# HIGH VELOCITY IMPLANTING OF ANCHORS

BY CARL T. ZOVKO

RESEARCH AND TECHNOLOGY DEPARTMENT

1 JULY 1984

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SECURITY CLASSIFICATION OF THIS PAGE (When Date Entered)

REPORT DCCUMENTATION PAGE	READ INSTRUCTIONS BEFORE COMPLETING FORM					
NSWC TR 84-214  AD: A 1586	3. RECIPIENT'S CATALOG NUMBER					
4 TITLE (and Subtitle)	5. Th . OF REPORT & PERIOD COVERED					
HIGH VELOCITY IMPLANTING OF ANCHORS	   Final					
	6. PERFORMING ORG. REPORT NUMBER					
7. AUTHOR(s)	8. CONTRACT OR GRANT NUMBER(#)					
Carl T. Zovko						
9. PERFORMING ORGANIZATION NAME AND ACCRESS	10. PROGRAM ELEMENT, PROJECT, TASK AREA & WORK UNIT NUMBERS					
Naval Surface Weapons Center (Code R12)						
White Oak Laboratory Silver Spring, Maryland 20910						
11. CONTROLLING OFFICE NAME AND ADDRESS	12. REPORT DATE					
	1 July 1984					
	93					
14 MONITORING AGENCY NAME & ADDRESS(If different from Controlling Office)	15. SECURITY CLASS. (of this report)					
	UNCLASSIFIED					
	15a. DECLASSIFICATION/ DOWNGRADING SCHEDULE					
18. DISTRIBUTION STATEMENT (of this Report)	1					
l deserved for sublic males and district which we will also						
Approved for public release, distribution unlimi	ted.					
Block 40 Hallings In						
17. DISTRIBUTION STATEMENT (of the ebstract entered in Block 20, if different fro	an Nepursy					
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18. SUPPLEMENTARY NOTES						
19. KEY WORDS (Continue on reverse side if necessary and identify by block number	1					
Anchors Rockets						
Propellant Emplaced Anchors Recoilless						
20. ABSTRACT (Continue on reverse side if necessary and identify by block number)						
This report is a summary of a theoretical investig	ation of three ways to avoid					
the severe problems caused by recoil in the implanting of Propellant Emplaced Anchors (PEA's). It was specifically requested that a launching system						
modeled after a recoilless rifle be evaluated. While doing this, the						
conclusion was reached that the recoilless rifle approach was more complicated than necessary, and that the desired performance could be achieved more easily						
by a direct rocket. The sponsors had suggested a water jet approach using cold						
high pressure gas to supply the energy, instead of	propellant gas. This turned					

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out to be impractical using the compressed air, but it became very practical using propellant gases.

All of the systems were analyzed and simulated by computer models. All three systems appear reasonable and they all solve the recoil problem. However, the recoilless and the direct rocket have a common problem. Their requirement of a rocket motor with very high thrust (1.6 million pounds) and a very short burning time (40 milliseconds) has no parallel in current rocket technology. Apparent solutions to this problem would require very large structures. In any case, their development promises to be expensive and lengthy. Fortunately, the water jet does not share this problem. Its development should be timely, and costs should be reasonable.

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#### **FOREWORD**

The work on propellant emplaced anchors (PEA) reported here was funded by the Naval Civil Engineering Laboratory (NCEL) under Amphibious and Advanced Base Technology, PE 62760N, Subproject YF 60.536. The purpose of the work covered by this report is to analyze and evaluate three candidate propulsion systems for PEA's to replace the high pressure gun propulsor now used. These alternate propulsion systems all have the capability to propel the PEA's and to eliminate the recoil problems that trouble existing PEA's. All of the propulsion systems are recoilless. All three propulsion systems were analyzed in depth, and the analyses were implemented into computer programs that can simulate their performance. The results from these computer programs, in turn, were used to make estimates of the size and weights of the competing systems. The final selection of the water jet propulsion system was based on size, weight, and anticipated short development time.

Approved by:

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## A. INTRODUCTION

I. THE PROBLEM: Newton's Third Law has been formulated in many ways, but they all have the same meaning--all forces are produced in equal and opposite pairs. The action and reaction are exactly equal in magnitude and exactly opposite in direction. Anyone who has fired a gun or rifle much larger than .22 caliber understands Newton's Third Law. The high pressure gases from the burning propellant act both on the base of the bullet and the base of the gun breech, producing equal forces on both. Since the bullet is free to move, the force drives it down the barrel and out the muzzle. The person firing the gun is not usually free to move very far because he is coupled to the earth (Figure 1). The recoil force is transmitted through the shooter's body to the earth. If the bullet is a .30 caliber with a weight of 150 grains and a muzzle velocity of 3,000 ft/s, the recoil force will change the earth's velocity by  $4.7 \times 10^{-24}$  ft/s. This will move the earth one inch in five trillion centuries. (The reader should not worry about the accumulated effects of shooting on the earth's trajectory, because air friction and the final impact produce equal and opposite forces which exactly counteract the velocity increment of the earth.) If the shooter is suspended free of the earth, his much smaller mass will be accel ated to a speed of four inches per second.

The previous paragraph discussed the cts of a man firing a .30 caliber rifle while standing on the earth and while suspended in the air. The effects are small but different. Larger caliber guns require much larger and stronger supports than a rifleman to keep the gun coupled to the earth. Our problem is greater yet. Propellant Emplaced Anchors (PEAs) comprise a system of large anchors for semipermanent mooring of ships. The anchors are shot into the sea floor to increase their effective lifetimes and their load capacities. There are four load ranges from 10,000 pounds to 300,000 pounds. Depending on their holding capacities and the type of sea floor they are intended for, the anchors' weights range from 160 pounds to 6,800 pounds, and their required velocities range from 360 to 520 ft/s. These are massive "bullets." Projecting the largest of these anchors from a reasonable gun tube requires projective forces (and therefore recoil forces) of over 1.5 million pounds. There is no practical way to tie the PEA gun barrel directly to the

earth during normal use. Therefore, the handling of the large recoil forces generated by PEAs is a significant problem. It is the topic of this report.

It will be necessary to develop a quantitative understanding of the problem before looking at potential solutions. Figure 2 shows the general layout of an unsupported launch tube, propellant charge, and anchor. It also shows the principal forces acting on anchor and launch tube. The net force acting on the anchor and the launcher is:

A-I-1

$$F_i = (P-P_a) A - F_f - 1/2 P A_i C_{di} U_i^2$$

where subscript  $i = designates$  anchor when  $i = 1$  and launch tube when  $i = 2$ 
 $F_i = net$  force (pounds)

 $P = gas$  pressure in launch tube (psf)

 $P_a = ambient$  pressure (psfa)

 $A = cross$ -sectional area of launch tube and piston (sq ft)

 $F_f = friction$  force between anchor piston and launch tube wall (pounds)

 $P_a = amaximum$  cross sectional area of anchor or launch tube (sq ft)

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The instantaneous accelerations of the anchor and launch tube are:

A-I-2 
$$U_i = a_i = F_i/M_i$$
  
where  $U_i = a_i = acceleration$  (ft/s<sup>2</sup>)  
 $M_i = mass$  (including virtual mass) (slugs)

The instantaneous velocities are:

$$U_{i} = \int_{0}^{t} a_{i} dx$$

where t = time (sec)

The distances travelled by the anchor and launch tube are given by:

$$A-I-4 x_i = \int_0^t U_i d\tau$$

where  $x_i$  = the distance traveled by the anchor or the launch tube (ft)

All one must do to compute the trajectories of the anchor and launch tube is to integrate equations A-I-3 and 4 for i=1 and 2 simultaneously until

$$x_1 + x_2 = L$$

where L = the effective length of the launch tube (ft).

One must know the various coefficients and boundary conditions before the equations can be integrated. In addition, the pressure must La known as a function of time and/or the sum  $x_1 + x_2$ . In the detailed calculations the pressure will be given as a differential equation involving pressure, time, and  $x_1 + x_2$ .

For approximate calculations, one may neglect the  $\mathbf{F}_{\mathbf{f}}$  and the fluid dynamic drag. Further, the pressure may be assumed constant because that gives the best performance and because it is nearly achievable. With these simplifications, the final velocity of the anchor is

A-I-6 
$$U_1 \text{ final} = \sqrt{\frac{2(P-P_a)AL}{M_1} \frac{M_2}{M_1 + M_2}}$$

The first term in the radical on the right-hand side of Equation A-I-6 is the square of the final anchor velocity that would result if the launcher were firmly attached to a very large, effectively infinite, mass. The second term on the right-hand side is a correction term for the case where the launcher is attached to a finite mass. The product of these two terms is the final anchor velocity when the mass of the launch tube is significant and free to move.

The correction term is always less than one. It increases as  $\rm M_2$  increases relative to  $\rm M_1$ . Equation A-I-6 shows that  $\rm U_1$  final can be increased by increasing P. A. L. and/or  $\rm M_2$  and/or by decreasing  $\rm M_1$ .

- II. CURRENT PEA DESIGNS: To increase the effective mass of the launcher without increasing its physical mass, the original designers added reaction vessels to increase the virtual mass of the launcher. Virtual mass is the mass of the water that gots accelerated along with an object. The virtual mass is added to the physical mass of the object being accelerated, but only while it is being accelerated. The quantity of the virtual mass is proportional to the maximum cross-sectional area of the object, taken perpendicular to the direction of acceleration. The proportionality constant is determined by the shape of the object. Figure 3 shows the present PEA design and how the virtual mass is increased by adding the reaction vessels. This is a good shape for increasing the virtual mass as well as increasing the drag. While this design achieves the required anchor velocity, it is large, heavy, and awkward. Furthermore, the reaction vessels on the larger anchor launchers occasionally break. The rest of this paper is a description, analysis, and evaluation of several new concepts for launchers that do not need reaction vessels.
- III. PROPOSED NEW APPROACHES TO LAUNCHER MASS REDUCTION: While the solutions developed in this paper also apply to the smaller PEAs, the main emphasis is placed on the 300 KIP PEA because of its size, weight, and handling problems. The purpose of these new approaches is to accelerate the anchor to the required velocity without making the launcher large, heavy, awkward, or prone to failure. All of the new approaches have one feature in common. Instead of reducing the effect of the recoil force by adding mass to the launcher, they all neutralize the recoil force with another source of thrust.

The three basic options are shown in Figure 4. The first option is the archetype for the rest. It is a scaled-up recoilless rifle with the anchor as a projectile. Conceptually, it is a PEA with an enlarged gas generator and a rocket nozzle venting to the rear. The thrust from the rocket nozzle can be tailored to exactly neutralize the recoil force. This makes  $M_2$  effectively infinite. Since there is no recoil displacement to reduce the efficiency of

the launcher, the pressure may be reduced. This, in turn, allows the launch tube to be thinner and lighter. On the negative side is the need for a much larger and more expensive gas generator.

The second option is derived from the first by the observation that the rocket thrust required to overcome the recoil force is exactly equal to that required to propel the anchor. Therefore, why not eliminate the launch tube and propel the anchor directly by the rocket's thrust? The launch tube is eliminated completely. There are other less obvious advantages to this option. The thrust duration is not limited by the length of a launch tube, because there is no launch tube. The thrust duration is only limited by the standoff, distance between the sea floor, and the launch position. The rocket thrust can be reduced because the required thrust is inversely proportional to this standoff distance. The principal disadvantage is that the mass of the rocket motor must be added to M<sub>1</sub>, the mass of the anchor. This requires an even larger and more expensive vented gas gene ator than that required for the recoilless launcher.

The third option is similar to the first in overall concept. Instead of using an ordinary rocket which vents the propellant gas, this concept uses a water jet. Gas from a gas generator forces water out the nozzle. The principal advantage of the water jet is a smaller (by half), simpler, and unvented gas generator. An unvented gas generator avoids all of the problems of the large vented gas generators.

# B. RECOILLESS OPTION

While all of the options considered in this report are effectively recoilless, the term will be reserved for the combination of a launch tube with a rocket which neutralizes the recoil force. The recoilless option is a direct copy of the recoilless rifle first used extensively in the Korean War. This original recoilless rifle eliminates the need for heavy gun mounts by eliminating the recoil. "his permits light artillery to be fired from light tripod mounts. These light tripods are required only to support the weight of the gun and to facilitate aiming; they do not have to absorb any recoil forces.

# I. RECOILLESS RIFLE TECHNOLOGY APPLIED TO PEAS

As shown in Figure 4, a recoilless anchor launcher has a single combustion chamber which produces gas to drive the anchor via the piston and to power the rocket. The piston area and the nozzle throat area are preset so that the two forces acting on the launch tube are equal and opposite, thus keeping the launcher stationary. As before, the force accelerating the anchor is:

B-I-1 
$$F_1 = (P - P_a) A - F_f - \frac{1}{2} \mu A_1 C_{d1} U_1^2$$

The recoil force is:

$$F_2 = (P - P_a) A - F_f$$

The thrust from the rocket must equal  ${\rm F_2}$  if the launcher is to be kept stationary. The rocket thrust,  ${\rm F_3}$ , is:

B-I-3 
$$F_3 = P A_t C_f$$
where 
$$A_t = \text{throat area of the nozzle (sq ft)}$$

$$C_f = \text{thrust coefficient (dimensionless)}$$

Equating equations B-I-2 and 3, and solving for  $\boldsymbol{A}_{t}$  gives:

$$B-I-4 A_t = \frac{A (P-Pa)-F_f}{C_f P}$$

 $P_a$  is small with respect to  $P_t$  and  $F_f$  is fairly small. Therefore,  $A_t$  can be estimated by:

$$B-I-5$$
  $A_t = \frac{A}{C_f}$ 

The net force on the launch tube for the recoilless option is:

$$F_{2T} = (P - P_a) A - F_f - P A_t C_f - \frac{1}{2}P A_2 C_{D2} U_2^2$$

To do a detailed calculation of the performance expected from any given set of parameters, one must substitute equations B-I-I and G into equations A-I-2 and integrate as in equations A-I-3 and G to the boundary condition expressed in equation A-I-5. To do this one needs an equation (algebraic or differential) for P.

If one assumes that P is constant and  $F_{2T}$  is nearly zero, then the equations can be solved analytically. The general equations for the anchor velocity and displacement are:

$$\begin{array}{lll} \text{B-I-7} & \text{U}_1 = & \text{U}_{1\infty} \tanh(t/\tau) & \text{and} \\ \\ \text{B-I-8} & \text{x}_1 = & \text{U}_{1\omega} \tau \log_e(\cosh(t/\tau)). \\ \\ \text{where} & \text{U}_{1\omega} = & \text{terminal velocity of the anchor if the driving force} \\ & & \text{were maintained indefinitely.} & \text{When U}_1 \text{ equ} & \text{U}_1^{\infty} \\ & & & \text{then F}_1 \text{ in equation B-I-1} = 0. \end{array}$$

$$U_{1\infty} = \frac{(P-P_a) A - F_f}{\frac{1}{2} P A_1 C_{d1}}$$

B-I-10 
$$\tau = a \text{ characteristic time}$$

$$\tau = \frac{M_1 U_{1\infty}}{(P-P_a)A-F_f}$$

The time, t, can be eliminated from equations B-I-7 and 8 to give  $\mathbf{U}_1$  as a function of  $\mathbf{x}_*$ 

B-I-11 
$$U_1 = U_{1\omega} - 1 - \exp(-2x/U_{1\omega}\tau)$$
 where 
$$\exp(\beta) = e^{\beta}$$

The final velocity can be calculated by substituting L for x in equation B-I-11.

These equations are useful for evaluating proposed systems and for comparing different types of systems, but they don't describe the gas generator necessary to provide the constant thrust. No real gas generator provides a perfectly constant pressure: therefore, more detailed calculations are needed to give accurate results. These detailed calculations will give answers for a real gas generator, but more important, they will be a powerful design tool for the development of the gas generator.

II. INTERIOR BALLISTICS: This technology area gives the means to calculate the changing interior pressure, P, and the means to design an effective propellant system. The first equation needed is the equation of state, which relates the pressure, volume, mass, temperature, and molecular weight of the gas. The ideal gas equation is usually used for more moderate pressure, but the high pressures used in the PEAs need an equation of state such as the modified van der Waals equation of state.

B-II-1 P 
$$(V - b \frac{m}{MW}) = \frac{m}{MW} RT$$

b = covolume, a measure of the finite volume of the gas molecules

MW = molecular weight of the gas (slugs/slug-mole)

V = volume available to the gas (cu ft)

R = universal gas constant (49,709 ft-1b/slug mole-R)

 $T = absolute temperature of the gas (<math>^{\circ}R$ )

m = mass of gas (slugs)

MW and b are parameters whose values depend on the composition of the gas; R is a universal constant; P, V, m, and T are variables. To calculate instantaneous values of P, it is necessary to know the two parameters, MW and b, the universal gas constant, R, and the variables V, m, and T. The remainder of this section covers the calculations of these variables.

