -7.9386E-12 |
| 6.2000E-04 | 4.5000E-04 | -9.5571E-12 |
| 7.6000E-04 | 5.8000E-04 | -1.1643E-11 |
| 9.4000E-04 | 7.4000E-04 | -1.4505E-11 |
| 1.1700E-03 | 9.5000E-04 | -1.7972E-11 |
| 1.4600E-03 | 1.2000E-03 | -2.2351E-11 |
| 1.6600E-03 | 1.3400E-03 | -2.5092E-11 |
| 1.8700E-03 | 1.5000E-03 | -2.8263E-11 |
| 2.1100E-03 | 1.6400E-03 | -3.1723E-11 |
| 2.4000E-03 | 1.8400E-03 | -3.5699E-11 |
| 2.7300E-03 | 2.0200E-03 | -4.0672E-11 |
| 3.1000E-03 | 2.1900E-03 | -4.5856E-11 |
| 3.5200E-03 | 2.3300E-03 | -5.1691E-11 |
| 4.0200E-03 | 2.4300E-03 | -5.8452E-11 |
| 4.5500E-03 | 2.4500E-03 | -6.4851E-11 |
| 5.1600E-03 | 2.3200E-03 | -7.2287E-11 |
| 5.7800E-03 | 1.9700E-03 | -7.9002E-11 |
| 6.4000E-03 | 1.2900E-03 | -8.4229E-11 |
| 6.8600E-03 | 1.7000E-04 | -8.6034E-11 |
| 6.9800E-03 | 1.4400E-03 | -7.9867E-11 |
| 6.4100E-03 | -3.2900E-03 | -6.3251E-11 |
| 4.6700E-03 | -4.2400E-03 | -2.9032E-11 |
| 4.6400E-03 | -2.0400E-03 | 2.0399E-12 |
| 2.4400E-03 | 1.2100E-03 | 1.8307E-11 |
| -2.8000E-04 | 3.7000E-04 | 6.2529E-12 |
| -7.8000E-04 | 9.0000E-05 | -1.7114E-11 |
| -9.0000E-05 | 3.0000E-04 | 1.6957E-11 |
| 2.0000E-05 | 2.9557E-11 | -2.8506E-11 |
| -1.0000E-05 | 1.5418E-12 | -6.1480E-12 |

ROLL SURGE SWAY HEAVE ROLL PITCH YAW

2.251



2.094

CASE 4

CONSTRAINED ROAD - SINE COMPONENTS

| PKR | SURGE | SWAY | HEAVE | ROLL | PITCH | YAW |
|-------|-------------|-------------|-------------|-------------|-------------|-------------|
| 0.251 | 2.1512E-11 | -6.3982E-11 | -1.3369E-01 | 1.3700E-03 | 5.9000E-04 | -1.6075E-11 |
| | 3.1797E-11 | -9.6536E-11 | -1.9922E-01 | 2.0200E-03 | 7.9000E-04 | -2.3897E-11 |
| | 3.4848E-11 | -1.0731E-10 | -2.1918E-01 | 2.2200E-03 | 8.3000E-04 | -2.6426E-11 |
| | 3.8934E-11 | -1.1838E-10 | -2.4326E-01 | 2.4400E-03 | 8.7000E-04 | -2.8966E-11 |
| | 4.1726E-11 | -1.3158E-10 | -2.7292E-01 | 2.6900E-03 | 8.9000E-04 | -3.1917E-11 |
| | 4.5489E-11 | -1.4681E-10 | -3.0981E-01 | 2.9600E-03 | 8.9000E-04 | -3.5215E-11 |
| | 4.9249E-11 | -1.6387E-10 | -3.5586E-01 | 3.2700E-03 | 8.4000E-04 | -3.8687E-11 |
| | 5.0905E-11 | -1.7260E-10 | -3.8468E-01 | 3.4300E-03 | 7.9000E-04 | -4.0347E-11 |
| | 5.2575E-11 | -1.8283E-10 | -4.1674E-01 | 3.6000E-03 | 7.2000E-04 | -4.2243E-11 |
| | 5.3636E-11 | -1.9295E-10 | -4.5333E-01 | 3.7600E-03 | 6.1000E-04 | -4.4001E-11 |
| | 5.4308E-11 | -2.0377E-10 | -4.9575E-01 | 3.9200E-03 | 4.7000E-04 | -4.5723E-11 |
| | 5.4837E-11 | -2.1334E-10 | -5.4526E-01 | 4.0700E-03 | 2.8000E-04 | -4.6733E-11 |
| | 5.5298E-11 | -2.2393E-10 | -6.0157E-01 | 4.2000E-03 | 2.0001E-05 | -4.7869E-11 |
| | 4.9763E-11 | -2.3235E-10 | -6.6733E-01 | 4.2900E-03 | -3.1000E-04 | -4.8033E-11 |
| | 4.4490E-11 | -2.3871E-10 | -7.4127E-01 | 4.3100E-03 | -7.3000E-04 | -4.7135E-11 |
| | 3.6178E-11 | -2.4254E-10 | -8.2145E-01 | 4.2700E-03 | -1.2400E-03 | -4.5150E-11 |
| | 2.3740E-11 | -2.3863E-10 | -9.0748E-01 | 4.0700E-03 | -1.8500E-03 | -4.0200E-11 |
| | 6.5674E-12 | -2.2869E-10 | -9.8810E-01 | 3.7000E-03 | -2.5400E-03 | -3.3191E-11 |
| | -1.5699E-11 | -2.0439E-10 | -1.0469E+00 | 3.0400E-03 | -3.2300E-03 | -2.1344E-11 |
| | -4.1624E-11 | -1.6569E-10 | -1.0480E+00 | 2.0600E-03 | -3.7500E-03 | -5.4177E-12 |
| | -6.5218E-11 | -1.0855E-10 | -9.2624E-01 | 6.8000E-04 | -3.7400E-03 | -1.5072E-11 |
| | -7.3155E-11 | -3.8673E-11 | -5.7772E-01 | -9.5000E-04 | -2.6800E-03 | 3.6824E-11 |
| | -4.4460E-11 | 1.8742E-11 | 8.2310E-02 | -2.1700E-03 | 6.0001E-05 | 4.9494E-11 |
| | 2.4257E-11 | -5.6267E-11 | 7.3015E-01 | 1.1000E-03 | 3.0200E-03 | 1.7792E-11 |
| | 4.7597E-11 | 3.3479E-11 | 4.7407E-01 | -3.1600E-03 | 1.6000E-03 | 1.7035E-11 |
| | 4.2400E-11 | -4.3840E-11 | 9.5780E-02 | -2.8300E-03 | -1.8000E-04 | -1.7078E-11 |
| | 9.9404E-12 | -3.1305E-11 | 8.6460E-02 | -3.9000E-04 | 2.9000E-04 | 3.0934E-12 |
| | -2.5080E-11 | -3.7103E-11 | -2.2650E-02 | -2.0000E-04 | -1.4000E-04 | -5.2885E-12 |
| | 3.3216E-11 | 3.2716E-12 | -5.8400E-03 | 9.0000E-05 | 1.0000E-05 | 1.4990E-12 |
| 2.094 | 3.1078E-11 | 2.5650E-11 | 2.1000E-03 | -3.0000E-05 | 1.0000E-05 | 1.0128E-11 |

CASE 4

CONSTRAINT FORCES

| FREQ | SURGE-C | SURGE-S | SMAY-C | SMAY-S | YAW-C | YAW-S |
|-------|-------------|-------------|-------------|-------------|-------------|-------------|
| 0.251 | 4.1354E+00 | 2.1512E+01 | -1.0191E+01 | -6.3982E+01 | -3.5907E+03 | -1.6075E+04 |
| | 9.8304E+00 | 3.1797E+01 | -2.2407E+01 | -9.6536E+01 | -7.9386E+03 | -2.3897E+04 |
| | 1.2053E+01 | 3.4848E+01 | -1.0723E+02 | -1.0723E+02 | -9.5571E+03 | -2.6426E+04 |
| | 1.4965E+01 | 3.8034E+01 | -3.2614E+01 | -1.1838E+02 | -1.1643E+04 | -2.8966E+04 |
| | 1.8821E+01 | 4.1726E+01 | -4.0749E+01 | -1.3158E+02 | -1.4505E+04 | -3.1917E+04 |
| | 2.3868E+01 | 4.5489E+01 | -5.0291E+01 | -1.4681E+02 | -1.7972E+04 | -3.5215E+04 |
| | 3.0508E+01 | 4.9249E+01 | -6.2342E+01 | -1.6387E+02 | -2.2351E+04 | -3.8687E+04 |
| | 3.4567E+01 | 5.0906E+01 | -7.0134E+01 | -1.7260E+02 | -2.5092E+04 | -4.0347E+04 |
| | 3.9440E+01 | 5.2575E+01 | -7.9012E+01 | -1.8283E+02 | -2.8263E+04 | -4.2243E+04 |
| | 4.4804E+01 | 5.3636E+01 | -8.8313E+01 | -1.9295E+02 | -3.1723E+04 | -4.4001E+04 |
| | 5.1131E+01 | 5.4308E+01 | -9.9517E+01 | -2.0377E+02 | -3.5699E+04 | -4.5733E+04 |
| | 5.8519E+01 | 5.4237E+01 | -1.1389E+02 | -2.1334E+02 | -4.0672E+04 | -4.6733E+04 |
| | 6.6565E+01 | 5.2998E+01 | -1.2814E+02 | -2.2393E+02 | -4.5856E+04 | -4.7869E+04 |
| | 7.5391E+01 | 4.9763E+01 | -1.4479E+02 | -2.3225E+02 | -5.1691E+04 | -4.8033E+04 |
| | 8.4998E+01 | 4.4490E+01 | -1.6504E+02 | -2.3871E+02 | -5.8452E+04 | -4.7135E+04 |
| | 9.4793E+01 | 3.6178E+01 | -1.8364E+02 | -2.4254E+02 | -6.4851E+04 | -4.5150E+04 |
| | 1.0339E+02 | 2.3740E+01 | -2.0745E+02 | -2.3865E+02 | -7.2287E+04 | -4.0200E+04 |
| | 1.0945E+02 | 6.5674E+00 | -2.2978E+02 | -2.2869E+02 | -7.9002E+04 | -3.3191E+04 |
| | 1.0985E+02 | -1.5699E+01 | -2.5183E+02 | -2.0439E+02 | -8.4229E+04 | -2.1344E+04 |
| | 9.9854E+01 | -4.1626E+01 | -2.6693E+02 | -1.6560E+02 | -8.6034E+04 | -5.4177E+03 |
| | 7.4165E+01 | -6.5218E+01 | -2.6487E+02 | -1.0855E+02 | -7.9867E+04 | 1.5072E+04 |
| | 2.9800E+01 | -7.3455E+01 | -2.3788E+02 | -3.8673E+01 | -6.3251E+04 | 3.6824E+04 |
| | -1.9819E+01 | -4.3460E+01 | -1.5971E+02 | 1.8742E+01 | -2.9032E+04 | 4.9494E+04 |
| | -2.3922E+01 | 2.4257E+01 | -9.3397E+01 | -5.6267E+01 | 2.0399E+03 | 1.7792E+04 |
| | 2.5338E+01 | 4.7697E+01 | -3.9171E+01 | 3.3479E+01 | 1.8307E+04 | 1.7035E+04 |
| | 5.0851E+01 | 4.2400E+01 | -1.0176E+01 | -4.3840E+01 | 6.2529E+03 | -1.7079E+04 |
| | 8.4175E+01 | 9.9404E+00 | -5.6835E+01 | -3.1305E+01 | -1.7114E+04 | 3.0934E+03 |
| | 2.3275E+01 | -2.9080E+01 | -1.0461E+01 | -3.7103E+01 | 1.6957E+04 | -5.2885E+03 |
| | 5.6555E+01 | 3.3216E+01 | -1.0675E+02 | 3.2716E+00 | -2.8506E+04 | 1.4990E+03 |
| | 1.4928E+01 | 3.1078E+01 | 3.1344E+00 | 2.5650E+01 | -6.1480E+03 | 1.0128E+04 |

