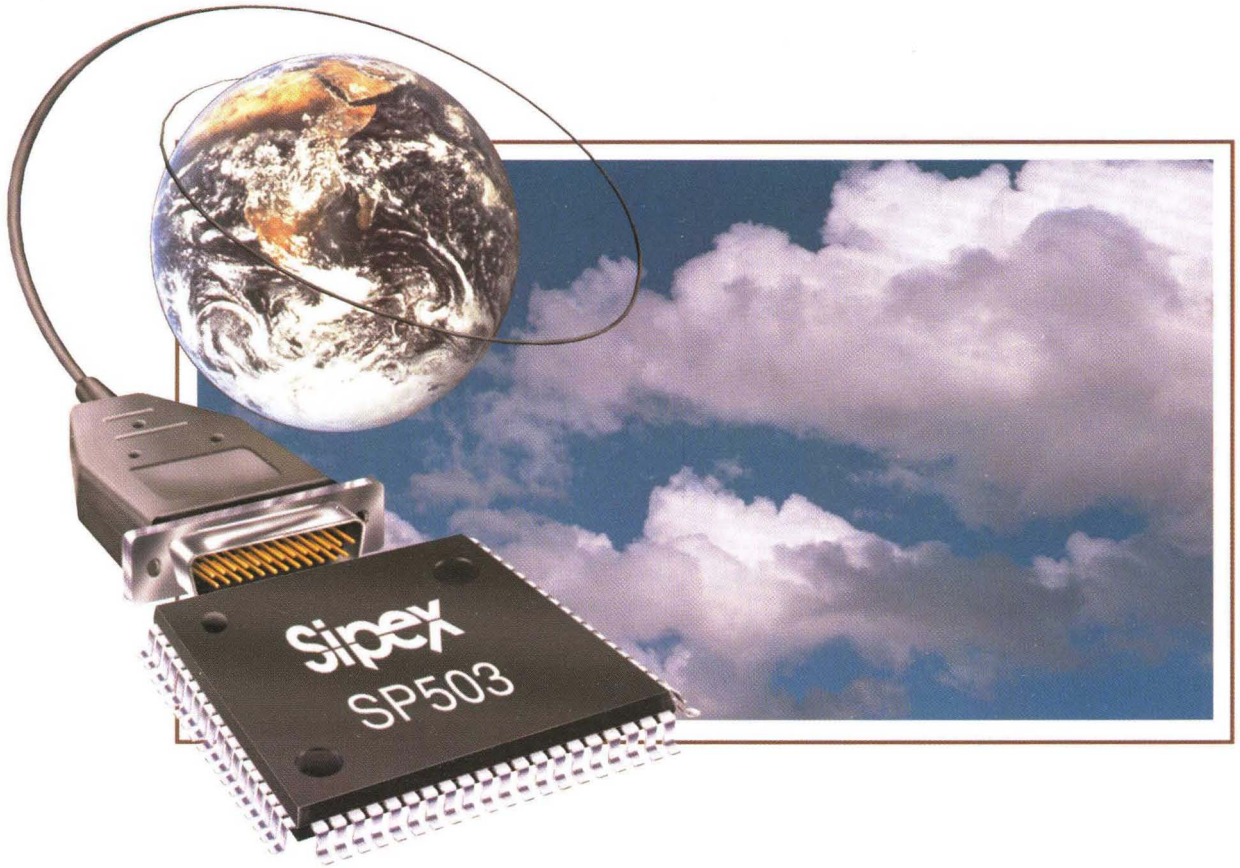


Catalog Supplement

# Interface Products Supplement



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<b>SP235B</b> ...	+5V Powered RS232 Drivers/Receivers (5 Drivers, 5 Receivers) .....	IPC
<b>SP236A</b> ...	+5V Powered RS232 Drivers/Receivers (4 Drivers, 3 Receivers) .....	IPC
<b>SP236B</b> ...	+5V Powered RS232 Drivers/Receivers (4 Drivers, 3 Receivers) .....	IPC
<b>SP237A</b> ...	+5V Powered RS232 Drivers/Receivers (5 Drivers, 3 Receivers) .....	IPC
<b>SP238A</b> ...	+5V Powered RS232 Drivers/Receivers (4 Drivers, 4 Receivers) .....	IPC
<b>SP239A</b> ...	+5V Powered RS232 Drivers/Receivers (3 Drivers, 5 Receivers) .....	IPC
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<b>SP241B</b> ...	+5V Powered RS232 Drivers/Receivers (4 Drivers, 5 Receivers) .....	IPC
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## INTERFACE PRODUCTS

## INTERFACE PRODUCT SELECTION TABLE

### +5V High-Speed RS-232 Transceivers with 0.1µF Capacitors

Model	No. Drivers	No. Receivers	Ext. Caps.	Shutdown (No.*)	Wakeup	TTL Tri-State	Page
SP200	5	0	4	Yes (0)	No	No	1
SP204	4	0	4	No	No	No	1
SP205	5	5	None	Yes(0)	No	Yes	1
SP205B	5	5	None	Yes (5)	Yes	Yes	1
SP206	4	3	4	Yes (0)	No	Yes	1
SP206B	4	3	4	Yes (3)	Yes	Yes	1
SP207	5	3	4	No	No	No	1
SP207B	5	3	4	Yes (3)	Yes	Yes	1
SP208	4	4	4	No	No	No	1
SP211	4	5	4	Yes (0)	No	Yes	1
SP211B	4	5	4	Yes (5)	Yes	Yes	1
SP213	4	5	4	Yes (2)	Yes	Yes	1

### +5V 400 kbps RS-232 Transceivers with 0.1µF Capacitors

Model	No. Drivers	No. Receivers	Ext. Caps.	Shutdown (No.*)	Wakeup	TTL Tri-State	Page
SP207H	5	3	4	No	No	No	17
SP207HB	5	3	4	Yes (3)	Yes	Yes	17
SP211H	4	5	4	Yes (0)	No	Yes	17
SP211HB	4	5	4	Yes (5)	Yes	Yes	17

### +5V/+12V Powered, Enhanced RS-232 Drivers/Receivers

Model	No. Drivers	No. Receivers	Ext. Caps.	Shutdown (No.*)	Wakeup	TTL Tri-State	Page
SP231A	2	2	2	No	No	No	IPC
SP239A	3	5	2	No	No	Yes	IPC

### +5V Powered, Enhanced RS-232 Drivers/Receivers

Model	No. Drivers	No. Receivers	Ext. Caps.	Shutdown (No.*)	Wakeup	TTL Tri-State	Page
SP232A	2	2	4	No	No	No	IPC
SP233A	2	2	None	No	No	No	IPC
SP310A	2	2	4	Yes (0)	No	No	IPC

### +5V Powered, Enhanced RS-232 Drivers/Receivers, with Receiver Enable, Shutdown and Wakeup

Model	No. Drivers	No. Receivers	Ext. Caps.	Shutdown (No.*)	Wakeup	TTL Tri-State	Page
SP241C	3	5	4	Yes (0)	Yes	Yes	IPC
SP312A	2	2	4	Yes (2)	Yes	Yes	IPC

### +5V Powered RS-232 Drivers/Receivers

Model	No. Drivers	No. Receivers	Ext. Caps.	Shutdown (No.*)	Wakeup	TTL Tri-State	Page
SP230A	5	0	4	Yes (0)	No	No	IPC
SP234A	4	0	4	No	No	No	IPC
SP235A	5	5	None	Yes (0)	No	Yes	IPC
SP235B	5	5	None	Yes (5)	Yes	Yes	IPC
SP236A	4	3	4	Yes (0)	No	Yes	IPC
SP236B	4	3	4	Yes (3)	Yes	Yes	IPC
SP237A	5	3	4	No	No	No	IPC
SP238A	4	4	4	No	No	No	IPC
SP240A	5	5	4	Yes (0)	No	Yes	IPC
SP240B	5	5	4	Yes (5)	Yes	Yes	IPC
SP241A	4	5	4	Yes (0)	No	Yes	IPC
SP241B	4	5	4	Yes (5)	Yes	Yes	IPC

### RS-232/RS-422 Line Drivers/Receivers

Model	No. RS-232 Ch.	No. RS-422 Ch.	Mode Select	Loopback Test	Page
SP301	2	2	Software	Yes	IPC
SP302	4	2	Software	Yes	IPC

### Enhanced RS-232/RS-422 Line Drivers/Receivers

Model	No. RS-232 Ch.	No. RS-422 Ch.	Mode Select	Loopback Test	Page
SP304	4	2	Software	Yes	IPC

\* Number of active receivers in Shutdown mode.

## INTERFACE PRODUCT SELECTION TABLE

### RS-232/AppleTalk™ Serial Transceiver

Model	No. RS-232 Drivers	No. RS-232 Receivers	Macintosh™ Port	Mode Select	Page
SP303	4	4	1	Software	IPC

### RS-422/RS423 Line Drivers/Receiver

Model	No. RS-232 Drivers	No. RS423 Ch.	Mode Select	Loopback Test	Page
SP306	2	2	Software	Yes	IPC

### V.35 Transceiver

Model	No. RS232 Drivers	No. RS-232 Receivers	No. V.35 Drivers	No. V.35 Receivers	TL Tri-State	Page
SP320	4	4	2	2	Yes	27

### +5V Powered RS-232/RS-485 Line Driver/Receiver

Model	No. RS-232 CH.	No. RS-485 Ch.	Mode Select	Loopback Test	Page
SP332	4	2	Software	Yes	39

### +5V Powered RS-232/AppleTalk™ Serial Transceivers

Model	No. RS-232 Drivers	No. RS-232 Receivers	Mode Select	Macintosh™ Port	Page
SP333	4	4	Software	1	49

### +3.3V Powered EIA562 Line Drivers/Receivers

Model	No. Drivers	No. Receivers	Shutdown (No.*)	WakeUp	TTL Tri-State	Page
SP341	3	5	Yes (0)	Yes	Yes	IPC

### RS485/RS422 Half-Duplex Interface Transceivers

Model	No. Drivers	No. Receivers	Shutdown (No.*)	Low Power	Low EMI	Driver Enable	Rcvr Enable	Page
SP481	1	1	Yes	Yes	No	Yes	Yes	61
SP483	1	1	Yes	Yes	Yes	Yes	Yes	61
SP485	1	1	No	Yes	No	Yes	Yes	61

### RS-485/RS-422 Line Drivers

Model	No. Drivers	Driver Enable	Page
SP486	4	Common	IPC
SP487	4	Independent	IPC

### RS-485/RS-422 Line Receivers

Model	No. Receivers	Receiver Enable	Page
SP488	4	Common	IPC
SP489	4	Dual Pair	IPC

### RS-485 Full-Duplex Interface Transceivers

Model	No. Drivers	No. Receivers	Shutdown	Low Power	Driver Enable	Rcvr Enable	Page
SP490	1	1	No	Yes	No	No	69
SP491	1	1	No	Yes	Yes	Yes	69

### RS-485/RS-422 Line Drivers/Receivers

Model	No. Drivers	No. Receivers	Driver Enable	Rcvr Enable	Page
SP495	4	4	Independent	Independent	77

### Multi-Protocol/Multi-Mode Serial Line Drivers/Receivers

Model	Protocols	Drivers	Receivers	Internal V.35 Terminator	Tri-State Control	Page
SP501	11	6	7	No	Driver	IPC
SP502	6	6	7	No	Driver	IPC
SP503	6	7	7	No	Driver	83
SP504	8	7	7	Yes	Driver/Receiver	125

### CMOS Asynchronous to Synchronous Converter

Model	Page
MAS7838	IPC

\* Number of active receivers in Shutdown mode.

## EIA STANDARDS

Specification	RS-232D	RS-423A	RS-422	RS-485	RS-562	
Mode of Operation	Single-Ended	Single-Ended	Differential	Differential	Single-Ended	
Number of Drivers and Receivers Allowed on One Line	1 Driver 1 Receiver	1 Driver 10 Receivers	1 Driver 10 Receivers	32 Drivers 32 Receivers	1 Driver 1 Receiver	
Maximum Cable Length	50 feet	4,000 feet	4,000 feet	4,000 feet	C≤2500pF @ ≤20kb/s C≤1000pF @ ≥20kb/s	
Maximum Data Rate	20kb/s	100kb/s	10Mb/s	10Mb/s	64kb/s	
Driver Output Maximum Voltage	±25V	±6V	-0.25V to +6V	-7V to +12V	-3.7 to +13.2V	
Driver Output Signal Level	Loaded	±5V	±3.6V	±2V	±1.5V	±3.7V
	Unloaded	±15V	±6V	±5V	±5V	±13.2V
Driver Load Impedance	3kΩ to 7kΩ	450Ω min.	100Ω	54Ω	3kΩ to 7kΩ	
Maximum Driver Output Current (High Impedance State)	Power On	— —	— —	— —	±100μA	— —
	Power Off	V <sub>MAX</sub> /300	100μA	±100μA	±100μA	— —
Slew Rate	30V/μs max.	Controls Provided	— —	— —	30V/μs max.	
Receiver Input Voltage Range	±15V	±12V	-7V to +7V	-7V to +12V	±15V	
Receiver Input Sensitivity	±3V	±200mV	±200mV	±200mV	±3V	
Receiver Input Resistance	3kΩ to 7kΩ	4kΩ min.	4kΩ min.	12kΩ min.	3kΩ to 7kΩ	



## SERIAL PROTOCOL REFERENCE TABLE

### Commonly-Used Data Communications Interfaces††

Signal Name	Source	RS-232		EIA-530		RS-449		EIA-561		EIA-574		V.35	
		Mnemonic	Pin	Mnemonic	Pin	Mnemonic	Pin	Mnemonic	Pin	Mnemonic	Pin	Mnemonic	Pin
Shield	—	—	1	—	1	—	1	—	—	—	—	—	A
Transmitted Data	DTE	BA	2	BA (A)	2	SD (A)	4	103	6	103	3	103	P
				BA (B)	14	SD (B)	22					103	S
Received Data	DCE	BB	3	BB (A)	3	RD (A)	6	104	5	104	2	104	R
				BB (B)	16	RD (B)	24					104	T
Request To Send	DTE	CA	4	CA (A)	4	RS (A)	7	105/133†	8	105/133†	7	105	C
				CA (B)	19	RS (B)	25					105	
Clear To Send	DCE	CB	5	CB (A)	5	CS (A)	9	106	7	106	8	106	D
				CB (B)	13	CS (B)	27					106	
DCE Ready (DSR)	DCE	CC	6	CC (A)	6	DM (A)	11	—	—	107	6	107	E
				CC (B)	22	DM (B)	29					107	
DTE Ready (DTR)	DTE	CD	20	CD (A)	20	TR (A)	12	108	3	108	4	108	H*
				CD (B)	23	TR (B)	30					108	
Signal Ground	—	AB	7	AB	7	SG	19	102	4	102	5	102	B
Recv. Line Sig. Det. (DCD)	DCE	CF	8	CF (A)	8	RR (A)	13	109	2	109	1	109	F
				CF (B)	10	RR (B)	31					109	
Trans. Sig. Elemt. Timing	DCE	DB	15	DB (A)	15	ST (A)	5	—	—	—	—	114	Y
				DB (B)	12	ST (B)	23					114	AA
Recv. Sig. Elemt. Timing	DCE	DD	17	DD (A)	17	RT (A)	8	—	—	—	—	115	V
				DD (B)	9	RT (B)	26					115	X
Local Loopback	DTE	LL	18	LL	18	LL	10	—	—	—	—	141	L*
Remote Loopback	DTE	RL	21	RL	21	RL	14	—	—	—	—	140	N*
Ring Indicator	DCE	CE	22	—	—	—	—	125	1	125	9	125	J*
Trans. Sig. Elemt. Timing	DTE	DA	24	DA (A)	24	TT (A)	17	—	—	—	—	113	U*
				DA (B)	11	TT (B)	35					113	W*
Test Mode	DCE	TM	25	TM	25	TM	18	—	—	—	—	142	NN*

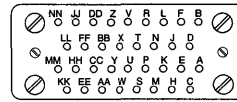
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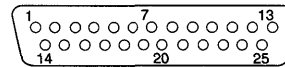
\* Pins are specified in ISO 2593 but are not included in CCITT v.35

† When hardware flow control is required, Circuit 105 may take on the functionality of Circuit 133.

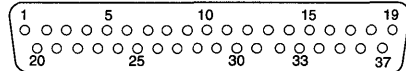
†† Some less-commonly used signals are not shown. METACOMP and SIPEX make no representation as to the accuracy or reliability of the information provided herein.



**V.35/ISO-2593 Connector**  
 DTE Connector Face — 34 Pin Male

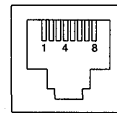


**RS-232 & EIA-530 Connector**  
 DTE Connector Face — DB-25 Pin Male

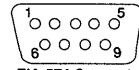


**RS-449 Connector**  
 DTE Connector Face — DB-37 Pin Male

Interchange Voltage States		
Notation	Negative	Positive
Binary State	1	0
Signal Condition	Marking	Spacing
Function	Off	On



**EIA-561 Connector**  
 Equip. Connector Face  
 RJ-45 8 Pin Female

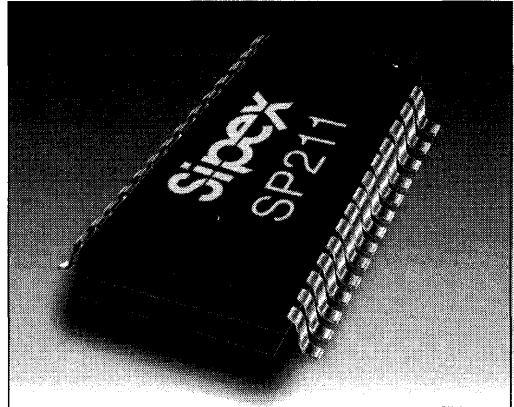


**EIA-574 Connector**  
 DTE Connector Face  
 DB-9 Pin Male

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**+5V High-Speed RS-232 Transceivers with 0.1µF Capacitors**

- 0.1µF External Charge Pump Capacitors
- 120Kbps Data Rate
- Standard SOIC and SSOP Packages
- Multiple Drivers and Receivers
- Single 5V Supply Operation
- 1µA Shutdown Mode
- WakeUp Feature in Shutdown Mode
- Tri-State Receiver Outputs
- Meets All RS-232 and V.28 Specifications
- Improved Driver Output Capacity for Mouse Applications
- ±10KV ESD Protection\*



**DESCRIPTION...**

The **SP200 Series** are multi-channel RS-232 line transceivers in a variety of configurations to fit most communication needs. All models in this Series feature low-power CMOS construction and Sipex-patented (5,306,954) on-board charge pump circuitry to generate the ±10V RS-232 voltage levels, using 0.1µF charge pump capacitors to save board space and reduce circuit cost. The **SP200, SP205, SP206, SP207B, SP211** and **SP213** models feature a low-power shutdown mode, which reduces power supply drain to 1µA. A WakeUp function keeps the receivers active in the shutdown mode.

Model	Number of RS-232		No. of Receivers Active in Shutdown	No. of External 0.1µF Capacitors	Shutdown	WakeUp	TTL Tri-State
	Drivers	Receivers					
SP200	5	0	0	4	Yes	No	No
SP204	4	0	0	4	No	No	No
SP205	5	5	0	None	Yes	No	Yes
SP205B	5	5	5	None	Yes	Yes	Yes
SP206	4	3	0	4	Yes	No	Yes
SP206B	4	3	3	4	Yes	Yes	Yes
SP207	5	3	0	4	No	No	No
SP207B	5	3	3	4	Yes	Yes	Yes
SP208	4	4	0	4	No	No	No
SP211	4	5	0	4	Yes	No	Yes
SP211B	4	5	5	4	Yes	Yes	Yes
SP213	4	5	2	4	Yes	Yes	Yes

*Table 1. Model Selection Table*

*\*All driver outputs and receiver inputs characterized per MIL-STD-883C Method 3015.7*

## ABSOLUTE MAXIMUM RATINGS

These are stress ratings only and functional operation of the device at these or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

$V_{CC}$ .....	+6V	
$V^+$ .....	( $V_{CC} - 0.3V$ ) to +13.2V	
$V^-$ .....	13.2V	
Input Voltages		
$T_{IN}$ .....	-0.3V to ( $V_{CC} + 0.3V$ )	
$R_{IN}$ .....	$\pm 20V$	
Output Voltages		
$T_{OUT}$ .....	( $V^+$ , +0.3V) to ( $V^-$ , -0.3V)	
$R_{OUT}$ .....	-0.3V to ( $V_{CC} + 0.3V$ )	
Short Circuit Duration on $T_{OUT}$ .....		Continuous
Power Dissipation		
Plastic DIP .....	375mW	
(derate 7mW/°C above +70°C)		
Small Outline .....	375mW	
(derate 7mW/°C above +70°C)		

## SPECIFICATIONS

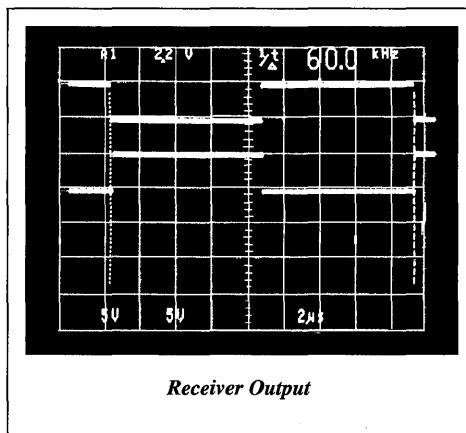
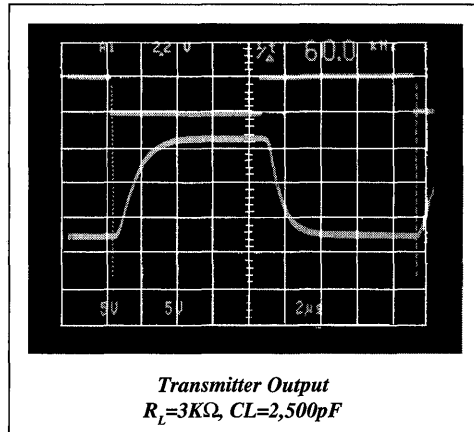
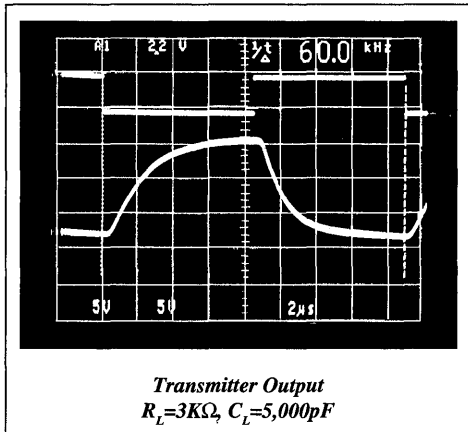
$V_{CC}$  at nominal ratings; 0.1 $\mu$ F charge pump capacitors;  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.

PARAMETER	MIN.	TYP.	MAX.	UNIT	CONDITIONS
<b>TTL INPUTS</b>					
Logic Threshold					$T_{IN}$ , EN, SD
$V_{IL}$	2.0		0.8	Volts	
$V_{IH}$				Volts	
Logic Pullup Current		15	200	$\mu$ A	$T_{IN} = 0V$
Data Rate			120	Kbps	$C_L = 2,500pF, R_L = 3K\Omega$
<b>TTL OUTPUTS</b>					
Compatibility		TTL/CMOS			
$V_{OL}$	3.5		0.4	Volts	$I_{OUT} = 3.2mA; V_{CC} = +5V$
$V_{OH}$				Volts	$I_{OUT} = -1.0mA$
Leakage Current		0.05	$\pm 10$	$\mu$ A	$EN = V_{CC}; 0V \leq R_{OUT} \leq V_{CC}; T_A = +25^\circ C$
<b>RS-232 OUTPUT</b>					
Output Voltage Swing	$\pm 5$	$\pm 7$		Volts	All transmitter outputs loaded with 3K $\Omega$ to ground
Output Resistance	300			Ohms	$V_{CC} = 0V; V_{OUT} = \pm 2V$
Output Short Circuit Current		$\pm 25$		mA	Infinite duration
<b>RS-232 INPUT</b>					
Voltage Range	-15		+15	Volts	
Voltage Threshold					
Low	0.8	1.2		Volts	$V_{CC} = 5V, T_A = +25^\circ C$
High		1.7	2.4	Volts	$V_{CC} = 5V, T_A = +25^\circ C$
Hysteresis	0.2	0.5	1.0	Volts	$V_{CC} = +5V$
Resistance	3	5	7	K $\Omega$	$\pm 15V; T_A = +25^\circ C$
<b>DYNAMIC CHARACTERISTICS</b>					
Propagation Delay		1.5		$\mu$ s	RS-232-to-TTL $C_L = 50pF, R_L = 3-7K\Omega;$ $T_A = +25^\circ C$ RS-232-to-RS-232 $C_L = 2,500pF, R_L = 3K\Omega;$ measured from +3V to -3V or -3V to +3V
Instantaneous Slew Rate			30	V/ $\mu$ s	
Transition Region Slew Rate		5		V/ $\mu$ s	
Output Enable Time		400		ns	
Output Disable Time		250		ns	

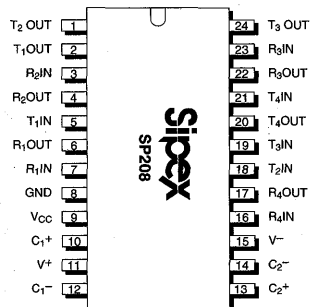
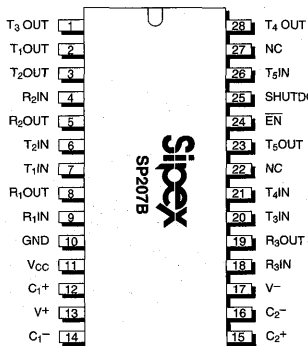
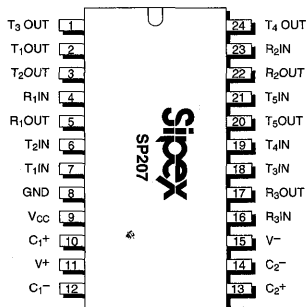
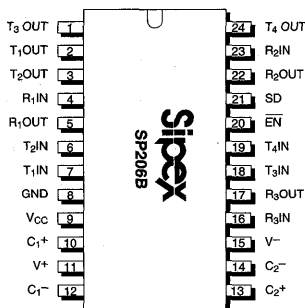
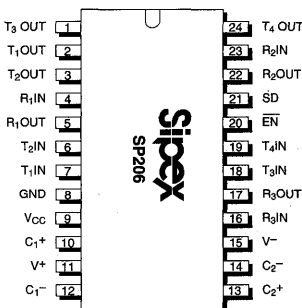
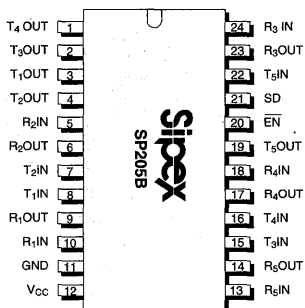
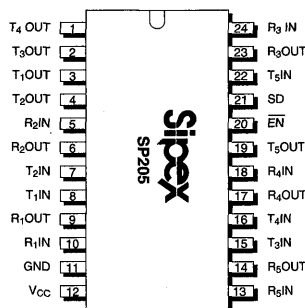
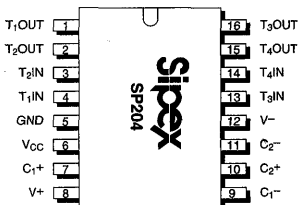
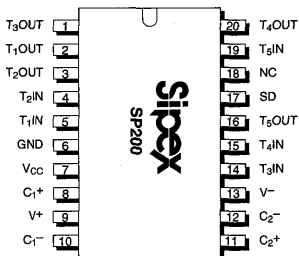
# SPECIFICATIONS

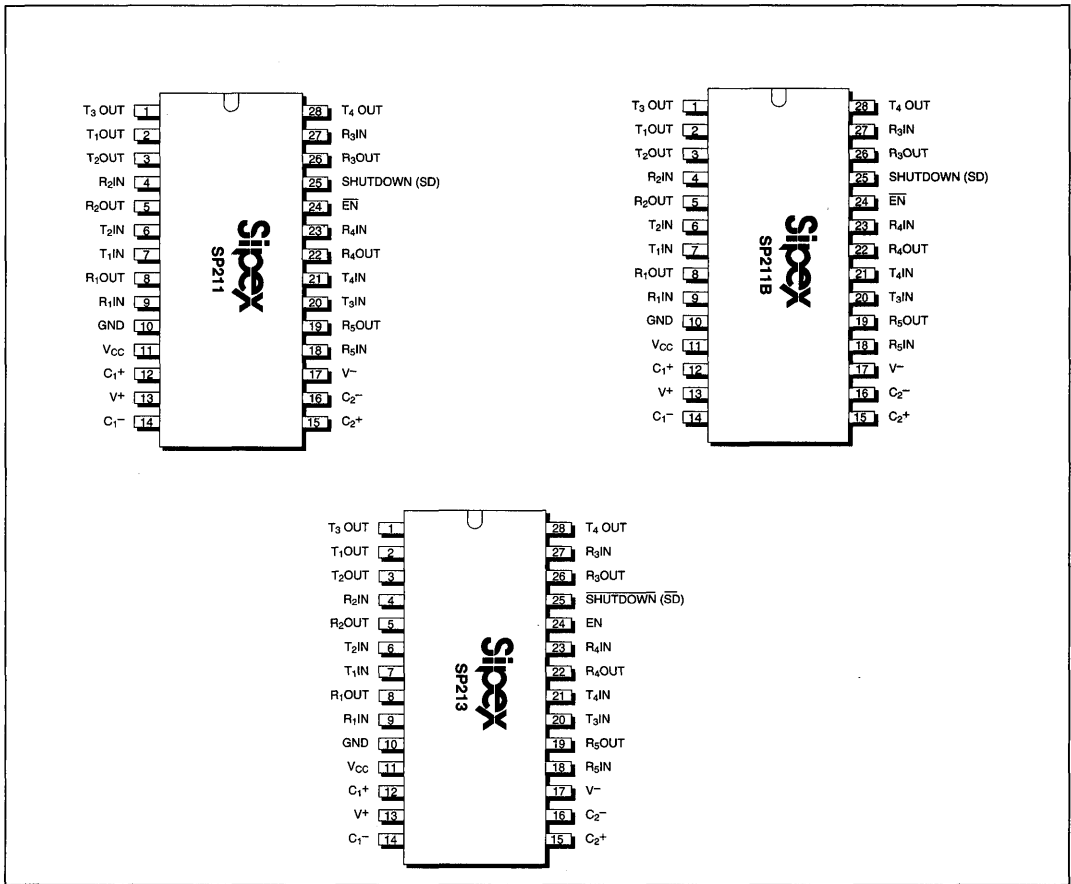
$V_{CC}$  at nominal ratings; 0.1  $\mu$ F charge pump capacitors;  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.

PARAMETER	MIN.	TYP.	MAX.	UNIT	CONDITIONS
<b>POWER REQUIREMENTS</b>					
$V_{CC}$ SP200, SP205, SP207 and SP207B	4.75	5.00	5.25	Volts	$T_A = +25^\circ\text{C}$ No load; $V_{CC} = \pm 10\%$ All transmitters $R_L = 3\text{K}\Omega$ $T_A = +25^\circ\text{C}$
All other parts	4.50	5.00	5.50	Volts	
$I_{CC}$		4	10	mA	
Shutdown Current		20	10	mA	
				$\mu\text{A}$	
<b>ENVIRONMENTAL AND MECHANICAL</b>					
Operating Temperature					
Commercial, -C	0		+70	$^\circ\text{C}$	
Extended, -E	-40		+85	$^\circ\text{C}$	
Storage Temperature	-65		+125	$^\circ\text{C}$	
Package					
-A	Shrink (SSOP) small outline				
-T	Wide (SOIC) small outline				



# PINOUT





**FEATURES...**

The **SP200 Series** multi-channel RS-232 line transceivers provide a variety of configurations to fit most communication needs, especially those applications where  $\pm 12V$  is not available. All models in this Series feature low-power CMOS construction and Sipex-proprietary on-board charge pump circuitry to generate the  $\pm 10V$  RS-232 voltage levels. The ability to use  $0.1\mu F$  charge pump capacitors saves board space and reduces circuit cost. Different models within the Series provide different driver/receiver combinations to match any application requirement.

The **SP200, SP205, SP206, SP207B, SP211** and **SP213** models feature a low-power shutdown mode, which reduces power supply drain to  $1\mu A$ . The WakeUp function keeps the receiv-

ers active in the shutdown mode, unless disabled by the EN pin. Models with -B suffix are equipped with the WakeUp function.

Models in the Series are available in 28-pin SO (wide) and SSOP (shrink) small outline packages. Devices can be specified for commercial ( $0^{\circ}C$  to  $+70^{\circ}C$ ) and industrial/extended ( $-40^{\circ}C$  to  $+85^{\circ}C$ ) operating temperatures.

**THEORY OF OPERATION**  
**Charge-Pump**

The charge pump is a Sipex-patented design (5,306,954) and uses a unique approach compared to older less-efficient designs. The charge pump still requires four external capacitors, but uses a four-phase voltage shifting technique to

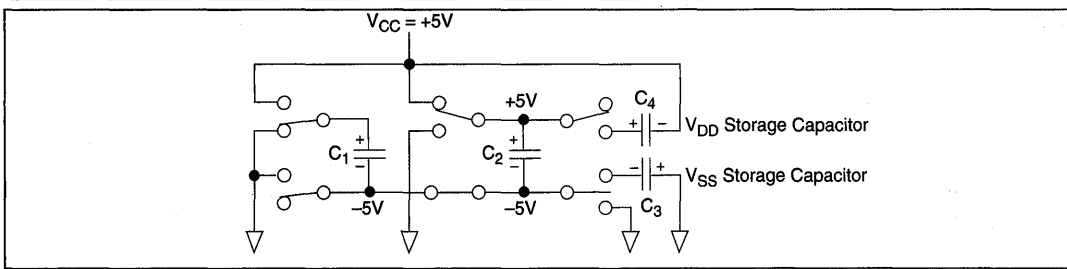


Figure 1. Charge Pump — Phase 1

attain symmetrical 10V power supplies. Figure 3a shows the waveform found on the positive side of capacitor  $C_2$ , and Figure 3b shows the negative side of capacitor  $C_2$ . There is a free-running oscillator that controls the four phases of the voltage shifting. A description of each phase follows.

### Phase 1

—  $V_{SS}$  charge storage — During this phase of the clock cycle, the positive side of capacitors  $C_1$  and  $C_2$  are initially charged to +5V.  $C_1^+$  is then switched to ground and the charge in  $C_1^-$  is transferred to  $C_2^-$ . Since  $C_2^+$  is connected to +5V, the voltage potential across capacitor  $C_2$  is now 10V.

### Phase 2

—  $V_{SS}$  transfer — Phase two of the clock connects the negative terminal of  $C_2$  to the  $V_{SS}$  storage capacitor and the positive terminal of  $C_2$  to ground, and transfers the generated -10V to  $C_3$ . Simultaneously, the positive side of capacitor  $C_1$  is switched to +5V and the negative side is connected to ground.

### Phase 3

—  $V_{DD}$  charge storage — The third phase of the clock is identical to the first phase — the charge

transferred in  $C_1$  produces -5V in the negative terminal of  $C_1$ , which is applied to the negative side of capacitor  $C_2$ . Since  $C_2^+$  is at +5V, the voltage potential across  $C_2$  is 10V.

### Phase 4

—  $V_{DD}$  transfer — The fourth phase of the clock connects the negative terminal of  $C_2$  to ground, and transfers the generated 10V across  $C_2$  to  $C_4$ , the  $V_{DD}$  storage capacitor. Again, simultaneously with this, the positive side of capacitor  $C_1$  is switched to +5V and the negative side is connected to ground, and the cycle begins again.

Since both  $V^+$  and  $V^-$  are separately generated from  $V_{CC}$ ; in a no-load condition  $V^+$  and  $V^-$  will be symmetrical. Older charge pump approaches that generate  $V^-$  from  $V^+$  will show a decrease in the magnitude of  $V^-$  compared to  $V^+$  due to the inherent inefficiencies in the design.

The clock rate for the charge pump typically operates at 15kHz. The external capacitors can be as low as 0.1 $\mu$ F with a 16V breakdown voltage rating.

The SP200 Series devices are made up of three basic circuit blocks — 1) transmitter/driver, 2) receiver and 3) the Sipex—proprietary charge

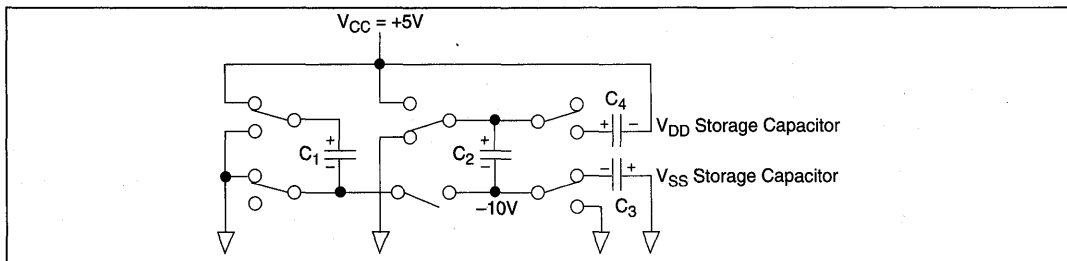


Figure 2. Charge Pump — Phase 2



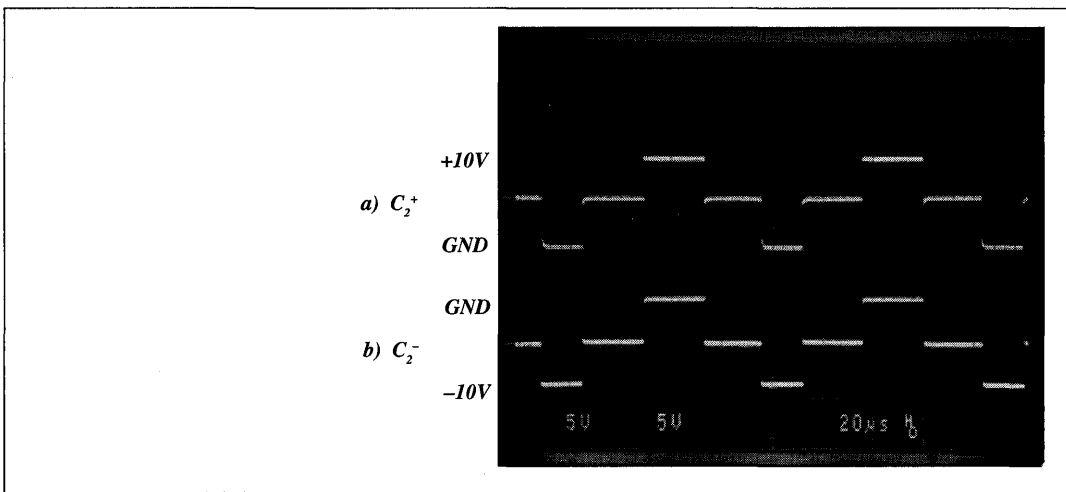


Figure 3. Charge Pump Waveforms

pump. Each model within the Series incorporates variations of these circuits to achieve the desired configuration and performance.

### Transmitter/Driver

The drivers are inverting transmitters, which accept either TTL or CMOS inputs and output the RS-232 signals with an inverted sense relative to the input logic levels. Typically, the RS-232 output voltage swing is  $\pm 9V$  with no load, and  $\pm 5V$  minimum with full load. The transmitter outputs are protected against infinite short-circuits to ground without degradation in reliability. The drivers of the SP200, SP205, SP205B, SP206, SP206B, SP207B, SP211, SP211B and SP213 can be tri-stated by using the SHUTDOWN function.

In the "power off" state, the output impedance will remain greater than 300 ohms, again satisfying the RS232 specifications. Should the input of the

driver be left open, an internal 400Kohm pullup resistor to  $V_{CC}$  forces the input high, thus committing the output to a low state. The slew rate of the transmitter output is internally limited to a maximum of  $30V/\mu s$  in order to meet the EIA standards (EIA RS-232D 2.1.7, Paragraph 5). The transition of the loaded output from high to low also meets the monotonicity requirements of the standard.

### Receivers

The receivers convert RS-232 input signals to inverted TTL signals. Since the input is usually from a transmission line where long cable lengths and system interference can degrade the signal, the inputs have a typical hysteresis margin of 500mV. This ensures that the receiver is virtually immune to noisy transmission lines. Should an input be left unconnected, a 5Kohm pulldown resistor to ground will commit the output of the receiver to a high state.

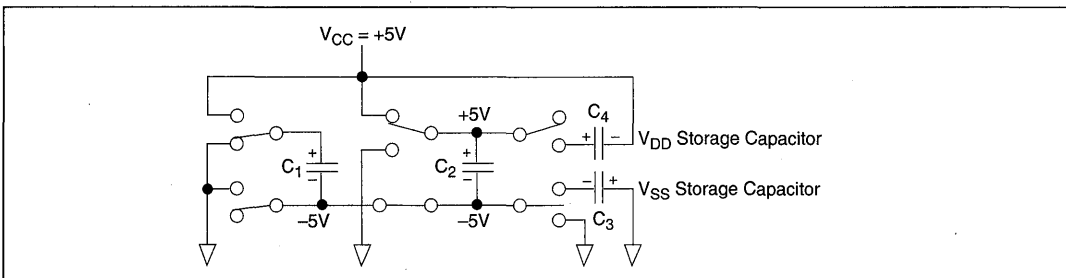


Figure 4. Charge Pump — Phase 3

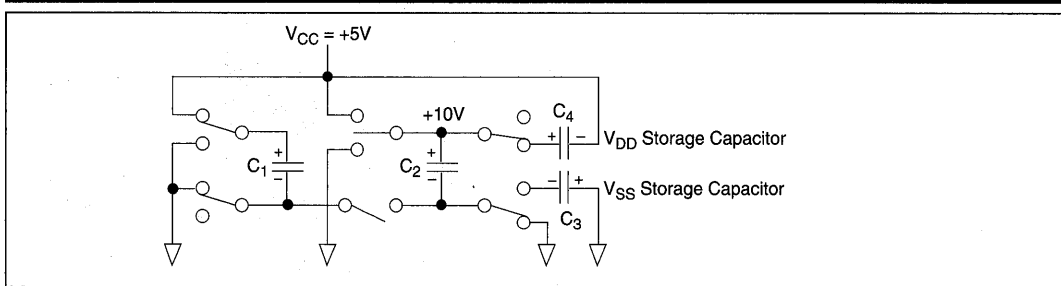


Figure 5. Charge Pump — Phase 4

## SHUTDOWN MODE

The **SP200**, **SP205**, **SP205B**, **SP206**, **SP206B**, **SP207B**, **SP211**, **SP211B** and **SP213** all feature a control input which will disable the device and reduce the power supply current to less than  $10\mu\text{A}$ , making the parts ideal for battery-powered systems. In the “shutdown” mode the receivers and transmitters will both be tri-stated. The  $V^+$  output of the charge pump will discharge to  $V_{CC}$ , and the  $V^-$  output will discharge to ground. Products with the WakeUp function can enable or disable the receivers during shutdown.

For complete shutdown to occur and the  $10\mu\text{A}$  power drain to be realized, the following conditions must be met:

### SP200, SP205/B, SP206/B, SP207B and SP211/B:

- +5V must be applied to the SD pin
- ENABLE must be either 0V, +5.0V or not connected
- the transmitter inputs must be either +5.0V or not connected
- $V_{CC}$  must be +5V
- Receiver inputs must be  $>0\text{V}$  and  $<+5\text{V}$

### SP213:

- 0V must be applied to the SD pin
- ENABLE must be either 0V, +5.0V or not connected
- the transmitter inputs must be either +5.0V or not connected
- $V_{CC}$  must be +5V
- Receiver inputs must be  $>0\text{V}$  and  $<+5\text{V}$

## ENABLE

The **SP205/B**, **SP206/B**, **SP207/B**, **SP211** and **SP213** all feature an enable input, which allows the receiver outputs to be either tri-stated or enabled. This can be especially useful when the receiver is tied directly to a microprocessor data bus. For the **SP205/B**, **SP206/B**, **SP207/B** and **SP211**, enable is active low; that is, 0V applied to the ENABLE pin will enable the receiver outputs. For the **SP213**, enable is active high; that is, +5V applied to the ENABLE pin will enable the receiver outputs.

## WAKEUP FUNCTION

The **SP205B**, **SP206B**, **SP207B**, **SP211B** and **SP213** have a wake-up feature that keeps two or more receivers in an enabled state when the device is in the shutdown mode. The **SP213** has two receivers active ( $R_4$  and  $R_5$ ), while the **SP205B**, **SP207B** and **SP211B** have all receivers active during shutdown. With only the receivers active during shutdown, the devices draw  $5\text{--}10\mu\text{A}$  of supply current.

SD	$\overline{\text{EN}}$	SP213 Only		Power Up/Down	Receiver Outputs
		SD	EN		
0	0	1	1	Up	Enable
0	1	1	0	Up	Tri-state
1	0	0	1	Down	Enable
1	1	0	0	Down	Tri-state

Table 2. Wake-Up Truth Table

A typical application of this function would be where a modem is interfaced to a computer in a power-down mode. The ring indicator signal from the modem could be passed through an active receiver in the **SP2XXB/SP213** that is itself in the shutdown mode. The ring indicator signal would propagate through the **SP2XXB/SP213** to the power management circuitry of the

computer to power up the microprocessor and the **SP2XXB/SP213** drivers. After the supply voltage to the **SP2XXB/SP213** reaches +5.0V, the SHUTDOWN pin can be disabled, taking the **SP2XXB/SP213** out of the shutdown mode.

All receivers that are active during shutdown maintain 500mV (typ.) of hysteresis.

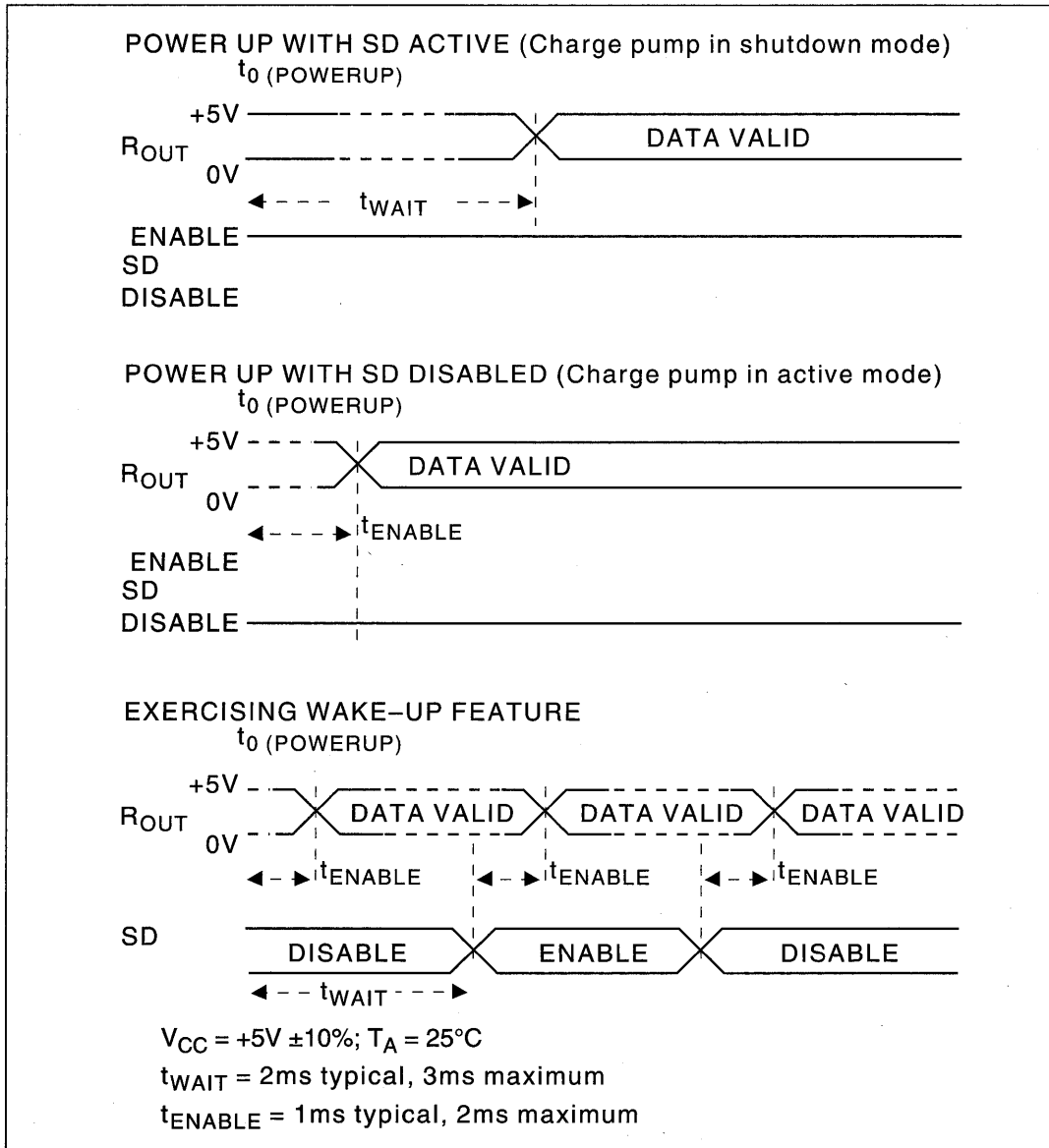


Figure 6. Wake-Up Timing

Specification	RS-232D	RS-423A	RS-422	RS-485	RS-562
Mode of Operation	Single-Ended	Single-Ended	Differential	Differential	Single-Ended
No. of Drivers and Receivers Allowed on One Line	1 Driver 1 Receiver	1 Driver 10 Receivers	1 Driver 10 Receivers	32 Drivers 32 Receivers	1 Driver 1 Receiver
Maximum Cable Length	50 feet	4,000 feet	4,000 feet	4,000 feet	C ≤ 2,500pF @ <20Kbps; C ≤ 1,000pF @ >20Kbps
Maximum Data Rate	20Kb/s	100Kb/s	10Mb/s	10Mb/s	64Kb/s
Driver output Maximum Voltage	±25V	±6V	-0.25V to +6V	-7V to +12V	-3.7V to +13.2V
Driver Output Signal Level Loaded Unloaded	±5V ±15V	±3.6V ±6V	±2V ±5V	±1.5V ±5V	±3.7V ±13.2V
Driver Load Impedance	3 – 7Kohm	450 ohm	100 ohm	54 ohm	3–7Kohm
Max. Driver Output Current (High Impedance State) Power On Power Off	$V_{MAX}/300$	100μA	±100μA	±100μA ±100μA	
Slew Rate	30V/μs max.	Controls Provided			30V/μs max.
Receiver Input Voltage Range	±15V	±12V	-7V to +7V	-7V to +12V	±15V
Receiver Input Sensitivity	±3V	±200mV	±200mV	±200mV	±3V
Receiver Input Resistance	3–7Kohm	4Kohm min.	4Kohm min.	12Kohm min.	3–7Kohm

Table 3. EIA Standard Definitions

## EIA STANDARDS

The Electronic Industry Association (EIA) developed several standards of data transmission which are revised and updated in order to meet the requirements of the industry. In data processing, there are two basic means of communicating between systems and components. The RS-232 standard was first introduced in 1962 and, since that time, has become an industry standard.

The RS-232 is a relatively slow data exchange protocol, with a maximum baud rate of only 20Kbaud, which can be transmitted over a maximum copper wire cable length of 50 feet. The **SP200** through **SP213** Series of data communications interface products have been designed

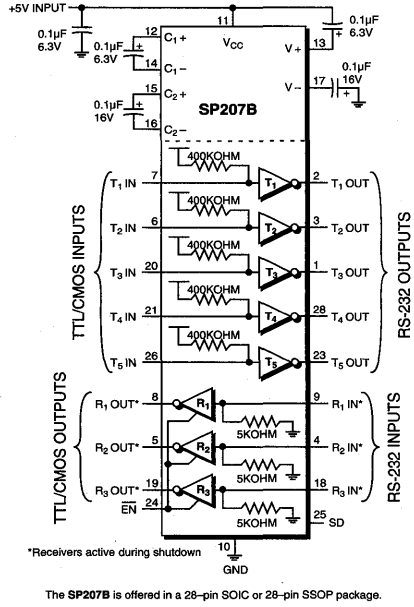
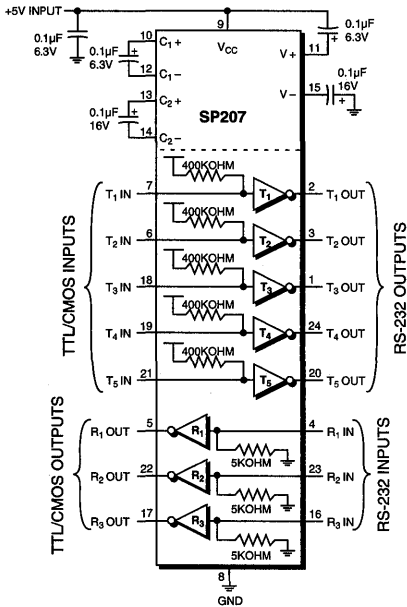
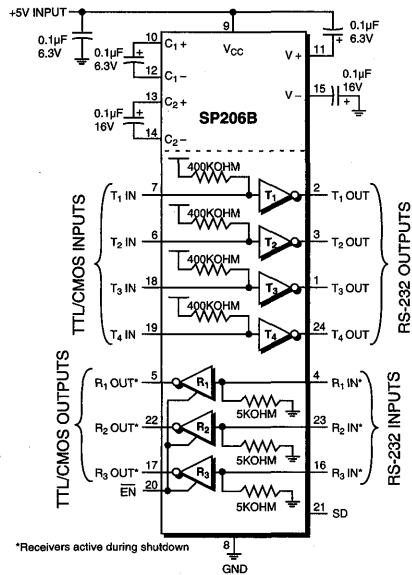
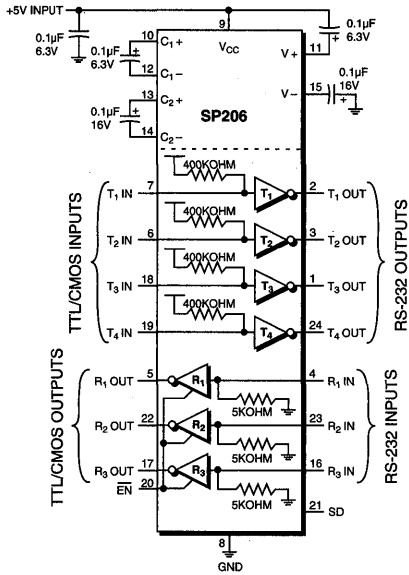
to meet both the EIA protocol standards, and the needs of the industry.

## ±10KV ESD PROTECTION

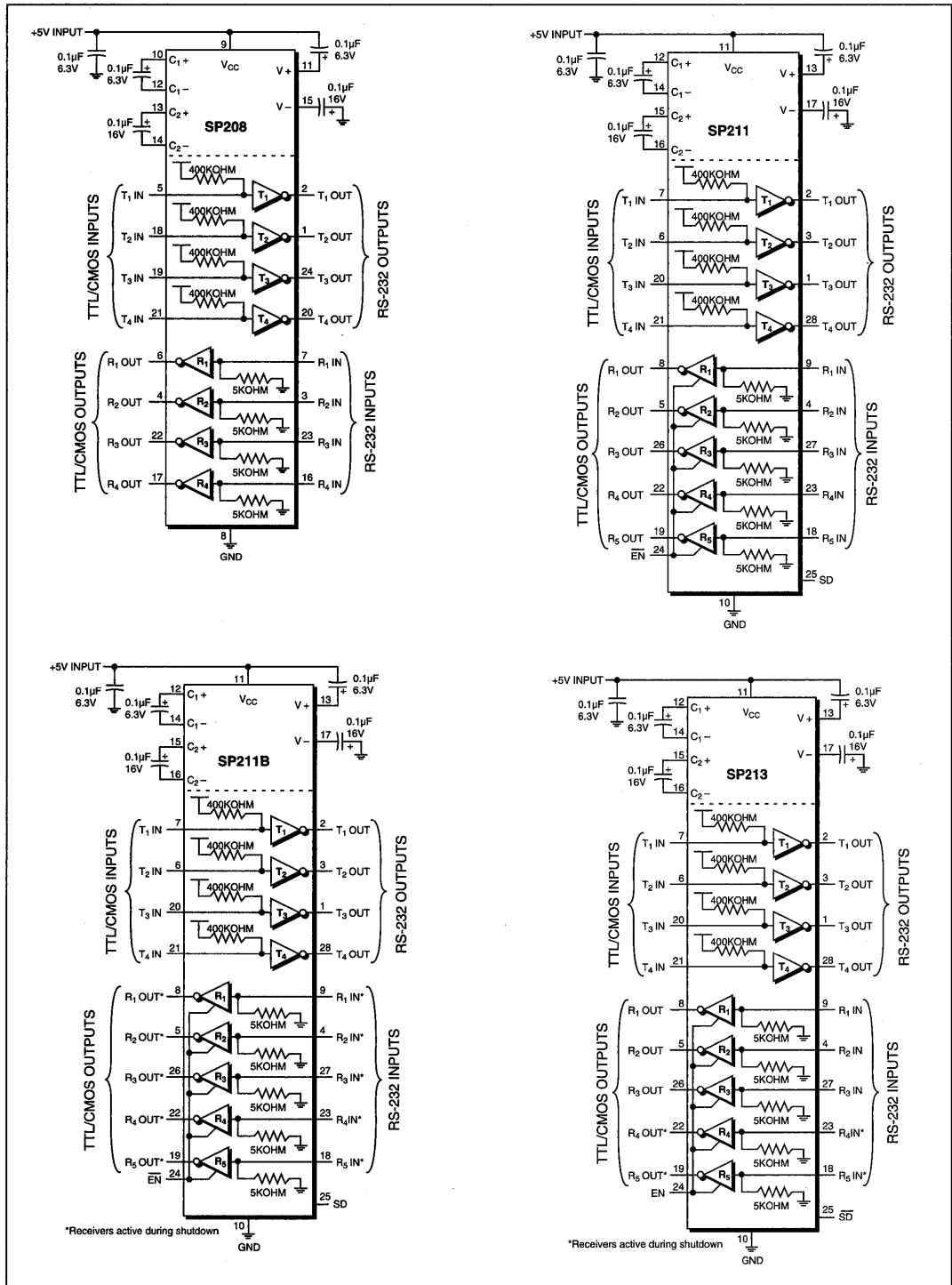
The **SP200** Series is equipped with **Sipex**-proprietary ESD protection circuitry on all RS-232 inputs and outputs. The **SP200** Series has been characterized using MIL-STD-883C Method 3015.7 Human Body Model. Each device in the family can withstand up to ±10KV of static discharge on all RS-232 inputs and outputs. All other pins of each device will maintain ≥ ±2KV of ESD protection.



# TYPICAL APPLICATION CIRCUITS



# TYPICAL APPLICATION CIRCUITS



## ORDERING INFORMATION

### RS-232 Transceivers:

Model	Drivers	Receivers	Temperature Range	Package Type
SP207CA	5	3	0°C to +70°C	24-pin SSOP
SP207CP	5	3	0°C to +70°C	24-pin Plastic DIP
SP207CT	5	3	0°C to +70°C	24-pin SOIC
SP207EA	5	3	-40°C to +85°C	24-pin SSOP
SP207EP	5	3	-40°C to +85°C	24-pin Plastic DIP
SP207ET	5	3	-40°C to +85°C	24-pin SOIC
SP208CA	4	4	0°C to +70°C	24-pin SSOP
SP208CP	4	4	0°C to +70°C	24-pin Plastic DIP
SP208CT	4	4	0°C to +70°C	24-pin SOIC
SP208EA	4	4	-40°C to +85°C	24-pin SSOP
SP208EP	4	4	-40°C to +85°C	24-pin Plastic DIP
SP208ET	4	4	-40°C to +85°C	24-pin SOIC

### RS-232 Transmitters:

Model	Drivers	Receivers	Temperature Range	Package Type
SP204CP	4	0	0°C to +70°C	16-pin Plastic DIP
SP204CT	4	0	0°C to +70°C	16-pin SOIC
SP204EP	4	0	-40°C to +85°C	16-pin Plastic DIP
SP204ET	4	0	-40°C to +85°C	16-pin SOIC

### RS-232 Transmitters with Low-Power Shutdown:

Model	Drivers	Receivers	Temperature Range	Package Type
SP200CP	5	0	0°C to +70°C	20-pin Plastic DIP
SP200CT	5	0	0°C to +70°C	20-pin SOIC
SP200EP	5	0	-40°C to +85°C	20-pin Plastic DIP
SP200ET	5	0	-40°C to +85°C	20-pin SOIC

### RS-232 Transceivers with Low-Power Shutdown and Tri-state Enable:

Model	Drivers	Receivers	Temperature Range	Package Type
SP205CP	5	5	0°C to +70°C	24-pin Plastic Double-Width DIP
SP205EP	5	5	-40°C to +85°C	24-pin Plastic Double-Width DIP
SP206CA	4	3	0°C to +70°C	24-pin SSOP
SP206CP	4	3	0°C to +70°C	24-pin Plastic DIP
SP206CT	4	3	0°C to +70°C	24-pin SOIC
SP206EA	4	3	-40°C to +85°C	24-pin SSOP
SP206EP	4	3	-40°C to +85°C	24-pin Plastic DIP
SP206ET	4	3	-40°C to +85°C	24-pin SOIC
SP211CA	4	5	0°C to +70°C	28-pin SSOP
SP211CT	4	5	0°C to +70°C	28-pin SOIC
SP211EA	4	5	-40°C to +85°C	28-pin SSOP
SP211ET	4	5	-40°C to +85°C	28-pin SOIC



## ORDERING INFORMATION

### RS-232 Transceivers with Low-Power Shutdown, Tri-state Enable, and Wake-Up Function:

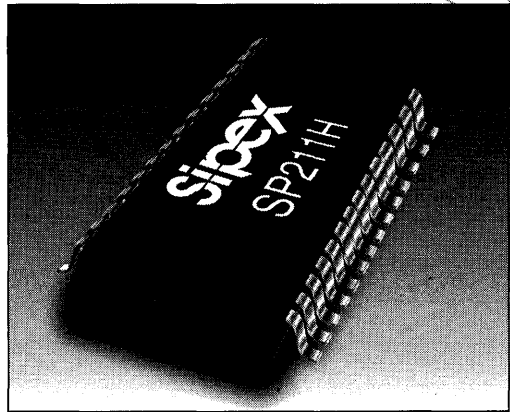
Model	Drivers	Receivers	Temperature Range	Package Type
SP205BCP	5	5, with 5 active in Shutdown	0°C to +70°C	24-pin Plastic Double-Width DIP
SP205BEP	5	5, with 5 active in Shutdown	-40°C to +85°C	24-pin Plastic Double-Width DIP
SP206BCA	4	3, with 3 active in Shutdown	0°C to +70°C	24-pin SSOP
SP206BCP	4	3, with 3 active in Shutdown	0°C to +70°C	24-pin Plastic DIP
SP206BCT	4	3, with 3 active in Shutdown	0°C to +70°C	24-pin SOIC
SP206BEA	4	3, with 3 active in Shutdown	-40°C to +85°C	24-pin SSOP
SP206BEP	4	3, with 3 active in Shutdown	-40°C to +85°C	24-pin Plastic DIP
SP206BET	4	3, with 3 active in Shutdown	-40°C to +85°C	24-pin SOIC
SP207BCA	5	3, with 3 active in Shutdown	0°C to +70°C	28-pin SSOP
SP207BCT	5	3, with 3 active in Shutdown	0°C to +70°C	28-pin SOIC
SP207BEA	5	3, with 3 active in Shutdown	-40°C to +85°C	28-pin SSOP
SP207BET	5	3, with 3 active in Shutdown	-40°C to +85°C	28-pin SOIC
SP211BCA	4	5, with 5 active in Shutdown	0°C to +70°C	28-pin SSOP
SP211BCT	4	5, with 5 active in Shutdown	0°C to +70°C	28-pin SOIC
SP211BEA	4	5, with 5 active in Shutdown	-40°C to +85°C	28-pin SSOP
SP211BET	4	5, with 5 active in Shutdown	-40°C to +85°C	28-pin SOIC
SP213CA	4	5, with 2 active in Shutdown	0°C to +70°C	28-pin SSOP
SP213CT	4	5, with 2 active in Shutdown	0°C to +70°C	28-pin SOIC
SP213EA	4	5, with 2 active in Shutdown	-40°C to +85°C	28-pin SSOP
SP213ET	4	5, with 2 active in Shutdown	-40°C to +85°C	28-pin SOIC

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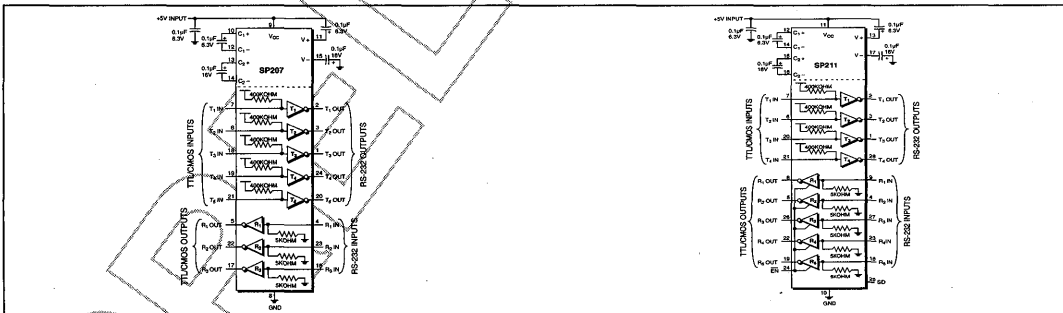
**+5V 400 kbps RS-232 Transceivers**

- Single 5V Supply Operation
- 0.1 $\mu$ F External Charge Pump Capacitors
- 400kbps Data Rate
- Standard SOIC and SSOP Packages
- SP207H - Five (5) Drivers and Three (3) Receivers
- SP211H - Four (4) Drivers and Five (5) Receivers
- 1 $\mu$ A Shutdown Mode
- WakeUp Feature in Shutdown Mode
- Tri-State Receiver Outputs
- Ideal for V.34 and High Speed RS-232 Type Applications



**DESCRIPTION...**

The **SP207H** and **SP211H** are multi-channel RS-232 line transceivers configured to fit most communication needs. The "H" series is based on Sipex's **SP200** Series transceivers and has been enhanced for speed. The data rate is improved to over 400kbps which easily meets the 230.4kbps data rates for V.34. The **SP207H** and **SP211H** use the same on-board charge pump to provide  $\pm 10V$  voltage levels, using 0.1 $\mu$ F charge pump capacitors to save board space and reduce circuit cost. The **SP207HB**, **SP211H** and **SP211HB** feature a low-power shutdown mode, which reduces power supply drain to 1 $\mu$ A. A WakeUp function keeps the receivers active in the shutdown mode (**SP207HB** and **SP211HB** only).