The process starts with the burning of the propellant to produce the gas. The surface of the propellant regresses everywhere perpendicular to the burning surface. Figure 5 shows a propellant grain with a single perforation (monoperf), and Figure 6 shows a grain with seven perforations (seven perf). Figures 7 and 8 show a rocket propellant grain of a design that might be appropriate to a recoilless or direct rocket PEA. The drawings show how the grains regress as they burn; the grain is shown unburned and partially

burned. The following equations give the surfaces of the three types of grains as functions of their original dimensions and the burned distance, z. These functions are needed to calculate the rate of gas production.

$$S_{m} = \pi (OD_{o} + ID_{o}) \{ \frac{1}{2} (OD_{o} - ID_{o}) + H_{o} - 4z \}$$
where
$$S_{m} = \text{burning surface of one monoperf propellant grain (sq. ft.)}$$

$$OD_{o} = \text{original outside diameter of grains (ft.)}$$

$$ID_{o} = \text{original inside diameter of perforation (ft)}$$

$$H_{o} = \text{original length of grain (ft)}$$

$$Z^{o} = \text{distance burned, perpendicular to grain's}$$

This monoperf grain is totally consumed whenever  $z = H_0/2$  or  $z = (00_0 - 10_0)/4$ , whichever comes first. The equation for the seven perf grain is:

$$S_{s} = \pi \left\{ \frac{1}{2} \left( 0D_{o} - 71D_{o} \right) + H_{o} \left( 0D_{o} + 71D \right)_{o} + 2z \left( 6H_{o} - 20D_{o} - 14ID_{o} \right) - 36z^{2} \right\}$$

where S<sub>s</sub> = burning surface of one seven perf propellant grain (sq ft)

surface (ft)

This equation for  $S_s$ , is valid while  $z>\frac{0D_o-3ID_o}{8}$ . When z reaches this limit, 7/8 of the grain is burned. The remaining part of the grain burns in two modes. It takes about six equations to calculate the surface of these afterburns. These equations are not shown here, but they are in the computer program listed in Appendix A. The equation for the rocket propellant grain is:

$$S_{r} = (H_{o} + 2w - 4z) \{16 h_{o} + 8 ID_{o}\phi + \pi (ID_{o} + 8w + 2z)\}$$

$$-2\pi (3w - z)(w + z) + 4ID_{o}[\phi (ID_{o} + 4w) - 2w \cos \phi]$$

$$S_{r} = instantaneous surface of a rocket type grain (sq ft)$$

$$h_{o} = length of straight sides of the scokes (feet)$$

$$w = web of propellant grain (feet)$$

$$\phi = arcsine (2w/ID_{o}) \qquad (radians)$$

The next item needed is the propellant's regression rate,  $\boldsymbol{z}$  .

$$B-II-5$$
  $z = BP'$ 

where 
$$B = burning rate coefficient (ft/s psf-n)$$

Both B and n are determined by the composition of the propellant. The overall burning rate  $\mathbf{m}_{\mathbf{h}}$  is given by:

$$B-II-6 \qquad m_b = N S \rho_p z$$

$$S = S_m, S_s, \text{ or } S_r \text{ as appropriate (sq ft)}$$

$$\dot{\rho}_{\rm p}$$
 = density of the propellant (slugs/cu ft)

In both the recoilless and the rocket launched PEAs, most of the propellant gas goes out the nozzle. The equation for the exhaust mass flow rate is:

$$B-II-7$$
  $m_e = PA_tC_e$ 

where 
$$A_{t}$$
 = area of the throat of the nozzle (sq ft)

C<sub>e</sub> = discharge coefficient of propellant gas (slugs/pound)

Typical values for the discharge coefficient are .0002 slugs/pound-seconds. The net rate of accumulation of propellant gas is:

B-II-8 
$$\dot{m} = N S \rho_p B P^n - P A_t C_e$$

where 
$$m(0) = \frac{P(0) V(0) MW}{b P(0) + R T(0)}$$

The next item to be calculated is the volume, V, available to the gas. This volume comes from three sources: the initial or free volume,  $V_f$ ; the rate of increase of volume due to motion of the piston which is equal to  $(U_1+U_2)$  A; and the burning of the propellant grains. The gas volume, V, is given as a derivative with respect to time. The boundary condition at time \* 0 is  $V_f$ .

B-II-9 
$$\dot{V} = (U_1 + U_2)A + N S B P^n$$
  
and  $\dot{V}(0) = V_f$  = initial volume available to gas (cu ft)

The next state function to be calculated is the temperature, T. The changes in temperature will be rather small in all of the configurations being considered here, because the propellants burn to produce gas at constant temperature. This constant flame temperature and the high burning rates tend to maintain the temperature nearly constant. The combination of a high throughput and a short action time means that heat transfer is minimal. The only significant heat loss comes from the expansion work done by the gas. The time derivative of the temperature is:

B-II-10 
$$\dot{T} = (T_f - T) \quad \dot{m}_b / m - P \quad \dot{V}_u / (c_p J m)$$

$$c_p = \text{specific heat (Btu/slug-}^0 R)$$

$$J = \text{mechanical equivalent of heat (778.3 ft-lb/Btu)}$$

$$c_p J = \frac{\gamma}{\gamma - 1} \quad \frac{R}{MW}$$

$$\gamma = \text{ratio of specific heats (dimensionless)}$$

$$T(0) = T_f$$

$$\dot{V}_u = (U_1 + U_2) A$$

Substitute Equations B-I-1 and 6 into Equation A-I-2 gives:

B-II-11 
$$\dot{U}_1 = \{ (P - P_a) A - F_f - \frac{1}{2} \rho A_1 C_{d1} U_1^2 \} / M_1$$

B-II-12 
$$\dot{U}_2 = \{ (P - P_a) A - F_f - \frac{1}{2} P A_2 C_{d2} U_2^2 - P A_t C_f \} / M_2$$

Taking the derivitive of equation A+I-4 gives:

$$B-II-13 \qquad x = U_1$$

$$B-11-14$$
  $x_2 = 0$ 

All of the equations for the recoilless launcher are finally assembled. The first step in calculating the performance of a specific recoilless design is to determine all of the parameters and boundary conditions. The next step is to select an appropriate burning surface equation; equation B-II-2, 3, or 4, or some other equation if a different grain is used. The burning surface and equation of state, equation B-II-1, are auxiliary equations. Equations B-II-8 through B-II-14 are all first order differential equations that must be integrated simultaneously until the final boundary condition is met,  $(x_1 + x_2 = L)$ . Because of the mixed nature of these equations, it will be necessary to use numerical techniques to integrate them. If the reader is planning to write a computer program to carry out these integrations, he should be aware of several conventions used in the derivation of the equations: The sign of  $U_1$  is positive when it is going forward, the desired direction. Similarly, the sign of  $U_2$  is considered positive when it is going rearward, its natural direction of motion.  $U_2$  might become negative if the rocket thrust is higher than the recoil force. It is extremely unlikely that  $U_1$  will ever become negative, but the possibility that  $U_2$  can become negative may cause a problem in equation B-II-12. All of the terms in this equation have intrinsic directions indicated by their signs. The fluid drag . term  $(\frac{1}{2}\rho C_{di}A_{i}U_{i}^{2})$  is always opposite in sign to the velocity  $U_{2}$ . The equations as given are correct so long as the velocity,  $U_2$ , is positive. This can be handled in a computer program by multipying this term by a function SIGNUM( $U_2$ ). This function has a value of +1 or -1 as as  $U_2$  is positive or negative.

Appendix A is a copy of a computer program like the one just described, and a run showing a typical set of results. This program was encoded several months before the detailed analysis shown in this report. This explains the difference between them. For example, the program uses the ideal gas equation of state instead of the modified van der Waals equation of state. Also the program does not have a term for fluid dynamic drag on the launcher, because the launcher velocity is intended to be so low that the drag is insignificant.

The calculations show that the anchor can be accelerated to 300 ft/s by a recoilless device operating at 20,000 psi. The propellant charge assumed in this calculation consisted of 115 seven perf grains (Figure 6). This is not

the usual way to fuel a solid propellant rocket. Most solid propellant rocket motors have one or two grains that are nearly as large as the motor. The grains are also of such a shape that they stay in place with a very high reliability. This is not the case with relatively small grains. They can be blown through the large nozzles required by the PEAs. It is not clear that the techniques for grain retention that work in the much smaller recoilless rifles will work in the PEA combustion chambers. If this potential problem becomes serious, then it will be necessary to use rocket-like propellant grains as described in Figure 7, if they can be made to sustain the high acceleration load. It seems clear that the development of the propellant assembly would be an expensive and chancy undertaking.

# C. DIRECT ROCKET

The recoilless PEA launcher system described in the previous section appears to be a theoretically workable solution to the problems involved in launching large PEAs, if the propellant problems can be solved. Also, it is rather sophisticated. This level of sophistication is accepted in light artillery because it can give high velocity and accuracy without recoil in a hand held weapon. PEAs are not hand held and they do not require high accuracy. High velocity and adequate accuracy can be achieved with unguided direct rocket propulsion, but the direct rocket shares the recoilless PEA's propellant problems. With the direct rocket, the gun tube and piston are eliminated.

# I. DESCRIPTION OF DIRECT ROCKET PROPELLED PEA:

A direct rocket powered PEA is shown in Figure 4. The rocket motor is attached directly to the anchor. The thrust from the rocket motor, less the fluid dynamic drag on the assembly, accelerates the anchor and the rocket motor. The analysis of the forces is simpler than for the original PEA system and the recoilless system, because the whole apparatus moves as a unit.

The "up front" advantages of the direct rocket propelled PEAs are the reduced weight and complexity resulting from the elimination of the launch tube and piston. There is another, less obvious, advantage to the direct rocket PEAs. The duration of the thrust is not tied to the barrel length, because there is no barrel. The rocket can fire for a somewhat longer time at a lower thrust level. If desirable, the thrust can be continued through

penetration of the sea floor. The direct rocket PEAs also have several disadvantages relative to the original and the recoilless PEAs. In the original and recoilless systems, only the anchor and the piston are accelerated forward. In the direct rocket PEA, everthing is accelerated forward. This substantially increases the drag and the propelled mass, thus requiring an increased thrust. Another disadvantage of the direct rocket is that the propellant grain(s) is exposed to the same high acceleration and gas flow as the anchor (250 g's). This could cause the propellant to break up and the motor to fail or rupture.

# II. ANALYSIS OF DIRECT ROCKET PEA:

This analysis is less wordy because it closely parallels the analysis of the recoilless PEA. It starts with the forces on the body. The subscript, 3, will be used to distinguish variables relating to the direct rocket PEA. The net force on the body is:

$$C-II-1$$
  $F_3 = P A_t C_f - \frac{1}{2} p U_3^2 A_3 C_{d3}$ 

All of the terms have been defined earlier. The terminal velocity,  $U_{3\infty}$ , is the velocity at which  $F_3 = {}^{\gamma}$ . It can be calculated by setting  $F_3$  equal to zero in Equation C-II-1, and solving for the terminal velocity.

$$U_{3\infty} = \sqrt{\frac{P A_t C_f}{\frac{1}{2 P A_3 C_{d3}}}}$$

The rate of change of the mass of the vehicle is:

$$C-II-3$$
  $M_3 = -PA_t C_e$ 

The initial mass of the vehicle, including propellant, is  $M_3(\theta)$ . The velocity of the vehicle is given by the differential equation:

$$c-11-4$$
  $\dot{U}_3 = F_3/M_3$ 

The position of the vehicle is given by the differential equation:

$$c-11-5$$
  $x_3 = V_3$ 

The initial values of  $U_3$  and  $X_3$  are zero. All that is necessary to integrate the equation is a way to calculate the instantaneous value of P. This can be done with most of the same equations used for the recoilless PEA. Equations B-II-1 to B-II-8 can be used as they are. The rate of change of the gas volume is different because there is no piston.

$$v_3 = NSBP^n$$

Equation B-II-10 is not needed because the temperature remains constant.

As with the recoilless PEA calculations, the first step is to get values for the boundary conditions and parameters. A burning surface equation must be selected from B-II-2, 3, or 4; or some combinations of them; or some other equation as needed. The equation of state, equation B-II-1, is needed, and the differential equations B-II-8, C-II-4, 5, and 6 are needed. Again, as with the recoilless PEA, these equations must be solved by numerical techniques. An example program is shown in Appendix B along with a sample calculation.

The differential equations can be solved in closed form if the pressure is constant. The velocity as a function of time is:

C-II-7 
$$U_3 = U_{3\infty} \tanh \left[ -\frac{C}{U_{3\infty}} \log_e \left\{ 1 - \frac{PA_L C_e}{M_o} t \right\} \right]$$

where  $C = C_f/C_e = \text{velocity of rocket exhaust (ft/s)}$ 

# D. WATER JET PEAS

While explaining the details of the assignment to the author, the sponsors mentioned an unusual propulsion scheme proposed at Port Hueneme. That proposal was for a gas driven water jet to neutralize the recoil force. Our understanding was that the gas was to be supplied from compressed gas (air) cylinders. To get the needed results would require nearly 50,000 standard

cubic feet of gas compressed to 40 000 psi. Half of this compressed gas would have to be transferred to the water chamber in 40 milliseconds. This would require a very impressive valve. While it seems very unlikely that the job can be done with compressed gas, the picture is quite different if the driving gas is generated by burning a charge of gun propellant. Instead of nearly two tons of very high pressure air, not to mention the tankage, the job can be done with only 200 pounds of gun propellant.

# I. WATER JET PEA DESCRIPTION

Figure 4 gives a conceptual drawing of a water jet PEA. A water jet PEA, operating at 20,000 psi<sup>1</sup> (2,880,000 psf), will have a six foot long launch tube with an inside diameter of ten inches (.8333 ft). This would be connected to the end of water tube that is 5.5 feet long and a 2.12 foot inside diameter. Its shape will be cylindrical with hemispherical ends. The free end of the 5.5 foot diameter tube is terminated with a convergent nozzle with an exit area of .25 square feet (ID = .564 ft). The propellant charge and the igniter are stored in the end of the water tube near the launch tube; the drive piston fits into the .833 foot diameter tube; and the seawater goes into the 2.12 foot inside diameter water tube. The water tube is dry during storage and handling. It fills with seawater while being lowered into the sea.

The propellant charge is ignited when the assembly is lowered to its deployment depth. The burning propellant causes the pressure to rise quickly to a constant level of about 20,000 psi internal. The high pressure causes the water to accelerate and stream out of the nozzle. After a few milliseconds, the exit velocity stabilizes at about 1,700 feet per second. Near the end of the water expulsion, there is another acceleration as the nozzle empties. Figure 10 is a graph of the water velocity as a function of time. The higher velocity trace represents the velocity of the water leaving the nozzle. The lower velocity trace represents the velocity of the gas-water interface.

# II. ANALYSIS OF THE WATER JET PEA-

The equations needed to culculate the performance of the water jet PEA are the same as those used for the recoilless PEA, with one exception. That

 $<sup>^{1}</sup>$  A later section will cover water jet PEAs operating at other pressures.

exception is equation B-I-3, which gives the thrust from the rocket. The thrust from the water jet is:

D-II-1 
$$F_5 = \rho A_t U_5^2 (1 - A_t/A_{wt}) + \rho A_{wt} (L - x) \frac{dU_4}{dt}$$

where  $U_5 = \text{exit velocity of water (ft/s)}$ 

 $U_4$  = velocity of water at interface with drive gas (ft/s)

L = length of the water tube (feet)

The definition of the terms is given pictorially in Figure 9. The detailed calculation is somewhat lengthy and complex, and it will not be derived here. The derivation, along with a computer model and sample problem, is given in Appendix C. If one assumes a constant gas pressure of 20,000 psi. the following events occur in sequence. Figure 10 should be referenced during the explanation. Initially, the water is at rest, but it starts to accelerate as the pressure is applied. The initial acceleration of the main body of water is about 240,000 ft/s2 but it drops to zero in about four milliseconds. The average acceleration over the four milliseconds is 42,500 ft/s2. The initial high acceleration is caused by the high pressure gradient across the constant area length of the water column. As the velocity increases, the pressure gradient across the constant area length decreases until the accel-At that time, all of the pressure gradient is across eration reaches zero. the nozzle where the speed increases by a factor of ten. A particle of water in the constant area section is traveling at about 170 ft/s, so long as it remains in the constant area section. When it reaches the nozzle it accelerates in one millisecond to 1,700 ft/s, an acceleration of 1,530,000 ft/s2.

Without detail, the operating sequence is: Four milliseconds accelerating the main body of water to its steady state speed of 170 ft/s; 35 milliseconds at the steady speed of 170 ft/s; and one millisecond of very high acceleration as the nozzle empties. During this whole process, the water leaving the nozzle is traveling ten times faster than the water in the main body. During the main steady portion, the exit velocity is 1,700 ft/s. The exit velocity can easily be calculated for the steady flow by equating the total heads at the inlet and the exit of the nozzle along with the continuity equation.

D-II-2 
$$P + \frac{1}{2} \rho U_4^2 = P_a + \frac{1}{2} \rho U_5^2$$

where 
$$U_4$$
 = velocity of the gas-water interface (ft/s)

$$U_{5}$$
 = water velocity at exit from nozzle (ft/s)

The continuity equation is:

D-II-3 
$$\rho A_{wt} U_4 = \rho A_t U_5$$

where  $A_{wt}$  = cross sectional area of straight portion of the water tube (sq ft)

Combining the equations gives:

$$0-II-4 \rho U_5^2 = \frac{2 (P-P_a)}{1 - (A_t/A_{wt})^2}$$

Combining this result with the steady stace form of equation D-II-1 gives:

0-II-5 
$$F_5 = \frac{2 A_t (P-P_a)}{1 + (A_t/A_{wt})}$$

If the forces are balanced so that the launcher remains stationary, then the motion of the anchor will be described by equations B-I-7 to 10. The following equation must be satisfied to have the forces balances.

D-II-6 
$$A_t = A_{wt} \frac{(P-P_a) A - F_f}{(P-P_a) (2A_{wt}-A) + F_f}$$

Since  $F_f$  is small compared to  $(P-P_a)$  A, a good approximation for . is

$$D-11-7 A_t = \frac{A_{wt} A}{2 A_{wt} + A}.$$

Assuming the same 2,880,000 psf (20,000 psi) that was used for the recrilless and direct rocket examples, the water jet exit velocity is 1,704 ft/s. With a nozzle throat area  $A_{\rm t}$ , of .25 sq ft, the thrust would be 1.5 x  $10^6$ 

pounds. The mass flow out the nozzle will be 852 slugs/s (27,400 pounds/s) for .04 seconds. The total mass of water is 34 slugs (weighing 1,100 pounds). To hold this much water, the internal volume of the water tube must be 17 cu. ft. For example, the tube could have an inside diameter of 2.12 feet and a length of 5.5 feet. The launcher also requires the piston tube which is six feet long and ten inches in inside diameter.

# E. COMPARISON OF THE APPROACHES

After having read this enthusiastic description of these several ways of reliably launching large PEAs, it is time to examine and compare them critically. They will be compared on the basis of weight, size, and probability of successful development. Finally, a recommendation will be made as to which option should be developed.