2.094

CONSTRAINT STIFFNESSES

| | K/F | K/F | K/F |
|-------|------------|-----|-----|
| SURGE | 1.0000E+12 | | |
| SMAY | 1.0000E+12 | | |
| YAW | 1.0000E+15 | | |

SIGNIFICANT HEIGHT = 6.00 FT.
MEAN ZERO-CROSSING PERIOD = 5.50 SEC

Values are:
Average of (1/3 x Spectral peaks) x 1.92.

MAXIMA
motions:

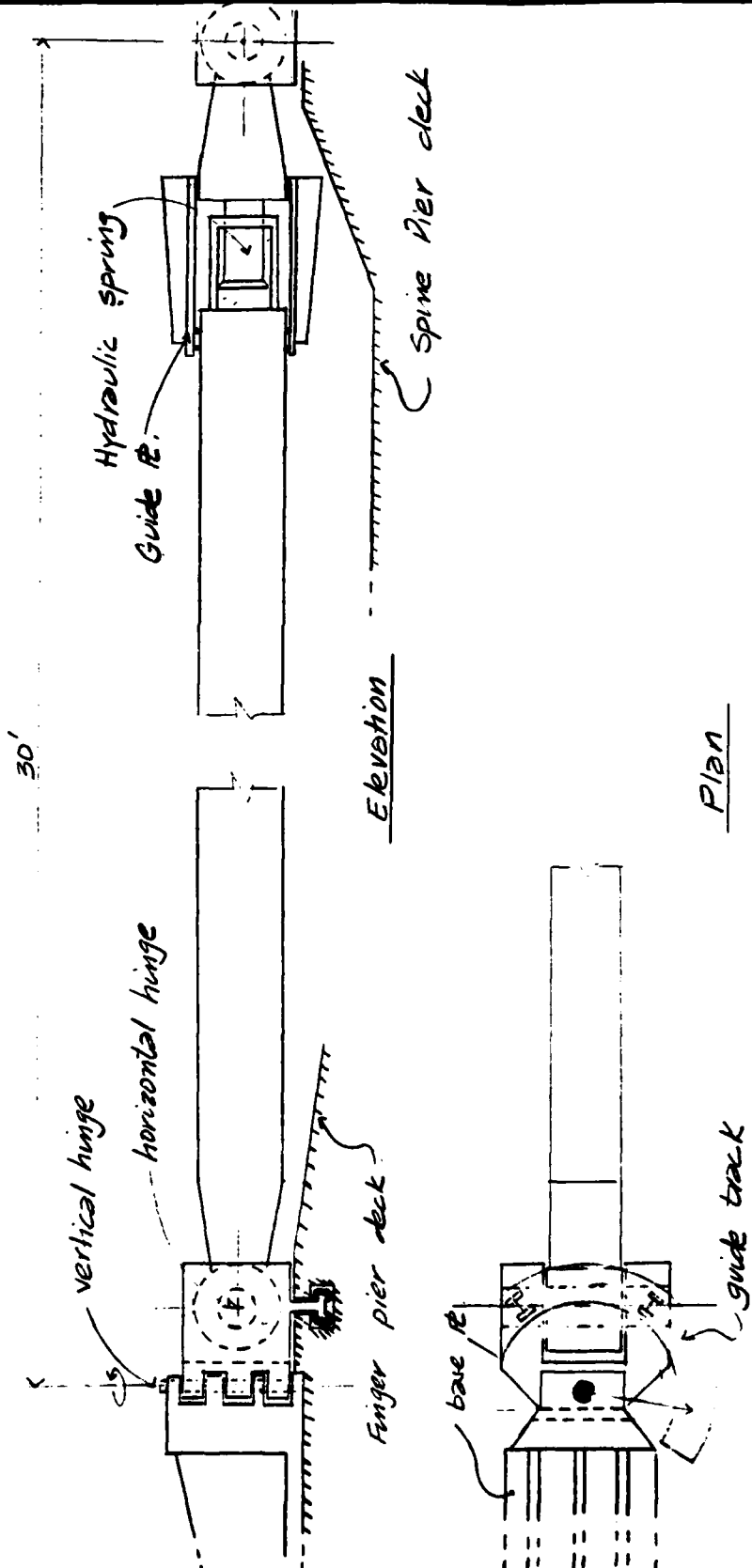
SURGE 4.3859E-10 FT.
SWAY 1.1377E-09 FT.
HEAVE 4.9076E+00 FT.
ROLL 3.0153E-02 RAD
PITCH 1.7566E-02 RAD
YAW 3.2339E-10 RAD

SURGE FORCE = 4.3859E+02 K
SWAY FORCE = 1.1377E+03 K
YAW MOMENT = 3.2339E+05 KF

APPENDIX C

EXTENDABLE LINK DESIGN

Schematic layout of extendable link: (no scale)



Elevation

Plan

Consider max. tension $\approx 10,000$ kips / link.

For Fatigue loading over 2 million cycles and Type B details, non-redundant load path.

Allowable American Welding Society (AWS) stress range

$$F_{sr} = 16 \text{ KSI.}$$

Assume 50% compression load since compression will be taken by bearing against spine pier.

\therefore Allow tensile stress of 12 KSI

Since allow. fatigue stress controls; use A36 steel.

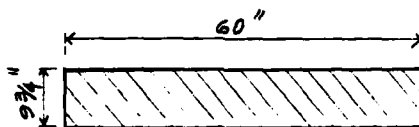
$$F_t = 0.45 F_y = 16.2 \text{ KSI} > 12 \text{ KSI} \quad (\text{static load requirement}).$$

$$A_n \text{ req.} = \frac{10,000 \text{ k}}{12 \text{ KSI}} = 833 \text{ in}^2$$

At pin connection (head) $1.5 A_n \text{ req.} > A_n > 1.33 A_n \text{ req.}$ (AISC 1.14.5)

$$\text{Let } A_n = 1.4 A_n \text{ req.} = 1.4 \times 833 = 1166 \text{ in}^2$$

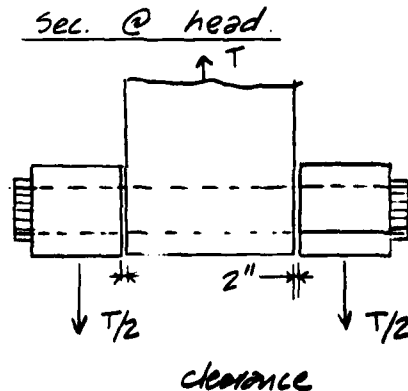
$$\underline{A_n = 1170 \text{ in}^2}$$



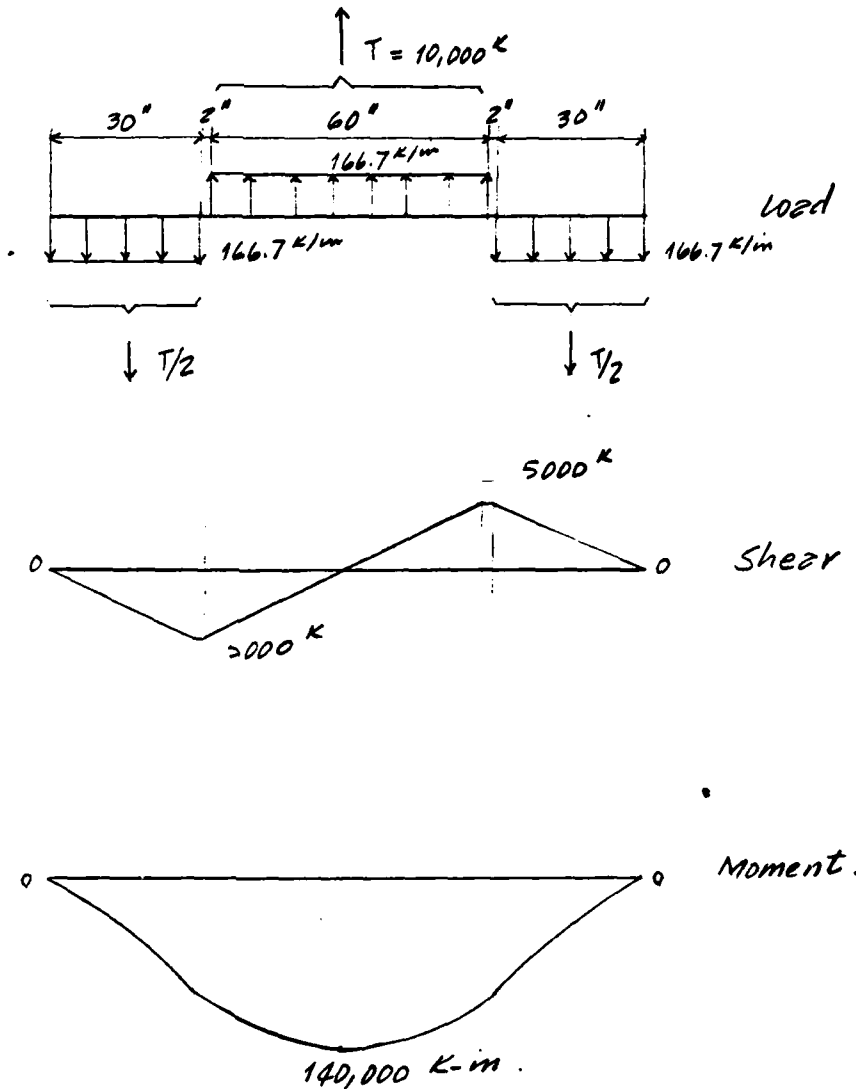
Pin design (use 100 KSI steel)

Use AASHTO design parameters

§ 1.7.1 B for steel pins



Forces on pin.



