

AA746

MagnetoResistive FreePitch Sensor

The AA746 is an angular sensor based on the Anisotropic MagnetoResistive (AMR) effect. The sensor contains two Wheatstone bridges with common ground (GND) and supply pin ($V_{\rm CO}$). They are shifted at a relative angle of 45° to one another.

A rotating magnetic field in the sensor plane delivers two sinusoidal output signals with the double frequency of the angle α between sensor and magnetic field direction shown in Fig. 1. The function of these signals is $\sin(2\alpha)$ and $\cos(2\alpha)$.

The AA746 is optimized for a low magnetic field strength down to 5 kA/m.

The bond version of AA746 is available as bare die on wafer or waffle pack. For SMD processing, the sensor is available in a LGA-package.



Article description	Package	Delivery Type
AA746ACA-AB	Die on wafer 1)	Waferbox
AA746ACA-AC	Bare die	Waffle pack (324)
AA746AMA-AE	LGA6L	Tape and Reel (2500)

¹⁾ Minimum order quantities apply.

Quick Reference Guide

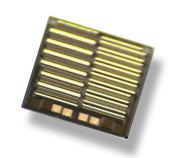
Symbol	Parameter	Min.	Тур.	Max.	Unit
V _{CC}	Supply voltage	-	5.0	-	V
$V_{\rm off}$	Offset voltage per V _{CC}	-0.5	-	+0.5	mV/V
V _{peak}	Signal amplitude per V _{CC}	12.0	13.0	14.0	mV/V
R _s	Sensor resistance	0.45	0.60	0.75	kΩ

Absolute Maximum Ratings

In accordance with the absolute maximum rating system (IEC60134).

Symbol	Parameter	Min.	Max.	Unit
V _{CC}	Supply voltage	-9.0	+9.0	V
T _{amb}	Ambient temperature	-40	+125	°C

Stresses beyond those listed under "Absolute maximum ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.



Features

- Based on the Anisotropic MagnetoResistive (AMR) effect
- Contains two Wheatstone bridges
- Sine and cosine output
- Temperature range from -40 °C to +125 °C

Advantages

- Non-contacting angle measurement
- Large air gap
- Excellent accuracy
- Position tolerant
- Minimal offset voltage
- Negligible hysteresis

Applications

- Incremental or absolute position measurement (linear and rotary motion)
- Motor commutation
- Rotational speed measurement
- Angle measurement (180° absolute on shaft end)







Magnetic Data

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
H _{ext}	Magnetic field strength 1)		5.0	-	-	kA/m

¹⁾ The stimulating magnetic field in the sensor plane necessary to ensure the minimum error as specified in note 7.

Electrical Data

 $T_{amb} = 25 \, ^{\circ}\text{C}$; $H_{avt} = 25 \, \text{kA/m}$; $V_{CC} = 5 \, \text{V}$; unless otherwise specified.

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
V _{CC}	Supply voltage		-	5.0	-	V
$V_{\rm off}$	Offset voltage per V _{CC}	See Fig. 1	-0.5	-	+0.5	mV/V
TC _{Voff}	Temperature coefficient of V _{off} 2)	T _{amb} = (-40+125)°C	-2.0	-	+2.0	(μV/V)/K
V _{peak}	Signal amplitude per V _{CC} 3)	See Fig. 1	12.0	13.0	14.0	mV/V
TC _{Vpeak}	Temperature coefficient of V _{peak} 4)	T _{amb} = (-40+125)°C	-0.36	-0.42	-0.48	%/K
R _s	Sensor resistance 5)		0.45	0.60	0.75	kΩ
R _B	Bridge resistance 6)		0.9	1.2	1.5	kΩ
TC _{RB}	Temperature coefficient of R _B 7)	T _{amb} = (-40+125)°C	0.24	0.28	0.32	%/K

$$^{2)} \quad TC_{\text{Voff}} = \ \frac{V_{\text{off(T2)}} \cdot V_{\text{off(T1)}}}{T_{2} \cdot T_{1}} \quad \text{with } T_{1} = +25 \, ^{\circ}\text{C}; \ T_{2} = +125 \, ^{\circ}\text{C}.$$

 $^{3)}$ Maximal output voltage without offset influences. Periodicity of V $_{\text{peak}}$ is $\text{sin}(2\alpha)$ and $\text{cos}(2\alpha)$.