Model	Number of RS-232		No. of Receivers Active in Shutdown	No. of External 0.1 $\mu$ F Capacitors	Shutdown	WakeUp	TTL Tri-State
	Drivers	Receivers					
SP207H	5	3	0	4	No	No	No
SP207HB	5	3	3	4	Yes	Yes	Yes
SP211H	4	5	0	4	Yes	No	Yes
SP211HB	4	5	5	4	Yes	Yes	Yes

Table 1. Model Selection Table

## ABSOLUTE MAXIMUM RATINGS

These are stress ratings only and functional operation of the device at these or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

$V_{CC}$ .....	+6V	
$V^+$ .....	( $V_{CC} - 0.3V$ ) to +13.2V	
$V^-$ .....	13.2V	
Input Voltages		
$T_{IN}$ .....	-0.3V to ( $V_{CC} + 0.3V$ )	
$R_{IN}$ .....	$\pm 20V$	
Output Voltages		
$T_{OUT}$ .....	( $V^+$ , +0.3V) to ( $V^-$ , -0.3V)	
$R_{OUT}$ .....	-0.3V to ( $V_{CC} + 0.3V$ )	
Short Circuit Duration on $T_{OUT}$ .....		Continuous
Power Dissipation		
Plastic DIP .....	375mW	
(derate 7mW/°C above +70°C)		
Small Outline .....	375mW	
(derate 7mW/°C above +70°C)		

## SPECIFICATIONS

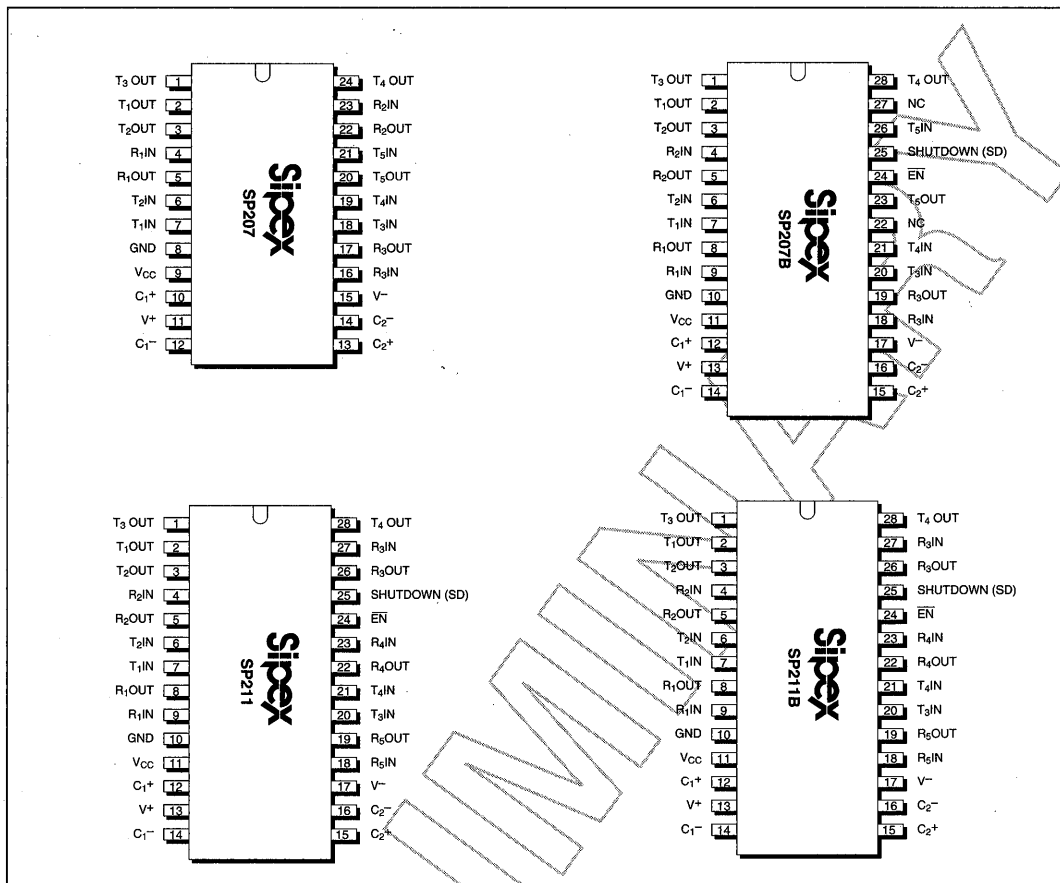
$V_{CC}$  at nominal ratings; 0.1 $\mu$ F charge pump capacitors;  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.

PARAMETER	MIN.	TYP.	MAX.	UNIT	CONDITIONS
<b>TTL INPUTS (DRIVER)</b>					$T_{IN}$ , EN, SD
Logic Threshold					
$V_{IL}$	2.0		0.8	Volts	
$V_{IH}$				Volts	
Logic Pullup Current		1.5	10.0	$\mu$ A	$T_{IN} = 0V$
Data Rate		400		kbps	$C_L = 2,500pF, R_L = 3K\Omega$
<b>TTL OUTPUTS (RECEIVER)</b>					$R_{OUT}$
Compatibility		TTL/CMOS			
$V_{OL}$	3.5		0.4	Volts	$I_{OUT} = 3.2mA; V_{CC} = +5V$
$V_{OH}$				Volts	$I_{OUT} = -1.0mA$
Leakage Current		0.05	$\pm 10$	$\mu$ A	EN = $V_{CC}$ ; $0V \leq R_{OUT} \leq V_{CC}$ ; $T_A = +25^\circ C$
<b>RS-232 OUTPUT (DRIVER)</b>					
Output Voltage Swing	$\pm 5$	$\pm 7$		Volts	All transmitter outputs loaded with 3K $\Omega$ to ground
Output Resistance	300			Ohms	$V_{CC} = 0V; V_{OUT} = \pm 2V$
Output Short Circuit Current		$\pm 25$		mA	Infinite duration
<b>RS-232 INPUT (RECEIVER)</b>					
Voltage Range	-15		+15	Volts	
Logic Pull Down Current		3.0	10.0	$\mu$ A	
Voltage Threshold					
Low	0.8	1.2		Volts	$V_{CC} = +5V, T_A = +25^\circ C$
High		1.7	2.4	Volts	$V_{CC} = +5V, T_A = +25^\circ C$
Hysteresis	0.2	0.5	1.0	Volts	$V_{CC} = +5V$
Resistance	3	5	7	K $\Omega$	$V_{IN} = \pm 15V; T_A = +25^\circ C$
Data Rate		400		kbps	
<b>DYNAMIC CHARACTERISTICS</b>					
Propagation Delay		1.0		$\mu$ S	TTL-to-RS-232
		1.5		$\mu$ S	RS-232-to-TTL
Instantaneous Slew Rate		60		V/ $\mu$ S	$C_L = 50pF, R_L = 3-7K\Omega$ ; $T_A = +25^\circ C$
Transition Region Slew Rate		5		V/ $\mu$ S	$C_L = 2,500pF, R_L = 3K\Omega$ ; measured from +3V to -3V or -3V to +3V

## SPECIFICATIONS

$V_{CC}$  at nominal ratings; 0.1 $\mu$ F charge pump capacitors;  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.

PARAMETER	MIN.	TYP.	MAX.	UNIT	CONDITIONS
Output Enable Time		400		ns	
Output Disable Time		250		ns	
<b>POWER REQUIREMENTS</b>					
$V_{CC}$	4.75	5.00	5.25	Volts	$T_A = +25^\circ\text{C}$ No load; $V_{CC} = \pm 10\%$ All transmitters $R_L = 3\text{K}\Omega$ $T_A = +25^\circ\text{C}$
$I_{CC}$		5		mA	
Shutdown Current		1		10	
<b>ENVIRONMENTAL AND MECHANICAL</b>					
Operating Temperature					
Commercial, -C	0		+70	$^\circ\text{C}$	
Extended, -E	-40		+85	$^\circ\text{C}$	
Storage Temperature	-65		+125	$^\circ\text{C}$	
Package					
-A	Shrink (SSOP) small outline				
-T	Wide (SOIC) small outline				



**FEATURES...**

The **SP207H** and **SP211H** line transceivers provide a variety of configurations to fit most communication needs, especially those applications where  $\pm 12V$  is not available. Both products feature low-power CMOS construction and Sipex-proprietary on-board charge pump circuitry to generate the  $\pm 10V$  RS-232 voltage levels. The ability to use  $0.1\mu F$  charge pump capacitors saves board space and reduces circuit cost.

The **SP207HB** and **SP211H** models feature a low-power shutdown mode, which reduces power supply drain to  $1\mu A$ . The **SP207HB** and **SP211HB** are equipped with the WakeUp function. The WakeUp function keeps the receivers active in the shutdown mode, unless disabled by the  $\overline{EN}$  pin.

**THEORY OF OPERATION**

The **SP207H** and **SP211H** are made up of three basic circuit blocks — 1) transmitter/driver, 2) receiver and 3) the Sipex-proprietary charge pump.

**Charge-Pump**

The charge pump is a Sipex-patented design (5,306,954) and uses a unique approach compared to older less-efficient designs. The charge pump still requires four external capacitors, but uses a four-phase voltage shifting technique to attain symmetrical 10V power supplies. *Figure 3a* shows the waveform found on the positive side of capacitor  $C_2$ , and *Figure 3b* shows the

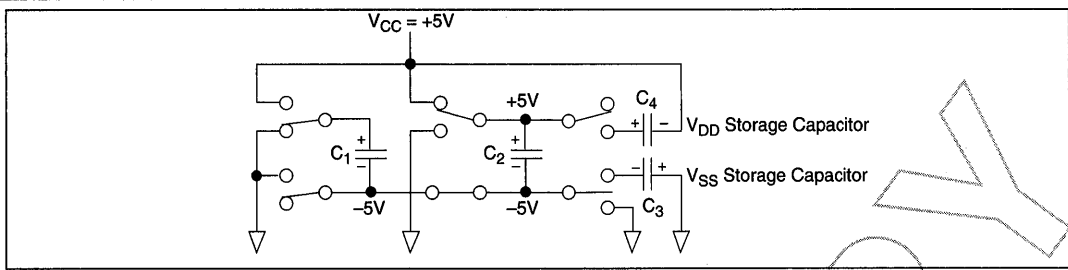


Figure 1. Charge Pump — Phase 1

negative side of capacitor  $C_2$ . There is a free-running oscillator that controls the four phases of the voltage shifting. A description of each phase follows.

### Phase 1

—  $V_{SS}$  charge storage — During this phase of the clock cycle, the positive side of capacitors  $C_1$  and  $C_2$  are initially charged to +5V.  $C_1^+$  is then switched to ground and the charge in  $C_1^-$  is transferred to  $C_2^-$ . Since  $C_2^+$  is connected to +5V, the voltage potential across capacitor  $C_2$  is now 10V.

### Phase 2

—  $V_{SS}$  transfer — Phase two of the clock connects the negative terminal of  $C_2$  to the  $V_{SS}$  storage capacitor and the positive terminal of  $C_2$  to ground, and transfers the generated -10V to  $C_3$ . Simultaneously, the positive side of capacitor  $C_1$  is switched to +5V and the negative side is connected to ground.

### Phase 3

—  $V_{DD}$  charge storage — The third phase of the clock is identical to the first phase — the charge transferred in  $C_1$  produces -5V in the negative terminal of  $C_1$ , which is applied to the negative side of capacitor  $C_2$ . Since  $C_2^+$  is at +5V, the

voltage potential across  $C_2$  is 10V.

### Phase 4

—  $V_{DD}$  transfer — The fourth phase of the clock connects the negative terminal of  $C_2$  to ground, and transfers the generated 10V across  $C_2$  to  $C_4$ , the  $V_{DD}$  storage capacitor. Again, simultaneously with this, the positive side of capacitor  $C_1$  is switched to +5V and the negative side is connected to ground, and the cycle begins again.

Since both  $V^+$  and  $V^-$  are separately generated from  $V_{CC}$ , in a no-load condition  $V^+$  and  $V^-$  will be symmetrical. Older charge pump approaches that generate  $V^-$  from  $V^+$  will show a decrease in the magnitude of  $V^-$  compared to  $V^+$  due to the inherent inefficiencies in the design.

The clock rate for the charge pump typically operates at 15kHz. The external capacitors can be as low as 0.1 $\mu$ F with a 16V breakdown voltage rating.

### Transmitter/Driver

The drivers are inverting transmitters which have been improved for speed over the SP200 Series. The transmitters accept either TTL or CMOS inputs and output the RS-232 signals at data rates over 400kbps. Typically, the RS-232 output volt-

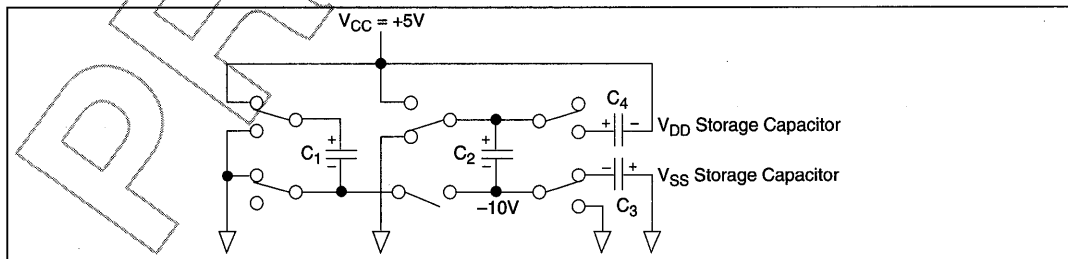


Figure 2. Charge Pump — Phase 2

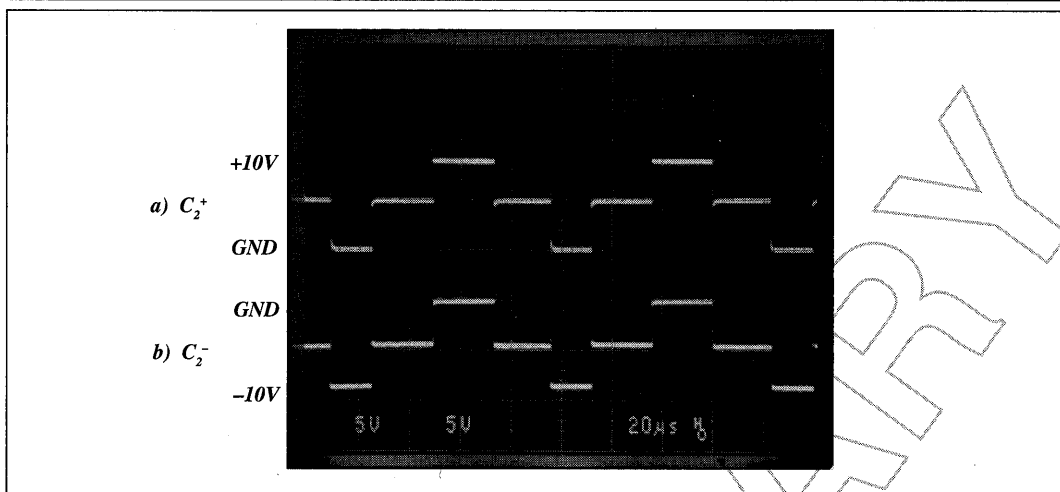


Figure 3. Charge Pump Waveforms

age swing is  $\pm 9V$  with no load, and  $\pm 5V$  minimum with full load. The transmitter outputs are protected against infinite short-circuits to ground without degradation in reliability. The **SP207HB**, **SP211H** and **SP211HB** drivers can be tri-stated by using the SHUTDOWN function.

In the “power off” state, the output impedance will remain greater than 300 ohms, again satisfying the RS-232 specifications. Should the input of the driver be left open, an internal 400Kohm pullup resistor to  $V_{CC}$  forces the input high, thus committing the output to a low state.

Because of the increased speed, the slew rate is typically  $60V/\mu S$  which is above the RS-232 specification of  $30V/\mu S$ . This is the only parameter that exceeds the RS-232 limits.

### Receivers

The receivers convert RS-232 input signals to inverted TTL signals. Since the input is usually from a transmission line where long cable lengths and system interference can degrade the signal, the inputs have a typical hysteresis margin of 500mV. This ensures that the receiver is virtually immune to noisy transmission lines. Should an input be left unconnected, a 5Kohm pulldown resistor to ground will commit the output of the receiver to a high state.

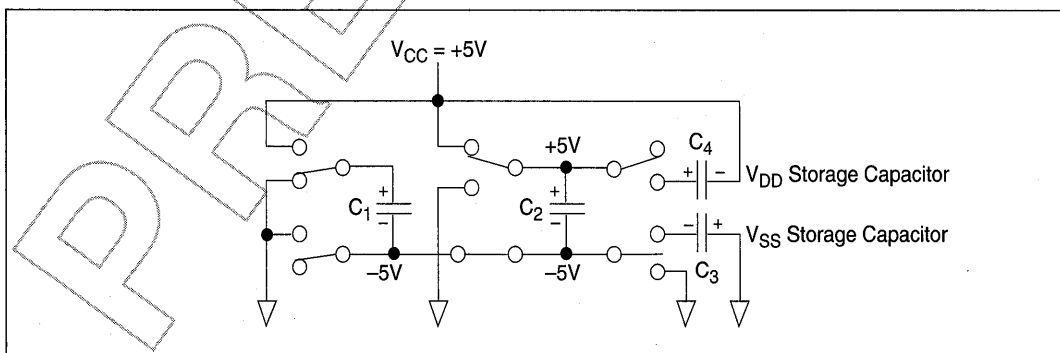


Figure 4. Charge Pump — Phase 3



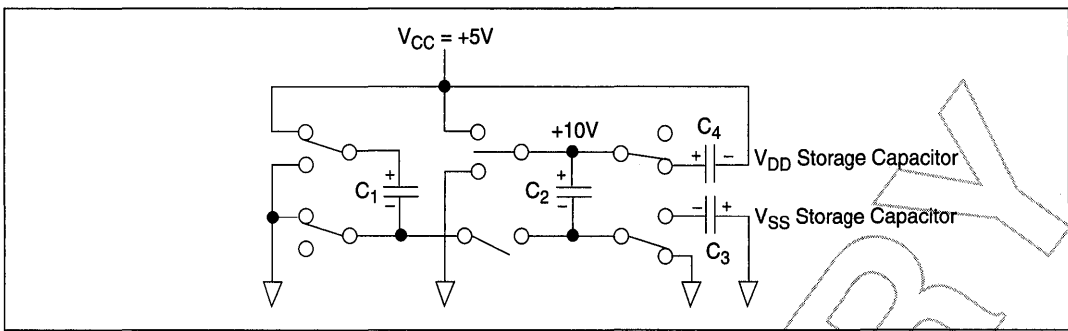


Figure 5. Charge Pump — Phase 4

## SHUTDOWN MODE

The **SP207HB**, **SP211H** and **SP211HB** all feature a control input which will disable the device and reduce the power supply current to less than 10 $\mu$ A, making the parts ideal for battery-powered systems. In the “shutdown” mode the receivers and transmitters will both be tri-stated. The V<sup>+</sup> output of the charge pump will discharge to V<sub>CC</sub>, and the V<sup>-</sup> output will discharge to ground.

For complete shutdown to occur and the 10 $\mu$ A power drain to be realized, the following conditions must be met:

- +5V must be applied to the SD pin
- ENABLE must be either 0V, +5.0V or not connected
- the transmitter inputs must be either +5.0V or not connected
- V<sub>CC</sub> must be +5V
- Receiver inputs must be >0V and <+5V

## ENABLE

The **SP207HB**, **SP211H** and **SP211HB** feature an enable input pin, which allows the receiver

SD	$\overline{\text{EN}}$	Power Up/Down	Receiver Outputs
0	0	Up	Enable
0	1	Up	Tri-state
1	0	Down	Tri-state
1	1	Down	Tri-state

Table 2. Truth Table for SP2xxH

outputs to be either tri-stated or enabled. This can be especially useful when the receiver is tied directly to a microprocessor data bus. The enable is active low; that is, 0V applied to the ENABLE pin will enable the receiver outputs.

## WAKEUP FUNCTION

The **SP207HB** and **SP211HB** have a wake-up feature that keeps all the receivers in an enabled state when the device is in the shutdown mode. With only the receivers active during shutdown, the devices draw 5–10 $\mu$ A of supply current. A typical application of this function would be where a modem is interfaced to a computer in a power-down mode. The ring indicator signal from the modem could be passed through an active receiver that is in the shutdown mode. The ring indicator signal would propagate through the receiver to the power management circuitry of the computer to power up the microprocessor and the **SP207HB/SP211HB** drivers. After the supply voltage to the transceivers reaches +5.0V, the SHUTDOWN pin can be disabled. All receivers that are active during shutdown maintain 500mV (typ.) of hysteresis.

SD	$\overline{\text{EN}}$	Power Up/Down	Receiver Outputs
0	0	Up	Enable
0	1	Up	Tri-state
1	0	Down	Enable
1	1	Down	Tri-state

Table 3. Wake-Up Truth Table for SP2xxHB

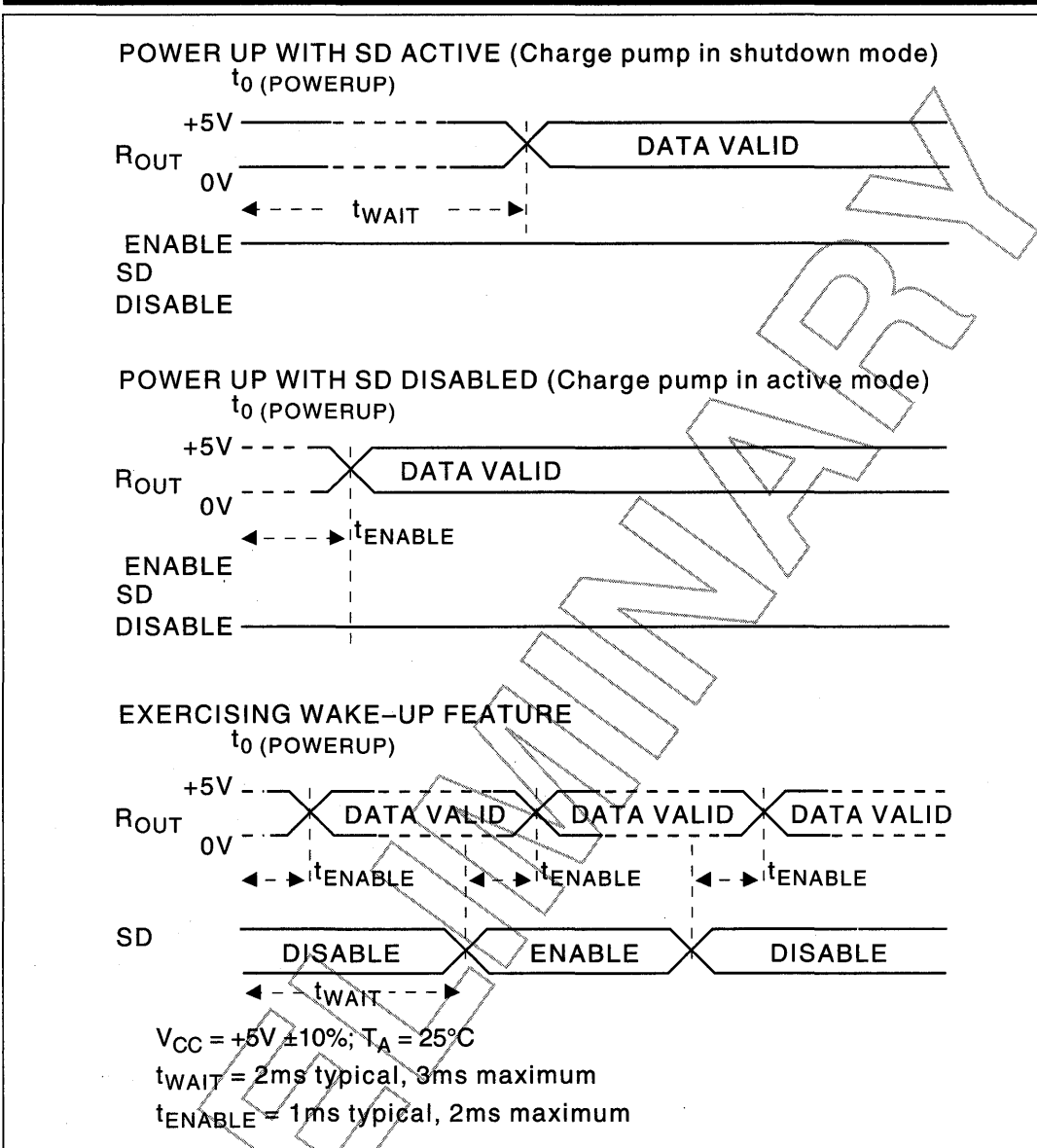
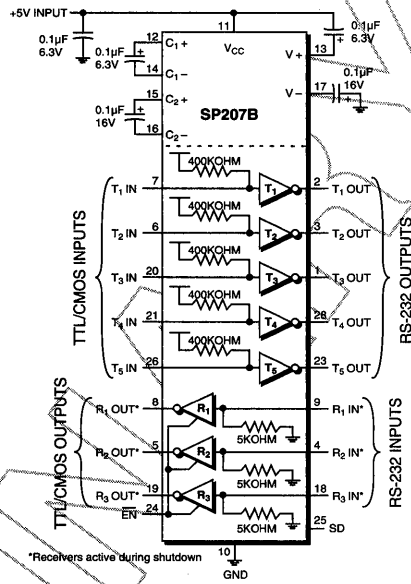
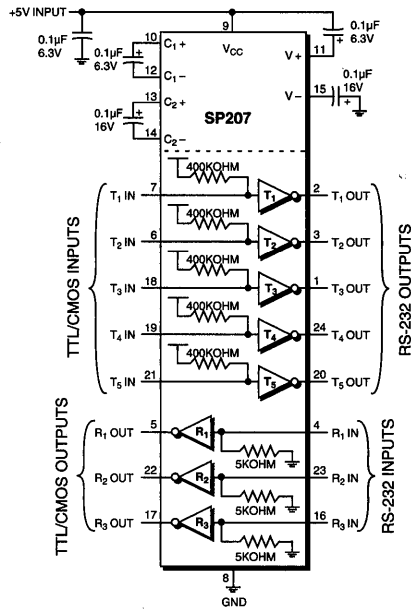
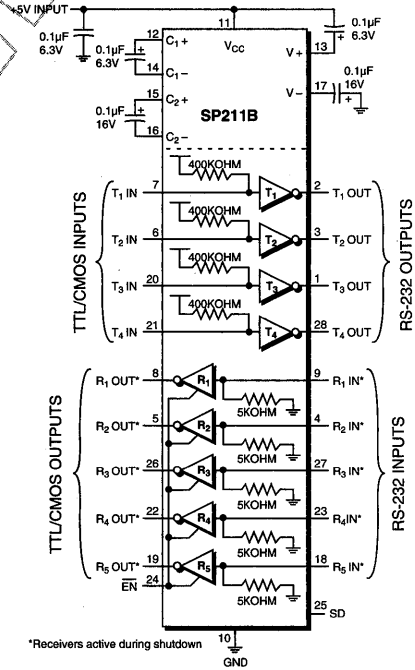
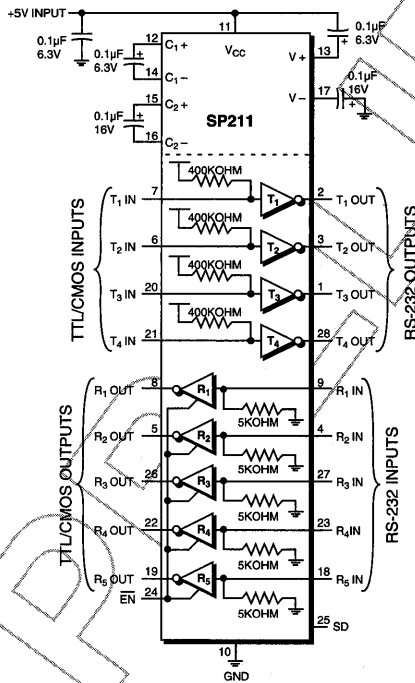


Figure 6. Wake-Up Timing

# TYPICAL APPLICATION CIRCUITS



The SP207B is offered in a 28-pin SOIC or 28-pin SSOP package.



## ORDERING INFORMATION

### RS-232 Transceivers:

Model	Drivers	Receivers	Temperature Range	Package Type
SP207HCA	5	3	0°C to +70°C	24-pin SSOP
SP207HCP	5	3	0°C to +70°C	24-pin Plastic DIP
SP207HCT	5	3	0°C to +70°C	24-pin SOIC
SP207HEA	5	3	-40°C to +85°C	24-pin SSOP
SP207HEP	5	3	-40°C to +85°C	24-pin Plastic DIP
SP207HET	5	3	-40°C to +85°C	24-pin SOIC

### RS-232 Transceivers with Low-Power Shutdown and Tri-state Enable:

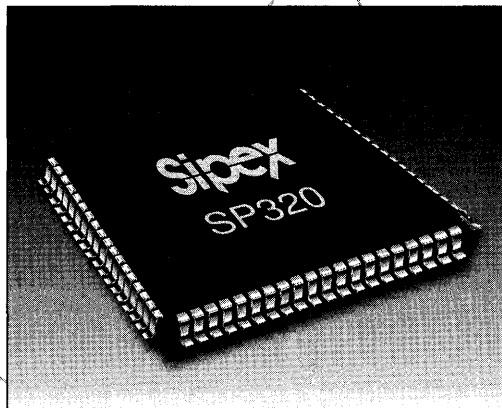
Model	Drivers	Receivers	Temperature Range	Package Type
SP211HCA	4	5	0°C to +70°C	28-pin SSOP
SP211HCT	4	5	0°C to +70°C	28-pin SOIC
SP211HEA	4	5	-40°C to +85°C	28-pin SSOP
SP211HET	4	5	-40°C to +85°C	28-pin SOIC

### RS-232 Transceivers with Low-Power Shutdown, Tri-state Enable, and Wake-Up Function:

Model	Drivers	Receivers	Temperature Range	Package Type
SP207HBCA	5	3, with 3 active in Shutdown	0°C to +70°C	28-pin SSOP
SP207HBCT	5	3, with 3 active in Shutdown	0°C to +70°C	28-pin SOIC
SP207HBEA	5	3, with 3 active in Shutdown	-40°C to +85°C	28-pin SSOP
SP207HBET	5	3, with 3 active in Shutdown	-40°C to +85°C	28-pin SOIC
SP211HBCA	4	5, with 5 active in Shutdown	0°C to +70°C	28-pin SSOP
SP211HBCT	4	5, with 5 active in Shutdown	0°C to +70°C	28-pin SOIC
SP211HBEA	4	5, with 5 active in Shutdown	-40°C to +85°C	28-pin SSOP
SP211HBET	4	5, with 5 active in Shutdown	-40°C to +85°C	28-pin SOIC

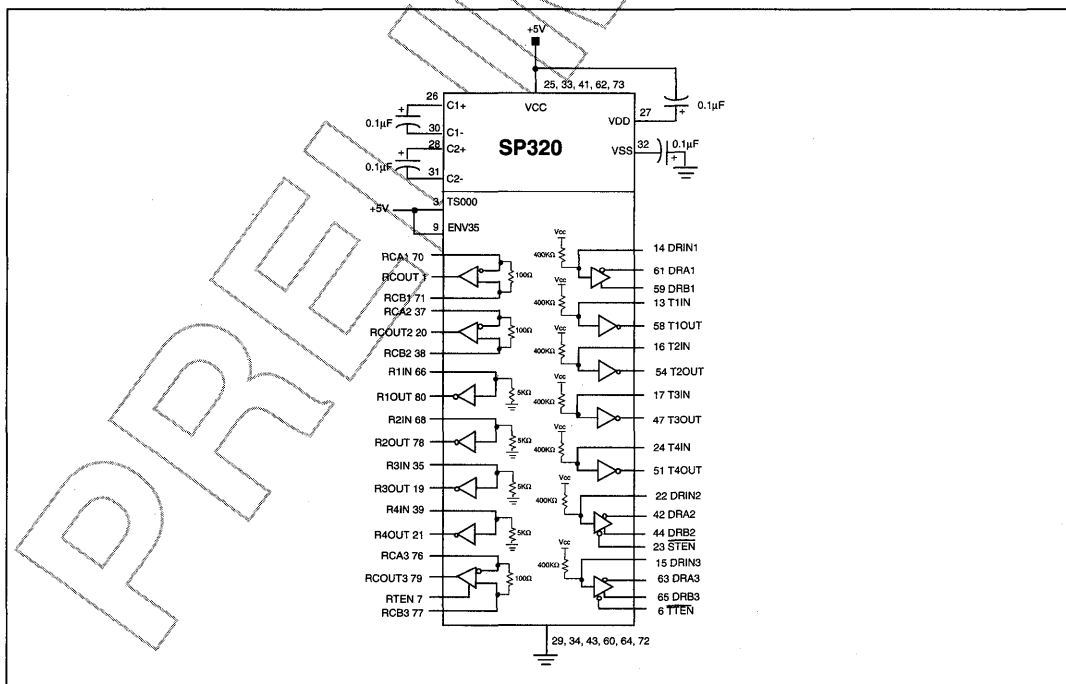
**Complete +5V Only V.35 Interface with RS-232 (V.28) Control Lines**

- +5V Only
- 3 Drivers 3 Receivers – V.35
- 4 Drivers 4 Receivers – RS-232
- No External V.35 Termination Resistors
- 80 pin QFP Surface Mount Packaging



**DESCRIPTION...**

The **SP320** is a complete V.35 interface transceiver offering 3 drivers and 3 receivers of V.35, and 4 drivers and 4 receivers of RS-232 (V.28). A **Sipex**-patented charge pump allows +5V only low power operation. RS-232 drivers and receivers are specified to operate at 120Kbps, all V.35 drivers and receivers operate up to 5Mbps.



## ABSOLUTE MAXIMUM RATINGS

These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

V <sub>CC</sub> .....	+7V
Input Voltages	
Logic.....	-0.3V to (V <sub>CC</sub> +0.5V)
Drivers.....	-0.3V to (V <sub>CC</sub> +0.5V)
Receivers.....	±15V
Output Voltages	
Logic.....	-0.3V to (V <sub>CC</sub> +0.5V)
Drivers.....	±14V
Receivers.....	-0.3V to (V <sub>CC</sub> +0.5V)
Storage Temperature.....	-65°C to +150°C
Power Dissipation.....	1500mW
Package Derating	
∅ <sub>JC</sub> .....	16 °C/W
∅ <sub>JA</sub> .....	46 °C/W

## SPECIFICATIONS

Typical at 25°C and V<sub>CC</sub> = 5V±5% unless otherwise noted.

PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>V.35 DRIVER</b>					
TTL Input Levels					
V <sub>L</sub>			0.8	Volts	
V <sub>IH</sub>	2.0			Volts	
Voltage Outputs					
Differential Outputs	±0.44	±0.55	±0.66	Volts	R <sub>L</sub> = 100Ω from A to B
Source Impedance	50	100	150	Ohms	
Short Circuit Impedance	135	150	165	Ohms	Measured from A=B to Gnd,
					V <sub>OUT</sub> = -2V to +2V
Voltage Output Offset	-0.6		+0.6	Volts	V <sub>Offset</sub> = ( V <sub>A</sub>   +  V <sub>B</sub>  ) / 2
AC Characteristics					
Transition Time		40		ns	Rise/fall time, 10% to 90%
Transmission Rate			5	Mbps	R <sub>L</sub> = 100Ω, V <sub>DIFF OUT</sub> = .55V±20%
Propagation Delay					
t <sub>PHL</sub>		200		ns	Measured from 1.5V of V <sub>IN</sub>
					to 50% of V <sub>OUT</sub>
t <sub>PLH</sub>		200		ns	Measured from 1.5V of V <sub>IN</sub>
					to 50% of V <sub>OUT</sub>
<b>V.35 RECEIVER</b>					
TTL Output Levels					
V <sub>OL</sub>			0.4	Volts	I <sub>OUT</sub> = -3.2mA
V <sub>OH</sub>	2.4			Volts	I <sub>OUT</sub> = 1.0mA
Receiver Inputs					
Differential Input					
Threshold	-0.2		+0.2	Volts	
Input Impedance	90	100	110	Ohms	
Short Circuit Impedance	135	150	165	Ohms	Measured from A=B to Gnd
					V <sub>IN</sub> = -2V to +2V
AC Characteristics					
Transmission Rate			5	Mbps	R <sub>L</sub> = 100Ω from A to B
Propagation Delay					
t <sub>PHL</sub>		200		ns	Measured from 50% of V <sub>IN</sub> to
					1.5V of R <sub>OUT</sub>
t <sub>PLH</sub>		200		ns	Measured from 50% of V <sub>IN</sub> to
					1.5V of R <sub>OUT</sub>

# SPECIFICATIONS (CONTINUED)

Typical at 25°C and  $V_{CC} = 5V \pm 5\%$  unless otherwise noted.

PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>RS-232 DRIVER</b>					
TTL Input Levels					
$V_{IL}$			0.8	Volts	
$V_{IH}$	2.0			Volts	
Voltage Outputs					
High Level Output	+5.0		+15.0	Volts	$R_L = 3K\Omega$ to Gnd
Low Level Output	-15.0		-5.0	Volts	$R_L = 3K\Omega$ to Gnd
Open Circuit Output	-15		+15	Volts	$R_L = \infty$
Short Circuit Current	-100		+100	mA	$R_L = \text{Gnd}$
Power Off Impedance	300			Ohms	$V_{CC} = 0V; V_{OUT} = \pm 2V$
AC Characteristics					
Slew Rate			30	V/ $\mu$ S	$R_L = 3K\Omega; C = 50pF$ ; From +3V to -3V or -3V to +3V
Transmission Rate			120	Kbps	$R_L = 3K\Omega; 2500pF$ to GND, $V_{OUT} = \pm 5V$
Transition Time			1.56	$\mu$ S	Rise/fall time, between $\pm 3V$ $R_L = 3K\Omega; C_L = 2500pF$
Propagation Delay					
$t_{PHL}$		2	8	$\mu$ S	$R_L = 3K\Omega; C_L = 2500pF$ ; From 1.5V of $T_{IN}$ to 50% of $V_{OUT}$
$t_{PLH}$		2	8	$\mu$ S	$R_L = 3K\Omega; C_L = 2500pF$ ; From 1.5V of $T_{IN}$ to 50% of $V_{OUT}$
<b>RS-232 RECEIVER</b>					
TTL Output Levels					
$V_{OL}$			0.4	Volts	
$V_{OH}$	2.4			Volts	
Receiver Input					
Input Voltage Range	-15		+15	Volts	
High Threshold		1.7	3.0	Volts	
Low Threshold	0.8	1.2		Volts	
Hysteresis	0.2	0.5	.1	Volts	
Receiver Input Circuit Bias			+2.0	Volts	$V_{CC} = 5V; T_A = +25^\circ C$
Input Impedance	3	5	7	KOhms	$V_{IN} = \pm 15V$
AC Characteristics					
Transmission Rate			120	Kbps	
Propagation Delay					
$t_{PHL}$		100	1	$\mu$ S	From 50% of $R_{IN}$ to 1.5V of $R_{OUT}$
$t_{PLH}$		100	1	$\mu$ S	From 50% of $R_{IN}$ to 1.5V of $R_{OUT}$
<b>POWER REQUIREMENTS</b>					
No Load $V_{CC}$ Supply Current		35		mA	No load; $V_{CC} = 5.0V; T_A = 25^\circ C$
Full Load $V_{CC}$ Supply Current		60		mA	RS-232 drivers $R_L = 3K\Omega$ to Gnd; DC Input
Shutdown Current		1.5		mA	V.35 drivers $R_L = 100\Omega$ from A to B; DC Input T5000 = ENV35 = 0V

## THEORY OF OPERATION...

The **SP320** is a single chip +5V only serial transceiver that supports all the signals necessary to implement a full V.35 interface. Three V.35 drivers and three V.35 receivers make up the clock and data signals. Four RS-232 (V.28) drivers and four RS-232 (V.28) receivers are used for control line signals for the interface.

### V.35 Drivers...

The V.35 drivers are +5V only, low power voltage output transmitters. The drivers do not require any external resistor networks, and will meet the following requirements:

1. Source impedance in the range of  $50\Omega$  to  $150\Omega$ .
2. Resistance between short-circuited terminals and ground is  $150\Omega \pm 15\Omega$ .
3. When terminated with a  $100\Omega$  resistive load the terminal to terminal voltage will be 0.55 volts  $\pm 20\%$  so that the A terminal is positive to the B terminal when binary 0 is transmitted, and the conditions are reversed to transmit binary 1.
4. The arithmetic mean of the voltage of the A terminal with respect to ground, and the B terminal with respect to ground will not exceed 0.6 volts when terminated as in 3.

The V.35 drivers can operate at data rates as high as 5Mbps. The driver outputs are protected against short-circuits between the A and B outputs and short circuits to ground.

Two of the V.35 drivers, DRIN2 and DRIN3 are equipped with enable control lines. When the enable pins are high the driver outputs are disabled, the output impedance of a disabled driver will nominally be  $300\Omega$ . When the enable pins are low, the drivers are active.

### V.35 Receivers...

The V.35 receivers are +5V only, low power differential receivers which meet the following requirements:

1. Input impedance in the range of  $100\Omega \pm 10\Omega$ .
2. Resistance to ground of  $150\Omega \pm 15\Omega$ , measured from short-circuited terminals.

All of the V.35 receivers can operate at data rates as high as 5Mbps. The sensitivity of the V.35 receiver inputs is  $\pm 200\text{mV}$  which applies over a common mode range of +12V to -7V.

### RS-232 (V.28) Drivers

The RS-232 drivers are inverting transmitters, which accept either TTL or CMOS inputs and output the RS-232 signals with an inverted sense relative to the input logic levels. Typically, the RS-232 output voltage swing is  $\pm 9\text{V}$  with no load, and  $\pm 5\text{V}$  minimum with full load. The transmitter outputs are protected against infinite short-circuits to ground without degradation in reliability.

In the power off state, the output impedance of the RS-232 drivers will be greater than  $300\Omega$  over a  $\pm 2\text{V}$  range. Should the input of a driver be left open, an internal  $400\text{K}\Omega$  pullup resistor to  $V_{CC}$  forces the input high, thus committing the output to a low state. The slew rate of the transmitter output is internally limited to a maximum of  $30\text{V}/\mu\text{s}$  in order to meet the EIA standards. The RS-232 drivers are rated for 120Kbps data rates.

### RS-232 (V.28) Receivers...

The RS-232 receivers convert RS-232 input signals to inverted TTL signals. Each of the four receivers features 500mV of hysteresis margin to minimize the effects of noisy transmission lines. The inputs also have a  $5\text{K}\Omega$  resistor to ground; in an open circuit situation the input of the receiver will be forced low, committing the output to a logic high state. The input resistance will maintain  $3\text{K}\Omega$ - $7\text{K}\Omega$  over a  $\pm 15\text{V}$  range. The maximum operating voltage range for the receiver is  $\pm 30\text{V}$ , under these conditions the input current to the receiver must be limited to less than 100mA. The RS-232 receivers can operate up to 120Kbps.

### CHARGE PUMP...

The charge pump is a Sipex-patented design (5,306,954) and uses a unique approach compared to older less-efficient designs. The charge pump still requires four external capacitors, but uses a four-phase voltage shifting technique to attain symmetrical 10V power supplies. The capacitors can be as low as  $0.1\mu\text{F}$  with a 16 volt rating. Polarized or non-polarized capacitors can be used.



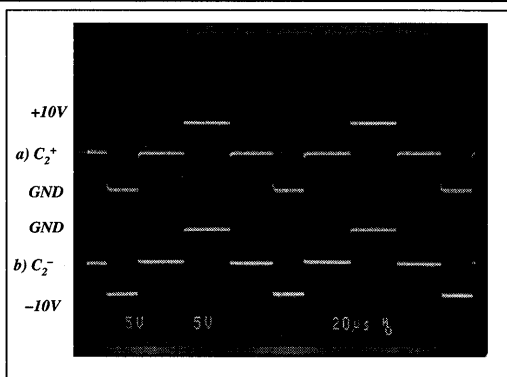


Figure 1. Charge Pump Waveforms

Figure 1a shows the waveform found on the positive side of capacitor C2, and Figure 1b shows the negative side of capacitor C2. There is a free-running oscillator that controls the four phases of the voltage shifting. A description of each phase follows.

### Phase 1

**-V<sub>ss</sub> charge storage-** During this phase of the clock cycle, the positive side of capacitors C1 and C2 are initially charged to +5V. C1+ is then switched to ground and charge in C1- is transferred to C2-. Since C2+ is connected to +5V, the voltage potential across capacitor C2 is now 10V.

### Phase 2

**-V<sub>ss</sub> transfer-** Phase two of the clock connects the negative terminal of C2 to the V<sub>ss</sub> storage capacitor and the positive terminal of C2 to ground, and transfers the generated -10V to C3. Simultaneously, the positive side of capacitor C1 is switched to +5V and the negative side is connected to ground.

### Phase 3

**-V<sub>dd</sub> charge storage-** The third phase of the clock is identical to the first phase- the transferred charge in C1 produces -5V in the negative terminal of C1, which is applied to the negative side of capacitor C2. Since C2+ is at +5V, the voltage potential across C2 is 10V.

### Phase 4

**-V<sub>dd</sub> transfer-** The fourth phase of the clock connects the negative terminal of C2 to ground and transfers the generated 10V across C2 to C4, the V<sub>dd</sub> storage capacitor. Again, simultaneously with this, the positive side of capacitor C1 is switched to +5V and the negative side is connected to ground, and the cycle begins again.

Since both V<sub>+</sub> and V<sub>-</sub> are separately generated from V<sub>cc</sub> in a no load condition, V<sub>+</sub> and V<sub>-</sub> will be symmetrical. Older charge pump approaches that generate V<sub>-</sub> from V<sub>+</sub> will show a decrease in the magnitude of V<sub>-</sub> compared to V<sub>+</sub> due to the inherent inefficiencies in the design.

The clock rate for the charge pump typically operates at 15KHZ. The external capacitors must be 0.1μF with a 16V breakdown rating.

### Shutdown Mode

The SP320 can be put into a low power shutdown mode by bringing both TS000 (pin 3) and ENV35 (pin 9) low. In shutdown mode, the SP320 will draw less than 2mA of supply current. For normal operation, both pins should be connected to +5V.

### External Power Supplies

For applications that do not require +5V only, external supplies can be applied at the V<sub>+</sub> and V<sub>-</sub> pins. The value of the external supply voltages must be no greater than ±10V. The current drain from the ±10V supplies is used for the RS-232 drivers. For the RS-232 driver the current requirement will be 3.5mA per driver. It is critical the external power supplies provide a power supply sequence of : +10V, +5V and then -10V.

### Applications Information

The SP320 is a single chip device that can implement a complete V.35 interface. Three (3) V.35 drivers and three (3) V.35 receivers are used for clock and data signals and four (4) RS-232 (V.28) drivers and four (4) RS-232 (V.28) receivers can be used for the control signals of the interface. The following examples show the SP320 configured in either a DTE or DCE application.

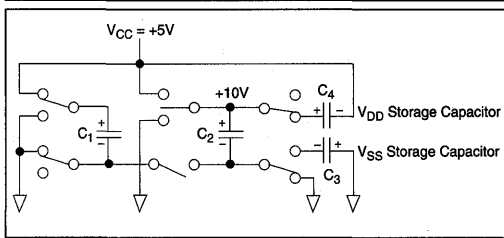


Figure 2. Charge Pump Phase 1

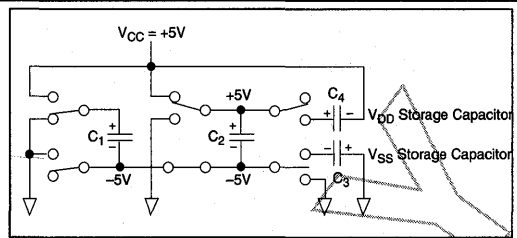


Figure 3. Charge Pump Phase 2

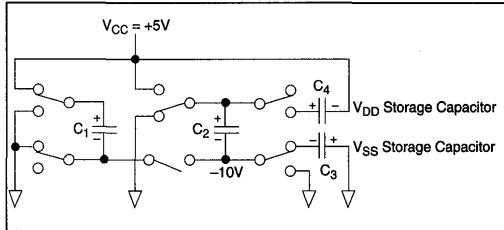


Figure 4. Charge Pump Phase 3

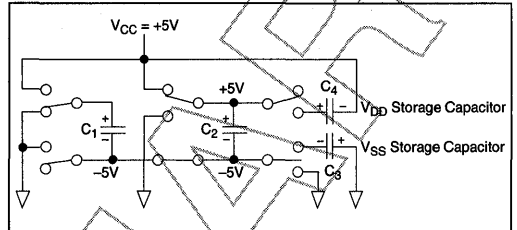


Figure 5. Charge Pump Phase 4

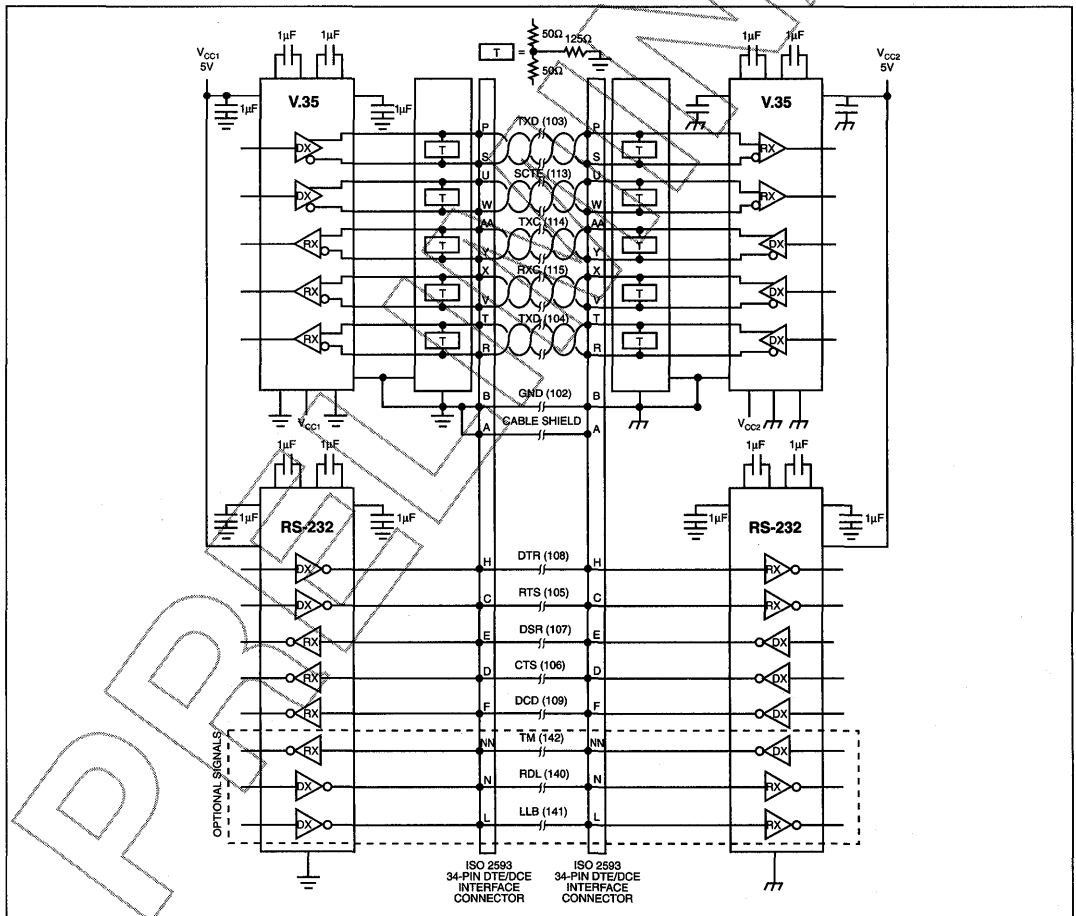


Figure 6. A Competitor's Typical V.35 Solution Using Six Components.

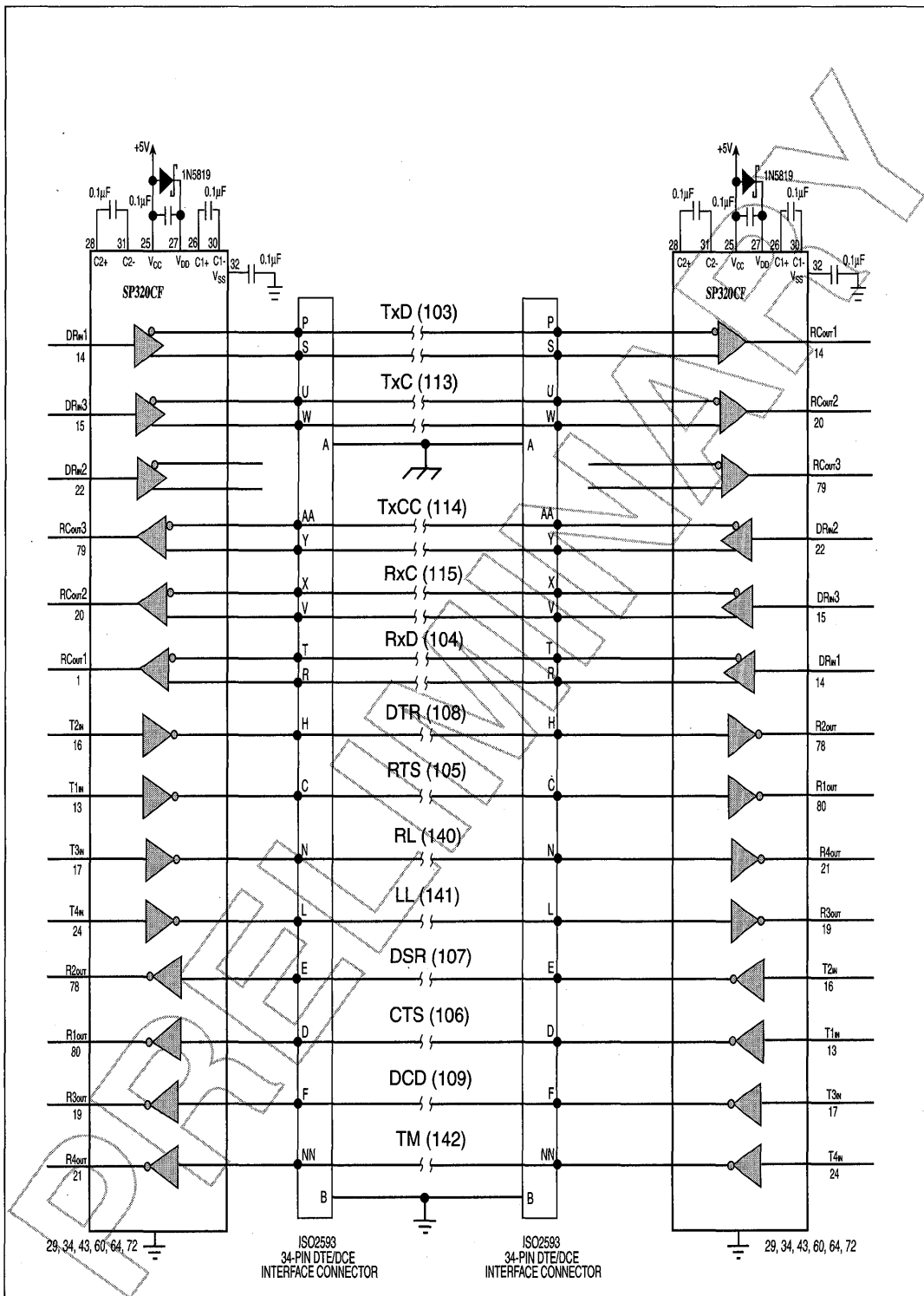
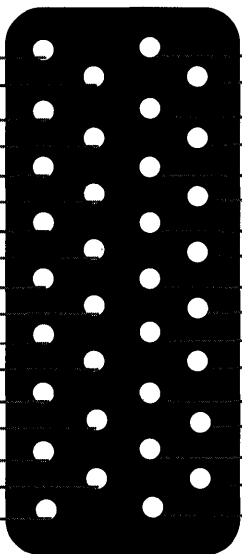


Figure 7. Typical DTE-DCE V.35 Connection with the SP320

# ISO-2593 connector pin out

Signal Ground  
 Clear to Send  
 Data Carrier Detect  
 Ring Indicator  
 Local Loopback  
 Remote Loopback  
 Receive Data (A)  
 Receive Data (B)  
 Receive Timing (A)  
 Receive Timing (B)  
 Unassigned---  
 Unassigned---  
 Unassigned---  
 Unassigned---  
 Unassigned---  
 Unassigned---  
 Test Mode

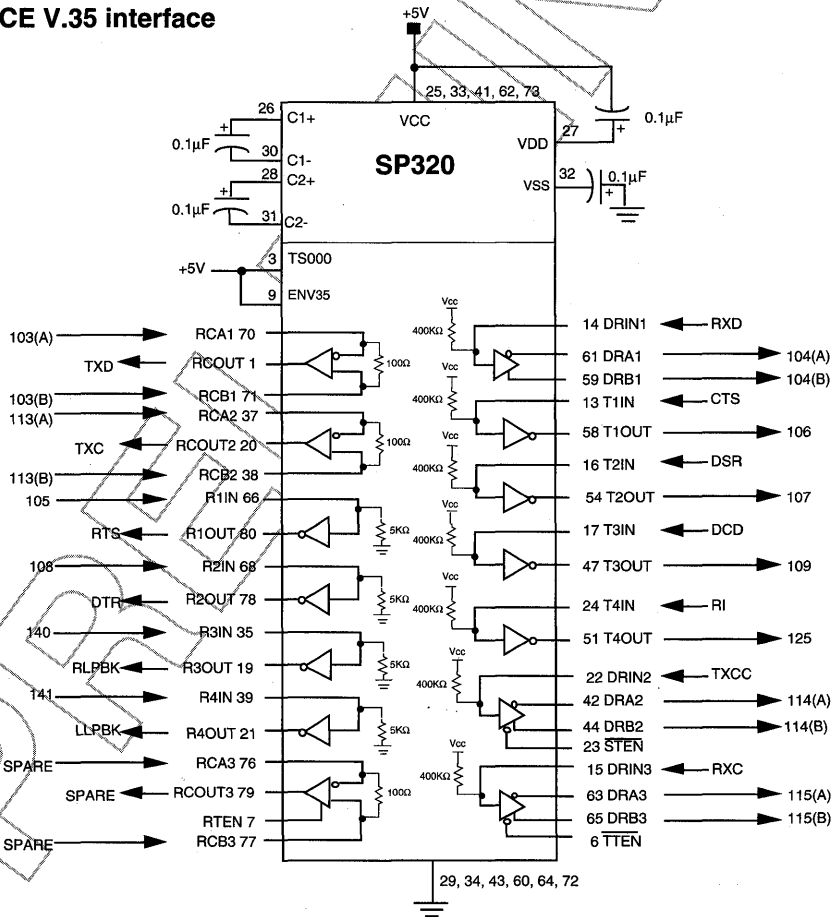
B  
D  
F  
J  
L  
N  
R  
T  
V  
X  
Z  
BB  
DD  
FF  
JJ  
LL  
NN



A  
C  
E  
H  
K  
M  
P  
S  
U  
W  
Y  
AA  
CC  
EE  
HH  
KK  
MM

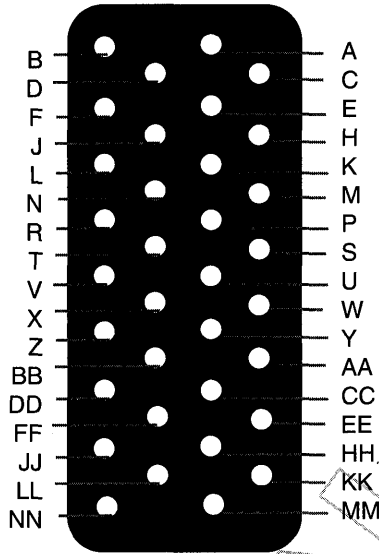
Chasis Ground  
 Request to Send  
 DCE Ready (DSR)  
 DTE Ready (DTR)  
 Unassigned---  
 Unassigned---  
 Transmitted Data (A)  
 Transmitted Data (B)  
 Terminal Timing (A) } 113(A)  
 Terminal Timing (B) } 113(B)  
 Transmit Timing (A) } 114(A)  
 Transmit Timing (B) } 114(B)  
 Unassigned---  
 Unassigned---  
 Unassigned---  
 Unassigned---  
 Unassigned---

## Typical DCE V.35 interface



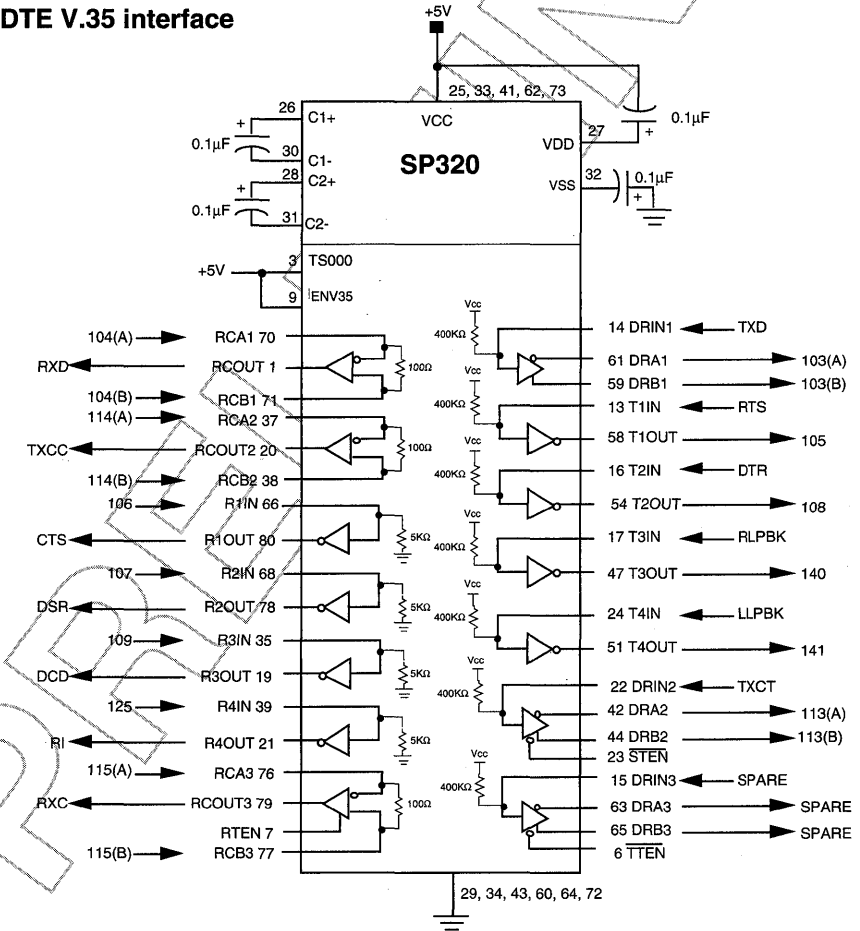
# ISO-2593 connector pin out

Signal Ground  
 Clear to Send  
 Data Carrier Detect  
 Ring Indicator  
 Local Loopback  
 Remote Loopback  
 Receive Data (A)  
 Receive Data (B)  
 Receive Timing (A)  
 Receive Timing (B)  
 Unassigned---  
 Unassigned---  
 Unassigned---  
 Unassigned---  
 Unassigned---  
 Unassigned---  
 Test Mode



Chasis Ground  
 Request to Send  
 DCE Ready (DSR)  
 DTE Ready (DTR)  
 Unassigned---  
 Unassigned---  
 Transmitted Data (A)  
 Transmitted Data (B)  
 Terminal Timing (A) } 113(A)  
 Terminal Timing (B) } 113(B)  
 Transmit Timing (A) } 114(A)  
 Transmit Timing (B) } 114(B)  
 Unassigned---  
 Unassigned---  
 Unassigned---  
 Unassigned---  
 Unassigned---

## Typical DTE V.35 interface





**ORDERING INFORMATION**

Model	Temperature Range	Package Types
SP320CF .....	0°C to +70°C .....	80-pin QFP .....

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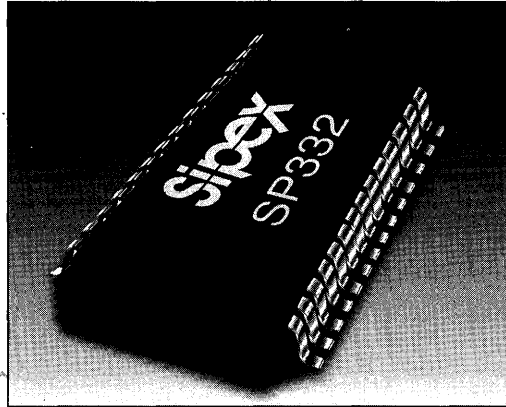
PRELIMINARY

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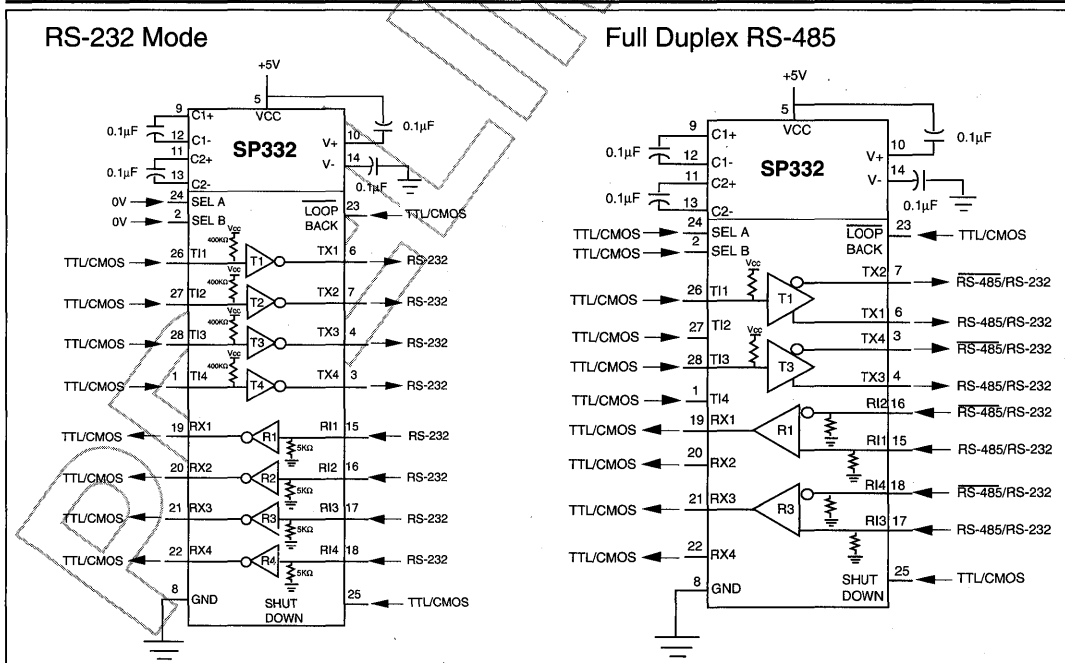
## RS-232/RS-485 Multi-Mode Serial Transceiver

- +5V Only
- 4 Drivers, 4 Receivers RS-232
- 2 Drivers, 2 Receivers RS-485
- Loop Back Function for Self Test
- 28 Pin SOIC Packaging



### DESCRIPTION...

The **SP332** is a monolithic device that contains both RS-232 and RS-485 line drivers and receivers. The configuration of the **SP332** can be changed at any time by changing the logic state of two control input pins. The device also includes a loop back function which internally connects driver outputs to receiver inputs for a chip self test. A **Sipex**-patented charge pump (5,306,954) allows +5V only operation.



## ABSOLUTE MAXIMUM RATINGS

These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

V <sub>CC</sub> .....	+12V
Input Voltages	
Logic.....	-0.5V to (V <sub>CC</sub> +0.5V)
Drivers.....	-0.5V to (V <sub>CC</sub> +0.5V)
Receivers.....	±30V @ ≤100mA
Driver Outputs.....	±15V
Storage Temperature.....	-65°C to +150°C
Power Dissipation.....	1000mW

## SPECIFICATIONS

T<sub>MIN</sub> to T<sub>MAX</sub> and V<sub>CC</sub> = 5V±5% unless otherwise noted.

PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>RS-485 DRIVER</b>					
<b>DC Characteristics</b>					
Differential Output Voltage	GND		V <sub>CC</sub>	Volts	Unloaded; R=∞; see figure 1
Differential Output Voltage	2.0		5.0	Volts	With Load; R=50Ω (RS-422); see figure 1
Differential Output Voltage	1.5		5.0	Volts	With Load; R=27Ω (RS-485); see figure 1
Change in Magnitude of Driver Differential Output Voltage for Complementary States			0.2	Volts	R=27Ω or R=50Ω; see figure 1
Driver Common-Mode Output Voltage			3	Volts	R=27Ω or R=50Ω; see figure 1
Input High Voltage	2.0			Volts	Applies to transmitter inputs, SEL A, SEL B, SD, LB
Input Low Voltage			0.8	Volts	Applies to SEL A, SEL B, SD, LB
Input Current			±10	μA	Applies to:
Pull-Up Current		1.5		μA	transmitter inputs, LB
Pull-Down Current		3.0		μA	SEL A, SEL B, SD,
Driver Short-Circuit Current					
V <sub>OUT</sub> = HIGH	35		250	mA	-7V ≤ V <sub>O</sub> ≤ 10V
V <sub>OUT</sub> = LOW	35		250	mA	-7V ≤ V <sub>O</sub> ≤ 10V
<b>AC Characteristics</b>					
Driver Data Rate			10	Mbps	
Driver Input to Output	20	60		ns	t <sub>PLH</sub> ; R <sub>DIFF</sub> =54Ω, C <sub>L1</sub> =C <sub>L2</sub> =100pF; see figures 3 and 6
Driver Input to Output	20	60		ns	t <sub>PHL</sub> ; R <sub>DIFF</sub> =54Ω, C <sub>L1</sub> =C <sub>L2</sub> =100pF; see figures 3 and 6
Driver Skew		5	10	ns	From output to output; see figures 3 and 6
Driver Rise or Fall Time	3	15	40	ns	From 10% to 90%; R <sub>DIFF</sub> =54Ω, C <sub>L1</sub> =C <sub>L2</sub> =100pF; see figures 3 and 6
<b>RS-485 RECEIVER</b>					
<b>DC Characteristics</b>					
Differential Input Threshold	-0.2		+0.2	Volts	-7V ≤ V <sub>CM</sub> ≤ 12V
Input Hysteresis		70		mV	V <sub>CM</sub> =0V
Output Voltage High	3.5			Volts	I <sub>O</sub> =-4mA, V <sub>ID</sub> =+200mV
Output Voltage Low			0.4	Volts	I <sub>O</sub> =+4mA, V <sub>ID</sub> =-200mV
Input Resistance	12	15		kΩ	-7V ≤ V <sub>CM</sub> ≤ 12V
Input Current (A, B); V <sub>IN</sub> = 12V			+1.0	mA	V <sub>IN</sub> = 12V, A is the non-inverting receiver input. B is the inverting receiver input
Input Current (A, B); V <sub>IN</sub> = -7V			-0.8	mA	V <sub>IN</sub> = -7V
Short Circuit Current			85	mA	0V ≤ V <sub>CM</sub> ≤ V <sub>CC</sub>

# SPECIFICATIONS (CONTINUED)

$T_{MIN}$  to  $T_{MAX}$  and  $V_{CC} = 5V \pm 5\%$  unless otherwise noted.

PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>AC Characteristics</b>					
Receiver Data Rate			10	Mbps	
Receiver Input to Output		90		ns	$t_{PLH}$ ; $R_{DIFF}=54\Omega$ , $C_{L1}=C_{L2}=100pF$ ; Figures 3 and 8
Receiver Input to Output		90		ns	$t_{PLH}$ ; $R_{DIFF}=54\Omega$ , $C_{L1}=C_{L2}=100pF$ ; Figures 3 and 7
Diff. Receiver Skew $ t_{PLH}-t_{PHL} $		13		ns	$R_{DIFF}=54\Omega$ , $C_{L1}=C_{L2}=100pF$ ; Figures 3 and 7
<b>RS-232 DRIVER</b>					
<b>DC Characteristics</b>					
TTL Input Levels					
$V_{IL}$			0.8	Volts	Applies to transmitter inputs, SEL A, SEL B, SD, LB
$V_{IH}$	2.0			Volts	Applies to transmitter inputs, SEL A, SEL B, SD, LB
Voltage Outputs					
High Level Output	+5.0		+15.0	Volts	$R_L=3K\Omega$ to Gnd
Low Level Output	-15.0		-5.0	Volts	$R_L=3K\Omega$ to Gnd
Open Circuit Output			$\pm 15$	Volts	$R_L=\infty$
Short Circuit Current			$\pm 100$	mA	$V_{OUT}=0V$
Power Off Impedance	300			Ohms	$V_{CC}=0V$ ; $V_{OUT}=\pm 2V$
<b>AC Characteristics</b>					
Transmission Rate			120	Kbps	
Transition Time			1.56	$\mu S$	Rise/fall time, +3V to -3V; -3V to +3V $R_L=3K\Omega$ , $C_L=2500pF$
Propagation Delay					
$t_{PHL}$		2		$\mu S$	$R_L=3K\Omega$ , $C_L=2500pF$ ; From 1.5V of $T_{IN}$ to 50% of $V_{OUT}$
$t_{PLH}$		1.5		$\mu S$	$R_L=3K\Omega$ , $C_L=2500pF$ ; From 1.5V of $T_{IN}$ to 50% of $V_{OUT}$
Slew Rate		10	30	V/ $\mu S$	$R_L=3K\Omega$ , $C_L=50pF$ ; From +3V to -3V or -3V to +3V
<b>RS-232 RECEIVER</b>					
<b>TTL Output Levels</b>					
$V_{OL}$			0.4	Volts	$I_{SINK} = 4mA$
$V_{OH}$	3.5			Volts	$I_{SOURCE} = -4mA$
<b>Receiver Input</b>					
High Threshold		1.7	3.0	Volts	
Low Threshold	0.8	1.2		Volts	
Input Voltage Range	-30		+30	Volts	$\pm 30V$ input @ $I_{IN} < 100mA$
Input Impedance	3	5	7	KOhms	$V_{IN}=\pm 15V$
Hysteresis	0.2	0.5	1.0	Volts	$V_{CC}=+5V$
<b>AC Characteristics</b>					
Transmission Rate			120	Kbps	
Transition Time		50		ns	Rise/fall time 10% to 90%
Propagation Delay					
$t_{PHL}$		100		ns	From 50% of $V_{IN}$ to 1.5V of $R_{OUT}$
$t_{PLH}$		100		ns	From 50% of $V_{IN}$ to 1.5V of $R_{OUT}$
<b>POWER REQUIREMENTS</b>					
No Load Supply Current		19	25	mA	No load; $V_{CC}=5.0V$ ; $T_A=25^\circ C$
Full Load Supply Current		90	120	mA	RS-232 drivers $R_L=3K\Omega$ to Gnd; DC Input RS-485 drivers $R_L=54\Omega$ from A to B; DC Input
Shutdown Supply Current		20		$\mu A$	$T_A=25^\circ C$ , $V_{CC}=5.0V$

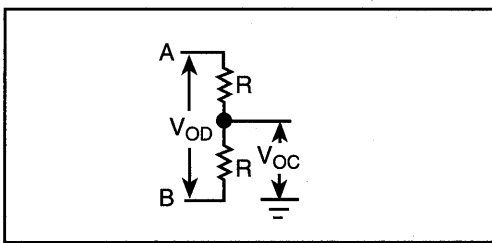


Figure 1. RS-485 Driver DC Test Load Circuit

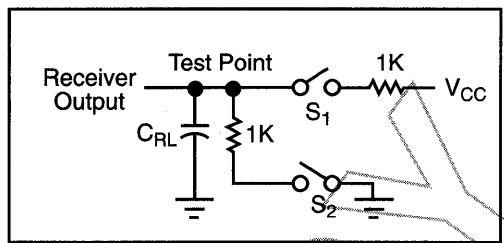


Figure 2. Receiver Timing Test Load Circuit

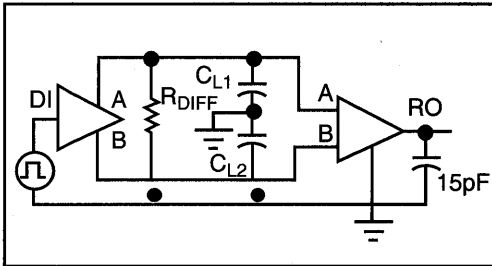


Figure 3. RS-485 Driver/Receiver Timing Test Circuit

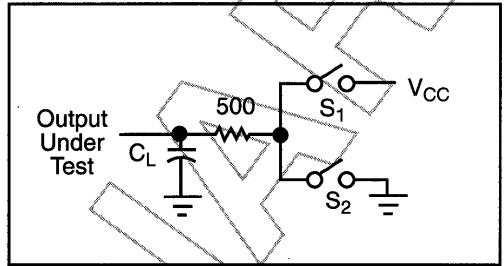


Figure 4. RS-485 Driver Timing Test Load #2 Circuit

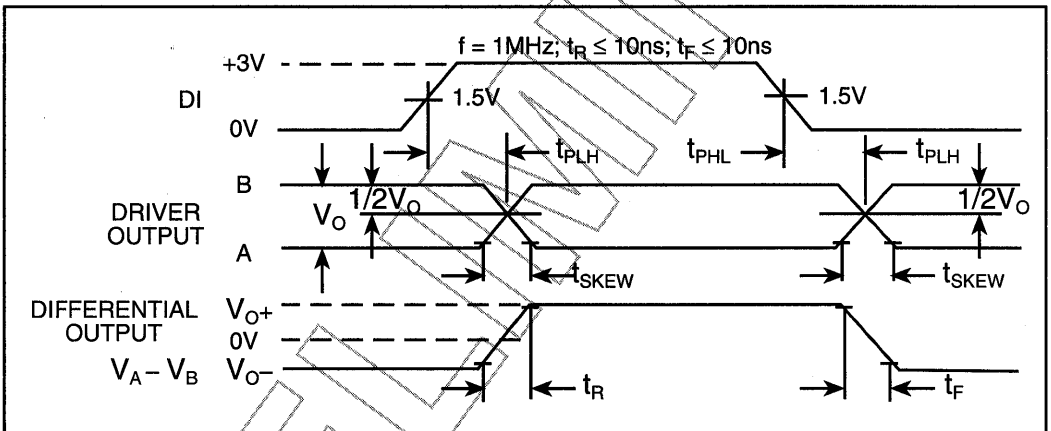


Figure 6. RS-485 Driver Propagation Delays

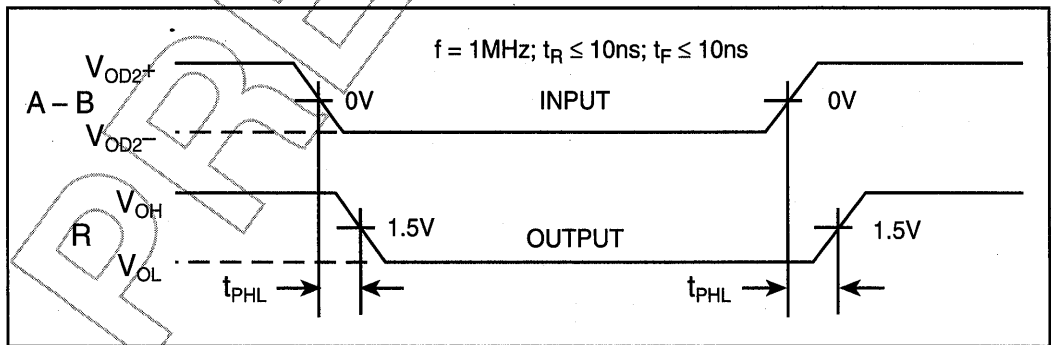


Figure 7. RS-485 Receiver Propagation Delays

## THEORY OF OPERATION...

The **SP332** is a single chip device that can be configured via software for either RS-232, RS-485 or both interface modes at any time. The **SP332** is made up of three basic circuit elements, single-ended drivers and receivers, differential drivers and receivers and charge pump.

## DIFFERENTIAL DRIVER/RECEIVER...

### RS-485, RS-422 Drivers...

The differential drivers and receivers comply with the RS-485 and RS-422 standards. The driver circuits are able to drive a minimum of 1.5V when terminated with a 54Ω resistor across the two outputs. The typical propagation delay from the driver input to output is 60nS. The driver outputs are current limited to less than 250mA, and can tolerate short circuits to ground, or to any voltage within a +10V to -7V range with no damage.

### RS-485, RS-422 Receivers...

The differential receivers of the **SP332** comply with the RS-485, RS-422 and V.11 standards. The input to the receiver is equipped with a common mode range of +12V to -7V. The input threshold over this range is a minimum of ±200mV. The differential receivers can receive data up to 10Mbps. The typical propagation delay from the receiver input to output is 90nS.

## SINGLE ENDED DRIVER/RECEIVER...

### RS-232 (V.28) Drivers...

The single-ended drivers and receivers comply with the RS-232E and V.28 standards. The drivers are inverting transmitters which accept either TTL or CMOS inputs and output the RS-232 signals with an inverted sense relative to the input logic levels. Typically, the RS-232 driver output voltage swing is ±9V with no load and is guaranteed to be greater than ±5V under full load. The drivers rely on the V+ and V- voltages generated by the on-chip charge pump to maintain proper RS-232 output levels. With worst case load conditions of 3KΩ and 2500pF, the four RS-232 drivers can still maintain ±5V output levels. The drivers can operate up to 120Kbps; the propagation delay from input to output is typically 2μS.

## RS-232 (V.28) Receivers...

The RS-232 receivers convert RS-232 input signals to inverted TTL signals. Each of the four receivers features 500mV of hysteresis margin to minimize the affects of noisy transmission lines. The inputs also have a 5KΩ resistor to ground, in an open circuit situation the input of the receiver will be forced low, committing the output to a logic high state. The input resistance will maintain 3KΩ-7KΩ over a ±15V range. The maximum operating voltage range for the receiver is ±30V, under these conditions the input current to the receiver must be limited to less than 100mA. Due to the on-chip ESD protection circuitry, the receiver inputs will be clamped to ±15V levels. The RS-232 receivers can operate up to 120Kbps.

## CHARGE PUMP...

The charge pump is a **Sipex**-patented design (5,306,954) and uses a unique approach compared to older less-efficient designs. The charge pump still requires four external capacitors, but uses a four-phase voltage shifting technique to attain symmetrical 10V power supplies. *Figure 8a* shows the waveform found on the positive side of capacitor C2, and *Figure 8b* shows the negative side of capacitor C2. There is a free-running oscillator that controls the four phases of the voltage shifting. A description of each phase follows.

### Phase 1

-Vss charge storage- During this phase of the clock cycle, the positive side of capacitors C1 and C2 are initially charged to +5V. C1+ is then switched to ground and charge in C1- is transferred to C2-. Since C2+ is connected to +5V, the voltage potential across capacitor C2 is now 10V.

### Phase 2

-Vss transfer- Phase two of the clock connects the negative terminal of C2 to the Vss storage capacitor and the positive terminal of C2 to ground, and transfers the generated -10V to C3. Simultaneously, the positive side of capacitor C1 is switched to +5V and the negative side is connected to ground.

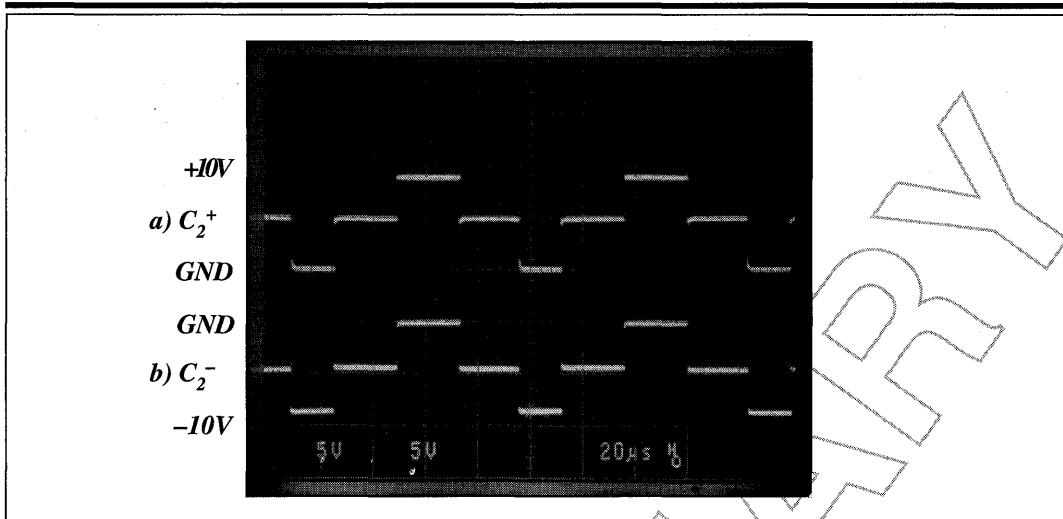


Figure 8. Charge Pump Waveforms

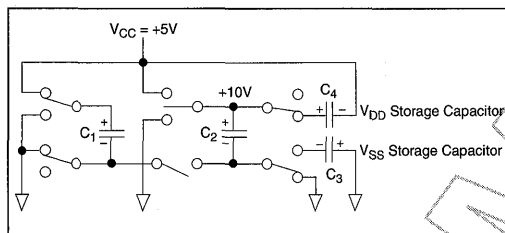


Figure 9. Charge Pump Phase 1

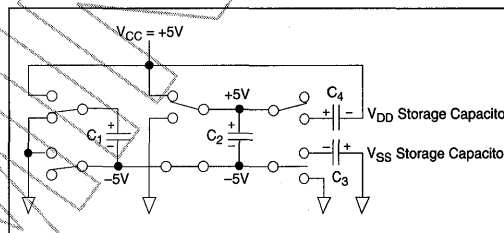


Figure 10. Charge Pump Phase 2

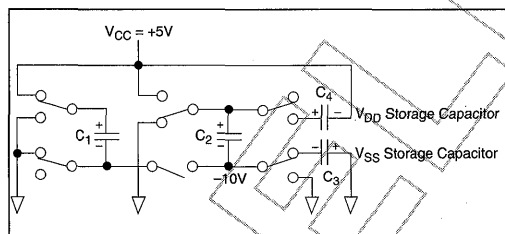


Figure 11. Charge Pump Phase 3

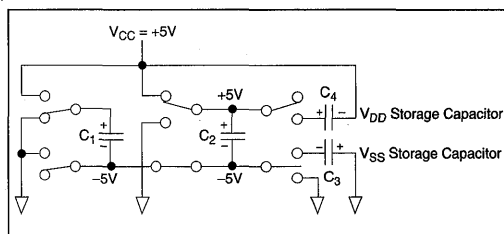


Figure 12. Charge Pump Phase 4

### Phase 3

-Vdd charge storage- The third phase of the clock is identical to the first phase- the transferred charge in C1 produces -5V in the negative terminal of C1, which is applied to the negative side of capacitor C2. Since C2+ is at +5V, the voltage potential across C2 is 10V.

### Phase 4

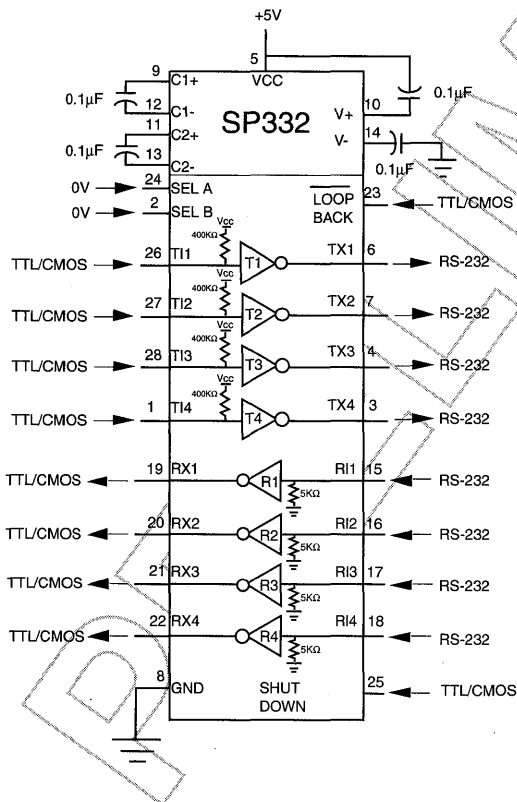
-Vdd transfer- The fourth phase of the clock connects the negative terminal of C2 to ground and transfers the generated 10V across C2 to C4, the Vdd storage capacitor. Simultaneously with this, the positive side of capacitor C1 is switched to +5V and the negative side is connected to ground, and the cycle begins again.

Since both V+ and V- are separately generated from Vcc in a no load condition, V+ and V- will be symmetrical. Older charge pump approaches that generate V- from V+ will show a decrease in the magnitude of V- compared to V+ due to the inherent inefficiencies in the design.

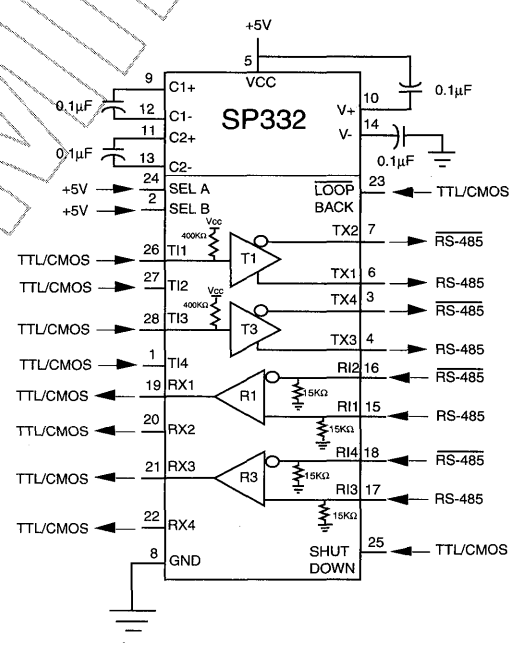
The clock rate for the charge pump typically operates at 15KHZ. The external capacitors must be 0.1μF with a 16V breakdown rating.

## SP332 TYPICAL OPERATING CIRCUIT

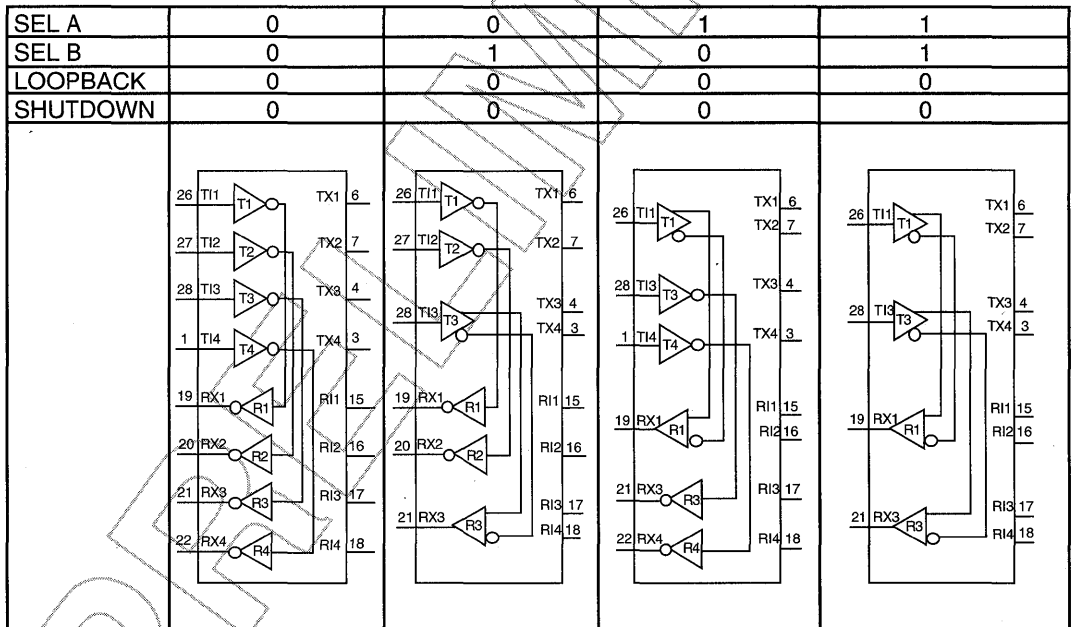
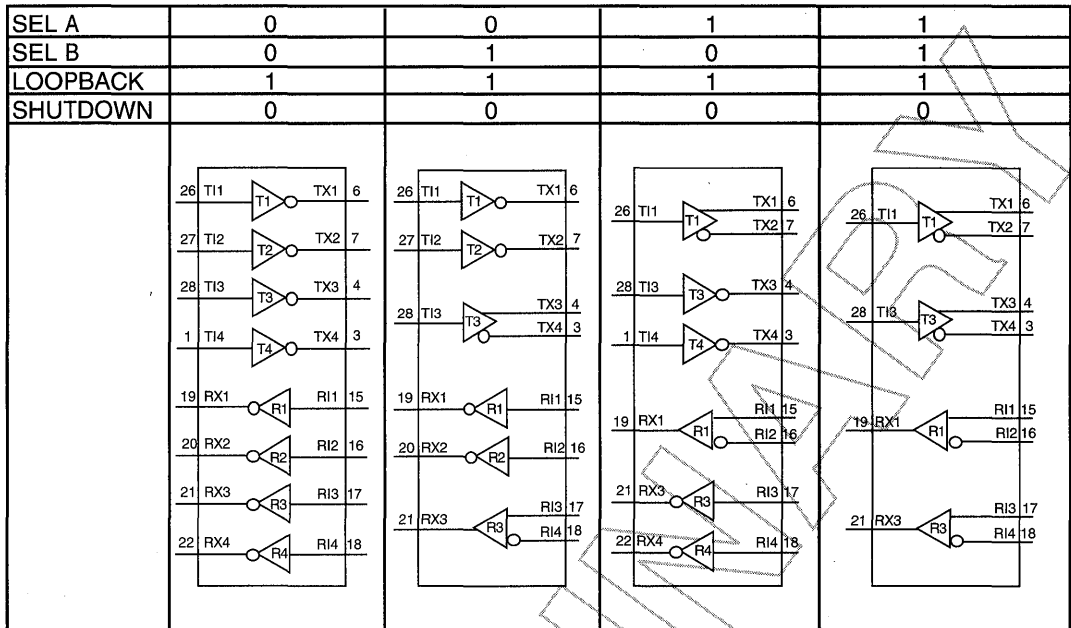
### RS-232 Mode



### RS-485 Mode

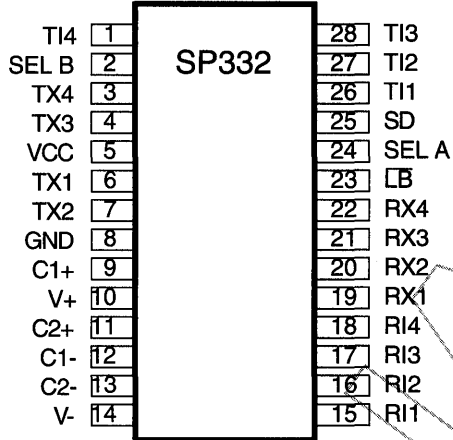


# SP332 CONTROL LOGIC CONFIGURATION



Receiver Inputs are inactive in Loopback Mode ( $\text{LOOPBACK} = 0$ )  
 Driver Outputs are Tri-States in Loopback Mode ( $\text{LOOPBACK} = 0$ )  
 Unused Outputs are Tri-States





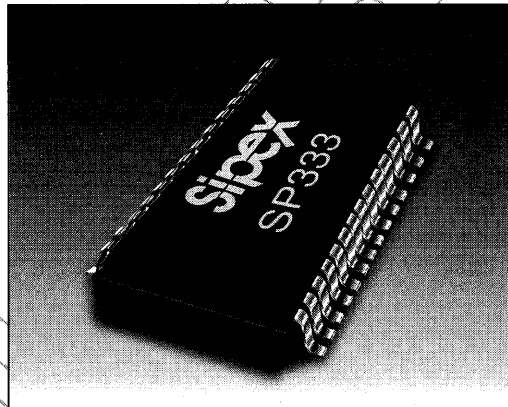
PRELIMINARY

**ORDERING INFORMATION**

<b>Model</b>	<b>Temperature Range</b>	<b>Package Types</b>
SP332CT .....	0°C to +70°C .....	28-Pin SOIC
SP332ET .....	-40°C to +85°C .....	28-Pin SOIC

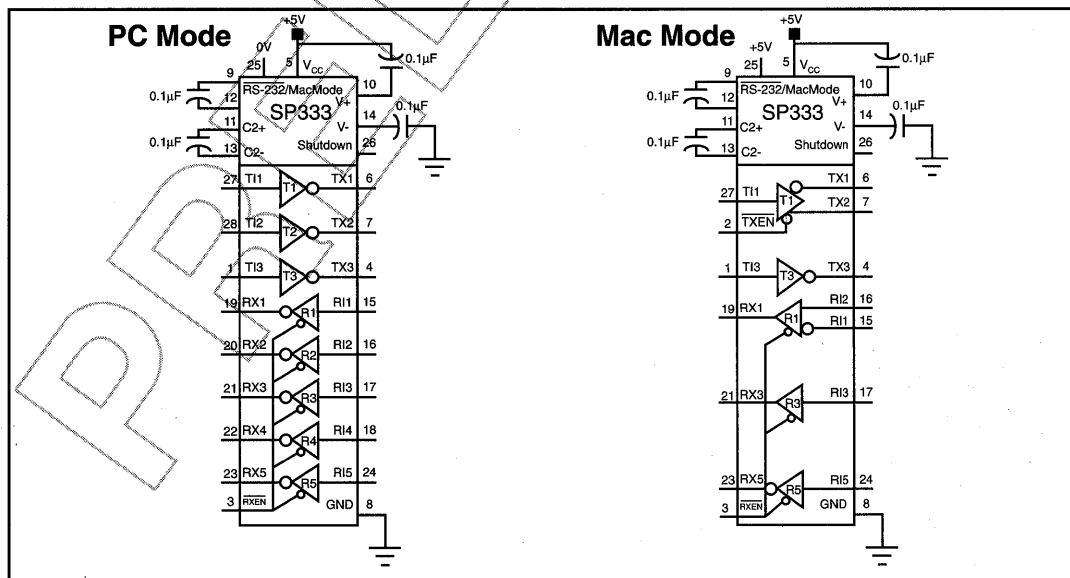
## +5V Only RS-232/AppleTalk™ Programmable Transceiver

- +5V Only
- Low Power Shutdown
- 28-Pin SOIC Packaging
- 3 Drivers, 5 Receivers – RS-232
- Complete AppleTalk™ Interface
- High Data Rates
  - 10Mbps Differential Transceivers
  - 400kpbs Single-Ended Transceivers



### DESCRIPTION...

The **SP333** is a monolithic device that supports both Macintosh™ and PC serial interfaces. RS-232 mode offers three (3) RS-232 drivers and five (5) RS-232 receivers. Mac Mode includes a differential driver and a single-ended inverting driver. Receivers in Mac mode include one differential receiver, one non-inverting single-ended receiver and one inverting single-ended receiver. An on-chip charge pump allows +5V only operation, and a low power shutdown mode makes the **SP333** ideal for battery powered applications. The interface mode can be changed at any time by a mode select pin.



## ABSOLUTE MAXIMUM RATINGS

These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

V <sub>CC</sub> .....	+12V
Input Voltages	
Logic.....	-0.3V to (V <sub>CC</sub> +0.5V)
Drivers.....	-0.3V to (V <sub>CC</sub> +0.5V)
Receivers.....	±15V
Driver Outputs.....	±14V
Storage Temperature.....	-65°C to +150°C
Power Dissipation.....	1000mW

## SPECIFICATIONS

T<sub>MIN</sub> to T<sub>MAX</sub> and V<sub>CC</sub> = 5V±5% unless otherwise noted.

PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>MAC Mode (pin 25 = +5V)</b>					
<b>Differential Driver</b>					
High Level Output Voltage			+3.6	Volts	I <sub>OH</sub> = 8mA
Low Level Output Voltage	-3.6			Volts	I <sub>OH</sub> = -8mA
Differential Output Load		±5V		Volts	R <sub>T</sub> = 450Ω (between TX outputs)
Differential Output No Load			±10	Volts	R <sub>L</sub> = ∞
Driver Short Circuit Current		±40		mA	-7V ≤ V <sub>O</sub> ≤ +7V; V <sub>IN LOW</sub> ≤ 0.8V or V <sub>IN HIGH</sub> ≥ 2.0V
Output Leakage Current			±10	μA	-7V ≤ V <sub>O</sub> ≤ +7V; TxEN = V <sub>CC</sub>
Input High Voltage	2.0			Volts	Applies to differential driver inputs
Input Low Voltage			0.8	Volts	Applies to differential driver inputs
Input Current			±10	μA	
Transition Time		30		ns	R <sub>T</sub> = 450Ω, C <sub>L</sub> = 50pF; Rise/Fall 10% - 90%
Propagation Delay					
t <sub>PHL</sub>		100		ns	R <sub>L</sub> = 450Ω, C <sub>L</sub> = 50pF
t <sub>PLH</sub>		100		ns	R <sub>L</sub> = 450Ω, C <sub>L</sub> = 50pF
Data Rate			10	Mbps	R <sub>L</sub> = 450Ω, C <sub>L</sub> = 50pF
<b>Single-Ended Inverting Driver</b>					
High Level Output Voltage	+3.6		+6.0	Volts	R <sub>T</sub> = 450Ω to GND; V <sub>IN LOW</sub> ≤ 0.8V or V <sub>IN HIGH</sub> ≥ 2.0V
Low Level Output Voltage	-6.0		-3.6	Volts	R <sub>T</sub> = 450Ω to GND; V <sub>IN LOW</sub> ≤ 0.8V or V <sub>IN HIGH</sub> ≥ 2.0V
Driver Open Circuit Voltage			±10	Volts	R <sub>L</sub> = ∞
Driver Short Circuit Current		±40		mA	-7V ≤ V <sub>O</sub> ≤ +7V; Infinite duration
Input High Voltage	2.0			Volts	Applies to differential driver inputs
Input Low Voltage			0.8	Volts	Applies to differential driver inputs
Input Current			±10	μA	
Transition Time		30		ns	R <sub>T</sub> = 450Ω, C <sub>L</sub> = 50pF; Rise/Fall 10% - 90%
Propagation Delay					
t <sub>PHL</sub>		100		ns	R <sub>L</sub> = 450Ω, C <sub>L</sub> = 50pF
t <sub>PLH</sub>		100		ns	R <sub>L</sub> = 450Ω, C <sub>L</sub> = 50pF
Data Rate			10	Mbps	R <sub>L</sub> = 450Ω, C <sub>L</sub> = 50pF
<b>Differential Receiver</b>					
Differential Input Threshold	-0.2	70	+0.2	Volts	-7V ≤ V <sub>CM</sub> ≤ +7V
Input Hysteresis				mV	V <sub>CM</sub> = 0V
Input Resistance	12			kΩ	-7V ≤ V <sub>CM</sub> ≤ +7V
Output Voltage High	3.5			Volts	I <sub>SOURCE</sub> = -4mA
Output Voltage Low			0.4	Volts	I <sub>SINK</sub> = +4mA
Short Circuit Current			85	mA	0V ≤ V <sub>OUT</sub> ≤ V <sub>CC</sub>

# SPECIFICATIONS (CONTINUED)

$T_{MIN}$  to  $T_{MAX}$  and  $V_{CC} = 5V \pm 5\%$  unless otherwise noted.

PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>Differential Receiver</b>					
Propagation Delay		100		ns	$R_L = 450\Omega, C_L = 50pF$
$t_{PHL}$		100		ns	$R_L = 450\Omega, C_L = 50pF$
$t_{PLH}$			10	Mbps	$R_L = 450\Omega, C_L = 50pF$
Data Rate					
<b>Single-Ended Inverting Receiver</b>					
Input Voltage Range	-15		+15	Volts	
Input Threshold Low	0.8	1.2		Volts	
Input Threshold High		1.7	3.0	Volts	
Hysteresis		70		mV	
Input Impedance	3	5	7	k $\Omega$	
Output Voltage High	3.5			Volts	$I_{SOURCE} = -4mA$
Output Voltage Low			0.4	Volts	$I_{SINK} = +4mA$
Propagation Delay		100		ns	
$t_{PHL}$		100		ns	
$t_{PLH}$			10	Mbps	
Data Rate					
<b>Single-Ended Non-Inverting Receiver</b>					
Input Voltage Range	-7		+7	Volts	
Input Threshold Low	-0.2			Volts	
Input Threshold High			+0.2	Volts	
Hysteresis		70		mV	
Input Impedance	12	15		k $\Omega$	
Output Voltage High	3.5			Volts	$I_{SOURCE} = -4mA$
Output Voltage Low			0.4	Volts	$I_{SINK} = +4mA$
Propagation Delay		100		ns	
$t_{PHL}$		100		ns	
$t_{PLH}$			10	Mbps	
Data Rate					
<b>PC Mode (pin 25 = GND)</b>					
<b>RS-232 Driver</b>					
TTL Input Levels			0.8	Volts	Applies to transmitter inputs
$V_{IL}$				Volts	Applies to transmitter inputs
$V_{IH}$	2.0			Volts	
High Level Voltage Output	+5.0		+15.0	Volts	$R_L = 3K\Omega$ to Gnd
Low Level Voltage Output	-15.0		-5.0	Volts	$R_L = 3K\Omega$ to Gnd
Open Circuit Output			$\pm 15$	Volts	$R_L = \infty$
Short Circuit Current			$\pm 100$	mA	$V_{OUT} = Gnd$
Power Off Impedance	300			Ohms	$V_{CC} = 0V; V_{OUT} = \pm 2V$
Slew Rate		60		V/ $\mu S$	$R_L = 3K\Omega, C_L = 50pF$ ; From +3V to -3V or -3V to +3V
Transition Time			1.56	$\mu S$	Rise/fall time, between +3V & -3V; $R_L = 3K\Omega, C_L = 2500pF$
Propagation Delay		1.5		$\mu S$	$R_L = 3K\Omega, C_L = 2500pF$ ; From 1.5V of $T_{IN}$ to 50% of $V_{OUT}$
$t_{PHL}$			1.3	$\mu S$	$R_L = 3K\Omega, C_L = 2500pF$ ; From 1.5V of $T_{IN}$ to 50% of $V_{OUT}$
$t_{PLH}$					$R_L = 3K\Omega, C_L = 2500pF$
Data Rate		400		Kbps	
<b>RS-232 Receiver</b>					
TTL Output Levels			0.4	Volts	$I_{SINK} = 4mA$
$V_{OL}$	2.4				$I_{SOURCE} = -4mA$
$V_{OH}$					
Receiver Input High Threshold		1.7	3.0	Volts	

# SPECIFICATIONS (CONTINUED)

$T_{MIN}$  to  $T_{MAX}$  and  $V_{CC} = 5V \pm 5\%$  unless otherwise noted.

PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>RS-232 Receiver</b>					
Low Threshold	0.8	1.2		Volts	$V_{IN} = \pm 15V$ $V_{CC} = +5V$  Rise/fall time: between +3V & -3V
Input Voltage Range	-15		+15	Volts	
Input Impedance	3	5	7	KOhms	
Hysteresis	0.2	0.5	1.0	Volts	
Transmission Rate			10	Mbps	
Transition Time		50		ns	
Propagation Delay					
$t_{PHL}$		100		ns	From 50% of $V_{IN}$ to 1.5V of $R_{OUT}$
$t_{PLH}$		100		ns	From 50% of $V_{IN}$ to 1.5V of $R_{OUT}$
<b>POWER REQUIREMENTS</b>					
No Load Supply Current		19	25	mA	No load; $V_{CC} = 5.0V$ ; $T_A = 25^\circ C$ $T_A = 25^\circ C$ ; $V_{CC} = 5.0V$
Shutdown Supply Current			20	$\mu A$	
<b>AC PARAMETERS</b>					
<b>Driver Delay Time from Enable Mode to Tri-state Mode</b>					
<b>Single-Ended Mode</b>					
$t_{PZL}$ ; Enable to Output low		90		ns	$C_L = 100pF$ , Figures 2 & 4, $S_2$ closed
$t_{PZH}$ ; Enable to Output high		90		ns	$C_L = 100pF$ , Figures 2 & 4, $S_1$ closed
$t_{PLZ}$ ; Disable from Output low		90		ns	$C_L = 15pF$ , Figures 2 & 4, $S_2$ closed
$t_{PHZ}$ ; Disable from Output high		90		ns	$C_L = 15pF$ , Figures 2 & 4, $S_1$ closed
<b>Differential Mode</b>					
$t_{PZL}$ ; Enable to Output low		90		ns	$C_L = 100pF$ , Figures 2 & 4, $S_2$ closed
$t_{PZH}$ ; Enable to Output high		90		ns	$C_L = 100pF$ , Figures 2 & 4, $S_1$ closed
$t_{PLZ}$ ; Disable from Output low		90		ns	$C_L = 15pF$ , Figures 2 & 4, $S_2$ closed
$t_{PHZ}$ ; Disable from Output high		90		ns	$C_L = 15pF$ , Figures 2 & 4, $S_1$ closed
<b>Receiver Delay Time from Enable Mode to Tri-state Mode</b>					
<b>Single-Ended Mode</b>					
$t_{PZL}$ ; Enable to Output low		90		ns	$C_{RL} = 15pF$ , Figures 1 & 6, $S_1$ closed
$t_{PZH}$ ; Enable to Output high		90		ns	$C_{RL} = 15pF$ , Figures 1 & 6, $S_2$ closed
$t_{PLZ}$ ; Disable from Output low		90		ns	$C_{RL} = 15pF$ , Figures 1 & 6, $S_1$ closed
$t_{PHZ}$ ; Disable from Output high		90		ns	$C_{RL} = 15pF$ , Figures 1 & 6, $S_2$ closed
<b>Differential Mode</b>					
$t_{PZL}$ ; Enable to Output low		90		ns	$C_{RL} = 15pF$ , Figures 1 & 6, $S_1$ closed
$t_{PZH}$ ; Enable to Output high		90		ns	$C_{RL} = 15pF$ , Figures 1 & 6, $S_2$ closed
$t_{PLZ}$ ; Disable from Output low		90		ns	$C_{RL} = 15pF$ , Figures 1 & 6, $S_1$ closed
$t_{PHZ}$ ; Disable from Output high		90		ns	$C_{RL} = 15pF$ , Figures 1 & 6, $S_2$ closed

**Notes:**

1. Measured from 2.5V of  $R_{IN}$  to 2.5V of  $R_{OUT}$ .
2. Measured from one-half of  $R_{IN}$  to 2.5V of  $R_{OUT}$ .
3. Measured from 1.5V of  $T_{IN}$  to one-half of  $T_{OUT}$ .
4. Measured from 2.5V of  $R_O$  to 0V of A and B.

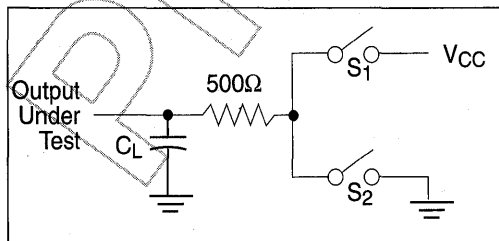


Figure 1. Receiver Timing Test Load Circuit

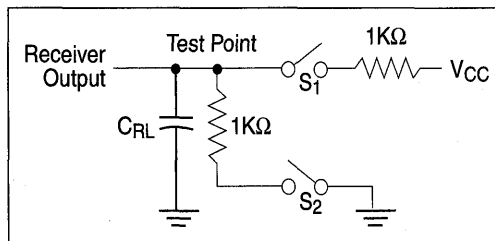


Figure 2. Driver Timing Test Load Circuit

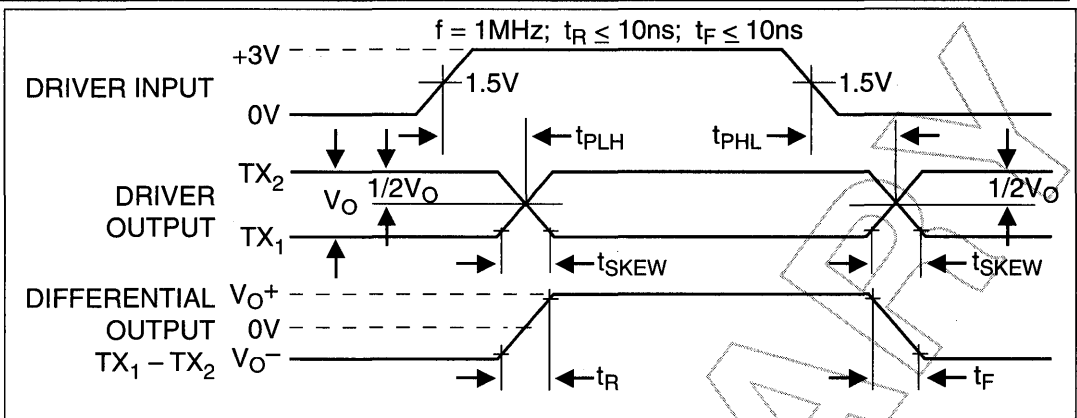


Figure 3. Driver Propagation Delays

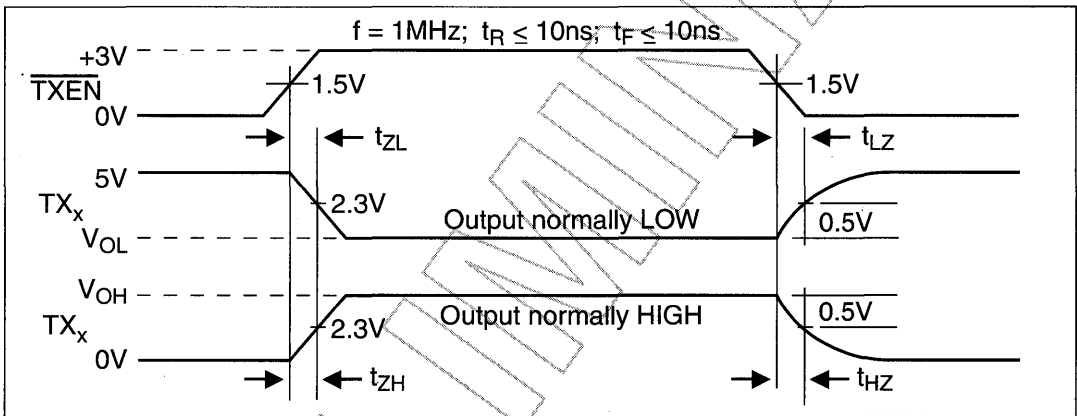


Figure 4. Driver Enable and Disable Times

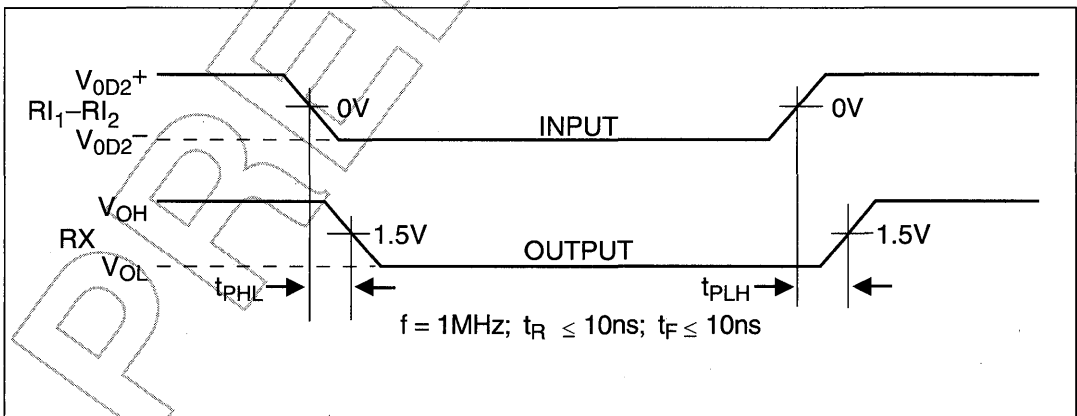


Figure 5. Receiver Propagation Delays

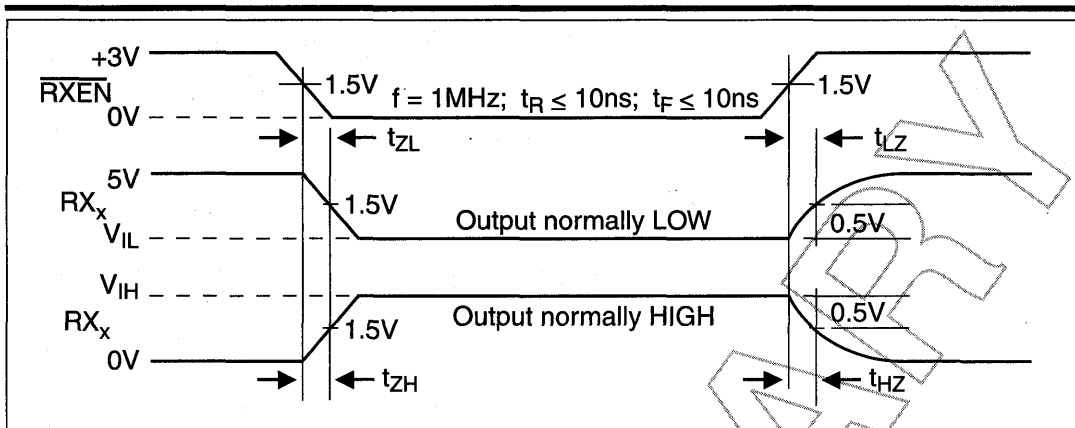


Figure 6. Receiver Enable and Disable Times

## THEORY OF OPERATION...

The **SP333** is a single chip device that can be configured via software for either RS-232 or AppleTalk™ interface modes at any time. The **SP333** is made up of three basic circuit elements; single-ended drivers and receivers, differential drivers and receivers and charge pump.

## APPLETALK™ DRIVERS/RECEIVERS...

To program the **SP333** for MacMode, pin 25 should be connected to a logic high. In MacMode, the **SP333** offers a complete AppleTalk serial interface.

The driver section of the AppleTalk interface is made up of a differential driver and a single-ended inverting driver. The differential driver has voltage swings that are typically  $\pm 5V$  on each output pin under loaded conditions, and typically  $\pm 8V$  under no-load conditions. The differential driver can maintain  $\pm 3.6V$  (minimum) swings (per pin) under worst case load conditions of  $450\Omega$  between the differential output.

The differential driver is equipped with a tri-state control pin. When  $\overline{TXEN}$  is a logic low, the differential driver is active. When the  $\overline{TXEN}$  pin is a logic high, the differential driver outputs are tri-stated. The  $\overline{TXEN}$  pin only functions in MacMode. The differential AppleTalk driver can support data rates up to 10Mbps.

The single-ended AppleTalk driver also has typical voltage output swings of  $\pm 5V$  under loaded conditions, and  $\pm 8V$  under no-load conditions. The single-ended AppleTalk driver can maintain  $\pm 3.6V$  (minimum) swings under worst case conditions of  $450\Omega$  to ground. The single-ended AppleTalk driver can support data rates over 400Kbps.

The receiver section of the **SP333** is made up of a differential receiver, a single-ended non-inverting receiver, and a single-ended inverting receiver. The differential receiver has an input sensitivity of  $\pm 200mV$  over a common mode range of  $\pm 7V$ . The receivers have a typical input resistance of  $15K\Omega$  ( $12K\Omega$  minimum). The differential receiver can receive data up to 10Mbps.

The single-ended non-inverting receiver has a  $\pm 200mV$  input threshold, however, the input voltage can vary between  $\pm 7V$ . The typical input resistance of the single-ended non-inverting receiver is  $15K\Omega$  ( $12K\Omega$  minimum). The single-ended non-inverting receiver can also receive data up to 10Mbps.

The **SP333** also has a single-ended inverting receiver input. This receiver is basically an RS-232 receiver (R5 receiver) and is typically used as a GPI (General Purpose Input) in the AppleTalk interface. The GPI input has TTL-compatible input thresholds that can receive signals up to  $\pm 15V$ . The input resistance of the



single-ended inverting receiver is typically  $5K\Omega$  ( $3K\Omega$  to  $7K\Omega$ ). The GPI receiver can operate up to 10Mbps.

## SINGLE ENDED DRIVERS/RECEIVERS...

### RS-232 (V.28) Drivers...

The single-ended drivers and receivers comply with the RS-232E and V.28 standards. The drivers are inverting transmitters which accept either TTL or CMOS inputs and output the RS-232 signals with an inverted sense relative to the input logic levels. Typically, the RS-232 driver output voltage swing is  $\pm 9V$  with no load and is guaranteed to be greater than  $\pm 5V$  under full load. The drivers rely on the V+ and V- voltages generated by the on-chip charge pump to maintain proper RS-232 output levels. With worst case load conditions of  $3K\Omega$  and  $2500pF$ , the four RS-232 drivers can still maintain  $\pm 5V$  output levels. The drivers can operate over 400Kbps; the propagation delay from input to output is typically  $1.5\mu s$ . During shutdown, the driver outputs will be put into a high impedance tri-state mode.

### RS-232 (V.28) Receivers...

The RS-232 receivers convert RS-232 input signals to inverted TTL signals. Each of the four receivers features 500mV of hysteresis margin

to minimize the affects of noisy transmission lines. The inputs also have a  $5K\Omega$  resistor to ground, in an open circuit situation the input of the receiver will be forced low, committing the output to a logic high state. The input resistance will maintain  $3K\Omega$ - $7K\Omega$  over a  $\pm 15V$  range. The maximum operating voltage range for the receiver is  $\pm 30V$ , under these conditions the input current to the receiver must be limited to less than 100mA. Due to the on chip ESD protection circuitry, the receiver inputs will be clamped to  $\pm 15V$  levels; this should not affect operation at  $\pm 30$  volts. The RS-232 receivers can operate over 400Kbps.

## CHARGE PUMP...

The charge pump is a Sipex-patented design (5,306,954) and uses a unique approach compared to older less-efficient designs. The charge pump still requires four external capacitors, but uses a four-phase voltage shifting technique to attain symmetrical 10V power supplies. The capacitor values of the SP333 can be as low as  $0.1\mu F$ . Figure 11a shows the waveform found on the positive side of capacitor C2, and Figure 11b shows the negative side of capacitor C2. There is a free-running oscillator that controls the four phases of the voltage shifting. A description of each phase follows.

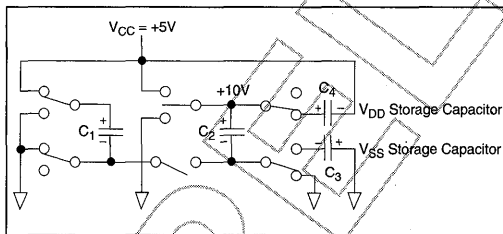


Figure 7. Charge Pump Phase 1

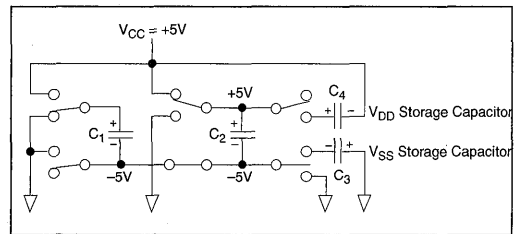


Figure 8. Charge Pump Phase 2

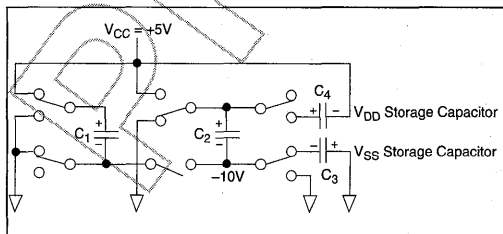


Figure 9. Charge Pump Phase 3

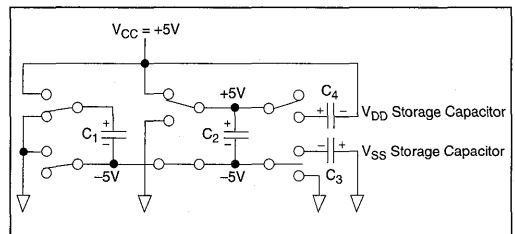


Figure 10. Charge Pump Phase 4

### Phase 1

-Vss charge storage- During this phase of the clock cycle, the positive side of capacitors C1 and C2 are initially charged to +5V. C1+ is then switched to ground and charge in C1- is transferred to C2-. Since C2+ is connected to +5V; the voltage potential across capacitor C2 is now 10V.

### Phase 2

-Vss transfer- Phase two of the clock connects the negative terminal of C2 to the Vss storage capacitor and the positive terminal of C2 to ground, and transfers the generated -10V to C3. Simultaneously, the positive side of capacitor C1 is switched to +5V and the negative side is connected to ground.

### Phase 3

-Vdd charge storage- The third phase of the clock is identical to the first phase- the transferred charge in C1 produces -5V in the negative terminal of C1, which is applied to the negative side of capacitor C2. Since C2+ is at +5V, the voltage potential across C2 is 10V.

### Phase 4

-Vdd transfer- The fourth phase of the clock connects the negative terminal of C2 to ground and transfers the generated 10V across C2 to C4,

the Vdd storage capacitor. Simultaneously with this, the positive side of capacitor C1 is switched to +5V and the negative side is connected to ground, and the cycle begins again.

Since both V+ and V- are separately generated from Vcc in a no load condition, V+ and V- will be symmetrical. Older charge pump approaches that generate V- from V+ will show a decrease in the magnitude of V- compared to V+ due to the inherent inefficiencies in the design.

The clock rate for the charge pump typically operates at 15KHZ. The external capacitors should be 0.1 $\mu$ F with a 16V breakdown rating.

### External Power Supplies

For applications that do not require +5V only, external supplies can be applied at the V+ and V- pins. The value of the external supply voltages must be no greater than  $\pm 10V$ . The current drain from the  $\pm 10V$  supplies is used for the RS-232 drivers. For the RS-232 driver, the current requirement is 3.5mA per driver. The external power supplies should provide a power supply sequence of either: +10V, -10V, and then +5V; or -10V, +10V, and then +5V. It is critical that the  $\pm 10V$  supplies are on before V<sub>cc</sub>.

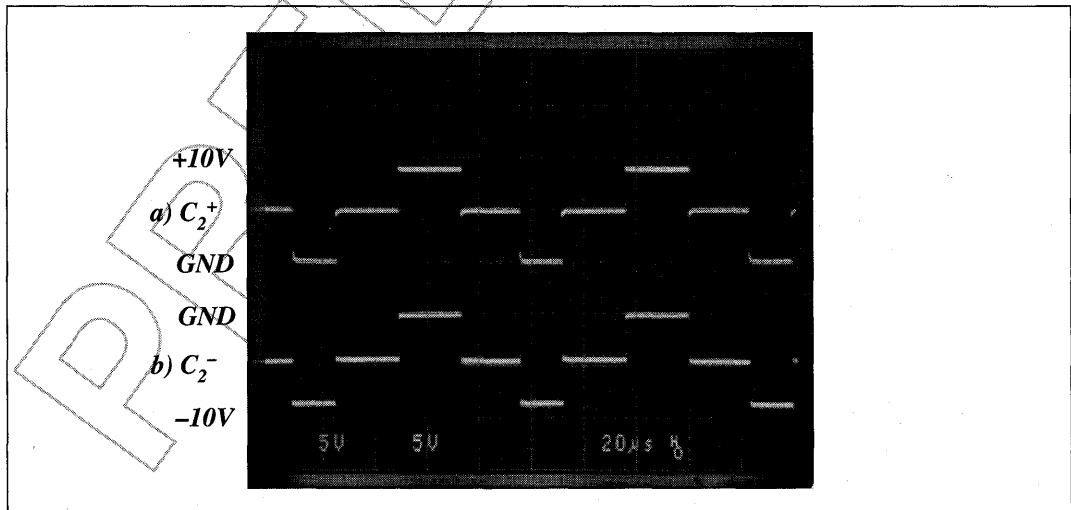


Figure 11. Charge Pump Waveforms

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## Shutdown Mode

The SP333 can be put into a low power shutdown mode by connecting the Shutdown pin (SD, pin 26) to a logic high. During shutdown, the driver outputs are put into a high impedance tri-state, and the charge pump is put into stand-by mode. The supply current drops to less than 10 $\mu$ A during shutdown and can be activated in either RS-232 or AppleTalk mode. For normal operation, the SD pin should be connected to a logic low.

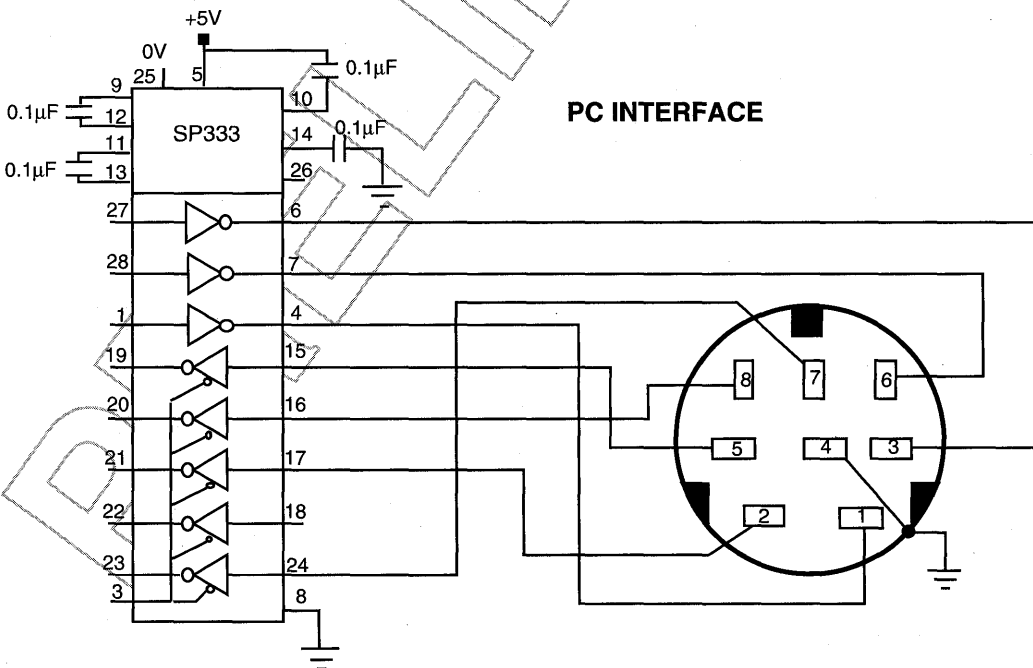
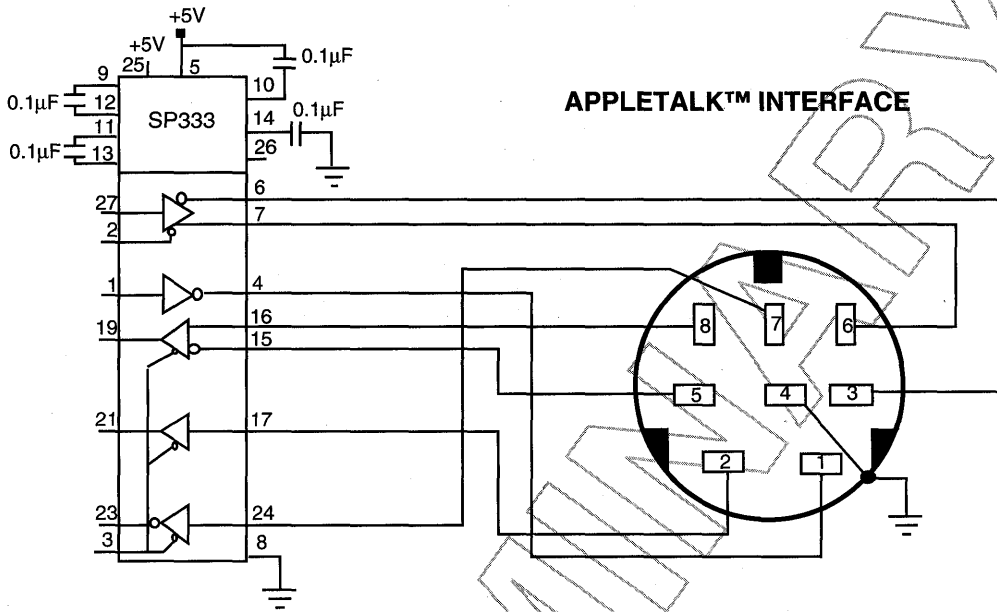
## Receiver Enable

The SP333 has a control line to enable or disable the receiver outputs. Pin 3 ( $\overline{\text{RXEN}}$ ) is active low; a logic low on pin 3 will enable the receiver outputs. A logic high on pin 3 will disable the receiver outputs. The receiver enable function can be initiated in either RS-232 or AppleTalk mode.

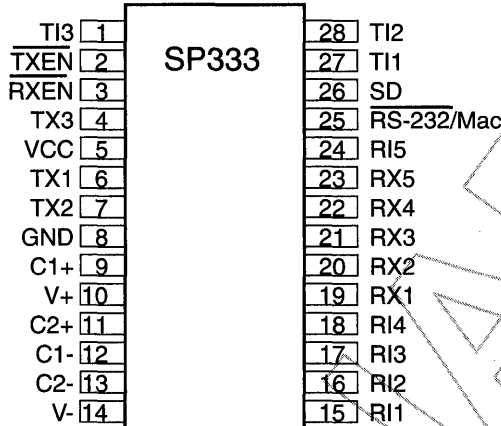
## Wake Up

The SP333 also features a "wake up" function. The wake up function allows the RS-232 receivers to remain active during shutdown mode unless they are disabled by the receiver enable control pin (pin 3). The wake up feature allows users to take advantage of the low power shutdown mode and keep the receivers active to accept an incoming "ring indicator" signal.

# SP333 Typical Application for AppleTalk™ and RS-232

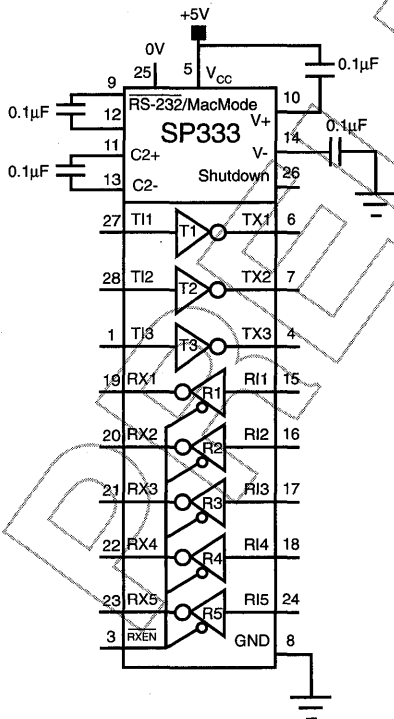


# SP333 PIN CONFIGURATION

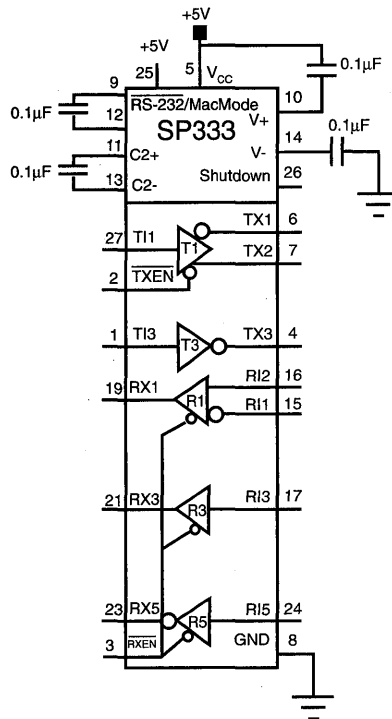


# SP333 TYPICAL OPERATING CIRCUIT

## PC Mode (RS-232)



## Mac Mode (AppleTalk)



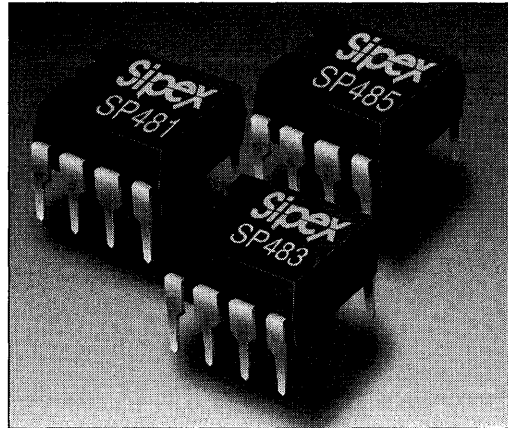
PRELIMINARY

**ORDERING INFORMATION**

<b>Model</b>	<b>Temperature Range</b>	<b>Package Types</b>
SP333CT .....	.0°C to +70°C .....	28-Pin SOIC .....
SP333ET .....	-40°C to +85°C .....	28-Pin SOIC .....

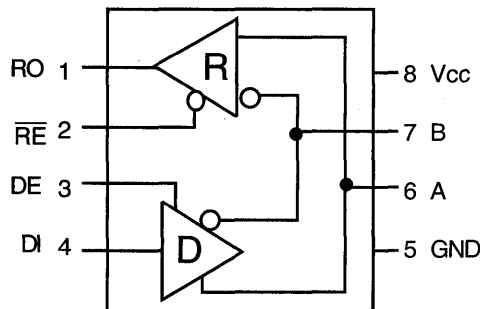
## Low Power Half-Duplex RS-485 Transceivers

- +5V Only
- Low Power BiCMOS
- Driver/Receiver Enable
- Slew Rate Limited Driver for Low EMI (SP483)
- Low Power Shutdown Mode (SP481 and SP483)
- RS-485 and RS-422 Drivers/Receivers



### DESCRIPTION...

The **SP481**, **SP483**, and the **SP485** are a family of half-duplex transceivers that meet the requirements of RS-485 and RS-422. Their BiCMOS design allows low power operation without sacrificing performance. The **SP481** and **SP485** meet the requirements of RS-485 and RS-422 up to 5Mbps. Additionally, the **SP481** is equipped with a low power Shutdown mode. The **SP483** is internally slew rate limited to reduce EMI and can meet the requirements of RS-485 and RS-422 up to 250kbps. The **SP483** is also equipped with a low power Shutdown mode.



SP481, SP483, and SP485

# ABSOLUTE MAXIMUM RATINGS

These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

V <sub>CC</sub> .....	±12V
Input Voltages	
Logic.....	-0.3V to (V <sub>CC</sub> +0.5V)
Drivers.....	-0.3V to (V <sub>CC</sub> +0.5V)
Receivers.....	±15V
Output Voltages	
Logic.....	-0.3V to (V <sub>CC</sub> +0.5V)
Drivers.....	±15V
Receivers.....	-0.3V to (V <sub>CC</sub> +0.5V)
Storage Temperature.....	-65°C to +150°C
Power Dissipation.....	500mW

# SPECIFICATIONS

T<sub>MIN</sub> to T<sub>MAX</sub> and V<sub>CC</sub> = 5V ± 5% unless otherwise noted.