Bending:

$F_b^* = 0.8 F_y = 80 \text{ ksi}$ on extreme fibre

$$F_b = \frac{Mc}{I} = \frac{M}{\pi r^3/4}$$

$$r^3 = \frac{4M}{\pi F_b} = \frac{4 \times 140,000}{\pi \times 80} = 2228 \text{ m}^3 \quad \text{OR } r = 13.06 \text{ m}$$

OR USE 26 1/2" φ pin.

* Fatigue is not considered. Ultra-high strength steel can be used to keep a practicle pin diameter and appropriate stresses.

Shear:

$$F_v = 0.4 F_y = 40 \text{ ksi}$$

$$F_v = \frac{V}{A} = \frac{5000}{A} \quad \text{OR} \quad A = 125 \text{ in}^2$$

$$\text{OR } d = \underline{12.6 \text{ in}}$$

Bearing:

$$F_b = 0.4 F_y \text{ for pins subject to rotation.}$$

$$F_b = \frac{P}{d \times W} = \frac{5000}{d \times 30} = 40 \text{ ksi} \quad \text{OR } \underline{d = 4.2 \text{ in}}$$

Bending controls. we use 26 1/2" φ pin

Check required thicknesses for hinge end tear-out. based on allowable fatigue stress.

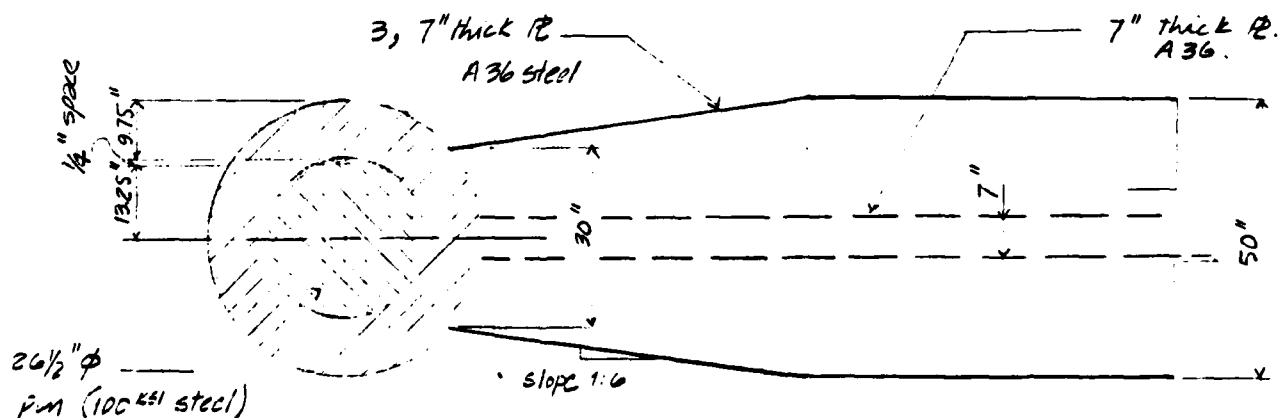
$$F_v = 12 \text{ ksi}$$

$$A_{req} = \frac{10,000}{12 \times 2} = 416.7 \text{ in}^2$$

$$t = \frac{416.7 \text{ in}^2}{60} = 6.9 \text{ in}$$

we use 9 3/4" as controlled by required net area.

Horizontal hinge head details:



(see Fig 4(a) for details)

AD-A146 144

FINGER PIER/SPINE PIER CONNECTION FOR THE EXPEDITIONARY
PIER(U) LIN (T Y) INTERNATIONAL SAN FRANCISCO CA
APR 84 2/84 N00014-83-C-0869

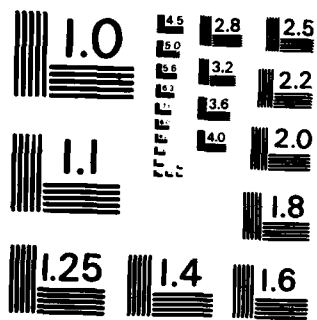
22

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F/G 13/13 NL



END
DATE
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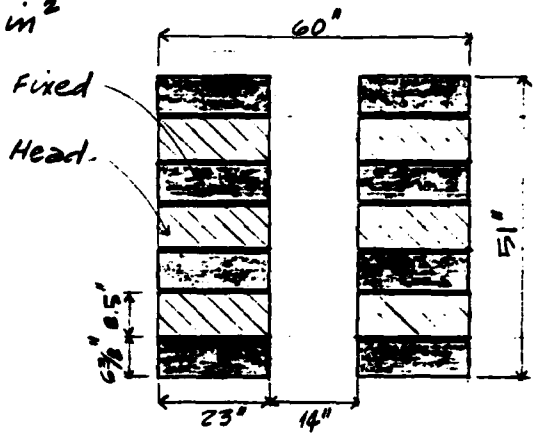
MICROCOPY RESOLUTION TEST CHART
NATIONAL BUREAU OF STANDARDS - 1963 - A

Vertical hinge :

Reqd. net area @ head = 1166 in²

Area provided = (85 x 23) 6
= 1173 in²
for head.

Area provided = (63/8 x 23) 8
= 1173 in²
for fixed part.



Net area section @ vertical hinge:

Check pin diameter :

Bending:

Appx.

M = T/3 x 7.44"
M = 10,000/3 x 7.44 = 24800 K-in

F_b = M / (π r³ / 4) For F_y = 100 KSI ; F_b = 0.8 F_y = 80 KSI

r³ = (4 x 24800) / (π x 80) = 394.7 in³ OR r = 7.3 in
d = 14.6 in ≈ 14 in OK

Shear:

F_v = 0.4 F_y = 0.4 x 100 = 40 KSI

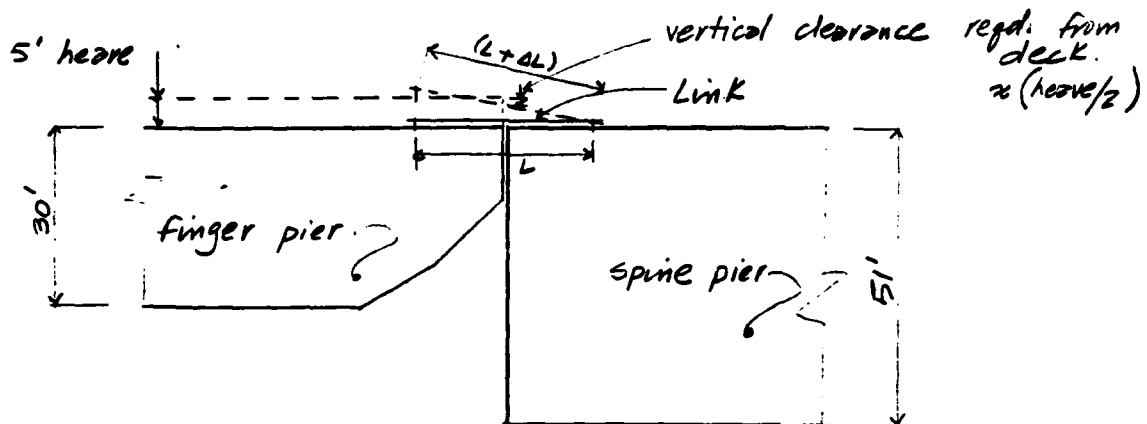
F_v = V / A = 10,000 / 4

A = 62.5 in² OR d = 8.9 in < 14 in OK

Bearing:

F_b = (10,000/3) / (14 x 3/8) = 26 KSI < 0.4 F_y for pins subject to rotation.

OK



In order to allow unconstrained vertical motions of the finger & spine piers the links should be axially extendable. A design value of 5' heave will be considered to estimate the required extension.

$$\text{Total length of link} = 30' = L$$

$$\text{For 5' heave } \Delta L = (5^2 + 30^2)^{1/2} - 30 = 0.41' \text{ OR } \approx \underline{5 \text{ inches}}$$

$$\text{Appx. pitch angle} = 0.0175 \text{ rad.}$$

assume finger pier pivots @ 12' below deck level.

$$\therefore \text{displacement @ deck level} \approx 0.0175 \times 12 = 0.21' \text{ OR } 2.5''$$

Total extension of link ≈ 7.5 in. say 12 in for design.

This can be provided by adding a hydraulic spring/damper to the link. The hydraulic spring can be manufactured for the desired requirements:

Stroke : 12" to 18"

Max. force : 10,000 kips

Acceleration of loading. $\approx 2.3 \text{ ft./s}^2$

The compressive stiffness of the spring can be specified less than the tensile stiffness. This enables the two pier to bear against each other without imposing high compressive forces in the links.