4)
$$TC_{Vpeak} = 100 \cdot \frac{V_{peak(T1)} - V_{peak(T1)}}{V_{peak(T1)} \cdot (T_2 - T_1)}$$
 with $T_1 = +25 \text{ °C}$; $T_2 = +125 \text{ °C}$.

- ⁵⁾ Sensor resistance between pads 1 and 2 (bare die); pads 3 and 4 (LGA6L).
- ⁶⁾ Bridge resistance between pads 3 and 4, 5 and 6 (bare die); pads 1 and 5, 2 and 6 (LGA6L).

$$^{7)} \quad TC_{RB} = 100 \cdot \frac{R_{B(T2)} - R_{B(T1)}}{R_{B(T1)} \cdot (T_2 - T_1)} \quad \text{with } T_1 = +25 \, ^{\circ}C; \, T_2 = +125 \, ^{\circ}C.$$

Accuracy

 $T_{amb} = 25$ °C; $H_{ext} = 5$ kA/m; $V_{CC} = 5$ V; unless otherwise specified.

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
Δα	Angular error ⁸⁾		-	±0.25	±0.5	deg
k	Amplitude synchronism 9)		-0.5	0	+0.5	% of V _{peak}

 $_{\alpha}$ = $|\alpha_{_{real}}$ - $\alpha_{_{measured}}$ without offset influences due to deviations from ideal sinusoidal characteristics.

9)
$$k = 100 - 100 \cdot \frac{V_{peak1}}{V_{peak2}}$$
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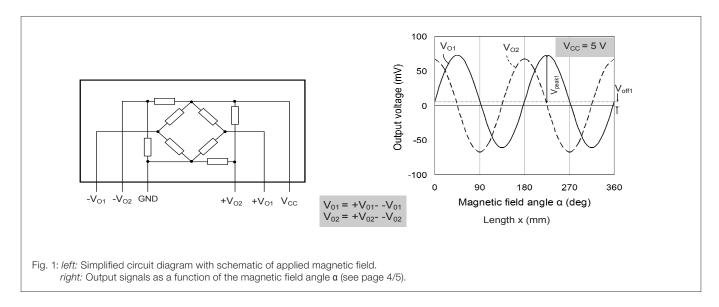
Dynamic Data

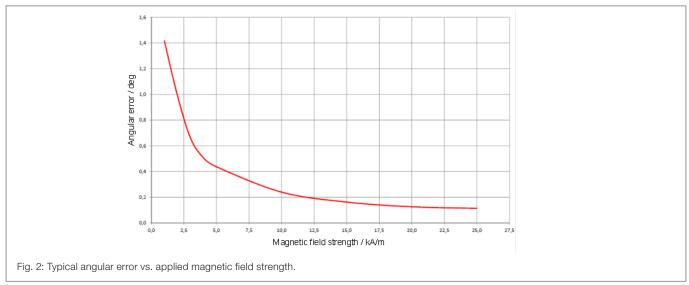
Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
ω	Angular velocity of the magnetic field 10)		1	-	-	MHz

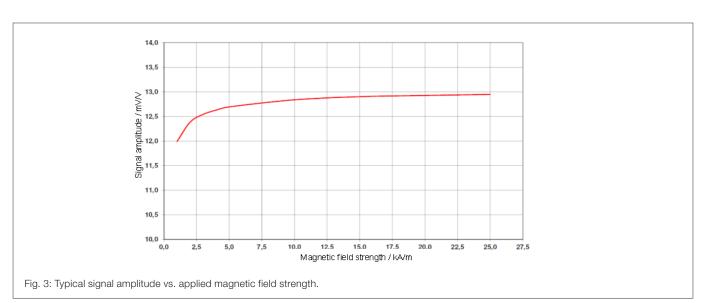
No significant amplitude attenuation.