PARAMETERS	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>SP481/SP483/SP485 DRIVER</b>					
<b>DC Characteristics</b>					
Differential Output Voltage	GND		V <sub>CC</sub>	Volts	Unloaded; R = ∞ ; see figure 1 with load; R = 50Ω; (RS422); see figure 1
Differential Output Voltage	2		V <sub>CC</sub>	Volts	
Differential Output Voltage	1.5		V <sub>CC</sub>	Volts	with load; R = 27Ω; (RS485); see figure 1
Change in Magnitude of Driver Differential Output Voltage for Complimentary States			0.2	Volts	R = 27Ω or R = 50Ω; see figure 1
Driver Common-Mode Output Voltage			3	Volts	R = 27Ω or R = 50Ω; see figure 1
Input High Voltage	2.0			Volts	Applies to DE, DI, RE
Input Low Voltage			0.8	Volts	Applies to DE, DI, RE
Input Current			±10	µA	Applies to DE, DI, RE
Driver Short-Circuit Current					
V <sub>OUT</sub> = HIGH	35		250	mA	-7V ≤ V <sub>O</sub> ≤ +12V
V <sub>OUT</sub> = LOW	35		250	mA	-7V ≤ V <sub>O</sub> ≤ +12V
<b>SP481/SP485 DRIVER</b>					
<b>AC Characteristics</b>					
Driver Data Rate			5	Mbps	RE = 5V, DE = 5V
Driver Input to Output	20	30	60	ns	t <sub>PLH</sub> ; R <sub>DIFF</sub> = 54Ω, C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 3 and 6
Driver Input to Output	20	30	60	ns	t <sub>PHL</sub> ; R <sub>DIFF</sub> = 54Ω, C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 3 and 6
Driver Skew		5	10	ns	From output to output; see figures 3 and 6
Driver Rise or Fall Time	3	15	40	ns	From 10% to 90%; R <sub>DIFF</sub> = 54Ω, C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 3 and 6
Driver Enable to Output High		40	70	ns	C <sub>L</sub> = 100pF; see figures 4 & 7; S <sub>2</sub> closed
Driver Enable to Output Low		40	70	ns	C <sub>L</sub> = 100pF; see figures 4 & 7; S <sub>2</sub> closed
Driver Disable Time from Low		40	70	ns	C <sub>L</sub> = 15pF; see figures 2 & 9; S <sub>1</sub> closed
Driver Disable Time from High		40	70	ns	C <sub>L</sub> = 15pF; see figures 2 & 9; S <sub>2</sub> closed
<b>SP481/SP483/SP485 RECEIVER</b>					
<b>DC Characteristics</b>					
Differential Input Threshold	-0.2		+0.2	Volts	-7V ≤ V <sub>CM</sub> ≤ +12V
Input Hysteresis		10		mV	V <sub>CM</sub> = 0V
Output Voltage High	3.5			Volts	I <sub>O</sub> = -4mA, V <sub>ID</sub> = +200mV
Output Voltage Low			0.4	Volts	I <sub>O</sub> = +4mA, V <sub>ID</sub> = -200mV
Three-State (High Impedance) Output Current			±1	µA	0.4V ≤ V <sub>O</sub> ≤ 2.4V; RE = 5V
Input Resistance	12	15		kΩ	-7V ≤ V <sub>CM</sub> ≤ +12V
Input Current (A, B); V <sub>IN</sub> = 12V			+1.0	mA	DE = 0V, V <sub>CC</sub> = 0V or 5.25V, V <sub>IN</sub> = 12V
Input Current (A, B); V <sub>IN</sub> = -7V			-0.8	mA	DE = 0V, V <sub>CC</sub> = 0V or 5.25V, V <sub>IN</sub> = -7V
Short-Circuit Current	7		95	mA	0V ≤ V <sub>CM</sub> ≤ V <sub>CC</sub>



# SPECIFICATIONS (continued)

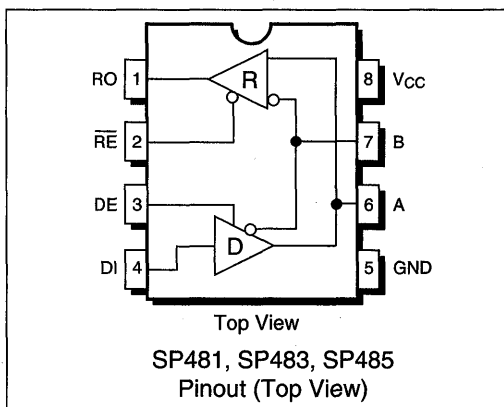
T<sub>MIN</sub> to T<sub>MAX</sub> and V<sub>CC</sub> = 5V ± 5% unless otherwise noted.

PARAMETERS	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>SP481/SP485 RECEIVER</b>					
<b>AC Characteristics</b>					
Receiver Data Rate			5	Mbps	$\overline{RE} = 0V, DE = 0V$
Receiver Input to Output	60	90	200	ns	$t_{PLH}; R_{DIFF} = 54\Omega,$ $C_{L1} = C_{L2} = 100pF; \text{ Figures 3 \& 8}$
Receiver Input to Output	60	90	200	ns	$t_{PHL}; R_{DIFF} = 54\Omega,$ $C_{L1} = C_{L2} = 100pF; \text{ Figures 3 \& 8}$
Diff. Receiver Skew $t_{PLH} - t_{PHL}$		13		ns	$R_{DIFF} = 54\Omega; C_{L1} = C_{L2} = 100pF;$ <i>Figures 3 &amp; 8</i>
Receiver Enable to Output Low		20	50	ns	$C_{RL} = 15pF; \text{ Figures 2 \& 9, } S_1 \text{ closed}$
Receiver Enable to Output High		20	50	ns	$C_{RL} = 15pF; \text{ Figures 2 \& 9, } S_2 \text{ closed}$
Receiver Disable from Low		20	50	ns	$C_{RL} = 15pF; \text{ Figures 2 \& 9, } S_1 \text{ closed}$
Receiver Disable from High		20	50	ns	$C_{RL} = 15pF; \text{ Figures 2 \& 9, } S_2 \text{ closed}$
<b>SP481</b>					
<b>Shutdown Timing</b>					
Time to Shutdown	50	200	600	ns	$\overline{RE} = 5V, DE = 0V$
Driver Enable from Shutdown to Output High		40	100	ns	$C_L = 100pF; \text{ See figures 4 \& 7; } S_2 \text{ closed}$
Driver Enable from Shutdown to Output Low		40	100	ns	$C_L = 100pF; \text{ See figures 4 \& 7; } S_1 \text{ closed}$
Receiver Enable from Shutdown to Output High		300	1000	ns	$C_L = 15pF; \text{ See figures 2 \& 9; } S_1 \text{ closed}$
Receiver Enable from Shutdown to Output Low		300	1000	ns	$C_L = 15pF; \text{ See figures 2 \& 9; } S_2 \text{ closed}$
<b>POWER REQUIREMENTS</b>					
Supply Voltage	+4.75		+5.25	Volts	
Supply Current					
<b>SP481/485</b>					
No Load		500	900	$\mu A$	$\overline{RE}, DI = 0V \text{ or } V_{CC}; DE = V_{CC}$
		300		$\mu A$	$\overline{RE} = 0V, DI = 0V \text{ or } 5V; DE = 0V$
<b>SP483</b>					
No Load		350	650	$\mu A$	$\overline{RE}, DI = 0V \text{ or } V_{CC}; DE = V_{CC}$
		250		$\mu A$	$\overline{RE} = 0V, DI = 0V \text{ or } 5V; DE = 0V$
<b>SP481/SP483</b>					
Shutdown Mode			10	$\mu A$	$DE = 0V, \overline{RE} = V_{CC}$
<b>ENVIRONMENTAL AND MECHANICAL</b>					
<b>Operating Temperature</b>					
Commercial ( <u>C</u> )	0		+70	°C	
Industrial ( <u>E</u> )	-40		+85	°C	
Storage Temperature	-65		+150	°C	
<b>Package</b>					
Plastic DIP ( <u>S</u> )					
NSOIC ( <u>N</u> )					

# SP483 AC SPECIFICATIONS

$T_{MIN}$  to  $T_{MAX}$  and  $V_{CC} = 5V \pm 5\%$  unless otherwise noted.

PARAMETERS	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>SP483 DRIVER</b>					
<b>AC Characteristics</b>					
Driver Data Rate			250	kbps	
Driver Input to Output	250	800	2000	ns	$t_{PLH}$ ; $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$ ; see figures 3 & 6
Driver Skew	250	800	2000	ns	$t_{PHL}$ ; $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$ ; see figures 3 & 6
Driver Rise and Fall Time		100	800	ns	From output to output; see figures 3 & 6
	250		2000	ns	From 10% to 90%; $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$ ; see figures 3 & 6
Driver Enable to Output High	250		2000	ns	$C_L = 100pF$ ; See figures 4 & 7; $S_2$ closed
Driver Enable to Output Low	250		2000	ns	$C_L = 100pF$ ; See figures 4 & 7; $S_2$ closed
Driver Disable Time from Low	300		3000	ns	$C_L = 15pF$ ; See figures 4 & 7; $S_1$ closed
Driver Disable Time from High	300		3000	ns	$C_L = 15pF$ ; See figures 4 & 7; $S_2$ closed
<b>SP483 RECEIVER</b>					
<b>AC Characteristics</b>					
Receiver Data Rate			250	kbps	
Receiver Input to Output	250		2000	ns	$t_{PLH}$ ; $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$ ; Figures 3 & 8
Diff. Receiver Skew $t_{PLH} - t_{PHL}$		100		ns	$R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$ ; Figures 3 & 8
Receiver Enable to Output Low		20	50	ns	$C_{RL} = 15pF$ ; Figures 2 & 9; $S_1$ closed
Receiver Enable to Output High		20	50	ns	$C_{RL} = 15pF$ ; Figures 2 & 9; $S_2$ closed
Receiver Disable from Low		20	50	ns	$C_{RL} = 15pF$ ; Figures 2 & 9; $S_1$ closed
Receiver Disable from High		20	50	ns	$C_{RL} = 15pF$ ; Figures 2 & 9; $S_2$ closed
<b>SP483 Shutdown Timing</b>					
Time to Shutdown	50	200	600	ns	$\overline{RE} = 5V$ , $DE = 0V$
Driver Enable from Shutdown to Output High			2000	ns	$C_L = 100pF$ ; See figures 4 & 7; $S_2$ closed
Driver Enable from Shutdown to Output Low			2000	ns	$C_L = 100pF$ ; See figures 4 & 7; $S_1$ closed
Receiver Enable from Shutdown to Output High			2500	ns	$C_L = 15pF$ ; See figures 4 & 7; $S_1$ closed
Receiver Enable from Shutdown to Output Low			2500	ns	$C_L = 15pF$ ; See figures 4 & 7; $S_2$ closed



## PIN FUNCTION

Pin#	Name	Description
1	RO	Receiver Output.
2	$\overline{RE}$	Receiver Output Enable Active LOW.
3	DE	Driver Output Enable Active HIGH.
4	DI	Driver Input.
5	GND	Ground Connection.
6	A	Driver Output/Receiver Input Non-inverting.
7	B	Driver Output/Receiver Input Inverting.
8	Vcc	Positive Supply $4.75V < V_{CC} < 5.25V$ .

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## DESCRIPTION...

### SP481, SP483, SP485

The **SP481**, **SP483**, and **SP485** are half-duplex differential transceivers that meet the requirements of RS-485 and RS-422. Fabricated with a Sipex proprietary BiCMOS process, all three products require a fraction of the power of older bipolar designs.

The RS-485 standard is ideal for multi-drop applications and for long-distance interfaces. RS-485 allows up to 32 drivers and 32 receivers to be connected to a data bus, making it an ideal choice for multi-drop applications. Since the cabling can be as long as 4,000 feet, RS-485 transceivers are equipped with a wide (-7V to +12V) common mode range to accommodate ground potential differences. Because RS-485 is a differential interface, data is virtually immune to noise in the transmission line.

## Drivers...

### SP481, SP483, SP485

The driver outputs of the **SP481**, **SP483**, and **SP485** are differential outputs meeting the RS-485 and RS-422 standards. The typical voltage output swing with no load will be 0 volts to +5 volts. With worst case loading of 54 $\Omega$  across the differential outputs, the drivers can maintain greater than 1.5V voltage levels. The drivers of the **SP481**, **SP483** and **SP485** have an enable control line which is active HIGH. A logic HIGH on DE (pin 5) will enable the differential driver outputs. A logic LOW on DE (pin 5) will tri-state the driver outputs.

The transmitters of the **SP481** and **SP485** will operate up to 5Mbps. The **SP483** has internally slew rate limited driver outputs to minimize EMI. The maximum data rate for the **SP483** driver is 250kbps.

## Receivers...

### SP481, SP483, SP485

The **SP481**, **SP483**, and **SP485** receivers have differential inputs with an input sensitivity as low as  $\pm 200\text{mV}$ . Input impedance of the receivers is typically 15k $\Omega$  (12k $\Omega$  minimum). A wide common mode range of -7V to +12V allows for large ground potential differences between systems. The receivers of the **SP481**, **SP483** and **SP485** have a tri-state enable control pin. A logic LOW on RE (pin 4) will enable the receiver, a logic HIGH on RE (pin 4) will disable the receiver.

The receiver for the **SP481** and **SP485** will operate up to 5Mbps. The **SP483** receiver is rated for data rates up to 250kbps. The receiver for each of the three devices is equipped with the fail-safe feature. Fail-safe guarantees that the receiver output will be in a HIGH state when the input is left unconnected.

## Shutdown Mode...

### SP481/SP483

The **SP481** and **SP483** are equipped with a Shutdown mode. To enable the Shutdown state, both the driver and receiver must be disabled simultaneously. A logic LOW on DE (pin 5) and a logic HIGH on RE (pin 4) will put the **SP481** or **SP483** into Shutdown mode. In Shutdown, supply current will drop to typically 1 $\mu\text{A}$ .

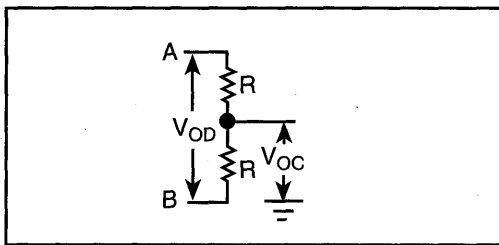


Figure 1. Driver DC Test Load Circuit

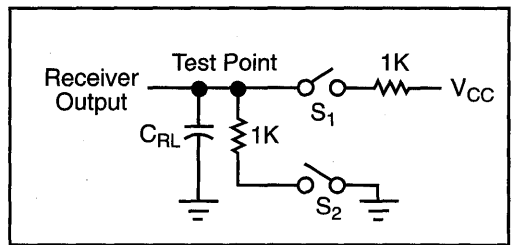


Figure 2. Receiver Timing Test Load Circuit

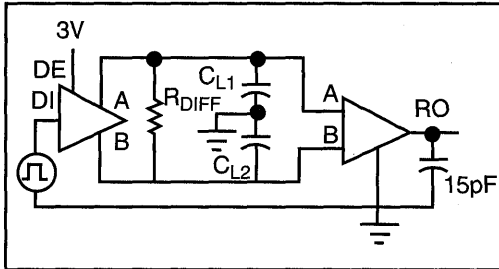


Figure 3. Driver/Receiver Timing Test Circuit

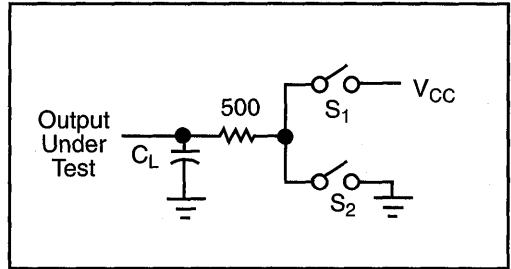


Figure 4. Driver Timing Test Load #2 Circuit

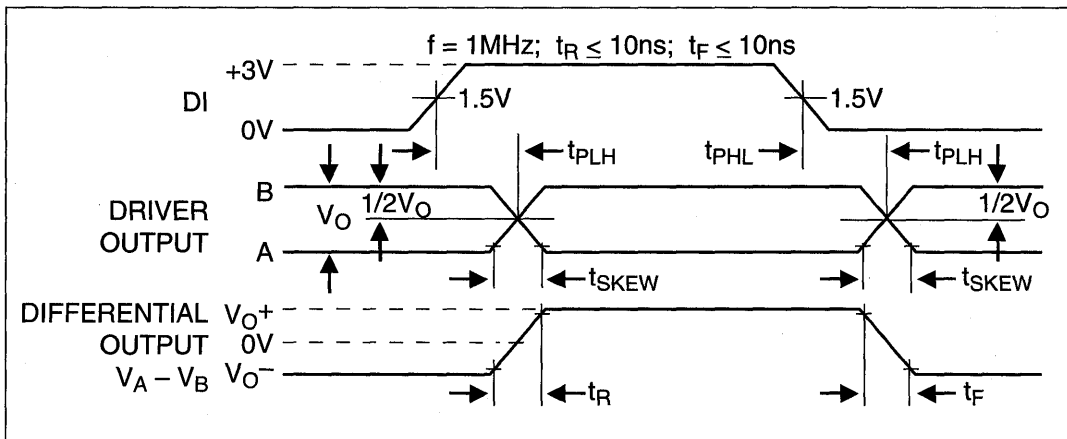


Figure 6. Driver Propagation Delays

INPUTS			LINE CONDITION	OUTPUTS	
$\overline{RE}$	DE	DI		B	A
X	1	1	No Fault	0	1
X	1	0	No Fault	1	0
X	0	X	X	Z	Z
X	1	X	Fault	Z	Z

Table 1. Transmit Function Truth Table

INPUTS			A - B	R
$\overline{RE}$	DE	DI		
0	0	0	+0.2V	1
0	0	0	-0.2V	0
0	0	Inputs Open		1
1	0		X	Z

Table 2. Receive Function Truth Table

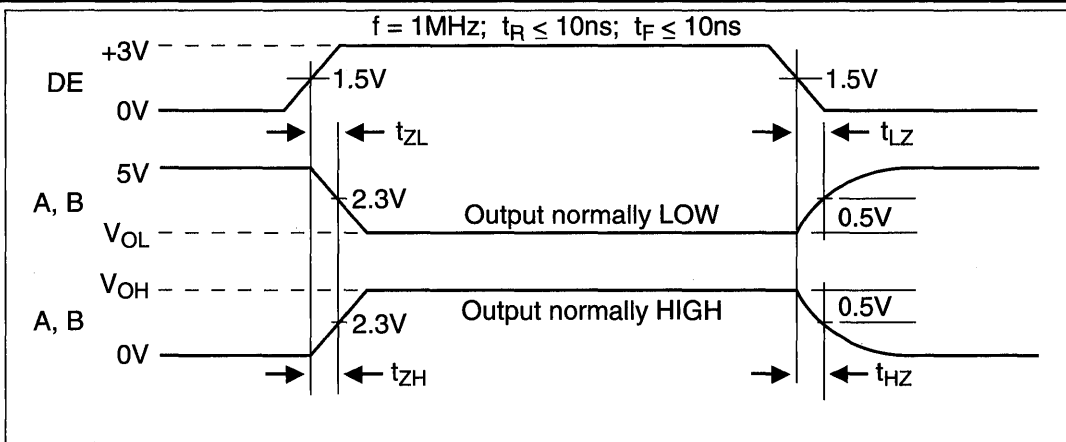


Figure 7. Driver Enable and Disable Times

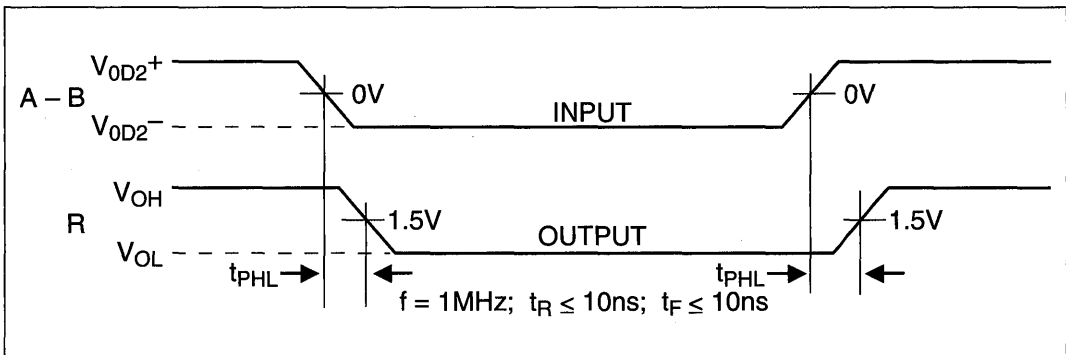


Figure 8. Receiver Propagation Delays

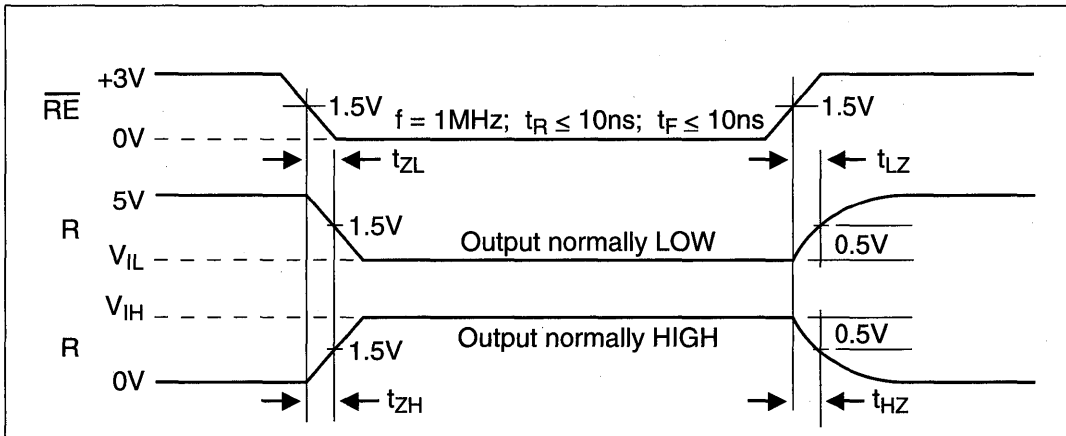


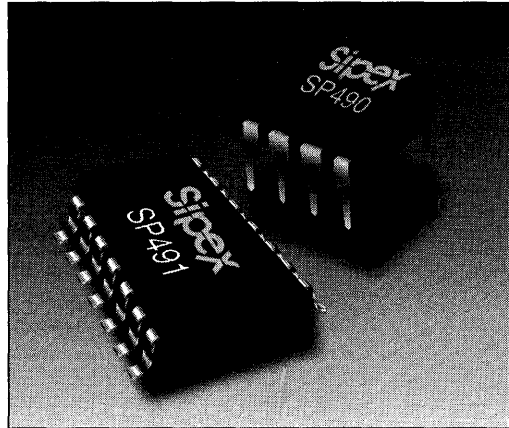
Figure 9. Receiver Enable and Disable Times

## ORDERING INFORMATION

Model	Temperature Range	Package
SP481CN .....	0°C to +70°C .....	8-pin Narrow SOIC
SP481CS .....	0°C to +70°C .....	8-pin Plastic DIP
SP481EN .....	-40°C to +85°C .....	8-pin Narrow SOIC
SP481ES .....	-40°C to +85°C .....	8-pin Plastic DIP
SP483CN .....	0°C to +70°C .....	8-pin Narrow SOIC
SP483CS .....	0°C to +70°C .....	8-pin Plastic DIP
SP483EN .....	-40°C to +85°C .....	8-pin Narrow SOIC
SP483ES .....	-40°C to +85°C .....	8-pin Plastic DIP
SP485CN .....	0°C to +70°C .....	8-pin Narrow SOIC
SP485CS .....	0°C to +70°C .....	8-pin Plastic DIP
SP485EN .....	-40°C to +85°C .....	8-pin Narrow SOIC
SP485ES .....	-40°C to +85°C .....	8-pin Plastic DIP

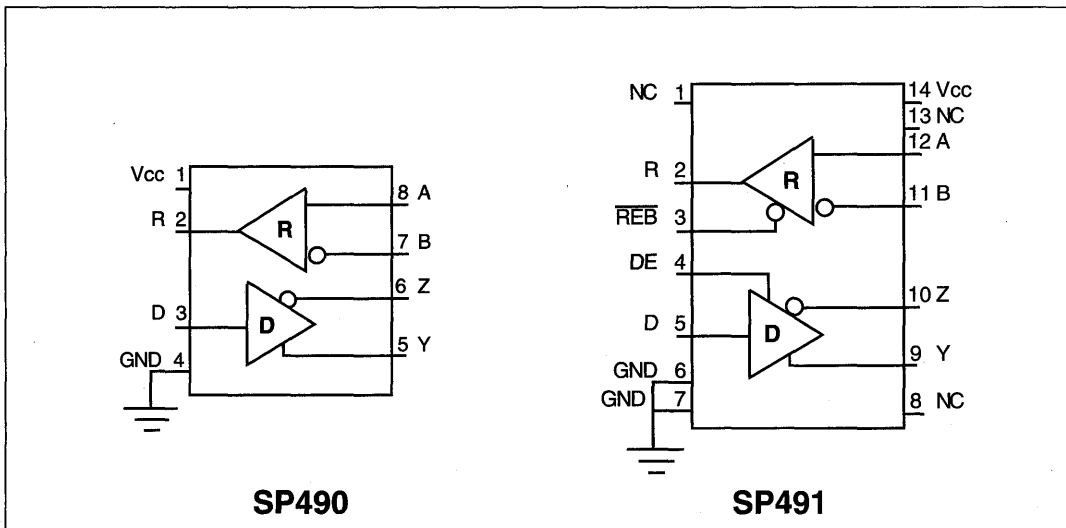
**Full Duplex RS-485 Transceivers**

- +5V Only
- Low Power BiCMOS
- Driver/Receiver Enable (SP491)
- RS-485 and RS-422 Drivers/Receivers
- Pin Compatible with LTC490 and SN75179 (SP490)
- Pin Compatible with LTC491 and SN75180 (SP491)



**DESCRIPTION...**

The **SP490** is a low power differential line driver/receiver meeting RS-485 and RS-422 standards up to 5Mbps. The **SP491** is identical to the **SP490** with the addition of driver and receiver tri-state enable lines. Both products feature  $\pm 200\text{mV}$  receiver input sensitivity, over wide common mode range. The **SP490** is available in 8-pin plastic DIP and 8-pin NSOIC packages for operation over the commercial and industrial temperature ranges. The **SP491** is available in 14-pin DIP and 14-pin NSOIC packages for operation over the commercial and industrial temperature ranges.



## ABSOLUTE MAXIMUM RATINGS

These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

V <sub>CC</sub> .....	+12V
Input Voltages	
Drivers.....	-0.5V to (V <sub>CC</sub> +0.5V)
Receivers.....	±14V
Output Voltages	
Drivers.....	±14V
Receivers.....	-0.5V to (V <sub>CC</sub> +0.5V)
Storage Temperature.....	-65°C to +150°
Power Dissipation.....	1000mW

## SPECIFICATIONS

T<sub>MIN</sub> to T<sub>MAX</sub> and V<sub>CC</sub> = 5V ± 5% unless otherwise noted.

PARAMETERS	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>SP490 DRIVER</b>					
<b>DC Characteristics</b>					
Differential Output Voltage	GND		V <sub>CC</sub>	Volts	Unloaded; R = ∞ ; see figure 1
Differential Output Voltage	2		V <sub>CC</sub>	Volts	With Load; R = 50Ω; (RS422); see figure 1
Differential Output Voltage Change in Magnitude of Driver	1.5		V <sub>CC</sub>	Volts	With Load; R = 27Ω; (RS485); see figure 1
Differential Output Voltage for Complimentary States			0.2	Volts	R = 27Ω or R = 50Ω; see figure 1
Driver Common-Mode Output Voltage			3	Volts	R = 27Ω or R = 50Ω; see figure 1
Input High Voltage	2.0			Volts	Applies to D
Input Low Voltage			0.8	Volts	Applies to D
Input Current			±10	μA	Applies to D
Driver Short-Circuit Current					
V <sub>OUT</sub> = HIGH	35		250	mA	-7V ≤ V <sub>O</sub> ≤ +12V
V <sub>OUT</sub> = LOW	35		250	mA	-7V ≤ V <sub>O</sub> ≤ +12V
<b>SP490 DRIVER</b>					
<b>AC Characteristics</b>					
Driver Data Rate			5	Mbps	
Driver Input to Output	20	30	60	ns	t <sub>PLH</sub> ; R <sub>DIFF</sub> = 54Ω, C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 3 and 6
Driver Input to Output	20	30	60	ns	t <sub>PHL</sub> ; R <sub>DIFF</sub> = 54Ω, C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 3 and 6
Driver Skew		5		ns	From output to output; see figures 3 and 6
Driver Rise or Fall Time	3	15	40	ns	From 10% to 90%; R <sub>DIFF</sub> = 54Ω, C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 3 and 6
<b>SP490 RECEIVER</b>					
<b>DC Characteristics</b>					
Differential Input Threshold	0.2		+0.2	Volts	-7V ≤ V <sub>CM</sub> ≤ 12V
Input Hysteresis		70		mV	V <sub>CM</sub> = 0V
Output Voltage High	3.5			Volts	I <sub>O</sub> = -4mA, V <sub>ID</sub> = +200mV
Output Voltage Low			0.4	Volts	I <sub>O</sub> = +4mA, V <sub>ID</sub> = -200mV
Input Resistance	12	15		kΩ	-7V ≤ V <sub>CM</sub> ≤ 12V
Input Current (A, B); V <sub>IN</sub> = 12V			±1.0	mA	V <sub>IN</sub> = 12V
Input Current (A, B); V <sub>IN</sub> = -7V			-0.8	mA	V <sub>IN</sub> = -7V
Short-Circuit Current	7		85	mA	0V ≤ V <sub>O</sub> ≤ V <sub>CC</sub>



# SPECIFICATIONS (continued)

$T_{MIN}$  to  $T_{MAX}$  and  $V_{CC} = 5V \pm 5\%$  unless otherwise noted.

PARAMETERS	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>SP490 RECEIVER</b>					
<b>AC Characteristics</b>					
Receiver Data Rate			5	Mbps	
Receiver Input to Output	60	90	150	ns	$t_{PLH}$ ; $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$ ; Figures 3 & 8
Receiver Input to Output	60	90	150	ns	$t_{PHL}$ ; $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$ ; Figures 3 & 8
Diff. Receiver Skew $ t_{PLH} - t_{PHL} $		13		ns	$R_{DIFF} = 54\Omega$ ; $C_{L1} = C_{L2} = 100pF$ ; Figures 3 & 8
<b>POWER REQUIREMENTS</b>					
Supply Voltage	+4.75		+5.25	Volts	
Supply Current		600		$\mu A$	
<b>ENVIRONMENTAL AND MECHANICAL</b>					
Operating Temperature					
Commercial (_C_)	0		+70	$^{\circ}C$	
Industrial (_E_)	-40		+85	$^{\circ}C$	
Storage Temperature	-65		+150	$^{\circ}C$	
Package					
Plastic DIP (_S_)					
NSOIC (_N)					

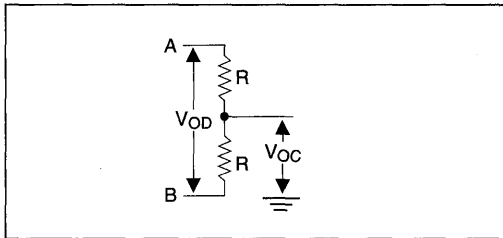


Figure 1. Driver DC Test Load Circuit

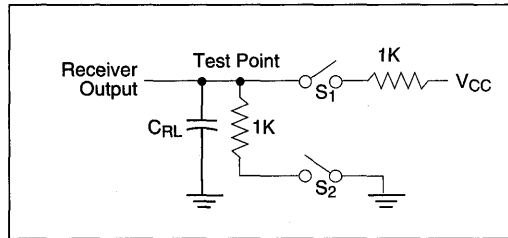


Figure 2. Receiver Timing Test Load Circuit

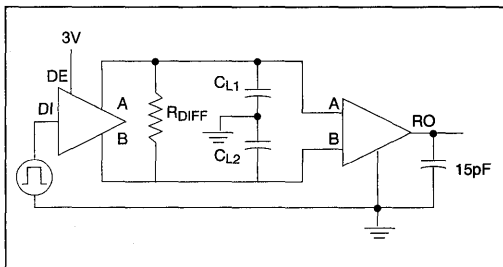


Figure 3. Driver/Receiver Timing Test Circuit

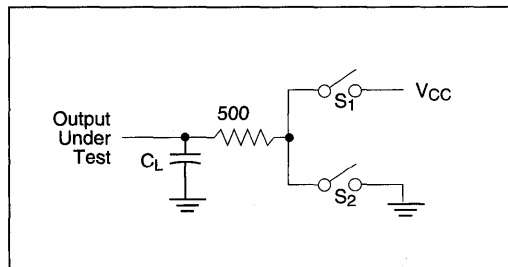


Figure 4. Driver Timing Test Load #2 Circuit

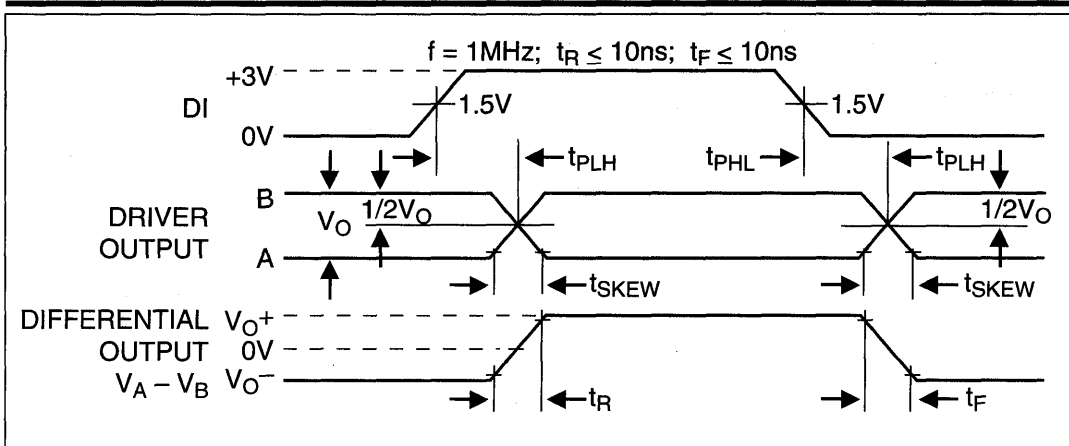


Figure 6. Driver Propagation Delays

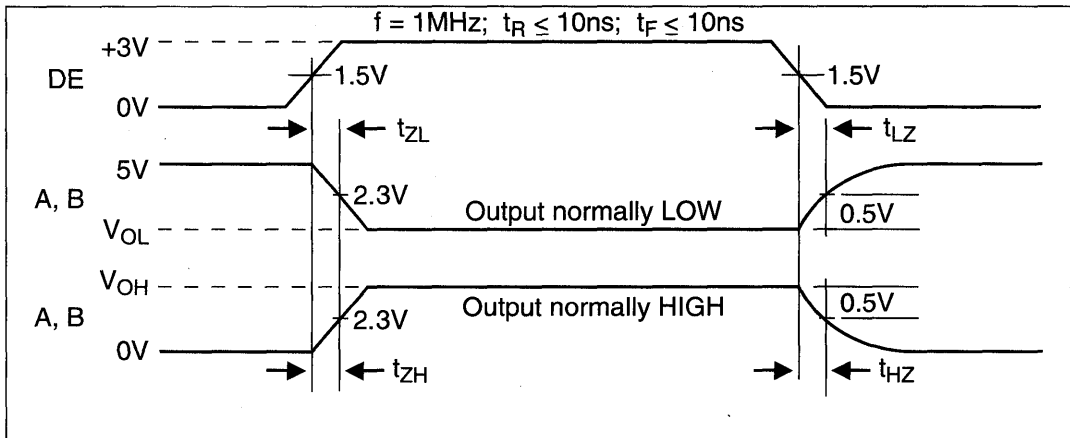


Figure 7. Driver Enable and Disable Times

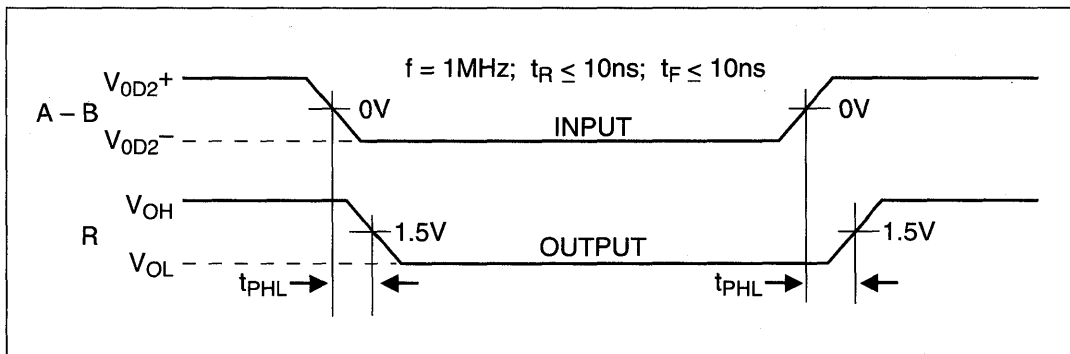


Figure 8. Receiver Propagation Delays

## ABSOLUTE MAXIMUM RATINGS

These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

V <sub>CC</sub> .....	+12V
Input Voltages	
Logic.....	-0.5V to (V <sub>CC</sub> +0.5V)
Drivers.....	-0.5V to (V <sub>CC</sub> +0.5V)
Receivers.....	±14V
Output Voltages	
Logic.....	-0.5V to (V <sub>CC</sub> +0.5V)
Drivers.....	±14V
Receivers.....	-0.5V to (V <sub>CC</sub> +0.5V)
Storage Temperature.....	-65°C to +150
Power Dissipation.....	1000mW

## SPECIFICATIONS

T<sub>MIN</sub> to T<sub>MAX</sub> and V<sub>CC</sub> = 5V ± 5% unless otherwise noted.

PARAMETERS	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>SP491 DRIVER</b>					
<b>DC Characteristics</b>					
Differential Output Voltage	GND		V <sub>CC</sub>	Volts	Unloaded; R = ∞ ; see figure 1
Differential Output Voltage	2		V <sub>CC</sub>	Volts	With Load; R = 50Ω; (RS422); see figure 1
Differential Output Voltage	1.5		V <sub>CC</sub>	Volts	With Load; R = 27Ω; (RS485); see figure 1
Change in Magnitude of Driver Differential Output Voltage for Complimentary States			0.2	Volts	R = 27Ω or R = 50Ω; see figure 1
Driver Common-Mode Output Voltage			3	Volts	R = 27Ω or R = 50Ω; see figure 1
Input High Voltage	2.0			Volts	Applies to D, REB, DE
Input Low Voltage			0.8	Volts	Applies to D, REB, DE
Input Current			±10	μA	Applies to D, REB, DE
Driver Short-Circuit Current					
V <sub>OUT</sub> = HIGH	35		250	mA	-7V ≤ V <sub>O</sub> ≤ 12V
V <sub>OUT</sub> = LOW	35		250	mA	-7V ≤ V <sub>O</sub> ≤ 12V
<b>SP491 DRIVER</b>					
<b>AC Characteristics</b>					
Driver Data Rate			5	Mbps	REB = 5V, DE = 0V
Driver Input to Output	20	30	60	ns	t <sub>PLH</sub> ; R <sub>DIFF</sub> = 54Ω, C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 3 and 6
Driver Input to Output	20	30	60	ns	t <sub>PHL</sub> ; R <sub>DIFF</sub> = 54Ω, C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 3 and 6
Driver Skew		5	10	ns	From output to output; see figures 3 and 6
Driver Rise or Fall Time	3	15	40	ns	From 10% to 90%; R <sub>DIFF</sub> = 54Ω, C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 3 and 6
Driver Enable to Output High		40	70	ns	C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 4 and 7; S <sub>2</sub> closed
Driver Enable to Output Low		40	70	ns	C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 4 and 7; S <sub>1</sub> closed
Driver Disable Time from Low		40	70	ns	C <sub>L1</sub> = C <sub>L2</sub> = 15pF; see figures 4 and 7; S <sub>1</sub> closed
Driver Disable Time from High		40	70	ns	C <sub>L1</sub> = C <sub>L2</sub> = 15pF; see figures 4 and 7; S <sub>2</sub> closed

# SPECIFICATIONS (continued)

$T_{MIN}$  to  $T_{MAX}$  and  $V_{CC} = 5V \pm 5\%$  unless otherwise noted.

PARAMETERS	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>SP491 RECEIVER</b>					
<b>DC Characteristics</b>					
Differential Input Threshold	-0.2		+0.2	Volts	$-7V \leq V_{CM} \leq 12V$
Input Hysteresis		70		mV	$V_{CM} = 0V$
Output Voltage High	3.5			Volts	$I_O = -4mA, V_{ID} = +200mV$
Output Voltage Low			0.4	Volts	$I_O = +4mA, V_{ID} = -200mV$
Three State (high impedance)					
Output Current			$\pm 1$	$\mu A$	$0.4V \leq V_O \leq 2.4V; \overline{REB} = 5V$
Input Resistance		15		k $\Omega$	$-7V \leq V_{CM} \leq 12V$
Input Current (A, B); $V_{IN} = 12V$			$\pm 1.0$	mA	$DE = 0V, V_{CC} = 0V$ or $5.25V, V_{IN} = 12V$
Input Current (A, B); $V_{IN} = -7V$			-0.8	mA	$DE = 0V, V_{CC} = 0V$ or $5.25V, V_{IN} = -7V$
Short-Circuit Current	7		85	mA	$0V \leq V_O \leq V_{CC}$
<b>SP491 RECEIVER</b>					
<b>DC Characteristics</b>					
Receiver Data Rate			5	Mbps	$\overline{REB} = 0V, DE = 5V$
Receiver Input to Output	60	90	150	ns	$t_{PLH}; R_{DIFF} = 54\Omega, C_{L1} = C_{L2} = 100pF; \text{ Figures 3 \& 8}$
Receiver Input to Output	60	90	150	ns	$t_{PHL}; R_{DIFF} = 54\Omega, C_{L1} = C_{L2} = 100pF; \text{ Figures 3 \& 8}$
Diff. Receiver Skew $t_{PLH} - t_{PHL}$		13		ns	$R_{DIFF} = 54\Omega; C_{L1} = C_{L2} = 100pF; \text{ Figures 3 \& 8}$
Receiver Enable to Output Low		20	50	ns	$C_{RL} = 15pF; \text{ Figures 2 and 9; } S_1 \text{ closed}$
Receiver Enable to Output High		20	50	ns	$C_{RL} = 15pF; \text{ Figures 2 and 9; } S_2 \text{ closed}$
Receiver Disable from Low		20	50	ns	$C_{RL} = 15pF; \text{ Figures 2 and 9; } S_1 \text{ closed}$
Receiver Disable from High		20	50	ns	$C_{RL} = 15pF; \text{ Figures 2 and 9; } S_2 \text{ closed}$
<b>POWER REQUIREMENTS</b>					
Supply Voltage	+4.75		+5.25	Volts	
Supply Current		600		$\mu A$	$\overline{REB}, D = 0V$ or $V_{CC}; DE = V_{CC}$
<b>SP491 ENVIRONMENTAL AND MECHANICAL</b>					
Operating Temperature					
Commercial ( $C$ )	0		+70	$^{\circ}C$	
Industrial ( $E$ )	-40		+85	$^{\circ}C$	
Storage Temperature	-65		+150	$^{\circ}C$	
Package					
Plastic DIP ( $S$ )					
NSOIC ( $N$ )					

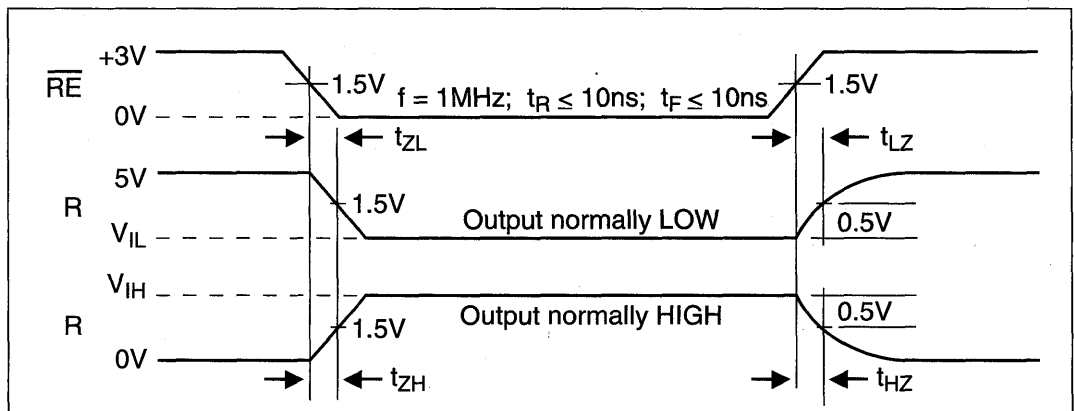


Figure 9. Receiver Enable and Disable Times

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## DESCRIPTION

The **SP490** and **SP491** are full-duplex differential transceivers that meet the requirements of RS-485 and RS-422. Fabricated with a **Sipex** proprietary BiCMOS process, both products require a fraction of the power of older bipolar designs.

The RS-485 standard is ideal for multi-drop applications or for long-distance interfaces. RS-485 allows up to 32 drivers and 32 receivers to be connected to a data bus, making it an ideal choice for multi-drop applications. Since the cabling can be as long as 4,000 feet, RS-485 transceivers are equipped with a wide (-7V to +12V) common mode range to accommodate ground potential differences. Because RS-485 is a differential interface, data is virtually immune to noise in the transmission line.

### Driver...

The drivers for both the **SP490** and **SP491** have differential outputs. The typical voltage output swing with no load will be 0 volts to +5 volts. With worst case loading of 54 $\Omega$  across the differential outputs, the driver can maintain greater than 1.5V voltage levels.

The driver of the **SP491** has a driver enable control line which is active high. A logic high on DE (pin 4) of the **SP491** will enable the differential driver outputs. A logic low on DE (pin 4) of the **SP491** will tri-state the driver outputs. The **SP490** does not have a driver enable.

### Receiver...

The receivers for both the **SP490** and **SP491** have differential inputs with an input sensitivity as low as  $\pm 200\text{mV}$ . Input impedance of the receivers is typically 15K $\Omega$  (12K $\Omega$  minimum). A wide common mode range of -7V to +12V allows for large ground potential differences between systems. The receivers for both the **SP490** and **SP491** are equipped with the fail-safe feature. Fail-safe guarantees that the receiver output will be in a high state when the input is left unconnected.

The receiver of the **SP491** has a receiver enable control line which is active low. A logic low on REB (pin 3) of the **SP491** will enable the differential receiver. A logic high on REB (pin 3) of the **SP491** will tri-state the receiver.

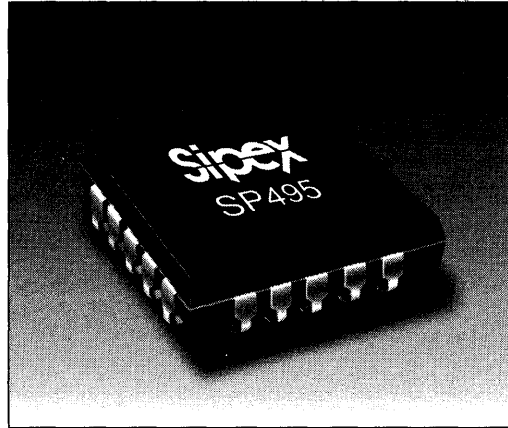
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## ORDERING INFORMATION

Model	Temperature Range	Package
SP490CN .....	0°C to +70°C .....	8-Pin NSOIC
SP490CS .....	-40°C to +85°C .....	8-Pin DIP
SP491CN .....	0°C to +70°C .....	14-Pin NSOIC
SP491CS .....	-40°C to +85°C .....	14-Pin DIP

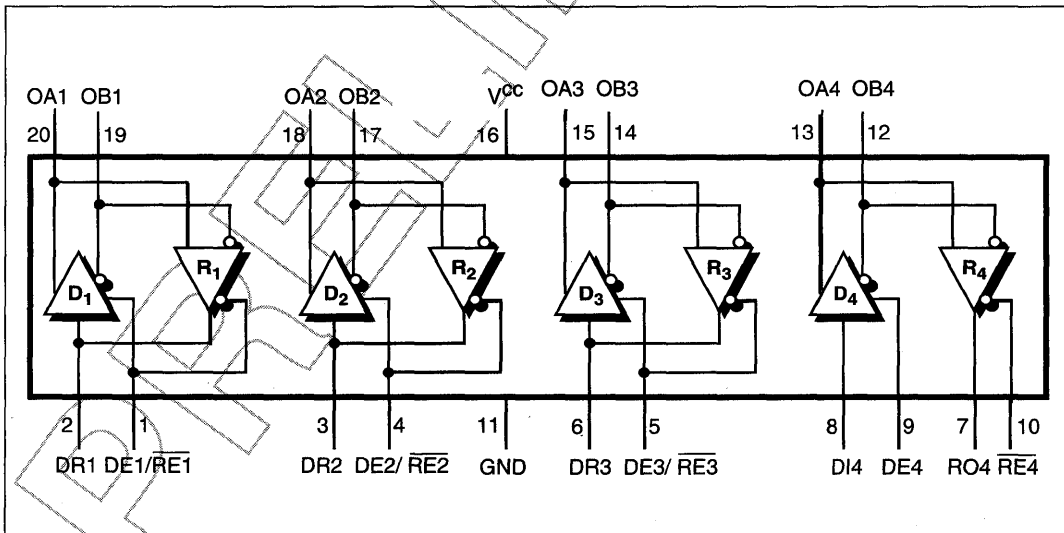
## Quad Differential RS-485 Transceiver

- Pinout for SCSI Interface
- Meets EIA-485 Standard for Multipoint Bus Transmission
- +5V-Only Power Supply Required
- Receiver Fail-Safe Mode
- Low Power BiCMOS Technology
- Glitch-Free Power-Up/Down
- Available in 20-Pin Plastic LCC
- Pin Compatible with DS36954



### DESCRIPTION...

The **SP495** is a quad differential line driver/receiver meeting both RS-485 and RS-422 standards at data rates beyond 10Mbps. The **SP495** features three half-duplex transceivers suitable for data bus connections and a fourth full-duplex transceiver with independent driver, receiver enables, ideal for use as a control bus transceiver. A complete SCSI initiator or target interface can be implemented using five **SP495s**. Propagation Delay Skew is tightly specified to aid in parallel interface designs. The **SP495** is available in a 20-pin plastic LCC package for operation over the commercial and industrial temperature ranges.



## ABSOLUTE MAXIMUM RATINGS

These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

V <sub>CC</sub> .....	+12V
Input Voltages	
Logic.....	-0.5V to (V <sub>CC</sub> +0.5V)
Drivers.....	-0.5V to (V <sub>CC</sub> +0.5V)
Receivers.....	±15V
Output Voltages	
Logic.....	-0.5V to (V <sub>CC</sub> +0.5V)
Drivers.....	±15V
Receivers.....	-0.5V to (V <sub>CC</sub> +0.5V)
Storage Temperature.....	-65°C to +150°C
Power Dissipation.....	100mW

## SPECIFICATIONS

T<sub>MIN</sub> to T<sub>MAX</sub> and V<sub>CC</sub> = 5V ± 5% unless otherwise noted.

PARAMETERS	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>DRIVER</b>					
<b>DC Characteristics</b>					
Differential Output Voltage	GND		V <sub>CC</sub>	Volts	Unloaded; R = ∞ ; see figure 1
Differential Output Voltage	2		V <sub>CC</sub>	Volts	With Load; R = 50Ω; (RS422); see figure 1
Differential Output Voltage	1.5		V <sub>CC</sub>	Volts	With Load; R = 27Ω; (RS485); see figure 1
Change in Magnitude of Driver Differential Output Voltage for Complimentary States			0.2	Volts	R = 27Ω or R = 50Ω; see figure 1
Driver Common-Mode Output Voltage			3	Volts	R = 27Ω or R = 50Ω; see figure 1
Input High Voltage	2.0			Volts	Applies to DRx, DEx/ $\overline{\text{REx}}$
Input Low Voltage			0.8	Volts	Applies to DRx, DEx/ $\overline{\text{REx}}$
Input Current			±10	μA	Applies to DRx, DEx/ $\overline{\text{REx}}$
Driver Short-Circuit Current					
V <sub>OUT</sub> = HIGH	35		250	mA	-7V ≤ V <sub>O</sub> ≤ 12V
V <sub>OUT</sub> = LOW	35		250	mA	-7V ≤ V <sub>O</sub> ≤ 12V
<b>DRIVER</b>					
<b>AC Characteristics</b>					
Driver Data Rate			10	Mbps	DEx/ $\overline{\text{REx}}$ = 5V
Driver Input to Output	20	30	60	ns	t <sub>PLH</sub> ; R <sub>DIFF</sub> = 54Ω, C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 3 and 6
Driver Input to Output	20	30	60	ns	t <sub>PHL</sub> ; R <sub>DIFF</sub> = 54Ω, C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 3 and 6
Driver Skew		10		ns	From output to output; see figures 3 and 6
Driver Rise or Fall Time	3	15	40	ns	From 10% to 90%; R <sub>DIFF</sub> = 54Ω, C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 3 and 6
Driver Enable to Output High		40	70	ns	C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 4 and 7; S <sub>2</sub> closed
Driver Enable to Output Low		40	70	ns	C <sub>L1</sub> = C <sub>L2</sub> = 100pF; see figures 4 and 7; S <sub>1</sub> closed
Driver Disable Time from Low		40	70	ns	C <sub>L1</sub> = C <sub>L2</sub> = 15pF; see figures 4 and 7; S <sub>1</sub> closed
Driver Disable Time from High		40	70	ns	C <sub>L1</sub> = C <sub>L2</sub> = 15pF; see figures 4 and 7; S <sub>2</sub> closed
<b>RECEIVER</b>					
<b>DC Characteristics</b>					
Differential Input Threshold	-0.2		+0.2	Volts	-7V ≤ V <sub>CM</sub> ≤ 12V
Input Hysteresis		70		mV	V <sub>CM</sub> = 0V
Output Voltage High	3.5			Volts	I <sub>O</sub> = -4mA, V <sub>ID</sub> = +200mV



# SPECIFICATIONS (continued)

$T_{MIN}$  to  $T_{MAX}$  and  $V_{CC} = 5V \pm 5\%$  unless otherwise noted.

PARAMETERS	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>RECEIVER</b>					
<b>DC Characteristics</b>					
Output Voltage Low			0.4	Volts	$I_O = +4mA, V_{ID} = -200mV$
Three State (high impedance)					
Output Current		$\pm 1$		$\mu A$	$0.4V \leq V_O \leq 2.4V; DEx/REx = 5V$
Input Resistance	12	15		k $\Omega$	$-7V \leq V_{CM} \leq 12V$
Input Current (A, B); $V_{IN} = 12V$			$\pm 1.0$	mA	$DE = 0V, V_{CC} = 0V$ or $5.25V, V_{IN} = 12V$
Input Current (A, B); $V_{IN} = -7V$			-0.8	mA	$DE = 0V, V_{CC} = 0V$ or $5.25V, V_{IN} = -7V$
Short-Circuit Current	7		85	mA	$0V \leq V_O \leq V_{CC}$
<b>RECEIVER</b>					
<b>AC Characteristics</b>					
Receiver Data Rate			10	Mbps	$DEx/REx = 0V$
Receiver Input to Output		60	150	ns	$t_{PLH}; R_{DIFF} = 54\Omega, C_{L1} = C_{L2} = 100pF; Figures 3 \& 8$
Receiver Input to Output		60	150	ns	$t_{PHL}; R_{DIFF} = 54\Omega, C_{L1} = C_{L2} = 100pF; Figures 3 \& 8$
Diff. Receiver Skew $ t_{PLH} - t_{PHL} $		13		ns	$R_{DIFF} = 54\Omega; C_{L1} = C_{L2} = 100pF; Figures 3 \& 8$
Receiver Enable to Output Low		20	50	ns	$C_{RL} = 15pF; Figures 2 \text{ and } 9; S_1 \text{ closed}$
Receiver Enable to Output High		20	50	ns	$C_{RL} = 15pF; Figures 2 \text{ and } 9; S_2 \text{ closed}$
Receiver Disable from Low		20	50	ns	$C_{RL} = 15pF; Figures 2 \text{ and } 9; S_1 \text{ closed}$
Receiver Disable from High		20	50	ns	$C_{RL} = 15pF; Figures 2 \text{ and } 9; S_2 \text{ closed}$
<b>POWER REQUIREMENTS</b>					
Supply Voltage	+4.75		+5.25	Volts	
Supply Current		3		mA	$DEx/REx, DRx = 0V$ or $V_{CC}$
<b>ENVIRONMENTAL AND MECHANICAL</b>					
Operating Temperature					
Commercial (C)	0		+70	$^{\circ}C$	
Industrial (E)	-40		+85	$^{\circ}C$	
Storage Temperature	-65		+150	$^{\circ}C$	
Package					
Plastic LCC (L)					

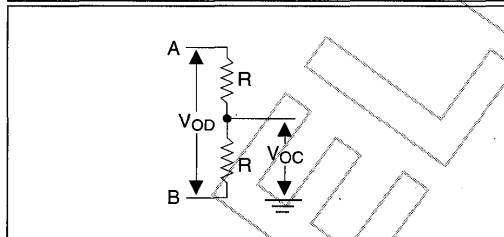


Figure 1. Driver DC Test Load Circuit

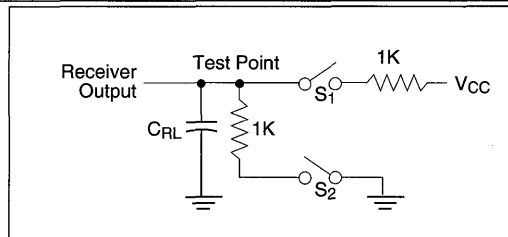


Figure 2. Receiver Timing Test Load Circuit

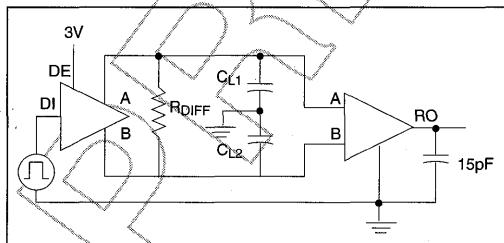


Figure 3. Driver/Receiver Timing Test Circuit

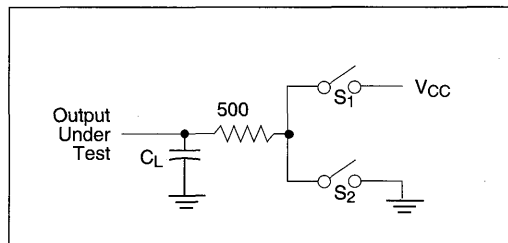


Figure 4. Driver Timing Test Load #2 Circuit

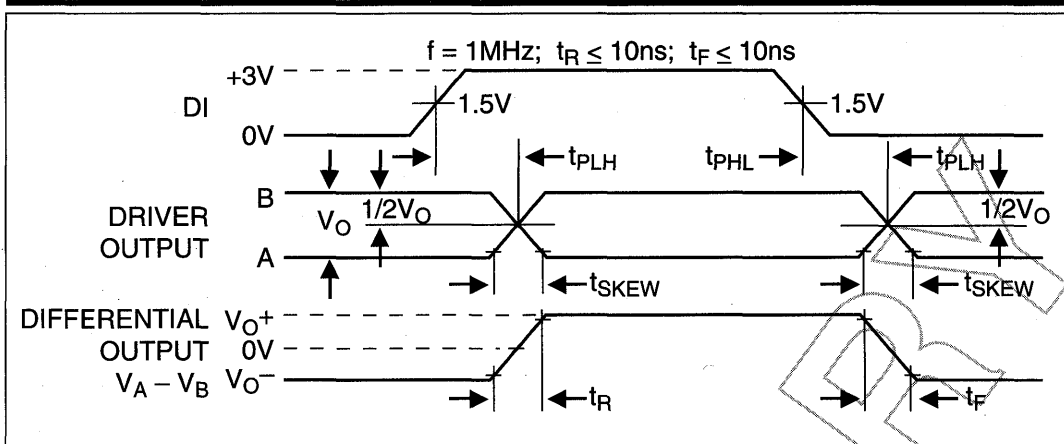


Figure 6. Driver Propagation Delays

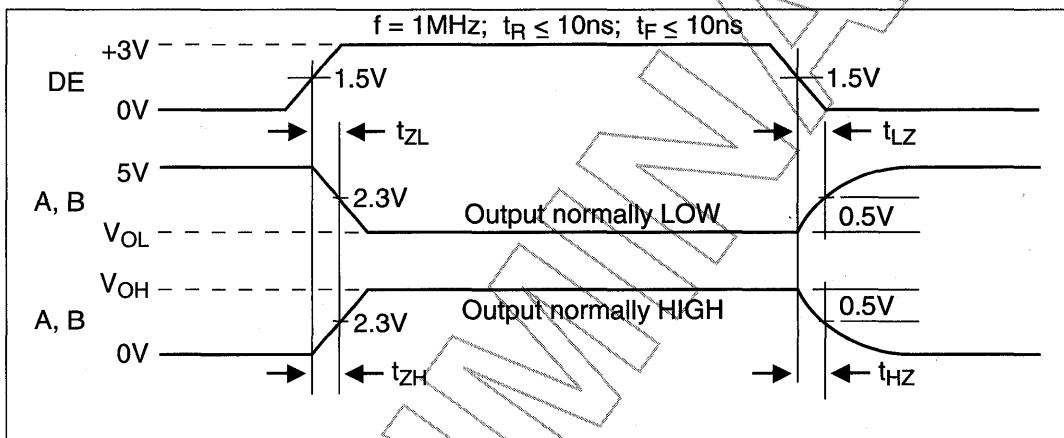


Figure 7. Driver Enable and Disable Times

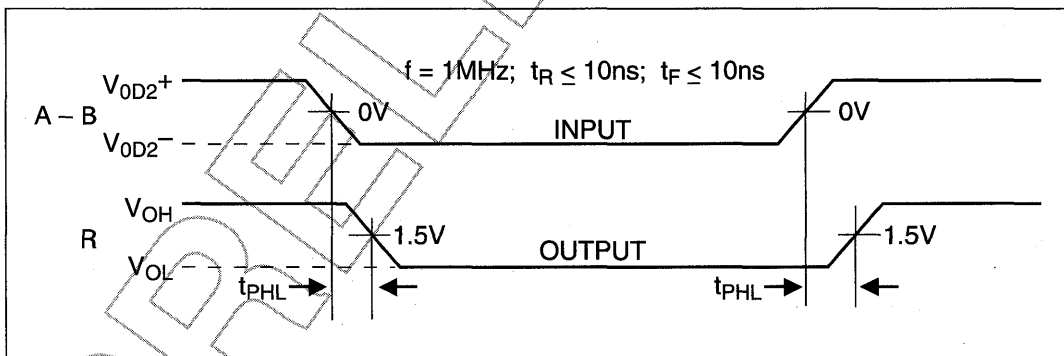


Figure 8. Receiver Propagation Delays

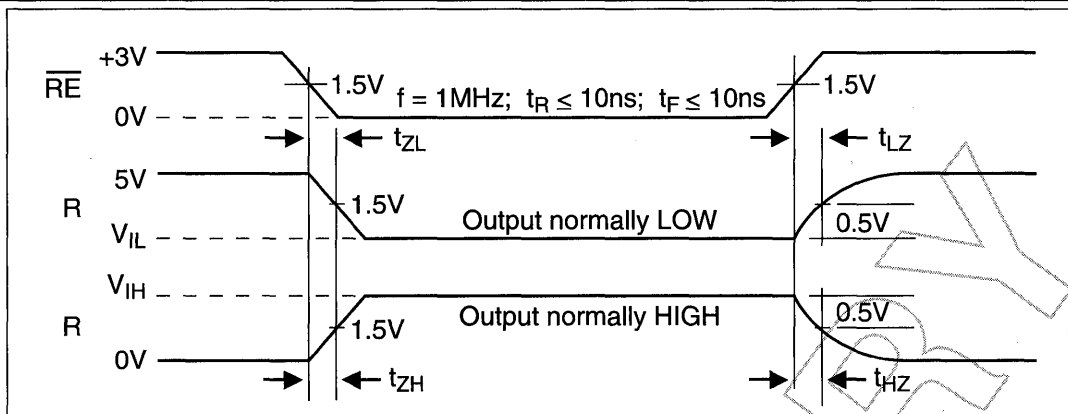


Figure 9. Receiver Enable and Disable Times

## DESCRIPTION

### General Description...

The **SP495** is a quad differential transceiver that meets the requirements of RS-485, RS-422, and differential SCSI at data rates beyond 10Mbps. Fabricated with a proprietary Sipex BiCMOS process, the **SP495** requires only a fraction of the power of older bipolar designs.

The **SP495** features three half-duplex transceivers suitable for data bus connections and a fourth full-duplex transceiver with independent enables ideal for use as a control bus transceiver. A complete SCSI initiator or target interface can be implemented using five **SP495**s.

The RS-485 standard is ideal for multi-drop applications and for long-distance interfaces. RS-485 allows up to 32 drivers and 32 receivers to be connected to a single data bus, making it an ideal choice for multi-drop applications. Since the cabling can be as long as 4,000 feet, RS-485 transceivers are specified for operation with a wide (-7V to +12V) common mode range to accommodate ground potential differences. Because RS-485 is a low impedance differential interface, data is virtually immune to noise in the transmission line.

### Drivers...

The differential drivers for the **SP495** have typical output voltage swings (no load) of 0 to +5Volts. With loading to the RS-485 specification (54Ω), drivers must maintain outputs greater than 1.5V.

The three half-duplex drivers of the **SP495** have independent Driver Enable control lines which are active HIGH. A logic HIGH on DEx (pins 1, 4, or 5 of the **SP495**) will enable the addressed differential driver output. A logic LOW on DEx will tri-state the driver output and enable the receiver. The fourth driver is controlled by its own DE4 Enable line and can be used in half-duplex or full-duplex modes.

### Receivers...

The differential receivers for the **SP495** have an input sensitivity of ±200mV. Input impedance is typically 15kΩ (12kΩ minimum). A wide common mode range of -7V to +12V allows for large ground potential differences between widely separated systems. These receivers are equipped with a fail-safe feature which guarantees that the receiver output will be in a HIGH state when the input is left unconnected (note: this feature operates with floating inputs, not terminated inputs).

Like the half-duplex drivers, the three half-duplex receivers of the **SP495** have independent Receiver Enable control lines which are active LOW. A logic LOW on  $\overline{\text{REx}}$  (pins 1, 4, or 5 of the **SP495**) enables the differential receivers. A logic HIGH on  $\overline{\text{REx}}$  tri-states the receivers. The fourth receiver is controlled by its own RE4 Enable line and can be used in half-duplex or full-duplex modes.

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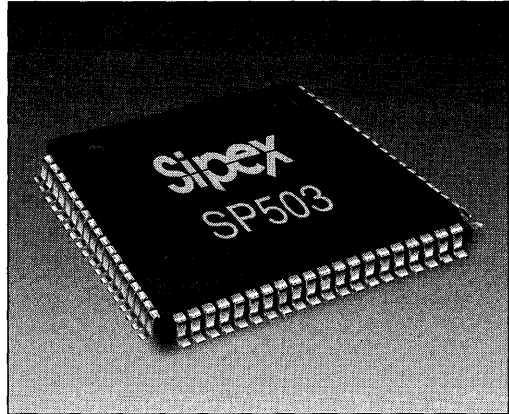
**ORDERING INFORMATION**

<b>Model</b>	<b>Temperature Range</b>	<b>Package</b>
SP495CL .....	0°C to +70°C .....	20-Pin PLCC
SP495EL .....	-40°C to +85°C .....	20-Pin PLCC

PRELIMINARY

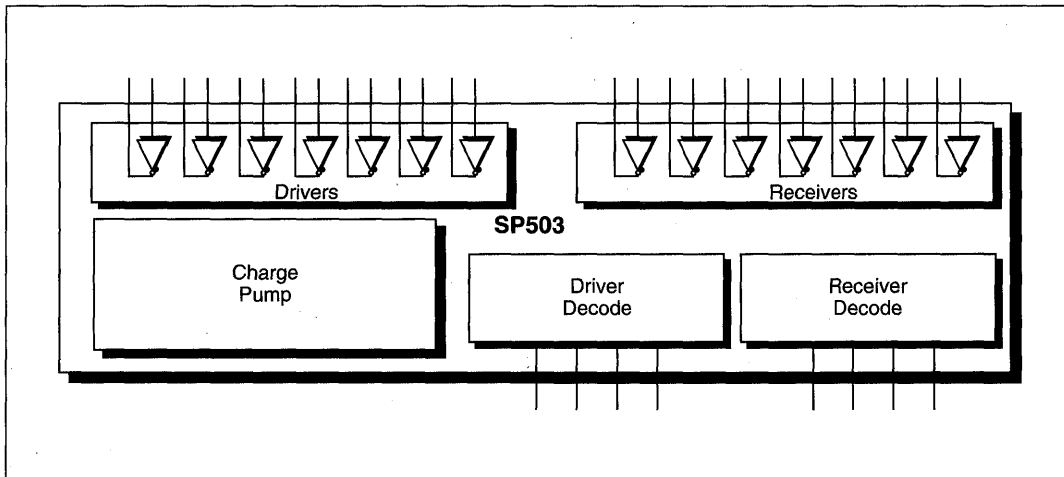
## Multi-Mode Serial Transceiver

- Single-Chip Serial Transceiver Supports Industry-Standard
- Software-Selectable Protocols:
  - RS-232 (V.28)
  - RS-422A (V.11, X.27)
  - RS-449
  - RS-485
  - V.35
  - EIA-530
- Programmable Selection of Interface
- Seven (7) Drivers and Seven (7) Receivers
- Surface Mount Packaging



### DESCRIPTION...

The **SP503** is a highly integrated serial transceiver that allows software control of its interface modes. It offers hardware interface modes for RS-232 (V.28), RS-422A (V.11), RS-449, RS485, V.35, and EIA-530. The **SP503** is fabricated using low-power BiCMOS process technology, and incorporates a **Sipex**-patented (5,306,954) charge pump allowing +5V only operation. Each device is packaged in an 80-pin Quad FlatPack package.



# SPECIFICATIONS

T<sub>MIN</sub> to T<sub>MAX</sub> @ V<sub>CC</sub> = +5V ±5% unless otherwise noted.