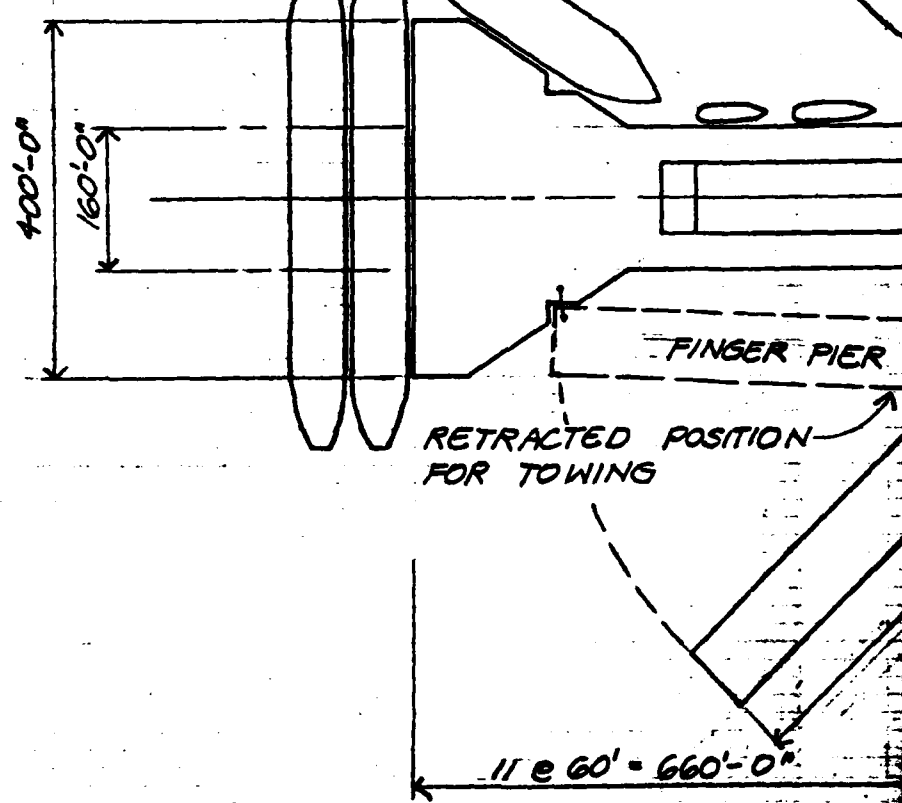
FIGURES

DRAFTING

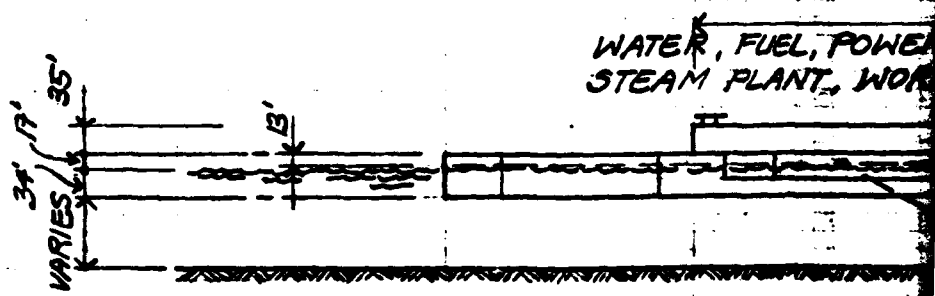
DESIGN

PROJECT NO

D-963 DESTROYER,
MISSILE CRUISER →



PLAN
1" = 200'-0"

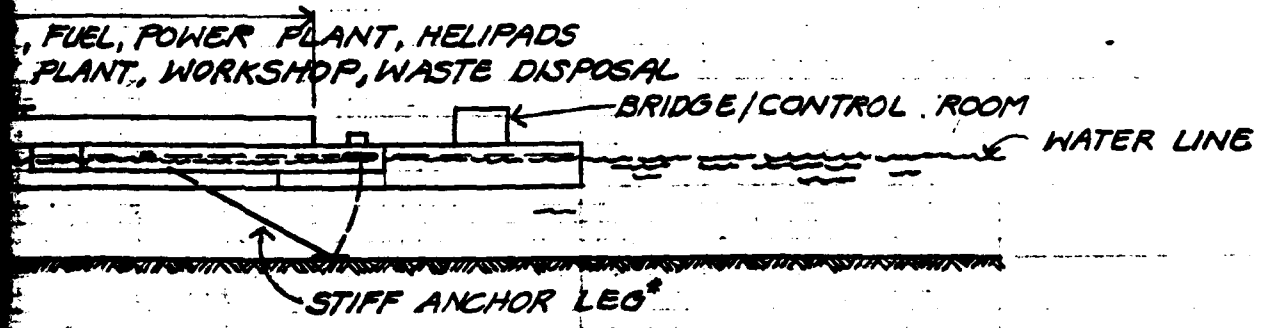
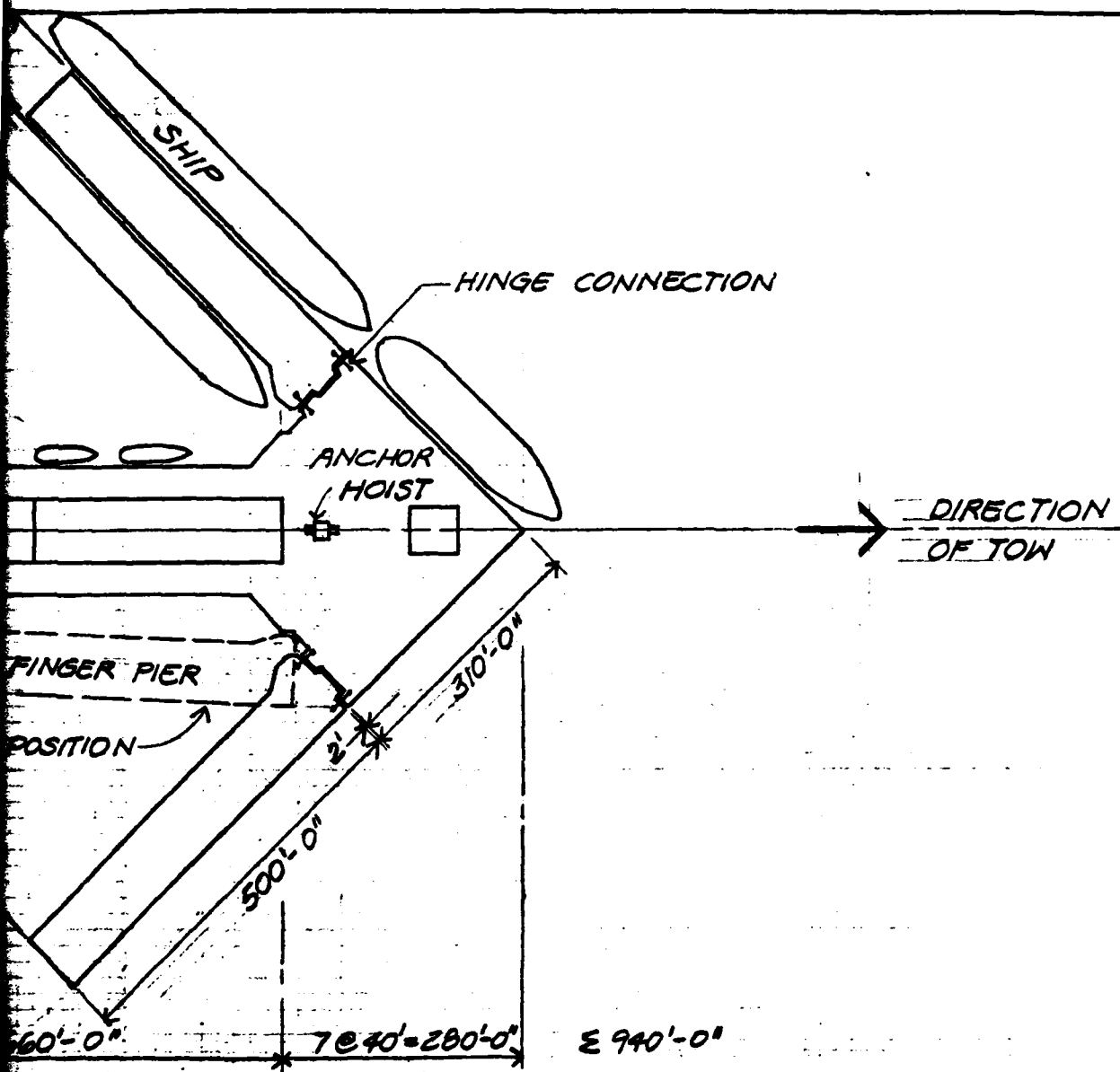


PROFILE
1" = 200'-0"

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* (MOORING SYSTEM HAS BEEN MODIFIED IN REPORT 1/84).

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| | DEC 82 | RM |
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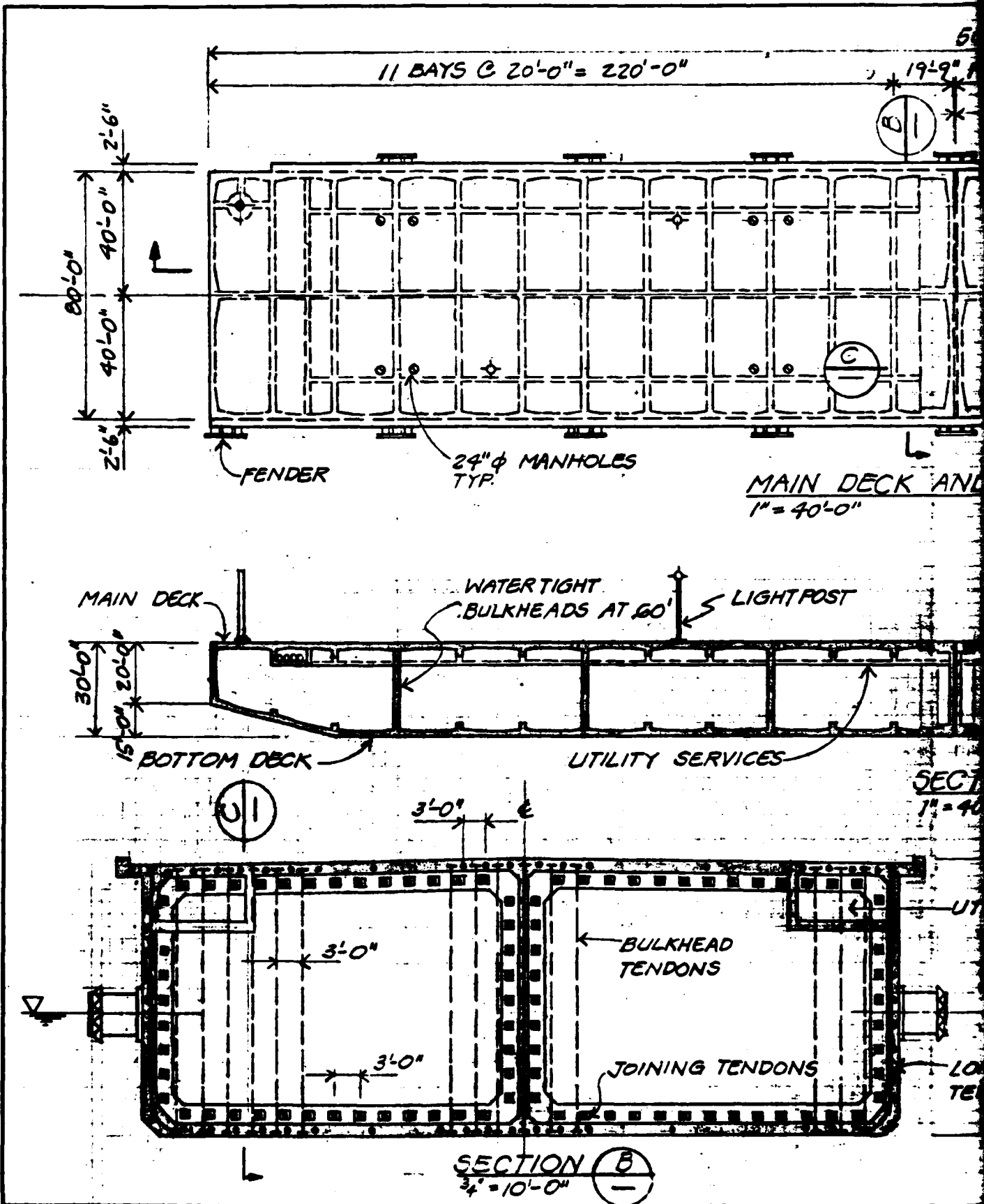
SHEET TITLE: **SCHEME A**
 PROJECT: **EXPEDITIONARY PIER**