General Data





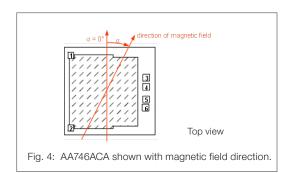




AA746ACA as Bare Die

Pinning

Pin	Symbol	Parameter
1	V _{cc}	Supply voltage
2	GND	Ground
3	+V ₀₂	Positive output voltage bridge 2
4	-V _{O2}	Negative output voltage bridge 2
5	+V _{O1}	Positive output voltage bridge 1
6	-V _{O1}	Negative output voltage bridge 1



Dimensions

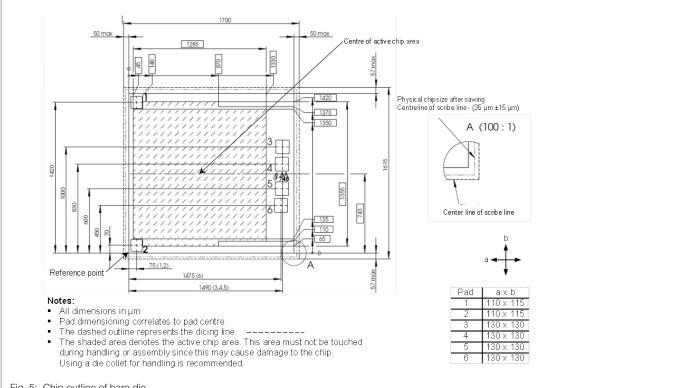


Fig. 5: Chip outline of bare die.

Data for Packaging and Interconnection Technologies

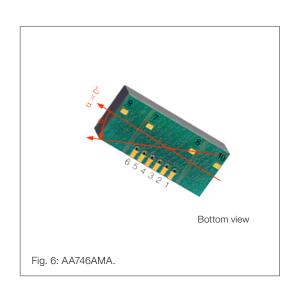
Parameter	Value	Unit
Chip area	1.7 x 1.6	mm
Chip thickness	525 ± 10	μm
Pad diameter (all)	See Fig. 5	μm
Pad thickness	0.8	μm
Pad material	AlCu	-



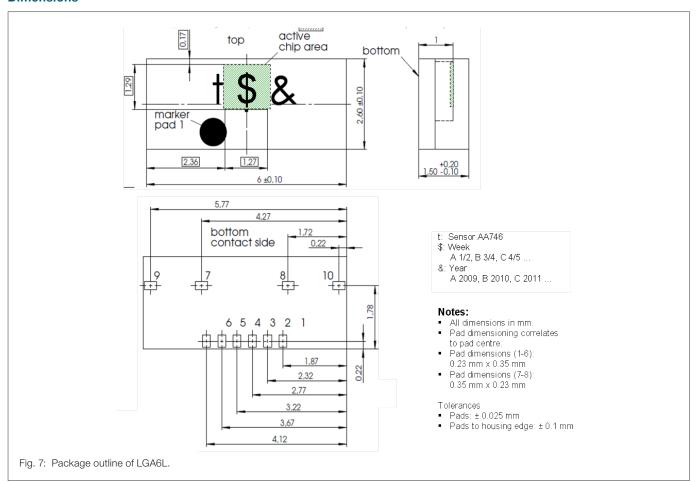
AA746AMA in LGA6L Housing

Pinning

	9	
Pin	Symbol	Parameter
1	+V _{O1}	Positive output voltage bridge 1
2	+V _{O2}	Positive output voltage bridge 2
3	GND	Ground
4	V _{cc}	Supply voltage
5	-V _{O1}	Negative output voltage bridge 1
6	-V _{O2}	Negative output voltage bridge 2
7	n.c.	Not connected
8	n.c.	Not connected
9	n.c.	Not connected
10	n.c.	Not connected



Dimensions





General Information

Product Status

Article	Status
AA746ACA-AB	The product is in series production.
AA746ACA-AC	The product is in series production.
AA746AMA-AE	The product is in series production.
Note	The status of the product may have changed since this data sheet was published. The latest information is available on the internet at www.sensitec.com.

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