# I. SIZE AND WEIGHT COMPARISON:

The size and weight comparisons are taken together because they are based on the same parameters. The launch tube comparison will be done first, because it is common to the recoilless and the water jet options. The key relationship for the launch tubes is the requirement that they deliver a force of 1.44 x  $10^6$  pounds over a stroke of six feet. Therefore, the inside diameter of the launch tube is

E-I-1 
$$ID_b = \sqrt{\frac{4 F_1}{\pi P}}$$

Note that inside diameter of the launch tube is given in feet and the pressure is given in psf. Figure 11 is a graph of the launch tube inside diameter as a function of pressure. In order to determine the wall thickness, one needs the yield strength of the reterial of construction. Because the pressures will be high, it will be necessary to use thick wall equations for cylinders to calculate the wall thickness. This equation is:

E-I-2 
$$P = S_y = \frac{x^2 - 1}{2x^2}$$
 or  $x = \sqrt{\frac{S_y}{S_y - 2P}}$   
where  $S_y = yield strength of material (same units as pressure)and  $x^2 = 00 \frac{10}{5}$$ 

$$OD_b = ID_b + 2t$$

where

t = wall thickness.

Equation E-I-2 can be rearranged to

E-I-3 
$$t = \frac{ID_b}{2} \left[ \sqrt{\frac{S_y}{S_y - 2P}} - 1 \right]$$

The weight of the steel tube launch is given by

E-I-4 
$$W_b = \rho_b L_b \frac{\pi}{4} (00^2_b - 10^2_b)$$

where

 $L_h$  = length of the launch tube cylinder

 $\epsilon_{\rm h}$  = density of structural material of launch tube.

 $\mathfrak{PC}_{+}$  = outside diameter of launch tube (ft)

 $10_{h}$  = inside diameter of launch tube (ft)

One must be careful to match all of the units in these equations. If Equation E-I-I and 2 are substituted into Equation E-I-A and simplified, one gets

E-I-5 
$$W_b = \rho_b L_b \frac{2 F_i}{S_y - 2 P}$$

Figure 12 is a plot of  $W_b$  as a function of  $S_y$  at several values of P with L fixed at six feet (72 inches). Examining Figure 12 shows that the weight decreases as the yield stress increases and as the pressure decreases. If one reduces the weight of the launch tube by decreasing the pressure, one must increase the inside diameter according to Equation E-I-1. At this time it is not clear what, if any, negative effects are related to large launch tube diameters.

The launch tube is the smaller of the two main components of the proposed PEAs, and the calculation of its size and weight is straightforward. The size and weight of the water tube for the water jet PEA can also be calculated by straightforward analysis. Unfortunately, the rocket motors of the recoilless and the direct rockets are not so simply handled. They require huge thrusts ranging from 1.5 to 3.0 million pounds and an extremely short burn time of .040 seconds. The volumes of main stream service rockets are proportional to their total impulse,  $I_{\rm t}$ . The approximate volume of a main stream rocket can be calculated by:

E-I-6 
$$V = 6.2 \times 10^{-5} I_t$$
  
where  $V = \text{volume of a mainstream rocket (cu ft)}$ 

Since the total impulse required for the PEA rocket motors range from 58,000 to 80,000 pound-seconds, the estimated volume ranges from 3.6 to 5.0 cubic feet. However, it would be totally impossible to make a rocket of this volume deliver 1.5 to 3.0 million pounds of thrust. To provide the very large thrust would require two or three hundred thousand square inches of burning surface. The propellant would have to be divided into many small pieces, and they must be supported in a dispersed array to allow room for 6,800 pounds per second of gas to flow through the array to the nozzle. This would cause a large increase in the volume of the PEA rockets over that predicted from their total impulse. It is difficult to predict how large the volume increase would have to be, because the PEA rockets would be far out of the main stream of relations.

The water jet must produce a thrust, F5, of 1.44  $\times$   $10^6$  pounds of thrust for .040 seconds. Starting with Bernoulli's Equation, Equation D-II-2, and the thrust Equation D-II-5, one can derive an equation for the mass flow of water coming out from the nozzle. This equation follows:

E-I-7 
$$m_W = F_5 \sqrt{\frac{\rho_W/2}{P - P_a - F_5/A_{wt}}}$$
 see Equation E-I-8 
$$m_W \times t = m_W \cdot \text{and } F_3 \cdot t = I_{t3}$$

We can multiply both sides by t, and calculate the weight of the water.

E-1-8 
$$m_w = I_{5t} \sqrt{\frac{P - P_a - F_5/A_{wt}}{P - P_a - F_5/A_{wt}}}$$

Dividing both sides by  $\rho_{_{\boldsymbol{W}}}$  gives the volume of the water that will be ejected during the launching.

$$V_{w} = \sqrt{\frac{I_{5t}}{2 \rho_{w} (P - P_{a} - F_{5}/A_{wt})}}$$

The dimensions of the water tube can now be calculated. First, the inside diameter,  ${\rm ID}_3$ , must be selected. The water tubes will have cylinders with hemispherical caps. Given this shape and the internal volume, one can calculate the length,  ${\rm L}_3$ .

E-I-10 
$$L_{3} = \frac{4 \text{ V}_{w}}{\pi \text{ ID}_{3}^{2}} + \text{ ID}_{3}/3$$

Figure 13 is a plot of water tube length as a function of  ${\rm ID}_3$  and pressure. Because the walls are moderately thick, it will be necessary to use the thick wall equations. The thick wall equation for cylinders was given earlier, Equation E-I-2 and 3. The equation for spheres is very similar

E-I-11 
$$P = S_y = \frac{x^3 - 1}{1.5 x^3}$$

Since u is the ratio of the outside diameter to the inside diameter, the outside diameter of the spheres is

E-1-12 
$$00_{sph} = 10_3 \sqrt[3]{\frac{S_y}{S_y - 1.5P}}$$

The weight of the water tube is ...

E-I-13 
$$W_{\text{wt}} = \rho_{\text{wt}} \left[ \frac{\pi}{4} \left( L_3 - ID_3 \right) \left( 0D^2_{\text{cyl}} - ID_3^2 \right) + \frac{\pi}{6} \left( 0U_{\text{sph}}^3 - ID_3^3 \right) \right]$$

Using Equations E-I-2, 12, and 13, one can calculate the weight of the water tube. Besides the equations, che needs the weight density of the material, the length and inside diameter, the pressure, and the yield stress of the material.

E-I-14 
$$W_{wt} = \rho_{wt} \frac{\pi}{4} P ID_3^2 \left[ \frac{2(L_3 - ID_3)}{S_y - 2 P} + \frac{ID_3}{S_y - 1.5P} \right]$$

The most likely material for the water tube and launch tube is steel. It has a weight density of 492 pounds per cubic foot. Composite materials, such as fibre glass-epoxy would permit lower weights.

Appendix D is a copy of a BASIC computer program that computes all of the dimensions and weights of the launch tube and water tube. The program computes all of these values for a matrix of pressure, inside diameter, and yield stress of material of construction. The limits and increments of the matrix are specified by the user. Besides the program, Appendix D includes several output sheets each of which lists the results for one inside diameter, a range of pressure, and a range of yield stresses. Figure 11 is a graph of the launch tube inside diameter as a function of pressure; Figure 12 is graph of of the launch tube weigth as a function of yield stress and pressure. Figure 13 is a graph of the length of the water tube as a function of its inside diameter and the working pressure. Figures 14 to 26 are plots showing the weight of the whole assembly (launch tube and water tube). Each figure has a family of curves, one for each value of the yield stress. One set of graphs, Figures 14 to 21 plot the system weight versus the pressure. There is one graph for each of the eight inside diameters considered. Figures 22 to 26 graph the system weight versus the inside diameter. There are five graphs, one for each pressure considered. With the aid of these graphs, one can select a configuration which most closely meets the needs of the users. One must keep in mind that although these analyses are very thorough, they are "first cuts." One shortcoming is the fact that the sizes given do not include space for the propellant.

# F. CONCLUSIONS AND RECOMMENDATIONS

Upon first examination, all three of the PEA launchers considered in this paper look workable. However, an examination of the requirements for the rocket motors needed for the recoilless and the direct rocket PEAs, shows a huge rocket engineering job. The recoilless PEA requires a total impulse of 57,600 pound-seconds. A typical service rocket with that total impulse would have about 250 pounds of propellant and have thrusts ranging from 6,000 to 36,000 pounds. The highest thrust of these rockets is nearly two orders of magnitude too low for the PEA application. One of the few service rockets which have a thrust near the 1.44 million pounds required is the TITAN III C, which is ten feet in diameter and 85 feet long--somewhat larger than desired. To bridge this gap, the propellant must be divided into many small pieces so that there will be sufficient burning surface. Some very strong means must be devised to hold the propellant in the combustion chamber while three tons per second of dense gas are flowing from the combustion chamber to and through the nozzle. The drag on the propellant grains from this enormous flow would rip the grains loose and out the nozzle before they were burned. The highly divided grains and the distributed flow area required would make such a rocket. motor much larger than other 57,600 pound-second rocket motors. The development and production costs for such rocket motors would be too high for this program.

The problems associated with the two high thrust rocket motors derive from the combination of many small grains of propellant, such as gun propellant, with a high flow through the bed of propellant grains and out a nozzle. The water jet PEA also requires highly divided, gun like propellant, but the combustion chamber is not vented. The burning propellant is always enclosed in a rapidly growing volume defined by the anchor piston, the water and launcher tubes, and the gas-water interface. Therefore, the propellant grains do not have to be restrained. All that is needed is a frangible waterproof container that can keep the propellant dry during the deployment. The large scale swaging equipment needed to make the water tube and launch tube are available, and production costs are moderate.

The conclusion of this study is that the water jet PEA is clearly the best choice. Experimental development of this system should be started as soon as possible.

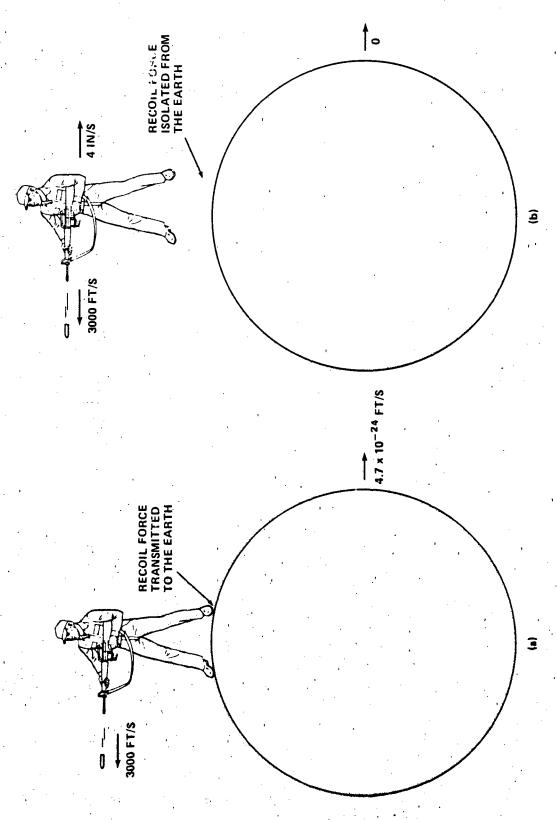


FIGURE 1. COMPARISON OF EFFECT FROM A PERSON FIRING A .30 CALIBER RIFLE WHILE STANDING ON THE EARTH (a) AND SUSPENDED ABOVE THE EARTH (b)

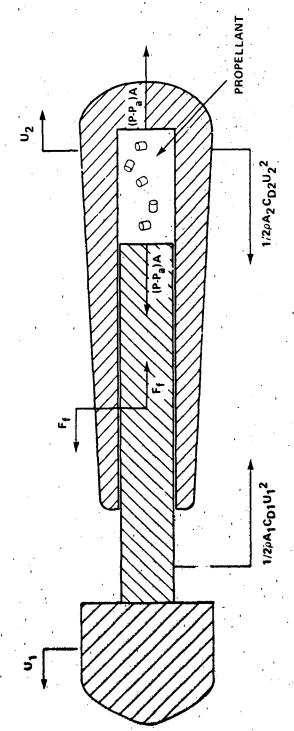


FIGURE 2. A CUTAWAY DRAWING OF A SIMPLIFIED PEA LAUNCHER WITH NO VIRTUAL MASS AUGMENTER

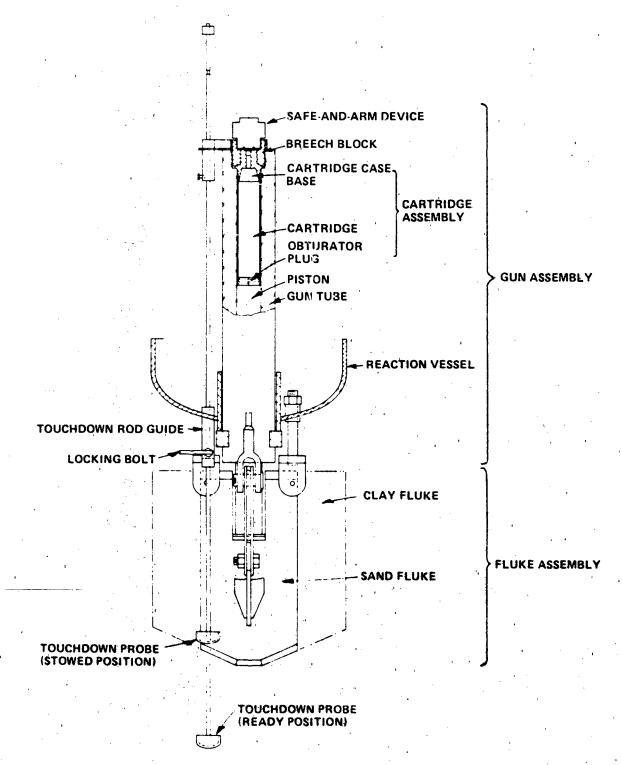
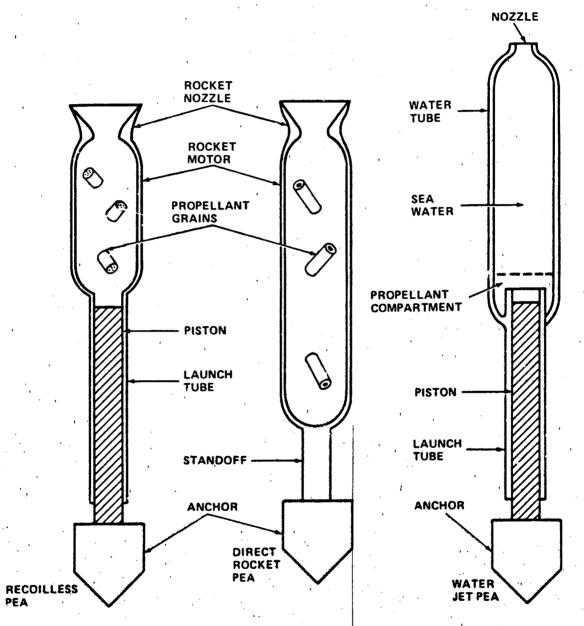
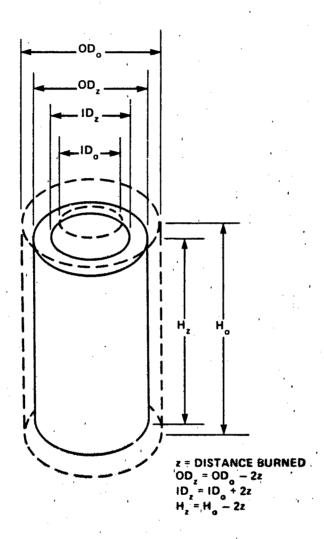


FIGURE 3. PARTIAL CUTAWAY DRAWING OF A SMALL (10 KIP) PROPELLANT EMPLACED ANCHOR

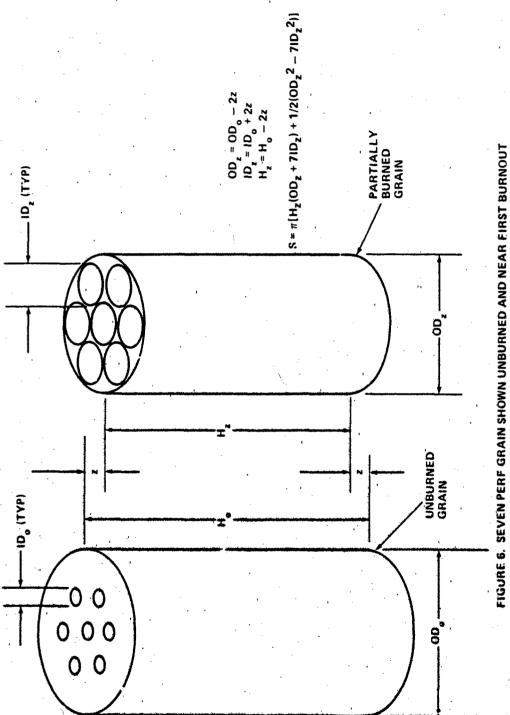


IGURE 4. CONCEPTUAL DRAWINGS FOR ALL THREE RECOILLESS PEA'S INVESTIGATED IN THIS REPORT



SURFACE PER GRAIN =  $\pi$  (OD<sub>o</sub> + ID<sub>o</sub>)(OD<sub>o</sub> - ID<sub>o</sub>/2 + H<sub>o</sub> - 4z) WHILE z  $\leq$  (OD<sub>o</sub> - ID<sub>o</sub>)/4

FIGURE 5. THE SURFACE OF A MONOPERFORATED GRAIN AS IT BURNS AWAY



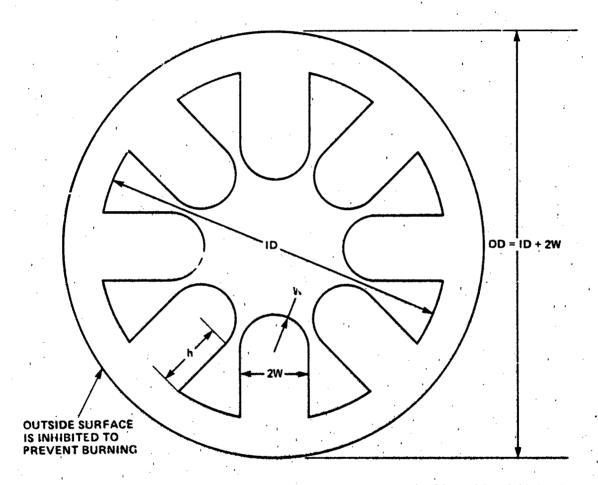


FIGURE 7. CROSS SECTIONAL VIEW OF A PROPELLANT GRAIN APPROPRIATE TO A ROCKET OR RECOILLESS PEA. FIGURE 8 SHOWS THE DETAILS OF BURNING