SHEET NO.
1

DRAFTING

DESIGN

PROJECT NO

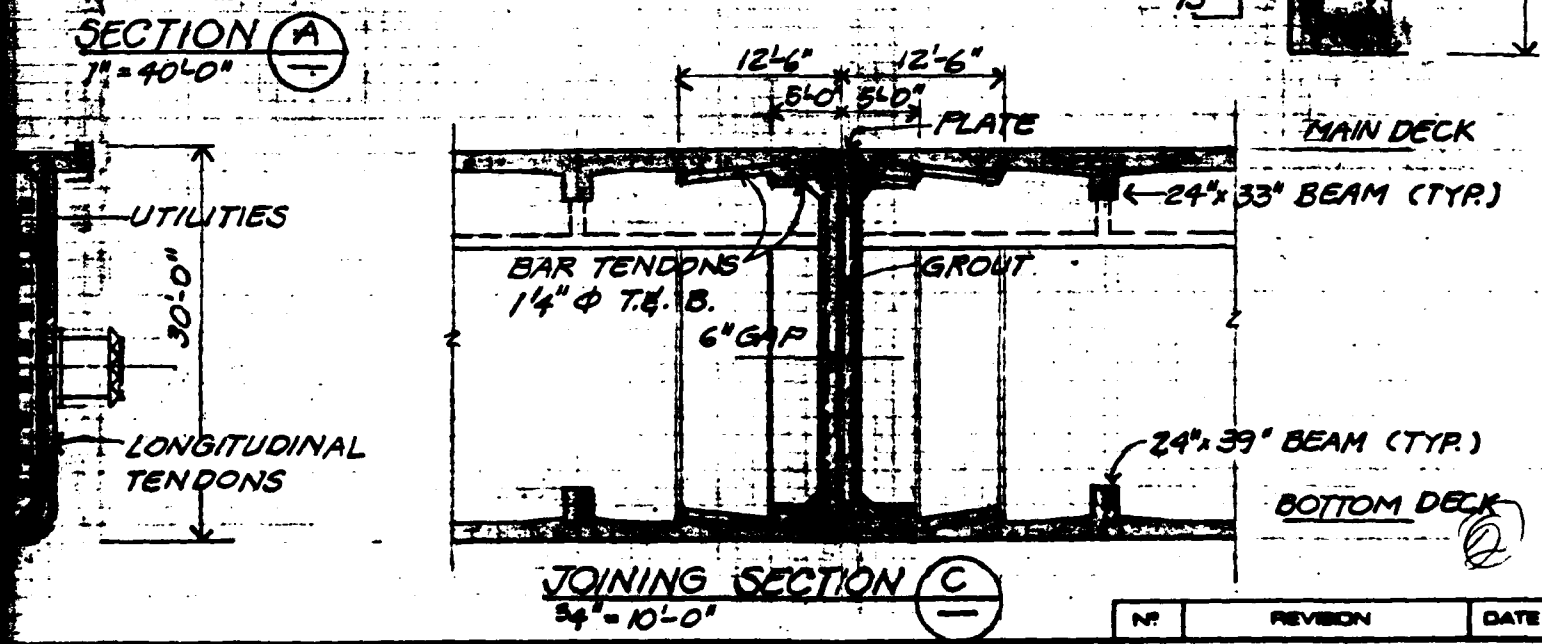
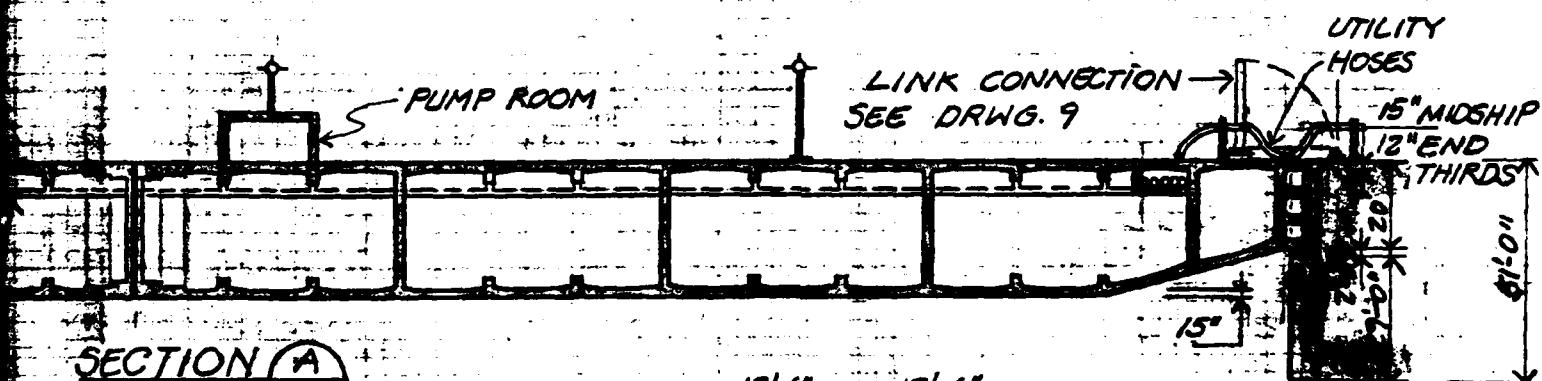
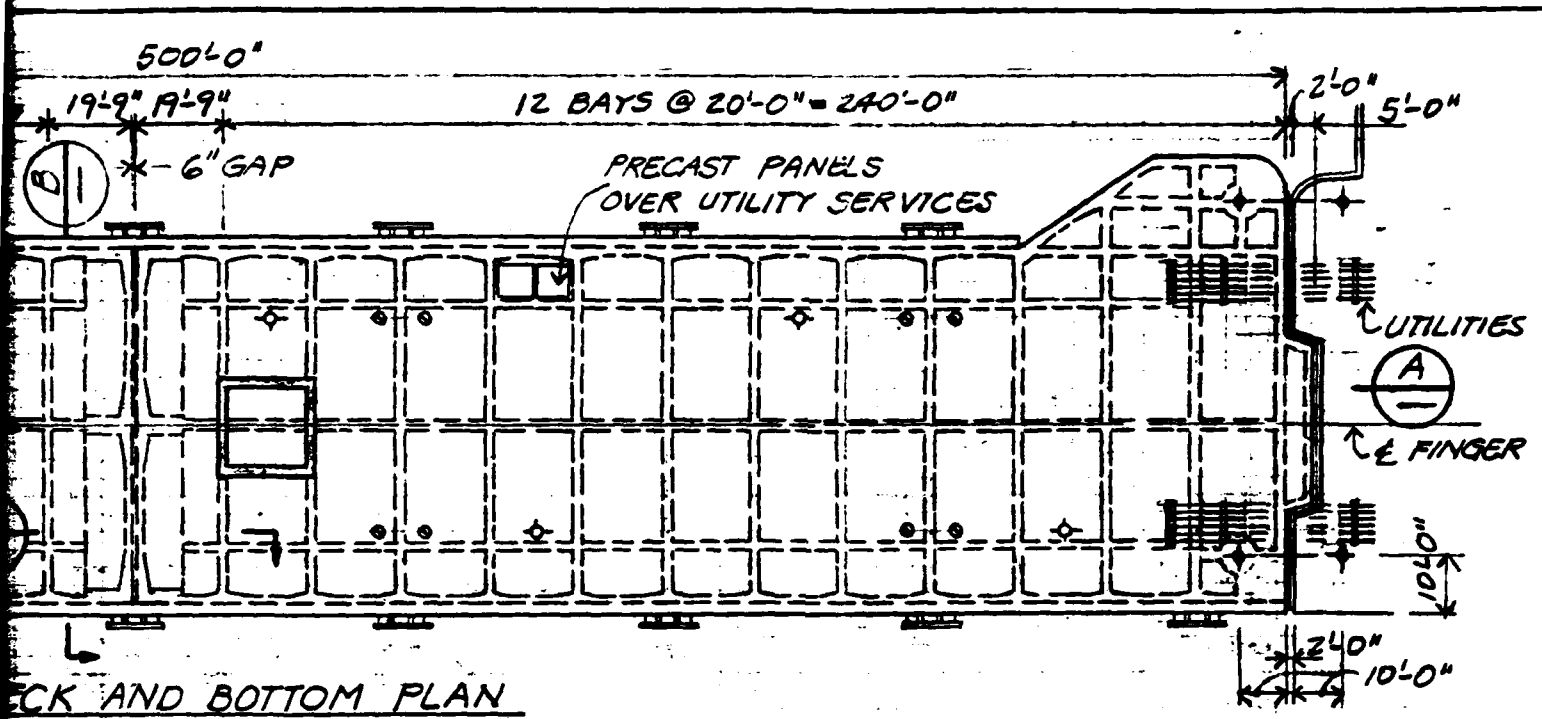