	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>LOGIC INPUTS</b>					
V <sub>IL</sub>			0.8	Volts	
V <sub>IH</sub>	2.0			Volts	
<b>LOGIC OUTPUTS</b>					
V <sub>OL</sub>			0.4	Volts	I <sub>OUT</sub> = 3.2mA
V <sub>OH</sub>	2.4			Volts	I <sub>OUT</sub> = 1.0mA
<b>RS-485 DRIVER</b>					
TTL Input Levels					
V <sub>IL</sub>			0.8	Volts	
V <sub>IH</sub>	2.0			Volts	
Outputs					
High Level Output			+6.0	Volts	
Low level Output	-0.3			Volts	
Differential Output	±1.5		±5.0	Volts	R <sub>L</sub> = 54Ω, C <sub>L</sub> = 50pF
Balance			±0.2	Volts	V <sub>T+</sub> -  V <sub>T-</sub>
Open Circuit Voltage			±6.0	Volts	
Output Current	28.0			mA	R <sub>L</sub> = 54Ω
Short Circuit Current			±250	mA	Terminated in -7V to +12V
Transition Time			120	ns	Rise/fall time, 10%-90%
Transmission Rate			5	Mbps	
Propagation Delay					
t <sub>PHL</sub>			200	ns	R <sub>L</sub> = 54Ω
t <sub>PLH</sub>			200	ns	R <sub>L</sub> = 54Ω
<b>RS-485 RECEIVER</b>					
TTL Output Levels					
V <sub>OL</sub>	0		0.4	Volts	
V <sub>OH</sub>	2.4			Volts	
Input					
High Threshold	+0.2		+12.0	Volts	(a)-(b)
Low Threshold	-7.0		-0.2	Volts	(a)-(b)
Common Mode Range	-7.0		+12.0	Volts	
High Input Current					Refer to graph
Low Input Current					Refer to graph
Receiver Sensitivity			±0.2	Volts	Over -7V to +12V common mode range
Input Impedance	12			KΩ	
Transmission Rate			5	Mbps	
Propagation Delay					
t <sub>PHL</sub>			200	ns	
t <sub>PLH</sub>			200	ns	
<b>V.35 DRIVER</b>					
TTL Input Levels					
V <sub>IL</sub>	0		0.8	Volts	
V <sub>IH</sub>	2.0			Volts	
Outputs					
Differential Output	±0.44		±0.66	Volts	With termination network in Figure 6; R <sub>L</sub> = 100Ω
Output Impedance	50		150	Ω	With termination network in Figure 6.
Transition Time			40	ns	
Transmission Rate			5	Mbps	
Propagation Delay					
t <sub>PHL</sub>			200	ns	R <sub>L</sub> = 100Ω
t <sub>PLH</sub>			200	ns	R <sub>L</sub> = 100Ω

# SPECIFICATIONS (Continued)

T<sub>MIN</sub> to T<sub>MAX</sub> @ V<sub>CC</sub> = +5V ±5% unless otherwise noted.

	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>V.35 RECEIVER</b>					
TTL Output Levels					
V <sub>OL</sub>	0		0.4	Volts	
V <sub>OH</sub>	2.4			Volts	
Input					
High Threshold	+0.2		+12.0	Volts	(a)-(b)
Low Threshold	-7.0		-0.2	Volts	(a)-(b)
Common Mode Range	-7.0		+12.0	Volts	
Receiver Sensitivity			±0.2	Volts	
Input Impedance	90		110	Ω	With termination network in Figure 6.
Transmission Rate			5	Mbps	
Propagation Delay					
t <sub>PHL</sub>			200	ns	
t <sub>PLH</sub>			200	ns	
<b>RS-422 DRIVER</b>					
TTL Input Levels					
V <sub>IL</sub>	0		0.8	Volts	
V <sub>IH</sub>	2.0			Volts	
Outputs					
Differential Output	±2.0		±5.0	Volts	R <sub>L</sub> =100Ω
Open Circuit Voltage, V <sub>O</sub>			±6.0	Volts	
Balance			±0.4	Volts	V <sub>T</sub>   -  V <sub>T</sub>
Offset			+3.0	Volts	
Short Circuit Current			±150	mA	-7V ≤ V <sub>out</sub> ≤ +12V
Power Off Current			±100	μA	V <sub>CC</sub> = 0V, V <sub>out</sub> = ±0.25V
Transition Time			60	ns	Rise/fall time, 10%-90%
Transmission Rate			5	Mbps	
Propagation Delay					
t <sub>PHL</sub>			200	ns	R <sub>L</sub> =100Ω
t <sub>PLH</sub>			200	ns	R <sub>L</sub> =100Ω
<b>RS-422 RECEIVER</b>					
TTL Output Levels					
V <sub>OL</sub>	0		0.4	Volts	
V <sub>OH</sub>	2.4			Volts	
Input					
High Threshold	+0.2		+6.0	Volts	(a)-(b)
Low Threshold	-6.0		-0.2	Volts	(a)-(b)
Common Mode Range	-7.0		+7.0	Volts	
High Input Current					Refer to graph
Low Input Current					Refer to graph
Receiver Sensitivity			±0.2	Volts	
Input Impedance	4			KΩ	
Transmission Rate			5	Mbps	
Propagation Delay					
t <sub>PHL</sub>			200	ns	
t <sub>PLH</sub>			200	ns	
<b>RS-232 DRIVER</b>					
TTL Input Level					
V <sub>IL</sub>	0		0.8	Volts	
V <sub>IH</sub>	2.0			Volts	
Outputs					
High Level Output	+5.0		+15	Volts	R <sub>L</sub> =3KΩ, V <sub>IN</sub> =0.8V, V <sub>CC</sub> =5V
Low Level Output	-15.0		-5.0	Volts	R <sub>L</sub> =3KΩ, V <sub>IN</sub> =2.0V, V <sub>CC</sub> =5V
Open Circuit Voltage	-15		+15	Volts	
Short Circuit Current			±100	mA	
Power Off Impedance	300			Ω	V <sub>CC</sub> = 0V, V <sub>out</sub> = ±2.0V

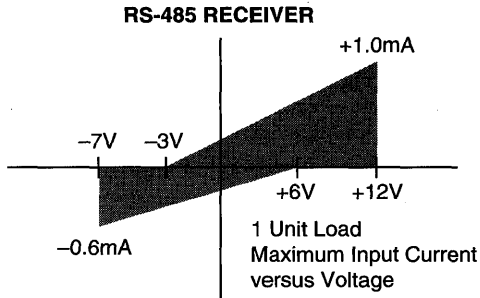
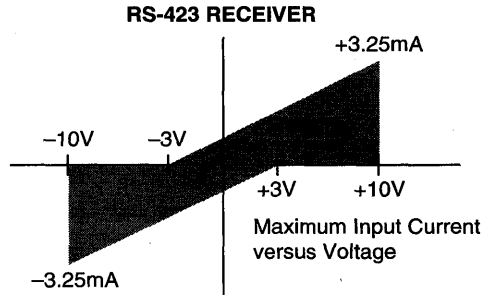
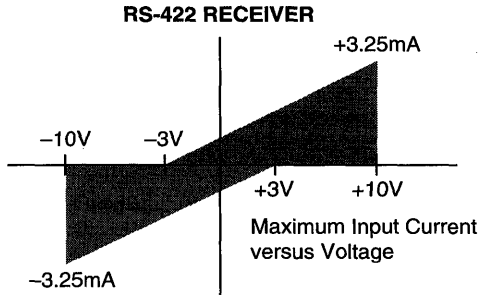
# SPECIFICATIONS (Continued)

T<sub>MIN</sub> to T<sub>MAX</sub> @ V<sub>CC</sub> = +5V ±5% unless otherwise noted.

	MIN.	TYP.	MAX.	UNITS	CONDITIONS
Slew Rate			30	V/μs	R <sub>L</sub> =3KΩ, C <sub>L</sub> =15pF
Transition Time			1.56	μs	R <sub>L</sub> =3KΩ, C <sub>L</sub> =2500pF
Transmission Rate			120	Kbps	
Propagation Delay					
t <sub>PHL</sub>		2	8	μs	R <sub>L</sub> =3KΩ
t <sub>PLH</sub>		2	8	μs	R <sub>L</sub> =3KΩ
<b>RS-232 RECEIVER</b>					
TTL Output Levels					
V <sub>OL</sub>	0		0.4	Volts	
V <sub>OH</sub>	2.4			Volts	
Input					
High Threshold		1.7	2.4	Volts	
Low Threshold	0.8	1.2		Volts	
Receiver Open Circuit Bias	0		+2.0	Volts	
Input Impedance	3	5	7	KΩ	
Transmission Rate			120	Kbps	
Propagation Delay					
t <sub>PHL</sub>			1	μs	
t <sub>PLH</sub>			1	μs	
<b>RS-423 DRIVER</b>					
TTL Input Levels					
V <sub>IL</sub>	0		0.8	Volts	
V <sub>IH</sub>	2.0			Volts	
Output					
High Level Output	+3.6		+6.0	Volts	R <sub>L</sub> =450Ω
Low Level Output	-6.0		-3.6	Volts	R <sub>L</sub> =450Ω
Open Circuit Voltage	±4.0		±10.0	Volts	
Short Circuit Current			±150	mA	
Power Off Current			±100	μA	V <sub>CC</sub> = 0V, V <sub>out</sub> = ±0.25V
Transition Time	0.8		2.4	μs	Rise/fall time, 10-90%
Transmission Rate			120	Kbps	
Propagation Delay					
t <sub>PHL</sub>		2	8	μs	R <sub>L</sub> =450Ω
t <sub>PLH</sub>		2	8	μs	R <sub>L</sub> =450Ω
<b>RS-423 RECEIVER</b>					
TTL Output Levels					
V <sub>OL</sub>	0		0.4	Volts	
V <sub>OH</sub>	2.4			Volts	
Input					
High Threshold	+0.2		+7.0	Volts	
Low Threshold	-7.0		-0.2	Volts	
Common Mode Range	-7.0		+7.0	Volts	
High Input Current					Refer to graph
Low Input Current					Refer to graph
Receiver Sensitivity			±0.2	Volts	V <sub>CM</sub> = +7V to -7V
Input Impedance	4			KΩ	V <sub>IN</sub> = +10V to -10V
Transmission Rate			120	Kbps	
Propagation Delay					
t <sub>PHL</sub>			1	μs	
t <sub>PLH</sub>			1	μs	
<b>POWER REQUIREMENTS</b>					
V <sub>CC</sub>	4.75		5.25	Volts	
I <sub>CC</sub>		20	30	mA	V <sub>CC</sub> = 5V; no interface selected
<b>ENVIRONMENTAL AND MECHANICAL</b>					
Operating Temperature Range	0		+70	°C	
Storage Temperature Range	-65		+150	°C	
Package	80-pin QFP				



## RECEIVER INPUT GRAPHS



## POWER MATRIX

Typical @ 25°C and  $V_{CC} = +5V$  unless otherwise noted. Input is applied to one driver.

Mode	Open Input	Input to 5V	Input to GND	AC signal to Input	Input to 5V with load	Input to GND with load	AC Signal with load	Conditions
V.35	47.0mA	48.8mA	47.3mA	54.5mA	104.2mA	100.9mA	100.9mA	With external termination resistor network; Input @ 60kHz, Load is 3kΩ & 2500pF for RS-232 and 100Ω for V.35
RS-232	35.4mA	37.8mA	35.2mA	43.6mA	54.1mA	57.1mA	55.9mA	Input @ 60kHz Load is 3kΩ & 2500pF for RS-232.
RS-422	25.8mA	31.4mA	25.8mA	27.5mA	140.2mA	135.9mA	145.2mA	Input @ 2.5MHz Load is 100Ω.
RS-485	33.4mA	37.91mA	33.51mA	34.81mA	200.3mA	194.8mA	203.3mA	Input @ 2.5MHz Load is 54Ω.
RS-449	37.8mA	40.3mA	41.1mA	42.9mA	142.3mA	138.8mA	147.4mA	Input @ 60kHz Load is 100Ω for RS-422 450Ω for RS-423
EIA-530	45.2mA	48.1mA	44.4mA	50.3mA	148.9mA	145.7mA	147.3mA	Input @ 60kHz Load is 100Ω for RS-422 450Ω for RS-423

## OTHER AC CHARACTERISTICS

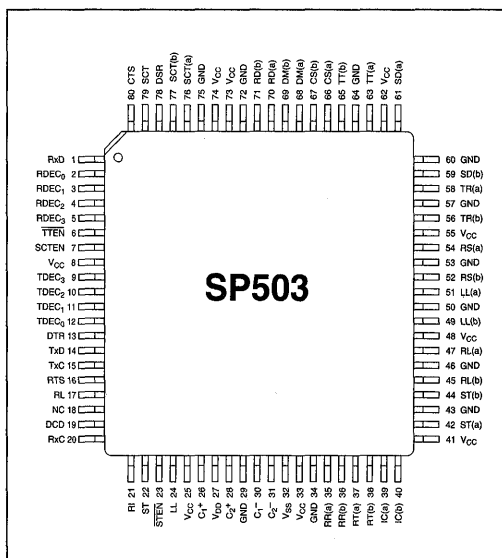
(Typical @ 25°C and nominal supply voltages unless otherwise noted)

PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>DELAY TIME FROM ENABLE MODE TO TRI-STATE MODE</b>					
<b>SINGLE-ENDED MODE (RS-232, RS-423)</b>					
$t_{PZL}$ : Enable to Output low		190		ns	3K $\Omega$ pull-up to output
$t_{PZH}$ : Enable to Output high		130		ns	3K $\Omega$ pull-down to output
$t_{PLZ}$ : Disable from Output low		270		ns	5V to input
$t_{PHZ}$ : Disable from Output high		400		ns	GND to input
<b>DIFFERENTIAL MODE (RS-422, RS-485, V.35)</b>					
$t_{PZL}$ : Enable to Output low		100		ns	3K $\Omega$ pull-up to output
$t_{PZH}$ : Enable to Output high		100		ns	3K $\Omega$ pull-down to output
$t_{PLZ}$ : Disable from Output low		130		ns	5V to input
$t_{PHZ}$ : Disable from Output high		140		ns	GND to input

### Notes:

1. Measured from 2.5V of  $R_{IN}$  to 2.5V of  $R_{OUT}$ .
2. Measured from one-half of  $R_{IN}$  to 2.5V of  $R_{OUT}$ .
3. Measured from 1.5V of  $T_{IN}$  to one-half of  $T_{OUT}$ .
4. Measured from 2.5V of  $R_O$  to 0V of A and B.

## PINOUT...



Pin 20 — RxC — Receive Clock; TTL output sourced from RT(a) and RT(b) inputs.

Pin 22 — ST — Send Timing; TTL input; source for ST(a) and ST(b) outputs.

Pin 37 — RT(a) — Receive Timing; analog input, inverted; source for RxC.

Pin 38 — RT(b) — Receive Timing; analog input, non-inverted; source for RxC.

Pin 42 — ST(a) — Send Timing; analog output, inverted; sourced from ST.

Pin 44 — ST(b) — Send Timing; analog output, non-inverted; sourced from ST.

Pin 59 — SD(b) — Analog Out — Send data, non-inverted; sourced from TxD.

Pin 61 — SD(a) — Analog Out — Send data, inverted; sourced from TxD.

Pin 63 — TT(a) — Analog Out — Terminal Timing, inverted; sourced from TxC

Pin 65 — TT(b) — Analog Out — Terminal Timing, non-inverted; sourced from TxC.

Pin 70 — RD(a) — Receive Data, analog input; inverted; source for RxD.

## PIN ASSIGNMENTS... CLOCK AND DATA GROUP

Pin 1 — RxD — Receive Data; TTL output, sourced from RD(a) and RD(b) inputs.

Pin 14 — TxD — TTL input ; transmit data source for SD(a) and SD(b) outputs.

Pin 15 — TxC — Transmit Clock; TTL input for TT driver outputs.

Pin 71 — RD(b) — Receive Data; analog input; non-inverted; source for Rx/D.

Pin 76 — SCT(a) — Serial Clock Transmit; analog input, inverted; source for SCT.

Pin 77 — SCT(b) — Serial Clock Transmit; analog input, non-inverted; source for SCT

Pin 79 — SCT — Serial Clock Transmit; TTL output; sources from SCT(a) and SCT(b) inputs.

### CONTROL LINE GROUP

Pin 13 — DTR — Data Terminal Ready; TTL input; source for TR(a) and TR(b) outputs.

Pin 16 — RTS — Ready To Send; TTL input; source for RS(a) and RS(b) outputs.

Pin 17 — RL — Remote Loopback; TTL input; source for RL(a) and RL(b) outputs.

Pin 19 — DCD — Data Carrier Detect; TTL output; sourced from RR(a) and RR(b) inputs.

Pin 21 — RI — Ring In; TTL output; sourced from IC(a) and IC(b) inputs.

Pin 24 — LL — Local Loopback; TTL input; source for LL(a) and LL(b) outputs.

Pin 35 — RR(a) — Receiver Ready; analog input, inverted; source for DCD.

Pin 36 — RR(b) — Receiver Ready; analog input, non-inverted; source for DCD.

Pin 39 — IC(a) — Incoming Call; analog input, inverted; source for RI.

Pin 40 — IC(b) — Incoming Call; analog input, non-inverted; source for RI.

Pin 45 — RL(b) — Remote Loopback; analog output, non-inverted; sourced from RL.

Pin 47 — RL(a) — Remote Loopback; analog output inverted; sourced from RL.

Pin 49 — LL(b) — Local Loopback; analog output, non-inverted; sourced from LL.

Pin 51 — LL(a) — Local Loopback; analog output, inverted; sourced from LL.

Pin 52 — RS(b) — Ready To Send; analog output, non-inverted; sourced from RTS.

Pin 54 — RS(a) — Ready To Send; analog output, inverted; sourced from RTS.

Pin 56 — TR(b) — Terminal Ready; analog output, non-inverted; sourced from DTR.

Pin 58 — TR(a) — Terminal Ready; analog output, inverted; sourced from DTR.

Pin 66 — CS(a) — Clear To Send; analog input, inverted; source for CTS.

Pin 67 — CS(b) — Clear To Send; analog input, non-inverted; source for CTS.

Pin 68 — DM(a) — Data Mode; analog input, inverted; source for DSR.

Pin 69 — DM(b) — Data Mode; analog input, non-inverted; source for DSR

Pin 78 — DSR — Data Set Ready; TTL output; sourced from DM(a), DM(b) inputs.

Pin 80 — CTS — Clear To Send; TTL output; sourced from CS(a) and CS(b) inputs.

### CONTROL REGISTERS

Pins 2–5 — RDEC<sub>0</sub> – RDEC<sub>3</sub> — Receiver decode register; configures receiver modes; TTL inputs.

Pin 6 —  $\overline{\text{TEN}}$  — Enables TT driver, active low; TTL input.

Pin 7 — SCTEN — Enables SCT receiver; active high; TTL input.

Pins 12–9 — TDEC<sub>0</sub> – TDEC<sub>3</sub> — Transmitter decode register; configures transmitter modes; TTL inputs.

Pin 23 —  $\overline{\text{STEN}}$  — Enables ST driver; active low; TTL input.

### POWER SUPPLIES

Pins 8, 25, 33, 41, 48, 55, 62, 73, 74 — V<sub>CC</sub> — +5V input.

Pins 29, 34, 43, 46, 50, 53, 57, 60, 64, 72, 75 — GND — Ground.

Pin 27 — V<sub>DD</sub> +10V Charge Pump Capacitor — Connects from V<sub>DD</sub> to V<sub>CC</sub>. Suggested capacitor size is 22 $\mu$ F, 16V.

Pin 32 —  $V_{SS}$  -10V Charge Pump Capacitor — Connects from ground to  $V_{SS}$ . Suggested capacitor size is  $22\mu\text{F}$ , 16V.

Pins 26 and 30 —  $C_1^+$  and  $C_1^-$  — Charge Pump Capacitor — Connects from  $C_1^+$  to  $C_1^-$ . Suggested capacitor size is  $22\mu\text{F}$ , 16V.

Pins 28 and 31 —  $C_2^+$  and  $C_2^-$  — Charge Pump Capacitor — Connects from  $C_2^+$  to  $C_2^-$ . Suggested capacitor size is  $22\mu\text{F}$ , 16V.

NOTE: NC pins should be left floating; internal signals may be present.

## FEATURES...

The **SP503** is a highly integrated serial transceiver that allows software control of its interface modes. The **SP503** offers hardware interface modes for RS-232 (V.28), RS-422A (V.11), RS-449, RS-485, V.35, and EIA-530. The interface mode selection is done via an 8-bit switch; four (4) bits control the drivers and four (4) bits control the receivers. The **SP503** is fabricated using low-power BiCMOS process technology, and incorporates a **Sipex**-patented (5,306,954) charge pump allowing +5V only operation. Each device is packaged in an 80-pin Quad FlatPack package.

The **SP503** is ideally suited for wide area network connectivity based on the interface modes offered and the driver and receiver configurations. The **SP503** has seven (7) independent drivers and seven (7) independent receivers. The seventh driver of the **SP503** allows it to support applications which require two separate clock outputs making it ideal for DCE applications.

## THEORY OF OPERATION

The **SP503** is made up of four separate circuit blocks — the charge pump, drivers, receivers, and decoder. Each of these circuit blocks is described in more detail below.

### Charge-Pump

The charge pump is a **Sipex**-patented design (5,306,954) and uses a unique approach com-

pared to older less-efficient designs. The charge pump still requires four external capacitors, but uses a four-phase voltage shifting technique to attain symmetrical 10V power supplies. Figure 3(a) shows the waveform found on the positive side of capacitor  $C_2$ , and figure 3(b) shows the negative side of capacitor  $C_2$ . There is a free-running oscillator that controls the four phases of the voltage shifting. A description of each phase follows.

### Phase 1

—  $V_{SS}$  charge storage — During this phase of the clock cycle, the positive side of capacitors  $C_1$  and  $C_2$  are initially charged to +5V.  $C_1^+$  is then switched to ground and charge on  $C_1^-$  is transferred to  $C_2^-$ . Since  $C_2^+$  is connected to +5V, the voltage potential across capacitor  $C_2$  is now 10V.

### Phase 2

—  $V_{SS}$  transfer — Phase two of the clock connects the negative terminal of  $C_2$  to the  $V_{SS}$  storage capacitor and the positive terminal of  $C_2$  to ground, and transfers the generated -10V to  $C_3$ . Simultaneously, the positive side of capacitor  $C_1$  is switched to +5V and the negative side is connected to ground.

### Phase 3

—  $V_{DD}$  charge storage — The third phase of the clock is identical to the first phase — the charge transferred in  $C_1$  produces -5V in the negative terminal of  $C_1$ , which is applied to the negative side of capacitor  $C_2$ . Since  $C_2^+$  is at +5V, the voltage potential across  $C_2$  is 10V.

### Phase 4

—  $V_{DD}$  transfer — The fourth phase of the clock connects the negative terminal of  $C_2$  to ground and transfers the generated 10V across  $C_2$  to  $C_4$ , the  $V_{DD}$  storage capacitor. Again,

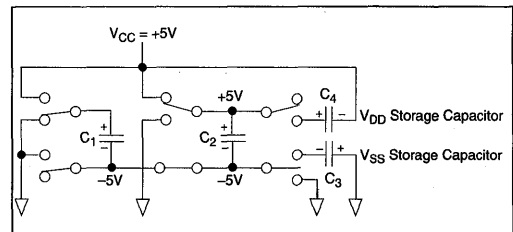


Figure 1. Charge Pump Phase 1.

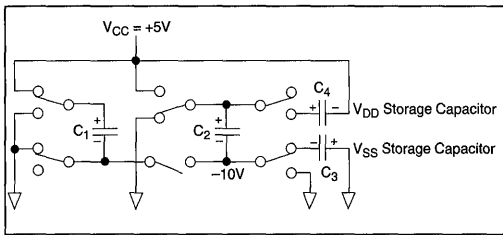


Figure 2. Charge Pump Phase 2.

simultaneously with this, the positive side of capacitor  $C_1$  is switched to +5V and the negative side is connected to ground, and the cycle begins again.

Since both  $V_+$  and  $V_-$  are separately generated from  $V_{CC}$  in a no-load condition,  $V_+$  and  $V_-$  will be symmetrical. Older charge pump approaches that generate  $V_-$  from  $V_+$  will show a decrease in the magnitude of  $V_-$  compared to  $V_+$  due to the inherent inefficiencies in the design.

The clock rate for the charge pump typically operates at 15kHz. The external capacitors must be 22 $\mu$ F with a 16V breakdown rating.

### External Power Supplies

For applications that do not require +5V only, external supplies can be applied at the  $V_+$  and  $V_-$  pins. The value of the external supply voltages must be no greater than  $\pm 10V$ . The current drain for the  $\pm 10V$  supplies is used for RS232,

and RS-423 drivers. For the RS-232 driver the current requirement will be 3.5mA per driver, and for the RS-423 driver the worst case current drain will be 11mA per driver. The external power supplies should provide a power supply sequence of :+10V, then +5V, followed by -10V.

### Drivers

The SP503 has seven (7) independent drivers, two of which have separate active-low tri-state controls. If a half-duplex channel is required, this can be achieved with external connections.

Control for the mode selection is done via a four-bit control word. The SP503 does not have a latch; the control word must be externally latched either high or low to write the appropriate code into the SP503. The drivers are pre-arranged such that for each mode of operation the relative position and functionality of the drivers are set up to accommodate the selected interface mode. As the mode of the drivers is changed, the electrical characteristics will change to support the requirements of clock, data, and control line signal levels. Table 1 shows a summary of the electrical characteristics of the drivers in the different interface modes. Unused driver inputs can be left floating; however, to ensure a desired state with no input signal, pull-up resistors to +5V or pull-down resistors to ground are suggested. Since the driver inputs are both TTL or CMOS compatible, any value resistor less than 100K $\Omega$  will suffice.

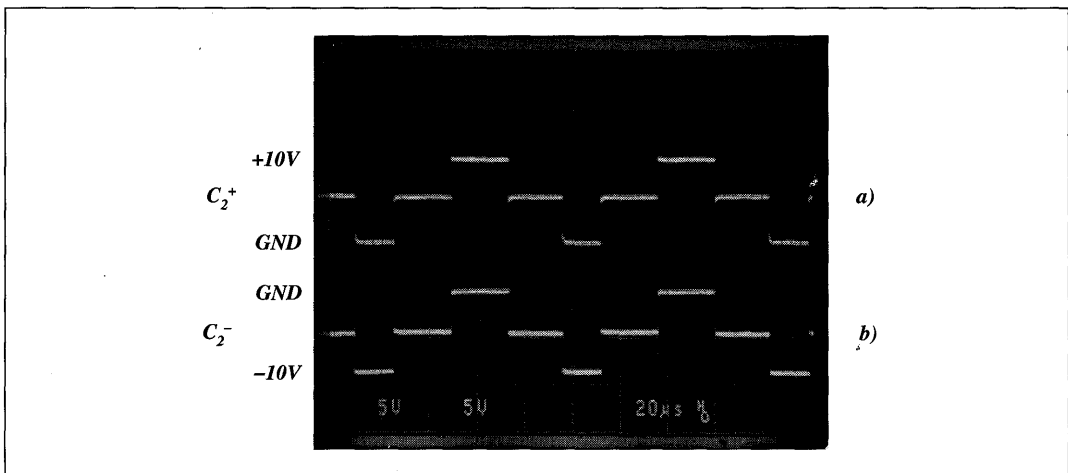


Figure 3. Charge Pump Waveforms

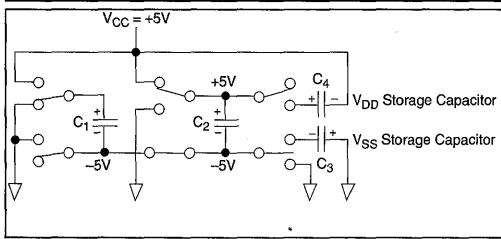


Figure 4. Charge Pump Phase 3.

There are three basic types of driver circuits — RS-232, RS-423, and RS-485. The RS-232 drivers output a minimum of  $\pm 5V$  level single-ended signals (with  $3K\Omega$  and  $2500pF$  loading), and can operate up to  $120Kbps$ . The RS232 drivers are used in RS232 mode for all signals, and also in V.35 mode where they are used as the control line signals.

The RS-423 drivers output a minimum of  $\pm 3.6V$  level single-ended signals (with  $450\Omega$  loading) and can operate up to  $120Kbps$ . Open circuit  $V_{OL}$  and  $V_{OH}$  measurements may exceed the  $\pm 6V$  limitation of RS-423. The RS-423 drivers are used in RS-449 and EIA-530 modes as RL and LL outputs.

The third type of driver supports RS-485, which is a differential signal that can maintain  $\pm 1.5V$  differential output levels with a worst case load of  $54\Omega$ . The signal levels and drive capability of

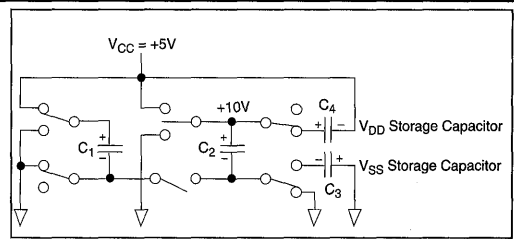


Figure 5. Charge Pump Phase 4.

the RS-485 drivers allow the drivers to also support RS-422 requirements of  $\pm 2V$  differential output levels with  $100\Omega$  loads. The RS-422 drivers are used in RS-449 and EIA-530 modes as clock, data, and some control line signals.

The RS-485-type drivers are also used in the V.35 mode. V.35 levels require  $\pm 0.55V$  signals with a load of  $100\Omega$ . In order to meet the voltage requirements of V.35, external series resistors with source impedance termination resistors must be implemented to voltage divide the driver outputs from 0 to  $+5V$  to 0 to  $+0.55V$ . Figure 6 shows the values of the resistor network and how to connect them. The termination network also achieves the  $50\Omega$  to  $150\Omega$  source impedance for V.35. For applications that require V.11 signals for clock and data instead of V.35 levels, omit the external termination networks. All of the differential drivers, RS-485, RS-422, and V.35 can operate up to  $5Mbps$ .

Pin Label	Mode:	RS-232	V.35	RS-422	RS-485	RS-449	EIA-530
$TDEC_3$ - $TDEC_0$	0000	0010	1110	0100	0101	1100	1101
SD(a)	tri-state	RS-232	V.35-	RS-422-	RS-485-	RS-422-	RS-422-
SD(b)	tri-state	tri-state	V.35+	RS-422+	RS-485+	RS-422+	RS-422+
TR(a)	tri-state	RS-232	RS-232	RS-422-	RS-485-	RS-422-	RS-422-
TR(b)	tri-state	tri-state	tri-state	RS-422+	RS-485+	RS-422+	RS-422+
RS(a)	tri-state	RS-232	RS-232	RS-422-	RS-485-	RS-422-	RS-422-
RS(b)	tri-state	tri-state	tri-state	RS-422+	RS-485+	RS-422+	RS-422+
RL(a)	tri-state	RS-232	RS-232	RS-422-	RS-485-	RS-423	RS-423
RL(b)	tri-state	tri-state	tri-state	RS-422+	RS-485+	tri-state	tri-state
LL(a)	tri-state	RS-232	RS-232	RS-422-	RS-485-	RS-423	RS-423
LL(b)	tri-state	tri-state	tri-state	RS-422+	RS-485+	tri-state	tri-state
ST(a)	tri-state	RS-232	V.35-	RS-422-	RS-485-	RS-422-	RS-422-
ST(b)	tri-state	tri-state	V.35+	RS-422+	RS-485+	RS-422+	RS-422+
TT(a)	tri-state	RS-232	V.35-	RS-422-	RS-485-	RS-422-	RS-422-
TT(b)	tri-state	tri-state	V.35+	RS-422+	RS-485+	RS-422+	RS-422+

Table 1. SP503 Drivers



## Receivers

The **SP503** has seven (7) independent receivers which can be programmed for six (6) different interface modes. One of the seven (7) receivers (SCT) has an active-high enable control, as shown in the Mode Diagrams.

Control for the mode selection is done via a 4-bit control word that is independent from the driver control word. The coding for the drivers and receivers is identical. Therefore, if the modes for the drivers and receivers are supposed to be identical in the application, the control lines can be tied together.

Like the drivers, the receivers are pre-arranged for the specific requirements of the interface. As the operating mode of the receivers is changed, the electrical characteristics will change to support the requirements of clock, data, and control line receivers. *Table 2* shows a summary of the electrical characteristics of the receivers in the different interface modes. Unused receiver inputs can be left floating without causing oscillation. To ensure a desired state of the receiver output, a pull-up resistor of 100K $\Omega$  to +5V should be connected to the inverting input for a logic low, or the non-inverting input for a logic high. For single-ended receivers, a pull-down resistor to ground of 5K $\Omega$  is internally connected, which will ensure a logic high output.

There are three basic types of receivers — RS-232, RS-423, and RS-485. The RS-232 receiver is a single-ended input with a threshold of 0.8V to 2.4V. The RS-232 receiver has an operating voltage range of  $\pm 15V$  and can receive signals up to 120Kbps. RS-232 receivers are used in RS-232 mode for all signal types, and in V.35 mode for control line signals.

The RS-423 receivers are also single-ended but have an input threshold as low as  $\pm 200mV$ . The input impedance is guaranteed to be greater than 4K $\Omega$ , with an operating voltage range of  $\pm 7V$ . The RS-423 receivers can operate up to 120Kbps. RS-423 receivers are used for the IC signal in RS-449 and EIA-530 modes, as shown in *Table 2*.

The third type of receiver supports RS-485, which is a differential interface mode. The RS-485 receiver has an input impedance of 15K $\Omega$  and a differential threshold of  $\pm 200mV$ . Since the characteristics of an RS-422 receiver are actually subsets of RS485, the receivers for RS-422 requirements are identical to the RS-485 receivers. RS-422 receivers are used in RS-449 and EIA-530 for receiving clock, data, and some control line signals. The RS-485 receivers are also used for the V.35 mode. V.35 levels require the  $\pm 0.55V$  signals with a load of 100 $\Omega$ . In order to meet the V.35 input impedance of 100 $\Omega$ , the external termination network of *Figure 6* must be applied. The threshold of the V.35 receiver is  $\pm 200mV$ . The V.35 receivers

Pin Label	Mode:	RS-232	V.35	RS-422	RS-485	RS-449	EIA-530
RDEC <sub>3</sub> -RDEC <sub>0</sub>	0000	0010	1110	0100	0101	1100	1101
RD(a)	Undefined	RS-232	V.35-	RS-422-	RS-485-	RS-422-	RS-422-
RD(b)	Undefined	15K $\Omega$ to GND	V.35+	RS-422+	RS-485+	RS-422+	RS-422+
RT(a)	Undefined	RS-232	V.35-	RS-422-	RS-485-	RS-422-	RS-422-
RT(b)	Undefined	15K $\Omega$ to GND	V.35+	RS-422+	RS-485+	RS-422+	RS-422+
CS(a)	Undefined	RS-232	RS-232	RS-422-	RS-485-	RS-422-	RS-422-
CS(b)	Undefined	15K $\Omega$ to GND	15K $\Omega$ to GND	RS-422+	RS-485+	RS-422+	RS-422+
DM(a)	Undefined	RS-232	RS-232	RS-422-	RS-485-	RS-422-	RS-422-
DM(b)	Undefined	15K $\Omega$ to GND	15K $\Omega$ to GND	RS-422+	RS-485+	RS-422+	RS-422+
RR(a)	Undefined	RS-232	RS-232	RS-422-	RS-485-	RS-422-	RS-422-
RR(b)	Undefined	15K $\Omega$ to GND	15K $\Omega$ to GND	RS-422+	RS-485+	RS-422+	RS-422+
IC(a)	Undefined	RS-232	RS-232	RS-422-	RS-485-	RS-423	RS-423
IC(b)	Undefined	15K $\Omega$ to GND	15K $\Omega$ to GND	RS-422+	RS-485+	15K $\Omega$ to GND	15K $\Omega$ to GND
SCT(a)	Undefined	RS-232	V.35-	RS-422-	RS-485-	RS-422-	RS-422-
SCT(b)	Undefined	15K $\Omega$ to GND	V.35+	RS-422+	RS-485+	RS-422+	RS-422+

*Table 2. SP503 Receivers*



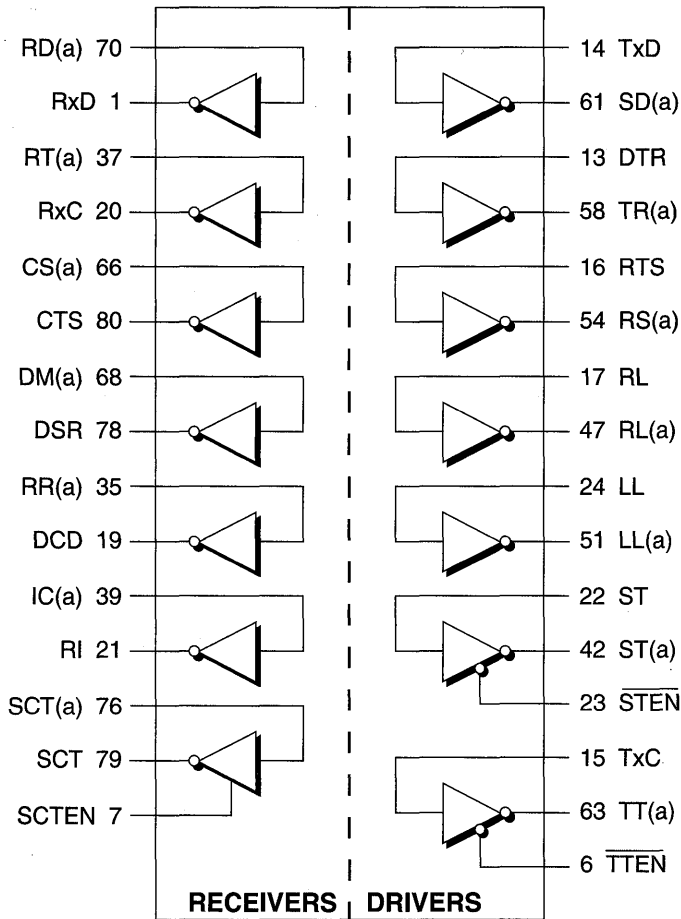
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can operate up to 5Mbps. All of the differential receivers can receive data up to 5Mbps.

### Decoder

The **SP503** has the ability to change the interface mode of the drivers or receivers via an 8-bit switch. The decoder for the drivers and receivers is not latched; it is merely a combinational logic switch. The codes shown in *Tables 1 and 2* are the only specified, valid modes for the **SP503**. Undefined codes may represent other interface modes not specified or random outputs (consult the factory for more information). The drivers are controlled with the data bits labeled  $TDEC_3$ – $TDEC_0$ . The drivers can be put into tri-state mode by writing 0000 to the driver decode switch. The receivers are controlled with data bits  $RDEC_3$ – $RDEC_0$ ; the code 0000 written to the receivers will place the outputs in an undetermined state. All receivers, with the exception of **SCT**, do not have tri-state capability; the outputs will either be high or low depending upon the state of the receiver input.

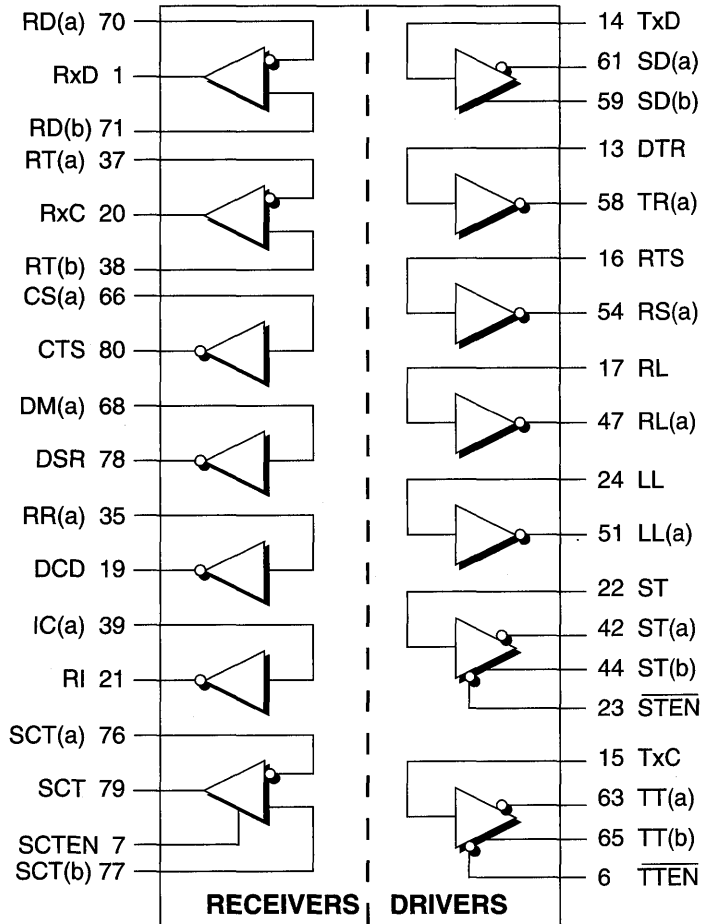
MODE: RS-232							
DRIVER				RECEIVER			
TDEC <sub>3</sub>	TDEC <sub>2</sub>	TDEC <sub>1</sub>	TDEC <sub>0</sub>	RDEC <sub>3</sub>	RDEC <sub>2</sub>	RDEC <sub>1</sub>	RDEC <sub>0</sub>
0	0	1	0	0	0	1	0



$\overline{\text{STEN}}$	ST	$\overline{\text{TTEN}}$	TT	SCTEN	SCT
1	Disabled	1	Disabled	1	Enabled
0	Enabled	0	Enabled	0	Disabled

Figure 7. Mode Diagram — RS-232

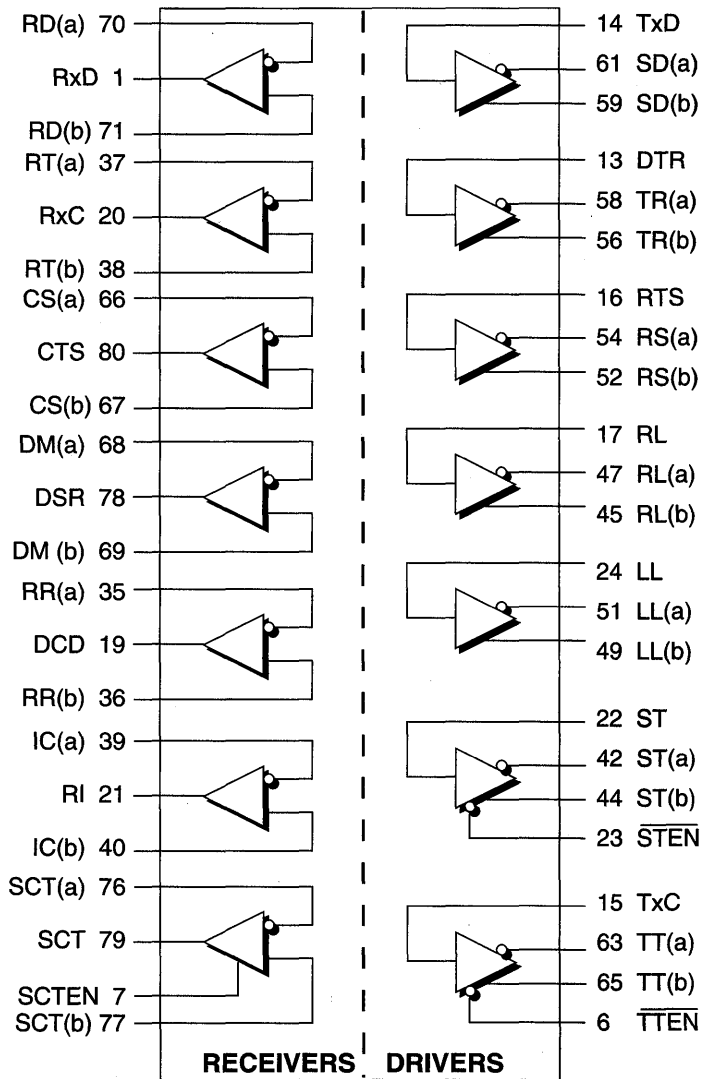
MODE: V.35							
DRIVER				RECEIVER			
TDEC <sub>3</sub>	TDEC <sub>2</sub>	TDEC <sub>1</sub>	TDEC <sub>0</sub>	RDEC <sub>3</sub>	RDEC <sub>2</sub>	RDEC <sub>1</sub>	RDEC <sub>0</sub>
1	1	1	0	1	1	1	0



$\overline{\text{STEN}}$	ST	$\overline{\text{TTEN}}$	TT	SCTEN	SCT
1	Disabled	1	Disabled	1	Enabled
0	Enabled	0	Enabled	0	Disabled

Figure 8. Mode Diagram — V.35

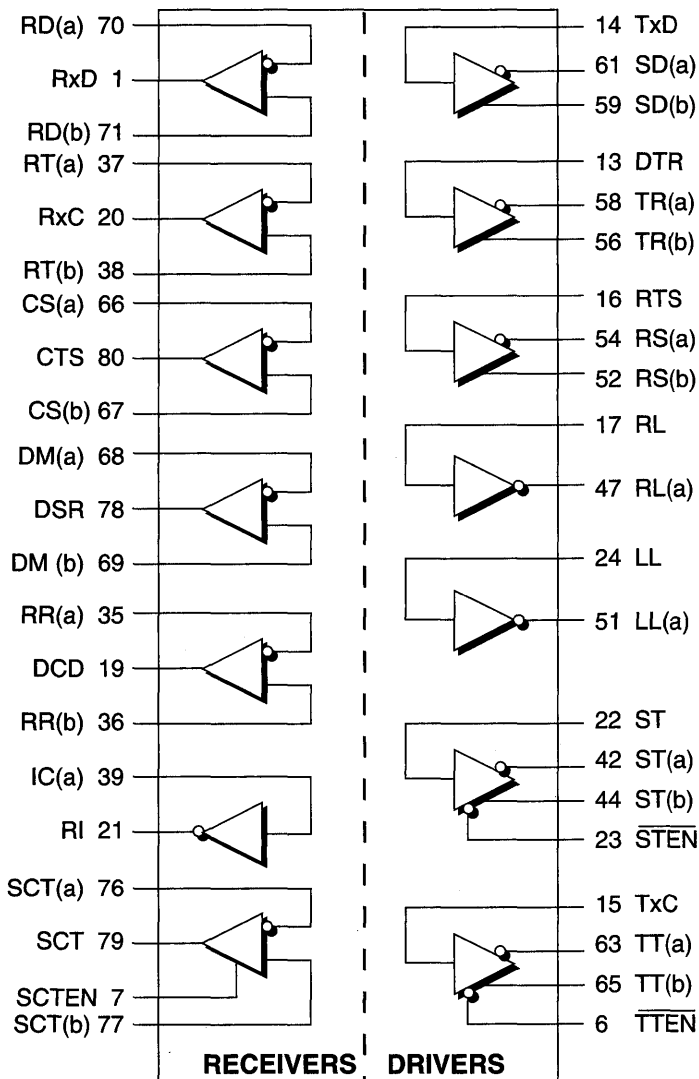
MODE: RS-422							
DRIVER				RECEIVER			
TDEC <sub>3</sub>	TDEC <sub>2</sub>	TDEC <sub>1</sub>	TDEC <sub>0</sub>	RDEC <sub>3</sub>	RDEC <sub>2</sub>	RDEC <sub>1</sub>	RDEC <sub>0</sub>
0	1	0	0	0	1	0	0



STEN	ST	$\overline{\text{TTEN}}$	TT	SCTEN	SCT
1	Disabled	1	Disabled	1	Enabled
0	Enabled	0	Enabled	0	Disabled

Figure 9. Mode Diagram — RS-422

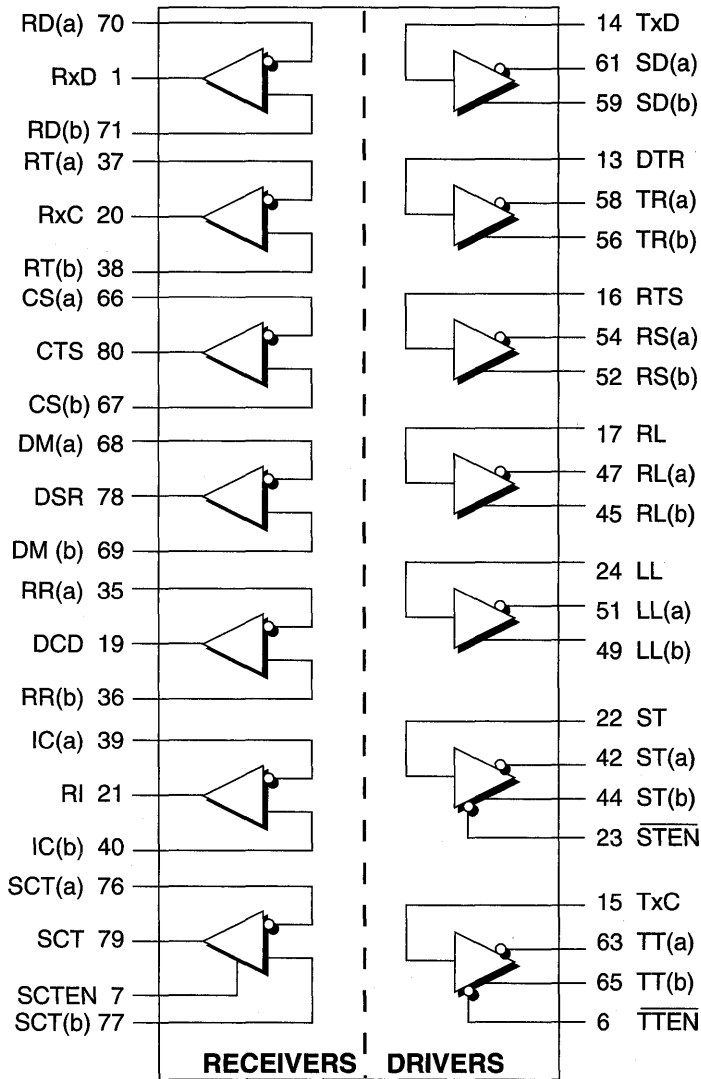
MODE: RS-449							
DRIVER				RECEIVER			
TDEC <sub>3</sub>	TDEC <sub>2</sub>	TDEC <sub>1</sub>	TDEC <sub>0</sub>	RDEC <sub>3</sub>	RDEC <sub>2</sub>	RDEC <sub>1</sub>	RDEC <sub>0</sub>
1	1	0	0	1	1	0	0



STEN	ST	TTEN	TT	SCTEN	SCT
1	Disabled	1	Disabled	1	Enabled
0	Enabled	0	Enabled	0	Disabled

Figure 10. Mode Diagram — RS-449

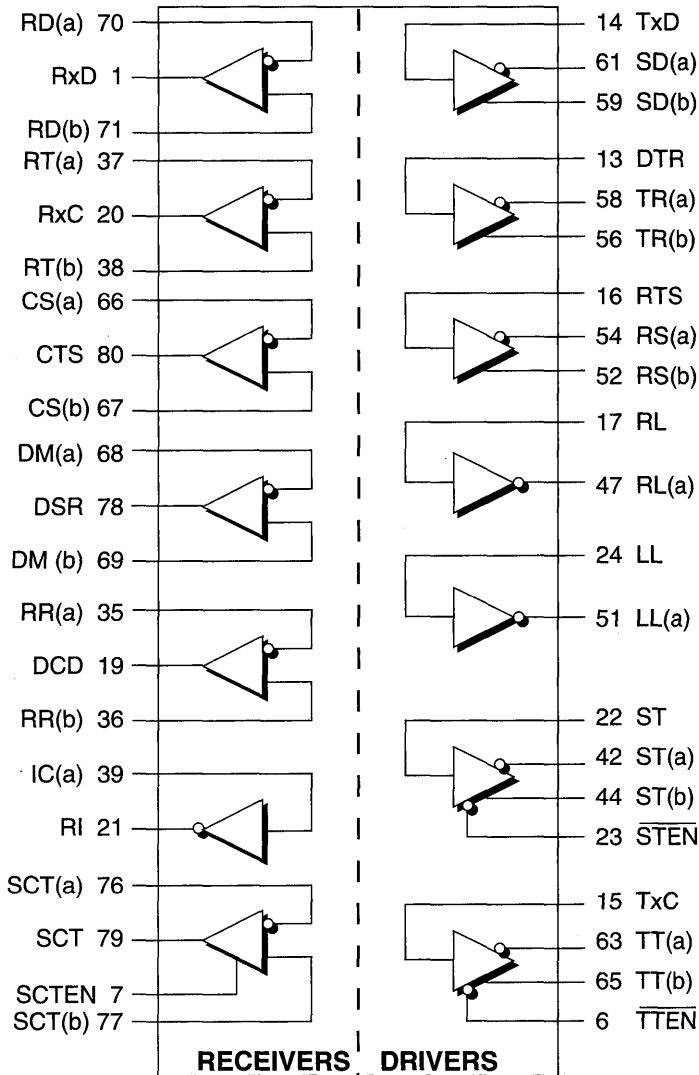
MODE: RS-485							
DRIVER				RECEIVER			
TDEC <sub>3</sub>	TDEC <sub>2</sub>	TDEC <sub>1</sub>	TDEC <sub>0</sub>	RDEC <sub>3</sub>	RDEC <sub>2</sub>	RDEC <sub>1</sub>	RDEC <sub>0</sub>
0	1	0	1	0	1	0	1



$\overline{\text{STEN}}$	ST	$\overline{\text{TTEN}}$	TT	SCTEN	SCT
1	Disabled	1	Disabled	1	Enabled
0	Enabled	0	Enabled	0	Disabled

Figure 11. Mode Diagram — RS-485

MODE: EIA-530							
DRIVER				RECEIVER			
TDEC <sub>3</sub>	TDEC <sub>2</sub>	TDEC <sub>1</sub>	TDEC <sub>0</sub>	RDEC <sub>3</sub>	RDEC <sub>2</sub>	RDEC <sub>1</sub>	RDEC <sub>0</sub>
1	1	0	1	1	1	0	1



$\overline{\text{STEN}}$	ST	$\overline{\text{TTEN}}$	TT	SCTEN	SCT
1	Disabled	1	Disabled	1	Enabled
0	Enabled	0	Enabled	0	Disabled

Figure 12. Mode Diagram — EIA-530

## SP502/SP503 EVALUATION BOARD

The **SP502/SP503 Evaluation Board (EB)** is designed to offer as much flexibility to the user as possible. Each board comes equipped with an 80-pin QFP Zero-Insertion socket to allow for testing of multiple devices. The control lines and inputs and outputs of the device can be controlled either manually or via a data bus under software control. There is a 50-pin connector to allow for easy connection to an existing system via a ribbon cable. There are also open areas on the PC board to add additional circuitry to support application-specific requirements.

### Manual Control

The **SP502/SP503EB** will support both the **SP502** or **SP503** multi-mode serial transceivers. When used for the **SP502**, disregard all notation on the board that is in (brackets). The **SP502** has a half-duplex connection between the RxT receiver and the TT driver. Due to this internal connection, the RxT receiver inputs can be accessed via the TT(a) and TT(b) pins. If the user needs separate receiver input test pins, jumpers JP1 and JP2 can be inserted to allow for separate receiver inputs located at SCT(a) and SCT(b). The corresponding TTL output for this receiver is labeled as SCT. This test point is tied to pin 79 of the **SP502** or **SP503**. Pin 7 of the evaluation board is connected to the DIP switch, and is labeled as (SCTEN). When used with the **SP502**, this pin should be switched to a low state. When the evaluation board is used with the **SP503**, pin 7 is a tri-state control pin for the SCT receiver.

The transceiver I/O lines are brought out to test pins arranged in the same configuration as shown elsewhere in this data sheet. A top layer silk-screen shows the drivers and receivers to allow direct correlation to the data sheet. The transmitter and receiver decode bits are tied together and are brought out to a DIP switch for manual control of both the driver and receiver interface modes. Since the coding for the drivers and receivers is identical, the bits have been tied together. The DIP switch has 7 positions, four of which are reserved for the TDEC/RDEC control and the other three are used as tri-state control pins. The labels that are in [brackets] apply only

to the **SP503**. If a logic one is asserted, the corresponding red LED will be lit. If a zero is asserted, the corresponding red LED will not be lit.

### Software Control

A 50-pin connector brings all the analog and digital I/O lines,  $V_{CC}$ , and GND to the edge of the card. This can be wired to the user's existing design via a ribbon cable. The pinout for the connector is described in the following section. When the evaluation board is operated under software control, the DIP switch should be set up so that all bits are low (all LEDs off). This will tie 20K $\Omega$  pull-down resistors from the inputs to ground and let the external system control the state of the control inputs.

### Power and Ground Requirements

The evaluation board layout has been optimized for performance by using basic analog circuit techniques. The four charge-pump capacitors must be 22 $\mu$ F (16V) and be placed as close to the unit as possible; tantalum capacitors are suggested. The decoupling capacitor must be a minimum of 1 $\mu$ F; depending upon the operating environment, 10 $\mu$ F should be enough for worst case situations. The ground plane for the part must be solid, extending completely under the package. The power supplies for the device should be as accurate as possible; for rated performance  $\pm 5\%$  is necessary. The power supply current will vary depending upon the selected mode, the amount of loading and the data rate. As a maximum, the user should reserve 200mA for  $I_{CC}$ . The worst-case operating mode is RS485 under full load of six (6) drivers supplying 1.6V to 54 $\Omega$  loads. The power and ground inputs can be supplied through either the banana jacks on the evaluation board (Red =  $V_{CC}$  =  $+5V \pm 5\%$ ; Black = GND) or through the connector.

For reference, the 80-pin QFP Socket is a TESCO part number FPQ-80-65-09A. The 50-pin connector is an AMP part number 749075-5.



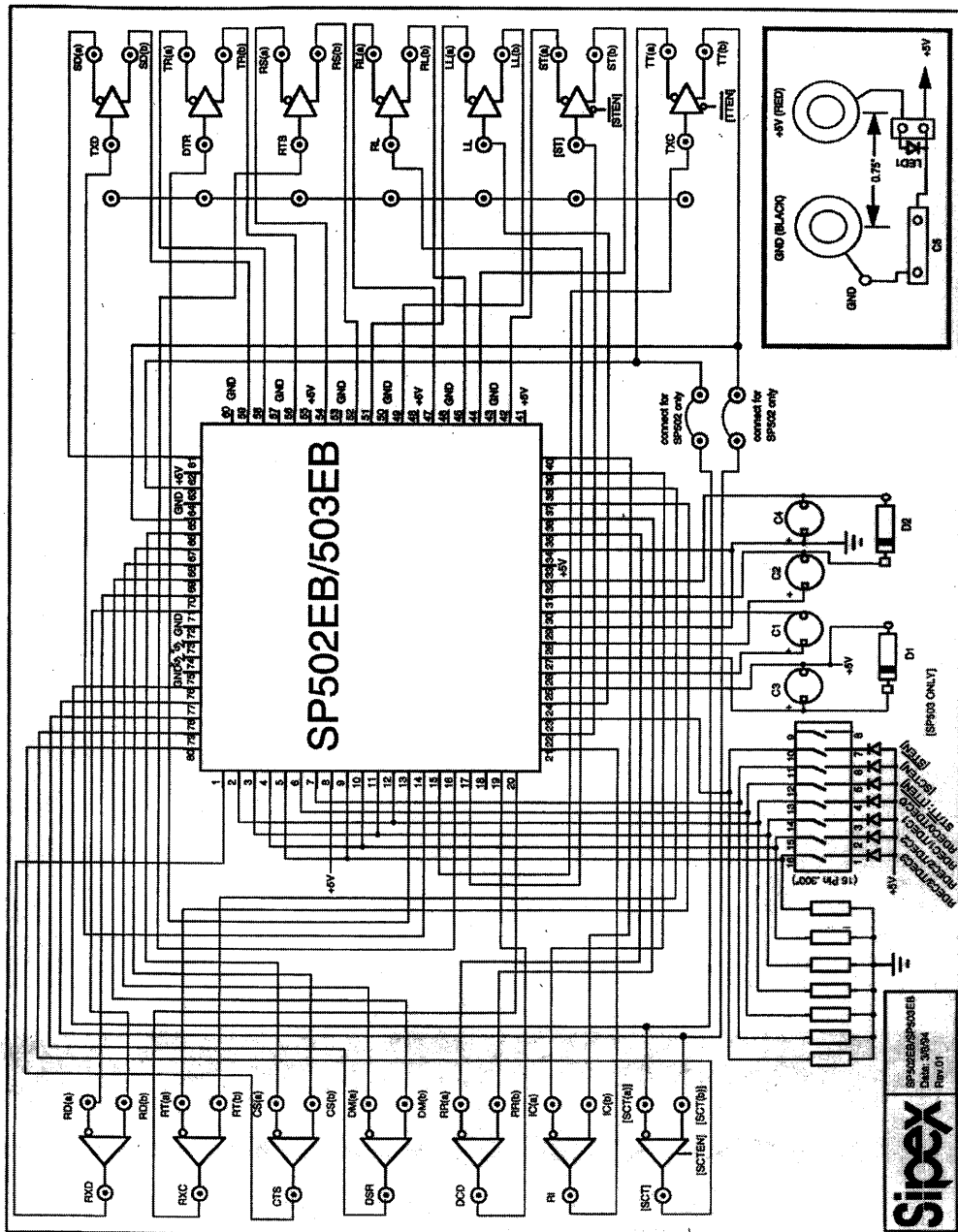
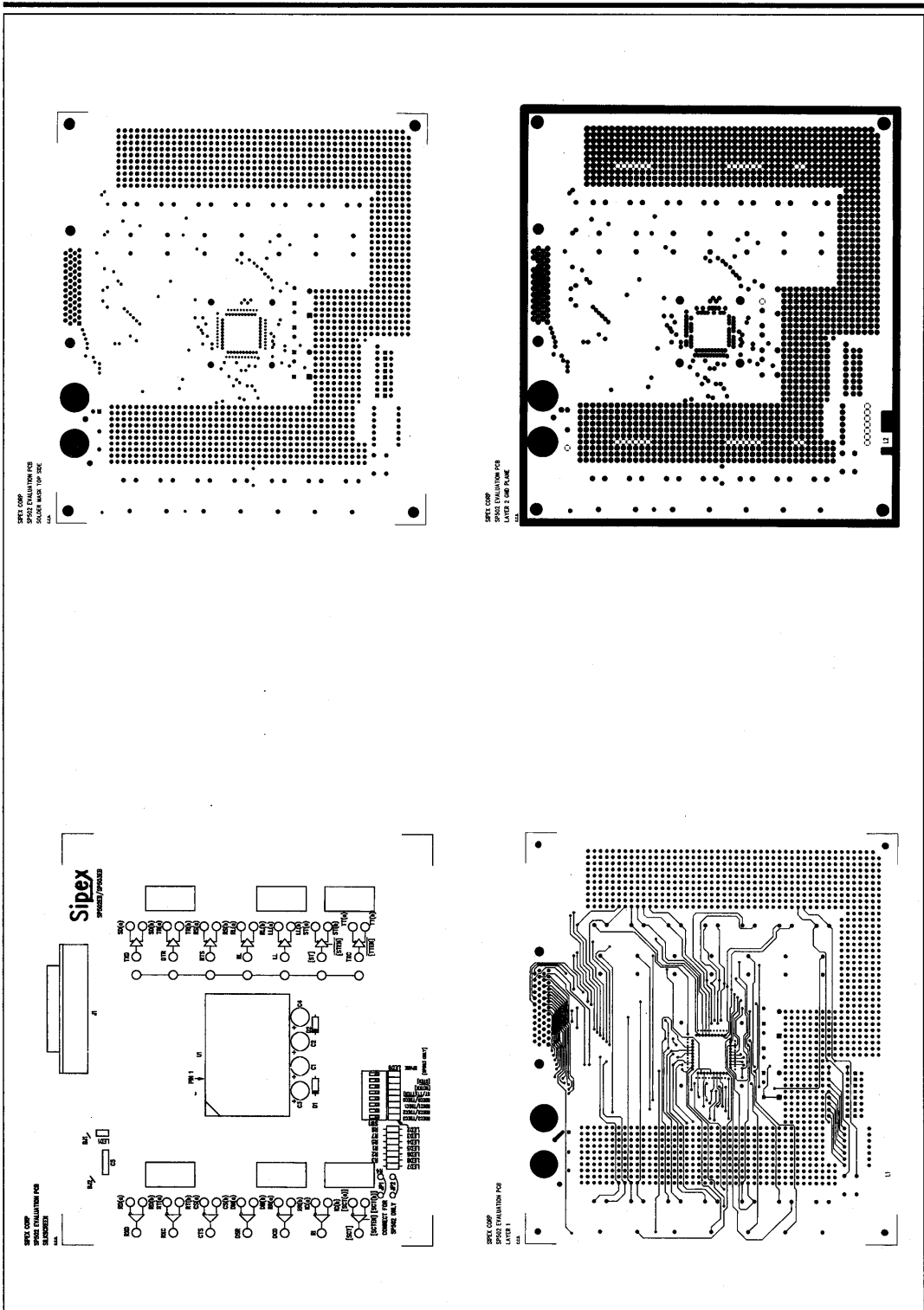


Figure 13. SP502/503 Evaluation Board Schematic



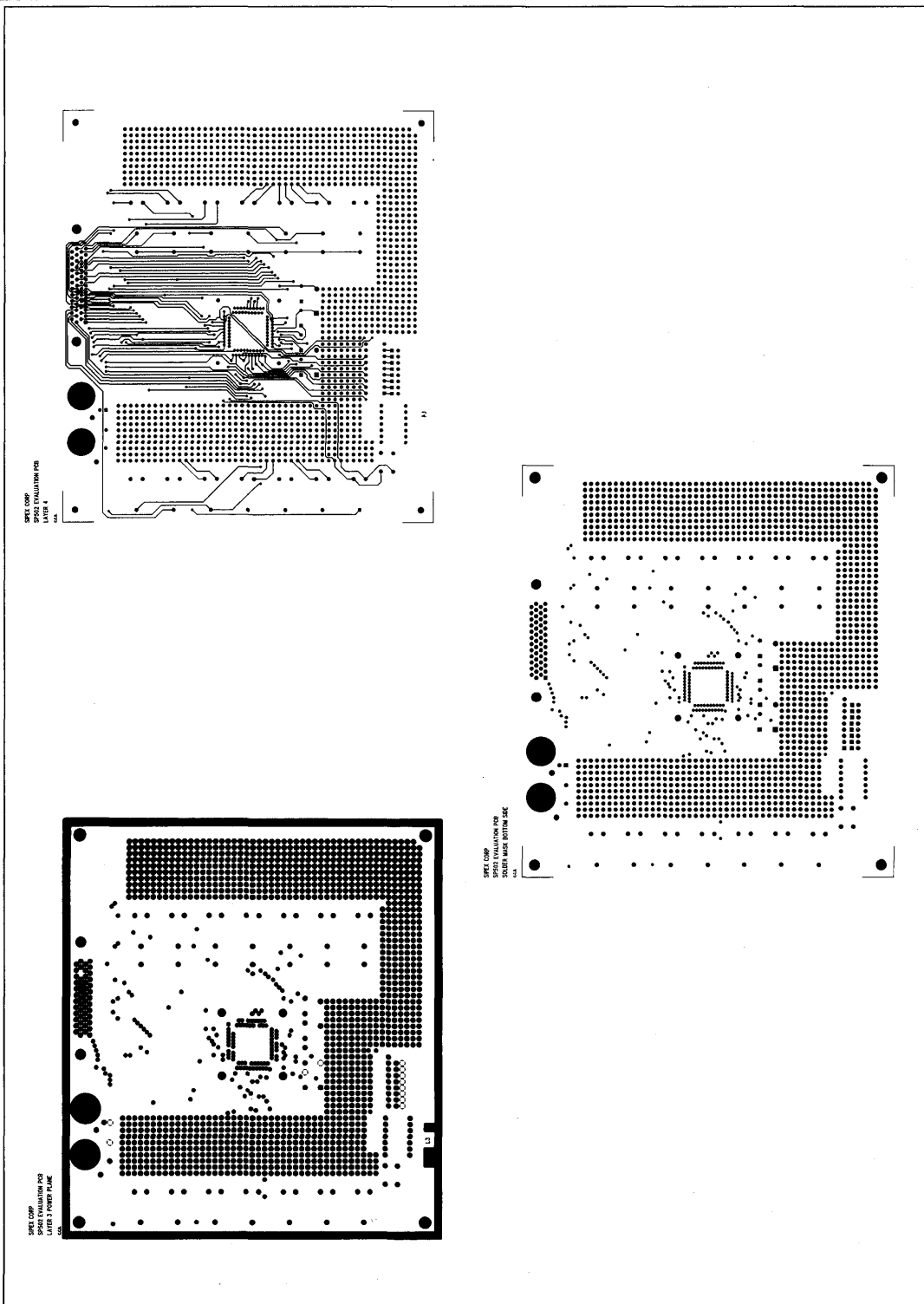


Figure 14b. Evaluation Board — Bottom Layers

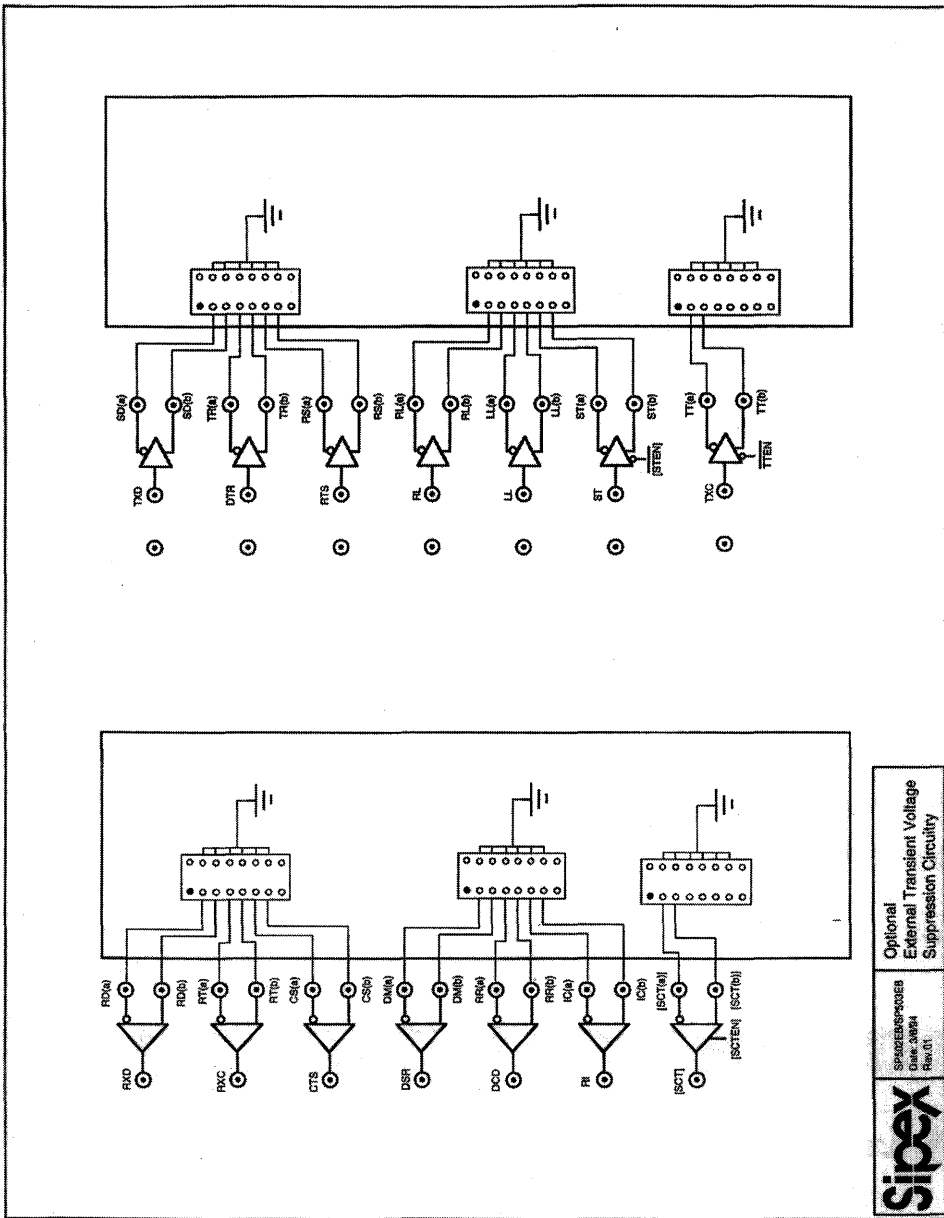
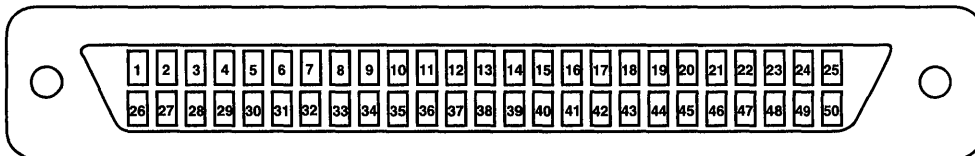
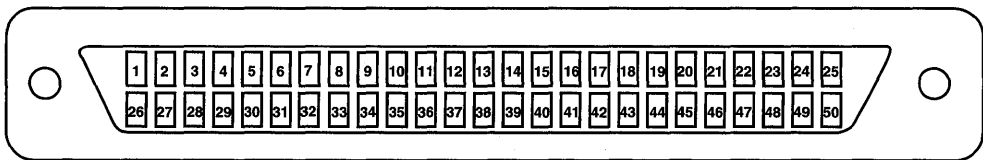


Figure 15. External Transient Suppressors



EDGE CONNECTOR	DUT PIN DESCRIPTIONS	EDGE CONNECTOR	DUT PIN DESCRIPTIONS
01	TxD (pin 14) – TTL Input – Transmit data; source for SD(a) and SD(b) outputs.	13	RD(a) (pin 70) – Analog In – Receive data, inverted; source for RxD.
02	DTR (pin 13) – TTL Input – Data terminal ready; source for TR(a) and TR(b) outputs.	14	DM(b) (pin 69) – Analog In – Data mode, non-inverted; source for DSR.
03	ST/TT (pin 6) – TTL Input – ST/TT select pin; enables ST drivers and disables TT drivers when high. Disables ST drivers and enables TT drivers when low.	15	DM(a) (pin 68) – Analog In – Data mode, inverted; source for DSR.
04	DEC <sub>3</sub> /RDEC <sub>3</sub> (pin 5) – TTL Input – Transmitter/Receiver decode register.	16	CS(b) (pin 67) – Analog In – Clear to send; non-inverted; source for CTS.
05	TDEC <sub>2</sub> /RDEC <sub>2</sub> (pin 4) – TTL Input – Transmitter/Receiver decode register.	17	CS(a) (pin 66) – Analog In – Clear to send, inverted; source for CTS.
06	TDEC <sub>1</sub> /RDEC <sub>1</sub> (pin 3) – TTL Input – Transmitter/Receiver decode register.	18	TT(b) (pin 65) – Analog Out – Terminal timing, non-inverted; sourced from TxC input.
07	TDEC <sub>0</sub> /RDEC <sub>0</sub> (pin 2) – TTL Input – Transmitter/Receiver decode register.	19	TT(a) (pin 63) – Analog Out – Terminal timing; inverted; sourced from TxC input.
08	RxD (pin 1) – TTL Output – Receive data; sourced from RD(a) and RD(b) inputs.	20	TR(a) (pin 58) – Analog Out – Terminal ready, inverted; sourced from DTR.
09	CTS (pin 80) – TTL Output – Clear to send; sourced from CS(a) and CS(b) inputs.	21	TR(b) (pin 56) – Analog Out – Terminal ready; non-inverted; sourced from DTR.
10	RxT (pin 79) – TTL Output – RxT; sourced from TT(a), TT(b) inputs.	22	SD(a) (pin 61) – Analog Out – Send data, inverted; sourced from TxD.
11	DSR (pin 78) – TTL Output – Data set ready; sourced from DM(a) and DM(b) inputs.	23	SD(b) (pin 59) – Analog Out – Send data; non-inverted; sourced from TxD.
12	RD(b) (pin 71) – Analog In – Receive data, non-inverted; source for RxD.	24	RS(a) (pin 54) – Analog Out – Ready to send; inverted; sourced from RTS.
		25	RS(b) (pin 52) – Analog Out – Ready to send, non-inverted; sourced from RTS.