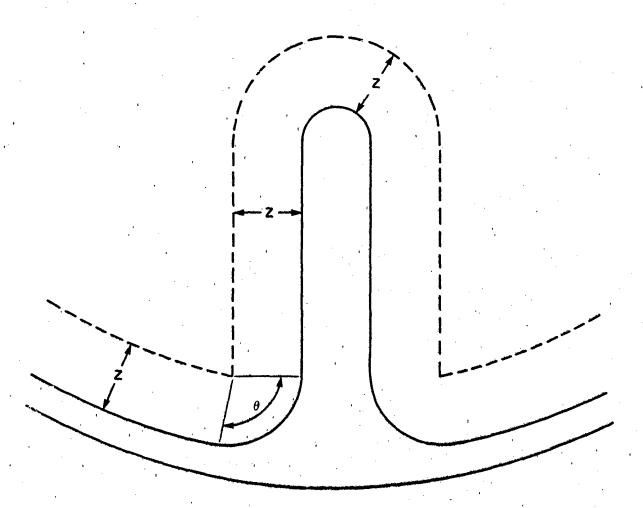


FIGURE 8. A DETAIL FROM FIGURE 7, SHOWING THE BURNING PATH. (DASHED LINES INDICATE ORIGINAL SHAPE AND SOLID LINES THE INSTANTANEOUS SHAPE)

FIGURE 9. DRAWING OF WATER JET PEA SHOWING GENERATION OF FORCE

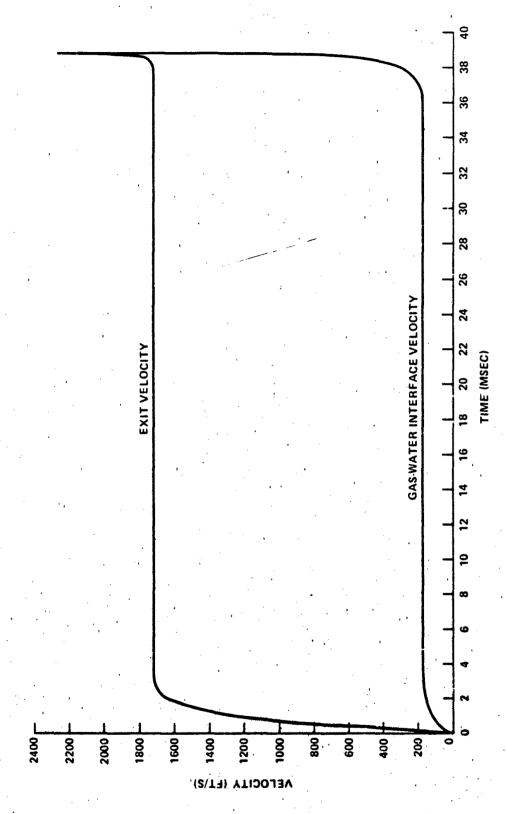


FIGURE 10. WATER VELOCITY AT EXIT AND AT GAS WATER INTERFACE AS A FUNCTION OF TIME. (PRESSURE IS ASSUMED TO BE CONSTANT AT 20,000 PSI)

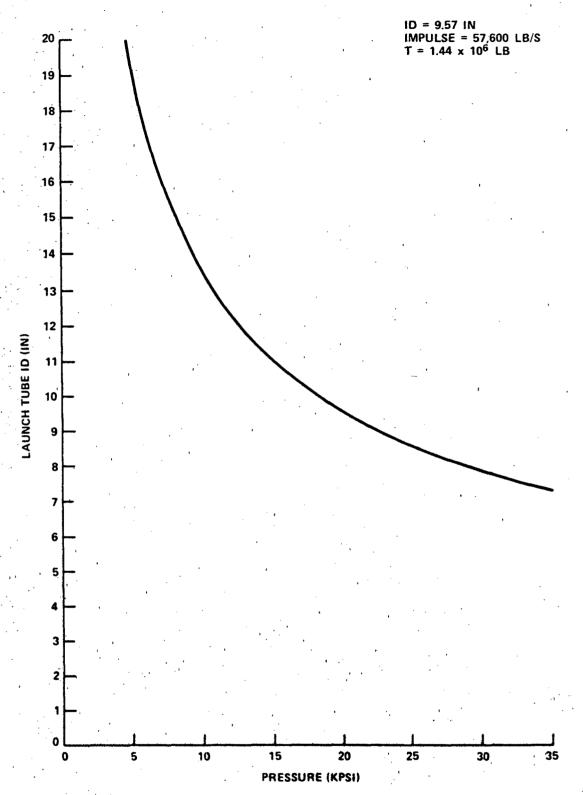


FIGURE 11. REQUIRED INSIDE DIAMETER OF LAUNCH TUBE AS A FUNCTION OF DRIVE PRESSURE

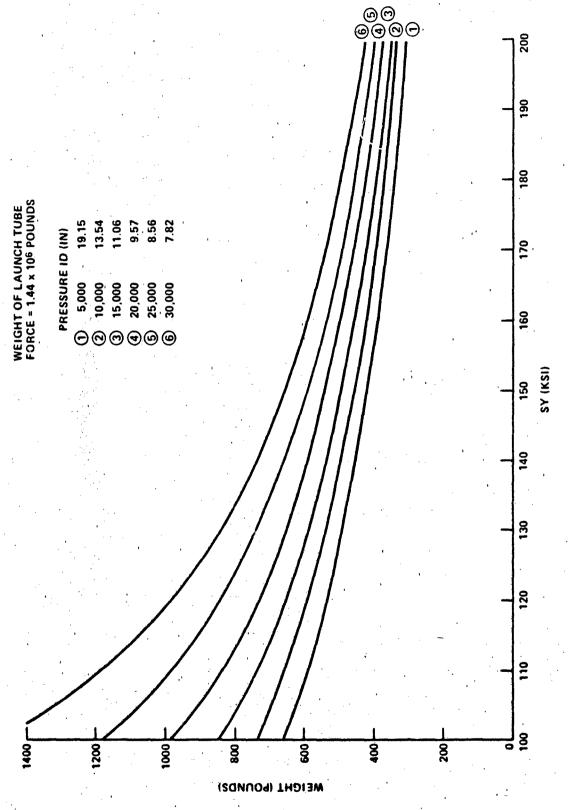


FIGURE 12. WEIGHT OF LAUNCH TUBE AS A FUNCTION OF PRESSURE AND YIELD STRESS OF MATERIAL (ASSUMED LENGTH IS SIX FEET AND THRUST IS 1.44 × 10<sup>6</sup> POUNDS)

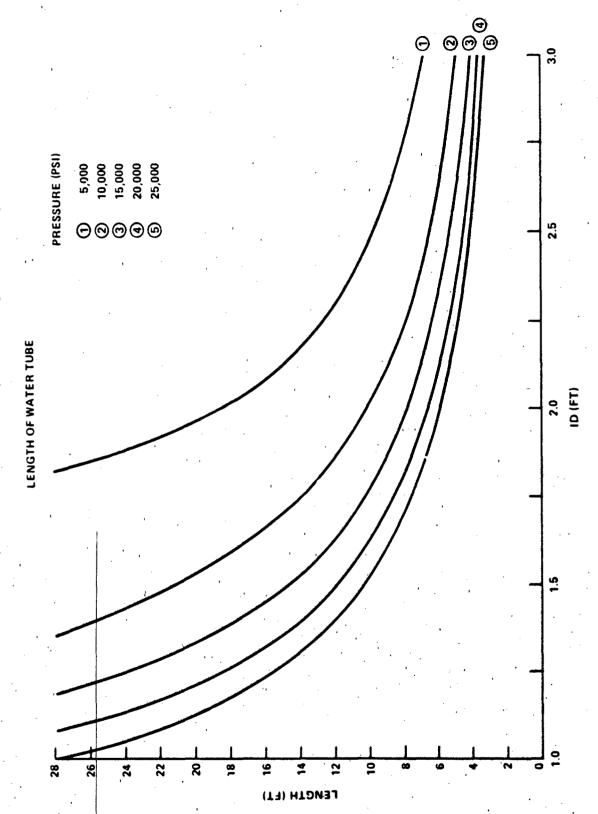


FIGURE 13. LENGTH OF WATER TUBE AS A FUNCTION OF PRESSURE AND WATER TUBE INSIDE DIAMETER

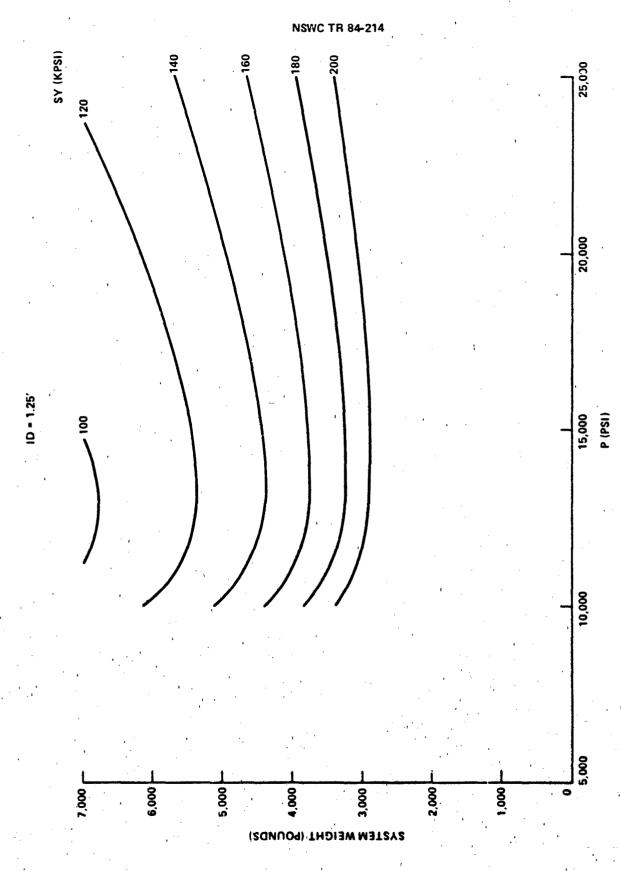
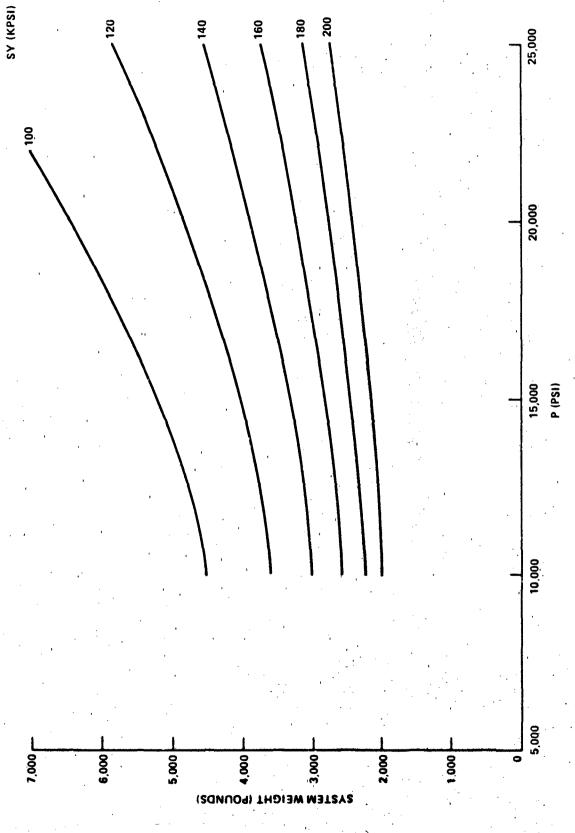
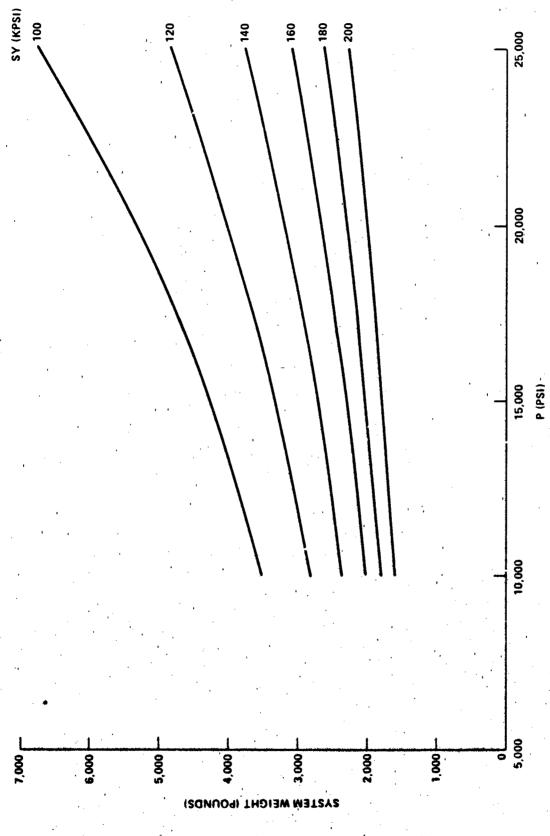


FIGURE 14: PLOT OF WATER JET TOTAL SYSTEMWEIGHT VS PRESSURE AND YIELD STRESS, SY.
THIS FAMILY OF CURVES IS BASED ON A WATER TUBE INSIDE DIAME IER OF 1.25 FEET



10 = 1.5'

FIGURE 15. PLOT OF WATER JET SYSTEM WEIGHT VS PRESSURE AND VIELD STRESS, SY. THIS FAMILY OF CURVES IS BASED ON A WATER TUBE INSIDE DIAMETER OF 1.5 FEET



ID \* 1.75'

FIGURE 16. PLOT OF WATER JET SYSTEM WEIGHT VS PRESSURE AND YIELD STRESS, SY. THIS FAMILY OF CURVES IS BASED ON A WATER TUBE INSIDE DIAMETER OF 1.75 FEET

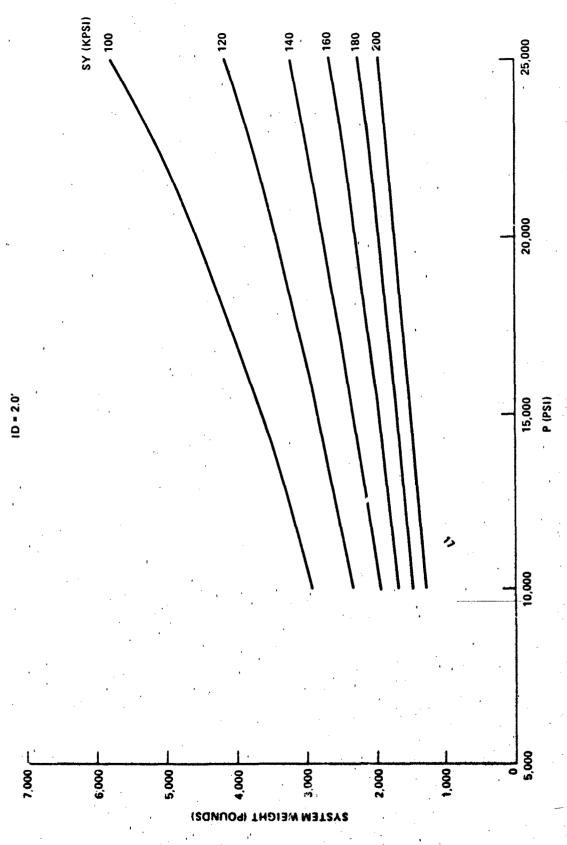


FIGURE 17. PLOT OF WATER JET SYSTEM WEIGHT VS PRESSURE AND YIELD STRESS, SY. THIS FAMILY OF CURVES IS BASED ON A WATER TUBE INSIDE DIAMETER OF 2.0 FEET

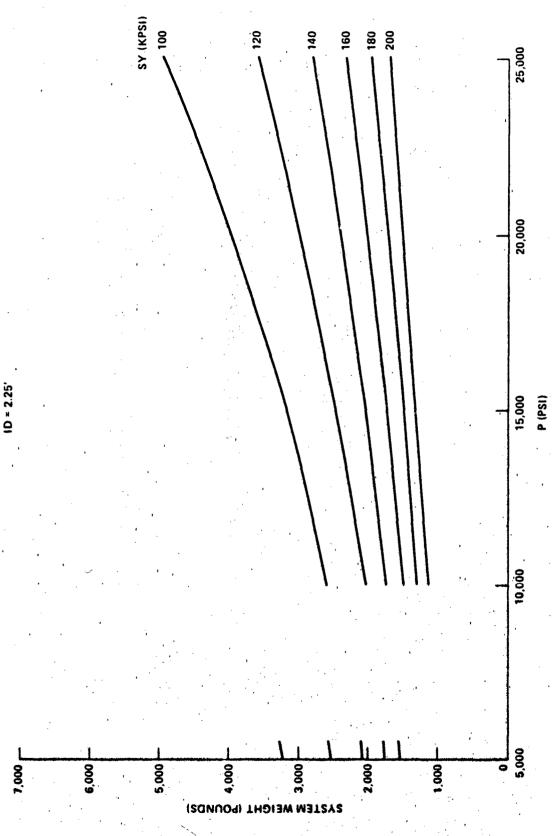
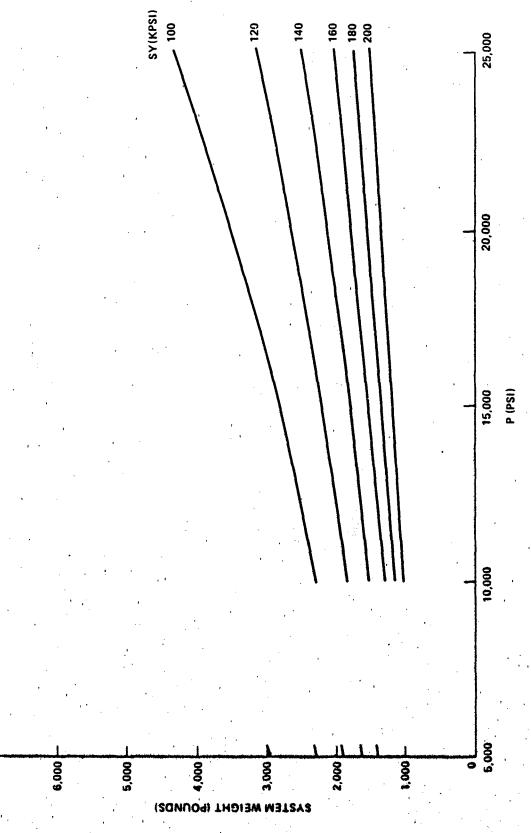