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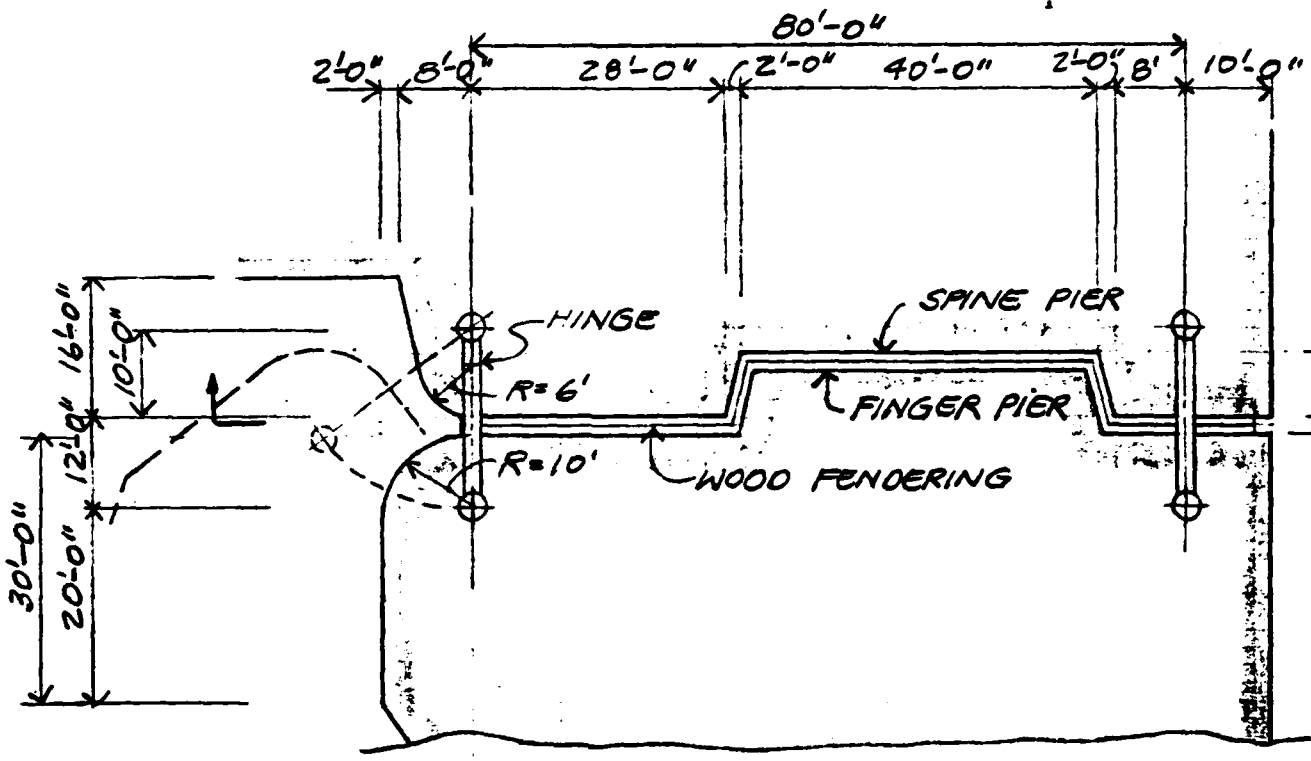
| NO. | REVISION | DATE |
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|-----------|---------|----|---|-----------|
| Drawn For | Date | By | SHEET TITLE: FINGER PIER SECTIONS & DETAILS | SHEET NO. |
| | DEC. 02 | RM | PROJECT: EXPEDITIONARY PIER | 2 |

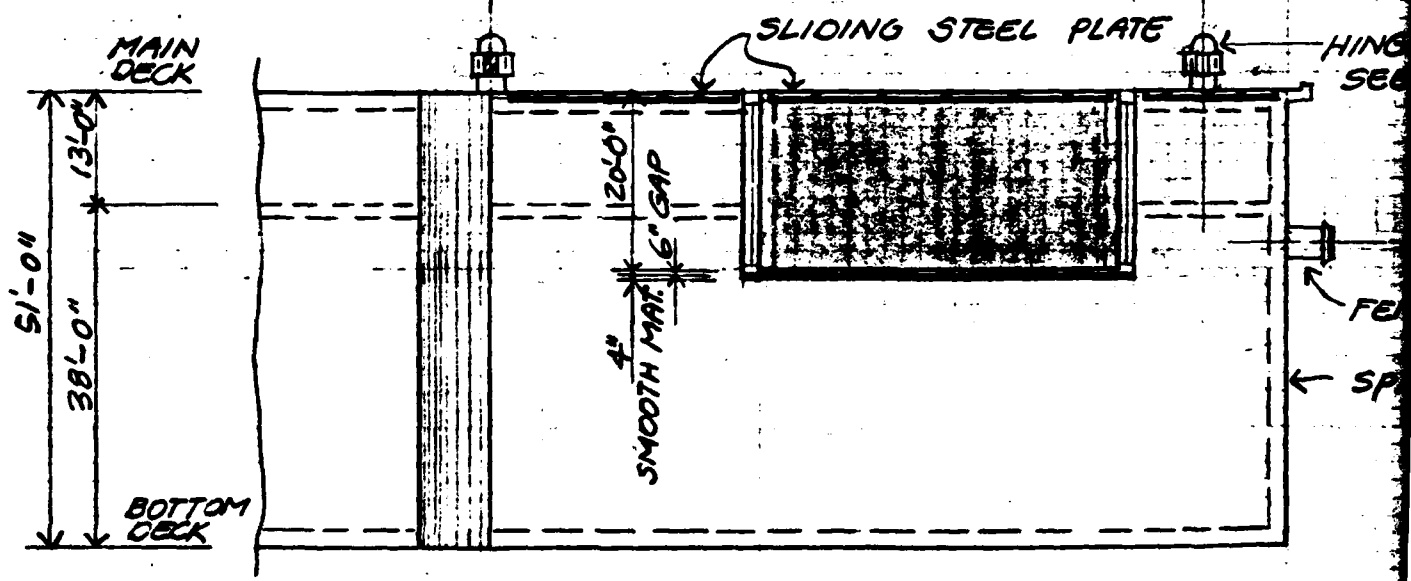
DRAFTING

DESIGN

PROJECT NO.



PLAN

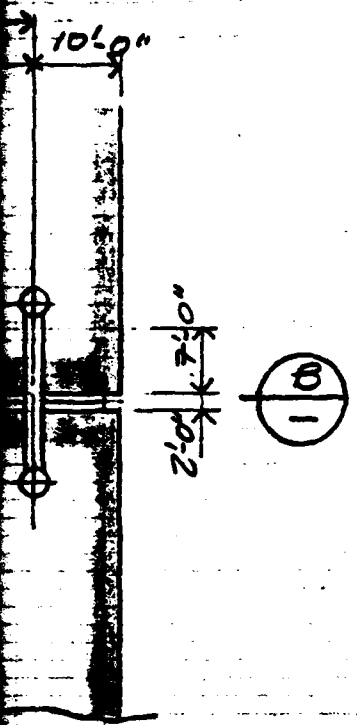


SECTION B
1" = 20'-0"

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HINGE CONNECTION
SEE DRWG 9

WATER
LINE

FENDER

← SPINE PIER

2

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| | | |

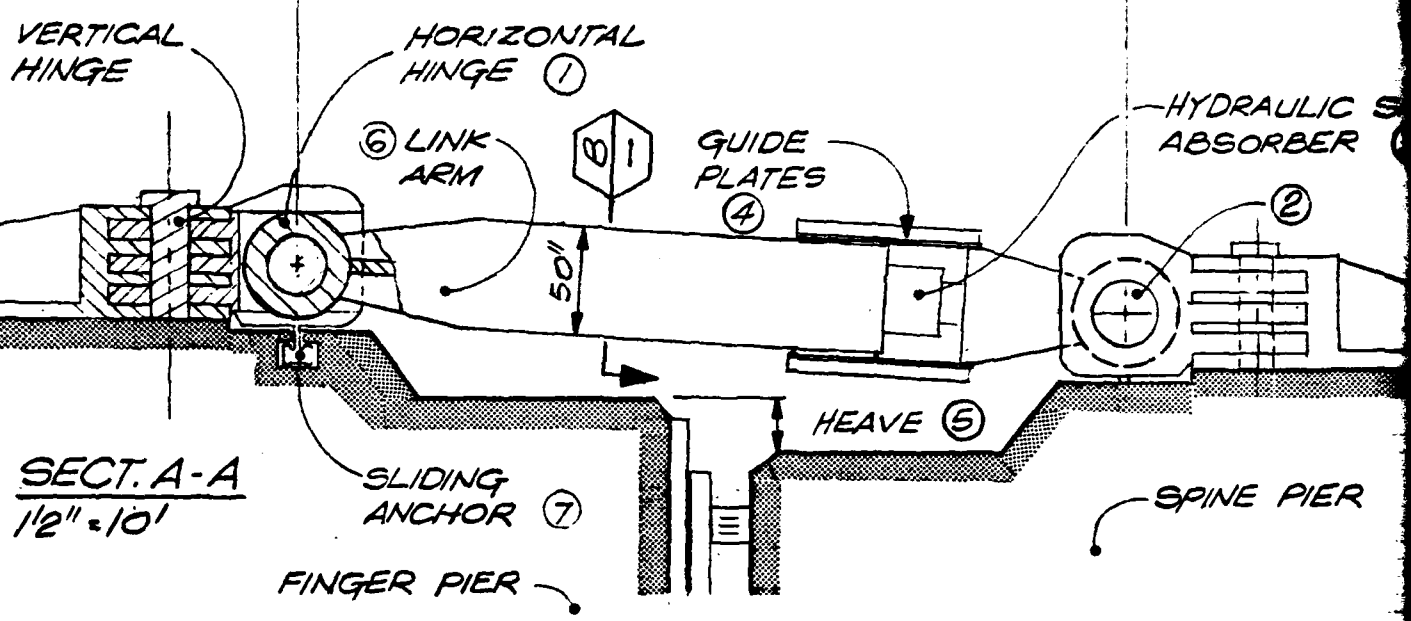
| Drawn For | Date | By |
|-----------|---------|----|
| | Jan. 63 | RM |
| | | |