EDGE CONNECTOR	DUT PIN DESCRIPTIONS	EDGE CONNECTOR	DUT PIN DESCRIPTIONS
26	ST (pin 22) – TTL Input – Send Timing; source for ST(a) and ST(b) outputs. SP503 only.	39	IC(a) (pin 39) – Analog In – Incoming call; inverted; source for RI.
27	STEN (pin 23) – TTL Input — Driver enable control pin; active low. SP503 only,	40	RT(b) (pin 38) – Analog In – Receive timing, non–inverted; source for RxC.
28	SCT(a) (pin 76) – Analog Input – Inverting; input for SCT receiver; SP503 only.	41	RT(a) (pin 37) – Analog In – Receive timing; inverted; source from RxC.
29	SCT(b) (pin 77) – Analog Input – Non-inverting; input for SCT receiver. SP503 only.	42	RR(b) (pin 36) – Analog In – Receiver ready; non–inverted; source for DCD.
30	V <sub>CC</sub> — +5V for all circuitry.	43	RR(a) (pin 35) – Analog In – Receiver ready; inverted; source for DCD.
31	GND — signal and power ground.	44	LL (pin 24) – TTL Input – Local loopback; source for LL(a) and LL(b) outputs.
32	LL(a) (pin 51) – Analog Out – Local loopback, inverted; sourced from LL.	45	RI (pin 21) – TTL Output – Ring indicator; sourced from IC(a) and IC(b) inputs.
33	LL(b) (pin 49) – Analog Out – Local loopback, non–inverted sourced from LL.	46	RxC (pin 20) – TTL Output – Receive clock; sourced from RT(a) and RT(b) inputs.
34	RL(a) (pin 47) – Analog Out – Remote loopback; inverted; sourced from RL.	47	DCD (pin 19) – TTL Output – Data carrier detect; sourced from RR(a) and RR(b) inputs.
35	RL(b) (pin 45) – Analog Out – Remote loopback; non–inverted; sourced from RL.	48	RL (pin 17) – Analog Out – Remote loopback; source for RL(a) and RL(b) outputs.
36	ST(b) (pin 44) – Analog Out – Send timing, non–inverted; sourced from TxC.	49	RTS (pin 16) – TTL Input – Ready to send; source for RS(a) and RS(b) outputs.
37	ST(a) (pin 42) – Analog Output – Send timing, inverted; sourced from TxC.	50	TxC (pin 15) – TTL Input – Transmit clock; source for TT(A) and TT(B) outputs.
38	IC(b) (pin 40) – Analog In – Incoming call; non–inverted; source for RI.		

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**ORDERING INFORMATION**

Model	Temperature Range	Package Types
SP503CF .....	0°C to +70°C .....	80-pin QFP

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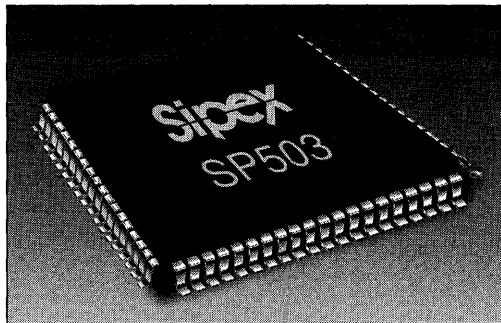




## SP503 Application Note



- DTE and DCE configurations with the SP503
- Connecting the SP503 to a DB-25 connector in DTE and DCE modes
- Implementing V.35 with the SP503
- Creating extra single-ended and differential channels with the SP503 using the SP310A and SP485
- Using external supplies with the SP503

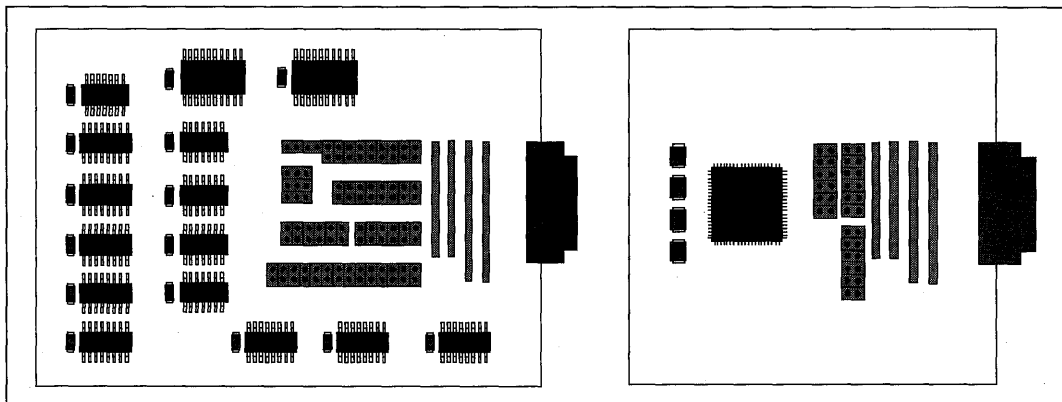


Due to its flexibility and programmability, the **SP503** has been finding its way into many new networking products. The **SP503** offers an excellent replacement for discrete solutions on X.25 implementations for frame relay systems, multi-protocol routers and other WAN products where many designs run various modes such as RS-232, RS-422, V.35 or V.36.

For RS-232, the older bipolar 1488 and 1489 parts, or even the newer MAX230 or SP230 series have traditionally been used. For RS-422 or RS-485, the 26LS31, 26LS32, 3488, and 3489 have been seen in many designs. These parts have been also

used for V.35 but with external termination resistors. For a typical design, four RS-232 chips would be used for a complete RS-232 port, four RS-422 chips for an RS-422 port and four chips for V.35 with an external resistor network. Port programmability would require relays or switches so that software lines can control whether RS-232 is active or RS-422 is active. The relays increase board capacity as well as cost to the design.

The **SP503** solves board space and cost problems by offering a single packaged part that supports various protocols and also offers software programmability to the port.



*Typical discrete solution vs. the SP503*

## DTE and DCE configurations with the SP503

The SP503 has designated signals such as "Transmit Data", "Clear-to-Send", etc. which designers can easily allocate the appropriate SP503 transceivers for the corresponding signals. The data signals specified in the EIA standards and CCITT are referenced in the SP503 datasheet as DTE. Some customers have wondered if they can use the SP503 for DCE applications. Although it can be confusing at first glance, the

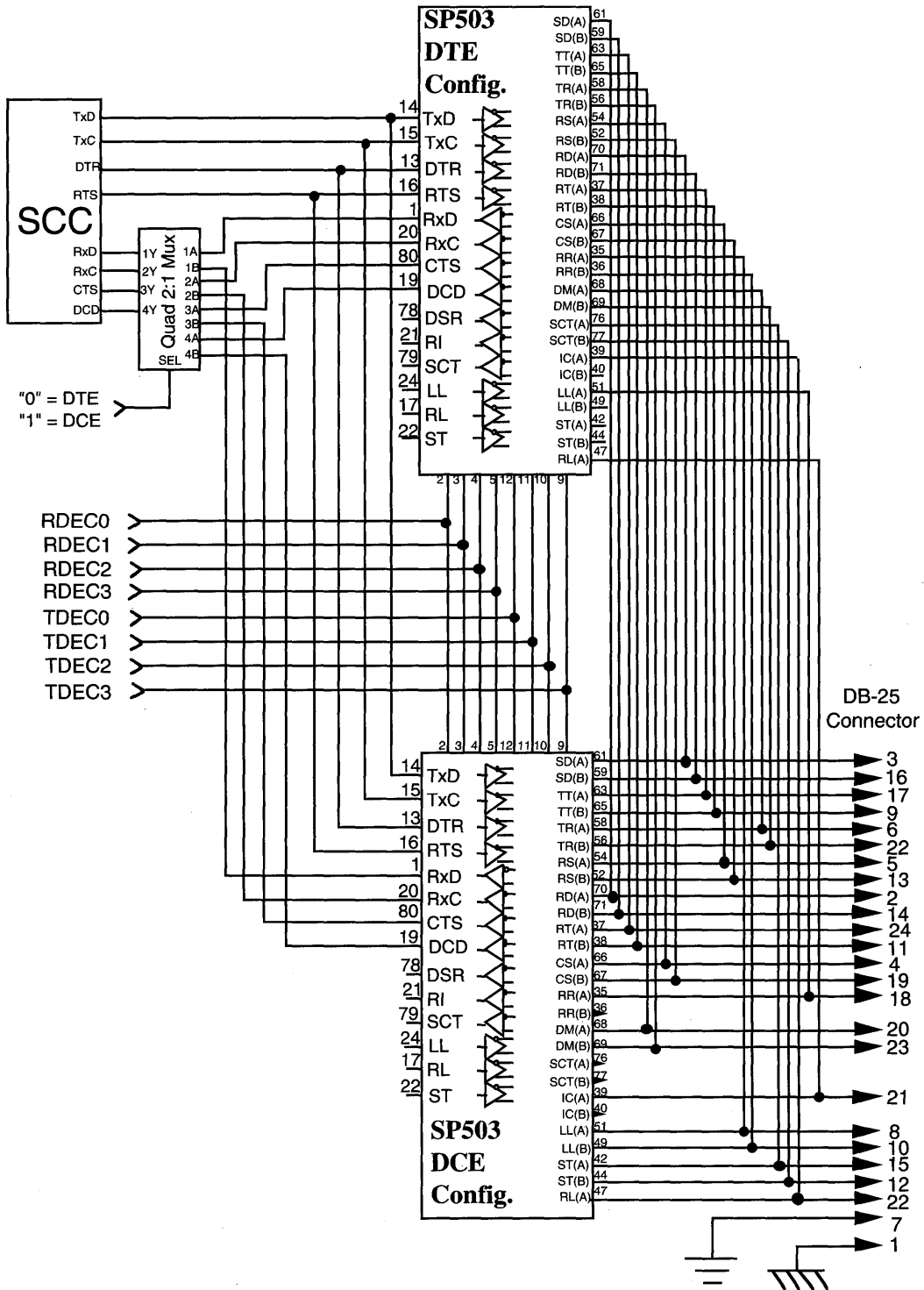
DCE implementation is the mirror image of the DTE side. For the DTE, TxD is a driver which drives the data to RxD, a receiver, on the DCE side. TxC or TT is a driver on the DTE side which drives the clock signal to the RxC receiver on the DCE side.

The next three pages illustrate the CCITT signal allocations from the SP503 in either DTE or DCE to the DB-25 connector. As shown, it is possible to use a DB-25 connector for the various protocols offered by the SP503.

### DB-25 Connector Pin Assignments for Various Protocols

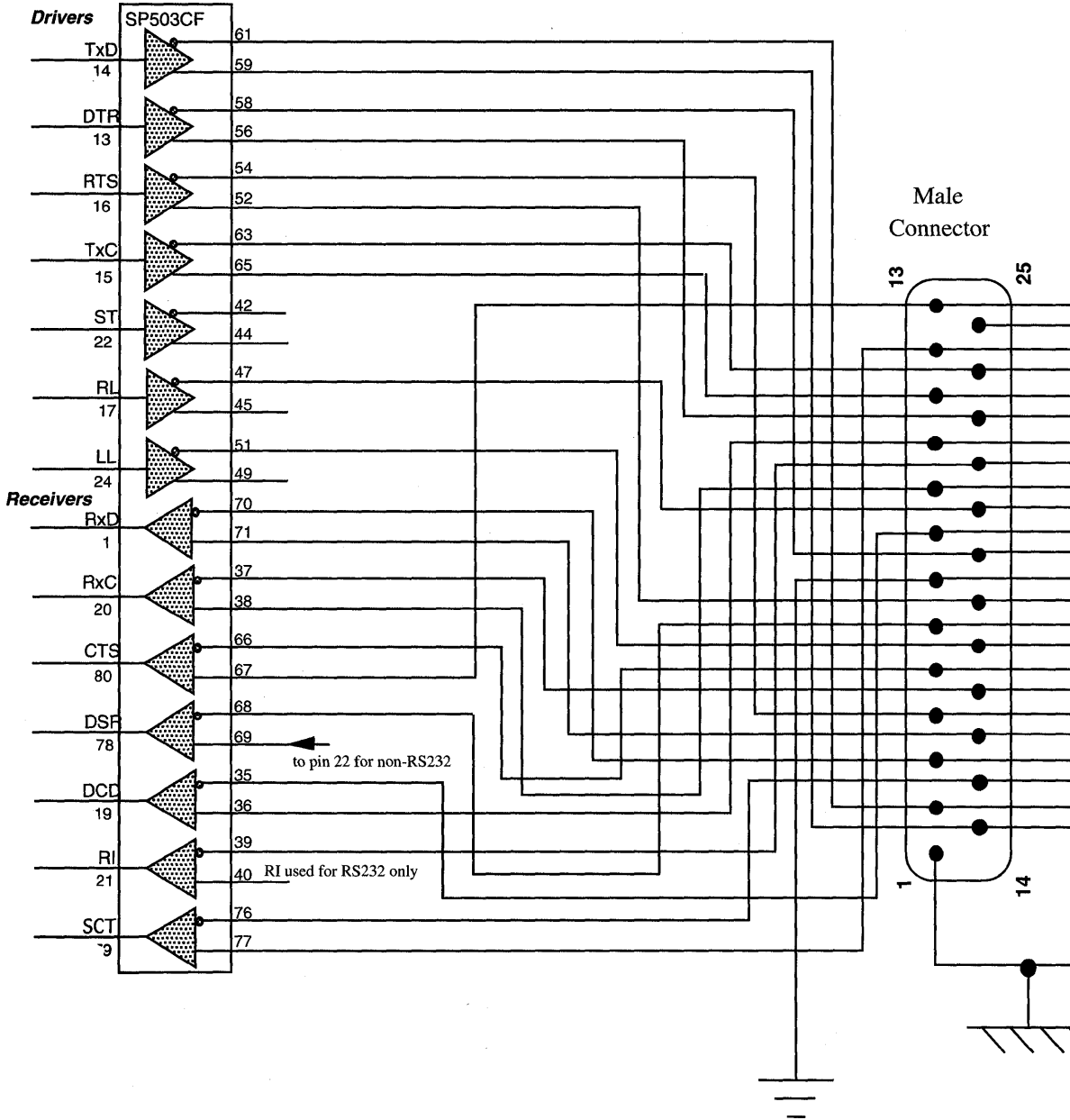
DB-25 Pin #	RS-232	EIA-530	RS-449	RS-422	V.35	V.36
1	shield	shield	shield	shield	CCITT# 101	CCITT# 101
2	TxD	TxD(A)	SD(A)	T(A)	103(A)	103(A)
3	RxD	RxD(A)	RD(A)	R(A)	104(A)	104(A)
4	RTS	RTS(A)	RS(A)	C(A)	105	105(A)
5	CTS	CTS(A)	CS(A)	-	106	106(A)
6	DSR	DSR(A)	DM(A)	-	107	107(A)
7	Signal GND	Signal GND	Signal GND	Signal GND	102	102
8	DCD	RLSD(A)	RR(A)	I(A)	109	109(A)
9	-	RxC(B)	RT(B)	-	115(B)	115(B)
10	-	RLSD(B)	RR(B)	I(B)	-	109(B)
11	-	TxC(B-DTE)	TT(B)	-	113(B)	113(B)
12	DCD (2nd)	TxCC(B-DCE)	ST(B)	S(B)	114(B)	114(B)
13	CTS (2nd)	CTS(B)	CS(B)	-	-	106(B)
14	TxD (2nd)	TxD(B)	SD(B)	T(B)	103(B)	103(B)
15	TxCC (DCE)	TxCC(A-DCE)	ST(A)	S(A)	114(B)	114(B)
16	RxD (2nd)	RxD(B)	RD(B)	R(B)	104(B)	104(B)
17	RxC	RxC(A)	RT(A)	-	115(A)	115(A)
18	LL	LL	LL	-	-	141
19	RTS (2nd)	RTS(B)	RS(B)	C(B)	-	105(B)
20	DTR	DTR(A)	TR(A)	-	-	-
21	RL	RL	RL	-	-	140
22	RI	DSR(B)	DM(B)	-	-	107(B)
23	SRS	DTR(B)	TR(B)	-	-	-
24	TxC (DTE)	TxC(A-DTE)	TT(A)	-	113(A)	113(A)

# DTE-DCE flexibility with the SP503 on a DB-25 serial port



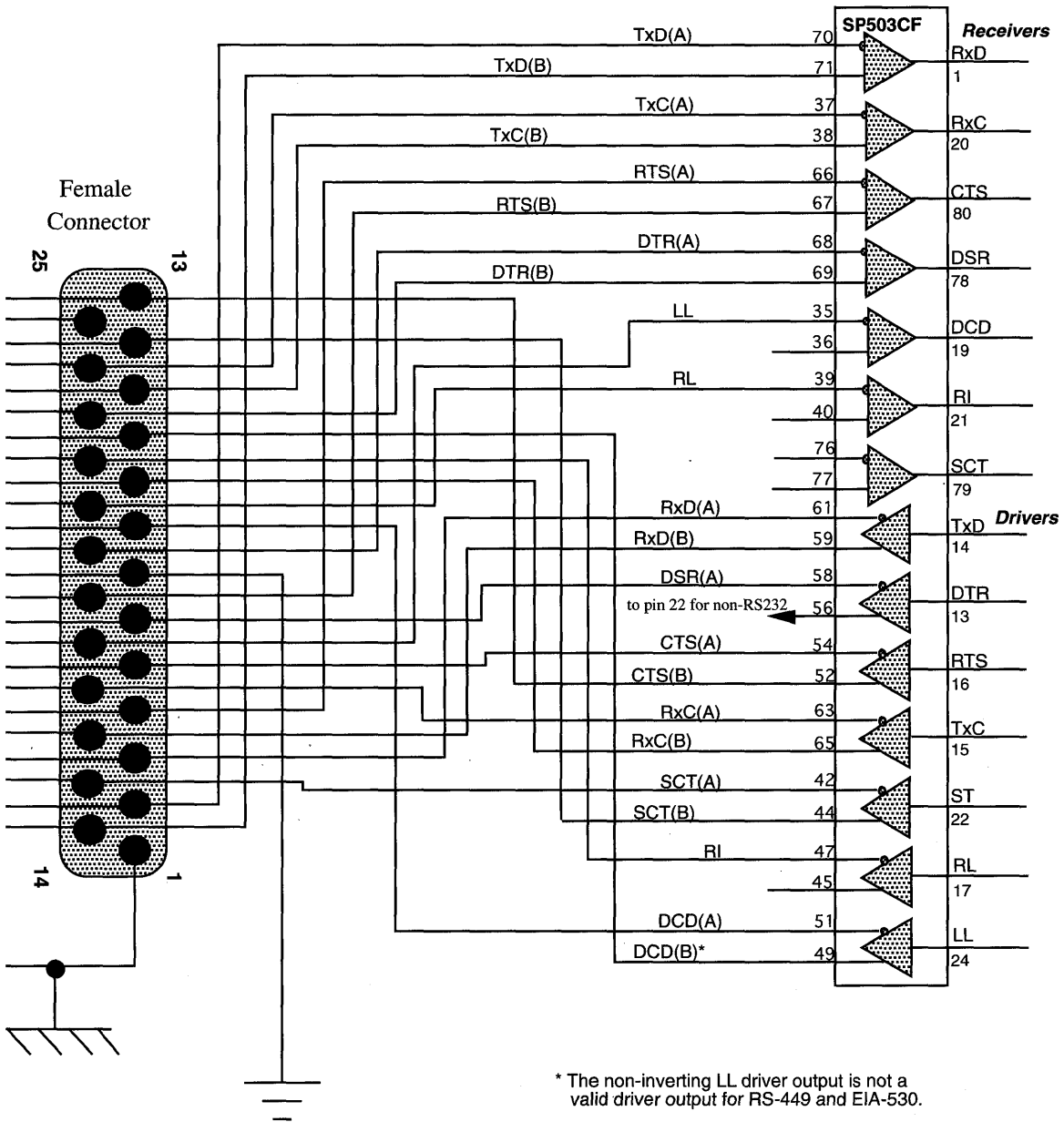
# Driver / Receiver Connections to a DB-25 Connector

## DTE Mode



# Driver / Receiver Connections to a DB-25 Connector

## DCE Mode



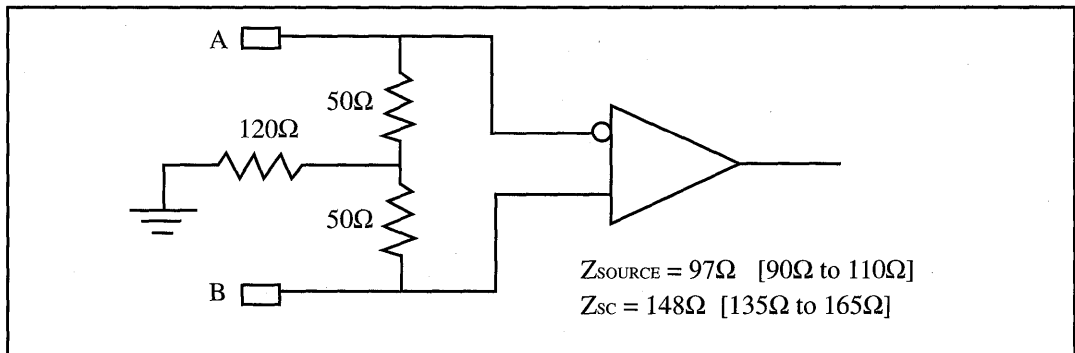
## SP503 V.35 External Termination Resistors

V.35 implementation requires external resistors to be connected to the driver outputs and receiver inputs. The resistors are needed for reducing signal levels and maintaining input and output impedance levels that conform to CCITT Recommendation V.35. The drawings below offer both receiver input termination and driver output termination configurations that will comply to V.35.

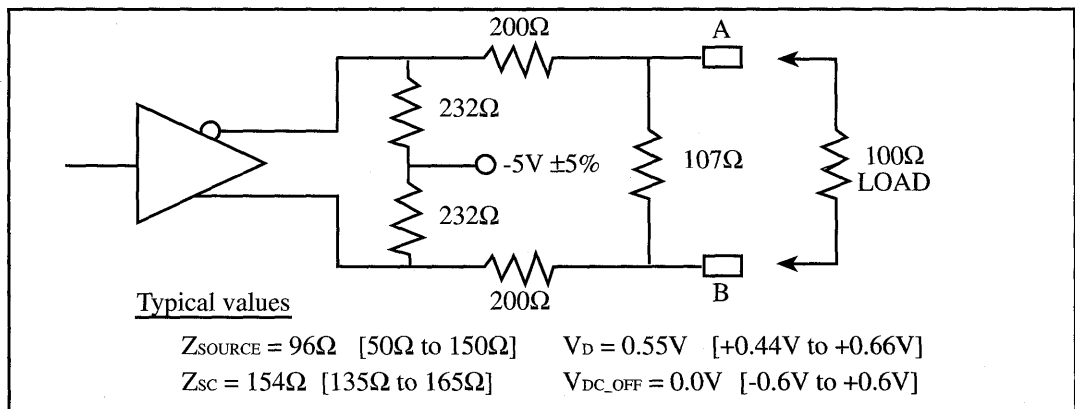
As you may know, the termination resistors are for V.35 mode only and have to be disconnected when another mode is programmed. There are a few ways to connect and disconnect the network. One method is to add a daughter-card option slot onto the main printed circuit board where the **SP503** is mounted. This allows the user to add a mini-PC card that contains the V.35

network to be connected to the driver outputs and receiver inputs. Another method is to implant the V.35 network into a cable if the user requires conversion cables to switch from one protocol to another. For example, if the serial port has a DB-25 connector and requires an ISO-2593 connector for V.35; a DB-25 to ISO-2593 conversion cable containing the V.35 network is connected to the port.

Of course this method will not allow programmability to the serial port if the user wants to run various protocols to that port. To actively switch protocols by software control, you can use analog switches or relays. Sipex recommends using low-ON resistance analog switches, such as Siliconix DG643<sup>®</sup> analog switches for the driver outputs, and solid-state relays such as the AT&T LH1514<sup>®</sup> for the receiver inputs. See opposite page for an example of the SP503 V.35 configuration.



**V.35 Receiver Input Termination Resistor Network**

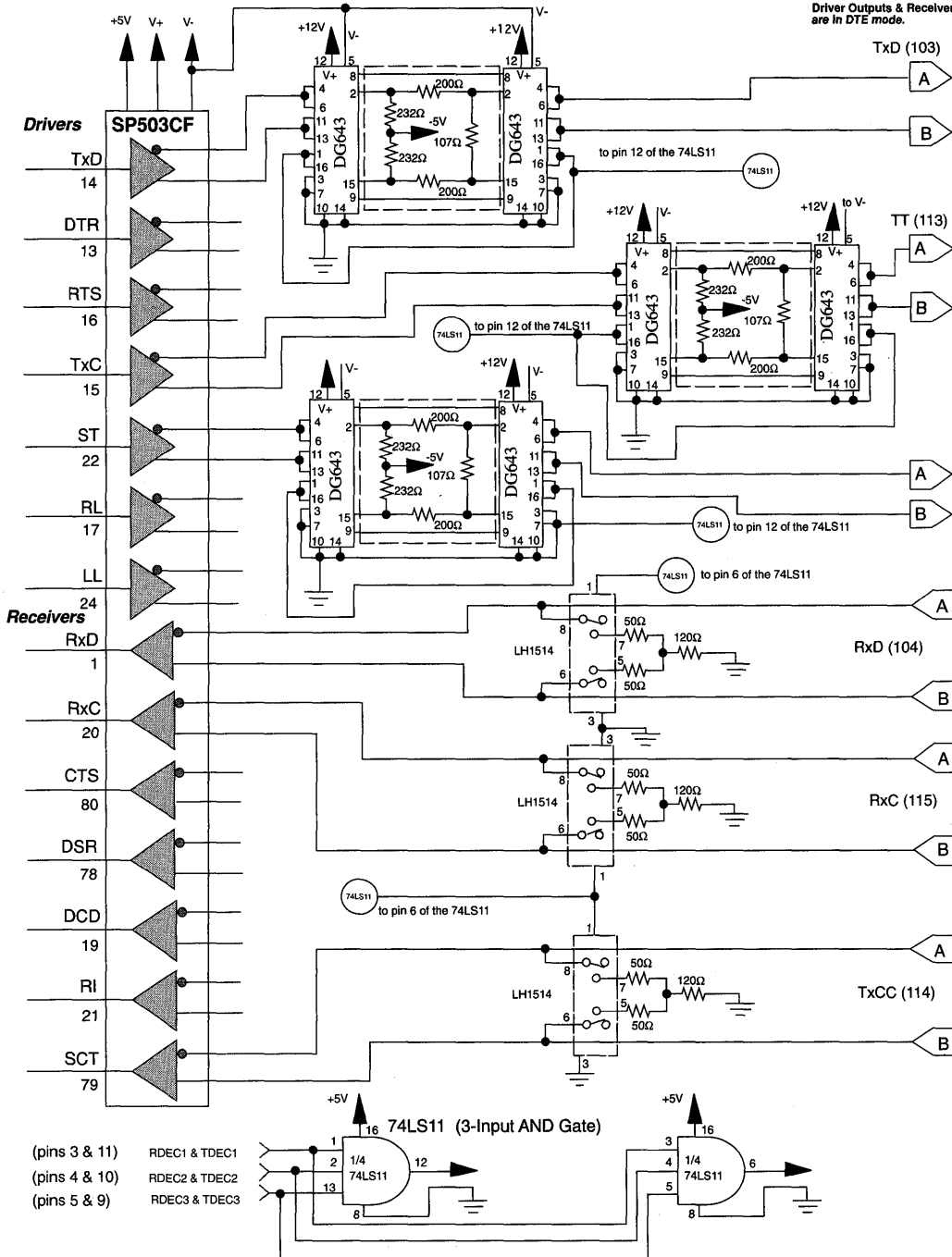


**V.35 Driver Output Termination Resistor Network**

# SP503 Switching Configuration for V.35 Implementations

- Switches are **Siliconix DG643DY** analog switches.
- Solid-State Relays are **AT&T, LH1514**.
- Resistors are 1/8W, 1% tolerance.
- External Supplies necessary are:  $V_{cc} = +5V$ ,  $V_+ = +12V$  (for  $V_+$  on the DG643DY) and  $V_n = -5V$ .

Driver Outputs & Receiver Inputs are in DTE mode.



## Typical Applications Questions on the SP503

Can the SP503 be used with external power supplies? If so, is there a power up sequence?

The internal charge pump can be bypassed through external supplies to  $V_{DD}$  and  $V_{SS}$ . The external voltage should be +10V for  $V_{DD}$  and -10V for  $V_{SS}$ . The tolerance is  $\pm 5\%$ . The SP503 can be powered up in any order without latch-up problems. The absolute minimum limit for the external supplies is  $\pm 7V$  and the absolute maximum limit is  $\pm 10.5V$ .

What is the maximum input voltage applied to the receiver input without damaging the SP503?

The receiver inputs can tolerate up to  $\pm 16V$  in any protocol without latching up the device. Since RS-232 ranges from  $\pm 5V$  to  $\pm 15V$ ; the SP503 is well within the accepted range. It may be worthwhile to include 15V clamping diodes or transient voltage suppressors so that the receiver input will be held below  $\pm 15V$ .

What is the maximum short-circuit voltage that can be applied to a SP503 driver output?

The driver outputs can be shorted up to  $\pm 16.0V$  without causing damage to the driver. Between the  $\pm 16V$  range, the SP503 adheres to the RS-232 short circuit current limit of 100mA and to the RS-422/RS-423 limit at 150mA. Again, transient voltage suppressors or clamping diodes will protect the SP503 if exceeding the  $\pm 16V$  range is possible.

What is the state of the SP503 drivers and receivers when the device is addressed with 0000?

The SP503 drivers are in a high impedance (over  $1M\Omega$ ) tri-state condition when "0000" is addressed. The receivers are not tri-stated and the outputs are undefined. This means that they could be floating to either a high or low level depending on the previous state of the receiver input prior to the 0000 addressing change. The receiver input impedance is at  $15k\Omega$  for "0000".

Can the SP503 be programmed for 7 drivers and 7 receivers in RS-423 mode?

The SP503 can be switched to RS-423 mode by programming TDEC<sub>3</sub>, TDEC<sub>2</sub>, TDEC<sub>1</sub>, TDEC<sub>0</sub> to "1000" for the drivers and RDEC<sub>x</sub> to "1000" for the receivers. However, external supplies must be used in order to drive RS-423. The internal charge pump can only support up to three RS-423 drivers and three RS-423 receivers.

What is the power dissipation in the SP503 and in which mode does it consume the most power?

The SP503 dissipates approximately 400mW to 1.4W depending on the protocol. RS-485 mode consumes the most power at 1.4W. For worst case power dissipation, all seven drivers were driven with a TTL signal and the outputs were looped back into the receiver inputs to generate a TTL output. All drivers and receivers were active.

MODE	$P_D$
RS-232	0.418W
RS-422	0.970W
RS-485	1.382W
RS-449	0.959W
EIA-530	0.959W
V.35	1.055W

What is the state of the SP503 drivers and receivers when the device is addressed with 1111?

The address for "1111" is not used in the SP503. If the SP503 is programmed for "1111", the drivers are approximately 1.0V and at a high impedance (approx.  $9M\Omega$ ). The receivers are not tri-stated and the outputs are undefined. All receiver inputs are at  $15k\Omega$  input impedance. The SP503 can receive a "1111" address while  $V_{CC}$  is off. The supply current is approximately 50mA ( $V_{CC} = +5V$ ) while the address is at "1111".



In the RS-232 signal assignments for the DB-25 connector, where does the SP503 account for Test Mode(TM) ?

For most RS-232 applications, the signals commonly used are TxD, TxC, RxD, RxC, RTS, CTS, DSR, SG, DCD, DTR and Frame Ground. In DTE mode; TxD, TxC, RTS, DTR are the drivers and RxD, RxC, CTS, DSR, DCD are the receivers. Since there are seven drivers and seven receivers in the SP503, the designer can easily use the SP503 for the above signals. Other RS-232 applications will support diagnostic functions such as LL (driver), RL (driver), and TM (receiver) which may or may not require extra transceivers depending if other signals are not used. Since Test Mode (TM) is a receiver for DTE designs, the Ring Indicator (RI) receiver in the SP503 (pin 21) can be used for TM if RI is not used. If all the available drivers and receivers are used in the SP503, then another RS-232 transceiver can be added. See page 120 and 121 for suggestions on adding Sipex's RS-232 and RS-485 transceivers.

Are the Schottky diodes used on Vcc to Vss and Vdd to C2- in the SP502 necessary for the SP503?

Sipex has incorporated the Schottky diodes needed in the SP502 into the SP503 in order to protect against potential start up problems due to fast rate of rise on  $V_{cc}$  (1V/ $\mu$ s) and overvoltage to the TTL inputs. However, a negative voltage ( $V_{in}$  -5V) applied to the receiver inputs while the SP503 is powered off will cause start up problems to the charge pump. In order to guard against this condition, an external Schottky diode should be placed from Vcc to Vdd to minimize  $V_{cc}$  current injection to the IC substrate and allow the charge pump to operate properly. See page 93 Figure 6 - Typical Operating Circuit, for diode connection schematic.

Can the SP503 be configured for V.36?

CCITT Recommendation V.36 is similar to RS-449 where certain signals are RS-422 signals and others are RS-423. Depending on different applications; "Transmit Data", "Terminal Timing",

"Request-to-Send", "Data Terminal Ready", "Receive Data", "Transmit Clock", "Receive Clock", "Clear-to-Send", "Data Carrier Detect", and "DataSet Ready" are specified as Category 1 Circuits where the protocol is RS-422 for rates over 20kbps. All other circuits are Category 2 Circuits which are specified as RS-423 circuits. Depending on particular signals, the SP503 can be easily used for V.36.

When the two drivers, ST and TT, are in tri-state mode, what will the driver outputs tolerate for maximum short circuit voltages? And the receiver, SCT, input?

The driver outputs will tolerate up to  $\pm 16.0V$  without any damage to the circuit regardless of whether or not ST and TT are in tri-state mode. The tri-state circuitry does not affect the short circuit protection on the driver outputs. The SCT receiver input will tolerate up to  $\pm 16.0V$  without any damage to the input structure regardless of whether or not SCT is in tri-state mode.

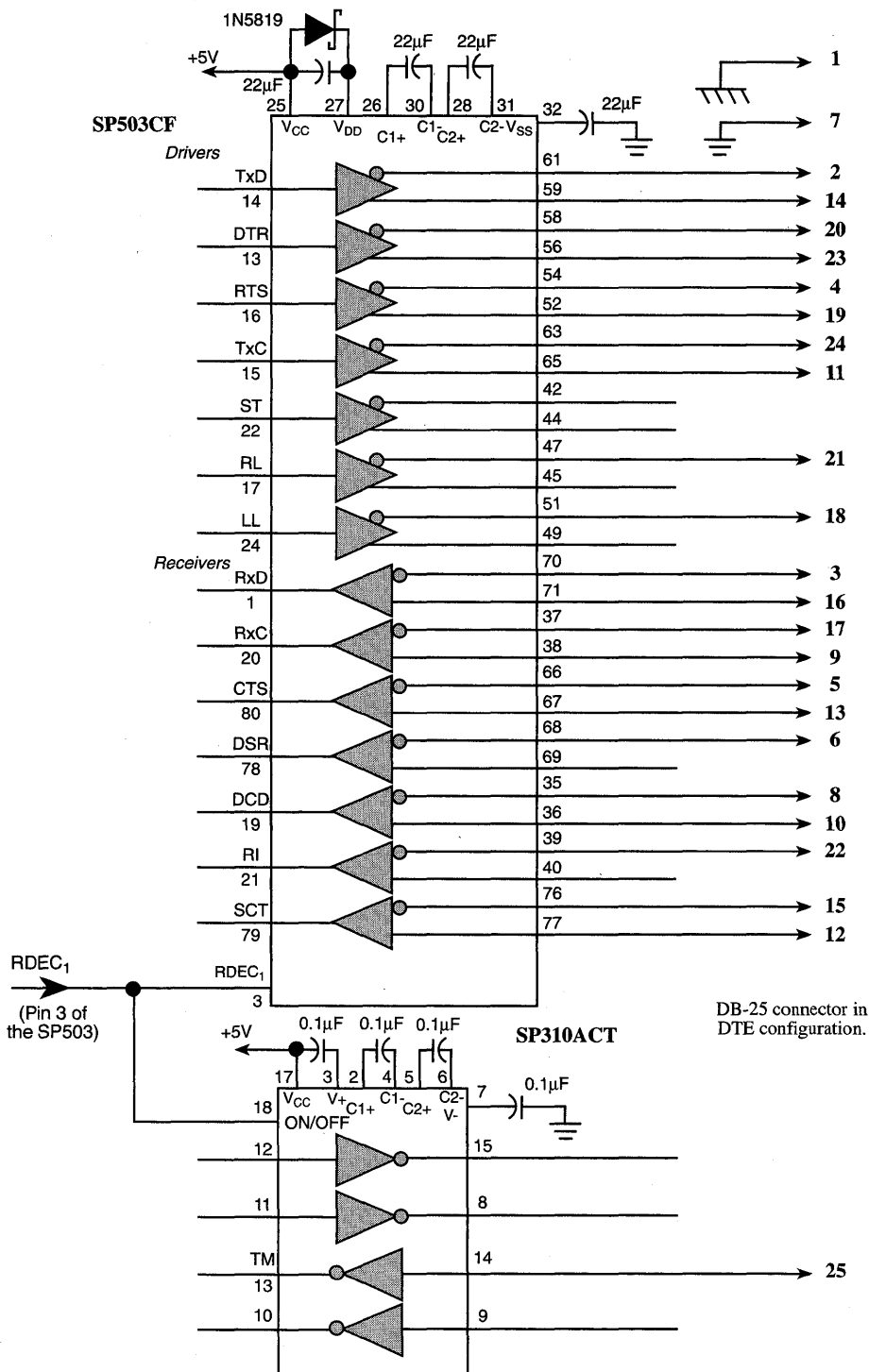
What does Sipex recommend for transient voltage suppression techniques for the SP503?

For our evaluation boards, Sipex uses transient voltage suppressor ICs from ProTek Devices, model numbers LCA05C to LCA15C. The two digits in the part number pertain to the rated stand-off voltage,  $V_{WM}$ , which is the maximum working DC voltage applied to the device. These TVS devices are especially designed for serial data communications because of their low capacitance and low impedance. Another recommended manufacturer is AVX Corporation TransGuard series of TVS components. AVX offers a variety of surface mount back-to-back diodes.

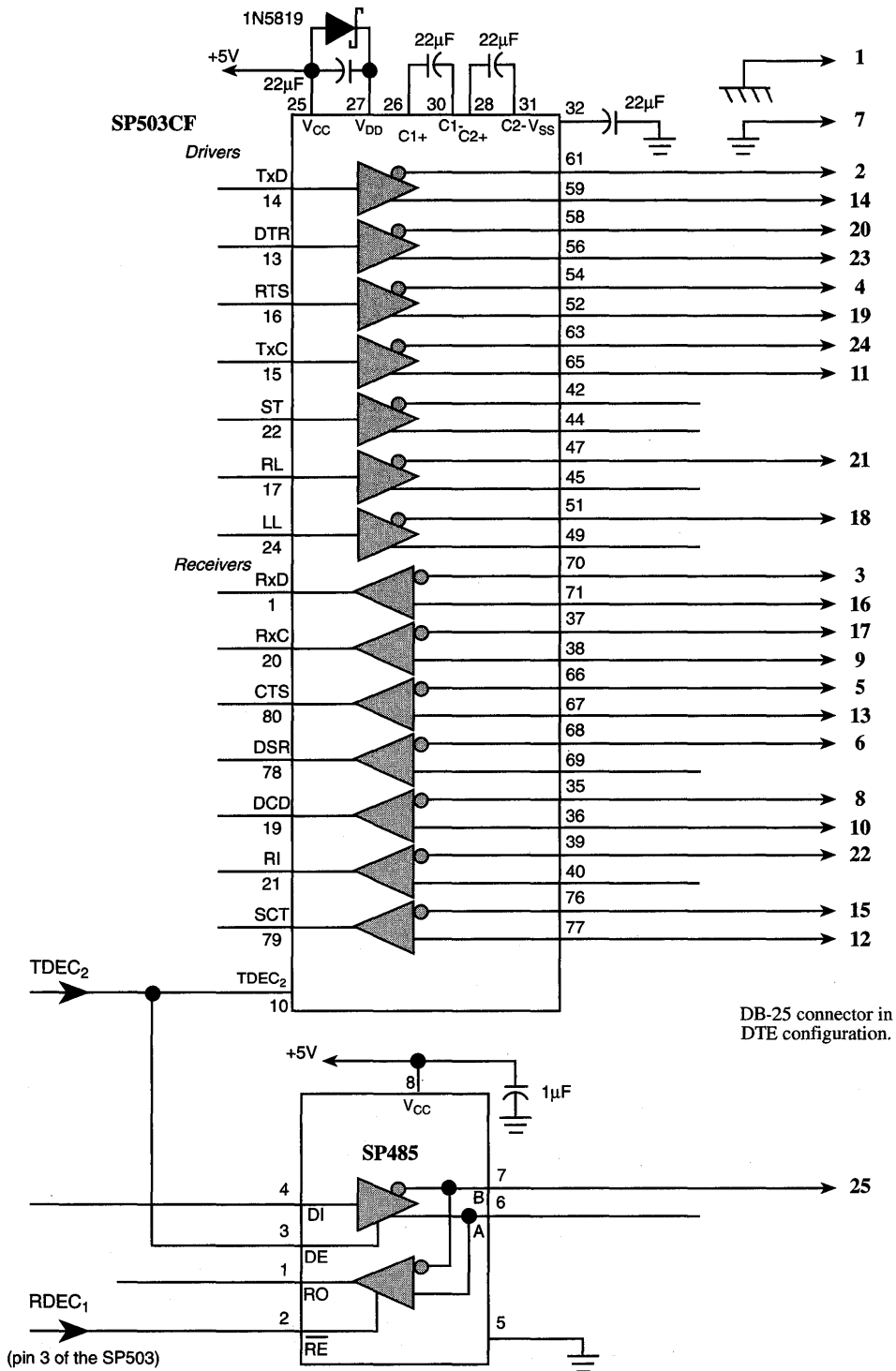
**ProTek Devices • P.O. Box 3129 • Tempe, AZ.  
85280 • 602-431-8101  
AVX Corporation • Myrtle Beach, SC • 803-448-9411**

The drawing on page 122 shows the SP503 configured with the ProTek LCA12C TVS devices to protect the drivers and receivers from ESD and over-voltage.

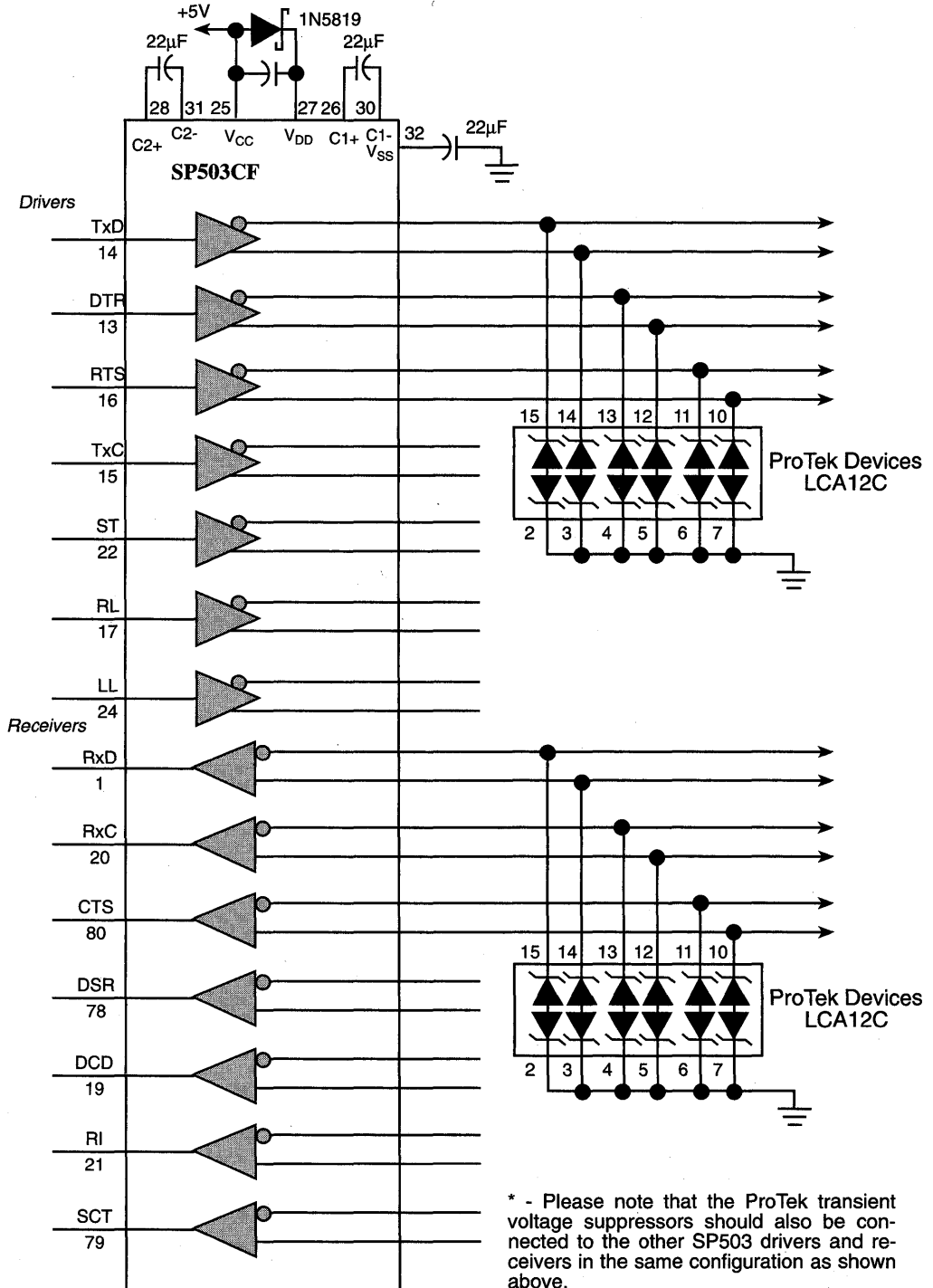
# Creating extra RS-232 channels using the SP310A



# Creating extra differential channels using the SP485



# Using Transient Voltage Suppressors with the SP503



\* - Please note that the ProTek transient voltage suppressors should also be connected to the other SP503 drivers and receivers in the same configuration as shown above.

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**ORDERING INFORMATION**

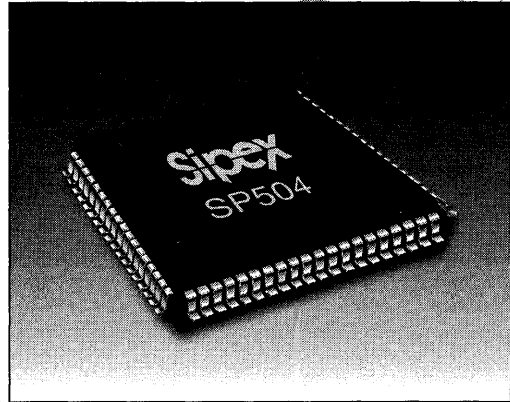
Model	Temperature Range	Package Types
SP503CF .....	0°C to +70°C .....	80-pin QFP

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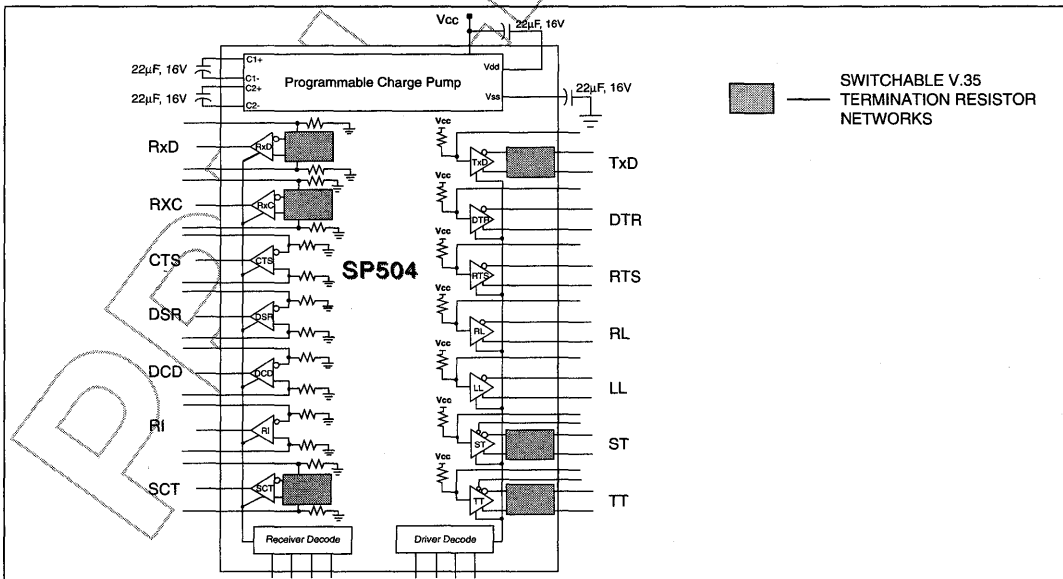
**WAN Multi-Mode Serial Transceiver**

- +5V Only
- Seven (7) Drivers and Seven (7) Receivers
- Driver and Receiver Tri-State Control
- Reduced V.35 Termination Network
- Pin Compatible with the SP503
- Software Selectable Interface Modes:
  - RS-232E (V.28)
  - RS-422A (V.11, X.27)
  - RS-449
  - RS-485
  - V.35
  - EIA-530
  - EIA-530A
  - V.36



**DESCRIPTION...**

The **SP504** is a single chip device that supports eight (8) of the most popular serial interface standards for Wide Area Network Connectivity. The **SP504** is fabricated using a low power BiCMOS process technology, and incorporates a Sipex patented (5,306,954) charge pump allowing +5V only operation. Seven (7) drivers and seven (7) receivers can be configured via software for any of the above interface modes at any time. The **SP504** requires only one external resistor per V.35 driver for compliant V.35 operation.



# SPECIFICATIONS

Typical @ 25°C and nominal supply voltages unless otherwise noted.

	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>LOGIC INPUTS</b>					
$V_{IL}$			0.8	Volts	
$V_{IH}$	2.0			Volts	
<b>LOGIC OUTPUTS</b>					
$V_{OL}$			0.4	Volts	$I_{OUT} = -3.2mA$
$V_{OH}$	2.4			Volts	$I_{OUT} = 1.0mA$
<b>RS-485 DRIVER</b>					
TTL Input Levels					
$V_{IL}$			0.8	Volts	
$V_{IH}$	2.0			Volts	
Outputs					
High Level Output			+6.0	Volts	
Low level Output	-0.3			Volts	
Differential Output	$\pm 1.5$		$\pm 5.0$	Volts	$R_L = 54\Omega, C_L = 50pF$
Balance		$\pm 0.2$		Volts	$ V_I -  V_T $
Offset		+2.5		Volts	
Open Circuit Voltage			$\pm 6.0$	Volts	
Output Current	28.0			mA	$R_L = 54\Omega$
Short Circuit Current		$\pm 250$		mA	Terminated in -7V to +12V
Transition Time			120	ns	Rise/fall time, 10%-90%
Transmission Rate			10	Mbps	$R_L = 54\Omega$
Propagation Delay					
$t_{PHL}$		100		ns	Figures 3a and 5; $R_{DIFF} = 54\Omega$
$t_{PLH}$		100		ns	$C_{RL} = 50pF$
<b>RS-485 RECEIVER</b>					
TTL Output Levels					
$V_{OL}$			0.4	Volts	
$V_{OH}$	2.4			Volts	
Input					
High Threshold	+0.2		+12	Volts	(a)-(b)
Low Threshold	-7.0		-0.2	Volts	(a)-(b)
Common Mode Range	-7.0		+12.0	Volts	
High Input Current					Refer to Rec. input graph
Low Input Current					Refer to Rec. input graph
Receiver Sensitivity			$\pm 0.2$	Volts	Over -7V to +12V common mode range
Input Impedance	12			K $\Omega$	
Transmission Rate			10	Mbps	
Propagation Delay					
$t_{PHL}$		100		ns	Figures 3a and 7; A is invert-
$t_{PLH}$		100		ns	ing and B is non-inverting.
<b>V.35 DRIVER</b>					
TTL Input Levels					
$V_{IL}$			0.8	Volts	
$V_{IH}$	2.0			Volts	
Outputs					
Differential Output	$\pm 0.44$		$\pm 0.66$	Volts	$R_L = 100\Omega$
Source Impedance	50	100	150	$\Omega$	$V_{OUT} = +2V$ to $-2V$ ; w/ 150 $\Omega$
Short-Circuit Impedance	135	150	165	$\Omega$	termination to GND.
Voltage Output Offset	-0.6		+0.6		
Transition Time		40		ns	
Transmission Rate			5	Mbps	$R_L = 100\Omega$
Propagation Delay					Figures 3b and 5
$t_{PHL}$		200		ns	
$t_{PLH}$		200		ns	



# SPECIFICATIONS (Continued)

Typical @ 25°C and nominal supply voltages unless otherwise noted.

	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>V.35 RECEIVER</b>					
TTL Output Levels					
$V_{OL}$			0.4	Volts	
$V_{OH}$	2.4			Volts	
Input					
Differential Threshold	-0.2		+0.2	Volts	
Input Impedance	90	100	110	$\Omega$	
Short-Circuit Impedance	135	150	165	$\Omega$	$V_{IN} = +2V \text{ to } -2V$
Transmission Rate			5	Mbps	
Propagation Delay					
$t_{PHL}$		200		ns	Figure 3b and 7; A is invert-
$t_{PLH}$		200		ns	ing and B is non-inverting.
<b>RS-422 DRIVER</b>					
TTL Input Levels					
$V_{IL}$			0.8	Volts	
$V_{IH}$	2.0			Volts	
Outputs					
Differential Output	$\pm 2.0$		$\pm 5.0$	Volts	$R_L = 100\Omega$
Open Circuit Voltage, $V_O$			$\pm 6.0$	Volts	
Balance			$\pm 0.4$	Volts	$ V_T  -  \bar{V}_T $
Offset			+3.0	Volts	
Short Circuit Current			$\pm 150$	mA	$V_{out} = 0V$
Power Off Current			$\pm 100$	$\mu A$	$V_{cc} = 0V, V_{out} = \pm 0.25V$
Transition Time			60	ns	Rise/fall time, 10%-90%
Transmission Rate			10	Mbps	$R_L = 100\Omega$
Propagation Delay					
$t_{PHL}$		100		ns	Figure 3a and 5;
$t_{PLH}$		100		ns	$R_{DIFF} = 100\Omega$
<b>RS-422 RECEIVER</b>					
TTL Output Levels					
$V_{OL}$			0.4	Volts	
$V_{OH}$	2.4			Volts	
Input					
High Threshold	+0.2		+6.0	Volts	(a)-(b)
Low Threshold	-6.0		-0.2	Volts	(a)-(b)
Common Mode Range	-7.0		+7.0	Volts	
High Input Current					Refer to Rec. input graph
Low Input Current					Refer to Rec. input graph
Receiver Sensitivity			$\pm 0.2$	Volts	
Input Impedance	4			K $\Omega$	
Transmission Rate			10	Mbps	
Propagation Delay					
$t_{PHL}$		100		ns	Figure 3a and 7; A is invert-
$t_{PLH}$		100		ns	ing and B is non-inverting.
<b>RS-232 DRIVER</b>					
TTL Input Level					
$V_{IL}$			0.8	Volts	
$V_{IH}$	2.0			Volts	
Outputs					
High Level Output	+5.0		+15	Volts	$R_L = 3K\Omega, V_{IN} = 0.8V$
Low Level Output	-15.0		-5.0	Volts	$R_L = 3K\Omega, V_{IN} = 2.0V$
Open Circuit Voltage	-15		+15	Volts	
Short Circuit Current			$\pm 100$	mA	$V_{OUT} = 0V$
Power Off Impedance	300			$\Omega$	$V_{cc} = 0V, V_{out} = \pm 2.0V$
Slew Rate			30	V/ $\mu s$	$R_L = 3K\Omega, C_i = 50pF$
Transition Time			1.56	$\mu s$	$R_L = 3K\Omega, C_i = 2500pF$ between $\pm 3V$

# SPECIFICATIONS (Continued)

Typical @ 25°C and nominal supply voltages unless otherwise noted.