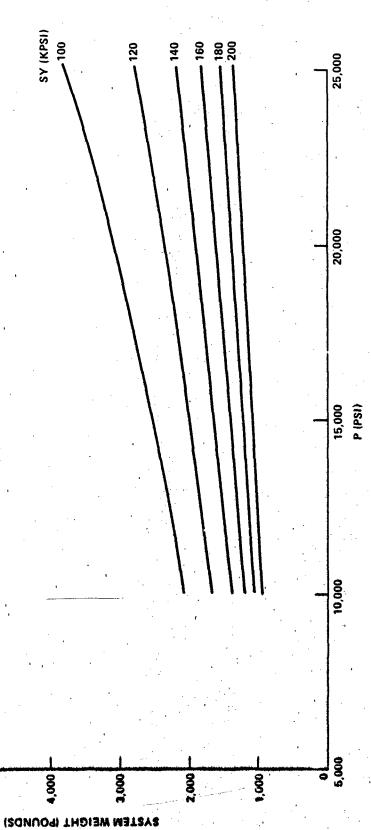
FIGURE 18. PLOT OF WATER JET SYSTEM WEIGHT VS PRESSURE AND VIELD STRESS, SY. THIS FAMILY OF CURVES IS BASED ON A WATER TUBE INSIDE DIAMETER OF 2.25 FEET



10 = 2.5'

7,000,7

FIGURE 19. PLOT OF WATER JET SYSTEM WEIGHT VS PRESSURE AND YIELD STRESS, SY. THIS FAMILY OF CURVES IS BASED ON A WATER TUBE INSIDE DIAMETER OF 2.5 FEET



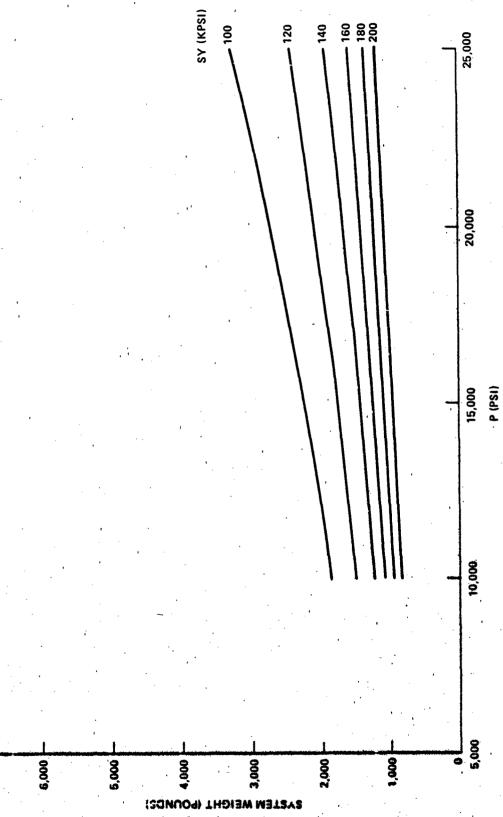
10 = 2.75

7.000.Y

6,000

5,000

FIGURE 20. PLOT OF WATER JET SYSTEM WEIGHT VS PRESSURE AND YIELD STRESS, SY. THIS FAMILY OF CURVES IS BASED ON A WATER TUBE INSIDE DIAMETER OF 2.75 FEET



10 = 3.0

7.000

FIGURE 21. PLOT OF WATER JET SYSTEM WEIGHT VS PRESSURE AND YIELD STRESS, SY. THIS FAMILY OF CURVES IS BASED ON A WATER TUBE INSIDE DIAMETER OF 3.0 FEET

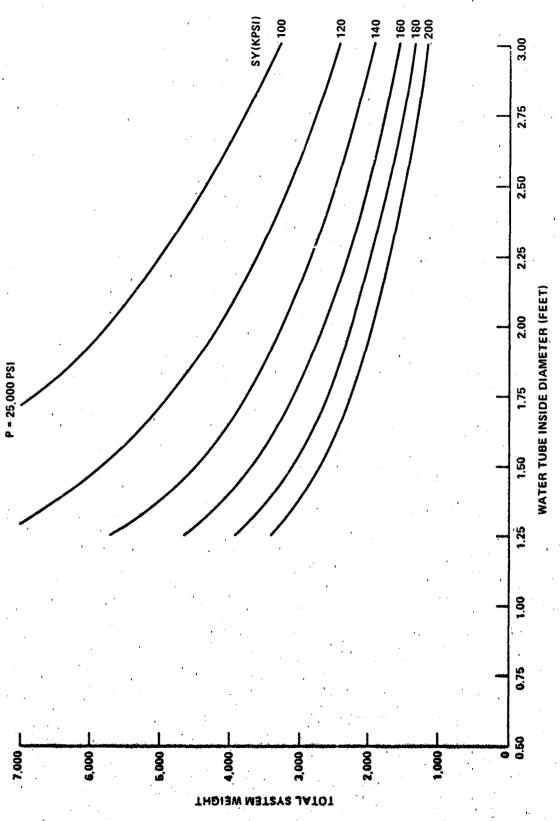


FIGURE 22. PLOT OF TOTAL WATER JET PEA WEIGHT VS WATER TUBE INSIDE DIAMETER AND YIELD TRESS. THIS FAMILY OF CURVES IS BASED ON AN OPERATING PRESSURE OF 25,000 PSI

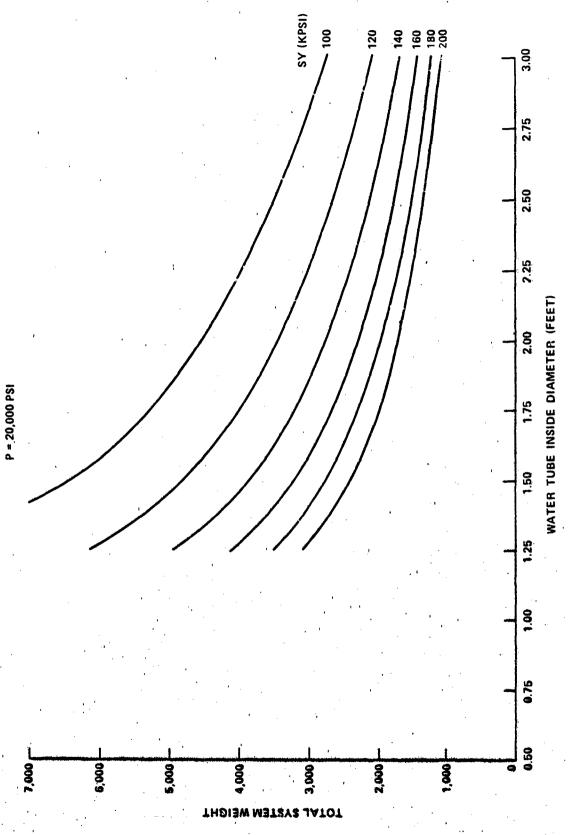


FIGURE 23. PLOT OF TOTAL WATER JET PEA WEIGHT VS WATER TUBE INSIDE DIAMETER AND YIELD STRESS. THIS FAMILY OF CURVES IS BASED ON AN OPERATING PRESSURE OF 20,000 PSI



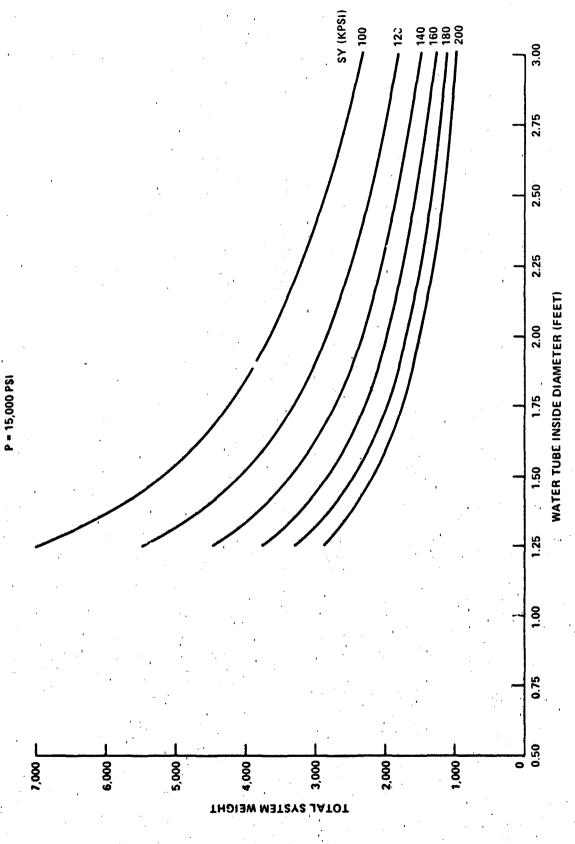


FIGURE 24 PLOT OF TOTAL WATER JET PEA WEIGHT VS WATER TUBE INSIDE DIAMETER AND YIELD STRESS. THIS FAMILY OF CURVES IS BASED ON AN OPERATING PRESSURE OF 15,000 PSI

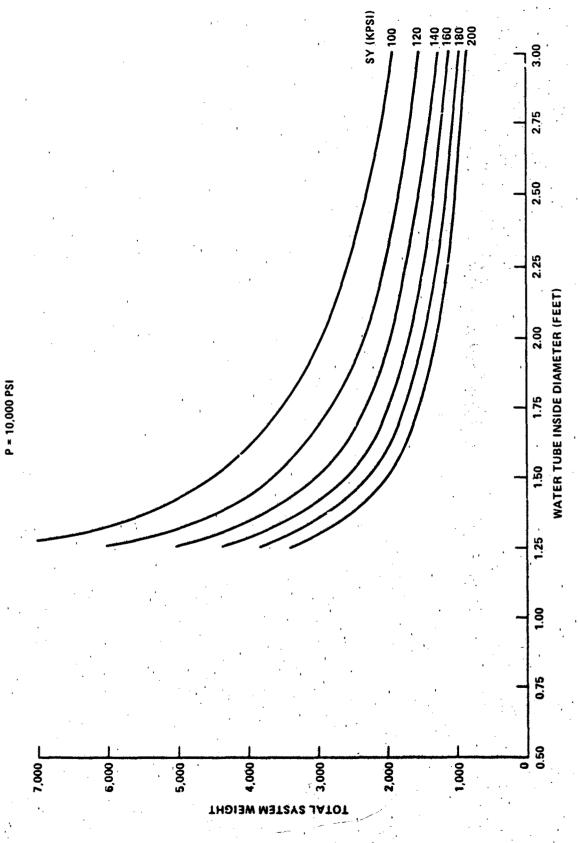
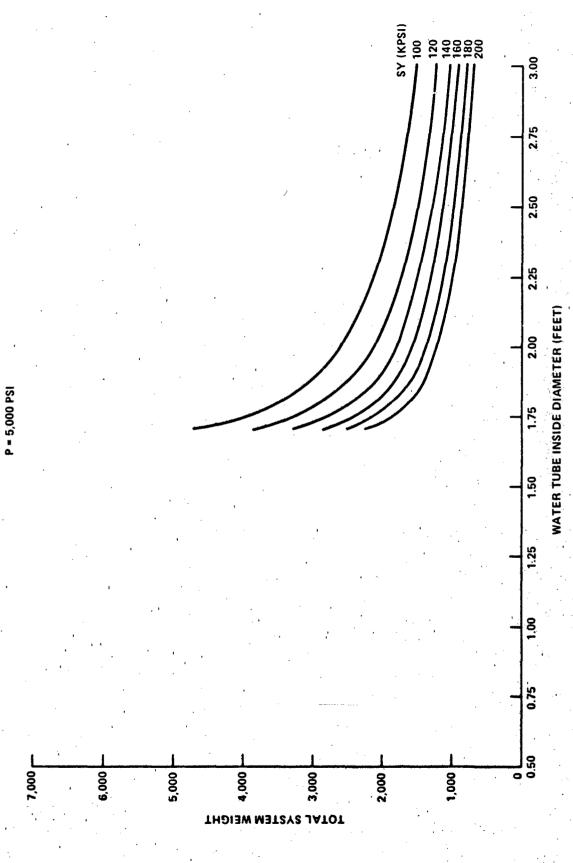


FIGURE 25. PLOT OF TOTAL WATER JET PEA WEIGHT VS WATER TUBE INSIDE DIAMETER AND YIELD STRESS. THIS FAMILY OF CURVES IS BASED ON AN OPERATING PRESSURE OF 10,000 PSI



PLOT OF TOTAL WATER JET PEA WEIGHT VS WATER TUBE INSIDE DIAMETER AND YIELD STRESS. THIS FAMILY OF CURVES IS BASED ON AN OPERATING PRESSURE OF 5,000 PSI FIGURE 26.

### APPENDIX A

## RECOILLESS COMPUTER PROGRAM, INCLUDING ITS DESCRIPTION AND SAMPLE CALCULATIONS

The computer program included in this appendix simulates the performance of a recoilless propellant emplaced anchor. The program numerically integrates Equations B-II-5 through 14. Equation A-I-5 expresses the termination conditions, and Equation B-II-3 is used to calculate the propellant burning surface. The ideal gas equation was used to calculate the pressure instead of the modified van der Waals equation (B-II-1), because the value for the covolume, b, was not known.

The main program, named TETHER, sets values for the constants, and reads in a file (TAPE8) of operating parameters. Any of these parameters can be changed at running time by using NAMELIST STUFF. After the input parameters have been established, the main program calculates auxiliary parameters and boundary conditions. All of the input and most of the calculated parameters are printed so that the user will have the the input parameters and the results in one output. The main program then prints the column headings and transfers control to the integration subroutine. With the aid of several other subroutines, it integrates the equations from the starting conditions to the termination condition and prints the results. Control is then returned to the main program, and the operator is queried to continue or stop. If the operator elects to continue, then he is requested to input any changed data via the NAMELIST STUFF statement. The entire process is then repeated with the new set of input data.

The integration subroutine, named RUINT, can integrate any number of simultaneous first order differential equations. It applies the Runge-Kutta method for numerical integration. From the main program, it gets several parameters such as the integration step value for the independent variable, the print frequency, the initial values, and the termination conditions. For each integration step, this subroutine must transfer to the DERIV subroutine to get current values for the derivatives. When the new values have been calculated, the time is incremented by the time step, and the new variable values are stored as old values. This process is continued until termination condition is met. Not every step is printed. The first and last steps are

of ten in this program. The individual integration steps are printed by a short subroutine named PRINT.

It is the subroutine, DERIV, which evaluates the equations listed in the first pararaph of this appendix. These are the derivatives which are integrated in RUINT. The pressure is also evaluated in DERIV by use of the equation of state. The propellant burning equations require instantaneous values of the total area of the burning surface of all the propellant grains. This calculation is done by the subroutine, SURF. The version of SURF listed in this appendix calculates the burning surface of a number. N. of seven perf propellant grains. The number and the dimensions of the grains are transferred to the function subprogram through COMMON statements. The instantaneous values of the burned distances are transferred via the argument list to SURF. The derivation of the equations is given partly in Equations B-II-3. This gives the surface of the grains until the first burnout, when the seven perfs have grown enough to become tangent. Subprogram SURF has the equations required to calculate the grains to complete burnout. While these equations aren't very complicated, their derivations are complicated. Therefore, the derivations have not been included.