SHEET TITLE: SPINE PIER DETAILS
PROJECT: EXPEDITIONARY PIER

SHEET NO
3

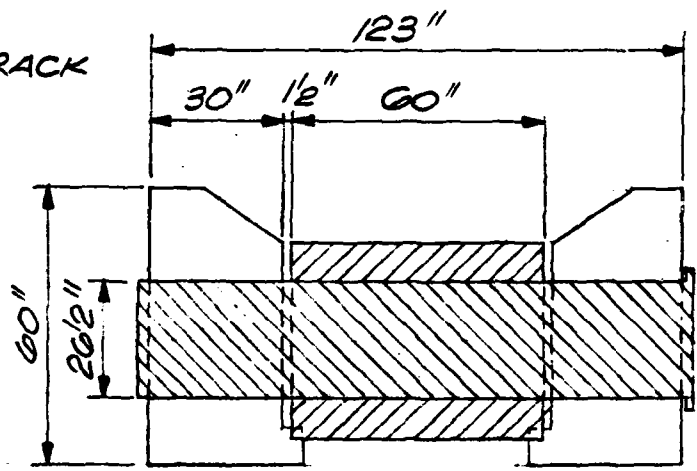
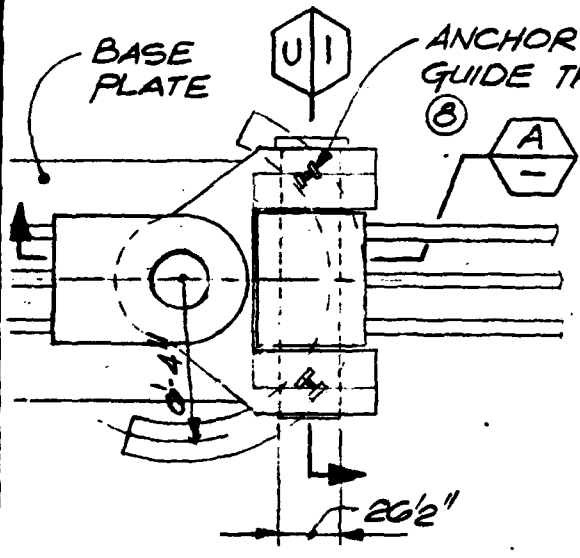
19-4

31'-0"



SECT. A-A
1/2" = 10'

ELEVATION
1/2" = 10'



SECT. C-C
1" = 4"

TOP VIEW
1/2" = 10'

DRAFTING

DESIGN

PROJECT NO.

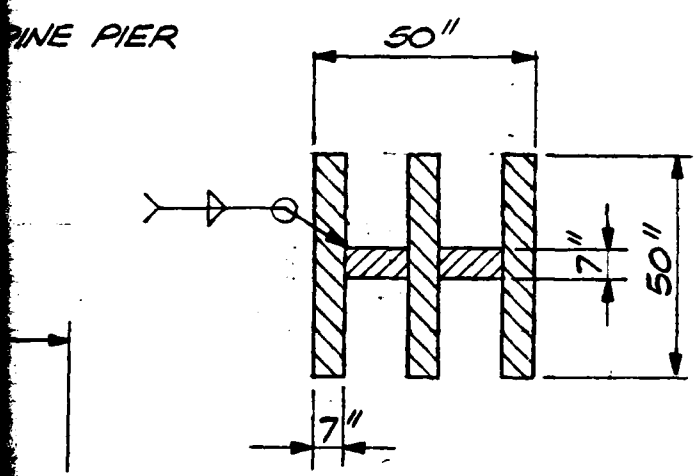
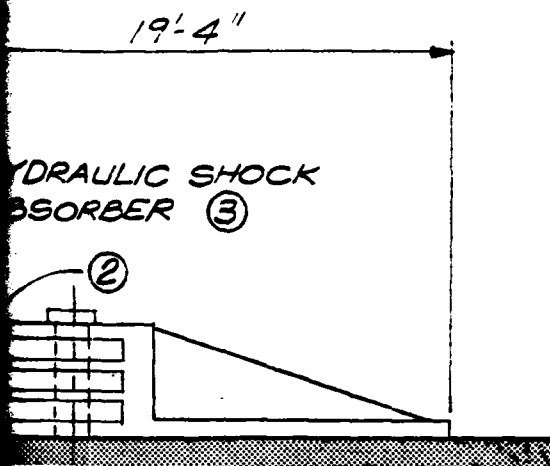
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NOTES

- ① COMPOSITE CENTERLEAF FOR EASY & QUICK ENGAGEMENT.
- ② HORIZONTAL HINGE @ SPINE PIER CAN HAVE "TOOTHED" CENTER LEAF TO REDUCE PIN SIZE.
- ③ CYLINDER 32 IN. O.D., STROKE 12 IN. TO 18 IN. OR CLUSTER OF 2 SMALLER (22 IN. O.D.) SHOCK ABSORBERS CAN BE USED.
- ④ GUIDE PLATES WITH STIFFENERS TO PREVENT MOMENTS DUE TO SELF WT. ON SHOCK ABSORBERS
- ⑤ MAX. HEAVE OF UP TO 5 FT. IS EXPECTED DURING OPERATION.
- ⑥ LINK ARM IS FLARED TO PROVIDE BETTER BULKING STABILITY FOR COMPRESSIVE LOADS. CAN BE DISENGAGED @ FINGER PIER HORIZONTAL HINGE AND STOWED @ THE SPINE PIER.
- ⑦ SLIDING ANCHOR CONSTRAINS HORIZONTAL HINGE IN VERTICAL DIRECTION.
- ⑧ ANCHOR GUIDE TRACK ALLOWS FREE ROTATION FOR VERTICAL HINGE.



SECT. B-B
1" = 40"

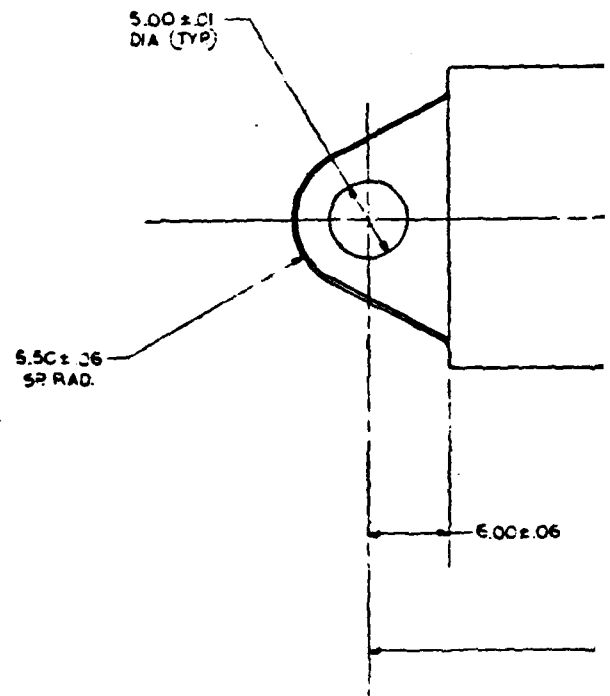
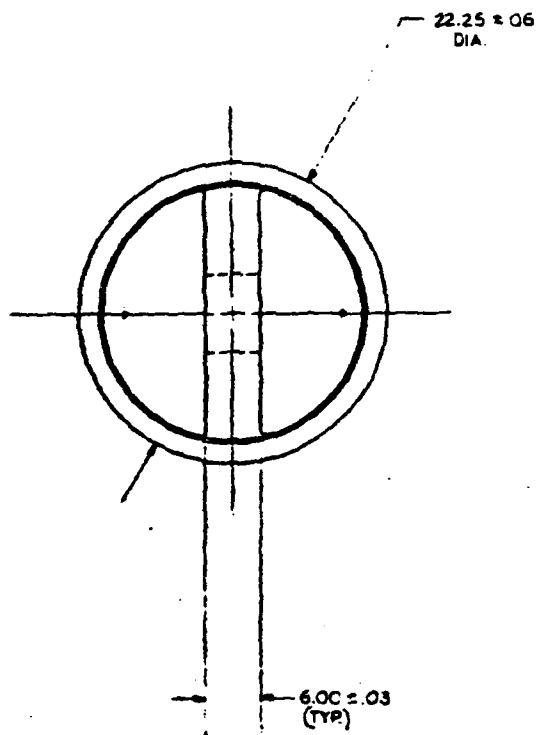
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| SHEET TITLE: | EXTENDABLE LINK |
| PROJECT: | FINGER/SPINE CONNECTION |

| |
|------------|
| SHEET NO. |
| 4 a |



SPECIFICATIONS:

- 1) DAMPING OUTPUT IN EXTENSION MODE TO BE 3000000 LB. (REF) AT 36 IN/SEC (NOM) VELOCITY.
- 2) NO APPRECIABLE DAMPING OUTPUT IN COMPRESSION MODE
- 3) DAMPING OUTPUT IN EXTENSION MODE TO BE INDEPENDANT OF STROKE POSITION AND TO VARY WITH THE IMPACT VELOCITY RAISED TO THE 7C REF POWER.
- 4) UNIT EXTENSION STROKE = 20.00 IN (NOM)
- 5) INTERNAL COIL SPRING RESET SYSTEM
- 6) TWO UNITS TO BE USED IN PARALLEL PER SYSTEM.

REPRODUCED BY PERMISSION 4/8/84.

8 9 COPY 12
8 9 SUBJECT
8 9 AND 12
TAYLOR COE
REPRODUCTIVE
MATTER 928

PROJECT NO _____
DESIGN _____
DRAFTING _____

PROJECT NO _____
DESIGN _____
DRAFTING _____

PROJECT NO _____
DESIGN _____
DRAFTING _____

785'