	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>RS-232 DRIVER</b>					
Transmission Rate			120	Kbps	$R_L=3K\Omega$ , $C_L=2500pF$
Propagation Delay					Measured from 1.5V of $V_{IN}$ to 50% of $V_{OUT}$ ; $R_L=3K\Omega$
$t_{PHL}$		2	8	$\mu S$	
$t_{PLH}$		2	8	$\mu S$	
<b>RS-232 RECEIVER</b>					
TTL Output Levels					
$V_{OL}$	2.4		0.4	Volts	
$V_{OH}$				Volts	
Input					
High Threshold		1.7	3.0	Volts	
Low Threshold	0.8	1.2		Volts	
Receiver Open Circuit Bias	0		+2.0	Volts	
Input Impedance	3	5	7	K $\Omega$	
Transmission Rate			120	Kbps	
Propagation Delay					Measured from 50% of $V_{IN}$ to 1.5V of $V_{OUT}$
$t_{PHL}$			1	$\mu S$	
$t_{PLH}$			1	$\mu S$	
<b>RS-423 DRIVER</b>					
TTL Input Levels					
$V_{IL}$			0.8	Volts	
$V_{IH}$	2.0			Volts	
Output					
High Level Output	+3.6		+6.0	Volts	$R_L=450\Omega$
Low Level Output	-6.0		-3.6	Volts	$R_L=450\Omega$
Open Circuit Voltage	$\pm 4.0$		$\pm 6.0$	Volts	
Short Circuit Current			$\pm 150$	mA	$V_{OUT} = 0V$
Power Off Current			$\pm 100$	$\mu A$	$V_{CC} = 0V$ , $V_{OUT} = \pm 0.25V$
Transition Time			2.4	$\mu s$	Rise/fall time, between $\pm 3V$
Transmission Rate			120	Kbps	$R_L=450\Omega$
Propagation Delay					Measured from 1.5V of $V_{IN}$ to 50% of $V_{OUT}$ ; $R_L=450\Omega$
$t_{PHL}$		2	8	$\mu S$	
$t_{PLH}$		2	8	$\mu S$	
<b>RS-423 RECEIVER</b>					
TTL Output Levels					
$V_{OL}$	2.4		0.4	Volts	
$V_{OH}$				Volts	
Input					
High Threshold	+0.2		+7.0	Volts	
Low Threshold	-7.0		-0.2	Volts	
Common Mode Range	-7.0		+7.0	Volts	
High Input Current					Refer to Rec. input graph
Low Input Current					Refer to Rec. input graph
Receiver Sensitivity			$\pm 0.2$	Volts	$V_{CM} = +7V$ to $-7V$
Input Impedance	4			K $\Omega$	$V_{IN} = +10V$ to $-10V$
Transmission Rate			120	Kbps	
Propagation Delay					Measured from 50% of $V_{IN}$ to 1.5V of $V_{OUT}$
$t_{PHL}$			1	$\mu S$	
$t_{PLH}$			1	$\mu S$	
<b>POWER REQUIREMENTS</b>					
$V_{CC}$	4.75	5.00	5.25	Volts	$V_{CC} = 5V$ ; no interface selected
$I_{CC}$		30		mA	
<b>ENVIRONMENTAL AND MECHANICAL</b>					
Operating Temperature Range	0		+70	$^{\circ}C$	
Storage Temperature Range	-65		+150	$^{\circ}C$	
Package	80-pin QFP				

## OTHER AC CHARACTERISTICS

(Typical @ 25°C and nominal supply voltages unless otherwise noted)

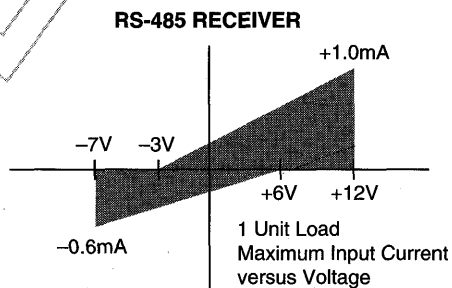
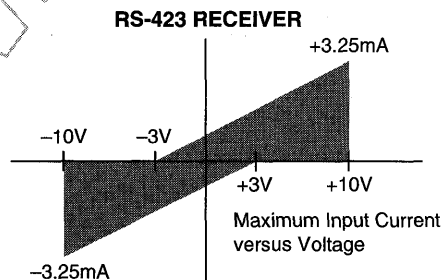
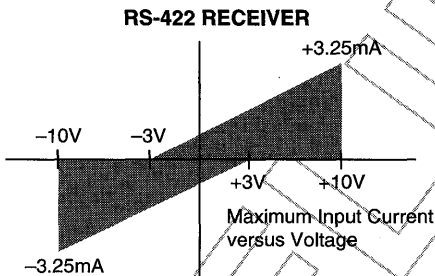
PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>DRIVER DELAY TIME BETWEEN ACTIVE MODE AND TRI-STATE MODE</b>					
<b>RS-232 MODE</b>					
$t_{pZL}$ : Tri-state to Output low		800		ns	$C_L = 100\text{pF}$ , Fig. 4; $S_2$ closed
$t_{pZH}$ : Tri-state to Output high		400		ns	$C_L = 100\text{pF}$ , Fig. 4; $S_2$ closed
$t_{pLZ}$ : Output low to Tri-state		200		ns	$C_L = 100\text{pF}$ , Fig. 4; $S_2$ closed
$t_{pHZ}$ : Output high to Tri-state		400		ns	$C_L = 100\text{pF}$ , Fig. 4; $S_2$ closed
<b>RS-423 MODE</b>					
$t_{pZL}$ : Tri-state to Output low		200		ns	$C_L = 100\text{pF}$ , Fig. 4; $S_2$ closed
$t_{pZH}$ : Tri-state to Output high		200		ns	$C_L = 100\text{pF}$ , Fig. 4; $S_2$ closed
$t_{pLZ}$ : Output low to Tri-state		200		ns	$C_L = 100\text{pF}$ , Fig. 4; $S_2$ closed
$t_{pHZ}$ : Output high to Tri-state		200		ns	$C_L = 100\text{pF}$ , Fig. 4; $S_2$ closed
<b>RS-422, RS-485 MODES</b>					
$t_{pZL}$ : Tri-state to Output low		3000		ns	$C_L = 100\text{pF}$ , Fig. 4 & 6; $S_1$ closed
$t_{pZH}$ : Tri-state to Output high		150		ns	$C_L = 100\text{pF}$ , Fig. 4 & 6; $S_2$ closed
$t_{pLZ}$ : Output low to Tri-state		150		ns	$C_L = 15\text{pF}$ , Fig. 4 & 6; $S_1$ closed
$t_{pHZ}$ : Output high to Tri-state		200		ns	$C_L = 15\text{pF}$ , Fig. 4 & 6; $S_2$ closed
<b>V.35 MODE</b>					
$t_{pZL}$ : Tri-state to Output low		3000		ns	$C_L = 100\text{pF}$ , Fig. 4 & 6; $S_1$ closed
$t_{pZH}$ : Tri-state to Output high		150		ns	$C_L = 100\text{pF}$ , Fig. 4 & 6; $S_2$ closed
$t_{pLZ}$ : Output low to Tri-state		150		ns	$C_L = 15\text{pF}$ , Fig. 4 & 6; $S_1$ closed
$t_{pHZ}$ : Output high to Tri-state		150		ns	$C_L = 15\text{pF}$ , Fig. 4 & 6; $S_2$ closed
<b>RECEIVER DELAY TIME BETWEEN ACTIVE MODE AND TRI-STATE MODE</b>					
<b>RS-232 MODE</b>					
$t_{pZL}$ : Tri-state to Output low		100		ns	$C_L = 100\text{pF}$ , Fig. 2; $S_1$ closed
$t_{pZH}$ : Tri-state to Output high		100		ns	$C_L = 100\text{pF}$ , Fig. 2; $S_2$ closed
$t_{pLZ}$ : Output low to Tri-state		100		ns	$C_L = 100\text{pF}$ , Fig. 2; $S_1$ closed
$t_{pHZ}$ : Output high to Tri-state		100		ns	$C_L = 100\text{pF}$ , Fig. 2; $S_2$ closed
<b>RS-423 MODE</b>					
$t_{pZL}$ : Tri-state to Output low		100		ns	$C_L = 100\text{pF}$ , Fig. 2; $S_1$ closed
$t_{pZH}$ : Tri-state to Output high		100		ns	$C_L = 100\text{pF}$ , Fig. 2; $S_2$ closed
$t_{pLZ}$ : Output low to Tri-state		100		ns	$C_L = 100\text{pF}$ , Fig. 2; $S_1$ closed

## OTHER AC CHARACTERISTICS (Continued)

(Typical @ 25°C and nominal supply voltages unless otherwise noted)

PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITIONS
<b>RECEIVER DELAY TIME BETWEEN ACTIVE MODE AND TRI-STATE MODE</b>					
$t_{PHZi}$ ; Output high to Tri-state		100		ns	$C_L = 100\text{pF}$ , Fig. 2; $S_2$ closed
<b>RS-422/RS-485 MODES</b>					
$t_{PZL}$ ; Tri-state to Output low		100		ns	$C_L = 100\text{pF}$ , Fig. 2 & 8; $S_1$ closed
$t_{PZH}$ ; Tri-state to Output high		100		ns	$C_L = 100\text{pF}$ , Fig. 2 & 8; $S_2$ closed
$t_{PLZ}$ ; Output low to Tri-state		100		ns	$C_L = 15\text{pF}$ , Fig. 2 & 8; $S_1$ closed
$t_{PHZ}$ ; Output high to Tri-state		100		ns	$C_L = 15\text{pF}$ , Fig. 2 & 8; $S_2$ closed
<b>V.35 MODE</b>					
$t_{PZL}$ ; Tri-state to Output low		100		ns	$C_L = 100\text{pF}$ , Fig. 2 & 8; $S_1$ closed
$t_{PZH}$ ; Tri-state to Output high		100		ns	$C_L = 100\text{pF}$ , Fig. 2 & 8; $S_2$ closed
$t_{PLZ}$ ; Output low to Tri-state		100		ns	$C_L = 15\text{pF}$ , Fig. 2 & 8; $S_1$ closed
$t_{PHZ}$ ; Output high to Tri-state		100		ns	$C_L = 15\text{pF}$ , Fig. 2 & 8; $S_2$ closed

## RECEIVER INPUT GRAPHS



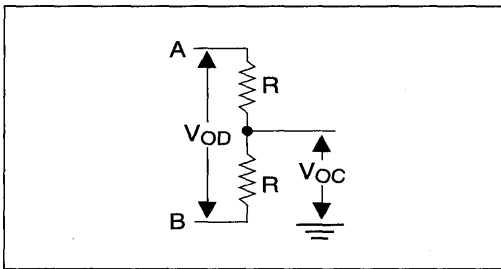


Figure 1. Driver DC Test Load Circuit

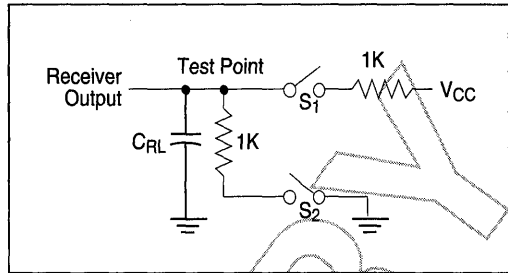


Figure 2. Receiver Timing Test Load Circuit

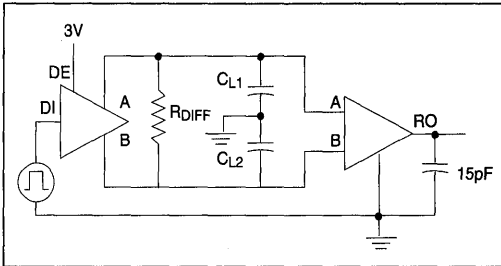


Figure 3a. Driver/Receiver Timing Test Circuit

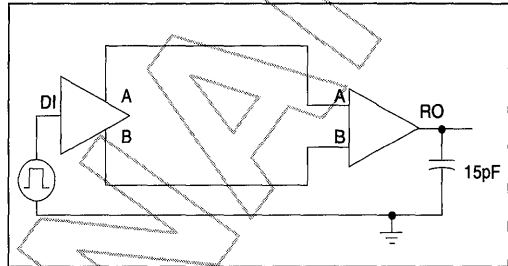


Figure 3b. Timing Test Ckt. (V.35 mode only for SP504)

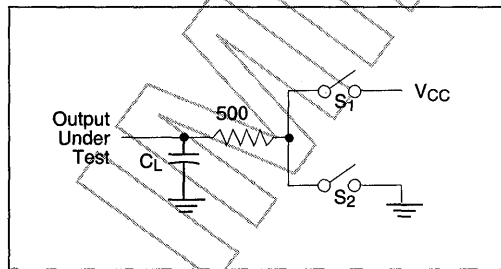


Figure 4. Driver Timing Test Load #2 Circuit

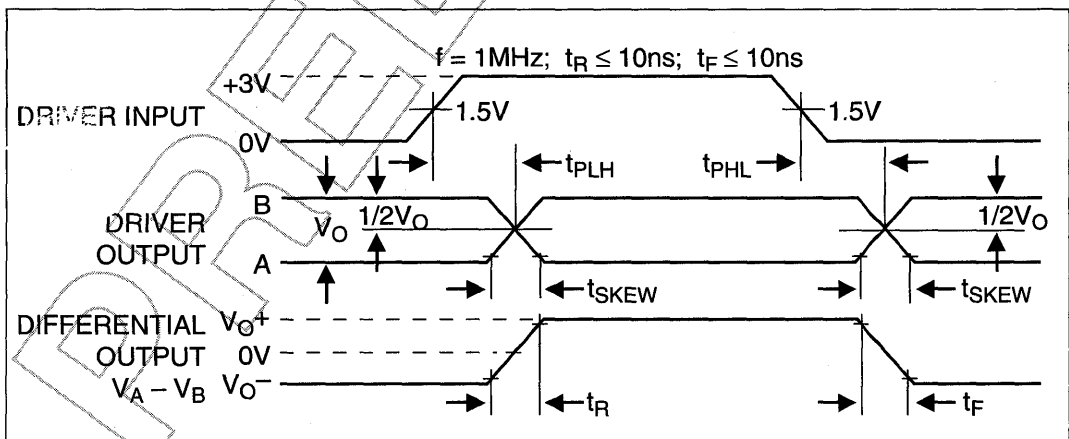


Figure 5. Driver Propagation Delays

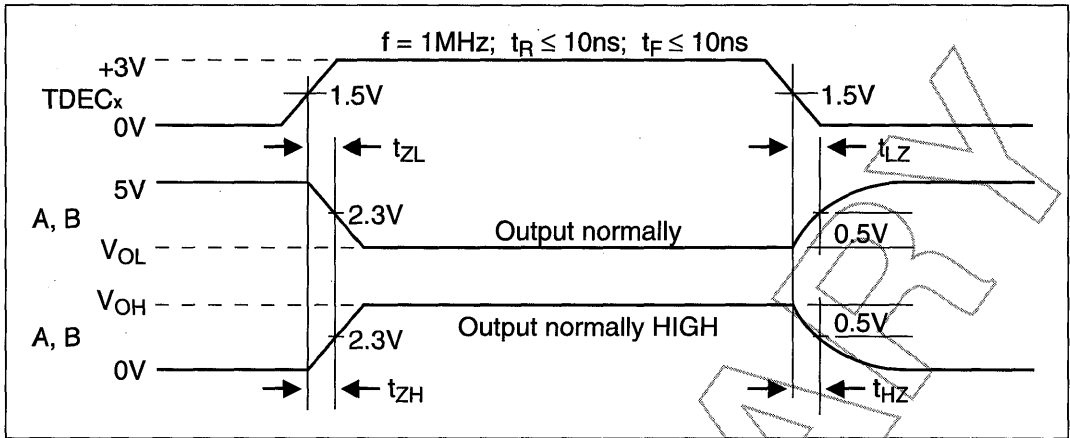


Figure 6. Driver Enable and Disable Times

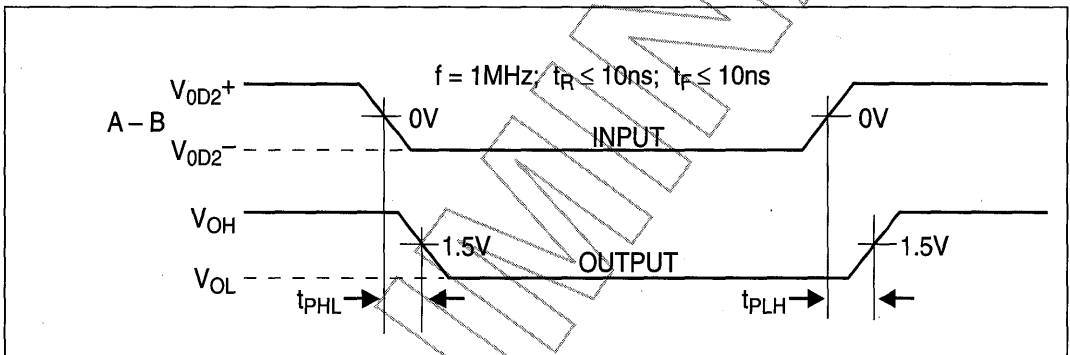


Figure 7. Receiver Propagation Delays

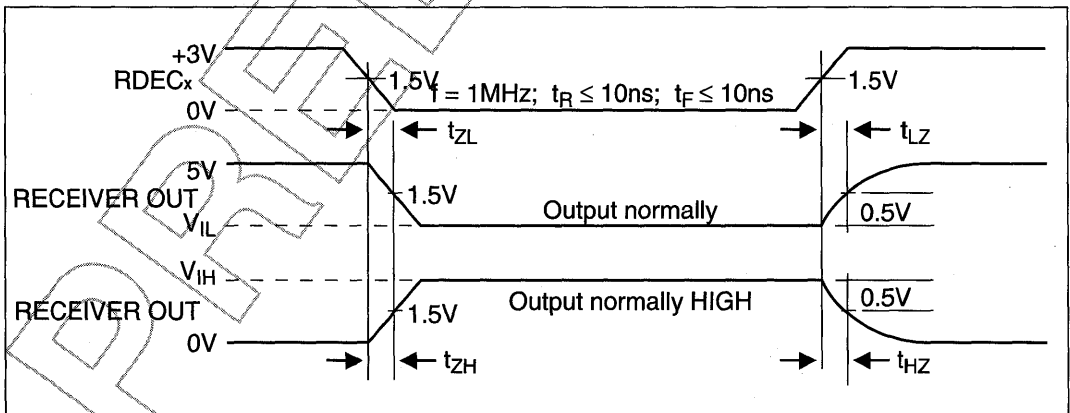


Figure 8. Receiver Enable and Disable Times

## ABSOLUTE MAXIMUM RATINGS

These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

$V_{CC}$ .....	+7V
Input Voltages:	
Logic.....	-0.3V to ( $V_{CC}+0.5V$ )
Drivers.....	-0.3V to ( $V_{CC}+0.5V$ )
Receivers.....	$\pm 15V$
Output Voltages:	
Logic.....	-0.3V to ( $V_{CC}+0.5V$ )
Drivers.....	$\pm 14V$
Receivers.....	-0.3V to ( $V_{CC}+0.5V$ )
Storage Temperature.....	-65°C to +150°C
Power Dissipation.....	2000mW
Package Derating:	
$\theta_{JA}$ .....	46°C/W
$\theta_{JC}$ .....	16°C/W

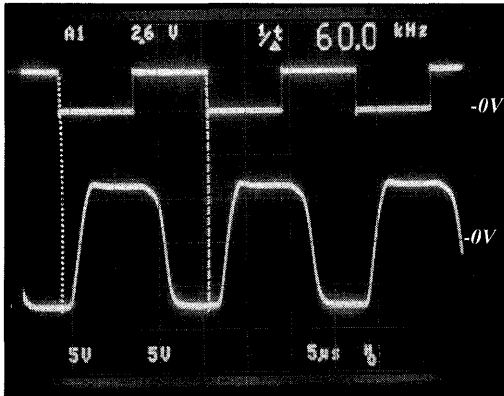


Figure 9. Typical RS-232 Driver Output Waveform

## STORAGE CONSIDERATIONS

Due to the relatively large package size of the 80-pin quad flat-pack, storage in a low humidity environment is preferred. Large high density plastic packages are moisture sensitive and should be stored in Vapor Barrier Bags. Prior to usage, the parts should remain bagged and stored below 40°C and 60%RH. If the parts are removed from the bag, they should be used within 48 hours or stored in an environment at or below 20%RH. If the above conditions cannot be followed, the parts should be baked for four hours at 125°C in order to remove moisture prior to soldering. Sipex ships the 80-pin QFP in Vapor Barrier Bags with a humidity indicator card and desiccant pack. The humidity indicator should be below 30%RH.

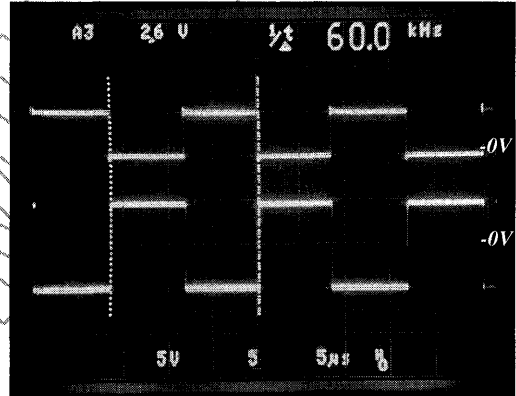


Figure 10. Typical RS-423 Driver Output Waveform

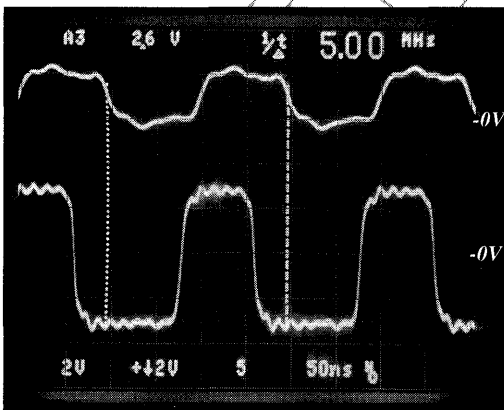


Figure 11. Typical RS-422/485 Driver Output Waveform

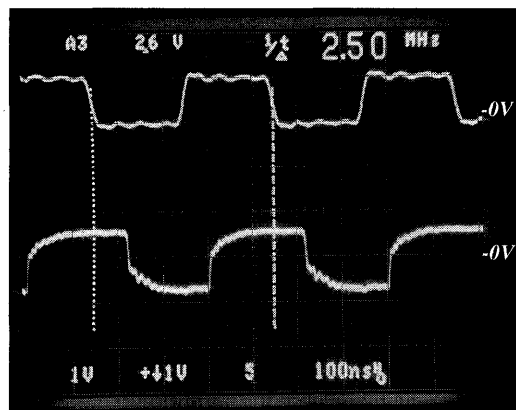
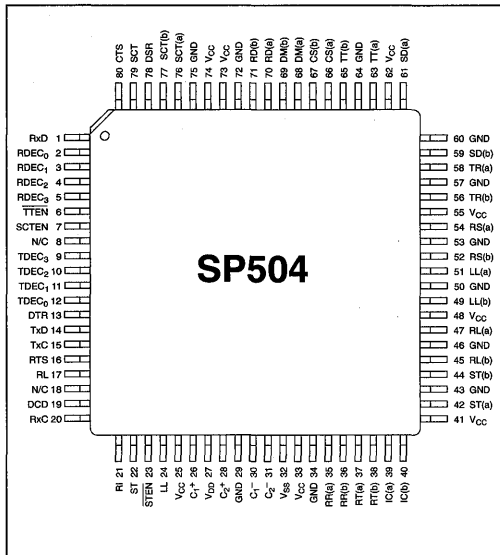


Figure 12. Typical V.35 Driver Output Waveform

## PINOUT...



### PIN ASSIGNMENTS...

#### CLOCK AND DATA GROUP

Pin 1 — RxD — Receive Data; TTL output, sourced from RD(a) and RD(b) inputs.

Pin 14 — TxD — TTL input ; transmit data source for SD(a) and SD(b) outputs.

Pin 15 — TxC — Transmit Clock; TTL input for TT driver outputs.

Pin 20 — RxC — Receive Clock; TTL output sourced from RT(a) and RT(b) inputs.

Pin 22 — ST — Send Timing; TTL input; source for ST(a) and ST(b) outputs.

Pin 37 — RT(a) — Receive Timing; analog input, inverted; source for RxC.

Pin 38 — RT(b) — Receive Timing; analog input, non-inverted; source for RxC.

Pin 42 — ST(a) — Send Timing; analog output, inverted; sourced from ST.

Pin 44 — ST(b) — Send Timing; analog output, non-inverted; sourced from ST.

Pin 59 — SD(b) — Analog Out — Send data, non-inverted; sourced from TxD.

Pin 61 — SD(a) — Analog Out — Send data, inverted; sourced from TxD.

Pin 63 — TT(a) — Analog Out — Terminal Timing, inverted; sourced from TxC

Pin 65 — TT(b) — Analog Out — Terminal Timing, non-inverted; sourced from TxC.

Pin 70 — RD(a) — Receive Data, analog input; inverted; source for RxD.

Pin 71 — RD(b) — Receive Data; analog input; non-inverted; source for RxD.

Pin 76 — SCT(a) — Serial Clock Transmit; analog input, inverted; source for SCT.

Pin 77 — SCT(b) — Serial Clock Transmit; analog input, non-inverted; source for SCT

Pin 79 — SCT — Serial Clock Transmit; TTL output; sources from SCT(a) and SCT(b) inputs.

#### CONTROL LINE GROUP

Pin 13 — DTR — Data Terminal Ready; TTL input; source for TR(a) and TR(b) outputs.

Pin 16 — RTS — Ready To Send; TTL input; source for RS(a) and RS(b) outputs.

Pin 17 — RL — Remote Loopback; TTL input; source for RL(a) and RL(b) outputs.

Pin 19 — DCD — Data Carrier Detect; TTL output; sourced from RR(a) and RR(b) inputs.

Pin 21 — RI — Ring In; TTL output; sourced from IC(a) and IC(b) inputs.

Pin 24 — LL — Local Loopback; TTL input; source for LL(a) and LL(b) outputs.

Pin 35 — RR(a) — Receiver Ready; analog input, inverted; source for DCD.

Pin 36 — RR(b) — Receiver Ready; analog input, non-inverted; source for DCD.

Pin 39 — IC(a) — Incoming Call; analog input, inverted; source for RI.

Pin 40 — IC(b) — Incoming Call; analog input, non-inverted; source for RI.



Pin 45 — RL(b) — Remote Loopback; analog output, non-inverted; sourced from RL.

Pin 47 — RL(a) — Remote Loopback; analog output inverted; sourced from RL.

Pin 49 — LL(b) — Local Loopback; analog output, non-inverted; sourced from LL.

Pin 51 — LL(a) — Local Loopback; analog output, inverted; sourced from LL.

Pin 52 — RS(b) — Ready To Send; analog output, non-inverted; sourced from RTS.

Pin 54 — RS(a) — Ready To Send; analog output, inverted; sourced from RTS.

Pin 56 — TR(b) — Terminal Ready; analog output, non-inverted; sourced from DTR.

Pin 58 — TR(a) — Terminal Ready; analog output, inverted; sourced from DTR.

Pin 66 — CS(a) — Clear To Send; analog input, inverted; source for CTS.

Pin 67 — CS(b) — Clear To Send; analog input, non-inverted; source for CTS.

Pin 68 — DM(a) — Data Mode; analog input, inverted; source for DSR.

Pin 69 — DM(b) — Data Mode; analog input, non-inverted; source for DSR.

Pin 78 — DSR — Data Set Ready; TTL output; sourced from DM(a), DM(b) inputs.

Pin 80 — CTS — Clear To Send; TTL output; sourced from CS(a) and CS(b) inputs.

## CONTROL REGISTERS

Pins 2–5 — RDEC<sub>0</sub> – RDEC<sub>3</sub> — Receiver decode register; configures receiver modes; TTL inputs.

Pin 6 — TTEN — Enables TT driver, active low; TTL input.

Pin 7 — SCTEN — Enables SCT receiver; active high; TTL input.

Pins 12–9 — TDEC<sub>0</sub> – TDEC<sub>3</sub> — Transmitter decode register; configures transmitter modes; TTL inputs.

Pin 23 — STEN — Enables ST driver; active low; TTL input.

## POWER SUPPLIES

Pins 25, 33, 41, 48, 55, 62, 73, 74 — V<sub>CC</sub> — +5V input.

Pins 29, 34, 43, 46, 50, 53, 57, 60, 64, 72, 75 — GND — Ground.

Pin 27 — V<sub>DD</sub> +10V Charge Pump Capacitor — Connects from V<sub>DD</sub> to V<sub>CC</sub>. Suggested capacitor size is 22μF, 16V.

Pin 32 — V<sub>SS</sub> –10V Charge Pump Capacitor — Connects from ground to V<sub>SS</sub>. Suggested capacitor size is 22μF, 16V.

Pins 26 and 30 — C<sub>1</sub><sup>+</sup> and C<sub>1</sub><sup>-</sup> — Charge Pump Capacitor — Connects from C<sub>1</sub><sup>+</sup> to C<sub>1</sub><sup>-</sup>. Suggested capacitor size is 22μF, 16V.

Pins 28 and 31 — C<sub>2</sub><sup>+</sup> and C<sub>2</sub><sup>-</sup> — Charge Pump Capacitor — Connects from C<sub>2</sub><sup>+</sup> to C<sub>2</sub><sup>-</sup>. Suggested capacitor size is 22μF, 16V.

NOTE: NC pins should be left floating; internal signals may be present.

## FEATURES...

The **SP504** is a highly integrated serial transceiver that allows software control of its interface modes. Similar to the **SP503**, the **SP504** offers the same hardware interface modes for RS-232 (V.28), RS-422A (V.11), RS-449, RS-485, V.35, EIA-530 and includes V.36 and EIA-530A. The interface mode selection is done via an 8-bit switch; four (4) bits control the drivers and four (4) bits control the receivers. The **SP504** is fabricated using low-power BiCMOS process technology, and incorporates a Sipex-patented (5,306,954) charge pump allowing +5V only operation. Each device is packaged in an 80-pin Quad FlatPack package.

The **SP504** is ideally suited for wide area network connectivity based on the interface modes offered and the driver and receiver configurations. The **SP504** has seven (7) independent drivers and seven (7) independent receivers. In

V.35 mode, the SP504 includes the necessary components and termination resistors internal within the device for compliant V.35 operation.

## THEORY OF OPERATION

The SP504 is made up of five separate circuit blocks — the charge pump, drivers, receivers, decoder and switching array. Each of these circuit blocks is described in more detail below.

### Charge-Pump

The SP504's charge pump design is based on the SP503 where Sipex's-patented charge pump design (5,306,954) uses a four-phase voltage shifting technique to attain symmetrical 10V power supplies. In addition, the SP504 charge pump incorporates a "programmable" feature that produces an output of  $\pm 10V$  or  $\pm 5V$  for  $V_{SS}$  and  $V_{DD}$  depending on the mode of operation. The charge pump still requires external capacitors to store the charge. Figure 17a shows the waveform found on the positive side of capacitor C2, and Figure 17b shows the negative side of capacitor C2. There is a free-running oscillator that controls the four phases of the voltage shifting. A description of each phase follows.

The SP504 charge pump is used for RS-232 where the output voltage swing is typically  $\pm 10V$  and also used for RS-423. However, RS-423 requires the voltage swing on the driver output be between  $\pm 4V$  to  $\pm 6V$  during an open-circuit (no load). The charge pump would need to be regulated down from  $\pm 10V$  to  $\pm 5V$ . A typical  $\pm 10V$  charge pump would require external clamping such as 5V zener diodes on  $V_{DD}$  and  $V_{SS}$  to ground. The  $\pm 5V$  output has symmetrical levels as in the  $\pm 10V$  output. The  $\pm 5V$  is used in the following modes where RS-423 levels are used: RS-449, EIA-530, EIA-530A and V.36.

### Phase 1 ( $\pm 10V$ )

—  $V_{SS}$  charge storage — During this phase of the clock cycle, the positive side of capacitors  $C_1$  and  $C_2$  are initially charged to +5V.  $C_1^+$  is then switched to ground and the charge on  $C_1^-$  is transferred to  $C_2^-$ . Since  $C_2^+$  is connected to +5V, the voltage potential across capacitor  $C_2$  is now 10V.

### Phase 1 ( $\pm 5V$ )

—  $V_{SS}$  &  $V_{DD}$  charge storage and transfer — With the  $C_1$  and  $C_2$  capacitors initially charged to +5V,  $C_1^+$  is then switched to ground and charge on  $C_1^-$  is transferred to the  $V_{SS}$  storage capacitor. Simultaneously the  $C_2^-$  is switched to ground and 5V charge on  $C_2^+$  is transferred to the  $V_{DD}$  storage capacitor.

### Phase 2 ( $\pm 10V$ )

—  $V_{SS}$  transfer — Phase two of the clock connects the negative terminal of  $C_2$  to the  $V_{SS}$  storage capacitor and the positive terminal of  $C_2$  to ground, and transfers the generated -10V or the generated -5V to  $C_3$ . Simultaneously, the positive side of capacitor  $C_1$  is switched to +5V and the negative side is connected to ground.

### Phase 2 ( $\pm 5V$ )

—  $V_{SS}$  &  $V_{DD}$  charge storage —  $C_1^+$  is reconnected to  $V_{CC}$  to recharge the  $C_1$  capacitor.  $C_2^+$  is switched to ground and  $C_2^-$  is connected to  $C_3$ . The 5V charge from Phase 1 is now transferred to the  $V_{SS}$  storage capacitor.  $V_{SS}$  receives a continuous charge from either  $C_1$  or  $C_2$ . With the  $C_1$  capacitor charged to 5V, the cycle begins again.

### Phase 3

—  $V_{DD}$  charge storage — The third phase of the

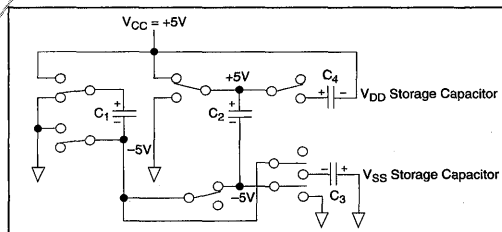


Figure 13a. Charge Pump Phase 1 for  $\pm 10V$ .

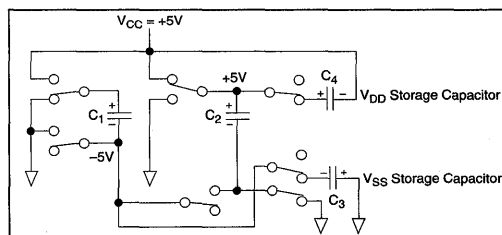


Figure 13b. Charge Pump Phase 1 for  $\pm 5V$ .

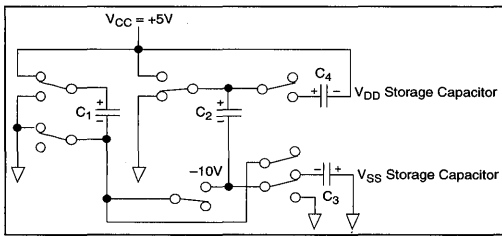


Figure 14a. Charge Pump Phase 2 for  $\pm 10V$ .

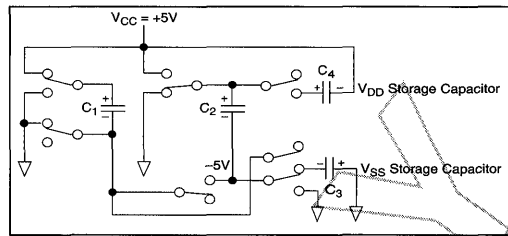


Figure 14b. Charge Pump Phase 2 for  $\pm 5V$ .

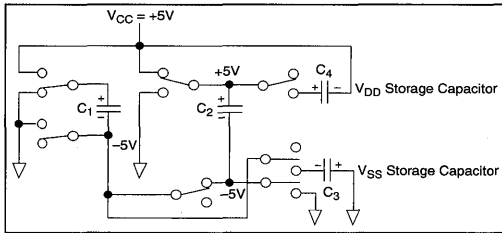


Figure 15. Charge Pump Phase 3.

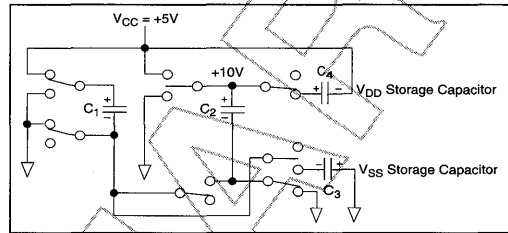


Figure 16. Charge Pump Phase 4.

clock is identical to the first phase — the charge transferred in  $C_1$  produces  $-5V$  in the negative terminal of  $C_1$ , which is applied to the negative side of capacitor  $C_2$ . Since  $C_2^+$  is at  $+5V$ , the voltage potential across  $C_2$  is  $10V$ . For the  $5V$  output,  $C_2^+$  is connected to ground so that the potential on  $C_2$  is only  $+5V$ .

#### Phase 4

—  $V_{DD}$  transfer — The fourth phase of the clock connects the negative terminal of  $C_2$  to ground and transfers the generated  $10V$  or the generated  $5V$  across  $C_2$  to  $C_4$ , the  $V_{DD}$  storage capacitor. Again, simultaneously with this, the

positive side of capacitor  $C_1$  is switched to  $+5V$  and the negative side is connected to ground, and the cycle begins again.

Since both  $V_{DD}$  and  $V_{SS}$  are separately generated from  $V_{CC}$  in a no-load condition,  $V_{DD}$  and  $V_{SS}$  will be symmetrical. Older charge pump approaches that generate  $V^-$  from  $V^+$  will show a decrease in the magnitude of  $V^-$  compared to  $V^+$  due to the inherent inefficiencies in the design.

The clock rate for the charge pump typically operates at  $15kHz$ . The external capacitors must

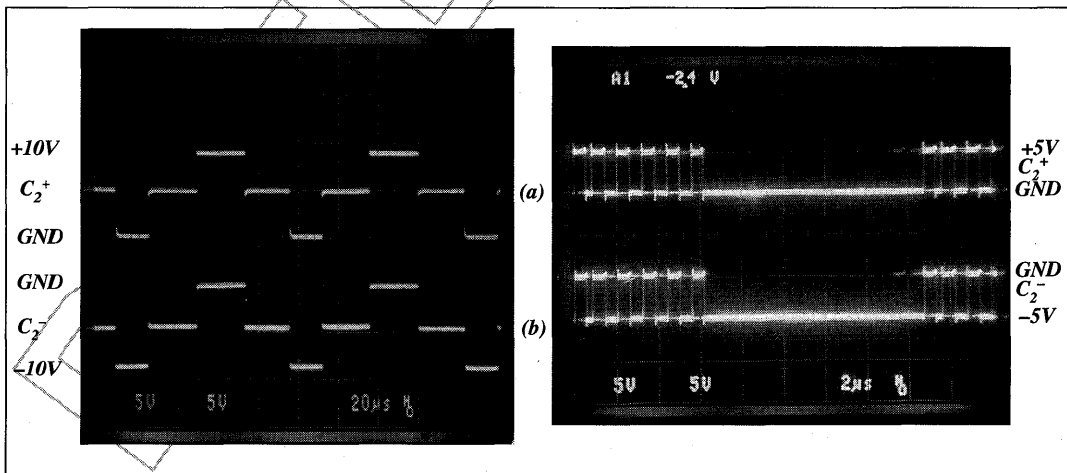


Figure 17. Charge Pump Waveforms

be a minimum of 22 $\mu$ F with a 16V breakdown rating.

### External Power Supplies

For applications that do not require +5V only, external supplies can be applied at the V+ and V- pins. The value of the external supply voltages must be no greater than  $\pm 10.5$ V. The tolerance should be  $\pm 5\%$  from  $\pm 10$ V. The current drain for the supplies is used for RS-232 and RS-423 drivers. For the RS-232 driver, the current requirement will be 3.5mA per driver. The RS-423 driver worst case current drain will be 11mA per driver. Power sequencing is required for the **SP504**. The supplies must be sequenced accordingly: +5V, +10V and -10V. It is important to prevent V<sub>SS</sub> from starting up before V<sub>CC</sub> or V<sub>DD</sub>.

### Drivers

The **SP504** has seven (7) enhanced independent drivers. Control for the mode selection is done via a four-bit control word. The drivers are pre-arranged such that for each mode of operation, the relative position and functionality of the drivers are set up to accommodate the selected interface mode. As the mode of the drivers is changed, the electrical characteristics will change to support the requirements of clock, data, and control line signal levels. *Table 1* shows the mode of each driver in the different interface modes that can be selected.

There are four basic types of driver circuits — RS-232, RS-423, RS-485 and V.35.

The RS-232 drivers output single-ended signals with a minimum of  $\pm 5$ V (with 3K $\Omega$  and 2500pF loading), and can operate up to 120Kbps. The RS-232 drivers are used in RS-232 mode for all signals, and also in V.35 mode where they are used as the control line signals such as DTR and RTS.

The RS-423 drivers are also single-ended signals with a minimum voltage output of  $\pm 3.6$ V (with 450 $\Omega$  loading) and can operate up to 120Kbps. Open circuit V<sub>OL</sub> and V<sub>OH</sub> measurements are  $\pm 4.0$ V to  $\pm 6.0$ V. The RS-423 drivers are used in RS-449, EIA530, EIA-530A and V.36 modes as Category II signals from each of their corresponding specifications.

The third type of driver produces a differential signal that can maintain RS-485,  $\pm 1.5$ V differential output levels with a worst case load of 54 $\Omega$ . The signal levels and drive capability of the RS-485 drivers allow the drivers to also support RS-422 (V.11) requirements of  $\pm 2$ V differential output levels with 100 $\Omega$  loads. The RS-422 drivers are used in RS-449, EIA530, EIA-530A and V.36 modes as Category I signals which are used for clock and data.

The fourth type of driver is the V.35 driver. V.35 levels require  $\pm 0.55$ V driver output signals with a load of 100 $\Omega$ . The **SP504** drivers simplify existing V.35 implementations that use external termination schemes. The drivers were specifically designed to comply with the requirements of V.35 as well as the driver output impedance values of V.35. The drivers achieve the 50 $\Omega$  to 150 $\Omega$  source impedance. However, an external 150 $\Omega$  resistor to ground must be connected to the non-inverting outputs; SD(b), ST(b), and TT(b), in order to comply with the 135 $\Omega$  to 165 $\Omega$  short-circuit impedance for V.35. The V.35 driver is disabled and transparent when the decoder is in all other modes. All of the differential drivers; RS-485, RS-422, and V.35, can operate up to 10Mbps.

The driver inputs are both TTL or CMOS compatible. Each driver input contains a pull-down resistor to ground so that the output will be at a defined state. Unused driver inputs can be left floating.

### Receivers

The **SP504** has seven (7) independent receivers which can be programmed for the different interface modes. Control for the mode selection is done via a 4-bit control word that is independent from the driver control word. The coding for the drivers and receivers is identical. Therefore, if the modes for the drivers and receivers are supposed to be identical in the application, the control lines can be tied together.

Like the drivers, the receivers are pre-arranged for the specific requirements of the interface. As the operating mode of the receivers is changed, the electrical characteristics will change to support the requirements of clock, data, and control

line receivers. *Table 2* shows the mode of each receiver in the different interface modes that can be selected.

There are three basic types of receiver circuits — RS-232, RS-423, and RS-485.

The RS-232 receiver is a single-ended input with a threshold of 0.8V to 2.4V. The RS-232 receiver has an operating voltage range of  $\pm 15$ V and can receive signals up to 120Kbps. The input sensitivity complies with EIA-RS-232 and V.28 at +3V to -3V. The input impedance is 3k $\Omega$  to 7k $\Omega$ . RS-232 receivers are used in RS-232 mode for all data, clock and control signals. They are also used in V.35 mode for control line signals such as CTS and DSR. The RS-423 receivers are also single-ended but have an input threshold as low as  $\pm 200$ mV. The input impedance is guaranteed to be greater than 4K $\Omega$ , with an operating voltage range of  $\pm 7$ V. The RS-423 receivers can operate up to 120Kbps. RS423 receivers are used in RS-449, EIA530, EIA-530A and V.36 modes as Category II signals as indicated by their corresponding specifications.

The third type of receiver is a differential which supports RS-485. The RS-485 receiver has an input impedance of 15K $\Omega$  and a differential threshold of  $\pm 200$ mV. Since the characteristics of an RS-422 (V.11) receiver are actually subsets of RS-485, the receivers for RS-422 requirements are covered by the RS-485 receivers. RS-422 receivers are used in RS-449, EIA530, EIA-530A and V.36 as Category I signals for receiving clock, data, and some control line signals. The differential receivers can receive data up to 10Mbps.

The RS-485 receivers are also used for the V.35 mode. Unlike the older implementations of differential or V.35 receivers, the **SP504** contains an internal resistor termination network that ensures a V.35 input impedance of 100 $\Omega$  ( $\pm 10\%$ ) and a short-circuit impedance of 150 $\Omega$  ( $\pm 15\%$ ). The traditional V.35 implementations required external termination resistors to achieve the proper V.35 impedances. The internal network is connected via low on-resistance FET

switches when the decoder is changed to V.35 mode. The termination network is transparent when all other modes are selected. The V.35 receivers can operate up to 10Mbps.

All receivers include a fail-safe feature that outputs a logic high when the receiver inputs are open. For single-ended RS-232 receivers, there are internal 5k $\Omega$  pull-down resistors on the inputs which produces a logic high ("1") at the receiver outputs. The single-ended RS-423 receivers produce a logic low ("0") on the output when the inputs are open. This is due to a pull-up device connected to the input. The differential receivers have the same internal pull-up device on the non-inverting input which produces a logic high ("1") at the receiver output. The three differential receivers when configured in V.35 mode (RxD, RxC & SCT) do not have fail-safe because the internal termination resistor network is connected.

### Decoder

The **SP504** has the ability to change the interface mode of the drivers or receivers via an 8-bit switch. The decoder for the drivers and receivers is not latched; it is merely a combinational logic switch.

The control word can be externally latched either high or low to write the appropriate code into the **SP504**. The codes shown in *Tables 1 and 2* are the only specified, valid modes for the **SP504**. Undefined codes may represent other interface modes not specified (consult the factory for more information). The drivers are controlled with the data bits labeled TDEC<sub>3</sub>–TDEC<sub>0</sub>. Most of the drivers can be put into tri-state mode by writing 0000 to the driver decode switch. The three drivers TxD, ST and TxC, have a 150 $\Omega$  pull-down resistor to ground connected at the (b) output. This resistor is part of the V.35 driver circuitry and is always connected regardless of mode. Tri-state is possible for all drivers in RS-232 mode. The receivers are controlled with data bits RDEC<sub>3</sub>–RDEC<sub>0</sub>; the code 0000 written to the receivers will place the outputs into tri-state mode. The 0000 decoder word will override the enable control line for the one receiver (SCT).

## SP504 Driver Mode Selection

Pin Label	Mode:	RS-232	V.35	RS-422	RS-485	RS-449	EIA-530	EIA-530A	V.36
TDEC <sub>3</sub> -TDEC <sub>6</sub>	0000	0010	1110	0100	0101	1100	1101	1111	0110
SD(a)	tri-state	RS-232	V.35-	RS-422-	RS-485-	RS-422-	RS-422-	RS-422-	RS-422-
SD(b)	tri-state	tri-state	V.35+	RS-422+	RS-485+	RS-422+	RS-422+	RS-422+	RS-422+
TR(a)	tri-state	RS-232	RS-232	RS-422-	RS-485-	RS-422-	RS-422-	RS-423	RS-423
TR(b)	tri-state	tri-state	tri-state	RS-422+	RS-485+	RS-422+	RS-422+	tri-state	tri-state
RS(a)	tri-state	RS-232	RS-232	RS-422-	RS-485-	RS-422-	RS-422-	RS-422-	RS-423
RS(b)	tri-state	tri-state	tri-state	RS-422+	RS-485+	RS-422+	RS-422+	RS-422+	tri-state
RL(a)	tri-state	RS-232	RS-232	RS-422-	RS-485-	RS-423	RS-423	RS-422-	RS-423
RL(b)	tri-state	tri-state	tri-state	RS-422+	RS-485+	tri-state	tri-state	RS-422+	tri-state
LL(a)	tri-state	RS-232	RS-232	RS-422-	RS-485-	RS-423	RS-423	RS-423	RS-423
LL(b)	tri-state	tri-state	tri-state	RS-422+	RS-485+	tri-state	tri-state	tri-state	tri-state
ST(a)	tri-state	RS-232	V.35-	RS-422-	RS-485-	RS-422-	RS-422-	RS-422-	RS-422-
ST(b)	tri-state	tri-state	V.35+	RS-422+	RS-485+	RS-422+	RS-422+	RS-422+	RS-422+
TT(a)	tri-state	RS-232	V.35-	RS-422-	RS-485-	RS-422-	RS-422-	RS-422-	RS-422-
TT(b)	tri-state	tri-state	V.35+	RS-422+	RS-485+	RS-422+	RS-422+	RS-422+	RS-422+

Table 1. Driver Mode Selection.

## SP504 Receiver Mode Selection

Pin Label	Mode:	RS-232	V.35	RS-422	RS-485	RS-449	EIA-530	EIA-530A	V.36
RDEC <sub>3</sub> -RDEC <sub>6</sub>	0000	0010	1110	0100	0101	1100	1101	1111	0110
RD(a)	R <sub>in</sub> =tri-state	RS-232	V.35-	RS-422-	RS-485-	RS-422-	RS-422-	RS-422-	RS-422-
RD(b)	R <sub>in</sub> =tri-state	>12KΩ to GND	V.35+	RS-422+	RS-485+	RS-422+	RS-422+	RS-422+	RS-422+
RT(a)	R <sub>in</sub> =tri-state	RS-232	V.35-	RS-422-	RS-485-	RS-422-	RS-422-	RS-422-	RS-422-
RT(b)	R <sub>in</sub> =tri-state	>12KΩ to GND	V.35+	RS-422+	RS-485+	RS-422+	RS-422+	RS-422+	RS-422+
CS(a)	R <sub>in</sub> =tri-state	RS-232	RS-232	RS-422-	RS-485-	RS-422-	RS-422-	RS-422-	RS-423
CS(b)	R <sub>in</sub> =tri-state	>12KΩ to GND	>12KΩ to GND	RS-422+	RS-485+	RS-422+	RS-422+	RS-422+	>12KΩ to GND
DM(a)	R <sub>in</sub> =tri-state	RS-232	RS-232	RS-422-	RS-485-	RS-422-	RS-422-	RS-423	RS-423
DM(b)	R <sub>in</sub> =tri-state	>12KΩ to GND	>12KΩ to GND	RS-422+	RS-485+	RS-422+	RS-422+	>12KΩ to GND	>12KΩ to GND
RR(a)	R <sub>in</sub> =tri-state	RS-232	RS-232	RS-422-	RS-485-	RS-422-	RS-422-	RS-422-	RS-423
RR(b)	R <sub>in</sub> =tri-state	>12KΩ to GND	>12KΩ to GND	RS-422+	RS-485+	RS-422+	RS-422+	RS-422+	>12KΩ to GND
IC(a)	R <sub>in</sub> =tri-state	RS-232	RS-232	RS-422-	RS-485-	RS-423	RS-423	RS-423	RS-423
IC(b)	R <sub>in</sub> =tri-state	>12KΩ to GND	>12KΩ to GND	RS-422+	RS-485+	>12KΩ to GND	>12KΩ to GND	>12KΩ to GND	>12KΩ to GND
SCT(a)	R <sub>in</sub> =tri-state	RS-232	V.35-	RS-422-	RS-485-	RS-422-	RS-422-	RS-422-	RS-422-
SCT(b)	R <sub>in</sub> =tri-state	>12KΩ to GND	V.35+	RS-422+	RS-485+	RS-422+	RS-422+	RS-422+	RS-422+

Table 2. Receiver Mode Selection.

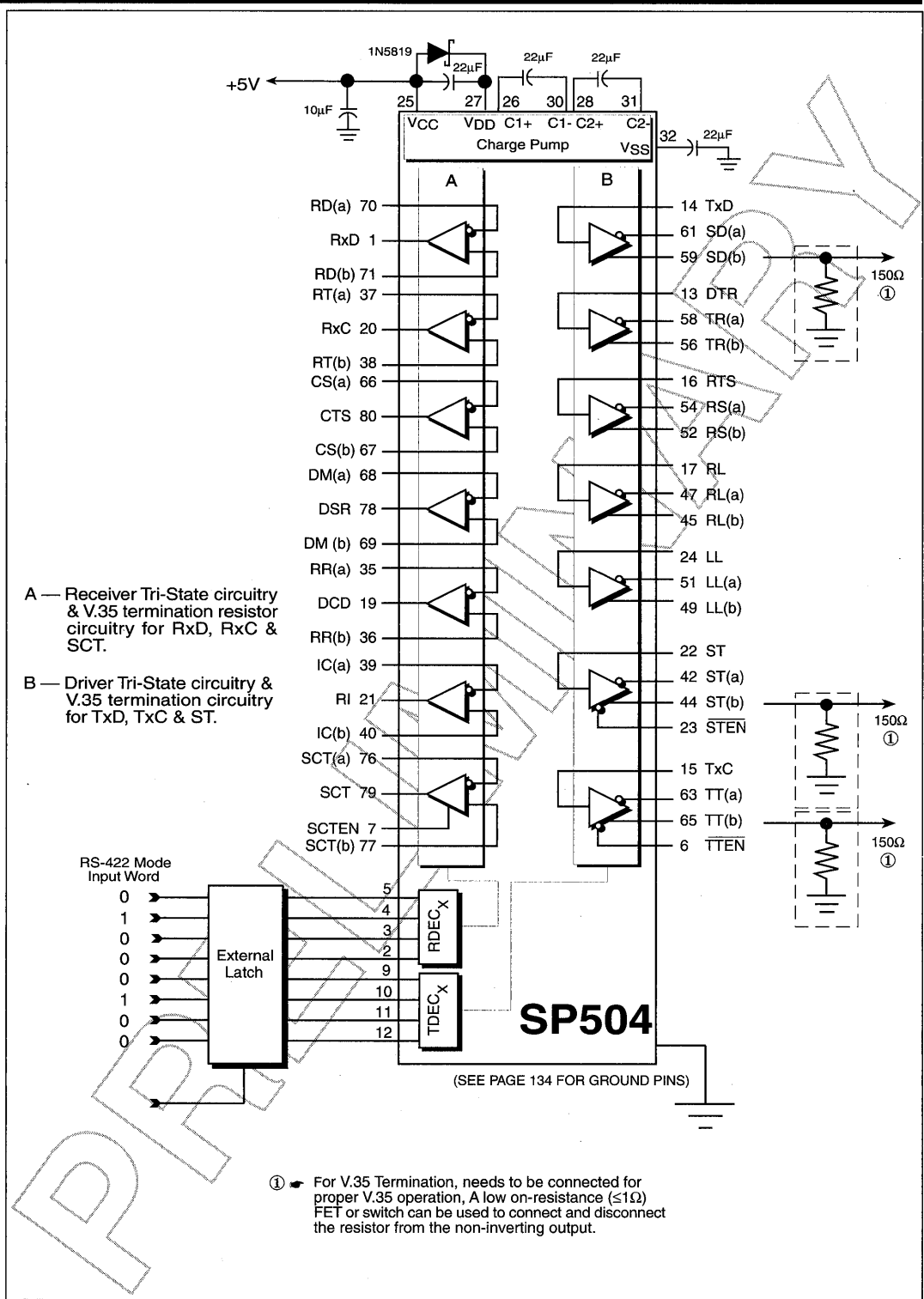
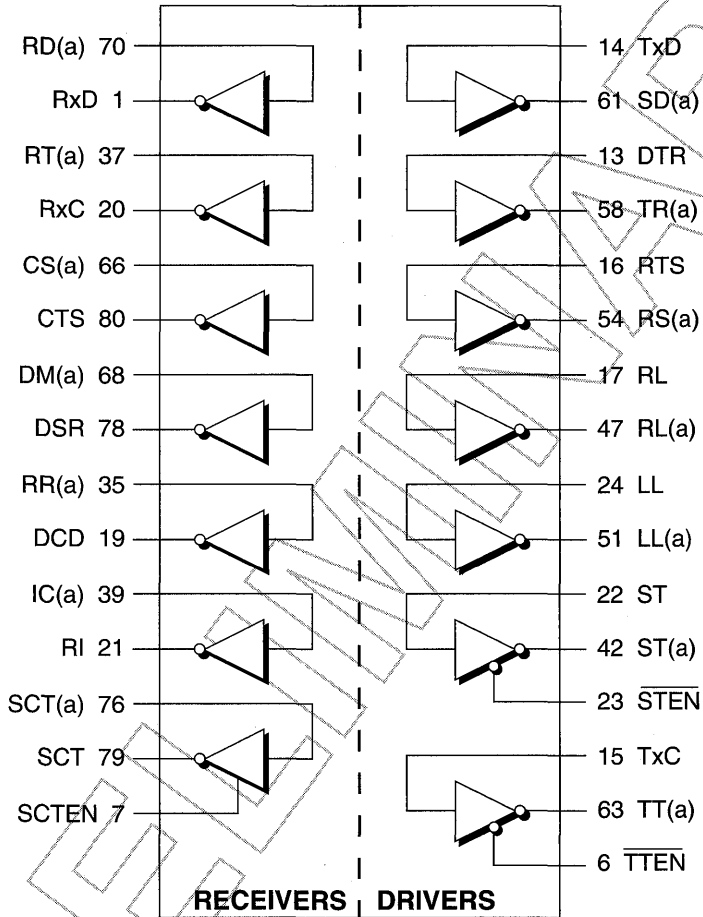


Figure 18. Typical Operation Circuit

MODE: RS-232							
DRIVER				RECEIVER			
TDEC <sub>3</sub>	TDEC <sub>2</sub>	TDEC <sub>1</sub>	TDEC <sub>0</sub>	RDEC <sub>3</sub>	RDEC <sub>2</sub>	RDEC <sub>1</sub>	RDEC <sub>0</sub>
0	0	1	0	0	0	1	0

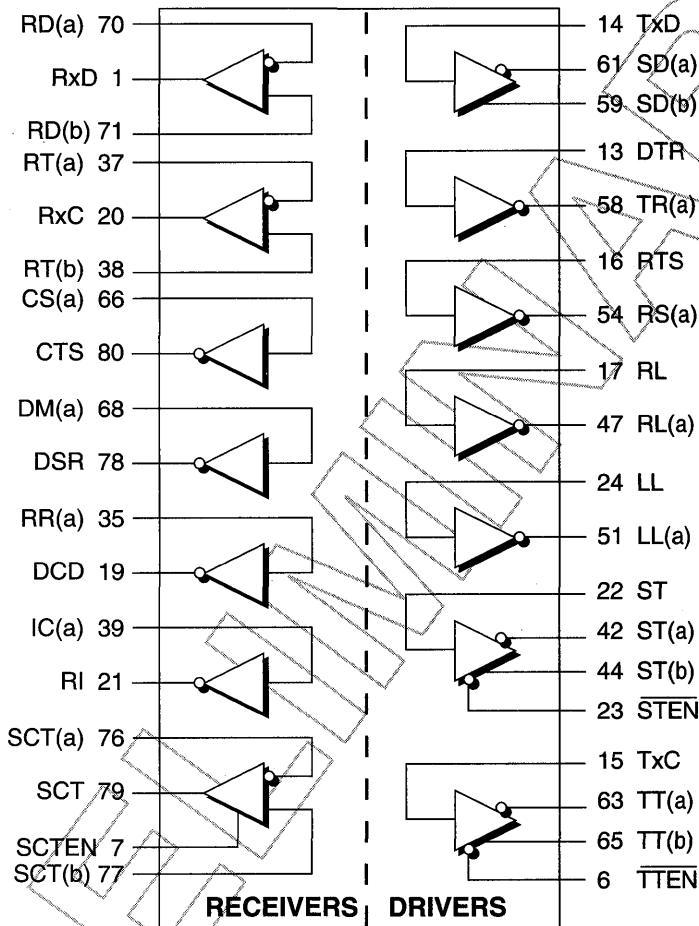


STEN	ST	TTEN	TT	SCTEN	SCT
1	Disabled	1	Disabled	1	Enabled
0	Enabled	0	Enabled	0	Disabled

Figure 19. Mode Diagram — RS-232



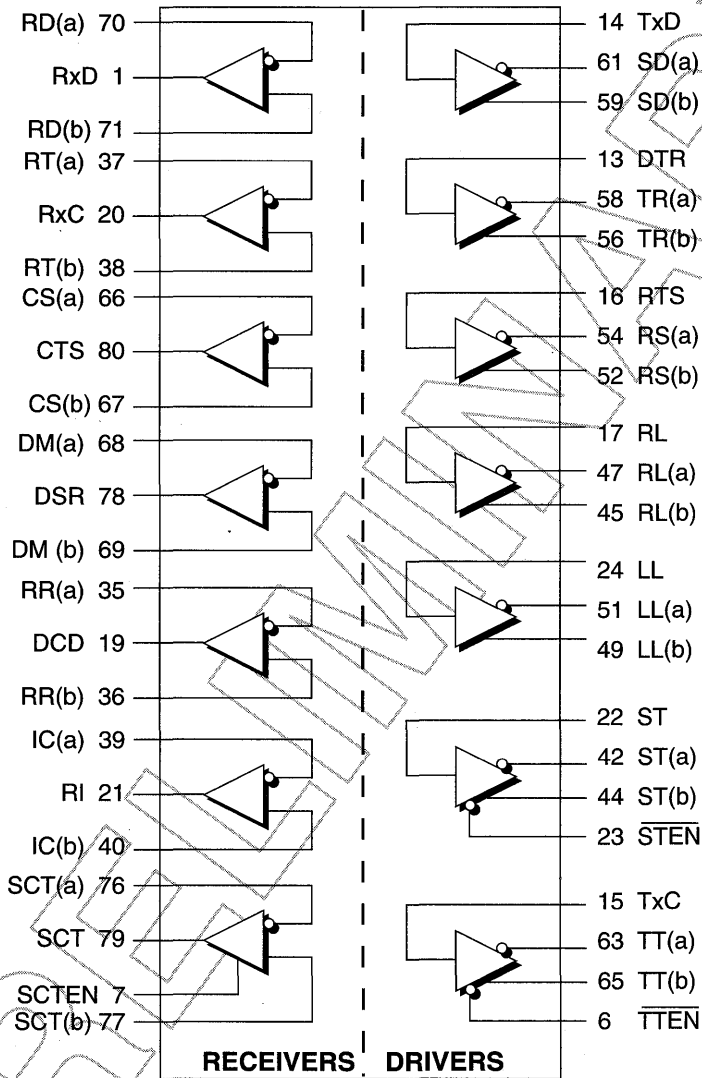
MODE: V.35							
DRIVER				RECEIVER			
TDEC <sub>3</sub>	TDEC <sub>2</sub>	TDEC <sub>1</sub>	TDEC <sub>0</sub>	RDEC <sub>3</sub>	RDEC <sub>2</sub>	RDEC <sub>1</sub>	RDEC <sub>0</sub>
1	1	1	0	1	1	1	0



STEN	ST	$\overline{\text{TTEN}}$	TT	SCTEN	SCT
1	Disabled	1	Disabled	1	Enabled
0	Enabled	0	Enabled	0	Disabled

Figure 20. Mode Diagram — V.35

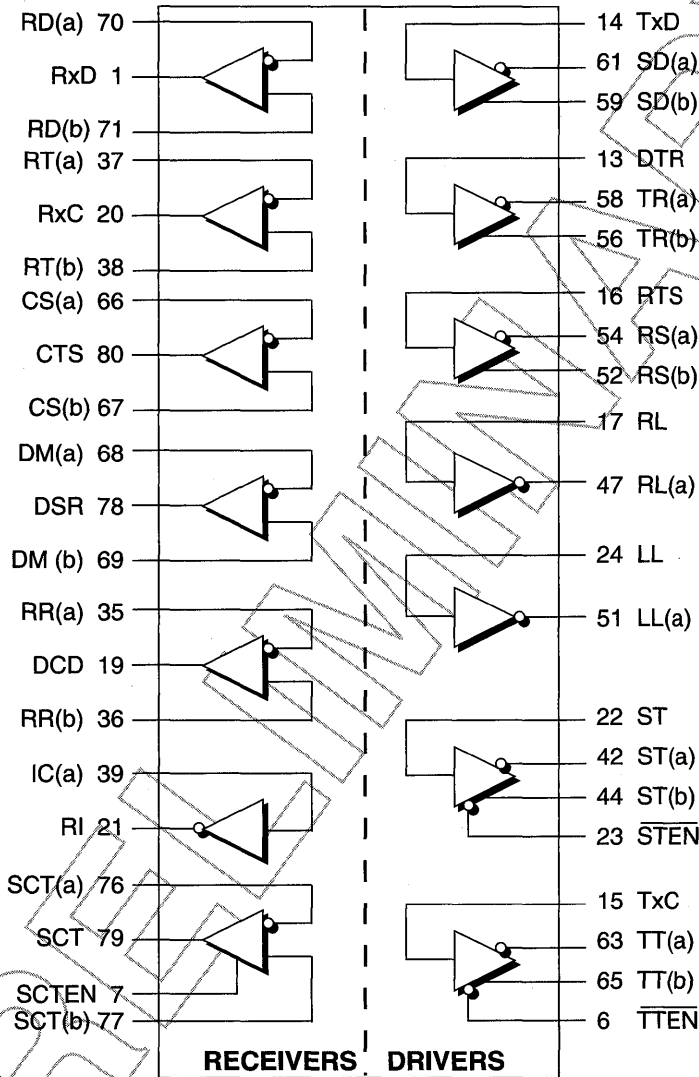
MODE: RS-422							
DRIVER				RECEIVER			
TDEC <sub>3</sub>	TDEC <sub>2</sub>	TDEC <sub>1</sub>	TDEC <sub>0</sub>	RDEC <sub>3</sub>	RDEC <sub>2</sub>	RDEC <sub>1</sub>	RDEC <sub>0</sub>
0	1	0	0	0	1	0	0



STEN	ST	$\overline{\text{TTEN}}$	TT	SCTEN	SCT
1	Disabled	1	Disabled	1	Enabled
0	Enabled	0	Enabled	0	Disabled

Figure 21. Mode Diagram — RS-422

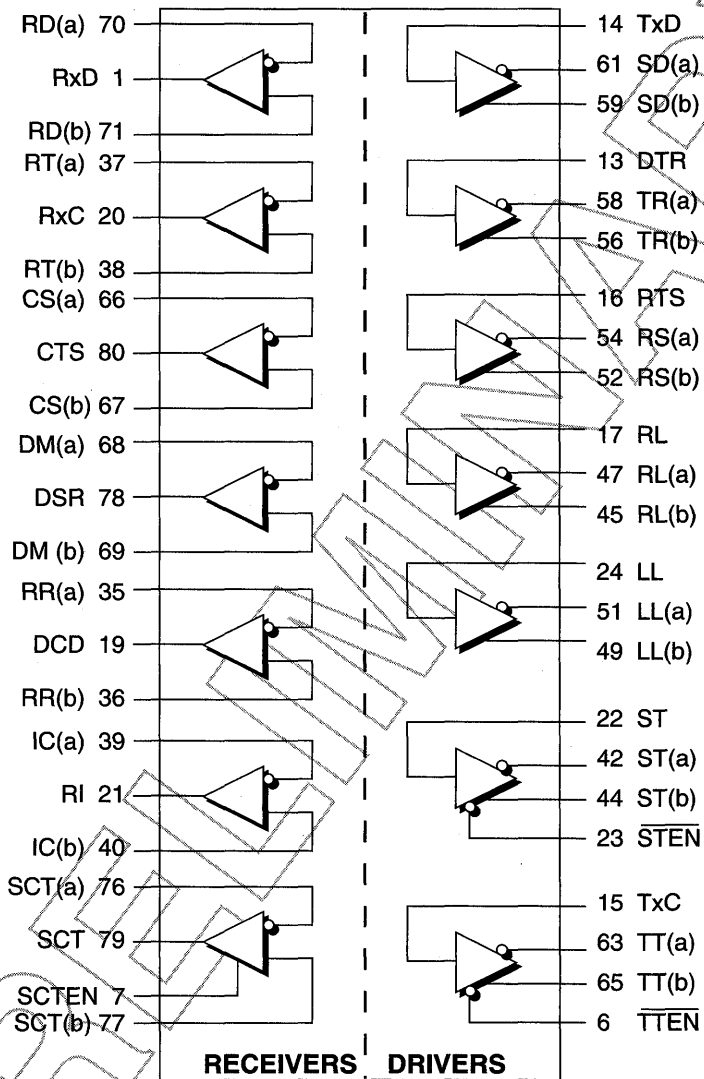
MODE: RS-449							
DRIVER				RECEIVER			
TDEC <sub>3</sub>	TDEC <sub>2</sub>	TDEC <sub>1</sub>	TDEC <sub>0</sub>	RDEC <sub>3</sub>	RDEC <sub>2</sub>	RDEC <sub>1</sub>	RDEC <sub>0</sub>
1	1	0	0	1	1	0	0



STEN	ST	TTEN	TT	SCTEN	SCT
1	Disabled	1	Disabled	1	Enabled
0	Enabled	0	Enabled	0	Disabled

Figure 22. Mode Diagram — RS-449

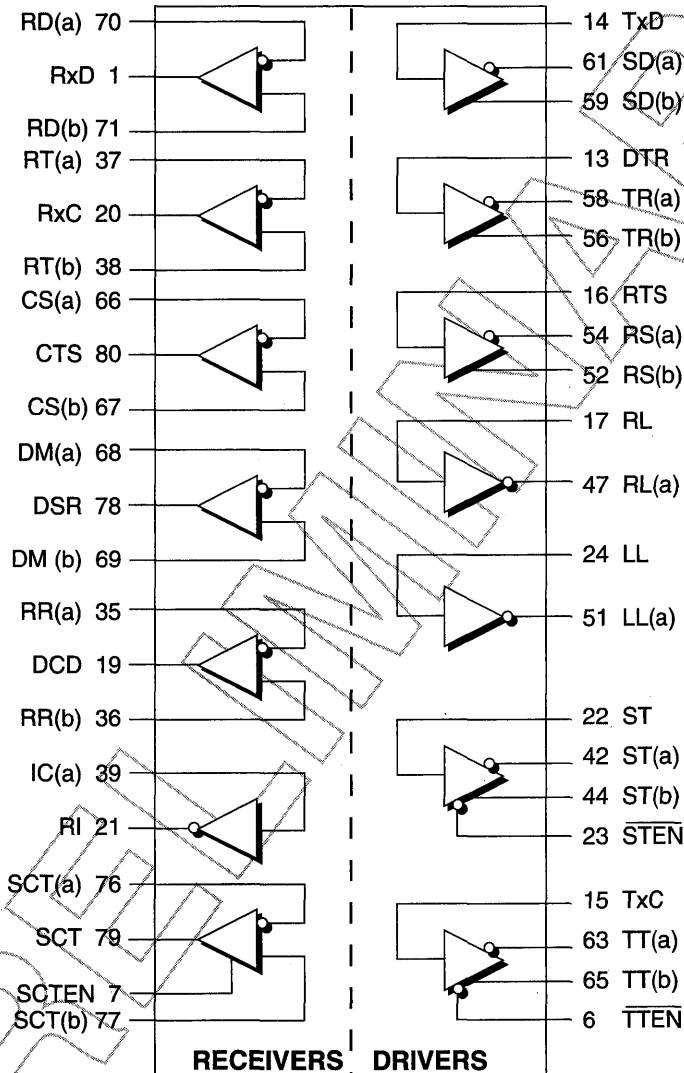
MODE: RS-485							
DRIVER				RECEIVER			
TDEC <sub>3</sub>	TDEC <sub>2</sub>	TDEC <sub>1</sub>	TDEC <sub>0</sub>	RDEC <sub>3</sub>	RDEC <sub>2</sub>	RDEC <sub>1</sub>	RDEC <sub>0</sub>
0	1	0	1	0	1	0	1



STEN	ST	$\overline{\text{TTEN}}$	TT	SCTEN	SCT
1	Disabled	1	Disabled	1	Enabled
0	Enabled	0	Enabled	0	Disabled

Figure 23. Mode Diagram — RS-485

MODE: EIA-530							
DRIVER				RECEIVER			
TDEC <sub>3</sub>	TDEC <sub>2</sub>	TDEC <sub>1</sub>	TDEC <sub>0</sub>	RDEC <sub>3</sub>	RDEC <sub>2</sub>	RDEC <sub>1</sub>	RDEC <sub>0</sub>
1	1	0	1	1	1	0	1



STEN	ST	TTEN	TT	SCTEN	SCT
1	Disabled	1	Disabled	1	Enabled
0	Enabled	0	Enabled	0	Disabled

Figure 24. Mode Diagram — EIA-530

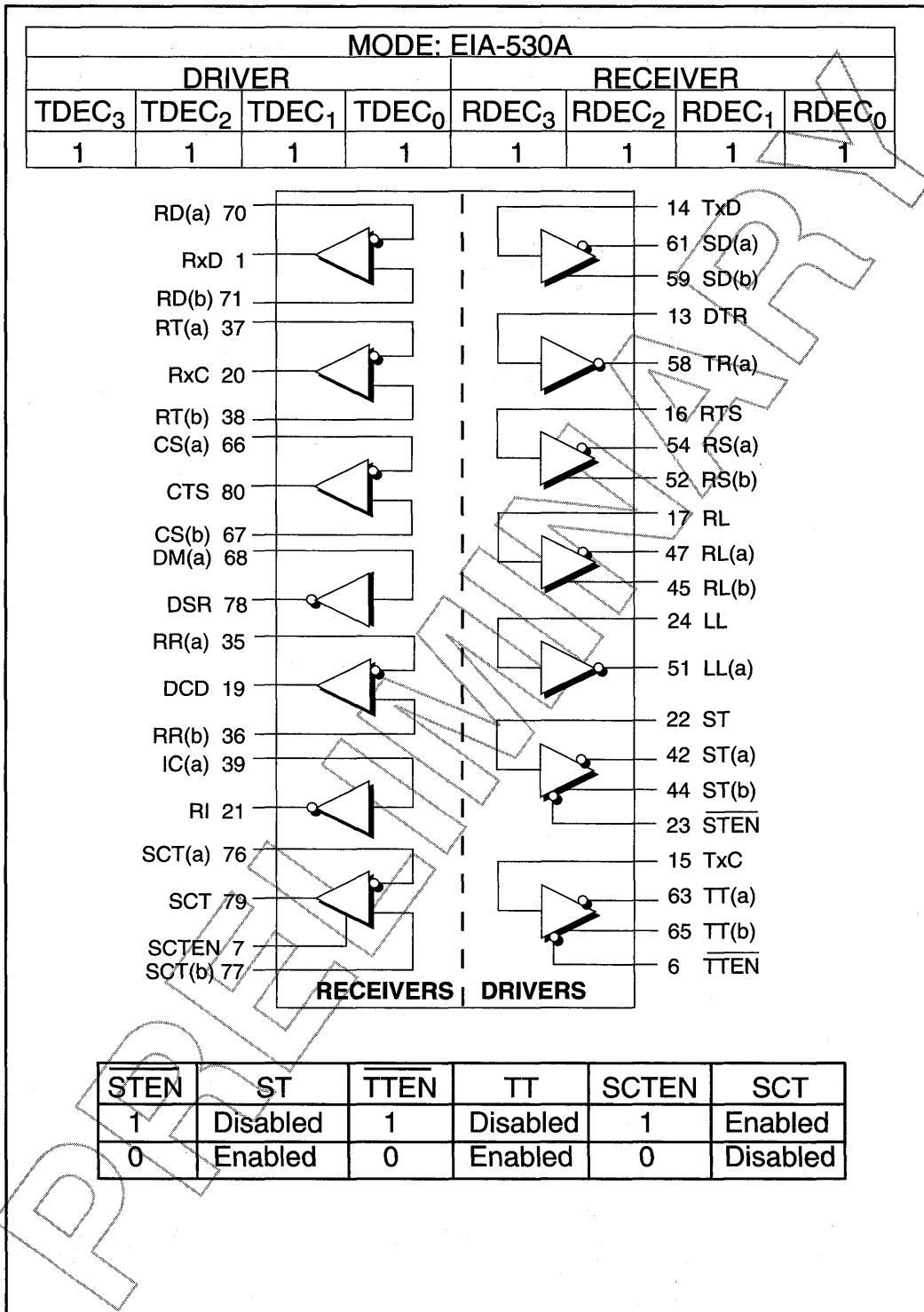
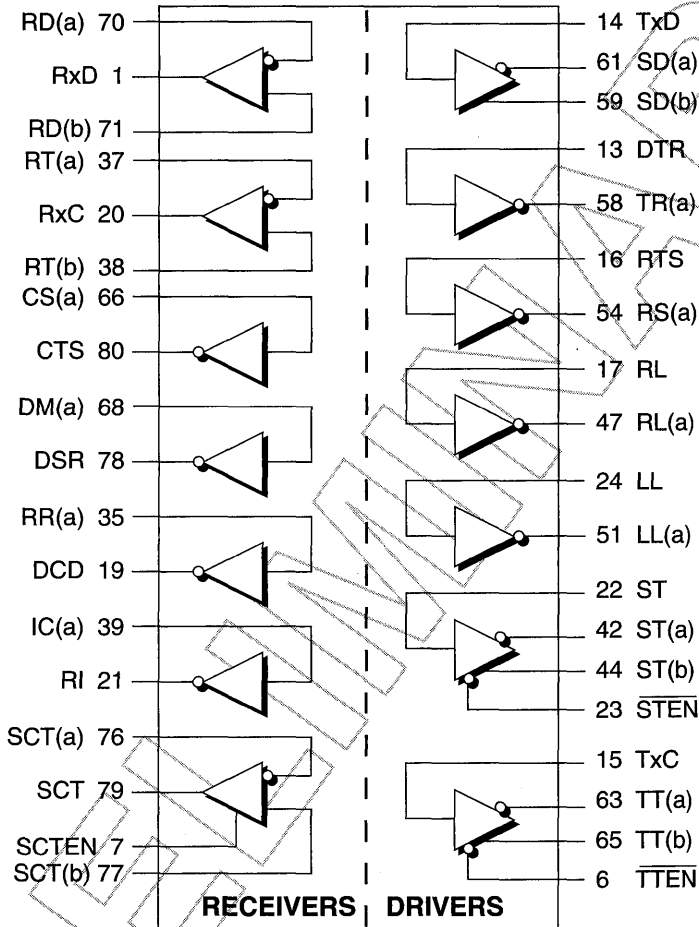


Figure 25. Mode Diagram — EIA-530A

MODE: V.36							
DRIVER				RECEIVER			
TDEC <sub>3</sub>	TDEC <sub>2</sub>	TDEC <sub>1</sub>	TDEC <sub>0</sub>	RDEC <sub>3</sub>	RDEC <sub>2</sub>	RDEC <sub>1</sub>	RDEC <sub>0</sub>
0	1	1	0	0	1	1	0



$\overline{\text{STEN}}$	ST	$\overline{\text{TTEN}}$	TT	SCTEN	SCT
1	Disabled	1	Disabled	1	Enabled
0	Enabled	0	Enabled	0	Disabled

Figure 26. Mode Diagram — V.36

## DTE and DCE configurations with the SP504

A serial port can be easily configured for DTE and DCE using two **SP504** parts. The **SP504** allocates signals for data, clock and control lines. The data signals specified in the EIA standards and CCITT are referenced as DTE in the **SP504** datasheet. The DB-25 pin assignment table below is also referenced as DTE. For the DTE, TxD is a driver which drives the data to RxD, a receiver, on the DCE side. TxC or TT is a driver on the DTE side which drives the clock signal to the RxC receiver on the DCE

side. The **SP504** offers tri-state control via the decoder address by writing "0000" into TDEC<sub>x</sub> or RDEC<sub>x</sub>. If the serial port is configured to DTE mode, the **SP504** dedicated to DCE must be tri-stated to avoid bus contention problems on the serial port.