A sample data set and a computer run are included along with the listing of the program. These show the way the data must be arranged and the way that the results are organized.

```
PROGRAM TETHER (INPUT. OUTPUT. TAPES)
    REAL HU.N.OD.ID.L.HA.MAU.ML.HLV.JAY.STROKE
    LOGICAL BEDONE
    DIMENSION Y(30), NTERM(5), TERM(5)
    COMMON /STUFF/RHOP.BEE.EN.TF.GAM.MU.N.OD.ID.L.PA.MA.FRIC.MAV.
   +ML.NLV.ACS.APIS.CDD.AT.EPS.PRN.R.CD.CFVAC.STROKE
    EXTERNAL DERIV
    DATA GEE.JAY,R/32.174,778.,49709./
    NAMELIST /STUFF/N.OD.ID.L.PINIT.VO.RHOP.BEE.EN.TF.GAM, NW.D. NA.
   +FRIC.MAV.ML.MLV.ACS.APIS.CDD.AT.EPS.STROKE
    READ(8.100)N.OD.ID.L.PINIT.VO.RHOP.BEE.EN.TF.GAM, MU.D.MA, FRIC.
   +HAV.NL.NLV.ACS.AFIS.CDD.AT.EFS.STROKE
100 FORMAT(5F16.8)
150 READ STUFF
    PA=D+63.98+2116.8
    G1=(GAM-1.)/GAM
    GFUNC=GAN/2.+.5
    GFUNC=GFUNC**(-GFUNC/(GAM-1.))
    PRN=.2
200 PRNCLD=FRN
    PF=SQRT(2./(GAN-1.)*(1.-PRN**G1))
    PRN=(GFUNC/EPS/PF)**GAM
    IF(ABS((FRN-PRNOLD)/FRN).GT.1.E-6) GO TO 200
    CFVAC=EPS*(2./G1*PRN**(1./GAM)-PRN*(GAM+1.)/(GAM-1.))
    AC=SQRT(GAM*R*TF/MW)
    CD=GAM*GFUNC/AC
    PRINT 300. TF. GAM. MU. PRN. CFVAC, AC. CD + GEE, RHOP *. 01862. EN.
   +BEE+12+144.++EN.N.OD+12..ID+12..L+12..D.HA.MAV.ACS.
   +STROKE, VO.AT.APIS.CDD.HL.HLV.EPS.FRIC
    PRINT 350
300 FORMAT(//1PROFELLANT THERMODYNAMIC DATA1/5X1FLAME TEMP =1
   +F8.2' DEG R'/5X'SPECIFIC HEAT RATIO ='F6.4/5X'NOLECULAR WEIGHT ='
   +F6.2/5X'EXIT TO CHAMBER PRESSURE RATIO = F6.5/5X
   +/VACUUM THRUST COEFFICIENT =/F6.4/5X/SOUND SPEED =/F10.2/ FT/S*
   +/5X'DISCHARGE COEFFICIENT ='F8.6' LBM/S-LBF'
   +/5X/PROPELLANT DENSITY =/F8%5
   +< LBM/CU IN</5x*BURNING RATE EXPONENT #*F6.5/5X
   + BURNING RATE COEFFICIENT = FIO.8 IN/S-PSIA ///GEONETRIC /
   +<pro>+<pro>+<pro>+<pro>+<pro>+<pro>+<pro>+<pro>+<pro>+<pro>+fo,4In
   +/5%*ID =*F6.4* IN*/5%*LENGTH =*F8.5*, IN*//
   * 'ANCHOR AND LAUNCHER DATA '/5X 'DEPTH = 'F5.0' FT '/5X
   * ANCHOR HASS = "F6.2" SLUGS: //SX/ANCHOR VIRTUAL HASS = "F6.2" SLUGS"
   +/5x'anchor cross sectional area ='f8.4' so ft'
   +/5X/LAUNCHER STROKE =/F8.4/ FT//5X/INITIAL FREE VOLUME =/F6.4/ FT/
   +/5x'RCCKET THROAT AREA ='F8.5' SO FT'/5x'DRIVE PISTON AREA ='
   +F8.4' SO FT'/5X'ANCHOR DRAG COEFFICIENT = F8.6/5X
   + "LAUNCHER MASS = "F4.2" SLUGS "/5X "LAUNCHER VIRTUAL MASS = "
   +F6.2/ SLUGS//5X/NOZZLE AREA RATIO =/F8.4/5X
   + FRICTION FORCE = F10.24 LBF4///)
```

```
350 FORMAT(30X <---- VELOCITY---->
     +/<---DISPLACEMENT--->1/6X1TIME | WEB BURN | GAS MASS
                                              GAS VOL GAS TEMP PREST
                           ANCHOR LAUNCHER
     + ANCHOR LAUNCHER
               THRUST"/5X1(SEC)16X1(IN)
                                                      (FT/S)
                                           (SLUG)
                                                      (POUNDS) 7/7)
     +6X*(FT)*6X*(FT) (CU FT) (DEG R)
                                            (PSIA)
      DO 400 I=1.10
  400 Y(I)=0.
      Y(3)=PINIT+VO+MU/R/TF
      Y(3)=V0
      Y(9)=TF
      Y(15) =PINIT
      Y(16)=PINITAAT+CEVAC-EES+AT+PA
      NTERH(1)=10
      TERM(1)=STROKE
      CALL RUINT(10..0001.10..T..Y.1.NTERM.TERM.DERIV)
      READ* . BEDONE
      IF(.N.BEDONE) GO TO 150
      STOP
      END
      SUBROUTINE RUINT(NUM.H.NPRINT.INIT.YNEW.NTC.NTERH.TERH.DERIV)
      DIMENSION YNEW(30) LYOLD(30/.D(30).B(4).Q(4.30).NTERH(30).
     + TERM(30)
      INTEGER COUNT
      LOGICAL INIT
      EQUIVALENCE(YOLD(:).TOLD)
      DATA B(1).B(2)/.5..5/.B(3).B(4)/1..1./.COUNT.N/0.0/.B(;)/1./
      HH = - HH
      HSAVE-0.,
      N=COUNT+HOD(N-COUNT, NPRINT)
      IF(.NOT.INIT) GC TO.100
      CALL PRINT(NUM.YNEW)
      COUNT = 0
      N=NPRINT
50
       H=HH
       DO 150 J=1, NUM
100
150
       YOLD(J)=YNEU(J).
      DO 250 J=1.4
      CALL DERIV(NUM.YNEW.D.HH*B(J))
     .DO 200-I=1.NUK
      G(J,I)=D(I)+HH
200
```

YNEW(I)=YULD(I)+U(J.1)+B(J)
CONTINUE
DD 300 I=1.NUH
YNEW(I)=YOLD(I)+(G(1,I)+U(4,I))/6.+(U(2,I)+U(3,I))/3.
IF(HTC.GT.NTC) GD TO 380
DO 375 J=HTC.NTC
LTC=IABS(NTERH(J))
IF(YNEW(LTC)+NTERH(J).LT.TERH(J)+NTERH(J)) GO TO 375

250

300

```
HH=(TERM(J)-YNEW(LTC))/D(LTC)
       HSAVE=HSAVE+HH
       65 TG 100
375
       CONTINUE
380
        CONTINUE
       JF(HH.GT.O.) GG TG 400
       CALL PRINT (NUM.YNEW)
       HH=HSAVE
       PETURN
400
        COURT - COURTES
       18 700007.00.0700 10 50
       CALL PRINT (NUM. YNEW)
       N=N+NPRINT
       60 TO 50
       TNU
```

```
SUBROUTINE DERIVINUM.Y.D.DELT)
REAL NU.HA.HAV.ML.MLV.JAY
DIMENSION Y(30).D(30)
CONHOW /STUFF/RHCP.SEE.EN.TF.GAM.HU.N.OD.ID.L.PA.MA.FRIC.MAV.
FML.MLV.ACS.AFIS.CDD.AT.EFS.FFW.R.CD.CFVAC.STROKE
JAY=778.
Y(15)=Y(3)+R+Y(9)/MW/Y(8)
Y(16)=Y(15)#AT#(CFVAC-EPS#PA/Y(15))
D(2)=BEE+Y(15)++EN
SPR=RHOP*SURF(Y(2))*D(2)
IF (GFR.EQ.0.)D(2)=0.
GEX=Y(15)*AT*CD*SURT(TF/Y(9))
D(3)#SFR-SEX
t(4)=(APIS+(Y(15)-PA)-FRIC-.7944+ACS+Y(4)++2*CDD)/(MA+MAV)
D(5)=(APIS*(Y(15)-FA)-FRIC-Y(15)+AT*(CFVAC-EPS*FA/Y(15)))/(ML+MLV)
 ひくるシェイくもと
 D(7)=Y(5)
 B(10)=Y(4)+Y(5)
 5(8)=APIS*(Y(4)+Y(5))+GPR/RHOP
 D(9)=(Y(3)*Y(7)+BPR+DELT+TF)/(Y(3)+GPR+DELT)-(GAN-1.)*Y(9)/
+Y(8)+(D(3)-GPR/RHOP)
 RETURN
 END
```

```
SUBROUTINE PRINT(N.Y).

DIMENSION Y(30)

PRINT 100.Y(1).Y(2)(12..Y(3).Y(4).Y(5).Y(6).Y(7).Y(8).Y(9).Y(9).Y(15).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(16).Y(1
```

```
FUNCTION SURF(X)
 READ N.L.ID.GD.LO
 COMMON /STUFF/RHOP.BEE.EN.TF.GAM.NW.N.OD.ID.LO.PA.MA.FRIC.MAV.
+ML.MLV.ACS.APIS.CDD.AT.EPS.PRN.R.CD.CFVAC.STROKE
 PI=3.1415926536
 RIO=ID/2.
 R00=0D/2.
 RI=RIO+X
 RO=ROO-X
 L=L0-2.*X
 S=(RI+R0)/2.
 SURF = 0.
 IF(L.LE.O..OR.RO/RI.LE.3./(5.-2.*SORT(3.))) RETURN
 SURF=2.*PI*(L*(RO+7.*RI)+RO**2-7.*RI**2)*N
 IF(RI.LT.S/2.) RETURN
 BETA=ASIN((5.*RO-3.*RI)/4./RO)
 GAMMA=BETA-PI/3.
 EPSILON=ACOS((RO+RI)/4./RI)
 IDTA=ASIN(RO/RI+COS(BETA))
 ALPHA=2.*PI/3.-EPSILON-IOTA
 SIGMA=PI/3.-2.*EPSILGN
 SURF=6.*(2*L*(RO*GAMMA+RI*ALPHA)+RO*SIN(GAMMA)*SORT((2.*RI*SIN(
+ALPHA/2.))**2-(RO*SIN(GAMMA))**2)-RI**2*(ALPHA-SIN(ALPHA)) '
++.5*R0**2*(2.*GAMMA-SIN(2.*GAMMA)))*N
 IF(RI.GT.S/SQRT(3.)) RETURN
 SURF=SURF+(1.5*SQRT(3.)*S**2-9.*S*SQRT(RI**2-(S/2.)**2)
+-9.*RI**2*SIGMA+18.*RI*L*SIGMA)*N
RETURN
END
```

## TAPE8

150.	.31666667	.01666667	.5	864000.
1.	3.28	.0000044	.81	5750.
1.22	28.12	300.	200.	1000.
50.	700.	50.	3.	
1	.5	5.5	6.	
EDI ENCOUNTERED.	• •		•	

PROPELLANT THERMODYNAMIC DATA
FLAME TEMP = 5750.00 DEG R
SPECIFIC HEAT RATIO =1.2200
MOLECULAR WEIGHT = 28.12
EXIT TO CHAMBER PRESSURE RATIO =.02678
VACUUM THRUST COEFFICIENT =1.6516
SOUND SPEED = 3521.47 FT/5
DISCHARGE COEFFICIENT = .006584 LBM/S-LBF
PROFELLANT DENSITY = .06107 L7M/CU IN
BURNING RATE EXPONENT =.81050
BURNING RATE COEFFICIENT = .00295738 IN/S-PSIA

\$STUFF.

GECMETRIC FROPELLANT DATA
NUMBER OF GRAINS = 150.
OD =3.8060 IN
ID = .2000 IN
LENGTH = 6.00060 IN

ANCHOR AND LAUNCHER DATA

DEFIN = 300. FT
ANCHOR MASS = 200.00 SLUGS
ANCHOR VIRIUAL MASS = 50.00 SLUGS
ANCHOR CROSS SECTIONAL AREA = 3.0000 SQ FT
LAUNCHER STROKE = 6.0000 FT
INITIAL FREE VOLUME =1.0000 FT
ROCKET THROAT AREA = .50000 SQ FT
ANCHOR DRAG COEFFICIENT = .100000
LAUNCHER MASS = 700.00 SLUGS
LAUNCHER MASS = 700.00 SLUGS
NOZZLE AREA RATIO = 5.5000
FRICTION FORCE = 1000.00 LBF

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(SEC)	UEB BURR (IN)	648 8453 (3183)		LAUNCHER (FT/S)	CROR		948 985 250 750	688 (1887 (1880 3)	PARSSURE (FSTA)	THRUST	
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001	00.	2000	2,3203			000	200	2 47 2 47 2 47		) er	
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0500	.024550	9/404C*	16.8737	CCI CCI	0370	Ö	C-1	65 - 65 E 65 E 65	91.00	(3)	
0990	3206	000 to 100	1:540	1000	- () 3   1	90		50.00	111	52.13	
00	300	2000	6.513.0	356	$\circ$	CO	69	747.3	951.7	(S)	
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0	5349	9359	3.757	43	Ç.1	C-1	000	0.017	5000	3900	
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0130	9530	5558	0.952	761	10	C:3	C ;	685.3	r and	1000 1000 1000	
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021	0520	5412	3.691	44	r.,	ביי	, e	(21.3	8955.3	50.00	
27	158	0633	350.0	et (5)	10	(1	0 12 10	1.0110	S-11110	33.56	
67.7	639	4003	6.884	0.007	143	51	6% 60 -6	527.3	9577.4	1839	
CO CO	04 04 04	2965	3.633	::0::	€.1 •4±	C 1	학 단 단 :		3.0.00 0.00	100	
S.	3839	3766	0.472	1.608	Ç-3	C.2	acc.	117. 127. 128.	0105.3	3323	
002	7.30	.942235	7.394	स्य	52.55	9501	ř.,	579.1	10 to	5	
0	,;;	.60727	5000	(1)	.03⊹	1.8	10.45	10° 00 000	6.0720	307.6	
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(N)	3242	40.00	50000	100	C3 C3	C4 63	023	1000	M		
000	63 54 57	500	B7.0	9 9 9 7	(D)	; ! ; .	7 T		2034.9		
•		•									

2575010.	2587260.	2598517.	2608816.	2618191.	2626672.	2634290.	2641071.	2647043.	2652232.	2656661.	2660356.	2663339.	2665631.	2667256.	2665307.	2608257.	253/288.
22146.65	22249.66	22344.32	22430.93	22509.76	22581.09	22645.14	22702.17	22752.39	22796.02	22833.27	22864.34	22889.42	22908.70	22922.36	22905.98	22426.22	21829.43
5394.37	5377.85	5361.45	5345.18	5329.05	5313.07	5297.24	5281.57	5265.06	5250.71	5235.54	5220.54	5205.71	5191.05	5176.57	5162.26	5148.11	5136.22
5.3698	5.6024	5.8404	6.0836	6.3321	6.5859	6. 448	7.1088	7.3780	7.6523	7.9315	8.2158	8.5050	8.7990	6.0979	9.4003	9.6821	9.9103
2939	3163	3396	-,3638	3890	4150	4.20	4699	4987	5284	5591	5907	6232	6567	8911	7264	7627	7941
2.5426	2,7341	2.9331	3.1398	3.3541	3.5761	3.8058	4.0432	4.2883	4.5412	4.8018	5.0701	5.3462	5.6301	5.9217	6.2211	6.5282	6.7941
-21,9549	-22.8576	-23.7646	-24.6755	-25.5900	-26.5078	-27.4284	-28.3518	-29.2774	-30.2051	-31.1345	-32.0654	-32.9975	-33.9306	-34.8644	-35.7986	-36.7228	-37.4846
													•				317,2743
1.795845	1.888134	1.982747	2.079643	2.178727	2.280102	2.383569	2.489125	2.596717	2,706288	2.817779	2.931130	3.046280	3.163164	3.281717	3.397809	3.435736	3.431072
.251920	261725	.271565	.281437	291339	301268	.311221	321195	331189	.341199	.351224	.361260	.371307	.38:362	.391422	.401486	411468	.419748
.031000	.032000	033000	.034000	.035000	.036060	.037000	.038000	.039000	.040000	.041000	.042060	.043000	.044000	.645000	.046000	.047600	.047846

## APPENDIX B

# DIRECT ROCKET COMPUTER PROGRAM, INCLUDING ITS DESCRIPTION AND A SAMPLE CALCULATION

While the mechanism of the direct rocket PEA is significantly different from that of the recoilless PEA, their performances can be simulated by very similar computer programs. The recoilless PEA has two parts which move differently, although interdependently. The anchor moves forward under the force of the gas pressure acting on a piston, less the internal and external frictions. The recoilless launcher is accelerated backward by the same force, a pressure on a piston. This force is diminished by the same small internal friction that affects the anchor and by the very large rocket thrust. The net force acting on the launcher should be vey small as compared to the force acting on the anchor. Since the net force acting on the launcher is a small difference between two large forces, that small net force could be positive or negative. A positive force would cause the launcher to accelerate to the rear; a negative force would accelerate it forward. Regardless of the sign of the force, its magnitude will be reduced by the external friction. The effective masses of the anchor and the launcher are both increased by their virtual. masses. The mass of the launcher is steadily decreasing because of the propellant gases being ejected. The temperature of the gases inside the combustion chamber and piston must be computed continuously because the gas is doing expansion work and new propellant gas is continuously being mixed with the ider gas.

The direct rocket moves as a single unit; therefore, only one velocity and displacement must be integrated. There is no internal drag. The force accelerating the whole system is equal to the rocket thrust less the external hydrodynamic force. The net mass is increased by the virtual mass and decreased by mass of the propellant gas exhausted. The propellant temperature remains constant inside the combustion chamber, because the gas does no expansion work until it reaches the nozzle.