POINT OF R

RETRACTED POS
FOR TOWING

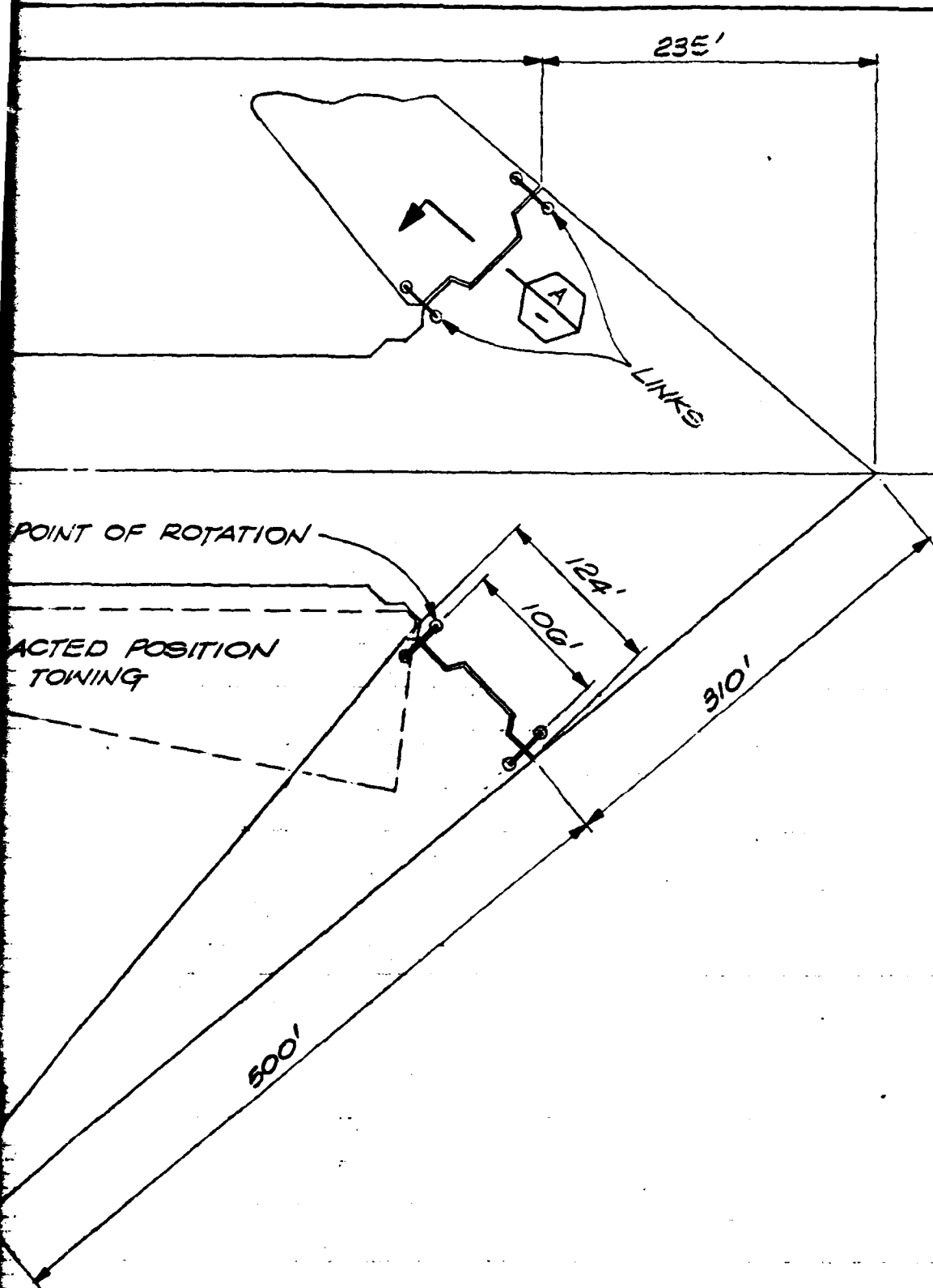
30'

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SHEET TITLE: REVISED FINGER PIER CONFIGURATION
PROJECT: FINGER/SPINE CONNECTION

SHEET NO. 6

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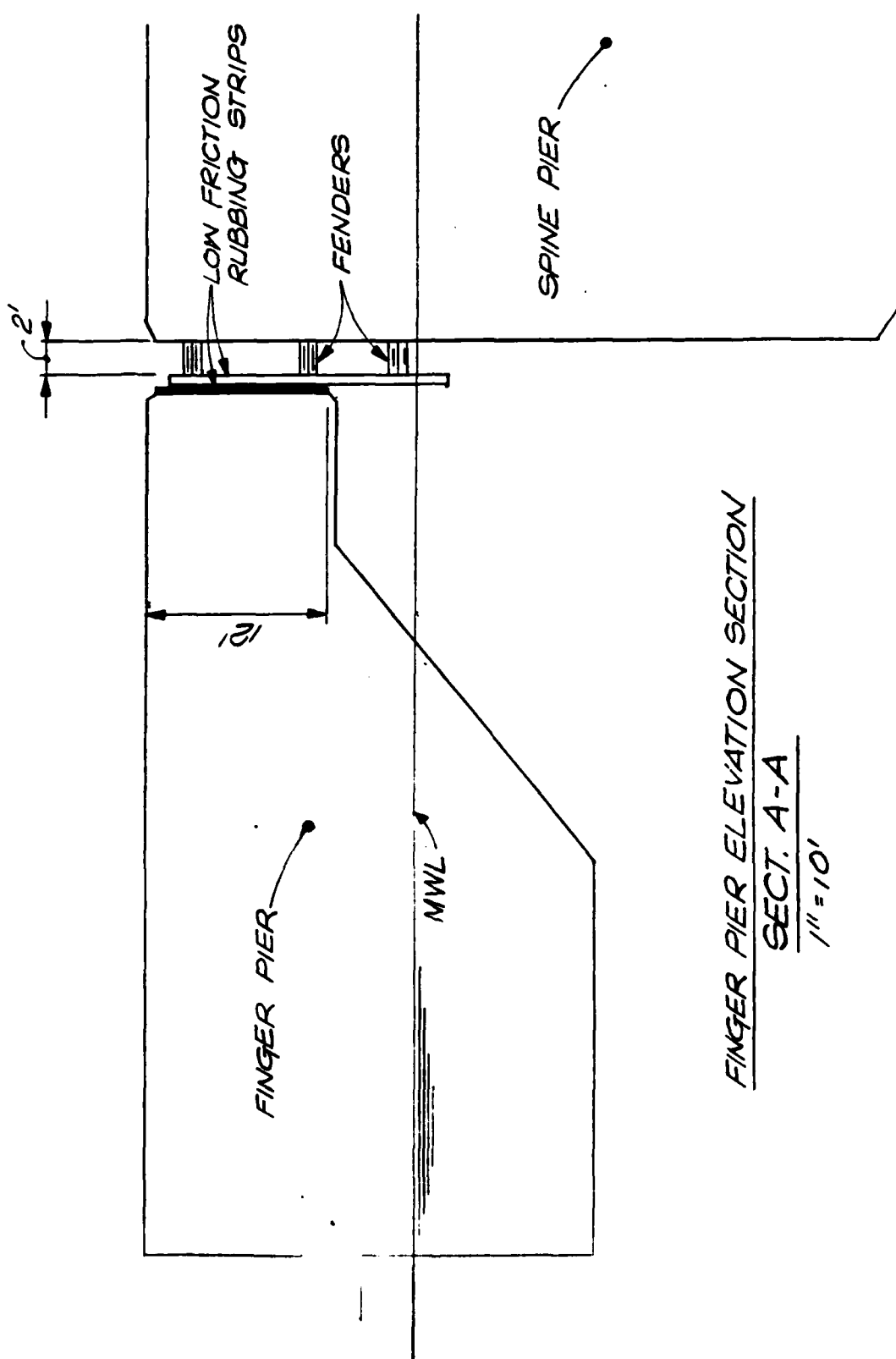
PROJECT: *NAVY PIER CONCEPTS*

ITEM: *FINGER/SPINE PIER CONN.*

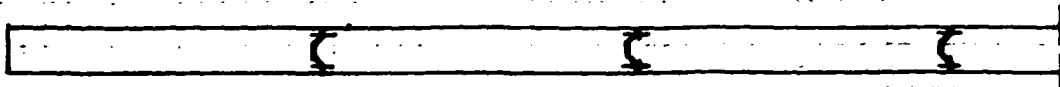
DESIGN: *FINGER PIER ELEV. SEC.*

DATE:

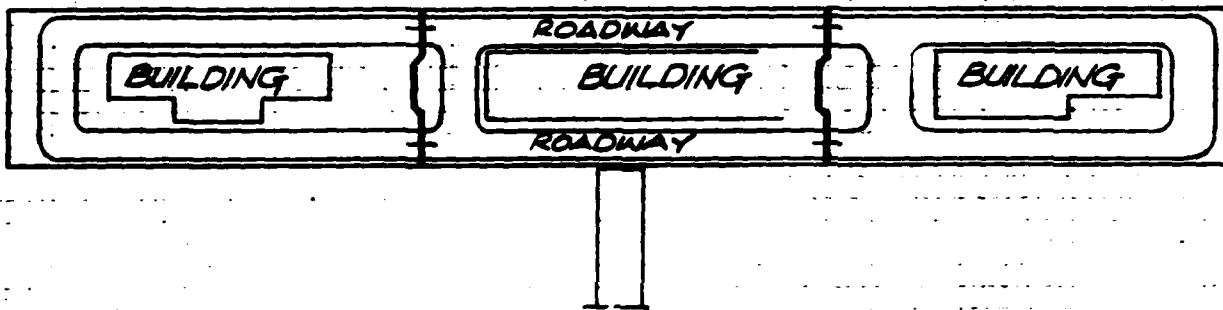
SHEET: *FIG. C*
OF _____
REVISIONS



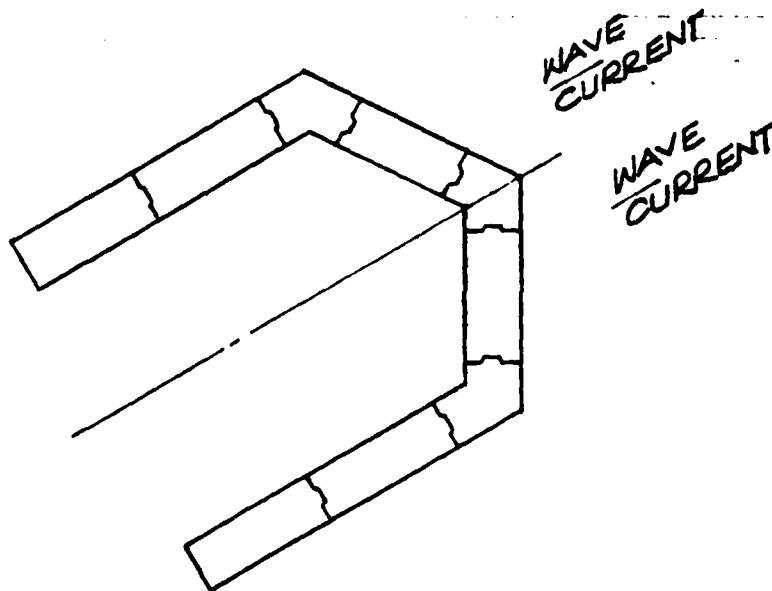
FINGER PIER ELEVATION SECTION
SECT. A-A
1" = 10'



(1) FLOATING ROADWAY TO OFFSHORE INSTALLATIONS



(2) FLOATING PLATFORM FOR OFFSHORE INSTALLATIONS



(3) FLOATING BREAKWATER FOR OFFSHORE HARBOR

SOME OTHER APPLICATIONS OF RETRACTABLE PIER

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PROJECT: *NAVY PIER CONCEPTS*
ITEM: *FINGER/SANE PIER CONN.*
DESIGN: *EFFECT OF INCREASED LINK*
DATE: *DISTANCE*

SHEET:
FIG. 8
OF _____
REVISIONS