As shown on Figure 15, the CCITT signal allocations from the **SP504** in either DTE or DCE to the DB-25 connector. This connector type was selected because of its wide usage. Another connector type can be used as well such as the  $\mu$ DB-26.

### DB-25 Connector Pin Assignments for Various Protocols

DB-25 Pin #	RS-232	EIA-530	RS-449	RS-422	V.35	V.36
1	shield	shield	shield	shield	CCITT# 101	CCITT# 101
2	TxD	TxD(A)	SD(A)	T(A)	103(A)	103(A)
3	RxD	RxD(A)	RD(A)	R(A)	104(A)	104(A)
4	RTS	RTS(A)	RS(A)	C(A)	105	105(A)
5	CTS	CTS(A)	CS(A)	-	106	106(A)
6	DSR	DSR(A)	DM(A)	-	107	107(A)
7	Signal GND	Signal GND	Signal GND	Signal GND	102	102
8	DCD	RLSD(A)	RR(A)	I(A)	109	109(A)
9	-	RxC(B)	RT(B)	-	115(B)	115(B)
10	-	RLSD(B)	RR(B)	I(B)	-	109(B)
11	-	TxC(B-DTE)	TT(B)	-	113(B)	113(B)
12	DCD (2nd)	TxCC(B-DCE)	ST(B)	S(B)	114(B)	114(B)
13	CTS (2nd)	CTS(B)	CS(B)	-	-	106(B)
14	TxD (2nd)	TxD(B)	SD(B)	T(B)	103(B)	103(B)
15	TxCC (DCE)	TxCC(A-DCE)	ST(A)	S(A)	114(B)	114(B)
16	RxD (2nd)	RxD(B)	RD(B)	R(B)	104(B)	104(B)
17	RxC	RxC(A)	RT(A)	-	115(A)	115(A)
18	LL	LL	LL	-	-	141
19	RTS (2nd)	RTS(B)	RS(B)	C(B)	-	105(B)
20	DTR	DTR(A)	TR(A)	-	-	-
21	RL	RL	RL	-	-	140
22	RI	DSR(B)	DM(B)	-	-	107(B)
23	SRS	DTR(B)	TR(B)	-	-	-
24	TxC (DTE)	TxC(A-DTE)	TT(A)	-	113(A)	113(A)



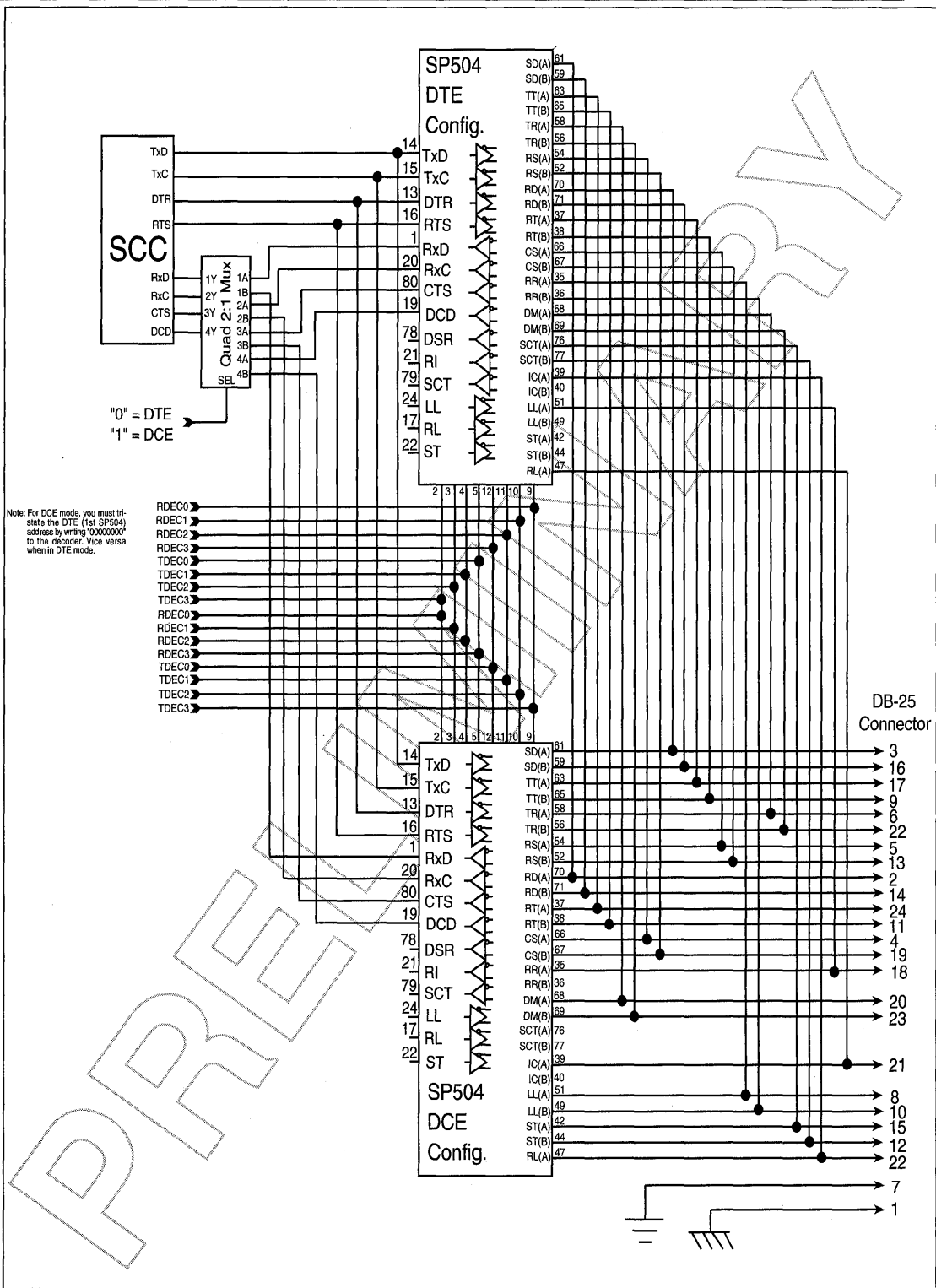


Figure 27. DTE/DCE Application with the SP504

## ADDITIONAL TRANSCEIVERS WITH THE SP504

Serial ports usually can have two data signals (SD, RD), three clock signals (TT, ST, RT), and at least eight control signals (CS, RS, etc.). EIA-RS-449 contains twenty six signal types including for a DB-37 connector. A DB-37 serial port design may require thirteen drivers and fourteen receivers<sup>1</sup>. Although many applications do not use all these signals, some applications may need to support extra functions such as diagnostics. The **SP504** supports enough transceivers for the primary channels of data, clock and control signals. Configuring LL, RL and TM would require two additional drivers and one receiver if designing for a DTE (one driver and two receivers for a DCE).

A programmable transceiver such as the **SP332** is a convenient solution in a design that requires a couple extra single ended or differential drivers/receivers. As shown in Figure 16, the **SP332** can be configured to four different variations.

The **SP332** in Figure 17 is configured for two single-ended drivers and one differential receiver. For a DTE design, the two drivers are used for LL and RL signals and the receiver is used for the TM signal. This configuration was selected because the two RS-232 drivers can be

used for RS-423 by connecting a zener clamping diode to ground on the two driver outputs. The diodes will limit the voltage swing on the outputs so that the  $V_{OC} = \pm 4V$  to  $\pm 6V$  adheres to the RS-423 specification. The differential receiver can be easily configured to RS-423 by grounding the non-inverting input. The receiver will adhere to the RS-423 specifications.

CIRCUIT MNEMONIC	CIRCUIT NAME	CIRCUIT DIRECTION	CIRCUIT TYPE	
SG	SIGNAL GROUND	-----	COMMON	PRIMARY CHANNEL
SC	SEND COMMON	TO DCE		
RC	RECEIVE COMMON	FROM DCE		
IS	TERMINAL IN SERVICE	TO DCE	CONTROL	
IC	INCOMING CALL	FROM DCE		
TR	TERMINAL READY	TO DCE		
DM	DATA MODE	FROM DCE		
SD	SEND DATA	TO DCE	DATA	
RD	RECEIVE DATA	FROM DCE		
TT	TERMINAL TIMING	TO DCE	TIMING	
ST	SEND TIMING	FROM DCE		
RT	RECEIVE TIMING	FROM DCE		
RS	REQUEST TO SEND	TO DCE	CONTROL	
CS	CLEAR TO SEND	FROM DCE		
RR	RECEIVER READY	FROM DCE		
SQ	SIGNAL QUALITY	FROM DCE		
NS	NEW SIGNAL	TO DCE		
SF	SELECT FREQUENCY	TO DCE		
SR	SIGNAL RATE SELECTOR	TO DCE		
SI	SIGNAL RATE INDICATOR	FROM DCE		
SSD	SECONDARY SEND DATA	TO DCE	DATA	SECONDARY CHANNEL
SRD	SECONDARY RD	FROM DCE		
SRS	SECONDARY RS	TO DCE	CONTROL	
SCS	SECONDARY CS	FROM DCE		
SRR	SECONDARY RR	FROM DCE		
LL	LOCAL LOOPBACK	TO DCE	CONTROL	
RL	REMOTE LOOPBACK	TO DCE		
TM	TEST MODE	FROM DCE		
SS	SELECT STANDBY	TO DCE	CONTROL	
SB	STANDBY INDICATOR	FROM DCE		

RS-449 Interchange Circuits Table

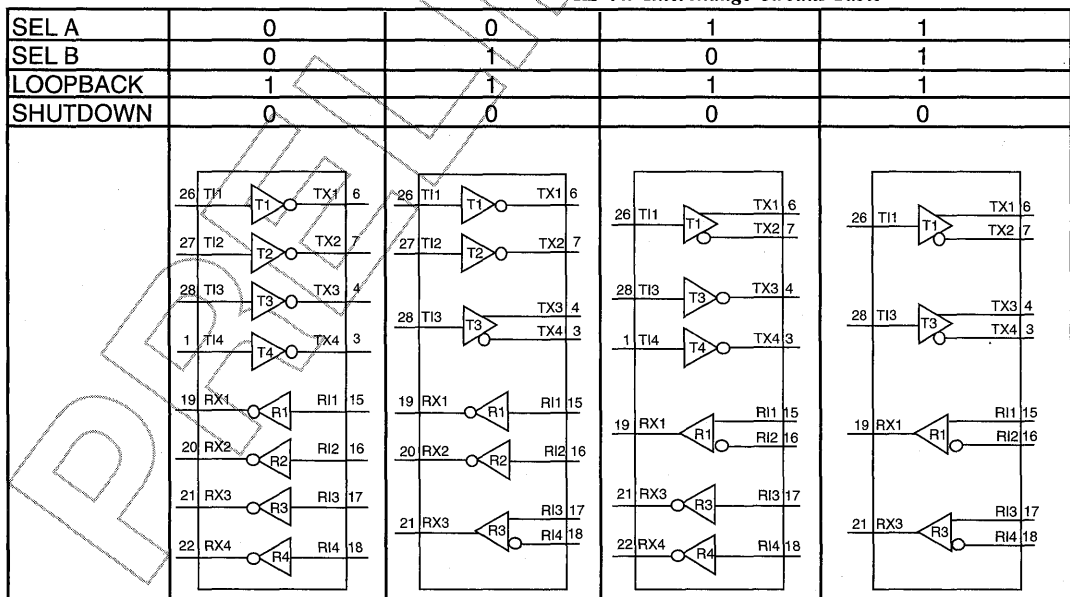


Figure 28. Mode selection for the SP332

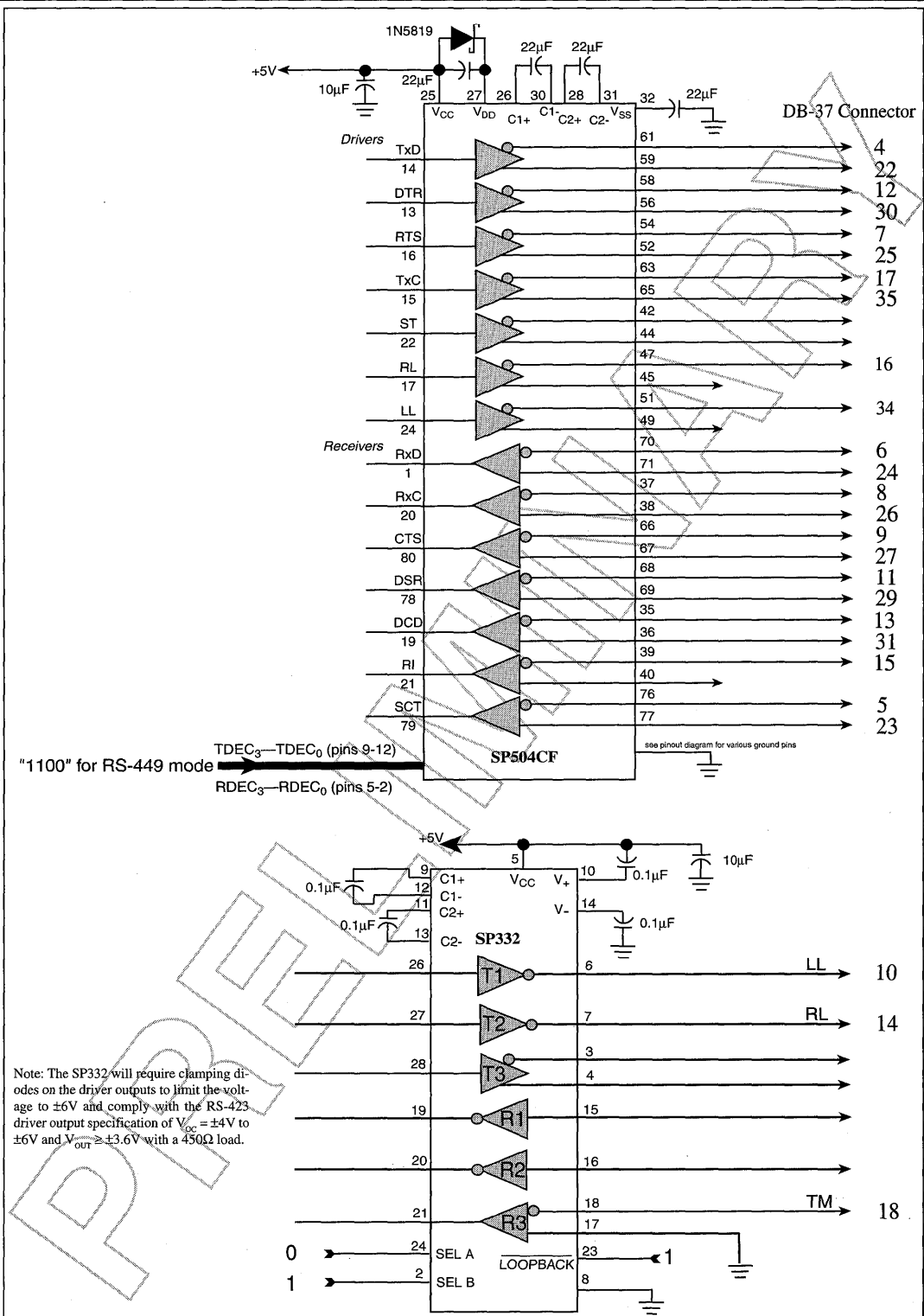


Figure 29. Adding extra differential and single-ended transceivers using the SP332

## SP502/SP503 EVALUATION BOARD

The **SP502/SP503 Evaluation Board (EB)** can be used to evaluate the **SP504**. Each board comes equipped with an 80-pin QFP Zero-Insertion socket to allow for testing of multiple devices. The control lines and inputs and outputs of the device can be controlled either manually or via a data bus under software control. There is a 50-pin connector to allow for easy connection to an existing system via a ribbon cable. There are also open areas on the board to add additional circuitry to support application specific requirements.

### Manual Control

The **SP502/SP503EB** will support the **SP502, SP503** and **SP504** multi-mode serial transceivers. The transceiver I/O lines are brought out to test pins arranged in the same configuration as shown elsewhere in this data sheet. A top layer silk-screen shows the drivers and receivers to allow direct correlation to the data sheet. The transmitter and receiver decode bits are tied together and are brought out to a DIP switch for manual control of both the driver and receiver interface modes. Since the coding for the drivers and receivers is identical, the bits have been tied together. The DIP switch has 7 positions, four of which are reserved for the TDEC/RDEC control and the other three are used as tri-state control pins. The labels that are in [brackets] apply only to the **SP503** and **SP504**. If a logic one, "1", is asserted, the corresponding red LED will be lit. If a zero is asserted, the corresponding red LED will not be lit.

### Software Control

A 50-pin connector brings all the analog and digital I/O lines,  $V_{cc}$ , and GND to the edge of the card. This can be wired to the user's existing design via a ribbon cable. A DB-25 adapter is available upon request. The pinout for the connector is described in the following section. When the evaluation board is operated under software control, the DIP switch should be set up so that all bits are low (all LEDs off). This will tie 20K $\Omega$  pulldown resistors from the inputs to ground and let the external system control the state of the control inputs.

## Power and Ground Requirements

The evaluation board layout has been optimized for performance by using basic analog circuit techniques. The four charge-pump capacitors must be 22 $\mu$ F (16V) and be placed as close to the unit as possible; tantalum capacitors are suggested. The decoupling capacitor must be a minimum of 1 $\mu$ F; depending upon the operating environment, 10 $\mu$ F should be enough for worst case situations. The ground plane for the part must be solid, extending completely under the package. The power supplies for the device should be as accurate as possible; for rated performance  $\pm 5\%$  is necessary. The power supply current will vary depending upon the selected mode, the amount of loading and the data rate. As a maximum, the user should reserve 450mA for  $I_{cc}$ . The worst-case operating mode is RS-485 under full load of seven drivers supplying 2V to 54 $\Omega$  loads. The power and ground inputs can be supplied through either the banana jacks on the evaluation board (Red =  $V_{cc}$  = +5V $\pm 5\%$ , Black = GND) or through the connector.

For reference, the 80-pin QFP Socket is a TESCO part number FPQ-80-65-09A. The 50-pin connector is an AMP part number 749075-5.

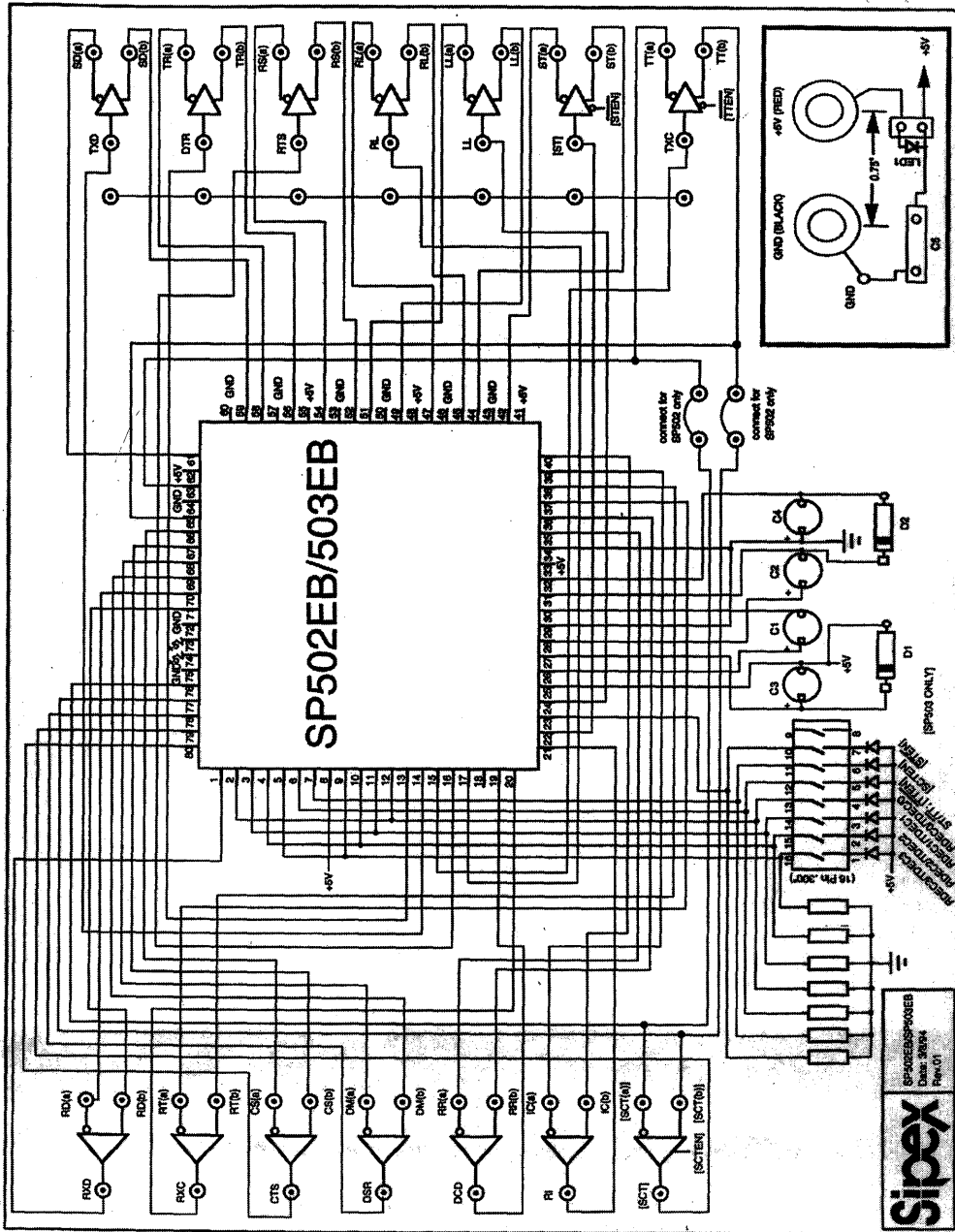
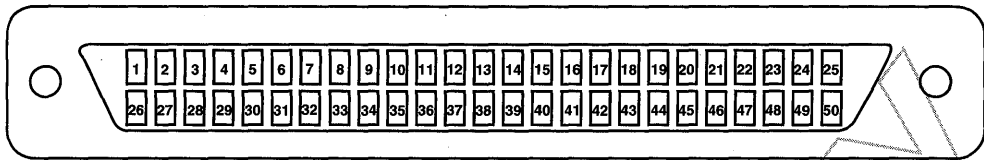


Figure 30. SP502/503 Evaluation Board Schematic

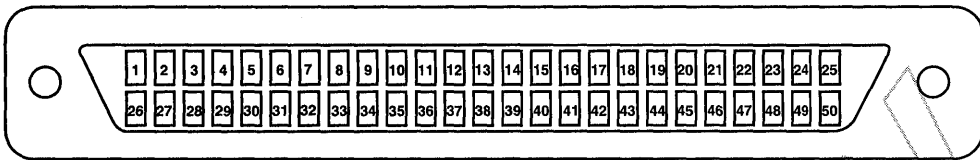


**EDGE CONNECTOR**      **DUT PIN DESCRIPTIONS**

- 01 TxD (pin 14) – TTL Input – Transmit data; source for SD(a) and SD(b) outputs.
- 02 DTR (pin 13) – TTL Input – Data terminal ready; source for TR(a) and TR(b) outputs.
- 03 ST/TT (pin 6) – TTL Input – ST/TT select pin; enables ST drivers and disables TT drivers when high. Disables ST drivers and enables TT drivers when low.
- 04 DEC<sub>3</sub>/RDEC<sub>3</sub> (pin 5) – TTL Input – Transmitter/Receiver decode register.
- 05 TDEC<sub>2</sub>/RDEC<sub>2</sub> (pin 4) – TTL Input – Transmitter/Receiver decode register.
- 06 TDEC<sub>1</sub>/RDEC<sub>1</sub> (pin 3) – TTL Input – Transmitter/Receiver decode register.
- 07 TDEC<sub>0</sub>/RDEC<sub>0</sub> (pin 2) – TTL Input – Transmitter/Receiver decode register.
- 08 RxD (pin 1) – TTL Output – Receive data; sourced from RD(a) and RD(b) inputs.
- 09 CTS (pin 80) – TTL Output – Clear to send; sourced from CS(a) and CS(b) inputs.
- 10 RxT (pin 79) – TTL Output – RxT; sourced from TT(a), TT(b) inputs.
- 11 DSR (pin 78) – TTL Output – Data set ready; sourced from DM(a) and DM(b) inputs.
- 12 RD(b) (pin 71) – Analog In – Receive data, non-inverted; source for RxD.

**EDGE CONNECTOR**      **DUT PIN DESCRIPTIONS**

- 13 RD(a) (pin 70) – Analog In – Receive data, inverted; source for RxD.
- 14 DM(b) (pin 69) – Analog In – Data mode, non-inverted; source for DSR.
- 15 DM(a) (pin 68) – Analog In – Data mode, inverted; source for DSR.
- 16 CS(b) (pin 67) – Analog In – Clear to send; non-inverted; source for CTS.
- 17 CS(a) (pin 66) – Analog In – Clear to send, inverted; source for CTS.
- 18 TT(b) (pin 65) – Analog In or Out – Terminal timing, non-inverted; sourced from TxC input.
- 19 TT(a) (pin 63) – Analog In or Out – Terminal timing; inverted; sourced from TxC input.
- 20 TR(a) (pin 58) – Analog Out – Terminal ready, inverted; sourced from DTR.
- 21 TR(b) (pin 56) – Analog Out – Terminal ready; non-inverted; sourced from DTR.
- 22 SD(a) (pin 61) – Analog Out – Send data, inverted; sourced from TxD.
- 23 SD(b) (pin 59) – Analog Out – Send data; non-inverted; sourced from TxD.
- 24 RS(a) (pin 54) – Analog Out – Ready to send; inverted; sourced from RTS.
- 25 RS(b) (pin 52) – Analog Out – Ready to send, non-inverted; sourced from RTS.



EDGE CONNECTOR	DUT PIN DESCRIPTIONS	EDGE CONNECTOR	DUT PIN DESCRIPTIONS
26	ST (pin 22) – TTL Input – Send Timing; source for ST(a) and ST(b) outputs.	40	RT(b) (pin 38) – Analog In – Receive timing, non-inverted; source for RxC.
27	STEN (pin 23) – TTL Input – Driver enable control pin; active low.	41	RT(a) (pin 37) – Analog In – Receive timing; inverted; source from RxC.
28	SCT(a) (pin 76) – Analog Input – Inverting; input for SCT receiver.	42	RR(b) (pin 36) – Analog In – Receiver ready; non-inverted; source for DCD.
29	SCT(b) (pin 77) – Analog Input – Non-inverting; input for SCT receiver.	43	RR(a) (pin 35) – Analog In – Receiver ready; inverted; source for DCD.
30	V <sub>CC</sub> – +5V for all circuitry.	44	LL (pin 24) – TTL Input – Local loopback; source for LL(a) and LL(b) outputs.
31	GND – signal and power ground.	45	RI (pin 21) – TTL Output – Ring indicator; sourced from IC(a) and IC(b) inputs.
32	LL(a) (pin 51) – Analog Out – Local loopback, inverted; sourced from LL.	46	RxC (pin 20) – TTL Output – Receive clock; sourced from RT(a) and RT(b) inputs.
33	LL(b) (pin 49) – Analog Out – Local loopback, non-inverted sourced from LL.	47	DCD (pin 19) – TTL Output – Data carrier detect; sourced from RR(a) and RR(b) inputs.
34	RL(a) (pin 47) – Analog Out – Remote loopback; inverted; sourced from RL.	48	RL (pin 17) – Analog Out – Remote loopback; source for RL(a) and RL(b) outputs.
35	RL(b) (pin 45) – Analog Out – Remote loopback; non-inverted; sourced from RL.	49	RTS (pin 16) – TTL Input – Ready to send; source for RS(a) and RS(b) outputs.
36	ST(b) (pin 44) – Analog Out – Send timing, non-inverted; sourced from ST.	50	TxC (pin 15) – TTL Input – Transmit clock; Source for TT(a) and TT(b) driver outputs.
37	ST(a) (pin 42) – Analog Output – Send timing, inverted; sourced from ST.		
38	IC(b) (pin 40) – Analog In – Incoming call; non-inverted; source for RI.		
39	IC(a) (pin 39) – Analog In – Incoming call; inverted; source for RI.		

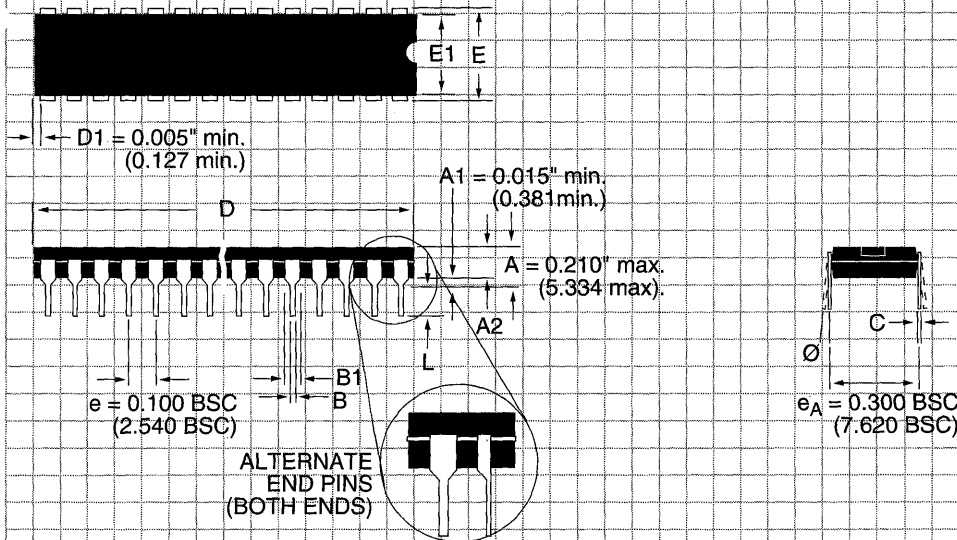
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ORDERING INFORMATION		
<b>Model</b>	<b>Temperature Range</b>	<b>Package Types</b>
SP504CF .....	0°C to +70°C .....	80-pin QFP



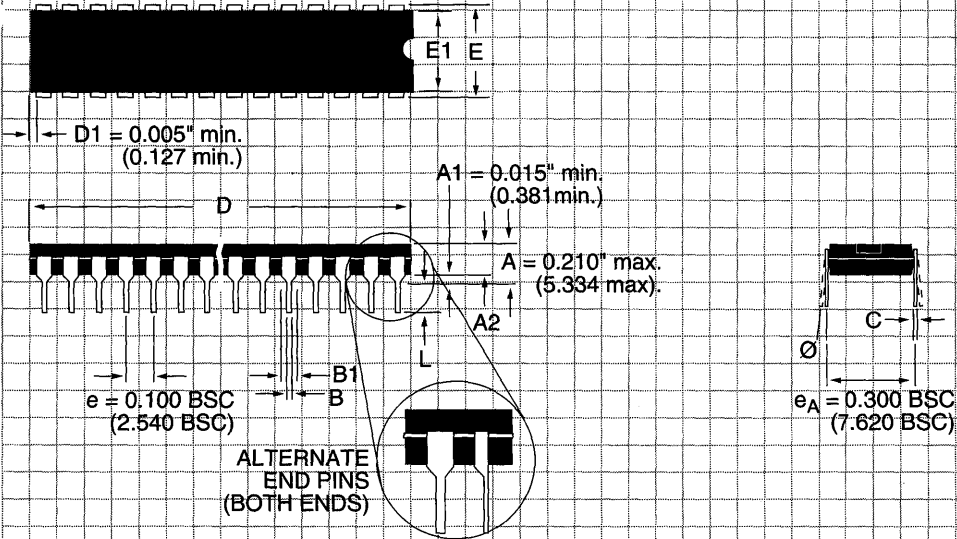
<b>Package Type</b>	<b>Page</b>
Dual-in-Line, Plastic, 0.3" Width, 8 through 22 pins .....	160
Dual-in-Line, Plastic, 0.3" Width, 24 pins or more .....	161
Dual-in-Line, Plastic, 0.6" Width, 22 pins or more .....	162
Small Outline, Shrink, SSOP .....	163
Small Outline, SOIC, 0.15" Width .....	164
Small Outline, SOIC, 0.30" Width .....	165
Leadless Chip Carrier, Plastic .....	166,167
Quad Flatpack, 80-pin .....	168

**PACKAGE: PLASTIC  
 DUAL-IN-LINE  
 (NARROW)**



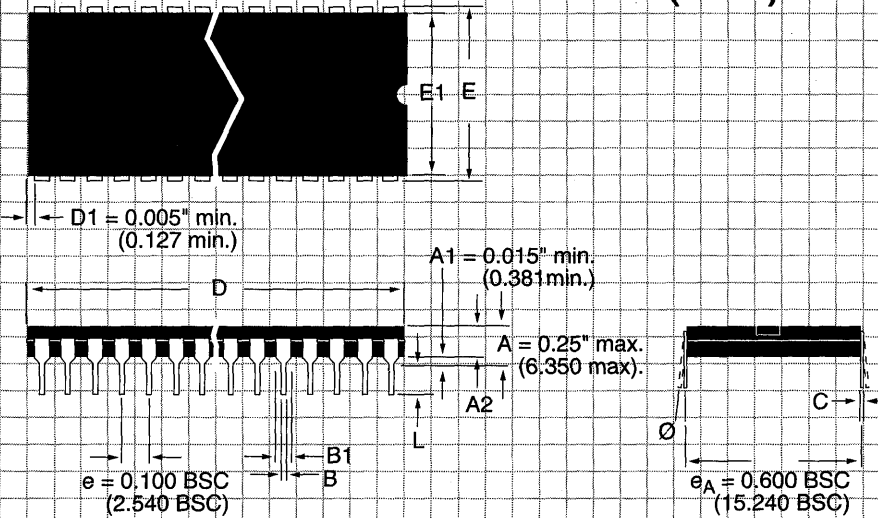
DIMENSIONS (Inches) Minimum/Maximum (mm)	8-PIN	14-PIN	16-PIN	18-PIN	20-PIN	22-PIN
A2	0.115/0.195 (2.921/4.953)	0.115/0.195 (2.921/4.953)	0.115/0.195 (2.921/4.953)	0.115/0.195 (2.921/4.953)	0.115/0.195 (2.921/4.953)	0.115/0.195 (2.921/4.953)
B	0.014/0.022 (0.356/0.559)	0.014/0.022 (0.356/0.559)	0.014/0.022 (0.356/0.559)	0.014/0.022 (0.356/0.559)	0.014/0.022 (0.356/0.559)	0.014/0.022 (0.356/0.559)
B1	0.045/0.070 (1.143/1.778)	0.045/0.070 (1.143/1.778)	0.045/0.070 (1.143/1.778)	0.045/0.070 (1.143/1.778)	0.045/0.070 (1.143/1.778)	0.045/0.070 (1.143/1.778)
C	0.008/0.014 (0.203/0.356)	0.008/0.014 (0.203/0.356)	0.008/0.014 (0.203/0.356)	0.008/0.014 (0.203/0.356)	0.008/0.014 (0.203/0.356)	0.008/0.014 (0.203/0.356)
D	0.355/0.400 (9.017/10.160)	0.735/0.775 (18.669/19.685)	0.780/0.800 (19.812/20.320)	0.880/0.920 (22.352/23.368)	0.980/1.060 (24.892/26.924)	1.145/1.155 (29.083/29.337)
E	0.300/0.325 (7.620/8.255)	0.300/0.325 (7.620/8.255)	0.300/0.325 (7.620/8.255)	0.300/0.325 (7.620/8.255)	0.300/0.325 (7.620/8.255)	0.300/0.325 (7.620/8.255)
E1	0.240/0.280 (6.096/7.112)	0.240/0.280 (6.096/7.112)	0.240/0.280 (6.096/7.112)	0.240/0.280 (6.096/7.112)	0.240/0.280 (6.096/7.112)	0.240/0.280 (6.096/7.112)
L	0.115/0.150 (2.921/3.810)	0.115/0.150 (2.921/3.810)	0.115/0.150 (2.921/3.810)	0.115/0.150 (2.921/3.810)	0.115/0.150 (2.921/3.810)	0.115/0.150 (2.921/3.810)
Ø	0°/15° (0°/15°)	0°/15° (0°/15°)	0°/15° (0°/15°)	0°/15° (0°/15°)	0°/15° (0°/15°)	0°/15° (0°/15°)

**PACKAGE: PLASTIC  
 DUAL-IN-LINE  
 (NARROW)**



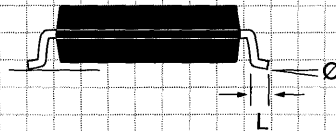
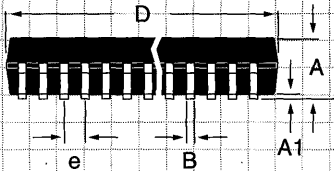
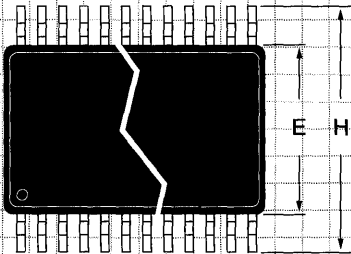
DIMENSIONS (Inches) Minimum/Maximum (mm)	24-PIN	28-PIN			
A2	0.115/0.195 (2.921/4.953)	0.115/0.195 (2.921/4.953)			
B	0.014/0.022 (0.356/0.559)	0.014/0.022 (0.356/0.559)			
B1	0.045/0.070 (1.143/1.778)	0.045/0.070 (1.143/1.778)			
C	0.008/0.014 (0.203/0.356)	0.008/0.014 (0.203/0.356)			
D	1.230/1.280 (31.24/32.51)	1.385/1.405 (35.179/35.687)			
E	0.300/0.325 (7.620/8.255)	0.300/0.325 (7.620/8.255)			
E1	0.240/0.280 (6.096/7.112)	0.240/0.280 (6.096/7.112)			
L	0.115/0.150 (2.921/3.810)	0.115/0.150 (2.921/3.810)			
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**PACKAGE: PLASTIC  
DUAL-IN-LINE  
(WIDE)**



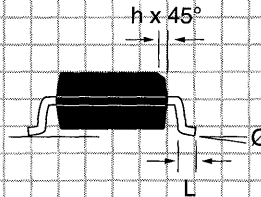
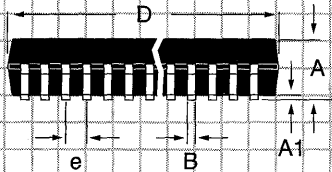
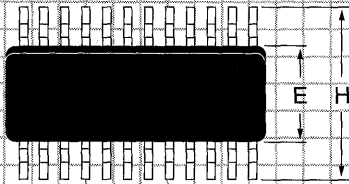
DIMENSIONS (Inches) Minimum/Maximum (mm)	24-PIN	28-PIN	40-PIN	48-PIN		
A2	0.125/0.195 (3.175/4.953)	0.125/0.195 (3.175/4.953)	0.125/0.195 (3.175/4.953)	0.125/0.195 (3.175/4.953)		
B	0.014/0.022 (0.366/0.559)	0.014/0.022 (0.366/0.559)	0.014/0.022 (0.366/0.559)	0.014/0.022 (0.366/0.559)		
B1	0.030/0.070 (0.762/1.778)	0.030/0.070 (0.762/1.778)	0.030/0.070 (0.762/1.778)	0.030/0.070 (0.762/1.778)		
C	0.008/0.015 (0.203/0.381)	0.008/0.015 (0.203/0.381)	0.008/0.015 (0.203/0.381)	0.008/0.015 (0.203/0.381)		
D	1.150/1.290 (29.21/32.76)	1.380/1.565 (35.05/39.75)	1.980/2.095 (50.29/53.21)	2.385/2.480 (60.57/62.99)		
E	0.600/0.625 (15.24/15.87)	0.600/0.625 (15.24/15.87)	0.600/0.625 (15.24/15.87)	0.600/0.625 (15.24/15.87)		
E1	0.485/0.580 (12.31/14.73)	0.485/0.580 (12.31/14.73)	0.485/0.580 (12.31/14.73)	0.485/0.580 (12.31/14.73)		
L	0.115/0.200 (2.921/5.080)	0.115/0.200 (2.921/5.080)	0.115/0.200 (2.921/5.080)	0.115/0.200 (2.921/5.080)		
$\emptyset$	0°/15° (0°/15°)	0°/15° (0°/15°)	0°/15° (0°/15°)	0°/15° (0°/15°)		

**PACKAGE: PLASTIC SHRINK  
 SMALL OUTLINE  
 (SSOP)**



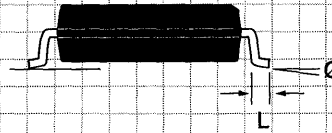
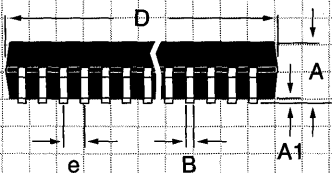
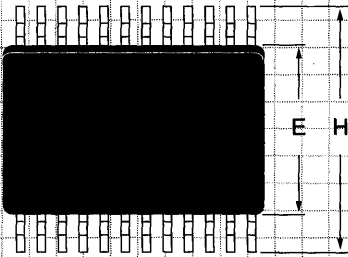
DIMENSIONS (Inches) Minimum/Maximum (mm)	24-PIN	28-PIN				
A	0.068/0.078 (1.73/1.99)	0.068/0.078 (1.73/1.99)				
A1	0.002/0.008 (0.05/0.21)	0.002/0.008 (0.05/0.21)				
B	0.010/0.015 (0.25/0.38)	0.010/0.015 (0.25/0.38)				
D	0.317/0.328 (8.07/8.33)	0.397/0.407 (10.07/10.33)				
E	0.205/0.212 (5.20/5.38)	0.205/0.212 (5.20/5.38)				
e	0.0256 BSC (0.65 BSC)	0.0256 BSC (0.65 BSC)				
H	0.301/0.311 (7.65/7.90)	0.301/0.311 (7.65/7.90)				
L	0.022/0.037 (0.55/0.95)	0.022/0.037 (0.55/0.95)				
Ø	0°/8° (0°/8°)	0°/8° (0°/8°)				

**PACKAGE: PLASTIC  
 SMALL OUTLINE (SOIC)  
 (NARROW)**



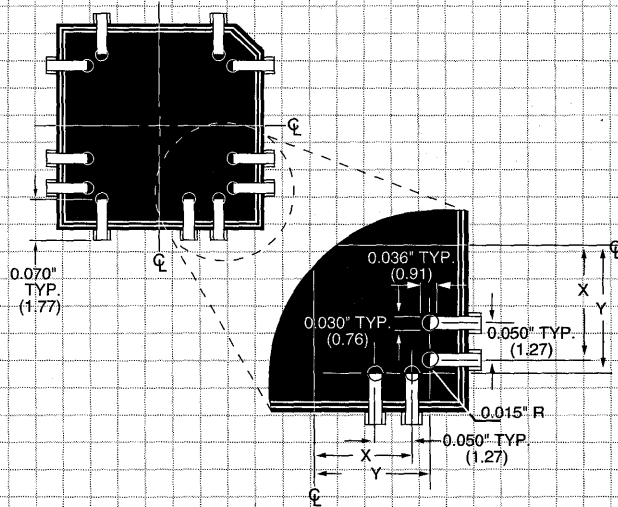
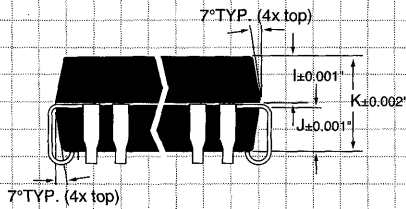
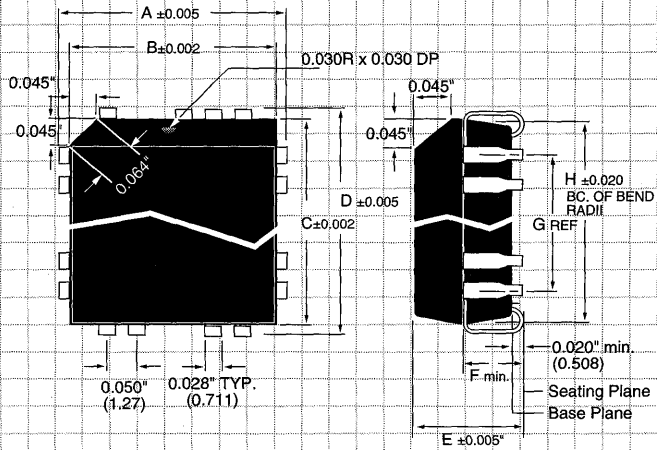
DIMENSIONS (Inches) Minimum/Maximum (mm)	8-PIN	14-PIN	16-PIN			
A	0.053/0.069 (1.346/1.748)	0.053/0.069 (1.346/1.748)	0.053/0.069 (1.346/1.748)			
A1	0.004/0.010 (0.102/0.249)	0.004/0.010 (0.102/0.249)	0.004/0.010 (0.102/0.249)			
B	0.014/0.019 (0.35/0.49)	0.013/0.020 (0.330/0.508)	0.013/0.020 (0.330/0.508)			
D	0.189/0.197 (4.80/5.00)	0.337/0.344 (8.552/8.748)	0.386/0.394 (9.802/10.000)			
E	0.150/0.157 (3.802/3.988)	0.150/0.157 (3.802/3.988)	0.150/0.157 (3.802/3.988)			
e	0.050 BSC (1.270 BSC)	0.050 BSC (1.270 BSC)	0.050 BSC (1.270 BSC)			
H	0.228/0.244 (5.801/6.198)	0.228/0.244 (5.801/6.198)	0.228/0.244 (5.801/6.198)			
h	0.010/0.020 (0.254/0.498)	0.010/0.020 (0.254/0.498)	0.010/0.020 (0.254/0.498)			
L	0.016/0.050 (0.406/1.270)	0.016/0.050 (0.406/1.270)	0.016/0.050 (0.406/1.270)			
Ø	0°/8° (0°/8°)	0°/8° (0°/8°)	0°/8° (0°/8°)			

**PACKAGE: PLASTIC  
 SMALL OUTLINE (SOIC)  
 (WIDE)**



DIMENSIONS (Inches) Minimum/Maximum (mm)	14-PIN	16-PIN	18-PIN	20-PIN	24-PIN	28-PIN
A	0.093/0.104 (2.352/2.649)	0.093/0.104 (2.352/2.649)	0.093/0.104 (2.352/2.649)	0.093/0.104 (2.352/2.649)	0.093/0.104 (2.352/2.649)	0.093/0.104 (2.352/2.649)
A1	0.004/0.012 (0.102/0.300)	0.004/0.012 (0.102/0.300)	0.004/0.012 (0.102/0.300)	0.004/0.012 (0.102/0.300)	0.004/0.012 (0.102/0.300)	0.004/0.012 (0.102/0.300)
B	0.013/0.020 (0.330/0.508)	0.013/0.020 (0.330/0.508)	0.013/0.020 (0.330/0.508)	0.013/0.020 (0.330/0.508)	0.013/0.020 (0.330/0.508)	0.013/0.020 (0.330/0.508)
D	0.348/0.363 (8.83/9.22)	0.398/0.413 (10.10/10.49)	0.447/0.463 (11.35/11.74)	0.496/0.512 (12.60/13.00)	0.599/0.614 (15.20/15.59)	0.697/0.713 (17.70/18.09)
E	0.291/0.299 (7.402/7.600)	0.291/0.299 (7.402/7.600)	0.291/0.299 (7.402/7.600)	0.291/0.299 (7.402/7.600)	0.291/0.299 (7.402/7.600)	0.291/0.299 (7.402/7.600)
e	0.050 BSC (1.270 BSC)	0.050 BSC (1.270 BSC)	0.050 BSC (1.270 BSC)	0.050 BSC (1.270 BSC)	0.050 BSC (1.270 BSC)	0.050 BSC (1.270 BSC)
H	0.394/0.419 (10.00/10.64)	0.394/0.419 (10.00/10.64)	0.394/0.419 (10.00/10.64)	0.394/0.419 (10.00/10.64)	0.394/0.419 (10.00/10.64)	0.394/0.419 (10.00/10.64)
L	0.016/0.050 (0.406/1.270)	0.016/0.050 (0.406/1.270)	0.016/0.050 (0.406/1.270)	0.016/0.050 (0.406/1.270)	0.016/0.050 (0.406/1.270)	0.016/0.050 (0.406/1.270)
Ø	0°/8° (0°/8°)	0°/8° (0°/8°)	0°/8° (0°/8°)	0°/8° (0°/8°)	0°/8° (0°/8°)	0°/8° (0°/8°)

## PACKAGE: PLASTIC LEADLESS CHIP CARRIER (PLCC)

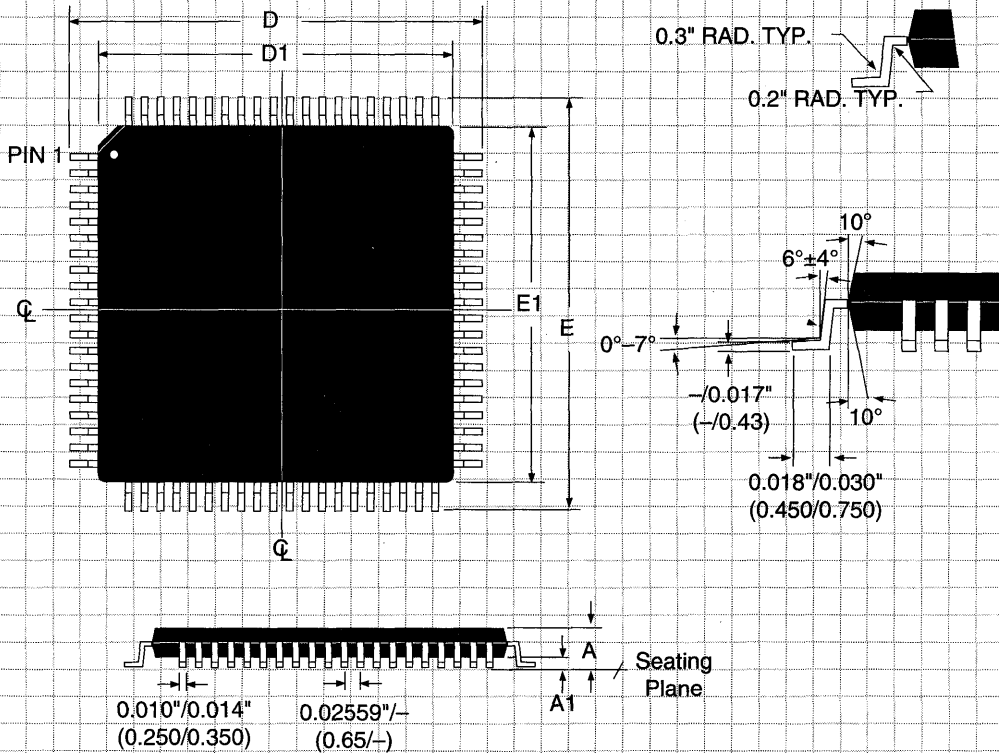




**PACKAGE: PLASTIC  
 LEADLESS CHIP  
 CARRIER (PLCC)**

DIMENSIONS (Inches) Minimum/Maximum (mm)	20-PIN	28-PIN	44-PIN	68-PIN	84-PIN
A	0.385/0.395 (9.77/10.03)	0.485/0.495 (12.31/12.57)	0.685/0.695 (17.39/17.65)	0.985/0.995 (25.02/25.27)	1.185/1.195 (30.09/30.35)
B	0.350/0.355 (8.89/9.017)	0.452/0.456 (11.48/11.58)	0.652/0.656 (16.56/16.61)	0.952/0.956 (24.18/24.28)	1.152/1.156 (29.26/29.36)
C	0.350/0.355 (8.89/9.017)	0.452/0.456 (11.48/11.58)	0.652/0.656 (16.56/16.61)	0.952/0.956 (24.18/24.28)	1.152/1.156 (29.26/29.36)
D	0.385/0.395 (9.77/10.03)	0.485/0.495 (12.31/12.57)	0.685/0.695 (17.39/17.65)	0.985/0.995 (25.02/25.27))	1.185/1.195 (30.09/30.35)
E	0.170/0.180 (4.32/4.57)	0.170/0.180 (4.32/4.57)	0.170/0.180 (4.32/4.57)	0.170/0.180 (4.32/4.57)	0.170/0.180 (4.32/4.57)
F	0.098/- (2.48/-)	0.098/- (2.48/-)	0.098/- (2.48/-)	0.098/- (2.48/-)	0.098/- (2.48/-)
G	0.200 REF (5.08 REF)	0.300 REF (7.62 REF)	0.500 REF (12.7 REF)	0.800 REF (20.32 REF)	1.000 REF (25.44 REF)
H	0.290/0.330 (7.36/8.38)	0.390/0.430 (9.906/10.922)	0.590/0.630 (14.98/16.00)	0.890/0.930 (22.60/23.62)	1.090/1.130 (27.69/28.70)
I	0.065/0.070 (1.65/1.77)	0.070/0.072 (1.77/1.83)	0.070/0.072 (1.77/1.83)	0.070/0.072 (1.77/1.83)	0.070/0.072 (1.77/1.83)
J	0.08/- (2.03/-)	0.070/0.072 (1.77/1.82)	0.070/0.072 (1.77/1.82)	0.070/0.072 (1.77/1.83)	0.070/0.072 (1.77/1.82)
K	0.145/0.156 (3.68/3.96)	0.148/0.152 (3.75/3.86)	0.148/0.152 (3.75/3.86)	0.148/0.152 (3.75/3.86)	0.148/0.152 (3.75/3.86)
X	0.100 REF (2.54 REF)	0.150 REF (3.810 REF)	0.250 REF (6.35 REF)	0.400 REF (10.16 REF)	0.500 REF (12.7 REF)
Y	0.140/0.147 (3.50/3.733)	0.180 REF (4.572 REF)	0.280 REF (7.11 REF)	0.430 REF (10.92 REF)	0.530 REF (13.46 REF)

## PACKAGE: QUAD FLATPACK



DIMENSIONS (Inches) Minimum/Maximum (mm)	80-PIN
A	-0.096 (-2.450)
A1	-0.010 (-0.250)
D	0.620/0.640 (15.750/16.250)
D1	0.547/0.555 (13.900/14.100)
E	0.620/0.640 (15.750/16.250)
E1	0.547/0.555 (13.900/14.100)

**APPENDIX CONTENTS**

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## SIPEX DATA CONVERSION PRODUCTS LISTING

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For information on any of the following SIPEX Data Conversion Products, please contact the SIPEX Literature Department at (508) 667-8700.

Model	Description
<b>Analog-to-Digital Converters</b>	
HS574A ...	12-Bit, 25 $\mu$ s
SP674A ...	12-Bit, 15 $\mu$ s
<b>Sampling Analog-to-Digital Converters</b>	
SP574B ...	12-Bit, 25 $\mu$ s; 20kHz Nyquist Frequency
SP674B ...	12-Bit, 15 $\mu$ s; 33kHz Nyquist Frequency
SP774B ...	12-Bit, 8 $\mu$ s; 62.5kHz Nyquist Frequency
SP1674B ...	12-Bit, 10 $\mu$ s; 50kHz Nyquist Frequency
SP7800A ...	12-Bit, 3 $\mu$ s; Single +5V Supply
SP8503 ...	12-Bit, 3 $\mu$ s; Bipolar Input
SP8505 ...	12-Bit, 5 $\mu$ s; Bipolar Input
SP8510 ...	12-Bit, 10 $\mu$ s; Bipolar Input
<b>NEW</b> SP8530 ...	12-Bit, 7.75 $\mu$ s, Simultaneous Sampling, Single +5V Supply, Serial Output
<b>NEW</b> SP8531 ...	12-Bit, 3.75 $\mu$ s, Single +5V Supply, Serial Output
SP8603 ...	12-Bit, 3 $\mu$ s; Unipolar Input
SP8605 ...	12-Bit, 5 $\mu$ s; Unipolar Input
SP8610 ...	12-Bit, 10 $\mu$ s; Unipolar Input
<b>Digital-to-Analog Converters</b>	
HS3120 ...	12-Bit, 2 $\mu$ s, Latched, 4-Quadrant Multiplying, Current Output
HS3140 ...	14-Bit, 2 $\mu$ s, 4-Quadrant Multiplying, Current Output
HS3160 ...	16-Bit, 2 $\mu$ s, 4-Quadrant Multiplying, Current Output
SP7512 ...	12-Bit, 2 $\mu$ s, Double-Buffered, 4-Quadrant Multiplying, Current Output
SP7514 ...	14-Bit, 2 $\mu$ s, 4-Quadrant Multiplying, Current Output
SP7516 ...	16-Bit, 2 $\mu$ s, 4-Quadrant Multiplying, Current Output
HS7541A ...	12-Bit, 2 $\mu$ s, 4-Quadrant Multiplying, Current Output
SP7545 ...	12-Bit, 2 $\mu$ s, Buffered, 4-Quadrant Multiplying, Current Output
HS7584 ...	12-Bit, 2 $\mu$ s, Quad, Double-Buffered, 4-Quadrant Multiplying, Current Output with Independent Reference Inputs
SP9316 ...	16-Bit, 2 $\mu$ s, Latched, 4-Quadrant Multiplying, Current Output
<b>NEW</b> SP9500 ...	12-Bit, 7.5 $\mu$ s, Single +5V Supply, 2 Quadrant Multiplying, Serial Input, Voltage Output
SP9501 ...	12-Bit, 4 $\mu$ s, 4-Quadrant Multiplying, Voltage Output
SP9502 ...	12-Bit, 4 $\mu$ s, Dual, 4-Quadrant Multiplying, Voltage Output
SP9504 ...	12-Bit, 4 $\mu$ s, Quad, 4-Quadrant Multiplying, Voltage Output, Extended Temperature Range
<b>NEW</b> SP9600 ...	12-Bit, 20 $\mu$ s, Low Power, +5V Supply, 2 Quadrant Multiplying, Serial Input, Voltage Output
SP9601 ...	12-Bit, 30 $\mu$ s, Low-Power; 4-Quadrant Multiplying, Voltage Output
SP9602 ...	12-Bit, 30 $\mu$ s, Low-Power; Dual, 4-Quadrant Multiplying, Voltage Output
SP9604 ...	12-Bit, 30 $\mu$ s, Low-Power; Quad, 4-Quadrant Multiplying, Voltage Output
SP9840 ...	8-Bit, 0.7 $\mu$ s; Octal, Multiplying, Voltage Output with 3-Wire Serial Interface and 8 Independent Reference Inputs
SP9841 ...	8-Bit, 0.7 $\mu$ s; Octal, 2-Quadrant Multiplying, Voltage Output with 8 Independent Reference Inputs
SP9842 ...	8-Bit, 0.7 $\mu$ s; Octal, Multiplying, Voltage Output with 4 pair of Reference Inputs
SP9843 ...	8-Bit, 0.7 $\mu$ s; Octal, Multiplying, Voltage Output with 3-Wire Serial Interface and 4 Pair Reference Inputs

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## SIPEX DATA CONVERSION PRODUCTS LISTING

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For information on any of the following SIPEX Data Conversion Products, please contact the SIPEX Literature Department at (508) 667-8700.

### Data Acquisition Systems

- SP8120 .... 8-Channel, 12-Bit, 100KHz, Parallel Out, Monolithic DAS
- SP8121 .... 8-Channel, 12-Bit, 100KHz, Parallel Out, Monolithic DAS7
- SP8480 .... 8-Channel, 12-Bit, 100KHz, 8/4 Nibble Out, Monolithic DAS
- SP8481 .... 8-Channel, 12-Bit, 100KHz, Latched MUX, Nibble Out, Monolithic DAS
- NEW** SP8542 .... 2-Channel, 12-Bit, 235KHz, Single +5V Supply, Serial I/O
- NEW** SP8544 .... 4-Channel, 12-Bit, 235KHz, Single +5V Supply, Serial I/O

## **SIPEX... EXCELLENCE IN SIGNAL PROCESSING**

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**Sipex Corporation** designs and manufactures Analog Signal Processing Circuits. Utilizing a broad range of technologies including CMOS, Bipolar and BiCMOS, **Sipex** has developed a wide range of monolithic products. **Sipex's** Standard Products are focused primarily in two areas: Data Converters and Interface Circuits. The Interface Circuits consist of industry standard as well as proprietary products. Data Converter products cover a full range of D/A's, A/D's, and DAS' with primary focus on high speed, high resolution circuits. In addition to **Sipex's** broad standard product offering, the company designs and manufactures custom circuits for unique signal processing needs.

This catalog introduces new **Sipex** Interface Products and is considered a supplement to our full line Interface Products Catalog. If you would like our full line Interface Products Catalog or our Data Conversion Products catalog, please contact the **Sipex** Literature Department at 508-667-8700.

### **SIPEX INTERFACE PRODUCTS:**

#### **Single Interface**

**Sipex** has been serving the +5V Only RS-232 market since 1988. This product line does represent our core product offering and is enhanced and improved as needed to keep pace with the rigorous requirements of industry. In 1993 **Sipex** released the first product in a family of RS-485 transceivers. The SP485 which is a half duplex RS-485 transceiver was the first in a series of RS-485 transceivers.

#### **Multi-Mode Interface**

**Sipex** entered the multimode serial interface market with the industry's first programmable RS-232/422 transceiver in 1990. Based on this technology the 300 series was expanded to support RS-232, RS-422, and AppleTalk™. Single-chip transceivers supporting two interface modes gave us the entree into our newest series — the 500 series supports up to eleven (11) programmable interface standards integrated into easy to use, space saving, single chip solutions.

Whether it's our multimode transceivers or one of our many single interface products, **Sipex** is delivering affordable, reliable solutions to the market today.

#### **RELIABILITY**

Quality and reliability have long been inherent to our company. While the majority of our sales today are to Industrial customers, our roots were in the military markets, including demanding space applications.

The disciplines required to successfully service these markets have been carried into all **Sipex's** products. Quality has always been a 'way of life' at **Sipex**. Outgoing quality levels of our monolithic products are better than 200ppm with our more mature products better than 100ppm. We are proud of our outgoing quality level and are continually striving to improve upon it.

### **Ordering Information**

**North America:** Orders may be placed through our North American Sales office located at 22 Linnell Circle, Billerica, MA 01821 USA by telephone at 508-667-8700 or by fax at 508-670-9001. Product information may be obtained, and orders placed through **Sipex's** representatives or distributors whose addresses and telephone numbers are listed in this catalog.

**International:** Customers outside North America are served by **Sipex** direct sales offices in France, Germany and Japan. **Sipex** is also represented throughout the world by international representatives and distributors whose offices are listed in this catalog.

### **Terms and Conditions of Sale**

Prices and delivery information of any item in this catalog is available from our sales representatives or direct from the Company. Quotations are F.O.B. factory of origin, and are subject to change without notice. On all orders, payment is net 30 days following date of shipment.

### **Applications Engineering**

**Sipex** maintains a support staff of technical sales engineers, both domestically and internationally, who are expert in specific areas of analog, digital, and microelectronics technology. Staff engineers provide further technical support, as needed, on advanced circuit designs or application problems.

### **Shipping Instruments**

Shipping will be via United Parcel Service or Parcel Post unless other instructions are indicated. For rush service, we will ship by Air Freight, Air Express or Air Parcel Post on request.

### **Warranty**

**Sipex** warrants its products to be free from defects in material and workmanship for a period of one year from the date of shipment. This warranty shall not apply to any product which has been abused or misused physically or electrically or whose leads have been clipped or soldered. **Sipex's** sole liability and the Purchaser's sole remedy under this warranty is limited to repairing or replacing defective components. **Sipex** shall not be liable for consequential damages under any circumstances.

### **Returns**

When returning material for repair or replacement, it is necessary first to contact Customer Service. Upon acceptance of the request, a return material authorization (RMA#) will be issued. We require a detailed description of the reason for the return; the date and purchase order number on which it was obtained, and the date of receipt.

### **Specifications**

**Sipex** reserves the right to discontinue items and change specifications without notice.

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SIGNAL PROCESSING EXCELLENCE

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