Because the details of the calculations are so similar to those of the recoilless PEA, it was most efficient to modify the recoilless program to handle the direct rocket. The SURF subprogram was changed to handle single perf propellant grains because the direct rocket does not need a progressive burn.

```
PROGRAM DIRROC(INPUT.OUTPUT.TAPES)
    REAL MU.N.OD.ID.L.MA.MAV.JAY.STROKE
    LOGICAL BEDONE
    DIMENSION Y(30).NTERM(5).TERM(5)
    COMMON /STUFF/RHOP.BEE.EN.TF.GAM.MW.N.OD.ID.L.PA.MA.MAV.
   HACS.CDD.AT.EPS.PRN.R.CD.CFVAC.STROKE
    EXTERNAL DERIV
    BATA GEE.JAY.R/32.174,778.,49709./
    NAMELIST /STUFF/N.OD.ID.L.PINIT.VO.RHOP.DEE.EN.TF.SAM.MU.D.MA.
   *MAV.ACS.CDD.AT.EPS.STROKE
    READ(8.100)N.OD.ID.L.PINIT.VO.RHOP.BEE.EN.TF.GAM.MW.D.MA.
   +MAV.ACS.CDD.AT.EPS.STRCKE
100 FORMAT(5514.8)
150 READ STUFF
    PI=4.*ATAN(1.)
    BA≈D#63.78+2116.8
    G1≈(GAM-1.)/GAM
    GFUNC=GAM/2.+.5
    GFUNC=SFUNC**(-GFUNC/(GAN-1.))
    PRN=.2
200 PRNOLD=PRN
    PF=SQRT(2./(GAM-1.)*(1.-PRN**G1))
    PRN=(GFUNC/EPS/PF)**GAM
    IF(ABS((PRN-PRNGLD)/PRN).GT.1.E-6) GD TO 200
    CFVAC=EPS*(2./61*PRN**(1./GAM)-PRN*(GAM+1.)/(GAM-1.))
    AC=SQRT(GAM*R*TF/MU)
    CD=GAH*GFUNC/AC
    PROPM=N#RHOP#PI#L#(CD##2-ID##2)/4.
    PRINT 300.TF.GAM.MU.PRN.CFVAC.AC.CD*GEE.RHOP*.01862.EN.
   +BEE*12*144.**EN.N.OD*12.,ID*12..L*12..D.MA.MAV.PROPM.ACS.
   +STROKE.VO.AT.CDD.EPS
    PRINT 350
300 FORMAT(// PROPELLANT THERHODYNAMIC DATA //5X FLAME TEMP =
   +F8.2' DEG RY/5X'SPECIFIC HEAT RATIO = F6.4/5X'MOLECULAR UEIGHT =
   +F6.2/5X/EXIT TO CHAMBER PRESSURE RATIO = F6.5/5X
   + "VACUUM THRUST COEFFICIENT = "F6.4/5X "SOUND SPEED = "F10.2" FT/S"
   +/5% DISCHARGE COEFFICIENT = FE.6 LBM/S-LBF C
   */SX'PROPELLANT BENSITY = FS.S
   + LBN/CU IN /SX/BURNING RATE EXPONENT + Fo.5/5X
   * * BURNING RATE COEFFICIENT # * F10.8 * IN/5-FSIA * / / CEOMETRIC
   * PROPELLANT DATA 1/5% NUMBER OF HONOPERS GRAINS # 1/8.0 ...
   +/5X10D = F6.41 IN1/5X1ID =1F6.41 IN1/5X1LENGTH =1F8.51 IX1//
   + SYSTEM DATA / SX DEPTH + CFS. O C RT C / SX
   + "SYSTEM HASS = "F6.2" SLUGS" / SX SYSTEM VIRTUAL HASS = "F6.2" SLUGS
   */5X*PROPELLANT MASS #*F10.4* SLUGS*
   +/5x/system cross sectional area = fo.4/ sq ft/
   +/5x/STROKE +/F8.4/ FT//5x/INITIAL FREE VOLUME +/F7.4
   +/5x/ROCKET THROAT AREA #/F8.5/ SQ FT/
   +/5x'ANCHOR DRAG COEFFICIENT = F8.6
   +/5x/NOZZLE_AREA_RATIO_=/F8.4///)
```

```
350 FORMAT(6X'TIME WEB BURN GAS MASS PROP'MASS'
     THRUST //SX*(SEC) /6X*(IN)
     # 1SURE
                                          (SLUS)
                                                      (SLUG)
                                                                (FT/S)/.
     +6X (FT)
               (00 71)
                           (PSIA) (POUNDS)(//)
      DO 400 I=1.10
  400 9(1)=0.
      Y(3)=PINIT: VO: MU/R/TF
      4(7)=00
      Y(4) =PROPM
      Y(9)=TE
      Y(15)=PINIT
      Y(16)=PINITHATHORUAC-EPSHATHPA
      MTERM(1)=6
      TERM(1)=STROKE
      CALL RUINT(7..0001.10..T..Y.1.HTERM.TERH.DERIV)
      PRINT 500
  500 FORMAT(//100 YOU WANT TO STOP (.T.) OR CONTINUE (.F.) COMPUTING?()
      READ+.BEDONE
      IF (.N.BEDONE) 30 TO 150
      STOP
      END
      SUBROUTIME RUINTIMUM.H.MPRIMT.IMIT.YMEW.MTC.MTERM.TERH.DERIU)
      DIMENSION YNEW(30).YOLD(30).D(30).B(4).Q(4.30).NTERH(30).
     + TERM(30)
      INTEGER COUNT
      LOSICAL IDIT
      COULYALENCE (YOUD: 1), FOLD:
      BATA D(1).9/2)/.5..5/.8(3).8(4)/1..1./.00UNT.N/0.0/.b(1)/1./
      38=-40
      .
CTRINGN.THUDO-W)GOK+THUOC+H
      MTC=1
      18 (.037.1017) 50 10 100
      CHIL BEINICHBATANERS
      1000
      1-428147
       57 150 Jan.898
      Y710())=Y824())
130
     . DO 200 Jet.: 🗝
      CALL RESIV(NUS. YMEQ. D. RESERVIN)
      DO 000 $-1.49k
      212221-2121-61
200
      YMCG: 11440000: 74 G: 11.1148(3)
250
      CONTINUE
      50 300 Ist.#UM
      4852412.47000412.47511.11.40(4.100/8.440(2.11.4013.12).3.
      IF (x10.07.210) 30 to 300
     po pre dianciare
     LTC=IABSINTER (U))
      IF COMEDICATION AFTERMIND LLT. TERMIND) INTERMIND) GO TO 375
```

```
MTC=J+1
      HH=(TERM(J)-YNEW(LTC))/B(LTC)
      HBAVE=HBAVE+RH,
      60 10 100
375
      CONTINUE
      SUNITABO
330
      IE(HH.ST.O.) SO IS 400
      CALL PRINT (NUM.YMEU)
      BYASHSAVE
      RETURN
       COUNT =00UNT91
400
      IF (COUNT.NE.N)GG TG 50
      CALL PRINT (NUM. YNEW)
      N=N+NPRINT
      GO TO 50
      END
```

```
SUBROUTINE DERIVINGH. Y.D. DELT)
REAL MULIALBAV. JAY
DIMENSION Y(30).D(30)
CORMON /STUFF/RHOP.BEE.EN.TF.GAM.MW.N.OD.ID.L.PA.MA.HAV.
+ACS.CDD.AT.EPS.PRN.R.CD.CFVAC.STROKE
JAY=778.
Y(15)=Y(3)+R+TF/M4/Y(7)
Y(16)=Y(15)+AT+(CTVAC EPS+PA/Y(15))
D(2)=BEE+7(15)**E%
GPR=RHOP*SURF(Y'(2))+D(C)
IF (GPR.EG.0.:0(2)≈0.
GEX=Y(15)+AT:CD
D(3)=6PR-GEX
 D(4) = -GEX
 DRAG=.7944*ACG*Y(S)++C+CDD
 D(5)=(Y015)*AT**CFVAC-ZDD*PAZY(CD)() ORAS)/(CAL-Y07):HAV?
 D(6)=Y(5)
 D(7)=SPR/SHCP
 RETURN
 END
```

SUBROUTINE PRINTED.Y)
DIMENSION Y(30)
PRINT 100.Y(1).Y(2):121.Y(3).Y(4).Y(5).Y(5).Y(7)
(Y(15):144..Y(16)
100 FORMAT(3F10.6.4F10.4.F10.2.F10.0)
RETURN
FND:

```
FUNCTION SURF(X)
    REAL N.L.ID.OD.LO
    COMMON /STUFF/RHOP.BEE.EN.TF.GAM.MU.N.GB.ID.LO.PA.MA.MAV.
    +ACS.CDD.AT.EPS.FRW.R.CD.CFVAC.STROKE
    PI=3.1415926536
    RIO=ID/2.
     R80=8D/2.
     RIBRIORA
     RO=ROC-X
    L=L0-2.*X
     SURF≓G.
     IF(L.LE.O..OR.RO.LE.RI) RETURN
     SURF=2.4PI4(RO+RI)*(L4RO-RI)*N
    RETURN
     END]
-END OF FILE
```

TAREC

700.	.125	.01446467	.5	1440000.
10.	3.23	.0001	. 6	5750.
1.22	28.12	300.	200.	50.
3.		.525	5.5	å.

FLAME TENP = 5750.00 DEG R
SPECIFIC HEAT-RAIID =1.2200
MOLEGULAR WEIGHT = 28.12
EXIT TO CHAMBER PRESSURE RAIID =.02578
VACUUN THRUST COEFFICIENT =1.6516
SCUND SPEED = 3521.47 FT/5
DISCHARGE CCEFFICIENT = .06584 LBM/S-LBF
PROFELLANT DEWSITY = .06107 LBM/CU IN
BURNING RAIE EXPONENT =.66600
LURNING RAIE COEFFICIENT = .02367003 IN/S-FSIA

PROPELLANT THERNODYNAMIC DATA

GEONETRIC PROFELLARY DATA
NUMBER OF MOMOFERF GRAINS = 700.

OD =1.5000 IN
ID = .2000 IN
LENGTH = 6.00000 IP

SYSTEM MASS = 200.00 SLUSS
SYSTEM MASS = 200.00 SLUSS
SYSTEM CACKS = 13.8376 SLUSS
SYSTEM CACKS SECTIONAL AREA = 5.6000 SR FT
STAGKE = 6.0000 FT
INITIAL FREE VOLUME = 10.0000 FT
ACCKET THROAT AREA = .52500 SR FT

GAS MASS FROP MASS VELOCITY DISTANCE GAS VOL F (SLUG) (FI/S) (FI) (CU FI) (CU FI) (1,41669) 13.8376 0.0000 0.0000 10.0004 1.515516 13.6268 4.6894	1566.72 12315.33 13036.98 13729.57
6AS MASS FROF MASS VELOCITY DISTANCE (SLUS) (FLVS) (FT/S) (FT) (FT) (FT/S) (5LUS) (5LUS) (FT/S) (5LUS) (5LU	1300
6AS MASS FROF MASS VELGCITY DI (SLUG) (SLUG) (FI/S) 1.416690 13.8376 0.0000	10.1784 10.2726 10.3699 10.4700
645 MHSS FROF MASS (SLUG) (SLUG) (SLUG) (SLUG) 1.416690 13.8376	.0095
645 Kinss Fra (SLUG) (SLUG) 1.416690	20.9608 27.0808 27.0808 27.0808
645 Km55 (SLUG) (SLUG) 1.416690	13.5048
2 X X 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	, , , , , , , , , , , , , , , , , , , ,
報 0000 第 2000 第 2000 第 2000 第 2000 第 2000 第 2000 第 2000 第 2000 第 2000 8 2000	10 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
41186 (S) 000 000 000 000 000	1

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735438	1414	œ	5839	100	088364	4583	201382	C-1	29910	34250	382427	41899	45234	48259	0660	**	5616	7537	592150	• • •	61834	~	63715	64343	64793;	65075	5196	65167	54996	64689	64256	59377	39749	19159
		<b></b>		õ	C-1	C)	CA CA	C-1	C-1	C.1	£.1	2.4	CI	£.1	C-1	c.i	CA.	C4	£-3	C4	C.1	c.₁	24	£.1	C-1	C-1	C4	CA	C.1	CA	CA	23	23	23
57		œ	C-1		8.10	6.35	3.21	9.43	5.87	4	3.15	6.01	3.03	5.40	4.06	0.10	'n	8.46	2.79	8,51	•		3.22	3.53	75.6	22:09	31.85	9.52	5.13	1.26	6.56	5.82		6.56
1439	15021	1551	1518	16717	17218	17686	± 0 €	1.00	18905	:9253	19573	19366	2013;	20375	2059	20790	2096	57	21252	2136	21456.	2154	21613	21663	21699	2172	2173	2172	2471	2169	2165	21265	1969	19646
Ç-1	37.6	847	.8937	0043	165	66€	3446	<b>209</b>	766	737	8114	295	5/4	664	851	038	223	407	7568	39%	939.	11103	.2271	429	580	5725	862	286	113	227	331	2190	190	-
10.57	10.5	10.7	10.8	11.0	•			•	-	•		•	12.0	12.1	•	•	•	•	•	<u>54</u>	•			13.3	•	•	13.6	•	13.9	14.0		4.2	14.2	14.2
43		<b>~</b>	65	4.4	90	~T	**	83	<del>-</del> -	5,	53	73	င်	02	49	2.6	235	75	010	26	26	<b>0</b>	မာ တ	32	782	435	9:	S.		29	248	520	893	00
.03	**		ca Ca	.2844		4	50	בים	Ç.5.	305	.922	1.042	1.135	1.330	1.484	1.649	æ	٥,	64	٦.	٠,	•	•	3,323	.67	<b>c</b> 3	•	4.405	4.701	5.007	r.	5.65	Ç.	9.00
~			0	ٔ د	٠	۰.	20.7	(0	12	C.1	۲٦		C^		œ	~	0	G	co	۰,	_	٠,		<b>~</b> 7	۰.۰		C-1	<b>.</b>	۲.	۲.		_		_
525.	c.i	.3419	681	288	[\ 45 1-	245	נט	250.	3.823.	2,7300	803	.035	30	9:3	536	268	660.	0166	25.0128	.077	.202.	,373;	.598	8	.133		765	. 694	426	350	.0781	364	1001.	.393(
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DO YOU WANT TO STOP (.T.) OR CONTINUE (.F.) COMPUTING? ? .T.

#### APPENDIX C

# WATER JET COMPUTER PROGRAM, INCLUDING ITS DESCRIPTION AND A SAMPLE CALCULATION

The flow equations and their derivatives were not included in the main text because their derivation is too lengthy and complex. This appendix also includes the computer program which evaluates these equations and gives a detailed view of the events that happen during the .040 seconds of a launch. The input data and a typical run are included.

Only two of the Navier Stokes Equations are needed because the flow is incompressible. The two equations needed are the equations of conservation of mass and momentum. The equation for the conservation of mass is

C-1 
$$\rho A(z) U(z,t) = \rho A(x) U(x,t).$$

Since the flow is incompressible, the densities on both sides of Eqn. C-1 are equal and can be canceled. It is more convenient to express the flow areas, A(z) and A(x), as the product of the main barrel flow area,  $A_0$ , and a function G(x) or G(z). The term, G(z), gives the flow area at any point along the length, z, as a fraction of  $A_0$ . With the water tube shape discussed in the text, G(z) has a value of 1 through the straight portion of the tube and less than one in the convergent nozzle. G(x) represents the area at x, the position of the gas-water interface. Again, both sides have equal terms,  $A_0$ , and they can be canceled. This simplifies Eqn. C-1 to

$$G(z) U(z,t) = G(x) U(x,t)$$

The one-dimensional momentum equation is

C-3 
$$\frac{1}{\rho} \frac{\partial P(z,t)}{\partial z} + \frac{\partial U(z,t)}{\partial t} + U(z,t) \frac{\partial U(z,t)}{\partial z} = 0$$

Rearranging Eqn. C-2 gives

$$U(z,t) = U(x,t) \frac{G(x)}{G(z)}.$$

Taking a partial derivative with respect to z gives

C-5 
$$\frac{\partial U(z,t)}{\partial z} = -U(x,t) G(x) \frac{G'(z)}{G^2(z)},$$
 where 
$$G'(z) = \frac{dG(z)}{dz}.$$

Taking a partial derivative of U(z) with respect to t gives

C-6 
$$\frac{\partial U(z,t)}{\partial t} = \frac{dU(x,t)}{dt} \frac{G(x)}{G(z)} + U^{2}(x,t) \frac{G'(x)}{G(z)}.$$

The reader should be warned that U(x,t) is not standard notation. It is used to signify the water velocity at any time where z=x. That explains why there is no derivative with repect to z and why the derivative with respect to time is not a partial derivative. Substituting Equations C-4, 5, and 6 into Equation C-3 gives

C-7 
$$\frac{1}{\rho} \frac{\partial P(z,t)}{\partial z} + \frac{dU(x,t)}{dt} \frac{G(x)}{G(z)} + U^{2}(x,t) \frac{G'(x)}{G(z)} - U^{2}(x,t) G^{2}(x) \frac{G'(z)}{G^{3}(z)} = 0.$$

Now multiply Eqn. C-7 by dz and integrate over z from x to L.

C-8 
$$-\frac{P(x,t) - P(L,t)}{\rho} + G(x) \frac{dU(x,t)}{dt} \int_{X}^{L} \frac{dz}{G(z)} + U^{2}(x,t) G'(x) \int_{X}^{L} \frac{dz}{G(z)}$$

$$+ U^{2}(x,t) G^{2}(x) \left[ \frac{1}{G^{2}(L)} - \frac{1}{G^{2}(x)} \right] = 0 .$$

Now solve Eqn. C-8 for  $\frac{dU(x,t)}{dt}$ 

$$C-9 \qquad \frac{dU(x,t)}{dt} = \frac{P(x,t) - P(L,t) - \frac{1}{2}\rho U^{2}(x,t) \left[1 - \frac{G^{2}(x)}{G^{2}(L)}\right]}{\rho G(x) \int_{x}^{L} \frac{dz}{G(z)}} - U^{2}(x,t) \frac{G^{*}(x)}{G(x)}.$$

Eqn. C-9 can be integrated with respect to time to give the velocity of the gas-water interface as a function of time. This velocity, in turn, can be integrated with respect to time to give the position of the gas-water interface as a function of time. In order to integrate Eqn. C-9, one needs to be able to calculate the pressure P at x and L for all times in the domain of the

calculation. Similarly, one needs a function for G(z) so that G(x), G(L), G'(x), and the integral of the reciprocal of G(z) from x to L. G(z) has a constant value of one (1) for values of z from zero to  $L_s$ ; therefore, G'(z) equals zero over that range of z. The value of G(z) decreases monotonically from one to the minimum value as z goes from  $L_s$  to L. Consequently, the value of G'(z) is negative in this range. Because G(z) is determined by two different functions in the two regions, it is necessary to evaluate the integral of the reciprocal of G(z) in two steps. (This breakup should only be used when x is less than  $L_s$ .)

$$\int_{x}^{L} \frac{dz}{G(z)} = \int_{x}^{L} s \frac{dz}{G(z)} + \int_{L}^{L} \frac{dz}{G(z)}, \quad \text{where } x \leq L_{s}.$$

G(z) has a constant value of one (1) while z is in the interval from zero to  $L_s$ . Therefore, the first integral on the right-hand side of Eqn. C-10 simplifies to the integral of dz over the same range. That integral reduces to  $L_s$  - x.

$$C-11 \qquad \int_{x}^{L} \frac{dz}{G(z)} = L_{s} - x + \int_{L_{s}}^{L} \frac{dz}{G(z)}, \quad \text{where } x \leq L_{s}.$$

When x is greater than  $L_S$ , the integral is not broken up. It is evaluated by integrating directly from x to L.

To calculate x, the distance traveled by the gas-water interface, it is necessary to integrate the following equations.

C-12 
$$\frac{dx}{dt} = U(x,t)$$

The boundary conditions for the velocity and the distance are

C-13 
$$U(x,t) = 0$$
 when  $t = 0$   
C-14  $x = 0$  when  $t = 0$ 

As with the other two PEA options, it is necessary to be able to calculate the pressures, P(x,t) and P(L,t). In an all-up analysis, the pressures would be calculated from first principles as was done for the recoilless and direct rocket PEAs. This was not done for the water jet PEA computer program. The pressures were set to constant values. Even though the actual

pressure would not be precisely constant, it would not be very far off. This simplification saved time and permitted many runs to be compared without the secondary effects of pressure variation blurring the relationships.

There is another shortcoming in the analysis as it is presented here. No account is taken of the mass of the propellant gas in the dynamic equations. Some of the energy from the expanding gas must be used to accelerate the ass as well as the water. The density of the gas is about one tenth that  $\infty$  water when the pressure is 10,000 psi and two tenths when the pressure is 20,000 psi. The added mass of the gas is insignificant at the start of the cycle when most of the tube is filled with water. Although the quantity of gas is greater during the main mid-portion of the run, it is also insignificant there because the acceleration is zero then. The only time that it has a significant effect is very near the end of the cycle, when there is very little water and the mass of the gas exceeds that of the water. Only the last part of the cycle is significantly affected by the mass of the gas. The acceleration of the interface would be very high and approach infinity as the denominator of the main term in Equation C-9 goes to zero. In reality, the mass of the gas would prevent this from happening, but that mass does not show in Equation C-9. The computer program in this appendix handles this in a nonrigorous, but effective, way.

Equation C-9 gives the acceleration of the gas water interface. If one multiplies the numerator and denominator of the main term by the term  $A_0$ , then one can see that that first term is a force divided by a mass (an acceleration). In the enclosed program, the mass of the gas is given as the product of the mass density of the water and the effective length of the gas column (Again  $A_0$  has been factored out.) In the program, this mass of gas per unit area is added to the mass of water per unit area in the denominator of the main term.

```
PROGRAM PEA(INPUT.OUTPUT)
     COMMON L.LM.GL.RHG.FX.PL.AO
     DIMENSION Y(30), NTERM(5), TERM(5)
     REAL I.L.LS.LN.NINTS
     LOGICAL BEDONE
     EXTERNAL DERIV
     NAMELIST /AGAIN/PX.DEPTH.L.LN.GL.AO.TSTEP.NPRINT
     RHO=1.7545
     BEDONE = . F.
     PRINT 50
  50 FORBAT('1 TYPE IN VALUES FOR PX.DEPTH,L.LN.GL.AO.TSTEP.NPRINT')
     READ *.PX.DEPTH.L.LN.GL.AO.TSTEP.NPRINT
     PL=14.7+DEPTH+.4367
     DO 200 Jel.30
 200 Y(J)=0.
     PRINT 300.PX.PL.BEPTH.L.LN.A0.GL*A0.TSTEP

    300 FORMAT('1 INPUT DATA'/5X'DRIVE PRESSURE #'F10.2' PSIA'/5X;

    ACAMBIENT PRESSURE =1F10.21 PSIA1/5X1DEPTH = 1F4.01 FEET1/5X
    BYTUBE LENGTH = 1F8.41 FEET//SX1NOZZLE LENGTH1F8.41 FEET//5X
    CICHANNEL CROSS SECTION = F8.47 SQ FEET//SX/NOZZLE AREA = F8.4
    D' SO FEET // 5X 'INTEGRATION STEP = 'E10.3' SEC'
                                             THRUST
    E///6X/TIME DISTANCE/6X/V(X)/6X/V(Y)
    F5X1(SEC)
                            (FT/S)
                                      (FT/S)
                                                (POUND)
                                                           (LB-S)(//)
     NTERM(1)=3
     TERM(1)=.2974L
     CALL PUINT (4.TSTEP.NPRINT..T..Y.1.NTERM.TERM.DERIV)
     PRINT 400
 400 FORMAT(////)
     READ AGAIN
     IF (.NOT.BEDDIE) GO TO 100
     END
```

```
SUBROUTINE RUINT (NUM. H. NPRINT, INIT, YNEW, NTC, NTERM, TERM, DERIV)
DIMENSION YNEW(30).YOLD(30).D(30).B(4).Q(4.30).NTERM(30).
+ TERM(30)
INTEGER COUNT -
LOGICAL INIT
EQUIVALENCE (YOLD (1), TOLD)
DATA B(1).B(2)/.5,%5/,B(3),B(4)/1.,1./.COUNT,N/0.0/,D(1)/1./
HH=-HH
HSAVE = 0.
N=COUNT+HOD(N-COUNT.NPRINT)
MIC=1
IF (.NOT.INIT) GD TO 100
CALL PRINT(NUM.YNEW)
COUNT=0
N=NPRINT
 HH=H
```

50

BG. 150 J=1.NUM

```
150
       YOLD(J)=YNEW(J)
      DO 250 J=1.4
      CALL DERIV(NUM.YNEW.D)
      DO 200 I=1.NUM
      Q(J,I)=D(I)*HH
200
       YNEW(I)=YOLD(I)+Q(J,I)*B(J)
250
       CONTINUE
      DO 300 I=1.NUM
300
       YNEW(I)=YOLD(I)+(Q(1,I)+Q(4,I))/6.+(Q(2,I)+Q(3,I))/3.
      IF(MTC.GT.NTC) GO TO 380
      DO 375 J=MTC.NTC
      LTC=IABS(NTERM(J))
      IF(YNEW(LTC)*NTERH(J).LT.TERH(J)*NTERH(J)) GO TO 375
      HH=(TERM(J)-YNEW(LTC))/D(LTC)
      HSAVE=HSAVE+HH
      GD TO '00
375
       CONTINUE
380
      · CONTINUE
      IF(HH.GT.O.) GO TO 400
      CALL PRINT (NUM.YNEW)
      HH=HSAVE
      RETURN
400
       COUNT =COUNT+1
      IF (COUNT.NE.N)GO TO 50
      CALL PRINT (NUM. YNEW)
      N=N+NPRINT
      GO TO 50
      END
```

```
SUBROUTINE DERIV(NUM.Y.D)

COMMON L.LN.GL.RHO.PX.PL.AO

REAL L.LN.LS

DIMENSION Y(30).D(30)

B(1)=1.

CALL NOZ(Y(3).GX.GPRIME,GINT.RAT)

B(2)=((PX-PL)*144./RHO+.5*Y(2)**2*(1.+(GX/GL)**2-RAT*(1.+GX**2)))

A/GX/GINT-Y(2)**2*GPRIME/GX

D(3)=Y(2)

D(4)=RHO*AO*GX*((L-Y(3))*D(2)+Y(2)**2*(GX/GL-1.))

Y(20)=D(4)

Y(21)=Y(2)*SX/GL

RETURN
```

END

```
SUBROUTINE NOZ(X.GX.GPRIME.GINT.RAT)
   COMMON L.LN.GL.RHO.PX.FL.AO
   REAL L.LN.LS
   LS=L-LN
   IF(X.GT.L*.99999999) X=L*.99979999
   PI=3.14159
   RAT=PX*6.24E-6
   GPRIME=0.
   GX=1.
   GINT=RAT*X+LS-X+LN/SQRT(GL)
   IF(X.LE.LS) RETURN
   GX=(1.+GL)/2.+(1.-GL)/2.*COS(PI*(X-LS)/LN)
   GPRIME=(GL-1.)*PI/2./LN*SIN(PI*(X-LS)/LN)
   TERM=2.*LN/PI/SQRT(GL)*ATAN(SQRT(GL)*TAN(PI*(X-LS)/2./LN))
   GINT=RAT*(LS+TERM)+LN/SQRT(GL)-TERM
   RETURN
   END
   SUBROUTINE PRINT(NUM.Y)
   DIMENSION Y(30)
   PRINT 100,Y(1),Y(3),Y(2),Y(21),Y(20),Y(4)
100 FORMAT(F10.6.F10.4.2F10.3.2E10.3)
   RETURN
   END
```

```
1 TYPE IN VALUES FOR PX.DEPTH.L.LN.GL.AO.TSTEP.NPRINT
7 20000..300..7..1...1.2.65..00001.100
1 INPUT DATA

DRIVE PRESSURE = 20000.00 PSIA

AMBIENT PRESSURE = 145.71 PSIA

DEPTH = 300. FEET

TUBE LENGTH = 7.0000 FEET

NOZZLE LENGTH 1.0000 FEET

CHANNEL CROSS SECTION = 2.6500 SQ FEET

NOZZLE AREA = .2650 SQ FEET

INTEGRATION STEP = .100E-04 SEC
```

TIME	DISTANCE	V(X)	V(Y)	THRUST	IMPULSE
(SEC)	(FEET)	(FT/S)	(FT/S)	(POUND)	(LB-S)
(323)	11 0011		,,,,,,		
0.001600	0.0000	0.000	0.000	0.,	0.
.001000	.0705	125.667	1256.668	.342E+07	.484E+04
.002000	.2203	163.966	1639.658	.177E+07	.725E+04
.003000	.3886	170.709	1707.092	.144E+07	.881E+04
.004000	.5600	171.733	1717.334	.139E+07	.102E+05
.005000	.7318	171.881	1718.811	.138E+07	.116E+05
.006000	.9037	171.902	1719.016	.138E+07	.130E+05
.007000	1.0756	171.904	1719.044	.138E+07	.143E+05
.008000	1.2475	171.905	1719.047	.138E+07	.157E+05
.009000	1.4194	171.905	1719.048	.138E+07	.171E+05
.010000	1.5913	171.905	1719.048	.138E+07	.185E+05
011000	1.7632	171.905	1719.048	.138E+07	.199E+05
.012000	1.9351	171.905	1719.048	.138E+07	.212E+05
.013000	2,1070	171.905	1719.048	.138E+07	.226E+05
.014000	2.2789	171.905	1719.048	.138E+07	.240E+05
.015000	<del>-</del> <u>-</u>	171.905	1719.048		.254E+05
.016000		171.905	1719.048	.138E+07	.267E+05
.017000		171.905	1719.048	.138E+07	.281E+05
.018000		171.905	1719.048	.138E+07	.295E+05
.019000		171.905	1719.048	.138E+07	.309E+05
.020000		171.905	1719.048	.138E+07	.323E+05
.021000		171.905	1719,048	.138E+07	.336E+05
.022000		171.905	1719.048	.138E+07	.350E+05
.023000		171.905	1719.046	.138E+07	.364E+05
.024000		171.905	1719.048	.138E+07	.378E+05
.025000		171.905	1719.048	.138E+97	.371E+05
.026000		171.905	1719.048	.138E+07	.405E+05
.027000		171.905	1719.048		.419E+05
.028000		171.905	1719.048	.138E+07	.433E+05
.029000		171.905	1719.048	.138E+07	.447E+05
.030000		17,1.905	1719.048		.460E+05
.031000		171.905	1719.048	.138E+07	.474E+05
032000		171.905	-1719.048		.483E+05
.033000		171.705	1719.048	.138E+07	.502E+05
.034000		121.905	1719.048	.138E+07	.515E+05
.035000		171.905	1719.048		
.033000		173.337	1719.094	.142E+07	.543E+05
.037000		176.648	1720.661	.131E+07	.558E+05
.038000		296.886	1729.629	.163E+07	.573E+05
.038808		2235.200	2257.625		.585E+05
				•	

#### APPENDIX D

# SYSTEM SIZE AND WEIGHT COMPUTER PROGRAM, INCLUDING ITS DESCRIPTION AND A SAMPLE CALCULATION

The BASIC computer program included in this appendix calculates a matrix of weights and dimensions of water jet PEA launchers. The program was coded to assume that all of the water jet launchers had to deliver 5.76 x  $10^4$  footpounds of impulse at a thrust level of 1.44 x  $10^6$  pounds. It also assumes that all of the launchers are made of steel with a weight density of 492 pounds per cubic foot. Within these constraints, the weights and dimensions of the water jet PEA launcher were calculated for a matrix of values of the inside diameter of the water tube, the driving pressure, and the yield stress of the structural material.

Four equations from the main text are needed to calculate the dependent variables. Equation E-I-1 is needed to calculate the inside diameter of the launch tube; Equation E-I-5 to calculate the weight of the launch tube; Equation E-I-10 to calculate the length of the water tube; and Equation E-I-13 to calculate the weight of the water tube. The total system weight calculated in this program does not include the weights of the anchor, piston, propellant, or water. It is the sum of the weights of the launch tube and the water tube.

```
00100 MARGIN 132
00110 R1 = 1.9997
00120 READ I3.I. RO
00130 READ P1,P2,F3
00140 READ D1,D2.D3
00150 READ $1.52.53
00160 F9=4 +ATN(1)
00170 FOR D=D1 TO D2 STEP D3
00180 A=P9+B12/4
00190 PRINT "INSIDE DIAMETER OF WATER TUBE ="D" FEET. ":
00200 PRINT "WATER TUBE CROSS SECTIONAL AREA ="A" SQUARE FEET.
00210 PRINT "TOTAL IMPULSE ="13" FOUND SECONDS."
00220 PRINT "THRUST ="T" FOUNDS."
00230 PRINT
00240 PRINT TAB(21); "WATER TUBE"
00310 PRINT
00320 PRINT "YIELD STRESSES (PSI)- ------";
00330 FOR S=S1 TO $2 STEP S3
00340 PRINT USING "#########; $/144;
00350 NEXT S
00360 PRINT
00370 FRINT
00380 FOR P=P1 TO P2 STEP P3
00390 V=I3/SOR(2+R1+(P-T/A))
00400 L=V/A+D/3
OC410 PRINT USING | OG420. P/141:00P/T+4/P/P9);L;
00420 : ######### ##### #####. ##
00430 FOR S=S1 TO S2 STEP S3 4
00449 W0=R0+12+T/(S-2+P)
90450 W=R0*P*D*(2*(L-D)/($-2*P)+9/($-1.5*P))+WO
00460 PRINT USING 00470, U;
00470 : ######
00480 NEXT S
00490 PRINT-
```

```
00500 NEXT P
00510 PRINT
00520 PRINT TAB(21); "WATER TUBE"
00530 PRINT " P-PA BARREL ID LENGTH ";
00540 PRINT "<-----BARREL WEI";
00580 FRINT ")----->"
00590 PRINT
00600 PRINT "YIELD STRESSES (PSI)----->";
00610 FOR S=S1 TO S2 STEP S3
00620 PRINT USING "#########",S/144;
00630 NEXT S
00640 PRINT
00650 PRINT
00660 FOR P=P1 TO P2 STEP P3
00670 V=I3/SQR(2*R1*(P-T/A))
00680 L=V/A+D/3
00690 PRINT USING 00700, P/144;SQR(T*4/P/P9);L;
00700 : 特种特殊特殊种种 神教科学 排稿 特殊 特殊的
00710 FOR S=S1 TO S2 STEP S3
00720 W0=R0+12+T/(S-2+P)
00730 FRINT USING 00740, WO;
00740 : ######
00750 NEXT S
00760 PRINT
00270 NEXT P
00780 PRINT
00790 PRINT
CORDO MEXT D
00810 DATA 57600,1440000.472
00820 BATA 1440000.3600000.144000
00830 DATA 1.25,3,.25
00840 DATA 1.44 E7,2.88 E7,1.44 E6
00850 END
```

NSWC TR 84-214

E O E	TOTAL TAPULE THRUST = 144	NOTAL INFULSE = 57.00 POUND SEINRUST = 144000 FOUNDS.	POUND SECO IDS.	CONDS.		ANIEN LUBE	เหยือง เ	SEC LIURAL	AKE A	3.77.808	SUCHKE	•     		
	(154)	u P-PA BARREL 1D PSI) (FEET)	WATER TUBE LENGTH (FEST)		\$ 1	; ; ; ; ; ; ; ;	\$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$	16 101	SYSTEM UPOUNDS)-	E16H1				1
YIE	TIELD STRESSES	SE3 (PS*)	1 1 1 1	100000	11,3090	120093	130000	140000	150000	150.00	179000	180000	190000	20000
	00001	1.128	7.75	C1 P3 C1	2270	2044	1859	1705-	1574	1452	1365	1280	1205	. <del>.</del>
	11000	1.075	7.32	2668	2367	21.7	1.931	1766	1631	1513	114	1322	1244	-
	00001	1.030	6.97	2789	2468	2213	2002	1833	1539	100 100 100 100 100	1459	1356	12 13 14 15 15 15 15 15 15 15 15 15 15 15 15 15	121
	13000	506.	99.6	2915	2572	2301	2081	1900	1748	1518	1508	1409	1324	4. 5.1
	14000	. P	94.9		2679	2391	2159	1948	1808	1672	555	1453	1364	123
	15000	.921	6.17	3184	2,791	2484	2238	2037	1859	1726	1604	•	1405	132
	1,000	60.	2.96	3326	9062.	2580	2320	2107	1931	1781	1653	•	446	136
•	. 2002.	988	5.78	3475	3025	2679	2403	2:80	1994	1837	1703	_	1487	139
	33081	. 841	5.61	3631	3143	2781	2489	2253	2058	1894	1754	1	1529	143
	19000	818	5.46	3795	3278	2886	25,77	2328	2124	1952	1806		1571	147
	-20000	.798	5,33	3967	3413	2995	2668	2496	2190	2010	1858	1727	1613	131
	21000	210	5.23	-4148	3553	3107	2761	2465	2253	2070	1911		1656	155
	22000	\$ 9 f	5.39	4339	3599	3224	2857	2555	23.5	2131	596	٠.	1699	159
	23000	744	86.	4541	3852	3345	2957	2649	2400	2193	2019		1743	163
. <b>.</b>	24000	6.1.3	4.83	47.56	4013	3472	3059	:735	2473	2256	2073		1787	167
	25006	.714	4.79	4935	4183	3604	3166	2923	2543	2321	2132		1832	171

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^ ^ · · · · · · · · · · · · · · · · · ·	20/000	328	331	335	339	343	347	351	355	360	364	369	373	378	383	388	393
	190009	347	33.5	355	340	364	369	373	378	383	388	393	398	404	410	415	421
	189000	369	373	3.78	383	388	393	398	404	410	415	421	427	434	440	447	454
! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! ! !	170000	393	398	404	410	415	421	427	434	440	447	454	461	894	476	483	492
	160900	421	427	434	440	- C 4 47	454	461	468	475	483	492	200	508	517	527	536
-BARREL WEIGHT (POUNDS)	150000	454	+51	468	476	483	492	500	508	517	527	536	546	355	567	5.78 8	590
BAR	1 4 0 0 0 0	492	200	208	517	527	536	546	556	267	578	590	602	615	\$28	641	656
1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	130000	536	545	556	267	578	065	. 602	615	628	641	929	9.79	989	702	720	738
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1 1	110000	55.8	0.0	686	702	720	738	957	9:2	266	920	843	898	894	\$22	952	486
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UATER TUBE LENGTH (FEET)		2.,5	C 3	6.07	99.9	5.43	6.1.3	5.96	5.78	5.61	5.40	5.33	5.20	5.09	80.	. 83	4.79
BARREL IR (FSET)	(ISJ) S3S	1.128	1.076	1.030	066	. 456	126.	C.S.	593.	. 84	. 313	362.	626	.761	. 744	. 728	**
F-FA (FSI)	TELD STRESSES (FSI)	00004	11600	17010	13000	14000	15000	16000	17000	18000	19000	20000	21.000	22996	23909	24000	25000

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